NASA CONTRACTOR REPORT



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ANALYSIS AND COMPILATION OF MISSILE AERODYNAMIC DATA

Volume I - Data Presentation and Analysis

James O. Nichols

NASA CR-2835

Prepared by AUBURN UNIVERSITY Auburn, Ala. 36830 for Langley Research Center

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	e) Slideslip derivativ	es, C _{ng} , C _{lg} , and C _l	'в .							
	f) Control effectivene	ss, $C_{m_{\delta}}$, $C_{n_{\delta}}$, $C_{\ell_{\delta}}$, a	and $C_{\gamma_{\delta}}$.							
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FOREWORD

The declassification of a number of technical documents which contain missile aerodynamic data and the need to facilitate the dissemination of this data to potential users prompted the work reported herein.

It was felt that the task could have educational benefits to senior level aerospace engineering students and could be incorporated into their regular academic work. Those students who participated received academic credit for Aeronautical Problems 1 and 2; Aerospace Design 1 and 2; and Missile Aerodynamics. Participation was on a volunteer basis since the Problems and Design courses are individual effort type laboratory courses and Missile Aerodynamics is a senior level technical elective. Altogether some 15 to 20 students have been involved.

A grant from the National Aeronautics and Space Administration provided the necessary funds for class materials, field trips, and for preparation and publication of the report. Mr. Leroy Spearman of NASA's Langley Research Center has served as Technical Officer for this grant and provided the documents which were used.

This final report, Analysis and Compilation of Missile Aerodynamic Data, is presented in two volumes. Volume I contains the analysis and compilation of data and Volume II, which will be compiled by Dr. John E. Burkhalter, will contain the results of some performance analyses based on the data.

An interim report was submitted December 31, 1974, which contained a compilation of the longitudinal data. The interim report has received

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some distribution, thus some errors that exist in that report and in the original technical documents will be pointed out here. These errors have been corrected in this final report.

- 1) A typographical error in the ABSTRACT of the Interim Report lists the pitch control effectiveness as $C_{m_{\alpha}}$. It should be $C_{m_{\alpha}}$.
- 2) The model drawing from TM X-3070 shown in the Interim Report shows the distance from the nose to the canard hinge line to be 12.60 centimeters. It should be 15.60 centimeters.
- 3) The plot of $C_{m_{\delta}}$ for TM X-3070 is incorrect in both the Interim Report and TM X-3070. The data shown bases the pitching moment coefficient on body length instead of body diameter as stated in SYMBOLS. The plot of $C_{m_{\delta}}$ in this final report has been corrected to use body diameter as the reference length.
- 4) The aerodynamic-center locations, X_{ac}/ℓ , were shown as percentages for the configurations in TM X-1839, TM X-2289, and TM X-2491 in the Interim Report.
- 5) The summary plot of longitudinal parameters in TM X-1332 and the Interim Report incorrectly show $C_{m_{e}}$ to be negative.
- 6) The conversion of reference area and length were inadvertently omitted for C in the summary plot of data from m_{δ} RM L58C19 in the Interim Report.
- 7) The decimal point was omitted in the base axial-force coefficient data in TM X-2367.

The summary data have been checked a number of times in order to reduce the number of errors which will appear in this final report.

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Finally, I want to express my appreciation to Mrs. Marjorie McGee, secretary in the Aerospace Engineering Department, Auburn University, for typing this report.

Auburn, Alabama

James O. Nichols

SUMMARY

This summary document was prepared in order to facilitate dissemination of a large amount of missile aerodynamic data which has recently been declassified. Only summary data are presented in this report, but a list of reference documents provides sources of detailed data.

Most of the configurations considered are suitable for highly maneuverable air-to-air or surface-to-air missiles; however, data for a few air-to-surface, cruise missile, and one projectile configuration are also presented.

The Mach number range of the data is from about 0.2 to 4.63; however, data for most configurations cover only a portion of this range. The following aerodynamic characteristics at various Mach numbers and zero angle of attack are presented:

- a) Base drag coefficient, C_{D.b}.
- b) Drag coefficient, C_{D.0}.
- c) Lift-curve slope, C_L.
- d) Aerodynamic-center location, X_{ac}/l .
- e) Sideslip derivatives, $C_{n_{\beta}}$, $C_{\ell_{\beta}}$, and $C_{Y_{\beta}}$. f) Control effectiveness, $C_{m_{\delta}}$, $C_{n_{\delta}}$, $C_{\ell_{\delta}}$, and $C_{Y_{\delta}}$.

