# Conditional SIC-POVMs 

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#### Abstract

In this paper we examine a generalization of the symmetric informationally complete POVMs. SIC-POVMs are the optimal measurements for full quantum tomography, but if some parameters of the density matrix are known, then the optimal SIC POVM should be orthogonal to a subspace. This gives the concept of the conditional SIC-POVM. The existence is not known in general, but we give a result in the special cases when the diagonal is known of the density matrix.


Keywords: Quantum state tomography, Hilbert-Schmidt distance, SIC-POVM, projections, quasi-orthogonality.

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## 1 Introduction

The motivation for a positive operator valued measure (POVM) is in the quantum information theory. The outcome statistics of a quantum measurement are described by (one or more) POVMs. A sequence of measurements on copies of a system in an unknown state will reveal the state. This process is called quantum state tomography [10].

A POVM is a set $\left\{E_{i}: 1 \leq i \leq k\right\}$ of positive operators such that $\sum_{i} E_{i}=I$. A quantum density matrix $\rho$ can be informed by the probability distribution $\left\{\operatorname{Tr} \rho E_{i}: 1 \leq\right.$ $i \leq k\}$. A density $\rho \in M_{n}(\mathbb{C})$ has $n^{2}-1$ real parameters. To cover all parameters $k \geq n^{2}$ should hold for the POVM. We can take projections $P_{i}, 1 \leq i \leq n^{2}$, such that

$$
\sum_{i=1}^{n^{2}} P_{i}=n I, \quad \operatorname{Tr} P_{i} P_{j}=\frac{1}{n+1} \quad(i \neq j), \quad E_{i}=\frac{1}{n} P_{i}
$$

and this is called symmetric informationally complete POVM (SIC POVM) by Zauner [18] and it is rather popular now [1, 2, 4, 9, 14, 19]. Zauner shoved the existence for $n \leq 5$

[^0]and there has been more mathemtical and numerical arguments [6, 16]. The existence of a SIC POVM is not known for every dimension. Another terminology for this is tight equiangular frame. We may also consider less than $n^{2}$ projections with similar properties.

A SIC POVM $\left\{E_{i}: 1 \leq i \leq n^{2}\right\}$ of an $n$-level system is optimal for several arguments. For example, the SIC POVM was optimal in our paper [12] where the minimization of the determinant of the average covariance matrix was studied. Actually, this kind of optimization is too complicated and a different argument was in [15], minimization of the square of the Hilbert-Schmidt distance of the estimation and the true density. In the present paper the minimization of the square of the Hilbert-Schmidt distance will be used.

In this paper the subject is the state estimation again, but a part of the $n^{2}-1$ parameters is supposed to be known and we want to estimate only the unknown parameters. A POVM $\left\{E_{i}: 1 \leq i \leq k\right\}$ is good when $k<n^{2}$ and $n^{2}-k$ parameters are known. It is obvious that the optimal POVM depends on the known parameters and we use the expression of conditional SIC POVM. This seems to be a new subject, the existence of such conditional SIC POVM can be a fundamental question in different quantum tomography problems. The description of the conditional SIC POVM is the main result in Section 1, however, the existence is not at all clear. The formalism is in a finite dimensional Hilbert space $\mathcal{H}$ and a state means a density matrix in $B(\mathcal{H})$. The known parameters determine a traceless part $B \subset B(\mathcal{H})$ and the operators of the conditional SIC POVM are orthogonal to $B$. In Section 2 a particular situation is studied, we assume that the diagonal entries of the state space are given. A mathematical subject called planar difference set in projective geometry is used there.

## 2 The optimality of conditional SIC-POVMs

We examine the case of $M_{n}(\mathbb{C})$. Let us suppose that $\sigma_{i}$ is an orthonormal basis of self-adjoint matrices, i.e.

$$
\sigma_{i}=\sigma_{i}^{*}, \quad\left\langle\sigma_{i}, \sigma_{j}\right\rangle=\delta_{i, j}, \quad i, j \in\left\{0,1,2, \ldots n^{2}-1\right\}
$$

