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C-5A/ORBITER WIND TUNNEL TESTING AND ANALYSIS

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Final Report LG73ER0193 December 1973

by

K.H. Tomlin W.T. Blackerby A.C. Hughes E.G. Husband J.H. Paterson



Prepared under Contract NAS9-13702 for the NATIONAL AERONAUTICS AND SPACE ADMINISTRATION JOHNSON SPACECRAFT CENTER Houston, Texas

by the

LOCKHEED-GEORGIA COMPANY A Division of Lockheed Aircraft Corporation Marietta, Georgia 30063



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SUMMARY

Wind tunnel testing and analytical studies of the feasibility of ferrying the NASA Shuttle Orbiter on the C-5A in a piggyback mode have been accomplished by the Lockheed-Georgia Company in response to NASA contract NAS9-13702. The study was managed by J. H. Paterson of the Flight Sciences Division. Testing was conducted in the Lockheed-California Company 8 x 12 foot low speed wind tunnel using an existing Air Force 0.0399 scale C-5A model in conjunction with a NASA 0.0405 scale Orbiter model. Six component force and moment data were measured over a range of pitch and yaw angles to determine lift and drag characteristics, lateral/directional stability characteristics and longitudinal and directional control powers.

Appendix A contains a description of the wind tunnel test program with a run schedule and the complete plotted data for all the test runs. Initial emphasis was given to determining the effects of the Orbiter above the C-5A and the optimum location for minimum interference on C-5A characteristics. A comprehensive series of cruise configurations were tested including a range of Orbiter longitudinal and vertical locations, incidences, and afterbody fairings. Subsequently, a series of configurations were devised during the test program to determine means of recovering directional stability degradation due to Orbiter interference.

Extensions to the present C-5 vertical stabilizer were designed as were twin fins to be located at the tips of the horizontal stabilizer. Analytical studies subsequent to the test and based on test results indicate that these exterior changes should not be necessary as automatic flight controls provide satisfactory flying qualities.

Performance studies of the C-5A/Orbiter Piggyback show that the drag penalty of the Orbiter on the C-5A does not preclude non-stop, unrefueled ferry missions up to 2500 nautical miles. Some flight restrictions for the Piggyback are unavoidable; however these are not considered unreasonable for the special nature of the mission. In short, ferrying the Shuttle Orbiter in a Piggyback mode on top of a C-5A appears feasible with minimum modifications to the basic C-5A.

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1.0 INTRODUCTION

Recent interest by NASA and Rockwell International in alternatives to the present Orbiter Airbreathing Propulsion System for ferry and flight test of the Space Shuttle Orbiter has led to a series of proposals, analytical studies and wind tunnel tests to determine the feasibility of alternate systems. The Lockheed-Georgia Company has actively participated in these studies because of the suitability of Lockheed's C-5A as a carrier system for the Orbiter and in an attempt to apply Lockheed's "big airplane" talents and knowledge to this program.

In response to NASA RFP 9-BC451-M6-4-4P, regarding the feasibility of ferrying the Orbiter piggyback on top of a C-5A, Lockheed-Georgia submitted a proposal and subsequently was awarded NASA contract NAS9-13702 for a low speed wind tunnel test and analytical study of a C-5A/Orbiter Piggyback configuration. This report constitutes the final report for this contract work. Analysis of the wind tunnel test results and the feasibility of the C-5A Piggyback concept are contained in the main part of the report. Appendix A contains the final plotted results from the wind tunnel test.

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2.0 ANALYSIS OF EXPERIMENTAL RESULTS

2.1 STABILITY AND CONTROL

2.1.1 Effects of Orbiter, Cruise Configuration

The small effect of the Orbiter on the C-5 longitudinal stability is demonstrated in Figure 1. These data are for the forward, low position of the Orbiter where maximum interaction of the two wings should occur. A negative shift in C_M of 0.04 occurs at all angles of attack. Minor modifications of the medium angle of attack pitching moment, in the destabilizing sense, is apparent for the Orbiter configuration without a fairing due to wake impingement on the horizontal tail. At high angles of attack, beyond stall, the typical C-5 initial pitch up followed by a strong nose down pitch is modified by both Orbiter configurations in such a manner that the net result should be almost imperceptible to the pilot.

An increase in lift curve slope due to the presence of the Orbiter, as well as a small increase in C_{LMAX} , is demonstrated in Figure 2. A small further improvement in C_{LMAX} due to the aft fairing is shown. The C_M - C_L curves demonstrate the negative C_{MO} shift and negligible change in neutral point due to the Orbiter. The C_{MO} shift is the equivalent of less than one degree of stabilizer angle.

The effect of the higher vertical center of gravity due to the Orbiter, approximately 60 inches, will result in a slight decrease in speed stability that will be most apparent in the landing approach mode. It is anticipated that this effect will require little more than pilot familiarization with the new pitch response to engine power since the current aircraft already has a vertical c.g. range of 51 inches.

The major effect of the Orbiter on the C-5 aerodynamic data is the reduction of weathercock stability as reflected by $C_{N_{\beta}}$. Figure 3 demonstrates this effect for the most critical configuration forward and low with a negative shuttle incidence. This loss of directional stability is primarily a result of the Orbiter's influence on the air flow at the C-5 vertical tail. There is also a secondary destabilizing effect with



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this Orbiter location due to Orbiter side area that is ahead of the C-5 center of gravity. The prime effect, however, occurs because of the flow bending, caused by the Orbiter body. As a result, the C-5 vertical tail does not experience the full yaw angle seen by the forward fuselage. This reduction in yaw angle, as seen by the fin is approximately 30% of the nominal value. As shown in Figure 3, the afterbody fairing resulted in an improvement in stability at high sideslip angles but delayed the turnover point.

Lateral stability, represented by dihedral effect, is little affected by the Orbiter as shown in Figure 4. A small reduction in $C_{l\beta}$ occurs through 15° of sideslip accompanied by a linearization of the higher sideslip angle data due to the Orbiter wing configuration effect on the C-5 wing. The aft fairing causes further increases in $C_{l\beta}$ at high sideslip angles due to the fin effectiveness.

Figure 5 shows that a large increase in $C_{\gamma\beta}$ occurs due to the presence of the Orbiter as a result of the side area increase, as would be expected. The aft fairing causes a small increase in sideforce at sideslip angles greater than 15° and no effect at lesser angles. It is somewhat surprising that more sideforce does not result from the added side area of the fairing. Apparently this area is not effective in sideforce due to the very thick boundary layer or there is a compensating flow change at the fin, or both.

2.1.2 Effect of Orbiter Position, Cruise Configuration

The effect on longitudinal stability of Orbiter fore and aft and vertical position relative to the C-5 is demonstrated in Figure 6. This comparison is made with the Gelac fairing No. 1 on the Orbiter and with the Orbiter at an incidence of 0.5 degrees. The destabilizing effect of the Orbiter in the forward high position is due to the combined effect of the Orbiter lifting moment and the interference with the flow at the C-5 horizontal stabilizer. The aft low position represents a significant improvement; showing a small negative ΔC_M shift that remains constant until the stall is reached. The pitch down tendency beyond stall of the basic C-5 has been reduced slightly. A small reduction in stability occurs in the aft high position with more pitch up at the

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र. पु stall than that for the low position due to the increased stabilizer interference: however, the stability change relative to the basic C-5, below stall is negligible.

Figure 7 shows that Orbiter position has little effect on the lift curve slope and only a small effect on C_{LMAX} : the highest C_{LMAX} occurs with the Orbiter in the aft high position. From a longitudinal stability point of view it is apparent that the aft low position would be the best with the aft high position a second choice.

The effect of Orbiter position on directional stability is very pronounced as shown in Figure 8. The major change that occurs with aft movement is due to the tail-off stability increase as the body side area is moved aft of the reference c.g. A small stabilizing change in fin effectiveness occurs with aft movement of the Orbiter. Again these data demonstrate the ability of the Orbiter body to reduce the local flow angle at the fin relative to the free stream angle through $\stackrel{+}{-}$ 15 degrees. The sensitivity of the C-5 weathercock stability to the presence of the Orbiter is largely due to the equal magnitudes of tail-off instability and tail-on stability. Thus, a 50 percent loss of fin effectiveness will cause a 100 percent loss of stability. The aft, high position of the Orbiter has the best directional stability characteristic but is still slightly unstable through small sideslip angles.

A significant change in dihedral effect occurs as a function of Orbiter position as shown in Figure 9. The major effect is due to Orbiter height above the C-5, showing larger $C_{\hat{\chi}_{\beta}}$ for increased height. Fore and aft position does not appear to have much influence, showing a small increase in C_{β} for aft movement of the Orbiter. It would appear that the major effect on C_{β} is probably due to the freeing effect of moving the wings apart thus allowing full development of the normal lift change due to sideslip on both wings.

Orbiter position has a negligible effect on the net sideforce due to sideslip as shown in Figure 10. A large increase in $C_{Y\beta}$ is, of course, present due to the side area of the Orbiter configuration.

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2.1.3 Effect of Orbiter Incidence, Cruise Configuration

The effect of Orbiter incidence on the C-5 pitching moment is shown in Figure 11 for the aft, high position of the Orbiter with the aft fairing (Test Fairing No. 3). Increasing the Orbiter incidence relative to the C-5 reduced the pitching moment shift through nominal angles of attack, and at high angles of attack, increased the pitch up with a slightly less stable pitch out.

Small shifts in a_{OL} with no change in lift curve slope due to Orbiter incidence are shown in Figure 12. Increasing Orbiter incidence results in small increases in net C_{LMAX} . The $C_M - C_L$ data reflect the expected shift in C_{MO} with essentially no change in neutral point.

Insignificant changes in directional stability resulted from Orbiter incidence variation as shown in Figure 13. The basic configuration for the Orbiter was the aft, high position with the No. 3 fairing.

Only minor changes in $C_{l\beta}$ occur due to Orbiter incidence as shown in Figure 14. A small increase in $C_{l\beta}$ at the higher sideslip angles, as Orbiter incidence increases, is apparent.

No change in C_{YR} due to Orbiter incidence is apparent, as shown in Figure 15.

2.1.4 Effect of After-body Fairing, Cruise Configuration

The effect of various after-body fairing changes on pitching moment is shown in Figure 16. These fairing modifications were aimed at improving directional stability characteristics and have little direct influence on longitudinal stability other than through the drag changes.

 $C_{N\beta}$ is unstable through small angles for C-5 Orbiter combinations with both the Gelac No. 1 fairing and the Rockwell fairing. Attempts to reshape the aft fairing to improve the flow field at the vertical tail are shown in Figure 17. Small improvements



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Г. : were obtained with fairing No. 2 and 3 but are not sufficient in themselves to cure the problem.

The effects of after-body shape on $C_{\ell_{\beta}}$ and $C_{\gamma_{\beta}}$ are negligible, demonstrating the lack of load producing area in the aft body region.

2.1.5 Effect of Orbiter, Landing Configuration

The effect of the Orbiter on the longitudinal characteristics of the C-5A in the landing mode is similar to that of the clean configuration. A larger negative pitching moment shift due to the Orbiter is apparent – Figure 18. (The Orbiter is in high aft position.) A slight increase in stability is also noted.

Little or no change in lift curve slope occurs, as shown in Figure 19. A small neutral point shift in the stable sense is predictable from the $C_M - C_L$ curves of this figure. These data were obtained without the uprigged spoilers normally used for the C-5 landing configuration, however, little or no influence is expected.

In the landing configuration, the airflow at the C-5 vertical tail is not as restricted as in the clean configuration due to the large downflow, away from the fin, caused by the flaps. As shown in Figure 20, the net result is a more stable $C_{N\beta}$ level than for the clean airplane even though a small "flat spot" still occurs at small sideslip angles. The shape of the basic C-5 curve is predicated by fin stall at large sideslip angles. Since the air flow at the fin is restricted by the Orbiter in the Piggyback mode, the fin never experiences stall in the tested sideslip range, hence the more linear yawing moment at large angles.

The major effect of the Orbiter on $C_{\gamma_{\beta}}$ is to delay the fin stall at high sideslip angles so that an increase in rolling moment occurs. This effect is shown in Figure 21. Little or no effect on $C_{\ell_{\beta}}$ in the small sideslip angle range is noted.

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The effect of the Orbiter on C $_{\gamma_{\beta}}$ parallels that obtained in the clean configuration and the levels at each sideslip angle are almost identical.

2.1.6 Vertical Tail Development

The effects of the addition of a central fin to the C-5 horizontal tail bullet and the addition of tip fins to the horizontal tail are demonstrated in Figure 22. The Orbiter position is aft and high with the [#]3 aft fairing. This position results in a negligible change in tail-off $C_{N_{\beta}}$ except at the higher sideslip angles, since the Orbiter finbody area is well aft of the c.g.

The addition of a center fin above the C-5 tail produces sufficient stability beyond 5° of sideslip but is influenced by the Orbiter body effect at smaller angles. The addition of twin fins at the horizontal stabilizer tips successfully achieves the same stability level as the basic C-5 throughout the small angle range, and a much increased level at the higher sideslip angles.

The additional sideforce developed in sideslip by tip and center fins required for directional stability is shown in Figure 23. These large values are not desirable because of gust response and turn coordination, especially in light of the already large increase in sideforce due to the Orbiter.

As shown earlier, the directional stability in the landing configuration in the presence of the Orbiter, is better than that for the clean configuration. As a result the fins, as sized, represent an excess capability as shown in Figure 24.

The sideforce due to sideslip is approximately the same as for the clean configuration shown in Figure 25.

The effectiveness of the center and tip fins, without the Orbiter, are shown in Figure 26. The center fin retains its effectiveness at high sideslip angles to a higher degree than the tip fins. They are equally effective at small angles.



Similar data for the sideforce characteristics are shown in Figure 27.

2.1.7 Effect of Orbiter on Longitudinal Trim

The Orbiter, in the aft high position, has a negligible influence on the dynamic pressure of the airflow at the C-5 horizontal stabilizer and only a minor influence on the downwash. The net effect is shown in Figure 28 for the cruise configuration. It may be noted that the "Orbiter on" data of this figure also have the vertical center fin whereas the "Orbiter-off" data do not. Although not shown here, the data in the appendix demonstrates that there is no effect in pitch due to the center fin, thus the comparison is valid.

Data are not available for the landing configuration. The influence of the Orbiter on trim effectiveness is anticipated to be even less than that for the cruise configuration because of the downward depression of the wing wake, away from the tail, caused by the flaps.

A small loss in dynamic pressure at the fin occurs due to the presence of the Orbiter and a reduction of local yaw angle relative to the free stream yaw in steady sideslip, as previously demonstrated. The net effect on rudder power for trim is shown in Figure 29. The Orbiter on data also include the effects of a center fin extension as discussed in 2.1.6.

The incremental effectiveness of the rudder in yaw is not anticipated to be affected by flap deflection.

2.2 DRAG CHARACTERISTICS

2.2.1 Effect of Orbiter

Figure 30 illustrates the magnitude of the effect of the Orbiter on C-5 drag. At a cruise C_L of 0.5, the drag of the Piggyback configuration is 70% greater than the basic C-5 level. By enclosing the bluff aft end of the Orbiter, the drag level of the

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Piggyback is reduced to a level about 40% above that of the C-5 at $C_L = 0.5$. Undoubtedly, the skin friction drag of this very long fairing offsets some of the potential reduction in Orbiter base drag.

2.2.2 Effect of Orbiter Position

The effect on Piggyback cruise configuration drag of Orbiter location is shown by Figure 31. In general, the drag is seen to be insensitive to position for the locations tested, except for the aft – low position, which carries slightly lower drag up to a C_L of 0.6. The drag of the aft high position is about the same as that of the forward positions at all C_L 's. These results indicate that interference drag is a very small contributor to total drag.

2.2.3 Effect of Afterbody Fairing

Figure 32 compares drag for the various afterbodies tested. Not a great deal of significance can be attached to these results. As expected, the increased afterbody fineness ratio of Gelac fairing #1 improved the flow relative to a blunter Rockwell fairing, however, the increased skin friction drag due to additional wetted area almost negates this as the decrease in cruise drag is only about 2 percent.

2.2.4 Effect of Orbiter Incidence

Figure compares drag results for the two Orbiter incidence angles and substantiates no change in Piggyback drag due to incidence over the range from -1.5° to 0.5° .

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3.0 ASSESSMENT OF FULL SCALE FLIGHT FEASIBILITY

3.1 STABILITY AND CONTROL

3.1.1 Comparison of Wind Tunnel and Full Scale Directional Stability

The wind tunnel data, obtained from this test, are compared with the published, fullscale, levels for the C-5A to establish the base for the incremental data obtained in the presence of the Orbiter. The full-scale data are based upon the correlation of flight test data, obtained during the C-5A development program and the design wind tunnel data.

The cruise data for yaw due to sideslip are shown in Figure 34. The major change from the wind tunnel data is an extension of the fin sideforce capability to a higher yaw angle and a slightly more effective fin. There is also a more linear continuation of the tail-off yawing moment through high sideslip angles.

The landing flap data, shown in Figure 35, demonstrate further differences from the wind tunnel data. These differences are largely due to a change in the aft body interference with flaps down, that resulted in a less stable airplane than predicted by the wind tunnel. As may be noted, the net fin effectiveness, full scale, is considerably less than the wind tunnel level. These data are for landing flaps with the gear up. When the gear is down a higher CN_{β} is realized due to the effect of the gear on the afterbody interference.

3.1.2 Predicted Full-Scale Directional Stability

Using incremental tail-off and tail-on data for the effect of the Orbiter, the fullscale predicted levels of weathercock stability are shown in Figure 36 compared with the basic C-5 in the cruise configuration. As may be noted, the Orbiter/C-5 combination is neutrally stable through +15 degrees of sideslip.

The full-scale prediction for the landing configuration, gear up, is shown in Figure 37.

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5. 2 These data reflect the low full-scale fin effectiveness discussed in the previous paragraph. The configuration is predicted to be neutrally stable through $\frac{+}{2}^{\circ}$ of sideslip and lightly stable at higher angles. Although not shown here, the gear-down landing configuration will be more stable.

3.2 FLYING QUALITIES

The wind tunnel test results have shown that the present C-5A longitudinal aerodynamic characteristics would not be critically affected by the piggyback shuttle installation. Evidently such would not be the case for the lateral-directional characteristics, particularly in the cruise configuration. The C-5A with the Orbiter in position exhibits an increase in sideforce due to sideslip, $C_{y\beta} = -1.39/radian$ compared to -0.80/radian for the C-5A. The directional stability level is reduced to nil, $C_{n\beta} = 0$ composed with 0.0728/radian for the basic airplane. These predicted characteristics pertain to the M=0.52 at 20,000 feet flight condition. A cursory analysis was completed to assess the impact of these aerodynamic changes on C-5A flying qualities.

Pertinent flight vehicle data are tabulated in Figure 38. The reference gross weight is 704,626 pounds, which represents a 550,000 -pound airplane (no payload) with either a 154,626-pound cargo or the present design piggyback installation of the Orbiter vehicle. The Orbiter center of mass is considered to be 11.55 feet behind and 28.02 feet above the C-5A mass center.

Modal response data are presented in Figure 39. The aerodynamic changes due to the Orbiter installation result in a re-distribution of the total airplane damping due to $C_{\gamma\beta}$, $C_{\ell p}$ and C_{n_r} . The spiral mode is more stable, now characterized by a 15.2 second time constant. The dutch roll mode is now unstable and the period of these oscillations is doubled, $\zeta_d = -.023$ and $T_d = 18.3$ seconds. The C-5A airplane incorporates a full-time stability augmentation system (SAS) on roll and yaw axes, and thus this unstable condition would not be experienced in flight. The Orbiter ferry mission may be completed with the autopilot also operative in cruise.

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Г. 2 Flight vehicle response data were obtained using a digital computer program to evaluate responses to a 30KTAS lateral gust disturbance and a 10.0-degree lateral control wheel input. The program considers the solution of the three lateral equations of motion with respect to the usual linear assumptions. SAS and pertinent autopilot functions were included on a simple gain basis. The various high-order filters and the 0.25-second servo time constants were neglected such that the problem reduced to the control loop closures indicated in Figure 40. It is noted that the autopilot control command loops are excluded. The lateral stability functions have been included to enable an evaluation of flight vehicle response to external gust disturbances. Bank angles are presumed to be less than 7.0 degrees and thus the heading stability elements of the autopilot may also be excluded.

Figure 41 presents sideslip and bank angle responses to a continuous step gust of 30 KTAS. The lack of directional stability with the piggyback Orbiter installation results in a reluctance of the flight vehicle to naturally crab into the wind. Figure 42 provides a comparison of flight vehicle responses to control wheel throw. The excellent turn coordination characteristics of the basic C-5A airplane are somewhat degraded by the Orbiter installation. It is evident from the foregoing material that the aerodynamic changes associated with Orbiter installation may require a re-tuning of the basic C-5A stability augmentation system gains for cruise flight. The autopilot will probably be activated for the cruise condition of the Orbiter ferry mission. These would be an associated tightening of the lateral stability loop for the autopilot operative mode. The data presented in Figure 43 indicate that the flight vehicle responses to lateral gust disturbances would be stabilized, although still greater than for the basic C-5A airplane.

As stated earlier, the present analysis was of a cursory nature. The guarded conclusion is that the ferry cruise of the piggyback C-5A/Orbiter flight vehicle may not require significant C-5A flight control modifications. A continuation of studies to a greater depth than those described herein is recommended. The effects of flight vehicle vertical center of gravity location should receive attention. It is acknowledged that

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an upward shift of the flight vehicle mass center will result in a reduction of the effective dihedral. The impact of c.g position on longitudinal characteristics should also be evaluated. Low speed, flaps-down, flight should also receive analytical attention.

3.3 PERFORMANCE

3.3.1 Full-Scale Drag Characteristics

Figure 44 compares estimated and wind tunnel drag for the C-5/Orbiter Piggyback. Test results on the isolated C-5 have been summed with wind tunnel data for an isolated Orbiter at the same test Reynolds number. The addition was accomplished at constant angle of attack. The excellent agreement between these two drag polars implies an absence of any net interference drag in the cruise configuration. Therefore, for purposes of this analysis, full-scale drag at flight Reynolds number for the Piggyback configuration has been defined by summing the estimated full-scale drag of an isolated Orbiter with C-5 flight test correlated drag. Resulting lift-to-drag ratios for the Piggyback at a typical cruise Mach number of 0.6 are shown compared with the C-5 in Figure 45.

Figure 46 shows a drag comparison, similar to Figure 44, for the landing configuration. The net interference drag in this case is seen to be equal to about 75% of the isolated Orbiter drag. Therefore, the low-speed, flaps-down drag data used for airport performance analyses reported herein have been increased to account for this effect.

3.3.2 Airfield Performance

Figures 47 and 48 show the takeoff and landing distances for the C-5/Orbiter Piggyback at varying gross weights. These data represent standard C-5 takeoff and land distances increased slightly to account for drag due to the Orbiter. Runway conditions for an airfield pressure altitude of 2000 feet and standard-day temperatures have been used for these as well as all other airfield performance data presented. Ĺ

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Takeoff flap setting for the C-5A is 16 degrees with a takeoff speed of 1.2 VSTALL.

For a long-range ferry mission takeoff gross weight of 700,000 pounds, takeoff ground roll is seen to be 7230 feet with a total distance of 8640 feet to clear a 50-foot obstacle. Engine-out climb capability of the C-5 Piggyback configuration may restrict operations at these conditions such that increased takeoff speeds and distances may be required. However, operation from airfields with runway lengths of 10,000 feet should not be prohibited.

Landing flaps for the C-5A are set at 40 degrees and approach speeds are normally $1.3 V_{STALL}$. For an aborted mission after takeoff at 700,000 pounds, a landing ground roll of 3250 feet is indicated by Figure 48. Normal ferry mission landing weights would be approximately 550,000 pounds, for which a landing ground roll of 2200 feet and total landing distance from a 50-foot obstacle of 3580 feet would be expected.

3.3.3 Climb and Cruise Performance

One-engine-inoperative climb gradients for the C-5 Piggyback at several takeoff speeds and with the landing gear retracted are shown in Figure 49 for standard-day, 2000foot pressure altitude conditions. Since Piggyback climb gradients are reduced relative to those of the basic C-5A, consideration has been given to increasing the takeoff speeds to improve climbout performance. As can be seen, an increase from 1.2 V_{STALL} to 1.3 V_{STALL} increases the gradient by about 0.35 percent, or for a constant climb gradient, the takeoff weight is increased by about 23,000 pounds. This amounts to approximately a 10 percent increase in fuel for long-range ferry missions.

Cruise ceilings for the C-5 Piggyback are shown in Figure 50 for several rates of climb. Long-range cruise performance calculated for the ferry mission is based on the altitudes for the 300-feet-per-minute ceiling shown for normal rated thrust (NRT). The cruise ceilings with military rated thrust (MRT) are useful for determining maximum speed-altitude capability of the C-5 Piggyback.

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₹. 2 Figure 51 summarizes the speed-altitude capability at MRT of the Piggyback for weights corresponding to both an empty and fully loaded Orbiter. Also shown are data for the case of an Orbiter configuration without an afterbody fairing. At 25,000 feet, the maximum speed attainable is 259 KEAS with a faired afterbody, fully loaded Orbiter and 266.5 KEAS with an empty Orbiter.

3.3.4 Orbiter Ferry Capability

Figure 52 summarizes the capability of the C-5A to ferry the Orbiter in the Piggyback mode as a function of military critical field length and takeoff ground roll. These data are shown for takeoff speeds of 1.2, 1.25 and 1.3 times the stall speed and for three values of one-engine inoperative climb gradient. A climb gradient of 2.3% is the current minimum allowable gradient for the C-5A. Reducing the climb gradient to 1.8% improves the range by 240 miles while increasing takeoff distance by less than 1000 feet. Similarly, increasing takeoff speed from 1.2 to 1.3 V_{STALL} increases range by 160 miles but increases takeoff distance by 2500 feet.

For a special-purpose airplane it appears quite reasonable to accept lower climb gradients as a means of increasing range, provided there are no obstacles in the takeoff path. Alternately, it is not necessary to resort to lower climb gradients, since the C-5A's inflight refueling capabilities make its range essentially unlimited.

3.4 FLIGHT RESTRICTIONS

Flight restrictions for the Piggyback are summarized in Figure 53 for two configurations, the C-5 with and without tail modifications. As discussed previously in subsection 3.2, ferry flight without any extension modifications to the C-5 tail can be accomplished with reliance on automatic flight controls, and flight restrictions listed here are given only as a matter of interest.

These restrictions have been established such that no structural modification to the C-5A is necessary other than that required to mount the Orbiter. The "fuselage fuel"

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included in the weights breakdown represents an amount of ballast required for the Orbiter mounted in the aft position. This position in 10 feet aft relative to the baseline location, and the ballast is required to bring the c.g. within the current aft limit of the C-5A. The operating weights shown include the weight of the fuselage fuel tank.

Flight restrictions for the C-5/Orbiter Piggyback are compared with those of the Super Guppy in Figure 54. As can be seen, they are quite comparable. The only condition in which the C-5A is restricted more than the Super Guppy is in touchdown rate of sink. This is insignificant, since the design weights can be lowered somewhat and still allow the ferry-range performance shown in subsection 3.3.4. Design speeds and gust weights are naturally considerably greater for the C-5A as represented by the 300 KCAS level-flight maximum speed for the C-5A/Orbiter Piggyback, compared with 219 KCAS for the Super Guppy, and a maximum gross weight of 865,000 pounds for the Piggyback compared with 162,000 pounds for the Super Guppy. Maneuver-load factors for cruise are about the same: 2.0 for the Piggyback and 2.2 for the Super Guppy.



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4.0 CONCLUSIONS AND RECOMMENDATIONS

Wind tunnel testing of the C-5A/Orbiter Piggyback configuration has demonstrated that the major effect of the Orbiter on the aerodynamics of the C-5A is a loss of directional stability due primarily to airflow losses at the vertical tail, and to an increase in overall side area and side forces. The effects of the Orbiter on longitudinal stability are almost negligible as evidenced by a C_{m_0} shift due to the Orbiter equivalent to less than one degree of horizontal stabilizer incidence. The effect on drag, as expected, is significant, but the drag level of the Piggyback configuration can be reduced to a level about 40% above C-5A cruise configuration drag with an Orbiter afterbody fairing. Interference effects from a drag standpoint appear from the test results to be insignificant for the ferry cruise configuration.

Variations in Orbiter longitudinal and vertical locations showed that the aft high position was the best, primarily because the losses in directional stability were minimized by moving the side areas aft of the reference c.g. The effects of varying the Orbiter incidence relative to the C-5A were, from any viewpoint, inconsequential for the range tested (-1.5° and 0.5°). A Lockheed-Georgia afterbody designed for the Orbiter to improve the flow at the empennage and the directional stability proved insufficient, although a slight drag reduction was noticed for the Lockheed-Georgia fairing.

During the wind tunnel test, several empennage modifications were designed and tested to remedy the directional stability problems. These modifications included a control fin addition above the present horizontal stabilizer, and twin fin additions to the horizontal stabilizer tip.

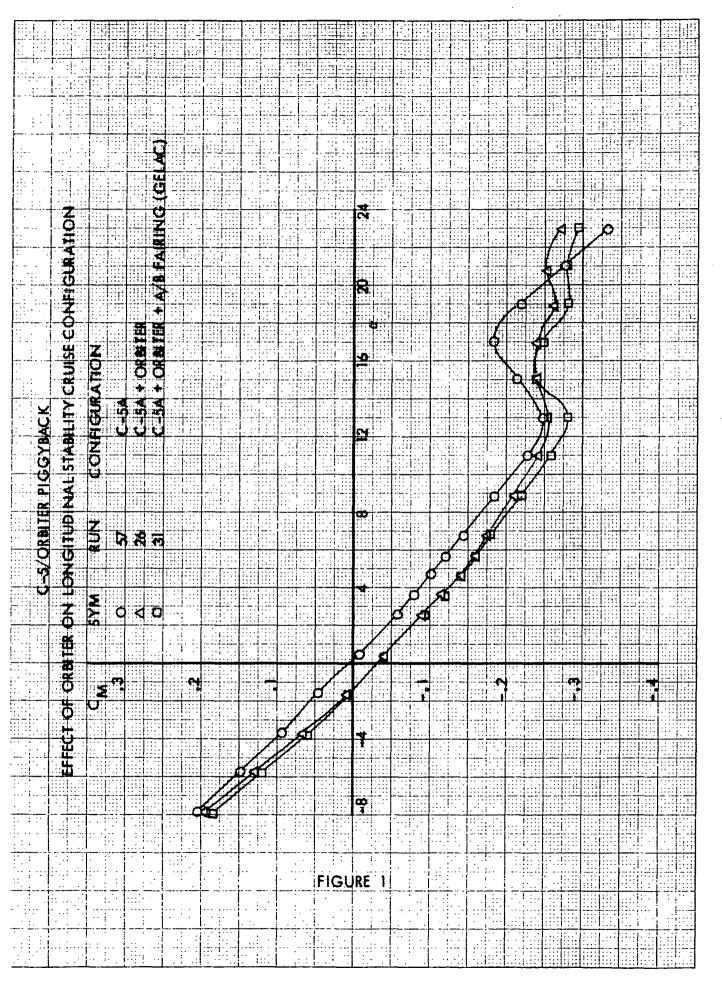
These were successful in restoring the stability level of the Piggyback to that of the basic C-5A so that, if desired, external modifications could be defined that would provide satisfactory flying qualities. Cursory analytical studies indicate that the C-5A automatic controls can be modified to fly the Piggyback configuration in a ferry operation without external modifications and with only minor modifications to the flight control systems.

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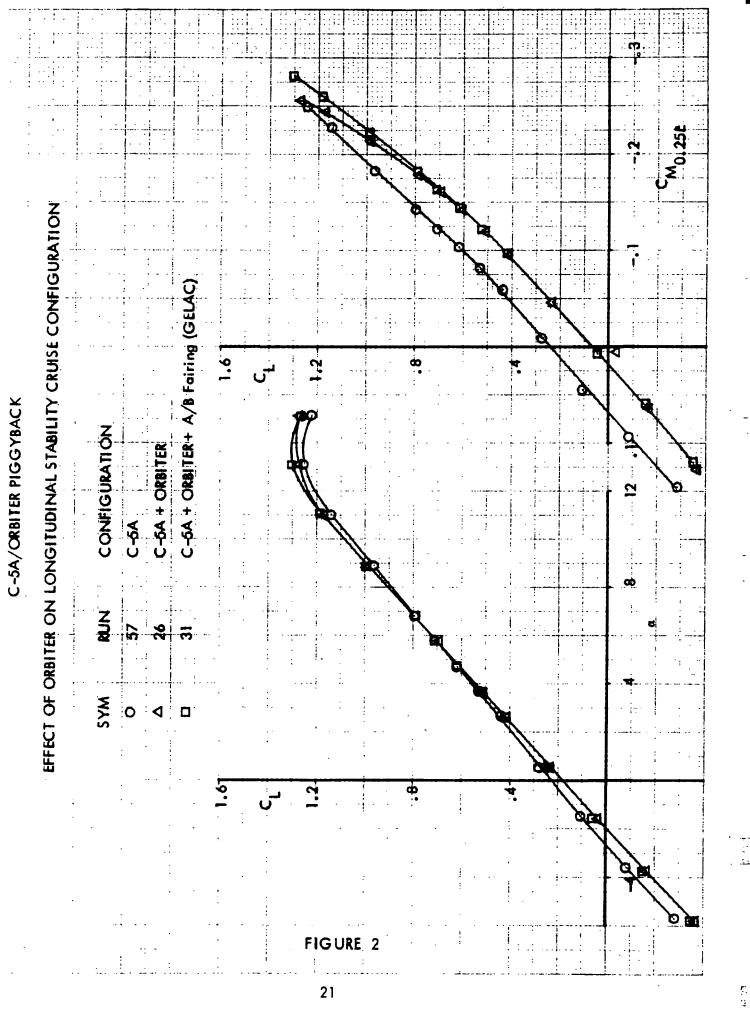
Performance analyses revealed the feasibility of trans-continental unrefueled distances for the C-5A ferrying the Shuttle Orbiter. Airfield performance assures operation from fields of less than 10,000 feet where minimum takeoff climbout gradients can be tolerated. In total, the feasibility of the C-5A/Orbiter Piggyback ferry concept appears excellent and the following recommendations are respectfully submitted:

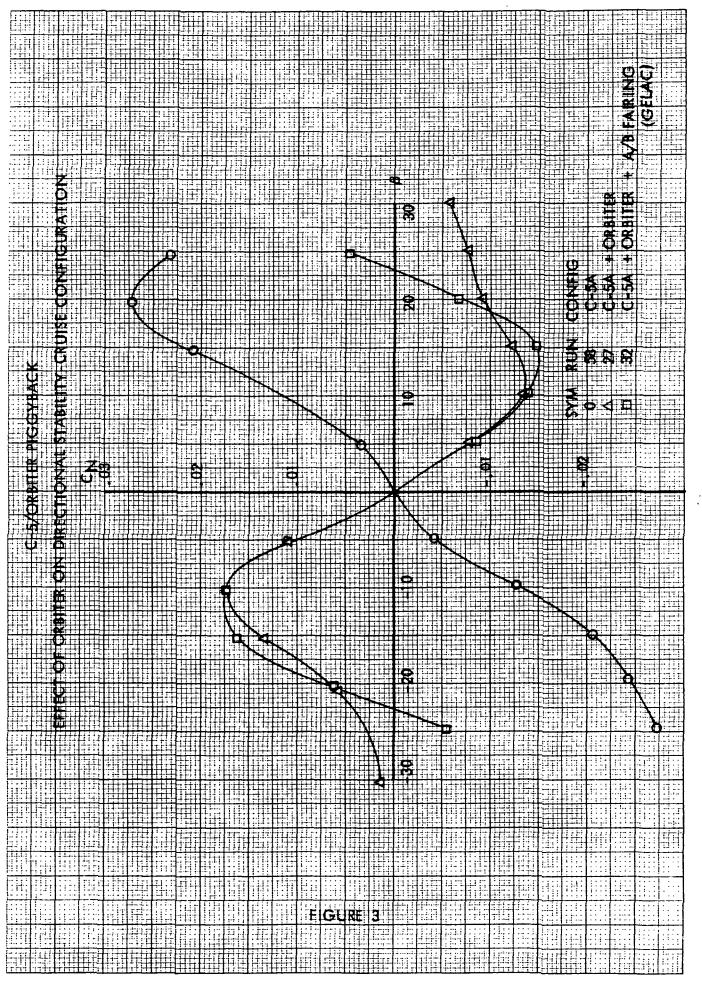
- o Development of the C-5A ferry vehicle should be initiated as soon as possible.
- o A wind tunnel test program of the airlaunch configuration should be initiated.
- o Studies of airlaunch concepts and separation trajectory analyses should be made in conjunction with the wind tunnel program.
- More detailed, flying-qualities studies of the C-5/Orbiter Piggyback configuration should be conducted to identify potential modifications of the C-5A automatic flight control systems.

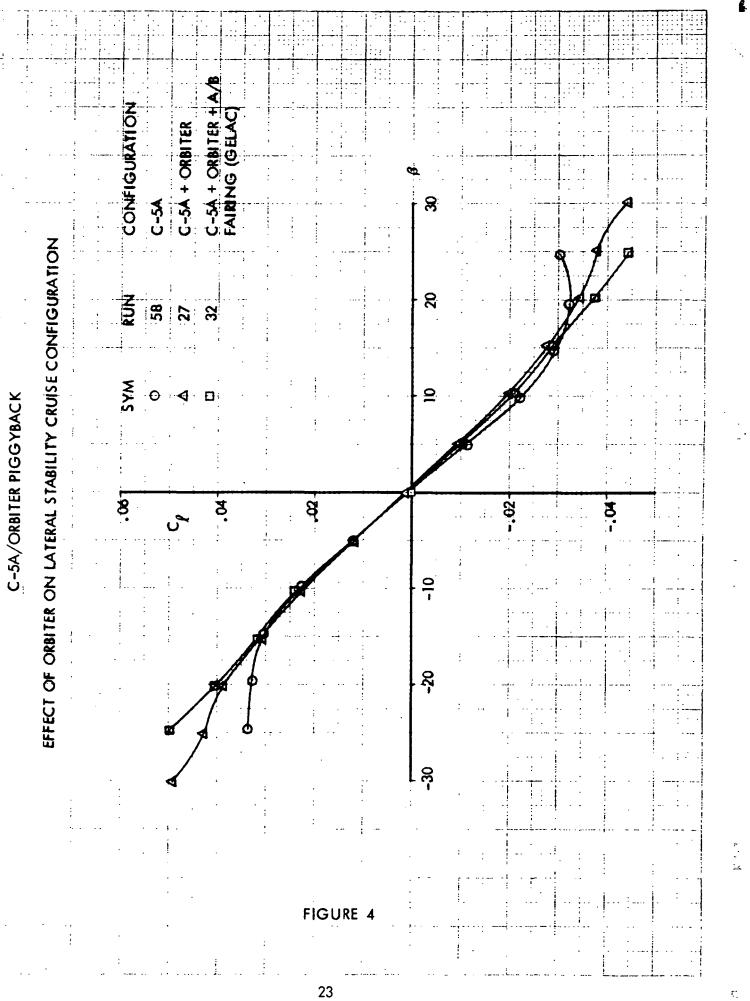
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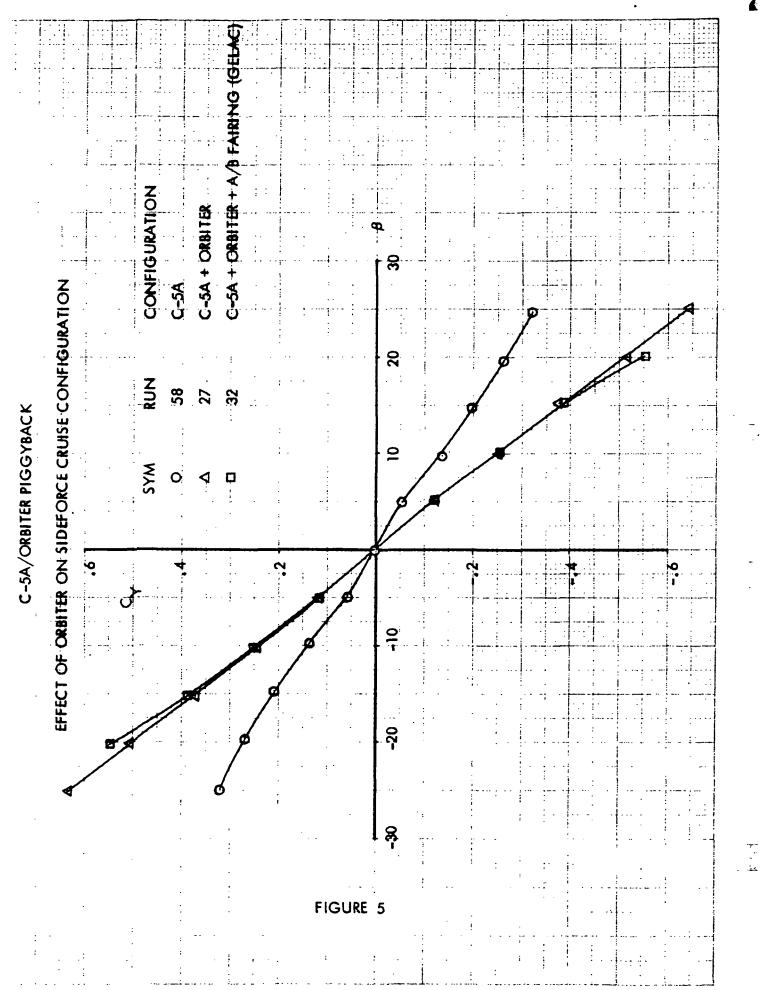
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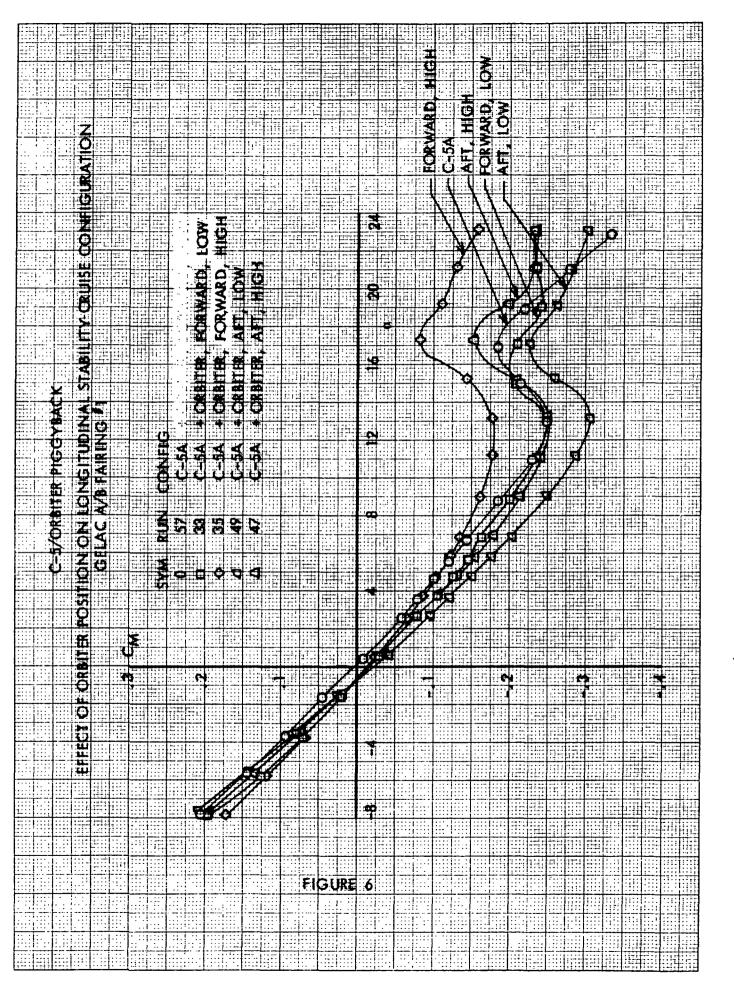




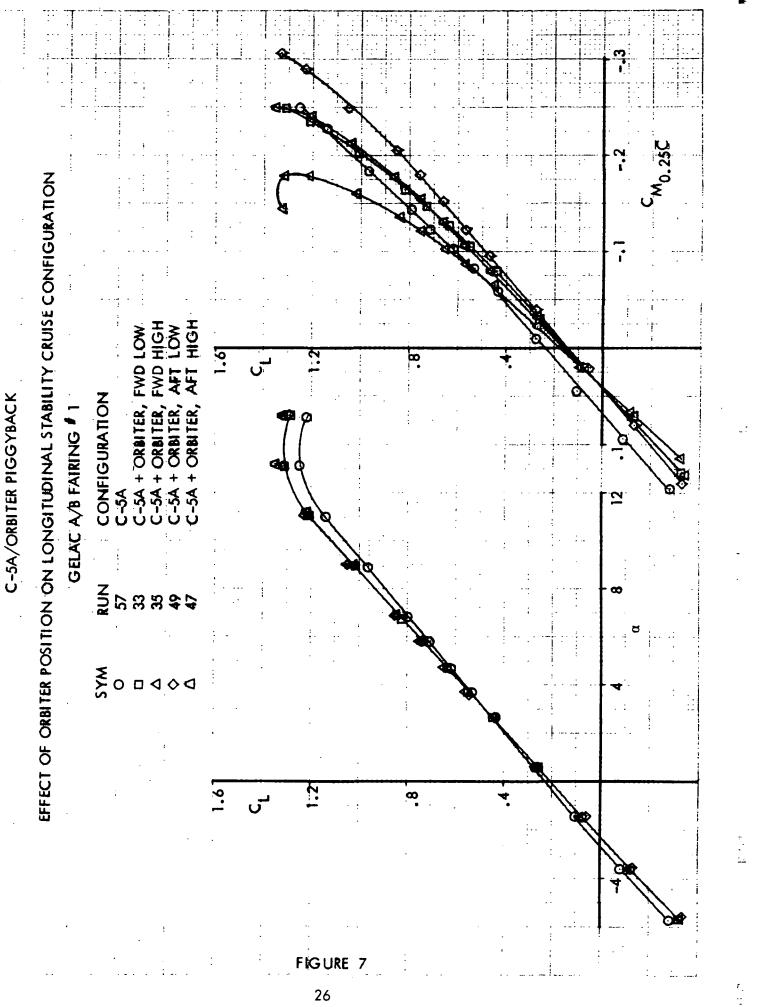
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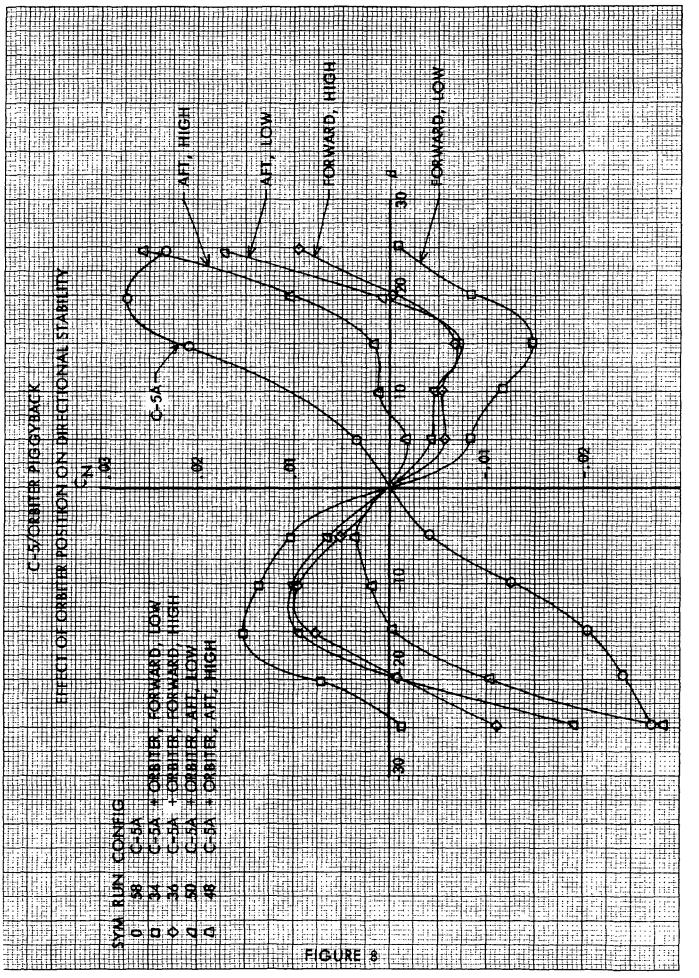


