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SONIC-BOX METHOD EMPLOYING LOCAL MACH NUMBER  
FOR OSCILLATING WINGS WITH THICKNESS

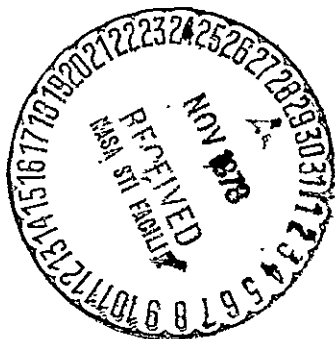
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# SONIC-BOX METHOD EMPLOYING LOCAL MACH NUMBER FOR OSCILLATING WINGS WITH THICKNESS

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## SUMMARY

A computer program has been developed to account approximately for the effects of finite wing thickness in the transonic potential flow over an oscillating wing of finite span. The program is based on the original sonic-box program of Rodemich and Andrew and has been extended to include the effects of the swept trailing edge and the thickness of the wing. Account for the non-uniform flow caused by finite thickness is made by application of the local linearization concept. The thickness effect, expressed in terms of the local Mach number, is included in the basic solution to replace the coordinate transformation method used in the earlier work. Calculations were made for a delta wing and a rectangular wing performing plunge and pitch oscillations, and the results were compared with those obtained from other methods. An input guide and a complete listing of the computer code are presented.

## INTRODUCTION

In reference 1, the sonic-box method computer program was developed for calculation of unsteady transonic flow aerodynamics for oscillating planar wings with unswept trailing edge by approximating the wing planform with a matrix of square boxes. Later, it was extended to include the swept trailing edge and control surfaces in reference 2. The sonic-box method uses a doublet velocity potential as the basic solution to satisfy the linearized transonic flow, unsteady small-perturbation velocity-potential equation with the associated boundary conditions.

In references 3 and 4, the wing thickness effect is partially recovered by the inclusion of local Mach number in the governing equation for the

unsteady transonic flow. It uses the concept of local linearization to reduce the nonlinear small-perturbation equation to a linear one with non-constant coefficients. This is further reduced to a linear equation with constant coefficients by an appropriate coordinate transformation. This final equation and the associated boundary condition in the transformed space become identical to those treated in the physical space by Rodemich and Andrew in reference 1. The numerical results for the wing with thickness were obtained by adopting the sonic-box method in the transformed space. Because of the assumptions made in deducing the governing equation to a manageable form, this technique is applicable only to relatively thin wings. That is, the local mean Mach number on the wing surface must not be very different from unity. Further, it is assumed that there is no flow separation and no strong shock waves on the wing surface.

The computer programs developed in references 1, 2, and 3 use the least-square method to fit some of the input data, such as wing deflection or steady Mach number distribution on the wing, and to fit the computed velocity potential with a form of pre-determined polynomial surface for the subsequent calculation of the unsteady pressure and the generalized aerodynamic force coefficients. The computer program described in reference 4 adopts the natural cubic spline for fitting calculated velocity potential and the spline-surface for fitting input modal deflections and Mach number distribution instead of the polynomial-surface fitting used in references 1, 2, and 3. The codes in references 3 and 4 allow the computation of generalized aerodynamic force coefficients for wings of zero and finite thickness; the swept trailing edges are allowed but not the control surfaces.

The computer program presented in this report is developed according to the "alternate technique" described in reference 5. The coordinate transformation technique as used in references 3 and 4 fails when the mean local Mach number on the wing becomes very different from unity. In order to avoid this problem, an alternate technique was proposed in reference 5 to approximately account for the thickness effect, expressed in terms of mean local Mach number on the wing, by including it directly in the basic doublet solution to replace the coordinate transformation. The computer program thus developed is smaller

than that of reference 4 and the amount of computation required has also been reduced.

In general, the basic assumptions and limitations applied to the computer code in reference 4 also apply to the present code. However, the present formulation avoids the difficulties associated with the artificial wake and wing-surface fold-over due to multivalued transformation which limits the usefulness of the coordinate transformation formulation of reference 4. The zero thickness wing portion of the computer code is unchanged from that of reference 4. Input is identical in both codes and the output differs very little between them.

#### SYMBOLS

b	reference length (dimension = L)
$C_p$	pressure coefficient
exp, e	exponential function
i	$\sqrt{-1}$
k	reduced frequency, $\omega b/U_\infty$
L	unit of length
$L_{ij}$	generalized aerodynamic force coefficient
M	local Mach number
T	unit of time
$U_\infty$	reference velocity (freestream), (dimension = L/T)
x, y, z	dimensionless Cartesian coordinates (reference length = b)
$\theta_{ij}$	phase angle of $L_{ij}$
$\tau$	maximum thickness to root chord ratio
$\phi_0$	magnitude of oscillatory dimensionless small perturbation velocity potential
$\omega$	angular velocity (dimension = radian/T)
( ) <sub>le</sub>	subscripts denote quantity at leading edge
( ) <sub>te</sub>	subscripts denote quantity at trailing edge

## METHOD

The computer program described in reference 4 is based on the coordinate transformation technique to reduce the locally linearized equation with non-constant coefficients for nonzero thickness wing at sonic speed to a linear one with constant coefficients. This linear equation with the associated boundary conditions can, then, be solved with sonic-box method. When the mean local Mach number on the wing becomes very different from that of the free-stream, the transformation may become multivalued and consequently an artificial wake or wing-surface fold-over may be created in the transformed space. This technique fails once it happens. In order to avoid this problem, an alternate technique was proposed in reference 5 to approximately account for the thickness effect, expressed in terms of mean local Mach number on the wing, by including it in the basic doublet solution.

The governing equation for unsteady transonic small perturbation velocity potential is

$$\varphi_{0yy} + \varphi_{0zz} - M^2(2ik\varphi_{0x} - k^2\varphi_0) = 0, \quad (1)$$

where

$$\varphi_0(x,y,z) = \varphi(x,y,z,t) \cdot e^{-ikt},$$

which is also equation (1) of reference 4.

The basic solution for equation (1), representing a point doublet oriented parallel to the z-axis at the origin and satisfying the required condition at infinity for a small finite region on the wing where the value of M, the Mach number, is considered to be constant, may be written as

$$\varphi_0 = \begin{cases} 0, & x \leq 0, \\ \frac{ik}{2\pi} \frac{zM^2}{x^2} \exp \left\{ -\frac{1}{2} ik \left[ x + \frac{M^2(y^2+z^2)}{x} \right] \right\}, & x > 0, \end{cases} \quad (2)$$

in which  $M$  is regarded as a parameter. This solution satisfies equation (1) only in a small finite region of the wing; so the solution may be considered to be of the locally linearized form.

The only quantity in the program of reference 4 requiring modification is the velocity influence coefficient for the wings with thickness. It is presently written as

$$A = \frac{ik}{2\pi} M^2 \iint_E \frac{1}{(x-\xi)^2} \exp \left\{ -\frac{ik}{2} \left[ (x-\xi) + \frac{M^2(y-\eta)^2}{(x-\xi)} \right] \right\} d\xi d\eta \quad (3)$$

$$= \frac{ik}{2\pi} M \iint \frac{1}{u^2} \exp \left[ -\frac{ik}{2} \left( u + \frac{v^2}{u} \right) \right] dudv \quad (4)$$

where

- $H$  = length of the box side
- $k$  = reduced frequency
- $M$  = mean local Mach number
- $i = \sqrt{-1}$
- $l = kH$
- $E$  = box at  $(\xi, \eta)$
- $u = (x-\xi)/H$
- $v = M(y-\eta)/H$

The value of the velocity influence coefficient computed in the sonic-box computer program is with  $M = 1.0$  in equations (3) and (4). Under this condition, the velocity influence coefficient is function of the wing geometry only. For  $M \neq 1.0$ , it becomes function of the Mach number also. The value of the modified velocity influence coefficient required in this alternate technique to account for the wing thickness effect may be evaluated from the table computed for  $M = 1.0$  condition for the same reduced frequency.

To evaluate the modified velocity influence coefficient for this alternate technique, one may do the following:

1. take the average value of the mean local Mach number at the center of the receiving,  $(x, y)$ , and sending,  $(\xi, \eta)$ , boxes,

2. multiply the spanwise distance between these two box centers by the value of the average Mach number,
3. interpolate the modified velocity influence coefficient from the original table for  $M = 1.0$  with the value of the modified spanwise distance,  $v$ ,
4. multiply this value by the mean local Mach number at the center of the sending box.

The rest of the computation remains practically unchanged except that the computation in the transformed space is totally eliminated.

#### COMMENTS ON THE PROGRAM

The velocity potential influence coefficients for a wing of zero thickness at a given frequency are only a function of the geometry. However, in addition to the geometry, they are also a function of the local Mach number distribution for the nonzero thickness wing under present formulation. It may be possible to perform the integration in equation (3) analytically with a new formula or with that already in the earlier program with some approximation. No attempt was made to derive the totally new formulation. One of the approximate methods which was studied but not implemented in the present program is to substitute the local Mach number,  $M$ , in the integrand of equation (3) with  $(1-\epsilon)$ , where  $\epsilon$  is a positive or a negative small number. After expanding the exponential function involving  $\epsilon$  term and neglecting all  $\epsilon^2$  or higher terms, one obtains an approximate form of the integrand, for a doublet at the origin and  $z = 0$ , as follows:

$$\left(\frac{1}{x^2} + i\epsilon k \frac{y^2}{x^3}\right) \cdot \exp\left[-\frac{ik}{2}\left(x + \frac{y^2}{x}\right)\right]. \quad (5)$$

The exponential function in equation (5) is the same as that used in the case for  $M = 1.0$  and the routines in the earlier sonic-box computer program may be utilized to perform the integration. Due to its complexity, and the additional computer storage and time required, this approximate method was not adopted to generate the new velocity influence coefficient matrix with the Mach number effect. Instead, it is interpolated from the velocity influence



coefficient matrix for the zero thickness wing as described in the preceding section. The Mach number appearing in the exponential function in equation (3) is only associated with the distance between receiving and sending points and it is regarded as to modify the effective distance between these two points. Therefore, the average Mach number is used to maintain its interchangeability. Another Mach number in equation (3) is regarded as to modify the doublet strength. Since the integration is performed over the surface of the sending box, it is logical to use the Mach number at that point. This simplification in coupling the Mach number effect enables a reduction of the size of the computer code and the computation time. The computed results appeared to be reasonable under the assumptions of small perturbation theory and local linearization concepts.

In the present formulation, it implies as in the coordinate transformation formulation (ref. 4) that the Mach number variation in the spanwise direction is not large. The accuracy of these methods decreases when a large Mach number variation in spanwise direction exists. The present method, however, does not fail abruptly as does the coordinate transformation method when spanwise variation of Mach number becomes large enough to cause multi-valued transformation and hence fold-over of wing-surface.

Since no smoothing has been applied on either the input data or any computed values in the data fitting process during the computation, the calculated unsteady pressure coefficient distribution may not be smooth and should be used with caution. In order to use it, the computed pressure coefficient should be put through a smoothing process such as the smoothing portion of the two-dimensional cubic-spline fitting routines in the present program. The pressure coefficient is obtained by differentiation of a set of numerical values whereas the generalized aerodynamic force coefficient is obtained by integration. Since integration itself is a smoothing process, the resulting generalized aerodynamic force coefficient is considered to be acceptable within the bounds of the accuracy of the numerical techniques and the adequacy of the sonic-box method. The option of data smoothing is not provided in the three-dimensional spline-surface fitting process used in the present code for

input data such as wing deflections and mean local Mach number. The spline-surface is required to go through all input points.

## RESULTS

Sample calculations are made for a delta wing and a rectangular wing oscillating in plunge (Mode 1) and in pitch about the apex (Mode 2). The mean angle of attack is zero and the freestream is at sonic speed.

### Delta Wing

The delta wing considered here is a flattened elliptic cone of aspect ratio 1.5 and thickness-to-root-chord ratio  $\tau = 0.1$ . Convergence with respect to the number of boxes along the root chord for the generalized force coefficients ( $L_{ij}$ ) due to plunge and pitch about the apex, at a reduced frequency of  $k = 0.2$ , is shown in figure 2. The maximum numerical difference within the applied range of 15 and 30 boxes along the root chord is about 4 percent, and the trend of convergence with and without thickness is essentially the same. Based on the results shown in figure 2, it appears that the gain in convergence by using a large number of boxes to represent the wing is not obvious as compared with a fortuitous selection of the number of boxes to use. The numerical fluctuation in the convergence plot is largely caused by the box arrangement along the wing leading edge which, in turn, is dependent on the number of boxes selected for use along the wing root chord. Contribution from the partial boxes along the leading edge has been taken into account, but the fluctuation still exists.

The variation of each force coefficient, using 30 boxes along the root chord, versus the reduced frequency is plotted in figure 3. The results from figure 7 of reference 4 are also shown. The numerical difference between the results for wings with and without thickness is very small, generally less than one percent. This is a result of the Mach number, at each box-center used in the computation, lying within the narrow range of 0.92 and 0.98 in chordwise direction and remaining constant in spanwise direction (see fig. 8

of ref. 4). However, the thickness effect on flutter speed can be significant (ref. 6). The results for the case with thickness obtained from the present method and that of reference 4 are not very different.

### Rectangular Wing

The rectangular wing considered here has aspect ratio 2.0 and a biconvex (circular arc) airfoil with thickness-to-chord ratio  $\tau = 0.0521$ . The variation of each force coefficient, using 20 boxes along the root chord, versus the reduced frequency is plotted in figure 4. The results obtained from the present method, and from references 4 and 7, are included in the figure. The thickness effect on the rectangular wing is seen to be slightly larger than that on the delta wing. This is probably caused by the wide range of Mach number variation (fig. 6) on the rectangular wing, even though the thickness ratio is only 0.0521 for the rectangular wing against 0.1 for the delta wing.

The present method predicts values higher than either Landahl's results (ref. 7) for the zero thickness case or the results of reference 4 for the non-zero thickness case. The difference of the generalized aerodynamic force coefficients for the nonzero thickness case between the results obtained from the present method and that of reference 4 is quite large. This might be caused by the difference in interpretation of the effective distance between the sending and the receiving points in the present method and the coordinate transformation method used in reference 4. It is felt, however, that the interpretation used in the present program is more physically sound than that used in reference 4. The phase angle predicted by the sonic-box method at very low reduced frequency becomes meaningless when the magnitude of any force coefficient approaches to zero with decreasing reduced frequency (for example, see figs. 4(b) and 4(d)). This is due to numerical inaccuracy and not to any inadequacy of the method.

The steady-state pressure coefficient obtained from reference 8 for the rectangular wing considered here is shown in figure 5(a) for the chordwise (x-direction) distribution and in figure 5(b) for the spanwise (y-direction) distribution. The corresponding Mach numbers at the box-centers, interpolated

from the fitted spline-surface, are plotted in figures 6(a) and 6(b). The interpolated values deviate from the input data more near the leading edge than near the trailing edge. This probably was caused by the use of more dense spacing of input points near the leading edge as compared with those near the trailing edge in chordwise direction and by the lack of input points near the leading edge in spanwise direction, especially in the in-board portion of the wing. A better fit than that shown in figures 6(a) and 6(b) may be obtained by using more evenly spaced input points than those shown in figures 5(a) and 5(b).

#### CONCLUDING REMARKS

A sonic-box method computer program is presented for the application of a local linearization concept capable of accounting approximately for wing thickness effects in unsteady sonic flow. The thickness effect, expressed in terms of the local steady Mach number, is directly included in the basic solution. The local doublet strength is adjusted from the sonic flow condition to that for the local flow, and the governing equation is reduced to the one used in the original sonic-box method for zero thickness wings. Thus, the original sonic-box method concept can be used directly to treat nonzero thickness wings.

Convergence of the numerical results with respect to the number of boxes used in representing the wing planform seemed to depend more on the arrangement of the boxes along a swept leading edge than on the total number of boxes used, even though the partial boxes along the leading edge were included in the computation. For a wing with unswept leading edge, the use of a small number of boxes (say, 15 to 20 along the root chord) appeared to be sufficient to obtain results that were essentially converged.

When the input data require spline-surface fitting, the input points must be selected in such a way that they are as uniformly spaced as possible to avoid locally-concentrated large errors. A smoothing option for the two-dimensional cubic-spline has been included in the present program, but it was

not utilized in the sample runs shown in this report. Since the box method itself is numerical in nature, the distribution of calculated values may not always be smooth; and it may become necessary to perform the smoothing before any gradients are evaluated.

Based on the sample runs made, the contribution due to thickness was not found to be very large in comparison with the results calculated from the coordinate transformation method. Due to the lack of reliable experimental data, it is rather difficult to assess the validity of the present approach in accounting for thickness effects.

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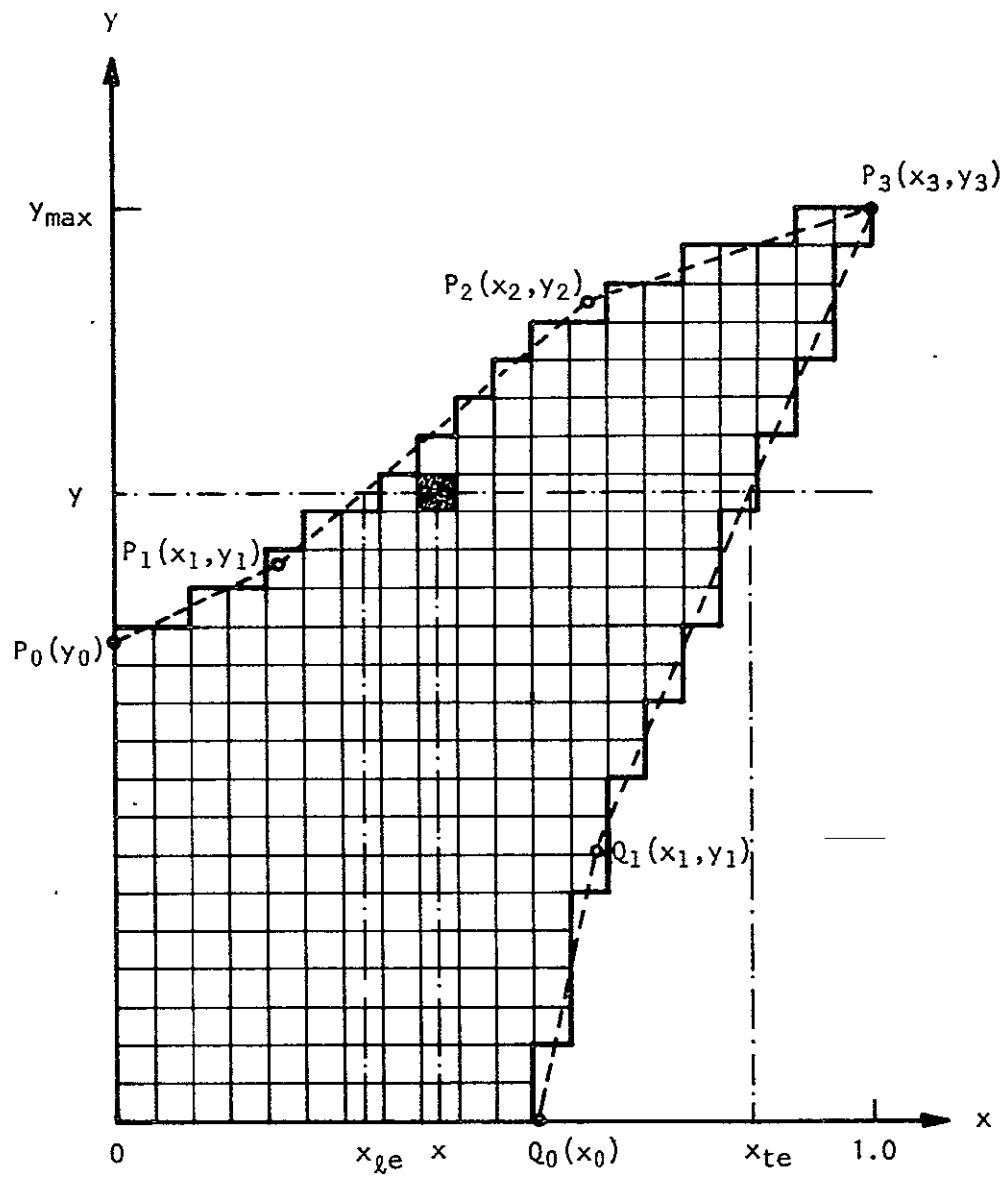
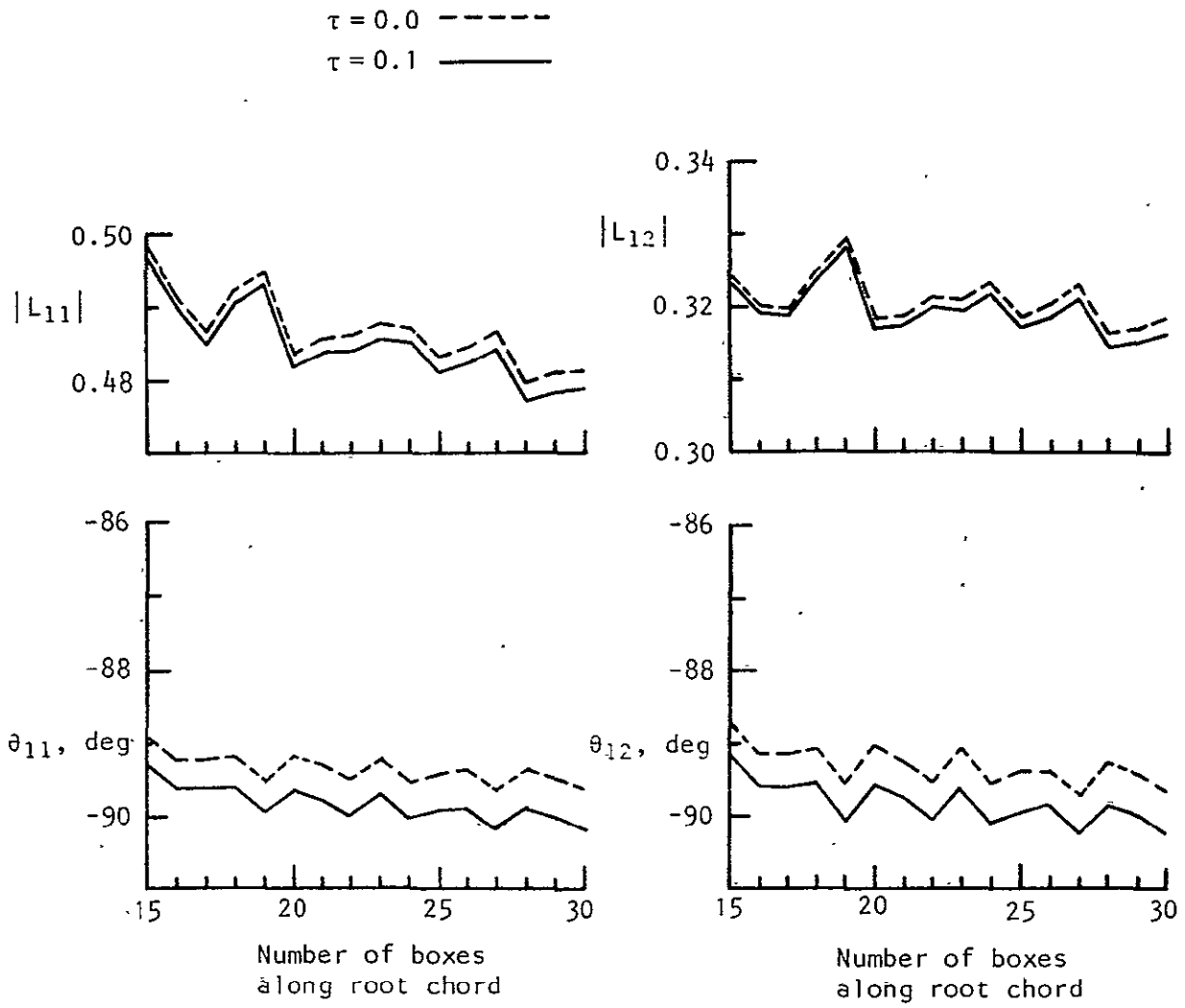


Figure 1. - Half wing geometry.

