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Uncertainties in river basin data at various support scales – Example from Odense Pilot River Basin

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Abstract

In environmental modelling studies field data usually have a spatial and temporal scale of support that is different from the one at which models operate. This calls for a methodology for rescaling data uncertainty from one support scale to another. In this paper data uncertainty is assessed for various environmental data types collected for monitoring purposes from the Odense river basin in Denmark by use of literature information, expert judgement and simple data analyses. It is demonstrated how such methodologies can be applied to data that vary in space or time such as precipitation, climate variables, discharge, surface water quality, soil parameters, groundwater abstraction, heads and groundwater quality variables. Data uncertainty is categorised and assessed in terms of probability density functions and temporal or spatial autocorrelation functions. The autocorrelation length scales are crucial when support scale is changing and it is demonstrated how the assumption used when estimating the autocorrelation parameters may limit the applicability of these autocorrelation functions.

1 Introduction

Understanding the uncertainty in environmental data and systems is essential for making robust and wise water management decisions (Funtowicz and Ravetz, 1990; Beck, 2002; Pahl-Wostl, 2002). Several authors have addressed various aspects of data uncertainty in different disciplines (e.g. Gelhar, 1986; Beven and Binley, 1992; Heuvelink and Burrough, 1993), but so far few attempts have been made to establish a methodology for characterising data uncertainty that is generic and applicable across disciplines. To fill in this gap a new methodology and an associated software tool was developed (Brown, 2004; Brown et al., 2005; Brown and Heuvelink, 2006) and literature surveys were made to support the assessment of uncertainty in different types of data (Van Loon and Refsgaard, 2005).

A particular problem fundamentally related to data uncertainty is the issue of scale
of support, both in time and in space. When field data are used for modelling either as input or for comparison with model variables the scale of support of the field data are most often not fully consistent with the scale on which the models operate (Heuvelink and Pebesma, 1999; Refsgaard et al., 1999).

This new data uncertainty assessment methodology and its application to different disciplines are described in several other papers in this HESS Special Issue (Castilla; Dunbar; Nilsson and Refsgaard; Rode and Suhr, 2006; van der Keur and Iversen, 2006; van Loon et al., 2005). Most scientific studies on data uncertainty have been based on data collected for research purposes. The present paper has two main objectives: (1) to test and illustrate the new methodology on different types of data from an ordinary river basin, based on existing data collected for river basin management purposes; and (2) to discuss the fundamental problems arising in connection with such data uncertainty assessment.

2 Methodological considerations

2.1 The HarmoniRiB network of representative river basins

Within the EU research project HarmoniRiB (Refsgaard et al., 2005a) data have been collected from eight European river basins. These basins have been selected to ensure a good coverage across Europe in terms of eco-regions, types of water problems, socio-economic conflicts and amount and quality of existing data. For each of the eight river basins a comprehensive amount of data has been collected and uploaded to the HarmoniRiB database. The data basically include all data that are required to carry out analysis for implementation of the European Water Framework Directive (WFD), i.e. data on climate, rivers, lakes, groundwater, transitional waters, and coastal waters, river basin characteristics and socio-economics. After uploading the data to the database, uncertainty has been assessed and added to the data. The aim of the HarmoniRiB network is, through interaction with the respective river basin organisations
and data owners, to provide well documented data for research purposes, suitable for studying the influence of uncertainty on management decisions. The data will be publicly accessible for all research purposes. Thus, scientists may use the data to e.g. assess the appropriateness of models and other tools in relation to the WFD.

2.2 Characterisation of uncertainty – support scale

As part of the data processing the HarmoniRiB project partners have characterised and assessed the data uncertainty using the new methodology described by Brown et al. (2005) and using the DUE (Data Uncertainty Engine) software tool (Brown and Heuvelink, 2006). This new methodology has been further elaborated in van Loon et al. (this issue). Tables 1–4 show the key characteristics used to characterise data uncertainty. The terms in these tables are used in Table 5 comprising the key characteristics of data uncertainty for the Odense River Basin as assessed in the present paper.

We found it, however, necessary to amend the tables in van Loon et al. (this issue) with characterisation of upscaled time and space support. The reason for this is that many of the data items have a measurement scale support that is considerably smaller than the corresponding variable typically simulated by a model. Let us, as an example, assume that a water quality variable in a river is sampled once per month by taking a bottle of water at a location in the river cross-section. The measurement scale support in this case is a couple of seconds in time and equivalent to the volume of the bottle in space. A river water quality model will typically simulate the concentration as the average for the whole cross-section (unless it is a 3-D river model, which is not common for water quality modelling) and with a time step of somewhere between an hour and a day. The measurement support scales are in this case not compatible with the modelling scales. If the modeller wants to analyse whether the model simulation has an accuracy that is within the range given by the measurement uncertainty it does not, therefore, make sense to compare these data. In such case we have to upscale the field data uncertainty and/or downscale the model scale uncertainty so that the tempo-
eral and spatial scales at which uncertainty is considered are the same for field data and modelled variable. The upscaling/downscaling can be done to many different scales depending on the objective of the particular study. If the objective is to assess the flux of the solute on a monthly basis the field data uncertainty could be upscaled to support scales of the cross-section (spatial) and one month (temporal).

2.3 Sources of uncertainty

Based on van Loon and Refsgaard (2005) the sources of uncertainty for field data can be characterised as follows:

- Field instruments (instrument errors, instrument calibration errors)
- Laboratory analysis (sample conservation and transport, instrument errors, instrument calibration errors, laboratory induced uncertainty)
- Model for relating measured values to the variable of interest. This applies in cases where the measurements are indirect, e.g. when transforming water level measurements to discharge values by use of a rating curve there is uncertainty related to the rating curve.
- Representativeness of sample in space (spatial heterogeneity of variable)
- Representativeness of sample in time (temporal variability of variable, sampling frequency and period, choice of extrapolation method)

The latter two of these sources are those relating to the upscaling from the measurement support to a larger scale. In the example above they relate to the upscaling from point scale to cross-sectional scale and from instantaneous to monthly average values. As noted by Rode and Suhr (2006) the sources of uncertainty related to upscaling are often dominant as compared to field instrument and laboratory uncertainty.
3 The Odense River Basin

The Island of Fyn covers approximately 3000 km$^2$ of which nearly 80% is cultivated. The Odense river basin covers approximately 1190 km$^2$ of the island (Fig. 1). The present landscape of Fyn was primarily created during the last Glacial Period. The topography is characterised by low rolling hills with three major topographic highs of about 100 m divided by a central lowland. Quaternary deposits up to 150 m thick are exposed at the surface and consist of glacial and interglacial sediments. These deposits consist primarily of clayey till with lenses and alternating layers of outwash sand, gravel and clay. The most regionally extensive and most heavily exploited aquifer on Fyn consists of Quaternary outwash sands bounded by upper and lower fine-grained deposits.