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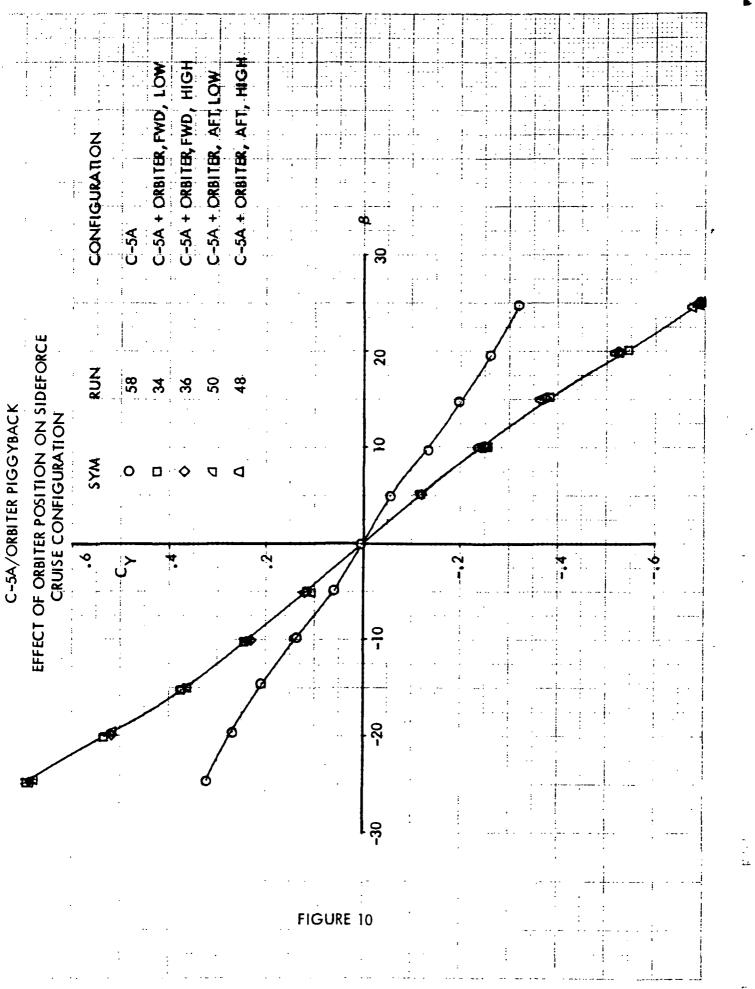
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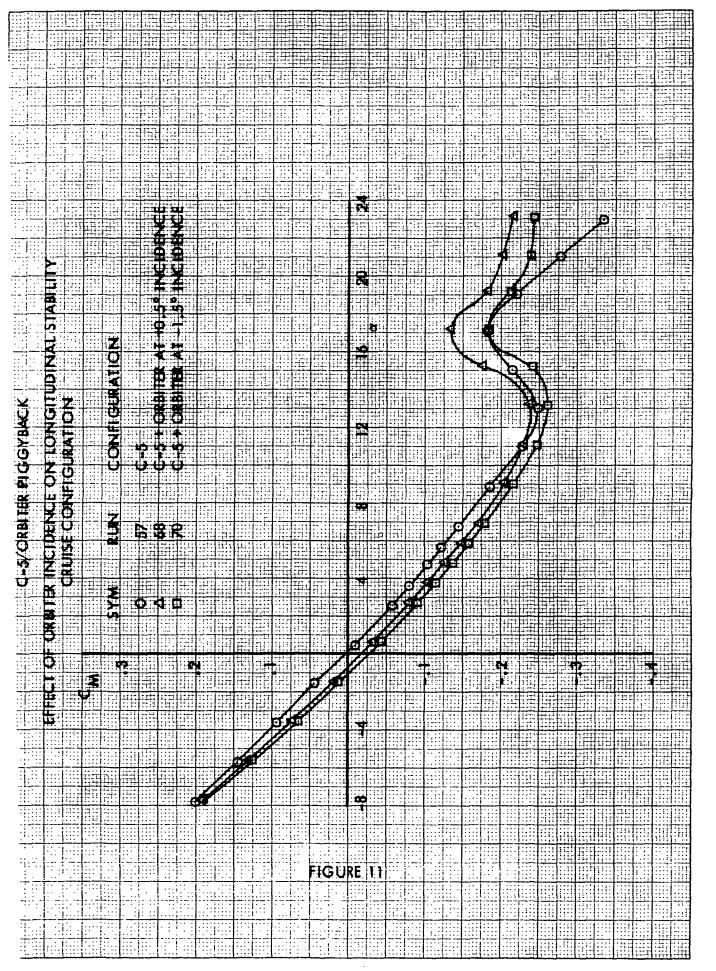
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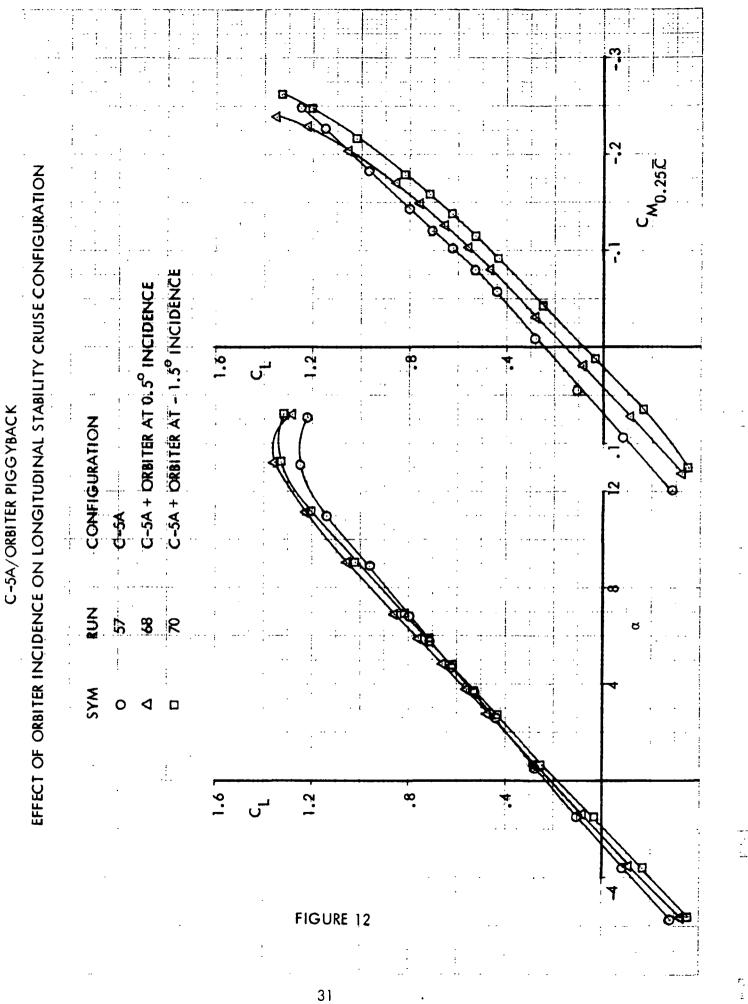


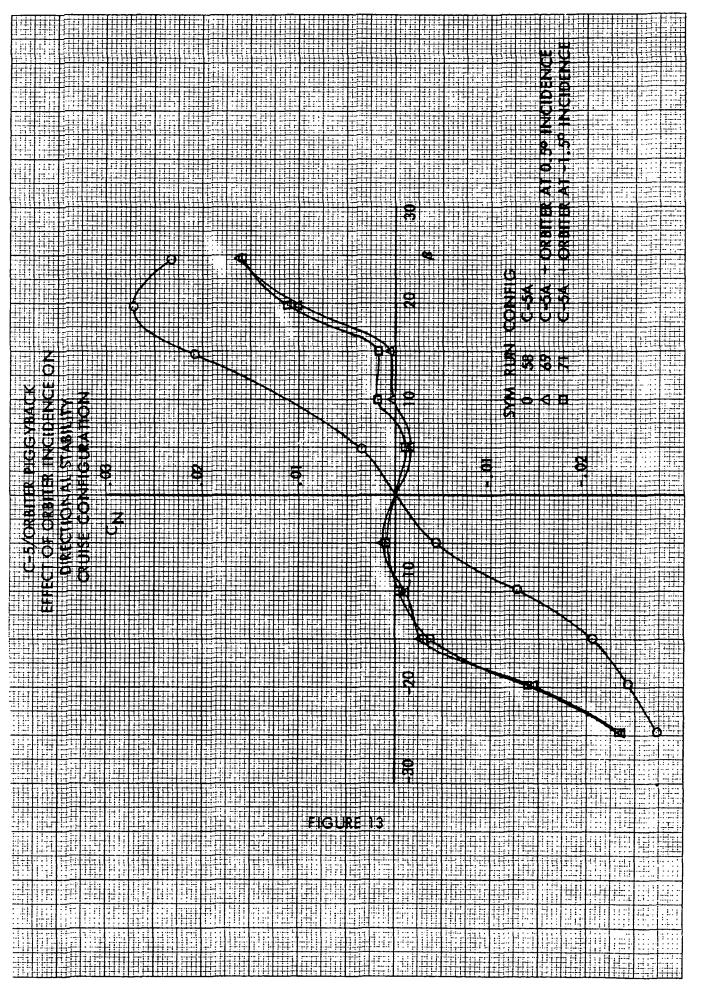
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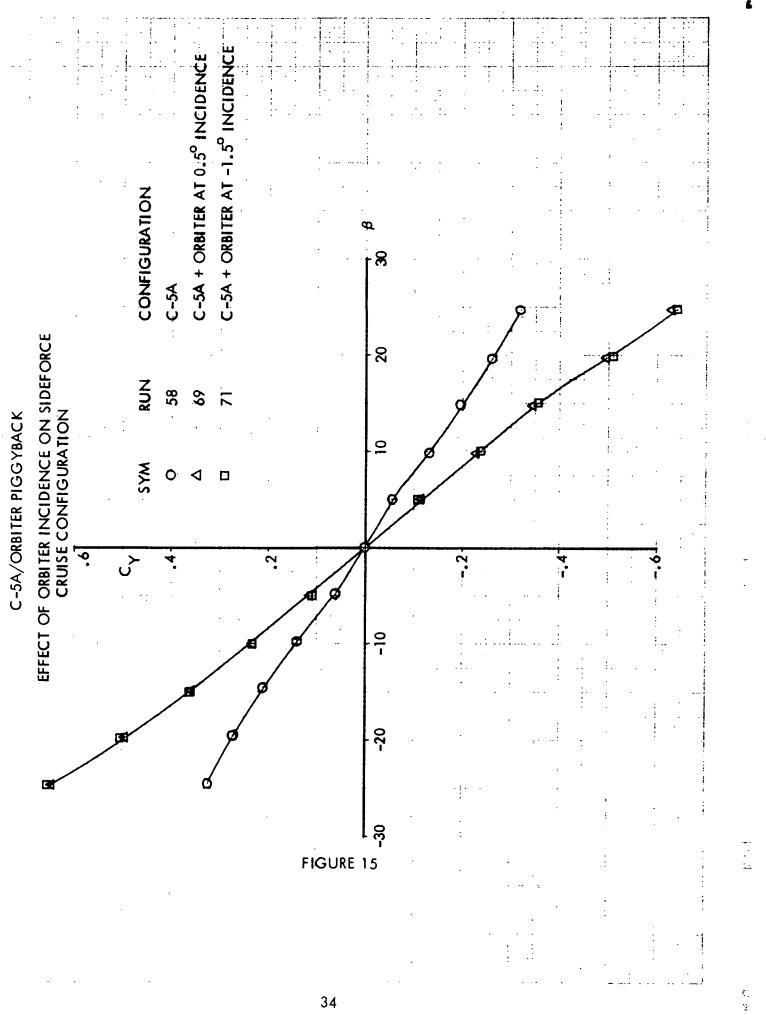


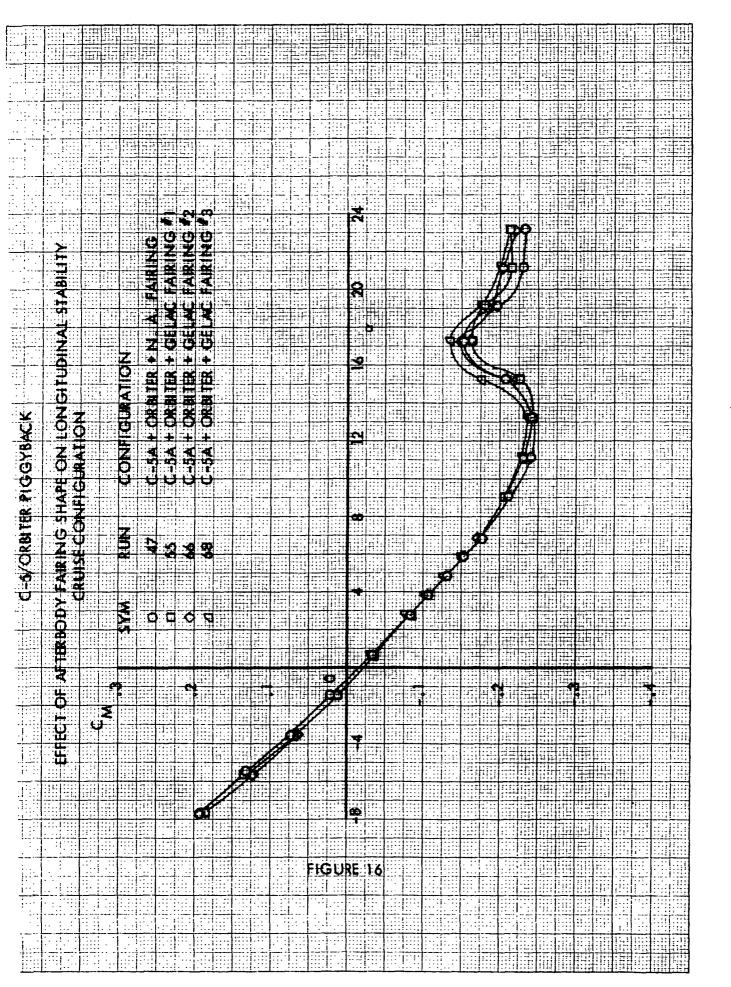
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C-5A/ORBITER PIGGYBACK

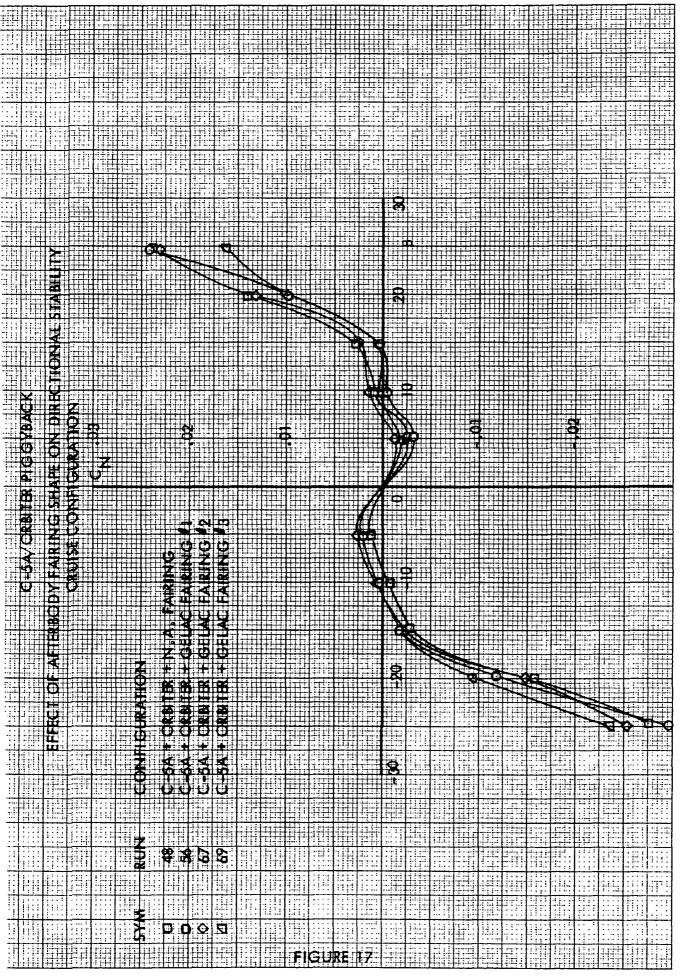
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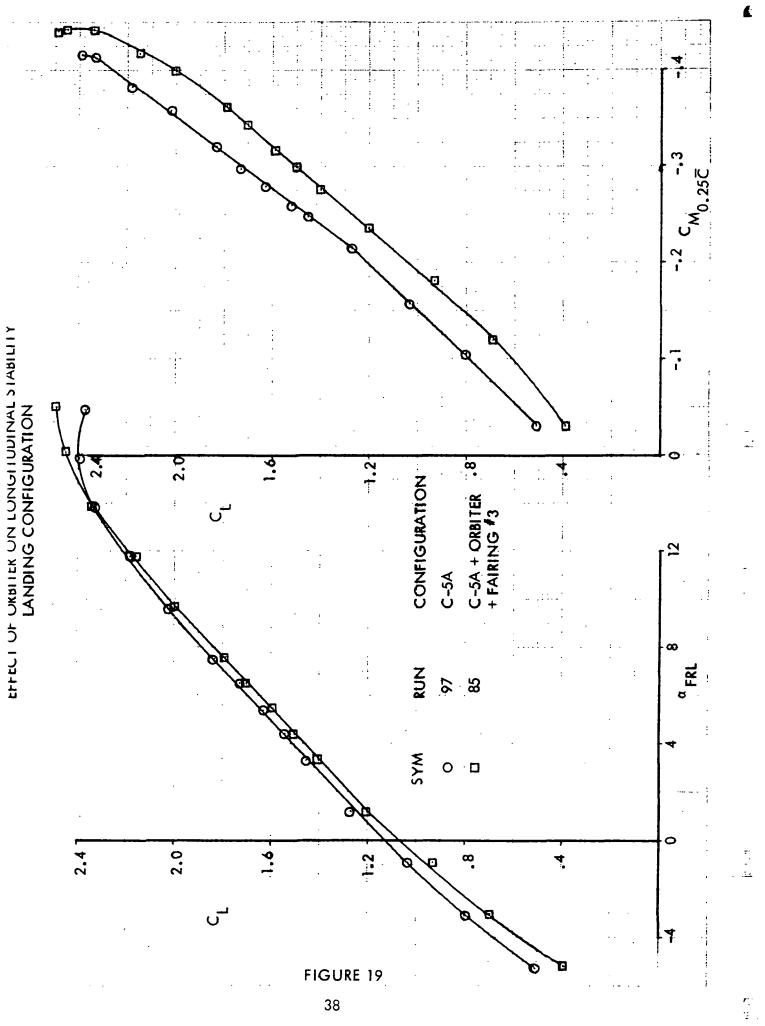
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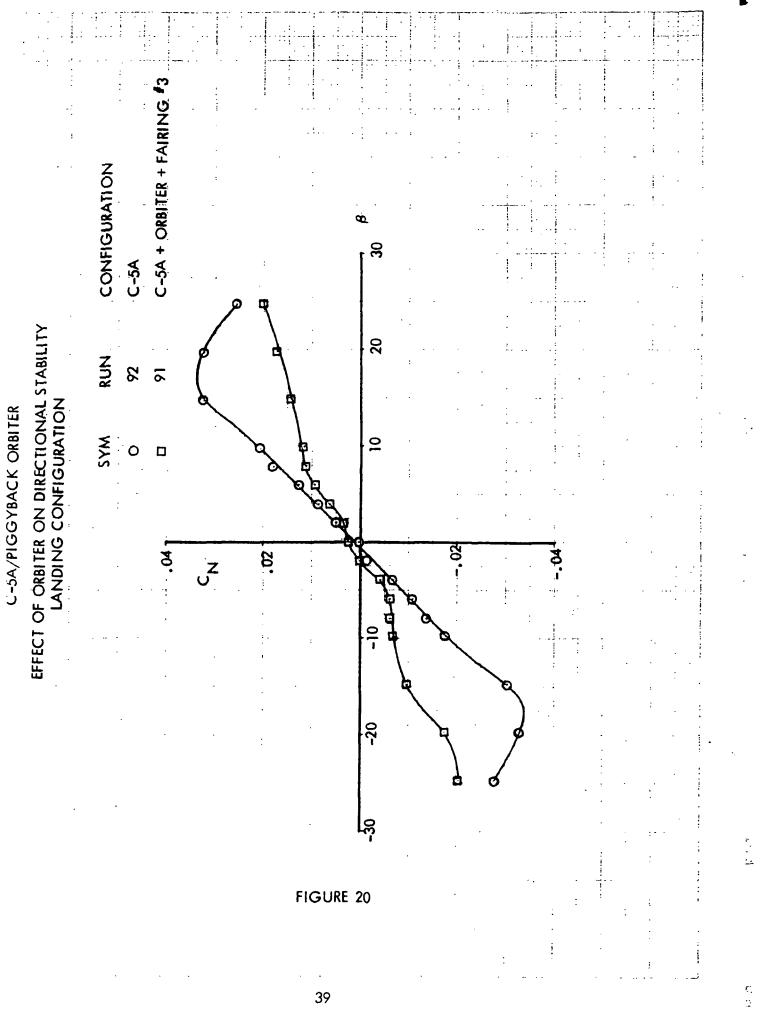
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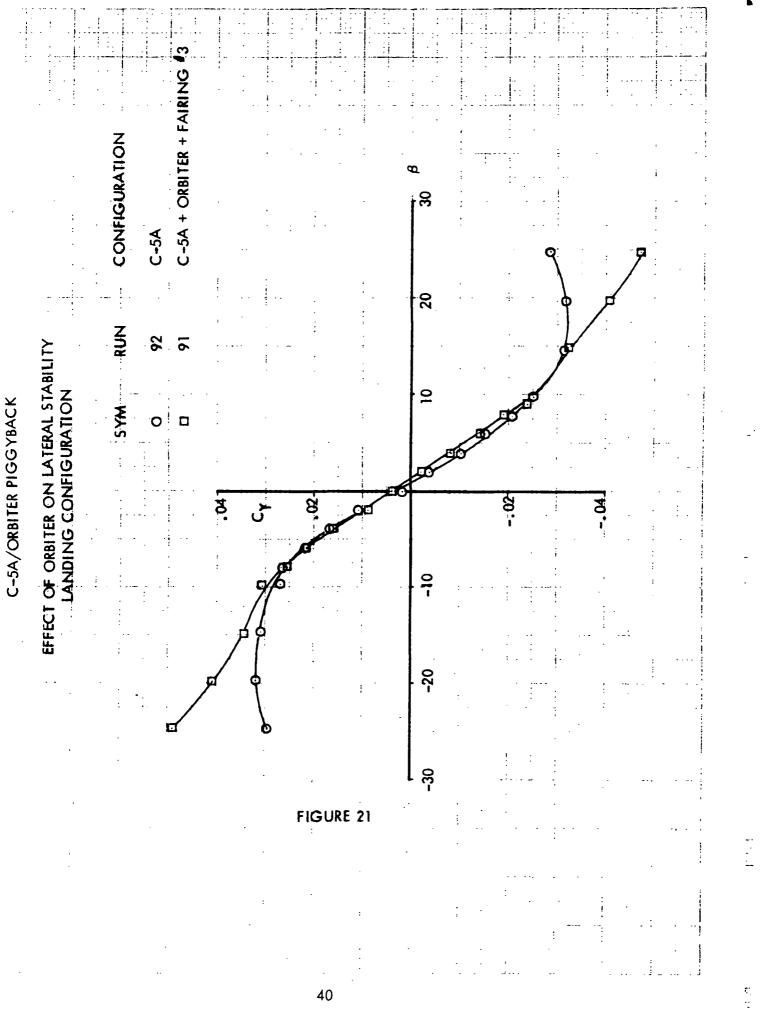
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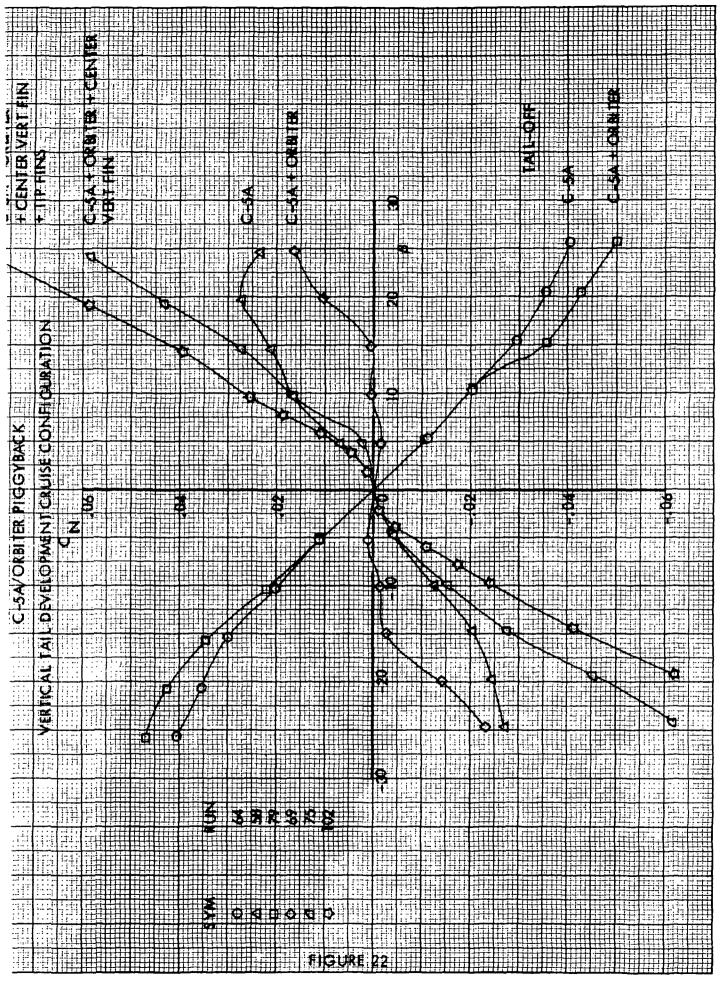
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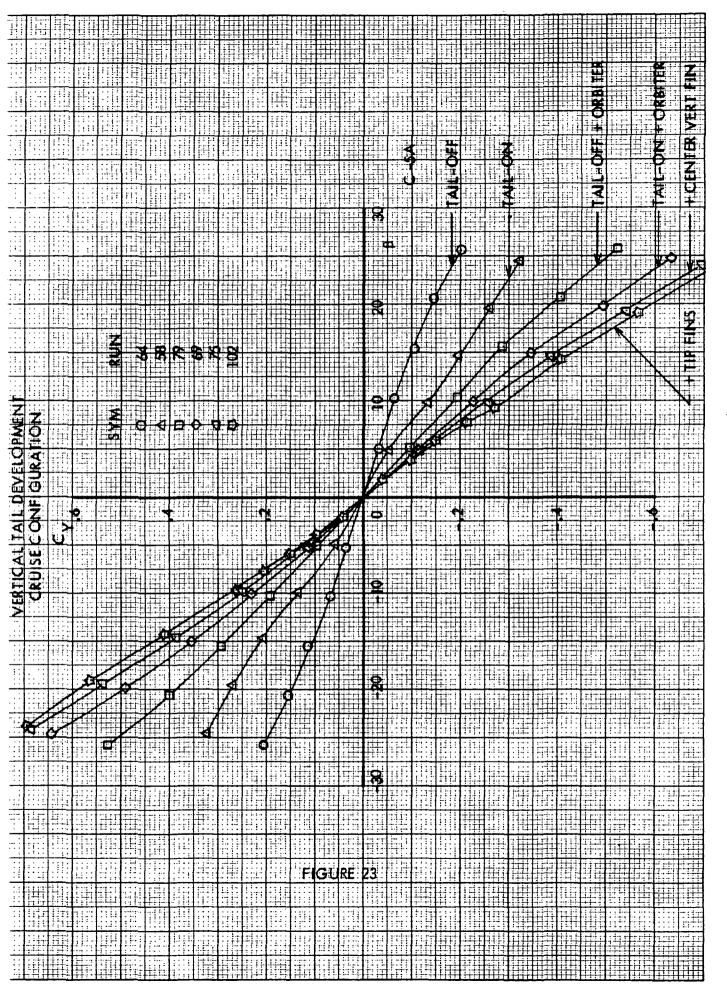
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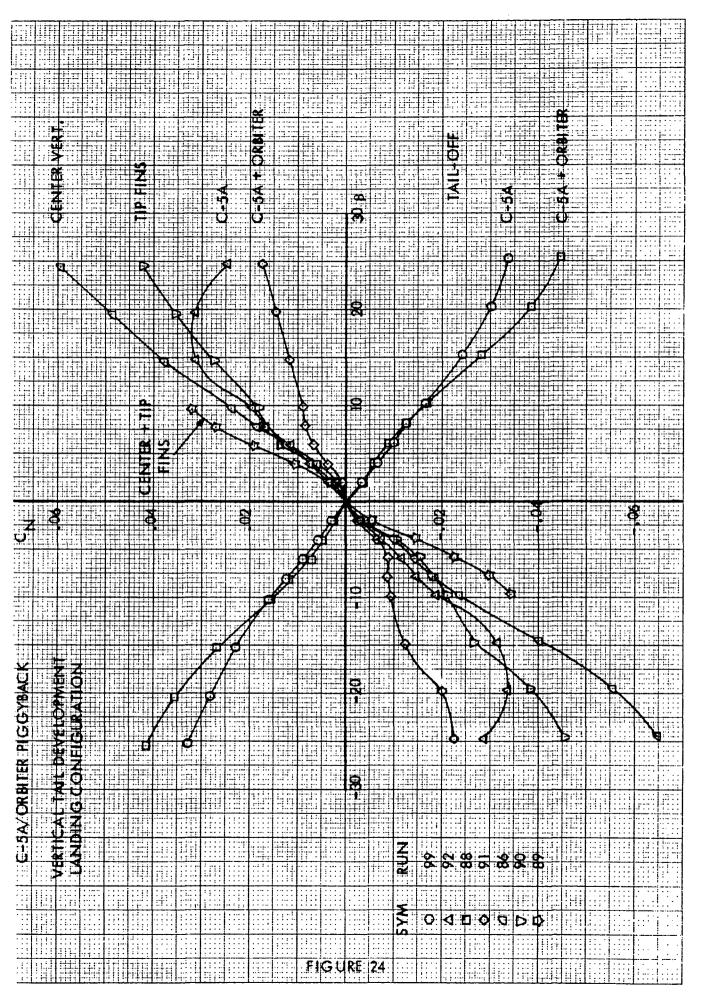


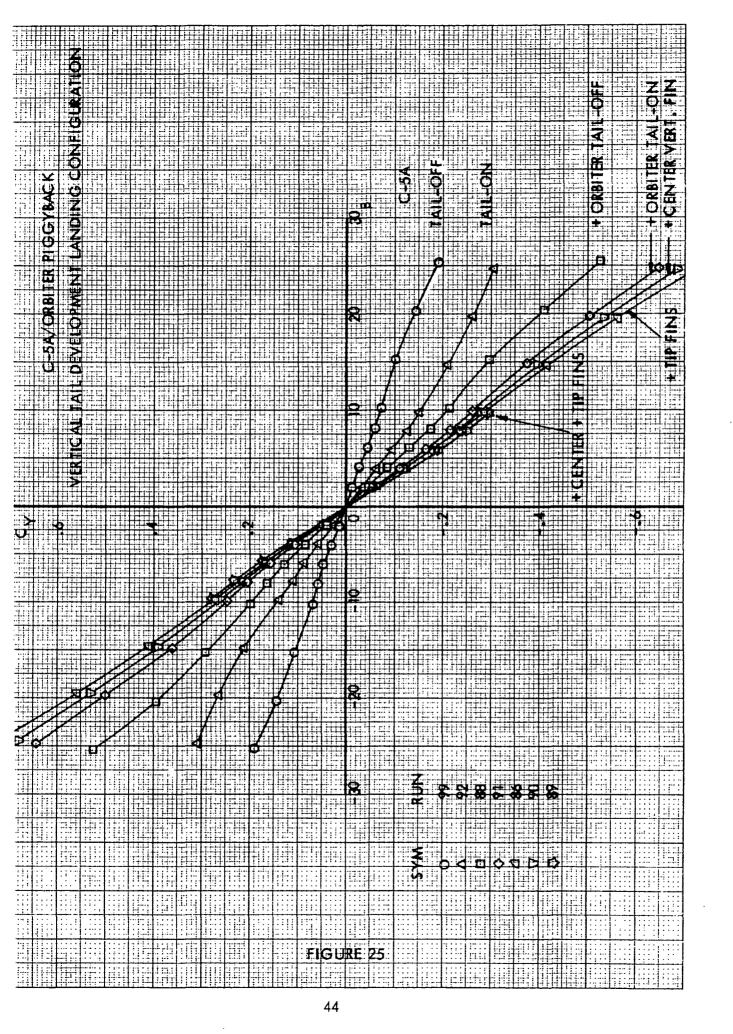


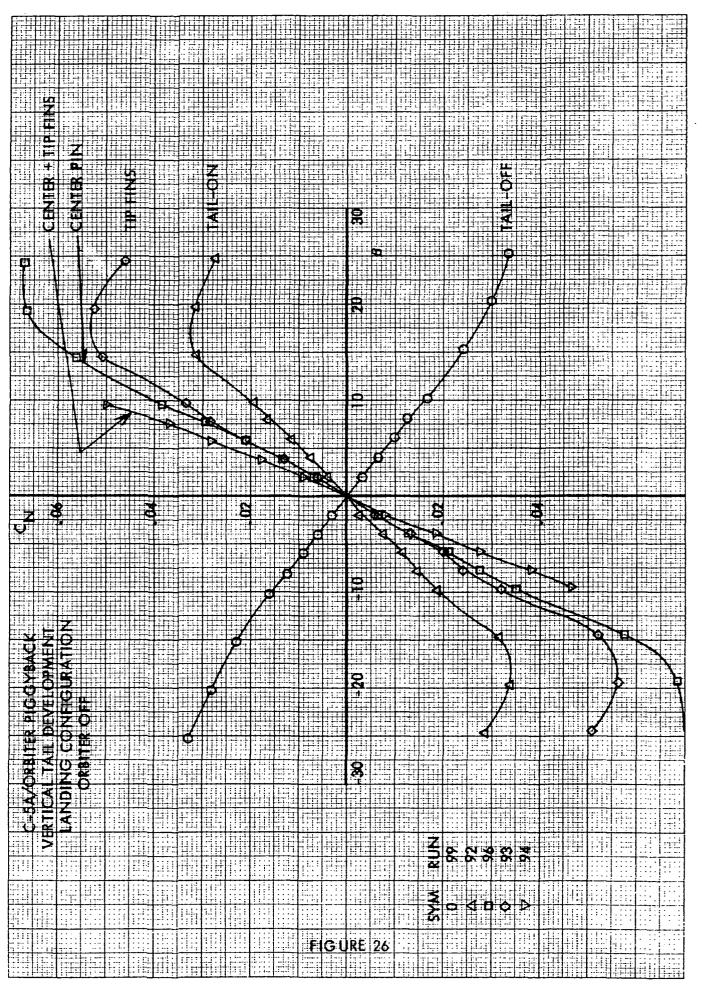


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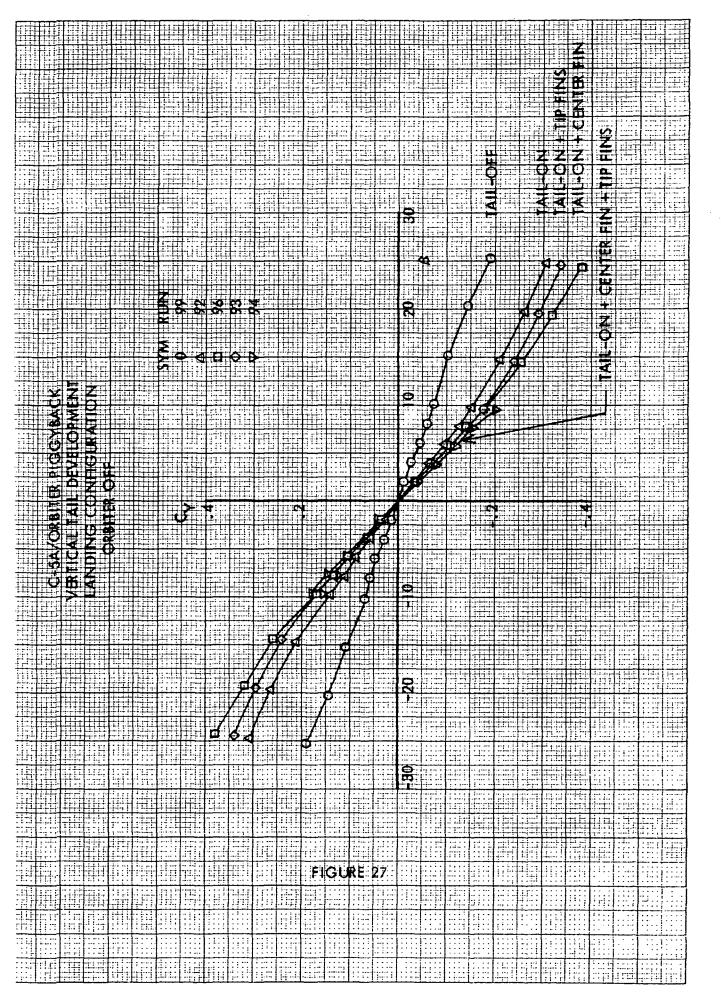


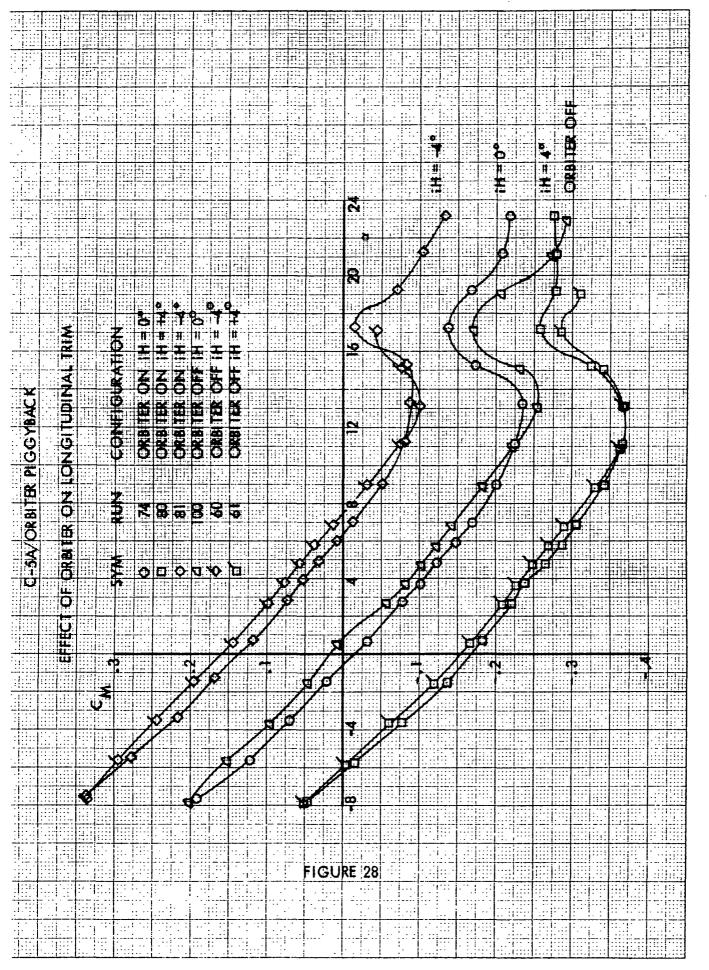




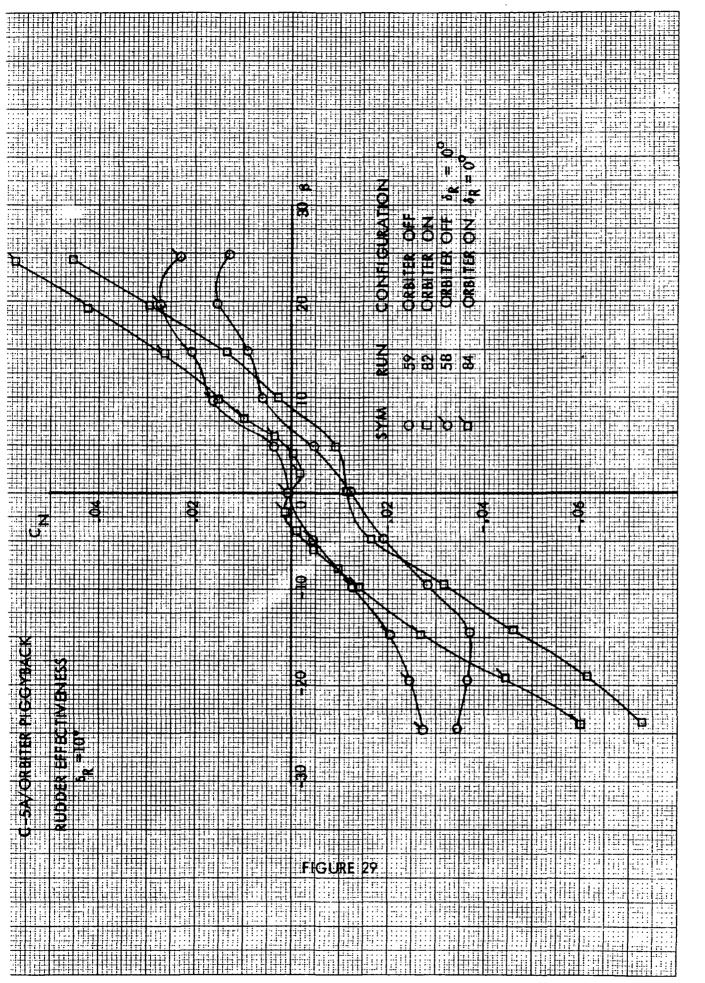
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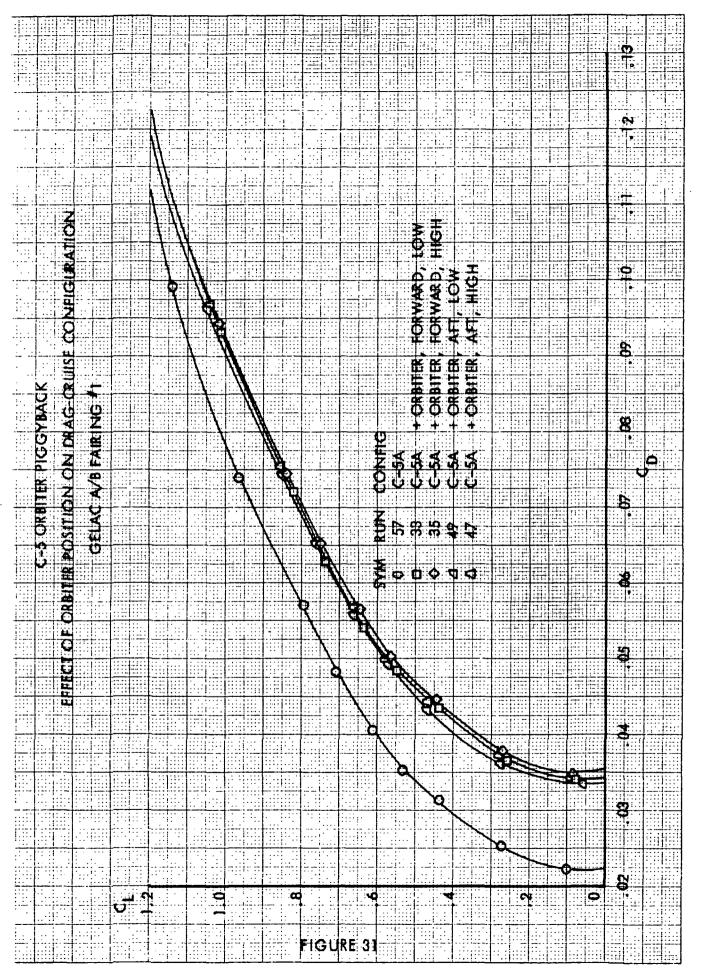
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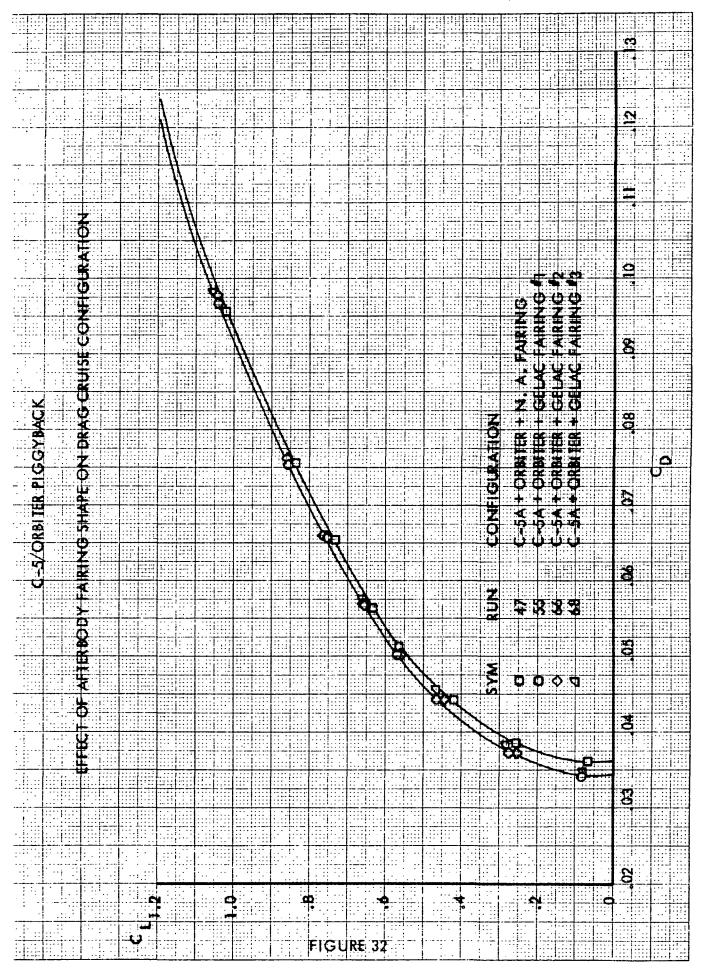
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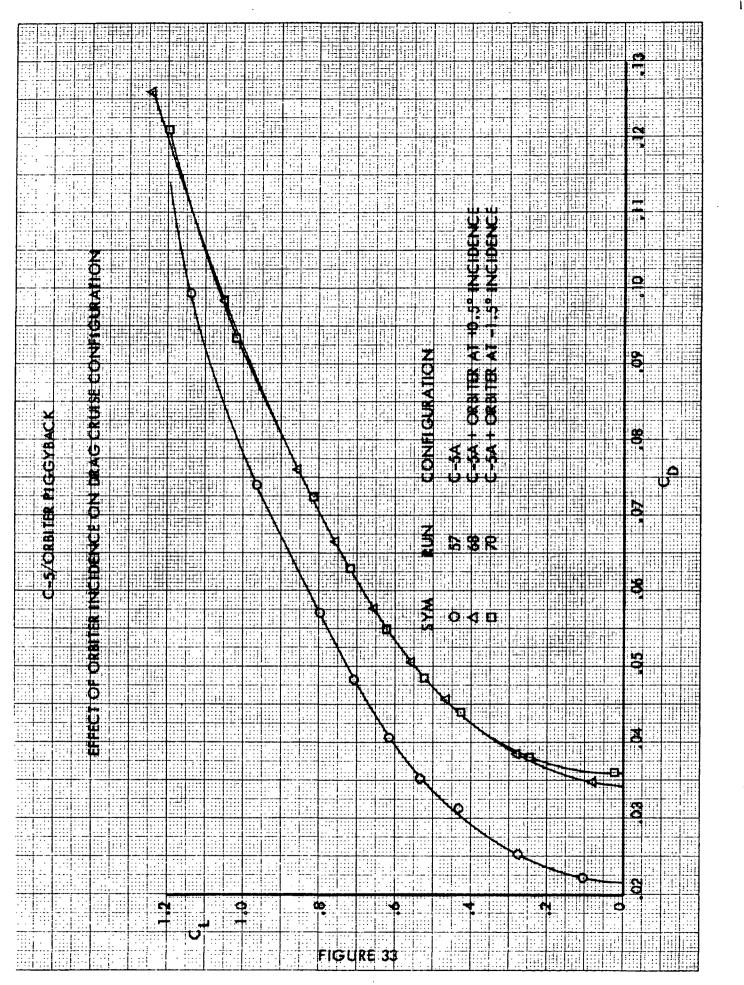