The maximum lift-drag ratio is also presented for some configurations.

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SYMBOLS

Α	body maximum cross-sectional area, $\pi d^2/4$
с _А	axial-force coefficient, $\frac{Axial force}{qA}$
с _р	drag coefficient, $\frac{\text{Drag}}{\text{qA}}$
C _{D,b}	base drag coefficient at $\alpha=0^\circ$, Base drag at $\alpha=0^\circ$ qA
с _{D,0}	drag coefficient at $\alpha=0^{\circ}$
C ^L	lift coefficient, $\frac{\text{Lift}}{qA}$
с _г	lift-curve slope at $\alpha=0^{\circ}$, per deg.
C _L	rolling-moment coefficient, Rolling moment qAd
C _{lo}	effective-dihedral parameter, per deg.
Cl	lateral (roll) control effectiveness, per deg.
° C _m	pitching-moment coefficient, Pitching moment qAd
C _m	slope of pitching-moment curve at $\alpha=0^{\circ}$, per deg.
C _m	pitch control effectiveness at $\alpha=0^{\circ}$, per deg.
с _N	normal-force coefficient, Normal force qA
с _N	normal-force-curve slope at $\alpha=0^{\circ}$, per deg.
с _N	variation of normal-force coefficient with pitch control surface deflection at $\alpha=0^\circ$, per deg.
C _n	yawing-moment coefficient, Yawing moment qAd
C _{n_e}	directional stability parameter, per deg.
C,	directional control effectiveness, per deg.
° C _Y	side-force coefficient, $\frac{\text{Side force}}{qA}$

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с _ү	side-force parameter, per deg.
с _ұ	variation of side-force coefficient with directional control surface deflection, per deg.
d	maximum body diameter
(L/D) max	maximum lift-drag ratio
L.	body length
M	free-stream Mach number
m/m _∞	mass-flow ratio
q	free-stream dynamic pressure
x,y,z	orthogonal set of body axes
x _s ,y _s ,z _s	orthogonal set of stability axes
X _{ac} /l	aerodynamic-center of lift location referenced to body length, positive aft from the nose
x _{mc} /l	moment center location referenced to body length, positive aft from the nose
α	angle of attack, deg.
β	sideslip angle, deg.
δ	angle of control surface deflection, positive trailing edge down or to left looking upstream, deg.
φ	angle of roll, deg.
Subscripts	• •
a	aileron
C	canard
F	flap
roll	indicates deflection of lateral control surfaces

yaw indicates deflection of directional control surfaces

Subscripts are used when there may be some confusion about which control surface is being deflected.

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INTRODUCTION

Recently a number of technical documents containing missile aerodynamic data published by the Langley Research Center of the National Aeronautics and Space Administration have been declassified. In order to facilitate dissemination of the data contained in these documents, this summary report was prepared. It was not intended that all of the original data be included, only summary plots of curve slopes and data suitable for comparison of the relative merits of the various configurations considered. A list of the reference documents is included to provide a source of more detailed data for configurations of interest.

Some of the documents summarized were not previously classified but were included to give a more complete coverage of the configurations that have been tested at Langley. In all, thirty documents have been summarized. Some of these were themselves compilations of data that had been reported previously. Data from one of the documents, TM X-348, has not been included herein because of its limited scope, and because of the difficulty in presenting summary data for the numerous configurations tested. It is primarily a report of a parametric study of the static stability characteristics of a series of cone-cylinder bodies with various afterbody configurations-flares, fins, and boattails.

Most of the configurations reported herein are suitable for highly maneuverable air-to-air or surface-to-air missiles; however, data for a few air-to-surface, cruise missile, and one projectile configuration are also presented. The Mach number range of the data is generally from about 1.5 to 4.63; however, data for some configurations extend to subsonic Mach numbers.

APPARATUS AND TESTS

The data summarized in this report were obtained originally in the Langley 8-foot transonic pressure tunnel and the Langley Unitary Plan wind tunnel. These tunnels are variable-pressure, continuous flow facilities. The 8-foot tunnel has a slotted test section which is about 2.44 meters square and has a Mach number range from about 0.20 to 1.30.

