



Department of Aerospace Engineering
and Applied Mechanics
University of Cincinnati

COMPUTER PROGRAM FOR THE
ANALYSIS OF THE CROSS FLOW IN A
RADIAL INFLOW TURBINE SCROLL

BY

A. HAMED, S. ABDALLAH AND W. TABAKOFF

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SUMMARY

This report describes and explains the computer program that has been used to solve the governing equations of the potential flow in the cross-sectional planes of a radial inflow turbine scroll. The derivation of the governing equations and the description of the numerical solution can be found in NASA CR (to be assigned) Report entitled "Analysis of the Cross Flow in a Radial Inflow Turbine Scroll."

A list of the main program, the subroutines, and typical output example are included.

COMPUTER PROGRAM

The Fortran computer program, which is used to solve the equations of potential flow in the cross-sectional plane of the centrifugal machine's volute or scroll will be described and listed. The input data to this program includes information about inlet flow properties, the cross section geometry, and its corresponding boundary conditions, which are shown in Figures 1 and 2. The maximum allowable number of mesh lines in the x and y directions are 50 and 30, respectively. The program output includes an echo print of the input data. At each grid point, the value of the potential function, the velocity components in the x and y directions, as well as the magnitude of the velocity vector and the angle it makes with the x axis are printed. Additional output is obtained in the form of plots of constant potential function contours, and arrows showing the direction of the velocity in the axial-radial plane.

The logical relations of the main program and subroutines are shown in Figures A-1, A-2 and A-3. A brief description of the main program and subroutines is given below.

Main Program:

The main program is primarily used to call the subroutines. The logic flow diagram is illustrated in Figure A-1.

Subroutine IRL(J) :

It is called from the main program and the subroutines to determine IL(J) and IR(J), the first and last interior mesh points for the scroll cross-section at a given J mesh line (see Fig. A-4).

Subroutine INTPL(I) :

It is called from the main program and the subroutines to determine JL(I) and JU(I), the lower and the upper interior mesh points for the scroll cross-section at a given I mesh line (see Fig. A-4).

Subroutine MESH(I,J) :

It is called from the main program and the subroutines to identify the interior mesh point neighbors, calculate the coeffi-

clients of the five points Laplace difference operator, and to determine the most recent values of the potential functions at the interior mesh points.

Subroutine SHABAN:

It is called from the main program, to determine the source strength at every mesh point $F(I,J)$, for a given mass flow rate and through flow velocity profile. The logic flow diagram is illustrated in Figure A-2.

Subroutine AWATEF:

It is called from the main program to determine the values of the potential function, at each grid point. The logic flow diagram of this subroutine is illustrated in Figure A-3.

Subroutine BCSI(I):

It is called from the subroutine AWATEF, to determine the values of the potential function at the boundary points on a given I mesh line.

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Subroutine BCSJ(J):

It is called from the subroutine AWATEF, to determine the values of the potential function at the boundary points on a given J mesh line.

Subroutine HVVEL:

It is called from the main program to determine the values of the velocity components in the x and y directions, at every mesh point.

Subroutine ABDLAH:

It is called from the main program to calculate the magnitude of the velocity vector in the axial radial plane and the angle it makes with the x-axis.

Subroutine HOSNY:

It is called from the subroutine SHABAN to calculate the flow density at each grid point.

Subroutine PLTISO:

It is called from the main program to plot the contours of constant potential function.

Additional library subroutines, namely, PLOT (X1, X2, X3), SYMBOL (Y1, Y2, Y3, Y4, Y5, Y6), and ENDPLT, are called from the main program, and used in the plotting of both the potential contours and the velocity direction.

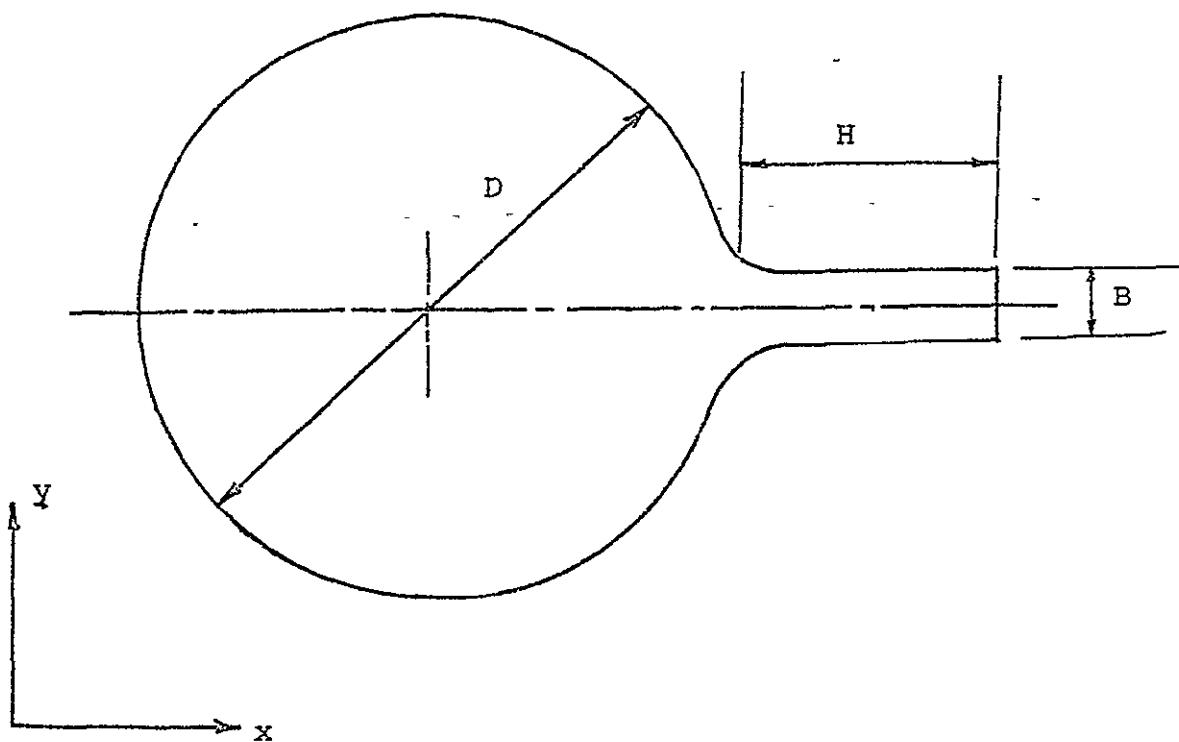


FIG. 1. SYMMETRIC SCROLL CROSS SECTION

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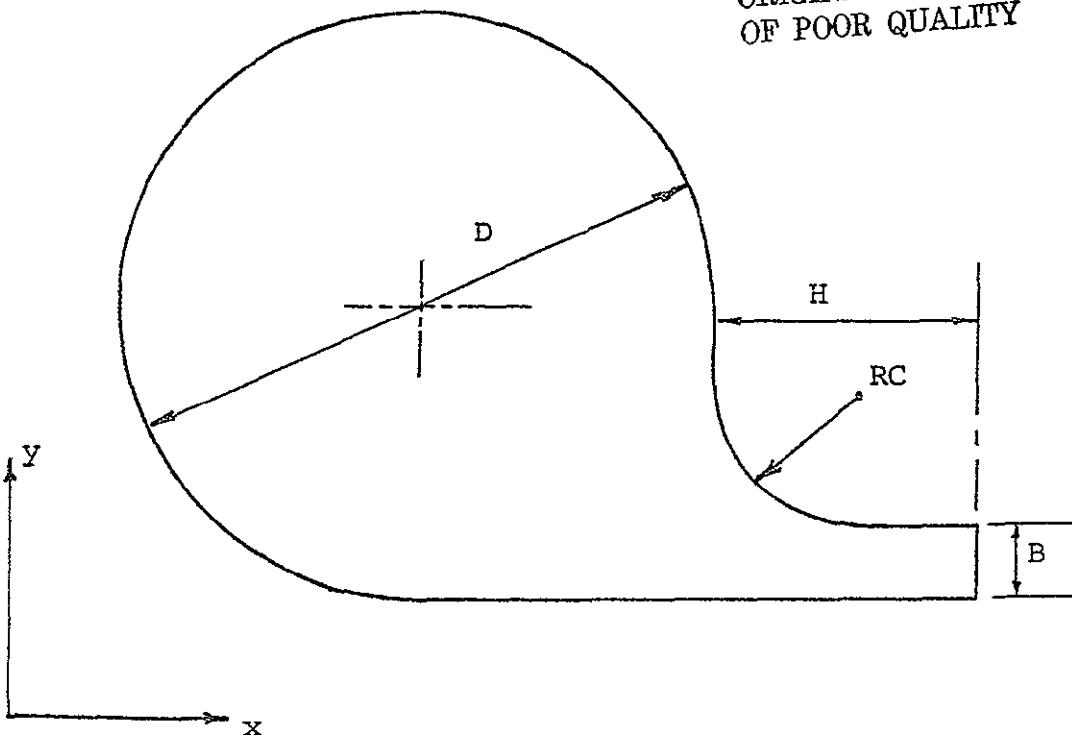


FIG. 2. NON SYMMETRIC SCROLL CROSS SECTION.

