

N74-19549

NATIONAL AERONAUTICS AND SPACE ADMINISTRATION

Technical Report 32-1240

Addendum

*ELAS—A General-Purpose Computer Program for the
Equilibrium Problems of Linear Structures*

Volume II. Documentation of the Program

Senol Utku

**JET PROPULSION LABORATORY
CALIFORNIA INSTITUTE OF TECHNOLOGY
PASADENA, CALIFORNIA**

October 15, 1969

REPRODUCED BY
NATIONAL TECHNICAL
INFORMATION SERVICE
U.S. DEPARTMENT OF COMMERCE
SPRINGFIELD, VA. 22161

076

Prepared Under Contract No. NAS 7-100
National Aeronautics and Space Administration

N O T I C E

THIS DOCUMENT HAS BEEN REPRODUCED FROM THE BEST COPY FURNISHED US BY THE SPONSORING AGENCY. ALTHOUGH IT IS RECOGNIZED THAT CERTAIN PORTIONS ARE ILLEGIBLE, IT IS BEING RELEASED IN THE INTEREST OF MAKING AVAILABLE AS MUCH INFORMATION AS POSSIBLE.

Preface

The work described in this report was performed by the Engineering Mechanics Division of the Jet Propulsion Laboratory.

The program was developed by Dr. Senol Utku and Dr. Fevzican A. Akyuz, and is dedicated to the memory of Professor M. Inan of the Technical University of Istanbul.

Acknowledgment

The author is indebted to Vivia Crew for her help in editing all documents related with the ELAS program.

Contents

I. Introduction	1
II. Main Program and Subroutines of Link 1	2
A. Main Program of Link 1	2
B. Subroutines of Link 1	3
1. Subroutine ARAN	3
2. Subroutine BUNG	3
3. Subroutine COOR	3
4. Subroutine CORG	3
5. Subroutine EXCH	3
6. Function LEBIN	4
7. Subroutine SEBIN	4
8. Subroutine MESH	4
9. Subroutine MESH	4
10. Subroutine OUTPT	4
11. Subroutine SRAT	4
12. Subroutine TABL	5
13. Subroutine TICK	5
14. Subroutine TOPO	5
III. Main Program and Subroutines of Link 2	6
A. Main Program of Link 2	6
B. Subroutines of Link 2	7
1. Subroutine ADM	7
2. Subroutine BEAM	8
3. Subroutine CAS2	8
4. Subroutine CODI	8
5. Subroutine CORT	8
6. Subroutine CUTE	8
7. Subroutine DARN	8
8. Subroutine DMM	9

Contents (contd)

9. Subroutine ELDI	9
10. Subroutine PLBE	9
11. Subroutine RLOC	9
12. Subroutine S01	9
13. Subroutine S02	9
14. Subroutine S03	10
15. Subroutine S04	10
16. Subroutine S05	10
17. Subroutine S07	11
18. Subroutine S09	11
19. Subroutine S11	11
20. Subroutine S13	11
21. Subroutine S15	12
22. Subroutine S17	12
23. Subroutine S18	12
24. Subroutine STFS	12
25. Subroutine STRA	12
26. Subroutine TICK	13
27. Subroutine TOPO	13
28. Subroutine TRAN	13
29. Subroutine TRIM	13
30. Subroutine TRM	13
IV. Main Program and Subroutines of Link 3	14
A. Main Program of Link 3	14
B. Subroutines of Link 3	15
1. Subroutine ELST	15
2. Subroutine PUNC	15
3. Subroutine RESI	15
4. Subroutine RESW	15
5. Subroutine TICK	16
6. Subroutine VELAS	16

Contents (contd)

V. Main Program and Subroutines of Link 4	17
A. Main Program of Link 4	17
B. Subroutines of Link 4	17
1. Subroutine ABEQ	17
2. Subroutine AGEL	18
3. Subroutine BEST	18
4. Subroutine BOFI	20
5. Subroutine CAS4	20
6. Subroutine CODI	20
7. Subroutine DIMI	20
8. Subroutine DINA	20
9. Subroutine EPAN	20
10. Subroutine FINDQ	21
11. Subroutine FINDX	21
12. Subroutine GENE	21
13. Subroutine INER	21
14. Subroutine INLZ	21
15. Subroutine INV	21
16. Subroutine LEST	22
17. Subroutine MDIN	22
18. Subroutine META	22
19. Subroutine QUAD	22
20. Subroutine REVO	23
21. Subroutine ROTA	23
22. Subroutine SAME	23
23. Function SCAL	23
24. Subroutine SETA	23
25. Subroutine STRA	24
26. Subroutine STRS	24
27. Subroutine TEMP	24
28. Subroutine TICK	24
29. Subroutine TOPO	24
30. Subroutine TRAN	24

Contents (contd)

31. Subroutine UNIT	24
32. Subroutine VECT	24
VI. Semidetailed Flowcharts	25
VII. Source Program Listings	112
References	161

Tables

V-1. Values of important parameters used in subroutine ABEQ for various classes	19
V-2. Arrangement of prescribed boundary forces by subroutine ABEQ in SR vector for the eight class types	19
VII-1. Source program listing of main program of Link 1 (input link)	113
VII-2. Source program listing of subroutine ARAN (Link 1)	115
VII-3. Source program listing of subroutine BUNG (Link 1)	116
VII-4. Source program listing of subroutine COOR (Link 1)	117
VII-5. Source program listing of subroutine CORG (Link 1)	117
VII-6. Source program listing of subroutine EXCH (Link 1)	117
VII-7. Source program listing of function LEBIN and subroutine SEBIN (Link 1)	117
VII-8. Source program listing of subroutine MMSG (Link 1)	118
VII-9. Source program listing of subroutine MEST (Link 1)	118
VII-10. Source program listing of subroutine OUTPT (Link 1)	118
VII-11. Source program listing of subroutine SRAT (Link 1)	119
VII-12. Source program listing of subroutine TABL (Link 1)	120
VII-13. Source program listing of subroutine TICK (Link 1)	120
VII-14. Source program listing of subroutine TOPO (Link 1)	120
VII-15. Source program listing of main program of Link 2 (generation link)	121
VII-16. Source program listing of subroutine ADM (Link 2)	123
VII-17. Source program listing of subroutine BEAM (Link 2)	123
VII-18. Source program listing of subroutine CAS2 (Link 2)	123
VII-19. Source program listing of subroutine CODI (Link 2)	123
VII-20. Source program listing of subroutine CORT (Link 2)	124

Contents (contd)

Tables (contd)

VII-21. Source program listing of subroutine CUTE (Link 2)	124
VII-22. Source program listing of subroutine DARN (Link 2)	125
VII-23. Source program listing of subroutine DMM (Link 2)	125
VII-24. Source program listing of subroutine ELDI (Link 2)	125
VII-25. Source program listing of subroutine PLBE (Link 2)	126
VII-26. Source program listing of subroutine RLOC (Link 2)	126
VII-27. Source program listing of subroutine S01 (Link 2)	126
VII-28. Source program listing of subroutine S02 (Link 2)	127
VII-29. Source program listing of subroutine S03 (Link 2)	127
VII-30. Source program listing of subroutine S04 (Link 2)	128
VII-31. Source program listing of subroutine S05 (Link 2)	128
VII-32. Source program listing of subroutine S07 (Link 2)	129
VII-33. Source program listing of subroutine S09 (Link 2)	129
VII-34. Source program listing of subroutine S11 (Link 2)	130
VII-35. Source program listing of subroutine S13 (Link 2)	130
VII-36. Source program listing of subroutine S15 (Link 2)	131
VII-37. Source program listing of subroutine S17 (Link 2)	132
VII-38. Source program listing of subroutine S18 (Link 2)	132
VII-39. Source program listing of subroutine STFS (Link 2)	133
VII-40. Source program listing of subroutine STRA (Link 2)	133
VII-41. Source program listing of subroutine TICK (Link 2)	133
VII-42. Source program listing of subroutine TOPO (Link 2)	134
VII-43. Source program listing of subroutine TRAN (Link 2)	134
VII-44. Source program listing of subroutine TRIM (Link 2)	135
VII-45. Source program listing of subroutine TRM (Link 2)	135
VII-46. Source program listing of main program of Link 3 (deflection link)	136
VII-47. Source program listing of subroutine ELST (Link 3)	137
VII-48. Source program listing of subroutine PUNC (Link 3)	137
VII-49. Source program listing of subroutine RESI (Link 3)	137
VII-50. Source program listing of subroutine RESW (Link 3).	138
VII-51. Source program listing of subroutine TICK (Link 3)	138
VII-52. Source program listing of subroutine VELAS (Link 3)	139

Contents (contd)

Tables (contd)

VII-53. Source program listing of main program of Link 4 (stress link)	140
VII-54. Source program listing of subroutine ABEQ (Link 4)	141
VII-55. Source program listing of subroutine AGEL (Link 4)	142
VII-56. Source program listing of subroutine BEST (Link 4)	142
VII-57. Source program listing of subroutine BOFI (Link 4)	142
VII-58. Source program listing of subroutine CAS4 (Link 4)	143
VII-59. Source program listing of subroutine CODI (Link 4)	144
VII-60. Source program listing of subroutine DIMI (Link 4)	144
VII-61. Source program listing of subroutine DINA (Link 4)	145
VII-62. Source program listing of subroutine EPAN (Link 4)	146
VII-63. Source program listing of subroutine FINDQ (Link 4)	147
VII-64. Source program listing of subroutine FINDX (Link 4)	148
VII-65. Source program listing of subroutine GENE (Link 4)	148
VII-66. Source program listing of subroutine INER (Link 4)	148
VII-67. Source program listing of subroutine INLZ (Link 4)	149
VII-68. Source program listing of subroutine INV (Link 4)	150
VII-69. Source program listing of subroutine LEST (Link 4)	150
VII-70. Source program listing of subroutine MDIN (Link 4)	151
VII-71. Source program listing of subroutine META (Link 4)	152
VII-72. Source program listing of subroutine QUAD (Link 4)	153
VII-73. Source program listing of subroutine REVO (Link 4)	154
VII-74. Source program listing of subroutine ROTA (Link 4)	155
VII-75. Source program listing of subroutine SAME (Link 4)	156
VII-76. Source program listing of function SCAL (Link 4)	156
VII-77. Source program listing of subroutine SETA (Link 4)	157
VII-78. Source program listing of subroutine STRA (Link 4)	158
VII-79. Source program listing of subroutine STRS (Link 4)	158
VII-80. Source program listing of subroutine TEMP (Link 4)	159
VII-81. Source program listing of subroutine TICK (Link 4)	159
VII-82. Source program listing of subroutine TOPO (Link 4)	159
VII-83. Source program listing of subroutine TRAN (Link 4)	160
VII-84. Source program listing of subroutine UNIT (Link 4)	160
VII-85. Source program listing of subroutine VECT (Link 4)	160

Contents (contd)

Figures

VI-1. Flowchart of main program of Link 1 (input link)	27
VI-2. Flowchart of subroutine ARAN (Link 1)	29
VI-3. Flowchart of subroutine COOR (Link 1)	31
VI-4. Flowchart of subroutine EXCH (Link 1)	32
VI-5. Flowchart of function LEBIN (Link 1)	32
VI-6. Flowchart of subroutine SEBIN (Link 1)	33
VI-7. Flowchart of subroutine MEST (Link 1)	34
VI-8. Flowchart of subroutine OUTPT (Link 1)	36
VI-9. Flowchart of subroutine SRAT (Link 1)	37
VI-10. Flowchart of subroutine TABL (Link 1)	38
VI-11. Flowchart of subroutine TICK (Link 1)	39
VI-12. Flowchart of subroutine TOPO (Link 1)	40
VI-13. Flowchart of main program of Link 2 (generation link)	42
VI-14. Flowchart of subroutine ADM (Link 2)	45
VI-15. Flowchart of subroutine BEAM (Link 2)	46
VI-16. Flowchart of subroutine CODI (link 2)	47
VI-17. Flowchart of subroutine CORT (Link 2)	48
VI-18. Flowchart of subroutine CUTE (Link 2)	49
VI-19. Flowchart of subroutine DARN (Link 2)	50
VI-20. Flowchart of subroutine DMM (Link 2)	51
VI-21. Flowchart of subroutine ELDI (Link 2)	51
VI-22. Flowchart of subroutine PLBE (Link 2)	52
VI-23. Flowchart of subroutine RLOC (Link 2)	52
VI-24. Flowchart of subroutine S01 (Link 2)	53
VI-25. Flowchart of subroutine S02 (Link 2)	54
VI-26. Flowchart of subroutine S03 (Link 2)	55
VI-27. Flowchart of subroutine S04 (Link 2)	56
VI-28. Flowchart of subroutine S05 (Link 2)	57
VI-29. Flowchart of subroutine S07 (Link 2)	58
VI-30. Flowchart of subroutine S09 (Link 2)	59
VI-31. Flowchart of subroutine S11 (Link 2)	60
VI-32. Flowchart of subroutine S13 (Link 2)	60

Contents (contd)

Figures (contd)

VI-33. Flowchart of subroutine S15 (Link 2)	61
VI-34. Flowchart of subroutine S17 (Link 2)	64
VI-35. Flowchart of subroutine S18 (Link 2)	66
VI-36. Flowchart of subroutine STFS (Link 2)	67
VI-37. Flowchart of subroutine STRA (Link 2)	68
VI-38. Flowchart of subroutine TOPO (Link 2)	69
VI-39. Flowchart of subroutine TRAN (Link 2)	70
VI-40. Flowchart of subroutine TRIM (Link 2)	70
VI-41. Flowchart of subroutine TRM (Link 2)	70
VI-42. Flowchart of main program of Link 3 (deflection link)	71
VI-43. Flowchart of subroutine ELST (Link 3)	72
VI-44. Flowchart of subroutine RESI (Link 3)	74
VI-45. Flowchart of subroutine RESW (Link 3)	75
VI-46. Flowchart of subroutine VELAS (Link 3)	76
VI-47. Flowchart of main program of Link 4 (stress link)	78
VI-48. Flowchart of subroutine ABEQ (Link 4)	81
VI-49. Flowchart of subroutine BEST (Link 4)	82
VI-50. Flowchart of subroutine BOFI (Link 4)	83
VI-51. Flowchart of subroutine DIMI (Link 4)	88
VI-52. Flowchart of subroutine DINA (Link 4)	89
VI-53. Flowchart of subroutine EPAN (Link 4)	90
VI-54. Flowchart of subroutine FINDQ (Link 4)	92
VI-55. Flowchart of subroutine FINDX (Link 4)	92
VI-56. Flowchart of subroutine GENE (Link 4)	92
VI-57. Flowchart of subroutine INER (Link 4)	94
VI-58. Flowchart of subroutine INLZ (Link 4)	94
VI-59. Flowchart of subroutine INV (Link 4)	95
VI-60. Flowchart of subroutine LEST (Link 4)	97
VI-61. Flowchart of subroutine MDIN (Link 4)	98
VI-62. Flowchart of subroutine META (Link 4)	99
VI-63. Flowchart of subroutine QUAD (Link 4)	101
VI-64. Flowchart of subroutine REVO (Link 4)	103

Contents (contd)

Figures (contd)

VI-65. Flowchart of subroutine ROTA (Link 4)	105
VI-66. Flowchart of subroutine SAME (Link 4)	106
VI-67. Flowchart of function SCAL (Link 4)	107
VI-68. Flowchart of subroutine SETA (Link 4)	107
VI-69. Flowchart of subroutine STRS (Link 4)	110
VI-70. Flowchart of subroutine TEMP (Link 4)	111
VI-71. Flowchart of subroutine UNIT (Link 4)	111
VI-72. Flowchart of subroutine VECT (Link 4)	111

Abstract

A general-purpose digital computer program (named ELAS) for the in-core solution of linear equilibrium problems of structural mechanics is described for potential and actual users in Volume I of this report, and is documented in Volume II. The program requires minimum input for the description of the problem. The solution is obtained by means of the displacement method and the finite element technique. Almost any geometry and structure may be handled because of the availability of lineal, triangular, quadrilateral, tetrahedral, hexahedral, conical, triangular torus, and quadrilateral torus elements. The assumption of piecewise linear deflection distribution insures monotonic convergence of the deflections from the stiffer side with decreasing mesh size. The stresses are provided by the best-fit strain tensors in the least-squares sense at the mesh points where the deflections are given. The selection of local coordinate systems whenever necessary is automatic. The core memory is efficiently used by means of dynamic memory allocation, an optional mesh-point relabelling scheme, imposition of the boundary conditions during the assembly time, and the straight-line storage of the rows of the stiffness matrix within variable bandwidth and the main diagonal. The number of unsuppressed degrees of freedom that can be handled in a given problem is 500 to 600 for a typical structure, but might far exceed these average values for special types of problems; the execution time of such problems is about four minutes in 32K IBM 7094 Model I machines. The program is written in FORTRAN II language. The source deck consists of about 8000 cards and the object deck contains about 1400 binary cards. The physical program (standard ELAS) is available from COSMIC, the agency for the distribution of NASA computer programs.

I. Introduction

Volume I, *User's Manual*, of this report gives a general description of ELAS,* a general-purpose digital computer program for the in-core solution of linear equilibrium problems of structural mechanics, and contains the information necessary for input preparation, arrangement of the physical program, and interpretation of output and error messages. Volume II, *Documentation of the Program*, is published in two parts: the basic Volume II, which gives the theoretical background of the program and contains tables and figures describing the COMMON variables, their meanings, and their arrangement in COMMON; and this report—Addendum to Volume II—which contains program descriptions, flowcharts, and source program listings for all program elements of ELAS/Level 3. (The original version of the ELAS program made available from COSMIC** in April 1968 is designated ELAS/Level 0. Subsequent program corrections made in January 1969, March 1969, and May 1969 updated the program to ELAS/Level 1, ELAS/Level 2, and ELAS/Level 3, respectively.)

* First two syllables of the word Elasticity.

**Computer Software Management and Information Center, Computer Center, University of Georgia, Athens, Georgia, 30601, telephone 404-542-3265.

Sections II, III, IV, and V of the Addendum briefly describe the main programs and the subroutines of Links 1, 2, 3, and 4, respectively, of the ELAS program with reference to the flowcharts illustrated in Section VI, and the source program listings given in Section VII. Program descriptions include all subroutines that are not in the FORTRAN library. The standard ELAS is coded in FORTRAN II, with the exception of subroutines LEBIN, SEBIN, and TICK, which are in FAP. The subroutines are described in alphabetical order under each main program. The flowcharts, which are also in alphabetical order, present semidetailed diagrams of the sequential logic and decision points in the program. The source program listings are a straight listing of the first file in the program tape that contains the physical program.

The user of this Addendum will need both Volume I and the basic Volume II for reference because of numerous cross-references to figures and tables contained therein. The information in the referenced figures and tables is essential to interpretation of the content of the Addendum. Reference is also made herein to program input and output items and error messages, which are described and identified by number in Volume I.

II. Main Program and Subroutines of Link 1

A. Main Program of Link 1

The flowchart and the source program listing of the main program of Link 1 are given in Fig. VI-1 and Table VII-1, respectively. The logical function of the program may be summarized as follows:

- (1) It defines IN, IT, IDEG, ITYPE, IGEM, ISTR, IH, IS, IBN, IP, IPRS, IMAT, NTIC, ISDT, ISDY, ISDZ, IARE, IMMX, IMMY, IMMZ, IMFI, INX, INP, ISHUF, ICOR, IBUN, IMES, IPIR, ITAP, ITAS, G1, G2, G3, ACEL directly from Input Item 2.
- (2) It computes constants ISUM, IND, IORD, IORD1, and ZGEM, and pointers J1, J2, J3, J4, J5, J6, J7, J8, J9, J10, IBB, IBO, IID, IIA, IDT, IDY, ITE, ICAR, ICIX, ICIIY, ICIZ, ICFI, IXX, IYY, IZZ, IIC, IDEF, IST, IIS, IU, and IDZ from the information given by Input Item 2.
- (3) It generates the vectors related with pointers J1, J2, J3, J4, J5, J6, J7, J8, J9, J10, IBB, IBO, IIC, IXX, IYY, IZZ, and IDEF (partially) directly or indirectly from the input information of the job.
- (4) Depending upon the value of INX, it transfers control either to statement 2700 or to the main program of Link 3.

Before using any input information, the main program checks it against the input specifications (see Sect. III and IV, Vol. I). If the program encounters an irrecoverable error in the input information, it always branches to statement 300, which prints out COMMON both in fixed- and floating-point modes and skips the related job. In transferring information from input cards into the proper locations in COMMON, the program uses DUMMY (also called IDUM) area in COMMON for temporary storage. The main program calls subroutine TABL to print out Output Item 1; subroutine TICK to measure time; subroutine BUNG to generate deflection boundary conditions (dbc) input units automatically, if IBUN = 1; subroutine CORG to generate coordinates of the nodes automatically, if ICOR = 1; subroutine MESH to generate mesh topology and element properties automatically, if IMES = 1; subroutine COOR to read in, examine, and store nodal coordinates; subroutine MEST to read in and store element data; subroutine TOPO to examine and separate the element data in storage; and finally, subroutine SRAT to obtain internal node labels in vector ISIR, and the highest internal label in the node set of each node in vector IMAX (refer to Input Item 17, Sect. IV, Vol. I). Among these subroutines, subroutine SRAT has its own subroutine. The contribution of the prescribed concentrated loads to the right-hand-side vector of the equilibrium equations before the displacement boundary conditions are imposed is stored in the

IDEF-pointer-related vector, first as in item (1) of the IDEF entry of Table III-3, Vol. II (basic), and then as in item (2) in the same entry. Probably the most important function of the main program is the generation of vectors defined by pointers IBB, IBO, and IIC. The meanings of the entries of these vectors are given in Table III-3, Vol. II (basic), and Table VI-2, Vol. I. These vectors are first generated as if all deflections were independent and with IBB numbers always equal to $IND + 1$. Then the numbers are modified with the dbc input units to recognize linear dependence. Finally, when vectors ISIR and IMAX are provided by subroutine SRAT, they are finalized. Vectors defined by pointers IBB, IBO, and IIC are first used in the main program to compute the contribution of the prescribed concentrated loads to the reduced right-hand-side vector in the IDEF-pointer-related vector. Later in Link 2, they are used in computing the contributions of the element stiffness matrices to the reduced stiffness matrix in the IST-pointer-related vector and the reduced load vector in the IDEF-pointer-related vector, and the contributions of the element load vectors to the reduced load vector in the IDEF-pointer-related vector. In Link 3, these three vectors are used in obtaining the deflections of all nodes from the reduced deflection vector in the IDEF-pointer-related vector. The standard ELAS Link 1 main program assumes that $IN \leq 540$ and $ISUM < 10000$. (See Appendix, Vol. I, for instructions on how to change these limits.)

B. Subroutines of Link 1

1. **Subroutine ARAN.** Subroutine ARAN is called by subroutine SRAT. The flowchart and the source program listing of ARAN are given in Fig. VI-2 and Table VII-2, respectively. The logical function of the subroutine may be summarized as follows:

- (1) Subroutine ARAN generates vector IMAX for subroutine SRAT.
- (2) If $0 < ISHUF < 3$, the subroutine modifies vector ISIR and computes vector IMAX accordingly, to minimize the shaded area of the coefficient matrix shown in Fig. II-1 (Vol. I).
- (3) If $ISHUF = 2$, the subroutine reads cards for vector ISIR, modifies matrix ABIN accordingly, and performs the function given in (2).
- (4) The subroutine produces relabelling output items (Output Item 5) according to Sect. VI-F, Vol. I.

In performing these tasks, subroutine ARAN expects that connectivity matrix ABIN, ISIR vector of labels,

row order IN, and column order ISUR of matrix ABIN are available in COMMON. In performing logical function (2), the subroutine also generates vector IMIN. Subroutine ARAN calls subroutine OUTPT to print out mesh topology (P) of Output Item 5 (see Sect. VI-F, Vol. I), subroutine EXCH to interchange to successive rows and their respective columns in the connectivity matrix ABIN, function LEBIN to find out if a node is connected with another node, and subroutine TICK to measure relabelling time. The algorithm for logical function (2) is given in Ref. 1. The standard ELAS assumes that a word consists of 36 binary bits, and this is assumed in subroutine ARAN. (See Appendix, Vol. I, for instructions on how to change this constraint.)

2. **Subroutine BUNG.** Subroutine BUNG is called by the main program of Link 1, if $IBUN = 1$. The standard ELAS contains only the dummy version of this subroutine, as shown in Table VII-3. If $IBUN = 1$, the subroutine should be rewritten by the user, as explained in Sect. V-D, Vol. I. The logical function of the subroutine is to place IBN number of dbc input units into DUMMY or IDUM area.

3. **Subroutine COOR.** Subroutine COOR is called by the main program of Link 1, if $ICOR = 0$. The flowchart and the source program listing of COOR are given in Fig. VI-3 and Table VII-4, respectively. The function of this subroutine is to read the cards of Input Item 14 in blocks of not greater than 1000 nodes, to examine whether the node labels are sequential, and to generate IXX-, IYY-, and IZZ-pointer-related vectors. If $IGEM = 0$, the IZZ-pointer-related vector will not be generated. In case of error, the subroutine returns control to the calling program with $IERR = 1$, without completing its function.

4. **Subroutine CORG.** Subroutine CORG is called by the main program of Link 1, if $ICOR = 1$. The standard ELAS contains only the dummy version of this subroutine, as shown in Table VII-5. If $ICOR = 1$, the subroutine should be rewritten by the user, as explained in Sect. V-B, Vol. I. The logical function of this subroutine, when $ICOR = 1$, is to generate vectors related with pointers IXX, IYY, and IZZ.

5. **Subroutine EXCH.** Subroutine EXCH is called by subroutine ARAN. The flowchart and the source program listing of EXCH are given in Fig. VI-4 and Table VII-6, respectively. The function of this subroutine is to interchange the I th row with the IP th row of the ABIN matrix, and I th binary column with the IP th binary column

of the same matrix; MI is the smallest binary column number of the first nonzero binary entry either in row I or in row IP; MX is the largest binary column number of the last nonzero binary entry either in row I or in row IP. Since ABIN is a symmetric binary matrix, MI and MX also define the limits of the *I*th and *IP*th columns. Interchange operation is carried out only within these limits. The subroutine expects ABIN, I, IP, MI, and MX to be available in COMMON, and it assumes that a word consists of 36 binary bits. (See Appendix, Vol. I for instructions on how to change this limit.) Subroutine EXCH calls function LEBIN to obtain the value of a certain bit of a word, and subroutine SEBIN to store 1 or 0 in a certain bit of a word.

6. Function LEBIN. The subprogram LEBIN is called by subroutines ARAN and EXCH. The flowchart and the source program listing of LEBIN are given in Fig. VI-5 and Table VII-7, respectively. The coding is in FAP for the IBM 7094. The logical function of LEBIN is to return as a FORTRAN integer the value of the bit, shown in the second argument, of the word shown in the first argument. It assumes that the word length is 36 binary bits. For any other machine, this function should be rewritten.

7. Subroutine SEBIN. Subroutine SEBIN is called by subroutines EXCH and SRAT. The flowchart and the source program listing of SEBIN are given in Fig. VI-6 and Table VII-7, respectively. The coding is in FAP for the IBM 7094. The logical function of SEBIN is to store 1 or 0 (as shown in the third argument) in to the bit (shown in the second argument) of the word (shown in the first argument). The subroutine assumes that a word consists of 36 binary bits. For any other machine, this subroutine should be rewritten.

8. Subroutine MESC. Subroutine MESC is called by the main program of Link 1, if $IMES = 1$. The standard ELAS contains only the dummy version of this subroutine, as shown in Table VII-8. If $IMES = 1$, the subroutine should be rewritten by the user, as explained in Sect. V-C, Vol. I. The logical function of this subroutine, when $IMES = 1$, is to generate vectors related with pointers J1, J2, J3, J4, J5, J6, J7, J8, J9, and J10.

9. Subroutine MEST. Subroutine MEST is called by the main program of Link 1, if $IMES = 0$. The flowchart and the source program listing of MEST are given in Fig. VI-7 and Table VII-9, respectively. The function of this subroutine is first to read the cards of Input Item 16, one or more at a time, into DUMMY area, and to check

the validity of M number of the element descriptors (see Table IV-3, Vol. I), then to store words J1W, J2W, J3W, J4W, J5W, and if they exist, J6W, J7W, J8W, J9W, J10W of the element descriptors into the proper locations in the respective vectors related with pointers J1, J2, J3, J4, J5, J6, J7, J8, J9, and J10, and to check the positiveness of the vertex labels. In case of error, the subroutine returns control to the calling program with $IERR = 1$, without completing its function. If no error is encountered, the subroutine performs its operations on the input cards of every element, sequentially, until all element data are processed.

10. Subroutine OUTPT. Subroutine OUTPUT is called by subroutine ARAN, if $INP = 2$. The flowchart and the source program listing of OUTPT are given in Fig. VI-8 and Table VII-10, respectively. The function of this subroutine is to print out Output Item 5(P) (see Sect. VI-F, Vol. I). This subroutine assumes that a word is 36 binary bits and $IN \leq 540$. (See Appendix, Vol. I for instructions on how to change these limits.) Subroutine OUTPT expects ISIR, IMIN, IMAX vectors, ABIN matrix, IN, and ISUR to be available in COMMON.

11. Subroutine SRAT. Subroutine SRAT is called by the main program of Link 1. The flowchart and the source program listing of SRAT are given in Fig. VI-9 and Table VII-11, respectively. The functions of this program may be summarized as follows:

- (1) If $ISHUF = 3$, subroutine SRAT reads the cards of Input Item 17 for the generation of internal node labels in vector ISIR, and the highest internal label in the node set of each node in vector IMAX (refer to Input Item 17, Sect. IV, Vol. I). If $ISHUF \neq 3$, subroutine SRAT generates vector ISIR by assuming that internal and external labels of the nodes are the same; computes ISUR, which is the number of words whose binary bits are enough to provide one bit for each of the IN nodes; generates connectivity matrix ABIN from the mesh-topology information of Input Item 16 and from the deflection boundary condition input units already in the IBO-pointer-related vector; and calls subroutine ARAN to obtain the finalized values of vectors ISIR and IMAX. (In generating the binary connectivity matrix ABIN, subroutine SRAT first clears matrix ABIN; then it processes elements one at a time by first listing the labels of the vertices of the element and the labels of the nodes connected with these vertices through the dbc

input items; and then indicates, by means of a binary 1 in the proper places in matrix ABIN, the fact that all these nodes are connected with each other. In matrix ABIN, one row and one column are assigned to every node so that ABIN is a symmetric matrix. If a node i is connected with a node j , the i th row and the j th column, and likewise the j th row and the i th column, of the binary matrix ABIN contain a binary bit 1. All diagonal elements of the binary matrix ABIN are binary bit 1. If a node is constrained completely by means of dbc input items the only nonzero bit in the row and the column of this node is on the diagonal. The ordering of rows and columns of the binary matrix ABIN is done by the order that is available in vector ISIR.)

- (2) If $INP \neq 0$, subroutine SRAT generates and prints out Output Item 6.
- (3) It generates the vector related with pointer IU, and if $INP \neq 0$, prints it as Output Item 9.
- (4) It computes the number of words between points D and F, and between the beginning of COMMON and point G, designated in Fig. III-1, Vol. II (basic), and prints out Output Items 7 and 8.
- (5) It prints Error Message 5 (see Table VII-1, Vol. I) if the number of words to the left of point G is less than 12,750, which is based on the assumption that the core memory is 32,768 words. (See Appendix, Vol. I for instructions on how to modify the program for other core memory sizes.)

Subroutine SRAT calls subroutine TOPO in obtaining the vertex labels of the elements, subroutine SEBIN in generating binary matrix ABIN, and subroutine ARAN to obtain vector IMAX and the corresponding vector ISIR.

12. Subroutine TABL. Subroutine TABL is called by the main program of Link 1. The flowchart and the source program listing of TABL are given in Fig. VI-10 and Table VII-12, respectively. The function of this subroutine is to print out Output Item 1. It expects the contents of Input Items 1 and 2 to be available in COMMON.

13. Subroutine TICK. Subroutine TICK is called by the main program of Link 1. It is also called by subroutine ARAN and by the main programs of Links 2, 3, and 4. The flowchart and the source program listing of subroutine TICK are given in Fig. VI-11 and Table VII-13, respectively. The coding is in FAP for the IBM 7094. The subroutine expects the time in units of 1/60 second in the absolute memory location 5 as a binary integer. Its function is to return, as a FORTRAN integer in the argument, the time, in 1/60-second units, elapsed since the first call. (See Appendix, Vol. I, for instructions on how to change this subroutine for other machines.)

14. Subroutine TOPO. Subroutine TOPO is called by the main program of Link 1. It is also called by subroutine SRAT. The flowchart and the source program listing of TOPO are given in Fig. VI-12 and Table VII-14, respectively. The function of this subroutine may be summarized as follows:

- (1) It extracts from J1-, J2-, J3-, J4-, J5-, J6-, J7-, J8-, J9-, and J10-pointer-related vectors for the M th element the vertex labels in N_i vector, the pressure type number in JPRS, the material type number in IMET, the thickness type number in ITIC, the temperature increase type number in ITEM, the temperature gradient in y -direction type number in JSDY, the temperature gradient in z -direction type number in JSDZ, the cross-sectional area type number in JARE, the torsional constant type number in JMMX, the y -moment of inertia type number in JMMY, the z -moment of inertia type number in JMMZ, and the angle for principal axes type number in JMFI, as described in Table III-2 (Vol. II, basic).
- (2) It checks whether the vertex labels and the property type numbers are within the bounds prescribed in Input Item 2. In case of error, the subroutine continues scanning the properties of the M th element and prints out Error Message 3 (see Table VII-1, Vol. I) after executing the implementation of the message.

III. Main Program and Subroutines of Link 2

A. Main Program of Link 2

The flowchart and the source program listing of the main program of Link 2 are given in Fig. VI-13 and Table VII-15, respectively. The logical function of the program may be summarized as follows:

- (1) It clears the reduced stiffness matrix area (the IST-pointer-related vector of Table III-3, Vol. II, basic).
- (2) It generates the elemental matrices in S and P areas, and assembles these into IST- and IDEF-pointer-related vectors, sequentially.
- (3) It stores on tape ITAS (if available) the elemental matrices, sequentially.
- (4) Depending upon the value of INX, it transfers control either to the main program of Link 1 or to the main program of Link 3.

In carrying out function (2) listed above, the program executes a DO-loop on element labels M. In this loop, for any element M, it first clears a certain work area (see block *133 in Fig. VI-13) and sets the variables

ITTT = 0, ITTM = NAV = 1, and CFE = 1. Variable ITTM is not in COMMON. For element types 1, 2, 3, 4, 5, 7, 9, 11, 13, 15, 17, and 18, ITTM = NAV = 1 and CFE = 1., and ITTT is made 1 at block 5100 of Fig. VI-13. For the remaining element types, that is, element types 6, 8, 10, 12, 14, and 16, the program establishes subelements as described in Table VI-5 (Vol. I). For element types 6, 8, 12, 14, and 16, the program obtains two triangles for every quadrilateral in two ways, as shown in Table VI-5 (Vol. I). Since such a procedure is equivalent to doubling the material volume of the structure, the elemental matrices are weighted with constant CFE = 1/2 (See block 4902 of Fig. VI-13); ITTM is the number of the subelements and ITTT is the subelement count in each way of subdivision, and NAV - 1 is the count of subdivisions. For example, NAV = 2, ITTT = 2 means the second triangle of the first way of subdivision, and NAV = 3, ITTT = 1 means the first triangle of the second way of subdivision. The same symbolism applies for element type 10, where ITTM = 5, which indicates that there are five tetrahedrons for every way of subdividing a hexahedron. The subdivision procedure is achieved as indicated in block 504 of Fig. VI-13, with the help of subroutine CUTE.

In the DO-loop on elements, after the initialization of block *133 (Fig. IV-13), by means of subroutine TOPO, the descriptive words of the element (the quantities listed in J1- through J10-pointer-related vectors) are extracted and analyzed to obtain the vertex labels in N block and the property type numbers. Next, the vertex labels are copied to NOO block in preparation for the subdivision operation and IMS is established. Following this, the order of the element stiffness matrix IDS is determined, actual values of load and geometry constraints are obtained, and the material constants are prepared. Even if an element is subdivided, the same load, geometry, and material constants are used for the subelements. The following constants are prepared, as explained in Sect. III-C, Vol. I: E and G for element types 1, 2, 3, and 4; D21 for element types 9, 10, 15, and 16; D33 for element types 5, 6, 7, 8, 11, 12, 13, and 14; and E22 for element types 7, 8, 11, 12, and 18. The constant E is the Young's modulus, G is the shear modulus, D21 is the upper half of the 6×6 material matrix, D33 is the material constants matrix for in-plane deformations, and E22 is the material constants matrix for out-of-plane deformations. Finally, arrays related with subelement vertex coordinates and labels are prepared (see block 5100, Fig. VI-13), the subelement count ITTT is set, and the number of entries in the free-free stiffness matrix, IDS2, is obtained; and S and P areas are cleared for elemental matrices of the subelement/element (see block 5600, Fig. VI-13).

In the DO-loop on elements, for every subelement/element, a free-free stiffness matrix and a load vector are generated in S and P, respectively. For this purpose the program calls subroutine STFS, which, in turn, calls the proper subroutine determined by the type number of the current element. These subroutines are S01, S02, S03, S04, S05, S07, S09, S11, S13, S15, S17, and S18. The numeral in these names corresponds to the type number of the element for which the subroutine is directly applicable. In all these subroutines, the input information is in X, Y, Z, XD, YD, ZD, DT, DG, DGY, DGZ, TE, AL1, AL2, AL3, E, G, D21, D33, E22, PRES, ACEL, N, CONS, UV, and COMMON 200-328 locations. The output consists of S, P, and sometimes IPBG and IPEN constants. The latter two constants indicate whether the element load vector in P is complete, or whether some additional operation is necessary in the main program. If IPBG is nonpositive and $IPBG < IPEN$, no additional operation is expected from the main program to modify load vector P. The thermal portion of load vector P is always completed by the main program. Before the subroutines

are called, the main program sets in vector UV the list of vertex deflections due to DT of the free-free element. The subroutines called by subroutine STFS modify this vector properly so that the portion of the element load vector due to temperature changes can be added to P as the product of the free-free stiffness matrix of the element (the quantities in S) times the deflections in UV by means of subroutine DMM. This is shown in block 951 of Fig. VI-13. In this figure, Block 953 corresponds to the inquiries on constants IPEN and IPBG. The modification to vector P in the main program consists of adding certain constant values derived from CONS, PRCO, and PD values to certain subvectors of P as indicated by IPEN and IPBG. The values of IPEN, IPBG, CONS, PRCO, and PD are determined by the subroutine that generates S and P.

After the generation of S and P in the DO-loop on elements, the main program scans each entry of S and P one at a time and assembles it to the governing equations of the system. This is the operation in block 9532 of Fig. VI-13, which ends just before block 95*. The assembly procedure is described in Sect. II, Vol. II (basic). With the notation given there, \underline{a} , \tilde{e}'_a , i'_a , and \underline{b} , \tilde{e}'_b , j'_b are generated in IQE, CCCI, IBS and JQE, CCCJ, JBS locations of COMMON, respectively, by means of subroutine DARN. After the assembly of the subelement/element matrices S and P, if a scratch tape is available, the operations shown in block 9982 (Fig. IV-13) are for future reference. Next, ITTT is compared with ITTM, and the value of NAV (which is updated by subroutine CUTE) is inquired. When the last subelement of the last subdivision is completed, the process is repeated for the next element until all the elements are handled. Then, scratch tape ITAS (if prescribed) is rewound, the total time elapsed since the first entry to the main program is obtained by means of subroutine TICK and recorded, and the transfer of control is made.

The main program of Link 2 is also responsible for the production of Output Items 14, 15, 16, and 17, as prescribed by INP and subroutine CAS2 (see Table VI-1, Vol. I). At the end of Link 2, the coefficients in the shaded areas of Fig. II-1, Vol. I, are generated and stored in IST- and IDEF-pointer-related arrays of COMMON.

B. Subroutines of Link 2

1. *Subroutine ADM.* Subroutine ADM is called by subroutines S05, S07, S09, S15, S17, and S18. The flow-chart and the source program listing of ADM are given

in Fig. VI-14 and Table VII-16, respectively. The subroutine has seven arguments. The function of the subroutine is to add a constant times a square matrix to another one which is symmetric. The constant is given by the seventh argument, the matrix to be added is given by the third argument, and the matrix to be increased is given by the first argument. The order of the latter matrix is given in the second argument, the order of the former by the fourth argument. Since the orders are different, the row and column numbers of the entry in the matrix of the first argument corresponding to the first entry of the matrix of the third argument are given with the fifth and sixth arguments. The addition operation is carried out such that the matrix of the first argument always remains symmetrical. Both matrices are assumed to be listed columnwise, with the column orders as prescribed by the second and fourth arguments. The order of the matrix in the third argument cannot be larger than 4. There is no error return of the subroutine. In all cases, the matrix in the first argument is the free-free stiffness matrix of various types of elements, and the matrix in the third argument is usually a submatrix related with given degree-of-freedom directions.

2. Subroutine BEAM. Subroutine BEAM is called by subroutines S02 and S04. The flowchart and the source program listing of BEAM are given in Fig. VI-15 and Table VII-17, respectively. This subroutine generates, in local coordinates, the free-free stiffness matrix of a planar beam element and stores it in A(6,6), which is located in COMMON (200). The matrix may be partitioned with respect to degrees of freedom (nine submatrices, 2×2 each). In generation of the stiffness matrix, the shear deformations are ignored.

3. Subroutine CAS2. Subroutine CAS2 is called by the main program of Link 2. The standard ELAS contains only the dummy version of this subroutine, as shown in Table VII-18. If Output Items 14, 15, and 16 are to be produced selectively, the subroutine should be rewritten by the user, as explained in Sect. V-G, Vol. I. The logical function of this subroutine is to change the value of INP as desired in the DO-loop on elements of the main program of Link 2.

4. Subroutine CODI. Subroutine CODI is called by subroutines S02, S03, and S04. The flowchart and the source program listing of CODI are given in Fig. VI-16 and Table VII-19, respectively. The subroutine generates the direction cosines of the local axes for element types 2, 3, and 4 in DIR(3,3) array, which is located in

COMMON(264). The first row of DIR corresponds to local x -axis, the second row corresponds to local y -axis, and the third row corresponds to local z -axis. (See Table III-3, Vol. I, and the description of Input Item 13, Sect. IV-B, Vol. I, for the rules covering the local coordinate systems of these elements.) The subroutine sets IERR = 1 and returns control to the calling program as soon as an error is detected.

5. Subroutine CORT. Subroutine CORT is called by subroutines S11 and S13. The flowchart and the source program listing of CORT are given in Fig. VI-17 and Table VII-20, respectively. The subroutine generates the direction cosines of the local coordinate axes for elements 11 and 13 in DIR(3,3) array, which is located in COMMON(264). The first, second, and third rows of DIR correspond to the first, second, and third local axis, respectively. (See Table III-3, Vol. I, for the rules in selecting the local coordinate system for elements 11 and 13.) After computation of direction cosines, the subroutine replaces X, Y, and Z values with the coordinates of the vertices in a coordinate system located usually at the centroid of the element and yet parallel to the local coordinate system of the element. Next, the subroutine computes in XD, YD, and ZD the coordinates of the second and third vertex in a coordinate system that is located at the first vertex, yet is parallel to the local coordinate system of the element. There is no error return in the subroutine.

6. Subroutine CUTE. Subroutine CUTE is called by the main program of Link 2. The flowchart and the source program listing of the subroutine are given in Fig. VI-18 and Table VII-21, respectively. This subroutine has the ITTM value as an argument (see Sect. III-A). The subroutine is called twice for element types 6, 8, 10, 12, 14, and 16 and is not called for other types of elements. Each time it is called for an element, the subroutine increments NAV (see Sect. III-A) by 1; determines ITTM, IMS, IELT, IDS values for the subelements; and generates in NOO array the list of mesh-point labels that conform to the (NAV - 1)st row in part A or B of Table VI-5, Vol. I, depending upon whether the value of ITTM is 2 or 5, respectively. For example, for a quadrilateral element with mesh-point labels 13, 8, 51, 16, the value of ITTM is 2, and if NAV = 2, according to the first line of Table VI-5A, Vol. I, the NOO array contains the following list: 13, 8, 51, 51, 16, 13. There is no error return in the subroutine.

7. Subroutine DARN. Subroutine DARN is called by the main program of Link 2. The flowchart and the

source program listing of the subroutine are given in Fig. VI-19 and Table VII-22, respectively. The subroutine has four arguments. The last three arguments, KBS, CCC, and KQE, correspond to i'_a , \tilde{e}'_a , and \underline{a} (or j'_b , \tilde{e}'_b , and \underline{b}), respectively, of Sect. II, Vol. II (basic). The first argument is the label of the degree-of-freedom direction under question (see Sect. III-A). To achieve this function, subroutine DARN interprets the entries of IBB-, IBO-, and IIC-pointer-related vectors, as described in Table VI-2, Vol. I. In case of error, the last argument is set to zero, and the subroutine returns control to the calling program.

8. Subroutine DMM. Subroutine DMM is called by the main program of Link 2. The flowchart and the source program listing of the subroutine are given in Fig. VI-20 and Table VII-23, respectively. The subroutine has four arguments. The first argument is a square matrix, and the second and fourth are vectors of order given by the third argument. The square matrix is assumed to be listed columnwise (the number and orders of the vectors being equal to the third argument). The subroutine adds on the vector in the fourth argument the product of the matrix in the first argument by the vector in the second argument. There is no error return in the subroutine.

9. Subroutine ELDI. Subroutine ELDI is called by subroutines S01, S02, and S04. The flowchart and the source program listing of ELDI are given in Fig. VI-21 and Table VII-24, respectively. The subroutine generates in vector PD the direction cosines of the pressure direction for element types 1, 2, and 4. (See description of Input Item 4, Sect. IV-B, Vol. I, and Table III-3, Vol. I, for the rule for determining the pressure direction.) If the element is in the general wind direction, the pressure is set to zero. If an error is encountered, IERR is set to 1, and the subroutine returns control to the calling program.

10. Subroutine PLBE. Subroutine PLBE is called by subroutines S03, and S04. The flowchart and the source program listing of PLBE are given in Fig. VI-22 and Table VII-25, respectively. This subroutine generates, in local coordinates, the free-free stiffness matrix of a grid beam element in A(6,6), which is located in COMMON(200). The matrix may be partitioned with respect to degrees of freedom (nine submatrices, 2×2 each). In generation of the stiffness matrix, the shear deformations are ignored.

11. Subroutine RLOC. Subroutine RLOC is called by subroutines S02, S03, and S04. The flowchart and the

source program listing of RLOC are given in Fig. VI-23 and Table VII-26, respectively. Its function is similar to that of subroutine ADM, described in Sect. III-B. The arguments in this subroutine are all implicit. They are S, A, IDS, II, JJ, IR, JR, NY. The subroutine assumes that S is an $IDS \times IDS$ matrix; A is a 6×6 matrix. The objective of the subroutine is to put $NY \times NY$ submatrix of matrix A on matrix S. The constants II and JJ are the row and column numbers of the first word of $NY \times NY$ submatrix of matrix A. The constants IR and JR are the row and column numbers of the corresponding word in matrix S. In contrast to subroutine ADM, subroutine RLOC does not add, but replaces the entries of matrix A on S. After the replacement, the processed portion of A is nullified. There is no error return in the subroutine.

12. Subroutine S01. Subroutine S01 is called by subroutine STFS. The flowchart and the source program listing of S01 are given in Fig. VI-24 and Table VII-27, respectively. The subroutine generates in S the free-free stiffness matrix of element type 1 in the overall coordinate system, and determines constants PRCO, CONS, IPBG, and IPEN for the generation of load vector P (also in overall coordinates) in the main program of Link 2, as described in Sect. III-A. The portion of the load vector related with the temperature change is also handled in the main program of Link 2. To obtain the direction cosines of the unit vector in the pressure direction, subroutine S01 calls subroutine ELDI. When an error condition is encountered, subroutine S01 sets IERR to 1 and returns control to the calling program.

13. Subroutine S02. Subroutine S02 is called by subroutine STFS. The flowchart and the source program listing of S02 are given in Fig. VI-25 and Table VII-28, respectively. The subroutine generates in S the free-free stiffness matrix of element type 2 in the overall coordinate system, determines constants PRCO, CONS, IPBG, IPEN, and modifies vector UV so that load vector P expressed in overall coordinates can be generated by the main program of Link 2 (see Sect. III-A). By calling subroutine CODI, subroutine S02 first generates the direction cosines of the local axes in DIR(3,3). Then subroutine BEAM is called to generate in A(6,6) the free-free stiffness matrix of the element in the local coordinate system. The direction cosines of the direction normal to the element are obtained and stored in PD(3) by means of subroutine ELDI. Then the free-free stiffness matrix, in local coordinates, is carried from A(6,6) into S by means of subroutine RLOC. Finally, by calling subroutine STRA, subroutine S02 obtains and stores in S the description of

the free-free stiffness matrix in the overall coordinate system. The content of COMMON location IERR is transmitted intact to the calling program for error handling.

14. Subroutine S03. Subroutine S03 is called by subroutine STFS. The flowchart and the source program listing of S03 are given in Fig. VI-26 and Table VII-29, respectively. The subroutine generates in S the free-free stiffness matrix of element type 3 in the overall coordinate system, modifies vector UV so that the portion of element load vector P related with the thermal loads can be generated in the main program of Link 2, and generates the remaining portion of element load vector P in the overall coordinate system. By calling subroutine CODI, subroutine S03 generates the direction cosines of the local axes in DIR(3,3). Then, by means of subroutine PLBE, the free-free stiffness matrix of the element in the local coordinate system is obtained and stored in A(6,6). The free-free stiffness matrix in local coordinates is carried from A(6,6) into S by means of subroutine RLOC. By calling subroutine STRA, subroutine S04 obtains and stores in S the description of the free-free stiffness matrix in the overall coordinate system. The load vector due to pressure and acceleration is obtained in the overall coordinate system and stored in P. The distortions of the free-free element due to temperature gradient are first obtained in the local coordinate system, then, by means of subroutine TRAN, in the overall coordinate system, and both descriptions are placed in UVG. Vector UVG is then added to vector UV, so that the main program of Link 2 can handle the thermal portion of P (see Sect. III-A). The content of COMMON location IERR is transmitted intact to the calling program for error handling.

15. Subroutine S04. Subroutine S04 is called by subroutine STFS. The flowchart and the source program listing of S04 are given in Fig. VI-27 and Table VII-30, respectively. The program generates in S the free-free stiffness matrix of element type 4 in the overall coordinate system, and the description of the element load vector P in the overall coordinate system is partly obtained. The remaining portion of element load vector P is obtained in the main program of Link 2. By calling subroutine CODI, subroutine S04 first obtains and stores in DIR(3,3) the direction cosines of the local axes. Then the contributions of the pressure and the acceleration loadings to the description of element load vector P in the overall coordinate system are partly obtained. In obtaining the pressure direction, subroutine S04 calls

subroutine ELDI. The stiffness matrix in the local coordinates is obtained in two steps. In the first step, subroutine BEAM is called to obtain the stiffness of the element in the local xy plane for storage in A(6,6). Then this matrix is carried into S by calling subroutine RLOC four times. In the second step, subroutine PLBE is called to obtain the stiffness of the element for deformations out of the local xy plane for storage in A(6,6), and the matrix is carried into S by calling subroutine RLOC once. The description of the free-free stiffness matrix is first obtained in local coordinates, then by means of subroutine STRA, in overall coordinates, for storage in S. So that the thermal load portion of P can be properly obtained in the main program of Link 2, subroutine S04 first computes into UVG the distortions of the free-free element due to temperature gradients, in the local coordinate system. Then, by means of subroutine TRAN, this vector is expressed in the overall coordinate system and added to vector UV. The content of COMMON location IERR is transmitted intact to the calling program for error handling.

16. Subroutine S05. Subroutine S05 is called by subroutines STFS, S11, S13, and S15. The flowchart and the source program listing of S05 are given in Fig. VI-28 and Table VII-31, respectively. When called by STFS (COMMON location IGEM is zero when called by STFS), subroutine S05 generates the free-free stiffness matrix S and partially generates load vector P of element type 5 in the overall coordinate system. When called by subroutines S11 and S13, it generates S and P (partially) in the local coordinates of the element, for element types 11 and 13, respectively, for membrane stretching. Actually, for the latter type of elements, X, Y, Z, XD, YD, and ZD contain local coordinates of the vertices. By calling subroutine TRIM, subroutine S05 first generates $[M]$ and $[N]$ matrices (defined in Ref. 2), in EM and EN locations in COMMON. The $[D]$ matrix (Ref. 2) corresponds to D33 in the subroutine. As far as the free-free stiffness matrix is concerned, the objective of this subroutine is to generate the $[K_M]$ matrix of Eq. (46) in Ref. 2 with $a = b = c = d = e = 0$. Submatrices $[P]$, $[Q]$, and $[R]$ (Ref. 2) are obtained by executing the triple matrix products by means of subroutine TRM, and then placed into S by means of subroutine ADM. For element types 11 and 13, pressure loading is not considered in this subroutine, but for element type 5, the pressure loading is handled in this routine. In the latter case, if the element is a subelement, the pressure is considered only for the first subelement of both ways of subdivisions (see Sect. III-A). Constants IPBG, IPEN, and CONS for

the handling of the acceleration loading in the main program of Link 2 are generated in this subroutine for all cases. The temperature loading portion of element load vector P is also handled in the main program of Link 2. When an error condition is encountered, the subroutine sets IERR to 1 and returns control to the calling program. The explicit expression of the free-free stiffness matrix may be obtained from Ref. 2.

17. Subroutine S07. Subroutine S07 is called by subroutines STFS and S11. The flowchart and the source program listing of S07 are given in Fig. VI-29 and Table VII-32, respectively. If the calling program is S11, then X, Y, Z, XD, YD, and ZD contain the local coordinates of the vertices; therefore S and P represent the free-free stiffness matrix and the element load vector for bending of element type 11, in local coordinates. If the calling program is STFS, S and P represent the free-free stiffness matrix and the element load vector of element type 7, in the overall coordinate system. The portion of P related with pressure loading is generated by subroutine S07. The constants IPBG, IPEN, and CONS are generated by subroutine S07 so that the portion of the vector P related with acceleration loading can be handled in the main program of Link 2 (see Sect. III-A). The portion of P related with the thermal loads is also handled in the main program of Link 2. Subroutine S07 generates in vector UV the distortions of the free-free element due to temperature gradient (see Sect. III-A). By calling subroutine TRIM, subroutine S07 first obtains $[M]$, $[N]$, and $[L]$ matrices of Ref. 2 in locations EM, EN, and EL. The matrices $[D]$ and $[D']$ of this reference correspond to D33 and E22 in the subroutine. The triple matrix products indicated by Eqs. (45) and (51) of Ref. 2 are carried out by means of subroutine TRM, and are properly placed into S by means of subroutine ADM. The objective of subroutine S07 in generating S is to obtain the shaded portions of $[K_b]$ and $[K_s]$ matrices given by Eqs. (49) and (55) of Ref. 2. In generating the shaded portion of $[K_s]$ given by Eq. (55) of Ref. 2, the subroutine uses the "constant trace scheme" of Ref. 3. When an error condition is detected, the subroutine sets IERR to 1 and returns control to the calling program.

18. Subroutine S09. Subroutine S09 is called by subroutine STFS. The flowchart and the source program listing of S09 are given in Fig. VI-30 and Table VII-33, respectively. The objective of this subroutine is to compute the free-free stiffness matrix and the element load vector of element type 9, in the overall coordinate system, into locations S and P. The portion of P related with

pressure loading is generated in subroutine S09. The subroutine generates the values of IPBG, IPEN, and CONS values for the handling of the acceleration loading portion of P in the main program of Link 2, which also handles the thermal load portion. The submatrices of the free-free stiffness matrix are obtained in the form of triple matrix products computed by means of subroutine TRM. These submatrices are properly placed in S by means of subroutine ADM. If the volume of the element is too small relative to a reference volume, an error message is printed out and the generation of S and P is skipped. If an error condition is encountered during the execution of the subroutine, IERR is set to 1, and control is returned to the calling program.

19. Subroutine S11. Subroutine S11 is called by subroutine STFS. The flowchart and the source program listing of S11 are given in Fig. VI-31 and Table VII-34, respectively. The objective of this subroutine is to generate the free-free stiffness matrix and partially generate the element load vector in S and P, respectively, of element type 11, in the overall coordinate system. The matrix in S is that of Eq. (61) of Ref. 2, with $a = b = c = d = e = 0$. Subroutine S11 first calls subroutine CORT to obtain and store in X, Y, Z, XD, YD, ZD, the coordinates of the vertices in the local coordinate system, and the direction cosines of the local axes in DIR(3,3). Next, by calling subroutine S07, subroutine S11 generates the bending portion of S and P by assuming the order as 9. Next, the quantities in S and P are properly relocated so that S and P are of order 18. The same relocation is applied to vector UV, which is generated by subroutine S07. After this, subroutine S11 calls subroutine S05 to generate the membrane portion of S and P. The P vector is partially generated in subroutine S11. The acceleration loading and the thermal loading portions of P are handled in the main program of Link 2 (see Sect. III-A). Subroutine S11 calls subroutine TRAN to express P and UV in overall coordinates, and subroutine STRA to express S in overall coordinates. The content of COMMON location IERR is transmitted intact to the calling program for error handling.

20. Subroutine S13. Subroutine S13 is called by subroutine STFS. The flowchart and the source program listing of S13 are given in Fig. VI-32 and Table VII-35, respectively. The objective of this subroutine is to generate the free-free stiffness matrix and partially generate the element load vector in S and P, respectively, of element type 13, in the overall coordinate system. Subroutine S13 first calls subroutine CORT to obtain and store

in X, Y, Z, XD, YD, ZD the coordinates of the vertices in the local coordinate system, and the direction cosines of the local axes in DIR(3,3). Next, subroutine S13 calls subroutine S05 to generate the membrane rigidity and the corresponding load vector in S and P. The pressure load portion of P is generated in subroutine S13, and the acceleration loading portion and the thermal load portion of P are generated in the main program of Link 2 (see Sect. III-A). Having generated S and P in local coordinates, subroutine S13 calls subroutine TRAN to express P in the overall coordinate system, and subroutine STRA to express S in the overall coordinate system. The content of COMMON location IERR is transmitted intact to the calling program for error handling.

21. Subroutine S15. Subroutine S15 is called by subroutine STFS. The flowchart and the source program listing of S15 are given in Fig. VI-33 and Table VII-36, respectively. The objective of this subroutine is to generate the free-free stiffness matrix and the element load vector of element type 15, in locations S and P, expressed in the overall coordinate system. Only the thermal load portion of P is generated in the main program of Link 2 (see Sect. III-A). The generation of the free-free stiffness matrix is performed as described in Ref. 4. The terminology of Table VII-36 should be interpreted in the light of Ref. 4. Subroutine S15 calls subroutine TRIM to obtain the EM and EN arrays corresponding to M and N, respectively, of Ref. 4. The triple matrix products of Ref. 4 are performed by means of subroutine TRM, and properly placed in S by means of subroutine ADM. The first term in Eq. (9) of Ref. 4 is obtained in S by means of subroutine S05. In case of error, IERR location is set to 1 and control is returned to the calling program.

22. Subroutine S17. Subroutine S17 is called by subroutines STFS and S18. The flowchart and the source program listing of S17 are given in Fig. VI-34 and Table VII-37, respectively. The objective of this subroutine is to generate the free-free stiffness matrix and the element load vector of element type 17, in locations S and P, expressed in the overall coordinate system. Only the thermal load portion of P is generated in the main program of Link 2 (see Sect. III-A). The generation of the free-free stiffness matrix is performed as described in Ref. 5. The triple matrix products of this reference are performed by means of subroutine TRM, and properly placed in S by means of subroutine ADM. The terminology in Table VII-37 should be interpreted in the light of Ref. 5. In case of error, location IERR is set to 1 and control is returned to the calling program.

23. Subroutine S18. Subroutine S18 is called by subroutine STFS. The flowchart and the source program listing of S18 are given in Fig. VI-35 and Table VII-38, respectively. The objective of this subroutine is to generate the free-free stiffness matrix and the element load vector of element type 18, in locations S and P, expressed in the overall coordinate system. Only the thermal load portion of P is generated in the main program of Link 2 (see Sect. III-A). The generation of the free-free stiffness matrix is performed as described in Ref. 5. For this purpose, subroutine S18 first calls subroutine S17 to generate the membrane portion of S and P. The triple matrix products of Ref. 5 are performed by means of subroutine TRM, and properly placed in S by means of subroutine ADM. The terminology in Table VII-38 should be interpreted in the light of Ref. 5. Before returning control to the calling program, the subroutine modifies vector UV for the inclusion of thermal gradient effects. The content of COMMON location IERR is transmitted intact to the calling program for error handling.

24. Subroutine STFS. Subroutine STFS is called by the main program of Link 2. The flowchart and the source program listing of STFS are given in Fig. VI-36 and Table VII-39, respectively. The subroutine has one argument, which is the type number of the current element being processed by the calling program. The function of this subroutine is to call the proper subroutine from among S01, S02, S03, S04, S05, S07, S09, S11, S13, S15, S17, and S18 to suit the type number in the argument. The functions of these subroutines are to generate the free-free stiffness matrix, and partially generate the element load vector, in locations S and P, expressed in the overall coordinate system. There is no error return in the subroutine.

25. Subroutine STRA. Subroutine STRA is called by subroutines S02, S03, S04, S11, and S13. The flowchart and the source program listing of STRA are given in Fig. VI-37 and Table VII-40, respectively. The objective of this subroutine is to generate in S the description of the free-free stiffness matrix, in overall coordinates, from the description in local coordinates in S, and the directions cosines of local axes in DIR(3,3). The subroutine assumes that S is an $IDS \times IDS$ matrix. By calling subroutine TRAN, IDS times, subroutine STRA first obtains and places the description of each of the IDS vectors of S, in overall coordinates, in the same S locations. Then it generates in S the transpose of $IDS \times IDS$ free-free stiffness matrix. Finally, by calling subroutine TRAN, again IDS times, subroutine STRS obtains and

places the description of each of the IDS vectors of the transposed matrix, in overall coordinates, in the same S locations. The final matrix is the description of the free-free stiffness matrix in the overall coordinate system. There is no error return in the subroutine, and all arguments are implicit.

26. Subroutine TICK. Subroutine TICK is called by the main program of Link 2. It is identical with subroutine TICK of Link 1. For further information, see Sect. II-B-13. The source program listing of this program is given in Table VII-41.

27. Subroutine TOPO. Subroutine TOPO is called by the main program of Link 2. The flowchart and the source program listing of TOPO are given in Fig. VI-38 and Table VII-42, respectively. The objective of this subroutine is to extract and analyze the descriptive words of the element being currently processed by the main program of Link 2. The subroutine is identical with subroutine TOPO of Link 1 up to the statement whose number is 1450 (see Fig. VI-38). As a result of the analysis of the descriptive words, the vertex labels and the property type numbers of the element are obtained in N block and in locations IELT, IMET, JPRS, ITIC, ITEM, JSDY, JSDZ, JMMX, JMMY, JMMZ, JMFI, JARE, respectively. In case of error, the subroutine returns control to the calling program.

28. Subroutine TRAN. Subroutine TRAN is called by subroutines S03, S04, S11, S13, and STRA. The flowchart and the source program listing of TRAN are given in Fig. VI-39 and Table VII-43, respectively. The subroutine has two explicit arguments. The objective of this subroutine is to generate the description of a vector of order $(IGEM + 1) * IMS * 3$ in the overall coordinates from the description of the vector in the local coordinates,

and DIR(3,3) (the directions cosines of local axes). The description of the vector in the local coordinate system is in the array indicated by the first argument, just after the entry indicated by the second argument. The subroutine first computes the description of the vector in the overall system in DUM block, and then carries it on the local description. There is no error return in the subroutine.

29. Subroutine TRIM. Subroutine TRIM is called by subroutines S05, S07, and S15. The flowchart and the source program listing of TRIM are given in Fig. VI-40 and Table VII-44, respectively. The objective of this subroutine is to obtain in blocks EM, EN, and EQ the matrices [M], [N], and [L] of Ref. 2 from the information in XD and YD. There is no error return in the subroutine.

30. Subroutine TRM. Subroutine TRM is called by subroutines S05, S07, S09, S15, S17, and S18. The flowchart and the source program listing of TRM are given in Fig. VI-41 and Table VII-45, respectively. The objective of the subroutine is to perform triple matrix products of the type $[B]^T[A][B]$ or $[C]^T[A][B]$ where [A] is always a symmetric matrix of order 3 or less, and [B] and [C] matrices of order (3×4) or less. The subroutine has five arguments. If the last argument is negative, $[C]^T[A][B]$ is performed; if the last argument is positive, $[B]^T[A][B]$ is performed. The order of the symmetric matrix [A] is given by the fourth argument. The absolute value of the last argument is the column order of [C] or [B]. The matrices [A], [B], and [C] are indicated by the first, second, and third arguments, respectively. The subroutine returns control to the calling program by placing the triple product into the array indicated by the third argument. There is no error return in the subroutine.

IV. Main Program and Subroutines of Link 3

A. Main Program of Link 3

The flowchart and the source program listing of the main program of Link 3 are given in Fig. VI-42 and Table VII-46, respectively. The logical function of the program may be summarized as follows:

- (1) The program generates and stores the upper decomposed stiffness matrix in the IST-pointer-related vector, and the unknown deflections in the IDEF-pointer-related vector.
- (2) Possibly destroying some portions of the decomposed stiffness matrix, the program generates in BB array the complete list of nodal deflections, and carries them onto the IDEF-pointer-related vector.
- (3) If execution of the stress link is requested, i.e., if $INX = 4$, the program computes into the IST-pointer-related vector the forces acting on mesh points (see Output Item 20, Sect. VI-D, Vol. I).
- (4) If $INX = 4$, the program generates in the IST-pointer-related vector the list of labels of the elements meeting at the mesh points, immediately after the residual forces computed in (3), and saves this list on tape ITAS for use in Link 4.

- (5) Depending upon the values of INX and $ITAS$, the main program transfers the control either to Link 4 or to Link 1, as the logically last operation.

In carrying out function (1), the program calls subroutine VELAS, which requires as arguments the number of equations in the system, the pointer of the list of pointers of the diagonal elements of the coefficient matrix, the pointer of the coefficient matrix, and the pointer of the right-hand-side vector. The successful solution of linear equations is indicated by the zero content of the second argument. Function (2) is carried out with the help of the information in IBO-, IBB- and IIC-pointer-related arrays and within the framework of Table III-1, Vol. I. The program produces Output Item 19 from BB block, and calls subroutine PUNC for other modes of output (see Sect. V-F, Vol. I). Then, the information in BB block is carried out to the IDEF-pointer-related vector for use in Link 4. To carry out function (3), the program calls subroutine RESI, and to produce Output Item 20, it calls subroutine RESW. Function (4) is carried out by means of subroutine ELST. The main program, in measuring the elapsed time in executing Link 3, and solving the linear equations, calls subroutine TICK. Output Items 18, 19, and 21 are directly produced by the main program.

B. Subroutines of Link 3

1. *Subroutine ELST.* Subroutine ELST is called by the main program of Link 3. The flowchart and the source program listing of ELST are given in Fig. VI-43 and Table VII-47, respectively. The function of the subroutine is to generate, for each node, information listing the labels of the non-one-dimensional elements meeting at a node. This information is listed as a one-dimensional array starting immediately after the residual forces produced by subroutine RESI (between points E and E' in Fig. III-1, Vol. II, basic). For this purpose, 13 words are assigned for every mesh point. The first word contains the number of non-one-dimensional elements meeting at the mesh point, and the remaining words the labels of these elements. Whenever there are more than 12 non-one-dimensional elements meeting at the mesh point, subroutine ELST returns control to the calling program by setting ITAS to zero, thus preventing the execution of Link 4 even if $INX = 4$. When the number of non-one-dimensional elements meeting at a mesh point and their labels are obtained successfully, the subroutine generates one logical record on tape ITAS for each mesh point to contain such information, and thus releases the corresponding core area. These records are listed after the elemental matrices, and are ordered with the labels of the mesh points. The subroutine also counts the one-dimensional elements and saves the total in COMMON location IONE. If a mesh point does not have any non-one-dimensional elements, the respective record in tape ITAS contains the label of this mesh point and two negative integers. The subroutine, before returning control to the calling program, positions the tape to the nodal set information of the first mesh point by means of IN number of BACKSPACE commands.

2. *Subroutine PUNC.* Subroutine PUNC is called by the main program of Link 3. The standard ELAS contains only the dummy version of this subroutine, as shown in Table VII-48. If the user wishes to produce Output Item 19 in different media and format, he may do so by writing his version of this subroutine, as explained in Sect. V-F, Vol. I. The logical function of this subroutine is to copy deflections from BB block to the desired output media with the desired format.

3. *Subroutine RESI.* Subroutine RESI is called by the main program of Link 3. The flowchart and the source program listing of RESI are given in Fig. VI-44 and Table VII-49, respectively. The function of this subroutine is to generate the forces acting at the mesh points,

in the overall coordinate system, in the IST-pointer-related vector. Such forces consist of nonthermal element forces less the elastic forces (element stiffness matrix times the vertex deflections). In the absence of thermal loading, these forces represent the round-off errors at a nonboundary point, and the reaction force at a boundary point where the deflections are prescribed, or prescribed concentrated loads where the deflections are not prescribed. In this context, these forces are labelled as the residual forces. The residual forces are used in Link 4 to compute average stresses at the boundary points. To compute the residual forces, subroutine RESI clears the first IND words of the IST-pointer-related vector, and considers that the residual forces are to be listed as in Table III-3 with increasing mesh-point labels and conforming with Table III-1, Vol. I (i.e., the residual forces of the first mesh point are to be listed first, the residual forces of the second mesh point are to be listed second, etc.). Since tape ITAS is already positioned by the main program of Link 2 for this purpose, the subroutine reads in sequentially the element matrices (the stiffness matrix and the load vector without thermal load contribution) one at a time, and performs the operation of "element load vector less element stiffness matrix times vertex deflections," and assembles the resulting vector onto the vector of residual forces. In the case of subelements, the scaling factors discussed in Section III-A are properly considered. If an error is detected during the tape handling, the subroutine sets the contents of ITAS to zero and returns control to the calling program, thus preventing the execution of Link 4 even if $INX = 4$. The residual forces are kept intact in the core until the execution of Link 4 is completed.

4. *Subroutine RESW.* Subroutine RESW is called by the main program of Link 3, if $INP \neq 0$. The flowchart and the source program listing of RESW are given in Fig. VI-45 and Table VII-50, respectively. The purpose of this subroutine is to produce Output Item 20. This is achieved by looping on mesh points. At every loop cycle, the subroutine first abstracts the residual force of the respective mesh point from the list of residual forces in the IST-pointer-related vector, and arranges the components to a complete six-component vector in accordance with Table III-1, Vol. I, and finally prints a line for these components. The ordering of the residual forces is explained in Table III-3, Vol. II (basic). In arranging the components of a mesh point, the subroutine uses the constant IELT, which is generated by the main program of Link 3 for Output Item 19 (the ordering of Output Items 19 and 20 is similar). There is no error return in the subroutine.

5. *Subroutine TICK.* Subroutine TICK is called by the main program of Link 3. It is identical with subroutine TICK of Link 1. For further information see Section II-B-13. The source program listing of this program is given in Table VII-51.

6. *Subroutine VELAS.* Subroutine VELAS is called by the main program of Link 3. The flowchart and the source program listing of VELAS are given in Fig. VI-46 and Table VII-52, respectively. The purpose of this subroutine is to solve linear equations with positive-definite, symmetric, and variable-banded coefficient matrices. The subroutine has four explicit and no implicit arguments. The first argument is the order of the linear system (i.e., the number of equations); at entry to the program, the second argument contains the pointer of the vector listing the pointers of the diagonal elements of the coefficient matrix; the third argument is the pointer of the coefficient matrix; the fourth argument is the pointer of the right-hand-side vector. Subroutine VELAS assumes that the arrays related with the last three arguments are all in COMMON. By applying the Cholesky scheme, the subroutine first obtains the decomposed matrix (referred

to in Fig. VI-46 as $U(I,J)$) on the coefficient matrix (referred to in Fig. VI-46 as $A(I,J)$); then by a forward sweep it obtains the auxiliary solution (referred to in Fig. VI-46 as $Y(I)$) in the right-hand-side vector (referred to in Fig. VI-46 as $B(I)$); and finally, by a backward sweep, it obtains the solution vector (referred to in Fig. VI-46 as $X(I)$) in the right-hand-side vector (referred to in Fig. VI-46 as $B(I)$). During decomposition, if the quantity under the radical sign is nonpositive, the subroutine returns control to the calling program by setting the location of the associated diagonal element relative to the beginning of the coefficient matrix in the second argument. If the first argument is nonpositive, the return is made by setting the second argument to -1 . The subroutine assumes that a quantity is positive if it is larger than the 10^{-10} multiple of the smallest diagonal element (in magnitude) of the coefficient matrix. During decomposition, the subroutine uses NN locations immediately after the array related with the third argument to store the number of matrix elements in the columns of coefficient matrix within the shaded area shown in Fig. II-1, Vol. I. Here NN is the order of the system. The subroutine assumes that the coefficient matrix is arranged as described in Table III-3 under IST-pointer-related vector.

V. Main Program and Subroutines of Link 4

A. Main Program of Link 4

The flowchart and the source program listing of the main program of Link 4 are given in Fig. VI-47 and Table VII-53, respectively. The logical functions of the program may be summarized as follows:

- (1) For line elements, by means of subroutine DIMI, the program computes stress resultants at the end points of the elements and prints out Output Item 24.
- (2) For non-one-dimensional elements, it computes, with the method described in Sect. II, Vol. II (basic), the stresses at the mesh points and prints out Output Item 22, by means of Link 4 programs other than DIMI.
- (3) It transfers control to the main program of Link 1 as the logically last operation.

By checking the contents of IONE (see Sect. IV-B-1), the main program performs either function (1) or (2) or both.

If function (2) is to be performed, the program checks whether the starting point of vector FF (see Tables III-4

and III-5, Vol. II, basic) and point E (see Fig. III-1, Vol. II, basic) are overlapping. If overlapping occurs, Error Message 23 is produced and no stress computation is done. Otherwise the main program loops on mesh points with the objective of computing stresses at a mesh point for each material group and for each class group (see Output Item 22 in Sect. VI-E, Vol. I). When the loop on mesh points is satisfied, if there are line elements in the structure, the main program calls subroutine DIMI for function (1). During the performance of function (2), the program calls subroutines ABEQ, BOFI, CAS4, DINA, FINDQ, FINDX, GENE, INLZ, LEST, MDIN, META, SAME, SETA, and STRS. The program calls subroutine TICK to measure the time spent in Link 4. The main program is directly responsible for the production of Output Items 22 and 25.

B. Subroutines of Link 4

1. Subroutine ABEQ. Subroutine ABEQ is called by the main program of Link 4, if the current mesh point ICN is on the boundary of a two- or three-dimensional continuum. The flowchart and the source program listing of ABEQ are given in Fig. VI-48 and Table VII-54, respectively. The objective of this subroutine is to generate

the first IEQ rows of the augmented matrix A (see Table III-5, Vol. II, basic), the corresponding weights in vector IWG, and the actual values of the prescribed stresses in vector SR. The first IEQ rows of the augmented matrix A correspond to the IEQ number of stress boundary conditions at the boundary point ICN. These equations are generated as discussed in Sect. II, Vol. II (basic). The subroutine first copies the residual vector (see Sect. IV-B-3) of mesh point ICN into RES vector. Then, depending upon the class type of current ICth group, it computes certain parameters listed in Table V-1. The program carries two right-hand-side vectors for class 6 and 8 structures in the strain deflection equations, because of the symmetry in strains and curvature changes (see Ref. 2). This is very useful in minimizing the column order of the strain deflection equations.

In Table V-1, the parameters used by the subroutine are defined. The meanings of these parameters are as follows: IEQ is the number of the stress boundary equations (note that the number of stress boundary conditions is the product of IEQ*IRIG); IRIG is the number of right-hand sides in the strain deflection equations; ICOL is the column order of the coefficient matrix of strain deflection equations; vector N lists the component number (see Table VI-6, Vol. I) of the prescribed stress (as stated in Sect. VI-E, Vol. I, the local coordinate axes on a boundary point are such that the first axis is the outer normal of the boundary surface, and the second and the third axes are tangential to the boundary surface; the stress boundary conditions are expressed in the local coordinate system); IREB and IREN are the entry numbers of the beginning and the end, respectively, of the portion of vector RES to be used in generating the prescribed stress values for the right-hand sides of the stress boundary condition equations. Because of the ordering of the residual forces (first, force components, and then moment components) for the second right-hand side, the program takes IREB and IREN as IREB + 1 and IDEG, respectively. The first and second columns of matrix NEK list the labels of the local axes to be used in projecting the portion of vector RES for obtaining the prescribed stress components, for the first and second right-hand sides, respectively. Matrix REK, like matrix NEK, indicates whether any sign change is to be performed for the correct sign of the prescribed stress. Scale factors CR and CL are used in scaling a stress boundary condition equation to achieve similar orders of magnitude in the whole set strain deflection equations; CR is for the right-hand side, CL for the left-hand side. The basic format of a stress boundary condition equation is shown in Table V-1. To obtain the components of the

best-fit strain tensor from the strain deflection equations in a manner that satisfies the stress boundary conditions more correctly than the remaining equations, the subroutine assigns the stress boundary equations a weight of 100 in the corresponding entries of vector IWG. The subroutine also updates the equation count ICON, and saves the prescribed stress values in vector SR in the order shown in Table V-2. There is no error return in the subroutine.

2. Subroutine AGEL. Subroutine AGEL is called by subroutine DINA if the IPIR field of the control card (see Table IV-2, Vol. I) is 2. The standard ELAS contains only the dummy version of this subroutine, as shown in Table VII-55. If the user wishes to prescribe local coordinate systems at the mesh points of shell structures, he may do so by writing his version of this subroutine, as explained in Sect. V-E, Vol. I. The logical function of this subroutine is to define matrix DIN for the direction cosines of the local axes of mesh point ICN.

3. Subroutine BEST. Subroutine BEST is called by subroutines BOFI and QUAD. The flowchart and the source program listing of BEST are given in Fig. VI-49 and Table VII-56, respectively. The objective of this subroutine is to obtain the direction cosines of the normal of the best-fit plane (in the least squares sense) related with the mesh points listed in the array referenced by the second argument and mesh point ICN. The number of mesh points listed in the second argument is given by the third argument. The subroutine places the direction cosines of the normal into the array indicated by the first argument. One condition equation is generated for each mesh point listed in the array referenced by the second argument to express the situation for that point to be in the sought-for plane. The mesh-point coordinates are obtained by means of subroutine FINDX. The equation of the plane is arbitrarily expressed in a coordinate system that is parallel to the overall, but located at a point with coordinates 1.15, 1.16, and 1.17 less than those of mesh point ICN. Once the condition equations are established, the coefficients of variables (i.e., quantities proportional to the direction cosines of the normal) are solved by least squares, by first premultiplying both sides of the condition equations by the transpose of the coefficient matrix, and then solving the resulting equations by means of subroutine INV. If the inversion fails in subroutine INV, subroutine BEST attempts to approximate the direction cosines of the normal, as explained in block 45 of Fig. VI-49. This latter process necessitates a vector product, which is carried out by means of subroutine VECT.

Table V-1. Values of important parameters used in subroutine ABEQ for various classes (see Sect. V-B-1 for discussion)

Class No.	IEQ	N(1)	N(2)	N(3)	IREB	IREN	IRIG, (NES(2))	NEK(1,1)	NEK(1,2)	REK(1,1)	REK(1,2)	ICOL, (NES(1))	CR	CL	IDR, (NES(3))
1	2	1	3		1	2	1	$\begin{Bmatrix} 1 \\ 2 \end{Bmatrix}$		$\begin{Bmatrix} 1. \\ 1. \end{Bmatrix}$		3	$\frac{ARE}{TE*DD_{1,1}}$	$\frac{ARE^2}{DD_{1,1}}$	0
2	2	1	3		2	3	1	$\begin{Bmatrix} 2 \\ 1 \end{Bmatrix}$		$\begin{Bmatrix} 1. \\ -1. \end{Bmatrix}$		3	$\frac{-TE^2*ARE}{12*DD_{1,1}}$	$\frac{ARE^2}{DD_{1,1}}$	1
3	2	1	3		1	2	1	$\begin{Bmatrix} 1 \\ 2 \end{Bmatrix}$		$\begin{Bmatrix} 1. \\ 1. \end{Bmatrix}$		3	$\frac{ARE}{XX*DD_{1,1}}$	$\frac{ARE^2}{DD_{1,1}}$	0
4	3	1	3	5	1	3	1	$\begin{Bmatrix} 1 \\ 2 \\ 3 \end{Bmatrix}$		$\begin{Bmatrix} 1. \\ 1. \\ 1. \end{Bmatrix}$		6	$\frac{1}{DD_{1,1}}$	$\frac{ARE}{DD_{1,1}}$	0
5	1	1			1	2	1	$\begin{Bmatrix} 1 \\ 2 \end{Bmatrix}$		$\begin{Bmatrix} 1. \\ 1. \end{Bmatrix}$		1	$\frac{ARE^2}{XX*DD_{1,1}}$	$\frac{ARE^2}{DD_{1,1}}$	0
6	1	1			1	2	2	$\begin{Bmatrix} 1 \\ 2 \end{Bmatrix}$	{2}	$\begin{Bmatrix} 1. \\ 1. \end{Bmatrix}$	{1.}	3	$\frac{ARE^2}{XX*DD_{1,1}}$	$\frac{ARE^2}{DD_{1,1}}$	0
7	2	1	3		1	3	1	$\begin{Bmatrix} 1 \\ 2 \end{Bmatrix}$		$\begin{Bmatrix} 1. \\ 1. \end{Bmatrix}$		3	$\frac{ARE}{DD_{1,1}}$	$\frac{ARE^2}{DD_{1,1}}$	0
8	2	1	3		1	3	2	$\begin{Bmatrix} 1 \\ 2 \end{Bmatrix}$	$\begin{Bmatrix} 2 \\ 1 \end{Bmatrix}$	$\begin{Bmatrix} 1. \\ 1. \end{Bmatrix}$	$\begin{Bmatrix} 1. \\ -1. \end{Bmatrix}$	3	$\frac{ARE}{DD_{1,1}}$	$\frac{ARE^2}{DD_{1,1}}$	0

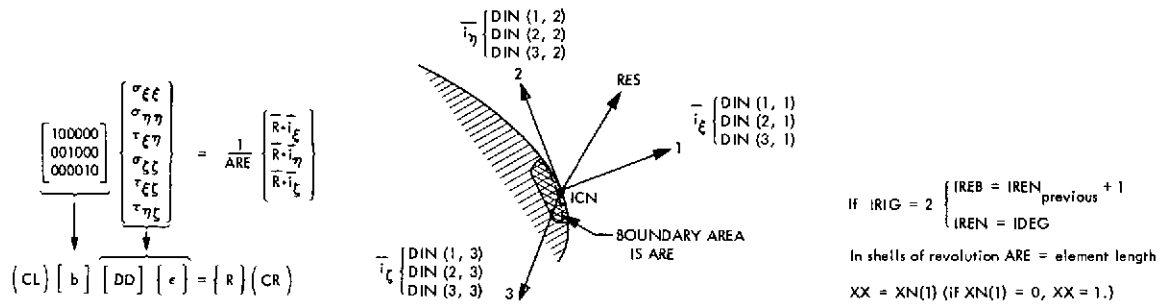


Table V-2. Arrangement of prescribed boundary forces by subroutine ABEQ in SR vector for the eight class^a types

Class	1	2	3	4	5	6	7	8
SR(1)	σ_{ξ}	M_{ξ}	σ_{ξ}	σ_{ξ}	N_{ξ}	N_{ξ}	N_{ξ}	N_{ξ}
SR(2)	$\tau_{\xi\eta}$	$M_{\xi\eta}$	$\tau_{\xi\eta}$	$\tau_{\xi\eta}$		M_{ξ}	$N_{\xi\eta}$	$N_{\xi\eta}$
SR(3)				$\tau_{\xi\xi}$				M_{ξ}
SR(4)								$M_{\xi\eta}$

^aSee Table VI-6, Vol. I.

Before returning control to the calling program, subroutine BEST calls subroutine UNIT to normalize the vector in the first argument. There is no error return in the subroutine.

4. Subroutine BOFI. Subroutine BOFI is called by the main program of Link 4. The flowchart and the source program of BOFI are given in Fig. VI-50 and Table VII-57, respectively. The objective of this subroutine is to determine from the element set information in NEL whether mesh point ICN is on the boundary. If mesh point ICN is not on the boundary, the subroutine returns control to the calling program without any action. However, if mesh point ICN is found to be on the boundary, the subroutine sets $INBON = 1$ and $AST = IH^*$, and computes the direction cosines of the outer normal of the boundary at mesh point ICN into vector BIR. To obtain the direction cosines, subroutine BOFI calls subroutine INER to obtain a general vector heading towards the structure, and calls subroutine BEST to obtain the direction cosines of the best-fit plane to boundary nodes neighboring mesh point ICN. After re-directing the normal of the plane with the general vector heading towards the structure, the normal of the best-fit plane is assumed to be the outer normal of the structure at the boundary node. If any trouble arises in finding the outer normal, subroutine BOFI will assume that mesh point ICN is an internal one. The subroutine also generates in ARE an average boundary surface area if mesh point ICN is on the boundary. The number of repeated interelement boundaries in the element set and the number of unrepeated element boundaries are used in determining whether mesh point ICN is on the boundary. In performing its function, BOFI also calls subroutines FINDX, SCAL, and UNIT. There is no error return in the subroutine.

5. Subroutine CAS4. Subroutine CAS4 is called by the main program of Link 4. The standard ELAS contains only the dummy version of this subroutine, as shown in Table VII-58. If Output Item 23 is to be produced selectively, this subroutine should be rewritten by the user, as explained in Sect. V-H, Vol. I. The logical function of this subroutine is to change the value of INP as desired in the DO loop on mesh points in the main program of Link 4.

6. Subroutine CODI. Subroutine CODI is called by subroutine DIMI. It is identical with subroutine CODI of Link 2. For further information, see Section III-B-4.

The source program listing of this subroutine is given in Table VII-59.

7. Subroutine DIMI. Subroutine DIMI is called by the main program of Link 4, if IONE is positive. The flowchart and the source program listing of DIMI are given in Fig. VI-51 and Table VII-60, respectively. The objective of this subroutine is to obtain the end forces of the one-dimensional elements in the local coordinate system and to produce Output Item 24. For this purpose, the subroutine rewinds tape ITAS and processes the mesh elements one at a time. If a one-dimensional element is encountered, by means of subroutines CODI, STRA and TRAN, the element stiffness matrix, the element load vector, and the deflection vector of the vertices are first expressed in local coordinates of the element (see Fig. VI-1, Vol. I), and then the end forces are expressed as the product of the element stiffness matrix and the vector of vertex deflections less the element load vector. If an error is encountered during the tape handling, the subroutine sets $IERR = 1$, $ICN =$ the element number, and the explicit argument of the subroutine with the record number as read from the tape, and returns control to the calling program.

8. Subroutine DINA. Subroutine DINA is called by the main program of Link 4, if the current class group is of shell type (i.e., ICAS is equal to or larger than 5). The flowchart and the source program listing of DINA are given in Fig. VI-52 and Table VII-61, respectively. The objective of this subroutine is to determine the direction cosines of the axes in which the stresses are to be expressed in DIN and find the value of ANGLE associated with these axes. If the IPIR value of the control card (see Table IV-2, Vol. I) is larger than 1, subroutine DINA calls subroutine AGEL to do the job. Otherwise, subroutine DINA calls either subroutine QUAD or subroutine REVO, depending upon whether the shell is general or axisymmetrical type, respectively, to perform its function. There is no error return in the subroutine.

9. Subroutine EPAN. Subroutine EPAN is called by subroutine QUAD, if there are less than eight neighboring mesh points in the element set of mesh point ICN (subroutine QUAD is called only for the general shell case). The flowchart and the source program listing of EPAN are given in Fig. VI-53 and Table VII-62, respectively. The objective of this subroutine is to expand the vector containing the labels of the mesh points in the immediate neighborhood of the current mesh point ICN by the element set information of the mesh points in the immediate neighborhood of mesh point ICN. When

control is transferred to the subroutine, vector NSET contains the labels of the immediate neighbors of mesh point ICN, and NB contains the order of this vector. By minimum tape handling, the subroutine obtains the element set information of each of these immediate neighbors from tape ITAS and expands vector NSET with the mesh-point labels of the neighbors of neighbors of mesh point ICN and updates NB correspondingly. Before it returns control to the calling program, the subroutine repositions tape ITAS to the position at the time of entry. There is no error return in the subroutine.

10. Subroutine FINDQ. Subroutine FINDQ is called by the main program of Link 4 and by subroutine SETA. The flowchart and the source program listing of FINDQ are given in Fig. VI-54 and Table VII-63, respectively. The function of this subroutine is to compute, in overall coordinates, the deflection components of the mesh point indicated by the first argument into the vector indicated by the second argument. There is no error return in this subroutine.

11. Subroutine FINDX. Subroutine FINDX is called by the main program of Link 4 and subroutines BEST, BOFI, INER, INLZ, QUAD, REVO, and SETA. The flowchart and the source program listing of FINDX are given in Fig. VI-55 and Table VII-64, respectively. The function of this subroutine is to compute the overall coordinates of the mesh point indicated by the first argument into the vector indicated by the second argument. There is no error return in the subroutine.

12. Subroutine GENE. Subroutine GENE is called by the main program of Link 4. The flowchart and the source program listing of GENE are given in Fig. VI-56 and Table VII-65, respectively. The objective of this subroutine is to generate the columns of matrix NEL, other than the first (the first column of NEL is already generated by the main program of Link 4), the corresponding matrix MAC, vector ICLAS, and variable IMEL. The format of NEL and MAC matrices is given in Table VI-7, Vol. I. Since the rows of matrix NEL contain information about the elements meeting at mesh point ICN, subroutine GENE calls subroutine TOPO to extract such information from COMMON. Matrix MAC is generated by the information in completed matrix NEL. Vector ICLAS and variable IMEL are generated as a by-product of the generation of matrix MAC. Error conditions that may be encountered during the generation of matrix MAC may cause the production of Error Messages 18, 19, and 20. There is no error return in the subroutine.

13. Subroutine INER. Subroutine INER is called by subroutine BOFI, if mesh point ICN is on the boundary. The flowchart and the source program listing of INER are given in Fig. VI-57 and Table VII-66, respectively. The objective of this subroutine is to generate the components of a vector heading towards the structure at mesh point ICN, and store them in the vector indicated by the argument. At the time of entry to the subroutine, vector NSET contains the labels of the neighboring mesh point. The subroutine simply adds the vectors, joining mesh point ICN to its neighbors to obtain the required vector. The mesh-point coordinates are obtained by means of subroutine FINDX. There is no error return in the subroutine.

14. Subroutine INLZ. Subroutine INLZ is called by the main program of Link 4. The flowchart and the source program listing of INLZ are given in Fig. VI-58 and Table VII-67, respectively. The function of this subroutine is to initialize the values of IROT, BST, DIN, W, TE, DT, DG, ICOL, IRIG, IDR, ANGLE, ICON, IERR, and BAS quantities for the stress computation corresponding to the current values of ICN/IM/IC (see Table III-4). In initializing these values, the subroutine assumes that the mesh point is an internal one and the local coordinate system is parallel to the overall coordinate system. Values of TE, DT, and DG are obtained as the arithmetical average of those of the related mesh elements. Values of IRIG, ICOL, and IDR are obtained, depending upon the class type number of the current mesh-element group (see Tables III-4, Vol. II, basic, and V-1). To perform its functions, INLZ calls subroutines FINDX and UNIT. There is no error return in the subroutine.

15. Subroutine INV. Subroutine INV is called by subroutines BEST, LEST, QUAD, and REVO of Link 4. The flowchart and the source program listing of INV are given in Fig. VI-59 and Table VII-68, respectively. The purpose of the subroutine is to solve a set of linear equations by Gauss elimination. The coefficient matrix is referred by the first argument, and the right-hand-side vectors are referred by the third argument. The second argument is the order of the system, and the fourth argument is the number of right-hand-side vectors. When the subroutine returns control to the calling program, the fifth argument contains the value of the determinant of the coefficient matrix, the first argument contains the inverse of the coefficient matrix, and the third argument contains the solution vector if the fourth argument and the determinant are nonzero. This subroutine is borrowed from

the IBM 1620 library of the Jet Propulsion Laboratory as of September 1966.

16. Subroutine LEST. Subroutine LEST is called by the main program of Link 4. The flowchart and the source program listing of LEST are given in Fig. VI-60 and Table VII-69, respectively. The objective of this subroutine is to obtain the components of the best-fit strains from the strain deflection equations. At the time of entry to the subroutine, matrix A contains the augmented matrix of the strain deflection equations, ICON contains the number of equations, JMM the number of columns in the coefficient matrix, JMR the number of right-hand sides (therefore $JMX = JMM + JMR$ is the column order of the augmented matrix), and IWC the weight assigned to each of the strain deflection equations. Considering the multiplicity of the equations as given in vector IWC, the subroutine premultiplies both sides of the strain deflection equations by the transpose of the coefficient matrix, then calls subroutine INV to obtain the best-fit strain components, and reorders the components in matrix C and redefines JMM and JMR such that the first column contains the usual strain components and the second column contains the angular strain (curvature change) components. For axisymmetrical structures, cases in which mesh point ICN is on the axis of revolution are handled separately in the subroutine by considering the thermal strains, if there are any. For shells of revolution, if mesh point ICN is on the axis, vectors DDIS, DROT, and DCOR contain the relative displacement, relative rotation, and relative coordinate of the opposite end of the nodal line with respect to mesh point ICN. These vectors are expressed in the local coordinate system of mesh point ICN. If the inversion performed by subroutine INV is not successful (indicated by zero determinant), subroutine LEST sets IERR = 1 and returns control to the calling program. If INP is 2, the best-fit strain components are printed out as part of Output Item 23.

17. Subroutine MDIN. Subroutine MDIN is called by the main program of Link 4, if mesh point ICN is on the boundary. The flowchart and the source program listing of MDIN are given in Fig. VI-61 and Table VII-70, respectively. The objective of this subroutine is to obtain the direction cosines of the local coordinate axes at mesh point ICN with the specifications described in Sect. VI-E, Volume I; i.e., the first local axis is always normal to the boundary. At the time of entry to the subroutine, matrix DIN contains the direction cosines of the local axes of mesh point ICN, assuming that the mesh point is not on

boundary, and vector BIR contains the direction cosines of the outer unit normal vector of the boundary surface at mesh point ICN. In reorienting the local axes, subroutine MDIN calls subroutines UNIT and VECT. There is no error return in the subroutine.

18. Subroutine META. Subroutine META is called by the main program of Link 4. The flowchart and the source program listing of META are given in Fig. VI-62 and Table VII-71, respectively. The objective of this subroutine is to obtain the material matrix (see Fig. III-2b, Vol. I) and thermal expansion coefficients of the current element group associated with ICN/IM/IC, in DD and AL1, AL2, AL3, respectively, in the local coordinate system of mesh point ICN. If the material axes of the current group are not parallel to the local axes of mesh point ICN, subroutine META calls subroutine ROTA to express the material matrix in the local coordinate system. Before returning control to the calling program, subroutine META rearranges the rows and the columns of DD such that the material matrix is arranged with the order of 11, 22, 12, 33, 13, 23. There is no error return in the subroutine.

19. Subroutine QUAD. Subroutine QUAD is called by subroutine DINA if a general shell structure is under question. The flowchart and the source program listing of QUAD are given in Fig. VI-63 and Table VII-72, respectively. The objective of the subroutine is to generate in DIN the direction cosines of the local axes of mesh point ICN of the shell structure, and find the value of ANGLE. The subroutine first obtains in vector MSET the labels of the nodes appearing in the mesh elements corresponding to the current values of ICN/IM/IC. Then it obtains in ZD a vector in the general direction of shell normal (block 10* of Fig. VI-63). After this, the subroutine extracts from vector MSET a list of unrepeated labels in vector NSET. The order of NSET is in NB. If NB is not smaller than 9, a best-fit quadratic surface passing through mesh point ICN and its immediate neighbors may be possible. If NB is smaller than 9, subroutine QUAD calls subroutine EPAN to enlarge vector NSET and NB to include in the list the labels of the immediate neighbors of the mesh points that are already included in vector NSET, without repetition.

Next, by calling subroutine BEST, subroutine QUAD attempts to generate in vector ZTA the direction cosines of the normal of a best-fit plane (in the least squares sense) to the family of mesh points listed in vector NSET. If this fails, vector ZD is taken as vector ZTA. Then,

assuming that the first local axis is in the direction of vector BAS, the subroutine generates the first approximation of matrix DIN (the first, second, and third columns of matrix DIN are referred to as vectors XII, ETA, and ZTA). If NB is not smaller than 9, subroutine QUAD generates in matrix D the condition equations for a quadratic surface passing through the mesh points listed in vector NSET. The condition equations are obtained in the first approximation of the local axes. These equations are next solved by a least squares method with the help of subroutine INV. If the solution is successful, the local normal is taken as the normal direction of this quadratic surface, and matrix DIN is corrected accordingly. With the use of the new matrix DIN, the process of locating a best-fit quadratic surface is repeated to increase the accuracy. If the process of finding a best-fit quadratic surface fails, the subroutine prints out Error Message 21 and returns control to the calling program with the first approximation of matrix DIN. Otherwise, the subroutine examines the value of IPIR. If IPIR is larger than 1, the subroutine rotates the local axes about the normal until the first local axis is in the smaller principal curvature direction of the best-fit quadratic surface. Initially zero value of ANGLE is changed to the degrees value of the angle between vector BAS and the final orientation of the first local axis. In performing its functions, QUAD also calls subroutines FINDX, SCAL, UNIT, and VECT. There is no error return in the subroutine.

20. Subroutine REVO. Subroutine REVO is called by subroutine DINA if a shell of revolution is under question. The flowchart and the source program listing of REVO are given in Fig. VI-64 and Table VII-73, respectively. The objective of this subroutine is to generate in matrix DIN the direction cosines of the local axes by fitting, if possible, a fourth-order polynomial to the meridional curve. The normal of this curve is taken as the direction for the third local axis. For this purpose, the subroutine first finds the labels of the first four immediate neighbors of mesh point ICN and places them in vector NSET. Vector NSET also contains the label of ICN. The order of NSET is NB. If for some reason NB is less than 5, the subroutine fits a polynomial curve of degree NB-1 to the meridional curve. The conditions for the mesh points listed in vector NSET on the polynomial curve are generated on matrix B and vector C. The unknown coefficients of the polynomial are obtained from these conditions by means of subroutine INV. If the system is singular, and a polynomial curve fit is not possible, the program will use the line segment joining the mesh points confining mesh point ICN as the fitted curve and

cause the production of Error Message 22. The normal direction of the fitted curve is taken as the third local axis. The overall Z axis is taken as the negative of the second local axis. The first local axis is tangent to the fitted curve and heads towards the increasing arc distance on the meridian (the meridian curve is assumed directed). The first, second, and third columns of matrix DIN are named as vectors XII, ETA, and ZTA, and contain the direction cosines of the first, second, and third local axes. In obtaining the direction cosines of the local axes, subroutine REVO calls subroutines FINDX, SCAL, UNIT, and VECT.

21. Subroutine ROTA. Subroutine ROTA is called by subroutine META if the local axes are not parallel to the material axes. The flowchart and the source program listing of ROTA are given in Fig. VI-65 and Table VII-74, respectively. The objective of this subroutine is to express the material matrix DD in the local coordinate system defined by matrix DIN (see Table III-5, Vol. II, basic). There is no error return in the subroutine. In obtaining various unit vectors, subroutine ROTA calls subroutines SCAL, UNIT, and VECT.

22. Subroutine SAME. Subroutine SAME is called by the main program of Link 4. The flowchart and the source program listing of SAME are given in Fig. VI-66 and Table VII-75, respectively. The objective of this subroutine is to output stresses for the current ICN/IC/IM group, in the local coordinate system if mesh point ICN is a boundary point, and the group is not of shell type. Therefore, this subroutine produces the last portion of Output Item 22. There is no error return in the subroutine.

23. Function SCAL. Function SCAL is called by subroutines BOFI, QUAD, REVO, ROTA, and SETA of Link 4. The flowchart and the source program listing of SCAL are given in Fig. VI-67 and Table VII-76, respectively. The objective of the program is to return to the calling program the scalar product of the vectors referred by the first and second arguments. There is no error return.

24. Subroutine SETA. Subroutine SETA is called by the main program of Link 4 once for every mesh element in the group of current ICN/IM/IC. The flowchart and the source program listing of SETA are given in Fig. VI-68 and Table VII-77, respectively. The objective of the program is to add one additional row to the augmented matrix of strain deflection equations for each direction joining mesh point ICN to the remaining vertices of the mesh element. The subroutine assigns a

weight of 10 or 1 to the equation of a direction, depending upon whether the vertex is on the boundary or not. The weights are recorded in vector IWG. The subroutine generates the row of the augmented matrix as described in Sect. II, Vol. II (basic), by considering thermal strains. When a row is added to the augmented matrix, row count ICON is also updated. In obtaining the thermal strain per unit temperature in a given direction, subroutine SETA calls subroutine TEMP. In achieving various vector operations, it also calls function SCAL, and subroutines FINDQ, FINDX, UNIT, and VECT of Link 4. There is no error return in the program.

25. Subroutine STRA. Subroutine STRA is called by subroutine DIMI. It is identical with subroutine STRA of Link 2. For further information, see Sect. III-B-25. The source program listing of this subroutine is given in Table VII-78. In performing its function, STRA calls subroutine TRAN.

26. Subroutine STRS. Subroutine STRS is called by the main program of Link 4. The flowchart and the source program listing of STRS are given in Fig. VI-69 and Table VII-79, respectively. The objective of this subroutine is to obtain the components of the best-fit stress tensor for current ICN/IM/IC, and list them in vector SR to comply with Table VI-6, Vol. I. At the time of entry to the subroutine, matrix DD contains the material constants, matrix C contains the components of the best-fit usual and angular strains in the first and second columns, respectively, and SR contains the prescribed stresses in the order shown in Table V-2. The subroutine first generates in vector RED the best-fit stresses, then modifies them with the prescribed stresses in SR, and finally copies the final set into vector SR in the order shown in Table VI-6, Vol. I. There is no error return in the subroutine.

27. Subroutine TEMP. Subroutine TEMP is called by subroutine SETA if temperature loading of an anisotropic material is under question. The flowchart and the source program listing of TEMP are given in Fig. VI-70 and Table VII-80, respectively. The objective of this subroutine is to obtain the lineal strain in the direction given by the unit vector in XF (see the comment in Table VII-80) due to unit temperature increase, and to store this quantity in the explicit argument. To do this, the subroutine uses matrix W generated by subroutine

ROTA and XF generated by subroutine SETA as DCAR. There is no error return in the subroutine.

28. Subroutine TICK. Subroutine TICK is called by the main program of Link 4. It is identical with subroutine TICK of Link 1. For further information, see Sect. II-B-13. The source program listing of this program is given in Table VII-81.

29. Subroutine TOPO. Subroutine TOPO is called by subroutine GENE. It is identical with subroutine TOPO of Link 2. For further information, see Sect. III-B-27. The source program listing of this program is given in Table VII-82.

30. Subroutine TRAN. Subroutine TRAN is called by subroutines DIMI and STRA of Link 4. It is identical with subroutine TRAN of Link 2. For further information, see Sect. III-B-28. The source program listing of the program is given in Table VII-83.

31. Subroutine UNIT. Subroutine UNIT is called by subroutines BEST, BOFI, INLZ, MDIN, QUAD, REVO, ROTA, and SETA of Link 4. The flowchart and the source program listing of UNIT are given in Fig. VI-71 and Table VII-84, respectively. The objective of the subroutine depends upon the contents of the second argument. If the second argument is zero, the subroutine computes the magnitude squared of the vector indicated by the first argument and returns control to the calling program. If the second argument is nonzero, the subroutine replaces the vector in the first argument with a unit vector and the second argument with the magnitude of the original vector. If the second argument, at the beginning, is a positive number, the unit vector is parallel and in the same direction as the original vector. If the second argument, at the beginning, is a negative number, the unit vector is parallel and in the opposite direction of the original vector. There is no error return in the subroutine.

32. Subroutine VECT. Subroutine VECT is called by subroutines BEST, MDIN, QUAD, REVO, ROTA, and SETA of Link 4. The flowchart and the source program listing of VECT are given in Fig. VI-72 and Table VII-85, respectively. The objective of this subroutine is to obtain in the vector indicated by the first argument the cross-product of the vector in the second argument times the vector in the third argument. There is no error return in the subroutine.

VI. Semidetailed Flowcharts

This section contains semidetailed flowcharts of ELAS/Level 3. The flowchart of each program element is treated separately, and given a figure number. The flowcharts are arranged alphabetically by the subroutine names, under the main program of each link. The meanings of the symbols used in the flowcharts may be obtained from the text description of the corresponding subroutine given in the preceding sections and/or Tables III-2 and III-4 of Vol. II (basic). Each flowchart should be considered together with the corresponding source program listing in Sect. VII, and the descriptive paragraph of the earlier sections. The number attached to a block in a flowchart is the number

of the first statement in the source program listing corresponding to this block. If the first statement does not have a statement number, the nearest statement number is used with an asterisk in the block. An asterisk before the number in the block means that the first statement of the block is before the statement indicated by the block number. An asterisk after the number in the block means that the first statement of the block is after the statement indicated by the block number. Multiple asterisks indicate qualitatively the distance between the statement with the number and the first statement of the block in the source program listing.

