

Optimisation of maintenance routing and scheduling for offshore wind farms

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Abstract An optimisation model and a solution method for maintenance routing and scheduling at offshore wind farms are proposed. The model finds the optimal schedule for maintaining the turbines and the optimal routes for the crew transfer vessels to service the turbines along with the number of technicians required for each vessel. The model takes into account multiple vessels, multiple periods (days), multiple Operation & Maintenance (O&M) bases, and multiple wind farms. We develop an algorithm based on the Dantzig-Wolfe decomposition method, where a mixed integer linear program is solved for each subset of turbines to generate all feasible routes and maintenance schedules for the vessels for each period. The routes have to consider several constraints such as weather conditions, the availability of vessels, and the number of technicians available at the O&M base. An integer linear program model is then proposed to find the optimal route configuration along with the maintenance schedules that minimise maintenance costs, including travel, technician and penalty costs. The computational experiments show that the proposed optimisation model and solution method find optimal solutions to the problem in reasonable computing times.

Key words: Maintenance scheduling, routing problem, offshore wind farm.

1. Introduction

The development of offshore wind farms has been significant over the past 20 years. One of the reasons for this growth is that a wind turbine at sea generally produces more electricity than that of its onshore equivalent as the average wind speed at sea is higher. However, the installation, operation, and maintenance costs are also much higher for offshore wind

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turbines, since more resources and infrastructures are needed to install and maintain a wind turbine at sea. According to Snyder and Kaiser (2009), the operations and maintenance costs could contribute a quarter of the life-cycle costs, making it one of the largest cost components of an offshore wind farm. One way to reduce the costs is to make the maintenance activities more efficient by optimising maintenance schedules and the routing of maintenance vessels. This potential for cost reduction becomes increasingly important as wind farms become larger and constructed farther from shore, increasing the vessel travel times both to and within the wind farms.

According to European Committee for Standardization (2010), maintenance activities in wind power systems involve corrective maintenance, predetermined (preventive) maintenance, and condition-based maintenance. Corrective maintenance is performed following detection of a failure where the aim of this maintenance is to restore normal operating conditions. Predetermined preventive maintenance is conducted at predetermined intervals or based on prescribed criteria such as the age of the equipment and production schedule. This maintenance aims to reduce the failure risk or performance degradation of the equipment. Condition-based maintenance is done by assessing the actual equipment condition using inspection or (on-line) condition monitoring. The maintenance activity is performed when there are indicators which give information that the system is deteriorating and the probability of failure is rising. In this paper, we deal with the maintenance scheduling problem where the recommended period for a set of turbines that need to be maintained is given. The turbines can be selected based on the principles of predetermined preventive maintenance or condition-based maintenance. A penalty cost is incurred in the model when the maintenance activity is performed after the recommended period.

Maintenance scheduling for offshore wind farms is a complex and challenging problem (Shafiee, 2015). The main goal of maintenance scheduling is to construct a detailed schedule of maintenance activities that have to be performed within a planning horizon. There are several factors that need to be considered when scheduling the maintenance activities of an offshore wind farm including the weather conditions, the availability of various resources (e.g. service vessels, crews, and spare parts), and the disruption to electricity generation. Resources needed for maintaining the offshore turbines are commonly based at the nearest port or Operation & Maintenance (O&M) base. The weather conditions (such as wind speed and wave height) and the vessel availability are the main factors that affect the performance of the maintenance activities. For safety reasons, the maintenance can only be performed in

periods where the required weather conditions are met. As good weather periods are limited in most locations where wind farms are currently located or being planned, maintenance schedules must be optimised to exploit the resulting weather windows. Once the maintenance schedules have been fixed (the period when the turbines in the wind farms will be serviced/visited), other aspects required to be addressed are as follows: the type of vessels that will be used for each period; the optimal route for each selected vessel to visit the set of turbines in the wind farms; and the number of each skill type of technicians required by each vessel for the given maintenance schedule and vessel route. Therefore, the maintenance problem of an offshore wind farm is a complex problem and difficult to solve to optimality.

The main contributions of this paper include: (i) Presenting a new routing and scheduling problem from the offshore wind industry that considers several logistics bases and the possibility of servicing more than one wind farms with the same fleet. (ii) Proposing a new mathematical model and solution method to solve the problem. (iii) Obtaining new optimal solutions for a set of benchmark problems from the literature along with the solutions for new more challenging problems.

The paper is organised as follows: Section 2 presents a description of the maintenance routing and scheduling problem for offshore wind farms, a brief review on maintenance scheduling in offshore wind farms, and an overview of related routing problems. Section 3 gives a description of the maintenance routing and scheduling problem for offshore wind farm. Section 4 presents the optimisation model and solution method for solving the maintenance routing and scheduling problem. Section 5 presents the computational results on the data available in the literature and new randomly generated data. The last section provides a summary of our findings and some avenues for future research.

2. Literature Review

2.1 Maintenance routing and scheduling for offshore wind farms

The maintenance routing and scheduling problem for an offshore wind farm was introduced by Dai *et al.* (2015). The problem consists of finding one route and schedule for each vessel to perform maintenance on a set of wind turbines over a planning period of several days. The model takes into account a penalty cost if the turbines are maintained after the recommended period. The model also considers the capacity of vessels in transporting

technicians and spare parts. Stålhane *et al.* (2015) study the problem proposed by Dai *et al.* (2015), but consider only one period. They propose an arc-flow model of the problem, and reformulate it as a path-flow model by using Dantzig-Wolfe decomposition (Dantzig and Wolfe (1960)). The re-formulated problem is solved as a mixed integer program, where a subset of possible routes and schedules are generated heuristically.

The papers mentioned above only consider one O&M base and one wind farm. However, some wind farm operators or O&M service providers may serve multiple offshore wind farms in the same area, and may use multiple ports as the base for conducting O&M. This may be increasingly relevant to consider as more clusters of neighbouring wind farms are being developed, allowing more resources to be shared between them. To the best of our knowledge, there is no paper in the literature dealing with maintenance routing and scheduling problem for multiple wind farms and O&M bases. Therefore, in this paper, we propose a new mathematical model and a solution method to tackle such a problem. In addition, we take into account the number of each skill type of technicians available at each O&M base, the availability of the vessels and spare parts, and the ability of a vessel to transfer spare parts.

2.2 Review on maintenance scheduling problems for offshore wind farms

This subsection presents an overview of related maintenance scheduling problems from the wind energy sector. We begin by giving an overview of predetermined preventive maintenance scheduling, and then presenting papers studying corrective and condition-based maintenance scheduling.

Predetermined preventive maintenance

A mathematical model for determining the best time for maintenance operations taking into account the performance of the wind turbine and the availability of the resources was built by Kovács *et al.* (2011). Parikh (2012) proposed a mathematical model to optimise the maintenance cost of wind farms by scheduling preventive maintenance and replacement of critical components. An optimal preventive maintenance scheduling model for minimising the overall downtime energy losses was studied by Zhang *et al.* (2012). The model takes into account weather conditions, crews, transportation, and tooling infrastructure. A model for the preventive maintenance scheduling of power plants including wind farms was proposed by Perez-Canton and Rubio-Romero (2013), which aims to maximise the system reliability.

Corrective and condition-based maintenance

There are several papers that study scheduling of corrective and condition based maintenance operations. An opportunistic maintenance optimization model taking into account wind forecasts and corrective maintenance activities was studied by Besnard *et al.* (2009). Besnard *et al.* (2011) extended their previous work by formulating a stochastic optimisation problem that considers uncertainty in weather conditions. Byon *et al.* (2011) used the discrete event system specification (DEVS) to build a simulation model for wind farm operations and maintenance where two different maintenance strategies, namely scheduled maintenance and condition-based maintenance are applied. The results showed that condition-based maintenance yields more wind power generation by reducing wind turbine failure rates. Van Horenbeek *et al.* (2012) investigated prognostic maintenance scheduling for offshore wind turbines where the added value of a prognostic maintenance policy was quantified. Camci (2015) studied a methodology to schedule the maintenance of geographically distributed assets using their prognostic information which can be applied for maintenance scheduling at offshore wind farm.

The previous works cited on optimal scheduling of maintenance in this subsection have not considered how to access the turbines that need to be maintained. This is taken into account in the routing and scheduling problem presented in this paper.

2.3 Related routing problems

The routing and scheduling problem of maintenance vessels at offshore wind farms can be categorized as a vehicle routing problem with pick-up and delivery (VRPDP) according to the classification scheme provided in the survey conducted by Berbeglia *et al.* (2007). As the survey shows, the most successful exact solution approach for this type of pickup and delivery problems is based on a Dantzig-Wolfe decomposition of the original mathematical formulation (Dantzig and Wolfe, 1960). When applying the Dantzig-Wolfe decomposition method to a vehicle routing problem (VRP), one obtains a master problem that consists of selecting one route for each vehicle, such that all customers are serviced exactly once. The corresponding sub-problems determine the set of feasible routes and their corresponding costs. For problems where the number of feasible routes is relatively small, all routes can be generated *a priori*, and the master problem can then be solved as an integer program. Otherwise new routes can be generated dynamically in each node of the Branch-and-Bound

tree, a method known as branch-and-price (Barnhart et al. 1998). This approach has been used successfully to solve different versions of the one-to-one VRPDP by, among others, Dumas *et al.* (1991), Savelsbergh and Sol (1998), Røpke and Cordeau (2009), Brønmo *et al.* (2010) and Baldacci *et al.* (2011).