The Unitary Plan wind tunnel has two test sections, each about 1.22 meters square and about 2.13 meters long. The nozzle leading to each test section is of the asymmetric sliding block type which permits a continuous variation in Mach number from about 1.47 to 2.86 in the low Mach number test section and from 2.3 to 4.7 in the high Mach number test section.

The Reynolds number at which the tests were conducted varied from about 6.56 x 10^6 per meter to 9.84 x 10^6 per meter. Boundary-layer transition strips were used on the models.

Aerodynamic forces and moments were measured by means of a sixcomponent electrical strain-gage balance located within the model and, in turn, rigidly fastened to a sting-support system. Angles of attack were corrected for sting and balance deflection due to aerodynamic loads and for tunnel airflow misalignment. The results have been adjusted to correspond to free-stream static pressure acting over the model base.

Since cruciform configurations may fly with wings in the vertical and horizontal planes or with wings in 45° planes, data at both $\phi = 0^{\circ}$ and $\phi = 45^{\circ}$ are presented for many of these configurations. The longitudinal aerodynamic characteristics were similar in both attitudes except for increased pitch control effectiveness at $\phi = 45^{\circ}$ due to deflection of four surfaces instead of two.

METHOD OF DATA PRESENTATION

The following aerodynamic characteristics at various Mach numbers and zero angle of attack are presented in this report:

- a) Base drag coefficient, C_{D.b}.
- b) Drag coefficient, C_{D.0}.
- c) Lift-curve slope, $C_{L_{\gamma}}$.
- d) Aerodynamic-center location, $X_{ac}^{/l}$.
- e) Sideslip derivatives, $C_{n_{\beta}}$, $C_{\ell_{\beta}}$, and $C_{Y_{\beta}}$.
- f) Control effectiveness, $C_{m_{\delta}}$, $C_{n_{\delta}}$, $C_{\ell_{\delta}}$, and $C_{Y_{\delta}}$.

Cross coupling effects at zero angle of attack are presented for a few cases where they were not negligible. Maximum lift-drag ratios are also shown for some configurations.

Maximum body cross-sectional area and maximum body diameter are used as reference area and length, respectively, for the aerodynamic coefficients in this report. In one case (TM X-1538) where the body was not a body of revolution, the maximum frontal area and an equivalent maximum body diameter are used. Care should be exercised when comparing the data in this report with that in the original documents since conversion of some data was necessary because different reference areas and lengths were used.

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The longitudinal aerodynamic characteristics are presented relative to a stability-axis system while directional and lateral characteristics are relative to a body-axis system. Figure 1 shows the axes systems. In one case (TM X-846) there was insufficient data to convert to the stability-axis system. In that one case, the longitudinal data are also presented relative to the body-axis system. The moment reference center is shown on each model drawing included in the Data Summary. Drawings of model configurations were generally duplicated directly from the original reports; thus, not all model dimensions are given in the International System of Units (SI). In some cases where new drawings were necessary, model dimensions were converted to the SI system.

The aerodynamic-center location, X_{ac}/ℓ , is referenced to body length and measured positive aft from the nose. It was calculated with the following equation when it was not included in the original reports

$$X_{ac}/\ell = - (C_{m_{\alpha}}/C_{L_{\alpha}})(d/\ell) + (X_{mc}/\ell)$$

where X is the distance from the nose to the moment center, d is maximum body diameter, and l is body length.

The data are shown in the Data Summary plotted against Mach number except in cases where data for only one or two Mach numbers were available. In those cases the data are presented in tabular form. Each data summary contains a reference to the original report from which the data were taken. A complete list of the reports summarized is given in the last section of this report.

The order in which the data are presented for each configuration is as follows. A model drawing is followed by the longitudinal characteristics, $C_{m_{\delta}}$, $C_{D,o}$, $C_{D,b}$, $C_{L_{\alpha}}$, $(L/D)_{max}$, and X_{ac}/ℓ . All of these characteristics are evaluated at zero angle of attack except $(L/D)_{max}$. Variation of sideslip derivatives $C_{n_{\beta}}$, $C_{\ell_{\beta}}$, and $C_{Y_{\beta}}$ are shown next for those configurations for which these data are available. Table 1 is a listing of the original reports which contain directional and lateral data. Finally, directional and lateral control effectiveness parameters are presented. Cross coupling is generally negligible at zero angle of attack but is shown for those cases where it is not negligible.