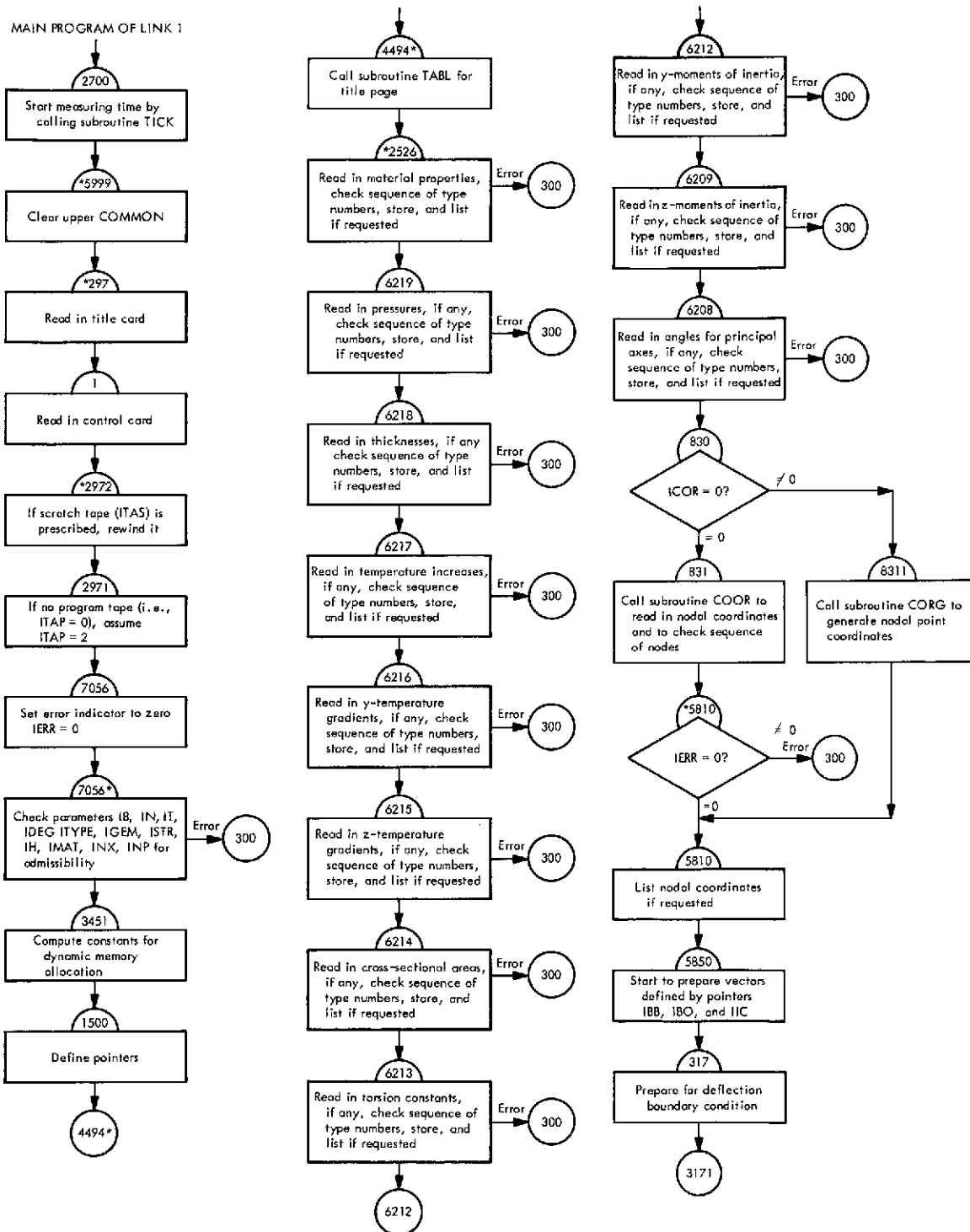


Fig. VI-1. Flowchart of main program of Link 1 (input link)

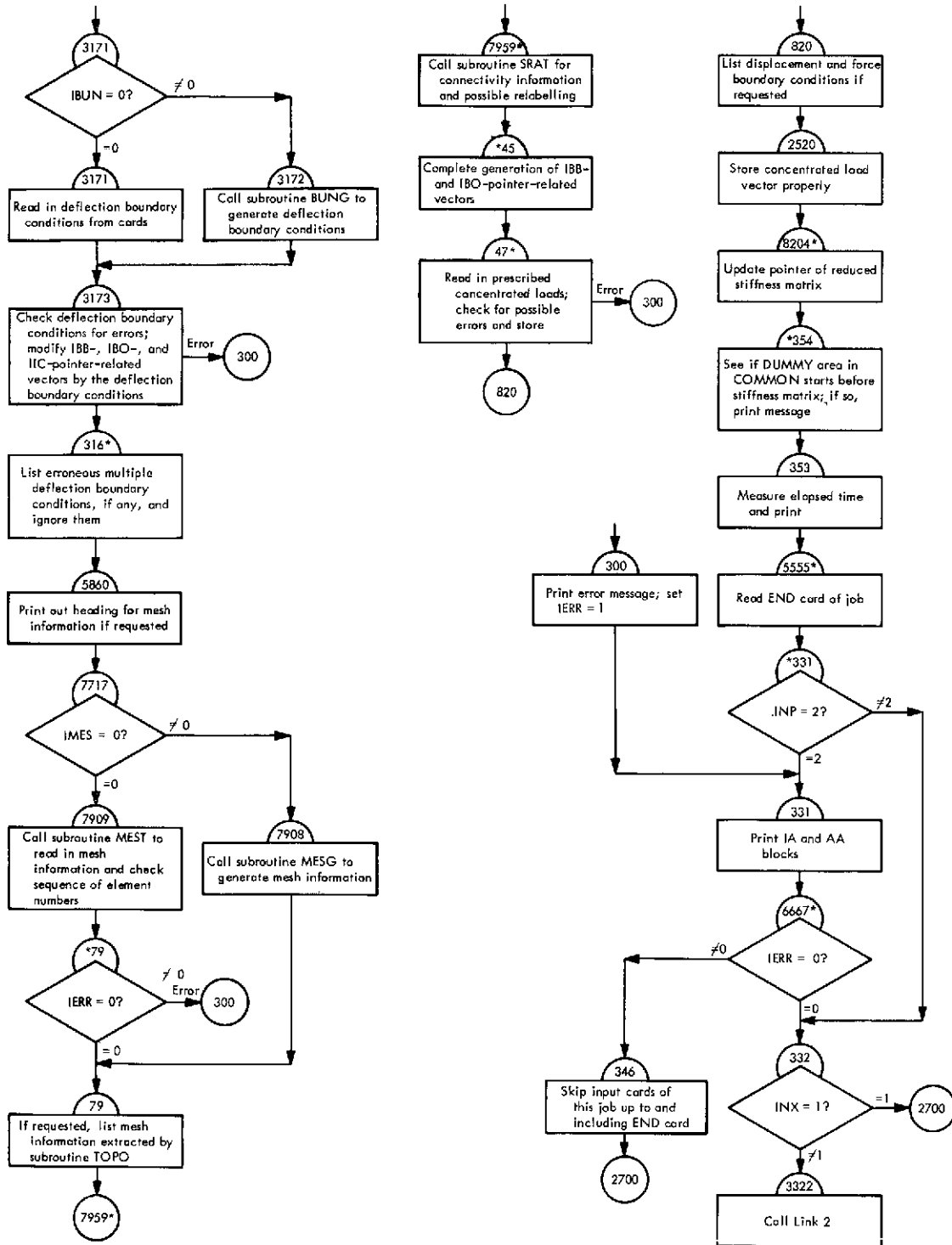


Fig. VI-1 (contd)

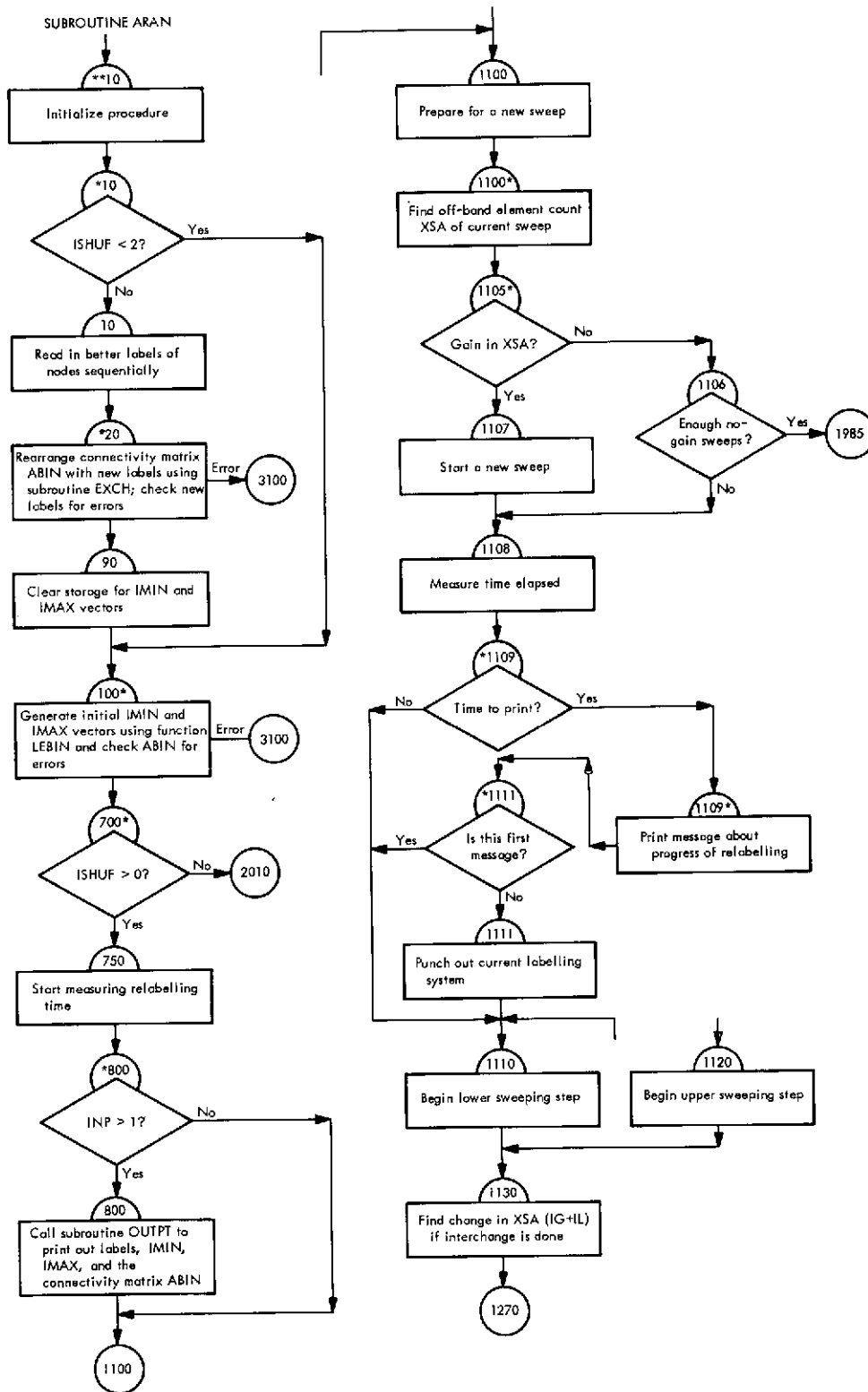


Fig. VI-2. Flowchart of subroutine ARAN (Link 1)

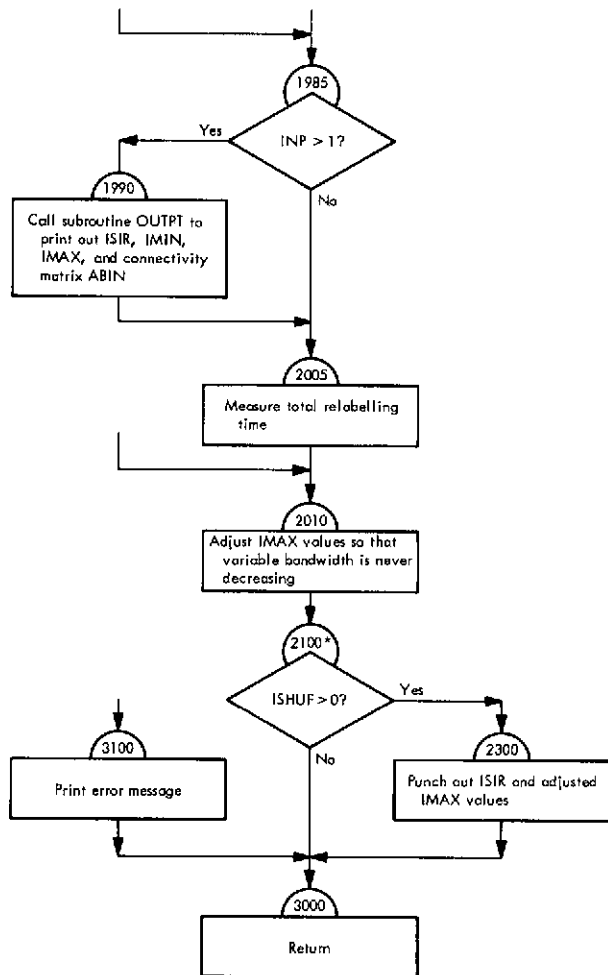
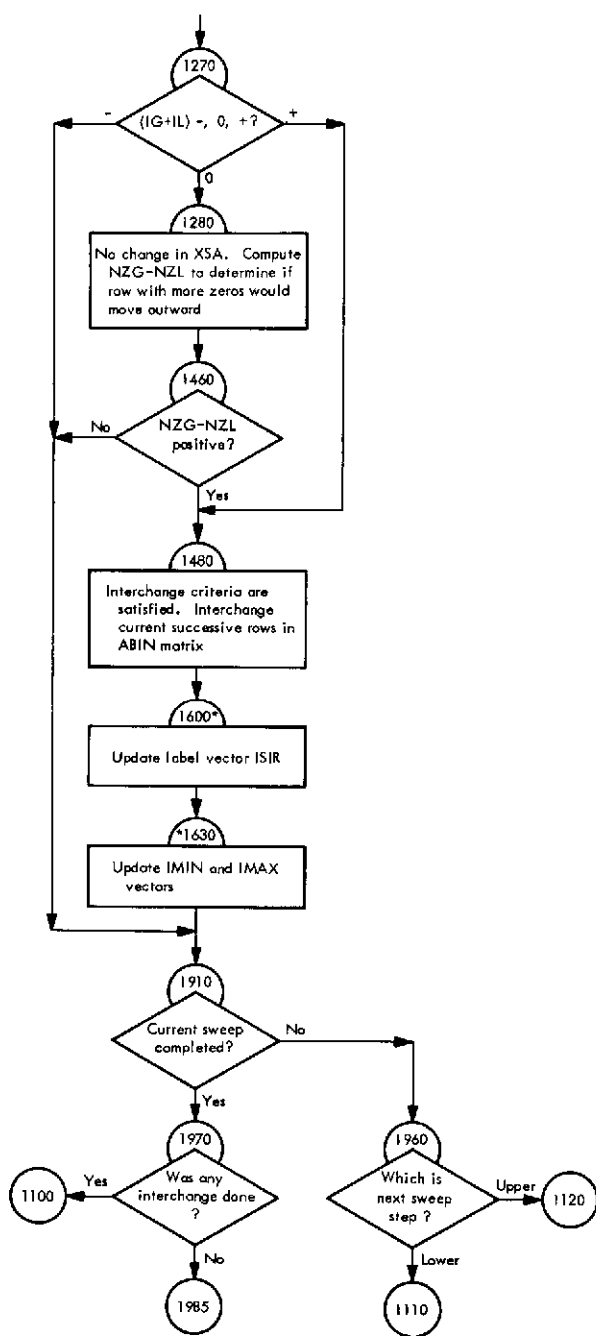


Fig. VI-2 (contd)

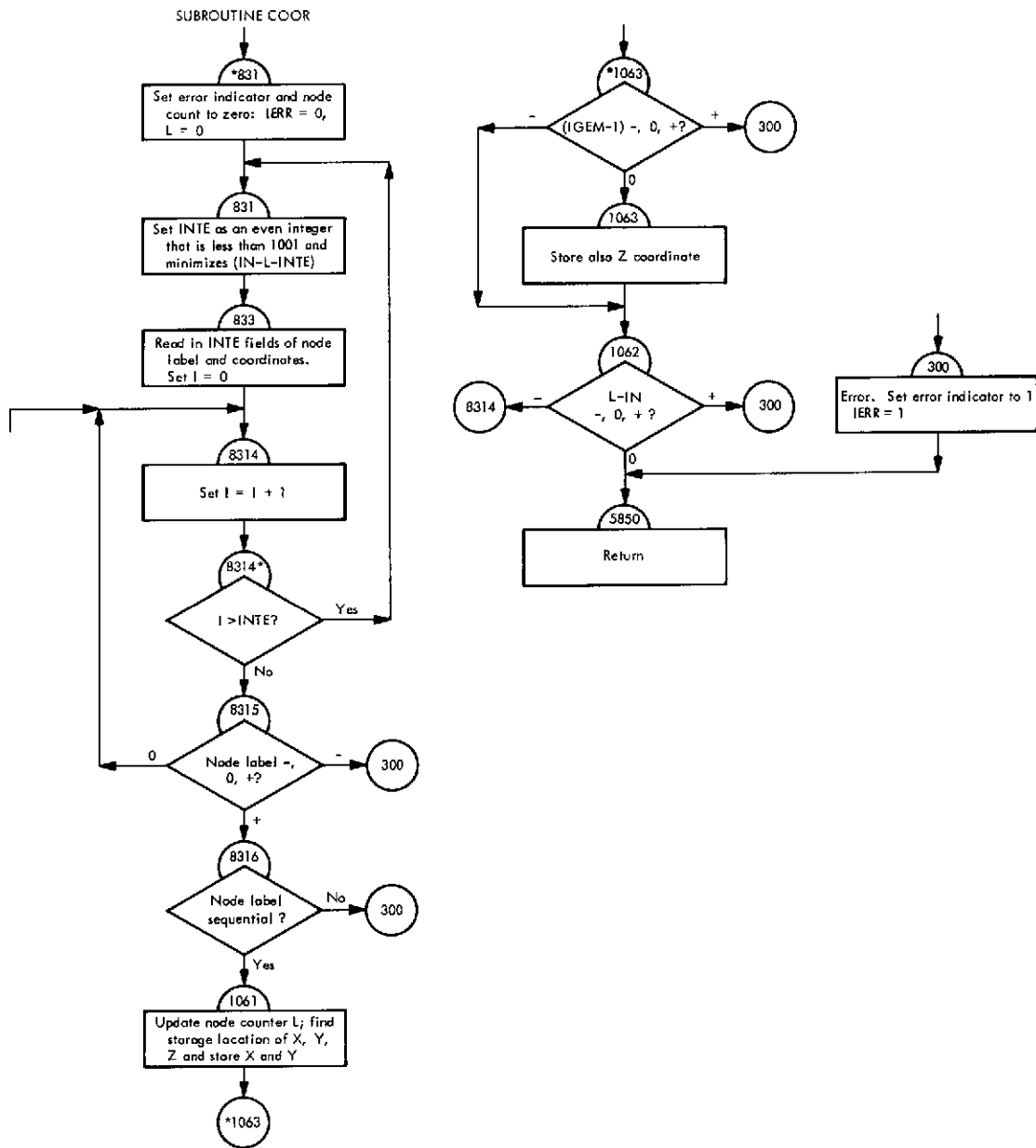


Fig. VI-3. Flowchart of subroutine COOR (Link 1)

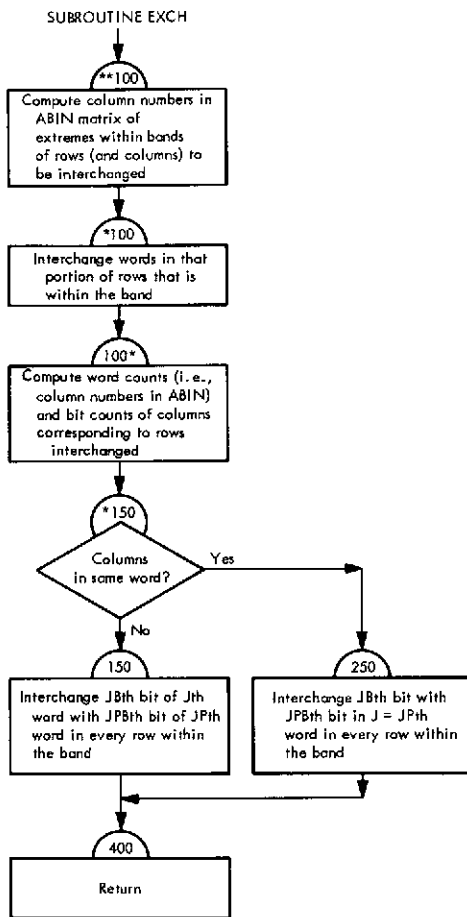


Fig. VI-4. Flowchart of subroutine EXCH (Link 1)

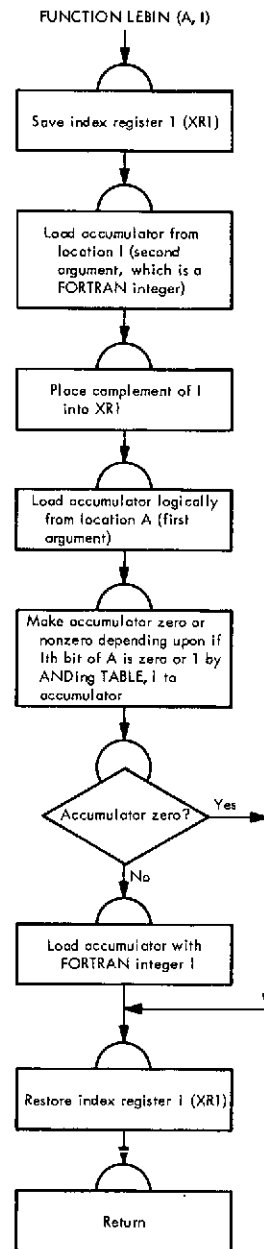


Fig. VI-5. Flowchart of function LEBIN (Link 1)

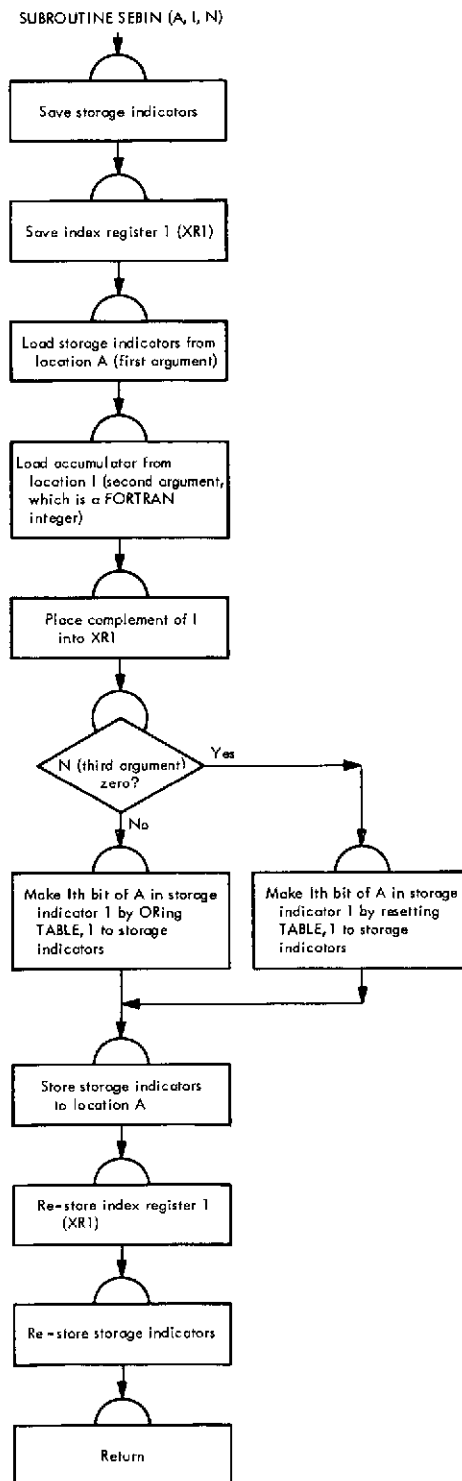


Fig. VI-6. Flowchart of subroutine SEBIN (Link 1)

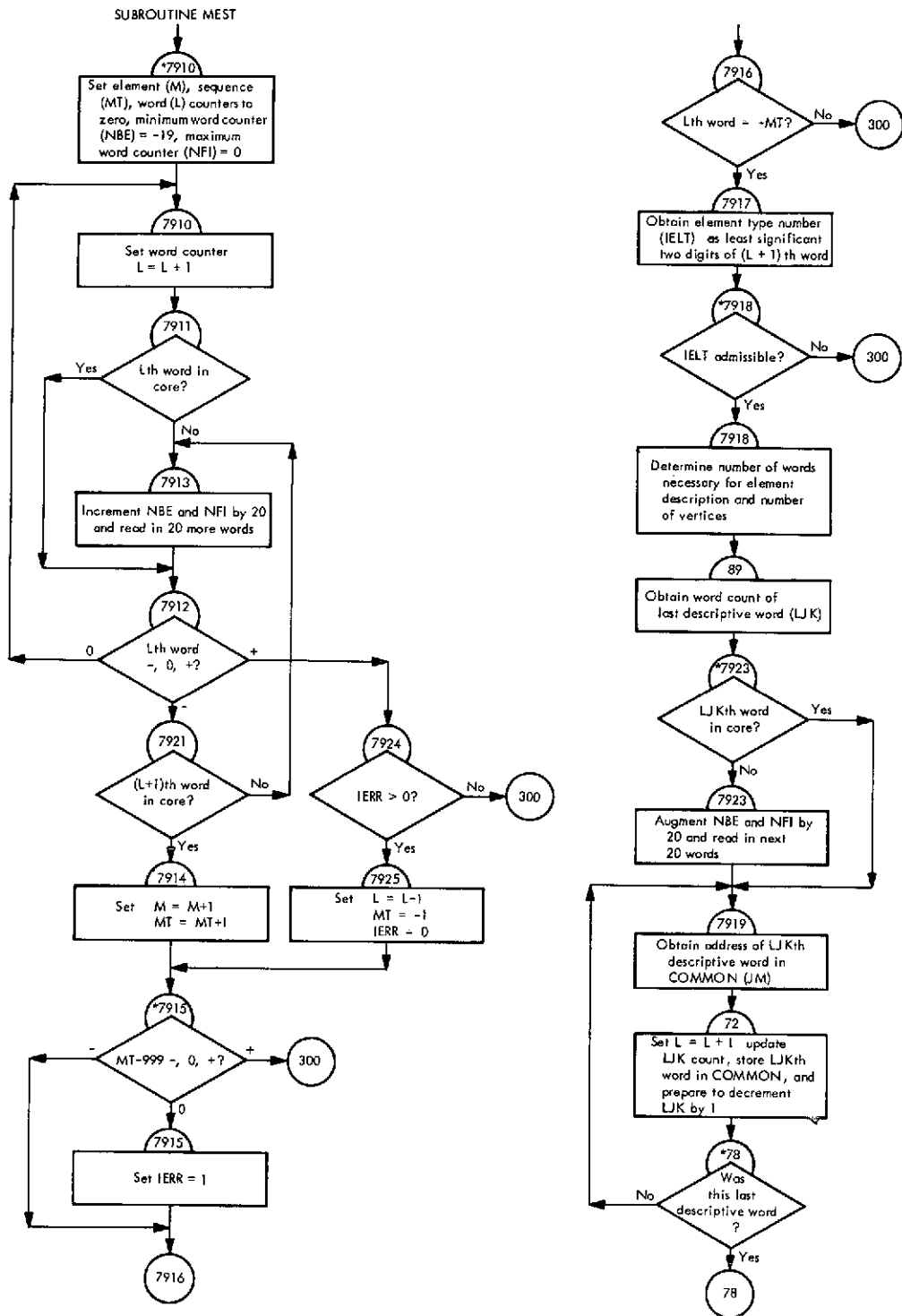


Fig. VI-7. Flowchart of subroutine MEST (Link 1)

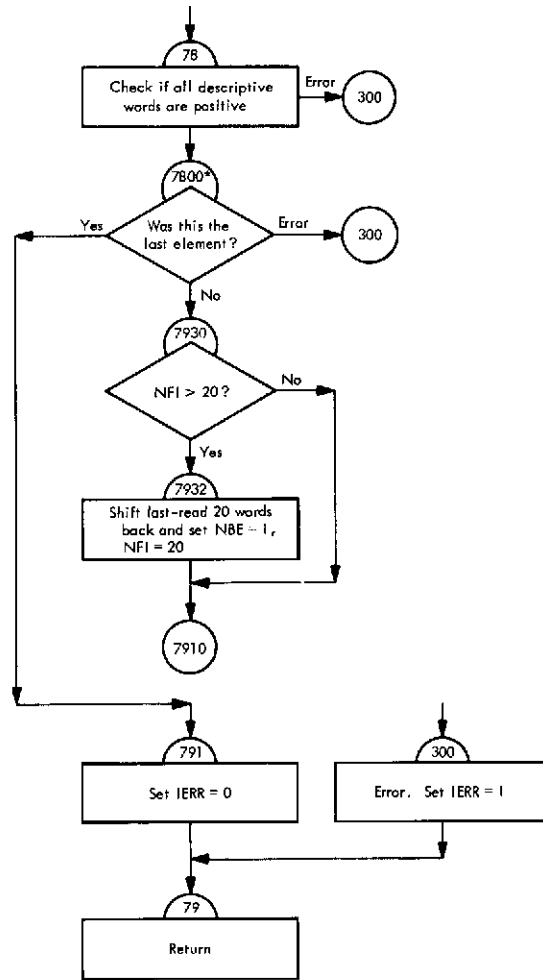


Fig. VI-7 (contd)

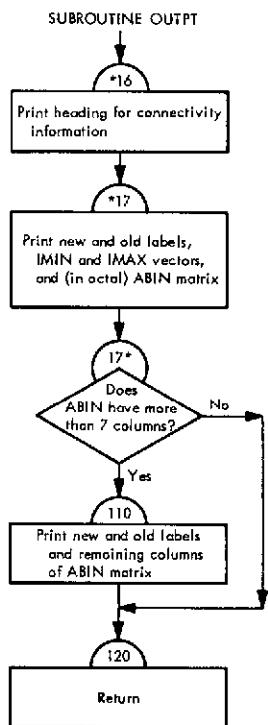


Fig. VI-8. Flowchart of subroutine OUTPT (Link 1)

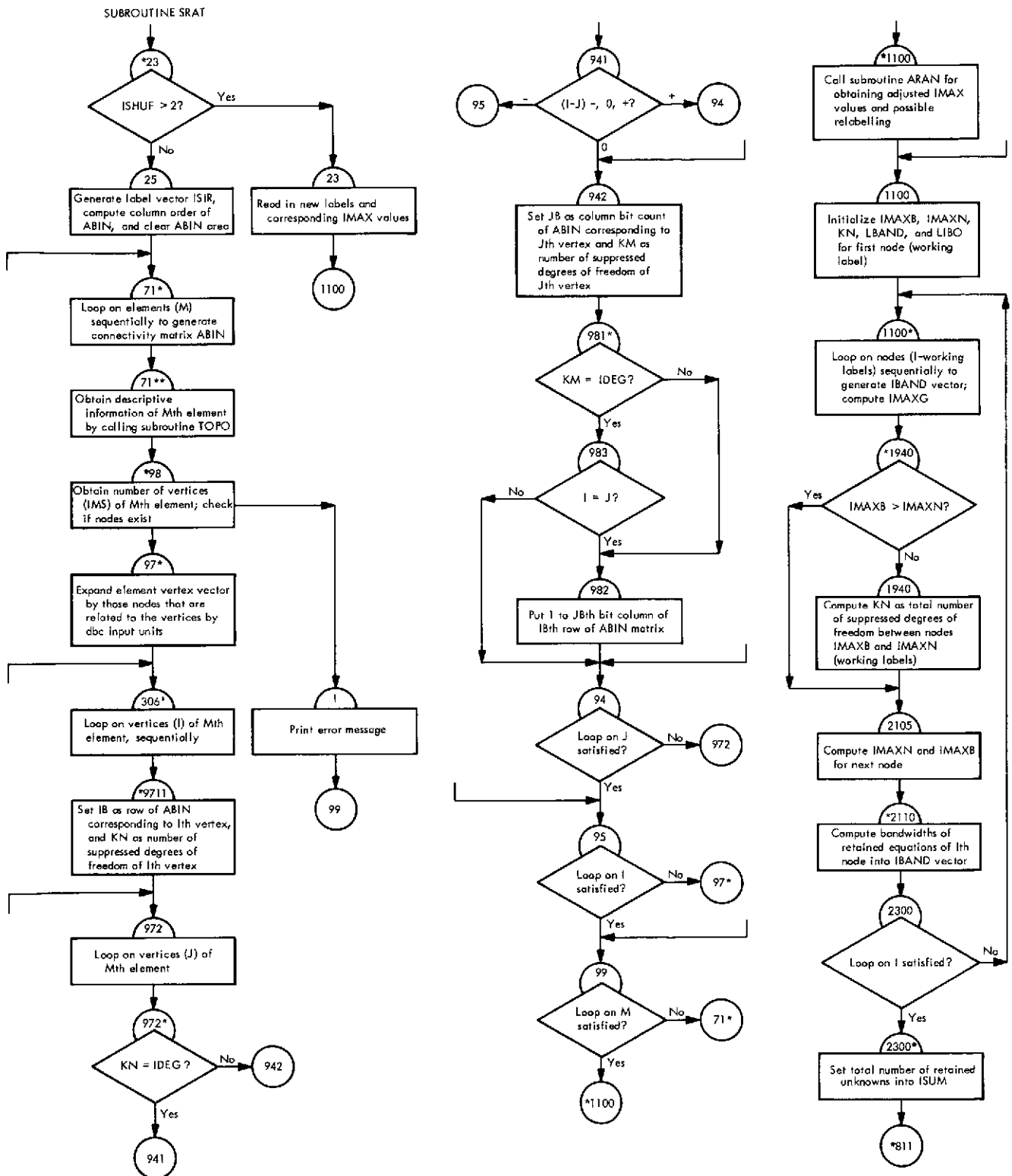


Fig. VI-9. Flowchart of subroutine SRAT (Link 1)

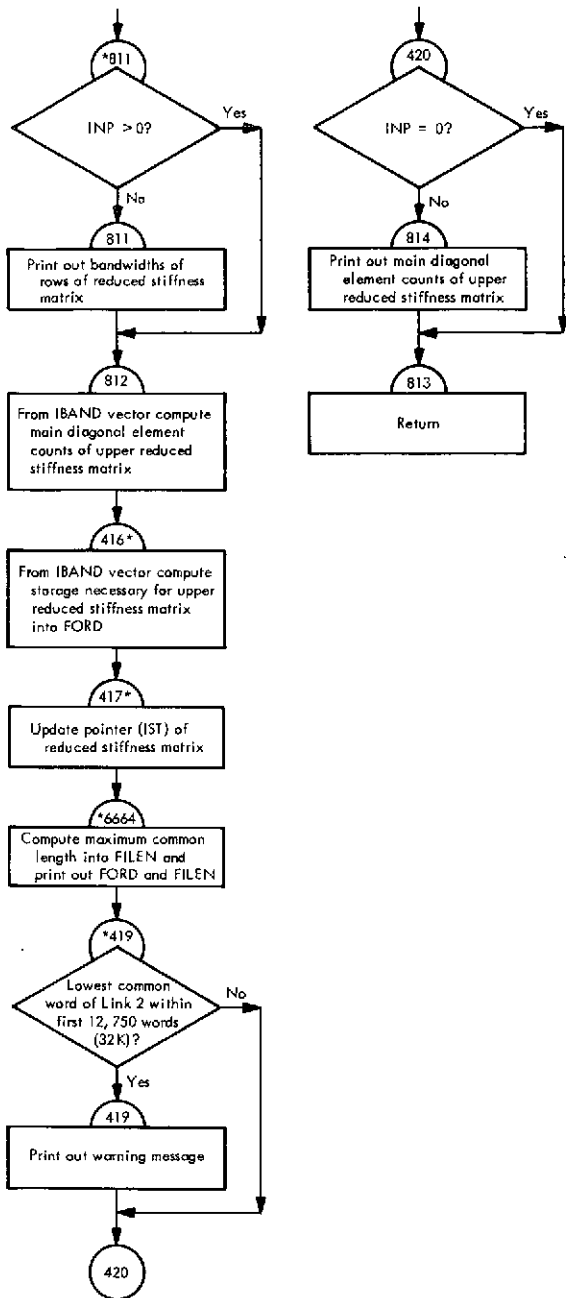


Fig. VI-9 (contd)

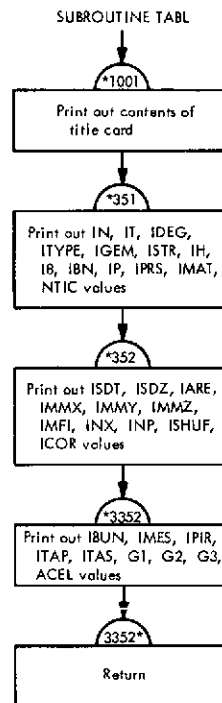
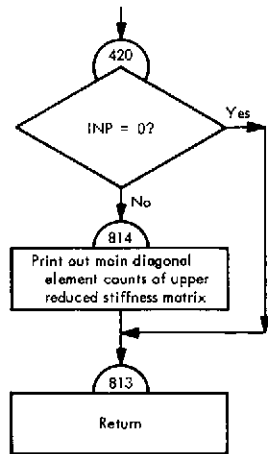


Fig. VI-10. Flowchart of subroutine TABL (Link 1)

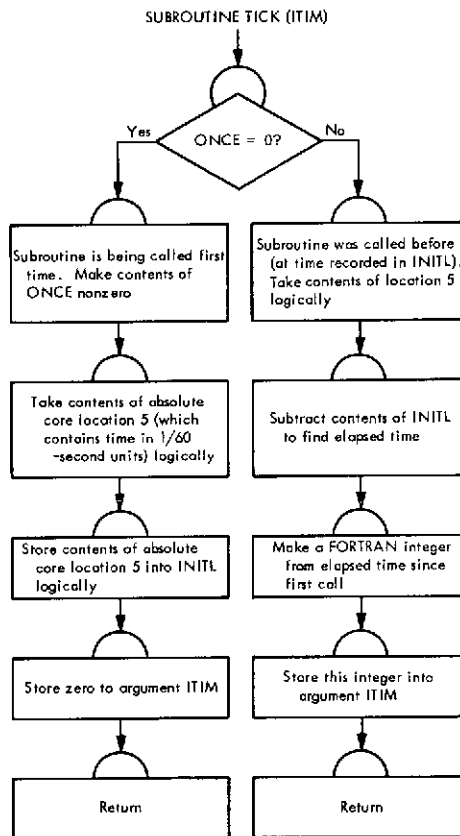


Fig. VI-11. Flowchart of subroutine TICK (Link 1)

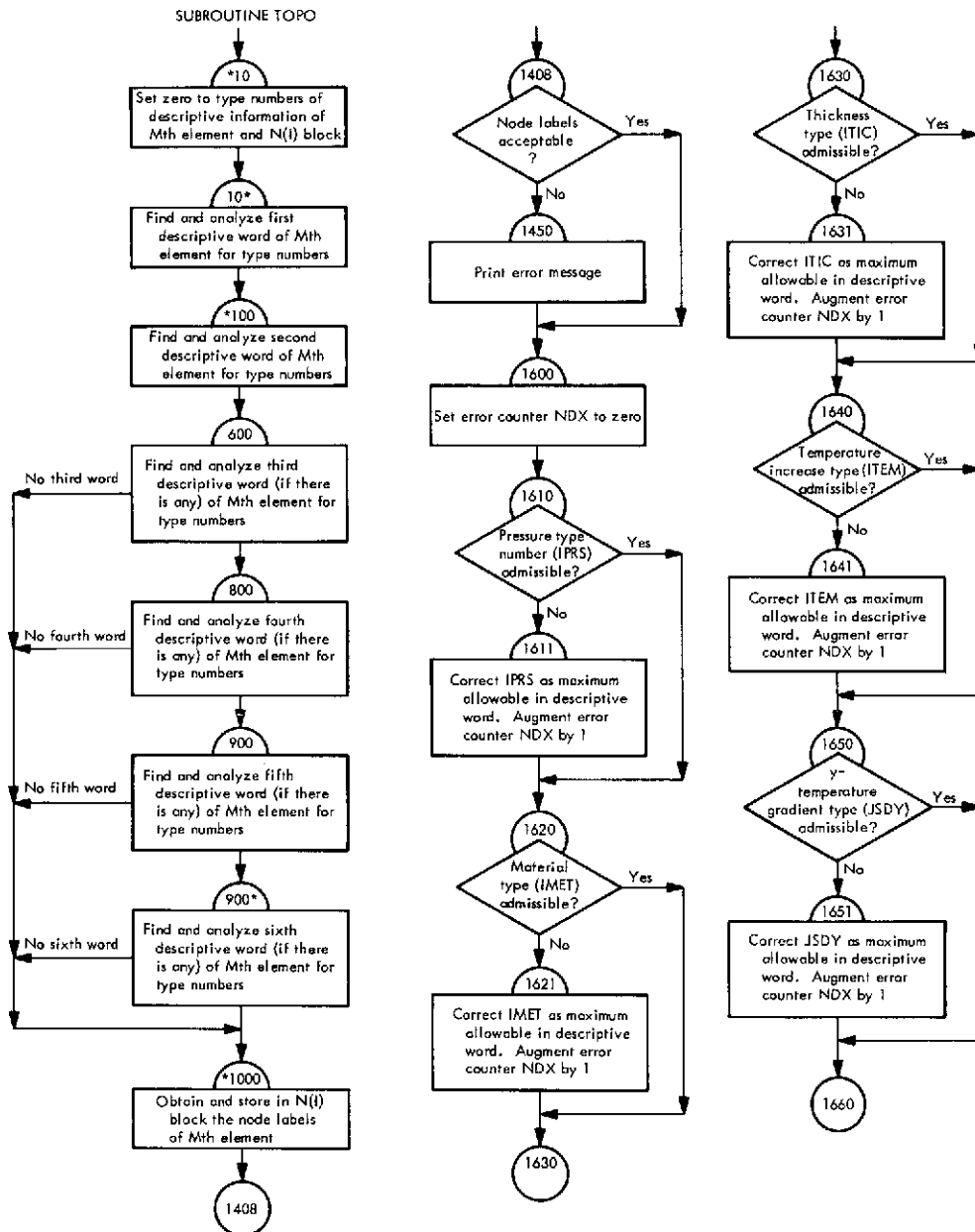


Fig. VI-12. Flowchart of subroutine TOPO (Link 1)

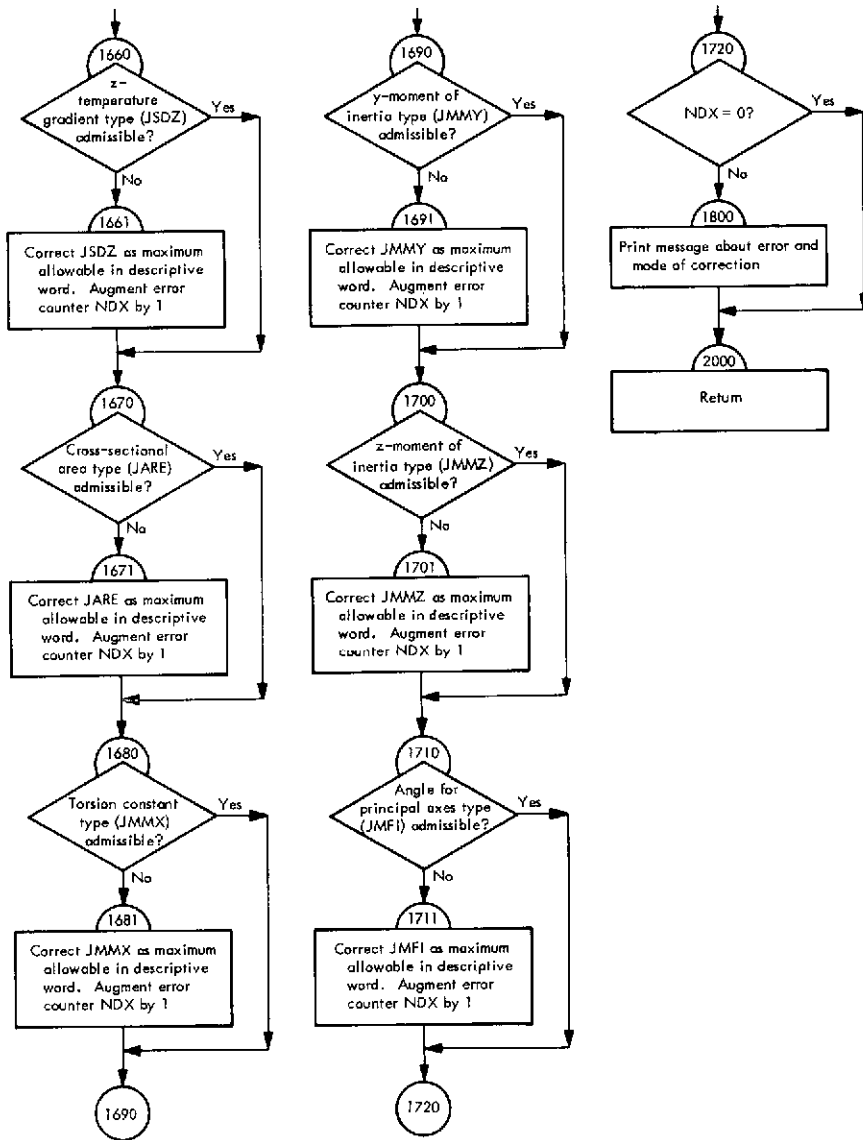


Fig. VI-12 (contd)

MAIN PROGRAM OF LINK 2

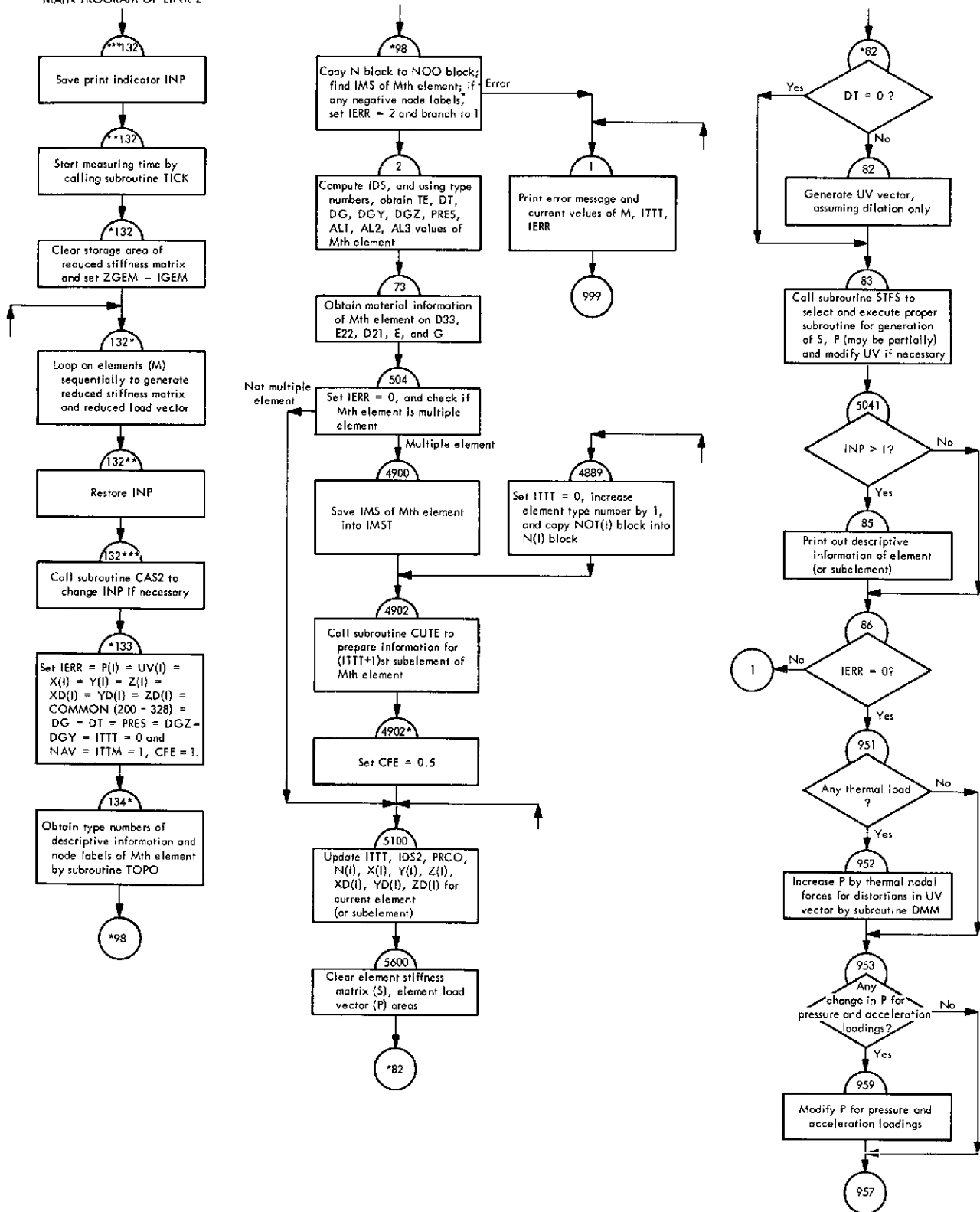


Fig. VI-13. Flowchart of main program of Link 2 (generation link)

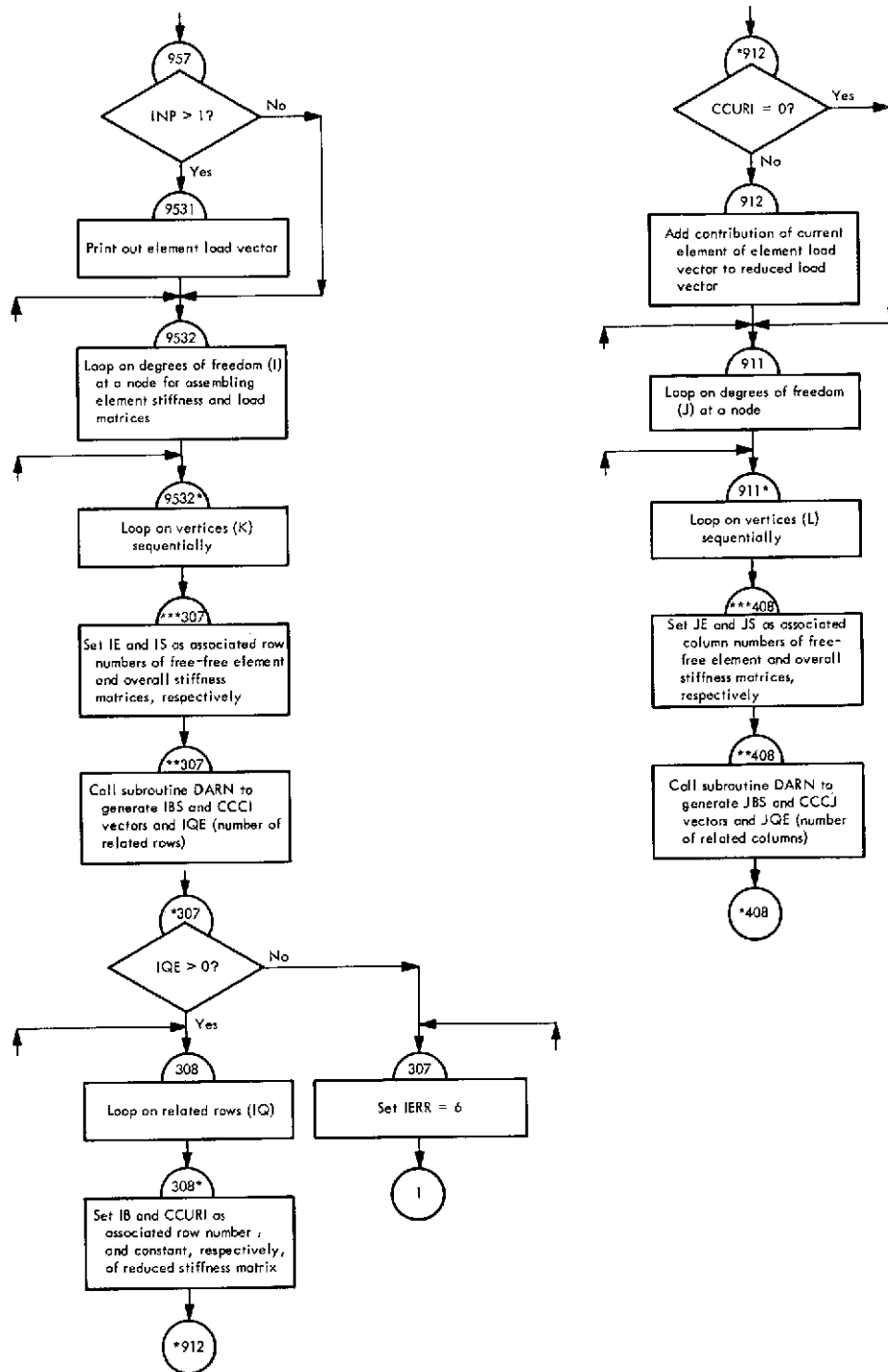


Fig. VI-13 (contd)

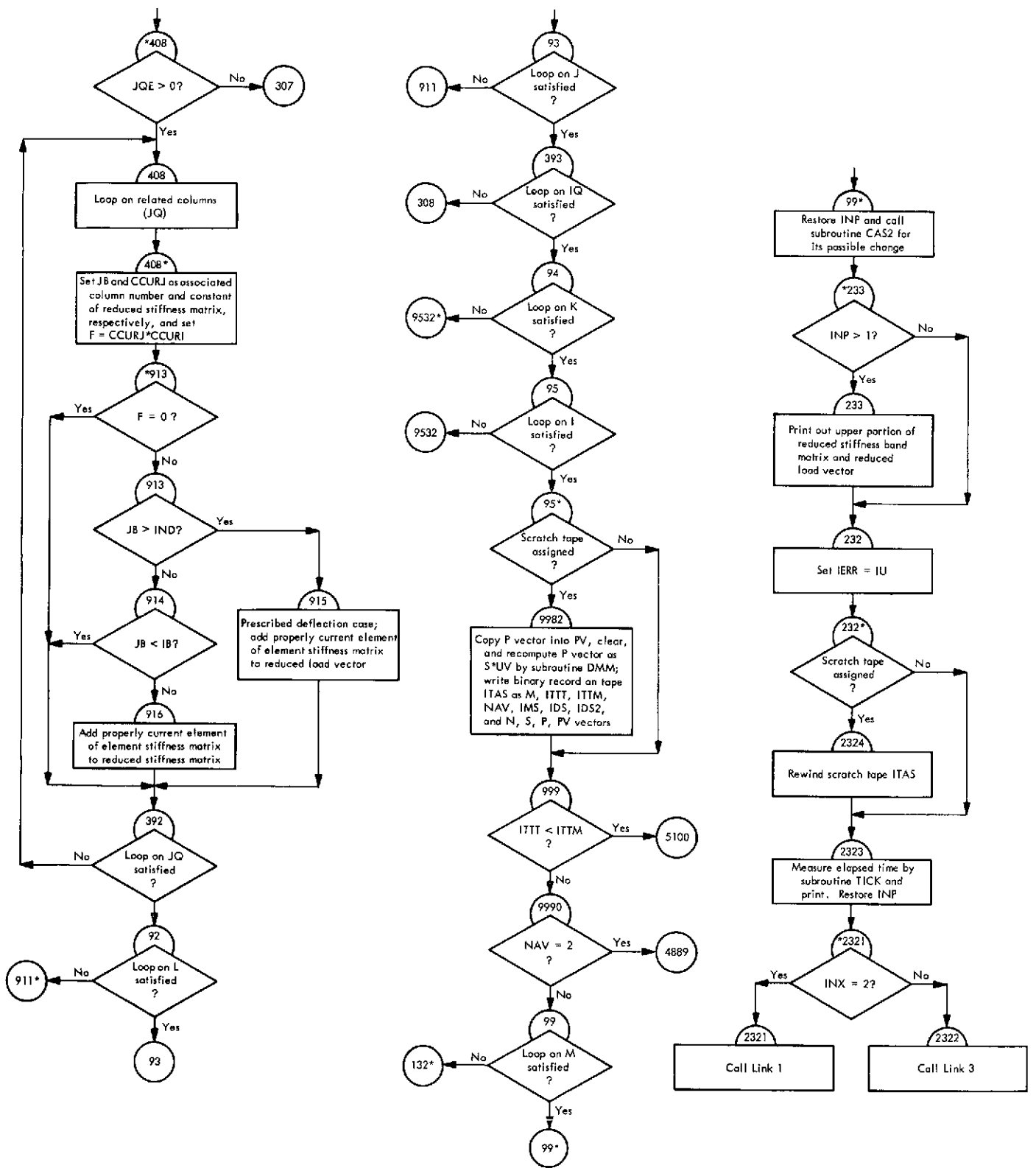


Fig. VI-13 (contd)

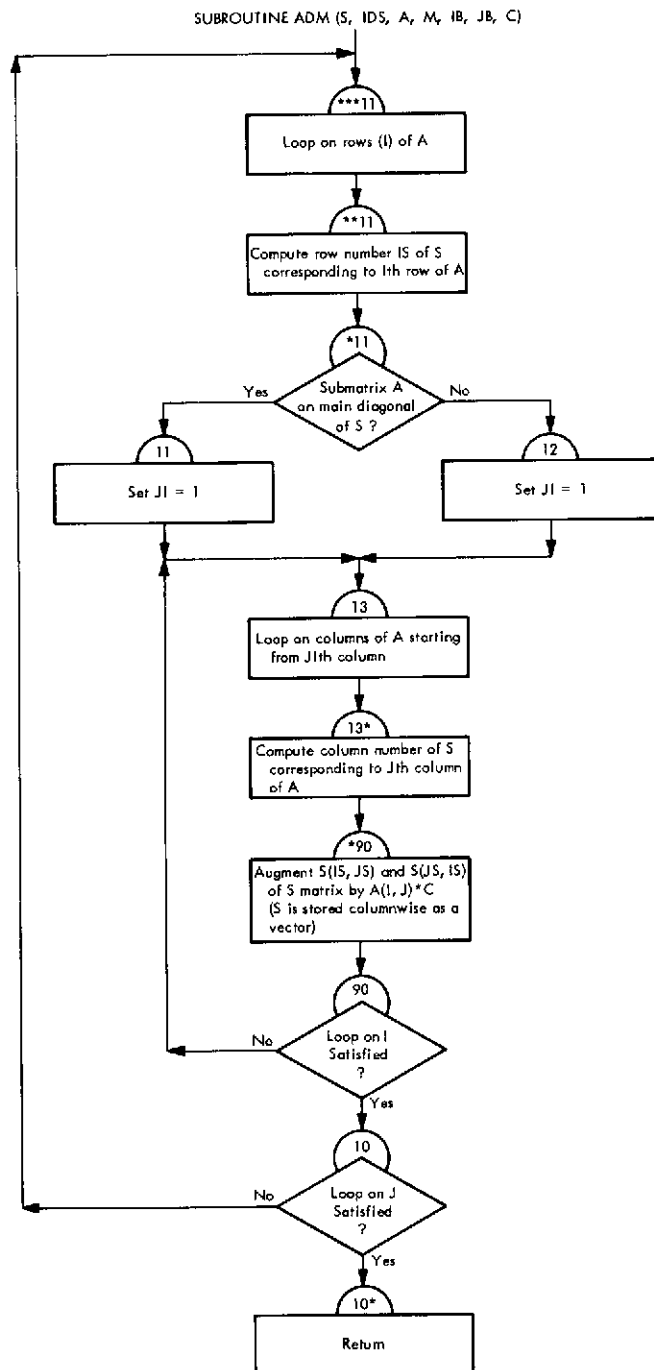


Fig. VI-14. Flowchart of subroutine ADM (Link 2)

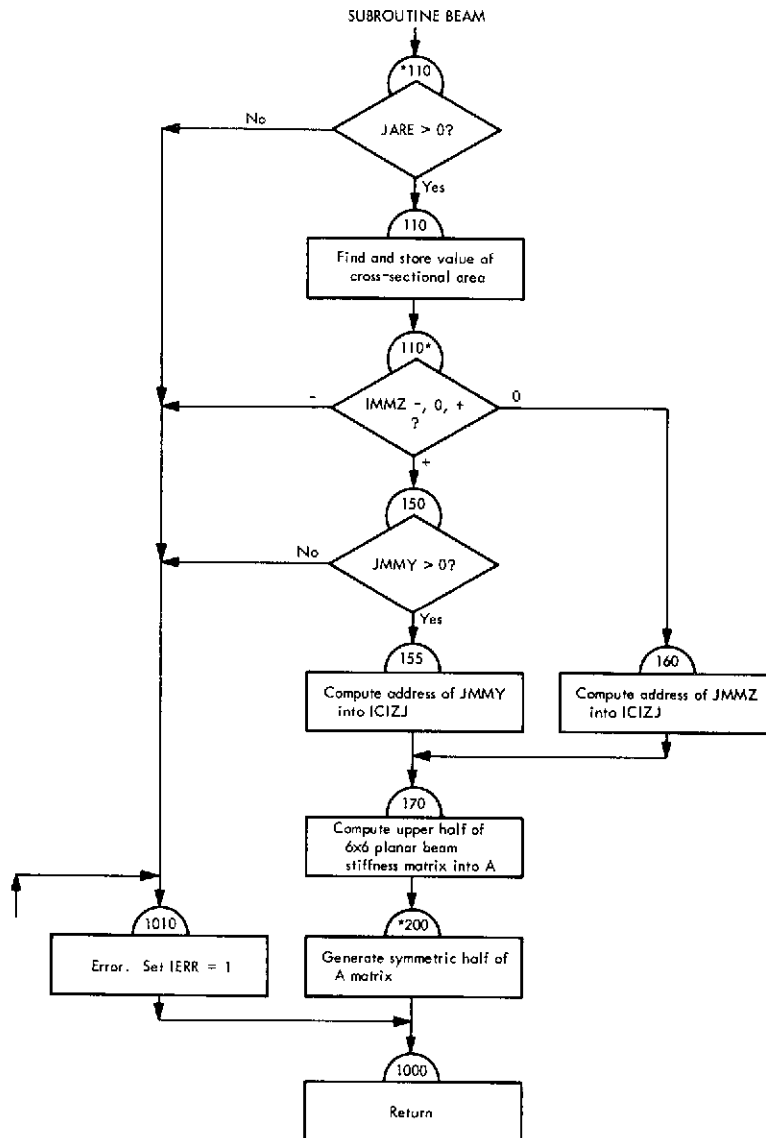


Fig. VI-15. Flowchart of subroutine BEAM (Link 2)

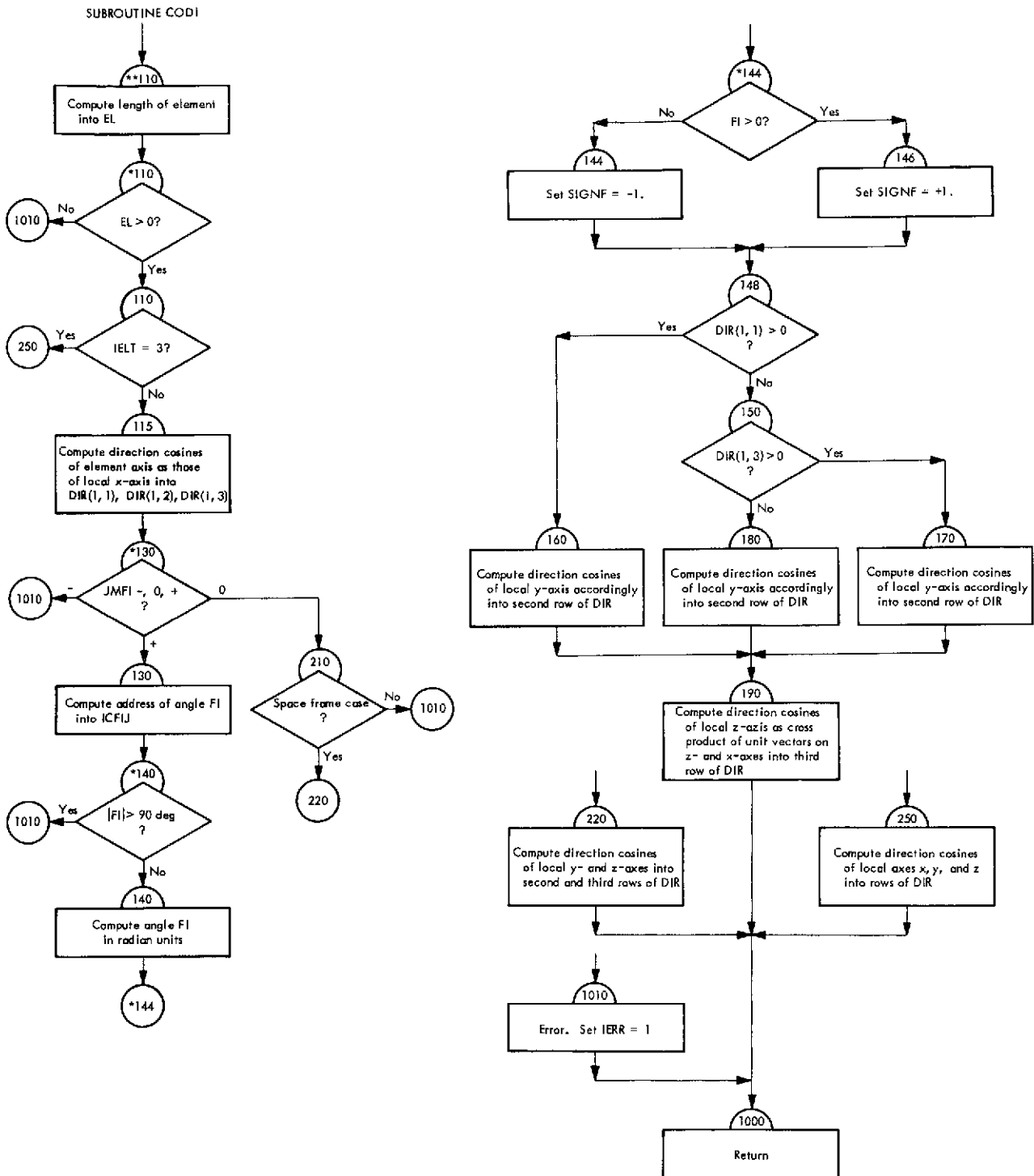


Fig. VI-16. Flowchart of subroutine CODI (Link 2)

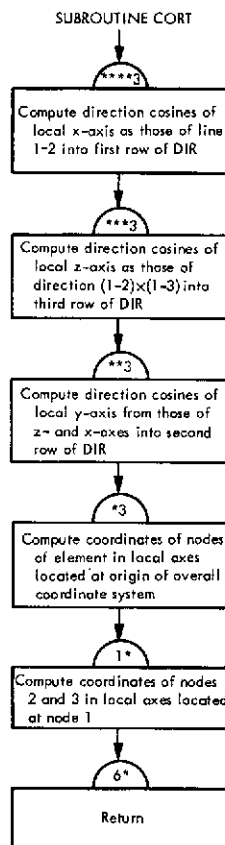


Fig. VI-17. Flowchart of subroutine CORT (Link 2)

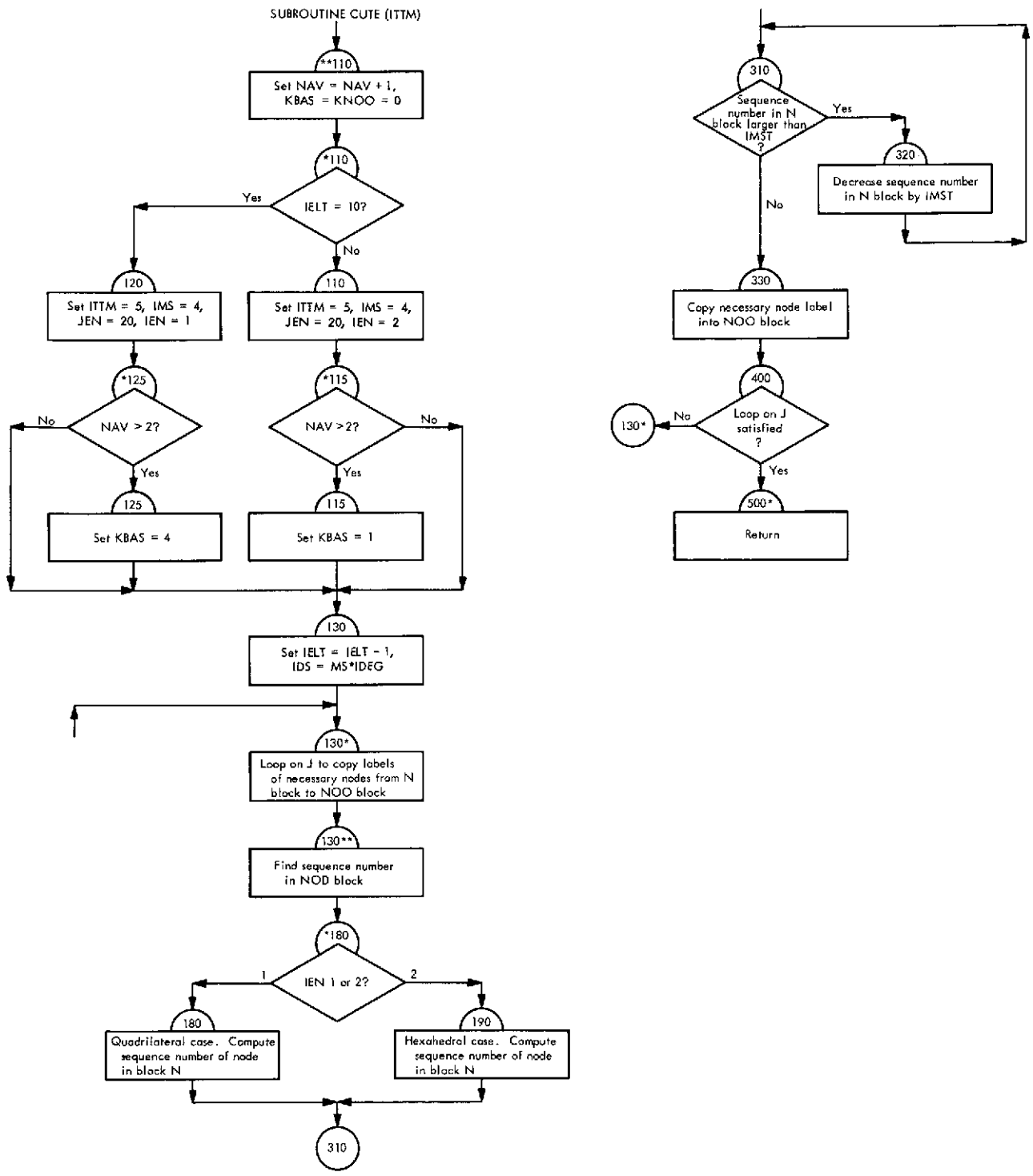


Fig. VI-18. Flowchart of subroutine CUTE (Link 2)

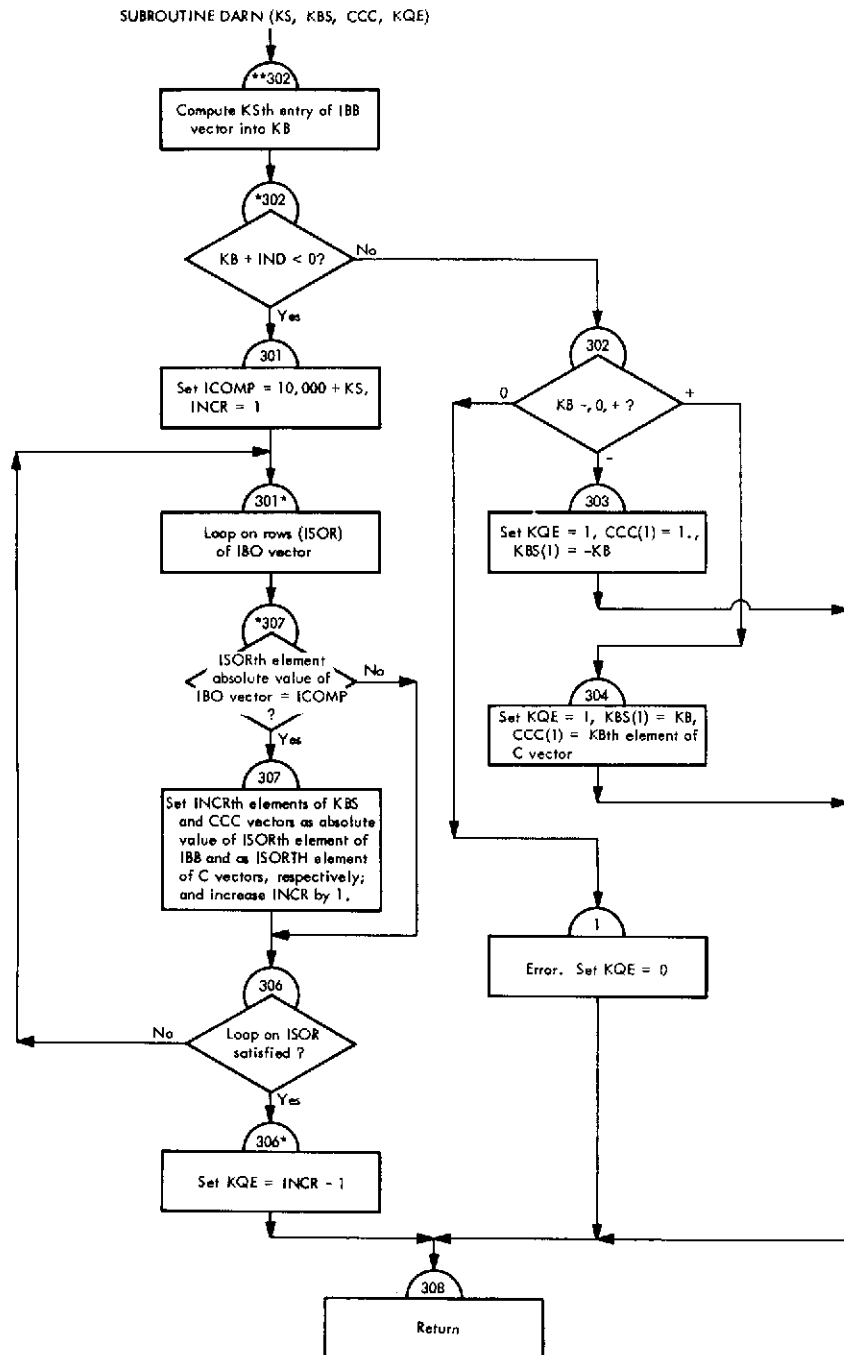


Fig. VI-19. Flowchart of subroutine DARN (Link 2)

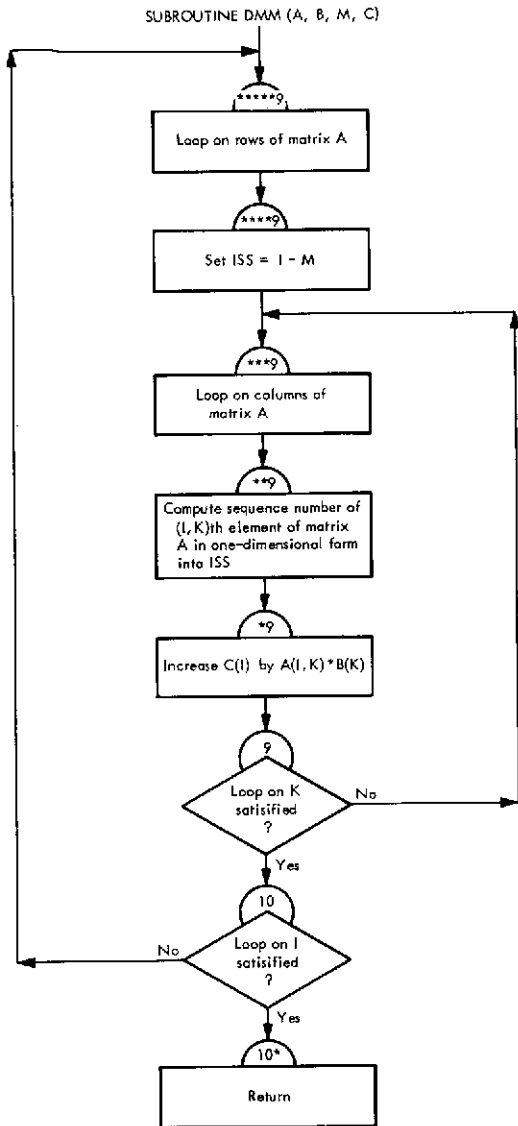


Fig. VI-20. Flowchart of subroutine DMM (Link 2)

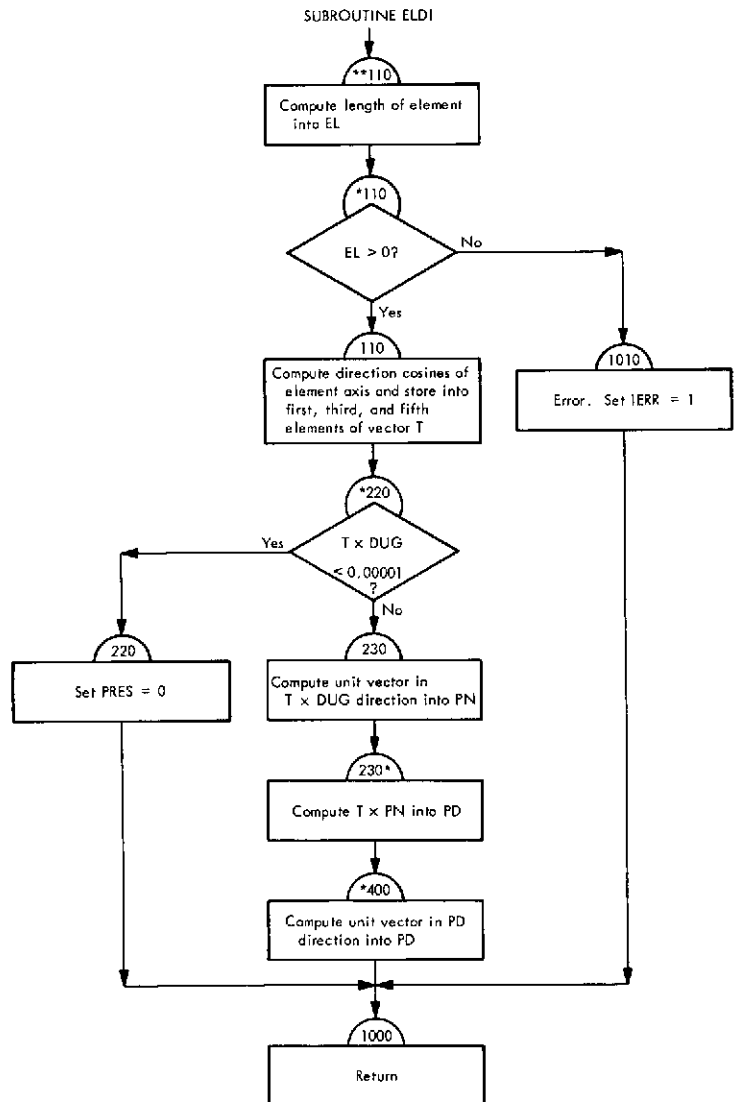


Fig. VI-21. Flowchart of subroutine ELDI (Link 2)

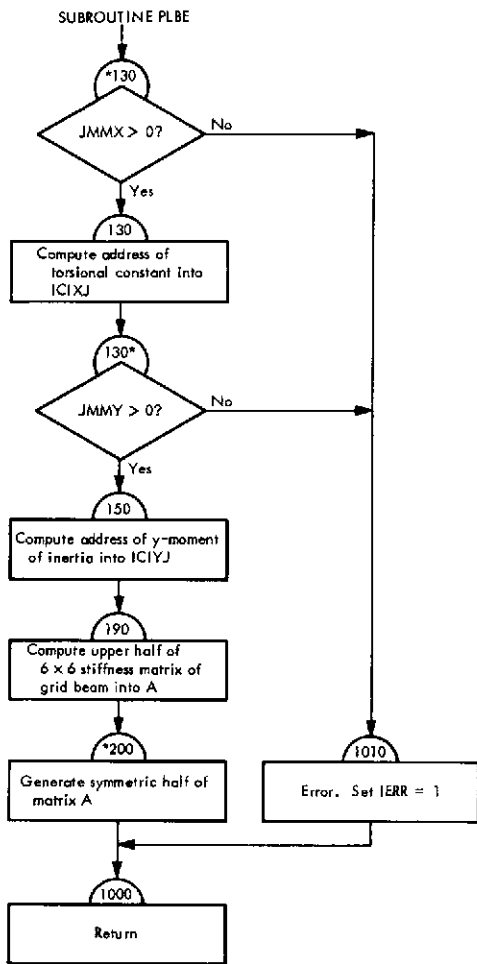


Fig. VI-22. Flowchart of subroutine PLBE (Link 2)

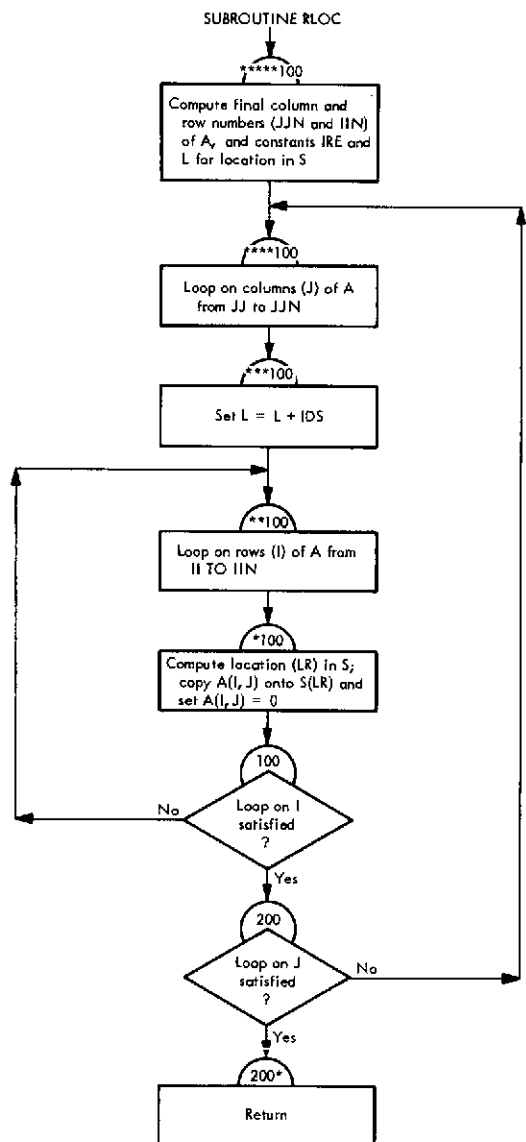


Fig. VI-23. Flowchart of subroutine RLOC (Link 2)

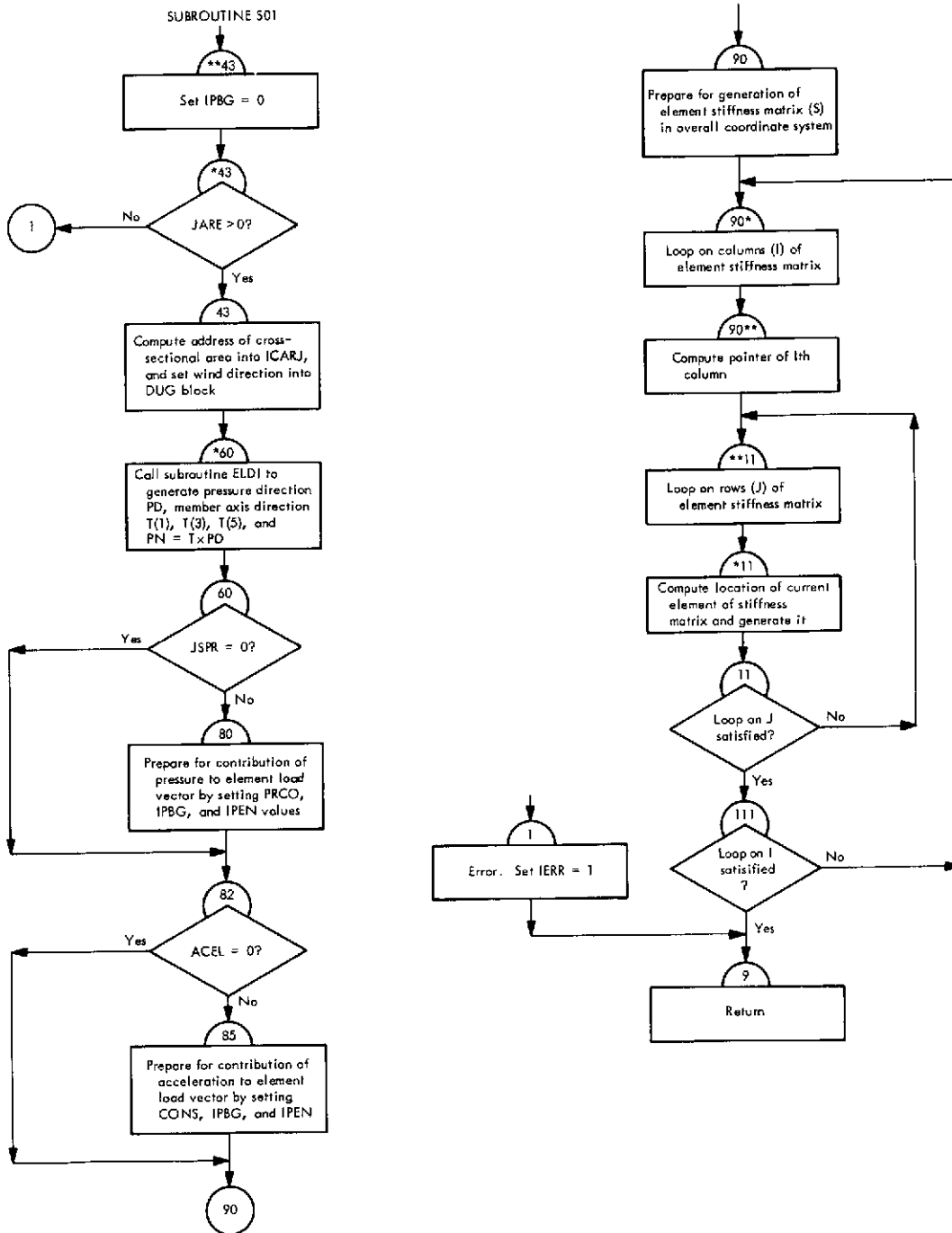


Fig. VI-24. Flowchart of subroutine S01 (Link 2)

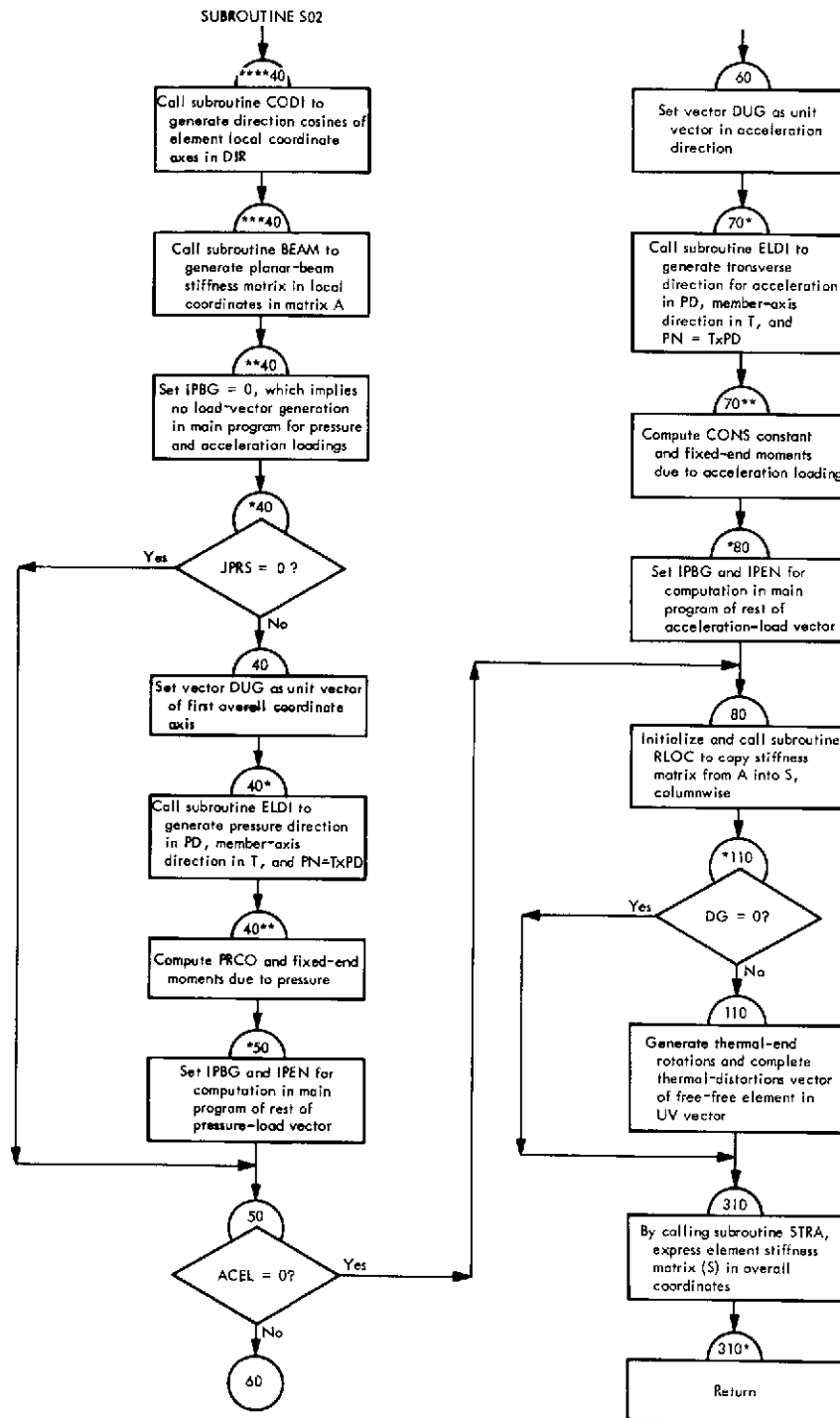


Fig. VI-25. Flowchart of subroutine S02 (Link 2)

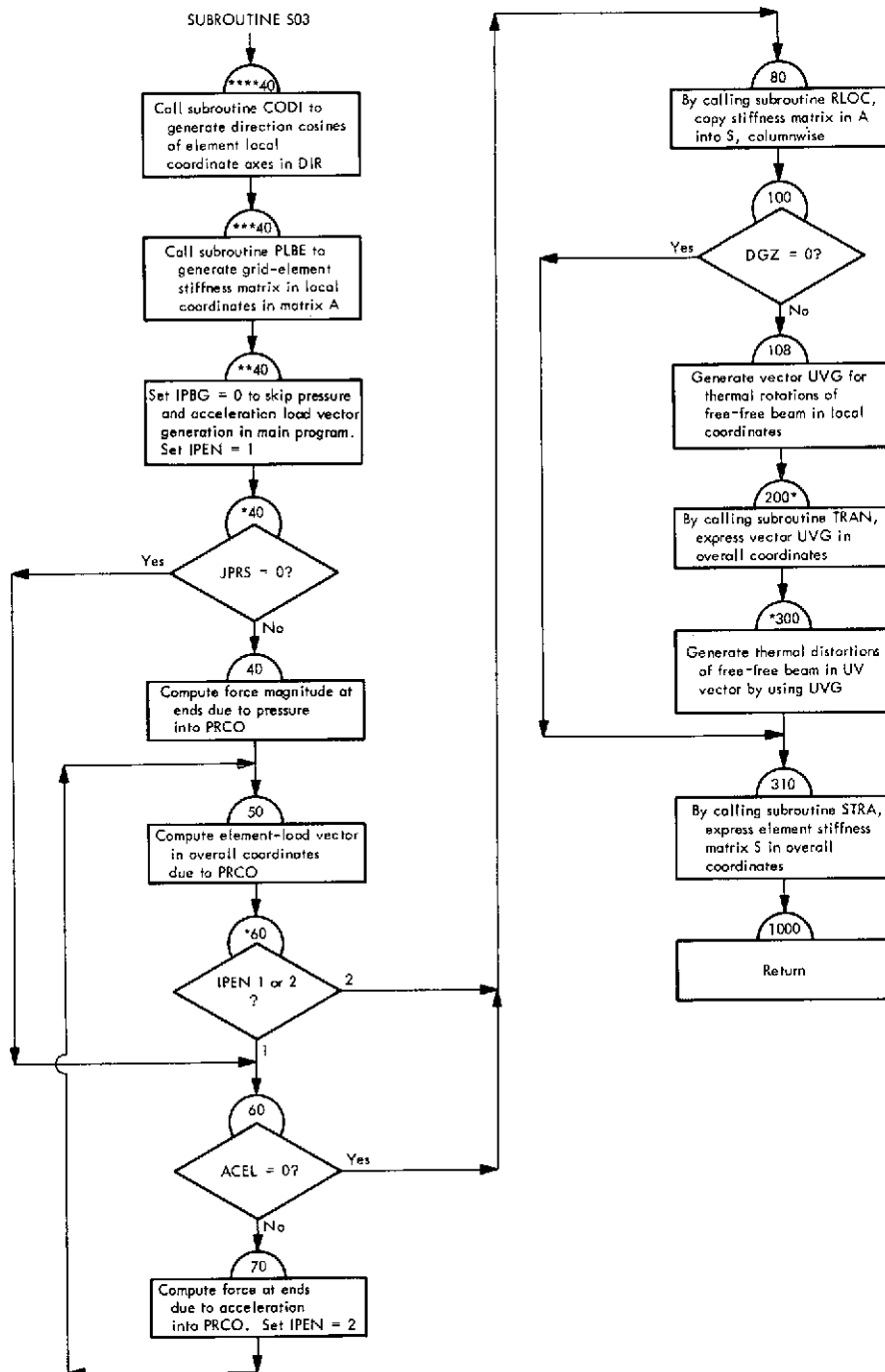


Fig. VI-26. Flowchart of subroutine S03 (Link 2)

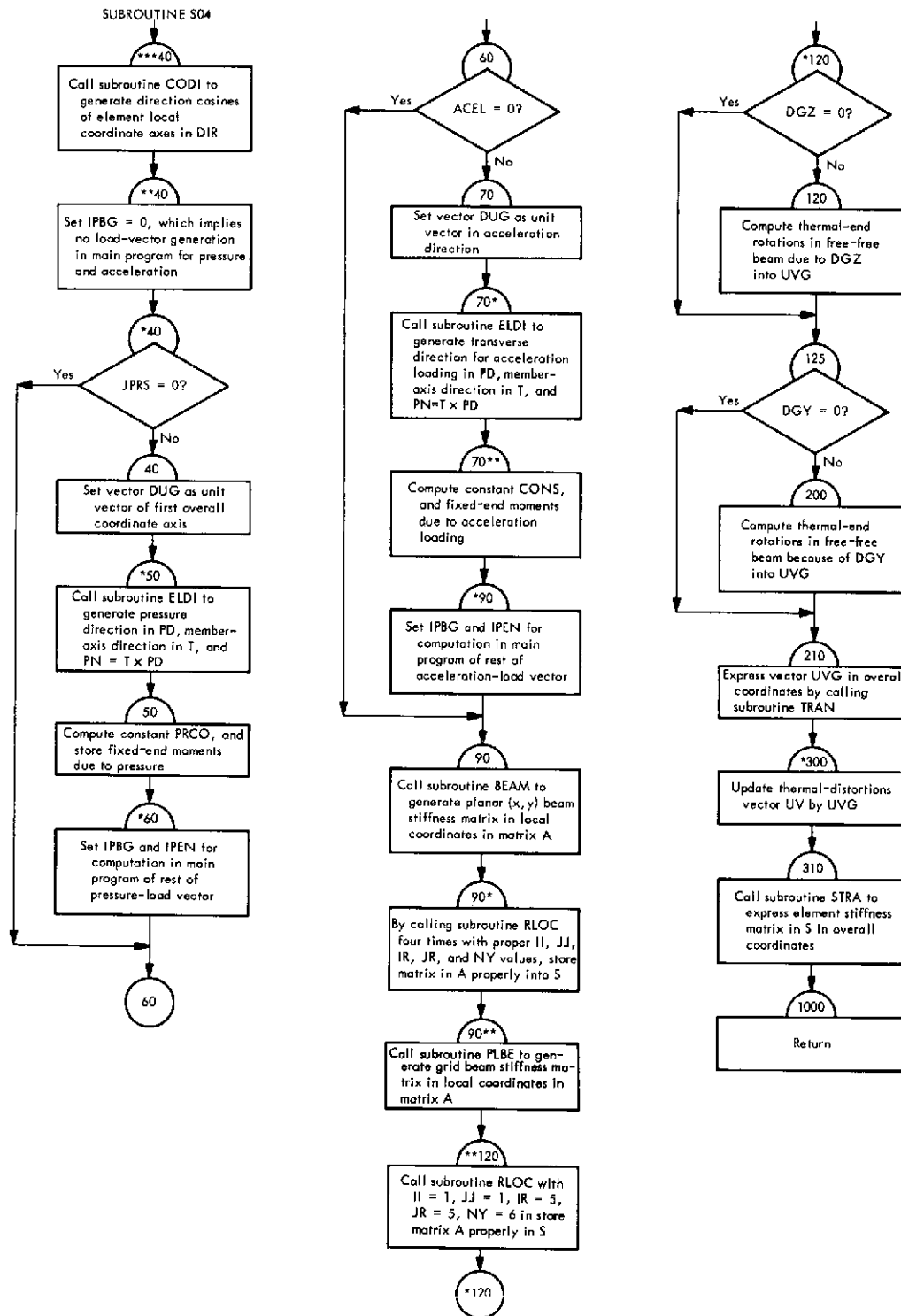


Fig. VI-27. Flowchart of subroutine S04 (Link 2)

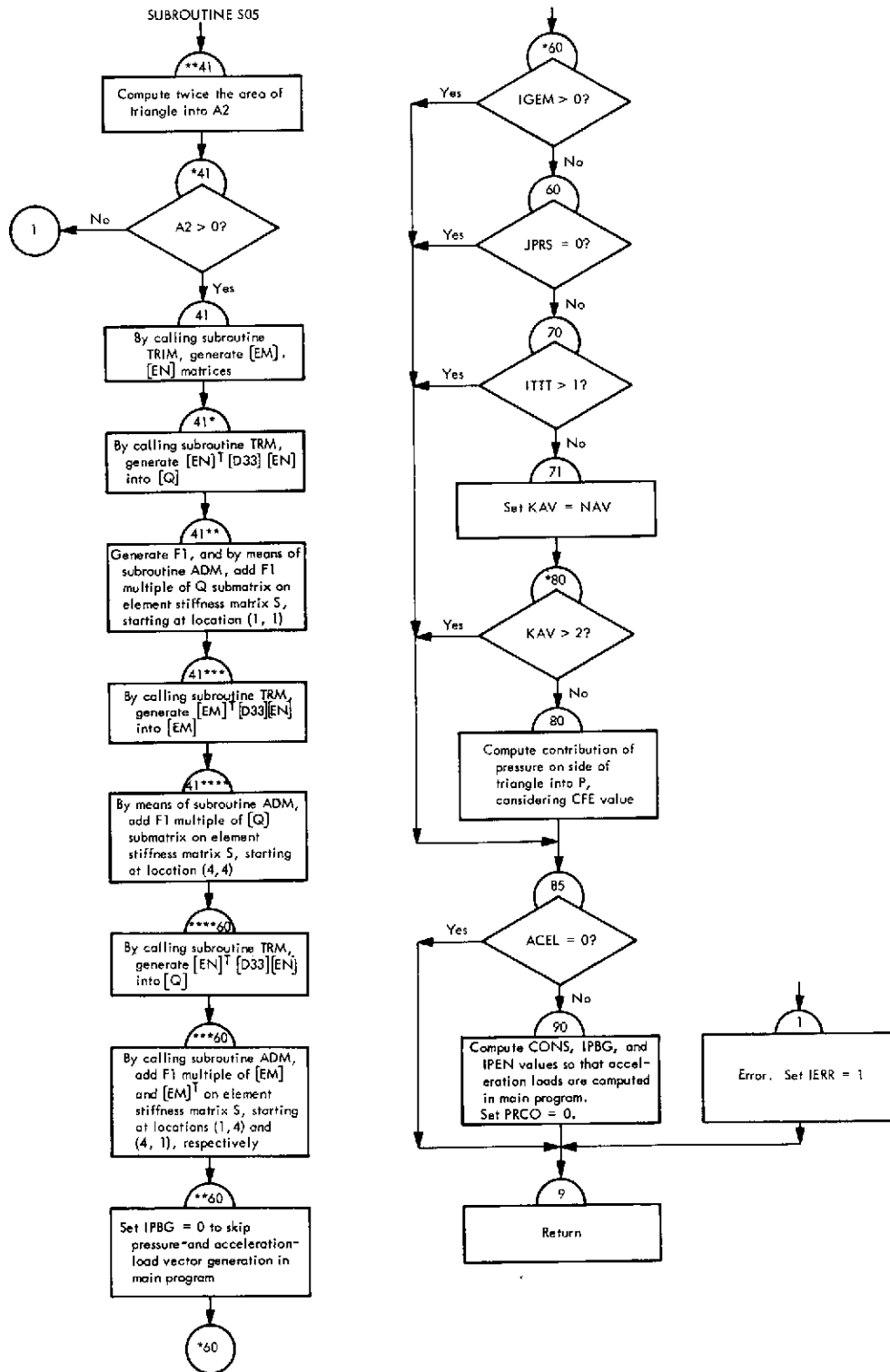


Fig. VI-28. Flowchart of subroutine S05 (Link 2)

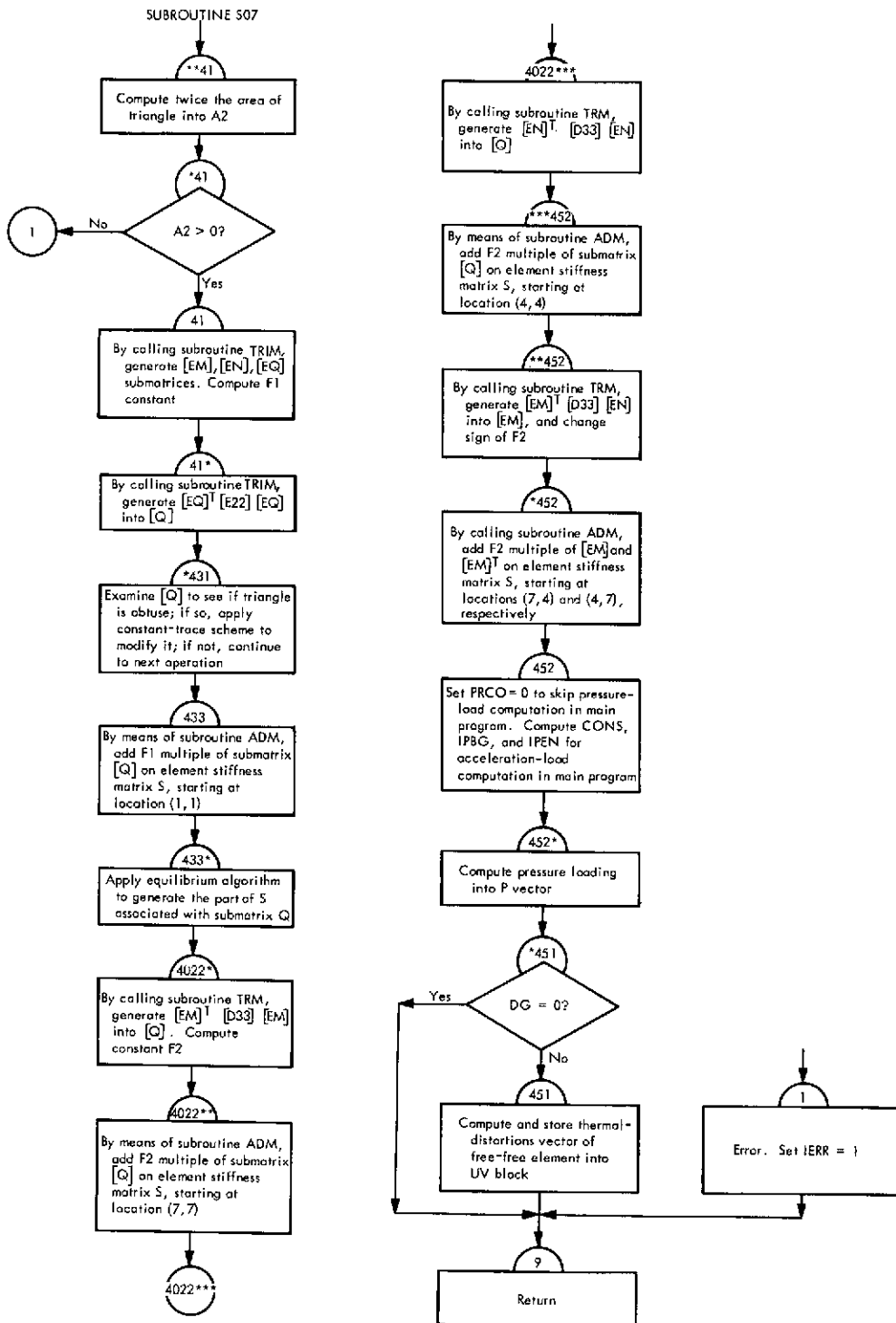


Fig. VI-29. Flowchart of subroutine S07 (Link 2)

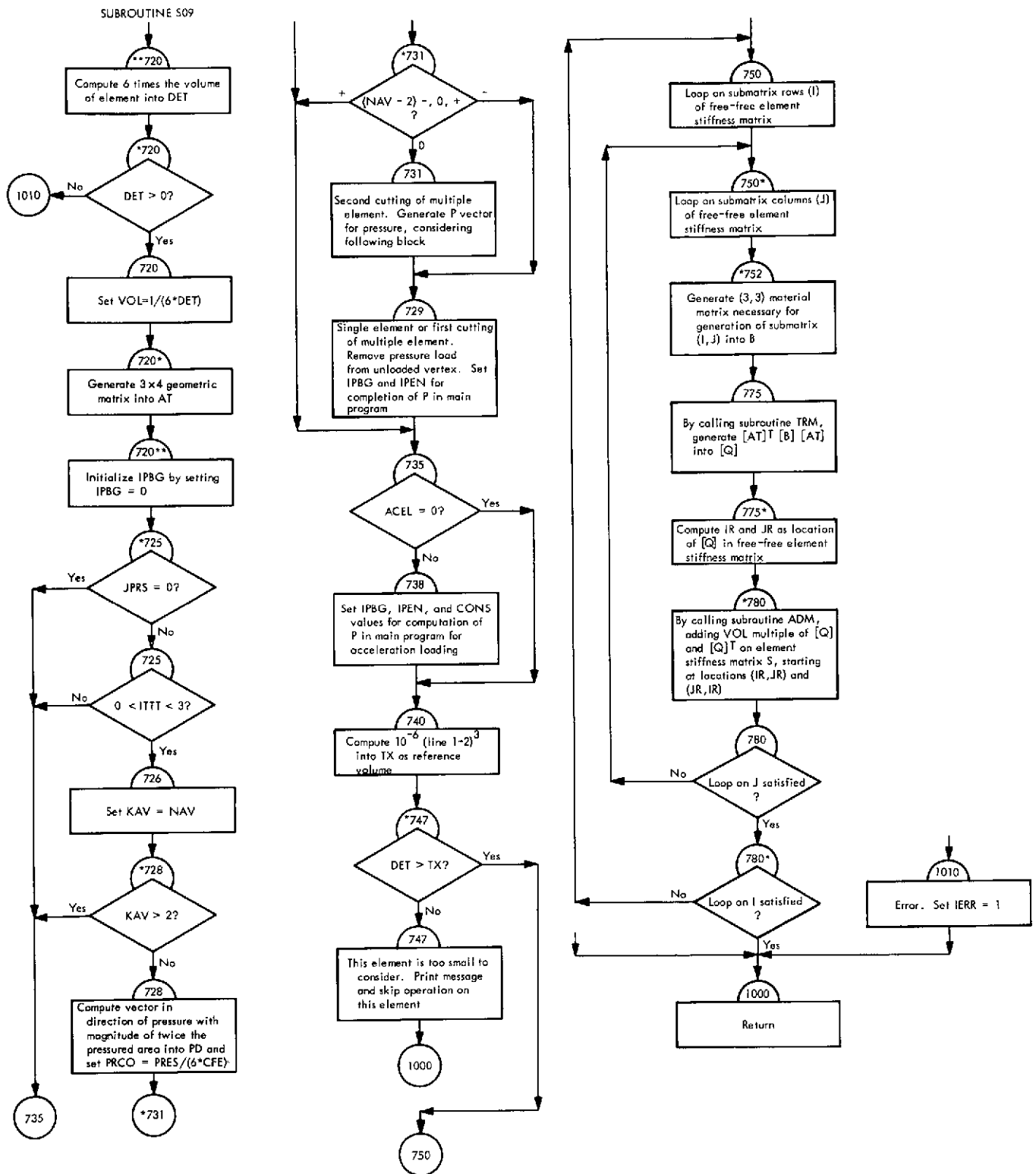


Fig. VI-30. Flowchart of subroutine S09 (Link 2)

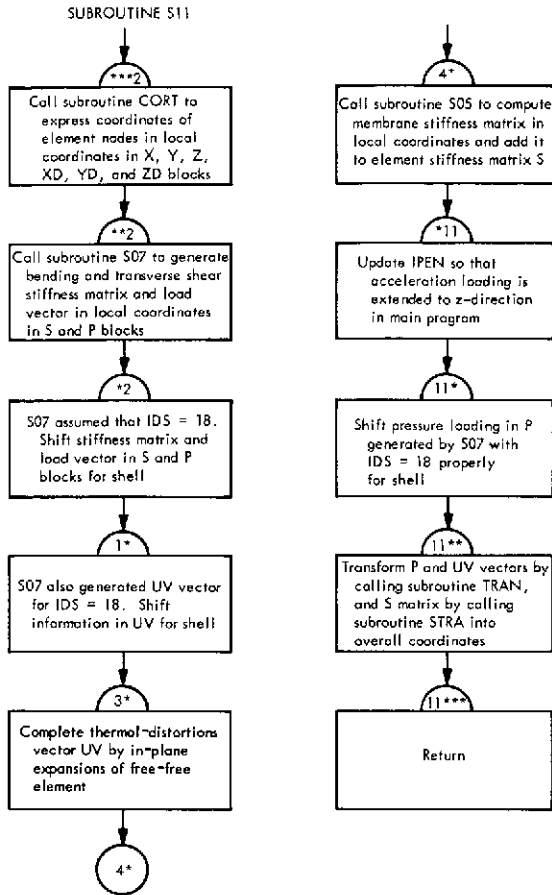


Fig. VI-31. Flowchart of subroutine S11 (Link 2)

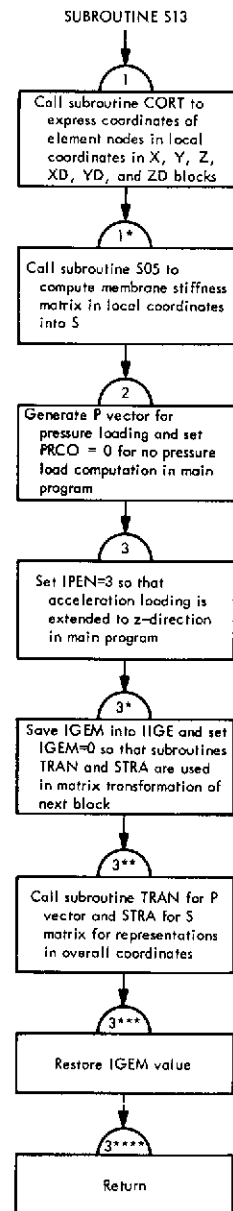


Fig. VI-32. Flowchart of subroutine S13 (Link 2)

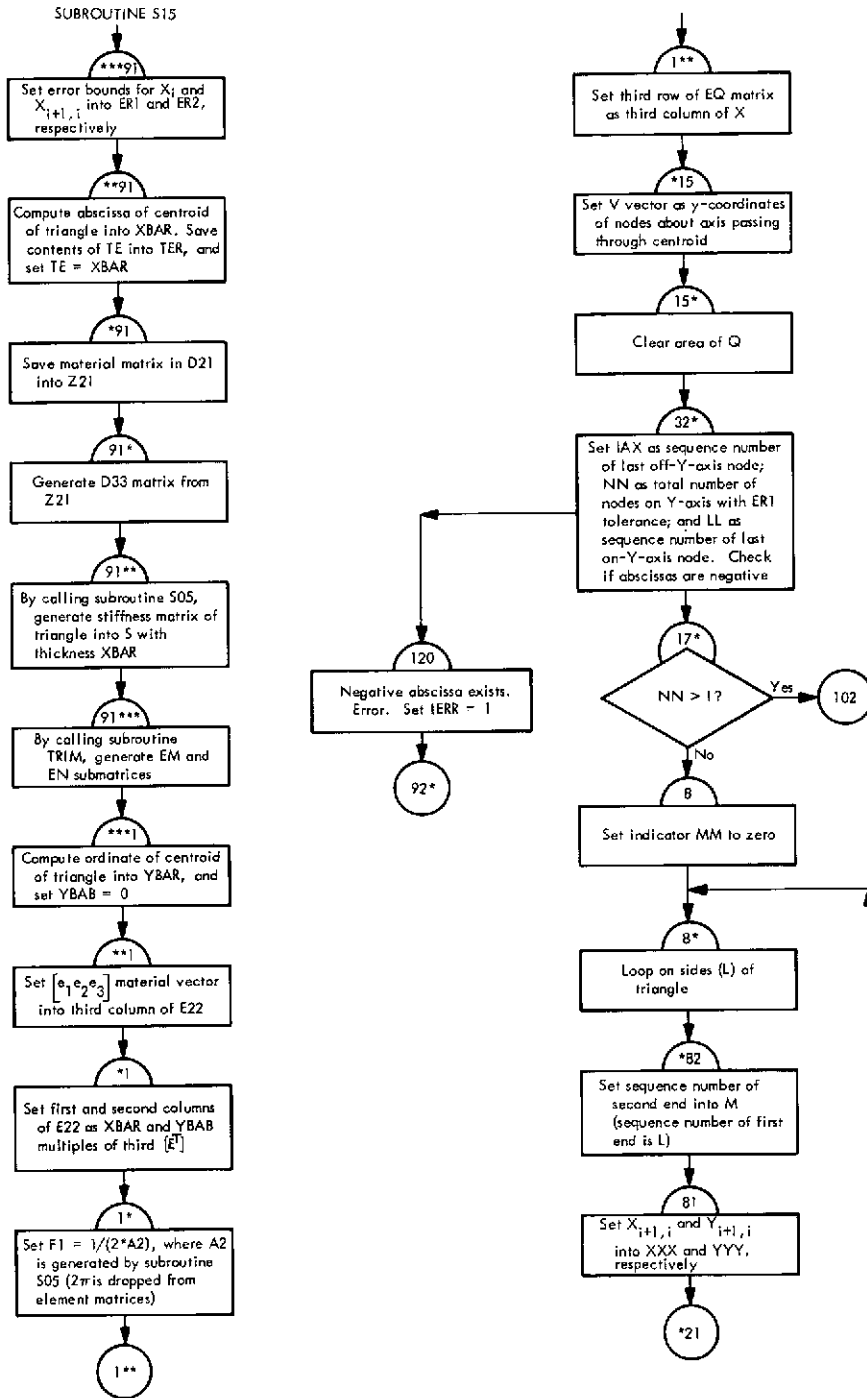


Fig. VI-33. Flowchart of subroutine S15 (Link 2)

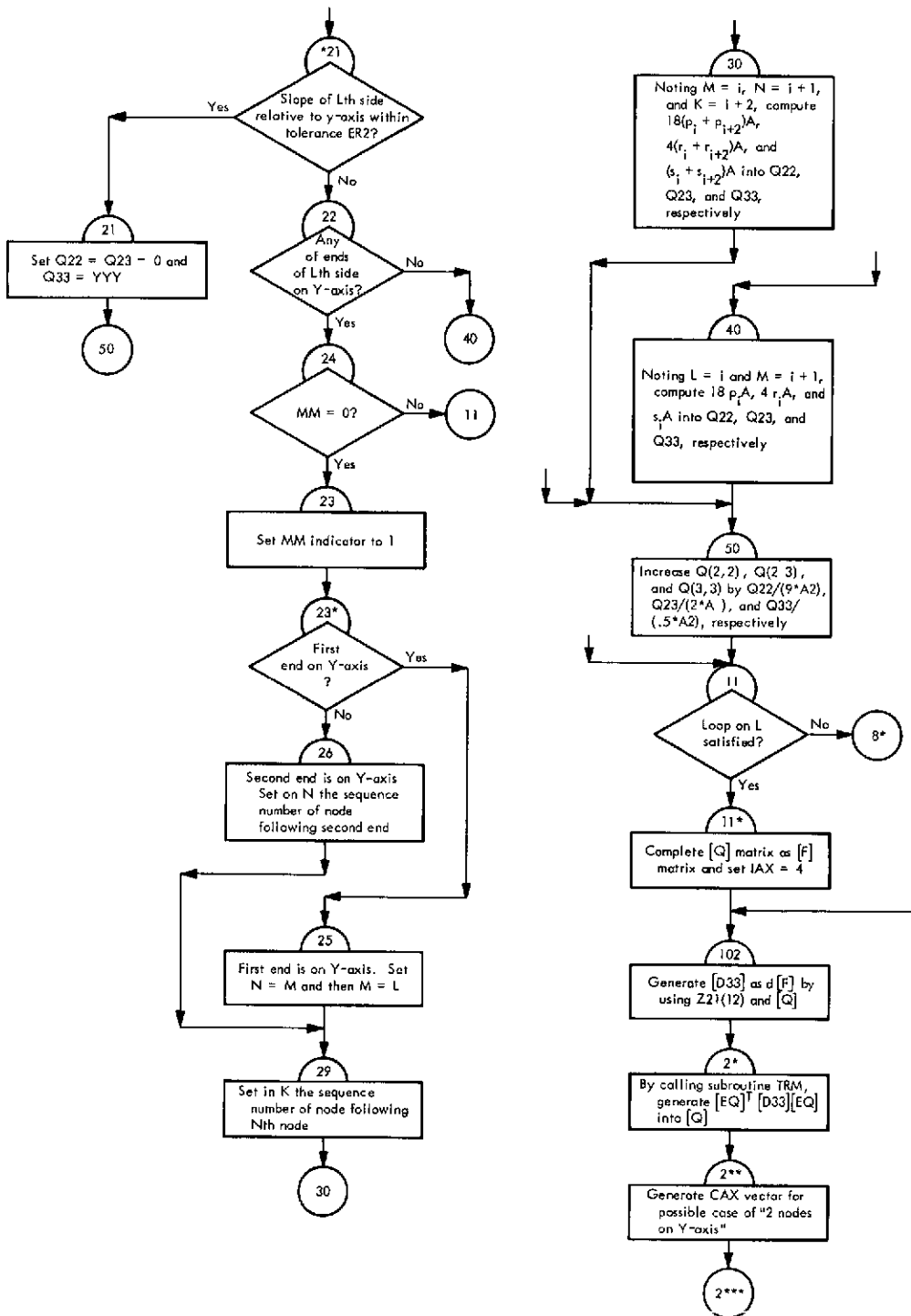


Fig. VI-33 (contd)