We fix $\sigma_{0}=\frac{1}{\sqrt{n}} I_{n}$. (The elements of this basis are often called generalized Pauli matrices.)
A quantum state $\rho$ satisfies the conditions $\operatorname{Tr} \rho=1$ and $\rho \geq 0$. It can be written in the form

$$
\rho=\sum_{i=0}^{n^{2}-1} \theta_{i} \sigma_{i}
$$

where $\theta_{0}=\frac{1}{\sqrt{n}}$. A necessary condition for the coefficients can be obtained:

$$
\begin{equation*}
\sum_{i=1}^{n^{2}} \theta_{i}^{2}=\operatorname{Tr} \rho^{2} \leq 1 \tag{1}
\end{equation*}
$$

We decompose $M_{n}(\mathbb{C})$ to three orthogonal subspaces:

$$
\begin{equation*}
M_{n}(\mathbb{C})=A \oplus B \oplus C \tag{2}
\end{equation*}
$$

where $A:=\left\{\lambda I_{n}: \lambda \in \mathbb{C}\right\}$ is one dimensional. Denote the orthogonal projections to the subspaces $A, B, C$ by $\mathbf{A}, \mathbf{B}, \mathbf{C}$. A density matrix $\rho \in M_{n}(\mathbb{C})$ has the form

$$
\rho=\frac{I_{n}}{n}+\mathbf{B} \rho+\mathbf{C} \rho
$$

Assume that $\mathbf{B} \rho$ is the known traceless part of $\rho$ and $\mathbf{C} \rho$ is the unknown traceless part of $\rho$. We use the notation $\rho_{*}=\rho-\mathbf{B} \rho$. The aim of the state estimation is to cover $\rho_{*}$. If the dimension of $B$ is $m$, then the dimension of $C$ is $n^{2}-m-1$. For the state estimation we have to use a POVM with at least $N=n^{2}-m$ elements. To get a unique solution we will use POVM with exactly $N$ elements: $\left\{F_{1}, F_{2}, \ldots, F_{N}\right\}$. For obtaining optimal POVM, we will use similar arguments to [11] which was a straightforward extension of the idea appeared in [15].

If $\left\{Q_{i}: 1 \leq i \leq N\right\}$ are self-adjoint matrices satisfying the following equation

$$
\rho_{*}=\frac{1}{n} I+\sum_{\sigma_{i} \in C} \theta_{i} \sigma_{i}=\sum_{i=1}^{N} p_{i} Q_{i}, \quad p_{i}=\operatorname{Tr} \rho F_{i}
$$

then $\left\{Q_{i}: 1 \leq i \leq N\right\}$ is a dual frame of $\left\{F_{i}: 1 \leq i \leq N\right\}$. Then the state reconstruction formula can be written as

$$
\hat{\rho}_{*}=\sum_{i=1}^{N} \hat{p}_{i} Q_{i} .
$$

We define the distance as

$$
\left\|\rho_{*}-\hat{\rho}_{*}\right\|_{2}^{2}=\operatorname{Tr}\left(\rho_{*}-\hat{\rho_{*}}\right)^{2}=\sum_{i, j=1}^{N}(p(i)-\hat{p}(i))(p(j)-\hat{p}(j))\left\langle Q_{i}, Q_{j}\right\rangle
$$

and its expectation value is

$$
\begin{aligned}
\sum_{i, j=1}^{N} & (p(i) \delta(i, j)-p(i) p(j))\left\langle Q_{i}, Q_{j}\right\rangle \\
& =\sum_{i=1}^{N} p(i)\left\langle Q_{i}, Q_{i}\right\rangle-\left\langle\sum_{i=1}^{N} p(i) Q_{i}, \sum_{j=1}^{N} p(j) Q_{j}\right\rangle \\
& =\sum_{i=1}^{N} p(i)\left\langle Q_{i}, Q_{i}\right\rangle-\operatorname{Tr}\left(\rho_{*}\right)^{2} .
\end{aligned}
$$

