# DETERMINATION OF CONSTANT-VOLUME BALLOON CAPABILITIES FOR AERONAUTICAL RESEARCH 

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Symbol
Definition

## English Symbols

a
a
$\widetilde{\mathbf{a}}$

A
$\mathbf{A}_{i j}$
b
b
$\tilde{b}$

B
$B\left(k, w ;{ }_{3}\right)$
$B_{l k}$
c
c
C

$$
\frac{36 \mu}{(2 \sigma+\rho) D^{2}} \text { (Appendix B only) }
$$

first constant in linearized approximation for Basset term (Appendix $M$ only)
$\frac{\mathrm{rD}}{\mathrm{T}_{\mathrm{O}}}$ (Appendix C only)
fluid wave amplitude for $x_{1}$-direction
element of experiment matrix in Phase I
$\frac{3 \rho}{2 \sigma+\rho}$ (Appendix B only)
second constant in linearized approximation for Basset term (Appendix $M$ only)
g/Ry (Appendix C only)
fluid wave amplitude for
$x_{2}$-direction
Fourier transform of $u^{\prime}{ }_{1}\left(x_{1}, t, x_{3}\right)$
element of experiment matrix in Phase II
$\frac{18}{(2 \sigma+\rho) D} \sqrt{\frac{\rho \mu}{\pi}}$ (Appendix B only)
phase velocity, $\omega / k$
fluid wave amplitude for
$\mathrm{x}_{3}$-direction

## LIST OF SYMBOLS

(Continued)

Symbol
$C_{D}$
$C_{D \ell}$
$\mathrm{C}_{22}$
$C_{33}$
d

D
$D_{\text {iim }}$
f()
$F\left(k, \omega ; X_{30}\right)$
$\left(F_{B}\right)_{i}$
$\left(F_{D}\right)_{1}$
(Fg $_{i}$
$(F p)_{i}$
$g$
$G_{1}$
$H_{L}\left(\tau ; X_{30}\right)$

Definition
drag coefficient
drag coefficient ( $10^{3}<\operatorname{Re}<10^{5}$ )
cruciform arrangement about element $A_{22}$ in matrix $A_{i j}$
cruciform arrangement about element $A_{33}$ in matrix $A_{i j}$
$\frac{2(\sigma-\rho)}{2 \sigma+\rho}$ (Appendix B only)
diameter of spherical body (balloon)
m-th element in lower arm of cruciform arrangement $\mathrm{C}_{\text {ii }}$
function of ()
$\left\langle B\left(k, \omega ; X_{30}\right) B^{*}\left(k, \omega ; X_{30}\right)\right\rangle$
i-th component of force based on Basset term
i-th component of drag force
i-th component of gravitational force
i-th component of pressure force (dynamic buoyancy)
gravitational acceleration
nonlinear contribution to the drag term (Appendix $M$ only)
quasi-Lagrangian time autocorrelation function for stationary turbulence

## LIST OF SYMBOLS

(Continued)

| Symbol | Definition |
| :---: | :---: |
| $\hat{\mathbf{i}}$ | the longitudinal component ( $x_{1}$-direction) of the unit vector |
| k | - wave number in stationary coordinate system |
| K | spatial wave number in transformed coordinate system |
| $\ell$ | length |
| $L_{\text {iim }}$ | m-th element in left arm of cruciform arrangement $C_{i i}$ |
| $L_{1}$ | first dimensionless group, $\frac{\rho}{2 \sigma+\rho}$ |
| $L_{2}$ | second dimensionless group, $\frac{\sigma}{2 \sigma+\rho}$ |
| $\mathrm{L}_{3}$ | third dimensionless group, $\frac{12 v}{A D}$ |
| $\mathrm{L}_{4}$ | fourth dimensionless group, $\frac{1}{2} C_{D l}$ |
| $L_{5}$ | fifth dimensionless group, $\frac{2}{3} \mathrm{~g} \frac{(\mathrm{~g} / \mathrm{R}-\gamma) \mathrm{D}^{2}}{\mathrm{~A}^{2} \mathrm{~T}_{\mathrm{O}}}$ |

## LIST OF SYMBOLS

## (Continued)

| Symbol | $\therefore \quad \cdots \quad$ Definition |
| :---: | :---: |
| $L_{6}$ | sixth dimensionless group, |
|  | $6 \sqrt{v /(A D \pi)}$ |
| m | mass of spherical body (balloon) |
| $\mathrm{m}_{\mathrm{a}}$ | apparent mass of the displaced fluid |
| M | mass |
| $\mathrm{N}^{2}$ | linear component of buoyancy term (Appendix M only) |
| p | pressure in the flow field |
| R | specific gas constant |
| $\mathrm{R}_{\text {i } \mathrm{im}}$ | m-th element in right arm of cruciform arrangement $C_{i i}$ |
| Re | the Reynolds number for flow past the balloon |
| t | elapsed time |
| T | atmospheric temperature |
| $\mathbf{u}_{\mathbf{i}}$ | wind velocity component in $\mathbf{x}_{i}$-direction |
| $\mathrm{U}_{\mathrm{ijm}}$ | $m-t h$ element in upper arm of cruciform arrangement $C_{i i}$ |
| $\mathbf{v}_{\mathbf{i}}$ | velocity component of spherical body (balloon) in $x_{i}$-direction |
| v | volume of spherical body (balloon) |
| $\mathbf{x}_{1}$ | component of Cartesian coordinate system |
| $\mathrm{x}_{3}$ | vertical position relative to equilibrium altitude, $X_{30}$ |

(Continued)

| Symbol | Definition |
| :---: | :---: |
| $\mathrm{x}_{30}$ | equilibrium altitude at which $\sigma=\rho_{0}$ |
| $\mathrm{X}_{\mathbf{i}}$ | balloon coordinate |
|  | Greek Symbols |
| $\alpha$ | linear drag term used in firstorder theoretical analysis (Appendix $M$ only) |
| $\beta$ | latitudinal derivative of Coriolis force, appearing in phase velocity relation for Rossby wave (Appendices H, I and J only) |
| B | ratio of Eulerian frequency to quasi-Lagrangian frequency |
| $\gamma$ | constant temperature lapse rate |
| $\gamma_{p}$ | lapse rate of air parcel |
| $\Gamma_{s}$ | adiabatic lapse rate |
| $\Gamma_{\rho}$ | constant density lapse rate |
| $\delta()$ | Dirac delta function |
| $\delta_{i j}$ | Kronecker delta function |
| 5 | $\mathrm{k}\left(\mathrm{x}_{1}+\mathrm{x}_{2}+\mathrm{x}_{3}\right)$ |
| $\theta_{i}$ | phase angle for i-th component of fluid velocity |
| $\lambda$ | frequency for case \#2 in linear analysis (Appendix $M$ only) |
|  | . xiii |

## LIST OF SYMBOLS

## (Continued)



Definition
micro-scale of turbulence dynamic viscosity
kinematic viscosity
dimensionless group
density of ambient fluid
density of spherical body
(balloon)
variance
period of oscillation according
to first-order theory
time relative to some elapsed
time $t$ (Appendix $H$ only)
$2 \pi / N$ (Appendix $M$ only)
$2 \pi / \alpha$ (Appendix $M$ only)
general Eulerian space-time
power spectrum

Eulerian space-time power spectrum at equilibrium altitude $x_{30}$

Eulerian space power spectrum at equilibrium altitude $\mathbf{x}_{30}$

Lagrangian two-dimensional spacetime spectrum
quasi-Lagrangian time power spectrum at equilibrium altitude $x_{30}$

Eulerian frequency of the wind
(Continued)

| Symbol | Definition |
| :---: | :---: |
| $\Omega$ | transformed frequency in coordi system moving with the mean wind |
| $\Omega_{L}^{\prime}$ | quasi-Lagrangian frequency of t balloon |
|  | Superscripts |
| $\sim$ | dimensionless |
| * | conjugate |
| - | mean value |
| $\rightarrow$ | vector |
| , | quasi |
| ' | ```fluctuating quantity (Appendix H only)``` |
| $\wedge$ | unit vector |
|  | Subscripts |
| a | apparent .. |
| B.V. | Brunt-Vaisala |
| C.VB | constant-volume balloons |
| (DISPERSIVE) | characteristic of a dispersive medium |
| E | Eulerian |
| (GRAVITY) | gravity waves |
| i | i-th component |
| J | j-th component |

## LIST OF SYMBOLS

## (Concluded)

| Symbol | Definition |
| :---: | :---: |
| L | Lagrangian |
| $\bigcirc$ | equilibrium altitude |
| (ROSSBY) | Rossby waves |
| (TAYLOR) | according to Taylor's hypothesis |
| 1 | longitudinal direction in horizontal plane (normally alligned with mean wind direction) |
| 2 | transverse direction in horizontal plane |
| 3 | vertical direction |
|  | eous Symbols |
| < > | ensemble average |
| $\Rightarrow$ | implies |

The use of constant-volume balloons (CVB) has proven a popular method of measuring atmospheric phenomena, Certain questions, regarding the proper application of such balloons and the proper interpretation of resulting data, have arisen. Thus a need has developed for determining the true capabilities of the CVB for aeronautical research. This study described in this report was designed to satisfy this need.

The initial phase of the study involved a literature survey concerned with CVB. A description of this survey is contained in Section 2.

Examination of the literature revealed the need for a more rigorous mathematical treatment of the dynamics of CVB in a fluctuating flow field. Accordingly a mathematical model was developed which describes the response of the CVB to threedimensional periodic non-homogeneous flow. A description of this model is provided in Section 3.

The mathematical model previously noted was incorporated into a digital computer program. Section 4 provides a.description of this program, which is called BALLOON.

By means of BALLOON, over 84 numerical runs were conducted with the NASA/MSFC UNIVAC 1108. These runs produced both digital and graphical results as discussed in Section 5. Because of the considerable bulk involved, most of the computer plots are not included. They are available in a separate document. [1].

Analysis of the numerical results obtained, combined with a study of the work of other investigations has resulted in certain observations and conclusions. Section 6 contains such observations and conclusions. Because of limitations in the scope of the investigation these conclusions are not considered to be completely general with regard to CVB behavior.

At the same time they do provide some insight into the nature of the problem of properly interpreting data collected by CVB's.

References cited and included in Section 7. In
addition there are 16 appendices containing supplementary , material. Of special significance is a first-order perturbation analysis contained in Appendix $H$.

The survey of literature consisted of three separate activities. The first involved an inspection of existing balloon literature from the files of the NASA Contracting Officer's Representative, Dr. George H. Fichtl, representing approximately 600 papers and reports. Such an inspection revealed 60 pertinent documents. The second activity involved utilization of the computerized information retrieval system at Redstone Scientific Information Center. The third activity consisted of a personal review of journals pertaining to meteorology and atmospheric physics back to 1969. Because Dr. Fichtl's files appeared to adequately cover all earlier years, the personal review did not proceed back to any earlier journals. The journals review included:

```
Journal of Meteorology
Journal of the Atmospheric Sciences
Journal of Applied Meteorology
Quarterly Journal of the Royal Meterological Society
Journal of Geophysical Research
Beiträge zür Physik der freien Atmosphüre
Journal of Japanese Meteorology Society
```

In the process of reviewing the literature some distinction had to be made between different types of balloons. Clearly not all literature concerning balloons is pertinent to the study. At the same time it was recognized that there exist a number of types of balloons which are closely related or nearly equivalent to CVB's. These include tetroons, constant-altitude balloons, constant level balloons, transondes, horizontalsounding balloons and certain types of super-pressure balloons. A description of each of these types is provided in Appendix A. The decision was made to include in the survey literature pertaining to all of these types of balloons so long as the application of the balloon was consistent with the general application of CVB's.

The results of the survey revealed four categories of articles or reports. The first category is concerned with the general theory, design, and operation of constant-volume balloons as discussed in subsection 2.1 . The second category, which is described in subsection 2.2 , is concerned with the use of constant-volume balloons to determine the mean wind velocity. The third category, which is of primary interest in the current study, is similar to the second except that, in addition to the mean wind velocity, some measurement of turbulent fluctuations is recorded. This category is presented in subsection 2.3. Within the third category of literature, it is appropriate to recognize two subcategories labeled $3-A$ and $3-B$. In subcategory 3-A, the measurements of turbulent phenomena are presented in their simplest form, involving variation with respect to spatial position or time. In $3-B$ such data may be present, but in addition, some spectral analysis or correlation of such data is provided. Clearly subcategory 3-B is of special interest in the current investigation. The fourth category which is presented in subsection 2.4, pertains to theoretical studies of the motion of constant-volume balloons and related objects immersed in a turbulent flow field, and also to the theory of atmospheric turbulence.

### 2.1 Category 1 Literature - General Theory, Design and Operation of Constant-Volume Balloons

For the current investigation, Iiterature describing the general characteristics of constant-volume balloons (CVB) was not of primary importance. At the same time such literature was of some value in providing background material and in developing an understanding of the various uses to which the balloons have been put. More than seventy papers, reports, and articles [2-75] were identified in this category. Some of these also contained information pertinent to other categories as discussed in other subsections. For the sake of brevity the discussion of Category 1 literature which follows will be limited to material of special significance.

The first CVB investigation was reported over sixtyfive years ago by Ley [2] and concerned the use of "balanced pilot balloons." The objectives of the study were to obtain a better picture of:
"(a) Periodic oscillations of stratum as apart from variations due to altitude.
(b) Vertical currents or rising winds.
(c) Local eddies or other phenomena."

These objectives correspond quite closely to those of more recent studies. Ley in a separate article [3] also reported on an automatic valve for maintaining such pilot balloons at a constant altitude.

The first apparent use of CVB's in conjunction with radio transmitters was reported by Akerman and Piccard [4] shortly prior to World War II. During the fifteen years,following the war a number of articles appeared describing various methods of improving balloon performance [5-17]. The initial works of Lally [14,16] and Angell [15] are included in this group as are some of the works of Hopper [ 7,13,17] and Laby [13, 17].

During the ten-year period from 1961 through 1970, more than 40 category 1 articles were written [18-61]. One of the most useful of these was a summary of the state-of-the-art in 1961 written by Angell [18]. The introduction of Mylar as a material for the balloon skin was probably the most significant development in CVB operations in this period. Both the Ghost balloon experiment [ $26,27,29,30,31,36,39,43,50,53,57,58]$ and the EOLE experiment $[28,34,35,38,44,54,57]$ began operations during this period.

Category 1 literature during the period 1971 - 1975 consisted of thirteen articles [62-74]. Several of these were concerned with the EOLE experiment [62,66-68]. One of the most significant articles was concerned with tetrocri drag coefficients over a range of Reynolds number from $10^{4}$ to $6 \times 10^{5}$ [71]. Typical drag coefficient values were .73.

The literature survey uncovered 68 articles, reports, and papers dealing with the use of CVB's to measure the horizontal mean wind velocity. Of these, 23 also contained category 1 material, including the initial work of Ley, and have already been noted $[2,12,15,17,18,20,21,26,29,34,43,44,48,53,55,57-59$, $63,68,69,72,74]$. The remaining 42 papers [75-117] cover a twenty-five year span (1950-1974) and describe various programs in which CVB's were utilized to track the mean horizontal wind. One of these papers [80] was not actually so much concerned with measuring the mean wind as with utilizing such a wind to send "balloon bombs" from Japan to the United States during World War II. A number of investigations involved flights over urban areas $[82-84,92,101,105,109,114]$ while others dealt with the GHOST program [87,89-91,94-96,100,117] and still others with the EOLE experiment [ $98,99,102,111,112,116,117]$. Balloon trajectories at various altitudes were analyzed including 500mb [85], 200mb [116], 50 mb [86], and 50 km [108]. Clustering phenomena were studied in some cases [ 85,97 ] while the relationship between the dispersing of CVB's and turbulent diffusion in the atmosphere was investigated in others [102,104,115]. A number of studies were concerned with balloon trajectories in the planetary boundary layer $[97,103,109,110]$. Still others were directed toward measurements of rain clouds and thunderstorms [93, 113].

In essentially all the studies noted the basic assumption was made that the mean motion of the balloon corresponded to the mean motion of the atmosphere.

### 2.3 Category 3 Literature - The Use of CVB's to Measure

Category 3 literature can be divided into two groups, as noted previously. All literature which contained some measurement of turbulent fluctuations, either vertical or
horizontal, was considered Sub-Category 3-A if it did not provide for some form of spectral analysis or correlation of the fluctuations. Sub-Category $3-B$ consisted of all iiterature which contained both measurement of fluctuations and spectral analysis or correlation of the data.

### 2.3.1 $\frac{\text { Sub-Category 3-A Literature }}{\text { Correlation }}$ Without Spectral Analysis of

Twenty-two different studies provided basic measurements of turbulent fluctuations $[2,18,20,25,74,75,83,92,108,110,111$, 112,115,118-126]. The majority of these studies were concerned with vertical fluctuation $[2,18,20,25,74,83,92,108,110,115$, 120,122-126]. The data were generally presented in the form of a plot of altitude, temperature or pressure versus time. The period of oscillation were generally relatively short, being measured in minutes.

Ten studies provided measurement of horizontal fluctuations [75,110-112,118-121,124,125]. As with vertical fluctuation the data were generally presented in the form of a plot of displacement versus time. Two separate groups could be identified. The first of these was concerned with large-scale fluctuation with periods of oscillation measured in hours or even days $[111,112]$ while the second group dealt with small-scale fluctuations with periods of oscillation measured in minutes [110, 118-121].

Sub-Category 3-A literature contains a wealth of information but time and manpower limitations precluded any attempt to carry out any detailed analysis of the measured data.
2.3.2 $\frac{\text { Sub-Category 3-B Literature }}{\text { Correlation }}$ With Spectral Analysis or

The most significant group of literature bearing on the current study consisted of twenty-one articles which provide both turbulence measurements and spectral analysis or correlations of measured data $[68,72,78,84,127-143]$. It was appropriate
to identify two groups within Sub-Category 3-B. In the first of these, the authors generally provided turbulence measurements, based on tracking the CVB, and some analysis of the resulting data $[68,72,78,84,127,129,130,135,136,138-141,143]$. These types of analyses produced Lagrangian or quasi-Lagrangian representations of turbulence. It is important to note that a wide range of frequencies and wave numbers were covered in these studies. A number of the studies were primarily concerned with low frequency oscillations (. 001 to 0.1 cycles/hr) of the horizontal winds $[68,130,139,140,143]$. The remaining dealt with intermediate to high frequency oscillations (0.1 to 100 cycles/hour) of the vertical winds $[72,78,84,127,129,135,136$, 138]. In several of these cases the natural frequency of oscillation was detected [72,84,129,136]. One study utilizing neutrally buoyant floats for measuring vertical velocity fluctuations in the ocean (in the spectral range from $10^{-2}$ to 1 cycle/hour), also detected the natural frequency of oscillation [141].

The seven remaining Sub-Category $3-B$ papers [128,131-134, 137,142] were especially pertinent to the current investigation because in addition to turbulence measurements and analysis based on the motion of CVB's they also provide corresponding data and analysis based on measurements taken at a stationary point. Thus both Lagrangian (or quasi-Lagrangian) and Eulerian descriptions of turbulence were available for comparison.

The first of these studies is especially noteworthy because of its completeness. Gifford [128] calculated the vertical velocity energy spectra over the range from 3 to 200 cycles/hour at a height of 300 feet based on measurement, by fixed anemometers, CVB's and gust equipment mounted aboard an airplane. He demonstrated that in terms of the frequency, (corresponding to the spectral maxima), the data could be correlated by the relation

$$
\begin{equation*}
\omega=\Omega_{\mathrm{L}}^{\prime}+\mathrm{k} \overline{\mathrm{u}}_{1} \tag{2-1}
\end{equation*}
$$

where
$\omega=$ Eulerian frequency (measured by the fixed anemometer)
$\Omega_{L}^{\prime}=$ (quasi) Lagrangian frequency (measured by the CVB)
$k$ = wave number (measured by the airplane)
$\bar{u}_{1}=$ mean wind velocity
Angell and Pack [131], in a study of low-level CVB flights from Wallops Island, obtained measurements of vertical, longitudinal, and transverse fluctuations. Based on such measurements they calculated values of transverse velocity variance and transverse turbulence intensity at altitudes from 2500 3000 feet. They provided a comparison of such values with Eulerian values (obtained at heights from 6 to 300 feet) and with other Lagrangian values (obtained at altitudes from 1000 to 3000 feet). In general the values of Lagrangian variance and intensity obtained by Angell and Pack were less than the corresponding Eulerian values and were also less than the other Lagrangian values. Because the mean wind velocities were not provided and because of differences in height at which the various measurements were obtained, it is difficult to draw quantitative conclusions from these comparisons.

Angell [132] in another study carried out an analysis of the trajectories of CVB's launched from Cardington at altitudes ranging from 1200 to 4200 feet. Based on measurement of vertical fluctuations, vertical velocity spectra were derived extending from . 01 to 1.0 cycles/minute. The spectral peaks of these quasi-Lagrangian spectra were then compared with corresponding peaks from Eulerian spectra, derived from measurements by wind vanes attached to a barrage-balloon cable at heights ranging from 600 to 3500 feet. The ratio, $B$, of the frequency for the Eulerian spectral peak to the frequency for the Lagrangian spectral peak was computed and tabulated. Values of $\beta$ ranged from 1.1 to 8.5. An approximate correlation of $\beta$ with turbulence intensity was developed.

Kao and Bullock [133] performed a comparison of Lagrangian and Eulerian correlations and energy spectra of geostrophic velocities. The frequency range for the spectra extended from . 001 to .07 cycles/hour. The curves for the Eulerian auto correlation coefficients of both horizontal velocity components resembled their Lagrangian counterparts but displayed larger integral time scales. The Eulerian velocity spectra also resembled the Lagrangian but were shifted toward lower frequency. The value of $\beta$ based on the ratio of the integral time scale was 0.53 .

In a separate paper Kao [134] computed and analyzed the Eulerian and Lagrangian autocorrelations and energy spectra of large-scale turbulent motion at the 300 mb level. The results were similar to those presented in the preceding study. The frequency range was the same and the same resemblance of the Eulerian autocorrelation curves and spectra to their Lagrangian counterparts was again observed. The value of $\beta$ was found to be 0.33. It is important to note that the Lagrangian values were based on data collected by Angell [15] from CVB flights from Japan to the United States while the Eulerian values were based on data collected by Kao over Salt Lake City. The mean wind speeds were not equal in the two experiments.

Angell, Pack, Hoecker, and Delver [137] performed a comparison of Lagrangian and Eulerian time-scales based on CVB flights past a 460 meter tower in Nevada equipped with a bidirection wind vane. The range of frequencies extended from $\sim .0003$ to . 01 cycles/ sec. Based on the frequencies corresponding to the spectral peaks, values of $\beta$ from 1.5 to 4.7 were obtained. A limited correlation of $\beta$ as a function of turbulence intensity was developed.

In a closely related study, Angell [142] calculated the Lagrangian and Eulerian time scales based on CVB flights past a 460-meter television tower near Oklahoma City. The time scales were based on the spectral peaks of composite Lagrangian and Eulerian spectra with a frequency range from . 0001 to 1.0
cycles/second. Values of $\beta$ ranged from 2.4 to 13 . Angell suggested that the presence of an urban area might reduce the Lagrangian time scale, thus causing larger values of $\beta$. Correlation of $B$ with turbulence intensity was demonstrated to a limited degree.
2.4 Category 4 Literature - Theoretical Studies of CVB's

Many of articles, papers, and reports already described also provided some theoretical treatment regarding the behavior of CVB's $[2,20,22,46,58,65,72,72,97-99,102,103,119,122,124$, 126,127,136]. Some of these dealt with predicting the expansion of the balloon due to pressure differences and predicting the equilibrium altitude $[58,65,72]$. Others dealt with predicting the natural frequency of vertical oscillation for the CVB and/or an air parcel $[20,58,72,127,136]$. Still others were concerned ' with the response of the CVB to oscillations in the flow field $[22,46,97,126]$. Two papers dealt with the numerical simulation of the dispersion of CVB [98,99], while two others were concerned with relating balloon dispersion to atmospheric diffusion [102,119]. The behavior of CVB's in the vicinity of mountains was the subject of two other studies [122,124].

Much of the remaining Category 4 literature was concerned with the behavior of a body immersed in a fluid [144-167]. One of the earliest treatments of this problem was that by Bassett [144], who took into account transient viscous effects. For the case of low Reynolds numbers, corresponding to small particles, a sizeable number of studies have been performed [145-154]. These studies generally involved particle densities which were much greater than the fluid density and thus differed significantly from the CVB problem. The rigor with which the governing equations were derived, however, proved useful in establishing the governing equations for CVB motion. Two other papers $[155,156]$ dealt with the behavior of bubbles in
fluids, when the density of the bubble is much less than the density of the fluid. The basic question of the natural vertical oscillation in a stratfied fluid has been addressed in a number of studies $[20,58,72,127,136]$ as previously noted. In addition to these, the original work of Brunt [157], for vertical oscillations of an air parcel in the atmosphere, and the work of Larsen [158], for a neutrally buoyant sphere oscillating in a stratified fluid, are worthy of note.

Clearly the most relevant studies involving immersed bodies were those dealing with balloon motion [159-167]. Two papers [161,163] were especially pertinent. The paper by Hirsch and Booker [161] dealt with the response of superpressure balloons to vertical air motions. In developing the governing equation for the balloon response, however, the authors apparently neglected apparent mass and pressure gradient effects as well as the Bassett terms. In addition the equations describing the motions of the air and the balloon, as presented in the paper, appear erroneous. For these reasons the resulting balloon trajectories are of questionable value.

The paper by Hanna and Hoecker [163] was concerned with the response of constant-density balloons to sinusoidal variations of vertical wind speeds. The equation governing the balloon motion was derived with more rigor than noted above, but several important assumptions and/or simplifications were made which were not clearly stated. First, the follow-the-fluidparticle total derivative was assumed identical to the follow-the-balloon total derivative. Second the Bassett term was neglected. The first assumption is valid because the authors considered only a periodic velocity field, which was spatially homogeneous. The second simplification appears acceptable for large Reynolds numbers. The authors presented dimensionless plots for calculating phase lag and amplitude response as a function of the properties of the atmosphere and the balloon.

It is important to note that the authors did not predict any frequency, shift of the balloon motion with respect to the air motion.

In addition to literature dealing with the behavior of immersed bodies, certain other Category 4 literature was identified. This included certain studies dealing with CVB trajectories [168-170]. Also, a number of important references dealing with atmospheric turbulence [171-180]. Especially useful in this regard were the works of Lumley and Panofsky [175] and Slade [176].

In order to gain a better understanding of the behavior of a constant-volume balloon immersed in a flow field, a mathematical model has been developed based on the appropriate governing equations. The equations describing the balloon motion and the fluid velocity field are presented in subsection 3.1. These equations are presented in both dimensional and dimensionless form. By means of dimensional analysis, as described in subsection 3.2 certain important dimensionless groups can be identified, which are useful in presenting results with more general application.

As an alternative method of treating the problem, a first-order perturbation analysis of a perfectly responding CVB has been performed as discussed in subsection 3.3.
3.1 Governing Equations for Balloon Motion

The governing equations for the motion of a balloon submerged in a turbulent flow field consist of the equations for the conservation of momentum of the balloon coupled with the equations for conservation of momentum of the fluid.