The method of calculating $C_{l_{\delta}}$ varies widely among the original reports and care must be exercised when comparing various configurations. In some cases the roll control deflection is the algebraic difference (absolute sum) of the surface deflections, while others use the average of the deflections. In this report all the control data have been presented in terms of the average of the surface deflections. Since, for roll, the control surfaces are deflected differentially but equally in magnitude, the average deflection is equal to the magnitude of deflection of the individual control surface. The sign convention also varies but in this report positive deflection gives positive rolling moment.

Unless indicated otherwise, $C_{n_{\delta}}$ means the change in yawing moment coefficient per degree of deflection of the directional (yaw) control surfaces. $C_{l_{\delta}}$ is the change in rolling moment coefficient per degree of deflection of the lateral (roll) control surfaces, and $C_{Y_{\delta}}$ indicates the change in side force coefficient per degree deflection of the

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directional control surfaces. Cross coupling is usually indicated by a subscript; e.g., $C_{\ell_{\delta_{yaw}}}$, which means the change in rolling moment coefficient per degree of deflection of the directional (yaw) control surfaces. In some of the data tables the subscripts are omitted and the column headings indicate the appropriate control surface. Subscripts are used also to indicate the control surface used to produce a control moment when there may be more than one set of control surfaces which could be used for pitch and roll. A pitching control effectiveness $C_{m_{\delta_{c}}}$ or $C_{m_{\delta_{F}}}$ would indicate the change in pitching moment coefficient per degree deflection of the canards or wing flap, respectively. Rolling moment effectiveness $C_{\ell_{\delta_{c}}}$ or $C_{\ell_{\delta_{a}}}$ would indicate the change in rolling moment coefficients per degree deflection of the canards or the canards or ailerons, respectively.

DATA ANALYSIS

Linearity of data - The range at angle of attack for which the data can be assumed to be linear varies from $\pm 2^{\circ}$ for some configurations to $\pm 12^{\circ}$ for others. The lift-curve slopes tend to increase with angle of attack while they decrease with increasing Mach number at supersonic speeds. The slope of the pitching-moment curve in some cases increases with angle of attack, while in others it decreases. In all cases $C_{m_{\alpha}}$ decreases with increasing Mach number.

The nonlinearity of the data makes the use of curve slopes to calculate missile performance questionable when used over a complete trajectory. Missile performance calculations would be more accurate if equations representing the aerodynamic characteristics as functions of Mach number and angle of attack were used. The nonlinearity of the data

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contained in the original reports is such that it should not be difficult to formulate equations to fit the data.

Effects of wing planform shape, size, and location - Some of the original documents were reports of design studies in which various configuration parameters were investigated. For example, TM X-1839 reports the results of an investigation of the effects of wing planform shape, size, and location. The planform shapes tested were delta, rectangular, and cranked. The sizes were classified as small, mid, and large; however, only the midsized cranked wing was tested. The location of the rectangular wing was also varied. The summary included in this report contains only the data for the three mid-sized wings.

<u>Canards and tail control surfaces</u> - Two of the original documents compared canard and tail control surfaces. TM X-1834 reports the results of an investigation of the effects of various longitudinal positions of canard control surfaces and tail control surfaces on the same wing-body combination. Also included in the report are the effects of the various components on the aerodynamic characteristics. In this summary report only the data for one canard configuration and one tail configuration from TM X-1834 are included. In TM X-2780, the body is the same for the canard configuration and the tail configuration but the wings are different. The effect of a blunt or conical forebody is also reported. It was found that differentially deflected canard controls were not effective as roll control devices because a control reversal resulted at low angles of attack. The tail control surfaces were effective as roll control devices; however, some adverse yawing moments did result.

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Various tail control configurations - An investigation of various tail-control surface configurations was reported in TM X-71984. The tail-control configurations investigated were the cruciform inclined 45° to the horizontal and vertical planes, the conventional airplane type with an upper vertical fin and the inverted type with lower vertical fin. The cruciform tail configuration exhibits the greatest pitch-control effectiveness; however, relatively large nonlinear pitching moment characteristics are experienced due to the effects of the wing wake. The lower vertical fin shows a substantial increase in control effectiveness as angle of attack is increased, whereas the configuration with the upper vertical fin exhibits a small decrease.