The routing and scheduling problem of maintenance vessels at offshore wind farms also incorporates elements from an extension of the one-to-one VRPDP known as the Dial-a-Ride Problem (DARP). According to Cordeau and Laporte (2007), DARP problems often include quality of service criteria such as maximum route duration and customer ride times. At offshore wind farms the length of a shift and the width of the weather window for a given vessel limits the maximum route duration, while the requirement of a minimum elapsed time between when the technicians are delivered to a turbine and picked up again are the opposite of customer ride time considerations where a maximum time between pickup and delivery is enforced. Thus, similar to the DARP, it is insufficient to find the optimal route for each vessel that performs maintenance at the offshore wind farm; one must also find the optimal schedule for this route. Recently, Parragh *et al.* (2015) studied a branch-and-price algorithm to solve a generalization of the DARP where each customer could be visited by more than one vehicle, while Gschwind (2015) presented several approaches to the VRPDP where there is a minimum and/or maximum time limit on the time elapsed between visiting the pickup and corresponding delivery node.

Another routing problem related to maintenance at offshore wind farms is the travelling repairman problem (TRP) where the objective of the TRP is to find a Hamiltonian tour on a network made up of a set of failed equipment, starting from and ending at a depot, which minimizes the total waiting time of equipment. Salehipour *et al.* (2011) proposed efficient metaheuristics based on GRASP and variable neighborhood search (VNS) for solving the traveling repairman problem. A VNS algorithm for heterogeneous traveling repairmen problem with time windows was studied by Bjelić *et al.* (2013). Dewilde *et al.* (2013) proposed heuristic techniques for a variant of TRP, namely the traveling repairman problem with profits where the aim of the problem is to maximize the total collected revenue. Related to integration of routing problem with condition-based maintenance known as Travelling Maintainer Problem (TMP), Camci (2014) introduced a mathematical model integrating the output of prognostics in Condition-based Maintenance (CBM) with the Travelling Salesman Problem (TSP). Luo *et al.* (2014) enhanced the multiple traveling repairman problem by considering a limitation on the total distance that a vehicle can travel where branch-and-

price-and-cut is used to address the problem. Bock (2015) studied the complexity status of TRP on a line (Line-TRP) with general processing times at the request locations and deadline restrictions. Unlike the problem presented in this paper, the TRP assumes that the vehicles carrying the repairers wait at each node in the network until the repair is completed. Thus, the TRP does not have a pickup and delivery structure, which is present in our problem.

Common for all the routing problems presented above is the fact that the most successful exact solution methods for solving them are based on decomposing the problem into a master problem assigning routes to the vehicles and one or more sub-problems that create the routes. In fact the overview of new exact solution methods for the capacitated VRP given by Poggi and Uchoa (2014) shows that all recent advances in solution methods are built on a similar separation of the problem into a master problem and sub-problem(s). It is therefore natural to use such decomposition also when solving the routing and scheduling problem of maintenance vessels at offshore wind farms.

3. Overview of the proposed maintenance routing and scheduling model

The main factors considered in the model are depicted in Figure 1. Each wind farm consists of a set of turbines that need to be maintained in the next 3-7 day planning horizon based on the recommended period of the turbines that need to be serviced. An O&M base is usually located at the harbour/port near the wind farm, and contains resources such as vessels, technicians, and warehouses. An O&M base may have more than one vessel with different specifications. The types of technicians considered in this paper are classified as electrical, mechanical, or electromechanical, and each maintenance task requires technicians with different skills.

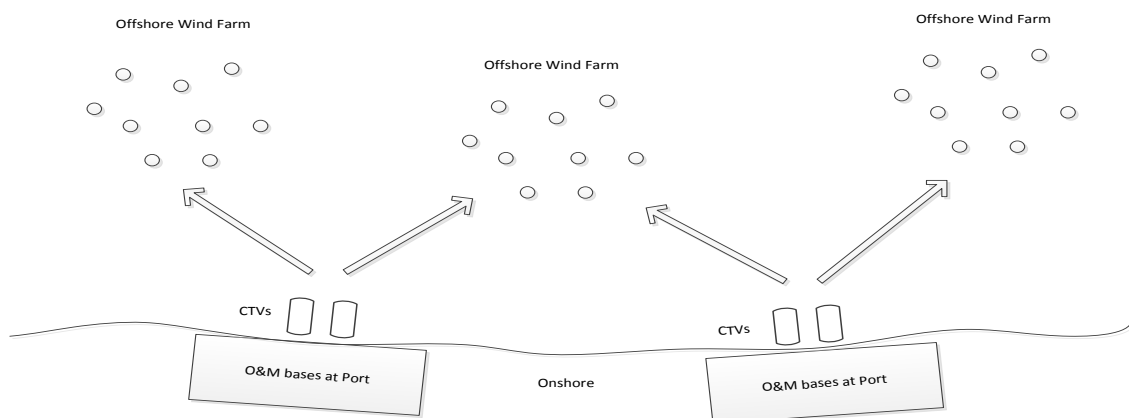


Figure 1. Illustration of the maintenance routing and scheduling framework

This section describes the proposed model for routing and scheduling of maintenance vessels and technicians in offshore wind farms. Figure 2 shows the maintenance routing and scheduling model that we propose and the different inputs, constraints and outputs. The main inputs required by the model include the set of turbines that need to be maintained during the planning horizon. Each turbine has the following parameters: the maintenance/repair time, the number of technicians required (for each type of technician e.g. electrician, mechanical, and electromechanical), the availability and the weight of spare parts needed, the recommended (last) period of maintenance, and a penalty cost (if the turbine is maintained after the recommended period).

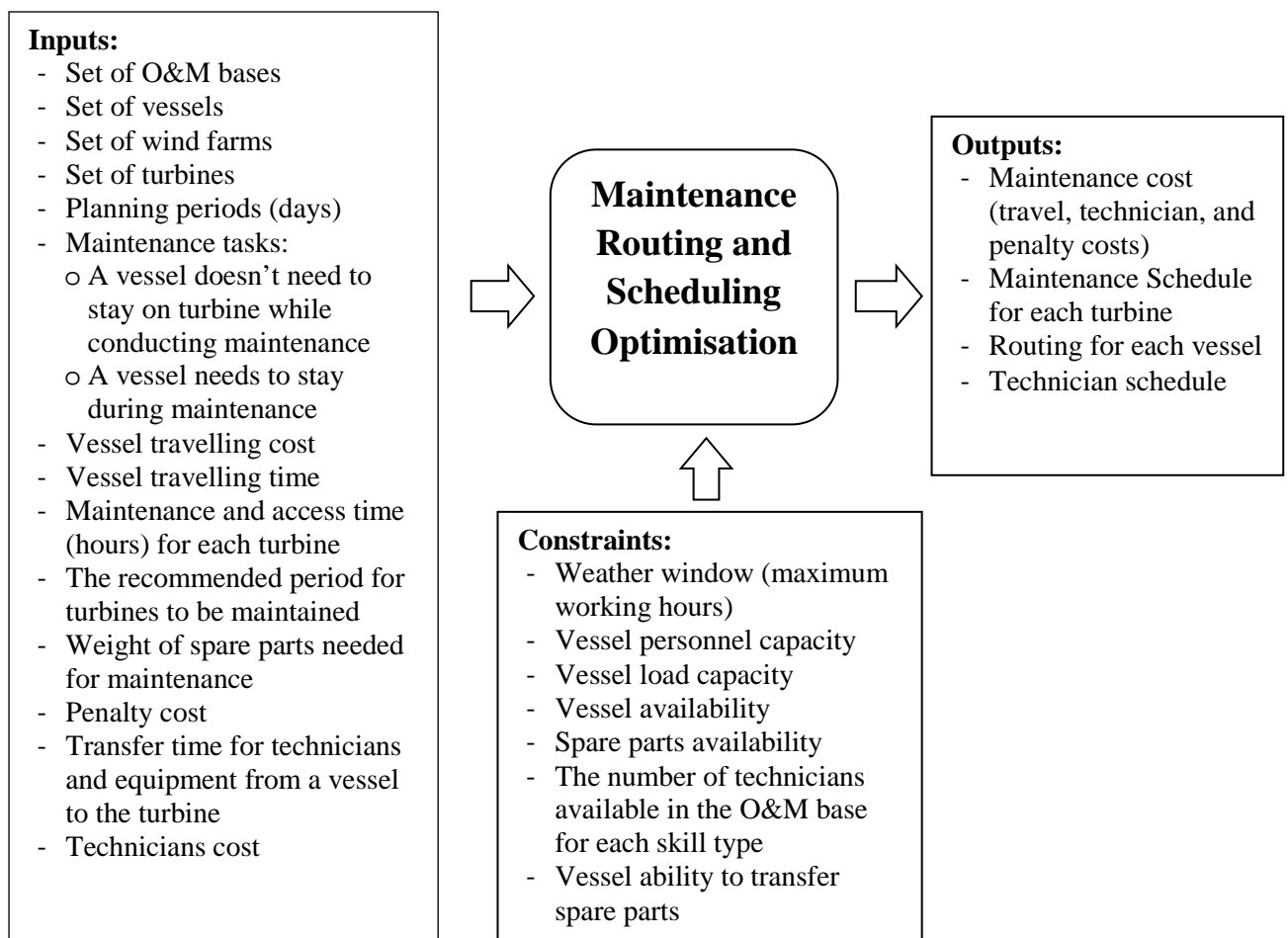


Figure 2. The proposed model

The penalty cost represents the incentives of the operator to perform the maintenance tasks and reflects the priority of visiting the different turbines. For periodic inspections and predetermined preventive maintenance, the recommended period would be based on the recommended inspection/maintenance interval (typically given by the turbine manufacturer). For condition-based maintenance, the recommended period of maintenance and the penalty

cost could be set to reflect the estimated condition of the turbine and hence the risks associated with its deterioration. It could in that case also represent the revenue lost when the turbine has to be set (derated) to operate at reduced performance. The determination of the penalty costs depends on the preferences and perspective of the user and whether he or she represents a wind farm owner/operator or an O&M service provider. In general, the electricity price of wind energy is also a key factor in determining the penalty cost. As this is a complex problem, further research is worth conducting to determine the penalty cost by considering e.g. models for wind power scheduling available in the literature such as García-González *et al.* (2008) and Zhang *et al.* (2013).