### 3.1.1 Conservation of Momentum Equations for the Balloon

The conservation of momentum equations were originally derived for small Reynolds numbers (>0.1) as discussed in Appendix B. Based on the derivation provided in that appendix, but without the assumption of low Reynolds numbers, the conservation of momentum equations for a balloon can be written as
$m \frac{d v_{i}}{d t}+m_{a} \frac{d\left(v_{i}-u_{i}\right)}{d t}=\frac{1}{2} \rho\left(u_{i}-v_{i}\right)|\vec{u}-\vec{v}| C_{D} \frac{\pi D^{2}}{4}-\frac{m}{\sigma} \frac{\partial p}{\partial x_{i}}$

$$
\begin{equation*}
+m g \delta_{i 3}-\frac{3}{2} \quad \rho D^{2} v \frac{\pi \nu}{\pi} \int_{0}^{t} \frac{d\left(v_{i}-u_{i}\right)}{\sqrt{t t^{\prime}}} d t^{\prime} \tag{3-1}
\end{equation*}
$$

If viscous stresses in the fluid are neglected,

$$
\begin{equation*}
\frac{\partial p}{\partial x_{i}}=\rho g \delta_{i 3}-\rho \frac{D u_{i}}{D t} \tag{3-2}
\end{equation*}
$$

A combination of Equations (3-1) and (3-2) yields
$m \frac{d v_{i}}{d t}+m_{a} \frac{d\left(v_{i}-u_{i}\right)}{d t}$

$$
\begin{align*}
= & \frac{1}{2} \rho\left(u_{i}-v_{i}\right)|\vec{u}-\vec{v}| C_{D} \frac{\pi D^{2}}{4}-\frac{m}{\sigma}\left(\rho g \delta_{i 3}-\rho \frac{D u_{i}}{D t}\right) \\
& +m g \delta_{i 3}-\frac{3}{2} \rho D^{2} \sqrt{\pi v} \int_{0}^{t} \frac{d\left(v_{i}-u_{i}\right)}{\frac{d t^{\prime}}{t-t^{\prime}}} d t^{\prime} \tag{3-3}
\end{align*}
$$

Rearrangement yields

$$
\begin{align*}
\left(m+m_{a}\right) & \frac{d v_{i}}{d t} \\
= & \frac{1}{2} \rho\left(u_{i}-v_{i}\right)|\vec{u}-\vec{v}| c_{D} \frac{\pi D^{2}}{4}+\left(m_{a}+\frac{m \rho}{\sigma}\right) \frac{D u_{i}}{D t} \\
& +m_{a}\left(v_{j}-u_{j}\right) \frac{\partial u_{i}}{\partial x_{j}}-(1-\rho / \sigma) m g \delta_{i 3} \\
& -\frac{3}{2} \rho D^{2} \sqrt{\pi v} \int_{0}^{t} \frac{d\left(v_{i}-u_{i}\right)}{\frac{d t^{\prime}}{}} d t^{\prime} \tag{3-4}
\end{align*}
$$

Division by $\frac{V \sigma A^{2}}{D}$ yields

$$
\begin{align*}
& =\frac{1}{2} \frac{\rho}{\sigma}\left(\frac{u_{i}}{A}-\frac{\dot{v}_{i}}{A}\right)\left|\frac{\vec{u}}{A}-\frac{\vec{v}}{A}\right| \frac{C_{D} \pi D^{3}}{4 \bar{V}} \\
& \\
& +\left(\frac{m_{a}}{\sigma V}+\frac{m \rho}{\sigma^{2} v}\right) \frac{D\left(u_{i} / A\right)}{D(A t / D)}+\frac{m_{a}}{\sigma \bar{V}}\left(\frac{v_{j}}{A}-\frac{u_{j}}{A}\right) \frac{\partial\left(u_{i} / A\right)}{\partial\left(x_{j} / D\right)} \\
&  \tag{3-5}\\
& -(1-\rho / \sigma) \frac{m}{\sigma V} \frac{g D}{A^{2}} \delta_{i 3} \\
& -\frac{3}{2} \frac{\rho}{\sigma} \frac{D^{3}}{V} \sqrt{\frac{\pi V}{A D}} \int_{0}^{A t / D} \frac{d\left(v_{i} / A-u_{i} / A\right)}{\frac{d(A L / D)}{\sqrt{A t / D-A t^{\prime} / D}}} d\left(A t^{\prime} / D\right)
\end{align*}
$$

The following relations hold:

$$
\begin{align*}
& m=\sigma V  \tag{3-6}\\
& m_{a}=\frac{1}{2} \rho V \tag{3-7}
\end{align*}
$$

and

$$
\begin{equation*}
v=\frac{1}{6} \pi D^{3} \tag{3-8}
\end{equation*}
$$

With these identities Equation (3-5) can be written

$$
\begin{aligned}
\left(1+\frac{\tilde{\rho}}{2}\right) \frac{d \tilde{v}_{i}}{d t}= & \frac{3}{4}\left(\tilde{u}_{i}-\tilde{v}_{i}\right)|\overrightarrow{\tilde{u}}-\overrightarrow{\tilde{v}}| C_{D} \tilde{\rho}+\left(\frac{\tilde{\rho}}{2}+\tilde{\rho}\right) \frac{D \tilde{u}_{i}}{D \tilde{t}}+\frac{\tilde{\rho}^{2}}{2}\left(\tilde{v}_{j}-\tilde{u}_{j}\right) \frac{\partial \tilde{u}_{i}}{\partial \tilde{x}_{j}} \\
& -(1-\tilde{\rho}) \tilde{\mathrm{g}} \delta_{i 3}-9 \tilde{\rho} \sqrt{\frac{\tilde{v}}{\pi}} \int_{0}^{\tilde{t}} \frac{d\left(\tilde{v}_{i}-\tilde{u}_{i}\right)}{\frac{d \tilde{t}^{\prime}}{\sqrt{t-\tilde{t}^{\prime}}}} d \tilde{t}
\end{aligned}
$$

where

$$
\begin{align*}
& \tilde{\rho}=\rho / \sigma  \tag{3-10}\\
& \tilde{v}_{i}=v_{i} / A  \tag{3-11}\\
& \tilde{u}_{i}=u_{i} / A  \tag{3-12}\\
& \tilde{t}=A t / D  \tag{3-13}\\
& \tilde{x}_{j}=x_{j} / D  \tag{3-14}\\
& \tilde{g}=g D / A 2  \tag{3-15}\\
& \tilde{v}=v /(A D) \tag{3-16}
\end{align*}
$$

Division by $\left(\frac{2+\tilde{\rho}}{2}\right)$ yields

$$
\begin{align*}
\frac{d \tilde{v}_{i}}{d t}= & \frac{3}{4}\left(\frac{2 \tilde{\rho}}{2+\tilde{\rho}}\right) C_{D}\left(\tilde{u}_{i}-\tilde{v}_{i}\right)|\overrightarrow{\tilde{u}}-\overrightarrow{\tilde{v}}|+\frac{3}{2}\left(\frac{2 \tilde{\rho}}{2+\tilde{\rho}}\right) \frac{D \tilde{u}_{i}}{D \tilde{t}} \\
& +\frac{1}{2} \cdot\left(\frac{2 \tilde{\rho}}{2+\tilde{\rho}}\right)\left(\tilde{v}_{j}-\tilde{u}_{j}\right) \frac{\partial \tilde{u}_{i}}{\partial x_{j}}-\frac{2(1-\tilde{\rho})}{2+\tilde{\rho}} \tilde{g} \delta_{i 3} \\
& -\frac{18 \tilde{\rho}}{(2+\tilde{\rho})} \sqrt{\frac{\tilde{v}}{\pi}} \int_{0}^{\tilde{t}} \frac{d\left(\tilde{v}_{i}-\tilde{u}_{i}\right)}{\frac{d \tilde{t}^{\prime}}{\sqrt{\tilde{t}-\tilde{t}^{\prime}}}} d \tilde{t} \tag{3-17}
\end{align*}
$$

Now the drag coefficient $C_{D}$ can be approximated by the relation

$$
\begin{equation*}
C_{D}=\frac{24}{R e}+C_{D l} \quad\left(\operatorname{Rc}<1 n^{i)}\right) \tag{3-18}
\end{equation*}
$$

where

$$
\begin{equation*}
C_{D \ell} \simeq .5 \tag{3-19}
\end{equation*}
$$

$$
\begin{align*}
\operatorname{Re}_{\mathrm{e}} & =\frac{|\overrightarrow{\mathbf{u}}-\overrightarrow{\mathbf{v}}| \mathrm{D}}{v} \\
& =\frac{|\overrightarrow{\tilde{u}}-\overrightarrow{\tilde{v}}|}{\tilde{v}} \tag{3-20}
\end{align*}
$$

A combination of Equations (3-17), (3-18) and (3-20) yields

$$
\begin{align*}
& \frac{d \tilde{v}_{i}}{d \tilde{t}}=\frac{3}{2}\left(\frac{\tilde{\rho}}{2+\tilde{\rho}}\right) \frac{24 \tilde{v}}{|\overrightarrow{\tilde{u}}-\overrightarrow{\tilde{v}}|}\left(\tilde{u}_{i}-\tilde{v}_{i}\right)|\overrightarrow{\tilde{u}}-\overrightarrow{\tilde{v}}| \\
& +\frac{3}{2}\left(\frac{\tilde{\rho}}{2+\tilde{\rho}}\right) C_{D \ell} \quad\left(\tilde{u}_{i}-\tilde{v}_{i}\right)|\overrightarrow{\mathrm{u}}-\overrightarrow{\mathrm{v}}|+3\left(\frac{\tilde{\rho}}{2+\tilde{\rho}}\right) \frac{D \tilde{u}_{i}}{\tilde{D t}} \\
& +\left(\frac{\tilde{\rho}}{2+\tilde{\rho}}\right)\left(\tilde{v}_{j}-\tilde{u}_{j}\right) \frac{\partial \tilde{u}_{i}}{\partial \tilde{x}_{j}}-\frac{2(1-\tilde{\rho})}{2+\tilde{\rho}} \tilde{g} \delta_{i 3} \\
& -18\left(\frac{\tilde{\rho}}{2+\tilde{\rho}}\right) \sqrt{\frac{\tilde{\mathrm{v}}}{\pi}} \int_{0}^{\tilde{t}} \frac{d\left(\tilde{v}_{i}-\tilde{\mathrm{u}}_{i}\right)}{\frac{d \tilde{t}^{\prime}}{\sqrt{\tilde{t}-\tilde{t}}}} \mathrm{~d} \tilde{t}^{\prime} \\
& =36\left(\frac{\tilde{\rho}}{2+\tilde{\rho}}\right) \tilde{v} \quad\left(\tilde{u}_{i}-\tilde{v}_{i}\right)+\frac{3}{2}\left(\frac{\tilde{\rho}}{2+\tilde{\rho}}\right) C_{D \ell} \quad\left(\tilde{u}_{i}-\tilde{v}_{i}\right)|\vec{u}-\vec{v}| \\
& +3\left(\frac{\tilde{\rho}}{2+\tilde{\rho}}\right) \frac{D \tilde{u}_{i}}{D \tilde{t}}+\left(\frac{\tilde{\rho}}{2+\tilde{\rho}}\right)\left(\tilde{v}_{j}-\tilde{u}_{j}\right) \frac{\partial \tilde{u}_{j}}{\partial \tilde{x}_{j}}-\frac{2(1-\tilde{\rho})}{2+\tilde{\rho}} \tilde{g} . \delta_{i 3} \\
& -18\left(\frac{\tilde{\rho}}{2+\tilde{\rho}}\right) \sqrt{\frac{\tilde{v}}{\pi}} \int_{0}^{\tilde{t}} \frac{\frac{d\left(\tilde{v}_{i}-\tilde{u}_{i}\right)}{d \tilde{t}} \tilde{t}^{\prime}}{\sqrt{\tilde{t}-\tilde{t}^{\prime}}} \tag{3-21}
\end{align*}
$$

Further development of the dimensionless form of the equation is provided in Appendix $C$.

The equations governing the motion of fluid are commonly referred to as the Navier-Stokes equations. Although numerical solutions of these equations are possible, such a procedure is beyond the scope of the current study. Accordingly a simple mathematical model was developed representing a periodic threedimensional flow field which conserves mass, as described in Appendix D. The final dimensional form of the model is:

$$
\begin{equation*}
u_{i}=\bar{u}_{i} \delta_{i 1}+A \sin \left(\zeta-\omega t+\theta_{i}\right) \tag{3-22}
\end{equation*}
$$

where

$$
\left.\begin{array}{l}
\zeta=k\left(x_{1}+x_{2}+x_{3}\right) \\
\theta_{1}=0 \\
\theta_{2}=2 \pi / 3  \tag{3-24}\\
\theta_{3}=-2 \pi / 3
\end{array}\right\}
$$

It is important to note that the flow field model is three-dimensional and does contain a mean translational velocity.* To increase the generality of the model it can be cast in dimensionless form as described in Appendix $E$. In such form the model can be written:

$$
\begin{equation*}
\tilde{u}_{i}=\tilde{\bar{u}}_{1} \delta_{i 1}+\sin \left(\zeta-\tilde{\omega} \tilde{t}+\theta_{i}\right) \tag{3-25}
\end{equation*}
$$

where

$$
\begin{align*}
& \tilde{u}_{i}=u_{i} / A  \tag{3-26}\\
& \tilde{u}_{1}=\bar{u}_{1} / A \tag{3-27}
\end{align*}
$$

[^0]\[

$$
\begin{align*}
& \zeta=\tilde{k}\left(\tilde{x}_{1}+\tilde{x}_{2}+\tilde{x}_{3}\right)  \tag{3-28}\\
& \tilde{k}=\mathbf{k} D  \tag{3-29}\\
& \tilde{\mathbf{x}}_{\mathbf{i}}=x / D  \tag{3-30}\\
& \tilde{\omega}=\omega D / A  \tag{3-31}\\
& \tilde{t}=A t / D \tag{3-32}
\end{align*}
$$
\]

### 3.2 Dimensional Analysis

Inspection of Equation (3-21) reveals certain dimensionless groups. As shown in Appendix $C$ these groups can be written as:

$$
\begin{align*}
& L_{1}=\frac{\rho}{2 \sigma+\rho}  \tag{3-33}\\
& L_{2}=\frac{\sigma}{2 \sigma+\rho}  \tag{3-34}\\
& L_{3}=\frac{12 \nu}{A D}  \tag{3-35}\\
& L_{4}=\frac{1}{2} C_{D \ell}  \tag{3-36}\\
& L_{5}=\frac{2}{3} g \frac{(g / R-\gamma) D^{2}}{A^{2} T_{O}}  \tag{3-37}\\
& L_{6}=6 \sqrt{\nu /(A D \pi} \tag{3-38}
\end{align*}
$$

A comparison of Equations (3-35) and (3-38) reveals

$$
\begin{equation*}
L_{6}=\sqrt{3 L_{3} / \pi} \tag{3-39}
\end{equation*}
$$

For a CVB the balloon density is essentially equal to the atmospheric density. Thus,

$$
L_{1} \approx 1 / 3
$$

and

$$
\begin{equation*}
L_{2} \approx .1 / 3 \tag{3-41}
\end{equation*}
$$

For simplicity the balloon is assumed to have a spherical shape. For this case

$$
\begin{equation*}
C_{D \ell} \approx 1 / 2 \tag{3-42}
\end{equation*}
$$

and

$$
\begin{equation*}
\mathrm{L}_{4} \approx 1 / 4 \tag{3-43}
\end{equation*}
$$

Thus the six dimensionless groups are reduced to two: $L_{3}$ and $L_{5}$. Furthermore, the dimensionless group, $L_{3}$, can be approximated as:

$$
\begin{equation*}
L_{3} \approx \frac{12 \nu_{0}}{A D} \tag{3-44}
\end{equation*}
$$

where $\nu_{0}=k i n e m a t i c$ viscosity at the equilibrium altitude. This parameter is clearly the reciprocal of a type of Reynolds number as shown in Appendix $F$. It is important to note that the two dimensionless groups, $12 \nu_{0} /(A D)$ and $\frac{2}{3} g(g / R-\gamma) D^{2} /\left(A^{2} T_{o}\right)$ are essentially constant for any given balloon problem and appear sufficient (to first-order accuracy) for characterizing the balloon motion. At the same time, the six original dimensionless groups are not truly constants and the numerical solution of Equations (3-21) described in Section 4, has allowed for the actual variation of these groups to achieve higher-order accuracy.

Examination of Equation (3-25) indicates that the
flow field model contains five dimensionless parameters: $\tilde{\bar{u}}_{1}$, $\tilde{K}, \tilde{\mathbf{x}}_{\mathfrak{i}}, \tilde{\omega}$, and $\mathfrak{Z}$. Two of these, $\tilde{\mathbf{x}}_{i}$ and $\mathfrak{Z}$, represent the balloon coordinates in space and time as obtained from the solution to the equation governing the balloon motion, and thus these two parameters

The true significance of Equation (3-45) can best be understood in terms of certain examples as presented in Appendix H. The example based on Taylor's Hypothesis is especially noteworthy. For this case the relation between the two spectra becomes

$$
\begin{equation*}
\psi_{\mathrm{L}(\mathrm{TAYLOR})}\left(\Omega, \mathbf{x}_{30}\right)=\delta(\Omega) \int_{-\infty}^{\infty} \phi_{\mathrm{E}(\mathrm{TAYLOR})}\left(\mathrm{K} ; \mathbf{x}_{30}\right) \mathrm{dK} \tag{3-48}
\end{equation*}
$$

According to Equation. (3-48) the quasi-Lagrangian power spectrum is simply a spike at $\Omega=0$, and is thus independent of the shape of the Eulerian space-time power spectrum. It therefore appears according to the first-order perturbation analysis, that the quasi-Lagrangian power spectrum, obtained from observing the balloon motion, could not be used to describe the Eulerian spectrum, if Taylor's Hypothesis holds.

The equations presented in Section 2 were incorporated into a digital computer program entitled "BALLOON". Essentially, the program utilizes a fourth-order Runge-Kutta technique to integrate the differential equations governing the balloon motion. The program consists of a driver routine (MAIN); 9 subroutines (GEOMET, INTEG, ACCEL, PROPTY, BUOYNT, APARNT, DRAG, BASSET, and POTFLU); and 2 functions (DVAL and MREF). The basic orginization of BALLOON is indicated in Figure 4-1.

A copy of the source program is contained in Appendix K. A description of each subroutine or function is contained in Table 4-1. In subsection 4.1 an explanation of all input parameters is provided including the input format. A description of the output is contained in subsection 4.2.

### 4.1 Inputs

All inputs to the program are read in through MAIN. These inputs can be divided into two segments or blocks. To facilitate explaining the sequence and format for each input item, the actual FORTRAN statements (both READ and FORMAT) associated with the inputs are provided as part of the discussiol which follows.

### 4.1.1 Block \#1 Inputs

The first set of inputs consists of data setting up certain initial parameters. The form of the input is as follows:

READ (5,7002) NNN
READ (5, 7001) BCDX, BCDY1, BCDY2 , BCDY3, FLDY1, FLDY2 , FLDY3
READ (5,100) G,X,K,THETA,UB,V
READ (5,100) A, (MEGA,SIGMA,D, MUREF,TEMREF,T,TLIM, DELTAT ,
*TEMPO , PO, TEMLAP , R , X30
100 FЯRMAT (8E10,3)
7001 FФRMAT (12A6,8X)
7002 FดRMAT (12)


Figure 4-1. Organization of Balloon Program

Summary of Subroutines and Functions in BALLOON

| Name | Purpose | Called by | Calls Up |
| :--- | :--- | :--- | :--- |
| ACCEL | Calculates acceleration of <br> balloon | INTEG | APPRNT <br> BASSET <br> BUOYNT |
| APPRNT |  | Calculates forces due to <br> apparent mass and pressure <br> gradients in the fluid | ACCEL |

Table 4-2 provides a definition of each input item. Notice should be taken than the table is arranged in the same order as the items are read.
4.1.2 Block \#2 Inputs

The second set of data occur in the following form: READ (5,101) $\mathrm{XD}(2), \mathrm{XD}(5), \operatorname{BCDX}(11), \mathrm{BCDX}(12), \mathrm{T}, \mathrm{TLIM}, \mathrm{DELTAT}, I D T, I D S$ 101 FØRMAT (2E10.3,10X,2A6,8X,3F5.0,2I5)

The data in Block \#2 are somewhat redundant of Block \#1 data. This redundancy results from certain modifications to the program to permit dimensionless results and to provide for multiple cases to be run in sequence. The meaning of each Block \#2 input is provided in Table 4-3. As before, the items in the table are listed in the same order as they are read into the program. One set of these inputs must be provided for each case to be run in sequence.

### 4.2 Outputs

All outputs to the program occur in MAIN. These outputs can be divided into 4 blocks. As with the description of inputs, to aid in explaining the sequence and format of each output item, the actual FORTRAN statements (both WRITE and FORMAT), associated with the outputs are provided as part of the discussion which follows.

### 4.2.1 Block \#1 Outputs

The first output set occurs in the following form:
WRITE(6,9004) A,B,C
9004 FФRMAT(///10X,1P3E12.4)
The variables $A, B, C$, refer to the amplitudes of the $u_{1}, u_{2}$ and $u_{3}$ velocity components. The variable $A$ is read in, but $B$ and $C$ are computed. Sample values of this output is included in Appendix $L$.

## Definitions of Block \#1 Inputs

## Variable

NNN
BCDX BCDY1

BCDY2

BCDY3

FLDY1

FLDY2

FLDY3

G
X
K
THETA

UB
V
A
OMEGA
SIGMA
D
MUREF
TEMREF
T
TLIM
DELTAT
TEMPO
PO
TEMLAP
R
X30

## Meaning

The number of different cases to be run in sequence alphanumeric label for abscissa of all plots alphanumeric label for ordinate of first plot (normally $x_{i}$-component of velocity)
alphanumeric label for ordinate of second plot (normally $\mathrm{x}_{2}$-component of velocity)
alphanumeric label for ordinate of third plot (normally $x_{3}$-component of velocity)
alphanumeric label for ordinate of fourth plot (normally $x_{1}$-coordinate of balloon)
alphanumeric label for ordinate of fifth plot (normally $\mathrm{x}_{2}$-coordinate of balloon)
alphanumeric label for ordinate of sixth plot (normally $x_{3}$-coordinate of balloon)
gravitational acceleration vector
position vector for initial position
wave number vector for the fluid
phase angles for the components of the fluid velocity model
initial fluid velocity vector
initial balloon velocity vector
fluid wave amplitude for $\mathrm{x}_{1}$ direction
Eulerian frequency for the fluid balloon density balloon diameter reference dynamic viscosity coefficient reference temperature initial time of balloon fluid final time of balloon flight time step for numerical integration temperature at altitude $x_{30}$ pressure at altitude $x_{30}$ temperature lapse rate gas constant
initial balloon altitude

Table 4-3
Definitions of Block \#2 Inputs

Variable
$\mathrm{XD}(2)$
$X D(5)$
$\operatorname{BCDX}(11)$ BCDX(12)

T
TLIM
DELTAT
IDT

IDS

## Meaning

dimensionless wave number, $\tilde{k}$
dimensionless frequency, $\tilde{\omega}$
alphanumeric label to permit identifying each run by a "test" caption
initial time of balloon flight
final time of balloon flight
time step for numerical integration
number of integration time steps between output data generations
factor for increasing TLIM (final time = IDS*TLIM)

## Block \#2 Outputs

The second set of output provides a label for each case and provides a list of most inputs in the following form:

WRITE (6.0915) $\operatorname{BCDX}(11), \operatorname{BCDX}(12),(X D(L 2), \mathrm{L} 2=1.5)$
WRITE (6, INPUT)

: 12.4/' N8='E12.4/ ' N9='E12.4/' N10='E12.4/' N11='E12.4)
NAMELIST/IMPUT/G, X, K, THETA UB, V, A, ØMEGA, SIGMA , D , MUREF , TEMREF,T, *TLIM, DELTAT, TEMPO, PO, TEMLAP, R, X3O

The definition of all of these items are provided in Tables 4.2 and 4.3. A sample set of this output is included in Appendix. L.

### 4.2.3 Block \#3 Outputs

The form of this output is as follows:
WRITE (6,9002)
WRITE(6, 9003) ((WRA (I, J) , J=1, 11), $\mathrm{I}=1,50)$
WRITE $(6,9008)$
WRITE (6, 9009) ((WRB(I, J), J=1, 6), $\mathrm{I}=1,50$ )
WRITE $(6,9006)$
WRITE (6, 9007) ( (WRC(I, J), J=1, 17, I=1,50)
9002 FORMAT (' 1 TIME SCALED TIME SCALED ATM
1SCALED BALLดดN VELดCITIES
9003 FФRMAT(1X,OPF8.2,1P10E11.3)
9008 FЯRMAT ('1 TIME SCALED TIME X $\quad \mathrm{Y} \quad$ DZ 1' / / )
9009 FФRMAT(1X.OPF8.2,1PS5E11.3)
9006 FøRMAT('1 TIME SCALED TIME FDRAG/FBUØY
1 FAP1/FBASS FAP2'//)
9007 FЯRMAT(1X,OPF8.2,1P10E11.3/20X,1P6E11.3)
Basic data describing the computed wind and balloon motion are stored in the fields WRA, WRB, and WRC. The WRA field provides a tabulation of wind and balloon velocity as a function of time. The WRB field contains the balloon coordinates and the Reynolds number as a function of time. The WRC field contains a tabulation of the various forces acting on the balloon as a function of time. Sample values of block \#3 data are included in Appendix L.

### 4.2.4 Block \#4 Outputs

This output set consists of calls to the NASA/MSFC
UNIVAC 1108 plotting routines as follows:
$Y B=8.8$
$\mathrm{YT}=11.2$
CALL QUIK3L ( $-1, \mathrm{XL}, \mathrm{XR}, \mathrm{YB}, \mathrm{YT}, 1 \mathrm{H}+, \mathrm{BCDX}, \mathrm{BCDY} 1,-\mathrm{IDX}, \mathrm{PT}, \mathrm{PY} 1$ )
CALL QUIK3L(C,XL, XR,YB,YT, IHO, BCDX, BCDY1, -IDX, PT, PZ1).
$Y B=-1.5$
$Y T=1.5$
CALL QUIK3L( $-1, \mathrm{XL}, \mathrm{XR}, \mathrm{YB}, \mathrm{YT}, 1 \mathrm{H}+$, BCDX, BCDY2,-IDX, PT , PY2 )
CALL QUIK3L(0,XL,XR,YB,YT,1HO,BCDX, BCDY2,-IDX,PT,PZ2)
CALL QUIK3L( $-1, \mathrm{XL}, \mathrm{XR}, \mathrm{YB}, \mathrm{YT}, 1 \mathrm{H}+, \mathrm{BCDX}, \mathrm{BCDY} 3,-\mathrm{IDX}, \mathrm{PT}, \mathrm{PY} 3$ )
CALL QUIK3L(0,XL,XR,YB,YT,1HO,BCDX,BCDY3,-IDX,PT,PZ3)
CALL QUIK3V( $-1,1 H 0, B C D X, F L D Y 2,-I D X, P T, P Y)$
CALL QUIK3V(-1,1H0, BCDX,FLDY3,-IDX,PT,PZ)
The fluid velocity components are stored in the PY1, PY2 and PY3 fields while the balloon velocity components are stored in the PZ1, PZ2, and PZ3 fields. The lateral and vertical coordinates of the balloon position are stored in the PY and PZ fields respectively. The preceding parameters are plotted as a function of time which is stored in the PT field. Examples of the plots generated by this block of output data are found in Section 5.

The computer program, BALLOON, has been used to numerically solve the equations governing the motion of the balloon in a periodic, three-dimensional flow field. The numerical results can be grouped in two categories. The first category contains the results of test runs to validate the numerical model incorporated into the program. This category is presented in subsection 5.1. The second category represents the results of a series of runs, which are designed to provide general insight into the balloon response to the flow field. This category is described in subsection 5.2

Based on these numerical results certain observations concerning the behavior of constant-volume balloons have been made. These observations are presented in subsection 5.3

### 5.1 Test Case Results

Several types of test runs were carried out. The first were designed to provide a means of initially validating the model for certain simple conditions for which first-order theoretical solutions exist. These runs are described in subsection 5.1.1. The second type of test run was designed to verify the generality of the dimensionless form of the numerical solution. The results of these runs are presented in subsection 5.1.2. A number of other test cases were conducted to determine the effect of changing or omitting certain features in the program. The results of these tests are discussed in subsection 5.1.3. 5.1.1 Initial Test Cases

A series of four test cases were carried out which were simple enough to permit comparison with first-order theory. The simplifications employed in these four cases are summarized in Table 5-1. For each of these cases, as discussed in Appendix $M$, the period of oscillation based on first-order theory agreed closely with the results of the numerical solution. One additional test case (\#5) was conducted to ensure that the simplification involving an isothermal atmosphere was not a special case. The period of oscillation for this test run, according to first-order theory, and the period obtained from the numerical solution were nearly identical.

Table 5-1

Summary of Simplifications for Initial Test Runs
Simplifications

| Test Run \# | Drag <br> Force | Apparent $\qquad$ | $\begin{array}{r} \text { Bassett } \\ \text { Force } \\ \hline \end{array}$ | Fluid Acceleration Force | Atmosphere |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | zero | zero | zero | zero | isothermal |
| 2 | linear | zero | zero | zero | isothermal |
| 3 | zero | $\frac{1}{2}$ balloon mass | zero | zero | isothermal |
| 4 | zero | zero | linear | zero | isothermal |
| 5 | zero | zero | zero | zero | nonisothermal |

In order to verify the dimensionless formulation of the governing equations and the resulting dimensionless solution, two test cases (\#6 and \#7) were conducted with the program BALLOON. The dimensional input values for the two cases are presented in Table 5-2. While the dimensional inputs are clearly different for the two cases, the values of the five dimensionless parameters developed in Section 3.3 are the same for both'cases. Values of the dimensionless groups are presented in Table 5-3.

In terms of dimensionless time, space, and velocity the differences in the numerical solutions for the two cases were less than $1 \%$. The dimensionless plots of the vertical components of the balloon and wind velocities versus time for these cases are presented in Figure $\mathrm{N}-1$ of Appendix N . . Thus the validity of the dimensionless formulation was confirmed.

### 5.1.3 Other Test Cases

Because of the fact that evaluation of the Bassett term represents $90 \%$ of the computation time in BALLOON, a test run (test case \#8) was conducted, in which the Bassett term was set to zero with the same inputs as given for test case \#6. The results are presented in Figure $N-2$ of Appendix N. As indicated in the figure, the absence of the Bassett term caused an $11 \%$ reduction in the period of the balloon motion. Although such a reduction is considered significant, the general shape of the plots of both balloon and wind vertical velocity components closely resemble those shown in Figure N-1. Furthermore, the Reynolds number associated with this test case was 2480 which is considerably above the Stokes flow regime in which the Bassett term is rigorously applicable. For these reasons, computation of the Bassett term was omitted in subsequent runs unless the Reynolds number was $\sim 1$.

