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MAY 1979

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# PHASE I OF THE FIRST SMALL POWER SYSTEM EXPERIMENT (ENGINEERING EXPERIMENT NO. 1)

Final Technical Report Volume V - Supporting Analyses and Trade Studies 

#### PHASE I OF THE FIRST SMALL POWER SYSTEM EXPERIMENT (ENGINEERING EXPERIMENT NO. 1)

Final Technical Report Volume V – Supporting Analyses and Trade Studies

MAY 1979

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APPROVED BY: R & Hell

DR. R. J. HOLL PROGRAM MANAGER

PREPARED FOR:

CALIFORNIA INSTITUTE OF TECHNOLOGY JET PROPULSION LABORATORY 4800 OAK GROVE BLVD PASADENA, CALIF. 91103 CONTRACT JPL NO. 955117 (NAS7-100, TASK ORDER NO. RD-152)

MCDONNELL DOUGLAS ASTRONAUTICS COMPANY-HUNTINGTON BEACH 5301 Bolsa Avenue Huntington Beach, California 92647 (714) 896-3311





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#### PREFACE

This document constitutes the McDonnell Douglas Astronautics Company (MDAC) final technical report for Phase I of the First Small Power System Experiment (Engineering Experiment No. 1). Phase I is an investigation of various system concepts that will allow the selection of the most appropriate system or systems for the first small solar power system application. This 10-month study is a part of the Small Power Systems Program that is being developed under the direction of the Department of Energy (DOE) and managed by the Jet Propulsion Laboratory (JPL). The final report is submitted to JPL under Contract No. 955117.

The final technical report consists of five volumes, as follows:

Volume	I	Executive Summary
	II	System Concept Selection
	III	Experimental System Definitions (3.5, 4.5, and 6.5 Year Programs)
	IV	Commercial System Definition
	۷	Supporting Analyses and Trade Studies

Requests for further information should be directed to the following:

- Mr. J. R. Womack, JPL Technical Manager Jet Propulsion Laboratory Pasadena, California Telephone (213) 577-9302
- Dr. R. J. Holl, MDAC Program Manager MDAC-Huntington Beach, California Telephone (714) 896-2755
- Mr. R. P. Dawson, MDAC Deputy Program Manager MDAC-Huntington Beach, California Telephone (714) 896-3080
- Mr. W. H. Scott, Manager Energy Contracts MDAC-Huntington Beach, California Telephone (714) 896-4821



#### ACKNOWLEDGMENTS

The following personnel made significant contributions to this report: <a href="MDAC">MDAC</a>

C. B. Boenmer	Reliantity/Availantity Analyses
W. L. Dreier	Energy Storage and Energy Transport Subsystems
C. R. Easton	Concentrator Assembly
T. Fahrner	Receiver Assembly
J. C. Grosse	Plant Control Subsystem
G. Hilliard	Maintainability and Logistics Analyses
G. L. Keller	Concentrator Assembly
R. H. McFee	Collector Field Optics and Receiver Flux
R. T. Neher	Receiver Assembly
J. H. Nourse	Costing Analyses
J. E. Raetz	Systems Analysis
E. J. Riel	Plant Control Subsystem
E. T. Suter	Energy Transport Subsystem
B. E. Tilton	Systems Analysis and Power Conversion Subsystems
Rocketdyne	
R. R. Gross	Receiver Assembly Design
D. E. Vanevenhoven	Collection Fluid Analysis
J. J. Vrolyk*	Receiver Assembly, Energy Storage Subsystem
<u>Stearns-Roger</u>	
J. Dubberly	Tower Assembly: Power Plant Equipment
J. Gormely	Tower Assembly; Power Plant Equipment
W. R. Lang*	Tower Assembly; Power Plant Equipment
Energy Technology, Inc.	
T. T. Kolenc*	Radial Outflow Turbine
University of Houston Energy Labora	tory
Dr. R. C. Bannerot*	Heliostat Field Analysis
Dr. L. L. Vant-Hull	Heliostat Field Analysis

\*Subcontractor Program Manager



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### Section 1 PHASE I PROGRAM INTRODUCTION

The Solar Thermal Power Systems Office of the Division of Solar Energy of DOE has initiated several application-oriented programs, one of which is the Small Power Systems Program. The overall objective of this program is to develop and foster the commercialization of modular solar thermal power systems for application in the 1 to 10 MWe range. Potential applications include power systems for remote utility applications, small communities, rural areas, and industrial users. Engineering Experiment No. 1 represents the first small power system to be developed under this program.

The primary goal of Engineering Experiment No. 1 (EE No. 1) is to identify suitable technological approaches for small power systems applications and to design, fabricate, field install, test and evaluate a solar power facility based on an optimum use of near-term technologies. Investigation of the performance, functional, operational and institutional interface aspects of such a facility in a field test environment are additional objectives.

Engineering Experiment No. 1 will be conducted in three phases: Phase I -Concept Defnition, Phase II - Design and Development Testing, and Phase III -Plant Construction and Testing. Three candidate programs for EE No. 1 are shown on Figure 1-1.

Phase I objectives were to investigate various system concepts and develop information which will allow selection of the most appropriate system for the first small power system application. System design and system optimization studies were conducted considering plant size, annual capacity factor, and startup time (the time from start of Phase I to the initiation of testing in Phase III) as variables. The primary output of Phase I was to be the definition of preferred system concepts for each startup time, design sensitivity and cost data for the systems studied, and Phase II Program Plans for each preferred system concept.

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THREE CANDIDATE PROGRAMS FOR EE NO. 1

YEARS FROM PHASE I START																	
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THREE PROJECT PHASES

- 1 CONCEPT DEFINITION
- II PRELIMINARY AND DETAILED DESIGN;
  - COMPONENT/SUBSYSTEM DEVELOPMENT/TESTING
- 111 FABRICATION, INSTALLATION, TEST AND EVALUATION

CATEGORY A CANDIDATE SYSTEMS - GENERAL, EXCLUDING DISH CONCENTRATORS

#### Figure 1-1. Overall Program Scope

Phase II involves the preliminary and detailed design of the preferred system, and component and/or subsystem development testing that are needed before proceeding with plant construction in Phase III. Phase II may be from 8 to 42 months depending on the program selected by JPL as a result of Phase I.

Phase III will consist of subsystem fabrication, plant construction, installation, testing, and evaluation of the solar power facility (Engineering Experiment No. 1). A 3-year schedule is anticipated for this phase, with testing conducted during the third year.

Late in the Phase I study period, DOE concluded that a better balance of the overall solar thermal electric program could be achieved by limiting the JPL Small Power Applications activities to point-focus distributed systems. Consequently, DOE directed that JPL take the necessary steps to constrain the JPL-managed first Engineering Experiment (EE No. 1) to point-focusing distributed receiver technology for all phases beyond Phase I. Accordingly, on 3 April 1979, all MDAC efforts on Phase II program planning were terminated by JPL directive.

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#### 1.1 STUDY TASK APPROACH

Phase I study objectives were: (1) select preferred system concepts for each of the three program durations, (2) complete conceptual designs for each of three system concepts, (3) provide sensitivity data over range; plant rating: 0.5-10 MWe; annual capacity factor: 0 storage to 0.7, (4) prepare detailed Phase II plans and cost proposal (3 versions of EE No. 1), (5) prepare Phase III program and cost estimates (3 versions of EE No. 1), and (6) recommend preferred EE No. 1 program. Three major tasks were planned for the 10-month Phase I effort. They were Task 1 - Development of Preferred System Concepts, Task 2 - Sensitivity Analyses, and Task 3 - Phase II Program Plans. The Top-Level study flow is indicated in Figure 1-2.

In Task I, three preferred concepts were defined to the conceptual design level. The concepts were consistent with the three specified program startup

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Figure 1-2. Top Level Study Flow

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times of 3.5, 4.5, and 6.5 years. In Task I, power plants were considered for a nominal 1.0 MWe rated capacity and 0.4 capacity factor. Activities in Task I through the selection of the three preferred system concepts were primarily a systems engineering/evaluation conducted by MDAC. Subsystem characteristics, performance, and preliminary development requirements were supplied by the appropriate subcontractors. Following this concept selection, the conceptual design of subsystems was initiated in which descriptions, finalized development requirements, performance, reliability, and cost data for each of the three selected concepts were developed.

In Task II, the impact of varying rated power (0.5 and 10.0 MWe) and system capacity factor (zero storage case and 0.7) was investigated. Sensitivity analysis in Task II was performed by MDAC using subsystem data supplied by the subcontractors. This task featured system and subsystem reoptimization for each of the cases evaluated.

In Task III, the management, technical and cost plans for Phase II for each of the three selected concepts were to be prepared in accordance with JPL guidelines and MDAC system recommendations were to be provided. However, as reviewed above, during the latter period of the contract, JPL directed MDAC to terminate all Task III efforts. Accordingly, Task III efforts were discontinued and Phase II Program Plans are not reported.

#### 1.2 ROLES AND RESPONSIBILITIES

A team of companies led by the McDonnell Douglas Astronautics Company (MDAC) was contracted to conduct the Phase I definition of Category A systems (general only excluding dish concentrators). The team includes MDAC, Rocketdyne, Stearns-Roger, the University of Houston Energy Laboratory, and Energy Technology, Incorporated (ETI). MDAC was the prime contractor for the effort and was responsible for overall contract compliance. The four major subcontractors and their prime areas of responsibility were: (1) Rocketdyne Division of Rockwell International (receiver, dual-media energy storage),



(2) Energy Technology, Inc. (radial turbine and gearbox), (3) Stearns-Roger (tower and plant layout/equipment), and (4) University of Houston Solar Energy Laboratory (collector field optimization).

#### 1.3 SYSTEM SUMMARY

From the preliminary design analyses efforts to date, MDAC concludes that the proposed central receiver power system concept is a feasible, low-cost, and low-risk approach for a small solar power system experiment. It is particularly suitable for early deployment under the 3.5- and 4.5-year programs. The concentrator subsystem is currently under development and low-cost, highproduction rate heliostats will be available for this program. The proposed receiver subsystem using Hitec is similar to existing fossil fired/Hitec heaters. The tower is a standard low-cost guyed steel tower. The energy transport system using Hitec is based on standard state-of-the art equipment and operating conditions. For the 3.5- and 4.5-year programs, a simple twotank storage subsystem is proposed which requires no development. The power conversion system is based on existing axial steam turbines. All the balance of plant equipment involves state-of-the-art equipment and processes. The 6.5-year program contains development of a radial outflow turbine and qualification of a dual media thermocline storage subsystem. The technology employed in all programs is consistent with the development time available. Thus, the proposed MDAC concepts satisfy all of the important JPL selection criteria, namely, high operational reliability, minimum risk of failure, good commercialization potential, and low program costs.

#### 1.4 SUPPORTING ANALYSES AND TRADE STUDIES

This volume contains all supporting analyses and trade studies conducted during Phase I on the preferred system concepts. Analyses and trades on the overall system are contained in Section 2. Subsystem analyses and trades are contained in Sections 3 through 9. The state of the art and applications of Hitec and heat transfer salt (HTS) are contained in Section 10. Preliminary cost estimates of the development programs for each of the three EE No. 1 concepts are contained in Appendix A of this volume. Cost information on the commercial system is given in Volume IV. MCDONNELL DOUGLAS

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### Section 2 OVERALL SYSTEM ANALYSES AND TRADE STUDIES

This section presents a description of system level analyses and trade studies. These discussions reflect the supporting studies identified in Volume III.

#### 2.1 CONCENTRATOR FIELD OPTIMIZATION

The purpose of the concentrator field ontimization analysis was to establish sizing requirements for the concentrator field, receiver, and tower which result in the lowest cost of thermal energy on an annual basis. In order to satisfy the annual thermal energy requirements for the alternate systems, the concentrator field was optimized for outputs ranging from 10,000 to 15,000 MWHt per year.

#### 2.1.1 Field Optimization Methodology

The optimization analysis, which was carried out by the University of Houston, utilized well established computer codes which have been exercised extensively in support of other DOE contracts. The objective of the codes is to determine the most cost effective approach to the gathering and delivery of thermal energy to the base of the tower over a representative 1-year period. The resulting subsystem characteristics are, of course, dependent on the nature of the inputs assumed for the analysis. Table 2-1 presents a listing of the principal study inputs along with typical values for the current study.

Before initiating the optimization procedure, the collector field was divided into a number of computational cells. In this case 14 rows and 15 columns were used (rows run west to east and columns north to south). The cell size was  $\sqrt{3/4}$ times the tower height. A performance data base was established for each cell containing annual cell performance information as a function of heliostat spacing. The performance information reflects cosine, shading, and blocking efficiencies. The data are used as input to the optimizer. 

2-1

 Table 2-1. Field Optimization	on Input Data
Heliostat Cost	\$240/m <sup>2</sup>
Heliostat Wiring Costs	
Cable	\$20.50/m
Trenching	\$15.60/m
Receiver Cost	\$250,000 $\left(\frac{\text{Peak Power}}{4.8 \text{ MWt}}\right)^{0.5}$
Tower Cost	
38 m Optical Height	\$84,000
42 m Optical Height	\$90,000
Riser/Downcomer Cost	\$23,000 ( <u>Power</u> ) <sup>0.5</sup>
Pump Cost (28 HP at 5.6 MWt)	\$350/HP
Land Cost	\$5,000/acre
Heliostat Area	49 m <sup>2</sup>
Receiver Loss Model	0.037 (Incident Power)
	+ 0.430 MWt
Heliostat Error Budget	2.83 mr (10)

The optimizer requires as an input a figure of merit based on the expected total cost of the field, including the tower, receiver, etc., divided by the annual collected energy. From this, a cell matching parameter is formed based on the ratio of heliostat cost to input figure of merit times annual available energy. For each cell the optimizer locates all possible values of heliostat spacing which will satisfy the cell matching parameter. The optimizer also locates all values of heliostat spacings which will maximize the production of energy from each cell. The optimal heliostat spacings satisfy both of the conditions, thus minimizing cost and maximizing energy.

The optimizer compares the product of annual energy contributed by the cell and cell intercept fraction (see Section 2.1.2) to the cell matching parameter.

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As long as the product is greater than the cell matching parameter, the cell is not degrading the figure of merit and stays in the field. If it is less, the cell is trimmed from the field. Thus, the field boundary is formed. Once the optimal heliostat spacings and field boundary are determined, the number of heliostats in each cell can be determined and a new output figure of merit is formed. The process can be repeated and convergence is quickly obtained. Use of the cell matching parameter in defining the heliostat separation and in determining the field boundary assures that each cell is contributing to the system performance in a cost optimal way. All of the various costs and losses are balanced throughout the field so the converged figure of merit defines the economic optimal system.

Implicit in the figure of merit are the influences of all cost and performance considerations which can be allocated to the individual heliostats. These factors include:

- A. Shading and blocking of adjacent heliostats
- B. Guidance error model
  - 1. Slope errors of reflectors
  - 2. Tracking errors
- C. Aberration model for canted heliostats
- D. Heliostat aim strategy
- E. Cost model
  - 1. Heliostats (including guidance, etc.)
  - 2. Tower
  - 3. Receiver
  - 4. Plumbing in tower
  - 5. Land for heliostat
  - 6. Wiring for heliostat
  - 7. Receiver feed pump
- F. Energy loss model
  - 1. Mirror reflection and receiver absorption
  - 2. Receiver absorptivity versus angle of incidence
  - 3. Reradiation and convection from receiver
  - 4. Atmospheric losses between heliostat and receiver
  - 5. Interception losses at receiver

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The interception factor data (as defined in Section 2.1.2) between individual heliostats and the receiver were calculated off line and used as inputs to the optimization analysis. A description of the approach used to define the interception factors for each cell is presented in Section 2.1.2.

The information developed as a result of this optimization analysis includes a specification of the optimized cost of annual energy, the annual energy absorbed into the receiver working fluid, the peak power level, field shape, and heliostat spacing data for each of the computational cells selected for use. A simple change in tower height (expressed in terms of revised interception factors) and the corresponding cost scaling will result in a new set of collector subsystem performance and design data. This process was repeated until a sufficient parametric data base was established to cover the range of interest from 10,000 to 15,000 MWH of annual thermal energy.

#### 2.1.2 Receiver Interception Factor

The average annual receiver interception factor (AIF), which is a primary input to the concentrator field optimization analysis, is defined as the ratio of the total annual energy collected within the aperture to the total annual energy redirected by the heliostat field.

An analysis was made, using the McDonnell Douglas optical analysis computer code (CONCEN), of the variation in annual interception factor with location in the field. A heliostat mirror size of 7.4 by 7.4 m was used. The height of the receiver aperture center above the heliostat mirror center was taken to be 38 and 42 m. The receiver was assumed to be tilted downward  $30^{\circ}$  from due north, and the ambient temperature was  $32^{\circ}C$  ( $90^{\circ}F$ ). Figures 2-1 and 2-2 contain values of the AIF extrapolated from the above data for each of the cell locations in the collector field for a circular receiver aperture of 4.5 m diameter.

#### 2.1.3 Field Optimization Results

The results of the concentrator field optimization analysis carried out by the University of Houston are shown in Figure 2-3 for different tower heights. The figure-of-merit parameter represents the capital cost divided by the annual  $\omega = (1,1,2,2)$ 

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Figure 2-1. Receiver Intercept Factor, 38-m Optical Height



Figure 2-2. Receiver Intercept Factor, 42-m Optical Height



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Figure 2-3. Experimental Field - Optimization Results

thermal energy delivered to the base of the tower through the energy transport subsystem expressed in \$/MWHt per year. Cost factors considered include heliostats, land, wiring, tower, receiver, piping, pumps, and a fixed cost which is independent of the specific system under consideration. The indicated values of the figure of merit were based on an insolation model defined by the University of Houston.

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In order to refine the predictions of annual energy production provided by the University of Houston's optimization analysis, a reference case was analyzed using the MDAC Program P5595 and comparing its results to those obtained by the University of Houston. The program P5595 uses insolation, ambient temperature, and wind velocity for the specific site (Barstow 1976) and evaluates the performance of the concentrator/receiver subsystem at 15-minute intervals. The performance is integrated for each day for an entire year and can be presented at 15-minute intervals or given as daily average efficiencies.

The design characteristics of the reference run are presented below.

Number of heliostats	154
Heliostat area	49 m <sup>2</sup>
Receiver aperture	4.0 x 4.0 m
Receiver absorptivity	0.95
Receiver thermal	
Losses	430 kW <sub>t</sub>
Optical height	38 m

Performance results for typical days near winter and summer solstice and spring equinox are given in Figure 2-4. Average daily performance is shown for each day in Table 2-2. The results of this analysis show the annual energy produced to be approximately 4.5% greater than that predicted by the University of Houston results which corresponds to a 4.5% reduction in figure of merit.

This study was made to determine the collector field characteristics for the experimental plant and to determine whether a 40 or 44 m tower is preferred. From the results presented it is seen that the figure of merit is nearly identical for the two tower heights; therefore, the more conservative 40 m tower (38 m optical height) was selected for the alternate systems. The closeness of the results also confirms that the tower heights analyzed span the optimum.



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#### 2.2 SYSTEM AVAILABILITY

The work sheets for the availability analysis of the three EE-1 concepts are presented in Tables 2-3 through 2-14. The overall results are shown in Tables 2-15 through 2-18.

The analysis considered each generic type of component for each subsystem. A failure rate was estimated for each of the applicable failure modes for each generic component. These failure rates were estimated using data from References 2-1 through 2-7.

The operating time for each type of component was established. The operating time for the collector, energy transport, and energy storage was set at 3,861 hr/yr which was derived from the average sun insolation of 11.7 hr/day for 330 cloudless days per year. The operating time for the power conversion subsystems was based on a 40% load factor and was calculated to be 3,504 hr/yr. The operating time for the plant control and components that contain fluids on a full-time basis used the actual clock time per year (8,760 hr).

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Day	Date	Insol (kwh/m <sup>2</sup> - day)	Field eff.	Receiver eff.	Thermal engy (mw H <sub>+</sub> )
Day 12345678901234567890123456789012	Date 2122222222222222222222222222222222222	Insol (kwh/m <sup>2</sup> - day) 8.1316 8.3159 5.8186 5.1637 7.9716 7.7984 6.3557 7.3886 7.3857 5.4308 3.3006 5.9582 3.7675 7.3763 7.2878 7.7425 8.6133 2.5058 3.4460 4.0219 7.3613 9.4696 8.7230 7.7804 8.8066 2.8393 4.3695 5.1309 5.3139 8.4598 9.2280	Field eff. 734 7742 7742 77558 773558 7735 77359 77399 7727 7718 772568 7727 7718 772568 7727 7718 772568 7727 7718 772568 7727 7718 772568 7727 7718 772568 7727 7718 772568 7727 7718 772568 7727 7718 772568 7727 7727 7727 7727 7727 7727 7727 77	Receiver eff. .855 .860 .800 .789 .851 .858 .833 .764 .737 .771 .656 .845 .845 .845 .847 .680 .734 .777 .808 .861 .872 .835 .859 .702 .835 .859 .702 .835 .859 .702 .805 .758 .868 .860	Thermal engy $(mw H_t)$ 38,562 39,643 26,110 22,842 37,456 36,609 30,203 34,587 34,158 23,001 13,410 13,410 34,927 13,410 34,266 9,3565 18,444 33,516 41,618 41,618 41,618 41,618 41,618 41,503 18,929 22,102 39,779 43,022
91234567890	3 2 2 3 4 5 2 2 4 5 2 2 4 5 2 2 4 5	6,2454 8,5335 8,7936 5,4438 8,9600 8,4591 8,6357 9,1543 9,7686	728 724 721 730 718 720 718 720 715 710	.800 .827 .814 .830 .773 .857 .800 .816 .859 .859	43,022 28,410 37,991 39,745 23,198 41,677 36,807 38,419 42,484 44,802
91 92 93 94 95 96 97	3 1 1 2 3 4 4 4 4 5 6	8,3329 9,2392 8,9465 6,0164 4,3545 6,7055 9,0182	/20 713 714 /24 ./42 .707 .711	852 835 855 787 738 774 834	38,604 41,558 41,272 25,871 18,008 27,701 40,359

Table 2-2. Average Daily Concentrator/Receiver Performance (Page 2 of 7)

Ta	ble 2-2.	Average Daily Concen	trator/Receive	r Performance (	Page 3 of 7)
Day	Date	Insol (kwh/m <sup>2</sup> - day)	Field eff.	Receiver eff.	Thermal engy (mw H <sub>+</sub> )
98	4 7	9.1746	.708	865	42.474
00	4 8	6.1020	82	-742	53.311
100	4 9	8.8684	.742	057	10 869
100	4 40	6.6860	1221	,007	0 147
101	7 10	6 50 4 6	1764	.800	27,142
102	4 11	0,0040	110	,807	29.337
103	4 12	3,0791	!/17	,694	13,062
104	4 13	2,2362	, 5 2 2 2	,543	6,002
105	4 14	4,9355	.695	.761	19,362
106	4 15	2,7710	1745	.640	9,987
107	4 16	6,4142	700	,764	25,923
108	4 17	9,47<1	705	.839	42,312
109	4 18	9,3900	.701	.840	41.791
110	4 19	9,1884	.703	.856	41,754
111	4 20	9,4566	,/02	.854	42,812
112	4 21	8.1846	.709	.827	36.239
113	4 22	7.8308	.723	.801	34.245
	4 23	8.6153	.703	.843	18.555
115	4 24	8.2285	200	.835	36.304
112	4 25	7.6156	709	.772	74 448
110	4 26	9.7189		.852	43 770
11/	4 27	0 8876	1,00	856	431/12
110	1 28	9 5301	1.05	847	44,000
119	4 20	0,5021		854	37,930
120	4 24	10,0021	1677	954	42,020
121	4 30	10,1940	1692	.020	45,597
122	5 1	9.8001	. 6 90	,040	43,969
123	5 2	8,8771	1044	1825	38,371
124	53	4,2632	1084	,/00	15,560
125	54	8,6122	. 689	.848	37,969
126	5 5	5,4127	. 681	.700	19,490
127	56	6,0051	c 87	1786	24,495
125	57	-2,2896	£66	.608	7.002
129	58	9,9307	. 687	.857	44,191
130	59	8,9267	c 95	,834	39,086
131	5 10	9,0997	. 090	.835	39,616
132	5 11	8,9760	. \$83	.836	38,733
133	5 12	9,5182	. \$ 85	.842	41,473
134	5 13	10,4815	. : 84	.859.	46.553
135	5 14	9.8611	84	.819	41.727
136	5 15	9.2331	. 6 88	.835	40.066
1 37	5 16	9,1621	. 685	.831	39.392
1 7 8	5 47	10.1977	79	.839	43.875
1 70	5 18	8,9826	£ 93	825	38.767
140	5 40	7.5611	169	786	30.027
1 4 4	5 20	3,7004	684	.686	13.147
141	5 21	8.0741		797	33.183
1 4 7	5 22	0.37.4		.823	39.647
143	5 07	0.1500	1.80	.813	78.374
144	5 04	0 5544		814	10.044
145	5 24	0 5430	1002	1011	40 402
146	2 23	9,5070	15/2	1000	43 437
147	2 20	9,9470	· · / 0	.020	40,1//
148	5 2/	9,7117		.000	EU + / 72
149	5 28	F 0000	, , , , , ,	,/08	34,/5/
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Ta	ble 2-2.	Average Daily C	oncentrator/Receiv	er Performance	(Page 4 of 7)
Day	Date	Insol (kwh/m <sup>2</sup> - )	day) Field eff.	Receiver eff.	Thermal engy (mw H <sub>+</sub> )
150	5 29	9,3013	¢79	.801	38,220
151	5 30	9,8997	. \$75	813	41,082
152	5 31	10,4037	. \$ 75	.822	43,589
153	0 1	10,2469	1673	.844	43,953
154	0 2	7,9449	1054	,779	28,621
155	6 4	0 6870	. 6 / 5	.818	43,067
157	6 5	9,9685	76	.813	40,204
158	6 6	9.6302	675	.812	39,898
159	6 7	9,5408	e 77	.813	39,560
160	68	8,0849	077	,813	37,660
161	69	7,8251	676	,817	34,165
162	0 10	10083	654	738	31,431
163	0 11	10,4200	1069	,835	44.094
145	6 13	9.9022	1000	1842	42,639
166	6 14	10.8781	1001	.824	40,710
167	6 15	11,2407	663	870	46,156
168	6 16	9,9196	2 71	802	48,991
169	6 17	9,6660	665	820	10,312
170	6 18	10,8363	665	,832	45.250
171	6 19	10,452/	\$ 66	.841	44,219
172	6 21	10,0000	1 \$ 65	.826	45,141
173	6 22	10.9537	<u>• • 62</u>	.830	44,838
175	6 23	11.1702	1964	.836	45,922
176	6 24	11,3631	1002	.047	47.329
177	6 25	10,1328	.667	.830	40,/01
178	6 26	10,7693	. 68	.846	45.999
179	6 27	10.4820	. 67	847	44.779
180	6 28	9,1903	c 77	.826	38,806
181	6 30	9,9084	, 64	,815	39,322
197	7 1	10.9224	1000	,832	41,482
184	7 2	10.6461	10/0	1833	46.067
185	7 3	10,2447	70	1029	44,252
186	7 4	10,2014	. 69	.846	43, 507
187	7 5	10,5394	c 69	.839	44.706
188	76	10,1472	, c 7 0	844	43,331
189	7 6	9,5450	, = 74	,837	40,662
190	7 9	9.6165	1674	.834	40,556
192	7 10	7.9894	10//	1820	40,316
193	7 11	8,7717	. 676	.010	32,675
194	7 12	9,4203	£78	.831	40,098
195	7 13	9,5090	e76	.840	40.773
196	7 14	7,3423	. 687	,805	30,687
197	/ 7	4 2000	. 68	,711	15,309
100	7 17	8.9311	1000	,781	18,222
200	7 18	9,3842	678	840	38,414
201	7 1.9	10,2152	76	852	42,539
202	7 20	9,8130	.77	840	42.146
203	7 21	9,6052	, : 80	.845	41,664
204	7 22	1,5738	00 104 1454	,703	6,503
205	0 0	THOULATION I			
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Tab	le 2-2.	Average Daily Co	ncentrator/Rece	iver Performance	(Page 5 of 7)
Day	Date	Insol (kwh/m <sup>2</sup> - d	ay) Field eff	. Receiver eff	. Thermal engy
206	7 24	9,0295	, c 8	3 ,830	38,656
207	7 25	4,2460	. 6 8	6 ,759	16.705
200	7 27	9,2/52	173	4 ,785	19,610
210	7 28	6.4022	169	7 .7/7	20,928
211	7 29	5,3669	107	6 765	20,100
212	7 3 Q	3,1530	. 66	9 .744	11,855
213	7 31	9,2271	8	4 838	39,928
214	0 1	10,4821	, e B	2 ,856	46,255
212	8 3	9,9105	. 68	5 .840 0 828	44,650
217	8 4	10.3629		5 .833	44.680
218	8 5	10,2390	8	9 ,846	45,081
219	8 6	10.3718	108	9 .842	45,427
220	8 7	10,4122	109	843	45,793
221	3 0	10.4157	A A	8 834	43,290
222	8 10	10.4562	9	2 .851	46.509
224	8 11	10,3909	. 69	2 .856	46,481
225	8 12	10,1363		7 ,841	44,843
226	8 13	9,8082	. 69	.820	42.306
227	8 45	3,2020	. / 0	.648	12,224
220	8 16	9.9645	. 6 9	7 851	44.657
230	8 17	9,5800	,70	5 .837	42,737
231	8 18	8,5655	,70	2 ,814	36,982
232	6 19	9,2230		.847	41,004
233	8 20	8,79,2	.20	3,851	44,369
234	8 22	9.7679	.70	0 874	42.666
236	8 23	10,0325	. 6 9	7 .863	45.593
237	8 24	9,5443	.70	3 838	43,482
238	8 25	9,5145	.70	3 ,845	42,702
239	8 20	9,5060	1/0	834	42,167
240	8 28	8.68.0	.70	8 .853	41,050
242	8 29	8,5366	.7 1	.0 .852	39.003
243	8 30	8,2910	.71	.3 .859	38,377
244	8 31	6,6058	.71	.1 .851	39,295
245	9 1	7,4392	.74	7 846	40,552
240	9 3	2.4324		1 743	9.576
248	9 4	7,9461	71	9 ,832	35,876
249	9 5	6,0615	70	501	25,731
250	9 6	4,2244	.7 1	2 ,612	18,516
251	9 /	6,5541	.73	1074	37,243
252	0 0	PASOLATION	TCO LOW	1020	271704
254	õ õ	INSOLATION	TCO LOW		
255	0 0	INSOLATION	TOO LOW		
256	9 12	7,6103	17	10 ,837	34,458
257	9 10	5,4823	!/.	47 .810	32,1/4
259	9 15	7.8792	.7	16 .824	35,105
260	9 16	7,8766		24	
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Ta	ble 2-2.	Average Daily	Concentra	tor/Receiv	ver Performance	(Page 6 of 7)
Day	Date	Insol (kwh/m <sup>2</sup> -	dat) F	ield eff.	Receiver eff.	Thermal engy (mw H <sub>t</sub> )
261	9 17	8,6420		,720	.841	39,554
262	9 18	8,7647		1718	,861	40,918
200	9 19	TASOLATION	700 104	./37	.832	30,914
265	9 21	8.4372		.724	.864	19.851
266	9 22	4.9474		.731	.797	21.788
267	9 23	4,0698		759	793	18,511
268	9 24	2,7743		759	778	12,362
269	9 25	4,9445		744	,806	22,392
270	7 20	4 3544		1/29	.043	34,2/3
271	9 28	2,9803		.126	781	12.774
273	0 0	INSOLATION	TOO LO	1	1	
274	9 30	8,6133		725	.845	39,871
275	10 1	7.0034		735	,834	32,456
276	10 2	8,2011		,728	.817	37,150
277	10 3	8,6473		.725	865	40.989
279	10 5	8.7977		724	. 367	41.721
280	10 6	8,7510		,724	364	41,344
281	10 7	8,1967		1/35	.854	38,880
282	10 8	8,8725		,725	.867	42,178
283	10 9	8,5369		1/25	,800	41,909
285		6.2657		730	.851	38.769
286	10 12	7,8012		733	852	36,769
287	10 13	8,3103		1/28	.862	39,405
288	10 14	8,3558		,729	.852	39,171
289	10 12	8,1234		.745	.820	17.885
290	10 17	5.8634		740	823	26.975
292	10 18	6,7735		747	847	32,386
293	10 19	5,8998		159	,841	28,466
294	10 20	1,0111	700 10	u 194	.700	. 0,/53
295	0 0	INSOLATION	TOO LO	W		
290	10 23	5,8765		,736	.826	26,996
298	10 24	6,7075		,733	.836	31,047
299	10 25	6,2465		,737	.835	29.573
300	10 20	5,4037		722	854	35,572
301	10 27	8,0132		723	867	37.768
302	10 29	7,1604		734	.861	34,184
304	10 30	7,2295		,721	.856	33,093
305	10 31	7,5600		.718	.803	35,893
306	11 1	7.7077		1/10	.857	33,450
307	11 2	7.6248		.714	.862	35,451
300	14 4	7.8980		713	.869	36,966
310	11 5	7,8835		,712	,865	36,699
311	11 6	7,8205		,113	. 868	30,241
312	11 7	7,5430		1/13	.863	35,197
313	11 0	4.9139		706	822	21,541
345	11 10	6,9622		.713	.844	31,631
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Tab	le 2-2	Average Daily Concentra	tor/Receive	er Performance	(Page 7 of 7)
Day	Date	Insol (kwh/m <sup>2</sup> - day) F	ield eff.	Receiver eff.	Thermal engy (mw H <sub>t</sub> )
316	11 11	1.7102 TA SOLATION TOO LON	,722	.610	5,694
710	44 47	5 3070	-749	837	CA 543
310	1.1 1.4	4 67.00		744	24,540
319	11 19	4,0300	./00	1/14	10,410
320	11 12	7,1480	,/10	,052	32,0/3
321	11 10	7.1993	,/08	.859	33,060
322	11 17	7,3339	.707	,808	34,019
323	11 18	7,1591	,738	,869	33,261
324	11 19	6,6319	.709	.863	30,878
325	11 20	6,7399	710	.866	31,533
326	11 21	6,5116	710	851	29,700
327	11 22	6,0091	./00	,027	31,470
328	11 23	6,9126	708	.867	32,073
329	11 24	5,9241	708	.853	31,570
330	11 25	7.0602	.706	.844	31,804
331	11 26	5.6527	.719	.809	24,830
332	11 27	7.0698	709	.837	31,682
377	11 28	6.7555	.210	.860	31,129
314	11 29	6.6472	210	.865	30.828
795	11 20	6 6654		859	30.666
335	11 00	6 5443	200	.862	30.211
330	12 1	7 0044	107	.864	32.237
33/	12 4	7.0004 .4	1/05	858	33.074
338	12 3	1,2022	./00	867	20 404
339	12 9	0.3750	1/05	94.	27, 400
340	12	7.0503	.702	.071	31,900
341	12 6	6,8398	.707	.002	31,200
342	12 7	6,9576	<u>102 ء</u>	. 839	31,0/0
343	12 8	6,9020	.701	.8/6	32,021
344	12 9	5,6533	.708	.826	24,984
345	12 10	6,8121	./00	.845	30,468
346	12 11	6,8004	.700	.862	30,989
347	12 12	6,7057	. \$ 99	.857	30,363
348	12 13	6,2193	,702	.874	28,793
349	12 14	5.5977	94	.839	24.604
350	12 15	6.8612	. c 98	.865	31,281
351	12 16	6.8871	. 697	. 265	31,384
352	12 17	6.7738	. + 97	855	30,527
353	12 18	4.8363	.700	.832	21.273
354	12 10	4.2409	694	.797	17.701
355	12 20	6.3319		.854	28.502
784	12 24	6 8012	+ 25	.872	31,115
370	12 21	4 4 9 4 3		.864	28.504
35/	12 .4				2-1-0
358		A BEER		839	30.271
359	12 /4	4 0004	1070	.866	31.870
350	12 22	017754	16.40	784	44 094
361	12 26	2,8082	721	257	20 544
362	12 27	6,5526	. 696		27,014
363	12 28	7,0682	. 098	.0/2	32,4//
364	12 29	1,2914	. \$ 97	.507	3,443
365	0 0	INSOLATION TOO LO	N _		
366	12 31	.6695	, c 9 4	.492	1,621