The annual precipitation and reference evapotranspiration are about 900 mm and 600 mm, respectively. There is a positive precipitation gradient from the northern coast toward the southern boundary of the catchment. The phreatic groundwater table is close to the surface and the low lying areas are generally drained by tile drains. All water supply is based on groundwater abstraction. The two main water resources management problems in the area are (1) groundwater pollution due to point and non-point sources, and (2) eutrophication of Odense Fjord due to nutrient load originating from agricultural areas.

The Odense Pilot River Basin project comprises Denmark’s contribution to the testing of a number of EU guidance documents relating to implementation of the Water Framework Directive (WFD). All relevant information in this respect is described in Fyns Amt (2003) that also provides a thorough description of the basin, its environmental status and the water management issues.
4 Description of data and assessment of data uncertainty

In the following sections some of the data collected from the Odense River Basin are described together with the assessed data uncertainty. The data types and the key characteristics of the uncertainty assessment are shown in Table 5. A more detailed description is given in Van der Keur et al. (2006). The reason for selecting these data is that they together illustrate most of the difficulties and fundamental problems we were confronted with when we assessed data uncertainty for the river basin.

4.1 Precipitation data

4.1.1 Data description

Daily values have been collected for seven precipitation stations for the period 1990–2003 (Thomsen and Rosenørn, 2004). Precipitation data are measured by manual readings as accumulated data over 24 h using a Hellman raingauge located 150 cm above the ground.

4.1.2 Uncertainty aspects

The precipitation data are known to be biased, because wetting and wind effects cause the measured data to underestimate the real precipitation (Allerup and Madsen, 1979; Barca et al., 2005). The data can be corrected for this bias by multiplying the measured data by a factor that varies over the year with highest correction factors in winter months where wind speeds are higher and where some of the precipitation falls as snow (Allerup et al., 1998). The average correction factor is 1.21.

After removing this bias the uncertainty on the corrected data are still significant. Analyses of point measurements indicate that the uncertainty on the monthly correction factors is between 2% and 11% (Vejen, 2002) implying that uncertainty on daily values are even higher.
For precipitation data the measurement support scale is basically a point in space (the area of the gauge is 200 cm$^3$) and a day in time. In all the hydrological models applied for Fyn so far the precipitation data is used as being representative for a model grid or a subcatchment, ranging from a few hundred m to a few hundred km$^2$. As data are used as representative of a given area we have chosen to upscale the spatial support to 170 km$^2$, which in average corresponds to the area covered by one station, if the seven stations are used to estimate the precipitation for the whole basin.

The uncertainty varies both in time and in space. We have chosen an uncertainty model (Table 1) that assumes the data and their uncertainty to be continuous numerical variables that varies in time but are constant in space. The more qualitative characterisation of uncertainty of the precipitation data according to type empirical uncertainty (Table 2), methodological quality (Table 3) and longevity (Table 4) are straightforward and shown in Table 5.

Instead of conducting a comprehensive statistical analysis on precipitation data from the Odense catchment, we decided to base the assessments on results from a previous research study in another Danish catchment, Suså, with similar climatic regime (Allerup et al., 1981, 1982). The advantage of this approach is that these results were based on a sophisticated statistical analysis with much more data than available in our case and that the results are readily available and scientifically published. The disadvantage is that in order to transfer these results to the Odense river basin and to our desired form, we need to make some assumptions that may not all be easy to justify. The critical assumptions and their implications are discussed later in this paper.

In the study by (Allerup et al., 1981, 1982) areal precipitation was estimated for the 800 km$^2$ Suså catchment on the basis of data from 14 precipitation stations. They found that a normal distribution was applicable. By use of comprehensive statistical analyses considering the effects of spatial and temporal correlations they estimated confidence bounds for the (upscaled) areal precipitation for daily, monthly and annual precipitation as follows:

- Standard deviation (daily values): about 60% of average daily precipitation
Standard deviation (monthly values): about 10% of average monthly precipitation

Standard deviation (annual values): about 6% of average annual precipitation

The problem we want to address is now to estimate how accurate one precipitation station would represent the average precipitation over an area of 170 km². To do that we start by going from the catchment uncertainty for the 800 km² with 14 stations to the uncertainty for one station over 800/14 = 57 km². If we assume that the 14 stations are equally spaced and weighted and that data from the 14 stations are spatially independent, then the standard deviation for one of the stations can be calculated backwards from

$$\text{STD}_{800 \text{km}^2} = \frac{\text{STD}_{57 \text{km}^2}}{\sqrt{N_{\text{eff}}}}$$  \hspace{1cm} \text{(1)}$$

where

- $N_{\text{eff}}$: number of independent observations used to calculate the average precipitation over 800 km²
- $\text{STD}_{800 \text{km}^2}$: standard deviation of precipitation over 800 km² based on $N_{\text{eff}}$ independent observations
- $\text{STD}_{57 \text{km}^2}$: standard deviation of precipitation for one station representing 57 km²

However, due to spatial autocorrelation $N_{\text{eff}}$ is less than the number of stations. Spatial autocorrelation functions for daily and monthly precipitation are given in (Allerup et al., 1981, 1982). For daily precipitation the spatial autocorrelation over a length corresponding to 57 km² (7.6 km) is 0.4. By using a standard text book formula for calculating the effective sample size in autocorrelated time series, e.g. Salas (1993), with 14 stations and a correlation coefficient of 0.4, $N_{\text{eff}}$ can in this case be calculated to 12.5. By rearranging Eq. (1) $\text{STD}_{57 \text{km}^2}$ is calculated to

$$\sqrt{12.560\%} = 210\%$$
This implies that by upscaling the spatial support of precipitation data from representing 57 km$^2$ (7.6 km) to representing 800 km$^2$ (28 km) the standard deviation increases from 60% to 210%. By making the same calculation for different number of stations the relationship shown in Fig. 2 appears. For the case of the Odense river basin we want to upscale the support to 170 km$^2$ (13 km) which then is seen (Fig. 2) to result in a standard deviation of about 105% of the average daily precipitation.

For monthly values the spatial autocorrelation is larger. Using the correlation function for monthly values shown in Allerup et al. (1981) the relationship between spatial support and standard deviation becomes as shown in Fig. 3. For the case of Odense river basin the standard deviation upscaled to a spatial support of 170 km$^2$ (13 km) is seen to be 19%. If the correlation structure for annual values is similar to the monthly correlation the standard deviation for annual values upscaled to 170 km$^2$ (13 km) would be 11%. If the annual correlations are higher than the monthly values, which is a reasonable assumption, the standard deviation for the annual values would become less than 11%.