Dimensional Input Values for Test Cases \#6 and \#7

| Variable | Case \#6 | Case \#7 | Units |
| :---: | :---: | :---: | :---: |
| To | 218 | 300 | ${ }^{\circ} \mathrm{K}$ |
| R | $2.870224 \times 10^{6}$ | $2.870224 \times 10^{6}$ | $\mathrm{cm}^{2} / \mathrm{sec}^{2} \mathrm{O}_{\mathrm{K}}$ |
| $\gamma$ | $0 . \because$ | 0 | ${ }^{0} \mathrm{~K} / \mathrm{cm}$ |
| g | 980.6 | 980.6 | $\mathrm{cm} / \mathrm{sec}^{2}$ |
| $\mu_{0}$ | $1.40646 \times 10^{-4}$ | $1.84540 \times 10^{-4}$ | $\mathrm{g} / \mathrm{cm} \mathrm{sec}$ |
| $\omega$ | $3.20036 \times 10^{-2}$ | $2.72746 \times 10^{-2}$ | rad/sec |
| A | 15.44 | 19.15 | cm/sec |
| D | 12.0616 | 17.5562 | cm |
| k | $2.072693 \times 10^{-3}$ | $1.42399 \times 10^{-3}$ | $\mathrm{cm}^{-1}$ |
| $\bar{u}_{1}$ | $\therefore 45.7555$ | 56.75966 | cm/sec |
| $\sigma$ | $3.61494 \times 10^{-4}$ | $2.626856 \times 10^{-4}$ | $\mathrm{gm} / \mathrm{cm}^{3}$ |
| $\rho_{0}$ | $3.61494 \times 10^{-4}$ | $2.626856 \times 10^{-4}$ | $\mathrm{gm} / \mathrm{cm}^{3}$ |

## Values of Dimensionless Parameters for <br> Test Cases \#6 and \#7

Variable Definition Value
$\mathrm{L}_{3}$

| $\frac{12 \nu_{0}}{A D}$ | $2.5 \times 10^{-2}$ |
| :---: | :---: |
| $\frac{2}{3} \frac{\mathrm{~g}(\mathrm{~g} / \mathrm{R}-\gamma) \mathrm{D}^{2}}{\mathrm{~A}^{2} \mathrm{~T}_{\mathrm{O}}}$ | $6.25 \times 10^{-4}$ |

$\tilde{\bar{u}}_{1}$
$\bar{u}_{1} / A$
2.96
$\stackrel{\ddot{2}}{\mathrm{k}}$
kD
$2.5 \times 10^{-2}$
$\widetilde{\omega}$
$\frac{\omega D}{A}$
$2.5 \times 10^{-2}$

In the setup of test cases \#6 and \#7, the initial balloon velocity was set equal to the mean wind velocity and, in the flow field model, the phase angle $\theta_{1}$ was set to 0 , with $\theta_{2}$ set to $2 \pi / 3$, and $\theta_{3}$ set to $-2 \pi / 3$. In examining the results obtained, the question arose as to whether or not a change in the value of the phase angle would have a significant effect on performance of the balloon. This question is equivalent to the question of the influence of the initial phase relation between balloon and wind velocity on the periodic solution.

To resolve this issue, three additional test cases (\#9, 10, and 11) were conducted with phase angles as indicated in Table 5-4. All other input variables in test cases \#9, 10 and 11 were the same as case $\# 6$. The results obtained are presented in Figures $N-3$ through $N-5$ of Appendix N. Examination of these figures reveals that for each different phase angle immediately following time zero there is a different transient buildup for the balloon motion. Subsequent to the transient buildup, a periodic pattern occurs. Comparison of Figures $N-1, N-3, N-4$, and $N-5$ indicated that the periodic motion of the balloon relative to the wind, following the transient buildup, is essentially independent of the phase angle.
5.2 Results of Numerical Experiments

Based on the results of test cases \#1 - \#11, the computer program BALLOON was considered acceptable for conducting a series of numerical experiments. To provide maximum results with a minimum number of computer runs the entire experiment was set up in dimensionless form. The experiment was carried out in two phases as described in subsections 5.2.1 and 5.2.2 which follow.

### 5.2.1 Phase I Numerical Experiments

Considerable effort was devoted to devising a series of dimensionless runs involving variation of the primary dimensionless groups discussed in Section 3.2. With five independent parameters a complete investigation would entail a

## Table 5-4

Phase Angles Used in Test Cases \#6 - \#11

| Test Case \# | ${ }_{1}{ }_{1}$ | $\frac{{ }_{2}}{}$ | $-{ }_{3}$ |
| :---: | :---: | :---: | :---: |
| 6 | 0 | $2 \pi / 3$ | $-2 \pi / 3$ |
| 7 | 0 | $2 \pi / 3$ | $-2 \pi / 3$ |
| 8 | 0 | $2 \pi / 3$ | $-2 \pi / 3$ |
| 9 | $\pi / 2$ | $\pi / 2^{+2 \pi / 3}$ | $\pi / 2^{-2 \pi / 3}$ |
| 10 | $\pi$ | $\pi+2 \pi / 3$ | $\pi-2 \pi / 3$ |
| 11 | $3 \pi / 2$ | $3 \pi / 2^{+2 \pi / 3}$ | $3 \pi / 2^{-2 \pi / 3}$ |

very large number of runs. Accordingly in Phase $I$ the decision was made to hold the variables $L_{3}, L_{5}$ and $\bar{u}_{1}$ constant with the values given in Table $5-5$ while systematically varying $\tilde{k}$ and $\tilde{\omega}$ over the ranges indicated in the same table. The individual runs were visualized as elements in a matrix, as shown in Figure 5-1. The values of $\tilde{k}$ and $\tilde{\omega}$ for each run were assigned according to the position of the element in the matrix. The matrix was designed such that along the main diagonal

$$
\tilde{\omega}=\tilde{\mathrm{k}} \tilde{\bar{u}}_{1}
$$

which satisfies Taylor's Hypothesis.
The dimensionless form of the input variables correspond to a large number of different physical situations. In this form, however, it is difficult to visualize the type of physical situation represented. Actually in Phase I the dimensionless parameters were computed from "typical" dimensional values of the physical parameters. The dimensional values used are presented in Table 5-6. It is important to note that in certain portions of the report dimensional results are presented in lieu of dimensionless values. In these cases the corresponding dimensional inputs are those presented in Table 5-6.

### 5.2.1.1 Phase I - Original 16 Runs

For the sixteen runs shown in Figure 5-1 a quantitative analysis of the numerical results is presented in Appendix 0. A qualitative view of the results of these experiments is provided by means of Figures 5-2 through 5-6. These figures depict the transverse and vertical position of the balloon and the velocities in all three directions as functions of time for each test. case within the matrix. In each figure, the sixteen plots are arranged in order of test case number so as to correspond to the elements in the test case matrix. Note that the scales differ from plot to plot within these figures. The scales were selected to provide a maximum of 10 complete oscillations of the forcing function. Also note that the equilibrium point is represented by a darkened line and that the balloon velocity may exceed the upper or lower limits of the graphs over certain intervals. In such situations portions of

Values of Dimensionless Parameters for Phase I

| Parameter | Definition | Value |
| :---: | :---: | :---: |
| $L_{3}$ | $\frac{12 v_{0}}{A D}$ | $3.5914 \times 10^{-4}$ |
| $L_{5}$. | $\frac{2}{3} \frac{g\left(g / R-\gamma D^{2}\right.}{A^{2} T_{O}}$ | $1.7317 \times 10^{-3}$ |
| $\tilde{\bar{u}}_{1}$ | $\overline{\mathrm{u}}_{1} / \mathrm{A}$ | 10 |
| $\tilde{\mathbf{k}}$ | kD | $8.168 \times 10^{-4}$ to $8.168 \times 10^{-1}$ |
| $\tilde{\omega}$ | $\frac{\omega D}{A}$ | $8.168 \times 10^{-3}$ to 8.168 |


|  |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- |
|  | $8.168 \times 10^{-4}$ | $8.168 \times 10^{-3}$ | $8.168 \times 10^{-2}$ | $8.168 \times 10^{-1}$ |
|  | $A_{11}$ | $A_{12}$ | $A_{13}$ | $A_{14}$ |
|  | $A_{21}$ | $A_{22}$ | $A^{A_{23}}$ | $A^{A_{24}}$ |
|  | $A_{31}$ | $A_{32}$ | $A_{33}$ | $A_{34}$ |
|  | $A_{41}$ | $A_{42}$ | $A_{43}$ | $A_{44}$ |

Figure 5-1. Basic Matrix $A_{i j}$ for Cases in Phase I

## Typical Dimensional Values for Phase I

Physical
Parameter
To $218^{\circ} \mathrm{K}$
R
$2.870224 \times 10^{6} \mathrm{~cm}^{2} / \mathrm{sec}^{2} \mathrm{o}_{\mathrm{K}}$
$0.0^{\circ} \mathrm{K} / \mathrm{cm}$
g
$980.6 \mathrm{~cm} / \mathrm{sec}$
$\mu_{o}$

A
$1.40646 \times 10^{-4} \mathrm{~g} / \mathrm{cm} \mathrm{sec}$

D
$100.0 \mathrm{~cm} / \mathrm{sec}$
130.0 cm
$\bar{u}_{1}$
$1000.0 \mathrm{~cm} / \mathrm{sec}$
$\sigma$
$3.61494 \times 10^{-4} \mathrm{~g} / \mathrm{cm}^{3}$
$\rho_{0}$
$3.61494 \times 10^{-4} \mathrm{~g} / \mathrm{cm}^{3}$
k
$6.28 \times 10^{-6}$ to $6.28 \times 10^{-3} \mathrm{~cm}^{-1} *$
$6.28 \times 10^{-3}$ to $6.28 \times 10^{-1} \mathrm{sec}^{-1} *$
*Such ranges of $k$ and $\omega$ correspond to spatial wave lengths from 10 m to 10 km and time periods of 1 sec to 1000 sec .

time

Figure 5-2. $\quad x_{2}$-Coordinates of Balloon Position


Figure 5-3. $\mathbf{x}_{3}$-Coordinates of Balloon Position


Figure 5-4. $\quad \mathrm{x}_{1}$-Component of Velocity (Balloon and Wind


Figure 5-5. $\mathrm{x}_{2}$-Component of Velocity (Balloon and Wind
Phase I)


Figure 5-6. $\mathrm{x}_{3}$-Component of Velocity (Balloon and Wind
Phase I)
velocity plots are "chopped off". Examination of Figures 5-2 through 5-6 reveals that all runs, which are off of the main diagonal, display a periodic motion which is in good agreement with first-order theory. As shown in Appendix O, the period of oscillation according to first-order theory is given by

$$
\begin{equation*}
\tilde{\tau}=\frac{2 \pi}{\tilde{k}\left|\tilde{\bar{u}}_{1}-\tilde{c}\right|} \tag{5-1}
\end{equation*}
$$

where

$$
\begin{equation*}
\tilde{c}=\frac{\tilde{\omega}}{\tilde{k}} \tag{5-2}
\end{equation*}
$$

Along the main diagonal where Taylor's Hypothesis is satisfied, no long-term periodic motion is observed. The balloon experiences one or two oscillations after which the velocity components appear to reach steady-state values. It is important to note, however, that under such steady-state conditions the balloon drifts laterally (perpendicular to the mean wind direction) and generally remains below its equilibrium altitude.

### 5.2.1.2 Phase I-Intermediate Runs in Cruciform Arrangement

The marked difference between on-diagonal and offdiagonal runs suggested the need for runs at intermediate values of wave number and frequency in the vicinity of the main diagonal. Accordingly two sets of runs in cruciform arrangements, $\mathrm{C}_{22}$ and $\mathrm{C}_{33}$, about elements $\mathrm{A}_{22}$ and $\mathrm{A}_{33}$, as shown in Figure 5-7, were carried out. A quantitative description of the results of these runs is presented in Appendix P. The basic trend observed in both sets of runs was one of increasing disagreement between first-order theory and observation, as conditions satisfying Taylor's hypothesis were approached along any branch of either cruciform. This trend indicates that nonlinear effects become significant under conditions which (nearly) satisfy Taylor's Hypothesis. It was also observed that the bounds of the region in which such nonlinear effects occurred were related to the magnitude of the product of the dimensionless period of oscillation, as computed by Equation (5-1) according to first-order theory, and the dimensionless wave number.


Figure 5-7. $\begin{aligned} & \text { Relative Position of Runs in } \\ & \text { Cruciform Arrangements } C_{22}\end{aligned}$ and $C_{33}$

### 5.2.1.3 Phase I-Special Runs Concerning Lateral Drift

In all cases of balloon motion studied during Phase I, a lateral( $x_{2}$-direction) drift was noted. That is, the balloon appeared to be subject to a mean lateral velocity. This drift was observed for the 16 cases comprising the original experiment matrix as shown in Figure 5-2. An example of this drift is shown in Figures 5-8 and 5-9. Figure 5-8 represents a case off the principal diagonal of the experiment matrix and shows the superposition of the oscillation due to the fluid oscillations and mean drift. Figure 5-9 represents a case on the principal diagonal and shows an initial or transient displacement of the balloon (a feature found in many of the cases examined both on and off the principal diagonal) followed by a final mean drift in the opposite direction.

In examining long periods of balloon motion, it was found that the final direction of the lateral balloon motion depended on which side of the principle diagonal of the experiment matrix the experiment occurred. Thus, the final direction of drift appeared to depend in general on the sign of the quantity ( $\bar{u}-c$ ), where $\bar{u}$ is the mean wind velocity and $c$ is the phase velocity. When $c>\bar{u}$, a positive lateral drift was observed for the flow field under examination and when $c<\bar{u}$, a negative lateral drift was observed. Examination of the flow field model confirmed in general that with such inequalities, the balloon would be subject to lateral forces consistent with the drift observed. However, since a negative lateral final drift was observed when $\bar{u}=c$ (as shown in Figure 5-9), this rule was not considered sufficient and further tests were necessary.

Several runs were prepared to examine the effects of modifications in the flow field on the balloon drift. These cases consisted of (1) varying the initialization of the balloon motion, (2) modifying the initial phase relationships among the velocity perturbations, and (3) setting $\bar{u}=0$. These tests were carried out for the two matrix points, $A_{11}$ and $A_{31}$, as indicated in Figure 5-7.


Figure 5-8. Transverse Balloon Drift ( $\overline{\mathrm{u}}>\mathrm{c}$ )


Figure 5-9. Transverse Balloon Drift ( $\bar{u}=c$ )

For both cases the first two procedures produced results which generally resembled those of the original experiment. Neither altering the initialization by setting

$$
\begin{equation*}
\overrightarrow{\mathrm{v}}=-\overrightarrow{\mathrm{u}} \tag{5-3}
\end{equation*}
$$

rather than

$$
\begin{equation*}
\overrightarrow{\mathbf{v}}=\mathrm{u} \hat{i} \tag{5-4}
\end{equation*}
$$

nor changing the phase angles of the $y$ and $z$ perturbations,

$$
\begin{equation*}
\theta_{2} \longleftrightarrow \theta_{3} \tag{5-5}
\end{equation*}
$$

quantitatively affected the direction of the drift. Setting $\bar{u}=0$ alters the original experiment such that $c>\bar{u}$ at all times. With this point in mind, the results, which showed the balloon drifting off in the positive $x_{2}$-direction, were consistent with the -earlier experiments.

The preceding results indicated that there was no special bias in the model which caused the lateral drift along the main diagonal where Taylor's Hypothesis for the fluid was satisfied. Further study revealed that the mean balloon velocity, $\bar{v}$, (instead of the mean wind velocity, $\bar{u}$, ) was the appropriate variable to be compared with the phase velocity, c. Thus the dividing line for lateral drift corresponds to

$$
\begin{equation*}
\bar{v}=c \tag{5-6}
\end{equation*}
$$

representing Taylor's Hypothesis for a finite parcel. This relationship is satisfied slightly to the left ( $c>\bar{u}$ ) of the principal diagonal of the original matrix. Three test cases were performed to confirm this relationship. The first, designated $T_{1}$, corresponded to $\overline{\mathrm{v}}<c$; the second, $T_{2}$, represented $\overline{\mathrm{v}}=c$; and the third, $T_{3}, \bar{v}>c$. Figures 5-10 through 5-12 illustrate how the lateral velocity $\mathrm{v}_{2}$ asymptotically reaches a constant value in accordance with

$$
\mathbf{v}_{2} \quad \begin{cases}>0 & (\bar{v}<c)  \tag{5-7}\\ =0 & (\bar{v}=c) \\ <0 & (\bar{v}>c)\end{cases}
$$



Figure 5-10. Transverse Balloon Velocity for Case $\mathrm{T}_{1}(\overline{\mathrm{v}}<\mathrm{c})$


Figure 5-11. Transverse Balloon Velocity for Case $T_{2}(\bar{v}=c)$


Figure 5-12. Transverse Balloon Velocity for Case $T_{3}(\bar{v}>c)$

Similarly, Figures $5-13$ through $5-15$ show the lateral drift changing direction.*

Thus the question of lateral drift was resolved and the distinction between Taylor's Hypothesis for the fluid $(\bar{u}=c)$ and Taylor's Hypothesis for the parcel ( $\bar{v}=c$ ) was clearly established.

### 5.2.2 Phase II-Numerical Experiments

As noted in subsection 5.2.1.3 the results of Phase I revealed the distinction between Taylor's Hypothesis for the fluid (THF) and Taylor's Hypothesis for a finite parcel (THP). In addition, there was some indication that nonlinear effects. became significant when the product of the dimensionless wave number and the dimensionless period of oscillation, according to first-order theory, exceeded some limiting value. For these reasons a second experiment matrix $B_{\ell k}$ was designed. The relation between the original matrix $A_{i j}$ and the second matrix is depicted in Figure 5-16. In the matrix $B_{\ell k}$ along each row the product of $\tilde{k} \cdot \tilde{\omega}$ was held constant while along each column the ratio of $\tilde{\omega} / \tilde{k}$ remained constant. The arrangement of the matrix, along with the value of $\tilde{k}$ and $\tilde{\omega}$ for each element is shown in Figure 5-17. The values of all other parameters are the same as for the first matrix.

Also included in the figure is the product of the dimensionless wave number and the dimensionless period of oscillation (according to first-order theory) for each element of the matrix. It is important to note that along each column this product remains constant, with THF being represented by the fourth column. Because the mean balloon velocity is a dependent variable, it is not possible to satisfy THP exactly along any column of the matrix. Based on analysis of the special runs of Phase I, however, the third column was empirically designed to

[^1]

Figure 5-13. Transverse Position of Balloon for Case $\mathrm{T}_{1}$ ( $\mathrm{v}<\mathrm{c}$ )


Figure 5-14. Transverse Position of Balloon for Case $T_{2}(\bar{v}=c)$


Figure 5-15. Transverse Position of Balloon for Case $T_{3}(\bar{v}>c)$.


Figure 5-16. Relation Between Experiment Matrix $A_{i j}$ of Phase $I$ and $B_{k \ell}$ of Phase II


Figure 5-17. Matrix $\mathrm{B}_{\mathrm{k} \mathrm{\ell}}$ for Phase II
approximately satisfy this hypothesis based on the value of the product, $\tilde{\mathrm{T}} \mathrm{k}$.

A complete set of detailed plots from Phase II is provided in a separate document [1]. Qualitative results are given graphically in Figures 5-18, 5-19 and 5-20. The period of observation is the same for each column but none of the other coordinates necessarly coincide. Figure 5-18 presents the vertical velocity of the balloon and the wind at the balloon's position as a function of time. These results are similar to those found in previous cases. The vertical position of the balloon, shown in Figure 5-19, is seen to correspond to the vertical velocities. Away from THP corresponding to column 3, the balloon is seen to oscillate regularly. Close to THP the balloon is seen to reach equilibrium at progressively lower altitudes to the right (along the rows), or toward the bottom (along the columns), of the figure. Along the bottom row, it can be seen that the balloon does not reach equilibrium within the time period shown, although the balloon velocities are approaching zero. Also in the last case shown along the third row the oscillation is not found.

Figure 5-20 shows the lateral position of the balloon as a function of time. The results are very similar to those discussed in subsection 5.2.1. When the phase velocity exceeds the mean balloon velocity ( $c>\overline{\mathrm{v}}$ ), corresponding to column 4 and 5 , the balloon drifts toward the positive $y$-direction. When $c<\bar{v}$ corresponding to column \#1 and \#2, the balloon dirfts toward the negative $y$-direction. It is important to note that along column \#3 Taylor's Hypothesis for the parcel is not exactly satisfied. In row \#1 of column \#3 the balloon drifts toward the positive $y$ direction in near equilibrium, while in subsequent cases the balloon drifts toward the negative y-direction. Thus, the assumption that THP depends only on the product $\tilde{\tau} \tilde{\mathrm{k}}$ is found to be incorrect as it probably also depends on the scale of motion (which may also be responsible for the differences seen in row \#3 of Figures 5-18 and 5-19).


Figure 5-18. Vertical Velocity as a Function of Time (phase II)


Figure 5-19. Vertical Position of Balloon as a Function of Time (Phase II).
$\operatorname{Var}^{N^{211}}$




63










TIME

Figure 5-20. Lateral Position of Balloon as a Function of Time . (Phase II)

### 5.3 General Observations Concerning Balloon Response

Examination of the numerical results from Phases I and II of the numerical experiments revealed a number of significant features of the balloon behavior. First of all, the mean motion of the balloon in the horizontal plane did not in general correspond to mean horizontal. wind. As already noted the balloon exhibited a lateral drift except when Taylor's Hypothesis (for the parcel) (THP) was satisfied. In addition, when the $x_{1}$ - component of the mean wind velocity greatly exceeded the phase velocity ( $\bar{u}_{1} \gg c$ ), the balloon mean $x_{1-}$ velocity component generally was slightly less than the wind velocity component ( $v_{1}<u_{1}$ ) as shown in Figure 5-21. However, as $c$ increased relative to $\bar{u}_{1}, \bar{v}_{1}$ also increased until, as Taylor's Hypothesis (for the fluid) (THF) was approached, $\bar{v}_{1}$ first equaled and then exceeded $\bar{u}_{1}$. Subsequently when THF was satisfied, $\bar{v}_{1}$ exceeded both $\bar{u}_{1}$ and $c$. For a value of $c$ slightly greater ( $\sim 5 \%$ ) than $\bar{u}_{1}$, THP was satisfied with $c$ becoming equal to $\bar{v}_{1}$. Further increases in $c$ resulted in a reduction in $\bar{v}_{1}$ until, for cases where $c$ was very large compared with $\bar{u}_{1}, \bar{v}_{1}$ became essentially equal to $\bar{u}_{1}$.

Comparison of the quasi-Lagrangian frequency of the balloon, $\Omega_{L}^{\prime}$ with the Eulerian frequency of the wind, $\omega$, also proved of interest. The quasi-Lagrangian frequency was less than the Eulerian frequency for all values of $c$ greater than $\bar{u}_{1} / 2$. For smaller values of $c$ the quasi-Lagrangian frequency exceeded the Eulerian frequency. This variation is shown in Figure 5-22. As indicated in the figure the quasi-Lagrangian frequency is zero when THP is satisfied $\left(c=\bar{v}_{1}\right)$. Also the quasi-Lagrangian frequency equals the Eulerian frequency for $c=\bar{u}_{1} / 2$.

As indicated by the figure the numerical results generally agreed with linear theory except in the vicinity of Taylor's Hypothesis where non-linear effects became significant. The relation between the quasi-Lagrangian frequency and the Eulerian frequency was observed to be

$$
\begin{equation*}
\Omega_{L}^{\prime}=|k c c c c| \tag{5-8}
\end{equation*}
$$



Figure 5-21. General Variation of Mean Balloon Velocity wich Phase Velocity Based on Numerical Results
frequency


Figure 5-22. General Variation of Quasi-Lagrangian Frequency with Phase Velocity
where

$$
\begin{equation*}
\omega=|\mathrm{kc}| \tag{5-9}
\end{equation*}
$$

This relation is quite similar to that suggested by Gifford [128] which, as.shown in Section 2.3, was of the form

$$
\begin{equation*}
\omega=\Omega_{L}^{\prime}+k \bar{u}_{1} \tag{2-1}
\end{equation*}
$$

In Gifford's case the Eulerian frequencies were all larger than the Lagrangian frequencies and thus the absence of the absolute value signs was of no significance. With this fact in mind, combined with the observation that

$$
\begin{equation*}
\bar{v}_{1} \approx \bar{u}_{1} \tag{5-10}
\end{equation*}
$$

it can be seen than the two relations are nearly equivalent. Notice should be taken that the first-order perturbation analysis presented in Appendix $H$ also suggested this same type of relation.

Gifford demonstrated [128] that a relation of the form of Equation (2-1) was sufficient to correlate the measured Lagrangian spectral peak frequencies to the corresponding Eulerian spectral peak frequencies. Three investigations by Angell et.al. [132,137,142] also developed and compared Eulerian and quasiLagrangian spectra as discussed in Section 2.3. Unfortunately, in none of these studies were the values of the spatial wave number $k$ determined.* In every case, however, the Lagrangian frequencies were less than the Eulerian and there was a tendency for the ratio, $\beta\left(=\omega / \Omega_{L}^{\prime}\right)$ to increase as the wind velocity increased. These observations are consistent with the form of Equation (5-8).

In two other studies discussed in Section 2.3, Kao et.al. [133,134] also presented Eulerian and Lagrangian spectra for comparison. In these cases, which involved much higher altitudes and lower frequencies than the studies of Gifford and Angell, the Lagrangian peak spectral frequencies were larger than the Eulerian.

[^2]Based on Equation (5-8) and Figure 5-18, it would appear that the phase velocities encountered by Gifford and Angell exceeded $\bar{u}_{1} / 2$, while the phase velocities involved in Kao's investigation were less than this value. This result is generally similar to the observations of Mizuno and Panofsky [180] in the atmospheric surface layer. However, because of the fact that both Gifford's and Angell's data involved measurement of small-scale vertical fluctuations at low altitudes (300-4200 feet) while Kao's data involved measurement of large-scale horizontal fluctuations at higher altitudes ( 18000 to 30000 feet), a certain degree of caution must be exercised before drawing any final conclusions concerning the relative magnitude of phase velocities and mean wind velocities.

Many of the investigations discussed in Section 2.3 involved measurement of the ratio of the Eulerian frequency to the quasi-Lagrangian frequency $\beta$. It is important to note that

$$
\begin{align*}
\beta & \equiv \omega / \Omega_{\mathrm{L}}^{\prime} \\
& =|\mathrm{kc}| / \Omega_{\mathrm{L}}^{\prime} \tag{5-11}
\end{align*}
$$

A combination of Equations (5-8) and (5-11) yields

$$
\begin{align*}
\beta & \left.=\frac{|k c|}{\mid k c-k \bar{v}_{1}} \right\rvert\, \\
& =\left|\frac{c}{c-\bar{v}_{1}}\right| \\
& =\left|1+\frac{\bar{v}_{1}}{c-\bar{v}_{1}}\right| \tag{5-12}
\end{align*}
$$

Except in the immediate vicinity of Taylor's Hypothesis, Equation (5-12) can be approximated as

$$
\begin{equation*}
\beta \approx\left|1+\frac{\bar{u}_{1}}{c-\bar{u}_{1}}\right| \tag{5-13}
\end{equation*}
$$

## 6. CONCLUSIONS AND RECOMMENDATIONS

Clearly the response of a constant-volume balloon to atmospheric turbulence is a complex problem. The current investigation has utilized a more rigorous mathematical model than previously employed, but even so, certain simplifications were made to keep the problem tractable. Representing the flow field as a periodic function, as opposed to a random variable, is of special significance. Some of the responses of the balloon to the periodic function may not occur in the presence of the real random process. Thus, caution must be exercised in reaching general conclusions. At the same time, the numerical results obtained are in general agreement with observations, and a number of points are worthy of note. These matters are presented in subsection 6.1. In the course of the study a number of questions arose for which no answers could be obtained due to time and funding limitations. Certain recommendations aimed at answering such questions are provided in subsection 6.2.

### 6.1 Conclusions

First, the distinction between Taylor's Hypothesis (for the fluid) and Taylor's Hypothesis (for the parcel) is of considerable interest because this distinction sheds light on a number of characteristics of the balloon motion. The balloon does not move with the same mean velocity as the wind and thus when THF is satisfied the balloon does not "lock in" with the wind velocity. When THP is satisfied, however, the balloon does match the mean wind direction (but not its speed). Under such conditions the balloon displays no oscillation or lateral drift.

Except in the vicinity of Taylor's Hypothesis the quasiLagrangian frequençy of the balloon could be related to the Eulerian frequency of the wind by means of a Doppler shift law, in accordance with first-order theory. In the vicinity of Taylor's Hypothesis first-order theory was not sufficient to relate the Lagrangian and Eulerian frequencies. When THP was exactly satisfied, the Lagrangian frequency was, of course, zero.

Based on available measured data, it would appear that constant-volume balloons generally display some oscillatory motion and thus THP is not being satisfied. Because THP is generally close to THF, this suggests that the latter is also not being satisfied.

An examination of the available Eulerian and Lagrangian turbulence spectra obtained from earlier studies indicates that a simple Doppler shift relation such as that suggested by firstorder theory is possibly sufficient for correlation. Unfortunately such an approach requires values of the spatial wave number (based on direct measurement as opposed to calculation based on Taylor's Hypothesis) and these values are not generally available.

Although the balloon did not respond exactly to either the mean wind velocity or the periodic velocity fluctuations, the wind velocity served as a forcing function. The natural oscillatory frequency of the balloon was only observed during the initial phase following the start of a test case.

Casting the problem in dimensionless form and providing a dimensionless numerical solution are also significant. Unfortunately a complete evaluation of the relative importance of the pertinent dimensionless groups was not accomplished and it is not clear whether or not a more "universal" solution can be obtained. 6.2 Recommendations

The most important recommendation would be to replace the current periodic model for the flow field with a random model. The resulting balloon motion could then be subjected to Fourier analysis and realistic Eulerian and Lagrangian spectra could be generated and compared.

Further analysis of the existing numerical data should be made to provide better understanding of the relationship between the various parameters. Such analysis might lead to a more precise relationship between Taylor's Hypothesis (for the fluid) and Taylor's Hypothesis (for the parcel).

The dimensionless groups associated with the dimensionless form of the equation should be varied over a wider range of values to establish their relative importance. A more general solution should be obtained if possible.

Further study should be made of existing Eulerian-Lagrangian turbulence spectra to provide more conclusive proof of the Doppler shift relation between these two types of systems. Methods for calculating the spatial wave number as a function of altitude, without use of Taylor's Hypothesis, should be investigated.

Further investigation should be made into the question of the difference between the mean direction and speed of the balloon motion and that of the wind. Conditions under which such differences are significant in the atmosphere should be defined if possible.

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During the past 65 years a number of different terms have been used to describe that class of balloons which are designed for horizontal flight with a constant volume at essentially a constant altitude. The definitions which follow are designed to aid the reader in understanding the similarities and differences between the types of balloons to which the terms apply. For convenience the definitions are arranged in alphabetical order.

CONSTANT ALTITUDE BALLOON - A helium-filled, zero-pressure balloon made of polyethelene for high altitude research.

