



# Ground referencing GRACE satellite estimates of groundwater storage changes in the California Central Valley, USA

B. R. Scanlon, L. Longuevergne, D. Long

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1 **Ground Referencing GRACE Satellite Estimates of Groundwater Storage Changes in the**  
2 **California Central Valley, US**

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5 **Scanlon, B.R.<sup>1</sup>, Longuevergne, L.<sup>2</sup> and Long, D.<sup>2</sup>**

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8 <sup>1</sup>Bureau of Economic Geology, Jackson School of Geosciences, University of Texas at Austin,  
9 Austin, Texas 78758, United States

10 <sup>2</sup>Géosciences Rennes - UMR CNRS 6118, Université de Rennes 1, 35042 Rennes Cedex,  
11 France

12

13 **Abstract**

14 There is increasing interest in using GRACE (Gravity Recovery and Climate Experiment)  
15 satellite data to remotely monitor groundwater storage variations; however, comparisons with  
16 ground-based well data are limited but necessary to validate satellite data processing,  
17 especially when the study area is close to or below the GRACE footprint. The Central Valley is a  
18 heavily irrigated region with large-scale groundwater depletion during droughts. Here we  
19 compare updated estimates of groundwater storage changes in the California Central Valley  
20 using GRACE satellites with storage changes from groundwater level data. A new processing  
21 approach was applied that optimally uses available GRACE and water balance component data  
22 to extract changes in groundwater storage. GRACE satellites show that groundwater depletion  
23 totaled  $\sim 31.0 \pm 3.0 \text{ km}^3$  for GRGS (Groupe de Recherche de Geodesie Spatiale) satellite data  
24 during the drought from Oct 2006 through Mar 2010. Groundwater storage changes from  
25 GRACE agreed with those from well data for the overlap period (Apr 2006 through Sep 2009)  
26 ( $27 \text{ km}^3$  for both). General correspondence between GRACE and groundwater level data  
27 validates the methodology and increases confidence in use of GRACE satellites to monitor  
28 groundwater storage changes.

29 **Introduction**

30 Water scarcity is a critical issue globally with an estimated 1.1 billion people lacking access  
31 to safe drinking water globally (UN Development Program, 2006). Groundwater is increasingly  
32 being used for drinking water and serves an estimated 1.5 – 2.8 billion people globally and up to  
33 98% of rural populations (Morris et al., 2003). There has been a rising trend in groundwater use  
34 for irrigation since the 1940s and 1950s and groundwater now accounts for  $\sim 40\%$  of irrigation  
35 water globally (Siebert and Döll, 2010). Increasing reliance on groundwater for drinking water  
36 and irrigation is attributed to ubiquity of groundwater resources, ease of development with  
37 minimal capital costs, generally good water quality because of filtering during recharge, and  
38 greater resilience to drought relative to surface water (Giordano, 2009). The importance of  
39 groundwater to water resources should continue to increase with projected reductions in  
40 reliability of surface water and soil moisture associated with climate extremes related to climate  
41 change (Kundzewicz and Döll, 2009).

42 Groundwater is often referred to as the invisible resource and our understanding of the  
43 dynamics of groundwater resources is generally much less than that of surface water.  
44 Monitoring networks for groundwater are more limited than those of surface water. Even when  
45 monitoring networks are available, access to data is often restricted. Because of the general

46 lack of monitoring data, there has been great interest in use of remote sensing to monitor  
47 changes in groundwater storage, specifically in use of GRACE satellites. GRACE consists of  
48 two satellites that track each other at a distance of ~220 km and are ~450 km above the land  
49 surface. A rule of thumb for estimating GRACE footprint is to use the elevation of the satellites  
50 ( $450 \times 450 \text{ km} = \sim 200,000 \text{ km}^2$  basin area). Measurements of the distance between the  
51 satellites to within micron scale resolution are used to derive a global map of changes in the  
52 Earth's gravity field at 10-day to monthly intervals. Gravity variations at monthly to annual  
53 timescales may be interpreted as changes in water distribution on the continents after correction  
54 for impacts of tidal, atmospheric, and oceanic contributions (Bettadpur, 2007; Bruinsma et al.,  
55 2010).

56 GRACE data provide vertically integrated estimates of changes in total water storage  
57 (TWS), which include changes in snow water equivalent storage (SWES), surface water  
58 reservoir storage (RESS), soil moisture storage (SMS), and groundwater storage (GWS). Using  
59 a priori monitoring or model-based estimates of SWES, RESS, and SMS, changes in GWS can  
60 be calculated as a residual from the disaggregation equation:  $\Delta\text{GWS} = \Delta\text{TWS} - \Delta\text{SWES} -$   
61  $\Delta\text{RESS} - \Delta\text{SMS}$ .

62 GRACE satellites provide continuous monitoring of TWS changes globally. GRACE has  
63 been used to monitor GWS changes in global hotspots of depletion (Wada et al., 2010) in NW  
64 India (Rodell et al., 2009; Tiwari et al., 2009), US High Plains (Strassberg et al., 2007;  
65 Longuevergne et al., 2010), and in the California Central Valley (Famiglietti et al., 2011).  
66 However, with the exception of the High Plains, where detailed groundwater level monitoring  
67 has been conducted since the 1980s in ~ 9000 wells annually (McGuire, 2009), GRACE-based  
68 estimates of GWS have not been compared with ground-based data in NW India or in the  
69 Central Valley. Other studies that have compared GRACE data with groundwater level  
70 monitoring data have generally focused on seasonal signals rather than long-term trends and  
71 groundwater level data have generally been limited to  $\leq 100$  wells (Yeh et al., 2006; Moiwo et al.,  
72 2009; Rodell et al., 2007).

73 GRACE satellites provide a spatially filtered image of real TWS that needs to be processed  
74 to produce information on changes in TWS over a space-limited area or basin (Swenson and  
75 Wahr, 2002; Klees et al., 2007; Longuevergne et al., 2010). A large number of processing steps  
76 and uncertainties in other water balance components used to estimate changes in GWS from  
77 TWS make it imperative to compare GRACE GWS changes with ground-based data to assess  
78 their validity, especially when the size of the area of interest is close to or below GRACE  
79 footprint ( $\sim 200,000 \text{ km}^2$ ) (Yeh et al., 2006). Ground-based estimates of GWS changes are

80 generally derived from water table or potentiometric surface fluctuations and require information  
81 on aquifer storage coefficients to translate water level fluctuations to water storage (Domenico  
82 and Schwartz, 1998).