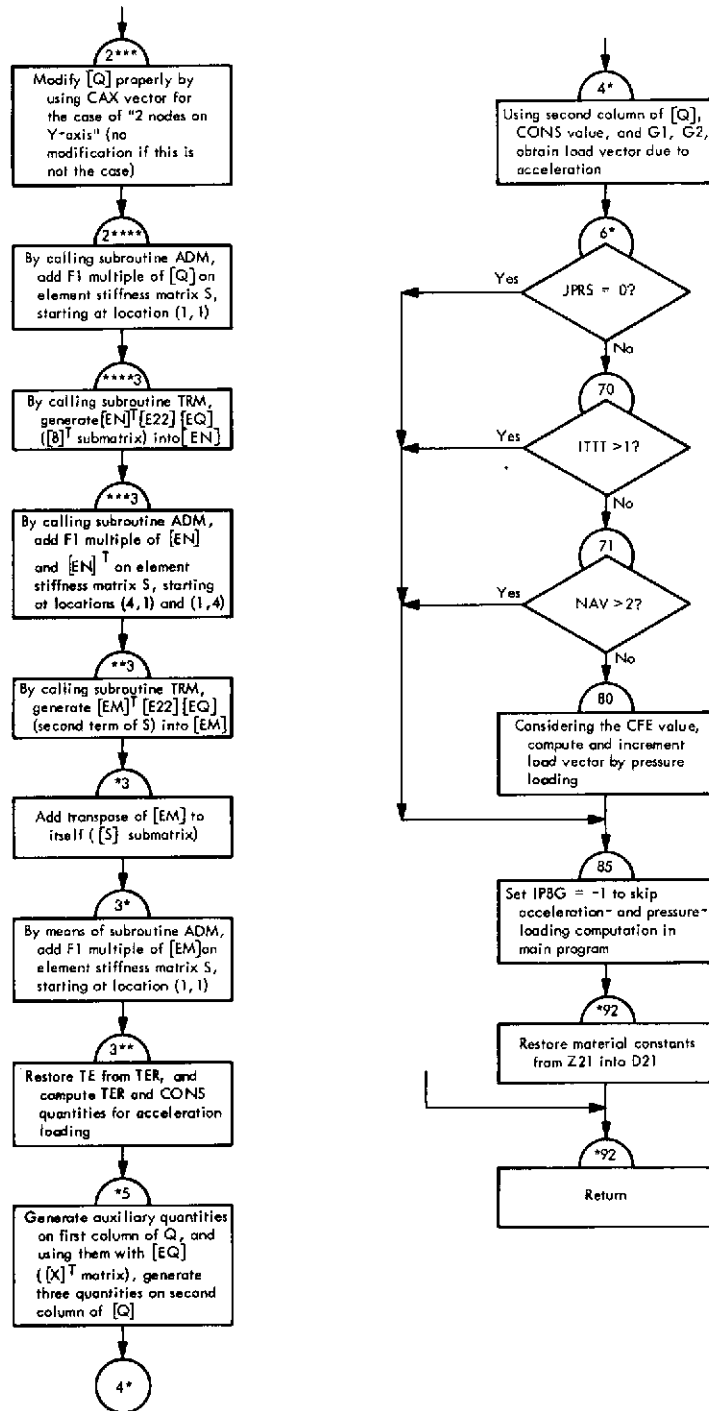


Fig. VI-33 (contd)

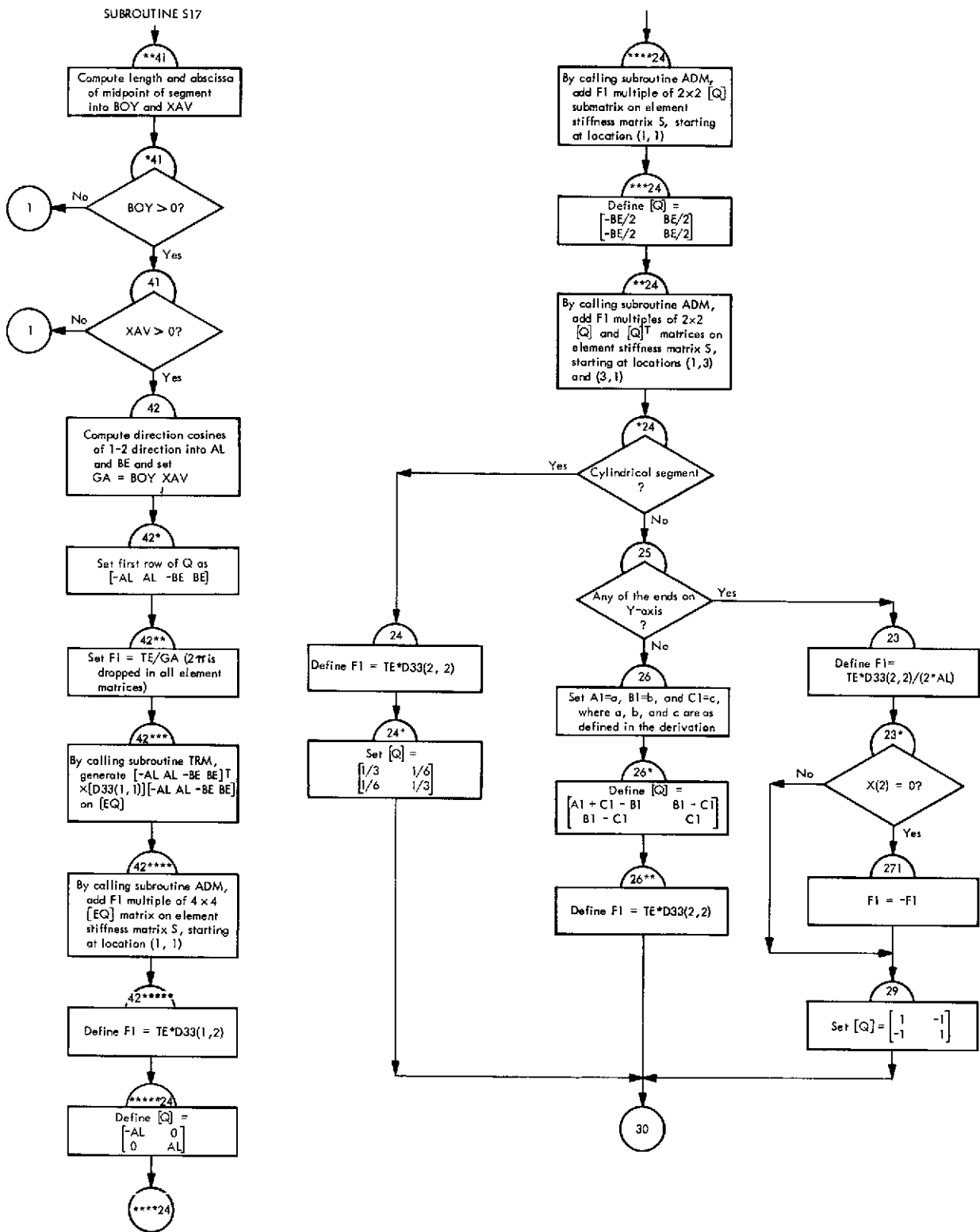


Fig. VI-34. Flowchart of subroutine S17 (Link 2)

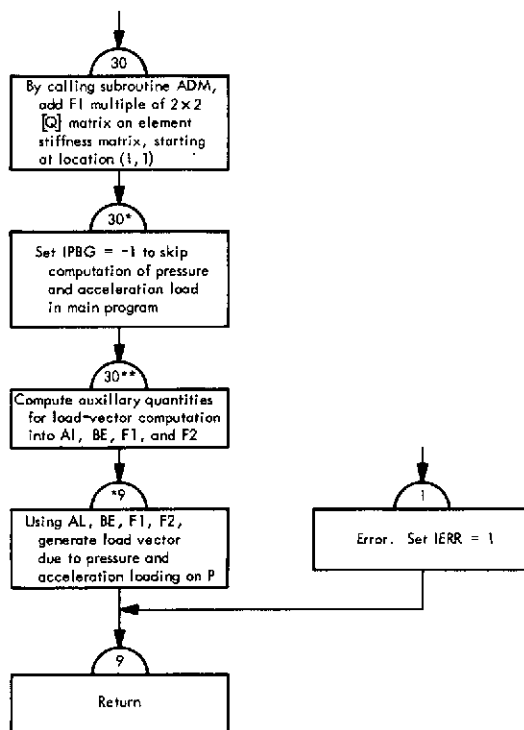


Fig. VI-34 (contd)

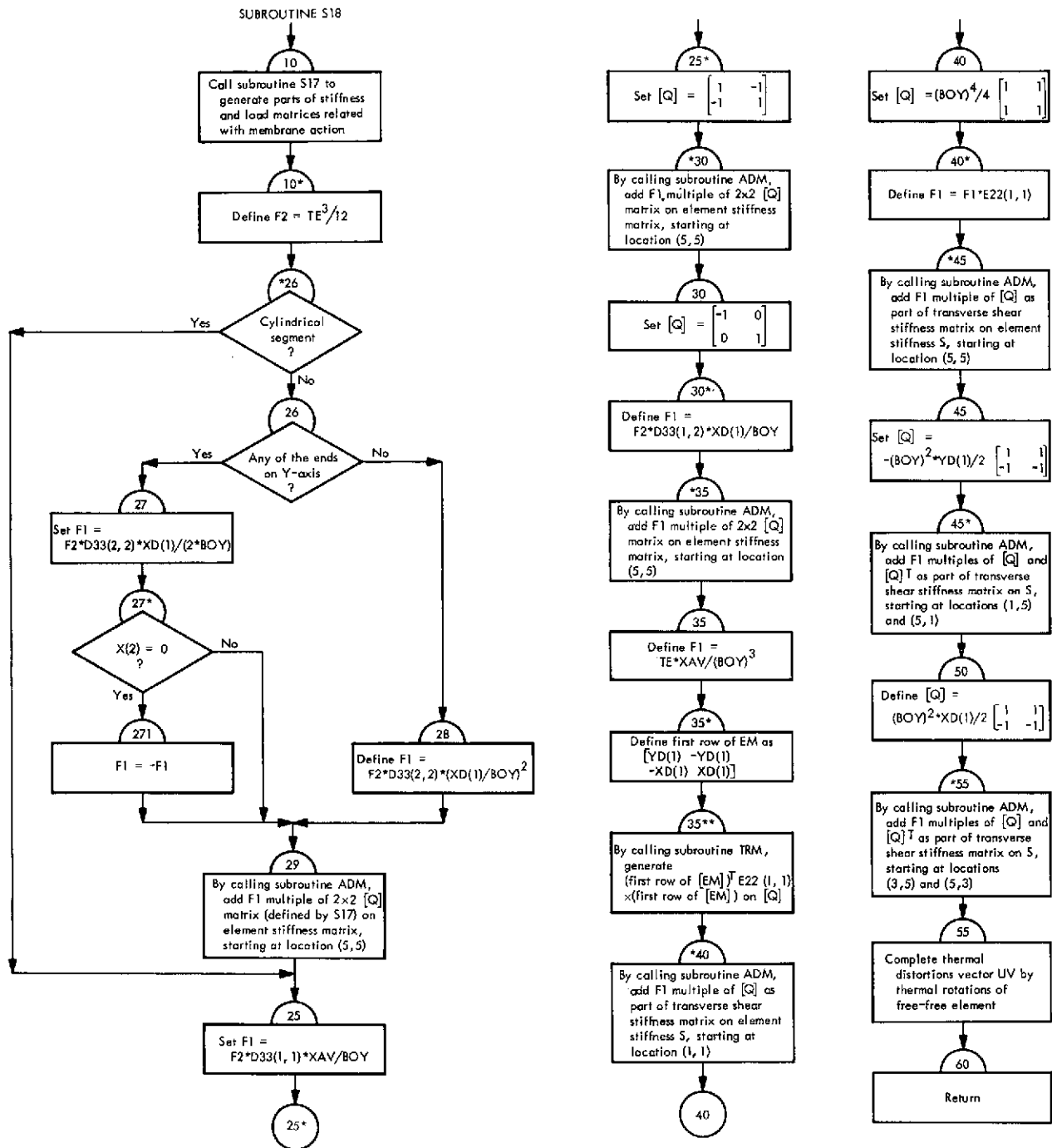


Fig. VI-35. Flowchart of subroutine S18 (Link 2)

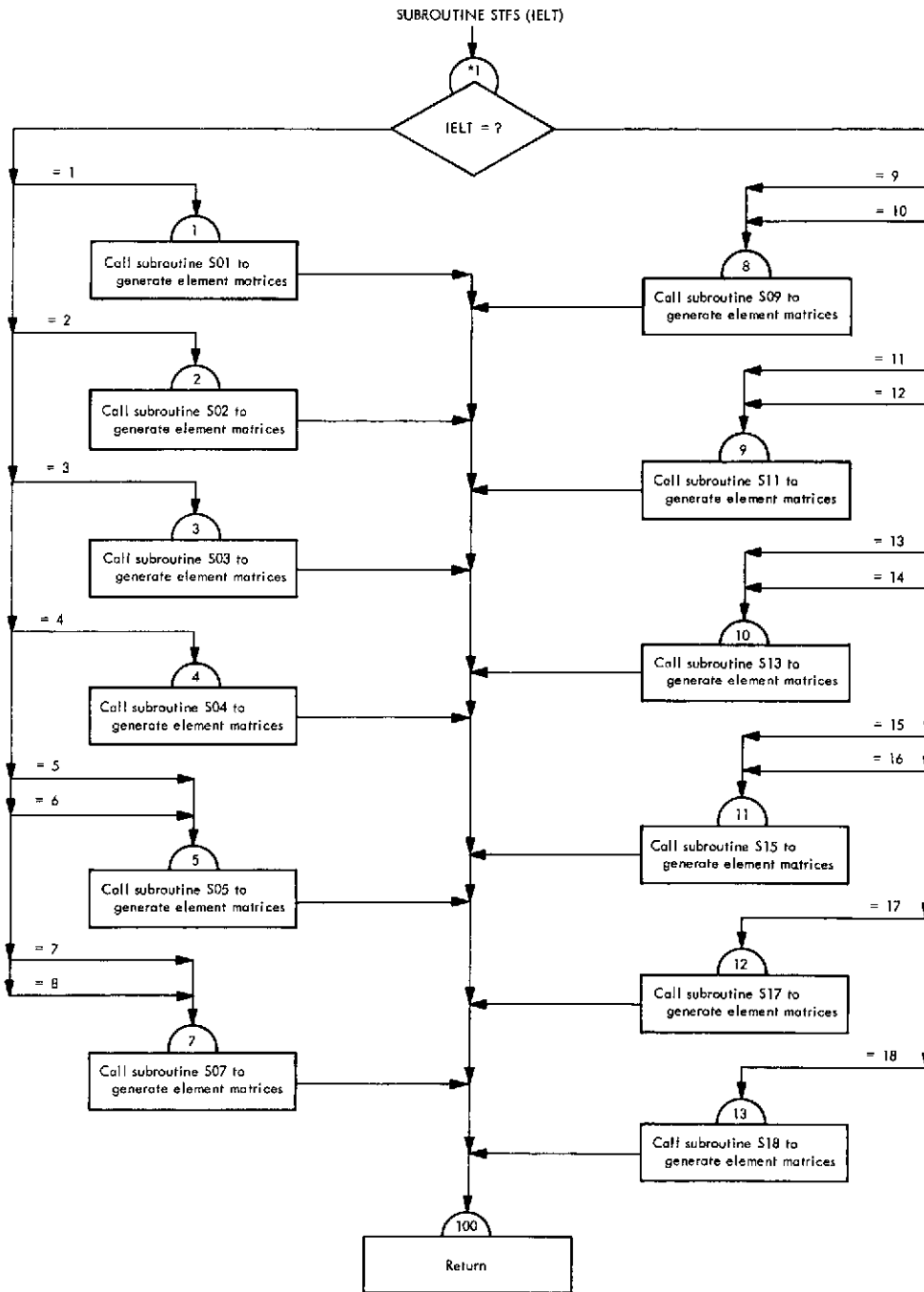


Fig. VI-36. Flowchart of subroutine STFS (Link 2)

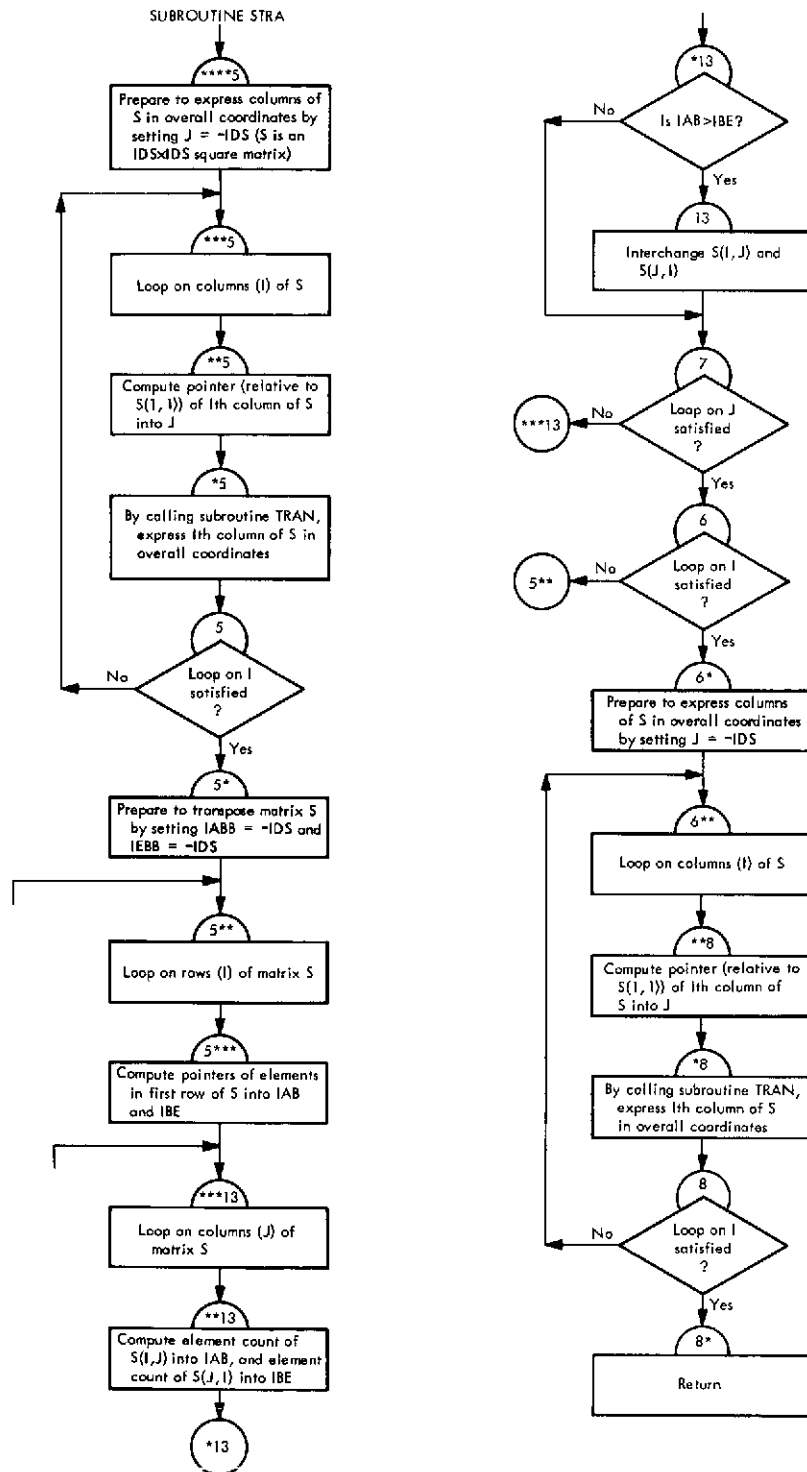


Fig. VI-37. Flowchart of subroutine STRA (Link 2)

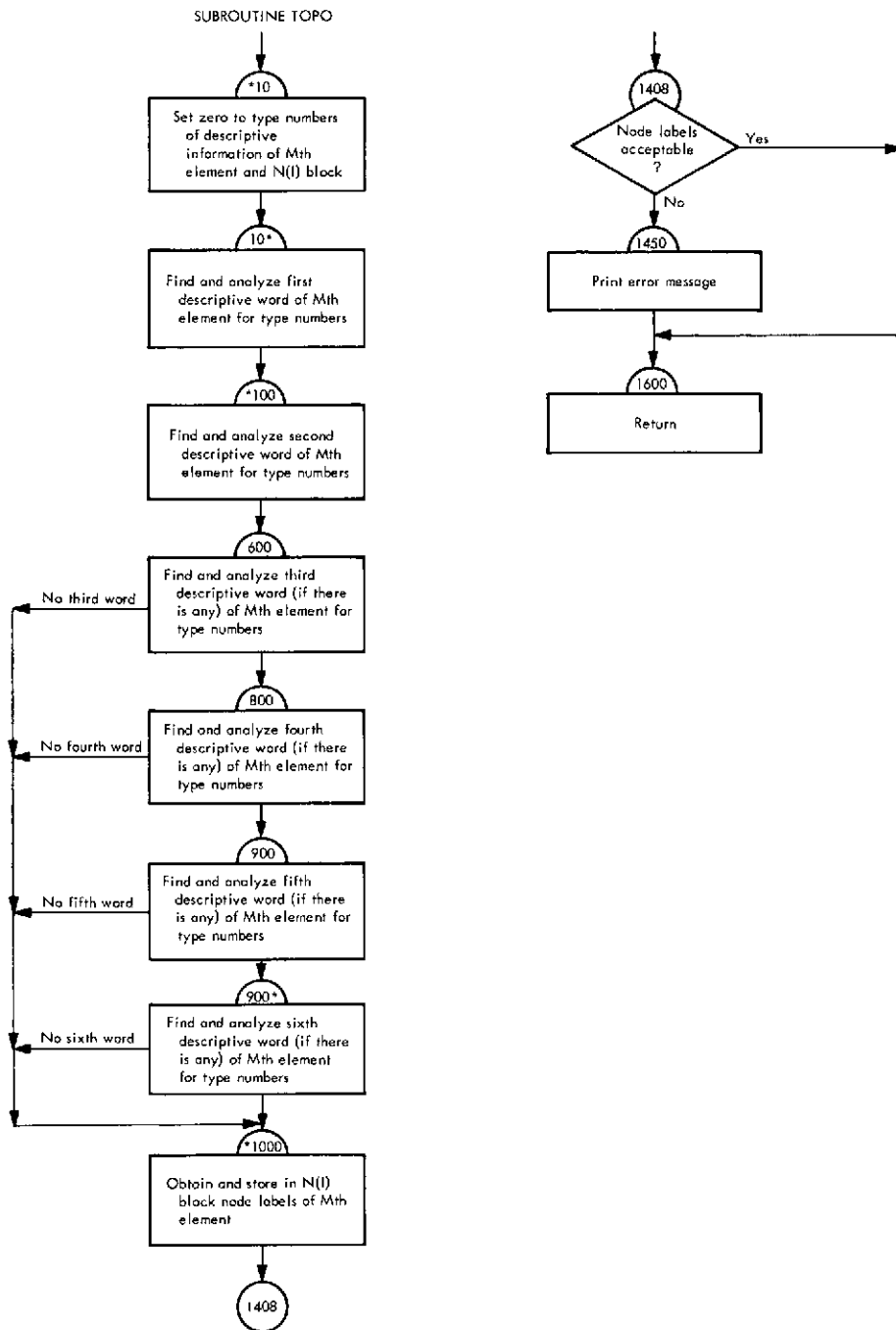


Fig. VI-38. Flowchart of subroutine TOPO (Link 2)

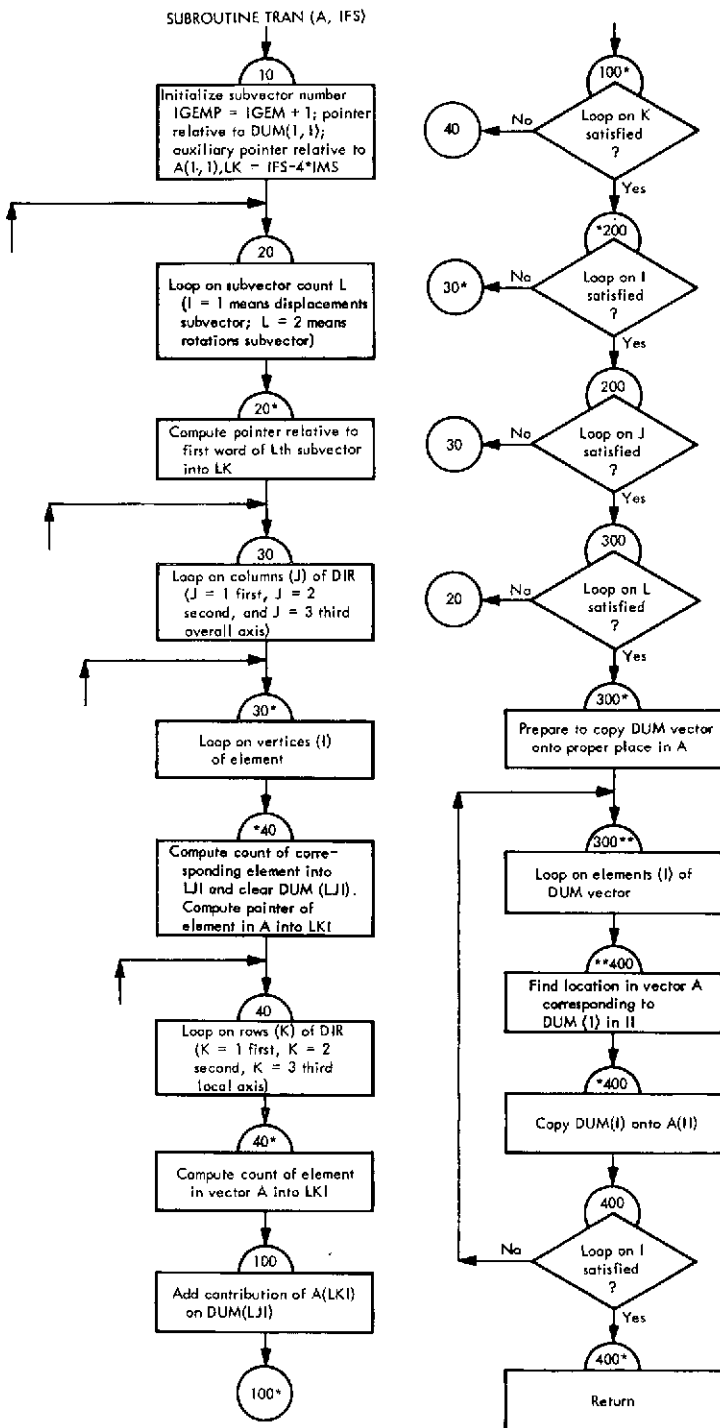


Fig. VI-39. Flowchart of subroutine TRAN (Link 2)

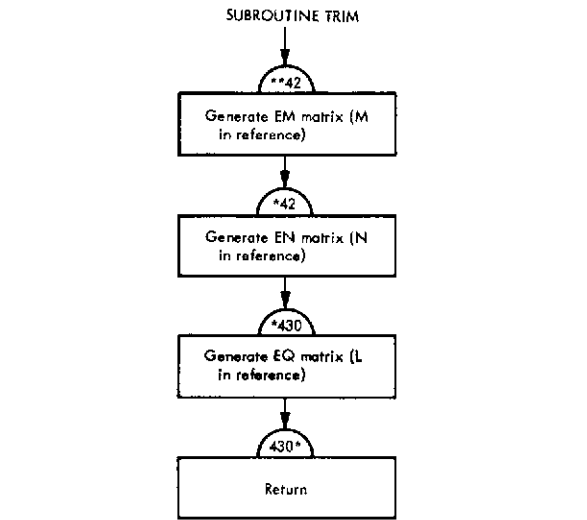


Fig. VI-40. Flowchart of subroutine TRIM (Link 2)

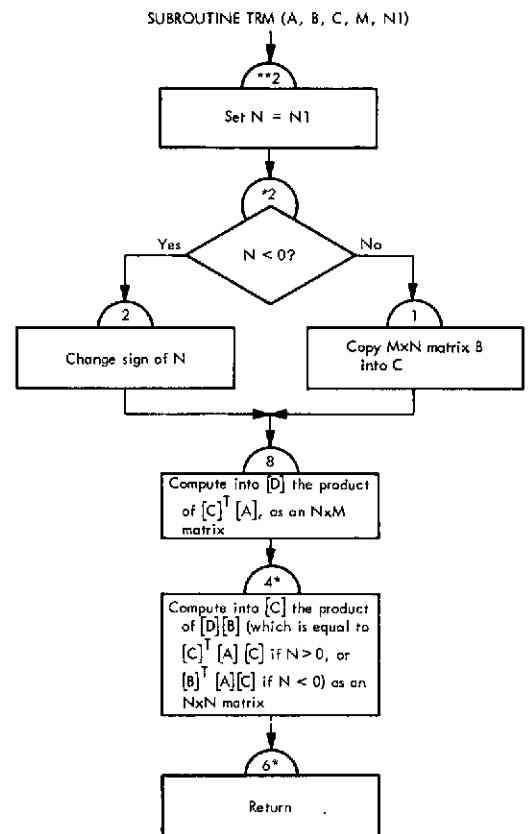


Fig. VI-41. Flowchart of subroutine TRM (Link 2)

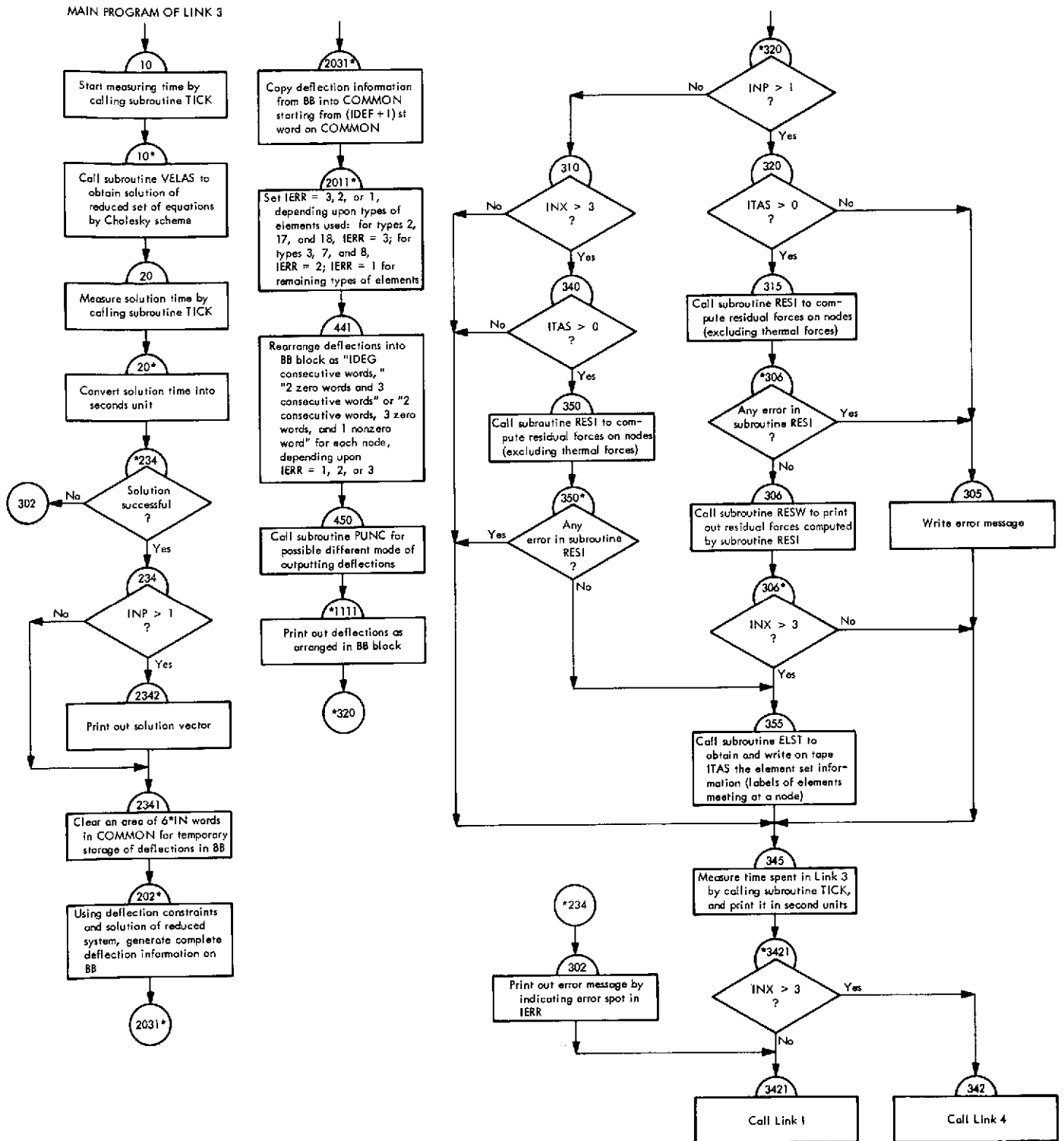


Fig. VI-42. Flowchart of main program of Link 3 (deflection link)

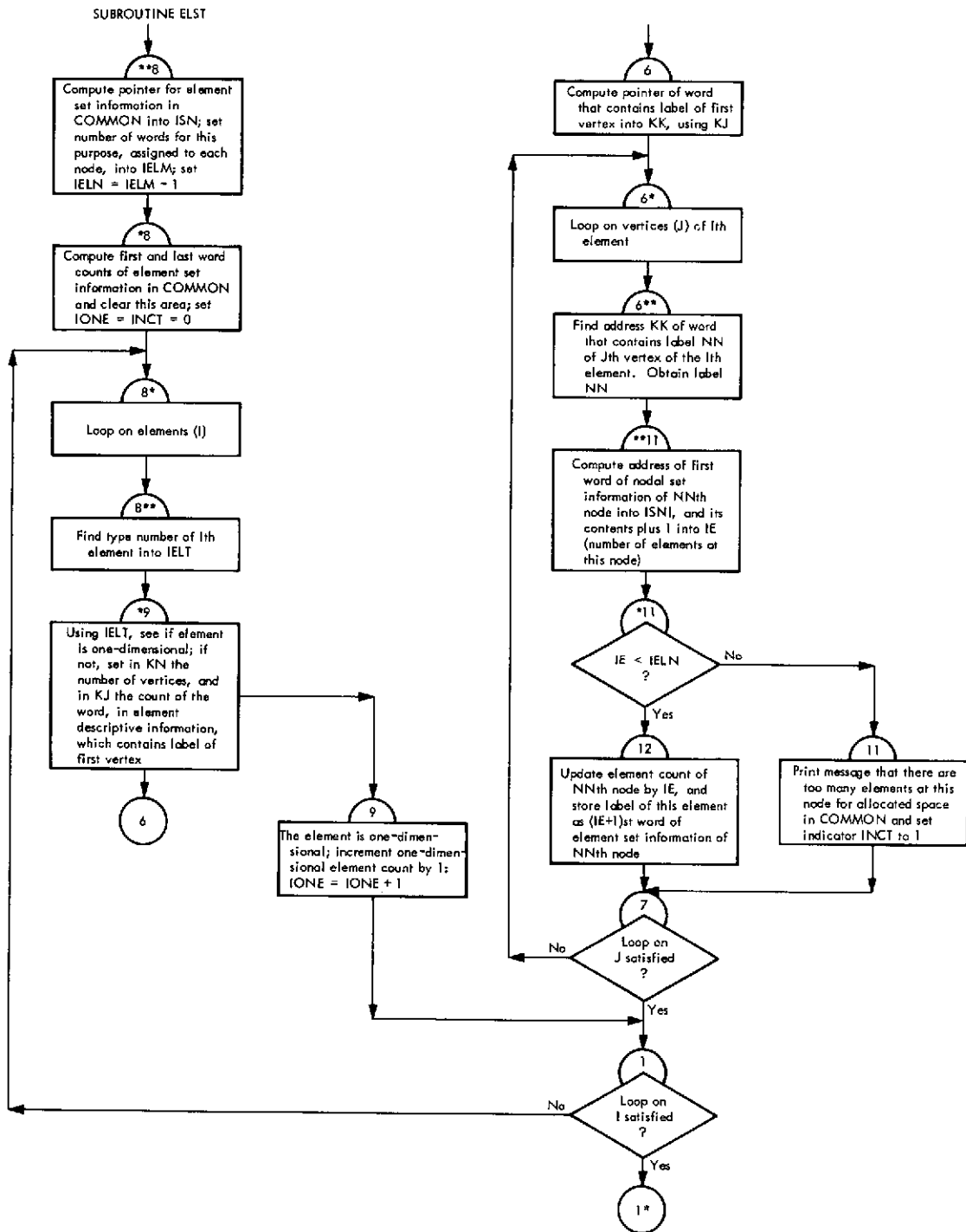


Fig. VI-43. Flowchart of subroutine ELST (Link 3)

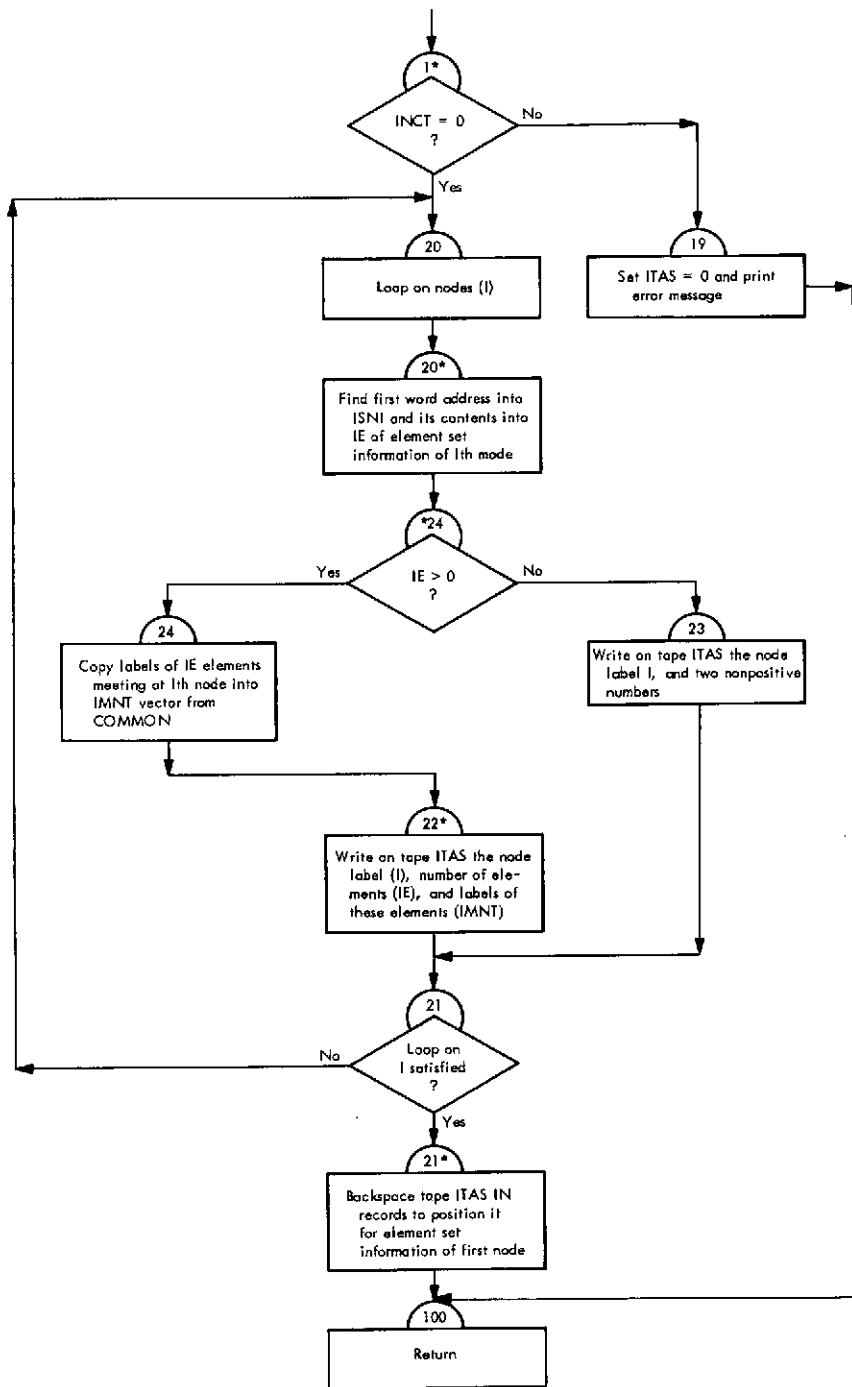


Fig. VI-43 (contd)

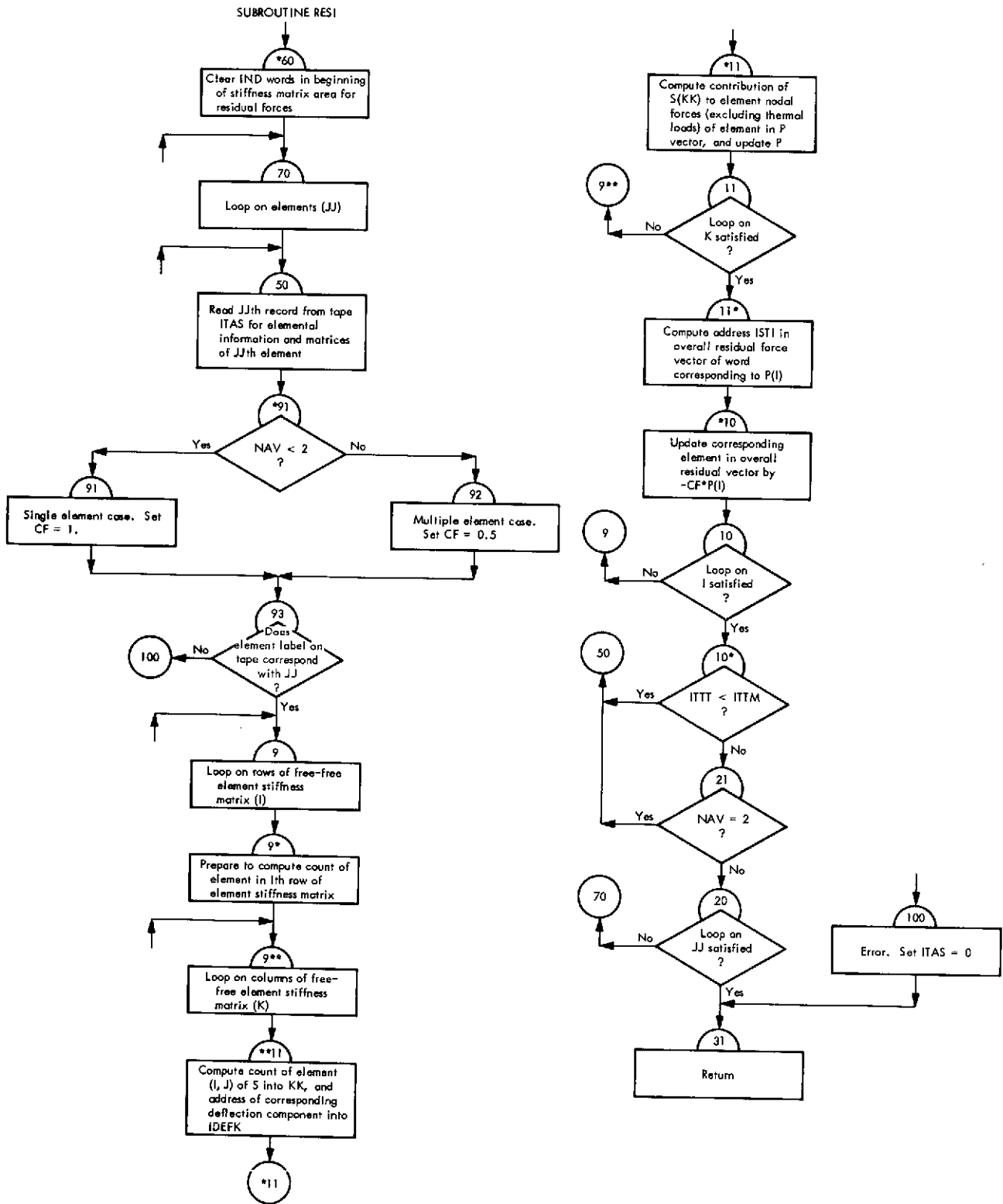


Fig. VI-44. Flowchart of subroutine RESI (Link 3)

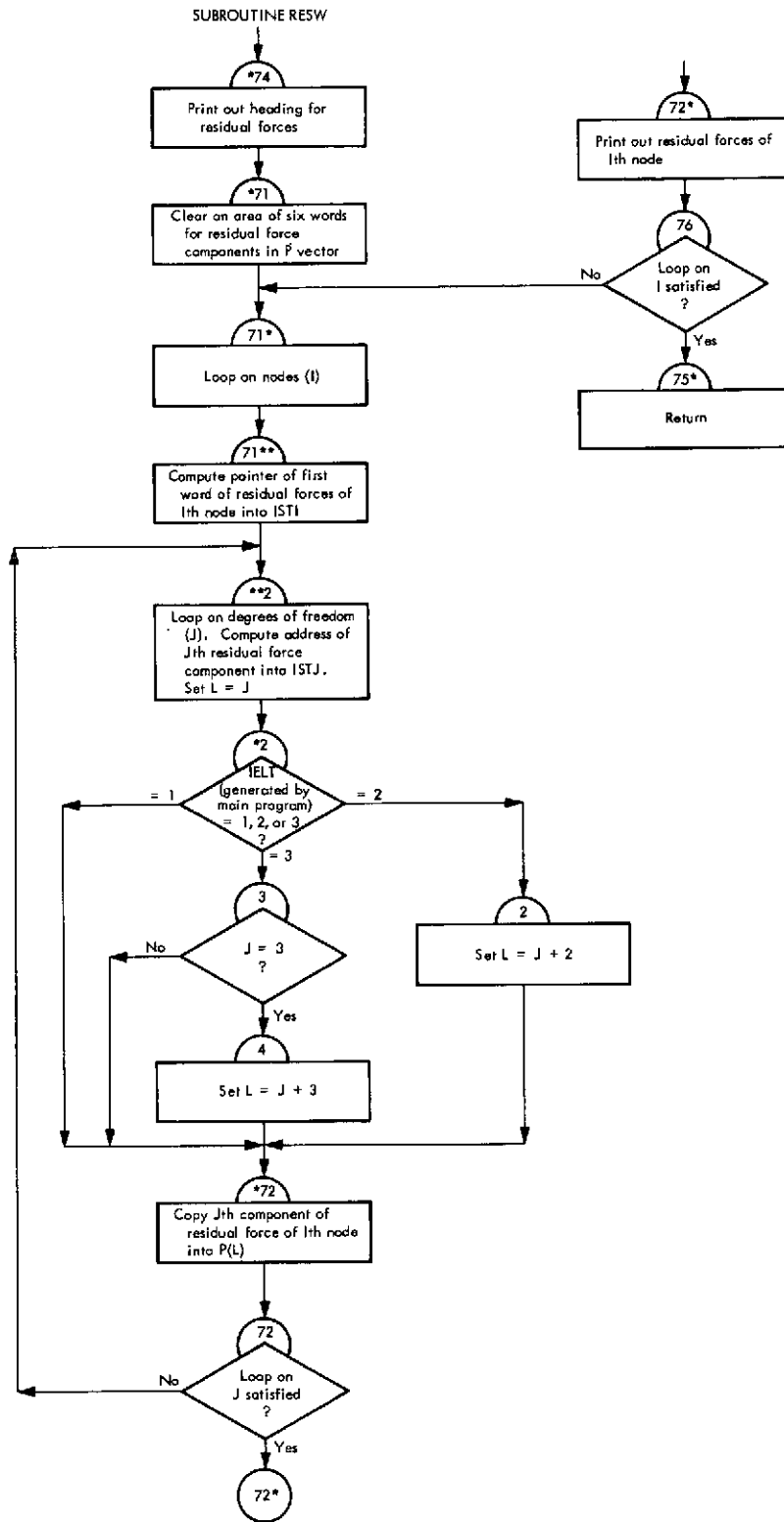


Fig. VI-45. Flowchart of subroutine RESW (Link 3)

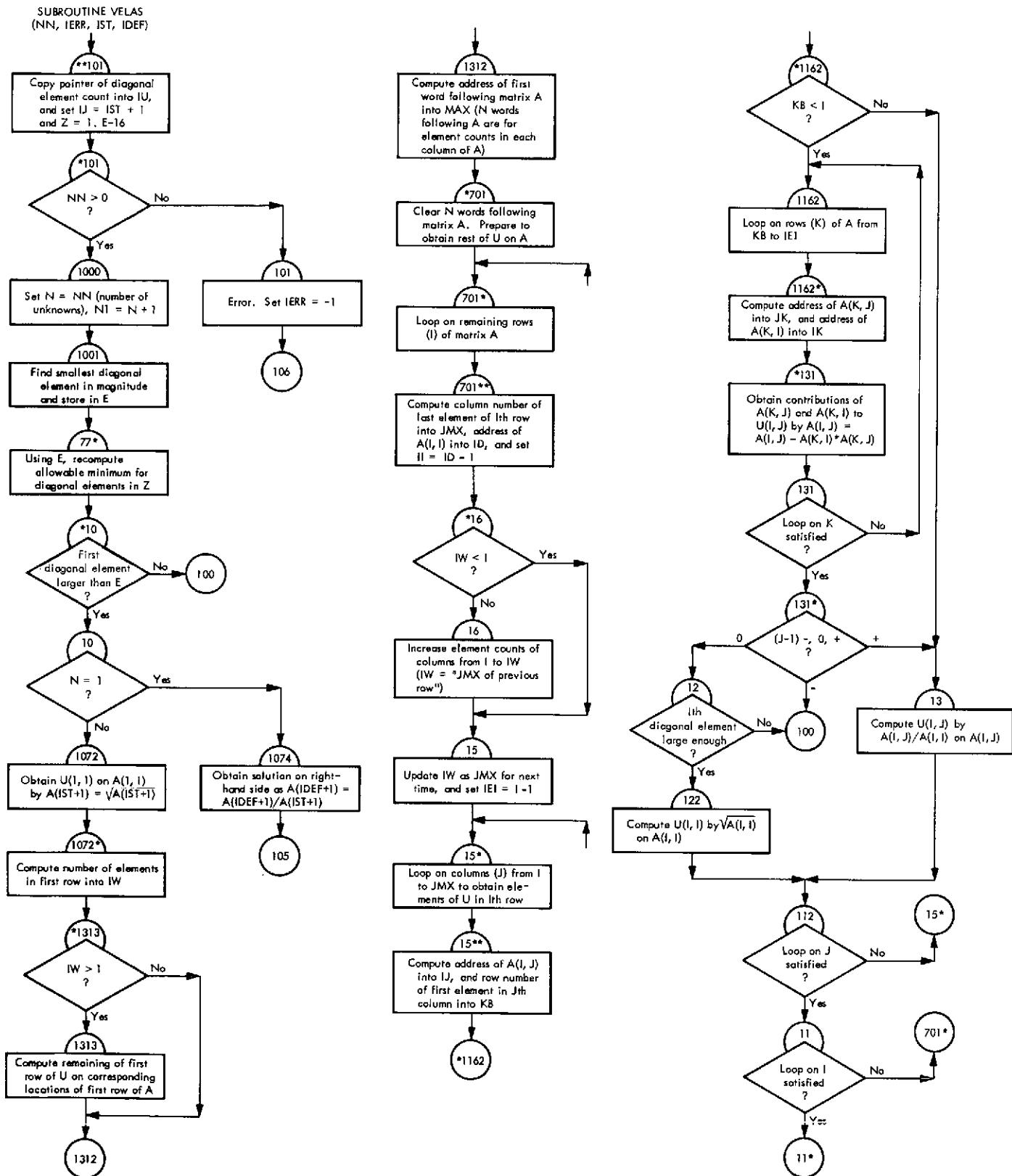


Fig. VI-46. Flowchart of subroutine VELAS (Link 3)

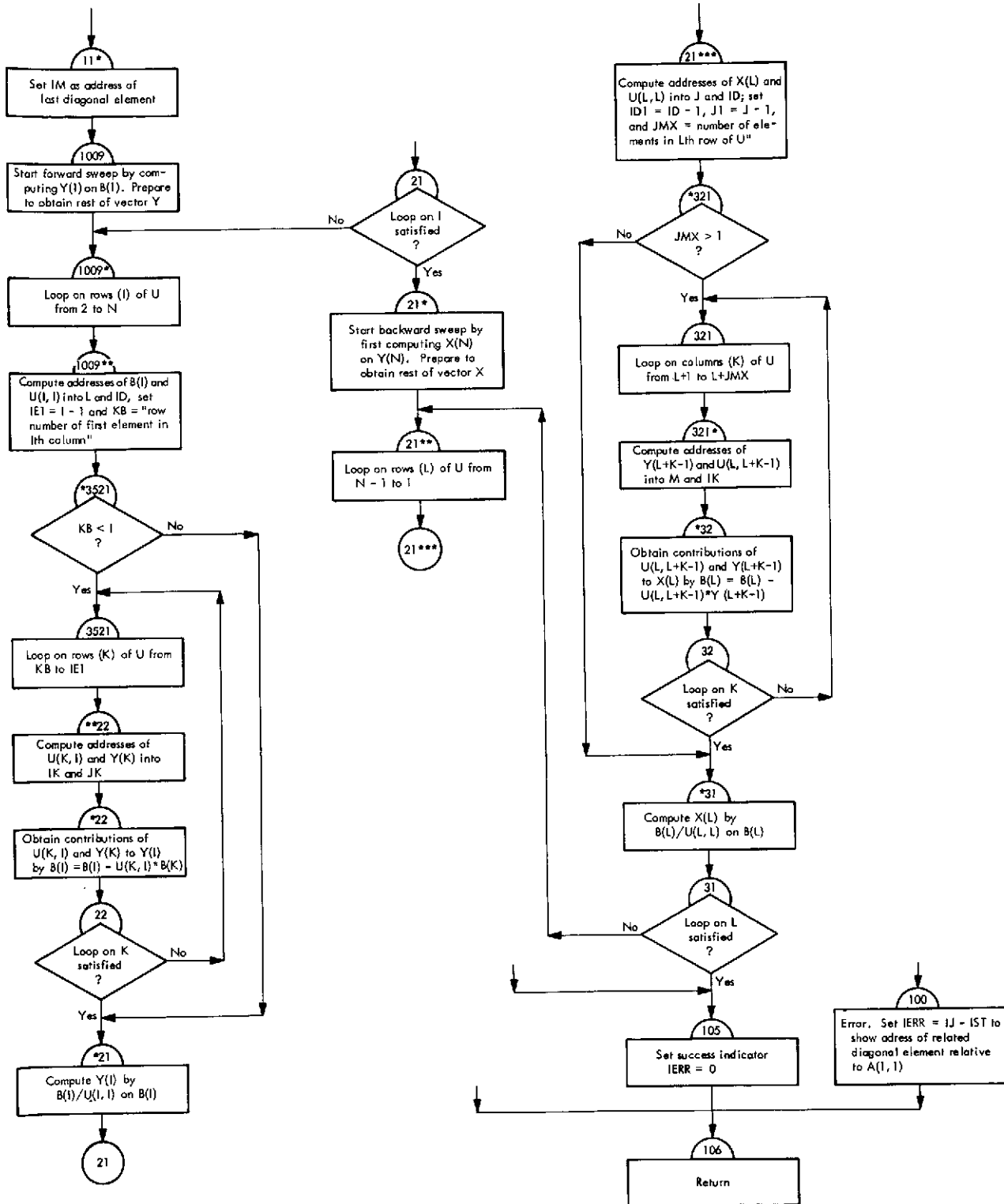


Fig. VI-46 (contd)

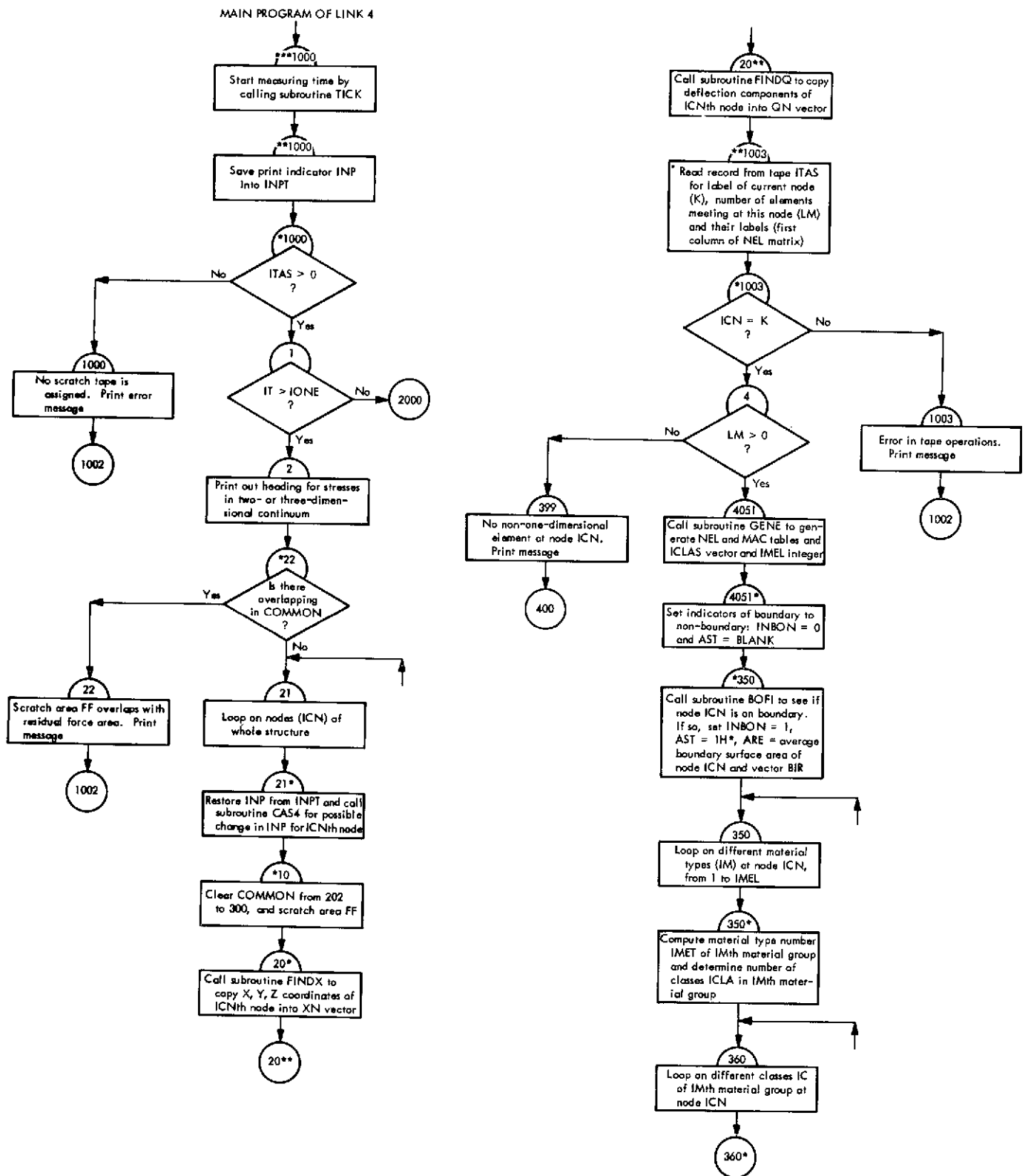


Fig. VI-47. Flowchart of main program of Link 4 (stress link)

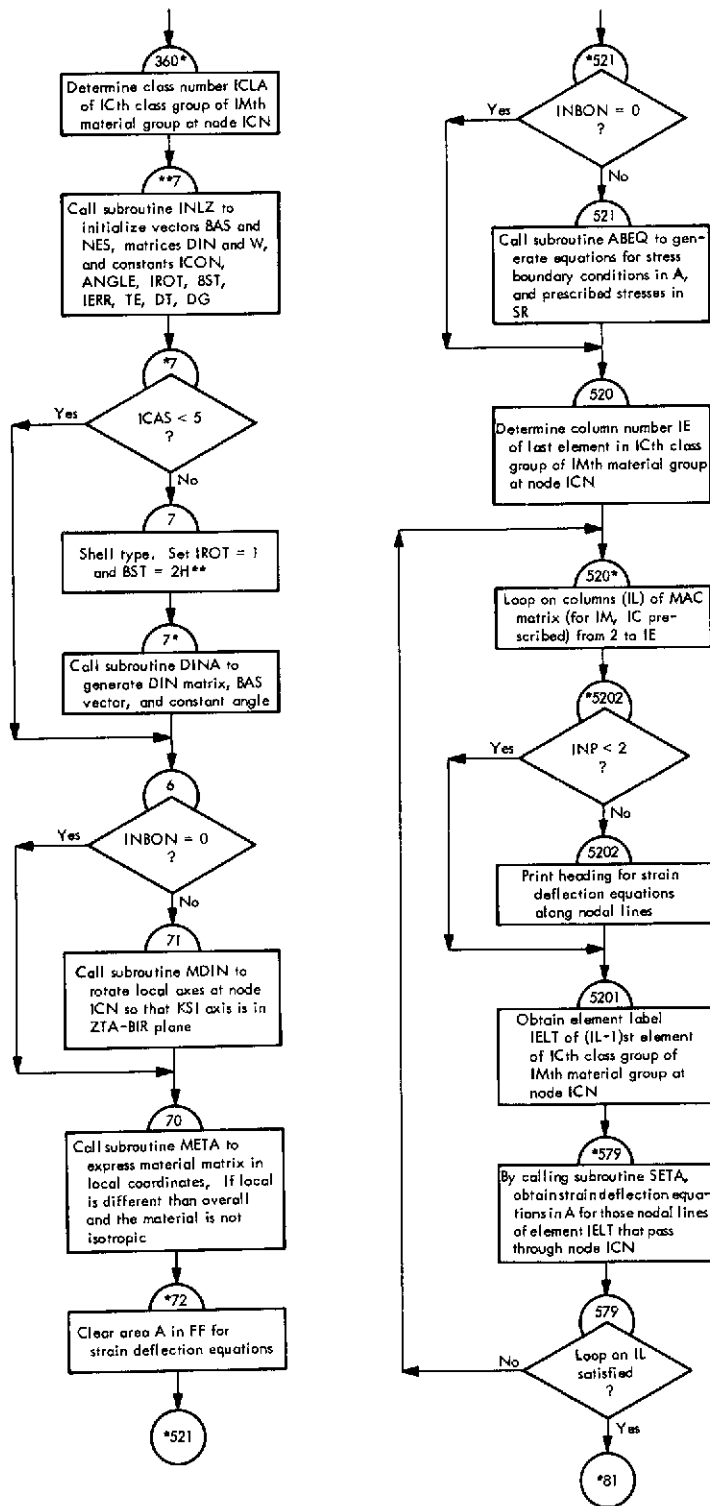


Fig. VI-47 (contd)

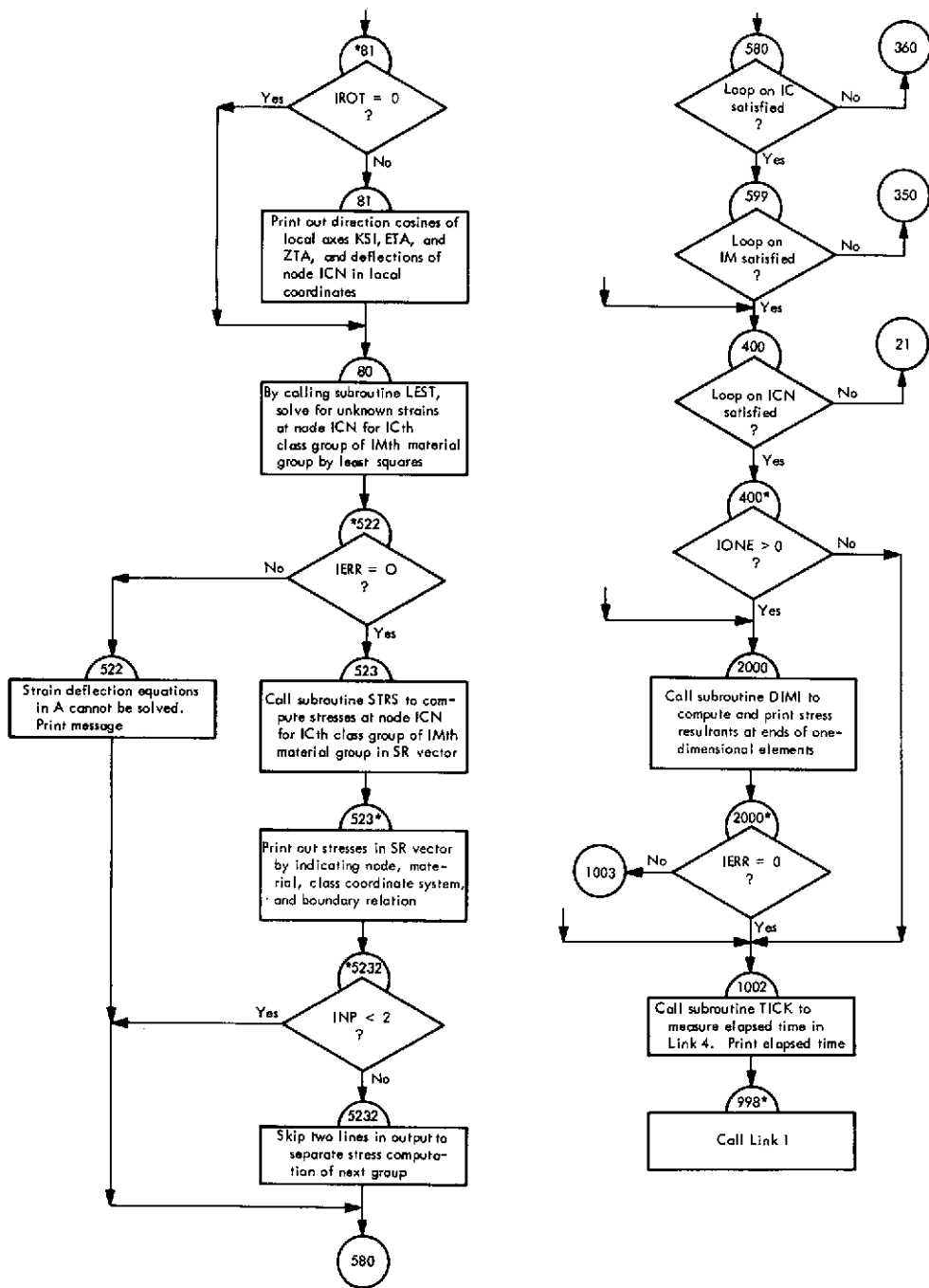


Fig. VI-47 (contd)

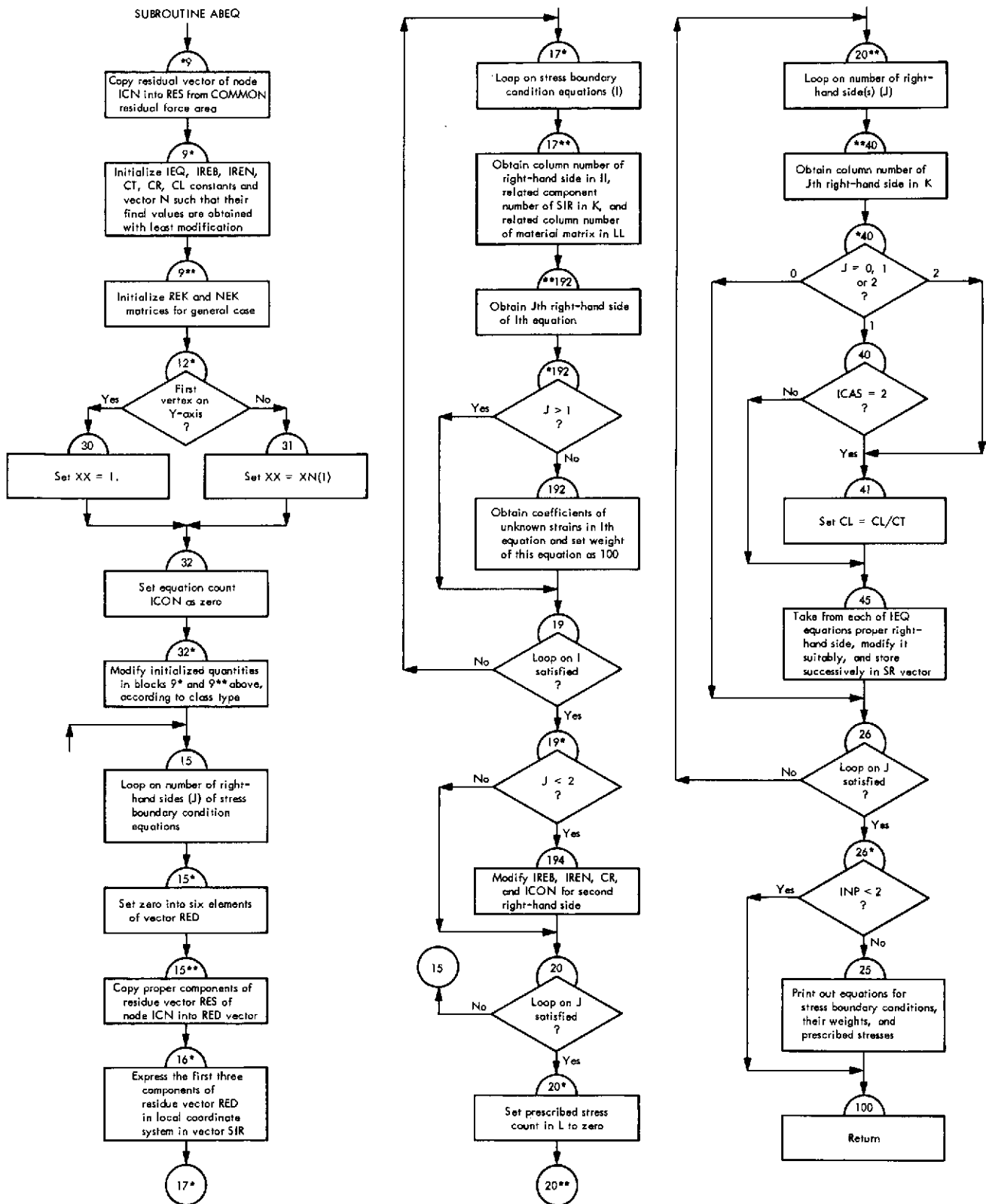


Fig. VI-48. Flowchart of subroutine ABEQ (Link 4)

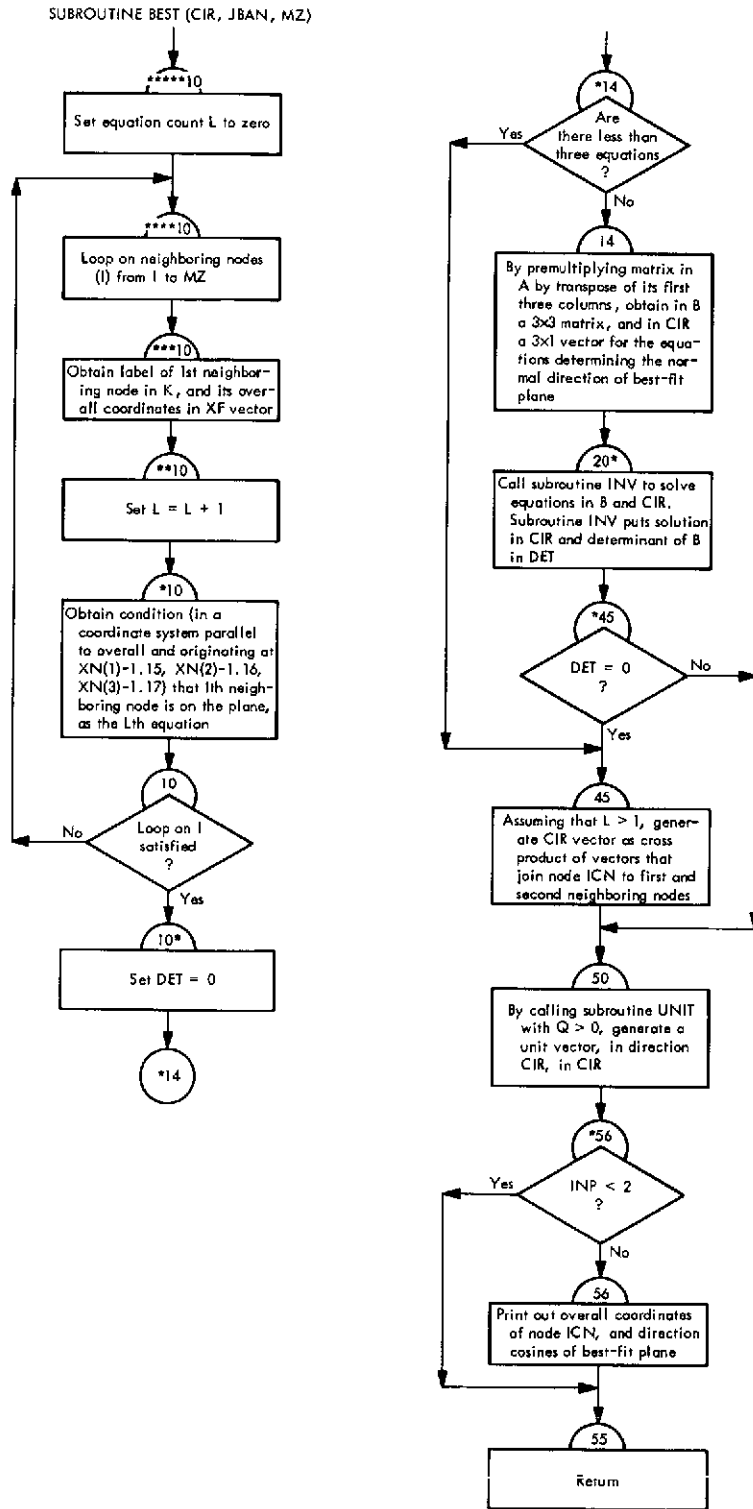


Fig. VI-49. Flowchart of subroutine BEST (Link 4)

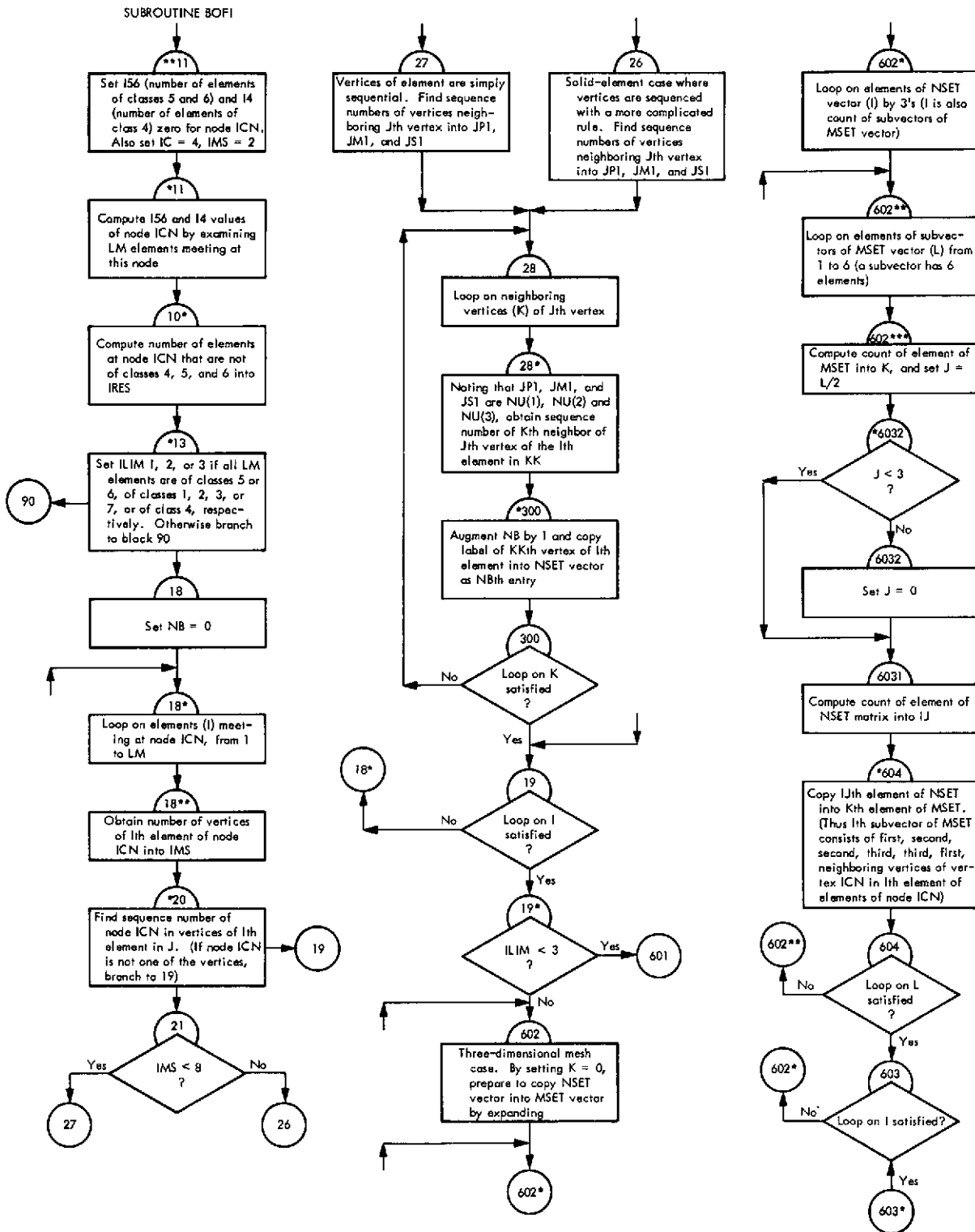


Fig. VI-50. Flowchart of subroutine BOFI (Link 4)

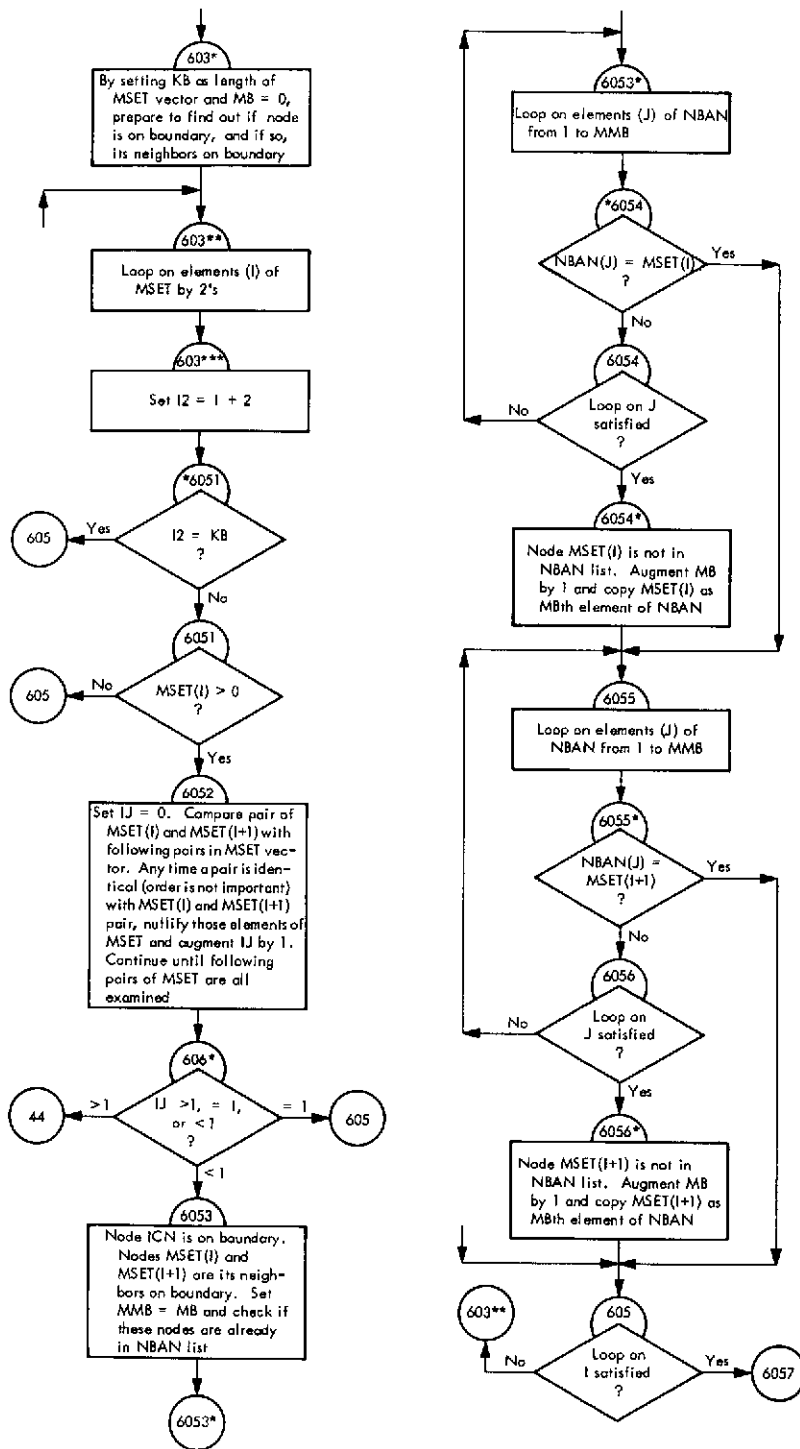


Fig. Vi-50 (conid)

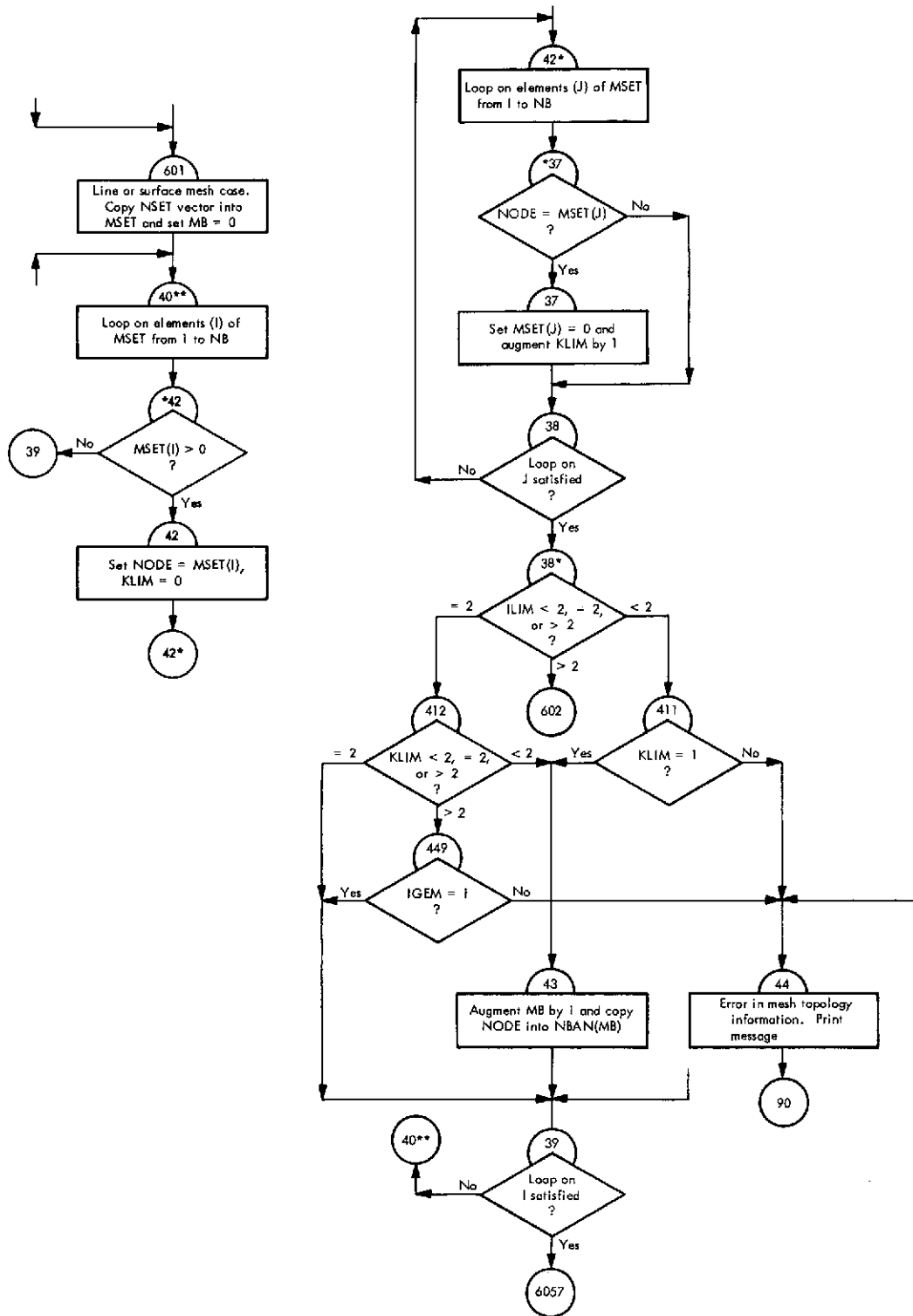


Fig. VI-50 (contd)

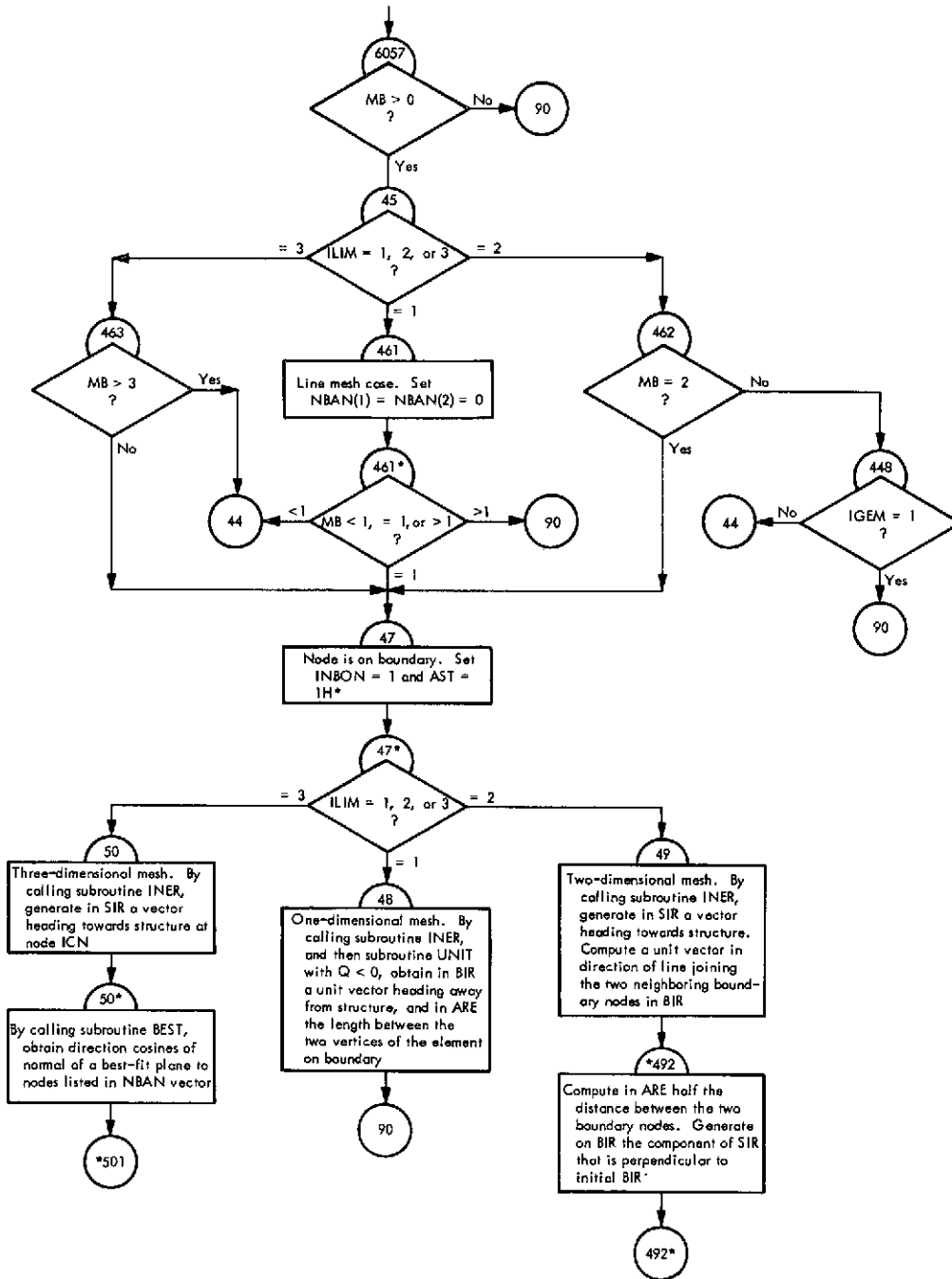


Fig. VI-50 (contd)

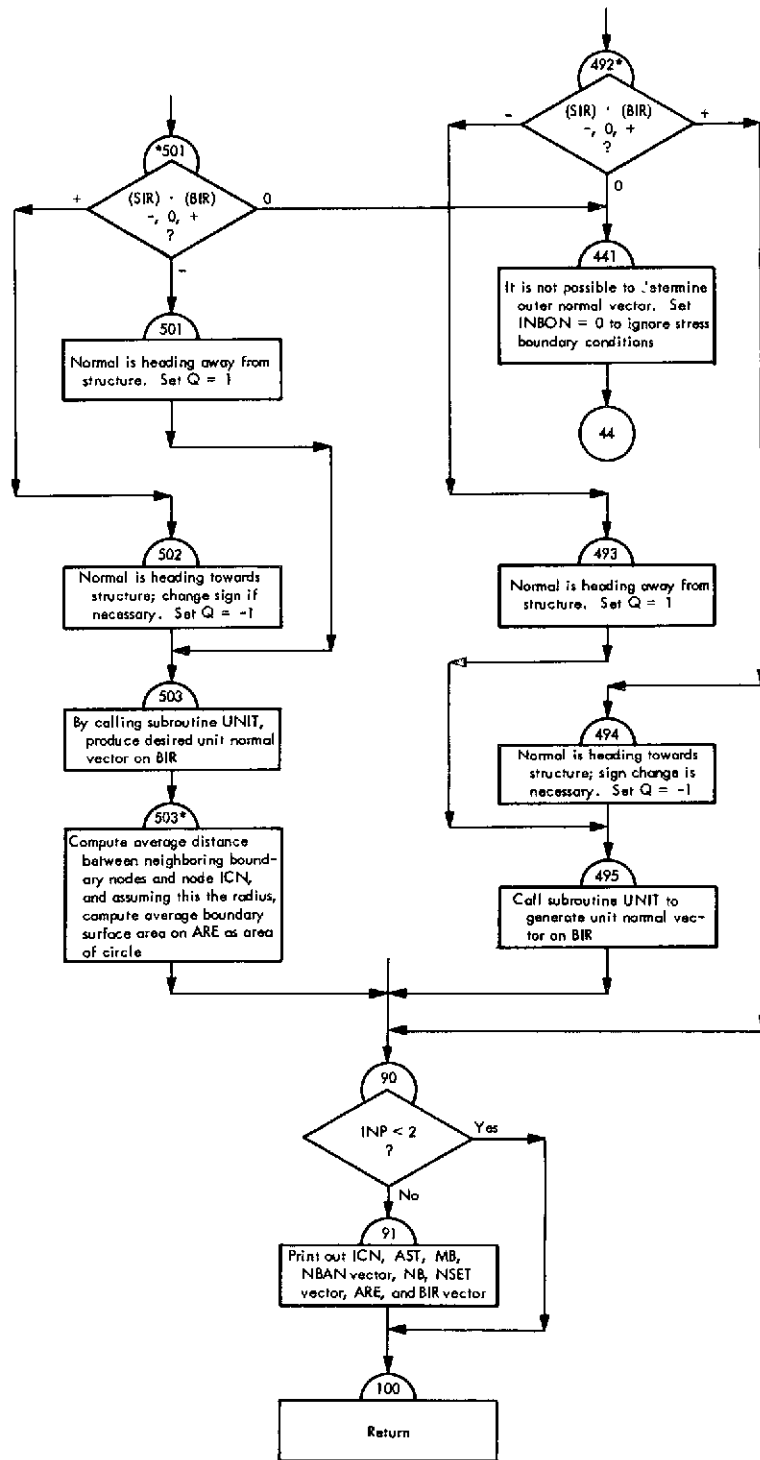


Fig. VI-50 (contd)

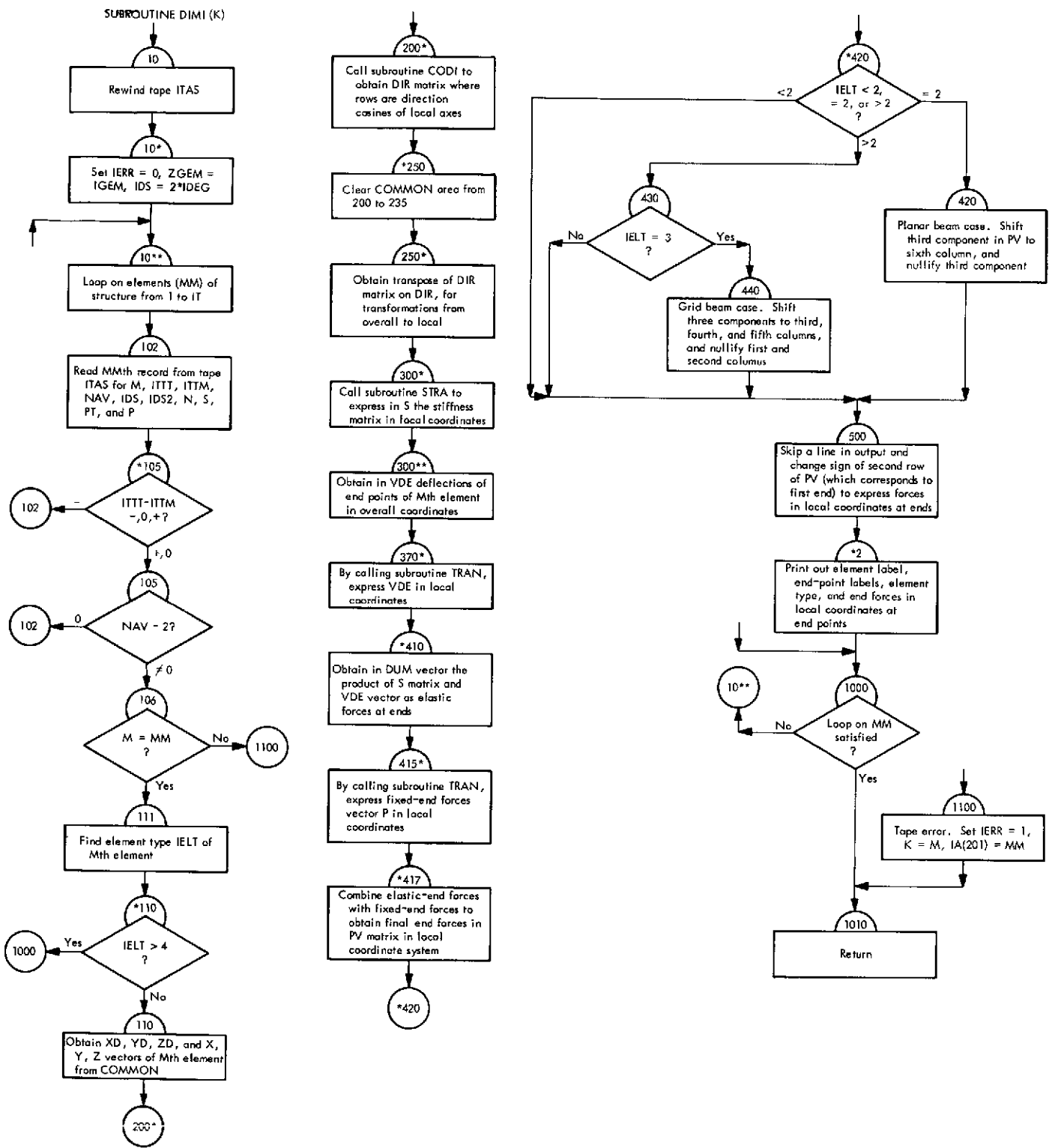


Fig. VI-51. Flowchart of subroutine DIMI (Link 4)

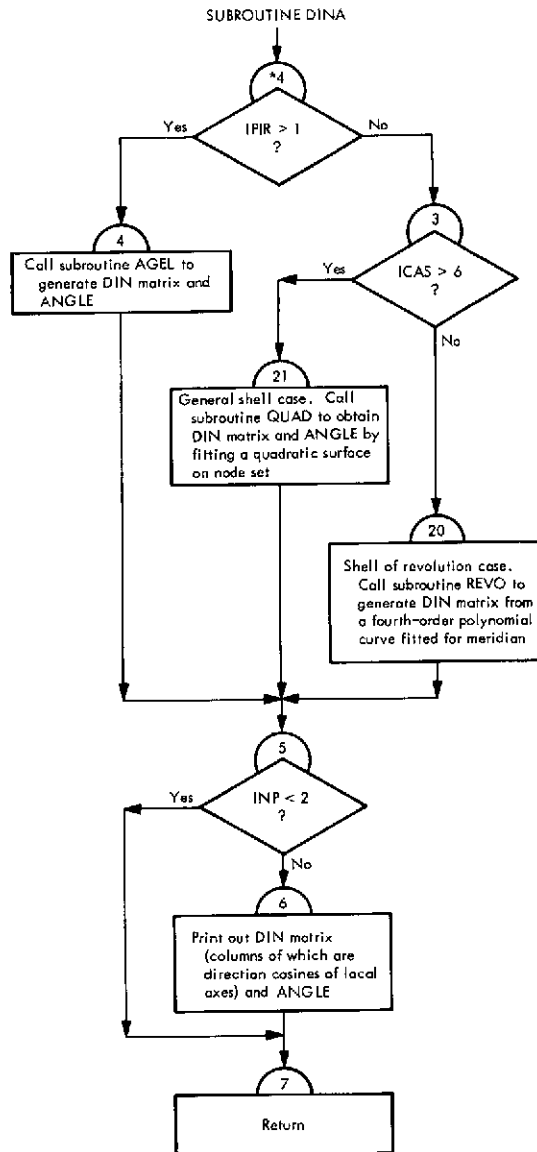


Fig. VI-52. Flowchart of subroutine DINA (Link 4)

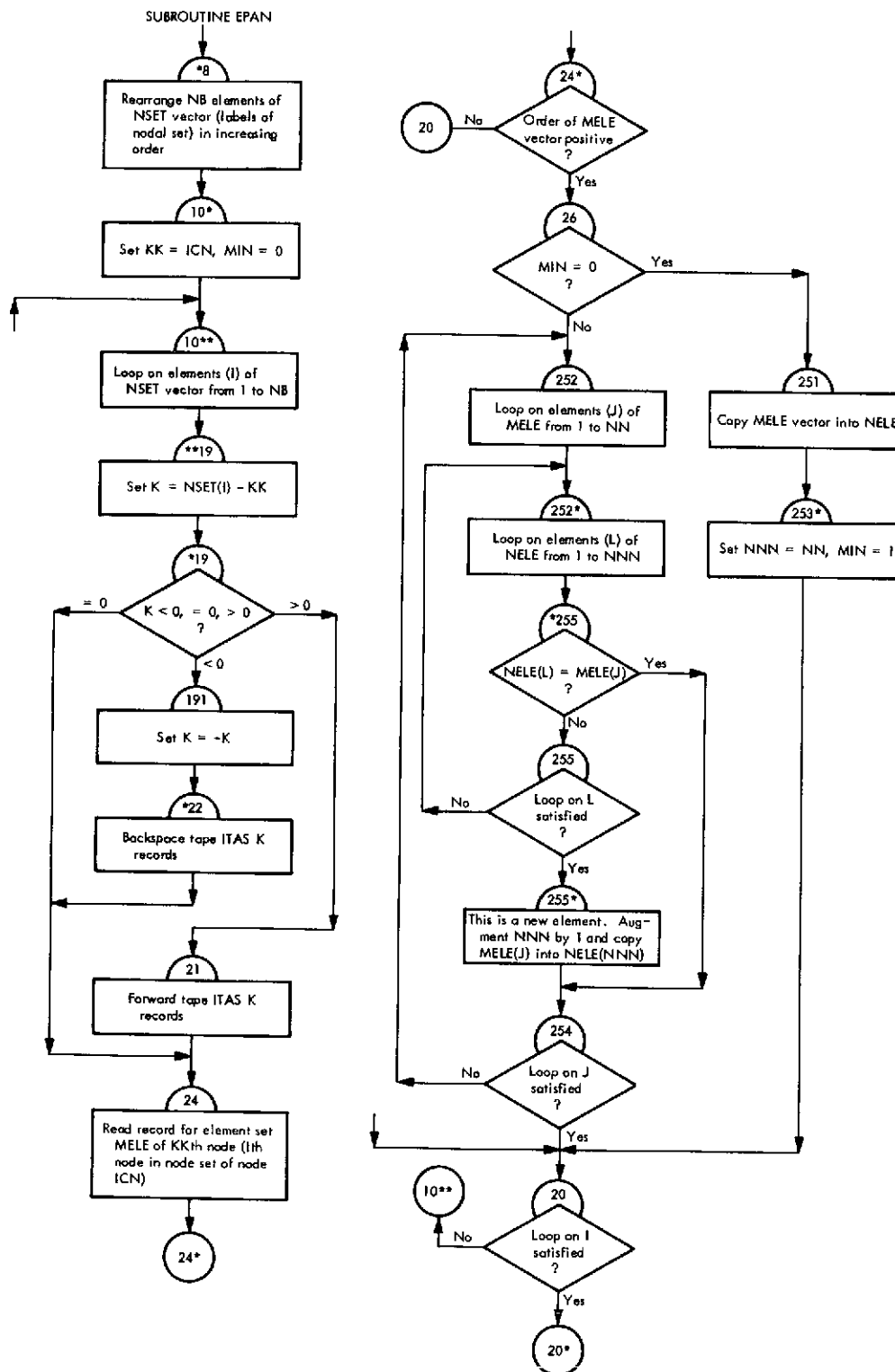


Fig. VI-53. Flowchart of subroutine EPAN (Link 4)

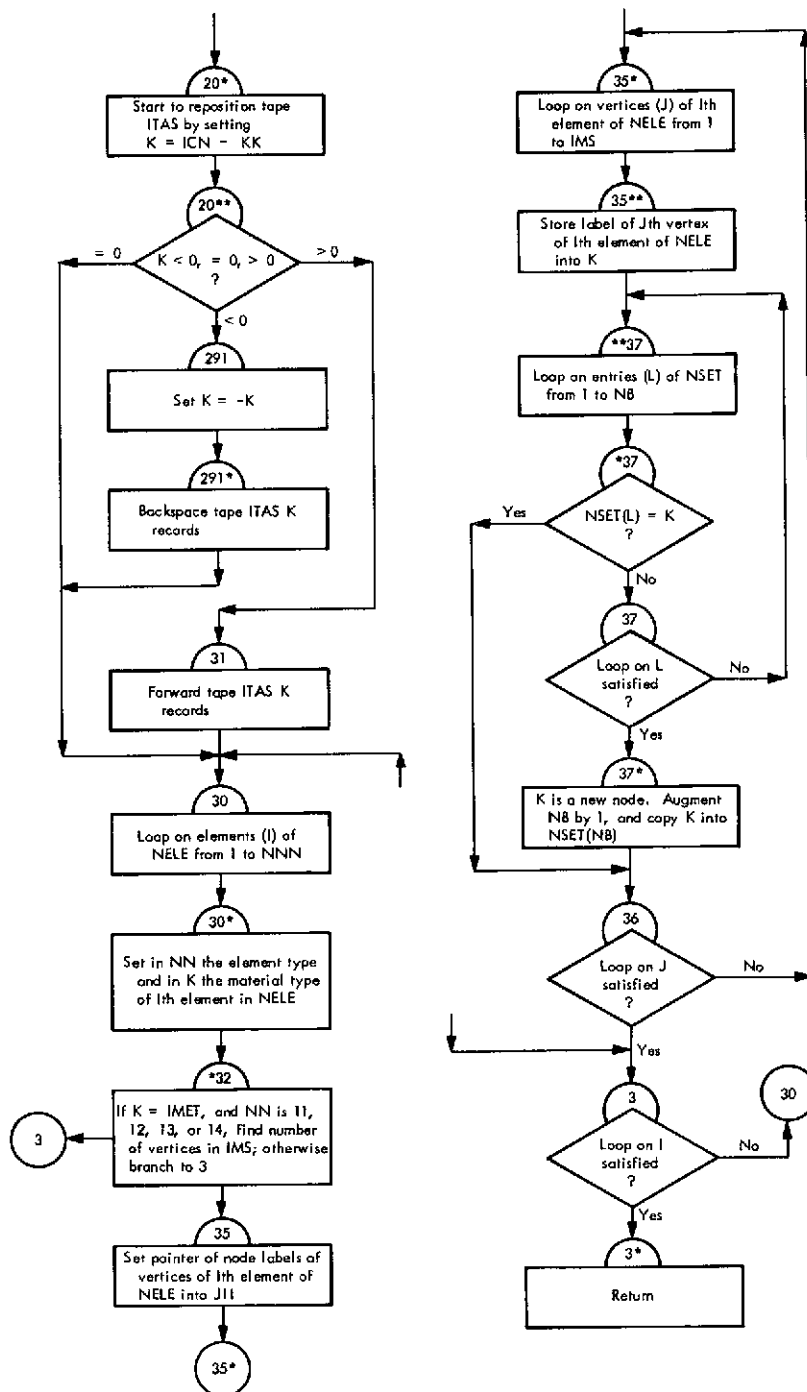


Fig. VI-53 (contd)

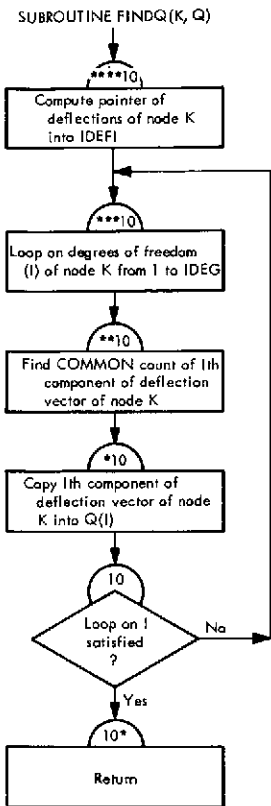


Fig. VI-54. Flowchart of subroutine FINDQ (Link 4)

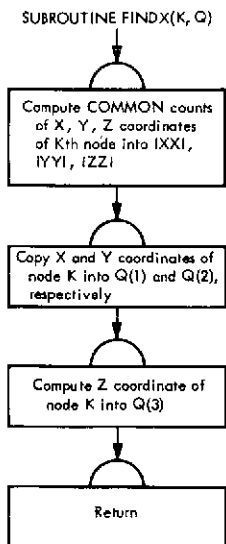


Fig. VI-55. Flowchart of subroutine FINDX (Link 4)

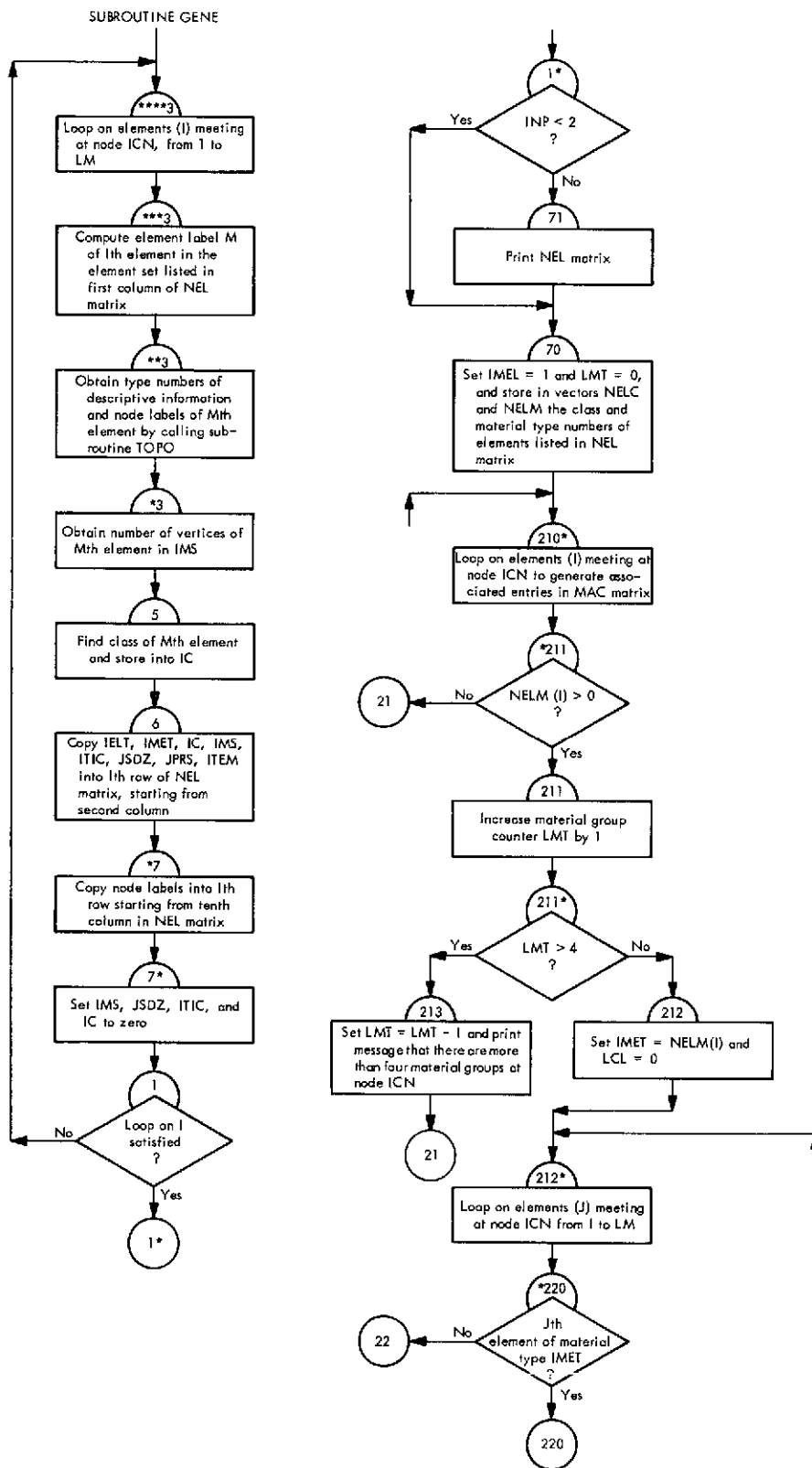


Fig. VI-56. Flowchart of subroutine GENE (Link 4)