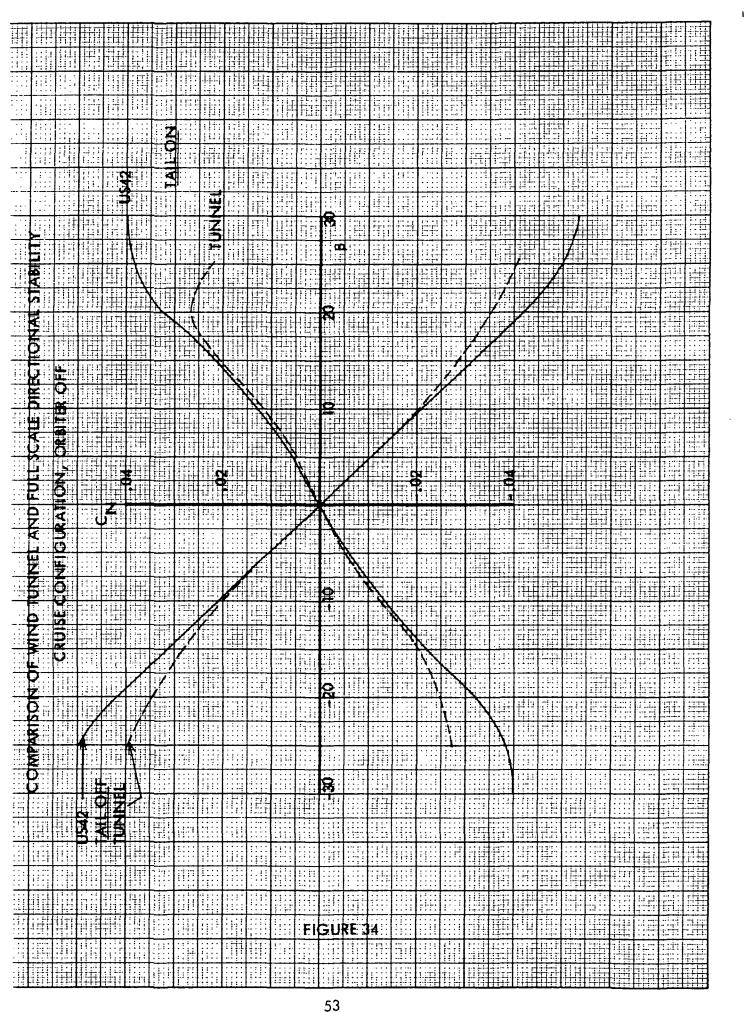
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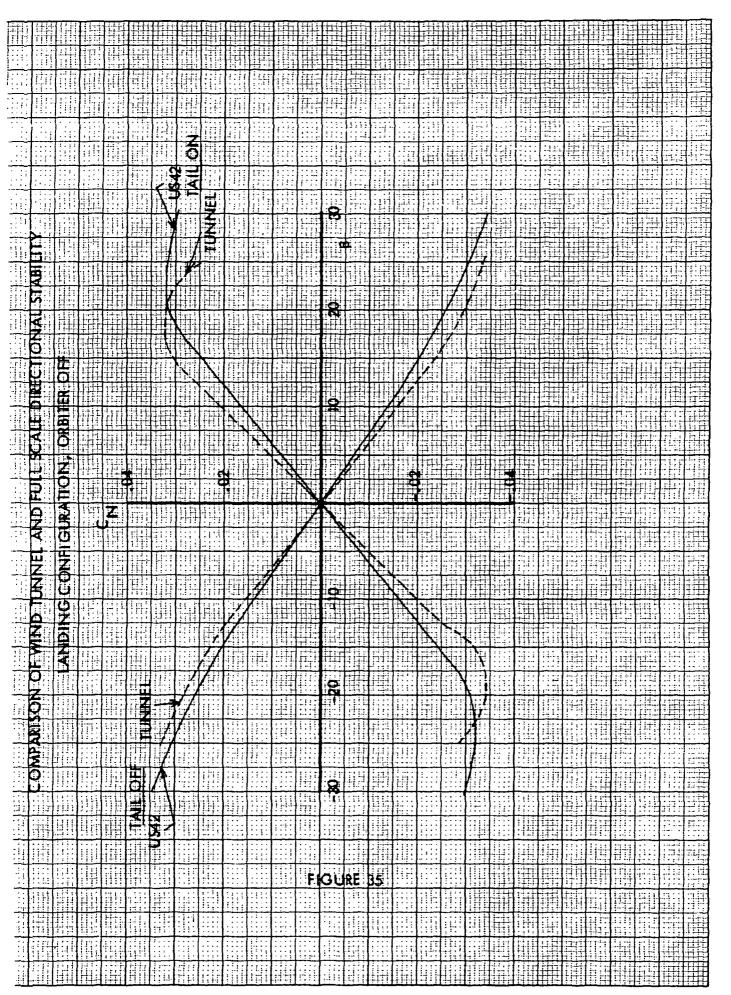
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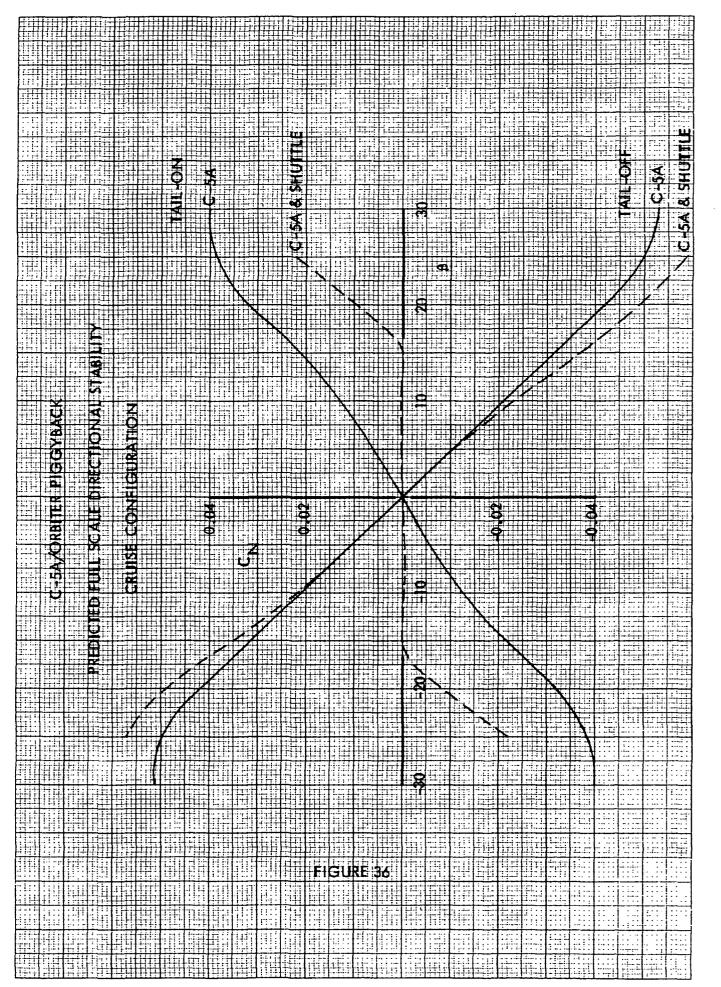
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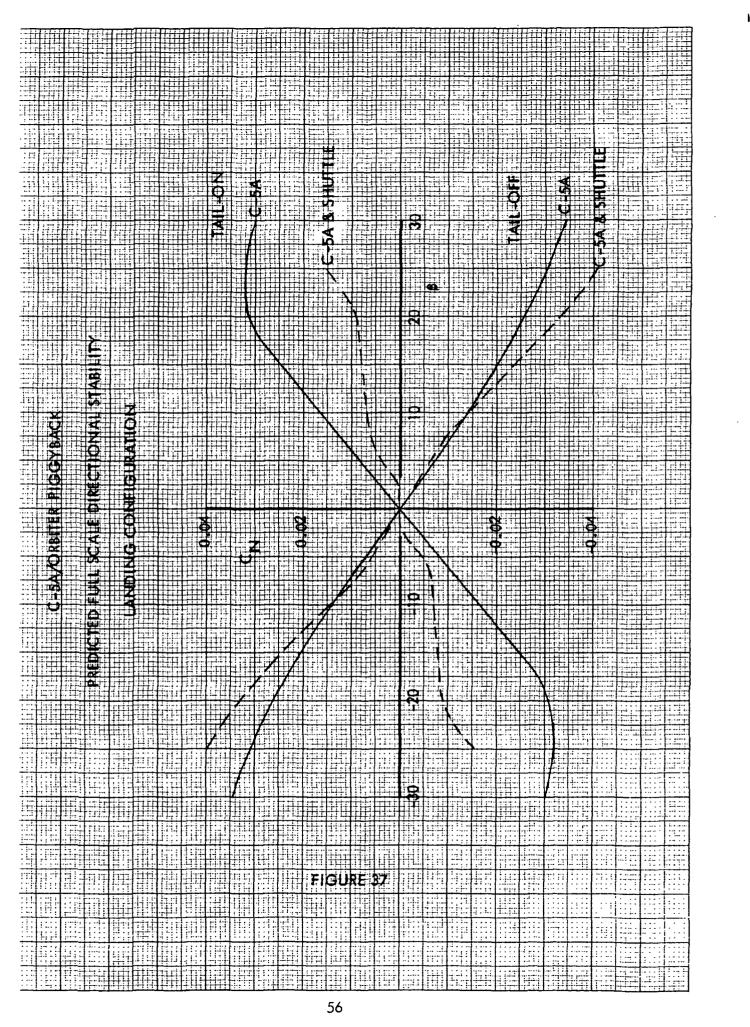


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C-5A/ORBITER PIGGYBACK FLIGHT VEHICLE DATA

M = 0.52 @ 20,000 ft Wing area, S = 6200 ft² V_T = 319 KTAS Wing span, b = 219 ft

Wing area, $5 = 6200$ ff	Wing span, b - 219 ff									
LIGHT CASE	#]	#2	#3							
eight ~lbs	550,000	704,626	704,626							
- slugs ft ² x 10 ⁻⁶	3.43	3.45	3.89							
~ slugs ft ² x 10 ⁻⁶	5.48	6.07	6.11							
~ slugs ft ² x 10 ⁻⁶	2.20	2.42	3.97							
Stability and	Control Derivatives		J							
$C_{y_o} \sim /rad.$	802	802	-1.34							
$C_{l_{\beta}} \sim /rad.$	0771	0997	0997							
$C_{n_{\beta}} \sim /rad.$.0728	.0728	0							
	390	390	390							
C ~/rad.	081	081	081							
$C_{y_{-}}^{p}$ ~/rad.	.510	.500	.500							
$C_{p_r} \sim /rad.$.177	.199	.199							
C _n ~/rad.	180	180	180							
$C_{p} \sim / rad.$	0319	0319	0319							
C ~/rad. δ_	0	0	0							
$C_{y} \sim /rad.$.2006	.2006	.2006							
$C_{l_{\delta_{1}}} \sim /rad.$.0210	.0181	.0181							
	1031	1031	1031							
	0573	0573	0573							
$C_{l_{\delta}} \sim /rad.$.0268	.0268	.0268							
	.0057	.0057	.0057							
۱ <u>ـــــ</u>	FIGURE 38 57		<u> </u>							
	LIGHT CASE =ight ~lbs $r slugs ft^2 \times 10^{-6}$ $r slugs ft^2 \times 10^{-6}$ $r slugs ft^2 \times 10^{-6}$ $r slugs ft^2 \times 10^{-6}$ $r slugs ft^2 \times 10^{-6}$ r stability and $C_{\gamma_{\beta}} \sim /rad.$ $C_{\beta} \sim /rad.$ $C_{\beta} \sim /rad.$ $C_{\beta} \sim /rad.$ $C_{\gamma} \sim /rad.$ $C_{\gamma} \sim /rad.$ $C_{\gamma} \sim /rad.$ $C_{\gamma} \sim /rad.$ $C_{\gamma} \sim /rad.$ r $C_{\gamma} \sim /rad.$ r $C_{\gamma} \sim /rad.$ δ_{α} $C_{\gamma} \sim /rad.$ δ_{α} $C_{\gamma} \sim /rad.$ δ_{α} $C_{\gamma} \sim /rad.$ δ_{γ} r $C_{\gamma} \sim /rad.$ δ_{γ} $C_{\gamma} \sim /rad.$ δ_{γ} C_{γ} δ_{γ} C_{γ} δ_{γ} C_{γ} δ_{γ} C_{γ} δ_{γ} C_{γ} δ_{γ} C_{γ} δ_{γ} C_{γ} δ_{γ} C_{γ} δ_{γ} C_{γ} δ_{γ} C_{γ} δ_{γ} C_{γ} δ_{γ} δ_{γ} C_{γ} δ_{γ} δ_{γ} C_{γ} δ_{γ} δ_{γ} C_{γ} δ_{γ} δ_{γ} C_{γ} δ_{γ} $\delta_$	$\begin{array}{c c c c c c c c c c c c c c c c c c c $	LIGHT CASE #1 #2 sight ~ lbs 550,000 704,626 s lugs ft ² x 10 ⁻⁶ 3.43 3.45 - slugs ft ² x 10 ⁻⁶ 5.48 6.07 - slugs ft ² x 10 ⁻⁶ 2.20 2.42 Stability and Control Derivatives $C_{\gamma_{\beta}} ~ / rad.$ 0771 0997 $C_{\eta_{\beta}} ~ / rad.$ 0771 0997 $C_{\eta_{\beta}} ~ / rad.$ 0728 .0728 $C_{\gamma_{\beta}} ~ / rad.$ 081 081 $C_{\gamma} ~ / rad.$ 081 081 $C_{\gamma_{r}} ~ / rad.$.177 .199 $C_{\eta_{r}} ~ / rad.$ 0319 0319 $C_{\gamma_{r}} ~ / rad.$ 0319 0319 $C_{\eta_{\delta_{\alpha}}} ~ / rad.$ 0 0 $C_{\eta_{\delta_{\alpha}}} ~ / rad.$ 0.2006 .2006 $C_{\gamma_{\delta_{\alpha}}} ~ / rad.$.0210 .0181 $C_{\eta_{\delta_{\alpha}}} ~ / rad.$.0210 .0181 $C_{\eta_{\delta_{\gamma_{r}}}} ~ / rad.$.0268 .0268 $C_{\gamma_{\delta_{\gamma_{r}}}} ~ / rad.$.0268 .0268 $C_{\eta_{\delta_{\gamma_{r}}}} ~ / rad.$.0268 .0268							

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Characteristic Equation:

$$(s^{2} + 2\zeta_{d}w_{d}s + w_{d}^{2})(s + 1/\tau_{R})(s + 1/\tau_{s}) = 0$$

Item or Parameter	Case #1	Case #2	Case #3		
G.W. (no payload)	550,000#	550,000#	550,000#		
cargo weight	-	154,626#	-		
orbiter weight	-	-	154,626#		
gross weight	550,000#	704,626#	704,626#		
	Dutch Roll Mode		· · · · · · · · · · · · · · · · · · ·		
frequency, w _d - rad/sec	.634	.620	. 344		
damping ratio, 💡 d	.118	.076	023		
period, T _d - secs.	9.98	10.2	18.3		
time to $1/2$ -ampl, $t_{1/2}$ - secs.	9.18	14.6	-89		
cycles 1/2-ampl, C	.92	1.44	-4.9		
	Roll Convergence Moc	le	L No		
time constant, $\tau_{\rm R}$ - secs	1.45	1.42	1.35		
time to $1/2$ -ampl, $t_{1/2}$ - secs	1.0	.98	.93		
	Spiral Mode		I <u></u>		
time constant, τ_s - secs	694	216	15.2		
time to $1/2$ -ampl, $t_{1/2}$ - secs	479	149	10.5		

NOTE: Negative values signify an unstable dutch roll mode.

FIGURE 39

C-5A STABILITY AUGMENTATION &

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AUTOPILOT SYSTEMS APPROXIMATIONS

Stability Augmentation Elements

Aileron: $\delta_{\alpha} = 0.055 (\phi)$

Spoiler: $\delta_s = 0$

Rudder: $\delta_r = -.482(p) - .101(\phi) + 1.0 (r)$

Incremental Elements for Autopilot Operative*

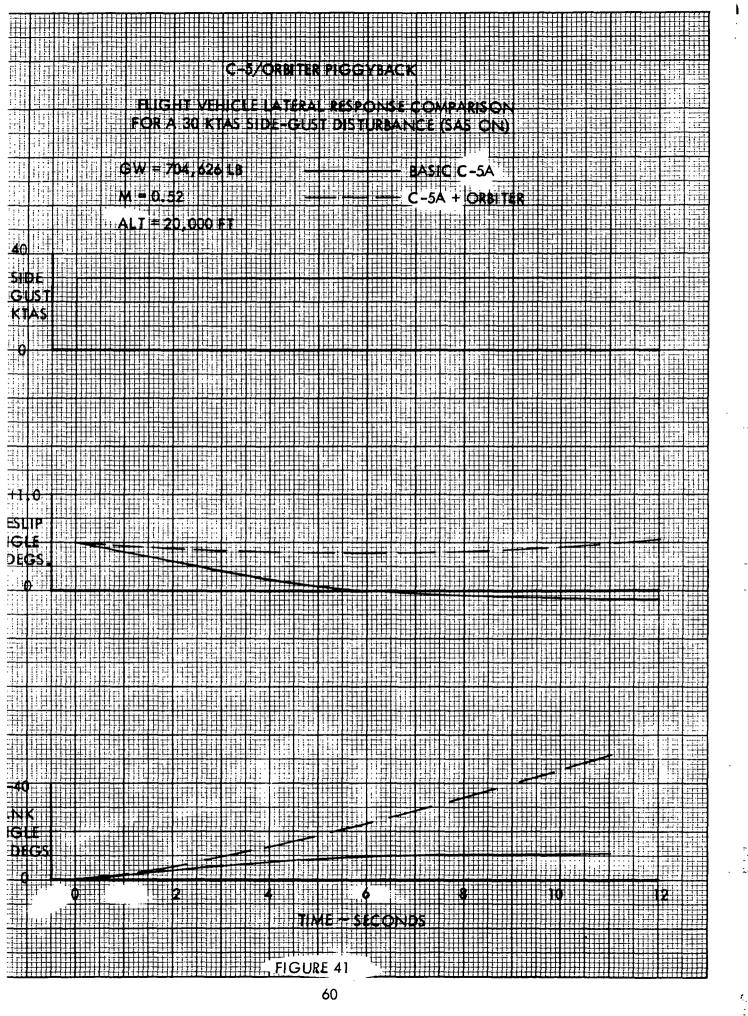
Aileron: $\Delta \delta_{q} = 2.25 (p) + 3.22 (\phi)$

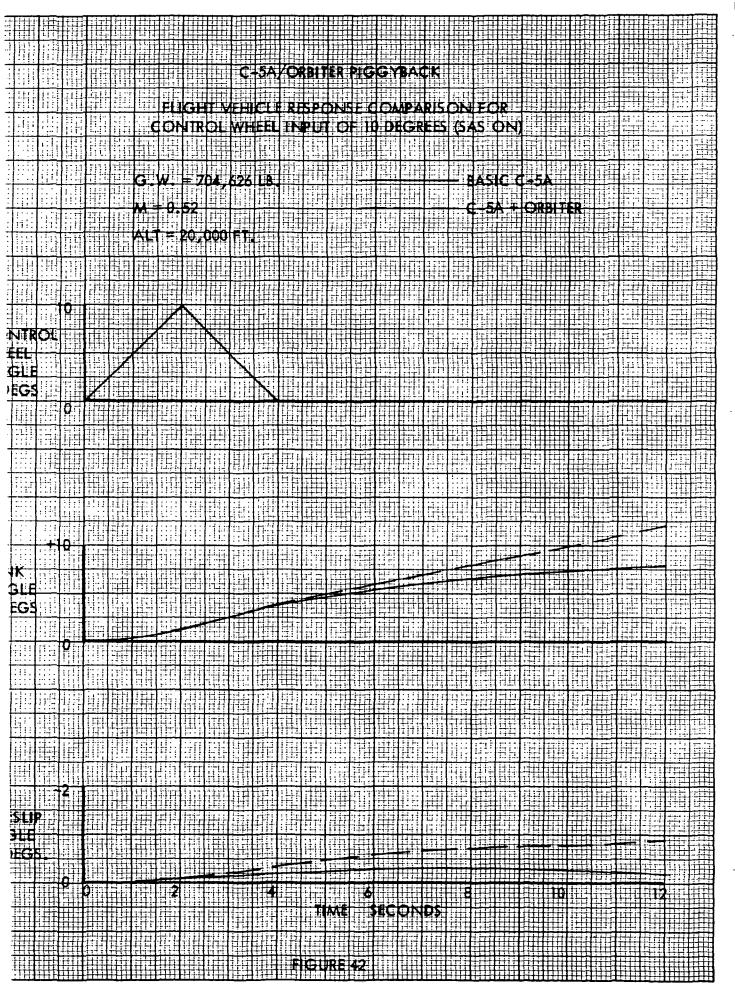
Spoiler: $\Delta \delta_s = -.786 \ (\phi)$

Rudder: $\Delta \delta_r = 0$

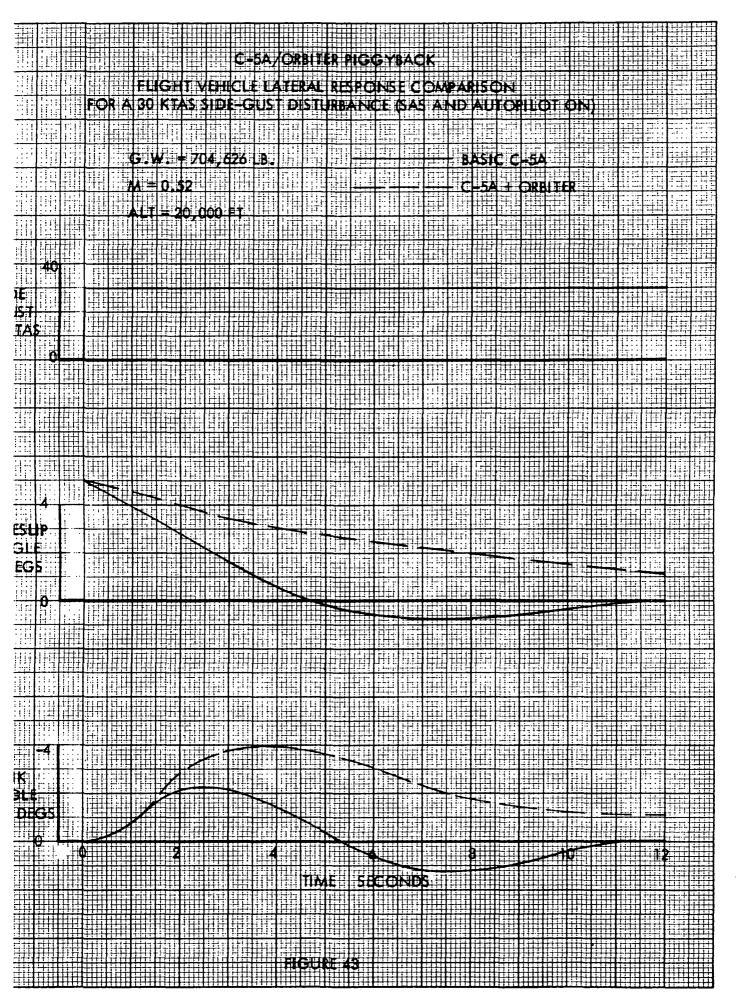
* Control command and heading stability ($\phi < 7^{\circ}$) elements are excluded.

FIGURE 40





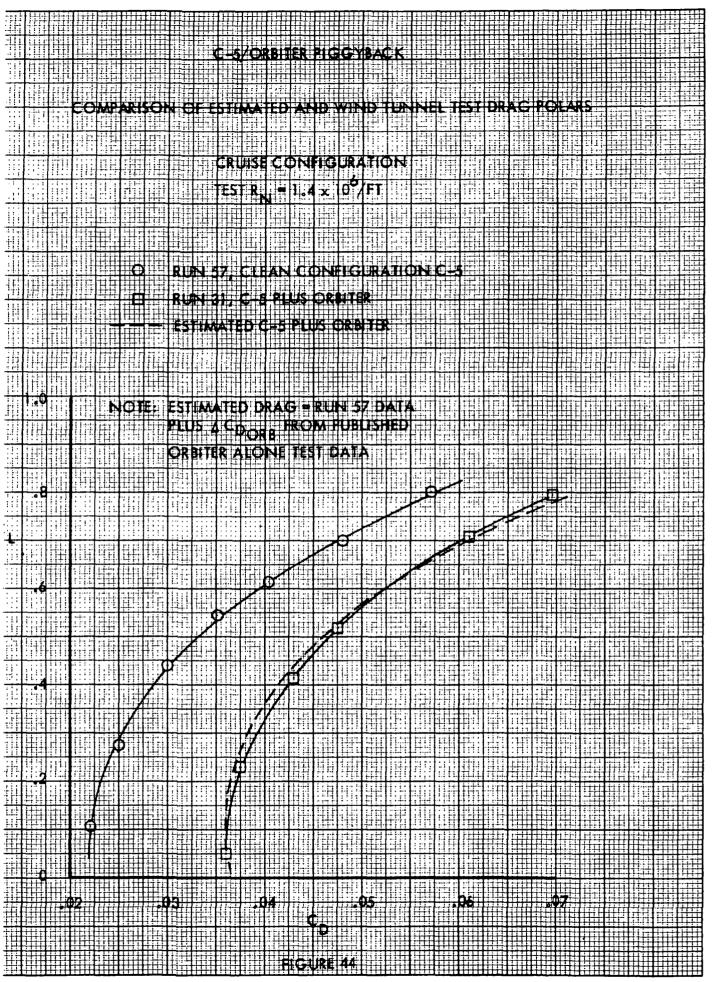
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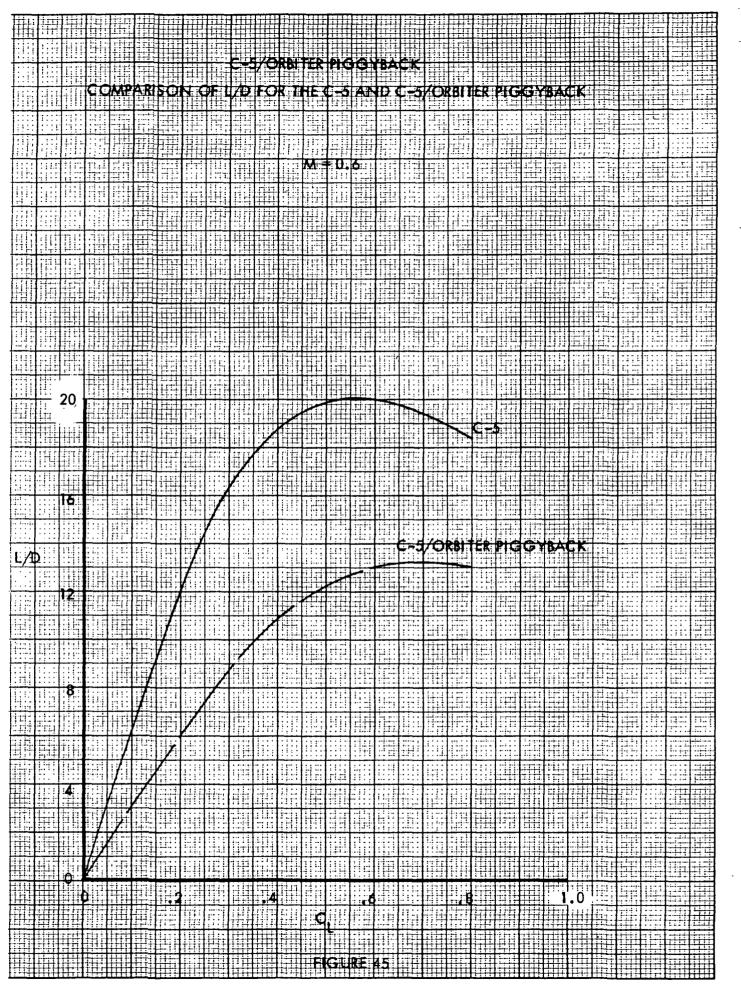
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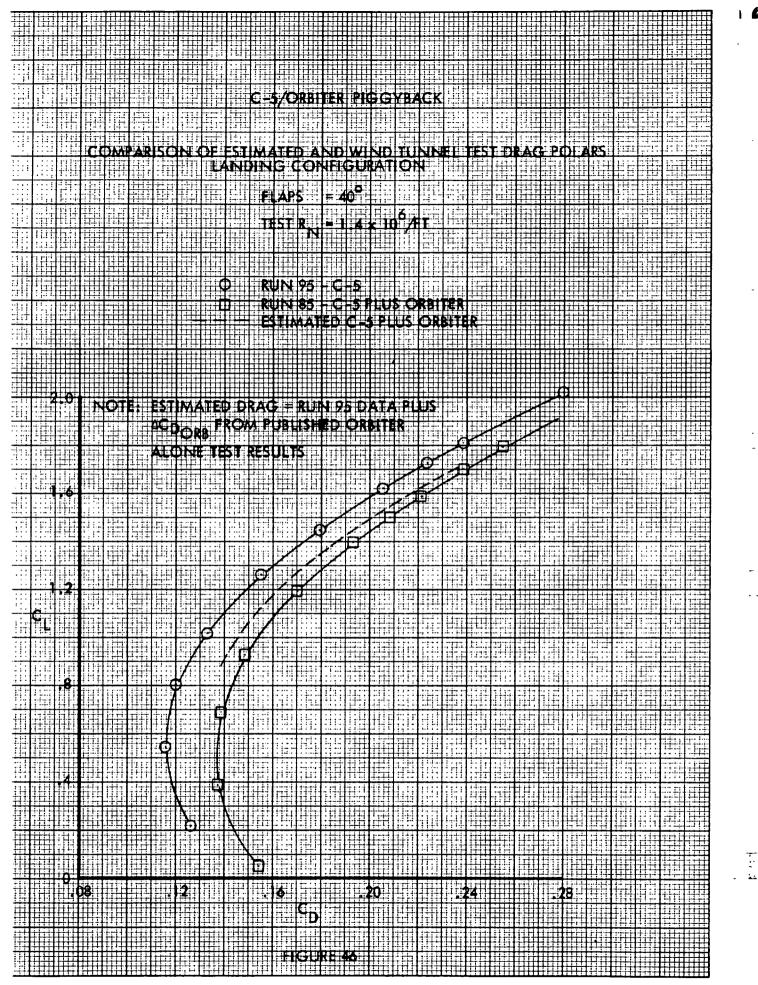
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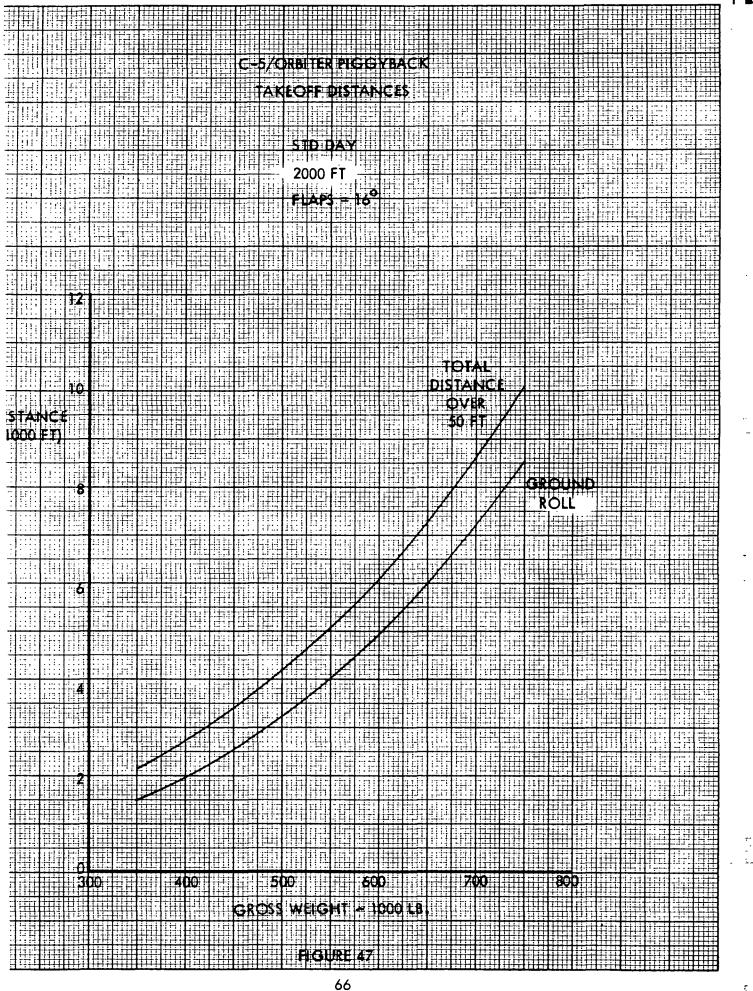


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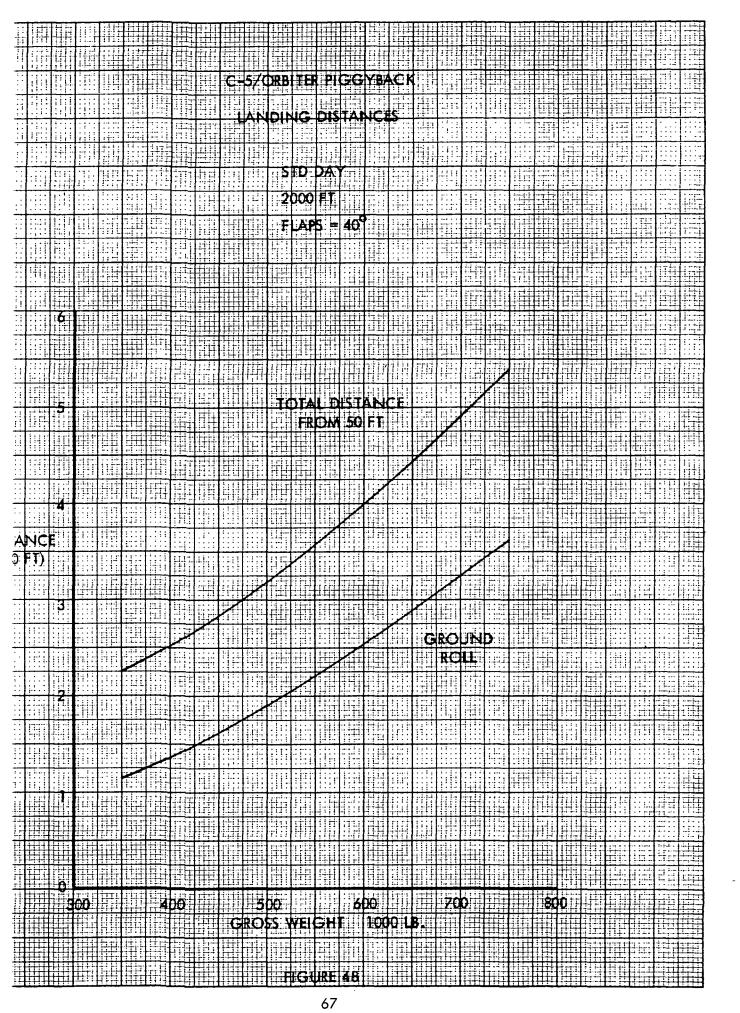


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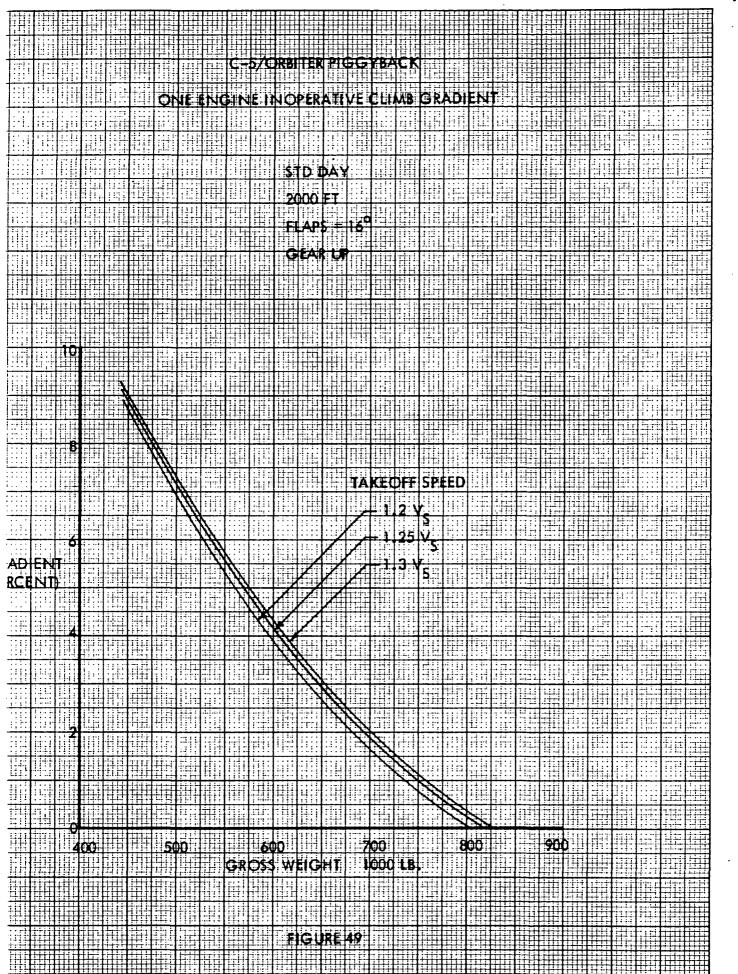


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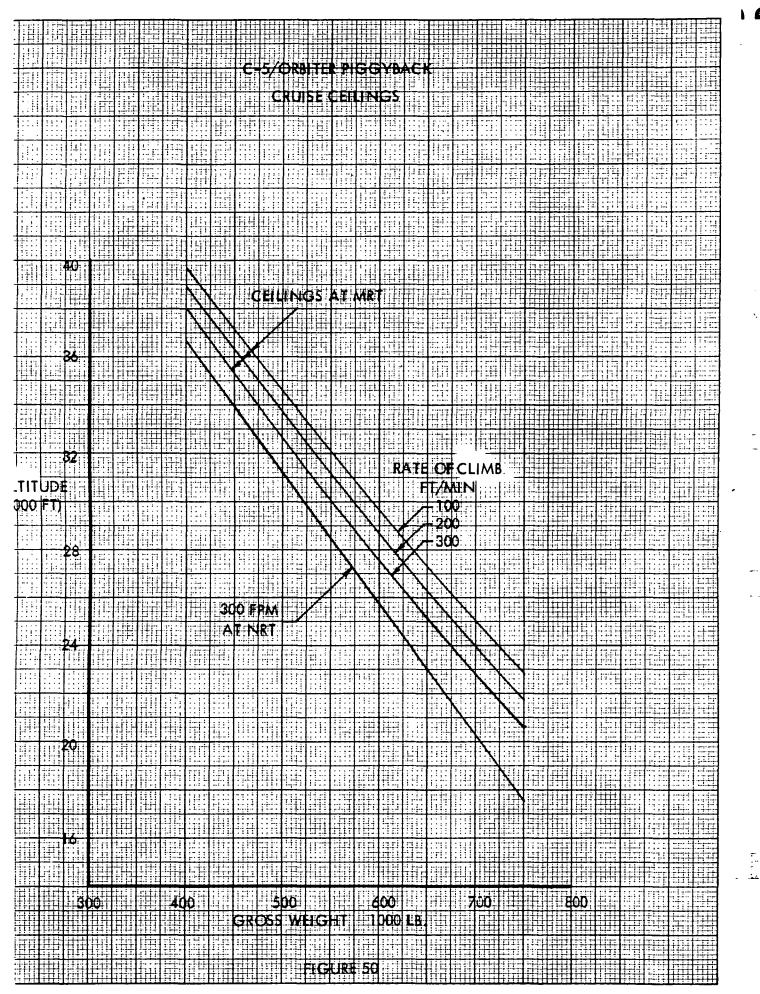
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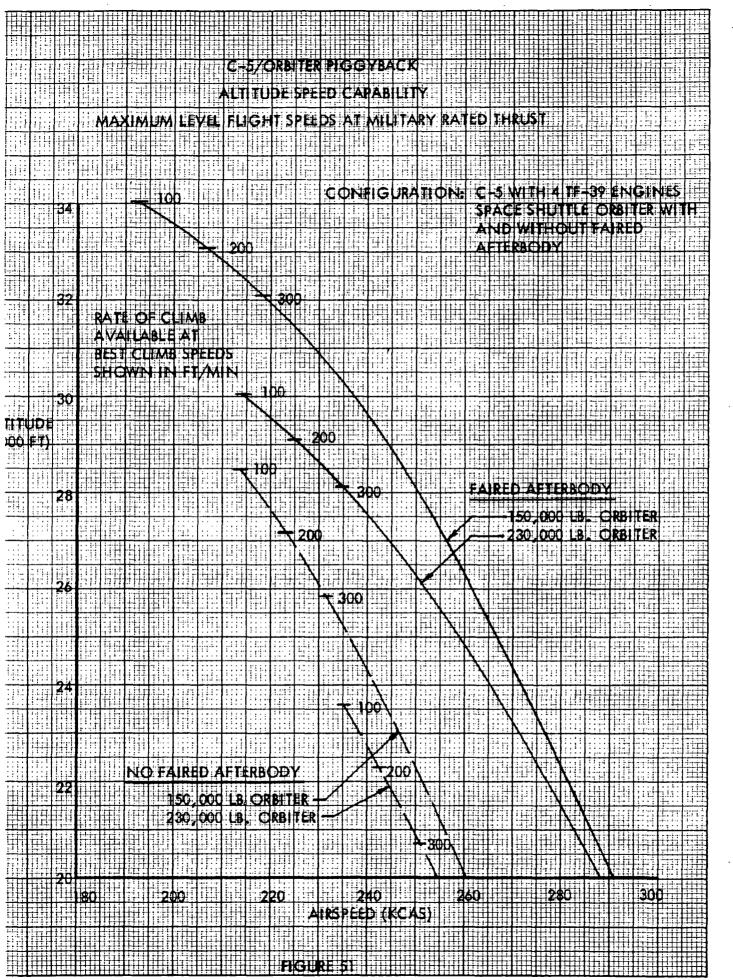
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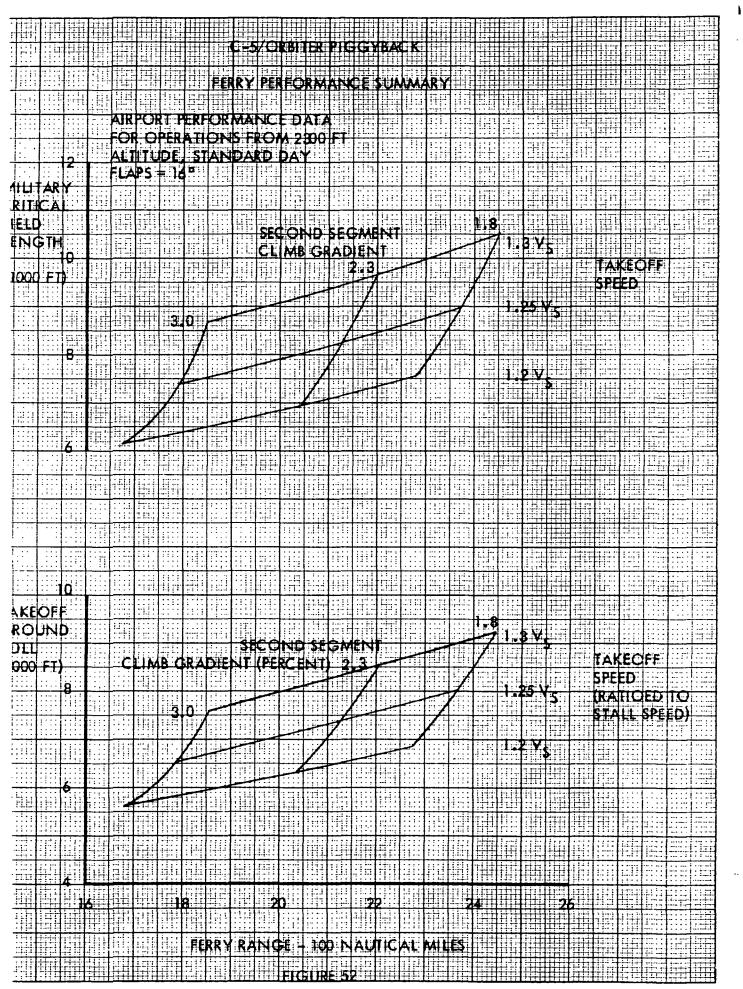
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FLIGHT RESTRICTIONS		
	¢	В
LEVEL FLIGHT MAXIMUM SPEED, V _{HR} /M _H , KCAS	300/.775	280/.75
LIMIT SPEED, V _L /M _L , KCAS	360/.85	350/ .8
speed for maximum gust intensity, v_{G}/m_{H} , kcas	240/.775	210/.75
MANEUVER LOAD FACTOR, G	+2.0, -0.0	+2.0, -0.0
DESIGN SINK SPEED, F. P. S.	6.0	6.0
NO ABRUPT MANEUVERS	×	×
SIDE LOAD FACTOR DURING TURNS, G	.2	.2
WEIGHTS FOR STRUCTURAL DESIGN		
OPERATING WEIGHT, LB	334, 900	336,310
MAXIMUM ZERO WING FUEL WEIGHT, LB	598,204 *	4 *
MAXIMUM WING FUEL, LB	318,500	0
MAXIMUM FUSELAGE FUEL, LB	11,300	13,525
MAXIMUM GROSS WEIGHT, LB	865,000	0
MAXIMUM LANDING WEIGHT, LB	635,850	0
* INCLUDES FUSELAGE FUEL		
A = NO INCREASE IN VERTICAL STABILIZER AREA.		
B = INCREASED VERTICAL STABILIZER AREA.		
FIGURE 53		

C-5/ORBITER PIGGYBACK

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FLIGHT RESTRICTIONS	SUPER GUPPY	LEVEL FLIGHT MAXIMUM SPEED, V _{HR} /M _H , KCAS 300/.775 219	D, V _L /M _L , KCAS 360/.85 , 219/.58	SPEED FOR MAXIMUM GUST INTENSITY, V _G /M _H , KCAS 240/.775 180-198	R LOAD FACTOR, G +2.0, -0.0 2.2 FLAPS UP 2.0 FLAPS DOWN	NK SPEED, F.P.S. 6.0 7.5	T MANEUVERS × × ×	SIDE LOAD FACTOR DURING TURNS, G .2 NO BRAKES	GROSS WEIGHT, LB 865,000 162,000	FIGURE 54	
		LEVEL FLIGHT MAXI	LIMIT SPEED, V _L /M _L , KCAS	SPEED FOR MAXIMU	MANEUVER LOAD FACTOR	DESIGN SINK SPEED, F.P.S.	NO ABRUPT MANEUVERS	SIDE LOAD FACTOR	MAXIMUM GROSS WEIGHT		

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C-5/ORBITER PIGGYBACK

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1. 1. 21 APPENDIX A

WIND TUNNEL TEST DESCRIPTION AND PLOTTED DATA

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I - MODEL DESCRIPTION

The C-5A Piggyback model is a combination of the Rockwell International 0.0405 Shuttle Orbiter model and the Lockheed-Georgia 0.0399-scale low speed C-5A model joined with suitable attach fittings.

The Orbiter model is fabricated from wood and metal and incorporates adjustable control surfaces. Provision was made for the installation of various afterbody fairings. Five afterbody fairing shapes were available for test. The basic Rockwell International fairing is denoted by a superscript 1. The original Lockheed-Georgia fairing, denoted by a superscript 2, was designed to minimize the afterbody drag. Fairings 3, 4, and 5 were fabricated by cutting away various portions of the fairing in an attempt to improve the flow at the C-5A tail.

The 0.0399-scale, low speed C-5A model is assembled from numerous components that allow the simulation of configurations encompassing the entire flight regime of the aircraft. The model is fabricated primarily from aluminum with some steel and plastic parts. All control surfaces are adjustable, and the landing gears and cargo doors may be positioned in increments from fully retracted to fully extended.

