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\section*{ABSTRACT}

This study presents in a systematic form the theoretical, analytical, and experimental results of radar-cross-sections of targets of different shapes. This report is designed to give the engineer a feel for the gross features of the target and the resulting radar-cross-section to be expected. This will heip him then to begin a detailed analysis inorder to obtain a better prediction of the true RCS of the target. Various techniques useful to predict RCS are given. RCS of finite standard targets is presented. Then a presentation of techniques used to predict the RCS of complex targets is made. Finally, RCS of complex shapes is given. This report will be very helpful to accomplish National Aeronautics and Space Administration goal of predicting the RCS of candidate targets.

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\section*{Introduction}

Radars were developed by independent efforts of several countries during the early twentieth century. Basically speaking, it is an electronic eye useful:
(1) To detect and locate targets which are obscured to the naked eye because of distance or environmental conditions.
(2) To determine the physical shape of a target, from the knowledge of the incident energy and reflected energy.
(3) To determine the speed of the moving target.
(4) To determine the type of material the target is made of.
(5) To guide airplanes when the pilot is not able to see due to bad weather conditions.

\section*{RADAR-CROSS-SECTION}

In order for a radar to determine the physical shape of an object, the utilization of the radar-cross-section is employed. Radar-Cross-Section or RCS is defined as 4 times the ratio of the back scattered power per unit solid angle to the incident power per unit area. It maybe noted here that radar-crosssection has units of area and is generally denoted by \((\sigma)\).

\section*{back scattered power/unit solid angle} incident power/unit area

In other words, the reflectivity of the target at which a radar signal is incident is expressed by the radar-cross-section, which includes eddects of area, configuration, size and material of the target.

\section*{METHODS OF DETERMINING THE RADAR-CROSS-SECTION}

Research on RCS dates as far as 1949. Some of the methods found in the earlier research were used in World War II to determine targets of interest to the United States Military. Some of the earlier methods are:
(1) Using pulse signals and measuning the electric field strength.
(2) Using continious wave (cw) signals and measuining the standing wave distribution or measuring the doppler shift (shifts caused by the effect of target or medium motion wlith relative to each other.)
(3) intiont
(3) Methods uising frequency modulated continious wave signals in frequency modulated radars.

Today, there are techniques such as:
(1) Physical Optics
(2). Geometrical Theory of Diffraction
(3) Creeping Wave Analysis
(4) Impulse Response Theory

Physical optics is used to calculate the radar-cross-section for perfectly conducting bodies. This theory explains the behavior of light and takes into account the phasing between scatters. The physical optics theory arises from the radiation integral which
assumes that the surface current is the same attany point as it would be at that point on an infinite plane tangent to the body at that point and assumes further the existence of a sharp shadow boundary, beyond which surface current is identically zero, Unfortunately, the approzimation is poor at just those parts of the surface of the body that are most important in determining the value of the integral. Therefore, physical optics ferequently give poor results.

This theory has certain limitations such as:
(1) When the theory is applied to bistatic cases (transmitter and reciever in different places) it yields results that do not conform to the principles of reciprocity.
(2) Polarization dependence of backscattering cannot be obtained from using this method.
(3) Physical optics is unable to account for effects For arising from diffraction or creeping-wave progacion into the shadow region of a body.

However, physical optics is still used despite it. limitatigons. It is used because in some cases it gives good results such as for perfectly conducting bodies and most of the time can tell in advance for which cases these results can be obtained.

The physical-optics cross section for backscattering of a body' is given by this expression: (Ross, 1966)
\[
\sigma=4 \pi|g(k)|^{2}
\]

Where:
\[
g(k)=\frac{-j k}{Q \pi} \int d z \frac{d a}{d z} e^{j k z}
\]
\(\therefore \quad k=\) wave number \(=2 \pi / \lambda\)
\(\lambda=\) radar wavelength
\(z=\) coordinate along the radar line of sight
\(A=\) area of intercept of body with plane perpendicular to radar. line of sight

However, the expression just sited to give poor results for bistatic scattering. Yarious methods have been suggested for the modification of physical optics so that it will yield better results. Such suggestions as: modifying the assumed surface currents, or the method used by S. Adachi, which was to continue the integration over the total surface instead of over just the illiminated portion. However, Adachi (1965) method proved rather odd results.

Physical Optics can lead to serious error, mainly because it assumes that the current distribution on a surface is the same at each point.

The most practical of the asymptotic techiniques that have been developed so far is the geometrical theory of diffraction, developed poincipatly by J. B. Keller (1960). This theory takes: into account diffractedg as well as reflected rays. Geometrical diffraction theory assumes localization of the scattering at points defined by stationary phase arguments or by abrupt geometric discontinuities. Also, the current distribution of a scattering center is obtainable from that of a known case of similar geometry. Then based on similar known problems a diffraction coefficient is assigned to each center. This coefficient is the function of a phaser proportional to the distance along a ray projected from the scattering center to the radar.

Even though, this theory is practical for many targets it is not yet related to Maxwell's equations. Also, the prediction of cross section near grazing incidence is a problem for the geometrical theory of diffraction. The results from this theory approaches
infinity near edge on aspect engles due to singularities contained in terms describing multireflections. The effect of multireflections issnot discussed in this study, because radar-crossrsection of the target to be consldered in this study can be predicted by the scattering centers in term of single diffraction.

Moreover, the geometrical theory of diffraction has been applied to predict RCS of such bodies as spheres, rectangular flat plates and cones. The theory provides good results except for the nose on aspect angles.

The creeping wave theory is concerned with the waves that passes around the rear of a smooth body. This theory is of importance mainly for small bodies, generally in the resonamoe region, or for bodies specifically constructed to have low radar-cross-section. The theory is valid for the resonance region mainly because the creeping wave tends to become very small after progating a few wavelengths. The creeping-wave contributions to cross-sections are generally small, ther are usually important for bodies that do not have large scatters on them.

There are two methods for momputing the creeping-wace contrimutions to radar scattering. First, one can perform an asymptotic expansion of the exact solution of the scattering problem and recognize the creeping-wave contributions in the answer through the phase expressions that appear in the answer. However, here one needs the exact solution to the scattering. Second, one can use the geometrical theory of diffraction approach. This method uses
the diffraction and decay coefficients so obtained from the geometrical theory of diffraction to calculate the contribution from the creepingwave.

The impulse-response teehnique was developed by Kennaugh (1965). This method considers the scattering of a short pulse, an impulse, a step function, or a ramp function rather than the continious wave or short oscillatory pulse normally considered. The method is similar to the impulserresponse method used in the investigations of the transient behavior of physical systems such as servomechnisms.

It is noted here that an impulse function can only be approximated and the ideal implise is not normally generated. Therefore, the hypothetical impulse is not oscillatory, so the entire surface of the body contributes to the scattering. Frim linear systems analsis, it is khown that convolution techniques can be used to derive continious waves or short oscillatory pulses from the impulse response.

The impulse-response technique is capable of bridging the gap between Rayleigh scattering and high frequency results into the lower-frequency region, physical optics and geometrical diffraction theory results can thus be made to hold quite well in the resonance region. The impulse-response theory also takes into account com-. binations of simple shapes and the distortion of a simple shape into a more complex one. This technique permits the use of different computational techniques for diffrent parts of the body, since the impulse response for each region of the body can be added together.

The advantages of the impulse-response technique are:
1) Its ability to treat scattering in the resonance region
2) The simple pictures it gives of scattering
3) The ease in which computational methods dan be used
4) Its experimental results can be used to improve the results of analytical techniques.

The geometrical theory of diffraction produces good results for many bodies. It has been applied to such bodies as; flat plates, right circular cones, cylinder, frustrums and other bodies. The theory also provides good results for complex and composite bodies.

Moreover, the radar-cross-section of composite bodies such as service satellites, missles and other such bodies are of great concern. This paper will present the radar-cross-section of a missle, by the use of the geometrical theory of diffraction.

\section*{APPLICATION OF GEOMETRICAL DIFRACTION THEORY TO SCATTERING FROM CONES AND DISKS}

\begin{abstract}
The study compares the previous analytical results, obtained by geometrical theory of diffraction for perfectly conducting cones and disks, with experimental results for both horizontal and vertical polarization cases. Presentation is made for cones ranging from 0.98 to 2.87 wavelengths in diameter at the base and having half angles of \(4^{\circ}, 15^{\circ}\), and \(90^{\circ}\), the latter corresponds to a disk.
\end{abstract}

\section*{TARGET GEOMETRY AND COORDINATE SYSTEM}

The target geometry and coordinate system used. is presented in Figure 1.

ANALYTICAL AND/OR EXPERIMENTAL PLOTS

The analytical and experimental resuits are plotted in Figures 2. through 13.

\section*{INTERPRETATION OF RESULTS}

The results seem to agree well. Futhermore, for cones having normalized base circumference (ka) of 8 or 9 , the predicted and measured RCS agree well except when the cone is observed within about \(30^{\circ}\) of nose-on for vertical polarization, in which case large errors occur for some as yet unknown reason. For smaller cones having diameters about equal to the wavelength: (ka around 3), the computed RCS is generally pre-
dicted within 5 dB , but the form of RCS is not predicted very accurately. Baskscattering from a disk of the same diameter for viewing angles within \(60^{\circ}\) of the normal to the base.