We concentrate on the first term which is

$$
\begin{equation*}
\sum_{i=1}^{N}\left(\operatorname{Tr} F_{i} \rho\right)\left\langle Q_{i}, Q_{i}\right\rangle \tag{3}
\end{equation*}
$$

and we take the integral with respect to the Haar measure on the unitaries $\mathrm{U}(n)$.
Note first that

$$
\int_{\mathrm{U}(n)} U P U^{*} d \mu(U)
$$

is the same constant $c$ for any projection of rank 1 . If $\sum_{i=1}^{n} P_{i}=I_{n}$, then

$$
n c=\sum_{i=1}^{n} \int_{\mathrm{U}(n)} U P_{i} U^{*} d \mu(U)=I_{n}
$$

and we have $c=I_{n} / n$. Therefore for $A=\sum_{i=1}^{n} \lambda_{i} P_{i}$ we have

$$
\int_{\mathrm{U}(n)} U A U^{*} d \mu(U)=\sum_{i=1}^{n} \lambda_{i} c=\frac{I_{n}}{n} \operatorname{Tr} A
$$

and application to the integral of (3) gives

$$
\int \operatorname{Tr} F_{i}\left(U \rho U^{*}\right) d \mu(U)=\frac{1}{n} \operatorname{Tr} F_{i} .
$$

So we get the following quantity for the error of the state estimation:

$$
T:=\int E\left(\left\|U \rho^{*} U^{*}-U \hat{\rho^{*}} U^{*}\right\|_{2}^{2}\right) d \mu(U)=\frac{1}{n} \sum_{i=1}^{N}\left(\operatorname{Tr} F_{i}\right)\left\langle Q_{i}, Q_{i}\right\rangle-\operatorname{Tr}\left(\rho^{*}\right)^{2}
$$

This is to be minimized. Since the second part is constant, our task is to minimize the first part:

$$
\begin{equation*}
\sum_{i=1}^{N}\left(\operatorname{Tr} F_{i}\right)\left\langle Q_{i}, Q_{i}\right\rangle \tag{4}
\end{equation*}
$$

We define the superoperator:

$$
\mathbf{F}=\sum_{i=1}^{N}\left|F_{i}\right\rangle\left\langle F_{i}\right|\left(\operatorname{Tr} F_{i}\right)^{-1}
$$

It will have rank $N$, so if $N<n^{2}$ the inverse of $\mathbf{F}$ does not exists, but we can use its pseudo-inverse $\mathbf{F}^{-}$, so $\mathbf{F}^{-}\left|\sigma_{i}\right\rangle=0$, if $\sigma_{i} \in B . R_{i}$ is the canonical dual frame of $F_{i}$, if

$$
\left|R_{i}\right\rangle=\mathbf{F}^{-}\left|P_{i}\right\rangle
$$

where $P_{i}=\left(\operatorname{Tr} F_{i}\right)^{-1} F_{i}$.
Lemma 1 For a fixed $F_{i}$, (4) is minimal if $Q_{i}=R_{i}$, i.e. if we use the canonical dual frame.

Proof. Let us use the notation $W_{i}=Q_{i}-R_{i}$. Then

$$
\begin{align*}
\sum_{i=1}^{N} \operatorname{Tr} F_{i}\left|R_{i}\right\rangle\left\langle W_{i}\right| & =\sum_{i=1}^{N} \operatorname{Tr} F_{i}\left|R_{i}\right\rangle\left\langle Q_{i}\right|-\sum_{i=1}^{N} \operatorname{Tr} F_{i}\left|R_{i}\right\rangle\left\langle R_{i}\right| \\
& =\sum_{i=1}^{N} \operatorname{Tr} F_{i} \mathbf{F}^{-}\left|P_{i}\right\rangle\left\langle Q_{i}\right|-\sum_{i=1}^{N} \operatorname{Tr} F_{i} \mathbf{F}^{-}\left|P_{i}\right\rangle\left\langle P_{i}\right| \mathbf{F}^{-} \\
& =\mathbf{F}^{-} \sum_{i=1}^{N} \operatorname{Tr} F_{i}\left|P_{i}\right\rangle\left\langle Q_{i}\right|-\mathbf{F}^{-}\left(\sum_{i=1}^{N} \operatorname{Tr} F_{i}\left|P_{i}\right\rangle\left\langle P_{i}\right|\right) \mathbf{F}^{-} \\
& =\mathbf{F}^{-} \boldsymbol{\Pi}-\mathbf{F}^{-} \mathbf{F F}^{-}=\mathbf{F}^{-} \boldsymbol{\Pi}-\mathbf{F}^{-} \boldsymbol{\Pi}=0, \tag{5}
\end{align*}
$$

where $\boldsymbol{\Pi}=\mathbf{A}+\mathbf{C}$, and we use that from

$$
\left|\rho^{*}\right\rangle=\sum_{i=1}^{N}\left\langle F_{i}\right||\rho\rangle\left|Q_{i}\right\rangle
$$

follows

$$
\boldsymbol{\Pi}=\sum_{i=1}^{N}\left|Q_{i}\right\rangle\left\langle F_{i}\right| .
$$