A symbol list of all the model components used in this test is presented in Section VI.

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II - TEST FACILITY

The C-5A - Orbiter Piggyback combination tests were conducted in the Lockheed-California Company 8 X 12 - Foot Low Speed Wind Tunnel. The tunnel is a conventional, low speed, single-return type with the test section vented to atmospheric pressure. Details of the facility are presented in Reference 1.

The model is supported in the upright position by a three-support fork. The fork is connected to an external, six-component, pyramidal-type balance located below the floor of the test section. The balance transmits loads from the model and support to an electrical readout system. Raw data are converted to punched cards using an IBM 1442 card reader punch. The raw data cards are input to the IBM 1131 Processor computer, which converts these data into coefficient form for output as tabulated data and provides the input for the Calcomp 565 plotter which produced the finished data plots presented in this appendix.

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III - TEST CONDITIONS

All runs with flaps deflected were made at a dynamic pressure of 40 P.S.F. Flaps up runs were made at a dynamic pressure of 60 P.S.F. These dynamic pressures correspond to Mach Numbers of 0.165 and 0.201, and Reynolds Numbers of 1.436 $\times 10^{6}$ and 1.758 $\times 10^{6}$, respectively. Reynolds Numbers are based on the C-5A model M.A.C.



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IV - DATA REDUCTION

Six-component force data were measured during all runs. The data were reduced to coefficient form and transferred to the stability axis system coincident at the reference moment center (F.S. 53.762, W.L. 10.578, BL 0.000). Corrections applied to the six-component data include tunnel wall corrections, blockage, buoyancy drag, and support tare and interference corrections.

The support tare and interference were obtained in a previous test of a similar model (Reference 2). The correction values applied to the longitudinal components data were taken from faired plots of the tare and interference corrections, whereas the values applied to the lateral component data were taken directly from the computed results.

The six-component data reduction constants are listed below.

Wing Area, square feet		9.878
Wing Span, inches		104. 997
Wing Mean Aerodynamic Chord, inche	es	14.817
Wing Mean Aerodynamic Chord Locati	ion F.S.	53.762
	W.L.	12.577
	B.L.	21.654
Front Trunnion Location	F.S.	53.742
	W.L	4.328
Moment Reference Center	F.S.	53.762
	W.L.	10.578

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- "Wind Tunnel Computing Handbook," Lockheed California Company Report LALI, 15 June 1955.
- "C-141: Investigation of the Low Speed Characteristics of the Production Airplane Configuration Using a 0.044 Scale Model in the Lockheed-California Company 8 X 12-Foot Wind Tunnel, "Tests L-45-1, 11, and 111; Report No. ER 5071, June 1963.

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VI - MODEL CONFIGURATION SYMBOLS

a ¹⁰	<u>Aileron</u> , Simple hinge, sealed range ⁺ 25 ⁰ , denoted angles set with protra	by subscripts.	07-C5A-0197-110			
A	with/without aft fairi	<u>Orbiter, Shuttle</u> – 0.0405 Scale Rockwell International Model. with/without aft fairing; capability of being located at 4 position on C–5A model, 3 angles of attack (ref. Orbiter FRL; –1 1/2°, + 1/2°, + 2 1/2°)				
Superscripts:	Afterbody fairing shape and Or and letter superscripts, respect indicates afterbody fairing rem	ively. Lack of a number				
1	Rockwell International fairing					
2	Lockheed–Georgia fairing					
3	Lockheed-Georgia fairing mod	fied to lower surface up	sweep			
4	Lockheed-Georgia fairing mod	fied to upper surface do	wnsweep.			
5	Lockheed-Georgia fairing modified to shorter fairing with horizontal knife edge Orbiter c.g. locations in terms of C-5 Fuselage Stations					
	Longitudinal Position	Vertical Position				
A (BASE)	54.424"	Base				
В	56.819"	Base				
С	59.235"	Base				
D	54.424"	Base + 2.395"				
E	56.819"	Base + 2.395"				
F	59.235"	Base + 2.395"				

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Subscripts: Orbiter incidence in degrees referenced to C-5A FRL is denoted by a subscript

(i.e. $A_{1.5}^{1A}$ - Orbiter with Rockwell International afterbody fairing located in the base position at 1.5° incidence)

в ²²	Fuselage		07-C5A-0181-200
b ¹⁶	Bullet		07-C5A-0182-403
D ^{8 MOD}	Dorsal		07-C5A-0181-402A
e ¹²	Elevator	Inboard. Simple hinge, hinge line gap sealed. Deflection range –25 ⁰ +15 ⁰ ; denoted by subscripts. Set with protractor.	07-C5A-0198-401
13 e	<u>Elevator</u>	Outboard. Simple hinge, hinge line gap sealed. Deflections range – 25 [°] 15 [°] , denoted by subscripts. Set with protractor.	07-C5A-0198-401
f ³⁷	Flaps, T.E.	. Fowler. Six sections/side, 0 ⁰ and 40 ⁰ (ldg.) to be tested.	07-C5A-0198-105
н ⁸	<u>Horizontal</u>	Stabilizer. Incidence settings capability. 0°, + 4°, + 6°, -8°, -12°; set with pin in push rod in vertical.	07-C5A-0198-401- -0195-400
к ^{24А} N ^{20А}	Pylon/Nac	elles	07-C5A-0197-300
Q ¹³		ling Edge. 14% C _W , 3 section/side. Inboard 2 section sealed to wing and pylon, outboard section 1.25% C _W T.E. gap and sealed to pylons. Deflection 20 [°] inboard sections, 20 [°] outboard; denoted by subscript "20".	07-C5A-0197-109

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78 rr	<u>Rudders</u> , lower and upper, respectively. Simple hinge, hinge line gap sealed; deflections $\frac{+}{-}30^{\circ}$.	07-C5A-0192-402
v ⁹	Vertical Stabilizer	07-C5A-0182-402
WIIA	Wing	07-C5A-0197-100
z ^{f6}	Flap Track Fairing	07-C5A-0197-106
z ^{g27}	Nose Landing Gear Fairing	07-C5A-0197-201
z ^{g23}	Main Landing Gear Fairing	07-C5A-0151-204
z ^{w27}	<u>Wing - Fuselage Fillet</u> - Alum. and Plastic; Composed of Z ^{w26} fwd. fillet and Z ^{w22} aft. fillet.	07-C5A-0197-200
$S^{1} = B^{22}W^{1}$	$A_{A}^{w27}K^{24A}N^{20A}Z^{f6}Z^{g27}Z^{g23}$	
v ¹	<u>Center Vertical Fin Extension</u> – Alum. plate, cut to match L.E – T.E vertical stabilizer sweep and tip chord of vertical (V ⁹), span 6", attached to top of horizontal bullet fairing.	
h ¹	<u>Horizontal Stab. Fins.</u> – end plates on tips of horizontal stabilizer 1" inbd. from horizontal tips, 4" chord, 8" span (or height).	



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<u>vileron</u> , (a ¹⁰)	0.039916 Scale
Area per side, square feet	0.188
Span, inches	10.651
Chord lengths, inches	
Inboard	2.978
Outboard	2.337
Mean (RMS, streamwise)	
Sweep of hinge line, degrees	20.417
Deflection limits, degrees	+25
uselage, (B ²²)	
Length, inches	110.487 (9.207')
Maximum frontal area, square inches	126.60
Equivalent maximum diameter, inches	12.69
Fuselage reference line	W.L. 7.983
Nose location	F.S. 6.387
Wetted area, square feet (imprints not removed)	25.223
Volume, Cu. Ft.	5.379
ullet, (b^{16})	
Length, inches	21.44
Maximum frontal area, square inches	3.22
Equivalent diameter, inches	2.03
Wetted area, square	0.541

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Dorsal, (D^{8 mod.}) 0.129 Wetted area, square feet 0.075 Imprint area, square feet (On fuselage) Elevator, Inboard (e¹²) Area per side, square 0.1434 feet 3.227 Root chord, inches 2.228 Tip chord, inches 2.773 Mean chord length (RMS), inches Span per side, inches 7.569 Hinge line, % horizontal 66.000 chord Deflections, degrees + 30.000 Elevator, Outboard (e¹³) Area per side, square 0.0624 feet 2.228 Root chord, inches Tip chord, inches 1.609 Mean chord length 1.943 (RMS), inches Span per side, inches 4.684 Hinge line, % horizontal 66.000 chord Deflections, degrees +33.000Trailing Edge Fowler Flaps, (f³⁷)* Panel 1 (Inboard) Area per side, square feet 0.214

*All dimensions given in Wing Reference Plane.

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Trailing Edge Fowler Flaps, (Cont.)		
Span, inches		7.085
Sweep of leading edge, degrees		9.832
Chord lengths, inches		
Root		4.410
Tip		4.410
Average		4.410
Mean (RMS)		4.410
Chord locations, inches		
Root	W.S.	5.620
Tip	W.S.	12.705
Average	W.S.	9.163
Mean (RMS)	W.S.	9.163
Maximum deflection, degrees		40.000
Panel 2		
Area per side, square feet		0.173
Span, inches		5.718
Sweep of leading edge, degrees		9.832
Chord lengths, inches		
Root		4.410
Tip		4.410
Average		4.410
Mean (RMS)		4.410
Chord locations, inches		
Root	W.S.	13.344
Tip	W.S.	19.062
Average	W.S.	16.203

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Trailing Edge Fowler Flaps, (Cont.)		
Mean (RMS	W.S.	16.203
Maximum deflection, degrees		40.000
Panel 3		
Area per side, square feet		0.125
Span, inches		4.845
Sweep of leading edge, degrees		12.364
Chord lengths, inches		
Root		3.804
Tip		3.804
Average		3.804
Mean (RMS)		3.804
Chord locations, inches		
Root	W.S.	19.701
Tip	W.S.	24.546
Average	W.S.	22.123
Mean (RMS)	W.S.	22.123
Maximum deflection		40.000
Panel 4		
Area per side, square feet		0.094
Span, inches		4.497
Sweep of leading edge, degrees		17.033
Chord lengths, inches		
Root		3.133
Tip		3.133
Average		3.133
Mean (RMS)		3.133

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Trailing Edge Fowler Flaps (Cont.)

Chord locations, inches		
Root	W.S.	25.184
Tip	W.S.	29.681
Average	W.S.	27.433
Mean (RMS)	W.S.	27.433
Maximum deflection, degrees		40.000
Panel 5		
Area per side, square feet		0.079
Span, inches		3.802
Sweep of leading edge, degrees		17.033
Chord lengths, inches		
Root		3.133
Tip		3.133
Average		3.133
Mean (RMS)		3.133
Chord locations, inches		
Root	W.S.	30.321
Tip	W.S.	34.135
Average	W.S.	32.222
Mean (RMS)	W.S.	32.222
Maximum deflection, degrees		40.000
Panel 6		
Area per side, square feet		0.082
Span, inches		3.938
Sweep of leading edge, degrees		17.033

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Trailing Edge Fowler Flaps (Cont.)

Chord lengths, inches		
Root		3.133
Тір		3.133
Average		3.133
Mean (RMS)		3.133
Chord locations, inches		
Root	W.S.	34.773
Tip	W.S.	38.712
Average	W.S.	36.742
Mean (RMS)	W.S.	36.742
Maximum deflection, degrees	· ··· ·· ·	40.000
<u>Horizontal Stabilizer</u> , (H ⁸)		
Airfoil Section NACA 0010.5-0.833-0.40/1.432 (modified)		
Area – projected square feet		1.539
- wetted, square feet (Exposed only)		2.910
Span		32.397
Chord lengths - MAC, inches		7.322
Root, inches		9.985
Tip, inches		3.695
Aspect ratio		4.736
Taper ratio		0.370
Sweep of 25% chord line, degrees		24.583

25% MAC Location F.S. 115.533

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Horizontal Stabilizer, (Cont.)

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	B.L.	6.858
Volume coefficient		0.629
Tail length, inches		60.028
Pylon, (K ^{24A})		
Sweep of L.E., degrees		71.504
Chord length, inches		13.073
Taper ratio		0.876
Airfoil section NACA 0008-1.100-0.335/1.575 (modified)		
Wing intersection, % wing chord		1.4
Toe -in, degrees		1.0
Wing intersection, inboard	B.L.	19.122
Wing intersection, outboard	B.L.	29.781
Nacelle, (N ^{20A})		
Length, inches		9.228
Maximum diameter, inches		4.091
Duct diameter, inches		3.409
Fineness ratio		2.256
Area, square feet		
Maximum frontal area		0.091
Inlet area		0.075
Side area		0.249
Toe-in angle, degrees		1.0
Incidence, degrees		2.0

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Nacelle (Cont.)				
Inlet location				
Inboard nacel	le	F.S.	41.970	
		W.L.	8.864	
		B.L.	18.999	
Outboard nac	elle	F.S.	47.490	
		W.L.	7.891	-
		B.L.	29.658	
Leading Edge Slat,	(Q ¹³)			
Section I (outboo 1–1/4% C _w gap	ard)			
Area, square	feet		0.191	
Span, inches			19.556	
Chord length	- root, inches		1.698	
	tip, inches		1.135	
	average, inches		1.417	-
Chord location	n – root	B.L.	29.291	
	tip	B.L.	48.788	
Angle from stop position, degr			22.0	
Section II (mid se sealed	ection),			
Area, square	feet		0.079	
Span, inches			6.336	
Chord length	- root, inches		1.881	• • •
	tip, inches		1.698	<u></u>
	average , inches		1.790	

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Leading Edge Slat (Cont.)						
Chord location	Chord location – root				22.974	
	tip			B.L.	29.291	
Angle from stor position, degre					20.0	
Section III (inboar sealed	⁻ d),					
Area, square f	eet				0.261	
Span					16.377	
Chord length -	root , inc hes				2.714	
	tip, in	ches			1.881	
	averag inches	e,			2.298	
Chord location	- root			B.L.	6.646	
	tip			B.L.	22.974	
Angle from stor position, degre					20.0	
<u>Rudder</u> , (r ⁷ , r ⁸)			r ⁸ (Upper)		7 r (Lower)	
Area, square feet			0.161		0.203	
Location						
Lower end		W.L.	22.924		15.793	
Upper end		W.L.	29.119		22.924	
Hinge line, pe vertical chord	rcent		71		71	
Span, inches			6.195		7.133	
Deflection limits, degrees			+30		+ 30	
Root chord, inche	s		3.097		4.278	
Tip chord, inches			3.585		3.907	

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Rudder, (Cont.)				
Mean chord length (RMS), inches		3.750		4.097
Mean chord location	W.L.	25.949		19.272
Percent of vertical tail		10.5		13.1
<u>Spoiler</u> , (a ²²)*				
Panel (Inboard Section	ר)			
Area per side, square	e feet			0.0514
Span, inches				3.606
Sweep of hinge line,	degrees			9.832
Chord lengths, inche	S			
Root				2.206
Тір				2.026
Average				
Mean (RMS)				
Chord locations, incl	nes			
Root			W.S.	5.550
Tip			W.S.	9.157
Average			W.S.	
Mean (RMS)			W.S.	
Maximum deflection, degrees				60.000
Panel 2				
Area per side, square	feet			0.0508
Span, inches				3.610
Sweep of hinge line,	degrees			9.832
Chord lengths, inches	i			
Root				2.026

*All dimensions given in wing reference plane.

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Spoiler, (Cont.)		
Tip		2.026
Average		2.026
Mean (RMS)		2.026
Chord locations, inches		
Root	W.S.	9.169
Tip	W.S.	12.779
Average	W.S.	
Mean (RMS)	W.S.	
Maximum deflection, degrees		60.000
Panel 3		
Area per side, square feet		0.0412
Span, inches		2.927
Sweep of hinge line, degrees		9.832
Chord lengths, inches		
Root		2.026
Tip	•	2.026
Average		2.026
Mean (RMS)		2.026
Chord locations, inches		
Root	W.S.	13.270
Tip	W.S.	16.197
Average	W.5.	
Mean (RMS)	W.S.	
Maximum deflection, degrees		60.000
Panel 4		
Area per síde, square feet		0.0412
Span, inches		2.927
Sweep of hinge line, degrees		9.832

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Spoiler (Cont.)		
Chord lengths, inches		
Root	2.026	
Tip	2.026	
Average	2.026	
Mean (RMS)	2.026	
Chord locations, inches		
Root	W.S. 16.209	
Тір	W.S. 19.136	
Average	W.S.	
Mean (RMS)	W.S.	
Maximum deflection, degrees	60.000	
Panel 5		
Area per side, square feet	0.0272	
Span, inches	2.490	
Sweep of hinge line, degrees	12.347	
Distance hinge line forward of leading edge, inches	0.336	
Chord lengths, inches		
Root	1.910	
Tip	1.910	
Average	1.910	
Reference**	2.247	

**Reference chord is defined as twice the distance from the hinge line to spoiler t.e. minus the average chord.

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Spoiler (Cont.)

oller (Cont.)	
Chord locations, inches	
Root	W.S.
Тір	W.S.
Average	W.S.
Reference	W.S.
Maximum deflection, degrees	
Panel 6	
Area per side, square feet	
Span, inches	
Sweep of hinge line, degrees	
Distance hinge line forward of leading edge, inches	
Chord lengths, inches	
Root	

Chord lengths, inches		
Root		1.910
Tip		1.910
Average		1.910
References**		2.247
Chord lœations, inches		
Root	W.S.	22.129
Tip	W.S.	24.620
Average	W.S.	
Reference	W.S.	
Maximum deflection, degrees		60.000

**Reference chord is defined as twice the distance from the hinge line to spoiler t.e. minus the average chord.

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S	po	il	er (Cont.)
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Panel 7		
Area per side, square feet		0.0399
Span, inches		4.645
Distance hinge line forward of leading edge, inches		0.260
Sweep of hinge line, degrees		17.033
Chord lengths, inches		
Root		1.236
Тір		1.236
Average		1.236
Reference**		1.757
Chord locations, inches		-
Root	W.S.	25.111
Tip	W.S.	29.756
Average	W.S.	
Reference	W.S.	
Maximum deflection, degrees		60.000
Panel 8		
Area per side, square feet		0.0340
Span, inches		3.962
Sweep of hinge line, degrees		17.033
Distance hinge line forward of leading edge, inches		0.260
Chord lengths, inches		
Root		1.236
Tip		1.236
Average		1.236
Reference**		1.757

**Reference chord is defined as twice the distance from the hinge line to spoiler t.e. minus the average chord. 16

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Spoiler (Cont.)

Chord locations, inches

Root	W.S.	30.247
Tip	W.S.	34.209
Average	W.S.	
Reference	W.S.	
Maximum deflection, degrees		60.000
Panel 9		
Area per side, square feet		0.0336
Span, inches		4.086
Sweep of hinge line, degrees		17.033
Distance hinge line forward of leading edge, inches		0.247
Chord lengths, inches		
Root		1.184
Тір		1.184
Average		1.184
Reference**		1.679
Chord locations, inches		
Root	W.S.	34.700
Тір	W.S.	38.785
Average	W.S.	
Reference	W.S.	
Maximum deflection, degrees		60.000

**Reference chord is defined as twice the distance from the hinge line to spoiler t.e. minus the average chord.

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Vortex Generator, (U^2)	
Height, inches	
Superscript A	0.08
Superscript B	0.10
Superscript C	0.12
Width, inches	
Superscript A	0.16
Superscript B	0.20
Superscript C	0.24
Angle to freestream, degrees	15.00
Chordwise location (centerline of generator), % of t.e. flap	15.00
Spanwise location, inches from flap tip chord	
Subscript 1	0.18
Subscript 2	0.23
Subscript 3	0.28
Subscript 4	0.33
Subscript 5	0.38
Vertical Stabilizer, (V ⁹)	
Airfoil section NACA 0013-1.1-0.40/1.575 (modified)	
Areas (theoretical), square feet	
Projected	1.531
Wetted (exposed only)	2.848
Span, inches	16.535
Chord lengths, MAC, inches	13.390
Root, inches	14.817
Tip, inches	11.853
Aspect ratio	1.240

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MODEL DIMENSIONAL DATA (CONT.)

<u>Vertical Stabilizer</u> (Cont.)			
Taper ratio		0.800	
Sweep of 25% chord line, degrees		34.931	
25% MAC location	F.S.	107.992	
	W.L.	23.388	
Volume coefficient		0.079	
Tail length, inches		53.246	
$\underline{\text{Wing}}$, (W ^{11A}) (6204.601 ft ² Full Scale)			Data
Area, square feet			Reduction
Planform, theoretical		9.8857	9.878
Planform, exposed (Outboard of B.L.)		8.4930	
Wetted, exposed (Outboard ot B.L.)		16.504	
Volume, Cu. Ft.			0.770
Span, inches	(8.749')	104.997	104.997
MAC chord length, inches		14.826	14.817
Location of 0.25 chord MAC	F.S.	53.765	
	W.L.	12.557	
	B.L.	21.658	
Aspect ratio		7.744	
Taper ratio, theoretical		0.371	
Taper ratio, exposed		0.401	
Dihedral (0.25 chord), degrees		3.500	
Sweep angle, degrees			
Panel I (Inboard)			
Leading edge		28.449	
0.25 chord		24.268	
Trailing edge		10.046	

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Wing (Cont.)

Panel 2	
Leading edge	28.449
0.25 chord	24.803
Trailing edge	12.581
Panel 3	
Leading edge	27.382
0.25 chord	23.954
Trailing edge	12.581
Panel 4	
Leading edge	27.382
0.25 chord	25.001
Trailing edge	17.298
Chord length, inches	
Root	21.806
Break station, inboard	14.826
Break Station, Mid	13.606
Break Station, Outboard	13.018
Tip	7.332
Chord location, inches	
Root	B.L. 0
Break Station, Inboard	B.L. 19.144
Break Station, Mid	B.L. 22.973
Break Station, Outboard	B.L. 24.970
Тір	B.L. 52.498
Geometric twist, degrees	
Root	0
Break Station, Inboard	1.132
Break Station, Mid	1.500
Break Station, Outboard	1.576

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Flap Track Fairing, Z ^{f6}		
Centerline locations	W.S.	
	W.S.	
Nose Landing Gear Fairing (Z ^{G27})		
Maximum length, inches	11.30	
Maximum frontal area, square inches	6.06	
Wetted area, square feet	0.6311	
Imprint area on fuselage, square feet	0.5886	
Main Landing Gear Fairing, (Z ^{G28})		(Z ^{G23})
Maximum length, inches	33.290	35.36
Maximum frontal area, square feet	0.125	0.135
Wetted area, square feet	4.364	4.366
Imprint area on fuselage, square feet	3.513	
Maximum width, inches	14.078	14.18
Wing – Fuselage Fillet, (Z ^{W27})		
Maximum length	41.71	
Wetted area	3.638	
Imprint area of fuselage and fillet on Wing	3.582	
Side area	1.10	

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MODEL DIMENSIONAL DATA (CONT.)

Imprint area of wing and fillet on fuselage	3.013	
Location:		
Most forward point	F.S. 32.13	
Most aft point	F.S. 73.84	
Main Landing Gear Outer Door (FWD),	(d ^{m3})	
Length, inches	6.63	
Reference area, square feet	0.1932	
Span, inches	4.19	
Deflections, % Open	0,10,25,50, 75,100	
Main Landing Gear Outer Door (AFT),	(d ^{m4})	
Length, inches	6.63	
Reference area, square feet	0.1932	
Span, inches	4.19	
Deflections, % Open	0,10,25,50, 75,100	
Main Landing Gear Inner Door (FWD), (d ^{m5})	
Length, inches	4.23	
Reference area, square feet	0.0311	
Span, inches	1.06	
Deflections, degrees	0,3,6,29,75,95	
Main Landing Gear Inner Door (AFT), (a	J ^{m6})	
Length, inches	4.23	
Reference area, square feet	0.0311	÷
Span, inches	1.06	<u>خم .</u>
Deflections, degrees	0,3,6,29,75,95	

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MODEL DIMENSIONAL DATA (CONT.)

Nose Landing Gear Inner Door, (d ^{n 3})		
Length, inches		5.35
Reference area, square feet		0.0884
Span, inches		2.37
Deflections, % Open		0,10,25,50,75,100
Nose Landing Gear Outer Door, (d ⁿ⁴)		
Length, inches		4.18
Reference area, square feet		0.0371
Span, inches		1.28
Deflections, % Open		0,10,25,50,75,100
Ref. Moment Center:	F.S.	53.762
	W.L.	10.578
	B.L.	0.000



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VIII - RUN SCHEDULE

The following three pages present the run schedule for the wind tunnel test program.

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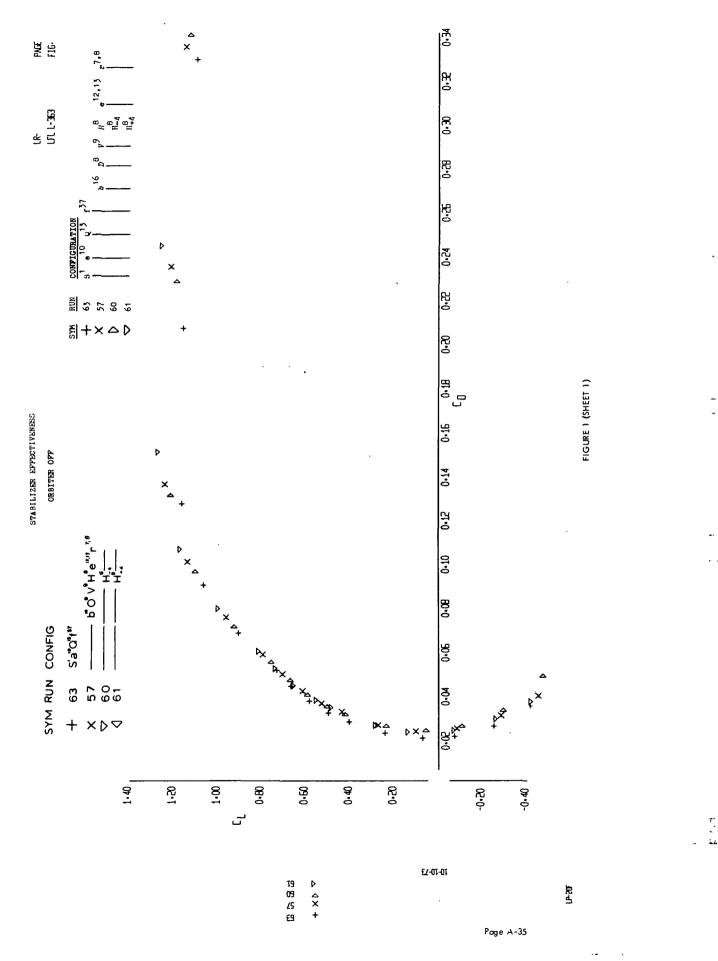
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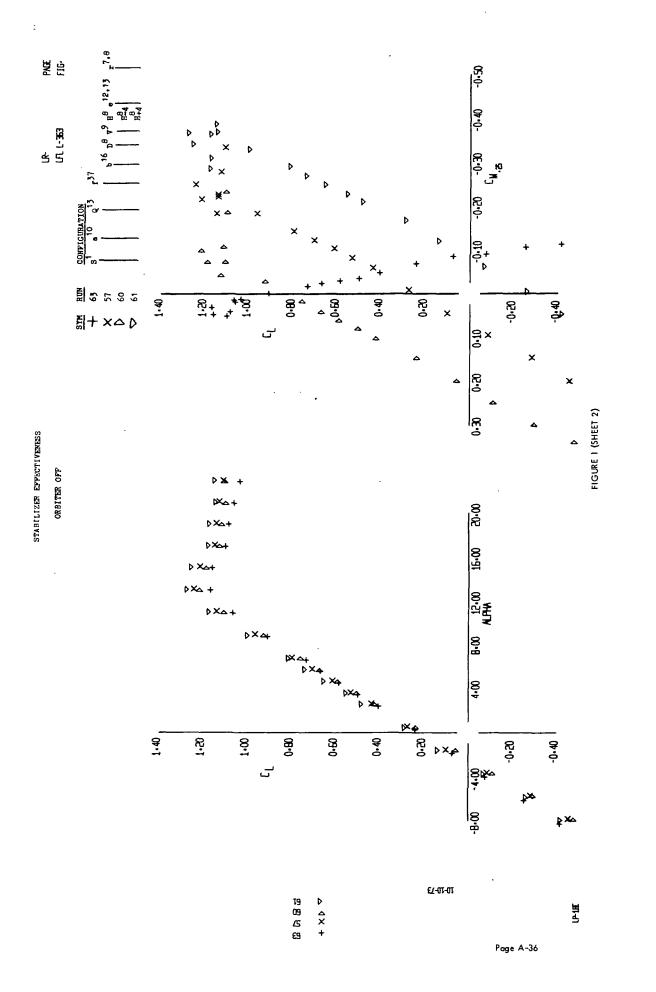
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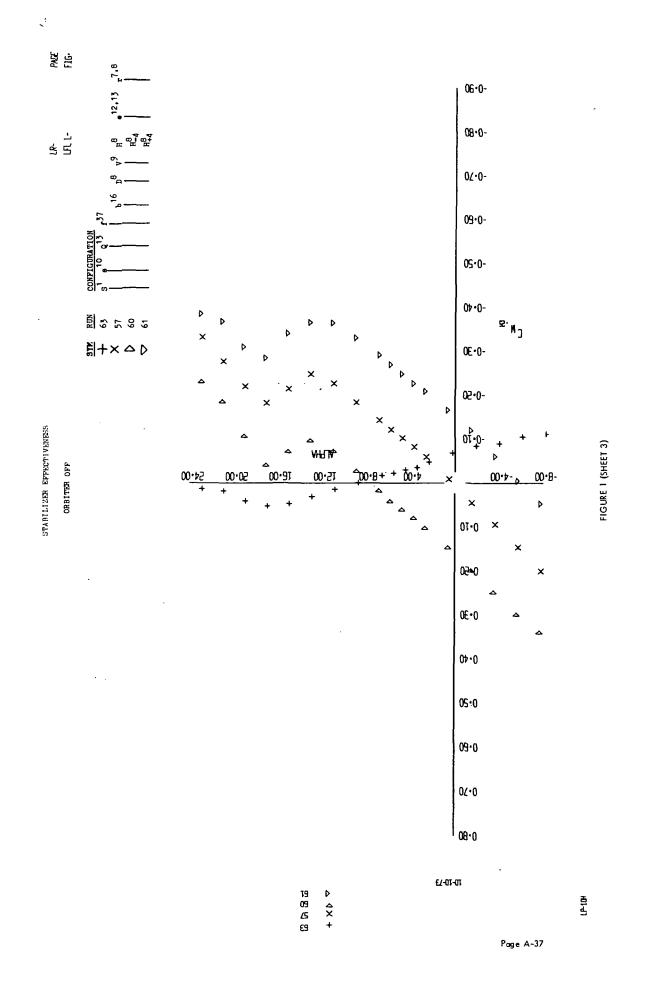
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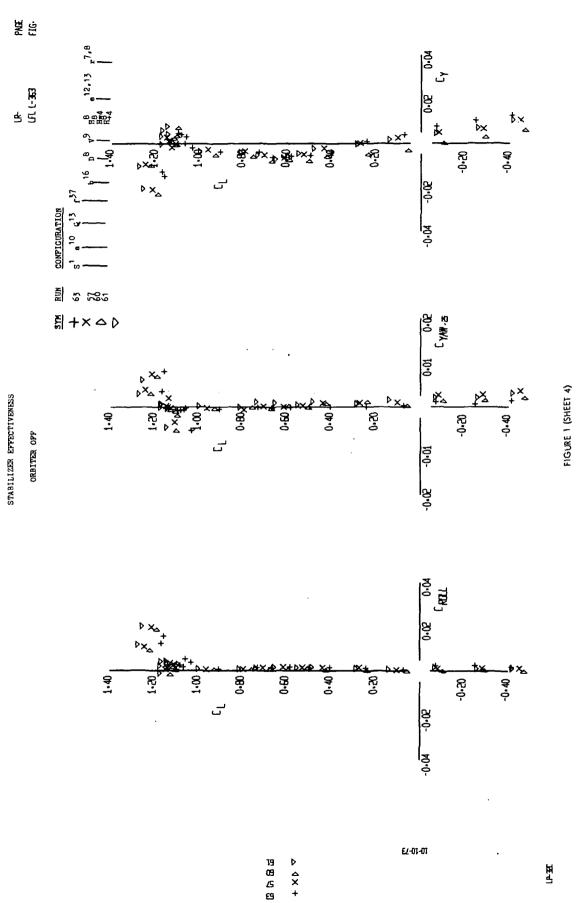
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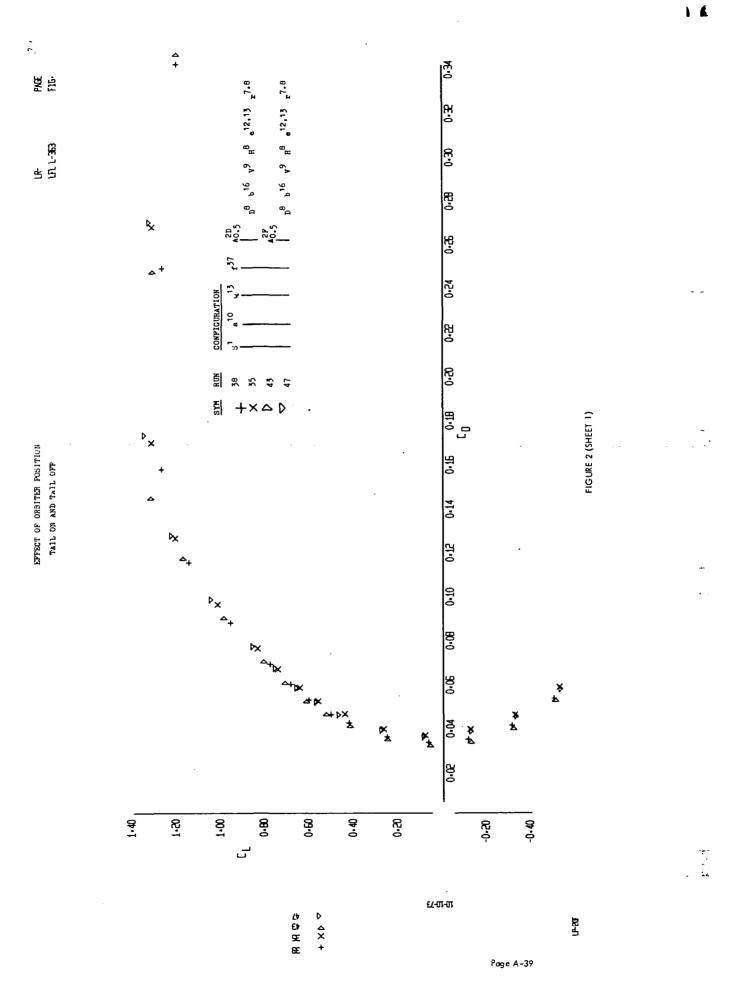
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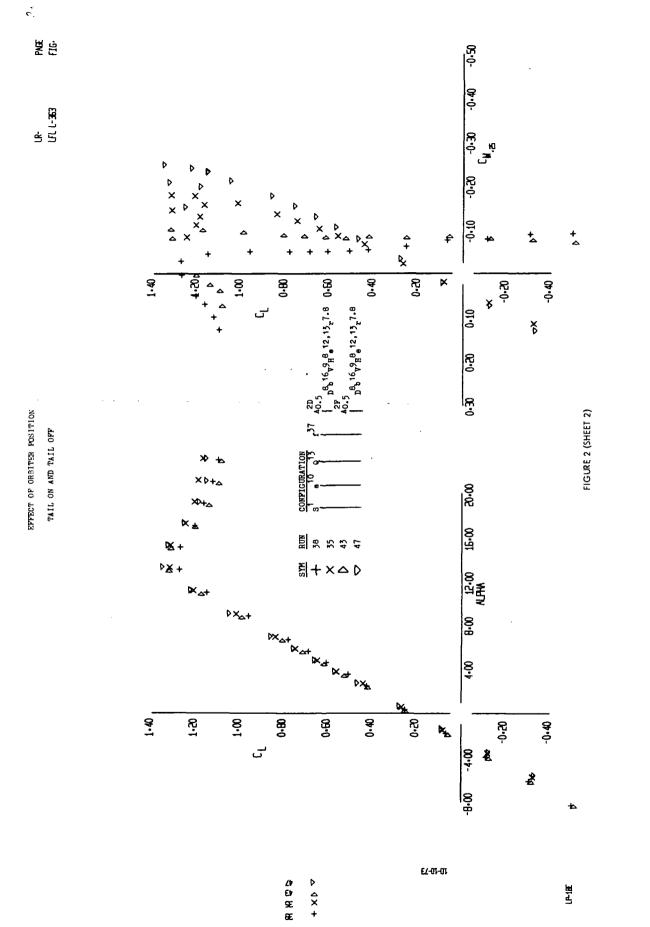
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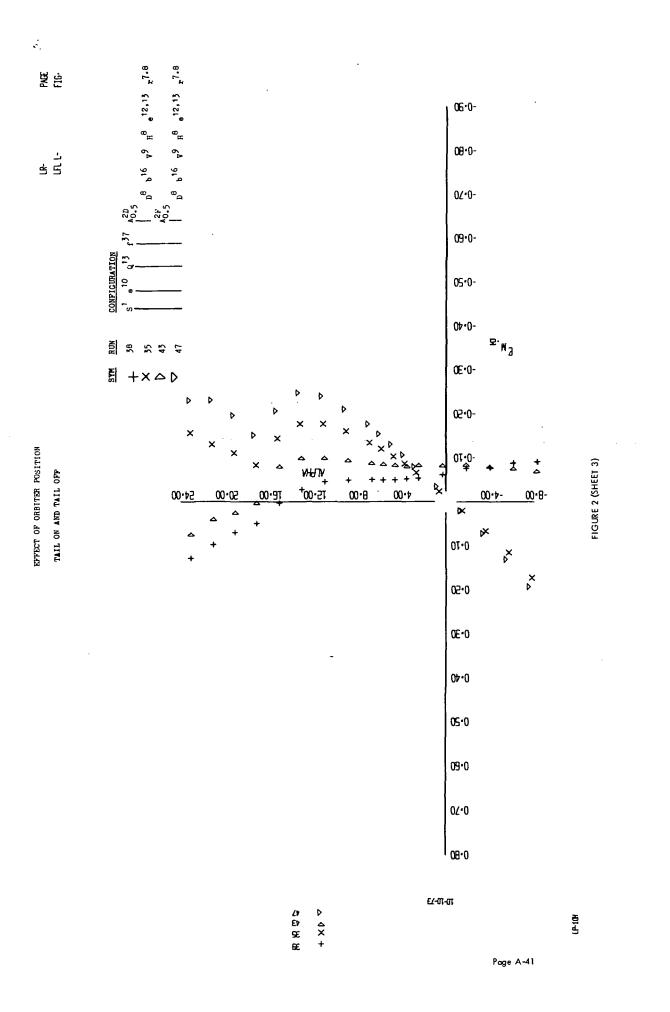


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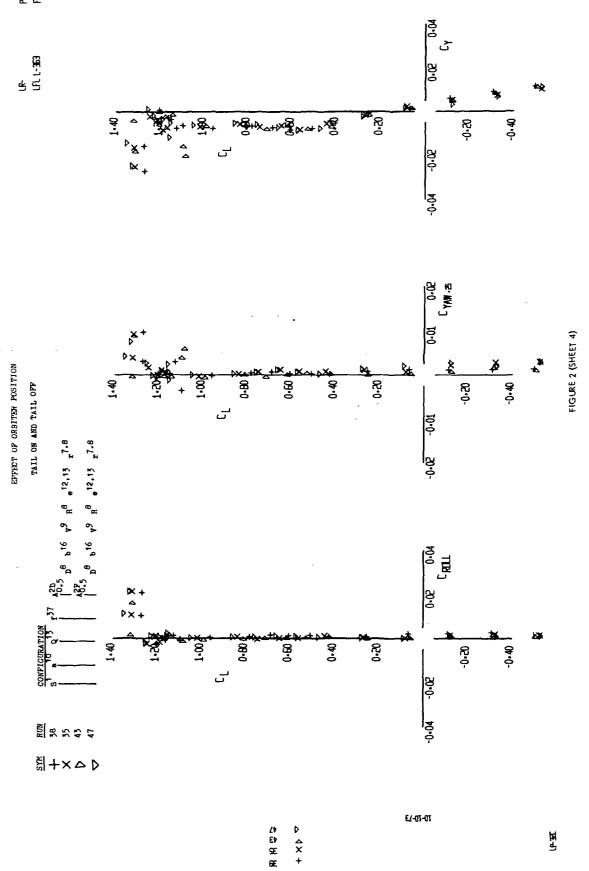
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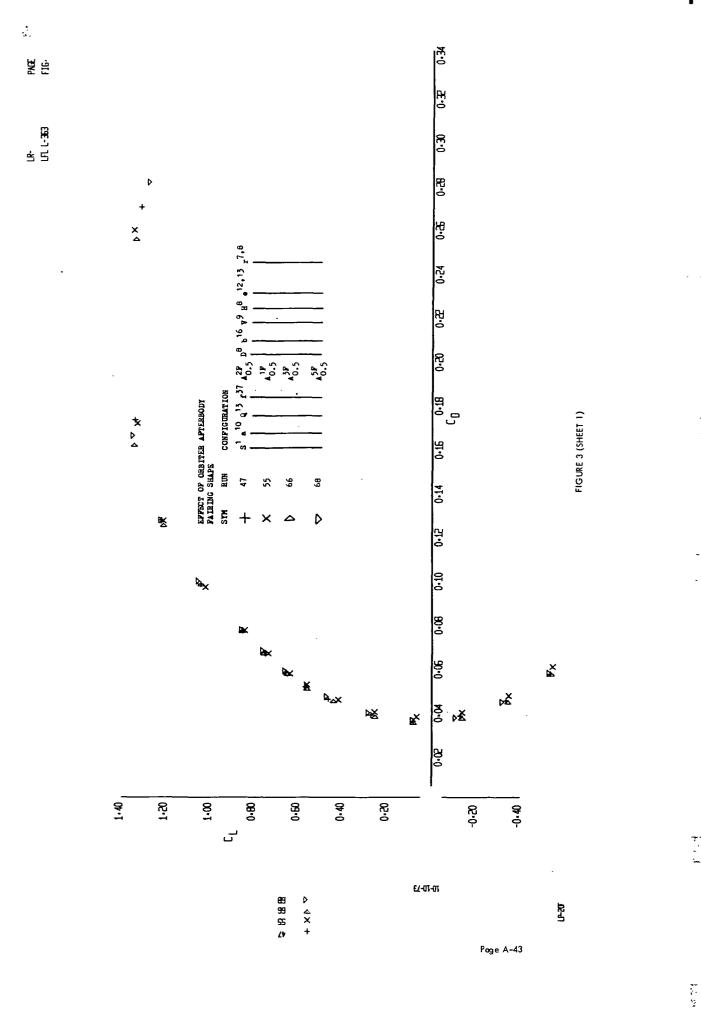
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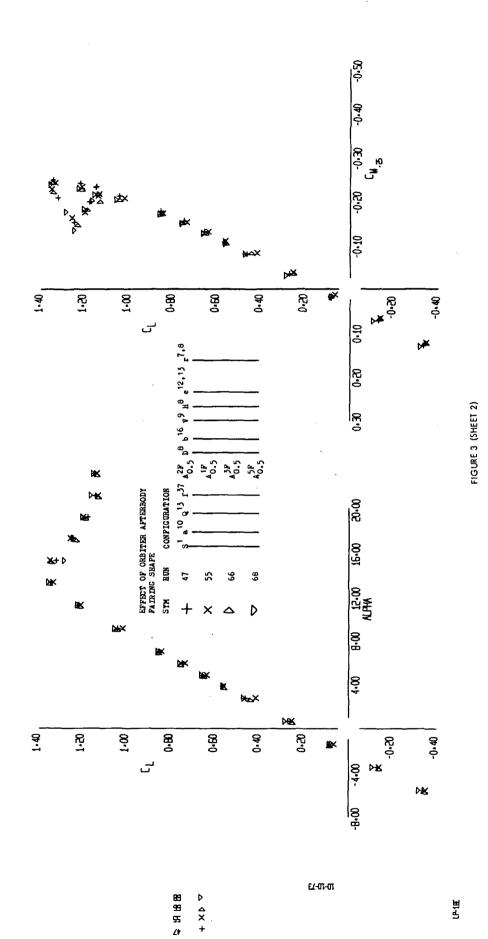
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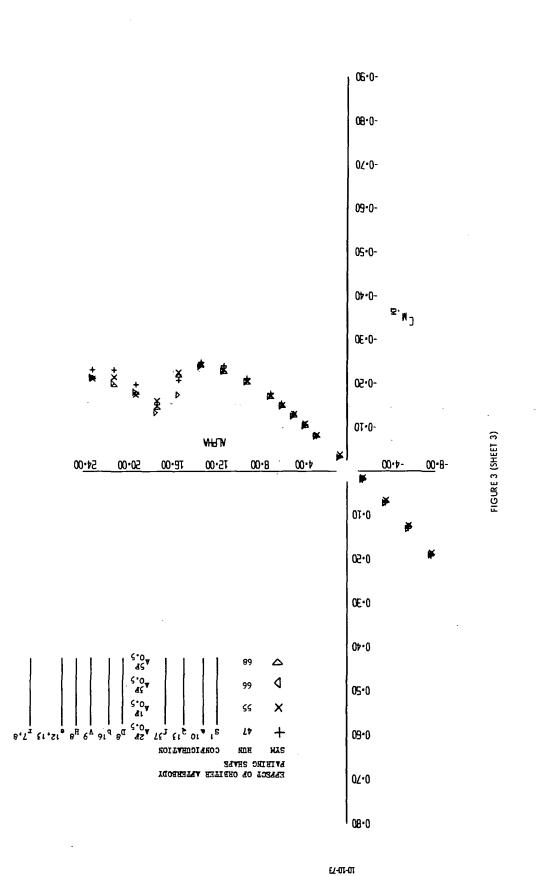
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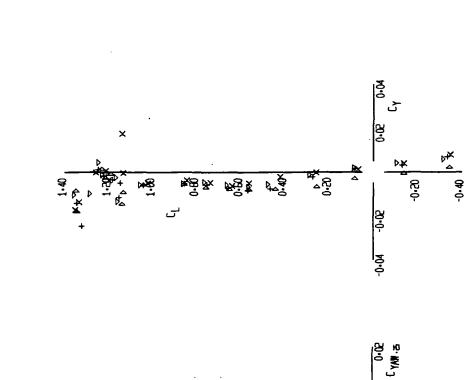
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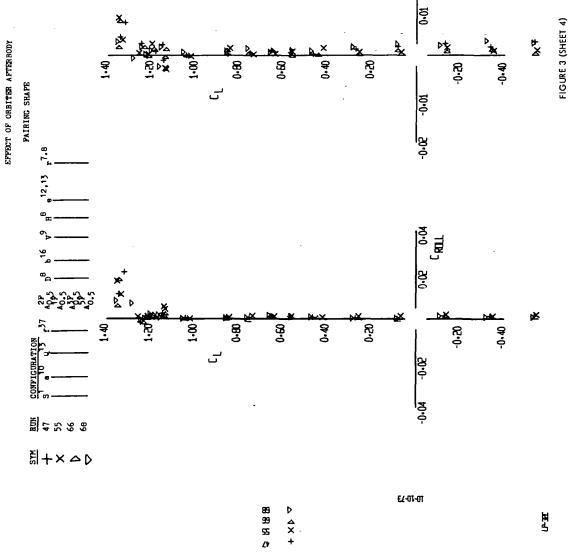
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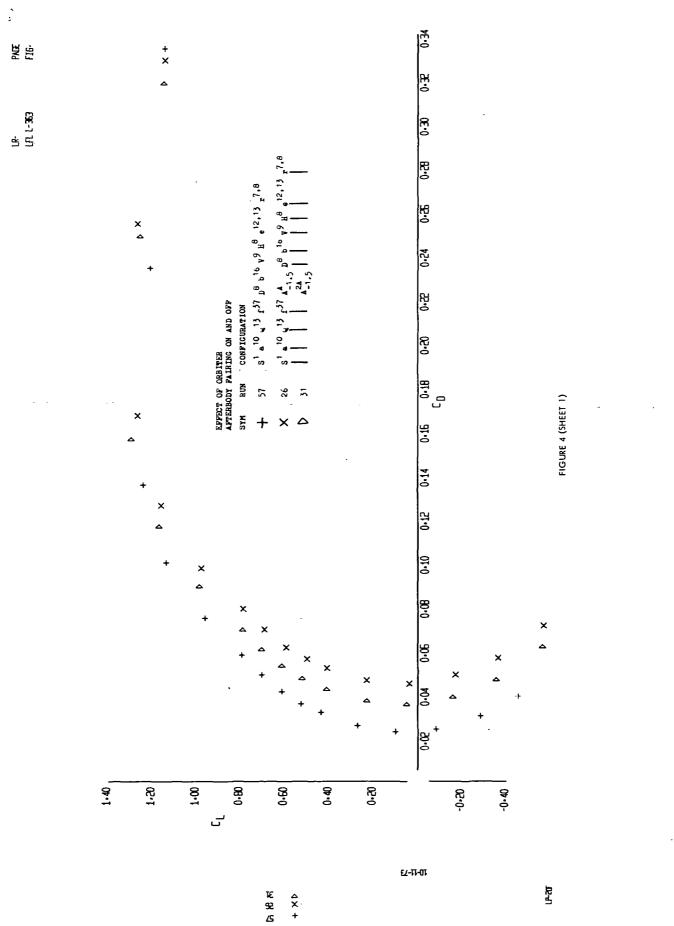