CONSTANT DENSITY BALLOON - A pillow-shaped balloon made of Mylar.
CONSTANT-LEVEL BALLOON - A balloon which by means of ballast or superpressure is designed to operate at essentially a constant altitude.

CONSTANT-PRESSURE BALLOON - A balloon of the type used in the transosonde system.

CONSTANT-VOLUME BALLOON - A balloon whose volume remains essentially constant during flight. This condition is usually achieved by inflating the balloon to a pressure which is considerably greater than the ambient air pressure at the equilibrium áltitude.

CONTROLLED ALTITUDE FREE BALLOON - A balloon made of polyethelene with a control device to maintain constant altitude.

HORIZONTAL SOUNDING BALLOON - A superpressure balloon made of Mylax designed for level flight for periods in excess of 60 days.

LEVEL BALLOON - An expansible balloon made of rubber or Neoprene equipped with a valve in the neck to maintain constant levels at high altitudes.

NEUTRAL BALLOON - A balloon with zero lift.
PILOT BALLOON - A balloon made of rubber or Neoprene used for observing winds aloft.

SUPERPRESSURE BALLOON - A balloon made of nonstretchable material (normally Mylar) so that its volume is essentially constant with excess internal pressure.

TETROON - A one-cubic-meter constant-volume balloon of tetrahedronal shape constructed of Mylar.

TRANSOSONDE - A constant-level balloon equipped with meteorological sensing instruments, a radio transmitter, and a power supply.

## APPENDIX B

Equation of Motion for Immersed Bodies

The governing equation for the motion of a body submerged in a turbulent fluid consists of the equation for the conservation of momentum of the body coupled with the equation for conservation of momentum of the fluid. The governing equation has been developed in various forms $141,144-156,161,163,165,166$ with various simplifying assumptions for a number of different applications, but there is not total agreement as to the validity or equivalence of all such forms. The development which follows is relatively general and the result is an equation which is representative of the type encountered in the analysis of the motion of bodies immersed in a turbulent flow.

Consider first the conservation of momentum for a spherical body of density $\sigma$, diameter $D$, and mass $m$, slowly moving (Re<0.1)* with a velocity $v_{i}$ in an otherwise stationary fluid in the presence of a gravitational field, as originally developed by Basset 144 . This equation can be written in the form $m \frac{d v_{i}}{d t}+m_{a} \frac{d v_{i}}{d t}=\left(F_{D}\right)_{i}+\left(F_{p}\right)_{i}+\left(F_{g}\right)_{i}+\left(F_{B}\right)_{i}$
where

$$
\begin{array}{ll}
m_{a}=\frac{1}{2} m \rho / \sigma & \text { (apparent mass) } \\
\left(F_{D}\right)_{i}=-3 \pi D \mu v_{i} & \text { (drag force) } \\
\left(F_{p}\right)_{i}=-m / \sigma \partial p / \partial x_{i} & \text { (pressure force) } \\
\left(F_{g}\right)_{i}=m g_{i} & \text { (gravitational force) } \\
\left(F_{B}\right)_{i}=3 / 2 \rho D^{2} \sqrt{\pi v} \int_{0}^{t} \frac{d v_{i}\left(t^{\prime}\right) / d t^{\prime}}{\sqrt{t-t^{\prime}}} d t^{\prime} \text { (Basset term) }
\end{array}
$$

[^3]Before proceeding further it is important to note that the apparent mass term, $m_{a} \mathrm{dv}_{\mathrm{i}} / \mathrm{dt}$, can be derived from inviscid flow theory and has the same value for both viscous and inviscid flow. The apparent mass term represents the time-rate-of-change of fluid momentum due to inviscid effects. The Basset term is produced by viscous effects and thus can be interpreted as the time-rate-of-change of momentum of the fluid due to viscous effects. Together the apparent mass and Basset terms produce an additional drag on the body which is a function of the time-rate-of-change of the relative velocity of the fluid with respect to the body.

The next step in the development involves considering the case of a body slowly moving in a fluid with non-uniform velocity $u_{i}\left(t, x_{i}\right)$. The non-uniform velocity $u_{i}\left(t, x_{i}\right)$ represents a turbulent flow process with the following assumptions [148].

1. The turbulence is steady and homogeneous.
2. The domain of turbulence is infinite in extent.
3. The body is spherical with a motion relative to the fluid which is characterized by a Reynolds number less than 0.1.*
4. The body is small relative to the smallest turbulence wavelength present.
5. While the body is in motion the fluid immediately surrounding it will be composed of the same fluid particles.
6. The only external force acting on the body is produced by a gravitational field (or other potential field).

The conservation of momentum equation for this case can be written:
$m \frac{d v_{i}}{d t}+m_{a} \frac{d\left(v_{i}-u_{i}\right)}{d t}=\left(F_{D}\right)_{i}+\left(F_{p}\right)_{i}+\left(F_{g}\right)_{i}+\left(F_{B}\right)_{i}$
where

$$
\begin{align*}
& \left(F_{D}\right)_{i}=-3 \pi D \mu\left(v_{i}-u_{i}\right)  \tag{B-8}\\
& \left(F_{p}\right)_{i}=-m / \sigma \partial p / \partial x_{i} \tag{B-9}
\end{align*}
$$

[^4]\[

$$
\begin{equation*}
\left(F_{g}\right)_{i}=m g_{i} \tag{B-10}
\end{equation*}
$$

\]

$\left(F_{B}\right)_{i}=-\frac{3}{2} \rho D^{2} \sqrt{\pi v} \int_{0}^{t} \frac{d\left[v_{i}\left(t^{\prime}\right)-u_{i}\left(t^{\prime}\right)\right] / d t^{\prime}}{\sqrt{t-t^{\prime}}} d t^{\prime}$
Notice should be taken that in apparent mass term, the drag term, and the Basset term the body velocity $v_{i}$ has been replaced by the relative velocity ( $v_{i}-u_{i}$ ), because in each case the resistance is a function of the relative velocity between the body and the fluid.

The next step in the development of the body momentum equation consists of expressing the pressure force term as a function of the fluid velocity. For the case of an incompressible fluid with a velocity $u_{i}(t)$ which is a function of time but is spatially uniform, conservation of fluid momentum can be expressed as
$\rho \frac{D u_{i}}{D t}=-\partial p / \partial x_{i}+\rho g_{i}$
For the case of the non-uniform fluid velocity $u_{i}\left(t, x_{i}\right)$ the instantaneous equation for the conservation of fluid momentum can be written for the incompressible case as:
$\rho \frac{D u_{i}}{D t}=-\partial p / \partial x_{i}+\mu \frac{\partial^{2} u_{i}}{\partial x_{j} \partial x_{j}}+\rho g_{i}$
Notice should be taken that in equation ( $B-13$ ) the instantaneous fluid properties are represented and not the time-averaged. Thus, although the flow may be turbulent, no turbulent or Reynolds stresses appear in the equation for momentum conservation.

In his original development Tchen [145] neglected the viscous stress terms and effectively equat'ed the follow-the-fluid particle derivative, $D u_{i} / D t$, to the follow-the-solid body derivative, $d u_{i} / d t$. Such a process corresponds to the simplifying assumption:
$-\frac{\partial p}{\partial x_{i}} \approx \frac{d u_{i}}{d t}-\rho g_{i}$

Tchen used this relation to replace the pressure force term in equation (B-1). Corrsin and Lumley [146] first noted the inexactness of this approximation while Hinze [148] indicated that such an approach was valid if:

$$
\begin{equation*}
\frac{D^{2}}{v} \frac{\partial u}{\partial x} \ll 1 \tag{B-15}
\end{equation*}
$$

and

$$
\begin{equation*}
\frac{v}{D^{2}\left(\partial^{2} u / \partial x^{2}\right)} \ggg 1 \tag{B-16}
\end{equation*}
$$

Hinze's development of Equations ( $B-15$ ) and ( $B-16$ ) is not altogether rigorous as indicated by the absence of subscripts. More precisely the two conditions are:

$$
\begin{equation*}
\frac{D^{2}}{18 v}\left|\left(u_{k}-v_{k}\right)\left(\frac{\partial u_{i}}{\partial x_{k}}\right) /\left(u_{i}-v_{i}\right)\right| \ll 1 \tag{B-17}
\end{equation*}
$$

and
$\frac{v_{k}\left(\partial u_{i} / \partial x_{k}\right)}{2 / 3 v\left(\partial^{2} u_{i} / \partial x_{j} \partial x_{j}\right)} \gg 1$
If the flow is near isotropic it is reasonable to assume:
$u_{1}-v_{1} \approx u_{2}-v_{2} \approx u_{3}-v_{3}$
$\mathrm{v}_{1} \approx \mathrm{v}_{2} \approx \mathrm{v}_{3}$
$\frac{\partial u_{i}}{\partial x_{1}} \approx \frac{\partial u_{i}}{\partial x_{2}} \approx \frac{\partial u_{i}}{\partial x_{3}}$
and
$\frac{\partial^{2} u_{i}}{\partial x_{1}{ }^{2}} \approx \frac{\partial^{2} u_{i}}{\partial x_{2}{ }^{2}} \approx \frac{\partial^{2} u_{i}}{\partial x_{3}{ }^{2}}$
With these assumptions equations ( $\mathrm{B}-17$ ) and ( $\mathrm{B}-18$ ) reduce to
$\frac{D^{2}}{6 v}\left|\partial u_{i} / \partial x_{j}\right| \ll 1$
and
$\frac{9\left|v_{i}\right|}{} \begin{aligned} & D^{2} \mid \partial^{2} u_{j} / \partial x_{k}^{2}\end{aligned} \gg 1$
Equations ( $B-23$ ) and ( $B-24$ ) are seen to agree with equations ( $B-15$ ) and ( $B-16$ ) except for the subscripts, the numerical constants, and the use of absolute values, all of which Hinze omitted.

Because the spatial derivatives of the fluid velocity represent instantaneous values as opposed to time-averaged values, for the case of homogeneous turbulent flow, the order of magnitude of such derivatives can be expressed in terms of the scale and intensity of the turbulence as follows:

$$
\begin{align*}
& \left|\partial u_{i} / \partial x_{j}\right| \approx \sqrt{{u_{i}^{\prime}}^{2}} / \lambda_{j}  \tag{B-25}\\
& \left|\partial^{2} u_{i} / \partial x_{j}^{2}\right| \approx \sqrt{\overline{u_{i}^{\prime}}} / \lambda_{j}{ }^{2} \tag{B-26}
\end{align*}
$$

where
$\lambda_{j}=$ micro-scale of turbulence.
A combination of equations ( $B-23$ ) and ( $B-25$ ) yields:
$\frac{D^{2}}{6 v} \sqrt{\overline{u_{i}^{\prime}}} / \lambda_{j} \quad \ll 1$
while combining equations ( $B-24$ ) and ( $B-26$ ) produces:
$\frac{9\left|v_{i}\right| \lambda_{j}{ }^{2}}{D^{2} \sqrt{\overline{u_{i}^{\prime 2}}}} \ggg 1$
Now

$$
\begin{equation*}
v_{i} \sim \bar{u}_{i}+\sqrt{\overline{u_{i}^{\prime 2}}} \tag{B-29}
\end{equation*}
$$

Thus equation ( $\mathrm{B}-28$ ) can be reduced to
$\frac{9\left(\bar{u}_{i} / \sqrt{\overline{u_{i}^{2}}}+1\right) \lambda_{j}{ }^{2}}{D^{2}} \ggg 1$
(B-30)

For a turbulent flow field with known values of kinematic viscösity, turbulence intensity, turbulence micro-scale, and mean fluid velocity, equations ( $B-27$ ) and $B-30$ ) provide a means of quantitatively determining the maximum size bodies for which Tchen's approximation of the pressure force is valid.

For spherical bodies which satisfy the preceding restrictions the particle momentum equation can be written

$$
\begin{aligned}
m \frac{d v_{i}}{d t}+m_{a} \frac{d\left(v_{i}-u_{i}\right)}{d t}= & -3 \pi D \mu\left(v_{i}-u_{i}\right)+m \rho / \sigma \frac{d u_{i}}{d t}+m g_{i}-m_{\rho} g_{i} / \sigma \\
& -\frac{3}{2} D^{2} \sqrt{\pi \rho \mu} \int_{0}^{t} \frac{d\left[v_{i}\left(t^{\prime}\right)-u_{i}\left(t^{\prime}\right)\right] / d t^{\prime}}{\sqrt{t-t^{\prime}}} d t^{\prime} \quad \text { (B-31) }
\end{aligned}
$$

Now
$m=\frac{\pi}{6} \quad D^{3}{ }_{\sigma}$
and
$m_{a}=\frac{\pi}{12} D^{3}{ }_{\rho}$
Introduction of the two preceding relations into equation (B-31) produces
$\frac{d v_{i}}{d t}+a v_{i}=a u_{i}+b \frac{d u_{i}}{d t}+c \int_{0}^{t} \frac{d\left[u_{i}\left(t^{\prime}\right)-v_{i}\left(t^{\prime}\right)\right] / d t^{\prime}}{\sqrt{t-t^{\prime}}} d t^{\prime}+d g_{i}$
where
$a=\frac{36 \mu}{(2 \sigma+\rho) D^{2}}$
$b=\frac{3 \rho}{2 \sigma+\rho}$
$c=\frac{18}{(2 \sigma+\rho) D} \sqrt{\frac{\rho \mu}{\pi}}$
$\mathrm{d}=\frac{2(\sigma-\rho)}{2 \sigma+\rho}$
Equation (B-34) is the most familiar form of the immersed body momentum equation. It should be realized, however, that in this form the application of the equation is generally limited by the original assumptions, as well as the restrictions imposed by equations ( $B-27$ ) and ( $B-30$ ).

As developed in Section 3.1.1 the equations for conservation of balloon momentum in dimensionless form can be written

$$
\begin{align*}
& \frac{d \tilde{v}_{i}}{d \tilde{t}}= 36\left(\frac{\tilde{\rho}}{2+\tilde{\rho}}\right) \tilde{v}\left(\tilde{u}_{i}-\tilde{v}_{i}\right)+\frac{3}{2}\left(\frac{\tilde{\rho}}{2+\tilde{\rho}}\right) C_{D l}\left(\tilde{u}_{i}-\tilde{v}_{i}\right)|\overrightarrow{\tilde{u}}-\stackrel{\vec{v}}{\tilde{v}}| \\
&+3\left(\frac{\tilde{\rho}}{2+\tilde{\rho}}\right) \frac{D \tilde{u}_{i}}{D \tilde{t}}+\left(\frac{\tilde{\rho}}{2+\tilde{\rho}}\right)\left(\tilde{v}_{j}-\tilde{u}_{j}\right) \frac{\partial \tilde{u}}{\partial \tilde{x}_{j}}-\frac{2(1-\tilde{\rho})}{2+\tilde{\rho}} \tilde{\mathbf{g}} \delta_{i 3} \\
&-18\left(\frac{\tilde{\rho}}{2+\tilde{\rho}}\right) \sqrt{\frac{\tilde{u}}{\pi}} \int_{0}^{\tilde{t}} \frac{d\left(\tilde{v}_{i}-\tilde{u}_{i}\right)}{d \tilde{t}^{\prime}}  \tag{C-1}\\
& \sqrt{\tilde{t}-\tilde{t}^{\prime}}
\end{align*}
$$

Now the density $\rho$ is not a constant but varies with altitude, $x_{3}$. For an ideal gas
$\rho=\frac{p}{R T}$
For the case of a constant temperature lapse rate, $\gamma$, in a hydrostatic atmosphere,
$p=p_{o}\left(\frac{T}{T_{o}}\right)^{\frac{g}{R \gamma}}$

A combination of Equations (C-2) and (C-3) produces

$$
\begin{align*}
\rho & =\frac{p_{o}}{R T}\left(\frac{T}{T_{o}}\right)^{\frac{g}{R \gamma}} \\
& =\frac{p_{0}}{R_{0}}\left(\frac{T}{T_{0}}\right)^{\frac{g}{R_{\gamma}}} \\
& =\rho_{0}\left[1-\frac{\gamma}{T_{o}}\left(x_{3}-x_{30}\right)\right]^{\frac{g}{R \gamma}-1} \tag{C-4}
\end{align*}
$$

where $x_{30}$ is the equilibrium altitude at which $\sigma=\rho_{o}$. If Equation (C-4) is divided by $\sigma$ the result is

$$
\begin{align*}
\tilde{\rho} & =\frac{\rho_{0}}{\sigma}\left[1-\frac{\gamma}{T_{0}}\left(x_{3}-x_{30}\right)\right]^{\frac{g}{R \gamma}-1} \\
& =\left[1-\tilde{a} \Delta \tilde{x}_{3}\right]^{\tilde{b}-1} \tag{C-5}
\end{align*}
$$

where

$$
\begin{align*}
& \tilde{\mathbf{a}}=\frac{\gamma D}{T_{0}}  \tag{C-6}\\
& \Delta \tilde{\mathbf{x}}_{3}=\mathbf{x}_{3} / D-\mathbf{x}_{30} / D  \tag{C-7}\\
& \tilde{b}=g /(R \gamma) \tag{C-8}
\end{align*}
$$

Now Equation (C-5) can be substituted into Equation (C-1) but the result is quite cumbersome. A term by term examination of the R. H. S. of Equation (C-1) reveals that only in the numerator of the fifth term, representing buoyancy, does the variation of $\tilde{\rho}$ appear significant. If Equation (C-5) is substituted into only this term in Equation ( $C-1$ ), the result is still awkward because of the nonlinear form of Equation (C-5). To avoid this difficulty, by means of series expansions,

$$
\begin{equation*}
\left(1-\tilde{a} \Delta \tilde{x}_{3}\right)^{b-1}=1-(\tilde{b}-1) \tilde{a} \Delta \tilde{x}_{3}+0\left(\Delta^{2} \tilde{x}_{3}\right) \tag{C-9}
\end{equation*}
$$

Neglecting second order terms,

$$
\begin{equation*}
\rho \simeq 1-(\tilde{b}-1) \tilde{a} \Delta \tilde{x}_{3} \tag{C-10}
\end{equation*}
$$

If Equation ( $\mathrm{C}-10$ ) is substituted into the numerator of the fifth term of the R. H. S. of Equation (C-1), the result is

$$
\begin{aligned}
\frac{d \bar{v}_{i}}{d \tilde{t}}= & 36\left(\frac{\tilde{\rho}}{2+\tilde{\rho}}\right) \tilde{v}\left(\tilde{u}_{i}-\tilde{v}_{i}\right)+\frac{3}{2}\left(\frac{\tilde{\rho}}{2+\tilde{\rho}}\right) C_{D \ell}\left(\tilde{u}_{i}-\tilde{v}_{i}\right)|\overrightarrow{\tilde{u}}-\tilde{v}| \\
& +3\left(\frac{\tilde{\rho}}{2+\tilde{\rho}}\right) \frac{D \tilde{u}_{i}}{D \tilde{t}}+\left(\frac{\tilde{\rho}}{2+\tilde{\rho}}\right)\left(\tilde{v}_{j}-\tilde{u}_{j}\right) \frac{\partial \tilde{u}_{i}}{\partial \tilde{x}_{j}} \\
& -\frac{2(\tilde{b}-1) \tilde{a}}{2+\tilde{\rho}}
\end{aligned} \quad \Delta \tilde{x}_{3} \tilde{g} \delta_{i 3}-18\left(\frac{\tilde{\rho}}{2+\tilde{\rho}}\right) \sqrt{\frac{\tilde{\nu}}{\pi}} \int_{0} \frac{\frac{d\left(\tilde{v}_{i}-\tilde{u}_{i}\right)}{d \tilde{t}^{\prime}} d \tilde{t}}{\sqrt{\tilde{t}-\tilde{t}}}(\mathrm{C}-11) \quad .
$$

Equation (C-11) represents a dimensionless form of the balloon equations from which certain dimensionless parameters can be obtained. A term by term inspection of the R. H. S. of Equation (C-11) results in the following dimensionless groups:

$$
\begin{align*}
& L_{1}=\frac{\rho}{2 \sigma+\rho}  \tag{C-12}\\
& L_{2}=\frac{\sigma}{2 \sigma+\rho}  \tag{C-13}\\
& L_{3}=\frac{12 \nu}{A D}  \tag{C-14}\\
& L_{4}=\frac{1}{2} C_{D \ell}  \tag{C-15}\\
& L_{5}=\frac{2}{3} \frac{g(g / R-\gamma) D^{2}}{A^{2} T_{0}}  \tag{C-16}\\
& L_{6}=6 \sqrt{\frac{V}{A D}} \tag{C-17}
\end{align*}
$$

In terms of the six preceding dimensionless groups, Equation (C-11) can be written

$$
\begin{aligned}
\frac{d \tilde{v}_{i}}{d \tilde{t}}= & 3 L_{1} L_{3}\left(\tilde{u}_{i}-\tilde{v}_{i}\right)+3 L_{1} L_{4}\left(\tilde{u}_{i}-\tilde{v}_{i}\right)|\overrightarrow{\tilde{u}}-\tilde{v}| \\
& +3 L_{1} \frac{D \tilde{u}_{i}}{D \tilde{t}}+L_{1}\left(\tilde{v}_{j}-\tilde{u}_{j}\right) \frac{\partial \tilde{u}_{i}}{\partial x_{j}}-3 L_{2} L_{5} \Delta x_{3} \delta_{i 3}
\end{aligned}
$$

$$
-3 L_{1} L_{6} \int_{0}^{\frac{\mathfrak{Z}}{d\left(\tilde{v}_{1}-\tilde{u}_{j}\right)}} \frac{d \tilde{Z}^{\prime}}{\sqrt{\mathfrak{Z} \mathfrak{Z}^{\prime}}}
$$

( $\mathrm{C}-18$ )

## Dimensional Inviscid Flow Field Development

The velocity components are assumed to be of the form

$$
\begin{align*}
& u_{1}=\bar{u}_{1}+A \sin \left(k_{1} x_{1}+k_{2} x_{2}+k_{3} x_{3}-\omega t+\theta_{1}\right)  \tag{D-1}\\
& u_{2}=B \sin \left(k_{1} x_{1}+k_{2} x_{2}+k_{3} x_{3}-\omega t+\theta_{2}\right) \\
& u_{3}=c \sin \left(k_{1} x_{1}+k_{2} x_{2}+k_{3} x_{3}-\omega t+\theta_{3}\right)
\end{align*}
$$

For brevity let

$$
\begin{equation*}
\xi=k_{1} x+k_{2} y+k_{3} z \tag{D-4}
\end{equation*}
$$

Then

$$
\begin{align*}
& \frac{\partial u_{1}}{\partial x_{1}}=A k_{1} \cos \left(\xi-\omega t+\theta_{1}\right)  \tag{D-5}\\
& \frac{\partial u_{2}}{\partial x_{2}}=B k_{2} \cos \left(\xi-\omega t+\theta_{2}\right)  \tag{D-6}\\
& \frac{\partial u_{3}}{\partial x_{3}}=C k_{3} \cos \left(\xi-\omega t+\theta_{3}\right) \tag{D-7}
\end{align*}
$$

For mass conservation,

$$
\begin{equation*}
\frac{\partial u_{1}}{\partial x_{1}}+\frac{\partial u_{2}}{\partial x_{2}}+\frac{\partial u_{3}}{\partial x_{3}}=0 \tag{D-8}
\end{equation*}
$$

Thus

$$
\begin{align*}
& A k_{1} \cos \left(\xi-\omega t+\theta_{1}\right)+B k_{2} \cos \left(\xi-\omega t+\theta_{2}\right)+C k_{3} \cos \left(\xi-\omega t+\theta_{3}\right) \\
&=0 \tag{D-9}
\end{align*}
$$

or

$$
\begin{align*}
A k_{1}\{\cos & \left.(\xi-\omega t) \cos \theta_{1}-\sin (\xi-\omega t) \sin \theta_{1}\right\}+B k_{2}\left\{\cos (\xi-\omega t) \cos \theta_{2}\right. \\
& \left.-\sin (\xi-\omega t) \sin \theta_{2}\right\}+C k_{3}\left\{\cos (\xi-\omega t) \cos \theta_{3}\right. \\
& \left.-\sin (\xi-\omega t) \sin \theta_{3}\right\}=0 \tag{D-10}
\end{align*}
$$

To satisfy Equation (D-10), it is necessary for
$\left(A k_{1} \cos \theta_{1}+B k_{2} \cos \theta_{2}+\mathrm{Ck}_{3} \cos \theta_{3}\right) \cos (\xi-\omega t)=0$
and

$$
\begin{equation*}
\left(A k_{1} \sin \theta_{1}+B k_{2} \sin \theta_{2}+C k_{3} \sin \theta_{3}\right) \sin (\xi-\omega t)=0 \tag{D-12}
\end{equation*}
$$

This in turn requires

$$
\begin{equation*}
A k_{1} \cos \theta_{1}+B k_{2} \cos \theta_{2}+C k_{3} \cos \theta_{3}=0 \tag{D-13}
\end{equation*}
$$

and

$$
\begin{equation*}
A k_{1} \sin \theta_{1}+B k_{2} \sin \theta_{2}+C k_{3} \sin \theta_{3}=0 \tag{D-14}
\end{equation*}
$$

Equation ( $D-13$ ) can be multiplied by $\tan \theta_{1}$ to obtain
$A k_{1} \sin \theta_{1}+B k_{2} \cos \theta_{2} \tan \theta_{1}+C k_{3} \cos \theta_{3} \tan \theta_{1}=0$
Subtracting (D-15) from (D-14) yields
$\mathrm{Bk}_{2}\left(\sin \theta_{2}-\cos \theta_{2} \tan \theta_{1}\right)+\mathrm{Ck}_{3}\left(\sin \theta_{3}-\cos \theta_{3} \tan \theta_{1}\right)=0$
Solving for $B$,

$$
\begin{equation*}
B=-\frac{C k_{3}}{k_{2}} \frac{\left(\sin \theta_{3}-\cos \theta_{3} \tan \theta_{1}\right)}{\left(\sin \theta_{2}-\cos \theta_{2} \tan \theta_{1}\right)} \tag{D-17}
\end{equation*}
$$

Next Equation ( $D-13$ ) can be multiplied by $\tan \theta_{2}$ to obtain

$$
\begin{equation*}
A k_{1} \cos \theta_{1} \tan \theta_{2}+B k_{2} \sin \theta_{2}+C k_{3} \cos \theta_{3} \tan \theta_{2}=0 \tag{D-18}
\end{equation*}
$$

Subtracting ( $D-18$ ) from ( $D-14$ ) yields

$$
\begin{equation*}
A k_{1}\left(\sin \theta_{1}-\cos \theta_{1} \tan \theta_{2}+C k_{3}\left(\sin \theta_{3}-\cos \theta_{3} \tan \theta_{2}\right)=0\right. \tag{D-19}
\end{equation*}
$$

Solving for A,

$$
\begin{equation*}
A=-\frac{\mathrm{Ck}_{3}}{k_{1}} \frac{\left(\sin \theta_{3}-\cos \theta_{3} \tan \theta_{2}\right)}{\left(\sin \theta_{1}-\cos \theta_{1} \tan \theta_{2}\right)} \tag{D-20}
\end{equation*}
$$

Thus if Equation ( $D-17$ ) and ( $D-20$ ) are satisfied, the inviscid flow field model described in Equations (D-1) through (D-3) satisfies the continuity equation.

Certain other partial derivatives of velocity with respect to space and time can be derived from the model as follows:

$$
\begin{equation*}
\frac{\partial u_{1}}{\partial x_{2}}=A k_{2} \cos \left(\xi-\omega t+\theta_{1}\right) \tag{D-21}
\end{equation*}
$$

$$
\begin{align*}
& \frac{\partial u_{1}}{\partial x_{3}}=A k_{3} \cos \left(\xi-\omega t+\theta_{1}\right)  \tag{D-22}\\
& \frac{\partial u_{2}}{\partial x_{1}}=B k_{1} \cos \left(\xi-\omega t+\theta_{2}\right)  \tag{D-23}\\
& \frac{\partial u_{2}}{\partial x_{3}}=B k_{3} \cos \left(\xi-\omega t+\theta_{2}\right)  \tag{D-24}\\
& \frac{\partial u_{3}}{\partial x_{1}}=C{k_{1}}_{1} \cos \left(\xi-\omega t+\theta_{3}\right)  \tag{D-25}\\
& \frac{\partial u_{3}}{\partial x_{2}}=C k_{2} \cos \left(\xi-\omega t+\theta_{3}\right)  \tag{D-26}\\
& \frac{\partial u_{1}}{\partial t}=-A \omega \cos \left(\xi-\omega t+\theta_{1}\right)  \tag{D-27}\\
& \frac{\partial u_{2}}{\partial t}=-B \omega \cos \left(\xi-\omega t+\theta_{2}\right)  \tag{D-28}\\
& \frac{\partial u_{3}}{\partial t}=-C \omega \cos \left(\xi-\omega t+\theta_{3}\right) \tag{D-29}
\end{align*}
$$

As formulated the model contains a total of eleven different parameters ( $\bar{u}_{1}, A, B, C, k_{1}, k_{2}, k_{3}, \omega, \theta_{1}, \theta_{2}$, and $\theta_{3}$ ). As given by Equations ( $D-17$ ) and ( $D-20$ ) for conservation of mass, two of the three amplitudes ( $A, B$, and $C$ ) must be functions of the third. Thus there are nine independent parameters in Equations (D-1) through (D-3). In the current study, it was not feasible to consider all possible combinations of these nine parameters. The following simplifications were made: First, all wave numbers ( $k_{1}, k_{2}$ and $k_{3}$ ) were taken to be equal,

$$
\begin{equation*}
\mathrm{k}_{1}=\mathrm{k}_{2}=\mathrm{k}_{3}=\mathrm{k} \tag{D-30}
\end{equation*}
$$

Second, by proper choice of the phase angles $\left(\theta_{1}, \theta_{2}\right.$, and $\left.\theta_{3}\right)$ the amplitudes were taken to be equal.

$$
\begin{equation*}
A=B=C \tag{D-31}
\end{equation*}
$$

It can be readily shown by means of Equations (D-17) and (D-20) that the phase angles,

$$
\begin{align*}
& \theta_{1}=0  \tag{D-32}\\
& \theta_{2}=2 \pi / 3 \tag{D-33}
\end{align*}
$$

$$
\begin{equation*}
\theta_{3}=-2 \pi / 3 \tag{D-34}
\end{equation*}
$$

or any similar combination of phase angles set $120^{\circ}$ apart, satisfy Equation (D-31).