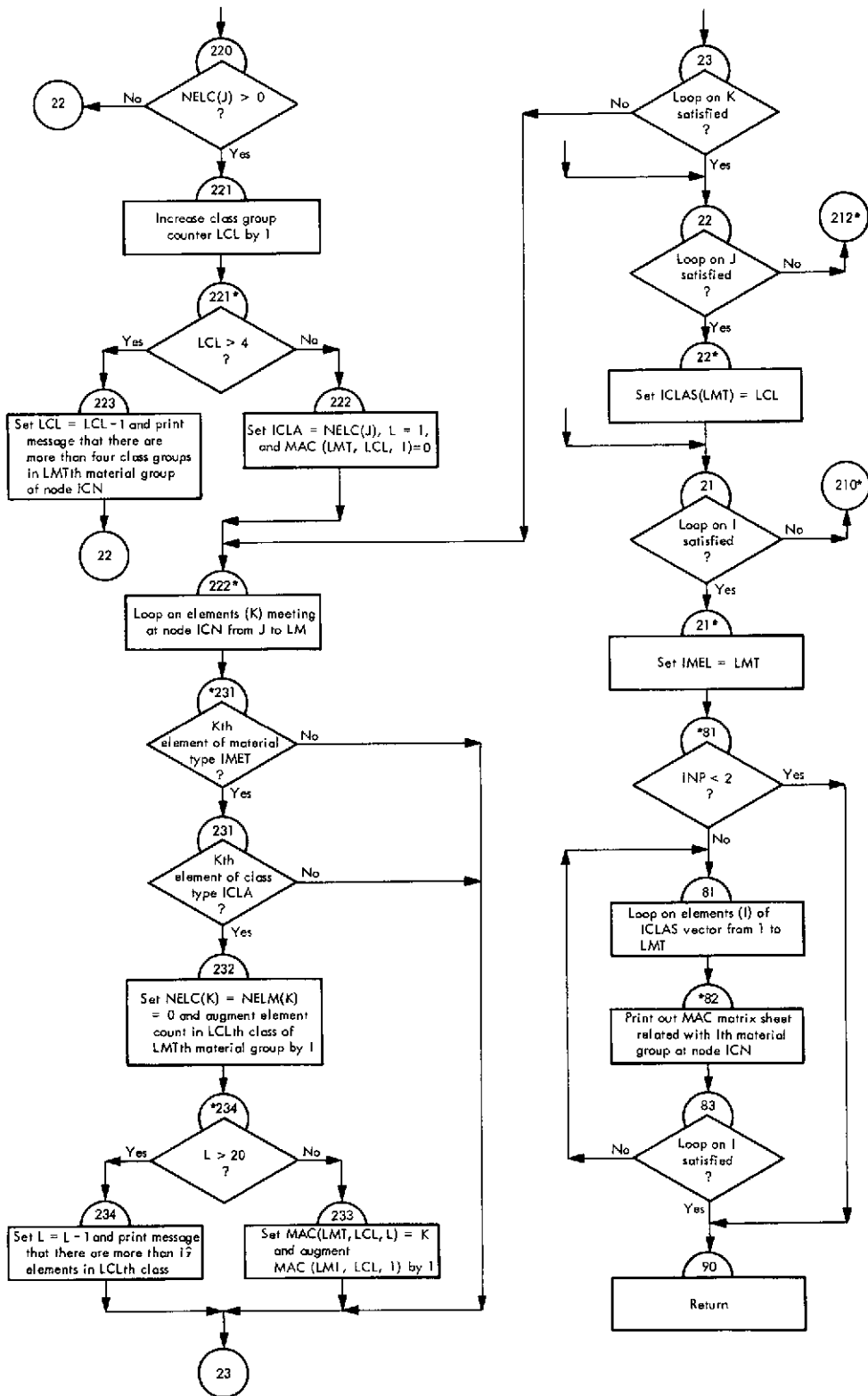


Fig. VI-56 (contd)

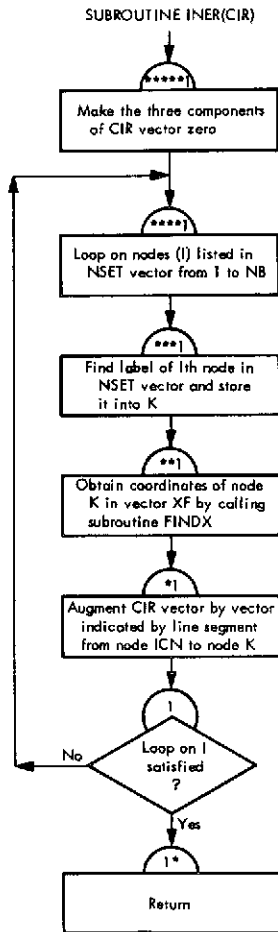


Fig. VI-57. Flowchart of subroutine INER (Link 4)

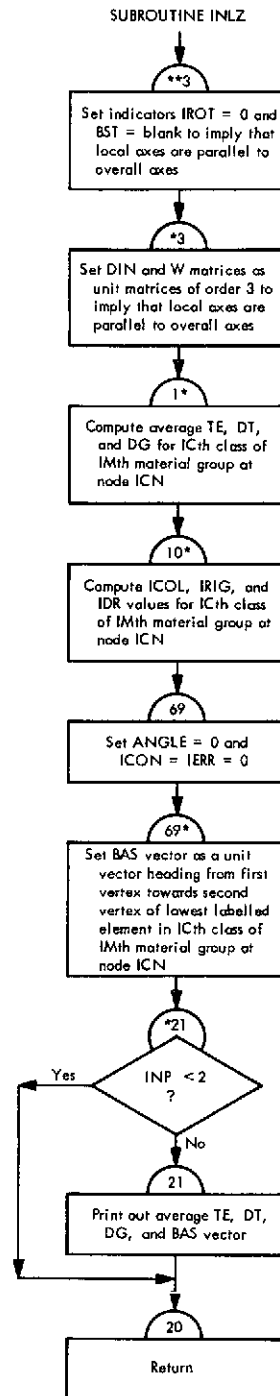


Fig. VI-58. Flowchart of subroutine INLZ (Link 4)

SUBROUTINE INV (A, N, B, M, DETERM)

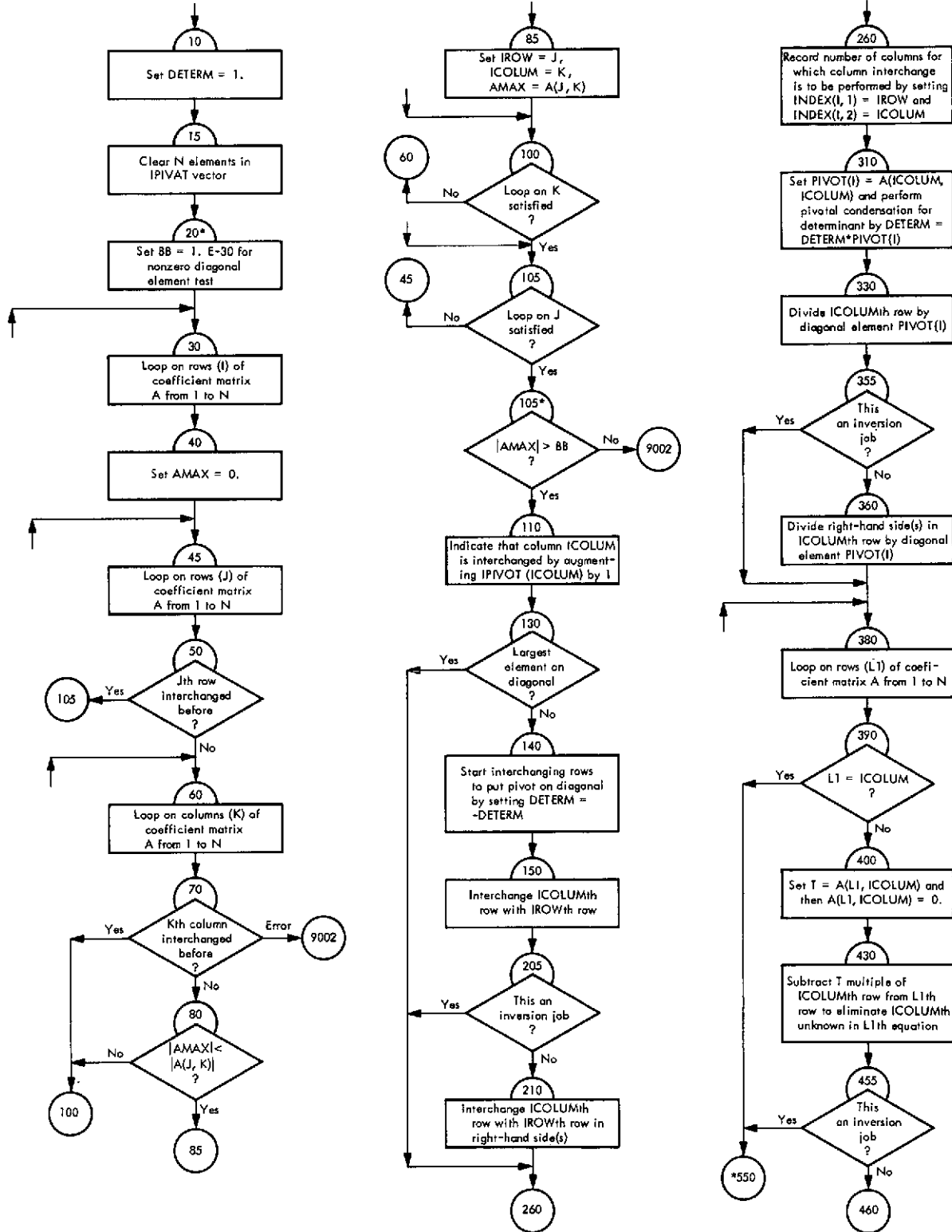


Fig. VI-59. Flowchart of subroutine INV (Link 4)

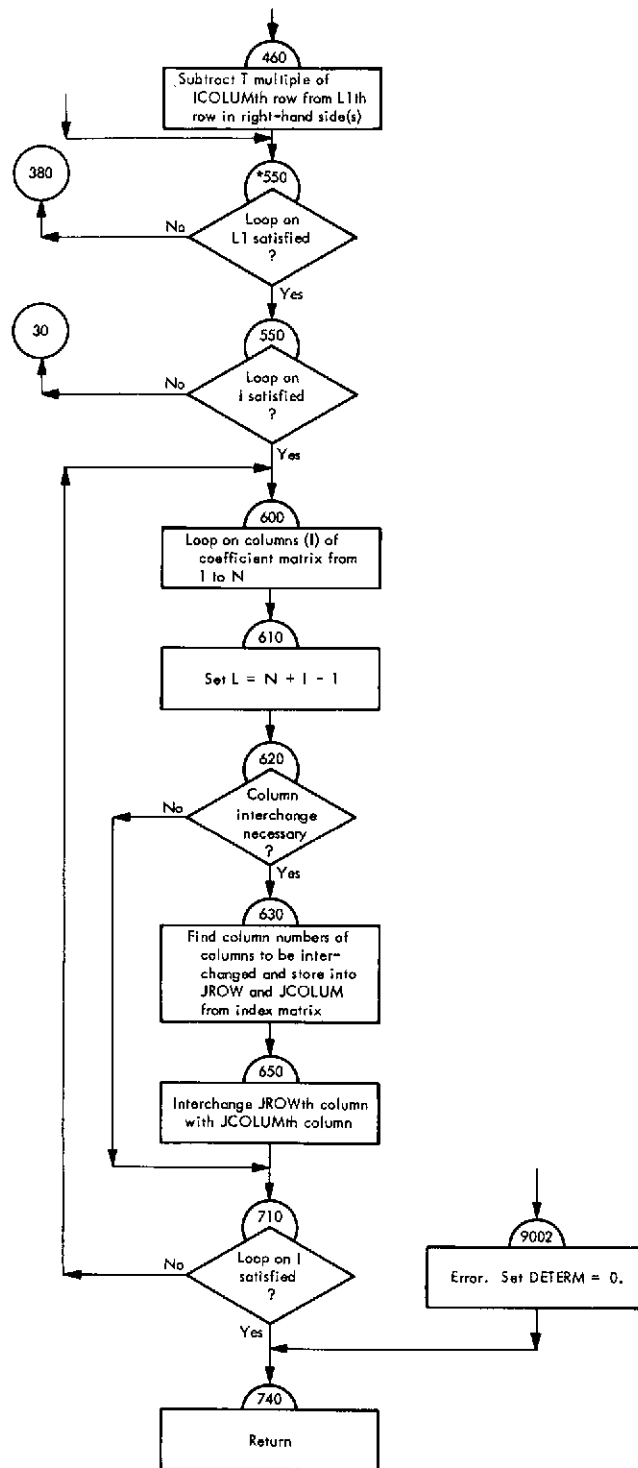


Fig. VI-59 (contd)

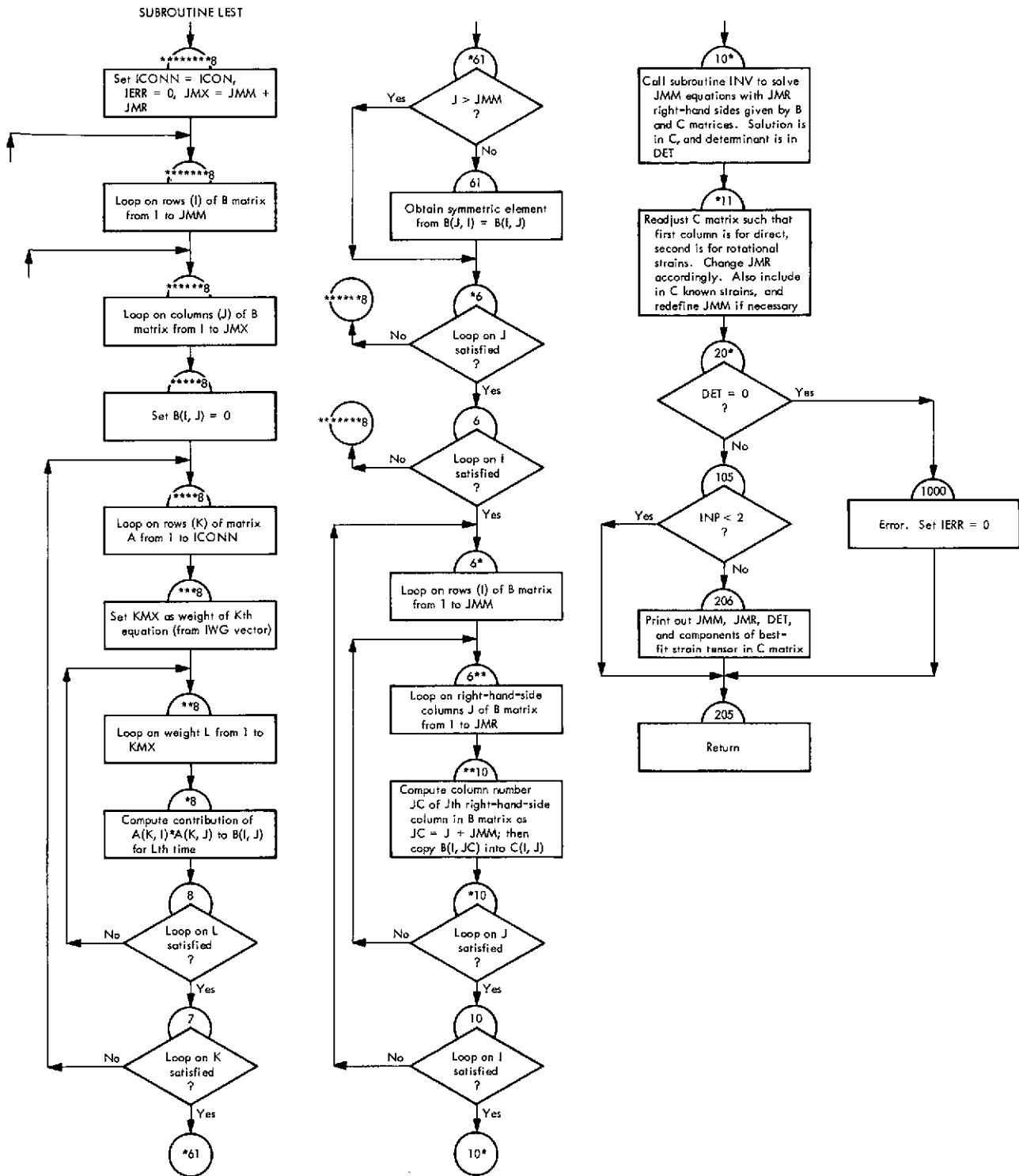


Fig. VI-60. Flowchart of subroutine LEST (Link 4)

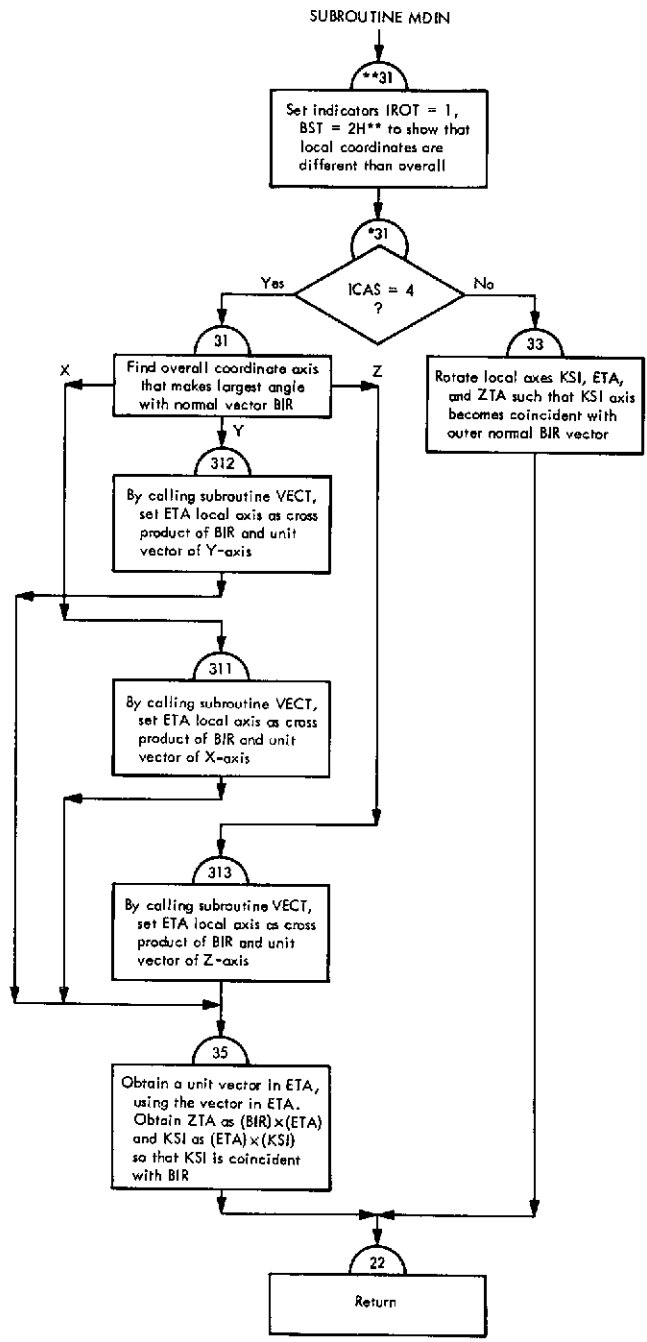


Fig. VI-61. Flowchart of subroutine MDIN (Link 4)

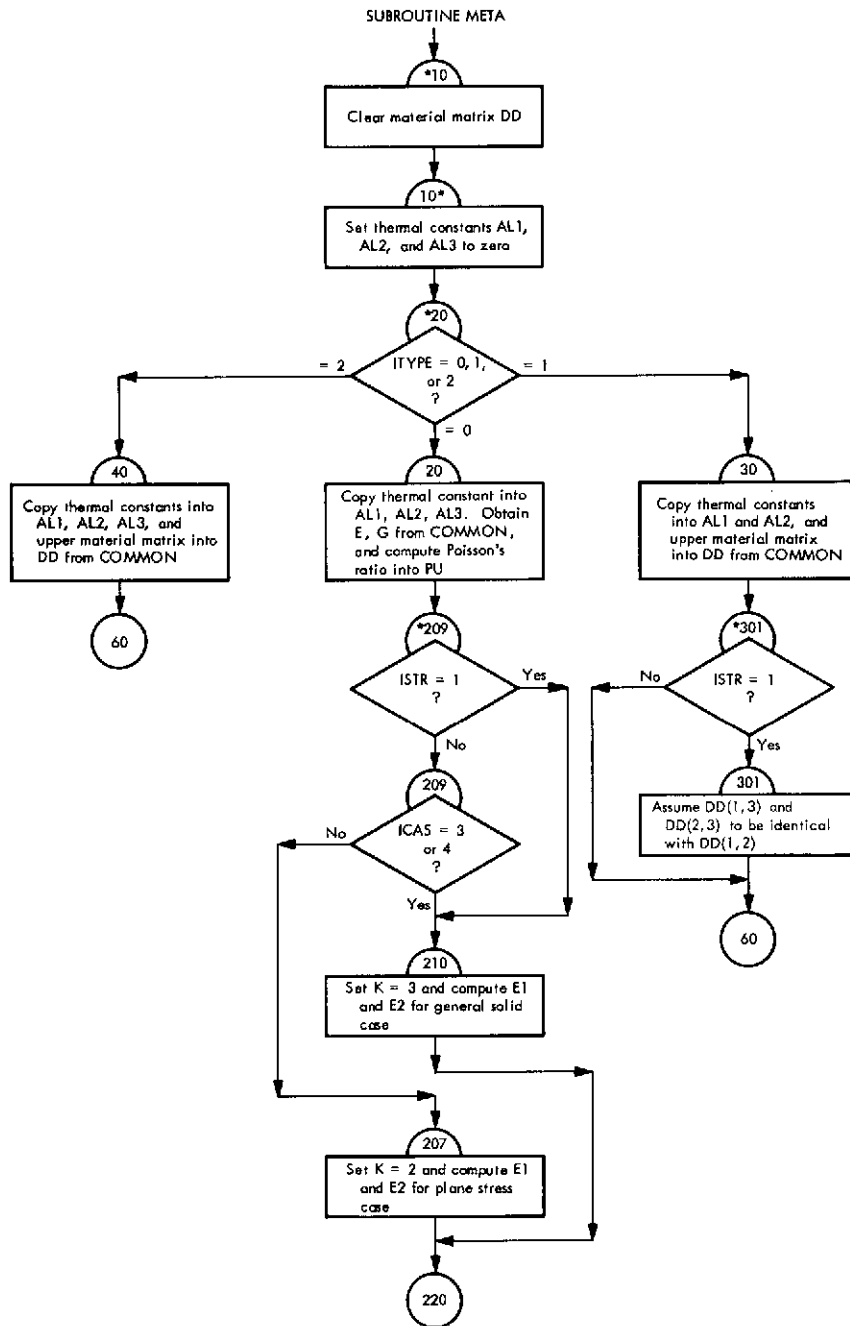


Fig. VI-62. Flowchart of subroutine META (Link 4)

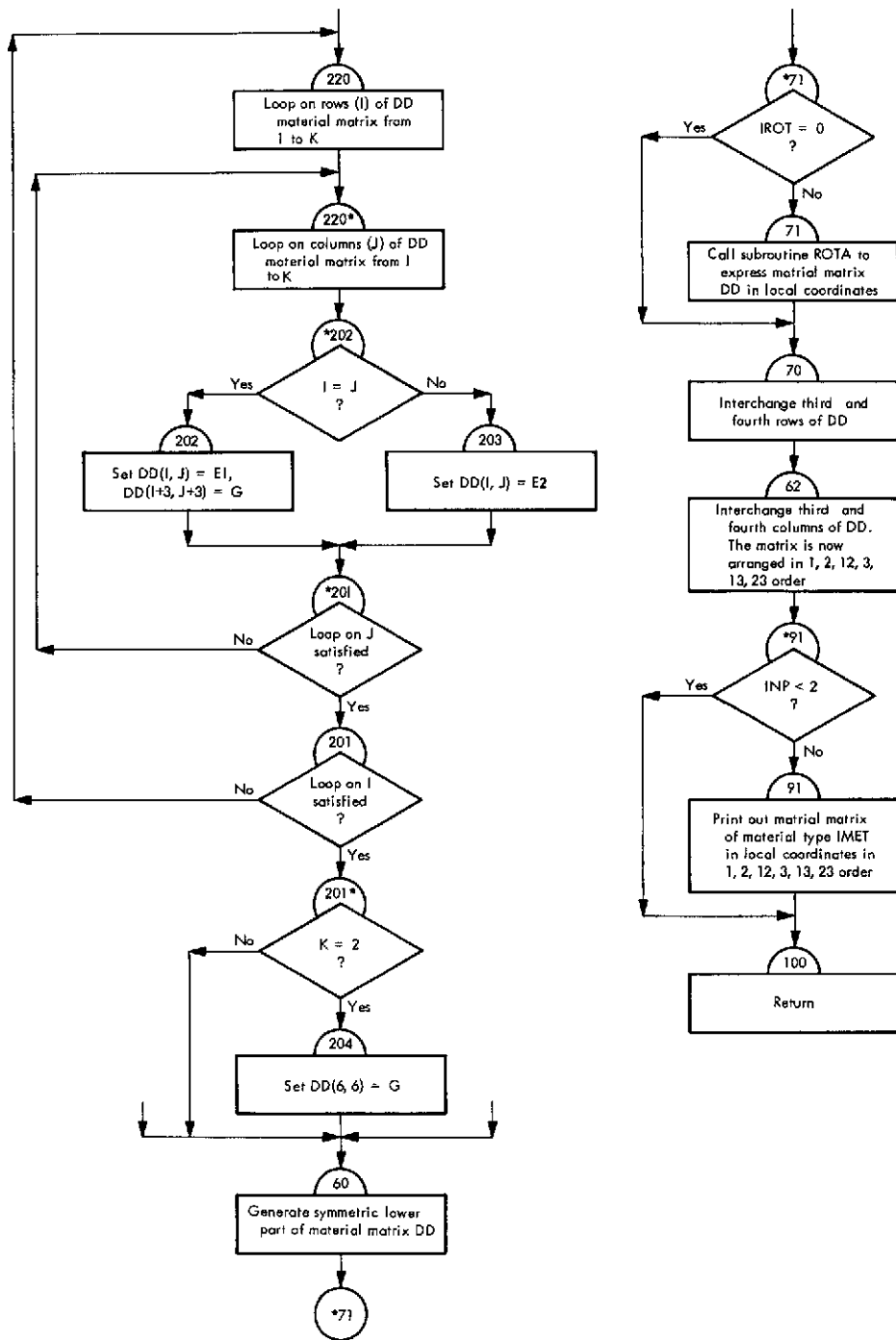


Fig. VI-62 (contd)

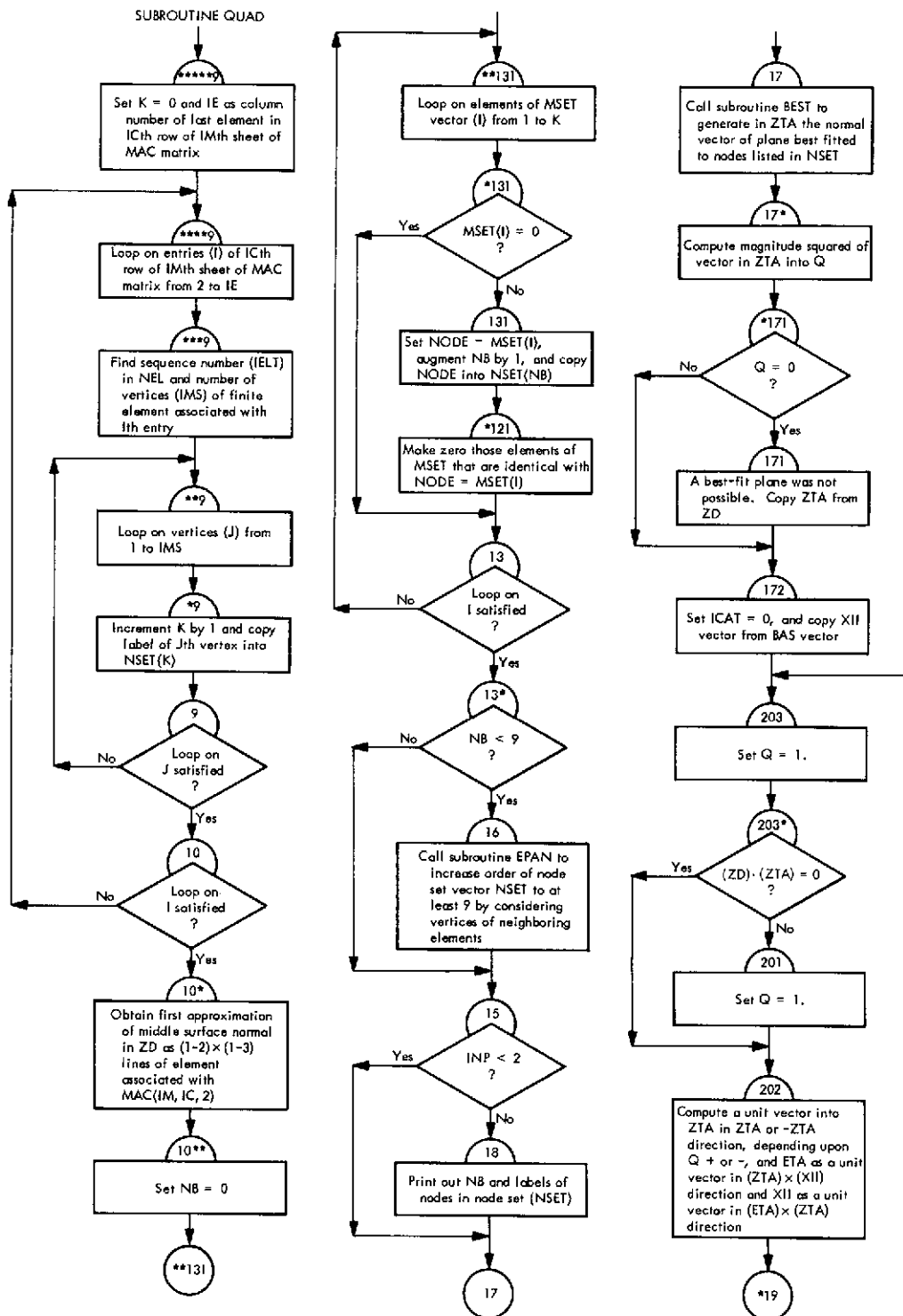


Fig. VI-63. Flowchart of subroutine QUAD (Link 4)

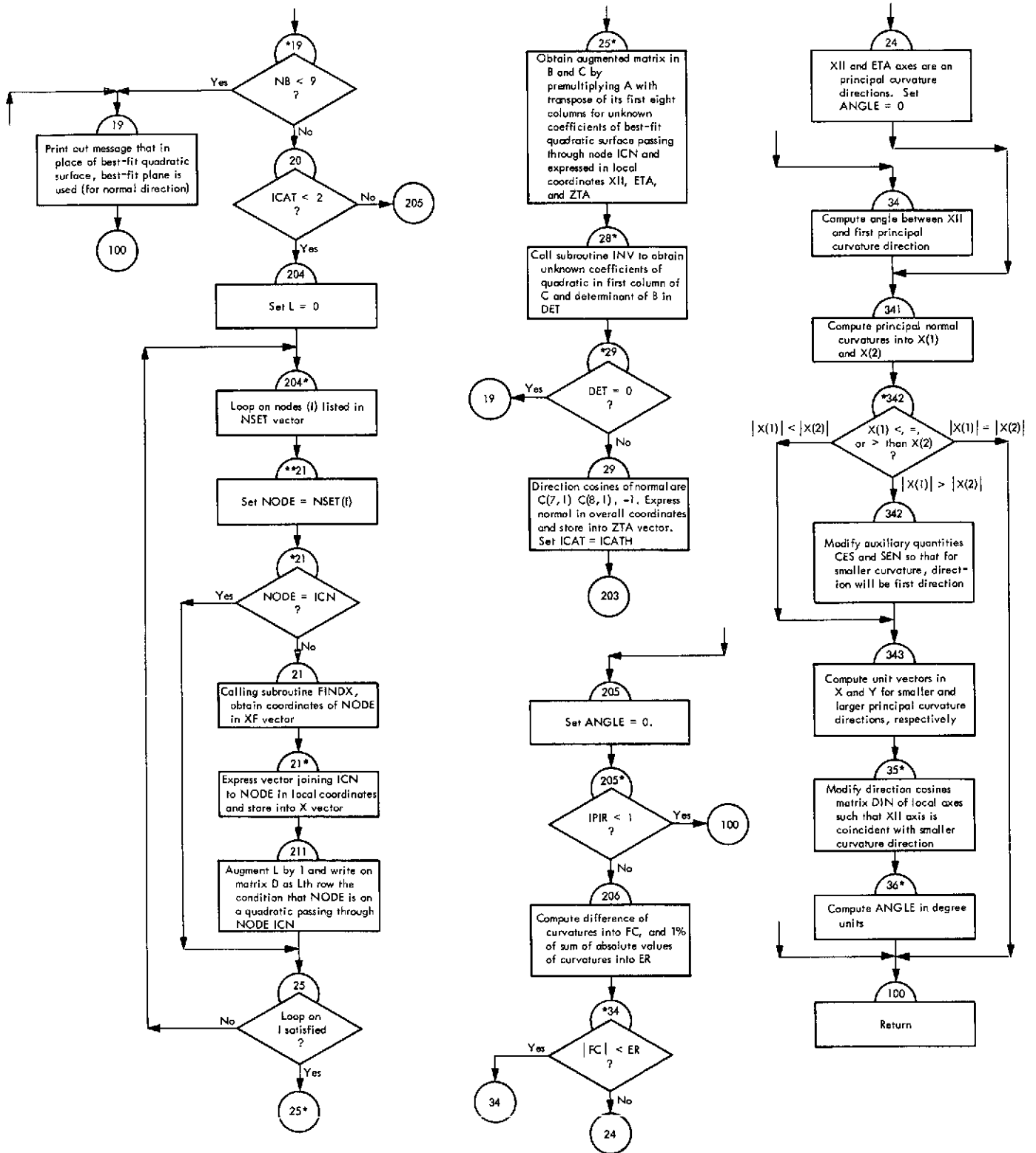


Fig. VI-63 (contd)

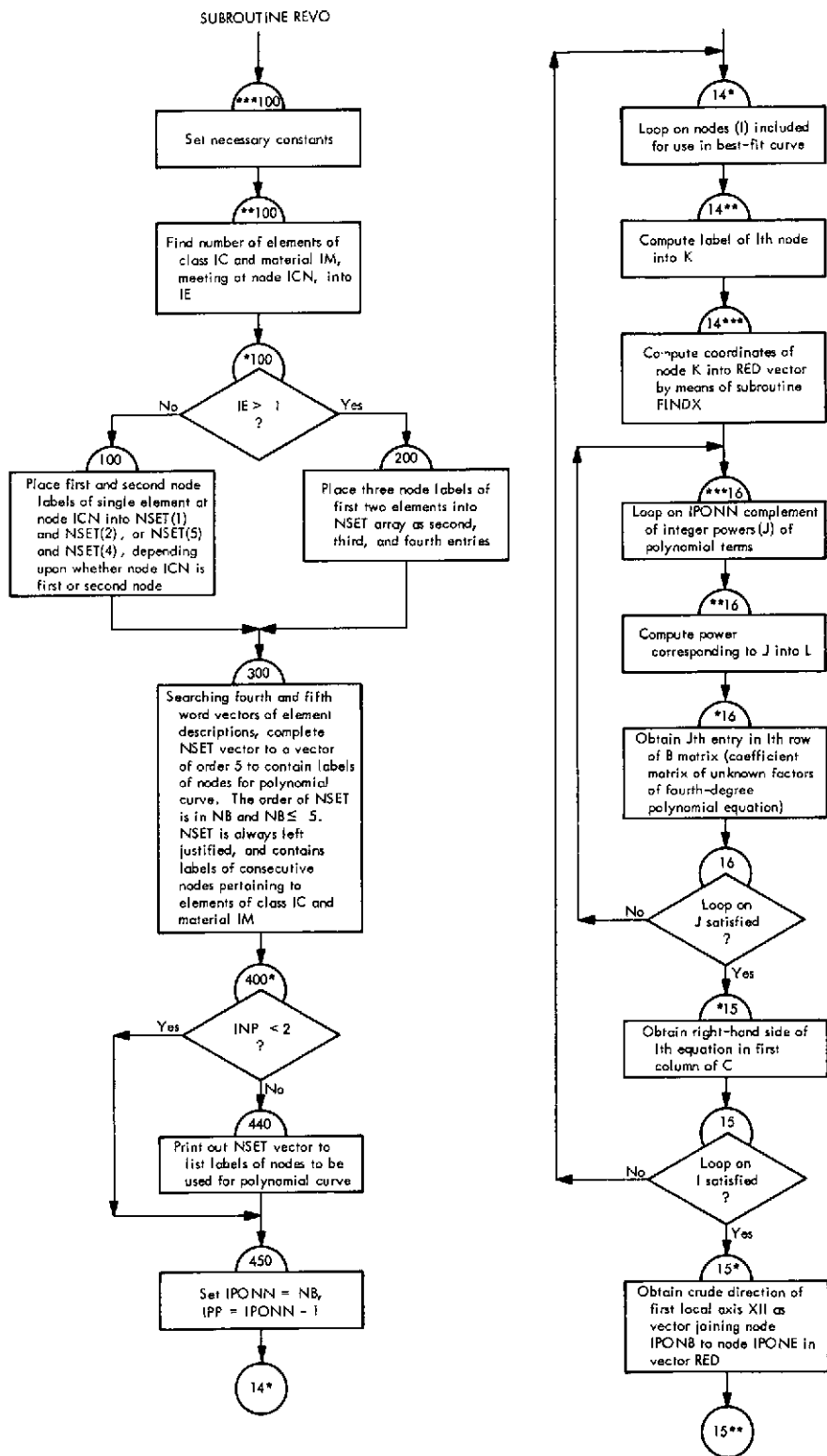


Fig. VI-64. Flowchart of subroutine REVO (Link 4)

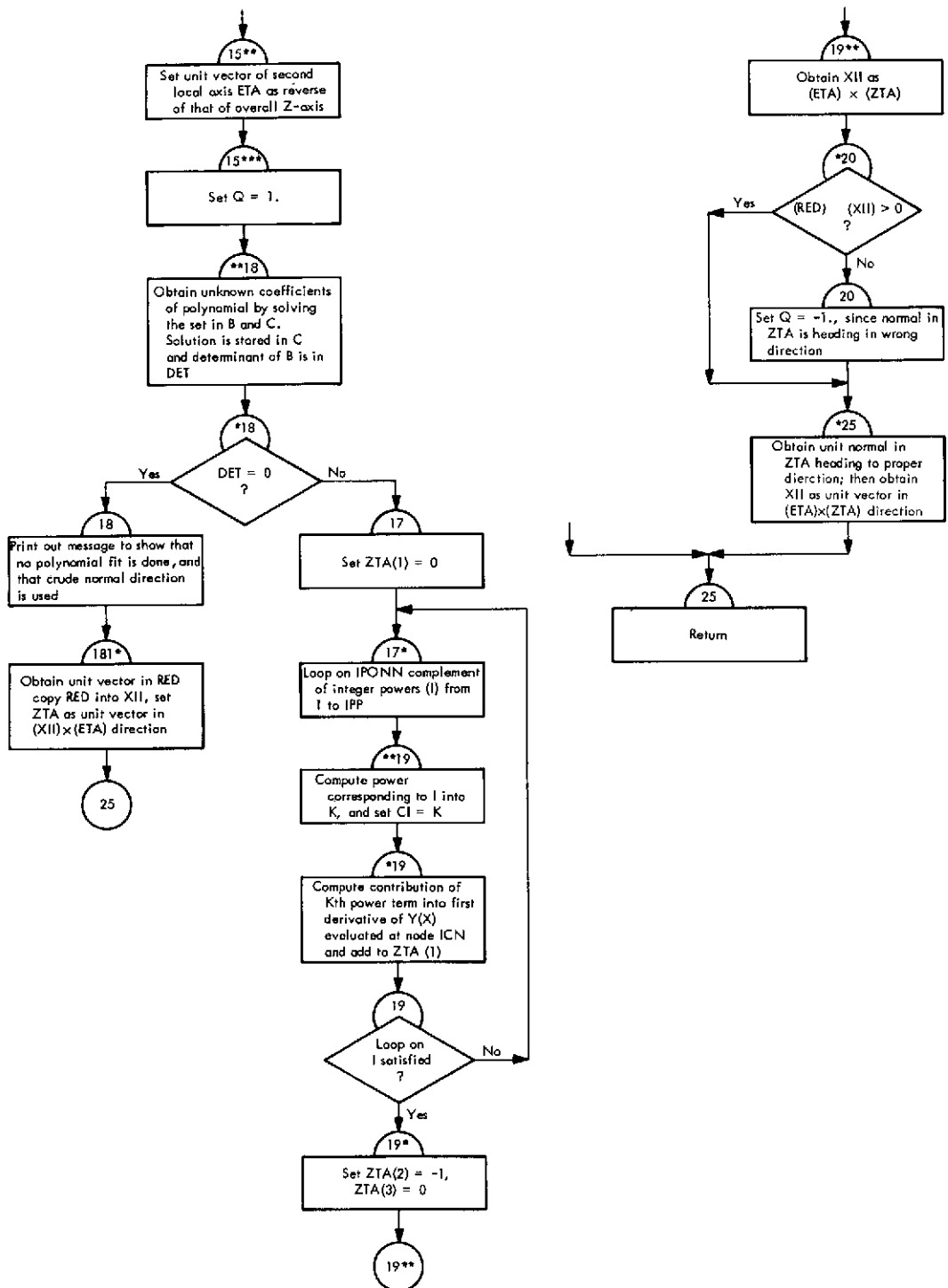


Fig. VI-64 (contd)

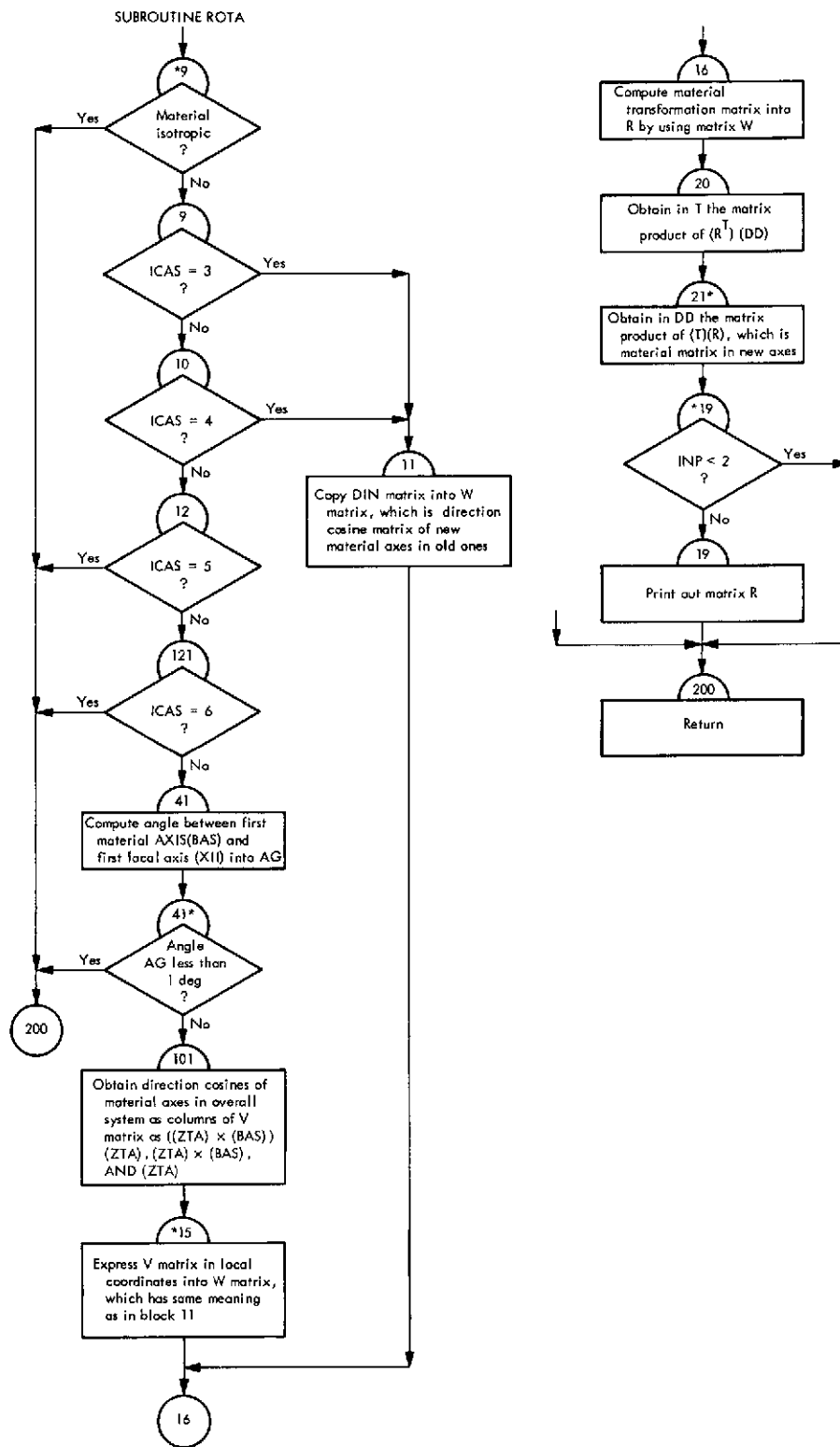


Fig. VI-65. Flowchart of subroutine ROTA (Link 4)

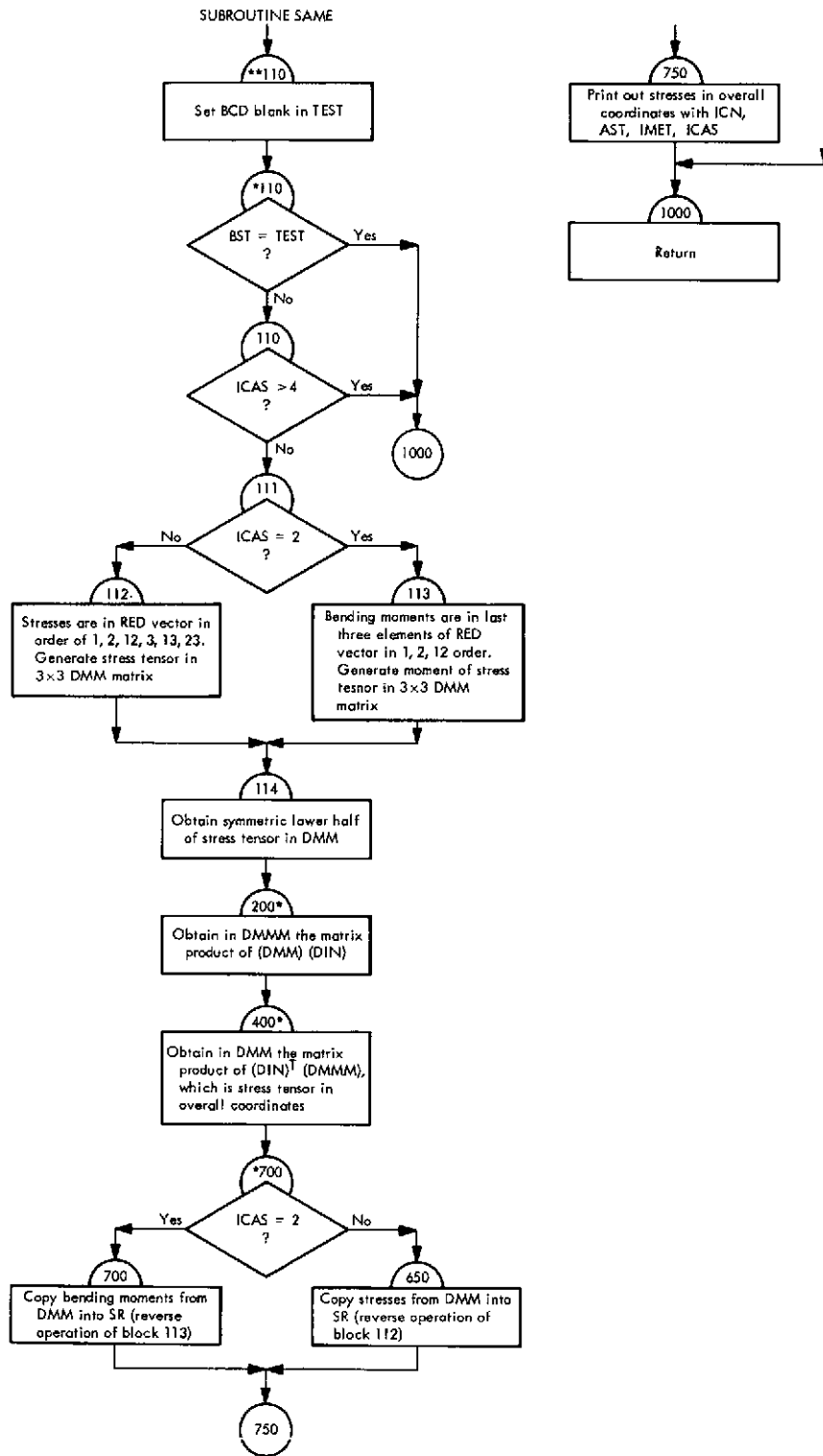


Fig. VI-66. Flowchart of subroutine SAME (Link 4)

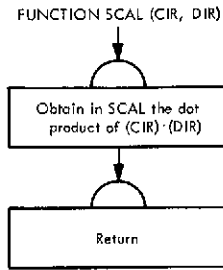


Fig. VI-67. Flowchart of function SCAL (Link 4)

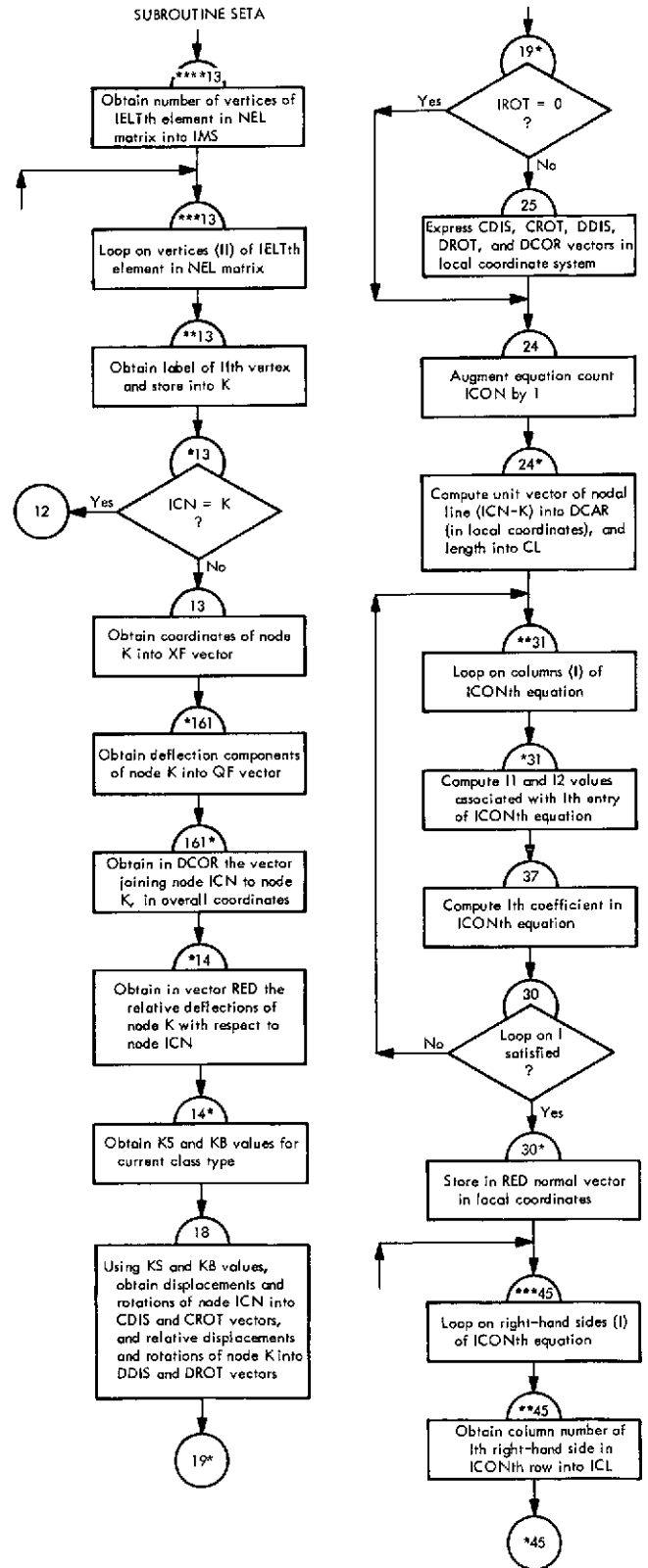


Fig. VI-68. Flowchart of subroutine SETA (Link 4)

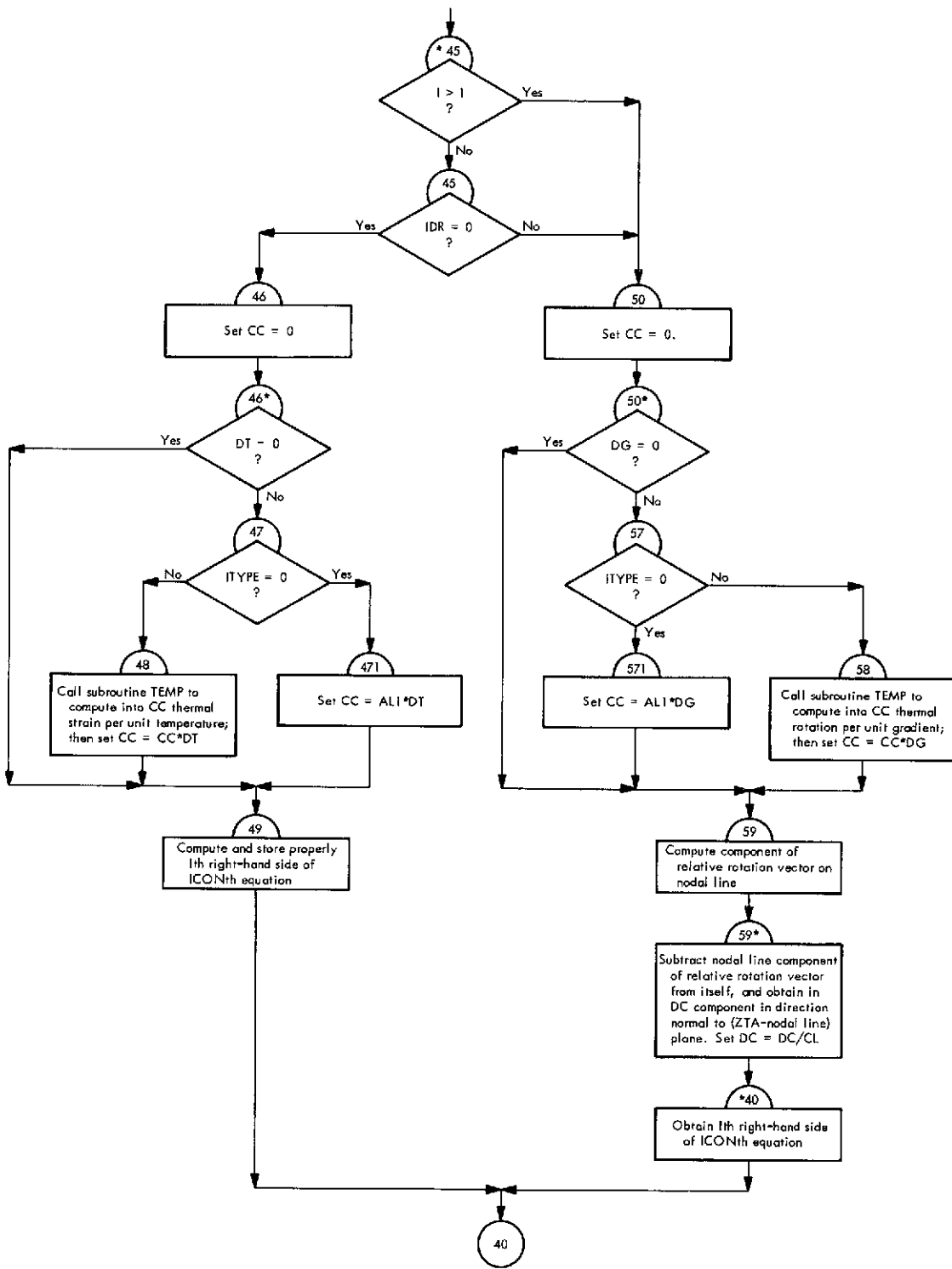


Fig. VI-68 (contd)

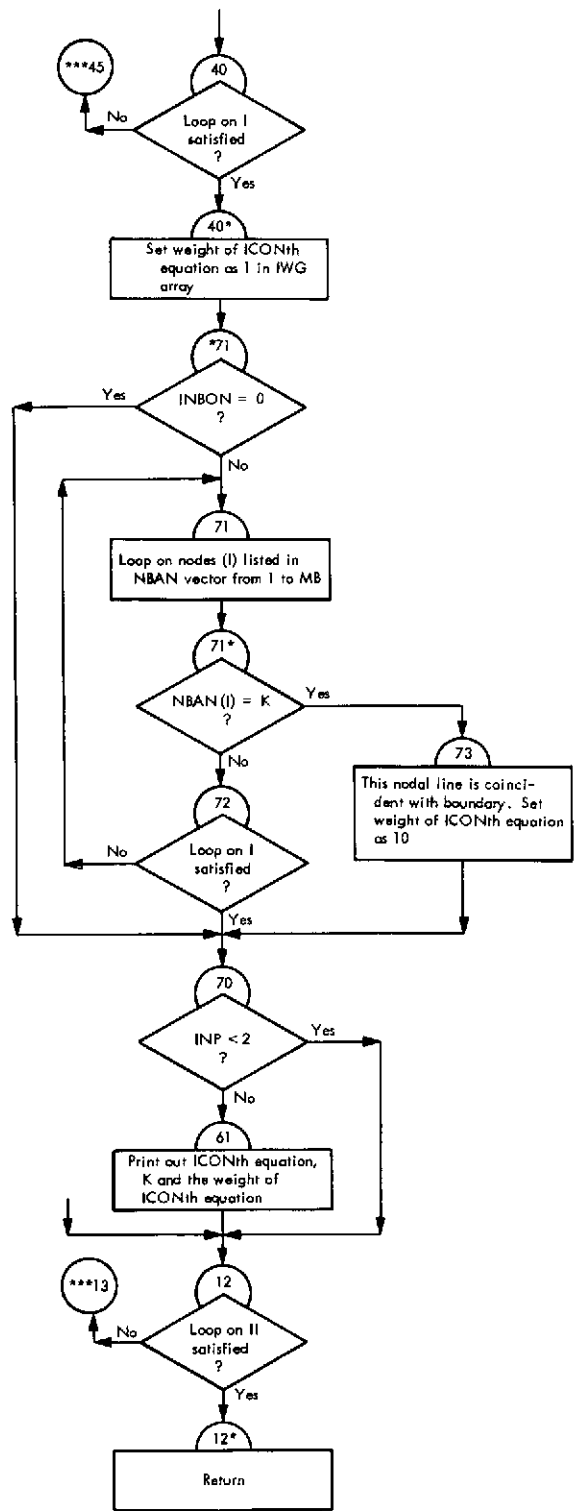


Fig. VI-68 (contd)

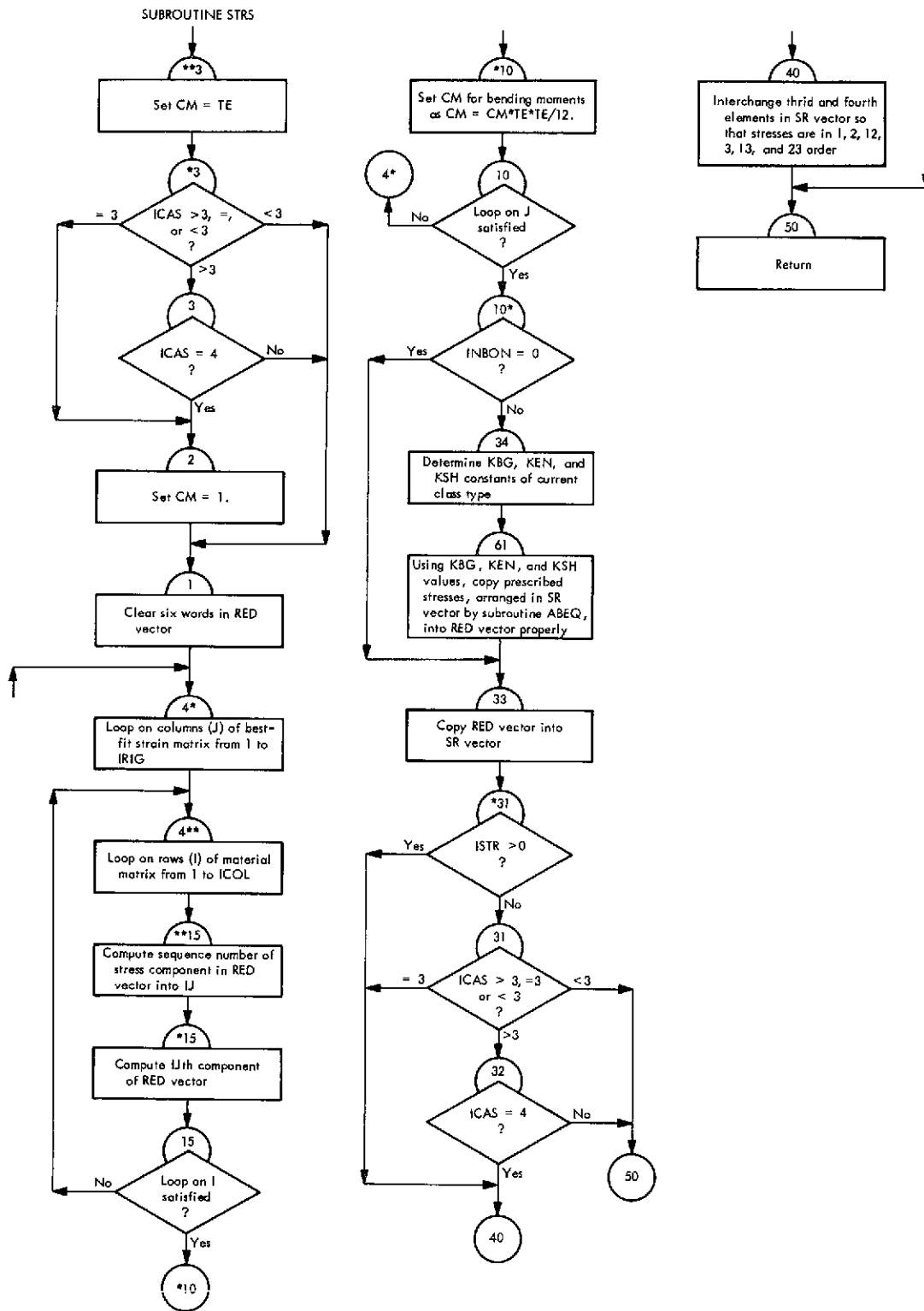


Fig. VI-69. Flowchart of subroutine STRS (Link 4)

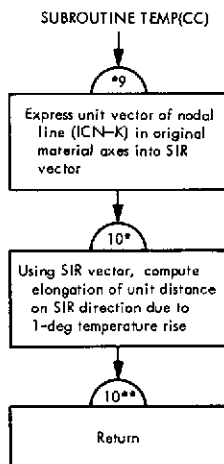


Fig. VI-70. Flowchart of subroutine TEMP (Link 4)

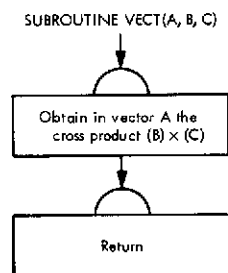


Fig. VI-72. Flowchart of subroutine VECT (Link 4)

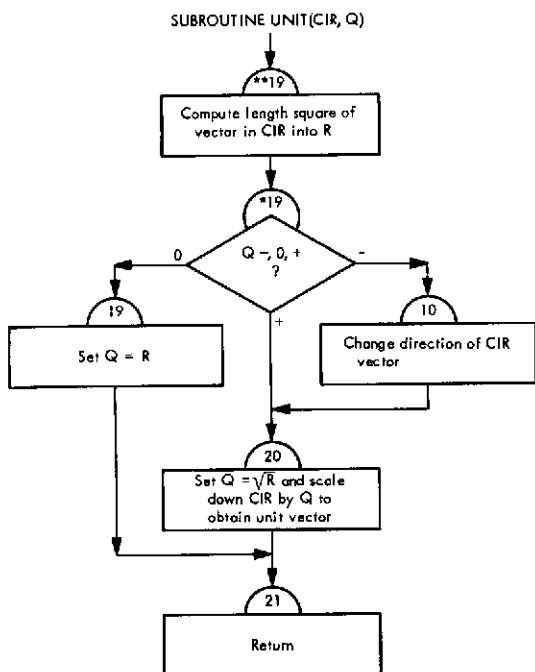


Fig. VI-71. Flowchart of subroutine UNIT (Link 4)

VII. Source Program Listings

This section contains the source program listings of ELAS/Level 3. The listing of each program element is treated separately, and given a table number. The listings are arranged alphabetically by the subroutine names, under the main program of each link. The meanings of the variables used in the source program may be obtained from Tables III-2, III-3, and III-4 of Vol. II (basic). The organization of COMMON for each link is shown in Fig. III-1 of Vol. II (basic).

Table VII-1 (contd)

```

2400 READ INPUT TAPE 5,2001,(IDUM(I),DUMMY(I+100),I=1,NTIC) EL451225 DUMMY(I+1000)=AA(IYY1) EL451340
DD 2600 I=1,NTIC EL451226 DUMMY(I+2000)=AA(IZZ1)*ZGEM EL451341
IF (IDUM(I)-1) 300,5500,300 EL451227 5800 CONTINUE EL451342
5900 ITEI=ITE+1 EL451228 WRITE OUTPUT TAPE 6,8302,I1,DUMMY(I),DUMMY(I+1000),DUMMY(I+2000),I EL451343
AA(ITE)=DUMMY(I+100) EL451229 I=L+1000 EL451344
2600 CONTINUE EL451230 L=L+1000 EL451345
IF (INP-I) 6217,2900,2900 EL451231 IF (L-NTP) 9010,9030,9030 EL451346
2900 WRITE OUTPUT TAPE 6,1302,(I,DUMMY(I+100),I=1,NTIC) EL451232 IN=NTP EL451347
1302 FORMAT (///4X,15HTHICKNESS TYPES//15(I5,F15.5,4X)) EL451233 C PREPARE VECTORS NECESSARY FOR IMPUSING BOUNDARY CONDITIONS EL451348
6217 IF (ISDT) 300,6216,5700 EL451234 5850 DD 6 I=1,IND EL451349
5700 READ INPUT TAPE 5,2001,(IDUM(I),DUMMY(I+100),I=1,ISDT) EL451235 IBDI=IBDI+1 EL451350
DD 5720 I=1,ISDT EL451236 IBDI=IBDI+1 EL451351
IF (IDUM(I)-1) 300,5710,300 EL451237 ICI=ICI+1 EL451352
5710 IOTI=IOT+1 EL451238 IAC(ROI)=I EL451353
AA(IOTI)=DUMMY(I+100) EL451239 IAC(ROI)=INDI EL451354
5720 CONTINUE EL451240 6 AA(ICI)=I EL451355
IF (INP-I) 6216,5730,5730 EL451241 IF (IBN) 300,5860,317 EL451356
5730 WRITE OUTPUT TAPE 6,1303,(I,DUMMY(I+100),I=1,ISDT) EL451242 C READ IN BOUNDARY CONDITIONS EL451357
1303 FORMAT (///4X,26HTEMPERATURE INCREASE TYPES//5(I5,E15.5,4X)) EL451243 3170 IF (IBUM) 3172,3171,3172 EL451358
6216 IF (ISDY) 300,6215,3500 EL451244 I=0 EL451359
3500 READ INPUT TAPE 5,2001,(IDUM(I),DUMMY(I+100),I=1,ISDY) EL451245 IRR=I EL451360
DD 3700 I=1,ISDY EL451246 NTP=IBN EL451361
IF (IDUM(I)-1) 300,3600,300 EL451247 3000 IF (L+1000-NTP) 3100,3200,3200 EL451362
3600 IOYI=IOY+1 EL451248 3100 IBN=1000 EL451363
AA(IOYI)=DUMMY(I+100) EL451249 3200 IHN=NTP-L EL451364
3700 CONTINUE EL451250 3170 IF (IBUM) 3172,3171,3172 EL451365
IF (INP-I) 6215,3800,3800 EL451251 3172 CALL BUNG EL451366
3800 WRITE OUTPUT TAPE 6,1304,(I,DUMMY(I+100),I=1,ISDY) EL451252 GO TO 3173 EL451367
1304 FORMAT (///4X,39HTEMPERATURE GRADIENT TYPES ALONG Y AXIS// EL451253 3171 READ INPUT TAPE 5,108,(IDUM(I),IDUM(I+1000),IDUM(I+2000),IDUM(I+30 EL451368
15(I5,E15.5,4X)) EL451254 100),DUMMY(I+4000),I=1,IRN) EL451369
6215 IF (ISDZ) 300,6214,4000 EL451255 108 FORMAT (5(I4,I1,I4,I1,F6.5)) EL451370
4000 READ INPUT TAPE 5,2001,(IDUM(I),DUMMY(I+100),I=1,ISDZ) EL451256 3173 DD 441 I=1,IRN EL451371
DD 4200 I=1,ISDZ EL451257 KCR=IDUM(I+1000) EL451372
IF (IDUM(I)-1) 300,4100,300 EL451258 ICR=IDUM(I+3000) EL451373
4100 IOZI=IOZ+1 EL451259 IF (KCR-IDEG) 318,319,300 EL451374
AA(IOZI)=DUMMY(I+100) EL451260 318 IF (KCR) 300,300,319 EL451375
4200 CONTINUE EL451261 319 IF (KCO-IDEG) 320,321,300 EL451376
IF (INP-I) 6214,4300,4300 EL451262 320 IF (KCO) 300,300,321 EL451377
4300 WRITE OUTPUT TAPE 6,1305,(I,DUMMY(I+100),I=1,ISDZ) EL451263 321 NO-IDUM(I) EL451378
1305 FORMAT (///4X,10HAREA TYPES//15(I5,E15.5,4X)) EL451264 NR-IDUM(I+2000) EL451379
6214 IF (IARE) 300,6213,4500 EL451265 IF (NO-IN) 322,323,300 EL451380
4500 READ INPUT TAPE 5,2001,(IDUM(I),DUMMY(I+100),I=1,IARE) EL451266 322 IF (NO) 300,300,323 EL451381
DD 4700 I=1,IARE EL451267 323 IF (NR-IN) 324,325,300 EL451382
IF (IDUM(I)-1) 300,4600,300 EL451268 324 IF (NR) 300,300,325 EL451383
4600 ICARI=ICAR+1 EL451269 II=IDEG+IN-1+KCR EL451384
AA(ICARI)=DUMMY(I+100) EL451270 JI=IDEG+INR-1+KCR EL451385
4700 CONTINUE EL451271 IBDI=IBDI+1 EL451386
IF (INP-I) 6213,4800,4800 EL451272 ICI=ICI+1 EL451387
4800 WRITE OUTPUT TAPE 6,1306,(I,DUMMY(I+100),I=1,IARE) EL451273 N=IA(ROI) EL451388
1306 FORMAT (///4X,10HAREA TYPES//15(I5,E15.5,4X)) EL451274 GO TO 172 EL451389
6213 IF (IMMX) 300,6212,5000 EL451275 176 IF (N+I) 357,1757,1758 EL451390
5000 READ INPUT TAPE 5,2001,(IDUM(I),DUMMY(I+100),I=1,IMMX) EL451276 1757 IAI(ROI)=J EL451391
DD 5200 I=1,IMMX EL451277 GO TO 44 EL451392
IF (IDUM(I)-1) 300,5100,300 EL451278 1758 IF (N-10000)1759,1760,1760 EL451393
4100 ICIXI=ICIX+1 EL451279 1760 IBDJ=IBDJ+J EL451394
AA(ICIXI)=DUMMY(I+100) EL451280 IF (IA(IBDJ+1)) 357,1763,357 EL451395
5200 CONTINUE EL451281 IAI(ROI)=10000-I EL451396
IF (INP-I) 6212,5300,5300 EL451282 IICJ=IIC+J EL451397
5300 WRITE OUTPUT TAPE 6,1307,(I,DUMMY(I+100),I=1,IMMX) EL451283 AA(IICJ)=DUMMY(I+4000) EL451398
1307 FORMAT (///4X,22HTORSION CONSTANT TYPES//15(I5,E15.5,4X)) EL451284 GO TO 441 EL451399
6212 IF (IMMY) 300,6209,6000 EL451285 IBDJ=IBDJ+J EL451400
6000 READ INPUT TAPE 5,2001,(IDUM(I),DUMMY(I+100),I=1,IMMY) EL451286 1759 IF (IA(IBDJ+1)) 357,1761,357 EL451401
DD 6200 I=1,IMMY EL451287 1761 IRDN=IBDN+1 EL451402
IF (IDUM(I)-1) 300,6100,300 EL451288 IF (IA(IBDN+1)) 357,1762,357 EL451403
6100 ICYI=ICY+1 EL451289 IICN=IIC+N EL451404
AA(ICYI)=DUMMY(I+100) EL451290 IAI(BDN)=10000-I EL451405
6200 CONTINUE EL451291 AA(IGN)=AA(IIC) EL451406
IF (INP-I) 6209,6300,6300 EL451292 AA(ICI)=0 EL451407
6300 WRITE OUTPUT TAPE 6,1308,(I,DUMMY(I+100),I=1,IMMY) EL451293 IAI(ROI)=IA(IBDN) EL451408
1308 FORMAT (///4X,50HMODMENT OF INERTIA TYPES ABOUT FIRST PRINCIPAL AXES// EL451294 IICJ=IIC+J EL451409
15(I5,F15.5,4X)) EL451295 AA(IICJ)=DUMMY(I+4000) EL451410
6209 IF (IMMZ) 300,6208,6500 EL451296 IAI(ROI)=10000 EL451411
6500 READ INPUT TAPE 5,2001,(IDUM(I),DUMMY(I+100),I=1,IMMZ) EL451297 GO TO 441 EL451412
DD 6700 I=1,IMMZ EL451298 172 IF (I-J) 176,175,176 EL451413
IF (IDUM(I)-1) 300,6600,300 EL451299 175 IF (N) 1751,357,1753 EL451414
6600 ICZ1=ICZ+1 EL451300 1751 IF (N+1) 357,1750,175 EL451415
AA(ICZ1)=DUMMY(I+100) EL451301 1750 IAI(ROI)=0 EL451416
6700 CONTINUE EL451302 GO TO 44 EL451417
IF (INP-I) 6208,6800,6800 EL451303 1752 IAI(ROI)=10000+I EL451418
6800 WRITE OUTPUT TAPE 6,1309,(I,DUMMY(I+100),I=1,IMMZ) EL451304 GO TO 44 EL451419
1309 FORMAT (///4X,51HMODMENT OF INERTIA TYPES ABOUT SECOND PRINCIPAL EL451305 1753 IF (N-10000)1754,1752,357 EL451420
AXES//15(I5,E15.5,4X)) EL451306 1754 IRDN=IBDN+1 EL451421
6208 IF (IMF) 300,6300,7000 EL451307 IF (IA(IBDN+1)) 357,1756,357 EL451422
7000 READ INPUT TAPE 5,2001,(IDUM(I),DUMMY(I+100),I=1,IMF) EL451308 1756 IAI(ROI)=10000+I EL451423
DD 7200 I=1,IMF EL451309 IICN=IIC+N EL451424
IF (IDUM(I)-1) 300,7100,300 EL451310 AA(IGN)=AA(IIC) EL451425
7100 ICFI=ICF+1 EL451311 IAI(IND)=-10000-I EL451426
AA(ICFI)=DUMMY(I+100) EL451312 GO TO 44 EL451427
7200 CONTINUE EL451313 IERR=IERR+1 EL451428
IF (INP-I) 830,7300,7300 EL451314 IRR=IERR EL451429
7300 WRITE OUTPUT TAPE 6,1310,(I,DUMMY(I+100),I=1,IMF) EL451315 GO TO 441 EL451430
1310 FORMAT (///4X,35HANGLE TYPES DEFINING PRINCIPAL AXES//15(I5,E15.5, EL451316 44 AA(IIC)=DUMMY(I+4000) EL451431
L4X)) EL451317 441 CONTINUE EL451432
2001 FORMAT (I2,ER,5) EL451318 L=L+1000 EL451433
C READ IN AND PRINT OUT NODAL COORDINATES EL451319 3165 I=1+1000 EL451434
8302 FORMAT (1H1,50X,17HNOODAL COORDINATES//2(15H NODE,5X,14X,14X,14X, EL451320 316 IRR=NTP EL451435
114X,14Z,19X)//2(15,3E15.5,10X)) EL451321 IRR=IBRR-I EL451436
8301 IF (ICOR) 8311,8311,8311 EL451322 IF (IBRR) 3161,5860,3161 EL451437
8311 CALL COR EL451323 3161 WRITE OUTPUT TAPE 6,3162 EL451438
GO TO 5810 EL451324 3162 FORMAT(1H1,11HTHE FOLLOWING DISPLACEMENT BOUNDARY CONDITION(S) CAELAS1439
8311 CALL COOR EL451325 1USE IS MORE THAN ONE MULTIPLE CONNECTION FOR THE UNKNOWN(S). EL451440
IF (IERR) 300,5810,300 EL451326 2)BH THEY ARE IGNORED. ) EL451441
5810 IF (INP-I) 5850,2519,2519 EL451327 DD 3163 I=1,IBRR EL451442
2519 L=0 EL451328 I=IBRR(I) EL451443
NTP=IN EL451329 WRITE OUTPUT TAPE 6,3164, IDUM(J), IDUM(J+1000), IDUM(J+2000), IDUM(J+ EL451444
9010 IF (L+1000-NTP) 9015,9020,9020 EL451330 13000),DUMMY(I+4000) EL451445
9015 IN=1000 EL451331 3164 EOPMAT (4,6,C15.5) EL451446
GO TO 9025 EL451332 3163 CONTINUE EL451447
9020 IN=NTP-L EL451333 C READ IN AND PRINT OUT MESH TOPOLOGY AND ELEMENT TYPES EL451448
9025 DD 5800 I=1,IN EL451334 5800 IF (INP-I) 7717,2523,2523 EL451449
IXX=IXX+1 EL451335 2523 WRITE OUTPUT TAPE 6,799 EL451450
IYY=IYY+1 EL451336 PRINT OUT THE HEADLINE EL451451
IZZ=IZZ+1 EL451337 799 FORMAT (1H1,23X,13HMESH TOPOLOGY,42X,2PHILLMENT PROPERTY TYPES//6(F EL451452
DUMMY(I)=AA(IXX1) EL451338 1H EL NO,5X,4HND-1,5H ND-2,5H ND-3,5H ND-4,5H ND-5,5H ND-6,5H ND-7, EL451453
EL451339 25H ND-8,11X,4HELMT,5H PRES,5H MTRL,5H THCR,5H DTMP,5H TGOY,5H TGOZELAS1454

```


Table VII-1 (contd)

```

3,5R AREA,5H 1-XX,5H 1-YY,5H 1-ZZ,5H FI-Y1//)
717 IF (IMES) 7908,7909,7908
7908 CALL MESC
GO TO 79
7909 CALL MEST
IF (IEER) 300,79,300
79 DO 9000 M=1,11
CALL TPO
IF (INP-1) 9000,5895,5895
5895 WRITE OUTPUT TAPE 6,7959,M,(N1),1=1,8),I,ELT,JPRS,IMFT,ITIC,ITFM
1,JSDY,JSOZ,JARE,JMMX,JMMY,JMMZ,JMFI
9000 CONTINUE
7959 FORMAT (16,4X,815,10X,1215)
CALL SRAT
L1=
DO 461 K=1,IN
IK=ISIR(K)
(KD=IK-1)*IDEG
DO 46 J=1,IDEG
I=IK+J
IBB1=IBB+1
IBO1=IBO+1
N=IA(1BO1)
IF (N) 45,46,46
45 IF (N+1) 451,452,46
451 IA(1BB1)=J
GO TO 453
452 IA(1BB1)=1
453 I=I+1
46 CONTINUE
461 CONTINUE
ISUM=J-1
DO 47 I=1,IND
IBO1=IBO+1
N=IA(1BO1)
IF (N) 47,47,48
48 IF (N-1000)4R1,482,482
482 IBB1=IBB+1
IA(1BB1)=IND
GO TO 47
481 IBB1=IBB+N
IBO1=IBO+I
IA(1BB1)=IA(1BBN)
47 CONTINUE
READ IN EXTERNAL CONCENTRATED LOADS
DO 2310 I=1,IND
IDEF1=IDEF+1
DUMMY(1+4000)=0.
2310 AA(IDEF1)=0.
IF (IP) 300,820,5450
5450 L=0
NTP=IP
8000 IF (L+1000-NTP) 8100,8200,8200
8100 IP=1000
GO TO 1211
8200 IP=NTP+L
1211 READ INPUT TAPE 5,121,(IDUM(I),IDUM(I+1000)+DUMMY(I+2000),1=1,IP)
DO 2311 I=1,IP
ND=IDUM(I)
K0=IDUM(I+1000)
IF (K0-IDF) 326,327,300
326 IF (K0) 300,300,327
327 IF (K0-IN) 328,329,300
328 IF (ND) 300,300,329
329 J=IDEG*(ND-1)+K0
IDEFJ=IDEF+J
AA(IDFJ)=DUMMY(1+2000)
IBBJ=IBB+J
I=IA(1BBJ)
IICJ=IIC+J
2311 DUMMY(1+4000)=DUMMY(I+4000)+AA(IICJ)*DUMMY(1+2000)
121 FORMAT (51A,11-E11,51)
PRINT OUT DISPLACEMENT AND FORCE BOUNDARY CONDITIONS
820 IF (INP-1) 2520,2521,2521
2521 DO 8201 J=1,10FG
IBJ=IBB+J-1
IBRJ=IBB+J-1
IICJ=IIC+J-1
IDEFJ=IDEF+J-1
WRITE OUTPUT TAPE 6,8202,J
8202 FORMAT (1H1,30X,55FORCE AND DISPLACEMENT BOUNDARY CONDITIONS IN
1 INSTRUCTION,15//215H NODE,7X,1HP,12X,3H1RO,4X,3H1RR,6X,1MC,1RX1//)
DO 8203 I=1,IND,IDEG
IBJ=IBB+J-1
IBRJ=IBB+J-1
IICJ=IIC+J-1
IDEFJ=IDEF+J-1
K=I/IDEG+1
DUMMY(K) =AA(10FFI)
IDUM(K+1000)=IA(1BBJ)
IDUM(K+2000)=IA(1BOJ)
8203 DUMMY(K+3000)=AA(IICJ)
WRITE OUTPUT TAPE 6,8214,(K,DUMMY(K),IDUM(K+1000),IDUM(K+2000),
IDUM(K+3000),K=1,IN)
8214 FORMAT (215,E16,4,217,F15.4,10X1)
8201 CONTINUE
L=L+1000
IF (L-NTP) 8000,2517,2517
2517 IP=NTP
2520 DO 8204 I=1,IND
IDFJ=IDEF+J
8204 AA(IDFJ)=DUMMY(1+4000)
C COMPUTE IMPORTANT CONSTANTS
IST=I+ISUM+1
LIST=IST-9000
IF (LIST) 353,354,354
354 WRITE OUTPUT TAPE 6,355,LIST
355 FORMAT (6X,54HDUMMY AREA OVERLAYS COMMON AREA BY 16,19H DECIMAL
LOCATIONS,7X,8TH RECOMPILE BY CHANGING THE EQUIVALENCES OF DUMMY
2ND BR IN LINKS 1 AND 3, RESPECTIVELY.)
353 CALL TICK (ITIM)
CIT=ITIM
CIT=CIT/60.
WRITE OUTPUT TAPE 6,555,CIT
555 FORMAT (16H INPUT LINK TOOK,F7.2,10H SECONDS.)
READ INPUT TAPE 5,2800,TEST
IF (INP-1) 332,332,331
331 N81=XLOC(IA(1))
N82=XLOC(IA(1D+1))
N83=XLOC(IA(1ST+1))
NC1=N81-N82
NC3=N81-N83
WRITE OUTPUT TAPE 6,6666,(I,IA(1),I=1,NC1)
6666 FORMAT (1H1,RHAA BLOCK/1201A1)
WRITE OUTPUT TAPE 6,6667,(I,AA(1),I=1,NC3)
6667 FUKMAI (1H1,RHAA BLOCK/1511A,15.5,4X1)
IF (ERR) 346,332,346
346 READ INPUT TAPE 5,2800,1E51
IF (TEST-CF5) 346,2700,346
2800 FORMAT (7X,45)
342 IF (INX-1) 300,3321,3322
3321 GO TO 2700
3322 CALL CHAIN (2,ITAP)
300 WRITE OUTPUT TAPE 6,6665
6665 FORMAT (1H1,12H INPUT FRKMI)
IFRR=
GO TO 331
END

```

Table VII-2. Source program listing of subroutine ARAN (Link 1)

```

* LABEL
C=I,ARAN
SUBROUTINE ARAN
XELAPLS MESC POINTS
DIMENSION IA(11,AA1),REFM(11),N(110),DUMMY(5000),IDUM(5000),M(8)
L,P(24),HV(24),X(R),Y(R),Z(H),X1(7),Y1(7),Z1(7),RUMMY(27,9)
2,R2(121),S(11),G(1)
COMMON IA,AA
EQUIVALENCE (IA,AA),(AA,9000),DUMMY)
EQUIVALENCE (DUMMY,IDUM,NT,ARUMMY),DUMMY(11),REFM)
EQUIVALENCE (IA(1),IN),(IA(2),IN),(IA(3),IT),(IA(4),KK),(IA(5),
1)PHS),(IA(6),ITYPE),(IA(7),IA(11),IA(8),IDEG),(IA(9),INX),(IA(10),FIARNO10)
2)H),(IA(11),R),(IA(12),IMMX),(IA(13),IMMY),(IA(14),IMMZ),(IA(15),FIARNO11)
3)HFI),(IA(16),IARF),(IA(17),M(11),IA(25),M),(IA(26),ITY),(IA(27),FIARNO12)
4)ISTR),(IA(28),I,ELT),(IA(29),ITFM),(IA(30),ITIC),(IA(31),IMFT),(
5)IA(32),ISUM),(IA(33),IND),(IA(34),INST),(IA(36),INSL),(IA(37),IIS)
6)IRB),(IA(38),IBO1),(IA(39),ICEL),(IA(40),I),(IA(41),J),(IA(42),
7)IA(52),J3),(IA(53),IA(154),IA(155),IA(55),JA),(IA(56),J7),(IA(57),IARNO16)
8)I),(IA(58),JTY),(IA(59),IBO),(IA(60),IBR),(IA(61),ID),(IA(62),FIARNO17)
9)IA),(IA(63),IDT),(IA(64),IDY),(IA(65),ITF),(IA(66),ITAP)
EQUIVALENCE (IA(66),ICAR),(IA(67),ICIX),(IA(68),ICIY),(IA(69),
1)ICIZ),(IA(70),ICF),(IA(71),IX),(IA(72),IYY),(IA(73),IZZ),
2)IA(74),IIC),(IA(75),IDF),(IA(76),IST),(IA(77),IIS)
3),IA(78),IERR),(IA(79),IFRR),(IA(80),IFR),(IA(81),IOT),(IA(82),OG),
4)IA(83),AL1),(IA(84),AL2),(IA(85),AL3),(IA(86),D21),(IA(107),P1),
5)AA(131),HV),(AA(155),X1),(AA(163),Y1),(AA(171),Z1),(AA(179),XD),
6)AA(186),YD),(AA(193),ZD),(AA(351),S),(AA(401),ZGM)
7),IA(42),IPG),(AA(43),IPNG),(AA(44),IPFG),(AA(45),DINS1),(AA(46),I)FIARNO24)
8),IA(47),G1),(AA(48),G2),(AA(49),G3)
EQUIVALENCE (IA(35),ISUM),(IA(301),ISIR)
EQUIVALENCE (AA(302),M),(AA(303),MX),(AA(304),1),(AA(305),IP)
EQUIVALENCE (IARIN,IRIC),(IARIN,IRANO)
I)MNSJIN (IBRC,IBO0),IBAND(BO0),ISIR(540),INX(540),IMIN(540),
IARIN(540,15),ISIR(540)
EQUIVALENCE (DUMMY,ABIN),(DUMMY(8100),ISIR),(DUMMY(8640),INX),
1)DUMMY(9180),IMIN),(DUMMY(8640),ISIR)
CLT=0.
1110 NEP=2
M=ANRO+1
I=RO
GO TO 1130
1120 NEP=1
NEQ=NEQ+1
I=NEQ
1130 IP=I+1
IG=IMAX(I)-IMAX(IP)
IL=IMIN(I)-IMIN(IP)
IT=(IG+IL)/2
1140 MX=IMAX(I)
MX=IMAX(IP)
GO TO 1160
1150 MX=IMAX(IP)
MX=IMAX(I)
1160 IP=IL+1/2
1170 M1=IMIN(IP)
M1=IMIN(I)
GO TO 1190
1180 M1=IMIN(I)
M1=IMIN(IP)
1190 J1=I+1/2
1200 ACI=ARIN(IP,J1)
J1I=I-36/(J1-1)
IP=LFJMINIACH,JBIT)
IF (IP) 1270,1210,1270
1210 IF (IMIN(I)-1) 1220,1230,1220
1220 IF (IMIN(IP)-IP) 1240,1230,1240
1230 I=I+1
1240 IF (IMAX(I)-1) 1250,1260,1250
1250 IF (IMAX(IP)-IP) 1270,1260,1270
1260 IG=IG+1
1270 IF (IG+IL) 1910,1280,1400
1280 NZL=0
NZR=0
DO 1300 J=1,IN

```

Table VII-2 (contd)

<pre> XSAP=0 XN-IN NCYCL=0 NCYCN=IN/10+3 ISURP=ISUR+1 ICYCL=1 DO 80 I=1,90,40,10 10 READ INPUT TAPE 5,1,(ISIRI),I=1,INI 1 FORMAT (20I4) DO 20 I=1,IN 20 ISIRI(I)=I MI=1 MX=IN DO 30 IP=1,IN DO 23 JP=1,IN IF ((SIRI(I)-SIRI(J)))/23,24,23 23 CONTINUE GO TO 3100 24 IF ((I-IP) 25,80,25 25 ISIRI(IP)=SIRI(I) CALL EXCH 80 CONTINUE 30 DO 100 I=1,IN IMINI(I)=0 100 IMAX(I)=0 DO 700 I=1,IN DO 400 J=1,ISIR ACH=ABIN(I,J) DO 300 JB=1,36 IF ((LFIN(ACH,JR)) 420,300,420 300 CONTINUE 400 CONTINUE GO TO 3100 420 IMINI(I)=36*(J-1)+JB JE=ISURP-J DO 600 J=1,JC JB=ISURP-J ACH=ABIN(I,JB) DO 500 JR=1,36 JBC=36-JR+1 IF ((LFIN(ACH,JBC)) 620,500,620 500 CONTINUE 600 CONTINUE GO TO 3100 620 IMAX(I)=36*(JB)-JH+1 700 CONTINUE IF ((ISURF-1) 2010,750,750 750 CALL TICK (ITIM) CRT=ITIM IF ((INP-1) 1100,1100,800 800 CALL OUTPT 1100 NBD=0 NFD=IN NCH=0 ICYCL=ICYCL+1 XSA=IN-IMAX(I) JMAXP=IMAX(I) XMAXP=XMAXP DO 1105 I=2,IN IF ((IMAX(I)-IMAXP) 1105,1105,1102 1102 IMAXP=IMAX(I) XMAXP=XMAXP 1105 XSA=XSA+XN-XMAXP IF (XSA-XSAP) 1106,1106,1107 1106 NCYCL=NCYCL+1 IF (NCYCL-NCYCN) 1108,1108,1985 1107 XSAP=XSA NCYCL=0 1108 CALL TICK (ITIM) CNT=ITIM CNT=(CNT-CRT)/60 IF (CNT-CLT) 1110,1109,1109 1109 CLT=CLT+100 WRITE OUTPUT TAPE 6,3,CNT,ICYCL,XSA IF (CNT-100) 1110,1110,1111 1111 MIPMCH=1+(SIRI(I)-1),INI 3 FORMAT (3H AT,47,2,10H REC. OF RELABELING,16,75H INTERCHANGES DONE) 1, UPPER OFF-DIAGONAL ELEMENT COUNT OF MESH TOPOLOGY MATRIX (S,EP,0) IJ=IP+J IF (IJ-IN) 1290,1290,1310 1290 IF ((MIN(IJ)-MIN) 1500,1500,1320 1300 CONTINUE 1310 MNN=IN GO TO 1330 1320 MNN=MIN(IJ)-1 1330 DO 1350 J=1,IP JI=J-J IF (JI-1) 1360,1360,1360 1360 IF ((MAX(JI)-MXM) 1360,1360,1360 1370 CONTINUE 1380 MXA=1 GO TO 1370 1380 MXB=IMAX(JI)+1 1370 IF (MNN-NIM) 1410,1375,1375 1375 IF (MNN-1) 1390,1380,1380 </pre>	<pre> FIARN036 FIARN037 FIARN038 FIARN039 FIARN040 FIARN041 FIARN042 FIARN043 FIARN044 FIARN045 FIARN046 FIARN047 FIARN048 FIARN049 FIARN050 FIARN051 FIARN052 FIARN053 FIARN054 FIARN055 FIARN056 FIARN057 FIARN058 FIARN059 FIARN060 FIARN061 FIARN062 FIARN063 FIARN064 FIARN065 FIARN066 FIARN067 FIARN068 FIARN069 FIARN070 FIARN071 FIARN072 FIARN073 FIARN074 FIARN075 FIARN076 FIARN077 FIARN078 FIARN079 FIARN080 FIARN081 FIARN082 FIARN083 FIARN084 FIARN085 FIARN086 FIARN087 FIARN088 FIARN089 FIARN090 FIARN091 FIARN092 FIARN093 FIARN094 FIARN095 FIARN096 FIARN097 FIARN098 FIARN099 FIARN100 FIARN101 FIARN102 FIARN103 FIARN104 FIARN105 FIARN106 FIARN107 FIARN108 FIARN109 FIARN110 FIARN111 FIARN112 FIARN113 FIARN114 FIARN115 FIARN116 FIARN117 FIARN118 FIARN119 FIARN120 FIARN121 FIARN122 FIARN123 FIARN124 FIARN125 FIARN126 FIARN127 FIARN128 FIARN129 FIARN130 FIARN131 FIARN132 FIARN133 FIARN134 FIARN135 FIARN136 FIARN137 FIARN138 FIARN139 FIARN140 FIARN141 FIARN142 FIARN143 FIARN144 FIARN145 FIARN146 FIARN147 </pre>	<pre> 1300 MNN=I-1 GO TO 1370 1390 DO 1400 J=MIN,MNN JJ=J-1/36 JJP=JJ+1 ACH=ABIN(I,JJP) JRI=J-36*JJ IF ((LFIN(ACH,JRI)) 1395,1393,1395 1393 NZG=NZG+1 1395 ACH=ABIN(IP,JJP) JRI=J-36*JJ IF ((LFIN(ACH,JRI)) 1400,1397,1400 1397 NZL=NZL+1 1400 CONTINUE 1410 IF (MXB-MXM) 1415,1415,1460 1415 IF (MXB-IP) 1420,1420,1430 1420 MXR=IP+1 GO TO 1410 1430 DO 1450 J=MXB,MXM JJ=J-1/36+1 ACH=ABIN(I,JJ) ACH=ABIN(IP,JJ) JRI=J-36*(JJ-1) IF ((LFIN(ACH,JRI)) 1440,1435,1440 1435 NZL=NZL+1 1440 IF ((LFIN(ACH,JRI)) 1450,1445,1450 1445 NZG=NZG+1 1450 CONTINUE 1460 IF (NZG-NZL) 1910,1910,1480 1480 ICYCL=ICYCL+1 CALL EXCH NCH=ISIR(I) ISIR(I)=ISIR(IP) IF (IIP) 1720,1430,1720 1630 IF ((MAX(IP)-IP) 1650,1640,1650 1650 IMAX(IP)=IMAX(IP)-1 1650 IF ((MAX(I)-I) 1670,1660,1670 1660 IMAX(I)=IMAX(I)+1 1670 IF ((MIN(I)-I) 1690,1680,1690 1690 IMIN(I)=IMIN(I)+1 1690 IF ((MIN(IP)-IP) 1720,1710,1720 1710 IMIN(IP)=IMIN(IP)-1 1720 NCH=IMAX(I) IMAX(IP)=IMAX(IP) IMAX(I)=NCH NCH=IMIN(I) IMIN(IP)=IMIN(IP) IMIN(I)=NCH DO 1900 J=MI,MX IF ((I-J)=IP-J) 1740,1900,1740 1740 IF (J-I) 1810,1900,1750 1750 IF ((MIN(J)-I) 1780,1760,1780 1760 JJ=J-1/36+1 ACH=ABIN(I,JJ) JRI=J-36*(JJ-1) IF ((LFIN(ACH,JRI)) 1900,1770,1900 1770 IMINI(J)=IMINI(J)+1 GO TO 1900 1780 IF ((MIN(J)-IP) 1900,1790,1900 1790 IMINI(J)=IMINI(J)-1 SD TO 1900 1810 IF ((MAX(J)-I) 1830,1820,1830 1820 IMAX(J)=IMAX(J)+1 GO TO 1900 1830 IF ((MAX(J)-IP) 1900,1840,1900 1840 JJ=J-1/36+1 ACH=ABIN(IP,JJ) JRI=J-36*(JJ-1) IF ((LFIN(ACH,JRI)) 1900,1850,1900 1850 IMAX(J)=IMAX(J)-1 1900 CONTINUE 1910 IF (MBO-NBO) 1960,1970,1970 1960 GO TO (1110,1120),NFP 1970 IF (MBO) 1100,1980,1100 1980 CONTINUE 1985 IF (INP-1) 2005,2005,1990 1990 CALL OUTPT 2005 CALL TICK (ITIM) CNT=ITIM CNT=(CNT-CRT)/60 WRITE OUTPUT TAPE 6,3,CNT,ICYCL,XSA DO 2100 I=1,NBO IP=I+1 IF ((MAX(IP)-IMAX(I)) 2030,2100,2100 2100 CONTINUE IF ((ISURF-1) 3000,2300,2300 2300 PUNCH 1,(SIRI(I),IMAX(I),I=1,IN) 3000 RETURN 3100 WRITE OUTPUT TAPE 6,4,1 4 FORMAT (10H THE POINT,15,35H DOES NOT APPEAR IN MESH TOPOLOGY) GO TO 3000 END </pre>	<pre> FIARN148 FIARN149 FIARN150 FIARN151 FIARN152 FIARN153 FIARN154 FIARN155 FIARN156 FIARN157 FIARN158 FIARN159 FIARN160 FIARN161 FIARN162 FIARN163 FIARN164 FIARN165 FIARN166 FIARN167 FIARN168 FIARN169 FIARN170 FIARN171 FIARN172 FIARN173 FIARN174 FIARN175 FIARN176 FIARN177 FIARN178 FIARN179 FIARN180 FIARN181 FIARN182 FIARN183 FIARN184 FIARN185 FIARN186 FIARN187 FIARN188 FIARN189 FIARN190 FIARN191 FIARN192 FIARN193 FIARN194 FIARN195 FIARN196 FIARN197 FIARN198 FIARN199 FIARN200 FIARN201 FIARN202 FIARN203 FIARN204 FIARN205 FIARN206 FIARN207 FIARN208 FIARN209 FIARN210 FIARN211 FIARN212 FIARN213 FIARN214 FIARN215 FIARN216 FIARN217 FIARN218 FIARN219 FIARN220 FIARN221 FIARN222 FIARN223 FIARN224 FIARN225 FIARN226 FIARN227 FIARN228 FIARN229 FIARN230 FIARN231 FIARN232 FIARN233 FIARN234 FIARN235 FIARN236 FIARN237 FIARN238 FIARN239 FIARN240 FIARN241 FIARN242 FIARN243 FIARN244 FIARN245 FIARN246 FIARN247 FIARN248 FIARN249 FIARN250 FIARN251 FIARN252 FIARN253 FIARN254 FIARN255 FIARN256 FIARN257 FIARN258 FIARN259 FIARN260 FIARN261 FIARN262 </pre>
--	--	---	---

Table VII-3. Source program listing of subroutine BUNG (Link 1)

```

* LABEL
CEIBUNG
SUBROUTINE BUNG
C DUMMY SUBROUTINE FOR BOUNDARY CONDITION GENERATOR
RETURN
END
FIARN000
FIARN001
FIARN002
FIARN003
FIARN004

```

Table VII-4. Source program listing of subroutine COOR (Link 1)

```

* LABEL
CEICOR
SUBROUTINE COOR
  READS AND STORES COORDINATES
  DIMENSION IA(11,AA(1)),REM(13),NT(10),DUMMY(5000),IDUM(5000),N(8)
  1,P(24),UV(24),X(8),Y(8),Z(8),XD(7),YD(7),ZD(7),RUMMY(27,9)
  2,DZ(12),S(1),G(1)
  COMMON IA,AA
  EQUIVALENCE (IA,AA),(AA( 9000),DUMMY)
  EQUIVALENCE (DUMMY,IDUM,NT,RUMMY),(DUMMY(1),REM)
  EQUIVALENCE (IA(1),IN),(IA(2),IMN),(IA(3),IT),(IA(4),IP),(IA(5),
  1)PS),(IA(6),ITYPE),(IA(7),IMAF),(IA(8),IDEG),(IA(9),INX),(IA(10),EICOR01
  2)H),(IA(11),IB),(IA(12),IMMZ),(IA(13),IMMY),(IA(14),IMZ),(IA(15),EICOR01
  3)MFI),(IA(16),JARE),(IA(17),IN1),(IA(18),P),(IA(19),IT),(IA(20),EICOR01
  4)STR),(IA(21),IFL),(IA(22),ITM),(IA(23),IIC),(IA(24),IMET),EICOR01
  5)IA(25),ISUM),(IA(26),IND),(IA(27),IMS),(IA(28),IUS),(IA(29),
  6)ORD),(IA(30),IDRO),(IA(31),ACEL),(IA(32),J1),(IA(33),J2),EICOR01
  7)IA(34),J3),(IA(35),J4),(IA(36),J5),(IA(37),J6),(IA(38),J7),(IA(39),EICOR01
  8),J8),(IA(39),JTY),(IA(40),I80),(IA(41),I81),(IA(42),EICOR01
  9)IA),(IA(43),IDT),(IA(44),IDY),(IA(45),IIF),(IA(46),ITAP),EICOR01
  EQUIVALENCE (IA(66),ICAR),(IA(67),ICF),(IA(68),ICV),(IA(69),
  1)ICF),(IA(70),ICF),(IA(71),IX),(IA(72),IY),(IA(73),IZ),EICOR02
  2)IA(74),IIC),(IA(75),IDF),(IA(76),IST),(IA(77),IIS),EICOR02
  3),(IA(78),IRFM),(IA(79),IRK),(IA(80),IR),(IA(81),IR),(IA(82),OG),EICOR02
  4)AA(83),ALL),(AA(84),AL2),(AA(85),AL3),(AA(86),O21),(AA(107),P),EICOR02
  5)AA(131),UV),(AA(155),X),(AA(163),Y),(AA(171),Z),(AA(179),XD),EICOR02
  6)AA(186),YD),(AA(193),ZD),(AA(251),S),(AA(40),ZGM),EICOR02
  7)AA(42),INP),(AA(43),IPBG),(AA(44),IPFN),(AA(45),CONS),(AA(46),EICOR02
  8),(AA(47),G1),(AA(48),G2),(AA(49),G3),EICOR02
  EQUIVALENCE (IA(349),NTIC),(IA(349),ISD1),(IA(347),ISPY),(IA(346),EICOR02
  1),ISD2),(IA(345),J9),(IA(344),J10),(IA(343),JPRS),(IA(342),JSDY),EICOR02
  2),(IA(341),JSDZ),(IA(340),JARE),(IA(339),JMMX),(IA(338),JMMY),EICOR02
  3),(IA(337),JMMZ),(IA(336),JMP1),(IA(335),ITAS),(IA(334),IN7),EICOR02
  4),(IA(333),IPR1),(AA(332),UGY),(AA(331),OGZ),(AA(330),PRES),EICOR02
  5),(IA(329),IPR)
  IARR=0
  LE0
  831 INTE=INT(L-1)/2
  INTE=2*(INTE+1)
  IF (INT(-1000) 833,833,832
  832 INTE=1000
  833 READ INPUT TAPE 5,102,(IDUM(1),DUMMY(1+1000),DUMMY(1+2000),DUMMY
  1)I+3000),I-1,-INTE)
  102 FORMAT (2I14,3E12.7)
  I=0
  8314 I=I+1
  IF (I-INTE) 8315,8315,831
  8315 IF (IDUM(I)) 300,8314,8314
  8316 IF (DUMMY(I)-L-1) 300,1061,300
  1061 I=I+1
  IXXL=IX+L
  IYYL=IY+L
  IZZL=IZ+L
  AA(IXL)=DUMMY(I+1000)
  AA(IYL)=DUMMY(I+2000)
  1063 IF (IGEM-1) 1062,1063,300
  AA(IZZL)=DUMMY(I+3000)
  1062 IF (L-IN) 8314,8314,300
  5050 RETURN
  300 IERR=1
  GO TO 5050
  END
  
```

Table VII-5. Source program listing of subroutine CORG (Link 1)

```

* LABEL
CEICORG
SUBROUTINE CORG
  DUMMY SUBROUTINE FOR COORDINATE GENERATOR
  RETURN
  END
  
```

```

EICOR000
EICOR001
EICOR002
EICOR003
EICOR004
EICOR005
EICOR006
EICOR007
EICOR008
EICOR009
EICOR010
EICOR011
EICOR012
EICOR013
EICOR014
EICOR015
EICOR016
EICOR017
EICOR018
EICOR019
EICOR020
EICOR021
EICOR022
EICOR023
EICOR024
EICOR025
EICOR026
EICOR027
EICOR028
EICOR029
EICOR030
EICOR031
EICOR032
EICOR033
EICOR034
EICOR035
EICOR036
EICOR037
EICOR038
EICOR039
EICOR040
EICOR041
EICOR042
EICOR043
EICOR044
EICOR045
EICOR046
EICOR047
EICOR048
EICOR049
EICOR050
EICOR051
EICOR052
EICOR053
EICOR054
EICOR055
EICOR056
EICOR057
EICOR058
EICOR059
EICOR060
  
```

Table VII-6. Source program listing of subroutine EXCH (Link 1)

```

* LABEL
CEIEXC
SUBROUTINE EXCH
  INTERCHANGES CONSECUTIVE ROWS AND COLUMNS OF CONNECTIVITY MATRIX
  COMMON AA
  EQUIVALENCE (AA( 9000),ARIN)
  EQUIVALENCE (AA(302),MT),(AA(303),MX),(AA(304),I),(AA(305),IP)
  DIMENSION ARIN(40,15)
  JMI=(MI-1)/36+1
  JMX=(MX-1)/36+1
  OJ 100 K=JMI,JMX
  ACH=ARIN(I,K)
  ARIN(I,K)=ARIN(IP,K)
  100 ARIN(IP,K)=ACH
  J=I-1/36+1
  JB=(J-1)/36+1
  JP=(J-1)/36+1
  JPB=JP-36*(JP-1)
  IF (J-JP) 150,250,150
  150 DO 200 K=MI,MX
  ACH=ARIN(K,J)
  BCH=ARIN(K,JP)
  NCH=LEBIN(ACH,JB)
  NCT=LEBIN(BCH,JPB)
  CALL SEBIN (ACH,JB,NCT)
  CALL SEBIN (BCH,JPB,NCH)
  ARIN(K,J)=ACH
  200 ARIN(K,JP)=BCH
  GO TO 400
  250 DO 300 K=MI,MX
  ACH=ARIN(K,J)
  NCH=LEBIN(ACH,JB)
  NCT=LEBIN(ACH,JPB)
  CALL SEBIN (ACH,JB,NCT)
  CALL SEBIN (BCH,JPB,NCH)
  300 ARIN(K,J)=ACH
  400 RETURN
  END
  
```

Table VII-7. Source program listing of function LEBIN and subroutine SEBIN (Link 1)

```

* FAP
COUNT 100
LEBL CLEED
REW
* THIS SUBPROGRAM IS CALLED USING FORTRAN 'SUBROUTINE' CONVENTIONS.
* CALLING SEQUENCE IS...
* CALL SEBIN(A,I,N)
* WHERE 'A' IS THE NAME OF A WORD (VARIABLE).
* 'I' IS THE INTEGER SPECIFYING DESIRED BIT (1-36) IN 'A'.
* 'N' IS A FORTRAN INTEGER ONE OR ZERO INDICATING THE NEW
* VALUE OF THE I' TH BIT OF 'A'.
  REM
  ENTRY SEBIN
  ENTRY LEBIN
  REM
  EVEN
  NAC
  SFBIN EQU *
  STJ INDKR SAVE INDICATORS
  SXA SAVX1+1 AND XR1
  LDI* 1,4 RESET
  CLAP* 2,4
  PDC *
  ZETP 3,4 DO WE SET OR RESET
  TRA SET SET
  RIS TABLE,1 RESET
  TRA EXIT
  EVEN
  SET OSI TABLE,1
  EXIT STI* 1,4
  SAVX1 AXT **,-1
  LDI INDKTR
  TRA 4,4
  REM
  INDKTR PZE **
  TABLE PZE 0
  WZF
  DEC 1B1,1B2,1B3,1B4,1B5,1B6,1B7,1B8,1B9,1B10,1B11,1B12
  DEC 1B13,1B14,1B15,1B16,1B17,1B18,1B19,1B20,1B21,1B22
  DEC 1B23,1B24,1B25,1B26,1B27,1B28,1B29,1B30,1B31,1B32
  DEC 1B33,1B34,1B35
  SPACE 4
  * A FUNCTION SUBPROGRAM...
  * CALLING SEQUENCE 'X=LEBIN(A,I)'.
  * WHERE 'X' IS THE NAME OF A VARIABLE
  * 'I' IS A FORTRAN INTEGER SPECIFYING THE DESIRED BIT IN 'A'.
  * ON RETURN THE CALLER THE AC CONTAINS A FORTRAN INTEGER
  * ONE OR ZERO DEPENDING ON WHETHER I' TH BIT OF 'A' IS
  * ONE OR ZERO.
  REM
  EQU *
  LEBIN SXA LEBX1,1
  CAL* 2,4 THIS BIT
  PDC ,1
  CAL* 1,4
  ANA TABLE,1
  TZE LEBX1
  CAL ONE
  LEBX1 AXT **,1
  TRA 3,4
  RFM
  ONE PZE **,1 A FORTRAN I I 1
  END
  
```

Table VII-8. Source program listing of subroutine MESHG (Link 1)

```
* LABEL
CEIMFS SUBROUTINE MESHG
C DUMMY SUBROUTINE FOR MESH GENERATOR
RETURN
END
FIMFS000
FIMFS001
FIMFS002
FIMFS003
FIMFS004
FIMFS005
FIMFS006
FIMFS007
FIMFS008
FIMFS009
FIMFS010
FIMFS011
FIMFS012
FIMFS013
FIMFS014
FIMFS015
FIMFS016
FIMFS017
FIMFS018
FIMFS019
FIMFS020
FIMFS021
FIMFS022
FIMFS023
FIMFS024
FIMFS025
FIMFS026
FIMFS027
FIMFS028
FIMFS029
FIMFS030
FIMFS031
FIMFS032
FIMFS033
FIMFS034
FIMFS035
FIMFS036
FIMFS037
FIMFS038
FIMFS039
FIMFS040
FIMFS041
FIMFS042
FIMFS043
FIMFS044
```