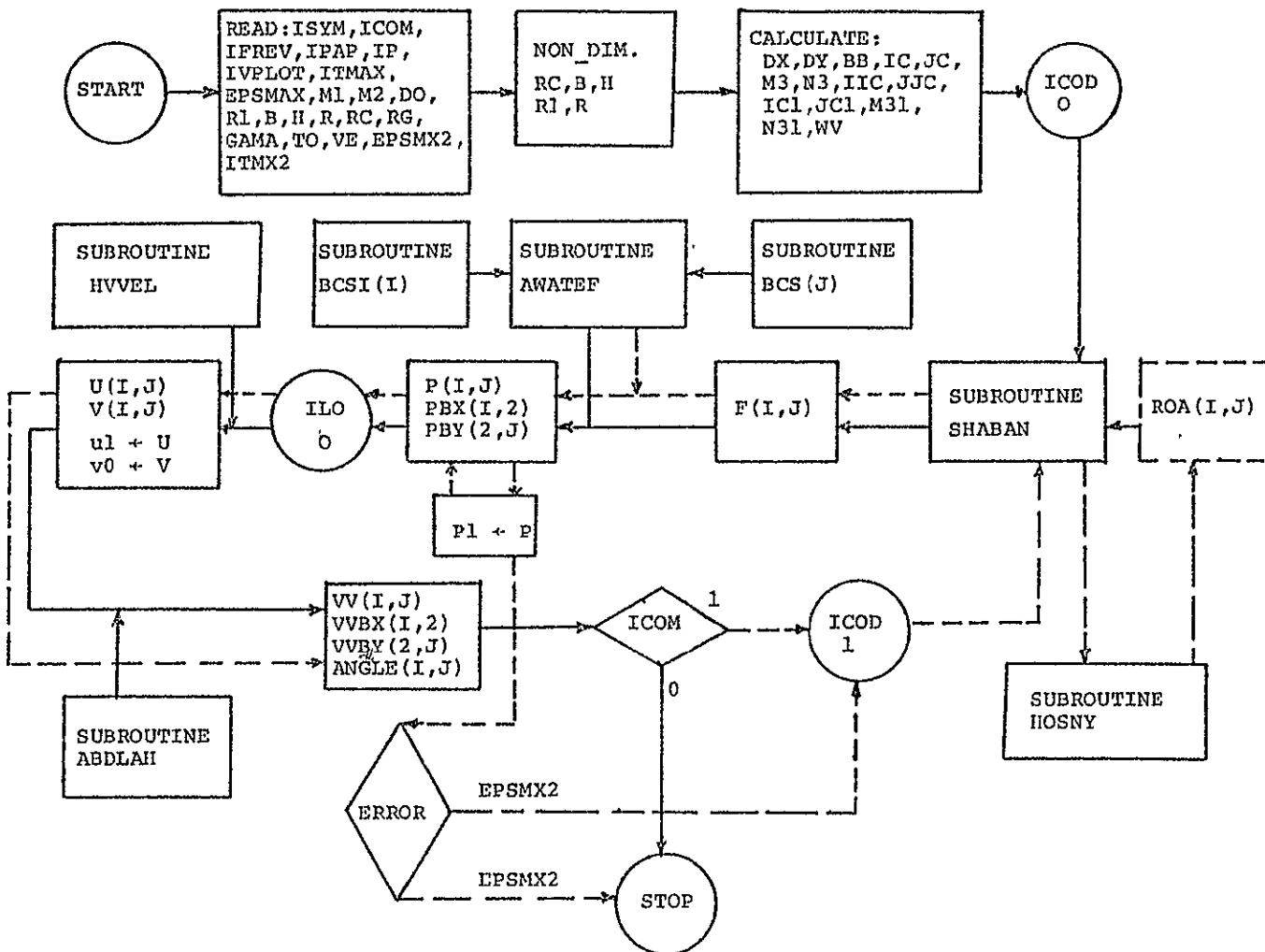


FIGURE (A-1) MAIN PROGRAM

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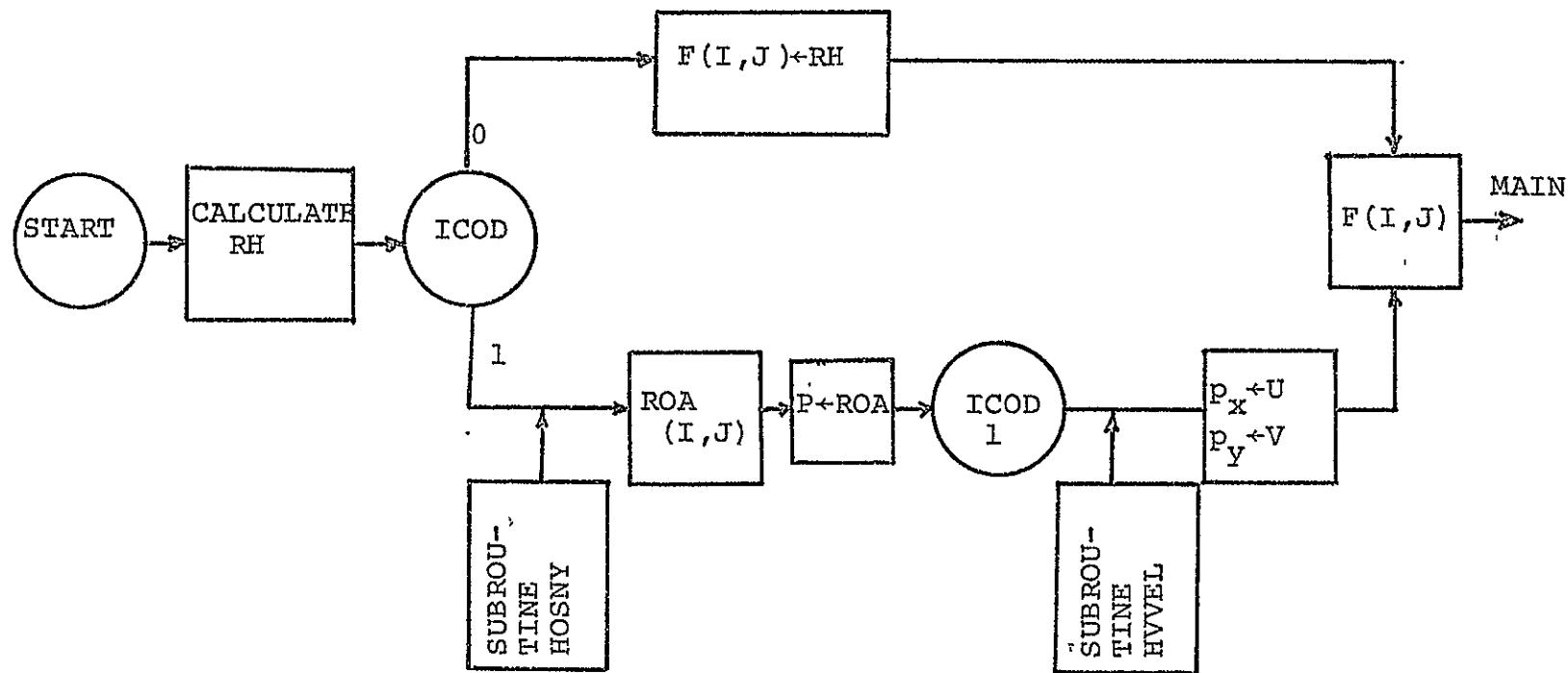


FIGURE (A-2) SUBROUTINE SHABAN

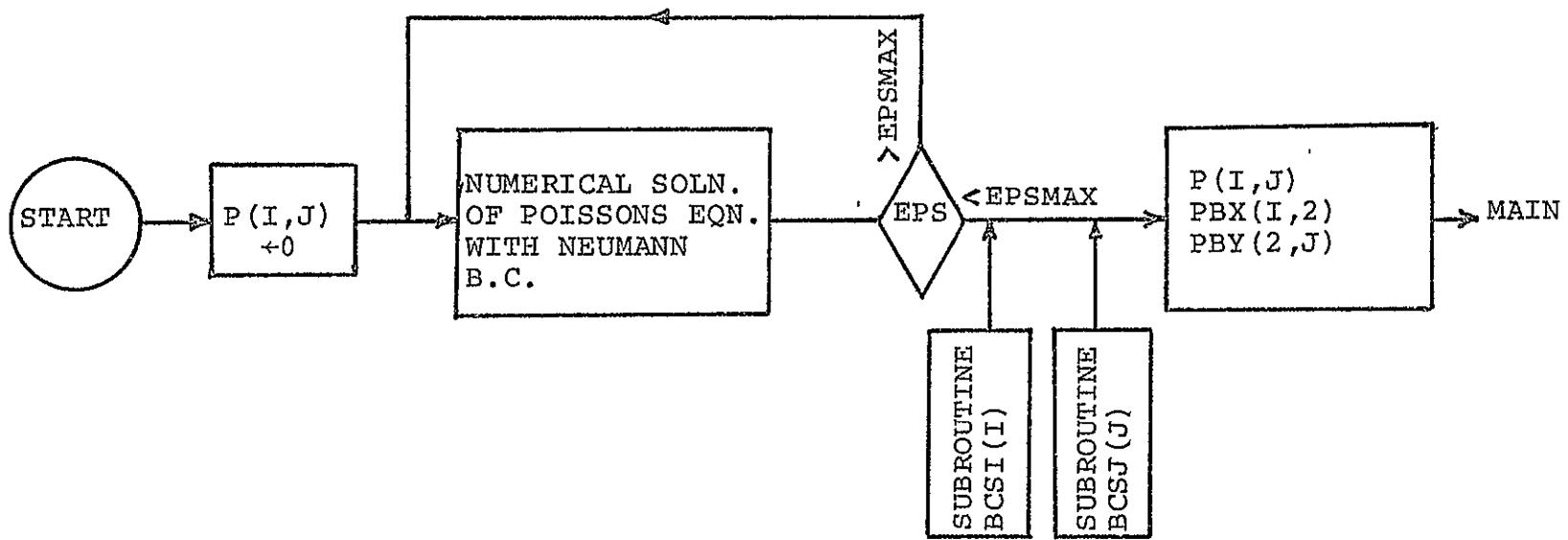


FIGURE (A-3) SUBROUTINE AWATEF

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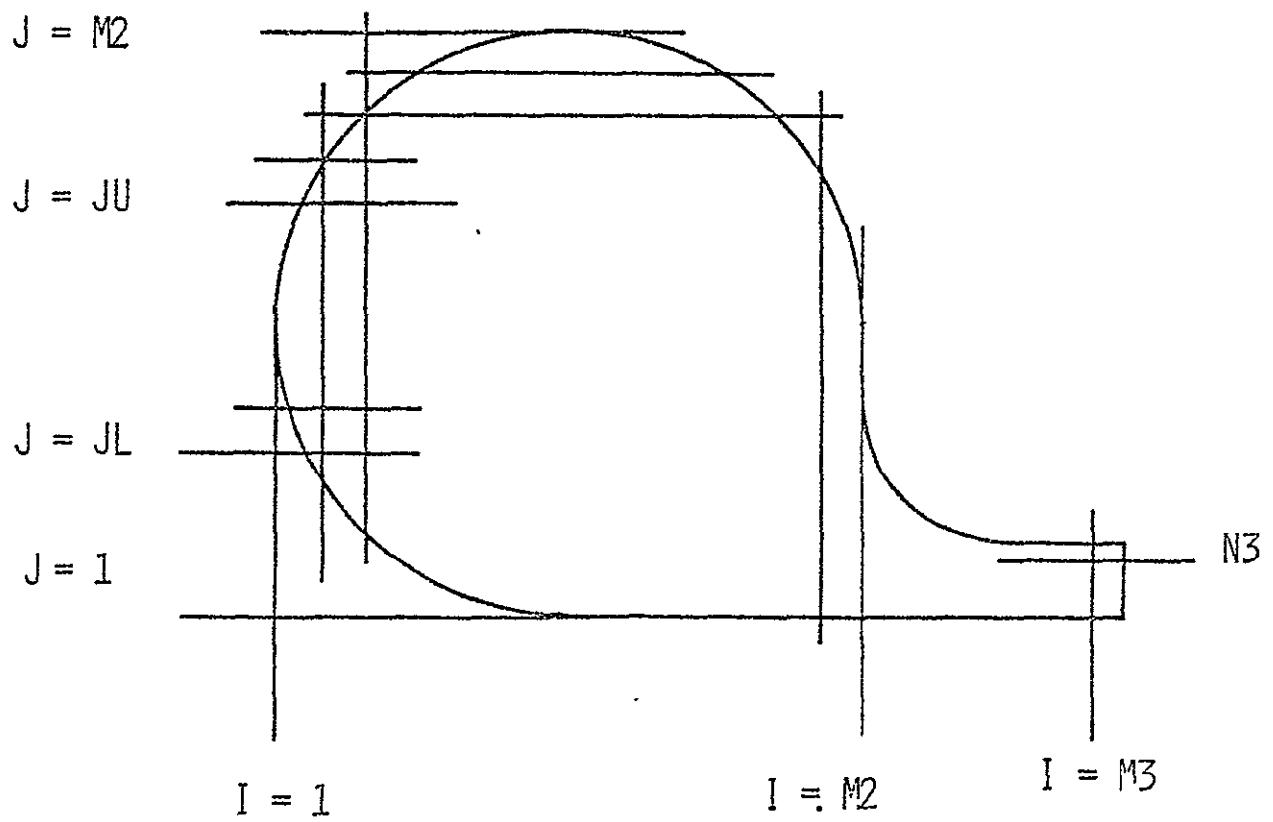


FIGURE (A-4)

DEFINITION OF SYMBOLS AND FORTRAN LISTING

<u>Symbols</u>	<u>Description</u>
B	Width of the scroll exit (Figs 1, 2).
DO	Scroll inlet diameter.
EPSMAX	The largest tolerable value of the square of the sum of the absolute values of the deviations of $\phi_{i,j}$ from their previously computed values.
F	Vector containing the values of Poisson's source strength at each grid point.
GAMA	Ratio of specific heats.
H	Length of scroll exit nozzle, Figs. 1 and 2.
ICOM	Parameter to control type of calculations. ICOM = 0 for incompressible flow and ICOM = 1 for compressible flow.
IFG, IPAP, IFREVO	Parameters to control the mass source distribution (i.e., the type of through flow velocity profile).
IP	Frequency of intermediate printout.— Solutions are printed after every IP iteration.
IPLT	Number of contours in the output plot for the potential velocity.
ISYM	Parameter to control type of scroll cross section. For symmetric cross-section ISYM = 1, and for unsymmetric cross-section ISYM = 0.
ITMAX	Maximum allowable number of iterations.
IVPLOT	Parameter to control plotting of program output, IVPLOT = 1, a plot is prepared; if IVPLOT = 0, no plot is prepared.
M1,M2,M3,N3	Number of mesh lines of the scroll cross-section, Fig. (A-4).

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<u>Symbols</u>	<u>Description</u>
P	Vector containing the values of the potential function ϕ at all grid points.
PBX,PBY	Vectors containing the values of ϕ on the scroll boundaries.
P_i ($i=0,1,2,3,4$)	The values of the potential function at the standard five points Laplace difference operator.
R	Radius of the scroll cross-section equal $D/2$, Figs. 1 and 2.
RC	Radius of exit portion of the unsymmetric cross-section, Fig. 3. (Ref. 1)
Rl	Radius of scroll exit .
RG	Gas constant.
ROA	Vector containing the values of the density at all grid points.
ROBX,ROBY	Vectors containing the values of the density at the boundary points.
THETA	Vector containing the values of the angle between the velocity vector \bar{V} , and the x-axis at each grid point.
TO	Stagnation temperature
U,V	Vectors containing the values of the flow velocity, components in the x and y directions, respectively.
UBX,UBY	Vectors containing the values of the velocity component in the x-direction at the boundary points of all I and J mesh lines.
VBX,VBY	Vectors containing the values of the velocity component in the y-direction at the boundary points of all I and J mesh lines.
VE	Scroll exit velocity in radial direction.

<u>Symbols</u>	<u>Description</u>
VISOBR	Numerical values of the velocity potential contours to be plotted as output.
VV	Vector containing the absolute values of the velocity vector \bar{V} , at each grid point.
VVBX,VVBY	Vectors containing the absolute values of the velocity vector \bar{V} , at the boundary points for each I and J mesh lines, respectively.
WO,WOP	Successive relaxation factors. WO for interior mesh points, and WOP for the points adjacent to the boundaries.