Based on the simplifications noted, the fluid velocity components can be written as

$$
\begin{equation*}
u_{i}=\bar{u}_{1} \delta_{11}+A \sin \left(\zeta-\omega t+\theta_{i}\right) \tag{D-35}
\end{equation*}
$$

where

$$
\begin{align*}
& \zeta=k\left(x_{1}+x_{2}+x_{3}\right)  \tag{D-36}\\
& \theta_{1}=0  \tag{D-37}\\
& \theta_{2}=2 \pi / 3  \tag{D-38}\\
& \theta_{3}=-2 \pi / 3
\end{align*}
$$

(D-39)

## Dimensionless Inviscid Flow Field Development

As developed in Appendix $D$, the wind velocity components can be expressed as:

$$
\begin{equation*}
u_{i}=\bar{u}_{1} \delta_{i 1}+A \sin \left(\zeta-\omega t+\theta_{i}\right) \tag{E-1}
\end{equation*}
$$

where

$$
\begin{align*}
& \zeta=k\left(x_{1}+x_{2}+x_{3}\right)  \tag{E-2}\\
& \theta_{1}=0  \tag{E-3}\\
& \theta_{2}=2 \pi / 3  \tag{E-4}\\
& \theta_{3}=-2 \pi / 3 \tag{E-5}
\end{align*}
$$

Based on the nondimensional procedure followed in Appendix C, Equation (E-1) can be written in the following dimensionless form:

$$
\begin{equation*}
\tilde{u}_{i}=\tilde{\bar{u}}_{1} \delta_{i 1}+\sin \left(\zeta-\tilde{\omega} \tilde{t}+\theta_{i}\right) \tag{E-6}
\end{equation*}
$$

where

$$
\begin{align*}
& \tilde{u}_{i}=u_{i} / A  \tag{E-7}\\
& \tilde{\bar{u}}_{1}=\bar{u}_{1} / A  \tag{E-8}\\
& \zeta=\tilde{k}\left(\tilde{x}_{1}+\tilde{x}_{2}+\tilde{x}_{3}\right)  \tag{E-9}\\
& \tilde{\omega}=\omega D / A  \tag{E-10}\\
& \tilde{t}=A t / D  \tag{E-11}\\
& \tilde{k}=k D  \tag{E-12}\\
& \tilde{x}_{i}=x_{i} / D \tag{E-13}
\end{align*}
$$

Equation (E-6) represents the dimensionless form of the inviscid flow field. Notice should be taken that in dimensionless form the flow field can be described in terms of three dimensionless
groups, $\tilde{\bar{u}}_{1}, \tilde{\mathbf{k}}$, and $\tilde{\boldsymbol{\omega}}$. The dimensionless variables $\tilde{x}_{i}$ and $\tilde{t}$ are not necessary for characterizing the flow field because they represent the coordinates of the balloon in space and time (to be obtained from the solution of the differential equation governing the balloon motion).

## APPENDIX F

## Reynolds Number Reiation to Dimensionless Groups

The Reynolds number for flow past the balloon is defined
as:

$$
\begin{equation*}
\operatorname{Re}=\frac{\dot{\rho}|\vec{u}-\vec{v}| D}{u} \tag{F-1}
\end{equation*}
$$

Now, the maximum difference between the wind velocity and the balloon velocity must be roughly equal to the amplitude $A$ in the inviscid flow field model. Thus,

$$
\begin{equation*}
|\vec{u}-\vec{v}| \simeq A \tag{F-2}
\end{equation*}
$$

Therefore,

$$
\begin{equation*}
\operatorname{Re} \simeq \frac{\rho A D}{\mu} \tag{F-3}
\end{equation*}
$$

An examination of the first dimensionless groups given in Appendix C reveals that to first-order accuracy,

$$
\begin{equation*}
R e \simeq 12 / L_{3} \tag{F-4}
\end{equation*}
$$

where

$$
\begin{equation*}
L_{3}=\frac{12 \nu}{A D} \tag{F-5}
\end{equation*}
$$

## APPENDIX G

## Dimensional Analysis

Dimensional analysis is a standard technique for reducing the number of variabies in a problem and for identifying the important parameters associated with the problem. This is particularly useful when one has a physical problem the variables of which are well known but for which no analytic relationship is known. But, it is also useful for determining the necessary nondimensional groups for a given set of analytic relationships describing a physical process.

For the analysis of a balloon in a realistic atmosphere, this analysis is presented as an extension of the development of the nondimensional equations discussed in Appendices $C$ and $E$. The pertinent variables for the analysis are:

| $\mathbf{v}_{\mathbf{i}}$ | balloon velocity |
| :--- | :--- |
| $\mathbf{x}_{\mathbf{i}}$ | balloon position |
| $u_{i}$ | ambient wind velocity |
| $t$ | elapsed time |
| $\rho$ | ambient density |
| $\mu$ | dynamic viscosity |
| $g$ | gravitational acceleration |
| $\sigma$ | density of the balloon |
| $D$ | diameter of the balloon |
| $C_{D \ell}$ | drag coefficient $\left(10^{3}<R e<10^{5}\right)$ |

The first two variables, $\mathrm{v}_{\mathrm{i}}$ and $\mathrm{x}_{\mathrm{i}}$ represent the unknown properties of the balloon. These two variables are not independent of each other since $v_{i}$ is simply the time deviative of $x_{i}$. The variable $u_{i}$, representing the ambient wind velocity can be expressed as

$$
\begin{equation*}
u_{i}=u_{i}\left(\bar{u}_{1}, A, k, \omega\right) \tag{G-1}
\end{equation*}
$$

The ambient density, $\rho$, can likewise be expressed as

$$
\begin{equation*}
\rho=\rho\left(\rho_{o}, \gamma, T_{0}, g, R, x_{3}\right) \tag{G-2}
\end{equation*}
$$

The viscosity, $\mu$, can also be expressed as

$$
\begin{equation*}
\mu=\mu\left(\mu_{0}, \gamma, T_{0}, x_{3}\right) \tag{G-3}
\end{equation*}
$$

Thus there are 16 variables ( $v_{i}, x_{i}, \bar{u}_{1}, A, k, \omega, t, \rho_{o}, \gamma, T_{o}, R, \mu_{o}, g, \sigma, D_{j} C_{D \ell}$ ) involved in the dimensional analysis. The primary dimensions involved are mass ( $M$ ), length ( $\ell$ ), time ( $t$ ) and temperature ( $T$ ). The dimensional matrix for this case is as follows:


| M | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 0 | 0 | 0 | - | 0 | 1 | 0 |
| :--- | ---: | ---: | ---: | ---: | ---: | ---: | ---: | ---: | ---: | ---: | ---: | ---: | ---: | ---: | ---: |
| $\ell$ | 1 | 1 | 1 | 1 | -1 | 0 | 0 | -3 | -1 | 0 | 2 | $\mathbf{- 1}$ | 1 | -3 | 1 |
|  | 0 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| t | $\mathbf{- 1}$ | 0 | -1 | -1 | 0 | -1 | 1 | 0 | 0 | 0 | -2 | $\mathbf{- 1}$ | -2 | 0 | 0 |
| T | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 1 | -1 | 0 | 0 | 0 | 0 |
| 0 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |

According to the Buckingham $I I$ theorem, with 16 variables and 4 primary dimensions, there will be a maximum of 12 dimensionless groups. The 12 dimensionless groups take on a variety of forms depending on the choice of primary variables. If $A, \rho_{o}, D$ and $T_{o}$ are chosen as the primary variables, then the following dimensionless groups result:

$$
\begin{align*}
& \Pi_{1}=v_{i} / A  \tag{G-4}\\
& \Pi_{2}=x_{i} / D  \tag{G-5}\\
& \Pi_{3}=\bar{u}_{1} / A  \tag{G-6}\\
& \Pi_{4}=\omega D / A  \tag{G-7}\\
& \pi_{5}=A t / D  \tag{G-8}\\
& \Pi_{6}=\gamma D / T_{o}  \tag{G-9}\\
& \Pi_{7}=R T_{o} / A^{2}  \tag{G-10}\\
& \Pi_{8}=\mu_{o} /\left(A \rho_{o} D\right)  \tag{G-11}\\
& \Pi_{9}=g D / A \tag{G-12}
\end{align*}
$$

Some of the preceding dimensionless groups are identical to or closely resemble the dimensionless groups derived in Appendices $C$ and $E$ of this report. Others, however, are not so easily identified. The relationships between the two sets of dimensionless groups can be developed as follows:

$$
\begin{align*}
& \tilde{\mathrm{v}}_{i}=\Pi_{1} \text { (balloon velocity) }  \tag{G-16}\\
& \tilde{x}_{i}=\Pi_{2} \text { (balloon position) }  \tag{G-17}\\
& \tilde{\mathrm{t}}=\Pi_{5} \text { (elapsed time) }  \tag{G-18}\\
& L_{1} \cong \frac{1}{2 \Pi_{10}+1}  \tag{G-19}\\
& L_{2} \cong \frac{\Pi_{10}}{2 \Pi_{10}+1}  \tag{G-20}\\
& L_{3} \cong 12 \Pi_{8}  \tag{G-21}\\
& L_{4} \cong \frac{1}{2} \Pi_{12}  \tag{G-22}\\
& L_{5} \cong \frac{2}{3} \Pi_{9}\left(\frac{\Pi_{9}}{\Pi_{7}}-\Pi_{6}\right)  \tag{G-23}\\
& L_{6} \cong 6  \tag{G-24}\\
& \tilde{k}=\Pi_{11}  \tag{G-25}\\
& \tilde{\omega}=\Pi_{4}  \tag{G-26}\\
& \tilde{\Pi_{1}}=\Pi_{3}
\end{align*}
$$

The use of the approximate equalities in Equations (G-19) through (G-22) and in Equation (G-24) reflects the fact that $L_{1}$ through $L_{4}$ and $L_{6}$ contain the variables $\rho$ and $\mu$ while $\Pi_{8}, \Pi_{10}$ and $\Pi_{11}$ contain their equilibrium counterparts $\rho_{0}$ and $\mu_{0}$. An examination of Equations (G-16) through (G-27) reveals that all 12 dimensionless groups ( $\Pi_{1}$ through $\Pi_{12}$ ) appear in the definitions of the dimensionless terms which arise in the dimensionless differential equation for balloon motion and the dimensionless inviscid flow field model. Furthermore, as previously noted, $\tilde{v}_{i}$ and $\tilde{x}_{i}$ (II ${ }_{1}$ and $\Pi_{2}$ ) are not independent of each other but represent the solution of the differential equation for the balloon equation. The variable $\tilde{t}\left(\Pi_{5}\right)$ is obviously dimensionless time, with respect to
which both $\tilde{x}_{i}$ and $\tilde{v}_{i}$ can be expressed. The remaining eight dimensionless groups can be reduced to five if the ratio $\rho / \sigma$ is taken as unity and if $C_{D}$ is taken as constant.* Thus, with this simplification the entire problem can be characterized in terms of five dimensionless groups:

$$
\frac{12 \nu}{A D}, \frac{2 g(g / R-\gamma) D^{2}}{3 A^{2} \cdot T_{o}}, k D, \frac{\omega D}{A}, \text { and } \frac{\bar{u}_{1}}{A}
$$

The solution in terms of dimensionless balloon position ( $X_{i} / D$ ) and velocity ( $v_{i} / A$ ) as functions dimensionless time (At/D) should remain unchanged (to first-order accuracy) provided these five groups remain constant.

[^5]
## First Order Perturbation Analysis of Constant-Volume

Balloon Motion in Turbulent Flow

The problem under consideration is a constant-volume balloon floating in a two-dimensional turbulent flow field with stationary turbulence which is homogeneous in the x-direction. The coordinate system is shown in Figure H-1.

sarmery
Figure H-1. Coordinate System for First-Order Perturbation Analysis The longitudinal component of the wind velocity can be expressed as

$$
\begin{equation*}
u_{1}\left(x_{1}, t, x_{3}\right)=u_{1}\left(x_{3}\right)+u_{1}^{\prime}\left(x_{1}, t, x_{3}\right) \tag{H-1}
\end{equation*}
$$

The fluctuating portion of the longitudinal component can be expressed in terms of a Fourier integral;

$$
\begin{equation*}
u_{i}^{\prime}\left(x_{1}, t, x_{3}\right)=\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} B\left(k, \omega ; x_{3}\right) e^{i\left(k x_{1}-\omega t\right)} d k d \omega \tag{H-2}
\end{equation*}
$$

The coordinates of the CVB are functions of both time and the initial balloon position. Because the turbulence is homogeneous in the $x$-direction and the mean wind velocity is assumed to be constant with respect to $x_{1}$ and $t$, only the $x_{3}$-coordinate of the initial position is significant. Thus
(Balloon Coordinates) $=\left[X_{1}\left(t, X_{30}\right), X_{3}\left(t, X_{30}\right)\right]$
The horizontal component of the'balloon velocity can be written as

$$
\begin{equation*}
v_{1}\left(t, x_{30}\right)=\frac{\partial x_{1}}{\partial t}=u_{1}\left[x_{1}\left(t, x_{30}\right), t, x_{3}\left(t, x_{30}\right)\right] \tag{H-4}
\end{equation*}
$$

Equating the horizontal component of the balloon velocity to the corresponding wind velocity component at the balloon location is based on the assumption that the balloon responds perfectly to the wind velocity in the horizontal direction.

The vertical component of balloon velocity can be
written:

$$
\begin{equation*}
v_{3}\left(t, X_{30}\right)=\frac{\partial X_{3}}{\partial t} \tag{H-5}
\end{equation*}
$$

Notice should be taken that $v_{3}$ cannot be set equal to vertical component of the wind velocity, $u_{3}$, because a constant-volume balloon cannot be perfectly responsive in the vertical direction.

The balloon coordinates can be written as:

$$
\begin{align*}
x_{1}\left(t, x_{30}\right) & =\int_{0}^{t} v_{1}\left(t, x_{30}\right) d t \\
& =\bar{u}_{1}\left(X_{30}\right) t+\int_{0}^{t} u_{i}^{\prime}\left(x_{1}, t, x_{3}\right) d t \\
& =\bar{x}_{1}\left(X_{30}, t\right)+X_{1}^{\prime}\left(t, x_{30}\right) \tag{H-6}
\end{align*}
$$

and

$$
\begin{align*}
x_{3}\left(t, x_{30}\right) & =\int_{0}^{t} v_{3}\left(t, x_{30}\right) d t+x_{30} \\
& =x_{3}^{\prime}\left(t, x_{30}\right)+x_{30} \tag{H-7}
\end{align*}
$$

The fluctuating portion of the longitudinal component of the balloon velocity, $v_{1}^{\prime}$, can be expressed in terms of a Fourier integral analogous to that for the wind velocity component, $u_{1}$. Thus:

$$
\begin{align*}
v_{1}^{\prime}\left(t, X_{30}\right) & =v_{1}\left(t, X_{30}\right)-\bar{u}_{1}\left(x_{3}\right) \\
& =\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} B\left(k, \omega ; x_{3}\right) e^{i\left[k\left(\bar{x}_{1}+x_{1}^{\prime}\right)-\omega t\right]} d k d \omega \tag{H-8}
\end{align*}
$$

Expansion of $B\left(k, \omega ; X_{3}\right)$ in a Taylor series about $X_{30}$ yields

$$
\begin{align*}
B\left(k, \omega ; X_{3}\right) & =B\left(k, \omega ; X_{30}\right)+\frac{\partial B}{\partial Z}\left(X_{3}-X_{30}\right)+\frac{1}{2} \frac{\partial^{2} B}{\partial Z^{2}}\left(X_{3}-X_{30}\right)^{2}+\ldots \\
& =B\left(k, \omega ; X_{30}\right)+\frac{\partial B}{\partial Z} \quad X_{3}^{\prime}+\frac{1}{2} \cdot \frac{\partial^{2} B}{\partial Z^{2}}\left(X_{3}^{\prime}\right)^{2}+\ldots \tag{H-O}
\end{align*}
$$

Likewise the exponential series for $e^{i k X_{1}^{\prime}}$ can be written

$$
\begin{equation*}
e^{i k X_{1}}=1+i k X_{1}-\frac{1}{2}\left(k X_{1}^{\prime}\right)^{2}+\ldots \tag{H-10}
\end{equation*}
$$

A combination of Equations (H-8) through (H-10) yields

$$
\begin{align*}
v_{1}^{\prime}\left(t, X_{30}\right)= & \int_{-\infty}^{\infty} \int_{-\infty}^{\infty}\left[B\left(k, \omega ; X_{30}\right)+\frac{\partial B}{\partial Z} X_{3}^{\prime}+\frac{1}{2} \frac{\partial^{2} B}{\partial Z^{2}}\left(X_{3}^{\prime}\right)^{2}+\ldots\right][1 \\
& \left.+i k X_{1}-\frac{1}{2}\left(k X_{1}^{\prime}\right)^{2}+\ldots\right] e^{i\left(k \bar{X}_{1}-\omega t\right)} d k d \omega
\end{align*}
$$

To first-order accuracy*

$$
\begin{equation*}
v_{1}^{\prime}\left(t, X_{30}\right)=\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} B\left(k, \omega ; X_{30}\right) e^{i\left(k \bar{X}_{1}-\omega t\right)} d k d \omega \tag{H-12}
\end{equation*}
$$

In similar fashion the velocity component $v_{1}^{\prime}\left(t+\tau, X_{30}\right)$
can be expressed to first-order accuracy as

$$
v_{1}^{\prime}\left(t+\tau, X_{30}\right)=\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} B\left(k, \omega ; X_{30}\right) e^{i\left[k\left(\bar{X}_{1}+\bar{u}_{1} \tau\right)-\omega(t+\tau)\right]} d k d \omega(H-13)
$$

Because $v_{1}^{\prime}$ is real, the Fourier integral representation for $v_{1}^{\prime}\left(t+\tau, X_{30}\right)$ can be written as

$$
\begin{equation*}
v_{\mathbf{1}}^{\prime}\left(t+\tau, X_{30}\right)=\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} B^{*}\left(k, \omega ; X_{30}\right) e^{-i\left[k\left(\bar{X}_{1}+\bar{u}_{1} \tau\right)-\omega(t+\tau)\right]_{d k} d \omega} \tag{H-14}
\end{equation*}
$$

[^6]The product $v_{1}^{\prime}\left(t, X_{30}\right) v_{i}^{\prime}\left(t+\tau, X_{30}\right)$ can be expressed as $v_{i}^{\prime}\left(t, X_{30}\right) v_{i}\left(t+\tau, X_{30}\right)$
$=\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} B\left(k^{\prime}, \omega^{\prime} ; X_{30}\right) B^{*}\left(k, \omega ; X_{30}\right) e^{i\left(k^{\prime} \bar{x}_{1}-\omega^{\prime} t\right)}$
$e^{-i\left[k\left(\bar{X}_{1}+\bar{u}_{1} \tau\right)-\omega(t+\tau)\right]} d k^{\prime} d \omega ' d k d \omega$
Equation (H-15) holds for each realization of the ensemble. Thus the ensemble average representing the quasi-Lagrangian time autocorrelation function, can be written as

$$
\begin{align*}
& \left\langle v_{i}^{\prime}\left(t, x_{30}\right) v_{1}^{\prime}\left(t+\tau, x_{30}\right)\right\rangle \\
& =\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty}\left\langle B\left(k^{\prime}, \omega^{\prime} ; x_{30}\right) B^{*}\left(k, \omega ; x_{30}\right)\right\rangle \\
& e^{-i\left[\bar{x}_{1}\left(k^{\prime}-k\right)-t\left(\omega^{\prime}-\omega\right)\right]} e^{-i\left(k \bar{u}_{1} \tau-\omega \tau\right)} d k^{\prime} d \omega^{\prime} d k d \omega \tag{H-16}
\end{align*}
$$

A more useful form of Equation ( $\mathrm{H}-16$ ) can be obtained by the following change of variables:

$$
\left.\begin{array}{l}
\mathbf{k}^{\prime \prime}=\mathbf{k}-\mathbf{k}^{\prime}  \tag{H-17}\\
\omega^{\prime \prime}=\omega-\omega^{\prime}
\end{array}\right\} \longrightarrow\left\{\begin{array}{l}
\mathbf{k}^{\prime}=\mathbf{k}-\mathbf{k}^{\prime \prime} \\
\omega^{\prime}=\omega-\omega^{\prime}
\end{array}\right.
$$

Introduction of $\mathrm{k}^{\prime \prime}$ and $\omega^{\prime \prime}$ in Equation ( $\mathrm{H}-16$ ) produces

$$
\begin{align*}
& v_{i}\left(t, X_{30}\right) v_{i}\left(t+\tau, X_{30}\right) \\
& =\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty}\left\langle B\left(k-k^{\prime} \cdot, \omega-\omega^{\prime} ; X_{30}\right) B^{*}\left(k, \omega ; \mathrm{X}_{30}\right)\right\rangle \\
& e^{-i\left(k^{\prime} \bar{x}_{1}-\omega^{\prime} ' t\right)} e^{-i\left(k \bar{u}_{1} \tau-\omega \tau\right)} d k^{\prime} d \omega^{\prime \prime} d k d \omega \tag{H-18}
\end{align*}
$$

The general Eulerian space-time power spectrum, $\phi_{E}\left(k, \omega, x_{1}, t ; x_{3}\right)$, of the horizontal wind velocity $u_{1}^{\prime},\left(x_{1}, t, x_{3}\right)$ by definition is:

$$
\begin{align*}
\phi_{E}\left(k, \omega, x_{1}, t^{-} ; x_{3}\right)= & \int_{-\infty}^{\infty} \int_{-\infty}^{\infty}\left\langle B\left(k-k^{\prime}, \omega-\omega^{\prime \prime} ; x_{3}\right) B^{*}\left(k, \omega ; x_{3}\right)\right\rangle \\
& e^{i\left(k^{\prime} ' x_{1}-\omega^{\prime} ' t\right)} d k^{\prime \prime} d \omega^{\prime \prime \prime} \tag{H+19}
\end{align*}
$$

At the balloon coordinates ( $\bar{X}_{1}, X_{30}$ ) the general power spectrum of the wind velocity component $u_{i}\left(\bar{x}_{1}, t, X_{30}\right)$ would be

$$
\begin{align*}
\phi_{E}\left(k, \omega, \bar{X}_{1}, t ; X_{30}\right)= & \int_{-\infty}^{\infty} \int_{-\infty}^{\infty}\left\langle B\left(k-k^{\prime \prime}, \omega-\omega^{\prime \prime} ; X_{30}\right) B^{*}\left(k, \omega ; X_{30}\right)\right\rangle \\
& e^{i\left(k^{\prime \prime} \bar{X}_{1}-\omega^{\prime} ' t\right)} d k^{\prime \prime} d \omega^{\prime \prime} \tag{H-20}
\end{align*}
$$

For the case under consideration the turbulence is homogeneous in the $x_{1}$-direction and stationary, and thus the corresponding Eulerian space-time power spectrum is not a function of $\bar{X}_{1}$ or $t$. For such a case,

$$
\begin{equation*}
\phi_{E}\left(k, \omega, \bar{X}_{1}, t ; X_{30}\right) \longrightarrow \phi_{E}\left(k, \omega ; X_{30}\right) \tag{H-21}
\end{equation*}
$$

A combination of Equations ( $\mathrm{H}-20$ ) and ( $\mathrm{H}-21$ ) produces

$$
\begin{align*}
\phi_{E}\left(k, \omega ; X_{30}\right)= & \int_{-\infty}^{\infty} \int_{-\infty}^{\infty}\left\langle B\left(k-k^{\prime} \cdot, \omega-\omega^{\prime \prime} ; X_{30}\right) B^{*}\left(k, \omega ; X_{30}\right)\right\rangle \\
& e^{i\left(k^{\prime} \bar{X}_{1}-\omega^{\prime} \cdot t\right)} d k^{\prime \prime} d \omega^{\prime \prime} \tag{H-22}
\end{align*}
$$

In order for the RHS of Equation (H-22) to be consistent with the LHS

$$
\begin{equation*}
\left\langle B\left(k-k^{\prime \prime}, \omega-\omega^{\prime \prime} ; X_{30}\right) \quad B^{*}\left(k, \omega ; X_{30}\right)>=F\left(k, \varphi ; X_{30}\right) \delta\left(k^{\prime \prime}\right) \delta\left(\omega^{\prime \prime}\right)\right. \tag{H-23}
\end{equation*}
$$

where

$$
\begin{equation*}
F\left(k ; \omega ; X_{30}\right) \propto<B\left(k, \omega ; X_{30}\right) B^{*}\left(k, \omega ; X_{30}\right)> \tag{H-24}
\end{equation*}
$$

A combination of Equations (H-22) through (H-24) yields

$$
\begin{align*}
\phi_{E}\left(k, \omega ; X_{30}\right)= & \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} F\left(k, \omega ; X_{30}\right) \delta\left(k^{\prime \prime}\right) \delta\left(\omega^{\prime}\right) \\
& e^{\left.i\left(k^{\prime}\right) \bar{X}_{1}-\omega^{\prime} t\right) d k^{\prime} d \omega^{\prime \prime}} \\
= & F\left(k, \omega ; X_{30}\right) \tag{H-25}
\end{align*}
$$

and

$$
\begin{equation*}
\left.\phi_{E}\left(k, \omega ; X_{30}\right) \propto<B\left(k, \omega ; X_{30}\right) B^{*}\left(k, \omega ; X_{30}\right)\right\rangle \tag{H-26}
\end{equation*}
$$

The quasi-Lagrangian time auto correlation for stationary turbulence with homogeneity in the $x$-direction can be developed by a combination of Equations ( $\mathrm{H}-18$ ), ( $\mathrm{H}-23$ ) and ( $\mathrm{H}-25$ ) as follows:

$$
\begin{align*}
<v_{1}^{\prime}\left(t ; X_{30}\right) v_{1}^{\prime}\left(t+\tau ; X_{30}\right)>= & \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \phi_{E}\left(k, \omega ; X_{30}\right) \\
& e^{-i\left(k \bar{u}_{1}-\omega\right) \tau} d k d \omega
\end{align*}
$$

The LHS of Equation (H-27) must be independent of time because, due to stationarity the RHS is not a function of time. Thus,

$$
\begin{equation*}
\left\langle v_{1}^{\prime}\left(t ; X_{30}\right) v_{1}^{\prime}\left(t+\tau ; X_{30}\right)>\longrightarrow H_{L}\left(\tau, X_{30}\right)\right. \tag{H-28}
\end{equation*}
$$

Thus the quasi-Lagrangian time auto correlation function for stationary turbulence, with $x_{1}$-direction homogeneity, can be expressed as:

$$
\begin{equation*}
H_{L}\left(\tau ; X_{30}\right)=\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \phi_{E}\left(k, \omega ; X_{30}\right) e^{-i\left(k \bar{u}_{1}-\omega\right) \tau} d k d \omega \tag{H-29}
\end{equation*}
$$

Equation (H-29) can be cast in a more convenient form by means of a coordinate transformation where

$$
\left.\begin{array}{l}
\mathrm{K}=\mathrm{k}  \tag{H-30}\\
\Omega=k \bar{u}_{1}-\omega
\end{array}\right\}
$$

The quantity ( $-\Omega$ ) is the doppler frequency observed in a coordinate system moving with a velocity $\bar{u}_{1}$. In $K, \Omega$ - space Equation (H-29) becomes

$$
\begin{align*}
H_{L}\left(\tau ; X_{30}\right) & =\int_{-\infty}^{\infty} \int_{\infty}^{-\infty} \phi_{E}\left(K, K \bar{u}_{1}-\Omega ; X_{30}\right) e^{-i \Omega \tau}\left|\begin{array}{cc}
\frac{\partial k}{\partial K} & \frac{\partial k}{\partial \Omega} \\
\frac{\partial \omega}{\partial K} & \left.\frac{\partial \omega}{\partial \Omega} \right\rvert\, \\
\end{array}\right| \\
& =\int_{-\infty}^{\infty} \int_{+\infty}^{-\infty} \phi_{E}\left(K, K \bar{u}_{1}-\Omega ; X_{30}\right) e^{-i \Omega \tau}\left|\begin{array}{cc}
1 & 0 \\
\bar{u}_{1} & -1
\end{array}\right| d K d \Omega \\
& =\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \phi_{E}\left(K, K \bar{u}_{1}-\Omega ; X_{30}\right) e^{-i \Omega \tau} d K d \Omega \tag{II-31}
\end{align*}
$$

At the same time, based on generalized Fourier integral theory,

$$
\begin{equation*}
H_{L}\left(\tau ; X_{30}\right)=\int_{-\infty}^{\infty} \Psi_{L}\left(\Omega ; X_{30}\right) e^{-i \Omega \tau} d \Omega \tag{H-32}
\end{equation*}
$$

where $\Psi\left(\Omega ; \mathrm{X}_{30}\right)$ is the quasi-Lagrangian time power spectrum. Thus by comparison of Equations (H-31) and (H-32),

$$
\begin{equation*}
\Psi_{L}\left(\Omega, X_{30}\right)=\int_{-\infty}^{\infty} \phi_{E}\left(K, K \bar{u}_{1}-\Omega ; X_{30}\right) d K \tag{H-33}
\end{equation*}
$$

Notice should be taken that Equation (H-31) represents a relationship between the quasi-Lagrangian time auto correlation function and the Eulerian space-time power spectrum for stationary turbu-: lence with $x$-direction homogeneity, while Equation (H-33) relates the quasi-Lagrangian time power spectrum with the same Eulerian space-time power spectrum. Both relations are based on firstorder perturbation theory.