83 The primary objective of this study was to compare GRACE-based estimates of GWS  
84 changes in the Central Valley of California with ground-based estimates from water-level data  
85 from wells to assess reliability of GRACE-based estimates of groundwater depletion. Secondary  
86 objectives include use of an updated processing approach for GRACE data that considers  
87 spatial variability in water balance components and should reduce uncertainties in GWS and  
88 evaluation of different temporal filters for estimation of long-term trends in storage. for GRACE  
89 data The area of the Central Valley (52,000 km<sup>2</sup>) is below the limit of GRACE footprint  
90 (~200,000 km<sup>2</sup>); however, large mass changes in the aquifer as a result of irrigation pumpage  
91 allow storage changes to be detected by GRACE. The Central Valley is an extremely important  
92 region for agricultural productivity in California and in the US with an economic value of ~ 20  
93 billion dollars in 2007 (NASS, 2007; <http://www.nass.usda.gov/>, accessed in 2010). Because  
94 this region plays a large role in table food production in the US it is critical to understand the  
95 dynamics of the groundwater system which is essential for irrigated agriculture, particularly in  
96 the Tulare Basin in the south. Previous groundwater modeling shows large-scale depletion  
97 during droughts (Faunt, 2009); therefore, the recent drought from ~ 2006 – 2009 should provide  
98 a large signal for GRACE analysis. This study expands on the recent analysis of GRACE data  
99 for the Central Valley described in Famiglietti et al. (2011) by comparing results from GRACE-  
100 based estimates of GWS changes with those from groundwater level data and using a different  
101 processing approach

## 102 **Methods**

### 103 **GRACE Data**

104 Water storage changes were estimated for the Sacramento and San Joaquin River Basins  
105 (154,000 km<sup>2</sup> area), which include the Central Valley (52,000 km<sup>2</sup> area) (Fig. 1). GRACE data  
106 from CSR (Center for Space Research, Univ. of Texas at Austin) and GRGS analysis centers  
107 were used because they represent two different processing strategies: one of the least  
108 constrained solutions, CSR RL04 (Bettadpur, 2007) and one of the most constrained, GRGS  
109 RL02 (Bruinsma et al., 2010). Comparison of these two products allows estimation of the  
110 confidence in GRACE-derived water storage changes. CSR provides data at monthly intervals  
111 and GRGS at 10 day intervals. The GRACE processing approach was updated in this study

112 relative to the regular processing approach applied in most studies. The following sections  
113 describe the regular processing approach which provides context for the updated approach.

#### 114 **Regular GRACE Processing**

115 The regular processing approach estimates changes in TWS from GRACE data by filtering  
116 the data, applying corrections for bias and leakage (Swenson et al., 2002, Klees et al., 2007,  
117 Longuevergne et al., 2010) and solving the disaggregation equation to calculate changes in  
118 GWS as shown in Fig. 2. This processing is described in detail in Auxiliary Material (Section 1).

119 Changes in TWS are estimated from GRACE data by recombining spherical harmonics up  
120 to degree 50 (truncation to degree 50) for GRGS and to degree 60 for CSR. Further filtering was  
121 applied to CSR data to remove north-south stripes (Swenson and Wahr, 2006) and to reduce  
122 high frequency noise (300 km Gaussian smoother). No further filtering beyond truncation at  
123 degree 50 was applied to GRGS data because there are no north-south stripes and the  
124 regularization process used on GRGS precludes the need for additional filtering. In the  
125 following, filtering will refer to both truncation and filtering.

126 Because filtering removes TWS signal at small spatial scales, in addition to high frequency  
127 noise, the amplitude of the TWS signal has to be restored. Most studies calculate a rescaling or  
128 multiplicative factor to restore the signal amplitude by applying the same filtering as applied to  
129 GRACE data to a synthetic mass distribution and calculating the ratio between filtered and  
130 unfiltered data. Applying filtering to a synthetic mass distribution is sometimes referred to as  
131 “forward modeling” and generates a mass distribution similar to what GRACE sees. Ideally the  
132 synthetic mass distribution should match the actual mass distribution as closely as possible. For  
133 TWS, this mass distribution should include all components of the water budget. The synthetic  
134 mass distribution is generally derived from Global Land Data Assimilation System (GLDAS) land  
135 surface models (LSMs), such as CLM, MOSAIC, NOAH, and VIC. Output from the LSMs is  
136 generally used as a proxy for the true water mass distribution. The reliability of LSM outputs  
137 depends on the ability of the LSM to approximate the true water mass distribution in the system.  
138 LSMs are simplifications of the natural system with limited resolution and most simulate snow  
139 and soil moisture storage but generally do not include surface water or groundwater storage.  
140 Runoff is simulated but is not routed, and cold processes are not simulated accurately  
141 (especially glaciated areas). Water redistribution from groundwater to soils through irrigation is  
142 also not simulated in most LSMs. The signal restoration process uses spatial variability from  
143 LSMs which may or may not be realistic and could lead to biased estimates in TWS  
144 (Longuevergne et al., 2010). Once the TWS signal is restored, the various water balance

145 components, including SWES, RESS, and SMS basin averages, are then subtracted from TWS  
146 to calculate GWS as a residual (Fig. 2). Therefore, this regular processing approach does not  
147 consider spatial variability of masses in a basin and uses a rescaling factor based on a priori  
148 LSM masses that ignore GWS.

#### 149 **Updated GRACE Processing**

150 GRACE processing was updated in this study to provide more reliable estimates of GWS  
151 changes with optimal use of available information. The new processing approach differs from  
152 the regular approach in calculating GWS from TWS using filtered data at GRACE resolution  
153 before any rescaling is applied (Fig. 2). In this updated approach, GRACE data were  
154 recombined and filtered to provide filtered TWS as previously described. The various water  
155 balance components (SWES, SMS, and RESS) were then filtered in the same way as GRACE  
156 data, i.e. projection of model grids on spherical harmonics, recombination to maximum degree  
157 50 for comparison with GRGS data or degree 60 for comparison with CSR data and application  
158 of a 300 km Gaussian filter for comparison with CSR data. Gridded SWES and SMS data and  
159 point RESS data were used, allowing spatial variability in these different storage components to  
160 be incorporated in the processing, in contrast to the regular processing approach which uses  
161 basin means. Restoring the amplitude of the filtered GWS signal only requires bias correction  
162 (simple rescaling) and no leakage correction (no external groundwater masses leaking into the  
163 area of interest) because GWS changes are assumed to be concentrated inside the aquifer;  
164 therefore, errors associated with leakage corrections should be minimized. Bias correction was  
165 done using a multiplicative factor that was calculated from the ratio of unfiltered to filtered GWS  
166 changes from output from the USGS Central Valley hydrologic model. This is important because  
167 GWS changes are highly variable spatially, i.e. ~ 10 times greater in the Tulare Basin in the  
168 south than elsewhere in the Central Valley (Faunt, 2009). This updated processing approach  
169 minimizes reliance on a-priori information and allows GRACE to be used as independent  
170 observational data as much as possible. However, this updated approach requires knowledge of  
171 changes in SWES, SMS, and RESS inside and outside the basin and the quality of the GWS  
172 changes still depends on the quality of the models for these water balance components.  
173 Computation of GWS is independent of the TWS calculation at basin scale.