PROGRAM LISTING

```

* IV G LEVEL 21          MAIN          DATE = 7/26/83      21/45/41      PAGE 0001

- - - IMPLICIT REAL*8 (A-H,O-Z)
DIMENSION X(50,21),Y(50,21),VAR(50,21),VRR(50,21)
COMMON /ONE/ V1
COMMON /TAD/ ILD,IWR,ISYM,IPAP,ICOD,IP,ICOM
COMMON /FDR/ RI,RF,IFREVO
COMMON /DIMS/ R,RC+4,B,DX,DY,B1,BB
COMMON /FDIM/ M1,M2,IC,JC,IIC,JJC,43,N3
COMMON /MSH/ S1,S2,S3,S4,P1,P2,P3,P4,JL,JU,IL,IR
COMMON /PHI/ P(50,30),PB(2,30),PBX(50,2),PP(50,30),PBY(2,30),
1 PBX1(50,2),F(50,30)
COMMON /VEES/U(50,30),V(50,30),UBX(50,2),VBX(50,2),
1 UBY(2,30),VBY(2,30),U1(50,30),V0(50,30),UBX1(50,2)
1 ,VBX1(50,2),UBY1(2,30),VBY1(2,30),VV(50,30),ANGLE(50,30)
COMMON /CAL/ M21,IC1,JC1,M11,N31,IC2
COMMON /SH/ RG,GAMA,TG,WV,VE
COMMON /HO/ EPSMAX,EPSMAX2,W0,WOP,ITMAX,ITMX2
COMMON /RD/ RDA(50,30),RDX(50,2),ROBY(2,30)
COMMON /GD/ VVEX(50,2),VVBY(2,30),ANGL1(50,2),ANGL2(2,30)
CALL UNDFLW

C
CC CALCULATE 2-DIM. POTENTIAL FUNCTION & VELOCITY VECTOR V IN THE
CC SCROLL CROSS SECTION FOR INCOMP. & COMP. FLOW
C
CC     READ INPUT DATA *****

C
READ(5,102) RG,GAMA,TG,VE
READ(5,100) M1,M2,D0,R1+B,H,R,RC
READ(5,101) ICGM,ISYM,IFG,IPAP,IFREVO
READ(5,200) ITMAX,EPSMAX,W0,WOP
READ(5,7177) IP,IVPLOT,IP_T

C
C
ITMX2=ITMAX
EPSMX2=EPSMAX

C
C
V1=1.0D0
RC=RC/(2*R)
B=B/(2*R)
IF(ISYM.EQ.1) B=B/2.0D0
H=H/(2*R)
P0=R1/D0
R1=R1/(2*R)
AV=16.0D0*R0*B*R/DO
IF(ISYM.EQ.1) WV=2.0D0*B*V
RF=2.0D0*R
R=R/(2*R)
RATIO=(R1+4*R)/(2.0D0*R)
DX=2*R/(M1-1)
DY=2*R/(M2-1)
IF(ISYM.EQ.1) DY=R/(M2-1)
B1=DX/DY
BB=B1*B1

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M21=M2-1
IC=(M1+1)/2
JC=(M2+1)/2
IF(1SYM.EQ.1) JC=1
N3=(B/DY-0.00010D0)+1
N3=((R+R+1)/DX-J.00010D0)+1
IC1=IC-1
JC1=JC-1
IC2=IC+1
M11=M1-1
N31=N3-1
M31=M3-1
IF(1SYM.EQ.1) GO TO 555
IC=(RC/DX-0.00010D0)+M1
JC=((B+RC)/DY-0.00010D0)+1
C
555 DO 12 I=1,M3
DO 12 J=1,42
ANGLE(I,J)=0.0D0
ROA(I,J)=1.000
ROBX(I,I)=1.000
ROBX(I,2)=1.000
ROBY(I,J)=1.000
ROBY(2,J)=1.000
F(I,J)=0.000
12 CONTINUE
IF(IFG.EQ.0) GO TO 5557
DO 5552 I=2,M31
CALL INTPL(I)
5552 READ(5,5553)(F(I,J),J=J_,JU)
5557 CONTINUE
C
CC      WRITE INPJT DATA FOR CHECK      ****
C
WRITE(6,1313)
WRITE(6,405) RG,GAMA,T0,VE
WRITE(6,340) M1,M2,R1,B,H,RC,RF,DO
WRITE(6,310) ICOM,1SYM,IFS,IPAP,IFREVO
WRITE(6,320) ITMAX,EPSMAX,W0,WOP
WRITE(6,330) IP,IVPLOT,IPLT
WRITE(6,301) J_,DY,IC,JC,M3,N3
C
CC SOLVE FOR INCOMP. FLUX      ****
C
IwR=0
ICOD=0
CALL SHABAN
CALL A*ATEF
ILD=0
CALL HVVEL
CALL ABD_AH
IF(ICOM.EQ.0) GO TO 818
C

```

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-
CC SOLVE FOR COMP. FLOW      ****
C
DO 2 I=2,M3
CALL INTPL(I)
DO 2 J=JL,JU
2  PP(I,J)=1.0D0
VEC=VE
IT=0
I+R=1
717 IT=IT+1
ERROR=0.0D0
ICOD=1
VE=VEO/RUBY(2,2)
CALL SHABAN
CALL AWATER
ILQ=0
CALL HVVEL
CALL ABD_AH
DO 7 I=2,M3
CALL INTPL(I)
DO 7 J=JL,JU
SAV=PP(I,J)
7  ERROR=ERROR+DABS(P(I,J)-SAV)*#2
DO 111 I=2,M3
CALL INTPL(I)
DO 111 J=JL,JU
111 P(I,J)=P(I,J)
DO 112 I=2,M3
DO 112 J=1,2
112 PBX1(I,J)=PBX(I,J)
DO 114 J=2,M21
DO 114 I=1,2
114 PBY1(I,J)=PSY(I,J)
IF(IT.GE.ITMX2) GO TO 919
IF(ERROR.GE.EPSMX2) GO TO 717
919 WRITE(6,14)
WRITE(6,407)
DO 9 I=2,M3
9  WRITE(6,408) I,(F(I,J),J=1,M21)
WRITE(6,151) IT,ERROR,VE
WRITE(6,404)
DO 40 J=1,M21
40  WRITE(6,400) J,(P(I,J),I=1,M3)
IF(ISYM.EQ.1) GO TO 46
WRITE(6,401)
DO 42 I=2,M3
42  WRITE(6,402) I,(PBX(I,J),J=1,2)
GO TO 45
46  WRITE(6,4005)
DO 47 I=2,M3
47  WRITE(6,406) I,PBX(I,2)
48  WRITE(6,403)
DO 44 J=1,M21

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44 WRITE(6,402) J,(PBV(I,J),I=1,2)
  IWR=0
  CALL HVVEL
  CALL ABD_AH
  B18 CONTINUE
  IF(IVPLDT.EQ.0) GO TO 7007
C
CC PLOTTING OF THE FLOW DIRECTIONS ****
C
  ISKIP=1
  JSKIP=1
  DXD=0.25
  CALL BEGP_T
  ICPM=2
  ICP=1
  DO 59 I=1,M3
  DO 58 J=1,M2
  X(I,J)=(I-1)*DXD
  Y(I,J)=(J-1)*DXD
  58 CONTINUE
  59 CONTINUE
  WRITE(6,14)
  WRITE(6,5001)
  DO 62 I=1,M3
  62 WRITE(6,20) (X(I,J),J=1,M2)
  WRITE(6,14)
  WRITE(6,5002)
  DO 64 I=1,M3
  64 WRITE(6,20) (Y(I,J),J=1,M2)
  WRITE(6,14)
  75 IF(ISYM.EQ.1) GO TO 76
  CALL PLOT(1.5,1.5,23)
  GO TO 77
  76 CALL PLOT(1.5,3.5,23)
  77 IUPODW=1
  SIZE=0.14
  ISYMBL=75
  IF(ICP.EQ.1) GO TO 11
  IF(ICP.EQ.2) GO TO 133
  11 DO S0 I=2,M3
  DO 50 J=1,M21
  VRR(I,J)=270.0+ANGLE(I,J)
  50 CONTINUE
  CALL PLDT(0.0,0.0,3)
  DO 501 I=2,M31
  CALL INTPL(I)
  DO S11 J=JL,JU
  XXX=X(I,J)
  YYC=Y(I,J)
  CALL SYMBOL (XXX,YYC,SIZE,18,VRR(I,J),-1)
  511 CONTINUE
  501 CONTINUE
  CALL PLDT (0.0,0.0,3)

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ICP=ICP+1
IF(ICP.GT.ICPM) GO TO 3
CALL PAUSE
CALL PAUSE
GO TO 75
133 CONTINUE
C
CC CONTOURS PLOT
C
      DO 510 I=1,M3
      DO 510 J=1,M2
510 VAR(I,J)=P(I,J)
      DO 514 I=2,M3
      CALL INTPL(I)
      J1=JL-1
      J2=JU+1
      VAR(I,J2)=PBX(I,2)
      IF(ISYM.EQ.1) GO TO 514
      VAR(I,J1)=PBX(I,1)
514 CONTINUE
      DO 515 J=2,M21
      CALL IR_(J)
      I1=IL-1
      I2=IR+1
      VAP(I1,J)=PBY(1,J)
515 VAR(I2,J)=PBY(2,J)
      CALL PLOT(0.0,0.0,3)
      DO 222 IP_=1,IPLT
      READ(5,5) VISOR
      CALL PLTISO(M21,ISYMBL,IUPDOW,SIZE,VISOR,VAR,X,Y)
      CALL PLOT(0.0,0.0,23)
222 CONTINUE
      CALL PLOT(0.0,0.0,3)
3  CONTINUE
      CALL ENDPLT
7007 CONTINUE
5  FORMAT(F10.0)
14 FORMAT(1$)
20 FORMAT(10(6X,=6.3))
100 FORMAT(2I10,6F10.0)
101 FORMAT(5I10)
102 FORMAT(4F10.0)
151 FORMAT(20X,'ITCOM=',I5,/,,20X,'ERROR=',E20.9,,20X,'EX.=',E20.9)
200 FORMAT(I10,3F10.0)
301 FORMAT(20X,'DX     =',F10.5,SX,'DY     =',F10.5,5A,'IC     =',I10,/,
1   20X,'JC     =',I10,  5X,'N3     =',I10,5X,'V3     =',I10,/)
310 FORMAT(/,,20X,'ICUM   =',I10,/,,20X,'ISYM   =',I10,,/,,20X,'IFG   =',
1   I10,/,,20X,'IPAP   =',I10,/,,20X,'IFREVO=',I10,,/)
320 FORMAT(/,,20X,'ITMAX=',I10,/,,20X,'EPSMAX=',F10.8,/,,20X,'W0    =',
1   F10.5,/,,20X,'WDP    =',F10.5,/)
330 FORMAT(/,,20X,'IP     =',I10,/,,20X,'IVPLDT=',I10,/,,20X,'IPLT   =',
1   I10,,/)
340 FORMAT(/,,20X,'M1     =',I10,/,,20X,'M2     =',I10,/,,20X,'RI     =',F10.5
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```
1   ,/,20X,*B    =*,=10.5,/,20X,*H    =*,F10.5,/,20X,*RC    =*,  
1   F10.5,/,20X,*D    =*,F10.5,2X,*JUNIT DIM*,/,20X,*JG    =*,F10.5  
1   *2X,*UNIT DIM*,/)   
400 FORMAT(//,7X,*J    =*,12,/,10{5X,D15.6//})  
401 FORMAT(//,15X,*I    *,5X,*PBX1*,15X,*PBX2*)  
402 FORMAT(//,10X,I4,5X,2{5X,D15.6})  
403 FORMAT(//,15X,*J    *,5X,*PBY1*,15X,*PBY2*)  
404 FORMAT(//,20X,*VALUES OF VELOCITY POTENTIAL P(I,J) FOR COMPRESSIBLE  
1E FLOW*,/)  
405 FORMAT(//,20X,*GAS CONSTANT =*,=10.5,/,20X,*GAMA      =*,F10.5  
1   ,/,20X,*STAG. TEMP. =*,F10.5,/,20X,*RAD. EXIT VELE=*,F10.5,/  
406 FORMAT(//,15X,I4,10X,D15.6)  
407 FORMAT(//,10X,*POISSONS SOURCE DIS. AT EACH GRID POINT*//)  
408 FORMAT(//,7X,*I    =*,110,/,4(BF10.5))  
1313 FORMAT(//,10X,*INPUT DATA*,//)  
4005 FORMAT(//,20X,*I    *,5X,*PBX2*,/)  
5001 FORMAT(//,20X,*X-COORD. OF THE PLOTTING DOMAIN*,//)  
5002 FORMAT(//,20X,*Y-COORD. OF THE PLOTTING DOMAIN*,//)  
7177 FORMAT(3I10)  
5553 FORMAT(8(F10.0))  
7177 FORMAT(3I10)  
STOP  
END
```

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AWATEF

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```
SUBROUTINE AWATEF
IMPLICIT REAL*8 (A-H,O-Z)
COMMON /ONE/ V1
COMMON /TWO/ ILJ,IWR,ISYM,IPAP,ICD,IP,ICOM
COMMON /DIAM/ R,RC,H,B,DX,DY,B1,BB
COMMON /FORM/ M1,M2,IC,JC,IIC,JJC,M3,N3
COMMON /MSH/ S1,S2,S3,S4,P1,P2,P3,P4,JL,JU,IL,IR
COMMON /PHI/ P(50,30),PBY(2,30),PBX(50,2),PP(50,30),PSY1(2,30),
1    PBX1(50,2),F(50,30)
COMMON /CAL/ M21,IC1,JC1,W11+N31,IC2
COMMON /IO/ EPSMAX,EPSMA2,*0,*OP,ITMAX,ITMX2
C
C CALCULATE POTENTIAL VELOCITY DIST. IN THE SCRULL CROSS SECTION BY
CC SOLVING POISSONS EQN. WITH NEUMANN B. C. THE ITER. METHOD IS S.O.R.
C
2    DO 1 I=1,M3
DO 1 J=1,M2
1    P(I,J)=0.000
ITER=0
15   ITER=ITER+1
EPS=0.000
DO 5 I=2,M3
XX1=(IC-I)*DX
X1=DABS(XX1)
YY1=DABS(R*R-X1*X1)
Y1=DSQRT(YY1)
CALL INTP_(I)
DO 4 J=JL,JU
K=W0
W1=1.000-W
WB=W/(2.0DC+2.0D0*BB)
DD=1.000-WB*BB
WB1=1.000-WB
YY2=(JC-J)*DY
Y2=DABS(YY2)
XX2=DABS(R*R-Y2*Y2)
X2=DSQRT(XX2)
SAVP=P(I,J)
CALL IR_(J)
CALL MESH(I,J)
L11=1.000
L33=1.000
WB11=1.000-WB*L11
WB12=1.000-WB*L33
C24=1/(DY*DY*S2*S4)
C13=1/(DX*DX*S1*S3)
S24=1/(DY*DY*(S2+S4))
S13=1/(DX*DX*(S1+S3))
S1L=S13*L11,
S1K=S13*L33
P11=L11*P1/S1
P22=P2/S2
P33=L33*P3/S3
```