Fig.1. Longitudinal section of a right circular cone.



Fig. 3. Horizontally polarized RCS for cone \(\gamma=15^{\circ}, k a=9.02\).


Fig. 4.. Veritically polarized RCS for cone; \(\gamma=15^{\circ}\), ka=8.28.


Fig. 5. Horizonitally polarized RCS for cone; \(\gamma=15^{\circ}\), ka=8.28.


Fig. 6. Vertically polarized RCS for cone; \(\gamma=15^{\circ}\), kam3.08


Fig. 7. 'Horizontially polarizad RCS for cone; \(\gamma=15^{\circ}\), ka=3.08.


Fig. 8. Veritically Polarized RCS for cone; \(\gamma^{\prime}=4^{\circ}\). ka=8.28.


Fig. 9. Horizontally polarized RCS for cone; \(\gamma=14, k a=8.28\).


Fig. 10. Vertically polarized RCS for disk; ka=8.28


Fig, 21. Horizontally polarized RCS for disk; ka=8.28.


Fig, 12. Measured vertically polarized RCS of cones; ka=8.28


Fig. 13. Measured horizontally polarized RCS of cones; ka=8.28

\section*{RADAR-CROSS-SECTION OF RECTANGULAR FLAT PLATES Ar A FUNCTION OF ASPECT ANGLE}

This study investigates the scattering from flat perfectly conducting plates. Radar-Cross-Section results are presented, based upon both theoretical as well as experimental studies. RCS expressions based upon physical optics theory for near specular returns are presented. Geometrical theory of diffraction gives good results for non-specular cases except for edge on case. Based upon experimental measurements, an analytical expression is derived from this data for edgeron case.

TARGET AND COORDINATE SYSTEM
The target (perfectly conducting rectangular flat plate) and coordinate system used is shown in Fig. 1.

\section*{ANALYTICAL EXPRESSIONS}

Based upon optics theory, an expression of the RCS, for both horizontal and vertical polarization may be written as:
\[
\sigma_{p .0 .}=\frac{64 \pi a^{2} b^{2}}{\lambda^{2}} \cos ^{2} \phi\left[\frac{\sin (2 k a \sin \phi)}{(2 k a \sin \phi)}\right]^{2}
\]

Futhermore, based upon geometric diffraction theory, the RCS expressions may be written:
\[
\begin{aligned}
& \text { For the vertical polarization case: } \\
& \sigma_{V_{g \cdot d .}}=\frac{4 b^{2}}{\pi} \\
left[\cos 2 h a \sin \phi-\frac{j \sin 2 k a \sin \phi}{\sin \phi}\right] \\
& -\frac{e^{j k a-j \pi / 4}}{\sqrt{2^{\pi}}(2 k a)^{3 / 2}}\left[\frac{1}{\cos \phi}+\frac{e^{j 2 k a-j \pi / 4}}{4 \sqrt{2 \pi}(2 k a)^{3 / 2}}\left(\frac{(1+\sin \phi) e^{-j 2 k a}}{\left(1-\sin ^{2} \phi\right)}+\right.\right. \\
& \left.\left.\frac{(1-\sin \phi) e^{+2 j k a \sin \phi}}{\left(1+\sin ^{2} \phi\right)}\right)\right] \times\left.\left[1-\frac{e^{j 4 k a-j \pi / 2}}{8 \pi(2 k a)^{3}}\right]^{-1}\right|^{2} \\
& \text { and for the horizontal polarization case: } \\
& \text { EXPERIMENTAL DETAILS } \\
& \begin{array}{l}
{\left[\frac{1}{\cos \phi}-\frac{e^{j 2 k a+j \pi / 4}}{2 \sqrt{2 \pi}(2 k a)^{1 / 2}}\left(\frac{e^{-j 2 k a \sin \phi}}{1-\sin \phi}+\frac{e^{j 2 k a \sin \phi}}{1+\sin \phi}\right)\right]} \\
{\left.\left[1-\frac{e^{j 4 k a-j \pi / 2}}{2 \pi(2 k a)}\right]^{-1}\right|^{2}}
\end{array} \\
& \frac{4 e^{j 2 k a+j \pi / 4}}{\sqrt{2 \pi(2 k a)^{1 / 2}}} x \\
& \begin{array}{l}
{\left[\frac{1}{\cos \phi}-\frac{e^{j 2 k a+j \pi / 4}}{2 \sqrt{2 \pi}(2 k a)^{1 / 2}}\left(\frac{e^{-j 2 k a \sin \phi}}{1-\sin \phi}+\frac{e^{j 2 k a \sin \phi}}{1+\sin \phi}\right)\right] \times} \\
\\
{\left.\left[1-\frac{e^{j 4 k a-j \pi / 2}}{2 \pi(2 k a)}\right]^{-1}\right|^{2}}
\end{array} \\
& \sigma_{H g \cdot d}=\frac{4 b^{2}}{\pi} \left\lvert\,\left[\cos 2 k a \sin \phi+\frac{j \sin 2 k a \sin \phi}{\sin \phi}\right]-\frac{4 e^{j 2 k a+j \pi / 4}}{\sqrt{2 \pi(2 k a)^{1 / 2}}} x\right.
\end{aligned}
\]

Three targets (aluminum material) are fabricated for monostatic measurements on the Cornell Aeronautical Labs X -band CW radar range at 1.28 inches wavelength. The dimensions of the plate are shown in the respective figures.

\section*{ANALYTICAL AND/OR EXPERIMENTAL PLOTS}

Figures 2 and 3 show the plots obtained from the measured and analytical data.

Futhermore, experiment was carried out to measure RCS at grazing indidence \(\left(\overline{1}=90^{\circ}\right)\). Results are shown in figure 4.

An analytical fit to the experimental data show the following accurate expression:
\[
\begin{aligned}
\square\left(\phi=90^{\circ}\right) & =a / \lambda b^{2}\left[\left(1+\pi / 2^{x 1} /(2 a / \lambda)^{2}\right)\right. \\
& \left.+\left(1-\frac{\pi}{2} \frac{1}{(2 a / \lambda)^{2}}\right) \cos \left(4 k a-\frac{3 \pi}{5}\right)\right]
\end{aligned}
\]
for the vertical polarization case and
\[
\sigma_{H}\left(\Phi=90^{\circ}\right)=0
\]
for the horizontal polarization case.

\section*{INTERPRETATION OF RESULTS}

A comparasion of the results shows that physical optics theory is valid for a near specular aspect angle incident, whereas geometrical theory of diffraction is valid for \(30^{\circ} \leqslant \Phi \leqslant 80^{\circ}\)
 empirical formular obtained from the expremental results shows good fit for grazing incidents on a flat finite rectangular plate. Futher work needs to be done in the area of deriving modified diffraction coefficients at near grazing incidents.


Fig.1. Limitation on aspect angle.
Fig. 4. Cross section of \(5 \times 5\) inch flat plate \((\lambda=1.281 n\).\() .\)


Fig. 5. Cross section of \(6.5 \mathrm{X} \phi .5\) inch flat plate \((\lambda=1.28 i n\).\() .\)


Fig.4. Comparision of analytical fit with measurement data, vertical polarization

Keller's geometrical theory of diffraction is applied to derive theoretically the radar-cross-section expressions of a frustum as a function of frequency, aspect angle and bistatic angle. The calculated results from these expressions are in good agreement with the bistatic measurement data.

\section*{TARGET AND COORDINATE SYSTEM}

The target ( perfectly conducting frustrum) and the coordinate system used is shown in Fig. 1.

ANALYTICAL EXPRESSIONS

Symmetry of the problem shows that there are four scattering centers, and the radar-cross-section expressions for them may be written as:
\[
\begin{equation*}
\sqrt{\sigma} e^{j \rho}=\sum_{i=1}^{4} \sqrt{\sigma_{i}} e^{j f_{i}} \tag{1}
\end{equation*}
\]
where \(\sigma=\) RCS and \(\rho=\) phase of the scattered field.