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### Table 2-3. Availability Analysis (Page 1 of 5)

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ىيىن مۇرا بىرىمەر بىرىنى ئىسىرىمەر مىرىمەر بىرى ئۆكۈك ئىسىرىيىدىدىنى بۇرىرىك سۇر شىماردى دىرىدىرى بىرىغۇر. سۇر مۇرا بىرى بىرىنى ئىسىرىمەر بىرى بىرى بىرى ئۆكۈك ئىسىرىيىدىدىنى ئۇرىرىك سۇر سەرى بىرى بىرى بىرى بىرى بىرىغۇر

Subsystem: Collector, Assembly: Heliostat

System: All

Item	Failure Mode	Failure Rate (10 <sup>-6</sup> /hr)	Operating Time (hr)	Failures per year (x10 <sup>-3</sup> )	MTTR (hr)	Downtime per year (10-3hr)	Critical	Population	System Downtime per year (10 <sup>-3</sup> hr)	Comments
Power										Field power must
Cable	Open/Short	0.108	3,861	0.42	1.5	0.63	Yes	1	0.63	be turned off
Control cable	Open/Short	0.108	3,861	0.42	1.5	0.63	Yes	1	0.63	Field power must be turned off
Motors	F Тор	2.0	3,861	7.72	1.9	14.7	No	2	0	
Harmonic Drive	F Тор	1.65	3,861	6.37	4.0	25.5	No	1	0	
Linear Drive	F Тор	2.94	3,861	11.4	2.2	25.2	No	l	0	
Azimuth Optical Encoder	F Тор	1.35	3,861	5.21	2.7	14.1	No	2	0	

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### Table 2-3. Availability Analysis (Page 2 of 5)

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Subsystem: Collector, Assembly: Heliostat

System: All

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Item	Failure Mode	Failure e Rate (10 <sup>-6</sup> /hr)	Operating Time (hr)	Failures per year (x10 <sup>-3</sup> )	MTTR (hr)	Downtime per year (10 <sup>-3</sup> hr)	Critical	Population	System Downtime per year (10 <sup>-3</sup> hr)	Comments
Elevation										
Optical										
Encoder	F Тор	1.35	3,861	5.21	2.0	10.4	No	3	0	
Azimuth										
Limit										
Switches	<b>F</b> Тор	1.87	3,861	7.22	2.0	14.4	No	2	0	
Elevation										
Limit										
Switches	F Тор	1.87	3,861	7.22	1.1	7.9	No	4	0	
	Structura	1								
Pedestal	Failure	e 0.1	8,760	0.876	1.0	0.876	No	1	0	
	ȱ	. 4								
<b>.</b> .	Structura	ц , , , , , , , , , , , , , , , , , , ,				e e7		_	-	
Structure	Failure	e 0.5	8,760	4.38	1.5	6.57	No	1	0	

WCDONNELL DOUGLAS

### Table 2-3. Availability Analysis (Page 3 of 5)

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Subsystem: Collector, Assembly: Heliostat

System: All

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Item	Failure Mode	Failure Rate (10-6/hr)	Operating Time (hr)	Failures per year (x10 <sup>-3</sup> )	MTTR (hr)	Downtime per year (10 <sup>-3</sup> hr)	Critical	Population	System Downtime per year (10 <sup>-3</sup> hr)	Comments
Muroc	Structural	ł	,							
Panel	Failure	6.0	8,760 、	52.6	2.0	105	No	1	0	
Storage Motor	<b>F</b> Тор	2.0	165	0.33	1.9	0.63	No	1	0	
Storage Actuator	F Тор	2.94	1 <b>6</b> 5	0.5	2.2	1.07	No	1	0	
Helio Controlle	r F Top	5.79	3,861	22.36	2.2	49.2	No	31/32	0	Use for 4.5, 6.5 and commercial programs
Circuît Breaker	FTRC	1.0	3,861	3.86	1.6	6.18	Yes	1	6.18	
Field Power Cables	Open/Short	E 0.108	3,861	0.42	2.5	1.05	Yes	1	1.05	

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MCDOWNELL DOUG

### Table 2-3. Availability Analysis (Page 4 of 5)

Subsystem: Collector, Assembly: Heliostat

والمحادث فليعهدون الإزارية كتريتك بويهوا وأرزار مخارك مخاري والارتيان والمري

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System: All

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Item	Failure Mode	Failure Rate (10- <sup>6</sup> /hr)	Operating Time ) (hr)	Failures per year (x10 <sup>-3</sup> )	MTTR (hr)	Downtime per year (10 <sup>-3</sup> hr)	Critical	Population	System Downtime per year (10- <sup>3</sup> hr)	Comments
Field Control Cables	Open/Short	: 0.108	3,861	0.42	2.5	1.05	Yes	1	1.05	
Data Distri- bution Interface	<b>Г</b> Тор	9.74	3,861	37.6	2.2	82.7	Yes	1/32	2.58	Use for commercial programs
HAC/Field Control- ler Power Cables	Open/Short	t 0.108	3,861	0.42	2.5	1.05	Yes	1/32	0.04	
HAC/Field Control- ler Power Cables	Open/Short	t 0.108	3,861	0.42	2.5	1.05	Yes	1/32	0.04	
Helio Control- ler	<b>F</b> Тор	26.22	3,861	101.2	2.2	223	No	31/32	0	Use for 3.5 year program

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Table 2-3. Availability Analysis (Page	5	oft	(נ
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Subsystem: Collector, Assembly: Heliostat

System: All

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Item	Failure Mode	Failure Rate (10 <sup>-6</sup> /hr)	Operating Time (hr)	Failures per year (x10 <sup>-3</sup> )	MTTR (hr)	Downtime per year (10 <sup>-3</sup> hr)	Critical	Population	System Downtime per year (10 <sup>-3</sup> hr)	Comments
Field Con-	F Top	13 25	3 861	167	22	367	Yes	1/32	11.5	Use for 3.5 vear program

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### Table 2-4. Availability Analysis (Page 1 of 2)

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System:

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Item	Failure Mode	Failure Rate (10 <sup>-6</sup> /hr)	Operating Time (hr)	Failures per year (x10 <sup>-3</sup> )	MTTR (hr)	Downtime per year (10 <sup>-3</sup> hr)	Critical	Population	System Downtime per year (10 <sup>-3</sup> hr)	Comments
<u> </u>	Leak/	··· <b>··································</b>								
Absorber	clogged	16.0	8,760	140.1	14	1962	Yes	1	1962	
Absorber										
Support	Structural									
Structure	failure	1.0	8,760	8.76	10	87.6	Yes	1.	87.6	
Absorber	Structural									
Door	failure	1.0	8,760	8.76	8	70.1	Yes	1	70.1	
Piping	Leak/ clogged	1.0	8,760	8.76	12	105	Yes	1	105	
Vent		5.23/d								
Value	FTRC	1.72/hr	3,861	10.46	5.2	54.4	Yes	1	54.4	1 demand/week
Relief										
Valve	FTRC	10.0	3,861	38.6	4.5	173.8	Yes	1	173.8	•
Trace										
Heaters	F Top	10.0	3,861	38.6	20	772	No	1	0	
Insula-	Structura]									
tion	failure	1.0	3,861	3.86	10	38.6	Yes	1	38.6	

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MCDONNELL DOUGLAS

Subsystem: Collector, Assembly: Receiver
# Table 2-4. Availability Analysis (Page 2 of 2)

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Subsystem: Collector, Assembly: Receiver

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System: All

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Item	Failure Mode	Failure Rate (10 <sup>-6</sup> /hr)	Operating Time (hr)	Failures per year (x10 <sup>-3</sup> )	MTTR (hr)	Downtime per year (10 <sup>-3</sup> hr)	Critical	Population	System Downtime per year (10 <sup>-3</sup> hr)	Comments
Hand										
Valves	FTRC	0.1	3,861	0.386	4.5	1.74	Yes	2	3.47	
Sensors	<b>F</b> Тор	1.0	3,861	3.86	4.0	15.44	No	20	0	
Door										
Motors	F Тор	2.0	122	0.244	3.0	0.732	No	1	0	20 min/day

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Table 2-5. Availability Analysis

ارزا الوادية وجورو بعراري هماميو درما ورم

 $= \sum_{i=1}^{n} \left\{ \sum_{j=1}^{n} \frac{\partial f_{ij}^{(i)}}{\partial t_{ij}} + \sum_{j=1}^{n} \frac{\partial f_{ij}^{(i)}}{\partial t_{j}} + \sum_{j=1}^{n} \frac{\partial f$ 

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Subsystem:	Energy Transport
System:	3.5, 4.5

المراجعة ويستهدون الوجر ومرما الاسترابط والمصابطون بالمالية ومكان ارتداما الوقامين بالدائر والمانية المتعرية فم

Item	Failure Mode (	Failure Rate 10 <sup>-6</sup> /hr)	Operating Time (hr)	Failures per year (x10 <sup>-3</sup> )	MTTR (hr)	Downtime per year (10 <sup>-3</sup> hr)	Critical	Population	System Downtime per year (10 <sup>-3</sup> hr)	Comments
Control										
Valves	<b>F</b> Top	6,46	3,861	24.9	5.7	142	Yes	3	427	
Remote		5.23/d								
Valves	<b>F</b> Top	1.72/m	3,861	10.5	5.2	54.4	Yes	6	326	2 demands/day
Check Valves	FTRO	4	3,861	15.4	4.5	69.5	Yes	1	70	
Hand Valves	FTRO	0.3	3,861	1.16	4.5	5.2	YES	19	<u>99</u>	
		1000/d								
Pumps	F Top	<b>30/</b> m	3,861	467	9.7	4,530	Yes	2	9,060	1 demand/day
Sensor	F Top	1.0	3,861	3.86	3.0	11.6	No	5	0	
Heat	Leak									12.8 hr/yr
Exchanger	clogged	1.8	3,504	6.31	10	63.1	Yes	3	189	planned outage
Heater	F Тор	10	8,760	87.6	20	1752	No	1	0	

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Subsystem: Energy Transport

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System: 6.5

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Item	Failure Mode	Failure Rate (10 <sup>-6</sup> /hr)	Operating Time (hr)	Failures per year (x10 <sup>-3</sup> )	MTTR (hr)	Downtime per year (10 <sup>-3</sup> hr)	Critical	Population	System Downtime per year (10 <sup>-3</sup> hr)	Comments
Control				- <u> </u>						
Valves	F Тор	6.46	3,861	24.94	5.7	142	Yes	3	426	
Remote		5.23/d								•
Valves	F Top	1.72/hr	3,861	10.46	5.2	54.4	Yes	7	381	2 demands/day
Check										
Valves	FTRO	4.0	3,861	15.44	4.5	69.5	Yes	1	70	
Hand										
Valves	- FTRO	0.3	3,861	1.16	4.5	5.2	Yes	25	131	
		1.000/d								
Pumps	<b>F</b> Тор	30/m	3,861	467	9.7	4,530	Yes	2	9,060	1 demand/day
Sensor	F Top	1.0	3,861	3.86	3.0	11.6	No	5	0	•
Heat	Leak,									12.8 hr/yr
Exchangers	clogged	1.8	3,504	6.31	10	63.1	Yes	3	1.89	planned outages
Mixer										
Tank	Leak	1.0	8,760	8.76	10	87.6	Yes	1	87.6	
Heaters	Leak	10	8,760	87.6	10	1752	No	1	0	

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### Table 2-7. Availability Analysis

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Subsystem: Energy Storage

الحجو والمائد الجائم معيدة الأوجاء الشاخل منارب وتتقيبها خائرها ويعاد بالأروال ويساكن الارام الأرام

System: 3.5, 4.5

التهجف المحافدة بالوأج يتبط يفتقا الهور

Item	Failur Mode	Failure ( e Rate (10 <sup>-6</sup> /hr)	)perating Time (hr)	Failures per year (x10 <sup>-3</sup> )	MTTR (hr)	Downtime per year (10 <sup>-3</sup> hr)	Critical	Population	System Downtime per year (10 <sup>-3</sup> hr)	Comments
Hand Valves	FTRO	0.3	3,861	1.16	4.5	5.2	Yes	5	26.1	
Check Valves	FTRO	4.0	3,861	15.4	4.5	69.5	Yes	2	139	
Regulator	F Тор	18	3,861	69.5	5.7	396	Yes	2	792	
Sensors	F Тор	1.0	3,861	3.9	3.0	11.6	No	20	0	
Relief Valves	FTRC	1.0	3,861	38.6	4.5	174	Yes	2	347	
Heater	F Top	0.4	100	0.04	10	0.4	No	20	0	
Tank	Leak	1.0	8,760	8.76	10	87.6	Yes	2	154	

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# Table 2-8. Availability Analysis

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Subsystem: Energy Storage System: 6.5

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المافية والإمير المكاذفين بالاسار والال

المعربين بمحصر المحجا المع

Item	Failure Mode	Failure Rate (10 <sup>-6</sup> /hr)	Operating Time (hr)	Failures per year (x10 <sup>-3</sup> )	MTTR (hr)	Downtime per year (10 <sup>-3</sup> hr)	Critical	Population	System Downtime per year (10- <sup>3</sup> hr)	Comments
Hand Valves	FTRO	0.3	3,861	1.16	4.5	5.21	Yes	4	20.8	
Check Valves	FTRO	4.0	3,861	15.4	4.5	69.5	Yes	1	69.5	
Regulator	F Тор	18	3,861	69.5	5.7	39.6	Yes	-	39.6	
Sensor	F Тор	1.0	3,861	3.9	3.0	11.6	No	10	0	
Relief Valves	FTRC	10	3,861	38.6	4.5	173.8	Yes	1	173.8	
Heater	F Top	0.4	100	0.04	10	0.4	No	10	0	
Tank	Leak	1.0	8,760	8.8	10	87.6	Yes	1	87.6	

MCDONNELL DOUGLAS

Table 2-9.	Availabilitv	Analysis	(Page	1	of	2)
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Subsystem:	Power C	onversion								
System:	3.5, 4.	5								
Item	Failure Mode	Failure Rate (10-6/hr)	Operating Time (hr)	Failures per year (x10-3)	MTTR (hr)	Downtime per year (10 <sup>-3</sup> hr)	Critical	Population	System Downtime per year (10 <sup>-3</sup> hr)	Comments
										Planned Outage
Turbine	<b>F</b> Тор	102	3,504	357	40	14,296	Yes	1	14,296	104 hr/yr
Generator	F Тор	80	3,504	280	40	11,212	Yes	1	11,212	76 hr/yr
Condensor	Leak	1.0	3,504	3.5	10	35	Yes	1	35	12.8 hr/yr
Tank	Leak	1.0	3,504	3.5	10	35	Yes	1	35	
Diaerator	Leak	1.0	3,504	3.5	10	35	Yes	1	35	12.8 hr/yr
		1000/d								
Pump	<b>F</b> Тор	30/hr	3,504	457	9.7	4,434	Yes	3	13,302	1 demand/day
Control										
Valves	F Тор	6.46	3,504	22.6	4.7	106	Yes	8	848	
Hand										
Valves	FTRO	0.3	3,504	1.05	3.5	3.7	Yes	47	173	
Hand Valves	FTRC	0.1	3,504	0.35	3.5	1.2	Yes	7	8.6	
Pressure										
Sensor	F Тор	1.0	3,504	3.5	2	7.0	No	8	0	

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# Table 2-9. Availability Analysis (Page 2 of 2)

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Subsystem:	Power	Conversion
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System: 3.5, 4.5

Item	Failure Mode	Failure Rate (10 <sup>-6</sup> /hr)	Operating Time (hr)	Failures per year (x10-3)	MTTR (hr)	Downtime per year (10 <sup>-3</sup> hr)	Critical	Population	System Downtime per year (10 <sup>-3</sup> hr)	Comments
Flow Sensor	F Тор	12	3,504	42	3.5	147	No	2	0	
Level Sensors	F Тор	1.0	3,504	3.5	2	7.0	No	13	0	

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가 철말하였다고 나는 것 같은데 가방에 방법에서 한 것이 가장에서 없었지? 것을 할 수 있어서 있는 것이라 가지 않는 것 같아요. 물법을 다 한 것 같아요. 나는 것이 것이라는 것 같이 가지 않는 것

Subsystem: Power Conversion

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System: 6.5

Item	Failure Mode	Failure Rate (10 <sup>-6</sup> /hr)	Operating Time (hr)	Failures per year (x10 <sup>-3</sup> )	MTTR (hr)	Downtime per year (10 <sup>-3</sup> hr)	Critical	Population	System Downtime per year (10- <sup>3</sup> hr)	Comments
Heat	Leak	<u></u>		·····						Planned outage
Exchanger	Clogged	1.8	3,504	6.31	10	63.1	Yes	4	252	12.8 hr/yr
Deaerator	Leak	1.0	3,504	3.5	10	35	Yes	1	35	
		1000/d								
Pumps	<b>F</b> Top	30/hr	3,504	457	9.7	4,434	Yes	4	17,736	1 demand/day
Turbine	F Тор	102	3,504	357	40	14,296	Yes	1	14,296	Planned outage 104 hr/yr
										Planned outage
Generator	F Тор	80	3,504	280	40	11,212	Yes	1	11,212	76 hr/yr
Condenser	Leak	1.0	3,504	3.5	10	35	Yes	1	35	
Control										
Valves	F Тор	6.46	3,504	22.6	4.7	106.4	Yes	12	1,277	
Remote		5.23/d								
Valves	<b>F</b> Top	1.72/m	3,504	9,85	4.2	41.4	Yes	5	207	2 demands/day
Three-										
way		5.23/d								
Valves	F Тор	1.72/m	3,504	9.85	4.7	46.3	Yes	12	555	2 demands/day

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# Table 2-10. Availability Analysis (Page 2 of 2)

Subsystem:	Power	Conversion
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System: 6.5

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Item	Failure Mode	Failure Rate (10 <sup>-6</sup> /hr)	Operating Time (hr)	Failures per year (x10 <sup>-3</sup> )	MTTR (hr)	Downtime per year (10 <sup>-3</sup> hr)	Critical	Population	System Downtime per year (10 <sup>-3</sup> hr)	Comments
Check	<u> **</u> <u></u> .					- <u>-</u>				-
Valves	FTRO	4.0	3,504	14.0	3.5	49.1	Yes	11	540	
Relief Valves	FTRC	10	3,504	35.0	3.5	122.6	Yes	9	1,104	
Hand Valves	FTRO	0.3	3,504	1.05	3.5	3.68	Yes	88	324	
Hand Valves	FTRC	0.1	3,504	0.35	3.5	1.23	-	15	11.1	6 not critical 9 critical
Level Sensors	F Top	1.0	3,504	3.5	2	7.01	No	16	0	
Flow Meters	F Тор	12	3,504	42	3.5	147	No	2	0	
Tempera- ture Sensors	<b>F</b> Тор	1.0	3,504	3.5	2	7.01	No	4	0	
Pressure Sensors	F Тор	1.0	3,504	3.5	2	7.01	No	7	0	

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## Table 2-11. Availability Analysis (Page 1 of 2)

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Subsystem: Power Conversion, Assembly: Cooling Tower Feed

System: A11

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	Failure Mode	Failure Rate (10-6/hr)	Operating Time (hr)	Failures per year (x10 <sup>-3</sup> )	MTTR (hr)	Downtime per year (10 <sup>-3</sup> hr)	Critical	Population	System Downtime per year (10 <sup>-3</sup> hr)	Comments
·	, , , , , , , , , , , , , , , , ,	1000/d		<u></u>			- 40 mm			
Pump	F Top	30/m	3,504	457	9.7	4434	Yes	2	8,868	1 demand/day
Heat Fxchanger	Clogged	1.8	3,504	6.31	10	63.1	Yes	2	126	Planned outage 12.8 hr/yr
Domoto		5 23/d								
Valves	<b>F</b> Тор	1.72/hr	3,504	9.85	4.2	41.4	Yes	2	82.8	2 demands/day
Control Valves	F Тор	6.46	3,504	22.64	4.7	106.4	Yes	3	319	
Hand Valves	FTRO	0.3	3,504	1.05	3.5	3.7	Yes	35	130	
Hand Valves	FTRC	0.1	3,504	0.35	3.5	1.23	Yes	11	13.5	
Relief Valves	FTRC	10	3,504	35.04	3.5	123	Yes	4	491	
Level Sensors	F Тор	1.0	3,504	3.5	2.0	7.0	No	3	0	

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# Table 2-11. Availability Analysis (Page 2 of 2)

Subsystem: Power Conversion, Assembly: Cooling Tower Feed

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System: All

Item	Failure Mode	Failure Rate (10 <sup>-6</sup> /hr)	Operating Time (hr)	Failures per year (x10 <sup>-3</sup> )	MTTR (hr)	Downtime per year (10 <sup>-3</sup> hr)	Critical	Population	System Downtime per year (10 <sup>-3</sup> hr)	Comments
Pressure										
Sensors	<b>F</b> Top	1.0	3,504	3.5	2.0	7.0	No	12	0	
Check										
Valves	FTRO	4.0	3,504	14.02	3.5	49	Yes	4	196	
Tank	Leak	1.0	8,760	8.76	10	87.6	Yes .	3	261	
	Structural	1								
Structure	Failure	1.0	8,760	8.76	10	87.6	Yes	1	87.6	

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### Table 2-12. Availability Analysis

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Power Conversion, Assembly, Boiler Chemical Feed Subsystem: A11

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System:

Item	Failure Mode	Failure ( Rate (10 <sup>-6</sup> /hr)	Operating Time (hr)	Failures per year (x10-3)	MTTR (hr)	Downtime per year (10 <sup>-3</sup> hr)	Critical	Population	System Downtime per year (10 <sup>-3</sup> hr)	Comments
Hand										
Valves	FTRO	0.3	3,504	1.05	3.5	3.68	No	20	0	
Hand										
Valves	FTRC	0.1	3,504	0.35	3.5	1.23	No	8	0	
Relief										
Valves	FTRC	10	3,504	35	3.5	123	No	5	0	
Tanks	Leak	1.0	3,504	3.5	10	35	No	3	0	

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# Table 2-13. Availability Analysis

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Subsystem: Power Conversion, Assembly: Demineralizer

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System: All

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Item	Failure Mode	Failure Rate (10 <sup>-6</sup> /hr)	Operating Time (hr)	Failures per year (x10 <sup>-3</sup> )	MTTR (hr)	Downtime per year (10 <sup>-3</sup> hr)	Critical	Population	System Downtime per year (10-3hr)	Comments
Remote Valve	F Top	5.23/d 1.72/m	3,504	9.85	4.2	41.4	No	24	0	2 demands/day
Hand Valve	FTRO	0.3	3,504	1.05	3.5	3.68	No	6	0	
Hand Valve	FTRC	0.1	3,504	0.35	3.5	1.23	No	3	0	
Flow Meter	F Тор	12	3,504	42.05	3.5	147	No	2	0	
Level Meter	<b>F</b> Тор	1.0	3,504	3.5	2	7.0	No	2	0	
Tanks	Leak	1.0	3,504	3.5	10	35	No	4	0	

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# Table 2-14. Availability Analysis (Page 1 of 2)

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Subsystem: Plant Control

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System: All

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Item	Failure Mode	Failure Rate (10 <sup>-6</sup> /hr)	Operating Time (hr)	Failures per year (x10 <sup>-3</sup> )	MTTR (hr)	Downtime per year (10 <sup>-3</sup> hr)	Critical	Population	System Downtime per year (10 <sup>-3</sup> hr)	Comments
Computer	F Тор	20.4	8,760	179	4	715	Yes	1	715	
CRT/Key- board Pro- grammer	<b>F</b> Тор	4.0	8,760	35.0	2	70.0	Yes	1	70.0	
Console with Controls	F Тор	14.4	8,760	126.1	1	126	Yes	1	126	
Interface Units	<b>F</b> Тор	5.2	8,760	45.6	1	45.6	Yes	18	821	5+2+7+4
Power Supply	F Тор	9.9	8,760	86.7	1	86.7	Yes	1	86.7	
Timer/ Counter	F Тор	0.198	8,760	1.73	1	1.73	Yes	1	1.7	Assume 3 chips

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Table 2-14. Availability Analysis (Page 2 of 2)

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Subsystem: Plant Control

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System: All

Item	Failure Mode	Failure Rate (10 <sup>-6</sup> /hr)	Operating Time (hr)	Failures per year (x10-3)	MTTR (hr)	Downtime per year (10 <sup>-3</sup> hr)	Critical	Population	System Downtime per year (10 <sup>-3</sup> hr)	Comments
										11+21+21+26 Assume 3 chips, 3 resistors, 3 capac- itors, 2-20 pin
Modules	<b>F</b> Тор	0.397	8,760	3.48	1	3.48	Yes	79	274.7	connectors
Cables	Open/Short	0.108	8,760	0.95	1	0,95	Yes	43	40.7	
Modules	FYOp	0.397	8,760	3.48	1	3.48	Yes	15	52.2	Add for 4.5 yr
Modules	<b>F</b> Тор	0.397	8,760	3.48	1	3.48	Yes	30	104.4	Add for 6.5 comm system

2-36

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	Collector	Energy Transport	Energy Storage	Power Conversion	Plant Control	Total System	
Total Failures/yr	58.94	1.23	0.35	4.31	1.57	66.40	-
Critical Failures/yr	2.55	1.13	0.27	3.54	1.57	9.06	
Forced Outages, hr/yr	7.08	10.17	1.46	50.52	2.14	71.37	
Planned Outages, hr/yr	0	12.80	0	104.00	0	104.00	
Total Outages, hr/yr	7.08	22.97	1.46	154.52	2.14	175.37	
Forced Outage Rate, %	0.18	0.26	0.04	1.44	0.02	1.94	
Planned Outage Rate, %	0	0.33	0	2.97	0	2.97	
Total Outage Rate, %	0.18	0.59	0.04	4.41	0.02	4.91	
Operating Availability, %	99.82	99.41	99.96	95,59	99.98	95.09	٩
CMTBF, hr	1,608	3,417	14,300	990	5,580	460	
CMTTR, hr	2.83	9.00	5.41	14.27	1.36	7.98	
Corrective MMH/yr	463	41	4	149	0	657	
Preventive MMH/yr	713	96	1	994	0	1,804	
Total MMH/yr	1,176	137	5	1,143	0	2,461	

Table 2-15. Availability Analysis Results - 3.5 Year System

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	Collector	Energy Transport	Energy Storage	Power Conversion	Plant Control	Total System
Total .ailures/yr	32.57	1.23	0.35	4.31	1.62	40.08
Central Failures/yr	1.17	1.13	0.27	3.54	1.62	7.73
Forced Outages, hr/yr	4.14	10.17	1.46	50.52	2.19	68.48
Planned Outages, hr/yr	0	12.80	0	104.00	0	104.00
Total Outage, hr/yr	4.14	22.97	1.46	154.52	2.19	172.48
Forced Outage Rate, %	0.11	0.26	0.04	1.44	0.03	1.88
Planned Outage Rate, %	0	0.33	0	2.97	0	2.97
Total Outage Rate, %	0.11	0.59	0.04	4.41	0.03	4.85
Operating Availability, %	99.88	99.41	99.96	95,59	99.97	95.15
CMTBR, hr	3,387	3,417	14,300	990	5,407	540
CMTTR, hr	3.59	9.00	5.41	14.27	1.35	8.88
Corrective MMH/yr	211	41	4	149	0	405
Preventive MMH/yr	566	96	1	994	0	1,657
Total MMH/yr	777	137	5	1,143	0	2,062

Table 2-16. Availability Analysis Results - 4.5-Year System

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	Collector	Energy Transport	Energy Storage	p <sub>ower</sub> Conversion	Plant Control	Total System	
Total Failures/yr	26.54	1.26	0.18	5.58	1.72	35.28	
Central Failures/yr	0.99	1.15	0.14	4.77	1.72	8.77	
Forced Outages, hr/yr	3.83	10.35	0.39	58.16	2.29	75.02	
Planned Outages, hr/yr	0	12.80	0	104.00	0	104.00	
Total Outages, hr/yr	3.83	23.15	0.39	162.16	2.29	179.02	
Forced Outage Rate, %	0.10	0.27	0.01	1.66	0.03	2.07	
Planned Outage Rate, %	0	0.33	0	2.97	0	2.97	
Total Outage Rate, %	0.10	0.60	0.01	4.63	0.03	5.04	
Operating Availability, %	99.89	99.40	99,99	95.37	99.97	94.96	
CMTBR, hr	3,900	3,357	27,579	735	5,093	466	
CMTTR, hr	3.87	9.00	2.79	12.19	1.33	8.55	
Corrective MMH/yr	174	41	2	169	0	386	
Preventive MMH/yr	464	96	1	1,122	0	1,683	
Total MMH/yr	638	137	3	1,291	0	2,069	

Table 2-17. Availability Analysis Results - 6.5-Year System

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table 2-1	8. Availabil	ity Analysis	Results - L	ommercial syste	:		
	Collector	Energy Transport	Energy Storage	Power Conversion	Plant Control	Total System	
Total Failures/yr	25.56	1.26	0.18	5.58	3.44	36.02	
Central Failures/yr	1.12	1.15	0.14	4.77	0	7.18	
Forced Outages, hr/yr	4.12	10.35	0.39	58.16	0	73.02	
Planned Outages, hr/yr	0	12.80	0	104.00	0	104.00	
Total Outages, hr/yr	4.12	23.15	0.39	162.16	Û	177.02	
Forced Outage Rate, %	0.11	0.27	0.01	1.66	0	2.05	
Planned Outage Rate, %	0	0.33	0	2.97	0	2.97	
Total Outage Rate, %	0.11	0.60	0.01	4.63	0	5.02	
Operating Availability, %	99.9	99.40	99.99	95.37	100.0	94.98	
CMTBF, hr	3,713	3,357	27,579	735		509	
CMTTR, hr	3.83	9.00	2.79	12.19		10.26	
Corrective MMH/yr	166	41	2	169	0	378	
Preventive MMH/yr	445	96	1	1,122	0	1,664	
Total MMH/yr	611	137	3	1,291	0	2,042	

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Based on the failure rates and operating times, the failures per year were calculated for each of the specified components. This is multiplied by the mean time to recover (MTTR) to obtain the downtime per year for each component. The MTTR was obtained by detailed analysis of recovery times on similar programs and by actual time measurements on test heliostats in field operations at China Lake, California.

A determination was then made on the criticality of each component. If the failure of the component would cause a system shutdown, it is classified as critical. This is the case of most valves, pumps, etc. It was assumed that most sensors and some auxiliary systems (e.g., demineralizer) were not critical and the system could continue to run while corrective maintenance was performed. The majority of the heliostat components are non-critical, as discussed below, due to the fact that the loss of one or a few heliostats would not cause a system shutdown.

The next column (Population) of Tables 2-3 through 2-14 lists the number of components of the generic type within the subsystem. The product of this number and the component downtime per year for the critical component gives the system downtime per year.

The results of this analysis are displayed in Tables 2-15 through 2-18.

The results of the study indicate that the overall availability for this type of system should be about 0.95 with small variations due to design specifics. The 3.5-year program with an axial turbine subsystem, a dual tank energy storage subsystem and 217 heliostats has a projected availability of 95.09%. The 4.5-year system with the same power generation and energy storage but with only 171 heliostats has a projected availability of 95.15%. The 6.5-year and the commercial programs with radial turbine power generation subsystems, single tank energy storage subsystems and 139 and 133 heliostats have an availability of 94.96% and 94.98%, respectively.

The loss of a single heliostat, or a few heliostats, does not directly affect the system availability due to the fact that system outages of less than 2% are not counted as a forced outage (Reference 2-1). Losses greater than 2% are counted as either partial forced outages or total forced outages depending



on the magnitude of the outage. In this study the concept of partial forced outages was not used due to very small probability of losing several heliostats at the same time and the fact that the remainder of the system is a single thread design which means that any critical failure causes a total shutdown. The probability of losing one heliostat in one operating day is 0.15 for the 3.5-year system (and even less for the 4.5- and 6.5-year programs) and 0.0225 for losing two heliostats in one day. The loss of 4 heliostats (probability of 0.00051) would still result in a loss of power of less than 2%.

However, some failures on the heliostat (failure of power or control cables) will cause a loss of 32 heliostats due to the fact that power must be removed from all heliostats on that circuit in order to effect the repair. In addition, failure of a field controller will cause loss of 32 heliostats. These failures are classified as critical and appear in the critical failure classifications in Table 2-3. The collector subsystem in Tables 2-3 and 2-4 include the heliostat field and the receiver.

The large difference between the total failures per year value for the collector subsystem (55.16 in Table 2-15) and the critical failures per year, failures which cause a system shutdown (2.4 in Table 2-15) reflect the fact that most failures in the heliostat field do not cause a system shutdown.

The reduction in collector system total failures, critical failure and forced outage hours from the 3.5-year program and the commercial program reflects the reduction in the number of heliostats from 217 to 133. The corrective maintenance values also reflect this reduction. Most of the preventive maintenance shown for the collector subsystem represents heliostat mirror washing. The details of the maintenance analysis are discussed in Volume III, Section  $\delta$ .2.

The cumulative mean time between failure (CMTBF) and the cumulative mean time to recover (CMTTR) are calculated by dividing the operating time per year by the number of critical failures per year and the forced outage hours per year by the number of critical failures per year.

The differences in failure characteristics in the energy storage subsystems for the different programs reflect the change from a two-tank system to a single-tank dual-media system with the reduction of system components. The

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increase in the failure characteristics of the power conversion subsystem of the 6.5 year and commercial program over the 3.5 and 4.5 year system reflects the change to the radial turbine and the four feedwater heaters as opposed to the axial turbine with no feedwater heaters.

The lack of maintenance manhours for the plant control subsystem reflects the fact that all maintenance on this subsystem will be performed by the supplier and the cost is included in the initial acquisition cost. Also, the plant control subsystem for the commercial program will be redundant, therefore there are no critical failures in that subsystem.

The preventive maintenance (planned outage) downtime is shown for each subsystem. Specifically, this represents the downtime required to clean heat exchanger (steam generator and feedwater heaters) tubes and perform seasonal maintenance on the turbine and generator. However, it is assumed that all of this maintenance would be scheduled at the same time, therefore only the largest downtime (104 hours for the turbine) is charged overall system downtime.

The results of this analysis can be compared to the historical experience of conventional power generating plants as reported in Reference 2-2 and Figure 2-5. The figure shows the operating availability and outages (forced and planned) are strong functions of plant size. There is little information on power plants in the 1 MW range, but extrapolations of the data from larger power plants indicate that the forced outage for a 1 MW plant should be about 2.5%. This compares with the results of this study which range from 1.88 to 2.07%. The lower value from the study probably reflects the relatively simplified designs available at this stage of the program. It would be expected that as the design matures the design will contain more components. The historical data indicate that the planned outage should be about 5.5% as opposed to the study results of 2.97%. This is primarily due to the fact that the solar system operates only 40% of the time; therefore, preventive maintenance can be performed on a 24-hour basis but is only charged at a 0.6-hour basis. The charged planned outage may be somewhat high, based on this comparative analysis, indicating that the critical planned outage may be less.

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#### Figure 2-5. Power Plant Failure Characteristics

The extrapolated availability value is 94% as compared with analysis results of 94.96 to 95.09. This higher availability is primarily the result of the advantage of the charged versus actual planned outage time.

The mean time to recover (MTTR) values used in Tables 2-3 through 2-14 assume that maintenance personnel are on the site or within a short distance. This may not be true in all cases. For example, the maintenance for the plant control will be performed by the noted supplier. Also, maintenance personnel may be situated some distance from some plant locations when several locations utilize on the same maintenance crews.

The results of an analysis of the effect of this type of operation are shown in Figure 2-6. Figure 2-6 shows the drop in system availability as a function of the travel time (time it takes to get to the power plant site).