A summary of the configurations considered in the original documents is given in the next section. Not all the configurations are shown, only typical examples. These examples were chosen on the basis of various configuration classification such as:

- a) Wing planform shape.
- b) Wing arrangement cruciform or monoplane.
- c) Control surfaces wing, tail, or canard. Hinge lines are shown as dashed lines.
- d) Surface arrangement in-line or interdigitated.

With each configuration the reference documents which contain data for that configuration and the page numbers of this report where the summary data is presented are listed.

These configurations are grouped according to the missions for which they were originally designed. Arrangement of Data Summary follows the same plan as the Summary of Configurations.

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SUMMARY OF CONFIGURATIONS

AIR-TO-AIR



TM X-3070 18-20

SUMMARY IN THIS

REPORT ON PAGES

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SURFACE-TO-AIR OR AIP-TO-AIR



TM X-1839, TM X-2289 21-28



TM X-1839 21-	-23
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TM X-2491

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TM X-1309, TM X-1352,

PAGES

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REFERENCE

TM X-2780, TM X-1834 38-45









TM X-187 46-47

TM X-1184, TM X-1332 48-51



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SURFACE-TO-AIR



AIR-TO-SURFACE



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TM X-1112 68-71

TM X-1491

72-73





REFERENCE PAGES TN D-7069 80-82





TM X-1304 83-87

1. 1. E. E.

TM X-1538 88-91



PROJECTILE



TM X-2831

103-104





	SI	DESLI	Р	YAW	CONT	ROL	ROLL	CONT		
REPORT NO.	C _n β	с _г	$c_{\gamma_{\beta}}$	C _n	с _г	с _ү	с _{пб}	C _l	с _ү	REMARKS
RM L58C19	\checkmark		\checkmark							1
TM X-187	\checkmark	\checkmark	\checkmark		7	\checkmark	\checkmark	_ /	\checkmark	2,3
TM X-1025	\checkmark	\checkmark	\checkmark	\checkmark	/	\checkmark				4
TM X-1112	\checkmark	V		\checkmark	$\overline{}$	\checkmark	\checkmark	<u>√</u>	\checkmark	3,5,6
TM X-1184	\checkmark	\checkmark	\checkmark		√		\checkmark	\checkmark	\checkmark	3,7,8
TM X-1304	√	√	1	\checkmark	\checkmark	\checkmark	$\overline{}$	\checkmark	\checkmark	5,9
TM X-1309	✓	\checkmark	\checkmark	\checkmark	/	\checkmark	\checkmark	\checkmark	\checkmark	3,10
TM X-1332	7	✓	\checkmark	\checkmark	√	\checkmark	\checkmark	√	\checkmark	3,7,8
TM X-1352	/	$\overline{}$	\checkmark	1		7	\checkmark	$\overline{}$	\checkmark	3,10
TM X-1416	\checkmark	\checkmark	\checkmark				\checkmark	- / -	\checkmark	3,11
TM X-1491				\checkmark		7				12
TM X-1492	√	$\overline{}$	$\overline{}$				\checkmark	7	1	2,3
TM SX-1531	\checkmark		\checkmark					\checkmark	\checkmark	10
TM X-1538	√	7		7	$\overline{\mathbf{v}}$	\checkmark	\checkmark	V	\checkmark	3
TM X-1834	✓	7	7							
TM X-1839		7								
TM SX-1961	$\overline{}$	7						\checkmark	\checkmark	3,5,10
TM X-2289		\checkmark	\checkmark							
TM SX-2299	$\overline{}$	7	\checkmark				\checkmark	\checkmark	\checkmark	3,5,10
TM X-2780				\checkmark	\checkmark	\checkmark	√	V	\checkmark	3,5
TM X-3070				$\overline{}$	$\overline{}$	\checkmark	$\overline{}$	1	V	3
TM X-71984		$\overline{}$		$\overline{}$	$\overline{}$	\checkmark	\checkmark	7	\checkmark	13
TN D-7069		$\overline{}$	\checkmark							

TABLE 1. DIRECTIONAL AND LATERAL STABILITY AND CONTROL DATA CONTAINED IN REFERENCE REPORTS

1. Data for one Mach number only, not included in this report,

2. Data for one Mach number only, table included in this report.

3. Cross coupling negligible at $\alpha=0^{\circ}$.

4. Vertical-tail surfaces were deflected in combination with horizontal-tail deflection.

5. Measurements of control surface hinge moments included in Reference.

6. Lateral and directional control provided by movement of the two vertical tail surfaces.

7. Lateral control provided by deflection of all four wings.

8. Cross coupling adverse at angle of attack.

9. Reference report also shows effect of mass flow rate through nacelle.

10. Lateral control provided by differential deflection of wing flaps.

- 11. Differential deflection of all four tails used to produce roll.
- 12. Control wings effective in providing increments in normal force and side force with essentially no effect on yawing or pitching moments.