174 Spatial distribution of water masses may differ among storage components and may have  
175 different signatures at GRACE resolution (i.e. filtered). For example, SMS is more or less  
176 distributed uniformly over the area of interest; however, SWE is concentrated in the mountains,  
177 generally at the edge of the basins, while GWS may be focused in on one part of the basin. The

178 importance of considering spatial variability in mass variations within the different storage  
179 components on GRACE GWS changes is shown by comparing the different multiplicative  
180 factors for converting filtered storages to true storages calculated separately for each  
181 component of the water budget. The equivalent multiplicative factor to restore the GRACE  
182 signal for GRGS (CSR) varies by up to 15% depending on spatial variability in water mass  
183 distribution (2.69 for GRGS (4.94 for CSR)) multiplicative factor for SWES, i.e. unfiltered SWES  
184 divided by filtered SWES, 2.30 (4.29) for RESS, 2.58 (4.74) for SMS, and 2.37 (4.28) for GWS).  
185 The more concentrated the mass distribution, the lower the multiplicative factor. Therefore, use  
186 of a single multiplicative factor applied to TWS in the regular processing approach ignores  
187 spatial variability in water storage in each of the components and increases propagation of  
188 uncertainties in GRACE GWS estimates.

### 189 **Water Storage Components and Uncertainties**

190 The following describes each of the water storage components and estimation of  
191 uncertainties. Changes in TWS over the Central Valley river basins were estimated from CSR  
192 and GRGS data as described previously and also in more detail in Auxiliary Material (Section 1).  
193 TWS was not used directly to calculate GWS but was only estimated to evaluate temporal  
194 variability in TWS in the system. Uncertainties in TWS changes were estimated from GRACE  
195 measurement uncertainties derived from residuals over the Pacific Ocean at the same latitude  
196 as the Sacramento and San Joaquin River Basins (Chen et al. 2009) with a magnitude 18 mm  
197 for GRGS and 22 mm for CSR. While GRACE is corrected from Glacial Isostatic Adjustment  
198 (GIA) using the ICE5G PGR model from Paulson et al. (2007), impacts of GIA in the Central  
199 Valley are minimal.

200 Uncertainties in GWS were estimated from propagating errors in SWE, RESS, and SMS  
201 from LSMs into GWS changes, resulting in 10 d (for GRGS) and monthly (for CSR) errors in  
202 GWS with a magnitude of 55 mm for GRGS and 67 mm for CSR. As the rescaling or  
203 multiplicative factor has a direct impact on the amplitude of GWS changes, we also computed  
204 an error estimate on the bias correction for GWS. Sources of uncertainty in the multiplicative  
205 factor are twofold: (1) numerical calculation in the integration process, estimated to be  $\leq 1\%$   
206 when integrating on a 0.25 degree grid (Longuevergne et al., 2010), and (2) uncertainty in mass  
207 distribution within the area of interest. For the latter uncertainty, the multiplicative factor was  
208 calculated with different realistic mass distributions: USGS Central Valley hydrologic model,  
209 considering simulated mass depletion in the different subbasins during the previous droughts  
210 and well analysis (see later), considering spatial variability in water level variations, variability in



211 specific yield, or multiplication of both. Variability among computed multiplicative factors is ~  
212 6%.

213 Water storage changes from snow cover were based on snow data assimilation system  
214 (SNODAS). Because SNODAS assimilates ground-based snow water equivalent (SWE)  
215 estimates in California (Barret, 2003), it is considered the most reliable model for this study. As  
216 SNODAS output is only available after October 2003, the time series was supplemented with  
217 SWE output from the National Land Data Assimilation System (NLDAS) MOSAIC land surface  
218 model, LSM rescaled with SNODAS data. The scaling factor was calculated by comparing  
219 standard deviations from SNODAS and NLDAS MOSAIC SWE for overlapping times.  
220 Uncertainties in SWES were estimated from variability between SNODAS and scaled NLDAS  
221 MOSAIC model. Calculated monthly uncertainties in SWES are 28 mm based on differences  
222 between the models; however, calculated uncertainties do not include potential model bias.

223 Variations in surface water reservoir storage were estimated from changes in water storage  
224 in the 26 largest reservoirs in the Sacramento-San Joaquin basins (California Department of  
225 Water Resources (<http://cdec.water.ca.gov/>) (Auxiliary Material, Section 2, Table S1). Because  
226 information on uncertainties in reservoir storage volumes is not available (only uncertainties in  
227 water level changes of ~3 mm from California Department of Water Resources), a conservative  
228 estimate of 10% reservoir volume error was assumed. To estimate changes in soil moisture  
229 storage, output from GLDAS LSMs (MOSAIC and VIC at 1° resolution and NOAH at 0.25°  
230 resolution) and NLDAS (MOSAIC at 0.125° resolution) were averaged. Uncertainties in SMS  
231 were estimated from variability among the LSMs (~ 3 mm/yr). Kato et al. (2007) showed that the  
232 variability among GLDAS models is greater than variability among forcing datasets and that the  
233 root mean square (RMS) error of SMS from the LSMs can be used as a conservative estimate  
234 of SMS uncertainty.

235 Trends in each of the water budget components were calculated to estimate storage  
236 depletion in response to the drought. Various temporal filters were applied to assess their  
237 impact on calculated water storage changes. Some suggest that the raw data should be used to  
238 estimate trends; however, most studies apply a temporal filter to remove seasonal fluctuations  
239 and high frequency noise to estimate long-term trends. One filtering approach was to remove  
240 seasonal components of the data series using a six-term harmonic series (sine and cosine  
241 periodic waves with annual, semiannual, and 3-month periods). A centered 12 month moving  
242 average was also applied. A fourth order Butterworth low-pass filter was finally tested. Trends in  
243 water storage changes and associated standard errors were estimated using weighted linear  
244 least squares regression, considering the inverse of squared errors in the weighting process.