For an uncertainty category B1 (varies in time, not in space) we also need to estimate an autocorrelation function and the associated parameter values. We could not find much relevant information on this. Therefore we assumed an exponential shape of the autocorrelation function. The parameter to estimate is then the autocorrelation length scale. The review of Barca et al. (2005) does not provide information on this parameter. Willems (2001) found that there was hardly any autocorrelation in hourly and half-daily data from Belgium. Allerup et al. (1981) in their statistical analyses of temporal and spatial correlation found temporal autocorrelation on daily data in the order of a few days. We have therefore assumed a parameter value for the autocorrelation length scale of 2 days.

With this autocorrelation length scale of 2 days the standard deviation of monthly and annual values can be estimated and compared to the figures derived above. If the monthly average precipitation is estimated from daily values then the standard deviation on the monthly mean value can be estimated form the standard deviation on the
daily data (105%) and the effective sample size (30 reduced to 30/2 due to temporal autocorrelation) to \((30/2)^{-1/2}\) 105% = 27%. This is somewhat larger than the 19% derived from Fig. 3. A similar calculation for annual values results in \((365/2)^{-1/2}\) 105% = 8%, which is somewhat less than the 11% given above. The autocorrelation structure in reality, as also reflected in the statistical model developed by Allerup et al. (1981, 1982), is truly spatio-temporal, while the B1 model used here is only temporal. We have then tried to compensate for this lack by using the results from Allerup et al. (1981) to derive temporal autocorrelation models for different spatial scales. The above calculation is a check illustrating to which extent our relatively simple uncertainty model can reflect the spatio-temporal autocorrelation structure in the much more comprehensive model by Allerup et al. (1981). The comparisons show that there are clear limitations in our simple model and that is should be used with care. However, considering the crude assumptions made, the figures match reasonably well indicating that there are no major discrepancies in the uncertainty model and that if it is used to generate random samples of daily data then the uncertainties on monthly and annual basis will be of the right order of magnitude.

4.2 Climate data

4.2.1 Data description

Daily values of temperature, wind direction, wind speed, relative humidity and solar radiation have been collected for one climate station that is located at the same place as one of the seven precipitation stations. The data are described in Thomsen and Rosenørn (2004). The climate station was modernised in 2001. The instrumentation of the stations is listed in Table 6. The daily values are aggregate values based on continuously recordings. The daily potential evapotranspiration is calculated by means of a modified Makkink formula (Scharling, 2001) where the variables are aggregated to hourly values before calculations.
4.2.2 Uncertainty aspects

The climatic data on temperature, relative humidity, wind direction and speed and solar radiation have a measurement time support of 1 day obtained from aggregated continuous measurements. The uncertainty category is for all variables is B1 (varies temporally, not in space) and the empirical uncertainty, methodological quality and longevity is as for precipitation (Barca et al., 2005), except for air temperature and relative humidity where the overall method is evaluated as O4, i.e. approved standard in well established discipline. As the potential evapotranspiration is calculated and not directly measured, the methodological quality is O2, as the method is accepted, but with limited consensus on reliability. Plauborg et al. (2002) reported that potential evapotranspiration calculated using the Makkink formula (Makkink, 1957) could be up to 10% overestimated (Table 5). The measurement space support for air temperature, relative humidity and solar radiation is the sensor area of about 10 cm$^2$. Often climate data are used to represent larger areas. For instance Nielsen et al. (2004) used climate variables from one stations to represent the entire 800 km$^2$ Odense Basin. Therefore, it would be useful to apply an upscaled support scale of 800 km$^2$. As we have no information on uncertainty when this space support is rescaled, the measurement space support in maintained in Table 5. The assessed uncertainties are based on information in Barca et al. (2005). The autocorrelation function is assumed to be of the exponential type with a length scale of 2 days as for precipitation.

4.3 Discharge data

4.3.1 Data description

There are 10 river gauging stations in the basin. At these stations water levels are measured by continuous recordings. Discharge measurements are made manually by use of current meters at regular (approximately monthly) intervals and rating curves are established. The ratings curves are not constant in time due to changes in bed
form and growth of weed. The water level recordings are transformed to average daily water levels, which then are converted to average daily discharges by use of a time varying rating curve. Data are collected for the period 1990–2000.

4.3.2 Uncertainty aspects

According to information from the organisation (NERI) responsible at a national level for discharge measurements a typical uncertainty (standard deviation) on daily discharge data is in the order of 10%, while the uncertainty on annual average flows is about 5% (Refsgaard et al., 2003). This is also the order of magnitudes indicated in (Goodwin, 2005).

The uncertainty characteristics of the discharge, according to the methodology described by van Loon et al. (2006) are similar to those of the precipitation data, namely an uncertainty model that assumes variation in time but not in space (B1) and empirical uncertainty, methodological quality and longevity as shown in Table 5.

The measurement support in space is the river cross-section (indicated as 1–20 m² in Table 5), while the time support is one day (it is daily average water levels that are converted to daily discharges). The uncertainties on the data are assumed to be zero-mean, Gaussian, with a standard deviation of 10% of the measured discharge.

The difficult issue here is to assess the temporal autocorrelation. In Table 5 it is given as an exponential function with a temporal length scale of 90 days. The review made by Goodwin (2005) does not provide much support in this respect. The assumption of an exponential function is therefore somewhat arbitrary, although an exponential correlation structure is common in time-series analysis (e.g. Sivapalan and Blöschl, 1998). The reasoning behind the 90 days as temporal length scale is related to the uncertainty of 10% and 5% on daily and annual flows, respectively. If the daily flows were assumed not to be correlated (length scale = 0 days) the uncertainty on the annual average flow (STDannual_flow) can be estimated from the uncertainty on the daily

1955
values \( (\text{STD}_{\text{daily\_flow}}) \) as follows:

\[
\text{STD}_{\text{annual\_flow}} = \frac{\text{STD}_{\text{daily\_flow}}}{\sqrt{N}}
\]

(2)

where \( N \) is the number of observations. With \( N=365 \) and \( \text{STD}_{\text{daily\_flow}}=10\% \), \( \text{STD}_{\text{annual\_flow}} \) becomes 0.5\% which is a factor 10 too low. If we consider autocorrelation, \( N \) can be considered as the equivalent number of independent observations. If we for instance have \( N=4 \) we get \( \text{STD}_{\text{annual\_flow}}=5\% \). \( N=4 \) can be interpreted as a year information content equivalent to four independent observations or in other words that the average length scale is in the order of 90 days.