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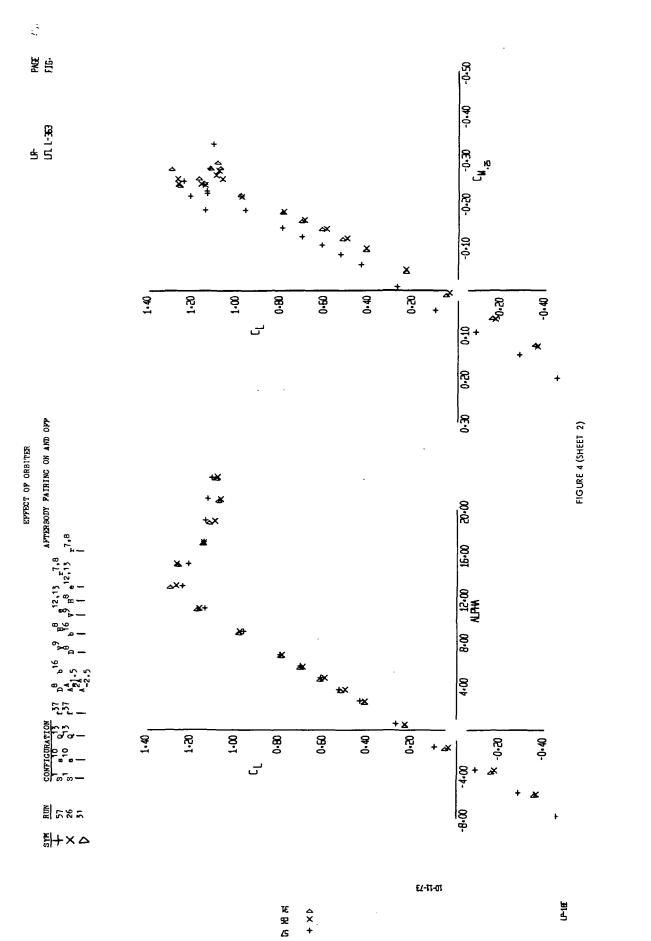
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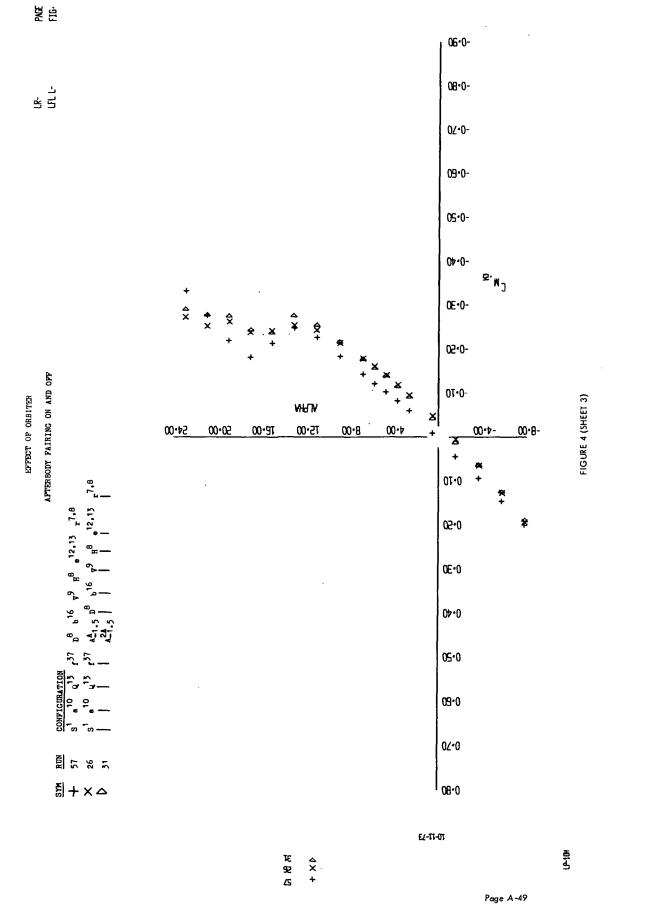
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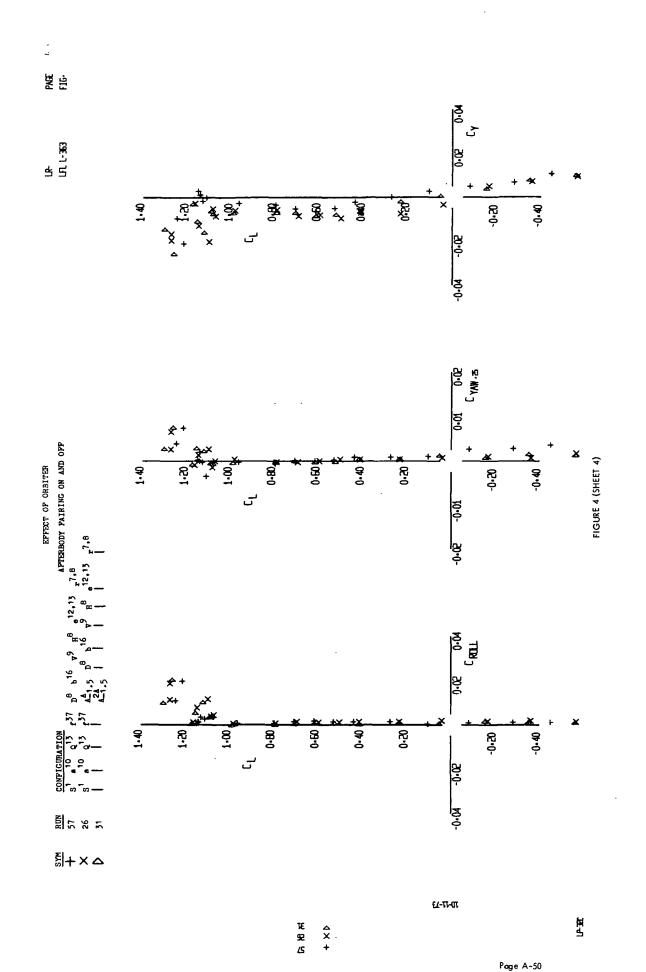
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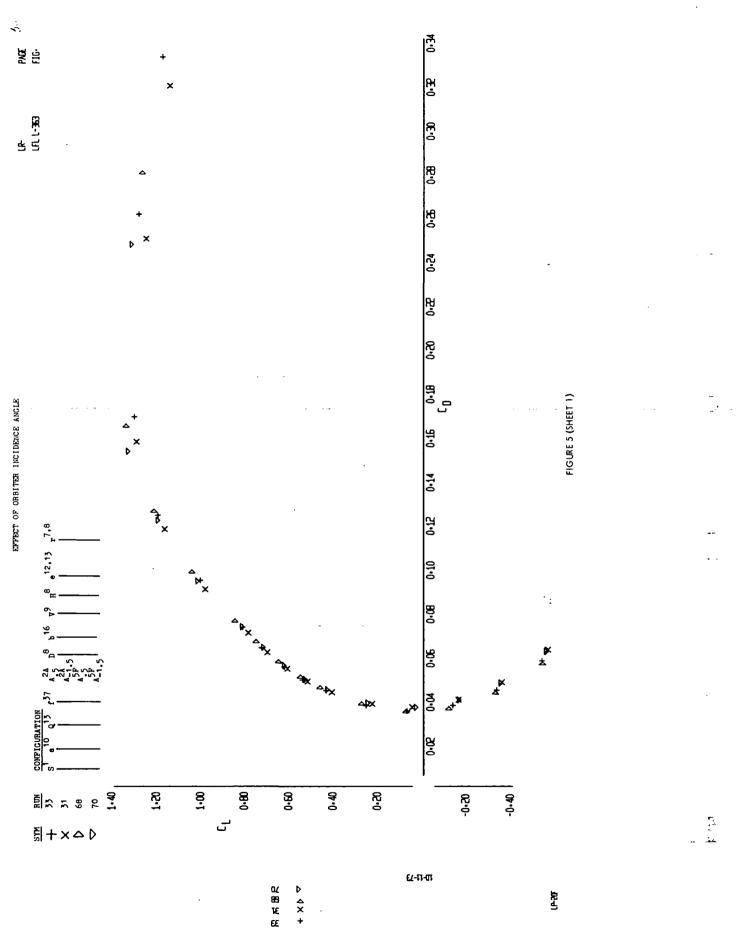




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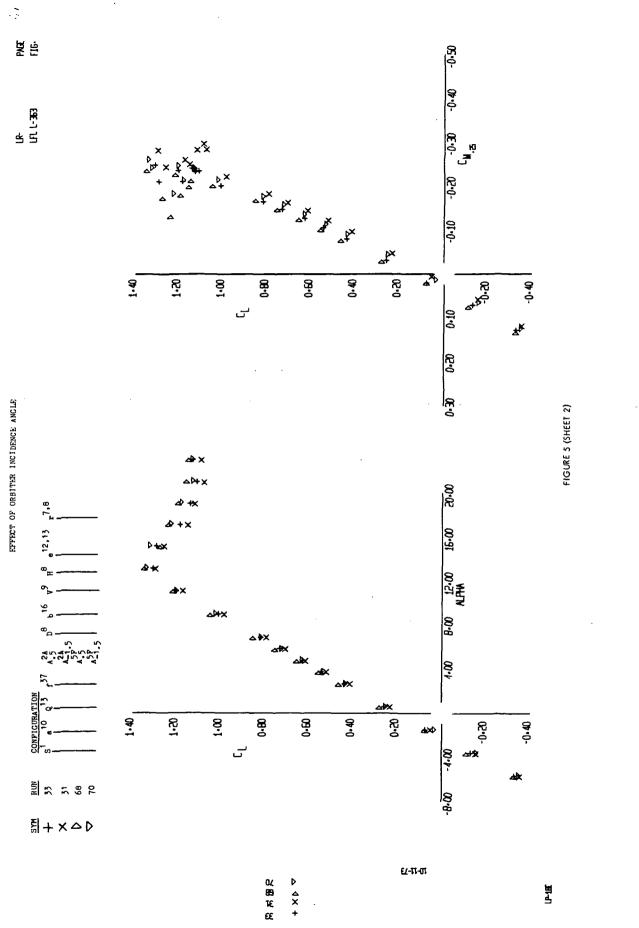
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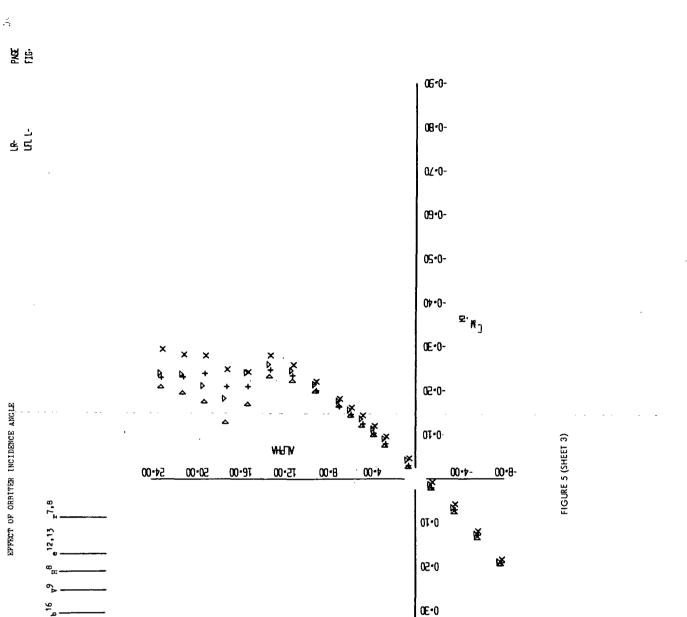
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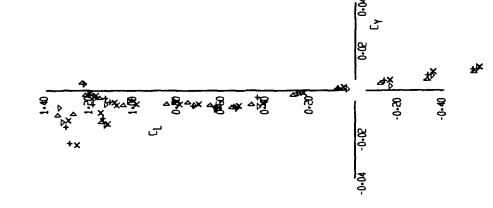
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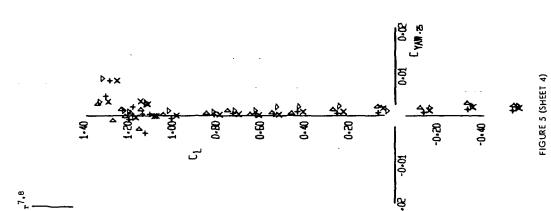


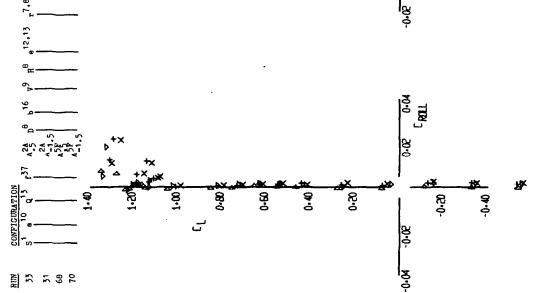


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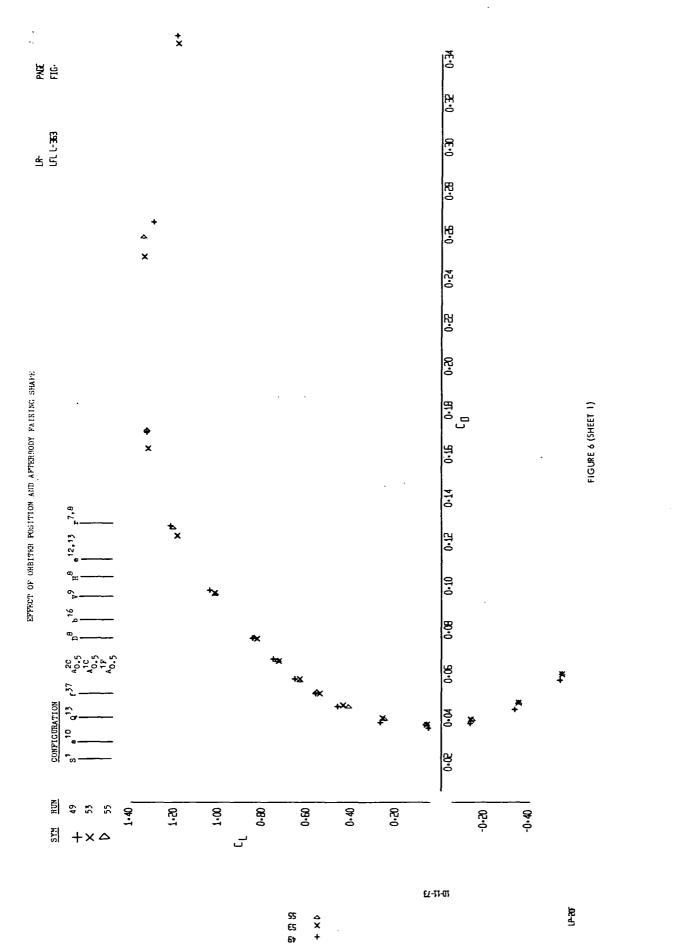


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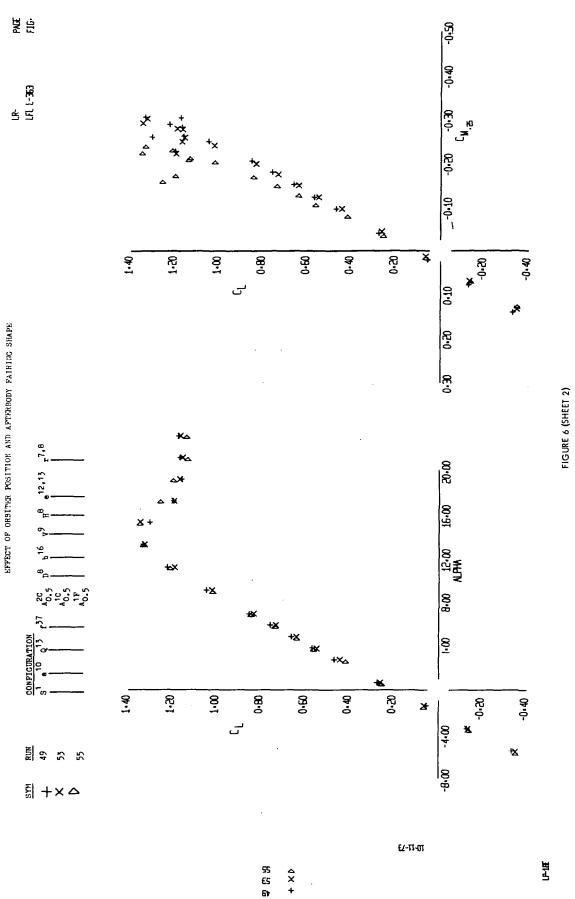
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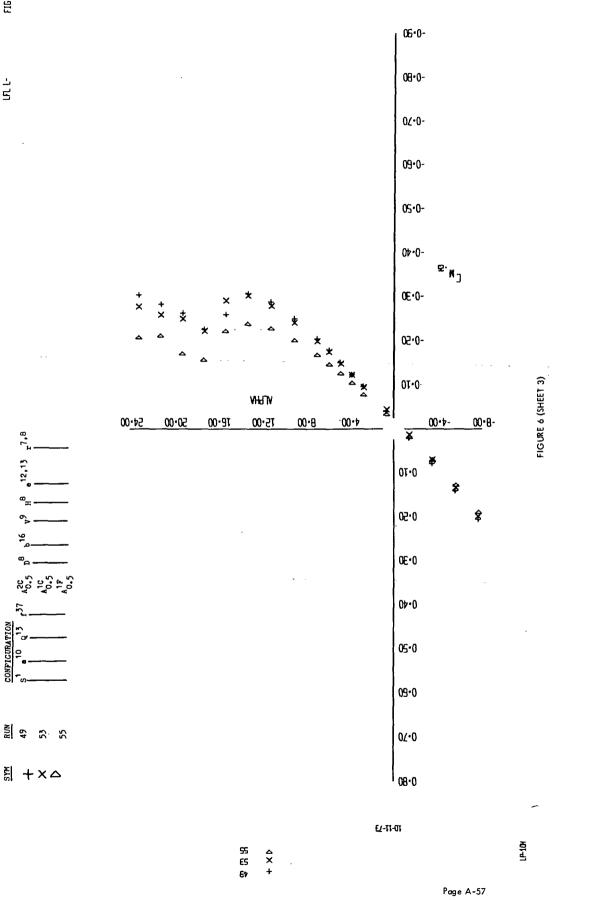


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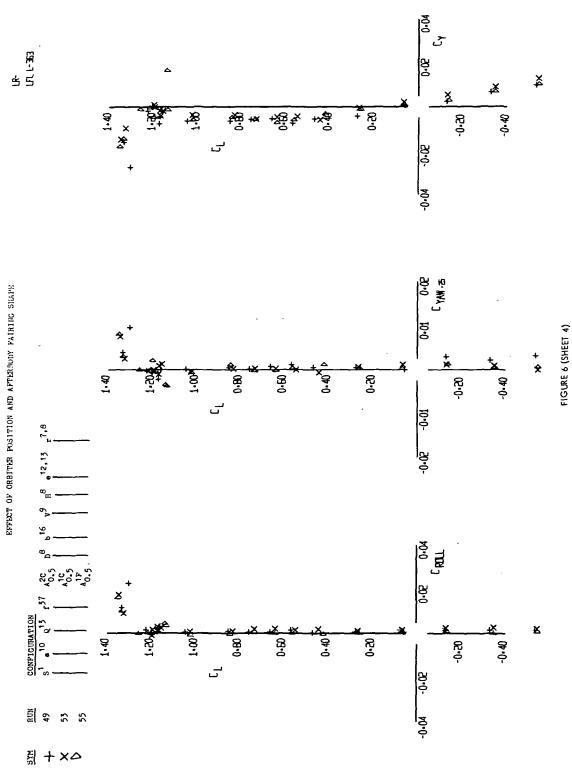
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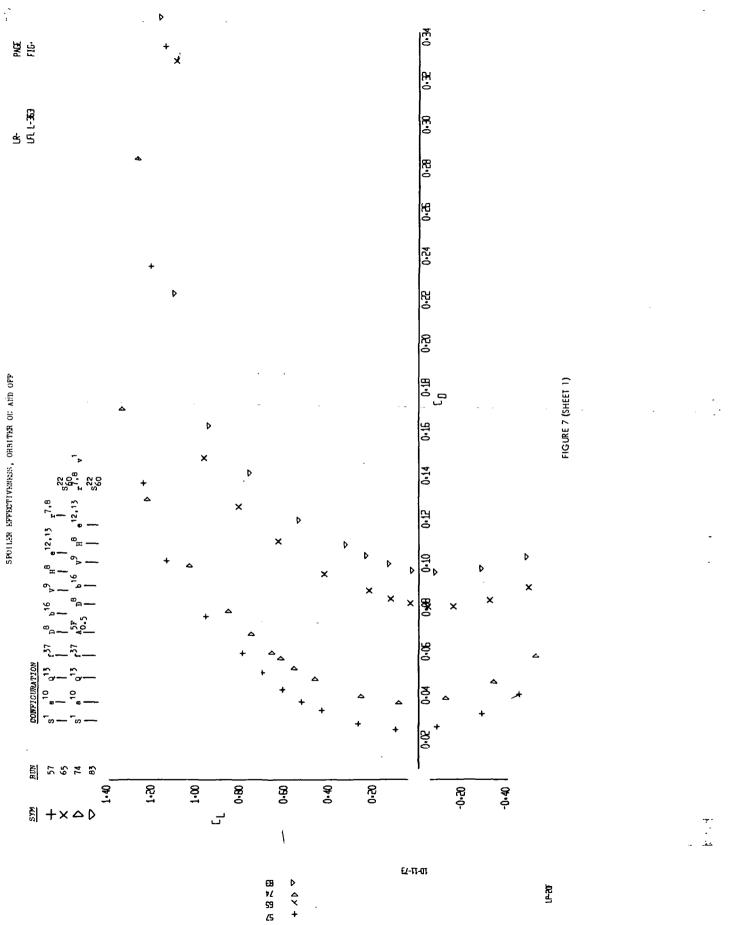


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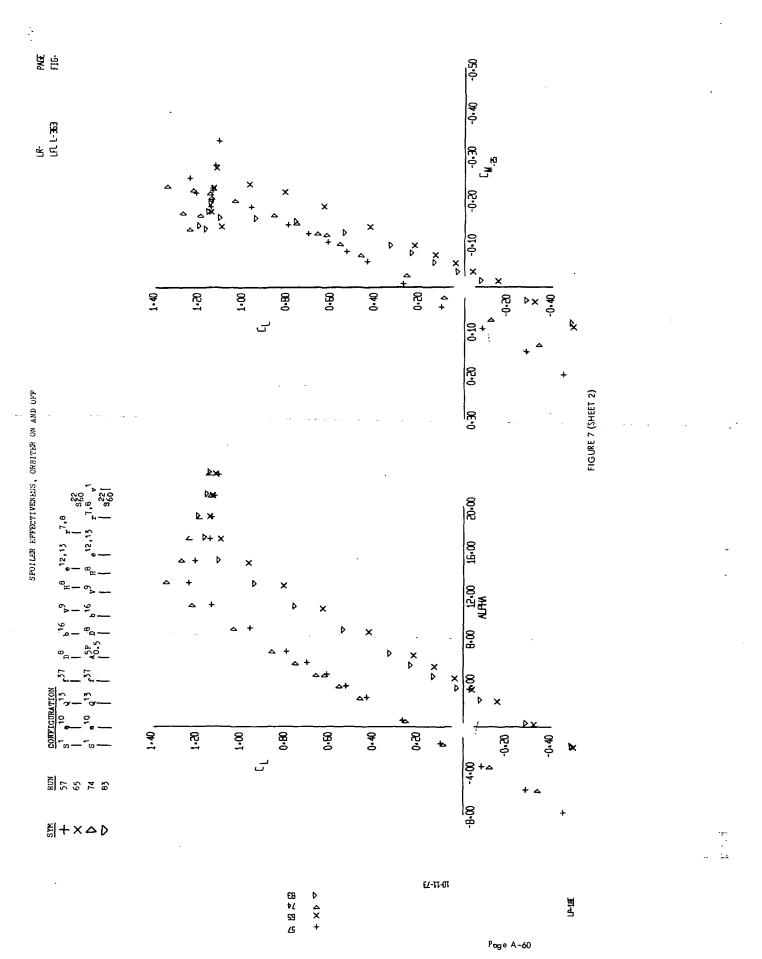
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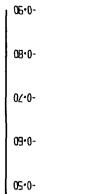
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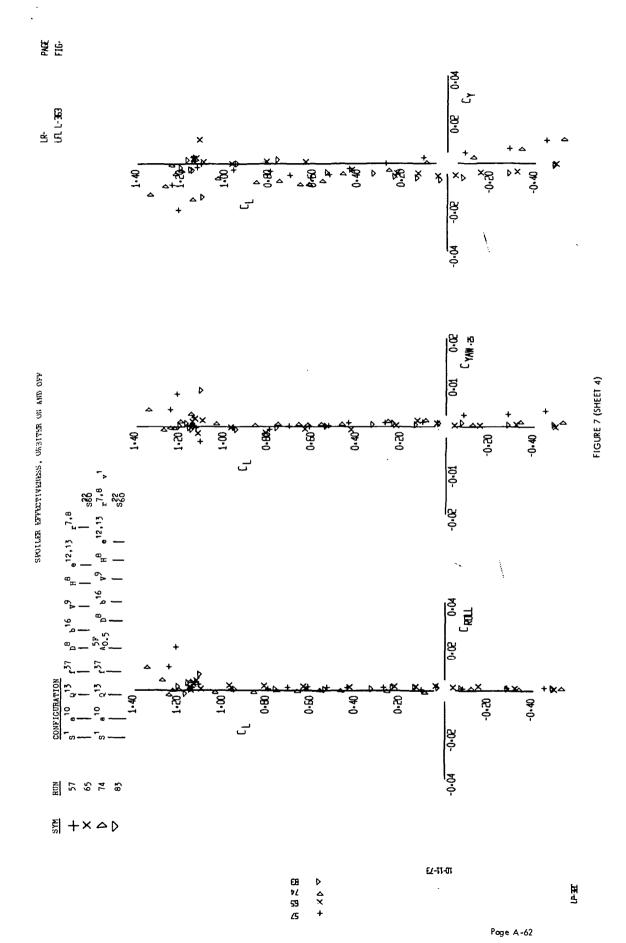




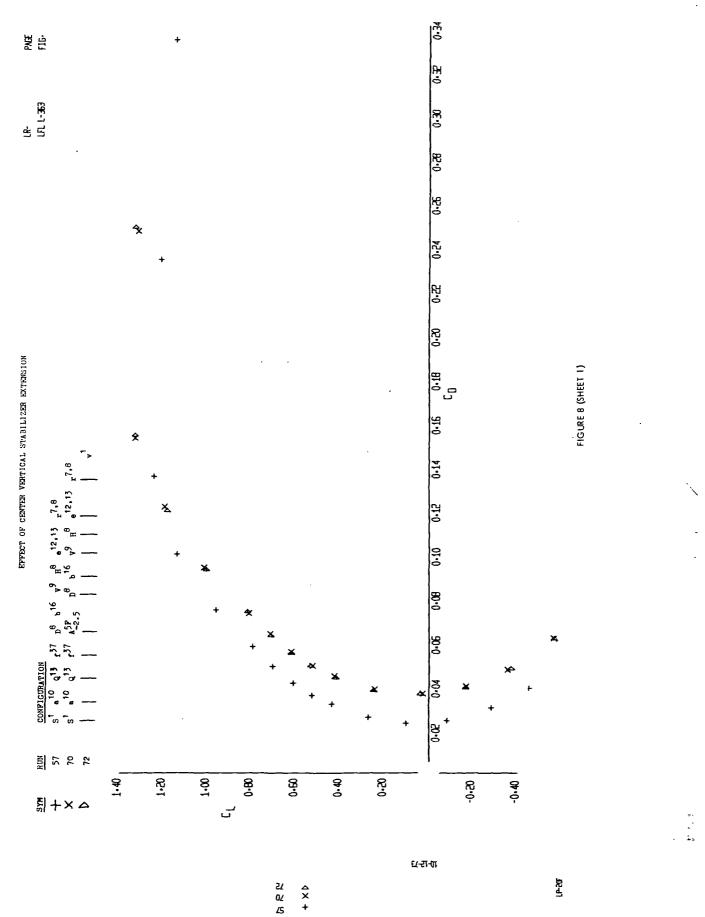
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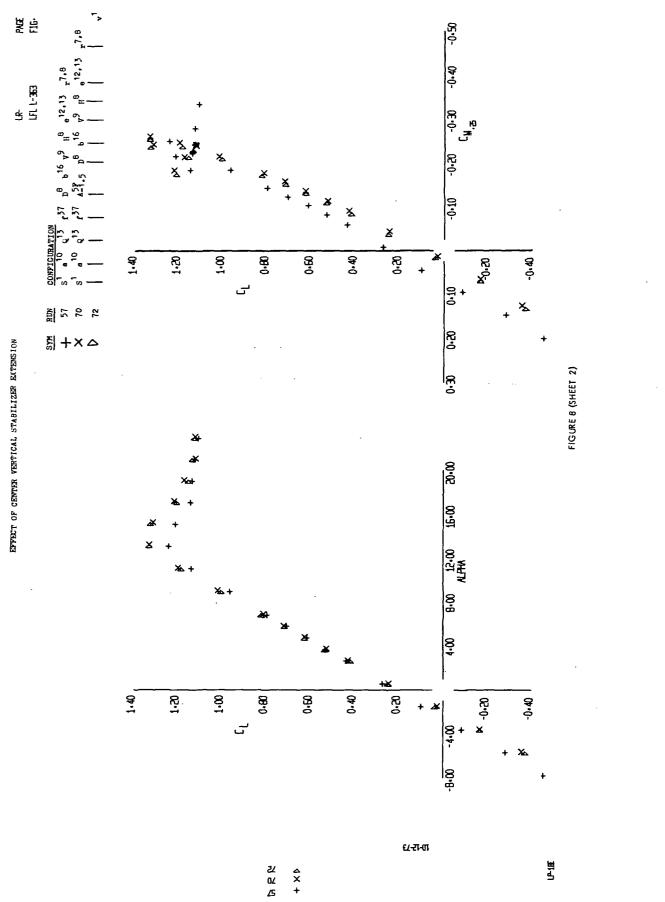
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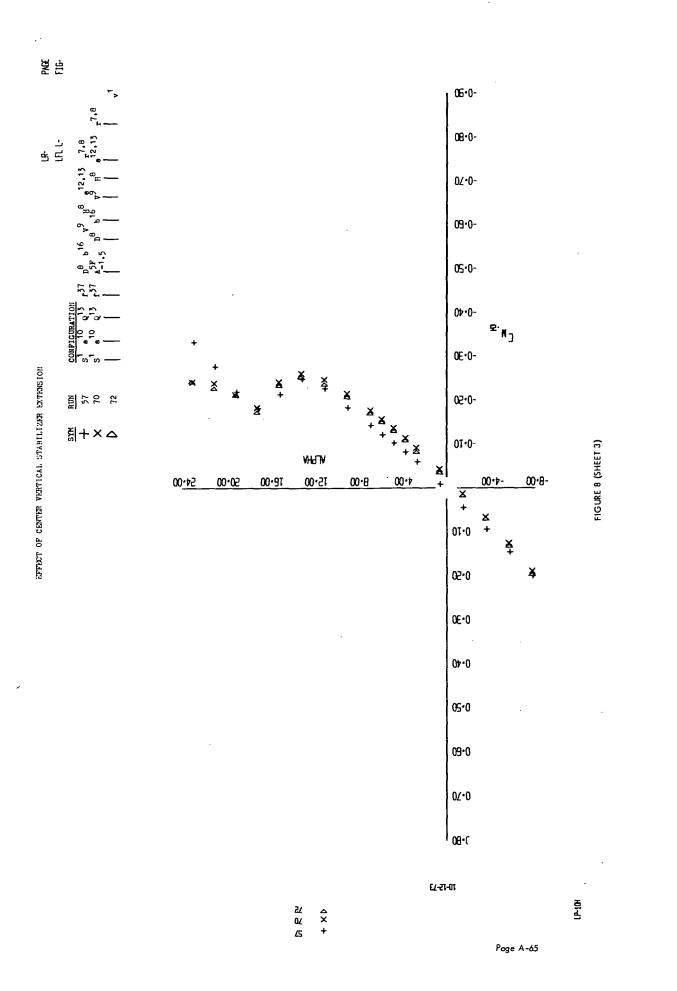
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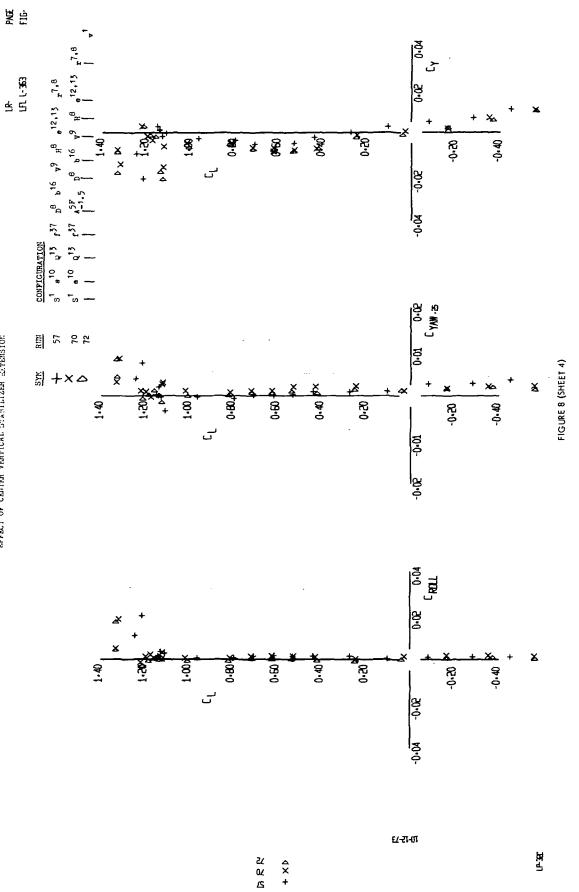
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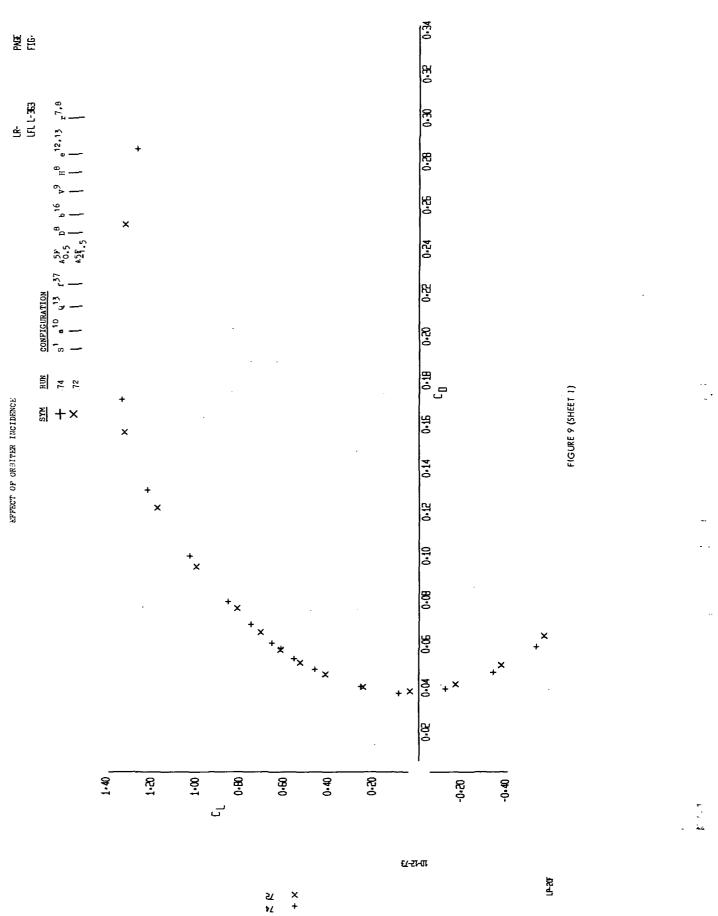


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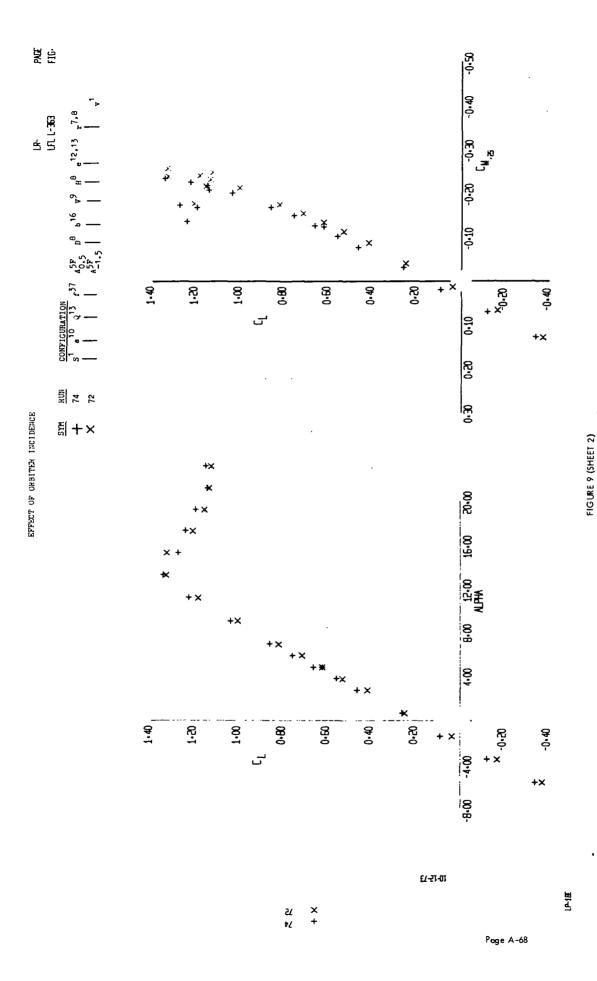
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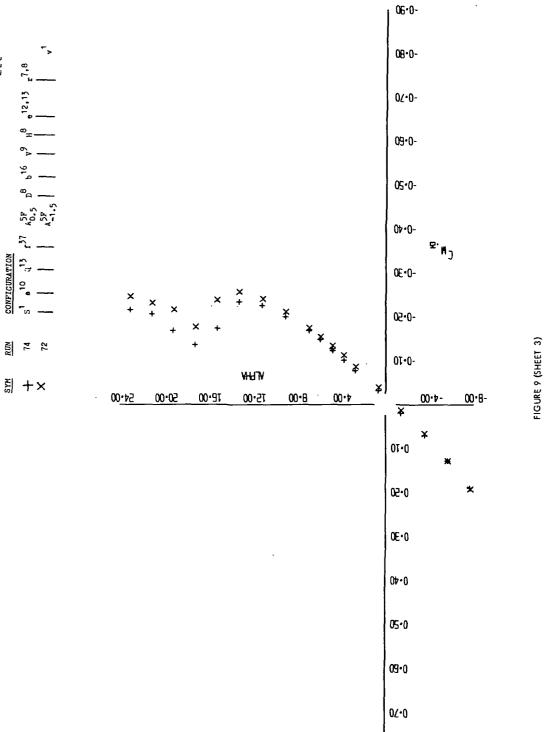
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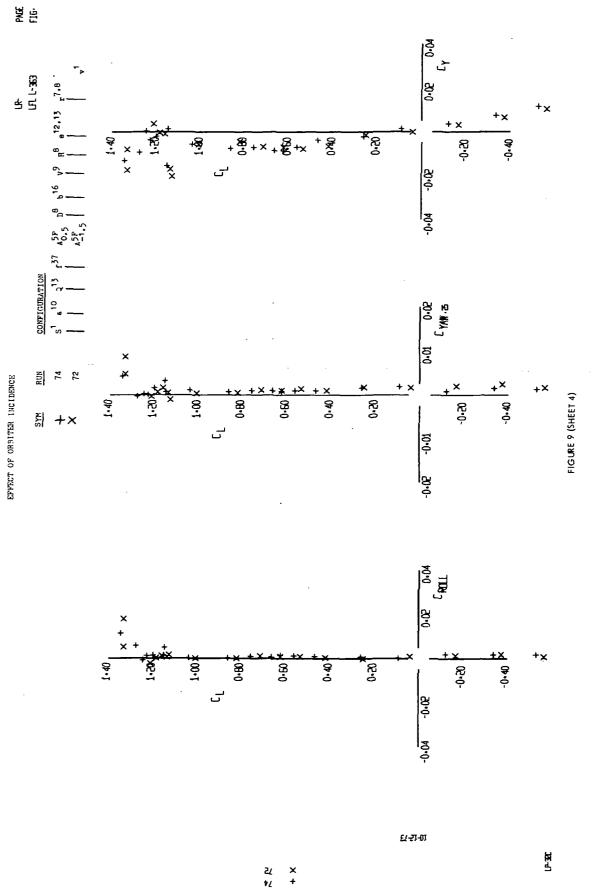
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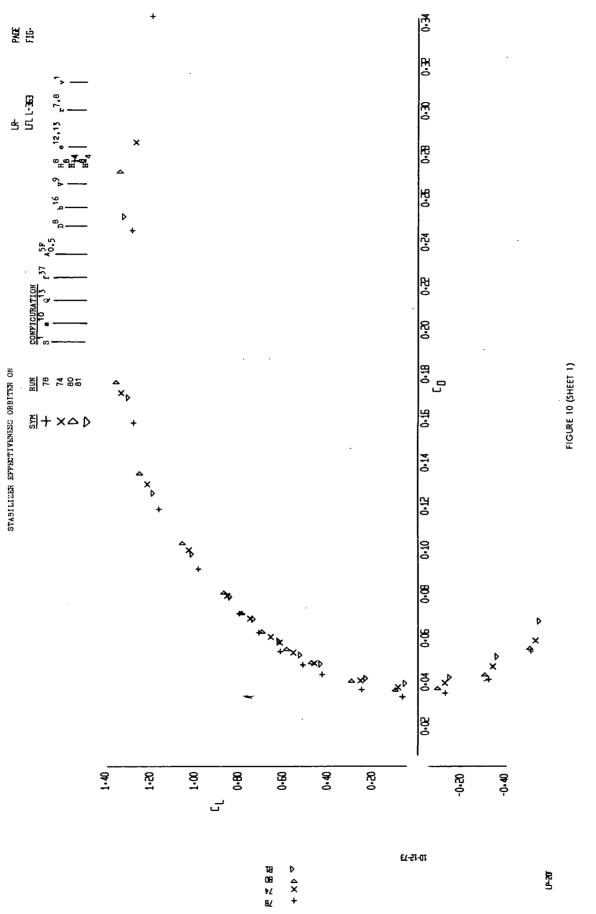




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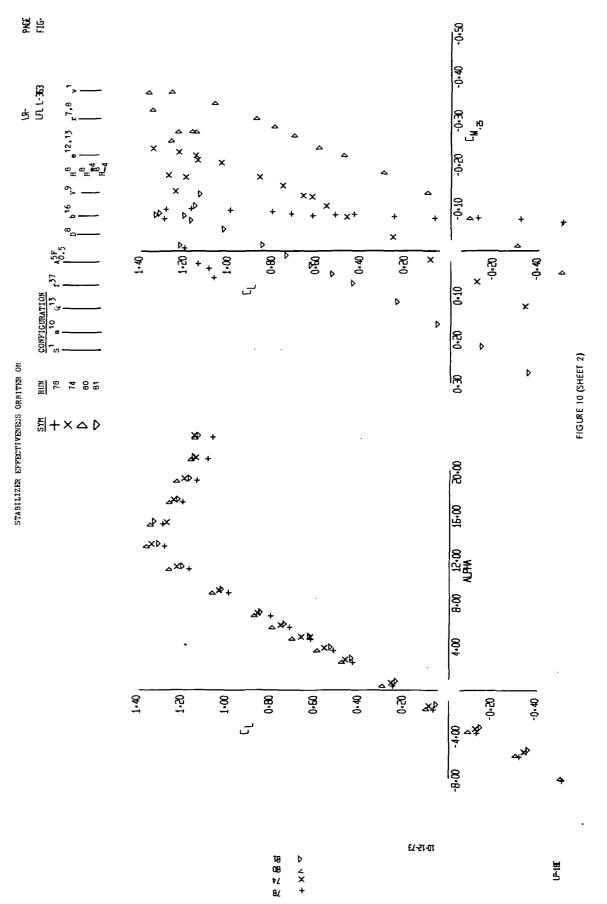
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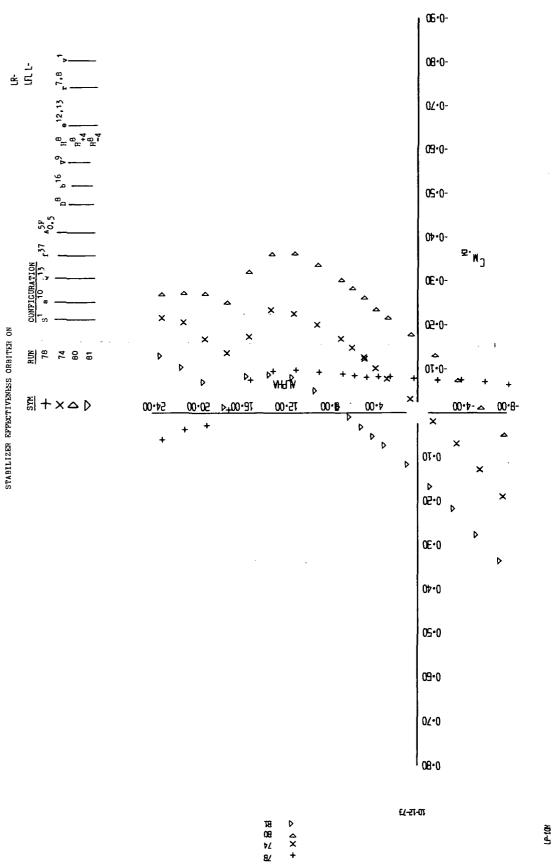
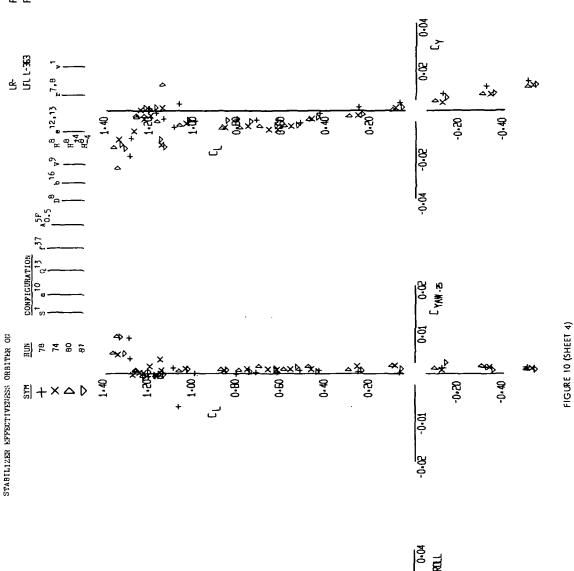


FIGURE 10 (SHEET 3)