We also need the information on whether the vessels are required to be present during the maintenance operation on a turbine. In case that the maintenance operation does not need a vessel to be present, the vessel delivers (drop off) the technicians and picks them up on the same day after the maintenance activity has been completed. Other information required for the model are the travel cost/time for each vessel (based on distance, fuel cost and the speed of the vessel), the transfer time for technicians (and equipment) from a vessel to the turbine, and technician cost per period/day. Depending on the form of employment for the technicians, the main contribution to the technician cost for the operator could be a fixed salary component. In this case, the technician cost per period/day should be understood as an offshore bonus for the days the technicians are actually performing maintenance work at the wind farm. In this study, a turbine is only maintained once during the planning horizon. However, if more maintenance tasks are grouped for turbine visits within the planning horizon than there is time for any single period, one could easily specify multiple visits to different virtual turbines representing the same physical turbine.

There are several constraints that are taken into account by the model including the weather window (maximum working hours per period) for each vessel, vessel personnel capacity, vessel load capacity, vessel availability, spare parts availability, the number of each skill type of technicians available in the O&M base and vessel ability to transfer spare parts. The weather window for each period is different for each vessel depending on its specification or accessibility level (the weather conditions are such that technicians can safely access an offshore wind turbine from the vessel). The duration for a vessel leaving from the harbour and until its return must be less than its weather window. In this study, a vessel will not be able to visit more than one wind farm in one period/day. However, in one period it can visit/service more than one turbine in a wind farm within the weather window. We also

assume that a single weather window per day for each vessel is used. An enhancement of the model can be done to consider some vessels that have multiple (non-continuous) weather windows per day. The weather window could also to a certain degree reflect the best time (period) to do maintenance since low wind speeds and hence low revenue losses due to maintenance activities are partially correlated with good accessibility to the turbines. These revenue losses are therefore not optimized explicitly in the model. In this study the main objective is to find the optimal set of routes and schedules for the vessels and technicians to perform the maintenance activities at the offshore wind farms.

4. Maintenance routing and scheduling optimisation model

The optimisation model proposed consists of a master problem and one sub-problem for each vessel. The master problem for a maintenance routing and scheduling model for offshore wind farms is presented in this section whereas the sub-problem is given in the next sub-section. The following notations are used to describe the sets and parameters of the proposed maintenance routing and scheduling model.

Sets

- B : set of O&M bases with b as index
- V : set of vessels with v as index
- V_b : set of vessels at O&M base b ($V_b \subset V$)
- F : set of wind farms with f as index
- J : set of turbines that need to be maintained with j as index
- J_f : set of turbines at wind farm f ($J_f \subset J$)
- J_v : set of turbines that require the vessel to be present during maintenance ($J_v \subset J$)
- T : set of periods with t as index
- P : set of technician types (electrical, mechanical, and electromechanical) with p as index

Parameters

- ∂_j : the latest period/day to maintain turbine j (without penalty).
- $c_{vii'}$: travel cost of vessel v to travel from node i to i' ($i, i' \in J \cup B$).
- $\tau_{vii'}$: travel time of vessel v to travel from node i to i' ($i, i' \in J \cup B$).
- \hat{t}_j : required time to perform maintenance task on turbine j .
- $\tilde{\tau}_v$: transfer time for technicians and equipment from vessel v to a turbine.

- w_j : weight of spare parts and equipment needed by turbine j .
 ρ_{pj} : number of technicians classified as type p required to maintain turbine j .
 $\widehat{\rho}_{bpt}$: number of technicians (type p) available in O&M b at period t .
 \widehat{c}_p : technician (type p) cost per period/day.
 λ_{bf} : = 1, if O&M base b serves wind farm f ,
 = 0, otherwise
 \widetilde{c}_j : penalty cost per period if turbine j is maintained after period δ_j^t
 $\widetilde{\rho}_v$: maximum number of personnel on board vessel v (technician capacity).
 \widehat{w}_v : total weight of spare parts or equipment that can be transported by vessel v .
 a_{vt} : = 1 if vessel v is available at period t ,
 = 0 otherwise.
 \widehat{a}_{vj} : = 1 if vessel v is able to transfer parts/components needed by turbine j ,
 = 0 otherwise.
 \widetilde{a}_{jt} : = 1 if spare parts required by turbine j are available at period t ,
 = 0 otherwise.
 \widehat{c}_v : average fuel cost for vessel v to travel for an hour.
 ψ_{vft} : weather window for vessel v in period t at wind farm f .

Figure 3 shows the proposed methodology for solving the maintenance routing and scheduling problem in offshore wind farms. A new set of all feasible routes for vessel v at period t (R_{vt}) is introduced. In the first step, all feasible routes for each vessel and each period are generated. In this study, a feasible route may consist of 1 to η turbines where η denotes the maximum number of turbines that can be serviced/visited by a vessel in one period/day. A Mixed Integer Linear Program (MILP) is proposed to find the optimal routing for a set of turbines (more than 1) which is given in subsection 4.1. Once the optimal routing has been obtained, the total cost which includes technician, travel, and penalty costs for this route is calculated. In the second step, an Integer Linear Program (ILP) is proposed to select the best route configuration from all feasible routes that have been determined in the previous step.

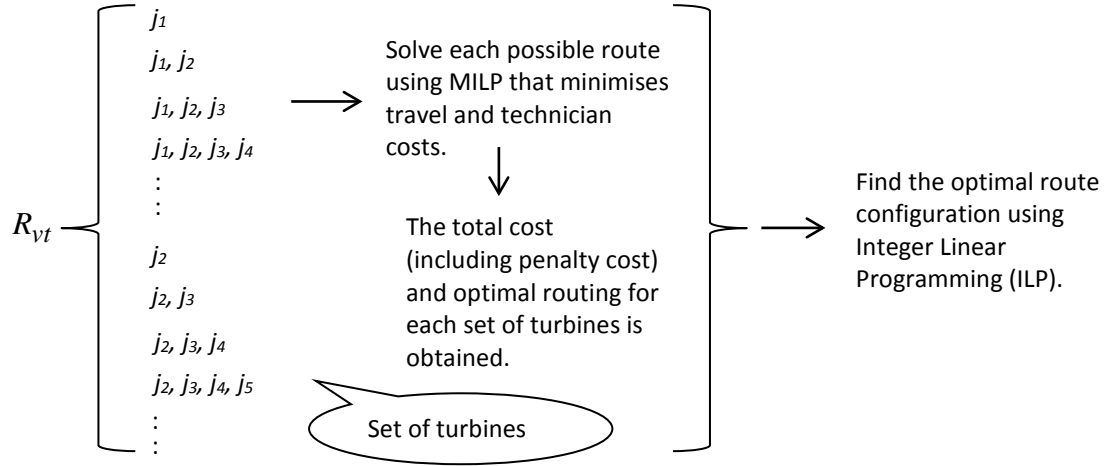


Figure 3. The proposed methodology for solving the routing and scheduling model

The set of feasible routes (R_{vt}) consists of several parameters as follows:

S_{vtr} : ordered list of nodes (turbines) included in route r of vessel v in period t .

c_{vtr}^r : total cost for route r of vessel v in period t .

θ_{vtrj} : = 1 if turbine j is in route r of vessel v in period t ,
= 0 otherwise.

q_{vtrp} : number of technicians (type p) required in route r of vessel v in period t .

An Integer Linear Programming (ILP) model is proposed to obtain the best route configuration from all feasible routes.

The decision variable is as follows:

X_{vtr} = 1 if route r of vessel v in period t is used in the solution,
= 0 otherwise.

The following objective function is used to select the optimal route.

$$\text{Minimise } Z_c = \sum_{t \in T} \sum_{v \in V} \sum_{r \in R_{vt}} (X_{vtr} \cdot c_{vtr}^r) \quad (1)$$

The objective is to find the optimal maintenance schedule and routing for vessels that minimises the maintenance costs including travel, technician, and penalty costs of the routes that are selected in the optimal solution.