Table VII-9. Source program listing of subroutine MEST (Link 1)

```
* LABEL
CEIMFS SUBROUTINE MEST
C READS AND STORES MESH TOPOLOGY DATA
DIMENSION IA(1),AA(1),REM(13),NT(10),DUMMY(5000),IDUM(5000),N(8)
1,P(24),UV(24),X(8),Y(8),Z(8),XD(7),YE(7),ZD(7),RUMMY(27,9)
2,D(21),S(1),G(1)
COMMON JA,AA
EQUIVALENCE (IA,AA),(AA(9000),DUMMY)
EQUIVALENCE (DUMMY,IDUM,NT,RUMMY),(DUMMY(1)),REFM)
EQUIVALENCE (IA(1),IN),(IA(2),IHN),(IA(3),IT),(IA(4),IP),(IA(5),
1,IPRS),(IA(6),ITYPE),(IA(7),IMAT),(IA(8),IDEG),(IA(9),INX),(IA(10),FIM
2,IM),(IA(11),IB),(IA(12),IMMX),(IA(13),IMMY),(IA(14),IMM2),(IA(15),FIM
3,IMF1),(IA(16),IARE),(IA(17),NLI),(IA(18),M1),(IA(19),ITP),(IA(20),
4,ISTR),(IA(21),IFL1),(IA(22),IFPM),(IA(23),ITIC),(IA(24),IMF1),
5,(IA(25),ISUM),(IA(26),IND),(IA(27),IMS),(IA(28),IDS),(IA(29),
6,INDR),(IA(30),IDRD),(IA(31),ACEL),(IA(32),J1),(IA(33),J2),
7,(IA(34),J3),(IA(35),J4),(IA(36),J5),(IA(37),J6),(IA(38),J7),(IA(39),
8),J8),(IA(40),JTY),(IA(41),IRB),(IA(42),IRD),(IA(43),IID),(IA(44),
9,IA),(IA(45),IDT),(IA(46),IDY),(IA(47),ITE),(IA(48),ITAP)
EQUIVALENCE (IA(49),ICAR),(IA(50),ICR),(IA(51),IC1),(IA(52),IC2),(IA(53),
1,IC12),(IA(54),ICF1),(IA(55),ICF2),(IA(56),ICX),(IA(57),ICY),(IA(58),
2,(IA(59),IC1),(IA(60),ICF1),(IA(61),IST),(IA(62),IIS)
3,(IA(63),IGFM),(IA(64),IGFR),(IA(65),IGT),(IA(66),IGT),(IA(67),IGT),
4,(AA(83),AL1),(AA(84),AL2),(AA(85),AL3),(AA(86),B21),(AA(87),P),
5,(AA(131),UV1),(AA(155),X),(AA(163),Y),(AA(171),Z),(AA(179),XD),
6,(AA(186),YD),(AA(193),ZD),(AA(351),S),(AA(40),ZGEM)
7,(AA(42),INP),(AA(43),IPBS),(AA(44),IPFN),(AA(45),CONS),(AA(46),I
8),(IA(47),G1),(AA(48),G2),(AA(49),G3)
EQUIVALENCE (IA(349),NTIC),(IA(348),ISDT),(IA(347),ISDY),(IA(346)
1,ISDZ),(IA(345),J9),(IA(344),J10),(IA(343),JPRS),(IA(342),JSDY)
2,(IA(341),JSDZ),(IA(340),JARE),(IA(339),JMMX),(IA(338),JMMY)
3,(IA(337),JMM2),(IA(336),JMF1),(IA(335),JIAS),(IA(334),IDZ)
4,(IA(333),IPR),(AA(332),OGY),(AA(331),OGZ),(AA(330),PRFS)
5,(IA(329),IPR)
ERR=0
M=0
MT=0
L=0
NRE=-19
NF=0
7910 C=1
7911 IF (L-NF) 7912,7912,7913
7913 NRE=NRE+20
NF=NF+20
79 READ INPUT TAPE 5,791,(IDUM(1),I=NRE,NF)
79) FORMAT (20I4)
7912 IF (IDUM(1)) 7921,7910,7924
7921 IF (L-NF) 7914,7912,7913
7924 IF (L-ERR) 300,300,7925
7925 L=L-1
MT=-1
ERR=0
7914 M=M+1
MT=1
IF (MT-999) 7916,7915,300
7915 ERR=1
7916 IF (M+IDUM(L)) 300,7917,300
7917 I=LT+IDUM(L)/100
IF (I+I*IFLT-19) 7918,300,300
7918 GO TO (81,82,81,83,84,85,84,85,86,87,84,85,84,85,84,85,81,81),IFLT
81 JK=5
JN=2
GO TO 89
82 JK=6
JN=2
END
FIMFS000
FIMFS001
FIMFS002
FIMFS003
FIMFS004
FIMFS005
FIMFS006
FIMFS007
FIMFS008
FIMFS009
FIMFS010
FIMFS011
FIMFS012
FIMFS013
FIMFS014
FIMFS015
FIMFS016
FIMFS017
FIMFS018
FIMFS019
FIMFS020
FIMFS021
FIMFS022
FIMFS023
FIMFS024
FIMFS025
FIMFS026
FIMFS027
FIMFS028
FIMFS029
FIMFS030
FIMFS031
FIMFS032
FIMFS033
FIMFS034
FIMFS035
FIMFS036
FIMFS037
FIMFS038
FIMFS039
FIMFS040
FIMFS041
FIMFS042
FIMFS043
FIMFS044
FIMFS045
FIMFS046
FIMFS047
FIMFS048
FIMFS049
FIMFS050
FIMFS051
FIMFS052
FIMFS053
FIMFS054
FIMFS055
FIMFS056
FIMFS057
FIMFS058
FIMFS059
FIMFS060
FIMFS061
FIMFS062
FIMFS063
FIMFS064
FIMFS065
FIMFS066
FIMFS067
FIMFS068
FIMFS069
FIMFS070
FIMFS071
FIMFS072
FIMFS073
FIMFS074
FIMFS075
FIMFS076
FIMFS077
FIMFS078
FIMFS079
FIMFS080
FIMFS081
FIMFS082
FIMFS083
FIMFS084
FIMFS085
FIMFS086
FIMFS087
FIMFS088
FIMFS089
FIMFS090
FIMFS091
FIMFS092
FIMFS093
FIMFS094
FIMFS095
FIMFS096
FIMFS097
FIMFS098
FIMFS099
FIMFS100
FIMFS101
FIMFS102
FIMFS103
FIMFS104
FIMFS105
FIMFS106
FIMFS107
FIMFS108
FIMFS109
FIMFS110
FIMFS111
FIMFS112
FIMFS113
FIMFS114
FIMFS115
FIMFS116
FIMFS117
FIMFS118
FIMFS119
FIMFS120
FIMFS121
FIMFS122
FIMFS123
FIMFS124
FIMFS125
FIMFS126
FIMFS127
FIMFS128
FIMFS129
FIMFS130
```

Table VII-10. Source program listing of subroutine OUTPT (Link 1)

```
* LABEL
CEIOUT SUBROUTINE OUTPT
C WRITES INFORMATION RELATED WITH REMELLING
DIMENSION IA(1),AA(1),REM(13),NT(10),DUMMY(5000),IDUM(5000),N(8)
1,P(24),UV(24),X(8),Y(8),Z(8),XD(7),YE(7),ZD(7),RUMMY(27,9)
2,D(21),S(1),G(1)
COMMON JA,AA
EQUIVALENCE (IA,AA),(AA(9000),DUMMY)
EQUIVALENCE (DUMMY,IDUM,NT,RUMMY),(DUMMY(1)),REFM)
EQUIVALENCE (IA(1),IN),(IA(2),IHN),(IA(3),IT),(IA(4),IP),(IA(5),
1,IPRS),(IA(6),ITYPE),(IA(7),IMAT),(IA(8),IDEG),(IA(9),INX),(IA(10),FIM
2,IM),(IA(11),IB),(IA(12),IMMX),(IA(13),IMMY),(IA(14),IMM2),(IA(15),FIM
3,IMF1),(IA(16),IARE),(IA(17),NLI),(IA(18),M1),(IA(19),ITP),(IA(20),
4,ISTR),(IA(21),IFL1),(IA(22),IFPM),(IA(23),ITIC),(IA(24),IMF1),
5,(IA(25),ISUM),(IA(26),IND),(IA(27),IMS),(IA(28),IDS),(IA(29),
6,INDR),(IA(30),IDRD),(IA(31),ACEL),(IA(32),J1),(IA(33),J2),
7,(IA(34),J3),(IA(35),J4),(IA(36),J5),(IA(37),J6),(IA(38),J7),(IA(39),
8),J8),(IA(40),JTY),(IA(41),IRB),(IA(42),IRD),(IA(43),IID),(IA(44),
9,IA),(IA(45),IDT),(IA(46),IDY),(IA(47),ITE),(IA(48),ITAP)
EQUIVALENCE (IA(49),ICAR),(IA(50),ICR),(IA(51),IC1),(IA(52),IC2),(IA(53),
1,IC12),(IA(54),ICF1),(IA(55),ICF2),(IA(56),ICX),(IA(57),ICY),(IA(58),
2,(IA(59),IC1),(IA(60),ICF1),(IA(61),IST),(IA(62),IIS)
3,(IA(63),IGFM),(IA(64),IGFR),(IA(65),IGT),(IA(66),IGT),(IA(67),IGT),
4,(AA(83),AL1),(AA(84),AL2),(AA(85),AL3),(AA(86),B21),(AA(87),P),
5,(AA(131),UV1),(AA(155),X),(AA(163),Y),(AA(171),Z),(AA(179),XD),
6,(AA(186),YD),(AA(193),ZD),(AA(351),S),(AA(40),ZGEM)
7,(AA(42),INP),(AA(43),IPBS),(AA(44),IPFN),(AA(45),CONS),(AA(46),I
8),(IA(47),G1),(AA(48),G2),(AA(49),G3)
EQUIVALENCE (IA(349),NTIC),(IA(348),ISDT),(IA(347),ISDY),(IA(346)
1,ISDZ),(IA(345),J9),(IA(344),J10),(IA(343),JPRS),(IA(342),JSDY)
2,(IA(341),JSDZ),(IA(340),JARE),(IA(339),JMMX),(IA(338),JMMY)
3,(IA(337),JMM2),(IA(336),JMF1),(IA(335),JIAS),(IA(334),IDZ)
4,(IA(333),IPR),(AA(332),OGY),(AA(331),OGZ),(AA(330),PRFS)
5,(IA(329),IPR)
ERR=0
M=0
MT=0
L=0
NRE=-19
NF=0
7910 C=1
7911 IF (L-NF) 7912,7912,7913
7913 NRE=NRE+20
NF=NF+20
79 READ INPUT TAPE 5,791,(IDUM(1),I=NRE,NF)
79) FORMAT (20I4)
7912 IF (IDUM(1)) 7921,7910,7924
7921 IF (L-NF) 7914,7912,7913
7924 IF (L-ERR) 300,300,7925
7925 L=L-1
MT=-1
ERR=0
7914 M=M+1
MT=1
IF (MT-999) 7916,7915,300
7915 ERR=1
7916 IF (M+IDUM(L)) 300,7917,300
7917 I=LT+IDUM(L)/100
IF (I+I*IFLT-19) 7918,300,300
7918 GO TO (81,82,81,83,84,85,84,85,86,87,84,85,84,85,84,85,81,81),IFLT
81 JK=5
JN=2
GO TO 89
82 JK=6
JN=2
END
FIMFS000
FIMFS001
FIMFS002
FIMFS003
FIMFS004
FIMFS005
FIMFS006
FIMFS007
FIMFS008
FIMFS009
FIMFS010
FIMFS011
FIMFS012
FIMFS013
FIMFS014
FIMFS015
FIMFS016
FIMFS017
FIMFS018
FIMFS019
FIMFS020
FIMFS021
FIMFS022
FIMFS023
FIMFS024
FIMFS025
FIMFS026
FIMFS027
FIMFS028
FIMFS029
FIMFS030
FIMFS031
FIMFS032
FIMFS033
FIMFS034
FIMFS035
FIMFS036
FIMFS037
FIMFS038
FIMFS039
FIMFS040
FIMFS041
FIMFS042
FIMFS043
FIMFS044
FIMFS045
FIMFS046
FIMFS047
FIMFS048
FIMFS049
FIMFS050
FIMFS051
FIMFS052
FIMFS053
FIMFS054
FIMFS055
FIMFS056
FIMFS057
FIMFS058
FIMFS059
FIMFS060
FIMFS061
FIMFS062
FIMFS063
FIMFS064
FIMFS065
FIMFS066
FIMFS067
FIMFS068
FIMFS069
FIMFS070
FIMFS071
FIMFS072
FIMFS073
FIMFS074
FIMFS075
FIMFS076
FIMFS077
FIMFS078
FIMFS079
FIMFS080
FIMFS081
FIMFS082
FIMFS083
FIMFS084
FIMFS085
FIMFS086
FIMFS087
FIMFS088
FIMFS089
FIMFS090
FIMFS091
FIMFS092
FIMFS093
FIMFS094
FIMFS095
FIMFS096
FIMFS097
FIMFS098
FIMFS099
FIMFS100
FIMFS101
FIMFS102
FIMFS103
FIMFS104
FIMFS105
FIMFS106
FIMFS107
FIMFS108
FIMFS109
FIMFS110
FIMFS111
FIMFS112
FIMFS113
FIMFS114
FIMFS115
FIMFS116
FIMFS117
FIMFS118
FIMFS119
FIMFS120
FIMFS121
FIMFS122
FIMFS123
FIMFS124
FIMFS125
FIMFS126
FIMFS127
FIMFS128
FIMFS129
FIMFS130
```

Table VII-11. Source program listing of subroutine SRAT (Link 1)

```

* LABEL
CF15RT
C SUPROUTINE SRAT F1SR1000 KN=0 F1SR1064
GENERATES CONNECTIVITY MATRIX AND PRECISES TOPOLOGY OF STIFF.MAT. F1SR1001 F1SR1065
DIMENSION I(A(1),JA(1)),RE(1:15),N(1:15),DUMMY(15*10),IDUM(15*10),N(8) F1SR1002 F1SR1066
1-PE(24),UV(24),X(8),Y(8),Z(8),XP(7),YP(7),ZP(7),SUMMY(27*9) F1SR1003 F1SR1067
2-DZ(12),S(11),G(11) F1SR1004 F1SR1068
COMMON IA,AA F1SR1005 9711 KN=KN+1 F1SR1069
EQUIVALENCE (IA,AA),(AA, 9090),DUMMY) F1SR1006 971 CONTINUE F1SR1070
EQUIVALENCE (DUMMY,IDUM,NT,RUMMY),(DUMMY(11),REM) F1SR1007 F1SR1071
EQUIVALENCE (IA(1),IN),(IA(2),INB),(IA(3),IT),(IA(4),IP),(IA(5), F1SR1008 F1SR1072
IPRS),(IA(6),ITYPE),(IA(7),IMAT),(IA(8),IDEG),(IA(9),IMS),(IA(10), F1SR1009 F1SR1073
2EN),(IA(11),I8),(IA(12),IMXX),(IA(13),IMMY),(IA(14),IMW2),(IA(15),F1SR1010 F1SR1074
3MFI),(IA(16),IAR5),(IA(17),N(1)),(IA(18),M),(IA(19),IY),(IA(20),F1SR1011 F1SR1075
4ISTR),(IA(21),IEL1),(IA(22),ITEM),(IA(23),ITIC),(IA(24),IYF1), F1SR1012 F1SR1076
5(IA(25),ISUM),(IA(26),IND),(IA(27),IMS),(IA(28),I55),(IA(29), F1SR1013 F1SR1077
6TORO),(IA(30),TORO1),(IA(31),ACSL),(IA(32),J1),(IA(33),J2), F1SR1014 F1SR1078
7(IA(34),J3),(IA(35),J4),(IA(36),J5),(IA(37),J6),(IA(38),J7),(IA(39),F1SR1015 F1SR1079
8),(JA(1),I8),(IA(59),JY),(IA(60),JZ),(IA(61),JRO),(IA(62),IT1),(IA(62),F1SR1016 F1SR1080
9(IA(63),IDT),(IA(64),IDY),(IA(65),IDZ),(IA(66),ID1),(IA(67),ID2),F1SR1017 F1SR1081
EQUIVALENCE (IA(66),ICAR),(IA(67),ICTX),(IA(68),IC1),(IA(69), F1SR1018 F1SR1082
1ICIZ),(IA(70),ICF),(IA(71),IXX),(IA(72),IYY),(IA(73),IZZ), F1SR1019 F1SR1083
2(IA(74),ICC),(IA(75),IDFF),(IA(76),IST),(IA(77),IIS) F1SR1020 F1SR1084
3(IA(78),IGF),(IA(79),IFRR),(IA(80),IF1),(IA(81),DT),(IA(82),DG), F1SR1021 F1SR1085
4(IA(83),AL1),(IA(84),AL2),(IA(85),AL3),(IA(86),AL4),(IA(87),AL5),F1SR1022 F1SR1086
5(IA(88),AL6),(IA(89),AL7),(IA(90),AL8),(IA(91),AL9),(IA(92),AL10),F1SR1023 F1SR1087
6(IA(93),AL11),(IA(94),AL12),(IA(95),AL13),(IA(96),AL14),(IA(97),AL15),F1SR1024 F1SR1088
7(IA(98),AL16),(IA(99),AL17),(IA(100),AL18),(IA(101),AL19),(IA(102),AL20),F1SR1025 F1SR1089
8(IA(103),AL21),(IA(104),AL22),(IA(105),AL23),(IA(106),AL24),(IA(107),AL25),F1SR1026 F1SR1090
9(IA(108),AL26),(IA(109),AL27),(IA(110),AL28),(IA(111),AL29),(IA(112),AL30),F1SR1027 F1SR1091
EQUIVALENCE (IA(349),NTIC),(IA(350),ISOT),(IA(351),ISY),(IA(352),F1SR1028 F1SR1092
1,ISD1),(IA(353),J9),(IA(354),J10),(IA(355),JRS5),(IA(356),JSDY) F1SR1029 F1SR1093
2,(IA(357),JSDZ),(IA(358),JARE),(IA(359),JMW),(IA(360),JMWV) F1SR1030 F1SR1094
3(IA(361),JMW7),(IA(362),JMF1),(IA(363),JMF2),(IA(364),JMF3),(IA(365),JMF4),F1SR1031 F1SR1095
4(IA(366),JMF5),(IA(367),JMF6),(IA(368),JMF7),(IA(369),JMF8),(IA(370),JMF9),F1SR1032 F1SR1096
DIMENSION IBS(25),CCC(125),JRS(25),CCC(25) F1SR1033 F1SR1097
EQUIVALENCE (IA(201),IRS),(IA(225),JRS),(AA(250),CCC), F1SR1034 F1SR1098
1(AA(275),CCCJ) F1SR1035 F1SR1099
EQUIVALENCE (IA(351),ISHUF),(IA(301),ISUP) F1SR1036 F1SR1100
EQUIVALENCE (ASIN,IPAC),(SPIN,IPAW) F1SR1037 F1SR1101
DIMENSION ITRC(800),IRAND(800),ISIR(540),IMAX(540),IMIN(540), F1SR1038 F1SR1102
1ARIN(540,15) F1SR1039 F1SR1103
EQUIVALENCE (DUMMY,ARIN),(DUMMY(3700),ISIP),(DUMMY(8660),IMAX), F1SR1040 F1SR1104
1(DUMMY(9180),IMIN) F1SR1041 F1SR1105
IF ISHUF=2) 25,25+23 F1SR1042 F1SR1106
23 READ INPUT TAPE 5,100,1,ISIR(1),IMAX(1),IMIN(1) F1SR1043 F1SR1107
100 FORMAT (20I4) F1SR1044 F1SR1108
GO TO 1100 F1SR1045 F1SR1109
25 DO 22 I=1,N F1SR1046 F1SR1110
22 ISIR(I)=1 F1SR1047 F1SR1111
ISUR=(N-1)/36+1 F1SR1048 F1SR1112
DO 71 I=1,N F1SR1049 F1SR1113
DO 71 J=1,ISUR F1SR1050 F1SR1114
71 ARIN(I,J)=0 F1SR1051 F1SR1115
DO 99 M=1,IT F1SR1052 F1SR1116
CALL TOP0 F1SR1053 F1SR1117
DO 98 I=1,1H F1SR1054 F1SR1118
L=IH+I F1SR1055 F1SR1119
IF IA(L) 98,98,97 F1SR1056 F1SR1120
98 CONTINUE F1SR1057 F1SR1121
1 WRITE OUTPUT TAPE 6,111,M F1SR1058 F1SR1122
111 FORMAT (1H ELEMENT,14,2X,29H IS UNACCEPTABLE. DISREGARDED.) F1SR1059 F1SR1123
DO 99 F1SR1060 F1SR1124
99 M=M+1 F1SR1061 F1SR1125
C THIS CARD (E1SR61A0) IS IMMEDIATELY BEFORE CARD E1SR1061. F1SR61A0 F1SR1126
EXPAND ELEMENT VECTOR, BY MULTIPLE DRG INPUT UNITS, IN IMAX F1SR61A1 F1SR1127
L=0 F1SR61A2 F1SR1128
DO 300 I=1,IMS F1SR61A3 F1SR1129
L=L+1 F1SR61A4 F1SR1130
IMAX(L)=N(1) F1SR61A5 F1SR1131
KN=(N(1)-1)*IDEG+190 F1SR61A6 F1SR1132
DO 301 J=1,IDEG F1SR61A7 F1SR1133
IROL=KN+J F1SR61A8 F1SR1134
IF (IA(IROL)-10000) 301,302,307 F1SR61A9 F1SR1135
302 KM=10000+IROL-180 F1SR61B0 F1SR1136
IROL=190 F1SR61B1 F1SR1137
DO 303 K=1,IND F1SR61B2 F1SR1138
IROL=IROL+1 F1SR61B3 F1SR1139
IF (IA(IROL)+KM) 303,304,303 F1SR61B4 F1SR1140
304 L=L+1 F1SR61B5 F1SR1141
IMAX(L)=(K-1)/IDEG+1 F1SR61B6 F1SR1142
303 CONTINUE F1SR61B7 F1SR1143
301 CONTINUE F1SR61B8 F1SR1144
300 CONTINUE F1SR61C0 F1SR1145
IMS=1 F1SR61C1 F1SR1146
DO 306 I=2,L F1SR61C2 F1SR1147
KN=IMAX(I) F1SR61C3 F1SR1148
DO 307 J=1,IMS F1SR61C4 F1SR1149
IF (IMAX(J)-KN) 307,306,307 F1SR61C5 F1SR1150
307 CONTINUE F1SR61C6 F1SR1151
IMS=IMS+1 F1SR61C7 F1SR1152
IMAX(L)=KN F1SR61C8 F1SR1153
CONTINUE F1SR61C9 F1SR1154
C THIS CARD (E1SR61C9) IS IMMEDIATELY BEFORE CARD E1SR162. F1SR162 F1SR1155
DO 95 I=1,IMS E1SR162 F1SR1156
IA=IMAX(I) E1SR163 F1SR1157

```

Table VII-12. Source program listing of subroutine TABL (Link 1)

```

* LABEL
CENTRAL SUBROUTINE TABL F1TRLO00
C PRINTS FIRST OUTPUT ITEM F1TRLO01
DIMENSION I4(1),AA(1),RFM(13),NT(10),DUMMY(5000),IDUM(5000),N(8) F1TRLO02
1,P(24),UV(24),X(8),Y(8),Z(8),XO(7),YO(7),ZO(7),RUMMY(27,9) F1TRLO03
2,D(21,21),S(1),G(1) F1TRLO04
COMMON I4,AA F1TRLO05
EQUIVALENCE (I4,AA),(AA,9000),DUMMY) F1TRLO06
EQUIVALENCE (DUMMY,TDUM,NT,RUMMY),(DUMMY(11),RFM) F1TRLO07
EQUIVALENCE (I4(1),IN),(I4(2),JN),(I4(3),IT),(I4(4),IP),(I4(5), F1TRLO09
1PRS),(I4(6),ITYPE),(I4(7),IMAT),(I4(8),IDEG),(I4(9),INX),(I4(10),F1TRLO10
2IH),(I4(11),IR),(I4(12),IMM),(I4(13),IMMY),(I4(14),I1),(I4(15),F1TRLO11
3IMP),(I4(16),IARE),(I4(17),A(1)),(I4(18),M),(I4(19),IY),(I4(20),F1TRLO12
4ISTR),(I4(21),IFLT),(I4(22),IFRM),(I4(30),ITIC),(I4(31),IMFT) F1TRLO13
5IA(192),ISUM,(I4(32),IND),(I4(34),IMS),(I4(35),IOS),(I4(37), F1TRLO14
6IORD),(I4(38),IORD1),(I4(39),ACFL),(I4(40),J1),(I4(51),J2) F1TRLO15
7IA(92),J3),(I4(53),J4),(I4(54),J5),(I4(55),J6),(I4(56),J7),(I4(57),F1TRLO16
8J),(I4(58),JTY),(I4(59),J8),(I4(60),I80),(I4(61),I81),(I4(62),F1TRLO17
9IAT),(I4(63),I8T),(I4(64),I8Y),(I4(65),I8E),(I4(61),I8P) F1TRLO18
EQUIVALENCE (I4(66),ICAR),(I4(67),ICIX),(I4(68),ICFY),(I4(69), F1TRLO19
1ICIZ),(I4(70),ICFI),(I4(71),ICX),(I4(72),ICY),(I4(73),ICZ) F1TRLO20
2IA(74),IIC),(I4(75),IDH),(I4(76),IS),(I4(77),IIS) F1TRLO21
3IA(78),IDEM),(I4(79),IDEX),(I4(80),IDF),(I4(81),IDT),(I4(82),IDG) F1TRLO22
4IA(83),ALI),(I4(84),AL2),(I4(85),AL3),(I4(86),AL4),(I4(87),AL5) F1TRLO23
5AA(131),UV),(I4(155),X),(I4(163),Y),(I4(171),Z),(I4(179),XO) F1TRLO24
6AA(186),YO),(I4(193),ZO),(I4(351),S),(I4(401),ZGFM) F1TRLO25
7IA(42),IMP),(I4(43),IPRG),(I4(44),IPEN),(I4(45),CONS),(I4(46),I1) F1TRLO26
8IA(47),G1),(I4(48),G2),(I4(49),G3) F1TRLO27
EQUIVALENCE (I4(349),NTIC),(I4(349),ISD),(I4(347),ISDY),(I4(346) F1TRLO28
1,ISD),(I4(345),J4),(I4(344),J10),(I4(343),JPRS),(I4(342),JSDY) F1TRLO29
2,I4(341),JSDZ),(I4(340),JARE),(I4(339),JMMX),(I4(338),JMMY) F1TRLO30
3,I4(337),JMMZ),(I4(336),JMF),(I4(335),I7AS),(I4(334),I8Z) F1TRLO31
4,I4(333),IPR),(I4(332),IOY),(I4(331),DOZ),(I4(330),PRES) F1TRLO32
5,I4(329),IPR),(I4(328),TCOR),(I4(327),TRUN),(I4(326),IMFS) F1TRLO33
DIMENSION IRR(50) F1TRLO34
EQUIVALENCE (I4(200),IRFR) F1TRLO35
DIMENSION ISTR(540) F1TRLO36
EQUIVALENCE (DUMMY(100),ISIR) F1TRLO37
EQUIVALENCE (I4(35),ISHU) F1TRLO38
WRITE OUTPUT TAPE 6,1001,(RFM(1),I4,14) F1TRLO39
1001 FORMAT (1H1,36X,25HLINEAR ELASTICITY PROBLEM// 2X,1446) F1TRLO40
WRITE OUTPUT TAPE 6,351,IN,IT,IDEG,ITYPE,IGEM,ISTR,IN,IN,IP F1TRLO41
1,IPRS,IMAT,NTIC F1TRLO42
351 FORMAT (//22H TOTAL NUMBER OF NODES,14X,15/32H TOTAL NUMBER OF FINE,11H,1043
11E ELEMENTS,8X,15/29H DEGREES OF FREEDOM AT A NODE,11X,15/12H ITYPE,11H,1044
2HE VALUE,28X,15,10X,54H FOR ISOTROPIC, 1 FOR ORTHOTROPIC, 2 FOR ANISOTROPIC,
3GENERAL MATERIAL/11H IGEN VALUE,29X,15,10X,40H FOR 2-, 1 FOR 3-DIM,11H,1046
4ANISOTROPIC STRUCTURES/11H ISTR VALUE,29X,15,10X,34H FOR PLANE STRAIN,11H,1047
5H CASE, 0 OTHERWISE/44H MAXIMUM NUMBER OF CONTACTS IN AN ELEMENT,11H,1048
64/32H CONTACT NUMBER INCLUDING DUMMIES,11/210H IRR VALUE,30X,15,10H,11H,1049
7X,65HNUMBER OF SUPPRESSED DEGREES OF FREEDOM IF NO MULTIPLE CONNECTIONS,11H,1050
8IONS/35H TOTAL NUMBER OF CONCENTRATED LOADS,5X,15/19H PRESSURE TYPE,11H,1051
9ES,25X,15/15H MATERIAL TYPES,25X,15/15H THICKNESS TYPES,24X,15) F1TRLO52
WRITE OUTPUT TAPE 6,352,ISUT,ISDY,ISDZ,IRFR,IMMX,IMMY,IMMZ,IMEI F1TRLO53
1,INX,IMP,ISHU,ICOR F1TRLO54
352 FORMAT (25H TEMPERATURE CHANGE TYPES,15X,15/35H TEMPERATURE GRADIENT,11H,1055
1NT TYPES ALONG Y,5X,15/35H TEMPERATURE GRADIENT TYPES ALONG Z,5X,15/11H,1056
25/11H AREA TYPES,29X,15/23H TORSION CONSTANT TYPES,17X,15/26H Y MOMENT,11H,1057
3MOMENT OF INERTIA TYPES,14X,15/26H Z MOMENT OF INERTIA TYPES,14X,15/2) F1TRLO58
439H NUMBER OF ANGLES FIXING PRINCIPAL AXES,16/10X,INX VALUE,30X,15/11H,1059
5,10X,35HNUMBER OF THE LINK FROM WHICH RETURN-TO-BEGINNING IS MADE,11H,1060
610H IMP VALUE,30X,15,10X,50H MINIMUM PRINT, 1 PARTIAL PRINT, 2 COMPLETE PRINT,11H,1061
7MPLETE PRINT/12H ISHUP VALUE,29X,15,10X,43H NO LABELLING, 1 LABELLING,11H,1062
8AREL, 2 OR 3 READ CARDS FOR LABELLING,11H,1063 FOR VALUE,29X,15,10X,11H,1063
9,520H READ CARDS, 1 CALL SUBROUTINE CURV FOR COORDINATES) F1TRLO64
WRITE OUTPUT TAPE 6,335Z,INUM,IMPS,IMEI,IPAS,ACFL,G1,G2,G3 F1TRLO65
335Z FORMAT (11H IRR VALUE,29X,15,10X,40H READ CARDS, 1 CALL SUBROUTINE) F1TRLO66
1HE RING FOR BOUNDARY CONDITIONS/11H IMPS VALUE,29X,15,10X,54H READ CARDS,
20 CARDS, 1 CALL SUBROUTINE MESH FOR MESH TOPLOGY/38H IPRR VALUE,11H,1068
3ON SHALL LOCAL NODAL AXES,17,10X,54H ASSUME ZERO, 1 COMPUTE AS USUAL,11H,1069
4INC,PAL, 2 READ AS INPUT/26H CHAIN PROGRAM TAPE NUMBER,16X,15/20H,11H,1070
5SCRATCH TAPE NUMBER,20X,15,10X,50H NIK - DO NOT COMPUTE RESULTS,11H,1071
6 OTHERWISE COMPUTE/ 23H ACCELERATION UNIT MASS,17X,10,4/34H DIRECT,11H,1072
7TINW COSINES OF ACCELERATION,16,6,5X,10,5,4X,10,4//) F1TRLO73
RETURN F1TRLO74
END F1TRLO75

```

Table VII-13. Source program listing of subroutine TICK (Link 1)

```

* FAP LABEL
COLUMN 25 TICK000
LBI TICK TICK001
ENTRY TICK TICK002
NZI ONCE TICK003
TRA FIRST TICK004
CAL 5 TICK005
SHR INITL TICK006
ALS 18 TICK007
SLWR 1,4 TICK008
TRA 2,4 TICK009
FIRST STL ONCE TICK010
CAL 5 TICK011
N1W 1,1,1 TICK012
S17* 1,4 TICK013
PZE TICK014
PZE TICK015
INITL TICK016
END TICK017

```

Table VII-14. Source program listing of subroutine TOPO (Link 1)

```

* LABEL
CENTRAL SUBROUTINE TOPO E1TOP000
C PREPARES ELEMENT PROPERTIES AND CHECKS E1TOP001
DIMENSION I4(1),AA(1),REMI(13),NT(10),DUMMY(5000),IDUM(5000),N(8) E1TOP002
1,P(24),UV(24),X(8),Y(8),Z(8),XO(7),YO(7),ZO(7),RUMMY(27,9) E1TOP003
2,D(21,21),S(1),G(1) E1TOP004
COMMON I4,AA E1TOP005
EQUIVALENCE (I4,AA),(AA,9000),DUMMY) E1TOP006
EQUIVALENCE (DUMMY,TDUM,NT,RUMMY),(DUMMY(11),REMI) E1TOP007
EQUIVALENCE (I4(1),IN),(I4(2),JN),(I4(3),IT),(I4(4),IP),(I4(5), E1TOP008
1PRS),(I4(6),ITYPE),(I4(7),IMAT),(I4(8),IDEG),(I4(9),INX),(I4(10),F1TOP010
2IH),(I4(11),IR),(I4(12),IMM),(I4(13),IMMY),(I4(14),I1),(I4(15),F1TOP011
3IMP),(I4(16),IARE),(I4(17),A(1)),(I4(18),M),(I4(19),IY),(I4(20),F1TOP012
4ISTR),(I4(21),IFLT),(I4(22),IFRM),(I4(30),ITIC),(I4(31),IMFT) E1TOP013
5IA(192),ISUM,(I4(32),IND),(I4(34),IMS),(I4(35),IOS),(I4(37), F1TOP014
6IORD),(I4(38),IORD1),(I4(39),ACFL),(I4(40),J1),(I4(51),J2) E1TOP015
7IA(92),J3),(I4(53),J4),(I4(54),J5),(I4(55),J6),(I4(56),J7),(I4(57),F1TOP016
8J),(I4(58),JTY),(I4(59),J8),(I4(60),I80),(I4(61),I81),(I4(62),F1TOP017
9IAT),(I4(63),I8T),(I4(64),I8Y),(I4(65),I8E),(I4(61),I8P) E1TOP018
EQUIVALENCE (I4(66),ICAR),(I4(67),ICIX),(I4(68),ICFY),(I4(69), F1TOP019
1ICIZ),(I4(70),ICFI),(I4(71),ICX),(I4(72),ICY),(I4(73),ICZ) E1TOP020
2IA(74),IIC),(I4(75),IDH),(I4(76),IS),(I4(77),IIS) E1TOP021
3IA(78),IDEM),(I4(79),IDEX),(I4(80),IDF),(I4(81),IDT),(I4(82),IDG) E1TOP022
4IA(83),ALI),(I4(84),AL2),(I4(85),AL3),(I4(86),AL4),(I4(87),AL5) E1TOP023
5AA(131),UV),(I4(155),X),(I4(163),Y),(I4(171),Z),(I4(179),XO) E1TOP024
6AA(186),YO),(I4(193),ZO),(I4(351),S),(I4(401),ZGFM) E1TOP025
7IA(42),IMP),(I4(43),IPRG),(I4(44),IPEN),(I4(45),CONS),(I4(46),I1) E1TOP026
8IA(47),G1),(I4(48),G2),(I4(49),G3) E1TOP027
EQUIVALENCE (I4(349),NTIC),(I4(349),ISD),(I4(347),ISDY),(I4(346) E1TOP028
1,ISD),(I4(345),J4),(I4(344),J10),(I4(343),JPRS),(I4(342),JSDY) E1TOP029
2,I4(341),JSDZ),(I4(340),JARE),(I4(339),JMMX),(I4(338),JMMY) E1TOP030
3,I4(337),JMMZ),(I4(336),JMF),(I4(335),I7AS),(I4(334),I8Z) E1TOP031
4,I4(333),IPR),(I4(332),IOY),(I4(331),DOZ),(I4(330),PRES) E1TOP032
5,I4(329),IPR),(I4(328),TCOR),(I4(327),TRUN),(I4(326),IMFS) E1TOP033
IELT=0 E1TOP034
ITEM=0 E1TOP035
ITIC=0 E1TOP036
IMEI=0 E1TOP037
DO 10 I=1,8 E1TOP038
N(I)=0 E1TOP039
K=1+335 E1TOP040
I4(K)=0 E1TOP041
JM=J3+M E1TOP042
INET=IA(JM)-100*IELT E1TOP043
JM=J2+M E1TOP044
IF (IELT-4) 100,100,450 E1TOP045
100 IF (IELT-3) 200,300,200 E1TOP046
200 JAR=IA(JM)/100 E1TOP047
ITEM=IA(JM)-100*JARE E1TOP048
GM=TO,400 E1TOP049
JPRS=IA(JM)/100 E1TOP050
JSDZ=IA(JM)-100*JPRS E1TOP051
400 IF (IELT-3) 600,800,800 E1TOP052
400 IF (IELT-10) 470,470,500 E1TOP053
470 IF (IELT-8) 500,500,480 E1TOP054
480 JPRS=IA(JM)/100 E1TOP055
ITEM=IA(JM)-100*JPRS E1TOP056
L=1 E1TOP057
GO TO 1000 E1TOP058
ITIC=IA(JM)/100 E1TOP059
ITEM=IA(JM)-100*ITIC E1TOP060
JM=J3+M E1TOP061
JSDZ=IA(JM)/100 E1TOP062
JPRS=IA(JM)-100*JSDZ E1TOP063
L=2 E1TOP064
GO TO 1000 E1TOP065
JM=J3+M E1TOP066
JPRS=IA(JM) E1TOP067
L=2 E1TOP068
IF (IELT-2) 1000,700,700 E1TOP069
700 JM=J4+M E1TOP070
JSDZ=IA(JM)/100 E1TOP071
JSDY=IA(JM)-100*JMMY E1TOP072
L=3 E1TOP073
IF (IELT-4) 1000,900,1000 E1TOP074
800 JM=J3+M E1TOP075
JMMX=IA(JM)/100 E1TOP076
JMMY=IA(JM)-100*JMMX E1TOP077
L=2 E1TOP078
IF (IELT-4) 1000,700,1000 E1TOP079
900 JM=J5+M E1TOP080
JSDZ=IA(JM)/100 E1TOP081
JMEI=IA(JM)-100*JSDZ E1TOP082
JM=J6+M E1TOP083
JPRS=IA(JM) E1TOP084
1000 I=1 E1TOP085
GM=TO (1100,1200,1300,1400),L E1TOP087
1100 JM=J3+M E1TOP088
N(I)=IA(JM) E1TOP089
I=1 E1TOP090
1200 JM=J4+M E1TOP091
N(I)=IA(JM) E1TOP092
I=1 E1TOP093
1300 JM=J5+M E1TOP094
M(I)=IA(JM) E1TOP095
I=1 E1TOP096
JM=J6+M E1TOP097
N(I)=IA(JM) E1TOP098
I=1 E1TOP099
1400 JM=J7+M E1TOP100
N(I)=IA(JM) E1TOP101
I=1 E1TOP102
JM=J8+M E1TOP103
N(I)=IA(JM) E1TOP104
I=1 E1TOP105
JM=J9+M E1TOP106

```

Table VII-14 (contd)

```

N(I)=I*(JM)
I=I+1
JH=J10+M
N(I)=I*(JM)
IF (I-1)H 1408,1408,1402
1402 JHP=I+H
DO 1405 J=JHP,8
1405 N(J)=0
1408 DO 1410 J=1,1H
IF (N(I)-I) 1410,1410,1450
1410 CONTINUE
GO TO 1600
1450 WRITE OUTPUT TAPE 6,7,M
2 FORMAT (11H IN ELEMENT,15,59H ERROR IN MESH TOPOLOGY INFORMATION,
1 NO CORRECTION IS MADE)
1600 NDX=0
1610 IF (I*(JPRS+1)*(JPRS-IPRS-1)) 1620,1611,1611
1611 JPRS=IPRS
IF (IELT=4) 1612,1613,1614
1612 IF (IELT=2) 1614,1616,1616
1614 IF (IELT=9) 1618,1616,1617
1617 IF (IELT=10) 1618,1616,1618
1618 JH=J+M
L=I*(JM)-(I*(JM)/100)*100
I*(JM)=100*(JPRS+L
GO TO 1615
1613 JH=J+M
I*(JM)=JPRS
GO TO 1615
1618 JH=J+M
L=I*(JM)/100
I*(JM)=100*(JPRS
1615 CONTINUE
NDX=NDX+1
1620 IF (IMF+1)IMFT-(IMAT-1)) 1630,1621,1621
1621 IMF=IMAT
JM=J+M
I*(JM)=100*(IELT+JMET
NDX=NDX+1
1630 IF (ITIC+1)*(ITIC-NTIC-1)) 1640,1631,1631
1631 ITIC=NTIC
JM=J+M
L=I*(JM)-(I*(JM)/100)*100
I*(JM)=100*(ITIC+L
NDX=NDX+1
1640 IF (ITEM+1)*(ITEM-ISDT-1)) 1650,1641,1641
1641 ITEM=ISDT
JM=J+M
L=I*(JM)/100
I*(JM)=100*(L+ITEM
NDX=NDX+1
1650 IF (JSDY+1)*(JSDY-ISDY-1)) 1660,1651,1651
1651 JSDY=ISDY
JM=J+M
L=I*(JM)/100
I*(JM)=100*(L+JSDY
NDX=NDX+1
1660 IF (JSD2+1)*(JSD2-ISD2-1)) 1670,1661,1661
1661 JSD2=ISD2
IF (IELT=4) 1662,1663,1664
1662 JM=J+M
L=I*(JM)/100
I*(JM)=100*(L+JSD2
GO TO 1665
1663 JM=J+M
GO TO 1666
1664 JM=J+M
L=I*(JM)-(I*(JM)/100)*100
I*(JM)=100*(JSD2+L
1665 CONTINUE
NDX=NDX+1
1670 IF (JARE+1)*(JARE-IARE-1)) 1680,1671,1671
1671 JARE=IARE
JM=J+M
L=I*(JM)-(I*(JM)/100)*100
I*(JM)=100*(JARE+L
NDX=NDX+1
1680 IF (JMMX+1)*(JMMX-IMMX-1)) 1690,1681,1681
1681 JMMX=IMMX
JM=J+M
L=I*(JM)-(I*(JM)/100)*100
I*(JM)=100*(JMMX+L
NDX=NDX+1
1690 IF (JMMY+1)*(JMMY-IMMY-1)) 1700,1691,1691
1691 JMMY=IMMY
JM=J+M
L=I*(JM)/100
I*(JM)=100*(L+JMMY
NDX=NDX+1
1700 IF (JMMZ+1)*(JMMZ-IMMZ-1)) 1710,1701,1701
1701 JMMZ=IMMZ
JM=J+M
L=I*(JM)-(I*(JM)/100)*100
I*(JM)=100*(JMMZ+L
NDX=NDX+1
1710 IF (JMF+1)*(JMF-IMF-1)) 1720,1711,1711
1711 JMF=IMF
JM=J+M
L=I*(JM)/100
I*(JM)=100*(L+JMF
NDX=NDX+1
1720 IF (INDX) 2000,2000,1800
1800 WRITE OUTPUT TAPE 6,7,M,NDX
1 FORMAT(11H IN ELEMENT,15,2X,1H,15,2X,95HPROPERTY TYPE NUMBER IS
1 IS OUTSIDE THE PRESCRIBED RANGE. TYPE NO IS ASSUMED AS LARGEST POSSIBLE)
25T6L1
2000 RETURN
END

```

Table VII-15. Source program listing of main program of Link 2 (generation link)

```

* CHAIN (2,2)
* LABEL
CFLAS2
C MAIN PROGRAM FOR GENERATION LINK
C GENERATES GOVERNING EQUATIONS
DIMENSION IA(1),AA(1),SILV,N(1),D2L(2),D33(3,3),F22(3,3)
1,P(24),UV(124),X(8),Y(8),Z(8),XD(7),YD(7),ZD(7),G(1)
COMMON IA,AA
EQUIVALENCE (IA,AA),D21,D33,(D21(10),F22),(D21(19),F1),(D21(20),G)
EQUIVALENCE (IA(1),IN),(IA(7),IN),(IA(9),IT),(IA(4),IP),(IA(5),
1PKS),(IA(9),ITYPF),(IA(7),IN),(IA(9),IDEG),(IA(9),IN),(IA(10),
2EM),(IA(11),ID),(IA(12),IMMX),(IA(13),IMMY),(IA(14),JMMZ),(IA(15),
3IMF),(IA(16),IARE),(IA(17),4(1)),(IA(25),M),(IA(26),ITY),(IA(27),
4ISRT),(IA(28),IELT),(IA(29),ITER),(IA(30),ITIC),(IA(31),IMF1),
5IA(32),ISUM),(IA(33),IMD),(IA(34),IMS),(IA(36),IUS),(IA(37),
6IDRO),(IA(38),IDRO1),(IA(39),AGFL),(IA(40),J),(IA(51),J2),
7IA(52),J3),(IA(53),J4),(IA(54),J5),(IA(55),J6),(IA(56),J7),(IA(57),
8J8),(IA(58),J9),(IA(59),I0),(IA(60),I00),(IA(61),I10),(IA(62),
9I1),(IA(63),I101),(IA(64),I01),(IA(65),I1),(IA(61),I10),(IA(62),
EQUIVALENCE (IA(66),ICAR),(IA(67),ICX),(IA(68),ICY),(IA(69),
1ICIZ),(IA(70),ICFI),(IA(71),IX),(IA(72),IY),(IA(73),I17),
2IA(74),IIC),(IA(75),IIEF),(IA(76),IST),(IA(77),IIS)
3,(IA(78),IGEM),(IA(79),IERK),(IA(80),IF),(IA(81),IT),(IA(82),I06),
4IA(83),IUV),(IA(84),AL2),(IA(85),AL3),(IA(86),D21),(IA(107),IP),
5IA(184),YD),(IA(193),ZD),(AA(251),S),(AA(40),ZGMF)
7,(AA(42),INP),(AA(43),IPBG),(AA(44),IPFN),(AA(45),CONS),(AA(46),
8),(AA(47),G1),(AA(48),G2),(AA(49),G3)
EQUIVALENCE (IA(349),NTIC),(IA(348),ISHT),(IA(347),ISDY),(IA(346),
1,ISDZ),(IA(345),J9),(IA(344),J10),(IA(343),JPRS),(IA(342),JSHY)
2,(IA(341),JSDZ),(IA(340),JARE),(IA(339),JMX),(IA(338),IMMY)
3,(IA(337),JMMZ),(IA(336),JMF1),(IA(335),ITAS),(IA(334),I07)
4,(IA(333),IPR),(IA(332),OBY),(AA(331),OZ2),(AA(330),PRES)
5,(IA(329),IPR),(IA(328),NAV),(AA(327),CF)
DIMENSION IBS(25),CCC(125),JRS(25),CCC(25),PV(24)
EQUIVALENCE (IA(200),IBS),(IA(225),JRS),(AA(250),CCC),
IAA(275),CCC,PV)
DIMENSION NND(20),PD(3),NRT(4)
EQUIVALENCE (AA(300),NND),(AA(324),PKCO),(AA(325),ITTT),(AA(291),P
ID),(IA(326),IMS)
INPT=INF
CALL TICK (ITIM)
CLEAR ST ARRAY
DO 132 I=1,NDX
IST=IST+1
132 C GENERATE ELEMENTAL MATRICES AND ASSEMBLY
ZGEM=IGEM
DO 99 M=1,II
INPT=INPT
CALL CAS2
ERR=0
DO 133 I=1,8
N(I)=0
X(I)=0.
Y(I)=0.
Z(I)=0.
DO 134 I=1,107,32R
AA(I)=0.
DG=0.
DT=0.
PRES=0.
OGY=0.
OGY=0.
CFE=1.
NAV=1
ITTT=0
CALL TOP1
DO 98 I=1,1H
NND(I)=N(I)
IF (N(I)) 9400,97,98
CONTINUE
IMS=IH
GO TO 2
9800 IERR=2
1 WRITE OUTPUT TAPE 6,7,M,ITTT,IFRR
11) FURNAT (8H ELEMFT,21,2X,20HIS UNACCFIABLE. DISKFCAM(1),I)
WRITE TAPE (11AS,M,ITTT,ITTM,NAV,IMS,IMS,IMS2,(N(I),I=1),IMS),IS(1),
1I=1,IMS2),(I11),PV(1),I=1,IMS)
IERR=H
GO TO 999
97 IMS=I-1
2 ITE=ITE+ITIC
IIS=IMS+IDEG
TE=AA(ITE)
IF (ITE) 972,972,971
973 IDT=IDT+ITEM
DT=AA(IDT)
972 IF (JSDY) 974,974,973
973 IDY=IDY+JSHY
OGY=AA(IDY)
OBY=0
974 IF (JSDZ) 976,976,975
975 IDZ=IDZ+JSHZ
NRZ=AA(IDZ)
OG=OGZ
976 IF (JPKS) 978,978,977
977 IPR=IPR+JPRS
PRES=AA(IPR)
978 IF (ITYPF-1) 70,71,72
70 IIA=IA+IMFT
AL1=AA(IAI)
AL2=AL1
AL3=AL1
GO TO 73
71 IIA=IA+(IMFT-1)*2
AL1=AA(IAI+1)
AL2=AA(IAI+2)
AL3=0
GO TO 73
72 IIA=IA+(IMFT-1)*3
AL1=AA(IAI+1)
AL2=AA(IAI+2)
AL3=AA(IAI+3)
73 IF (ITYPF-1) 601,602,603

```

Table VII-15 (contd)

```

601 I1D1=I1D+I1MFT-1)*2
GO TO 604
602 I1O1=I1D+I1MFT-1)*9
GO TO 604
603 I1D1=I1D+I1MFT-1)*2
604 E=AA(I1D1+1)
R=AA(I1D1+2)
MU=F/12.*G)-1.
KELT=IELT
GO TO 504,504,504,504,502,502,502,502,502,503,503,502,507,507,507,502,
1503,503,507,502).KELT
502 IF (I1TYPE=1) 5021,5022,5023
5021 IF (ISTR1 6021,6021,6022
6021 D3311,1)=2.*G/(1.-PU)
D3312,2)=D3311,1)
D3311,2)=D3311,1)*PU
GO TO 6025
6022 D3311,1)=2.*G*(1.-PU)/(1.-2.*PU)
D3312,2)=D3311,1)
D3311,2)=2.*G*PU/(1.-2.*PU)
6023 D3311,3)=0.
D3312,3)=0.
D3313,3)=G
IF (IEL1-5) 5024,5024,6025
6025 IF (IELT-6) 5024,5024,6024
6024 E2211,1)=G
E2212,2)=G
F2212,2)=G
GO TO 5024
5022 D3311,1)=AA(I1D1+1)
D3311,2)=AA(I1D1+2)
D3311,3)=AA(I1D1+3)
D3312,2)=AA(I1D1+4)
D3312,3)=AA(I1D1+5)
D3313,3)=AA(I1D1+6)
E2211,1)=AA(I1D1+7)
E2211,2)=AA(I1D1+8)
E2212,2)=AA(I1D1+9)
GO TO 5024
5023 D3311,1)=AA(I1D1+1)
D3311,2)=AA(I1D1+2)
D3311,3)=AA(I1D1+4)
D3312,2)=AA(I1D1+7)
D3312,3)=AA(I1D1+9)
D3313,3)=AA(I1D1+16)
E2211,1)=AA(I1D1+19)
E2211,2)=AA(I1D1+20)
F2212,2)=AA(I1D1+21)
D3312,1)=D3311,2)
D3313,1)=D3311,3)
D3313,2)=D3311,3)
E2212,1)=E2211,2)
GO TO 504
503 IF (I1TYPE=1) 5031,5031,5033
5031 EE=E
CG=0
DO 5032 I=1,21
5032 D2111)=0.
D2111)=2.*GG*(1.-PU)/(1.-2.*PU)
D2112)=D2111)*PU/(1.-PU)
D2113)=D2112)
D2117)=D2111)
D2118)=D2112)
D2112)=D2111)
D2116)=GG
D2119)=GG
D21121)=GG
GO TO 504
5033 DO 5034 I=1,21
I1D1=I1D+I
5034 D2111)=AA(I1D1+1)
504 IERR=0
C IS THERE MULTIPLE ELEMENT
IF (IELT=6) 5100,4900,4499
4299 IF (IELT=8) 5100,4900,4700
4700 IF (IELT=10) 5100,4900,4800
4800 IF (IELT=12) 5100,4900,4850
4850 IF (IELT=14) 5100,4900,4880
4880 IF (IELT=16) 5100,4900,5100
C THERE IS MULTIPLE ELEMENT.CUT IT IN PIECES
4889 I1TT=0
IELT=IELT+1
DU 4890 I=1,4
N(I)=N(I)+1
GO TO 4902
4900 I1NS=I1NS
DO 4901 I=1,4
4901 N(I)=N(I)+1
4902 CALL CUTE (ITTK)
CFE=45
5100 J1=ITTT*I1NS
PRCD=0.
ITTT=ITTT+1
I1D2=I1D+I1D5
C1MS*I1MS
CX=0.
CY=0.
CZ=0.
DO 5500 I=1,I1MS
J1=J1+I
J=N(I)+I1)
5450 IF (J1 1,1,5450
I1XJ=I1X+J
I1YJ=I1Y+J
I1ZJ=I1Z+J
X(I)=AA(I1XJ)
Y(I)=AA(I1YJ)
Z(I)=AA(I1ZJ)+ZDEM
CX=CX+X(I)
CY=CY+Y(I)
CZ=CZ+Z(I)
IF (I-1) 5500,5500,5460
5460 X(I)-1)=X(I)-X(I)
Y(I)-1)=Y(I)-Y(I)
Z(I)-1)=Z(I)-Z(I)
5500 CONTINUE
CX=CX/I1MS
CY=CY/I1MS
CZ=CZ/I1MS
DO 5501 I=1,I1MS
FLAS2113
FLAS2114
FLAS2115
FLAS2116
FLAS2117
FLAS2118
FLAS2119
FLAS2120
FLAS2121
FLAS2122
FLAS2123
FLAS2124
FLAS2125
FLAS2126
FLAS2127
FLAS2128
FLAS2129
FLAS2130
FLAS2131
FLAS2132
FLAS2133
FLAS2134
FLAS2135
FLAS2136
FLAS2137
FLAS2138
FLAS2139
FLAS2140
FLAS2141
FLAS2142
FLAS2143
FLAS2144
FLAS2145
FLAS2146
FLAS2147
FLAS2148
FLAS2149
FLAS2150
FLAS2151
FLAS2152
FLAS2153
FLAS2154
FLAS2155
FLAS2156
FLAS2157
FLAS2158
FLAS2159
FLAS2160
FLAS2161
FLAS2162
FLAS2163
FLAS2164
FLAS2165
FLAS2166
FLAS2167
FLAS2168
FLAS2169
FLAS2170
FLAS2171
FLAS2172
FLAS2173
FLAS2174
FLAS2175
FLAS2176
FLAS2177
FLAS2178
FLAS2179
FLAS2180
FLAS2181
FLAS2182
FLAS2183
FLAS2184
FLAS2185
FLAS2186
FLAS2187
FLAS2188
FLAS2189
FLAS2190
FLAS2191
FLAS2192
FLAS2193
FLAS2194
FLAS2195
FLAS2196
FLAS2197
FLAS2198
FLAS2199
FLAS2200
FLAS2201
FLAS2202
FLAS2203
FLAS2204
FLAS2205
FLAS2206
FLAS2206A
FLS2206B
FLS2206C
ELS2206D
FLAS2207
FLAS2208
FLAS2209
FLAS2210
FLAS2211
FLAS2212
FLAS2213
FLAS2214
FLAS2215
FLAS2216
FLAS2217
FLS2217A
FLS2217B
FLS2217C
FLAS2218
FLAS2219
FLAS2220
FLAS2221
FLAS2222
FLS2222A
FLS2222B
FLS2222C
ELS2222D
X(I)=X(I)-CX
Y(I)=Y(I)-CY
5501 Z(I)=Z(I)-CZ
5600 DO 6 I=1,I1D5
P(I)=0.
UV(I)=0.
ISS=I-ID5
DO 7 J=1,I1D5
ISS=ISS+IOS
7 ISS=ISS+0.
6 CONTINUE
IF (DT) 82,83,82
82 DR A4 I=1,I1MS
I1=I1MS+1
I2=I1MS+1
UV(I1)=X(I1)*DT*AL1
UV(I2)=Y(I1)*DT*AL2
R4 UV(I2)=Z(I1)*DT*AL3
83 CALL STFS(IECT)
5043 IF (I1M=1) 86,86,85
87 FORMAT (////2015/12F10.3/12F10.3//1516.F13,4,5X1)
85 WRITE OUTPUT TAPE 6,87,M,(N1J),J=1,81,IELT,IMFT,ITTC,ITEM,JPPS,JARELAS2260
1E,JSDY,JSDZ,JNMX,JNFI,IDS,(X1J),Y1J),Z1J),J=1,81,I1,S111,I=1,I0S2IFLAS2261
86 IF (IERR) 1,951,1
921 IF (DT) 952,954,952
924 IF (DG) 952,9551,952
9551 IF (DGZ) 952,953,952
952 CALL DMN (S,UV,I0S,P)
953 IF (IPRG) 957,957,958
928 IF (IPRG-IPEN) 959,959,957
959 DO 955 I=IPRG,IPEN
DELP=CONS*G(I)
CPRS=PRCD*P(I)
I1=I1-IPRG*I1MS
DO 956 J=1,I1MS
I1=I1+J
956 P(I1J)=P(I1J)+DELP+CPRS
955 CONTINUE
951 IF (I1M=1) 9532,9532,9531
9543 WRITE OUTPUT TAPE 6,9533,(I,P111,I=1,I0S)
9533 FORMAT (//1516.E13,4,5X1)
9537 DO 95 I=1,I0EG
DO 94 K=1,I1MS
I2=I1MS*(I-1)+K
I5=IDEG*(I1M(K)-1)+I
I5E=I-ID5
CALL DARN (I5,I1MS,CCCJ,I0E)
IF (I0E) 307,307,308
307 IERR=6
GO TO 1
308 DO 393 I=0,1,I0E
ISS=ISE
CCUR=CCCJ(I0E)*CFE
IF (CCUR(I) 912,911,912
912 IDEF1=IDEF1+R
AA(IDEF1)=AA(IDEF1)+CCUR*I1E(I)
911 DO 93 J=1,I0EG
DO 92 I=1,I1MS
ISS=ISS+I0E
JE=I1MS*(J-1)+L
JS=IDEG*(I1M(J)-1)+J
CALL DARN (JS,J1MS,CCCJ,J0E)
IF (J0E) 307,307,408
408 DO 397 J=1,I0E
CCURJ=CCCJ(J0E)
JR=J1S(J0E)
F=CCURJ*CCURJ
IF (F) 913,392,913
913 IF (JR-IND) 914,914,915
915 AA(IDEF1)=AA(IDEF1)+F*(ISS)
GO TO 392
914 IF (JR-IB) 392,916,916
916 I1=I1+IB
IST1=IST1+I1(I1)+JB-IB
AA(IST1)=AA(IST1)+F*(I1SS)
392 CONTINUE
393 CONTINUE
94 CONTINUE
95 CONTINUE
9987 DO 9983 I=1,I0S
PV(I)=P(I)
9983 P(I)=0.
CALL DMMS(UV,I0S,P)
WRITE TAPE (I1AS,M,ITTT,ITTM,NAV,I1MS,I0S,I0S2,(N1I),F1,I1MS),(I1I)
I1=I1D52),(P(I),PV(I),I=1,I0S)
99H) CONTINUE
999 IF (ITTT-ITTM) 5100,9990,9990
9990 IF (I1AV=2) 99,4889,99
99 CONTINUE
I1M=I1MPT
CALL CAS?
IF (I1M=1) 232,232,233
233 IEND=IST+I1ND
I1=I1+1
WRITE OUTPUT TAPE 6,871,(I,AA(I),I=IST1,IEND)
871 FORMAT (I1M,82HUPPER HALF OF THE STIFFNESS MATRIX AFTER R.C.L. IMPROVEAS2216
LED FOLLOWS./89H ROW LISTING. FOR BANDWIDTHS SEE THE TABLE FOR MESHELAS2219
2. TYPOLOGY OF REDUCED STIFFNESS MATRIX,////1516.E14,5,4X1)
IEND=I0E+I1SUM
WRITE OUTPUT TAPE 6,871,(I,AA(I),I=IDEF1,IEND)
8711 FORMAT (I1M,31MREDUCED LOADING VECTOR FOLLOWS,////1516.F14,5,4X1)ELAS2224
232 IERR=LU
IF (I1AS) 2323,2323,2324
2324 REWIND I1AS
2323 CONTINUE
CALL TICK (ITTM)
C2T=ITTK
C2T=C2T/60.
WRITE OUTPUT TAPE 6,5555,C2T
5555 FORMAT I 21H GENERATION LINK TOOK.FT.-2.10H SECONDS.)
I1M=I1MPT
IF (I1M=2) 2321,2321,2322
2321 CALL CHAIN (ITAP)
2322 CALL CHAIN (I1TAP)
END
FLAS2222E
FLAS2222F
FLAS2222G
FLAS2222H
FLAS2222I
FLAS2222J
FLAS2222K
FLAS2222L
FLAS2222M
FLAS2222N
FLAS2222O
FLAS2222P
FLAS2222Q
FLAS2222R
FLAS2222S
FLAS2222T
FLAS2222U
FLAS2222V
FLAS2222W
FLAS2222X
FLAS2222Y
FLAS2222Z
FLAS2223
FLAS2224
FLAS2225
FLAS2226
FLAS2227
FLAS2228
FLAS2229
FLAS2230
FLAS2231
FLAS2232
FLAS2233
FLAS2234
FLAS2235
FLAS2236
FLAS2237
FLAS2238
FLAS2239
FLAS2240
FLAS2241
FLAS2242
FLAS2243
FLAS2244
FLAS2245
FLAS2246
FLAS2247
FLAS2248
FLAS2249
FLAS2250
FLAS2251
FLAS2252
FLAS2253
FLAS2254
FLAS2255
FLAS2256
FLAS2257
FLAS2258
FLAS2259
FLAS2260
FLAS2261
FLAS2262
FLAS2263
FLAS2264
FLAS2265
FLAS2266
FLAS2267
FLAS2268
FLAS2269
FLAS2270
FLAS2271
FLAS2272
FLAS2273
FLAS2274
FLAS2275
FLAS2276
FLAS2277
FLAS2278
FLAS2279
FLAS2280
FLAS2281
FLAS2282
FLAS2283
FLAS2284
FLAS2285
FLAS2286
FLAS2287
FLAS2288
FLAS2289
FLAS2290
FLAS2291
FLAS2292
FLAS2293
FLAS2294
FLAS2295
FLAS2296
FLAS2297
FLAS2298
FLAS2299
FLAS2300
FLAS2301
FLAS2302
FLAS2303
FLAS2304
FLAS2305
FLAS2306
FLAS2307
FLAS2308
FLAS2309
FLAS2310
FLAS2311
FLAS2312
FLAS2313
FLAS2314
FLAS2315
FLAS2316
FLAS2317
FLAS2318
FLAS2319
FLAS2320
FLAS2321
FLAS2322
FLAS2323
FLAS2324
FLAS2325
FLAS2326
FLAS2327
FLAS2328
FLAS2329
FLAS2330
FLAS2331
FLAS2332
FLAS2333
FLAS2334
FLAS2335
FLAS2336
FLAS2337
FLAS2338

```


Table VII-16. Source program listing of subroutine ADM (Link 2)

```
* LABEL
C F2ADM
SUBROUTINE ADM (S,IDS,A,M,IB,J3,C)
ADD5 SUBMATRICES TO FORM STIFFNESS MATRIX
DIMENSION A(4,4),S(1)
DO 10 J=1,M
  IS=IB+J-1
  IF (IB-JB) 12,11,12
11  J1=1
  GO TO 13
12  J1=1
13  DO 90 J=J1,M
    JS=JB+J-1
    ISS=(JS-1)*IDS+IS
    S(ISS)=S(ISS)+A(I,J)*C
    ISK=(IS-1)*IDS+JS
    S(ISK)=S(ISS)
90  CONTINUE
10  CONTINUE
RETURN
END
F2ADM000
F2ADM001
F2ADM002
F2ADM003
F2ADM004
F2ADM005
F2ADM006
F2ADM007
F2ADM008
F2ADM009
F2ADM010
F2ADM011
F2ADM012
F2ADM013
F2ADM014
F2ADM015
F2ADM016
F2ADM017
F2ADM018
F2ADM019
```

Table VII-18. Source program listing of subroutine CAS2 (Link 2)

```
* LABEL
C F2CAS2
SUBROUTINE CAS2
DIMENSION DUMMY SUBROUTINE
RETURN
END
F2CAS200
F2CAS201
F2CAS202
F2CAS203
F2CAS204
```

Table VII-17. Source program listing of subroutine BEAM (Link 2)

```
* LABEL
C F2BEA
SUBROUTINE BEAM
GENERATES SUBMATRICES FOR ELEMENT TYPES 2 AND 4
DIMENSION IA(1),AA(1),S(1),N(1),D21(21),D33(3,3),F2(3,3)
1,PI(24),UV(24),X(8),Y(8),Z(4),XD(7),YD(7),ZD(7),GL(1)
COMMON IA,AA
EQUIVALENCE (IA,AA),(D21,D33),(D21(10),F22),(D21(19),F),(D21(20),G),F2BEA006
EQUIVALENCE (IA(1),IN),(IA(2),INR),(IA(3),IT),(IA(4),IP),(IA(5),I) F2BEA007
1IPRS1,(IA(6),ITYPE),(IA(7),IMAT),(IA(8),IDFG),(IA(9),INX),(IA(10),F2BEA008
2IM),(IA(11),IB),(IA(12),IMMX),(IA(13),IMMY),(IA(14),IMW2),(IA(15),F2BEA009
3IMF1),(IA(16),IARE),(IA(17),M(1)),(IA(18),M),(IA(19),M2),(IA(20),F2BEA010
4ISTR),(IA(21),FL7),(IA(22),ITEM),(IA(23),ITIC),(IA(24),IMF1), F2BEA011
5IA(32),ISUM),(IA(33),IND),(IA(34),IMS),(IA(35),IOS),(IA(37),F2BEA012
6ISR1),(IA(38),IEL1),(IA(39),ITEM),(IA(40),ITIC),(IA(41),IMF1), F2BEA013
7IA(52),J31),(IA(53),J4),(IA(54),J5),(IA(55),J6),(IA(56),J7),(IA(57),F2BEA014
8JIB),(IA(58),JTY),(IA(59),IBR),(IA(60),IRI),(IA(61),ID),(IA(62),F2BEA015
9IA),(IA(63),IDT),(IA(64),IIV),(IA(65),ITF),(IA(66),IIP),(IA(67),F2BEA016
EQUIVALENCE (IA(66),ICAR),(IA(67),ICIX),(IA(68),ICIV),(IA(69), F2BEA017
1ICIZ),(IA(70),ICF),(IA(71),IX),(IA(72),IY),(IA(73),IZ), F2BEA018
2IA(74),ICJ),(IA(75),IDF),(IA(76),IST),(IA(77),IIS) F2BEA019
3,(IA(78),IGEM),(IA(79),IFRR),(IA(80),ITE),(IA(81),IDT),(IA(82),F2BEA020
4AA(83),ALI),(AA(84),AL2),(AA(85),AL3),(AA(86),M21),(AA(107),P), F2BEA021
5AA(131),H),(AA(135),X),(AA(136),Y),(AA(171),Z),(AA(179),X), F2BEA022
6AA(186),Y),(AA(193),Z),(AA(351),S),(AA(401),ZGF) F2BEA023
7,(AA(421),INP),(AA(43),IPRG),(AA(44),IPEN),(AA(45),GINS),(AA(46),F2BEA024
8),(AA(47),G1),(AA(48),G2),(AA(49),G3) F2BEA025
EQUIVALENCE (IA(349),NTIC),(IA(348),ISDT),(IA(347),ISDY),(IA(346), F2BEA026
1,ISD2),(IA(345),J9),(IA(344),J10),(IA(343),JPRS),(IA(342),JSDY) F2BEA027
2,(IA(341),JSD2),(IA(340),JAKE),(IA(339),JMW),(IA(338),JMW1) F2BEA028
3,(IA(337),JMW2),(IA(336),JMF1),(IA(335),IAS),(IA(334),IDZ) F2BEA029
4,(IA(333),IPR),(AA(332),DGY),(AA(331),DGZ),(AA(330),PREF1) F2BEA030
5,(IA(329),IPR1) F2BEA031
DIMENSION A(6,6),DIR(3,3),UVG(12),T(6),PD(3),PN(3),DUG(3)
EQUIVALENCE (AA(200),A),(AA(236),FL),(AA(237),AREA),(AA(238),I) F2BEA033
1,(AA(239),J1),(AA(240),IR),(IA(241),JR),(AA(242),NY),(AA(244),DIR) F2BEA034
2,(AA(306),UVG),(AA(291),PD),(AA(294),PN),(AA(297),DUG),(AA(300),T) F2BEA035
IF (JAKE) 1010,1010,110
110 ICAR=ICAR+JARE
AREA=AA(ICAR)
IF (IMW2) 1010,150,160
150 IF (IMMY) 1010,1010,155
155 ICIZ=ICIZ+JMWY
GO TO 170
160 ICIZ=ICIZ+JMMZ
170 A(1,1)=BAREA/FL
A(2,2)=A(1,1)
A(3,3)=12.*F*AA(1CIZJ)/IEL**3
A(3,4)=A(3,3)
A(4,4)=A(3,3)
A(3,5)=4.*F*AA(1CIZJ)/IEL**2
A(3,6)=A(3,5)
A(4,5)=A(3,5)
A(4,6)=A(3,5)
A(5,5)=4.*F*AA(1CIZJ)/FL
A(5,6)=5.*A(3,5)
A(6,6)=A(5,5)
DO 200 I=1,6
  DO 200 J=1,6
200 A(J,I)=A(I,J)
1000 RETURN
1010 IERR=1
GO TO 1000
END
F2BEA000
F2BEA001
F2BEA002
F2BEA003
F2BEA004
F2BEA005
F2BEA006
F2BEA007
F2BEA008
F2BEA009
F2BEA010
F2BEA011
F2BEA012
F2BEA013
F2BEA014
F2BEA015
F2BEA016
F2BEA017
F2BEA018
F2BEA019
F2BEA020
F2BEA021
F2BEA022
F2BEA023
F2BEA024
F2BEA025
F2BEA026
F2BEA027
F2BEA028
F2BEA029
F2BEA030
F2BEA031
F2BEA032
F2BEA033
F2BEA034
F2BEA035
```

Table VII-19. Source program listing of subroutine CODI (Link 2)

```
* LABEL
C F2CODI
SUBROUTINE CODI
OBTAINS TRANSFORMATION MATRIX OF LOCAL-OVERALL FOR LINE ELEMENT
DIMENSION IA(1),AA(1),S(1),N(1),D21(21),D33(3,3),F2(3,3)
1,PI(24),UV(24),X(8),Y(8),Z(4),XD(7),YD(7),ZD(7),GL(1)
COMMON IA,AA
EQUIVALENCE (IA,AA),(D21,D33),(D21(10),F22),(D21(19),F),(D21(20),G),F2BEA006
EQUIVALENCE (IA(1),IN),(IA(2),INR),(IA(3),IT),(IA(4),IP),(IA(5),I) F2BEA007
1IPRS1,(IA(6),ITYPE),(IA(7),IMAT),(IA(8),IDFG),(IA(9),INX),(IA(10),F2BEA008
2IM),(IA(11),IB),(IA(12),IMMX),(IA(13),IMMY),(IA(14),IMW2),(IA(15),F2BEA009
3IMF1),(IA(16),IARE),(IA(17),M(1)),(IA(18),M),(IA(19),M2),(IA(20),F2BEA010
4ISTR),(IA(21),FL7),(IA(22),ITEM),(IA(23),ITIC),(IA(24),IMF1), F2BEA011
5IA(32),ISUM),(IA(33),IND),(IA(34),IMS),(IA(35),IOS),(IA(37),F2BEA012
6ISR1),(IA(38),IEL1),(IA(39),ITEM),(IA(40),ITIC),(IA(41),IMF1), F2BEA013
7IA(52),J31),(IA(53),J4),(IA(54),J5),(IA(55),J6),(IA(56),J7),(IA(57),F2BEA014
8JIB),(IA(58),JTY),(IA(59),IBR),(IA(60),IRI),(IA(61),ID),(IA(62),F2BEA015
9IA),(IA(63),IDT),(IA(64),IIV),(IA(65),ITF),(IA(66),IIP),(IA(67),F2BEA016
EQUIVALENCE (IA(66),ICAR),(IA(67),ICIX),(IA(68),ICIV),(IA(69), F2BEA017
1ICIZ),(IA(70),ICF),(IA(71),IX),(IA(72),IY),(IA(73),IZ), F2BEA018
2IA(74),ICJ),(IA(75),IDF),(IA(76),IST),(IA(77),IIS) F2BEA019
3,(IA(78),IGEM),(IA(79),IFRR),(IA(80),ITE),(IA(81),IDT),(IA(82),F2BEA020
4AA(83),ALI),(AA(84),AL2),(AA(85),AL3),(AA(86),M21),(AA(107),P), F2BEA021
5AA(131),H),(AA(135),X),(AA(136),Y),(AA(171),Z),(AA(179),X), F2BEA022
6AA(186),Y),(AA(193),Z),(AA(351),S),(AA(401),ZGF) F2BEA023
7,(AA(421),INP),(AA(43),IPRG),(AA(44),IPEN),(AA(45),GINS),(AA(46),F2BEA024
8),(AA(47),G1),(AA(48),G2),(AA(49),G3) F2BEA025
EQUIVALENCE (IA(349),NTIC),(IA(348),ISDT),(IA(347),ISDY),(IA(346), F2BEA026
1,ISD2),(IA(345),J9),(IA(344),J10),(IA(343),JPRS),(IA(342),JSDY) F2BEA027
2,(IA(341),JSD2),(IA(340),JAKE),(IA(339),JMW),(IA(338),JMW1) F2BEA028
3,(IA(337),JMW2),(IA(336),JMF1),(IA(335),IAS),(IA(334),IDZ) F2BEA029
4,(IA(333),IPR),(AA(332),DGY),(AA(331),DGZ),(AA(330),PREF1) F2BEA030
5,(IA(329),IPR1) F2BEA031
DIMENSION A(6,6),DIR(3,3),UVG(12),T(6),PD(3),PN(3),DUG(3)
EQUIVALENCE (AA(200),A),(AA(236),FL),(AA(237),AREA),(AA(238),I) F2BEA033
1,(AA(239),J1),(AA(240),IR),(IA(241),JR),(AA(242),NY),(AA(244),DIR) F2BEA034
2,(AA(306),UVG),(AA(291),PD),(AA(294),PN),(AA(297),DUG),(AA(300),T) F2BEA035
EL=SQRT(FX(1)*FX(1)+YD(1)*YD(1)+ZD(1)*ZD(1))
IF (EL) 1010,1010,110
110 IF (IEL=3) 115,250,115
115 DIR(1,1)=XD(1)/EL
DIR(1,2)=YD(1)/EL
DIR(1,3)=ZD(1)/EL
IF (JMF1) 1010,210,130
210 IF (IGEM) 1010,220,1010
330 ICFL=ICFL+JMF1
140 IF (ABS(F*AA(1CFLJ)-90.) > 140,140,1010
IF (F=1) 144,144,144
144 SIGNF=1
GO TO 148
146 SIGNF=-1
148 IF (ABS(DIR(1,1))-1E-3) 150,150,180
150 IF (ABS(DIR(1,3))-1E-3) 180,180,170
160 DIR(2,2)=COS(F)
ASO=DIR(1,1)*DIR(1,1)
AX=1.-DIR(1,1)*DIR(1,1)/ASO
BX=DIR(1,2)*DIR(1,2)/ASO
CX=DIR(2,2)*DIR(2,2)+DIR(1,2)*DIR(1,2)*DIR(2,2)/ASO-1
DIR(2,3)=(-BX+SIGNF*SQRT(1-BX*BX-AX*AX))/AX
165 DIR(2,1)=1.-DIR(1,1)*DIR(2,2)-DIR(1,3)*DIR(2,3)/DIR(1,1)
GO TO 190
170 DIR(2,2)=COS(F)
DIR(2,3)=-DIR(1,2)*DIR(2,2)/DIR(1,3)
DIR(2,1)=SIGNF*SQRT(1.-DIR(2,2)*DIR(2,2)-DIR(2,3)*DIR(2,3))
GO TO 190
180 DIR(2,3)=SIGNF*F
DIR(2,1)=SIGNF*SQRT(1.-DIR(2,3)*DIR(2,3))
190 DIR(3,1)=DIR(1,2)*DIR(2,3)-DIR(1,3)*DIR(2,2)
DIR(3,2)=-DIR(1,1)*DIR(2,3)+DIR(1,3)*DIR(2,2)
DIR(3,3)=DIR(1,1)*DIR(2,2)-DIR(1,2)*DIR(2,3)
GO TO 1000
220 DIR(2,1)=DIR(1,2)
DIR(2,2)=DIR(1,1)
DIR(2,3)=0
DIR(3,1)=0
DIR(3,2)=0
DIR(3,3)=1
GO TO 1000
250 DIR(1,1)=1
DIR(1,2)=0
DIR(1,3)=0
DIR(2,1)=0
DIR(2,2)=0
DIR(2,3)=XD(1)/FL
DIR(3,1)=0
DIR(3,2)=YD(1)/FL
DIR(3,3)=0
DIR(3,2)=-DIR(2,3)
DIR(3,3)=DIR(2,2)
1000 RETURN
1010 IERR=1
GO TO 1000
END
F2COD000
F2COD001
F2COD002
F2COD003
F2COD004
F2COD005
F2COD006
F2COD007
F2COD008
F2COD009
F2COD010
F2COD011
F2COD012
F2COD013
F2COD014
F2COD015
F2COD016
F2COD017
F2COD018
F2COD019
F2COD020
F2COD021
F2COD022
F2COD023
F2COD024
F2COD025
F2COD026
F2COD027
F2COD028
F2COD029
F2COD030
F2COD031
F2COD032
F2COD033
F2COD034
F2COD035
F2COD036
F2COD037
F2COD038
F2COD039
F2COD040
F2COD041
F2COD042
F2COD043
F2COD044
F2COD045
F2COD046
F2COD047
F2COD048
F2COD049
F2COD050
F2COD051
F2COD052
F2COD053
F2COD054
F2COD055
F2COD056
F2COD057
F2COD058
F2COD059
F2COD060
F2COD061
F2COD062
F2COD063
F2COD064
F2COD065
F2COD066
F2COD067
F2COD068
F2COD069
F2COD070
F2COD071
F2COD072
F2COD073
F2COD074
F2COD075
F2COD076
F2COD077
F2COD078
F2COD079
F2COD080
F2COD081
F2COD082
F2COD083
F2COD084
F2COD085
F2COD086
F2COD087
F2COD088
F2COD089
F2COD090
F2COD091
```

Table VII-20. Source program listing of subroutine CORT (Link 2)

```

C
LAREL
SUBROUTINE CORT
DIMENSION COORDINATES OF TRIANGULAR SHELL ELEMENT IN LOCAL COORDINATES
DIMENSION I(11),AA(1),S(1),N(1),D21(21),D33(3),E22(3,3)
1,P(24),UV(24),X(18),Y(18),Z(18),XD(17),YD(17),ZD(17),G(11)
COMMON IAA,AA
EQUIVALENCE (IA,AA), (D21,D33), (D21(10),F22), (D21(19),E), (D21(20),G)
EQUIVALENCE (IA(1),IN), (IA(2),IN), (IA(3),IT), (IA(4),IP), (IA(5),
1IPRS), (IA(6),ITYPE), (IA(7),IPAT), (IA(8),IDEG), (IA(9),INX), (IA(10),
2IH), (IA(11),IR), (IA(12),IMX), (IA(13),IMY), (IA(14),IMZ), (IA(15),
3IMF1), (IA(16),IARE), (IA(17),N(1)), (IA(25),M), (IA(26),IT), (IA(27),
4ISTR), (IA(28),IFLT), (IA(29),ITEM), (IA(30),ITIC), (IA(31),IMCT),
5IA(32),ISUM), (IA(33),IND), (IA(34),IMS), (IA(36),IDS), (IA(37),
6IORD), (IA(38),INRD), (IA(39),ACEL ), (IA(50),J1), (IA(51),J2),
7IA(52),J3), (IA(53),J4), (IA(54),J5), (IA(55),J6), (IA(56),J7), (IA(57),
8J), (IA(58),JTY), (IA(59),JBB), (IA(60),IBD), (IA(61),ID), (IA(62),
9IA), (IA(63),ID1), (IA(64),IDY), (IA(65),IDZ), (IA(41),ITAP)
EQUIVALENCE (IA(66),ICAR), (IA(67),ICIX), (IA(68),ICIX), (IA(69),
1ICIZ), (IA(70),ICFI), (IA(71),IXX), (IA(72),IYY), (IA(73),IYZ),
2IA(74),IIC), (IA(75),IDEF), (IA(76),IST), (IA(77),IIS)
3IA(78),IGEM), (IA(79),IERR), (AA(80),TE), (AA(81),DT), (AA(82),DG),
4AA(83),AL1), (AA(84),AL2), (AA(85),AL3), (AA(86),D21), (AA(87),D1),
5AA(88),YD), (AA(89),XD), (AA(90),YD), (AA(91),XD),
6AA(186),YD), (AA(193),ZD), (AA(135),S), (AA(40),ZGEM)
7AA(42),INP), (AA(43),IPRS), (AA(44),IPEN), (AA(45),CONS), (AA(46),
8IA(47),G1), (AA(48),G2), (AA(49),G3)
EQUIVALENCE (IA(349),NTIC), (IA(348),ISDT), (IA(347),ISDY), (IA(346),
1ISDZ), (IA(345),J9), (IA(344),J10), (IA(343),JPRS), (IA(342),JSIY)
2IA(341),JSDZ), (IA(340),JARE), (IA(339),JMX), (IA(338),JMY)
3IA(337),JMZ), (IA(336),JMF1), (IA(335),JMS), (IA(334),JTDZ)
4IA(333),IPR), (AA(332),DGY), (AA(331),DGZ), (AA(330),PRES)
5IA(329),IPR)
DIMENSION DUMX(3),DUMY(3)
EQUIVALENCE (AA(200),DUMX), (AA(203),DUMY)
DIMENSION F(4,4),EN(4,4),D(1,3),DUM(18)
EQUIVALENCE (AA(209),EM), (AA(216),EN), (AA(232),F), (AA(248),D),
1AA(264),DIR), (AA(273),DUM)
EL=SQRT (XD**2+YD**2+ZD**2)
DIR(1,1)=XD(1)/EL
DIR(1,2)=YD(1)/EL
DIR(1,3)=ZD(1)/EL
DIR(3,1)=DIR(1,2)*ZD(2)-DIR(1,3)*YD(2)
DIR(3,2)=DIR(1,3)*XD(2)-DIR(1,1)*YD(2)
DIR(3,3)=DIR(1,1)*YD(2)-DIR(1,2)*XD(2)
EL=SQRT (DIR(3,1)**2+DIR(3,2)**2+DIR(3,3)**2)
DIR(3,1)=DIR(3,1)/EL
DIR(3,2)=DIR(3,2)/EL
DIR(3,3)=DIR(3,3)/EL
DIR(2,1)=DIR(3,2)*DIR(1,3)-DIR(3,3)*DIR(1,2)
DIR(2,2)=DIR(3,3)*DIR(1,1)-DIR(3,1)*DIR(1,3)
DIR(2,3)=DIR(3,1)*DIR(1,2)-DIR(3,2)*DIR(1,1)
DO I=1,3
DUMX(I)=X(I)
DUMY(I)=Y(I)
DUMZ(I)=Z(I)
DO J=1,3
DUMX(J)=X(J)
DUMY(J)=Y(J)
DUMZ(J)=Z(J)
3 DUMX(J)=DUMX(J)+DIR(J,K)*DUMX(K)
2 CONTINUE
X(1)=DUMX(1)
Y(1)=DUMX(2)
Z(1)=DUMX(3)
DO N=1,2,3
XD(1)=X(1)-X(N)
YD(1)=Y(1)-Y(N)
ZD(1)=Z(1)-Z(N)
6 RETURN
END

```

Table VII-21. Source program listing of subroutine CUTE (Link 2)

```

LAREL
SUBROUTINE CUTE (ITTM)
CUTS QUADRILATERALS AND HEXAHEDRONS INTO TRIANGLES AND TETRAHEDRONS
DIMENSION I(11),AA(1),S(1),N(1),D21(21),D33(3),E22(3,3)
1,P(24),UV(24),X(18),Y(18),Z(18),XD(17),YD(17),ZD(17),G(11)
COMMON IAA,AA
EQUIVALENCE (IA,AA), (D21,D33), (D21(10),F22), (D21(19),E), (D21(20),G)
EQUIVALENCE (IA(1),IN), (IA(2),IN), (IA(3),IT), (IA(4),IP), (IA(5),
1IPRS), (IA(6),ITYPE), (IA(7),IPAT), (IA(8),IDEG), (IA(9),INX), (IA(10),
2IH), (IA(11),IR), (IA(12),IMX), (IA(13),IMY), (IA(14),IMZ), (IA(15),
3IMF1), (IA(16),IARE), (IA(17),N(1)), (IA(25),M), (IA(26),IT), (IA(27),
4ISTR), (IA(28),IFLT), (IA(29),ITEM), (IA(30),ITIC), (IA(31),IMCT),
5IA(32),ISUM), (IA(33),IND), (IA(34),IMS), (IA(36),IDS), (IA(37),
6IORD), (IA(38),INRD), (IA(39),ACEL ), (IA(50),J1), (IA(51),J2),
7IA(52),J3), (IA(53),J4), (IA(54),J5), (IA(55),J6), (IA(56),J7), (IA(57),
8J), (IA(58),JTY), (IA(59),JBB), (IA(60),IBD), (IA(61),ID), (IA(62),
9IA), (IA(63),ID1), (IA(64),IDY), (IA(65),IDZ), (IA(41),ITAP)
EQUIVALENCE (IA(66),ICAR), (IA(67),ICIX), (IA(68),ICIX), (IA(69),
1ICIZ), (IA(70),ICFI), (IA(71),IXX), (IA(72),IYY), (IA(73),IYZ),
2IA(74),IIC), (IA(75),IDEF), (IA(76),IST), (IA(77),IIS)
3IA(78),IGEM), (IA(79),IERR), (AA(80),TE), (AA(81),DT), (AA(82),DG),
4AA(83),AL1), (AA(84),AL2), (AA(85),AL3), (AA(86),D21), (AA(87),D1),
5AA(88),YD), (AA(89),XD), (AA(90),YD), (AA(91),XD),
6AA(186),YD), (AA(193),ZD), (AA(135),S), (AA(40),ZGEM)
7AA(42),INP), (AA(43),IPRS), (AA(44),IPEN), (AA(45),CONS), (AA(46),
8IA(47),G1), (AA(48),G2), (AA(49),G3)
EQUIVALENCE (IA(349),NTIC), (IA(348),ISDT), (IA(347),ISDY), (IA(346),
1ISDZ), (IA(345),J9), (IA(344),J10), (IA(343),JPRS), (IA(342),JSIY)
2IA(341),JSDZ), (IA(340),JARE), (IA(339),JMX), (IA(338),JMY)
3IA(337),JMZ), (IA(336),JMF1), (IA(335),JMS), (IA(334),JTDZ)
4IA(333),IPR), (AA(332),DGY), (AA(331),DGZ), (AA(330),PRES)
5IA(329),IPR)
DIMENSION DUMX(3),DUMY(3)
EQUIVALENCE (AA(200),DUMX), (AA(203),DUMY)
DIMENSION F(4,4),EN(4,4),D(1,3),DUM(18)
EQUIVALENCE (AA(209),EM), (AA(216),EN), (AA(232),F), (AA(248),D),
1AA(264),DIR), (AA(273),DUM)
EL=SQRT (XD**2+YD**2+ZD**2)
DIR(1,1)=XD(1)/EL
DIR(1,2)=YD(1)/EL
DIR(1,3)=ZD(1)/EL
DIR(3,1)=DIR(1,2)*ZD(2)-DIR(1,3)*YD(2)
DIR(3,2)=DIR(1,3)*XD(2)-DIR(1,1)*YD(2)
DIR(3,3)=DIR(1,1)*YD(2)-DIR(1,2)*XD(2)
EL=SQRT (DIR(3,1)**2+DIR(3,2)**2+DIR(3,3)**2)
DIR(3,1)=DIR(3,1)/EL
DIR(3,2)=DIR(3,2)/EL
DIR(3,3)=DIR(3,3)/EL
DIR(2,1)=DIR(3,2)*DIR(1,3)-DIR(3,3)*DIR(1,2)
DIR(2,2)=DIR(3,3)*DIR(1,1)-DIR(3,1)*DIR(1,3)
DIR(2,3)=DIR(3,1)*DIR(1,2)-DIR(3,2)*DIR(1,1)
DO I=1,3
DUMX(I)=X(I)
DUMY(I)=Y(I)
DUMZ(I)=Z(I)
DO J=1,3
DUMX(J)=X(J)
DUMY(J)=Y(J)
DUMZ(J)=Z(J)
3 DUMX(J)=DUMX(J)+DIR(J,K)*DUMX(K)
2 CONTINUE
X(1)=DUMX(1)
Y(1)=DUMX(2)
Z(1)=DUMX(3)
DO N=1,2,3
XD(1)=X(1)-X(N)
YD(1)=Y(1)-Y(N)
ZD(1)=Z(1)-Z(N)
6 RETURN
END

```

Table VII-22. Source program listing of subroutine DARN (Link 2)

```

C LABEL
C=ZURM SUBROUTINE DARN (KS,KBS,CCC,KOE) F20R000
PREPARES INFORMATION RELATD WITH DIMSIRAINIS FOR ASSEMBLY F20R001
DIMENSION A(1),AA(1),S(1),N(1),D21(21),D33(3,3),E22(3,3) F20R002
1,P(24),UV(24),X(18),Y(18),Z(18),XD(7),YD(7),ZD(7),G(1) F20R003
COMMON IA,AA F20R004
EQUIVALENCE (IA,AA), (D21,D33), (D21(10),F22), (D21(19),F1), (D21(20),G1) F20R005
EQUIVALENCE (IA(1),IN), (IA(2),IAM), (IA(3),II), (IA(4),IP1), (IA(5), F20R007
11PR5), (IA(6),ITYPE1), (IA(7),IMAT), (IA(8),IDEG), (IA(9),INX), (IA(10),F20R008
21H), (IA(11),IR), (IA(12),IMAX), (IA(13),IMY), (IA(14),IMZ), (IA(15),F20R009
31MF1), (IA(16),IARE), (IA(17),N(1)), (IA(25),M), (IA(26),ITY), (IA(27),F20R010
41STR), (IA(28),IELT), (IA(29),ITEM), (IA(30),ITIC), (IA(31),IMF1), F20R011
51A(32),ISUM), (IA(33),IND), (IA(34),IP5), (IA(35),I05), (IA(37), F20R012
61ORR), (IA(38),IDRD1), (IA(39),ACEL), (IA(50),J1), (IA(51),J2), F20R013
71A(52),J3), (IA(53),J4), (IA(54),J5), (IA(55),J6), (IA(56),J7), (IA(57),F20R014
81J8), (IA(58),JTY), (IA(59),IRK), (IA(60),IRU), (IA(61),IID), (IA(62),F20R015
91IA), (IA(63),IDT), (IA(64),IDY), (IA(65),ITF), (IA(67),ITAP) F20R016
EQUIVALENCE (IA(66),ICAR), (IA(67),ICIX), (IA(68),ICY), (IA(69), F20R017
1IC12), (IA(70),ICF1), (IA(71),ICX), (IA(72),IYY), (IA(73),I72) F20R018
21A(74),IIC), (IA(75),IDEF), (IA(76),I57), (IA(77),I15) F20R019
31A(78),IDEG), (IA(79),IFRR), (IA(80),TF), (IA(81),DF), (IA(82),DF) F20R020
41A(83),ALL), (IA(84),AL2), (IA(85),AL3), (IA(86),D21), (IA(107),P1), F20R021
51A(131),UV1), (AA(155),X), (AA(163),Y), (AA(171),Z), (AA(179),XD), F20R022
61A(186),YD), (AA(193),ZD), (AA(351),S), (AA(40),ZGFM) F20R023
71A(42),INP), (AA(43),IPRG), (AA(44),IPFN), (AA(45),CONS), (AA(46),IUF20R024
81), (AA(47),G1), (AA(48),G2), (AA(49),G3) F20R025
EQUIVALENCE (IA(369),NTIC), (IA(348),ISDT), (IA(347),ISDY), (IA(346) F20R026
1,ISDZ), (IA(345),J9), (IA(346),J10), (IA(343),JPRS), (IA(342),J5Y) F20R027
21A(134),JSDZ), (IA(340),JARF), (IA(339),JMMX), (IA(338),JMMY) F20R028
31A(337),JMMZ), (IA(336),JMF1), (IA(335),JTAS), (IA(334),ID7) F20R029
41A(333),IPR), (AA(332),DGY), (AA(331),DGT), (AA(330),PRE5) F20R030
51A(329),IPR) F20R031
DIMENSION IMS(25),CCC(25),JRS(25),CCC(25) F20R032
EQUIVALENCE (IA(200),I05), (IA(225),J05), (AA(250),CCC1), F20R033
1, (AA(275),K05), (IA(180),K05), (IA(181),K06), (IA(182),K07) F20R034
DIMENSION KRS(1),CCC(1) F20R035
18R1=JBB1 F20R036
KR=IA(18B1) F20R037
1F (KB+IND) 301,302,302 F20R038
1F (KB) 303,1,304 F20R039
KOE=1 F20R040
1IC1=IICAKS F20R041
CCC1=AA(1)IC1 F20R042
KRS(1)=KB F20R043
GD TO 308 F20R044
KOE=1 F20R045
CCC(1)=1 F20R046
KRS(1)=KB F20R047
GD TO 308 F20R048
101 ICOMP=10000+KS F20R049
INCR=1 F20R050
DD 306 ISOR=1,IND F20R051
18O1=180+ISOR F20R052
1F (XARSE(IA(1801))-ICOMP) 306,307,306 F20R053
18RE=180+ISOR F20R054
1IC1=IIC+ISOR F20R055
KRS(1)=KRS+ISOR F20R056
CCC(1)=KRS+ISOR F20R057
INCR=INCR+1 F20R058
CONTINUE F20R059
KOE=INCR-1 F20R060
RETURN F20R061
101 KOE=0 F20R062
GD TO 308 F20R063
END F20R064

```

Table VII-23. Source program listing of subroutine DMM (Link 2)

```

C LABEL F20R000
C=ZURM SUBROUTINE DMM (A,B,M,C) F20R001
OBTAINS THE PRODUCT OF ELEMENT STIFFNESS MATRIX IIMS A VECTOR F20R002
DIMENSION A(1),B(1),C(1) F20R003
DD 10 1=1,M F20R004
ISS=1,M F20R005
DD 9 K=1,M F20R006
ISS=ISS+M F20R007
C(1)=C(1)+A(ISS)*B(K) F20R008
CONTINUE F20R009
RETURN F20R010
END F20R011

```

Table VII-24. Source program listing of subroutine ELDI (Link 2)

```

C LABEL F2FL000
C=ZELL SUBROUTINE ELDI F2FL001
OBTAINS UNIT VECTOR OF PRESSURE FOR LINE ELEMENT F2FL002
DIMENSION A(1),AA(1),S(1),N(1),D21(21),D33(3,3),E22(3,3) F2FL003
1,P(24),UV(24),X(18),Y(18),Z(18),XD(7),YD(7),ZD(7),G(1) F2FL004
COMMON IA,AA F2FL005
EQUIVALENCE (IA,AA), (D21,D33), (D21(10),F22), (D21(19),F1), (D21(20),G1) F2FL006
EQUIVALENCE (IA(1),IN), (IA(2),IAM), (IA(3),II), (IA(4),IP1), (IA(5), F2FL007
11PR5), (IA(6),ITYPE1), (IA(7),IMAT), (IA(8),IDEG), (IA(9),INX), (IA(10),F2FL008
21H), (IA(11),IR), (IA(12),IMAX), (IA(13),IMY), (IA(14),IMZ), (IA(15),F2FL009
31MF1), (IA(16),IARE), (IA(17),N(1)), (IA(25),M), (IA(26),ITY), (IA(27),F2FL010
41STR), (IA(28),IELT), (IA(29),ITEM), (IA(30),ITIC), (IA(31),IMF1), F2FL011
51A(32),ISUM), (IA(33),IND), (IA(34),IP5), (IA(35),I05), (IA(37), F2FL012
61ORR), (IA(38),IDRD1), (IA(39),ACEL), (IA(50),J1), (IA(51),J2), F2FL013
71A(52),J3), (IA(53),J4), (IA(54),J5), (IA(55),J6), (IA(56),J7), (IA(57),F2FL014
81J8), (IA(58),JTY), (IA(59),IRK), (IA(60),IRU), (IA(61),IID), (IA(62),F2FL015
91IA), (IA(63),IDT), (IA(64),IDY), (IA(65),ITF), (IA(67),ITAP) F2FL016
EQUIVALENCE (IA(66),ICAR), (IA(67),ICIX), (IA(68),ICY), (IA(69), F2FL017
1IC12), (IA(70),ICF1), (IA(71),ICX), (IA(72),IYY), (IA(73),I72) F2FL018
21A(74),IIC), (IA(75),IDEF), (IA(76),I57), (IA(77),I15) F2FL019
31A(78),IDEG), (IA(79),IFRR), (IA(80),TF), (IA(81),DF), (IA(82),DF) F2FL020
41A(83),ALL), (IA(84),AL2), (IA(85),AL3), (IA(86),D21), (IA(107),P1), F2FL021
51A(131),UV1), (AA(155),X), (AA(163),Y), (AA(171),Z), (AA(179),XD), F2FL022
61A(186),YD), (AA(193),ZD), (AA(351),S), (AA(40),ZGFM) F2FL023
71A(42),INP), (AA(43),IPRG), (AA(44),IPFN), (AA(45),CONS), (AA(46),IUF2FL024
81), (AA(47),G1), (AA(48),G2), (AA(49),G3) F2FL025
EQUIVALENCE (IA(369),NTIC), (IA(348),ISDT), (IA(347),ISDY), (IA(346) F2FL026
1,ISDZ), (IA(345),J9), (IA(346),J10), (IA(343),JPRS), (IA(342),J5Y) F2FL027
21A(134),JSDZ), (IA(340),JARF), (IA(339),JMMX), (IA(338),JMMY) F2FL028
31A(337),JMMZ), (IA(336),JMF1), (IA(335),JTAS), (IA(334),ID7) F2FL029
41A(333),IPR), (AA(332),DGY), (AA(331),DGT), (AA(330),PRE5) F2FL030
51A(329),IPR) F2FL031
DIMENSION A(6,6),D1(3,3),P(6,12),T(6),P(13),P(13),DUG(3) F2FL032
EQUIVALENCE (IA(200),A), (IA(236),EL1), (IA(237),AKEA), (AA(238),II) F2FL033
1, (AA(239),J01), (AA(240),IR), (AA(241),JK), (AA(242),NY), (AA(264),DIR) F2FL034
21A(304),UVG), (AA(291),PD), (AA(294),PN), (AA(297),DUG), (AA(300),IUF2FL035
31=SORFIX(1)*XD(1)+YD(1)+ZD(1)*ZD(1) F2FL036
IF (EL1) 1010,1010,110 F2FL037
110 ELI=1/VEL F2FL038
T(1)=X(1)*VEL F2FL039
113=YD(1)*VEL F2FL040
T(5)=ZD(1)*VEL F2FL041
PN(1)=DUG(2)*T(15)-DUG(3)*T(3) F2FL042
PN(2)=DUG(3)*T(1)-DUG(1)*T(5) F2FL043
PN(3)=DUG(1)*T(3)-DUG(2)*T(1) F2FL044
VEL=SORF(PN(1)*PN(1)+PN(2)*PN(2)+PN(3)*PN(3)) F2FL045
1F (VEL) 1E-4) 220,220,230 F2FL046
220 PRES=0 F2FL048
GD TO 1000 F2FL049
230 VEL=1/VEL F2FL050
DD 300 I=1,3 F2FL051
300 PN(I)=PN(I)*VEL F2FL052
PD(1)=T(3)*PN(3)-T(5)*PN(2) F2FL053
PD(2)=T(15)*PN(1)-T(1)*PN(3) F2FL054
PD(3)=T(1)*PN(2)-T(3)*PN(1) F2FL055
VEL=1/(VEL*(PD(1)*PD(1)+PD(2)*PD(2)+PD(3)*PD(3))) F2FL056
DD 400 I=1,3 F2FL057
400 PD(I)=PD(I)*VEL F2FL058
1000 RETURN F2FL059
1010 IERR=1 F2FL060
GD TO 1000 F2FL061
END F2FL061

```

Table VII-25. Source program listing of subroutine PLBE (Link 2)

```

* LABEL
CE2PLR
SUBROUTINE PLBE
GENFRATES SUBMATRICES FOR PLPMT TYPE 3 AND 4
DIMENSION I(1),AA(1),S(1),N(8),D21(21),D33(3),E22(3,3)
1,P(24),UV(24),X(8),Y(8),Z(8),XD(7),YD(7),ZD(7),G(1)
COMMON IA,AA
EQUIVALENCE (IA,AA), (D21,D33), (D21(10),E22), (D21(19),F), (D21(20),G)
EQUIVALENCE (IA(1),IN), (IA(2),IN), (IA(3),IT), (IA(4),IP), (IA(5),I)
1)PR5, (IA(6),I)YPE, (IA(7),I)MAT, (IA(8),I)DFG, (IA(9),I)MX, (IA(10),I)
2)H, (IA(11),I)B, (IA(12),I)MK, (IA(13),I)MY, (IA(14),I)MZ, (IA(15),I)
3)MF, (IA(16),I)ARE, (IA(17),I)TEM, (IA(18),I)ITEM, (IA(19),I)ITC, (IA(20),I)TET,
4)STR, (IA(21),I)T, (IA(22),I)M, (IA(23),I)M, (IA(24),I)T, (IA(25),I)T,
5)IA(32),ISUM, (IA(33),IND), (IA(34),IMS), (IA(35),IDS), (IA(36),I)
6)IRD, (IA(37),I)RD, (IA(38),I)RD, (IA(39),I)RD, (IA(40),I)RD, (IA(41),I)RD,
7)IA(52),J3, (IA(53),J4), (IA(54),J5), (IA(55),J6), (IA(56),J7), (IA(57),J8)
8),J81, (IA(58),JTY), (IA(59),I)B, (IA(60),I)B, (IA(61),I)B, (IA(62),I)B,
9)IA(63),I)D, (IA(64),I)D, (IA(65),I)D, (IA(66),I)D, (IA(67),I)D,
EQUIVALENCE (IA(66),I)CAR, (IA(67),I)CX, (IA(68),I)CY, (IA(69),I)
1)C(2), (IA(70),I)CF, (IA(71),I)X, (IA(72),I)Y, (IA(73),I)Z),
2)IA(74),I)C, (IA(75),I)DF, (IA(76),I)ST, (IA(77),I)S)
3, (IA(78),I)GEM, (IA(79),I)ERR, (IA(80),I)TE, (IA(81),I)DT, (IA(82),I)DG,
4)AA(83),AL1, (AA(84),AL2), (AA(85),AL3), (AA(86),D21), (AA(107),P),
5)AA(131),UV, (AA(155),X), (AA(156),Y), (AA(157),Z), (AA(179),XD),
6)AA(186),YD, (AA(193),ZD), (AA(351),S), (AA(401),ZGFM)
7, (AA(421),I)NP, (AA(443),I)PB, (AA(444),I)PN, (AA(465),I)CONS, (AA(466),I)
8), (AA(477),G), (AA(488),G2), (AA(491),G3)
EQUIVALENCE (IA(349),NTIC), (IA(348),ISDT), (IA(347),ISDY), (IA(346)
1, ISDZ), (IA(345),J9), (IA(344),J10), (IA(343),JPRS), (IA(342),J5DY)
2, (IA(341),J5DZ), (IA(340),JARE), (IA(339),JMX), (IA(338),JMY)
3, (IA(337),JMMZ), (IA(336),JMF), (IA(335),JIAS), (IA(334),I)DZ)
4, (IA(333),I)PR, (AA(332),DGY), (AA(331),DGZ), (AA(330),PRFS)
5, (IA(329),I)PR)
DIMENSION A(6,6),DIR(3,3),UVG(12),T(6),PD(3),PN(3),RUG(13)
EQUIVALENCE (AA(200),A), (AA(236),EL), (AA(237),AREA), (AA(238),I)
1, (AA(239),J3), (AA(240),IR), (AA(241),JR), (AA(242),NY), (AA(264),DIR)
2, (AA(306),UVG), (AA(291),PD), (AA(296),PN), (AA(297),RUG), (AA(300),T)
IF (JMX) I(10),I(10),I(10)
150 ICX=ICX+JMX
IF (JMY) I(10),I(10),I(10)
150 ICY=ICY+JMY
150 A(1,1)=12, *E=AA(1)CYJ/(EL**3)
A(1,2)=-A(1,1)
A(2,1)=A(1,1)
A(2,2)=A(1,1)
A(2,3)=A(1,1)
A(2,4)=A(1,1)
A(2,5)=A(1,1)
A(2,6)=A(1,1)
A(3,1)=A(1,1)
A(3,2)=A(1,1)
A(3,3)=A(1,1)
A(3,4)=A(1,1)
A(3,5)=A(1,1)
A(3,6)=A(1,1)
A(4,1)=A(1,1)
A(4,2)=A(1,1)
A(4,3)=A(1,1)
A(4,4)=A(1,1)
A(4,5)=A(1,1)
A(4,6)=A(1,1)
A(5,1)=A(1,1)
A(5,2)=A(1,1)
A(5,3)=A(1,1)
A(5,4)=A(1,1)
A(5,5)=A(1,1)
A(5,6)=A(1,1)
A(6,1)=A(1,1)
A(6,2)=A(1,1)
A(6,3)=A(1,1)
A(6,4)=A(1,1)
A(6,5)=A(1,1)
A(6,6)=A(1,1)
DO 200 J=1,6
DO 200 I=1,6
200 A(I,J)=A(1,1)
1000 RETURN
1010 IPR=1
GO TO 1000
END
    
```

Table VII-26. Source program listing of subroutine RLOC (Link 2)

```

* LABEL
CE2KLC
SUBROUTINE RLOC
ADD SUBMATRICES TO FORM ELEMENT STIFFNESS MATRICES OF LINE ELEMENT
DIMENSION I(1),AA(1),S(1),N(8),D21(21),D33(3),E22(3,3)
1,P(24),UV(24),X(8),Y(8),Z(8),XD(7),YD(7),ZD(7),G(1)
COMMON IA,AA
EQUIVALENCE (IA,AA), (D21,D33), (D21(10),E22), (D21(19),F), (D21(20),G)
EQUIVALENCE (IA(1),IN), (IA(2),IN), (IA(3),IT), (IA(4),IP), (IA(5),I)
1)PR5, (IA(6),I)YPE, (IA(7),I)MAT, (IA(8),I)DFG, (IA(9),I)MX, (IA(10),I)
2)H, (IA(11),I)B, (IA(12),I)MK, (IA(13),I)MY, (IA(14),I)MZ, (IA(15),I)
3)MF, (IA(16),I)ARE, (IA(17),I)TEM, (IA(18),I)ITEM, (IA(19),I)ITC, (IA(20),I)TET,
4)STR, (IA(21),I)T, (IA(22),I)M, (IA(23),I)M, (IA(24),I)T, (IA(25),I)T,
5)IA(32),ISUM, (IA(33),IND), (IA(34),IMS), (IA(35),IDS), (IA(36),I)
6)IRD, (IA(37),I)RD, (IA(38),I)RD, (IA(39),I)RD, (IA(40),I)RD, (IA(41),I)RD,
7)IA(52),J3, (IA(53),J4), (IA(54),J5), (IA(55),J6), (IA(56),J7), (IA(57),J8)
8),J81, (IA(58),JTY), (IA(59),I)B, (IA(60),I)B, (IA(61),I)B, (IA(62),I)B,
9)IA(63),I)D, (IA(64),I)D, (IA(65),I)D, (IA(66),I)D, (IA(67),I)D,
EQUIVALENCE (IA(66),I)CAR, (IA(67),I)CX, (IA(68),I)CY, (IA(69),I)
1)C(2), (IA(70),I)CF, (IA(71),I)X, (IA(72),I)Y, (IA(73),I)Z),
2)IA(74),I)C, (IA(75),I)DF, (IA(76),I)ST, (IA(77),I)S)
3, (IA(78),I)GEM, (IA(79),I)ERR, (IA(80),I)TE, (IA(81),I)DT, (IA(82),I)DG,
4)AA(83),AL1, (AA(84),AL2), (AA(85),AL3), (AA(86),D21), (AA(107),P),
5)AA(131),UV, (AA(155),X), (AA(156),Y), (AA(157),Z), (AA(179),XD),
6)AA(186),YD, (AA(193),ZD), (AA(351),S), (AA(401),ZGFM)
7, (AA(421),I)NP, (AA(443),I)PB, (AA(444),I)PN, (AA(465),I)CONS, (AA(466),I)
8), (AA(477),G), (AA(488),G2), (AA(491),G3)
EQUIVALENCE (IA(349),NTIC), (IA(348),ISDT), (IA(347),ISDY), (IA(346)
1, ISDZ), (IA(345),J9), (IA(344),J10), (IA(343),JPRS), (IA(342),J5DY)
2, (IA(341),J5DZ), (IA(340),JARE), (IA(339),JMX), (IA(338),JMY)
3, (IA(337),JMMZ), (IA(336),JMF), (IA(335),JIAS), (IA(334),I)DZ)
4, (IA(333),I)PR, (AA(332),DGY), (AA(331),DGZ), (AA(330),PRFS)
5, (IA(329),I)PR)
DIMENSION A(6,6),DIR(3,3),UVG(12),T(6),PD(3),PN(3),RUG(13)
EQUIVALENCE (AA(200),A), (AA(236),EL), (AA(237),AREA), (AA(238),I)
1, (AA(239),J3), (AA(240),IR), (AA(241),JR), (AA(242),NY), (AA(264),DIR)
2, (AA(306),UVG), (AA(291),PD), (AA(296),PN), (AA(297),RUG), (AA(300),T)
IF (JMX) I(10),I(10),I(10)
150 ICX=ICX+JMX
IF (JMY) I(10),I(10),I(10)
150 ICY=ICY+JMY
150 A(1,1)=12, *E=AA(1)CYJ/(EL**3)
A(1,2)=-A(1,1)
A(2,1)=A(1,1)
A(2,2)=A(1,1)
A(2,3)=A(1,1)
A(2,4)=A(1,1)
A(2,5)=A(1,1)
A(2,6)=A(1,1)
A(3,1)=A(1,1)
A(3,2)=A(1,1)
A(3,3)=A(1,1)
A(3,4)=A(1,1)
A(3,5)=A(1,1)
A(3,6)=A(1,1)
A(4,1)=A(1,1)
A(4,2)=A(1,1)
A(4,3)=A(1,1)
A(4,4)=A(1,1)
A(4,5)=A(1,1)
A(4,6)=A(1,1)
A(5,1)=A(1,1)
A(5,2)=A(1,1)
A(5,3)=A(1,1)
A(5,4)=A(1,1)
A(5,5)=A(1,1)
A(5,6)=A(1,1)
A(6,1)=A(1,1)
A(6,2)=A(1,1)
A(6,3)=A(1,1)
A(6,4)=A(1,1)
A(6,5)=A(1,1)
A(6,6)=A(1,1)
DO 200 J=1,6
DO 200 I=1,6
200 A(I,J)=A(1,1)
1000 RETURN
1010 IPR=1
GO TO 1000
END
    
```

