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Advanced Space Power Requirements and Techniques

Task 1: Mission Projections and Requirements

Volume I: Technical Report

Prepared by

Advanced Mission Analysis Directorate Advanced Orbital Systems Division

1 March 1978

Prepared for

NATIONAL AERONAUTICS AND SPACE ADMINISTRATION Washington, D. C.

Contract No. NASW-3078



Systems Engineering Operations

THE AEROSPACE CORPORATION

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TASK 1: MISSION PROJECTIONS AND REQUIREMENTS

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والمسابقة والمرتبعة المستحد المناري المواركة المتحادة مستحدية وسنتجوض ورجاور والمحاك فستحاف

ADVANCED SPACE POWER REQUIREMENTS AND TECHNIQUES TASK 1: MISSION PROJECTIONS AND REQUIREMENTS

Volume I: Technical Report

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FOREWORD

This is Volume I of a three-volume report. The report documents the results of Task 1 of a study entitled, "Advanced Space Power Requirements and Techniques" performed under NASA Headquarters Contract No. NASW-3078 during fiscal years 1977 and 1978. Task 2 is documented separately.

The Task 1 effort was directed by Dr. Malcolm G. Wolfe of the Advanced Applications Analysis Office. Mr. Jerome P. Mullin (Code RP) of NASA Headquarters was the NASA study director. Technical direction was also provided by Mr. Lee Holcomb of NASA Headquarters, speaking for Mr. Mullin.

The report consists of the following three volumes:

Volume I: Technical Report Volume II: Classified Addendum Volume III: Appendices

10 14

Volume I is an unclassified volume which describes the results of the technical studies that were performed as part of the effort. The study encompassed DoD as well as NASA and civil missions and mission requirements. Volume II is a classified volume which includes data which could not be included in Volume I for national security reasons. Volume III is unclassified and contains ancillary information, such as computer printout, which was generated during the course of the study.

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1

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1. INTRODUCTION

1.1 OBJECTIVES

The objectives of this study are to:

- 1. Develop projections of the NASA, DoD, and civil space power requirements for the 1980-1995 time period
- 2. Identify specific areas of application and space power subsystem type needs for each prospective user group
- 3. Document the supporting and historical base, including relevant cost-related measures of performance
- 4. Quantify the benefits of specific technology projection advancements.

1.2 SCOPE

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The initial scope of this study included:

- 1. Construction of likely mission models for NASA, DoD, and civil space systems in the 1980-1995 time period
- 2. Generation of a number of future scenarios
- 3. Extraction of time-phased technology requirements based on the scenarios
- 4. Cost/benefit analyses of some of the technologies identified.

Major emphasis was to be placed on the development of technology projections.

During the study NASA directed the inclusion of a development of NASA, DoD, and civil traffic models, together with the corresponding life-cycle costs, within specified budgetary constraints. Two budgetary levels were to be studied, one conservative and one optimistic, for each

of the three user groups; and to define the budgetary constraints in terms of average yearly cost expenditures during the 1980-1995 time period. Because of this reorientation, the planned effort in the areas of technology projections and cost/benefit analysis was de-emphasized.

1.3 APPROACH

Since the study emphasis was reoriented partway through the effort, the results of both the original and the modified approaches are documented herein. One of the approaches emphasizes a future in which large multipurpose, multi-user satellites will be the objective of early development and deployment; the other approach emphasizes a future in which many dedicated, single-user satellites will be deployed in the near and mid term, with large multipurpose satellites not being introduced until the far term.

The scenarios, mission models, and traffic models are, in general, synthesized from modified and amplified extractions from the prior efforts described in the documents listed in the bibliography to this report. They have no official NASA or DoD standing and very few can be traced to a single document source; however, the significant characteristics are articulated in such a way that they can be used as a base for determining the impact of changes in NASA or DoD policy or as a departure point for performing sensitivity analyses in future studies.

The first approach adopted in this study was to use the output of previous NASA studies (References 1 and 2), which themselves included the results of a number of other studies, to prepare a set of future mission scenarios. The power requirements to satisfy the needs of the missions included in these scenarios were then determined.

The second approach adopted in this study is illustrated in Figure 1-1. Individual low and high average yearly budget goals were selected for each of the three user groups (NASA, DoD, and civil). The budget levels

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Figure 1-1. Study Plan

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that were selected are listed in Table 1-1. Mission models and, from these, traffic models were synthesized and the corresponding average yearly cost expenditures estimated. An iterative process was used, modifying the mission/traffic models to meet the budgetary goals established by Table 1-1. The missions included in the mission/traffic models were extracted from prior efforts described in a number of documents, as described later in this report. Some of the ground rules and assumptions that were used during the course of the effort are delineated in Appendices I and II, Volume III to this report.

Historical space power requirements and technologies were compiled and anticipated capabilities extrapolated into the future. The technology requirements arising out of the scenario development effort then were compared with future anticipated capabilities. Finally, a simplified cost/benefit analysis was performed.

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ORGANIZATION	CONSERVATIVE BUDGET (\$B)	OPTIMISTIC BUDGET (\$B)	
NASA			
Institutional	2.0	2.0	
Transportation	1.0	2.0	
Programs	1.0	2.0	
Total	4.0	6.0	
DoD Programs	0.7	1.5	
Civii (Non-NASA, Non-DoD Programs)	0.5	1.0	

Table 1-1. Assumed Average Yearly Budget Goals for 1980-1995

Notes:

- (1) Budgets are in 1977 dollars.
- (2) Budgets are averages and therefore peak budgets will exceed these values in certain years.

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2. HISTORICAL SPACE POWER TRENDS

2.1 HISTORICAL POWER LEVEL REQUIREMENTS

Using References 3 through 7, a survey was made of satellites launched or planned to be launched during the 1959-1979 time period, together with their user group, function, power system type and prime power requirements. The results are listed in Appendix III, Volume III to this report. Scatter diagrams of power versus launch date for the satellite programs listed in Appendix III were prepared for each user group and are shown in Figures 2-1 through 2-4. A trend line of 100 watts per year is shown for reference purposes. The single point which lies above this trend line is the OAO 2 launch of 7 December 1968, which is given in Reference 8 as 1400 W.

2.2 POWER LEVEL REGRESSION ANALYSIS

A general problem solving computer program (GYPSY) was used to perform a regression analysis on the historical prime power requirements data. A total of 175 launches were used, including 96 NASA, 44 DOD and 35 civil data points.

The computer program considers eight types of equation, viz:

1.
$$Y = A + BX + CX^{2} + DX^{3}$$
$$Y = A + BX + CX^{2}$$
$$Y = A + BX$$
2.
$$I/Y = A + BX + CX^{2} + DX^{3}$$
$$I/Y = A + BX + CX^{2}$$
$$I/Y = A + BX + CX^{2}$$

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 $(1,1,2,\dots,2^{n}) \in \mathbb{R}^{n} \times \mathbb{$



Figure 2-1. NASA Satellites Prime Power Trend, 1959-1979



Figure 2-2. DoD Satellites Prime Power Trend, 1959-1979



Figure 2-3. Civil Satellites Prime Power Trend, 1959-1979



3.
$$Y^{2} = A + BX + CX^{2} + DX^{3}$$
$$Y^{2} = A + BX + CX^{2}$$
$$Y^{2} = A + BX$$

4.
$$LnY = A + BX + CX^{2} + DX^{3}$$
$$LnY = A + BX + CX^{2}$$
$$LnY = A + BX$$

5.
$$X/Y = A + BX + CX^{2} + DX^{3}$$
$$X/Y = A + BX + CX^{2}$$
$$X/Y = A + BX + CX^{2}$$
$$X/Y = A + BX$$

6.
$$Y = AB^{X}$$

7.
$$Y = Ae^{BX}$$

8.
$$Y = AX^{B}$$

and bases its selection on high correlation and low standard deviation of residuals. The best fit to all the data was found to be:

$$LnP = A + BM + CM^2 + DM^3$$

where: P = Prime power in watts

M = Number of months after June 1959

and the coefficients are as follows:

	А	В	С	D
NASA	6.41	-0.0186	$6 \ge 10^{-5}$	5×10^{-8}
DoD	6.9	-0.06	0.0005	-10×10^{-5}
Civil	5.4	-0.05	$6 \ge 10^{-4}$	$-2 \ge 10^{-6}$
A11	6.5	-0.0377	-0.00029	$-6 \ge 10^{-7}$

Computer plots of the output are shown in Figures 2-5 through 2-8.



Power in Watts

Figure 2-5. Satellite Prime Power Regression Analysis - NASA



Number of Months After June 1959





Number of Months After June 1959

Figure 2-7. Satellite Prime Power Regression Analysis - Civil



Number of Months After June 1959



2.3 POWER SYSTEM COSTS

2.3.1 Background

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For a number of years The Aerospace Corporation has collected satellite and launch vehicle hardware costs on ongoing programs from government and private industry sources and incorporated them into a computerized cost data bank. This data bank has a number of uses, including being used as a base for developing future subsystem nonrecurring and recurring costs and is being constantly expanded. It has been found expedient to organize the data to suit the accounting procedures of industry as much as possible and the format used for the satellite power system is illustrated in Table 2-1.

2.3.2 Ground Rules and Assumptions

In addition to the guidelines delineated in Appendices I and II, Volume III to this report, the following specific ground rules and assumptions were used to develop the costs reported below:

- 1. Only unmanned satellite data is included.
- The programs utilized include: OGO A-C; OGO D-F; Tiros-M; Nimbus-D; SMS; ATS-F; OSO-I; VELA; VASP; TACSAT; DSP; DSCS-II; STP 72-2; GPS.
- 3. All program quantities are adjusted to a quantity of 5 for comparability.
- 4. All dollar figures represent prime contractor cost (less fee) and are adjusted to constant 1977 dollars.
- 5. Costs include supplier and prime contractor effort plus allocated system related costs (i.e., system engineering and integration, assembly, test and checkout, quality control and program management).
- 6. The electrical power subsystem is composed of solar arrays, drives (if required), batteries, power control units, shunt elements, converters and wiring.

Table 2-1. Satellite Power System Cost Summary Format

SATELLITE _____ W, BOL Pwr, ____ W, Avg Pwr,

First Launch 19___

Cost Category	Solar Array (sq ft)	Battery (A-H)	Power Control Unit	Converters	Wiring	Drive	Total
Non-recurring							
Design Engrg.							
Test & Eval.							
Recurring (5 Sat.)							
Syst. Engrg.							
Production		27 1 					• •
Total (1977 \$)							
Average (5 Sat.)		<u> </u>					<u> </u>
Subsystem Weight/Sa	atellite Weight						. * •
Cost/lb. (kg)		···· · · · · · · · · · · · · · · · · ·					•
$Cost/ft^2(m^2)$							
Cost/A-H			•				
Cost/kW-H							

2.3.3 Cost Analyses

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Historical electric power subsystem costs were analyzed for the years 1963 through 1977 and the percentage distribution by major component is listed in Table 2-2. The electrical subsystem cost per kilowatt-hour as a function of year of first flight is given in Figure 2-9 and as a function of kilowatt hour in Figure 2-10. The data is scattered but, as shown, some trend lines can be postulated.

	+ +				
Year of 1st Launch	Solar Array	Batteries	PCU Plus Converters	Wiring	Array Drives
1963	43, 3	16.7	37.0	2.9	
1964	23.5	22.6	15.8	23.6	14.6
1967	34.2	9.6	45.8	10,3	-
1967	21.6	10.9	23.1		44.4
1969	62.5	9.0	15.9	12.6	1 <u>1</u>
1970	46.2	13.2	32.2	8,5	-
1970	9.3	11.1	9.2	22,4	48.0
1971	46,0	12.1	28.9	13.0	-
1971	21.4	19.3	32.1	27.1	-
1974	26.9	8.9	26.5	37.8	
1974	34.2	15.9	33.6	16.3	-
1975	23.3	12.1	36.7	28.0	-
1975	18.4	14.7	43.3	23.6	-
1977	10.8	9.9	41.6	9.4	28.4
1		1			

Table 2-2. Satellite Electrical Power Cost Percentage Distribution by Major Components

2-15







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Figure 2-10. Electrical Subsystem Cost per kW-hr vs. $$\rm kW{\mbox{-}hr}$$

2-16

COST PER kW-hr (1977 DOLLARS)

3. FUTURE SPACE POWER REQUIREMENTS

3.1 INTRODUCTION

As stated earlier, two approaches were used to develop future space power requirements. One approach emphasizes a future in which large multipurpose, multi-user satellites will be the objective of early development and deployment; the other approach emphasizes a future in which many dedicated, single-user satellites will be deployed in the near and mid term, with large multipurpose satellites not being introduced until the far term. As far as total power requirements are concerned, the two approaches lead to more or less the same conclusions since, in general, the accumulation of several initiatives on one space platform results in a corresponding accumulation of total power. Where differences will occur, however, is in such areas as the need for supporting and folding large solar arrays and the establishment of policies for the design, development and deployment of remote space power modules. If remote space power modules are used to supply power to other satellites via laser or microwave links, consideration must be given to whether they have to supply a multitude of low-powered satellites or a small number of high-powered satellites.

3.2 MISSION/TRAFFIC MODELS

A number of sources (References 8 through 28) together with judgment was used to assemble information necessary to construct the traffic models shown in Figure 3-1 through 3-17. Some of the basic design and cost assumptions are delineated in Appendices I, II and IV, Volume III, to this report. Appendix IV lists the basic mission and design characteristics assigned to each initiative included in the traffic models and also the assumed launch vehicle combination; Appendix II lists the performance and cost characteristics of the launch vehicles which are assumed to develop the costs listed in Figures 3-1 through 3-17; Appendix I lists some general guidelines and assumptions. The methods used for developing costs are described in References 29 and 30.

	FUNC	TION	MISSION			,
	Category	Subcategory	Code	Title	Destination (Alt. / Incl.)	Power (kW)
	Earth Resource Monitoring	Automated	NO1-1-1 -2 -3 -4	Landsat Follow-on Earth Survey Satellite Geosync. GRANSAT	Low/Low Low/High Geosync. Low/High	1.3 1.2 1.2 0.35
			-5 -6 -7 -8	MAGSAT B SMIAS HCMM Follow-on STEREOSAT	HIGH/ LOW	1.1 1.1 0.84
······································		Spacelab	NO1-2-1	Spacelab Payloads	Low/Int.	7.5
				Beginnin Solar Arr Power Su Solar Arr Power Su Dower Su	of Life Power (kW) ay Weight (lb) bsystem Weight (lb 2 ray Cost (\$ X 10 ⁵) bsystem Cost (\$ X 10	<u>(10³)</u>
	Environmental Monitoring	Automated	NO2-1-1 -2 -3 -4 -5	<u>Total Press</u> SEASAT -B Environ. Monitoring Sat. HALOE STORMSAT ERBSS	Low/High Low/High Geosync.	3.5 1.8 1.3 1.4 0.47
		Spacelab	NO2-2-1 -2	ACPL Spacelab Payloads	Low/Low Low/High	1.9 3.0
				Beginning Solar Arı Power Su Solar Arı Power Su Total Port	a of Life Power (kW) ay Weight (lb) bsystem Weight (lb) ay Cost (\$ X 10 ⁶) bsystem Cost (\$ X 10 ⁶)	<u>(103)</u>
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		ter en				an a
1						
		TAT TUOUIOE				
		LIDIDOTI FRAME				

NEAR-TERM							MID-TERM										COSTS (\$M)			
1979	1980	1981	1982	1983	1984	1985	1986	1987	1988	1989	1990	1991	1992	1993	1994	1995	Acq	Ops	Total	Avg
		1	1 1	1	1	1	1	1 1 1	1 1	1 1 1	1	1 1 1	1	1 1	1	1 1 1				
1 3 82	2 9 176	1 70 1 6 163	2 120 63	3 76	2 70 1 2 7 136	1 70 4 8 157	2 130 2 8 136	3 200 1 2 9 123	60 3 94	2 130 2 1 5 86	2 140 3 77	3 130 2 73	1 60 2 4 72	3 • 140 3 3 73	1 70 1 4 93	4 190 1 3 52	8 30 566	12 50 1166	20 80 1732	1.2 4.7 102
	1	1	1	1 1 1 1	1	1 1	1	1 1 1	1	1	1 1 1 1	1 1	1 1	1 1 1	1 1 1	1 1				
2 7 116	1 70 .2 2 .6 107	3 190 .6 1 4 74	1 4 72	2 140 .5 2 4 35	<u>1</u> 27	.4 1 5 69	2 100 .5 2 2 61	1 80 2 26	1 24	345	3 180 .7 2 23	17	2 2 35	1 80 .5 2 36	2 100 .4 1 23	2 26	7 23 344	6 25 472	13 28 216	0.8 1.6 48

Figure 3.1 Traffic Model - NASA Observation (Nominal Budget)

3-3

FOLDOUT FRAME
FUNC	TION		MIS	SION	
Category	Subcategory	Code	Title	Destination (Alt./Incl.)	Power (kW)
Intergovernment Links		NC1-1-1 -2 -3 -4	Hotline Intergovernment - I '' - II '' - III Beginnin	Geosync. "" g of Life Power (kW)	2.0 2.0 3.5 5.0
			Solar Ar Power Su Solar Ar Power Su Total Pro	ray Weight (lb) bsystem Weight (lb X ray Cost (\$ X 10 ⁶) bsystem Cost (\$ X 10 ⁶) ogram Cost (\$ X 10 ⁶)	(10 ³)
Gov't to People Links		NC2-1-1 -2	Voting/Polling - I " - II	Geosync.	1.0 50
			Beginnin Solar Ar Power Su Solar Ar Power Su Total Pro	g of Life Power (kW) ray Weight (lb) bsystem Weight (lb X ray Cost (\$ X 10 ⁶) bsystem Cost (\$ X 10 ogram Cost (\$ X 10 ⁶)	(10 ³) (6)
Intra Gov't Links	Routine	NC4-1-1 -2	Electronic Mail - I	Geosync.	5.0 15
	Emergency	NC4-2-1 -2	Emergency - I " - II	Geosync.	2.0 5.0
			Beginnin Solar Ar Power Su Solar Ar Power Su Total Pre	g of Life Power (kW) ray Weight (lb) bsystem Weight (lb X ray Cost (\$ X 10 ⁵) bsystem Cost (\$ X 10 ogram Cost (\$ X 10 ⁶)	5 10 ³) 6)