13. Cross coupling in roll negligible.

DATA SUMMARIES

AIR-TO-AIR MISSILES (AAM)





Model details. Dimensions are in inches unless otherwise noted.

Ref. TM X-846

TABLE 2. - LONGITUDINAL PARAMETERS; $\alpha \simeq 0^{\circ}$.

	M = 1	2.30	M = 4.60					
	φ=0°	φ≖45°	φ=0 °	φ=45°				
$c_{N_{\alpha}}$	0.592	0.568	0.454	0.373				
$c_{m_{\alpha}}$	-0.643	-0.440	-0.421	-0.146				
$\frac{X_{ac}}{l}$	0.586	0.569	0.577	0.547				
c_{m_δ}	0.267	0.427	0.026	. 0.090				
$c_{N_{\delta}}$	0.208	0.294	0.117	0.166				

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DIAMOND AIRFOIL

WEDGE AIRFOIL

	M =	2.30	M = 4.60				
	φ=0°	φ=45°	φ=0°	φ=45 °			
$c_{N_{\alpha}}$	0.568	0.547	0.424	0.374			
$c_{m_{\alpha}}$	-0.589	-0.507	-0.626	-0.345			
$\frac{X_{ac}}{\ell}$	0.584	0.577	0.608	0.577			
с _т	0.361	0.463	0.030	0.066			
$c_{N_{\delta}}$	0.199	0.304	0.145	0.210			

Ref. TM X-846

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Ref. TM X-3070





Ref. TM X-3070

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SURFACE-TO-AIR MISSILES (SAM)

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OR

AIR-TO-AIR MISSILES (AAM)





Figure 7. - Variation of longitudinal parameters with Mach number; $\alpha \approx 0$, $\phi=0$, mid-sized wings.

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Figure 8. - Variation of sideslip derivatives with Mach number; $\alpha \approx 0^{\circ}$, $\phi = 0^{\circ}$, mid-sized wings.

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Nose 3 (hemispherical nose)

Figure 9. - Drawing of model showing nose shapes investigated. Linear dimensions are given in centimeters and parenthetically in inches.

Ref. TM X-2289





Ref. TM X-2289

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Ref. TM X-2289

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Figure 12. - Variation of sideslip derivatives with Mach number; $\alpha \approx 0^{\circ}$, $\phi = 0^{\circ}$.













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Body station







Small booster

Figure 14 - Concluded.



Figure 15 - Variation of longitudinal parameters with Mach number; $\alpha \simeq 0^{\circ}$.



Ref. TM X-1309, TM X-1352

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Figure 17. - Variation of longitudinal parameters with Mach number; $\alpha \simeq 0$?

Ref. TM X-1309, TM X-1352

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Figure 18. - Variation of sideslip derivatives with Mach number; $\pm 0^{\circ}$.

Ref. TM X-1309, TM X-1352







Figure 19. - Directional and lateral control effectiveness: < 0°. Ref. TM X-1309, TM X-1250





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Figure 24. - Variation of longitudinal parameters with Mach number; $\alpha{\simeq}0.$ Ref. TM X-2780



Figure 25. - Directional and lateral control effectiveness of canard configuration with blunted ogive nose; $\alpha \approx 0^{\circ}$.





(a) Complete model.





Figure 27. - Variation of longitudinal parameters with Mach number; $\alpha \simeq 0$.