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P44=P4/S4
IF(I.EQ.M1.AND.J.EQ.JU) GO TO 923
IF(I.EQ.IL.AND.J.EQ.JL) GO TO 86
IF(I.EQ.I_.AND.J.EQ.JU) GO TO 85
IF(I.EQ.IL) GO TO 90
IF(I.EQ.IR.AND.J.EQ.JL) GO TO 91
IF(I.EQ.IR.AND.J.EQ.JU) GO TO 92
IF(I.EQ.IR) GO TO 93
IF(J.EQ.JL) GO TO 94
IF(J.EQ.JU) GO TO 95
P(I,J)=(1.0D0-WUP)*P(I,J)+(WUP/(2+2*BB))*(L11*P1+L33*D3+
1 BB*(P2+P4)-F(I,J)*DX*DX)
GO TO 477
80 CONTINUE
IF(J.EQ.1) GO TO 81
PB1=Y2*B1*P(I,J+1)/X2
PB2=X1*D(I+1,J)/(B1*Y1)
CK1=(W*S1_*((1/S1)-Y2*B1/X2)+W*S24*((1/S4)-X1/(B1*Y1)))/(C13+C24)
IF(CK1.GT.0.9990D0.AND.C<1.LT.1.001) GO TO 16
CK=1.0D0-CK1
GO TO 17
16 CK1=CK1/W
CK=1.0D0-CK1
W1=0.0D0
W=1.0D0
17 CONTINUE
P(I,J)=(W1*P(I,J)+W*(S13*(PB1+P33)+S24*(P22+PB2)-F(I,J)/2)
1 /(C13+C24))/CK
GO TO 477
81 CONTINUE
P(I,J)=(W1*P(I,J)+W*(2*BB*P2+P33-F(I,J)*DX*DX))/WE11
GO TO 477
85 CONTINUE
PB1=Y2*B1*P(I,J-1)/X2
PB2=X1*D(I+1,J)/(B1*Y1)
CK1=(W*S1L*((1/S1)-Y2*B1/X2)+W*S24*((1/S2)-X1/(B1*Y1)))/(C13+C24)
IF(CK1.GT.0.9990D0.AND.C<1.LT.1.001) GO TO 18
CK=1.0D0-CK1
GO TO 19
18 CK1=CK1/W
CK=1.0D0-CK1
W1=0.0D0
W=1.0D0
19 CONTINUE
P(I,J)=(W1*P(I,J)+W*(S13*(PB1+P33)+S24*(P44+PB2)-F(I,J)/2)
1 /(C13+C24))/CK
GO TO 477
90 CONTINUE
IF(J.GT.JC) GO TO 909
PB1=P(I,J+1)*Y2*B1/X2
CK1=(W*S1L*((1/S1)-Y2*B1/X2))/(C13+C24)
IF(CK1.GT.0.9990D0.AND.C<1.LT.1.001) GO TO 20
CK=1.0D0-CK1

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GO TO 21
20 CK1=CK1/W
CK=1.000-CK1
W1=0.000
W=1.000
21 CONTINUE
P(I,J)=(W1*P(I,J)+W*(S13*(P81+P33)+S24*(P22+P44)-F(I,J)/2)
1 / (C13+C24))/CK
GO TO 477
909 CONTINUE
P81=P(I,J-1)*Y2*B1/lambda2
CK1=(W*S1L*((I/S1)-Y2*B1/X2))/(C13+C24)
IF(CK1.GT.0.9990D0.AND.CK1.LT.1.001) GO TO 22
CK=1.000-CK1
GO TO 23
22 CK1=CK1/W
CK=1.000-CK1
W1=0.000
W=1.000
23 CONTINUE
P(I,J)=(W1*P(I,J)+W*(S13*(P81+P33)+S24*(P22+P44)-F(I,J)/2)
1 / (C13+C24))/CK
GO TO 477
91 CONTINUE
IF(J.EQ.1) GO TO 910
CK1=(W*S1K/S3)+W*S24/S4)/(C13+C24)
IF(CK1.GT.0.9990D0.AND.CK1.LT.1.001) GO TO 24
CK=1.000-CK1
GO TO 25
24 CK1=CK1/W
CK=1.000-CK1
W1=0.000
W=1.000
25 CONTINUE
P(I,J)=(W1*P(I,J)+W*(S13*P11+S1K*V1*DX+S24*P22-F(I,J)/2)
1 / (C13+C24))/CK
GO TO 477
910 CK1=W*S1L/(S3*(C13+C24))
IF(CK1.GT.0.9990D0.AND.CK1.LT.1.001) GO TO 26
CK=1.000-CK1
GO TO 27
26 CK1=CK1/W
CK=1.000-CK1
W1=0.000
W=1.000
27 CONTINUE
P(I,J)=(W1*P(I,J)+W*(S13*P11+S1K*V1*DX+2*S24*P22-F(I,J)/2)
1 / (C13+C24))/CK
GO TO 477
92 CONTINUE
IF(J.GT.43) GO TO 921
CK1=(W*S1K/S3)+W*S24/S2)/(C13+C24)
IF(CK1.GT.0.9990D0.AND.CK1.LT.1.001) GO TO 28
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CK=1.000-CK1
GO TO 29
28 CK1=CK1/*
CK=1.000-CK1
*1=0.000
W=1.000
29 CONTINUE
P(I,J)=(*1*P(I,J)+W*(S13*P11+S1<*V1*DX+S24*P44-F(I,J)/2)
1 /(*C13+C24))/CK
GO TO 477
921 CONTINUE
IF(1SYM.EQ.1) GO TO 922
IF(J.GT.JJC) GO TO 922
XC1=RC-(I-M1)*DX
YYC1=DABS(RC*RC-XC1*XC1)
YC1=DSQRT(YYC1)
YC2=(RC+B)-(J-1)*DY
XXC=DABS(RC*RC-YC2*YC2)
XC2=DSQRT(XXC)
PB2=XC1*P(I-1,J)/(B1*YC1)
PB3=YC2*B1*P(I,J-1)/XC2
CK1=(W*S24*((1/S2)-XC1/(B1*YC1))+W*S1K*((1/S3)-YC2*B1/XC2))/(*C13
1 +C2*)
IF(CK1.GT.0.9990D0.AND.CK1.LT.1.001) GO TO 30
CK=1.000-CK1
GO TO 31
30 CK1=CK1/*
CK=1.000-CK1
*1=0.000
W=1.000
31 CONTINUE
P(I,J)=(*1*P(I,J)+W*(S13*(PB3+P11)+S24*(P44+PB2)-F(I,J)/2)
1 /(*C13+C24))/CK
GO TO 477
922 CONTINUE
PB3=Y2*B1*P(I,J-1)/X2
PB2=X1*P(I-1,J)/(B1*Y1)
CK1=(W*S1K*((1/S3)-Y2*B1/X2)+W*S24*((1/S2)-X1/(B1*Y1)))/(*C13+C24)
IF(CK1.GT.0.9990D0.AND.CK1.LT.1.001) GO TO 32
CK=1.000-CK1
GO TO 33
32 CK1=CK1/*
CK=1.000-CK1
*1=0.000
W=1.000
33 CONTINUE
P(I,J)=(*1*P(I,J)+W*(S13*(PB3+P11)+S24*(P44+PB2)-F(I,J)/2)
1 /(*C13+C24))/CK
GO TO 477
93 CONTINUE
IF(J.GT.N3) GO TO 930
CK1=W*S1K/(S3*(C13+C24))
IF(CK1.GT.0.9990D0.AND.CK1.LT.1.001) GO TO 34
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CK=1.000-CK1
GO TO 35
34 CK1=CK1/W
CK=1.000-C<1
W1=0.000
W=1.000
35 CONTINUE
P(I,J)=(W1*P(I,J)+W*(S13*P11+S1K*V1*DX+S24*(P22+P44)-F(I,J)/2)
1   /(C13+C24))/CK
GO TO 477
930 CONTINUE
IF(ISYM.EQ.1) GO TO 932
IF(J.GT.JJC) GO TO 931
YC2=(RC+B)-(J-1)*DY
XXC=DABS(RC*RC-YC2*YC2)
XC2=DSQRT(XXC)
PB3=YC2*B1*P(I,J-1)/XC2
CK1=(W*S1K*((1/S3)-YC2*B1/XC2))/(C13+C24)
IF(CK1.GT.0.999000.AND.C<1.LT.1.001) GO TO 36
CK=1.000-CK1
GO TO 37
36 CK1=CK1/W
CK=1.000-CK1
W1=0.000
W=1.000
37 CONTINUE
P(I,J)=(W1*P(I,J)+W*(S13*(PB3+P11)+S24*(P22+P44)-F(I,J)/2)
1   /(C13+C24))/CK
GO TO 477
931 CONTINUE
IF(J.GT.JC) GO TO 932
P(I,J)=(W1*P(I,J)+W*B*(P11+B3*(P22+P44)-F(I,J)*DX*DX))/WB12
GO TO 477
932 CONTINUE
PS3=Y2*B1*P(I,J-1)/X2
CK1=(W*S1K*((1/S3)-Y2*B1/X2))/(C13+C24)
IF(CK1.GT.0.999000.AND.CK1.LT.1.001) GO TO 38
CK=1.000-CK1
GO TO 39
38 CK1=CK1/W
CK=1.000-C<1
W1=0.000
W=1.000
39 CONTINUE
P(I,J)=(W1*P(I,J)+W*(S13*(PB3+P11)+S24*(P22+P44)-F(I,J)/2)
1   /(C13+C24))/CK
GO TO 477
94 CONTINUE
IF(J.EQ.1) GO TO 945
IF(I.GE.IC) GO TO 940
PB4=X1*P(I+1,J)/(B1*Y1)
CK1=(W*S24*((1/54)-X1/(B1*Y1)))/(C13+C24)
IF(CK1.GT.0.999000.AND.C<1.LT.1.001) GO TO 40
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CK=1.0D0-CK1
GO TO 41
40 CK1=CK1/*
CK=1.0D0-CK1
W1=J.0D0
W=1.0D0
41 CONTINUE
P(I,J)=(W1*P(I,J)+W#(S13*(P33+P11)+S24*(P22+PB4)-F(I,J)/2)
1 /(C13+C24))/CK
GO TO 477
945 CONTINUE
P(I,J)=W1*P(I,J)+W#(P11+P33+2.0D0*BB*P22-F(I,J)*DX*CX)
GO TO 477
940 CONTINUE
P(I,J)=(W1*P(I,J)+W#(P11+P33+BB*P22-F(I,J)*DX*DX))/DD
GO TO 477
95 CONTINUE
IF(I.GE.IC) GO TO 950
PB2=X1*P(I+1,J)/(B1*Y1)
CK1=(W*S24*((1/S2)-X1/(B1*Y1)))/(C13+C24)
IF(CK1.GT.0.999D0.AND.CK1.LT.1.001) GO TO 42
CK=1.0D0-CK1
GO TO 43
42 CK1=CK1/*
CK=1.0D0-CK1
W1=0.0D0
W=1.0D0
43 CONTINUE
P(I,J)=(W1*P(I,J)+W#(S13*(P33+P11)+S24*(P44+PB2)-F(I,J)/2)
1 /(C13+C24))/CK
GO TO 477
923 CONTINUE
P(I,J)=0.0D0
GO TO 477
950 CONTINUE
IF(I.GT.M1) GO TO 951
PB2=X1*P(I-1,J)/(B1*Y1)
CK1=(W*S24*((1/S2)-X1/(B1*Y1)))/(C13+C24)
IF(CK1.GT.0.999D0.AND.CK1.LT.1.001) GO TO 44
CK=1.0D0-CK1
GO TO 45
44 CK1=CK1/*
CK=1.0D0-CK1
W1=0.0D0
W=1.0D0
45 CONTINUE
P(I,J)=(W1*P(I,J)+W#(S13*(P33+P11)+S24*(P44+PB2)-F(I,J)/2)
1 /(C13+C24))/CK
GO TO 477
951 CONTINUE
IF(ISYM.EQ.1) GO TO 952
IF(I.GT.IIC) GO TO 952
XC1=RC-(I-M1)*DX