Furthermore
\[
\sqrt{\sigma_{1}}=\left\{\begin{array}{l}
\frac{\sin \left(\pi / \eta_{1}\right)}{\eta_{1}} \sqrt{\frac{a_{1} \cos \phi}{k \cos \left(n_{1} / 2\right)}\left[\left\{\cos \left(\pi / \eta_{1}\right)-\cos \left(\frac{\pi+2 \phi}{\eta_{1}}\right)\right\}\right.}  \tag{2}\\
\mp \quad\left[\cos \left(\pi / \eta_{1}\right)-\cos \left(\frac{\left.\beta_{2} / \eta_{1}\right)}{-1}\right], \beta \Phi \leq \pi-\alpha-\frac{\beta_{2}}{2}\right.
\end{array}\right.
\]
\[
\sqrt{\sigma_{2}}=\left\{\begin{array}{l}
\frac{\sin \left(\pi / \eta_{2}\right)}{\eta_{2}} \sqrt{\frac{a_{2} \cos \phi}{\beta_{\cos \left(\beta_{2} / 2\right)}}\left[\left\{\cos \left(\pi / \eta_{2}\right)-\cos \left(\frac{3 \pi-2 \phi}{\eta_{2}}\right)\right\}^{-1}\right.}  \tag{3}\\
\left.+\left\{\cos \left(\pi / \eta_{2}\right)-\cos (\bar{\beta} / 2)\right\}^{-1}\right], \Phi \geqslant-\alpha+\frac{\beta_{a}}{2} \\
\vdots, \Phi<-\alpha+\beta_{2 / 2}
\end{array}\right.
\]
\[
\sqrt{\sigma_{3}}=\left\{\begin{array}{l}
\frac{\sin \left(\pi / \eta_{1}\right)}{\eta_{1}} \sqrt{\frac{a_{1} \csc \phi}{k \cos \left(\beta_{a / 2}\right.}}\left[\left\{\cos \left(\pi / \eta_{1}\right)-\cos \left(\frac{\pi-2 \phi}{\eta_{1}}\right)\right\}^{-1}\right. \\
\left.\mp\left\{\cos \left(\pi / \eta_{1}\right)-\cos \left(\beta_{1} / \eta_{i}\right)\right\}^{-1}\right], \Phi \leqslant \frac{\pi}{2}-\frac{\beta_{2}}{2} \\
0, \Phi>\frac{\pi}{2}-\beta_{a / 2}
\end{array}\right.
\]
\[
\sqrt{\sigma_{4}}=\left\{\begin{array}{l}
\frac{\sin \left(\pi / \eta_{2}\right)}{\eta_{2}} \sqrt{\frac{a_{2} \csc \phi}{k \cos \left(\beta_{\alpha} / 2\right)}}\left[\left\{\cos \left(\pi / \eta_{2}\right)-\cos \left(\frac{3 \pi+2 \phi}{\eta_{2}}\right)\right\}\right. \\
\left.\mp\left\{\cos \left(\pi / \eta_{2}\right)-\cos \left(\beta_{\alpha} / \eta_{2}\right)\right\}\right], \phi \leqslant \alpha-\beta_{1 / 2} \\
0, \pi / 2+\beta_{1 / 2}>\phi>\alpha-\beta_{a / 2} \\
\frac{\sin \left(\pi / \eta_{2}\right)}{\eta_{2}} \sqrt{\frac{a_{2} \csc \phi}{k \cos \left(n_{/ 2}\right)}}\left[\left\{\cos \left(\pi / \eta_{2}\right)-\cos \left(\frac{-\pi+2 \phi}{\eta_{2}}\right)\right\}^{-1}\right. \\
\left.\mp\left\{\cos \left(\pi / \eta_{2}\right)-\cos \left(\beta_{4} / 2\right)\right\}^{-1}\right], \Phi \leqslant \frac{\pi}{2}+\frac{\beta_{q}}{2}
\end{array}\right.
\]

And the phase referenced to the base of the frustum are given by:
\[
\begin{aligned}
& \rho_{1}=-2 k \cos \left(\beta a_{12}\right)\left[a_{1} \sin \phi+2 h \cos \phi\right]+\pi / 4 \\
& \rho_{2}=-2 k a_{2} \sin \phi \cos \left(\beta_{u} / 2\right)+\pi / 4 \\
& \rho_{3}=+2 k \cos \left(\beta_{n} / 2\right)\left[a_{1} \sin \phi-2 h \cos \phi\right]-\pi / 4 \\
& \rho_{4}=+2 k a_{2} \sin \phi \cos \left(\beta_{a} / 2\right)-\pi / 4
\end{aligned}
\]
where \(\alpha\) is the frustum angle in radians.
\[
\alpha=\tan ^{-1}\left(\frac{a_{2}-a_{1}}{2 h}\right)
\]
\[
\begin{aligned}
& n_{2}=\frac{3}{2}+\frac{\alpha}{\pi} \\
& k=2 \pi / \lambda
\end{aligned}
\]

Upper sign in above equations correspond to vertical polarizaton and lower sign corresponds to horizontal polarization.

Also using small approximation, at and near the nose-on axial aspects, one obtains:
\[
\begin{aligned}
\sqrt{\sigma} e^{j \rho}= & 2 \sqrt{\pi}\left[\left(k \cos \left(\beta_{1} / 2\right)\right) \alpha_{1}^{2} J_{1} \frac{\left(2 k a_{1} \sin \phi \cos \left(\beta_{a / 2}\right)\right)}{\left(2 k a_{1} \sin \phi \cos (\beta a / 2)\right)} e^{-j \pi / 2}\right. \\
& \left. \pm \frac{a_{1} \sin \left(\pi / \eta_{1}\right) J_{2}\left(2 k a_{1} \sin \phi \cos \left(\beta_{n} / 2\right)\right)}{\eta_{1}\left(\cos \left(\pi / \eta_{1}\right)-\cos \left(\beta_{a} / \eta_{1}\right)\right)}\right] \cdot \exp \left[-j 4 k h \cos \phi \cos \left(\frac{\beta_{2}}{2}\right)^{-}\right. \\
& +2 \sqrt{\pi a_{2} \frac{\sin \left(\pi / \eta_{2}\right)}{\eta_{2}}\left[\frac{J_{0}\left(2 k a_{2} \sin \phi \cos (\beta a / 2)\right)}{\cos \left(\pi / \eta_{2}\right)-\cos \left(3 \pi / \eta \eta_{2}\right)}\right.}= \\
& -j \frac{2 \sin \left(3 \pi / \eta_{2}\right) \tan \phi}{\eta_{2}} \cdot \frac{J_{1}\left(2 \beta_{k} a_{2} \sin \phi \cos \left(\beta_{a / 2}\right)\right)}{\left(\cos \left(\pi / \eta_{2}\right)-\cos \left(3 \pi / \eta_{2}\right)\right)^{2}}
\end{aligned}
\]

At and near the tailor aspect \((\Phi=\pi)\) small angle approximation of equations (2) -(5) yield:
\[
\begin{aligned}
\sqrt{\sigma} e^{j \rho}= & 2 \sqrt{\pi}\left[\left(k \cot \left(\beta_{a / 2}\right)\right) a_{2}^{2} \frac{J_{1}\left(2 k a_{2} \sin \phi \cos (\beta a / 2)\right)}{\left(2 k a_{2} \sin \phi \cos (\beta a / 2)\right)} e^{-j \pi / 2}\right. \\
& \left. \pm a_{2} \frac{\sin \left(\pi / \eta_{2}\right)}{\eta_{2}} \cdot \frac{\left.J_{2}\left(2 k a_{2} \sin \phi \cos \beta a_{2}\right)\right)}{\left(\cos \left(\pi / \eta_{2}\right)-\cos \left(\beta_{a} / \eta_{2}\right)\right)}\right]
\end{aligned}
\]

For \(\Phi=\pi / 2-\alpha\), the expression for the radar-cross-section, using physical optics theory, may be written as:
\[
\begin{aligned}
\sigma(\phi=\pi / 2-\alpha)= & \frac{8 \pi}{9 \lambda}\left[a_{2}^{3 / 2}-a_{1}^{3 / 2}\right]^{2} \cos \left(\beta_{a} / 2\right) / \\
& {\left[\sin ^{2} \alpha \cos \alpha\right] }
\end{aligned}
\]

\section*{EXPERIMENTAL DETAILS}

The experiment was conducted by General Dynamics at Forth Worth, Texas: Operating frequency of 6.050 GHz was used. All other details are listed in the respective diagrams.

ANALYTICAL AND/OR EXPERIMENTAL PLOTS
These results are ploted in Figs. 2 and 3.

\section*{INTERPRETATION OF RESULTS}

The general agreement between theory and experiment is very good. Generalization of formulas in terms of an unrestricted bistatic parameter \(\beta\) (where \(\beta\) is the projection of \(\beta\) in the azimuth plane) is straight forwarded. Therefore, the theory is suitable for scintillation, doppler spectrum and coherent radar studies, as well as for grosser aspects of RCS investigations.

\(\because\)
Fig. 1. Scattering centers on frustrum.


Aspect Angle \(\emptyset\) degrees


Aspect Angle \(\varnothing\) degrees
Fig. 2. Bistatic scattering matrix for frustrum。 \(2 a 1=2.507\), \(2 \mathrm{a}_{2}=3.239,2 \mathrm{~h}=2.083, \beta_{a}=30.0\) degrees. Dotted line indicates geometrical diffraction theory (single diffraction); solid line indicates experimental.



Fig.3. Bistatic radar cross section of frustrum for vertical and horizontal polarizations. \(2 \mathrm{a}_{1}=2.510,2 \mathrm{a}_{2}=3.844,2 \mathrm{~h}=3.804\) Des30.0 degrees. Dotted line indicates geometrical diffraction theory (single diffraction); solid line indicates experimental.

Keller's Geometrical Theory of Diffraction, with scattering centers concept, is applied to investigate the high frequency scattering from a finite rectangular cylinder. Theoretical expressions of RCS as a function of frequency and aspect angle are derived. Experimental work is also reported to compare the results for the mono-static case.

\section*{TARGET AND COORDINATE SYSTEM}

The target geometry and coordinate system used is shown in Fig. 1.