This backwards calculation give us some kind of consistency between uncertainty on daily and annual flow. However, it can be argued that the “uncertainty model” in this case is too simplistic and will lead to wrong conclusions for many applications. In reality the uncertainties most likely contains both a bias on the expected value and an autocorrelation on the residual. The bias could be related to representativeness of the current meter profiles and the shape of the rating curve. If the data is biased on one day they are also likely to be biased on other days, which will increase the correlation and the variance of the combined uncertainty. We do not know how the uncertainty in reality is decomposed into bias and partially correlated variability, but this combination can explain that we by the backwards calculation arrive at an autocorrelation length scale that is much larger than one would assume if only considering instrument and other measurement errors. A further discussion on the applicability and limitations of the above results are given in the final section of the paper.

4.4 Tot N in streams

4.4.1 Data description

The concentration of Total nitrogen (Tot N) is monitored at some of same river gauging stations where water levels are also measured. Daily data have been collected from 4 1956
stations for the period 1990–2000. The samples for Tot N analyses are taken as time proportional sampling aggregated over one day. The samples are taken at a point in the river, which is indicated by a space support of 100 ml in Table 5.

4.4.2 Uncertainty aspects

We have decided to upscale the space support from a point in the river (100 ml) to the river cross-section. This implies that we can consider the uncertainty to be composed of two elements: (a) one related to the measurement at point scale (sampling, instrument, laboratory procedures, etc.) and (b) the other related to the representativeness of the point (100 ml) to characterise average cross-sectional concentration.

The statistical distribution is assumed to be Gaussian, as recommended by Rode and Suhr (this issue). Rode and Suhr (this issue) furthermore suggest that the instrument and measurement uncertainty for point samples have a coefficient of variation of 5%. The main difficulty in our case is therefore to assess how upscaling of space support from point to cross-sectional area affects the uncertainty. This can be done in different ways. If sufficient data is available, or if sufficient assumptions can be made, on the spatio-temporal correlation structure within the cross-section, the uncertainty can be assessed through spatio-temporal block kriging (Heuvelink and Webster, 2001). We had no data (only one sample point) or information to justify any assumptions to support this. Instead we have relied on experience on how mixing or lack of mixing within a cross-section affects variation of concentrations across a profile. Based on data and recommendations made by Rode and Suhr (this issue) we assume that the uncertainty of a single point to represent average value of an entire cross-section corresponds to a factor of 2. By multiplying the coefficient of variation for instruments/measurements (5%) with this representativeness factor the uncertainty at a cross-sectional scale is estimated to be 10%.

The time series of daily data allows analysis of how representative a daily value is for the monthly average, or in other words an upscaled temporal support of the uncertainty to one month. Figure 4 shows daily and monthly average concentrations for one station.
for one year. The concentration of Tot N is seen to have a clear seasonal pattern with relatively slowly varying daily fluctuations on top. The variability of daily values within a month can be characterised by the coefficient of variation, i.e. the standard deviation divided by the mean monthly value. The average coefficient of variation for the 12 months shown in Fig. 4 can be calculated to 0.22 implying that the average error of using a daily value instead of the mean monthly value is 22%.

A time series analysis of the Tot N values for the whole period 1990–2003 resulted in the autocorrelogram shown in Fig. 5. Before calculating the autocorrelogram the seasonal pattern was removed by subtracting the monthly mean values from the daily values. The autocorrelation is seen to fit nicely to an exponential function with a time scale of 4 days. The autocorrelation is therefore assumed to follow an exponential distribution with a correlation length scale of 4 days (Table 5).

4.5 Tot P in streams

4.5.1 Data description

The concentration of Total phosphorous (Tot P) is monitored at some of same river gauging stations where also water levels are measured. Daily data have been collected from 4 stations for the period 1990–2000. Samples for Tot P are taken time proportionally in small volumes with a space support of 100 ml. Time proportional measurements are aggregated to 1 day. Therefore the time support is indicated as 1 day and the space support as 100 ml in Table 5.

4.5.2 Uncertainty aspects

The analysis leading to the uncertainty characteristics are similar to those for N Tot. The only difference is that the uncertainty related to instruments and laboratory analysis are assumed to be characterised by a standard error of 6% instead of 5% for N Tot following recommendations from Rode and Suhr (this issue).
Figure 6 shows the variability of daily Tot P values within a month. In contrary to the Tot N data shown in Fig. 4, the concentration of Tot P does not show a seasonal pattern, and the daily concentrations are much more erratic. The average coefficient of variation within a month for the Tot P data is 0.51 which is considerably higher than the 0.22 for Tot N. This more erratic behaviour is consistent with the much lower autocorrelation length scale of one day for Tot P (Fig. 7).

4.6 Heavy metals in streams

4.6.1 Data description

The concentration of about 10 compounds of heavy metals is monitored at some of the same river gauging stations where also water levels are measured. Data have been collected from 2 stations and 29 compounds for the period 1990–2000. Samples for heavy metals are taken as instantaneous samples in small volumes with a space support of about 100 ml. Therefore the time support is indicated as 10 s and the space support as 100 ml in Table 5. Sampling is made approximately once per month.

4.6.2 Uncertainty aspects

Like for the case of Total N in streams we have decided to upscale the space support from a point in the river (100 ml) to the river cross-section. In addition, we have upscaled the temporal support from an instant (10 s) to one month. This implies that we, in addition to instrument and measurement uncertainty, need to include the uncertainty of the point sample in representing average cross-sectional conditions and of the instantaneously sampled data to representing monthly average concentrations.

The statistical distributions for the uncertainties, including the autocorrelation, are assumed to be as for the data type “N-Total in streams”. The only difference is the standard error that here is assumed to be 20% instead of 10%. The rationale for the 20% is as follows:
The instrument/measurement uncertainty is assumed to be 5%. This is based on Rode and Suhr (this issue).

The spatial upscaling from point to cross-section is assumed to result in an increase of the uncertainty with a factor 2 as for the case of “N-Total in streams”.

The temporal upscaling from 10 s to 1 month is assumed to result in an increase of the uncertainty with a factor 2. This factor is partly justified by data. The variation of daily data on Tot N and Tot P (Figs. 4–5) show that the coefficient of standard deviation during a month divided by the mean value of the month was in average 0.22 for Tot N and 0.51 for Tot P. This coefficient of variation can be seen as a measure of the uncertainty of a daily value to be representative for a monthly value. As Tot P data are likely to be more representative for most heavy metals in its behaviour, because it depends more on suspended sediments than Tot N does, the factor for the Tot P is used. Unfortunately, no similar data exist for variations within a day. Assuming that this is the same order of magnitude we arrive at the uncertainty factor of 2.