245 **Groundwater Level Data**

246 Groundwater data were obtained from the California Department of Water Resources  
247 ([www.water.ca.gov/waterdatalibrary](http://www.water.ca.gov/waterdatalibrary)) to estimate GWS changes for comparison with GRACE-  
248 based estimates (Fig. 1). The Central Valley includes a shallow unconfined aquifer and deeper  
249 confined aquifers (Faunt, 2009). The unconfined aquifer provides water through drainable  
250 porosity related to water table decline times aquifer storage coefficient, termed specific yield. In  
251 contrast, the confined aquifer provides water through compressibility of water and the skeletal  
252 matrix and the aquifer storage coefficients are orders of magnitude less than those in the  
253 unconfined aquifer. In this analysis we focused on water storage changes in the unconfined  
254 aquifer because they are generally greater than those in the confined aquifer and many wells  
255 penetrate both aquifers, increasing hydraulic connectivity between the unconfined and confined  
256 systems (Faunt, 2009). Changes in GWS were computed from water-level time series from  
257 wells using the Karhunen-Loève transform which extracts the temporal signal in the regional  
258 groundwater behavior from a set of well observations with local representativity [Longuevergne  
259 et al., 2007]. Other terms used to describe KLT analysis in different fields include singular value  
260 decomposition (SVD) and empirical orthogonal functions (EOFs). Linear interpolation was used  
261 to recompute seasonal variations because KLT requires monitoring data for the same dates.  
262 The first three eigenvectors were considered which account for ~ 80% of the total variance.  
263 Kriging was used for analysis of spatial variability in water level data.

264 To evaluate results of the KLT well analysis, we compared GWS changes from well data  
265 with storage changes estimated from a groundwater model of the Central Valley that simulated  
266 flow from 1962 – 2003 (Faunt, 2009). While this comparison is not a true test of the KLT well  
267 analysis approach because the water level data were used in the groundwater model  
268 calibration, the Central Valley hydrologic model provides a much more comprehensive  
269 description of the groundwater system and this comparison provides a check on the well  
270 analysis technique. While data from 2,256 wells are available, this analysis requires temporally  
271 continuous data; therefore, only 670 wells were used from 1982 through 2010. Selected wells  
272 are generally sampled twice a year, during high and low water times, allowing general  
273 reconstruction of seasonal variations. Mean groundwater level changes over the aquifer were  
274 then computed using kriging and GWS changes were derived considering distributed specific  
275 yield data from Faunt (2009). A 10% uncertainty in specific yield data was also included  
276 because there are no published estimates on uncertainties in specific yield. Relative errors from  
277 the two sources of uncertainties were added up (10% specific yield, 2% kriging).

278

279 **Results and Discussion**

280 Changes in precipitation are one of the primary drivers of water storage variations.  
281 Precipitation anomalies from 2002 through 2010 ranged from -11 to -69 mm during 2002  
282 through 2004 but were high (surplus) during 2005 (227 mm) and 2006 (110 mm) (Fig. 3).  
283 Negative precipitation anomalies (deficit) were recorded during the drought with the lowest  
284 values in 2007 (-259 mm) with lesser deficits in 2008 (-155 mm) and 2009 (-81 mm). The  
285 drought ended in 2010 with a positive precipitation anomaly of 290 mm.

286 Monthly TWS changes from GRGS and CSR TWS are highly correlated ( $r^2=0.93$ ) and  
287 amplitude ratios are close to one, even after removal of seasonal variations (Fig. 3). Moreover,  
288 the difference between CSR and GRGS TWS time series ( $\sim 26$  mm) is slightly larger but very  
289 similar to estimated monthly RMS errors (18 mm for GRGS and 22 mm for CSR). Similarity in  
290 TWS changes from GRGS and CSR increases confidence in GRACE output from different  
291 processing centers. TWS changes are highest in spring (Feb/Mar) and lowest in fall (Sept/Oct)  
292 with amplitudes ranging from 15 to 30 km<sup>3</sup> at different times. TWS changes were relatively  
293 uniform during 2002 to 2004 and increased by  $\sim 15$  km<sup>3</sup> (Apr 2004 – Mar 2006, GRGS and CSR)  
294 in response to increased precipitation. Depletion in TWS during the drought was greatest during  
295 the beginning of the drought, when precipitation was lowest in 2007 (-259 mm). The drought has  
296 been documented to persist during water years 2007 through 2009 (i.e. Oct 2006 through Sept  
297 2009) (Jones, 2010). The maximum depletion in TWS occurred from Jan 2006 through Jul 2009  
298 and ranged from  $39.0 \pm 2.5$  km<sup>3</sup> (CSR) to  $40.8 \pm 0.9$  km<sup>3</sup> (GRGS) based on a Butterworth filter to  
299 remove seasonal signals and high frequency noise. Different filters were evaluated; however,  
300 errors in the Butterworth filter were among the lowest (Auxiliary Material, Section 3, Fig. S1).

301 The largest reductions in snow water equivalent and soil moisture storage occurred during  
302 winter of 2006 – 2007 because this was the driest period of the drought (Fig. 4). The snowpack  
303 reservoir decreased markedly during the winter of 2006 – 2007 but increased after that resulting  
304 in essentially zero overall change in storage during the drought. Surface water reservoir storage  
305 from the 26 largest reservoirs decreased by  $7.3 \pm 0.6$  km<sup>3</sup> from Oct 2006 through Sep 2009. The  
306 largest reductions in simulated SMS from the various LSMs also occurred during the first year of  
307 the drought with recovery after that time. Simulated changes in SMS may not be highly reliable  
308 because the LSMs do not simulate redistribution of water from the aquifer to the soil zone from  
309 irrigation.

310

311 **GRACE Estimates of GWS Changes and Comparison with Groundwater Level Data**

312 While the GWS change signal varies around that of TWS (standard deviation TWS [CSR &  
313 GRGS] 20 km<sup>3</sup>, GWS CSR 21 km<sup>3</sup>; GWS GRGS 13 km<sup>3</sup>), uncertainties in GWS changes are  
314 about a factor of three higher than those in TWS (RMS errors: CSR: GWS 10.2 km<sup>3</sup>; TWS 3.3  
315 km<sup>3</sup>; GRGS GWS 8.4 km<sup>3</sup>; TWS 2.8 km<sup>3</sup>). The following discussion focuses on GWS changes  
316 from GRGS data because they are less noisy than those from CSR data (Fig. 5; Auxiliary  
317 Material, Section 4, Fig. S3). The temporally filtered GWS data show that GWS increased  
318 slightly from Apr 2004 through Mar 2006 ( $2.7 \pm 0.5$  km<sup>3</sup>) when precipitation was high. However,  
319 GWS decreased sharply during the drought by  $31.0 \pm 3.0$  km<sup>3</sup> from Oct 2006 through March 2010  
320 (Table 1). Use of raw data resulted in depletion of only 5.1 km<sup>3</sup>, showing the importance of  
321 temporally filtering the data to remove seasonal signals and high frequency noise. The  
322 Butterworth and centered 12 month moving average filters provided similar results whereas the  
323 seasonal sine/cosine function did not smooth the data and resulted in the largest errors ( $\pm 5$  km<sup>3</sup>)  
324 (Auxiliary Material, Section 3, Fig. S2). Mean GWS depletions from this study are 16%  
325 ( $27.7 \pm 5.2$  km<sup>3</sup> CSR) and 44% ( $34.4 \pm 3.2$  km<sup>3</sup> GRGS) higher than that based on analysis by  
326 Famiglietti et al. (2011) for CSR ( $23.9 \pm 5.8$  km<sup>3</sup>) for the same time period (Apr 2006 through Mar  
327 2010). Therefore GWS depletions during the drought in this study are within the error bars for  
328 CSR data and slightly higher for GRGS data relative to the estimate from Famiglietti et al.  
329 (2011).