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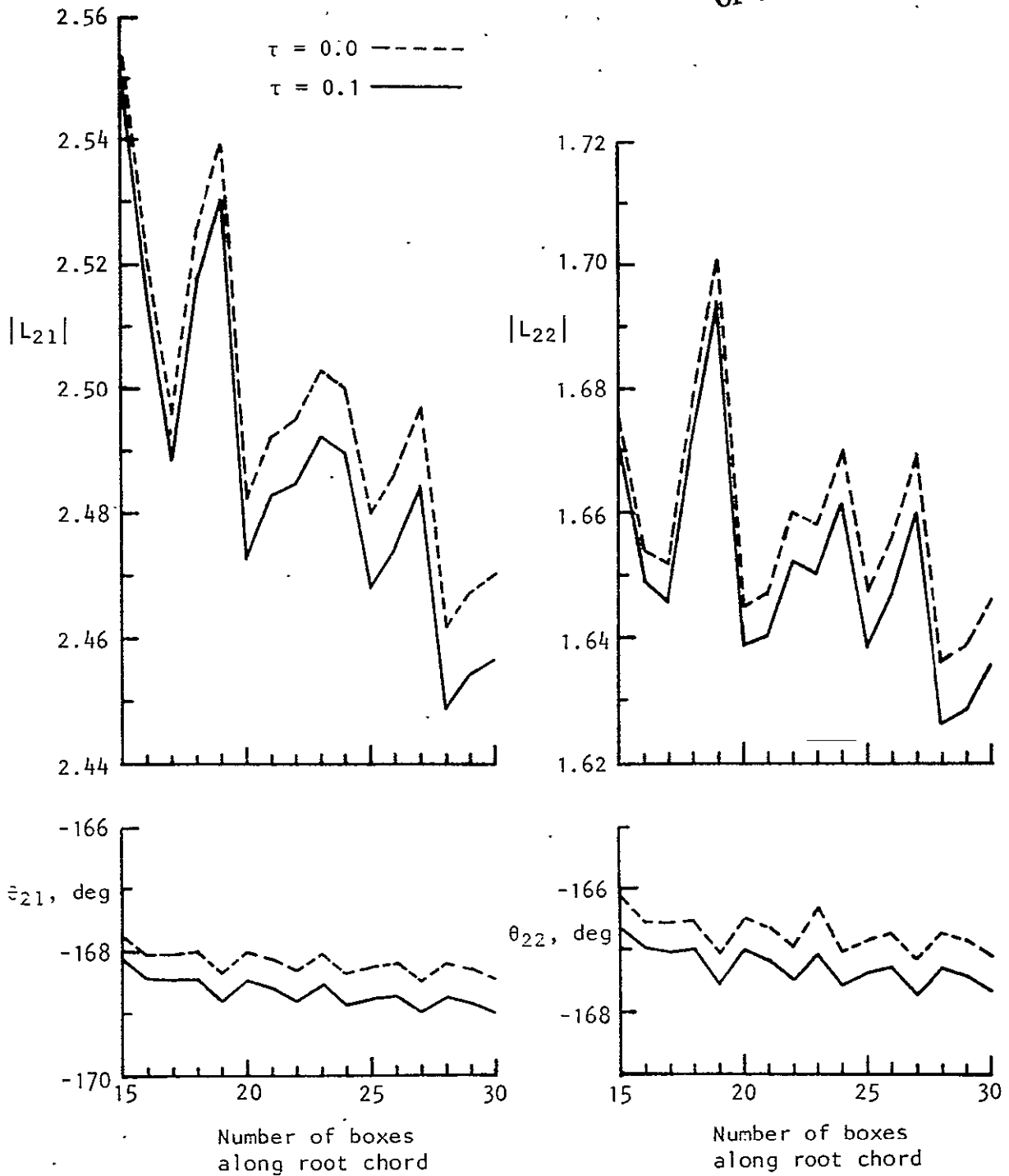
(a) Lift due to plunge.

(b) Moment due to plunge.

Figure 2. - Convergence of force coefficients due to plunge and pitch for delta wing of aspect ratio 1.5 at reduced frequency 0.2.



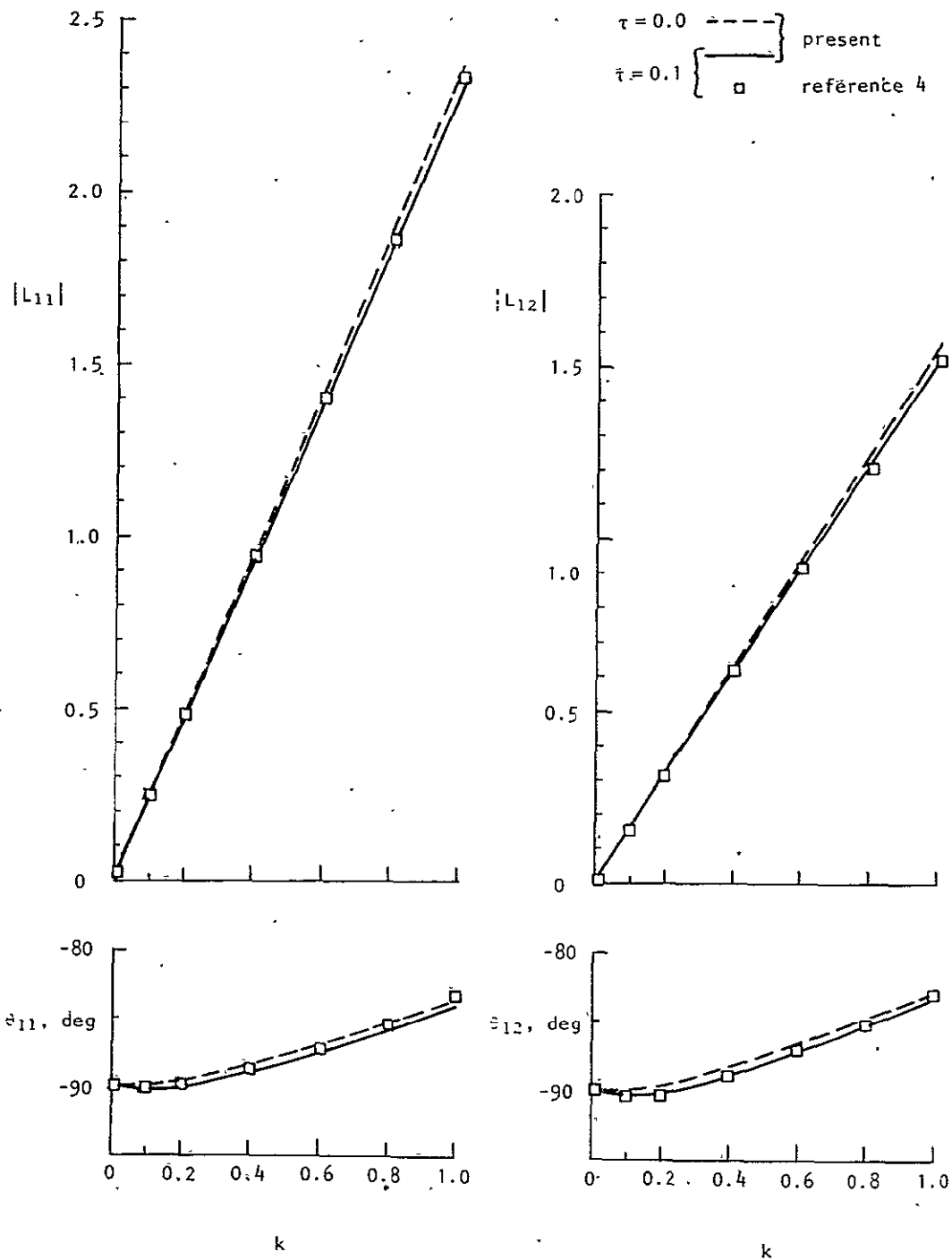
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(c) Lift due to pitch.

(d) Moment due to pitch.

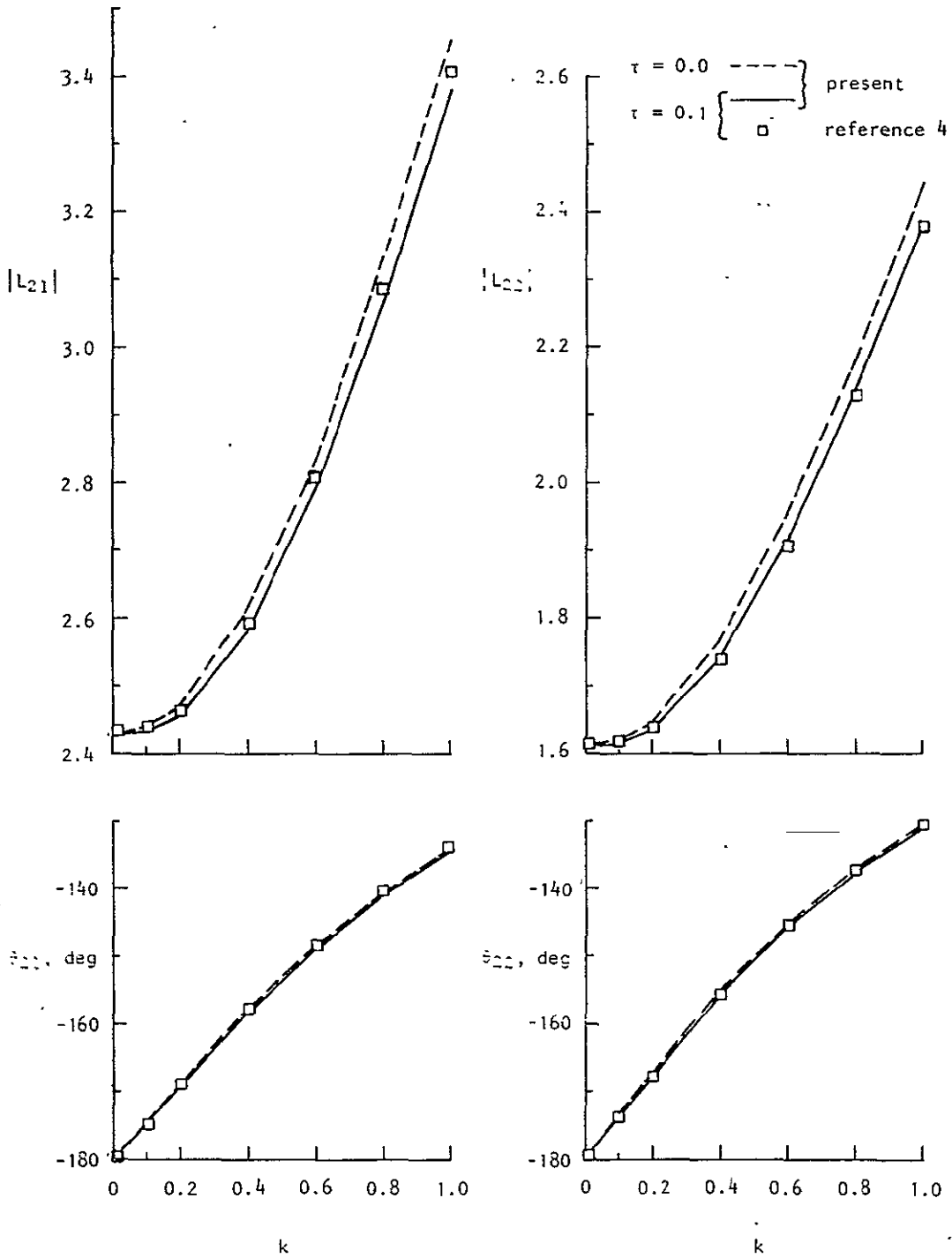
Figure 2. - Concluded.



(a) Lift due to plunge.

(b) Moment due to plunge.

Figure 3. - Force coefficients due to plunge and pitch for delta wing of aspect ratio 1.5 with 30 boxes along root chord.



(c) Lift due to pitch.

(d) Moment due to pitch.

Figure 3. - Concluded.

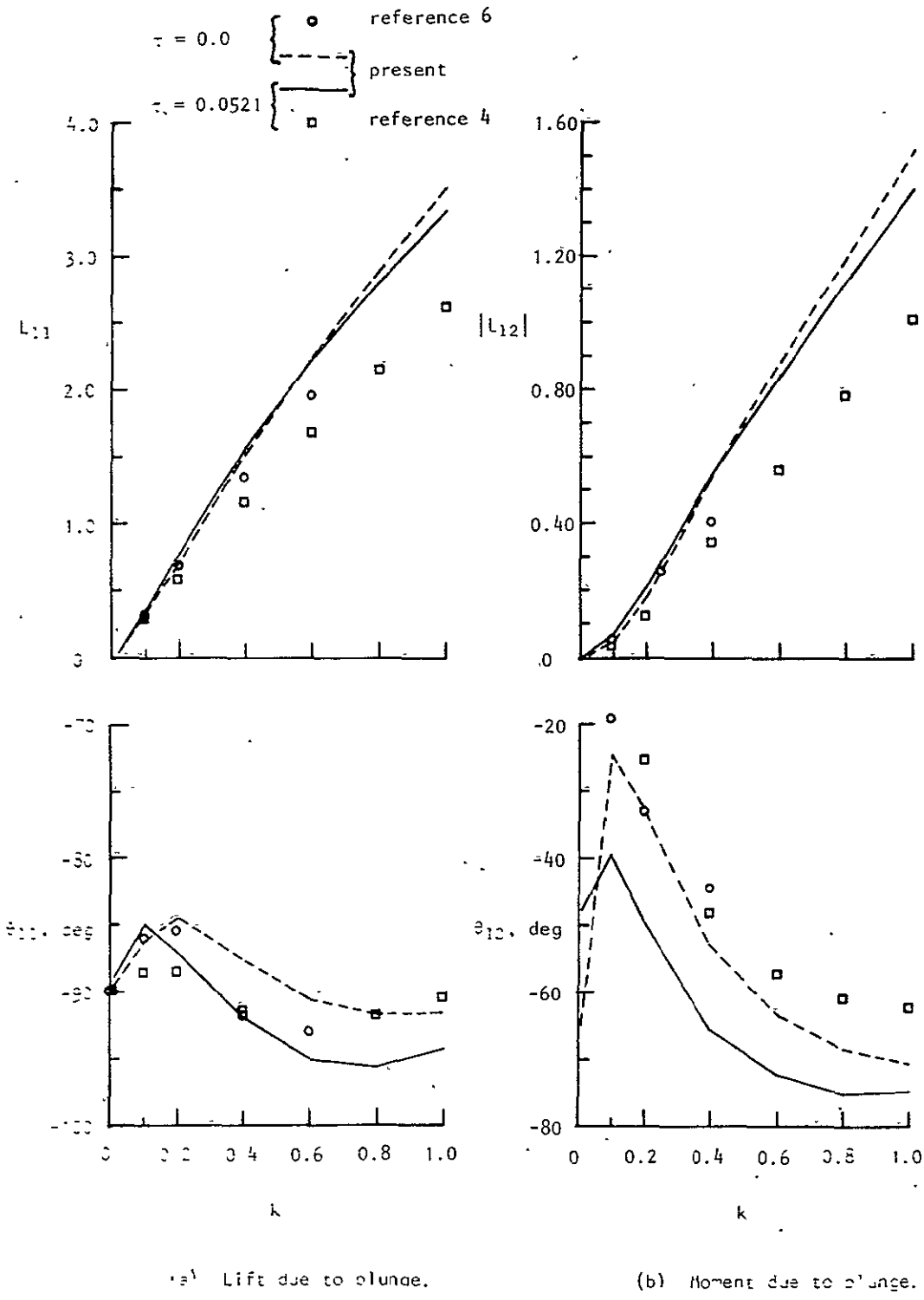
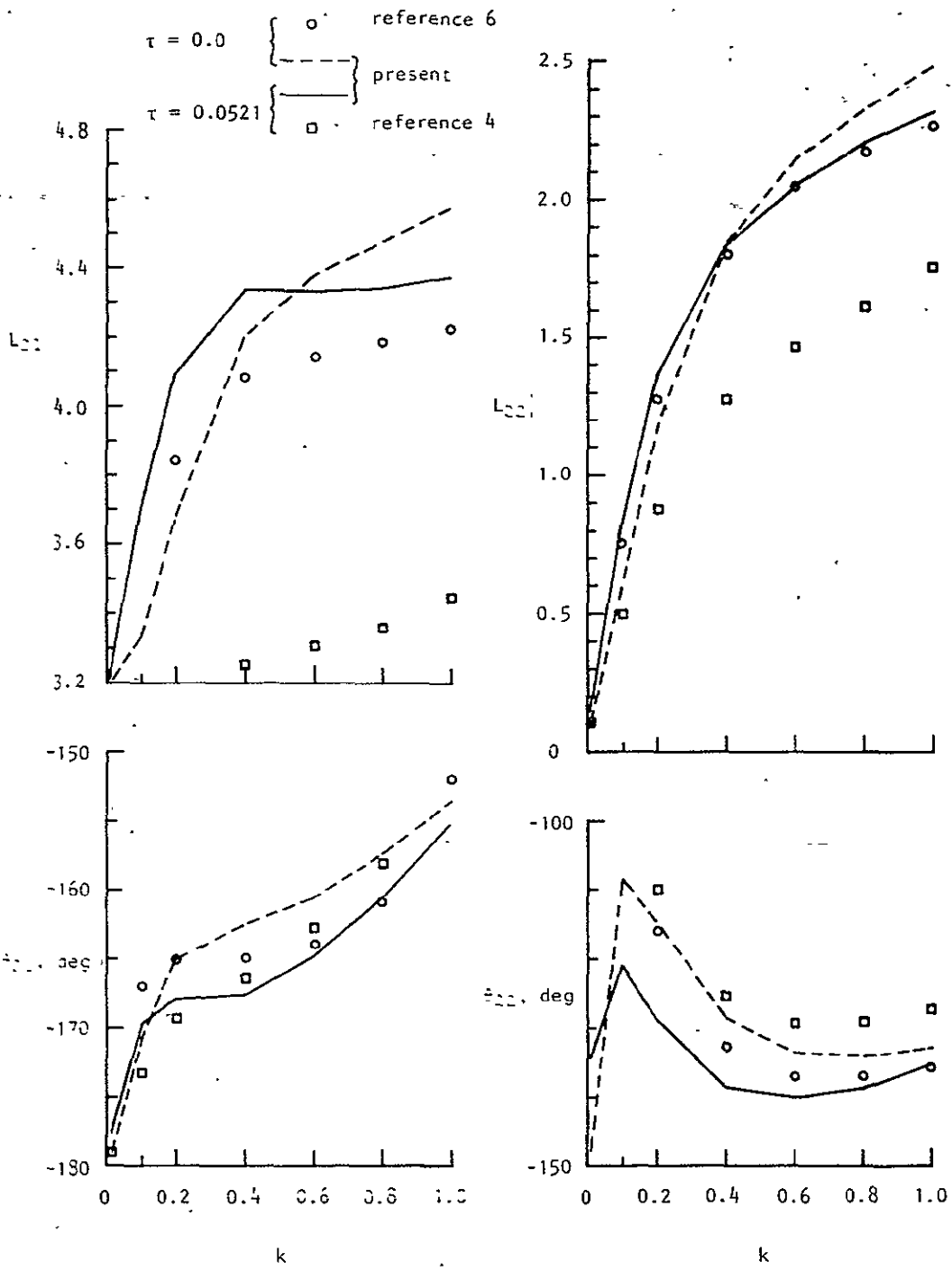


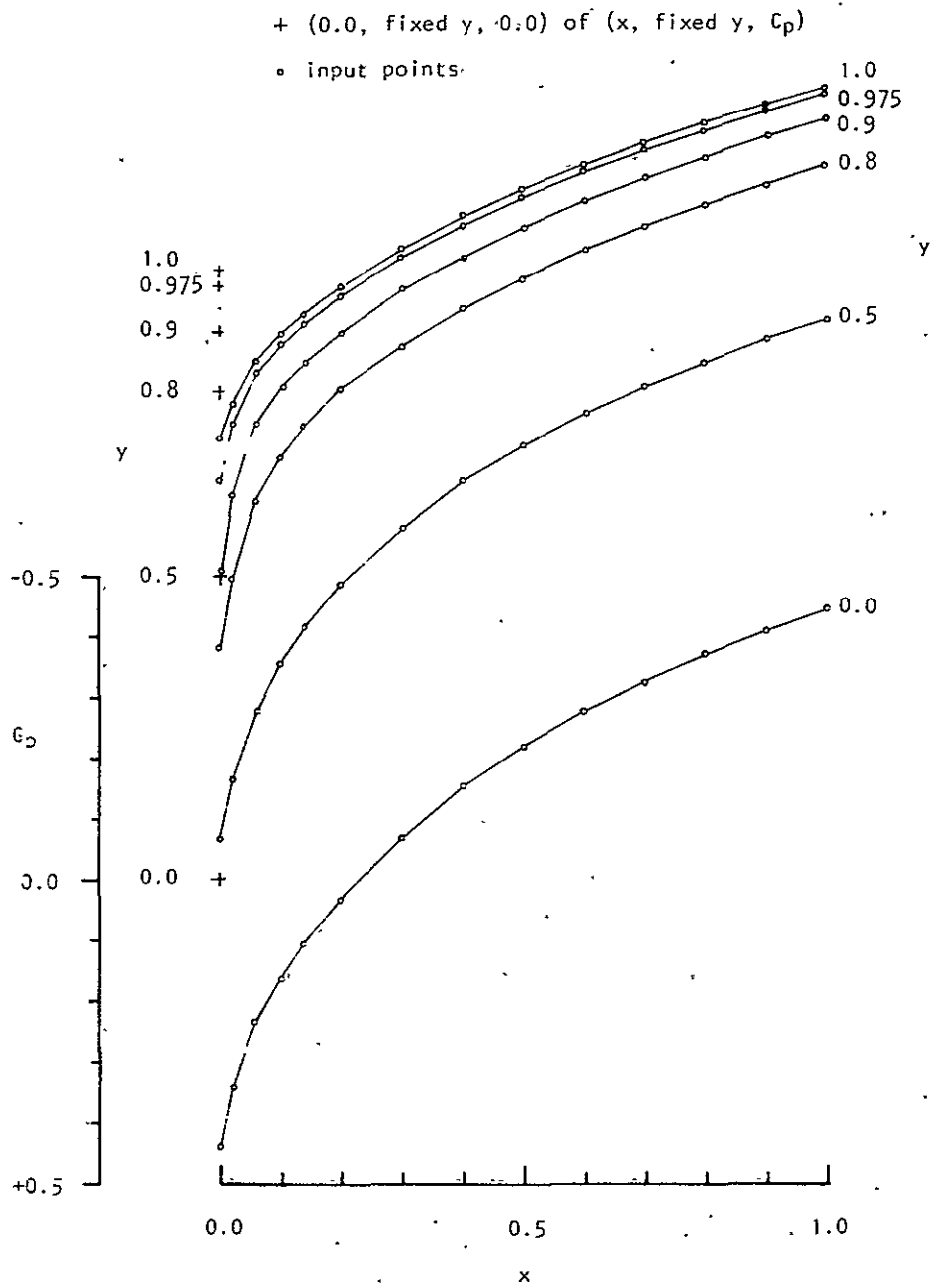
Figure 4. - Force coefficients due to plunge and pitch for rectangular wing of aspect ratio 2.0 with 20 boxes along root chord.



(c) Lift due to pitch.

(d) Moment due to pitch.

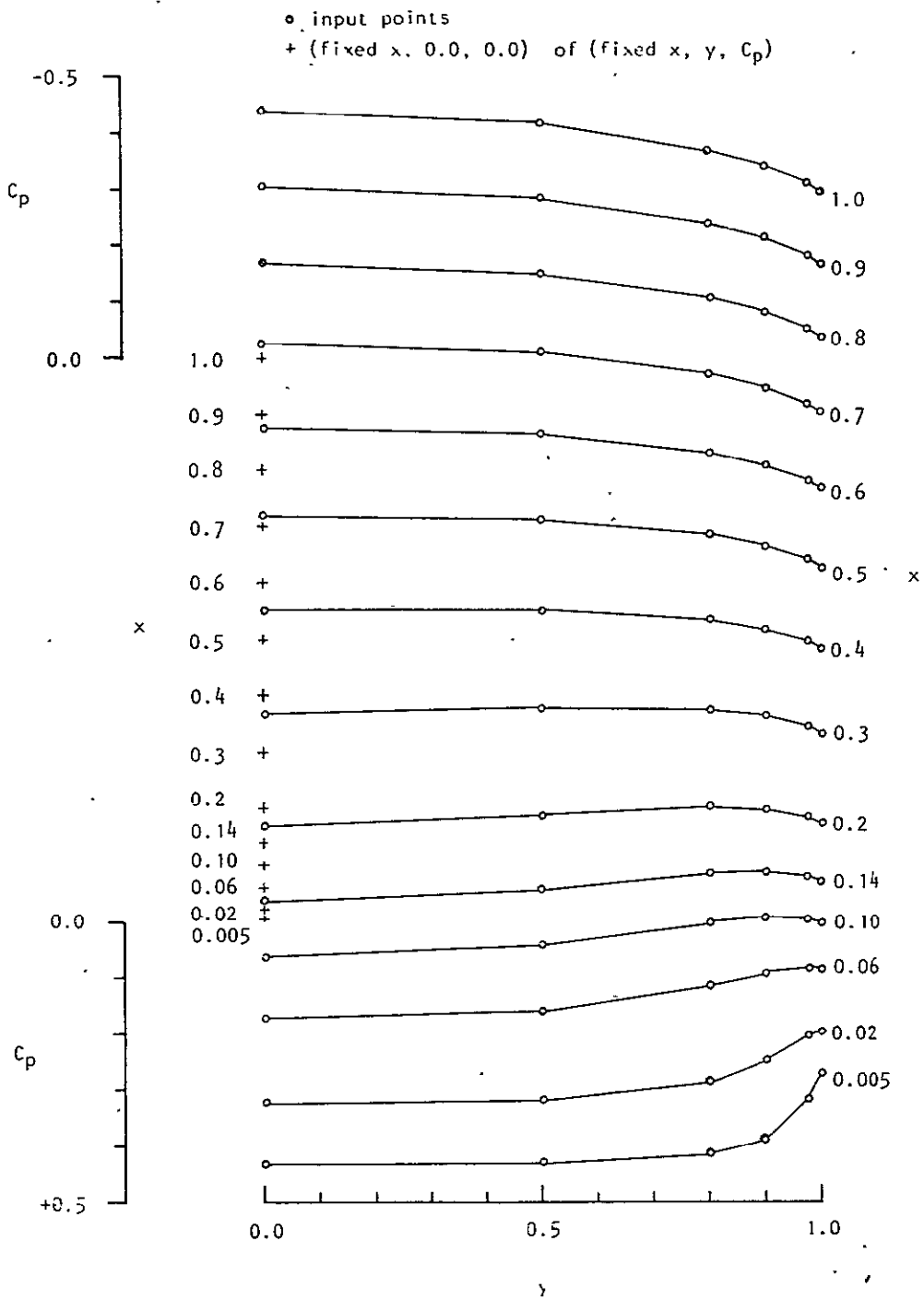
Figure 4. - Concluded.