The autocorrelation is here assumed to follow an exponential distribution with a correlation length scale of one day. This assumption is based on the data from Tot P, but we have no specific data on heavy metals to support this assumption which therefore is questionable. However, with an upscaled temporal support of one month a correlation length scale of one day implies that the monthly data are considered independent, and hence the autocorrelation function is of no practical importance.

4.7 Pesticides and organic compounds in streams

4.7.1 Data description

The concentrations of about 29 pesticides and other organic compounds are monitored at two of the same river gauging stations where also water levels are measured.
have been collected from the two stations for the period 1998–2003. Samples are taken as instantaneous samples in small volumes. Therefore the time support is indicated as 10 s and the space support as 100 ml in Table 5. Sampling is made approximately once per month.

4.7.2 Uncertainty aspects

The analysis leading to the uncertainty characteristics are similar to those for heavy metals. The only difference is that the uncertainty related to instruments and laboratory analysis are assumed to be characterised by a standard error of 10% instead of 5% for heavy metals following recommendations from Rode and Suhr (this issue). The autocorrelation function is assumed identical to the one for heavy metals discussed above.

4.8 Groundwater data

4.8.1 Data description

For the Odense catchment 116 groundwater bodies at various depths have been identified, mapped and monitored for drinking water purposes. Water abstraction data from 168 wells are recorded on a yearly basis. Groundwater head is monitored by means of automated datalogger recordings from some wells and by manual sampling from other wells in a dense network. Most groundwater bodies are monitored for nitrate, phosphorus, heavy metals and pesticide concentrations as well as physical-chemical properties, like pH, temperature and alkalinity. Sampling for compounds and physical properties is usually on a yearly basis and the measurement space support is 100 ml. Water quality has since 1990 been measured yearly from 2255 wells with 2615 intakes of which 1811 are connected to groundwater bodies (Fyns Amt, 2005).
4.8.2 Uncertainty aspects

Well abstraction data are usually very reliable and uncertainties due to instrument accuracy are low. However, data may be uncertain with respect to the origin of abstractions due to the location of filters relative to assumed boundaries between different aquifers. We have characterised the uncertainty by a normal distribution with zero mean and a standard deviation of 2% of the abstracted volumes (Table 5). The uncertainties of the annual data are assumed to be independent in time.

The spatial support scale for groundwater head observations are upscaled from a point to 0.5×0.5 km$^2$, because this is a common grid scale for regional groundwater modelling (Henriksen et al., 2003). The temporal support scale is upscaled from a point in time (10 s) to one year for the manual observations, while it is kept at the 10 s for the automatically recorded data. Inspired by the methodology described in Henriksen et al. (2003) the uncertainty of one observation to represent 0.25 km$^2$ at 10 s or one year can be assumed to be composed of the following independent sources of uncertainty:

- measurement errors: 0.1 m
- scaling errors due to hydraulic head gradient over the 500 m grid and uncertainty on where in the grid the observation well is located: 0.75 m
- uncertainty due to geological heterogeneity: 1.0 m
- non-stationarity, i.e. head fluctuations over a year: 0.5 m (this becomes 0 m in case of automatic readings and 10 s support scale)

Using the error propagation equation the uncertainty can then be calculated to 1.35 m and 1.25 m for the manual and automatically recorded data respectively. We have no information on the autocorrelation function for the groundwater head data (Table 5).

No data is available on probability density and autocorrelation functions for physical- and chemical properties. Measurements of physical and chemical properties may be uncertain as to which aquifers the samples represent. For instance, samples of nitrate

1962
may be taken from a mixture of water from near-surface and deeper aquifers dependent on the filter position and geologic structure around the filter. Usually, counties monitor sample measurements for anomalies with regard to discontinuities in data over time as a means of data quality assurance (Copenhagen County, personal communication). Time between samples is dependent on the location (depth) of the reservoir and for routinely monitoring purposes the range is usually between 1 month and 1 year for surface near- and deep-groundwater respectively.

4.9 Soil data

4.9.1 Data description

Soil texture for Fyn is measured at 20 cm depth in 3619 points. The texture class is subdivided in clay, silt, fine sand and coarse sand. Furthermore soil organic matter (SOM), CaCO$_3$ content and a colour code are registered. Coordinates of all point are provided in UTM coordinates. Soil hydraulic properties are not included and must be estimated from pedotransfer functions.

4.9.2 Uncertainty aspects

Uncertainty in soil (physical) data arises from the spatial and temporal variability of environmental variables, from sampling procedures in the field, and from analysis in the laboratory. Soil variability is the product of soil-forming factors operating and interacting over a range of spatial and temporal scales. The uncertainty characteristics listed in Table 5 are in accordance with the recommendations in van der Keur and Iversen (this issue). Here it is only noted that the soil data, in contrary to the other data types in Table 5 vary in space, but not in time, making the measurement and upscaled time supports irrelevant in this case.

The measurement space support for soil samples taken in the field are typically in the order of magnitude of 100 cm$^3$. Mulla and McBratney report ranges in coefficient
of variation of 3–37% and 16–53% for sand- and clay content respectively. This is translated to 25% and 40% in Table 5 where 30% is assumed for silt content. Spatial autocorrelation lengths for soil texture are reviewed in van der Keur and Iversen (this issue). For clay-, silt- and sand content, Neuman and Wierenga (2003) found correlation lengths ranging from 20–33 m, 20–26 m and 20–35 m respectively, fitted to spherical models. Soil organic matter Hansen et al. (1999) estimate the standard error to be 25% and Kristensen et al. (1995) fit an exponential model to the data with a range of 34–45 m. For CaCO3 content the standard error is 10% and the variogram model of the exponential type with a range of 30 m (Kristensen et al., 1995). This is shown in Table 5.

5 Discussion and conclusions

5.1 Critical assumptions

In order to make the above uncertainty assessments many assumptions had to be made. Many of these assumptions used in the expert judgements are based on general knowledge from literature or on regional knowledge from nearby catchments and the validity of these assumptions to the Odense River Basin can, and should, be questioned. It would no doubt have been better to have more detailed local data, which would have been possible in an experimental research catchment. However, when making assessment of data uncertainty in real life basins where “only” data from routine monitoring programmes exist, it is often necessary to make such assumptions and simplified expert judgements. Odense river basin is one of the so-called Pilot River Basins used as testing ground for guidelines for the EU Water Framework Directive. And it is probably the basin among the about 15 Pilot River Basins with the best data availability. So for most other basins it will be necessary to make even more assumptions than we have done here.

What are then the most critical assumptions?
– The most critical assumption is probably that we have assumed data to vary either spatially (C1) or temporally (B1), whereas many data in reality varies both in time and space (D1). The way we circumvented this assumption for precipitation data was to upscale temporally varying data to a certain scale of support. This may, as discussed above, lead to inconsistency when these data are then aggregated from daily to monthly or annual values.