ANALYTICAL EXPRESSIONS
Based upon this theory, there will be three scattering centers and the final expression for the mono-static radar-cross-section may be written as:
\[
\sigma=\left[\sqrt{\sigma_{1}} \exp j \rho_{1}+\sqrt{\sigma_{2}} \operatorname{expj} \rho_{2}+\sqrt{\sigma_{3}} \operatorname{expj} \rho_{3}\right]^{2}
\]
with the amplitude of the contribution reradiate from each center 'given by
\[
\begin{aligned}
\sqrt{\sigma_{1}}=\frac{46}{3 \sqrt{\pi}} \sin \left(\frac{2 \pi}{3}\right) & {\left[\left\{\cos \left(\frac{2 \pi}{3}\right)-\cos \left(2 / 3 \pi+\frac{4}{3} \phi\right)\right\}^{-1}\right.} \\
& \left.+\left\{\cos \left(\frac{2 \pi}{3}\right)-1\right\}^{-1}\right]
\end{aligned}
\]
\[
\begin{aligned}
\sqrt{\sigma_{2}}= & \frac{4 b}{3 \sqrt{\pi}} \sin (2 \pi / 3) \\
& \mp\{\cos (2 \pi / 3)-\cos (4 \phi / 3)\}^{-1} \\
& \left.+\cos (2 \pi / 3)-1\}^{-1}\right] \\
\sqrt{\sigma_{3}}= & \frac{4 b}{3 \sqrt{\pi}} \sin \left(\frac{2 \pi}{3}\right)\left[\{\cos (2 \pi / 3)-\cos 2 / 3(\pi-2 \phi)\}^{-1}\right. \\
& \mp\{\cos (2 \pi / 3)-1\}]
\end{aligned}
\]
and with the phase of contribution reradiate from each center given by:
\[
\begin{aligned}
& \rho_{1}=-2 k(a \sin \phi+c \cos \phi)+\pi / 4 \\
& \rho_{2}=-2 k(a \sin \phi-c \cos \phi)+\pi / 4
\end{aligned}
\]
\[
\rho_{3}=2 k(a \sin \phi-c \cos \phi)+\pi / 4
\]
\(k=2 \pi / \lambda: \quad \lambda=\) wavelength.
These, equations were programmed on computer for \(0.5^{\circ} \leqslant \Phi \leqslant 89.5^{\circ}\)

\section*{EXPERIMENTAL DETAILS}

Experiment was conducted at Cornell Aeronautical Labs, to measure the mono-static radar-cross-section of the rectangular cylinder using ka band pulsed-radar range with operating frequency 34.85 GHz . The model. dimensions used are: \(2 \mathrm{a}=14.763 \lambda\); \(2 b=171716 \lambda ; 2 c=2.26 \lambda\).

\section*{ANALYTICAL AND/OR EXFERIMENTAL PLOTS}

The results are plotted in Figs. \(2 a\) and \(2 b\).

\section*{INTERPRETATION OF RESULTS}

There seems to be a good agreement at all aspect angles in both cases between theory and experiment. It will improve for long cylinders and when the effect of multiple diffractions terms are also taken into account. The present analysis can be extended to handle bistatic and specular cases. The espressions valid for arbitrary aspect angles are yet to be develpoed.

\[
0 \leqslant \Phi \leqslant \pi / 2
\]

Fig. I Scattering centres on a rectangular cylinder.


a, Horizontal-Polarization

Fig. 2 Radar cross-section of rectangular cylinder for vertical and horizonital polarisations.

RADAR SCATTERING FROM BLUNTED. CONE TIPS

In this study radar-cross-section expressions are developed by using exact electromagnetic theory for:
1. Ball-point tip cone
2. Round-tip cone
3. Concave-tip cone

Results obtained from these expressions are further compared with the results obtained by Physical Optics Theory and the so called "Crude Model Theory," which approximates blunt cone as a combination of pointed cone plus sphere.

TARGET AND COORDINATE SYSTEM
1. Ball-point tip semi-infinite cone is shown in Fig. la.
where \(r=a\) for \(0 \leqslant \theta \leqslant \pi-\alpha\)
\(\theta=\pi-\alpha\) for \(々>a\)
2. Round-tip semi-infinite cone is shown in Fig. lb.
where \(r=-R \cdot \sec \alpha\left[\cos \theta+\sqrt{\cos ^{2} \theta+\cos ^{2} \alpha}\right]\)
for
\(R=a \cot \alpha\)
3. Concave-tip semi-infinite cone is shown in Fig. lc. where \(r=R \quad\) for \(\pi-\alpha \leqslant \theta \leqslant \pi\)

ANALYTICAL EXPRESSIONS
1. Using exact theory, the radar-cross-section of a ballpoint tip cone may be written as:
\[
\begin{aligned}
& \sigma=\pi / k^{2} \left\lvert\,\left[\sum_{\nu} \frac{\nu(\nu+1)}{N_{\gamma}} \exp (j \nu \pi)-\sum_{\mu} \frac{\mu(\mu+1)}{N_{\mu}} \exp (j \mu \pi)\right]\right. \\
& -2 j\left[\sum_{\gamma} \frac{\gamma(\nu+1)}{N_{\nu}} \exp (j \nu \pi) \frac{\dot{J_{\nu}} \mid n_{\nu}}{1+j J_{\nu} / \eta_{\mu}}-\sum_{\mu} \frac{\mu(\mu+1)}{N_{\mu}} \exp (j \mu \pi) \frac{J_{\mu}^{*} / \eta_{\mu}^{*}}{1+J_{\mu}^{\prime j} / n_{\mu}^{*}}\right]^{2} \\
& \gamma_{n} \approx n-\frac{n(n+1)}{4} \alpha^{2}+\left\{n ^ { 2 } ( n + 1 ) ^ { 2 } \left[1+I_{n}(\alpha / 2)+\psi(n+1)\right.\right. \\
& +\Psi(n-1)-24(1)]+2 n(n+1)^{3}+4 n(n+1) / 3+3(n-1) * \\
& n(n+1)(n+2) / 2\} \alpha^{4} / 6 \\
& \mu_{n} n \quad n+\frac{n(n+1)}{4} \alpha^{2}+\left\{n^{2}(n+1)^{2}[1+2 \ln (\alpha / 2]+\psi(n+1)\right. \\
& +4(n-1)-2 \psi(1)]+n(n+1)(2 n+1)-n(n-1)(n+1) x \\
& (n+2) / 2-n(n+1) / 3\} \alpha^{4} / 16 \\
& {\left[\begin{array}{l}
N \gamma_{n} \\
N \mu_{n}
\end{array}\right]=2 n(n+1) / 2 n+1\left\{1 \pm \alpha^{2} 2 n(n+1) / 2(2 n+1)\right\}}
\end{aligned}
\]

These approximations are valid, provided that \(n \lll 2\)
11. Using exact theory, radar-cross-section expressions for a round-tip and concave-tip cones may be written as:
\[
\begin{aligned}
& \sigma=\pi / k^{2} \mid \alpha^{2} / 2-2 j \sum_{n, m} j^{m+n}(2 m+1) n(n+1) / m(m+1) \times \\
& {\left[\frac{\left.A_{n, \gamma_{m}-j c_{n, m_{n}}}^{B_{n, v_{n}}}-\frac{C_{n, k_{m}}+j \ddot{A}_{n, m_{m}}}{D_{n, \mu_{n}}}\right]\left.\right|^{2}}{}\right.}
\end{aligned}
\]
111. Using physical optics theory, for nose-on incidences, the back-scattering cross-section for the concave tip is: (neglecting the cone termination at infinity)
\[
\sigma=4 \pi k^{2} R^{4}\left|\frac{(2 j k R-1) \exp (2 j k R)}{(2 k R)^{2}}-\quad \frac{(2 j k R \cos \alpha-1) \exp (2 j k R \cos \alpha)}{(2 k R \cos \alpha)^{2}}\right|^{2}
\]
IV. Using physical optics theory, the backscattering-cross section may be written as:
\[
\begin{aligned}
\sigma=\pi a^{2}\{1- & \frac{\sin [2 h a(1-\sin \alpha)]}{k a \cos ^{2} \alpha}+\frac{1+\cos ^{4} \alpha}{4(k a)^{2} \cos ^{4} \alpha} \\
& \left.-\frac{\cos [2 k a(1-\sin \alpha)]}{2(k a)^{2} \cos ^{2} \alpha}\right\}
\end{aligned}
\]
V. RCS for round-tip cone, using crude model, may be written as:
\[
\sigma^{-}=\sigma^{-} \text {cone }+\therefore \sigma_{\text {sphere }}
\]

Furthermore, Table 1 shows scaling of \(\left(\sigma / \pi a^{2}\right)\) min. as a function of \(\alpha\)

TABLE 1
Scaling of \(\left(\sigma / \pi a^{2}\right)\) min As a Function of \(\alpha\)
\begin{tabular}{|c|c|c|}
\hline Tip Shape & \(\left(6 / \pi a^{2}\right)_{\min } \ldots\) & Location (ka) \\
\hline \[
\text { Rounded }\left\{\begin{array}{l}
\text { Exact } \\
\begin{array}{l}
\text { Physical } \\
\text { Optics }
\end{array}
\end{array}\right.
\] & \(0.7 \alpha^{2}\) \(0.8 \alpha^{2}\) & \[
\begin{aligned}
& 0.8 \alpha \\
& 0.8 \alpha
\end{aligned}
\] \\
\hline \[
\text { Concave }\left\{\begin{array}{l}
\text { Exact } \\
\text { Physical } \\
\text { Optics }
\end{array}\right.
\] & \[
\begin{gathered}
0.6 \alpha^{2} \\
\alpha^{2}
\end{gathered}
\] & \[
\begin{aligned}
& 0.9^{2} \alpha \\
& 0.75 \alpha
\end{aligned}
\] \\
\hline  & \(1.6 \alpha^{8 / 3}\)
\(1.6 \alpha^{8 / 3}\) & \[
\begin{aligned}
& 0.5 \alpha^{2 / 3} \\
& 0.5 \alpha^{2 / 3}
\end{aligned}
\] \\
\hline
\end{tabular}

ANALYTICAL AND/OR EXPERIMENTAL PLOTS
The above equations are programmed on a computer and results are plotted in Figures 2, 3, 4, and 5.