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    YYCI=DABS(RC*RC-XC1*XC1)
    YC1=DSQRT(YYCI)
    PB2=XC1*B(I-1,J)/(B1+YC1)
    CK1=W*S24*((1/S2)-XC1/(B1+YC1))/(C13+C24)
    IF(CK1.GT.0.999D0.AND.CK1.LT.1.001) GO TO 40
    CK=1.0D0-CK1
    GO TO 47
40  CK1=CK1/*
    CK=1.0D0-CK1
    W1=0.0D0
    W=1.0D0
47  CONTINUE
    P(I,J)=(W1*P(I,J)+W*(S13*(P11+P33)+S24*(P44+PB2)-F(I,J)/2)
1     /(C13+C24))/CK
    GO TO 477
952 CONTINUE
    CK1=W*S24/(S2*(C13+C24))
    IF(CK1.GT.0.999D0.AND.CK1.LT.1.001) GO TO 46
    CK=1.0D0-CK1
    GO TO 49
48  CK1=CK1/*
    CK=1.0D0-CK1
    W1=0.0D0
    W=1.0D0
49  CONTINUE
    P(I,J)=W1*P(I,J)+W*(S13*(P11+P33)+S24*P44-F(I,J)/2)
1     /(C13+C24))/CK
477 CONTINUE
    EPS=EPS+DABS(P(I,J)-SAVP)**2
4  CONTINUE
5  CONTINUE
    IF(ITER/IP*IP.NE. ITER) GO TO 2222
    WRITE(6,102) EPS,ITER
    DO 900 J=1,M2
900  WRITE(6,101)(P(I,J),I=1,43)
    WRITE(6,104)
    DO 1000 I=1,M3
1000  WRITE(6,103) I,(PBX(I,J),J=1,2)
    WRITE(6,105)
    DO 1100 J=1,M2
1100  WRITE(6,103) J,(PBY(I,J),I=1,2)
2222 CONTINUE
    IF(EPS.LT.1.0D0) GO TO 3
    WQ=0.90D0*WG
    WQP=0.90D0*WQP
    GO TO 2
3  IF(ITER .GE. ITMAX) GO TO 8
    IF(EPS .GE. EPSMAX) GO TO 15
8  CONTINUE
    WRITE(6,102) EPS,ITER
    WRITE(6,14)
C
    DO 6 I=2,M3
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SUBROUTINE ABD_AH
IMPLICIT REAL*8 (A-H,O-Z)
COMMON /ONE/ VI
COMMON /T+3/ ILJ,IwR,ISYM,IPAP,IC0J,IP,ICUM
COMMON /FORM/ M1,M2,IC,JC,IIC,JJC,M3,N3
COMMON /MSH/ S1,S2,S3,S4,P1,P2,P3,P4,JL,JU,IL,IR
COMMON /VEES/U(50,30),V(50,30),UBX(50,2),VAX(50,2),
1 UBY(2,30),VBY(2,30),U1(50,30),V0(50,30),UBX1(50,2),
1 ,VAX1(50,2),UBY1(2,30),VBY1(2,30),VV(50,30),ANGLE(50,30)
COMMON /CAL/ M21,IC1,JC1,M11,N31,IC2
COMMON /SD/ VV BX(50,2),VV BY(2,30),ANGL1(50,2),ANGL2(2,30)

C
CC CALCULATE THE VELOCITY VECTOR V IN THE SCROLL CROSS SECTION BY
CC USING THE TWO COMPONENTS U,V IN THE X&Y DIRECTIONS
C
IF(IWR.EQ.1) GO TO 5
*WRITE(6,14)
*WRITE(6,149)
*WRITE(6,150)
5 CONTINUE
DO 2 J=2,M3
CALL INTPL(I)
DO 2 J=JL,JU
U2=DABS(U(I,J))
V2=DABS(V(I,J))
VV(I,J)=DSQRT(U2**2+V2**2)
IF(U(I,J).GT.0.0D0.AND.V(I,J).LT.0.0D0) GO TO 82
IF(U(I,J).LT.0.0D0.AND.V(I,J).GT.0.0D0) GO TO 63
IF(U(I,J).LT.0.0D0.AND.V(I,J).LT.0.0D0) GO TO 84
IF(J(I,J).EQ.0.0D0.AND.V(I,J).GT.0.0D0) GO TO 85
IF(U(I,J).EQ.0.0D0.AND.V(I,J).LT.0.0D0) GO TO 86
IF(U(I,J).GT.0.0D0.AND.V(I,J).EQ.0.0D0) GO TO 87
IF(U(I,J).LT.0.0D0.AND.V(I,J).EQ.0.0D0) GO TO 88
IF(U(I,J).EQ.0.0D0.AND.V(I,J).EQ.0.0D0) GO TO 87
ANGLE(I,J)=(DATAN(V2/U2))*57.296D0
GO TO 1
82 ANGLE(I,J)=(6.283D0-(DATAN(V2/U2)))*57.296D0
GO TO 1
83 ANGLE(I,J)=(3.142D0-(DATAN(V2/U2)))*57.296D0
GO TO 1
84 ANGLE(I,J)=(3.142D0+(DATAN(V2/U2)))*57.296D0
GO TO 1
85 ANGLE(I,J)=90.0D0
GO TO 1
86 ANGLE(I,J)=270.0D0
GO TO 1
87 ANGLE(I,J)=0.0D0
GO TO 1
88 ANGLE(I,J)=180.0D0
1 CONTINUE
IF(IWR.EQ.1) GO TO 2
*WRITE(6,100) I,J,VV(I,J), ANGLE(I,J)
2 CONTINUE

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      WRITE(6,200)
      DC 3 I=2,M3
      DO 3 J=1,2
      J2=DABS(JBX(I,J))
      V2=DABS(VBX(I,J))
      VVDX(I,J)=DSQRT(U2*U2+V2*V2)
      IF(UBX(I,J).GT.0.0D0.AND.VBX(I,J).LT.0.0D0) GO TO 72
      IF(JBX(I,J).LT.0.0D0.AND.VBX(I,J).GT.0.0D0) GO TO 73
      IF(UBX(I,J).LT.0.0D0.AND.VBX(I,J).LT.0.0D0) GO TO 74
      IF(UBX(I,J).EQ.0.0D0.AND.VBX(I,J).GT.0.0D0) GO TO 75
      IF(UBX(I,J).EQ.0.0D0.AND.VBX(I,J).LT.0.0D0) GO TO 76
      IF(UBX(I,J).GT.0.0D0.AND.VBX(I,J).EQ.0.0D0) GO TO 77
      IF(UBX(I,J).EQ.0.0D0.AND.VBX(I,J).EQ.0.0D0) GO TO 78
      ANGL1(I,J)=(DATAN(V2/U2))*57.2960D0
      IF(UBX(I,J).LT.0.0D0.AND.VBX(I,J).EQ.0.0D0) GO TO 78
      GO TO 10
    72  ANGL1(I,J)=(6.2830D0-(DATAN(V2/U2)))*57.2960D0
      GO TO 10
    73  ANGL1(I,J)=(3.1420D0-(DATAN(V2/U2)))*57.2960D0
      GO TO 10
    74  ANGL1(I,J)=(3.1420D0+(DATAN(V2/U2)))*57.2960D0
      GO TO 10
    75  ANGL1(I,J)=90.0D0
      GO TO 10
    76  ANGL1(I,J)=270.0D0
      GO TO 10
    77  ANGL1(I,J)=0.0D0
      GO TO 10
    78  ANGL1(I,J)=180.0D0
    10  CONTINUE
      IF(I>R.EQ.1) GG TO 3
      WRITE(6,100) I,J,VV3X(I,J),ANGL1(I,J)
    3  CONTINUE
      WRITE(6,300)
      DO 4 J=2,M21
      DO 4 I=1,2
      J2=DABS(UBY(I,J))
      V2=DABS(VBY(I,J))
      VVBY(I,J)=DSQRT(U2*J2+V2*V2)
      IF(UBY(I,J).GT.0.0D0.AND.VBY(I,J).LT.0.0D0) GG TO 62
      IF(UBY(I,J).LT.0.0D0.AND.VBY(I,J).GT.0.0D0) GO TO 63
      IF(UBY(I,J).LT.0.0D0.AND.VBY(I,J).LT.0.0D0) GO TO 64
      IF(UBY(I,J).EQ.0.0D0.AND.VBY(I,J).GT.0.0D0) GO TO 65
      IF(UBY(I,J).EQ.0.0D0.AND.VBY(I,J).LT.0.0D0) GO TO 66
      IF(UBY(I,J).GT.0.0D0.AND.VBY(I,J).EQ.0.0D0) GO TO 67
      IF(UBY(I,J).LT.0.0D0.AND.VBY(I,J).EQ.0.0D0) GO TO 68
      IF(UBY(I,J).EQ.0.0D0.AND.VBY(I,J).EQ.0.0D0) GO TO 67
      ANGL2(I,J)=(DATAN(V2/U2))*57.2960D0
      GO TO 20
    62  ANGL2(I,J)=(6.2630D0-(DATAN(V2/U2)))*57.2960D0
      GO TO 20
    63  ANGL2(I,J)=(3.1420D0-(DATAN(V2/U2)))*57.2960D0
      GO TO 20
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```
64 ANGL2(I,J)=(3.1420D0+(DATAN(V2/U2)))*57.2960D0
  GO TO 20
65 ANGL2(I,J)=90.0D0
  GO TO 20
66 ANGL2(I,J)=270.0D0
  GO TO 20
67 ANGL2(I,J)=0.0D0
  GO TO 20
68 ANGL2(I,J)=180.0D0
20 CONTINUE
IF(IWR.EQ.1) GO TO 4
WRITE(6,100) I,J,VVBY(I,J),ANGL2(I,J)
4 CCNTINUE
14 FORMAT(1H1)
100 FORMAT(20X,1S,5X,1S,5X,E20.9,5X,F8.4)
149 FORMAT(/,10X,*ABSOLUTE VELOCITY & ITS DIR. WITH THE X CJO. *,//)
150 FORMAT(//,20X,*I      *,5X,*J      *,5X,*VV      *,20X,*THETA*,/)
200 FORMAT(//,20X,*I      *,5X,*J      *,5X,*VVBX *,20X,*THETA*,/)
300 FORMAT(//,20X,*I      *,5X,*J      *,5X,*VVBY *,20X,*THETA*,/)
RETURN
END
```

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```

SUBROUTINE SHABAN
IMPLICIT REAL*8 (A-H,O-Z)
COMMON /ONE/ V1
COMMON /TWO/ IL0,ILW,R,ISYM,IPAP,IC00,IP,ICOM
COMMON /FOUR/ R1,RF,IFREVU
COMMON /DIMS/ R,RCM,B,DX,DY,B1,B8
COMMON /FORM/ M1,M2,IC,JC,IIC,JJC,M3,N3
COMMON /MSH/ S1,S2,S3,S4,P1,P2,P3,P4,JL,JU,IL,IR
COMMON /PHI/ P(50,30),PBX(2,30),PBX(50,2),PP(50,30),PBY(2,30),
1 PBX1(50,2),F(50,30)
COMMON /VEES/U(50,30),V(50,30),UBX(50,2),VBX(50,2),
1 UBY(2,30),VBY(2,30),U1(50,30),V0(50,30),UBX1(50,2)
1 ,VBX1(50,2),UBY1(2,30),VBY1(2,30),VV(50,30),ANGLE(50,30)
COMMON /CAL/ M21,IC1,JC1,M11,N31,IC2
COMMON /SH/ RG,GAMA,T0,WV,VE
COMMON /RD/ RDA(50,30),ROBX(50,2),ROBY(2,30)
COMMON /GD/ VVEX(50,2),VVBY(2,30),ANG1(50,2),ANGL2(2,30)

C
CC CALCULATE POISSONS SOURCE DIS. F(I,J)
C
      DG 400 I=1,M3
      IF(IFG.EQ.1) GO TO 101
      DO 400 J=1,M2
400  F(I,J)=0.0D0
      IF(ISYM.EQ.1) IIC=M1
      IF(ISYM.EQ.1.AND.IPAP.EQ.1) GO TO 777
      AA=0.0D0
      DC 555 I=2,IC1
      CALL INTPL(I)
555  AA=AA+(JU-JL)*DY*DX
      DO 5556 I=IC2,M11
      CALL INTPL(I)
5556 AA=AA+(JU-JL)*DY*DX
      DO 666 I=M1,M3
      CALL INTPL(I)
666  AA=AA+(JU-JL)*DY*DX
      A1=(M3-IIC)*(N3-2)*DX*DY
      IF(ISYM.EQ.1) A1=(M3-IIC)*(N3-1)*DX*DY
      RH=B/(AA-A1)
      IF(IFREV3.EQ.1) G3 TO 3336
      GO TO 1
3336 CONTINUE
      R11=R1+H+R
      DO 401 I=2,M1
      R22=R1+H+(M1-I)*DX
      CALL INTPL(I)
      DO 401 J=JL,JU
401  F(I,J)=R11*RH/R22
      GO TO 3337
777 CONTINUE
      DG 11 I=2,M11
      CALL INTPL(I)
      DO 12 J=JL,JU
12    
```

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```
X=(I-IC)*DX
Y=(J-JC)*DY
F(I,J)=5.09090 DD*B*(1.0D0-(X*X+Y*Y)/(R*R))
12 CONTINUE
11 CONTINUE
3337 IF(ICOD.EQ.0) GO TO 7
1 IF(ICOD.EQ.0) GO TO 17
CALL HDSNY
DO 2 I=2,M3
CALL INTPL(I)
DO 2 J=JL,JU
2 P(I,J)=ROA(I,J)
DO 3 I=2,M3
PBX(I,1)=ROBX(I,1)
3 PBX(I,2)=ROBX(I,2)
DO 4 J=1,M21
PBY(1,J)=ROBY(1,J)
4 PBY(2,J)=ROBY(2,J)
ILG=1
CALL HVVE_
IF(IPAP.EQ.1) RH=0.0D0
IF(IFREVO.EQ.1) RH=0.0D0
IF(ISYM.EQ.1) IIC=M1-1
DO 5 I=2,M3
IF(I.GT.IIC) RH=0.0D0
CALL INTPL(I)
DO 5 J=JL,JU
5 F(I,J)=F(I,J)*(ROBY(2,2)/ROA(I,J))+RH*(ROBY(2,2)/ROA(I,J))-
1 (U1(I,J)*U(I,J)+V0(I,J)*V(I,J))/ROA(I,J)
GO TO 7
17 DO 6 I=2,M3
IF(I.GT.IIC) RH=0.0D0
CALL INTPL(I)
DO 8 J=JL,JU
8 F(I,J)=RH
7 AE=0.0D0
DO 444 I=2,IC1
CALL INTPL(I)
J1=JL
J2=JU-1
DO 444 J=J1,J2
444 AE=AE+((F(I,J)+F(I+1,J)+F(I,J+1)+F(I+1,J+1))/4)*DX*DY
DO 4446 I=IC2,M11
CALL INTPL(I)
J1=JL
J2=JU-1
DO 4446 J=J1,J2
4446 AE=AE+((F(I,J)+F(I-1,J)+F(I,J+1)+F(I-1,J+1))/4)*DX*DY
DO 333 I=41,M3
CALL INTPL(I)
J1=JL
J2=JU-1
DO 333 J=J1,J2
```

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```
333 AE=AE+((F(I,J)+F(I-1,J)+F(I,J+1)+F(I-1,J+1))/4)*DX*DY
      AN=(B-N31*DY)*V1*ROBY(2,2)
      DO 29 J=1,N31
29   AN=AN+V1*DY*ROBY(2,2)
      IF(1SYM.EQ.1.AND.1PAP.EQ.1) AA=1.571430D0*R*R
      DO 30 I=2,M3
      CALL INTPL(I)
      DO 30 J=JL,JU
30   F(I,J)=F(I,J)-(AE-AN)/AA
101  CONTINUE
      IF(IWR.EQ.1) GO TO 300
      WRITE(6,200)
      DO 9 I=2,M3
9       WRITE(6,100) I,(F(I,J),J=1,M2I)
      WRITE(6,14)
14   =CRMAT(//,******)
1     ******/]
100  FORMAT(//,7X,'I =',I10,/,4(8F10.5))
200  FORMAT(//,10X,'POISONS SOURCE DIS. AT EACH GRID POINT',//)
300  CONTINUE
      RETURN
      END
```