### 2.3 STAND-ALONE CAPABILITY

The experimental plant, as defined in Volume III, is designed to interface with an existing electrical transmission grid. The plant can be modified to operate as a stand-alone unit in a location not serviced by a grid by making a few alterations.

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Figure 2-6. Effect of Maintenance Personnel Travel Time on System Availability

The most obvious constraint placed upon a plant operating in this mode is that it must be capable of supplying the electrical demand 24 hr/day throughout the year. This can be accomplished by either or both:

- A. Adding a diesel generator capable of supplying the plant rated power.
- B. Adding a fossil fuel fired Hitec heater capable of supplying the heat input necessary for operation.

The diesel generator would provide a reliable, quick-starting source of electrical energy to make up that portion of the electrical load the solar powered steam turbine could not provide. It would also provide a redundant power source for periods of no insolation or when the steam cycle is down for repair or maintenance. The capital cost of such a system would be low, but operating and maintenance costs would be relatively high.

The second approach consists of a fossil fired Hitec heater placed in parallel with the receiver. This heater would function in a capacity identical to that of the receiver, taking the Hitec/HTS from the energy storage at the "cold" temperature and returning it to storage at the "hot" temperature. This unit would not need to be sized for the same thermal output as that required by the steam generator since the steam generator (and power conversion subsystem)

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would not be operating at full capacity 24 hr/day. The heater could then operate 24 hr/day at a reduced output and still supply the necessary energy per day. The use of the plant as a stand-alone unit would require operating the steam cycle 24 hr/day. This would eliminate the penalties associated with daily shutdown and startup procedures such as thermal fatigue, water cleanup procedures, gaseous nitrogen blanketing, and make unsupervised operation less complicated. The capital cost of the fired Hitec heater is less than that of a diesel generator and the operating and maintenance costs are much less due to fewer moving parts and the ability to burn lower grades of fuel than required for a diesel generator.

Assuming that the application is one that can tolerate occasional losses of electrical power, the Hitec heater is the preferred approach due to lower costs and easier operation.

Additional equipment required in a stand-alone plant would be an electrical resistance bank to serve as a buffer for electrical load transients. This unit would be cooled using the cooling tower water.

2.4 AUXILIARY POWER REQUIREMENTS

A tabulation of the auxiliary power requirements of the experimental systems is made in Tables 2-19 through 2-21. These power requirements are based on the component efficiencies and power needs presented in Volume III for design conditions during periods of insolation, no insolation, night standby, and emergency shutdown conditions. Where appropriate, the power consumption of cycling units such as the instrument air dryer has been averaged over the cycle period. The results of these tabulations have been used to refine (1) the gross electrical power that the turbine should produce for 1 MWe net power, and (2) the gross electrical energy to be produced annually to meet the 0.4 capacity factor requirement.

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Component	Daylight operation (1.0 mW <sub>e</sub> )	Evening operation (1.0 mW <sub>e</sub> )	Night standby	Emergency power (AC)
Steam Generator Feed Pump	23.0	23.0	No	No
Condensate Pump	2.3	2.3	No	No
Condenser Exhauster Vacuum Pump	6.0	6.0	No	No
Condensate Transfer Pump	No	No	0.1	No
Plant Air Compressor	2.8*	2.8*	0.5**	No
Circulating Water Pump	13.8	13.8	No	No
Cooling Tower Fan	15	15	No	No
Turbine DC Oil Pump	No	No	No	No
Chemical Pumps	1.9	1.9	No	No
HVAC	5.0	5.0	3.0	5.0
Lighting	3.0	3.0	2.0	1.0
Uninterruptable Power Supply	7.5	7.5	7.5	8.3
Receiver Pump	40	No	No	No
Hot Storage Pump	6	6	No	No
Heliostats	6.0	No	No	24.9
Trace Heating	No	No	].7****	1.7****
Powdex Recirculating Pump	No	No	Neg	Neg
Plant Air Dryer	0.7***	0.7***	0.7***	No
Misc Equipment				
Transformer and Transmissior Loss	1 	1	Neg	Neg
TOTAL	134.0	88.0	15.5	40.9

Table 2-19. Plant Auxiliary Power Requirements (kW), 3.5-Year Axial Turbine Case

\*Estimated average power requirement during operation-maximum requirement 11.9 kW

\*\*Estimated average power requirement during standby-maximum requirement
11.9 kW

\*\*\*Average requirement based on one regeneration per 4 hours — requirement is 1.8 kW for 1-1/2 hours

\*\*\*\*Estimated average power requirement during 14-hour standby

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Component	Daylight operation	Evening operation	Night	Emergency power
	(1.0 mme)	(1.0 mme)	Scattuny	(70)
Steam Generator Feed Pump	18.4	18.4	No	No
Condensate Pump	1.9	1.9	No	No
Condenser Exhauster Vacuum Pump	6.0	6.0	No	No
Condensate Transfer Pump	No	No	0.1	No
Plant Air Compressor	2.8*	2.8*	0.5**	No
Circulating Water Pump	11.4	11.4	No	No
Cooling Tower Fan (avg)	113.0	13.0	No	No
Turbine DC Oil Pump	No	No	No	No
Chemical Pumps	1.9	1.9	No	No
HVAC	5.0	5.0	2.0	5.0
Lighting	3.0	3.0	2.0	1.0
Uninterruptable Power Supply	2.0	2.0	2.0	2.8
Receiver Pump	3.0	No	No	No
Hot Storage Pump	5	5	No	No
Heliostats	5.4	No	No	22.4
Trace Heating	No	No	1.3****	1.3****
Powdex Recirculating Pump	No	No	Neg	Neg
Plant Air Dryer	0.7***	0.7***	0.7***	No
Misc Equipment				
Transformer and Transmission Loss	ן נ	1	Neg	Neg
TOTAL	107.5	72.1	8.6	32.5

Table 2-20. Plant Auxiliary Power Requirements (kW), 4.5-Year Axial Turbine Case

\*Estimated average power requirement during operation-maximum requirement 11.9 kW

\*\*Estimated average power requirement during standby-maximum requirement
11.9 kW

\*\*\*Average requirement based on one regeneration per 4 hours - requirement is 1.8 kW for 1-1/2 hours

\*\*\*\*Estimated average power requirement during 14-hour standby



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Component	Daylight operation (1.0 mW <sub>e</sub> )	Evening operation (1.0 mW <sub>e</sub> )	Night standby	Emergency power (AC)
Steam Generator Feed Pump	19.3	19.3	No	No
Condensate Pump	1.0	1.0	No	No
Condenser Exhauster Vacuum Pump	6.0	6.0	No	No
Condensate Transfer Pump	No	No	0.1	No
Plant Air Compressor	2.8*	2.8*	0.5**	No
Circulating Water Pump	8.4	8.4	No	No
Cooling Tower Fan (avg)	10	10	No	No
Turbine DC Oil Pump	No	No	No	No
Chemical Pumps	1.9	1.9	No	No
HVAC	5.0	5.0	2.0	5.0
Lighting	3.0	3.0	2.0	1.0
Uninterruptable Power Supply	2.0	2.0	2.0	2.8
Receiver Pump	14	No	No	No
Hot Storage Pump	3	3	No	No
Heliostats	4.0	No	No	16.6
Trace Heating	No	No	8.1****	8.1****
Powdex Recirculating Pump	No	No	Neg	Neg
Plant Air Dryer	0.7***	0.7***	0.7***	No
Misc Equipment	1			
Transformer and Transmission Loss	n k	1	Neg	Neg
TOTAL	82.1	64.1	15.4	33.5

Table 2-21. Plant Auxiliary Power Requirements (kW), 6.5-Year Radial Turbine Case

\*Estimated average power requirement during operation-maximum requirement 11.9 kW

\*\*Estimated average power requirement during standby-maximum requirement
11.9 kW

\*\*\*Average requirement based on one regeneration per 4 hours - requirement is 1.8 kW for 1-1/2 hours

\*\*\*\*Estimated average power requirement during 14-hour standby

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# Section 3 COLLECTOR SUBSYSTEM ANALYSIS - CONCENTRATOR ASSEMBLY

Four trade studies have been identified for adapting existing heliostat designs to small power systems. The trade studies stem from two requirements specific to small central receiver power systems. The first requirement is to generate a reflected image size at the receiver which is sufficiently small to achieve the desired concentration ratio. High concentration ratios are desired to maximize receiver efficiency and minimize receiver size and cost. The second requirement is to minimize the assembly, transportation, and installation costs of the heliostats and field electronics, consistent with the requirements of small power systems.

Most of the design analyses which are necessary to perform the preliminary trade studies have been performed under parallel contracts and prior company funded studies.

### 3.1 DESIGN MODIFICATIONS TO THE HELIOSTATS

Design modifications to the heliostats to achieve the short focal lengths of a small power system include curving the mirror modules and establishing cant angles for each mirror module.

#### 3.1.1 Mirror Module Curvature

An individual mirror module is 1.22 by 3.15 m (48 by 124 in) for the Barstow heliostat. If this module were perfectly flat, perfectly aligned, and the sun's rays perfectly parallel, the image from the mirror module would be exactly its size. All of the reflected energy could be accepted into a 3.5-m-diameter aperture. However, the sun angle, alignment errors, and surface irregularities combine to cause a total cone angle spread of about 12 mrad.



At the maximum slant range of EE No. 1 ( $\sim$ 200 m), this spread adds an effective 2.4 m to the image size from a nominally flat mirror module. Thus, the apparent size of an individual mirror module grows to about 3.62 by 5.55 m.

The short dimension is still well within the allowable for 4.5-m receiver aperture of EE No. 1. However, the long dimension falls somewhat outside the aperture. Providing a single curvature in the long dimension to achieve perfect focus at about 200 m, as described in Volume III, Section 4.2, will give the minimum image size, and the image becomes 2.4 by 3.62 m. It is easily shown that holding the radius of curvature constant for all heliostats produces a net image size which is everywhere smaller than that of the most remote heliostat. For example, at 100 m, the growth due to sun and angular errors is 1.2 m. The apparent height is half of the 3.15 m actual height or 1.575 m. The image size is 2.775 by 2.42 m. This image is only about 77% as large as the image at 200 m.

Off-axis aberration will cause the image height to be either greater or less than that indicated above. However, the off-axis angles for the north field are sufficiently small that the effects of aberration are not dominating.

Detailed computer studies conducted on the DOE 10 MWe Pilot Plant program (Reference 3-1) verify the adequacy of this approach.

These analyses were used to establish that the mirror modules will be singly curved to a single radius of curvature equal to twice the maximum slant range (perfect focus at the maximum slant range).

### 3.1.2 Mirror Module Cant Angles

The reflective unit, comprised of 12 mirror modules plus support structure, would still produce an unacceptably large image at the receiver if all the mirror modules were parallel. Cant angles are introduced for each mirror module to cause the images of the individual mirror modules to be superimposed at the receiver. A spherical focus of the mirror modules is thereby achieved.



The larger dimensions of the reflective unit (7 by 7.4 m) will require that the reflective unit focal length (cant angles) be varied over the field. No substantial additional growth in image size can be permitted if the image size is to be bounded by the 4.5-m aperture. Hence, it appears that five discrete cant angle sets or reflective unit focal lengths will be required.

Two methods for providing variable cant angles for the heliostat were considered. In the first method, a kit of standard spacers would be made for each discrete focal length desired. The reflector panels would be assembled with a nominal cant angle for all panels. The heliostats would be mounted on the foundations and a crew would insert a kit of standard spacers between the support structure and the mirror modules to achieve the offset required from the nominal cant angles.

The second method employs an automatically adjusting assembly fixture for the reflector panel. The fixture is adjusted for each panel focal length and the changes in cant angles are taken up in the bondline thickness between the cups or stringers and the mirror module. For Small Power Commercial System requiring less than 200 heliostats, this method of obtaining cant angles can easily be accomplished in a high volume production line. By introducing an adjustable bonding fixture in a production loop parallel to the production line, the few heliostats having special cant angle requirements can be pulled from the production line and sent through the loop. The cost impact of adding the adjustable bonding fixture is small, especially for commercialization of the Small Power Systems.

#### 3.2 SUBSYSTEM ASSEMBLY AND CHECKOUT

The 10 MWe Pilot Plant heliostats have been designed to utilize a site assembly facility. The facility receives details of the reflective unit plus assembled main beams and mirror modules. The reflective units are built up and integrated with the remainder of the heliostat. The heliostat is then moved as one piece to the foundation and emplaced. The validity of this production approach tends to vary with site size and production volume.



The alternative approach adopted for Small Power Systems is to divide the reflective unit into two halves. The drive unit includes the center section of the main beam and the mounting interfaces for the reflector panels. The drive unit is assembled in the factory and shipped to the site. It is in the factory and shipped to the site. It is in the factory and shipped to the drive unit, again using automated equipment.

Small Power Systems will not provide for the installation of enough heliostats in one location to justify a site assembly facility. The allocated cost of moving a site assembly facility from one small power system site to another may exceed  $10/m^2$ . Hence, the approach of assembly on the pedestal is preferred. A final determination will be made during the preliminary design phase (Phase II) on the installation equipment design.

### 3.3 COLLECTOR FIELD ELECTRONICS

The pilot plant and second generation heliostats employ intermediate distribution points in the field for both power and data communication networks. Field transformers are used to step high voltage ( $\sim$  2.4 kV) primary feeder power down to 208/240 V power for the heliostats. Each transformer services 200 to 300 heliostats. For the small power system, the field transformers will not be required. A decision has been made to distribute power directly from the power conversion subsystem to the heliostats along 7 (for the 3.5-year program) parallel, serial hookups of about 32 heliostats each.

The data network uses high baud rate serial connections to each of the field controllers. The field controllers control the heliostats by a secondary, low baud rate serial hookup. EE No. 1, using the pilot plant controls system, will employ such a serial connection. However, in the 4.5-, 6.5-year and in the commercial programs, the field controller function may be incorporated into the plant controller.

### 3.4 MIRROR MODULE THERMAL CHARACTERISTICS

The mirror modules of both heliostat designs use, in effect, glass backed by steel. As the mirror module temperature changes, the different thermal

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expansion coefficients of the glass and steel will cause a warping of the mirror, i.e., a tendency to change focal length. The total movement of the mirror module from  $0^{\circ}$ C to  $40^{\circ}$ C is about 10 mrad in the reflected beam. Hence, this effect is not negligible.

For the pilot plant mirror module, the thermal warping can be reduced by increasing the foam core thickness. Doubling the thickness cuts the warping in half and reduces spillage accordingly. The added cost would be about  $4/m^2$ .

Composite (glass fiber/plastic) stringers designed to match the expansion coefficient of the mirror glass may eventually prove economic for the second generation heliostat configuration. This approach would completely eliminate thermal warping.

The trade study to determine the most cost effective approach among the three alternatives (accept the losses, reduce the losses by increasing mirror module thickness, and reduce losses by use of composite structures) must be determined for the specific field layout. The results are expected to be that the curvature of the mirror modules is biased to minimize annual losses, and no design changes are made. Based on data previously reported in the first quarterly report, losses are expected to be not more than about one percent. If this result is verified, no corrective design action will be justified.

# Section 4 COLLECTOR SUBSYSTEM ANALYSES - RECEIVER ASSEMBLY

### 4.1 ABSORBER CONFIGURATION SELECTOR

The investigation leading to a set of receiver design conditions appropriate to the 3.5-year program goals is described in this section. The objectives are: (1) a minimum absorber surface area, together with a power density distribution and fluid flow path such that the peak receiver temperature occurs near the apex of the cavity; (2) a peak heat flux less than 400 kW/m<sup>2</sup> (126,900 Btu/hr ft<sup>2</sup>); and (3) maximum spillage of 3%.

The absorber surface configuration and the power density distribution over the absorber surface were varied systematically. The resulting configuration/ power density combinations were analyzed to evaluate the receiver performance as limited by the system operating temperatures and by fluid heat transfer.

### 4.1.1 Candidate Configurations/Irradiation Patterns

Outline dimensions of the absorber surfaces which were investigated are shown in Figure 4-1. The design power for all receivers is 7.08 MWt absorbed, and is determined by the thermal efficiency of the power conversion system which has been selected for the 3.5-year program. The aperture diameter of 4.5 m is near the minimum consistent with a maximum spillage of 3% and an acceptable power density distribution at the absorber surface.

Irradiation patterns were obtained by means of the CONCEN computer program. The CONCEN program determines the irradiation pattern at the receiver by summing the circular solar images from elementary areas of the heliostat mirror surfaces. The mirror surface is modeled as 480 identical plane elements, each approximately  $0.1 \text{ m}^2$  ( $1 \text{ ft}^2$ ). Focusing is provided by applying appropriate slope deviations to each mirror element. For computation, a single heliostat is randomly selected. Then a mirror element on that heliostat is randomly selected. The image location and its size, for that element, are computed

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Figure 4-1. 7.\* .orber Surfaces Investigated

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at a plane normal to the reflected beam at the receiver. Points on a grid on a plane receiver absorber surface are projected back, in the direction of the reflected beam, onto the normal plane and their positions are related to that of the element image. By repeating the random selection of elements over the heliostat field 10,000 to 15,000 times, the irradiation pattern over the grid on the absorber surface is built up. By computing the fraction of each element image that is included within the receiver aperture, the absorbed power and the spillage are determined.

### 4.1.2 Heat Transfer/Fluid Flow Analysis

The absorber surface is a coil of small diameter steel tubing, spiral wound, and arranged to form one or more parallel fluid flow paths through the receiver. Given the total absorbed power, the power density distribution, the design fluid temperatures and the fluid flow path, the analysis proceeds as follows:

- Compute the power density and fluid bulk temperature profiles, from receiver inlet to outlet.
- Determine the location, along the flow path, of the maximum inside tube surface temperature (maximum film temperature) and the corresponding required heat transfer coefficient.
- Determine the number of parallel flow paths, fluid pressure drop and pumping power as functions of tubing diameter and wall thickness.
- Determine the maximum tube metal temperature.

### 4.1.3 Collector Field Model/Heliostat Aiming/Aperture Power Distribution

The power density distribution at the receiver aperture is determined by the design of the individual heliostat (i.e., mirror size, number of mirror elements per heliostat, element curvature and canting), the layout of the collector/ receiver complex (i.e., the total number of heliostats and their locations relative to the receiver), and the aiming pattern. The field conditions are given in Table 4-1.


Table 4-1. Operating Conditions for Power Density Distributions

217 heliostats, in radial - concentric array 7.4 x 7.4 m heliostat mirrors Reflectance - 0.88 Mirror surface waviness - 1.1 mrad, 10 Tower height = 40 m Date = March 21 Time = 1000 hr Atmospheric attenuation coefficient = 0.092 km<sup>-1</sup> Latitude = 35° N Receiver cavity tilt = 30°, 20°, and 15° toward N Cant angle adjusted for each heliostat location Panel curvature = 0.0025 m<sup>-1</sup> Ambient temperature = 90°F Pointing error = 2 mrad, each coordinate axis

The following aiming patterns, with variations, were investigated and are shown in Figure 4-2.

- One-point: All heliostats are aimed to project an image which is centered on the receiver aperture.
- Four-point, Five-point, Eight-point-circle: Equal numbers of heliostats, uniformly distributed in the collector field, are assigned to each aim point.
- Eight-point: Heliostats at distances greater than 100 m are aimed in the 1.4 by 1.4 m square pattern. Those at less than 100 m are aimed in the 2.1 by 2.1 m square pattern.
- Nine-point: Heliostats at distances greater than 150 m are aimed at the center of the receiver. Those between 150 and 100 m are aimed in the 1.4 by 1.4 m square pattern and those less than 100 m distance are aimed in the 2.1 by 2.1 m square pattern.

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# Nine-point-circle-and-center: Heliostats at distances greater than 150 m are aimed at the center of the receiver. All others are uniformly distributed among the eight points on a 1.5 m diameter circle.

Figure 4-3 shows the power density distributions, along a horizontal center line in the aperture plane, for 7.08 MWt into a 4.5 m diameter aperture, for the aiming patterns of Figure 4-2. As would be expected, the peak power density decreases with spreading of the aim points; actually from about 2.8  $MW/m^2$  for the one-point aim to 0.5  $MW/m^2$  for the four-point (1.75 by 1.75 m) aim point.

Peak power density, peak/average ratio, and percent spillage are tabulated, for the various aiming patterns, in Table 4-2. The 8-point, 8-point- circle (2.6 m) and the 4-point (1.75 by 1.75 m) aiming patterns are rejected because of excessive spillage.

		Peak MWt/m <sup>2</sup>	
Aiming Pattern	Peak MWt/m <sup>2</sup>	Average MWt/m <sup>2</sup>	Spillage, %
1-Point	2.6	6.2	0.3
5-Point, 1 x 1 m	1.8	4.0	0.90
5-Point, 1.5 x 1.5 m	1.0	2.3	1.75
4-Point, 1.5 x 1.5 m	0.77	1.6	2.1
4-Point, 1.6 x 1.6 m	0.58	1.4	2.6
4-Point, 1.75 x 1.75 m	0.50	1.2	4.4
9-Point Squares and Center	0.90	1.9	3.3
9-Point Circle and Center	1.5	3.7	0.2
8-Point Squares	0.57	1.4	4.3
8-Point Circle 1.5 m	1.4	2.9	.7
8-Point Circle 2.12 m	0.80	1.8	1.9
8-Point Circle 2.6 m	0.61	1.4	5.3

Table 4-2. Power Density at Aperture Plane and Spillage vs Aiming Pattern\*

\*7.08 MWt

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4.5-m-diameter aperture

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Figure 4-3. Power Density Profiles At Horizontal Centerline of Aperture (7.08MWt)

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### 4.1.4 Absorber Configuration Screening Analysis

As a starting point for optimizing the absorber configuration, CONCEN power density profiles were generated for configurations 1 through 8 of Figure 4-1 using the five-point 1 by 1 m aiming pattern, and for configurations 1 and 7 using the one-point aim. These configurations are variations of the receiver types which were identified as being the most favorable in initial screening (Volume II). Figures 4-4 through 4-13 show the power density profiles at the absorber surface, along a line from the aperture edge of the horizontal center line to the apex of the cone. The peak power densities are all greater than  $0.4 \text{ MW/m}^2$ . For all of these configurations, the five-point aim appears to be too narrow; and, for the partial-cavity configurations, the depth of the conical section should be increased.

Power density profiles for configurations 6B, 9A, 10, and 12B are shown in Figures 4-14 through 4-17. All of these meet the design objectives for spillage and peak power density. However, configurations 6B and 9A are deficient in that the peak power density occurs at locations deep inside the cavity. In order to maintain the design temperatures and reasonable flow velocities with these configurations, the low temperature fluid must enter the receiver at the apex of the cone, and the heated fluid exit at the edge of the aperture. In order to achieve minimum radiation and convection losses, this temperature profile should be reversed, i.e., minimum temperature should occur at the edge of the aperture, and maximum temperature at the apex of the cone.

Configurations 10 and 12B can be operated with "edge-to-center" fluid flow, to give the desired temperature profile. Configuration 12 has slightly smaller surface area.

#### 4.1.5 Absorber Configuration Optimization

A receiver tilt of  $30^{\circ}$  downward, and several aperture-centered aiming patterns (Figure 4-2) were used for the preceding horizontal centerline profiles, which show the power density along the line of intersection of the absorber surface with the plane containing both the horizontal diameter of the aperture and the apex of the cone. The horizontal profile may or may not be representative of the entire absorber surface, depending upon the aiming

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Figure 4-4. Cavity Receiver Irradiation - Configuration 1A, 1-Point Aim



Figure 4-5. Cavity Receiver Irradiation - Configuration 1B, 5-Point Aim - 1.0 x 1.0 m

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Figure 4-6. Cavity Receiver Irradiation - Configuration 2, 5-Point Aim - 1.0 x 1.0 m



Figure 4-7. Cavity Receiver Irradiation -- Configuration 3, 5-Point Aim - 1.0  $\times$  1.0 m

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Figure 4-8. Cavity Receiver Irradiation - Configuration 4, 5-Point Aim - 1.0  $\times$  1.0 m

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Figure 4-9. Cavity Receiver Irradiation - Configuration 5, 5-Point Aim - 1.0 x 1.0 m

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Figure 4-10. Cavity Receiver Irradiation - Configuration 6A, 5-Point Aim - 1.0 x 1.0 m



Figure 4-11. Cavity Receiver Irradiation - Configuration 7A, 1-Point Aim

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Figure 4-12. Cavity Receiver Irradiation - Configuration 78, 5-Point Alm - 1.0 x 1.0 m



Figure 4-13. Cavity Receiver Irradiation - Configuration 8, 5-Point Aim - 1.0 x 1.0 m

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Figure 4-14. Cavity Receiver Irradiation - Configuration 6B, 5-Point Aim - 1.5 x 1.5 m



Figure 4-15. Cavity Receiver Irradiation - Configuration 9A, 4-Point Aim - 1.5 x 1.5 m

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Figure 4-16. Cavity Receiver Irradiation - Configuration 10, 4-Point Aim - 1.5 x 1.5 m



Figure 4-17. Cavity Receiver Irradiation - Configuration 12B, 9-Point Aim

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pattern and the tilt of the receiver axis with respect to the heliostat field. Figures 4-18 and 4-19 show the effect of receiver tilt, for configuration 6A. Three power density profiles (horizontal, 45° and vertical) are shown in each figure. For the 30° tilt angle, Figure 4-18, the peak power density occurs in the vertical cross-section on the lower half of the absorber surface and it is evident that more than half of the total power is absorbed in the lower half of the receiver. For the 15° tilt angle, the peak occurs in the vertical crosssection on the upper half of the absorber surface, and more than half of the power is absorbed in the upper half of the receiver.

The situation is similar for receiver configuration 12B as shown in Figures 4-20 and 4-21. Also, it is apparent that for this receiver shape, the design goal of 0.4  $MW/m^2$  peak cannot be met with the 9-point-squares-and-center aim, which tends to concentrate the irradiation at the 45° cross-section.

Figure 4-22 shows power density profiles for configuration 12C. The tilt is 20° and a circular aiming pattern is used to improve the circumferential symmetry of the power distribution. The flux peak at the junction of the inner and outer cones has been reduced by substituting a 16.5 cm radius for the sharp corner.

Figure 4-23 shows heat flux and fluid bulk temperature profiles along the spiral flow path for configuration 12C.

#### 4.2 ABSORBER THERMAL PERFORMANCE

A wide spectrum of receiver absorber concepts was studied, and the most promising of these were selected for more detailed analyses of thermal performance, hydraulic characteristics, and fatigue life. A summary of the analyses and design work accomplished by Rocketdyne is given in this Section.

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Figure 4-18. Irradiation Profiles, 30<sup>0</sup> Tilt

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Figure 4-19. Irradiation Profiles, 15<sup>0</sup> Tilt



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Figure 4-22. Irradiation Profiles, 20<sup>0</sup> Tilt -

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Figure 4-23. Fluid Temperature and Heat Flux Profiles, Receiver Configuration 12C, 7.08 MWT

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#### 4.2.1 Computer Model

A computer model was developed for performing a numerical integration of heat input and pressure drop along one or more tubes wound in a spiral with the contour of its wall defined by radius and depth coordinates. Heat flux is input either as the aperture field in radial and angular coordinates or as a table of flux versus position along the length of the tubes. With inputs of flowrate, tube diameter and thickness, required coolant inlet pressure and inlet temperature, the program computes number of tubes in parallel, and at each nodal point on the tube, it computes the wall angles, coolant heat transfer coefficient, tube wall coolant surface and hot surface temperature, coolant temperature, pressure drop, Reynolds number, velocity and coolant properties. A subroutine for computing tube cross section temperatures provides data for accurate computation of fatigue life at the maximum heat flux location. To optimize the design, several parameters were varied with the program such as wall contour, routing of the flow circuit, and tube size. The computer program has the capability for thermal-hydraulic analysis of variations and combinations of the spiral disk and cone configurations. A printout of a typical run is shown in Figure 4-24. About 175 of these runs were performed during the Phase I program.

#### 4.2.2 Preliminary Study Results

Thermal, hydraulic, and fatigue life analyses were performed for the spiralflow-path conical cavity. The results are summarized in Tables 4-3, 4-4, and 4-5. The parameter Rw, the ratio of the tube OD to wall thickness, should not be greater than about 17 to ensure that the tube can be bent without undue flatening; i.e., this is a fabricability parameter.

The results show that, to attain an acceptable fatigue life and a reasonable fluid pressure drop across the absorber, a combination of heat flux less than about 600 kW/m<sup>2</sup> and coolant velocity less than about 3 mps is required. In addition, a tube material having a high thermal conductivity combined with an inherently high resistance to fatigue damage is advantageous. Note that the design finally derived permits a safety factor, since the heat flux is kept closer to 400 kW/m<sup>2</sup> than to 600 kW/m<sup>2</sup>.

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и.	240.6	200.0	560.0	sap.a	n, n	4.6	42879.1	ព.ព	119.0	0.00/957	8.41	6.0	0.071796
400.	543.3	193.4	525.1	542.2	14.3	15944 8	41332.4	817.0	117.9	P.082975	8.42	307.P	0.071750
600.	509.0	187.7	541.5	566.9	12.5	74462.5	44140.4	r45.5	117.8	0.002872	8.41	288.7	8.821572
1700.	517.0	192.0	\$59.7	593.7	17.0	12059.1	45425.1	157.4	117.4	1.192797	H.44	288,9	8.021555
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2008.	554.7	178.7	687.6	788.6	55.4	105895.5	519C 3. 8	914.2	116.6	8.007442	8.51	11.3	2.820979
2400.	589.6	145.2	731.5	843.3	67.0	120329.9	59952.8	767.4	115.8	0.002114	8.5A	125.5	3.020192
2840.	614.2	159.8	722.5	809.7	49.6	97421.5	66274.8	1010.5	115.0	0.001918	8.61	292.7	0.019990
1200	£45+5	154.4	754.8	A46.5	53.6	99848.4	71569.6	1051.6	114.4	0.001771	8,46	156.4	8.019673
3600.	675.1	149.5	787.1	384.8	34.7	107477.2	78615.2	1746'3	113.6	0.001612	8,74	68.7	8.819347
4000.	786.7	144.6	826.2	921.7	36.7	111524.7	97068.2	1142.3	112.8	8.461455	P 84	46.6	a 414017
4200.	723.3	142.8	836.9	919.2	11.7	115527.8	90519.1	1162.0	112.4	0 001403	2 a 1	107 0	4 410760
4408.	734.7	139.4	850.4	951.1	30.9	114468.3	94.342.4	1181.6	112.0	0.001145	8.87	296.4	0.010000
4686.	755.7	136.8	864.6	957.1	29.9	113261.2	98179.2	1.780.8	111.6	3 001 701	8.04	349 9	0.010460
4888.	771.1	114.2	860 G	961.5	28.5	105177.7	102261.4	1210.4	i i i . 7	R.801240	8.91	133.4	0.019319
51411	785.7	131.9	878.1	965.1	16.1	taganz, t	106488.7	1217 9	110.8	d au 100	* **	e1 e	
5768.	799.5	129.5	884.4	965.5	15.2	91196.8	110008.7	1254.8	110.4	8.301144	8.99	156.1	6.019075
5400	812.2	127.2	989 8	961.5	11.8	85144.6	111402.5	1266.5	113.1	0.001118	9.07	11.0	8.817923
5500.	H18.3	125.4	041.0	961.5	11.0	610 19.0	11111.1.1.1	1272.4	109.9	3.001106	7.43	114.2	8-017001
5689.	823,9	124.6	892.7	954.7	14.4	77012.0	1150:19,4	1277.4	119.8	9.001094	9.64	240.0	A. #17867
5780	829.2	121.4	894.2	957.7	9.9	72985.0	114995 4	1201 1	109 7				
5640.	614.2	177.2	893.a	952. t		67209.9	115960.7	1248 0	100 6	P+P01003	34117	1144.0	0.017700
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6900.	842.9	119.8	891.6	9 19 . 9	1.5	55758.9	120055.4	1.006.6	101.1	0.001066	3.07	344.3	0.0177/68
4050.	u44.9	119.2	\$90.8	936,5	3,5	52711.4	128584.0	1298.5	1#9.3	9.081052	9.89	98.3	8.017726
6138.	£15.7	118.6	964.0	011.A		40993 6	110000	1144 1					
6150.	848.4	118.8	869.4	3 35 6		16736 0	121210 0	1300+3	199.2	H. 401048	9.89	248.9	0.817714
6248.	658.4	117.4	117.4	036.7	1.1	41748 -	121211.9	1302.0	149.2	8.001045	9.89	84.9	8.017762
625#.	851.5	15.8	A86.6	077 8	1 3	43247.1	122403 0	1183.5	199.2	W. RR1342	9.IN	331.6	9.017692
6114.	852.9	116.2	585.4	919.1	112	17377 5	179169 4	1304.9	109.1	9.801839	9+18	274.9	0.017687
					++ 7	1.4.2.3	174392.4	1186,3	193.1	a.a01#36	<b>310</b>	319.8	Ø.617672
6325.	853.5	115.9	884,7	916.2	1.2	15744.8	122513.8	1107.0	169.1	A. 201035	9.10	67 6	4 117668
6342.	934.8	115.7	884.2	914.8	A.3	34674,2	122611.4	1187.5	149.1	4.401014	9.1#	78.9	A.017664

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NUMBER OF ITERATIONS = 54 Difference Hetween Heat in and Jut = 0.009775 Crown Heat Flux = 0.25560/102-5 of 1:2179.0/Ft2-00



Figure 4-24. Typical Computer Printout of Absorbent Thermal Analysis Code (3.5-Year Program Design)

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Tubing Size			e							
Number of	ID	OD	Wall		Tm	Τf	Th	ΔP	V	
Parallel Tubes	cm (in.)	cm (in.)	cm (in.)	Rw	°C (°F)	°C (°F)	°C (°F)	Bars (psi)	m/sec (ft/sec)	
4	4 3.891 4.445 0.277 (1.532) (1.750) (0.109)		0.277 (0.109)	16	427 (801)	387 (729)	519 (966)	5.8 (84)	2.77 (9.10)	
5	3.338 (1.334)	3.81 (1.50)	0.211 (0.083)	18	409 (769)	379 (714)	504 (939)	7.0 (102)	2.93 (9.61)	
5	3.327 (1.310)	3.810 (1.50)	0.241 (0.095)	16	414 (778)	378 (713)	509 (948)	7.7 (112)	3.04 (9.96)	
6	6 3.256 3.810 0.277 (1.282) (1.50) (0.109)		0.277 (0.109)	14	429 (805)	388 (731)	52] (970)	5.2 (75)	2.64 (8.67)	
<pre>NOTES: Rw: Ratio of tube OD to wall thickness Tm: Hotest outside tube wall temperature at point of maximum heat flux (flux = 416 kW/m<sup>2</sup>) Tf: Film temperature at the same point as Tm Th: Hotest point on hotest tube in entire absorber Heat Load: 7.08 MW(t) Fluid: Molten HITEC at flowrate of 84,000 kg/hr Fluid Inlet/Outlet Temperature: 260 (500)/454 (850) °C/(°F) Material: CRES 304 V. Fluid valocity at absorber apex (outlet)</pre>										

Table 4-3. Summary of Preliminary Thermal Analysis Study of a 4.5 m Aperture Partial Cavity Absorber (3.5-Year Program)



(in the

	Τu	Tubing Size							
Number of	ID	OD	Wall		Tm	Tf	Th	ΔP	V
Parallel Tubes	cm (in.)	cm (in.)	cm (in.)	Rw	°C (°F)	°C (°F)	°C (°F)	Bars (psi)	m/sec (ft/sec)
3	4.023 (1.584)	4.45 (1.75)	0.211 (0.083)	21	440 (825)	412 (774)	551 (1023)	5.86 (85)	2.67 (8.78)
3	3.962 (1.56)	4.45 (1.75)	0.241 (0.095)	18	444 (831)	441 (771)	554 (1030)	6.4 (93)	2.76 (9.05)
3	3.891 (1.532)	4.45 (1.75)	0.277 (0.109)	16	447 (837)	409 (769)	558 (1037)	7.0 (101)	2.86 (9.39)
4	3.891 (1.532)	4.45 (1.75)	0.277 (0.109)	17	462 (863)	425 (797)	569 (1056)	3.0 (44)	2.15 (7.04)
4	3.388 (1.334)	3.81 (1.50)	0.211 (0.083)	18	436 (816)	407 (764)	549 (1020)	7.0 (101)	2.82 (9.28)
4	3.327 (1.310)	3.81 (1.50)	0.241 (0.095)	16	437 (819)	404 (760)	552 (1026)	7.7 (112)	2,94 (9.63)
5	3.256 (1.282)	3.81 (1.50)	0.277 (0.109)	14	452 (846)	414 (778)	563 (1046)	4.6 (66)	2.45 (8.04)
NOTES:				L					
Rw: Ratio Tm: Hotes	of tube. t outside	OD to wa tube wa	ll thickn 11 temper	ess atur	e at po	int of :	maximum	heat flu	x
(flux	= 400 kW	/m²)							
Th: Hotes	t point o	re at th n hotest	e same po tube in	enti	as im re abso	rber			
Heat Load:   Fluid: Mo	6.05 MW Iten HITE	(t) C at flo	wrate of	62 Q	00 ka/h	~			

# Table 4-4. Summary of Preliminary Thermal Analysis Study of a 4.28 m Aperture Partial Cavity Absorber (4.5- Year Program)

Fluid: Molten HITEC at flowrate of 62,800 kg/hr Fluid Inlet/Outlet Temperature: 288 (550)/510 (950) °C/(°F) Material: CRES 304 V: Fluid velocity at absorber apex (outlet)

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	Tu	Tubing Size								
Number of	ID	OD	Wall		Tm	Ĩf	Th	ΔP	V	
Parallel Tubes	ст (in.)	cm (in.)	cm (in.)	Rw	°C (°F)	°C (°F)	°C (°F)	Bars (psi)	m/sec (ft/sec)	
3	3.388 (1.334)	3.81 (1.50)	0.211 (0.083)	18	436 (816)	409 (768)	569 (1056)	7.4 (107)	2.47 (8.96)	
3	3.327 (1.310)	3.81 (1.50)	0.241 (0.095)	16	437 (819)	407 (764)	572 (1061)	8.1 (118)	2.83 (9.29)	
4	3.327 (1.310)	3.81 (1.50)	0.241 (0.095)	16	467 (873)	434 (814)	603 (1117)	3.6 (52)	2.15 (7.06)	
4	3.256 (1.282)	3,81 (1,50)	0.277 (0.109)	14	456 (852)	421 (790)	582 (1080)	4.0 (59)	2.22 (7.27)	
5	2.845 (1.120)	3.175 (1.25)	0.165 (0.065)	19	433 (812)	413 (775)	566 (1051)	4.9 (71)	2.32 (7.62)	
5	2.753 (1.084)	3.175 (1.25)	0.211 (0.083)	15	434 (814)	408 (767)	571 (1059)	518 (84)	2.48 (8.14)	
5	2.672 (1.052)	3.175 (1.25)	0.251 (0.099)	13	437 (819)	406 (763)	575 (1067)	6.7 (97)	2.63 (8.64)	
NOTES:		L			L	L	<u> </u>			
Rw: Ratio of tube OD to wall thickness Tm: Hotest outside tube wall temperature at point of maximum heat flux (flux = 400 kW/m <sup>2</sup> ) Tf: Film temperature at the same point as Tm Th: Hotest point on hotest tube in entire absorber Heat Load: 4.72 MW(t) Fluid: Molten HTS at flowrate of 44,900 kg/hr Fluid Inlet/Outlet Temperature: 288 (550)/566 (1050) °C/(°F)										
Material: V: Fluid	velocity	at absor	ber apex	(out	let)					

## Table 4-5. Summary of Preliminary Thermal Analysis Study of a 4 m Aperture Partial Cavity Absorber (6.5-Year Program)

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Using this analysis and the results shown in Section 4.1, the partial cavity configuration was selected. The regulating power density and tube wall temperature profiles are shown in Figure 4-25 for the 3.5-year program design.