\section*{INTERPRETATION OF RESULTS}

For the ball-point tip case, exact theory agrees very closely
 results. The RCS of rounded and concave tips were calculated by means of exact theory and by using physical optics theory. These results show close agreement. The agreement is better for the rounded tip is probably due to the smooth tip cone join, wereas crude model failed miserably in cases of round and concave tip cones.


Fig. 1. (a) Ball-point tip. (b) Rounded tip. (c) Concave tip.


Fig. 2. \(\sigma / \pi a^{2}\) for ball-point, tip as a function of ka for \(\alpha=10^{\circ}\); ais shown lightly are the curves for a pointed cone and an isolated sphere.


Fig. 3. \({ }^{\left(\sigma / \pi a^{2}\right)}\) for ball-point tip as a function of \(k a\) for \(\alpha=5^{\circ}, 8^{\circ}, 10^{\circ}\), and \(12^{\circ}\); curves for pointed cones and an isolated sphere are shown lightly.


Fig.4. \(\sigma / \pi a^{2}\) for concave and rounded tips as functions of \(k\) for \(\alpha=10^{\circ}\); also shown are physical optics results.

Fig. 5. \(\sigma / \pi a^{2}\) for rounded tip as a function of \(k\) for \(\alpha=5^{\circ}, 8^{\circ}, 10^{\circ}\), and \(12^{\circ}\).

This study derives the far-field backscatter radar cross section of a spherical shell for nose-on and near nose-ion as pects for the high frequency. case. The theoretical expressions are derived by first computing specular contributions by physical optics method and then adding to it the edge diffracted term. The sommerfield half-plane solution is modified to give the edge contribution. This technique involves deriving a correction factor, based on phase considerations, which takes into account the differences between the basic two dimensional problem considered and the three dimensional problem of interest here. Analytical results are compared with the experimental results.

\section*{TARGET GEOMETRY AND COORDINATE SYSTEM}

The target geometry and coordinate system used is shown in Figs. 1, 2, \(\because\) and 4.

\section*{ANALYTICAL EXPRESSION}

Using technique of adding specular terms by physical optics and the edge diffraction term by sommerfield theory; the expression for the RCS, for the nose-on case, may be written as:
\[
\sigma=4 \pi a^{2} \sin ^{2} k a(1-\cos \gamma)
\]

For the case of a near nose-on aspects, or in a region such that \(\sin \theta \gg \frac{1}{2 k b}\) (where \(b=1 \quad \sin \gamma\) ). Furthermore, this region is characterized by the following:
1. Specular reflection is present.
2. All of the edge is in "lit" region.
3. The entire edge is not in phase at any angle.

RCS is given by:
\[
\begin{aligned}
\sigma\binom{V}{H} & =\pi a^{2}(1-\sqrt{\sin \gamma / 4 \pi k a \sin \theta} \\
& \left.\left\{e^{j \eta_{1}}\left[\frac{1}{\sin (\gamma-\theta)} \mp 1\right]+e^{j n_{2}}\left[\frac{1}{\sin (\gamma-\theta)} \mp 1\right]\right\}\right|^{2}
\end{aligned}
\]
where
\[
\begin{aligned}
& \eta_{1}=2 k \dot{a}[1-\cos (\gamma-\theta)]+\pi / 4 \\
& \eta_{2}=2 k a[1-\cos (\gamma+\theta)]-\pi / 4
\end{aligned}
\]

\section*{EXPERIMENTAL DETAILS}

To compare the theoretical results for nose-on case, experimental data obtained by Blore and Musal (1960 is used. But for the case of near-nose-on aspect, two models are made from this walled copper and measured at the Conduction Corporation Radar Cross Section Measuring Range. Measurements were made at frequencies of 9.00 KMC and 10.23 KMC , and for both horzontail and vertical polarizations.

TABLE 1
\begin{tabular}{|c|c|c|c|}
\hline Model & Radius of Curvature (a) & \(\gamma\) & \begin{tabular}{l}
Ring \\
Radius \\
(b)
\end{tabular} \\
\hline A & 4.44 cm & \(48 \frac{1}{2}^{\circ}\) & 3.32 cm \\
\hline B & 4.44 cm & . \(60 \frac{1}{2}^{\circ}\) & 3.87 cm \\
\hline
\end{tabular}

ANALYTICAL AND/OR EXPERIMENTAL PLOTS
Theoretical and experimental resuits for both cases are shown in Figures 2, 5, 6, 7, and 8.

\section*{INTERPRETATION OF RESULTS}

It may be seen that results obtained are valid when \(k b \gg 1\) (where \(b\) is the edge radius), for segments smaller than a hemisphere. For noseon incidence, it is shown that the edge contribution has the same value as the well known specular contribution. \(A_{n}\) important consequence of this is strong interferences between these two contributors. Comparasion of this result with experiment shows that it is in good agreement. It is found to be much more accurate than the ordinary physical optics results.


Fig. 1. Spherical shell segment.


Fig.2. Radar cross section vs. depth for - spherical shell segment.


Fig. 3. Parameters for \(\phi^{\prime}=\varnothing\).


Fig.4. Parameters for \(\sigma^{\prime}=\phi+\pi\).

Horizontal Polarization

- - -Experiment-Hor. Pol.
\(\mathrm{x} x\) xTheory -Hor. Pol.
Experiment-Ver. Pol.

Fig.7. Cross section vs. aspect angle-Model A, frequency \(=10.23 \mathrm{kMc}\).


\footnotetext{
Aspect Angle
- - Experimental.-Hor. Pol.
\(x\) x xTheory -Hor. Pol.
}


Aspect Angle \(\overline{\mathrm{x}} \overline{\mathrm{x}} \overline{\mathrm{x}}\) Experiment-Hor. Pol.

Experiment-Ver. Pol. Theory -Var. Pol.

Fig. 5. Cross section vs, aspect angle-Model A, frequency \(=9.00 \mathrm{kMc}\).
 Experiment Hor. Pol. Experiment -Der. Pol. \(\overline{\mathrm{x}} \overline{\mathrm{x}} \overline{\mathrm{x}}\) Theory -Hor. Pol. Theory -Ter. Pol. Fig.6. Cross section vs. aspect angle-Model B, frequency \(=9.00 \mathrm{kMc}\).

The study deals with the calculations of radar-crosssection of non-conducting bodies. Two approximate methods are proposed: The method of super-position approximation, for calculating the RCS of a concentric dielectric-clod sphere. This approximation treats scattering by outer and inner bodies separately; refraction at the free space/dielectric interface are introduces to modify the size of the inner body. This technique is easily applicable but requires that the properties of inner and outer body be known separately. This technique valid prococircled
\[
\left(z_{2}-z_{1}\right) / \lambda>\left(\lambda / 4 \pi n 1_{1}\right)
\]
where \(r_{1} r_{2}\) are the radii of inner and outer shells.
Second technique called, "the modified geometrical optics theory', is applied to calculate the RCS of dielectric bodies. The basis of this modified geometrical optics methods is ray tracing. The \(\therefore\) wave fronts, which are normal to the rays; can be determined by tracing individual paths for a number of rays adjacent to the stationary ray and glory ray.

Finally, results obtained by these two methods are compared against the results obtained by exact theory.