Table VII-27. Source program listing of subroutine S01 (Link 2)

```

* LABEL
CE2S01
SUBROUTINE S01
GENFRATES FOR ELEMENT TYPE 1 STIFFNESS AND LOAD MATRICES
DIMENSION I(1),AA(1),S(1),N(8),D21(21),D33(3),E22(3,3)
1,P(24),UV(24),X(8),Y(8),Z(8),XD(7),YD(7),ZD(7),G(1)
COMMON IA,AA
EQUIVALENCE (IA,AA), (D21,D33), (D21(10),E22), (D21(19),F), (D21(20),G)
EQUIVALENCE (IA(1),IN), (IA(2),IN), (IA(3),IT), (IA(4),IP), (IA(5),I)
1)PR5, (IA(6),I)YPE, (IA(7),I)MAT, (IA(8),I)DFG, (IA(9),I)MX, (IA(10),I)
2)H, (IA(11),I)B, (IA(12),I)MK, (IA(13),I)MY, (IA(14),I)MZ, (IA(15),I)
3)MF, (IA(16),I)ARE, (IA(17),I)TEM, (IA(18),I)ITEM, (IA(19),I)ITC, (IA(20),I)TET,
4)STR, (IA(21),I)T, (IA(22),I)M, (IA(23),I)M, (IA(24),I)T, (IA(25),I)T,
5)IA(32),ISUM, (IA(33),IND), (IA(34),IMS), (IA(35),IDS), (IA(36),I)
6)IRD, (IA(37),I)RD, (IA(38),I)RD, (IA(39),I)RD, (IA(40),I)RD, (IA(41),I)RD,
7)IA(52),J3, (IA(53),J4), (IA(54),J5), (IA(55),J6), (IA(56),J7), (IA(57),J8)
8),J81, (IA(58),JTY), (IA(59),I)B, (IA(60),I)B, (IA(61),I)B, (IA(62),I)B,
9)IA(63),I)D, (IA(64),I)D, (IA(65),I)D, (IA(66),I)D, (IA(67),I)D,
EQUIVALENCE (IA(66),I)CAR, (IA(67),I)CX, (IA(68),I)CY, (IA(69),I)
1)C(2), (IA(70),I)CF, (IA(71),I)X, (IA(72),I)Y, (IA(73),I)Z),
2)IA(74),I)C, (IA(75),I)DF, (IA(76),I)ST, (IA(77),I)S)
3, (IA(78),I)GEM, (IA(79),I)ERR, (IA(80),I)TE, (IA(81),I)DT, (IA(82),I)DG,
4)AA(83),AL1, (AA(84),AL2), (AA(85),AL3), (AA(86),D21), (AA(107),P),
5)AA(131),UV, (AA(155),X), (AA(156),Y), (AA(157),Z), (AA(179),XD),
6)AA(186),YD, (AA(193),ZD), (AA(351),S), (AA(401),ZGFM)
7, (AA(421),I)NP, (AA(443),I)PB, (AA(444),I)PN, (AA(465),I)CONS, (AA(466),I)
8), (AA(477),G), (AA(488),G2), (AA(491),G3)
EQUIVALENCE (IA(349),NTIC), (IA(348),ISDT), (IA(347),ISDY), (IA(346)
1, ISDZ), (IA(345),J9), (IA(344),J10), (IA(343),JPRS), (IA(342),J5DY)
2, (IA(341),J5DZ), (IA(340),JARE), (IA(339),JMX), (IA(338),JMY)
3, (IA(337),JMMZ), (IA(336),JMF), (IA(335),JIAS), (IA(334),I)DZ)
4, (IA(333),I)PR, (AA(332),DGY), (AA(331),DGZ), (AA(330),PRFS)
5, (IA(329),I)PR)
DIMENSION A(6,6),DIR(3,3),UVG(12),T(6),PD(3),PN(3),RUG(13)
EQUIVALENCE (AA(200),A), (AA(236),EL), (AA(237),AREA), (AA(238),I)
1, (AA(239),J3), (AA(240),IR), (AA(241),JR), (AA(242),NY), (AA(264),DIR)
2, (AA(306),UVG), (AA(291),PD), (AA(296),PN), (AA(297),RUG), (AA(300),T)
IF (JMX) I(10),I(10),I(10)
150 ICX=ICX+JMX
IF (JMY) I(10),I(10),I(10)
150 ICY=ICY+JMY
150 A(1,1)=12, *E=AA(1)CYJ/(EL**3)
A(1,2)=-A(1,1)
A(2,1)=A(1,1)
A(2,2)=A(1,1)
A(2,3)=A(1,1)
A(2,4)=A(1,1)
A(2,5)=A(1,1)
A(2,6)=A(1,1)
A(3,1)=A(1,1)
A(3,2)=A(1,1)
A(3,3)=A(1,1)
A(3,4)=A(1,1)
A(3,5)=A(1,1)
A(3,6)=A(1,1)
A(4,1)=A(1,1)
A(4,2)=A(1,1)
A(4,3)=A(1,1)
A(4,4)=A(1,1)
A(4,5)=A(1,1)
A(4,6)=A(1,1)
A(5,1)=A(1,1)
A(5,2)=A(1,1)
A(5,3)=A(1,1)
A(5,4)=A(1,1)
A(5,5)=A(1,1)
A(5,6)=A(1,1)
A(6,1)=A(1,1)
A(6,2)=A(1,1)
A(6,3)=A(1,1)
A(6,4)=A(1,1)
A(6,5)=A(1,1)
A(6,6)=A(1,1)
DO 200 J=1,6
DO 200 I=1,6
200 A(I,J)=A(1,1)
1000 RETURN
1010 IPR=1
GO TO 1000
END
    
```

Table VII-28. Source program listing of subroutine S02 (Link 2)

```

* LABEL
CEZS02
SUBROUTINE S02
  GENRALS FOR ELEMENT TYPE 2 STIFFNESS AND LOAD MATRICES
  DIMENSION IA(1),AA(1),S(1),M(1),D21(2),D33(3,3),E22(3,3)
  1,P(24),UV(24),X(8),Y(8),Z(8),XD(7),YD(7),ZD(7),GL(1)
  COMMON IA,AA
  EQUIVALENCE (IA,A1,(D21,D33),(D21(10),F22),(D21(19),F), (D21(20),G),F2502005
  EQUIVALENCE (IA(1),IN),(IA(2),IBN),(IA(3),IT),(IA(4),IP),(IA(5), E2502007
  1)PRS),(IA(6),ITYPE),(IA(7),IMAT),(IA(8),IDEG),(IA(9),INX),(IA(10),E2502008
  2)H),(IA(11),IB),(IA(12),IMMX),(IA(13),IMMY),(IA(14),IMMZ),(IA(15),E2502009
  3)MF),(IA(16),IARE),(IA(17),N(1)),(IA(25),M),(IA(26),ITY),(IA(27),E2502010
  4)STR),(IA(28),IFLT),(IA(29),ITEM),(IA(30),ITIC),(IA(31),IMFI), E2502011
  5)IA(32),ISUM,(IA(33),IND),(IA(34),IMS),(IA(36),IDS),(IA(37), F2502012
  6)ORD),(IA(38),IORD1),(IA(39),ACEL),(IA(50),J1),(IA(51),J2), E2502013
  7)IA(52),J3),(IA(53),J4),(IA(54),J5),(IA(55),J6),(IA(56),J7),(IA(57),E2502014
  8)J8),(IA(58),J9),(IA(59),IBB),(IA(60),IBO),(IA(61),IID),(IA(62),E2502015
  9)IA),(IA(63),IDT),(IA(64),IDY),(IA(65),ITF),(IA(41),ITAP) F2502016
  EQUIVALENCE (IA(66),ICAR),(IA(67),ICIX),(IA(68),ICIV),(IA(69), F2502017
  1)ICZ),(IA(70),ICF),(IA(71),IX),(IA(72),IY),(IA(73),IZZ), F2502018
  2)IA(74),IIC),(IA(75),IDEF),(IA(76),IST),(IA(77),IST), F2502019
  3)IA(78),IGEM),(IA(79),IERR),(IA(80),TE),(IA(81),DT),(IA(82),DG), F2502020
  4)IA(83),AL1),(IA(84),AL2),(IA(85),AL3),(IA(86),D21),(AA(107),P), F2502021
  5)AA(131),UV),(AA(155),X),(AA(163),Y),(AA(171),Z),(AA(179),XD), F2502022
  6)AA(186),YD),(AA(193),ZD),(AA(195),S),(AA(40),ZGEM) E2502023
  7)AA(42),INP),(AA(43),IPRG),(AA(44),IPEN),(AA(45),CONS),(AA(46),IUE2502024
  8)IA(47),G1),(AA(48),G2),(AA(49),G3) F2502025
  EQUIVALENCE (IA(349),NTIC),(IA(348),ISDT),(IA(347),ISDY),(IA(346) F2502026
  1)ISD),(IA(345),J9),(IA(344),J10),(IA(343),JPRS),(IA(342),JSDY) F2502027
  2)IA(341),JSDZ),(IA(340),JARE),(IA(339),JMMX),(IA(338),JMMY) F2502028
  3)IA(337),JMMZ),(IA(336),JMF1),(IA(335),ITAS),(IA(334),IDZ) E2502029
  4)IA(333),IPR),(AA(332),DGY),(AA(331),DG1),(AA(330),PRES) F2502030
  5)IA(329),IPIR),(AA(324),PRCO) F2502031
  DIMENSION A(6),DIR(3,3),UVG(12),T(6),PD(3),PN(3),DUG(3) F2502032
  EQUIVALENCE (AA(200),A),(AA(236),EL),(AA(237),AREA),(AA(238),I1) F2502033
  1,AA(239),J1),(AA(240),J1),(AA(241),J1),(AA(242),NY),(AA(264),DIR) F2502034
  2,(AA(306),UVG),(AA(291),PD),(AA(294),PN),(AA(297),DUG),(AA(300),T) F2502035
  CALL CODI F2502036
  CALL BEAM F2502037
  IPBG=0 F2502038
  IF (JPRS) 40,50,40 F2502039
  DUG(1)=1 F2502040
  DUG(2)=0 F2502041
  DUG(3)=0 F2502042
  CALL EL0 F2502043
  PRCO=S*EL*PRES*PD(1) F2502044
  P(5)=-PRCO*EL/6 F2502045
  P(6)=-P(5) F2502046
  IPBG=1 F2502047
  IPEN=2 F2502048
  20 IF (ACEL) 60,80,60 F2502049
  60 DD TO I=2 F2502050
  70 DUG(1)=G1(1) F2502051
  CALL ELB F2502052
  CONS=S*EL*ACEL*AREA F2502053
  CACE=IDUG(1)*PD(1)+DUG(2)*PD(2)+CONS*EL/6 F2502054
  P(5)=P(5)-CACE F2502055
  P(6)=-P(5) F2502056
  IPBG=1 F2502057
  IPEN=2 F2502058
  60 IJ=1 F2502059
  IR=1 F2502060
  JR=1 F2502061
  NY=6 F2502062
  CALL RLOC F2502063
  IF (NG) 110,310,110 F2502064
  110 UVG(5)=-5*DG*AL1*EL F2502065
  UVG(6)=-UVG(5) F2502066
  DD 300 I=1,INS F2502067
  300 UV(1)=UV(1)+UVG(1) F2502068
  310 CALL STRA F2502069
  RETURN F2502070
  END F2502071

```

Table VII-29. Source program listing of subroutine S03 (Link 2)

```

* LABEL
CEZS03
SUBROUTINE S03
  GENRALS FOR ELEMENT TYPE 3 STIFFNESS AND LOAD MATRICES
  DIMENSION IA(1),AA(1),S(1),M(1),D21(2),D33(3,3),E22(3,3)
  1,P(24),UV(24),X(8),Y(8),Z(8),XD(7),YD(7),ZD(7),GL(1)
  COMMON IA,AA
  EQUIVALENCE (IA,AA),(D21,D33),(D21(10),F22),(D21(19),E1),(D21(20),G)E2503005
  EQUIVALENCE (IA(1),IN),(IA(2),IBN),(IA(3),IT),(IA(4),IP),(IA(5), E2503007
  1)PRS),(IA(6),ITYPE),(IA(7),IMAT),(IA(8),IDEG),(IA(9),INX),(IA(10),E2503008
  2)H),(IA(11),IB),(IA(12),IMMX),(IA(13),IMMY),(IA(14),IMMZ),(IA(15),E2503009
  3)MF),(IA(16),IARE),(IA(17),N(1)),(IA(25),M),(IA(26),ITY),(IA(27),E2503010
  4)STR),(IA(28),IFLT),(IA(29),ITEM),(IA(30),ITIC),(IA(31),IMFI), E2503011
  5)IA(32),ISUM,(IA(33),IND),(IA(34),IMS),(IA(36),IDS),(IA(37), F2503012
  6)ORD),(IA(38),IORD1),(IA(39),ACEL),(IA(50),J1),(IA(51),J2), E2503013
  7)IA(52),J3),(IA(53),J4),(IA(54),J5),(IA(55),J6),(IA(56),J7),(IA(57),E2503014
  8)J8),(IA(58),J9),(IA(59),IBB),(IA(60),IBO),(IA(61),IID),(IA(62),E2503015
  9)IA),(IA(63),IDT),(IA(64),IDY),(IA(65),ITF),(IA(41),ITAP) E2503016
  EQUIVALENCE (IA(66),ICAR),(IA(67),ICIX),(IA(68),ICIV),(IA(69), F2503017
  1)ICZ),(IA(70),ICF),(IA(71),IX),(IA(72),IY),(IA(73),IZZ), F2503018
  2)IA(74),IIC),(IA(75),IDEF),(IA(76),IST),(IA(77),IST), F2503019
  3)IA(78),IGEM),(IA(79),IERR),(IA(80),TE),(IA(81),DT),(IA(82),DG), F2503020
  4)IA(83),AL1),(IA(84),AL2),(IA(85),AL3),(IA(86),D21),(AA(107),P), F2503021
  5)AA(131),UV),(AA(155),X),(AA(163),Y),(AA(171),Z),(AA(179),XD), E2503022
  6)AA(186),YD),(AA(193),ZD),(AA(195),S),(AA(40),ZGEM) E2503023
  7)AA(42),INP),(AA(43),IPRG),(AA(44),IPEN),(AA(45),CONS),(AA(46),IUE2503024
  8)IA(47),G1),(AA(48),G2),(AA(49),G3) F2503025
  EQUIVALENCE (IA(349),NTIC),(IA(348),ISDT),(IA(347),ISDY),(IA(346) F2503026
  1)ISD),(IA(345),J9),(IA(344),J10),(IA(343),JPRS),(IA(342),JSDY) F2503027
  2)IA(341),JSDZ),(IA(340),JARE),(IA(339),JMMX),(IA(338),JMMY) F2503028
  3)IA(337),JMMZ),(IA(336),JMF1),(IA(335),ITAS),(IA(334),IDZ) E2503029
  4)IA(333),IPR),(AA(332),DGY),(AA(331),DG1),(AA(330),PRES) F2503030
  5)IA(329),IPIR),(AA(324),PRCO) F2503031
  DIMENSION A(6),DIR(3,3),UVG(12),T(6),PD(3),PN(3),DUG(3) F2503032
  EQUIVALENCE (AA(200),A),(AA(236),EL),(AA(237),AREA),(AA(238),I1) F2503033
  1,AA(239),J1),(AA(240),J1),(AA(241),J1),(AA(242),NY),(AA(264),DIR) E2503034
  2,(AA(306),UVG),(AA(291),PD),(AA(294),PN),(AA(297),DUG),(AA(300),T) F2503035
  CALL CODI F2503036
  CALL PLRF F2503037
  IPBG=0 F2503038
  IPEN=1 F2503039
  IF (JPRS) 40,60,40 F2503040
  40 PRCO=S*EL*PRES F2503041
  P(1)=PKC*(P(1) F2503042
  20 P(2)=PKC*(P(2) F2503043
  P(3)=PKC*(P(3)+R1(1,2)/6.+P(3) F2503044
  P(4)=-P(3)+P(4) F2503045
  P(5)=PKC*(P(5)+R1(1,1)/6.+P(5) F2503046
  P(6)=-P(5)+P(6) F2503047
  G1 I0 (60,80),IPEN F2503048
  60 IF (ACEL) 70,80,70 F2503049
  70 PRCO=S*EL*ACEL*G3 F2503050
  IPEN=2 F2503051
  GO TO 50 F2503052
  60 IJ=1 F2503053
  JR=1 F2503054
  IR=1 F2503055
  NY=6 F2503056
  CALL RLOC F2503057
  100 IF (DG2) 108,310,108 F2503058
  108 DG=DG2 F2503059
  110 CONTINUE F2503061
  UVG(5)=-5*DG*AL1*EL F2503062
  UVG(6)=-UVG(5) F2503063
  CALL TRAN (UVG,0) F2503064
  DD 300 I=1,INS F2503065
  300 UV(1)=UV(1)+UVG(1) F2503066
  310 CALL STRA F2503067
  1000 RETURN F2503068
  END F2503069

```

Table VII-30. Source program listing of subroutine S04 (Link 2)

```

* LABEL
CE2S04 SUBROUTINE S04 F2S04000
C GENERATES FOR ELEMENT TYPE 4 STIFFNESS AND LOAD MATRICES F2S04001
DIMENSION IA(1),AA(1),S(1),N(8),D21(21),D33(3,3),E22(3,3) F2S04002
1,PI(24),UV(24),X(8),Y(8),Z(8),XD(7),YD(7),ZD(7),G(11) F2S04003
COMMON IA,AA F2S04004
EQUIVALENCE(IA,AA),(D21,D33),(D21(10),E22),(D21(19),E1),(D21(20),G) F2S04005
EQUIVALENCE(IA(1),IN),(IA(2),IBN),(IA(3),IT),(IA(4),IP),(IA(5), F2S04006
1IPRS),(IA(6),ITYPE),(IA(7),IMAT),(IA(8),IDEG),(IA(9),IMX),(IA(10), F2S04008
2IH),(IA(11),IB),(IA(12),IMMX),(IA(13),IMMY),(IA(14),IMW),(IA(15), F2S04009
3IMFI),(IA(16),IARE),(IA(17),N(1)),(IA(25),M),(IA(26),ITY),(IA(27), F2S04010
4ISTR),(IA(28),ITELT),(IA(29),ITEM),(IA(30),ITIC),(IA(31),IMET), F2S04011
5IA(32),ISUM),(IA(33),IND),(IA(34),IMS),(IA(36),IDS),(IA(37), F2S04012
6IORD),(IA(38),IORDI),(IA(39),ACEL),(IA(50),JI),(IA(51),J2), F2S04013
7IA(52),J3),(IA(53),J4),(IA(54),J5),(IA(55),J6),(IA(56),J7),(IA(57), F2S04014
8I,J),(IA(58),JY),(IA(59),IBN),(IA(60),IBO),(IA(61),IIO),(IA(62), F2S04015
9IA(63),IDT),(IA(64),IDY),(IA(65),ITE),(IA(67),ITAP) F2S04016
EQUIVALENCE(IA(66),ICAR),(IA(67),ICIX),(IA(68),ICIV),(IA(69), F2S04017
1ICIZ),(IA(70),ICFI),(IA(71),IXX),(IA(72),IYY),(IA(73),ITZ), F2S04018
2IA(74),IC),(IA(75),IDEF),(IA(76),IST),(IA(77),IIS) F2S04019
3,(IA(78),IGEM),(IA(79),IFRR),(IA(80),TE),(IA(81),DT),(IA(82),DG), F2S04020
4(AA(83),AL1),(AA(84),AL2),(AA(85),AL3),(AA(86),O21),(AA(87),P), F2S04021
5(AA(131),UV),(AA(135),X),(AA(136),Y),(AA(171),Z),(AA(179),XD), F2S04022
6(AA(186),YD),(AA(193),ZD),(AA(351),S),(AA(40),ZGEM) F2S04023
7,(AA(42),IMP),(AA(43),IPRG),(AA(44),IPEN),(AA(45),CONS),(AA(46),IIE F2S04024
8),(AA(47),H1),(AA(48),G2),(AA(49),G3) F2S04025
EQUIVALENCE(IA(349),NTIC),(IA(348),ISDT),(IA(347),ISDY),(IA(346) F2S04026
1,ISDZ),(IA(345),J9),(IA(344),J10),(IA(343),JPRS),(IA(342),JSDY) F2S04027
2,(IA(341),JSDZ),(IA(340),JARE),(IA(339),JMMX),(IA(338),JMMY) F2S04028
3,(IA(337),JMMZ),(IA(336),JMF1),(IA(335),ITAS),(IA(334),IDZ) F2S04029
4,(IA(333),IPR),(IA(332),DGY),(AA(331),OC2),(AA(330),PRES) F2S04030
5,(IA(329),IPR1),(AA(324),PRCO) F2S04031
DIMENSION A(6,6),DIR(3,3),UVG(12),T(6),PN(3),PN(3),DUG(3) F2S04032
EQUIVALENCE(AA(200),A),(AA(236),EL),(AA(237),AREA),(AA(238),I) F2S04033
1,(AA(239),J3),(AA(240),IR),(AA(241),JR),(AA(242),NY),(AA(264),DIR) F2S04034
2,(AA(306),UVG),(AA(291),PD),(AA(294),PN),(AA(297),DUG),(AA(300),T) F2S04035
CALL CDDI F2S04036
IPBG=0 F2S04037
IF(IPRS) 40,60,40 F2S04038
40 DUG(1)=1. F2S04039
DUG(2)=0. F2S04040
DUG(3)=0. F2S04041
CALL EL01 F2S04042
50 PRCO=5*EL*PRES*PD(1) F2S04043
P(7)=PRCO*EL*PN(1)/6. F2S04044
P(8)=-P(7) F2S04045
P(9)=PRCO*EL*PN(2)/6. F2S04046
P(10)=-P(9) F2S04047
P(11)=PRCO*EL*PN(3)/6. F2S04048
P(12)=-P(11) F2S04049
IPBG=1 F2S04050
IPEN=3 F2S04051
60 IF (ACEL) 70,90,70 F2S04052
70 DD 80 I=1,3 F2S04053
80 DUG(1)=G(1) F2S04054
CALL EL01 F2S04055
CUNS=5*EL*ACEL*AREA F2S04056
CACE=IDUG(1)*PD(1)+DUG(2)*PN(2)+DUG(3)*PD(3)+CUNS*EL/6. F2S04057
P(7)=P(7)+CACE*PN(1) F2S04058
P(8)=-P(7) F2S04059
P(9)=P(9)+CACE*PN(2) F2S04060
P(10)=-P(9) F2S04061
P(11)=P(11)+CACE*PN(3) F2S04062
P(12)=-P(11) F2S04063
IPRG=1 F2S04064
IPEN=3 F2S04065
90 CALL BEAM F2S04066
I1=5 F2S04067
JR=11 F2S04068
JR=3 F2S04069
NY=2 F2S04070
CALL RLDC F2S04071
J1=5 F2S04072
J1=11 F2S04073
J1=1 F2S04074
CALL RLDC F2S04075
I1=3 F2S04076
IR=3 F2S04077
CALL RLDC F2S04078
I1=1 F2S04079
J1=1 F2S04080
I1=1 F2S04081
JR=1 F2S04082
NY=4 F2S04083
CALL RLDC F2S04084
CALL PLHF F2S04085
IR=5 F2S04086
JR=5 F2S04087
NY=6 F2S04088
CALL RLDC F2S04089
IF IDG1 170,125,120 F2S04090
120 UVG(9)=5*DDG*AL1*EL F2S04091
UVG(10)=UVG(9) F2S04092
125 IF (DGY) 200,210,200 F2S04093
200 UVG(11)=5*DDGY*AL1*EL F2S04094
HVG(12)=UVG(11) F2S04095
210 CALL TRM (HVG,0) F2S04096
DO 300 I=1,IDS F2S04097
300 UV(I)=UV(I)+HVG(I) F2S04098
310 CALL STRA F2S04099
1000 RETURN F2S04100
END F2S04101

```

Table VII-31. Source program listing of subroutine S05 (Link 2)

```

* LABEL
CE2S05 SUBROUTINE S05 F2S05000
C GENERATES FOR ELEMENT TYPE 5 STIFFNESS AND LOAD MATRICES F2S05001
DIMENSION IA(1),AA(1),S(1),N(8),D21(21),D33(3,3),E22(3,3) F2S05002
1,PI(24),UV(24),X(8),Y(8),Z(8),XD(7),YD(7),ZD(7),G(11) F2S05003
COMMON IA,AA F2S05004
EQUIVALENCE(IA,AA),(D21,D33),(D21(10),E22),(D21(19),E1),(D21(20),G) F2S05005
EQUIVALENCE(IA(1),IN),(IA(2),IBN),(IA(3),IT),(IA(4),IP),(IA(5), F2S05006
1IPRS),(IA(6),ITYPE),(IA(7),IMAT),(IA(8),IDEG),(IA(9),IMX),(IA(10), F2S05008
2IH),(IA(11),IB),(IA(12),IMMX),(IA(13),IMMY),(IA(14),IMW),(IA(15), F2S05009
3IMFI),(IA(16),IARE),(IA(17),N(1)),(IA(25),M),(IA(26),ITY),(IA(27), F2S05010
4ISTR),(IA(28),ITELT),(IA(29),ITEM),(IA(30),ITIC),(IA(31),IMET), F2S05011
5IA(32),ISUM),(IA(33),IND),(IA(34),IMS),(IA(36),IDS),(IA(37), F2S05012
6IORD),(IA(38),IORDI),(IA(39),ACEL),(IA(50),JI),(IA(51),J2), F2S05013
7IA(52),J3),(IA(53),J4),(IA(54),J5),(IA(55),J6),(IA(56),J7),(IA(57), F2S05014
8I,J),(IA(58),JY),(IA(59),IBN),(IA(60),IBO),(IA(61),IIO),(IA(62), F2S05015
9IA(63),IDT),(IA(64),IDY),(IA(65),ITE),(IA(67),ITAP) F2S05016
EQUIVALENCE(IA(66),ICAR),(IA(67),ICIX),(IA(68),ICIV),(IA(69), F2S05017
1ICIZ),(IA(70),ICFI),(IA(71),IXX),(IA(72),IYY),(IA(73),ITZ), F2S05018
2IA(74),IC),(IA(75),IDEF),(IA(76),IST),(IA(77),IIS) F2S05019
3,(IA(78),IGEM),(IA(79),IFRR),(IA(80),TE),(IA(81),DT),(IA(82),DG), F2S05020
4(AA(83),AL1),(AA(84),AL2),(AA(85),AL3),(AA(86),O21),(AA(87),P), F2S05021
5(AA(131),UV),(AA(135),X),(AA(136),Y),(AA(171),Z),(AA(179),XD), F2S05022
6(AA(186),YD),(AA(193),ZD),(AA(351),S),(AA(40),ZGEM) F2S05023
7,(AA(42),IMP),(AA(43),IPRG),(AA(44),IPEN),(AA(45),CONS),(AA(46),IIE F2S05024
8),(AA(47),H1),(AA(48),G2),(AA(49),G3) F2S05025
EQUIVALENCE(IA(349),NTIC),(IA(348),ISDT),(IA(347),ISDY),(IA(346) F2S05026
1,ISDZ),(IA(345),J9),(IA(344),J10),(IA(343),JPRS),(IA(342),JSDY) F2S05027
2,(IA(341),JSDZ),(IA(340),JARE),(IA(339),JMMX),(IA(338),JMMY) F2S05028
3,(IA(337),JMMZ),(IA(336),JMF1),(IA(335),ITAS),(IA(334),IDZ) F2S05029
4,(IA(333),IPR),(IA(332),DGY),(AA(331),OC2),(AA(330),PRES) F2S05030
5,(IA(329),IPR1),(AA(324),PRCO) F2S05031
DIMENSION A(6,6),DIR(3,3),UVG(12),T(6),PN(3),PN(3),DUG(3) F2S05032
EQUIVALENCE(AA(200),A),(AA(236),EL),(AA(237),AREA),(AA(238),I) F2S05033
1,(AA(239),J3),(AA(240),IR),(AA(241),JR),(AA(242),NY),(AA(264),DIR) F2S05034
2,(AA(306),UVG),(AA(291),PD),(AA(294),PN),(AA(297),DUG),(AA(300),T) F2S05035
CALL CDDI F2S05036
IPBG=0 F2S05037
IF(IPRS) 40,60,85 F2S05038
60 IF (J1T) 71,71,85 F2S05039
71 KAV=NAV F2S05040
GO TO 180,80,851,KAV F2S05041
80 P(11)=5*PRES*YD(1)/CFE F2S05042
P(2)=P(11) F2S05043
P(4)=-5*PRES*XO(1)/CFE F2S05044
P(5)=P(4) F2S05045
85 IF (ACEL) 90,9,90 F2S05046
90 CONS=TE*A2*ACFL/6. F2S05047
IPBG=1 F2S05048
IPEN=2 F2S05049
PRCO=0 F2S05050
9 IERR=1 F2S05051
GO TO 9 F2S05052
END F2S05053

```

Table VII-32. Source program listing of subroutine S07 (Link 2)

```

* LAREL
CE2S07
SUBROUTINE S07
GENERATES FOR ELEMENT TYPE 7 STIFFNESS AND LOAD MATRICES
DIMENSION I(4),AA(1),S(1),N(8),D2(21),D3(3),F22(3,3)
1,P(24),UV(24),X(8),Y(8),XD(7),YD(7),ZD(7),G(1)
COMMON IA,AA
EQUIVALENCE (IA,AA), (D2,D33), (D2(10),F22), (D2(19),E1), (D2(20),G)
EQUIVALENCE (IA(1),IN), (IA(2),IBN), (IA(3),IT), (IA(4),IP), (IA(5),
1)PRS), (IA(6),ITYPE), (IA(7),IMAT), (IA(8),IDEG), (IA(9),INX), (IA(10),
2)H), (IA(11),IB), (IA(12),IMX), (IA(13),IMY), (IA(14),IMZ), (IA(15),
3)MFI), (IA(16),IARE), (IA(17),N(1)), (IA(25),M), (IA(26),JTY), (IA(27),
4)STR), (IA(28),IELT), (IA(29),ITEM), (IA(30),ITIG), (IA(31),IMEF),
5)IA(32),ISUM), (IA(33),IND), (IA(34),IMS), (IA(36),IDS), (IA(37),
6)ORD), (IA(38),IORD1), (IA(39),ACEL), (IA(50),J1), (IA(51),J2),
7)IA(52),J3), (IA(53),J4), (IA(54),J5), (IA(55),J6), (IA(56),J7), (IA(57),
8)J8), (IA(58),JTY), (IA(59),IBB), (IA(60),IBO), (IA(61),ID), (IA(62),
9)IA), (IA(63),IDT), (IA(64),IOY), (IA(65),ITE), (IA(6),ITAP)
EQUIVALENCE (IA(66),ICAR), (IA(67),ICIX), (IA(68),ICIV), (IA(69),
1)ICIZ), (IA(70),ICF), (IA(71),ICX), (IA(72),IY), (IA(73),IZZ),
2)IA(74),ITC), (IA(75),IDEF), (IA(76),IST), (IA(77),IIS)
3), (IA(78),IGEM), (IA(79),IERR), (IA(80),TE), (IA(81),DT), (IA(82),DC),
4)AA(83),AL1), (AA(84),AL2), (AA(85),AL3), (AA(86),D21), (AA(87),P),
5)AA(131),UV), (AA(155),X), (AA(163),Y), (AA(171),Z), (AA(179),XD),
6)AA(186),YD), (AA(193),ZD), (AA(251),S), (AA(40),ZGEM)
7), (AA(42),INP), (AA(43),IPRG), (AA(44),IPEN), (AA(45),CONS), (AA(46),JHE
8), (AA(47),G1), (AA(48),G2), (AA(49),G3)
EQUIVALENCE (IA(349),NTIC), (IA(348),ISOT), (IA(347),ISDY), (IA(346),
1)ISDZ), (IA(345),J9), (IA(344),J10), (IA(343),JPRS), (IA(342),JSDY)
2), (IA(341),JSDZ), (IA(340),JARE), (IA(339),JMMX), (IA(338),JMMY)
3), (IA(337),JMMZ), (IA(336),JMF1), (IA(335),ITAS), (IA(334),IDZ)
4), (IA(333),IPR), (AA(332),RGY), (AA(331),OGZ), (AA(327),CFE)
5), (IA(329),IPR1), (AA(324),PRC0)
DIMENSION EM(4,4),EM(4,4),EM(4,4),EM(4,4),EM(4,4),EM(4,4),EM(4,4),EM(4,4)
1)EM(4,4),EM(4,4),EM(4,4),EM(4,4),EM(4,4),EM(4,4),EM(4,4),EM(4,4)
C
1)EM(4,4),EM(4,4),EM(4,4),EM(4,4),EM(4,4),EM(4,4),EM(4,4),EM(4,4)
A2=XD(1)+YD(2)-XD(2)+YD(1)
IF (A2) 1,1,4
41 CALL TRM
F1=TE*(2,=A2)
CALL TRM (E2,E0,0,7,3)
IF (D(2,1)) 431,431,435
431 IF (D(3,1)) 432,432,436
432 IF (D(3,2)) 433,433,437
433 O(3,1)+O(3,1)+O(2,1)/2.
O(3,2)+O(3,2)+O(2,2)/2.
GO TO 438
436 O(2,1)+O(2,1)+O(3,1)/2.
O(3,2)+O(3,2)+O(3,1)/2.
O(3,1)+O(3,1)
GO TO 438
437 O(2,1)+O(2,1)+O(3,2)/2.
O(3,1)+O(3,1)+O(3,2)/2.
O(3,2)+O(3,2)
O(1,1)+O(2,1)-O(3,1)
O(1,2)+O(2,2)-O(3,2)
O(2,3)+O(3,3)
O(1,3)+O(3,1)
O(2,3)+O(3,2)
O(1,3)+O(3,1)-O(1,2)-O(2,3)
433 CALL ADM (S,IDS,0,3,1,1,F1)
DO 4022 I=1,3
IF (L-2) 4019,4018,4019
4018 DO 4021 I1=4,9
DO 4021 J1=1,3
ISS=(J1-J1)*IDS+I1
ISR=(I1-I1)*IDS+J1
4021 S(I1R)=ISS
4019 DO 4010 I=1,3
I1=I-[I/3]*3+1
I2=I-[I/3]*3+1
K=3-[I-1]*1+1
ISS=(K-I)*IDS
ISS1=ISS+I
ISS2=ISS+I1
ISS3=ISS+I2
CY=(X(I1)-X(I1))*S(ISS2)
DY=(X(I2)-X(I1))*S(ISS3)
CX=(Y(I1)-Y(I1))*S(ISS2)
DX=(Y(I2)-Y(I1))*S(ISS3)
S(ISS1+3)=CX*DX/2.
S(ISS2+3)=CX*DY/2.
S(ISS3+3)=DX*DY/2.
S(ISS1+6)=(CY+DY)/2.
S(ISS2+6)=CY/2.
S(ISS3+6)=DY/2.
4010 CONTINUE
CALL TRM (D33,EM,0,3,3)
F2=F1*TE*TE/12.
CALL ADM (S,IDS,0,3,7,7,F2)
CALL TRM (D33,EM,0,3,3)
CALL ADM (S,IDS,0,3,4,4,F2)
CALL TRM (D33,EM,EM,3,-3)
F2=F2
CALL ADM (S,IDS,EM,3,7,4,F2)
492 PRC0=0.
IPB=3
IPEN=3
CONS=A2*ACEL*TE/6.
CCNT=PRES*A2 /6.
P(1)=CCNT
P(2)=CCNT
P(3)=CCNT
C COMPUTE THERMAL DEFORMATION VECTOR
451 F1=DG*AL1
F2=DG*AL2
DO 455 I=1,3
I1=IMS+I
I2=IMS+I1
UV(I)=0.
UV(I2)=F1*X(I)
UV(I1)=F2*Y(I)
9 REURN
1 IRR=1
GO TO 9
END

```

Table VII-33. Source program listing of subroutine S09 (Link 2)

```

* LAREL
CE2S09
SUBROUTINE S09
GENERATES FOR ELEMENT TYPE 9 STIFFNESS AND LOAD MATRICES
DIMENSION I(4),AA(1),S(1),N(8),D2(21),D3(3),F22(3,3)
1,P(24),UV(24),X(8),Y(8),XD(7),YD(7),ZD(7),G(1)
COMMON IA,AA
EQUIVALENCE (IA,AA), (D2,D33), (D2(10),F22), (D2(19),E1), (D2(20),G)
EQUIVALENCE (IA(1),IN), (IA(2),IBN), (IA(3),IT), (IA(4),IP), (IA(5),
1)PRS), (IA(6),ITYPE), (IA(7),IMAT), (IA(8),IDEG), (IA(9),INX), (IA(10),
2)H), (IA(11),IB), (IA(12),IMX), (IA(13),IMY), (IA(14),IMZ), (IA(15),
3)MFI), (IA(16),IARE), (IA(17),N(1)), (IA(25),M), (IA(26),JTY), (IA(27),
4)STR), (IA(28),IELT), (IA(29),ITEM), (IA(30),ITIG), (IA(31),IMEF),
5)IA(32),ISUM), (IA(33),IND), (IA(34),IMS), (IA(36),IDS), (IA(37),
6)ORD), (IA(38),IORD1), (IA(39),ACEL), (IA(50),J1), (IA(51),J2),
7)IA(52),J3), (IA(53),J4), (IA(54),J5), (IA(55),J6), (IA(56),J7), (IA(57),
8)J8), (IA(58),JTY), (IA(59),IBB), (IA(60),IBO), (IA(61),ID), (IA(62),
9)IA), (IA(63),IDT), (IA(64),IOY), (IA(65),ITE), (IA(6),ITAP)
EQUIVALENCE (IA(66),ICAR), (IA(67),ICIX), (IA(68),ICIV), (IA(69),
1)ICIZ), (IA(70),ICF), (IA(71),ICX), (IA(72),IY), (IA(73),IZZ),
2)IA(74),ITC), (IA(75),IDEF), (IA(76),IST), (IA(77),IIS)
3), (IA(78),IGEM), (IA(79),IERR), (AA(80),TE), (AA(81),DT), (AA(82),DC),
4)AA(83),AL1), (AA(84),AL2), (AA(85),AL3), (AA(86),D21), (AA(87),P),
5)AA(131),UV), (AA(155),X), (AA(163),Y), (AA(171),Z), (AA(179),XD),
6)AA(186),YD), (AA(193),ZD), (AA(251),S), (AA(40),ZGEM)
7), (AA(42),INP), (AA(43),IPRG), (AA(44),IPEN), (AA(45),CONS), (AA(46),JHE
8), (AA(47),G1), (AA(48),G2), (AA(49),G3)
EQUIVALENCE (IA(349),NTIC), (IA(348),ISOT), (IA(347),ISDY), (IA(346),
1)ISDZ), (IA(345),J9), (IA(344),J10), (IA(343),JPRS), (IA(342),JSDY)
2), (IA(341),JSDZ), (IA(340),JARE), (IA(339),JMMX), (IA(338),JMMY)
3), (IA(337),JMMZ), (IA(336),JMF1), (IA(335),ITAS), (IA(334),IDZ)
4), (IA(333),IPR), (AA(332),RGY), (AA(331),OGZ), (AA(327),CFE)
5), (IA(329),IPR1), (AA(324),PRC0)
DIMENSION AT(4,4),B(3,3),O(4,4),MOD(20),PD(3)
EQUIVALENCE (IA(200),AT), (AA(201),B), (AA(225),O), (AA(241),DET), (AA(259),P3)
1)MOD), (AA(324),PRC0), (AA(325),ITTT), (AA(291),PD)
DET=XD(1)+YD(2)+ZD(3)+XD(2)+YD(3)+XD(3)+ZD(3)+XD(3)+ZD(3)+XD(3)+ZD(3)
1)+ZD(1)+X(2)+Y(3)+Z(3)+X(3)+Y(2)+Z(2)
IF (DET) 301,1010,720
720 VOL=L*(1/6.*DET)
AT(1,1)=X*(YD(2)-YD(1))+ZD(3)-ZD(1))-YD(3)-YD(1))*ZD(2)-ZD(1))
AT(1,2)=(-YD(2)+ZD(3)+YD(3)+ZD(2))
AT(1,3)=YD(1)+ZD(3)-YD(3)+ZD(1))
AT(1,4)=(-YD(1)+ZD(2)+YD(2)+ZD(1))
AT(2,1)=(-XD(2)-XD(1))+ZD(3)-ZD(1))+XD(3)-XD(1))+ZD(2)-ZD(1))
AT(2,2)=(-XD(1)+ZD(3)-XD(3)+ZD(2))
AT(2,3)=XD(1)+ZD(3)+XD(3)+ZD(1))
AT(2,4)=(-XD(1)+ZD(2)-XD(2)+ZD(1))
AT(3,1)=(-XD(2)-XD(1))+YD(3)-YD(1))-XD(3)-XD(1))+YD(2)-YD(1))
AT(3,2)=(-XD(2)+YD(3)+XD(3)+YD(2))
AT(3,3)=XD(1)+YD(3)-XD(3)+YD(1))
AT(3,4)=(-XD(1)+YD(2)+XD(2)+YD(1))
IPB=0
IF (JPRS) 725,735,725
725 IF (ITTT)=1+(ITTT-2) 735,726,735
726 KAV=NAV
GO TO I728,728,735,KAV
PD(1)=YD(1)+ZD(2)-YD(2)+ZD(1)
PD(2)=XD(1)+ZD(2)+XD(2)+ZD(1)
PD(3)=XD(1)+YD(2)-XD(2)+YD(1)
PRC0=PRES*(6.*CFE)
IF (NAV-2) 729,731,735
731 DO 737 I=1,3
I1=I-4
DO 736 J=1,3
I1=I+4
GO TO I732,733,733,I
732 P(I)=PRC0*PD(I)/2.
GO TO 736
733 P(1)=PRC0*PD(1)/4.
736 CONTINUE
737 DO 730 I=1,3
I4=4*I
730 P(I)=PRC0*PD(I)
IPB=3
IPEN=3
735 IF (ACFL) 738,740,738
738 CONS=DE*ACFL/24.
IPB=3
IPEN=3
740 TX=0.
DO 745 I=1,3
745 TX=XD(1)+XD(1)+YD(1)+YD(1)+ZD(1)+ZD(1)
TX=TX*TX*3
IF (DET-TX) 747,747,750
747 WRITE OUTPUT TAPE 6,1,M,ITTT,DET
1)FORMAT(22H0TIF VOLUME OF ELEMENT,214,12MIS TOO SMALL,E12,4,13H DISE
1)REGARDH.
GO TO 1000
750 DO 780 I=1,3
DO 780 J=1,3
GO TO I752,754,755,J
752 GO TO I752,754,755,J
753 R(1,1)=O2(1)
R(1,2)=O2(4)
R(1,3)=O2(16)
R(2,1)=O2(16)
R(2,2)=O2(118)
R(3,1)=O2(12)
R(3,2)=O2(11)
R(3,3)=O2(120)
GO TO 739
734 B(1,1)=O2(4)
B(1,2)=O2(2)
B(1,3)=O2(15)
B(2,1)=O2(16)
B(2,2)=O2(19)
B(2,3)=O2(110)
B(3,1)=O2(118)
B(3,2)=O2(11)
B(3,3)=O2(120)
GO TO 735
735 R(1,1)=O2(16)
R(1,2)=O2(15)
R(1,3)=O2(13)

```

Table VII-33 (contd)

```

B(2,1)= D21(1R)
B(2,2)= D21(17)
B(2,3)= D21(13)
B(3,1)= D21(21)
B(3,2)= D21(20)
B(3,3)= D21(15)
GD TO 775
/56 GD TO (1000,757,758)J
/57 B(1,1)= D21(16)
      B(1,2)= D21(9)
      B(1,3)= D21(17)
      B(2,2)= D21(7)
      B(2,3)= D21(10)
      B(3,3)= D21(19)
      GD TO 739
/58 B(1,1)= D21(18)
      B(1,2)= D21(17)
      B(1,3)= D21(13)
      B(2,1)= D21(11)
      B(2,2)= D21(110)
      B(2,3)= D21(18)
      B(3,1)= D21(20)
      B(3,2)= D21(19)
      B(3,3)= D21(114)
      GD TO 775
/59 B(1,1)= D21(21)
      B(1,2)= D21(20)
      B(1,3)= D21(115)
      B(2,2)= D21(19)
      B(2,3)= D21(124)
      B(3,3)= D21(12)
/59 B(2,1)=B(1,2)
      B(3,1)=B(1,3)
      B(3,2)=B(2,3)
/75 CALL TRN (B,AT,0,3,4)
      IR=0-1-3
      JC=4-7-3
      CALL ADMS,IDS,0,4,IR,JC,VOL1
/80 CONTINUE
1000 RETURN
1010 IERR=1
      GO TO 1000
      END

```

```

F2509114
F2509115
F2509116
F2509117
F2509118
F2509119
F2509120
F2509121
F2509122
F2509123
F2509124
F2509125
F2509126
F2509127
F2509128
F2509129
F2509130
F2509131
F2509132
F2509133
F2509134
F2509135
F2509136
F2509137
F2509138
F2509139
F2509140
F2509141
F2509142
F2509143
F2509144
F2509145
F2509146
F2509147
F2509148
F2509149
F2509150
F2509151
F2509152
F2509153
F2509154
F2509155
F2509156

```

Table VII-34. Source program listing of subroutine S11 (Link 2)

```

* LABEL
CE2S11
SUBROUTINE S11
GENERATES FOR ELEMENT TYPE 11 STIFFNESS AND LOAD MATRICES
DIMENSION IA(1),AA(1),S(1),N(8),D21(21),D33(3,3),E22(3,3)
1,P(24),UV(24),X(8),Y(8),Z(8),XD(7),YD(7),ZD(7),GL(1)
COMMON IA,AA
EQUIVALENCE (IA,AA), (D21,D33), (D21(10),E22), (D21(19),E), (D21(20),G)E2511000
EQUIVALENCE (IA(1),IN), (IA(2),IN), (IA(3),IP), (IA(4),IP), (IA(5),E2511001
1IPRS), (IA(6),ITYPE), (IA(7),IMAT), (IA(8),IDEG), (IA(9),IMX), (IA(10),E2511002
2IH), (IA(11),IR), (IA(12),IMX), (IA(13),IMY), (IA(14),IMZ), (IA(15),E2511003
3IMF), (IA(16),IARE), (IA(17),NI), (IA(25),M), (IA(26),ITY), (IA(27),E2511004
4ISTR), (IA(28),IELT), (IA(29),ITEM), (IA(30),ITIC), (IA(31),IMET), F2511011
5(IA(32),ISUM), (IA(33),INQ), (IA(34),IMS), (IA(36),IDS), (IA(37),E2511012
6IRRD), (IA(38),IRPD), (IA(39),ACEL), (IA(50),J1), (IA(51),J2), F2511013
7(IA(52),J3), (IA(53),J4), (IA(54),J5), (IA(55),J6), (IA(56),J7), (IA(57),E2511014
8), (IA(58),JTY), (IA(59),IRB), (IA(60),IRU), (IA(61),IRD), (IA(62),E2511015
9(IA), (IA(63),IDT), (IA(64),IDY), (IA(65),ITE), (IA(61),ITAP) E2511016
EQUIVALENCE (IA(66),ICAR), (IA(67),ICIX), (IA(68),ICLY), (IA(69),E2511017
1ICIZ), (IA(70),ICFI), (IA(71),ICX), (IA(72),ICY), (IA(73),ICZ), E2511018
2(IA(74),IDEF), (IA(76),IST), (IA(77),IIS) E2511019
3(IA(78),IGEM), (IA(79),IERR), (AA(80),TE), (AA(81),DT), (AA(82),DG), F2511020
4(AA(83),AL1), (AA(84),AL2), (AA(85),AL3), (AA(86),D21), (AA(107),P), E2511021
5(AA(131),UV), (AA(155),X), (AA(163),Y), (AA(171),Z), (AA(179),XD), E2511022
6(AA(186),YD), (AA(193),ZD), (AA(351),S), (AA(40),ZGEM) E2511023
7( (AA(42),INP), (AA(43),IPRG), (AA(44),IPEN), (AA(45),CONS), (AA(46),IUE2511024
8), (AA(47),G1), (AA(48),G2), (AA(49),G3) E2511025
EQUIVALENCE (IA(349),NTIC), (IA(348),ISDT), (IA(347),ISDY), (IA(346),E2511026
1,ISDZ), (IA(345),J9), (IA(344),J10), (IA(343),JPRS), (IA(342),JSDY), E2511027
2(IA(341),JSDZ), (IA(340),JARE), (IA(339),JMX), (IA(338),JMY), E2511028
3(IA(337),JMMZ), (IA(336),JMF1), (IA(335),ITAS), (IA(334),IDZ), E2511029
4(IA(333),IPR), (AA(332),DRY), (AA(331),DG2), (AA(330),PRE5) E2511030
5(IA(329),IPR) E2511031
DIMENSION EM(4,4),FN(4,4),O(4,4),DIR(3,3),DUM(8) E2511032
EQUIVALENCE (AA(200),EM), (AA(216),DUM), (AA(232),E0), (AA(248),O), E2511033
1( (AA(264),DIR), (AA(276),DUM), (AA(297),A2) E2511034
C
TRIANGULAR SHELL ELEMENT
CALL CORT
CALL S07
ISHF=6+IDS+1
IESS=9+IDS
DO 1 I=1,9
IESS=IESS-IDS
IE5=IESS
DO 2 J=1,9
IF5=IE5+1
IYE=IE5+ISHF
S(IYE)=S(IIE5)
2 CONTINUE
DO 3 I=4,9
UV(I+6)=UV(I)
DO 4 I=1,IMS
II=IMS+I
I2=IMS+11
UV(I)=X11*UDT*AL1
UV(I1)=Y11*UDT*AL2
4 CONTINUE
CALL S05
IPEN=3
DO 11 I=1,3
P(I+6)=P(I)
P(I)=0
11 CONTINUE
C
TRANSFORM 5,P,UV INTO OVERALL SYSTEM
CALL TRAN (P,O)
CALL TRAN (UV,O)
CALL STRA
RETURN
END
E2511000
E2511001
E2511002
E2511003
E2511004
E2511005
E2511006
E2511007
E2511008
E2511009
E2511010
E2511011
E2511012
E2511013
E2511014
E2511015
E2511016
E2511017
E2511018
E2511019
E2511020
E2511021
E2511022
E2511023
E2511024
E2511025
E2511026
E2511027
E2511028
E2511029
E2511030
E2511031
E2511032
E2511033
E2511034
E2511035
E2511036
E2511037
E2511038
E2511039
E2511040
E2511041
E2511042
E2511043
E2511044
E2511045
E2511046
E2511047
E2511048
E2511049
E2511050
E2511051
E2511052
E2511053
E2511054
E2511055
E2511056
E2511057
E2511058
E2511059
E2511060
E2511061
E2511062
E2511063
E2511064
E2511065
E2511066
E2511067

```

Table VII-35. Source program listing of subroutine S13 (Link 2)

```

* LABEL
CE2S13
SUBROUTINE S13
GENERATES FOR ELEMENT TYPE 13 STIFFNESS AND LOAD MATRICES
DIMENSION IA(1),AA(1),S(1),N(8),D21(21),D33(3,3),E22(3,3)
1,P(24),UV(24),X(8),Y(8),Z(8),XD(7),YD(7),ZD(7),GL(1)
COMMON IA,AA
EQUIVALENCE (IA,AA), (D21,D33), (D21(10),E22), (D21(19),E), (D21(20),G)E2513000
EQUIVALENCE (IA(1),IN), (IA(2),IN), (IA(3),IP), (IA(4),IP), (IA(5),E2513007
1IPRS), (IA(6),ITYPE), (IA(7),IMAT), (IA(8),IDEG), (IA(9),IMX), (IA(10),E2513008
2IH), (IA(11),IR), (IA(12),IMX), (IA(13),IMY), (IA(14),IMZ), (IA(15),E2513009
3IMF), (IA(16),IARE), (IA(17),NI), (IA(25),M), (IA(26),ITY), (IA(27),E2513010
4ISTR), (IA(28),IELT), (IA(29),ITEM), (IA(30),ITIC), (IA(31),IMET), F2513011
5(IA(32),ISUM), (IA(33),INQ), (IA(34),IMS), (IA(36),IDS), (IA(37),E2513012
6IRRD), (IA(38),IRPD), (IA(39),ACEL), (IA(50),J1), (IA(51),J2), F2513013
7(IA(52),J3), (IA(53),J4), (IA(54),J5), (IA(55),J6), (IA(56),J7), (IA(57),E2513014
8), (IA(58),JTY), (IA(59),IRB), (IA(60),IRU), (IA(61),IRD), (IA(62),E2513015
9(IA), (IA(63),IDT), (IA(64),IDY), (IA(65),ITE), (IA(61),ITAP) F2513016
EQUIVALENCE (IA(66),ICAR), (IA(67),ICIX), (IA(68),ICLY), (IA(69),E2513017
1ICIZ), (IA(70),ICFI), (IA(71),ICX), (IA(72),ICY), (IA(73),ICZ), E2513018
2(IA(74),IDEF), (IA(76),IST), (IA(77),IIS) E2513019
3(IA(78),IGEM), (IA(79),IERR), (AA(80),TE), (AA(81),DT), (AA(82),DG), F2513020
4(AA(83),AL1), (AA(84),AL2), (AA(85),AL3), (AA(86),D21), (AA(107),P), E2513021
5(AA(131),UV), (AA(155),X), (AA(163),Y), (AA(171),Z), (AA(179),XD), E2513022
6(AA(186),YD), (AA(193),ZD), (AA(351),S), (AA(40),ZGEM) E2513023

```

```

7( (AA(42),INP), (AA(43),IPRG), (AA(44),IPEN), (AA(45),CONS), (AA(46),IUE2513024
8), (AA(47),G1), (AA(48),G2), (AA(49),G3) E2513025
EQUIVALENCE (IA(349),NTIC), (IA(348),ISDT), (IA(347),ISDY), (IA(346),E2513026
1,ISDZ), (IA(345),J9), (IA(344),J10), (IA(343),JPRS), (IA(342),JSDY), E2513027
2(IA(341),JSDZ), (IA(340),JARE), (IA(339),JMX), (IA(338),JMY), E2513028
3(IA(337),JMMZ), (IA(336),JMF1), (IA(335),ITAS), (IA(334),IDZ), E2513029
4(IA(333),IPR), (AA(332),DRY), (AA(331),DG2), (AA(330),PRE5) E2513030
5(IA(329),IPR) E2513031
EQUIVALENCE (AA(291),A2), (AA(324),PRC0)) F2513032
CALL CORT
CALL S05
CNT=PRCS*42/6
P(B)=CNT
P(Y)=LUN
PRC=0
IPEN=3
IIGE=IGEM
IGEM=0
CALL TRAN (P,O)
CALL STRA
IGEM=IIGE
RETURN
END
E2513033
E2513034
E2513035
E2513036
E2513037
E2513038
E2513039
E2513040
E2513041
E2513042
E2513043
E2513044
E2513045
E2513046
E2513047

```


Table VII-36. Source program listing of subroutine S15 (Link 2)

```

* LABEL
CE2S15 SUBROUTINE S15 E2S15000 D23=0. F2S15095
GENERATES FOR ELEMENT TYPE 15 STIFFNESS AND LOAD MATRICES F2S15001 E23=YYY F2S15096
DIMENSION IAL1,AA(1),S(1),T(1),O21(21),D33(3,3),E22(3,3) F2S15002 GO TO 50 F2S15097
1,P(24),UV(24),X(8),Y(8),Z(8),XD(7),YD(7),ZD(7),G(1) F2S15003 22 IF (ABSF(X(M)*X(L)-ER1) 24,24,40 F2S15098
COMMON IA,AA F2S15004 24 IF (MM1 11,23,11 F2S15099
EQUIVALENCE (IA,AA), (D21,033), (D21(10),E22), (D21(19),E), (D21(20),G) F2S15005 23 MM=1 F2S15100
EQUIVALENCE (IA(1),IN), (IA(2),IBN), (IA(3),IT), (IA(4),IP), (IA(5), F2S15007 26 N=M+1 F2S15101
1)PRS), (IA(6),ITYPE), (IA(7),IMAT), (IA(8),IDEG), (IA(9),IMK), (IA(10), F2S15008 26 N=M+1 F2S15102
2)H), (IA(11),IB), (IA(12),IMKX), (IA(13),IMKY), (IA(14),IMZ), (IA(15), F2S15009 26 N=M+1 F2S15103
3)MF1), (IA(16),IARE), (IA(17),T(1)), (IA(25),O), (IA(26),IT), (IA(27), F2S15010 26 N=M+1 F2S15104
4)STR1, (IA(28),IELT), (IA(29),ITEM), (IA(30),ITIC), (IA(31),IMET), F2S15011 27 DD TD 29 F2S15105
5)IA(32),ISUM), (IA(33),IND), (IA(34),IMS), (IA(36),IOS), (IA(37), F2S15012 29 M=L F2S15107
6)URD), (IA(38),IDRO1), (IA(39),ACEL), (IA(50),J1), (IA(51),J2), F2S15013 29 K=N+1 F2S15108
7)IA(52),J3), (IA(53),J4), (IA(54),J5), (IA(55),J6), (IA(56),J7), (IA(57), F2S15014 29 K=N+1 F2S15109
8),JB), (IA(58),JTY), (IA(59),JBR), (IA(60),IBH), (IA(61),ID), (IA(62), F2S15015 31 K=1 F2S15110
9)IA(1), (IA(63),ID), (IA(64),IDY), (IA(65),ITF), (IA(66),ITPP) F2S15016 30 GG=LNDFIX(X)/X(IN) F2S15111
EQUIVALENCE (IA(66),ICAR), (IA(67),ICIX), (IA(68),ICIX), (IA(69), F2S15017 30 YR=M*(K-VIN) F2S15112
1)CJ2), (IA(70),ICF1), (IA(71),IXX), (IA(72),IYY), (IA(73),I77), F2S15018 30 Q33=(M*GG) F2S15113
2)IA(74),IIC), (IA(75),IDEF), (IA(76),IST), (IA(77),IIS) F2S15019 Q23=2.*V(IN)**2*GG+YKN*(2.*V(M)+V(N)+V(K)) F2S15114
3), (IA(78),IGEM), (IA(79),IERR), (AA(80),TE), (AA(81),OT), (AA(82),DG), F2S15020 Q22=6.*V(M)**2*GG+YKN*(2.*V(IN)**2+V(N)**2+V(K)**2) F2S15115
4)AA(83),AL1), (AA(84),AL2), (AA(85),AL3), (AA(86),D21), (AA(107),P), F2S15021 1 +6.*V(M)**2+1.*V(M)*V(N)+V(K)) F2S15116
5), (AA(131),UV), (AA(135),X), (AA(163),Y), (AA(171),Z), (AA(179),XD), F2S15022 GO TO 50 F2S15117
6)AA(186),YD), (AA(193),ZD), (AA(195),S), (AA(401),ZGEM) F2S15023 GG=LNDFIX(X)/X(L) F2S15118
7), (AA(421),IMP), (AA(43),IPR), (AA(44),IPN), (AA(45),CONSI), (AA(46),1UE2S15024 Q33=F*GG F2S15119
8), (AA(47),G1), (AA(48),G2), (AA(49),G3) F2S15025 Q23=YYY*3.*F+(X(L)*V(L)-X(M)*V(M))/XXX-2.*F**2*GG F2S15120
EQUIVALENCE (IA(349),NTIC), (IA(348),ISDT), (IA(347),ISDY), (IA(346), F2S15026 Q22=YYY*(1-V(M)**2+11.*X(L)**2-7.*X(L)*X(M)+2.*X(L)**2) F2S15121
1),ISDZ), (IA(345),J9), (IA(344),J10), (IA(343),JPRS), (IA(342),J50Y) F2S15027 -V(L)*V(M)**2+5.*X(L)**2+5.*X(M)**2-22.*X(L)*X(M))/XXX**2 F2S15122
2), (IA(341),J50Z), (IA(340),JARE), (IA(339),JMKX), (IA(338),JMKY) F2S15028 1 -V(L)*V(M)**2+5.*X(L)**2+5.*X(M)**2-22.*X(L)*X(M))/XXX**2 F2S15123
3), (IA(337),JMKZ), (IA(336),JMF1), (IA(335),IYAS), (IA(334),IDZ) F2S15029 Q(2,2)=Q(2,2)+Q27(1,9)*A21 F2S15124
4), (IA(333),IPR), (AA(332),DRY), (AA(331),DG2), (AA(330),PRES) F2S15030 Q(2,3)=Q(2,3)+Q27(1,2)*A21 F2S15125
5), (IA(329),IPR), (IA(328),NAV), (IA(327),GFF), (IA(325),ITTT) F2S15031 Q(3,3)=Q(3,3)+Q33(1,2)*A21 F2S15127
DIMENSION EM(4,4),EN(4,4),O(4,4),E(4,4),CAX(4),Z21(21),V(3) F2S15032 Q(3,3)=Q(3,3)+Q33(1,2)*A21 F2S15128
EQUIVALENCE (AA(200),EM), (AA(216),EN), (AA(232),E), (AA(248),O) F2S15033 11 CONTINUE F2S15129
1), (AA(291),A2), (AA(292),IAX), (AA(293),CAX), (AA(264),Z21) F2S15034 Q(L,1)=XBAR F2S15130
EQUIVALENCE (AA(297),XBAR), (AA(298),YBAR), (CAX,V) F2S15035 Q(L,2)=YBAR F2S15131
C SET RUNDOS FOR X SUB1 AND X SUB1, I+1 F2S15036 Q(1,3)=0 F2S15132
FRZ=0. F2S15037 Q(2,1)=Q(1,1) F2S15133
ER1=1.E-4 F2S15038 Q(3,1)=Q(1,1) F2S15134
XBAR=(X(1)+X(2)+X(3))/3. F2S15039 Q(3,2)=Q(2,3) F2S15135
TER=TE F2S15040 IAX=4 F2S15136
TB=XBAR F2S15041 102 CONTINUE F2S15137
DO 91 I=1,21 F2S15042 DO 2 J=1,3 F2S15138
Z21(I)=O21(I) F2S15043 DO 2 J=1,3 F2S15139
D33(1,1)=Z21(1) F2S15044 D33(1,1)+Z21(1)*Q(I,1) F2S15140
D33(1,2)=Z21(2) F2S15045 CALL TRM ID33,ED,Q,3,3 F2S15141
D33(1,3)=Z21(4) F2S15046 CAX(1)=0. F2S15142
D33(2,2)=Z21(7) F2S15047 CAX(2)=0. F2S15143
D33(2,3)=Z21(9) F2S15048 CAX(3)=0. F2S15144
D33(3,3)=Z21(16) F2S15049 CAX(IAX)=1. F2S15145
D33(2,1)=D33(1,2) F2S15050 Q(1,1)*IAX+Z71(1,2)*XBAR*(CAX(1)+N(3,1)+CAX(2)*EM(3,2)+CAX(3)* F2S15146
D33(3,1)=D33(1,3) F2S15051 1 EN(3,3)**2 F2S15147
D33(3,2)=D33(2,3) F2S15052 CALL ADM IS,IDS,Q,3,1,1,F1) F2S15148
CALL S05 F2S15053 CALL TRM IE22,EO,EN,3,-3) F2S15149
CALL TRM F2S15054 CALL ADM IS,IDS,EN,3,4,1,F1) F2S15150
YBAR=(Y(1)+Y(2)+Y(3))/3. F2S15055 CALL TRM IE22,EO,EN,3,-3) F2S15151
YBAR=0. F2S15056 GO 3 J=1,3 F2S15152
E22(1,3)=Z21(3) F2S15057 DO 3 J=1,3 F2S15153
E22(2,3)=Z21(8) F2S15058 EM(1,J)=EM(1,J)+EM(J,1) F2S15154
E22(3,3)=Z21(13) F2S15059 EM(2,1)=EM(1,2) F2S15155
UD 1 I=1,3 F2S15060 EM(3,1)=EM(1,3) F2S15156
E22(1,1)=XBAR*E22(1,3) F2S15061 CALL ADM IS,IDS,FM,3,1,1,F1) F2S15157
E22(1,2)=YBAR*E22(1,3) F2S15062 TER=TER+(X(1)-XBAR)*(Y(2)-YBAR)-(X(2)-XBAR)*Y(1)-YBAR)/I2.*A2) F2S15158
F1=1./I2.*A2) F2S15063 CONS=TE*AGLE*P/4. F2S15159
EQ(3,1)=X(2)*Y(3)-YBAR-X(3)*Y(2)-YBAR F2S15064 Q(1,1)=TER*(X(1)-XBAR)**2+(X(1)-XBAR)*X(2)-XBAR+(X(2)-XBAR)**2 F2S15160
EQ(3,2)=X(3)*Y(1)-YBAR-X(1)*Y(3)-YBAR F2S15065 CONS=TE*AGLE*P/4. F2S15161
EQ(3,3)=X(1)*Y(2)-YBAR-X(2)*Y(1)-YBAR F2S15066 1 *XBAR**2 F2S15162
C COMPUTE THE INTEGRATION CONSTANT F2S15067 Q(2,1)=TER*(Y(1)-YBAR)**2+(X(1)-XBAR)*Y(2)-YBAR+(Y(2)-YBAR)* F2S15163
DO 15 I=1,3 F2S15068 1 (X(1)-XBAR)**2+(X(1)-XBAR)*X(2)-XBAR+(X(2)-XBAR)**2 F2S15164
V(I)=Y(I)-YBAR F2S15069 Q(3,1)=XBAR F2S15165
DO 32 J=1,4 F2S15070 DO 4 I=1,3 F2S15166
DO 32 J=1,4 F2S15071 Q(I,2)=0. F2S15167
U(I,J)=0. F2S15072 DO 5 K=1,3 F2S15168
LL=0 F2S15073 DO 5 K=1,3 F2S15169
NN=0 F2S15074 Q(I,2)=Q(I,2)+EQ(I,K)*Q(K,1) F2S15170
DO 17 I=1,3 F2S15075 CONTINUE F2S15171
IF (X(1)) 120,20,121 F2S15076 DO 6 J=1,3 F2S15172
121 IF (X(1)-ER1) 20,20,51 F2S15077 P(I+3)=CONS*EQ(I,2) F2S15173
120 IERR=1 F2S15078 IF (ITTT-1) 71,71,85 F2S15174
RETURN F2S15079 IF (JPRS) 70,85,70 F2S15175
IAX=1 F2S15080 IF (ITTT-1) 71,71,85 F2S15176
GO TO 17 F2S15081 KAV=NAV F2S15177
20 NN=MM+1 F2S15082 GO TO (R0,80,85),KAV F2S15178
LL=1 F2S15083 CONS=M(1)/3.+X(2)/K.)=PRES/CFE F2S15179
1/ CONTINUE F2S15084 TER=(X(1)+Y(2)+X(2)/K.)=PRES/CFE F2S15180
IF (NN-1) 8.,8.,102 F2S15085 P(1)=P(1)+Y(1)*CONS F2S15181
8 MM=0 F2S15086 P(2)=P(2)+Y(1)*TER F2S15182
DO 11 L=1,3 F2S15087 P(4)=P(4)-X(1)*CONS F2S15183
IF (L=1) 81.,81.,82 F2S15088 P(5)=P(5)-X(1)*TER F2S15184
M=1 F2S15089 CONS=0. F2S15185
81 KXX=X(M)-X(L) F2S15090 IPRG=1 F2S15186
YYY=V(M)-V(L) F2S15091 DO 92 I=1,21 F2S15187
IF (ABSF(XXX/SDRTF(XXX*XXX*YYY*YYY))-EK2) 21,21,22 F2S15092 D21(I)=Z21(I) F2S15188
21 Q22=0. F2S15093 RETURN F2S15189
F2S15094 ENO F2S15190

```

Table VII-37. Source program listing of subroutine S17 (Link 2)

```

* LABEL
CE2S17
SUBROUTINE S17
GENERATES FOR ELEMENT TYPE 17 STIFFNESS AND LOAD MATRICES
DIMENSION I(11),AA(1),S(1),N(1),D2(2),D3(3),E22(3,3)
1 P(24),UV(24),X(8),Y(8),Z(8),XD(7),YD(7),ZD(7),G(1)
COMMON IA,AA
EQUIVALENCE (IA,AA),(D2,D3),(E22),(D21,D31),E,(D21,D31),G,E2S17006
EQUIVALENCE (IA(1),IN),(IA(2),IRN),(IA(3),IT),(IA(4),IP),(IA(5),  F2S17007
1)PRS),(IA(6),ITYPE),(IA(7),IMAT),(IA(8),IDEG),(IA(9),INX),(IA(10),F2S17008
2)H),(IA(11),IB),(IA(12),IMMX),(IA(13),IMMY),(IA(14),IMZ),(IA(15),E2S17009
3)MF),(IA(16),IARE),(IA(17),N(1)),(IA(25),R),(IA(26),ITY),(IA(27),E2S17010
4)STR),(IA(28),IFL1),(IA(29),ITEM),(IA(30),ITIC),(IA(31),IMEF), F2S17011
5)IA(32),ISUM),(IA(33),INDI),(IA(34),IMS),(IA(36),IDS),(IA(37), F2S17012
6)IRD),(IA(38),IRD1),(IA(39),ACEL),IA(50),J1,(IA(51),J2), F2S17013
7)IA(52),J3),(IA(53),J4),(IA(54),J5),(IA(55),J6),(IA(56),J7),(IA(57),F2S17014
8),J8),(IA(58),JTY),(IA(59),IBB),(IA(60),IBO),(IA(61),ID),(IA(62),E2S17015
9)IA),(IA(63),IDI),(IA(64),IDY),(IA(65),ITE),(IA(61),ITAP) F2S17016
EQUIVALENCE (IA(66),ICAR),(IA(67),ICIX),(IA(68),ICIY),(IA(69), F2S17017
1)ICIZ),(IA(70),ICF1),(IA(71),ICX),(IA(72),ICY),(IA(73),ICZ), F2S17018
2)IA(74),ITC),(IA(75),IDEF),(IA(76),IST),(IA(77),IS) F2S17019
3),(IA(78),IGEM),(IA(79),IFRR),(IA(80),TE),(IA(81),DT),(AA(82),DG), F2S17020
4)AA(83),AL1),(AA(84),AL2),(AA(85),AL3),(AA(86),O2),(AA(107),P), F2S17021
5)AA(131),UV),(AA(155),X),(AA(163),Y),(AA(171),Z),(AA(179),XD), F2S17022
6)AA(186),YD),(AA(193),ZD),(AA(351),S),(AA(40),ZGEM) F2S17023
7),(AA(42),INP),(AA(43),IPBG),(AA(44),IPEN),(AA(45),CONSI),(AA(46),IUE2S17024
8),(AA(47),G1),(AA(48),G2),(AA(49),G3) F2S17025
EQUIVALENCE (IA(349),NTIC),(IA(348),ISD1),(IA(347),ISD1),(IA(346) F2S17026
1),ISD2),(IA(345),J9),(IA(344),J10),(IA(343),JPKS),(IA(342),JSOY) F2S17027
2),(IA(341),JSD2),(IA(340),JARE),(IA(339),JMMX),(IA(338),JMMY) F2S17028
3),(IA(337),JMMZ),(IA(336),JMF1),(IA(335),ITAS),(IA(334),IDZ) F2S17029
4),(IA(333),IPR),(AA(332),DGY),(AA(331),DGZ),(AA(330),PRES) F2S17030
5),(IA(329),IPR) F2S17031
DIMENS ION EM(4,4),EN(4,4),O(4,4),EO(4,4) F2S17032
EQUIVALENCE (AA(200),EM),(AA(216),EN),(AA(232),EO),(AA(248),O), F2S17033
1)AA(264),F1),(AA(265),F2),(AA(266),RBY),(AA(267),XAV) F2S17034
ER1=1-E
BODY=SORTF (XD(1)**2+YD(1)**2)
XAV=(X(1)+X(2))/2.
IF (BODY) 1,1,4
2 IF (XAV) 1,1,4
41 IF (X(1)) 1,4,4
42 IF (X(2)) 1,4,4
43 IF (X(2)) 1,4,4
44 AL=XD(1)/BODY
RE=YD(1)/BODY
GA=BODY/XAV
Q(1,1)=-AL
Q(1,2)=AL
Q(1,3)=-BE
Q(1,4)=GE
F1=TE*GA
CALL TRM (D33,Q,F,4)
CALL ADM (S,IDS,FU,4,1,1,F1)
F1=TE*O33(1,2)
Q(1,1)=-AL
Q(2,1)=-AL
Q(1,2)=O
Q(2,1)=O
CALL ADM (S,IDS,Q,2,1,1,F1)
Q(1,1)=-BE*F
Q(2,1)=O(1,1)
Q(1,2)=-O(1,1)
Q(2,2)=O(1,2)
CALL ADM (S,IDS,Q,2,1,3,F1)
IF (ABS(F1)-ER) 24,24,25
24 F1=TE*O33(2,2)*GA
Q(1,1)=O.3333333
Q(1,2)=O(1,1)/2.
Q(2,1)=O(1,2)
Q(2,2)=O(1,1)
GO TO 30
25 IF (X(1)**2) 26,23,26
23 F1=TE*O33(2,2)/2.*AL
IF (X(2)) 27,27,29
27 F1=F2
Q(1,1)=1.
Q(1,2)=-1.
Q(2,1)=-1.
Q(2,2)=1.
GO TO 30
26 GUL=LGF(X(2)/X(1))
AL=BOY*GUL/XD(1)
R1=1.-X(1)*GUL/XD(1)*BOY/XD(1)
C1=(XAV/XD(1))-2.*X(1)/XD(1)+(X(1)/XD(1))**2*GUL/BOY/XD(1)
F1=TE*O33(2,2)
Q(1,1)=A1+C1-2.*R1
Q(1,2)=B1-C1
Q(2,1)=O(1,2)
Q(2,2)=C1
30 CALL ADM (S,IDS,Q,2,1,1,F1)
IPRG=-1
F1=PRE*YD(1)+BOY*ACEL*TE*G1
F2=PRE*XD(1)+BOY*ACEL*TE*G2
AL=X(1)/3.+X(2)/6.
BE=X(1)/6.+X(2)/3.
P(1)=F1*AL
P(2)=F1*BE
P(3)=F2*AL
P(4)=F2*BE
9 RETURN
1 IERR=1
GO TO 9
END

```

Table VII-38. Source program listing of subroutine S18 (Link 2)

```

* LABEL
CE2S18
SUBROUTINE S18
GENERATES FOR ELEMENT TYPE 18 STIFFNESS AND LOAD MATRICES
DIMENSION I(11),AA(1),S(1),N(1),D2(2),D3(3),E22(3,3)
1 P(24),UV(24),X(8),Y(8),Z(8),XD(7),YD(7),ZD(7),G(1)
COMMON IA,AA
EQUIVALENCE (IA,AA),(D2,D3),(D21,D31),E,(D21,D31),G,E2S18006
EQUIVALENCE (IA(1),IN),(IA(2),IRN),(IA(3),IT),(IA(4),IP),(IA(5),  F2S18007
1)PRS),(IA(6),ITYPE),(IA(7),IMAT),(IA(8),IDEG),(IA(9),INX),(IA(10),F2S18008
2)H),(IA(11),IB),(IA(12),IMMX),(IA(13),IMMY),(IA(14),IMZ),(IA(15),F2S18009
3)MF),(IA(16),IARE),(IA(17),N(1)),(IA(25),R),(IA(26),ITY),(IA(27),E2S18010
4)STR),(IA(28),IFL1),(IA(29),ITEM),(IA(30),ITIC),(IA(31),IMEF), F2S18011
5)IA(32),ISUM),(IA(33),INDI),(IA(34),IMS),(IA(36),IDS),(IA(37), F2S18012
6)IRD),(IA(38),IRD1),(IA(39),ACEL),IA(50),J1,(IA(51),J2), F2S18013
7)IA(52),J3),(IA(53),J4),(IA(54),J5),(IA(55),J6),(IA(56),J7),(IA(57),F2S18014
8),J8),(IA(58),JTY),(IA(59),IBB),(IA(60),IBO),(IA(61),ID),(IA(62),E2S18015
9)IA),(IA(63),IDI),(IA(64),IDY),(IA(65),ITE),(IA(61),ITAP) F2S18016
EQUIVALENCE (IA(66),ICAR),(IA(67),ICIX),(IA(68),ICIY),(IA(69), F2S18017
1)ICIZ),(IA(70),ICF1),(IA(71),ICX),(IA(72),ICY),(IA(73),ICZ), F2S18018
2)IA(74),ITC),(IA(75),IDEF),(IA(76),IST),(IA(77),IS) F2S18019
3),(IA(78),IGEM),(IA(79),IFRR),(IA(80),TE),(IA(81),DT),(AA(82),DG), F2S18020
4)AA(83),AL1),(AA(84),AL2),(AA(85),AL3),(AA(86),O2),(AA(107),P), F2S18021
5)AA(131),UV),(AA(155),X),(AA(163),Y),(AA(171),Z),(AA(179),XD), F2S18022
6)AA(186),YD),(AA(193),ZD),(AA(351),S),(AA(40),ZGEM) F2S18023
7),(AA(42),INP),(AA(43),IPBG),(AA(44),IPEN),(AA(45),CONSI),(AA(46),IUE2S18024
8),(AA(47),G1),(AA(48),G2),(AA(49),G3) F2S18025
EQUIVALENCE (IA(349),NTIC),(IA(348),ISD1),(IA(347),ISD1),(IA(346) F2S18026
1),ISD2),(IA(345),J9),(IA(344),J10),(IA(343),JPKS),(IA(342),JSOY) F2S18027
2),(IA(341),JSD2),(IA(340),JARE),(IA(339),JMMX),(IA(338),JMMY) F2S18028
3),(IA(337),JMMZ),(IA(336),JMF1),(IA(335),ITAS),(IA(334),IDZ) F2S18029
4),(IA(333),IPR),(AA(332),DGY),(AA(331),DGZ),(AA(330),PRES) F2S18030
5),(IA(329),IPR) F2S18031
DIMENS ION EM(4,4),EN(4,4),O(4,4),EO(4,4) F2S18032
EQUIVALENCE (AA(200),EM),(AA(216),EN),(AA(232),EO),(AA(248),O), F2S18033
1)AA(264),F1),(AA(265),F2),(AA(266),RBY),(AA(267),XAV) F2S18034
CALL S17
F2=TE**3/12.
IF (X(1)) 26,25,26
26 IF (X(1)*X(2)) 28,27,28
27 F1=TE*O33(2,2)*XD(1)/2.*BOY
IF (X(2)) 27,27,29
27 F1=F2
GO TO 29
28 F1=F2*O33(2,2)*(XD(1)/BOY)**2
CALL ADM (S,IDS,Q,2,5,5,F1)
29 F1=TE*O33(1,1)*XAV/BOY
Q(1,1)=1.
Q(1,2)=-1.
Q(2,1)=1.
Q(2,2)=1.
CALL ADM (S,IDS,Q,2,5,5,F1)
Q(1,1)=1.
Q(2,1)=1.
Q(2,2)=1.
CALL ADM (S,IDS,Q,2,5,5,F1)
Q(1,1)=YD(1)
EM(1,2)=-YD(1)
EM(1,3)=-XD(1)
EM(1,4)=-XD(1)
CALL TRM (E22,EM,Q,1,4)
CALL ADM (S,IDS,Q,4,1,1,F1)
Q(1,1)=BOY**4/4.
Q(1,2)=O(1,1)
Q(2,1)=O(1,1)
Q(2,2)=O(1,1)
F1=FL*E22(1,1)
CALL ADM(S,IDS,Q,2,5,5,F1)
Q(1,1)=-BOY**2*YD(1)/2.
Q(1,2)=O(1,1)
Q(2,1)=O(1,1)
Q(2,2)=O(1,1)
CALL ADM (S,IDS,Q,2,1,5,F1)
Q(1,1)=BOY**2)*XD(1)/2.
Q(1,2)=O(1,1)
Q(2,1)=O(1,1)
Q(2,2)=O(1,1)
CALL ADM (S,IDS,Q,2,3,5,F1)
UV(5)=O.
IF(6)=DG*BOY*AL1
RETURN
END

```

Table VII-39. Source program listing of subroutine STFS (Link 2)

```

* LABEL
CE2STF
SUBROUTINE STFS (JFLT)
SELECTS PROPER SUBROUTINE FOR GENERATION OF ELEMENT MATRICES
IELT=IELT
GO TO (1,2,3,4,5,5,7,7,8,8,9,9,10,10,11,11,12,13), IELT
1 CALL S01
GO TO 100
2 CALL S02
GO TO 100
3 CALL S03
GO TO 100
4 CALL S04
GO TO 100
5 CALL S05
GO TO 100
7 CALL S07
GO TO 100
8 CALL S09
GO TO 100
9 CALL S11
GO TO 100
10 CALL S13
GO TO 100
11 CALL S15
GO TO 100
12 CALL S17
GO TO 100
13 CALL S18
GO TO 100
100 RETURN
END
F2STF000
F2STF001
F2STF002
F2STF003
F2STF004
F2STF005
F2STF006
F2STF007
F2STF008
F2STF009
F2STF010
F2STF011
F2STF012
F2STF013
F2STF014
F2STF015
F2STF016
F2STF017
F2STF018
F2STF019
F2STF020
F2STF021
F2STF022
F2STF023
F2STF024
F2STF025
F2STF026
F2STF027
F2STF028
F2STF029

```

Table VII-41. Source program listing of subroutine TICK (Link 2)

```

* FAP COUNT 25
TICK CBL TICK
TICK ENTRY TICK
TICK NZT ONCE
TICK TRA FIRST
TICK CAL 5
TICK SUB INITL
TICK ALS 18
TICK SLW* 1,4
TICK TRA 2,4
TICK FIRST STL ONCE
TICK CAL 5
TICK SLW INITL
TICK SLZ* 1,4
TICK TRA 2,4
TICK ONCE PZE
TICK INIIL PZE
TICK END
TICK000
TICK001
TICK002
TICK003
TICK004
TICK005
TICK006
TICK007
TICK008
TICK009
TICK010
TICK011
TICK012
TICK013
TICK014
TICK015
TICK016
TICK017
TICK018

```

Table VII-40. Source program listing of subroutine STRA (Link 2)

```

* LABEL
CE2STR
SUBROUTINE STRA
TRANSFORMS DESCRIPTION OF ELEMENT MATRICES FROM LOCAL TO OVERALL
DIMENSION IA(1),AA(1),S(1),N(8),D2(2),D3(3),P(2),P2(3),3
1,P(24),UV(24),X(8),Y(8),Z(8),XD(7),YD(7),ZD(7),G(1)
COMMON IA,AA
EQUIVALENCE (IA-AA), (D2-D3), (D2(1)-E221, D2(15)-E), (D2(20)-G)
EQUIVALENCE (IA(1),IM), (IA(2),IMN), (IA(3),IT), (IA(4),IP), (IA(5),
11PRS), (IA(6),ITYPE), (IA(7),IMAT), (IA(8),IDEG), (IA(9),INX), (IA(10),
2IH), (IA(11),IR), (IA(12),IMMX), (IA(13),IMMY), (IA(14),IMZ), (IA(15),
3IMP1), (IA(16),IARE), (IA(17),N(1)), (IA(25),M), (IA(26),ITY), (IA(27),
4ISTR), (IA(28),IELT), (IA(29),ITEM), (IA(30),ITIC), (IA(31),IMET),
5(IA(32),ISUM), (IA(33),IORD), (IA(34),IMS), (IA(36),IDS), (IA(37),
6IORD), (IA(38),IORD1), (IA(39),ACEL), (IA(50),J1), (IA(51),J2),
7(IA(52),J3), (IA(53),J4), (IA(54),J5), (IA(55),J6), (IA(56),J7), (IA(57),
8I,JB), (IA(58),JTY), (IA(59),IBR), (IA(60),IBD), (IA(61),IID), (IA(62),
9IIA), (IA(63),IDI), (IA(64),IOY), (IA(65),IFI), (IA(61),IIP)
EQUIVALENCE (IA(66),ICAR), (IA(67),ICIX), (IA(68),ICY), (IA(69),
11G12), (IA(70),ICF), (IA(71),IAX), (IA(72),IY), (IA(73),IZ),
2(IA(74),IIC), (IA(75),IDEP), (IA(76),IS), (IA(77),ISJ)
3(IA(78),IGEM), (IA(79),IERK), (IA(80),TE), (IA(81),OT), (AA(82),DC),
4(IA(83),ALI), (IA(84),ALZ), (AA(85),AL3), (AA(86),D21), (AA(107),P),
5(AA(131),UV), (AA(155),X), (AA(163),Y), (AA(171),Z), (AA(179),XD),
6(AA(186),YD), (AA(193),ZD), (AA(351),S), (AA(401),ZGEM)
7(IA(421),INP), (AA(431),IPBG), (AA(444),IPEN), (AA(451),GNNS), (AA(461),
8), (AA(471),G1), (AA(481),G2), (AA(491),G3)
EQUIVALENCE (IA(349),ATIC), (IA(348),ISDT), (IA(347),ISDY), (IA(346),
1,ISDZ), (IA(345),J9), (IA(344),J10), (IA(343),JPR5), (IA(342),JSDY)
2(IA(341),JSDZ), (IA(340),JARE), (IA(339),JMMX), (IA(338),JMMY)
3(IA(337),JMMZ), (IA(336),JMF), (IA(335),ITAS), (IA(334),IDY)
4(IA(333),IPR), (IA(332),IDY), (IA(331),IBZ), (IA(330),PRES)
5(IA(329),IPR)
J=105
DO 5 I=1,IDS
J=J+1
CALL TRAN (S,J)
CONTINUE
IARB=-IDS
IEBB=-IDS
DO 6 I=1,IDS
IABB=IARB+1
IAB=IARB
IEBB=IEBB+IDS
IHE=IFBB
DO 7 J=1,IOS
IAB=IAB+IOS
IHE=IHE+1
IF IAB=IHE 7,7,13
TEMP=S(IAB)
S(IAB)=S(IAB)
S(IAB)=TEMP
CONTINUE
CONTINUE
J=105
DO 8 I=1,IOS
J=J+IOS
CALL TRAN (S,J)
CONTINUE
RETURN
END
F2STR000
F2STR001
F2STR002
F2STR003
F2STR004
F2STR005
F2STR006
F2STR007
F2STR008
F2STR009
F2STR010
F2STR011
F2STR012
F2STR013
F2STR014
F2STR015
F2STR016
F2STR017
F2STR018
F2STR019
F2STR020
F2STR021
F2STR022
F2STR023
F2STR024
F2STR025
F2STR026
F2STR027
F2STR028
F2STR029
F2STR030
F2STR031
F2STR032
F2STR033
F2STR034
F2STR035
F2STR036
F2STR037
F2STR038
F2STR039
F2STR040
F2STR041
F2STR042
F2STR043
F2STR044
F2STR045
F2STR046
F2STR047
F2STR048
F2STR049
F2STR050
F2STR051
F2STR052
F2STR053
F2STR054
F2STR055
F2STR056
F2STR057
F2STR058
F2STR059

```

Table VII-42. Source program listing of subroutine TOPO (Link 2)

```

* LABEL
CEZTOP SUBROUTINE TOPO E270P000
PREPARES ELEMENT PROPERTIES E270P001
DIMENSION IA(1),AA(1),S(1),N(8),D21(21),D33(3,3),E27(3,3) E270P002
1,P(24),UV(24),X(8),Y(8),Z(8),XD(17),YD(17),ZD(17),G(11) E270P003
GUMMIN IA,AA E270P004
EQUIVALENCE (IA,AA),(D21,D33),(D21(10),E22),(D21(19),E),D21(20),G E270P005
EQUIVALENCE (IA(1),IN),(IA(2),IBN),(IA(3),IT),(IA(4),IP),(IA(5), E270P006
1IPRS),(IA(6),ITYPE),(IA(7),IMAT),(IA(8),IDEG),(IA(9),INX),(IA(10),E270P007
2IH),(IA(11),I8),(IA(12),IMX),(IA(13),IMY),(IA(14),IMZ),(IA(15),E270P009
3IMF),(IA(16),IARE),(IA(17),N(1)),(IA(25),M),(IA(26),ITY),(IA(27),E270P010
4ISTR),(IA(28),IELT),(IA(29),ITEM),(IA(30),ITEM),(IA(31),IMET), E270P011
5(IA(32),ISUM),(IA(33),IND),(IA(34),IMS),(IA(36),IDS),(IA(37), E270P012
6IORD),(IA(38),IORD),(IA(39),AGEL),(IA(50),J),(IA(51),J2), E270P013
7(IA(52),J3),(IA(53),J4),(IA(54),J5),(IA(55),J6),(IA(56),J7),(IA(57),E270P014
8)J8),(IA(58),JTY),(IA(59),IBB),(IA(60),I80),(IA(61),I1D),(IA(62),E270P015
9)IA),(IA(63),IDT),(IA(64),IDY),(IA(65),ITE),(IA(43),ITAP) E270P016
EQUIVALENCE (IA(66),ICAR),(IA(67),ICIX),(IA(68),ICIX),(IA(69), E270P017
1ICIZ),(IA(70),ICF),(IA(71),IXR),(IA(72),IYY),(IA(73),I2Z), E270P018
2(IA(74),IIC),(IA(75),IDFF),(IA(76),IST),(IA(77),IIS) E270P019
3,(IA(78),IGEM),(IA(79),IERR),(IA(80),TE),(IA(81),DT),(IA(82),DG), E270P020
4(AA(83),AL1),(AA(84),AL2),(AA(85),AL3),(AA(86),D21),(AA(107),P), E270P021
5(AA(131),UV),(AA(155),X),(AA(163),Y),(AA(171),Z),(AA(179),XD), E270P022
6(AA(186),YD),(AA(193),ZD),(AA(351),S),(AA(40),ZGEM) E270P023
7,(AA(42),INP),(AA(43),IPRG),(AA(44),IPRN),(AA(45),CINS),(AA(46),IUE270P024
8),(AA(47),GL),(AA(48),G2),(AA(49),G3) E270P025
EQUIVALENCE (IA(349),NTIC),(IA(348),ISDT),(IA(347),ISDY),(IA(346) E270P026
1,ISDZ),(IA(345),J9),(IA(344),J10),(IA(343),JPRS),(IA(342),JSDY) E270P027
2,(IA(341),JSDZ),(IA(340),JARE),(IA(339),JMMX),(IA(338),JMMY) E270P028
3,(IA(337),JMMZ),(IA(336),JMF),(IA(335),I4S),(IA(334),IDZ) E270P029
4,(IA(333),IPR),(IA(332),DGY),(AA(331),G2),(AA(330),PRES) E270P030
5,(IA(329),IPR) E270P031
IELT=0 E270P032
ITEM=0 E270P033
ITJC=0 E270P034
IMET=0 E270P035
DO LO I=1,8 E270P036
N(1)=0 E270P037
K=1-395 E270P038
IAK=0 E270P039
JM=J1+M E270P040
IELT=IA(JM)/100 E270P041
IMET=IA(JM)-100*IELT E270P042
JM=J2+M E270P043
IF (IELT-4) 100,100,450 E270P044
IF (IELT-3) 200,300,200 E270P045
100 JARE=IA(JM)/100 E270P046
200 JARE=IA(JM)/100 E270P047
ITEM=IA(JM)-100*JARE E270P048
GO TO 400 E270P049
300 JPRS=IA(JM)/100 E270P050
JSDZ=IA(JM)-100*JPRS E270P051
400 IF (IELT-3) 600,800,800 E270P052
450 IF (IELT-10) 470,470,500 E270P053
470 IF (IELT-8) 500,500,480 E270P054
480 JPRS=IA(JM)/100 E270P055
ITEM=IA(JM)-100*JPRS E270P056
L=1 E270P057
GO TO 1000 E270P058
ITIC=IA(JM)/100 E270P059
ITEM=IA(JM)-100*ITIC E270P060
JM=J3+M E270P061
JSDZ=IA(JM)/100 E270P062
JPRS=IA(JM)-100*JSDZ E270P063
L=2 E270P064
GO TO 1000 E270P065
JM=J4+M E270P066
JMMZ=IA(JM)/100 E270P067
JSDY=IA(JM)-100*JMMZ E270P068
L=3 E270P069
IF (IELT-4) 1000,900,1000 E270P070
JM=J3+M E270P071
JMMX=IA(JM)/100 E270P072
JMMY=IA(JM)-100*JMMX E270P073
L=2 E270P074
IF (IELT-4) 1000,700,1000 E270P075
JM=J5+M E270P076
JSDZ=IA(JM)/100 E270P077
JMF=IA(JM)-100*JSDZ E270P078
JM=J6+M E270P079
JPRS=IA(JM) E270P080
L=4 E270P081
GO TO (1100,1200,1300,1400),L E270P082
1100 JM=J3+M E270P083
N(1)=IA(JM) E270P084
I=1+L E270P085
1200 JM=J4+M E270P086
N(1)=IA(JM) E270P087
I=1+L E270P088
1300 JM=J5+M E270P089
N(1)=IA(JM) E270P090
I=1+L E270P091
JM=J6+M E270P092
N(1)=IA(JM) E270P093
I=1+L E270P094
JM=J7+M E270P095
N(1)=IA(JM) E270P096
I=1+L E270P097
JM=J8+M E270P098
N(1)=IA(JM) E270P099
I=1+L E270P100
JM=J9+M E270P101
N(1)=IA(JM) E270P102
I=1+L E270P103
JM=J10+M E270P104
N(1)=IA(JM) E270P105
I=1+L E270P106
JM=J11+M E270P107
N(1)=IA(JM) E270P108
I=1+L E270P109
IF (I-IH) 1600,1600,1450 E270P110
1450 IH=IH+1 E270P111
DO 1500 I=1HP,8 E270P112
1500 N(1)=0 E270P113
1600 RETURN E270P114
END E270P115

```

Table VII-43. Source program listing of subroutine TRAN (Link 2)

```

* LABEL
CEZTRN SUBROUTINE TRAN (A,IFS) E270N000
TRANSFORMS THE DESCRIPTION OF A VECTOR FROM LOCAL TO OVERALL E270N001
DIMENSION IA(1),AA(1),S(1),N(8),D21(21),D33(3,3),F22(3,3) E270N002
1,P(24),UV(24),X(8),Y(8),Z(8),XD(17),YD(17),ZD(17),G(11) E270N003
GUMMIN IA,AA E270N004
EQUIVALENCE (IA,AA),(D21,D33),(D21(10),E22),(D21(19),E),(D21(20),G)E270N005
EQUIVALENCE (IA(1),IN),(IA(2),IBN),(IA(3),IT),(IA(4),IP),(IA(5), E270N006
1IPRS),(IA(6),ITYPE),(IA(7),IMAT),(IA(8),IDEG),(IA(9),INX),(IA(10),E270N007
2IH),(IA(11),I8),(IA(12),IMX),(IA(13),IMY),(IA(14),IMZ),(IA(15),E270N009
3IMF),(IA(16),IARE),(IA(17),N(1)),(IA(25),M),(IA(26),ITY),(IA(27),E270N010
4ISTR),(IA(28),IELT),(IA(29),ITEM),(IA(30),ITEM),(IA(31),IMET), E270N011
5(IA(32),ISUM),(IA(33),IND),(IA(34),IMS),(IA(36),IDS),(IA(37), E270N012
6IORD),(IA(38),IORD),(IA(39),AGEL),(IA(50),J),(IA(51),J2), E270N013
7(IA(52),J3),(IA(53),J4),(IA(54),J5),(IA(55),J6),(IA(56),J7),(IA(57),E270N014
8)J8),(IA(58),JTY),(IA(59),IBB),(IA(60),I80),(IA(61),I1D),(IA(62),E270N015
9)IA),(IA(63),IDT),(IA(64),IDY),(IA(65),ITE),(IA(43),ITAP) E270N016
EQUIVALENCE (IA(66),ICAR),(IA(67),ICIX),(IA(68),ICIX),(IA(69), E270N017
1ICIZ),(IA(70),ICF),(IA(71),IXR),(IA(72),IYY),(IA(73),I2Z), E270N018
2(IA(74),IIC),(IA(75),IDFF),(IA(76),IST),(IA(77),IIS) E270N019
3,(IA(78),IGEM),(IA(79),IERR),(IA(80),TE),(IA(81),DT),(AA(82),DG), E270N020
4(AA(83),AL1),(AA(84),AL2),(AA(85),AL3),(AA(86),D21),(AA(107),P), E270N021
5(AA(131),UV),(AA(155),X),(AA(163),Y),(AA(171),Z),(AA(179),XD), E270N022
6(AA(186),YD),(AA(193),ZD),(AA(351),S),(AA(40),ZGEM) E270N023
7,(AA(42),INP),(AA(43),IPRG),(AA(44),IPRN),(AA(45),CINS),(AA(46),IUE270N024
8),(AA(47),GL),(AA(48),G2),(AA(49),G3) E270N025
EQUIVALENCE (IA(349),NTIC),(IA(348),ISDT),(IA(347),ISDY),(IA(346) E270N026
1,ISDZ),(IA(345),J9),(IA(344),J10),(IA(343),JPRS),(IA(342),JSDY) E270N027
2,(IA(341),JSDZ),(IA(340),JARE),(IA(339),JMMX),(IA(338),JMMY) E270N028
3,(IA(337),JMMZ),(IA(336),JMF),(IA(335),I4S),(IA(334),IDZ) E270N029
4,(IA(333),IPR),(IA(332),DGY),(AA(331),G2),(AA(330),PRES) E270N030
5,(IA(329),IPR) E270N031
DIMENSION EM(4,4),EN(4,4),D(4,4),DIR(3,3),DUM(1) E270N032
EQUIVALENCE (AA(200),EM),(AA(216),EN),(AA(232),EQ),(AA(248),O), E270N033
1(AA(264),DIR),(AA(273),DUM) E270N034
DIMENSION A(1) E270N035
1 IGFMP=IGFMP+1 E270N036
LJ1=0 E270N037
LK=IFS-4*IMS E270N038
DO 300 L=1,IGFMP E270N039
LK=LK+3*IMS E270N040
DO 200 J=1,3 E270N041
DO 200 I=1,IMS E270N042
LJ1=LJ1+1 E270N043
DUM(LJ1)=0, E270N044
LK=LK+1 E270N045
DO 100 K=1,3 E270N046
LK=LK+IMS E270N047
100 DUM(LJ1)=DUM(LJ1)+DIR(K,J)*LK E270N048
200 CONTINUE E270N049
300 CONTINUE E270N050
INI=3*IGFMP*IMS E270N051
DO 400 I=1,INI E270N052
I1=IFS+I E270N053
400 A(I)=DUM(I) E270N054
RETURN E270N055
END E270N056

```

Table VII-44. Source program listing of subroutine TRIM (Link 2)

```

* LABEL
CE2TRT SUBROUTINE TRIM F2TR1000
          GENERATES M, N AND L MATRICES OF THIN TRIANGULAR ELEMENT F2TR1001
          DIMENSION IA(2),AA(1),S(1),N(8),D21(21),D33(3,3),E22(3,3) F2TR1002
          1,P(24),UV(24),X(8),Y(8),Z(8),XN(7),YN(7),ZN(7),GL(1) F2TR1003
          COMMON IA,AA F2TR1004
          EQUIVALENCE(IA,AA),(D21,D33),(D21110),F22),(D21119),E1,(D21120),G1 F2TR1006
          EQUIVALENCE(IA(1),IN),IA(2),IBN),IA(3),IT),IA(4),IP),IA(5), F2TR1007
          11PRS),IA(16),ITYPE),IA(17),IMAT),IA(18),IDEG),IA(19),INX),IA(10),E2TR1008
          21M),IA(11),IB),IA(17),IMMX),IA(13),IMMY),IA(14),IMZ),IA(15),E2TR1009
          31MF1),IA(16),IARE),IA(17),N11),IA(25),M),IA(26),ITY),IA(27),E2TR1010
          41STR),IA(28),IELT),IA(29),ITFM),IA(30),ITIC),IA(31),IMET), F2TR1011
          51A(32),ISUM),IA(33),IND1),IA(34),IMS),IA(36),IDS),IA(37), F2TR1012
          6(ORD),IA(38),IORD1),IA(39),ACEL),IA(50),J1),IA(51),J2), F2TR1013
          7(IA(52),J3),IA(53),J4),IA(54),J5),IA(55),J6),IA(56),J7),IA(57),J8), F2TR1014
          8),J8),IA(58),J1Y),IA(59),J8),IA(60),IB),IA(61),ID),IA(62),E2TR1015
          9(IA),IA(63),OT),IA(64),IDV),IA(65),ITE),IA(4),ITAP) F2TR1016
          EQUIVALENCE(IA(66),ICAR),IA(67),ICIX),IA(68),ICLY),IA(69), F2TR1017
          11C12),IA(70),ICF1),IA(71),ICX),IA(72),IYY),IA(73),IZ), F2TR1018
          2(IA(74),IIC1),IA(75),IUEP),IA(76),IST),IA(77),IIS) F2TR1019
          3,IA(78),IGEM),IA(79),IERK),AA(80),TE),AA(81),OT),AA(82),DGI, F2TR1020
          4(AA(83),AL1),AA(84),AL2),AA(85),AL3),AA(86),D21),AA(107),P1, F2TR1021
          5(AA(131),UV),AA(155),K),AA(163),V),AA(171),Z),AA(179),XD), F2TR1022
          6(AA(186),VD),AA(193),ZD),AA(351),S),AA(40),ZGEM) F2TR1023
          7,AA(42),INP),AA(43),IPBC),AA(44),IPEN),AA(45),CONS),AA(46),IUE2TR1024
          8),AA(47),GL),AA(48),G2),AA(49),G3) F2TR1025
          DIMENSION EM(4,4),EN(4,4),O(4,4),F(4,4) F2TR1026
          EQUIVALENCE(AA(200),EM),AA(216),EN),AA(232),E0),AA(248),O) F2TR1027
          EM(1,2)=YD(2) F2TR1029
          EM(1,3)=-YD(1) F2TR1030
          EM(1,1)=YD(1)-YD(2) F2TR1031
          EM(2,1)=0. F2TR1032
          EM(2,2)=0. F2TR1033
          EM(2,3)=0. F2TR1034
          EM(3,1)=XD(2)-XD(1) F2TR1035
          EM(3,2)=XD(2) F2TR1036
          EM(3,3)=XD(1) F2TR1037
          DD 42 J=1,3 F2TR1038
          EN1,J)=EM(2,J) F2TR1039
          EN2,J)=EM(3,J) F2TR1040
          EN3,J)=EM(1,J) F2TR1041
          42 CONTINUE F2TR1042
          DD 63 J=1,3 F2TR1043
          EO(1,J)=EM(1,J) F2TR1044
          EO(2,J)=EM(3,J) F2TR1045
          430 RETURN F2TR1046
          END
    
```

Table VII-45. Source program listing of subroutine TRM (Link 2)

```

* LABEL
CE2TRM SUBROUTINE TRM (A,B,C,M,N) F2TRM000
          N=N1 F2TRM001
          DIMENSION A(3,3),B(4,4),C(4,4),D(4,4) F2TRM002
          IF (NT 2,I,1) F2TRM003
          2 N=N F2TRM004
          GO TO 5 F2TRM005
          1 DO 3 I=1,M F2TRM006
          DO 3 J=1,N F2TRM007
          3 C(I,J)=B(I,J) F2TRM008
          8 DO 4 I=1,N F2TRM009
          DO 4 J=1,M F2TRM010
          D(I,J)=0. F2TRM011
          DO 5 K=1,M F2TRM012
          5 D(I,J)=D(I,J)+C(K,I)*A(K,J) F2TRM013
          4 CONTINUE F2TRM014
          DO 6 I=1,N F2TRM015
          DO 6 J=1,N F2TRM016
          C(I,J)=0. F2TRM017
          DO 7 K=1,M F2TRM018
          7 C(I,J)=C(I,J)+D(I,K)*B(K,J) F2TRM019
          6 CONTINUE F2TRM020
          RETURN F2TRM021
          END F2TRM022
    
```

Table VII-46. Source program listing of main program of Link 3 (deflection link)

```

* CHAIN (3,2)
* LABEL
CELAS3
C MAIN PROGRAM FOR DEFLECTION LINK
C OBTAINS THE DEFLECTION COMPONENTS IN OVERALL COORDINATES
DIMENSION I(11),AA(1),S(1),N(8),D21(21),Q33(3,3),E22(3,3)
1,P(24),UV(24),X(8),Y(8),Z(8),XD(7),YD(7),ZD(7)
COMMON IA,AA
EQUIVALENCE (IA,AA), (D21,D33), (D21(10),E22), (D71(19),E1, (D71(20),G)
EQUIVALENCE (IA(1),IN), (IA(2),IN8), (IA(3),IT), (IA(4),IP), (IA(5),
1)PRS), (IA(6),ITYPE), (IA(7),IMAT), (IA(8),IDEG), (IA(9),INX), (IA(10),ELAS3008
2)H), (IA(11),T8), (IA(12),IMMX), (IA(13),IMMY), (IA(14),IMM2), (IA(15),ELAS3009
3)MF), (IA(16),IARE), (IA(17),N(1)), (IA(25),M), (IA(26),ITY), (IA(27),FLAS3010
4)STR), (IA(28),IELT), (IA(29),ITEM), (IA(30),ITIC), (IA(31),IME7),
5)IA(32),ISUM), (IA(33),IND), (IA(34),IMS), (IA(36),IOS), (IA(37),
6)ORD), (IA(38),IORD1), (IA(39),ACEF), (IA(50),J1), (IA(51),J2),
7)IA(52),J3), (IA(53),J4), (IA(54),J5), (IA(55),J6), (IA(56),J7), (IA(57),ELAS3014
8),J8), (IA(58),J9), (IA(59),J8B), (IA(60),J8D), (IA(61),J8D1), (IA(62),ELAS3015
9)IA), (IA(63),IDT), (IA(64),IDY), (IA(65),ITE), (IA(67),ITAP)
EQUIVALENCE (IA(66),ICAR), (IA(67),ICIX), (IA(68),ICIY), (IA(69),
1)ICIZ), (IA(70),ICF1), (IA(71),ICX), (IA(72),ICY), (IA(73),IZZ),
2)IA(74),ICG), (IA(75),IDEF), (IA(76),IST), (IA(77),IIS)
3), (IA(78),IGEM), (IA(79),IERR), (IA(80),TE), (IA(81),OT), (IA(82),NG),
4)AA(83),ALL1), (AA(84),AL2), (AA(85),AL3), (AA(86),D71), (AA(87),P),
5)AA(131),UV1), (AA(155),X), (AA(156),Y), (AA(171),Z), (AA(179),XD1),
6)AA(186),YD1), (AA(193),ZD), (AA(351),S), (AA(40),ZGEM)
7), (AA(42),INP), (AA(43),IPRG), (AA(44),IPFN), (AA(45),CONS), (AA(46),I)
8), (AA(47),G1), (AA(48),G2), (AA(49),G3)
EQUIVALENCE (IA(349),NTIC), (IA(348),ISDT), (IA(347),ISDY), (IA(346)
1),ISDZ), (IA(345),J8), (IA(344),J10), (IA(343),JPRS), (IA(342),JSDY)
2), (IA(341),JSDZ), (IA(340),JAKF), (IA(339),JMMX), (IA(338),JMMY)
3), (IA(337),JMMZ), (IA(336),JMF1), (IA(335),ITAS), (IA(334),IDZ)
4), (IA(333),IPR), (AA(332),DGY), (AA(331),DGZ), (AA(330),PRFS)
5), (IA(329),IP1R)
DIMENSION RA(999,6)
EQUIVALENCE (AA( 9000),RB)
C SOLVE THE EQUILIBRIUM EQUATIONS FOR UNKNOWN DEFLECTIONS
10 CALL TICK (ITIM)
CALL VELAS(I,SUM,IERR,IST,IOEF)
20 CALL TICK(ITIM)
TINV=ITIM
TINV=INV/60
IF (IERR) 302,234,302
234 IF (INP-1) 2341,2341,2342
2342 IOEF=IOEF+1
IEND=IOEF+ISUM
WRITE OUTPUT TAPE 6,2343,(I,AA(I),I=IOEF1,IFND)
2343 FORMAT (11H,34HREDUCED DEFLECTION VECTOR FOLLOWS.//5(116,F14.5,
14X))
C COMPLETE THE DEFLECTION VECTOR AND PRINT.
2341 DO 202 M=1,IN
DO 202 K=1,6
202 BB(M,K)=0.
JJ=-IOEG
DO 2031 M=1,IN
JJ=JJ+IDEG
DO 203 K=1,6DEG
JJ=JJ+K
1STJ=1S1+J
100J=1B0+J
L=IA(18UJ)
IICJ=IIC+J
204 IF (L) 204,205,206
2042 IF (L=1) 2042,2041,206
100J=1BB+J
I=IA(18UJ)
IDFF1=IDFF-7
BB(M,K)=AA(IDFF1)
11=(L-1)/DEG+1
L2=L-(L-1)*IOEG
BB(L1,L2)=BB(L1,L2)+AA(IICJ)*BB(M,K)
GO TO 203
2041 IBB=IBB+J
I=IA(18UJ)
IDFF1=IDFF+1
BB(M,K)=AA(IDFF1)
GO TO 203
205 BB(M,K)=AA(IICJ)+BB(M,K)
GO TO 203
206 IF (L=1000) 2061,205,205
2061 LL=IA(LL)
IDFF1=IDFF+LL
BB(M,K)=AA(IDFF1)*AA(IICJ)
203 CONTINUE
2031 JJ=-IDEG
DO 2011 M=1,IN
JJ=JJ+IDEG
DO 201 K=1,6DEG
IDFF1=IDFF+JJ+K
201 AA(IDFF1)=BB(M,K)
2011 CONTINUE
C REARRANGE DEFLECTIONS ACCORDING TO TYPE
C ASSUME NORMAL CASE
IELT=1
C CHECK THE SPECIAL CASES
IF (IOEG-3) 449,449,450
449 IF (IGEM) 450,449,450
448 IF (ITH-2) 450,447,443
C DISTINGUISH GRIDWORK CASE
447 IF (IMMY) 447,442,443
C PLATE AND/OR GRIDWORK CASE
443 IELT=2
GO TO 441
C SHELL OF REVOLUTION OR PLANAR FRAME CASE
442 IELT=3
441 DO 40 M=1,IN
GO TO 440,42,43,IELT
42 X(1)=BB(M,1)
X(2)=BB(M,2)
X(3)=BB(M,3)
BB(M,1)=0.
BB(M,2)=0.
BB(M,3)=X(1)
BB(M,4)=X(2)
BB(M,5)=X(3)
GO TO 40
43 X(1)=BB(M,3)
BB(M,3)=0.
BB(M,6)=X(1)
40 CONTINUE
C PUNCH OUT RESULTS IF NECESSARY
450 CALL PUNC
WRITE OUTPUT TAPE 6,1111,(M,(BB(M,K),K=1,6),M=1,IN)
1111 FORMAT (11H,39X,17HMODAL DEFLECTIONS//5H NODE,5X,13HDISP.,ALONG X,ELAS3126
15X,13HDISP.,ALONG Y,5X,13HDISP.,ALONG Z,5X,13HROTA.,ABOUT X,
25X,13HROTA.,ABOUT Y,5X,13HROTA.,ABOUT Z//15,6ELR,7))
IF (INP) 310,310,320
320 IF (ITAS) 305,305,315
310 CALL RESI
IF(ITAS) 305,305,306
306 CALL RESW
IF (INX-3) 345,345,355
305 WRITE OUTPUT TAPE 6,3051
3051 FORMAT (54H NO SCRATCH TAPE IS GIVEN OR ERROR IN THE SCRATCH TAPE)
GO TO 345
310 IF (INX-3) 345,345,340
340 IF (ITAS) 345,345,350
350 CALL RESI
IF (ITAS) 345,345,355
355 CALL ELST
345 CALL TICK (ITIM)
C3T=ITIM
C3T=C3T/60.
WRITE OUTPUT TAPE 6,5555,C3T,TINV
5555 FORMAT (21H DEFLECTION LINK TOOK,F7.2,2X,8HSECONDS.,75X,F7.2)
IF (INX-3) 3421,3421,342
3421 CALL CHAIN (1,ITAP)
342 CALL CHAIN (4,ITAP)
302 WRITE OUTPUT TAPE 6,3021,IERR
3021 FORMAT (42H STIFFNESS MATRIX IS NOT POSITIVE DEFINITE.15)
GO TO 3421
END