(a) Chordwise distribution.

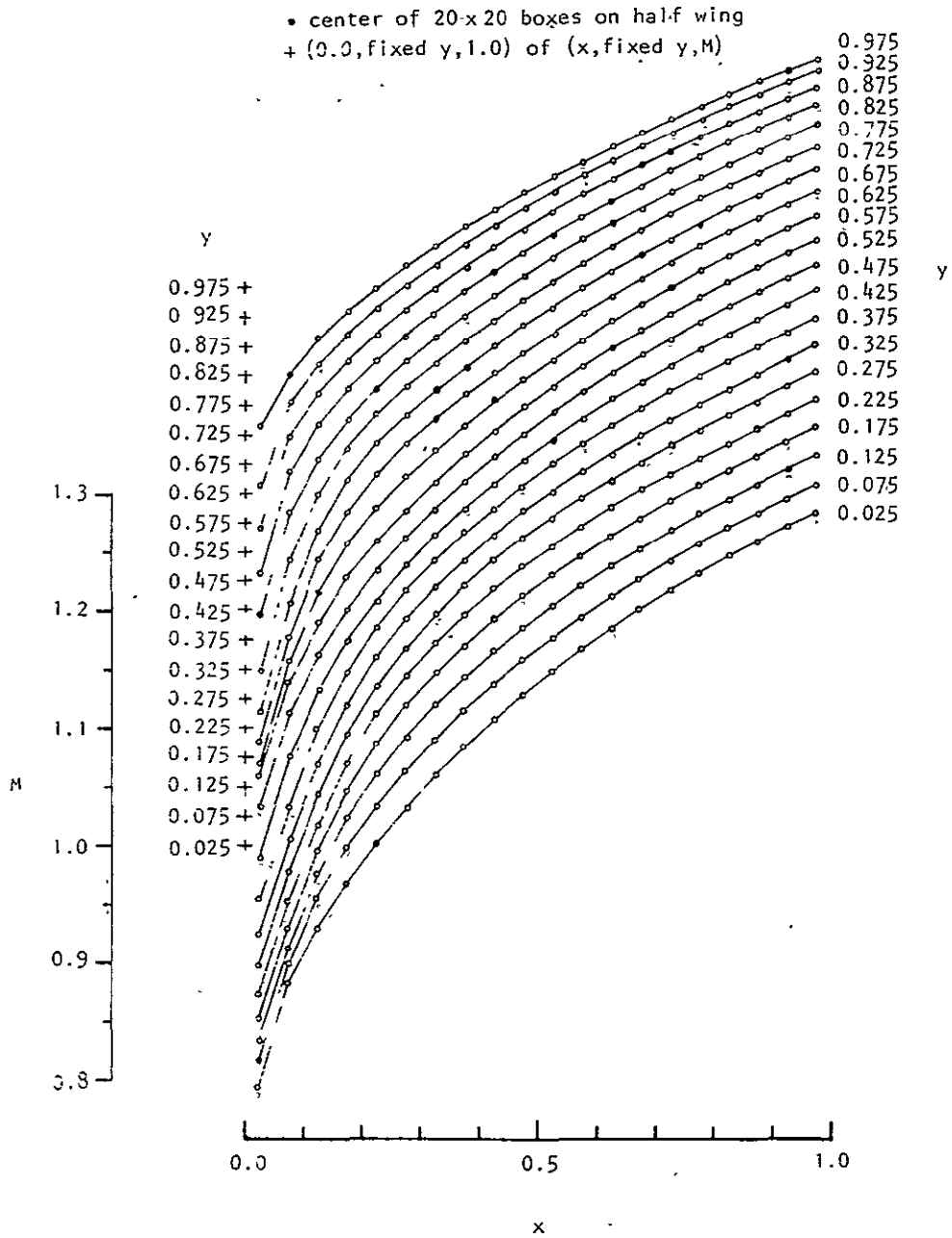
Figure 5. - Input steady state (mean) pressure coefficient on rectangular wing of aspect ratio 2.0 and thickness ratio 0.0521 (reference 8).

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(b) Spanwise direction.

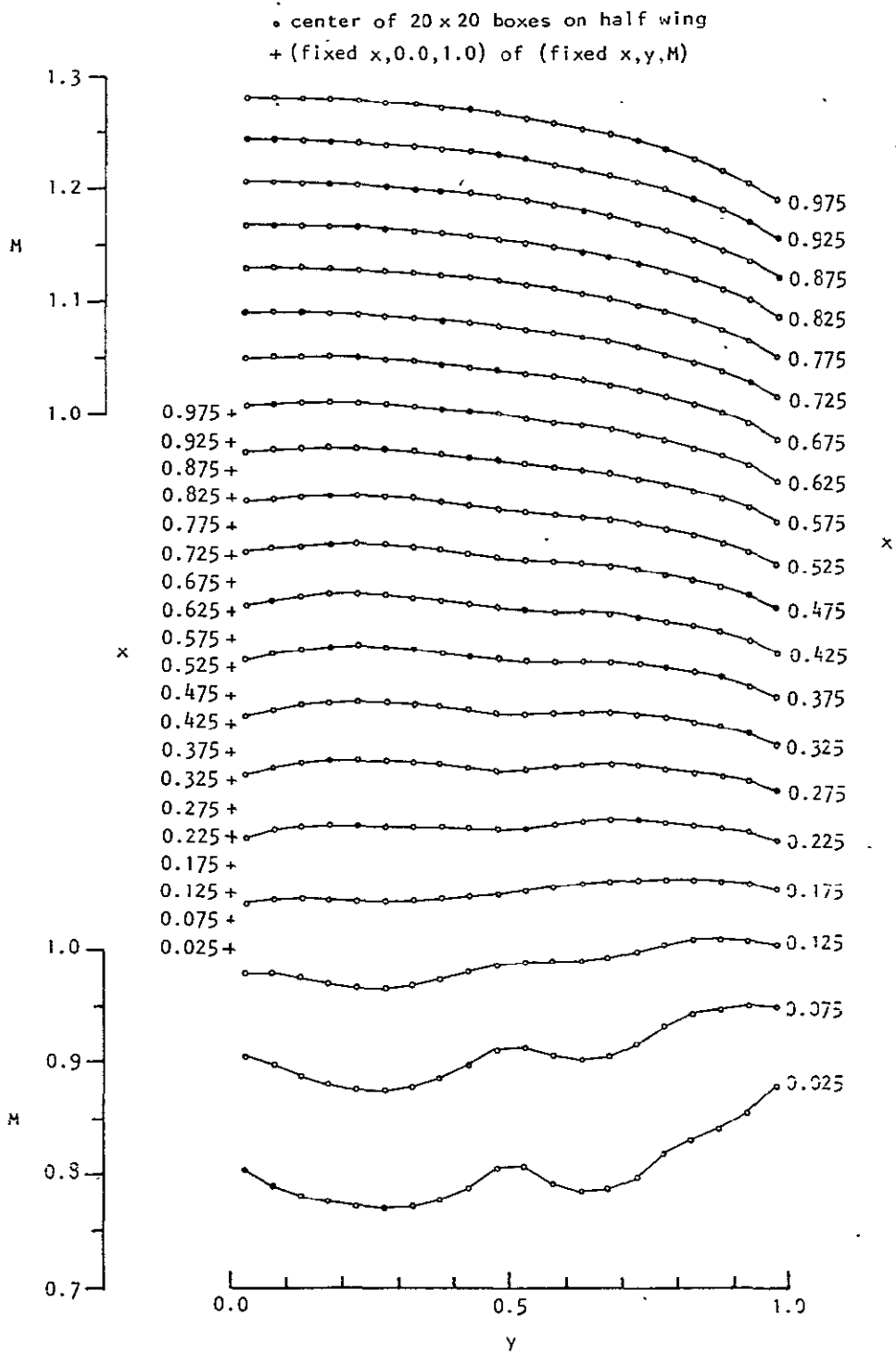
Figure 5. - Concluded.



(a) Chordwise distribution.

Figure 6. - Computed steady state (mean) Mach number on rectangular wing of aspect ratio 2.0 and the thickness ratio 0.0521.





(b) Spanwise distribution.

Figure 6. - Concluded.

## APPENDIX

### COMPUTER PROGRAM

The computer program listed in this appendix is dimensioned to handle a maximum of 30 boxes, either in chordwise or spanwise directions, in approximating the wing planform. The maximum numbers of leading and trailing edge segments are, respectively, 7 and 2 per semispan. The program can handle up to 3 wing deflection mode shapes. The maximum number of points used in spline-surface fitting is 100, so the maximum number of input points to describe the wing deflections and the Mach number or pressure coefficient distribution is also 100. These limitations can easily be increased by changing the dimensions of the corresponding variables in the computer program.

In order to activate the smoothing option in two-dimensional cubic-spline data fitting, it is required that a two-digit fixed point number be assigned to the last argument, NSMOS, of subroutine SPLN1. The right digit is for the control of the number of smoothings desired; and the left-digit is for pre-interpolation, zero for omitting pre-interpolation and non-zero for including pre-interpolation. The pre-interpolation is a process to increase the number of known points to be used in the interpolation by inserting an additional point between every successive pair of input points in the original set.

## Input Guide

Data are input through the subroutine DATRD using the one dimensional array DA with a size of 1005. The allowable maximum number for some of the input data as indicated below may be changed if the dimensions of the corresponding storage array and computational operations are also changed accordingly. Subroutine DATRD initializes DA(1) through DA(22) to blank, the weighting factors in DA(104), DA(108), ---, DA(500) to 1.0, and the remaining portion of the DA array to 0.0. Consequently, these are the default values. The layout of the array DA(k) as it is presently used is similar to that in reference 4 and is as follows:

- 1-7: Title
- 8-12: Not used
- 13-19: Mode title
- 20-22: Not used
- 23: Frequency, (cycle/sec)
- 24: Overall length of wing in streamwise direction, (ft or meter)
- 25: Speed of sound of the freestream, (ft/sec or meter/sec)
- 26: (0) - indicates the frequency is the first one for a new wing  
(1) - indicates the frequency is the additional one for the same wing
- 27: Number of boxes in streamwise direction (maximum 30)
- 28: Number of deflection modes (maximum 3)
- 29: Number (m) of segments of leading edge per semispan to be given, excluding segment from origin to  $y_0$  ( $m_{\max} = 7$ )
- 30-44: Coordinates of points on the leading edge, (ft or meter)  
(in sequence of  $y_0, x_1, y_1, x_2, y_2, \dots, x_m, y_m$ ),  $m_{\max} = 7$
- 45: Number (n) of segments of trailing edge per semispan to be given, (default: unswept trailing edge),  $n_{\max} = 2$
- 46-48: Coordinates of points on the trailing edge, (ft or meter)  
(in sequence of  $x_0, y_1, x_1$  for  $n = 2$ ,  
or  $x_0$  (only) for  $n = 1$ ,  
no input for  $n = 0$ ;  
last trailing edge point coincides with the last leading edge point and is set internally)

- 49: Number of boxes allowed for upstream influence (if this location is left blank or assigned a zero, it will assume  $DA(49)=DA(27)$  and in no case  $DA(49)>DA(27)$  is allowed).
- 50: (0) - indicates to calculate cases with and without thickness effect  
 (1) - indicates to calculate case without thickness effect only  
 (2) - indicates to calculate case with thickness effect only
- 51: Indicator to suppress calculation of potential for a mode  
 (0) - no suppression  
 (1) - suppression
- 52-53: Coefficients of the deflection polynomial (in the sequence of  $a_0$  and  $a_1$ )
- 54-70: Not used\*
- 71-72: Coefficients of the Mach number distribution polynomial (in the sequence of  $a_0$  and  $a_1$ )
- 73-95: Not used\*
- 96: Indicator of the type of wing thickness effect input  
 (1) - pressure coefficient  
 (2) - Mach number
- 97: Number of points at which pressure coefficient or Mach number to be given
- 98: Number of points on which deflections to be given
- 99-100: Not used\*
- 101-500: Deflection data for a maximum of 100 points (in the sequence of  $x$ ,  $y$ , deflection and weighting factor)
- 501-700: Not used\*\*
- 701-1000: Pressure coefficient or Mach number data for a maximum of 100 points (in the sequence of  $x$ ,  $y$  and pressure coefficient or Mach number)

The remaining part of DA array is used for the control of intermediate results print out. When the latter is desired, a non-zero positive integer number should be entered at locations in the DA array corresponding to the information from the one particular subroutine that is needed.

- 1001: CBA: for wing deflection (DRED)  
 A=1, for NEW=1 } spline-surface fitted results  
 B=1, for NEW=2 }  
 C - not applicable
- 1002: BA: for wing upwash (WVAL)  
 A=1, - upwash  
 B - not applicable
- 1003: FEDCBA for velocity potential (BOXP and BOXPO)  
 A=1, for NEW=1 } velocity potential  
 B=1, for NEW=2 }  
 C=1, for NEW=1 } influence coefficient and solution matrices  
 D=1, for NEW=2 }  
 E=1, for NEW=1 } pressure coefficient  
 F=1, for NEW=2 }
- 1004: A: for Mach number (MRED)  
 A=1 - spline-surface fitted results
- 1005: DCBA: for wing shape (SHAPE and PLNFM)  
 A=1, for NEW=1 } distributions of box, box area, leading and  
 B=1, for NEW=2 } trailing edges  
 C=1 - Mach number at box centers  
 D - not applicable

The format of the input data card is (A1, A5, 16, 6A10, A8). The first field is for the control of clearing the data array, DA, for a new wing (+) and the control to indicate the end of the set of data (-). The second field is the indicator for the type of data, either numeric (blank) or alphanumeric (ALPHA). The third field is the designator for the relative location in the data array of the first number to follow in the fourth field. If this field is left blank, or a zero is entered, the execution will be terminated. The fourth and fifth fields are for five consecutive input data each occupying 12 columns plus 8 blank columns at the end. All the fixed point numbers are right-adjusted and the decimal point for the floating point number must be included. If an input datum is left blank, no change at the storage location for that particular datum in the data array will occur unless the set of the input data is for a new wing.

Those storages currently not used in array DA marked with \* are reserved for future improvements in the method used for the functional form of data input. Those marked with \*\* are reserved for the case where large numbers of data input points for deflections or Mach numbers are required.

## Sample Input

A typical input data deck set-up for an aspect ratio 1.5 delta wing having an elliptic lateral cross-section with 10% thickness ratio performing plunge and pitch about its apex are given below.

The input format is (A1, A5, I6, 6A10, A8).

Card 1: title of the case under consideration.

Card 2: title of the first mode of deflection.

Card 3: first frequency (cycle/sec), centerline chord length (ft), reference velocity (ft/sec).

Card 4: number of boxes along the centerline chord, number of deflection modes, number of total leading edge segments of the wing.

Card 5: spanwise coordinate (ft) of the first section of the leading edge, chordwise and spanwise coordinates (ft) of the next section (the sequence is  $y_0, x_1, y_1$  -- e.g., see figure 1).

Card 6: first mode of deflection  $f = 1.0$   
the " - " sign indicates the end of the group of data cards to be read at this stage.

Card 7: title of the second mode.

Card 8: second mode of deflection  $f = 0.1x$ .

Card 9: identification of the type of input regarding the wing thickness effect (Mach number for this case), number of points on the wing this information to be given.

Cards 10 to 69:

chordwise and spanwise coordinates (ft) of a point on the wing, and the Mach number at this point.

the " - " sign on the last card indicates the end of the group of data cards to be read at this stage.

Cards 70 and 71:

additional frequencies for the same wing, one card is read in at one time.

Card 72: blank card to make an exit from the computer.

The card images are as follows:

	1	2	3	4	5	6	7	8
	1234567890123456789012345678901234567890123456789012345678901234567890							
♦ALPHA	ASPECT RATIO 1.5 DELTA WING (TAU=0.10)							1
ALPHA	13PLUNGE							2
	23	0.159154941		10.0		1000.0		3
	27		30	2		.1		4
	30		0.0	10.0		3.75		5
	52		1.0					6
ALPHA	13PITCH ABOUT ROOT LEADING EDGE X=0.0							7
	52		0.0		0.1			8
	96		1		60			9
	701		0.1			0.140232		10
	704		0.3			0.135125		11
	707		0.5			0.132175		12
	710		0.7			0.129943		13
	713		0.9			0.128084		14
	716		1.3			0.124980		15
	719		1.7			0.122340		16
	722		2.1			0.119963		17
	725		2.5			0.117746		18
	728		2.9			0.115627		19
	731		3.3			0.113564		20
	734		3.9			0.110510		21
	737		4.5			0.107428		22
	740		5.1			0.104243		23
	743		5.7			0.100872		24
	746		6.3			0.097215		25
	749		6.9			0.093129		26
	752		7.5			0.088395		27
	755		7.9			0.084697		28
	758		8.3			0.080342		29
	761		8.7			0.074970		30
	764		9.1			0.067825		31
	767		9.3			0.063062		32
	770		9.5			0.056823		33
	773		9.7			0.047661		34
	776		9.9			0.029651		35
	779		1.7	0.5		0.122340		36
	782		3.3	1.0		0.113564		37
	785		4.5	1.0		0.107428		38
	788		5.7	1.0		0.100872		39
	791		6.9	1.0		0.093129		40
	794		8.3	1.0		0.080342		41
	797		9.5	1.0		0.056823		42
	800		4.5	1.5		0.107428		43
	803		6.3	2.0		0.097215		44
	806		7.5	2.0		0.088395		45
	809		8.7	2.0		0.074970		46
	812		9.7	2.0		0.047661		47
	815		8.3	2.5		0.080342		48
	818		9.7	3.0		0.047661		49
	821		2.5	0.5		0.117746		50
	824		3.9	0.5		0.110510		51
	827		5.1	0.5		0.104243		52
	830		6.3	0.5		0.097215		53
	833		7.5	0.5		0.088395		54
	836		9.1	0.5		0.067825		55
	839		9.9	0.5		0.029651		56
	842		5.1	1.5		0.104243		57
	845		6.3	1.5		0.097215		58
	848		7.9	1.5		0.084697		59
	851		9.1	1.5		0.067825		60
	854		9.9	1.5		0.029651		61
	857		5.7	2.0		0.100872		62
	860		6.9	2.5		0.093129		63
	863		9.5	2.5		0.056823		64
	866		9.9	2.5		0.029651		65
	869		8.3	3.0		0.080342		66
	872		9.1	3.0		0.067825		67
	875		9.5	3.5		0.056823		68
	878		9.9	3.5		0.029651		69
	23	1.591549407						70
	23	6.366197628						71
								72

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OF POOR QUALITY

Sample Output

ASPECT RATIO 1.5 DELTA WING (TAU=0.10)

30 BOXES ALONG ROOT CHORD

ROOT CHORD LENGTH = 10.00 FT

REDUCED FREQUENCY = .010

FREE STREAM VELOCITY = 1000.00 FT/SEC

FREQUENCY = 1.592E-01 CYCLE/SEC

MODE NO. 1 PLUNGE

MODE NO. 2 PITCH ABOUT ROOT LEADING EDGE X=0.0

GENERALIZED FORCES (NO THICKNESS EFFECT)

MODES	PPES.	DEFL.	REAL PART	IMAG PART	ABS. VALUE	PHASE ANGLE
1	1		2.15396E-06	-2.42783E-02	2.42783E-02	-89.9949
1	2		-1.69639E-07	-1.61159E-02	1.61159E-02	-90.0006

GENERALIZED FORCES (NO THICKNESS EFFECT)

MODES	PPES.	DEFL.	REAL PART	IMAG PART	ABS. VALUE	PHASE ANGLE
2	1		-2.42788E+00	-2.44689E-02	2.42800E+00	-179.4226
2	2		-1.61162E+00	-1.81349E-02	1.61173E+00	-179.3553

MODE NO. 1

MODE NO. 2

GENERALIZED FORCES (WITH THICKNESS EFFECT)

MODES	PPES.	DEFL.	REAL PART	IMAG PART	ABS. VALUE	PHASE ANGLE
1	1		-1.00531E-05	-2.43535E-02	2.43535E-02	-90.0237
1	2		-1.29338E-05	-1.61534E-02	1.61534E-02	-90.0459

GENERALIZED FORCES (WITH THICKNESS EFFECT)

MODES	PPES.	DEFL.	REAL PART	IMAG PART	ABS. VALUE	PHASE ANGLE
2	1		-2.43541E+00	-2.33020E-02	2.43552E+00	-179.4518
2	2		-1.61539E+00	-1.68848E-02	1.61548E+00	-179.4011

ASPECT RATIO 1.5 DELTA WING (TAU=0.10)

30 BOXES ALONG ROOT CHORD

ROOT CHORD LENGTH = 10.00 FT

REDUCED FREQUENCY = .100

FREE STREAM VELOCITY = 1000.00 FT/SEC

FREQUENCY = 1.592E+00 CYCLE/SEC

MODE NO. 1

MODE NO. 2

GENERALIZED FORCES (NO THICKNESS EFFECT)

MODES					
PPES.	DEFL.	REAL PART	IMAG PART	ABS. VALUE	PHASE ANGLE
1	1	3.6426E-04	-2.4214E-01	2.4214E-01	-89.9138
1	2	1.20006E-04	-1.60604E-01	1.60604E-01	-89.9572

GENERALIZED FORCES (NO THICKNESS EFFECT)

MODES					
PPES.	DEFL.	REAL PART	IMAG PART	ABS. VALUE	PHASE ANGLE
2	1	-2.47556E+00	-2.45153E-01	2.43792E+00	-174.2287
2	2	-1.60948E+00	-1.81827E-01	1.61972E+00	-173.5545

MODE NO. 1

MODE NO. 2

GENERALIZED FORCES (WITH THICKNESS EFFECT)

MODES					
PPES.	DEFL.	REAL PART	IMAG PART	ABS. VALUE	PHASE ANGLE
1	1	-7.33272E-04	-2.42506E-01	2.42507E-01	-90.1732
1	2	-1.03563E-03	-1.6059E-01	1.60601E-01	-90.3695

GENERALIZED FORCES (WITH THICKNESS EFFECT)

MODES					
PPES.	DEFL.	REAL PART	IMAG PART	ABS. VALUE	PHASE ANGLE
2	1	-2.47011E+00	-2.34356E-01	2.44138E+00	-174.4915
2	2	-1.61039E+00	-1.70175E-01	1.61936E+00	-173.9678

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OF POOR QUALITY

ASPECT RATIO 1.5 DELTA WING (TAU=0.10)

30 BOXES ALONG ROOT CHORD

ROOT CHORD LENGTH = 10.00 FT

REDUCED FREQUENCY = .400

FREE STREAM VELOCITY = 1000.00 FT/SEC

FREQUENCY = 6.366E+00 CYCLE/SEC

MODE NO. 1

MODE NO. 2

GENERALIZED FORCES (NO THICKNESS EFFECT)

MODES		REAL PART	IMAG PART	ABS. VALUE	PHASE ANGLE
PRES.	DEFL.				
1	1	2.60265E-02	-9.51379E-01	9.51735E-01	-89.4330
1	2	1.93704E-02	-6.28441E-01	6.28740E-01	-88.2345

GENERALIZED FORCES (NO THICKNESS EFFECT)

MODES		REAL PART	IMAG PART	ABS. VALUE	PHASE ANGLE
PRES.	DEFL.				
2	1	-2.41529E+00	-9.98983E-01	2.61373E+00	-157.5296
2	2	-1.60030E+00	-7.44074E-01	1.76483E+00	-155.0635

MODE NO. 1

MODE NO. 2

GENERALIZED FORCES (WITH THICKNESS EFFECT)