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SUBROUTINE HOSNY
IMPLICIT REAL*8 (A-H,O-Z)
COMMON /TWO/ ILG,IWR,ISYM,IPAP,ICOD,IP,ICOM
COMMON /FOUR/ R1,RF,IFREV3
COMMON /DIMS/ R,RC,H,B,DX,DY,B1,BB
COMMON /FORM/ M1,M2,IC,JC,IIC,JJC,M3,N3
COMMON /MSH/ S1,S2,S3,S4,P1,P2,P3,P4,JL,JU,IL,IR
COMMON /VEES/U(50,30),V(50,30),U1(50,30),V0(50,30),UBX(50,2),
1 UBY(2,30),V3Y(2,30),U1(50,30),V0(50,30),UBX1(50,2),
1 ,VBY1(50,2),JBY1(2,30),VBY1(2,30),VV(50,30),ANGLE(50,30)
COMMON /CAL/ M21,IC1,JC1,M11,N31,IC2
COMMON /SH/ RG,GAMA,TO,WW,VE
COMMON /RD/ ROA(50,30),ROBX(50,2),R3BY(2,30)
COMMON /GD/ VVEX(50,2),VVBY(2,30),ANGL1(50,2),ANGL2(2,30)

C
CC CALCULATE DENSITY ROA(I,J) AT EACH GRID POIN
C
CP=RG*GAMA/(GAMA-1.0D0)
POWER=1.0D0/(GAMA-1.0D0)
63 DK=VE*VE/(2.0D0*CP*T0)
IF(IPAP.EQ.1) GO TO 4
DO 1 I=2,M3
CALL INTPL(I)
DO 1 J=JL,JU
VEL=VV(I,J)*VV(I,J)+WW*WW
T=1.0D0-DK*VEL
IF(T.LE.0.000010D0) GO TO 80
ROA(I,J)=T**POWER
1 CONTINUE
GO TO 8
4 CONTINUE
DO 5 I=2,M3
CALL INTPL(I)
DO 5 J=JL,JU
X=(I-IC)*DX
Y=(J-JC)*DY
WW=5.0900*B*(1.0D0/RF)*(1.0D0-(X*X+Y*Y)/(R*R))
VEL=VV(I,J)*VV(I,J)+WW*WW
T=1.0D0-DK*VEL
IF(T.LE.0.000010D0) GO TO 80
ROA(I,J)=T**POWER
5 CONTINUE
8 DO 2 I=2,M3
DO 2 J=1,2
VEL=VVBX(I,J)*VVBX(I,J)
T=1.0D0-DK*VEL
IF(T.LE.0.000010D0) GO TO 80
2 ROBX(I,J)=T**POWER
DO 3 J=2,M21
DO 3 I=1,2
VEL=VVBY(I,J)*VVBY(I,J)
T=1.0D0-DK*VEL
IF(T.LE.0.000010D0) GO TO 80

```

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HOSNY

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```
3  ROBY(I,J)=T**POWER
   GO TO 90
50  CONTINUE
*WRITE(6,32) I,J,T,VEL,DK
52  FORMAT(5X,2I10,3F12.7)
VE=.9000*VE
WRITE(6,34) VE
54  FORMAT(20X,*VE=' ,F12.7,//)
   GO TO 83
90  RETURN
END
```

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INTPL

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```
SUBROUTINE INTPL(I)
C
CC SUBROUTINE INTPL(I) FOR DETERMINING BOUNDARY POINTS FOR A GIVEN
CC COLUMN I,(I,JL(I)) IS THE LOWER MOST INTERIOR POINT AND
CC (I,JU(I)) IS THE UPPER MOST INTERIOR POINT
C
IMPLICIT REAL*8 (A-H,O-Z)
COMMON /TWO/ ILU,IWK,ISYM,IPAP,ICOD,IP,ICGM
COMMON /DIMS/ R,RC,-1,B,DX,DY,B1,B8
COMMON /FORM/ M1,M2,IIC,JC,IIC,JJC,M3,N3
COMMON /MSH/ S1,S2,S3,S4,P1,P2,P3,P4,JL,JU,IL,IR
C
IF(I .GT. IC) GO TO 10
X=(I-1)*DX-R
YY2=DABS(R*R-X*X)
YY=DSQRT(YY2)
IF(ISYM.EQ.1) GO TO 9
Y1=R-YY
Y2=R+YY
JL=(Y1/DY-0.0100000)+2
JU=(Y2/DY-0.0100000)+1
GO TO 40
1
2
9
JL=1
JU=(YY/DY-0.0100000)+1
GO TO 40
10
CONTINUE
11
IF(I.EQ.M1) GO TO 19
12
IF(I.GT.M1) GO TO 20
13
X=(I-1)*DX-R
14
YY2=DABS(R*R-X*X)
YY=DSQRT(YY2)
15
IF(ISYM.EQ.1) GO TO 18
16
JL=2
17
Y2=R+YY
JU=(Y2/DY-0.0100000)+1
18
19
GO TO 40
20
JL=1
JU=(YY/DY-0.0100000)+1
IF(YY.LT.B) JU=N3
GO TO 40
21
22
23
CONTINUE
24
IF(ISYM.EQ.1) GO TO 30
25
JL=2
26
IF(I.GT.IIC) GO TO 30
27
X=RC-(I-M1)*DX
28
YY2=DABS(RC*RC-X*X)
29
YY=DSQRT(YY2)
30
Y1=(RC+B)-YY
31
JU=(Y1/DY-0.0100000)+1
GO TO 40
32
33
CONTINUE
34
IF(ISYM.EQ.1) GO TO 30
35
JL=2
```

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INTPL

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```
JU=JJC  
GO TO 40  
30 CONTINUE  
JL=2  
IF(1SYM.EQ.1) JL=1  
JU=(B/DY-0.00100D0)+1  
40 CONTINUE  
RETURN  
END
```

31M
32
33
34

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      SUBROUTINE MESH(I,J)
      IMPLICIT REAL*8 (A-H,O-Z)
      COMMON /T#0/ ILO,IWR,ISYM,IPAP,ICOD,IP,ICOM
      COMMON /DIMS/ R,RC,H,B,DX,DY,B1,B2
      COMMON /FORM/ M1,M2,IC,JC,IIC,JJC,M3,N3
      COMMON /MSH/ S1,S2,S3,S4,P1,P2,P3,P4,JL,JU,IL,IR
      COMMON /PHI/ P(50,30),PBY(2,30),PBX(50,2),PP(50,30),PBY1(2,30),
      1   PBX1(50,2),F(50,30)

C
CC DETERMINE THE STANDARD FIVE POINTS LAPLACE DIFF. OPERATOR AND
CC THEIR POSITIONS S1,S2,S3,S4 & R.T. POINT O(X,Y)
C
      IF(J.EQ.JL.AND.J.EQ.JU) GO TO 101
      IF(J.EQ.JL) GO TO 50
      IF(J.EQ.JJ) GO TO 60
      S2=1.000
      P2=P(I,J+1)
      S4=1.000
      P4=P(I,J-1)
      GO TO 70
  50  CONTINUE
      IF(ISYM.EQ.1) GO TO 51
      IF(I.GT.IC) GO TO 51
      S2=1.000
      P2=P(I,J+1)
      X=R-(I-1)*DX
      YY2=DABS(R*R-X*X)
      YY=DSQRT(YY2)
      Y1=YY-(JC-J)*DY
      S4=Y1/DY
      IF(S4.GT.1.000) S4=1.000
      P4=PBX(I,1)
      GO TO 70
  51  CONTINUE
      S2=1.000
      P2=P(I,J+1)
      S4=1.000
      P4=PBX(I,1)
      GO TO 70
  60  CONTINUE
      IF(I.EQ.M1) GO TO 62
      IF(I.GT.M1) GO TO 65
      X=(IC-I)*DX
      YY2=DABS(R*R-X*X)
      YY=DSQRT(YY2)
      Y1=YY-(J-JC)*DY
      S2=Y1/DY
      IF(YY.LT.B) S2=(B-(J-1)*DY)/DY
      IF(S2.GT.1.000) S2=1.000
      P2=PBX(I,2)
      S4=1.000
      P4=P(I,J-1)
      GO TO 70
      001
      002
      004
      005
      007
      008
      009
      0011
      0012
      0021
      0023
      0024
      0025
      0037
      0038
      0039
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      0084
      0085
  
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 62 CONTINUE 0048
 IF(1SYM.EQ.1) GO TO 64
 S2=1.0D0
 P2=PBX(I,2)
 S4=1.0D0
 P4=P(I,J-1)
 GO TO 70
 65 CONTINUE 0050
 IF(1SYM.EQ.1) GO TO 64
 IF(I.GT.IIC) GC TO 64
 XC=RC-(I-M1)*DX 0052
 YY2=DABS(RC*RC-XC*XC)
 YY=DSORT(YY2)
 YC=B+RC-YY-(J-1)*DY 0053
 S2=YC/DY 0054
 IF(S2.GT.1.0D0) S2=1.0D0
 P2=PBX(I,2)
 S4=1.0D0
 P4=P(I,J-1)
 GO TO 70
 64 CONTINUE 0055
 Y2=B-(J-1)*DY 0056
 S2=Y2/DY 0057
 IF(S2.GT.1.0D0) S2=1.0D0
 P2=PBX(I,2)
 S4=1.0D0
 P4=P(I,J-1)
 GO TO 70
 101 CCNTINUE 0059
 Y=B-(J-1)*DY 0060
 S2=Y/DY 0061
 IF(S2.GT.1.0D0) S2=1.0D0
 P2=PBX(I,2)
 S4=1.0D0
 P4=PBX(I,1)
 70 CONTINUE 0063
 IF(I.EQ.IL) GO TO 80 0064
 IF(I.EQ.IR) GO TO 90 0065
 S1=1.0D0
 P1=P(I-1,J)
 S3=1.0D0 0066
 P3=P(I+1,J)
 GO TO 100 0067
 80 CCNTINUE 0068
 Y=(JC-J)*DY 0069
 XX2=DABS(R*R-Y*Y)
 XX=DSQRT(XX2)
 X1=XX-(IC-I)*DX 0070
 S1=X1/DX 0071
 IF(S1.GT.1.0D0) S1=1.0D0
 P1=P3Y(I,J)
 S3=1.0D0 0073
 P3=P(I+1,J) 0074
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 0080
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 0087