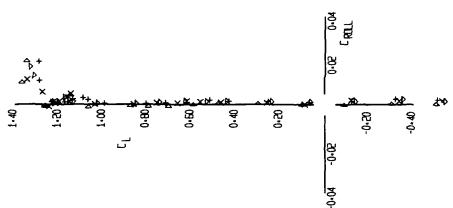
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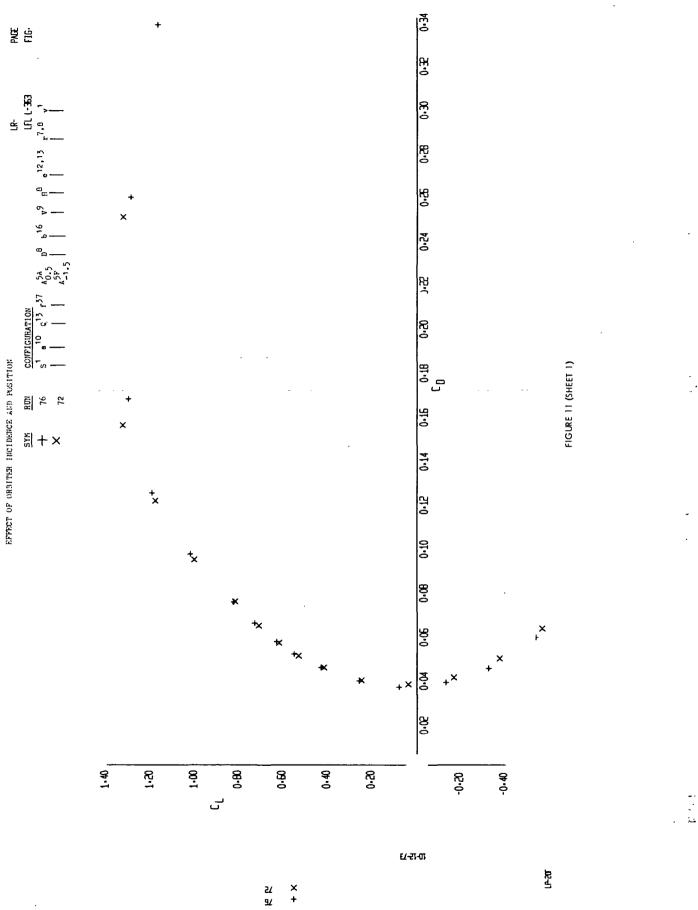
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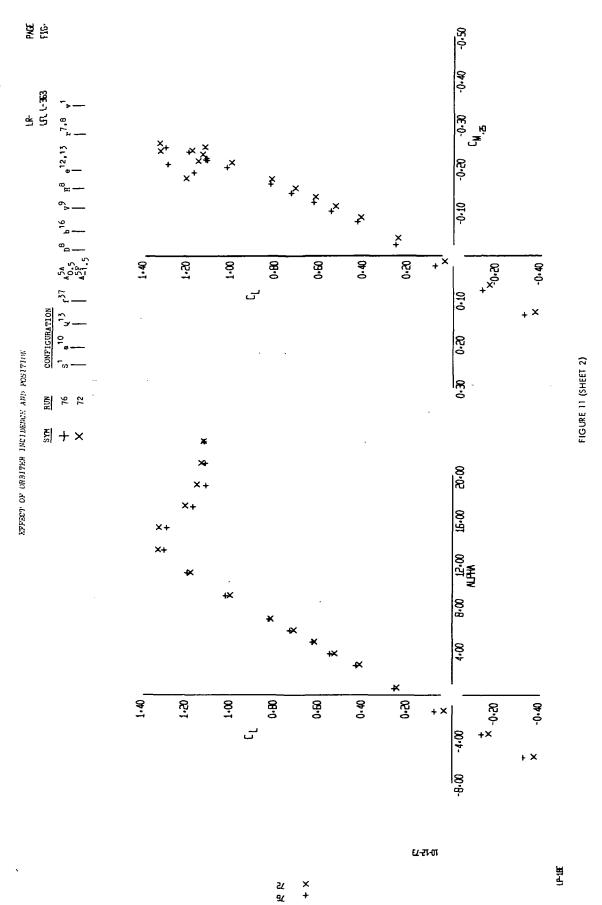
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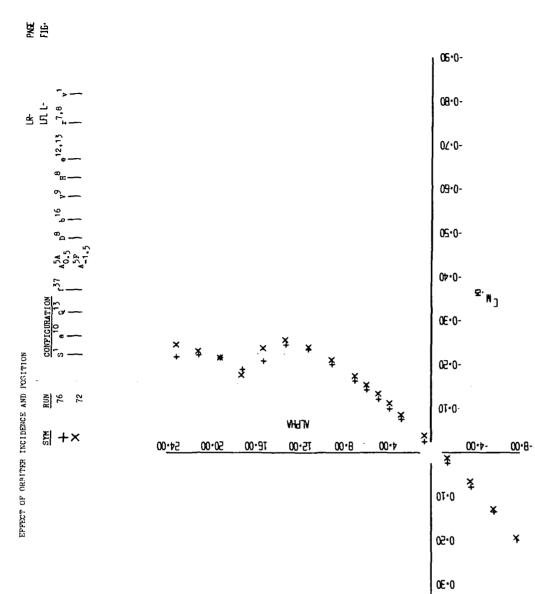


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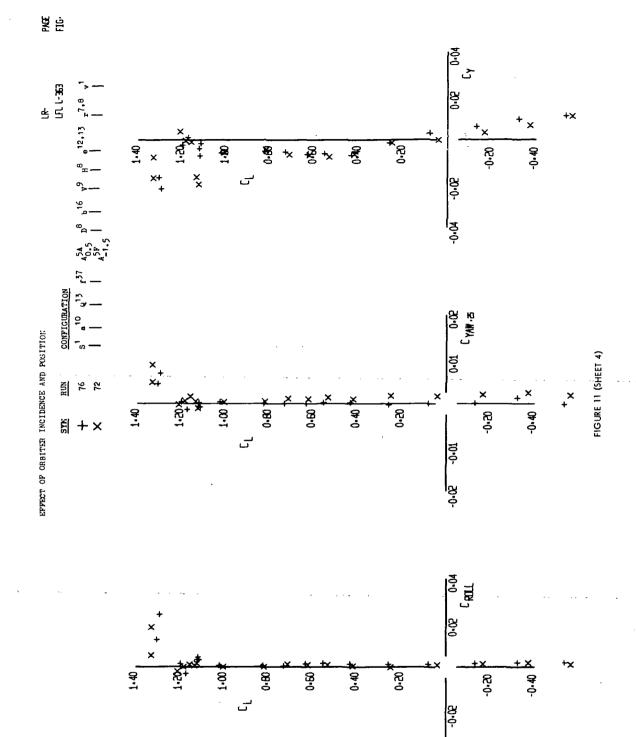
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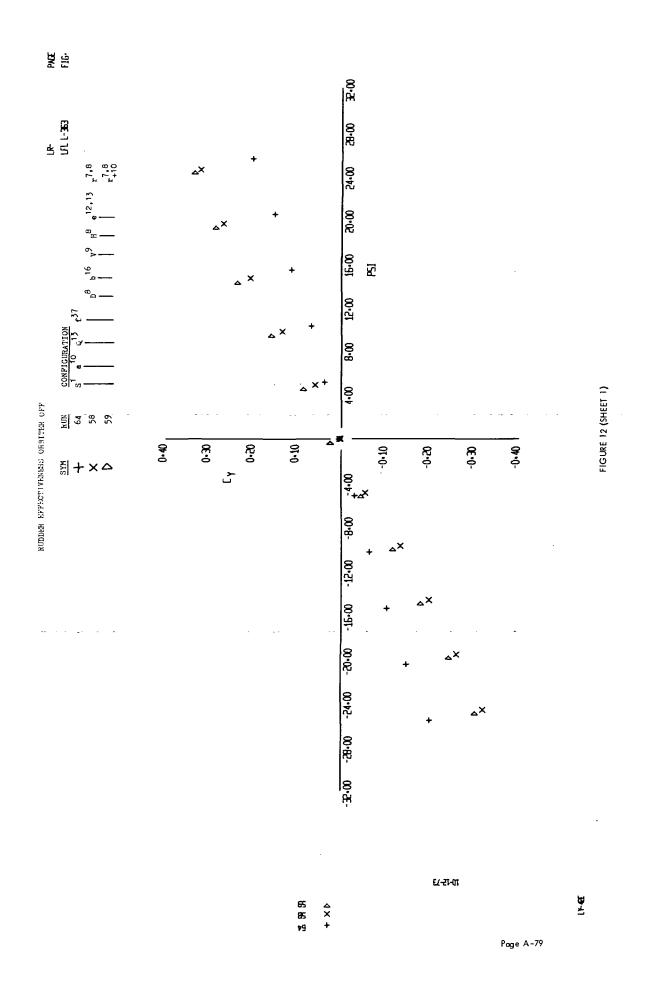
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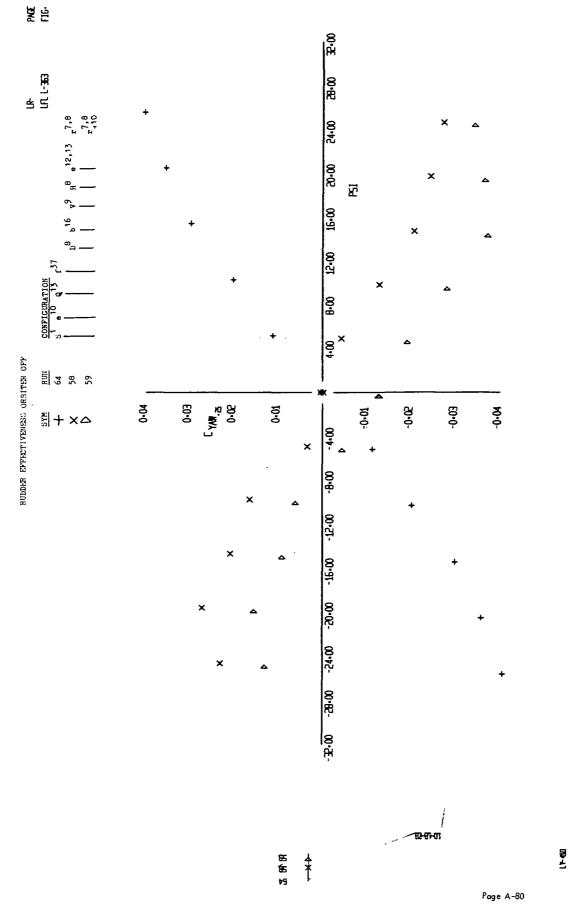
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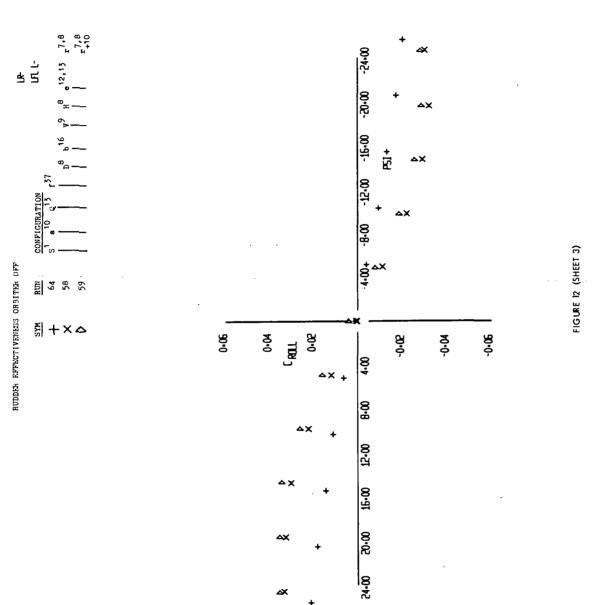
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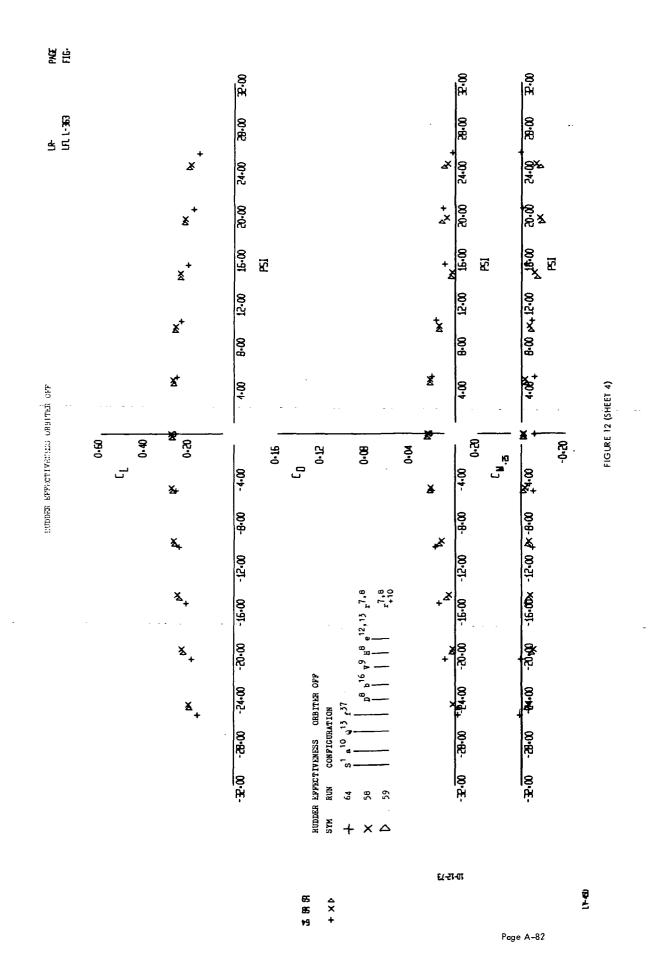
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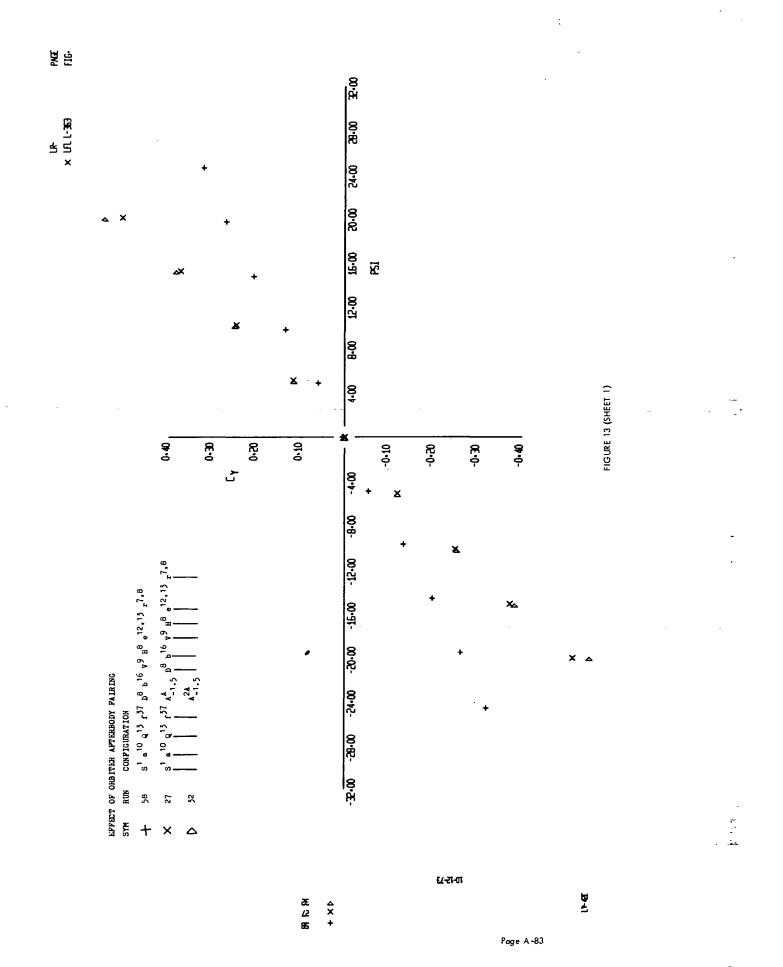
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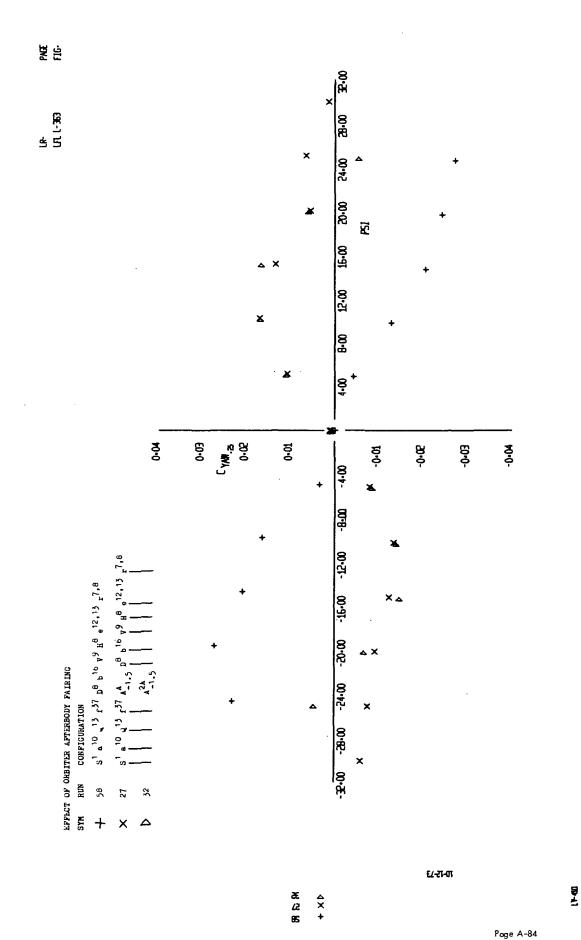


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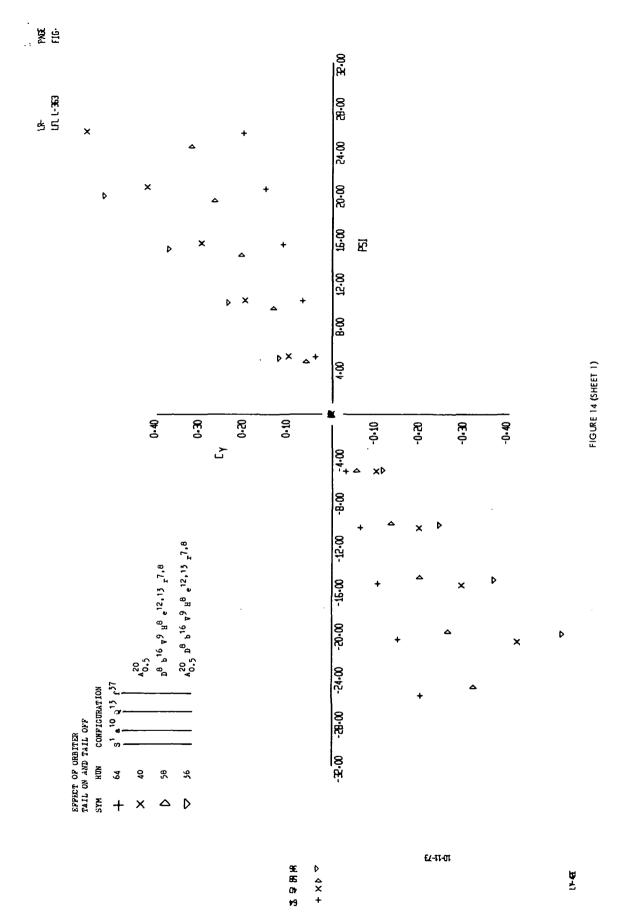


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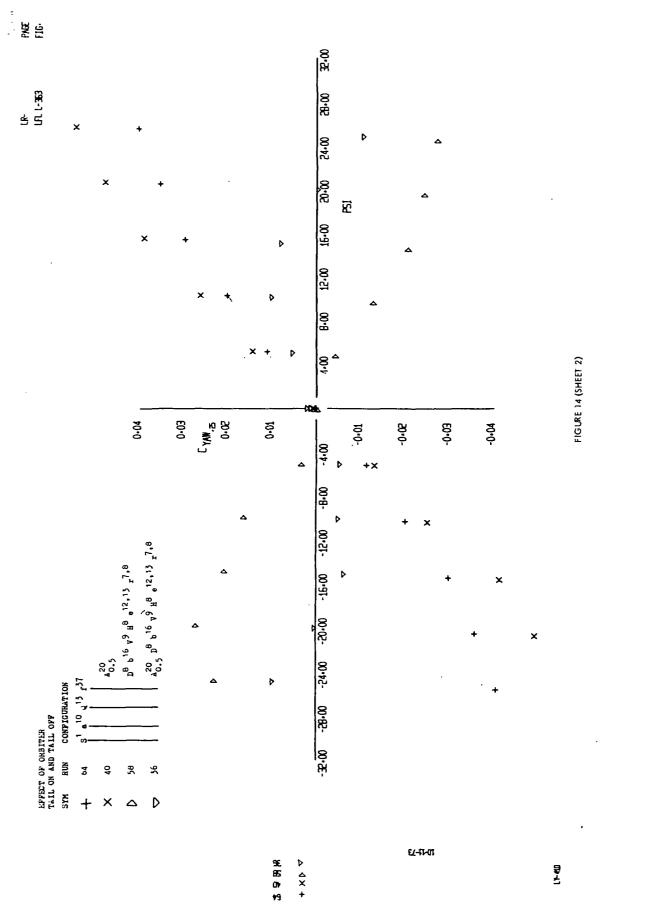
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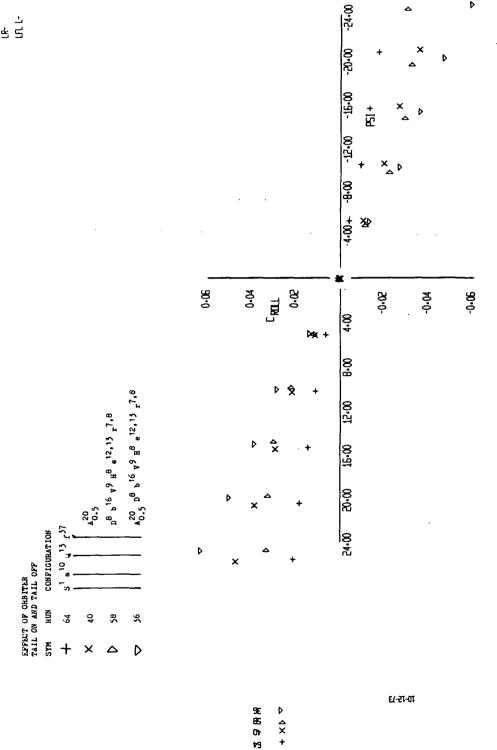


FIGURE 14 (SHEET 3)

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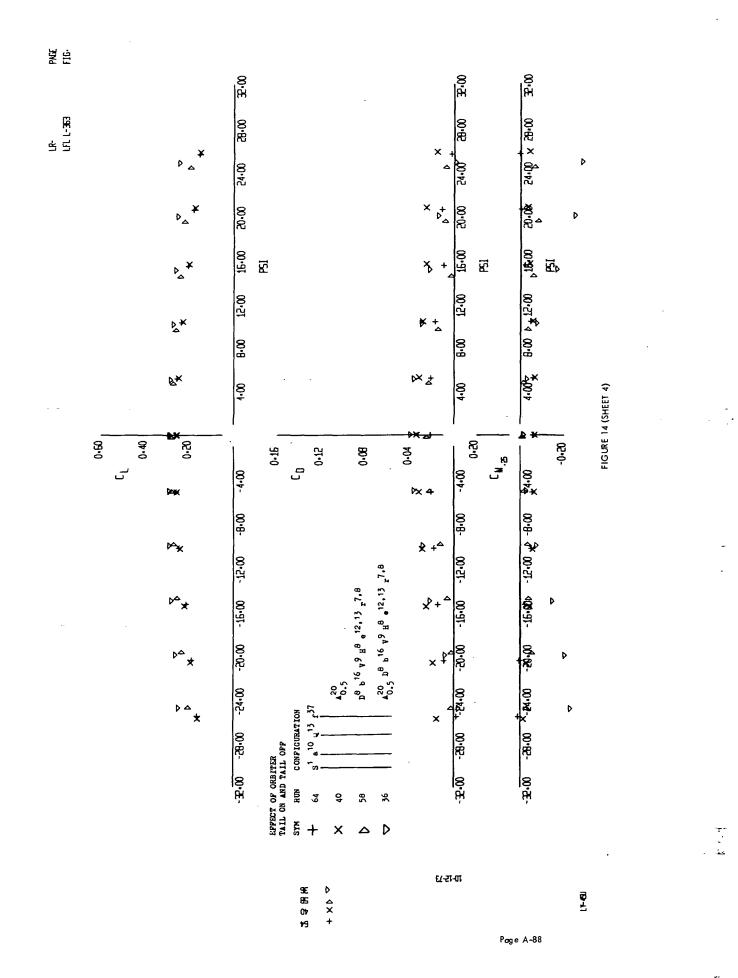
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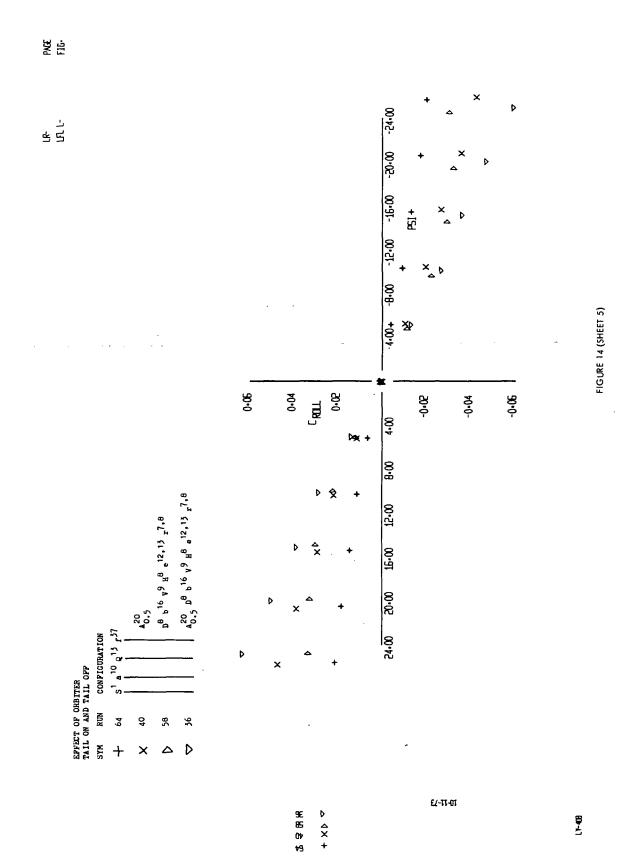
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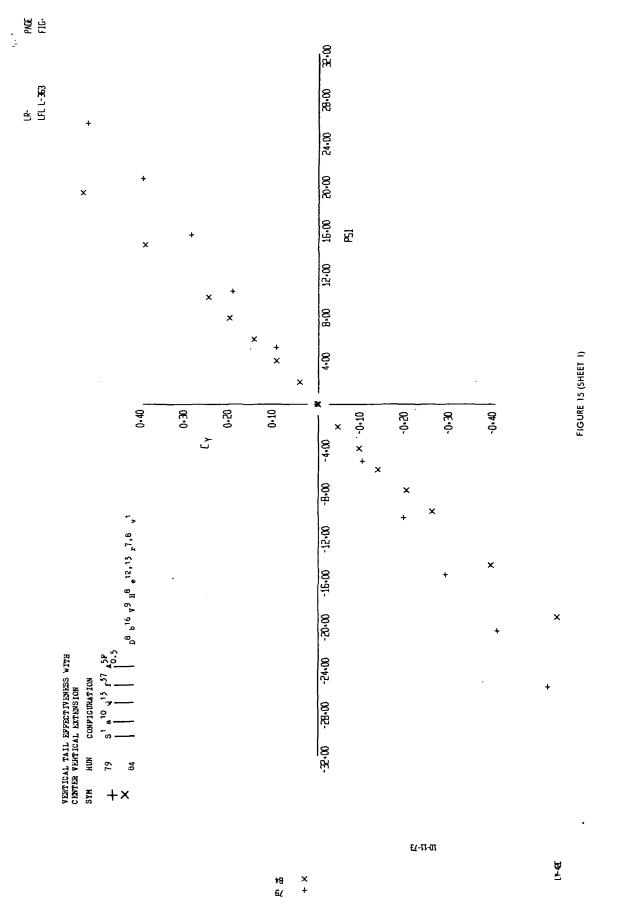


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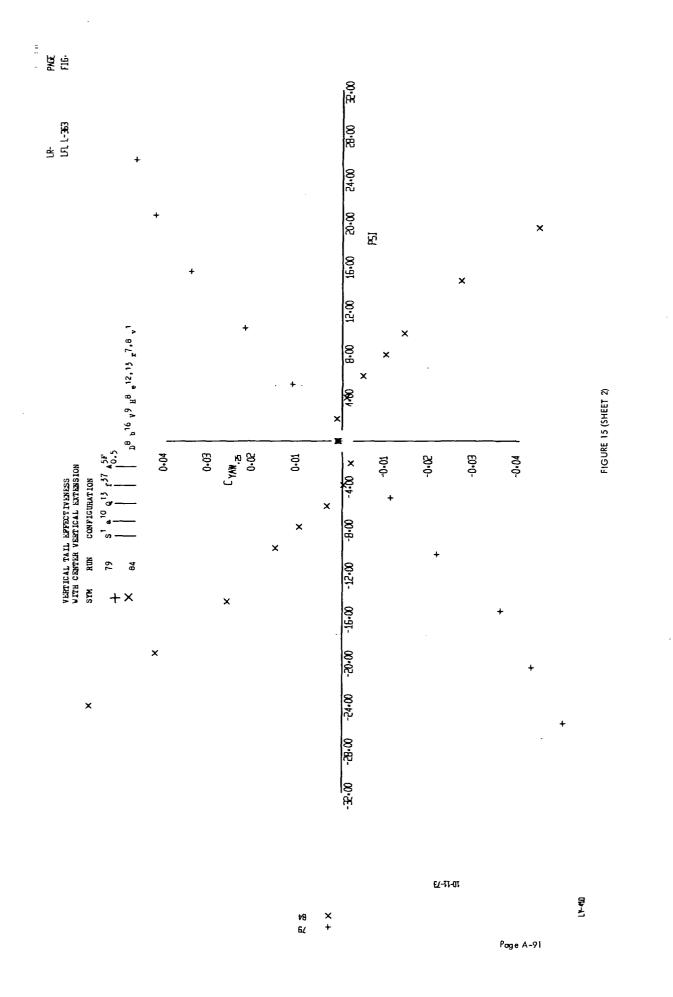


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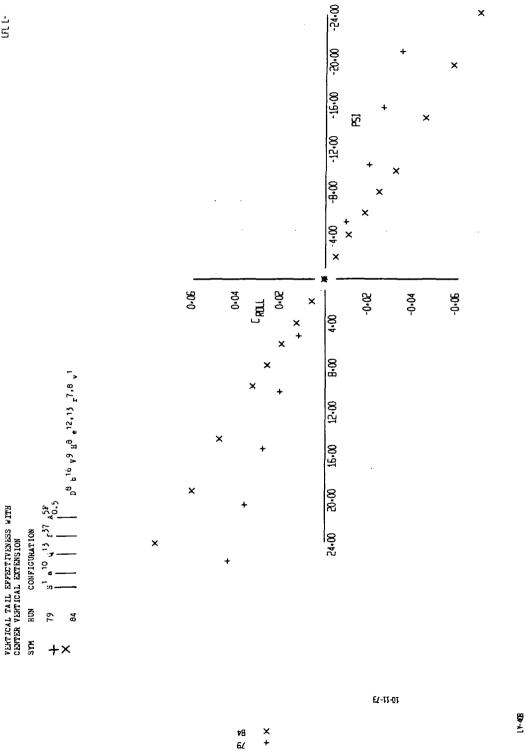
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FIGURE 15 (SHEET 3)

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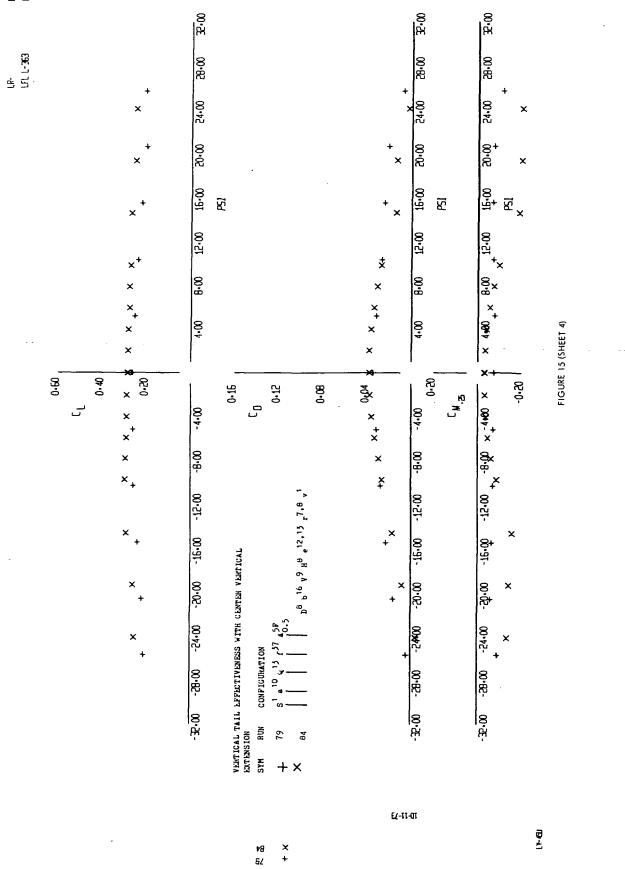
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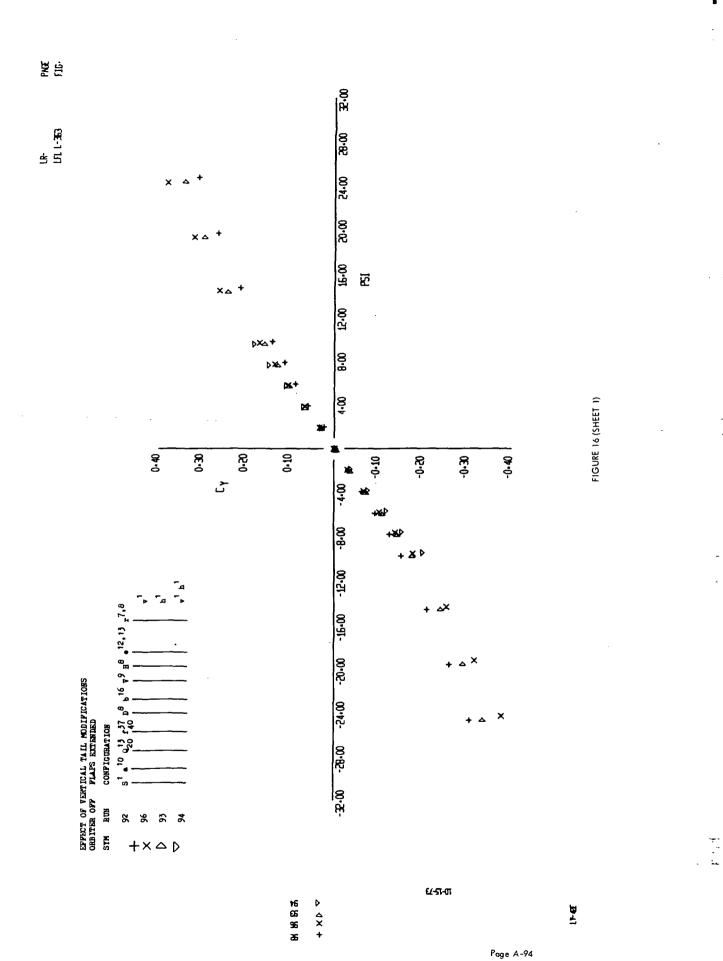
Page A-92



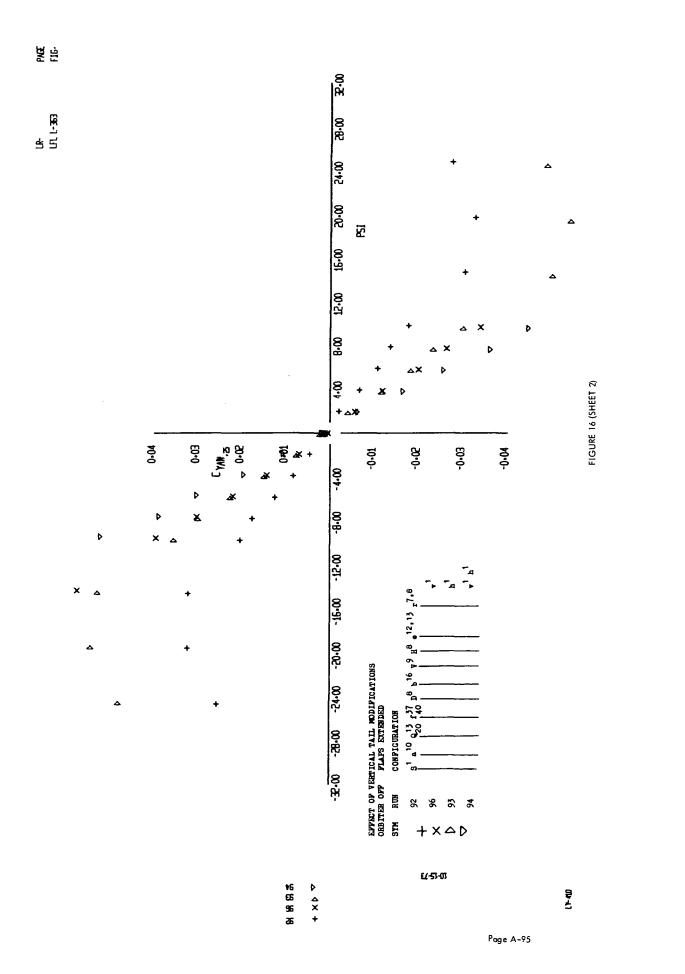


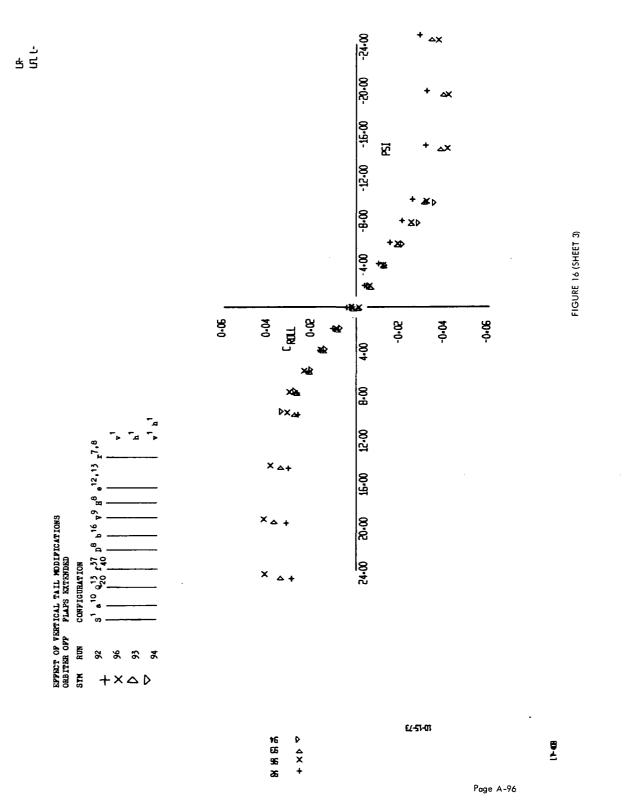
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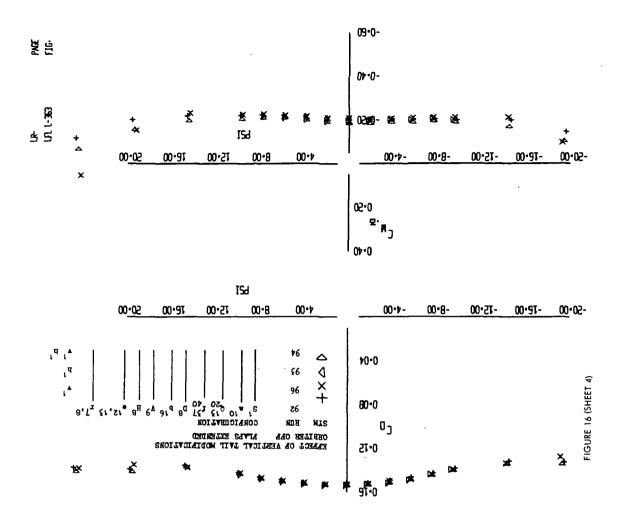
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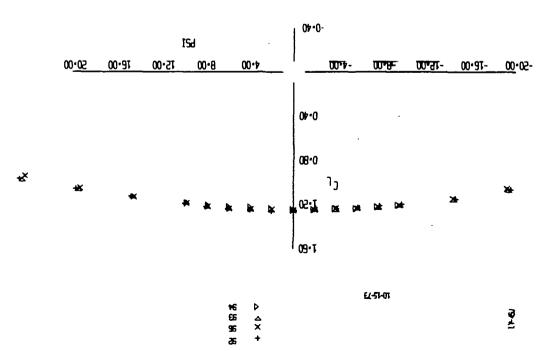
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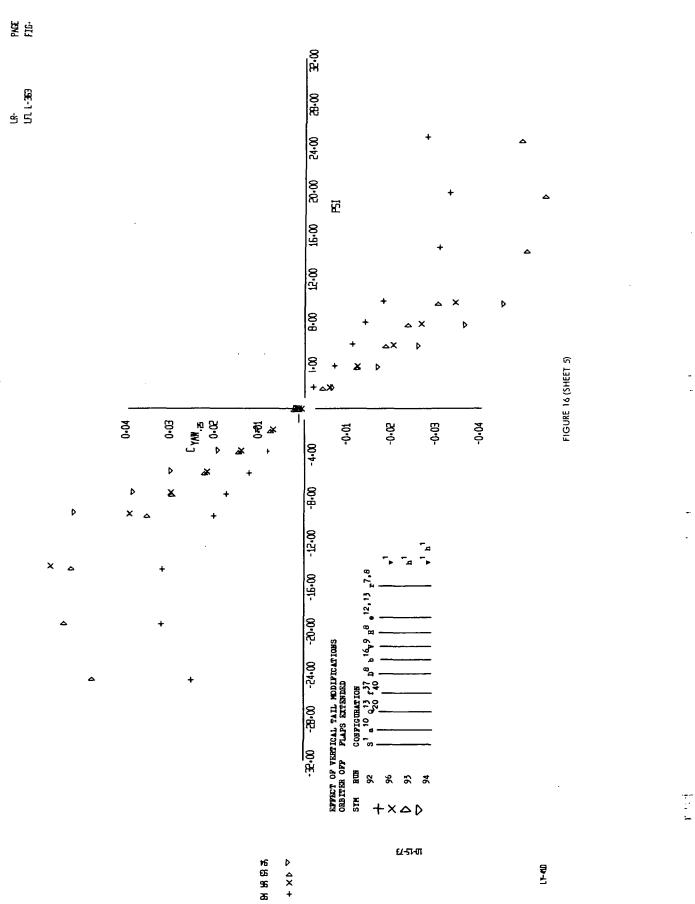


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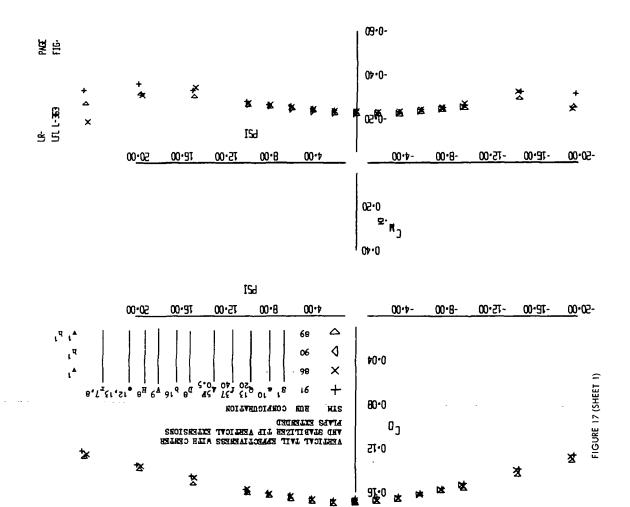
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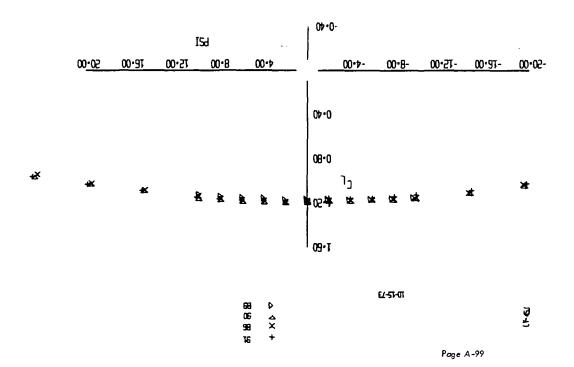


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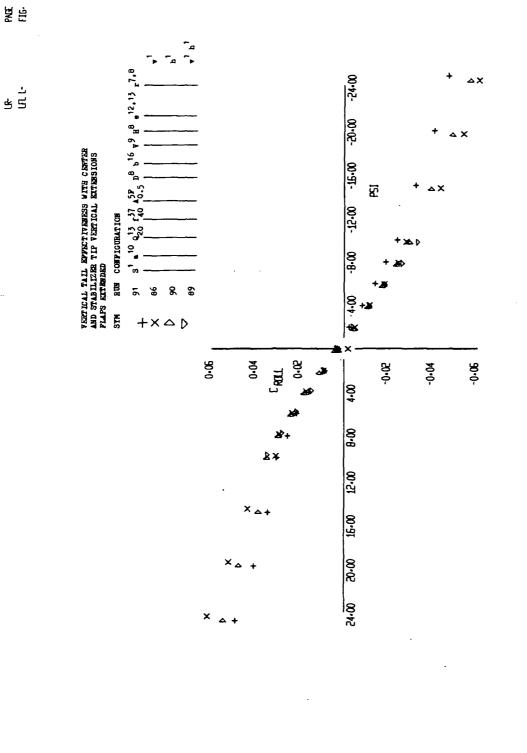


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FIGURE 17 (SHEET 2)

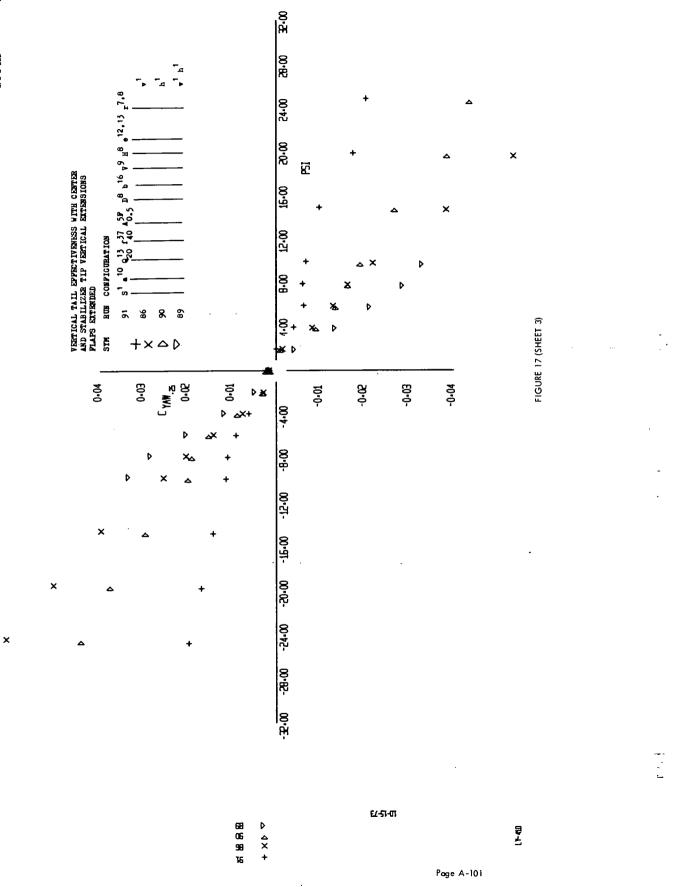
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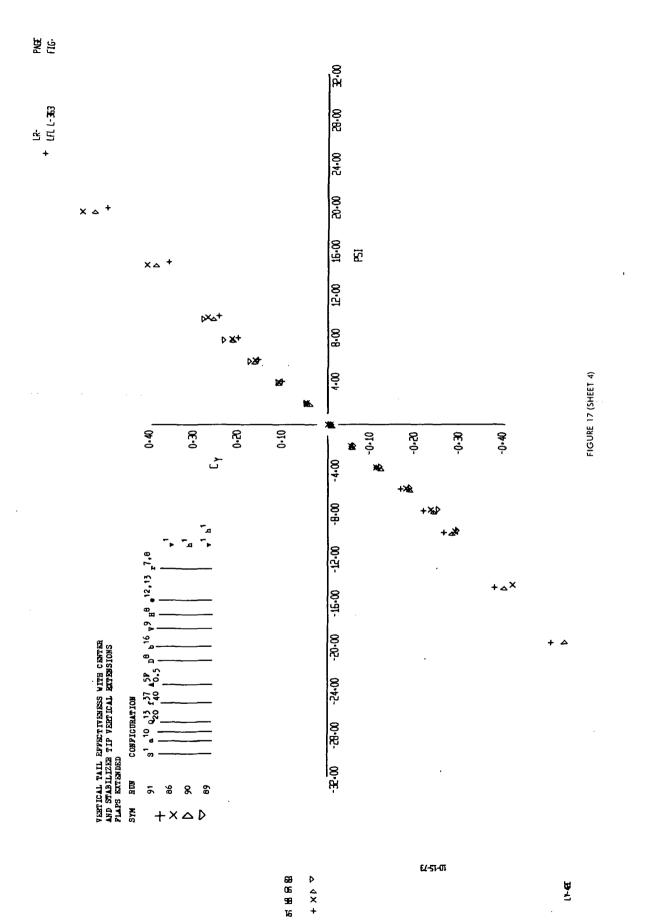