– The assumptions made on spatial and temporal autocorrelation length scales have generally not been much supported by local data and are therefore very uncertain. These autocorrelation length scales are crucial when the data are up-scaled in either space or time.

– In case of sampling from a river cross section, measurements vary across the cross-section and over time. Usually one measurement is taken for the entire cross-section and assumed representative as no information exists on the spatial distribution. Again we rely on experience from literature and transfer it to our own case. In the rare event of having knowledge on the spatio-temporal behaviour of the variable at hand, spatio-temporal geostatistics may be applied for upscaling to the cross-section support scale. In this case the similar assumptions apply as for the spatial- or temporal case.

– We use data from Suså instead of Odense for precipitation. This is probably a less critical assumption as compared to many of the other ones, because it is based on a very comprehensive statistically based research study with a much data in the Suså basin, and because the climatic regimes do not differ very much between the two basins.

In spite of these simplistic and crude assumptions we see no other realistic option if uncertainty assessments should be carried out in ordinary river basins as an integrated part of the water resources management. The only alternative in most cases would in practise be to make no uncertainty assessments at all. And we consider this a very
poor alternative. One of the important aspects of uncertainty assessments is to make uncertainty aspects a recognised factor in the whole water management process.

Although data uncertainty is only one source of uncertainty in water resources management, and some times even not the most important one (Refsgaard et al., 2005; Højberg and Refsgaard, 2005; Waetzold, 2000) it is a source of uncertainty which is relatively easy to handle in statistical terms and therefore for many people easier to comprehend than many other sources of uncertainty that can only be characterised qualitatively. The difficulty of handling uncertainty in an objective manner has often been a barrier with the result that uncertainty has been neglected in the management process. As we consider uncertainty as a very important element in water resources management it is therefore important to encourage water managers to be aware of uncertainty and include it some way or the other in the management process. In this perspective assessments of data uncertainty may in some cases be an eye opener illustrating the importance of uncertainty, and therefore relatively simple methodologies like the ones used in the present paper are important.

5.2 Limitations in applicability of our simplistic uncertainty models

The critical assumptions leading to the uncertainty models for the various data types have some implications in terms of limitations of applicability.

Let us as an example look at the discharge data where we assessed that an autocorrelation length scale of 90 days were required in order to match the expert information that uncertainty on daily and annual discharge values could be characterised by standard deviations of 10% and 5% of the daily and annual mean values, respectively. By doing so we ensured that if daily discharge time series were generated then the annual flow values would have the right order of magnitude of uncertainty. A simple analysis of the discharge time series would show that the autocorrelogram would not have an autocorrelation length scale of 90 days. It would probably rather be in the order of a few days. Thus, if the discharge series should be used to analyse something related to peak flows, generation of time series with a length scale of 90 days would lead to very
wrong results. If we had used a length scale suitable for generation of short term phenomena like floods, the uncertainty would not be able to preserve the correct level of uncertainty for mean annual flows. Similarly the 90 days length scale for discharge cannot be used to assess the necessary sampling frequency. By assuming the uncertainty model valid for such purpose one might get the idea that much more than four samples per year would be waste of money. This is of course not the case. This illustrates that the simple models can be calibrated to fit certain phenomena, but if the uncertainty model is intended to be used for something outside the calibration base, then it cannot be assumed valid and this extrapolation might lead to very biased results.

Another illustration of the same problem is the autocorrelation function for river water quality variables, where the autocorrelation length scales were assessed from time series analysis to be 1–4 days. The key sources of uncertainty for water quality at cross-sectional scale are (a) instrument and laboratory calibration and practise and (b) representativeness of point sample at cross-sectional scale. The time scales derived from the autocorrelation analysis only considers the first of these sources, which can be assumed unbiased. The second uncertainty source is very likely to be biased. If the sampling point has a lower concentration than the cross-sectional average concentration on one day it is also likely to be lower on another day. We do not know the average bias. Therefore we can only assume an expected mean of this uncertainty of zero, but the uncertainty will be consistently either positive or negative. What we have done is to aggregate these two uncertainty terms in one term. By doing so the aggregated autocorrelation length scale is likely to be much larger than the 1–4 days. This implies that use of an autocorrelation function with time scales of a few days to generate time series of water quality variables may be appropriate if the purpose of a study is to look at short term variations, but if such series are used to analyse annual mean values of concentrations the uncertainty on the annual values will be severely underestimated.

The reason for this lack of universal applicability of the uncertainty models is that it is only an approximation within a small window of the true spatio-temporal autocorrelation structure. A simple model can be thought of as an approximation like a tangent is
a linear approximation to a non linear curve. The approximation is very good near its point of derivation, but will become less and less accurate the further away from this point we move. Therefore an important conclusion is that we have to be careful when using the uncertainty models. They are in a way only valid for certain types of applications, and it is necessary to understand the assumptions and limitations in order to use them correct.

5.3 Selection of upscaled spatial support for uncertainty

Why do we have to upscale the spatial and temporal support? Could we not just assess the uncertainty at the support scale of measurements and then leave the remaining upscaling to the modellers or other users of the data uncertainty? In principle we could stop at the measurement scale. But then we would have to provide a detailed spatio-temporal autocorrelation function in order to enable future users of the uncertainty information to make a suitable upscaling. This would from an ideal, theoretical point of view be preferable. However in practise there are two problems with such approach:

– We do not know the detailed spatio-temporal autocorrelation function. And it would be a function where the assumptions on second-order stationarity in time and space are severely violated.

– Most standard software tools can not deal with such sophisticated spatio-temporal autocorrelation functions. For instance, the DUE (Brown and Heuvelink, 2005) can only treat uncertainty autocorrelation functions that describe variation in either time or in space, not both in time and space at the same time.

The choice of which upscaled spatial support to use is a subjective decision depending on the intended application of the data and their uncertainty. To illustrate this let us consider the case of river water quality data, where we decided to upscale the data uncertainty from a point sample to the river cross-section. In a case where a model has a detailed 3-dimensional discretisation with computational elements in the order of 1968
the sampling length scale (e.g. 10 cm) an upscaling to cross-sectional support is not relevant (if the exact xyz location of each sample is known and more or less matches the cross-sectional grid). But for the more common case of 1-dimensional river modelling which operates with cross-sectional average concentrations the upscaled value is the one of interest in modelling. It is essential to ensure that there is no mismatch of support scale between field data and modelling when using the field data either as direct input to the model or as calibration or validation data.

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Data uncertainty at various scale support for Odense Basin

J. C. Refsgaard et al.

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Interactive Discussion


**Table 1.** The subdivision and coding of attribute uncertainty-categories, along the “axes” of space-time variability and measurement scale (van Loon et al., this issue).