So we have

$$
\begin{aligned}
\sum_{i=1}^{N} \operatorname{Tr} F_{i}\left\langle Q_{i}, Q_{i}\right\rangle= & \sum_{i=1}^{N} \operatorname{Tr} F_{i}\left\langle W_{i}, W_{i}\right\rangle+\sum_{i=1}^{N} \operatorname{Tr} F_{i}\left\langle W_{i}, R_{i}\right\rangle \\
& +\sum_{i=1}^{N} \operatorname{Tr} F_{i}\left\langle R_{i}, W_{i}\right\rangle+\sum_{i=1}^{N} \operatorname{Tr} F_{i}\left\langle R_{i}, R_{i}\right\rangle \\
= & \sum_{i=1}^{N} \operatorname{Tr} F_{i}\left\langle W_{i}, W_{i}\right\rangle+\sum_{i=1}^{N} \operatorname{Tr} F_{i}\left\langle R_{i}, R_{i}\right\rangle \\
\geq & \sum_{i=1}^{N} \operatorname{Tr} F_{i}\left\langle R_{i}, R_{i}\right\rangle .
\end{aligned}
$$

We know the optimal dual frame for a fixed POVM $F_{i}$, and the following lemma provides a property for the optimal POVM:

Lemma 2 The quantity in (4) is minimal if

$$
\mathbf{F}=\mathbf{A}+\frac{n-1}{N-1} \mathbf{C} .
$$

Proof. From (5) we have

$$
\sum_{i=1}^{N}\left(\operatorname{Tr} F_{i}\right)|R(i)\rangle\langle R(i)|=\mathbf{F}^{-} \boldsymbol{\Pi}=\mathbf{F}^{-}
$$

so we have the equation:

$$
\sum_{i=1}^{N}\left(\operatorname{Tr} F_{i}\right)\langle R(i), R(i)\rangle=\operatorname{Tr}\left(\mathbf{F}^{-}\right)
$$

Let $\nu_{1} \geq \nu_{2} \geq \ldots \geq \nu_{n^{2}}$ be the eigenvalues of $\mathbf{F}$. Since the $\operatorname{rank}$ of $\mathbf{F}$ is $N$, we have $\nu_{i}=0$ for $i>N$. We want to minimize

$$
\operatorname{Tr}\left(\mathbf{F}^{-}\right)=\sum_{i=1}^{N} \frac{1}{\nu_{i}} .
$$

It is easy to check that $\mathbf{A}$ is an eigenfunction of $\mathbf{F}$ with $\nu_{1}=1$ eigenvalue:

$$
\mathbf{F}|I\rangle=\sum_{i=1}^{N}\left(\operatorname{Tr} F_{i}\right)|P(i)\rangle\langle P(i), I\rangle=\sum_{i=1}^{N}\left(\operatorname{Tr} F_{i}\right)|P(i)\rangle=\sum_{i=1}^{N}|F(i)\rangle=|I\rangle
$$

and we have the following condition:

$$
\sum_{i=1}^{N} \nu_{i}=\operatorname{Tr} \mathbf{F}=\sum_{i=1}^{N}\left\langle P_{i}, P_{i}\right\rangle \operatorname{Tr} F_{i} \leq \sum_{i=1}^{N} \operatorname{Tr} F_{i}=\operatorname{Tr} I=n
$$

Combining these conditions we get that the measurement is optimal if $\nu_{2}=\nu_{3}=\ldots=$ $\nu_{N}=\frac{n-1}{N-1}$.