Subject to the following constraints:

$$\sum_{r \in R_{vt}} X_{vtr} \leq 1, \forall v \in V, t \in T \quad (2)$$

$$\sum_v \sum_t \sum_{r \in R_{vt}} (X_{vtr} \cdot \theta_{vtrj}) = 1, \forall j \in J \quad (3)$$

$$\sum_{v \in V_b} \sum_{r \in R_{vt}} (X_{vtr} \cdot q_{vtrp}) \leq \hat{\rho}_{bpt}, \forall p \in P, b \in B, t \in T \quad (4)$$

$$X_{vtr} = \{0,1\} \quad (5)$$

Constraints (2) ensure that a vessel cannot use more than one route at a period. Constraints (3) guarantee that a turbine is only maintained/visited once in the planning horizon. Constraints (4) state that the total number of technicians (for each type of technicians) required by vessels in the solution for each period is not greater than the ones available at the O&M base. In sign restrictions (5), all X -variables are set as binary.

4.1 The mixed integer linear program (MILP) for the routing problem

This subsection presents the sub-problem for a given vessel formulated as a mixed integer linear program. It is used to find the optimal route for a vessel (vessel v based at O&M base b) to visit/service a set of turbines in a period (period t). Let n denote the number of turbines that might be visited and \hat{J} the set of nodes consisting of O&M base b and turbines (j_1, \dots, j_n) where $\hat{J} = \{b, j_1, \dots, j_n\}$ or $\hat{J} = \{0, 1, \dots, n\}$ for simplification. The model is an extension of the model proposed by Dai *et al.* (2015) where the cost and the availability of different types of technicians are considered. The following notation describes the sets and parameters used in the MILP model.

J^- : set of delivery/drop nodes, $J^- = \{1, 2, \dots, n\}$.

J^+ : set of pick up nodes, $J^+ = \{n+1, n+2, \dots, 2n\}$.

$J^* = J^- \cup J^+ \cup \{0, 2n+1\}$: Nodes 0 and $2n+1$ represent start and end nodes respectively (O&M base b).

$J^v \subseteq J^-$: the set of turbines that need the vessel to be present during the maintenance operations.

The MILP model aims to find the optimal route that minimises the cost (travel and technicians costs). Indices t, b, f, v , and r are known/fixed; therefore, in this MILP model, those indices are removed. There are three decision variables for this problem as follows:

$Y_{ii'}$: = 1 if vessel v travel from node i to i' , = 0 otherwise ($i, i' \in J^*$).

\hat{T}_i : the time when vessel v visit (drop/pick) node i ($i \in J^*$).

Q_{pi} : number of technicians (type p) on vessel v after leaving node i

The objective function is defined as follows:

$$\min Z = c^{qr} + c^{tr} \quad (6)$$

where c^{qr} and c^{tr} are the technicians and travel costs respectively for route r of vessel v in period t which is formulated as follows:

$$c^{qr} = \sum_{p \in P} (q_p \cdot \hat{c}_p) \quad (7)$$

$$c^{tr} = \sum_{i \in J^*} \sum_{i' \in J^*} (c_{ii'} \cdot y_{ii'}) \quad (8)$$

q_p is the number of technicians (for each type p) required by vessel v on period t with $q_p = Q_{p0}$. In other words, q_p is the number of technicians leaving from O&M base b .

The constraints are given as follows:

$$\sum_{i' \in J^*} Y_{ii'} = 1, \forall i \in J^* \quad (9)$$

$$\sum_{i \in J^-} Y_{0i} = 1 \quad (10)$$

$$\sum_{i \in J^+} Y_{i(2n+1)} = 1 \quad (11)$$

$$\sum_{i' \in J^*} Y_{ii'} = \sum_{i' \in J^*} Y_{i'i}, \forall i \in J^* \quad (12)$$

$$\sum_{i' \in J^*} Y_{ii'} = \sum_{i' \in J^*} Y_{(n+i)i'}, \forall i \in J^- \quad (13)$$

$$Y_{i(n+i)} = 1, \forall i \in J^v \quad (14)$$

$$\hat{T}_{n+i} - \hat{T}_i \geq \hat{t}_i + \tilde{\tau}, \forall i \in J^- \quad (15)$$

$$\hat{T}_{2n+1} \leq \psi \quad (16)$$

$$\hat{T}_0 = 0 \quad (17)$$

$$0 \leq \sum_{p \in P} Q_{p,i} \leq \tilde{\rho}, \forall i \in J^* \quad (18)$$

$$Y_{ii'}(\hat{T}_i + \tau_{ii'} + \tilde{\tau} - \hat{T}_{i'}) \leq 0, \forall i, i' \in J^*, i' \neq i+n \quad (19)$$

$$Y_{ii'}(Q_{pi} - \rho_{pi'} - Q_{pi'}) = 0, \forall p \in P, i \in J^-, i' \in J^* \quad (20)$$

$$Y_{ii'}(Q_{pi} + \rho_{pi'} - Q_{pi'}) = 0, \forall p \in P, i \in J^+, i' \in J^* \quad (21)$$

$$q_p = \max_{i \in J^*} \{Q_{pi}\} = Q_{p0}, \forall p \in P \quad (22)$$

$$Q_{pi} \leq \hat{\rho}_p, \forall p \in P, i \in J^* \quad (23)$$

The explanation of the constraints is as follows:

- (9) Ensure that each turbine is visited only once for delivery and once for pick up.
- (10) and (11) Ensure that the vessel leaves and returns the harbour only once.
- (12) Ensure flow conservation at each node.
- (13) Guarantee that both delivery and pick up at a turbine are done.
- (14) Ensure that the vessel travels directly from the delivery node to the pickup node (which is the same location) if the vessel needs to be present during the maintenance operation.
- (15) Ensure that the time between the delivery and the pickup is greater than the time required to perform maintenance at the turbine.
- (16) Guarantee the working time of the service vessels to be less than time window (maximum working hours).
- (17) Makes sure that the time when the vessel leaves the O&M base is 0.
- (18) Ensure that the number of technicians onboard does not exceed the vessel capacity.
- (19) Maintain the travel time compatibility of the vessel.
- (20) and (21) track the number of technicians (for each type) onboard the vessel when arriving at each node.
- (22) calculate the number of technicians (for each type) required for route r of vessel v in period t (which is the number of technicians in the vessel when leaving the harbour).
- (23) Guarantee that the number of technicians (for each type) required is less than the number of technicians available.

Constraints (19) – (21) make the proposed model nonlinear. Here, we transform the model into a linear model by incorporating big- M value so the model can be solved using an exact method. The introduction of new variables and constraints are needed to linearise the problem. Once the optimal route is obtained, we can calculate the maintenance cost (c^r) for

route r of vessel v in period t by including the penalty cost (c^{lr}). c^r can be written as follows:

$$c^r = c^{qr} + c^{tr} + c^{lr} \quad (24)$$

with c^{lr} is defined as follows:

$$c^{lr} = \sum_j (\theta_j \cdot \max\{0, (t - \partial_j)\} \cdot \tilde{c}_j) \quad (25)$$

4.2 The procedure for generating feasible routes

An algorithm for generating all feasible routes is presented in this subsection. Figure 4 provides the procedure for generating all feasible routes for each vessel in each period. In the procedure, in one period/day a vessel only visits one or more turbines within a wind farm as the distance between two wind farms is usually relatively far. The maximum number of turbines visited by a vessel in a day is also limited to η where $\eta \leq |J_f|$. However, to guarantee the optimality, η must be set to $|J_f|$.

The algorithm in Figure 4 seeks all possible routes for vessel v at period t . The process of the algorithm uses a top-bottom procedure. The first level consists of 1 turbine ($n = 1$) whereas the last level involves η turbines. It starts from the first level and then descends to the next level where the higher level is a feasible route. In other words, it starts solving the routing problem (and checks its feasibility) for 1 turbine, and if it is a feasible route then the algorithm adds another turbine to be maintained. This process is repeated until all possible combinations of turbines are explored.

For $n = 1$, it is easy to obtain the optimal routing as there is only one possible route which is $b-j_1-j_1-b$. Here, the vessel leaves from O&M base b and goes to turbine j_1 to drop/deliver the technicians, and then the vessel waits at this turbine until the maintenance task is completed. After the vessel has picked up the technicians, it goes back to O&M base b . However, this route might be infeasible if some constraints are not met such as load/technician capacity of the vessel and the weather window. For $n \geq 2$, the problem is harder to solve as the number of possible routes increases drastically. Therefore, the MILP procedure is proposed to solve the routing problem as shown in Figure 5.

Procedure Generating_Feasible_Routes ()

For each period t in T do the following:

For each O&M base b in B do the following:

For each wind farm f in F do the following:

If $\lambda_{bf} = 0$ then continue (skip the following under looping f).

For each vessel v in V_b do the following:

If $a_{vt} = 0$ then continue (skip the following under looping v).

Set $r = 0$ and determine the value of η ($\eta = |J_f|$ for optimality).

For each turbine j_1 in J_f do the following:

If $\hat{a}_{v(j_1)} = 0$ or $\tilde{a}_{(j_1)t} = 0$ then continue (skip the following under looping j_1).