FOLDOUT ERAME

		NE/	AR-TE	RM							MID	-TERN	1					COST	S (\$M	[)
1979	1980	1981	1982	1983	1984	1985	1986	1987	1988	1989	1990	1991	1992	1993	1994	1995	Acq	Ops	Total	Avg
3 84	3 7 222	1 110 .5 2 7 218	3 7 208	1 110 .5 1 5 180	1 <u>3</u> <u>190</u> .7 <u>1</u> <u>6</u> <u>152</u>	2 6 192	1 110 .6 3 6 186	1 5 280 .8 2 4 146	1 110 .6 3 98	1 190 .7 1 2 54	3 95	1 2 110 .5 2 5 137	1 5 280 .8 1 4 126	1 110 .5 2 3 91	1 1 190 .7 1 24		9 29 841	14 43 1372	23 72 2213	1.4 4.2 130
	1		1	<u>1</u> 17	1 2 52 1	3	1 1 60 .5 1 16 1	6	1 12 1	· 1 <u>4</u> <u>60</u> 1	1 1 60 .5 3 6 127 1	6 10 201	5 10 210 1	1 50 1380 2.2 3 5 95 1	1 1 60 .5 7 1	1	12 24 474	9 18 383	20 42 857	<u>1.2</u> 2.5 50
3 8 230	2 110 .5 1 7 216	3 8 220	5 280 .8 2 6 219	5 10 239	5 280 .8 3 7 221	3 8 195	15 690 1.3 2 6 155	2 110 .6 1 4 145	5 280 .8 3 6 160	5 280 .8 2 5 137	15 690 1.3 1 3 82	1 4 114	5 280 .8 2 5 134	2 110 .5 4 6 161	15 690 1.3 5 119	5 280 .8 1 1 29	13 37 1017	24 62 1759	37 99 2776	2.2 5.8 16:

Figure 3.2 Traffic Model - NASA Communications (Nominal Budget)

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FOLDOUT FRAME

FUN	CTION		MIS	SION	
Category	Subcategory	Code	Title	Destination (Alt. / Incl.)	Power (kW)
Space Processing	Spacelab	NS1-1-1 -2	Space Processing Spacelab R&D Facility	Low/Low Low/Low	5.0 10
	Space Station	NS1-2-1	Extended Mission Vehicle	Low/Low	5.5
			Beginning o Solar Array Power Subs Solar Array Power Subs Total Progr	f Life Power (kW) 7 Weight (lb) 9 Stem Weight (lb X 1 7 Cost (\$ X 10 ⁶) 9 Stem Cost (\$ X 10 ⁶) 9 am Cost (\$ X 10 ⁵)	03)
Orbital Operations		NS3-1-1 -2 -3 -4 -5 -6	Large Struc. Deployment Skylab Revisit Tethered Sat. Op. Satellite Retrieval Shuttle External Tank Usage Launch Retrieval & Refueling of Upper Stages	Low/Low Low/Low Low/Low Low/Low Lcw/Low Low/Low	10 1.0 0.5 1.0 1.0 1.0
		- 	Beginning o	f Life Power (kW)	- 41 18
			Power Subs	ystem Weight (lb X 1	03)
			Solar Array	/ Cost (\$ X 106)	
			Total Progr	ram Cost (\$ X 10 ⁶)	
Satellite Power		NS4-1-1 -3 -5 -6 -2	25 kW Power Module 2 MW Power Module 1,2 GW Power Module 10 GW Power Station 250 kW Power Module	Low/Low Geosync. Geosync. Geosync. Low/Low	25 2 X 103 12 X 105 10 X 106 250
			Beginning o	of Life Power (kW)	
			Power Subs	ystem Weight (lb X]	03)
			Solar Array	y Cost (\$ X 106)	
			Total Prog	ram Cost $(\$ X 10^6)$	



			NE	AR-TE	RM							MID	-TERA	٨					COST	S (\$N	1)
r	1979	1980	1981	1982	1983	1984	1985	1986	1987	1988	1989	1990	1991	1992	1993	1994	1995	Acq	Ops	Total	Avg
3	10 179	1 25 820 1.6 5 10 123	1 1 1 550 1.1 1 4 63	1 1 1 1 1 2 4 50	1 1 550 1.1 1 2 43	1 1 1 2 4 49	1 1 550 1.1 1 1 1 1 7	1	1	1 1 2 26	1 3 48	1 1 1 1 1 1 1 1 1 1 2 3 41	2 5 74	1 24 1 1 1 1 1 550 1.1 3 5 68	2 5 113 1 1 550 1.1 1 20	3 5 127 1 1 1	1 <u>6</u> <u>310</u> <u>9</u> <u>2</u> <u>40</u> <u>1</u> <u>1</u>	3 9 200 10 23 261	2 4 104	5 13 304 31 63 812	0.3 0.8 18
)5)5)6						1 2 3	7 12 19	25 820 2 4 10 15	9 17 19	19 40 42	1 3100 6 15 15		8 19 19	26 57 57	50 101 105	99 181 195	1 22000 22150 46 110 193 205	101 231 244	238 416 450	339 647 694	20.0 38.1 41

ROLDOUT FRAME

Figure 3.3 Traffic Model - NASA Support (Nominal Budget)

FUN	CTION		MIS	SION	
Category	Subcategory	Code	Title	Destination (Alt./Incl.)	Power (kW)
Astrophysics	Automated	NP1-1-1 -2 -3 -4 -5 -6 -7 -8	Space Telescope HEAO-D HEAO-E VLBI (a) E Gravity Wave Detector Gravity Probe B/C Adv. Relativity Exp. Explorer	Low/Low Low/Low Low/Low Scape (5) High/Low Low/Low Low/High Low/High Geosync.	1.5 2.7 2.7 (a) 0.21 (b) 0.38 0.57 0.35 0.35 0.18
	Spacelab	NP1-2-1 -2 -3 -4	P.I. S/L Payloads SIRTF SUOT IR Interferometer	Low/Low Low/Low Low/Low Low/Low	6.2 1.2 0.72 1.8
			Beginn Solar A Power Solar A Power Total I	ing of Life Power (k) Array Weight (lb) Subsystem Weight (ll Array Cost (\$ X 10 ⁶) Subsystem Cost (\$ X Program Cost (\$ X 10 ⁶)	W) <u>6 X 10³)</u> <u>10⁶)</u> <u>10⁶)</u>
Solar Terrestrial	Automated	NP2-1-1 -2 -3 -4 -5	Solar Max. Missions Out-of-eclip. Solar Obs. Explorer (Delta Class) Explorer (Scout Class) Large Solar Observatory	Low/Low Escape Geosync. Geosync. Low/Low	0.94 0.22 0.31 0.22 2.7
	Spacelab	NP2-2-1 -2 -3 -4	Solar Terr. S/L Payloads Solar/Stellar IM Obs. Solar Physics S/L Block II AMPS	Low/Low Low/Int. Low/Int. Low/Int.	3.0 2.9 2.7 3.9
			Beginn Solar / Power Solar / Power Total I	ing of Life Power (k) Array Weight (lb) Subsystem Weight (l Array Cost (\$ X 10 ⁵) Subsystem Cost (\$ X Program Cost (\$ X 1	() (10 ³) (10 ⁶)) (10 ⁵)

FOLDOUT FRAME

 \bigcirc

			NEA	R-TEI	RM							MID	-TERN	١					COST	S (\$M)
	1979	1980	1981	1982	1983	1984	1985	1986	1987	1988	1989	1990	1991	1992	1993	1994	1995	Acq	Ops	Total	Avg
), 38				1	1	1	1	1 1 (a) 1	1 1 1	1	1 (Ь)	1	1 2	l (a)		1	1 (b)				
		1		1 1 1	1 1 1	1 1 1	1 1 1	1 1 1	1 1 1 1	1 1 1											
		20		3 170	2 150	2 150	3 150	4 210	4 300	30	60	4	4	30		5 240	1 60 2				
	4	.1 2 7	2 13	1.2 3 17	1.3 3 11	1.0 3 11	1.1 2 12	1.5	1 4	2	2 8	1.1	1 3	2	6	3	1	10 48 494	15 77 874	25 125 1368	1.5 7.4 80
	27	57	119	168	126	104	140	112	56	56	94	107	1	40	1		1	1/1		1000	
	1	1 1	1	1	1 1 1 1	1	1 1 1	2	2 2	2 2	2	2 2 1	2 2	2 2	2 2	2 2	2 2				
					1	2	1 1 1 2														
		1	1	80	1	1 80	2	1	1	2	1 210	5	2	1 160	2	1	2 210				
	.4 1	.4	.3	.3	.8	.4	.6	.6	1.0	.6	.9 4	2.4	.1	.1	, 1 2	. 7	· 9 1	5	19	24	1.4
	4 41	4 41	3 39	8 76	5 69	5 57	5	5 68	9 78	12	16	88	65	68	65	61	34	209	967	1176	69
																		X			



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FOLDOUT FRAME

2

FU	NCTION		MIS	SION	
Category	Subcategory	Code	Title	Destination (Alt./ incl.)	Power (kW)
Life Sciences	Automated	NP3-1-1 -2	BESS Vestibular Func. Research	Low/Low Low/Low	1.1 1.1
	Spacelab	NP3-2-1 -2 -3 -4	Life Sciences Dedicated Lab Mini-Lab (Multi-Mission) Carry-on Lab (Multi-Missio KOSMOS	Low/Low Low/Low n) Low/Low Low/Low	3.7 1.1 1.1 1.6
	Space Station	NP3-3-1	Research Module	Low/Low	5,2
			Beginning of Solar Array Power Subsy Solar Array Power Subsy Total Progra	Life Power (kW) Weight (lb) stem Weight (lb X 10 Cost (\$ X 10 ⁶) stem Cost (\$ X 10 ⁶) m Cost (\$ X 10 ⁶)	3)
1					
	COLLON .	UT FRAME			

		NE/	AR-TE	RM							MID	-TER/	N					COST	rs (\$№	1)
1979	1980	1981	1982	1983	1984	1985	1986	1987	1988	1989	1990	1991	1992	1993	1994	1995	Acq	Ops	Total	Avg
	1	1 2 2 2	1 2 2 2	1 2 2 2	2 2 2 2	1 2 2 2														
1 2 99	1 4 173	1 60 .3 1 3 138	1 60 .3 3 102	1 60 .3 1 3 104	2 120 .6 2 65	2 60 .3 1 12								1 24	2 4 113	3 5 127	5 14 431	5 13 426	10 27 957	0.6 1.6 56

Figure 3.4 Traffic Model - NASA Scientific (Nominal Budget) cont.

2 EOLDOUT FRAME

FUNC	TION	200	MIS	SION	
Category	Subcategory	Code	Title	Destination (Alt. / Incl.)	Power (kW)
Planetary		NL1-1-1 -2 -3 -4 -5 -6 -7 -8 -9 -10 -11 -12	JUP VOIR Mercury Orbiter/SEPS Saturn-Uranus Probe Dual Comet Flyby Sat. Orb./Tit. Lander Mars Polar Orbiter Follow-on Jupiter (SEPS) Encke Rendezvous (SEPS) Multi-Asteroid (SEPS) Jupiter Swing by Mars Surf. Sample Return	Escape Escape Escape Escape Escape Escape Escape Escape Escape Escape Escape Escape	0.57 1.43 0.74 0.30 1.07 1.27 0.89 0.82 0.78 0.78 0.78 0.52 1.59
			Beginning Solar Arr Power Su Solar Arr Power Su Total Pro	g of Life Power (kW) ray Weight (lb) bsystem Weight (lb 2 ray Cost (\$ X 10 ⁶) bsystem Cost (\$ X 10 ogram Cost (\$ X 10 ⁶)	((10 ³) () ()
Lunar		NL2-1-1	Lunar Orbiter	Escape	0.59
			Solar Ar Power Su Solar Ar Power Su Total Pr	ray Weight (lb) bsystem Weight (lb) ray Cost (\$ X 10 ⁶) bsystem Cost (\$ X 10 ogram Cost (\$ X 10 ⁶)	<u>x 10³)</u>

EOLDOUT FRAME

(

		NE	AR-TE	RM							MID	-TERA	٨					COST	S (\$M	.)
1979	1980	1981	1982	1983	1984	1985	1986	1987	1988	1989	1990	1661	1992	1993	1994	566	Acq	Ops	Total	Avg
					1	1 1 2	1	1	1	1	1	1 1	1	1	1	1				
	1	6	2 45	1 10 144	30 .2 3 16 255	4 230 1.7 8 247	2 90 .6 2 193	1 3 185	1 40 .3 1 4 183	1 8 199	1 40 .3 1 6 171	3 120 1.0 1 4 107	5 69	2 80 • 9 4 88	1 90 .5 4 78	1 120 .7 1 20	6 41 883	3 36 1107	9 77 1990	0.5 4.5 117
3 41	1 30 .2 14																2	1 31	3 55	0.2

Figure 3.5 Traffic Model - NASA Planetary and Lunar (Nominal Budget)

FOLDOUT ERAME

FUNG	CTION		MIS	SION	
Category	Subcategory	Code	Title	Destination (Alt. / Incl.)	Power (kW)
Environmental Monitoring	U.S. Domestic	CO1-1-1 -2	Environ. Monitor. Sat. GOES	Low/High Geosync.	1,2 0,44
	Foreign	CO1-2-1	All Weather Microwave	Low/High	3.6
Forth and Ocean		602-1-1	Beginning Solar Arra Power Sub Solar Arra Power Sub Total Prog	of Life Power (kW) y Weight (lb) system Weight (lb X y Cost (\$ X 10 ⁶) system Cost (\$ X 10 gram Cost (\$ X 10 ⁶) Low/High	10 ³)
Monitoring		002-1-1	Operational SEASA1	Low/High	
			Beginning Solar Arra Power Sub Solar Arra Power Sub Total Prop	of Life Power (kW) y Weight (lb) system Weight (lb X y Cost (\$ X 10 ⁶) system Cost (\$ X 10 gram Cost (\$ X 10 ⁶)	103) 6)
Earth Resources	U.S. Domestic	CO3-1-1	U.S. Government LEO	Low/High	1.6
	Foreign	CO3-2-1 -2 -3	SPOT SPOT Follow-on ETS-III	Low/High Low/High Low/High	1.5 1.6 0.98
			Beginning Solar Arra Power Sub Solar Arra Power Sub Total Prog	of Life Power (kW) ay Weight (lb) system Weight (lb X ay Cost (\$ X 10°) system Cost (\$ X 10 gram Cost (\$ X 10°)	10 ³)
Weather Monitoring	Weather	CO4-1-1 -2 -3	TIROS TIROS Follow-on NOAA Follow-on	Low/High Low/High Low/High	1.2 1.5
	Foreign Meteorology	CO4-2-1 -2 -3	METEOSAT METEOSAT Follow-on GEO Meteorol. Sat (GMS)	Geosync. Geosync. Geosync.	0.46
			Beginning Solar Arr Power Sub Solar Arr Power Sub Total Pro	of Life Power (kW0 ay Weight (lb) system Weight (lb X ay Cost (\$ X 10 ⁶) system Cost (\$ X 10 gram Cost (\$ X 10 ⁶)	(103) (12)

TOLDOUT FRAME

		NE	AR-TE	RM							MID	-TERM	٨					COST	S (\$M	()
1979	1980	1981	1982	1983	1984	1985	1986	1987	1988	1989	1990	1991	1992	1993	1994	1995	Acq	Ops	Total	Avg
	2	1				1				1		1		1						
	1	.3				4				1		4		2						
7 71	3 41	7	1 13	4 60	5 68	2 21	10	3 45	3 51	1 40	4 52	1 28	2 22	8			16 228	20 309	36 537	2.1
											2	1			2	1				
											1 4	8			1.4	9				
								1		0	4.1	.0	2		4.4	.0				
								16	94	137	75	12	34	89	4 61	13	8	26 364	34 531	2.0
				1 1 1	1	1	1	2	2	2	2	3	3	3						
				5	1	2	2	4	3	5	3	5	6	5					_	
				.8	.3	. 3	1	1	1		1	1	2	1						
		4	12	3	2	4	4	6	7	5	6	7	5	1			17	49	66	3.0
		60	134	63	32	48	48	71	99	71	72	85	55	13			229	622	851	50 -
1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1				
1	2	1	1	1		2	3	1	2		2		2							
1	2	-		-	÷			-			-	-			-					
.3	.2			.3	.2	.2	1.0	1.0			-	.3	.3	.3	1.0	.3				
2	4	6	3	3	3	6	2	2	3	3	3	2	2	2			11	35	46	2.7
35	55	76	51)	44	77	78	44	31	37	44	36	3.2	29	21	5		175	526	695	41

Figure 3.6 Traffic Model - Non-NASA/Non-DoD Observation (Nominal Budget)

PULDOUT FRAME

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FUNC	TION		MIS	SION	
Category	Subcategory	Code	Title	Destination (Alt./Incl.)	Power (kW)
International Commun.		CC1-1-1	INTELSAT V	Geosync.	1.44
			Beginning Solar Arra Power Sub Solar Arra Power Sub Total Prog	of Life Power (kW) ay Weight (lb) system Weight (lb X ay Cost (\$ X 10 ⁶) system Cost (\$ X 10 ram Cost (\$ X 10 ⁶)	103) 5)
U.S. Domestic Com- munications		CC2-1-1 -2 -4 -5 -6 -7 -8 -9 -11 -12	TDRS/WESTAK COMSTAR WESTAR RCA SATCOM RCA Follow-on MARISAT Follow-on AM, SAT, Corp (ASC) SAT BUS SYST (SBS) Public Service Image Transmission	Geosync.	0.98 1.04 0.35 0.94 0.96 0.40 0.59 0.49 1.19 1.91
			Beginning Solar Arra Power Sub Solar Arra Power Sub Total Prog	of Life Power (kW) ay Weight (lb) system Weight (lb X by Cost (\$ X 10 ⁵) system Cost (\$ X 10 ⁵) gram Cost (\$ X 10 ⁵)	10 ³)
Foreign Communi- cation		CC3-1-1 -2 -3 -4 -5 -6 -10 -11 -12 -13 -14 -15 -16 -17 -18 -19 -20	Arab Comsat (ARCOMSAT) ARCOMSA'T Follow-on Orbital Test Sat (OTS) Eurocomsat (ECS) ECS Follow-on MAROTS SYMPHONIE-3 AMSAT APPLE Indian Sat (INSAT) INSAT Follow-on PALAPA PALAPA PALAPA Follow-on IRAN IRAN Follow-on SIRIO SIRIO Follow-on	Geosync.	0.42 0.49 0.41 0.42 0.40 0.48 0.08 0.36 0.42 0.47 0.48 1.20 0.40 0.56 0.38