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MESH

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      GO TO 100
90  CONTINUE
      IF(J.GT.43) GO TO 91
      S1=1.0D0
      P1=P(I-1,J)
      XX=H-(M3-M1)*DX
      S3=XX/DX
      IF(S3.GT.1.0D0) S3=1.0D0
      P3=PBY(2,J)
      GO TO 100
91  CONTINUE
      IF(ISYM.EQ.1) GO TO 93
      IF(J.GT.JJC) GO TO 92
      S1=1.0D0
      P1=P(I-1,J)
      YC=B+RC-(J-1)*DY
      XXC=DABS(RC*RC-YC*YC)
      XC=DSQRT(XXC)
      X1=RC-XC-(I-M1)*DX
      S3=X1/DX
      IF(S3.GT.1.0D0) S3=1.0D0
      P3=PBY(2,J)
      GO TO 100
92  CONTINUE
      IF(J.GT.JC) GO TO 93
      S1=1.0D0
      P1=P(I-1,J)
      S3=1.0D0
      P3=PBY(2,J)
      GO TO 100
93  CONTINUE
      S1=1.0D0
      P1=P(I-1,J)
      Y=(J-JC)*DY
      XX2=DABS(R*R-Y*Y)
      XX=DSQRT(XX2)
      X1=XX-(I-IC)*DX
      S3=X1/DX
      IF(S3.GT.1.0D0) S3=1.0D0
      P3=PBY(2,J)
100  CONTINUE
      RETURN
      END

```

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IRL

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      SUBROUTINE IRL(J)
      IMPLICIT REAL*8 (A-H,O-Z)
      COMMON /TWO/ ILO,IWR,ISYM,IPAP,ICDD,IP,ICOM
      COMMON /DIMS/ R,RC,H,B,DX,DY,B1,B3
      COMMON /FORM/ M1,M2,LC,JC,LIC,JJC,M3,N3
      COMMON /MSH/ S1,S2,S3,S4,P1,P2,P3,P4,JL,JU,IL,IR
      C
      CC SUBROUTINE IRL(J) FOR DETERMINING BOUNDARY POINTS FOR A IVEN
      CC ROW J,(J,IL(J)) IS THE FIRST INTERIOR POINT &(J,IR(J)) IS THE MAXIMUM
      CC INTERIOR POINT
      C
      IF(J.GT.N3) GO TO 1000                               01
      Y=(JC-J)*DY
      XX2=DABS(R*R-Y*Y)
      XX=DSQRT(XX2)
      X1=R-XX                                         05
      IL=(X1/DX+0.010000D0)+2
      IR=M3                                         07
      GO TO 4000                                         08
1000 CONTINUE
      IF(ISYM.EQ.1) GO TO 3000                           09
      IF(J.GT.JJC) GO TO 2000                           010
      Y=R-(J-1)*DY                                     011
      XX2=DABS(R*R-Y*Y)
      XX=DSQRT(XX2)
      X1=R-XX                                         014
      IL=(X1/DX+0.010000D0)+2
      YC=B+RC-(J-1)*DY                                016
      XXC=DABS(RC*RC-YC*YC)
      XC=DSQRT(XXC)
      X1=RC-XC                                         019
      IP=(X1/DX-0.010000D0)+41
      GO TO 4000                                         021
2000 CONTINUE
      IF(J.GT.JC) GO TO 3000                           022
      Y=(J-1)*DY-R                                     023
      XX2=DABS(R*R-Y*Y)
      XX=DSQRT(XX2)
      X1=R-XX                                         027
      IL=(X1/DX+0.010000D0)+2
      IR=M1-1                                         029
      GO TO 4000                                         030
3000 CONTINUE
      Y=(J-JC)*DY
      XX2=DABS(R*R-Y*Y)
      XX=DSQRT(XX2)
      X1=R-XX                                         035
      IL=(X1/DX+0.010000D0)+2
      IR=(XX/DX-0.010000D0)+1C
4000 CONTINUE
      RETURN
      END

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      SUBROUTINE ECSI(I)
      IMPLICIT REAL*8 (A-H,O-Z)
      COMMON /TNO/ ILD,I*R,ISYM,IPAP,IC00,IP,ICOM
      COMMON /DIMS/ R,RC,H,B,DX,DY,B1,BB
      COMMON /FORM/ M1,M2,IC,JC,ILC,JJC,M3,N3
      COMMON /MSH/ S1,S2,S3,S4,P1,P2,P3,P4,JL,JU,IL,IK
      COMMON /PHI/ P(50,30),PBX(2,30),PBK(50,2),PP(50,30),PBV(2,30),
      1 PBX1(50,2),F(50,30)
      COMMON /INPC/ PL,PU,PT,PR

C
C CALCULATE POTENTIAL FUNCTION ALONG THE B. FOR EACH I (PBX1,PBX2)
C
      IF(I .GE. IC) GO TO 180
      J=JL
      CALL IRL(J)
      CALL MESH(I,J)
      X=(IC-I)*DX
      YY=DABS(R*R-X*X)
      Y=DSQRT(YY)
      IF(ISYM.EQ.1) GO TO 100
      SS=S4*DY*X+DX*Y
      PL=(I+S4)*P(I+1,J)-S4*P(I+1,J+1)
      PBX(I,1)=(S4*Y*X*PL+DX*Y*P(I,J))/SS
      GO TO 101
100  PBX(I,1)=P(I,J)
      PL=PBX(I,1)
101  J=JU
      CALL IRL(J)
      CALL MESH(I,J)
      SS=S2*DY*X+DX*Y
      PU=(I+S2)*P(I+1,J)-S2*P(I+1,J-1)
      PBX(I,2)=(DX*Y*P(I,J)+DY*S2*X*PU)/SS
      GO TO 900
180  CONTINUE
      IF(I .GT. IC) GO TO 190
      J=JL
      PBX(I,1)=P(I,J)
      PL=PBX(I,1)
      J=JU
      PBX(I,2)=P(I,J)
      PU=PBX(I,2)
      GO TO 900
190  CONTINUE
      IF(I .GE. M1) GO TO 210
      J=JL
      PBX(I,1)=P(I,J)
      PL=PBX(I,1)
      J=JU
      IF(J.LE.N3) GO TO 216
      CALL IRL(J)
      CALL MESH(I,J)
      X=(I-IC)*DX
      YY=DABS(R*R-X*X)

```

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Y=DSQRT(YY)
SS=DY*S2*X+DX*Y
PU=(I+S2)*P(I-1,J)-S2*P(I-1,J-1)                      31
PBX(I,2)=(DX*Y+P(I,J)+S2*DY*X*PU)/SS                  32
GO TO 900                                                 33
34
210 PBX(I,2)=P(I,J)
PU=PBX(I,2)
GO TO 900
210 CONTINUE
IF(ISYM.EQ.1) GO TO 214
IF(I.GT.M1) GO TO 212
J=JL
PBX(I,1)=P(I,J)
PL=PBX(I,1)
J=JJ
PBX(I,2)=P(I-1,J+1)
PU=PBX(I,2)
GO TO 900
41
42
43
44
45
46
47
48
49
50
51
52
53
54
212 CONTINUE
IF(I.GT.IIC) GO TO 214
J=JL
PBX(I,1)=P(I,J)
PL=PBX(I,1)
J=JJ
CALL IRL(J)
CALL MESH(I,J)
X=RC-(I-M1)*DX
YY=DABS(RC*RC-X*X)
Y=DSQRT(YY)
SS=DY*S2*X+DX*Y
PU=(I+S2)*P(I-1,J)-S2*P(I-1,J-1)
PBX(I,2)=(DY*S2*X*PU+DX*Y*P(I,J))/SS
GO TO 900
214 CONTINUE
J=JL
PBX(I,1)=P(I,J)
PL=PBX(I,1)
J=JJ
PBX(I,2)=P(I,J)
PU=PBX(I,2)
900 CONTINUE
RETURN
END

```

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```

SUBROUTINE BCSJ(J,V1)
IMPLICIT REAL*8 (A-H,O-Z)
COMMON /TAD/ ILJ,IWR,ISYM,IPAP,ICOD,IP,ICDM
COMMON /DIMS/ R,RC,H,B,DX,DY,B1,B8
COMMON /DRM/ M1,M2,IC,JC,IIC,JJC,M3,N3
COMMON /MSH/ S1,S2,S3,S4,P1,P2,P3,P4,JL,JU,IL,IR
COMMON /PHI/ P(50,30),PBY(2,30),PBX(50,2),PP(50,30),PBY1(2,30),
      PBX1(50,2),F(50,30)
COMMON /INPO/ PL,PU,PT,PR

C
CC CALCULATE POTENTIAL FUNCTION ALONG THE B. FOR EACH J (PBY1,PBY2)
C
IF(J .GE. JC) GO TO 200
I=IL
CALL INTPL(I)
CALL MESH(I,J)
Y=(JC-J)*CY
XX=DABS(R*R-Y*Y)
X=DSQRT(XX)
SS=DY*X+DX*S1*Y
PT=(1+S1)*P(I,J+1)-S1*P(I+1,J+1)
PBY(1,J)=(DY*X*P(I,J)+DX*S1*Y*PT)/SS
I=IR
CALL INTPL(I)
CALL MESH(I,J)
IF(J .GT. N3) GO TO 110
PBY(2,J)=P(I,J)+DX*S3*V1
PR=PBY(2,J)
GO TO 900
110 CONTINUE
IF(J .GT. JJC) GO TO 120
Y=B+RC-(J-1)*DY
XX=DABS(RC*RC-Y*Y)
X=DSQRT(XX)
SS=DX*S3*Y+DY*X
PR=(1+S3)*P(I,J-1)-S3*P(I-1,J-1)
PBY(2,J)=(DY*X*P(I,J)+DX*S3*Y*PR)/SS
GO TO 900
120 CONTINUE
PBY(2,J)=P(I,J)
PR=PBY(2,J)
GO TO 900
200 CONTINUE
IF(J .GT. JC) GO TO 210
I=IL
PBY(1,J)=P(I,J)
PT=PBY(1,J)
I=IR
CALL INTPL(I)
CALL MESH(I,J)
IF(ISYM.EQ.1) GO TO 101
PBY(2,J)=P(I,J)
GO TO 102

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```
101 PBY(2,J)=P(I,J)+DX*S3*V1
102 PR=PBY(2,J)
GO TO 900
210 CONTINUE
I=IL
CALL INTPL(I)
CALL MESH(I,J)
Y=(J-JC)*DY
XX=DABS(R*R-Y*Y)
X=DSQRT(XX)
SS=DX*S1*Y+DY*X
PT=(I+S1)*P(I,J-1)-S1*P(I+1,J-1)
PBY(I,J)=(DX*S1*Y*PT+DY*X*P(I,J))/SS
I=IR
CALL INTPL(I)
CALL MESH(I,J)
IF(ISYM.EQ.0) GO TO 260
IF(J.GT.N3) GO TO 260
PBY(2,J)=P(I,J)+DX*S3*V1
PR=PBY(2,J)
GO TO 900
260 Y=(J-JC)*DY
XX=DABS(R*R-Y*Y)
X=DSQRT(XX)
SS=DX*S3*Y+DY*X
PP=(I+S3)*P(I,J-1)-S3*P(I-1,J-1)
PBY(2,J)=(DY*X*P(I,J)+DX*S3*Y*PR)/SS
900 CONTINUE
RETURN
END
```

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```

      SUBROUTINE HVVEL
      IMPLICIT REAL*8 (A-H,O-Z)
      COMMON /ONE/ V1
      COMMON /TDO/ ILU,IWR,ISYM,IPAP,ICOD,IP,ICOM
      COMMON /DIMS/ R,RC,I,B,DX,DY,B1,BB
      COMMON /FORM/ M1,M2,IC,JC,IIC,JJC,M3,N3
      COMMON /MSH/ S1,S2,S3,S4,P1,P2,P3,P4,JL,JU,IL,IR
      COMMON /PHI/ P(50,30),PBY(2,30),PBX(50,2),PP(50,30),PBY1(2,30),
      1   PBX1(50,2),F(50,30)
      COMMON /VEES/U(50,30),V(50,30),UBX(50,2),VBX(50,2),
      1   UBY(2,30),VBY(2,30),U1(50,30),V0(50,30),UBX1(50,2),
      1   ,VBX1(50,2),UBY1(2,30),VBY1(2,30),VV(50,30),ANGLE(50,30)
      COMMON /INPO/ PL,PU,PT,PR

C
C  CALCULATE VELOCITY COMPONENTS U,V IN THE X&Y DIR. (U=DX/DX ,V=DP/DY)
C
      IF(IWR.EQ.1) GO TO 25
      WRITE(6,14)
      WRITE(6,400)
      WRITE(6,107)
25    CONTINUE
      DO 10 I=2,M3
      CALL INTP_(I)
      DO 20 J=JL,JU
      CALL IRL(J)
      CALL MESH(I,J)
      C13=S1/(S3*(S3+S1))
      C31=S3/(S1*(S3+S1))
      C1=(S1-S3)/(S1*S3)
      C24=S2/(S4*(S2+S4))
      C42=S4/(S2*(S2+S4))
      C2=(S4-S2)/(S2*S4)
      U(I,J)=(P3*C13-P1*C31-P(I,J)*C1)/DX
      IF(J.EQ.1) P4=P2
      V(I,J)=(P2*C42-P4*C24-P(I,J)*C2)/DY
      IF(ILG.EQ.1) GO TO 20
      U1(I,J)=J(I,J)
      V0(I,J)=V(I,J)
      IF(IWR.EQ.1) GO TO 20
      WRITE(6,111) I,J,U(I,J),V(I,J)
20    CONTINUE
10    CONTINUE
      IF(IWR.EQ.1) GO TO 30
      IF(ISYM.EQ.1) GO TO 666
      WRITE(6,108)
      GO TO 30
666  WRITE(6,109)
30    IF(ISYM.EQ.1) IIC=M1
      DO 50 I=2,M3
      CALL INPL(I)
      IF(I.EQ.M3) GO TO 100
      J=JL
      CALL IRL(J)