#### 4.3 STRUCTURAL DESIGN ANALYSIS

The primary purpose of the stress analysis is to ensure that the design is consistent with the applicable codes and that the predicted life of the absorber is adequate for the specified life of 30 years and 11,000 temperature cycles. Stress analyses are directly related to the thermal analysis results discussed above which define tube wall temperatures and temperature gradients. The two principal failure modes are discussed below: creep and low-cycle fatigue.

#### 4.3.1 Creep Rupture Analysis

Any material operating at high temperature suffers creep damage and fails with a limited life under lower stress conditions than its short-term measured strength. The receiver tubes are subjected to a small internal pressure simultaneous with high temperature. The creep rupture life of the tube is determined by the tube hoop stress. For both Incoloy 800 and 316 stainless steel, the creep rupture life is substantially higher than the specified 30-year life time under the temperature and tube hoop stress calculated for the present absorber design. Hence, the effect of creep damage in this case is negligible.

#### 4.3.2 Low Cycle Fatigue Analysis

Since only part of the tube surface is exposed to the insolation, temperature gradients exist along the tube circumference and across the tube wall under high heat flux conditions. This usually induces plastic strain in the tube and could possibly lead to low cycle fatigue failure if large strain variation occurs with the temperature cycling. The number of allowable cycles for a given material is a function of the design cycle strain range and the metal temperature. It decreases with increase in strain range and metal temperature.

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Figure 4-25. Tube Wall Temperature and Heat Flux Profiles (3,5-Year Design)

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In this case, low cycle fatigue is considered to be the most critical factor affecting the receiver panel design life because of the large number of daily temperature excursions which the absorber will be subjected to during the 30-year life duration.

If the loading condition and the strain range are variable, then the accumulated creep and fatigue damage sustained during the various loading conditions are elevated. The total creep fatigue damage is a linear function of the creep component and the fatigue component is given in the ASME Code Case of N-47 (1592-10), and in the criteria for Design of Elevated Temperature Class 1 Components in Section III, Div. I, of the ASME Boiler and Pressure Vessel Code (Section 7.7.4). High cycle fatigue is considered to be negligible since there is no known excitation source to initiate vibration.

#### 4.3.3 Analytical Techniques

To predict low cycle fatigue life, elastic and plastic strains induced by the thermal gradients in the tubes must be determined. A Finite Element Axisymmetric and Planar Structural Analysis Computer Program (APSA) has been used for stress and strain analysis. It is a two-dimensional program, used to determine the displacements, stresses, and strains in axisymmetric and planar solids. The program allows for orthotropic, temperature-dependent material properties under thermal and mechanical loads. The mechanical loads can be surface pressures, surface shears, and nodel point forces. The continuous solid is replaced by a system of ring or planar elements with quadrilateral cross section. Accordingly, the method is valid for solids that are composed of many different materials, and which have complex geometry. The APSA program analyzes elastic or elastic-plastic problems with a single set of loads.

A typical APSA model for analyzing stress and strain of a tube for an existing absorber design is shown in Figure 4-26. The figure shows the division of the tube cross section into nodal elements. Figure 4-27 shows the temperature distribution obtained from heat transfer analysis and used as input for computing stress and strain. Figures 4-28 and 4-29 give the maps of the effective stress and strain values obtained from the computer output. These are used in subsequent fatigue analyses.

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Figure 4-26. Division of the Tube Cross Section Into Nodal Elements



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Figure 4-28. Map of the Effective Stress

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45.20 R 45.10 . A X I S 45.00 44.90 44.80 44.70 A = 3.09 µM (122, µIn.) 44.60 B = 12.9 VM (508, WIn.) C = 23.8 \M (938, \In.) 44.50 D = 34.5 MM (1360. MIn.) 44.40 E = 44.5 MM (1750. MIn.) 44.30 44.20 44.10 44.00 43.90 43.80 43.70 43,60 Ч, 43.50 . 6 .4 .2 . د я -.6 2 . RXIS C 9.38×10<sup>-04</sup> 9 1.36×10<sup>-03</sup> E 1.75×10<sup>-03</sup> 8 1.22810 я 5.08810 nim 7.94×10 NAN 1.79×10



Figure 4-29. Map of the Effective Strain

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Low cycle fatigue life studies were made on typical tube sizes. Both Incoloy 800 and 316L stainless steel tubes showed cycle life greater than 30 years (11,000 temperature cycles).

#### 4.4 RECEIVER EFFICIENCY

The receiver efficiency is defined as the ratio: (Power Absorbed by the Receiver)/(Power Incident on the Receiver Aperture) Fluid. The power absorbed is a fixed design requirement. The losses (reflection and radiation from the asborbed surface, convective heat loss from the absorber surface to the atmosphere, and thermal conduction via the absorber insulation blanket and supports) are determined by the receiver geometry, the operating temperatures and thermal properties of the materials.

Receiver losses and efficiencies for four partial-cavity receivers and one external receiver are shown in Table 4-7. The data show that the partial cavity receiver achieves 91% efficiency over the entire range of fluid outlet temperatures, i.e., from 454°C for the 3.5-year program to 566°C for the commercial unit. Data for an "external" (flat disk) receiver having the same heat transfer area and fluid temperature profile as the 7.08 MWt partial cavity (last column of the table) is included in the table to show that advantage of the partial cavity configuration.

Table	4-7.	Receiver	Efficiency
-------	------	----------	------------

			Fytarnal		
	<u>3.5 Yr</u>	<u>4.5 Yr</u>	<u>6.5 Yr</u>	Comm	<u>(Disk)</u>
Aperture Diameter, m	4.5	4.28	4.00	3.5	6.07
Absorbed Power, MWt	7.08	6.05	4.87	4.72	7.08
Reflection Loss, MWt*	0.195	0.167	0.134	0.125	0.337
Radiation Loss, MWt*	0.205	0.211	0.198	0.167	0.434
Convection Loss, MWt**	0.189	0.182	0.164	0.132	0.344
Conduction Loss, MWt	0.012	0.009	0.008	0.006	0.012
Efficiency, %	92.2	91.4	90.6	91.6	85.0

 $*_{\alpha} = \varepsilon = 0.95$  $**h = 28.4 \text{ W/m}^2 \text{ °C}$ 



#### Section 5

#### TOWER SUBSYSTEM ANALYSES

The tower subsystem analyses consisted of: (1) a trade study to determine the most cost effective type of tower in the height and receiver weight range of interest, and (2) a preliminary design of the tower for Engineering Experiment No. 1.

The trade study was conducted comparing three different types of towers: (1) free-standing steel, (2) guyed steel, and (3) reinforced concrete. Reinforced concrete towers were given a precursor evaluation and eliminated from further consideration because of:

- A. Traditionally higher costs associated with concrete structures of this size in comparison to steel structures due to extensive onsite construction activities and substantial foundation requirements. (Steel towers can be partially prefabricated and site assembled in sections.)
- B. Structural stiffness which produces high receiver accelerations during seismic events which requires additional receiver structure. (Flexible steel towers absorb some of the ground motion, delivering less severe acceleration loads to the receiver.)
- C. Greater difficulty in attaching pipe supports, work platforms, and providing extensive access for maintenance.

#### 5.1 TOWER REQUIREMENTS

The requirements, upon which the preliminary design and costing activities were based, can be divided into design and environmental factors. From a design standpoint, it was desirable to develop data over a sufficient range of tower height and receiver weight to permit these results to be applicable to any of the candidate systems. As a result, three discrete combinations of tower height and receiver weight were specified for each tower type.



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	Tower Height m (ft)	Receiver Weight kg (lb)				
Case 1	48 (158)	7,273 (16,000)				
Case 2	48 (158)	34,090 (75,000)				
Case 3	42 (138)	7,273 (16,000)				

In addition, the heavier receiver, with a face dimension of 12.2 by 12.2 m (40 by 40 ft), was assumed to have its center of gravity located 4.6 m (15 ft) above the top of the tower and located along the vertical centerline of the tower. The receiver attachment points were assumed to be the corners of a square pattern 4.9 m (16 ft) on a side. The lighter receiver, with a face dimension of 5.2 by 5.2 m (17 by 17 ft), was assumed to have its center of gravity located 2.3 m (8.5 ft) above the top of the tower and displaced by i.6 m (5.3 ft) from the tower centerline. The receiver attachment points were assumed to be the corners of a square pattern 2.45 m (8 ft) on a side.

From an environmental standpoint, the following requirements were to be met:

Operating wind speed at 10 m elevation	16.1 m/sec	(36 mph)
Operating deflection	0.15 m	(6 in)
Survival wind speed	40.2 m/sec	(90 mph)
Seismic load	0.25 g	(horizontal ground acceleration)
Soil bearing strength	7,322 kg/m <sup>2</sup>	(1500 lb/ft <sup>2</sup> )

5.2 GUYED STEEL TOWER CONCEPTS

The guyed steel tower (Figure 5-1), in the configuration, required to support the heavier receiver load, is of a constant cross section with four guy cables strung at a 45° angle. In carrying out the analysis, it was found that the overturning moment associated with the survival wind load was a factor of 2 larger than the seismic-induced moment. As a result, the towers were designed on the basis of wind load requirements.

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Figure 5-1. Guyed Tower Design (34,090 kg Receiver)

The principal design characteristics for each of the guyed towers are summarized in Table 5-1. The structural steel which forms the vertical structure and drag bracing is made up of commercial steel angles with the angle depth and thickness being selected to accommodate local load conditions. Cabling is assumed to be of commercial galvanized bridge cable type with the diameter being determined on the basis of loads associated with the maximum overturning moment condition.

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Tower height Receiver weight		Structural steel		Cable diameter		Cable length		Concrete			
ш	(ft)	kg	(1b)	kg	(16)	cm	(in)	m	(ft)	"3	(yd <sup>3</sup> )
48	(158)	7,273	(16,000)	17,341	(38,150)	2.06	(13/16)	305	(1,000)	23	(30)
48	(158)	34,090	(75,000)	24,091	(53,000)	4.45	(1-3/4)	305	(1,000)	64	(84)
42	(138)	7,273	(16,000)	14,841	(32,650)	1.91	(3/4)	262	(860)	23	(30)

TABLE 5-1. Characteristics of Guyed Steel Towers

The tower foundation consists of a mat design of sufficient area to distribute the compressive load at a rate less than the soil bearing strength limit of 7,322 kg/m<sup>2</sup> (1,500 lb/ft<sup>2</sup>). The mat is assumed to be 0.61 m (2 ft) thick which is a sufficient depth, based on Barstow soils data, to encounter reasonably stable soil. The deadmen consist of buried concrete piers which are sized to accommodate the maximum cable loads.

#### 5.3 FREE-STANDING TOWER CONCEPT

The free-standing steel tower of the type shown in Figure 5-2 is a tapered design with the base dimension approximately one-fifth the tower height. As in the case of the guyed tower, the structural and foundation designs are based on the overturning moments created by the maximum wind loads.

The principal design characteristics for the free-standing towers are shown in Table 5-2. The structural steel contained in the vertical members and drag braces is assumed to be commercial angle steel. The foundations for each of the four legs are designed to withstand the overturning moments while

Τe	ower			Structural			Dimensions (square)				
h	eight	Receiver Weight		steel		Concrete	Тор		Base		
m	(ft)	kg	(16)	kg	(16)	m <sup>3</sup> (yd <sup>3</sup> )	т	(ft)	m	(ft)	
48	(158)	7,273	(16,000)	28,545	(62,800)	142 (186)	2.4	(8)	7.3	(24)	
48	(158)	34,090	(75,000)	45,113	(99,250)	153 (200)	4.9	(16)	9.7	(31.8)	
42	(138)	7,273	(16,000)	24,364	(53,600)	126 (165)	2.4	(8)	7.3	(24)	

Table 5-2. Characteristics of Free-Standing Towers




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providing a sufficient base for the distribution of the compressive loads consistent with soil loading limitations.

## 5.4 TOWER CONCEPT EVALUATION

Figure 5-3 presents tower cost data as a function of tower height and receiver weight. The results indicate the consistent superiority of the guyed tower over the height and weight ranges of interest in this study. From a comparison of cost breakdowns for the two towers, it is seen that each of the cost increments for the free-standing tower exceeds the corresponding value shown for the guyed tower (except the electrical value) with the biggest discrepancy occurring for the concrete required for foundations and supports. The indirect entries include construction equipment and supplies, temporary facilities, labor benefits, and other field expenses. The miscellaneous category includes engineering, contingency, and fees.

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Figure 5-3. Cost Comparison Between Free Standing and Guyed Steel Towers



Based on these cost data, the guyed tower is a superior choice for the present application and will be retained as the baseline tower configuration. In addition, the high cost increment associated with concrete for the freestanding steel tower also supports the earlier decision to eliminate the freestanding concrete tower from further consideration.

## 5.5 GUYED TOWER DESIGN

A summary of the analysis and design work accomplished by Stearns-Roger is provided in the following pages. Table 5-3 presents the load requirements as applied to the structure. Figure 5-4 shows the design of the guy wires and Figure 5-5 the design of the foundation. Table 5-4 illustrates the method used to calculate the maximum allowable member loads. These values are then compared to the maximum design loads in Table 5-5. The resultant tower is a rather stiff structure with a deflection of only 1.7 cm at maximum load.

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Table 5-3. Tower Loads

Wind Loads

Wind loads were determined per the provisions of ANSI AS8.1 - 1972. Maximum wind velocity = 40 m/sec (at 9 m) [90 mph (at 30 ft)] Exposure type C (flat open country) Gust factor = 1.15 (from Appendix A6.3.4.1) Net pressure coefficients: Steel tower: Values of C<sub>f</sub> from Section 6.9 Receiver: Normal wind, C<sub>f</sub> = 1.3 Diagonal wind, C<sub>f</sub> = 1.0 Projected area of receiver: Normal wind, A = 28 m<sup>2</sup> (300 ft<sup>2</sup>) Diagonal wind, A = 39 m<sup>2</sup> (420 ft<sup>2</sup>)

An additional area of 0.3  $m^2/m$  (3 ft<sup>2</sup>/ft) of height was added to account for wind on the ladder, elevator, piping, etc.

Seismic

6.25 g maximum ground acceleration in both the horizontal (one component) and vertical directions.

Ground response spectra obtained from NRC Reg. Guide 1.60. Damping ratio assumed to be 7%.

SRSS method used for summing components and modes.

Load Factors for Member Design

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1) 0.75 (D + G + W)
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2) 0.75 (D + G + E)

D = Dead loads (tower and receiver)

G = Guy preloads

W = Wind load

E = Seismic load

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Figure 5-5. Mat Design

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Allowable Member Forces Fy = 248 mPa (36 KSI)Verticals L 15.2 x 15.2 x 1.9 cm (L6 x 6 x 3/4)  $\mathfrak{L} = 3.007 \, \mathrm{m} \, (118.385 \, \mathrm{in})$ F<sub>a</sub> = 88.5 mPa (12.83 KSI)  $P_a = 12.83 \times 8.44 = 108.29^k$ Diagonal Braces L 7.6 x 7.6 x 0.63 cm (L3 x 3 x 1/4)  $\mathfrak{L} = 4.282 \, \mathrm{m} \, (168.568 \, \mathrm{in})$  $\frac{0.75\iota}{r} = \frac{0.75 \times 168.568}{0.930} = 135.94$  $\frac{0.5 \ell}{r_{a}} = \frac{0.5 \times 168.568}{0.592} = 142.37 \quad F_{a} = 50.8 \text{ mPa} (7.37 \text{ KSI})$  $P_a = 7.37 \times 1.44 = 10.61^k$ Horizontals L 7.6 x 7.6 x .48 cm (L3 x 3 x 3/16)  $\ell = 3.048 \text{ m} (120 \text{ in})$  $\frac{2}{r_{\star}} = \frac{120}{0.596} = 201.34$ F<sub>a</sub> = 25.4 mPa (3.68 KSI)  $P_a = 3.68 \times 1.09 = 4.01^k$ 

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Tai	ble	5-5.	Computed	Member	Forces
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	Ma	ximum Memt Load Case	per Force No.*		Allowable		
Member Type	1	2	3	4	Force Nx10 <sup>3</sup> (LBx10 <sup>3</sup> )		
Vertical, Compr.	92.38 (20.77)	497.0 (111.73)	303.7 (68.28)	161.2 (36.25)	481.7 (108.29)		
Diagonal, Compr.	6.89 (1.55)	48.48 (10.90)	40.61 (9.13)	13.57 (3.05)	47.19 (10.61)		
Horizontal, Compr.	-	10.45 (2.35)	12.19 (2.74)	-	17.84 (4.01)		
Horizontal, Tens.	21.13 (4.75)	25.53 (5.74)	26.64 (5.99)	22.11 (4.97)	104.7 (23.54)		
Deflection of receiver under operating wind (load case 4 ) = 1.74 cm (0.686 in.)							
*Load case 1 = Tower	and recei	ver dead '	loads + g	uy forces			
Load case 2 = 0.75 ;	k (Load ca	se 1 + de:	sign wind	along dia	agonal)		
Load case 3 = 0.75 x (Load case 1 + design wind along flats)							
Load case 4 = Load case 1 + operating wind along diagonal							
Seismic load did not govern the design of any member.							



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#### Section 6

### ENERGY STORAGE ANALYSES AND TRADE STUDIES

Trade studies for the energy storage subsystem are described in this section.

6.1 STORAGE TANK DESIGN

The storage tank volumes were determined based on the following considerations:

- A. Minimum extractable energy requirements
- B. Buffer requirement
- C. Heat losses to the environment
- D. Unavailable energy
- E. Space requirements for internal components such as pumps, manifolds, or baffles
- F. Ullage space

The tank configurations will depend on:

- A. Storage technique (two tank or dual media)
- B. Pump configurations
- C. Transportation constraints
- D. Tensile and thermal stresses

#### 6.1.1 Minimum Volume Required

The determination of the energy storage requirement including extractable energy, system losses, and buffer allowance was described in Volume III, Section A.3.5. The minimum volume required to store this energy can be calculated by

$$V_m = Q_m / C_n \Delta T_\rho$$
)

 $Q_m$  = Total energy requirement including buffer and heat losses

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- $C_n$  = Heat capacity of the storage media
- $\Delta T$  = Temperature difference
  - p = Density of the storage media

Values used for the calculation of minimum volume requirements are shown in Table 6-1.

## 6.1.2 Heat Losses

The heat which is lost to the environment from the lines and the storage tanks represents energy which is collected but is unavailable for power generation. To compensate for this, the storage capacity must include energy which is equivalent to the heat lost in a 24-hour period. The duty cycle assumed for these calculations is as follows:

A. The hot tank is full for 12 hours and empty for 12 hours

B. The cold tank is full for 24 hours

Program/Tank	Q <sub>m</sub> (MWHt)	(°C)	ρ (kg/m <sup>3</sup> )	Cp (cal/g °C)	Minimum Volume (m <sup>3</sup> )
3.5 Year	17.1	194		0.373	
Hot Tank			1,746		116
Cold Tank			1,889		107
4.5 Year	14.9	222		0.373	
Hot Tank			1,706		91
Cold Tank			1,870		83
6.5 Year	12.5	250	HTS 1,818	0.373	50
			Iron 5,247 ore	0.2	

Table 6-1. Storage Tank Minimum Volumes



The steady state heat loss is given by

$$\dot{q}_{s} = (T_{w} - T_{a}) / \frac{x}{k_{i}A_{ave}} + \frac{1}{h_{o}A_{o}}$$
  
 $\dot{q}_{s} = \text{Steady state heat loss}$   
 $T_{w} = \text{Tank or pipe wall temperature}$   
 $T_{a} = \text{Ambient temperature}$   
 $X = \text{Insulation thickness}$   
 $k_{i} = \text{Thermal conductivity of the insulation}$   
 $A_{ave} = \text{Log mean area}$   
 $A_{o} = \text{Outside area of the insulation}$   
 $h_{o} = \text{Outside heat transfer coefficient}$ 

The transient heat loss which occurs when the tank is empty is given by

q<sub>t</sub> = (mc) T<sub>Wi</sub> T<sub>Wf</sub>
q<sub>t</sub> = Transient heat loss
mc = Tank capacitance
T<sub>Wi</sub> = Initial wall temperature
T<sub>We</sub> = Final wall temperature

The ambient temperature was assumed to be 15.5°C and the outside heat transfer coefficient was taken to be 22.7  $W/m^2$  - °C. Based on tank dimensions given in Volume III, Section 4.5.1, heat losses have been calculated for the various program durations and are shown on Table 6-2 along with critical parameters. The thermal conductivity of tank insulation is shown in Figure 6-1 as a function of temperature. The capacitance of the insulation was conservatively ignored in these calculations. Cooldown transients for the hot tank in an empty condition are shown in Figure 6-2.

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			Х (ст)	T <sub>w</sub> (°C)	q <sub>s</sub> (MWH)		9 <sub>t</sub> (MWH)	Total Heat Loss (MWH)	% of Extractable
3.5	Year								
	Hot 1	l'ank	27.9	454	0	.208	0.176		
	Cold	Tank	20.3	260	0	.220	-	0.604	3.7
4.5	Year								
	Hot T	ľank	30.5	510	0	.175	0.159		
	Co1d	Tank	22.9	288	0	.176	-	0.501	3.5
6.5	Year		30.5	538/	Тор О	.030	-		
				288	Side O	.144		0.272	2.3
					Bottom O	.098			
	• •	·					_		9CR20
	0.14								
	0,12		_ <u></u>						$ \rightarrow $
	1				(F	IBERGL	ASS)		
, 2	0.10					$\rightarrow$	+		
o - m/i							$\checkmark$		
2	0.09			PIPE INSU		$\nearrow$			
IIVIT	0.07					$\geq$	1		
anuc	0.07					) HO (Mi	T TANK INS	ULATION ER)	
100	0.05		$ \rightarrow $	/					
	0,03								
	0,01	50	15	0	250		350	450	550
					TEMPERA	TURE, (	°C)		

Table 6-2. Storage Tank Heat Losses



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 $\phi_{0},\phi_{1},\phi_{2},\phi_{1},\phi_{2},\phi_{2},\phi_{3$ 



#### Figure 6-2. Hot Tank Cooldown Transients

#### 6.1.3 Unavailable Energy

In the two-tank concept, all the sensible heat stored (excluding daily losses and the tank sump) is available for extraction. In the dual media thermocline technique, a portion of the stored energy cannot be extracted due to the thermocline thickness. This is typically on the order of 10%. The mass of storage media and tank volume was increased by 10% to account for this in the 6.5-year program. (See Section 6.4.)

#### 6.1.4 Additional Space Requirements

In the two tank configuration, an excess of 2% was allowed for space occupied by the pump shaft, immersion heater, and ullage. A total of 9% excess is allowed for two manifolds and ullage space in the dual media thermocline tank.

## 6.1.5 Tank Configuration

Because submerged bearing pumps were selected over vertical cantilever designs, there was no constraint on tank diameters. In order to be transportable, the

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diameters were limited to 3.6 m. Horizontal tanks were chosen for the two tank configuration so that they could be easily installed below ground level to facilitate draining salt from the system back to the tanks. A vertical tank is, of course, required in the 6.5-year program for thermocline operation. In this case, a length/diameter ratio greater than 1.5 was assumed adequate.

## 6.1.6 Tank Gage

Using standard equations established by the ASME boiler code, the thermal storage tank gages were determined based on the following assumptions:

	Cold Tank	Hot Tank
Differential Pressure	3 Bars	3 Bars
Diameter ·	3.6 m	3.6 m
Allowable Stress	880 kgF/cm <sup>2</sup>	1056 kgF/cm <sup>2</sup>
Corrosion Allowance	2.5 mm	0.9 mm

The calculated wall thickness was increased to the next closest 1.58 mm (1/16 in) as a safety measure and the gage was specified as 11.1 mm (7/16 in) for the carbon steel cold tanks and 8.1 mm (5/16 in) for the stainless 316 hot tank.

## 6.2 INSULATION THICKNESS

As the insulation thickness increases, the cost of the insulation increases accordingly. Since heat losses are reduced, the storage requirements and related costs are decreased. The required heat input to the system is also less and this is related directly to the required number and cost of heliostats. An optimum thickness will therefore exist. As illustrated in Figure 6-3 for the hot tank (4.5-year program), the optimum insulation thickness can be chosen for the cold tank and the hot tank at the minimum total system cost. Data assumed in the optimization analysis are given in Table 6-3. Because the effective thermal conductivity of installed insulation is always greater than





Figure 6-3. Hot Tank Insulation Optimization

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Table 6-3. Tank Insulation Opti	imization
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	3.5 Year		4.5	íear	6.5 Year
	Hot Tank	Cold Tank	Hot Tank	Cold Tank	
Insulation Cost (Installed), \$/m <sup>3</sup>	777	600	777	600	847
Cost of Salt, \$/kWh capacity	9	9	8	8	3
Cost of Collector \$/kWh/day	69	69	71	71	73
Design Thickness					
in	11	8	12	9	12
cm	27.9	20.3	30.5	22.9	30.5

that specified by a manufacturer, the design thickness was increased to the next standard interval (inch). It should be noted that the installed cost of insulation is a function of the material and thickness as well as the tank configuration (horizontal, vertical). The collector cost is based on the figure of merit.

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## 6.3 IMMERSION HEATER DESIGN

Immersion heaters must be selected which are capable of:

- Α. Melting the entire salt inventory in a reasonable period of time (less than 2 weeks)
- Β. Maintaining the salt above the melting point or minimum operating temperature if required.

The total heat required to bring solid heat transfer salt to operating conditions is given by

$$Q = M_{s}C_{p_{s}}(T_{m} - T_{a}) + M_{s}\Delta H_{f} + M_{s}C_{p_{g}}(T_{o} - T_{m}) + M_{t}C_{t}(T_{o} - T_{a}) + Q_{L}$$

where

$$M_s = Mass of salt$$
  
 $M_t = Mass of tank$   
 $C_{p_s} = Heat capacity of solid salt$   
 $C_{p_l} = Heat capacity of liquid salt$   
 $C_t = Heat capacity of steel tank$   
 $T_m = Salt melting temperature$   
 $T_a = Ambient temperature$   
 $T_o = Minimum salt operating temperature$   
 $AH_f = Salt heat of fusion$   
 $Q_l = Heat loss to the environment$ 

With a selected 100 kW heater, the total time required to raise the temperature of salt to the minimum operating temperature is given below. This size heater is more than sufficient to maintain salt at the operating temperature. The maximum loss is from the hot tank in the 3.5-year program and amounts to 17.4 kW.

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	3.5 Year	<u>4.5 Year</u>
T <sub>o</sub> (°C)	260	288
Q(MWh)		
Salt Heatup Salt Melting Tank Heatup Losses	19.9 4.6 0.4 0.8	17.0 3.5 0.3 0.7
t(hr)	256	216

#### 6.4 THERMOCLINE DEGRADATION

This section provides the rationale for sizing the dual-media thermal storage unit above the value required if an ideal thermocline could be assumed. The means whereby increased storage capacity can be obtained by careful operating techniques and the increased turndown ratio required to achieve this goal are also discussed.

If the thermocline is caused to move up and down in the middle of the thermal storage unit several times, it has a tendency to be smeared or degraded. Thus the change from the high temperature in the top of the tank to the lower temperature in the bottom of the tank, as one proceeds across the thermocline, is no longer as abrupt. When this region reaches the top of the tank, typically near the end of the discharge period, the exiting fluid temperature going to the steam generator will necessarily decrease below the design value. The amount of temperature drop that the steam generator can tolerate is usually limited to an 8°C to 16°C range. The heat remaining in the thermal storage unit is thus not available for use to generate power. Similarly, after the thermal storage unit has been almost fully charged, the thermocline reaches the bottom of the tank, and the temperature of the exiting fluid begins to rise above the level of the design value. For this case, the control system must necessarily increase the flowrate to assure that the exiting temperature from the receiver does not climb above the design value. This process can continue until the control valve is fully opened and the flow is at its maximum. At this point some heliostats must be repositioned to decrease the energy to the receiver.

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It can be seen that the material in the thermocline band contains heat that is not available to the system. The thermal storage unit must thus be constructed somewhat larger, usually by from 10 to 15%. This factor can be reduced somewhat by ensuring that the thermocline is run off the bottom of the tank and off the top of the tank (if possible) whenever the opportunity presents itself. Each time this occurs, it tends to upgrade the thermocline, resulting in a slightly increased thermal capacity for the thermal storage tank. Should a condition arise where no sunlight reaches the system for a number of days or possibly weeks, the thermocline will tend to degrade and create a condition as previously described. This thermocline degradation can, however, be eliminated by carefully bringing the system on stream when heat is again first being received from the receiver. This can be accomplished with the aid of instrumentation which measures the available energy in the thermal storage unit and the degree of degradation of the thermocline. This instrumentation consists of a series of thermocouples placed in the bed in a vertical row spaced approximately 15 to 30 cm apart. The thermocline profile can be displayed on a cathode ray tube in the control room to show the degradation of the thermocline to the operator. In addition, if desired, the computer can determine the amount of available energy in the thermal storage unit.

A convenient time to reestablish a steep thermocline is in the early morning when only a small amount of energy is absorbed by the receiver. The temperature of the fluid entering the receiver can then be allowed to rise above the normal operating range and still not require excessive flowrates to maintain the proper outlet temperature from the receiver. The thermal storage unit is thus charged slowly to reestablish an efficient thermocline field. Since the opposite action of discharging at a slow rate to the steam generator is probably not possible (since the turndown ratio of the steam generator will be limited), it is best to run the thermocline out of the bottom of the tank, utilizing small amounts of energy coming to the receiver, rather than trying to improve the thermocline by running it out of the top of the tank upon discharge. The above condition is rare since the degradation of the thermocline to the point where such measures must be taken, will require many many days and possibly many weeks. Therefore, the condition referred to above and the action taken will seldom occur.



# Section 7 ENERGY TRANSPORT SUBSYSTEM ANALYSES

Analyses and trade studies for the energy transport subsystem are described in this section.

#### 7.1 FEEDPUMP SELECTION AND DESIGN

Because molten salt is utilized as the heat transport medium, certain precautions must be taken in pump selection. The following types were considered for use:

- A. Vertical centilever With a pump of this type, all bearings are above the mounting plate. Long shafts on the order of 2 m (6 ft) are extremely expensive or totally impractical. Extension pipes can be attached to the pump inlet at a nominal depth of 1 m (3 ft). However, an auxiliary pressurization system or suction device is required to ensure that liquid is above the impeller during pump startup.
- B. Sleeve bearing design Normally used for low-head, low-speed applications, this design would allow the pump shaft to be as long as necessary so that tank diameters would only be limited by transportation constraints. Because of problems encountered with auxiliary systems used for pump startup with cantilever designs, the submerged bearing type was recommended by pump manufacturers. They are also less expensive and were found to be used quite extensively in industrial molten salt applications with minimum maintenance.

## 7.1.1 Receiver Feedpump Requirements

The total head requirements were based on the system configurations shown in Figure 7-1. The requirement includes the frictional pressure drop from the

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9CR20 VALVES TOWER/ RECEIVER (44-m ELEVATION) -> HAND FIELD ξю COLD TANK L. (BEI.OW GROUND LEVEL) STEAM GENERATOR ¢÷ HOT YC TANK 3,5/4,5 YEAR SYSTEM TOWER/ RECEIVER 65 RECEIVER Ξ <u>,</u> α BOTTOM MANIFOLD STEAM GENERATOR TOP MANIFOLD 34 STORAGE TANK STEAM GENERATOR FEED PUMP 6.5-YEAR SYSTEM Figure 7-1, System Layout



pump inlet to the receiver outlet, in addition to the static head. Frictional losses include contributions from elbows, tees, valves, and entrance/exit effects, in addition to line losses. Data used in standard pressure drop calculations are shown in Table 7-1.

## 7.1.2 Steam Generator

The total head was determined from frictional losses through the lines and the steam generator and the static head requirements. Losses in valves, tees, and elbows were accounted for although losses in the steam generator were conservatively estimated. Results are shown in Table 7-1.