MODES		REAL PART	IMAG PART	ABS. VALUE	PHASE ANGLE
PRES.	DEFL.				
1	1	1.95356E-02	-9.43362E-01	9.43564E-01	-88.8137
1	2	1.17730E-02	-6.19079E-01	6.19191E-01	-88.9105

GENERALIZED FORCES (WITH THICKNESS EFFECT)

MODES		REAL PART	IMAG PART	ABS. VALUE	PHASE ANGLE
PRES.	DEFL.				
2	1	-2.39926E+00	-9.75339E-01	2.58993E+00	-157.8775
2	2	-1.59205E+00	-7.16462E-01	1.73672E+00	-155.6357

Program Listing

	INPUT, JUTPUT, TAPE5=INPUT, TAPE6=OUTPUT)	SBOXR2	2
	MAI=...	SBOXR2	3
	MAXIMUM NUMBER OF BOXES ALONG THE CENTERLINE CHORD ALLOWED	SBOXR2	4
	... DIMENSION STATEMENT	SBOXR2	5
	MAXIMUM NUMBER OF MODES ALLOWED IN DIMENSION STATEMENT	SBOXR2	6
	MAXIMUM NUMBER OF BOXES ALLOWED FOR SPLINE FITTING	SBOXR2	7
	MODES ALLOWED IN DIMENSION STATEMENT	SBOXR2	8
	CALL ... XLE(30), XTE(30), EDG(30), AR(30,30)	A	2
	... ML(30), MLC(30), MLC(2,30), MB, AMA(30,30)	A	3
	... XEDG(8), YEDG(8), NTDCI, NS, XTDG(3), YTDG(3), NTDGI, NST	A	4
	... SFDX(100), SFDY(100), SFDH(103), KSFD, T(103,104), MB, NM	A	5
	... DA(100), AREA, CK, D, DH, DI, YMAX, JMAX, JHAK, IEDG, IW, L, NEW	A	6
	DIMENSION A(2, 60,30), S(2,30,30)	SBOXR2	10
	... SFDX(100,3), SFDY(100,3), SFDH(103,3), KSFD(3), G(3)	SBOXR2	11
	DATA 2/10 /	SBOXR2	12
	IF=0	SBOXR2	13
	IW=0	SBOXR2	14
	NTDCI=0	SBOXR2	15
	NTDCI=3	SBOXR2	16
	MB=3	SBOXR2	17
	MD=3	SBOXR2	18
	NB=100	SBOXR2	19
	MATCH ABOVE NUMBERS TO THE DEFINED DIMENSION IN STORAGE ARRAYS	SBOXR2	20
	ME=MB+1	SBOXR2	21
	MC=2*MB	SBOXR2	22
	NM=MB+3	SBOXR2	23
	WRITE (IW,55)	SBOXR2	24
	READ DATA FOR THE ACTUAL WING	SBOXR2	25
100	CALL DATRD(DA)	SBOXR2	26
	NEW=1	SBOXR2	27
	TEST1=DA(1001)+DA(1002)+DA(1003)+DA(1004)+DA(1005)	SBOXR2	28
	CK=DA(23)*DA(24)/DA(25)+6.28318531	SBOXR2	29
	DI=DA(27)	SBOXR2	30
	L=DI	SBOXR2	31
	D=1.0/DI	SBOXR2	32
	DH=0.5*D	SBOXR2	33
	WRITE(IW,60) (DA(I),I=1,7)	SBOXR2	34
110	IF (L) 600,600,120	SBOXR2	35
120	IF (MB-L) 600,130,130	SBOXR2	36
130	WRITE (IW,65) L,DA(24),CK,DA(25),DA(23)	SBOXR2	37
	IF (DA(26)) 160,150,160	SBOXR2	38
150	CALL SHAPE	SBOXR2	39
	IF(NEW.EQ.2) GO TO 180	SBOXR2	40
	AC=8.0/AREA	SBOXR2	41
160	LIM=ML(L)	SBOXR2	42
	IF (LIM-MB) 170,170,650	SBOXR2	43
170	LIM2=2*MB	SBOXR2	44
	NFLNS = DA(49)	SBOXR2	45
	IF(NFLNS.EQ.0) NFLNS = L	SBOXR2	46
	LPOT = MINO(L,NFLNS)	SBOXR2	47
	LIM1=2*MB	SBOXR2	48
	CALL POT2(LIM1,LIM2,LPOT,CK,D,A)	SBOXR2	49
180	CONTINUE	SBOXR2	50
	M=0	SBOXR2	51
	K=DA(28)	SBOXR2	52
	GO TO 230	SBOXR2	53
		SBOXR2	54
	PRELIMINARY CALCULATIONS ARE FINISHED.	SBOXR2	55
	THE NEXT SECTION IS GONE THROUGH FOR EACH MODE.	SBOXR2	56
		SBOXR2	57
200	IF (DA(26)) 230,210,230	SBOXR2	58
210	IF(NEW.EQ.2) GO TO 230	SBOXR2	59
	CALL DATRD(DA)	SBOXR2	60

230	K=K-1	SBOXR2	61
	M=M+1	SBOXR2	62
	IF (TEST1.LT.1.0) GO TO 250	SBOXR2	63
	WRITE (IW,55)	SBOXR2	64
250	WRITE (IW,15) M	SBOXR2	65
	WRITE (IW,16) (DA(I),I=13,19)	SBOXR2	66
15	FORMAT (1H0,15X,8HMODE NO.,I3)	SBOXR2	67
16	FORMAT (1H+,30X,7A10)	SBOXR2	68
	IF (DA(26)) 250,280,290	SBOXR2	69
C		SBOXR2	70
280	IF (NEW.EQ.2) GO TO 290	SBOXR2	71
	IPRINT=DA(1001)	SBOXR2	72
	CALL DRED(SFDX,SFDY,SFDH,KSFD,SFMX,SFMY,SFMH,KSFH,DA,T	SBOXR2	73
	,XX,YY,IW,L,HLC,H,MD,NB,NEW,NM,KSFS,IPRINT)	SBOXR2	74
C		SBOXR2	75
	G(H)=DA(51)	SBOXR2	76
290	IF (K) 310,310,300	SBOXR2	77
300	IF (M=MD) 200,310,310	SBOXR2	78
310	CONTINUE	SBOXR2	79
C		SBOXR2	80
	IF (I+IX(DA(50)).EQ.2.AND.NEW.EQ.1) GO TO 490	SBOXR2	81
	DU 470 M2=1,M	SBOXR2	82
	IF (J(M)) 480,320,480	SBOXR2	83
320	CONTINUE	SBOXR2	84
C		SBOXR2	85
	IPRINT=DA(1002)	SBOXR2	86
	CALL XVAL(XX,YY,XTDG,YTDG,XTE,SFDX,SFDY,SFDH,KSFD,S,D,CK	SBOXR2	87
	,I,H,L,ML,M1,NEW,NST,MB,MD,NB,NM,KSFS,IPRINT)	SBOXR2	88
C		SBOXR2	89
	IF (Y2GG(1)) 590,300,330	SBOXR2	90
330	CONTINUE	SBOXR2	91
C		SBOXR2	92
	CONTINUE EDGE CORRECTION	SBOXR2	93
	IF (J(M)) 500,300,330	SBOXR2	94
500	CONTINUE	SBOXR2	95
C		SBOXR2	96
	Y2=Y2GG(2)	SBOXR2	97
	IPRINT=DA(49)	SBOXR2	98
	IF (I+I=1) 510,300,330	SBOXR2	99
	CALL XVAL(XX,YY,XTDG,YTDG,XTE,XLE,A,AR,DAN,T,EDG,S,CK,D,YE	SBOXR2	100
	,IPRINT,MLT,MLC,AMA	SBOXR2	101
	,JMAK,C,ML,MLC,M1,NEW,NST,IH,MB,MC,ME,MD)	SBOXR2	102
C		SBOXR2	103
	CONTINUE	SBOXR2	104
C		SBOXR2	105
	COMPUTATION OF GENERALIZED FORCES FOR EACH MODE	SBOXR2	106
	IF (TEST1.LT.1.0) GO TO 420	SBOXR2	107
	WRITE (IW,20)	SBOXR2	108
	WRITE (IW,21) (IA(I),I=1,7)	SBOXR2	109
	WRITE (IW,22) (L,CA(1),CK,DA(25),DA(23))	SBOXR2	110
410	WRITE (IW,20)	SBOXR2	111
	IF (NEW.EQ.1) WRITE (IW,22)	SBOXR2	112
	IF (NEW.EQ.2) WRITE (IW,24)	SBOXR2	113
	WRITE (IW,25)	SBOXR2	114
20	FORMAT (1H0,10X,18HGENERALIZED FORCES)	SBOXR2	115
22	FORMAT (1H+,28X,22H (NO THICKNESS EFFECT))	SBOXR2	116
24	FORMAT (1H+,26X,24H (WITH THICKNESS EFFECT))	SBOXR2	117
25	FORMAT (1H0,5X,5HMODES/4X,11HPRES. DEFL.,8X,9HREAL PART,10X,9HIMAG	SBOXR2	118
	SPART,10X,10HABS. VALUE,6X,11HPHASE ANGLE)	SBOXR2	119
C		SBOXR2	120
	DU 470 M2=1,M	SBOXR2	121
C		SBOXR2	122
	CALL FURGI(XX,YY,S,SFDX,SFDY,SFDH,KSFD,KSFS,XLE,XTE,YMAX	SBOXR2	123
	,AMA,JMAK,MLT,L,NEW,M2,MB,MD,NB,NM,CK,T)	SBOXR2	124
C		SBOXR2	125
	S1=AC*T(1,1)	SBOXR2	126
	S2=AC*T(2,1)	SBOXR2	127
	S3=SQRT(S1**2+S2**2)	SBOXR2	128
	S4=57.29576*ATAN2(S2,S1)	SBOXR2	129
		SBOXR2	130

450	WRITE (IW,30) M1,M2,S1,S2,S3,S4	SBOXR2	131
30	FORMAT (1H02I6,1P3E19.5,0P1F16.4)	SBOXR2	132
470	CONTINUE	SBOXR2	133
480	WRITE (IW,55)	SBOXR2	134
490	CONTINUE	SBOXR2	135
	IF (DA(26).GT.C.) GO TO 510	SBOXR2	136
	DO 500 I=13,22	SBOXR2	137
500	DA(I)=Z	SBOXR2	138
510	IF (IFIX(DA(50))-1.EQ.0) GO TO 100	SBOXR2	139
	IF (NEW.EQ.2) GO TO 100	SBOXR2	140
	NEW=C	SBOXR2	141
	IF (DA(26)) 18C,580,180	SBOXR2	142
580	IPRINT=DA(1G04)	SBOXR2	143
	CALL MRED(DA,T,NH,NB,KSFM,SFMX,SFMY,SFMH,IW,IPRINT)	SBOXR2	144
	GO TO 150	SBOXR2	145
C		SBOXR2	146
C	ERROR EXITS	SBOXR2	147
C		SBOXR2	148
590	IPR=30	SBOXR2	149
	GO TO 610	SBOXR2	150
600	IPR=27	SBOXR2	151
610	WRITE (IW,35) IPR	SBOXR2	152
35	FORMAT(1H010X,8HBAD DATA14)	SBOXR2	153
	GO TO 700	SBOXR2	154
650	WRITE (IW,4C)	SBOXR2	155
40	FORMAT(1H010X,42HLATERAL LIMIT ON NUMBER OF BOXES EXCEEDED.)	SBOXR2	156
700	STOP	SBOXR2	157
55	FORMAT(1H1)	SBOXR2	158
60	FORMAT(1H0,10X,7A10)	SBOXR2	159
65	FORMAT(1H0,10X,12,23H BOXES ALONG ROOT CHORD,	SBOXR2	160
1	15X,22HROOT CHORD LENGTH =,F8.2,3H FT/	SBOXR2	161
2	1H0,10X,19HREDUCED FREQUENCY =,F6.3,	SBOXR2	162
3	15X,22HFREE STREAM VELOCITY =,F8.2,7H FT/SEC/	SBOXR2	163
4	1H0,10X,11HFREQUENCY =,1PE11.3,10H CYCLE/SEC)	SBOXR2	164
	END	SBOXR2	165

Code	Statement	Line Number
	SUBROUTINE DATRD(DATA)	2
C	CARD-READ SUBROUTINE "DATRD(DATA(I))"	3
	DIMENSION DRBU(12),DATA(1),DDRBU(10)	4
	DATA ATEST/5,HALPHA/,DTEST/1H /,ETEST/1H-/,STEST/1H+/ DATA Z/1H /	5
	IR=5	6
	IW=6	7
	1 READ (IR,2) EMIN,ALP,IND,(DRBU(I),I=1,7)	8
	2 FORMAT(1A,45,16,6A10,A8)	9
	IF(IND.EQ.0) GO TO 20	10
	IF (EMIN.NE.STEST) GO TO 105	11
C	NEW KING IF COLUMN 1 CONTAINS A PLUS SIGN	12
C	INITIALIZATION OF DATA ARRAY	13
	DO 101 I=23,1005	14
101	DATA(I)=0.0	15
	DO 102 I=1,22	16
102	DATA(I)=Z	17
	DO 103 I=104,700,4	18
103	DATA(I)=1.0	19
105	CONTINUE	20
	IF (ALP.EQ.ATEST) GO TO 9	21
	IF (ALP.NE.CTEST) GO TO 8	22
C	NUMERIC CARD	23
	DO 3 I=1,6	24
	DDRBU(I)=G+ZU(I)	25
	3 CONTINUE	26
	DECOB=(C0,790,DDRBU)(DRBU(I),I=1,5)	27
	DO 5 I=1,5	28
	IF(DNEU(I))4,6,4	29
C	TEST FOR BLANK FIELD	30
	IF(SIGN(1.0,DRBU(I)))2,3,4	31
	DATA(IND)=DRBU(I)	32
	IND=IND+1	33
	GO TO 11	34
C	ALTER CASE	35
	DO 17 I=1,7	36
	DATA(IND)=DRBU(I)	37
	17 IND=IND+1	38
	11 IF (EMIN.NE.STEST) GO TO 1	39
C	RETURN IF COLUMN 1 CONTAINS A MINUS SIGN	40
	10 RETURN	41
	END OF DATA CARDS	42
	1. PRINT (1,5,9,0)	43
	CALL EXIT	44
	STOP	45
C	END CARD	46
	2 CONTINUE	47
	WRITE (1,5,9,0) EMIN,ALP,IND,(DRBU(I),I=1,7)	48
	WRITE (1,5,9,0)	49
	STOP	50
405	PRINT(1,5,9,0)	51
410	FORMAT(1,5,9,0) END OF DATA ON THIS CARD. JOB TERMINATED .)	52
415	FORMAT(1,5,9,0) END OF DATA ON THIS CARD. JOB TERMINATED .)	53
420	FORMAT(1,5,9,0) END OF DATA ON THIS CARD. JOB TERMINATED .)	54
425	FORMAT(1,5,9,0) END OF DATA ON THIS CARD. JOB TERMINATED .)	55
430	FORMAT(1,5,9,0) END OF DATA ON THIS CARD. JOB TERMINATED .)	56
	END	57

		SHAPE	2
		A	2
		A	3
		A	4
		A	5
		A	6
		SHAPE	4
		SHAPE	5
		SHAPE	6
		SHAPE	7
		SHAPE	8
		SHAPE	9
		SHAPE	10
		SHAPE	11
		SHAPE	12
		SHAPE	13
		SHAPE	14
		SHAPE	15
		SHAPE	16
		SHAPE	17
100	IF (NS-NEUGI+1) 10>,10>,850	SHAPE	18
105	NSP=NS+1	SHAPE	19
	NS=NSP	SHAPE	20
	IF (DA(24)) 855,85>,110	SHAPE	21
110	DO 115 I=1,NSP	SHAPE	22
	XEDG(I)=DA(2*I+27)/DA(24)	SHAPE	23
115	YEDG(I)=DA(2*I+28)/DA(24)	SHAPE	24
	XEDG(1)=0.0	SHAPE	25
	NST=DA(45)	SHAPE	26
	IF (NST) 871,125,130	SHAPE	27
125	XTDG(1)=1.0	SHAPE	28
	NST=1	SHAPE	29
	GO TO 141	SHAPE	30
130	IF (NST-NTDGI+1) 135,135,871	SHAPE	31
135	NSTP=NST	SHAPE	32
	DO 140 I=1,NSTP	SHAPE	33
	YTDG(I)=DA(2*I+43)/DA(24)	SHAPE	34
140	XTDG(I)=DA(2*I+44)/DA(24)	SHAPE	35
141	NSTP=NSTP+1	SHAPE	36
	NST=NSTP	SHAPE	37
	XTDG(NSTP)=XEDG(NSP)	SHAPE	38
	YTDG(NSTP)=YEDG(NSP)	SHAPE	39
	YTDG(1)=0.0	SHAPE	40
	IF (NST.EQ.NTDGI) GO TO 150	SHAPE	41
	JL=NST+1	SHAPE	42
	DO 142 I=JL,NTDGI	SHAPE	43
	XTDG(I)=XTDG(I-1)	SHAPE	44
142	YTDG(I)=YTDG(I-1)	SHAPE	45
150	IF (ABS(XTDG(NSTP)-XEDG(NSP)+YTDG(NSTP)-YEDG(NSP)).GT.ERRR)	SHAPE	46
	S GO TO 871	SHAPE	47
	GO TO 550	SHAPE	48
C		SHAPE	49
C	FOR WING WITH THICKNESS	SHAPE	50
C	COMPUTE MACH NUMBER DISTRIBUTION ON PHYSICAL WING	SHAPE	51
200	DM=0.	SHAPE	52
	DO 210 I=1,MB	SHAPE	53
	DO 210 J=1,MB	SHAPE	54
210	AMA(J,I)=1.0	SHAPE	55
	DO 215 I=1,L	SHAPE	56
	IF (MLC(1,I).EQ.0) GO TO 215	SHAPE	57
	J=MLC(1,I)	SHAPE	58
	K=MLC(2,I)	SHAPE	59
	CALL SURF2(XX(I),YY,J,K,1,AMA(1,I),DM,DM,SFMX,SFMY,SFMH,KSFH,1)	SHAPE	60
215	CONTINUE	SHAPE	61
	IF (J.KITE.EQ.0) GO TO 235	SHAPE	62
C	PRINT OUT MACH DISTRIBUTION	SHAPE	63
	WRITE(IH,60)	SHAPE	64
	DO 230 I=1,L	SHAPE	65
	IF (MLC(1,I).EQ.0) GO TO 230	SHAPE	65





	GO TO 642	SHAPE	137
646	NZ2=I2-1	SHAPE	138
	GO TO 652	SHAPE	139
648	NZ2=I2	SHAPE	140
652	CONTINUE	SHAPE	141
	MLT(1,J)=NZ1	SHAPE	142
	MLT(2,J)=NZ2	SHAPE	143
655	CONTINUE	SHAPE	144
C		SHAPE	145
C	FIND ORDER OF WING BOXES AT EACH I-TH SPANWISE COLUMN	SHAPE	146
	DO 670 I=1,L	SHAPE	147
	IF (MLW(I)) 664,662,662	SHAPE	148
662	MLC(1,I)=MLW(I)+1	SHAPE	149
	IF (MLC(2,I).EQ.0) MLC(1,I)=0	SHAPE	150
	GO TO 670	SHAPE	151
664	MLC(2,I)=IABS(MLW(I))-1	SHAPE	152
	MLC(1,I)=1	SHAPE	153
670	CONTINUE	SHAPE	154
C		SHAPE	155
	IF (IRITE.EQ.0) GO TO 678	SHAPE	156
	WRITE (IW,65)	SHAPE	157
	IF (NEW.EQ.1) WRITE (IW,77)	SHAPE	158
	IF (NEW.EQ.2) WRITE (IW,78)	SHAPE	159
	WRITE (IW,82)	SHAPE	160
	DO 672 J=1,JMX	SHAPE	161
672	WRITE (IW,85) J,MLT(1,J),MLT(2,J)	SHAPE	162
	WRITE (IW,83)	SHAPE	163
	DO 674 J=1,L	SHAPE	164
C 674	WRITE (IW,85) J,MLC(1,J),MLC(2,J)	SHAPE	165
674	WRITE (IW,85) J,MLC(1,J),MLC(2,J),MLW(J),ML(J)	SHAPE	166
678	CONTINUE	SHAPE	167
C		SHAPE	168
	IF (XEDG(NSP).GT.1.) GO TO 865	SHAPE	169
	NSP=NSP-1	SHAPE	170
	DY=YEDG(NSP)-YEDG(NSP)	SHAPE	171
	IF (ABS(DY).LE.LERR) IEDG=1	SHAPE	172
	IF (DY.LT.0.) GO TO 827	SHAPE	173
C	COMPUTE VALUES FOR LEADING EDGE CORRECTION	SHAPE	174
	YMAX2=YMAX*YMAX	SHAPE	175
	DY=0	SHAPE	176
	DO 720 J=1,JMX	SHAPE	177
	IF (IEDG) 710,715,715	SHAPE	178
C	DY IN FOLLOWING EXPRESSION IS ARBITRARY	SHAPE	179
710	EDG(J)=SQRT((YMAX2-YY(J)*YY(J))/(DY*(2.*YMAX-DY)))	SHAPE	180
	IF (EDG(J).GT.1.) GO TO 715	SHAPE	181
	GO TO 720	SHAPE	182
715	EDG(J)=1.0	SHAPE	183
720	CONTINUE	SHAPE	184
C		SHAPE	185
750	CONTINUE	SHAPE	186
C		SHAPE	187
790	CONTINUE	SHAPE	188
C		SHAPE	189
	RETURN	SHAPE	190
C		SHAPE	191
800	IERROR=800	SHAPE	192
	T(1,1)=XEDG(K)	SHAPE	193
	T(2,1)=YEDG(K)	SHAPE	194
	IERR=2	SHAPE	195
	GO TO 843	SHAPE	196
805	IERROR=805	SHAPE	197
	GO TO 840	SHAPE	198
810	IERROR=810	SHAPE	199
	T(1,1)=DA(27)	SHAPE	200
	T(2,1)=NSP	SHAPE	201
	IERR=2	SHAPE	202
	GO TO 840	SHAPE	203
815	IERROR=815	SHAPE	204
	GO TO 840	SHAPE	205
820	IERR=2	SHAPE	206
	T(1,1)=XEDG(NSP)	SHAPE	207

T(2,1)=YEDG(NSP)	SHAPE	208
T(3,1)=NSP	SHAPE	209
IER=3	SHAPE	210
GO TO 840	SHAPE	211
825 IERROR=825	SHAPE	212
T(1,1)=NEH	SHAPE	213
T(2,1)=K	SHAPE	214
T(3,1)=ML(K)	SHAPE	215
T(4,1)=ML(K-1)	SHAPE	216
IER=4	SHAPE	217
GO TO 840	SHAPE	218
827 IERROR=827	SHAPE	219
T(1,1)=YEDG(NSP)	SHAPE	220
T(2,1)=YEDG(NSM)	SHAPE	221
T(3,1)=NSP	SHAPE	222
T(4,1)=NSM	SHAPE	223
IER=4	SHAPE	224
GO TO 840	SHAPE	225
830 IERROR=730	SHAPE	226
T(1,1)=I	SHAPE	227
T(2,1)=J	SHAPE	228
T(3,1)=X	SHAPE	229
T(4,1)=Y	SHAPE	230
T(5,1)=EM	SHAPE	231
T(6,1)=EMY	SHAPE	232
T(7,1)=DEL	SHAPE	233
IER=7	SHAPE	234
840 WRITE(IN,20) IERROR, (T(I,1),I=1,IER)	SHAPE	235
STOP	SHAPE	236
850 IPR=29	SHAPE	237
GO TO 890	SHAPE	238
855 IPR=24	SHAPE	239
GO TO 890	SHAPE	240
860 IPR=30	SHAPE	241
GO TO 890	SHAPE	242
865 K= MINO(K,NS)	SHAPE	243
IPR=2*K+29	SHAPE	244
GO TO 890	SHAPE	245
871 IPR=45	SHAPE	246
890 WRITE	SHAPE	247
0 (IN,10)IPR	SHAPE	248
10 FORMAT(1H0,10X,17HSHAPE -- BAD DATA,I5)	SHAPE	249
20 FORMAT(1H0,10X,38HBAD NUMBER IN SHAPE NEAR STATEMENT NO.,I5,	SHAPE	250
1 /1H,15X,1P8E14.6)	SHAPE	251
40 FORMAT(/1H0,5X,3HNO.,12,43H REDISTRIBUTION OF WING LEADING EDGES,	SHAPE	252
1 NS(I,1,4H) = ,12,7H, IEDG,3H = ,11)	SHAPE	253
45 FORMAT(/1H0,5X,25HWING TRAILING EDGES, NST(,11,4H) = ,12,	SHAPE	254
5 /10H, IEDG = ,11)	SHAPE	255
50 FORMAT(4(6X,I3,1P2E11.4))	SHAPE	256
60 FORMAT(1H1,5X,47HLOCAL MACH NUMBER DISTRIBUTION ON PHYSICAL WING/)	SHAPE	257
65 FORMAT(1H1)	SHAPE	258
70 FORMAT(1H0,5X,12,19H-TH SPANWISE COLUMN)	SHAPE	259
75 FORMAT(1H0,5X,12,17H-TH CHORDWISE ROW)	SHAPE	260
77 FORMAT(40X,13HPHYSICAL WING//)	SHAPE	261
78 FORMAT(40X,16HTRANSFORMED WING//)	SHAPE	262
80 FORMAT(1H,5X,6(2X,I3,1PE13.5))	SHAPE	263
82 FORMAT(15X,62HORDER OF FIRST(LEADING) AND LAST(TRAILING) WING BOX	SHAPE	264
11N CHORDWISE ROW//20X,1HJ,3X,12HMLT(NEW,1,J),3X,12HMLT(NEW,2,J))	SHAPE	265
83 FORMAT(///15X,62HORDER OF FIRST(ROOT) AND LAST(TIP) WING BOX. IN SP	SHAPE	266
1ANWISE COLUMN//20X,1HI,3X,12HMLC(NEW,1,I),3X,12HMLC(NEW,2,I)	SHAPE	267
2 ,4X,11H(MLW(NEW,I),5X,10HML(NEW,I))//)	SHAPE	268
85 FORMAT(16X,15,5X,15,3(10X,I5))	SHAPE	269
86 FORMAT(20X,58HGAUSSIAN INTEGRATION POINTS IN CHORDWISE ROW - GX(NE	SHAPE	270
1W,K,J))//)	SHAPE	271
87 FORMAT(///20X,52HGAUSSIAN INTEGRATION POINTS IN SEMI-SPAN - GY(NE	SHAPE	272
1W,K,J))//)	SHAPE	273
88 FORMAT(///20X,60HSPANWISE COORDINATE (GYP) AND MACH NUMBER (GMP) A	SHAPE	274
ND GX(2,K,J))//)	SHAPE	275
89 FORMAT(1H,5X,3(2X,I3,1P2E16.0))	SHAPE	276
STOP	SHAPE	277
END	SHAPE	278