330 Although there is a seasonal component to the GRACE based GWS changes (~30 mm) for  
331 GRGS, ~47 mm for CSR, which is below the 10 d to monthly error estimate (GRGS 55 mm;  
332 CSR 67 mm), it is not considered reliable because it is the residual of seasonal fluctuations in  
333 other water balance components, including SWES, RESS, and SMS, and reflects uncertainties  
334 in seasonal storage changes in these components with associated phase lags that can result in  
335 large differences after subtraction.

336 GWS changes were also calculated from well data by converting water level changes to  
337 water volumes using spatially distributed specific yield (Fig. 6). Typical well hydrographs for the  
338 different basins indicate minimal water level declines in the north and all declines focused in the  
339 Tulare Basin in the south (Fig. 1). GWS changes using KLT for time series analysis and kriging  
340 for spatial variability in this study compared favorably with simulated GWS changes from the  
341 Central Valley hydrologic model for the overlap period of the groundwater model ( $r^2 = 0.98$ ; Fig.  
342 7). Well analysis for the 1987 – 1992 drought yielded a GWS decline of 8.2 km<sup>3</sup>/yr, similar to the  
343 simulated GWS decline from the model of 8.2 km<sup>3</sup>/yr. This comparison gives confidence in the

344 KLT/kriging approach used to analyze the well data. Although the Central Valley model also  
345 used the well data for calibration, the model represents a much more comprehensive evaluation  
346 of the groundwater system.

347 To compare GWS changes from the well data with those from the GRACE data,  
348 groundwater depletion from the well data was forward modeled to determine what GRACE can  
349 see (Auxiliary Material, Section 5, Fig. S4). The same spatial filtering was applied to the well  
350 data as is applied to GRACE products (Fig. 2). Although there is 10 times more depletion in the  
351 Tulare Basin in the southern part of the Central Valley, it is not possible to determine this at  
352 GRACE resolution (Figs. S4a and S4b). The GWS anomaly is spread above the CV aquifer,  
353 shifted towards the south. Spatial trends in GWS depletion from CSR and GRGS data (Figs.  
354 S4c and S4d) generally correspond to the modeled impact of depletion on groundwater (Figs.  
355 S4a and b), with equivalent amplitude and position. In addition to using standard errors in trend  
356 estimates of GWS from GRACE and well data, we also estimated the GWS signal in the oceans  
357 for the same area as the Central Valley. The signal in the ocean should be zero if all  
358 background models for mass disaggregation were perfect (oceanic & atmospheric model in  
359 GRACE processing, SWES, SMS, and RESS for GWS extraction); therefore, nonzero values  
360 suggest errors in GWS of ~ 30% of groundwater depletion after integration over an area as  
361 large as the Central Valley river basins. These error estimates may be more reliable than the  
362 standard errors in trends and in multiplicative factors, which probably underestimate total error.  
363 While the main negative GWS anomaly is located above the Central Valley aquifer, it is shifted  
364 towards the mountains for both GRGS and CSR solutions. The north-south trending anomaly,  
365 along the mountain range, suggests that snow water equivalent was not properly corrected for  
366 when extracting the GWS contribution.

367 Because the well data only extend to December 2009, GWS changes from the well data  
368 were compared with GRACE-based estimates for the period Apr 2006 through Sep 2009 to  
369 avoid problems with filtering toward the end of the data record (Table 1). Groundwater depletion  
370 from the well data is the same as that from GRACE GRGS data (both ~27 km<sup>3</sup>) for the 3.5 yr  
371 period (Table 1). These comparisons indicate that the GRACE based estimates of GWS  
372 changes are generally consistent with those from well data.

373 Reduction in GWS from GRACE during the recent drought (8.9 km<sup>3</sup>/yr) is similar to GWS  
374 reductions from previous droughts from the Central Valley hydrologic model (1976 – 1977; 12.3  
375 km<sup>3</sup>/yr; 1987 – 1992; 8.2 km<sup>3</sup>/yr). Although precipitation during the recent drought was not as  
376 low as the 1976 – 1977 drought or the length of the recent drought was much shorter than the  
377 six year drought from 1987 – 1992, the impact of the recent drought on GWS was as large or

378 larger than that of previous droughts because surface water diversions from north to south were  
379 reduced to 10% by the third year of the drought to protect the endangered delta smelt species in  
380 response to the Central Valley Improvement Act of 1992 (California Dept. of Water Resources,  
381 2010). Reductions in surface water diversions resulted in large increases in groundwater  
382 pumpage and amplified the impact of the drought on GWS changes.

### 383 **Future Work**

384 There are many areas of potential future work that would improve application of GRACE  
385 data for monitoring water storage changes in the Central Valley region. Updating the Central  
386 Valley hydrologic model to include the time period evaluated by GRACE would provide another  
387 estimate of GWS changes for comparison with GRACE-based estimates. This work is currently  
388 being conducted by the U.S. Geological Survey (Faunt, pers. comm. 2011). Improving the  
389 ground-based well monitoring network would greatly enhance estimates of GWS changes from  
390 this dataset. Basic information on wells, such as length and depth of screened intervals and  
391 whether wells penetrate only unconfined aquifers or unconfined/confined aquifers would be very  
392 helpful. Additional information on storage coefficients for converting water level data to water  
393 volumes is extremely important in this type of analysis. Expanding the well network, particularly  
394 in the Tulare Basin in the south, where most of the depletion has occurred, and including more  
395 continuous monitoring of water levels would provide improved information for estimating GWS  
396 changes. Information on soil moisture currently relies on output from LSMs; however, these  
397 models do not simulate irrigation. Developing a ground-based network of soil moisture sensors  
398 would be very beneficial for application to GRACE studies and would also provide a comparison  
399 of output from LSMs. Because LSMs play an integral role in GRACE processing, reliable water  
400 storage change estimates from GRACE depends on accurate LSMs. Improving LSMs to  
401 simulate soil moisture, groundwater, and irrigation is very important for applications of GRACE  
402 to groundwater depletion studies related to irrigated agriculture. The study of Famiglietti et al.  
403 (2011) used unconstrained CSR GRACE data whereas this study also used constrained or  
404 regularized GRGS GRACE data. The next GRACE CSR release will include some type of  
405 regularization or constraint (Save et al., 2010); therefore, filtering beyond truncation may no  
406 longer be required and spatial resolution may be improved.