			NE/	AR-TE	RM							MID	-TERN	١					COST	S (\$M	.)
	1979	1980	1981	1982	1983	1984	1985	1986	1987	1988	1989	1990	1991	1992	1993	1994	1995	Acq	Ops	Total	Avg
	1	3																			
	1	5																			
	.6	1.7																			
	0	2																0	10	10	0.6
5	115	77																0	192	192	11.3
	1	2	2	1			1			2			1				2				
	1			1	1 2				2	1	1	2				2	1				
								2	1 1 1	î		1	2			1					
	2	2	2	2	3		1	1	3	2	1	4	5			2	4				
_	8	7	7	7	9		4	6	1.6	13	3	1 4	1.8			1.4	1.1				
		• •							1.0			1.1									
	8	5 80	7	56	2	4 56	15	181	128	6 115	9	106	34	34	94	9 124	98	49	74	123	7.2
	1	1	1	1 1 1		1	1			-1	1		1	1	1		1				
			2	1			1			2	1				1		2				c

Figure 3.7 Traffic Model - Non-NASA/Non-DoD Communications (Nominal Budget)

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BOLDOUT FRAME

FUNCT	ION		MIS	SION	
Category	Subcategory	Code	Title	Destination (Alt. / Incl.)	Power (kW)
Foreign Communi- cation (cont'd)		CC3-1-21 -22 -23 -24 -25 -26 -27 -28 -29 -30 -31 -32 -33 -34 -35 -36 -37 -38 -39 -40	NORDSAT NORDSAT Follow-on BRAZILSAT BRAZILSAT Follow-on NATO III NATO Follow-on Eng. Test Sat (ETS-II) ETS IV Comm. Sat. (CS) CS Follow-on Brdest Sat. Exp. (BSE) BSE Follow-on Exp. Comm. Sat. (ECS) TELESAT-B TELESAT-D TELESAT-C TELESAT-D TELESAT Follow-on UHF Canadian Direct Brdest Other Regional Beginning Solar Arr Power Sul Solar Arr Dower Sul Total Pro	Geosync. " " " " " " " " " " " " " " " " " " "	0.40 0.42 0.59 0.62 0.64 0.57 1.19 0.42 0.64 0.28 0.68 0.42 1.41 0.59 -

EOLDOUT FRAME

		NE/	AR-TE	RM							MID	-TERA	٨					COST	S (\$M	.)
1979	1980	1981	1982	1983	1984	1985	1986	1987	1988	1989	1990	1991	1992	1993	1994	1995	Acq	Ops	Total	Avg
	1	1	1	1	1	1			1	1	1	1	1	1						
	1	1	1	1	1	1	1	1 1 1 1 1	1	1		1	1.	1	1	1 1 1				
	1	1	5	4	3	4	1	2	3	4	2	3	5	4	3	3				
	1		2	2		3		3	3	2	2			2	1					
28	33	33	36	27	18	8	13	26	17	11	15	17	11	9	13	14	130	299	329	19.4
260	312	295	308	284	187	121	156	219	159	99	130	173	135	109	149	119	1225	1990	3215	189

Figure 3.7 Traffic Model - Non-NASA/Non-DoD Communications (Nominal Budget) cont.

2 FOLDOUT FRAME

FUNC	TION		MIS	SION	
Category	Subcategory	Code	Title	Destination (Alt. / Incl.)	Power (kW)
U.S. Domestic		CP1-1-1	Multipurpose Payload	Low/Low	4.2
			Beginning o Solar Array Power Subs Solar Array Power Subs Total Progr	f Life Power (kW) Weight (lb) ystem Weight (lb X 10 Cost (\$ X 10 ^c) ystem Cost (\$ X 10 ^c) am Cost (\$ X 10 ^c)	3)
Foreign		CP2-1-1 -2 -3 -4 -5 -6 -7 -8 -9 -10 -11 -12 -13 -14 -15	GEOS GEOS 2 EXOSAT UK-6 IRAS French Scientific European Scientific Canadian Scientific MST-3 ISS Replacement TAIYO Replacement EXOS A EXOS B ASTRO A ASTRO B	Geosync. Geosync. Ellip/High Low/Int. Low/High Various Various Various Ellip/High Low/Int. Ellip/Low Ellip/Int. Ellip/Low Low/Low Low/Low	0.18 0.30 0.04 0.56 0.55 0.04 0.03 0.03 0.02 0.03 0.02 0.04 0.04 0.04
			Beginning o Solar Array Power Subs Solar Array Power Subs Total Prog	f Life Power (kW) 7 Weight (lb) ystern Weight (lb X 10 7 Cost (\$ X 10 ⁵) ystem Cost (\$ X 10 ⁵) ram Cost (\$ X 10 ⁵)	<u>j3)</u>



			NE/	AR-TE	RM					5		MID	-TERA	٨					COST	S (\$N	£)
•	1979	1980	1981	1982	1983	1984	1985	1986	1987	1988	1989	1990	1991	1992	1993	1994	1995	Acq	Ops	Total	Avg
							1	1	1	1	1	1	1	1	1						
							4	4	4	5	4	4	4	4	4						
							1		1	1		1	1	1	-						
					3	7	6	4	3	4	4	4	4	2	1			8	34	42	2.5
		1	1 1 1 1 1	1	19	1	1	1	1	20	1	20	1	15	1	1	1 1	51	183	234	14
							_	1	2		1						_				
	10	14	g	3	7	4	3	3	2	2	5	4	1	3	2	3		20	45	74	4.4
	116	148	70	44	57	36	24	36	29	44	41	32	26	43	37	29	6	215	603	818	48

Figure 3.8 Traffic Model - Non-NASA/Non-DoD Scientific (Nominal Budget)

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FRAME

FUN	CTION		MIS	SION	
Category	Subcategory	Code	Title	Destination (Alt./Incl.)	Power (kW)
Earth Resource Monitoring	Automated Spacelab	NO1-1-1 -2 -3 -4 -5 -6 -7 -8 NO1-2-1	Landsat Follow-on Earth Survey Satellite Sync. Earth Obs. Sat (SEOS) GRANSAT MAGSAT B SMIAS HCMM Follow-on STEREOSAT Spacelab Payloads	Low/Low Low/High Geosync. Low/High High/Low Low/Int.	1.3 1.2 1.2 0.35 0.18 1.1 1.1 0.54 7.5
			Beginning Solar Arra Power Sub Solar Arra Power Sub Total Prop	of Life Power (kW) ay Weight (lb) system Weight (lb X ay Cost (\$ 10 ⁶) system Cost (\$ X 10 ⁶) gram Cost (\$ X 10 ⁶)	103) 2)
Environmental	Automated	NO2-1-1. -2 -3 -4 -5	SEASAT-B Environ. Monitoring Sat. HALOE STORMSAT ERBSS	Low/High Low/High Geosync.	3.5 1.8 1.3 1.4 0.47
	Spacelab	NO2-2-1 -2	ACPL Spacelab Payloads	Low/Low Low/High	1.9 3.0
			Beginning	of Life Power (kW)	J
			Solar Arra	ay Weight (lb)	103)
			Solar Arra	av Cost (\$ X 100)	105)
			Power Sub	system: Cost (\$ X 10t	2)
			Total Pro	gram Cost (\$ X 10 ⁶)	

EOLDOUT FRAME

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6		NE/	AR-TE	RM							MID	-TERA	٨					COST	S (\$M	.)
1979	1980	1981	1982	1983	1984	1985	1986	1987	1988	1989	1990	1661	1992	1993	1994	1995	Acq	Ops	Total	Avg
		1	1		1	1	1	1 1	1 1	1	1	1	1	1	1	1 1				
1 3 82	2 9 176	$ \begin{array}{r} 1 \\ 100 \\ .3 \\ 1 \\ 6 \\ 163 \end{array} $	1 200 .8 63	1 3 76	1 2 2 7 136	1 100 .2 4 8 157	1 200 .6 2 8 136	1 3 100 .9 2 9 123	1 .3 .3 .94	1 2 100 .6 1 5 86	1 <u>2</u> 100 • 4 <u>3</u> 77	1 3 200 .6 2 73	1 100 .4 2 4 72	1 200 .5 3 3 73	1 100 .2 4 93	1 4 .9 3 52	8 30 566	12 50 1166	20 80 1732	1.2 4.7 102
	1	1	1 1	1 1 1 1 1 1	1	1	1	1	1	1 1	1 1 1 1	1 1	1	1	1	1				
2 7 116	1 70 .2 2 6 107	3 190 .6 1 4 74	1 4 72	2 140 .5 2 4 35	 	.4 1 5 69	2 100 .5 2 2 61	1 80 2 26	1 24	3 45	3 180 .7 2 23	17	2 2 35	1 80 .5 2 36	2 100 .4 1 23	2 26	7 23 344	6 25 472	13 28 216	0,8 1,6 48

Figure 3.9 Traffic Model - NASA Observation (Optimistic Budget)

FORDOUT FRAME

FUNC	TION		MIS	SSION	
Category	Subcategory	Code	Title	Destination (Alt./Incl.)	Power (kW)
intergovernment Links		NC1-1-1 -2 -3 -4	Hotline Intergovernment - I Intergovernment - II Intergovernment - III	Geosync. Geosync. Geosync. Geosync.	2.0 2.0 3.5 5.0
			Beginnin Solar Ar Power Su Solar Ar Power Su Total Pr	g of Life Power (kW) ray Weight (lb) ubsystem Weight (lb X ray Cost.(\$ X 10 ⁶) ubsystem Cost (\$ X 10 ogram Cost (\$ X 10 ⁶)	103) 6)
Gov't to People Links		NC2-1-1 -2	Voting/Polling - I Voting/Polling - II	Geosync. Geosync.	1.0 50
			Beginnin Solar Ar Power Si Solar Ar Power S Total Pr	g of Life Power (kW) ray Weight (lb) ubsystem Weight (lb X ray Cost (\$ X 10 ⁵) ubsystem Cost (\$ X 10 ogram Cost (\$ X 10 ⁵)	6)
People to People Lin.' 3		NC3-1-1 -2 -3	Personal Comm. Teleconferencing - I Teleconferencing - II	Geosync. Geosync. Geosync.	10 25 100
			Beginnin Solar Ar Power S Solar Ar Power S Total Pr	g of Life Power (kW) ray Weight (lb) ubsystem Weight (lb X ray Cost (\$ X 10 ⁶) ubsystem Cost (\$ X 10 ogram Cost (\$ X 10 ⁶)	6)
FOLDOUT	ERAME		1		

			NE/	AR-TE	RM							MID	-TERM	٨					COST	S (\$M	.)
Standard Standard	1979	1980	1981	1982	1983	1984	1985	1986	1987	1988	1989	1990	1991	1992	1993	1994	1995	Acq	Ops	Total	Avg
			1		1	1		1	1	1	1		1	1	1	1					
	3 84	3 7 222	2 110 .5 2 7 218	3 7 208	2 110 .5 1 5 130	3 190 .7 1 6 152	2 6 192	2 110 .6 3 6 186	5 280 • 8 2 4 146	2 110 .6 3 98	4 190 .7 1 2 54	3 95	2 110 .5 2 5 137	5 280 .8 1 4 126	2 110 .5 2 3 91	3 190 .7 1 24		9 29 841	14 43 1372	23 72 2213	1.4 4.2 130
						1		1 <u>1</u> <u>60</u> .5		1	1	1 1 60 .5 3	6	5	1 50 1380 2.2 3	1 1 60 .5		12	8	20	1.2
				1	1	2	3 54	1	6	12	4 60	6	10 201 1 1	10 210	5 95 1	7	1	24 474	18 383	42 857	2.5
	1 4 112	3 6 174	3 5 169	10 500 1,1 3 62		6	2 2 92	4 9 235	10 600 1.1 6 10 288	9 16 359	25 800 1.6 11 17 367	11 16 360	110 2900 4.1 5 9 189	3 5 132	25 800 1.6 2 3 102	5 9 181	10 600 1.1 7 10 197	28 51 1213	42 73 1812	72 124 3025	4.2 7.3 178

Figure 3.10 Traffic Model - NASA Communications (Optimistic Budget)

3-25

ADDOOT FRAME

Code NC4-1-1 -2 NC4-2-1 -2 NC5-1-1 -2	Title Electronic Mail - I Electronic Mail - II Emergency - I Emergency - II Beginning of Solar Arra Power Subi Solar Arra Power Subi Total Prog TV Broadcast - I TV Broadcast - II W Broadcast - II TV Broadcast - II	Destination (Alt./Incl.) Geosync. Geosync. Geosync. Geosync. Dif Life Power (kW) y Weight (lb) system Weight (lb X 10) system Cost (\$ X 10 ⁶) ram Cost (\$ X 10 ⁶) Geosync. Geosync. Geosync.	Power (kW) 5.0 15 2.0 5.0 5.0 03)
NC4-1-1 -2 NC4-2-1 -2 NC5-1-1 -2	Electronic Mail - I Electronic Mail - II Emergency - I Emergency - II Beginning (Solar Arra Power Sub: Solar Arra Power Sub: Total Prog TV Broadcast - I TV Broadcast - II W Broadcast - II Beginning (Solar Arra Power Sub:	Geosync. Geosync. Geosync. Geosync. Of Life Power (kW) y Weight (lb) system Weight (lb X 10) system Cost (\$ X 10 ⁶) ram Cost (\$ X 10 ⁶) Geosync. Geosync. Geosync.	5.0 15 2.0 5.0 03)
NC4-2-1 -2 NC5-1-1 -2	Emergency - I Emergency - II Beginning (Solar Arra Power Subi Total Prog TV Broadcast - I TV Broadcast - I TV Broadcast - II Beginning (Solar Arra Power Subi	Geosync. Geosync. Df Life Power (kW) y Weight (lb) system Weight (lb X 10 y Cost (\$ X 10 ⁶) system Cost (\$ X 10 ⁶) ram Cost (\$ X 10 ⁶) Geosync. Geosync. Geosync.	2.0 5.0
NC5-1-1 -2	Beginning of Solar Arra Power Sub- Solar Arra Power Sub- Total Prog TV Broadcast - I TV Broadcast - II Beginning of Solar Arra Power Sub-	of Life Power (kW) y Weight (lb) system Weight (lb X 10 y Cost (\$ X 10 ⁶) system Cost (\$ X 10 ⁶) ram Cost (\$ X 10 ⁶) Geosync. Geosync. Geosync. of Life Power (kW) y Weight (lb)	10 10 40
NC5-1-1 -2	TV Broadcast - I TV Broadcast - II Beginning of Solar Arra Power Sub:	Geosync. Geosync. of Life Power (kW) v Weight (lb)	10 40
	Beginning o Solar Arra Power Sub	of Life Power (kW) v Weight (lb)	
	Power Suba Total Prog	system Weight (lb X 10 y Cost (\$ X 10 ⁵) system Cost (\$ X 10 ⁶) ram Cost (\$ X 10 ⁶))3)
1	1		

0

CANAL STREET, S

			NE/	AR-TE	RM							MID	TERN	1					CCST	S (\$M	L)
	1979	1980	1981	1982	1983	1984	1985	1986	1987	1988	1989	1990	1661	1992	1993	1994	1995	Acq	Ops	Total	Avg
		1		1		1		1	1	-1	1	1			1	1	1				
	3 8 230	2 110 .5 1 7 216	3 8 220	5 280 .8 2 6 219	5 10 239	5 280 .8 3 7 221	3 8 195	15 690 1.3 2 6 155	2 110 .6 1 4 145	5 280 .8 3 6 160	5 280 .8 2 5 137	15 690 1.3 1 3 82	1 4 113	5 280 .8 2 5 134	2 110 .5 4 6 161	15 690 1.3 5 119	5 280 .8 1 1 29	13 37 1017	24 62 1759	37 99 2776	2.2 5.8 163
Non-the Non-The State					1				1		1	1	1	1			1 1 50				
	1	1 4 94	3 6	3 5 139	10 500 1.1 2 50	6	2 4 80	5 9 207	10 600 1.1 5 10 225	5 11 232	40 1100 2.0 6 10 212	500 1.1 5 9 187	1100 2.0 2 5 125	600 1.1 1 2 42	3 4 95	5 10 201	1600 3.1 1 3 70	14 30 678	34 65 146	48 95 0 213	2.8 5.6 8 126

Figure 3.10 Traffic Model - NASA Communications (Optimistic Budget) cont.