	SUBROUTINE PLNFH(XEDG, YEDG, XTDC, YTDG, XX, YY, XLE, XTE, AR, AREA, D	PLNFH	2
3	, IN, L, MB, HL, HLC, HLM, HEM, HS, NST, JRYE)	PLNFH	3
	DIMENSION XEDG(12), YEDG(12), XTDC(1), YTDG(1), XX(1), YY(1), AR(MB,1)	PLNFH	4
1	, HEM(1), HLC(2,1), HLM(1), XLE(1), XTE(1)	PLNFH	5
	DATA ERRR/1.E+06/, ERR1/0.001/, ERR2/1.E+05/, ANAK/0.5/	PLNFH	6
	DATA Z1/ZHF=1, Z2/ZHG=1	PLNFH	7
	DH=0.5*0	PLNFH	8
	D2=0*0	PLNFH	9
	NSP =NS	PLNFH	10
	NSTP=NST	PLNFH	11
	DO 30 I=1,MB	PLNFH	12
	HLC(2,I)=0	PLNFH	13
	HLM(I)=0	PLNFH	14
	XLE(I)=XEDG(NSP)	PLNFH	15
	XTE(I)=YEDG(NSP)	PLNFH	16
	DO 30 J=1,MB	PLNFH	17
	30 AR(J,I)=0.0	PLNFH	18
C		PLNFH	19
210	K1=0	PLNFH	20
	K2=NST	PLNFH	21
	JK=1	PLNFH	22
	XR=XEDG(1)	PLNFH	23
	YR=YEDG(1)	PLNFH	24
	X2=XR	PLNFH	25
	Y2=YR	PLNFH	26
	XE2=0.0	PLNFH	27
	SUM=0.0	PLNFH	28
	AREA=0.0	PLNFH	29
	ASNG=1.0	PLNFH	30
	JLT=1	PLNFH	31
C		PLNFH	32
220	DO 530 I=1,L	PLNFH	33
	ICHQ=0	PLNFH	34
	IFIN=0	PLNFH	35
	IEDZ=0	PLNFH	36
	XL=XR	PLNFH	37
	YL=YR	PLNFH	38
	XR=XX(I)+DH	PLNFH	39
	J=0	PLNFH	40
	SAH=0.0	PLNFH	41
	IF(ASNG) 225,230,230	PLNFH	42
225	IF(XR.LT.XTDC(I).AND.XTDC(I)-XR.GT.ERR2) GO TO 530	PLNFH	43
	IF(K2.EQ.0) GO TO 440	PLNFH	44
	GO TO 240	PLNFH	45
230	CONTINUE	PLNFH	46
	IF(K1+1.GT.NS) GO TO 420	PLNFH	47
	IF(K1.EQ.0) GO TO 400	PLNFH	48
240	ICHQ=0	PLNFH	49
	IF(XR.GT.XE2) ICHQ=1	PLNFH	50
250	J=J+1	PLNFH	51
	JFIN=0	PLNFH	52
	Y=YY(J)+DH	PLNFH	53
	IF(ASNG) 252,256,256	PLNFH	54
252	IF(ABS(XTDC(I)-XTDC(NSTP)).GT.ERR2.OR.I.NE.L) GO TO 254	PLNFH	55
	IF(Y-DH.GT.YTDG(NSTP)) GO TO 530	PLNFH	56
	XTE(J)=XTDC(I)	PLNFH	57
	GO TO 250	PLNFH	58
254	SUM=SUM-AR(J,I)	PLNFH	59
	GO TO 258	PLNFH	60
256	AR(J,I)=0.0	PLNFH	61
258	CONTINUE	PLNFH	62
	IF(YL.LT.Y) GO TO 280	PLNFH	63
	IF(ASNG) 265,270,270	PLNFH	64
265	AR(J,I)=0.0	PLNFH	65
	GO TO 250	PLNFH	66
270	CONTINUE	PLNFH	67
	AR(J,I)=1.0	PLNFH	68
	SAH=SAH+AR(J,I)	PLNFH	69
	GO TO 250	PLNFH	70

280	IF(Y-YL+ERR2.GE.D) GO TO 290	PLNFM	71
	AR(J,I)=AR(J,I)+ASNG*(YL-Y+D)/D	PLNFM	72
	X1=XL	PLNFM	73
	Y1=YL	PLNFM	74
	IF(ICHQ.NE.1) GO TO 310	PLNFM	75
	IF(JK) 284, 85, 285	PLNFM	76
284	IF(YE2.LE.Y-D) GO TO 320	PLNFM	77
	GO TO 286	PLNFM	78
285	IF(YE2.GE.Y) GO TO 320	PLNFM	79
286	CONTINUE	PLNFM	80
	IF(XE1.GT.XL) GO TO 400	PLNFM	81
	IEDZ=2	PLNFM	82
	GO TO 400	PLNFM	83
290	X1=X2	PLNFM	84
	Y1=Y2	PLNFM	85
295	IEDZ=0	PLNFM	86
	IF(ICHQ.NE.1) GO TO 310	PLNFM	87
	YR=YE2	PLNFM	88
	GO TO 315	PLNFM	89
310	YR=YE1+TNG*(XR-XE1)	PLNFM	90
315	IF(JK) 317, 316, 316	PLNFM	91
316	IF(YR.GE.Y) GO TO 320	PLNFM	92
	GO TO 318	PLNFM	93
317	IF(YR.LE.Y-D) GO TO 320	PLNFM	94
318	CONTINUE	PLNFM	95
	IF(ICHQ.EQ.1) GO TO 325	PLNFM	96
	IFIN=1	PLNFM	97
	X2=XR	PLNFM	98
	Y2=YR	PLNFM	99
	GO TO 330	PLNFM	100
320	JFIN=1	PLNFM	101
	IF(JK) 322, 321, 321	PLNFM	102
321	Y2=Y	PLNFM	103
	GO TO 323	PLNFM	104
322	Y2=Y-D	PLNFM	105
323	X2=XE1+(Y2-YE1)/TNG	PLNFM	106
	IF(ABS(X2-XR).GT.ERRR) GO TO 330	PLNFM	107
	IFIN=1	PLNFM	108
	JFIN=0	PLNFM	109
	GO TO 330	PLNFM	110
325	IEDZ=1	PLNFM	111
	X2=XE2	PLNFM	112
	Y2=YE2	PLNFM	113
330	AR(J,I)=AR(J,I)+0.5*ASNG*(2.*XR-X2-X1)*(Y2-Y1)/D2	PLNFM	114
C		PLNFM	115
C		PLNFM	116
	IF(ABS(TNG).GT.ERRR) TNG=T-20	PLNFM	117
1331	CONTINUE	PLNFM	118
	IF(JK) 332, 331, 331	PLNFM	119
331	IF(J.LT.JLT) GO TO 334	PLNFM	120
	XLT=XE1+(YY(JLT)-YE1)/TNG	PLNFM	121
	IF(XLT.GT.XE2.AND.ASNG.GT.0.0) GO TO 334	PLNFM	122
	IF(YE2.GT.0.GT.C.G.AND.YY(JLT).LE.YL.AND.ASNG.GT.0.0) XLT=0.0	PLNFM	123
	IF(YY(JLT).GE.YTGG(INSTP)) XLT=XTGG(INSTP)	PLNFM	124
	IF(ASNG.GT.C.C) XLE(JLT)=XLT	PLNFM	125
	IF(ASNG.LT.C.C) XTE(JLT)=XLT	PLNFM	126
	GO TO 333	PLNFM	127
332	IF(J.GT.JLT) GO TO 334	PLNFM	128
	XLT=XE1+(YY(JLT)-YE1)/TNG	PLNFM	129
	IF(YY(JLT).GE.YTGG(INSTP)) XLT=XTGG(INSTP)	PLNFM	130
	XTE(JLT)=XLT	PLNFM	131
333	JLT=JLT+JK	PLNFM	132
	GO TO 1331	PLNFM	133
334	CONTINUE	PLNFM	134
C		PLNFM	135
	IF(IEDZ.EQ.1) GO TO 400	PLNFM	136
	SAM=5AM+AS(J,I)	PLNFM	137
	IF(JK) 344, 342, 342	PLNFM	138
342	CONTINUE	PLNFM	139
	IF(JFIN.....) GO TO 200	PLNFM	140

	GO TO 350	PLNFM	141
344	IF(JFIN.EQ.1) GO TO 475	PLNFM	142
350	IF(ASNG) 355,360,360	PLNFM	143
355	IF(IIFIN.EQ.1) GO TO 473	PLNFM	144
	GO TO 530	PLNFM	145
360	IF(IIFIN.EQ.1) GO TO 465	PLNFM	146
	GO TO 500	PLNFM	147
C		PLNFM	148
C	LEADING EDGE AND TRAILING EDGE COMPUTATION	PLNFM	149
C		PLNFM	150
400	IF(ASNG) 440,405,405	PLNFM	151
405	IF(JK) 430,410,410	PLNFM	152
410	KI=KI+JK	PLNFM	153
	IF(K1.GE.NSP) GO TO 420	PLNFM	154
	XE1=XEDG(K1)	PLNFM	155
	YE1=YEDG(K1)	PLNFM	156
	K=KI+JK	PLNFM	157
	XE2=XEDG(K)	PLNFM	158
	YE2=YEDG(K)	PLNFM	159
	GO TO 450	PLNFM	160
420	IF(JK.LT.0) GO TO 240	PLNFM	161
	JK=-1	PLNFM	162
	JLT=J	PLNFM	163
	MLC(2,1)=0	PLNFM	164
	K2=K2-JK	PLNFM	165
430	K2=K2+JK	PLNFM	166
	XE1=XTDG(K2)	PLNFM	167
	YE1=YTDG(K2)	PLNFM	168
	K=K2+JK	PLNFM	169
	XE2=XTDG(K)	PLNFM	170
	YE2=YTDG(K)	PLNFM	171
	GO TO 450	PLNFM	172
440	K2=K2+1	PLNFM	173
	XE1=XTDG(K2)	PLNFM	174
	YE1=YTDG(K2)	PLNFM	175
	XE2=XTDG(K2+1)	PLNFM	176
	YE2=YTDG(K2+1)	PLNFM	177
450	G=XE2-XE1	PLNFM	178
	F=YE2-YE1	PLNFM	179
	TNG=F/(G+1.E-20)	PLNFM	180
	IF(G.LT.0.) GO TO 650	PLNFM	181
	AREA=AREA+ASNG*G*(YE2+YE1)	PLNFM	182
C		PLNFM	183
	ICHO=0	PLNFM	184
	IF(XR.GT.XE2) ICHO=1	PLNFM	185
	IF(IEDZ.EQ.1) GO TO 290	PLNFM	186
	IF(IEDZ.EQ.2) GO TO 295	PLNFM	187
	GO TO 250	PLNFM	188
C		PLNFM	189
C	NUMBER OF BOXES IN SPANWISE COLUMN	PLNFM	190
C	WAKE TYPE AND ORDER OF WAKE BOX	PLNFM	191
C		PLNFM	192
465	IF(ASNG) 478,467,467	PLNFM	193
467	IF(JK) 476,469,469	PLNFM	194
469	JJ=0	PLNFM	195
	IF (AR(J,I).LT.ERR2) JJ=1	PLNFM	196
	ML(I)=J-JJ	PLNFM	197
C		PLNFM	198
	JJ=ML(I)	PLNFM	199
	DO 471 K=1,JJ	PLNFM	200
	KK=K	PLNFM	201
	IF (AR(K,I).LT.AWAK) GO TO 472	PLNFM	202
471	CONTINUE	PLNFM	203
	MLC(2,I)=KK	PLNFM	204
	GO TO 473	PLNFM	205
472	MLC(2,I)=KK-1	PLNFM	206
473	CONTINUE	PLNFM	207
C	ADJUSTMENT OF FIRST BOX AT LEADING EDGE ALONG KK-TH CHORDWISE ROW	PLNFM	208
	KK=MLC(2,I)	PLNFM	209
	IF (XX(I).GE.XLE(KK)) GO TO 474	PLNFM	210



YE2=YTDG(1)	PLNFM	281
X2=XE2	PLNFM	282
Y2=YE2	PLNFM	283
ASNG=-1.0	PLNFM	284
JLT=1	PLNFM	285
GO TO 220	PLNFM	286
C ERROR MESSAGE	PLNFM	287
650 K=450	PLNFM	288
A=C	PLNFM	289
Z=Z2	PLNFM	290
WRITE(IH,15G) K,Z,A	PLNFM	291
STOP	PLNFM	292
C	PLNFM	293
700 CONTINUE	PLNFM	294
IF(JRITE.EQ.0) GO TO 760	PLNFM	295
WRITE(IH,65)	PLNFM	296
IF(NEW.EQ.1) WRITE(IH,66)	PLNFM	297
IF(NEW.EQ.2) WRITE(IH,67)	PLNFM	298
DO 750 I=1,L	PLNFM	299
JL=ML(I)	PLNFM	300
K=JL/5	PLNFM	301
IF(JL.LE.5*K) GO TO 710	PLNFM	302
K=K+1	PLNFM	303
710 WRITE(IH,70) I	PLNFM	304
WRITE(IH,72) PLC(2,I)	PLNFM	305
IF (MLW(I)) 715,725,720	PLNFM	306
715 WRITE(IH,75) PLW(I)	PLNFM	307
GO TO 725	PLNFM	308
720 WRITE(IH,80) PLW(I)	PLNFM	309
725 DO 740 JJ=1,K	PLNFM	310
740 WRITE(IH,82) (J,AR(J,I),J=JJ,JL,K)	PLNFM	311
750 CONTINUE	PLNFM	312
C	PLNFM	313
JL=ML(L)	PLNFM	314
WRITE(O,14G)	PLNFM	315
WRITE(IH,145) (J,ALC(J),XTE(J),J=1,JL)	PLNFM	316
C	PLNFM	317
SUM=2.*SUM*02	PLNFM	318
WRITE(IH,90) AREA,SUM	PLNFM	319
760 RETURN	PLNFM	320
65 FORMAT(1H,20X,37HNON-DIMENSIONAL BOX-AREA DISTRIBUTION)	PLNFM	321
66 FORMAT(1H+,57X,21H - ( PHYSICAL WING)///)	PLNFM	322
67 FORMAT(1H+,57X,21H - (TRANSFORMED WING)///)	PLNFM	323
70 FORMAT(/2X,12,14H-TM SPANWISE COLUMN/)	PLNFM	324
72 FORMAT(12X,16HFIRST L.C. BOX =,13,22H-TM BOX FROM WING ROOT)	PLNFM	325
75 FORMAT(12X,16HFIRST WAKE BOX =,13,22H-TM BOX FROM WING ROOT//)	PLNFM	326
80 FORMAT(12X,16HLAST WAKE BOX =,13,22H-TM BOX FROM WING ROOT//)	PLNFM	327
85 FORMAT(5X,5(1X,13,1P=11.4))	PLNFM	328
90 FORMAT(/10X,25HHING AREA CALCULATED FROM/	PLNFM	329
1 15X,26HLEADING AND TRAILING EDGES =,1PE11.4/	PLNFM	330
2 15X,26HSUMMATION OF AREA OF BOXES =,1PE11.4)	PLNFM	331
96 FORMAT(/10X,43HNEGATIVE BOX AREA EXCEEDS ALLOWABLE LIMIT (,	PLNFM	332
1 1PE11.4,1H)/10X,3HAR(,13,1H,,13,1H,,6HNEW) =,1PE11.4,	PLNFM	333
2 5X,21HCOMPUTATION CONTINUES//)	PLNFM	334
140 FORMAT(1H,9X,54HLEADING AND TRAILING EDGE POINTS AT EACH CHORDWIS	PLNFM	335
SE ROW/13X,1HJ,6X,7HLEADING,8X,8HTRAILING/)	PLNFM	336
145 FORMAT(10X,13,1P2E15.5)	PLNFM	337
150 FORMAT(1H0,4X,29HPLNFM--NEGATIVE VALUE NEAR SN,14,2X,A2,1PE11.4)	PLNFM	338
155 FORMAT(1H0,4X,25HORDER OF WING TIP BOX IN ,12,43H-TM SPANWISE COLU	PLNFM	339
IMN IS NOT PROPERLY DEFINED//	PLNFM	340
2 15X,8HMLW(NEW,,12,3H) =,13/15X,8HMLL(NEW,,12,3H) =,13)	PLNFM	341
END	PLNFM	342



	SUBROUTINE POT2(M2,MO,NO,CK,D,A)	POT2	2
C		POT2	3
C	THE VELOCITY FIELD OF A UNIFORM DOUBLET DISTRIBUTION	POT2	4
C	OVER A BOX IS COMPUTED AT ALL POINTS AT WHICH IT WILL BE	POT2	5
C	NEEDED AND STORED IN THE ARRAY A IN COMMON	POT2	6
C		POT2	7
C	MO,NO CONTROL THE NUMBER OF VALUES COMPUTED	POT2	8
C		POT2	9
C	M2 IS THE RANGE OF THE SECOND SUBSCRIPT IN THE ARRAY,	POT2	10
C	DIMENSIONED A(2,M2,N2), BUT TREATED HERE AS AN ARRAY	POT2	11
C	WITH TWO SUBSCRIPTS	POT2	12
C		POT2	13
	DIMENSION A(2,1)	POT2	14
	M=MO	POT2	15
	N=NO	POT2	16
	DK=CK*D	POT2	17
	DK2=DK**2	POT2	18
	M1=M-1	POT2	19
	DK8=DK2/8.0	POT2	20
	DK4=2.0*DK8	POT2	21
	DK12=DK2/12.0	POT2	22
	CM=0.5	POT2	23
	DM=DK**0.5	POT2	24
	JM=0.5*DM	POT2	25
	DD=2.0*DK	POT2	26
	DCM=DD	POT2	27
	C1=0.25*DK2	POT2	28
	B5=CK2/24.0	POT2	29
	DO 3 I=1,M	POT2	30
	B1=0.0	POT2	31
	B4=2.0/DM	POT2	32
	B2=35/84-DM	POT2	33
	B3=-0.5*B5	POT2	34
	B6=DM**0.4+B5	POT2	35
	D4=0.8*B4	POT2	36
	DC4=2.0*D4	POT2	37
	CM=1.0	POT2	38
	K=1	POT2	39
	C3=0.0	POT2	40
	C4=0.0	POT2	41
	C7=0.0	POT2	42
	C8=0.0	POT2	43
	DO 2 J=1,N	POT2	44
	A1=DM/CM	POT2	45
	C1=C4* COS(A1)	POT2	46
	C2=-CM* SIN(A1)	POT2	47
	C5=CM*CM*(A1,C6)	POT2	48
	C6=-CM*B6	POT2	49
	C9=C1-C3	POT2	50
	C10=C2-C4	POT2	51
	C11=C5-C7	POT2	52
	C12=C6-C8	POT2	53
	A(1,K)=B3*C9-B4*C10-B5*C3-B1*C11-B2*C12	POT2	54
	A(2,K)=B4*C9+B3*C10-B5*C4+B2*C11-B1*C12	POT2	55
23	C3=C1	POT2	56
	C4=C2	POT2	57
	C7=C5	POT2	58
	C8=C6	POT2	59
	B1=B1-D1	POT2	60
	B3=B3-D3	POT2	61
	B4=B4-D4	POT2	62
	D4=D4+DD4	POT2	63
	CM=CM*2.0	POT2	64
2	K=K+M2	POT2	65
	CM=CM+1.0	POT2	66
	DM=DM+DDM	POT2	67
3	DDM=DDM+DD	POT2	68
	DO 5 IL=1,2	POT2	69
	KI=1	POT2	70

DO 5 J=1,N	POT2	71
DO 4 I=1,M1	POT2	72
K=K1+M-1	POT2	73
4 A(IL,K)=A(IL,K)-A(IL,K-1)	POT2	74
A(IL,K1)=2.0*A(IL,K1)	POT2	75
5 K1=K1+M2	POT2	76
CM=0.0	POT2	77
DH=0.0	POT2	78
DDH=DK	POT2	79
DO 12 I=1,M	POT2	80
C7=0.0	POT2	81
C8=0.0	POT2	82
C9=0.0	POT2	83
C10=0.0	POT2	84
P1=0.0	POT2	85
P2=0.0	POT2	86
CN=1.0	POT2	87
B6=0.5*DK12	POT2	88
K=1	POT2	89
DO 10 J=1,N	POT2	90
A1=CM/CN	POT2	91
A2=DH/CN	POT2	92
IF (A1-0.2) 7,7,8	POT2	93
7 B1=2.0-A1**273.0	POT2	94
B2=-DK/(6.0*CN)	POT2	95
GO TO 9	POT2	96
8 B3= SIN(A1)/A1	POT2	97
B1=2.0*B3	POT2	98
B2=(B3- COS(A1))/A2-DH/CN*B3	POT2	99
9 B3= COS(A2)/CN	POT2	100
B4= SIN(A2)/CN	POT2	101
C3=B1*B3+B2*B4	POT2	102
C4=B2*B3-B1*B4	POT2	103
B5=DH*CN	POT2	104
C1=B5*C4-2.0*C3	POT2	105
C2=-2.0*C4-B5*C3	POT2	106
C5=C1-C7	POT2	107
C6=C2-C8	POT2	108
P3=P2-B6*CN	POT2	109
P4=P3+2.0*DK12*(CN-1.0)	POT2	110
A(1,K)=A(1,K)+C5-P1+C6+P3*C3-P4*C9	POT2	111
A(2,K)=A(2,K)+C6+P1+C5+P3*C4-P4*C10	POT2	112
P1=P1+DH	POT2	113
P2=P2+CN*DK4	POT2	114
CN=CN+2.0	POT2	115
C7=C1	POT2	116
C8=C2	POT2	117
C9=C3	POT2	118
C10=C4	POT2	119
B6=B6*DK12	POT2	120
10 K=K+M2	POT2	121
CN=CN+DK	POT2	122
DH=DH+DDH	POT2	123
12 DDH=DDH+DD	POT2	124
D3=CK/(2.0*3.14159265)	POT2	125
M1=M2-N	POT2	126
K=1	POT2	127
A1=0.0	POT2	128
DO 14 J=1,M	POT2	129
C1=D3* SIN(A1)	POT2	130
C2=-D3* COS(A1)	POT2	131
DO 13 I=1,N	POT2	132
DFE =A(1,K)*C1+A(2,K)*C2	POT2	133
A(2,K)=A(2,K)*C1-A(1,K)*C2	POT2	134
A(1,K)=DFE	POT2	135
13 K=K+1	POT2	136
K=K+M1	POT2	137
14 A1=A1+DH	POT2	138
RETURN	POT2	139
END	POT2	140