### 407 **Conclusions**

408 While the area of the CV aquifer is less than the GRACE footprint (~ 200,000 km<sup>2</sup>),  
409 extensive groundwater depletion caused by irrigation results in a large signal that can be

410 detected by GRACE. A new processing approach was applied to GRACE data that calculates  
411 changes in GWS from TWS by subtracting SWES, RESS, and SMS using filtered data at  
412 GRACE spatial resolution minimizing uncertainties associated with LSMs for bias and leakage  
413 corrections. Moreover, this method takes into account the specific spatial distribution of each  
414 water storage component (including SWES, SMS, and RESS) resulting in different signatures  
415 on GRACE. In the case of the Central Valley, availability of high-resolution validated models  
416 (SNODAS, NLDAS) and accurate ground measurements for surface water storage reservoirs,  
417 greatly improved the ability to resolve GWS changes for this relatively small basin.

418 TWS changes from GRGS and CSR processing centers were similar ( $r^2 = 0.93$ ). Reductions  
419 in TWS during the drought ranged from  $39.0 \pm 2.5 \text{ km}^3$  (CSR) to  $40.8 \pm 0.9 \text{ km}^3$  (GRGS)  
420 (Butterworth filter) (Jan 2006 through July 2009). SWES and SMS decreased markedly in the  
421 early phase of the drought (2006 – 2007) but partially recovered after that resulting in overall  
422 negligible to low water storage changes. Reservoir storage decreased continuously during the  
423 drought by  $7.3 \pm 0.6 \text{ km}^3$  (Oct 2006 through Sep 2009).

424 Analysis of GWS changes focused on GRGS data because CSR data are noisier. GWS  
425 declined by  $31.0 \pm 3.0 \text{ km}^3$  based on maximum depletion from Oct 2006 through Mar 2010.  
426 Annual decline rates ( $8.9 \text{ km}^3/\text{yr}$ ) are consistent with typical decline rates from previous  
427 droughts (1976 – 1977;  $12.3 \text{ km}^3/\text{yr}$ ; 1987 – 1992;  $8.2 \text{ km}^3/\text{yr}$ ). GRACE based estimates of  
428 groundwater depletion during the drought are similar to those from well data based on the  
429 uppermost unconfined aquifer for the overlap period (Apr 06 – Jul 09; both  $27 \text{ km}^3$ ). The general  
430 consistency of GWS changes from GRACE and ground-based estimates increases confidence  
431 in application of GRACE for monitoring groundwater depletion.

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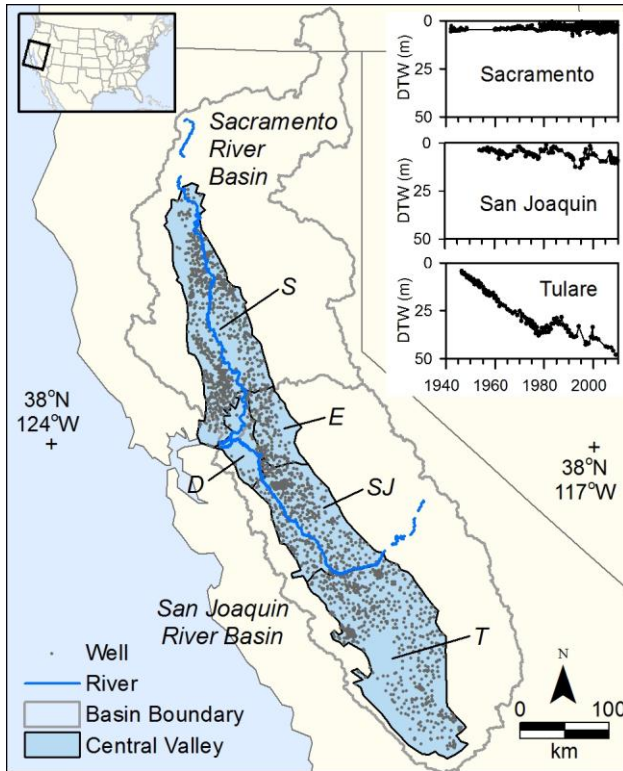
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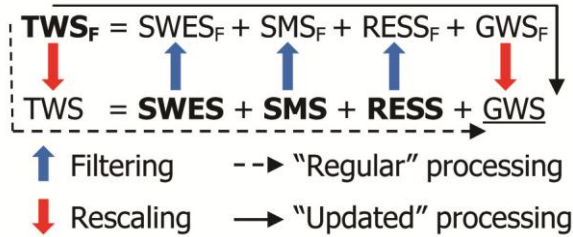
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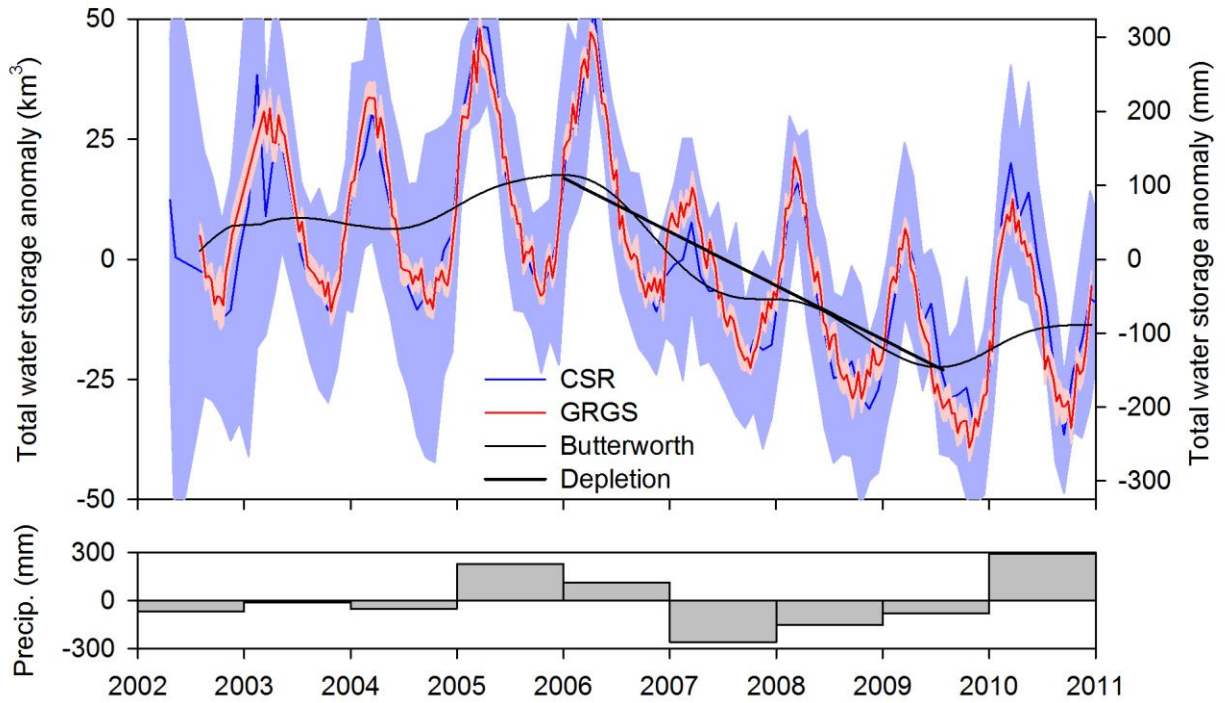
527 Figure 1. Central Valley aquifer subdivided into Sacramento, Delta, Eastside, San Joaquin, and  
528 Tulare basins and enclosed in the Sacramento River Basin in the north and San Joaquin River  
529 Basin in the south. Distribution of monitoring wells (~2,300 wells) is also shown. Well data were  
530 obtained from the California Department of Water Resources. Typical well hydrographs are  
531 shown for the Sacramento, San Joaquin, and Tulare basins. Note large groundwater depletion  
532 typical of the Tulare Basin.