2

E BOLDOUT FRAME

FUNC	TION		MIS	SION	
Category	Subcategory	Code	Title	Destination (Alt. / Incl.)	Power (kW)
Space Processing	Spacelab	NS1-1-1 -2	Space Processing Spacelab R&D Facility	Low/Low Low/Low	5.0 10
	Space Station	NS1-2-1	Extended Mission Vehicle	Low/Low	5.5
Space Industrialization		NS2-1-1 -2	Early Space Constr. Base ESCB Resupply	of Life Power (kW) ay Weight (lb) bsystem Weight (lb X ay Cost (\$ X 10 ⁵) bsystem Cost (\$ X 10 gram Cost (\$ X 10 ⁵) Low/Low Low/Low	25. 1.0
		- 3 - 4 - 5	Adv. Space Constr. Base ASCTS Resupply Space Manufac, Facility Beginning Solar Arr Power Su Splar Arr	Low/Low Low/Low Low/Low cof Life Power (kW) ray Weight (lb) bsystem Weight (lb 2 ray Cost (\$ X 10 ⁰)	60 1.0 100
			Power Su Total Pro	bsystem.Cost (\$ X 10 ogram Cost (\$ X 10 ⁶))6)
Orbital Operations		NS3-1-1 -2 -3 -4 -5 -6	Large Struc. Deployment Skylab Revisit Tethered Sat. Op. Satellite Retrieval Shuttle External Tank Usage Launch Retrieval & Refueling of Upper Stages	Low/Low Low/Low Low/Low Low/Low Low/Low Low/Low Low/Low	10 1.0 0.5 1.0 1.0 1.0
			Beginning Solar Arr Power Su Solar Arr Power Su Total Pro	g of Life Power (kW) ray Weight (lb) bsystem Weight (lb) ray Cost (\$ X 106) bsystem Cost (\$ X 10 gram Cost (\$ X 106)	<u>x 10³)</u>

FOLDOUT FRAME

0

		NEA	R-TE	RM							MID	-TERN	1					COST	S (\$№	1)
1979	1980	1981	1982	1983	1984	1985	1986	1987	1988	1989	1990	1661	1992	1993	1994	1995	Acq	Ops	Total	Avg
													1							
										1 24	5 113	2 5 127	310 .9 3 2 40				3 9 200	2 4 104	5 13 304	0.3 0.8 18
						1	1	1	1 1	1 1 1	1	1 1	1	1 1	1	1				
		1 1 200	2 5 600	3 7 1102	5 8 1225	25 800 1.6 2 5 625	4 6 510	6 11 994	6 11 1122	60 1600 2.4 3 4 435	54	54	54	54	53	33	19 36 3650	13 22 3465	32 58 7115	1.9 3.4 418
	1	1	1 1 1	1	1	1	1	1	1		1		1	1	1 1					
<u>10</u> 19 179	25 820 1,6 5 10 123	10 550 1,1 1 4 63	2 4 50	10 550 1,1 1 2 43	2 4 49	10 550 1.1 1 17	5	4	1 2 26	1 3 48	10 550 1,1 2 3 41	2 5 74	10 550 1,1 3 5 68	10 550 1,1 1 20	1	1	10 24 261	21 39 551	31 63 812	1.8 3.7 48
											c.	0								

Figure 3.11 Traffic Model - NASA Support (Optimistic Budget)

ROLDOUT FRAME

FUN	CTION		MIS	SION	
Category	Subcategory	Code	Title	Destination (Alt./Incl.)	Power (kW)
Satellite Power		NS4-1-1 -2 -3 -4 -5 -6	25 kW Power Module 250 kW Power Module 2 MW Power Module 15 MW Power Module 1.2 GW Power Module 10 GW Power Station	Low/Low Low/Low Geosync. Geosync. Geosync. Geosync.	25 250 2x103 15x103 12x105 10x106
			Beginning Solar Arr Power Sul Solar Arr Power Sul Total Pro	of Life Power (kW) ay Weight (lb X 10 ⁴) bystem Weight (lb X ay Cost (\$ X 10 ⁶) bystem Cost (\$ X 10 ⁶) gram Cost (\$ X 10 ⁶)	10 ³)
					•

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		NE/	AR-TE	RM							MID	-TERA	٨	2				COST	S (\$M	I)
1979	1980	1981	1982	1983	1984	1985	1986	1987	1988	1989	1990	1991	1992	1993	1994	1995	Acq	Ops	Total	Avg
			1			1			1				2	2	1	2				
			25			250			2000				30000	30000	15000	30000				
	-		8	-		31	-	-	222				2140	2140	1070	2140				
	1	7	4	9	27	32	50	59	50	82	2.54	553	571	456	646	646	365	3082	3447	203
	2	12	10	17	59	72	101	111	92	155	436	914	934	744	1052	1051	726	5036	5762	338
									7 -											

Figure 3.11 Traffic Model - NASA Support (Optimistic Budget) cont.

2 ROLDOUT FRAME

FUN	NCTION		MIS	SION	
Category	Subcategory	Code	Title	Destination (Alt./Incl.)	Power (kW)
Astrophysics	Automated	NP1-1-1 -2 -3 -4 -5 -6 -7 -8	Space Telescope HEAO-D HEAO-E VLBI (a) Gravity Wave Detector Gravity Probe B/C Adv. Relativity Exp. Explorer	Low/Low Low/Low Low/Low Low/Low Low/Low Low/High Low/High Geosync.	1.5 2.7 2.7 (a) 0.21 (b) 0.3 0.35 0.35 0.35 0.18
	Spacelab	NP1-2-1 -2 -3 -4	P.I. S/L Payloads SIRTF SUOT IR Interferometer	Low/Low Low/Low Low/Low Low/Low	6.2 1.2 0.72 1.8
			Beginni Solar A Power S Solar A Power S Total P	ng of Life Power (kW rray Weight (lb) Subsystem Weight (lb rray Cost (\$ X 10 ⁶) Subsystem Cost (\$ X rogram Cost (\$ X 10) X 10 ³) 10 ⁶)
Solar Terrestrial	Automated	NP2-1-1 -2 -3 -4 -5	Solar Max. Missions Out-of-eclip. Solar Obs. Explorer (Delta Class) Explorer (Scout Class) Large Solar Observatory	Low/Low Escape Geosync. Geosync. Low/Low	0.94 0.22 0.31 0.22 2.7
	Spacelab	NP2-2-1 -2 -3 -4	Solar Terr. S/L Payloads Solar/Stellar IM Obs. Solar Physics S/L Block II AMPS	Low/Low Low/Int. Low/Int. Low/Int.	3.0 2.9 2.7 3.9
			Beginn Solar A Power Solar A Power Total I	ing of Life Power (kV pray Weight (lb) Subsystem Weight (lb pray Cost (\$ X 106) Subsystem Cost (\$ X Program Cost (\$ X 106) Subsystem Cost (\$ X 106	x 10 ³) 106) 9)
1					

EOLDOUT FRAME

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			NE/	AR-TF.	RM							MID	-TERA	٨					COST	S (\$N	í)
	1979	1980	1981	1982	1983	1984	1985	1986	1987	1988	1989	1990	1991	1992	1993	1994	1995	Acq	Ops	Total	Avg
.38				1	1	1	1	1 1(a) 1	1 1 1	1	1 (b)	1	1 2	l (a)		1	1 (b)				
		1		1 1 1 1	1 1 1	1 1 1	1 1 1	1 .1 1	1 1 1 1	1 1 1											
		20		3 170	2 150	2 150	3 150	4 210	4	30	60	4 180	4 270	30		5 240	1 60				
		.1 2	2	1.2	1.3	1.0	1.1	1.5	2.3	.2	.3	1.1	1.5	.2		2.1	.2	10	15	25	1.5
	4 27	7 57	13	17	126	11	12	10	4 56	5	8 94	8	52	40	65	35	1 10	48	77 874	125 1368	7.4
	1	1	1	1	1 1 1 1	1	1 1 1	2 2	1 2 2	2 2	1 2 2	2 2 1	1 2 2	2 2	1 2 2	2 2	1 2 2				
					1	2	1 1 1 2														
	80	$-\frac{1}{80}$	1 80	80	1 160	1 80	2	1 160	1 210	2 160	210	5 310	2 210	1 160 8	210	1 160 7	210				
	.4 1 4	1	.3	2	2 5	1	1	2	9	3	4	7	2	1	2	1 7	1 2	5	19 82	24	1.4
	41	31	49	76	69	57	62	68	78	131	133	88	65	68	65	61	34	209	967	1176	69

Figure 3.12 Traffic Model - NASA Scientific (Optimistic Budget)

COLDOUT FRAME

FUNCT	ION		MIS	SION	
Category	Subcategory	Code	Title	Destination (Alt. / Incl.)	Power (kW)
Life Sciences	Automated	NP3-1-1 -2	BESS Vestibular Func, Research	Low/Low Low/Low	1.1 1.1
	Spacelab	NP3-2-1 -2 -3 -4	Life Sciences Dedicated Lat Mini-Lab (Multi-Mission) Carry-on Lab ('' '') KOSMOS	Low/Low Low/Low Low/Low Low/Low	3.7 1.1 1.1 1.6
	Space Station	NP3-3-1	Research Module	Low/Low	5.2
	OUT ERAME		Beginning Solar Arra Power Sub Total Prop	of Life Power (kW) ty Weight (lb) system Weight (lb X ty Cost (\$ X 10 ⁶) system Cost (\$ X 10 ⁶) gram Cost (\$ X 10 ⁵)	<u>103)</u>

		NE/	AR-TE	RM							MID	-TERN	٨					COST	S (\$№	L)
1979	1980	1981	1982	1983	1984	1985	1986	1987	1988	1989	1990	1991	1992	1993	1994	1995	Acq	Ops	Total	Avg
		1	1	1	2	1														
	1	2 2 2	2 2 2	2 2 2	2 2 2	2 2 2	1													
		1 60	1 60	1 60	2 120	2 60	5 300													
 1 2 99	1 4 173	.3 1 3 138	. 3 3 102	.3 1 4 128	2 (178	. 3 4 5 139	2 40										5 15 449	5 14 548	10 29 997	.6 1.7 59

Figure 3.12 Traffic Model - NASA Scientific (Optimistic Budget) Cont.



FUNC	TION		MIS	SION	
Category	Subcategory	Code	Title	Destination (Alt. / Incl.)	Power (kW)
Planetary	Subcategory	COGe NL1-1-1 -2 -3 -4 -5 -6 -7 -8 -9 -10 -11 -12 NL2-1-1	JUP VOIR Mercury Orbiter/SEPS Saturn-Uranus Probe Dual Comet Flyby Sat. Orb/Tit. Lander Mars Polar Orbiter Follow-on Jupiter (SEPS) Encke Rendezvous (SEPS) Multi-Asteroid (SEPS) Jupiter Swing by Mars Surf. Sample Return Beginning o Solar Array Power Subs Solar Array Power Subs Total Progr Lunar Orbiter Beginning o Solar Array Power Subs Solar Array Power Subs Solar Array Power Subs Solar Array Power Subs Solar Array Power Subs Solar Array Power Subs Solar Array	(All./IIICL.) Escape (1 Life Power (kW) Weight (lb) ystem Cost (\$ X 10 ⁶) Escape f Life Power (kW) Weight (lb) ystem Weight (lb X 1 Cost (\$ X 10 ⁶) ystem Weight (lb X 1 Cost (\$ X 10 ⁶) ystem Cost (\$ X 10 ⁶) ystem Cost (\$ X 10 ⁶) ystem Cost (\$ X 10 ⁶) State Cost (\$ X 10 ⁶) Escape	(KW) 0.57 1.43 0.74 0.30 1.07 1.27 0.89 0.82 0.78 0.78 0.52 1.59 0.59 0.59 0.59



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		NE/	AR-TE	RM							MID	-TERA	٨					COST	S (\$M)
1979	1980	1981	1982	1983	1984	1985	1986	1987	1988	1989	1990	1991	1992	1993	1994	1995	Acq	Ops	Total	Avg
					1	1 1 2	1	1	1	1	1	1	1	1	1 1	1 1				
	1	6	245	1 10 144	30 ,2 3 16 255	4 230 1.7 8 247	2 90 .6 2 193	1 3 185	1 40 .3 1 4 183	1 8 199	1 40 , 3 1 6 171	3 120 1.0 1 4 107	5 69	2 80 • 9 4 88	1 90 .5 4 78	1 120 .7 1 20	6 41 883	3 36 1107	9 77 1990	0.5 4.5 117
3	.2																24	1 31	3 55	0.2

Figure 3.13 Traffic Model - NASA Planetary and Lunar (Optimistic Budget)

COLDOUT FRAME

FUNC	TION		MIS	SION	
Category	Subcategory	Code	Title	Destination (Alt./Incl.)	Power (kW)
Environmental Monitoring	U.S. Domestic	CO1-1-1	Environmental Monitoring Satellite (EMS) GOES	Low/High	1.2
		-3	GOES Follow-on	Geosync	0.58
	Foreign	CO1-2-1	All Weather Microwave	Low/High	3.6
			Beginning Solar Arr Power Su Solar Arr Power Su Total Pro	of Life Power (kW) ay Weight (lb) bsystem Weight (lb X ay Cost (\$ X 10 ⁶) bsystem Cost (\$ X 10 gram Cost (\$ X 10 ⁶)	103) 6)
Earth and Ocean Monitoring		CO2-1-1	Operational SEASAT	Low/High	4.1
			Beginning	of Life Power (kW)	
			Solar Arr	ay Weight (lb)	1031
· · · · ·	a a an an an a	12 V	Fower Su	osystem weight (ID A	105)
		1.	Power Su	hsystem Cost (\$ X 10)	6)
			Total Pro	gram Cost (\$ X 10 ⁶)	1
Earth Resources	U.S. Domestic	CO3-1-1 -2 -3 -4	US Government LEO Private Industry LEO US Government GEO Private Industry GEO	Low/High Low/High Geosync Geosync	1.6 1.6 0.99 0.99
	Foreign	CO3-2-1 -2 -3 -4 -5 -6	SPOT SPOT Follow-on ETS-III Earth Observation ESA - GEO Other - GEC	Low/High Low/High Low/High Low/High Geosync Geosync	1.5 1.6 0.98 0.98 0.93 0.93
			Beginning Solar Arr Power Sul Solar Arr Power Sul Total Pro	of Life Power (kW) ay Weight (lb) osystem Weight (lb X ay Cost (\$ X 10 ⁶) osystem Cost (\$ X 10 ⁶) gram Cost (\$ X 10 ⁶)	<u>103)</u>
		1 m			

E DOLDOUT FRAME

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FOLDOUT

			NE/	AR-TE	RM							MID	-TERA	٨					COST	S (\$M	.)
	1979	1980	1981	1982	1983	1984	1985	1986	1987	1988	1989	1990	1991	1992	1993	1994	1995	Acq	Ops	Total	Avg
											1		1		1						
		2	1			1	1	1		1	1	1		1	1	1					
							1						1								
		1					4	1			2		4	1	3						
		. 6	.3			.4	1.0	3		.4	.7	.4	.9	.4	.6						
	7	3 41	8	3 39	10	9 112	4 44	1 25	5 69	6 81	3 62	5 67	4 52	4 43	14			23 298	41 552	64 850	3.8
												2	1	1	2	4	4				
					_							8	4	4	9	16	16				
												1.4	. 8	.7	1.4	2.9	2.9				
0									1	6	9	5	6	14	19	18	13	17	74	91	5.4
									16	94	137	92	100	211	284	276	192	265	1157	1402	82
					1	1	1	1	2	2 1	2	2 1 1	3	3 1 1	3						
					1			1			1			1							
Della second					-		1		1		1		1 1	1	1 1						
					5	1	5	2	6	4	6	6	9	9	8			-			
				-	. 8	. 3	1.0	. 6	. 8	1.0	1.2	1.4	2.0	2.3	1.9						
			4	12	7	9	6	7	7	12	14	17	16	13	3			42	85	127	7.5
-			60	134	112	135	92	72	106	167	220	264	235	170	45			592	1220	1812	107

TI FRAME

Figure 3.14 Traffic Model - Non-NASA/Non-DoD Observation (Optimistic Budget)
Category Subcategory Code Title Destination (Alt./Incl.) Weather Monitoring Weather C-2 -3 TIROS TIROS Follow-on -3 Low/High Low/High Low/High Code Tollow-on Code Tollow-O	FUNC	TION		MIS	SION	
Weather Monitoring Weather C04-1-1 -2 Foreign Meteorology C04-2-1 -2 -3 Foreign Meteorology C04-2-1 -2 -3 -4 Other C054T Follow-on C6 cosync. C6 cosync. C6 cosync. C6 cosync. C6 cosync. C6 cosync. C6 cosync. C7 C6 cosync. C7 C7 C6 cosync. C7 C7 C7 C7 C7 C7 C7 C7 C7 C7	Category	Subcategory	Code	Title	Destination (Alt./Incl.)	
Foreign Meteorology CO4-2-1 -2 -3 -4 METEOSAT Pollow-on GEO Meteorol. Sat (GMS) GMS Follow-on Other Geosync. Geosync. Geosync. Geosync. Geosync. Geosync. Geosync. Geosync. Geosync. Geosync. Solar Array Weight (Ib) Solar Array Weight (Ib) Solar Array Gest (§ X 109) Power Subsystem Cost (§ X 109) Power Subsystem Cost (§ X 109)	Weather Monitoring	Weather	CO4-1-1 -2 -3	TIROS TIROS Follow-on NOAA Follow-on	Low/High Low/High Low/High	
Beginning of Life Power (kW) Solar Array Weight (lb) Power Subsystem Veight (lb) Total Program Cost (\$ X 100) Total Program Cost (\$ X 100)		Foreign Meteorology	CO4-2-1 -2 -3 -4 -5	METEOSAT METEOSAT Follow-on GEO Meteorol. Sat(GMS) GMS Follow-on Other	Geosync. Geosync. Geosync. Geosync. Geosync.	
				Beginning Solar Arr Power Sul Solar Arr Power Sul Total Pro	of Life Power (kW) ay Weight (lb) bsystem Weight (lb X ay Cost (\$ X 10 ⁶) bsystem Cost (\$ X 10 ⁶) gram Cost (\$ X 10 ⁶)	10

C

			NE	AR-TE	RM							MID	-TER	N					COST	S (\$1	(1)
1970		1980	1981	1982	1983	1984	1985	1986	1987	1988	686T	1990	1991	1992	1993	1994	1995	Acq	Ops	Total	Avg
1		1	1	1	1	1	1	1	1	1	1	1	1	1	1					land.	
			1	1		1		1	1			1 1 1 1			1	1					
1		2	2	2	1	2	2	4	1	2	1	3	1	2	3	_1					
.3		. 2	, 5	.8	.3	.5	.2	.9	.5	.2	3	1,1	.3	.3	.8	.3					
3	1	9 142	10 160	3 83	4 71	4 104	7 111	4 73	3 50	3 61	5	5 61	2.	4	3 34	5		17 306	52 937	69 1243	4.1 73

Figure 3.14 Traffic Model - Non-NASA/Non-DoD Observation (Optimistic Budget) cont.