SUBROUTINE DRED(SFDX,SFDY,SFDH,KSFD,SFMX,SFMY,SFMH,KSFM,DA,T	DRED	2
,X,Y,IN,L,MLC,M,MU,NB,NEW,NH,KSFS,IPRINT)	DRED	3
DIMENSION SFDX(NB,1),SFDY(NB,MU),SFDH(NH,MU),KSFD(1)	DRED	4
,SFMX(1),SFMY(1),SFMH(1),DA(1),T(NH,1),MLC(2,1)	DRED	5
,Z(1),YY(1)	DRED	6
C	DRED	7
ERRR=1.E-06	DRED	8
IRITE=IPRINT/10	DRED	9
JAITE=IPRINT/100	DRED	10
IF(NH.LO.1) IRITE=IPRINT-10*IRITE	DRED	11
KSFD(M)=DA(98)	DRED	12
NP=KSFD(M)	DRED	13
IF(NP) 73C,17C,100	DRED	14
C	DRED	15
C	DRED	16
C	DRED	17
C	DRED	18
100 IF (NB-NP) 73C,120,120	DRED	19
120 CONTINUE	DRED	20
KP=100	DRED	21
DO 140 IP=1,NP	DRED	22
SFDX(IP,M)=DA(KP+1)/DA(24)	DRED	23
SFDY(IP,M)=DA(KP+2)/DA(24)	DRED	24
SFDH(IP,M)=DA(KP+3)	DRED	25
140 KP=KP+4	DRED	26
C	DRED	27
C	DRED	28
C	DRED	29
145 CONTINUE	DRED	29
IF(IRITE) 150,100,150	DRED	30
150 WRITE(IN,30) P	DRED	31
WRITE(IN,10)	DRED	32
C	DRED	33
100 CONTINUE	DRED	34
CALL SURFIT(NH,KSFD(M),T,SFDX(1,M),SFDY(1,M),SFDH(1,M),IRITE)	DRED	35
GO TO 200	DRED	36
C	DRED	37
PRESENTLY FOR PITCH AND PLUNGE OF FORM $Z=A_0+A_1*X$	DRED	37
170 SFDH(1,M)=DA(52)	DRED	38
SFDH(2,M)=DA(53)*DA(24)	DRED	39
SFDH(3,M)=0.0	DRED	40
GO TO 145	DRED	41
200 ICHECK=0	DRED	42
RETURN	DRED	43
730 IPR=98	DRED	44
GO TO 750	DRED	45
750 WRITE	DRED	46
C (TW,20)IPR	DRED	47
STOP	DRED	48
10 FORMAT(1H0,10X,73HCOMPUTED DEFLECTION = $A_0+A_1*X+A_2*Y$ + SUM OF $H(I)*$	DRED	49
$1(R(I)**2)+(ALCG(R(I)**2))$ )	DRED	50
20 FORMAT(1H0,10X,16HRED -- BAD DATA,15)	DRED	51
30 FORMAT(1H0,8X,26HPHYSICAL PLANE -- NODE NO.,13)	DRED	52
END	DRED	53

	SUBROUTINE	NVAL	2
	IWL,ML,HL,HEW,HST,HB,HD,ND,NR,KSFS,IPRINT)	NVAL	3
C	CALCULATES DOWNWASH VELOCITY DISTRIBUTION (REAL AND IMAGINARY)	NVAL	4
	DIMENSION XX(1),YY(1),XTDG(1),YTDG(1),XTE(1),SIZ,HB,LT,ML(1)	NVAL	5
	,SFDX(HB,LT),SFDY(HB,MD),SFDH(HM,MD),KSFO(1)	NVAL	6
	IRITE=IPRINT/10	NVAL	7
	IF(MEW.EQ.1) IRITE=IPRINT-10*IRITE	NVAL	8
	JLP=KSFO(M1)	NVAL	9
	IF(KSFO(M1).EQ.0.AND.MEW.EQ.2) JLP=KSFS	NVAL	10
	JL=ML(1)	NVAL	11
	DO 5 I=1,L	NVAL	12
	DO 5 J=1,JL	NVAL	13
	DO 5 K=1,2	NVAL	14
5	S(K,J,I)=0.0	NVAL	15
	DO 80 I=1,L	NVAL	16
	JL=ML(I)	NVAL	17
	IF(JL) 40,80,40	NVAL	18
40	CONTINUE	NVAL	19
	DO 70 J=1,JL	NVAL	20
	IF (XX(I).GT.(XTE(J)+0)) GO TO 70	NVAL	21
	CALL SURF2(XX(I),YY(J),1,1,1,VALU,VALUD,OH,SFDX(1,M1)	NVAL	22
	,SFDY(1,M1),SFDH(1,M1),JLP,2)	NVAL	23
	S(1,J,I)=VALUE	NVAL	24
	S(2,J,I)=CR*VALU	NVAL	25
70	CONTINUE	NVAL	26
80	CONTINUE	NVAL	27
	IF(IRITE) 100,200,100	NVAL	28
100	WRITE (IW,10)	NVAL	29
	WRITE (IW,12) M1	NVAL	30
10	FORMAT(1H,10X,47HUPWASH (REAL, IMAGINARY, ABSOLUTE, PHASE ANGLE))	NVAL	31
12	FORMAT(1H+,58X,28H---PHYSICAL PLANE---MODE NO.,13/)	NVAL	32
	DO 170 I=1,L	NVAL	33
	JL=ML(I)	NVAL	34
	IF (JL) 110,170,110	NVAL	35
110	WRITE (IW,20) I	NVAL	36
	JLP=JL/2	NVAL	37
	IF(JL-2*JLP.NE.0) JLP=JLP+1	NVAL	38
	DO 160 J=1,JLP	NVAL	39
	S1=SQRT(S(1,J,I)*S(1,J,I)+S(2,J,I)*S(2,J,I))	NVAL	40
	IF(S1.GT.0.0) GO TO 120	NVAL	41
	S2=0.0	NVAL	42
	GO TO 130	NVAL	43
120	S2=57.29578*ATAN2(S(2,J,I),S(1,J,I))	NVAL	44
130	J1=J+JLP	NVAL	45
	IF(JL.LE.JL) GO TO 160	NVAL	46
	J1=0	NVAL	47
	S3=0.0	NVAL	48
	S4=0.0	NVAL	49
	GO TO 160	NVAL	50
150	CONTINUE	NVAL	51
	S3=SQRT(S(1,J1,I)*S(1,J1,I)+S(2,J1,I)*S(2,J1,I))	NVAL	52
	IF(S3.GT.0.0) GO TO 160	NVAL	53
	S4=0.0	NVAL	54
	GO TO 160	NVAL	55
155	S4=57.29578*ATAN2(S(2,J1,I),S(1,J1,I))	NVAL	56
160	WRITE (IW,25) J,S(1,J,I),S(2,J,I),S1,S2,J1,S(1,J1,I),S(2,J1,I),S3,S4	NVAL	57
170	CONTINUE	NVAL	58
C	THESE ARE THE UPWASHES	NVAL	59
C		NVAL	60
200	CONTINUE	NVAL	61
	RETURN	NVAL	62
20	FORMAT(1H0,5X,12,19H---TH SPANWISE COLUMN)	NVAL	63
25	FORMAT(1H+,5X,2(2X,13,1P4E13.5))	NVAL	64
	END	NVAL	65

	SUBROUTINE BOXP(XX,YY,XTDG,YTDG,XTE,XLE,A,AR,DAN,T,EDG,S,CK,D,YE	BOXP	2
1	,IPRINT,MLY,MLC,AMA	BOXP	3
2	,JMAX,L,ML,MLW,MI,NEW,NST,IW,MB,MC,ME,MD)	BOXP	4
C	ICHECK=0 - POTENTIAL AS COMPUTED IN BOXP	BOXP	5
C	ICHECK=1 - WITH LEADING EDGE CORRECTION	BOXP	6
C	ICHECK=2 - PRESSURE COEFFICIENT COMPUTED FROM CORRECTED POTENTIAL	BOXP	7
C	ICHECK=3 - PRESSURE COEFFICIENT COMPUTED FROM TRANSFORMED VALUE	BOXP	8
C	FOR PHYSICAL WING	BOXP	9
	DIMENSION XX(1),YY(1),XTDG(1),YTDG(1),XTE(1),XLE(1),A(2,MC,MB)	BOXP	10
1	,AM(MB,1),CDG(1),S(2,MB,MB),T(ME,ME,1)	BOXP	11
2	,ML(1),MLW(1),MLT(2,1),MLC(2,MB),AMA(MB,MB)	BOXP	12
	IPRIN=IPRINT	BOXP	13
	KRITE=IPRIN/ICCG	BOXP	14
	IPRIN=IPRIN-ICCG*KRITE	BOXP	15
	JRITE=IPRIN/ICG	BOXP	16
	IPRIN=IPRIN-ICG*JRITE	BOXP	17
	IRITE=IPRIN	BOXP	18
	IF(NEW.EQ.1) GO TO 140	BOXP	19
	KRITE=KRITE/10	BOXP	20
	JRITE=JRITE/10	BOXP	21
	IRITE=IRITE/10	BOXP	22
	GO TO 150	BOXP	23
140	KRITE=KRITE-(KRITE/10)*10	BOXP	24
	JRITE=JRITE-(JRITE/10)*10	BOXP	25
	IRITE=IRITE-(IRITE/10)*10	BOXP	26
150	CONTINUE	BOXP	27
	NSMOS=0	BOXP	28
	DH=C.5*0	BOXP	29
C	CALL BOXP(XX,YY,XTDG,YTDG,XTE,A,AR,DAN,T,S,CK,D,AMA	BOXP	30
3	,IWL,L,MB,MC,ML,NLC,MLW,MI,NEW,NST,JRITE)	BOXP	31
		BOXP	32
C	BOXP COMPUTES THE POTENTIAL VALUES IN EACH BOX.	BOXP	33
C	THEY ARE STORED IN THE ARRAY'S.	BOXP	34
C		BOXP	35
	ICHECK=0	BOXP	36
	NEW=NEW	BOXP	37
	JMAX=JMAX	BOXP	38
	IF(IRITE.EQ.0) GO TO 270	BOXP	39
	WRITE(IW,30)	BOXP	40
200	DO 205 I=1,L	BOXP	41
	DO 205 J=1,JMAX	BOXP	42
	DO 205 K=1,2	BOXP	43
205	T(J,I,K)=S(K,J,I)	BOXP	44
215	WRITE(IW,32) #1	BOXP	45
30	FORMAT(IH1,IGX,6HPOTENTIAL CALCULATED (REAL, IMAGINARY, ABSOLUTE,	BOXP	46
	\$ PHASE ANGLE))	BOXP	47
32	FORMAT(IH+,7IX,28H---PHYSICAL PLANE---MODE NO.,13/)	BOXP	48
C	PRINT-OUT	BOXP	49
218	DO 250 I=1,L	BOXP	50
	JL=ML(I)	BOXP	51
	IF (JL) 220,250,220	BOXP	52
220	WRITE(IW,20) I	BOXP	53
	JLP=JL/2	BOXP	54
	IF(JL-2*JLP.NE.0) JLP=JLP+1	BOXP	55
	DO 240 J=1,JLP	BOXP	56
	S1=SQRT(T(J,I,1)*T(J,I,1)+T(J,I,2)*T(J,I,2))	BOXP	57
	IF(S1.NE.0.C) GO TO 224	BOXP	58
	S2=0.0	BOXP	59
	GO TO 226	BOXP	60
224	CONTINUE	BOXP	61
	S2=57.29578*ATAN2(T(J,I,2),T(J,I,1))	BOXP	62
226	CONTINUE	BOXP	63
	J1=J+JLP	BOXP	64
	IF(J1.LE.JL) GO TO 230	BOXP	65
	J1=0	BOXP	66
	S3=0.0	BOXP	67
	S4=0.	BOXP	68
	T(J1,I,1)=0.0	BOXP	69
		BOXP	70

	T(J1,I,2)=0.0	BOXP	71
	GO TO 245	BOXP	72
230	CONTINUE	BOXP	73
	S3=5.0*T(T(J1,I,1))+T(J1,I,1)+T(J1,I,2)+T(J1,I,2)	BOXP	74
	IF(S3.NE.0.0) GO TO 234	BOXP	75
	S4=0.0	BOXP	76
	GO TO 236	BOXP	77
234	CONTINUE	BOXP	78
	S4=7.07-7.07*TAN(1/(J1,I,2),T(J1,I,1))	BOXP	79
236	CONTINUE	BOXP	80
240	WRITE(IH,25) J,T(J,I,1),T(J,I,2),S1,S2	BOXP	81
	* J1,T(J1,I,1),T(J1,I,2),S3,S4	BOXP	82
250	CONTINUE	BOXP	83
C		BOXP	84
270	CONTINUE	BOXP	85
	IF(ICHECK.GE.1) GO TO 400	BOXP	86
C	LEADING EDGE CORRECTION	BOXP	87
	DO 300 J=1,JMAX	BOXP	88
	IF (MLT(1,J).EQ.0) GO TO 285	BOXP	89
	I1=MLT(1,J)	BOXP	90
	I2=MLT(2,J)	BOXP	91
	S3=0.0	BOXP	92
	DO 280 I=I1,I2	BOXP	93
	K=1	BOXP	94
	IF (AR(J,I).GE.1.0) GO TO 290	BOXP	95
280	CONTINUE	BOXP	96
285	S3=0	BOXP	97
290	IF(K.EQ.1) S3=0	BOXP	98
	S3=XX(K)-XLE(J)-DH+S3	BOXP	99
	DO 370 I=1,L	BOXP	100
	S1=(XX(I)-XLE(J))/S3	BOXP	101
	IF(S1) 300,340,310	BOXP	102
300	S1=0.0	BOXP	103
	GO TO 340	BOXP	104
310	IF(YE) 320,320,330	BOXP	105
320	S1=S1+(XX(I)+XLE(J))/(S3+2.*XLE(J))	BOXP	106
330	IF(S1.GT.1.0) S1=1.0	BOXP	107
	S1=EDG(J)*SQRT(S1)	BOXP	108
340	DO 350 K=1,2	BOXP	109
350	S(K,J,I)=S1*S(K,J,I)	BOXP	110
370	CONTINUE	BOXP	111
380	CONTINUE	BOXP	112
	ICHECK=1	BOXP	113
	IF(IRITE) 390,400,390	BOXP	114
390	WRITE(IH,36)	BOXP	115
36	FORMAT(IH1,10X,61HPOTENTIAL CORRECTED (REAL, IMAGINARY, ABSOLUTE,	BOXP	116
	\$ PHASE ANGLE))	BOXP	117
C	TRANSFER TO THE PRINT-OUT OF CORRECTED VELOCITY POTENTIAL	BOXP	118
	GO TO 200	BOXP	119
400	CONTINUE	BOXP	120
	IF(IRITE.EQ.0) GO TO 700	BOXP	121
	IF(ICHECK.GE.2) GO TO 520	BOXP	122
C	CALCULATE AND PRINT PRESSURE COEFFICIENT	BOXP	123
	ICHECK=2	BOXP	124
	DO 410 I=1,L	BOXP	125
	JL=ML(I)	BOXP	126
	DO 410 J=1,JL	BOXP	127
	T(J,I,3)=S(1,J,I)	BOXP	128
410	T(J,I,4)=S(2,J,I)	BOXP	129
420	JMAX=JMAX	BOXP	130
	DO 430 I=1,L	BOXP	131
	JL=ML(I)	BOXP	132
	DO 430 J=1,JL	BOXP	133
	DO 430 K=1,2	BOXP	134
430	T(J,I,K)=0.0	BOXP	135
	DO 500 J=1,JMAX	BOXP	136
	I1=MLT(1,J)	BOXP	137
	I2=MLT(2,J)-MLT(1,J)+1	BOXP	138
	I=I1	BOXP	139
	IK=I2+1	BOXP	140

T(1, 6,5)=XLE(J)	BOXP	141
T(1, 8,5)=XLE(J)	BOXP	142
T(1,10,5)=0.0	BOXP	143
T(1,12,5)=0.0	BOXP	144
IF (ABS(XLE(J)-XX(I))) .GT. 1.E-05) GO TO 445	BOXP	145
C ADJUSTMENT -- LEADING EDGE AND FIRST BOX COINCIDES	BOXP	146
II=II+1	BOXP	147
IK=IK-1	BOXP	148
445 CONTINUE	BOXP	149
DO 450 I=2,IK	BOXP	150
T(I, 6,5)=XX(I)	BOXP	151
T(I, 8,5)=XX(I)	BOXP	152
T(I,10,5)=T(J,II,3)	BOXP	153
T(I,12,5)=T(J,II,4)	BOXP	154
T(I-1,1,5)=XX(II)	BOXP	155
450 II=II+1	BOXP	156
CALL SPLNI(I2,T(1, 1,5),T(1, 2,5),T(1, 4,5)	BOXP	157
,IK,T(1, 6,5),T(1,10,5),T(1,14,5),NSMOS)	BOXP	158
CALL SPLNI(I2,T(1, 1,5),T(1, 3,5),T(1, 5,5)	BOXP	159
,IK,T(1, 8,5),T(1,12,5),T(1,14,5),NSMOS)	BOXP	160
II=II	BOXP	161
DO 470 I=1,I2	BOXP	162
T(J,II,1)=T(I,4,5)-CK*T(I,3,5)	BOXP	163
T(J,II,2)=T(I,5,5)+CK*T(I,2,5)	BOXP	164
470 II=II+1	BOXP	165
500 CONTINUE	BOXP	166
WRITE(IH,40)	BOXP	167
40 FORMAT(1H1,10X,61HPRESSURE COEFFICIENT (REAL, IMAGINARY, ABSOLUTE,	BOXP	168
PHASE ANGLE))	BOXP	169
C TRANSFER TO PRINT-OUT SECTION	BOXP	170
GO TO 215	BOXP	171
520 CONTINUE	BOXP	172
700 CONTINUE	BOXP	173
RETURN	BOXP	174
20 FORMAT(1H0,5X,I2,19H--TH SPANWISE COLUMN)	BOXP	175
25 FORMAT(1H ,5X,2(2X,I3,1P4E13.5))	BOXP	176
END	BOXP	177

	PROGRAM CODE	STATEMENT	BOXPO	LINE NO.
		SUBROUTINE BOXPO(XX,YY,XTDG,YTDG,XTE,A,AR,DAN,T,S,CK,D,AMA	BOXPO	2
		,IW,L,MB,MC,ML,MLC,MLH,HI,NEH,NST,JRITE)	BOXPO	3
C		SOLUTION OF SIMULTANEOUS EQUATIONS FOR THE POTENTIAL	BOXPO	4
		DIMENSION XX(1),YY(1),XTDG(1),YTDG(1),XTE(1),A(2,MC,1)	BOXPO	5
	1	,AR(MB,MB),T(2,MB,1),S(2,MB,1),AMA(MB,MB)	BOXPO	6
	2	,ML(1),MLC(2,1),MLH(1)	BOXPO	7
		DH=0.5*D	BOXPO	8
		DD=2.0*D	BOXPO	9
		LI=2+2*ML(L)	BOXPO	10
		IF(JRITE.EQ.0) GO TO 25	BOXPO	11
		IF(NEH.EQ.2.OR.ML.GT.1) GO TO 25	BOXPO	12
C		PRINT INFLUENCE COEFFICIENT	BOXPO	13
		WRITE(IW,100)	BOXPO	14
		JL=2*ML(L)	BOXPO	15
		K=JL/4	BOXPO	16
		IF(JL-4*K.NE.0) K=K+1	BOXPO	17
		DO 20 I=1,L	BOXPO	18
		II=I-1	BOXPO	19
		WRITE(IW,110) II	BOXPO	20
		DO 15 JI=1,K	BOXPO	21
	15	WRITE(IW,120) ((J,A(1,J,I),A(2,J,I)),J=J1,JL,K)	BOXPO	22
	20	CONTINUE	BOXPO	23
	25	CONTINUE	BOXPO	24
		II=NST	BOXPO	25
		AMI=1.0	BOXPO	26
		DO 26 I=1,II	BOXPO	27
	26	AMI=AMINI(XTDG(II),AMI)	BOXPO	28
C		IF(JRITE.EQ.0) GO TO 28	BOXPO	29
		WRITE(IW,168)	BOXPO	30
	28	CONTINUE	BOXPO	31
		II=0	BOXPO	32
		MFLNS = DAN	BOXPO	33
		DO 90 I=1,L	BOXPO	34
		X=XX(I)	BOXPO	35
C		ADJUST UPSTREAM INFLUENCE	BOXPO	36
		KO = 1	BOXPO	37
		IF(MFLNS.EQ.0) GO TO 30	BOXPO	38
		KO = MAX(1,I-MFLNS+1)	BOXPO	39
	30	CONTINUE	BOXPO	40
		JL=ML(II)	BOXPO	41
		IF (JL.EQ.0) GO TO 90	BOXPO	42
C		DEFINE WING AND WAKE BOXES	BOXPO	43
C		JW=NO. OF WAKE BOXES IN ROW	BOXPO	44
C		JE=NO. OF WING BOXES	BOXPO	45
C		JS=ORDER OF FIRST WING BOX	BOXPO	46
C		JN=ORDER OF LAST WING BOX	BOXPO	47
C		JSW=ORDER OF FIRST WAKE BOX	BOXPO	48
C		JNW=ORDER OF LAST WAKE BOX	BOXPO	49
		JW=0	BOXPO	50
		IF(X.LE.AMI) GO TO 34	BOXPO	51
		J=1	BOXPO	52
	32	IF(J.GT.JL) GO TO 34	BOXPO	53
		IF (X.LE.(XTE(J)+DH)) GO TO 33	BOXPO	54
		JW=JW+1	BOXPO	55
	33	J=J+1	BOXPO	56
		GO TO 32	BOXPO	57
	34	JE=JL-JW	BOXPO	58
		IF (MLH(II)) 36,35,35	BOXPO	59
	35	JS = JW+1	BOXPO	60
		JSW=1	BOXPO	61
		GO TO 37	BOXPO	62
	36	JS = 1	BOXPO	63
		JSW=JE +1	BOXPO	64
	37	JN = JS +JE-1	BOXPO	65
		JNW=JS# +JW-1	BOXPO	66
		IF (II.EQ.0) GO TO 50	BOXPO	67
C		SUBTRACTION OF CONTRIBUTIONS OF PRECEDING ROWS TO UPWASH	BOXPO	68
		GO 47 J=JS,JN	BOXPO	69
			BOXPO	70



DO 45 K=KQ,I1	BOXPO	71
KL=ML(K)	BOXPO	72
K1=I+I-K	BOXPO	73
IF (ML.EQ.0) GO TO 45	BOXPO	74
DO 40 N=1,K'	BOXPO	75
IF (NEM.EQ.2) GO TO 38	BOXPO	76
N1=N+J	BOXPO	77
N2=IABS(N-J)+1	BOXPO	78
A1=A(1,N1,K1)+A(1,N2,K1)	BOXPO	79
A2=A(2,N1,K1)+A(2,N2,K1)	BOXPO	80
GO TO 39	BOXPO	81
38 CONTINUE	BOXPO	82
TEMP=(AMA(J,I)+AMA(N,K))/DD	BOXPO	83
YM1=(YY(J)+YY(N))*TEMP	BOXPO	84
YM2=(YY(J)-YY(N))*TEMP	BOXPO	85
YM2=ABS(YM2)	BOXPO	86
N1=YM1	BOXPO	87
N2=YM2	BOXPO	88
YM1=YM1-FLOAT(N1)	BOXPO	89
YM2=YM2-FLOAT(N2)	BOXPO	90
N1=N1+1	BOXPO	91
N2=N2+1	BOXPO	92
IF (N1.GT.LIM2) GO TO 138	BOXPO	93
ARN10=A(1,N1,K1)	BOXPO	94
AIN10=A(2,N1,K1)	BOXPO	95
IF (N1+1.GT.LIM2) GO TO 238	BOXPO	96
ARN11=A(1,N1+1,K1)	BOXPO	97
AIN11=A(2,N1+1,K1)	BOXPO	98
GO TO 338	BOXPO	99
138 ARN10=A(1,LIM2,K1)	BOXPO	100
AIN10=A(2,LIM2,K1)	BOXPO	101
238 ARN11=A(1,LIM2,K1)	BOXPO	102
AIN11=A(2,LIM2,K1)	BOXPO	103
338 CONTINUE	BOXPO	104
ARN20=A(1,N2,K1)	BOXPO	105
AIN20=A(2,N2,K1)	BOXPO	106
ARN21=A(1,N2+1,K1)	BOXPO	107
AIN21=A(2,N2+1,K1)	BOXPO	108
A1=ARN10+(ARN11-ARN10)*YM1+ARN20+(ARN21-ARN20)*YM2	BOXPO	109
A2=AIN10+(AIN11-AIN10)*YM1+AIN20+(AIN21-AIN20)*YM2	BOXPO	110
A1=A1*AMA(N,K)	BOXPO	111
A2=A2*AMA(N,K)	BOXPO	112
39 CONTINUE	BOXPO	113
WT=1.0	BOXPO	114
IF (N.GE.MLC(2,K).AND.MLC(2,K).NE.0) WT=AR(N,K)	BOXPO	115
S(1,J,I)=S(1,J,I)-(A1*S(1,N,K)-A2*S(2,N,K1))*WT	BOXPO	116
40 S(2,J,I)=S(2,J,I)-(A2*S(1,N,K)+A1*S(2,N,K1))*WT	BOXPO	117
45 CONTINUE	BOXPO	118
47 CONTINUE	BOXPO	119
C SETTING UP MATRIX FOR SIMULTANEOUS EQUATIONS	BOXPO	120
50 DO 52 J=1,JL	BOXPO	121
DO 52 K=1,JL	BOXPO	122
N1=J+K	BOXPO	123
N2=IABS(J-K)+1	BOXPO	124
WT=1.0	BOXPO	125
IF (K.GE.MLC(2,I).AND.MLC(2,I).NE.0) WT=AR(K,I)	BOXPO	126
C	BOXPO	127
IF (J.EQ.K) WT=1.0	BOXPO	128
C	BOXPO	129
T(1,J,K)=(A(1,N1,I)+A(1,N2,I))*WT	BOXPO	130
T(2,J,K)=(A(2,N1,I)+A(2,N2,I))*WT	BOXPO	131
52 CONTINUE	BOXPO	132
C SUBTRACTION OF CONTRIBUTION	BOXPO	133
C FROM WAKE BOXES -- S(WING)=	BOXPO	134
C S(WING)=T(WAKE)*PHI(WAKE)	BOXPO	135
IF (JW.EQ.0) GO TO 60	BOXPO	136
DO 56 J=JS,JN	BOXPO	137
DO 55 N=JSH,JMW	BOXPO	138
S(1,J,I)=S(1,J,I)-T(1,J,N)*S(1,N,I)+T(2,J,N)*S(2,N,I)	BOXPO	139
55 S(2,J,I)=S(2,J,I)-T(1,J,N)*S(2,N,I)+T(2,J,N)*S(1,N,I)	BOXPO	140