Set $\hat{J} = \{b, j_1\}$ and check feasibility of this set with predefined constraints.

If not feasible then continue (skip the following under looping j_1).

Update S_{vtr} , c_{vtr}^r , θ_{vtrj} , and q_{vtrp} .

Set $r = r + 1$.

For $j_2 = (j_1 + 1)$ to $|J_f|$ do the following:

If $\hat{a}_{v(j_2)} = 0$ or $\tilde{a}_{(j_2)t} = 0$ then continue (skip the following under looping j_2).

Set $\hat{J} = \{b, j_1, j_2\}$

Use Procedure “Solving_MILP” given in Figure 5 to solve the problem.

If not feasible then continue (skip the following under looping j_2).

For $j_3 = (j_2 + 1)$ to $|J_f|$ do the following:

If $\hat{a}_{v(j_3)} = 0$ or $\tilde{a}_{(j_3)t} = 0$ then continue (skip the following under looping j_3).

Set $\hat{J} = \{b, j_1, j_2, j_3\}$

Use Procedure “Solving_MILP” given in Figure 5 to solve the problem.

If not feasible then continue (skip the following under looping j_3).

:

For $j_\eta = (j_{\eta-1} + 1)$ to $|J_f|$ do the following:

:

End for j_η

:

End for j_3

End for j_2

End for j_1

End for v

End for f

End for b

End for t

Figure 4. The algorithm for generating all feasible routes

Procedure Solving MILP ($v, t, \hat{J}, r, S_{vtr}, c_{vtr}^r, \theta_{vtrj}, q_{vtrp}$)

- Set $J^- = \hat{J} - \{b\}$ and $w = \sum_{j \in J^-} w_j$.
- If $\hat{w}_v < w$ then return infeasible solution and exit
- Set $\gamma = \text{true}$ if \hat{J} has been solved using MILP in the previous period, say period \tilde{t} (this can be done using a good data structure).
- If $\gamma = \text{true}$ then
 - If \hat{J} provides a feasible route at period \tilde{t} and $\psi_{vft} = \psi_{v\tilde{t}}$ then
 - Copy the solution given by MILP for \hat{J} at period \tilde{t} into period t .
 - Copy the travel cost
 - Calculate the penalty cost for period \tilde{t} (It could be different from the one at period t)
 - Return feasible solution and exit
 - End If
 - If \hat{J} provides an infeasible route at period \tilde{t} and $\psi_{vft} \leq \psi_{v\tilde{t}}$ then
 - Return infeasible solution and exit
 - End If
- End if
- Solve the routing problem for \hat{J} using MILP that we propose (equation 6-23).
- If the feasible solution is obtained then
 - Update S_{vtr} , θ_{vtrj} , and q_{vtrp}
 - Calculate c_{vtr}^r and set $r = r+1$
 - Return feasible solution and exit
- Else
 - Return infeasible solution and exit
- End If

Figure 5. The procedure for solving the routing problem using MILP

The procedure in Figure 5 first ensures that the total weight of spare parts needed to service the set of turbines is less than the load capacity of the vessel. The procedure also checks whether the problem with the same set of turbines has been solved for the previous period. This step aims to decrease the computing time as there is no advantage in solving the same problem (with the same constraints) more than once. This can be done by constructing a good data structure to store the computational results. The next section presents the computational experiments of the proposed method on existing dataset available in the literature and newly generated dataset.

5. Computational analysis

We carried out extensive experiments to examine the performance of the proposed solution approaches. The code was written in C++ .Net 2012 and used the IBM ILOG CPLEX version 12.6 Concert Library. The tests were run on a PC with an Intel Core i5 CPU @ 3.20GHz processor, 8.00 GB of RAM and under Windows 7. In the computational experiments, we use an existing dataset from the literature. We also generate a new more challenging dataset where multiple offshore wind farms and O&M bases, and different types of technicians available at O&M bases are considered with a longer planning horizon.

5.1 Experiments on the existing dataset with single O&M base and wind farm

The proposed method was examined with the dataset available in the literature (Dai *et al.*, 2015). Here, we tested our method on the dataset called Dataset C consisting of 10 instances. This dataset is very hard to solve by the model proposed by Dai *et al.* (2015). The dataset only considers one wind farm and one O&M base. It consists of 8 turbines to be maintained for 3 periods (days) and it involves 2 vessels with different specifications. The experimental results obtained with the proposed method on the existing dataset have been compared with the ones obtained by Dai *et al.* (2015), referred to as DAI.

In DAI, the objective function of the model only considers the travel and penalty costs. To compare with their results, we set the technician cost $\hat{c}_p = 0$. Moreover, DAI does not take into account the number of technicians available in the O&M base. Here, we set $\hat{\rho}_{bpt} = M$ where M is a big number. In other words, the technicians required for maintaining the turbines are always available in the O&M base.

In this study, we vary the maximum number of turbines visited by a vessel $\eta = 3, 4, 5$ and 8. The use of $\eta = |J_f| = 8$ will guarantee to find the optimal solution as all possible routes are considered. When the value of η decreases, the objective function value increases as the number of trips required increases along with the penalty cost. However, a bigger value of η requires a longer computational time to solve the problem. Table 1 presents the computational results on the existing dataset where it compares the performance of DAI and the proposed method. The optimal objective function value (Z^*) is obtained from the

proposed method with $\eta = |J_f| = 8$. The percentage deviation ($Dev(\%)$) is calculated as follows:

$$Dev(\%) = \frac{Z_k - Z^*}{Z^*} \times 100$$

where Z_k refers to the solution cost obtained by method ‘ k ’. CPU time is measured in seconds where boldface values in the table refer to the optimal solutions. The table also provides the average deviation for each method, the number of instances where the optimal solution is found, and the average CPU time.

In Table 1, the solutions obtained from the proposed method with $\eta = 8$ are the optimal solutions so we can compare the quality of the solution attained by other approaches. In general, regarding the computational time, the proposed method provided a significant improvement as the method runs very fast compared to DAI to produce the optimal solutions. Furthermore, the table shows that the proposed method improves the solution quality given that the value of η is increased. For example, the average deviation ($Dev(\%)$) is decreased from 0.0621% to 0% when the value of η is increased from 3 to 8 respectively. However, the average computing time increases drastically from 2.45 seconds ($\eta = 3$) to 79.11 seconds ($\eta = 8$).

Table 1. Computational results on Dataset C

Ins- tance	Z^* (Optimal Z)	DAI		Proposed Method							
		Dev (%)	CPU time (s)	$\eta = 3$		$\eta = 4$		$\eta = 5$		$\eta = 8$	
				Dev (%)	CPU time (s)	Dev (%)	CPU time (s)	Dev (%)	CPU time (s)	Dev (%)	CPU time (s)
#1	4252.55	0.0000	3,130	0.0000	2.36	0.0000	6.05	0.0000	8.31	0.0000	18.98
#2	4664.47	0.6307	10,000	0.0959	2.69	0.0110	9.72	0.0000	23.88	0.0000	26.21
#3	4161.47	0.0000	10,000	0.0608	2.53	0.0000	9.13	0.0000	28.28	0.0000	87.62
#4	5101.95	0.0278	10,000	0.0302	2.21	0.0000	6.49	0.0000	10.07	0.0000	11.60
#5	3984.52	0.3966	10,000	0.1472	2.58	0.0000	8.72	0.0000	26.20	0.0000	75.24
#6	6313.97	0.0411	10,000	0.0396	2.94	0.0000	8.83	0.0000	20.24	0.0000	40.17
#7	5690.93	0.0000	355	0.0000	1.62	0.0000	4.08	0.0000	4.52	0.0000	5.92
#8	4576.5	0.0023	10,000	0.0037	2.14	0.0000	4.80	0.0000	11.09	0.0000	30.35
#9	3428.72	0.2760	10,000	0.2438	3.09	0.1083	11.85	0.0000	43.13	0.0000	438.6 4
#10	5084.91	0.0000	9,874	0.0000	2.29	0.0000	7.19	0.0000	13.74	0.0000	56.38
Avg Dev		0.1375		0.0621		0.0119		0.0000		0.0000	
# Optimal		4		3		8		10		10	
Avg Cpu			8,336		2.45		7.69		18.95		79.11

The proposed method with $\eta = 5$ also produces the optimal solutions for all instances. It means that in the optimal solution, there is no vessel visiting more than 5 turbines in one period/day. The proposed method with $\eta = 5$ runs approximately five times faster than the one with $\eta = 8$ as the number of possible combinations of the set of turbines solved by the proposed MILP is relatively smaller. For relatively small instances, the computational time required to obtain the optimal solution is not significant; although when it comes to large instances, the computational time increases in order to obtain optimal solution.

Table 2 presents the breakdown of the cost for the solutions of all instances on the existing dataset obtained by the proposed method. There are two costs considered in the problem on the existing data namely the travel (fuel) cost and the penalty cost. In Table 2, the average travel and penalty costs and the percentage of each cost type from the total cost (prop) are also given. The table reveals that to get a good (optimal) solution, the method tends to avoid the penalty cost. Penalty cost only occurs on instances 6 and 7 for all the different values of η used in the proposed method. It could be occurred because in instances 6 and 7, many of turbines need to be maintained on the earlier period/day. On average, the fuel cost contributes more or less 94% to the total cost with 6% for the penalty cost.