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FUNC	TION		MIS	SION	
Category	Subcategory	Code	Title	Destination (Alt. / Incl.)	Power (kW)
International Communication		CC1-1-1 -2 -3	INTELSAT V INTELSAT V INTELSAT VI	Geosync. Geosync. Geosync.	1.44 1.44 1.91
			Beginning Solar Arr: Power Sub Solar Arra Power Sub Total Pro	of Life Power (kW) ay Weight (lb) system Weight (lb X ay Cost (\$ X 10 ⁶) system Cost (\$ X 10 ⁶) gram Cost (\$ X 10 ⁶)	103)
U.S. Domestic Com- munications	2	CC2-1-1 -2 -3 -4 -5 -6 -7 -8 -9 -10 -11 -12 -13 -14	TDRS/WESTAK COMSTAR COMSTAR Follow-on WESTAR RCA SATCOM RCA Follow-on MARISAT Follow-on AM. SAT. Corp. (ASC) SAT BUS SYST (SBS) SBS Follow-on Public Service Image Transmission Hi Cap. Video Brdcst Other U.S.	Geosync. Geosync. Geosync. Geosync. Geosync. Geosync. Geosync. Geosync. Geosync. Geosync. Geosync. Geosync. Geosync. Geosync. Geosync.	0.98 1.04 1.91 0.35 0.94 0.96 0.40 0.59 0.49 1.91 1.19 1.91 0.64 0.41
			Beginning Solar Arr Power Sul Solar Arr Power Sul Total Pro	of Life Power (kW) ay Weight (lb) psystem Weight (lb X ay Cost (\$ X 10 ⁶) psystem Cost (\$ X 10 ⁶) gram Cost (\$ X 10 ⁶)	103)

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		NE/	AR-TE	RM							MID	-TERA	٨					COST	S (\$M)
1979	1980	1981	1982	1983	1984	1985	1986	1987	1988	1989	1990	1991	1992	1993	1994	1995	Acq	Ops	Total	Avg
1	3	3		3	3	2		2	2	2	1		1	2						
1	5	4		5	4	3		4	4	3	2		2	4						
.6	1.7	1.7		1.7	1.7	1.2		1.4	1.4	1.3	.7		.7	1.4						
14	10	6	9	9	7	5	7	7	6	3	1	4	4	1			13	60	93	5.5
192	198	89	120	119	94	99	131	117	86	51	35	55	64	17			178	1289	1467	86
1	2	2	1	2 1	1	1			2	1		1			2	2				
			1	2	1	2	2 1 2	2 1 1 1 1	1 1	1	2 1 2	2 2	2	1	2	1				
2	2	2	2	7	2	5	4	6	3	3	4	8	5	2	5	6				
. 8	.7	.7	.7	2.4	1.0	1.8	1.8	2.5	1.4	1.0	1.9	3.0	1.7	.7	2.3	2.4				
8	6	11	13	15	12	24	28	16	9	14	14	8	10	14	15	9	72	154	226	13
122		162	208	195	204	258	274	178	172	207	213	162	166	222	201	138	867	2319	3186	187

Figure 3.15 Traffic Model - Non-NASA/Non-DoD Communications (Optimistic Budget)

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FUNCT	ON		MIS	SION	
Category	Subcategory	Code	Title	Destination (Alt./Incl.)	Power (kW)
Foreign Communica-		CC3-1-1	Arab Comsat (ARCOMSAT	Geosync.	0.42
tion		-2	ARCOMSAT Follow-on		0.49
		-3	Orbital Test Sat (OTS)	11	0.41
		- 4	Eurocomsat (ECS)		0.41
		-5	ECS Follow-on	17	0.42
		- 6	MAROTS		0.40
		-7	MAROTS Follow-on	11	0.42
		- 8	TV Broadcast Sat (TVBS)		1.57
		-9	TVBS Follow-on		1.56
		- 10	SYMPHONIE-3		0.48
		-11	AMSAT	11	0.08
		- 12	APPLE		0.36
		-13	Indian Sat (INSAT)	19	0.42
		-14	INSAT Follow-on		0.47
		- 15	PALAPA		0.48
		-16	PALAPA Follow-on		1.20
Foreign Communica-		-17	IRAN	Geosync.	0.40
tion (cont'd)		-18	IRAN Follow-on	11	0.56
		-19	SIRIO	***	
		-20	SIRIO Follow-on	11	0.38
		-21	NORDSAT	11	0.40
		-22	NORDSAT Follow-on		0.42
		-23	BRAZILSAT	**	0.59
		-24	BRAZILSAT Follow-on	11	0.62
		-25	NATO III		3
		-26	NATO Follow-or	11	0.64
		- 2.7	Eng. Test Sat (ETS-II)	U U	3
		-28	ETS IV		0.08
		29	Comm. Sat. (CS)		
		- 30	CS Follow-on		0.57
		- 31	Brdcst Sat. Exp. (BSE)		
		- 32	BSE Follow-on	1	1.19
		- 33	Exp. Comm. Sat. (ECS)		0.42
		- 34	TELESAT-B	11	
		- 35	TELESAT-C		0.64
		- 36	TELESAT-D		0.28
		- 37	TELESAT Follow-on	1	0.68
		38	UHF		0.42
		- 39	Canadian Direct Brdcst		1.41
		- 40	Other Regional		0.59
			Destant	and tite Demon (h	1471
			Beginni Solar A	ng of Life Power (K	vv]
			Dower A	Subsystem Weight (1)	h x 1031
			Edwert	Subsystem wergint (
			Solar A	rray Cost (\$ A 100)	2 1061
			L'ower i	Subsystem Cost (\$ 2	061
			Total	rogram Cost (\$ X 1	<u></u>
		1			

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(Constant)

			NE/	AR-TE	RM			MID-TERM							COST	S (\$M	[)				
	1979	1980	1981	1982	1983	1984	1985	1986	1987	1988	1989	1990	1991	1992	1993	1994	1995	Acq	Ops	Total	Avg
	1 1	1 1 1	2 2 1 1 1 2	1	1 1 2 1	1	1	198	1	1	1	1	1	1 1 1	1	199	1 1 2	Acq	Ops	Total	Avg
			1	1	1	1	1	1	1 1 1 1	1	1		1	1	1	1	1 1 1				
-	2	1	1	6	6	3	4	2	3	3	4	2	5	5	5	3	4				
-	. 8	1.0	2.1	1.7	2.6	1.4	1.9	.6	1.7	2.3	1.3	. 9	2.0	1.5	2.1	.9	2.6				
A STAN DE CASA	31 311	38 365	<u>39</u> 369	39 373	29 308	20 209	10 149	15 186	27 229	17 165	12 114	16 164	20 19	13 154	10 126	14 177	15 128	143 1397	222 2327	365 3724	21,5 219

Figure 3.15 Traffic Model - Non-NASA/Non-DoD Communications (Optimistic Budget) cont.

FOLDOUT FRAME

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FUNG	CTION		MIS	SION	
Category	Subcategory	Code	Title	Destination (Alt./Incl.)	fower (kW)
Disaster Warning		CS1-1-1	Disaster Warning	Geosync.	4.2
			Beginning o Solar Array Power Subs Solar Array Power Subs Total Progr	f Life Power (kW) v Weight (lb) ystem Weight (lb X 1) cost (\$ X 10 ⁶) ystem Cost (\$ X 10 ⁶) am Cost (\$ X 10 ⁶)	03)
Traffic Management		CS2-1-1 -2 -3	INMARSAT INMARSAT Follow-on INATSAT	Geosync.	0,50 0,60 0,60
			Beginning o Solar Array Power Subs Solar Array Power Subs Total Progr	f Life Power (kW) 7 Weight (lb) 7 Vost (\$ X 10 ⁵) 7 Cost (\$ X 10 ⁵) 7 ystem Cost (\$ X 10 ⁶) 7 ram Cost (\$ X 10 ⁶)	03)
Space Manufacturing	U.S. Domestic	CS3-1-1 -2 -3 -4	Space Processing R&D Com. Manuf-Develop. -Deployment -Servicing	Low/Low Low/Low Low/Low Low/Low	5, 0 10, 0 15, 0 1, 0
	Foreign	CS3-2-1 -2 -3 -4 -5	Space Processing R&D Com. Manuf-Develop. -Deployment -Servicing Spacelab Science/Tech	Low/Low Low/Low Low/Low Low/Low Low/Low	5.0 10.0 15.0 1.0 3.8
			Beginning of Solar Array Power Subs Solar Arra Power Subs Total Prog	of Life Power (kW) y Weight (lb) system Weight (lb X 1 y Cost (\$ X 10 ⁶) system Cost (\$ X 10 ⁶) ram Cost (\$ X 10 ⁶)	03)

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NEAR-TERM											MID	-TERA	1					COST	S (\$M	1)
1979	1980	1981	1982	1983	1984	1985	1986	1987	1985	1989	1990	1991	1992	1993	1994	1995	Acq	Ops	Total	Avg
								1	1				1	1						
								4	4				5	4						
			1					1.2	1.2				1.3	1.2						
					1 11	5 46	8 58	5 36	1 7	1	2	4 31	4 27	$\frac{1}{7}$			13 81	22	35 236	2.1
				2	1		,					2	1	,						
							1	1	1	1		1	1	1						
							. 3	. 2	.6	. 3		.7	.6	. 2						
					1	3	4	8	3	2	7	5	2				13	22	35	2.1
				6	33	77	75	70	46	50	85	69	31	6			151	397	548	32
					1	3	5 1	6 2	8	9	9	9	9	9	9	9				
									1	3	3	3	3	3	6	6				
						1	2	2 2	2	2	2	3	3	3						
		1	1	1		1	1	1	1	3 1	3 1	3 1	3	1 3 1	6 1	6 1				
																				<u> </u>
1	1	2	3	3	10	11	18	21	21	23	19	25	27	26	21	11	0	243	243	14

Figure 3.16 Traffic Model - Non-NASA/Non-DoD Support (Optimistic Budget)

EOLDOUT FRAME

FUNC	TION		MIS	SION	
Category	Subcategory	Code	Title	Destination (Alt. / Incl.)	Power (kW)
U.S. Domestic		CP1-1-1	Multipurpose Payload	Low/Low	4.2
2			Beginning Solar Arr Power Su Solar Arr Power Su Total Pro	of Life Power (kW) ay Weight (lb) bsystem Weight (lb X ay Cost (\$ X 10 ⁶) bsystem Cost (\$ X 10 gram Cost (\$ X 10 ⁶)	10 ³) 6)
Foreign		CP2-1-1 -2 -3 -4 -5 -6 -7 -8 -9 -10 -11 -11 -12 -13 -14 -15 -16	GEOS GEOS 2 EXOSAT UK-6 IRAS French Scientific European Scientific Canadian Scientific MST-3 ISS Replacement TAIYO Replacement EXOS A EXOS B ASTRO A ASTRO B Japanese Scientific	Geosync. Ellip/High Low/Int. Low/High Various Various Various Ellip/High Low/Int. Ellip/Low Ellip/Low Ellip/Low Low/Low Low/Low Various	0.18 0.18 0.30 0.04 0.56 0.55 0.04 0.03 0.03 0.02 0.03 0.02 0.03 0.02 0.04 0.04 0.04
			Beginning Solar Arr Power Su Solar Arr Power Su	of Life Power (kW) ay Weight (lb) bsystem Weight (lb X ay Cost (\$ X 10 ⁶) bsystem Cost (\$ X 10	. 10 ³)
			<u>Total Pre</u>	ngram Cost (\$ X 10°)	

FOLDOUT FRAME

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		NEA	R-TE	RM							MID	-TER/	Λ					COST	S (\$M	()
1979	1980	1981	1982	1983	1984	1985	1986	1987	1988	1989	1990	1991	1992	1993	1994	1995	Acq	Ops	Total	Avg
						1	1	1	1	1	1	1	1	J	1	1				
						4	4	4	.7	-4	- 7	-4	-7	-7	.7	.7				
				3	7	6	4	3	4	4	4	4	5	9	5	3	16	45	61	3.6
				19	43	31	20	21	20	21	20	21	32	49	29	16	101	241	342	20
	1	1 1 1	1	1	1	1	1	1 1		1	1	1		1 1	1	1				
	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1				
		1	1	1	2	1	1	2	1	2	3	2	1	2		1				
	.4	.7	.4	. 3	.7	.2	.4	.6	.1	.5	.6	.7	. 2	. 6	.3	.4				
10 116	14 169	10 120	5 83	9 83	4 63	4 51	4 63	3 57	4 69	6 68	5	1 53	4 71	4 63	4	11	32	59 976	91 1247	5.4

Figure 3.17	Traffic Model - Non-NASA/Non-DoD Scie	ntific
	(Optimistic Budget)	

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The traffic models have no official approval, either of NASA or of DoD, and are intended to be representative only. Nevertheless, the component parts have been extracted from published documents in most cases. The traffic models represent low and high average budgetary levels for the following mission categories:

- 1. NASA Observation
- 2. NASA Communication
- 3. NASA Support
- 4. NASA Scientific
- 5. NASA Planetary
- 6. DoD Surveillance
- 7. DoD Communication
- 8. DoD Navigation and Meteorology
- 9. DoD Weaponry
- 10. Non-NASA/Non-DoD Communication
- 11. Non-NASA/Non-DoD Observation
- 12. Non-NASA/Non-DoD Support
- 13. Non-NASA/Non-DoD Scientific

The mission categories are themselves divided into groups of missions which have functional similarities. The entries in Figures 3-1 through 3-17 are extracted from the data included in Volume III to this report. (Appendices VI through IX)

3.3 ADVANCED SYSTEM SCENARIOS

3.3.1 Background

A very large number of initiatives was identified in the 1973 NASA Mission Model, the "Outlook for Space" study, The Aerospace Corporation study "Advanced Space Systems and Their Orbital Support Needs (1980-2000)," DoD planning studies, internal NASA studies and many others. The totality of these initiatives represents a formidable data bank of ideas which could be implemented in the next 20 years or so, if desired. The concepts identified span the entire technical and functional range from current programs to massive undertakings with enormous increases in required technology and launch and support facilities. They represent varying degrees of schedule, risk, funding requirements, and potential benefits and hazards.

In order to handle the literally hundreds of known initiatives, a rationale was established in an Aerospace Corporation study for NASA (Reference 2) for categorizing the initiatives into five generic groups or eleven subgroups, as listed in Table 3-1. The generic groups attempt to subsume each of the identified initiatives and are intended to be broad enough that other initiatives yet to be identified will be likely to fall within one of the groups. A natural progressive increase in capability can be postulated for each of the eleven groups, exemplified by the deployment of a series of space systems over a period of time, with each system having a considerable increase in capability over its predecessor (but not necessarily replacing its predecessor). The increase in capability and the time period between each launch impacts the needs for technology advancements, the launch vehicle and support facility needs, and the overall space program funding requirements.

The development plan for each group provides the development required to satisfy the initiatives contained within that group. An orderly step-by-step technology program is the primary determinant of the number of time-phased steps in each of the development plans. Each step is intended to culminate in demonstrated flight hardware capable of operational use; however, the operational option may not be exercised.

In the construction of the development plans it was found expedient to lump the low and high altitude optical concepts (Groups 4 and 6) together Table 3-1. New Space Initiative Groupings

CATEGONY	NO.	INITIATIVE GROUPINGS* TITLE
-	1	Public Service Systems Using Microwave Multibeam Antennas
	2	Public Service Systems Using Long Microwave Antennas
	3	Active/Passive Radar and Power Distribution Systems
INFORMATION	4	Observation and Designation Systems Using Optics at Low Altitude
	5	High Altitude Navigation. Location, and Relay Systems
	6	Observation Systems Using Synchronous Altitude Optics
PROCESSING	7	Space Processing and Manufacturing
ENERGY	8	Large Scale, High Energy, Far-Term Systems
SCIENCE	9	National Operations Facilities
	11	Scientific and Research Experiments
PLANETARY	10	Planetary

* Initiative groupings and designators are identical to those identified in,"Integrated Planning Support Functions" (Study 2.7) Aerospace Report No. ATR-77(7378)-1 Vols. 1 and 11 June 1977, Contract NASW-2884

and also to combine the scientific and research experiments (Group 11) with the national operations facilities required to operate them (Group 9).

The construction of development plans in this manner provides maximum flexibility for dealing with an indeterminant future for the following reasons:

- 1. Each development plan is not linked to a single initiative, the need for which may change radically during the development time period.
- 2. The decision as to which initiative to promote can be delayed until late in the development schedule.
- 3. The unexpected need for crash programs is minimized.

3.3.2 Typical Initiatives

Some basic characteristics of typical initiatives that might be included in the various groups are listed in Tables 3-2 through 3-11. It should be noted that most of the initiatives are concepts only and that preliminary design information is in general not available. (The design of three advanced initiatives, viz: Personal Communications, Educational TV, and Electronic Mail are being examined by The Aerospace Corporation under contract to NASA in an ongoing study. Also NASA/Langley is initiating design studies of two large multipurpose public service satellites -a Data Acquisition Platform (DAP) and an Information Service Platform (ISP). In addition, the Air Force has recently initiated the concept design phase for the orbital assembly of a large spacecraft, using space-based radar as a representative mission). However, in the case of the Information category of initiatives a small number of primary sensors or antennas can be identified which, in general, drive the raw power requirements. Other factors, of course, influence the type of power system design to satisfy those raw power requirements.