#### 7.2 HEAD DISSIPATION

A method of dissipating the hydrostatic head in the receiver downcomer was required. Pressurized tanks and baffles were considered too expensive. Since control valves are normally sized to absorb one-third of the total system pressure drop, it was determined that the control valve in the receiver loop could be used for both control and head dissipation. Since constant-speed pumps are utilized, the valve must be designed to produce a greater pressure drop as the flowrate decreases. The valve inlet pressure at maximum flow is

Pvalve = (Downcomer static head)
inlet - (Frictional loss, receiver to valve)

At minimum flow, since the frictional loss is negligible,

Pvalve = (Downcomer static head)
inlet + (Increase in pump discharge)
+ (Frictional loss, pump to valve)

The design outlet pressure from the value is specified as  $0.97 \pm 0.2$  bar gage plus the frictional loss from the value to the tank. The pressure drop required through the value can be determined as a function of flow rate, as illustrated in Figure 7-2 for the receiver control value in the 3.5-year

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	Receiver Feed Pump				
	3.5 Year	4.5 Year	6.5 Year		
Line Diameter, cm	7.79	7.79	6.27		
Velocity, m/s	2.6	2.0	2.2		
Equivalent Length, m	81.7	81.7	94.8		
Pressure Drop, bars					
Line	1.5	0.8	1.4		
Receiver	5.7	3.1	3.0		
Elevation	8.8	8.8	8.1		
Total	16.0	12.7	12.5		

# Table 7-1. Pump Developed Head

## Steam Generator Feed Pump

	3.5 Year	4.5 Year	6.5 Year	
Line Diameter, cm	6.27	6.27	5.25	
Velocity (max), m/s	2.6	2.0	2.0	
Equivalent Length, m	82.3	81.7	76.2	
Pressure Drop, bars				
Line	1.7	0.9	1.1	
Steam Generator	1.4	0.8	0.4	
Static	1.3	1.3	0.6	
Total	4.4	3.0	2.1	

system. Results for the 4.5- and 6.5-year programs are presented in Volume III, Section 4.6.1.3. In order to prevent cavitation, the critical flow factor of the valve will have to be on the order of 0.97.





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Figure 7-2. Pressure Proof Characteristics of the Receiver Control Valve (3.5-Year System)

## 7.3 HEAT LOSSES

Heat losses from pipelines to the environment will be reflected in increased storage and heliostat requirements. Equations given in Section 6.1.2 were used assuming 10.2 cm of calcium silicate insulation. An ambient temperature of 15.5°C and an outside heat transfer coefficient of 11.4  $W/m^2$  - °C were assumed. Line lengths were estimated from the configurations shown in Figure 7-1.

### 7.3.1 Steady State Losses

Following normal daily operation, salt will drain from the lines. Steady state losses were therefore assumed to occur for 10 hours in the receiver loop and 14 hours in the steam generator circuit. Results are shown in Table 7-2.

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	Receiver Riser	Receiver Downcomer	Steam Generator Feed	Steam Generator Return
Design Length, m	50.6	55.5	12.8	18.9
3.5-Year Program				
∆T, °C	244	439	439	244
k, W/m - °C	0.062	0.073	0.073	0.062
q, kW	3.9	9.0	1.9	1.3
Total Loss:	174 kWh/	day		
4.5-Year Program				
∆T, °C	272	494	494	272
k, W∕m – °C	0.064	0.076	0.076	0.064
q, kW	4.5	10.6	2.2	1.5
Total Loss:	203 kWh/	day	- - P 	
6.5-Year Program				
∆T, °C	272	522	522	272
k, W∕m − °C	0.064	0.078	0.078	0.064
q, kW	4.3	9.7	3.0	1.5
Total Loss:	203 kWh/	day		

Table 7-2. Piping Steady State Thermal Losses (Daily Operation)

## 7.3.2 Transient Losses

Following shutdown, the lines can only cool down to specified control temperatures, at which time trace heating will be initiated.

Based on daily duty cycles of 10 and 14 operating hours for the receiver loop and steam generator loop, respectively, the receiver riser and downcomer will have 14 hours to cool down at night before operation begins the following morning. The steam generator feed and return lines will cool for 10 hours. The hot lines do not reach the heater control temperature within these periods, as shown in Figure 7-3, for the 3.5-year system. The capacitance of the insulation was included in the analysis. Calcium silicate has a



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Figure 7-3. Pipeline Cooldown Transiants (3.5-Year System)

specific heat of 0.20 to 0.22 cal/g-°C and a density of 208 kg/m<sup>3</sup>. Transient losses are summarized in Table 7-3. In the 6.5-year system, there are no losses shown for the low temperature lines since the control temperature is the same as the operating temperature (288°C) and trace heaters on these lines will be initiated immediately following shutdown.

#### 7.3.3 Total Daily Line Thermal Losses

The total thermal losses experienced by the energy transport system are shown below:

	3.5 Year	4.5 Year	6.5 Year
Steady State Loss, kWh/day	174	203	203
Transient Loss, kWh/day	76	92	45
Total Thermal Loss, kWh/day	240	295	248



	Receiver Riser	Receiver Downcomer	Steam Generator Feed	Steam Generator Return
3.5-Year Program				
Pipe loss, kWh	6.5	24.3	4.4	1.9
Insulation Loss, kWh	6.8	24.1	5.2	2.3
Maximum total los	s: 75.5 kW	h/day		
4.5-Year Program				
Pipe loss, kWh	8.5	27.7	5.0	2.4
Insulation loss, kWh	9.0	27.6	8.5	3.1
Maximum total los	s: 91.6 kW	h/day		
6.5-Year Program				
Pipe loss, kWh	0	15.8	3.4	0
Insulation loss, kWh	0	19.5	6.1	0
Maximum total los	s: 44.8 kW	h/day		

Table 7-3. Line Cooldown Loses (Transient)

## 7.4 TRACE HEATING

Trace heating can be accomplished electrically or with steam. A comparative study was carried out which considered the cost impact on the collector subsystem of providing the necessary trace heating energy which could be compared to the cost of the trace heating equipment. For the steam heating case, additional heliostats were included to furnish a surplus energy to thermal storage which could be utilized as the necessary source of energy. For the electrical trace heating approach, it was assumed that the collector subsystem was sized to provide sufficient energy so that the surplus electrical output would cover the resistance heating demand (even though the demand would normally occur after the plant had been shut down for the day). This latter

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approach includes the effects of cycle conversion efficiency. It was also assumed that the trace heating would be initiated when the component temperature decayed to the specified temperatures (171°C for Hitec and 288°C for the binary HTS). Based on an annual heater requirement of 7,010 kWh, a summary of the impact of trace heating on collector subsystem costs is shown in Table 7-4 for the two approaches. It is seen that in both cases, less than a single equivalent heliostat would have to be added to offset the trace heating requirements. The indicated cost data favors the steam approach by \$1,100. However, this value must offset the additional expense associated with installing the trace heating lines to all components as well as the water/steam circulation equipment.

Preliminary estimates indicate that a much more substantial cost difference would be required to offset the additional steam equipment cost. An exact number has not been determined as all steam trace heating components would have to be specified in detail. As a result, electrical trace heating was selected for the baseline system configuration.

	Trace heating method	
	Steam	Electrical
Required trace heating power (kW)	2.9	2.9
Annual trace heating energy (kWH)	7,010	7,010
Additional collector capability (kWh)	7,010	26,960*
Fraction of total annual collection	0.0005	0.0018
Equivalent additional heliostats	0.10	0.37
Equivalent additional heliostat cost**	\$400	\$1,500

Table 7-4. Impact of Trace Heating on Collector Subsystem Costs for the 3.5-Year Program

\*26% assumed conversion cycle efficiency
\*\*Assumes \$4,000 per heliostat

NOTE:	Comparison	excludes	costs	of	installing	trace	heaters	or	water/steam
	piping and	circulati	on equ	lipm	ent.				



## 7.4.1 Trace Heater Configuration

Trace heating requirements were determined from the system configurations shown in Figure 7-1. Allowances were made for valves and equivalent lengths for the various circuits and are given in Table 7-5.

Trace heating losses were calculated, based on operational times required at night after the lines had cooled to 171°C (or 288°C in the 6.5-year system). Data used in calculating trace heater requirements are given in Table 7-6. Lines not indicated do not cool down to control temperatures before morning operations begin.

		Equivalent le	ength, m
Line*	Description	3.5/4.5 Year	6.5 Year
1	Receiver downcomer	57.0	53.9
2	Receiver riser	51.5	55.2
3	Steam generator return	18.9	21.0
4	Steam generator feed	14.3	19.5
5	Steam generator startup	12.5	14.0
6	Receiver startup	4.9	5.5
7	Transfer line	5.2	8.5
8	Transfer line	4.0	-

Table 7-5. Trace Heating Circuits

\*Numbers refer to lines shown in Volume III, Figure 4.6-3.

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.5-Year Program (171°C)						
Line	2	!	3		6 a:	nd 8
Diameter	8	3.9	7.3		8.9	
Loss, kW	2	4	0.8	}	0.4	
Operating time, hr	7	.5	3.8	;	3.5	
Total loss, kWh	18	3.2	3.0		1.4	
Tot	al system:	loss =	22.6 kW	h/day		
.5-Year Program (171°C)						
Line	2	-	3		6 а	nd 8
Diameter, cm	8	3.9	7.3		8.9	
Loss, kW	2	2.4	0.8	ł	0.4	
Operating time, hr	é	5.0	2.3		2.3	
Total loss, kWh	14	1.5	1.8		0.9	
Tat	al system:	loss =	17.3 kW	h/day		
.5-Year Program (288°C)						
Line	2	1	3	4	5	6 and 7
Diameter, cm	7.3	7.3	6.0	6.0	6.0	7.3
Loss, kW	4.4	4.3	1.5	1.4	1.0	1.1
Operating time, hr	14	4.7	10	1.3	5.4	9.2

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# Section 8 POWER CONVERSION SUBSYSTEM ANALYSES AND TRADE STUDIES

Analyses and trade studies of the power conversion subsystem (PCS) are described in this section.

#### 8.1 TURBINE-GENERATOR SELECTION

The selection of an appropriate prime mover type was addressed in the early portion of this study and in the technical reviews. A survey of the availability, performance, reliability, and cost of various types of prime movers was made and presented in Volume II, Section 3. Other factors taken into account in the selection process include ease of startup and shutdown, low maintenance costs, and flexibility in power output.

Performance/cost trades showed the steam rankine cycle to have an advantage over organic rankine cycles and Brayton cycles. This advantage would increase as power output was increased beyond 1 MWe. In addition, the steam turbine is a proven design with high reliability and is readily available over a wide range of power levels. The steam turbine was therefore selected as the most appropriate prime mover.

The search for high efficiency steam turbines has led to two options, the first being state-of-the-art axial flow steam turbines readily available for use in the 3.5- and 4.5-year programs. The second option is a radial outflow turbine which promises to have a higher performance than the axial machines, but requires development, eliminating it as a feasible candidate for the 3.5- and 4.5-year programs.

#### Axial Turbine

Using the results of the survey and the specified steam conditions for the 3.5- and 4.5-year programs, the candidate axial turbines were reduced to three.

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A summary of the operating parameters and cost of the candidate turbinegenerators for the 3.5- and 4.5-year programs is presented in Table 8-1. It is obvious from this summary that all the turbine-generators are quite similar in most respects. This includes the ancillary equipment that would be provided with the turbine-generator set and mounted on a common baseplate. Typically, this ancillary equipment would include:

- Oil reservoir
- Gear-driven oil pump
- Motor-driven oil pump
- 0il cooler
- Governing valve
- Emergency stop valve
- Overspeed trip
- Alarms
- Instrumentation

In addition, the condenser can be mounted on the same baseplate.

Table 8-1. Axial Turbine Candidates for the 3.5- and 4.5-Year Programs

	AND INCOME AND INCOME AND INCOME.		
No. of stages	5	8	8-10
Rotor speed, RPM	10,000	10,000 .	10,000
Expansion efficiency, % (to mechanical)	0.68	0.71	0.71
Maximum output, kW	1,800	3,000	3,300
Approximate cost, dollars	410,000	500,000	455,000
Package includes	Condenser, Generator, Steam Jet Ejector, Lube Oil System, Control System	Condenser, Generator, Steam Jet Ejector, Lube Oil System, Control System	Condenser, Generator, Vacuum Pump Lube Oil System, Control System



The selection of a high efficiency, multi-stage marine turbine capable of operating at high temperature was accomplished by a simple trade study comparing the cost of extra collectors to the savings in turbine cost for lower performance multistage and single stage turbines.

In order to select the preferred turbine-generator from the candidates available, a cost-performance trade study was made. This was accomplished using the following two assumptions:

- A. The overall cycle efficiency is directly proportional to the turbine expansion efficiency.
- B. The most sensitive and largest cost element affected by small variations in cycle efficiency is the number of heliostats.

The potential for a reduction in cost of each kilowatt for the PCS is apparent from Table 8-1 which gives the maximum power production capability of the turbines at rated steam conditions. The same turbine built for 3,000 kW would cost only marginally more than one built for 1,000 kW output. Based on vendor budget costs for the remainder of the PCS, the total cost of the PCS would increase by approximately 50% or the cost/kW be reduced by 50%. It is apparent that significant cost savings can be realized by increasing the output power of the PCS.

The radial outflow turbine, as designed by Energy Technology Inc. (ETI), offers significant performance and cost advantages over the axial flow turbines being considered.

Since the steam is introduced at the center and expands radially outward, the low volumetric flow stages have a small diameter and the higher volumetric flow stages are at a larger diameter. The single rotor disc can have a large number of stages resulting in subsonic steam velocities. This results in a high efficiency which is insensitive to load and maintains good efficiency at off-design speeds.

Interstage steam leakage is reduced by the elimination of axial shaft seals necessary in axial machines and the use of fully shrouded blade rows with multiple labyrinth interstage seals. The radial outflow design should also be

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able to tolerate much high moisture levels in the exhaust (up to 15%) without encountering blade erosion problems. Provisions can also be made for multiple extraction ports to provide for regenerative feedwater heating.

In addition to the above performance advantages, the radial outflow turbine has the potential for significant manufacturing and cost advantages in comparison with axial machines. The single rotor disc is mounted on the shaft in an overhung arrangement, leading to reduced housing and sealing requirements and a much more easily balanced shaft than with axial machines. Blade manufacturing costs are greatly reduced, since the blades are untwisted in a radial flow design.

Expansion efficiencies ranging from 80 to 85% are predicted for the ETI turbine, depending on the tightness of tolerances and amount of testing permitted. Individual stage performances are presented in Table 8-2 as computed by ETI. This design has the ability to expand steam to 15% moisture as illustrated in the high temperature, high efficiency design. This ability also contributes to high cycle efficiencies in addition to the improved expansion efficiencies. The physical design of the unit will permit up to five uncontrolled extractions for feedwater heating to enhance cycle performance.

The auxiliary equipment to be provided with all turbines will include a double reduction gearbox, steam throttle valve and emergency shutoff valve, oil lubrication pump, oil cooler, filter and piping. In addition a pressurized oil reservoir will be provided to ensure oil pressure if the oil pump fails. Lubrication requirements are given below.

#### ETI Turbine/Gearbox Lubrication Requirements

Oil Flow Rate	60 liters/min (16 GPM)
0il Pump Power (approx)	1.1 kW (1.5 HP)
Cooling Required	24 kW <sub>t</sub> (81,400 Btu/hr)
Cooling Water Flow Rate	76 liters/min (20 GPM)
Cooling Water Pump Power (approx)	0.45 kW (0.6 HP)

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Table 8-2. Radial Turbine Design for 6.5-Year Program

Design Specifications:

Turbine inlet	510°C (950°F), 121 bars (1,750 psia)
Turbine exhaust	0.084 bars (2.5 in. Hg A)
Shaft speed	12,000 RPM
Overall efficiency	0.850
Power output	1169 kW

Individual Stage Performance:

Number	Exit Pressure (Bars)	Exit Enthalpy (Btu/lb)	Total- Static Efficiency*
1	66.2	3256	0.631
2	37.2	3154	0.697
3	21.4	3051	0.770
4	12.2	2946	0.832
5	6.76	2842	0.896
6	4.07	2758	0,925
7	2.28	2668	0.940
8	1.15	2568	0.941
9	0.51	2456	0.937
10	0.20	2335	0.938
11	0.084	2228	0.939
*Includes ne	nalty for wet stea	63	

#### 8.2 POWER GENERATION CYCLE OPTIMIZATION

The basic power conversion subsystem designs reflect an attempt to develop an optimized cost effectivity design. For the short-term development systems, the design is constrained to the use of state-of-the-art equipment.

One of the issues involved in the cycle optimization concerns the choice of the number of regenerative feedwater heaters and the specification of the extraction pressure and final feedwater temperature. For the 3.5-year system employing an existing axial turbine, these choices are somewhat limited due to the fact that only a single turbine extraction port is available.

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Two alternate configurations which were considered are shown in Figure 8-1. Since only a single turbine extraction is available, both of the options shown have the same cycle efficiency. The key issue involves the ability of the deaerator to provide all of the feedwater heating required to raise the feedwater temperature to 163°C, which is the minimum temperature acceptable at the steam generator inlet (20°C above the fresh salt freeze point). Most larger deaerators are not designed to add significant sensible energy to the feedwater. With such a deaerator, adjacent low and high pressure heaters would be required to provide the necessary sensible heat addition.

During part load operation, the extraction pressure falls below that required to maintain the final feedwater temperature at  $171^{\circ}$ C. Each of the two options is configured with a turbine bypass line to ensure that the  $171^{\circ}$ C temperature is maintained at all times. During periods when the turbine is operating at full load, n or urbine bypass flow will be required for either of the two options.

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Figure 8-1. Design Options for 3.5-Year Axial Turbine System



Clearly from a cost and complexity standpoint, the single heater option is preferred. Representatives of Chicago Heater Company were contacted concerning the feasilibity of the single heater design. They foresaw no special problems in constructing and operating a deaerator in accordance with the proposed scheme. They also felt that it would not be necessary to desuperheat the turbine bypass steam before its introduction into the deaerator. This is a potential area of concern since the steam would be  $\sim 370^{\circ}$ C downstream of the pressure reducing valve which is higher than the normal 343°C design limit for carbon steel. The representatives from a commercial heater company felt that a carbon steel design could be used which would accept the slightly higher steam temperature. They stressed that the bid specification should specify flows, temperatures, and pressures under full load conditions using extraction steam and at part load using turbine bypass steam since the deaerator will have to be designed to accommodate both conditions.

For the 6.5-year program utilizing the radial outflow turbine, options exist concerning the number of and pressure of turbine extraction ports. Two factors were considered in establishing the extraction pressures. First, it is desirable for maximum thermodynamic efficiency to increase the feedwater temperature in approximately equal steps through the heater train. This is constrained to some extent by the steam conditions available at the turbine extraction ports which is controlled by the expansion which occurs across each stage of the turbine. The compromise between these two factors resulted in the extraction pressures and cycle diagram using five feedwater heaters shown in Figure 8-2.

The number of extractions and feedwater heaters specified in the design are the result of a trade study conducted comparing the cost of the heaters to the cost of the energy saved due to higher cycle efficiency. Included in the cost of heaters is the heater, insulation, instrumentation, piping and valves and the labor required to install the above items. The cost of energy is determined by using the cost of heliostats, tower, and receiver for the experimental plant. The results of this study are presented in Figure 8-3 and show that the four heater cycle and five heater cycle are nearly identical. Since the commercial version is expected to have five heaters, the five heater cycle has been selected for the experimental plant.

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Figure 8-2. Power Conversion for 6.5-Year System Based on a Radial Turbine





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#### 8.3 STEAM GENERATOR

The steam generator types considered for this application are described below.

- A once-through steam generator. A spiral-wound annulus of tubing contains the water/steam and is bathed by salt on the shell side.
   Water enters the tubing at one end, boils as it passes through the tubing and exits as super heated vapor.
- B. A separate preheater, natural recirculation boiler with steam drum, and a separate superheater. The water/steam is contained on the tube side of the heat exchangers, the salt on the shell side.
- C. A separate preheater, kettle boiler, and superheater. The water/ steam is on the tube side in the preheater and superheater and on the shell side in the kettle boiler.

The design selected for use is the separate preheater, natural recirculation boiler and superheater. This type of unit offers distinct operational advantages over a once-through steam generator. These advantages include:

- Reduced feedwater purity requirements
- Easier startup (A turbine bypass circulation loop is not required)
- Easier control of outlet pressure and temperature due to separation of boiler and superheater
- Less danger of moisture entering turbine

The kettle boiler is impractical at the high steam pressures being used due to the required thickness of the shell walls.

The availability and feasibility of the selected type of steam generator has been confirmed by both domestic and foreign manufacturers.

A preliminary analysis of the steam generator design parameters was accomplished to facilitate cost estimates and provide inputs to general arrangement drawings. A plot of the Hitec/HTS and water/steam temperatures versus percentage of enthalpy change is given for each of the three programs in Figures 8-4 to 8-6. The resultant design parameters and requirements are listed in Table 8-3 for the three experimental programs.

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Figure 8-4. Enthalpy Change Diagram (3.5-Year Program)



Figure 8-5. Enthalpy Change Diagram (4.5-Year Program)

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Program time		3.5 Year	4.5 Year	6.5 Year
Preheater				
Туре	Two-pass	U-tubes with	longitudinal baffle,	Type CFU
LMTD* °C(°F)		67 (120)	76 (137)	23 (42)
U Value ** kW/hr-m <sup>2</sup> -°C (Btu/hr-ft <sup>2</sup> -°F)			1.13 (200)	
Duty, MW <sub>t</sub> (Btu x Tube area m <sup>2</sup> (ft <sup>2</sup>	10 <sup>-6</sup> ) ')	0.89 (3.0) 11.6 (125)	1.0 (3.4) 11.6 (125)	0.5 (1.7) 18.8 (200)

Table 8-3. Steam Generator Design Parameters

\* LMTD - Log mean temperature difference

\*\* U Value - Overall heat transfer coefficient

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Program Time	3.5 Year	4.5 Year	6.5 Year
Boiler			
Туре	Natural recircula	ation with steam	drum
LMTD* °C(°F)	94 (170)	81 (146)	49 (88)
U Value ** Vul/bram <sup>2</sup> -°C	1 28	(225)	
(Btu/hr-ft <sup>2</sup> -°F)		(220)	
Duty, MW <sub>t</sub> (Btu x 10 <sup>-6</sup> )	2.67 (9.10)	1.75 (5.97)	1.47 (5.00)
Tube area $m^2$ (ft <sup>2</sup> )	22.1 (238)	16.9 (182)	23.2 (250)
Superheater			
Type 2-pass	U-tube with long	itudinal baffle,	Type CFU
LMTD* °C(°F)	81 (145)	71 (128)	65 (117)
U Value** kW/hr-m <sup>2</sup> -°C (Btu/hr-ft <sup>2</sup> -°F)	0.9	993 (175)	
Duty, MW <sub>t</sub> (Btu x 10 <sup>-6</sup> )	0.68 (2.32)	0.83 (2.83)	0.86 (2.94)
Tube area $m^2$ (ft <sup>2</sup> )	8.4 (91)	11.7 (126)	13.4 (144)

Table 8-3. Steam Generator Design Parameters (Continued)

#### 8.4 BOILER FEEDWATER QUALITY

Stearns-Roger carried out a study of issues related to boiler feedwater quality. The purpose of the study was to:

- A. Review industrial/utility boiler water quality requirements and verify their applicability to a 1 MW plant.
- B. Assess the impact of cyclic operation on water quality and equipment requirements.
- C. Evaluate potential design options for the feedwater loop.
- D. Define cost impacts.

The study assumed a recirculating drum-type steam generator which is the baseline configuration for each of the candidate EE No. 1 systems. If a once-through steam generator design were adopted, the water quality requirements would be more stringent than those considered in this study. The results of the study are presented below.

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#### 8.4.1 General Feedwater Treatment Considerations

References 8-1 and 8-2 provide general discussions of recommended feedwater and boiler water concentrations, and list recommended limits.

Only very low concentrations of corrosion products such as iron and copper are permitted, since these materials deposit upon heat transfer surfaces in the boiler. Most of the iron and copper present in boiler feedwater exist as suspended solids in the form of the respective oxides; however, a portion of these materials will be present in the form of dissolved ions. In either case, they form insoluble deposits once introduced into the boiler. They do not remain suspended in the boiler water and accordingly, cannot be removed by blowdown. For this reason, it is necessary to establish limits for their concentration in the feedwater rather than in the boiler water.

Conversely, limits have been established in the boiler water for such constituents as silica, hydroxyl alkalinity, and total dissolved solids because, with some qualifications, these do not deposit in the boiler, and their concentrations can be controlled by blowdown, assuming that they are reasonably low in the feedwater. The primary reason for limiting these concentrations is to assure high steam purity. The steam purity limits shown in References 8-3 and 8-4 are extremely stringent, and were established subsequent to the establishment of the boiler water limits in the earlier references. They imply that more stringent boiler water limits may now be needed. However, there is a significant lack of data regarding steam purity levels at varying boiler water concentrations.

The most common water treatment approach for utility boilers is coordinated phosphate-pH control in which an elevated pH is achieved by the maintenance of a mixture of disodium phosphate and trisodium phosphate in relatively low concentrations in the boiler water. The elevated pH provides corrosion protection as well as some buffering against acid attack in the event of cooling water contamination of the condensate, which can reduce boiler water pH. The phosphate also provides a measure of protection against condensate contamination, precipitating as a relatively loose deposit small amounts of calcium,

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which would otherwise form a scale. In addition, formation of free hydroxide is prevented. This is desirable since concentration of hydroxide under deposits or at other dead spots in the boiler will result in caustic attack of the steel.

A disadvantage of coordinated phosphate-pH control is that the need to maintain a phosphate residual in the boiler, however low, increases the potential for steam contamination. An alternative approach is utilization of what is termed "all volatile treatment." With this approach, only volatile materials such as hydrazine, neutralizing amines, and ammonia are employed. Since no protection against condensate contamination is provided, such treatment is quite risky without full flow condensate polishing. Assuming good control utilization of full flow condensate polishing and all-volatile treatment will assure steam of suitable purity for turbine operation.

Full flow condensate polishing with all volatile treatment is essential for once-through steam generators since such units cannot be blown down, and all solids entering the unit will either deposit in the steam generator or contaminate the steam.

#### 8.4.2 Cyclic Operation

Reference 8-5 addresses problems associated with cyclic operation such as would be encountered with the unit under discussion. Operation would be similar to that described in the introduction of this reference as "B-Peaking Mode of Two-Shifting." Specifically, the potential for formation of undue concentrations of corrosion products in the condensate and feedwater systems of such units is much greater than for base loaded units because of the increased opportunity for air inleakage. (The term "preboiler" in this reference refers to the condensate and feedwater system.) As the paper indicates, Combustion Engineering recommends that cycling units have an auxiliary subloop of 25% capacity for preboiler cleanup to reduce suspended solids (primarily corrosion products) and oxygen levels to suitable low levels after startup. Even with such a subloop, cyclic units will accumulate more internal deposits than an equivalent base loaded unit, and will require more

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frequent chemical cleaning. By implication, without the use of such a loop, cleaning requirements would be excessive.

A full flow, deep bed condensate polisher was assumed for this unit rather than a 25% side loop since, considering the low condensate flow rate, the cost of such a unit would not be significantly greater than for a unit rated at 25%. The full flow unit would have the additional advantage of permitting boiler operation with all volatile treatment rather than coordinated phosphate-pH control, reducing the potential for turbine problems because of contaminated steam.

Four steam cycle configurations are now under consideration for the subject plant (three versions of EE No. 1 and the commercial unit). Two of these employ axial turbines with a single tray-type deaerator. The other two employ radial turbines with a deaerator, two closed low pressure heaters and two closed high pressure heaters. Operation without cleanup provisions is feasible with the axial turbine approaches, since considerably less opportunity for introduction of corrosion products into the preboiler cycle exists with systems involving a single, closed high pressure feedwater heater.

In the cases involving radial turbines, the quantity of metal exposed to the condensate and feedwater is significantly greater, and the design should include provisions for coping with the high corrosion product load encountered with cyclic operation. This was the principal reason for inclusion of the condensate polisher in the preliminary design.

Reference 8-5 also describes the importance of maintaining a low oxygen environment in the preboiler during cleanup to promote the formation of magnetite, which is more readily removed by condensate polishing than is ferric oxide. The absence of auxiliary steam for deaeration prior to startup eliminates this capability, meaning that cleanup will be delayed. This can be partially compensated for by utilizing a full flow condensate polisher instead of a side loop.

An alternative would involve the use of titanium tubes in the condenser, and stainless steel tubes in the feedwater heaters. Titanium would be recommended for the condenser tubes because of the susceptibility of stainless steel tubes to concentration cell corrosion on the circulating water side should they become partially covered with sediment while the system is shut down.

Utilization of stainless steel tubes in high pressure feedwater heaters is relatively limited because of the expense. Accordingly, very little data is available concerning iron pickup from such systems. This lack of data compels us to not recommend this approach.

#### 8.4.3 Boiler Feedwater Conclusions

Full flow condensate polishing will be used for either of the two radial turbine cycles because of the number of feedwater heaters employed, and because of the particularly strong susceptibility of low pressure heater drips to corrosion products pickup. It will also be used in the axial turbine cycles to enhance reliability/availability of EE No. 1. A powdered resin unit will be used for this function.

8.5 NIGHTTIME CONDITIONING

An evaluation of alternate nighttime procedures was also conducted to determine the preferred procedure to be employed during nighttime nonoperating periods. Three alternate approaches were considered: (1) total shutdown - no conditioning systems operating, (2) steam blanketing, and (3)  $GN_2$  pressurization.

The critical issues include

- Thermal cycling of components
- Potential air inleakage and resulting hardware corrosion
- Acceptable rate for subsequent morning startup
- Required ancillary equipment
- Required operator involvement



#### 8.5.1 Total Shutdown

Total system shutdown employs no conditioning procedures and equipment. As a result, the hot equipment is allowed to soak down in temperature and in turn must be reheated to its operating temperature during subsequent morning startup. This approach maximizes the thermal cycling and stress problems for the turbine.

Since the local vapor pressure can drop well below atmospheric pressure through most of the water/steam loop, chances for air leakage into the loop are high. The oxygen which enters the loop subsequently attacks the carbon steel surfaces resulting in significant corrosion. On the other hand, this approach requires no additional ancillary equipment and completely eliminates the need for any operator involvement during shutdown periods.

#### 8.5.2 Steam Blanketing

The blanketing steam option uses low grade steam to maintain an elevated temperature and pressure in those elements of the water/steam loop which normally operate above atmospheric pressure (deaerator, pipes, steam generator, and turbine seals). The low pressure in the condenser is maintained by continuing the operation of the vacuum equipment to prevent atmospheric leakage. Since this approach maintains the water/steam loop conditions somewhat near the actual operating conditions, rapid morning startup can be accomplished with a minimum level of thermal cycling.

The use of blanketing steam requires auxiliary equipment in the form of additional lines, valves, regulators, and drains to distribute and control the blanketing steam. The steam generator may be designed to serve as the source of the steam as long as thermal energy can be drawn from the thermal storage. This approach requires an additional low-flow salt pump for nighttime operation. Since only low grade steam is required, the thermal energy could be extracted from the cold tank or low temperature zone of a thermocline design, the latter approach requiring an additional manifold to be located

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some distance above the bottom manifold in the thermocline storage tank. In the event that stored thermal energy is not available, a standby boiler would be required.

From an operational standpoint, the use of blanketing steam requires the highest level of nighttime equipment operation. As discussed above, water/steam circulation, salt circulation, and condenser vacuum equipment must be operated during this period. This approach will require a more sophisticated level of standby control and may require the presence of an operator, depending on the code requirements for the steam generator and auxiliary boiler.

# 8.5.3 GN<sub>2</sub> Pressurization

The use of pressurized GN<sub>2</sub> eliminates much of the operational concerns and equipment costs associated with the blanketing steam approach. In this approach, the entire water/steam loop is pressurized with an inert environment to prevent air inleakage and resulting corrosion. Since the condenser is also pressurized, the vacuum equipment is shut down. In addition, there is no need for the circulation of either water/steam or salt.

From the standpoint of subsequent morning startup, the condenser vacuum must be reestablished and the  $GN_2$  must be vented from the loop. Since the  $GN_2$  does not maintain the operating thermal environment within the loop, the startup must be controlled to minimize the problems associated with thermal cycling.

Since the approach of total system shutdown is felt to be unacceptable because of the problems associated with air inleakage and corrosion, some type of nighttime conditioning is required. Of the two conditioning approaches, the pressurized GN<sub>2</sub> approach is preferred because of lower cost for ancillary equipment, operational simplicity, and potential for unattended operation.



#### 8.6 PUMP REDUNDANCY

A study has carried out to assess the cost impact associated with pump redundancy. The study considered the condensate pump as defined by requirements for the 3.5-year development system. Four cases were considered: (1) a single 100% capacity pump, (2) two 100% capacity pumps in parallel, (3) two 50% capacity pumps, and (4) three 50% capacity pumps. For each of these cases, both carbon and stainless steel were treated (stainless steel would be appropriate if inline condensate polishers were not used in the loop).

The analysis considered both pump and piping costs as well as costs associated with the electrical supply. They were based on information available for a Gould VIC model 6ALC pump and drive. The pump would be similar for both the 100% and 50% with 27 and 22 stages being required respectively for the two applications. With this design, the 100% capacity pump would have an efficiency of 62% while the 50% capacity pump would have an efficiency of 46%.

The cost breakdown is contained in the following tabulation.

<u>One 100% Pump</u>	Carbon Steel	Stainless Stee	
Pump	\$ 5,000	\$18,000	
Piping	1,830	3,730	
Electrical Supply	400	400	
Total Cost	\$ 7,230	\$22,130	
Two 100% Pumps			
Pump	\$10,000	\$36,000	
Piping	3,660	7,460	
Electrical Supply	800	800	
Total Cost	\$14,460	\$44,260	

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\$ 9,000	\$31,000
2,880	6,380
800	800
\$12,680	\$38,180
\$13,500	\$46,500
4,320	9,570
1,200	1,200
\$19,020	\$57,270
	\$ 9,000 2,880 800 \$12,680 \$13,500 4,320 1,200 \$19,020

The economic superiority of the single 100% capacity carbon steel pump clearly is apparent. Based on previous availability analysis, the need for pump redundancy has not been justified, as a result, the 100% capacity carbon steel pump was selected for the baseline system design.

#### 8.7 HEAT REJECTION METHODS

A study was carried out to compare alternate methods for plant heat rejection. Issues of interest included capital cost, parasitic power requirements, and impacts on turbine back pressure. Three heat rejection approaches were considered:

- A. Wet cooling tower
- B. Dry cooling tower
- C. Direct contact dry cooled condenser

The wet cooling tower employs a water loop which carries the heat of condensation from the condenser located at the turbine exhaust to the cooling tower. The heated water then cascades down the tower walls which allows evaporation to remove the heat from the water. The resulting minimum water temperature approaches the local wet-bulb temperature. Tower mounted fans are used to enhance the air circulation through the tower.

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The dry cooling tower equipment operates in a fashion similar to the wet cooling tower with the exception that the cooling water circuit is a completely closed loop. As a result, air forced through the tower passes over a heat transfer surface and allows the cooling water temperature to approach the local dry-bulb temperature.

The direct contact dry cooled condenser employs a series of heat transfer surfaces as an integral part of the condenser. Air forced over these surfaces condenses the steam directly. The condensation temperature and pressure are controlled by the local dry-bulb temperature.

The cost and parasitic power requirements for the three alternate heat rejection approaches are summarized in the following table for equipment sized to reject 3 MWt.

	Wet Tower	Dry Tower	Direct Contact
Cost			
Condenser	\$ 3,000	\$ 3,000 }	\$155,000
Vacuum System	11,000	11,000 }	
Tower	25,000	118,000	
Water Treatment	22,000	22.000	
Water Circulation	4,500	4,500	
Total	\$65,500	\$158,500	\$155,000
Parasitic Power			
Fan	15 kW	90 kW	58 kW
Pump	9 kW	15 k₩	

If cooling water is available, the cost and parasitic power advantages of the wet tower make it the obvious choice for heat rejection. An additional benefit of wet cooling is the lower turbine back pressure which can be maintained, resulting in a higher turbine cycle efficiency. A typical condenser pressure for a wet tower is 2.5 in Hg as opposed to 5.0 in Hg for a dry cooling system. The wet tower heat rejection equipment was selected and physical features are presented in Volume III, Section 4.7.