The true significance of Equations (H-31) and (H-33) can be ascertained by applying them to certain situations involving both nondispersive and dispersive media. First, in a nondispersive
media Taylor's hypothesis holds and thus,

$$
\omega \doteq k \bar{u}_{1}
$$

or

$$
\Omega=0
$$

For this case Equation (H-33) becomes

$$
\begin{align*}
\Psi_{L(T A Y L O R)}\left(\Omega, \mathrm{X}_{30}\right) & =\int_{-\infty}^{\infty} \phi_{\mathrm{E}(\text { TAYLOR })}\left(\mathrm{K}, \mathrm{~K} \bar{u}_{1}-\Omega ; \mathrm{X}_{30}\right) \mathrm{dK} \\
& =\int_{-\infty}^{\infty} \Phi_{\mathrm{E}(\mathrm{TAYLOR})}\left(\mathrm{K} ; \mathrm{X}_{30}\right) \delta(\Omega) \mathrm{dK} \\
& =\delta(\Omega) \int_{-\infty}^{\infty} \Phi_{E(T A Y L O R)}\left(\mathrm{K} ; \mathrm{X}_{30}\right) \mathrm{dK}
\end{align*}
$$

where $\Phi_{E}\left(K, X_{30}\right)$ is the Eulerian space power spectrum Equation (H-36) indicates that the quasi-Lagrangian time spectrum based on Taylor's hypothesis is simply a spike at $\Omega=0$. A combination of Equations ( $\mathrm{H}-31$ ) and ( $\mathrm{H}-36$ ) yields

$$
\begin{align*}
\mathrm{H}_{\mathrm{L}(\text { TAYLOR })}\left(\tau, \mathrm{X}_{30}\right) & =\int_{-\infty}^{\infty} \delta(\Omega) \int_{-\infty}^{\infty} \Phi_{\mathrm{E}(\mathrm{TAYLOR})}\left(\mathrm{K}_{;} \mathrm{X}_{30}\right) \mathrm{dK} \mathrm{e}^{-\mathrm{i} \Omega \tau} \mathrm{~d} \Omega \\
& =\int_{-\infty}^{\infty} \Phi_{\mathrm{E}(\mathrm{TAYLOR})}\left(\mathrm{K}_{\mathrm{i}} \mathrm{X}_{30}\right) \mathrm{dK} \tag{H-37}
\end{align*}
$$

Notice should be taken that the RHS of Equation (H-37) is independent of $\tau$. Thus the quasi-Lagrangian time auto correlation function is independent of $\tau$ and

$$
\begin{equation*}
\mathrm{H}_{\mathrm{L}(\text { TAYLOR })}\left(\tau, \mathrm{X}_{30}\right)=\mathrm{H}_{\mathrm{L}(\mathrm{TAYLOR)}}\left(\mathrm{X}_{30}\right) \tag{H-38}
\end{equation*}
$$

Equation (H-38) combined with Equation (H-28) indicates that

$$
\left.\begin{array}{rl}
\mathrm{H}_{\mathrm{L}(\text { TAYLOR })}\left(\mathrm{X}_{30}\right) & =\left\langle\mathrm{v}_{1}^{\prime}\left(\mathrm{X}_{30}\right) \quad \mathrm{v}_{1}^{\prime} \quad\left(\mathrm{X}_{30}\right)\right.
\end{array}\right\rangle
$$

Based on Equation (H-39) the quasi-Lagrangian time auto correlation function (for the case of Taylor's Hypothesis), for the balloon velocity component $v_{1}^{\prime}\left(t, X_{30}\right)$, equals the variance of the same velocity component. The latter in turn equals the variance of the $x_{1}$ component of the wind velocity. These relations are based on the first-order perturbation analysis with the assumption of a perfectly responsive balloon (in the $x$-direction) with stationary turbulence which is homogeneous in the x-direction.

For the case of a dispersive media, Taylor's hypothesis does not hold. Instead

$$
\begin{equation*}
\omega=\bar{u}_{1} \quad k+F,(k) \tag{H-40}
\end{equation*}
$$

or

$$
\begin{equation*}
\Omega=-F(K) \tag{H-41}
\end{equation*}
$$

The inverse of Equation (H-41) proves more useful and can be written

$$
\begin{equation*}
\mathbf{K}=\mathbf{f}(\Omega) \tag{H-42}
\end{equation*}
$$

A combination of Equations (H-33) and (H-42) yields
$\Psi_{L}\left(\right.$ DISPERSIVE) $\left(\Omega ; X_{30}\right)=\int_{\infty}^{\infty} \phi_{E(D I S P E R S I V E)}\left(K, K \bar{u}_{1}-\Omega ; \mathrm{X}_{30}\right) \mathrm{dK}$

$$
\begin{align*}
& =\int_{-\infty}^{\infty} \Phi{ }_{E(\text { DISPERSIVE })}\left(\mathrm{K} ; \mathrm{X}_{30}\right) \delta[\mathrm{f}(\Omega)-\mathrm{K}] \mathrm{dK} \\
& =\Phi_{\mathrm{E}(\text { DISPERSIVE })}\left[\mathrm{f}(\Omega) ; \mathrm{X}_{30}\right] \tag{H-43}
\end{align*}
$$

Thus in a dispersive media the quasi-Lagrangian time power spectrum can be related to the corresponding Eulerian spatial power spectrum if the function $f(\Omega)$ is known. Furthermore, the quasi-Lagrangian time auto correlation function can be related to the same Eulerian spatial power spectrum by a conbination of Equations (H-32) and (H-43) as follows:

$$
\begin{equation*}
H_{L}\left(\tau ; X_{30}\right)=\int_{-\infty}^{\infty} \Phi_{E(\text { DISPERSIVE })}\left[f(\Omega) ; X_{30}\right] e^{-i \Omega \tau} d \Omega \tag{H-44}
\end{equation*}
$$

For dispersive Rossby waves the phase velocity $c$ is given by the relation

$$
\begin{equation*}
c=\bar{u}_{1}-\beta / k^{2} \tag{H-45}
\end{equation*}
$$

By definition

$$
\begin{equation*}
c=\omega / \mathbf{k} \tag{H-46}
\end{equation*}
$$

and thus

$$
\begin{equation*}
\omega=\bar{u}_{1} k-\beta / \mathbf{k} \tag{H-47}
\end{equation*}
$$

or

$$
\begin{equation*}
\Omega=\beta / \mathbf{k} \tag{H-48}
\end{equation*}
$$

Thus for a Rossby wave, based on Equation (H-42) and (H-48),

$$
\begin{equation*}
f_{(\text {ROSSBY })}(\Omega)=\beta / \Omega \tag{H-49}
\end{equation*}
$$

Then

$$
\Psi_{L(\operatorname{ROSSBY})}\left(\Omega ; \mathrm{X}_{30}\right)=\Phi_{\mathrm{E}(\text { ROSSBY })}\left(B / \Omega ; \mathrm{X}_{30}\right)
$$

$$
(H-50)
$$

The relation between $\Phi$ ( $E$ (ROSSBY) $\left(K_{i} X_{30}\right)$ and $K$ is known to be of the form

$$
\Phi \cdot E(\text { ROSSBY })\left(K ; X_{30}\right) \propto K^{P_{1}}
$$

where

$$
P_{1}<0
$$

Therefore

$$
\begin{equation*}
\Psi_{: L(\text { ROSSBY })}\left(\Omega, \mathrm{X}_{30}\right) \propto \Omega^{-\mathrm{P}_{1}} \tag{H-52}
\end{equation*}
$$

For dispersive gravity waves,

$$
\begin{equation*}
\omega=\bar{u}_{1} k \pm \sqrt{g k} \tag{H-53}
\end{equation*}
$$

or

$$
\begin{equation*}
\Omega=\mp \sqrt{g k} \tag{H-54}
\end{equation*}
$$

Thus, based on Equation ( $\mathrm{H}-42$ ) and ( $\mathrm{H}-54$ ),

$$
\begin{equation*}
f_{(\text {GRAVITY })}(\Omega)=\Omega^{2} / \mathrm{g} \tag{H-55}
\end{equation*}
$$

In this case

$$
\begin{equation*}
\Psi_{L(G R A V I T Y)}\left(\Omega ; X_{30}\right)=\Phi \cdot E(\text { GRAVITY })\left(\Omega^{2} / \mathrm{g}, \mathrm{X}_{30}\right) \tag{H-56}
\end{equation*}
$$

The relation between $\Phi{ }_{E}$ (GRAVITY) $\left(K, X_{30}\right)$ and $K$ is of the form

$$
\begin{equation*}
{ }^{\Phi} \mathrm{E}_{(\text {GRAVITY })}\left(\mathrm{K}, \mathrm{X}_{30}\right) \propto K^{\mathrm{P}_{2}} \tag{H-57}
\end{equation*}
$$

where

$$
\mathbf{P}_{\mathbf{2}}<0
$$

Therefore


Rossby waves possess long wave lengths and thus small wave numbers while gravity waves have relatively short wave lengths and hence larger wave numbers. A plot of $\Phi_{E}\left(K ; X_{30}\right)$ for these two types of waves is given in Figure H-2. The corresponding plot of $\Psi_{L}\left(\Omega ; X_{30}\right)$ is shown in Figure $H-3$.


Figure H-2. Eulerian Space Power Spectra for Rossby and Gravity Waves


Figure H-3. Lagrangian Time Power Spectra for Rossby and Gravity Waves

## NOTES ON SPACE-TIME SPECTRUM $\phi_{E}\left(k, \omega ; X_{30}\right)$

The function $\phi_{E}\left(k, \omega ; X_{30}\right)$ represents the Eulerian Space-time spectral density at altitude $X_{30}$ of turbulent eddy with wave number $k$ and frequency $\omega$. If no relation between $k$ and $\omega$ exist, the general variation of $\phi$ with $k$ and $\omega$ might be pictured as shown in Figure I-1.


Figure I-1. General Eulerian Space-Time Power Spectrum

If, however, $k$ and $\omega$ are related according to Taylor's hypothesis,

$$
\begin{equation*}
\omega=\mathrm{k} \overline{\mathrm{u}}_{1} \tag{I-1}
\end{equation*}
$$

$\phi_{E(T A Y L O R),}$ as a function of $k$ and $\omega$, appears as shown in Figure I-2.


Figure I-2. Eulerian Space-Time Power Spectrum According to Taylor's Hypothesis

Notice should be taken that, with increasing $\bar{u}_{1}$, the plane containing $\phi_{E(T A Y L O R)}\left(k, k \bar{u}_{1} ; X_{30}\right)$ rotates CCW.

For the case of dispersive media,
$\omega=k \bar{u}_{1}+F(k)$
For this case, $\phi_{E}$ as a function of $k$ and $\omega$ appears as shown in Figure I-3.


Figure I-3. Eulerian Space-Time Power Spectrum for Dispersive Media

The preceding figure represents the general concept of the spectral density function for a dispersive media. Two specific examples are useful. For a Rossby wave,

$$
\begin{equation*}
\omega=k \bar{u}_{1}-\frac{\beta}{k} \tag{I-3}
\end{equation*}
$$

Although Rossby waves are limited to relatively low frequencies. and thus low wave numbers, it is beneficial to picture the variation of $\phi_{E}$ (ROSSBY) with $k$ and $\omega$ over a wide range of values of $k$ and $\omega$ as shown in Figure 1 -4.


Figure I-4. Eulerian Space-Time Power Spectrum for Rossby Waves

Notice should be taken in the preceding figure that the heavily shaded portion of the plots of $\phi_{E}$ (ROSSBY) $\left(k, k \bar{u}_{1}-\beta / k ; X_{30}\right)$ represents the regions where Rossby waves would most likely be present.

For gravity waves

$$
\begin{equation*}
\omega=\bar{u}_{1} k \pm \sqrt{\mathrm{gk}} \tag{I-4}
\end{equation*}
$$

Gravity waves normally occur at relatively high values of $k$, but as before it is beneficial to plot the curve over a range of values of both $k$ and $\omega$. The result is as shown in Figure $\mathrm{I}-5$.


Figure I-5. Eulerian Space-Time Power Spectrum for Gravity Waves

As before the more heavily shaded portions of the plot indicates the part of the spectrum in which gravity waves most likely will occur.

## APPENDIX J

Notes on SpaceTime Spectrum $\psi_{L}\left(K, \Omega ; X_{30}\right)$
It is desirable to introduce a two-dimensional spacetime spectrum $\psi_{L}\left(K, \Omega ; X_{30}\right)$ which satisfies the relation

$$
\begin{equation*}
\psi_{\mathrm{L}}\left(\Omega ; \mathrm{X}_{30}\right)=\int_{\infty}^{\infty} \psi_{\mathrm{L}}\left(\mathrm{~K}, \Omega: \mathrm{X}_{30}\right) \mathrm{dK} \tag{J-1}
\end{equation*}
$$

The function $\psi_{L}\left(K,-\Omega ; X_{30}\right)$ is the counterpart of $\phi_{E}\left(k, \omega ; X_{30}\right)$. Each of the five figures given in Appendix $I$ could be redrawn to represent $\psi_{L}\left(K, \Omega ; X_{30}\right)$ as a function of $K, \Omega$. For the sake of brevity only the three specific cases, illustrated by Figures I-2, I-4 and I-5, will be developed.

For the case involving Taylor's hypothesis, $\Omega=0$
$\psi_{L}$ as a function of $K$ and $\Omega$ is shown in Figure $J-1$.


Figure J-1. Lagrangian Space-Time Power Spectrum According to Taylor's Hypothesis

A comparison of Figures $I-2$ and $J-1$ reveals that as $\dot{\mathbf{u}}_{1}$ approaches zero, $\psi \cdot$ L (TAYLOR ( $\mathrm{K},-\Omega ; \mathrm{X}_{30}$ ) approaches $\phi_{\mathrm{E}}$ (TAYLOR) ( $k, \omega ; X_{30}$ ).

For the case involving the Rossby wave,

$$
\begin{equation*}
\Omega=\beta / K \tag{J-3}
\end{equation*}
$$

or

$$
\begin{equation*}
K=\beta / \Omega \tag{J-4}
\end{equation*}
$$

The variation of $\psi_{L}$ (ROSSBY) $\left(K, \Omega ; X_{30}\right)$ with $K$ and $\Omega$ is shown in Figure J-2. As before the more heavily shaded regions andicate


Figure J-2. Lagrangian Space-Time Power Spectrum for Rossby Waves
that portion of the spectrum where Rossby waves are more likely to occur. A comparison of Figures $\mathrm{I}-4$ and $\mathrm{J}-2$ indicates that as $\overline{\mathrm{u}}_{1}$ approaches zero, $\psi_{L(R O S S B Y)}\left(K,-\Omega ; X_{30}\right)$ approaches $\phi_{E}($ ROSSBY $)$ (k, $\omega ; X_{30}$ )

In addition, inspection of the shaded portion of Figure $\mathbf{J}-2$ reveals that in that portion of the spectrum where Rossby waves occur, $\psi_{\text {L (ROSSBY) }}$ increases with increasing $\Omega$ while, as, shown in Figure $I-4, \phi_{E}$ (ROSSBY) decreases with increasing k. This provides a slightly better understanding of the relationship between $\Phi^{\Phi}$ E(ROSSBY) and $\Psi_{L}$ (ROSSBY) which was originally presented in Appendix H .

For the case involving gravity waves,

$$
\begin{equation*}
\Omega=\mp \sqrt{\mathrm{gK}} \tag{J-5}
\end{equation*}
$$

and

$$
\begin{equation*}
K=\frac{\Omega^{2}}{g} \tag{J-6}
\end{equation*}
$$

The variation of $\psi_{L}(G R A V I T Y)\left(k ; \Omega ; X_{30}\right)$ with $K$ and $\Omega$ is shown in Figure J-3.
The more heavily shaded portion of the spectrum represents the region in which gravity waves normally occur. Comparison of Figures $\mathrm{I}-5$ and $\mathrm{J}-3$ reveals, that as $\bar{u}_{1}$ approaches zero, $\dot{\psi}$ L(GRAVITY) ( $\mathrm{K}-\Omega$; $\mathrm{X}_{30}$ ) approaches $\phi_{\mathrm{E}(\mathrm{GRAVITY})}\left(\mathrm{k}, \omega ; \mathrm{X}_{30}\right.$ ). Furthermore, although difficult to determine quantitatively from Figure $I-5$ and $J-3$, it is possible to observe qualitatively that $\psi_{\text {L (GRAVITY) }}$ decreases more rapidly with increasing $\Omega$ than $\phi_{E(G R A V I T Y)}$ decreases with increasing $k$.


Figure J-3. Lagrangian Space-Time Power Spectrum for Gravity Waves

Balloon is written in FORTRAN IV for the Univac 1108 Computer. The listing which follows represents the current form of the program.

```
        COMMUN/CONS/PI.D.SIGMA.AP,M. VOL,
        *MUREF,TEMREF, TEMPI,TEMLAP,X3N,R,GSRTL,G(3),PO,X33
            COMMON/TEKMS/FURAG(3),FAP1(3),FAP2(3),FBUUY(3),FGASS(3),
        *MA,NU,MU,RHO,TEMP.X(3),FACTOR,KE
            COMMUNI/VELOC/U(3),V(3).UMAG.VMAG.MAGDIF
            COMMON/INTL/K(3),THETA(3),OMEGA,UG(3),A.B.C
            DIMENSION FU(3),FV(3),VOU(3)
            DIMENSION XO(5),XIN(7)
            UIMENSION WRA(SO,11),WRE(50.6),WRC(50.17)
            DIMEIVSION BCDX(12).RCDYI(12),BCOY2(12),BCDY3(17),FLDY1(12),FLOYZ(
            112),FLDY3(12)
            DIMENSION PT(5NO),PX(50n), PY(500), PZ(500),PYI(500),PYZ(500),PYJ(SO
            10),PZ1(500), PZ2(5CO),PZ3(500)
            EQUIVALEINCE(K(1),K1),(K(2),K2),(K(3),K3),(THETA(1),THETAA),(THETA(
            12),THETAB),(THETA(3):THETAC)
            REAL MOL,K
            REAL MA,NU,MU,MUREF
            KEAL MAGOIF
            NAMELIST/INPUT/G,X,K,THETA,UB,V,A.OMEGA,SIGMA.N,MUREF,TEMREF,T,
            -TLIM,UELTAT,TEMPD,PO,TEMLAP,R,X30
            PI=3.141542654
            READ(S,7UL2) NNN
            READ(5,7US\) BCDX,RCDY1,BCDY2.BCUY3,FLOY1;FLDY`,FLUY3
            KEAD(5,10U) G.X,K.THETA.UB,V
            KEAO(S,ICU) A.OMEGA.SIGMA,D,MUREF.TEMREF,T,TLIM,UELTAT,
            -TEMPU.PO.TEMLAP,R,X3U
            IGC FORMAT(8E10.3)
7UOI FOKMAT(12AG,8X)
7CO2 FORMAT(12)
    0O 20 I=1.3
    FBASS(I)=0.
20 V(I) = UB(I)
    DGTOKU=PI/18C.
    TMETAI=THETAA*IGTOHD
    THETAZ=THETAB*DGTORD
    THETA3=THETAC*UGTORD
    IF(THETR&.EQ.O.ANU.THETAZ.EQ.C.) GO TO &
    C=-A*K\*(SIN(THETA1)-CUS(THETA1)*TAN(THETA2))/K3/(SIN(THETA3)
    * -COS(THETA3)*TAN(THETAZ))
    B=-A*K1*(SIN(TMETAI)-COS(THETA1)*TAN(THETA3))/K2/(SIN(THETAZ)
    * -COS(THETA2)*TAN(theTA3))
```

```
    GO TO 2
    1 B=-A-K1*.5/K2
    C=-A*K1*.S/K3
    2 CONTINUE
    WRITE(6.9004) A.B.C
9004 FGKMAT(///1&X,1P3E/2.4)
    UCON:UB(1)/A
    DO 1UO\ LIEI.NNN
    KEAD(5,101) XO(2), XO(5).BCDX(11),HCOX(12),T,TIIM,GELTAT,IDT,IDS
    101 FOKMAT(2E10.3.10X,2A6.8X,3F5.0.215)
        TRF=T
    TRLIM= TLIM
    K(1)=XD(2)/D
    K(2) = K(1)
    K(3) =K(1)
    UMEGA= =O(5)\oplus\/D
    ETA=1.UE-3C
    DO 10 1=1.3
    K(I) = AMAXI(K(I).ETA)
    1O CONTINUE
    CALL GEOMET
    CALL PROPTY(X)
    GR=-G\3\
    GAM=GR/R/4*184E+7
    XU(1)=(12.*NU)/(A*D)
    XD(3)= = 6666667*GR*D*U*(GAM-TEMLAP)/(A*A*TEMPN)
    XD(4) = UCON
    WKITE(6,9015) ACDX(11),BCDX(12),(XO(L2),L2=1.5)
    WRITE(6,INPUT)
```




```
    CALL IDENT (8,1)
    DO 1002 LS = 1.IDS
    I0=0
    IDX = D
    5 CALL INTEG(T,V.X,DELTAT,IDT)
    DO 200 I = 1.3
    Fu(I)=U(I)/A
    FV(I)=V(I)/A
    VOU(I) = V(I)/U(I)
200 CONTINUE
    AKT = A@K(1)%T
    DZ=x(3)=x3n
    10=10+1
    IOX = IDX + 1
    PX(IOX)=x(1)
    PY(IOX)=X(2)
    PZ(IUX)=DZ
    PYI(IUX)=FU(1)
    PY2(IUX)=FU(2)
    PY3(IDX) =FU(3)
    PZ\(\ux) =FV(1)
    PZ2(10x) = FV(2)
    PZ3(10X)=FV(3)
    WRA(ID,I)=T
    WRB(IU,I)= T
```

```
    HRC(ID,1)=T
    WRA(10,2) = AKT
    WRB(&U,2)=AKT
    WRC(10.2; = AKT
    PT(IDX) = AKT
    WRE(ID,3) = X(1)
    WRB(10,4)=X(2)
    WRE(10.5)=DZ
    WRB(ID,G)=RE
    DO 300 1=1:3
    WHA(IU,I+2)=FU(I)
    WRA(IU,I+5)=FV(I)
    WRA(ID,I+B) = VDU(I)
    WRC(IU,I+2)=FDRAG(I)
    WRC(ID,It5)=FAPI(I)
    WRC(IU,I+B)=FAP2(I)
    WKC(IU:I+11)=FBUOY(I)
    WRC(IU.I+14)=FBASS(I)
    300 CONTINUE
    1F(IO - 50) 325,302.302
    302 CONTINUE
    *RITEE(6,9002)
    NKITE(6.9J03) ((NRA(I.J),J=1,11),1=1.50)
    WKITE(6,90UB)
    WRITE(6.9009) ((WRA(1,J),J=1.6).1=1:50)
    WKITE(6.9006)
    HRITE(6.9007) ((WRC(I.J):J=1.17):t=1.5J)
9002 FORMATI'I TIME SCALED TIME SCALED ATMOSPHFRIC WIND
    ISCALED BALLOON VELOCITIES VELOCITY RATIOSP//I
9003 FORMAT(1X,OPF8.2.1PIOEI1.3)
```



```
    1'//)
9009 FORMAT(IX.GPFO.2,1P5E11.3)
9006 FORMATI'I TIME SCALED TIME FDRAG/F゙RUOY
    1FAPI/FBASS
        FAp%'//)
9007 FORMAT(1X,OPFB.2.1PIUEI1.3/20X.1PGEII.3)
    10=0
    305 CONTINUE
    IF(T.LT.TLIM) GO TO 5
    XL = A*K(1)*TRF
    XR=A*K(1)*TLIM
    YB}=8.
    YT=11.2
    CALL WUIK3L(-1,XL,XR,YB,YT,1H+,BCOX,BCOYI,OIDX,PT,PY1)
    CALL WUIK3L(C,XL,XR,YB,YT,IHO,BCUX,ACDYI,=IDX,PT,PZI)
    YB=-1.5
    YT=1.5
    CALL WUIK3L(-1,XL,XR,YB,YT,1H+,ACDX,BCDYZ,-1DDX,PT,PYZ)
    CALL GUIK3L(O,XL,XR,YB,YT,1HO,BCUX,BCDY2,-IDX,FT,PZ2)
    CALL WUIK3L(-1.XL,XR,YB,YT,1H+,ACOX,BCOY3,-10X,PT,PY3)
    CALL QUIK3L(O,XL,XR,YB,YT,IHO,BCDX,BCDY3,=IDX,PT,PZ3)
    CALL WUIK3VI-1,1HO.BCDX,FLDY2,-IDX,PT,PYI
    CALL WUIK3V(-1,1HO,RCDX,FLOY3.-IUX,PT,PZ)
    TRF=T
    TLIM= TLIM + TRLIM
lCO2 CONTINUE
```

```
    CALL ENDJOB
    T=0.
    X(1)=0.
    X(2)=0.
    x(3)=x30
    V(1) = USं(1)
    V(2) = UB(2)
    V(3)=U日(3)
1001 CONTINUE
    STUP
    ENO
    SUBROUTINE ACCEL(T.VI,XI,OVDT,DELTAT,S)
    COMMON/CONS/PI.D,SIGMA.AP,M,
                                    VOL:
    *MUREF,TEMREF, TEMPO.TEMLAP,X3O,R,GSRTL,G(3),PO,X33
    COMMON/TERMS/FURAG(3),FAP1(3).FAP2(1),FBUOY(3).FBASS(3),
    *MA,NU,MU,RHO,TEMP, X(3).FACTOR
    COMMON/VELOC/U(3),V(3),UHAG,VMAG:MAGDIF
    REAL M,L,K
    REAL MA,NU,MU,MUREF
    REAL MAGDIF
    REAL MEFF
    DIMENSION VI(3),XI(3).OVDT(3)
    CALL PROPTY(XI)
    CALL BUOYNT
    CALL APARNT(T:XI,VI)
    VMAG=SGRT(VI(1)**2+VI(2)**2+VI(3)**)
    UMAG=SGRT(U(1)**2+U(2)**2+U(3)**2)
    SUM=0.
    DO 5 I=1.3
5 SUM=SUM+1VI(I)-U(I))**2
    MAGDIF=SORT(SUM)
    CALL ORAG(VI)
    B=FACTOR*SGRT(UELTAT*S)
    MEFF=M+MA
    DO 1ú l =1.3
    DVOT(I)=(FDRAG(I)+FAPI(I)+FAP2(I)+FGUOY(I)+FBACS(I)})/(MEFF+B
10 CONTINUE
    RETURM
    END
```

```
        SUGRUUTINE APARNT(T.XI.VI)
        DIMENSION XI(3),VI(3)
    THIS KOUTINE CALCULATE FORCES RFSULTING FROM APPAHENT MASS AND FLUID
        COMMUN/CONS/PI.D.SIGMA.AP.M. VUL.
    *MUREF,TEMREF, TEMPO.TEMLAP,X3N,R,GSRTL,G131,PO,X33
        COMMON/TEKMS/FORAG(3),FAP1(3),FAP2(3) ,FBUOY(3),FBASS(3).
    #MA,NU,MU,RHO,TEMP,X(3).FACTOR
        COMMON/VELOC/U(3),V(3).UMAG,VMAG,MAGDIF
        COMMON/DEEV/PDUDX(3.3).PDUDT(3)
        COMMON/TIME/N
        DIMENSION DUDTF(3)
        REAL MgL.K
        REAL MA,NUBMU,MUREF
    REAL MAPMRS
    REAL MAGDIF
    MAPMRS=MA+M*RHU/SIGMA
    XI3 = XI(3)- X30
    CALL POTFLU(T,XI(1),XI(2),XI3)
    DO 10 1=1.3
    UDUDX=DVAL(U.0..1)
    DUDTF(I)=PDUDT(I)+UDUDX
    FAP1(I)=MAPMRS*DUDTF(I)
    FAP2(1) = MA*DVAL(VI,U.I)
IO CONTINUE
    RETURN
    END
```

    SUBROUTINE BUOYNT
    COMMON/CONS/PI.D,SIGMA.AP.M. VUL,
    -MUREF,TEMKEF. TEMPO,TEMLAP, X3n,R,GSRTL,G(3),PO,X33
    COMMON/TERMS/FURAG(3), FAP1(3), FAP2(3), FBUOY(3). FDASS(3).
    -MA,NU,MU,RHO,TEMP, X(3),FACTOR
    C
REAL MOL,K
REAL MA,NU,MU
REAL MROSIG
MROSIG=M*(1.-RHO/SIGMA)
$00101=1,3$
FBUOY(I)=G(I)*MROSIG
RETURN
END

```
    SUBRUUTINE DRAGIVTI
    COMMON/CONS/PI.DISIGMA.AP.M.
                VUL,
    #MUREF.TEMREF. TEMPO.TEMLAP,X30.R,GSRTL,G(3),PO,X33
    COMMON/TEKMS/FURAG(3),FAP1(3).FAP2(3),FBUOY(3).FBASS(3),
    *MA,NU,MU,RHO,TEMP,X(3),FACTOR,RE
        COMMON/VELOC/U(3),V(3),UMAG.VMAG.MAGDIF
        DIMENSION RTABL(8).REN(B)
        DIMENSION VI(3)
        REAL MOLOK
        REAL MA,NU,MU,MUREF
        REAL MAGOIF
        DATA RTABL/7.74066.5.29a3.3.13549:1.5:.079531.0.693147%
    *-1.23787.-.544727/.NREN/B/.EPS/.01/,REN/=4.6OG%,-2.3026.0..0
    *2.3J26.4.6052.6.9n79.9.2103.11.5124/
C
    RE= MAGOIFHr,/NU
    REZ = RE + 1.SOE=3n
    CO = 24./REZ + 0.50
    VI1=V1(1)
    V12=vi(2)
    VI3=V1(3)
    HALFRO=.5%RHO
    CDAPMD=CD@AP*MAGDIF
    HACU=HALFRO*CDAPMO
    OO 1U I=1.3
    FORAG(I)=HACD*(U(I)-VI(I))
10 CUNTINUE
    RETUKN
    ENO
```

    FUNCTIUN UVALIH.Z.EII
    COMMON/DEKV/PDUDX(3.3).PDUDT(3)
    DIMENSION (3). Z(3)
    DVALEO.
    DO \(10 \mathrm{~J}=1.3\)
    10 DVAL=UVAL+(W(J)-Z(J)) ©PDUDX(I.J)
RETURN
ENO

```
        SUBROUTINE GEOMET
        THIS KOUTINE CALCULATES TIME INDEPENDEIVT GEOMETRIC VALUES
        COMHION/CONS/PI.DISIGMA.AP,M, VOL,
        OMUREF,TEMKEF. TEMPO,TEMLAP,X3N,R.GSKTL,G(3),PO,X3.3
            REAL MILIK,MUREF
            VOL=PI*D**3/6.
            M=VOL.SIGMA
                APEPI*D**2/4.0
            IF(TEMLAP) 10.20.10
10 CONTINUE
            GSRTL=ABS(G(3)//(R*TEMLAP)/4*184E+7
            GO TO 30
20 COINTINUE
                GSRTLEABS(G(3)//(K#TEMPO )/4.184E+7
30 CONTINUE
    RETURN
    ENO
SUBROUTINE INTEG(T.V.X.NELTAT.IDTI
OIMENSION X(3),V(3), OVI(3), DV2(3). OV4(3).DV5(3).
- VI(3).XI(3).DVDT(3).UV3(3)
DIMENSIOH OX1(3), DX2(3), DX3(3), DX4(3), OX5(3), E(3), EX(3)
COMMON/TIME/N
DATA ACCUR/I•/
UO 2UOO LIEI,IUT
CALL ACCELIT,V.X:OVOT, DFLTAT,I•I
4 DO \(5 \mathrm{I}=1.3\)
DV1(1) =DELTAT@UVDT(I)/3.
OXI(1) =DELTATEV(I)/3.
VI(I) =V(I)+OVI(I)
\(5 \times 1(1)=X(1)+D \times 1(1)\)
CALL ACCELIT+DELTAT/3..VI.XI.DVDT.DELTAT, © 333333333 )
DO \(61=1.3\)
DV2(I) =DELTATOOVDT(I)/3.
\(0 \times 2(1)=D E L T A T+V I(1) / 3\).
```




```
CALL ACCEL(T+DELTAT/3..VI.XI.DVDT.DELTAT... 333333333 )
DO 7 LE1.3
DV3(1)=DELTATOUVDT(I)/3.
D×3(I) =DELTAT*VI(I)/3.
V1(1) =V(1)+0.375*0v1(1)+1.12500v3(1)
```



```
CALL ACCEL(T+DELTAT/2•,VI,XI,OVQT, OELTAT:.5)
DO 8 1 \(=1.3\)
DV4(1)=DELTAT*OVDT(1)/3.
DX4(I) =DELTATeV1(I)/3.
VI(I) \(=\) V(I) +1.5*DVi(i)=4.5*DV3(1)+6.0*DV4(1)
```

    \(8 \times 1(1)=X(1)+1.5 * D X_{1}(1)-4.5 * 0 \times 3(1)+6 . n \oplus 0 \times 4(1)\)
    CALL ACCEL (T+DELTAT,VI,XI, OVDT, DELTAT, I。)
    TEST=0.0
    DO \(9 \quad 1=1.3\)
    DVS(1) =DELTAT OOVDT(I)/3.
    DX5(I) =DELTAT*VI(I)/3.
    