Table 2. Breakdown of cost for the solutions attained by the method on Dataset C

Ins- tance	$\eta = 3$			$\eta = 4$			$\eta = 5$ and $\eta = 8$		
	Fuel Cost	Penalty Cost	Total Cost	Fuel Cost	Penalty Cost	Total Cost	Fuel Cost	Penalty Cost	Total Cost
#1	4,252.55	0.00	4,252.55	4,252.55	0.00	4,252.55	4,252.55	0.00	4,252.55
#2	5,111.69	0.00	5,111.69	4,715.82	0.00	4,715.82	4,664.47	0.00	4,664.47
#3	4,414.56	0.00	4,414.56	4,161.47	0.00	4,161.47	4,161.47	0.00	4,161.47
#4	5,256.07	0.00	5,256.07	5,101.95	0.00	5,101.95	5,101.95	0.00	5,101.95
#5	4,571.03	0.00	4,571.03	3,984.52	0.00	3,984.52	3,984.52	0.00	3,984.52
#6	4,564.20	2,000.00	6,564.20	4,613.97	1,700.00	6,313.97	4,613.97	1,700.00	6,313.97
#7	4,590.93	1,100.00	5,690.93	4,590.93	1,100.00	5,690.93	4,590.93	1,100.00	5,690.93
#8	4,593.30	0.00	4,593.30	4,576.50	0.00	4,576.50	4,576.50	0.00	4,576.50
#9	4,264.60	0.00	4,264.60	3,800.02	0.00	3,800.02	3,428.72	0.00	3,428.72
#10	5,084.91	0.00	5,084.91	5,084.91	0.00	5,084.91	5,084.91	0.00	5,084.91
Avg	4,670.39	310.00	4,980.39	4,488.26	280.00	4,768.26	4,446.00	280.00	4,726.00
Prop.	93.78	6.22		94.13	5.87		94.08	5.92	

5.2 Experiments on new dataset with multiple O&M bases and wind farms

This subsection presents the computational results on the dataset that we have randomly generated. The new dataset generated represents the maintenance problem illustrated in

Figure 1 which is constructed to illustrate the functionalities of the optimisation model. However, we do not claim that the scenario and the values of the input parameters represent accurately the O&M of typical, current offshore wind farms. For the new dataset, we would like to solve the maintenance routing and scheduling problems where two O&M bases (OM1 and OM2) and three wind farms are considered. Each O&M base has two vessels with different specifications and each O&M base is only able to serve two wind farms. The number of technicians available for each technician type in O&M base and the technician cost are also taken into account. In this experiment, there are three types of technician namely mechanical, electrical, and electromechanical.

We construct two types of datasets namely Dataset G1 and Dataset G2 where each dataset consists of 10 instances. The planning horizon is set to 3 and 7 periods/days in Dataset G1 and Dataset G2 respectively. For each instance, the number of turbines that need to be maintained in each wind farm is 8 turbines and 12 turbines for Dataset G1 and Dataset G2 respectively. It means that for each instance, Dataset G1 involves 24 turbines whereas Dataset G2 comprises 36 turbines. The problem with the new generated dataset is more difficult to solve than the existing dataset from DAI as the size of the new problem is much larger. However, the parameter values of the new dataset are more or less similar to the ones of DAI.

Table 3 presents the specification of the vessels used in the newly generated data. The data provides the O&M base for the vessel, the load capacity (\widehat{w}_v), the personnel capacity ($\widetilde{\rho}_v$), and the fuel cost per hour (\widehat{c}_v). It is assumed that the vessels are always available on the O&M base ($a_{vt} = 1$) and all vessels are able to transport the spare parts required for maintaining the turbines ($\widehat{a}_{vj} = 1$). In case that $a_{vt} = 0$ or $\widehat{a}_{vj} = 0$, the complexity of the problem decreases.

Table 3. Specification of the vessels used in the new generated data

Vessel	O&M base	Load Capacity (tonnes)	Personnel capacity	Fuel Cost/hour (Euro)
V1	OM1	1.5	12	225
V2	OM1	26	12	300
V3	OM2	2	12	250
V4	OM2	15	12	280

Tables 4 and 5 present the information required in Dataset G1. The weather window (ψ_{vft}) of Dataset G1 is given in Table 4 where $\lambda_{11} = 1, \lambda_{12} = 1, \lambda_{22} = 1,$ and $\lambda_{23} = 1$. In other words, the vessels based at OM1 serve wind farms 1 and 2 while the vessels at OM2 maintain wind farms 2 and 3.

Table 4. Weather window for each vessel in Dataset G1

Vessel	Period / Day	Weather Window (hours)		
		Wind Farm 1	Wind Farm 2	Wind Farm 3
V1	1	6	6	-
V1	2	6	6	-
V1	3	12	12	-
V2	1	12	12	-
V2	2	12	12	-
V2	3	12	12	-
V3	1	-	7	7
V3	2	-	7	7
V3	3	-	12	12
V4	1	-	12	12
V4	2	-	12	12
V4	3	-	12	12

Table 5 illustrates an example of the test data for instance #1 in dataset G1, where the maintenance time ($\hat{\tau}_j$), the number of technicians (ρ_{pj}), and the weight of spare parts and equipment (w_j) required to maintain a turbine are given. In the table, technician type 1, 2, and 3 denote electrical, mechanical, and electromechanical where the technician cost is €300, €325, and €350 per day, respectively. Table 5 also provides the recommended/latest period to maintain a turbine (∂_j) along with the penalty cost per day if the maintenance activity is conducted after that period. In the column, vessel needs to be present, the binary value is given where 1 means that the service vessel needs to be present during the maintenance service, and 0 otherwise. We assume that the required transfer time for technicians and equipment from a vessel to a turbine ($\tilde{\tau}_v$) is 15 minutes (0.25 hours). The number of each type technician available in each O&M base ($\hat{\rho}_{bpt}$) is set to 6. We also assume that the spare parts needed to service the turbines are always available ($\tilde{a}_{jt} = 1$).

Table 6 shows the computational results of the proposed method on Dataset G1. We also implement four scenarios where $\eta = 3, 4, 5$ and $\eta = 8$ are used. As $|J_f| = 8$ for $f = 1, 2,$ and

3, the proposed method with $\eta = 8$ will produce the optimal solutions. Table 6 reveals that the proposed method with $\eta = 5$ also obtains the optimal solutions for all instances of Dataset G1. Similarly to the experiments with the existing dataset, on Dataset A, when η is set to 5, the proposed method runs more than three times faster than when $\eta = 8$. The proposed method with $\eta = 3$ and 4 produces a relatively small deviation of 0.0746% and 0.0190% respectively in a relatively small computational time. The proposed method with $\eta = 3$ runs approximately five hundred (500) times faster than the one with $\eta = 8$. Moreover, the use of $\eta = 3$ and 4 are able to obtain the optimal solution for 1 and 2 instances respectively. For instance 1, in the optimal solution there is no vessel visiting more than 3 turbines in one day.

Table 5. Test data for instance #1 in Dataset G1

Turbine	Wind Farm	Maint. time (hours)	Weight of parts (kg)	Penalty cost (euro)	The latest period (in days)	The vessel needs to be present	Number of Technicians		
							Type 1	Type 2	Type 3
T1	WF 1	4	700	1900	3	0	2	0	1
T2	WF 1	3	700	1500	2	0	0	1	1
T3	WF 1	5	300	1600	4	1	3	0	0
T4	WF 1	2	900	1900	1	0	1	0	2
T5	WF 1	4	600	1200	1	0	1	2	2
T6	WF 1	5	900	1600	1	1	3	0	0
T7	WF 1	2	900	1800	4	0	2	2	1
T8	WF 1	2	500	1100	1	0	3	0	1
T9	WF 2	3	400	1300	1	0	0	1	1
T10	WF 2	2	600	1500	3	0	0	1	1
T11	WF 2	4	800	1400	2	1	1	3	0
T12	WF 2	2	700	1900	1	0	0	2	1
T13	WF 2	3	600	1900	2	0	3	2	0
T14	WF 2	4	800	1600	3	0	1	2	0
T15	WF 2	4	400	1500	3	1	3	0	1
T16	WF 2	3	800	1800	2	0	3	1	0
T17	WF 3	3	700	1300	1	0	3	1	0
T18	WF 3	4	800	1500	1	1	3	0	1
T19	WF 3	3	800	1900	4	0	0	2	2
T20	WF 3	2	700	1200	2	0	0	3	0
T21	WF 3	3	600	1600	1	0	1	0	2
T22	WF 3	2	800	1900	4	0	0	1	1
T23	WF 3	2	700	1500	3	0	0	0	2
T24	WF 3	5	300	1900	2	1	3	2	0

Table 7 presents the cost breakdown for the solutions of all instances on Dataset G1 obtained by the proposed method. In Table 7, three types of costs are considered travel (fuel)

cost, crew cost and the penalty cost. The table reveals that on average the crew cost contributes the highest proportion to the total cost with more or less 57%, followed by the fuel cost and penalty cost with 39% and 4% respectively. According to Table 7, the travel, crew, and penalty costs increase when the value of η decreases. For $\eta = 5$ or 8, there are six instances without penalty cost whereas for $\eta = 3$, four instances without such cost. The table also shows that the proportion of penalty cost to the total cost increases when the value of η decreases.