<table>
<thead>
<tr>
<th>Space-time variability</th>
<th>Measurement scale</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Continuous numerical</td>
</tr>
<tr>
<td>Constant in space and time</td>
<td>A1</td>
</tr>
<tr>
<td>Varies in time, not in space</td>
<td>B1</td>
</tr>
<tr>
<td>Varies in space, not in time</td>
<td>C1</td>
</tr>
<tr>
<td>Varies in time and space</td>
<td>D1</td>
</tr>
</tbody>
</table>
Table 2. Types of empirical uncertainty (van Loon et al., this issue).

<table>
<thead>
<tr>
<th>Code</th>
<th>Explanation</th>
</tr>
</thead>
<tbody>
<tr>
<td>M1</td>
<td>Probability distribution or upper and lower bounds</td>
</tr>
<tr>
<td>M2</td>
<td>Qualitative indication of uncertainty</td>
</tr>
<tr>
<td>M3</td>
<td>Some examples of different values a variable may take</td>
</tr>
</tbody>
</table>

1974
Table 3. Indices for “methodological quality” of a variable (van Loon et al., this issue).

<table>
<thead>
<tr>
<th>Instrument quality</th>
<th>Sampling strategy</th>
<th>Overall method</th>
</tr>
</thead>
<tbody>
<tr>
<td>I4 Instrument quality is irrelevant.</td>
<td>S4 Full coverage, no sampling involved.</td>
<td>O4 Approved standard in well-established discipline.</td>
</tr>
<tr>
<td>I3 Instruments well suited for the field situation and calibrated.</td>
<td>S3 Large sample of direct measurements, good sample design, controlled experiments and cross-validation.</td>
<td>O3 Reliable method, common within discipline.</td>
</tr>
<tr>
<td>I2 Instruments are not well matched for the field situation, no calibration performed.</td>
<td>S2 Indirect measurements, historical field data, uncontrolled experiments, or small sample of direct measurements.</td>
<td>O2 Acceptable method, but limited consensus on reliability.</td>
</tr>
<tr>
<td>I1 Instruments of questionable reliability and applicability.</td>
<td>S1 Educated guesses, very indirect approximations, handbook or “rule of thumb” estimates.</td>
<td>O1 Unproven methods, questionable reliability.</td>
</tr>
<tr>
<td>I0 Instruments of unknown quality or applicability.</td>
<td>S0 Pure guesses.</td>
<td>O0 Highly subjective method.</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
Table 4. Codes for “longevity” of uncertainty information (van Loon et al., this issue).

<table>
<thead>
<tr>
<th>Code</th>
<th>Explanation</th>
</tr>
</thead>
<tbody>
<tr>
<td>L0</td>
<td>Temporal variability of the uncertainty information is unknown.</td>
</tr>
<tr>
<td>L1</td>
<td>The uncertainty information is known to change significantly over time (specify how fast it changes if you know it).</td>
</tr>
<tr>
<td>L2</td>
<td>Uncertainty does not change significantly, in principle no updating required.</td>
</tr>
</tbody>
</table>
Table 5. Characterisation of uncertainty for various data types.