533



534

535 Figure 2: Synthesis of regular and updated method for processing GRACE data to extract  
 536 changes in GWS. Subscript F represents spatial filtering, applied equivalently to GRACE and  
 537 water budget data (SWES, SMS, and RESS), i.e. truncation to degree 50 (GRGS) and degree  
 538 60 (CSR), removal of north-south stripes (for GRACE data only), and 300 km Gaussian filtering  
 539 (CSR). Regular processing involves filtering GRACE data to estimate TWS, rescaling TWS  
 540 using bias and leakage correction based on LSMs, and subtraction of changes in SWES, SMS,  
 541 and RESS to calculate changes in GWS. Updated processing calculates changes in GWS from  
 542 TWS using filtered models and data at GRACE resolution and rescaling  $GWS_F$  to  $GWS$  using  
 543 bias correction, no leakage correction required. The updated approach also uses spatial  
 544 variability of SWES, SMS, and RESS within the area of interest rather than mean values as in  
 545 the regular approach. Bolded text refers to available data from GRACE or models.  
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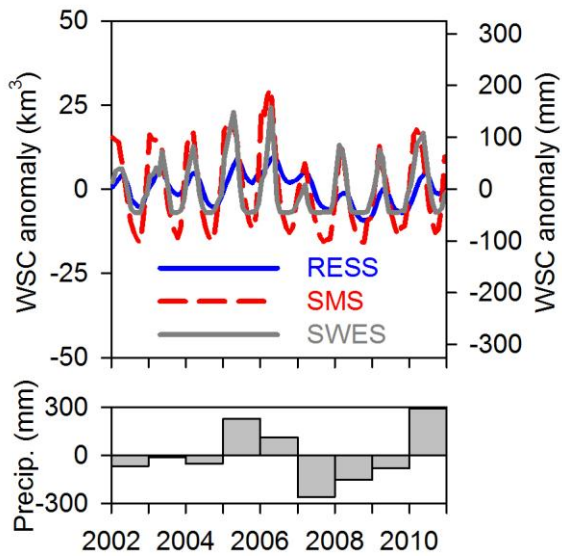
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548 Figure 3. Total water storage (TWS) change anomaly (in  $\text{km}^3$  and mm of water) from CSR  
 549 monthly data and GRGS 10 d data for the Sacramento and San Joaquin River Basins. Shaded  
 550 areas represent monthly errors. Estimation of TWS is described in Auxiliary Material (Section 1).  
 551 A Butterworth filter was applied to the GRGS data to remove the seasonal signal and high  
 552 frequency noise. The depletion trend during the drought is shown ( $40.8 \text{ km}^3$  from January 2006  
 553 through July, 2009). The precipitation anomaly is based on gridded data from PRISM (Daly et  
 554 al., 2009).

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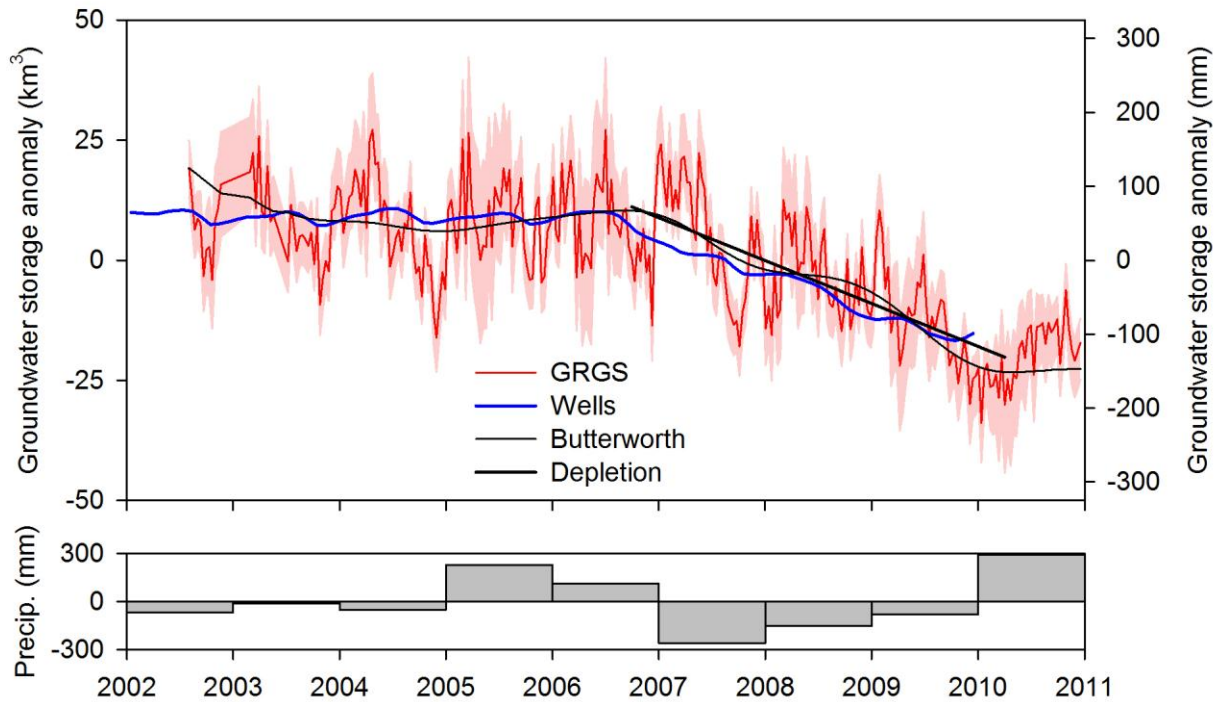
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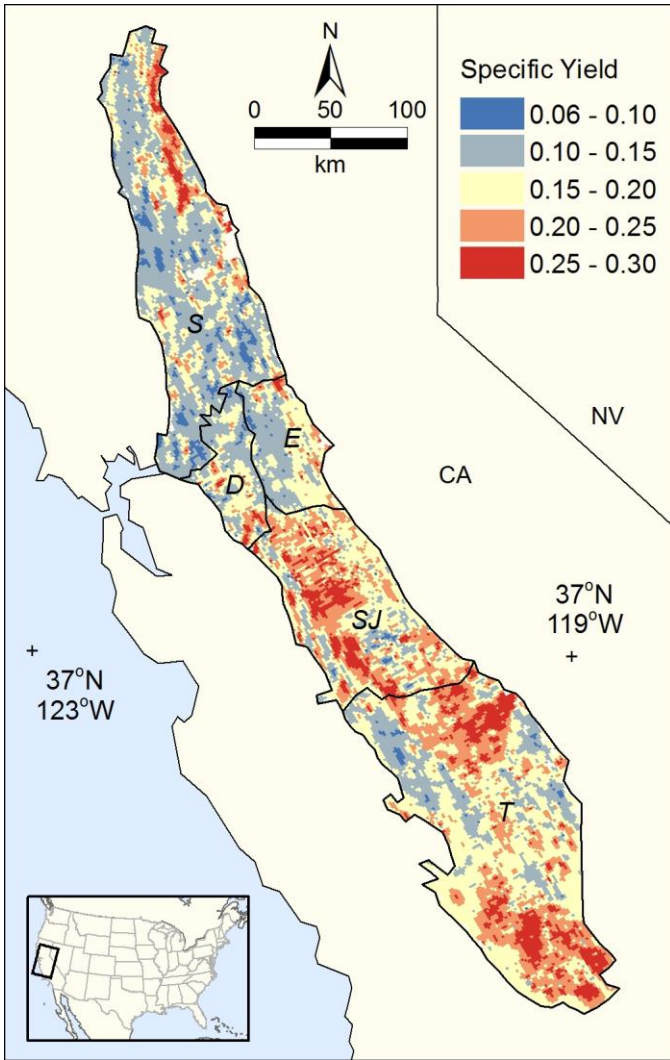
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559 Figure 4. Surface water reservoir storage (RESS), snow water equivalent storage (SWES), and  
 560 soil moisture storage (SMS) change anomalies for the Sacramento and San Joaquin River  
 561 basins. Note large reduction in water storages in response to the 2006 through 2009 drought,  
 562 particularly in the first year of the drought. The precipitation anomaly is based on gridded data  
 563 from PRISM (Daly et al., 2009).  
 564