\section*{ANALYTICAL AND/OR EXPERIMENTAL RESULTS}

Results obtained by Supperposition, Modified Geometric
Theory, and exact theory, techniques are shown in Figures
```

1, 2, 3, 4, and <5.

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\section*{INTERPRETATION OF RESULTS}

The analysis shows that superposition gives excellent results when the radius of the conducting body is less than \(0.5 \lambda\). This method fails to predict the depth of the nulls accurately for extremely deep nulls and for bodies with larger inner radius but predicts the maxima for such cases with rasonable accuracy. The modified geometrical optics theory should be used for larger inner bodies if the depth of the nulls is of interest. The results obtained from these studies seem to be in good agreement with theory.

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Fig. 1. Bistatic scattering of dielectric coated conducting spheres.

Fig. 2. Bistatic scattering of dielectric coated conducting spheres.


Fig．3．Baclscattering radar cross section of＇ka dielectric sphere（ \(\mathrm{E}_{2}=2.592\) ） as a function of ka by the use of modified geometrical optics．


Fig．Bistatic cross section of a plasma sphere with \(\epsilon_{V}=0.74\) and \(a \ll=0.75\) ．


Fig. 5:. Radar cross sections of plasma-clad conducting spheres.

\section*{CROSS POLARIZATION DIAGNOSTICS}

When a body is illuminated by an electromagnetic wave, the backscattered field usually includes direct and cross-polarization components. Historically, the former has been more widely studied because it is the component typically sensed by nomostatic radars and since it contains all specular contributions, it tends to be larger of the two. In contrast, the cross-polarized return is produced by more subtle contrubutions which elementary theories cannot predict.

Because of this dependence on the finer details, of the object, the cross polarized return contains information about the scatter that is not readily obtainable from the direct return. The relationship of the transverse body dimensions and severity of any edges to the cross polarized RCS is shown.

ANALYTICAL EXPRESSIONS
Based upon geometrical theory of diffraction, for a right circular cone with half-angle \(\gamma\), an expression for cross-polarized RES ( \(\gamma_{c r}\) ) may be written as:
\[
\frac{\sigma_{c r}}{\lambda^{2}}=\frac{1}{\pi}\left\{A k_{a} J_{2}(\xi)\right\}^{2}
\]
where \(A=n^{-1} \cot \pi /(2 n) ; n=\frac{3}{2}+\gamma / \pi, \varepsilon=2 k_{a} \sin \phi\) and \(J_{2}(\xi)\) is the bessel function of second order. Equation 1 reduces to an expression for the disk for \(n=2\) but is relatively insensitive to cone angle, Similarly, an expression for a cone-sphere may be written as:
\[
\frac{\sigma_{c r}}{\lambda^{2}}=\frac{1}{4 \pi}\left\{\frac{\cos ^{2} r \cos \phi}{\cos 2 r+\cos 2 \phi}\right\}^{2}\left\{J_{2}^{2}(\xi)+\tan ^{2} r \tan ^{2} \phi J_{1}^{2}(\xi)\right\}
\]
where \(\xi=2 \mathrm{ka} \cos \gamma \sin \phi j \neq\) aspect angle.

\section*{EXPERIMENTAL DETAILS}

The -S- and - X-band measurements of the backscattering for four axially symmetric bodies: thin disks, right circular cones, cones with rounded edges and cone-spheres, are undertaken, The transmitted and received polarizations are inclined \(\pm 45^{\circ}\) to the horizontal, and the resulting patterns were recorded over an angular range \(-30^{\circ} \leqslant \Phi \leqslant 30^{\circ}\) about the axis.

\section*{ANALYTICAL AND/OR EXPERIMENTAL PLOTS}

The analytical and experimental results obtained are shown in Fig. 1.

\section*{INTERPRETATION OF RESULTS}

The analysis shows that disks and sharply edged cones have the strongest returns, cone-spheres the weakest, and cones with rounded edges have intermediate values. The difference between cones and cone-sphere is as much as \(30 d B\) for \(k a=20\). The agreement between theory and experiment is of the order of 1 dB for disks and narrow cones. In case of cone-sphere, agreement with the experiment is reasonable in view of the extreme by low level measures, but the systematic discrepancy for small (ka) suggests that there may be another source of depolarization, such as creeping waves.


Fig. 1. Cross polarized radar cross sections.
\[
-60-
\]

Approximate theoretical expressions are developed for a thin dielectrix body of revolution on a perfectly conduction plane and surrounded by free space. In particular cases of circular sylinder and cone are treated. The development is based upon image theory.

\section*{TARGET AND COORDINATE SYSTEM}

The target and coordinate system is shown in Fig. 1.

\section*{ANALYTICAL EXPRESSIONS}

Case 1- For the case of a circular cylinder, \(\rho=a\), and the RCS expression may be written as:
\[
\begin{equation*}
\sigma \cong k^{4} V^{2}\left(A \cos ^{2} \alpha+B \sin ^{2} \alpha\right) \tag{1}
\end{equation*}
\]
where \(k=2 \pi / \lambda\) is the free space wave number, \(V=\pi l a^{2}\) is the volume of the cylinder, and
\[
\begin{align*}
& A=A(\epsilon, \beta)= \frac{\sin ^{4} \beta}{\pi}\left(\frac{\epsilon-1}{\epsilon+1}\right)^{2}\left\{(\epsilon+1)^{2}+4 \epsilon^{2} \cot t^{2} \beta\right\}  \tag{2}\\
& B= B(\epsilon, \beta)=  \tag{3}\\
& \frac{\sin ^{4} \beta}{\pi}\left(\frac{\epsilon-1}{\epsilon+1}\right)^{2}\left\{1+\frac{\sin ^{2} \beta}{\epsilon-\cos ^{2} \beta}\right\}^{2} \\
&-6
\end{align*}
\]

Equation (1) is valid if the following assumptions are made:
\[
\begin{align*}
& \frac{l}{\lambda} \gg 1  \tag{4}\\
& k a \sqrt{\left(\epsilon-\cos ^{2} \beta\right)} \ll 1  \tag{5}\\
& 2 k l \cos \beta \gg 1  \tag{6}\\
& \beta \text { is bounded away from zero }  \tag{7}\\
& \quad \sin \beta / \sqrt{\left(\epsilon-\cos ^{2} \beta\right)} \text { is bounded away from zero } \tag{8}
\end{align*}
\]

Case 11- For the case of a right circular cone, whose lateral surface is defined as:
\[
\begin{gathered}
\rho=a(1-(z \mid l)), \quad 0 \leqslant z \leqslant l \\
i f \\
\text { ale } \ll 1
\end{gathered}
\]
the RCS expressions are given by equations (1), (2), and (3), where now \(V=\pi \ell a^{2} / 3\), volume of cone. Assumptions (4) - (8) also apply in this case.

INTERPRETATION OF RESULTS
The expressions of RCS derived here are valid for all bodies of revolution satisfying the restrictions outlined and such that on their lateral surface \(\rho=\rho(z)\) : 5
\[
|(d \rho \mid d z)| \ll 1
\]
\[
\text { for } 0 \leqslant z \leqslant l
\]


Fig. 1. Geometry for the scattering problem.

PREDICTION OF RADAR CROSS SECTION OF A COMPOSITE TARGET USING SCATTERING CENTER THEORY

The radar-cross-section of a composite body consisting of sections of a sphere, cone, cylinder, flare and frustrum is peredieted. The theoretical expressions predicted are programmed on a computer and the results are plotted. The catering center concept is used and such a target will have eight scattering centers.

TARGET GEOMETRY COORDINATE SYSTEM

The target geometry and coordinate system used is shown in Figures \(1^{1}\) and 2 .

ANALYTICAL EXPRESSIONS

A detailed derviation of scattering center contributions is not required for the composite body. Using Geometrical theory of diffraction, one may write by inspection
\[
\begin{aligned}
& \sqrt{\sigma_{2}}=\frac{\sin \pi_{\eta_{2}}}{\eta_{2}} \sqrt{\frac{a_{1} \csc \phi}{k}}\left\{\left[\cos \frac{\pi}{\eta_{2}}-\cos \frac{2 \pi-2 \phi}{\eta_{x}}\right]^{-1} \mp\left[\cos \frac{\pi}{\eta_{2}}-1\right]^{-1}\right\} \\
& 0 \leqslant \Phi \leqslant \Phi_{2} \\
& =0 ; \Phi>\Phi_{2} \\
& \sqrt{\sigma_{3}}=\frac{\sin \pi / \eta_{3}}{\eta_{3}} \sqrt{\frac{a_{1} \csc \phi}{k}}\left[\left[\cos \frac{\pi}{\eta_{3}}-\cos \frac{2 \phi}{\eta_{3}}\right]^{-1} \mp\left[\cos \frac{\pi}{\eta_{3}}{ }^{-1}\right]^{-1}\right\} \\