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```
CALL MESH(I,J)
CALL BCSI(I)
IF(I.GE.IC) P_=PBX(I+1,1)
UBX(I,1)=(PL-PBX(I,1))/DX
VBX(I,1)=(P(I,J)-PBX(I,1))/(S4*DY)
J=JU
CALL IRL(J)
CALL MESH(I,J)
CALL BCSI(I)
IF(I.GE.IIC) PU=PBX(I+1,2)
UBX(I,2)=(PU-PBX(I,2))/DX
IF(I.GT.IC) UBX(I,2)=-UBX(I,2)
IF(I.GE.IIC) UBX(I,2)=-UBX(I,2)
VBX(I,2)=(PBX(I,2)-P(I,J))/(S2*DY)
GO TO 900
100 CONTINUE
J=JL
UBX(I,1)=(PBX(I,1)-PBX(I-1,1))/DX
VBX(I,1)=(P(I,J)-PBX(I,1))/DY
J=JJ
CALL IRL(J)
CALL MES4(I,J)
CALL BCSI(I)
USX(I+2)=(PBX(I,2)-PBX(I-1,2))/DX
VBX(I,2)=(PBX(I,2)-P(I,J))/(S2*DY)
900 CONTINUE
IF(IL0.EQ.1) GO TO 50
UBX1(I,1)=UBX(I,1)
VBX1(I,1)=VBX(I,1)
UBX1(I,2)=UBX(I,2)
VBX1(I,2)=VBX(I,2)
IF(IWR.EQ.1) GO TO 50
IF(ISHY.EQ.1) GO TO 103
WRITE(6,310) UBX(I,1),VBX(I,1),USX(I,2),VBX(I,2)
GO TO 50
103 WRITE(6,210) UBX(I,2),VBX(I,2)
50 CONTINUE
M21=M2-1
IF(IWR.EQ.1) GO TO 15
WRITE(6,777)
15 CONTINUE
DO 60 J=2,M21
CALL IR_(J)
I=IL
CALL INTPL(I)
CALL MESH(I,J)
CALL BCSJ(J,V1)
UBY(I,J)=(P(I,J)-PBY(I,J))/(S1*DX)
VBY(I,J)=(PT-PBY(I,J))/DY
IF(J.GE.JC) VBY(I,J)=-VBY(I,J)
I=IR
CALL INTPL(I)
CALL MESH(I,J)
.
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```
CALL BCSJ(J,V1)
IF(J.GT.N3) GO TO 180
UBY(2,J)=(PBY(2,J)-P(I,J))/(S3*DX)
VBY(2,J)=0.000
GO TO 2000
180 CONTINUE
IF(ISYM.EQ.1) GO TO 240
IF(J.GT.JJC) GO TO 190
UBY(2,J)=(PBY(2,J)-P(I,J))/(S3*DX)
VBY(2,J)=(PBY(2,J)-PR)/DY
GO TO 2000
190 CONTINUE
IF(J.GE.JC) GO TO 220
UBY(2,J)=(PBY(2,J)-P(I,J))/DX
VBY(2,J)=(PBY(2,J+1)-PBY(2,J))/DY
GO TO 2000
220 CONTINUE
IF(J .GT. JC) GO TO 240
UBY(2,J)=(PBY(2,J)-P(I,J))/DX
VBY(2,J)=(PBY(2,J)-PBY(2,J-1))/DY
GO TO 2000
240 CONTINUE
JBY(2,J)=(PBY(2,J)-P(I,J))/(S3*DX)
VBY(2,J)=(PBY(2,J)-PR)/DY
2600 CONTINUE
IF(IL3.EQ.1) GO TO 60
UBY1(1,J)=UBY(1,J)
VBY1(1,J)=VBY(1,J)
UBY1(2,J)=UBY(2,J)
VBY1(2,J)=VBY(2,J)
IF(IWR.EQ.1) GO TO 60
WRITE(6,310) JBY(1,J),VBY(1,J),UBY(2,J),VBY(2,J)
60 CONTINUE
14 FORMAT(1H1)
107 FORMAT(//,10X,"I      ",5X,"J      ",5X,"U      ",20X,"V      ")
108 FORMAT(//,10X,"UBX1    ",15X,"VBX1    ",15X,"UBX2    ",15X,"VBX2    ")
111 FORMAT(10X,IS,5X,I5,10X,D15.6,10X,D15.6)
210 FORMAT(//,10X,2(5X,D15.6))
310 FORMAT(//,10X,4(5X,D15.6))
400 FORMAT(10X,"VELOCITY COMP. U&V IN THE X& Y DIR.",//)
777 FORMAT(//,10X,"UBY1    ",15X,"VBY1    ",15X,"UBY2    ",15X,"VBY2    ")
109 FORMAT(//,15X,"UBX2    ",15X,"VBX2    ",/)
RETURN
END
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SUBROUTINE PLTISD(JMAXG,ISYMBL,IUPUDW,SIZE,VISOBR,VAR,X,Y)
IMPLICIT REAL*8 (A-H,D-Z)
COMMON /MSH/ S1,S2,S3,S4,P1,P2,P3,34,JL,JU,IL,IR
DIMENSION VAR(32,21),X(32,21),Y(32,21)
IC=ISYMBL
ICA=IUPUDW
JMAXG1=JMAXG-1
NNN=1
1115 CONTINUE
1113 DC 1128 J=1,JMAXG1
CALL IRL(J)
DO 1130 INV=IL,IR
IIB=1
I=IR+I_-INV
1103 IF((VAR(I,J).GT.VISOBR).AND.(VAR(I,J+1).GT.VISOBR)) GO TO 1117
IF((VAR(I,J).LT.VISOBR).AND.(VAR(I,J+1).LT.VISOBR)) GO TO 1117
IIB=1
DS= X(I,J+1)- X(I,J)
DSS=DSS*(VISOBR-VAR(I,J))/(VAR(I,J+1)-VAR(I,J))
C YYB= ( Y(I,J)+ Y(I,J+1))/2.
DN= Y(I,J+1)- Y(I,J)
DNN=DNN*(VISOBR-VAR(I,J))/(VAR(I,J+1)-VAR(I,J))
XXB= ( X(I,J)+DSS)
YYB= ( Y(I,J+1)-(DN-DNN))
WRITE(6,1114) XXB,YYB,I,J,VISOBR,VAR(I,J+1),VAR(I,J),DS,DN
1114 FORMAT(2X,'XXB=',F10.5,2X,'YYB=',F10.6,2X,'I=',I3.2A,'J=',I2.2A,
1 'VISOBR=',F14.6,3X,4(F10.6))
IF(NNN.EQ.1) GO TO 1116
CALL SYMBOL(XXB,YYB,SIZE,IC,0.,-1)
C CALL SYMBOL (-YYB,XXB,SIZE,IC,0.,-1)
CCC CALL SYMBOL_(XXB,YYB,SIZE,IC,0.,-ICA)
GO TO 1120
1116 NNN=0
CALL SYMBOL_(XXB,YYB,SIZE,IC,0.,-1)
C CALL SYMBOL (-YYB,XXB,SIZE,IC,0.,-1)
GO TO 1120
1117 IIB=2
IF((VAR(I,J).GT.VISOBR).AND.(VAR(I-1,J).GT.VISOBR)) GO TO 1123
IF((VAR(I,J).LT.VISOBR).AND.(VAR(I-1,J).LT.VISOBR)) GO TO 1125
1109 DN=( Y(I,J)- Y(I-1,J))
DNN=DNN*(VISOBR-VAR(I-1,J))/(VAR(I,J)-VAR(I-1,J))
YYB= ( Y(I,J)-(DN-DNN))
DS= X(I,J)- X(I-1,J)
DSS=DSS*(VISOBR-VAR(I-1,J))/(VAR(I,J)-VAR(I-1,J))
XXB= ( X(I,J)-(DS-DSS))
WRITE(6,1114) XXB,YYB,I,J,VISOBR,VAR(I-1,J),VAR(I,J),DS,DN
IF(NNN.EQ.1) GO TO 1118
ICA=2
IF(IIB.EQ.2) ICA=1
CALL SYMBOL_(XXB,YYB,SIZE,IC,0.,-ICA)
C CALL SYMBOL (-YYB,XXB,SIZE,IC,0.,-1)
IF(IIB.EQ.1) GO TO 1127
GO TO 1124

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1118 NNN=0
    CALL SYMBOL (XXB,YYB,SIZE,IC,0.,-1)
C   CALL SYMBOL (-YYB,XXB,SIZE,IC,0.,-1)
    IF(IIB.EQ.1) GO TO 1127
    GO TO 1124
1120 IF((VAR(I-1,J+1).GT.VISOBR).AND.( VAR(I,J+1).GT.VISOBR)) GO TO
1124
    IF((VAR(I-1,J+1).LT.VISOBR).AND.( VAR(I,J+1).LT.VISOBR)) GO TO
1124
1121 DN=( Y(I,J+1)- Y(I-1,J+1))
DNN=DNN*(VISOBR-VAR(I-1,J+1))/(VAR(I,J+1)-VAR(I-1,J+1))
YYB=      ( Y(I,J+1)-(DN-DNN))
DS= X(I,J+1)- X(I-1,J+1)
DSS=DSS*(VISOBR-VAR(I-1,J+1))/(VAR(I,J+1)-VAR(I-1,J+1))
XXB=      ( X(I,J+1)-(DS-DSS))
*RITE(6,1114) XXB,YYB,I,J,VISOBR,VAR(I-1,J+1),VAR(I,J+1),DS,DN
    IF(NNN.EQ.1) GC TO 1122
    CALL SYMBOL (XXB,YYB,SIZE,IC,0.,-2 )
C   CALL SYMBOL (-YYB,XXB,SIZE,IC,0.,-1)
CCC  CALL SYMBOL (XXB,YYB,SIZE,IC,0.,-ICA)
    GO TO 1127
1122 NNN=0
    CALL SYMBOL (XXB,YYB,SIZE,IC,0.,-1)
C   CALL SYMBOL (-YYB,XXB,SIZE,IC,0.,-1)
    GO TO 1127
1124 IF((VAR(I-1,J).GT.VISOBR).AND.(VAR(I-1,J+1).GT.VISOBR).AND.(IIB.EQ
1.1)) GO TO 1109
    IF((VAR(I-1,J).LT.VISOBR).AND.(VAR(I-1,J+1).LT.VISOBR).AND.(IIB.EQ
1.1)) GO TO 1109
    IF((VAR(I-1,J).GT.VISOBR).AND.(VAR(I-1,J+1).GT.VISOBR).AND.(IIB.EQ
1.2)) GO TO 1121
    IF((VAR(I-1,J).LT.VISOBR).AND.(VAR(I-1,J+1).LT.VISOBR).AND.(IIB.EQ
1.2)) GO TO 1121
    GO TO 1125
1125 IIB=5
    IF((VAR(I-1,J).GT.VISOBR).AND.(VAR(I-1,J+1).GT.VISOBR)) GO TO 1127
    IF((VAR(I-1,J).LT.VISOBR).AND.(VAR(I-1,J+1).LT.VISOBR)) GO TO 1127
1126 DS= X(I-1,J+1)- X(I-1,J)
DSS=DSS*(VISOBR-VAR(I-1,J))/(VAR(I-1,J+1)-VAR(I-1,J))
XXB=      ( X(I-1,J)+DSS)
DN= Y(I-1,J+1)- Y(I-1,J)
DNN=DNN*(VISOBR-VAR(I-1,J))/(VAR(I-1,J+1)-VAR(I-1,J))
YYB=      ( Y(I-1,J+1)-(DN-DNN))
*RITE(6,1114) XXB,YYB,I,J,VISOBR,VAR(I-1,J),VAR(I-1,J+1),DS,DN
    IF(NNN.EQ.1) GC TO 1126
    ICA=2
    IF(IIB.EQ.5) ICA=1
    CALL SYMBOL (XXB,YYB,SIZE,IC,0.,-ICA)
    IF(IIB.EQ.5) GC TO 1121
    GO TO 1127
1127 NNN=0
    CALL SYMBOL (XXB,YYB,SIZE,IC,0.,-1)
C   CALL SYMBOL (-YYB,XXB,SIZE,IC,0.,-1)

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IF(11B.EQ.5) GO TO 1121
1127 CONTINUE
1130 CONTINUE
1128 CONTINUE
NNN=1
RETURN
END
```

INPUT DATA

In the following, the different parameters used to specify the cases that can be computed using the computer program, will be explained, then a description in details of how to prepare the input data will be given.

Control Parameters for Computations

1. (a) Symmetric scroll cross section, ISYM = 1.
(b) Nonsymmetric scroll cross section, ISYM = 0.
2. The type of through flow profile is specified using the parameters IFG, IFREVO, and IPAP.
 - (a) IFG = 1, IPAP = 0, IFREVO = 0, for an arbitrary source distribution. In this case the source strength is fed as an input at all the interior mesh points.
 - (b) IPAP = 1, IFG = 0, IFREVO = 0, for a circular paraboloid source distribution.
 - (c) IFREVO = 1, IPAP = 0, IFG = 0, for free vortex source distribution.
 - (d) IFG = 0, IPAP = 0, IFREVO = 0, represents uniform source distribution.
3. Either compressible or incompressible flow solutions are obtained by specifying the value of the parameter ICOM. Compressible flow solutions specify ICOM = 1, and for incompressible flow case ICOM = 0.

How to Prepare the Input

The input is divided into seven sets, and is given in the following.

First Set (Fluid Properties), one card

READ: RG, GAMA, TO, VE
according to format (4F10.0)

Second Set (Scroll Geometry), one card

READ: M1, M2, DO, RL, B, H, R, RC
according to format (2I10, 6F10.0)

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Third Set (Control Parameters), one card

READ: ICOM, ISYM, IFG, IPAP, IFREVO
according to format (5I10)

Fourth Set (Numerical Parameters), one card

READ: ITMAX, EPSMAX, WO, WOP
according to format (I10, 3F10.0)

Fifth Set (Output Control Parameters), one card

READ: IP, IVPLOT, IPLT
according to format (3I10)

Sixth Set (Values for Velocity Potential Contour Plotting),

number of cards is equal to IPLT

READ: VISOBR
according to format (F10.0)

VISOBR Numerical values of the velocity potential
contours to be plotted as output.

Seventh Set (Arbitrary Source Distribution)

Is required only in the case of arbitrary source distribution, i.e., IFG = 1. The value of the source distribution F(I,J) is read in DO loop according to format (8F10.0). The input data is fed starting from I = 1 to I = M₃, and marching in J direction from J = JL, JU as shown in Fig. 3a. (Ref. 1)

OUTPUT

The program output includes a printout of the pertinent flow properties at all the grid points every IP iteration and of two figures, one for the desired velocity potential contours as specified by IPLT and VISOBR and the second showing the velocity direction in the cross-sectional plane.

Samples of the program output are included in Ref. 1.

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