	56 CONTINUE	BOXPO	141
	IF (MLW(I).LT.0) GO TO 60	BOXPO	142
C	RE-POSITION ELEMENTS OF Y	BOXPO	143
	DO 59 N=1,JE	BOXPO	144
	NW=N+JW	BOXPO	145
	DO 58 J=1,JE	BOXPO	146
	MW=J+JW	BOXPO	147
	DO 58 K=1,2	BOXPO	148
	Y(K,J,N)=Y(K,MW,NW)	BOXPO	149
	59 CONTINUE	BOXPO	150
C	SOLUTION OF EQUATIONS	BOXPO	151
C	60 CONTINUE	BOXPO	152
C	IF (WRITE.EQ.0) GO TO 72	BOXPO	154
	WRITE(IH,167) I	BOXPO	155
	DO 70 K=1,2	BOXPO	156
	N1=1	BOXPO	157
	N2=N1+3	BOXPO	158
	DO 67 J=1,JE	BOXPO	159
	67 WRITE(IW,169) (J,N,(K,J,N),N=N1,N2)	BOXPO	160
	IF (N2.GE.JE) GO TO 68	BOXPO	161
	N1=N2+1	BOXPO	162
	N2=N1+3	BOXPO	163
	GO TO 66	BOXPO	164
	68 CONTINUE	BOXPO	165
	DO 69 J=1,JE	BOXPO	166
	WRITE(IW,170) K,J,1,(K,J,1)	BOXPO	167
	69 CONTINUE	BOXPO	168
	70 CONTINUE	BOXPO	169
	167 FORMAT(IH0,5X,I2,1,M-TH SPANWISE COLUMN)	BOXPO	170
	168 FORMAT(IH1,10X,64H)EFFICIENT MATRIX (A) OF (A)*(X)=(B) FOR VELO	BOXPO	171
	SICITY POTENTIAL (X) ALONG EACH COLUMN//)	BOXPO	172
	169 FORMAT(8X,4(2X,1H(,I2,1H,,I2,2H) ,E13.6))	BOXPO	173
	170 FORMAT(9X,2HS(,I2,1H,,I2,1H,,I2,2H)=,E13.6)	BOXPO	174
	72 CONTINUE	BOXPO	175
C	K = MSIMEC(MB,JE,I,T,S(1,JS,I))	BOXPO	176
	IF (K.NE.1) GO TO 90	BOXPO	177
C	COMPUTE WAKE POTENTIALS --	BOXPO	180
C	PHI(TE)*EXP(-IK*(X-XTE))	BOXPO	181
	IF (X.LL.(AMI-D)) GO TO 85	BOXPO	182
	JS=1	BOXPO	183
	75 Y=YY(JS)	BOXPO	184
	IF (X.LT.(XTE(JS)-DH)) GO TO 82	BOXPO	185
	IF (X.GE.(XTE(JS)+DH)) GO TO 82	BOXPO	186
	IF (X.GT.XTE(JS)) GO TO 76	BOXPO	187
	PTR=S(1,JS,I)	BOXPO	188
	PTI=S(2,JS,I)	BOXPO	189
	KK=1	BOXPO	190
	XB=X+D	BOXPO	191
	GO TO 77	BOXPO	192
	76 P=(X-XTE(JS))/C	BOXPO	193
	PTR=(1.0-P)*S(1,JS,I)+P*S(1,JS,I-1)	BOXPO	194
	PTI=(1.0-P)*S(2,JS,I)+P*S(2,JS,I-1)	BOXPO	195
	KK=0	BOXPO	196
	XB=X	BOXPO	197
	77 CONTINUE	BOXPO	198
	80 IF (XB.GT.1.0) GO TO 82	BOXPO	199
	XW=(XB-XTE(JS))*CK	BOXPO	200
	IKW=I+KK	BOXPO	201
	S(1,JS,IKW)=PTR*COS(XW)+PTI*SIN(XW)	BOXPO	202
	S(2,JS,IKW)=PTI*COS(XW)-PTR*SIN(XW)	BOXPO	203
	KK=KK+1	BOXPO	204
	XB=XB+D	BOXPO	205
	GO TO 80	BOXPO	206
	82 JS=JS+1	BOXPO	207
	IF (JS.LE.JL) GO TO 75	BOXPO	208
	85 CONTINUE	BOXPO	209
	90 II=II+1	BOXPO	210

RETURN	BOXPO	211
95 WRITE (17,140)	BOXPO	212
STOP	BOXPO	213
100 FORMAT(1H1,20X-42HINFLUENCE COEFFICIENT (REAL AND IMAGINARY)///)	BOXPO	214
110 FORMAT(1H0,3X,13,38H-BOX SEPARATION IN CHORDWISE DIRECTION)	BOXPO	215
120 FORMAT(1H ,5X,4(1X,1P2E13.6))	BOXPO	216
140 FORMAT(1H010X,59HSOLUTION OF SIMULTANEOUS EQUATIONS FOR THE POTENT	BOXPO	217
IAL FAILED)	BOXPO	218
END	BOXPO	219

	SUBROUTINE FORCI(KX,YY,S,SFDX,SFDY,SFDH,KSF,KSFS,XLE,XTE,YMAX	FORCI	2
1	,AMA,JMAK,MLT,L,NEW,MZ,MB,MD,NB,NH,CK,T)	FORCI	3
	DIMENSION MLT(2,MB),XLE(MB),XTE(MB),XX(MB),YY(MB),S(2,MB,MB),	FORCI	4
1	,SFDX(MB,MD),SFDY(MB,MD),SFDH(MB,MD),KSF(MD),T(NH,1)	FORCI	5
2	,AMA(MB,MB)	FORCI	6
C		FORCI	7
	N=0	FORCI	8
C	NO SMOOTHING IN SUBROUTINE SMOOTH. (SPLN1)	FORCI	9
	D=XX(2)-XX(1)	FORCI	10
	MZ=KSFS(MZ)	FORCI	11
	IF((KSFS(MZ).EQ.0.AND.NEW.EQ.2) MZ=KSFS	FORCI	12
	DO 150 J=1,JMAX	FORCI	13
	MLT1=MLT(1,J)	FORCI	14
	NZ=MLT(2,J)-MLT1+2	FORCI	15
	NC=NZ+1	FORCI	16
	K1=1	FORCI	17
	K2=4	FORCI	18
	KC=0	FORCI	19
	T(1,1)=XTE(J)	FORCI	20
40	KK=MLT1	FORCI	21
	T(1,2)=XLE(J)	FORCI	22
	T(1,K2)=0.0	FORCI	23
	KA=	FORCI	24
	KB=N	FORCI	25
	IF(K1.EQ.3.OR.NZ.EQ.2) GO TO 45	FORCI	26
	IF(NC.EQ.2) GO TO 45	FORCI	27
C	EXCLUDE LEADING EDGE POINT IF IT IS TOO CLOSE TO FIRST BOX	FORCI	28
	IF (YA(KK)-XLE(J).GT.0.2*D) GO TO 45	FORCI	29
	KA=1	FORCI	30
	KB=NZ-1	FORCI	31
	NC=1	FORCI	32
45	CONTINUE	FORCI	33
	DO 50 K=KA,KB	FORCI	34
	T(K,2)=YA(KK)	FORCI	35
	IF(K1.EQ.3) GO TO 50	FORCI	36
	T(K,K2)=S(K1,J,KK)	FORCI	37
50	KK=KK+1	FORCI	38
	IF(KC.EQ.2) GO TO 51	FORCI	39
	IF(K1.EQ.3) GO TO 50	FORCI	40
	CALL SPLN1(1,T(1,1),T(1,8),T(1,9),KB,T(1,2),T(1,K2),T(1,10),N)	FORCI	41
	T(NC,K2)=T(1,8)	FORCI	42
	IF(KC.NE.1) GO TO 51	FORCI	43
	NC=2	FORCI	44
	GO TO 40	FORCI	45
51	CONTINUE	FORCI	46
C		FORCI	47
	IF(NZ.GT.2) GO TO 52	FORCI	48
C	ADJUSTMENT FOR TRAILING EDGE VELOCITY POTENTIAL	FORCI	49
	KK=MLT(2,J)	FORCI	50
	DUM=SQRT((XTE(J)-XLE(J))/(XX(KK)-XLE(J)))	FORCI	51
	T(NC,K2)=DUM*T(NZ,K2)	FORCI	52
52	CONTINUE	FORCI	53
C		FORCI	54
	KC=0	FORCI	55
	IF(K1.EQ.2) GO TO 55	FORCI	56
	K1=2	FORCI	57
	K2=6	FORCI	58
	GO TO 40	FORCI	59
55	K1=3	FORCI	60
	GO TO 40	FORCI	61
60	T(NC,2)=XTE(J)	FORCI	62
	IF (ABS(XLE(J)-XX(MLT1)).GT.1.E-05) GO TO 67	FORCI	63
C	LEADING EDGE AND FIRST BOX COINCIDE	FORCI	64
	NZ=NZ-1	FORCI	65
	NC=NC-1	FORCI	66
	DO 65 K=2,NC	FORCI	67
	T(K,2)=T(K+1,2)	FORCI	68
	T(K,4)=T(K+1,4)	FORCI	69
	T(K,6)=T(K+1,6)	FORCI	70

	IF (NEW,1,1) GC TO 165	FORCI	71
	T(K,12)=T(K+1,12)	FORCI	72
65	CONTINUE	FORCI	73
67	CONTINUE	FORCI	74
C		FORCI	75
C	INTERPOLATE DEFLECTION AT BOX CENTER, LEADING AND TRAILING EDGES	FORCI	76
	CALL SURFZ(YY(J),T(1,1),1,NQ,2,T(1,13),T(1,14),DUM,SFDX(1,M2)	FORCI	77
	5 SFDY(1,M2),SFDZ(1,M2),RZ,2)	FORCI	78
C	PERFORM CHORDWISE INTEGRATION	FORCI	79
	DC 75 K=1,NQ	FORCI	80
	T(K,12)=T(K,14)*T(K,4)+CK*T(K,13)*T(K,6)	FORCI	81
75	T(K,16)=T(K,14)*T(K,6)-CK*T(K,13)*T(K,4)	FORCI	82
	CALL INTGL(T(1,1),T(1,15),T(1,1),T(1,19),2,NQ,NZ,NM)	FORCI	83
	DUM=T(NQ,13)	FORCI	84
	T(J,17)=T(NQ,4)*DUM-T(J,17)	FORCI	85
	T(J,18)=T(NQ,6)*DUM-T(J,18)	FORCI	86
150	CONTINUE	FORCI	87
C	PERFORM SPANWISE INTEGRATION	FORCI	88
	NQ=JMAK+2	FORCI	89
	K1=17	FORCI	90
	K2=15	FORCI	91
	T(1,1)=0.0	FORCI	92
165	DC 170 K=1,JMAK	FORCI	93
170	T(K,2)=YY(K)	FORCI	94
	NZ=JMAK	FORCI	95
	CALL SFLN1(1,T(1,1),T(1,5),T(1,9),NZ,T(1,2),T(1,K1),T(1,10),N)	FORCI	96
	T(NQ,K2)=0.0	FORCI	97
	T(1,K2)=T(1,6)	FORCI	98
	DC 175 K=1,JMAK	FORCI	99
175	T(K+1,K2)=T(K,K1)	FORCI	100
	IF (K1.EQ.16) GC TO 180	FORCI	101
	K1=18	FORCI	102
	K2=16	FORCI	103
	GO TO 165	FORCI	104
180	CONTINUE	FORCI	105
	NZ=JMAK+1	FORCI	106
	T(1,2)=0.0	FORCI	107
	T(NQ,2)=YMAX	FORCI	108
	DC 185 K=1,JMAK	FORCI	109
185	T(K+1,2)=YY(K)	FORCI	110
C	WING TIP CORRECTION	FORCI	111
	K1=0	FORCI	112
	XD=T(NQ,2)-T(NZ-1,2)	FORCI	113
	PR=T(NZ-1,15)	FORCI	114
	PI=T(NZ-1,16)	FORCI	115
	IF (T(NZ,2)+.5*D.LT.T(NQ,2)) GO TO 195	FORCI	116
190	DUM=SQRT((T(NC,2)-T(NZ,2))/XD)	FORCI	117
	T(NZ,15)=DUM*PR	FORCI	118
	T(NZ,16)=DUM*PI	FORCI	119
	IF (K1.EQ.1) GC TO 196	FORCI	120
195	IF (YY(JMAK)+1.05*D.GE.YMAX) GO TO 196	FORCI	121
	K1=1	FORCI	122
	NZ=NZ+1	FORCI	123
	NQ=NQ+1	FORCI	124
	T(NQ,2)=T(NQ-1,2)	FORCI	125
	T(NZ,2)=T(NZ-1,2)+D	FORCI	126
	T(NQ,15)=T(NQ-1,15)	FORCI	127
	T(NQ,16)=T(NQ-1,16)	FORCI	128
	GO TO 190	FORCI	129
196	CONTINUE	FORCI	130
	IF (ABS(T(NQ,2)-T(NZ,2)).GE.1.E-05) GO TO 197	FORCI	131
	NQ=NQ-1	FORCI	132
	NZ=NZ-1	FORCI	133
	T(NQ,2)=T(NQ+1,2)	FORCI	134
	T(NQ,15)=T(NQ+1,15)	FORCI	135
	T(NC,16)=T(NQ+1,16)	FORCI	136
197	CONTINUE	FORCI	137
C		FORCI	138
	CALL INTGL(T(1,2),T(1,15),T(1,1),T(2,1),T(1,19),2,NQ,NZ,NM)	FORCI	139
	RETURN	FORCI	140
	END	FORCI	141

	SUBROUTINE MRED(DA,T,NM,NB,KSFM,SFMX,SFMY,SFMH,IN,IPRINT)	MRED	2
C	SPLINE-SURFACE FIT OF MACH NUMBER	MRED	3
	DIMENSION DA(1),I(NM,1),SFMX(1),SFMY(1),SFMH(1)	MRED	4
	CONST=0.28571429	MRED	5
	KSFM=DA(7)	MRED	6
	IF(KSFM) 80,50,10	MRED	7
C		MRED	8
C	FITTING OF GIVEN PRESSURE/MACH TO A SPLINE-SURFACE	MRED	9
C		MRED	10
	10 IF(NB-KSFM) 80,15,15	MRED	11
	15 CONTINUE	MRED	12
	KP=701	MRED	13
	DO 30 IP=1,KSFM	MRED	14
	SFMX(IP)=DA(KP )/DA(24)	MRED	15
	SFMY(IP)=DA(KP+1)/DA(24)	MRED	16
	SFMH(IP)=DA(KP+2)	MRED	17
C	DA(96)=1, IMPLT DATA ARE PRESSURE COEFFICIENT	MRED	18
C	DA(96)=2, INPUT DATA ARE LOCAL MACH NUMBER	MRED	19
	IF(DA(96)-1.0) 75,20,25	MRED	20
C	CONVERT PRESSURE COEFFICIENT INTO LOCAL MACH NUMBER	MRED	21
	20 SFMH(IP)=SQRT(5.*(1.2/((1.+0.7*SFMH(IP))*CONST)-1.))	MRED	22
	25 CONTINUE	MRED	23
	30 KP=KP+3	MRED	24
C	SPLINE-SURFACE FITTING OF DATA	MRED	25
	40 CONTINUE	MRED	26
	IF(IPRINT.NE.C) WRITE(IN,100)	MRED	27
	CALL SURF1(NM,KSFM,T,SFMX,SFMY,SFMH,IPRINT)	MRED	28
	RETURN	MRED	29
C		MRED	30
C	PRESENTLY IMPLT OF PRESSURE COEFFICIENT IN	MRED	31
C	A POLYNOMIAL FORM IS NOT ALLOWED	MRED	32
C	THE FOLLOWING IS FOR MACH INPUT AS A POLYNOMIAL $M=A0+A1*X$	MRED	33
	50 CONTINUE	MRED	34
	KSFM=0	MRED	35
	SFMH(1)=JA(71)	MRED	36
	SFMH(2)=DA(72)*DA(24)	MRED	37
	SFMH(3)=0.0	MRED	38
	GO TO 40	MRED	39
C		MRED	40
	75 IPR=96	MRED	41
	GO TO 85	MRED	42
	80 IPR=97	MRED	43
	85 WRITE	MRED	44
	(IN,110)IPR	MRED	45
	STOP	MRED	46
	100 FORMAT(1H0,10X,73HCOMPUTED MACH(X,Y) = A0+A1*X+A2*Y+ SUM OF H(I)*	MRED	47
	(R(I)**2)*(ALCG(R(I)**2)))	MRED	48
	110 FORMAT(1H0,10X,14HMRED--BAD DATA,15)	MRED	49
	END	MRED	50

	SUBROUTINE INTGL(X,Y,VR,VI,S,N,NQ,NZ,NN)	INTGL	2
C	INTEGRATION BASED ON SPLINE FUNCTION	INTGL	3
	DIMENSION X(1),Y(NM,2),S(NM,1)	INTGL	4
C	DEFINE L(J)	INTGL	5
	DO 20 I=2,NQ	INTGL	6
20	S(I,1)=X(I)-X(I-1)	INTGL	7
	IF (NQ.EQ.2) GO TO 50	INTGL	8
C	DEFINE TRI-DIAGONAL COEFFICIENT MATRIX	INTGL	9
	DC 25 I=2,NZ	INTGL	10
	S(I,2)= S(I,1)/6.0	INTGL	11
	S(I,3)=(S(I,1)+S(I+1,1))/3.0	INTGL	12
25	S(I,4)= S(I+1,1)/6.0	INTGL	13
	S( 2,2)=0.0	INTGL	14
	S(NZ,4)=0.0	INTGL	15
C	DEFINE RIGHT-HAND-SIDE COLUMN MATRIX	INTGL	16
	K=1	INTGL	17
35	DO 40 I=2,NQ	INTGL	18
40	S(I,5)=(Y(I,K)-Y(I-1,K))/S(I,1)	INTGL	19
	DC 45 I=2,NZ	INTGL	20
45	S(I,6)= S(I+1,5)-S(I,5)	INTGL	21
C	SOLVE FOR COEFFICIENTS OF SPLINE FUNCTION M(J)	INTGL	22
	CALL TRIDI(2,NZ,S(I,2),S(I,3),S(I,4),S(I,6),S(I,7),S(I,8),S(I,9))	INTGL	23
50	CONTINUE	INTGL	24
	S( 1,7)=0.0	INTGL	25
	S(NQ,7)=0.0	INTGL	26
	VI=0.0	INTGL	27
	DO 60 I=2,NQ	INTGL	28
	VI=VI+0.5*S(I,1)	INTGL	29
	S * (Y(I,K)+Y(I-1,K)-S(I,1)*S(I,1)+(S(I,7)+S(I-1,7))/12.)	INTGL	30
60	CONTINUE	INTGL	31
	IF(K.EQ.2) RETURN	INTGL	32
	VR=VI	INTGL	33
	IF(N.EQ.1) RETURN	INTGL	34
	K=2	INTGL	35
	GO TO 35	INTGL	36
	END	INTGL	37

	SUBROUTINE TRIDI(K1,K3,A,B,C,D,V,E,F)	TRIDI	2
	DIMENSION A(1),B(1),C(1),D(1),V(1),E(1),F(1)	TRIDI	3
	IF (K3.NE.K1) GO TO 5	TRIDI	4
	V(K3)=C(K3)/B(K3)	TRIDI	5
	RETURN	TRIDI	6
5	CONTINUE	TRIDI	7
	E(K1)=B(K1)	TRIDI	8
	F(K1)=D(K1)/E(K1)	TRIDI	9
	K2=K1+1	TRIDI	10
	CC 1) I=K2,K3	TRIDI	11
	E(I)=B(I)-A(I)*C(I-1)/E(I-1)	TRIDI	12
10	F(I)=(D(I)-A(I)*F(I-1))/E(I)	TRIDI	13
	V(K3)=F(K3)	TRIDI	14
	K2=K3-K1	TRIDI	15
	CC 2) J=1,K2	TRIDI	16
	I=K3-J	TRIDI	17
20	V(I)=F(I)-C(I)*V(I+1)/E(I)	TRIDI	18
	RETURN	TRIDI	19
	END	TRIDI	20

	SUBROUTINE SPLN1(N1,X,Y,DY,N,XX,YY,DYY,NSMOS)	SPLN1	2
C	X,Y,DY=INTERPOLATION INDEPENDENT, DEPENDENT VARIABLES, AND DY/DX	SPLN1	3
C	N1 =NO. OF INTERPOLATION POINTS	SPLN1	4
C	XX,YY =INPUT INDEPENDENT AND DEPENDENT VARIABLES	SPLN1	5
C	N =NO. OF INPUT POINTS	SPLN1	6
C	DYY =D(YY)/C(XX) FOR INPUT DATA	SPLN1	7
C	NSMOS =CONTROLS OF SMOOTHING AND PRE-INTERPOLATION	SPLN1	8
	DIMENSION X(1),Y(1),YY(1),XX(1),YY(1),DYY(1)	SPLN1	9
	N2=N	SPLN1	10
	IPRE=NSMOS/10	SPLN1	11
	NSML=NSMOS-IPRE*10	SPLN1	12
	IF(IPRE.EC.0) GO TO 30	SPLN1	13
C	STORE INPUT DATA FOR PRE-INTERPOLATION	SPLN1	14
	DO 25 J=1,N	SPLN1	15
	Y(J)=XX(J)	SPLN1	16
20	DY(J)=YY(J)	SPLN1	17
	CALL SPISET(N,XX,YY,DYY,0.0,0)	SPLN1	18
C	PRE-INTERPOLATION	SPLN1	19
	DO 25 I=2,N	SPLN1	20
	I1=I+I-2	SPLN1	21
	I2=I1+1	SPLN1	22
	XX(I2)=Y(I1)	SPLN1	23
	YY(I2)=DY(I1)	SPLN1	24
	XX(I1)=0.5*(Y(I-1)+Y(I))	SPLN1	25
25	CALL SPLN2(XX(I1),1,N,Y,DY,DYY,YY(I1),DUM,1)	SPLN1	26
	N2=2*N-1	SPLN1	27
30	CONTINUE	SPLN1	28
	IF(NSPS.EC.0) GO TO 40	SPLN1	29
C	SMOOTH INPUT DATA XX, YY	SPLN1	30
	CALL SMOOTH(N2,XX,YY,Y,NSPJ)	SPLN1	31
C	INTERPOLATE Y AT X FROM XX, YY, DYY AND CALCULATE DY=D(Y)/D(X)	SPLN1	32
40	CALL SPISET(N2,XX,YY,DYY,0.0,0)	SPLN1	33
	CALL SPLN2(X,N1,N2,XX,YY,DYY,Y,DY,2)	SPLN1	34
	RETURN	SPLN1	35
	END	SPLN1	36