	IDENTI-		GR	OUND		ar Salar en a Garrier a na		SPACE		
YEAR	CODE	ION TITLE AND DESCRIPTION		TRANS- MITTED POWER	ORBIT	ANTENNA DIAMETER	NUMBER OF BEAMS	CHANNELS/ BEAMS	TRANS- MITTED POWER	ELEC. POWER
1985	CC-10	Diplomatic/UN Hotlines Secure Conferencing 200 Heads of State	7 m	1 W	Sync	2 m	200	1	200 W	1 kW
1985	X-1	Telephone Long Line, High Capacity Long Line Service	10 m	500 W	Sync	10 m	50	1	25 kW	100 kW
1985	CC-9 1026 1027	Personal Communications Wrist Radio - 1	Stub	0,025 W	Sync	60 m	25	10 ³	6 kW	21 kW
1985	CS-9	Energy Use Monitor, Transmits Power Data on Query	Steele	25 W Peak	Sync	60 m	100	10 ³	6 kW	23 kW
1985	CS-14	Burglar Alarm, Sensors Transmit When Activated	Stub	G. 25 W	Sync	60 m	500	10 ³	Receive Only	1 kW
1985	CC-3	Disaster Communications Net	Stub	1 W	Sync	60 m	250	100	25 kW	75 kW
1987	MC-10	Military Communications Wrist Radio - 1	Helix	1 W	Sync	60 m	25	10 ³	25 kW	100 kW
1990	CC-9	Personal Communications Wrist Radio - 2	Stub	0. 025 W	Sync	70 m.	1600	10 ³	70 kW	21 kW
1990	X-2	Computer Long Line	3 m	500 W	Sync	25 m	200	1	100 kW	400 kW
1990	CC-11	Holographic Teleconferencing, Laser Holograms Transmitted	2 m	30 W	Sync	25 m	100	25	75 kW	220 kW
1990	CC-8	National Information Service - 1	2 m	0.05 W	Sync	25 m	10 ³	100	5 kW	15 kW
1990	CC-6	Advanced TV Broadcast	1 m 3 m	Receive 1 kW	Sync	25 m	250	33	50 kW	150 kW
1990	X-3	Military Aircraft Communication	1 m	0.2 W	Sync	25 m	10 ³	100	20 kW	75 kW
1990	X-4	Mobile Communication - Trunk	lm	0.2 W	Sync	25 m	103	103	200 kW	750 kW
1990	CC-4	Electronic Mail Transmission	2 m	1 W	Sync	25 m	103	100	100 kW	15 kW
1990	CC-2	Police Wrist Radio Communication-1	Stub	1 W	Sync	25 m	200	100	20 kW	75 kW
1990	CC-7	Voting/Polling Wrist Radio	Stub	0.25 W	Sync	60 m	100	103	25 kW	90 kW
1			1							

Table 3-2. Typical Group 1 Initiatives (Public Service Systems Using Microwave Multibeam Antennas)

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Table 3-3. Typical Group 2 Initiatives

(PUBLIC SERVICE SYSTEMS USING LONG MICROWAVE ANTENNAS WITH STATIONKEPT ANTENNAS)

	IDENTI-		GROL	IND		5	PACE		
YEAR	FICATION	TITLE AND DESCRIPTION	ANTENNA TYPE	TRANS- MITTED POWER	ORBIT	ANTENNA SIZE	NUMBER OR ARRAYS	TRANS- MITTED POWER	ELEC. POWER
1980	CS-16	Personal Nav - 1: Near Term. Two Orthogonal Sweeping Fan Beams. Time of Successive Passage Gives Location	Stub	Receive	Sync	50 x 0.3 m	2	200 W	1 kW
1990	CO-8	Border Surveillance. Narrow Beam Antenna Monitors Border Sensors	Stub	0.01 W	Sync	3000 x 3 m	1	Receive	20 kW
1990	CS-7	Personal Navigation - 2	Stub	Receive	Sync	4000 x 0.5 m	2	8 W	2 kW
1990	CC-12	Vehicle or Package Locator. Self-Location of Package by Personal Navigation System. Report Location on Query by Personal Communica- tion	Stub	3 W Peak	Combin and Vot Radio	ation of Perso ing/Polling Wi	nal Nav. rist		23 kW
1990	CS-10	Vehicle Speed Limit Control. Self-Location by Personal Navigation System. Speed Limit Instruction for Each Location by Comsat.	Stub						1 kW

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YEAR	IDENTI- FICATION CODE	TITLE AND DESCRIPTION	ORBIT	ANTENNA S I Z E	TRANS- MITTED POWER	WEIGHT METRIC TON	NUMBER OF UNITS	RESOLU- TION (M)	SWATH (NMI)	ELEC. Power
1980	XER-9	OFT-2 Radar - Geology	400 km	1			1	40	55	
1980	XER-II	OFT-5 Radar - Soll Moisture	400 km				1	100	200	
1985	XER-12	Spaceborne Imaging Radar	400 km			i i		25	100	
1985	XER-17	Customized Orbital Imaging Radar, Small Free Flyer	400 km					25	100	
1985	1	Advanced Sea State Monitor			10 kW			25	200	
1985		Phased Array Radiotelescope - Terrestrial	600 km	30 x 30 m	None		1			}
1985		Phased Array Radiotelescope - Astronomical, Multifrequency	600 km	30 x 30 m	None		1		1	
1985	CO-5	Multinational Air Traffic Control Radar – Diffracting Passive Element in Space to Obtain Large Area Over-Horizon Coverage From Ground-Based Radar	600 km	75 x 75 m	None	1.7	150			1 kW
1985	MO-16	Military Over-Horizon Radar Fence	SGU km		None					
1987		Radar Ground Mapper - Urban/Rural Land Use	600 km		1 kW			100	200	
1990	2007 2008	Long Wavelength Microwave Systems - Passive Microwave Receiver 1, 4 GHz for Terrestrial Geology (Phased Array Version)	600 km	100 x 100 m	None		1	<u>.</u> • •		
1990	CO-13	High Resolution Earth - Mapping Radar	400 km		? MW	50	1	3	400	2.5 MW
1990		UN Truce Observation Imaging Radar	400 km		1 MW	50	1	3	40C	
1995		Advanced Array Radar - Mullifunction Capability	600 km		1 MW	60	4	3	1200	
2000		Coastal Passive Radar	Sync		2 MW		2			
2000		Power Relay Satellite	Sync							
2000	CS-8 1012 1013	Multinational Energy Distribution – Phase Controlled Reflectors Direct Microwave Power From Power Source to Users	600 km	225 x 5 m	None	15	200			20 kW
2000	1098	Large Scale Microwave Telescope	600 km	10 ³ x 10 ³ Thinned	None		1			

Table 3-4. Typical Group 3 Initiatives (Power Distribution and Active/Passive Radars)

Table 3-5. Typical Group 4 Initiatives

(Observation and Designation Systems Using Low Altitude Optics)

Year	Identification Code	Title and Description	Electrical Power
1985	CO-1	Advanced Resources/Pollution Observatory - Only Optical (Not Radar) Sensors Included; 2-m Multispectral Sensor	12 kW
1985	CO-4	Ocean Resources and Dynamics System - LWIR Sensor 3-m Optics	25 kW
1985	CO-6	U.N. Truce Observation Satellite - Visible and IR 2-m Optics; CCD Focal Plane	3 kW
1990	CO-11	Atmospheric Temperature Profile Sounder - Pulsed CO ₂ Laser (1 kW); 10-cm Optics	5 kW
1982	XER-1	Landsat Follow-On	
1985	XER-2	Earth Survey Satellite	
1982	XER-6	Specialized Multispectral Imaging and Analysis System	
1982	XER-7	Heat Capacity Mapping Mission	
1986	XER-8	Sterosat	

Table 3-6. Typical Group 5 Initiatives

(High Altitude Navigation and Location Systems)

Year	Identification Code	Title and Description	Electrical Power
1980	MS	Global Positioning System (GSP)	1 kW
1985		TDRSS	600 W
1985	CO-7	Nuclear Fuel Locator	300 W
1985	CC-1	Global Search and Rescue Locator	1 kW
1985	CC-5	Transportation Services Satellites	600 W
1990		TDRSS Follow-On	1 KW

Table 3-7. Typical Group 6 Initiatives

(Observation Systems Using Synchronous Orbits)

Year	Identification Code	Title and Description	Electrical Power
1985	CO-2	Fire Detection - 3-m IR Optics CCD Mosaic Detector for Prompt Small Outdoor Fire Detection	2 kW
1985	CO-3	Water Level and Fault Movement Locator - Picosecond Pulsed Laser Used in Radar Mode for 0.3 nmi Range Resolution	250 W
1985	CO-12	Synchronous Meteorological Satellite - 1-m Visible Light Optics; Photocathode-CCD Detector	1 kW
1990	CS-6	Night Illuminator	1.2 kW
1990		Synchronous Landsat - 2-m Optics; 10-m Resolution	1 KW

Table 3-8. Typical Group 7 Initiatives(Space Processing and Manufacturing)

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Year	Identification Code	Title and Description	Electrical Power
1984	1014	Hazard Waste System - Development	
1985-1990	1015	Hazard Waste System - Operational	
1981-1987	1028	"Short Term" Physical Chemical Research - Crew Operated	
1987-1999	1029	"Long Term" Physical Chemical Research - Crew Operated	
1981-1987	1030	''Short Term'' Low-g Material Science Research - Crew Operated	
1987-1999	1031	"Long Term" Low-g Material Science Research - Crew Operated	
1987-1999	1032	Commercial Processing - Crew Operated	
1981-1987	1033	"Short Term" Biological Materials Research - Crew Operated	
1987-1999	1034	"Long Term" Biological Materials Research - Crew Operated	
1981-1987	1039	Preliminary Disease Process Research - Crew Operated	
1987-1999	1040	Disease Process Research - Crew Operated	
1995	1117	Industrial Space Facility	
2000	4006	Synthesis of Living Matter in Labs	

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Table 3-9. Typical Group 8 Initiatives

(Large Scale, High Energy, Far-Term Systems)

Year	Identification Code	Title and Description	Electrical Power
1995	CS-1	Energy Generation - Solar to Microwave	10 GW
1995	CS-2	Energy Generation - High Efficiency Solar Cells with Thin Film Mirror Concentrator	10 GW
2000	CS-3	Energy Generation - Nuclear to Microwave	10 GW
2000	х	Energy Generation - Solar Laser (for Space Use)	
2000	CS-5	Aircraft Laser Beam Powering	
1995	CS-4	Nuclear Waste Disposal	
2000	CS-12	Ozone Layer Protection	
2000+	X	Laser Beam Reflector System as Energy Common Carrier	

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Table 3-10. Typical Group 9 Initiatives (National Operations Facilities)

Year	Identification Code	Title and Description	Electrical Power
1990		National Microwave Detection Facility - Manned Used for solar, galactic, metagalactic radio astronomy, search for extraterrestrial radio signals, interplanetary microwave link, precise radar astronomy, passive microwave scanning of earth.	10 kW
2000	CO-10	National Space Telescope Facility - Manned Visible and near visible; also high energy radiation. Basic instrument is astronomical super-telescope, but other instruments are included, such as long base interferometers, large, low quality photon buckets, cosmic ray equipment, X-ray imaging telescopes. Used for celestrial and terrestrial observation.	10 kW

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Year	. 1980 1980		1980	1983	1985	1985 1990		1000
Space Facility	-					Nation	nal Research Fa	cilities
s-ientific Field	Free-Flying	Free-Flying Other Orbits	Shuttle	Spacelab	Tethered Shuttle	Biological Research Laboratory	Microwave Astronomicat And Terrestriat Observatory	High-Energy Radiation Observatory (Add-On To Optical)
Astrophysics								-
Solar-Terrestrial								
Life Sciences + Basic Biology			See Notes*					
Life Sciences - Biology and Human Physiology in Space Environment								<u>.</u>
Fundamental Physics - Large Scale Laws					-			
Fundamental Physics - Small Scale Fundamental Interactions								
Basic Physics and Chemistry								

Table 3-11. Typical Group 11 Initiatives (Scientific and Research Experiments)

•NOTES:

Initiatives Constitute Matrix Elements

Typical Initiatives are: EOIVOS Effects Experiment (Outlook for Space No. 1064)

Solar Maximum Mission (Extended Five-Year Plan No. X ST-D

All Matrix Elements are not Necessarily Represented by Viable Initiatives

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3.3.3 Mission Scenarios

Development plans and the resulting prime power requirements are illustrated in Figure 3-18 through 3-26. In general, the required power levels increase monotonically within each generic group. An optimistic and conservative schedule is approximated for each operational capability step. Representative initiatives are listed and coded to indicate their source as follows:

(OFS)	=	The NASA "Outlook for Space" study (Reference 31)
(5-YP)	=	The NASA Five-Year Plan (References 14 and 15)

 (A) = The Aerospace Corporation "Advanced Space Systems Concepts and Their Orbital Support Needs (1980-2000)" Study (Reference 1)



Figure 3-18. Group 1 Initiatives (Public Service Platforms Using Microwave Multibeam Antennas)

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Figure 3-19. Group 2 Initiatives (Public Service Systems Using Long Microwave Antennas with Stationkept Antennas)



Figure 3-20, Group 3 Initiatives (Power Distribution and Active/Passive Radars)

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Figure 3-21. Group 4 and 6 Initiatives (Optical Observation, Designation, and Measurement)

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Figure 3-22. Group 5 Initiatives (High Altitude Navigation, Location, and Relay Systems)

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Figure 3-23. Group 7 Initiatives (Space Processing and Manufacturing)

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Figure 3-24. Group 8 Initiatives (Large Scale, High Energy, Far-Term Systems)



Figure 3-25. Group 9 and 11 Initiatives (Scientific/Research Experiments and National Facilities)

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ORBITERS Lunar (5 YP) Titan (OFS) Uranus (OFS) INITIATIVE Jupiter (5 YP, OFS) Venus/Radar (5 YP) Neptune (OFS) Mars Polar (OFS) Mercury (OFS) Saturn (OFS) POWER LEVEL SCHEDULE (OPTIMISTIC/CONSERVATIVE) **FLY-BY PROBES** Saturn/Uranus (5 YP, OFS) Neptune (OFS) INITIATIVE Encke Comet (OFS) Jupiter/Pluto (5 YP) Interplanetary - Near Sun (OFS) Jupiter Atmospheric (OFS) POWER LEVEL SCHEDULE (OPTIMISTIC/CONSERVATIVE) 3-74 LANDERS Viking Mobile (5 YP) Titan (OFS) Titan, w/Penetrometers (OFS) Halley Rendezvous (5 YP) Mercury w/Penetro- Venus, w/Penetrometers (OFS) meters (OFS) Lunar Rover (0-S). INITIATIVE Venus (OFS) Jupiter Tour, Ganymede · Asteroid w/Penetro-Lander (5 YP) meters (OFS) Mars Rover (OFS) ORIGINAL PAGE IS OF POOR QUALITY SAMPLE RETURNS Mars (OFS, 5 YP) Mercury (OFS) Lunar Highlands (OFS) Venus (OFS) INITIATIVE . Asteroid (OFS) Comet (OFS) POWER LEVEL SCHEDULE (OPTIMISTIC/CONSERVATIVE)

> Figure 3-26. Group 10 Initiatives (Planetary Missions)

4. SPACE POWER TECHNOLOGY PROJECTIONS

4.1 INTRODUCTION

A review was made of the existing literature to assess potential future space power technology advancements, assuming that the present rate of progress and funding continues. The utility of this is that, if the projections for a particular area of technology do not meet the requirements at a specific point in time, then increased emphasis (in terms of funding, generally) must be placed on that area of technology.

4.2 SOLAR CELLS

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4.2.1 Power-Efficiency Characteristics

The basic efficiences of various types of current production and developmental silicon solar cells are illustrated in Figure 4-1. Conventional cells, the best available until recently, provide typical efficiencies of 10-11%. A number of cell design and processing improvements during the past several years, (e.g., shallower junctions, finer grid designs, better anti-reflection coatings), led to the so-called "hybrid" cells, with substantially higher performance. The "Helios" cells (Spectrolab designation) are similar to the hybrid cells, but with the addition of a p+ backfield that lowers the effective resistivity of the cell material. Both the hybrid and Helios cells can be fabricated with integral back-surface reflectors that improve the basic cell efficiency and reduce the operating temperature. All new satellite programs and most recent cell procurements seem to have specified some variant of the hybrid or Helios cell types; the "conventional" cell is essentially obsolete.

A number of potential cell improvements are currently being pursued, the most prominent being the use of "sculptured" or "non-reflective" cell surfaces. These surfaces are textured (at a microscopic level) by



Figure 4-1. Solar Cell Power-Efficiency Characteristics
special etching processes so that absorption of solar energy is improved and reflection is reduced. These cells and their manufacturing processes have not yet been developed to the point where flightworthy cells can be produced in large quantities.

4.2.2 Efficiency Projections

Solar cell efficiency projections, based on existing technology and development programs, are shown in Figure 4-2. The silicon cell projections reflect an assumption that the developmental cell types shown in Figure 4-1 will eventually become production cells and that overall cell performance improvements will continue in the future. The long-term trend of these improvements should tend to be asymptotic, since there is a maximum theoretical limit of about 22% to silicon cell efficiency.

A projection for gallium arsenide cells is also shown to provide some idea of the potential performance of such cells, even though their state of development is far behind that of silicon cells and they have never been used on spacecraft, except as part of solar cell flight experiments. Several organizations (e.g., IBM, Varian Associates, and Hughes Research Labs) have made small cells in the laboratory with claimed efficiencies of 16 to 18%, and there appears to be good potential for still better performance. However, there is now no production capability for gallium arsenide cells and no firm indication as to when or if one will ever exist. Consequently, all solar array performance projections shown on subsequent charts have been based on silicon cells only.

The projections are shown as bands rather than single lines to reflect not only the uncertainty of the projections but also the fact that new programs do not always select the highest-efficiency cells available because of cost, schedule, or other mission requirements. In general, the midpoint of the bands should provide a realistic average projection.



Figure 4-2. Solar Cell Efficiency Projections

4.3 SOLAR ARRAY

4.3.1 Specific Area Projections

Solar array specific area projections, in terms of array area per kilowatt of output, are shown in Figure 4-3 for fully sun-oriented arrays with silicon solar cells and no radiation degradation. These projections are derived directly from the cell efficiency projections of Figure 4-2 and reflect a cell packing factor of 80% and an array temperature of 58°C.

Specific area requirements in terms of square feet per kilowatt of electrical load can be determined approximately by multiplying the specific areas shown in Figure 4-3 by 1.5 for geosynchronous equatorial orbits and by 2.2 for low earth orbits. These factors account for the worst-case eclipsing and battery recharge requirements for each type of orbit, and also include radiation degradation allowance of 25% for geosynchronous equatorial orbits (7-10 year missions) and 10% for low earth orbits (~ 5 year missions). Intermediate-altitude or elliptical orbits that pass through the inner trapped proton belts could incur substantially higher array degradation.