```

Table VII-47. Source program listing of subroutine ELST (Link 3)

```

* LABEL
CE3ELT SUBROUTINE ELST F3ELT000
WRITES ON TAPE ITAS ELEMENT SET INFORMATION F3ELT001
DIMENSION IA(1),AA(1),S(1),MIR(1),D21(2),D33(3,3),E22(3,3) F3ELT002
1,P(24),UV(24),X(R),Y(R),Z(R),XD(7),YD(7),ZD(7) F3ELT003
COMMON IA,AA F3ELT004
EQUIVALENCE (IA,AA),(D21,D33),(D21(10),E22),(D21(19),F),(D21(20),G) F3ELT005
EQUIVALENCE (IA(1),IN),(IA(2),INR),(IA(3),IT),(IA(4),P),(IA(5), F3ELT006
1IPRS),(IA(6),ITYPE),(IA(7),IMAT),(IA(8),IDFG),(IA(9),INX),(IA(10),F3ELT008
2IMI),(IA(11),I8),(IA(12),IMMX),(IA(13),IMY),(IA(14),IMZ),(IA(15),F3ELT009
3IMFI),(IA(16),IARE),(IA(17),M11),(IA(25),M),(IA(26),ITY),(IA(27),F3ELT010
4ISTR),(IA(28),IELT),(IA(29),ITEM),(IA(30),ITIC),(IA(31),IMET),( F3ELT011
5(IA(32),ISUM),(IA(33),IND),(IA(34),IMS),(IA(36),IDS),(IA(37), F3ELT012
6IORD),(IA(38),IORD1),(IA(39),ACEL),(IA(50),J11),(IA(51),J2), F3ELT013
7(IA(52),J3),(IA(53),J4),(IA(54),J5),(IA(55),J6),(IA(56),J7),(IA(57)F3ELT014
8),J8),(IA(58),JTY),(IA(59),IB8),(IA(60),IB0),(IA(61),ID1),(IA(62),F3ELT015
9IA),(IA(63),IDT),(IA(64),IDY),(IA(65),ITE),(IA(61),ITAP) F3ELT016
EQUIVALENCE (IA(66),ICAR),(IA(67),ICIX),(IA(68),ICIX),(IA(69), F3ELT017
1ICIZ),(IA(70),ICFI),(IA(71),ICX),(IA(72),IY),(IA(73),IZ),( F3ELT018
2(IA(74),IGEM),(IA(79),JERR),(AA(80),TE),(AA(81),DT),(AA(82),DG), F3ELT019
3,(IA(83),AL1),(AA(84),AL2),(AA(85),AL3),(AA(86),D21),(AA(107),P), F3ELT020
4(AA(131),UV),(AA(155),X),(AA(163),Y),(AA(171),Z),(AA(179),XD), F3ELT021
5(AA(186),YD),(AA(193),ZD),(AA(351),S),(AA(40),ZGEM) F3ELT022
7,(AA(42),INP),(AA(43),IPBG),(AA(44),IPEN),(AA(45),CONS),(AA(46),IUE)F3ELT024
8),(AA(47),G1),(AA(48),G2),(AA(49),G3) F3ELT025
EQUIVALENCE (IA(349),NTIC),(IA(348),ISD1),(IA(347),ISD2),(IA(346) F3ELT026
1,ISD2),(IA(345),J9),(IA(344),J10),(IA(343),JPRS),(IA(342),JSDY) F3ELT027
2,(IA(341),JSD2),(IA(340),JARE),(IA(339),JMMX),(IA(338),JMMY) F3ELT028
3,(IA(337),JMMZ),(IA(336),JMF1),(IA(335),ITAS),(IA(334),IDZ) F3ELT029
4,(IA(333),IPR),(AA(332),DCY),(AA(331),DG2),(AA(330),PRES) F3ELT030
5,(IA(329),IPR) F3ELT031
DIMENSION IMNT(24) F3ELT032
EQUIVALENCE (UV,IMNT),(IA(200),IONE) F3ELT033
ISN=IST+IND F3ELT034
IELM=13 F3ELT035
IELN=IELM-1 F3ELT036
ISN1=ISN+1 F3ELT037
ISNN=ISN+IN*IELM F3ELT038
INC1=0 F3ELT039
IONE=0 F3ELT040
DO 8 I=ISN1,ISNN F3ELT041
IA(I)=0 F3ELT042
DO 1 I=1,IT F3ELT043
JI I=JI+1 F3ELT044
IELT=IA(JI)/100 F3ELT045
GO TO 19,9,9,9,2,3,2,3,4,5,2,3,2,3,2,3,14,14,IELT F3ELT046
IONE=IONE+1 F3ELT047
GO TO 1 F3ELT048
KJ=4 F3ELT049
KN=3 F3ELT050
GO TO 6 F3ELT051
KJ=4 F3ELT052
KN=4 F3ELT053
GO TO 6 F3ELT054
KJ=3 F3ELT055
KN=4 F3ELT056
GO TO 6 F3ELT057
KJ=3 F3ELT058
KN=8 F3ELT059
GO TO 6 F3ELT060
KJ=4 F3ELT061
KN=2 F3ELT062
KK=J1+1+KJ-2)*11 F3ELT063
DO 7 J=1,KN F3ELT064
KK=KK+IT F3ELT065
NN=IA(KK) F3ELT066
ISN1=ISN+(NN-1)*IELM+1 F3ELT067
IE=IA(ISN1)+1 F3ELT068
IF (IE=IELN) 12,11,11 F3ELT069
WRITE OUTPUT TAPE 6,13,IELN,NN F3ELT070
FORMAT (10H MORE THAN,14,2X,31INDN-ONE-DIMENSNL ELMNTS AT NODE,15)F3ELT071
INCT=1 F3ELT072
GO TO / F3ELT073
ISNN=ISN1+IE F3ELT074
IA(ISN1)=IE F3ELT075
IA(ISNN)=I F3ELT076
CONTINUE F3ELT077
1 CONTINUE F3ELT078
IF (INC1) 19,20,19 F3ELT079
ITAS=0 F3ELT080
WRITE OUTPUT TAPE 6,19,1 F3ELT081
FORMAT(53H MODAL STRESS COMPUTATION IS DELETED DUE TO PRECEDING) F3ELT082
GO TO 100 F3ELT083
DO 21 I=1,IN F3ELT084
ISN1=ISN+(I-1)*IELM+1 F3ELT085
IE=IA(ISN1) F3ELT086
IF (IE) 23,23,24 F3ELT087
DO 22 J=1,IE F3ELT088
ISNN=ISN1+J F3ELT089
IMNT(J)=IA(ISNN) F3ELT090
WRITE TAPE ITAS,I,IE,(IMNT(J),J),IE) F3ELT091
GO TO 21 F3ELT092
WRITE TAPE ITAS,J,IE,IE F3ELT093
CONTINUE F3ELT094
DO 25 I=L,IN F3ELT095
BACKSPACE ITAS F3ELT096
RETURN F3ELT097
END F3ELT098

```

Table VII-48. Source program listing of subroutine PUNC (Link 3)

```

* LABEL F3PUNC000
CE3PUNC SUBROUTINE PUNC F3PUNC001
DUMMY SUBROUTINE F3PUNC002
RETURN F3PUNC003
END F3PUNC004

```

Table VII-49. Source program listing of subroutine RESI (Link 3)

```

* LABEL F3RES000
CE3RES SUBROUTINE RESI F3RES001
COMPUTES RESIDUAL FORCES AT THE NODES F3RES002
DIMENSION IA(1),AA(1),S(1),MIR(1),D21(2),D33(3,3),E22(3,3) F3RES003
1,P(24),UV(24),X(R),Y(R),Z(R),XD(7),YD(7),ZD(7) F3RES004
COMMON IA,AA F3RES005
EQUIVALENCE (IA,AA),(D21,D33),(D21(10),E22),(D21(19),F),(D21(20),G)F3RES006
EQUIVALENCE (IA(1),IN),(IA(2),INR),(IA(3),IT),(IA(4),P),(IA(5), F3RES007
1IPRS),(IA(6),ITYPE),(IA(7),IMAT),(IA(8),IDFG),(IA(9),INX),(IA(10),F3RES008
2IMI),(IA(11),I8),(IA(12),IMMX),(IA(13),IMY),(IA(14),IMZ),(IA(15),F3RES009
3IMFI),(IA(16),IARE),(IA(17),M11),(IA(25),M),(IA(26),ITY),(IA(27),F3RES010
4ISTR),(IA(28),IELT),(IA(29),ITEM),(IA(30),ITIC),(IA(31),IMET),( F3RES011
5(IA(32),ISUM),(IA(33),IND),(IA(34),IMS),(IA(36),IDS),(IA(37), F3RES012
6IORD),(IA(38),IORD1),(IA(39),ACEL),(IA(50),J11),(IA(51),J2), F3RES013
7(IA(52),J3),(IA(53),J4),(IA(54),J5),(IA(55),J6),(IA(56),J7),(IA(57)F3RES014
8),J8),(IA(58),JTY),(IA(59),IB8),(IA(60),IB0),(IA(61),ID1),(IA(62),F3RES015
9IA),(IA(63),IDT),(IA(64),IDY),(IA(65),ITE),(IA(61),ITAP) F3RES016
EQUIVALENCE (IA(66),ICAR),(IA(67),ICIX),(IA(68),ICIX),(IA(69), F3RES017
1ICIZ),(IA(70),ICFI),(IA(71),ICX),(IA(72),IY),(IA(73),IZ),( F3RES018
2(IA(74),IGEM),(IA(79),JERR),(AA(80),TE),(AA(81),DT),(AA(82),DG), F3RES019
3,(IA(83),AL1),(AA(84),AL2),(AA(85),AL3),(AA(86),D21),(AA(107),P), F3RES020
4(AA(131),UV),(AA(155),X),(AA(163),Y),(AA(171),Z),(AA(179),XD), F3RES021
5(AA(186),YD),(AA(193),ZD),(AA(351),S),(AA(40),ZGEM) F3RES022
7,(AA(42),INP),(AA(43),IPBG),(AA(44),IPEN),(AA(45),CONS),(AA(46),IUE)F3RES024
8),(AA(47),G1),(AA(48),G2),(AA(49),G3) F3RES025
EQUIVALENCE (IA(349),NTIC),(IA(348),ISD1),(IA(347),ISD2),(IA(346) F3RES026
1,ISD2),(IA(345),J9),(IA(344),J10),(IA(343),JPRS),(IA(342),JSDY) F3RES027
2,(IA(341),JSD2),(IA(340),JARE),(IA(339),JMMX),(IA(338),JMMY) F3RES028
3,(IA(337),JMMZ),(IA(336),JMF1),(IA(335),ITAS),(IA(334),IDZ) F3RES029
4,(IA(333),IPR),(AA(332),DCY),(AA(331),DG2),(AA(330),PRES) F3RES030
5,(IA(329),IPR) F3RES031
C FUNDAMENTAL MODAL FORCES AND ASSEMBLE FOR OBTAINING RESIDUALS F3RES032
DO 40 I=1,IND F3RES033
IST=IST+1 F3RES034
60 A(I)STI=0 F3RES035
70 DO 20 J=1,IT F3RES036
C READ THE QUANTITIES FOR ELEMENT JJ F3RES037
50 READ TAPE ITAS,I,ITTI,ITM,NAV,IMS,IDS,IDS2,INC(1),I=L,IMS,(S(1), F3RES038
1I=1,IDS2),(P(1),CF,I=1,IMS) F3RES039
C COMPUTE AND ASSEMBLE THE MODAL FORCES OF ELEMENT JJ F3RES040
IF (NAV-2) 91,92,92 F3RES041
CF=L F3RES042
GO TO 93 F3RES043
92 CF=0,5 F3RES044
93 IF (M-JJ) 100,9,100 F3RES045
DO 10 I=1,IDS F3RES046
KK=IDS+I F3RES047
DO 11 K=1,IDS F3RES048
KK=KK+IDS F3RES049
KDEG=(K-1)/IMS+1 F3RES050
KNDD=K-(KDEG-1)*IMS F3RES051
KNOD=N(KNOD) F3RES052
IDEF=IDEF+(KNOD-1)*IDEG+KDEG F3RES053
P(I)=P(I)-S(KK)*AA(IDEF) F3RES054
KDEG=(I-1)/IMS+1 F3RES055
KNDD=K-(KDEG-1)*IMS F3RES056
KNOD=N(KNOD) F3RES057
ND=(KNOD-1)*IDEG+KDEG F3RES058
IST=IST+ND F3RES059
AA(IST)=AA(IST)-P(I)*CF F3RES060
10 CONTINUE F3RES061
IF (ITTI-ITM) 50,21,21 F3RES062
21 IF (NAV-2) 20,50,20 F3RES063
20 CONTINUE F3RES064
31 RETURN F3RES065
100 ITAS=0 F3RES066
GO TO 31 F3RES067
END F3RES068

```

Table VII-50. Source program listing of subroutine RESW (Link 3)

```

* LABEL
CF3HEW
SUBROUTINE RESW
WRITES RESONANT FORCES AT THE NODES
DIMENSION IA(1),AA(1),S(1),N(R),DZ(12),D3(3,3),E22(3,3)
1,P(24),UV(24),X(8),Y(8),Z(8),XD(7),YD(7),ZD(7)
COMMON IA,AA
EQUIVALENCE (IA,AA),(D2,D3),(D2(10),E22),(D2(10),E),(D2(20),G)
EQUIVALENCE IA(1),IN,IA(2),IBN,IA(3),IT,IA(4),IP,IA(5),
1IPR,IA(6),ITYPE,IA(7),IMAT,IA(8),IDEG,IA(9),INX,IA(10),
2IH,IA(11),IB,IA(12),IMX,IA(13),IMY,IA(14),IMZ,IA(15),
3IMF,IA(16),IARL,IA(17),W(1),IA(25),M,IA(26),ITY,IA(27),
4ISTR,IA(28),IELT,IA(29),ITEM,IA(30),ITIC,IA(31),INF,
5IA(32),ISUM,IA(33),IND,IA(34),IMS,IA(36),IOS,IA(37),
6IORD,IA(38),IORD1,IA(39),ACEF,IA(50),J,IA(51),J2,
7IA(52),J3,IA(53),J4,IA(54),J5,IA(55),J6,IA(56),J7,IA(57),
8JBI,IA(58),JTY,IA(59),IBB,IA(60),IRO,IA(61),IIO,IA(62),
9IA(1),IA(63),IDT,IA(64),IYI,IA(65),ITF,IA(41),ITAP,
EQUIVALENCE (IA(66),ICAR),IA(67),ICEX,IA(68),ICY),IA(69),
1ICIZ),IA(70),ICFI,IA(71),IXX,IA(72),IYY,IA(73),IZZ,
2IA(74),IIC,IA(75),IDEP,IA(76),IST,IA(77),IIS,
3,IA(78),IGEM,IA(79),IERR,IA(80),TF,IA(81),DTI,IA(82),DG,
4IA(83),AL1,IA(84),AL2,IA(85),AL3,IA(86),D21,IA(107),P1,
5IAA(131),UV),IAA(155),X),IAA(163),Y),IAA(171),Z),IAA(179),XD,
6IAA(186),YD),IAA(193),ZD),IAA(351),S),IAA(40),ZGEM,
7,IAA(42),INP,IAA(43),IPBG,IAA(44),IPEM,IAA(45),CONS),IAA(46),
8),IAA(47),G1,IAA(48),G2,IAA(49),G3
EQUIVALENCE (IA(349),NTIC),IA(348),ISDT),IA(347),ISDY),IA(346),
1,ISDZ),IA(345),J9),IA(344),J10),IA(343),JPRS),IA(342),JSY)
2,IA(341),JSO2),IA(340),JARE),IA(339),JMX),IA(338),JMY)
3,IA(337),JMH2),IA(336),JMF),IA(335),ITAS),IA(334),IOT)
4,IA(333),IPR),IA(332),RGY),IA(331),DG2),IA(330),PREF)
5,IA(329),IPR)
IELT=IELT
WRITE OUTPUT TAPE 6,74
74 FORMAT (1H1,40X,26HFORCES ACTING AT THE NODES//5H NODE=5X,13HFORCE=3REW034
1 ALONG X,5X,13HFORCE ALONG Y,5X,13HFORCE ALONG Z,4X,14HMOMENT ABOUT X,5X,14HMO
2 T X,4X,14HMOPOINT ABOUT Y,4X,14HMOPOINT ABOUT Z//)
DO 71 I=1,6
71 P(I)=0.
DO 75 I=1,IN
ND=(I-1)*IDEG
TSTI=IST+ND
DO 72 J=1,IDEG
L=J
JSTJ=STI+J
GO TO 172,2+3),IELT
2 L=J+2
GO TO 72
3 IF (J-3) 72,4,72
4 L=J+3
72 P(L)=AA(IST+J)
WRITE OUTPUT TAPE 6,76,1,(P(I),J=1,6)
76 FORMAT (15,AE18,7)
77 CONTINUE
RETURN
END
E3REW000
E3REW001
E3REW002
E3REW003
E3REW004
E3REW005
E3REW006
E3REW007
E3REW008
E3REW009
E3REW010
E3REW011
E3REW012
E3REW013
E3REW014
E3REW015
E3REW016
E3REW017
E3REW018
E3REW019
E3REW020
E3REW021
E3REW022
E3REW023
E3REW024
E3REW025
E3REW026
E3REW027
E3REW028
E3REW029
E3REW030
E3REW031
E3REW032
E3REW033
E3REW034
E3REW035
E3REW036
E3REW037
E3REW038
E3REW039
E3REW040
E3REW041
E3REW042
E3REW043
E3REW044
E3REW045
E3REW046
E3REW047
E3REW048
E3REW049
E3REW050
E3REW051
E3REW052
E3REW053
E3REW054
E3REW055

```

Table VII-51. Source program listing of subroutine TICK (Link 3)

```

* FAP
COUNT 25
LBL TICK
ENTRY TICK
TICK
NZT ONCE
TRA FIRST
CAL 5
SIR INITL
ALS 18
SLW* 1,4
TRA 2,4
FIKST SIL ONCE
CAL 5
SLW INITL
STZ* 1,4
TRA 2,4
ONCE PZE
INITL END
TICK000
TICK001
TICK002
TICK003
TICK004
TICK005
TICK006
TICK007
TICK008
TICK009
TICK010
TICK011
TICK012
TICK013
TICK014
TICK015
TICK016
TICK017
TICK018

```


Table VII-52. Source program listing of subroutine VELAS (Link 3)

```

* LABEL
CE3VEL SUBROUTINE VELAS (NN,IERR,IST,IDEF)
C SOLVES THE GOVERNING EQUATIONS BY VARIABLE BAND-WIDTH CHOLESKI METHOD
DIMENSION A(1),IA(1)
COMMON Z
EQUIVALENCE (A,IA)
IU=IERR
IJ=IST+1
Z=1.E-16
IF (NN) 101,101,1000
101 IERR=1
GO TO 106
1000 NN=NN
NI=NI+1
C FIND THE SMALLEST DIAGONAL ELEMENT.
1001 E=ARSF(A(IST+1))
DO 77 I=1,N
IU=IU+1
ID=IA(IU)+IST
76 IF (ARSF(A(ID))-E) 771,77,77
771 E=ARSF(A(ID))
77 CONTINUE
C SET ALLOWABLE MINIMUM ON DIAGONAL ELEMENTS.
E=E*Z
C OBTAIN U(1,1)
IF (A(IST+1) -F) 100,100,10
10 IF (N-1) 1072,1074,1072
1074 A(IDEF+1)=A(IDEF+1)/A(IST+1)
GO TO 105
1072 A(IST+1)=SQRTF(A(IST+1))
C OBTAIN THE REST OF FIRST ROW OF U.
IU=IU+2
IW=IA(IU)-1
IF (IW-1) 1312,1312,1313
1313 DO 1311 J=2,IW
IJ=IJ+J
1311 A(IJ)=A(IJ)/A(IST+1)
C OBTAIN THE OTHER ROWS OF U SEQUENTIALLY.
1312 IU=IU+NI
MAX=IA(IU)+IST
DO 701 J=1,N
JJ=MAX+J
701 IA(JJ)=0
DO 11 I=2,N
PREPARE FOR THE I TH ROW.
IU=IU+1
ID=IA(IU)
IDE=IA(ID)+1
JMX=IDE-ID+1-1
ID=ID+IST
II=ID-1
IF (II-1) 15,16,16
16 DO 702 J=1,IW
JJ=MAX+J
702 IA(IJ)=IA(IJ)+1
15 IW=JMX
IEI=I-1
DO 112 J=I,JMX
IJ=IJ+J
JJ=MAX+J
KB=1-IA(IJ)
E3VFLO00
E3VFLO01
E3VFLO02
E3VFLO03
E3VFLO04
E3VFLO05
E3VFLO06
E3VFLO07
E3VFLO08
E3VFLO09
E3VFLO10
E3VFLO11
E3VFLO12
E3VFLO13
E3VFLO14
E3VFLO15
E3VFLO16
E3VFLO17
E3VFLO18
E3VFLO19
E3VFLO20
E3VFLO21
E3VFLO22
E3VFLO23
E3VFLO24
E3VFLO25
E3VFLO26
E3VFLO27
E3VFLO28
E3VFLO29
E3VFLO30
E3VFLO31
E3VFLO32
E3VFLO33
E3VFLO34
E3VFLO35
E3VFLO36
E3VFLO37
E3VFLO38
E3VFLO39
E3VFLO40
E3VFLO41
E3VFLO42
E3VFLO43
E3VFLO44
E3VFLO45
E3VFLO46
E3VFLO47
E3VFLO48
E3VFLO49
E3VFLO50
E3VFLO51
E3VFLO52
E3VFLO53
E3VFLO54
E3VFLO55
E3VFLO56
E3VFLO57
E3VFLO58
E3VFLO59
E3VFLO60
IF (KB-1) 1162,13,13
1162 DO 131 K=KB,IE1
IUK=I+K
KD=IA(IUK)+IST
IK=KD+1-K
JK=KD+J-K
131 A(IJ)=A(IJ)-A(IK)*A(IK)
IF (J-1) 100,12,13
12 IF (A(IJ)-E) 100,100,122
122 A(II)=SQRTF (A(II))
GO TO 112
13 A(IJ)=A(IJ)/A(II)
112 CONTINUE
11 CONTINUE
IM=ID
C U IS NOW AVAILABLE COMPLETELY.
C SOLUTION IS REQUESTED. START FORWARD SWEEP. FIRST B(1)
1009 A(IDEF+1)=A(IDEF+1)/A(IST+1)
C THEN THE REST OF B.
DO 21 I=2,N
L=IDEF+1
IU=IU+1
ID=IA(IU)+IST
IEI=I-1
JJ=MAX+1
KB=1-IA(IJ)
IF (KB-1) 3521,21,21
3>21 DO 22 K=KB,IE1
IUK=I+K
KD=IA(IUK)+IST
IK=KD+1-K
JK=IDEF+K
22 A(L)=A(L)-A(IK)*A(IK)
21 A(L)=A(L)/A(II)
C FORWARD SWEEP IS COMPLETED. START BACKWARD SWEEP. B(N) FIRST.
L=IDEF+N
A(L)=A(L)/A(IM)
C THEN THE REST OF B IN BACKWARD DIRECTION.
DO 31 L=2,N
I=N1-L
J=I+IDEF
JI=J-1
II=I+1
IU=IU+1
ID=IA(IU)
IDE=IA(II)+1
JMX=IDE-ID
ID=ID+IST
IDI=ID-1
IF (JMX-1) 31,31,321
321 DO 32 K=2,JMX
M=JI+K
IK=IDI+K
32 A(J)=A(J)-A(M)*A(IK)
31 A(J)=A(J)/A(II)
C THE SOLUTION IS OBTAINED SUCCESSFULLY ON B.
100 IERR=0
C NOW GO HOME.
GO TO 106
100 IERR=I-IST
106 RETURN
END
E3VFLO61
E3VFLO62
E3VFLO63
E3VFLO64
E3VFLO65
E3VFLO66
E3VFLO67
E3VFLO68
E3VFLO69
E3VFLO70
E3VFLO71
E3VFLO72
E3VFLO73
E3VFLO74
E3VFLO75
E3VFLO76
E3VFLO77
E3VFLO78
E3VFLO79
E3VFLO80
E3VFLO81
E3VFLO82
E3VFLO83
E3VFLO84
E3VFLO85
E3VFLO86
E3VFLO87
E3VFLO88
E3VFLO89
E3VFLO90
E3VFLO91
E3VFLO92
E3VFLO93
E3VFLO94
E3VFLO95
E3VFLO96
E3VFLO97
E3VFLO98
E3VFLO99
E3VF100
E3VF101
E3VF102
E3VF103
E3VF104
E3VF105
E3VF106
E3VF107
E3VF108
E3VF109
E3VF110
E3VF111
E3VF112
E3VF113
E3VF114
E3VF115
E3VF116
E3VF117
E3VF118
E3VF119
E3VF120
E3VF121
E3VF122

```

Table VII-53. Source program listing of main program of Link 4 (stress link)

```

* CHAIN (4,2)
* LABEL
CELAS4
C MAIN PROGRAM FOR STRESS LINK ELAS4000
C DATA MESH STRESSSES AT MESH POINTS ELAS4001
C DIMENSION I(1),J(1),K(1),L(1),M(1),N(1),O(1),P(1),Q(1),R(1),S(1),T(1),U(1),V(1),W(1),X(1),Y(1),Z(1),
1,P(2),Q(2),R(2),S(2),T(2),U(2),V(2),W(2),X(2),Y(2),Z(2),G(1) ELAS4002
COMMON I4,AA ELAS4003
EQUIVALENCE (I4,AA), (O21,O33), (O21(O10),E221), (O21(O19),F), (O21(O20),G) ELAS4006
FOURVALENCE (I4(1),IN), (I4(2),IBN), (I4(3),IT), (I4(4),IP), (I4(5), I ELAS4007
1PR5), (I4(6),ITYPE), (I4(7),IMAT), (I4(8),IDEG), (I4(9),IMX), (I4(10), I ELAS4008
2IM1), (I4(11),I8), (I4(12),IMM), (I4(13),IMY), (I4(14),IMZ), (I4(15), I ELAS4009
3IMF), (I4(16),IARE), (I4(17),IAC), (I4(18),IAC2), (I4(19),IAC3), (I4(20), I ELAS4010
4ISTK), (I4(21),IETL), (I4(22),ITEM), (I4(23),ITIC), (I4(24),IAC1), (I4(25), I ELAS4011
5(I4(26),ISHM), (I4(27),IND), (I4(28),IMS), (I4(29),IDS), (I4(30), I ELAS4012
6ORD), (I4(31),IORD1), (I4(32),IACEL), (I4(33),J1), (I4(34),J2), ELAS4013
7(I4(35),J3), (I4(36),J4), (I4(37),J5), (I4(38),J6), (I4(39),J7), (I4(40), I ELAS4014
8),J8), (I4(41),J9), (I4(42),J10), (I4(43),J11), (I4(44),J12), (I4(45), I ELAS4015
9(I4(46),I8), (I4(47),I8), (I4(48),I8), (I4(49),I8), (I4(50),I8), (I4(51), I ELAS4016
EQUIVALENCE (I4(16),IACR), (I4(17),IACX), (I4(18),IACY), (I4(19), I ELAS4017
IIC1), (I4(20),IICF), (I4(21),IIX), (I4(22),IYY), (I4(23),IIZ), ELAS4018
2(I4(24),IIC), (I4(25),IDEF), (I4(26),IS1), (I4(27),IIS) ELAS4019
3,I4(28),IGEM), (I4(29),IERR), (AA(81),TE), (AA(82),DT), (AA(83),DG), ELAS4020
4(AA(84),AL1), (AA(85),AL2), (AA(86),AL3), (AA(87),D21), (AA(107),P), ELAS4021
5(AA(131),UV), (AA(132),X), (AA(133),Y), (AA(134),Z), (AA(135),XD), ELAS4022
6(AA(136),XD), (AA(137),ZD), (AA(138),S), (AA(140),ZBPM) ELAS4023
7,(AA(142),INP), (AA(143),IPBC), (AA(144),IPEN), (AA(145),CONS), (AA(146), I ELAS4024
8), (AA(147),G), (AA(148),G2), (AA(149),G3) ELAS4025
FOURVALENCE (I4(34),IAC), (I4(35),ISD), (I4(36),ISDY), (I4(37), I ELAS4026
1,ISDZ), (I4(38),J9), (I4(39),J10), (I4(40),J11), (I4(41),J12), (I4(42), I ELAS4027
2,I4(34),J13), (I4(35),J14), (I4(36),J15), (I4(37),J16), (I4(38),J17), (I4(39), I ELAS4028
3,I4(37),J18), (I4(38),J19), (I4(39),J20), (I4(40),J21), (I4(41),J22), (I4(42), I ELAS4029
4,I4(43),J23), (I4(44),J24), (I4(45),J25), (I4(46),J26), (I4(47),J27), (I4(48), I ELAS4030
5,I4(49),J28) ELAS4031
DIMENSION BIR(3),SIR(3),DIR(3,3),SR(A),XN(3),XF(3),ON(A),OF(6), ELAS4032
IRES(6),RED(6),BAS(3),ICLAS(4),NRAN(10),NUI(3),NES(3) ELAS4033
EQUIVALENCE (AA(200),IDNE), (AA(201),ICN), (AA(202),LM), (AA(203),ASTELAS4034
3), (AA(204),INRDN), (AA(205),ARE), (AA(206),ICLA), (AA(207),IMFL), ELAS4035
2(AA(208),IM), (AA(209),IC), (AA(210),IDM), (AA(211),ANGLP), (AA(212), I ELAS4036
3,ICAS), (AA(213),IE), (AA(214),NB), (AA(215),NR) ELAS4037
4,(AA(216),IROT), (AA(217),B5T) ELAS4038
FOURVALENCE (AA(220),BIR), (AA(221),SIR), (AA(222),DIR), (AA(223),SR) ELAS4039
1,(AA(241),XN), (AA(242),XF), (AA(243),ON), (AA(244),OF), (AA(245),RFS) ELAS4040
2,(AA(265),RFD), (AA(271),BAS), (AA(274),ICLAS), (AA(278),NRAN) ELAS4041
3,(AA(292),RMI), (AA(295),NES) ELAS4042
DIMENSION NEL(20,17),MAC(4,4,20),IWR(10),DB(A,6),A(90,7),BIR(R), ELAS4043
IC(8,2),FF(1),NSET(100),MSE(100),H(3,3) ELAS4044
EQUIVALENCE (AA(14000),FF), (INUI(1),J1), (INUI(2),JN1), (INUI(3),J51) ELAS4045
EQUIVALENCE (FF(1),NEL), (FF(3),MAC), (FF(6),IWR), (FF(7),DB), (FF(15), I ELAS4046
1,FF(17),A), (FF(18),B), (FF(19),C), (FF(20),D), (FF(21),E), (FF(22),F), (FF(23), I ELAS4047
2,SET), (FF(24),W) ELAS4048
EQUIVALENCE (NES(11),ICD1), (NES(12),IRIC), (NES(13),IDR) ELAS4049
START THE CLOCK ELAS4050
CALL TICK (ITIM) ELAS4051
INPT=INP ELAS4052
SCRATCH TAPE ITAS NECESSARY. SET IF IT IS GIVEN ELAS4053
IF (ITAS) 1000,1000,1 ELAS4054
1000 WRITE OUTPUT TAPE 6,1001 ELAS4055
1001 FORMAT (46H NO SCRATCH TAPE. STRESS LINK IS NOT EXECUTED.) ELAS4056
GO TO 1002 ELAS4057
C SEE IF THERE IS ANY NON-ONE-DIMENSIONAL ELEMENT ELAS4058
1 IF (IT-10NE) 2000,2000,2 ELAS4059
C NON-ONE-DIMENSIONAL ELEMENTS EXIST. PRINT THE TABLE HEADING ELAS4060
2 WRITE OUTPUT TAPE 6,3 ELAS4061
3 FORMAT (15H,15X,8THSTRESSES AT THE NODES OF TWO- OR THREE-DIMENSIONAL ELAS4062
10AL CONTINUUM BY BEST FIT STRAIN TENSORS/AX,10AHALL QUANTITIES ARE) ELAS4063
2 IN OVERALL SYSTEM, UNLESS ** APPEARS INDICATING DATA IN KSI, FTA ELAS4064
3AND ZTA LOCAL SYSTEM/45X,24H** INDICATES NODE IN BOUNDARY ELAS4065
4 //5H NODE,2X,3HMAT,5H CLAS,7X,11HFIRST COMP,4X,11HSEC ELAS4066
50ND COMP,4X,11HTHIRD COMP,4X,11HFORTH COMP,4X,11HFIFTH COMP,4X, ELAS4067
61HSIXTH COMP//) ELAS4068
IF (I4000-15T-IND) 22,22,21 ELAS4069
22 WRITE OUTPUT TAPE 6,221 ELAS4070
221 FORMAT (18H SCRATCH AREA FF OVERLAPS WITH RESIDUAL AREA. PUSH FF ELAS4071
1URTHER DOWN BY RECOMPILING LINK4) ELAS4072
GO TO 1002 ELAS4073
C START STRESS COMPUTATION AT NODES ELAS4074
21 DO 400 ICN=1,IN ELAS4075
ICN=ICN ELAS4076
INP=INPT ELAS4077
CALL CAS4 ELAS4078
C INITIALIZE AA AND FF AREAS ELAS4079
OU 10 =202,300 ELAS4080
AA(I)=0. ELAS4081
DO 20 =1,1705 ELAS4082
FF(I)=0. ELAS4083
C GENERATE THE COORDINATES AND THE DEFLECTIONS OF NODE ICN ELAS4084
CALL FINDX(ICN,X) ELAS4085
CALL FINDO(1,ICN,O) ELAS4086
C READ IN THE ELEMENT SET ELAS4087
READ TAPE ITAS,K,LM,INEL(J,1),J=1,LM ELAS4088
IF (ICN-K) 1003,4,1003 ELAS4089
1003 WRITE OUTPUT TAPE 6,1004,ICN,K ELAS4090
1004 FORMAT (6H ERROR IN READING ELEMENT SETS FROM TAPE ITAS. STRESS ELAS4091
LINK EXECUTION IS DELETED.,216) ELAS4092
GO TO 1002 ELAS4093
C SEE IF ANY NON-ONE-DIMENSIONAL ELEMENT AT THE CURRENT NODE ELAS4094
4 IF (LM) 200,200,1001 ELAS4095
399 WRITE OUTPUT TAPE 6,399,ICN ELAS4096
3991 FORMAT (15,13X,43HNO NON-ONE-DIMENSIONAL ELEMENT AT THIS NODE) ELAS4097
GO TO 400 ELAS4098
C THERE IS AT LEAST ONE NON-ONE-DIMENSIONAL ELEMENT. ELAS4099
C PREPARE NEL(I,J),MAC(I,J,K) TABLES AND COMPUTE IMEL,ICLAS ELAS4100
4001 CALL GENE ELAS4101
SET INDICATORS TO NON-BOUNDARY NODE ELAS4102
INBND=0 ELAS4103
AST=TH A ELAS4104
C SEE IF THE NODE IS ON BOUNDARY ELAS4105
C IF SO MAKE INRDN=1, AS1=1H* AND COMPUTE RER(I) AND ARF ELAS4106
CALL BOFF ELAS4107
C COMPUTE STRESSES FOR EACH MATERIAL GROUP ELAS4108
DO 500 IM=1,IMEL ELAS4109
IM=IM
IMET=MAC(IM,1,2) ELAS4110
IMET=NEL(IM,1,3) ELAS4111
C COMPUTE STRESSES FOR EACH CLASS ELAS4112
ICLA=ICLAS(IM) ELAS4113
DO 580 IC=1,ICLA ELAS4114
IC=IC
C FIND THE CLASS TYPE ELAS4115
ICAS=MAC(IM,IC,2) ELAS4116
ICAS=NEL(ICAS,4) ELAS4117
C INITIALIZE TCON,ANGLF,BAS,DIN,IROT,AST,IERR,TE,DT,DG,NFS AND W ELAS4118
CALL INLZ ELAS4119
C SEE IF THE GROUP IS OF SHELL TYPE ELAS4120
IF (ICAS=5) 6,7,7 ELAS4121
YES, IT IS OF SHELL TYPE. RE-DTERMINE LOCAL AXES (DIN) ELAS4122
IROT=1 ELAS4123
BST=2H** ELAS4124
CALL DINA ELAS4125
C IS LOCAL AXES (DIN) TO BE ROTATED ELAS4126
IF (INBND) 71,70,71 ELAS4127
C IF NECESSARY ROTATE DIN SO THAT KSI IS IN ZTA-BIR PLANE ELAS4128
CALL MDIN ELAS4129
C GENERATE MATERIAL MATRIX DO IN LOCAL SYSTEM (DIN) ELAS4130
CALL MFTA ELAS4131
70 CLEAR THE A AREA ON WHICH AREO AND SETA WILL OPERATE ELAS4132
DO 72 I=1,90 ELAS4133
DO 72 J=1,7 ELAS4134
C CHECK IF THE NODE IS ON BOUNDARY ELAS4135
IF (INRDN) 521,520,521 ELAS4136
C YES IT IS ON BOUNDARY. GENERATE EOS FOR STRESS B.C. ELAS4137
CALL ABO ELAS4138
521 GENERATE STRAIN EOS FOR NODAL LINES OF ELEMENTS OF CLASS IC ELAS4139
IE=MAC(IM,IC,1)+1 ELAS4140
DO 520 I=1,24F ELAS4141
IF (INP-2) 5201,5202,5202 ELAS4142
520 WRITE OUTPUT TAPE 6,520,520,B5T,NES(11),NES(2) ELAS4143
5203 FORMAT (15,X,2,3X,41HSTRAIN EQUATIONS ALONG NODAL LINES FOLLOW,14 ELAS4144
13H X //) ELAS4145
5201 CONTINUE ELAS4146
I=I+1 ELAS4147
5202 WRITE OUTPUT TAPE 6,5221,ICN,AST,IMET,ICAS ELAS4148
5221 FORMAT (15,41,14,15,3X,44HNOT ENOUGH INDEPENDENT INFORMATION AVAIL ELAS4149
LABLE) ELAS4150
GO TO 580 ELAS4151
C COMPUTE STRESSES ELAS4152
523 CALL STRS ELAS4153
C PRINT OUT STRESSES ELAS4154
WRITE OUTPUT TAPE 6,523,ICN,AST,IMET,ICAS,B5T,(SR(I),I=1,6) ELAS4155
81 WRITE OUTPUT TAPE 6,81,ICN,(10DIN(I,J),I=1,3),J=1,3),ICN,AST,IX(I), ELAS4156
I=4,9) ELAS4157
83 FORMAT (15,10H DR,2COSINS,5X //3MKS1,2X,3F7.4,5X,3HETA,2X,3F7.4,5X) ELAS4158
1,3HZTA,2X,3F7.4/15,10H DEFLECONS,42,1X,AE15,5) ELAS4159
C EQUATIONS ARE AVAILABLE. SOLVE WITH LEAST SQUARES ELAS4160
80 CALL LFST ELAS4161
C SEE IF ENOUGH INDEPENDENT EQUATIONS EXIST ELAS4162
IF (IERR) 522,523,522 ELAS4163
522 WRITE OUTPUT TAPE 6,5221,ICN,AST,IMET,ICAS ELAS4164
5221 FORMAT (15,41,14,15,3X,44HNOT ENOUGH INDEPENDENT INFORMATION AVAIL ELAS4165
LABLE) ELAS4166
GO TO 580 ELAS4167
C COMPUTE STRESSES ELAS4168
523 CALL STRS ELAS4169
C PRINT OUT STRESSES ELAS4170
WRITE OUTPUT TAPE 6,523,ICN,AST,IMET,ICAS,B5T,(SR(I),I=1,6) ELAS4171
5231 FORMAT (15,41,14,15,42,1X,6E15,5) ELAS4172
C PRINT STRESSES IN THE OVERALL SYSTEM IF NECESSARY ELAS4173
CALL SAME ELAS4174
IF (INP-2) 580,5232,5232 ELAS4175
5232 WRITE OUTPUT TAPE 6,5233 ELAS4176
5233 FORMAT (1H //) ELAS4177
580 CONTINUE ELAS4178
400 CONTINUE ELAS4179
IF (IDNE) 1002,1002,2000 ELAS4180
C READ THE CLOCK AND PRINT THE ELAPSED TIME ELAS4181
1007 CALL TICK (ITIM) ELAS4182
CIT=ITIM ELAS4183
CIT=CIT/60. ELAS4184
WRITE OUTPUT TAPE 6,999,CIT ELAS4185
999 FORMAT (11X,14HSTRESS LINK TOOK,F7.2,10H SECONDS.) ELAS4186
GO TO THE FIRST LINK ELAS4187
CALL CHAIN (1,ITAP) ELAS4188
2000 CALL DIM(K) ELAS4189
IF (IERR) 1003,1002,1003 ELAS4190
END ELAS4191

```

Table VII-54. Source program listing of subroutine ABEQ (Link 4)

```

* LABFL
CF4A7D
C SUBROUTINE ABEQ
GENERATES EQUATIONS FOR STRESS BOUNDARY CONDITIONS AT A NODE
DIMENSION IA(11),AA(11),S(1),WB(1),DZ(1),O33(3,3),E22(3,3)
1,P(24),UV(24),X(R1),Y(R1),Z(R1),XD(7),YD(7),ZD(7),G(1)
COMMON IA,AA
EQUIVALENCE(IA,AA),(D21,D33),(D21(10),E27),(D21(19),E1,(D21(20),G)
EQUIVALENCE(IA(11),IN),(IA(21),IBN),(IA(31),IT),(IA(4),IP),(IA(5),
11PR5),(IA(16),ITYP),(IA(17),IMAT),(IA(18),IDEG),(IA(19),IMX),(IA(10),
2IM),(IA(11),IB),(IA(12),IMAX),(IA(13),IMMY),(IA(14),IMW),(IA(15),
3IMFI),(IA(18),IARE),(IA(17),IC(1)),(IA(25),N),(IA(26),ITY),(IA(27),
4ISTR),(IA(28),IFLT),(IA(29),ITEM),(IA(30),IFIC),(IA(31),IMFT),
5IA(32),ISUM),(IA(33),IND),(IA(34),IMS),(IA(36),IDS),(IA(37),
6IORI),(IA(38),IQRD1),(IA(39),ACEL),(IA(50),J1),(IA(51),J2),
7IA(52),J3),(IA(53),J4),(IA(54),J5),(IA(55),J6),(IA(56),J7),(IA(57),
8J),J8),(IA(58),JTY),(IA(59),IRB),(IA(60),IROJ),(IA(61),ITD),(IA(62),
9I14),(IA(63),IDT),(IA(64),IDY),(IA(65),ITE),(IA(61),ITAP)
EQUIVALENCE(IA(16),ICAR),(IA(17),ICX),(IA(18),ICY),(IA(19),
1ICZ),(IA(17),ICF),(IA(71),ICX),(IA(72),ICY),(IA(73),ICZ),
2IA(74),IC1),(IA(75),IDFF),(IA(76),IST),(IA(77),IIS)
3,(IA(78),IGEM),(IA(79),IFRR),(AA(80),TF),(AA(81),DT),(AA(82),DG),
4(AA(83),AL1),(AA(84),AL2),(AA(85),AL3),(AA(86),O21),(AA(107),P),
5(AA(111),UV),(AA(155),X),(AA(163),Y),(AA(171),Z),(AA(179),XD),
6(AA(186),YD),(AA(193),ZD),(AA(351),S),(AA(401),ZFM)
7,(AA(421),IMP),(AA(439),IPBE),(AA(441),IPEN),(AA(445),CONS),(AA(446),IUE)
8,(AA(447),G1),(AA(448),G2),(AA(449),G3)
EQUIVALENCE(IA(349),NTIC),(IA(348),ISDT),(IA(347),ISDY),(IA(346),
1,ISDZ),(IA(345),J9),(IA(344),J10),(IA(343),JPRS),(IA(342),JSDY)
2,(IA(341),JSDZ),(IA(340),JARF),(IA(339),JMMX),(IA(338),JMMY)
3,(IA(337),JMMZ),(IA(336),JMF1),(IA(335),JMAS),(IA(334),JIZ)
4,(IA(333),JPR1),(AA(332),D6Y),(AA(331),D6Y),(AA(330),PRF5)
5,(IA(329),IPR1)
DIMENSION BIR(3),DIR(3),DIM(3),SR(6),XN(3),XF(3),ON(6),OF(6),
1RES(6),RED(6),BAS(3),ICLAS(4),NBAN(10),NU(3),NES(3)
EQUIVALENCE(AA(200),IMPE),(AA(201),ICN),(AA(202),LM),(AA(203),AST)
1,(AA(204),INRDN),(AA(205),ARE),(AA(206),ICLA),(AA(207),IMFL),
2(AA(208),IM),(AA(209),IC),(AA(210),ICDN),(AA(211),ANGLE),(AA(212),
3ICAS),(AA(213),EI),(AA(214),NB),(AA(215),MB)
4,(AA(216),IWH),(AA(217),RST)
EQUIVALENCE(IA(220),BIR),(AA(223),SIR),(AA(226),DIN),(AA(235),SR)
1,(AA(241),XN),(AA(244),XF),(AA(247),DN),(AA(253),OF),(AA(259),RFS)
2,(AA(269),RED),(AA(271),BAS),(AA(274),ICLAS),(AA(278),NRAN)
3,(AA(292),NU),(AA(295),NES)
DIMENSION NEL(20),L1,MAC(4,4),ZD1,ING(90),DD(6,6),A1,490,71,B(8,8),
1IC(8,2),FF(11),MSET(100),MSET(100),W13,3)
EQUIVALENCE(AA(1000),FF),(M(1),J1),(M(2),JM1),(M(3),J51)
EQUIVALENCE(IEF11),NEL1,(FF(341),MAC),(FF(661),ING),(FF(751),ND1),
1(FF(787),A),(FF(1417),B),(FF(1481),C),(FF(1497),MSET),(FF(1597),
2MSET),(FF(1697),W)
EQUIVALENCE(NES(1),ICOL),(MES(2),IRIG),(NES(3),IDR)
DIMENSION NFK(3),Z1,NEK(3,2)
EQUIVALENCE(X(1),REK1,Y(1),NEK)
ICOL=ICOL
IRIG=IRIG
C GENERATE THE RESIDUE VECTOR
1ST=15+(ICN-1)*IDFG
DU 9 I=1,10FG
1ST=1ST+1
9 RES11=AA(1ST)
C INITIALIZE
IEQ=2
N11=1
N12=3
N13=5
IREB=1
IREN=2
CT=TE**3/12
CR=ARE/DD(1,1)
CL=CR*ARE
DD 12 J=1,2
DU 12 I=1,7
REK(I,J)=1
NEK(I,J)=1
IF(XN(11) 31,30,3)
30 XX=1
GO TO 32
31 XX=XN(11)
32 ICN=0
GENERATE EQUATIONS ACCORDING TO CLASS
ICAS=ICAS
GO TO(1,2,3,4,5,6,7,8),ICAS
C PLANE STRESS AND PLANE STRAIN
C CR=CR/TE
GO TO 15

```

Table VII-55. Source program listing of subroutine AGEL (Link 4)

```

A LABEL
CE*AGEL
SUBROUTINE AGEL
C DUMMY SUBROUTINE
RETURN
END
E44GFLO0
F44GFLO1
F44GFLO2
F44GEL03
E44GEL04

```

Table VII-57. Source program listing of subroutine BOFI (Link 4)

```

* LABEL
CF*BOFI
SUBROUTINE BOFI
C TO FIND IF THE NODE IS ON BOUNDARY
DIMENSION IA(1,AA(1),S11,N(8),D21(21),D33(3,3),F22(3,3)
L,P(24),UV(24),X(R),Y(R),Z(R),XPI(7),YPI(7),ZPI(7),G(11)
COMMON IA,AA
EQUIVALENCE IA,AA, I(21),D(3), (D21(10),F22(10),I(19),E), (D21(20),G)
EQUIVALENCE IA(11),IN, IA(12),IBN, IA(13),IT, IA(14),IP, IA(15),
1IPRS, IA(16),IPI, IA(17),IMX, IA(18),IDFG, IA(19),INX, IA(10),
2IM, IA(11),IR, IA(12),IMX, IA(13),IMY, IA(14),IMZ, IA(15),
3IMF1, IA(16),IARE, IA(17),M(1), IA(25),M, IA(26),IT, IA(17),
4ISTR, IA(28),IELT, IA(29),IEM, IA(30),ITIC, IA(31),IME1,
5IA(32),ISUM, IA(33),IND1, IA(34),IMS, IA(36),IDS, IA(137),
6IORD1, IA(138),IORD1, IA(139),ACEL, IA(150),J1, IA(151),J2,
7IA(152),J3, IA(153),J4, IA(154),J5, IA(155),J6, IA(156),J7, IA(157)
8I, JM, IA(158),JTY, IA(159),JBR, IA(160),IBO, IA(161),IJD, IA(162)
9IA(163),IOT, IA(164),IOT, IA(165),ITF, IA(166),ITF, IA(167),
EQUIVALENCE IA(168),ICAR, IA(167),ICX, IA(168),ICP, IA(169),
1ICZ, IA(170),ICF1, IA(171),IX, IA(172),IY, IA(173),IZ,
2IA(174),IC, IA(175),IDFF, IA(176),IST, IA(177),IIS
3IA(178),IGEM, IA(179),IERR, IA(180),TF, IA(181),DT, IA(182),OR,
4IA(183),ALL, IA(184),AL2, IA(185),AL3, IA(186),D21, IA(187),P,
5IA(188),UV, IA(189),X, IA(190),Y, IA(191),Z, IA(192),XD,
6IA(189),YD, IA(193),ZD, IA(194),ZGEM, IA(195),ZGEM
7IA(192),INP, IA(193),IPBG, IA(194),IPFN, IA(195),CONS, IA(196),IUF
8I, IA(197),G1, IA(198),G2, IA(199),G3
EQUIVALENCE IA(199),NTIC, IA(199),ISDT, IA(199),ISDY, IA(199)
1ISDZ, IA(199),J91, IA(199),J10, IA(199),JPRS, IA(199),ISDY
2IA(199),J502, IA(199),JARE, IA(199),JMX, IA(199),JMY
3IA(199),JMM2, IA(199),JMF1, IA(199),JAS, IA(199),IOT
4IA(199),IPR, IA(199),DGY, IA(199),D21, IA(199),PRES
5IA(199),IPR
DIMENSION BIR(3),SIR(3),DIN(3,3),SR(6),XN(3),XF(3),ONI(6),OF(6),
1RES(6),RED(6),BAS(3),ICLAS(4),MBANI(10),NU(3),NES(3)
EQUIVALENCE IA(1200),IONE, IA(1201),ICN, IA(1202),LM, IA(203),ASTF
2IA(1204),INRON, IA(205),ARE, IA(206),ICL, IA(207),IMEL,
3IA(1208),IM, IA(1209),IC, IA(1210),ICON, IA(1211),ANGLF, IA(1212),
3ICAS, IA(1213),IE, IA(1214),NBI, IA(1215),MB
4IA(1216),IROT, IA(1217),BST
EQUIVALENCE IA(1220),RJR, IA(1223),SIR, IA(1224),DIN, IA(1235),SR
1IA(241),XN, IA(1244),XF, IA(1247),ON, IA(1253),OF, IA(1259),KFS
2IA(265),KFD, IA(1271),BAS, IA(1274),ICLAS, IA(1278),NBN
3IA(1292),NU, IA(1295),NES
DIMENSION NEL(20,17),MAC(4,4,20),IWG(9),DD(6,6),A(9,7),R(8,8),
1IC(R,2),FF(1),NSET(100),MSET(100),M(3),J(1),NH(2),JM(1),NH(3),JS(1)
EQUIVALENCE IA(14000),FF, IA(1401),JP1, IA(1402),JM, IA(1403),JS1
EQUIVALENCE IFF(1),NEL, IFF(141),MAC, IFF(146),IWG, IFF(175),DD,
1IFF(178),A, IFF(147),R, IFF(148),C, IFF(149),NSET, IFF(1597),
2MSET, IFF(1697),W
DIMENSION CIR(3),JBAN(10),VE1(3),VF2(3)
EQUIVALENCE B(11),VE1, B(14),VE2
L=0
DO 10 I=1,M
K=JBAN(I)
CALL FINDX (K,XF)
L=L+1
A(L,1)=XF(1)-XN(1)+1.15
A(L,2)=XF(2)-XN(2)+1.16
A(L,3)=XF(3)-XN(3)+1.17
A(L,4)=1
CONTINUE
DE=0
IF (L-3) 45,14,14
DO 20 I=1,3
DO 30 J=1,4
R(I,J)=0
DO 30 K=1,L
B(I,J)+R(I,J)+A(K,1)*A(K,J)
IF (J-3) 40,40,4
40 GO TO 20
CIR(I)=B(I,4)
20 CONTINUE
CALL INV(R,3,CIR,1,DET)
IF (DET) 50,45,50
PHINIS ARE ON ONE PLANE, COMPUTE NORMAL AS VECTOR PRODUCT
DO 46 I=1,3
VE1(I)=R(I,1)
VE2(I)=R(I,2)
46 CALL VECT (CIR,VE1,VE2)
O=1
CALL UNIT (R,0)
IF (IMP-2) 55,56,56
50 WRITE OUTPUT TAPE 6,57,XN(1),XN(2),XN(3),CIR(1),CIR(2),CIR(3)
57 FORMAT(20X,12HCOORDINATES ,3F12.4,4X,7HNORMAL ,3F8.5)
59 RETURN
END
F44BOFI00
F44BOFI01
F44BOFI02
E44BOFI03
F44BOFI04
F44BOFI05
F44BOFI06
F44BOFI07
F44BOFI08
F44BOFI09
F44BOFI10
F44BOFI11
F44BOFI12
F44BOFI13

```

Table VII-56. Source program listing of subroutine BEST (Link 4)

```

* LABEL
CE*BST
SUBROUTINE BEST(CIR,JRAN,MZ)
C OBTAINS BEST FIT PLANE AT A NODE
TO OBTAIN UNIT NORMAL OF BEST FIT PLANE PASSING THROUGH MZ NODES
OF JRAN SET ON VECTOR CIR
DIMENSION IA(1,AA(1),S11,N(8),D21(21),D33(3,3),F22(3,3)
L,P(24),UV(24),X(R),Y(R),Z(R),XPI(7),YPI(7),ZPI(7),G(11)
COMMON IA,AA
EQUIVALENCE IA,AA, I(21),D(3), (D21(10),F22(10),I(19),E), (D21(20),G)
EQUIVALENCE IA(11),IN, IA(12),IBN, IA(13),IT, IA(14),IP, IA(15),
1IPRS, IA(16),IPI, IA(17),IMX, IA(18),IDFG, IA(19),INX, IA(10),
2IM, IA(11),IR, IA(12),IMX, IA(13),IMY, IA(14),IMZ, IA(15),
3IMF1, IA(16),IARE, IA(17),M(1), IA(25),M, IA(26),IT, IA(17),
4ISTR, IA(28),IELT, IA(29),IEM, IA(30),ITIC, IA(31),IME1,
5IA(32),ISUM, IA(33),IND1, IA(34),IMS, IA(36),IDS, IA(137),
6IORD1, IA(138),IORD1, IA(139),ACEL, IA(150),J1, IA(151),J2,
7IA(152),J3, IA(153),J4, IA(154),J5, IA(155),J6, IA(156),J7, IA(157)
8I, JM, IA(158),JTY, IA(159),JBR, IA(160),IBO, IA(161),IJD, IA(162)
9IA(163),IOT, IA(164),IOT, IA(165),ITF, IA(166),ITF, IA(167),
EQUIVALENCE IA(168),ICAR, IA(167),ICX, IA(168),ICP, IA(169),
1ICZ, IA(170),ICF1, IA(171),IX, IA(172),IY, IA(173),IZ,
2IA(174),IC, IA(175),IDFF, IA(176),IST, IA(177),IIS
3IA(178),IGEM, IA(179),IERR, IA(180),TF, IA(181),DT, IA(182),OR,
4IA(183),ALL, IA(184),AL2, IA(185),AL3, IA(186),D21, IA(187),P,
5IA(188),UV, IA(189),X, IA(190),Y, IA(191),Z, IA(192),XD,
6IA(189),YD, IA(193),ZD, IA(194),ZGEM, IA(195),ZGEM
7IA(192),INP, IA(193),IPBG, IA(194),IPFN, IA(195),CONS, IA(196),IUF
8I, IA(197),G1, IA(198),G2, IA(199),G3
EQUIVALENCE IA(199),NTIC, IA(199),ISDT, IA(199),ISDY, IA(199)
1ISDZ, IA(199),J91, IA(199),J10, IA(199),JPRS, IA(199),ISDY
2IA(199),J502, IA(199),JARE, IA(199),JMX, IA(199),JMY
3IA(199),JMM2, IA(199),JMF1, IA(199),JAS, IA(199),IOT
4IA(199),IPR, IA(199),DGY, IA(199),D21, IA(199),PRES
5IA(199),IPR
DIMENSION BIR(3),SIR(3),DIN(3,3),SR(6),XN(3),XF(3),ONI(6),OF(6),
1RES(6),RED(6),BAS(3),ICLAS(4),MBANI(10),NU(3),NES(3)
EQUIVALENCE IA(1200),IONE, IA(1201),ICN, IA(1202),LM, IA(203),ASTF
2IA(1204),INRON, IA(205),ARE, IA(206),ICL, IA(207),IMEL,
3IA(1208),IM, IA(1209),IC, IA(1210),ICON, IA(1211),ANGLF, IA(1212),
3ICAS, IA(1213),IE, IA(1214),NBI, IA(1215),MB
4IA(1216),IROT, IA(1217),BST
EQUIVALENCE IA(1220),RJR, IA(1223),SIR, IA(1224),DIN, IA(1235),SR
1IA(241),XN, IA(1244),XF, IA(1247),ON, IA(1253),OF, IA(1259),KFS
2IA(265),KFD, IA(1271),BAS, IA(1274),ICLAS, IA(1278),NBN
3IA(1292),NU, IA(1295),NES
DIMENSION NEL(20,17),MAC(4,4,20),IWG(9),DD(6,6),A(9,7),R(8,8),
1IC(R,2),FF(1),NSET(100),MSET(100),M(3),J(1),NH(2),JM(1),NH(3),JS(1)
EQUIVALENCE IA(14000),FF, IA(1401),JP1, IA(1402),JM, IA(1403),JS1
EQUIVALENCE IFF(1),NEL, IFF(141),MAC, IFF(146),IWG, IFF(175),DD,
1IFF(178),A, IFF(147),R, IFF(148),C, IFF(149),NSET, IFF(1597),
2MSET, IFF(1697),W
DIMENSION CIR(3),JBAN(10),VE1(3),VF2(3)
EQUIVALENCE B(11),VE1, B(14),VE2
L=0
DO 10 I=1,M
K=JBAN(I)
CALL FINDX (K,XF)
L=L+1
A(L,1)=XF(1)-XN(1)+1.15
A(L,2)=XF(2)-XN(2)+1.16
A(L,3)=XF(3)-XN(3)+1.17
A(L,4)=1
CONTINUE
DE=0
IF (L-3) 45,14,14
DO 20 I=1,3
DO 30 J=1,4
R(I,J)=0
DO 30 K=1,L
B(I,J)+R(I,J)+A(K,1)*A(K,J)
IF (J-3) 40,40,4
40 GO TO 20
CIR(I)=B(I,4)
20 CONTINUE
CALL INV(R,3,CIR,1,DET)
IF (DET) 50,45,50
PHINIS ARE ON ONE PLANE, COMPUTE NORMAL AS VECTOR PRODUCT
DO 46 I=1,3
VE1(I)=R(I,1)
VE2(I)=R(I,2)
46 CALL VECT (CIR,VE1,VE2)
O=1
CALL UNIT (R,0)
IF (IMP-2) 55,56,56
50 WRITE OUTPUT TAPE 6,57,XN(1),XN(2),XN(3),CIR(1),CIR(2),CIR(3)
57 FORMAT(20X,12HCOORDINATES ,3F12.4,4X,7HNORMAL ,3F8.5)
59 RETURN
END
F44BST000
F44BST001
F44BST002
F44BST003
F44BST004
F44BST005
F44BST006
F44BST007
F44BST008
F44BST009
F44BST010
F44BST011
F44BST012
F44BST013
F44BST014
F44BST015
F44BST016
F44BST017
F44BST018
F44BST019
F44BST020
E44BST021
F44BST022
F44BST023
F44BST024
F44BST025
F44BST026
F44BST027
F44BST028
F44BST029
F44BST030
F44BST031
F44BST032
F44BST033
F44BST034
F44BST035
F44BST036
F44BST037
F44BST038
F44BST039
F44BST040
F44BST041
F44BST042
F44BST043
F44BST044
F44BST045
F44BST046
F44BST047
F44BST048
F44BST049
F44BST050
F44BST051
F44BST052
F44BST053
F44BST054
F44BST055
F44BST056
F44BST057
F44BST058
F44BST059
F44BST060
F44BST061
F44BST062
F44BST063
F44BST064
F44BST065
F44BST066
F44BST067
F44BST068
F44BST069
F44BST070
F44BST071
F44BST072
F44BST073
F44BST074
F44BST075
F44BST076
F44BST077
F44BST078
F44BST079
F44BST080
F44BST081
F44BST082
F44BST083
F44BST084
F44BST085
F44BST086
F44BST087
F44BST088
F44BST089
F44BST090
F44BST091
F44BST092
F44BST093
F44BST094
F44BST095
F44BST096
F44BST097
F44BST098
F44BST099
F44BST100
F44BST101
F44BST102
F44BST103
F44BST104
F44BST105
F44BST106
F44BST107
F44BST108
F44BST109
F44BST110
F44BST111
F44BST112
F44BST113

```

Table VII-57 (contd)

```

6032 DO 603 I=1,NR,3
6031 DD 604 L=1,K
      K=K+1
      J=L/2
      IF (J-3) 6031,6032,6032
      J=0
      I1=1+J
604 MSET(K)=MSET(I1)
603 CONTINUE
      KR=K
      MR=0
      DU 605 I=1,KR,2
      I2=I+2
      IF (I2-KR) 6051,6051,605
6051 IF (MSET(I1)-MSET(I2)) 605,605,6052
6052 IJ=0
      DO 606 J=12,KR,2
      IF (MSET(I1)-MSET(I1+J)) 6061,6062,6061
6061 IF (MSET(I1)-MSET(I1+J)) 606,6063,606
6063 IF (MSET(I1+1)-MSET(I1)) 606,6064,606
6062 IF (MSET(I1+1)-MSET(I1+1)) 606,6064,606
6064 MSET(I1)=0
      MSET(I1+1)=0
      IJ=IJ+1
606 CONTINUE
      IF (IJ-1) 6053,605,44
6053 MRB=MR
      DO 6054 J=1,MRB
      IF (NBAN(J)-MSET(I1)) 6054,6055,6054
6054 CONTINUE
      MR=MR+1
      NBAN(MR)=MSET(I1)
6055 DO 6056 J=1,MRB
      IF (NBAN(J)-MSET(I1+1)) 6056,605,6056
6056 CONTINUE
      MR=MR+1
      NBAN(MR)=MSET(I1+1)
605 CONTINUE
      GO TO 6057
601 DO 40 I=1,NB
40 MSET(I)=MSET(I)
      MB=0
      DO 39 I=1,NB
      IF (MSET(I)) 39,39,42
42 NODE=MSET(I)
      KLIM=0
      DO 38 J=1,NB
      IF (NODE-MSET(J)) 38,37,38
37 MSET(I)=0
      KLIM=KLIM+1
38 CONTINUE
      IF (ILIM-2) 411,412,602
411 IF (KLIM-1) 44,43,44
412 IF (KLIM-2) 43,39,444
C MDRE: THAN 2 REPETITION IS POSSIBLE IF IGEN=1
444 IF (IGEN-1) 44,39,44
43 NB=NR-1
      NBAN(MR)=NODE
      GO TO 39
44 WRITE OUTPUT TAPE 6,96)+,ICN
961 FORMAT (15,15X,44HERROR IN MESH TOPOLOGY,NODE ASSUMED INTERNAL)
      GO TO 90
39 CONTINUE
8057 IF (MR) 90,90,45
45 GO TO (461,462,463),ILIM
      F4R0F114
      F4R0F115
      F4R0F116
      F4R0F117
      F4R0F118
      F4R0F119
      F4R0F120
      F4R0F121
      F4R0F122
      F4R0F123
      F4R0F124
      F4R0F125
      F4R0F126
      F4R0F127
      F4R0F128
      F4R0F129
      F4R0F130
      F4R0F131
      F4R0F132
      F4R0F133
      F4R0F134
      F4R0F135
      F4R0F136
      F4R0F137
      F4R0F138
      F4R0F139
      F4R0F140
      F4R0F141
      F4R0F142
      F4R0F143
      F4R0F144
      F4R0F145
      F4R0F146
      F4R0F147
      F4R0F148
      F4R0F149
      F4R0F150
      F4R0F151
      F4R0F152
      F4R0F153
      F4R0F154
      F4R0F155
      F4R0F156
      F4R0F157
      F4R0F158
      F4R0F159
      F4R0F160
      F4R0F161
      F4R0F162
      F4R0F163
      F4R0F164
      F4R0F165
      F4R0F166
      F4R0F167
      F4R0F168
      F4R0F169
      F4R0F170
      F4R0F171
      F4R0F172
      F4R0F173
      F4R0F174
      F4R0F175
      F4R0F176
      F4R0F177
      F4R0F178
461 NBAN(I)=0
      NBAN(2)=0
      IF (NB-1) 44,47,90
462 IF (NB-2) 448,47,448
C OTHER THAN 2 NEIGHBORING BOUNDARY NODES POSSIBLE IF IGEN=1
448 IF (IGEN-1) 44,40,44
463 IF (MR-3) 44,47,47
C THE NODE IS ON BOUNDARY
47 INRON=1
      EST=1H*
C ESTABLISH OUTER NORMAL ON RIR AND AREA ON ARE
      GO TO (48,49,50),ILIM
C ONE-DIMENSIONAL CONTINUUM, SHELL OF REVOLUTION
48 CALL INER(SIR)
      Q=-1
      CALL UNIT(BIR,0)
      ARE=0
      GO TO 90
C TWO-DIMENSIONAL CONTINUUM
49 CALL INER(SIR)
      K=NRAN(1)
      CALL FINDX(K,X)
      K=NRAN(2)
      CALL FINDX(K,Y)
      DO 491 I=1,3
491 RTAIL=K(I)-Y(I)
      ARE=L
      CALL UNIT(BIR,ARE)
      ARE=ARE/2
      Q=SCAL(BIR,SIR)
      DO 492 I=1,3
492 AIR(I)=SIR(I)-Q*IR(I)
      IF (SCAL(BIR,SIR)) 493,441,494
441 INRON=0
      GO TO 44
493 Q=1
      DO 10 495
494 Q=-1
495 CALL UNIT(BIR,0)
      GO TO 90
C THREE-DIMENSIONAL CONTINUUM
50 CALL INER(SIR)
      CALL BEST(BIR,NBAN,MR)
      IF (SCAL(BIR,SIR)) 501,441,502
501 Q=1
      GO TO 503
502 Q=-1
503 CALL UNIT(BIR,0)
      Q=0
      DO 504 I=1,MR
      K=NRAN(I)
      CALL FINDX(K,XF)
504 Q=Q*SORTF(1/XF(I)-XN(I))**2+(XF(2)-XN(2))**2+(XF(3)-XN(3))**2
      ARE=2.14159*(0.7/2.*ARE)**2
      IF (INP-2) 100,91,91
91 WRITE OUTPUT TAPE 6,92,ICN,AS1,MR,(NBAN(I),I=1,MR)
92 FORMAT (15,41,14X,21HBOUNDARY NODES FOLLOW,120/(20X,2015))
      WRITE OUTPUT TAPE 6,93,MR,(MSET(I),I=1,MR)
93 FORMAT (20X,18HNET ARRAY FOLLOWS,120/(20X,2015))
      WRITE OUTPUT TAPE 6,94,ARE,BIR(I),I=1,3)
94 FORMAT (20X,5HAREA=E15.5,5X,12HOUTER NORMAL,2X,3E15.6)
100 RETURN
      END
      F4R0F179
      F4R0F180
      F4R0F181
      F4R0F182
      F4R0F183
      F4R0F184
      F4R0F185
      F4R0F186
      F4R0F187
      F4R0F188
      F4R0F189
      F4R0F190
      F4R0F191
      F4R0F192
      F4R0F193
      F4R0F194
      F4R0F195
      F4R0F196
      F4R0F197
      F4R0F198
      F4R0F199
      F4R0F200
      F4R0F201
      F4R0F202
      F4R0F203
      F4R0F204
      F4R0F205
      F4R0F206
      F4R0F207
      F4R0F208
      F4R0F209
      F4R0F210
      F4R0F211
      F4R0F212
      F4R0F213
      F4R0F214
      F4R0F215
      F4R0F216
      F4R0F217
      F4R0F218
      F4R0F219
      F4R0F220
      F4R0F221
      F4R0F222
      F4R0F223
      F4R0F224
      F4R0F225
      F4R0F226
      F4R0F227
      F4R0F228
      F4R0F229
      F4R0F230
      F4R0F231
      F4R0F232
      F4R0F233
      F4R0F234
      F4R0F235
      F4R0F236
      F4R0F237
      F4R0F238
      F4R0F239
      F4R0F240
      F4R0F241
      F4R0F242

```

Table VII-58. Source program listing of subroutine CAS4 (Link 4)

```

* LABEL
DE+CAS4 F4CAS400
C SUBROUTINE CAS4 F4CAS401
  DUMMY SUBROUTINE F4CAS402
  RETURN F4CAS403
  END F4CAS404

```

Table VII-59. Source program listing of subroutine CODI (Link 4)

Table VII-60. Source program listing of subroutine DIMI (Link 4)

```

*      LAREL
CE4CUD
SUBROUTINE CODI
  TO GENERATE LOCAL-OVERALL COORDINATE TRANSFORMATION MATRIX
  DIMENSION IA(11),AA(1),S(1),N(8),D21(21),D33(3,3),E27(3,3)
  1,P(24),UV(24),X(8),Y(8),Z(8),XD(7),YD(7),ZD(7),G(11)
  COMMON IA,AA
  EQUIVALENCE(IA,AA), (D21,D33), (D21(10),E27), (D21(19),E1), (D21(20),G)
  EQUIVALENCE(IA(1),IN), (IA(2),IN), (IA(3),IT), (IA(4),IP), (IA(5),
  1PR(S), (IA(6),ITYPE), (IA(7),IMAT), (IA(8),IDEG), (IA(9),INX), (IA(10),
  2IMF(1), (IA(11),IB), (IA(12),IMNX), (IA(13),IMY), (IA(14),IMZ), (IA(15),
  3IMF(1), (IA(16),IARE), (IA(17),N(1)), (IA(18),M), (IA(19),IT), (IA(20),
  4ISTR), (IA(21),IELT), (IA(22),ITEM), (IA(23),ITIC), (IA(24),IMET),
  5(IA(25),ISUM), (IA(26),IND), (IA(27),IMS), (IA(28),IOS), (IA(29),
  6IORD), (IA(30),IORD1), (IA(31),ACEL), (IA(32),J1), (IA(33),J2),
  7(IA(34),J3), (IA(35),J4), (IA(36),J5), (IA(37),J6), (IA(38),J7), (IA(39),
  8J8), (IA(40),J9), (IA(41),IRB), (IA(42),IR0), (IA(43),IR1), (IA(44),
  9(IA), (IA(45),IDT), (IA(46),IDY), (IA(47),IF), (IA(48),ITAP),
  10(IA(49),ICAR), (IA(50),ICX), (IA(51),ICY), (IA(52),
  11CIZ), (IA(53),ICF1), (IA(54),ICX1), (IA(55),ICY1), (IA(56),
  12(IA(57),ICF), (IA(58),IDF), (IA(59),IST), (IA(60),
  13(IA(61),IGEM), (IA(62),IERR), (IA(63),OT), (IA(64),OG),
  14(IA(65),AL1), (IA(66),AL2), (IA(67),AL3), (IA(68),D21), (IA(69),P),
  15(IA(70),UV), (IA(71),X), (IA(72),Y), (IA(73),Z), (IA(74),XD),
  16(IA(75),YD), (IA(76),ZD), (IA(77),S), (IA(78),M), (IA(79),
  17(IA(80),IPB), (IA(81),IPG), (IA(82),IPN), (IA(83),CONS), (IA(84),
  18(IA(85),G1), (IA(86),G2), (IA(87),G3)
  EQUIVALENCE(IA(349),N(1)), (IA(348),ISD1), (IA(347),ISD2), (IA(346),
  1,ISD3), (IA(345),J9), (IA(344),J10), (IA(343),JPRS), (IA(342),JSDY),
  2,IA(341),JSDZ), (IA(340),JARE), (IA(339),JMMX), (IA(338),JMMY),
  3,IA(337),JMMZ), (IA(336),JMF1), (IA(335),ITAS1), (IA(334),IDZ),
  4,IA(333),IPR), (IA(332),DGV), (IA(331),NG2), (IA(330),PRFS),
  5(IA(329),IPR)
  DIMENSION A16(6),DIR(3,3),UV(12),T1(6),PD(3),PN(3),DUG(3)
  EQUIVALENCE(AA(200),A), (AA(236),FL), (AA(237),AREA), (AA(238),I)
  1, (AA(239),J), (AA(240),IR), (AA(241),JR), (AA(242),NY), (AA(243),DIR)
  2, (AA(306),UVG), (AA(291),PD), (AA(294),PN), (AA(297),DUG), (AA(300),
  EL=SQRT(FX(1)*XD(1)+YD(1)+ZD(1)+ZD(1))
  IF (IELT-3) 135,250,115
  110 IF (IELT-3) 135,250,115
  115 DIR(1,1)=XD(1)/EL
  DIR(1,2)=YD(1)/EL
  DIR(1,3)=ZD(1)/EL
  IF (JMF1) 1010,210,130
  210 IF (IGEM) 1010,220,1010
  130 ICFJ=ICF+JMF1
  IF (ABS(F(AA(1CFJ)))>.90) 140,140,1010
  140 FI=AA(1CFJ)*3.1415926/180.
  IF (FI) 144,144,146
  144 SIGNF=-1.
  GO TO 148
  146 SIGNF=1.
  148 IF (ABS(F(DIR(1,1)))>.1E-3) 150,150,160
  150 IF (ABS(F(DIR(1,3)))>.1E-3) 140,140,170
  160 DIR(2,2)=COS(F)
  ASO=DIR(1,1)*DIR(1,1)
  AX=-.4*DIR(1,3)*DIR(1,3)/ASO
  BX=DIR(1,2)*DIR(1,3)*DIR(1,2)/ASO
  CX=DIR(2,2)*DIR(1,2)*DIR(1,2)+DIR(1,2)*DIR(1,2)*DIR(1,2)/ASO-.
  DIR(2,3)=(-BX+SIGNF*SQRT(FX*AX-AX*CX))/AX
  165 DIR(2,1)=(-DIR(1,2)*DIR(1,2)+DIR(1,3)*DIR(1,3))/DIR(1,1)
  GO TO 190
  170 DIR(2,2)=COS(F)
  DIR(2,3)=-DIR(1,2)*DIR(1,2)/DIR(1,3)
  DIR(2,1)=SIGNF*SQRT(F1-DIR(2,2)*DIR(1,2)-DIR(1,3)*DIR(1,3))
  GO TO 190
  180 DIR(2,3)=COS(F)
  DIR(2,2)=0.
  DIR(2,1)=SIGNF*SQRT(F1-DIR(2,3)*DIR(1,2,3))
  DIR(3,1)=DIR(1,2)*DIR(1,2)+DIR(1,3)*DIR(1,3)
  DIR(3,2)=-DIR(1,1)*DIR(1,2)-DIR(1,2)*DIR(1,2)
  GO TO 1000
  220 DIR(2,1)=-DIR(1,2)
  DIR(2,2)=DIR(1,3)
  DIR(2,3)=0.
  DIR(3,1)=0.
  DIR(3,2)=0.
  DIR(3,3)=1.
  GO TO 1000
  250 DIR(1,1)=1.
  DIR(1,2)=0.
  DIR(1,3)=0.
  DIR(2,1)=0.
  DIR(2,2)=0.
  DIR(2,3)=XD(1)/EL
  DIR(3,1)=0.
  DIR(3,2)=YD(1)/EL
  DIR(3,3)=ZD(1)/EL
  DIR(3,1)=DIR(1,2,3)
  DIR(3,2)=DIR(1,2,3)
  1000 RETURN
  1010 IERR=1
  GO TO 1000
  END

```

```

*      LABEL
CE4DIM
SUBROUTINE DIMI(K)
  TO GENERATE AND OUTPUT STRESSES OF ONE-DIMENSIONAL ELEMENTS
  DIMENSION IA(11),AA(1),S(1),N(8),D21(21),D33(3,3),E27(3,3)
  1,P(24),UV(24),X(8),Y(8),Z(8),XD(7),YD(7),ZD(7),G(11)
  COMMON IA,AA
  EQUIVALENCE(IA,AA), (D21,D33), (D21(10),E27), (D21(19),E1), (D21(20),G)
  EQUIVALENCE(IA(1),IN), (IA(2),IN), (IA(3),IT), (IA(4),IP), (IA(5),
  1PR(S), (IA(6),ITYPE), (IA(7),IMAT), (IA(8),IDEG), (IA(9),INX), (IA(10),
  2IMF(1), (IA(11),IB), (IA(12),IMNX), (IA(13),IMY), (IA(14),IMZ), (IA(15),
  3IMF(1), (IA(16),IARE), (IA(17),N(1)), (IA(18),M), (IA(19),IT), (IA(20),
  4ISTR), (IA(21),IELT), (IA(22),ITEM), (IA(23),ITIC), (IA(24),IMET),
  5(IA(25),ISUM), (IA(26),IND), (IA(27),IMS), (IA(28),IOS), (IA(29),
  6IORD), (IA(30),IORD1), (IA(31),ACEL), (IA(32),J1), (IA(33),J2),
  7(IA(34),J3), (IA(35),J4), (IA(36),J5), (IA(37),J6), (IA(38),J7), (IA(39),
  8J8), (IA(40),J9), (IA(41),IRB), (IA(42),IR0), (IA(43),IR1), (IA(44),
  9(IA), (IA(45),IDT), (IA(46),IDY), (IA(47),IF), (IA(48),ITAP),
  10(IA(49),ICAR), (IA(50),ICX), (IA(51),ICY), (IA(52),
  11CIZ), (IA(53),ICF1), (IA(54),ICX1), (IA(55),ICY1), (IA(56),
  12(IA(57),ICF), (IA(58),IDF), (IA(59),IST), (IA(60),
  13(IA(61),IGEM), (IA(62),IERR), (IA(63),OT), (IA(64),OG),
  14(IA(65),AL1), (IA(66),AL2), (IA(67),AL3), (IA(68),D21), (IA(69),P),
  15(IA(70),UV), (IA(71),X), (IA(72),Y), (IA(73),Z), (IA(74),XD),
  16(IA(75),YD), (IA(76),ZD), (IA(77),S), (IA(78),M), (IA(79),
  17(IA(80),IPB), (IA(81),IPG), (IA(82),IPN), (IA(83),CONS), (IA(84),
  18(IA(85),G1), (IA(86),G2), (IA(87),G3)
  EQUIVALENCE(IA(349),N(1)), (IA(348),ISD1), (IA(347),ISD2), (IA(346),
  1,ISD3), (IA(345),J9), (IA(344),J10), (IA(343),JPRS), (IA(342),JSDY),
  2,IA(341),JSDZ), (IA(340),JARE), (IA(339),JMMX), (IA(338),JMMY),
  3,IA(337),JMMZ), (IA(336),JMF1), (IA(335),ITAS1), (IA(334),IDZ),
  4,IA(333),IPR), (IA(332),DGV), (IA(331),NG2), (IA(330),PRFS),
  5(IA(329),IPR)
  DIMENSION VFC(12),PV(6,2),DIR(3,3),DUM(12),PT(24)
  EQUIVALENCE(AA(200),VFC), (AA(212),PV), (AA(224),DUM), (AA(236),EL)
  1, (AA(264),PT), (AA(273),PT)
  C COMPUTE STRESSES AT THE NODES OF ONE DIMENSIONAL ELEMENT
  WRITE OUTPUT TAPE 6
  1 FORMAT (I1H,29X,STRESS AND MOMENT RESULTANTS AT THE NODES OF ONE-DI-
  MENSIONAL ELEMENTS/30X,70HQUANTITIES ARE IN THE LOCAL COORDINATE SY-
  2TE SYSTEMS AT THE ENDS OF ELEMENTS/18H EL NO. NODE TYPE PV,9X,3HM-FOR-
  3MIND PTAS
  IERR=0
  JDS=2*IDFG
  ZGEM=IGEM
  DO 1000 M=1,I
  102 READ TAPE 1TAS,X,ITTT,ITTM,NAV,IMV,IDS,IDSZ,IN(1)=1,IMS,(S(1),
  IF=-1,IDSZ,PT(1),PT(1),PT(1),PT(1),IDS)
  IF (ITTT-PTM) 104,104,105
  105 IF (NAV-1) 106,102,106
  106 IF (IMV-M) 1100,111,1100
  111 JIM=J1+M
  IFLT=IA(JIM)/10
  IF (IELT-4) 110,111,1000
  110 DO 200 I=1,IMS
  J=1
  IXXJ=IXX+J
  IYYJ=IYY+J
  IZZJ=IZZ+J
  X(I)=AA(IXXJ)
  Y(I)=AA(IYYJ)
  Z(I)=AA(IZZJ)+ZGEM
  IF (I=1) 200,120,120
  120 KDI=1+X(I)-X(1)
  YDI=1+Y(I)-Y(1)
  ZDI=1+Z(I)-Z(1)
  200 CONTINUE
  CALL CODI
  DO 250 I=1,200,255
  250 A(1)=0
  DO 300 J=1,3
  DO 300 J=1,3
  DIRT=DIR(I,J)
  DIRJ=DIR(J,I)
  300 CONTINUE
  CALL STRA
  IDFFM=IDEF-IDEG
  LV=0
  DO 370 I=1,INEG
  IDFFI=IDFFM+I
  DO 360 J=1,IMS
  IDFFJ=IDFFI+IDEG*(N(J)
  LV=LV+1
  VDE(LV)=AA(IDFFJ)
  360 CONTINUE
  370 CONTINUE
  CALL TRAN(VDF,?)
  JI=-IDS
  DO 415 J=1,IDS
  DO 410 J=1,IDS
  JI=JI+J
  DUM(I)=DUM(I)+S(JI)*VDE(I,J)
  410 CONTINUE
  415 CONTINUE
  CALL TRAN(P,0)
  L=0
  DO 418 I=1,6
  DO 417 J=1,2
  L=L+1
  PVI+J=DUM(L)-P(L)
  417 CONTINUE
  418 CONTINUE
  IF (IELT-2) 500,420,430
  420 PVI(6,1)=PVI(3,1)
  PVI(6,2)=PVI(3,2)
  PVI(3,1)=0.
  PVI(3,2)=0.
  GO TO 500
  430 IF (IELT-3) 500,440,500
  440 DO 450 J=1,2
  DO 450 J=1,3
  IM=6-I

```

Table VII-60 (contd)

```

JM4=JM-4
PV(IM,J)=PV(IM4,J)
PV(IM4,J)=0.
450 CONTINUE
500 WRITE OUTPUT TAPE 6,3
3 FORMAT (1H )
DO 510 J=1,6
510 PV(I,J)=-PVT(I,J)
WRITE OUTPUT TAPE 6,2,(M,N(I),TFLT,(PV(J,I),J=1,6),I=1,2)
2 FORMAT (1X,14,216,3X,6E15,5)
1000 CONTINUE
1010 RETURN
1100 IERR=1
K=M
IA(201)=MM
GO TO 1010
END

```

```

E401M114
E401M115
E401M116
E401M117
E401M118
E401M119
E401M120
E401M121
E401M122
E401M123
E401M124
E401M125
E401M126
E401M127
E401M128
E401M129
E401M130

```

Table VII-61. Source program listing of subroutine DINA (Link 4)

```

* LABEL
CE4DIN SURROUTINE DINA
C OBTAINS LOCAL COORDINATE AXES AT A NODE IN SHELLS
C TO GENERATE BAS VECIDR, DIN MATRIX AND ANGLE
C DIMENSION IA(1),AA(1),S(1),N(1),O21(21),O33(3,3),E22(3,3)
1,P(24),UV(24),X(8),Y(8),Z(8),XD(7),YD(7),ZD(7),G(11)
COMMON IA,AA
EQUIVALENCE (IA,AA), (O21,O33), (O21(10),E22), (O21(19),E), (O21(20),G)
EQUIVALENCE (IA(1),IN), (IA(2),IBN), (IA(3),IT), (IA(4),IP), (IA(5),
1)PRS), (IA(6),ITYPE), (IA(7),IMAT), (IA(8),IDEC), (IA(9),INXI), (IA(10),E401N007
EQUIVALENCE (IA(11),I8), (IA(12),IMX), (IA(13),IMY), (IA(14),IMZ), (IA(15),E401N009
2)H), (IA(16),IARF), (IA(17),M(11)), (IA(25),M), (IA(26),ITY), (IA(27),E401N010
3)MFI), (IA(28),IELT), (IA(29),ITEM), (IA(30),ITC), (IA(31),IME7),
4)STR), (IA(32),ISUM), (IA(33),IND), (IA(36),IMS), (IA(36),IUS), (IA(37),
5)IA(32),ISUM), (IA(33),IND), (IA(36),IMS), (IA(36),IUS), (IA(37),
6)ORD), (IA(38),IORD), (IA(39),ACFL), (IA(50),JL), (IA(51),J2),
7)IA(52),J3), (IA(53),J4), (IA(54),J5), (IA(55),J6), (IA(56),J7), (IA(57),E401N015
8)JRI), (IA(58),JTY), (IA(59),IBO), (IA(60),IBO), (IA(61),ID), (IA(62),E401N016
9)IA), (IA(63),IDT), (IA(64),IDY), (IA(65),ITF), (IA(41),ITAP)
EQUIVALENCE (IA(66),ICAR), (IA(67),ICIX), (IA(68),ICIV), (IA(69),
1)CIZ), (IA(70),ICFI), (IA(71),ICX), (IA(72),IY), (IA(73),I22),
2)IA(74),IC), (IA(75),IDF), (IA(76),IST), (IA(77),IIS)
3), (IA(78),IGEM), (IA(79),IERR), (AA(80),IF), (AA(81),DT), (AA(82),DG),
4)AA(83),ALI), (AA(84),AL2), (AA(85),M3), (AA(86),O21), (AA(107),P),
5)AA(131),UV), (AA(155),X), (AA(163),Y), (AA(171),Z), (AA(179),XD),
6)AA(186),YD), (AA(193),ZD), (AA(351),S), (AA(40),ZREM)
7), (AA(42),INP), (AA(43),IPBG), (AA(44),IPEN), (AA(45),CONS), (AA(46),I)
8), (AA(47),G1), (AA(48),G2), (AA(49),G3)
EQUIVALENCE (IA(349),NTIC), (IA(348),ISDT), (IA(347),ISHY), (IA(346)
1),ISDZ), (IA(345),J9), (IA(344),J10), (IA(343),JPRS), (IA(342),JSOY)
2), (IA(341),JSOZ), (IA(340),JARE), (IA(339),JMX), (IA(338),JMY)
3), (IA(337),JMNZ), (IA(336),JMF), (IA(335),IAS), (IA(334),IDZ)
4), (IA(333),IPR), (AA(332),DGY), (AA(331),DGZ), (AA(330),PRFS)
5), (IA(329),IPR)
DIMENSION BIR(3),SIR(3),DIM(3,3),SR(6),XM(3),XF(3),DN(6),OF(6),
1)RES(6),RE(6),BAS(3),ICLAS(4),NRAN(10),N(13),NFS(3)
EQUIVALENCE (AA(200),JONE), (AA(201),ICN), (AA(202),LMI), (AA(203),AST)
1), (AA(204),JNBON), (AA(205),ARE), (AA(206),ICLA), (AA(207),IMFL),
2)AA(208),INI), (AA(209),IC), (AA(210),ICUN), (AA(211),ANGLE), (AA(212),
3)ICAS), (AA(213),IE), (AA(214),NRI), (AA(215),MB)
4), (AA(216),IROT), (AA(217),RST)
EQUIVALENCE (AA(220),BR), (AA(223),SIR), (AA(226),DIM), (AA(235),SR)
1), (AA(241),XN), (AA(244),XF), (AA(247),ON), (AA(253),OF), (AA(259),RES)
2), (AA(265),RED), (AA(271),BAS), (AA(274),ICLAS), (AA(278),NRAN)
3), (AA(292),NII), (AA(295),NES)
DIMENSION NEL(20,17),MAC(4,4,20),TWR(90),MD(6,6),A(90,7),R(8,8),
1)C(8,2),FF(1),MSET(100),MSET(100),M(3,3)
EQUIVALENCE (AA(1400),FF), (M(11),JP1), (M(2),JM1), (M(11),J1)
EQUIVALENCE (FF(1),NEL), (FF(341),MAC), (FF(661),ING), (FF(751),DD)
1)FF(787),A), (FF(1417),B), (FF(1481),C), (FF(1497),MSET), (FF(1597),
2)MSET), (FF(1697),W)
C SEE IF DIN AND ANGLE ARE TO BE OBTAINED VIA SUBROUTINE AGLF
IF (IPTR-1) 3,3,4
C CALL SUBROUTINE AGLF FOR DIN AND ANGLE
CALL AGLF
GO TO 5
C IS IT SHELL OF REVOLUTION
IF (ICAS-6) 20,20,21
C SHELL OF REVOLUTION
CALL REVU
GO TO 5
C GENERAL SHELL. DETERMINE DIN AND ANGLE BY BEST FIT QUADRATIC
CALL QUAD
IF (INP-2) 7,6,6
6 WRITE OUTPUT TAPE 6,61,ANGLE, ((DIN(I,J),I=1,3),J=1,3)
6) FORMAT(20X
,5HANGLE,2X,F10,3/
120X,3HDIN,5X,3HMS1,2X,3F7,4,5X,3HETA,2X,3F7,4,5X,4HZETA,1X,3F7,4)
RETURN
7) END

```


Table VII-63. Source program listing of subroutine FINDQ (Link 4)

```

* LABEL
CE4FNQ SUBROUTINE FINDQ(K,0)
C OBTAINS DEFLECTIONS OF A NODE IN OVERALL COORDINATES
C TO GENERATE THE DEFLECTIONS OF NODE K ON VECTOR 0
DIMENSION IA(1),AA(2),S(1),N(8),D2(12),D3(3,3),E22(3,3)
1,P(24),UV(24),X(8),Y(8),Z(8),XD(7),YD(7),ZD(7),G(11)
COMMON IA,AA
EQUIVALENCE (IA,AA), (D2,D3), (D2(10),E22), (D2(19),E1), (D2(20),G)
EQUIVALENCE (IA(1),IN), (IA(2),IBN), (IA(3),IT), (IA(4),IP), (IA(5),
1)PRS), (IA(6),ITYPE), (IA(7),IMAI), (IA(8),IDEG), (IA(9),INX), (IA(10),
2)M), (IA(11),IB), (IA(12),IMMX), (IA(13),IMY), (IA(14),IMZ), (IA(15),
3)MF1), (IA(16),IARE), (IA(17),NI1), (IA(18),M), (IA(19),IT), (IA(20),
4)STR), (IA(21),IELT), (IA(22),ITEM), (IA(23),ITIC), (IA(24),IMET),
5)IA(25),ISUM), (IA(26),IND), (IA(27),AGEL), (IA(28),J1), (IA(29),
6)J2), (IA(30),IORD1), (IA(31),IORD2), (IA(32),IORD3), (IA(33),IORD4),
7)J3), (IA(34),J4), (IA(35),J5), (IA(36),J6), (IA(37),J7), (IA(38),
8)J8), (IA(39),J9), (IA(40),J10), (IA(41),J11), (IA(42),J12),
9)IA(43),IA(44),IA(45),IA(46),IA(47),IA(48),IA(49),IA(50),IA(51),IA(52),
EQUIVALENCE (IA(66),ICAR), (IA(67),ICIX), (IA(68),ICY), (IA(69),
1)ICIZ), (IA(70),ICF), (IA(71),IX), (IA(72),IY), (IA(73),IZ),
2)IA(74),IIG), (IA(75),IDEF), (IA(76),IST), (IA(77),IIS),
3)IA(78),IGEM), (IA(79),IERR), (IA(80),TE), (IA(81),DT), (IA(82),DG),
4)AA(83),AL1), (AA(84),AL2), (AA(85),AL3), (AA(86),D21), (AA(87),P),
5)AA(88),UV), (AA(89),X), (AA(90),Y), (AA(91),Z), (AA(92),XD),
6)AA(93),YD), (AA(94),ZD), (AA(95),S), (AA(96),ZGEM)
7)IA(97),INP), (AA(98),IPRR), (AA(99),IPRN), (AA(100),CONS), (AA(101),
8)IA(102),G1), (AA(103),G2), (AA(104),G3)
EQUIVALENCE (IA(349),NTIC), (IA(348),ISD1), (IA(347),ISD2), (IA(346)
1)ISD3), (IA(345),J91), (IA(344),J10), (IA(343),JPHS1), (IA(342),JSDY)
2)IA(341),JSDZ), (IA(340),JARE), (IA(339),JMMX), (IA(338),JMMY)
3)IA(337),JMMZ), (IA(336),JMF1), (IA(335),ITAS), (IA(334),IDZ)
4)IA(333),IPR), (AA(332),DGY), (AA(331),DG1), (AA(330),PRES)
5)IA(329),IPR)
DIMENSION BIR(3),SIR(3),DIN(3,3),SR(6),XN(3),XF(3),ON(6),OF(6),
1)RES(6),RED(6),BAS(3),ICLAS(4),NRAN(10),NU(3),NES(3)
EQUIVALENCE (AA(200),IDNE), (AA(201),ICN), (AA(202),LM), (AA(203),ASTE)
1), (AA(204),INBDN), (AA(205),ARE), (AA(206),ICLA), (AA(207),IMF1),
2)AA(209),IM), (AA(209),IC), (AA(210),ICDN), (AA(211),ANGLE), (AA(212),
3)ICAST), (AA(213),IE), (AA(214),NR), (AA(215),MB)
4)IA(216),IRH), (AA(217),BST)
EQUIVALENCE (AA(220),BIR), (AA(223),SIR), (AA(226),DIN), (AA(235),SR)
1)AA(241),XN), (AA(244),XF), (AA(247),ON), (AA(253),OF), (AA(259),RES)
2)AA(265),RED), (AA(271),BAS), (AA(274),ICLAS), (AA(278),NRAN)
3)AA(292),NU), (AA(295),NES)
DIMENSION NEL(20,17),MAC(4,4,20),IMG(90),DD(6,6),A(90,7),R(6,8),
1)C(8,2),FF(1),NSFT(100),MSFT(100),W(3,3)
EQUIVALENCE (AA(14000),FF), (MU(1),JPI), (MU(2),JMI), (MU(3),JSJ)
EQUIVALENCE (FF(1),NEL), (FF(341),MAC), (FF(1661),IMG), (FF(1751),DD),
1)FF(1787),A), (FF(1417),B), (FF(1481),C), (FF(1497),NSET), (FF(1597),
2)MSFT), (FF(1697),N)
DIMENSION O(16)
IDEF1=IDFF+K-1)*IDEG
DD LO I=1,IDEG
IDEF1=IDFF+I
O(1)=AA(1)DEF1
CONTINUE
RETURN
END

```

Table VII-64. Source program listing of subroutine FINDX (Link 4)

```

* LABEL
CE4FNX SUBROUTINE FINDX(K,0)
C OBTAINS OVERALL COORDINATES OF A NODE
C TO GENERATE THE COORDINATES OF NODE K ON VECTOR 0
DIMENSION IA(1),AA(1),S(1),N(8),D2(12),D3(3,3),E22(3,3)
1,P(24),UV(24),X(8),Y(8),Z(8),XD(7),YD(7),ZD(7),G(11)
COMMON IA,AA
EQUIVALENCE (IA,AA), (D2,D3), (D2(10),E22), (D2(19),E1), (D2(20),G)
EQUIVALENCE (IA(1),IN), (IA(2),IBN), (IA(3),IT), (IA(4),IP), (IA(5),
1)PRS), (IA(6),ITYPE), (IA(7),IMAI), (IA(8),IDEG), (IA(9),INX), (IA(10),
2)M), (IA(11),IB), (IA(12),IMMX), (IA(13),IMY), (IA(14),IMZ), (IA(15),
3)MF1), (IA(16),IARE), (IA(17),NI1), (IA(18),M), (IA(19),IT), (IA(20),
4)STR), (IA(21),IELT), (IA(22),ITEM), (IA(23),ITIC), (IA(24),IMET),
5)IA(25),ISUM), (IA(26),IND), (IA(27),AGEL), (IA(28),J1), (IA(29),
6)J2), (IA(30),IORD1), (IA(31),IORD2), (IA(32),IORD3), (IA(33),IORD4),
7)J3), (IA(34),J4), (IA(35),J5), (IA(36),J6), (IA(37),J7), (IA(38),
8)J8), (IA(39),J9), (IA(40),J10), (IA(41),J11), (IA(42),J12),
9)IA(43),IA(44),IA(45),IA(46),IA(47),IA(48),IA(49),IA(50),IA(51),IA(52),
EQUIVALENCE (IA(66),ICAR), (IA(67),ICIX), (IA(68),ICY), (IA(69),
1)ICIZ), (IA(70),ICF), (IA(71),IX), (IA(72),IY), (IA(73),IZ),
2)IA(74),IIG), (IA(75),IDEF), (IA(76),IST), (IA(77),IIS),
3)IA(78),IGEM), (IA(79),IERR), (IA(80),TE), (IA(81),DT), (IA(82),DG),
4)AA(83),AL1), (AA(84),AL2), (AA(85),AL3), (AA(86),D21), (AA(87),P),
5)AA(88),UV), (AA(89),X), (AA(90),Y), (AA(91),Z), (AA(92),XD),
6)AA(93),YD), (AA(94),ZD), (AA(95),S), (AA(96),ZGEM)
7)IA(97),INP), (AA(98),IPRR), (AA(99),IPRN), (AA(100),CONS), (AA(101),
8)IA(102),G1), (AA(103),G2), (AA(104),G3)
EQUIVALENCE (IA(349),NTIC), (IA(348),ISD1), (IA(347),ISD2), (IA(346)
1)ISD3), (IA(345),J91), (IA(344),J10), (IA(343),JPHS1), (IA(342),JSDY)
2)IA(341),JSDZ), (IA(340),JARE), (IA(339),JMMX), (IA(338),JMMY)
3)IA(337),JMMZ), (IA(336),JMF1), (IA(335),ITAS), (IA(334),IDZ)
4)IA(333),IPR), (AA(332),DGY), (AA(331),DG1), (AA(330),PRES)
5)IA(329),IPR)
DIMENSION BIR(3),SIR(3),DIN(3,3),SR(6),XN(3),XF(3),ON(6),OF(6),
1)RES(6),RED(6),BAS(3),ICLAS(4),NRAN(10),NU(3),NES(3)
EQUIVALENCE (AA(200),IDNE), (AA(201),ICN), (AA(202),LM), (AA(203),ASTE)
1), (AA(204),INBDN), (AA(205),ARE), (AA(206),ICLA), (AA(207),IMF1),
2)AA(209),IM), (AA(209),IC), (AA(210),ICDN), (AA(211),ANGLE), (AA(212),
3)ICAST), (AA(213),IE), (AA(214),NR), (AA(215),MB)
4)IA(216),IRH), (AA(217),BST)
EQUIVALENCE (AA(220),BIR), (AA(223),SIR), (AA(226),DIN), (AA(235),SR)
1)AA(241),XN), (AA(244),XF), (AA(247),ON), (AA(253),OF), (AA(259),RES)
2)AA(265),RED), (AA(271),BAS), (AA(274),ICLAS), (AA(278),NRAN)
3)AA(292),NU), (AA(295),NES)
DIMENSION NEL(20,17),MAC(4,4,20),IMG(90),DD(6,6),A(90,7),R(6,8),
1)C(8,2),FF(1),NSFT(100),MSFT(100),W(3,3)
EQUIVALENCE (AA(14000),FF), (MU(1),JPI), (MU(2),JMI), (MU(3),JSJ)
EQUIVALENCE (FF(1),NEL), (FF(341),MAC), (FF(1661),IMG), (FF(1751),DD),
1)FF(1787),A), (FF(1417),B), (FF(1481),C), (FF(1497),NSET), (FF(1597),
2)MSFT), (FF(1697),N)
DIMENSION O(16)
IDEF1=IDFF+K-1)*IDEG
DD LO I=1,IDEG
IDEF1=IDFF+I
O(1)=AA(1)DEF1
CONTINUE
RETURN
END