<table>
<thead>
<tr>
<th>Variable</th>
<th>Measurement – Space support</th>
<th>Measurement – Time support</th>
<th>Upscaled space support</th>
<th>Upscaled time support</th>
<th>Uncertainty category</th>
<th>Type of empirical uncertainty</th>
<th>Methodological quality</th>
<th>Longevity</th>
<th>Pdf type</th>
<th>Pdf parameters (mean, std)</th>
<th>Variogram/correlogram (Type, length scale)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Precipitation</td>
<td>200 cm³</td>
<td>1 day</td>
<td>13×13 km²</td>
<td>1 day</td>
<td>B1</td>
<td>M1 3, 2, 3, 4</td>
<td>L2 N</td>
<td>N</td>
<td>(0, 10%)</td>
<td>Exp (a=2 days)</td>
<td></td>
</tr>
<tr>
<td>Air temperature</td>
<td>10 cm²</td>
<td>1 day</td>
<td>10 cm²</td>
<td>1 day</td>
<td>B1</td>
<td>M1 3, 3, 3, 4</td>
<td>L2 N</td>
<td>N</td>
<td>(0, 5%)</td>
<td>Exp (a=2 days)</td>
<td></td>
</tr>
<tr>
<td>Relative humidity</td>
<td>10 cm²</td>
<td>1 day</td>
<td>10 cm²</td>
<td>1 day</td>
<td>B1</td>
<td>M1 3, 3, 3, 4</td>
<td>L2 N</td>
<td>N</td>
<td>(0, 10%)</td>
<td>Exp (a=2 days)</td>
<td></td>
</tr>
<tr>
<td>Pot. Evap.</td>
<td>10 cm²</td>
<td>1 day</td>
<td>1–20 m²</td>
<td>1 day</td>
<td>B1</td>
<td>M1 3, 3, 3, 4</td>
<td>L2 N</td>
<td>N</td>
<td>(0, 12%)</td>
<td>Exp (a=1 days)</td>
<td></td>
</tr>
<tr>
<td>Solar radiation</td>
<td>10 cm²</td>
<td>1 day</td>
<td>10 cm²</td>
<td>1 day</td>
<td>B1</td>
<td>M1 3, 3, 3, 4</td>
<td>L2 N</td>
<td>N</td>
<td>(0, 5%)</td>
<td>Exp (a=2 days)</td>
<td></td>
</tr>
<tr>
<td>Discharge</td>
<td>1–20 m²</td>
<td>1 day</td>
<td>1–20 m²</td>
<td>1 day</td>
<td>B1</td>
<td>M1 3, 3, 4</td>
<td>L2 N</td>
<td>N</td>
<td>(0, 10%)</td>
<td>Exp (a=90 days)</td>
<td></td>
</tr>
<tr>
<td>Tot N, streams</td>
<td>100 ml</td>
<td>1 day</td>
<td>1–20 m²</td>
<td>1 day</td>
<td>B1</td>
<td>M1 3, 3, 3, 4</td>
<td>L2 N</td>
<td>N</td>
<td>(0, 10%)</td>
<td>Exp (a=4 days)</td>
<td></td>
</tr>
<tr>
<td>Tot P, streams</td>
<td>100 ml</td>
<td>1 day</td>
<td>1–20 m²</td>
<td>1 day</td>
<td>B1</td>
<td>M1 3, 3, 3, 4</td>
<td>L2 N</td>
<td>N</td>
<td>(0, 12%)</td>
<td>Exp (a=1 days)</td>
<td></td>
</tr>
<tr>
<td>Heavy metals, streams</td>
<td>100 ml</td>
<td>10 sec</td>
<td>1–20 m²</td>
<td>1 month</td>
<td>B1</td>
<td>M1 3, 3, 3, 4</td>
<td>L2 N</td>
<td>N</td>
<td>(0, 20%)</td>
<td>Exp (a=1 day)</td>
<td></td>
</tr>
<tr>
<td>Pesticides and organic compounds, streams</td>
<td>100 ml</td>
<td>10 sec</td>
<td>1–20 m²</td>
<td>1 month</td>
<td>B1</td>
<td>M1 3, 3, 3, 4</td>
<td>L2 N</td>
<td>N</td>
<td>(0, 40%)</td>
<td>Exp (a=1 day)</td>
<td></td>
</tr>
<tr>
<td>Abstraction from groundwater</td>
<td>Wellfield year</td>
<td>Wellfield</td>
<td>1 year</td>
<td>B1</td>
<td>M1</td>
<td>3, 3, 3, 4</td>
<td>L2 N</td>
<td>N</td>
<td>(0, 2%)</td>
<td>N/A</td>
<td></td>
</tr>
<tr>
<td>Groundwater head – manual reading</td>
<td>10 cm</td>
<td>10 s</td>
<td>1 km²</td>
<td>1 year</td>
<td>B1</td>
<td>M1 3</td>
<td>L2 N</td>
<td>N</td>
<td>(0, 1.35 m)</td>
<td>N/A</td>
<td></td>
</tr>
<tr>
<td>Groundwater head – automatic recorder</td>
<td>10 cm</td>
<td>10 s</td>
<td>1 km²</td>
<td>1 year</td>
<td>B1</td>
<td>M1 3</td>
<td>L2 N</td>
<td>N</td>
<td>(0, 1.25 m)</td>
<td>N/A</td>
<td></td>
</tr>
<tr>
<td>Nitrate in groundwater</td>
<td>100 ml</td>
<td>10 s</td>
<td>100 ml</td>
<td>1 year</td>
<td>B1</td>
<td>M1 3</td>
<td>L2 N</td>
<td>N</td>
<td>N/A</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Pesticides in groundwater</td>
<td>100 ml</td>
<td>10 s</td>
<td>100 ml</td>
<td>1 year</td>
<td>B1</td>
<td>M1 3</td>
<td>L2 N</td>
<td>N</td>
<td>N/A</td>
<td></td>
<td></td>
</tr>
<tr>
<td>pH in groundwater</td>
<td>100 ml</td>
<td>10 s</td>
<td>100 ml</td>
<td>1 year</td>
<td>B1</td>
<td>M1 3, 3, 4</td>
<td>L2 N</td>
<td>N</td>
<td>N/A</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Alkalinity in groundwater</td>
<td>100 ml</td>
<td>10 s</td>
<td>100 ml</td>
<td>1 year</td>
<td>B1</td>
<td>M1 3, 3, 3, 4</td>
<td>L2 N</td>
<td>N</td>
<td>N/A</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Soil – clay content</td>
<td>100 cm³</td>
<td>N/A</td>
<td>100 cm³</td>
<td>1 year</td>
<td>B1</td>
<td>M1 3, 3, 4, 4</td>
<td>L2 N</td>
<td>N</td>
<td>(0, 40%)</td>
<td>Spherical (a=20–33 m)</td>
<td></td>
</tr>
<tr>
<td>Soil – silt content</td>
<td>100 cm³</td>
<td>N/A</td>
<td>100 cm³</td>
<td>1 year</td>
<td>B1</td>
<td>M1 3, 3, 4, 4</td>
<td>L2 N</td>
<td>N</td>
<td>(0, 30%)</td>
<td>Spherical (a=20–26 m)</td>
<td></td>
</tr>
<tr>
<td>Soil – sand content</td>
<td>100 cm³</td>
<td>N/A</td>
<td>100 cm³</td>
<td>1 year</td>
<td>B1</td>
<td>M1 3, 3, 4, 4</td>
<td>L2 N</td>
<td>N</td>
<td>(0, 25%)</td>
<td>Spherical (a=20–35 m)</td>
<td></td>
</tr>
<tr>
<td>Soil – organic matter</td>
<td>100 cm³</td>
<td>N/A</td>
<td>100 cm³</td>
<td>1 year</td>
<td>B1</td>
<td>M1 3, 3, 4, 4</td>
<td>L2 N</td>
<td>N</td>
<td>(0, 25%)</td>
<td>Spherical (a=34–46 m)</td>
<td></td>
</tr>
<tr>
<td>CaCO₃</td>
<td>100 cm³</td>
<td>N/A</td>
<td>100 cm³</td>
<td>1 year</td>
<td>B1</td>
<td>M1 3, 3, 4, 4</td>
<td>L2 N</td>
<td>N</td>
<td>(0, 10%)</td>
<td>Exponential (a=30 m)</td>
<td></td>
</tr>
</tbody>
</table>
Table 6. Instrumentation of meteorological stations.

<table>
<thead>
<tr>
<th>Variable</th>
<th>Precipitation stations</th>
<th>Climate station before 2001</th>
<th>Climate station after 2001</th>
</tr>
</thead>
<tbody>
<tr>
<td>Precipitation</td>
<td>Hellman, 150 cm height</td>
<td>CMII Kipp and zonen</td>
<td>Star sensor</td>
</tr>
<tr>
<td>Solar radiation</td>
<td></td>
<td>PT500 Aanderaa</td>
<td>PT Vaisala</td>
</tr>
<tr>
<td>Temperature</td>
<td></td>
<td>Malling 884</td>
<td>Waa151 and Wav151 Vaisala</td>
</tr>
<tr>
<td>Wind speed</td>
<td></td>
<td>Lambrecht hair hydrometer</td>
<td>Humicap Vaisala</td>
</tr>
<tr>
<td>Relative humidity</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
Fig. 1. Odense Fjord Basin.
Fig. 2. Standard deviation for daily precipitation as a function of the upscaled spatial support.
Fig. 3. Standard deviation for monthly precipitation as a function of the upscaled spatial support.
Fig. 4. Daily and monthly values of Total N for 1990 for Odense River, station 45.21.
Fig. 5. Autocorrelogram of Total N based on data for the period 1990–2003 after removing the seasonal pattern by subtracting monthly averages. The curve is an exponential function with a time scale of 4 days.
Fig. 6. Daily and monthly values of Total P for 1990 for Odense River, station 45.02.
Fig. 7. Autocorrelogram of Total P based on data for the period 1990–2003 after removing the seasonal pattern by subtracting monthly averages. The curve is an exponential function with a time scale of 1 day.