9 TEST=AMAXI(TEST.ABG(E(I)).ABS(EX(I)))
IF(TEST.LT.ACCUR) GO TO 10
WRITE (6,1000)
100C FORMATIIOX,38H***ACCURACY TEST FAILFD IN INTEGRATIONI
10 DO $111=1.3$

$11 \times(I)=X(I)+050 \times 1(I)+2 \cdot 0 \times 4(1)+\infty 5 * 0 \times 5(1)$
T=T+DELTAT
2000 CONTINUE
RETURN
END
REAL FUNCTION MREF(TEMP, MUREF, TEMREF)
REAL MUREF
A=MUREF © (TEMPITEMKEFI** 1.5
$8=1.505$ ©TEMREF
C=TEMP $=505$-TEMREF
MREF=A*B/C
RETURN
ENO

```
SUDRUUTINE POTFLU(T,X,Y,Z)
COMMON/INTL/K1,K2,K3,THETAI, THETA2,THETA3,OMEGA,U口,VB,WB,A,B,C
COMAON/DERV/DUDX,OVDX, DWDX, DUDY, UVDY, DWDY, OUDZ, DVUZ, DWUZ, OUDT,
- DVUT:UWDT
    COMMON/VELOC/U,V,*.DUMY(6)
    REAL LI,L2,L3,K1:K2,K3
    \(X I=K 1 * X+K 2 * Y+K 3 * Z\)
    \(X I M O M T=X I-O M E G A * T\)
    COSI=COS (XIMOMT+THFTA1)
    COS2=COS(XIMOMT + THETA2)
    COS \(3=\operatorname{COS}(X I M O M T+T H E T A 3)\)
    \(U \approx U B+A+S I N(X I M O M T+T H E T A I)\)
    \(V=V \operatorname{Va}_{+}+\)SIN(XIMOMT+THETA2)
    \(W=W B+C\) SIN(XIMOMT+THETA3)
    DUDX=A*KIकCOSI
    OUOY=A \(-K 2 * \operatorname{COS} 1\)
    DUDZ \(=A\) AK \(3 * \operatorname{COS} 1\)
```

```
            DVUX=B*K1*COS2
            DVOY=甘*KZ*COS2
            DVUZ=B*K3*COS2
            DwOX=C*K1*COS3
            UWDY=C*K2*COS 3
            Dw口L=C*K3*COS3
            DUDT=-A*UMEGA*COSI
            DVUT=-B*OMEGA*COS2
            DWDT=-C*OMEGA*COS3
        20 CONTINUE
            KETURN
                            END
SUBROUTINE PROPTY(XI)
C THIS KOUTINE CALCULATES TEMPERATUFE ANU DENSITY FROM
C TABULATED FUNCTIONG OF ALTITUDE (X(3) UR ALT). DYNAMIC
C VISCOSITY.MU, AND KINEMATIC VISCOSITY,NU,ARE CALCULATEO.
C PRESSURE = PG = DYNES/CM**2
C DENSITY = RHO = GMS/C**3
        DIMENSION XI(3)
    COMMON/CONS/PI.D,SIGMA.AP.M, VUL.
    *MUREF.TEMREF. TEMPO.TEMLAP,X3N,R,TSRTLIG(3),PO,X33
    COMMON/TERMS/FURAG(3),FAPI(3),FAPZ(3),FRUOY(3).FBASS(3),
    *MA,NU,MU,RHO,TEMP.X(3).FACTOR
    REAL MOLOK
    REAL MA,NU,MU,PIUREF
    REAL MKEF
    TEMP=TEMPO-TEMLAP*(XI(3)-X3%)
    MU=HKEF(TEMP,MUREF.TEMREF)
1000 FORMAT(10X,5HTEMP=.E\O.4)
200C FOKMAT(1OX,3HMU=,E10.4)
    IF(TEMLAP) 1C.20.1n
    IO CONTINUE
        P=PC*(TEMP/TEMPCI**GSRTL
        GO TU 30
    20 CONTINUE
        P=PO*EXP(-GSRTL*(XI(3)-x30))
    3J CONTINUE
    RHO=P/(R*TEMP)/4-1&4E+7
    NUaMU/RHO
    MA#VOL*RHO*.5
1OO FOKMATI//IOX:IGHPROPTY VARIABLESI
```



```
    | 1OX, 3HMU=,E10.4/10X, 2HP=,E10.4/1OX,6HGSRTLE,EIO,4/
```



```
    RETURN
    ENO
```

The sample outputs which follow correspond to Blocks \#1, \#2 and \#3 Outputs which are described in Section 4.2. These outputs are for the most part labeled and thus are self-explanatory. Where three components of a vector are printed out, the sequence always corresponds to the order $x_{1}, x_{2}, x_{3}$.
L. 1 Block \#1, Output (Sample)

$$
1.0000+02 \quad 1.0000+02=1.0000+02
$$

L. 2 Block \#2 Output (Sample)

TEST CASETEST (1.1)
DIMENSIONLESS GROUPS

| N7 $=$ | 3.5914-44 |  |  |
| :---: | :---: | :---: | :---: |
| N8= | 8.1681-04 |  |  |
| N9 | 1.7317-03 |  |  |
| N10= | 1.0000+01 |  |  |
| N11: | 8.1681-03 |  |  |
| sinfut |  |  |  |
| $G$ | -00000000e +00, | .80003nodetru. | -.9806650nE + 03 |
| $x$ | - $000000000 \mathrm{E}+100$ | .00, 000000 coo. | . 1100000 OE + O7 |
| K | .62831538E-05, | .02831538E-05. | . $62831538 \mathrm{E}-05$ |
| THETA | - 00000000E+00. | . $12 \mathrm{aconcce}+\mathrm{O}^{\text {a }}$ | . $24000600 E+03$ |
| UH | -1000uSveereis. | .0000200Je + 0 O, | -0000030Ne +00 |
| $v$ | -10000000e+04, | - UU000ndoe +00. | . 000.00000e+00 |
| A | .10000000E+03 |  |  |
| OMEGA | .62831538E-02 |  |  |
| SIGMA | . $36149400 \mathrm{E}-03$ |  |  |
| 0 | -13000000E + 33 | ; |  |
| muref | $\therefore 17080000 \mathrm{E}-03$ | : |  |
| temkef | . $27315000 E+03$ |  |  |
| T | .00000000E + J0 |  |  |
| TLIM | -10000000E+05 |  |  |
| deltat | -2500U000E+01 |  |  |
| TEMPO | -21800000E + 123 |  |  |
| PO | .22619000E+0゙6 |  |  |
| temlap | -000G0000E+00 |  |  |
| $k$ | \% .68600000E-01 |  |  |
| $\times 30$ | -11000000E+07 |  |  |

L. 3 Block \#3 Output (Sample - next four pages)


| TIME S | ScAled time | x | $Y$ | 02 | KE |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 50.00 | $0 \quad 3.142-32$ | 5. $4.59+34$ | 2.372+ ¢3 | $3.093+03$ | $1.240+04$ |
| 100.00 | 0 6.283-02 | $1.004+05$ | 5.475 + - 3 | $5.580+03$ | $1.170+04$ |
| 150.00 | $0 \quad 9.42 b-02$ | 1.548+05 | 8.73A+53 | $7.514+03$ | 2.071+04 |
| 200.13 | 1 1.257-01 | $2.015+05$ | 1.213+54 | 9.097+03 | $2.284+14$ |
| 250.00 | $0 \quad 1.571=01$ | $2.523+05$ | $1.560+04$ | $1.042+r 4$ | 2.446+04 |
| 300.00 | $0 \quad 1.085-01$ | 3.033+05 | $1.930+04$ | $1.155+04$ | 2.575+u4 |
| 350.00 | O 2.199-01 | 3.544+05 | $2.307+04$ | $1.252+04$ | $2.680+04$ |
| 40.0 .10 | 2.513-01 | $4.058+05$ | 2.697+04 | $1.335+04$ | $2.766+04$ |
| 450.00 | J 2.827-01 | $4.573+05$ | $3.098+04$ | 1. $406+04$ | 2.838+04 |
| 500.05 | J 3.142-01 | $5.090+05$ | $3.510+04$ | $1.467+04$ | $2.898+34$ |
| 550.00 | $03.456-01$ | $5.6 .39+05$ | $3.934+04$ | $1.518+04$ | $2.947+04$ |
| 600.00 | $03.770-01$ | $6.130+05$ | $4.369+04$ | $1.560+04$ | $2.987+04$ |
| 650.00 | - 4,084-01 | $6.653+05$ | $4.814+04$ | $1.594+04$ | 3.019+04 |
| 700.00 | ) $4.398-01$ | 7.178+05 | $5.269+34$ | $1.620+04$ | $3.043+04$ |
| 750.00 | - 4.712-01 | 7.745+0゙5 | 5.733+C4 | $1.637+04$ | $3.059+04$ |
| 800.00 | -5.027-01 | $8.234+05$ | 6.205+04 | 1. $647+04$ | $3.068+34$ |
| 850.00 | - 5.341m01 | 8.765+0.5 | $6.685+54$ | $1.648+04$ | $3.070+34$ |
| 900.00 | 0 5.655-01 | 9.298+05 | 7.172+04 | $1.640+04$ | 3.064*-4 |
| 958.00 | 5.969-01 | $9.833+05$ | $7.663+54$ | $1.625 * 04$ | 3.050+54 |
| $1000 \cdot 00$ | J 6.283-01 | $1.037+06$ | $8.159+34$ | 1.600404 | 3.028+34 |
| 1053.00 | -6.597-01 | $1.091+06$ | 8.654+04 | $1.566 * 04$ | $2.998+04$ |
| 1100.00 | 0 6.911-01 | $1.145+06$ | 9.157+04 | 1. $524+04$ | $2.960+04$ |
| 1150.00 | 37.220001 | $1.199+06$ | $9.657+04$ | $1.473+04$ | $2.912+54$ |
| 1200.00 | 7.540-01 | $1.253+06$ | $1.016+05$ | $1.413+04$ | $2.855+04$ |
| 1253.00 | 7.854-01 | $1.358+06$ | $1.065+05$ | $1.345+04$ | $2.789+04$ |
| 1300.00 | -8.168-01 | $1.362+06$ | 1.114+25 | $1.269+04$ | 2.712+04 |
| 1350.00 | 8.48z-01 | $1.417+06$ | $1.163+05$ | $1.185+04$ | 2.625+04 |
| 1400.00 | -8.796-01 | $1.472+06$ | $1.210+05$ | $1.096+04$ | $2.528+04$ |
| 1450.00 | $9.111=01$ | 1.526+06 | 1.257+05 | $9.999+03$ | $2.419+34$ |
| 1500.00 | 9.425-01 | $1.581+06$ | $1.303+05$ | $8.997+03$ | $2.300+34$ |
| 1550.00 | 9.739-01 | $1.636+06$ | $1.34 n+05$ | $7.962+03$ | 2.168+ن4 |
| 1600.00 | 1.005+00 | $1.691+06$ | $1.391+05$ | $6.906+03$ | 2. $024+04$ |
| 1650.00 | 1.037+00 | 1.746+06 | $1.433+65$ | $5.845+0^{3}$ | $1.868+04$ |
| 1703.00 | 1.068+00 | 1.801+ن 6 | $1.474+85$ | $4.798+0.3$ | $1.699+54$ |
| 1750.00 | 1.100+00 | $1.856+06$ | $1.513+35$ | $3.781+\mathrm{ES}^{3}$ | $1.516+34$ |
| 1800.00 | 1.131+00 | $1.911+06$ | $1.551+05$ | $2.816+03$ | $1.319+04$ |
| 1850.00 | 1.162+00 | $1.900+06$ | 1.587*35 | $1.926+03$ | 1. $105+04$ |
| 1900.00 | 1.194+00 | $2.021+06$ | $1.621+05$ | $1.137+03$ | 8.727+03 |
| 1950.00 | 1.225+00 | $2 \cdot 076+06$ | 1.654+05 | $4.806+02$ | $6.172+03$ |
| 2000.00 | 1.257+00 | 2.131+06 | $1.685+05$ | $-2.281+c 0$ | $3.286+03$ |
| 2059.00 | 1.288+00 | 2.185+06 | 1.714405 | -2.429+02 | 2.624*02 |
| 2100.00 | $1.319+00$ | 2.240+06 | $1.741+05$ | -1.885+C2 | $2.953+03$ |
| 2150.00 | $1.351+00$ | 2. $295+06$ | $1.760+05$ | -1.883+02 | 3.176*03 |
| 2200.00 | $1.382+00$ | 2.349+06 | $1.789+75$ | -3.372+02 | 4.007+03 |
| 2250.00 | $1.414+00$ | 2.4i3+06 | 1.811+05 | -5.232+02 | b. $221+03$ |
| 2300.00 | $1.445+00$ | $2.458+06$ | $1.830+05$ | -7.269+02 | $6.313+03$ |
| 2350.00 | $1.477+00$ | 2.512+06 | $1.848+05$ | -9.54 $4+02$ | $7.326+03$ |
| 2400.00 | $1.508+00$ | $2.506+06$ | $1.865+05$ | $-1.205+03$ | -. $294+\dot{3}$ |
| 2450.00 | $1.539+00$ | $2.620+06$ | $1.880+05$ | -1.474+03 | $4.222+03$ |
| 2500.00 | $1.571+00$ | 2.614+06 | $1.893+05$ | $-1.758+03$ | $1.011+34$ |


|  | 50.00 | 3-142-02 | $-1.057+01$ | 7.275*01 | 1.665403 | 6.236*51 | 4.951*01 | 1.426+01 | $-5.921+00$ | -3.980+00 | $-1.470+00$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | 0.00 v | U.coc | -1.972+03 | - 0.000 | cocn? | 0.0000 |  |  |  |
|  | -100.00 | 6.283-02 | -1.355+01 | -9.145+c0 | $3.406+03$ | $0.493+01$ | $5.015+01$ | 1.674+01 | $-6.858+00$ | -5.297+00 | $-1.768+00$ |
|  |  |  | $0.050$ | $0.050$ | $-3.551+03$ | U.000 | $0.0 \mathrm{no}$ | $0.000$ |  |  |  |
|  | . 150.00 | 9.425-02 | $-1.568+01$ | $-1.184+21$ | $4.676+53$ | -.728+01 | $5.055+01$ | $1.306+01$ | -8.005+00 | -6.017+00 | $-1.793+00$ |
|  |  |  | 0.000 | 0.000 | -4.774+03 | 0.000 | 0.0 On | U.0ui |  |  |  |
|  | -200.00 | 1.257-01 | $-1.719+c 1$ | $-1.262+31$ | $5.698+03$ | $6.940+01$ | $5.072+0.1$ | $1.319+01$ | -8:794-00 | -6.427+00 | $-1.671+00$ |
|  |  |  | 0.000 | $0 . c 00$ | $-5.773+03$ | 0.000 | $0.0 \text { onc }$ | $0 . \text { ũou }$ |  |  |  |
|  | 250.00 | 1.571-01 | $-1.828+01$ | $-1.303+01$ | $6.549+03$ | 7.138+il | 5-066+01 | $1.111+01$ | -9.369+00 | -6.649+00 | $-1.458+00$ |
|  | -300.00 | 1.885-01 | 0.050 $-1.908+01$ | 0.000 $-1.318+01$ | $-6.608+03$ $7.269+03$ | 0.000 $7.320+01$ | 0.0060 $5.034+08$ | 0.000 $8.744+00$ | -9.794+00 | -6.737+00 | $-1.175+00$ |
|  |  |  | 0.060 | 0.000 | -7.316+03 | 0.000 | $0.0 n \mathrm{c}$ | 0.000 |  |  |  |
|  | -350.00 | 2.199-01 | $-1.965+01$ | $-1.313+51$ | $7.883+03$ | 7.483+01 | 4.977+01 | $6.210+00$ | $-1.011+01$ | -6.72d+00 | -8.387-01 |
|  | 400.00. | 2.513-01 | $\begin{gathered} 0.000 \\ -2.004+08 \end{gathered}$ | $\begin{gathered} 0.0 C 0 \\ -1.291+01 \end{gathered}$ | $\begin{array}{r} -7.922+03 \\ 8.409+03 \end{array}$ | $\begin{aligned} & \text { u.0no } \\ & 7.627+01 \end{aligned}$ | $\begin{aligned} & 0.0 \cap 0 \\ & 4.891+01 \end{aligned}$ | $\begin{aligned} & 0.000 \\ & 3.364+00 \end{aligned}$ | $-1.032+01$ |  |  |
|  |  |  | D.000 | 0.0Cr | -8.441+03 | 0.000 | 0.000 | 0.000 |  |  |  |
|  | -450.00 | 2.827-01 | $-2.027+02$ | -1.256+01 | 8.86:+03 | 7.748+01 | $4 \cdot 773+01$ | 2.510-01 | $-1.046+01$ | $-6.440+40$ | -3.390-02 |
|  |  |  | 0.000 | 0.000 | $-8.887+03$ | 0.000 | 0.000 | 0.000 |  |  |  |
|  | $500 \cdot 00$ | 3.142-01 | -2.037+01 | $-1.207+01$ | $9.246+03$ | 7.843+01 | $4 \cdot 673+01$ | -3.15i+00 | $-1.053+01$ | $-6.206+00$ | 4.230-01 |
|  |  |  | 0.000 | $0.00 n$ | -9.267+03 | 0.000 | 0.0 O0 | 0.000 |  |  |  |
|  | 550.00 | $3.456=01$ | -2.033+01 | -1.148+01 | $9.571+03$ | 7.908+01 | 4.4.2.6+01 | -6.83\%+00 | $-1.053+01$ | $-5.906+00$ | 9.10:-01 |
|  |  |  | 0.000 | $0.0 C 0$ | -9.587+03 | U.0no | $0 \cdot 0$ O0 | 0.000 |  |  |  |
|  | $-600.00$ | 3.770-01 | -2.018+01 | $-1.07 b+01$ | $9.840+03$ | 7.940401 | 4.213+01 | -1.08U+01 | -1.046+01 | -5.550+00 | $1.423+00$ |
|  |  |  | 0.000 | $0 . c c o$ | -9.852+03 | 0.000 | C.0no | 0.000 |  |  |  |
| $\stackrel{\leftarrow}{+}$ | -650.00 | 4.084-01 | -1.991+01 | $-9.986+00$ | $1.006+04$ | /.935+01 | $3.950+01$ | -1.503+01 | $-1.033+01$ | -5.144+00 | $1.958+00$ |
| U | -700.00 | 4.398-01 | $\begin{gathered} 0.000 \\ -1.952+01 \end{gathered}$ | $\begin{gathered} 0.00 c \\ -9.112+00 \end{gathered}$ | $\begin{array}{r} -1.006+04 \\ 1.022+04 \end{array}$ | $\begin{aligned} & \text { U.0no } \\ & 7 . \operatorname{AR} 9+01 \end{aligned}$ | $\begin{aligned} & 0.0 n 0 \\ & 3.647+01 \end{aligned}$ | $\begin{aligned} & 0.000 \\ & =1.950+01 \end{aligned}$ | $-1.015+01$ | $-4.690+00$ | $2.508+00$ |
|  |  |  | $0.000$ | $0.0 \mathrm{CO}$ | $-1.022+04$ | $0.000$ | $0.0 \cap 0$ | $0.000$ |  |  |  |
|  | $-750.00$ | 4.712-01 | $-1.903+01$ | -8.151+00 | $1.033+04$ | 7.799+01 | $3 \cdot 3 n 4+01$ | $-2.419+01$ | $-9.899+00$ | $-4.194+00$ | $3.070+00$ |
|  |  |  | $0.000$ |  | $-1.033+14^{4}$ | 0.000 |  | 0.000 |  |  |  |
|  | $-100.00$ | 5.027-0t | -1.843+01 | -7.118+00 | $1.040+04$ | 7.663+01 | $2.922+61$ | -2.904+01 | -9.594*00 | -3.659*00 | 3.636+00 |
|  |  |  | 0.000 | 0.000 | $-1.039+04$ | 0.000 | U.0no | 0.000 |  |  |  |
|  | -850.00 | -5.-341-01 | $=1.772+01$ | $-6.031+00$ | 1.041+04 | 7.478+01 | 2.5n3+01 | $-3.402+01$ | -9.234*00 | -3.091*00 | $4 \cdot 200+00$ |
|  |  |  | $0.000$ | $0.000$ | $-1.040+24$ | $0.000$ | $0.0 \cap \mathrm{C}$ | $0.000$ |  |  |  |
|  | $-000.80$ | 5.655-0. | $\begin{gathered} -1.692+01 \\ 0.000 \end{gathered}$ | $-4.894+00$ 0.000 | $1.036+04$ $-1.035+04$ | $1.244+31$ 3.000 | 2.0504 Gl | $-3.406+01$ 0.000 | $-8.819+00$ | $-2.496+00$ | $4.756+00$ |
|  | -950.00 | $5.949-01$ | 0.000 $-1.603+02$ | 0.000 $-3.719+00$ | $-1.035+04$ $1.027+04$ | J.000 $6.969+01$ | 0.006 $1.566+01$ | 0.000 $-4.410+01$ | -8.354+00 | -1.880+00 | $5.293+00$ |
|  |  |  | $0.000$ |  | $-1.025+04$ | 0.000 | 0. eno | 0.000 |  |  |  |
|  | +000-90. | 6.283-01 | -1.506+01 | $-2.520+00$ | $1.012+04$ | $6.628+01$ | 1.057+01 | -4.907+01 | -7.842+00 | -1.25 $6+00$ | 5.906+00 |
|  |  |  | 0.0co | 0.000 | $-1.010+04$ | 0.000 | $0 \cdot 0$ O | 0.600 |  |  |  |
|  | - 050.00 | $6.597-01$ | -1.400+01 | $-1.313+00$ | $9.915+03$ | $6.250+01$ | $5.289+00$ | -5.584+01 | -7.269+00 | -6.160-01 | 6. $284+00$ |
|  |  |  |  |  | $-9.889+03$ | 0.000 | $0 \cdot 0$ 0no | 0.000 |  |  |  |
|  | 1800.00. | $6.911-01$ | -1.289+01 | -1.125-01 | $9.655+03$ | $5.830+01$ | -1.160-01 | $-3.848+01$ | -6.699+00 | $1 \cdot 333=02$ | $6.721+00$ |
|  |  |  | 0.000 | 0.000 | -9.625+03 | 0.000 | 0.0no | U.000 |  |  |  |
|  | 1450.00 | 7.226-01. | ..-1-172+01 | 1.064*00 | $9.340+03$ | 5.373+01 | $-5.570+00$ | -0. $280+01$ | $-6.080+00$ | $6.303=01$ | 7.106+00 |
|  |  |  | 0.000 | 0.000 | -9.305+03 | 0.000 | D.0n0 | 0.000 |  |  |  |
|  | +200.00 | $7.540-01$ | $-1.051+01$ | 2.200400 | 8.970+03 | 4.A84*01 | $=1 \cdot 100+01$ | -6.675+01 | -5.439*00 | $1.22 b+00$ | $7.433+00$ |
|  | 1250.00 | 7.854001 | $\begin{gathered} 0.000 \\ -9.275+00 \end{gathered}$ | $\begin{aligned} & 0.000 \\ & 3.279+00 \end{aligned}$ | $-8.932+03$ $8.548+03$ | $\begin{aligned} & 0.000 \\ & 4.371+01 \end{aligned}$ | $\begin{aligned} & 0.0 n 0 \\ & -1.631+01 \end{aligned}$ | $\begin{aligned} & 4.000 \\ & =7.0<7+01 \end{aligned}$ | $-4.786+00$ | 1.786+00 | 7.695*00 |
|  |  |  |  |  | -8.505+03 |  |  | 0.600 |  |  |  |
|  | 1300.00 | A.berabl. | $=8.034+00$ | $4.280+00$ | 8.077+03 | $3.839+0!$ | $-2.145+01$ | $-7.3 \mathrm{~J} 2+01$ | $-4.129+00$ | $2.300+00$ | 7.886+00 |
|  |  |  | 0.000 | 0.000 | -8.029+03 | 0.000 | 0.000 | 0.000 |  |  |  |
|  | 1350.00 | 19482-01 | -6.796+00 | $5.189+00$ | $7.558+03$ | 3.298+01 | $-2.633+01$ | -7.5日b+01 | $-3.477+00$ | $2.775+00$ | $7.996+00$ |