Now we can obtain that the optimal POVM is a conditional SIC-POVM:
Theorem 1 If

$$
\begin{equation*}
\mathbf{F}=\mathbf{A}+\frac{n-1}{N-1} \mathbf{C} . \tag{6}
\end{equation*}
$$

then

$$
\sum_{i=1}^{N} P_{i}=\frac{N}{n} I, \quad \operatorname{Tr} P_{i} P_{j}=\frac{N-n}{n(N-1)} \quad(i \neq j), \quad \operatorname{Tr} \sigma_{k} P_{i}=0 \quad\left(\sigma_{k} \in B\right)
$$

Proof. Let us use notation $\lambda_{i}=\operatorname{Tr} F_{i}$, then (6) has the form:

$$
\sum_{i=1}^{N} \lambda_{i}\left|P_{i}\right\rangle\left\langle P_{i}\right|=\mathbf{A}+\frac{n-1}{N-1} \mathbf{C}
$$

Then we have to the following equation:

$$
\begin{equation*}
\sum_{i=1}^{N} \lambda_{i}\left\langle Q \mid P_{i}\right\rangle\left\langle P_{i} \mid Q\right\rangle=\langle Q| \mathbf{A}+\frac{n-1}{N-1} \mathbf{C}|Q\rangle \tag{7}
\end{equation*}
$$

with $Q:=P_{k}-d \cdot I$.
From $\left\langle P_{i} \mid Q\right\rangle=\operatorname{Tr} P_{i} P_{k}-d$ the left hand side of (17) becomes

$$
\sum_{i=1}^{N} \lambda_{i}\left\langle Q \mid P_{i}\right\rangle\left\langle P_{i} \mid Q\right\rangle=\lambda_{k}(1-d)^{2}+\sum_{i \neq k} \lambda_{i}\left(\operatorname{Tr} P_{i} P_{k}-d\right)^{2}
$$

We can compute the right hand side as well:

$$
\begin{gathered}
\mathbf{A}\left(P_{k}-d I\right)=\mathbf{A} P_{k}-d I=\mathbf{A}\left(P_{k}-I / n\right)+I / n-d I=I(1 / n-d), \\
\langle Q| \mathbf{A}|Q\rangle=(1 / n-d) \operatorname{Tr}\left(P_{k}-d I\right)=n(1 / n-d)^{2}
\end{gathered}
$$

When $P_{k}=\sum_{i=0}^{N} c_{i} \sigma_{i}$, then

$$
\mathbf{C}|Q\rangle=\sum_{\sigma_{i} \in C} c_{i} \sigma_{i}, \quad\langle Q| \mathbf{C}|Q\rangle=\sum_{\sigma_{i} \in C} c_{i}^{2} .
$$

So (7) becomes

$$
\begin{equation*}
\lambda_{k}(1-d)^{2}+\sum_{i \neq k} \lambda_{i}\left(\operatorname{Tr} P_{i} P_{k}-d\right)^{2}=n(1 / n-d)^{2}+\frac{n-1}{N-1} \sum_{\sigma_{i} \in C} c_{i}^{2} \tag{8}
\end{equation*}
$$

From (1) we have

$$
\begin{equation*}
\sum_{\sigma_{i} \in C} c_{i}^{2} \leq 1-c_{0}^{2}=1-1 / n \tag{9}
\end{equation*}
$$

This implies

$$
\lambda_{k}(1-d)^{2} \leq n(1 / n-d)^{2}+\frac{n-1}{N-1}(1-1 / n)
$$

which is true for every value of $d$, so

$$
\lambda_{k} \leq \min _{d} \frac{n(1 / n-d)^{2}+\frac{n-1}{N-1}(1-1 / n)}{(1-d)^{2}}
$$

By differentiating we can obtain that the right hand side is minimal if:

$$
d=\frac{N-n}{n(N-1)}
$$

and then we get

$$
\lambda_{k} \leq \frac{n}{N} .
$$

Since $\sum_{i=k}^{N} \lambda_{k}=n$, we have $\lambda_{1}=\lambda_{2}=\ldots=\lambda_{N}=n / N$.
From that follows that there is an equality in (9) too, so we have

$$
\sum_{\sigma_{i} \in C} c_{i}^{2}=1-c_{0}^{2} \Rightarrow c_{i}=0, \text { if } \sigma_{i} \in B \quad \Rightarrow \quad \operatorname{Tr} \sigma_{i} P_{k}=0, \text { if } \sigma_{i} \in B
$$

On the other hand from (8) we have

$$
\sum_{i \neq k} \frac{n}{N}\left(\operatorname{Tr} P_{i} P_{k}-\frac{N-n}{n(N-1)}\right)^{2}=0
$$

So it implies

$$
\operatorname{Tr} P_{i} P_{k}=\frac{N-n}{n(N-1)} \quad \text { if } \quad i \neq k
$$

One has to be careful about this result though, since we only consider the case of linear state reconstruction, as it was stated in [15]. Finding the optimal statistic in a more general setting requires complicated nonlinear optimalization.