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#### 8.8 COOLING TOWER MAKEUP WATER REQUIREMENTS

The cooling tower makeup water requirement is the sum of the cooling tower evaporation rate, drift rate, and blowdown rate. The tower blowdown rate is given by

Blowdown, BD =  $\frac{E + D (1-C)}{C-1}$ 

where

E = Evaporation rate
D = Drift rate
C = Number of cycles concentration

The tower evaporation can be assumed to be equal to approximately threefourths of 1% of the circulating water flow for every  $5.6^{\circ}C$  ( $10^{\circ}F$ ) of cooling range. Thus, for the design conditions, the evaporation rate is approximately 2,400 kg/hr.

The drift rate for normal wind conditions can be assumed to be 0.01% of the circulating water flow, or 29 kg/hr. The number of cycles that can be maintained will depend on the makeup water quality but a typical number of cycles is six, resulting in a blowdown rate of 480 kg/hr and a total water consumption of 2,909 kg/hr.

8.9 CONTROL VALVE ACTUATOR SELECTION

A comparative evaluation between pneumatic and electrical valve actuators was made to determine the preferred approach for the power conversion subsystem.

Penumatic actuators have many features which resulted in their selection as the preferred approach. They are by far the most common and best suited for the linear stroking action of globe-type control valves. They are low friction devices and through simple spring adjustment have a definite position for every air pressure valve. This eliminates the need for a separate positioner which is normally required on electrically driven actuators.



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An additional advantage for the pneumatic actuator occurs in the event of a power failure. Since they operate off of a compressed air reservoir, their operation will be uninterrupted. The electrical actuators on the other hand would experience a loss of power for the 10 to 15 sec period required to bring the standby diesel generator on line. As a result, the electrically operated valves would move to their normal failed position. The alternative would be to tie the electrical actuators to the uninterruptible power supply (UPS) which would add to the cost of the UPS equipment.

If the control valve is located at a significant distance from the compressed air reservoir, valve responsiveness may be compromised due to the long line lengths through which the supply air must pass. For these applications, electrically operated valves may be preferred. However, for the design conditions anticipated for the 1 MW system, sufficiently short line lengths are involved so that the pneumatic actuators are clearly superior.

From a cost standpoint, the pneumatic actuators are also superior. The principal elements are a pneumatic regulator, diaphragm, bonnet, and spring. By contrast, an electrical actuator requires an electric motor, positioner, speed reduction gearing, and a crank assembly to convert rotary motion into linear motion if such a control motion is required for the control valve. If a rotary motion is sufficient for control valve operation as for example with a butterfly control valve, the crank assembly may be eliminated.

## Section 9 PLANT CONTROL SUBSYSTEM ANALYSES

Analyses and tradeoffs performed for the plant control subsystem were conducted in the following categories:

- Receiver control analysis
- HAC Computer tradeoff analysis
- Plant control system tradeoff analysis

The receiver control analysis was conducted to define a receiver control system design with sufficient bandwidth to reject the effects of disturbances and maintain a control system implementation that is simple and reliable.

The tradeoff analysis for the heliostat array controller computer was conducted to minimize implementation costs and evaluate the hardware throughput to accommodate concurrent collector control and plant control supervisory operations.

A trade analysis was performed to evaluate commercially available plant control systems that could be adapted to automatic control application for a small power plant with modularity that allows growth from the manually controlled 3.5-year plant to a completely automatic unattended commercial plant.

9.1 RECEIVER CONTROL ANALYSIS

The primary requirement for the receiver control system is that it maintain the desired fluid outlet temperature within a desired operating band in the presence of disturbances, either from variation in insolation or from flow anomalies.



#### 9.1.1 Control Simulation

Due to the nature of the central receiver design (large thermal capacitance and long absorption tubes), the receiver open-loop plant response is rather slow (≈100 sec time constants) relative to the nature of the insolation disturbances (≈10 sec). It is the goal to design a receiver control system with sufficient bandwidth to reject the effects of disturbances while maintaining a control system implementation that is relatively simple and reliable.

A candidate is shown in Figure 9-1. The receiver outlet temperature is controlled by sensing outlet fluid temperature and regulating the receiver inlet flow by means of a PID controller, control valve, and actuator. A typical linearized model of this control system is also presented in Figure 9-1.

The plant dynamics of the receiver is simplified for linear analysis purposes into the two first order systems cascaded with an equivalent system transport lag. The first order time constants are the equivalent roots resulting from the effects of coupling the dynamics of the wall, the fluid and the flowrate phenomena. Typical values used for initial control system design and sizing are shown in Figure 9-1.

A dynamic simulation of the receiver loop was generated to support the design of the receiver control system and also for evaluating the receiver response to insolation disturbances. The physical configuration of the receiver system is shown in Figure 9-2. The mathematical model of the receiver is a lumped parameter model where the receiver is divided into sections and energy and mass balance equations are derived in Figure 9-2 for each section.

Typically each section of the receiver is characterized by a wall and a fluid temperature node with the driving functions being a variable insolation on the receiver wall and a modulated fluid flowrate both in and out of each section. Nonlinear effects such as independent flux profile for each section, nonlinear film coefficients and variable receiver losses are included in the model.



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This simulation is implemented into a digital computer using the FORTRAN IV language. Capability for preselected number of sections for the receiver model is provided within the simulation so that the sensitivity of the results can be easily evaluated as a function of the arbitrary number of sections selected for the receiver. For preliminary analysis and evaluation, the receiver has been divided into six distinct sections.

A typical open loop response of the receiver to a step change in flowrate is shown in Figure 9-3 and demonstrates the relatively slow response of the receiver without controls. Addition of a control loop significantly increases the response of the receiver to disturbances. Using the preliminary control system model as described in Figure 9-1 and the receiver simulation, a typical closed loop control system response was evaluated for a relatively short period insolation disturbance. The system configuration and response is as shown in Figure 9-4. The control system gain and compensation have been adjusted for a relatively high gain (high bandwidth) system and the receiver outlet temperature variation is within 5° of the desired value for a 50% uniform variation in input insolation.

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Figure 9-3. Receiver Response to a Step Decrease in Flow - No Control



Figure 9-4. Receiver Response to all Insolation Transient - With Control

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#### 9.1.2 Receiver Control Considerations

The receiver control system compensation for this receiver model consists of proportional plus integral compensation to provide good steady state response characteristics and with sufficient loop gain (closed-loop bandwidth) to reject insolation disturbances. Phase lag contributed by a transport delay will result in a decrease in bandwidth based on stability considerations and degrade system performance. Additional lead-lag control system compensation can be implemented however to offset the additional phase lag due to this effect and to maintain the closed-loop bandwidth. The plant dynamic characteristics (gain and phase lag) are highly a function of receiver flowrate. A significant penalty in control system disturbance rejection capability or in closed-loop stability is paid if the control system gains and times are not variable with flowrate.

For example, if the control gains are set for good disturbance rejection (high gains) a significant penalty is stability is paid during low flux, low flow conditions characteristic of startup. A potential can exist for an oscillation during startup. A typical startup transient is shown for both high gain/low gain control systems in Figure 9-5. The low gain system exhibits a much more stable control response and a faster time to achieve rated temperature than the high gain system. Therefore, lower gains are desirable at lower flows. At the higher flux and higher flow conditions a high gain is desirable to reject short term and small amplitude disturbances. Therefore, to achieve a desirable control system response over the full range of operating conditions the control system gains and control time constants must be varied based on the operating condition.

#### 9.1.3 Receiver Transient Response to Disturbances

The receiver control system must be designed to achieve a stable, well controlled response when subjected to both large signal and small signal disturbances. A typical large signal disturbance is due to the passage of an opaque cloud over the collector field (0-100%) while a small signal disturbance might be due to partial clouds or heliostat variations.





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Figure 9.5. Receiver Morning Startup

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A simulated response to a cloud blackage transient (0 to 100% variation in 10 sec) is shown in Figure 9-6. A simulated receiver cooldown and recovery transient are shown. For a 100% blockage cloud transient and recovery, the response was stable and maintained the peak temperature over-shoot to within 468°C (875°F). The recovery transient requires approximately 120 sec and a temperature ramp command must be implemented during the recovery phase to minimize overshoot. The temperature command ramp can be mechanized and initiated within the master control system based on system flowrates, outlet temperature and/or temperature error. This simulated response demonstrates that a single temperature control loop can maintain control of the receiver under rather severe variations in solar flux.

The receiver control system can also reject small signal variations in insolation. Using the receiver simulation the receiver control system was subjected to a  $\pm$  10% sinusoidal variation in insolation at frequencies from 0.1 to 0.01 Hz. The receiver controller maintains the outlet temperature to within  $\pm$  4.5°C (8°F) of the commanded temperature. A summary of this small signal disturbance rejection capability is shown in Figure 9-7.

#### 9.1.4 Conclusions

A preliminary control system design and simulation was developed during the Phase I effort. The results substantiate that a simple single loop PID controller is adequate for controlling the receiver during startup, typical and severe cloud blockage transients as well as small signal variations in solar flux. It is also concluded that it is necessary to adjust controller gains time constants and the temperature set point as a function of the operating conditions in order to maintain a stable desirable response with a wide range of operating conditions.

#### 9.2 HAC COMPUTER TRADEOFF ANALYSIS

The heliostat array controller provides the automatic coordinated control of the collectors. The hardware and software for this function have been designed and implemented in a MODCOMP Classic 7861 computer for installation in the Solar Power 10 MWe Pilot Plant to be constructed at Daggett, California.







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The hardware was sized for this application considering a collector field in excess of 1,600 heliostats.

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EE No. 1 would require approximately 200 or less heliostats and therefore it was necessary to determine; (1) can a more cost effective computer size and type be used for HAC functions and still provide minimum hardware and software development risks for the 3.5-year program and; (2) can a single computer system provide the collector control functions of the HAC the HFC and the supervisory functions of plant control in a real-time multitasking concurrent mode of processor operation.

The analysis considered: (1) a scaled-down version of the MODCOMP Classic 7863 computer used for the 10 MWe Solar Pilot Plant; (2) a different MODCOMP computer (Model 7810-4) having lesser performance and expansion capability than the Classic 7863 but software compatible; and (3) a computer system of a different manufacturer (DEC LSI 11-2) that was compatible with and commercially available for a CAMAC (computer aided measurement and control system), a candidate process control system evaluated for plant control.

An analysis was performed to determine the instruction throughput requirements for the aggregate of the three software tasks (i.e., HAC, HFC and plant control). This analysis used previous analyses conducted for the HAC and HFC and applied an estimated instruction execution set and number of instructions for plant control supervisory functions.

A modified Gibson mix of instructions shown in Table 9-1 was considered typical of the percentage mix of instructions for the Plant supervisory control function. The size of the plant control supervisory function was estimated based on the number of plant control and monitor functions summarized in Table 9-2 and assuming that a complete cycle through the plant application code would occur once every second.

The computer system performance for each candidate was estimated using timing data from the instruction set and compared with the expected aggregate performance required (K operations, per second) to execute the computer code in 2 seconds.



Instruction	Percent of mix	
Load/store - double precision	35.6	
Add — single precision	8.0	
Multiply - single precision	5.3	
Divide - single precision	1.1	
Add — floating point	3.5	
Multiply — floating point	1.9	
Divide — floating point	0.8	
Compare — logic	21,3	
Branch	15.8	
Miscellaneous	6.7	
	100 Instructions	

#### Table 9-1. Modified Gibson Instruction Mix

The computer applications code was determined for the three applications and was used in the sizing of the computer configuration memory along with the operating system code, the data base and table requirements. The computer and required peripherals were sized and priced. To this price was added the nonrecurring software implementation costs expected for conversion of existing HAC computer codes to the new computer configurations.

The throughput data were summarized and compared. This summary is shown in Table 9-3 and Figure 9-8. The cost differences for the MODCOMP 7810-4 and LSI 11-2 hardware were insignificant when considering the software code conversion costs although the LSI-11 hardware cost were only 60% of the MODCOMP 7810 costs and 35% of the MODCOMP 7861 costs.

The LSE 11-2 configuration has the second best performance capability but provides the largest risk to the short 8-month development period of the 3.5-year program. The risk is in the development and conversion of existing HAC software on a new machine that uses a different operating system, has differences in FORTRAN IV instruction SRT, requires a completely new assembly language code for all I/O drivers and new equipment familiarization and . learning by the programmers.

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Number of measurements/location Subsystem Measurement Concentrator Temperature 24 Receiver absorber tube wall temperatures Receiver manifold wall temperatures Postion 2 Receiver absorber housing wall temperatures 8 Receiver track heating sections 4 Receiver absorber door positions and drive 4 2 Receiver safety/relief valves Heliostat 3 axes drive positions 609 Hot/cold tank wall temperatures 24 Energy storage Temperature Hot/cold tank level Pressure 6 2 Hot/cold tank fluid pressure Level Hot/cold tank ullage pressure (GN2) 4 Hot/cold tank fluid temperature 6 Receiver feed pump motor current Energy transport Temperature 1 Receiver panel flow Flow 7 Position Receiver control valve positions 2 Receiver pipe tracing heating temperatures Current 4 Hot/cold tank control valve positions 4 Energy transport pipe temperatures 2 Energy transport pipe trace heater state 2 Energy fluid to steam generator pipe temperatures 8 3 Energy fluid to steam generator heater state 2 Energy fluid mixing/hot flow Hot/cold energy fluid mixing temperature 1 Power conversion Temperature Flow Voltage 2 Boiler steam flow Level Current 1 Boiler H2O level Position Frequency 7 Boiler H<sub>2</sub>O temperature High pressure heater levels Speed 3 Phase 3 High pressure heater temperatures 3 High pressure heater pressures

Low pressure heater level

Low pressure heater temperature

#### Table 9-2. Plant Control and Measurements Summary

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Subsystem	Measurement	Number of measurements/location		
Power conversion (Con't)		<ol> <li>Low pressure heater pressure</li> <li>Turbine governing valve pressure</li> <li>Turbine emergency stop valve position</li> <li>Turbine speed</li> <li>Turbine generator synchronization phase</li> <li>Turbine auxillary system starts</li> <li>Compressor vacuum</li> <li>Generator current</li> <li>Generator voltage</li> <li>Generator frequency</li> </ol>		
Balance of plant	Temperature Pressure Flow Level Position Voltage Current	Demineralizer/polisher H20 flow Demineralizer/polisher conductivity Demineralizer/polisher contrnt Demineralizer/polisher drain valve position Boiler feed chemical tank level Boiler feed chemical tank pressure Boiler feed chemical tank pump state Ammonia feed tank level Ammonia feed tank level Hydrazine feed tank pressure Cooling tower blow down valve position Cooling tower acid feed valve position Cooling tower acid feed pressure Cooling tower chemical tank level Cooling tower chemical tank level Cooling tower chemical tank feed pump state Cooling tower coling temperature Station/substation power voltage Cooling tower current		

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# Table 9-2. Plant Control and Measurements Summary (Continued)

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Subsystem	Measurement	Number of measurements/location		
Balance of plant (Con't)		2 Facility air pressure 1 Facility air compressor motor state 1 Weather station temperature 1 Weather station wind direction 1 Weather station wind velocity 1 Weather station humidity 2 Weather station insulation		

Table 9-2. Plant Control and Measurements Summary (Continued)

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Task	Data	Instructions	Ops/sec fixed point	Ops/sec floating point
Operating system (Max III)		12,000		
Executive functions	100	200	5,000	
Scheduler			3,600	
Data acquisition and control	812	67	1,206	
Man-machine S/W	1,000	220	2,900	
Steady state mode (one)			1,163	
Mode transition control (one)	1,000		200	
Plant subsystem monitors	5,255	1,062	2,036	3,376
Plant performance calculations (background only)	1,000	3,000		
One-line diagnostics	170	650		
Totals	9,337	17,199	16,105	3,376

### Table 9-3. Computer Throughput and Memory Sizing, Summary, Heliostat Array Control Computer (HAC) 3.5-Year Program

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المريح محافظ ومحملة المريح محملة المريح والمستخلف ومن علم المريح المريح ومن معتقر ومن من المريح ومن محملة المست المريح من المريح الم

Total memory req = 26,536

Throughput req = 16,105 fixed point type instructions

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= 3,376 floating point type instructions

Note: HFC reqmts Add: Fixed Pt: 53.7 KOPS Flt Pt: 7.4 KOPS

1000 96,1 **900** 160 90 K OPERATIONS PER SECOND 80 76,6 70 60 50 KOPS/SEC REQUIRED FOR 4.5-YEAR AND 6.5-YEAR SYSTEM 40 30 24,5 20 KOPS/SEC REQUIRED FOR 3.5-YEAR SYSTEM 10 0 MODCOMP 7861 DEC LSI-II MODCOMP 7810

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Figure 9-8. HAC Throughput Analysis Summary

The tradeoff analysis shows the MODCOMP 7810-4 provides adequate performance for the 3.5-year program at a lower cost than the equipment used for the 10 MWe Solar Power Pilot Plant and there is a high degree of software compatibility between the two machines. The LSE 11-2 computer would be selected for the 4.5-year, 6.5-year and commercial programs since: (1) the longer development times of these programs negate risk, (2) the development cost is the same; (3) the MODCOMP 7810 computer cannot meet throughput requirements for these programs (HFC functions added to HAC); and (4) the LSI-11 hardware would be more economical for commercialization.

#### 9.3 PLANT CONTROL SYSTEM TRADEOFF ANALYSIS

The goal of the commercial program is to provide complete unattended automatic operation of the plant with a provision that allows an operator to control the plant in a degraded manual mode or an intermediate semiautomatic mode.

In the manual mode of operation, the supervisory processor would not be available, hence, the operator controls each event sequence, commands each action and makes all decisions. It is important in the implementation of manual control operation that a single operator not be burdened to the point that he cannot adequately control the plant. Of parallel importance, should the redundant computer systems fail in automatic control (loss of power for example) the plant remains in a stable safe condition. Therefore, the manual control provisions must provide built-in logic to aid manual control operations and provide control stability at each control point if the operator or automatic system fails.

Modern process control systems provide these capabilities and offer distributed digital supervisory control techniques. However, the market place for most of these systems is in the large utilities and large batch process industries such as textile, petrochemical, and food. A large entry level cost is associated with the procurement of these systems since their operation is usually based on high cost color graphic intelligent operator terminals, and includes unwanted flexibilities and capabilities in the basic configurations (i.e., high quantity entry level packaging, redundancy, interface adaptations for user functions and auxiliary test and display hardware, etc.).

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Smaller control systems exist in the programmed logic controller (PLC) category and are reasonably priced. However, these systems contain very limited arithmetic capability and are not equipped to handle three mode controller functions (PID) that require sophisticated feedback, feed forward, cascade and adaptive control algorithms. Consequently, the use of these systems for this plant are not attractive.

A survey of systems for process control functions revealed two candidates that would satisfy the requirements of (1) distributed supervisory digital control, (2) three mode controller capability, (3) simple operator interface, (4) programmable logic and arithmetic function control, (5) interface to a host process computer, (6) low entry level modularity, (7) growth capability, (8) reasonable entry level costs for small systems, and (9) commercially available. The Texas Instruments PM 550 system and the CAMAC system architecture were analyzed and a tradeoff study performed.

CAMAC hardware is developed from an international interface standard adopted by IEEE in their IEEE specification 583-1975. The hardware is very modular and is built by a variety of vendors in the USA and Europe. A typical CAMAC control system block diagram that would satisfy the architecture design for this application is shown in Figure 9-9.

A block diagram of the Texas Instrument PM 550 control system is shown in Figure 9-10.

The trade analysis compared both systems in the following categories: For the 3.5-year system capacity.

- Hardware cost
- Software cost
- Growth/Exapndability
- Programmability (Difficulty)
- Modularity
- Distributed Control Allocation
- Three Mode Control Capability

Equipment allocations that satisfy the 3.5-year system requirements are shown in Tables 9-4 and 9-5. A summary of this comparison is shown in Table 9-6.

The summary shows the PM 550 system provides satisfactory allocations in each of the compared categories at substantially reduced costs for hardware and software development. The PM 550 system was selected for the EE1 application.

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Figure 9-9. Typical CAMAC Control System Block Diagram

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Figure 9-10. TI PM550 Control System Block Diagram

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Qty	Part no.	Description	Manufacturer
1	PM550-300	Programmer with keyboard and display	Texas Instrument
1	PM550-100	Central control unit	Texas Instrument
٦	PM550-220	Power supply	Texas Instrument
1	PM500-410	Timer/counter access module	Texas Instrument
1	PM550 (5TI14100)	Simulator	Texas Instrument
5	PM550-400	Loop access modules	Texas Instrument
8	6MT-50	Mounting base	Texas Instrument
2	6MT-33	8 channel input/output interface	Texas Instrument
7	6MT-31	16 channel input interface	Texas Instrument
4	6MT-32	l6 channel output interface	Texas Instrument
1	571-5500	Input/output expander for 6MT system	Texas Instrument
5	7MT-900	Mounting base	Texas Instrument
26	7MT-100	4-20 Ma input modules	Texas Instrument
1	QJ648-AY	Softwar <del>e_R</del> SX-IIS operating system	Standard Engineering
1	6220	Software-basic	Kinetic Systems

# Table 9-4. Hardware Description 3.5-Year Control System



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Qty	Model no.	Description	Manufacturer
1	3970-Z1A	MODCOMP system driver	Kinetic Systems
1	3960-Z1A	System crate controller	Kinetic Systems
1	3992-Z1B	Serial hiway driver	Kinetic Systems
7	1875-D6B	U-Port bit serial cable with return path	Kinetic Systems
6	3952-Z1A	Type L-2 serical crate controller	Kinetic Systems
12	3510-A1A	16 channel scanning A/D converter	Kinetic Systems
2	3110-P1A	C channel, 16-bit D/A converter	Kinetic Systems
9	3080-A1B	8 bit output registar with AC switches	Kinetic Systems
7	3473-A1C	24 bit change-of-state input register	Kinetic Systems
6	3924-F1A	LAM encoder for serial system	Kinetic Systems
5	3125-A1A	4-20 Ma output driver	Kinetic Systems
2	MIK-11/1	LSI controller (PID)	Standard Engineering
2	KEV II	Extended arithmetic option	Standard Engineering
1	5330	5 conductor shielded cable - 2500 ft	Allied

# Table 9-5. Hardware Description CAMAC Control System

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Table	9-6.	Plant	Controller	Comparison
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	216,415 Programmable Controller	304,675 CAMAC
Cost:		
Hardware:	l (unit of currency)	1.8 (units of currency)
Software:	1000 mhrs	2360 mhrs
Expandability limits:	256 descrete I/O functions	64 crates — each
	256 analog inputs	crate handlers 24 single or
	256 analog outputs	multidevice functions
	8 PID three mode controllers	
	(Small system-limited growth expansion)	
Programmability:	Simple high level language	Requires professional
	Non-programmer capability	Programmer
Modularity:	Single and multidevice packaging	Single and multidevice packaging can
Peripherals:	Requires stand-alone host computer	adapt printing plotting and mass
	for printing, plotting, and mass storage	Storage is stand-alone system
Hardware fail-over:	No hardware redundance available	Fail over hardware capability between and within crates: dual transmission link available
Distributed		
control:	Serial data hiway	Serial data hiway
	Max. throughput ≈ 120 chan/sec	Max throughput $\approx 16,000$ ch/sec
	2500 ft maximum data highway length	No maximum data hiway
		Length restrictions

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## Section 10 HITEC/HTS STATE-OF-THE-ART AND APPLICATIONS

#### 10.1 HITEC/HTS CHARACTERISTICS

Hitec and HTS (draw salt) have been used for years in industrial situations as a heat transfer medium. Characteristics of the nitrate based salts are discussed below.

#### 10.1.1 Hitec Properties

Hitec was developed in the 1930's by DuPont Chemical Company. It is a white granular solid which turns yellow when melted. It is a eutectic mixture of potassium nitrate 53%, sodium nitrite 40%, and sodium nitrate 7%. Properties of the material are given in Table 10-1.

Hitec is used because it has a relatively low melting point, high heat transfer coefficient, thermal stability, and low cost. It is nonfouling, nonflammable, nonexplosive and evolves no toxic vapors under normal conditions. It has a low degree of corrosivity and can be used with carbon steel up to 454°C (850°F). Maximum operating temperature is 538°C (1,000°F). The vapor pressure below 450°C is essentially zero.

Although very stable up to high temperatures, the salt undergoes a slow thermal breakdown of the nitrite to nitrate:

5  $NaNO_2 \rightarrow 3NaNO_3 + Na_2O + N_2$ 

In contact with air, the nitrite is slowly oxidized by atmospheric oxygen:

 $2NaNO_2 + O_2 - 2NaNO_3$ 

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Carbon dioxide can be absorbed to form carbonates and water to form alkali metal hydroxides. These reactions tend to raise the freezing point and can be eliminated by using a nitrogen cover gas.

## 10.1.2 HTS (Draw Salt)

Draw salt is a binary eutectic consisting of potassium nitrate 54% and sodium nitrate 46%. It possesses most of the properties of Hitec but melts at a higher temperature (220°C) and is less expensive as shown in Table 10-1. It appears to be more stable, especially at the maximum operating temperature of 593°C (1,100°F). The major decomposition reactions are:

 $NaNO_3 = 2 NaNO_2 + O_2$ and  $KNO_3 = 2 KNO_2 + O_2$ 

Table 10-1 Physical Properties of HITEC and HTS (Draw Salt)

Property	Hitec	HTS
Composition, wt %	40NaNO <sub>2</sub> , 7NaNO <sub>3</sub> , 53KNO <sub>3</sub>	46NaNO <sub>3</sub> , 54KNO <sub>3</sub>
Melting point, °C (°F)	142 (288)	220 (428)
Density, kg/m <sup>3</sup> At 260°C AT 540°C	1,890 1,680	1,921 1,733
Specific heat, J/kg-°K	1,560	1,560
Viscosity, Pa/sec At 260°C At 540°C	0.0043 0.0012	0.0043 0.0011
Thermal conductivity, W/m-°K	0.61	0.57
Heat transfer coefficient, W/m <sup>2</sup> -°K	4,600-16,700	4,300-15,600
Latent Heat of Fusion, J/gm	81.4	81.4
Cost (approx) \$/kg	0.77	0.53

## 10.2 HITEC/HTS APPLICATIONS

Heat transfer salt has been safely used in numerous applications in the chemical and petroleum process industries as well as metallurgical metal treatment



fields. A number of companies were contacted which are familiar with the handling of molten salt. They included companies which utilize molten salt in various processes, those that supply the material and also companies which design and construct total heat transfer salt systems. Topics related to molten salt handling which were discussed included operating experience, equipment, maintenance, safety, salt stability, and corrosion.

## 10.2.1 Operating Experience

In the majority of operations, Hitec is used as a heat recovery fluid for fixed bed reactors. Hitec is pumped from a salt tank, through the reactor where it picks up heat from the exothermic reaction, and to a steam generator to be cooled. From here it flows back to the tank to be recycled. Some companies have been using salt since 1940 in this type operation. Many steam generators have been built which utilize molten salt, some of which have been operating for over 10 years.

#### 10.2.2 Equipment

Pumps used for molten salt applications are of the submerged vertical-centrifugal design. Most frequently the cantilever type is used to that contact is avoided between the molten salt and pump bearings or packing. Submerged bearings are also used extensively with no problems. Standard piping and valves (with asbestos gaskets) are used. Joints are welded where possible and ring joint flanges are used otherwise. Most systems utilize steam trace heating and calcium silicate insulation on all salt lines. Instrumentation usually consists of temperature transducers installed in thermowells.

#### 10.2.3 Maintenance

In all cases maintenance of salt systems is minimal. At most, the submerged bearing pumps may have to be pulled once a year for repacking. This, however, is usually more a result of using steam as a cover gas rather than a salt related problem.

10-3

## 10.2.4 Safety

Other than a "burnthrough" caused by overheating salt to 650°C (1,202°F), no unusual safety problems were reported. The only safety procedures involved minimizing leaks and organic materials of construction since the hot salt will support combustion. In an industrial facility which was visited, a leaking joint was left unrepaired for several weeks and still appeared to present no real concern. All other companies appeared to have no leakage problems at all.

## 10.2.5 Salt Stability

As discussed in Section 10.1, Hitec is subject to various reactions at operating temperatures. Most industrial systems use steam as a cover gas since it is readily available. This leads to the formation of sodium hydroxide from the decomposition of sodium nitrite. This results in increased corrosion and melting points. In some situations, the melting point is monitored weekly and fresh salt is added if the melting point exceeds 180°C. This does not occur rapidly and one system required no makeup between 1969 and 1972. Other companies use no cover gas at all and arbitrarily add salt from "time to time." Some never replace salt in their systems. Using nitroyen as a cover gas should give maximum control of side reactions resulting in minimal salt replacement.

## 10.2.6 Corrosion

The majority of chemical and petroleum process industries operate below 450°C (842°F) and use carbon steel exclusively. They all report no unusual corrosion problems. The literature indicates that corrosion rates on carbon steel are on the order of 0.1 to 0.4 mm/yr between 450°C and 538°C.

Some systems have operated up to 594°C (1100°F) using stainless 316.

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#### APPENDIX A

#### PHASE II AND PHASE III COST ESTIMATES

Appendix A covers the cost estimates and associated cost methodology and rationale developed for the three Phase II and III program schedule alternatives of Engineering Experiment Number One. The resulting estimates are encouraging and certainly support a projection of economic viability for Small Central Receiver Systems. The analysis has been supported through the development of a cost data package on important material and equipment unit costs, fabrication and installation hours, cost sensitivities, and direct support, efficiency and overhead factors. Following an overview of the cost results, groundrules and costing approach, further details are provided on Phase II design costs, and Phase III costs by subsystem. This is followed by a section listing the CBS, applied costing factors and list of material unit costs.

#### A.1 Overview

Costs developed for the three programs, although conceptual, have been carried to a fairly credible depth of analysis, especially for Phase III.

<u>Costing Results</u> - Results for the three potential Engineering Experiment I programs are summarized below in 1978 dollars:

	Pr	ogram (\$x10 <sup>6</sup>	)
Cost Element	<u>3.5 Year</u>	4.5 Year	<u>6.5 Year</u>
Design and Development (Phase II)	\$2.2	\$3.8	\$6.6
Investment (Phase III)			
Collector	\$2.9	\$2.1	\$1.8
Power Conversion	\$1.6	\$1.6	\$1.4
Energy Transport	\$.2	\$.2	\$.1
Energy Storage	\$.5	\$.4	\$.2
Control	\$.4	\$.4	\$.5
Balance* Total Investment	<u>\$2.7</u> \$8.3	<u>\$2.8</u> \$7.5	<u>\$2.8</u> \$6,8
Test & Evaluation (Phase III) Contingency on Phase III Total EEI	\$.7 <u>\$2.3</u> \$13.5	\$.6 <u>\$2.0</u> \$13.9	\$.7 <u>\$1.9</u> \$16.0

\*Indirects, Distributables, Land & Yard, and Miscellaneous Equipment

Design and development costs which include preliminary and detail design, subsystem test hardware and experimental tests increase rapidly as the program schedule is extended. This reflects the introduction of more advanced hardware requiring development and the longer time allowed for development and testing. This increase is countered in part by reduced hardware costs mainly because there are fewer heliostats and a smaller receiver required due to the increased efficiencies of the more advanced systems. Costs for power conversion and energy transport and storage also go down somewhat for the 6-1/2 year program reflecting the introduction of the radial outflow turbine and the dual media storage concept. Test and evaluation costs which appear fairly steady are actually the net of increased technical support costs and reduced costs for operations, maintenance and follow-on spares on the advanced programs. Finally, contingency is applied at 25 percent of overall Phase III costs and varies with the hardware costs.

<u>Groundrules and Approach</u> - The following major groundrules and assumptions have been considered during cost analysis:

- Minimum development and schedule risk in accordance with hardware selection.
- 2. Costs in 1978 dollars and bid rates.
- 3. Maximum use of prior study data base for solar hardware costs and development of factors for common system cost elements.
- Manufactured equipment costing based on detail estimating procedures and factors.
- 5. Maximum use of the industrial base for purchased parts and specialized forming operations.
- 6. Use of vendor quotes for conventional equipment.
- 7. Development program manufacturing support practice and associated factors.
- 8. Equal duration procurement, manufacturing, installation, checkout, test and evaluation for all three Phase III programs.
- 9. Maintenance cost based on failure rates and FMEA's.
- 10. Continuous manning of operations 24 hours a day and 7 days a week.
- 11. Nominal 8 percent fee across the board plus integrator's fee.

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The translation of these guidelines to a costing approach varies for each subsystem depending on its relative cost value and the nature of available engineering, manufacturing, logistics and cost data, as well as the characteristics of the responsible contractor's business. Of the most costly subsystems, the collector is the least "tried", but the heliostat, which accounts for almost 90 percent of collector cost, has been the subject of considerable prior government study so that expected costs are well documented. Thus, the major share of collector cost analysis has been directed toward costing the receiver unit, the tower and minor heliostat modifications. These cost elements are state-of-the-art designs and employ common materials, purchase parts and manufacturing techniques for which vendor quotes and estimating standards and factors are readily available.

The next most important hardware cost category, power conversion, as well as the less costly energy storage, energy transport and plant control subsystem, in the main, utilize off-the-shelf equipment. The equipment is assembled and installed in typical power plant or process plant configurations. This has allowed the use of equipment quotes, standards, construction estimating manuals and Stearns-Roger experience factors to arrive at costs with reasonable confidence.

Much of the "other" category contains elements that may be estimated using experience factors also compiled by Stearns-Roger. The remainder of this category is made up of miscellaneous equipment and initial spare parts for which vendor quotes are available and Solar Integrator costs which have been determined based on manloads.

Design and development and test and evaluation costs are based on engineering judgement concerning the impact of requirements with the exception of the direct operation and maintenance (O&M) of the experimental plant. Plant operation costs are based on operator/engineer and technician manloading. Maintenance costs are based on failure rates, the failure modes and effects analysis, the implied maintenance actions, available maintenance equipment, and the projected initial spares inventory.

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Further details concerning the cost estimates and the costing approach are provided in the subsections that follow, starting with Phase II costs.

#### A.2 Phase II Design and Development Costs

The following table provides further breakout of the projected Phase II design and development costs:

	Program (\$x10~)			
<u>Cost Element</u>	<u>3.5 Year</u>	4.5 Year	<u>6.5 Year</u>	
Design	\$2.20	\$2.45	\$3.45	
Development/Test	-	\$1.35	\$3.15	

Due to the reduction in contractual scope, Phase II estimates have been developed by MDAC Project Engineering considering the available schedule and expected development requirements.

The design cost projections allow for system integration, heliostat design modifications, A&E effort, and design of all subsystems. The 3 1/2 year program employs equipment which is standard or will have been tested under programs. The one exception is the receiver, but the design is very conservative and well within the state-of-the-art. As a result, no development/ test costs are indicated for the 3 1/2 year program.

The 4 1/2 and 6 1/2 year programs do include some development and testing. The 4 1/2 year program utilizes the extended schedule in order to test control automation techniques and to test a prototype receiver at the CRTF and verify the state-of-the-art technology utilized. The 6 1/2 year program, in addition to extending the receiver technology and control automation, incorporates the dual media storage concept and the Radial Outflow Turbine. Development/test costs for the turbine include the fabrication and test of a prototype turbine while thermal storage testing is mainly concerned with material compatibility verification for the dual media.