|  | 1400．00 | 8．796－91 | $\begin{aligned} & 0.000 \\ & -5.588+00 \end{aligned}$ | $\begin{aligned} & 0.9 c \mathrm{c} \\ & 5.99 \mathrm{c}+0 \mathrm{c} \end{aligned}$ | $\begin{array}{r} -7.507+03 \\ 6.998+03 \end{array}$ | $\begin{aligned} & 0.0 \mathrm{OD} \\ & 2.754+01 \end{aligned}$ | $\begin{aligned} & 0.0 \cap 0 \\ & -3.088+51 \end{aligned}$ | $\begin{aligned} & 0.300 \\ & -1.783+01 \end{aligned}$ | －2．840＋00 | $3.184+00$ | 1．024＊00 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | 0.000 | U．CEO | －6．942＋03 | 0.000 | $0 \cdot 0 \mathrm{O}$ | C． 000 |  |  |  |
|  | 1450.00 | $9 \cdot 111-01$ | $-4.423+00$ | 6．662＋0c | $6.401+03$ | $2.216+01$ | $-3.5 n 6+c 1$ | －7．925＋01 | －2．228400 | $3.526+00$ | 7．969400 |
|  |  |  | 0.000 | 0.000 | $-6.341+03$ | 0.000 | 0.0 Oo | 0.000 |  |  |  |
|  | 150c．00 | 9．425－51 | －3．316＋00 | $7.196+c 0$ | $5.774+03$ | 1．689＋01 | $-3.892+01$ | －8．010＋01 | $-1.650+00$ | 3．291＊00 | 1－224＋00． |
|  |  |  | 0.000 | 0.000 | $-5.710+03$ | U．1000 | $0 \cdot 000$ | 0.000 |  |  |  |
|  | 1550.00 | 9．739－01 | －2．289＋00 | $7.575+0 c$ | $5.125+03$ | 1．182＋01 | －4．211＋01 | $-8.034+01$ | $-1.115+00$ | $3.976+00$ | 7． $589+00$ |
|  |  | 1．005＋00 | 0.000 | 0.090 | $-5.057+03$ | 4.000 | $0 \cdot 000$ | 0.000 |  |  |  |
|  | 1600.00 |  | $-1.357+00$ | 7．788＋00 | $4.462+03$ | $6.979+00$ | －4．492＋01 | $-8.012+01$ | －6．327－01 | 4．0．72＋00 | 7．2 $24+00$ |
|  | 1650.00 | $1.037+00$ | $\begin{gathered} 0.030 \\ -5.366=01 \end{gathered}$ | $\begin{aligned} & 0.00 n \\ & 7.821+30 \end{aligned}$ | $-4.390+03$ $3.795+03$ | $\begin{aligned} & 0.000 \\ & 2.434+00 \end{aligned}$ | $\begin{gathered} 0.000 \\ -4.722+01 \end{gathered}$ | $\begin{gathered} 0.000 \\ -7.932+01 \end{gathered}$ | －2．101－01 | 4．076＋00 | 6．848＋00． |
|  | 1700．00 | $1.068+00$ | 0.090 | 0.090 | $-3.719+03$ | U． 000 | $0.0 n 0$ | 0.000 |  |  |  |
|  |  |  | 1．484－01 | $7.670+00$ | $3.134+03$ | －1．779＋00 | －4．9ni＋01 | －7．802＋01 | 1．446－01 | $3.984+00$ | $6.342+00$ |
|  |  |  | 0.020 | 0.000 | －3．055＋03 | 0.000 | D．DOU | 0.000 |  |  |  |
|  | 1750.00 | $1.100+00$ | 6．991－01 | 7．321＋50 | $2.493+03$ | $-5.627+00$ | $-5.029+01$ | －7．020＋01 | 4，240－01 | $3.790+00$ | 5.747400 |
|  |  |  | $0.00{ }^{\text {c }}$ | 0.000 | －2．409＋03 | 0.000 | $0.0 n 0$ | 0.000 |  |  |  |
|  | 1800．00 | $1.131+00$ | $1.080+00$ | $6.761+00$ | $1.884+03$ | －9．086＋00 | $-5.1 n 6+01$ | －7．407＋01 | 6．210－01 | $3.490+00$ | $5.062+00$ |
|  |  |  | 0.000 | 0.000 | $-1.796+03$ | 0.000 | $0.0 n 0$ | $0.000$ |  |  |  |
|  | 1850.00 | $1.162+00$ | $1.309+00$ | $5.982+00$ | $1.322+03$ | －1．214＋01 | $-5 \cdot 135+01$ | －7．148＋01 | 7．279－01 | $3.079+00$ | $4.286+00$ |
|  |  |  | 0．010 | C．OCO | －1．229＋03 | U． 000 | 0.0 O | 0.000 |  |  |  |
|  | 1900．00 | 1．194＋00 | 1．336＋00 | $4.957+00$ | $8.242+02$ | －1．477＋01 | －5．116＋01 | －6．853＋01 | 7．361－01 | 2．549＋00 | $3 \cdot 415+00$ |
| $\stackrel{\leftarrow}{\dot{\sigma}}$ |  |  | 0.0 0 | 0.000 | －7．263＋02 | U．000 | 0.000 | 0.000 |  |  |  |
|  | 1950.00 | $1.225+00$ | $1.148+00$ | $3.668+00$ | $4.128+02$ | $-1.698+11$ | $-5.051+01$ | －6．526＋01 | 6．338－01 | $1.885+00$ | $2.435 \pm 00$ |
|  |  |  | 0.0 c | 0.500 | －3．070＋02 | 0.000 | $0.0 n \mathrm{c}$ | 0.000 |  |  |  |
|  | 2000．100 | $1.257+00$ | 7－0゙98－cl | 2．039＋CC | $1.177+02$ | $-1.877+01$ | －4．941＋01 | $-6.169+01$ | 3．998－01 | $1.053+00$ | $1.314+00$ |
|  |  |  | 0.000 | －000\％ | $1.495+00$ | 0.000 | $0 \cdot 003$ | 0.400 |  |  |  |
|  | 2050．00 | $1.288+00$ | 7．058－02 | 1．938－01 | －8．500－01 | －2．013＋01 | －4．7H7＋61 | －5．78 $2+01$ | －2．390－02 | －5．684－02 | －6．866－02 |
|  |  |  | 0.000 | 0.000 | $1.553+02$ | $0.000$ | 0.0 On | C．UOU |  |  |  |
|  | 2100.00 | $1.319+00$ | 2．154－02 | 2．501－01 | －9．520＋01 | －2．105＋01 | －4．5A9＋C1 | －5．308＋01 | －4．503－01 | －9．819－01 | $-1 \cdot 14.9+00$ |
|  |  |  | $0.000$ | 0.006 | $1.205+02$ | 0.000 | 0.0 O | 0.000 |  |  |  |
|  | 2150.00 | $1.351+00$ | －6．0．78－01 | $-1.171+00$ | $-1.100+02$ | －2．152＋u1 | $-4.363+41$ | $-4.953+01$ | －5．447－01 | $-1.104+00$ | $-1.254+00$ |
|  |  |  | 0.006 | 0.0 C | $1.204+02$ | 0.000 | $0 \cdot 000$ | 0.000 |  |  |  |
|  | 2200．00 | $1.382+00$ | $-1.202+00$ | $-2.332+G C$ | $-1.745+12$ | －2．160＋01 | $-4.120+01$ | －4．549＋01 | －7．496－01 | $-1.430 * 00$ | $-1.579+00$ |
|  |  |  | 0.000 | 0.000 | $2.156+02$ | 4.000 | －0．000 | G．000 |  |  |  |
|  | 2250000 | $1.414+00$ | $-1.910+00$ | $-3.553+00$ | $-2.953+02$ | －2．134＋01 | －3．862＋01 | －4．155＋01 | $-1.047+00$ | $-1.895+00$ | $-2.039+00$ |
|  |  |  | 0.000 | －．Cこの | $3.346+02$ | 0.000 | 0.000 | 0.000 |  |  |  |
|  | 2300.00 | $1.445+00$ | $-2.561+00$ | $-4.533+20$ | $-4.310+02$ | －2．079＋01 | $-3.593+01$ | $-3.771+01$ | $-1.345+00$ | $-2.325+00$ | $-2.440+00$ |
|  |  |  | $0.00 \mathrm{n}$ | 0.000 | $4.649+02$ | 0.000 | $0 \cdot 0 \mathrm{CO}$ | 0.000 |  |  |  |
|  | 2350．00 | $1.477+00$ | －3．181400 | －5．376＋C0 | $-5.795+02$ | －1．999＋01 | －3．317＋01 | －3．402＋01 | $-1.646+00$ | $-2.731+00$ | $-2.801+00$ |
|  | 2400.00 | $1.508+05$ | －3．799＋00 | 0.03 c -6.165 | $6.107+02$ $-7.420+02$ | 0.000 | 0．0nc | －3．000 |  |  |  |
|  |  |  | 0.00 C | $0.000$ | $7.710+02$ | $\begin{aligned} & -1.900+31 \\ & 0.7000 \end{aligned}$ | $\begin{aligned} & =3.0394 \\ & 0.0 n 0 \end{aligned}$ | $\begin{aligned} & -3.050+0! \\ & 6.000 \end{aligned}$ | －1．953＋00： | $-3.125+00$ |  |
|  | 2450.00 | 1．539＋00 | －4．42c＋00 | $=0.923+00$ | －9．163＋02 | －1．784＋01 | $-2.762+01$ | $-2.714+01$ | $-2.264+00$ | $-3.506+00$ | －3．445＊00 |
|  |  |  | $0 \cdot 000$ | 0.007 | $9.432+02$ | 0.009 | 0.0 O | 0.000 |  |  |  |
|  | 2500．00 | $1.571+00$ | －5．043＋00 | $-7.651+00$ | $-1.100+\mathrm{C}^{3}$ | $-1.655+01$ | －2．4R9＋01 | －2．397＋01 | $-2.575+00$ | $-3.872+00$ | $-3.730+00$ |
|  |  |  | 0.000 | 0.000 | $1.125+03$ | 0.003 | 0.000 | C．000 |  |  |  |

## APPENDIX M

## Initial Testing of Balloon Program

In general according to first-order theory, the equation for a balloon in a stationary atmosphere can be written as
$\left(\frac{m+m_{a}}{m}\right) \frac{d v_{3}}{d t}+2 \alpha v_{3}+N^{2} x_{3}^{\prime}=G_{1}\left|v_{3}\right| v_{3}+F_{B}$
In this equation, the vertical displacement from equilibrium is $x^{\prime}{ }_{3}\left(=x_{3}-x_{30}\right)$. The mass of the balloon is $m$, and the apparent mass of the displaced fluid is $m_{a}$. In general, for a spherical balloon displaced a small distance from equilibrium, $\left(m+m_{a}\right) / m=3 / 2$.

In Equation ( $M-1$ ) $\alpha$ is the linear drag and $G_{1}$ is the nonlinear contribution to the drag term based on the following approximation for drag coefficient

$$
\begin{equation*}
C_{D}=\frac{24}{R e}+C_{D \ell} \tag{M-2}
\end{equation*}
$$

where $C_{D \ell}$ is a constant and $R e$ is the Reynolds number $\left(\operatorname{Re} \propto\left|v_{3}\right|\right)$
In Equation ( $M-1$ ) the term $F_{B}$ represents the Basset force which arises in a transient flow at low Reynolds numbers.

The buoyancy term $\mathrm{N}^{2}$ has been reduced to its linear component. Perturbation techniques used to evaluate the nonlinear contributions show that the first-order term contributes a modification of about 1 cm in 10 m to the amplitude of the oscillation and a subharmonic term of similar amplitude. These nonlinear contributions should be observed using a small time step and careful analysis. The perturbation technique cannot be used to solve the linear oscillator in general, as, the solution does not converge due to secular terms which arise in solutions higher than first-. order. However, the technique seems applicable here to determine, the order of magnitude of the nonlinear contribution since no resonance phenomena are expected in the unforced system.

In the first four tests respectively the following simplifications were made:
(1) $\left(m+m_{a}\right) / m=1, \quad \alpha=0, F_{B}=0, G_{1}=0$
(2) $\left(m+m_{a}\right) / m=1, \quad \alpha \neq 0, F_{B}=0, G_{1}=0$
(3) $\left(m+m_{a}\right) / m=3 / 2, \alpha=0, F_{B}=0, G_{1}=0$
(4) $\left(m+m_{a}\right) / m=1, \quad \alpha=0, F_{B} \neq 0, G_{1}=0$

For test case \#1 the governing equation is the same as that for a parcel of air displaced from its equilibrium position in the absence drag forces, Basset forces, apparent mass forces and fluid acceleration forces. With these simplifications the governing equation is

$$
\begin{equation*}
\frac{d v_{3}}{d t}=-\frac{\partial p}{\partial x_{3}}-g \tag{M-3}
\end{equation*}
$$

where the terms have their usual meaning.

For the atmosphere, by means of the hydrostatic equation,

$$
\begin{equation*}
0=-\frac{1}{\rho} \frac{\partial p}{\partial x_{3}}-g . \tag{M-4}
\end{equation*}
$$

The atmospheric temperature is assumed to vary linearly with altitude according to the relation.

$$
\begin{equation*}
T=T_{0}-\gamma x_{3}^{\prime} \tag{M-5}
\end{equation*}
$$

The temperature of the parcel is also assumed to vary linearly with altitude according to the relation

$$
\begin{equation*}
T_{p}=T_{o}-\gamma_{p} x_{3}^{\prime} \tag{M-6}
\end{equation*}
$$

As shown by Hess [181], based on the four preceding equations combined with the ideal gas law, by first-order theory the oscillation of the air parcel can be predicted. The period of oscillation is

$$
\begin{equation*}
\tau=\frac{2 \pi}{\sqrt{g / T_{o}\left(\gamma_{p}-\gamma\right)}} \tag{M-7}
\end{equation*}
$$

Normally $\gamma_{p}$ is assumed to be equal to the adiabatic lapse rate, $\Gamma_{S}$, and the resulting relation is

$$
\begin{equation*}
\tau_{B . V .}=\frac{2 \pi}{\sqrt{g / T_{o}\left(\Gamma_{s}-\gamma\right)}} \tag{M-8}
\end{equation*}
$$

where the subscript B.V. refers to Brunt-Väisälä.

As pointed out by Angell and Pack [131], if $\gamma_{p}$ is set equal to the constant density lapse rate, $\Gamma_{\rho}$, (instead of the adiabatic lapse rate), the motion of the air parcel is the same as that of a constant volume balloon with a period of oscillation of

$$
\begin{equation*}
\tau_{C V B}=\frac{2 \pi}{\sqrt{\overline{\mathbf{g}} / T_{o}\left(\Gamma_{\rho}-\gamma\right)}} \tag{M-9}
\end{equation*}
$$

Now

$$
\begin{equation*}
r_{\rho}=-.03410_{K / m} \tag{M-10}
\end{equation*}
$$

which is about six times larger than the lapse rate normally observed in the lower atmosphere. For the case of an isothermal atmosphere,

$$
\begin{align*}
\tau_{C V B} & =\frac{2 \pi}{\sqrt{g / T_{O} \Gamma_{\rho}}} \\
& =10.85 \sqrt{T_{0}} \tag{M-11}
\end{align*}
$$

Equation (M-11) closely agrees with the relation given by Lally [58].
Now for the test case \#1, with an isothermal atmosphere,

$$
\begin{equation*}
\gamma=0 \tag{M-12}
\end{equation*}
$$

and

$$
\begin{equation*}
\mathrm{T}_{\mathrm{O}}=218^{\circ} \mathrm{K} \tag{M-13}
\end{equation*}
$$

the time period is

$$
\begin{equation*}
{ }^{\tau} \mathrm{CVB}=160.20 \mathrm{sec} . \tag{M-14}
\end{equation*}
$$

The balloon displacement as a function of time, based on the computer program is presented in Table (M-1). Inspection of this table reveals a time period of 160 seconds, in close agreement with Equation (M-12).

For the case \#2, the solution to Equation (M-1) is

$$
\begin{equation*}
x_{3}^{\prime}=A e^{-\alpha t} \cos \lambda t \tag{M-15}
\end{equation*}
$$

where

$$
\begin{equation*}
\lambda=\left(N^{2}-\alpha^{2}\right)^{\frac{1}{2}} \tag{M-16}
\end{equation*}
$$

Predicted Displacement History of Constant-Volume
Balloon in a Stationary Isothermal Atmosphere . (Test Case \#1) *

| $\underset{\mathrm{N}}{\text { Time Step }}$ | Vertical Displacement $\mathrm{x}_{3}-\mathrm{x}_{30}$ (m) | Time <br> $t$ (sec) | Time Step | Vertical <br> Displacement $\mathrm{x}_{3}-\mathrm{x}_{30}(\mathrm{~m})$ | Time $t$ (sec) |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | 10. | 0 | 22 | -10.39 | 105 |
| 2 | 9.74 | 5 | 23 | - 8.14 | 10 |
| 3 | 8.93 | 10 | 24 | - 5.69 | 15 |
| 4 | 7.76 | 15 | 25 | - 3.13 | 20 |
| 5 | 6.12 | 20 | 26 | - . 57 | 25 |
| 6 | 4.13 | 25 | 27 | +1.89 | 30 |
| 7 | 1.86 | 30 | 28 | 4.15 | 35 |
| 8 | - . 59 | 35 | 29 | 6.13 | 40 |
| 9 | - 3.14 | 40 | 30 | 7.77 | 45 |
| 10 | - 5.69 | 45 | 31 | 8.99 | 150 |
| 11 | - 8.14 | 50 | 32 | 9.74 | 55 |
| 12 | -10.40 | 55 | 33 | 10.00 | 60 |
| 13 | -12.38 | 60 | 34 | 9.77 | 65 |
| 14 | -14.00 | 65 | 35 | 9.05 | 70 |
| 15 | -15.21 | 70 | 36 | 7.86 | 175 |
| 16 | -15.95 | 75 | 37 | 6.25 | 80 |
| 17 | -16.20 | 80 | 38 | 4.28 | 85 |
| 18 | -15.95 | 85 | 39 | 2.02 | 90 |
| 19 | -15.21 | 90 | 40 | - . 43 | 95 |
| 20 | -14.00 | 95 | 41 | - 2.98 | 200 |
| 21 | -12.37 | 100 |  |  |  |

* Note: An error in the balloon density places the equilibrium position at $\mathrm{x}_{3}-\mathrm{x}_{30} \cong-3 \mathrm{~m}$.

TABLE M-1 (con't)

| $\left\lvert\, \begin{gathered} \text { Time Step } \\ \mathrm{N} \end{gathered}\right.$ | $\begin{aligned} & \text { Vertical } \\ & \text { Displacement } \\ & \mathbf{x}_{3}-x_{3}(\mathrm{~m}) \end{aligned}$ | $\begin{aligned} & \text { Time } \\ & t(\mathrm{sec}) \end{aligned}$ | $\underset{\mathrm{N}}{\text { Time Step }}$ | Vertical Displacement $x_{3}-x_{3}{ }^{(m)}$ | Time <br> t (sec) |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 42 | - 5.53 | 205 | 62 | 7.67 | 305 |
| 43 | - 7.99 | 10 | 63 | 8.92 | 10 |
| 44 | -10.27 | 15 | 64 | 9.71 | 15 |
| 45 | -12.27 | 20 | 65 | 10.00 | 20 |
| 46 | -13.92 | 225 | 66 | 9.79 | 325 |
| 47 | -15.15 | 30 | 67 | 9.09 | 30 |
| 48 | -15.92 | 35 | 68 | 7.93 | 35 |
| 49 | -16.21 | 40 | 69 | 6.34 | 40 |
| 50 | -15.99 | 45 | 70 | 4.39 | 45 |
| 51 | -15.27 | 250 | 71 | 2.16 | 350 |
| 52 | -14.09 | 55 | 72 | - . 27 | 55 |
| 53 | -12.49 | 60 | 73 | - 2.82 | 60 |
| 54 | -10.53 | 65 | 74 | - 5.37 | 65 |
| 55 | - 8.29 | 70 | 75 | - 7.83 | 70 |
| 56 | - 5.85 | 275 | 76 | -10.11 | 375 |
| 57 | - 3.30 | 80 | 77 | -12.12 | 80 |
| 58 | - . 74 | 85 | 78 | -13.79 | 85 |
| 59 | + 1.73 | 90 | 79 | -15.06 | 90 |
| 60 | 4.02 | 95 | 80 | -15.87 | 95 |
| 61 | 6.02 | 300 | 81 |  | 400 |

In the case studied, it was found that $\alpha^{2} \ll N^{2}$. Consequently the period

$$
\begin{align*}
\tau & =\frac{\tau_{0}}{\sqrt{1-\tau_{0}^{2} / \tau_{\alpha}^{2}}} \\
& \simeq \tau_{0} \tag{M-17}
\end{align*}
$$

where

$$
\begin{align*}
& { }^{\tau}{ }_{o}=2^{\pi / N}  \tag{M-18}\\
& { }^{\tau_{\alpha}}=2^{\pi / \alpha}  \tag{M-19}\\
& N=\sqrt{\frac{g}{T_{o}\left(Y_{0}-Y\right)}} \tag{M-20}
\end{align*}
$$

Hence, no change in this period was observed in the numerical solution due to the dissipation term. However, the amplitude damping in the numerical solution was found to correspond almost exactly to the theoretical value.

In the Case \#3 test, it was observed that the period $\tau$ given by the numerical solution corresponded closely to the firstorder solution which required

$$
\begin{equation*}
\tau=\sqrt{\frac{3}{2}} \tau_{0} \tag{M-21}
\end{equation*}
$$

In the fourth test, the Basset force was non-zero,

$$
\begin{equation*}
F_{B} \propto \int_{0}^{t} \frac{d v_{3} / d t^{\prime}}{\sqrt{t-t^{\prime}}} d t^{\prime} \tag{M-22}
\end{equation*}
$$

No attempt was made to obtain a solution to the integral equation. The results of the test suggested that the Basset term behaves like a term, of the form,

$$
\begin{equation*}
F_{B}=2 a \quad v_{3}-b^{2} x_{3}^{\prime} \tag{M-23}
\end{equation*}
$$

leading to an equation of the form

$$
\begin{equation*}
\frac{d v_{3}}{d t}+2 a \quad v_{3}+\left(N^{2}-b^{2}\right) x_{3}^{\prime}=0 \tag{M-24}
\end{equation*}
$$

where the fundamental period was altered and the motion dampened. The oscillation was regular over two periods leading to the supposition that

$$
\begin{equation*}
a, b \neq f\left(x_{3}^{\prime}\right) \tag{M-25}
\end{equation*}
$$

The value of " $a$ " was of the same order of magnitude as the coefficient of the integral. However, " ${ }^{2}$ " was found to be an order of magnitude greater;

$$
\begin{equation*}
\mathrm{b}^{2} \sim 10 \mathrm{a} \sim 10^{-2} \tag{M-26}
\end{equation*}
$$

All of the preceding tests were conducted assuming an isothermal atmosphere with the natural period given by the relation

$$
\begin{equation*}
\tau_{0}=T_{0} \sqrt{\frac{g}{\gamma_{0}}} \tag{M-27}
\end{equation*}
$$

instead of the more general relation

$$
\begin{equation*}
\tau=T_{0} \sqrt{\frac{g}{\gamma_{0}-\gamma}} \tag{M-28}
\end{equation*}
$$

One additional test case (\#5) was run to ensure that $\gamma=0$ was not a special case. The period of this test case and the period obtained from the analytic solution of the equation were again nearly identical.

## APPENDIX N

## Results of Test Runs \#6 - \#11

Based on the numerical solution produced by BALLOON, the variation of the vertical component of velocity (for the wind and the balloon) versus time is presented in Figures N-1 through N-5 for test cases \#6 - \#11.


Figure N-1. Vertical Component of Velocity Versus Time, Test Cases \#6 and \#7


Figure N-2. Vertical Component of Velocity Versus Time, Test Case \#8


1-75-1567

Figure N-3. Vertical Component of Velocity Versus Time, Test Case \#9


1-75-1566

Figure N-4. Vertical Component of Velocity Versus Time, Test Case \#10


1-75-1565

Figure N-5. Vertical Component of Velocity Versus Time, Test Case \#11

For each of the sixteen runs which were initially performed as part of Phase $I$ a set of 6 position and velocity plots was generated. These plots are not included in the report because of the considerable bulk which they represent. They have been collected and bound in a separate document [1] for reference purposes.

For each of the sixteen runs special attention was given to the length of the time interval over which the numerical integration was carried out. The time interval used along with the time period of the associated flow field are presented in Figure 0-1.

Figure $0-2$ presents the linear period, the observed period and the observed phase lag in the balloon velocity for the 16 runs. The wind is given by:

$$
\begin{equation*}
u_{i}=\bar{u}_{i}+A \sin \left(k_{j} x_{j}-\omega t+\theta_{i}\right) \tag{0-1}
\end{equation*}
$$

Based on the assumption

$$
\begin{equation*}
\mathrm{x}_{\mathrm{i}}=\bar{u}_{\mathrm{i}} \mathrm{t} \tag{0-2}
\end{equation*}
$$

then the linear period is given by

$$
\begin{equation*}
\tau=\frac{2 \pi}{\mathrm{k}\left|\bar{u}_{1}-c\right|} \tag{0-3}
\end{equation*}
$$

since $k_{i}=k$ and $\bar{u}_{i}=\bar{u}_{i} \delta_{i 1}$, and

$$
\begin{equation*}
c=\frac{\omega}{\mathrm{k}} \tag{0-4}
\end{equation*}
$$

is the phase velocity. The observed periods are taken directly from the data represented in Figures 5-4 through 5-6.

In Figure $0-2$ values to the right of the principal diagonal represent cases where $\bar{u}_{1}>c$ and to the left where $\bar{u}_{1}<c$. Of course, on the diagonal, $\bar{u}_{1}=c$, corresponding to Taylor's hypothesis. Off the diagonal the equation for vertical motion has the form


NOTE: Associated with each element in the array there are two numbers. The top number is the total time interval over which the particular case was integrated, and the bottom number is the linear period due to the forcing function. Both time periods have units of seconds.

Figure 0-1. Total Time Intervals and Linear Periods for 16 Original Runs of Phase I


NOTE: Associated with each element in the array there are three numbers. The upper number is the theoretical (linear) period, the middle number is the observed period, and the lower number is the phase lag. Positive values of the phase lag indicate the balloon lags of the wind. All values are in seconds.

Figure 0-2. Periods of Oscillation and Phase Lag for 16 Original Runs of Phase I

$$
\begin{equation*}
\frac{d v_{3}}{d t}+2 \alpha v_{3}+N^{2} x_{3}^{\prime}=C \cos \left(k_{j} x_{j}-\omega t+\theta_{3}\right)+G \tag{0-5}
\end{equation*}
$$

where the left-hand-side of the equation is the usual equation for a damped oscillator. The first term on the right-hand-side is the forcing function due to the pressure forces where $C$ is assumed to be a constant, and $G$ is a function which is nonlinear in $d x_{3} / d t$. If the function $G$ is neglected, the balloon would be expected to oscillate with the period of the forcing function given by Equation (0-3). This expectation is borne out by the test case results. The largest observed deviation from the linear period occurs along the fourth column in Figure $0-2$ where the wave number is a maximum and not necessarily where $|u-c|$ approaches a minimum.

Along the diagonal of the experiment matrix, the cosine of Equation ( $0-5$ ) becomes a constant. For these cases the oscillations should be expected to damp out as was observed in the $A_{11}$ case. In these cases, the balloon approximately matched the flow after the initial transient motion was suppressed and the forces balanced to hold it in this position. Thus for case A11, the balloon was observed to reach equilibrium about 120 m below its equilibrium level and, was observed to continue to have a lateral motion. This lateral motion persists for longer time intervals, causing an ever-increasing lateral displacement of the balloon. Therefore, one would observe no vertical motion but a mean lateral motion.

The vertical displacement typically displayed two modes of oscillation. The short-period oscillation corresponded to the forced oscillation. The long-period oscillation resulted from the initial conditions and was found to be damped as expected.

Figure $0-3$ shows case $A_{31}$ where a very long total time interval for numerical integration was employed. This case clearly shows the damping in the transient mode of oscillation.


Figure 0-3. Run $A_{31}$. Vertical Position of Balloon
as a Function of Time.

Analysis of Numerical Results Phase I - Cruciform Runs
P. 1 Cruciform $\mathrm{C}_{22}$

Twenty-four runs were carried out in the Cruciform $C_{22}$ arrangement shown in Figure P-1. The values of $k$ and $\omega$ for each run are given in Figure $\mathrm{P}-1$. For each run, a set of six position and velocity histories are generated. These plots are not included in the report, because of the considerable bulk which they represent. Such plots have been collected and bound in a separate document [1] for reference pusposes.

Analysis of the numerical results of the 24 runs was primarily concerned with comparing the first-order theoretical time period with the observed value. The results of this comparison are presented in Figure P-2. In general, as the conditions corresponding to $A_{22}$ are approached along any one of the four branches of the cruciform the first-order theoretical period and the observed period agree less and less, with the observed value increasing more rapidly than the first-order theoretical value. This indicates that first-order theory, which is linear, is not sufficient to predict the balloon motion under conditions where Taylor's hypothesis is (nearly) satisfied.

## P. 2 Cruciform $\mathrm{C}_{33}$

Twelve runs were carried in the Cruciform $C_{33}$ arrangement as shown in Figure $P-3$. The values of $k$ and $w$ for these runs are presented in Figure $P-3$. As with the $C_{22}$ runs, a set of six position and velocity histories was generated for each run. These plots have been collected and bound in separate documents 1 for reference purposes.

As in the case of the $C_{22}$ runs, analysis of the numerical results of the twelve runs was primarily concerned with comparing the first-order theoretical time period with the observed values. Figure P-4 provides a summary of this comparison. Inspection of this figure reveals the same trend as observed in Cruciform $\mathrm{C}_{22}$. Again, it would appear that first-order theory is not adequate to predict the balloon motion under conditions where Taylor's hypothesis is (nearly) satisfied.


Figure p-1. Values of $\tilde{k}$ and $\tilde{\omega}$ for Cruciform $C_{22}$


Figure P~2. Dimensionless Time Periods for Runs in the Cruciform $C_{22}$



Figrse P-4. Dimensionless Time Periods for Runs in the Cruciform $C_{33}$


[^0]:    * These two features of the flow field model distinguish it from the model of Hanna and Hoecker [163], who, as already noted in Section 2.4, employed a model which contained no mean translational motion and was spatially homogeneous.

[^1]:    * Notice should be taken that the direction of lateral drift when $\bar{v} \neq c$ depends upon the flow field model. Thus the inequalities presented in Equation (5-7) might be reversed in some cases.

[^2]:    * It is not sufficient to calculate $k$ according to the relation, $k=\omega / c$, because this relation is based on the assumption that THF holds.

[^3]:    * This condition is not necessarily satisfied with a CVB

[^4]:    * The condition of small Re ( 0.1) is not necessarily satisfied with a CVB.

[^5]:    * This reduction from eight to five dimensionless groups is possible in part, because of the manner in which $\Pi_{6}, \Pi_{7}, \Pi_{8}, \Pi_{9}$, and $\Pi_{11}$ occur in the governing equations.

[^6]:    * The first term in the series expansion of $B(k, \omega ; Z)$ is first-order because $B(k, \omega ; Z)$ itself represents a perturbation and is firstorder. Thus the only first-order term in the product, $B(k ; \omega ; Z) e^{i k X_{1}}$ is the product of the first terms of the two series.