4.3.2 Specific Weight and Specific Area

Figure 4-4 illustrates the estimated or demonstrated specific areas and specific weights of several advanced array designs now under development or study. The weights shown include storage and deployment equipment, but do not include orientation mechanisms or associated power transfer equipment. The developmental arrays are advanced flexible roll-out or foldout designs (except for the TRW lightweight rigid array) with outputs of about 1 to 25 kW. The 1.5-kW Hughes FRUSA (Flexible Roll-Up Solar Array) design was flight-tested successfully as an experiment in late 1971 on the Space Test Program (STP) 71-2 spacecraft, and a similar 6-kW design has recently been selected as the prime power source for the STP 80-2 spacecraft. The 25-kW Lockheed SEPS (Solar Electric Propulsion System) array



Figure 4-3. Solar Array Specific Area Projections

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Figure 4-4. Solar Array Specific Weight and Specific Area

is a fold-out design being developed as a power source for electric propulsion. The GE/JPL 200 W/kg design exists only as a paper study and is not now under development.

The developmental array performance shown is based on conventional or early hybrid cell performance; the potential performance of these arrays with high-efficiency cells (15-16%) is also indicated.

4.3.3 Specific Weight Projections

Solar array specific weight projections are shown in Figure 4-5. These projections are based primarily on the assumption that the SEPS array technology would be available (with high-efficiency cells) by about 1980, and the GE/JPL 200 W/kg technology would be available by 1985. Also, some conservatism was applied to compensate for possible optimism in the estimated performance shown in Figure 4-4.

Projected weights of orientation mechanisms and power control equipment are also shown in Figure 4-5. Power control equipment would include components, such as voltage regulators and battery chargers, necessary to control and regulate the power system. These projections are based primarily on unpublished analyses by the Air Force Aero Propulsion Laboratory.

4.4 Battery Energy Density Projections

Virtually all spacecraft programs today use rechargeable nickelcadmium (Ni-Cd) batteries for energy storage. Conventional Ni-Cd batteries have been used in spacecraft for over 15 years and represent a fairly welldeveloped technology. Such batteries of current proven design can provide a total energy density, when completely discharged, of about 10-12 watt-hr/ lb. Advanced lightweight Ni-Cd battery designs are claimed to be capable of much higher performance, up to 15-20 watt-hr/lb, but the long-term reliability of such designs has not yet been proven.



Figure 4-5. Solar Array Specific Weight Projections

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The "usable" energy density of spacecraft Ni-Cd batteries is less than the totals cited above, because they must be derated, i.e., cycled at less than 100% depth of discharge, to provide the required cycle life and reliability. The amount of derating necessary depends primarily on the number of charge-discharge cycles required, which in turn depends on the mission length and the frequency of eclipses and/or peak loads requiring battery load sharing. The best current battery designs could provide a usable energy density of about 6-8 watt-hr/lb, with no redundancy, for long (5-10 yr) missions in geosynchronous equatorial orbits. In low earth orbits, for missions up to about five years, the usable densities would be about half of these values, due to the greater frequency of eclipses.

The overall usable energy density of batteries installed in a spacecraft is further reduced by whatever battery redundancy is provided to compensate for possible battery failures during the mission. Parallel batterylevel redundancy has been commonly used in the past, in which multiple batteries are provided so that even if one or more failures occur, sufficient battery capacity will remain to complete the mission. Some recent, more sophisticated designs have incorporated cell-level redundancy. With this approach, each battery includes several extra cells and suitable electronic circuits that permit defective cells to be bypassed, so that failure of an individual cell does not fail the entire battery. For equivalent reliability, cell-level redundancy can provide a substantial weight advantage over battery-level redundancy.

Battery energy density projections shown in Figure 4-6 apply to complete, installed battery systems with cell-level redundancy, and include weight allowances for redundant cells, associated bypass electronics, and thermal control components such as heat pipes. The curves shown are for long (7-10 yr) missions in geosynchronous equatorial orbits, with appropriate adjustment factors for low orbit missions of up to about five years' duration. It is assumed that nickel-hydrogen batteries would begin to supplant Ni-Cd batteries in the early 1980's. A more advanced battery type,



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Figure 4-6. Battery Energy Density Projections

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such as lithium-sulfur, might become available in the late 1980's. The lithium-sulfur battery is being investigated for possible electric vehicle and electric utility load-leveling applications, but it is in a very early stage of development and its ultimate feasibility and availability are very uncertain.

4.5 <u>SOLAR ARRAY-BATTERY POWER SYSTEMS</u> SPECIFIC WEIGHT PROJECTIONS

The solar array and battery performance projections have been used to derive weight projections for complete solar array-battery systems and their components; these are shown in Figures 4-7 and 4-8 for geosynchronous equatorial and low earth orbits, respectively. The projections are in terms of specific weight based on load requirements, viz., lb per kilowatt of electrical load, and reflect the eclipsing and battery recharge requirements of each type of orbit. Allowances made for solar array radiation degradation were 25% for geosynchronous equatorial orbits (7-10 year missions) and 10% for low earth orbits (~ 5 year missions). Intermediatealtitude or elliptical orbits that pass through the inner trapped proton belts could suffer substantially higher array degradation.

For geosynchronous equatorial orbits the battery weight comprises roughly half the total system weight, regardless of battery type or time period. Also, the solar array weight becomes such an insignificant fraction of the total system weight after the early 1980's that further improvements in array technology would appear to have little impact on the system weight. These trends are similar, though not so pronounced, for low earth orbits.

4.6 RADIOISOTOPE POWER SYSTEMS SPECIFIC POWER

Projected radioisotope power system performance, in terms of specific power output per lb of power system weight, is shown in Figure 4-9. Cost estimates, in dollars per watt of electrical output, are also shown. These projections are based on ERDA estimates for 150-2000 watt systems. These systems would use plutonium-238 fuel, with a half-life of





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Figure 4-8. Specific Weight Projections

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Figure 4-9. Radioisotope Power Systems Specific Power

about 86 years, to provide a nearly constant power output over a 5-10 year mission. The radioisotope thermoelectric generators (RTGs) available now and in the near future would be similar to the SNAP-19 and SNAP-27 units used on the Nimbus weather satellite and Apollo programs, respectively. Performance improvements are expected to result from the development of higher-efficiency selenide thermoelectric converter materials. Advanced designs with outputs of 2 kW or more might use Rankine or Brayton-cycle turbogenerators that have been under development for several years by NASA for possible application to isotope power systems.

4.7 NUCLEAR REACTOR SPACE POWER

4.7.1 <u>Status</u>

Figure 4-10 summarizes the status in the area of nuclear reactor space power system development. This development effort, though extensive and quite active in the early and mid 1960's, is virtually nonexistent now, for several reasons:

- 1. Performance of systems based on the relatively low-temperature zirconium-hydride thermal reactor technology generally did not provide compelling weight, size, or cost advantages over alternative systems, viz., solar array-battery systems.
- 2. Advanced systems based on fast reactor technology offered potentially high performance but involved such high temperatures and exotic materials (e.g., refractory metals and alkali metal working fluids) that their long-term reliability and even ultimate feasibility were doubtful.
- 3. No firm requirements, either military or NASA, were ever established for nuclear reactor space power systems.

Recent activity has consisted of an ERDA-sponsored study of 10-75 kilowatt zirconium-hydride reactor systems compatible with the Space Shuttle and of continuing studies of thermionic fast reactor systems at Los Alamos Scientific Laboratory.

- ZIRCONIUM HYDRIDE TECHNOLOGY
 - Extensive Development 1957-1973 (SNAP-2, SNAP-8, SNAP-10A)
 - Reactors to 1000 kW_t Built and Tested
 - Thermoelectric and Mercury Rankine Power Conversion Components Built and Tested (0.5-60 kW_e)
 - Flight Test, 1965 (SNAP-10A)
 - Currently Inactive

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- Recent Systems Studies (Thermoelectric, Brayton, Organic Rankine, Stirling, 10-75 kW_e)
- ADVANCED FAST REACTOR TECHNOLOGY
 - Extensive System Studies 1960-1973 (SPUR, SNAP-50, SNAP-70)
 - Liquid Metal Rankine (SPUR, SNAP-50, 300-1000 kW_e)
 - Thermionic In-Core (SNAP-70), Out-of-Core, On-Core
 - Little Reactor Design; Considerable Liquid Metal Technology Development
 - Currently Inactive
 - Thermionic System Studies

Figure 4-10. Nuclear Reactor Space Power Background

4.7.2 ERDA's 'Revitalized' Space Reactor Program

ERDA is now attempting to "revitalize" the space reactor program and to redirect it primarily toward producing Space Shuttle-compatible systems in the 10-100 kilowatt range, with a tentative schedule as shown in Figure 4-11. This schedule is evidently based on certain assumptions concerning availability of development funding and the existence of at least tentative requirements for this type of power system. Recent information from ERDA indicates that the funding necessary to initiate this development program has not yet been forthcoming, so the schedule would slip at least one year.

From the information presented in this and Figure 4-10, it should be evident that the future availability of nuclear reactor space power systems is very uncertain and cannot be predicted with any confidence. If a definite need is established, radical policy changes towards space reactor development and deployment must occur.

4.8 **POWER SYSTEM SPECIFIC WEIGHT VS OUTPUT**

Figure 4-12 shows a time-phased comparison of the specific weight (lb/kilowatt of electrical load) of several types of solar and nuclear reactor power systems in low earth orbits. In geosynchronous equatorial orbits the solar power systems would be about 15% lighter.

The solar array-battery system weights were obtained from the projections shown in previous figures. Nuclear reactor system weights were obtained from References 32 and 33 and include shielding weights for unmanned payloads. Weights of the solar-Brayton and solar-thermionic systems were obtained from Reference 34 and are based on thermal energy storage, rather than battery storage, for eclipse operation. The availability dates shown for nuclear reactor and solar thermal systems are rough estimates of the dates that such systems could become available if a firm

KEY OBJECTIVES/REQUIREMENTS

/ Power Output: 10-100 kW_e

- I Life: 5-7 Years
- I Space Shuttle Compatible
- TENTATIVE SCHEDULE





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Figure 4-12. Power System Specific Weight vs. Output

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requirement for them existed. Radioisotope systems are not shown in Figure 4-12, since their specific weights would exceed 300 lb/kW.

Scaling effects cause the specific weight of nuclear reactor power systems to decrease as power level increases. This effect also applies to a lesser extent to solar power systems, but is not shown in Figure 4-12 because it is assumed that large solar power systems would be built up from several smaller systems; that is, they would be modularized.

These results indicate that nuclear reactor systems, if they materialize, could offer some weight advantage over advanced solar array-battery systems at power levels above 10-20 kW. Radiator area requirements for the low-temperature thermal reactor systems would be about one-fourth to one-third the area of an equivalent solar array.

Solar thermal systems do not appear competitive with solar arraybattery systems, since they offer no weight advantage and in addition would require high-quality solar concentrators, high pointing accuracy, and high operating temperatures. Previous studies have substantiated this conclusion.

4.9 <u>POWER DISTRIBUTION WEIGHT VS SYSTEM VOLTAGE</u>

Figure 4-13 illustrates the strong influence of system voltage on power distribution weight for large power systems. The weight penalty for low voltages results from the heavy cables required to carry high currents. It is clear that conventional 28-volt distribution will not be suitable for large multikilowatt power systems. A trend to higher system voltages is already reflected in the STP 80-2 spacecraft design, which will have a 105volt bus to supply approximately 4 kW to an experiment payload, and, of course, solar power station studies are considering voltages of 20 to 40 kV.



Figure 4-13. Power Distribution Weight vs. System Voltage

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4.10 POWER SYSTEM HARDENING TECHNIQUES

Table 4-1 summarizes the hardening techniques in use and under study for solar array-battery power systems for military spacecraft. These techniques are intended to provide hardening against both high-altitude thermonuclear explosions and laser radiation. Such hardening can incur substantial weight and cost penalties.

Solar array hardening techniques are aimed basically at reflecting, or at least not absorbing, as much incident radiation as possible, and at minimizing the damage done by that which is absorbed. Metals with low atomic numbers, such as aluminum, are used for cell interconnects and contacts to minimize X-ray absorption. Solder is not used for interconnect bonding or grid coating because of its high X-ray absorption coefficient and low melting temperature. Laser radiation can be rejected by filter coatings that do not absorb energy at typical laser wavelengths or intensities. Adhesives and substrates with high thermal conductivity may be used to conduct heat away from solar cells and other sensitive components. Fused silica cover glass is used because of its resistance to crazing from the mechanical stresses caused by severe thermal pulses. There is no feasible way to shield solar cells from neutrons, so degradation of output due to neutron damage can be compensated for only by oversizing the array.

Hardened electronic circuits contain components and circuitry designed to suppress electromagnetic pulses and to minimize their damaging or disruptive effects. Radiation shielding may be provided for especially sensitive components.

Table 4-1. Power System Hardening Techniques

SOLAR ARRAYS

- Low Z Interconnect and Contact Materials (A1)
- Weided Interconnects
- Solderless Contacts and Grids
- Narrow Bandwidth Reflective Filters
- High Thermal Conductivity Adhesives and Substrates
- Fused Silica Coverglass

BATTERIES

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- None
- ELECTRONIC CIRCUITS
 - Suppression of System Generated Electromagnetic Pulse (SGEMP)
 - Shielding

5. STUDY RESULTS

5.1 GROUPED INITIATIVES POWER REQUIREMENTS

5.1.1 Power vs Time Requirements

Figures 5-1 through 5-8 show the power requirements for each initiative group as a function of time. Of the two solid plots, one represents an ambitious, well-funded, overall NASA space program, and one represents a more conservative approach where procurement of major systems is delayed approximately a further seven years. (The seven-year cycle was selected in a relatively arbitrary manner. However, it represents an estimate of the average time necessary to procure a major advanced space system, from initial go-ahead to IOC.) The dashed plot, in each case, indicates a stretched-out program in which each development program commences at approximately the same time as the optimistic program, but the procurement of major line items is spread over a longer period of time.

5.1.2 Results

The data contained in Figures 5-1 through 5-8 can be used in a number of ways. One use is to perform a rough rank ordering of the power requirements of the initiative groups. This provides information to determine which initiative groups can be "captured" by a given space power development plan at a specific point in time. In general, the initiative group development plans are divided into a number of steps or subgroups providing the option of not consummating all of the possible steps. Table 5-1 lists the subgroups of each initiative group in power demand rank order. It lists also the approximate IOC dates for an optimistic, well-funded NASA space plan, a more conservatively funded plan, and a stretched-out plan. The table demonstrates the power levels necessary to capture individual initiative group and subgroup developments.





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Figure 5-2. Power Requirements - Group 2 Initiatives (Public Service Systems Using Long Microwave Stationkept Antennas)







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Figure 5-4. Power Requirements - Groups 4 and 6 Initiatives (Optical Observation, Designation, and Measurement)



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> Figure 5-5. Power Requirements - Group 5 Initiatives (High Altitude Navigation, Location, and Relay System)

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Table 5-1. Initiative Group Rank Ordering

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	INFILATIVE				
Group/ Subgroup	Title	Optimistic Program	Stretched Program	Conservative Program	Power Level
2/1	PUBLIC SERVICE SYSTEMS USING LONG MICROWAVE STATIONKEPT ANTENNAS - I	1983	1983	1957	1.0 kW
3/1	POWER DISTRIBUTION SYSTEMS AND ACTIVE/PASSIVE RADAR - I	1982	1982	1989	1.0 kW
2/2	PUBLIC SERVICE SYSTEMS USING LONG MICROWAVE STATIONKEPT ANTENNAS - 11	1987	1991	1994	1.3 KW
5/1	HIGH ALTITUDE NAVIGATION, LOCATION, AND RELAY SYSTEM - I	1983	1983	1990	1.7 KW
2/3	PUBLIC SERVICE SYSTEMS USING LONG MICROWAVE STATIONKEPT ANTENNAS - 111	1992	1999	1999	2.0 kW
4 & 6/1	OPTICAL OBSERVATION, DESIGNATION, AND MEASUREMENT - 1	1982	1982	1989	2.0 kW
9 & 11/1	SCIENTIFIC/RESEARCH EXPERIMENTS AND NATIONAL FACILITIES - I	1984	1984	1991	2.0 KW
5/2	HIGH ALTITUDE NAVIGATION, LOCATION, AND RELAY SYSTEM - II	1988	1992	1975	2.2 kW
5/3	HIGH ALTITUDE NAVIGATION, LOCATION, AND RELAY SYSTEM - III	1994	2001	2001	3.0 kW
1/1	SERVICE PLATFORMS USING MICROWAVE MULTIBEAM ANTENNAS - I	1983	1983	1990	4,0 kW
3/2	POWER DISTRIBUTION SYSTEMS AND ACTIVE/PASSIVE RADAR - 11	1986	1993	1993	5.0 kW
4 & 6/2	OPTICAL OBSERVATION, DESIGNATION, AND MEASUREMENT - 11	1986	1988	1993	5.0 kW
9 & 11/2	SCIENTIFIC/RESEARCH EXPERIMENTS AND NATIONAL FACILITIES - 11	1988	ിപി	1995	5.0 kW
4 & 6/3	OPTICAL OBSERVATION, DESIGNATION, AND MEASUREMENT - III	1990	1994	1997	10.0 kW
7/1	SPACE PROCESSING AND MANUFACTURING - I	1983	1983	1990	10.0 kW
9 & 11/3	SCIENTIFIC/RESEARCH EXPERIMENTS AND NATIONAL FACILITIES - 111	1993	2000	2000	IO,0 kW
4 & 6/4	OPTICAL OBSERVATION, DESIGNATION, AND MEASUREMENT - IV	1995	2002	2002	20,0 kW
1/2	SERVICE PLATFORMS USING MICROWAVE MULTIBEAM ANTENNAS - 11	1987	1990	1994	25.0 KW
8/1	LARGE SCALE, HIGH ENERGY, FAR-TERM SYSTEMS - I	1982	1982	1989	25.0 kW
3/3	POWER DISTRIBUTION SYSTEMS AND ACTIVE/PASSIVE RADAR - 111	1990	1997	1997	50.0 kW
7/2	SPACE PROCESSING AND MANUFACTURING - 11	1988	1992	1995	50.0 kW
7/3	SPACE PROCESSING AND MANUFACTURING ~ [1]	1993	2000	2000	100.0 KW
1/3	SERVICE PLATFORMS USING MICROWAVE MULTIBEAM ANTENNAS - 111	1993	2000	2000	100.0 kW
8/2	LARGE SCALE, HIGH ENERGY, FAR-TERM SYSTEMS - 11	1984	1986	1990	210.0 kW
3/4	POWER DISTRIBUTION SYSTEMS AND ACTIVE/PASSIVE RADAR - IV	1994	2001	2001	300.0 kW
8/3	LARGE SCALE, HIGH ENERGY, FAR-TERM SYSTEMS - 111	1987	1990	1993	2.0 MW
8/4	LARGE SCALE, HIGH ENERGY FAR-TERM SYSTEMS - IV	1992	1996	1999	15.0 MW
8/5	LARGE SCALE, HIGH ENERGY, FAR-TERM SYSTEMS - V	1995	2000	2003	1.0 GW
8/6	LARGE SCALE, HIGH ENERGY, FAR-TERM SYSTEMS - VI	2000	2004	2007	15.0 GW

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2003 (____) Table 5-2 lists the power demands (in rank order) of initiative subgroups as a function of approximate IOC date. The utility of the table is to demonstrate which subgroups or development plan steps can be captured by a given space power capability in a given year. For instance, a 10 kW space power capability achieved in 1988 would capture Subgroups 5/2, 9&11/2, and 4&6/3 in the case of an optimistic space plan, but not be required until 1996 to capture the same subgroups if a conservative space plan were to be implemented. The data can be used as a tool for space planning in two ways:

- 1. If a projection is made of the space power technology capability at a given time in the future, the subgroups of initiatives that the projected technology will be able to "capture" is determinable.
- 2. If a projection is made of the total space system capability (the specific initiative subgroups implemented) at a given time in the future, the space power technology capability that will be required is determinable.