Table 6. Computational results on Dataset G1

Instance	Z^*	$\eta = 3$		$\eta = 4$		$\eta = 5$		$\eta = 8$	
		Dev (%)	CPU time (s)	Dev (%)	CPU time (s)	Dev (%)	CPU time (s)	Dev (%)	CPU time (s)
#1	41,839.74	0.0000	30.04	0.0000	121.22	0.0000	698.00	0.0000	2,444.69
#2	33,425.30	0.0941	24.85	0.0072	90.01	0.0000	255.58	0.0000	542.18
#3	36,501.28	0.0488	25.92	0.0065	89.47	0.0000	179.13	0.0000	317.69
#4	31,316.31	0.0681	32.79	0.0247	142.81	0.0000	566.33	0.0000	2,356.46
#5	31,147.73	0.0746	29.48	0.0008	107.33	0.0000	243.59	0.0000	549.59
#6	36,141.68	0.0368	22.01	0.0000	70.61	0.0000	132.17	0.0000	134.34
#7	29,995.24	0.1108	30.64	0.0463	120.98	0.0000	531.33	0.0000	1,779.76
#8	37,242.48	0.0420	23.04	0.0021	79.53	0.0000	249.62	0.0000	534.70
#9	30,779.64	0.1016	24.65	0.0615	108.41	0.0000	547.94	0.0000	3,465.71
#10	33,030.87	0.1688	23.89	0.0406	86.78	0.0000	275.04	0.0000	674.37
Avg Dev		0.0746		0.0190		0.0000		0.0000	
# Optimal		1		2		10		10	
Avg Cpu			26.73		101.71		367.87		1,279.95

Table 8 presents the experiments results of the proposed method on Dataset G2 where $|J_f| = 12$ for $f = 1, 2$, and 3. This dataset is relatively hard to solve as the number of periods and the total number of turbines considered are relatively large. The proposed method with $\eta = 12$ is guaranteed to obtain the optimal solution. In the experiments on Dataset G2, we only conduct three scenarios where $\eta = 3, 4$, and 5 meaning that the solutions attained cannot guarantee optimality. Therefore, the best known solution (Z') is provided instead of the optimal solution (Z^*). In Table 10, Dev (%) is calculated by using Z' instead of Z^* . Table 8 shows that the solutions obtained by the proposed method with $\eta = 5$ are used as the best known solutions. The proposed method with $\eta = 3$ and 4 produce a relative small deviation of 0.0170% and 0.0033% respectively in a relatively small computational time. The proposed method with $\eta = 3$ runs approximately 20 times faster than the one with $\eta = 5$. Table 9 presents the cost breakdown for the solutions of all instances on Dataset G2.

Table 7. Cost breakdown for the solutions attained by the proposed method on Dataset G1

Instance	$\eta = 3$				$\eta = 4$				$\eta = 5$ and 8			
	Fuel Cost	Crew Cost	Penalty Cost	Total Cost	Fuel Cost	Crew Cost	Penalty Cost	Total Cost	Fuel Cost	Crew Cost	Penalty Cost	Total Cost
#1	14,014.74	22,425.00	5,400.00	41,839.74	14,014.74	22,425.00	5,400.00	41,839.74	14,014.74	22,425.00	5,400.00	41,839.74
#2	15,044.57	21,525.00	0.00	36,569.57	13,164.46	20,500.00	0.00	33,664.46	13,225.30	20,200.00	0.00	33,425.30
#3	15,550.72	20,950.00	1,782.00	38,282.72	14,983.18	19,975.00	1,782.00	36,740.18	14,119.28	20,600.00	1,782.00	36,501.28
#4	15,322.89	18,125.00	0.00	33,447.89	13,914.89	18,175.00	0.00	32,089.89	13,491.31	17,825.00	0.00	31,316.31
#5	13,911.23	18,000.00	1,560.00	33,471.23	12,898.45	18,275.00	0.00	31,173.45	12,872.73	18,275.00	0.00	31,147.73
#6	14,998.26	22,475.00	0.00	37,473.26	13,666.68	22,475.00	0.00	36,141.68	13,666.68	22,475.00	0.00	36,141.68
#7	14,669.43	18,650.00	0.00	33,319.43	14,108.74	17,275.00	0.00	31,383.74	13,320.24	16,675.00	0.00	29,995.24
#8	15,581.11	20,825.00	2,400.00	38,806.11	13,854.10	20,175.00	3,292.00	37,321.10	13,775.48	20,175.00	3,292.00	37,242.48
#9	14,300.09	18,100.00	1,508.00	33,908.09	13,615.74	17,550.00	1,508.00	32,673.74	13,204.64	17,575.00	0.00	30,779.64
#10	14,679.25	20,825.00	3,103.00	38,607.25	13,043.14	19,600.00	1,730.00	34,373.14	11,400.87	19,900.00	1,730.00	33,030.87
Avg	14,807.23	20,190.00	1,575.30	36,572.53	13,726.41	19,642.50	1,371.20	34,740.11	13,309.13	19,612.50	1,220.40	34,142.03
Prop.	40.49	55.21	4.31		39.51	56.54	3.95		38.98	57.44	3.57	

Table 8. Computational results on Dataset G2

Instance	Best Known Z'	$\eta = 3$		$\eta = 4$		$\eta = 5$	
		Dev (%)	CPU time (s)	Dev (%)	CPU time (s)	Dev (%)	CPU time (s)
#1	50,835.10	0.0263	99.84	0.0000	499.83	0.0000	1,775.46
#2	49,047.09	0.0045	121.54	0.0004	735.60	0.0000	3,369.74
#3	44,026.05	0.0428	124.29	0.0212	713.73	0.0000	3,518.18
#4	54,139.22	0.0004	100.10	0.0000	510.60	0.0000	1,505.83
#5	53,733.12	0.0201	106.35	0.0107	603.41	0.0000	3,549.63
#6	49,156.52	0.0304	121.39	0.0005	776.08	0.0000	3,456.92
#7	49,315.18	0.0186	120.59	0.0000	742.43	0.0000	3,436.71
#8	51,051.50	0.0000	112.95	0.0000	631.74	0.0000	1,422.22
#9	57,920.34	0.0113	101.17	0.0000	458.87	0.0000	907.24
#10	52,668.30	0.0153	137.14	0.0001	718.16	0.0000	2,866.38
Avg Dev		0.0170		0.0033		0.0000	
# Optimal		1		5		10	
Avg Cpu			114.53		639.04		2,580.83

Similarly to the results on Dataset G1, the experiments on Dataset G2 given in Table 9 show that the crew cost also contributes the highest proportion to the total cost with more or less 61%, followed by the fuel cost and penalty cost with 35% and 4% respectively. The table reveals that the travel and crew costs increase when the value of η decreases, whereas the penalty cost increases. In contrast to the previous results on Dataset G1, the results on Dataset G2 show that the proportion of penalty cost to the total cost decreases when the value of η decreases. In other words, the optimal solution does not only consider the penalty cost but also other costs as well.

To assess the computational complexity of the problem, we also carried out experiments with a larger size of the problem, which considers 3 wind farms with 24 turbines each to be maintained (72 turbines in total) and a 2 week (14 periods) planning horizon. This problem can be solved successfully by the proposed decomposition method using $\eta = 5$. However, it requires more than 40 hours to solve the problem. In other words, when the size of the problem increases, the CPU time required for solving the problem increases exponentially. As the proposed model aims to deal with short term scheduling problem for a planning horizon where the weather windows can be accurately forecasted, the complexity of the problem does nevertheless not severely impact the applicability of the model. In the case that the medium (or long) term problems need to be solved, a simpler scheduling model (without routing) would probably be sufficient, or metaheuristic techniques could also be used to generate near-optimal solutions in a reasonable computation time.