& 0 \leqslant \Phi \leqslant \Phi_{3} \\
& =0 ; \quad \Phi>\Phi_{3} \\
& \sqrt{\sigma_{4}}=\frac{\sin \pi / \eta_{4}}{\eta_{4}} \sqrt{\frac{a_{2} \csc \phi}{k}}\left\{\left[\cos \frac{\pi}{\eta_{4}}-\cos \frac{2 \pi-2 \phi-2 \times F_{2}}{\eta_{4}}\right]^{-1} \mp\left[\cos \frac{\pi}{\eta_{4}-1}\right]^{-1}\right] \\
& \sqrt{\sigma_{5}}=\frac{\sin \pi / \eta_{2}}{\eta_{2}} \sqrt{\frac{a_{1} \csc \phi}{k}}\left\{\left[\cos \pi / \eta_{2}-\cos \frac{2 \pi+2 \phi}{\eta_{2}}\right]_{0 \leqslant \Phi \leqslant \Phi_{5}}^{-1} \mp\left[\cos \frac{\pi}{\eta_{2}-1}\right]^{-1}\right\} . \\
& =0 ; \text { a }
\end{aligned}
\]
\[
\begin{aligned}
& \sqrt{\sigma_{7}}=\frac{\sin \pi / \eta_{4}}{\eta_{4}} \sqrt{\frac{\eta_{2} \csc \phi}{k}}\left\{\left[\cos \pi / \eta_{L_{4}}-\cos \frac{2 \pi+2 \phi+2 x_{F_{2}}}{\eta_{4}}\right]^{-1} \mp\left[\cos \pi / \eta_{4}^{-1}\right]^{-1}\right\} \\
& =0 ; \quad \Phi_{7} \leqslant \Phi \leqslant \Phi_{8} \\
& 0 \leqslant \Phi \leqslant \Phi \eta ; \Phi_{-8} \leqslant \Phi \leqslant \pi \\
& \rho_{2}=\pi / 4-2 k\left[a_{1} \sin \phi+2 h_{2} \cos \phi\right] ; \rho_{3}=\frac{\pi}{4}-2 k a_{1} \sin \Phi \\
& \rho_{4}=\frac{\pi}{4}-2 k\left[a_{2} \sin \phi-2 h_{3} \cos \phi\right] ; \rho_{5}=-\frac{\pi}{4}+2 k\left[a_{1} \sin \phi-2 h_{2} \cos \phi\right] \\
& \rho_{7}=-\pi / 4+2 k\left[a_{2} \sin \phi+2 h_{3} \cos \phi\right] \\
& \eta_{2}=1+\frac{x_{c}}{\pi} ; x_{c}=\text { cone half angle } \\
& \eta_{3}=1-\frac{x_{F_{1}}}{\pi} ; x_{F_{1}}=\text { flare segment halfangle } \\
& \eta_{4}=1+\frac{x_{f_{1}}+x_{f_{2}}}{T} ; x_{f_{2}}=\text { Frustum halfangle } \\
& k=2 \pi / \lambda \\
& \Phi_{2}=\pi-\tan ^{-1} \frac{a_{2}-a_{1}}{2\left(h_{2}+h_{3}\right)} ; \Phi_{3}=\pi-\tan ^{-1} \frac{a_{2}-a_{1}}{2 h_{3}} \\
& \Phi_{5}=\tan ^{-1} \frac{a_{1}-a_{3}}{2 h_{1}} ; \Phi_{7}=\tan ^{-1} \frac{a_{2}-a_{1}}{2\left(h_{2}+h_{3}\right)} ; \Phi_{8}=\pi-\tan ^{-1} \frac{a_{2}-a_{7}}{2 h_{4}}
\end{aligned}
\]

At a near nose on aspect angles scattering centers \(S_{2}\) and \(S_{5}\) (and \(S_{4}\) and \(S_{7}\) ) expand to form a ring discontinuity. The RCS may be given by:
\[
\begin{aligned}
& {\left[\sqrt{\sigma_{2}} e^{j \rho_{2}}+\sqrt{\sigma_{s}} e^{j f_{5}}\right](\phi \approx 0)=\frac{\sin \pi / \eta_{2}}{\eta_{2}} 2 a \sqrt{\pi} e^{-j 4 k h_{2} \cos \phi}\left[\left\{\cos \frac{\pi}{\eta_{2}}-\cos \frac{2 \pi}{\eta_{2}}\right\}^{-1} x\right.} \\
& \left.J_{0}\left(2 k a_{1} \sin \phi\right)-j \frac{\frac{2}{\pi} \sin 2 \pi / \eta_{2} \tan \phi}{\left(\cos \pi / \eta_{2}-\cos \frac{\pi}{\eta_{2}}\right)} J_{1}(2 k a, \sin \phi) \pm\left\{\cos \frac{\pi}{\eta_{2}}-1\right\}^{-1} J_{2}\left(2 k a_{1} \sin \phi\right)\right] \\
& {\left[\sqrt{\sigma_{4}} e^{j \rho_{4}}+\sqrt{\sigma_{7}} e^{j \rho_{7}}\right](\phi \Delta \phi)=2 \sqrt{\pi} a \frac{\sin \pi / \eta_{4}}{\eta_{4}} e^{j 4 k h_{3} \cos \phi}} \\
& {\left[\left\{\cos \pi / \eta_{4}-\cos \frac{2 \pi-2 x_{F_{2}}}{\eta_{4}}\right\}^{-1} \times J_{0}\left(2 k a_{2} \sin \phi\right)-j \frac{2 / \eta_{4} \frac{\sin \frac{2 \pi+2 x f_{3}}{\eta_{4}} \tan \phi}{\left(\cos \pi / \eta_{4}-\cos \frac{2 \pi+2 \times f_{2}}{\eta_{4}}\right)} \times}{-1}\right.} \\
& \left.J_{1}\left(2 k a_{2} \sin \phi\right) \pm\left\{\cos \pi / \eta_{4}-1\right\}^{-1} J_{2}\left(2 k a_{2} \sin \phi\right)\right]
\end{aligned}
\]

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At the talon and near talon axil aspect, scattering centers \(S_{4}\) and \(S_{7}\) again expand to form a ring discontinuity. Then one may have:
\[
\begin{aligned}
& {\left[\sqrt{\sigma}_{4} e^{j \rho_{4}}+\sqrt{\sigma_{7}} e^{j \rho_{7}}\right](\phi, \pi)=2 \sqrt{\pi} a^{\frac{\sin \pi / \eta_{4}}{\eta_{4}}} e^{-j k 4 h_{3} \cos \phi} \times} \\
& {\left[\left\{\cos \pi / \eta_{4}-\cos 2 \times F_{2} / \eta_{4}\right\}^{-1} \times J_{0}\left(2 k a_{2} \sin \phi\right)-j \frac{\hat{\lambda}_{4} \sin \frac{2 \times F_{2}}{\eta_{4}} \tan \phi}{\left(\cos \pi / \eta_{4}-\cos \frac{2 \times F_{2}}{\eta_{4}}\right)^{2}} \times\right.} \\
& \left.J_{1}\left(2 k a_{2} \sin \phi\right) \pm\left\{\cos \pi / \eta_{4}-1\right\}^{-1} J_{2}\left(2 k a_{2} \sin \phi\right)\right]
\end{aligned}
\]

For the broadside case ( \(\varnothing=\pi / 2\) ), the RCS expression may be written as
\[
\begin{gathered}
{\left[\sqrt[\sigma]{\sigma}_{2} e^{j \rho_{2}}+\sqrt{\sigma}_{4} e^{j \rho_{3}}\right](\phi \exists \pi / 2)=\left[-\sqrt{k a_{1}} 2 h_{2} \frac{\sin \left(2 k h_{2} \cos \phi\right)}{\left(2 k h_{2} \cos \phi\right)} e^{j 3 \pi / 4-j 2 k h_{2} \cos \phi}\right.} \\
\left.\mp \sqrt{\frac{a_{1}}{k}} e^{j \pi / 4}\left\{\frac{1 / \eta_{2} \sin \pi / \eta_{2}}{\cos \pi / \eta_{2}-1} e^{-j 4 k h_{2} \cos \phi}+\frac{\frac{1}{\eta_{3}} \sin \pi / \eta_{3}}{\cos \pi / \eta_{3}^{-1}}\right\}\right] \times \\
-j 2 k_{2} \sin \phi \\
e
\end{gathered}
\]

\section*{ANALYTICAL PLOTS}

The RCS expressions were run on digital computer with a target dimensions (in inches) for test calculations shown as below:
\[
\begin{aligned}
& a_{1}=.90^{\prime \prime}, \quad a_{2}=1.70^{\prime \prime} \\
& \text { and } A=1.70^{\prime \prime}
\end{aligned}
\]

These results are plotted in figures 3. and 4,.

\section*{INTERPRETATION OF RESULTS}

The observed dincontinufies in the predicted RCS indicate aspects for which further modification of geometrical diffraction theory is required. The discontinuity observed for \(\emptyset=5.6\) degrees is due to the shadowing of ring discontinuity by the contribution due the scattering center \(\mathrm{S}_{4}\) and \(\mathrm{S}_{7}\) of Figure 2 . For \(\varnothing=75.6\) degrees, one may replace the return from this ring discontinuity by the contribution due to scattering center \(S_{4}\), according to equations 14 and 24 . The discontinuity observed for \(\emptyset=10\) degrees is due to the shadowing of scattering center \(\mathrm{S}_{5}\). Multiple diffraction consideration will allow smooth transition here. Two singularities remain in the formulation sue to the use of unmodified geometrical diffraction theory in describing specular scattering by conical surfaces. The effects of these singularities are the two spikes occuring at \(\varnothing=74.5\) degrees (due to the cone specular) and at \(\emptyset=70\) degrees (the specular from the flare). Since the theory fails gracefully for conical speculars, physical optics estimates may be. introduced in a small angular region centered about specular aspect. The remaining discontinuity occurs at \(\varnothing=117\) degrees, at which aspect, the return from the ring singularity
is introduced. In actual fact, this ting contribution is valid for aspect with 15 degrees of the tail-on axail aspect since it is based upon small angle approximation.


Fig. 1: Scattering Centers On Composite Body


Fig. 2: Composite Geometry


F1g. 35 Radar Cross Section of Composite body, Vertical Polarization.


Figure \(4:\) Radar Cross Section Of Composite Body, Horizontal Polarization

This study presents a method for estimating RCS of complex shapes such as an aircraft, missle, and satellite. It is based upon methods already developed for simple shapes. The theoretical method for estimating the RCS of complex shapes utilizes the following steps.
1. The complex shape is resolved into an ensamble of components each of which can be geometrically approximated by a simple shape in such a way that the RCS of simple shape approximates the RCS of the component it replaces.
2. RCS values are computed for the approximations to the components (simple shapes) derived in step (1).
3. Steps (1) and (2) are then combined to yield an estimate of the RCS of entire body.