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Figure 28. - Variation of sideslip derivatives with Mach number; $\alpha{\simeq}0^\circ.$ Ref. TM X-1834



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TABLE 3. - LONGITUDINAL PARAMETERS AT MACH NUMBER 4.65; $\alpha{\simeq}0\,^\circ$

CCNFIGURATION	с _т	C _{D,0}	с _г а	$\frac{X_{ac}}{\ell}$
Delta Fins and Trailing-Edge Controls	-0.017	0.12	0.134	0.637
Large Canard Controls with Flared Skirt	0.166	0.36	0.175	0.593
Small Canard Controls with Flared Skirt	0.143	0.34	0.150	0.583
Small Canard Controls without Flared Skirt		0.18	0.105	0.445

TABLE 4. - SIDESLIP DERIVATIVES AT MACH NUMBER 4.65; $\alpha{\simeq}0^\circ$

CONFIGURATION	c _{n_β}	$c_{\mathcal{I}_{\beta}}$	c _{y_β}	
Delta Fins and Trailing-Edge Controls	-0.266	0	-0.153	
Large Canard Controls with Flared Skirt	-0.418	0	-0.186	
Small Canard Controls with Flared Skirt	-0.390	0	-0.177	
Small Canard Controls without Flared Skirt	-0.433	0	-0.134	

TABLE 5. - DIRECTIONAL AND LATERAL CONTROL EFFECTIVENESS AT MACH NUMBER OF 4.65; $\alpha{\simeq}0^\circ$

CONFIGURATION	° _n	$c_{\mathcal{I}_\delta}$	C _{Y Cy} Cy roll yaw
Delta Fins and Trailing Edge Controls	-0.0133	0.008*	-0.020* 0.0067
Small Canard Controls with Flared Skirt		0.026†	-0.015 ⁺

* All four control surfaces used for roll.

 † Only two vertical canards used for roll.

Ref. TM X-187

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Figure 30. - Details of model. Linear dimensions are in inches (values within parentheses are centimeters).

Ref. TM X-1184, TM X-1332

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Figure 31. - Variation of longitudinal parameters with Mach numbers; $\alpha \approx 0$.

Ref. TM X-1184, TM X-1332







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Figure 36. - Variation of sideslip derivatives with Mach number; $\alpha{\simeq}0\,^\circ.$

Ref. TM X-71984





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SURFACE-TO-AIR MISSILES (SAM)





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Figure 39. - Variation of longitudinal parameters with Mach number; $\alpha{\simeq}\,0^\circ.$ Ref. TM X-1025

















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Figure 44. - Variation of sideslip derivatives and roll control effectiveness with Mach number; $\alpha \simeq 0^\circ$.



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(a) Model details.

Figure 47. - Drawing of model. All dimensions are in centimeters unless otherwise noted.



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Figure 48. - Variation of longitudinal parameters with Mach number; $\alpha^{\sim}0^{\circ}$.

AIR-TO-SURFACE MISSILES (ASM)











Figure 51. – Variation of sideslip derivatives with Mach number; $\alpha{\simeq}0^\circ$





Ref. TM X-1112





TABLE 6. – LONGITUDINAL PARAMETERS; $\alpha \simeq 0^{\circ}$.

Config-	Fin	C _{m_o}		C _D ,o		CLα		x	ac ^{/2}
uration	Sweep	φ=0°	φ=45°	φ=0°	φ=45°	φ=0°	φ=45°	φ=0°	φ=45°
BF ₁	65°			.380		.083		.617	.697
BF ₂	65°			.400	.398	.104	.108	.684	.697
BF ₂	30°			.565	.560	.114	.114	.702	.720
BF2W2	30°	012	016	.688	.69 0	.218	.227	.619	.619
BF_1W_1	30°	012	016	.610	.590	.174	.185	.606	.603

Mach Number 1.6

Mach Number 2.0

Config-	Fin	C _{m_δ}		C _D		CLa		Xac/l		
uration	Sweep	φ=0°	φ = 45°	φ=0°	φ=45°	φ=0°	φ=45°	φ=0 °	φ=45°	
BF ₁	65°			.36	.368	.075	.083	.581	.549	
BF ₂	65°			.38	.38	.100	.107	.630	.622	
BF ₂	30°	<u></u>		.508	.509	.110	.106	.683	.694	
BF ₂ W ₂	30°	0	.01	.628	.628	.194	.239	.609	.612	
BF1 ^W 1	30°	012	0	.542	.54	.161	.156	.590	.598	

Ref. TM X-1491

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(a) Basic model $W_2 I_1$.



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TABLE 7. - LONGITUDINAL PARAMETERS AT MACH NUMBER 2.5 WITH INLETS COVERED; $\alpha=0^{\circ}$.