With the aid of information on expected advancements in space power technology, an assessment can be made as to whether those planned advancements will meet the requirements objectives. If not, then the plans can be modified to attempt to meet those objectives.

5.1.3 Conclusions

If national space planning embarks on a policy of deploying large multipurpose satellites the needs of DoD and the civil sector will not in general drive space power requirements. However, DoD needs, in the long term, appear to parallel NASA needs because many of the civilian initiatives have similar applications.

Present NASA space planning policy does appear to be leaning towards the eventual implementation of a few very large multipurpose satellites which can be serviced on orbit and have indefinite lifetimes. The rationale for such a policy is that it makes maximum use of the unique

OPTIMISTIC PROGRAM IOC													
1982-1984		1985-1987		1988-1991		1992-1994		1995-1997		1998-2000			
CONSERVATIVE PROGRAM IOC													
1990-1992		1993-1995		1996-1998		1999-2001		2002-2004		2005-2007			
Subgroup	Power	Subgroup	Power	Subgroup	Power	Subgroup	Power	Subgroup	Power	Subgroup	Power		
2/1	1.0 kW	2/2	1,3 kW	5/2	2.2 kW	2/3	2.0 kW	4 & 6/4	20 kW	8/6	15 GW		
3/1	1.0 kW	3/2	5.0 kW	9 & 11/2	5. 0 kW	5/3	3.0 kW	8/5	1 GW				
5/1	1.7 kW	4 & 6 /2	5.0 kW	4 & 6/3	10. 0 kW	9 & 11/3	10.0 kW						
4 & 6/1	2.0 KW	1/2	25.0 kW	3/3	50. O kW	1/3	100.0 kW						
9 & 11/1	2.0 kW			7/2	50. O kW	8/2	210.0 kW						
1/1	4.0 kW			3/3	2.0 MW	3/4	300. 0 kW						
7/1	10. 0 kW					8/4	15.0 MW						
8/1	25.0 kW												
						l		 			l		

Table 5-2. Initiative Subgroup Power Demand vs. IOC Date

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capabilities of the Space Shuttle and leads as rapidly as possible to the exploitation of space for the immediate benefit of mankind. The large multipurpose satellites can be designed to service vast numbers of different users equipped with small, cheap user terminals. Some of the possible uses are personal communications, electronic mail, educational, and health and welfare TV, and personal navigation. The implication is that NASA may not be restricted to its traditional R&D role but might expand to commercial and private users by participating in commercial applications in providing orbital services as well as transportation.

The planning policy outlined above would result in the need for such space facilities as the Space Construction Base and the increased participation of man. The large satellites may be self-powered or may receive their power from separate space (the Space Power Module) or ground-based power plants.

DoD needs are somewhat different. The implementation of a few large undefended multipurpose satellites makes the space system fleet more vulnerable to enemy attack. The alternatives are either to provide active defense systems or to orbit a larger number of smaller satellites. The emphasis on survivability and anonymity in the case of DoD systems means that the DoD criteria for selection of space power system, subsystems and components may be different than the NASA criteria. For instance, at high power levels the DoD is more likely to select a more compact system than a solar cell/battery system with its large radar cross section. Solar cell design would also have to consider the susceptibility of solar cells to, for instance, intentional damage.

At this time, official DoD planning shows a less intense drive towards large multipurpose satellites than NASA planning. Nevertheless, DoD is presently initiating a well-funded study on the orbital assembly of large spacecraft (Reference 35) and a few high-powered systems are

already described in DoD planning documents. In addition, during the studies conducted by Aerospace for NASA in recent years, a large number of DoD initiatives were identified which require high power. Many public sector initiatives have a parallel military application and DoD space power technology requirements, in many ways, parallel the needs of NASA.

In the civil sector, the U.S.'s lead in the commercial application of space is partly based on satisfying individual users by providing relatively small, reliable, cheap satellites that can be clearly identified with a specific customer. It is not clear that foreign countries will be willing to relinquish the prestige associated with having their own satellite or be willing or able to fund their own large multipurpose satellites. The utility and economic benefits of such systems will have to be clearly demonstrated, either by NASA or by domestic civil users, before they are accepted by foreign users. This will probably result, in the near term, in a greater tendency for foreign users to lease time on U.S. satellites or continue to purchase single-purpose systems, rather than to purchase their own multipurpose systems.

It is concluded that within the context of the above arguments, the demands of civil users on space power requirements and technology can be subsumed within those of NASA. There are some differences between the power levels and the technology requirements of NASA and DoD in the near term which are likely to be less apparent in the far term.
5.2 MISSION/TRAFFIC POWER REQUIREMENTS

The power requirements derived by using the second approach described in Section 1.3 of this volume (and illustrated schematically in Figure 1-1) are summarized in Figures 3-1 through 3-16 of this volume (Volume I) and Figures 3-3 through 3-8 of Volume II to this report. Detailed life-cycle cost data are listed in the computer printouts contained in Volume III.

The yearly kW-hr space energy demands and the 15-year totals and 15-year averages for the period 1981-1995 are listed in Table 5-3 and plotted in Figures 5-9 and 5-10. Values for all three user groups are presented. It should be noted the contributions from the Satellite Solar Power Station (SPS) are not included since they tend to obscure the total picture.

Table 5-3. ENERGY DEMAND (1981-1995) - $(kW-hrs \times 10^3)$

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	CALENDAR YEAR													15 yr	15 yr				
ITEM	1979	1980	1961	1982	1983	1984	1965	1986	1987	1988	1989	1990	1991	1992	1993	1994	1995	(1981-95)	(1981-95)
NOMINAL BUDGET																			
NASA	4.1	31.5	89,5	156.4	203.5	259.1	267.Z	604.4	693.9	693, 3	2649.6	2825.6	2754.3	2776.2	2870.4	3010.6	6842.5	26696.5	1779.8
DoD	-	85,7	174.7	198.7	364.3	411.0	527.0	1059.5	1226.7	1313.6	1451.4	1924.7	1925.6	2326.9	2949.7	3312.1	3319.0	22487.9	1499.2
CIVIL	52.7	137.4	201.6	237.0	309.3	321, 2	364.0	288.8	409.0	451,9	465,0	\$12.8	617.9	594. B	534.2	463.3	434.4	6257.9	417.2
NASA & DoD & CIVIL	56.8	254.6	465.8	459.2	877. 7	991.3	1158. z	1952.7	2329.6	2458.8	4566.0	5263.1	5300.8	5697.7	6354.3	6786.0	10595.9	55442.3	3696, 2
OPTIMISTIC BUDGET																			
NASA	4.1	31.5	69.5	432, 2	558.1	613.7	2790.3	2976.0	3144.3	3143.7	3917.1	3896.0	5007.3	2312.8	2801, 1	2862.5	3370.6	37919.3	2528,0
DoD		85,7	174.7	198.7	443.1	450.4	1039.6	1288.3	1613.0	3166.6	3846.2	4392.7	6769.5	7325.2	6525.0	10344.7	10305.3	57884.9	3859.0
CIVIL	65,0	149.7	251.4	309.8	465.5	547,7	675.5	655.8	815.8	892.0	922.0	96	1074.0	1985.7	1111.1	1089.8	1107.4	11948.0	796, 5
NASA & DoD & CIVIL	69.1	266,9	515.6	940.7	1466.7	1611.8	4505.4	4920.1	5573.1	7202, 2	8687.3	9233. Z	12850, 8	10723.7	J0437 . Z	14297.0	14783.3	107752.2	7183,5



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Figure 5-9. Total Space Energy Demand (NASA, DoD & Civil) 1985 to 1995 - Nominal Budget

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1985 to 1995 - Optimistic Budget

6. COST/BENEFIT ANALYSIS

6.1 BACKGROUND

In order to provide funding for the reoriented study effort, emphasis was placed primarily on setting up the data to enable cost/benefit analyses to be performed. The stated request by NASA was for a "market survey" for space power, or estimates of the demands for space power on a yearly basis together with estimates of the yearly expenditures on space power subsystems. The data listed in Figures 3-1 through 3-16 are intended to satisfy this request by delineating a breakout of the yearly kilowatt demands, total program costs, power system weights and cost, and solar array weights and costs, under given budgetary constraints.

The cost/performance program (Reference 29) which was used to generate subsystem weights and costs has the capacity to identify and separate space power subsystem subassemblies and components. Accordingly, for the purposes of this study, the solar cell subassembly was selected for cost/benefit analysis because it was thought that changes in solar cell technology funding can be of great significance as large solar arrays are brought into development. Further candidates for cost/benefit analysis such as battery technology and others can of course be postulated.

The method developed in this study permits varying a number of input parameters, such as budget goals, specific missions selected for inclusion in the traffic models, traffic rates and technology levels.

6.2

METHOD OF ANALYSIS

The steps used in the cost/benefit analysis consist of the following:

- 1. Derive permissible yearly funding for advancing the technology of space power systems.
- Base calculations on probable demand from traffic model and associated life-cycle cost projections.
- 3. Identify candidate subsystem elements for receiving technology advancement funding.
- 4. Establish a figure-of-merit range of values.

6.3 GROUND RULES AND ASSUMPTIONS

- 1. Constant 1977 dollars.
- 2. Nominal budget conditions forecasted.
- 3. Only budget projections for NASA are used.
- 4. Large satellite power modules are separately identified and examined.
- Continuing technology advancements projected for large capacity solar power systems.
- 6.4 ANALYSIS
- 6.4.1 Traffic Model Data

The following data were extracted from Appendix VII, Volume III to this report.

- 1. Total power subsystem cost (1979-1995)
 - (a) NASA = \$758 million (excluding large power modules)
 - (b) NASA large power modules = \$703 million*

* Data through 1996 included for large modules because over half their capacity is launched in that year.

2. NASA 17-year averages (excluding large systems)

- (a) 11 satellites per year
- (b) Total of 22.2 kW per year
- (c) Power system costs = \$45 million per year
- 3. Satellite averages (excluding large systems)
 - (a) Power level = 2 kW
 - (b) Power subsystem weight = 395 lb
 - (c) Solar array weight = 110 lb
 - (d) Solar array cost = \$1.1 million
 - (e) Solar array cost/lb = \$10,000
 - (f) Launch cost/lb to synchronous orbit = \$4000*
 - (g) Watts per pound of solar array = 18
- 4. Large Power Modules
 - (a) Solar array cost = \$371 million
 - (b) Solar array weight = 70370 lb
 - (c) Solar array cost/lb = \$5300
 - (d) Power = 6275 kW
 - (e) Watts per pound of solar array = 90
 - (f) Subsystem cost = \$703 million
 - (g) Subsystem weight = 147000 lb
 - (h) Subsystem cost/lb = \$4780

6.4.2 Calculations

Based on data in Section 6.4.1 it can be seen that substantial savings are achieved in solar array cost per pound -- \$10000 vs \$5300 -- when the extremely large solar power modules are brought into operation. Such results stem principally from efficiencies of scale as power system arrays become larger. The important savings, however, come from the advancement of solar array technology whereby watts per pound are estimated to increase five-fold. Potential savings resulting from such technology advances can be calculated as follows:

* Assumes power systems placed in synchronous orbit.

			POTENTIAL SAVINGS						
			Maximum	Minimum*					
-	Weight saved, 350000-70000	=	280000	105000	(lb)				
-	Solar array cost saved, 350000 lb x \$4000/lb Less 70000 lb x \$5300/lb Net savings	=	\$1400 <u>- 371</u> 1029	\$770 <u>- 371</u> 399	(millions)				
-	Launch vehicle cost savings, 280000 lb x \$4000/lb*	=	1120	420					
-	Total Savings		\$2149	<u>\$819</u>	(millions)				

A figure-of-merit can be used to derive permissible funding amounts for technology R and D. The first step is to adopt an estimate of savings based on the above data -- let us assume \$1 billion, for example. Next, pick a figure-of-merit that is reasonable -- the lower the figure the higher the R and D funding will be and vice versa. If 5 and 10 are used to establish a range the resulting total permissible fundings would be 200 and 100 million dollars, respectively; i.e., total savings divided by the two figures-of-merit. The final step would be to spread such funds over a period sufficiently early to provide technology demonstrations before incorporation in the satellite power system designs -- prior \Leftrightarrow 1987 for the 250 kW module and prior to 1991 for the 2000 kW system. A conservative method would result in funding at approximately \$10 million per year during the 1980's -- possibly less in the earlier period and more in the later 80's to coincide with start of development of the large 2000 kW system.

6.5 OBSERVATIONS

From these preliminary results the following observations can be made:

1. To achieve the considerable savings demonstrated by the analysis, power subsystem technology must be advanced.

 ^{*} Assumes weight is reduced to 175000 lb because of size efficiencies with no technology advance, viz., total weight saved would be 175000 -70000 = 105000.

- 2. The solar arrays exceed 50% of electrical subsystem cost for the large power modules.
- 3. Based on historical data and the results of the above preliminary analysis, the solar array is an attractive candidate for such technology advancement.
- Other components of the power subsystem, such as power control and conditioning equipment, also appear to be potential candidates.
- 5. The battery subsystem is less important from a cost pointof-view; however, it is important from the standpoint of weight and its effect on launch costs.
- 6. If a figure-of-merit of 5 to 10 is assumed, R&D expenditures for solar array technology could be funded at 10 to 20 million dollars per year in the 1980's.

7. CONCLUSIONS AND RECOMMENDATIONS

7.1 CONCLUSIONS

The funding allocated to this study permitted only a general sweep through the subject with many decisions having to be made without in-depth consultation with the appropriate authorities. For this reason, the results should be considered representative rather than definitive. At the same time, broad conclusions can be drawn which would still be valid even if individual items in the data base diverged somewhat from the values shown.

It can be concluded that there is a monotonically increasing need for both higher power levels (kilowatts) and higher energy levels (kilowatthours) into the foreseeable future, whatever future is assumed. (That is, whether single-purpose satellites continue to be deployed or whether there is a movement towar s large multipurpose satellites; whether the space budget continues much as it is today or whether increased funding is allocated for space activities.)

In the lase of large multipurpose systems, Table 5-1 shows a need for primary mission power levels up to 10 kW in the late 1980's. However, the method of deployment of these large systems necessitates on-orbit construction facilities and support missions which themselves require power levels of 25 kW or more, justifying the need for both low altitude and high altitude 25 to 50 kW power modules. A particularly favored DoD radar system could demand a primary power level of 50 kW in the late 1980's.

In the mid to late 1990's, of course, the large scale, high energy systems (for instance, the Solar Power Satellite) could generate a need for very high power levels, possibly up to 15 GW. This corresponds, in turn, to a high total space power energy requirement in the same time period, as illustrated in Figure 5-10.

If a future is assumed which emphasizes single-purpose satellites, absolute power levels may be lower up to the late 1980's; nevertheless,

individual satellites requiring power levels of 5 kW are likely. Total energy demands will be essentially the same for both futures, reaching levels of over 5×10^6 kW-hrs/year (for a nominal budget) to about 10×10^6 kW-hrs/ year (for an optimistic budget) by 1990. If such systems as the Satellite Power Satellite (SPS) are planned for, the power levels and the total energy demands will be the same for both approaches. Total energy demands could reach 15×10^6 kW-hrs/year by the mid 1990's. Present proposals for an IOC date of 1998-2000 for a 5 GW SPS call for an extensive development program which includes Phase C and D development of geosynchronous flight articles as early as the mid 1980's. If such a program is followed, much of the space power technology developments for other systems can be subsumed within the SFS activity.

Whichever future is foreseen, the simple example shown in Section 6 illustrates a potential for sizeable cost savings, particularly if large power modules are to be employed and funds for continual R&D efforts are budgeted. The method outlined for analyzing such cost benefits (that is, in the context of an overall space program mission and traffic model) can be applied to a variety of alternative futures and also to a number of technologies other than solar array technology.

7.2 RECOMMENDATIONS

Because more up-to-date planning information (both for NASA and for DoD) has recently become available, it is recommended that the computer techniques and procedures developed herein should be used to examine a wider range of possible futures and to derive specific cost benefit break-even points. The methodology should also be applied to other technology areas to determine how to best distribute total technology expenditures. This is particularly important for the types of satellite systems now being planned which will require much longer development times than the types of satellites built today. Relatively high figures of merit must be assured to justify R&D expenditures because of the longer time delay between expenditure



and payoff. This is particularly important in programs such as, for instance the SPS program.

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