Two methods i. e. Urelative phase method" and "random phase method" are proposed. Furthermore, theoretical results are compared against the experimental results.

TARGET AND COORDINATE SYSTEM
Two targets are investigated:
A missle model is shown in Fig. it.
An aircraft model is shown in Fig. \(2 *\).

ANALYTICAL EXPRESSIONS
Relative Phase Method - For any given combination of aspect
angle, wave length, and polarization, \(N\) components for which

RCS values have been computed, e. g., the set of values.
\[
\sigma_{1}, \sigma_{2}, \sigma_{3}, \cdots \cdots, \sigma_{N}
\]

One of the methods of combination involves the consideration of the relative place angle between the returns from these \(N\) scatters. Therefore, the RCS of the entire body may be written as:
\[
\sigma_{p}=\left|\sum_{j=1}^{N}\left(\sigma_{j}\right)^{1 / 2} \exp \left(j \Phi_{j}\right)\right|^{2}
\]
where \(\sigma_{j}=\) the RCS of the \(j\) th component and \(\Phi_{j}=\) the relative phase angle associated in the \(j\) th component.

RANDOM PHASE METHOD- In case where \(\Phi_{j}\) are randomly distributed, then upon averaging over the \(\Phi_{j}\), one obtains the expressions:
\[
\begin{aligned}
& E[\sigma]=\sum_{j=1}^{N} \sigma_{j} \\
& E[\sigma] \pm S \\
& S^{2}=\left(\sum_{j=1}^{N} \sigma_{j}\right)^{2}-\sum_{j=1}^{N} \sigma_{j}^{2}
\end{aligned}
\]

\section*{ANALYTICAL AND/OR EXPERIMENTAL PLOTS}

For the case of a Missile, results are shown in Figs. 2,
-3 , and -4 , and for the case of a large jet-aircraft, results are shown in Figures 6 and 7 .

\section*{INTERPRETATION OF RESULTS}

It may be noted that relative phase method is not good for large aircrafts at small wavelengths. In such cases random phase method should be used. Techniques discussed here are most effective tools with which to describe modification, and even the design of RCS characteristics of complex shapes.


Fig.il. Sketch of missile model.


Fig \(2^{\prime}\). Missile with fins-theory and experiment for: vertical polarization (E vector normal to plane in which aspect is measured, two of the fins contained in that plane). X X X experimental points;- -theory (in , phase estimation); experneory (random phase estimation).


ASPECT ANGLE


ASPECT ANGLE
Fif. 3; Missile with fins ., theory and experiment for \(E\) vector slanted at a \(45^{\circ}\) angle to the plane in which aspect is measured (two fins located in that plane). X X X Experimental points;----theory (in-phase esti... mation);__theory (random phase estimation).

Fig. -4 . RCS for a missile near broadside. \(\qquad\) Experimental data; . . . theory (relative phase).
\[
-76-
\]


Fig. 5?. Monostatic and bistatic scattering from the nose of a large aircraft (the \(\theta=0^{\circ}\) case for \(\beta=0^{\circ}\) and \(\beta=135^{\circ}\) ).

(a) \(\quad \theta \rightarrow\)



Fig. 6; Bistatic RCS of a large jet aircraft at 250 MHz (horizontal polarization). - \(\beta=0^{\circ} ;--\beta=30^{\circ} ;\)
\(\cdots \quad \beta=60^{\circ} ;-\cdots=135^{\circ}\)

Fig. 7: Bistatic RCS o a missile shape at 200 MHz (horizontal polari zation)._ \(\beta=0^{\circ}\); - \(\beta=40^{\circ} ;-=\overline{1500}\).

\section*{COMPUTERIZED RAY OPTICS METHOD OF CALCULATING AVERAGE VALUE RADAR-CROSSSECTION}

In order to estimate the RCS of airborne vehicles, it is often necessary to consider the average values of radar returns. A method providing the quick estimate of the average static radar cross sectimon of the vehicle components would ve useful. This study extends a method of ray optics called computerized ray optics method to determine the RCS of a body of arbitrary shape, and which may be concave and/or convex on which double reflection and depolarization can occur. The reason for this method can be used here on an arbitrary body is that rather than finding an expression for the RCS, a large number.' of rays are simply "thrown" at the body. The reflection boundary conditions for a perfect conductor (Etangential \(=0\), and Dnormal are continuous) collected at the receiver and summed (vector-wise and phasewise). Analytical results are compared against the experimented results.

\section*{TARGET GEOMETRY AND/OR CONDUCTIVE SYSTEM}

The explanation of the target and coordinate system used is shown in Figs. 1, 2, and \(\#\).

\section*{ANALYTICAL EXPRESSIONS}

The bistatic radar cross section is defined as:
\[
\sigma_{\theta}\left(\theta_{\text {nom }}, \phi_{\text {nom }}\right)=\left(P_{\theta}\left(\theta_{\text {nom }}, \phi_{\text {nom }}\right) / d \Omega\right) /\left(P_{1 N} / 4 \pi\right)
\]
\[
\begin{aligned}
& \sigma_{\theta}=\frac{4 \pi \sqrt{\left[\sum_{A L R A Y S} R e\left(P_{\theta}\right)\right]^{2}+\left[\sum_{A L L R A Y S} \operatorname{Im}\left(P_{\theta}\right)\right]^{2}}}{(d \Omega)(N)\left(P_{i}\right)} \\
& \sigma_{\phi}=\frac{4 \pi \sqrt{\left[\sum_{A L L A A Y S} R e\left(P_{\phi}\right)\right]^{2}+\left[\sum_{A L L R A Y S} \operatorname{Im}\left(P_{\phi}\right)\right]^{2}}}{(d \Omega)(N)\left(P_{2}\right)}
\end{aligned}
\]
where
\[
P \theta=\operatorname{Re}(P \theta)+j \operatorname{lm}(P \theta)
\]
\[
P \emptyset=\operatorname{Re}(P \emptyset)+j \operatorname{lm}(P \emptyset)
\]
\(P_{2}\) is the power in the 2 nd incident ray and is equal to unity and \(N\) is the number of rays per square meter.

\section*{EXPERIMENTAL DETAILS}

An experimental body is shown in Fig. 3. It is composed of an ogive " 0 ", a cylinder " \(C\) ", a hemisphere " \(S\) ", and a winglike body 'W". It was is to test the method of computerized ray optics to calculate average values of RCS of bodies that can display l) interference phenomena, 2) double reflections, and 3) depolarization.

ANALYTICAL AND/OR EXPERIMENTAL PLOTS

The analytical and experimental plots are shown in Fig. 4.

\section*{INTERPRETATION OF RESULTS}

The analysis shows that agreement between measured and calculated results in generally good and within \(\pm 2 \mathrm{~dB}\), except at \(\theta=0, \emptyset=0\), where a crepting wave was identified experimentally. The angles at
which large creeping wave will be excited can be predicted by observing the angles of glancing incidence at a discontinuity of the surface.


Fig. li. Arbitrary body defined by patchwork surface.

* Ray Hits Block
- Ray above surface Block Hit
II Ray below Surface

Fig. 2. Double reflection.


Fig. 3. Experimental body.


Fig. 4. Monostatic radar cross section versus \(\theta\) for \(\phi=0\) and \(\varnothing=180^{\circ}\) at 10.0 GHz for body 1 .
\(-82\).

COMPARASION OF RCS BY MICROWAVE AND OPTICAL SIMULATION TECHNIQUES

\begin{abstract}
Radar cross section of a jet aircraft is obtained using microwave and optical simulation techniques.
\end{abstract}

TARGET AND COORDINATE SYSTEM
\(\left(\frac{1}{4}\right)\) scale model of a modern jet aircraft is used.

\section*{EXPERIMENTAL DETAILS}

Mictowave measurement are undertaken using a (cw) balancedbridge RCS measurement system at 4.4 GHz , and ( \(\frac{1}{4}\) ) scale model of a modern jet aircraft model to simulate quasi-monostatic RCS measurements at 8.6 GHz of the full scale aircraft.

The optical simulation measurements are conducted using a monostatic optical simulation system and ( \(1 / 35\) ) scale model of the same aircraft. The model was loaded with vacum deposit aluminium producing a mirror like surface.

EXPERIMENTAL PLOTS
The results obtained from both these techniques are plotted in Fig. 1.

\section*{-8 .5.}

\section*{INTERPRETATION OF RESULTS}
The mean radar-cross-sections are considered to be valid for frequencies between 3 GHz and 24 GHz . Results of measurement agree with in an average of 3.5 dB and that both techniques can be used to obtain RCS at microwave frequencies of complex shapes such as aircraft.


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