	SUBROUTINE SPLN2(XP,NP,N,X,Y,D,SPF,SPD,K)	SPLN2	2
	DIMENSION X(1),Y(1),D(1),XP(1),SPF(1),SPD(1)	SPLN2	3
C	EVALUATES A NATURAL CUBIC SPLINE AND ITS FIRST DERIVATIVE USING	SPLN2	4
C	SLOPE ARRAY D CALCULATED BY SPISET AND USING THE INPUT DATA	SPLN2	5
C	ARRAYS X AND Y	SPLN2	6
	DO 10 J=1,NP	SPLN2	7
	IF(XP(J).LT.X(1).OR.N.EQ.1) GO TO 6	SPLN2	8
	DO 2 I=2,N	SPLN2	9
	IF(XP(J).LT.X(I)) GO TO 4	SPLN2	10
2	CONTINUE	SPLN2	11
	SPF(J)=Y(N)+D(N)*(XP(J)-X(N))	SPLN2	12
	IF(K.EQ.1) GO TO 10	SPLN2	13
	SPD(J)=D(N)	SPLN2	14
	GO TO 10	SPLN2	15
4	C1=1./(X(I)-X(I-1))	SPLN2	16
	C2=X(I)-XP(J)	SPLN2	17
	C3=XP(J)-X(I-1)	SPLN2	18
	C4=C2*C1	SPLN2	19
	C5=C3*C1	SPLN2	20
	SPF(J)=C5*C5*(1.+2.*C4)*Y(I)-C2*D(I)	SPLN2	21
5	+C4*C4*(1.+2.*C5)*Y(I-1)+C3*D(I-1)	SPLN2	22
	IF(K.EQ.1) GO TO 10	SPLN2	23
	C6=2.*C2-C3	SPLN2	24
	C7=2.*C3-C2	SPLN2	25
	SPD(J)=C1*C1*(C3*(2.*(1.+C1*C6)*Y(I)-C6*D(I))	SPLN2	26
5	-C2*(2.*(1.+C1*C7)*Y(I-1)+C7*D(I-1)))	SPLN2	27
	GO TO 10	SPLN2	28
6	SPF(J)=Y(1)-D(1)*(X(1)-XP(J))	SPLN2	29
	IF(K.EQ.1) GO TO 10	SPLN2	30
	SPD(J)=D(1)	SPLN2	31
10	CONTINUE	SPLN2	32
	RETURN	SPLN2	33
	END	SPLN2	34



SUBROUTINE SPISET(N,X,Y,C,RMS,IFRMS)	SPISET	2
DIMENSION X(I),Y(I),D(I)	SPISET	3
DATA JMAX,FC,FZ,LC,IOOO,IOO7,IO7179677	SPISET	4
D(I)=0.	SPISET	5
IF(N.EQ.1) RETURN	SPISET	6
D(N)=0.	SPISET	7
AN=N	SPISET	8
DO 1 I=2,N	SPISET	9
I=N+2-I	SPISET	10
X(I)=X(I)-X(I-1)	SPISET	11
1 Y(I)=(Y(I)-Y(I-1))/X(I)	SPISET	12
IF(N.EQ.2) GO TO 5	SPISET	13
DO 2 I=3,N	SPISET	14
T=N+3-I	SPISET	15
D(I-1)=2.*(Y(I)-Y(I-1))/(X(I)+X(I-1))	SPISET	16
Y(I)=1.5*D(I-1)	SPISET	17
2 X(I)=0.5*X(I-1)/(X(I)+X(I-1))	SPISET	18
DO 3 J=1,JMAX	SPISET	19
DO 3 I=3,N	SPISET	20
3 D(I-T)=X*(Y(I)-Y(I-1))+D(I-2)-(0.5-X(I))*D(I)-(N-1.0)*D(I-1)	SPISET	21
DO 4 I=3,N	SPISET	22
X(I)=X(I-1)*(C./X(I)-1.)	SPISET	23
4 Y(I)=1.3333333*Y(I)*(X(I)+X(I-1))+Y(I-1)	SPISET	24
5 SAVE=Y(I)-C*X(I)=C*(Y(I)+Y(I-1))	SPISET	25
DO 6 I=2,N	SPISET	26
C=N*X(I)	SPISET	27
S1=Y(I)-C*(X(I)-X(I-1))+D(I)	SPISET	28
S2=Y(I)+C*(X(I-1)-X(I))+D(I)	SPISET	29
D(I-1)=0.5*(SAVE+S1)	SPISET	30
6 SAVE=S2	SPISET	31
D(N)=SAVE	SPISET	32
IF(IFRMS.NE.1) GO TO 5	SPISET	33
RMS=0.	SPISET	34
IF(N.EQ.2) GO TO 8	SPISET	35
DO 7 I=3,N	SPISET	36
C=2.*D(I-1)	SPISET	37
7 RMS=RMS+((C+D(I-2)-3.*Y(I-1))/X(I-1)+D(I)+C-3.*Y(I))/X(I)**2	SPISET	38
RMS=2.*SQRT(RMS/AN)	SPISET	39
8 DO 9 I=2,N	SPISET	40
Y(I)=Y(I)*X(I)+Y(I-1)	SPISET	41
9 X(I)=X(I)+X(I-1)	SPISET	42
RETURN	SPISET	43
END	SPISET	44

	SUBROUTINE SMOOTH (N,X,Y,T,NSMDS)	SMOOTH	2
C	THE Y ARRAY IS SMOOTHED BY A LOCAL FIVE POINT LEAST SQUARES	SMOOTH	3
C	CUBIC WEIGHTED BY W	SMOOTH	4
	DIMENSION X(1),Y(1),T(1)	SMOOTH	5
	IF(N.LT.5) RETURN	SMOOTH	6
	DO 10 NS=1,NSMDS	SMOOTH	7
	T(1)=NS	SMOOTH	8
	AN=N	SMOOTH	9
	S=(T(1)+(X(N)-X(1))/AN)**2	SMOOTH	10
	DO 4 L=1,N	SMOOTH	11
	K=MINO(N-4,MAXO(1,L-2))	SMOOTH	12
	K4=K+4	SMOOTH	13
	DO 1 I=1,20	SMOOTH	14
1	T(I)=0.	SMOOTH	15
	DO 3 M=K,K4	SMOOTH	16
	W=1./(S+(X(L)-X(M))**2)	SMOOTH	17
	R=1.0	SMOOTH	18
	DO 3 I=1,4	SMOOTH	19
	I4=I-4	SMOOTH	20
	RR=1.0	SMOOTH	21
	DO 2 J=1,4	SMOOTH	22
	J4=4*J+I4	SMOOTH	23
	T(J4)=T(J4)+R*RR*W	SMOOTH	24
2	RR=RR*X(M)	SMOOTH	25
	T(I+16)=T(I+16)+R*Y(M)*W	SMOOTH	26
3	R=R*X(M)	SMOOTH	27
	CALL CHLSKY(T,4,T(17),1,4)	SMOOTH	28
	M=L-((L-1)/5)*5	SMOOTH	29
	IF(L.GT.5) Y(L-5)=T(M+20)	SMOOTH	30
	T(M+20)=0.	SMOOTH	31
	R=1.0	SMOOTH	32
	DO 4 J=1,4	SMOOTH	33
	T(M+20)=T(M+20)+R*T(J+16)	SMOOTH	34
4	R=R*X(L)	SMOOTH	35
	I4=N-5	SMOOTH	36
	DO 5 L=1,5	SMOOTH	37
	ML=M+L-((M+L-1)/5)*5	SMOOTH	38
	J4=I4+L	SMOOTH	39
5	Y(J4)=T(ML+20)	SMOOTH	40
10	CONTINUE	SMOOTH	41
	RETURN	SMOOTH	42
	END	SMOOTH	43

	SUBROUTINE CHLSKY(A,N,B,M,NX)	CHLSKY	2
	DIMENSION A(NX,1),B(NX,1)	CHLSKY	3
C	CHOLESKY DECOMPOSITION IS USED TO SOLVE THE MATRIX EQUATION AX=B	CHLSKY	4
C	WHERE THE COEFFICIENT MATRIX, A, IS SYMMETRIC. ON OUTPUT X IS	CHLSKY	5
C	STORED IN B	CHLSKY	6
	IF(N.EQ.1) GO TO 6	CHLSKY	7
	DO 2 I=2,N	CHLSKY	8
	I1=I-1	CHLSKY	9
	DO 2 J=I,N	CHLSKY	10
	DO 2 L=1,I1	CHLSKY	11
	2 A(I,J)=A(I,J)-A(L,I)*A(L,J)/A(L,L)	CHLSKY	12
	DO 5 K=1,M	CHLSKY	13
	DO 3 I=2,N	CHLSKY	14
	I1=I-1	CHLSKY	15
	DO 3 L=1,I1	CHLSKY	16
	3 B(I,K)=B(I,K)-A(L,I)*B(L,K)/A(L,L)	CHLSKY	17
	DO 4 I=2,N	CHLSKY	18
	I1=I-1	CHLSKY	19
	DO 4 L=1,I1	CHLSKY	20
	NI=N-I1	CHLSKY	21
	NL=N+1-L	CHLSKY	22
	4 B(NI,K)=B(NI,K)-A(NI,NL)*B(NL,K)/A(NL,NL)	CHLSKY	23
	DO 5 I=1,N	CHLSKY	24
	5 B(I,K)=B(I,K)/A(I,I)	CHLSKY	25
	X=RETURN	CHLSKY	26
	6 A(I,I)=1./A(I,I)	CHLSKY	27
	DO 7 L=1,M	CHLSKY	28
	7 B(I,L)=A(I,I)*B(I,L)	CHLSKY	29
	RETURN	CHLSKY	30
	END	CHLSKY	31

	SURFROUTINE SURF1(NM,N,T,ABX,ABY,ABH,IRITE)	SURF1	2
C	FIT DATA (N POINTS) BROUGHT THROUGH ABX,ABY,ABH	SURF1	3
C	1 -- TEMPORARY ARRAY FOR SPLINE-SURFACE FITTING	SURF1	4
C	2 -- POINT(X,Y) ARRAYS FOR INPUT POINTS TO BE FITTED	SURF1	5
C	ABX(I) - INDEPENDENT VARIABLE X	SURF1	6
C	ABY(I) - INDEPENDENT VARIABLE Y	SURF1	7
C	ABH(I) - COMES IN AS DEPENDENT VARIABLE OF X AND Y	SURF1	8
C	GOES OUT AS COEFFICIENTS OF SPLINE-SURFACE	SURF1	9
C	DIMENSION T(NM,1),ABX(1),ABY(1),ABH(1)	SURF1	10
C	IRITE	SURF1	11
C		SURF1	12
	NP1=N +1	SURF1	13
	NP2=NP1+1	SURF1	14
	NP3=NP2+1	SURF1	15
	NP4=NP3+1	SURF1	16
	IF(N.EQ.0) GO TO 13	SURF1	17
	DO 2 I=1,N	SURF1	18
	T(I,NP2)=ABX(I)	SURF1	19
	T(I,NP3)=ABY(I)	SURF1	20
	2 T(I,NP4)=ABH(I)	SURF1	21
	DO 4 I=1,N	SURF1	22
	T(I,I)=0.	SURF1	23
	T(I,NP1)=1.0	SURF1	24
	T(NP1,I)=1.0	SURF1	25
	T(NP2,I)=T(I,NP2)	SURF1	26
	4 T(NP3,I)=T(I,NP3)	SURF1	27
	NM1=N-1	SURF1	28
	DO 5 I=1,NM1	SURF1	29
	IP1=I+1	SURF1	30
	DO 6 J=IP1,N	SURF1	31
	XX=T(I,NP2)-T(J,NP2)	SURF1	32
	YY=T(I,NP3)-T(J,NP3)	SURF1	33
	H=XX*XX+YY*YY	SURF1	34
	T(I,J)=H*ALOG(H)	SURF1	35
	6 T(J,I)=T(I,J)	SURF1	36
	DO 8 I=1,3	SURF1	37
	IPN=I+N	SURF1	38
	DO 8 J=1,4	SURF1	39
	JPN=J+N	SURF1	40
	8 T(IPN,JPN)=C.	SURF1	41
	K=MSIMPER(NM,NP3,1,T(1,1),T(1,NP4))	SURF1	42
	IF(K.EQ.1) GO TO 9	SURF1	43
	WRITE(IH,22C)	SURF1	44
	STOP	SURF1	45
	9 CONTINUE	SURF1	46
C	STORE (N+3) COEFFICIENT IN ARRAY ABH	SURF1	47
	DO 12 I=1,NP3	SURF1	48
	12 ABH(I)=T(I,NP4)	SURF1	49
	13 IF(IRITE) 18,18,14	SURF1	50
	14 WRITE(IH,20G)	SURF1	51
	WRITE(IH,12C) (ABH(I),I=NP1,NP3)	SURF1	52
	IF(N.EQ.0) GO TO 18	SURF1	53
	DO 16 I=1,N	SURF1	54
	16 WRITE(IH,110) I,ABH(I),ABX(I),ABY(I)	SURF1	55
	18 CONTINUE	SURF1	56
	RETURN	SURF1	57
	110 FORMAT(10X,15,1P3E14.7)	SURF1	58
	120 FORMAT(62X,1P3E14.7)	SURF1	59
	200 FORMAT(11H,20X,57HHERE X(I)+Z=(X-X(I))*+Z+(Y-Y(I))*+Z/	SURF1	60
	11H0,10X,54H(IN DIMENSIONLESS COORDINATES - DISTANCE/CHORD LENGTH)/	SURF1	61
	21H0,13X,11H1,3X,44H(I),10X,44X(I),10X,44Y(I),	SURF1	62
	315X,2HAG,12X,2HAI,12X,2HAZ/)	SURF1	63
	220 FORMAT(3X,20HEID NOT CONVERGE IN SURF1//)	SURF1	64
	END	SURF1	65

	SUBROUTINE SURF2(Z1,Z2,J1,J2,MXY,VALU,VLUX,VLUY,XI,YI,HI,N,H)	SURF2	2
C	COMPUTE VALUE OF SPLINE-SURFACE FITTED DATA AT A POINT (X,Y)	SURF2	3
C	Z1,Z2- COORDINATES OF THE POINT WHERE THE FITTED VALUE IS SOUGHT	SURF2	4
C	VALU - FITTED VALUE SOUGHT	SURF2	5
C	VLUX - GRADIENT OF FITTED VALUE IN X	SURF2	6
C	VLUY - GRADIENT OF FITTED VALUE IN Y	SURF2	7
C	XI,YI,HI - ARRAYS FOR KNOWN PROPERTIES IN SPLINE-SURFACE FORM	SURF2	8
C	N -- NUMBER OF POINTS IN XI, YI ARRAYS	SURF2	9
C	MXY=0 X=Z1(J), Y=Z2(J) WHERE J=J1,J2	SURF2	10
C	MXY=1 X=Z1(1), Y=Z2(J) WHERE J=J1,J2	SURF2	11
C	MXY=2 Y=Z1(1), X=Z2(J) WHERE J=J1,J2	SURF2	12
	DIMENSION XI(1),YI(1),HI(1)	SURF2	13
	DIMENSION Z1(1),Z2(1),VALU(1),VLUX(1),VLUY(1)	SURF2	14
	NP1=N +1	SURF2	15
	NP2=NP1+1	SURF2	16
	NP3=NP2+1	SURF2	17
	IF(MXY.EQ.1) X=Z1(1)	SURF2	18
	IF(MXY.EQ.2) Y=Z1(1)	SURF2	19
	DO 40 J=J1,J2	SURF2	20
	IF(MXY.EQ.1) Y=Z2(J)	SURF2	21
	IF(MXY.EQ.2) X=Z2(J)	SURF2	22
	IF(MXY.NE.0) GO TO 10	SURF2	23
	X=Z1(J)	SURF2	24
	Y=Z2(J)	SURF2	25
10	CONTINUE	SURF2	26
	IF (K-2) 13,12,11	SURF2	27
11	VLUY(J)=HI(NP3)	SURF2	28
12	VLUX(J)=HI(NP2)	SURF2	29
13	VALU(J)=HI(NP1)+HI(NP2)*X+HI(NP3)*Y	SURF2	30
	IF(N.EQ.0) GO TO 40	SURF2	31
	DC 30 I=1,N	SURF2	32
	TX=X-XI(I)	SURF2	33
	TY=Y-YI(I)	SURF2	34
	H = TX*TX+TY*TY	SURF2	35
	HA=0.	SURF2	36
	IF(H.GT.0.) HA=ALOG(H)	SURF2	37
	HB=2.*(1.+HA)*HI(I)	SURF2	38
	IF (K-2) 23,22,21	SURF2	39
21	VLUY(J)=VLUY(J)+HB*TY	SURF2	40
22	VLUX(J)=VLUX(J)+HB*TX	SURF2	41
23	VALU(J)=VALU(J)+HI(I)*H*HA	SURF2	42
30	CONTINUE	SURF2	43
40	CONTINUE	SURF2	44
	RETURN	SURF2	45
	END	SURF2	46

	FUNCTION CIN(X1,S)	CIN	2
C	SINE AND COSINE INTEGRAL SUBROUTINE	CIN	3
C		CIN	4
C	IF CALLED BY THE STATEMENT C=CIN(X,S)	CIN	5
C	C AND S ARE THE INTEGRALS OVER T FROM 1 TO INFINITY OF	CIN	6
C	COS(TX)/T AND SIN(TX)/T	CIN	7
C		CIN	8
	SG=1.0	CIN	9
	X=X1	CIN	10
	IF (X) 1,2,2	CIN	11
	1 SG=-SG	CTN	12
	X=-X	CIN	13
	2 X2=X*X	CIN	14
	IF (X-1.0) 3,3,4	CIN	15
C		CIN	16
C	FOR ABS(X) LESS THAN 1 A SERIES EXPANSION IS USED	CIN	17
C		CIN	18
	3 V=(((X2/98.0-0.6)*.05*X2+1.0)*X2/18.0-1.0)*X+1.57079633	CIN	19
	U=(((X2/45.0-1.0)*X2/24.0+1.0)*X2/4.0-.577215665-ALOG(X)	CIN	20
	GO TO 5	CIN	21
C		CIN	22
C	FOR ABS(X) GREATER THAN 1 APPROXIMATIONS OF HASTINGS ARE USED	CIN	23
C		CIN	24
	4 P=(((X2+19.394119)*X2+47.411538)*X2+8.493336)/(((X2+21.361055)	CIN	25
	1 *X2+70.376496)*X2+30.038227)*X)	CIN	26
	Q=(((X2+21.383724)*X2+49.719775)*X2+5.089504)/(((X2+27.177958)	CIN	27
	1 *X2+119.918932)*X2+76.707876)*X2)	CIN	28
	CO=COS (X)	CIN	29
	SI=SIN (X)	CIN	30
	U=Q*CO-P*SI	CIN	31
	V=P*CO+Q*SI	CIN	32
	5 S=V*SG	CIN	33
	CIN=U	CIN	34
	RETURN	CIN	35
	END	CIN	36

Code	Statement	MSIMER
	FUNCTION MSIMER(M,N,L,A,B)	2
	DIMENSION A(M,1),B(M,1)	3
	DC 30 I = 1,N	4
	C = 0.0	5
	DO 10 J = 1,N	6
10	C = AMAX1(C,ABS(A(I,J)))	7
	IF(C.EQ.0.0) GO TO 1000	8
	DC 20 J = 1,N	9
20	A(I,J) = A(I,J)/C	10
	DC 30 J = 1,L	11
30	B(I,J) = B(I,J)/C	12
	IF(N.EQ.1) GO TO 205	13
	MM = N - 1	14
	DO 200 J = 1,MM	15
	C = 0.0	16
	K = 0	17
	DO 40 I = J,N	18
	D = ABS(A(I,J))	19
	IF (C.GE.D) GO TO 40	20
	K = I	21
	C = D	22
40	CONTINUE	23
	IF(N.EQ.0.OR.C.LT.1.E-7) GO TO 1000	24
	IF(K.EC.J) GO TO 70	25
	DO 50 JJ = J,N	26
	C = A(J,JJ)	27
	A(J,JJ) = A(K,JJ)	28
50	A(K,JJ) = C	29
	DL 60 JJ = 1,L	30
	C = B(J,JJ)	31
	B(J,JJ) = B(K,JJ)	32
60	B(K,JJ) = C	33
70	C = A(J,J)	34
	JP = J + 1	35
	DL 80 JJ = JP,N	36
80	A(J,JJ) = A(J,JJ)/C	37
90	DO 100 JJ = 1,L	38
100	B(J,JJ) = B(J,JJ)/C	39
	DO 200 I = 1,N	40
	IF(I.EQ.J) GO TO 200	41
	C = A(I,J)	42
	DO 110 JJ = JP,N	43
110	A(I,JJ) = A(I,JJ) - C*A(J,JJ)	44
	DC 120 JJ = 1,L	45
120	B(I,JJ) = B(I,JJ) - C*B(J,JJ)	46
200	CONTINUE	47
205	C = A(N,N)	48
	IF(ABS(C).LT.1.E-7) GO TO 1000	49
	DO 210 J = 1,L	50
210	B(N,J) = B(N,J)/C	51
	IF(N.EQ.1) GO TO 230	52
	DC 220 I = 1,MM	53
	C = A(I,N)	54
	DO 220 JJ = 1,L	55
220	B(I,JJ) = B(I,JJ) - C*B(N,JJ)	56
230	MSIMER = 1	57
	RETURN	58
1000	MSIMER = 2	59
	RETURN	60
	END	61

FUNCTION MSINEC(M,N,L,A,B)	MSINEC	1
DIMENSION A(M,1),B(N,1)	MSINEC	2
COMPLEX A,B,G	MSINEC	3
DO 30 I = 1,N	MSINEC	4
C = 0.0	MSINEC	5
DO 10 J = 1,M	MSINEC	6
10 C=ANAXI(C,ABS(REAL(A(I,J)),ABS(REAL(B(I,J))))	MSINEC	7
IF(C.EQ.0.0) GO TO 1000	MSINEC	8
DO 20 J = 1,N	MSINEC	9
20 A(I,J) = A(I,J)/C	MSINEC	10
DO 30 J = 1,L	MSINEC	11
30 B(I,J) = B(I,J)/C	MSINEC	12
IF(N.EQ.1) GO TO 205	MSINEC	13
MM = M - 1	MSINEC	14
DO 200 J = 1,MM	MSINEC	15
C = 0.0	MSINEC	16
K = 0	MSINEC	17
DO 40 I = J,M	MSINEC	18
D=ABS(REAL(A(I,J)))+ABS(AIMAG(A(I,J)))	MSINEC	19
IF(C.GE.0) GO TO 40	MSINEC	20
K = I	MSINEC	21
C = D	MSINEC	22
40 CONTINUE	MSINEC	23
IF(K.EQ.0.OR.C.LT.1.E-7) GO TO 1000	MSINEC	24
IF(K.EQ.J) GO TO 70	MSINEC	25
DO 50 JJ = J,M	MSINEC	26
G = A(J,JJ)	MSINEC	27
A(J,JJ) = A(K,JJ)	MSINEC	28
50 A(K,JJ) = G	MSINEC	29
DO 60 JJ = 1,L	MSINEC	30
G = B(J,JJ)	MSINEC	31
B(J,JJ) = B(K,JJ)	MSINEC	32
60 B(K,JJ) = G	MSINEC	33
70 G = 1.0/A(J,J)	MSINEC	34
JP = J + 1	MSINEC	35
DO 80 JJ = JP,N	MSINEC	36
80 A(J,JJ) = A(J,JJ)*G	MSINEC	37
90 DO 100 JJ = 1,L	MSINEC	38
100 B(J,JJ) = B(J,JJ)*G	MSINEC	39
DO 200 I = 1,N	MSINEC	40
IF(I.EQ.J) GO TO 200	MSINEC	41
G = A(I,J)	MSINEC	42
DO 110 JJ = JP,N	MSINEC	43
110 A(I,JJ) = A(I,JJ) - G*A(J,JJ)	MSINEC	44
DO 120 JJ = 1,L	MSINEC	45
120 B(I,JJ) = B(I,JJ) - G*B(J,JJ)	MSINEC	46
200 CONTINUE	MSINEC	47
205 G = A(N,N)	MSINEC	48
IF (ABS(REAL(G)) + ABS(AIMAG(G)).LT.1.E-7) GO TO 1000	MSINEC	49
DO 210 J = 1,L	MSINEC	50
210 E(N,J) = B(N,J)/G	MSINEC	51
IF(N.EQ.1) GO TO 230	MSINEC	52
DO 220 I = 1,MM	MSINEC	53
DO 220 JJ = 1,L	MSINEC	54
220 B(I,JJ) = B(I,JJ) - A(I,N)*E(N,JJ)	MSINEC	55
230 MSINEC = 1	MSINEC	56
RETURN	MSINEC	57
1000 MSINEC = 2	MSINEC	58
RETURN	MSINEC	59
END	MSINEC	60
	MSINEC	61



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16. Abstract A computer program has been developed to account approximately for the effects of finite wing thickness in the transonic potential flow over an oscillating wing of finite span. The program is based on the original sonic-box program for planar wing which has previously been extended to include the effects of the swept trailing edge and the thickness of the wing. Account for the non-uniform flow caused by finite thickness is made by application of the local linearization concept. The thickness effect, expressed in terms of the local Mach number, is included in the basic solution to replace the coordinate transformation method used in the earlier work. Calculations were made for a delta wing and a rectangular wing performing plunge and pitch oscillations, and the results were compared with those obtained from other methods. An input guide and a complete listing of the computer code are presented.					
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