Now we look at some examples related to the previous theorem and we take different $N$ values.

Example 1 If we do not have any information a priori about the state ( $m=0, N=n^{2}$ ), then

$$
\operatorname{Tr} P_{i} P_{j}=\frac{1}{n+1} \quad(i \neq j)
$$

so the optimal POVM is the well-known SIC-POVM (if it exists [14]).
Example 2 If we know the off-diagonal elements of the state, and we want to estimate the diagonal entries ( $m=n^{2}-n, N=n$ ), then from Theorem 1 it follows that the optimal POVM has the properties

$$
\operatorname{Tr} P_{i} P_{j}=0 \quad(i \neq j), \quad \sum_{i=1}^{n} P_{i}=I, \quad \text { and } \quad P_{i} \text { is diagonal. }
$$

So the diagonal matrix units form an optimal POVM.
Example 3 If we know the diagonal elements of the state, and we want to estimate the off-diagonal entries ( $m=n-1, N=n^{2}-n+1$ ), then from Theorem 1 it follows that the optimal POVM has the properties

$$
\operatorname{Tr} P_{i} P_{j}=\frac{n-1}{n^{2}} \quad(i \neq j), \quad \sum_{i=1}^{n} P_{i}=\frac{n^{2}-n+1}{n} I
$$

and $P_{i}$ has a constant diagonal. More about this case is in the next section.

## 3 Existence of some conditional SIC-POVMs

Theorem 1 tells that conditional SIC-POVMs are the optimal measurements if they exist, but it was not written anything about the existence of such POVMs. The existence of SIC-POVMs for arbitrary dimension is not known and they are a special case of the conditional SIC-POVMs. We can not expect to give a full description of SIC-POVMs, but this section contains a particular example. There are seqveral equiangular frames with less than $n^{2}$ projections [3], but it is not clear, what parameters are spanned by their complementary part, ie. what the known parameters are. Intuition suggests that the case when the known part corresponds to a subalgebra of the full matrixalgebra is especially interesting.

Suppose we know the diagonal elements of a $n$-dimensional density matrix. We want to construct the related conditional SIC-POVM, that is subnormalized projections $P_{i}$ forming a symmetric POVM and complementary to the diagonal projections $E_{i}=\left|e_{i}\right\rangle\left\langle e_{i}\right| \in M_{n}(\mathbb{C})(1 \leq i \leq n)$. These projections form a maximal abelian subalgebra. Easy dimension counting shows, that we want to construct $N=n^{2}-n+1$ such projections.

So $\left\{\left|e_{i}\right\rangle: 1 \leq i \leq n\right\}$ is an orthonormal basis in the space. We set

$$
\begin{equation*}
|\phi\rangle=\frac{1}{\sqrt{n}} \sum_{i=1}^{n}\left|e_{i}\right\rangle, \quad q=e^{2 \pi \mathrm{i} / N} \tag{10}
\end{equation*}
$$

and a diagonal unitary

$$
U=\operatorname{Diag}\left(q^{\alpha_{1}}, q^{\alpha_{2}}, q^{\alpha_{3}}, \ldots q^{\alpha_{n}}\right)
$$

where the integer numbers $0 \leq \alpha_{i} \leq N-1$ are differents. Another unitary $T$ permutes the eigenvectors of $U$ :

$$
T\left|e_{i}\right\rangle= \begin{cases}\left|e_{i+1}\right\rangle & \text { if } 1 \leq i \leq n-1 \\ \left|e_{1}\right\rangle & \text { if } i=n\end{cases}
$$