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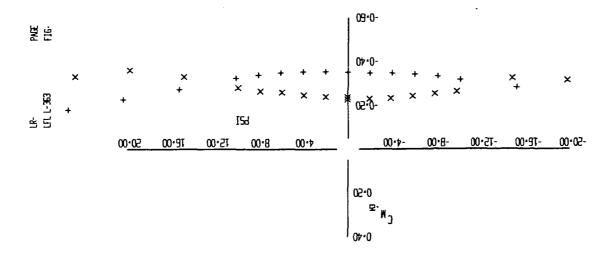
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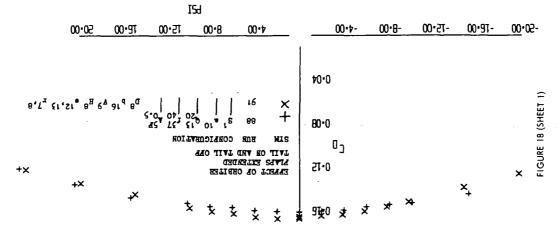
Page A-102

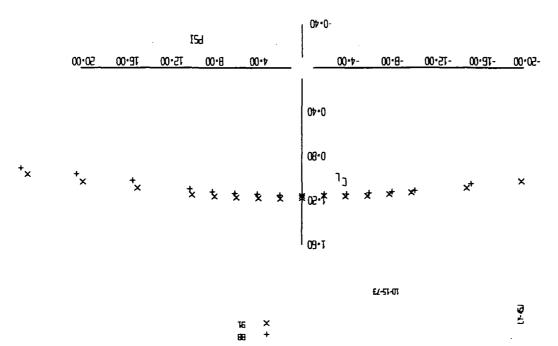
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FIGURE 18 (SHEET 2)

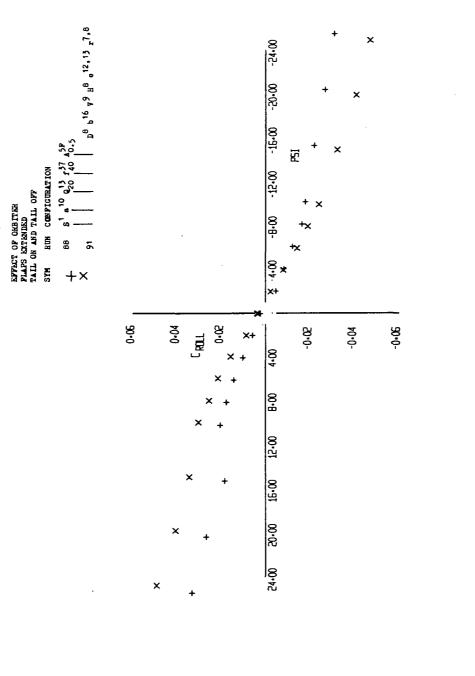
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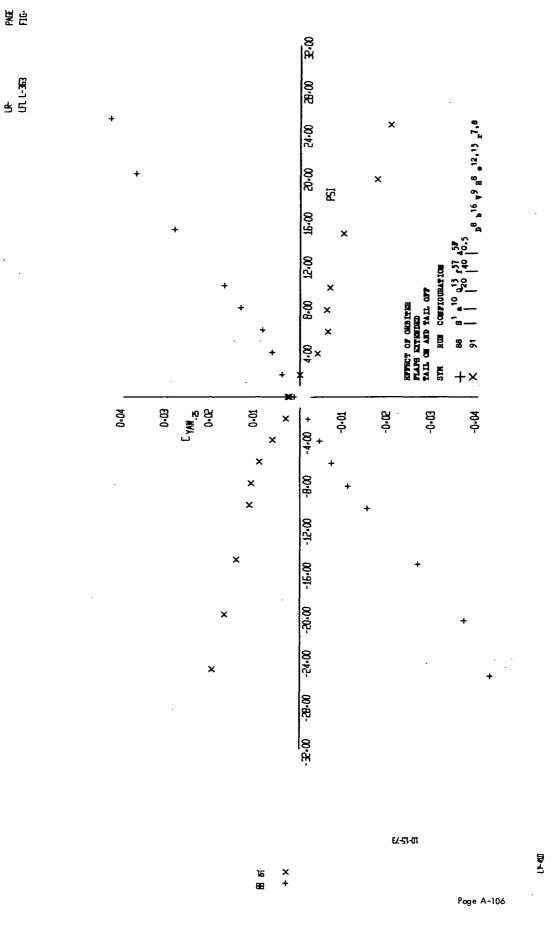
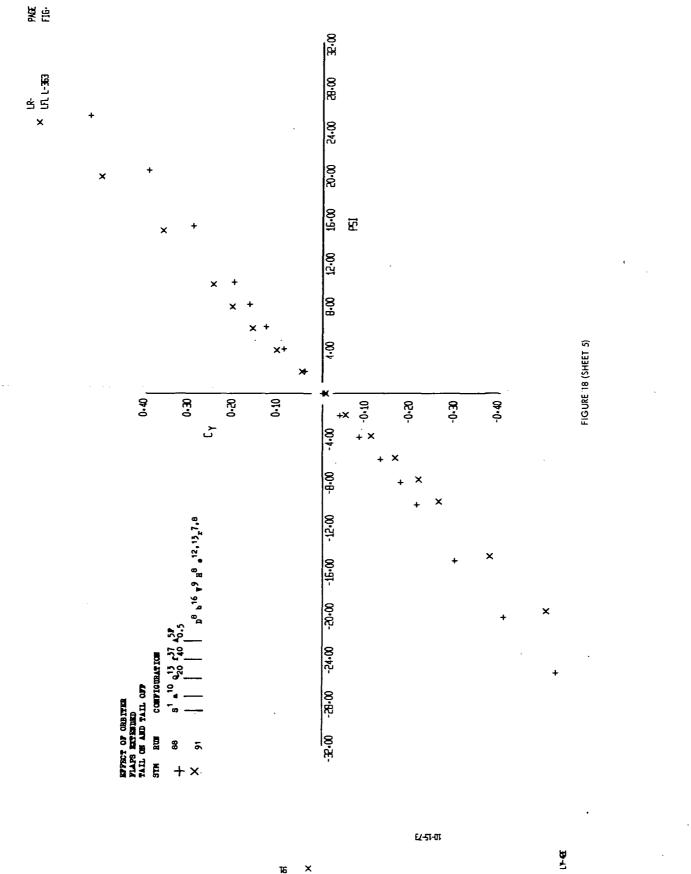


FIGURE 18 (SHEET 4)

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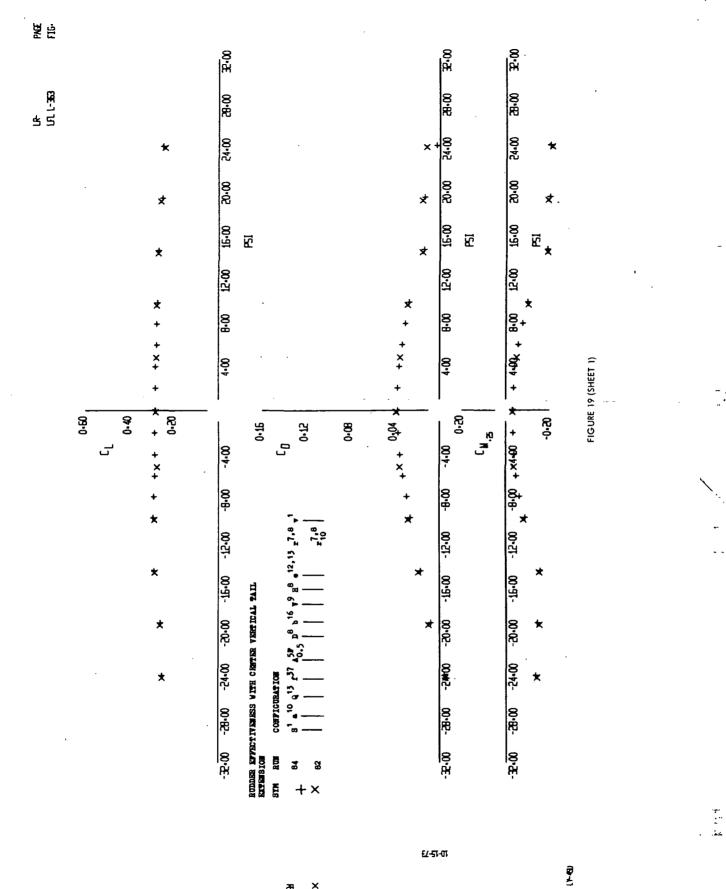
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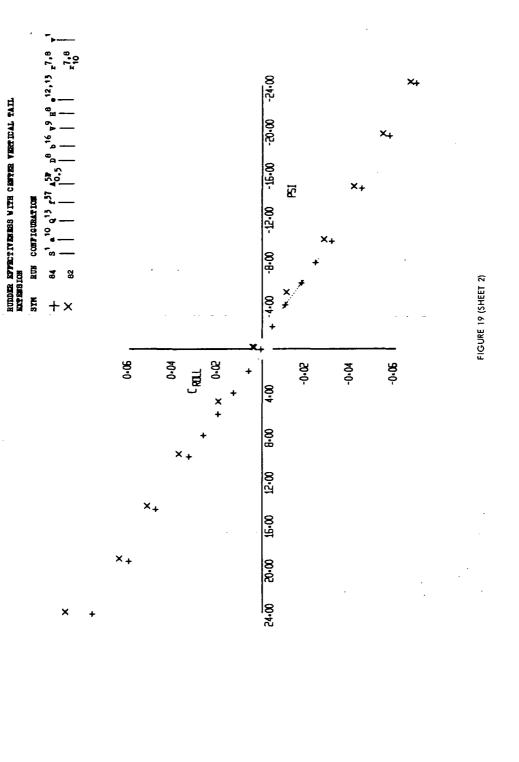
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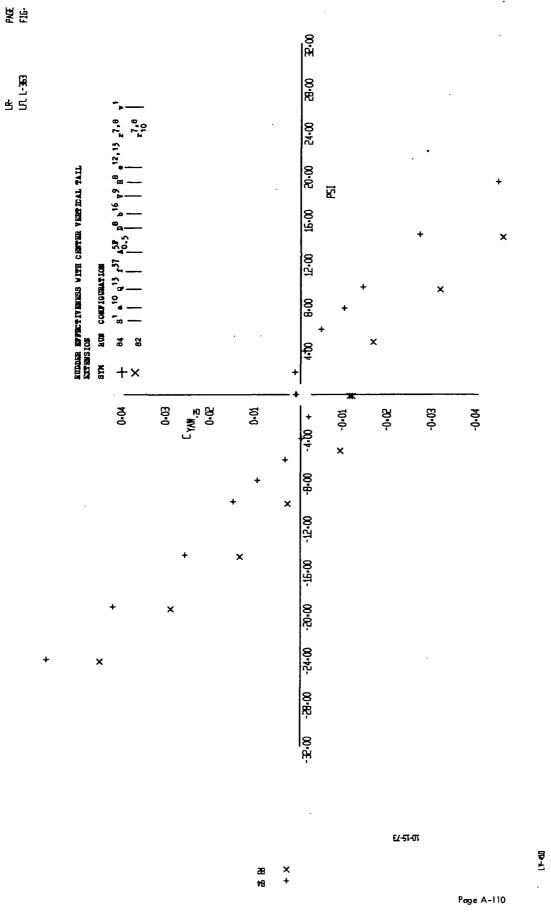
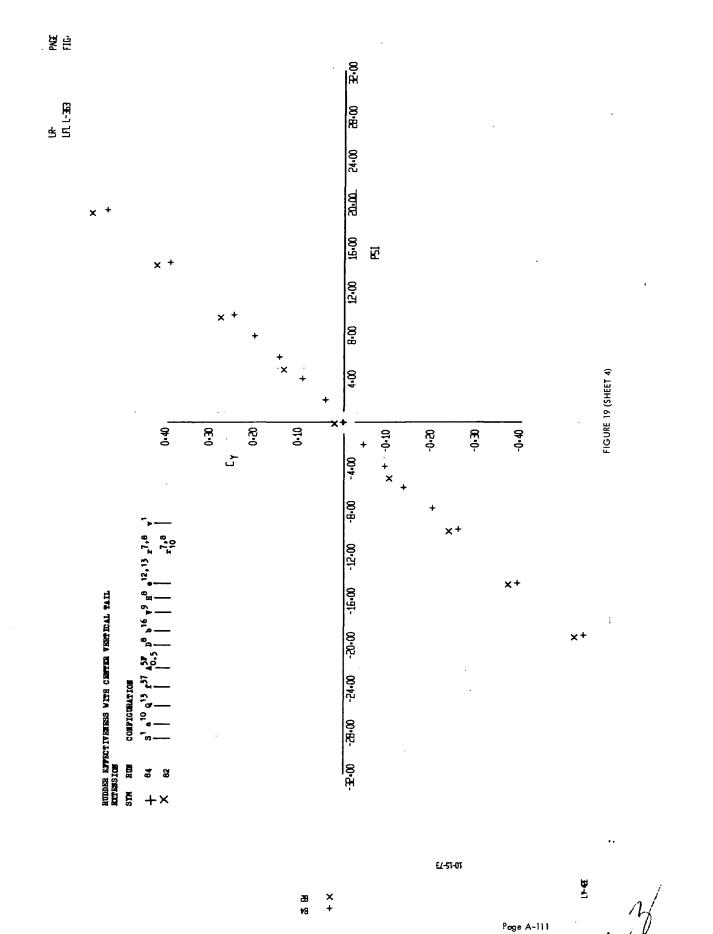


FIGURE 19 (SHEET 3)

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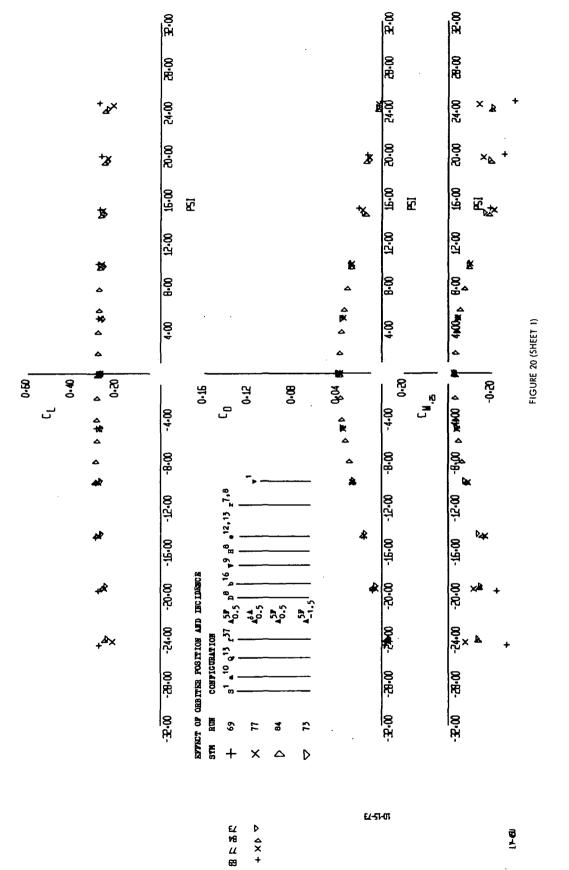


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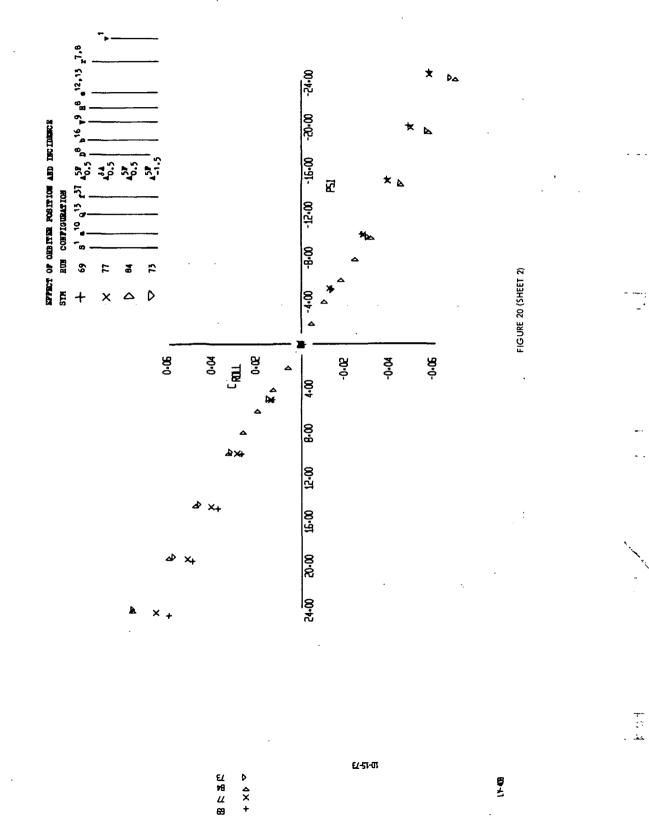
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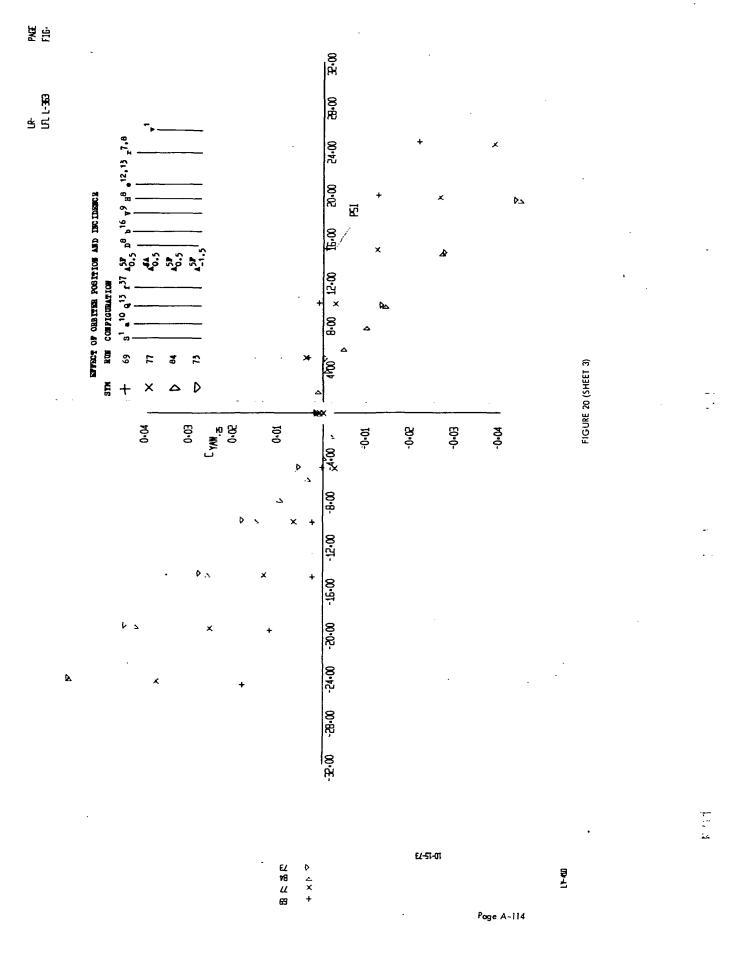
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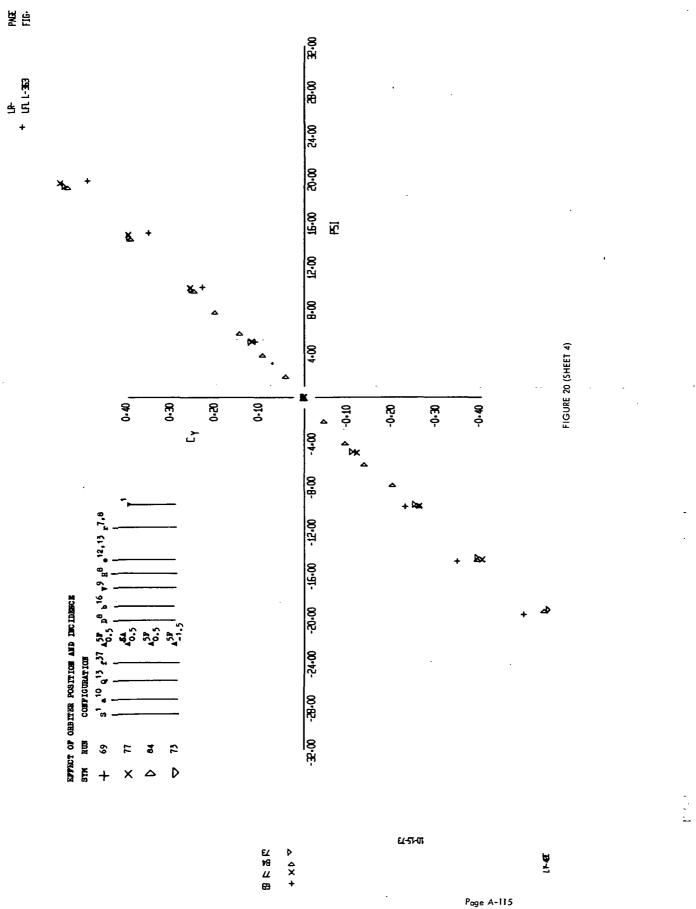
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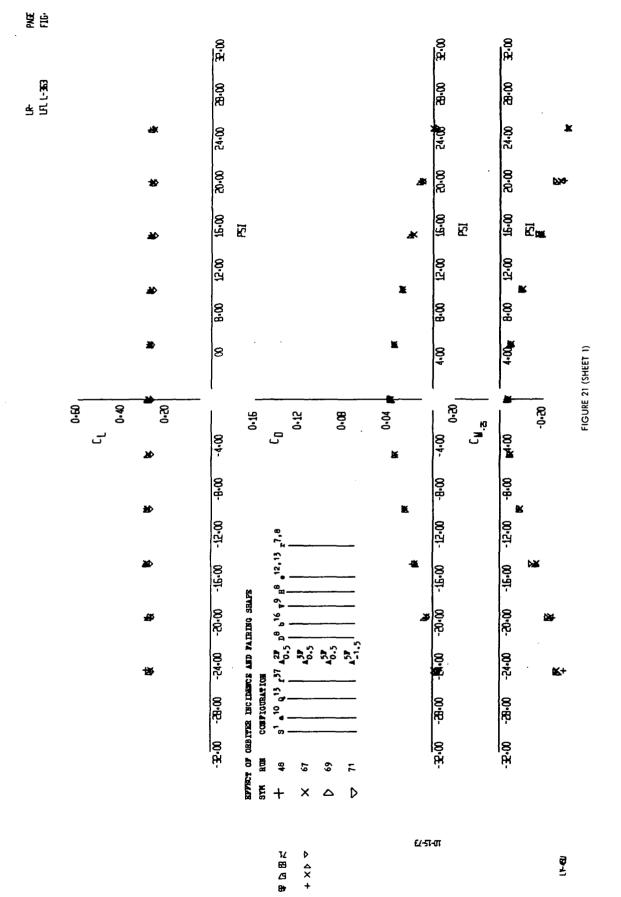
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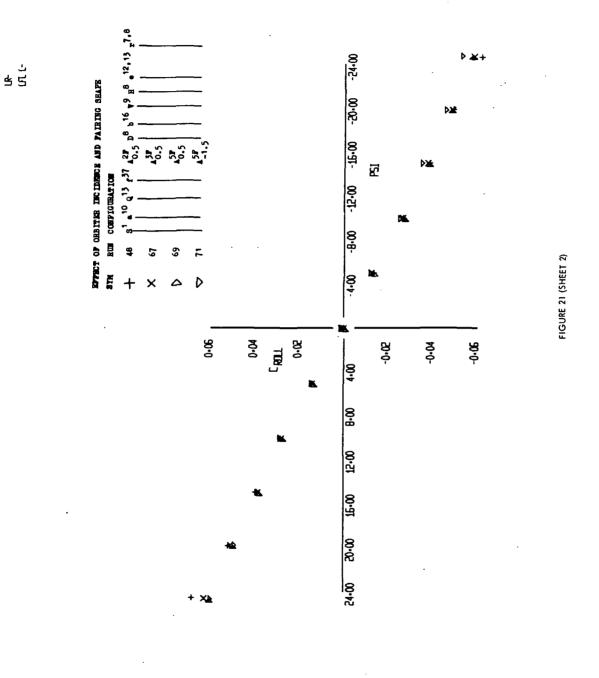


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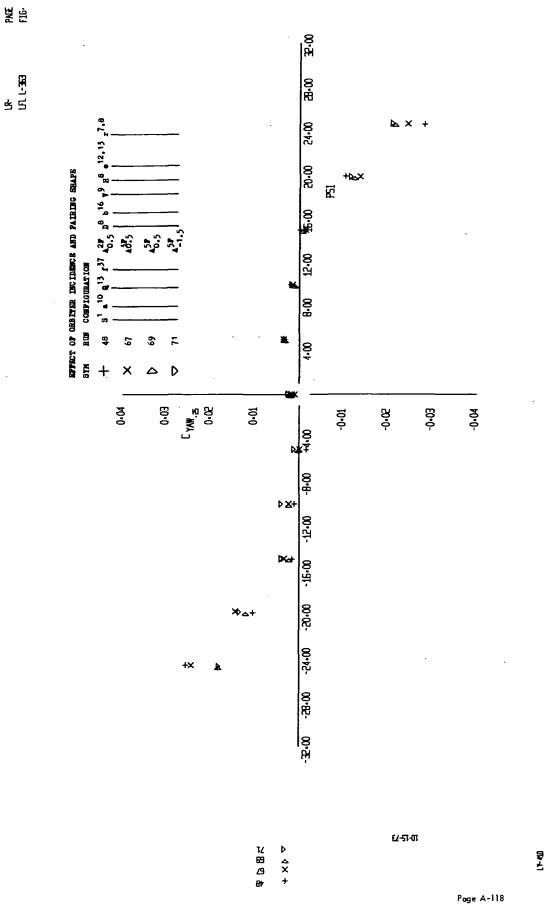
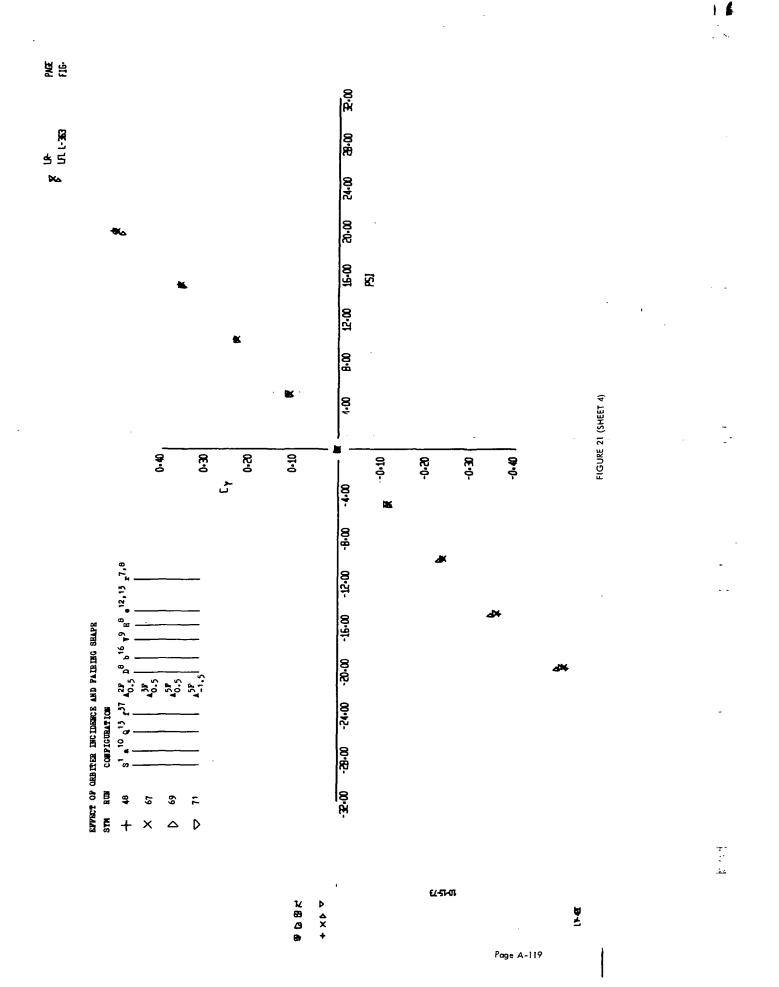


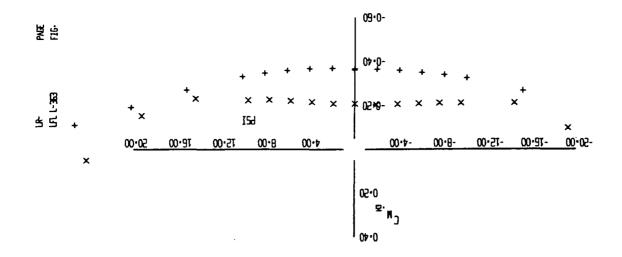
FIGURE 21 (SHEET 3)

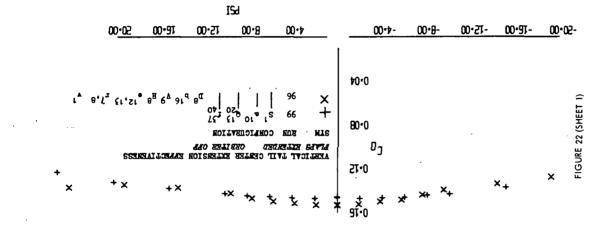
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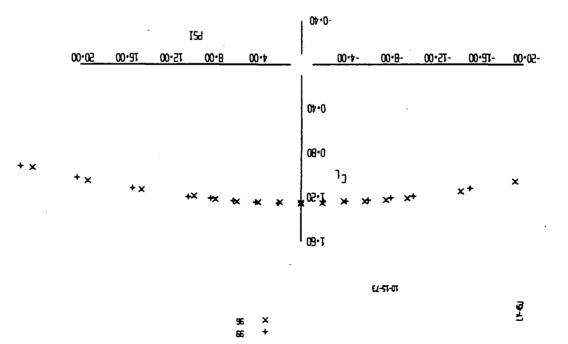
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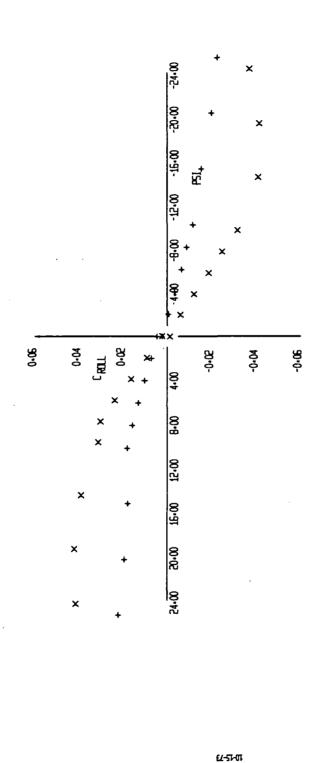
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FIGURE 22 (SHEET 2)

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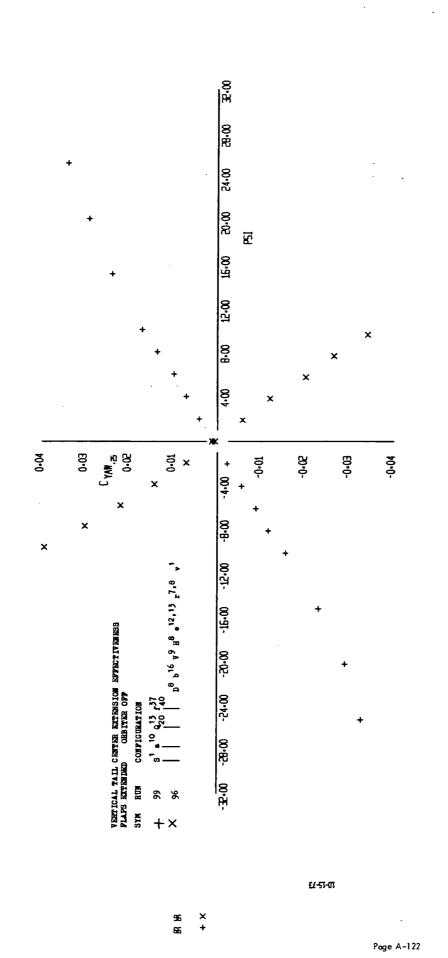
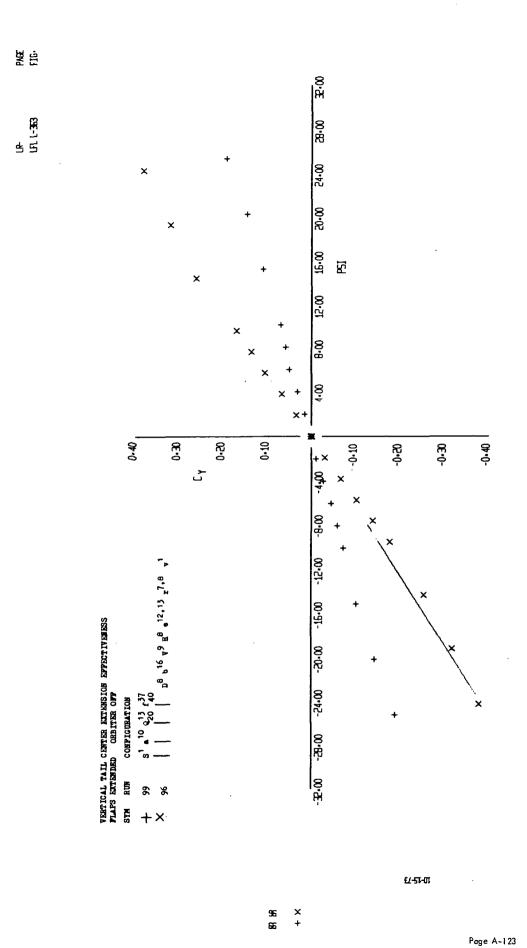


FIGURE 22 (SHEET 3)

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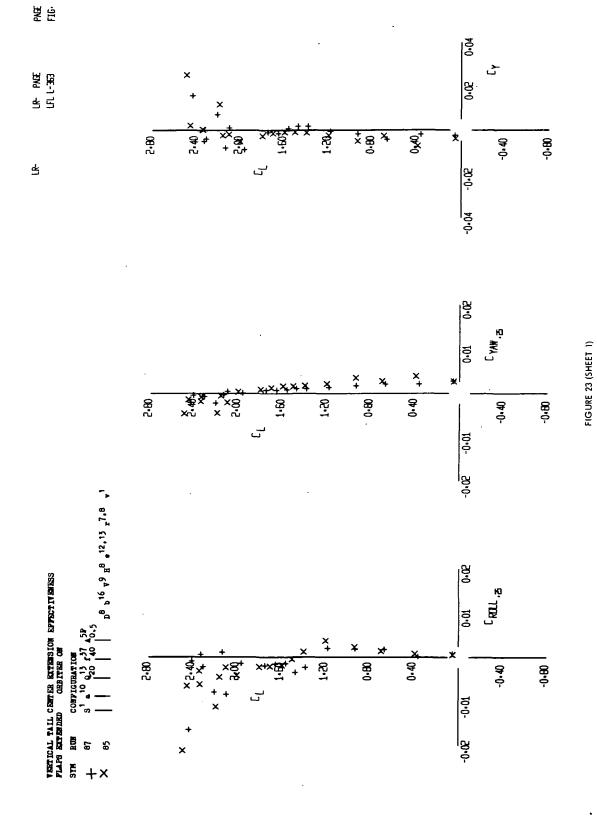
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FIGURE 22 (SHEET 4)

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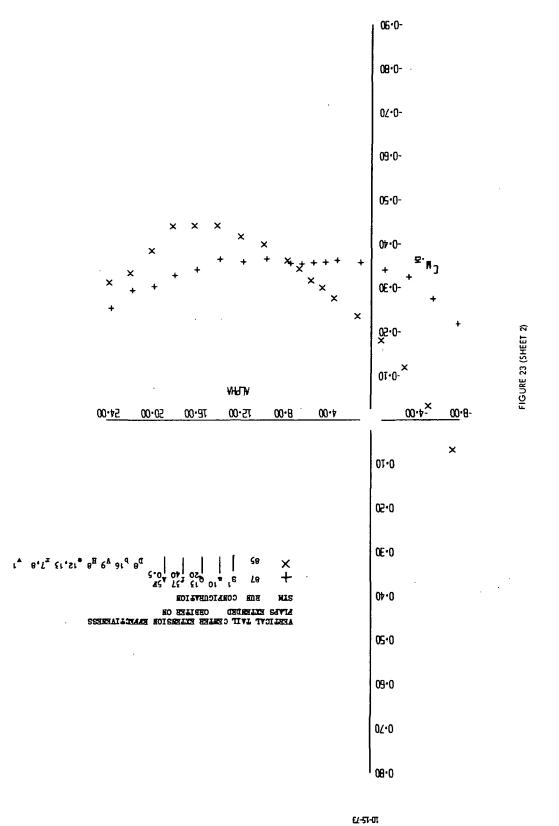
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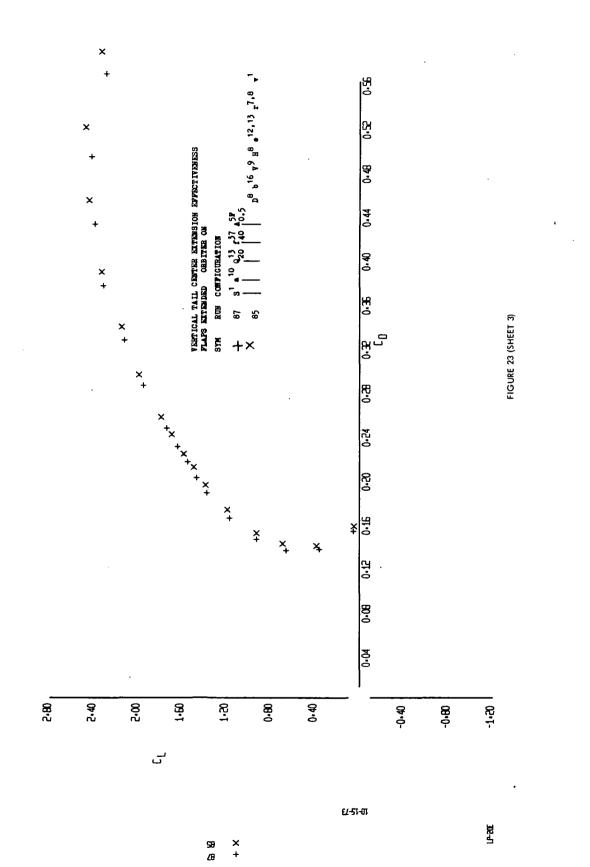
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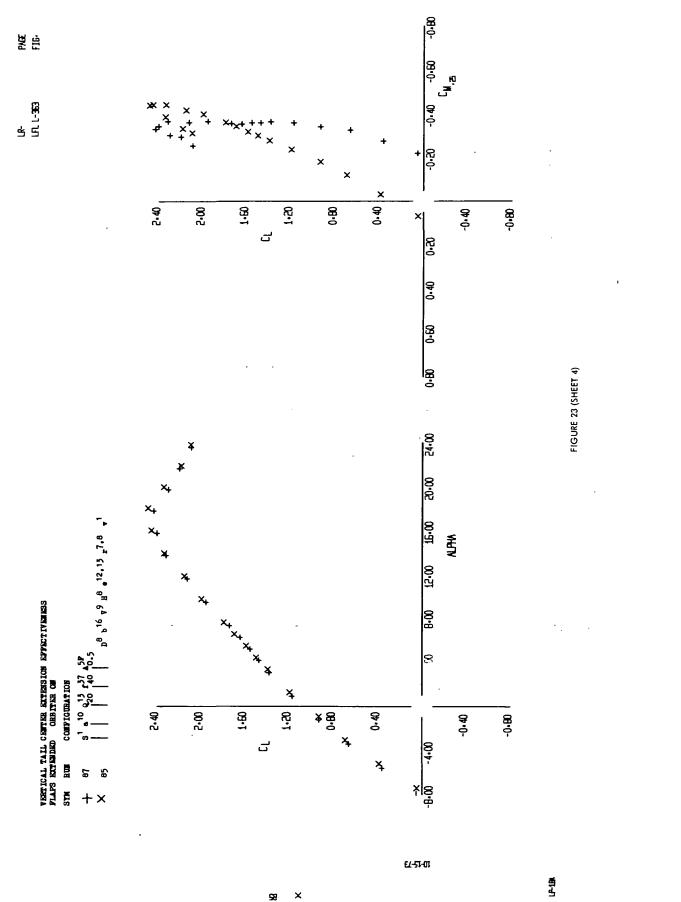


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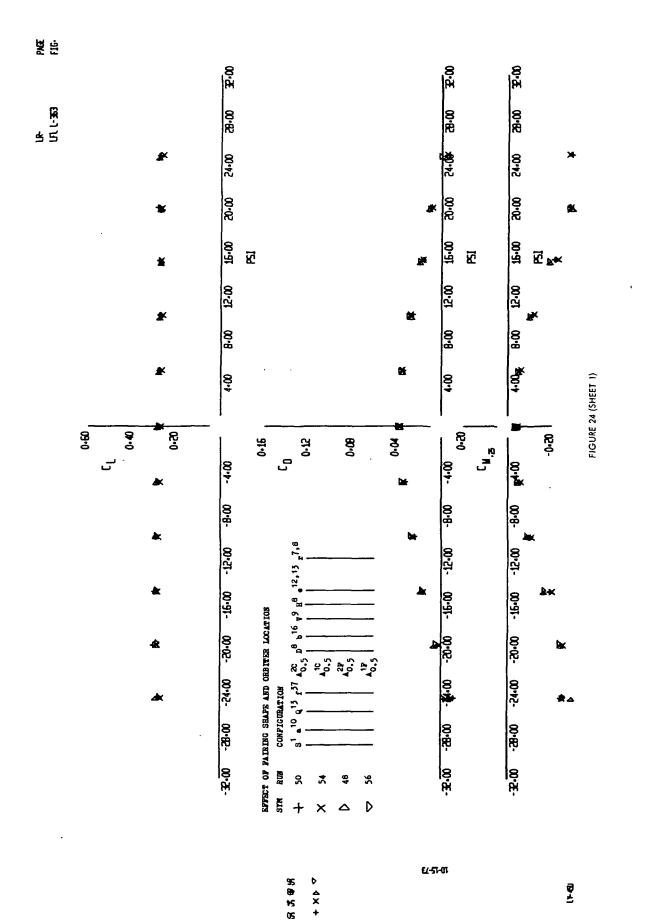
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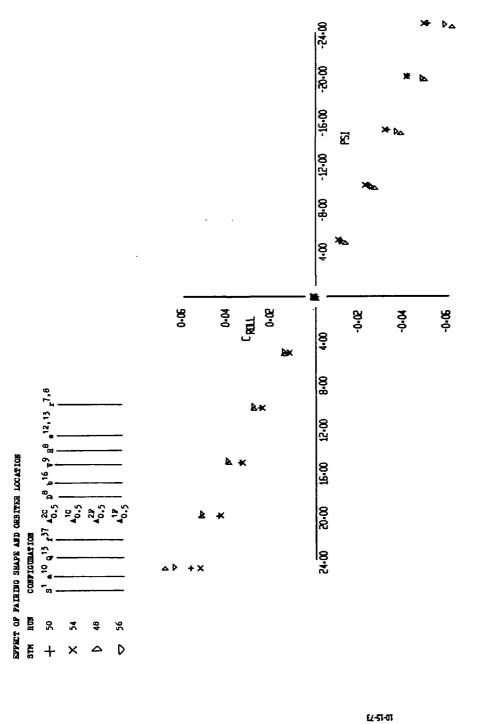
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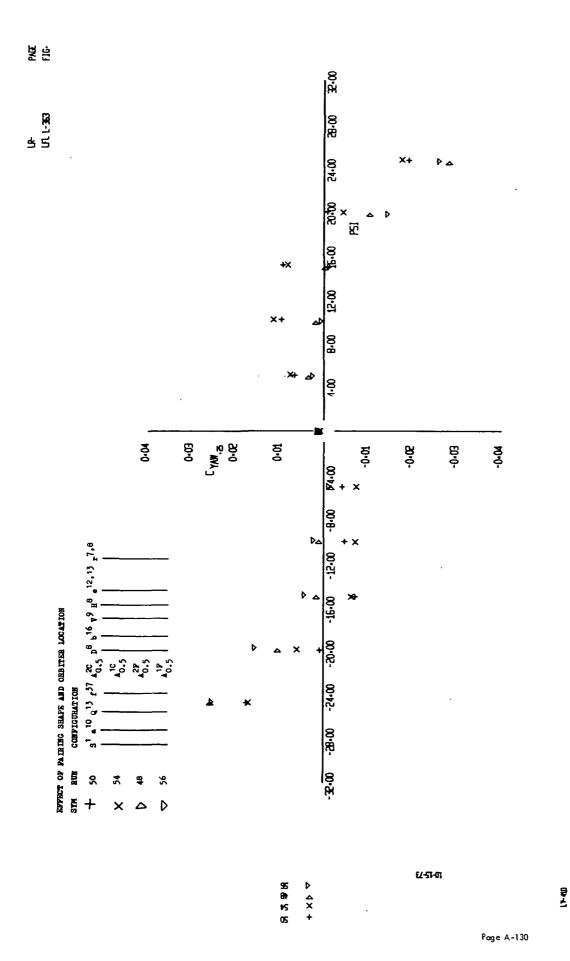
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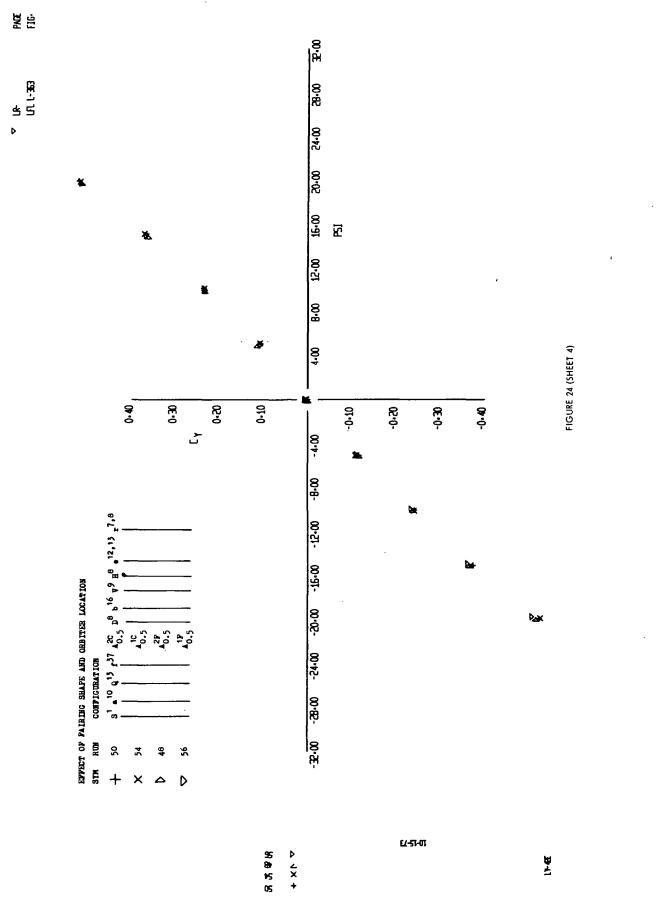
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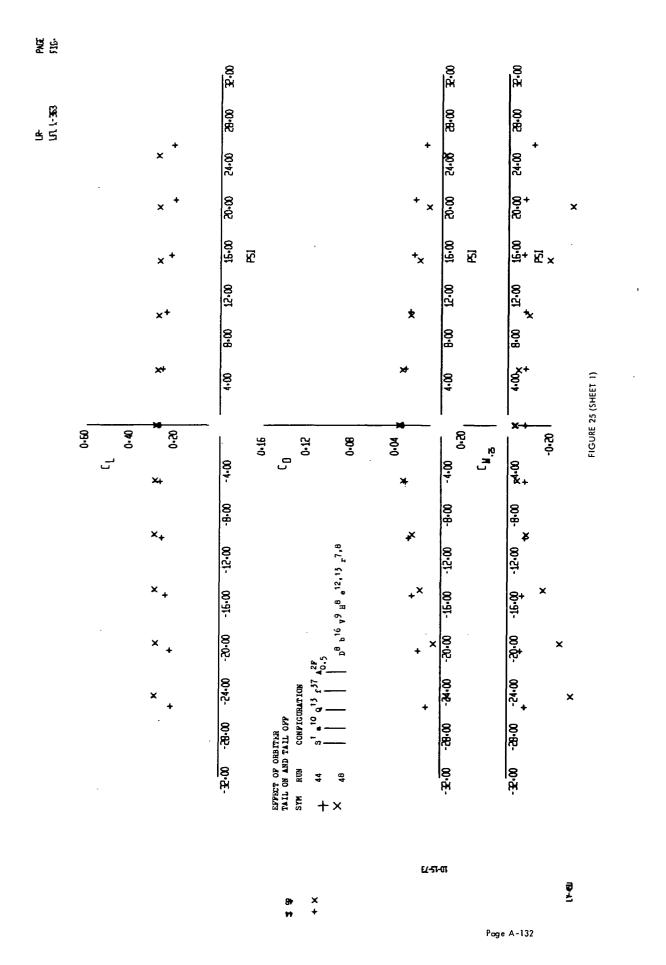
Page A-129