```


Table VII-67. Source program listing of subroutine INLZ (Link 4)

```

* LABEL
CE+INZ SUBROUTINE INLZ E4INZ000
C INITIALIZES SCALARS, VECTORS AND MATRICES AT A NODE E4INZ001
C TO INITIALIZE ICON,ANGLE,BAS,DIN,N,IRROT,BST,TE,DT,DF,AND NFS E4INZ002
DIMENSION I(41),AA(1),S(1),N(8),D2(21),D3(2,3),E2(3,3) E4INZ003
1,P(24),UV(24),X(8),Y(8),Z(8),XDI(7),YDI(7),ZD(7),GL(1) E4INZ004
COMMON IA,AA E4INZ005
EQUIVALENCE IA,AA,(D2,D3),(D2(10),F22),(D2(19),F),(D2(20),G) E4INZ006
EQUIVALENCE I(41),IN,(I(42),IBN),(I(43),IT),(I(44),IP),(I(45), E4INZ007
1PRS),(I(46),ITYPE),(I(47),IMAT),(I(48),IDEG),(I(49),INX),(I(410), E4INZ008
21HI),(I(411),IR),(I(412),IMX),(I(413),IMY),(I(414),IMZ),(I(415), E4INZ009
3INF),(I(416),IARE),(I(417),N(11),(I(418),M),(I(419),ITV),(I(420), E4INZ010
4ISTR),(I(421),IELT),(I(422),ITEM),(I(423),ITIG),(I(424),IMET), E4INZ011
5I(I(425),ISUM),(I(426),IND),(I(427),IMS),(I(428),IOS),(I(429), E4INZ012
6IORD),(I(430),IORD1),(I(431),JCEL),(I(432),J1),(I(433),J2), E4INZ013
7(I(434),J3),(I(435),J4),(I(436),J5),(I(437),J6),(I(438),J7),(I(439), E4INZ014
8),J8),(I(440),J9),(I(441),J10),(I(442),J11),(I(443),J12),(I(444), E4INZ015
9I(A),(I(445),IDT),(I(446),IDY),(I(447),ITE),(I(448),ITAP) E4INZ016
EQUIVALENCE I(449),ICAR,(I(450),ICIX),(I(451),ICLY),(I(452), E4INZ017
IICIZ),(I(453),ICF),(I(454),IX),(I(455),IYY),(I(456),IZ) E4INZ018
2(I(457),IIC),(I(458),IDEP),(I(459),ISJ),(I(460),ISJ) E4INZ019
3,(I(461),IGEM),(I(462),IGEM),(I(463),IGEM),(I(464),IGEM),(I(465),IGEM) E4INZ020
4(AA(83),AL1),(AA(84),AL2),(AA(85),AL3),(AA(86),AL4),(AA(87),AL5) E4INZ021
5(AA(88),UV),(AA(89),X),(AA(90),Y),(AA(91),Z),(AA(92),XD) E4INZ022
6(AA(93),YD),(AA(94),ZD),(AA(95),S),(AA(96),7GH) E4INZ023
7,(AA(97),INP),(AA(98),IPBG),(AA(99),IPFN),(AA(100),COMS),AA(101), E4INZ024
8),(AA(102),G1),(AA(103),G2),(AA(104),G3) E4INZ025
EQUIVALENCE I(466),RTIC,(I(467),ISOT),(I(468),ISOT),(I(469),ISOT) E4INZ026
1,(I(470),JSDZ),(I(471),JSDZ),(I(472),JSDZ),(I(473),JSDZ) E4INZ027
2,(I(474),JSDZ),(I(475),JSDZ),(I(476),JSDZ),(I(477),JSDZ) E4INZ028
3,(I(478),JSDZ),(I(479),JSDZ),(I(480),JSDZ),(I(481),JSDZ) E4INZ029
4,(I(482),JSDZ),(I(483),JSDZ),(I(484),JSDZ),(I(485),JSDZ) E4INZ030
5,(I(486),JSDZ),(I(487),JSDZ),(I(488),JSDZ),(I(489),JSDZ) E4INZ031
6,(I(490),JSDZ),(I(491),JSDZ),(I(492),JSDZ),(I(493),JSDZ) E4INZ032
7,(I(494),JSDZ),(I(495),JSDZ),(I(496),JSDZ),(I(497),JSDZ) E4INZ033
8,(I(498),JSDZ),(I(499),JSDZ),(I(500),JSDZ),(I(501),JSDZ) E4INZ034
9,(I(502),JSDZ),(I(503),JSDZ),(I(504),JSDZ),(I(505),JSDZ) E4INZ035
10,(I(506),JSDZ),(I(507),JSDZ),(I(508),JSDZ),(I(509),JSDZ) E4INZ036
11,(I(510),JSDZ),(I(511),JSDZ),(I(512),JSDZ),(I(513),JSDZ) E4INZ037
12,(I(514),JSDZ),(I(515),JSDZ),(I(516),JSDZ),(I(517),JSDZ) E4INZ038
13,(I(518),JSDZ),(I(519),JSDZ),(I(520),JSDZ),(I(521),JSDZ) E4INZ039
14,(I(522),JSDZ),(I(523),JSDZ),(I(524),JSDZ),(I(525),JSDZ) E4INZ040
15,(I(526),JSDZ),(I(527),JSDZ),(I(528),JSDZ),(I(529),JSDZ) E4INZ041
16,(I(530),JSDZ),(I(531),JSDZ),(I(532),JSDZ),(I(533),JSDZ) E4INZ042
17,(I(534),JSDZ),(I(535),JSDZ),(I(536),JSDZ),(I(537),JSDZ) E4INZ043
18,(I(538),JSDZ),(I(539),JSDZ),(I(540),JSDZ),(I(541),JSDZ) E4INZ044
19,(I(542),JSDZ),(I(543),JSDZ),(I(544),JSDZ),(I(545),JSDZ) E4INZ045
20,(I(546),JSDZ),(I(547),JSDZ),(I(548),JSDZ),(I(549),JSDZ) E4INZ046
21,(I(550),JSDZ),(I(551),JSDZ),(I(552),JSDZ),(I(553),JSDZ) E4INZ047
22,(I(554),JSDZ),(I(555),JSDZ),(I(556),JSDZ),(I(557),JSDZ) E4INZ048
23,(I(558),JSDZ),(I(559),JSDZ),(I(560),JSDZ),(I(561),JSDZ) E4INZ049
24,(I(562),JSDZ),(I(563),JSDZ),(I(564),JSDZ),(I(565),JSDZ) E4INZ050
25,(I(566),JSDZ),(I(567),JSDZ),(I(568),JSDZ),(I(569),JSDZ) E4INZ051
26,(I(570),JSDZ),(I(571),JSDZ),(I(572),JSDZ),(I(573),JSDZ) E4INZ052
27,(I(574),JSDZ),(I(575),JSDZ),(I(576),JSDZ),(I(577),JSDZ) E4INZ053
28,(I(578),JSDZ),(I(579),JSDZ),(I(580),JSDZ),(I(581),JSDZ) E4INZ054
29,(I(582),JSDZ),(I(583),JSDZ),(I(584),JSDZ),(I(585),JSDZ) E4INZ055
30,(I(586),JSDZ),(I(587),JSDZ),(I(588),JSDZ),(I(589),JSDZ) E4INZ056
31,(I(590),JSDZ),(I(591),JSDZ),(I(592),JSDZ),(I(593),JSDZ) E4INZ057
32,(I(594),JSDZ),(I(595),JSDZ),(I(596),JSDZ),(I(597),JSDZ) E4INZ058
33,(I(598),JSDZ),(I(599),JSDZ),(I(600),JSDZ),(I(601),JSDZ) E4INZ059
34,(I(602),JSDZ),(I(603),JSDZ),(I(604),JSDZ),(I(605),JSDZ) E4INZ060
35,(I(606),JSDZ),(I(607),JSDZ),(I(608),JSDZ),(I(609),JSDZ) E4INZ061
36,(I(610),JSDZ),(I(611),JSDZ),(I(612),JSDZ),(I(613),JSDZ) E4INZ062
37,(I(614),JSDZ),(I(615),JSDZ),(I(616),JSDZ),(I(617),JSDZ) E4INZ063
38,(I(618),JSDZ),(I(619),JSDZ),(I(620),JSDZ),(I(621),JSDZ) E4INZ064
39,(I(622),JSDZ),(I(623),JSDZ),(I(624),JSDZ),(I(625),JSDZ) E4INZ065
40,(I(626),JSDZ),(I(627),JSDZ),(I(628),JSDZ),(I(629),JSDZ) E4INZ066
41,(I(630),JSDZ),(I(631),JSDZ),(I(632),JSDZ),(I(633),JSDZ) E4INZ067
42,(I(634),JSDZ),(I(635),JSDZ),(I(636),JSDZ),(I(637),JSDZ) E4INZ068
43,(I(638),JSDZ),(I(639),JSDZ),(I(640),JSDZ),(I(641),JSDZ) E4INZ069
44,(I(642),JSDZ),(I(643),JSDZ),(I(644),JSDZ),(I(645),JSDZ) E4INZ070
45,(I(646),JSDZ),(I(647),JSDZ),(I(648),JSDZ),(I(649),JSDZ) E4INZ071
46,(I(650),JSDZ),(I(651),JSDZ),(I(652),JSDZ),(I(653),JSDZ) E4INZ072
47,(I(654),JSDZ),(I(655),JSDZ),(I(656),JSDZ),(I(657),JSDZ) E4INZ073
48,(I(658),JSDZ),(I(659),JSDZ),(I(660),JSDZ),(I(661),JSDZ) E4INZ074
49,(I(662),JSDZ),(I(663),JSDZ),(I(664),JSDZ),(I(665),JSDZ) E4INZ075
50,(I(666),JSDZ),(I(667),JSDZ),(I(668),JSDZ),(I(669),JSDZ) E4INZ076
51,(I(670),JSDZ),(I(671),JSDZ),(I(672),JSDZ),(I(673),JSDZ) E4INZ077
52,(I(674),JSDZ),(I(675),JSDZ),(I(676),JSDZ),(I(677),JSDZ) E4INZ078
53,(I(678),JSDZ),(I(679),JSDZ),(I(680),JSDZ),(I(681),JSDZ) E4INZ079
54,(I(682),JSDZ),(I(683),JSDZ),(I(684),JSDZ),(I(685),JSDZ) E4INZ080
55,(I(686),JSDZ),(I(687),JSDZ),(I(688),JSDZ),(I(689),JSDZ) E4INZ081
56,(I(690),JSDZ),(I(691),JSDZ),(I(692),JSDZ),(I(693),JSDZ) E4INZ082
57,(I(694),JSDZ),(I(695),JSDZ),(I(696),JSDZ),(I(697),JSDZ) E4INZ083
58,(I(698),JSDZ),(I(699),JSDZ),(I(700),JSDZ),(I(701),JSDZ) E4INZ084
59,(I(702),JSDZ),(I(703),JSDZ),(I(704),JSDZ),(I(705),JSDZ) E4INZ085
60,(I(706),JSDZ),(I(707),JSDZ),(I(708),JSDZ),(I(709),JSDZ) E4INZ086
61,(I(710),JSDZ),(I(711),JSDZ),(I(712),JSDZ),(I(713),JSDZ) E4INZ087
62,(I(714),JSDZ),(I(715),JSDZ),(I(716),JSDZ),(I(717),JSDZ) E4INZ088
63,(I(718),JSDZ),(I(719),JSDZ),(I(720),JSDZ),(I(721),JSDZ) E4INZ089
64,(I(722),JSDZ),(I(723),JSDZ),(I(724),JSDZ),(I(725),JSDZ) E4INZ090
65,(I(726),JSDZ),(I(727),JSDZ),(I(728),JSDZ),(I(729),JSDZ) E4INZ091
66,(I(730),JSDZ),(I(731),JSDZ),(I(732),JSDZ),(I(733),JSDZ) E4INZ092
67,(I(734),JSDZ),(I(735),JSDZ),(I(736),JSDZ),(I(737),JSDZ) E4INZ093
68,(I(738),JSDZ),(I(739),JSDZ),(I(740),JSDZ),(I(741),JSDZ) E4INZ094
69,(I(742),JSDZ),(I(743),JSDZ),(I(744),JSDZ),(I(745),JSDZ) E4INZ095
70,(I(746),JSDZ),(I(747),JSDZ),(I(748),JSDZ),(I(749),JSDZ) E4INZ096
71,(I(750),JSDZ),(I(751),JSDZ),(I(752),JSDZ),(I(753),JSDZ) E4INZ097
72,(I(754),JSDZ),(I(755),JSDZ),(I(756),JSDZ),(I(757),JSDZ) E4INZ098
73,(I(758),JSDZ),(I(759),JSDZ),(I(760),JSDZ),(I(761),JSDZ) E4INZ099
74,(I(762),JSDZ),(I(763),JSDZ),(I(764),JSDZ),(I(765),JSDZ) E4INZ100
75,(I(766),JSDZ),(I(767),JSDZ),(I(768),JSDZ),(I(769),JSDZ) E4INZ101
76,(I(770),JSDZ),(I(771),JSDZ),(I(772),JSDZ),(I(773),JSDZ) E4INZ102
77,(I(774),JSDZ),(I(775),JSDZ),(I(776),JSDZ),(I(777),JSDZ) E4INZ103
78,(I(778),JSDZ),(I(779),JSDZ),(I(780),JSDZ),(I(781),JSDZ) E4INZ104
79,(I(782),JSDZ),(I(783),JSDZ),(I(784),JSDZ),(I(785),JSDZ) E4INZ105
80,(I(786),JSDZ),(I(787),JSDZ),(I(788),JSDZ),(I(789),JSDZ) E4INZ106
81,(I(790),JSDZ),(I(791),JSDZ),(I(792),JSDZ),(I(793),JSDZ) E4INZ107
82,(I(794),JSDZ),(I(795),JSDZ),(I(796),JSDZ),(I(797),JSDZ) E4INZ108
83,(I(798),JSDZ),(I(799),JSDZ),(I(800),JSDZ),(I(801),JSDZ) E4INZ109
84,(I(802),JSDZ),(I(803),JSDZ),(I(804),JSDZ),(I(805),JSDZ) E4INZ110
85,(I(806),JSDZ),(I(807),JSDZ),(I(808),JSDZ),(I(809),JSDZ) E4INZ111
86,(I(810),JSDZ),(I(811),JSDZ),(I(812),JSDZ),(I(813),JSDZ) E4INZ112
87,(I(814),JSDZ),(I(815),JSDZ),(I(816),JSDZ),(I(817),JSDZ) E4INZ113
88,(I(818),JSDZ),(I(819),JSDZ),(I(820),JSDZ),(I(821),JSDZ) E4INZ114
89,(I(822),JSDZ),(I(823),JSDZ),(I(824),JSDZ),(I(825),JSDZ) E4INZ115
90,(I(826),JSDZ),(I(827),JSDZ),(I(828),JSDZ),(I(829),JSDZ) E4INZ116
91,(I(830),JSDZ),(I(831),JSDZ),(I(832),JSDZ),(I(833),JSDZ) E4INZ117
92,(I(834),JSDZ),(I(835),JSDZ),(I(836),JSDZ),(I(837),JSDZ) E4INZ118
93,(I(838),JSDZ),(I(839),JSDZ),(I(840),JSDZ),(I(841),JSDZ) E4INZ119
94,(I(842),JSDZ),(I(843),JSDZ),(I(844),JSDZ),(I(845),JSDZ) E4INZ120
95,(I(846),JSDZ),(I(847),JSDZ),(I(848),JSDZ),(I(849),JSDZ) E4INZ121
96,(I(850),JSDZ),(I(851),JSDZ),(I(852),JSDZ),(I(853),JSDZ) E4INZ122
97,(I(854),JSDZ),(I(855),JSDZ),(I(856),JSDZ),(I(857),JSDZ) E4INZ123
98,(I(858),JSDZ),(I(859),JSDZ),(I(860),JSDZ),(I(861),JSDZ) E4INZ124
99,(I(862),JSDZ),(I(863),JSDZ),(I(864),JSDZ),(I(865),JSDZ) E4INZ125
100,(I(866),JSDZ),(I(867),JSDZ),(I(868),JSDZ),(I(869),JSDZ) E4INZ126
101,(I(870),JSDZ),(I(871),JSDZ),(I(872),JSDZ),(I(873),JSDZ) E4INZ127
102,(I(874),JSDZ),(I(875),JSDZ),(I(876),JSDZ),(I(877),JSDZ) E4INZ128
103,(I(878),JSDZ),(I(879),JSDZ),(I(880),JSDZ),(I(881),JSDZ) E4INZ129
104,(I(882),JSDZ),(I(883),JSDZ),(I(884),JSDZ),(I(885),JSDZ) E4INZ130
105,(I(886),JSDZ),(I(887),JSDZ),(I(888),JSDZ),(I(889),JSDZ) E4INZ131
106,(I(890),JSDZ),(I(891),JSDZ),(I(892),JSDZ),(I(893),JSDZ) E4INZ132
107,(I(894),JSDZ),(I(895),JSDZ),(I(896),JSDZ),(I(897),JSDZ) E4INZ133
108,(I(898),JSDZ),(I(899),JSDZ),(I(900),JSDZ),(I(901),JSDZ) E4INZ134
109,(I(902),JSDZ),(I(903),JSDZ),(I(904),JSDZ),(I(905),JSDZ) E4INZ135
110,(I(906),JSDZ),(I(907),JSDZ),(I(908),JSDZ),(I(909),JSDZ) E4INZ136
111,(I(910),JSDZ),(I(911),JSDZ),(I(912),JSDZ),(I(913),JSDZ) E4INZ137
112,(I(914),JSDZ),(I(915),JSDZ),(I(916),JSDZ),(I(917),JSDZ) E4INZ138
113,(I(918),JSDZ),(I(919),JSDZ),(I(920),JSDZ),(I(921),JSDZ) E4INZ139
114,(I(922),JSDZ),(I(923),JSDZ),(I(924),JSDZ),(I(925),JSDZ) E4INZ140
115,(I(926),JSDZ),(I(927),JSDZ),(I(928),JSDZ),(I(929),JSDZ) E4INZ141
116,(I(930),JSDZ),(I(931),JSDZ),(I(932),JSDZ),(I(933),JSDZ) E4INZ142
117,(I(934),JSDZ),(I(935),JSDZ),(I(936),JSDZ),(I(937),JSDZ) E4INZ143
118,(I(938),JSDZ),(I(939),JSDZ),(I(940),JSDZ),(I(941),JSDZ) E4INZ144
119,(I(942),JSDZ),(I(943),JSDZ),(I(944),JSDZ),(I(945),JSDZ) E4INZ145
120,(I(946),JSDZ),(I(947),JSDZ),(I(948),JSDZ),(I(949),JSDZ) E4INZ146
121,(I(950),JSDZ),(I(951),JSDZ),(I(952),JSDZ),(I(953),JSDZ) E4INZ147
122,(I(954),JSDZ),(I(955),JSDZ),(I(956),JSDZ),(I(957),JSDZ) E4INZ148
123,(I(958),JSDZ),(I(959),JSDZ),(I(960),JSDZ),(I(961),JSDZ) E4INZ149
124,(I(962),JSDZ),(I(963),JSDZ),(I(964),JSDZ),(I(965),JSDZ) E4INZ150
125,(I(966),JSDZ),(I(967),JSDZ),(I(968),JSDZ),(I(969),JSDZ) E4INZ151
126,(I(970),JSDZ),(I(971),JSDZ),(I(972),JSDZ),(I(973),JSDZ) E4INZ152
127,(I(974),JSDZ),(I(975),JSDZ),(I(976),JSDZ),(I(977),JSDZ) E4INZ153
128,(I(978),JSDZ),(I(979),JSDZ),(I(980),JSDZ),(I(981),JSDZ) E4INZ154
129,(I(982),JSDZ),(I(983),JSDZ),(I(984),JSDZ),(I(985),JSDZ) E4INZ155
130,(I(986),JSDZ),(I(987),JSDZ),(I(988),JSDZ),(I(989),JSDZ) E4INZ156
131,(I(990),JSDZ),(I(991),JSDZ),(I(992),JSDZ),(I(993),JSDZ) E4INZ157
132,(I(994),JSDZ),(I(995),JSDZ),(I(996),JSDZ),(I(997),JSDZ) E4INZ158
133,(I(998),JSDZ),(I(999),JSDZ),(I(1000),JSDZ),(I(1001),JSDZ) E4INZ159
134,(I(1002),JSDZ),(I(1003),JSDZ),(I(1004),JSDZ),(I(1005),JSDZ) E4INZ160
135,(I(1006),JSDZ),(I(1007),JSDZ),(I(1008),JSDZ),(I(1009),JSDZ) E4INZ161
136,(I(1010),JSDZ),(I(1011),JSDZ),(I(1012),JSDZ),(I(1013),JSDZ) E4INZ162
137,(I(1014),JSDZ),(I(1015),JSDZ),(I(1016),JSDZ),(I(1017),JSDZ) E4INZ163
138,(I(1018),JSDZ),(I(1019),JSDZ),(I(1020),JSDZ),(I(1021),JSDZ) E4INZ164
139,(I(1022),JSDZ),(I(1023),JSDZ),(I(1024),JSDZ),(I(1025),JSDZ) E4INZ165
140,(I(1026),JSDZ),(I(1027),JSDZ),(I(1028),JSDZ),(I(1029),JSDZ) E4INZ166
141,(I(1030),JSDZ),(I(1031),JSDZ),(I(1032),JSDZ),(I(1033),JSDZ) E4INZ167
142,(I(1034),JSDZ),(I(1035),JSDZ),(I(1036),JSDZ),(I(1037),JSDZ) E4INZ168
143,(I(1038),JSDZ),(I(1039),JSDZ),(I(1040),JSDZ),(I(1041),JSDZ) E4INZ169
144,(I(1042),JSDZ),(I(1043),JSDZ),(I(1044),JSDZ),(I(1045),JSDZ) E4INZ170
145,(I(1046),JSDZ),(I(1047),JSDZ),(I(1048),JSDZ),(I(1049),JSDZ) E4INZ171
146,(I(1050),JSDZ),(I(1051),JSDZ),(I(1052),JSDZ),(I(1053),JSDZ) E4INZ172
147,(I(1054),JSDZ),(I(1055),JSDZ),(I(1056),JSDZ),(I(1057),JSDZ) E4INZ173
148,(I(1058),JSDZ),(I(1059),JSDZ),(I(1060),JSDZ),(I(1061),JSDZ) E4INZ174
149,(I(1062),JSDZ),(I(1063),JSDZ),(I(1064),JSDZ),(I(1065),JSDZ) E4INZ175
150,(I(1066),JSDZ),(I(1067),JSDZ),(I(1068),JSDZ),(I(1069),JSDZ) E4INZ176
151,(I(1070),JSDZ),(I(1071),JSDZ),(I(1072),JSDZ),(I(1073),JSDZ) E4INZ177
152,(I(1074),JSDZ),(I(1075),JSDZ),(I(1076),JSDZ),(I(1077),JSDZ) E4INZ178
153,(I(1078),JSDZ),(I(1079),JSDZ),(I(1080),JSDZ),(I(1081),JSDZ) E4INZ179
154,(I(1082),JSDZ),(I(1083),JSDZ),(I(1084),JSDZ),(I(1085),JSDZ) E4INZ180
155,(I(1086),JSDZ),(I(1087),JSDZ),(I(1088),JSDZ),(I(1089),JSDZ) E4INZ181
156,(I(1090),JSDZ),(I(1091),JSDZ),(I(1092),JSDZ),(I(1093),JSDZ) E4INZ182
157,(I(1094),JSDZ),(I(1095),JSDZ),(I(1096),JSDZ),(I(1097),JSDZ) E4INZ183
158,(I(1098),JSDZ),(I(1099),JSDZ),(I(1100),JSDZ),(I(1101),JSDZ) E4INZ184
159,(I(1102),JSDZ),(I(1103),JSDZ),(I(1104),JSDZ),(I(1105),JSDZ) E4INZ185
160,(I(1106),JSDZ),(I(1107),JSDZ),(I(1108),JSDZ),(I(1109),JSDZ) E4INZ186
161,(I(1110),JSDZ),(I(1111),JSDZ),(I(1112),JSDZ),(I(1113),JSDZ) E4INZ187
162,(I(1114),JSDZ),(I(1115),JSDZ),(I(1116),JSDZ),(I(1117),JSDZ) E4INZ188
163,(I(1118),JSDZ),(I(1119),JSDZ),(I(1120),JSDZ),(I(1121),JSDZ) E4INZ189
164,(I(1122),JSDZ),(I(1123),JSDZ),(I(1124),JSDZ),(I(1125),JSDZ) E4INZ190
165,(I(1126),JSDZ),(I(1127),JSDZ),(I(1128),JSDZ),(I(1129),JSDZ) E4INZ191
166,(I(1130),JSDZ),(I(1131),JSDZ),(I(1132),JSDZ),(I(1133),JSDZ) E4INZ192
167,(I(1134),JSDZ),(I(1135),JSDZ),(I(1136),JSDZ),(I(1137),JSDZ) E4INZ193
168,(I(1138),JSDZ),(I(1139),JSDZ),(I(1140),JSDZ),(I(1141),JSDZ) E4INZ194
169,(I(1142),JSDZ),(I(1143),JSDZ),(I(1144),JSDZ),(I(1145),JSDZ) E4INZ195
170,(I(1146),JSDZ),(I(1147),JSDZ),(I(1148),JSDZ),(I(1149),JSDZ) E4INZ196
171,(I(1150),JSDZ),(I(1151),JSDZ),(I(1152),JSDZ),(I(1153),JSDZ) E4INZ197
172,(I(1154),JSDZ),(I(1155),JSDZ),(I(1156),JSDZ),(I(1157),JSDZ) E4INZ198
173,(I(1158),JSDZ),(I(1159),JSDZ),(I(1160),JSDZ),(I(1161),JSDZ) E4INZ199
174,(I(1162),JSDZ),(I(1163),JSDZ),(I(1164),JSDZ),(I(1165),JSDZ) E4INZ200
175,(I(1166),JSDZ),(I(1167),JSDZ),(I(1168),JSDZ),(I(1169),JSDZ) E4INZ201
176,(I(1170),JSDZ),(I(1171),JSDZ),(I(1172),JSDZ),(I(1173),JSDZ) E4INZ202
177,(I(1174),JSDZ),(I(1175),JSDZ),(I(1176),JSDZ),(I(1177),JSDZ) E4INZ203
178,(I(1178),JSDZ),(I(1179),JSDZ),(I(1180),JSDZ),(I(1181),JSDZ) E4INZ204
179,(I(1182),JSDZ),(I(1183),JSDZ),(I(1184),JSDZ),(I(1185),JSDZ) E4INZ205
180,(I(1186),JSDZ),(I(1187),JSDZ),(I(1188),JSDZ),(I(1189),JSDZ) E4INZ206
181,(I(1190),JSDZ),(I(1191),JSDZ),(I(1192),JSDZ),(I(1193),JSDZ) E4INZ207
182,(I(1194),JSDZ),(I(1195),JSDZ),(I(1196),JSDZ),(I(1197),JSDZ) E4INZ208
183,(I(1198),JSDZ),(I(1199),JSDZ),(I(1200),JSDZ),(I(1201),JSDZ) E4INZ209
184,(I(1202),JSDZ),(I(1203),JSDZ),(I(1204),JSDZ),(I(1205),JSDZ) E4INZ210
185,(I(1206),JSDZ),(I(1207),JSDZ),(I(1208),JSDZ),(I(1209),JSDZ) E4INZ211
186,(I(1210),JSDZ),(I(1211),JSDZ),(I(1212),JSDZ),(I(1213),JSDZ) E4INZ212
187,(I(1214),JSDZ),(I(1215),JSDZ),(I(1216),JSDZ),(I(1217),JSDZ) E4INZ213
188,(I(1218),JSDZ),(I(1219),JSDZ),(I(1220),JSDZ),(I(1221),JSDZ) E4INZ214
189,(I(1222),JSDZ),(I(1223),JSDZ),(I(1224),JSDZ),(I(1225),JSDZ) E4INZ215
190,(I(1226),JSDZ),(I(1227),JSDZ),(I(1228),JSDZ),(I(1229),JSDZ) E4INZ216
191,(I(1230),JSDZ),(I(1231),JSDZ),(I(1232),JSDZ),(I(1233),JSDZ) E4INZ217
192,(I(1234),JSDZ),(I(1235),JSDZ),(I(1236),JSDZ),(I(1237),JSDZ) E4INZ218
193,(I(1238),JSDZ),(I(1239),JSDZ),(I(1240),JSDZ),(I(1241),JSDZ) E4INZ219
194,(I(1242),JSDZ),(I(1243),JSDZ),(I(1244),JSDZ),(I(1245),JSDZ) E4INZ220
195,(I(1246),JSDZ),(I(1247),JSDZ),(I(1248),JSDZ),(I(1249),JSDZ) E4INZ221
196,(I(1250),JSDZ),(I(1251),JSDZ),(I(1252),JSDZ),(I(1253),JSDZ) E4INZ222
197,(I(1254),JSDZ),(I(1255),JSDZ),(I(1256),JSDZ),(I(1257),JSDZ) E4INZ223
198,(I(1258),JSDZ),(I(1259),JSDZ),(I(1260),JSDZ),(I(1261),JSDZ) E4INZ224
199,(I(1262),JSDZ),(I(1263),JSDZ),(I(1264),JSDZ),(I(1265),JSDZ) E4INZ225
200,(I(1266),JSDZ),(I(1267),JSDZ),(I(1268),JSDZ),(I(1269),JSDZ) E4INZ226
201,(I(1270),JSDZ),(I(1271),JSDZ),(I(1272),JSDZ),(I(1273),JSDZ) E4INZ227
202,(I(1274),JSDZ),(I(1275),JSDZ),(I(1276),JSDZ),(I(1277),JSDZ) E4INZ228
203,(I(1278),JSDZ),(I(1279),JSDZ),(I(1280),JSDZ),(I(1281),JSDZ) E4INZ229
204,(I(1282),JSDZ),(I(1283),JSDZ),(I(1284),JSDZ),(I(1285),JSDZ) E4INZ230
205,(I(1286),JSDZ),(I(1287),JSDZ),(I(1288),JSDZ),(I(1289),JSDZ) E4INZ231
206,(I(1290),JSDZ),(I(1291),JSDZ),(I(1292),JSDZ),(I(1293),JSDZ) E4INZ232
207,(I(1294),JSDZ),(I(1295),JSDZ),(I(1296),JSDZ),(I(1297),JSDZ) E4INZ233
208,(I(1298),JSDZ),(I(1299),JSDZ),(I(1300),JSDZ),(I(1301),JSDZ) E4INZ234
209,(I(1302),JSDZ),(I(1303),JSDZ),(I(1304),JSDZ),(I(1305),JSDZ) E4INZ235
210,(I(1306),JSDZ),(I(1
```


Table VII-70. Source program listing of subroutine MDIN (Link 4)

```

A LABEL
CE4MDN F4MND000
SUBROUTINE MDIN F4MND001
C ORIENTS LOCAL AXES PROPERLY AT A BOUNDARY NODE IN SHELLS F4MND002
C TO ROTATE LOCAL AXES TO THAT KS1 IS IN Z-BIR PLANE F4MND003
DIMENSION I(11),AA(11),S(1),N(8),D21(21),D33(3,3),E21(3,3) F4MND004
I(1)=24,U(1)=24,X(1)=Y(1),Z(1)=XD(1),YD(1),ZD(1),G(1) F4MND005
COMMON IA,AA F4MND006
EQUIVALENCE (IA,AA),(D21,D33),(D21(10),F22),(D21(19),E),(D21(20),G) F4MND007
EQUIVALENCE (IA(1),IN),(IA(2),IRN),(IA(3),I),(IA(4),IP),(IA(5), F4MND008
1IPRS),(IA(6),ITYPF),(IA(7),INAT),(IA(8),IDEG),(IA(9),IRW),(IA(10), F4MND009
2IHS),(IA(11),IR),(IA(12),IMK),(IA(13),IMW),(IA(14),IMZ),(IA(15), F4MND010
3IMF),(IA(16),IARE),(IA(17),NI),(IA(25),NI),(IA(26),IY),(IA(27), F4MND011
4ISTR),(IA(28),IFLT),(IA(29),ITEM),(IA(30),ITIC),(IA(31),IMET), F4MND012
5(IA(32),ISUM),(IA(33),INO),(IA(34),IMS),(IA(36),IDS),(IA(37), F4MND013
6IORD),(IA(38),IORD1),(IA(39),ACEL),(IA(50),J1),(IA(51),J2), F4MND014
7(IA(52),J3),(IA(53),J4),(IA(54),J5),(IA(55),J6),(IA(56),J7),(IA(57), F4MND015
8J8),J9),(IA(58),JTY),(IA(59),IBBI),(IA(60),IBOI),(IA(61),IBD),(IA(62), F4MND016
9IAT),(IA(63),ID),(IA(64),IDY),(IA(65),ITE),(IA(66),IAP) F4MND017
EQUIVALENCE (IA(66),ICAR),(IA(67),ICIX),(IA(68),ICIX),(IA(69), F4MND018
1ICIZ),(IA(70),ICFI),(IA(71),ICX),(IA(72),IYY),(IA(73),IZZ), F4MND019
2(IA(74),IIC),(IA(75),IDEF),(IA(76),IST),(IA(77),IIS) F4MND020
3,(IA(78),IGEM),(IA(79),IFRK),(AA(80),TF),(AA(81),DT),(AA(82),DG), F4MND021
4(AA(83),ALL),(AA(84),AL2),(AA(85),AL3),(AA(86),D21),(AA(87),P), F4MND022
5(AA(88),X),(AA(89),Y),(AA(90),Z),(AA(91),I),(AA(92),X),(AA(93),Y), F4MND023
6(AA(94),D),(AA(95),Z),(AA(96),S),(AA(97),S),(AA(98),ZEM) F4MND024
7,(AA(42),IPR),(AA(43),IPBE),(AA(44),IPEN),(AA(45),CONS),(AA(46),IIF) F4MND025
8,(AA(47),G1),(AA(48),G2),(AA(49),G3) F4MND026
EQUIVALENCE (IA(349),NIC),(IA(348),ISDT),(IA(347),ISDY),(IA(346), F4MND027
1,ISDZ),(IA(345),J9),(IA(344),J10),(IA(343),JPRS),(IA(342),JSDY) F4MND028
2,(IA(341),JSDZ),(IA(340),JARE),(IA(339),JMK),(IA(338),JPMY) F4MND029
3,(IA(337),JMK),(IA(336),JMP),(IA(335),IAS),(IA(334),I02) F4MND030
4,(IA(333),JPR),(AA(332),NGV),(AA(331),DG2),(AA(330),PREFS) F4MND031
5,(IA(329),IPR) F4MND032
DIMENSION BIR(3),SIR(3),DINI(3,3),SKI(1),XNI(2),XF(3),ON(6),OF(6), F4MND033
1RES(6),RED(6),BAS(3),ICLAS(4),NBAN(10),NH(3),NFS(3) F4MND034
EQUIVALENCE (AA(200),IUNE),(AA(201),ICN),(AA(202),IM),(AA(203),ASTR) F4MND035
1),(AA(204),ININ),(AA(205),ARE),(AA(206),ICL),(AA(207),IMEL) F4MND036
2(AA(208),IM),(AA(209),IC),(AA(210),ICOM),(AA(211),ANGL1),(AA(212), F4MND037
3ICAS),(AA(213),IE),(AA(214),NH),(AA(215),MR) F4MND038
4,(AA(216),IROT),(AA(217),BST) F4MND039
EQUIVALENCE (AA(220),BIR),(AA(223),SIR),(AA(226),DIN),(AA(235),SR) F4MND040
1,(AA(241),XN),(AA(244),XF),(AA(247),QN),(AA(253),QF),(AA(259),RFS) F4MND041
2,(AA(265),RED),(AA(271),RAS),(AA(274),ICLAS),(AA(278),NRAN) F4MND042
3,(AA(292),NI),(AA(295),NES) F4MND043
DIMENSION MEL(20),MAC(4,4,20),IMG(90),DD(6,6),A(90,7),B(8,8), F4MND044
1C(6,2),FF(1),NSET(100),MSET(100),W(3,3) F4MND045
EQUIVALENCE (AA(14000),FF),(NU(1),JP1),(NU(2),JM1),(NU(3),JS1) F4MND046
EQUIVALENCE (FF(1),NEL),(FF(341),MAC),(FF(661),IMG),(FF(751),D01) F4MND047
1(FF(787),A),(FF(1417),B),(FF(1481),C),(FF(1497),NSET),(FF(1597), F4MND048
2MSET),(FF(1697),N) F4MND049
DIMENSION XI(3),ETA(3),ZTA(3) F4MND050
EQUIVALENCE (DIN(1),XI1),(DINI(4),ETA),(DINI(7),ZTA) F4MND051
C SET INDICATORS TO LOCAL IS DIFFERENT THAN OVERALL F4MND052
INOT=1 F4MND053
BST=2H** F4MND054
C SEE IF A SOLID F4MND055
IF (ICAS=4) 33,31,33 F4MND056
C SOLID CASE. FIND THE AXIS WHICH MAKES LARGEST ANGLE WITH BIR F4MND057
31 IF (ABS(FBIR(1))-ABS(FBIR(2))) 315,315,316 F4MND058
315 IF (ABS(FBIR(1))-ABS(FBIR(3))) 311,311,313 F4MND059
316 IF (ABS(FBIR(2))-ABS(FBIR(3))) 312,312,313 F4MND060
311 CALL VECT(ETA,BIR,XII) F4MND061
GO TO 35 F4MND062
312 CALL VECT(SIR,BIR,ETA) F4MND063
ETA(1)=SIR(1) F4MND064
ETA(2)=SIR(2) F4MND065
ETA(3)=SIR(3) F4MND066
GO TO 35 F4MND067
313 CALL VECT(ETA,BIR,ZTA) F4MND068
CC=1 F4MND069
CALL UNIT(ETA,CC) F4MND070
CALL VECT(ZTA,BIR,ETA) F4MND071
CALL UNIT(ZTA,CC) F4MND072
CALL VECT(XII,ETA,ZTA) F4MND073
CALL UNIT(XII,CC) F4MND074
GO TO 22 F4MND075
C MIN-SOLID CASE F4MND076
33 CC=1 F4MND077
CALL VECT(ETA,ZTA,BIR) F4MND078
CALL UNIT(ETA,CC) F4MND079
CALL VECT(XII,ETA,ZTA) F4MND080
CALL UNIT(XII,CC) F4MND081
22 RETURN F4MND082
END F4MND083

```

Table VII-71. Source program listing of subroutine META (Link 4)

```

CE4MET          E4MET000          208 IF (ICAS=4) 207,210,207          E4MET070
SUBROUTINE META E4MET001          207 E1=F/11.-PUPUI          E4MET071
TO GENERATE MATRIAL MATRIX DD IN THE ORDER OF 1,2,12,3,13,23 E4MET002          E4MET072
IN LOCAL COORDINATE SYSTEM E4MET003          E4MET073
DIMENSION IA(1),AA(1),S(1),N(8),D21(21),D33(3,3),E22(3,3) E4MET004          E4MET074
1,P(24),UV(24),X(8),Y(8),Z(8),XD(7),YD(7),ZD(7),GL(1) E4MET005          E4MET075
COMMON IA,AA E4MET006          E4MET076
EQUIVALENCE(IA,AA1,(D21,D33),(D21(10),E22),(D21(19),E1,(D21(20),G) E4MET007          E4MET077
EQUIVALENCE(IA(1),IN),(IA(2),IBN),(IA(3),IT),(IA(4),IP),(IA(5), E4MET008          E4MET078
1PRS),(IA(6),ITYPE),(IA(7),IMAT),(IA(8),IDEG),(IA(9),INX),(IA(10),E4MET009          E4MET079
2IH),(IA(11),IB),(IA(12),IMM),(IA(13),IMMY),(IA(14),IMW),(IA(15),E4MET010          E4MET080
3IMF),(IA(16),IARE),(IA(17),N(1)),(IA(25),M),(IA(26),ITY),(IA(27),E4MET011          E4MET081
4ISTR),(IA(28),IELT),(IA(29),ITEM),(IA(30),IIC),(IA(31),IMET) E4MET012          E4MET082
5(IA(32),SUM),(IA(33),IND),(IA(34),IMS),(IA(36),IDS),(IA(37), E4MET013          E4MET083
6DRD),(IA(38),JORDI),(IA(39),ACEL),(IA(50),JI),(IA(51),J2), E4MET014          E4MET084
7(IA(52),J3),(IA(53),J4),(IA(54),J5),(IA(55),J6),(IA(56),J7),(IA(57),E4MET015          E4MET085
8(J),(IA(58),JTY),(IA(59),IBB),(IA(60),IBO),(IA(61),ID),(IA(62),E4MET016          E4MET086
9(I),(IA(63),IDT),(IA(64),IUY),(IA(65),IF),(IA(61),ITAP) E4MET017          E4MET087
EQUIVALENCE(IA(66),ICAR),(IA(67),ICIX),(IA(68),ICIX),(IA(69), E4MET018          E4MET088
1ICIZ),(IA(70),ICF),(IA(71),IXI),(IA(72),IYI),(IA(73),IZI) E4MET019          E4MET089
2(IA(74),IIC),(IA(75),IDEF),(IA(76),IST),(IA(77),IIS) E4MET020          E4MET090
3(IA(78),IGEM),(IA(79),IERR),(AA(80),TE),(AA(81),DT),(AA(82),BG), E4MET021          E4MET091
4(AA(83),AL3),(AA(84),AL2),(AA(85),AL3),(AA(86),D21),(AA(107),P), E4MET022          E4MET092
5(AA(131),UV),(AA(135),X),(AA(135),Y),(AA(171),Z),(AA(179),XD), E4MET023          E4MET093
6(AA(186),YD),(AA(193),ZD),(AA(351),S),(AA(401),ZGEM) E4MET024          E4MET094
7(AA(421),IMP),(AA(431),IPBG),(AA(441),IPEN),(AA(451),CONS),(AA(461),IIE) E4MET025          E4MET095
8(IA(471),GL),(IA(481),G2),(IA(491),G3) E4MET026          E4MET096
EQUIVALENCE(IA(349),NTIC),(IA(348),ISDT),(IA(347),ISDY),(IA(1346) E4MET027          E4MET097
1,ISDZ),(IA(345),J9),(IA(344),J10),(IA(343),JPRS),(IA(342),JSDY) E4MET028          E4MET098
2(IA(341),JSDZ),(IA(340),JARE),(IA(339),JMMX),(IA(338),JMMY) E4MET029          E4MET099
3(IA(337),JMMF),(IA(336),JMF),(IA(335),JIAS),(IA(334),JID) E4MET030          E4MET100
4(IA(333),JPR),(IA(332),DGY),(IA(331),OGZ),(IA(330),PRES) E4MET031          E4MET101
5(IA(329),JPR) E4MET032          E4MET102
DIMENSION BIR(3),SIR(3),DIN(3,3),SR(6),XN(3),XF(3),DN(6),DF(6), E4MET033          E4MET103
IRES(6),RED(6),BAS(3),ICLAS(4),NBRAN(10),NI(3),NES(3) E4MET034          E4MET104
EQUIVALENCE(AA(200),IDNE),(AA(201),ICN),(AA(202),LMI),(AA(203),ASTE) E4MET035          E4MET105
1(IA(204),JNHUN),(AA(205),ARE),(AA(206),ICLA),(AA(207),IMEL) E4MET036          E4MET106
2(AA(208),IM),(AA(209),IC),(AA(210),ICDN),(AA(211),ANGLE),(AA(212),E4MET037          E4MET107
3ICAS),(AA(213),IE),(AA(214),NB),(AA(215),NB) E4MET038          E4MET108
4(AA(216),IRDT),(AA(217),BS) E4MET039          E4MET109
EQUIVALENCE(IA(220),BIR),(AA(223),SIR),(AA(226),DIN),(AA(235),SR) E4MET040          E4MET110
1(AA(241),XN),(AA(244),XF),(AA(247),DN),(AA(253),DF),(AA(259),RES) E4MET041          E4MET111
2(AA(265),RED),(AA(271),BAS),(AA(274),ICLAS),(AA(278),NBRAN) E4MET042          E4MET112
3(AA(292),NI),(AA(295),NES) E4MET043          E4MET113
DIMENSION NEL(20,17),MAC(4,4,20),IWC(90),DD(6,6),A(90,7),B(8,8), E4MET044          E4MET114
IC(8,2),FF(1),NSET(100),MSE(100),M(3) E4MET045          E4MET115
EQUIVALENCE(IA(14000),FF),(NU(1),JP1),(NU(2),JM),(NU(3),JS) E4MET046          E4MET116
EQUIVALENCE(FF(1),NEL),(FF(341),MAC),(FF(661),IWC),(FF(751),DD) E4MET047          E4MET117
1(FF(787),A),(FF(1417),B),(FF(1481),C),(FF(1497),NSET),(FF(1597), E4MET048          E4MET118
2MSET),(FF(1697),W) E4MET049          E4MET119
INITIALIZE DD ALPHA CONSTANTS E4MET050          E4MET120
DD IO J=1,6 E4MET051          E4MET121
DD IO J=1,6 E4MET052          E4MET122
DD(I,J)=0, E4MET053          E4MET123
AL=0, E4MET054          E4MET124
AL2=0, E4MET055          E4MET125
AL3=0, E4MET056          E4MET126
INQUIRE THE TYPE AND GENERATE DD IN THE ORDER OF 1,2,3,12,13,23 E4MET057          E4MET127
IF (ITYPE=1) 20,30,40 E4MET058          E4MET128
ISOTROPIC MATERIAL E4MET059          E4MET129
20 I(1)=I(1)+(MET-1)*2 E4MET060          E4MET130
E=AA(I(1)+1) E4MET061          E4MET131
G=AA(I(1)+2) E4MET062          E4MET132
I(1)=I(1)+MET E4MET063          E4MET133
AL=AA(I(1)) E4MET064          E4MET134
AL2=ALL E4MET065          E4MET135
AL3=ALL E4MET066          E4MET136
PUE=(2.*G)-1. E4MET067          E4MET137
IF (ISTR=1) 209,210,209 E4MET068          E4MET138
209 IF (ICAS=3) 208,210,208 E4MET069

```

Table VII-72. Source program listing of subroutine QUAD (Link 4)

```

C LABEL
CEQUAD
SUBROUTINE QUAD
FINDS LOCAL CURVATURE AXES BY BEST FIT QUADRATIC IN SHELLS
DIMENSION I(1),AA(1),S(1),N(1),DZ(1),D3(1),E2(1),E3(1)
I(1),I(2),I(3),I(4),I(5),I(6),I(7),I(8),I(9),I(10),I(11),I(12),I(13),I(14),I(15),I(16),I(17),I(18),I(19),I(20),I(21),I(22),I(23),I(24),I(25),I(26),I(27),I(28),I(29),I(30),I(31),I(32),I(33),I(34),I(35),I(36),I(37),I(38),I(39),I(40),I(41),I(42),I(43),I(44),I(45),I(46),I(47),I(48),I(49),I(50),I(51),I(52),I(53),I(54),I(55),I(56),I(57),I(58),I(59),I(60),I(61),I(62),I(63),I(64),I(65),I(66),I(67),I(68),I(69),I(70),I(71),I(72),I(73),I(74),I(75),I(76),I(77),I(78),I(79),I(80),I(81),I(82),I(83),I(84),I(85),I(86),I(87),I(88),I(89),I(90),I(91),I(92),I(93),I(94),I(95),I(96),I(97),I(98),I(99),I(100),I(101),I(102),I(103),I(104),I(105),I(106),I(107),I(108),I(109),I(110),I(111),I(112),I(113),I(114),I(115),I(116),I(117),I(118),I(119),I(120),I(121),I(122),I(123),I(124),I(125),I(126),I(127),I(128),I(129),I(130),I(131),I(132),I(133),I(134),I(135),I(136),I(137),I(138),I(139),I(140),I(141),I(142),I(143),I(144),I(145),I(146),I(147),I(148),I(149),I(150),I(151),I(152),I(153),I(154),I(155),I(156),I(157),I(158),I(159),I(160),I(161),I(162),I(163),I(164),I(165),I(166),I(167),I(168),I(169),I(170),I(171),I(172),I(173),I(174),I(175),I(176),I(177),I(178),I(179),I(180),I(181),I(182),I(183),I(184),I(185),I(186),I(187),I(188),I(189),I(190),I(191),I(192),I(193),I(194),I(195),I(196),I(197),I(198),I(199),I(200),I(201),I(202),I(203),I(204),I(205),I(206),I(207),I(208),I(209),I(210),I(211),I(212),I(213),I(214),I(215),I(216),I(217),I(218),I(219),I(220),I(221),I(222),I(223),I(224),I(225),I(226),I(227),I(228),I(229),I(230),I(231),I(232),I(233),I(234),I(235),I(236),I(237),I(238),I(239),I(240),I(241),I(242),I(243),I(244),I(245),I(246),I(247),I(248),I(249),I(250),I(251),I(252),I(253),I(254),I(255),I(256),I(257),I(258),I(259),I(260),I(261),I(262),I(263),I(264),I(265),I(266),I(267),I(268),I(269),I(270),I(271),I(272),I(273),I(274),I(275),I(276),I(277),I(278),I(279),I(280),I(281),I(282),I(283),I(284),I(285),I(286),I(287),I(288),I(289),I(290),I(291),I(292),I(293),I(294),I(295),I(296),I(297),I(298),I(299),I(300),I(301),I(302),I(303),I(304),I(305),I(306),I(307),I(308),I(309),I(310),I(311),I(312),I(313),I(314),I(315),I(316),I(317),I(318),I(319),I(320),I(321),I(322),I(323),I(324),I(325),I(326),I(327),I(328),I(329),I(330),I(331),I(332),I(333),I(334),I(335),I(336),I(337),I(338),I(339),I(340),I(341),I(342),I(343),I(344),I(345),I(346),I(347),I(348),I(349),I(350),I(351),I(352),I(353),I(354),I(355),I(356),I(357),I(358),I(359),I(360),I(361),I(362),I(363),I(364),I(365),I(366),I(367),I(368),I(369),I(370),I(371),I(372),I(373),I(374),I(375),I(376),I(377),I(378),I(379),I(380),I(381),I(382),I(383),I(384),I(385),I(386),I(387),I(388),I(389),I(390),I(391),I(392),I(393),I(394),I(395),I(396),I(397),I(398),I(399),I(400),I(401),I(402),I(403),I(404),I(405),I(406),I(407),I(408),I(409),I(410),I(411),I(412),I(413),I(414),I(415),I(416),I(417),I(418),I(419),I(420),I(421),I(422),I(423),I(424),I(425),I(426),I(427),I(428),I(429),I(430),I(431),I(432),I(433),I(434),I(435),I(436),I(437),I(438),I(439),I(440),I(441),I(442),I(443),I(444),I(445),I(446),I(447),I(448),I(449),I(450),I(451),I(452),I(453),I(454),I(455),I(456),I(457),I(458),I(459),I(460),I(461),I(462),I(463),I(464),I(465),I(466),I(467),I(468),I(469),I(470),I(471),I(472),I(473),I(474),I(475),I(476),I(477),I(478),I(479),I(480),I(481),I(482),I(483),I(484),I(485),I(486),I(487),I(488),I(489),I(490),I(491),I(492),I(493),I(494),I(495),I(496),I(497),I(498),I(499),I(500),I(501),I(502),I(503),I(504),I(505),I(506),I(507),I(508),I(509),I(510),I(511),I(512),I(513),I(514),I(515),I(516),I(517),I(518),I(519),I(520),I(521),I(522),I(523),I(524),I(525),I(526),I(527),I(528),I(529),I(530),I(531),I(532),I(533),I(534),I(535),I(536),I(537),I(538),I(539),I(540),I(541),I(542),I(543),I(544),I(545),I(546),I(547),I(548),I(549),I(550),I(551),I(552),I(553),I(554),I(555),I(556),I(557),I(558),I(559),I(560),I(561),I(562),I(563),I(564),I(565),I(566),I(567),I(568),I(569),I(570),I(571),I(572),I(573),I(574),I(575),I(576),I(577),I(578),I(579),I(580),I(581),I(582),I(583),I(584),I(585),I(586),I(587),I(588),I(589),I(590),I(591),I(592),I(593),I(594),I(595),I(596),I(597),I(598),I(599),I(600),I(601),I(602),I(603),I(604),I(605),I(606),I(607),I(608),I(609),I(610),I(611),I(612),I(613),I(614),I(615),I(616),I(617),I(618),I(619),I(620),I(621),I(622),I(623),I(624),I(625),I(626),I(627),I(628),I(629),I(630),I(631),I(632),I(633),I(634),I(635),I(636),I(637),I(638),I(639),I(640),I(641),I(642),I(643),I(644),I(645),I(646),I(647),I(648),I(649),I(650),I(651),I(652),I(653),I(654),I(655),I(656),I(657),I(658),I(659),I(660),I(661),I(662),I(663),I(664),I(665),I(666),I(667),I(668),I(669),I(670),I(671),I(672),I(673),I(674),I(675),I(676),I(677),I(678),I(679),I(680),I(681),I(682),I(683),I(684),I(685),I(686),I(687),I(688),I(689),I(690),I(691),I(692),I(693),I(694),I(695),I(696),I(697),I(698),I(699),I(700),I(701),I(702),I(703),I(704),I(705),I(706),I(707),I(708),I(709),I(710),I(711),I(712),I(713),I(714),I(715),I(716),I(717),I(718),I(719),I(720),I(721),I(722),I(723),I(724),I(725),I(726),I(727),I(728),I(729),I(730),I(731),I(732),I(733),I(734),I(735),I(736),I(737),I(738),I(739),I(740),I(741),I(742),I(743),I(744),I(745),I(746),I(747),I(748),I(749),I(750),I(751),I(752),I(753),I(754),I(755),I(756),I(757),I(758),I(759),I(760),I(761),I(762),I(763),I(764),I(765),I(766),I(767),I(768),I(769),I(770),I(771),I(772),I(773),I(774),I(775),I(776),I(777),I(778),I(779),I(780),I(781),I(782),I(783),I(784),I(785),I(786),I(787),I(788),I(789),I(790),I(791),I(792),I(793),I(794),I(795),I(796),I(797),I(798),I(799),I(800),I(801),I(802),I(803),I(804),I(805),I(806),I(807),I(808),I(809),I(810),I(811),I(812),I(813),I(814),I(815),I(816),I(817),I(818),I(819),I(820),I(821),I(822),I(823),I(824),I(825),I(826),I(827),I(828),I(829),I(830),I(831),I(832),I(833),I(834),I(835),I(836),I(837),I(838),I(839),I(840),I(841),I(842),I(843),I(844),I(845),I(846),I(847),I(848),I(849),I(850),I(851),I(852),I(853),I(854),I(855),I(856),I(857),I(858),I(859),I(860),I(861),I(862),I(863),I(864),I(865),I(866),I(867),I(868),I(869),I(870),I(871),I(872),I(873),I(874),I(875),I(876),I(877),I(878),I(879),I(880),I(881),I(882),I(883),I(884),I(885),I(886),I(887),I(888),I(889),I(890),I(891),I(892),I(893),I(894),I(895),I(896),I(897),I(898),I(899),I(900),I(901),I(902),I(903),I(904),I(905),I(906),I(907),I(908),I(909),I(910),I(911),I(912),I(913),I(914),I(915),I(916),I(917),I(918),I(919),I(920),I(921),I(922),I(923),I(924),I(925),I(926),I(927),I(928),I(929),I(930),I(931),I(932),I(933),I(934),I(935),I(936),I(937),I(938),I(939),I(940),I(941),I(942),I(943),I(944),I(945),I(946),I(947),I(948),I(949),I(950),I(951),I(952),I(953),I(954),I(955),I(956),I(957),I(958),I(959),I(960),I(961),I(962),I(963),I(964),I(965),I(966),I(967),I(968),I(969),I(970),I(971),I(972),I(973),I(974),I(975),I(976),I(977),I(978),I(979),I(980),I(981),I(982),I(983),I(984),I(985),I(986),I(987),I(988),I(989),I(990),I(991),I(992),I(993),I(994),I(995),I(996),I(997),I(998),I(999),I(1000)

```

Table VII-73. Source program listing of subroutine REVO (Link 4)

```

* LABEL
CE4REV          E4RFV000          350 J4B=J4+IJ-11*IT          E4RFV004
SUBROUTINE REVO E4RFV001          J4C=J4+(7-JI4)IT          E4RFV005
FINDS LOCAL AXES BY BEST FIT & 4TH ORDER POLYNOMIAL IN SHELLS OF NYV4REV002          LDOE=0          E4RFV006
TO FIND DIRECTION FOR SHELLS OF REVOLUTION BY 4TH ORDER POLYNOMIAL FIT E4RFV003          DO 355 K=1,IT          E4RFV007
DIMENSION I(41),AA(1),S(1),N(8),D21(2),D33(3),F22(3,3) E4RFV004          L1=J4+K          E4RFV008
1, F(24),UV(24),X(8),Y(8),Z(8),XD(7),YD(7),ZD(7),G(1) E4RFV005          L2=J4+K          E4RFV009
COMMON I,AA,         E4RFV006          L3=J1+K          E4RFV010
EQUIVALENCE (IA,AA),I(21),O(3),I(21),I(1),F22(1),F1, I(21),O(21),G,E4RFV007
EQUIVALENCE (IA(1),IN),IA(21),IBN),IA(31),IT,IA(41),IP,IA(51), E4RFV008
1IPRS),IA(16),ITYPE,IA(71),IPATI,IA(8),IDFG,IA(19),IMX),IA(10),E4RFV009
2IH,IA(11),IR,IA(12),IMMX),IA(13),IMNY),IA(14),IMM2),IA(15),E4RFV010
3IMF),IA(11A),JARE),IA(17),N(11),IA(25),M),IA(26),ITY),IA(127),E4RFV011
4ISTR),IA(128),IEL),IA(29),ITEM),IA(30),ITIC,IA(31),IMET), E4RFV012
5IA(132),ISUM),IA(133),IND),IA(34),INS),IA(36),IOS),IA(37), E4RFV013
6IGRD),IA(38),IORD1),IA(39),ACEL),IA(50),J1,IA(51),J2), E4RFV014
7IA(52),J3),IA(53),J4),IA(54),J5),IA(55),J6),IA(56),J7),IA(57),E4RFV015
8,UB1,IA(58),JTY),IA(59),IBB),IA(60),IBO),IA(61),ID1,IA(62),E4RFV016
9IA),IA(63),IDT),IA(64),IDY),IA(65),ITF),IA(41),IAP) E4RFV017
EQUIVALENCE (IA(66),ICMR),IA(67),ICIX),IA(68),ICIV),IA(69), E4RFV018
1ICIZ),IA(70),ICFI),IA(71),IXX),IA(72),IYY),IA(73),IZZ), E4RFV019
2IA(74),IIL),IA(75),IDEF),IA(76),ISJ),IA(177),IIS) E4RFV020
3,IA(178),IGEM),IA(79),IERR),IA(80),IF1,AA(81),DT),AA(82),DR), E4RFV021
4AA(83),AL1),AA(84),AL2),AA(85),AL3),AA(86),O21),AA(107),P), E4RFV022
5AA(131),UV),AA(135),X),AA(163),Y),AA(171),Z),AA(179),XD), E4RFV023
6AA(186),YD),AA(193),ZD),AA(185),S),AA(160),ZGEM) E4RFV024
7,AA(42),IIP),IA(43),IPB),IA(44),IPEM),AA(45),CONS),AA(46),IUE4RFV025
8),IA(47),G),IA(48),G2),IA(49),G3) E4RFV026
EQUIVALENCE (IA(349),MTC),IA(349),ISDT),IA(347),ISDY),IA(346) E4RFV027
1,ISD2),IA(345),J9),IA(344),J10),IA(343),JPKS),IA(342),JSDY) E4RFV028
2,IA(341),JSD2),IA(340),JARE),IA(339),JMX),IA(338),JMMY) E4RFV029
3,IA(337),JMM2),IA(336),JMF1),IA(335),IAS),IA(334),ID2) E4RFV030
4,IA(333),IPR),AA(332),OCY),AA(331),OG2),AA(330),PKES) E4RFV031
5,IA(329),IPIR) E4RFV032
DIMENSION I(41),S(1),S(13),DIN(3,3),SR(6),X(3),Y(3),ON(6),OF(6), E4RFV033
1RES(6),RED(6),BAS(3),ICLAS(4),NBSAN(10),NU(3),NES(3) E4RFV034
EQUIVALENCE (AA(200),ONE),AA(201),ICN),AA(202),LM),AA(203),AST4RFV035
1),AA(204),INBN),AA(205),ARE),AA(206),ICLA),AA(207),IMFL), E4RFV036
2IA(208),IM),AA(209),IC),AA(210),ICOM),AA(211),ANGLE),AA(212),E4RFV037
3ICAS),AA(213),IF),AA(214),NH),AA(215),MH) E4RFV038
4,IA(216),IROT),IA(217),B5T) E4RFV039
EQUIVALENCE (IA(220),RIR),IA(223),SIR),AA(226),DIN),AA(235),SR)E4RFV040
1,AA(241),XN),AA(244),XF),AA(247),DM),AA(253),OF),AA(259),RES)E4RFV041
2,AA(265),RED),AA(271),BAS),AA(274),ICLAS),AA(278),NBSAN) E4RFV042
3,AA(297),NU),AA(295),NES) E4RFV043
DIMENSION NEL(20,17),MAC(6,4,20),IWC(90),DO(6,6),A(90,7),R(8,R), E4RFV044
1C(8,2),JF(1),NSET(100),MSET(100),W(2,3) E4RFV045
EQUIVALENCE (AA(1400),FF),NU(1),JP1),NU(2),JM),NU(3),JS1) E4RFV046
EQUIVALENCE (FF(11),NEL),FF(341),MAC),FF(661),IWC),FF(1751),DD), E4RFV047
1,FF(1787),A1),FF(1471),B1),FF(1481),C1),FF(1497),NSET),FF(1597), E4RFV048
2MSET),FF(1697),W) E4RFV049
DIMENSION XII(3),ETA(3),ZTA(3) E4RFV050
EQUIVALENCE (DIN(1),XII),DIN(4),ETA),DIN(7),ZTA) E4RFV051
FIND THE FIRST AND THE LAST NUDE TO BE CONSIDERED FOR THE FIT E4RFV052
I=1 E4RFV053
IC=IC E4RFV054
I17M)=MET+1700 E4RFV055
I18M)=MET+1800 E4RFV056
LL=0 E4RFV057
IE=MAC(1M,IC,1) E4RFV058
IF (IE=1) 100,100,200 E4RFV059
IEL=MAC(1M,IC,2) E4RFV060
IF (NEL(IELT,10)-ICN) 102,101,102 E4RFV061
100 KL=1 E4RFV062
KR=2 E4RFV063
LL=1 E4RFV064
NSET(KL)=ICN E4RFV065
NSET(KR)=NEL(IELT,11) E4RFV066
GO TO 300 E4RFV067
102 KL=4 E4RFV068
KR=5 E4RFV069
NSET(KL)=NEL(IELT,10) E4RFV070
NSET(KR)=ICN E4RFV071
GO TO 300 E4RFV072
200 I=2 E4RFV073
IEL=MAC(1M,IC,1) E4RFV074
IF (NEL(IELT,10)-ICN) 202,201,202 E4RFV075
201 NSET(3)=ICN E4RFV076
NSET(4)=NEL(IELT,11) E4RFV077
GO TO 210 E4RFV078
202 NSET(3)=ICN E4RFV079
NSET(2)=NEL(IELT,10) E4RFV080
210 IF (I=3) 215,216,216 E4RFV081
215 I=3 E4RFV082
GO TO 220 E4RFV083
216 KL=2 E4RFV084
KR=4 E4RFV085
DO 300 I=1,3 E4RFV086
IF (KL=1) 301,301,302 E4RFV087
302 J=2 E4RFV088
NDDI=NSET(KL) E4RFV089
GO TO 350 E4RFV090
301 IF (KR=5) 303,400,400 E4RFV091
303 J=1 E4RFV092
NDDI=NSET(KR) E4RFV093

```


Table VII-74. Source program listing of subroutine ROTA (Link 4)

```

* LABEL
CE&KOT SUBROUTINE ROTA F4R0T000 C IF (1.-ABS(FIAG)-1.E-4) 200,200,101 F4R0T045
C EXPRESSES MATERIAL MATRIX IN LOCAL AXES F4R0T001 C NDN=SOLID, MATERIAL AXES ARE (ZTAXBAS)XZTA,ZTAXBAS,7TA F4R0T066
C TO ROTATE MATERIAL AXES IF NECESSARY SO THAT THEY COINCIDE W. DIM F4R0T003 CALL VECT IT,ZTA,BAS1 F4R0T068
C DIMENSION (A(1),A(1),S(1),N(4),D(2),D(2),D(3),D(3),F(2),F(3)) F4R0T004 CALL UNIT (T,CC) F4R0T069
1,P(24),UV(24),X(R),Y(B),Z(L),XD(7),YD(7),ZD(7),G(1)) F4R0T005 CALL VECT ISI,T,ZTA F4R0T070
COMMON IA,AA F4R0T006 CALL UNIT (SI,CC) F4R0T071
EQUIVALENCE (IA,AA),(D21,D33),(D22),(D11),E22),(D21(19),E1,(D21(20),G F4R0T007 DD 14 I=1,3 F4R0T073
EQUIVALENCE (IA(1),IM),(IA(2),IMN),(IA(3),IT),(IA(4),IP),(IA(5), F4R0T008 DD 14 J=1,3 F4R0T074
1IPAS),(IA(6),ITYPE),(IA(7),IMAT),(IA(8),IDEG),(IA(9),INX),(IA(10), F4R0T009 MI,J)=0 F4R0T075
2IH),(IA(11),IB),(IA(12),IMX),(IA(13),IMMY),(IA(14),IMW),(IA(15),F4R0T010 DD 15 K=1,3 F4R0T076
3IMF),(IA(16),IARH),(IA(17),N(1)),(IA(25),M),(IA(26),ITY),(IA(27),F4R0T011 15 MI,J)=0/(DINIK,I)*V(K,J) F4R0T077
4ESTR),(IA(28),IELT),(IA(29),ITEM),(IA(30),ITIC),(IA(31),IMET), F4R0T012 CONTINUE F4R0T078
5IA(32),ISUM,(IA(33),IND),(IA(34),IMS),(IA(36),IDS),(IA(37), F4R0T013 GO TO 16 F4R0T079
6IORD),(IA(38),IORD1),(IA(39),ACEL),(IA(50),J1),(IA(51),J2), F4R0T014 C SULLO MATERIAL AXES ARE PARALLEL TO OVERALL SYSTEM, F4R0T080
7IA(52),J3),(IA(53),J4),(IA(54),J5),(IA(55),J6),(IA(56),J7),(IA(57),F4R0T015 DD 13 I=1,3 F4R0T081
8),J8),(IA(58),JTY),(IA(59),IBB),(IA(60),IBO),(IA(61),ID1),(IA(62),F4R0T016 DD 13 J=1,3 F4R0T082
9IA),(IA(63),IDT),(IA(64),IDY),(IA(65),ITE),(IA(64),ITAF) F4R0T017 W(I,J)=0/(N(I,J)) F4R0T083
EQUIVALENCE (IA(66),ICAR),(IA(67),ICIX),(IA(68),ICIV),(IA(69), F4R0T018 GO TO 16 F4R0T084
11C1Z),(IA(70),ICFI),(IA(71),IXX),(IA(72),IYY),(IA(73),IZZ), F4R0T019 C GENERATE R OF (R)TRANS*(DD)*(R) F4R0T085
2IA(74),ICD),(IA(75),IDEF),(IA(76),IST),(IA(77),IISI) F4R0T020 DD 17 J=1,3 F4R0T086
3IA(78),IDEM),(IA(79),IERR),(IA(80),TE),(IA(81),D1),(IA(82),D5), F4R0T021 DD 17 I=1,3 F4R0T087
4IA(83),AL1),(IA(84),AL2),(IA(85),AL3),(IA(86),O21),(IA(87),P), F4R0T022 R(I,J)=W(I,J)**2 F4R0T088
5IA(88),UV),(IA(89),X),(IA(90),Y),(IA(91),Z),(IA(92),XD),(IA(93),XD), F4R0T023 DD 18 I=1,3 F4R0T089
6IA(94),YD),(IA(95),ZD),(IA(96),S),(IA(97),ZGEM) F4R0T024 R(I,4)=W(I,1)*W(I,2) F4R0T090
7IA(98),JNP),(IA(99),IPB),(IA(100),JPN),(IA(101),CONS),(IA(102), F4R0T025 R(I,5)=W(I,1)*W(I,3) F4R0T091
8IA(103),GL),(IA(104),G2),(IA(105),G3) F4R0T026 R(I,6)=W(I,2)*W(I,3) F4R0T092
EQUIVALENCE (IA(106),NIC),(IA(107),ISDT),(IA(108),ISDY),(IA(109), F4R0T027 R(I,4)=W(I,1)*W(I,2)**2 F4R0T093
1,ISDZ),(IA(110),J9),(IA(111),J10),(IA(112),JPR),(IA(113),JSDY) F4R0T028 R(I,5)=W(I,1)*W(I,3)**2 F4R0T094
2,IA(114),JSDZ),(IA(115),JRF),(IA(116),JMK),(IA(117),JMW) F4R0T029 R(I,6)=W(I,2)*W(I,3)**2 F4R0T095
3,IA(118),JMM),(IA(119),JMT),(IA(120),JTS),(IA(121),JNZ) F4R0T030 R(4,4)=W(1,1)*W(2,2)+W(2,1)*W(1,2) F4R0T096
4,IA(122),JPR),(IA(123),JOG),(IA(124),JOG),(IA(125),JOG) F4R0T031 R(4,5)=W(1,1)*W(2,3)+W(2,1)*W(1,3) F4R0T097
5,IA(126),JPR) F4R0T032 R(4,6)=W(1,2)*W(2,3)+W(2,2)*W(1,3) F4R0T098
DIMENSION BIR(3),SIR(3),DIR(3),SR(4),XN(3),XF(3),ONI(6),OF(6), F4R0T033 R(5,4)=W(1,1)*W(3,2)+W(3,1)*W(1,2) F4R0T099
1RES(6),RED(6),BAS(3),TCLAS(4),NBAN(10),NU(3),NES(3) F4R0T034 R(5,5)=W(1,1)*W(3,3)+W(3,1)*W(1,3) F4R0T100
EQUIVALENCE (IA(127),IDNE),(IA(128),ICW),(IA(129),ICW),(IA(130),AST) F4R0T035 R(5,6)=W(1,2)*W(3,3)+W(3,2)*W(1,3) F4R0T101
1),(IA(131),INRW),(IA(132),ARE),(IA(133),ICL),(IA(134),IMEL), F4R0T036 R(6,4)=W(2,1)*W(3,2)+W(3,1)*W(2,2) F4R0T102
2IA(135),IM),(IA(136),ICI),(IA(137),ICD),(IA(138),ANGLE),(IA(139), F4R0T037 R(6,5)=W(2,1)*W(3,3)+W(3,1)*W(2,3) F4R0T103
3ICAS),(IA(140),JE),(IA(141),NR),(IA(142),NR) F4R0T038 R(6,6)=W(2,2)*W(3,3)+W(3,2)*W(2,3) F4R0T104
4,(IA(143),IROT),(IA(144),RST) F4R0T039 DD 21 I=1,6 F4R0T105
EQUIVALENCE (IA(145),BIR),(IA(146),SIR),(IA(147),DIR),(IA(148),SR) F4R0T040 TIJ=0 F4R0T106
1,(IA(149),XN),(IA(150),XF),(IA(151),ONI),(IA(152),OF),IA(153),RFS) F4R0T041 DD 23 K=1,6 F4R0T107
2,(IA(154),RED),(IA(155),BAS),(IA(156),TCLAS),(IA(157),NBAN),(IA(158), F4R0T042 T(I,J)=((J+DDI)*K)*R(K,J) F4R0T108
3,(IA(159),NU),(IA(160),NES) F4R0T043 CONTINUE F4R0T109
DIMENSION NEL(20,17),MAC(4,4,20),IMG(90),D(16,6),A(90,7),R(8,8), F4R0T044 DD 24 J=1,6 F4R0T110
IC(R,2),FF(1),NSET(100),MSET(100),M(3,3) F4R0T045 DD(I,J)=T(I,J) F4R0T111
EQUIVALENCE (IA(161),FF),(IA(162),N),(IA(163),IND),(IA(164),JMI),(IA(165),JSL) F4R0T046 CONTINUE F4R0T112
EQUIVALENCE (FF(1),NEL),(FF(2),MAC),(FF(3),IMG),(FF(4),D),(FF(5),DD), F4R0T047 DD 31 J=1,5 F4R0T113
1FF(78),4),(FF(141),B),(FF(142),C),(FF(143),NSF),(FF(144),NSF) F4R0T048 DD 32 I=1,6 F4R0T114
2MSET),(FF(169),M) F4R0T049 TIJ=0 F4R0T115
DIMENSION X1(3),ETA(3),ZTA(3) F4R0T050 DD 33 K=1,6 F4R0T116
EQUIVALENCE (D(1),X1),(D(2),ETA),(D(3),ZTA) F4R0T051 T(I)=T(I)*R(K,I)*DD(K,J) F4R0T117
DIMENSION R(6,6),T(6),V(3,3),S(1),R(1) F4R0T052 CONTINUE F4R0T118
EQUIVALENCE (A(1),R),(A(2),T),(A(3),V),(A(4),S),(A(5),T),(A(6),R) F4R0T053 F4R0T119
NO ROTATION IF MATERIAL IS ISOTROPIC F4R0T054 DD 34 I=1,6 F4R0T120
IF (ITYPE) 200,200,9 F4R0T055 CONTINUE F4R0T121
SEE IF SOLID F4R0T056 DD(I,J)=T(I,J) F4R0T122
IF (ICAS=3) 10,11,10 F4R0T057 C DIRECTION COSINES OF NEW MATE. AXES IN THE OLD ARE IN W(3,3) F4R0T123
IF (ICAS=4) 12,11,12 F4R0T058 IF (INP=2) 200,19,19 F4R0T124
IF SHELL OF REVOLUTION, DO NOT TRANSFORM F4R0T059 19 WRITE OUTPUT TAPE 6,19,1,((R(I,J),J=1,6),I=1,6) F4R0T125
IF (ICAS=5) 12,1,200,121 F4R0T060 191 FORMAT (20X,57#POSTMULTIPLYING MATRIX IN MATERIAL TRANSFORMATION F4R0T126
IF (ICAS=6) 4,1,200,41 F4R0T061 10LLWS/(20X,6F12,5) F4R0T127
COMPUTE THE ANGLE BETWEEN BAS AND KSI F4R0T062 RETURN F4R0T128
ANG=SCAL(BAS,KSI) F4R0T063 END F4R0T129
NO ROTATION IF THE ANGLE IS SMALL F4R0T064

```

Table VII-75. Source program listing of subroutine SAME (Link 4)

```

* LABEL
CE4SAM SUBROUTINE SAME F4SAM000
EXPRESSES STRESS TENSOR IN OVERALL COORDINATE SYSTEM F4SAM001
DIMENSION IA(1),AA(11,51),N(R),M(121),D33(3,3),E22(3,3) F4SAM002
1,PI24),UV(24),X(R),Y(R),Z(R),XD(7),YD(7),ZD(7),RL(1) F4SAM004
COMMON IA,AA F4SAM005
EQUIVALENCE (IA(1),I), (IA(2),J), (IA(3),I1), (IA(4),I2), (IA(5), F4SAM006
EQUIVALENCE (IA(11),I), (IA(12),J), (IA(13),I1), (IA(14),I2), (IA(15), F4SAM007
1)PRS), (IA(16),ITYPE), (IA(17),IMAT), (IA(18),IDEG), (IA(19),INX), (IA(10), F4SAM008
2)H), (IA(11),IR), (IA(12),IMX), (IA(13),IMY), (IA(14),IMZ), (IA(15), F4SAM009
3)MF), (IA(16),IARE), (IA(17),N(1)), (IA(25),M), (IA(26),ITY), (IA(27), F4SAM010
4)STR), (IA(28),IEL), (IA(29),ITEM), (IA(30),ITIC), (IA(31),IM1), F4SAM011
5)IA(32),ISUM), (IA(33),IND), (IA(34),IMS), (IA(36),IOS), (IA(37), F4SAM012
6)ORD), (IA(38),FORD), (IA(39),ACFL), (IA(50),J1), (IA(51),J2), F4SAM013
7)IA(52),J1), (IA(53),J2), (IA(54),J3), (IA(55),J4), (IA(56),J7), (IA(57), F4SAM014
8),J8), (IA(58),J9), (IA(59),J8), (IA(60),I0), (IA(61),I10), (IA(62), F4SAM015
9)IA), (IA(63),IDT), (IA(64),IDY), (IA(65),ITE), (IA(61),ITAP), F4SAM016
EQUIVALENCE (IA(66),ICAR), (IA(67),ICIX), (IA(68),ICIX), (IA(69), F4SAM017
1)CIZ), (IA(70),ICFI), (IA(71),ICX), (IA(72),IYY), (IA(73),IZZ), F4SAM018
2)IA(74),IIC), (IA(75),IDFF), (IA(76),IST), (IA(77),IIS), F4SAM019
3), (IA(78),IGF), (IA(79),IER), (IA(80),TF), (IA(81),DT), (AA(82),BG), F4SAM020
4)IA(83),AL1), (AA(84),AL2), (AA(85),AL3), (AA(86),AL4), (AA(107),P), F4SAM021
5)AA(131),UV), (AA(155),X), (AA(163),Y), (AA(171),Z), (AA(179),XD), F4SAM022
6)AA(186),YD), (AA(193),ZD), (AA(351),S), (AA(401),ZGM), F4SAM023
7), (AA(42),INP), (AA(43),IPBG), (AA(44),IPEN), (AA(45),CONS), (AA(46),IHF), F4SAM024
8), (AA(47),G1), (AA(48),G2), (AA(49),G3), F4SAM025
EQUIVALENCE (IA(349),NTIC), (IA(348),ISDT), (IA(347),ISDY), (IA(346), F4SAM026
1),SDZ), (IA(345),J9), (IA(344),J10), (IA(343),PRS), (IA(342),JSDY), F4SAM027
2), (IA(341),I), (IA(340),JME), (IA(339),JMM), (IA(338),DMY), F4SAM028
3), (IA(337),JMMZ), (IA(336),JMF), (IA(335),I4S), (IA(334),ID7), F4SAM029
4), (IA(333),IPR), (AA(332),OGY), (AA(331),UGZ), (AA(330),PRS), F4SAM030
5), (IA(329),IPR), F4SAM031
DIMENSION BIR(3),SIR(3),DIR(3,3),SR(6),XN(3),XF(3),ON(6),OF(6), F4SAM032
1)RES(6),RED(6),BAS(2),ICLAS(4),NBA(101),MUI(3),NFS(3), F4SAM033
EQUIVALENCE (AA(200),I0N), (AA(201),ICM), (AA(202),LM), (AA(203),AST), F4SAM034
1), (AA(204),INBDN), (AA(205),ARE), (AA(206),ICLA), (AA(207),IMEL), (M(1), F4SAM035
2)AA(208),IM), (AA(209),IC), (AA(210),ICOM), (AA(211),ANGLE), (AA(212), F4SAM036
3)ICAS), (AA(213),IF), (AA(214),NB), (AA(215),MB), F4SAM037
4), (AA(216),IROT), (AA(217),BST), F4SAM038
EQUIVALENCE (AA(220),BIR), (AA(223),STR), (AA(226),OIN), (AA(235),SR), F4SAM039
1), (AA(241),XN), (AA(244),XF), (AA(247),DM), (AA(253),OF), (AA(259),RES), F4SAM040
2), (AA(265),RED), (AA(271),NAS), (AA(274),ICLAS), (AA(278),NBA), F4SAM041
3), (AA(292),MUI), (AA(295),MES), F4SAM042
DIMENSION NEL(20,17),MAC(4,4,20),IMG(90),ND(6,6),A(90,7),R(R,R), F4SAM043
1)C(B,2),FF(1),NSET(100),MSET(100),W(3,3), F4SAM044
EQUIVALENCE (AA(14000),FF), (MUI(1),J1), (MUI(2),J2), (MUI(3),J3), F4SAM045
EQUIVALENCE (FF(1),NEL), (FF(134),MAC), (FF(661),IMG), (FF(751),ND), F4SAM046
1)FF(757),4), (FF(1417),B), (FF(1481),C), (FF(1497),NSET), (FF(1597), F4SAM047
2)MSET), (FF(1597),W), F4SAM048
EQUIVALENCE (MES(1),ICDL), (MES(2),IRIG), (MES(3),IDR), F4SAM049
DIMENSION DMM(3,3),DMM(3,3), F4SAM050
EQUIVALENCE (A(1),DMM), (A(10),DMM), F4SAM051
NO COMPUTATION IF OVERALL COORDINATES ARE IDENTICAL WITH LOCAL F4SAM052
TEST=7H A F4SAM053
IF (B5)-TEST=110,1000,110 F4SAM054
NO COMPUTATION IF IT IS A SHELL POINT F4SAM055
110 IF (ICAS=4) 111,111,1000 F4SAM056
C IF IT IS A PLATE NOTE THE SHIFT IN RED VECTOR F4SAM057
111 IF (ICAS=2) 112,112,112 F4SAM058
112 DMM(1,1)=RED(1) F4SAM059
DMM(1,2)=RED(2) F4SAM060
DMM(1,3)=RED(3) F4SAM061
DMM(2,2)=RED(2) F4SAM062
DMM(2,3)=RED(3) F4SAM063
DMM(3,3)=RED(4) F4SAM064
GO TO 114 F4SAM065
113 DMM(1,1)=RED(1) F4SAM066
DMM(1,2)=RED(2) F4SAM067
DMM(1,3)=RED(3) F4SAM068
DMM(2,3)=0. F4SAM069
DMM(3,3)=0. F4SAM070
DMM(3,3)=0. F4SAM071
C OBTAIN THE SYMMETRIC PART F4SAM072
114 DO 200 I=1,3 F4SAM073
DO 200 J=1,3 F4SAM074
200 DMM(I,J)=DMM(I,J) F4SAM075
C PERFORM THE TRANSFORMATION USING THE DIR MATRIX F4SAM076
DO 400 I=1,3 F4SAM077
DO 400 J=1,3 F4SAM078
DMM(I,J)=0. F4SAM079
DO 300 K=1,3 F4SAM080
300 DMM(I,J)=DMM(I,J)+DIR(I,K)*DMM(K,J) F4SAM081
400 CONTINUE F4SAM082
DO ADD I=1,3 F4SAM083
DO 600 J=1,3 F4SAM084
DMM(I,J)=0. F4SAM085
DO 500 K=1,3 F4SAM086
500 DMM(I,J)=DMM(I,J)+DMM(I,K)*DIR(J,K) F4SAM087
600 CONTINUE F4SAM088
C REARRANGE SR NOTING THE SHIFT IN PLATE CASE F4SAM089
IF (ICAS=2) 650,700,650 F4SAM090
700 SR(1)=0. F4SAM091
SR(2)=0. F4SAM092
SR(3)=0. F4SAM093
SR(4)=DMM(1,1) F4SAM094
SR(5)=DMM(2,2) F4SAM095
SR(6)=DMM(1,2) F4SAM096
GO TO 750 F4SAM097
620 SR(1)=DMM(1,1) F4SAM098
SR(2)=DMM(2,2) F4SAM099
SR(3)=DMM(3,3) F4SAM100
SR(4)=DMM(1,2) F4SAM101
SR(5)=DMM(1,3) F4SAM102
SR(6)=DMM(2,3) F4SAM103
C PRINT THE RESULTS AND RETURN F4SAM104
750 WRITE OUTPUT TAPE 6,1,ICN,AST,IMET,ICAS,(SR(1),I=1,6) F4SAM105
1 FORMAT (15,A1,14,15,X,6E15.5) F4SAM106
1000 RETURN F4SAM107
END F4SAM108

```

Table VII-76. Source program listing of function SCAL (Link 4)

```

* LABEL
CE4SCL FUNCTION SCAL(CIR,DIR) F4SCL000
PERFORMS SCALAR VECTOR PRODUCT F4SCL001
C TO OBTAIN THE SCALAR PRODUCT OF VECTORS CIR AND DIR ON SCAL F4SCL002
C DIMENSION CIR(3),DIR(3) F4SCL003
SCAL=CIR(1)*DIR(1)+CIR(2)*DIR(2)+CIR(3)*DIR(3) F4SCL004
RETURN F4SCL005
END F4SCL007

```

Table VII-77. Source program listing of subroutine SETA (Link 4)

```

* LABEL
CE4SET          E4SET000      14 DROT(IK)=REC(I)
SUBROUTINE SETA E4SET001      C CONTINUE
GENERATES STRAIN-DEFLECTION RELATIONSHIP AT A NODAL LINE E4SET002      TRANSFORM COORDINATES AND DEFLEMS INTO LOCAL IF NECESSARY
DIMENSION IA(1),AA(1),S(1),N(1),D21(2),D33(3),S1+72(3,3) E4SET003      IF (IRHT) 25,24,25
1,P(24),UV(24),X(1),Y(1),Z(1),XD(7),YD(7),ZD(7),G(1) E4SET004      DO 26 J=1,5
COMMON IA,AA E4SET005      DO 27 I=1,3
EQUIVALENCE(IA,AA),(D21(33),(D21(10),F221,(D21(19),E),(D21(20),G) E4SET006      SIR(I)=0.
EQUIVALENCE (IA(1),IN),(IA(2),IBN),(IA(3),IT),(IA(4),IP),(IA(5), F4SET007      DO 28 L=1,3
1IPRS),(IA(6),ITYPE),(IA(7),IMAT),(IA(8),IDRG),(IA(9),IMX),(IA(10),E4SET008      SIR(I)=SIR(I)+DIN(L)+U(L),J)
2H),(IA(11),IR),(IA(12),IMM),(IA(13),IMMY),(IA(14),IMZ),(IA(15),F4SET009      CONTINUE
3IMF),(IA(16),IARE),(IA(17),N11),(IA(25),M),(IA(26),ITY),(IA(27),E4SET010      DO 29 I=1,3
4ISTR),(IA(28),IELT),(IA(29),IEM),(IA(30),ITIC),(IA(31),IMET), F4SET011      U(I,J)=SIR(I)
5(IA(32),ISUM),(IA(33),IND),(IA(34),IMS),(IA(36),DS),(IA(37), F4SET012      CONTINUE
6IORD),(IA(38),IORO),(IA(39),ACEL),(IA(50),J1),(IA(51),J2), F4SET013      ICON=ICON+1
7(IA(52),J3),(IA(53),J4),(IA(54),J5),(IA(55),J6),(IA(56),J7),(IA(57),E4SET014      ICOL=ICOL
8),J8),(IA(58),JTY),(IA(59),IB),(IA(60),IBO),(IA(61),IBD),(IA(62),F4SET015      DCAR(1)=DCAR(1)
9(IA),(IA(63),ID),(IA(64),IDY),(IA(65),IFE),(IA(61),ITAP) F4SET016      DCAR(2)=DCAR(2)
EQUIVALENCE (IA(66),ICAR),(IA(67),ICF),(IA(68),ICLY),(IA(69), E4SET017      DCAR(3)=DCAR(3)
1IC1),(IA(70),ICF1),(IA(71),IC1X),(IA(72),IY),(IA(73),I22), F4SET018      CL=1.
2(IA(74),IC),(IA(75),IDFF),(IA(76),IST),(IA(77),ITS) E4SET019      CALL UNIT(OCAR,CL)
3,(IA(78),IGEM),(IA(79),IERR),(AA(80),TE),(AA(81),DT),(AA(82),DC) E4SET020      GENERATE LEFTHAND SIDE
4(AA(83),AL1),(AA(84),AL2),(AA(85),AL3),(AA(86),D21),(AA(107),P), F4SET021      DO 30 I=1,ICOL
5(AA(131),UV),(AA(135),X),(AA(136),Y),(AA(171),Z),(AA(179),XD), F4SET022      J=I
6(AA(186),YD),(AA(193),ZD),(AA(351),S),(AA(401),ZGEM) F4SET023      I2=I
7,(AA(142),IPB),(AA(143),IPB1),(AA(44),IPB),(AA(45),CONS),(AA(46),TUE4SET024      IS=I
8),(AA(47),G1),(AA(48),G2),(AA(49),G3) E4SET025      GO TO (37,37,31,32,33,34),IS
EQUIVALENCE (IA(349),NTIC),(IA(348),ISDT),(IA(347),ISDY),(IA(346) E4SET026      I1=1
1,ISDZ),(IA(345),J9),(IA(344),J10),(IA(343),JPRS),(IA(342),JSOY) E4SET027      I2=2
2,(IA(341),JSOZ),(IA(340),JARE),(IA(339),JMX),(IA(338),JMY) E4SET028      GO TO 37
3,(IA(337),JMMZ),(IA(336),JMF),(IA(335),IAS),(IA(334),I0Z) F4SET029      I3=3
4,(IA(333),IPR),(AA(332),OCY),(AA(331),OG2),(AA(330),PRES) F4SET030      I2=3
5,(IA(329),IPR) F4SET031      GO TO 37
DIMENSION BIR(3),SIR(3),DIN(3),SR(6),XN(3),XF(3),ONI(6),DF(6), E4SET032      I1=1
1,NES(6),RED(6),BAS(3),ICLAS(4),NBN(10),NU(3),NES(3) E4SET033      I2=3
EQUIVALENCE (AA(200),IONF),(AA(201),ICN),(AA(202),LM),(AA(203),AST) F4SET034      GO TO 37
1),(AA(204),INBN),(AA(205),AKE),(AA(206),ICLA),(AA(207),IMEL), F4SET035      I1=2
2(AA(208),IM),(AA(209),IC),(AA(210),ICOL),(AA(211),ANGLE),(AA(212), F4SET036      I2=3
3,CAS),(AA(213),IE),(AA(214),AM),(AA(215),MB) F4SET037      I3=3
4,(AA(216),IROT),(AA(217),KST) E4SET038      GO TO 37
EQUIVALENCE (AA(220),RIR),(AA(223),SIR),(AA(226),DIN),(AA(235),SR) E4SET039      I1=1
1,(AA(241),XN),(AA(244),XF),(AA(247),ON),(AA(253),OF),(AA(259),RS) E4SET040      RED(1)=0.
2,(AA(265),RED),(AA(271),BAS),(AA(274),ICLAS),(AA(278),NRAN) F4SET041      RED(2)=0.
3,(AA(292),NU),(AA(295),NES) F4SET042      RED(3)=1.
DIMENSION NEL(20),MAC(4,4,20),ING(40),DRI(6,6),A(9,7),B(8,8), E4SET043      GENERATE RIGHAND SIDE(S)
1C(18,2),FF(1),MSET(100),MSET(100),MSET(100),MSET(100),DCAR(3) E4SET044      JRI8=I8I6
EQUIVALENCE (IA(1400),FF),(NU(11),J1),(NU(12),J1),(NU(3),J5) E4SET045      DO 40 I=1,IRIG
EQUIVALENCE (FF(1),NEL),(FF(341),MAC),(FF(461),IWG),(FF(751),DO), E4SET046      ICL=ICOL+1
1(FF(787),A),(FF(1417),B),(FF(1481),C),(FF(1497),MSET),(FF(1597), F4SET047      IF (I-1) 45,45,50
2MSET),(FF(1697),W) E4SET048      IF (IDR) 50,46,50
DIMENSION U(3,5),CDIS(3),CROT(3),ODIS(3),DROT(3),DCOR(3),ZTA(3) E4SET049      LINEAR STRAIN CASE
EQUIVALENCE (X(1),U,DCOR),(X(4),CDIS),(X(7),CROT),(X(10),ODIS) E4SET050      CC=0.
1(X(13),DROT),(DCAR,XF) F4SET051      IF (DT) 47,49,47
EQUIVALENCE (NES(1),ICOL),(NES(2),TRIG),(NES(3),IDR),(DINI(7),ZTA) E4SET052      IF (ITYPE) 48,47,48
C INITIALIZE F4SET053      CALL ALLDOT
IELT=IELT F4SET054      GO TO 49
IMS=NEL(IELT,5) F4SET055      CALL TEMP(CC)
C GENERATE STRAIN-DEFLECTION EQUATIONS FOR EVERY NODAL LINE F4SET056      CC=CC+DT
DO 12 II=1,IMS E4SET057      A(ICON,ICL)=SCALIDD(DCAR)/CL-CC
K=NEL(IELT,II+9) E4SET058      GO TO 40
IF IK=ICN(13,12,13) E4SET059      CHANGE OF CURVATURE CASE
C FIND RELATIVE COORDINATES AND DEFLEMS OF NODE K IN OVERALL SYSTEM F4SET060      CC=0.
13 CALL FINDX(K,XF) F4SET061      IF (DG) 57,59,57
CALL FINDY(K,YF) F4SET062      IF (IITYPE) 58,57,58
DO L61 I=1,15 F4SET063      CC=ALLDGG
161 X(1)=0. F4SET064      GO TO 59
DCOR(1)=XF(1)-XN(1) E4SET065      CALL TEMP(CC)
DCOR(2)=XF(2)-XN(2) F4SET066      CC=CC+DG
DCOR(3)=XF(3)-XN(3) F4SHTOA7      DC=SCALIDROT(DCAR)
JDEG=IDEG E4SET068      DO 592 J=1,3
DO 14 I=1,IDEG F4SET069      DROT(I)=DROT(I)+DC*DCAR(J)
14 RFD(I)=OF(I)-ONI(I) E4SET070      CALL VECT (SIR,RED,DCAR)
SEPARATE DEFLECTIONS INTO DISPLACEMENTS AND ROTATIONS E4SET071      DC=1.
K=0 E4SET072      CALL UNIT(SIR,DC)
IF (ICAS=2) 16,15,16 F4SET073      DC=SCAL(SIR,BRUI)/CL
K=1 E4SET074      A(ICON,ICL)=DC-CC
IF (ICAS=6) 18,17,18 F4SET075      CONTINUE
GO TO 18 F4SET076      IWS(ICON)=1
16 K=3 F4SET077      MB=MB
GO TO 18 F4SET078      IF (INBN) 71,70,71
17 K=3 F4SET079      DO 72 I=1,MB
DO 19 I=1,IDEG F4SET080      IF (INBN(I)-K) 72,73,72
IK=1 F4SET081      CONTINUE
IF (I-KB121,20,20) F4SET082      GO TO 70
IF (I-KS) F4SET083      IWS(ICON)=10
20 IK=KS F4SET084      IF (INP=2) 12,61,61
21 IF (I-K-3) 22,22,23 F4SET085      WRITE OUTPUT TAPE 6,62,ICN,K,(A(ICON,J),J=1,7),IWG(ICON)
22 CDIS(IK)=ONI(I) E4SET086      FORMAT (15,3X,2HTO,15,5X,7F13.5,15)
DDIS(IK)=RED(I) E4SET087      CONTINUE
GO TO 19 F4SET088      RETURN
IK=IK-3 F4SET089      END
CROT(IK)=ON(I)

```

Table VII-78. Source program listing of subroutine STRA (Link 4)

```

* LABEL
CE4STA SUBROUTINE STRA F45TA000
COORDINATE TRANSFORMATION FOR STIFFNESS MATRIX F45TA001
DIMENSION I(41),AA(1),S(1),N(1),D2(21),D3(3),E(22),Z(3) F45TA002
1,P(24),UV(24),X(8),Y(8),Z(8),XD(7),YD(7),ZD(7),G(1) F45TA004
COMMON IA,AA F45TA005
EQUIVALENCE (IA,AA),(D21,D33),(D2110),F22,(D2119),E,(D2120),G F45TA006
EQUIVALENCE (IA11),IN1,(IA(2),IBN),(IA(3),IT),(IA(4),IP),(IA(5), F45TA007
1PRS),(IA(6),ITYPE),(IA(7),IMAT),(IA(8),IDFG),(IA(9),INX),(IA(10), F45TA008
2IH),(IA(11),IAR),(IA(12),IMX),(IA(13),IMY),(IA(14),IMZ),(IA(15), F45TA009
3IMF),(IA(16),IARE),(IA(17),I(13)),(IA(25),M),(IA(26),ITY),(IA(27), F45TA010
4ISTR),(IA(28),IELT),(IA(29),ITEM),(IA(30),ITIC),(IA(31),IMFT) F45TA011
5IA(32),ISUM),(IA(33),IND),(IA(34),IMS),(IA(36),IDS),(IA(37), F45TA012
6IORD),(IA(38),IORD1),(IA(39),ACEL),(IA(50),J1),(IA(51),J2), F45TA013
7IA(52),J3),(IA(53),J4),(IA(54),J5),(IA(55),J6),(IA(56),J7),(IA(57), F45TA014
8I,JR),(IA(58),JTY),(IA(59),IRB),(IA(60),IRI),(IA(61),IIO),(IA(62), F45TA015
9IA(63),IDT),(IA(64),IDY),(IA(65),ITE),(IA(61),ITAP) F45TA016
EQUIVALENCE (IA(68),ICAR),(IA(67),ICIX),(IA(68),ICIV),(IA(69), F45TA017
1ICIZ),(IA(70),IEF),(IA(71),IXX),(IA(72),IYY),(IA(73),IZZ), F45TA018
2IA(74),IIC),(IA(75),IDFF),(IA(76),IST),(IA(77),IIS) F45TA019
3,(IA(78),IGEM),(IA(79),IERK),(AA(80),TE),(AA(81),DT),(AA(82),DC) F45TA020
4AA(83),AL1),(AA(84),AL2),(AA(85),AL3),(AA(86),D21),(AA(87),P) F45TA021
5AA(131),UV),(AA(135),X),(AA(136),Y),(AA(137),Z),(AA(139),XD) F45TA022
6AA(138),YD),(AA(143),ZD),(AA(151),S),(AA(140),ZGEM) F45TA023
7AA(42),INP),(AA(43),IPRS),(AA(44),IPENT),(AA(45),COMS),(AA(46),IUF F45TA024
8),(AA(47),G1),(AA(48),G2),(AA(49),G3) F45TA025
EQUIVALENCE (IA(349),NTIC),(IA(348),ISD1),(IA(347),ISD2),(IA(346) F45TA026
1,ISD2),(IA(345),J9),(IA(344),J10),(IA(343),JPRS),(IA(342),JSDY) F45TA027
2,(IA(341),JSDZ),(IA(340),JARP),(IA(339),JMMX),(IA(338),JMY) F45TA028
3,(IA(337),JMMZ),(IA(336),JMF),(IA(335),ITAS),(IA(334),IDT) F45TA029
4,(IA(333),IPR),(IA(332),DGY),(IA(331),DGZ),(AA(330),PRES) F45TA030
J=IOS F45TA031
DO 5 I=1,IDS F45TA032
J=J+IDS F45TA033
CALL TRAN (S,J) F45TA034
CONTINUE F45TA035
IARR=IDS F45TA036
IEBR=IDS F45TA037
DO 6 J=1,IOS F45TA038
IARR=IARR+1 F45TA039
IAB=IAB F45TA040
IEBR=IEBR+IOS F45TA041
IEF=IERR F45TA042
DO 7 J=1,IDS F45TA043
IAB=IAB+IDS F45TA044
IEF=IEF+1 F45TA045
IF (IAR-IEF) 7,7-13 F45TA046
IFMP=5(IEF) F45TA047
S(IEF)=S(IAB) F45TA048
S(IAR)=TEMP F45TA049
CONTINUE F45TA050
CONTINUE F45TA051
J=J+IDS F45TA052
CALL TRAN (S,J) F45TA053
DO 8 I=1,IDS F45TA054
J=J+IDS F45TA055
CONTINUE F45TA056
RETURN F45TA057
END F45TA059

```

Table VII-79. Source program listing of subroutine STRS (Link 4)

```

* LABEL
CF4STR SUBROUTINE STRS F45TR000
COMPUTE STRESSES FROM STRAINS F45TR001
DIMENSION I(11),AA(1),S(1),N(1),D2(21),D3(3),E(22),Z(3) F45TR002
1,P(24),UV(24),X(8),Y(8),Z(8),XD(7),YD(7),ZD(7),G(1) F45TR004
COMMON IA,AA F45TR005
EQUIVALENCE (IA,AA),(D21,D33),(D2110),E22,(D2119),E,(D2120),G F45TR006
EQUIVALENCE (IA11),IN1,(IA(2),IBN),(IA(3),IT),(IA(4),IP),(IA(5), F45TR007
1PRS),(IA(6),ITYPE),(IA(7),IMAT),(IA(8),IDFG),(IA(9),INX),(IA(10), F45TR008
2IH),(IA(11),IAR),(IA(12),IMX),(IA(13),IMY),(IA(14),IMZ),(IA(15), F45TR009
3IMF),(IA(16),IARE),(IA(17),I(13)),(IA(25),M),(IA(26),ITY),(IA(27), F45TR010
4ISTR),(IA(28),IELT),(IA(29),ITEM),(IA(30),ITIC),(IA(31),IMFT) F45TR011
5IA(32),ISUM),(IA(33),IND),(IA(34),IMS),(IA(36),IDS),(IA(37), F45TR012
6IORD),(IA(38),IORD1),(IA(39),ACEL),(IA(50),J1),(IA(51),J2), F45TR013
7IA(52),J3),(IA(53),J4),(IA(54),J5),(IA(55),J6),(IA(56),J7),(IA(57), F45TR014
8I,JR),(IA(58),JTY),(IA(59),IRB),(IA(60),IRI),(IA(61),IIO),(IA(62), F45TR015
9IA(63),IDT),(IA(64),IDY),(IA(65),ITE),(IA(61),ITAP) F45TR016
EQUIVALENCE (IA(68),ICAR),(IA(67),ICIX),(IA(68),ICIV),(IA(69), F45TR017
1ICIZ),(IA(70),IEF),(IA(71),IXX),(IA(72),IYY),(IA(73),IZZ), F45TR018
2IA(74),IIC),(IA(75),IDFF),(IA(76),IST),(IA(77),IIS) F45TR019
3,(IA(78),IGEM),(IA(79),IERK),(AA(80),TE),(AA(81),DT),(AA(82),DC) F45TR020
4AA(83),AL1),(AA(84),AL2),(AA(85),AL3),(AA(86),D21),(AA(87),P) F45TR021
5AA(131),UV),(AA(135),X),(AA(136),Y),(AA(137),Z),(AA(139),XD) F45TR022
6AA(138),YD),(AA(143),ZD),(AA(151),S),(AA(140),ZGEM) F45TR023
7AA(42),INP),(AA(43),IPRS),(AA(44),IPENT),(AA(45),COMS),(AA(46),IUF F45TR024
8),(AA(47),G1),(AA(48),G2),(AA(49),G3) F45TR025
EQUIVALENCE (IA(349),NTIC),(IA(348),ISD1),(IA(347),ISD2),(IA(346) F45TR026
1,ISD2),(IA(345),J9),(IA(344),J10),(IA(343),JPRS),(IA(342),JSDY) F45TR027
2,(IA(341),JSDZ),(IA(340),JARP),(IA(339),JMMX),(IA(338),JMY) F45TR028
3,(IA(337),JMMZ),(IA(336),JMF),(IA(335),ITAS),(IA(334),IDT) F45TR029
4,(IA(333),IPR),(IA(332),DGY),(IA(331),DGZ),(AA(330),PRES) F45TR030
J=IOS F45TR031
DO 5 I=1,IDS F45TR032
J=J+IDS F45TR033
CALL TRAN (S,J) F45TR034
CONTINUE F45TR035
IARR=IDS F45TR036
IEBR=IDS F45TR037
DO 6 J=1,IOS F45TR038
IARR=IARR+1 F45TR039
IAB=IAB F45TR040
IEBR=IEBR+IOS F45TR041
IEF=IERR F45TR042
DO 7 J=1,IDS F45TR043
IAB=IAB+IDS F45TR044
IEF=IEF+1 F45TR045
IF (IAR-IEF) 7,7-13 F45TR046
IFMP=5(IEF) F45TR047
S(IEF)=S(IAB) F45TR048
S(IAR)=TEMP F45TR049
CONTINUE F45TR050
CONTINUE F45TR051
J=J+IDS F45TR052
CALL TRAN (S,J) F45TR053
DO 8 I=1,IDS F45TR054
J=J+IDS F45TR055
CONTINUE F45TR056
RETURN F45TR057
END F45TR059

```

Table VII-80. Source program listing of subroutine TEMP (Link 4)

```

* LABEL
CE4TMP SUBROUTINE TEMP(CC)
C COMPUTES NODAL LINE VECTOR IN ORIGINAL MATERIAL AXES
C TO COMPUTE LENGTH CHANGE PER UNIT TEMPERATURE PER UNIT DISTANCE
DIMENSION IAA(1),AA(1),S(1),N(8),D2(12),D3(3,3),F22(3,3)
L,P(24),UV(24),X(8),Y(8),Z(8),XD(7),YD(7),ZD(7),G(11)
COMMON IA,AA
EQUIVALENCE (IA(1),AA(1),(D2(10),D22),(D2(19),F(1),(D2(17),G(11)
EQUIVALENCE (IA(1),IA(1),IN),(IA(2),IBN),(IA(3),IT),(IA(4),IP),(IA(5),
IPKS),(IA(6),ITYPE),(IA(7),IMAT),(IA(8),IDEG),(IA(9),INX),(IA(10),
2IH),(IA(11),IB),(IA(12),IMX),(IA(13),IMY),(IA(14),IMZ),(IA(15),FATMP010
3IMF),(IA(16),IARE),(IA(17),N(1)),(IA(25),M),(IA(26),ITY),(IA(27),
4ISTR),(IA(28),IELT),(IA(29),ITEM),(IA(30),ITIC),(IA(31),IMET),
5(IA(32),ISUM),(IA(33),IND),(IA(34),IMS),(IA(36),IOS),(IA(37),
6IOR),(IA(38),IORD),(IA(39),ACEL),(IA(40),J1),(IA(41),J2),
7(IA(52),J3),(IA(53),J4),(IA(54),J5),(IA(55),J6),(IA(56),J7),(IA(57),
8(J8),(IA(58),JTY),(IA(59),IBB),(IA(60),IRO),(IA(61),IIO),(IA(62),
9(IA(63),IDT),(IA(64),IDY),(IA(65),ITEL),(IA(66),ICIX),(IA(67),
EQUIVALENCE (IA(66),ICAR),(IA(67),ICIX),(IA(68),ICIX),(IA(69),
1ICIZ),(IA(70),ICF),(IA(71),IXX),(IA(72),IYY),(IA(73),IZZ),
2(IA(74),IIC),(IA(75),IOEF),(IA(76),IST),(IA(77),IIS)
3(IA(78),IGEM),(IA(79),IFR),(IA(80),ITE),(IA(81),IT),(IA(82),DO),
4(IA(83),AL),(IA(84),AL2),(IA(85),AL3),(IA(86),D21),(IA(107),P),
5(IA(131),UV),(AA(155),X),(AA(163),Y),(AA(171),Z),(AA(179),XO),
6(AA(186),YO),(AA(193),ZO),(AA(351),S),(AA(404),ZGFM)
7(AA(421),IMP),(AA(433),IPBG),(AA(444),IPEN),(AA(455),CONS),(AA(464),
8(IA(47),G1),(IA(48),G2),(IA(49),G3)
EQUIVALENCE (IA(349),NTIC),(IA(348),ISOT),(IA(347),ISDY),(IA(346),
1(ISO2),(IA(345),J9),(IA(344),J10),(IA(343),JPRS),(IA(342),JSDY)
2(IA(341),JSDZ),(IA(340),JARE),(IA(339),JMMX),(IA(338),JMMY)
3(IA(337),JMMZ),(IA(336),JMF1),(IA(335),IFAS),(IA(334),IDZ)
4(IA(333),IPR),(AA(332),DGY),(AA(331),UGZ),(AA(330),PRES)
5(IA(329),PIR)
DIMENSION HIR(3),SIR(3),DIN(3,3),SR(6),XN(3),XF(3),ON(6),OF(6),
3RES(6),RED(6),RAS(3),ICLAST(4),NBAM(10),NH(3),RFS(3)
EQUIVALENCE (AA(200),IDNE),(AA(201),ICN),(AA(202),LM),(AA(203),ASTE
1(IA(204),IMHMT),(AA(205),ARE),(AA(206),ICLA),(AA(207),IMFL),
2(IA(208),IM),(AA(209),IC),(AA(210),ICOM),(AA(211),ANGLE1),(AA(212),
3ICAS),(AA(213),IE),(AA(214),NK1),(AA(215),NR)
4(AA(216),IROT),(AA(217),BS1)
EQUIVALENCE (AA(220),SIR),(AA(223),SIR),(AA(226),DIR),(AA(235),SR)
1(AA(241),XN),(AA(244),XF),(AA(247),ON),(AA(253),OF),(AA(259),RFS)
2(AA(265),RH),(AA(271),RAS),(AA(274),ICLAST),(AA(279),NBAM)
3(AA(292),NU),(AA(295),NUS)
DIMENSION NUL(20,17),NAC(6,4,20),IWC(90),OO(6,6),AI(90,7),B(R,R),
1C(8,2),FF(11),NSET(100),MSF(100),W(3,3)
EQUIVALENCE (AA(14000),FF),(NU(11),JPL),(NU(2),JML),(NU(3),JSL)
EQUIVALENCE (FF(11),NEL),(FF(341),NAC),(FF(1661),IWC),(FF(751),DD),
1(FF(178),A),(FF(1417),B),(FF(1481),C),(FF(1497),WSET),(FF(1597),
2WSET),(FF(1697),W)
C COMPUTE THE NODAL LINE VECTOR IN THE ORIGINAL MATERIAL AXES
C XF,DCAR EQUIVALENCE D IN SETA, CONTAIN UNIT VECTOR OF NODAL LINE
OO IO I=1,3
SIR(I)=0.
OO Y K=1,3
SIR(I)=SIR(I)+X(I,K)*XF(K)
CONTINUE
C COMPUTE THE REQUIRED QUANTITY
CC=AL1*SIR(1)+X(1,K)*XF(K)
RETURN
END

```

Table VII-81. Source program listing of subroutine TICK (Link 4)

```

* FAP
CUMNT 25
LRL TICK
ENTRY TICK
TICK N2T DNCE
TRA FIRST
CAL 5
SUR IN1L
ALS 18
SLW* 1,4
TRA 2,4
FIRST STL DNCE
CAL 5
SLW IN1L
SLW* 1,4
TRA 2,4
UNCE PZF
IN1L PZF
END
TICK000
TICK001
TICK002
TICK003
TICK004
TICK005
TICK006
TICK007
TICK008
TICK009
TICK010
TICK011
TICK012
TICK013
TICK014
TICK015
TICK016
TICK017
TICK018

```

Table VII-82. Source program listing of subroutine TOPO (Link 4)

```

* LAHL
CE4TOP SUBROUTINE TOPO
C PREPARES ELEMENT PROPERTIES
DIMENSION IAA(1),AA(1),S(1),N(8),D2(12),D3(3,3),F22(3,3)
L,P(24),UV(24),X(8),Y(8),Z(8),XD(7),YD(7),ZD(7),G(11)
COMMON IA,AA
EQUIVALENCE (IA(1),AA(1),(D2(10),D22),(D2(19),F(1),(D2(17),G(11)
EQUIVALENCE (IA(1),IA(1),IN),(IA(2),IBN),(IA(3),IT),(IA(4),IP),(IA(5),
IPKS),(IA(6),ITYPE),(IA(7),IMAT),(IA(8),IDEG),(IA(9),INX),(IA(10),
2IH),(IA(11),IB),(IA(12),IMX),(IA(13),IMY),(IA(14),IMZ),(IA(15),FATMP010
3IMF),(IA(16),IARE),(IA(17),N(1)),(IA(25),M),(IA(26),ITY),(IA(27),
4ISTR),(IA(28),IELT),(IA(29),ITEM),(IA(30),ITIC),(IA(31),IMET),
5(IA(32),ISUM),(IA(33),IND),(IA(34),IMS),(IA(36),IOS),(IA(37),
6IOR),(IA(38),IORD),(IA(39),ACEL),(IA(40),J1),(IA(41),J2),
7(IA(52),J3),(IA(53),J4),(IA(54),J5),(IA(55),J6),(IA(56),J7),(IA(57),
8(J8),(IA(58),JTY),(IA(59),IBB),(IA(60),IRO),(IA(61),IIO),(IA(62),
9(IA(63),IDT),(IA(64),IDY),(IA(65),ITEL),(IA(66),ICIX),(IA(67),
EQUIVALENCE (IA(66),ICAR),(IA(67),ICIX),(IA(68),ICIX),(IA(69),
1ICIZ),(IA(70),ICF),(IA(71),IXX),(IA(72),IYY),(IA(73),IZZ),
2(IA(74),IIC),(IA(75),IOEF),(IA(76),IST),(IA(77),IIS)
3(IA(78),IGEM),(IA(79),IFR),(IA(80),ITE),(IA(81),IT),(IA(82),DO),
4(IA(83),AL),(IA(84),AL2),(IA(85),AL3),(IA(86),D21),(IA(107),P),
5(AA(131),UV),(AA(155),X),(AA(163),Y),(AA(171),Z),(AA(179),XO),
6(AA(186),YO),(AA(193),ZO),(AA(351),S),(AA(404),ZGFM)
7(AA(421),IMP),(AA(433),IPBG),(AA(444),IPEN),(AA(455),CONS),(AA(464),
8(IA(47),G1),(IA(48),G2),(IA(49),G3)
EQUIVALENCE (IA(349),NTIC),(IA(348),ISOT),(IA(347),ISDY),(IA(346),
1(ISO2),(IA(345),J9),(IA(344),J10),(IA(343),JPRS),(IA(342),JSDY)
2(IA(341),JSDZ),(IA(340),JARE),(IA(339),JMMX),(IA(338),JMMY)
3(IA(337),JMMZ),(IA(336),JMF1),(IA(335),IFAS),(IA(334),IDZ)
4(IA(333),IPR),(AA(332),DGY),(AA(331),UGZ),(AA(330),PRES)
5(IA(329),PIR)
IELT=0
ITEM=0
IIC=0
IMET=0
OO IO I=1,8
N(I)=0
K=1+355
10 IAKI=0
JM=J+M
IELT=IA(JM)/100
IMET=IA(JM)-100*IFTL
JM=J+M
IF (IET-4) 100,100,450
100 IF (IELT-3) 200,300,200
200 JARE=IA(JM)/100
ITEM=IA(JM)-100*JARE
GO TO 400
300 JPRS=IA(JM)/100
JSDZ=IA(JM)-100*JPRS
400 IF (IELT-3) 600,600,800
450 IF (IELT-10) 470,470,500
470 IF (IET-8) 900,500,480
480 JPRS=IA(JM)/100
ITEM=IA(JM)-100*JPRS
L=1
GO TO 1000
JM=J+M
ITEM=IA(JM)-100*ITEM
JM=J+M
JSDZ=IA(JM)/100
JPRS=IA(JM)-100*JSDZ
L=2
GO TO 1000
JM=J+M
JPRS=IA(JM)
L=2
IF (IET-2) 1000,700,700
JM=J+M
JMM=IA(JM)/100
JSDY=IA(JM)-100*JMMZ
L=3
IF (IELT-4) 1000,900,1000
JM=J+M
JMMX=IA(JM)/100
JMMY=IA(JM)-100*JMMX
L=2
IF (IELT-4) 1000,700,1000
JM=J+M
JSDZ=IA(JM)/100
JMF1=IA(JM)-100*JSDZ
JM=J+M
JPRS=IA(JM)
L=4
1000 I=1
GO TO (1100,1200,1300,1400),I
1100 JM=J+M
N(I)=IA(JM)
I=I+1
JM=J+M
N(I)=IA(JM)
I=I+1
1200 JM=J+M
N(I)=IA(JM)
I=I+1
1300 JM=J+M
N(I)=IA(JM)
I=I+1
JM=J+M
N(I)=IA(JM)
I=I+1
1400 JM=J+M
N(I)=IA(JM)
I=I+1
JM=J+M
N(I)=IA(JM)
I=I+1
JM=J+M
N(I)=IA(JM)
I=I+1
JM=J+M
N(I)=IA(JM)
I=I+1
JM=J+M
N(I)=IA(JM)
I=I+1
JM=J+M
N(I)=IA(JM)
I=I+1
1450 IHP=I+H
DO 1500 I=1,HP,8
1500 N(I)=0.
1600 RETURN
END

```

Table VII-83. Source program listing of subroutine TRAN (Link 4)

```

* LABEL
CE4TRN
SUBROUTINE TRAN (A,IFS)
FOR LOCAL-OVERALL COORDINATE TRANSFORMATION FOR VECTORS
DIMENSION IA(1),AA(1),S(1),N(8),D21(21),D33(3,3),F22(3,3)
1,P(24),UV(24),X(8),Y(8),Z(8),XD(7),YD(7),ZD(7),G(11)
COMMON IA,AA
EQUIVALENCE (IA,AA),(D21,D33),(D21(10),E22),(D21(19),E1),(D21(20),G)
EQUIVALENCE (IA(1),IN),(IA(2),IBN),(IA(3),IT),(IA(4),IP),(IA(5),I)
1PRS),(IA(6),ITYPE),(IA(7),IMAT),(IA(8),IDEG),(IA(9),INXI),(IA(10),E4TRN007
2IH),(IA(11),I8),(IA(12),IMMX),(IA(13),IMMY),(IA(14),IMMZ),(IA(15),E4TRN009
3IMFI),(IA(16),IARE),(IA(17),M(3)),(IA(25),M),(IA(26),ITY),(IA(27),E4TRN010
4ISTJ),(IA(28),IPLT),(IA(29),ITEM),(IA(30),ITTC),(IA(31),IMET), E4TRN011
5,IA(32),ISOM),(IA(33),IND),(IA(34),IMS),(IA(36),IOS),(IA(37), E4TRN012
6IDRO),(IA(38),IDROL),(IA(39),ACH), (IA(50),J1),(IA(51),J2), E4TRN013
7,(IA(52),J3),(IA(53),J4),(IA(54),J5),(IA(55),J6),(IA(56),J7),(IA(57),E4TRN014
8),J8),(IA(58),JTY),(IA(59),I8H),(IA(60),IBD),(IA(61),ID),(IA(62),E4TRN015
9,IA),(IA(63),IDT),(IA(64),IDY),(IA(65),ITE),(IA(41),ITAP) E4TRN016
EQUIVALENCE (IA(66),ICAR),(IA(67),ICIX),(IA(68),ICEY),(IA(69), E4TRN017
1,ICIZ),(IA(70),ICFI),(IA(71),ICX),(IA(72),ICY),(IA(73),ICZ), E4TRN018
2,(IA(74),IIC),(IA(75),IDEP),(IA(76),IST),(IA(77),IIS) E4TRN019
3,(IA(78),IGEM),(IA(79),IFRR),(AA(80),TE),(AA(81),D11),(AA(82),DG), E4TRN020
4,(AA(83),AL1),(AA(84),AL2),(AA(85),AL3),(AA(86),D21),(AA(107),P1, E4TRN021
5,(AA(131),UV),(AA(155),X),(AA(163),Y),(AA(171),Z),(AA(179),XD), E4TRN022
6,(AA(186),YD),(AA(193),ZD),(AA(125),S),(AA(40),ZGEM) E4TRN023
7,(AA(142),IMP),(AA(143),IPB6),(AA(44),IPFN),(AA(45),CONS),(AA(46),IIE4TRN024
8),(AA(147),S),(AA(48),G2),(AA(49),G3) E4TRN025
EQUIVALENCE (IA(349),NYIC),(IA(349),ISDT),(IA(347),ISDY),(IA(346) E4TRN026
1,ISDZ),(IA(345),J9),(IA(344),J10),(IA(343),JPR5),(IA(342),JSDY) E4TRN027
2,(IA(341),JSDZ),(IA(340),JARE),(IA(339),JMMX),(IA(338),JMMY) E4TRN028
3,(IA(337),JMMZ),(IA(336),JMF1),(IA(335),ITAS),(IA(334),IDZ) E4TRN029
4,(IA(333),JPR),(AA(332),DGY),(AA(331),DGZ),(AA(330),PRES) E4TRN030
5,(IA(329),IPIR) E4TRN031
DIMENSION EM(4,4),EN(4,4),O(4,4),DIR(3,3),DUM(3,8)
EQUIVALENCE (AA(200),EM),(AA(216),EN),(AA(232),EQ),(AA(246),O),
1,AA(264),DIR),(AA(273),DUM)
DIMENSION A(1)
10 IGEMP=IGEM+1
LJI=0
LKI=1
20 DD 300 L=1,IGEMP
LK=LK+3*IMS
30 DD 200 J=1,3
DD 200 I=1,IMS
LJI=LJI+1
DUM(LJI)=O.
LKI=LKI+1
40 DD 100 K=1,3
LKI=LKI+IMS
100 DUM(LJI)=DUM(LJI+DIR(K,J))*A(LKI)
200 CONTINUE
300 CONTINUE
IMI=3*IGEMP*IMS
DD 400 I=1,IMI
II=IFS+1
400 A(II)=DUM(II)
RETURN
END
E4TRN056

```

Table VII-84. Source program listing of subroutine UNIT (Link 4)

```

* LABEL
CE4UNT
SUBROUTINE UNIT(CIR,Q)
OBTAINS A UNIT VECTOR ALONG A LINE SEGMENT
IF Q=NEGATIVE, CHANGE DIRECTION AND REPLACE WITH UNITY, Q=LENGTH
IF Q=0, MAKE Q=LENGTH*LENGTH AND RETURN
IF Q=POSITIVE, REPLACE WITH UNITY, Q=LENGTH
DIMENSION CIR(3)
R=CIR(1)**2+CIR(2)**2+CIR(3)**2
IF (Q) 10,-19,20
19 Q=R
GO TO 21
20 CIR(1)=-CIR(1)
CIR(2)=-CIR(2)
CIR(3)=-CIR(3)
D=SQRT(F)
CIR(1)=CIR(1)/Q
CIR(2)=CIR(2)/Q
CIR(3)=CIR(3)/Q
21 RETURN
END
E4UNT000
E4UNT001
E4UNT002
E4UNT003
E4UNT004
E4UNT005
E4UNT006
E4UNT007
E4UNT008
E4UNT009
E4UNT010
E4UNT011
E4UNT012
E4UNT013
E4UNT014
E4UNT015
E4UNT016
E4UNT017
E4UNT018
E4UNT019

```

Table VII-85. Source program listing of subroutine VECT (Link 4)

```

* LABEL
CE4VCT
SUBROUTINE VECT(A,B,C)
PERFORMS VECTORIAL VECTOR PRODUCT
TO OBTAIN A AS XC
DIMENSION A(3),B(3),C(3)
A(1)=B(2)*C(3)-B(3)*C(2)
A(2)=B(3)*C(1)-B(1)*C(3)
A(3)=B(1)*C(2)-B(2)*C(1)
RETURN
END
E4VCT000
E4VCT001
E4VCT002
E4VCT003
E4VCT004
E4VCT005
E4VCT006
E4VCT007
E4VCT008
E4VCT009

```

References

1. Akyuz, F. A., and Utku, S., "An Automatic Node-Relabeling Scheme for Bandwidth Minimization of Stiffness Matrices," *AIAA Journal*, Vol. 6, No. 4, pp. 728-730, Apr. 1968.
2. Utku, S., "Stiffness Matrices for Thin Triangular Elements of Nonzero Gaussian Curvature," *AIAA Journal*, Vol. 5, No. 9, pp. 1659-1667, Sept. 1967.
3. Utku, S., and Melosh, R. J., "Behavior of Triangular Shell Element Stiffness Matrices Associated With Polyhedral Deflection Distributions," *AIAA Journal*, Vol. 6, No. 2, pp. 374-376, Feb. 1968. Also available as Technical Report 32-1217, Jet Propulsion Laboratory, Pasadena, Calif., Jan. 1968.
4. Utku, S., "Explicit Expressions for Triangular Torus Element Stiffness Matrix," *AIAA Journal*, Vol. 6, No. 6, pp. 1174-1176, June 1968.
5. Utku, S., "A Conical Element Stiffness Matrix Associated With Polyhedral Deflection Fields," in *M. Inan Memorial Volume*. ITU Publications, Istanbul, 1969 (in press).