## A.3 Phase III Hardware and Test and Evaluation Costs

Tables Al , A2 and A3 present Phase III costs in the E-2 tables format specified by JPL. As requested, cost data are provided in 1978 dollars. Although costs have been accumulated in accordance with the JPL cost breakdown guide-

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# Table A1. 3.5 Year Program (E-2 Format)

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Table A2. 4.5 Year Program (E-2 Forma	Tab	e A2. 4.5 Year	Program	(E-2	Format	)
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	4. DRIVE MECHANISM AND LOCAL CONTROL		127(58)	826	
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	3. HEAT EXCHANGER/BOILERS/CONDENSERS			296	
	4. CONTROL VALVES AND LOCAL CONTROL ELEMENTS AND PIPING			103	
	S. PUMPS AND FAMS			43	
	5. HEAT REACTION ECONIMENT 7. SUBSYSTEM NULDINGS AND FACILITIES			87	
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	10. MISCELLANEOUS (EXPLAIN)				
	11. FELD INSTALLATION			329	
	12. FRED SUPERVISION			18	
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	4. FLUID PUMPS AND DRIVES			40	
	5. SITE REPARATION, FOUNDATIONS, AND PIPING SUPPORT ELEMENTS			3	
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	S. FIELD INSTALLATION				
	4. FIELD SUPERVISION				
	7. SUBSYSTEM CHECKOUT/ADJUSTMENT			1	
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	2. HEAT EXCHANGERS/BOILERS			170	
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Table A2. 4.5 Year Program (E-2
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1. FIELD INSTALLATION			206	
10. SUSSESTIM CHECKDUT/ADJUSTMENT		·····	13	
POWER CONVERSION SUBSYSTEM				1597
1. HATENGINE			400	
2. GENERATOR 3. WAT EXCHANCER AND REACONDENSES			34	
4. CONTROL VALVES AND LOCAL CONTROL ELEMENTS AND PIPING			290	
S. MANPS AND FANS			43	an - Anna Anna
4. HEAT REJECTION EDUMAENT			87	Shine da ana ang ang ang ang ang ang ang ang an
7. SUBSTSTEM BUILDINGS AND PAGELERS E. SWITCH GEAR, TRANSFORMERS, em.			182	
T. CONCEPT FICURIAR (EXPLAIN)				
ID. MISCELLANCOUS (EXPLAIN)		·		
11. FRED INSTALLATION			329	
12. FILD SITERYSION			18	
ENERGY TRANSPORT SUBSYSTEM	000000000000000000000000000000000000000	Wilson Data		174
THERMAL			. Sector redecides	
1. PHING		5 MILT.	10	
3. CONTROL VALVES AND LOCAL CONTROL ELEMENTS			10	in the state of th
4. FLUID PUMPS AND DRIVES	Persident Andreas		40	
S. SITE REPARATION, FOUNDATIONS, AND PITING SUPPORT ELEMENTS			3	
4- MISCELLAENQUS (EXPLAIN)	. Fisis and the state			ha rishiki kura si
3. FIELD SUPERVISION			39	
1. SUSYSTEM CHICKOUT/ADJUSTMENT			1	
ELECTRICAL				
1. WRING (MATERIAL, SUTORTS, TRENCHES, and)			1	
2. UTILIT INTERACE SUBSTAIRS			2	
4. MISCELLANEOUS (EXPEAIN)				
5. FILLD INSTALLATION				
4. FIELD SUPERVISION			Į	
I SOBSTSTEM CRECKCOT/ADJUSTMENT				
1. TANKS, INSULATION, STORAGE MEDIUM			170	417
2. KEAS EXCHANGERS/BOILERS				
J. HEAT TRANSFER FLUID	log gettin den kom		133	
4. IDEAL CONTROL FIENDING			<u> </u>	
4. SITE PREPARATION/FOUNDATION	the state of the s		<u>i 11</u>	
7. MISCELLANEOUS (EXPLAIN)				
			91	
10. SURVETIM CHECKOLIT/ADJUSTMENT				
CONTROL SUBSYSTEM				369
1. CONTROL SOFTWARE			42	
2. PROCESSORI/COMPUTERS			82	
4. SUBSYSTEM OPERATION CONTEND ELEMENTS			4 41	
5. CONTROL LINES TO SURSYSTEMS AND PLANT CONTROL ELEMENTS	5. 10014-0499 (S.A.)		3	
4. KALDINGS AND FACILITIES TO HOUSE EQUIPMENT	ti di si	All WARDER IN CALL		
7. MICHANOUS (IXPAN) - SUSTAINING ENGR			96	
7. FIELD SUPERVISION			<u>영 #1</u> 역 14	
10. SUSSYSTEM CHECKOUT/ADJUSTMENT		·	45	XXXXXXX
DETAIL DESIGN	an attack to be all the	********		
PLANT CONSTRUCTION MANAGEMENT		ind in an chiefe	n training an an the state of the	410
SPECIAL FEATURES		14779233996	e en aggi grand i feddi. Laightean fe	2756
OTHER (SUILDINGS AND OTHER UTILITIES TO SUPPORT SYSTEM FUNCTIONS, etc.)		1.1.1.	a en la constante en en	264
TESTING AND EVALUATION			a i shina a satata a	639
	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	I-restantion that the second		10160

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Table A3. 6.5 Year Program (E-2	Format)	1
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	UTICIENCY	WEIGHTS	ESTIMATE 1778 SE		
ITEM	*	lie (ke)	COMPONENTS	SUBTOTALS	
1. SITE REPARATION/TOUNDATION		1749(703)	114	1823	
2. STEUCTURAL RAME WORK		52(23)	45		
3. REFLECTOR SURFACE AND SUPPORT		428(194)	301		
4. DEIVE MECHANISM AND LOCAL CONTROL		104(47)	673	e. Completente	
S. ELCEVER AND SUPPORT			318		
T MICH AND A REAL SUSTAINING ENGS			101		
6. FIELD INSTALLATION			186		
T. FIELD SUPERVISION			12	and person and	
10. SUBSYSTEM CHECKOUT/ADJUSTMENT			11		
POWER CONVERSION SUBSYSTEM				1377	
			79		
3. HEAT EXCHANGER/BOILERS/CONDENSES			275		
4. CONTROL VALVES AND LOCAL CONTROL ELEMENTS AND PIPING			114		
S. PUMPS AND FANS			91		
6. HEAT REJECTION EQUIPMENT			77		
7. SUBSTSTEM BUILDINGS AND PACILITES			214		
1. CONCEPT HELILIAR (EXPLAIN)			88		
10. MISCELLANEOUS (EXPLAIN)					
11. FIELD INSTALLATION			366		
12. FIELD SUPERVISION			20		
13. SUBSYSTEM CHECKOUT/ADJUSTMENT			8		
THERMAL				141	
1. FING			6		
2. INSULATION			÷ 9		
3. CONTROL VALVES AND LOCAL CONTROL ELEMENTS			64		
4. FLUID PUMPS AND DRIVES			24		
A. MICELLARMON, POURDATIONS, AND FINITE DEFICIT ELEMENTS			··· 3		
7. FIELD INSTALLATION	Brown (Brown)		33		
8. FIELD SUPERVISION			1		
*. SUBSYSTEM CHECKOUT/ADJUSTMENT			1		
ILICTOCAL					
1. WHEING (MATERIAL, SUPPORTS, TEENCHES, ML.)					
3. LOCAL CONTROL ELEMENTS					
4. MISCELLANE OUS (EXPLAIN)					
5. FIELD INSTALLATION			*		
4. FIELD SUPERVISION	8. (29949046) (1994)				
7. SUBSYSTEM CHECKOUT/ADJUSTMENT					
1. TAMES, INUS ATION, STORAGE MEDINA			120	249	
2. HEAT EXCHANGERS/BOILERS					
3. HEAT TRANSPER FLUID			69		
4. PUMPS, VALVES, FIFING, and			2		
S. LOCAL CONTROL ELEMENTS					
4. SITE PEPARATION/POUNDATION			4		
8. FILLD INSTALLATION			33		
P. FIELD SUPERVISION	part in the second second		1		
10. SURSYSTEM CHECKOUT/ADJUSTMENT			1		
CONTROL SUBSYSTEM				478	
1. CONTROL SOFTWARE			87		
2. SYSTEM CONTROL ELEMENTS FOR PLANT OPERATION			6		
4. SUBSYSTEM OPERATION CONTROL ELEMENTS	c ( ) specification		51		
5. CONTROL LINES TO SUBSYSTEMS AND PLANT CONTROL ELEMENTS			3		
4. BUILDINGS AND FACILITIES TO HOUSE EQUIPMENT	and the standard				
7. MISCELLANEOUS (EXPLAIN) - SUSTAINING ENGR			149	<ul> <li></li></ul>	
E. FRUI INSTALLATION 9. EIED SUMPHISION			41		
10. SUBSYSTEM CHECKOUT/ADJUSTMENT	entrepris de la terretaria. Referènció de la terretaria de la terretari	-	48	*******	
DETAIL DESIGN	1111111111111111111111111				
PLANT CONSTRUCTION MANAGEMENT	Ender States and the		🗰 te seri gan selêtî de	360	
SPECIAL FEATURES	5.599.55 <b>5</b> 566193		wy Proceeding Maria	2599	
RELATED THEMS			wa santa 2011, ningina a wa santa sata	1333	
OTHER (JUILDINGS AND OTHER UTILITIES TO SUPPORT S'STEM FUNCTIONS, etc.)			and the second s	264	
	1.144.00.0000			9320	

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lines, the alignment of costs associated with a central receiver system within the E-2 format may be somewhat confusing. For example, the Collector Site Preparation/Foundation category includes costs for not only the heliostat foundations, but also the tower base, piers, beams and deadmen. On the other hand, the tower structure is covered under Receiver and Support rather than item 2, structural framework which contains only costs for the heliostat pedestals. Subsection A.4 provides a breakdown of the cost elements contained in each of the E-2 line items as well as a reconcilliation to the DOE/Sandia Central Receiver cost breakdown structure.

The costs shown in the tables reflect the design configurations and manufacturing and logistics scenarios discussed in the main body of this volume. However, Table A4 has been included as a summary of the cost-driving technical characteristics. The remainder of this subsection provides further information by subsystem that may be helpful in understanding the costs shown in the tables.

#### A.3.1 Collector Subsystem

The Collector Subsystem contains the Receiver, Tower and Heliostat costs. Heliostat costs assume production in existing facilities with some modifications to the reflector and electronics. Costs are based on published DOE cost information which has been perturbed to add or delete tooling parts and labor in accordance with the altered design and production scenario. The production scenario assumes provision of mod kits which included the necessary spares, flanges and electronic components. Although a special reflector assembly area is necessary to handle the altered mirror curvature, cant angles and split beam (Barstow configuration), modifications to the electronics may be easily handled within the existing lines.

The Receiver cost estimates also assume use of existing production facilities. The absorber is vendor wound and welded and delivered to Rocketdyne's facilities in two sections. There, the sections are welded together and to the apex manifold and to the ancillary piping and manifolds. After a flow check, the absorber is shipped along with the preassembled support structure and housing. At the site, the absorber is assembled in the structure/housing, insulation is added and the whole assembly hoisted to the top of the tower with a mobile

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## COST DRIVING CHARACTERISTICS

			PROGRAMS	
	Item	3-1/2 Year	4-1/2 Year	<u>6-1/2 Year</u>
	Heliostats	217 units	. 171 units	. 139 units
		45 m <sup>2</sup>	. 49 m <sup>2</sup>	。 49 m <sup>2</sup>
R.		Barstow production	. 2nd Generation Prod.	<ul> <li>2nd Generation Prod.</li> </ul>
	Tower	, 39 m high	. Same	. Same
	Receiver	. Guyed Steel Truss Stru.	. 26.1 m <sup>2</sup> SA	22.8 m <sup>2</sup> SA
		. 28.9 m <sup>2</sup> SA	. Same	。 Same
		. Spiral Partial Cavity	. 316 CRES	. Incollay 800
		. 316 CRES Tubes	. 510°C 0.T.	. 538°C 0.T.
		, 454°C Outlet Temp.	. Same	. Same
		, Vendor wound tubes	• Same	. Same
	Energy Storage	. Two tank SS	. Two Tank SS	. Duel Media
	and Transport	. Hitec	. Hitec	. HTS
Þ		. 17.1 MWHt Capacity	. 14.9 MWHt	. 12.5 MWHt
ΰ.		. 454°C Max. Temp.	• 510°C	• 538°C
		, Vertical Submerged Pumps	. Same as 3-1/2	Horizontal in-line pumps
	Power Conversion	. Axial Marine Turbine	. Axial Marine Turbine	. Radial Outflow Turbine
		. 1 MWe nominal output	<ul> <li>Same</li> </ul>	. Same
		. Inlet 427°C, 62 Bar	. 482°C, 103 Bar	. 510°C, 121 Bar
		. Standard ancillary equipment & piping	. Same	. Same
		Fully Housed	. Same	" Same
	Plant Control	. Standard Equipment	. Same	. Same
		. Automatic Mode	. +Automatic loop warmup	+Automated turbine start up
		Transitions	and shut down	and shut down and other operations
	Land & Yard	8 acres	. 6.6 acres	. 5.5 acres
	Operations	. LRUs, 95% repairable	• Same	. Same
	•	. Special wash equipment	• Same	• Same

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crane. Costs were developed by Rocketdyne based on conceptual drawings, engineering variable estimates, and a preliminary bill of materials using vendor quotes, category prices, and labor standards, pricing factors and 1978 bid rates. Field costs have been developed from resource loads of men, materials and installation equipment.

The tower costs have been developed by Stearns-Roger and include an elevator, aircraft strobe lights, a platform at the top and a caged ladder. However, the elevator cost is included under Related Items since it was selected because of the experimental nature of the plant. The structure is subassembled and shipped in six sections which are assembled along with the ancillary equipment using the mobile crane. Stearns-Roger has based their estimates on conceptual level parts and material take-offs, and have employed concrete and steel experience factors, vendor quotes and categories, and 1978 trade labor rates to arrive at costs.

## A.3.2 Power Conversion

The power conversion subsystem costs have been estimated by Stearns-Roger for all but the turbine plant equipment based on vendor quotes for the mechanical, electrical and HFAC equipment and on experience factors for painting, instruments and concrete work. Piping is based on estimated quantities while the turbine/control building costs are based on volume and type of construction. The trubine equipment is based on vendor quotes solicited directly by MDAC.

#### A.3.3 Energy Storage and Energy Transport

Although presented as separate subsystem costs on the tables, energy storage and energy transport are very closely associated. These subsystems will be subcontracted and, in fact, the cost quotation from vendors that supply molton salt handling systems do not identify separate storage and transport elements. The cost breakout has been obtained by an independent MDAC analysis employing individual vendor equipment quotes and construction estimating manuals such as Richardson's, Mean's, Dodge Guide, and the National Construction Estimator. The results of the MDAC analysis were compared to the overall subsystem quotes and the SRE actuals for the Dual Media concept in order to verify cost breakdown. The costed scenario calls for factory constructed tanks

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which are shipped along with the associated pumps, valves and prefabricated insulation sections to the field site for final installation.

#### A.3.4 Control Subsystem

The plant control manufacturing scenario calls for the use of off-the-shelf equipment which is shipped to MDAC facilities in Huntington Beach. There it is assembled, integrated with the software, and checked out using MDAC's Systems Integration Laboratory. The equipment is then disassembled, shipped to site, reassembled and finally checked out. The costs are based on vendor quotes for the equipment lists and on manloading of engineers and technicians according to the schedules and tasks. MDAC-Huntington Beach labor rates and pricing factors have been applied in order to complete the costs.

#### A.3.5 Other Costs

A breakdown of other costs along with and indication of estimating methodology is provided in Table A5. As indicated, a large share of these costs are based on experience factors. These factors have been supplied by Stearns-Roger. Note that the costs covered by the distributables are developed for Balance of Plant (BOP) only. Field distributables for the solar related equipment are costed and accounted for under the individual subsystems.

## A.3.6 Test and Evaluation

Table A6 presents a summary of test and evaluation costs. The costs are summarized by Major Hardware Functions. The control subsystem is included within Electric Plant Equipment while the Operations and Maintenance category contains those elements that can't be specifically identified with a hardware element.

The spares and repair parts costs are relatively small because the test operations last only one year and there is a large complement of initial spares. By far, the largest portion of the cost falls under the operations category. Well over half of this cost is for technical support during the test operations period. The remainder is for assuring plant operating coverage of at least two operator/engineers at all times, 7 days per week and 24 hours per day during the one year experimental test operations project.



TABLE A5 ADDITIONAL COST BREAKDONN

A STREET CONTRACTOR CONTRACTOR

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	$\frac{\text{PROGRAM}(\$ \times 10^3)}{1000}$	
Cost Element	<u>3.5 Year</u> <u>4.5 Year</u> <u>6.5 Year</u>	Method of Costing
Plant Construction Manager	\$ 503 \$ 410 \$ 360	Factor on total costs
Land and Rights Grading & Gen. Excav. Roads, fences & lighting Sewer System Yard and Storm drain Field office personnel & service Insurance Temporary Facilities Temporary Equipment Construction Services Initial Spares	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	Provided at \$5000/acre Factor of PDR " " Factor on BOP Field Labor " " " Fauipment quotes and Spanos Palicy
A&E construction support Startup and C/O Contingency Subtotal	$\begin{array}{cccccccccccccccccccccccccccccccccccc$	Factor on Total Costs Manload Factor on Grand Total
Related Items Solar Integrator Special Heliostat SCR Production Equipment Elevator Subtotal	\$ 934 \$ 900 \$ 884 221 400 365 <u>84 84 84</u> <u>\$ 1239 \$ 1383 \$ 1333</u>	Manloads Conceptual Equipment Estimates Quote
Other Transport & lifting Eq. Communication Eq. Utilities & Fixtures Subtotal	$\begin{array}{cccccccccccccccccccccccccccccccccccc$	Conceptual Equipment Estimates Factor of PDR Factor of PDR

TABLE A6 TEST AND EVALUATION COSTS (DOLLARS IN THOUSANDS)

#### 5.5 YLAR PROGRAM

#### 12.30.51.

WBS NUMBER AND TITLE

+--UPERATIONS AND MAINTENANCE-----+ +---NUN-LABOR----+ +---LABOR----+ SPARES REP PT OTHER CORRECT SCHED TOTAL

GRAND TOTAL	\$6.	\$25.	\$ 17.	\$ 28. 5	\$ 5 9 0.	\$665.
SITE, STRUC, MISC	Ε Ο.	с.	0.	6.	14.	20.
TURBINE PLT EQ	1.	5.	1.	5.	18.	29.
ELECTRIC PLT EQ	Ο.	1.	6.	1.	Ο.	9.
HELIOSTAT EQUIP	4.	10.	1.	14.	21.	50.
RECEIVER EQ	1.	Χ.	ί.	1.	1.	11.
THERMAL STRG EQ	ο.	Ο.	0.	1.	3.	5.
JISTRIB & INDIR	Ο.	υ.	0.	Ο.	Ο.	Ú.
OPERATIONSMAINT	Ο.	Ο.	7.	Ũ.	534.	541.

4.5 YEAR PROGRAM

12.18.13.

W35 NUMBER AND TITLE

+--OPERATIONS AND MAINTENANCE-----+ +---NON-LABOR----+ SPARES REP PT OTHER CORRECT SCHED TOTAL

GRAND TOTAL	\$ 5.	\$ 19. \$	11.	\$ 19.	\$585.	\$ 539.
SITE, STRUC, MISC	ε Ο.	Ο.	Ο.	5.	14.	19.
TURBINE PLT EO	1.	8.	1.	5.	18.	32.
ELECTRIC PLT EQ	0.	1.	1.	1.	Ο.	3.
HELIOSTAT EQUIP	2.	2.	1.	6.	17.	28.
RECEIVER EQ	1.	8.	Ο.	1,	1.	11.
THERMAL STRG EQ	Ο.	G.	Ο.	1.	3.	5.
DISTRIB & INDIR	Û.	Ο.	Ο.	υ.	0.	ú.
OPERATIONSMAINT	Ο.	Ο.	7.	Ο.	534.	541.

6.5 YEAR PROGRAM

W35 NUMBER AND TITLE

12.10.10.

+--OPERATIONS AND MAINTENANCE-----+ +---NON-LASOR----+ +---LABOR----+ SPARES REP PT OTHER CORRECT SCHED TOTAL

GRAND TOTAL	\$4.	\$22.	\$17.	\$ 19.	\$635.	\$ 695.
SITE, STRUC, MISC	Ε Ο.	0.	Ο.	5.	14.	19.
TURBINE PLT EQ	2.	15.	1.	5.	20.	43.
ELECTRIC PLT EQ	Ο.	1.	7.	1.	Ο.	9.
HELIOSTAT FOUIP	2.	2.	1.	5.	14.	23.
RECEIVER EQ	1.	4 -	Ο.	1.	1.	7.
THERMAL STRG EQ	σ.	Ο.	Ο.	1.	3.	. 5 -
DISTRIB & INDIR	0.	Ο.	Ο.	Ο.	Ο.	ο.
OPERATIONSMAINT	Ο.	Ο.	7.	Ο.	534.	591.

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#### TABLE A6 TEST AND EVALUATION COSTS (DOLLARS IN THOUSANDS)

#### 12.30.51.

WBS NUMBER AND TITLE

3.5 YEAR PROGRAM

GRAND TOTAL	\$6.	\$25.	\$17.	\$ 28 .	\$ 5 9 0.	\$665.
SITE, STRUC, MISC	ε Ο.	C.	0.	6.	14.	20.
TURBÍNE PLÍ EQ	1.	5.	1_	5.	18.	29.
ELECTRIC PLT EQ	θ.	1.	6.	1.	0.	9.
HELIOSTAT EQUIP	4.	10.	1.	14.	21.	50.
RECEIVER EQ	1.	δ.	Ú	1.	1.	11.
THERMAL STRG EQ	θ.	Ο.	0.	1.	3.	5.
JISTRIB & INDIR	Ο.	υ.	٥.	Ο.	Ο.	Û.
OPERATIONSMAINT	0.	۵.	7 -	Ū.	534.	541.

4.5 YEAR PROGRAM

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12.18.13.

W35 NUMBER AND TITLE

+--OPERATIONS AND MAINTENANCE-----+ +---NON-LABOR----+ SPARES REP PT OTHER CORRECT SCHED TOTAL

GRAND TOTAL	\$5.	\$ 19. \$	11.	\$ 19.	\$585.	\$ 639.
SITE, STRUC, MISC	Ε 0.	0.	٥.	5.	14.	19.
TURBINE PLT EO	1.	8.	1.	5.	18.	32.
ELECTRIC PLT ÈQ	0.	1.	1.	1.	0.	3.
HELIOSTAT EOUIP	2.	2.	1.	6.	17.	28.
RECEIVER EQ	1.	8.	0.	1,	1.	11.
THERMAL STRG EQ	Ο.	6.	Ο.	1.	3.	5.
DISTRIS & INDIR	Ο.	Ο.	Ο.	ð.	0.	ύ.
OPERATIONSMAINT	0.	Ο.	7.	Ο.	534.	541.

6.5 YEAR PROGRAM

12.10.10.

WES NUMBER AND TITLE

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GRAND TOTAL	\$4.	\$22.	\$17.	\$ 19.	\$635.	\$ 696.
SITE,STRUC,MISC	Ε Ο.	Ο.	Ο.	5.	14.	19.
TURBÍNE PLT EQ	2.	15.	1.	5.	20.	43.
ELECTRIC PLT EO	Ο.	1.	7.	1.	0.	9.
HELIOSTAT FOULP	2 .	2.	1.	5.	14.	23.
RECEIVER EQ	1.	4.	θ.	1.	1.	7.
THERMAL STRG EO	С.	Ο.	Ο.	1.	3.	. 5 -
DISTRIB & INDIR	0.	0.	Ο.	Ο.	0.	0.
OPERATIONSMAINT	Ο.	Ο.	7.	Ο.	534.	591.

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#### A.4 Supporting Details

This section contains a more detailed listing of the cost breakdown structure (CBS) along with a reconcilliation to the DOE/Sandia Advanced Programs Central Receiver CBS. This is followed with the tables of Unit Material Costs and a table of Applied Costing Factors.

### A.4.1 The Cost Breakdown Structure

Table A7 provides further insight concerning the cost elements that are costed under each line item of Table E-2. In many cases line items shown in Table A7 actually have been costed at a lower level. Table A8, which follows, provide a further depth concerning the inclusions under the Table E-2 categories.

Table A8 shows the DOE/Sandia Cent: al Receiver CBS employed for Advanced Programs. This chart of accounts is the CBS actually employed in accounting for Phase III EEI costs for reasons of costing efficiency because the cost data base, experience factors, estimators, and subcontractors have related most directly, in the past, to this CBS for a Central Receiver System. This chart is arranged with the DOE/Sandia CBS numbers and indentured titles on the left and the Table E-2 acccount number in the right-hand column. A given cost is accumulated and carried over to the E-2 accounts shown in Table A7 wherever an E-2 account number appears opposite a line item in the DOE/Sandia CBS. However, the carried over cost may actually have been developed at lower levels in the indenture. An example of this is provided by the Heliostat Array Controller. Here, the cost is carried over to the E2 format as one line item, numbered 0502, but has been developed as the sum of a long list of equipment costs listed under the DOE/Sandia CBS number 4305010101 which corresponds to E-2 number 0502.

#### A.4.2 Material Unit Cost Tables

Tables A9 to All provide the list of unit material costs applied during the study. The costs indicated are in 1978 dollars and represent the vendor prices before factors for contractor's fee, visibility and rework factors have been applied.

"TABLE E-2" COST BREAKDOWN STRUCTURE

01 COLLECTOR SUBSYSTEM 0101 SITE PREPARATION/FOUNDATION FOUND/SITE PREP (HELIOSTAT) TOWER BASE PIERS AND BEAMS (TOWER) DEADMAN (TOWER) REBAR (TOWER) EXCAVATION (TOWER) BACKFILL (TOWER) 0102 HELIO SUPP STRUCT 0103 REFLECTIVE UNIT REFLECTIVE SURFACE MIRROR BACK STRUCT ASSY & BOARD 0104 DRIVE MECHANISM AND LOCAL CONTROL DRIVE UNIT (COLLECTOR) CONTROL/INSTRMTEQ (COLLECTOR) INSTRUMENTS (RECEIVER) GEARS & BEARINGS (RECEIVER) 0105 RECEIVER AND SUPPORT ABSORBER ASSY & CO TUBE X-RAY INSULATION APEX MANIFOLD TRACE HEATING HOUSING AND STRUCTURE ASSY & CO STRUC STEEL ABSORBER COVER OUTSIDE COVER STEEL FLOOR TOWER SUBASSY ON GRND ERECTION IN AIR STRUCTURAL STELL BRIDGE CABLES CLEVIS AND CLAMPS PI ATFORMS LIGHTING OBSTRUCTION LIGHT SAFETY LADDER LIGHTNING PROTEC

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"TABLE E-2" COST BREAKDOWN STRUCTURE

0106	PIPES, VALVES, FITTINGS (RECEIVER) ASSY & CO DISTRIB MANIFOLD INSULATION-PIPE PIPING VENT VALVE RELIEF VALVE
0107	MISCELLANEOUS <u>HELIOSTAT</u> PROTECT ENCL LIGHTNING PROT PACK & TRANSP DESIGN SUSTAINING ENGR.
0108	FIELD INSTALLATION <u>HELIOSTAT</u> HELIOSTAT SENSOR/CALIB EQ ELECTRICAL/DISTRIB <u>RECEIVER</u> TRANSPORTATION INSTALLATION <u>TOWER</u> SUBASSY ON GRND ERECTION IN AIR TOWER BASE PIERS AND BEAMS DEADMAN REBAR
0109	FIELD SUPPORT/SUPERVISION
0110	ALIGN HELIOSTATS/CHECKOUT
02 0201	POWER CONVERSION SUBSYSTEM TURB & GRBX
0202	ELEC GENERATOR
0203	HEAT EXCHANGERS, 30ILERS, CONDENSERS CONDENSER DEAERATOR HEATER 1 HEATER 2 HEATER 3 HEATER 4 COND STRG TANK WATER TRTMT EQ STEAM GENERATOR



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# "TABLE E-2" COST BREAKDOWN STRUCTURE

0204	CONTROL VALVES, LOCAL CONTROL ELEMENTS & PIPING PIPING INSTR AND CNTRLS
0205	PUMPS AND FANS CIRC WATER PUMP COND EXHAUST PUMP COND TRFR PUMP SG FEED PUMP CONDENSATE PUMP
0206	HEAT REJECTION EQ COOLING TOWER EVAP POND
0207	BUILDINGS AND FACILITIES FOUNDATION SITE PREP STRUCTURE EVAP COOLER ASSY AIR INTAKE LOUVER SUPPLY AIR DUCT EXHT AIR LOUVERS HEAT PUMP 1 DUCTWORK ETC HEAT PUMP 2 HEAT PUMP 3 ELEC UNIT HTR5KW ELEC UNIT HTR7.5W ELEC UNIT HTR7.5W ELEC UNIT HTR7.5W ELEC UNIT HTR7.5W ELEC UNIT HTR7.5W ELEC UNIT HTR7.5W
0208	SWITCH GEAR, TRANSFORMERS, ETC. MCS FEEDER BRKR SIZE 1 FVNR SIZE 2 FVNR MOLDED CS BRKR METAL CLAD SWGR DIESEL GENERATOR AUX XFMR DISTRIB XFMR HELIO XFMR BATTERY CHARGER INVERTER SURGE PROTECTION LIGHTING CABLES TRAYS AND CONDUIT



"TABLE E-2" COST BREAKDOWN STRUCTURE

0211	FIELD INSTALLATION TURB & GRBX COOLING TOWER CIRC WATER PUMP CONDENSER COND EXHAUST PUMP DEAERATOR HEATER 1 HEATER 2 HEATER 3 HEATER 4 COND TRFR PUMP SG FEED PUMP CONDENSATE PUMP COND STRG TANK PIPING INSTR AND CNTRLS WATER TRTMT EQ ELEC PLT LABOR STEAM GENERATOR
0212	FIELD SUPERVISION
0213	SUBSYSTEM CHECKOUT/ADJUSTMENT
03	ENERGY TRANSPORT SUBSYSTEM
0301	ENERGY TRANSPORT - THERMAL <u>PIPING</u> PIPING (RISER, DOWNCOMER) EXPANSION (RISER, DOWNCOMER) PIPING (THER. STRG.)
030102	INSULATION INSULATION (RECEIVER LOOP) TR HEAT/CONTROLLRS (RECEIVER LOOP) INSULATION (ST. GENERATOR LOOP) TR HEAT/CONTROLLRS (ST. GENERATOR LOOP)
030103	CONTROL VALVES AND LOCAL CONTROL ELEMENTS VALVES (RECEIVER FEED) VALVES (ST. GENERATOR FEED)
030104	<u>FLUID PUMPS AND DRIVES</u> PUMPS (RECEIVER FEED) PUMPS (ST. GENERATOR FEED)
030105	SITE PREPARATION, FOUNDATIONS, AND PIPING SUPPORT ELEMENTS SUPPORTS
030107	FIELD INSTALLATION PIPING (RISER, DOWNCOMER) INSULATION (RISER, DOWNCOMER)



#### "TABLE E-2" COST BREAKDOWN STRUCTURE

TR HEAT/CONTROLLRS (RISER, DOWNCOMER) VALVES PUMP PIPING (THERMAL STORAGE) INSULATION (THERMAL STORAGE) TR HEAT/CONTROLLRS VALVES PUMP

- 030108 FIELD SUPERVISION
- 030108 SUBSYSTEM CHECKOUT/ADJUSTMENT
- 04 ENERGY STORAGE SUBSYSTEM 0401 TANKS, INSULATION, STORAGE MEDIUM STAINLESS STL TNK CARBON STL TANK MANIFOLDS INSULATION IMMERSION HTRS NITROGEN & TANKS REGULATOR CHECK VALUE RELIEF VALVE MANIFOLD FILTERS CONTROL VALVE
- 0403 HEAT TRANSFER FLUID HITEC IRON ORE
- 0404 PUMPS, VALVES, PIPING, ETC.
- 0406 SITE PREPARATION/FOUNDATION
- 0408 FIELD INSTALLATION STAINLESS STL TNK CARBON STL TANK IMMERSION HTRS HITEC
- 0409 FIELD SUPERVISION
- 0410 SUBSYSTEM CHECKOUT/ADJUSTMENT

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TABLE A7				
"TABLE	E-2"	COST	BREAKDOWN	STRUCTURE

05 0501	CONTROL SUBSYSTEM CONTROL SOFTWARE SYSTEMS SOFTWARE APPLICATIONS SFTWR DOCUMENTATION SFTWR DEVLPMT/SPEC
0502	PROCESSORS/COMPUTERS <u>HELIO-ARRAY-CONTROLR</u> CLASSIC PROCESSOR BATTERY BACK UP DISK SUBSYST/CNTRL I/O CABLE, 10FT. 150 CPS PRINTER PRINTER CABLE 16 CHNL ASYNG CNTL HS. LINK LINK CABLE INTERNAL TIMER CABLE-INTERPROCSSR MAX III OPER SYST DOCUMENTATION CABINET INSTALLATION (SUB) CRT WITH KEYBOARD CRT CABLE
0503	SYS CNTRL ELEMNTS FOR PLANT OPERATION PROGRMMR/KYBRD/DSP CENTRL CONTRL UNIT POWER SUPPLY TIMR/COUNTR/ACCESS SIMULATOR PRIMARY MASTER MASTER SYNCH INTERFACE MODULE CNTRL PANELS/BRDS
0504	SUBSYS OPERATION CONTROL ELEMENTS LOOP ACCESS MODS MOUNTING BASE 8 CHNL I/O INTERFC 16 CHNL OUTPT INTF I/O EXPANDER MOUNTING BASE 4-20MA INPUT MODS REMOTE CNTRL UNITS DESCRETE INPT MODS DESCRETE OUTPT MODS



#### "TABLE E-2" COST BREAKDOWN STRUCTURE 0505 CNTRL LINES TO SUBSYSTS AND PLANT CNTRL ELEMENTS CABLE-2500 FT PWR SPLY-CNTRL CNL PRGRMR-CNTRL CNTRL TIMR COUNTR-PWR SP CABLE-MB,SIM,I/O X LOOP ACCESS MODULE PWR SPLY-MOUNT BAS LOOP ACCESS MODULE LOOP ACCESS MODULE 0507 MISCELLANEOUS (HDWR DESIGN/ENGR) REQUIREMENTS DEFN PLANT SIZING SYS ANAL/SIMULAT DRAWNGS/SPECS/MODS PROCUREMENT DEFN CNTRL SYS MGMT 0508 FIELD INSTALLATION 0509 FIELD SUPERVISION 0510 SUBSYST CHECKOUT/ADJUSTMENT 06 DETAIL DESIGN 07 PLANT CONSTRUCTION MANAGEMENT HEADQUARTERS EXP ENG. CLERICAL SAL CONSULT & SERV COMPUTER SCHEDULING PURCH & EXPED ESTIMATING ACCOUNTING COMM & REPRO OVERHEAD FED & STATE TAX 80 SPECIAL FEATURES LAND & RIGHTS GRADING, GEN EXC ROADS, FENCES & LIGHT SANITARY SEWER SY YARD & STORM DRAIN WATERFRONT IMPROVE ROADS TO PUB ROAD RAILWAY ACCESS

TABLE A7

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WATERWAY ACCESS AIR ACCESS FACIL CTR FIELD OFF P&S

## "TABLE E-2" COST BREAKDOWN STRUCTURE

08

SPECIAL FEATURES (continued) INSURANCE TEMP CONSTR FACIL TEMP CONSTR EQ CONSTR SERVICES FED & STATE TAX FOREIGN DUTIES/TAX INITIAL SPARES CONDENSATE PUMP PIPING INSTR AND CNTRLS POWER CABLES CONTROL CABLES HELIO CONTROLLER FIELD CONTROLLER MOTORS HARMONIC DRIVE LINERAR ACTUATOR OPTICAL ENCOD, A3 OPTICAL ENCOD, EL MIRROR MODULE STOR MOTOR STOR LIN ACT FIELD CTL CABLE FIELD PWR CABLES AZ LIM SW EL&STOW LIM SW CIRBRKR & SW HAC/FIELD CLT CAB HAC/FIELD PWR CAB STATION SERV EQ INSTRUMENTS REC VALVES DOOR MOTOR DOOR GBOX SENSORS HEATERS, IMER VALVES VALVES R PUMPS SENSORS HEATERS, TRACE CONSTR SUPPORT, A&E STARTUP& C/O CONTINGENCY ESCALATION INT. DUR CONSTR