566

567 Figure 5. Groundwater storage (GWS) change anomaly from GRGS data and monthly changes  
 568 GWS from well data from the upper unconfined aquifer. GWS change anomalies for CSR and  
 569 GRGS data are shown in Auxiliary Material, Section 4, Fig. S3. A Butterworth filter for removal  
 570 of seasonal trends and high frequency noise is shown. Application of other filters is shown in  
 571 Auxiliary Material, Section 3, Fig. S2. Depletion during the drought ( $31.0 \pm 3.0 \text{ km}^3$ ) is shown from  
 572 Oct. 2006 through March 2010. The precipitation anomaly is based on gridded data from PRISM  
 573 (Daly et al., 2009).



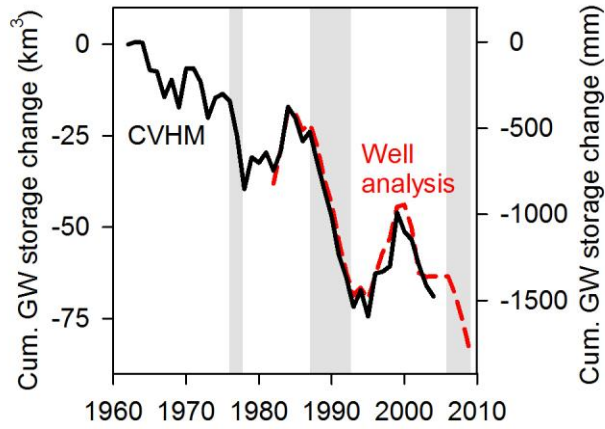
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575 Figure 6 . Variations in specific yield from Faunt (2009).

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578

579 Figure 7. Comparison of GWS changes from well analysis relative to simulated GWS changes  
 580 from the Central Valley hydrologic model (CVHM; Faunt, 2009). Drought periods are shaded  
 581 (1976 – 1977; 1987 – 1992; and 2006 – 2009).

582

583 Table 1. Trends in groundwater storage (GWS) changes during the drought in mm/yr, km<sup>3</sup>/yr,  
584 and in total km<sup>3</sup> for the different time periods shown based on GRGS and CSR GRACE data  
585 and well data (920 wells from the monitoring network). Depletion trends for different time  
586 periods and associated standard errors were estimated using weighted linear least squares  
587 regression, considering the inverse of squared errors (monthly for CSR and 10 d for GRGS) in  
588 the weighting process. Oct 1 2006 through Mar 31, 2010 represents the maximum depletion of  
589 GWS during the drought (Fig. ). Trends from Apr 1 2006 – Mar 31 2010 were calculated for  
590 comparison with depletion estimates from Famiglietti et al. (2011). Trends from Apr 1 2006 –  
591 Sep 30 2009 were calculated to compare depletion estimates from GRACE with those from  
592 analysis of 920 wells (Fig. 5). Results from application of different filters to remove seasonal  
593 fluctuations and high frequency noise are provided, including Butterworth, centered 12 month  
594 moving average (MA), a six-term harmonic series (sine and cosine periodic waves with annual,  
595 semiannual, and 3-month periods) (Seas.), and no temporal filter (trend from raw data).

<i>Time Interval</i>	<i>Model</i>	<i>Filter</i>	<i>Trend (mm/a)</i>	<i>Error (mm/a)</i>	<i>Trend (km<sup>3</sup>/a)</i>	<i>Error (km<sup>3</sup>/a)</i>	<i>Volume (km<sup>3</sup>)</i>	<i>Error (km<sup>3</sup>)</i>
Oct 1, 2006 to Mar 31, 2010	GRGS	Butterworth	57.6	5.5	8.9	0.8	31.0	3.0
		Moving average	58.1	5.6	8.9	0.9	31.3	3.0
		Seasonal	57.8	9.2	8.9	1.4	31.2	5.0
		None	9.4	-	1.4	-	5.1	-
Apr 1, 2006 to Mar 31, 2010	GRGS	Butterworth	55.9	5.3	8.6	0.8	34.4	3.3
	CSR	Butterworth	44.9	8.5	6.9	1.3	27.7	5.2
Apr 1, 2006 to Sep 30, 2009	GRGS	Butterworth	49.9	4.8	7.7	0.7	26.9	2.6
	Wells	Butterworth	49.7	0.5	7.7	0.1	26.8	0.3

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