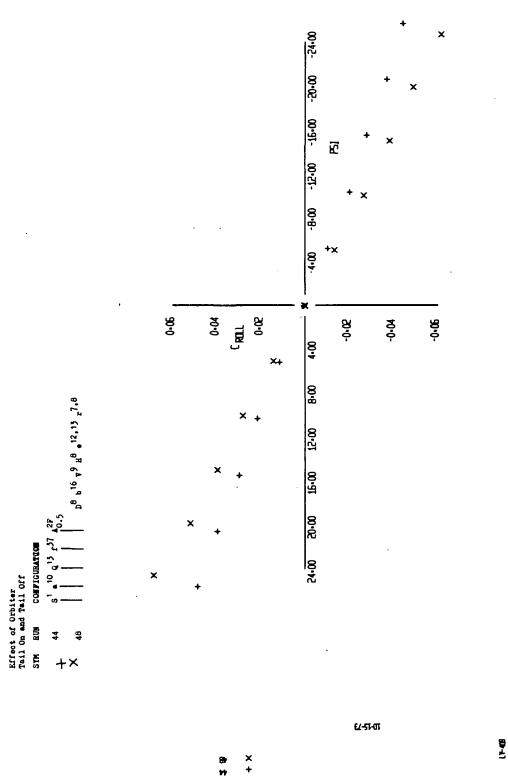
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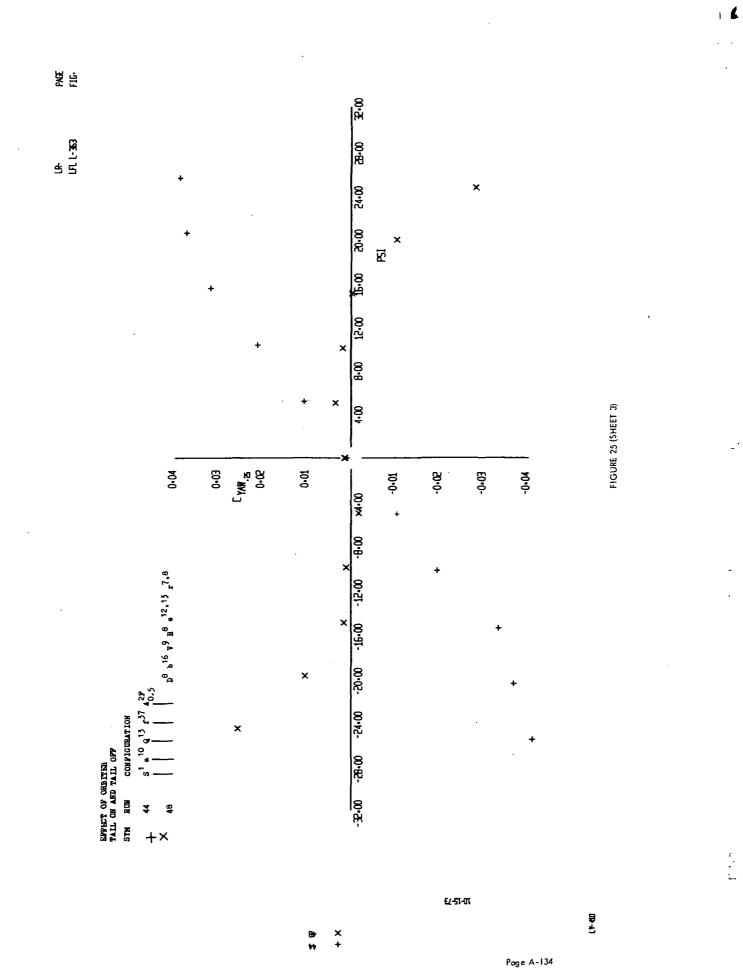
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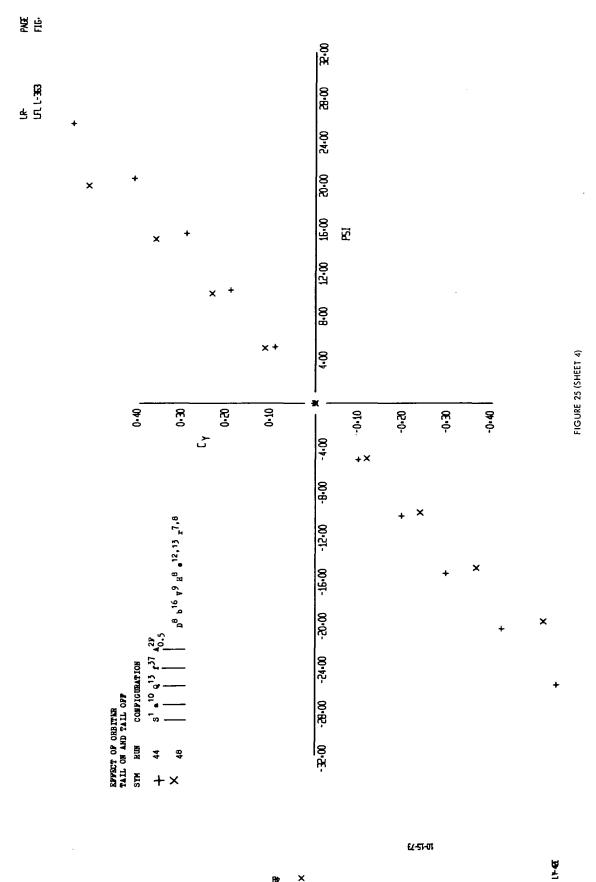
Page A-133

FIGURE 25 (SHEET 2)

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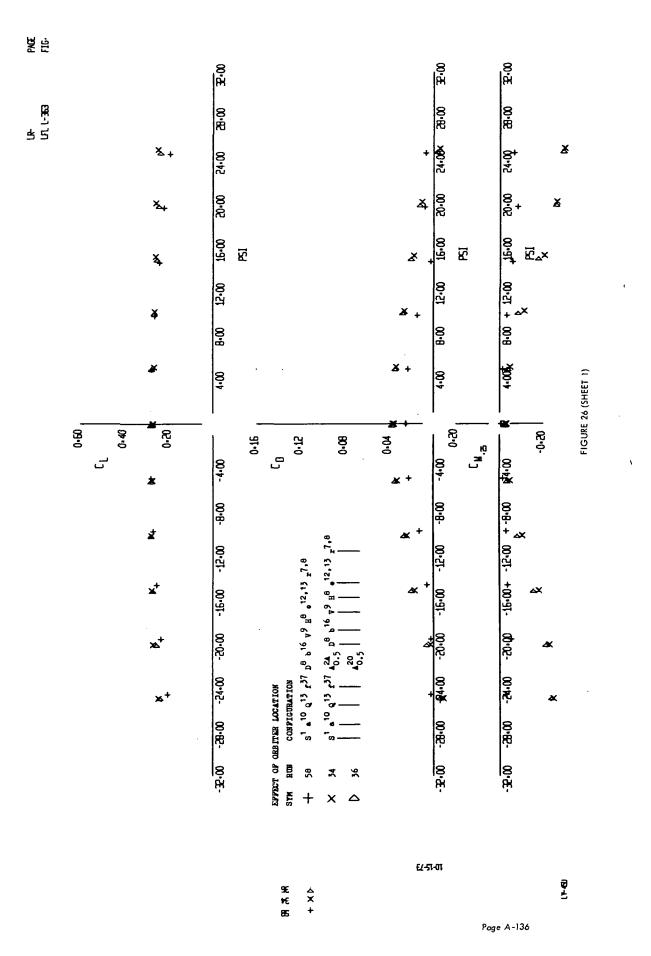
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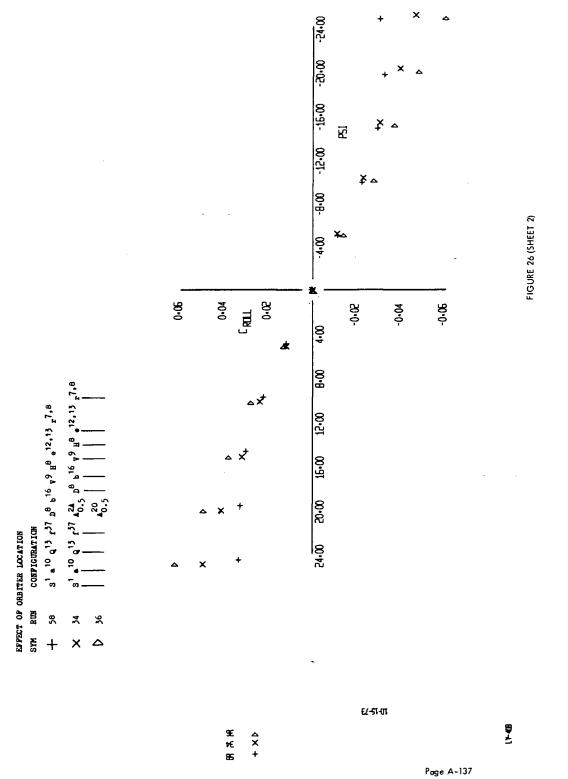
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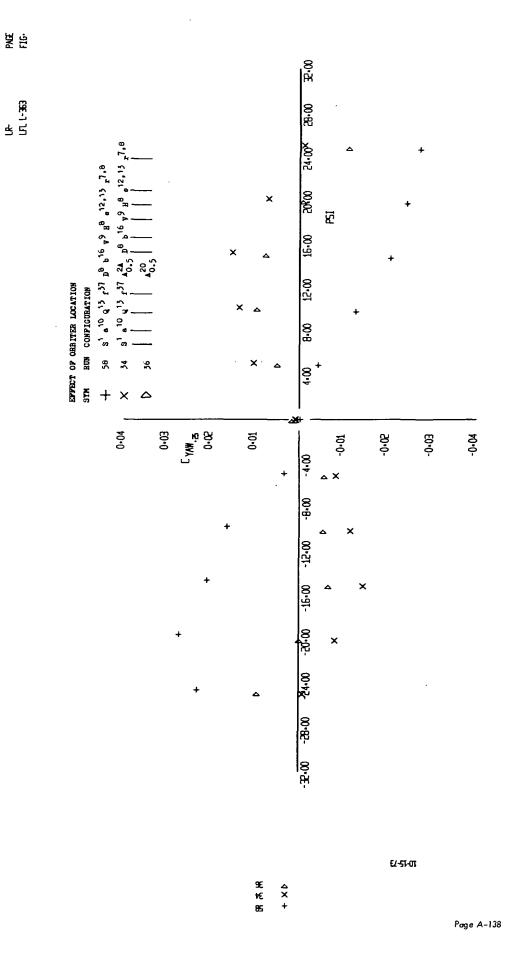


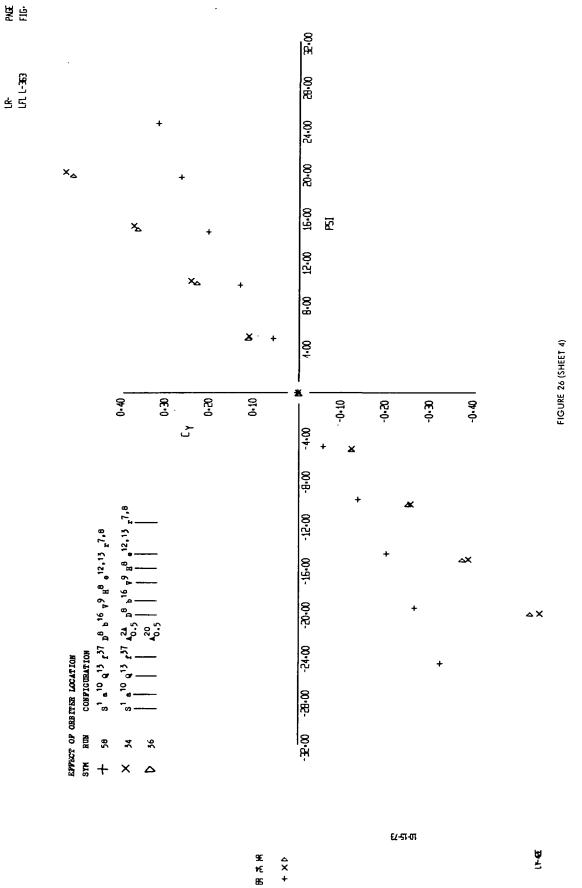
FIGURE 26 (SHEET 3)

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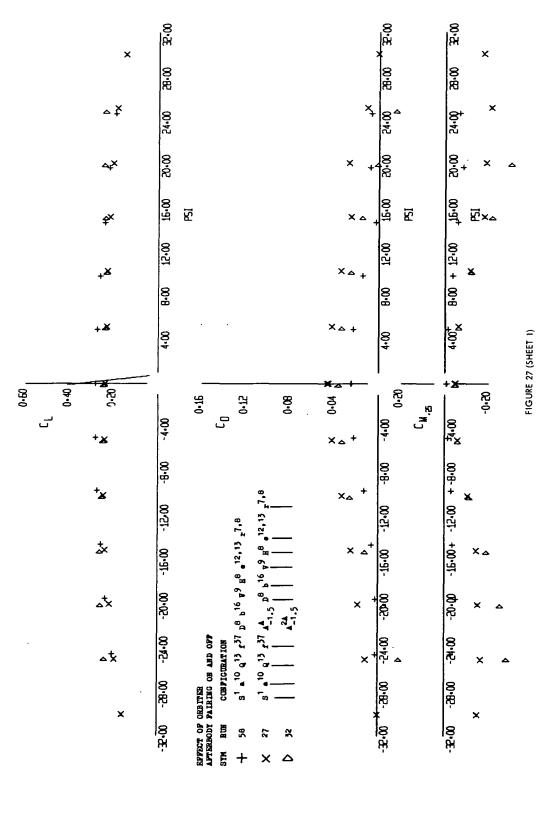
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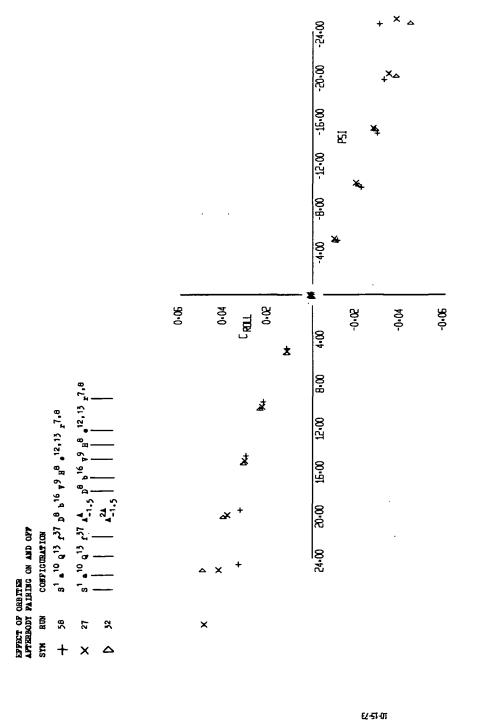
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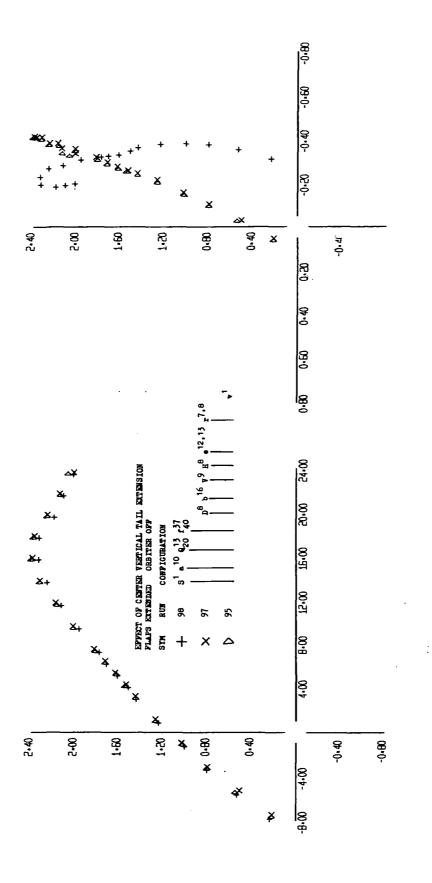
FIGURE 27 (SHEET 2)

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FIGURE 28 (SHEET 1)

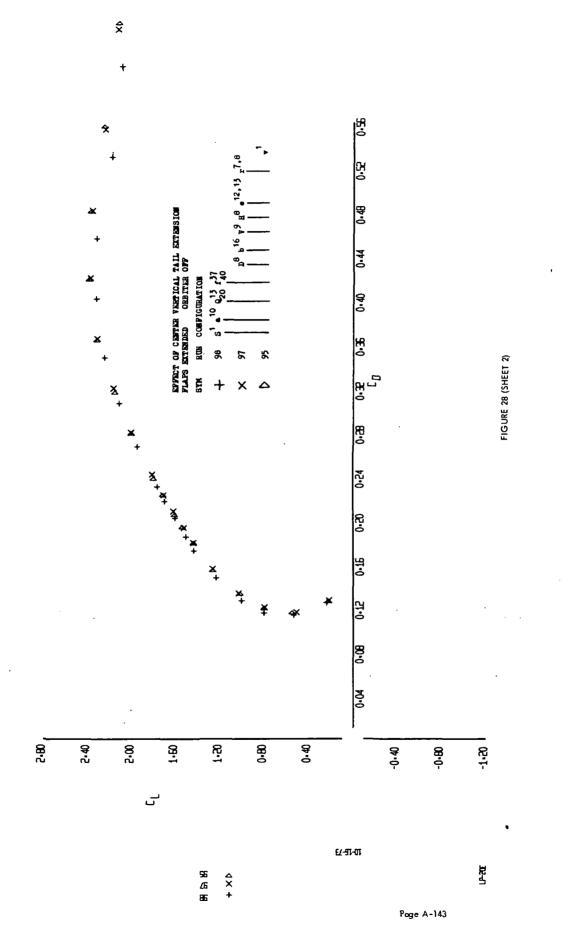
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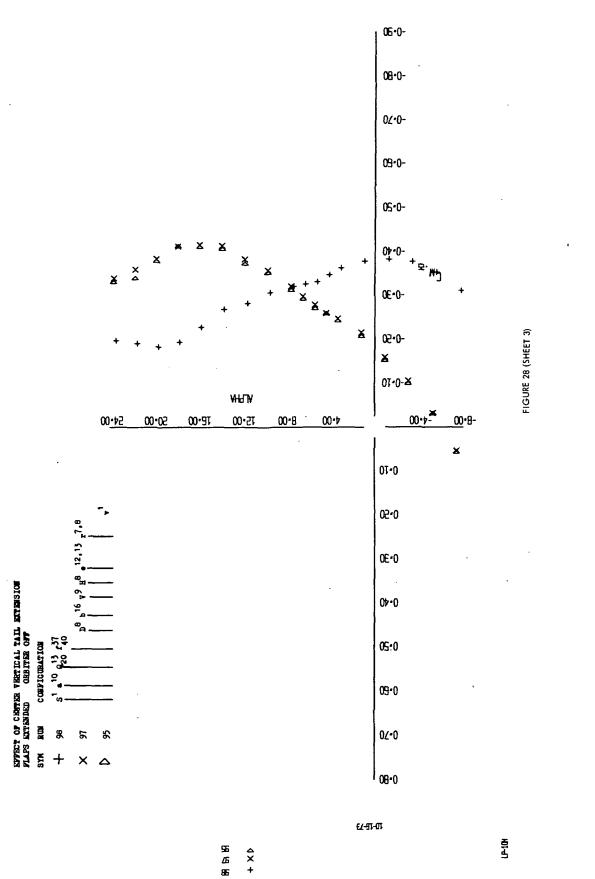


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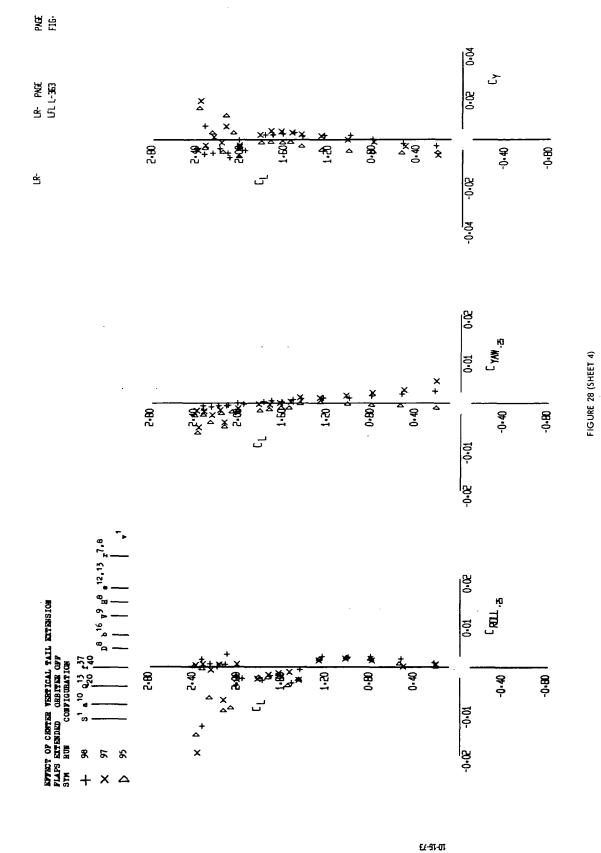


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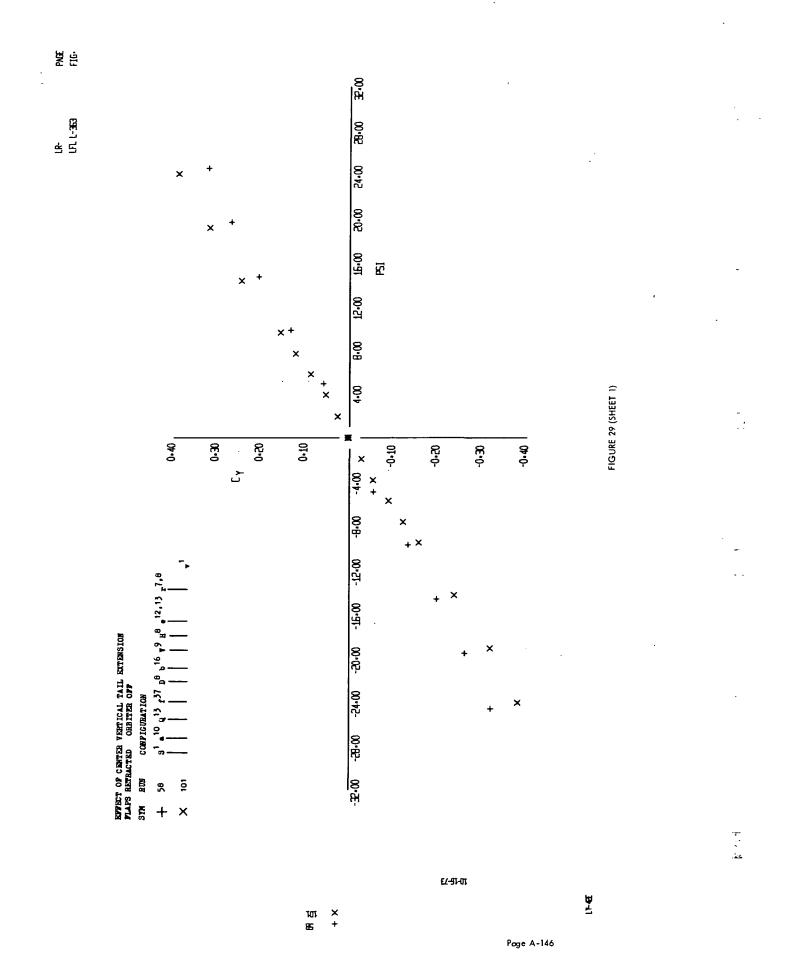


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Page A-145

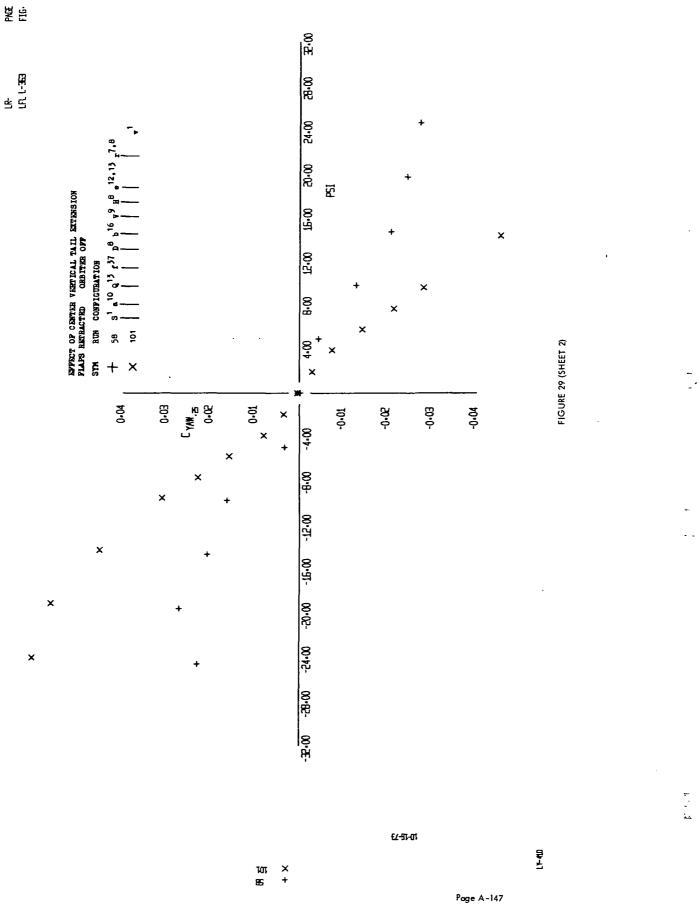
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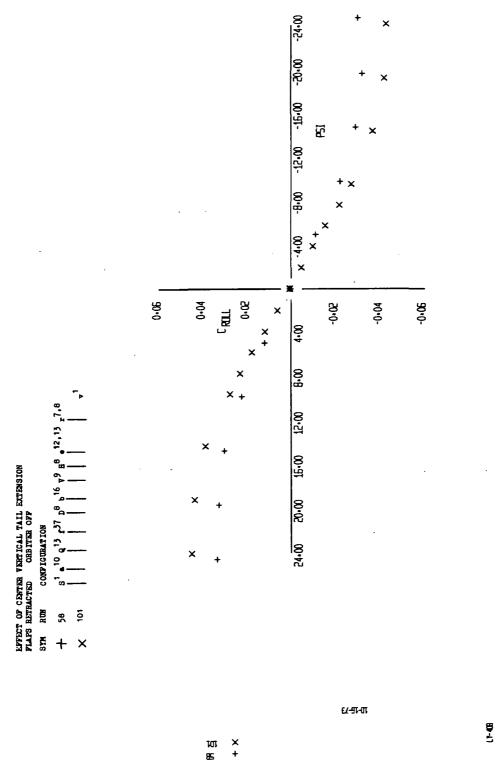


FIGURE 29 (SHEET 3)

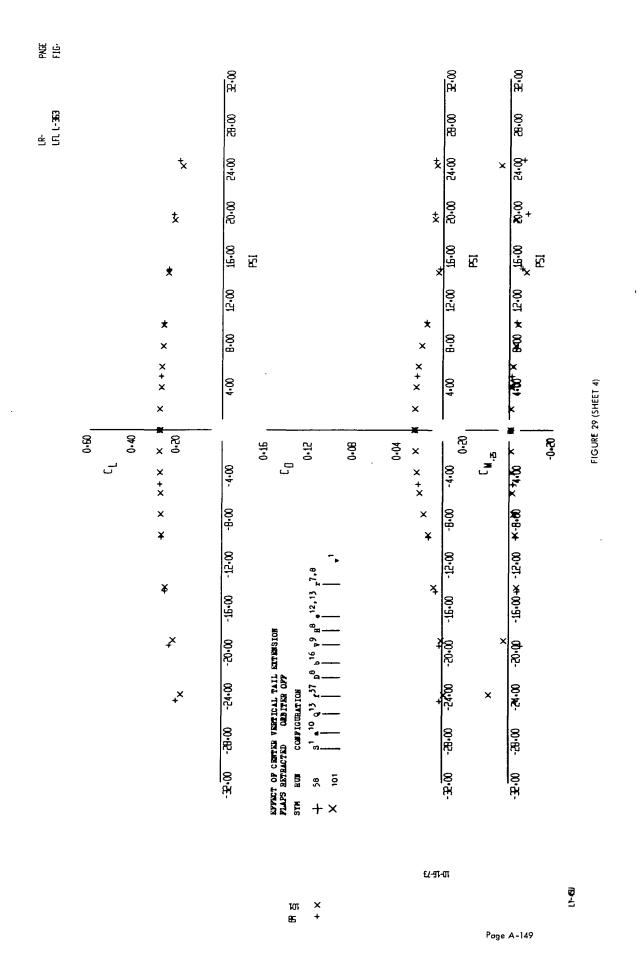
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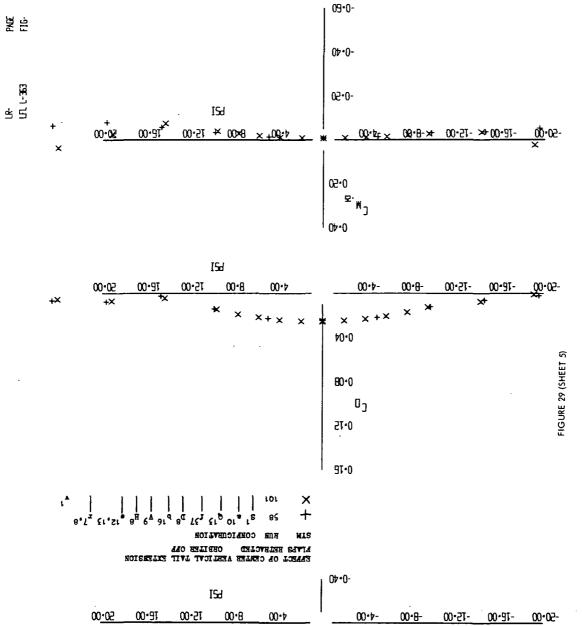
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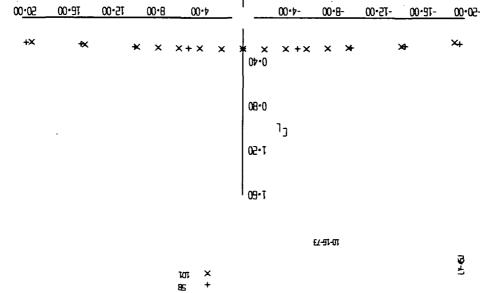


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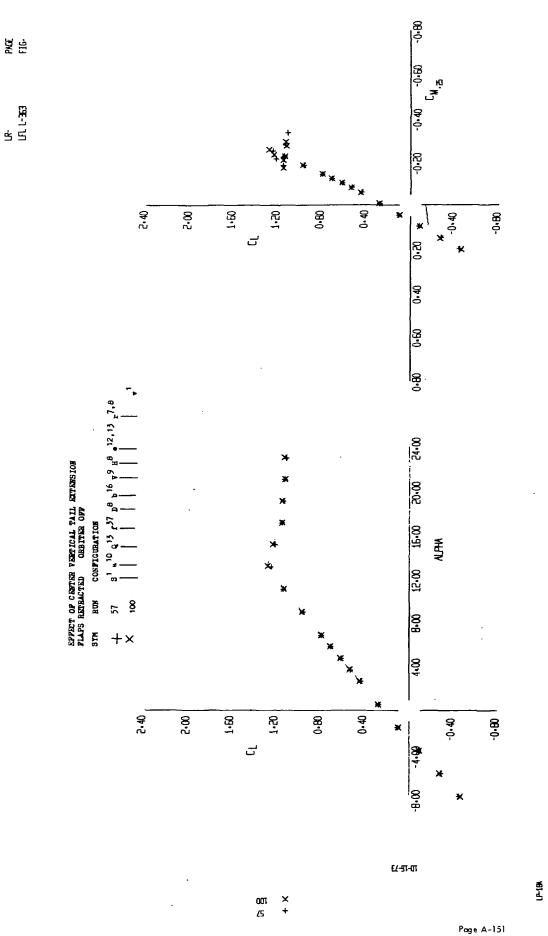
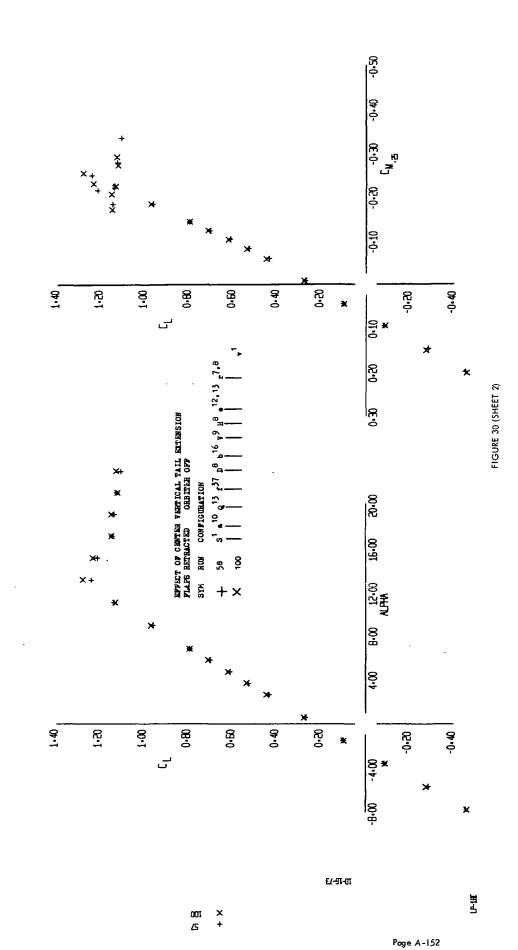


FIGURE 30 (SHEET 1)



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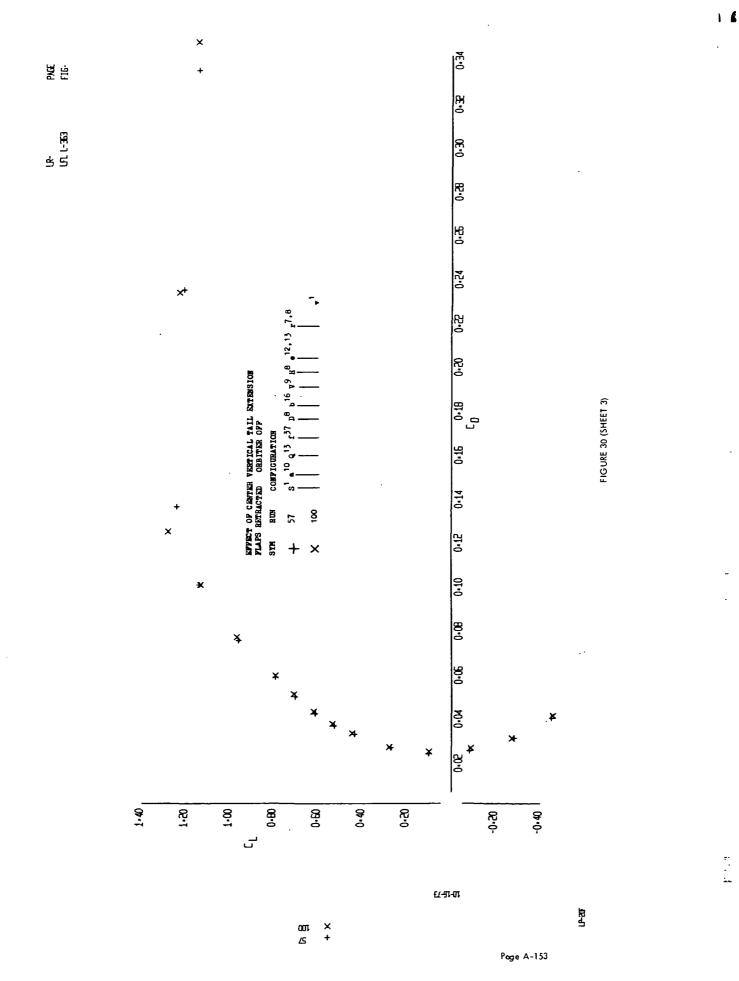
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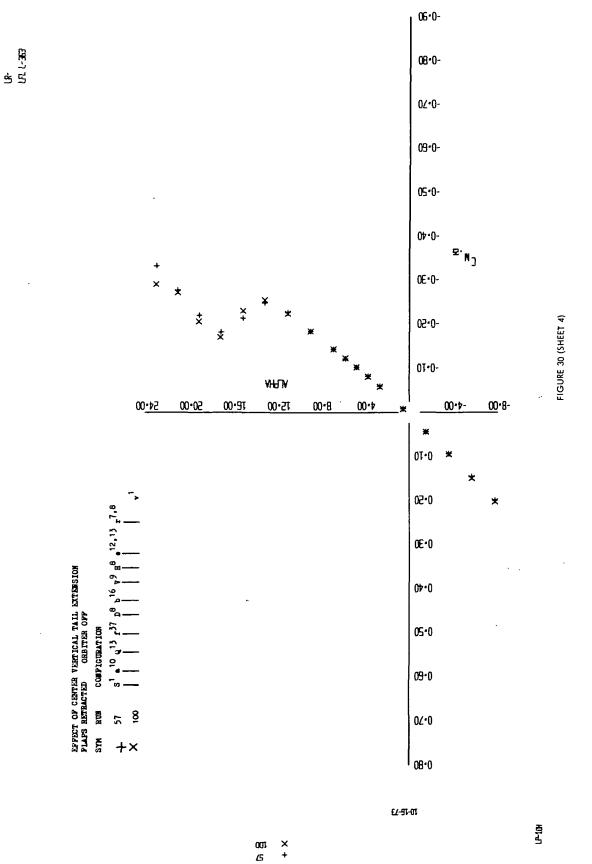
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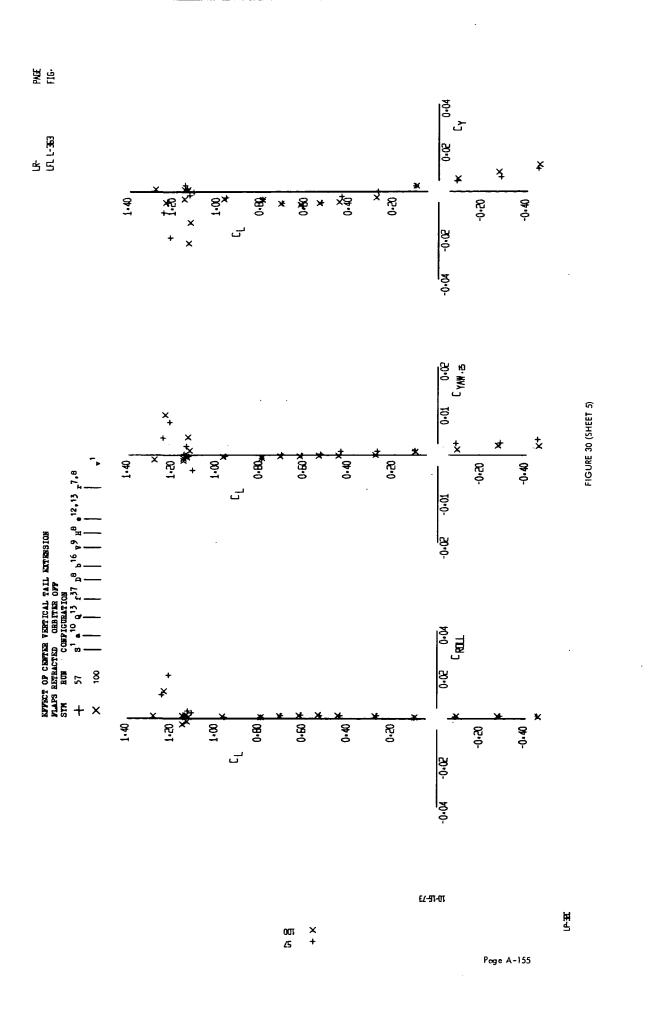


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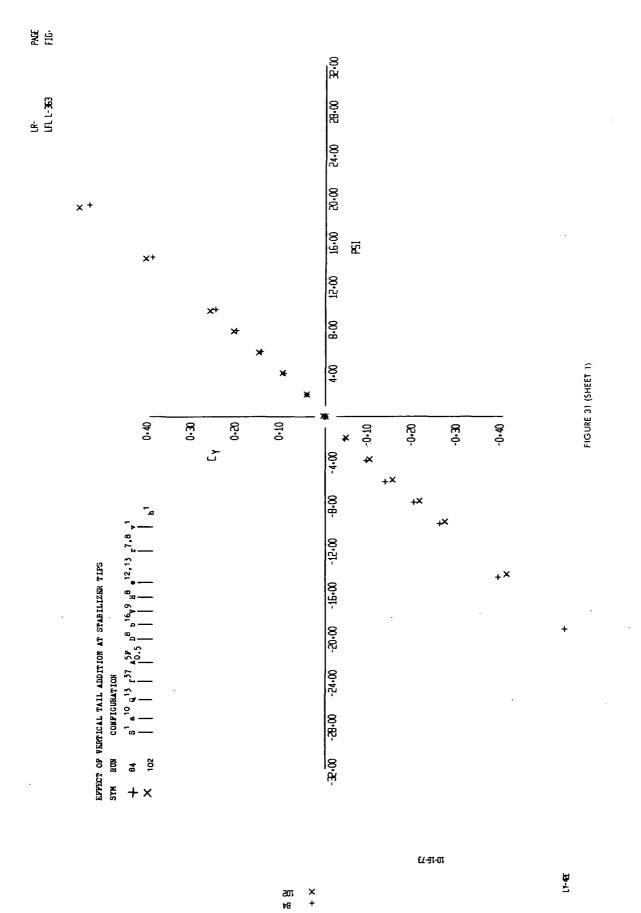
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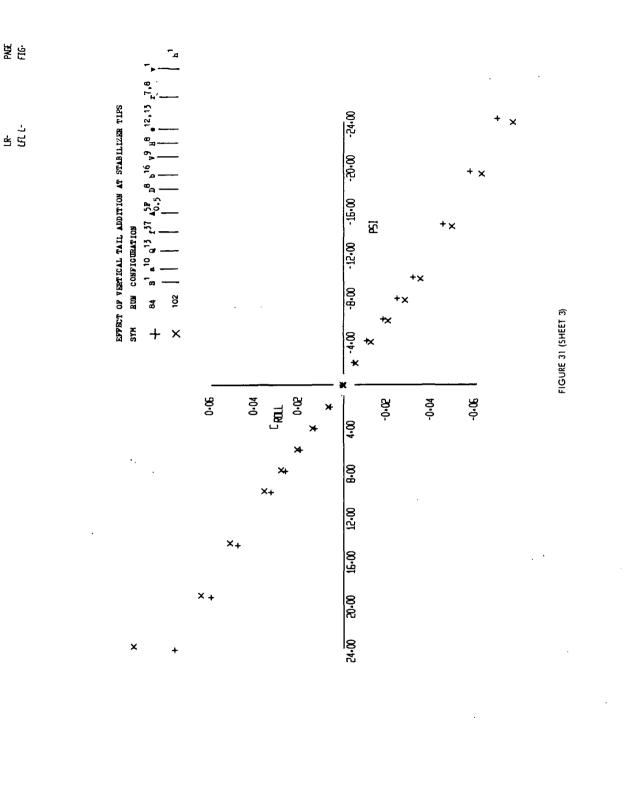


000 39400 ٦_ 12,13 T.B 1 16-00 20-00 24-00 EFFECT OF VERTICAL TAIL ADDITION AT STABILIZER TIPS SYM RUE COMPLEMENTION 6^H 6^A 91^Q R × ¥.9 12-00 ۲**ڈع** ڈن^م ⁰¹_ × 8.8 × + + × 102 102 84 **0**€ FIGURE 31 (SHEET 2) $+\times$ 0-04 E0-0 0-01 -0-04 9-0-E0•0-10.0-× -4-00 + × + × 8.8 × × -20.00 -28.00 -24.00 -20.00 -16.00 -12.00 × × + 10-18-63 * 705 84 Page A-157

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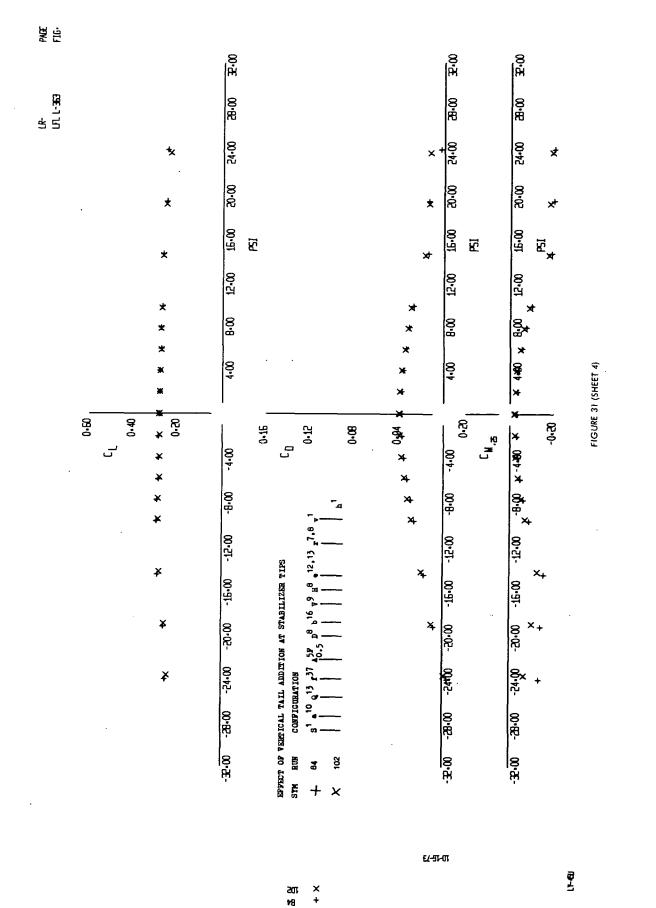
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