Note, that $T|\phi\rangle=T^{*}|\phi\rangle=|\phi\rangle$. We have

$$
\begin{aligned}
\left|\left\langle U^{k} \phi, e_{j}\right\rangle\right|^{2} & =\left|\left\langle\phi,\left(U^{*}\right)^{k} e_{j}\right\rangle\right|^{2}=\left|q^{-k \alpha_{j}}\right|^{2}\left|\left\langle\phi, e_{j}\right\rangle\right|^{2}=\left|\left\langle\phi, e_{j}\right\rangle\right|^{2} \\
& =\left|\left\langle\phi, T^{j-1} e_{1}\right\rangle\right|^{2}=\left|\left\langle\left(T^{*}\right)^{j-1} \phi, e_{1}\right\rangle\right|^{2}=\left|\left\langle\phi, e_{1}\right\rangle\right|^{2}
\end{aligned}
$$

and the projections $P_{k}:=\left|U^{k} \phi\right\rangle\left\langle U^{k} \phi\right|$ are complementary to the diagonal projections:

$$
\operatorname{Tr}\left|U^{k} \phi\right\rangle\left\langle U^{k} \phi\right|\left(\left|e_{i}\right\rangle\left\langle e_{i}\right|-I / n\right)=0
$$

It is easy to check that

$$
\sum_{k=1}^{N}\left\langle e_{i}, U^{k} \phi\right\rangle\left\langle U^{k} \phi, e_{j}\right\rangle=\frac{1}{n} \sum_{k=1}^{N} q^{-\alpha_{i} k} q^{\alpha_{j} k}=\frac{1}{n} \sum_{k=1}^{N} q^{\left(\alpha_{j}-\alpha_{i}\right) k}=\frac{N}{n} \delta_{i j},
$$

so we obtain

$$
\sum_{k=1}^{N} P_{k}=\frac{N}{n} I
$$

and the sum is multiple of $I$.
We need to choose the numbers $\alpha_{1}, \alpha_{2}, \ldots, \alpha_{n}$ such that

$$
\operatorname{Tr} P_{i} P_{j}=\left|\left\langle U^{i} \phi \mid U^{j} \phi\right\rangle\right|^{2}=\frac{1}{n^{2}}\left|\sum_{m=1}^{n} q^{(j-i) \alpha_{m}}\right|^{2}=\frac{1}{n^{2}} t
$$

is constant when $i \neq j$. From the formulas

$$
\sum_{j} \operatorname{Tr} P_{i} P_{j}=(N-1) \frac{1}{n^{2}} t+1, \quad \sum_{j} \operatorname{Tr} P_{i} P_{j}=\operatorname{Tr}\left(P_{i} \sum_{j} P_{j}\right)=\frac{N}{n}
$$

we obtain $t=n-1$.
Next we use a terminology from the paper [7]. The set $G:=\{0,1, \ldots, N-1\}$ is an additive group modulo $N$. The subset $D:=\left\{\alpha_{i}: 1 \leq i \leq n\right\}$ is a difference set with parameters $(N, n, \lambda)$ when the set of differences $\alpha_{i}-\alpha_{j}$ contains every nonzero element of $G$ exactly $\lambda$ times. When this holds, then we have

$$
\left|\sum_{i=1}^{n} q^{m \alpha_{i}}\right|^{2}=\sum_{i, j=1}^{n} q^{m\left(\alpha_{i}-\alpha_{j}\right)}=n+\sum_{s=1}^{N-1} \lambda q^{s}=n-\lambda,
$$

where $q$ is from (10). Here $\lambda=1$. If the appropriate difference set exists, then there exists a conditional SIC-POVM. Similar constructions of tight equiangular frames related to difference sets are examined in detail in [8].

The existence of difference sets with parameters $(N, n, 1)$ is a known problem, named the prime power conjecture [17, 7], and we get the following result:

Theorem 2 There exists a conditional SIC-POVM with respect to the diagonal part of a density matrix if $n-1$ is a prime power. Then $N=n^{2}-n+1$ and the projection $P_{i}$ ( $1 \leq i \leq N$ ) have the properties

$$
\sum_{i=1}^{N} P_{i}=\frac{N}{n} I, \quad \operatorname{Tr} P_{i} P_{j}=\frac{n-1}{n^{2}} \quad(i \neq j)
$$

A few examples about $M=\left\{\alpha_{k}: k\right\}$ is written here:

$$
\begin{gathered}
n=2, \quad M=\{0,1\}, \quad n=3, \quad M=\{0,1,3\}, \\
n=4, \quad M=\{0,1,3,9\}, \quad n=5, \quad M=\{0,1,4,14,16\} .
\end{gathered}
$$

## References

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