Table 9. Cost breakdown for the solutions attained by the proposed method on Dataset G2

Instance	$\eta = 3$				$\eta = 4$				$\eta = 5$			
	Fuel Cost	Crew Cost	Penalty Cost	Total Cost	Fuel Cost	Crew Cost	Penalty Cost	Total Cost	Fuel Cost	Crew Cost	Penalty Cost	Total Cost
#1	19,794.83	30,975.00	1,400.00	52,169.83	18,810.10	30,625.00	1,400.00	50,835.10	18,810.10	30,625.00	1,400.00	50,835.10
#2	17,045.11	32,225.00	0.00	49,270.11	17,114.72	31,950.00	0.00	49,064.72	16,702.09	30,975.00	1,370.00	49,047.09
#3	16,434.87	29,475.00	0.00	45,909.87	16,259.72	28,700.00	0.00	44,959.72	15,601.05	28,425.00	0.00	44,026.05
#4	18,834.46	33,450.00	1,876.00	54,160.46	18,813.22	33,450.00	1,876.00	54,139.22	18,813.22	33,450.00	1,876.00	54,139.22
#5	17,153.23	35,050.00	2,608.00	54,811.23	17,758.00	34,725.00	1,825.00	54,308.00	17,147.12	33,750.00	2,836.00	53,733.12
#6	19,354.96	29,875.00	1,420.00	50,649.96	18,512.57	29,250.00	1,420.00	49,182.57	18,461.52	29,275.00	1,420.00	49,156.52
#7	18,672.19	30,000.00	1,561.00	50,233.19	18,704.18	29,050.00	1,561.00	49,315.18	18,704.18	29,050.00	1,561.00	49,315.18
#8	17,667.50	29,825.00	3,559.00	51,051.50	17,667.50	29,825.00	3,559.00	51,051.50	17,667.50	29,825.00	3,559.00	51,051.50
#9	18,490.45	36,475.00	3,609.00	58,574.45	18,536.34	35,775.00	3,609.00	57,920.34	18,536.34	35,775.00	3,609.00	57,920.34
#10	18,166.46	32,125.00	3,183.00	53,474.46	17,694.28	30,800.00	4,180.00	52,674.28	17,988.30	30,500.00	4,180.00	52,668.30
Avg	18,161.41	31,947.50	1,921.60	52,030.51	17,987.06	31,415.00	1,943.00	51,345.06	17,843.14	31,165.00	2,181.10	51,189.24
Prop.	34.91	61.40	3.69		35.03	61.18	3.78		34.86	60.88	4.26	

5.3 Comparative analysis: multiple wind farms and O&M bases model versus single wind farm and O&M base model

In this subsection, the potential cost saving attained by implementing the multiple wind farms and O&M bases model (referred to as the multiple model) instead of applying single wind farm and O&M model separately (referred to as the single model) is presented. In the single model, an O&M base is dedicated to serve only one wind farm. In other words, the resources (vessels and technicians) are also only allocated to the corresponding wind farm. Additional experiments were carried out to calculate the cost saving made by implementing the multiple model. Dataset G1 is used in this experiment with a little amendment. We increase the duration of weather windows for vessel V3 given in Table 4 for periods 1 and 2 from 7 hours to 12 hours. This is to increase the chance that the feasible optimal solution can be obtained if the model is solved separately for each single model.

Table 10 presents the dataset configuration when the model is solved separately for each single model. As Dataset G1 includes three wind farms and two O&M bases, we divide OM2 into two O&M bases namely OM2a and OM2b. OM1 only serves wind farm 1 (WF1) whereas OM2a and OM2b are allocated to WF2 and WF3 respectively. The table also shows that OM1 has two vessels while OM2a and OM2b have only one vessel. The number of technicians for each skill type available in OM2a and OM2b is half of the one in OM2 (i.e. 6 technicians). The weather window for each vessel and each period is also given in Table 10. As the model will be solved separately, there are three single problems that need to be addressed with the total cost calculated by summing up the cost obtained from each problem. Ten instances (sets of turbines) of Dataset G1 are also used in this experiment.

Table 10. Dataset configuration for single wind farm and O&M base model

O&M	Number of Technicians			Wind farm	Vessel	Weather Window (hours)		
	Type 1	Type 2	Type 3			Period 1	Period 2	Period 3
OM1	6	6	6	WF1	V1	6	6	12
					V2	12	12	12
OM2a	3	3	3	WF2	V3	12	12	12
OM2b	3	3	3	WF3	V4	12	12	12

Table 11 shows the comparative analysis between multiple and single models, where the objective function value (total cost), CPU time (in seconds), and %Dev (deviation from the results of the single model to the multiple ones) are given.

Table 11. Comparison of results between the multiple and single models

Instance	multiple model		single model								Saving	
			OM1 serves WF 1		OM2a serves WF 2		OM2b serves WF 3		Total Solution (OM1+OM2a+OM2b)			
	Z	CPU time (s)	Z	CPU time (s)	Z	CPU time (s)	Z	CPU time (s)	Z	CPU time (s)	Cost	%Dev
#1	35,944.17	718.78	12,683.69	144.34	10,559.94	3.61	16,055.94	11.84	39,299.57	159.80	3,355.40	9.34
#2	31,378.89	258.85	10,000.42	103.18	13,600.63	2.32	12,033.73	6.53	35,634.78	112.03	4,255.89	13.56
#3	32,680.80	183.13	12,380.20	42.73	NF	-	11,408.92	13.17	NF	-	NF	-
#4	28,770.38	579.89	9,592.68	331.37	8,986.75	8.52	15,385.18	4.10	33,964.61	344.00	5,194.23	18.05
#5	28,068.42	249.75	10,178.69	110.29	9,290.87	3.23	10,572.14	4.77	30,041.69	118.29	1,973.28	7.03
#6	33,795.43	134.31	11,822.31	30.57	NF	-	NF	-	NF	-	NF	-
#7	27,499.47	559.84	9,909.68	125.52	9,040.84	9.08	10,476.79	30.87	29,427.31	165.47	1,927.84	7.01
#8	32,036.04	254.39	12,412.67	21.34	8,398.74	2.71	14,480.66	7.03	35,292.07	31.08	3,256.03	10.16
#9	27,392.17	797.20	9,140.52	51.76	11,061.70	2.75	12,758.18	33.94	32,960.40	88.45	5,568.22	20.33
#10	30,517.21	286.07	8,807.03	157.27	NF	-	12,637.36	5.33	NF	-	NF	-
Average		488.39								145.59		12.21

In this experiment we set the maximum number of turbines that can be visited by a vessel (η) to 5 as this value provides the optimal solutions for the multiple model. In Table 11, the solutions for each single problem along with total solution for all single problems are provided. The table shows that in instances 3, 6, and 10 the feasible solution cannot be obtained (infeasible solution – NF) when the problem is solved separately. This is due to the lack of resources needed in an O&M base to serve an offshore wind farm. This disadvantage can be overcome by implementing the multiple model where feasible optimal solutions can be obtained by sharing resources to maintain wind turbine in several wind farms. Table 11 also reveals that implementing the multiple model instead of the single model separately will also reduce the maintenance cost by 12.21% on average (calculated based on the results with feasible solutions). However, the computational time (on average) needed to solve the multiple model is more than three times compared to the one to solve all single problems. This is due to the fact that the number of possible routes for a vessel for visiting wind turbines in the multiple model is higher than in the single model.

6. Conclusion and suggestions

In this paper, we propose an optimisation model and a decomposition solution method for maintenance routing and scheduling in offshore wind farms. A mathematical model for selecting the optimum route configuration is developed to minimise the total cost comprising travel, technicians, and penalty costs. An algorithm incorporating a MILP model for generating all feasible routes is also proposed. The algorithm explores all combinations of turbines that are feasible to be serviced in a period and finds the optimal routing for the vessels to visit those turbines.

The proposed approach was tested on two types of datasets. The first one is the existing dataset from the literature provided by Dai *et al.* (2015), whereas the second one is randomly generated. The computational experiments on the existing dataset show that the proposed approach outperforms the method proposed by Dai *et al.* (2015). The proposed method obtained the optimal solutions in a relatively small computational time. The new datasets are generated for evaluating the proposed method to solve the enhanced model where multiple wind farms, multiple O&M bases, and the number of each technician type available at each O&M base are considered. The newly generated dataset is relatively hard to solve, and based on computational experiments, the proposed method required more time to obtain the optimal

solutions on this dataset than on the less challenging data set of Dai *et al.* (2015). Additional experiments are also carried out to assess the advantage of implementing the model for multiple wind farms and O&M bases compared to the model for single wind farm and O&M base. Based on the computational experiments, the proposed model (for multiple wind farms and O&M bases) not only gives a cost saving of 12.21% on average, but also provides optimal feasible solutions when the feasible solution cannot be found in the single problem (one wind farm and one O&M base) due to lack of resources (vessels and technicians).

There are a number of possible extensions to enhance the model to make it more applicable to both offshore wind farms in operation and under development. For larger wind farms and clusters of wind farms, one could investigate metaheuristic techniques to solve relatively larger maintenance routing and scheduling problems. For far-offshore wind farms and clusters of these, the scheduling and routing of Service Operation Vessels (SOV) or other "mother vessels" staying offshore for multiple days becomes more relevant. One challenge is coordinating the operation of such vessels with the use of daughter vessels, ordinary CTVs and possibly also helicopters. Another logistics solution for far-offshore wind farms, namely offshore accommodation platforms serving one or a cluster of wind farms, can on the other hand be represented in the proposed model without the need for any extensions. Extended or similar models could also include possible safety constraints specific to the offshore logistics for a given offshore wind farm. Furthermore, the model could also be extended to include the grouping of the maintenance tasks and number of turbine visits as decision variables, thus allowing "opportunistic" maintenance scheduling and an even more efficient utilization of the resources. Including revenue losses in the penalty costs to penalize preventive maintenance during good wind conditions would also be a promising extension of the model to further improve the maintenance schedule.

One major challenge for application as an operational decision support tool for a real offshore wind farm is the uncertainty and variability associated with weather conditions. Stochastic constraints such as weather condition uncertainty could also be taken into account in the model. Considering also the experience of the CTV crew on the local conditions within the wind farm could also improve the applicability of this optimisation model.

Acknowledgments

The research leading to these results has received funding from the European Union Seventh Framework Programme under the agreement SCP2-GA-2013-614020 (LEANWIND: Logistic Efficiencies And Naval architecture for Wind Installations with Novel Developments).

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