$\phi = 0^{\circ}$

CONFIGURATION	c _{m_o}	C _{D,0}	$C_{L_{\alpha}}$	$\frac{X_{ac}}{\ell}$
Wing 1, Tail 1	-0.0829	0.247	0.155	0.611
Wing 1, Tail 1, Pop-out Fin	-0.0859	0.255	0.159	0.628
Wing 2, Tail l	-0.0933	0.245	0.124	0.581
Wing 3, Tail 1	-0.0773	0.242	0.125	0.602
Wing 3, Tail 1, End Plate	-0.0762	0.255	0.148	0.622
Wing 4, Tail 2	-0.0821	0.240	0.129	0.574

 $\phi = 45^{\circ}$

CONFIGURATION	с _т	C _{D,0}	$c_{L_{\alpha}}$	$\frac{X_{ac}}{\ell}$
Wing 1, Tail 1	-0.1176	0.250	0.146	0.603
Wing 1, Tail 1, Pop-out Fin	-0,1165	0.257	0.154	0.624
Wing 2, Tail 1	-0.1262	0.247	0.122	0.574
Wing 3, Tail 1	-0.1198	0.247	0.135	0.584
Wing 3, Tail 1, End Plate	-0.1142	0.256	0.150	0.614
Wing 4, Tail 2	-0.1128	0.243	0.128	0.563

Ref. TM X-1492 -76-

TABLE 8. - SIDESLIP DERIVATIVES AND ROLL CONTROL EFFECTIVENESS AT MACH NUMBER 2.5 WITH INLETS COVERED: $\alpha \approx 0^\circ$.

 $\phi = 0^{\circ}$

	Configuration	с _п _в	c _{Z_β}	с _ұ	^C _Z * roll
Wing	l, Tail l	.1008	0	147	
Wing	1, Tail 1, Popout Fin	.1568	0	163	.0118
Wing	2, Tail 1	.0560	0	137	.0127
Wing	3, Tail 1, End Plate	.1344	0	155	

 $\phi = 45^{\circ}$

Configuration	с _п	c _{Z_β}	c _{γ_β}	c ⁺ ζ _δ roll
Wing 1, Tail 1	.0974	0	142	
Wing 1, Tail 1, Popout Fin	.1456	0	152	.0235
Wing 2, Tail 1	.0482	0	125	.0252
Wing 3, Tail 1, End Plate	.1378	0	156	
Wing 4, Tail 2				.0224

* Horizontal tails were deflected.

+ All four tails were deflected.

Ref. TM X-1492

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Ref. TN D-7069





Ref. TN D-7069





Ref. TN D-7069







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Figure 61. - Variation of longitudinal parameters with Mach number; $\alpha \approx 0^\circ$. Cone-shaped fairing attached to nacelle inlet.



Figure 62. - Variation of sideslip derivatives with Mach number; $\alpha \approx 0^\circ$. Cone-shaped fairing attached to nacelle inlet.

	Yan	w Control	Roll Control ^{††}			
Mach No.	C _n	CZS	с _ү	с _п	C _Z	с _ү
1.80	161	.032	.040	.437	.102	075
2.00	215	.027	.040	.437	.075	118

TABLE 9. - DIRECTION AND LATERAL CONTROL EFFECTIVENESS;* $\alpha \approx 0^{\circ}$.

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* With cone-shaped fairing attached to nacelle inlet.

+ Yaw control provided by pylon rudder.

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++Roll control provided by differential deflection of tail fins.





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Figure 64. - Variation of longitudinal parameters with Mach number, configuration BW_1HV ; $\alpha \simeq 0^\circ$.





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Tail T2

(b) Vertical tails and canard.

Figure 67. - Concluded



Figure 68. - Variation of longitudinal parameters with Mach number; $\alpha \approx 0$.



Figure 69. - Variation of sideslip derivatives and roll control effectiveness with Mach number; α≃0°.

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W₂ Wing

Figure 70. - Concluded



Figure 71. - Variation of longitudinal parameters with Mach number; $\alpha{\simeq}0^{\circ}.$ Ref. TM SX-1961

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Figure 72. - Variation of sideslip derivatives and roll control effectiveness with Mach number; $\alpha \approx 0^\circ$.

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Ref. TM SX-2299



Figure 75. - Variation of sideslip derivatives and roll control effectiveness with Mach number; $\alpha \approx 0^\circ$.

Ref. TM SX-2299





Ref. TM X-2831



Figure 77. – Variation of longitudinal parameters with Mach number; $\alpha \approx 0^{\circ}$.

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