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"TABLE E-2" COST BREAKDOWN STRUCTURE

09

RELATED ITEMS DESIGN/ENGINEERING PRE PROD UNIT SITE ACTIVATION ELEVATOR (RECEIVER TOWR) SOLAR INTEGRATOR PROJECT MGMT SYSTEM ENGR SUB CTRS SERVICE SUST ENGR EQUIP INTEG

10

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SYSTEM FUNCTIONS) TRANS & LIFT EQ CRANES, HOISTS, ETS VEHICLE MAINT EQ RECEIVER EQ COLLECTOR EQUIP THERMAL STORAGE AIR SYSTEM WATER SYSTEM FURNISH & FIXTURE COMMUNICATION EQ OTHER TESTING AND EVALUATION OPERATIONS AND MAINTENANCE SITE (MAINTENANCE LABOR) BUILDINGS (MAINTENANCE LABOR) MISCELL EQUIPMT (MAINT. LABOR) TURBINE PLT E (MAINT. LABOR) TURBINE PLT EQ (SPARES AND REPAIR PARTS) CONDENSATE PUMP 11 н PIPING u INSTR AND CNTRLS ELECTRIC PLT E (MAINT. LABOR) ELECTRIC PLT EQ (SPARES AND REPAIR PARTS) STATION SERV EQ HELIOSTAT EQUIP (MAINT. LABOR) MIRROR MODULE (SPARES AND REPAIR PARTS) HARMONIC DRIVE ... LINEAR ACTUATOR 11 STOR LIN ACT 11 MOTORS 11 STOR MOTOR 11 OPTICAL ENCOD, A3 11 OPTICAL ENCOD, EL ... AZ LIM SW . EL&STOW LIM SW 11 POWER CABLES

OTHER (BUILDINGS AND OTHER UTILITIES TO SUPPORT

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## "TABLE E-2" COST BREAKDOWN STRUCTURE

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TESTING AND EVALUATION (continued)
FIELD POWER CABLES (SPARES AND REPAIR PARTS)
CIRBRKR & SW
HAC/FIELD PWR CAB "
ETELD CONTROLLER "
CONTROL CABLES "
HELTO CONTROLLER "
FIFID CTL CABLE "
HAC/FIFID CLT CAB "
RECEIVER UNIT (MAINT, LABOR)
REC VALVES (SPARES AND REPAIR PARTS)
INSTRUMENTS "
DOOR MOTOR "
DOOR GBOX "
HEATERS, TRACE "
VALVES R "
PIIMPS
TOWER (MAINT LABOR)
THERMAL STRG FO (MAINT LABOR)
HEATERS IMER (SPARES AND REPAIR PARTS)
VALVES
OPERATORS
TEST SUPPORT
MATERIALS - CONSUMABLES

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ADVANCED CENTRAL RECEIVER COST BREAKDOWN

41.	SITE, STRUC, MISC E		
4101.	SITE		
410101.	LAND & RIGHTS	08	
41010101.	LAND & SURVEY		
41010102.	EASMENT & R-O-W		
41010103.	CLEARING & DEMOLIT		
410102.	YARD WORK		
41010201.	GRADING, GEN EXC	80	
41010202.	ROADS, FENCES&LIGHT	80	
4101020201.	ROADS		
4101020202.	SIDEWALKS		
4101020203.	PARKING		
4101020204.	RET WALL, BRIDGES		
4101020205.	FENCES AND GATES		
4101020206.	YARD LIGHTING		
41010203.	SANITARY SEWER SY	08	
4101020301.	CONNECTIONS TO SYS		
4101020302.	SEPTIC TANK		
4101020303.	DISTRIB BOX		
4101020304.	ALLE FIELD(DRNS)		
4101020305.	PIPING, EIC	08	
41010204.	WATEDEDONT INDONE	00	
41010205.	DOADS TO DUE DOAD	08	
41010200.	DATIMAN ACCESS	08	
41010207.	WATEDWAY ACCESS	08	
41010200	ALD ACCESS FACT	00	
41010207.	BUILDINGS	08	
410201	TUPBINE BLDG		
41020101	EQUIND/SITE DDED		
4102010101	FOUNDATION	0207	0211
4102010102	SITE PREP	0207	0211
41020102	STRUCTURE	0207	0211
41020103.	HVAC	9201	0211
4102010301	OPEN AREA CAV SYS		
410201030101.	EVAP COOLER ASSY	0207	
410201030102.	AIR INTAKE LOUVER	0207	
410201030103.	SUPPLY AIR DUCT	0207	
410201030104.	EXHT AIR LOUVERS	0207	
4102010302.	AC FOR OFFICES		
410201030201.	HEAT PUMPI	0207	
410201030202.	DUCTWORK ETC	0207	
410201030203.	HEAT PUMP2	0207	
410201030204.	HEAT PUMP3	0207	
4102010303.	OPEN AIR HEATING		
410201030301.	ELEC UNIT HTR5KW	0207	
410201030302.	ELEC UNIT HTR7.5KW	0207	
410201030303.	ELEC UNIT HTRIOKA	0207	
4102010304.	MISC FANS & HTRS		
410201030401.	EXHAUST FANI	0207	

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ADVANCED CENTRAL RECEIVER COST BREAKDOWN



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#### ADVANCED CENTRAL RECEIVER COST BREAKDOWN

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4103030308.	THE OF DAY REF		
4103030309.	PEDESIAL LEV.FIXI		
4103030310.	TUDDING DET E		
42.			
4201.		0201	0011
420101.	TURD & GRDA	0201	0211
420102.	ELEC GENERATOR	0202	
4202.	COOLING TOWED	0206	0211
420201.	CULING TOWER	0200	0211
420202.	CIUC WATED DUND	0200	0211
420203.	CONDENSING SVE E	0205	0211
4203.	CONDENSING SIS E	0202	0011
420301.	CONDENSER	0203	0211
420302.	COND EXHAUSI PUMP	0205	0211
4204.	FEED REATER E	0000	0077
420401.	DEAERATOR	0203	0211
420402.		0203	0211
420403.	HEATER 2	0203	0211
420404.	HEATER 3	0203	0211
420405.	HEATER 4	0203	0211
4205.	WATER CIRCZTRT E		0011
420501.	COND TRFR PUMP	0205	0211
420502.	SG FEED PUMP	0205	0211
420503.	CONDENSATE PUMP	0205	0211
420504.	COND STRG TANK	0203	0211
420505.	PIPING	0204	0211
420506.	INSTR AND CNTRLS	0204	0211
420507.	WATER TRIMT EQ	0203	0211
43.	ELECTRIC PLT E		
4301.	SWITCHGEAR EQ		
430101.	ELEC PLT LABOR	0211	
430102.	M CS FEEDER BRKR	0208	
430103.	SIZE I FVNR	0208	
430104.	SIZE 2 FVNR	0208	
430105.	SIZE 3 FVNR	0208	
430106.	MOLDED CS BRKR	0208	
430107.	METAL CLAD SWGR	0208	
4302.	STATION SERV E		
430201.	DIESEL GENERATOR	0208	
430202.	AUX XFMR	0208	
430203.	DISTRIB XFMR	0208	
430204.	HELIO XFMR	0208	
430205.	BATTERY	0208	
430206.	CHARGER	0208	
430207.	INVERTER	0208	
4303.	PROTECTION EQ		
430301.	SURGE PROTECTION	0208	
430302.	LIGHTING	0208	
4304.	WIRING & ELEC STR		
430401.	CABLES	0208	

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ADVANCED CENTRAL RECEIVER COST BREAKDOWN

		(Page 4 of 1)
430402.	TRAYS AND CONDUIT	0208
4305.	PLANT CONTROL	
430501.	HARDWARE	
43050101.	COMPUTRS-PERIFRLS	
4305010101.	HELIO-ARRAY-CNTRLR	0502
430501010101.	CLASSIC PROCESSOR	
430501010102.	BATTERY BACK UP	
430501010103.	DISK SUBSYST/CNTRL	
430501010104.	170 CABLE, TOFT.	
430501010105.	150 CPS PRINTER	
430501010100.	PRINTER CABLE	
43050101010107.		
430501010100		
43050101010109.		
4305010101110.	CARLEINTEDDDOCSED	
4305010101112	MAY III ODED SYST	
430501010112	DOCUMENTATION	
430501010114	CABINET	
430501010115	INSTALLATION (SUB)	
430501010116	CRT WITH KEYBOARD	
4305010101117.	CRT CABLE	
43050102.	SYS CNTRL ELEMNTS	0503
4305010201.	PROGRAMARZKYBRDZDSP	
4305010202.	CENTRL CONTRL UNIT	
4305010203.	POWER SUPPLY	
4305010204.	TIMR/COUNTR/ACCESS	
4305010205.	SIMULATOR	
4305010206.	PRIMARY MASTER	
4305010207.	MASTER SYNCH	
4305010208.	INTERFACE MODULE	<b>25.2</b> (
43050103.	SUBSYS OP CNTRL EL	0504
4305010301.	LOOP ACCESS MODS	
4305010302.	MOUNTING BASE	
4305010303.	A CHNL INDT INTERFC	
4305010304.	16 CUNE OUTDT INTE	
4305010305.	TZO EVENNUED	
4305010300.	MOUNTING HASE	
4305010307.	4-20MA INPUT MODS	
4305010309	REMOTE CNTRL UNITS	
4305010310	DESCRETE INPT MODS	
4305010311	DESCRETE OUTPT MOD	
43050104	CNTRL PANELS/BRDS	0503
4305010401	CONTROL CONSOLE	
43050105-	CNTRL LINES/CABLES	0505
4305010501	CABLE-2500 FT	
4305010502.	PWR SPLY-CNTRL CNL	
4305010503.	PRGRMR-CNTRL CNTRL	
4305010504	TIME COUNTE-PWR SP	



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ADVANCED CENTRAL RECEIVER COST BREAKDOWN

+305010505.	CABLE-MB, SIM, 170 X	
1305010506.	LOOP ACCESS MODULE	
4305010507.	PWR SPLY-MOUNT BAS	
\$305010508.	LOOP ACCESS MODULE	
4305010509.	LOOP ACCESS MODULE	
43050107.	FIELD INSTALLATION	0508
43050108.	FIELD SUPERVISION	0509
43050109.	SUBSYST C/O ADJUST	0510
430502.	HDWR DESIGN/ENGR	
43050201.	REQUIREMNTS DEFN	0507
43050202.	PLANT SIZING	0507
43050203.	SYS ANAL/SIMULAT	0507
43050204	DRAWNGS/SPECS/MODS	0507
43050205	PROCUREMENT DEFN	0507
43050206	CNTRL SYS MGMT	0507
430503	CONTROL SOFTWARE	
43050301	SYSTERS SHETWADE	0501
42050207.	ADDI LCATIONS SETWO	0501
43050302.	APPLICATIONS SPINE	0501
43050303.		0501
43050304.	HELLOCTAT FOULD	0501
44.		0100
4401.	REFLECTIVE UNIT	0103
440101.	REFLECTIVE SURFACE	
44010120.	MIRROR MODULE	
440102.	MIRROR BACK STRUCT	
440103.	ASSY & BOARD	0104
4402.	DRIVE UNIT	0104
440201.	AZIMUTH	
44020110.	HARMONIC DRIVE	
440202.	ELEVATION	
44020217.	LINEAR ACTUATOR	
44020222.	STOR LIN ACT	
440203.	MOTORS	
44020315.	MOTORS	
44020321.	STOR MOTOR	
440204.	POSZLIMIT INDICAT	
44020418.	OPTICAL ENCOD, A3	
44020419.	OPFICAL ENCOD,EL	
44020425.	AZ LIM SW	
44020426.	ELASTOW LIM SW	
440205.	POWER SPLY/DIST	
44020511.	POWER CABLES	
44020524.	FIELD PWR CABLES	
44020527.	CIRBRKR & SW	
44020529.	HAC/FIELD PWR CAB	
440206.	ASSYDR/PED/ELECT	
4403.	CONTROL/INSTRMTEQ	0104
440301.	SENSOR/CCALIB EQ	
440302	FIELD CONTROL	
44030214	FIELD CONTROLLER	

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#### ADVANCED CENTRAL RECEIVER COST BREAKDOWN

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440303.	CONTROL/SIG EQ	
44030312.	CONTROL CABLES	
44030313.	HELIO CONTROLLER	
44030323.	FIELD CTL CABLE	
44030328.	HAC/FIELD CLT CAB	
440304.	HELIO ARRAY CTRL	
4404.	FOUND/SIFE PREP	0101
440401.	FOUNDATION	
440402.	SITE PREPARATION	
4405.	HELIO SUPP STR/PE	
440501.	HELIO SUPP STRUCT	0102
440502.	PROTECT ENCL	0107
440503.	LIGHTNING PROT	0107
4406.	FIELD ASSY & C/O	
440601.	HELIOSTAT	0108
440002.	SENSUR/CALIB EQ	0108
440003.	ELECTRICAL/DISTRIB	0108
440004.	ALIGN HELIOSTATS	0110
440605.	FIELD SUPPORT	0109
440606.	PARK & TRANSP	0107
4407.	DESIGN/ENGINEER'G	
440701.	DESIGN	0107
440702.	SUSTAINING ENGR	0107
440703.	PRE PROD UNIT	09
440704.	SITE ACTIVATION	09
45.	RECEIVER EQ	
4501.	RECEIVER UNIT	
450101.	ABSORBER UNII	0105
45010101.	ASSI & CU	0105
45010102.	ABSORBER COIL	01.05
4501010201.	TUBE	0105
4501010202.		0105
45010103.	INSULATION	0105
45010104.	TDACE HEATING	0105
45010105.	SUDDOT STOUC	0105
450102.	SUPPORT STRUC	0105
45010207	STOLIC STREET	0105
45010202	ABSODBED COVED	0105
45010203.	ABSORDER COVER	0105
45010204.	STEEL EL (V)P	0105
450103	VEC CIPCI FO	0105
45010301	ASSY & CO	0106
45010302	REC PIPING F	0100
4501030201	DISTRIB MANIEOLD	0106
4501030202	INSULATION-DIDE	0100
4501030203	PIPING	0106
45010303	REC VALVES	
4501030301	VENT VALVE	0106
4501030302.	RELIEF VALVE	0106



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#### ADVANCED CENTRAL RECEIVER COST BREAKDOWN

		(Page 7 o	f 11)
450104	INSTU & CNITHIS		
45010401	INSTRUMENTS	0104	
45010402	GEARS & REARINGS	0104	
4501040210.	DOOR MOTOR	0104	
4501040211	DOUR GBOX		
450105	TRANSP. FILLD INSTL		
45010501.	TRANSPORTATION	0108	
45010502.	INSTALLATION	0108	
4502.	RIS/DWN/HORIZ PIPE		
450201.	PIPING	030101	030107
45020101.	PIPING/CARBON STL		
45020102.	PIPING/STAIN STL		
450202.	INSULATION		
45020201.	INSULATION	030102	000107
45020202.	TR HEAT/CONTROLLRS	030102	030107
4502020215.	SENSORS		
4502020216.	HEATERS, TRACE		000107
450203.	VALVES	030103	030107
45020301.	DRAG VALVE		
45020303.	REMOTE-ON-OFF		
450204.	PUMP	030104	030107
450205.	SUPPORTS	030105	
450206.	EXPANSION	030101	
4504.	TOWER		
450401.	STL TOWER ERECT		01.00
45040101.	SUBASSY ON GRND	0105	0108
45040102.	ERECTION IN AIR	0105	0108
450402.	STRUCTURAL STEEL	0105	
450403.	GUY WIRES	01.01	
45040301.	BRIDGE CABLES	0105	
45040302.	CLEVIS AND CLAMPS	0105	
450404.	DIA FEODIS	0105	
45040407		0105	
45040402		0105	
45040404	OBSTRUCTION LIGHT	0105	
45040405		0105	
45040406	I IGHTNING PROTEC	0105	
4505	FOUND/SITE PREP	0105	
450501	FOUNDATION		
45050101	TOWER BASE	0101	0108
45050102.	PIERS AND BEAMS	0101	0108
45050103.	DEADMAN	0101	0108
45050104.	REDAR	0101	0108
450502.	SITE PREP		
45050201.	EXCAVATION	0101	
45050202.	BACKFILL	0101	
46.	THERMAL STRG EQ		
4601.	MEDIA CONTNMT E		
400101.	STORAGE TANKS		

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# ADVANCED CENTRAL RECEIVER COST BREAKDOWN

40010101.	STAINLESS STL TNK	0401	0408
46010102.	CARBON SIL TANK	0401	0408
400102.	MANIFOLDS	0401	0408
400103.	INSULATION	0401	0408
400104.	IMMERSION HIRS	()4()1	0408
460105.	GN2 SYSTEM		
40010501.	NITROGEN & TANKS	0401	
46010502.	REGULATOR	0401	
40010503.		0401	
46010504.		0401	
40010505	EILTEDS	0401	
40010508	CONTROL VALVE	0401	
400105000	MEDIA CIRC FO	0404	
4002.	WEK FULLD CIRC FO	0404	
460301	PIPING	030101	030107
40030101	PIPING/CARBON STL	000101	
40030102	PIPING/STAIN STL		
400302	INSULATION		
40030201	INSULATION	030102	030107
40030202	TR HEAT/CONTROLLRS	030102	030107
4603020210.	SENSORS		
4603020211.	HEATERS.IMER		
400303.	VALVES	030103	030107
40030302.	REMOTE-FL CONTROL		
40030303.	REMOTE-ON-OFF		
40030304.	MANUAL-ON-OFF		
46030305.	VALVE INSTALLATION		
400304.	PUMP	030104	030107
4004.	DISCHRG HEAT EXC	0000	
460401.	STEAM GENERATOR	0203	0211
4006.	FOUNDATION/SITE P	0406	
4008.	MEDIA	12300 MM 12300 700	
400301.	HITEC	0403	0408
400802.	IRON ORE	()403	
48.	DISTRIB & INDIR		
4801.	TEMPORARY EXPNSE	00	
480101.	CIR FIELD OFF P&S	08	
48010101.	SUPPORT OF CONSTR		
48010102.	LNGINNEDING STAFE		
48010103.	ACCOUNTING STAFF		
40010104.	ACCOUNTING STAFF		
48010105.			
43010107	EIDN DENT DEDDA		
43010109	HEDICAL E ATD		
43010100		08	
43010201	LIAH SITE INSHD	55	
43010201	FOULP, AUTO INSUP		
480103	TEMP CONSTR FACTI	08	
-00100.			

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#### ADVANCED CENTRAL RECEIVER COST BREAKDOWN

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42010201	SITE ACCESS (IND)	
40010301.	SILE ACCESS/IMPR	
48010302.	BUILD & STRUCT	
4801030201.	FIELD OFFICES	
4801030202.	WAREHOUSE,STOR	
4801030203.	MAINT SHOPS	
4801030204	GUARD HOUSE/FENCE	
4901020205	HOUSING	
4801030205.	AUSINO	
4801030200.	UTHER	
48010303.	ELECT & WATER	
48010304.	COMMUNICATION EQ	
48010305.	AGGREGATE PLANT	
43010306.	CONCRETE BATCH PLT	
480104	TEMP CONSTR FO	
4 2010401	TDANG LIET UNLOAD	
48010401.	TRANS, LIFT, UNLUAD	
48010402.	WELDING EQ	
48010403.	AIR COMPRESSORS	
48010404.	STEAM GENERATORS	
480 0405.	CHEM CLEAN FACIL	
48010406	SCAFFLODS & ACCESS	
48010407	BUILD FURN & FIXT	
42010409	SIGNS TOOLS HISCI	
40010408.	SIGNS, ICALS, MISCL	
480105.	CONSTR SERVICES	
48010501.	PURCH UTIL	
4801050101.	ELECT POWER	
4801050102.	WAFER	
4801050103.	SEWAGE DISP	
4801050104	STEAM	
4801050105	COMPRESSED ATP	
4901050106	CHET	
4-01050107	THE TELLY ETC	
4801050107.	IELE, IELEX, EIC	
4801050108.	REFUSE & WATER	
48010502.	SECURITY	
48010503.	EDUCAT & TRAIN	
48010504.	COMMON REC & STOR	
48010505.	SITE CLEANUP	
48010506.	O & M FACIL & EQ	
43010507.	SNOW REMOVAL	
48010508.	INSPATEST OF MATS	
480106	FED & STATE TAY	
490107	FODELCH DUTLES TAY	
400107.	INITIAL COADEC	
4802.	INITIAL SPARES	
480201.	TURBINE PLANT	
48020111.	CONDENSATE PUMP	
48020112.	PIPING	
48020113.	INSTR AND CNTRLS	
480202.	COLLECTOR	
48020211	POWER CABLES	
43020212	CONTROL CARLES	
42020212120	HEI IN CONTRALLED	
40020213.	ELELD CONTROLLER	
40020214.	FIELD CONTROLLER	

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ADVANCED CENTRAL RECEIVER COST BREAKDOWN

MOTORS	08
HARMONIC DRIVE	08
LINEAR ACTUATOR	08
OPTICAL ENCOD, A3	08
OPTICAL ENCOD.EL	08
MIRROR MODULE	08
STOR MOTOR	08
STOR LIN ACT	08
FIELD CTL CABLE	08
FIELD PWR CABLES	08
AZ LIM SW	08
EL&STOW LIM SW	08
CIRBRKR & SW	08
HAC/FIELD CLT CAB	08
HAC/FIELD PWR CAB	60
ELECT PLANT	
STATION SERV EQ	08
RECEIVER	
INSTRUMENTS	08
REC VALVES	08
DOOR MOTOR	08
DOOR GBOX	08
THERMAL STOR	
SENSORS	08
HEATERS, IMER	08
VALVES	08
VALVES R	08
PUMPS	08
SENSORS	08
HEATERS, TRACE	08
A&E	10224 - 108
PRELIM DESIGN	06
DETAIL DESIGN	06
CONSTR SUPPORT	08
CONSTR MGMT	
DESIGN SUPP	06
CONSTR SUPPORT	07
HEADQUARTERS EXP	
ENG,CLERICLA SAL	
CONSULT & SERV	
COMPUTER	
SCHEDULING	
PURCH & EXPED	
ESTIMATING	
ACCOUNTING	
COMM & REPRO	
OVERHEAD	
FED & STATE TAX	
STARTUP & C/O	08
SOLAR INTEGRATOR	4860
	MOTORS HARMONIC DRIVE LINEAR ACTUATOR OPTICAL ENCOD,A3 OPTICAL ENCOD,EL MIRROR MODULE STOR MOTOR STOR LIN ACT FIELD CTL CABLE FIELD PWR CABLES AZ LIM SW ELASTOW LIM SW CIRBRKR & SW HAC/FIELD DWR CAB ELECT PLANT STATION SERV EQ RECEIVER INSTRUMENTS REC VALVES DOOR MOTOR DOOR GBOX THERMAL STOR SENSORS HEAFERS,IMER VALVES VALVES VALVES R PUMPS SENSORS HEAFERS,TRACE A & E PRELIM DESIGN DETAIL DESIGN CONSTR SUPPORT CONSTR SUPPORT HEADDUARTERS EXP ENG,CLERICLA SAL CONSULT & SERV COMPUTER SCHEDULING PURCH & EXPED ESTIMATING ACCOUNTING COMM & REPRO OVERHEAD FED & STATE TAX STARTUP & C/O SOLAR INFEGRATOR

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## ADVANCED CENTRAL RECEIVER COST BREAKDOWN

(Page 11 of 11)

480601.	PROJECT MGMT	83
480003.	SUBCTRS SERVICE	09
480004.	SUST ENGR	09
480605.	EQUIP INTEG FEE	09
4807.	CONTINGENCY	08
4808.	ESCALLATION	08
4809.	INT. DUR CONSTR	80
49.	OPERATIONAMAINT	4900
4901.	OPERATIONS	4910
490101.	OPERATORS	08
490102.	TEST SUPPORT	08
4902.	MATERIALS	08

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UNIT MATERIAL COSTS - SMALL POWER SYSTEM EXPERIMENT (Sheet 1 of 6)

Element	Size	Unit	Unit Cost (\$)
COLLECTOR SUBSYSTEM			
Receiver			
Plate, low-carbon (LC) steel		1b	0.28
Corrugation, LC steel		1b	0.82
Insulation, fiber glass batting		ft <sup>2</sup>	0.36
Pipe, stainless steel (SS) SCH 40	1.0"	ft	4.33
Pipe, Incology 800	1.5"	ft	6.11
Pipe, SS SCH 40	3.0"	ft	15.55
Pipe, 4130 13 ga	2.0"	ft	2.50
Insulation, 3.0 in-thick Sheet SCH 40		ft <sup>2</sup>	1.93
Insulation, pipe	3.0"	3-ft 1	9.04
Insulation, pipe	1.0"	3-ft 1	7.39
Insulation, pipe	8.0"	ft	5.77
Insulation, pipe	3.0"	ft	3.21
Insulation, pipe	14.0"	ft	15.66
I-Beams, 3.0-inch		1Ь	0.20
Gears & Bearings (Motor)		unit	1500.00
Trace Heating	1.5-3.0"	ft/in diam	23.27-28.41
Thermocouplers		unit	30.00
Heliostats			
Sheet, LC steel, galvanized	0.020	15	0.24
Sheet, LC steel, galvanized	0.063	15	0.257
Tube	10.0	1b	0.21
Channel, LC steel		16	0.24
Tube		1Ь	0.266
Flange, steel		unit	180.00
Casting, Azimuth Drive		1ь -	0.90
Drive, Azimuth	-	unit	550.00
Bearing		unit	170.00

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## UNIT MATERIAL COSTS - SMALL POWER SYSTEM EXPERIMENT

Element	Size	Unit	Unit Cost (\$)	
Drive, Elevation		unit	300.00	
Casting, Elevation		1ь	0.88	
Motor		unit	110.00	
Concrete Foundation w/Reinforc	ements	уd <sup>3</sup>	55.00	
Tower				
Excavation		yd3	2.00	
Consolidated Backfill		yd3	2.00	
Concrete Foundation, Installed		yd3	347.00	
Structure Steel Tower, Install	ed	Ton	1,435.00	
Guy Wires		ft	3.00	
Paint, Applied		Ton	75.00	
Service Platforms		ft <sup>2</sup>	30.00	
Safety Ladder		vert ft	33.00	
Elevator		unit	78,544.00	
Obstruction Lights		unit	16,000.00	
Lightning Protection		unit	15,000.00	
Lighting		per 12 ft	\$225.00	
ENERGY STORAGE SUBSYSTEM				
Immersion Heater		unit	3,617.00	
GN <sub>2</sub> System				
Nitrogen		per tank	15.00	
Regulator		unit	75.00	
Check Valve		unit	25.00	
Relief Valve		unit	125.00	
Manifold		unit	387.00	
Filters		unit	12.00	
Hand Valve		unit	43.00	
Control Valve	A-37	unit	65.00	

(Sheet 2 of 6)

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#### UNIT MATERIAL COSTS - SMALL POWER SYSTEM EXPERIMENT

Element	Size	Unit	Unit Cost (\$)
Manifolds (Tank)			6,500.00
Tank Insulation (Subcontract)			
Hot		ft <sup>3</sup>	22.73
Cold		ft <sup>3</sup>	17.87
Iron Ore		ton	36.00
Hitec		1ь	.36
Syltherm		gal	19.00
Caloria		1ь	.13
Medium Transport		1Ь	.10
Rock & Sand		ton	19.00
Rock Transport		ton	5.00
Tank Insulation		ft <sup>3</sup>	51.84
Tanks - LC		(Figur	e A-1)
Tanks - SS		(Figur	e A-2)
Pressurized Tank (A-285) 600 psi 4,	400 ft <sup>3</sup>	unit	100,000

(Sheet 3 of 6)



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## UNIT MATERIAL COSTS - SMALL POWER SYSTEM EXPERIMENT

Element	Size	Unit	Unit Cost (\$)
ENERGY TRANSPORT SYSTEM/GENERAL PI	IPING		
Pipe, Low Carbon Steel SCH 40	2.0"	ft	3.01
Pipe, Low Carbon Steel SCH 40	2.5"	ft	3.01
Pipe, Low Carbon Steel SCH 40	3.0"	ft	3.83
Pipe, Stainless Steel	2.0"	ft	19.18
Pipe, Stainless Steel	2.5"	ft	19.18
Pipe, Stainless Steel	3.0"	ft	25.77
Trace Heating. Elec Resist Eleme	ents		
220°F∆-270°F∆	2.0-3.0"	ft	6.09
Piping Insulation, 4.0-in thick			•
	2.0"	ft	39.15
	2.5"	ft	39.15

(Sheet 4 of 6)

Valves and Pumps

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(Table A-11)

43.15

ft



A-39

3.0"

Table A-9								
UNIT	MATERIAL	COSTS	-	SMALL	POWER	SYSTEM	EXPERIMENT	

			(Sheet 5 of 6)
Element .	Size	Unit	Unit Cost (\$)
PLANT CONTROL			
Classic Processor			9,500.00
Battery Back Up			450.00
Disk Subsystem/Control			9,800.00
I/O Cable		ft	32.50
Printer			3,870.00
16 Channel Asyng Control			4,020.00
HS. Link			2,060.00
Internal Timer			1,030.00
Cable - Interprocessor			196.00
Max III Oper. Syst.			1,580.00
Cabinet			1,150.00
Installation (Sub)			686.00
CRT with Keyboard			1,950.00
Programmer/Keyboard/Display			1,000.00
Central Control Unit			2,000.00
Power Supply			625.00
Timer/Counter/Access			775.00
Simulator			175.00
Primary Master			275.00
Master Synch			150.00
Interface Module			295.00
Loop Access Mods			875.00
Mounting Base			140.00
I/O Expander			375.00
4-20 MA Input Mods			450.00
Remote Control Units			235.00
Control Console			362.00
Cable		ft	0.25

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Element .	Size	Unit	Unit Cost (\$)
CONSUMABLES			e
Deionized Water		gal	.05
Cleaning Agent		gal	3.25
Gasoline		gal	.80
Diesel Gasoline		gal	.65
Cooling Tower and Boiler Makeup Water (Ordinary Tap Water)		gal	.0008
Cooling Tower Sulfuric Acid		gal	.75
Cooling Tower Sodium Hypochloride		gal	.70
Hydrazine		1ь	5.50
Cooling Tower Scale Inhibitor		- 1b	3.30
Amine		gal	1.45
HCL		gal	.60
Caustic Soda		1ь	. 185
Powdered Resin		1b	2.65

## Table A-9 UNIT MATERIAL COSTS - SMALL POWER SYSTEM EXPERIMENT

(Sheet 6 of 6)

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## POWER CONVERSION UNIT MATERIAL COST

		Program	
Element	3.5	4.5	6.5
Radial Outflow Turbine Gearbox			73,000
Axial Steam	370,000	370,000	
Generator	31,000	31,000	31,000
Cooling Tower	35,000	35,000	25,000
Circulating Water Pump	5,900	5,900	4,500
Condenser	9,000	9,000	4,000
Condenser Exhaust Pump	11,000	11,000	15,500
Deaerator	23,900	23,900	4,000
LP Heater #1	-	-	1,363
HP Heater #3	-	-	1,830
HP Heater #4	-	-	1,567
HP Heater #5	-	-	1,285
Condenser Transfer Pump	350	350	-
Steam Generator Feed Pump	5,730	17,500	17,500
Condensate Pump	4,800	4,800	11,500
Condensate Storage Tank	3,000	3,000	3,000
Steam Generator	87,500	87,500	87,500
Demineralizer	30,000	30,000	30,000
Condensate Polisher	32,000	32,000	32,000
Boiler Chemical Feed System	25,000	25,000	25,000
Cooling Tower Chem Feed System	18,000	18,000	18,000
Water Treatment Panel	28,000	28,000	28,000
Cooling Tower Control Panel	4,000	4,000	4,000
Iron Ore	ton	36.00	
Tank Insulation (Subcontract)	2	22.73	
Hot	ft	22.73	
Cold	ft <sup>3</sup>	17.87	

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VALVES						11997		
Size, Material	2"CS	2"SS	2.505	2.5"SS	3"CS	3"SS		
Psi	300	300	300	300	300	300		
Remote, Flow Control	\$1065	\$1501	-	\$1596	\$1365	-		
Remote (On, Off), Act								
2-Way	1065	1501	1017	1826	1146	2169		
Manual (Gate)	-	-	-	375	389	-		
Control (Drag)	-	-	-	37500	-	45000		
PUMPS								
Size, Material	2.0"CS	2	3.0"SS	3.0"SS	2.0"05	5	2.5"SS	
Flow Rate	196 GPM	1	27 GPM	104 GPM	105 GPN	1	69 GPM	
Head Rise	(255 FT)	(	53 FT)	(54 FT)	(241 FT)	)	(55 FT)	
Oper Temp	500°F		850°F	850°F	550°F		1000°F	
In Line	-		-	-	\$4,103	3	\$12,309	
Submerged	\$24,100		\$8,328	\$8,299		-	-	

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Table A -11 PUMP & VALVE COSTS

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#### A.4.3 Applied Factors and Rates

Table A12 indicates the factors that have been applied to basic material and labor dollars in order to arrive at total costs. The factors vary by subsystem depending on the source and nature of the cost inputs. For example, Stearns-Roger estimates already include allowances for field efficiency, visibility and rework in a hot climate so that a contractor's fee and a distributable allocation is all that is necessary. The receiver unit, on the other hand, represents detail estimates so that a full factor load is required. These factors are based on experience for the types of equipment involved.

# TABLE A 12

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#### FACTORS APPLIED TO BASE COSTS

	LABOR HOURS		LABOR \$		MATERIAL \$		
ELEMENT	PURPOSE	RATE	PURPOSE	RATE	PURPOSE	RATE	
Receiver Unit	<u>Plant</u> Efficiency Visibility Rework, shop Lias., In-scope Changes Mech. Engr, QC, Sust. tool, &	1.25 1.20 1.17	<u>Plant</u> Fee Rate with O/H	1.08 \$35.00	Fee Visibility Scrap & Rework Transport	1.08 1.20 1.05 1.05	
*	Prod. Supp. <u>Field</u> Efficiency Visibility Shortages & Weather QC & Super	1.45 1.30 1.20 1.15 1.07	<u>Field</u> Fee Base Rate Distributables	1.08 \$15.00 1.85	•		
Heliostat	As published	-	Plant w/Fee and O/H Field Assy. w/Fee & Distrib. Install w/Fee & Distrib.	\$35.30 \$27.10 \$30.44	As published	-	

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MCDONNELL DOUGLAS

## TABLE A12

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	LABOR HOURS		LABOR \$		MATERIAL	<u>\$</u>
ELEMENT	PURPOSE	RATE	PURPOSE	RATE	PURPOSE	RATE
Energy Storage & Transport	Visibility Rework Incremental fatigue	1.10 1.05 1.25	Fee Base Rate Storage Transport Trace heat O/H on S/Ctr. Distributables	- 1.08 \$20.00 \$17.83 \$17.02 1.10 1.85	Visibility Scrap & Rework Fee	1.10 1.05 1.08
Power Conversion	None Required		Fee Field Rate Distributables	1.08 \$20.00 **	Fee	1.08
Buildings	None Required		Fee Field Rate Distributables	1.08 \$15.00	Fee	1.08
Tower	None Required		Fee Field Rate Distributables	1.08 \$15.00 1.85	Fee	1.08

FACTORS APPLIED TO BASE COSTS

\*\* Covered in Distributables and indirects

MCDONNELL DOUGLAS

	LABOR HOURS		LABOR \$	MATERIAL \$		
ELEMENT	PURPOSE	RATE	PURPOSE	RATE	PURPOSE	RATE
Plant Control	Efficiency QA, Secretarial and other support	1.25 1.22	Fee Visibility Test Components Transport	1.08 1.20 1.05 1.05	Fee Plant Rate W/OH Field Rate W/OH	1.08 \$40.56 \$25.74
0&M	Efficiency Field Bench & Wash	2.0 1.18	Discard factor Average Major Equip. Sensors & Instr	.05 .02 .1.00	Field Rate W/OH	\$15.00
	Refix Mechanical Elect.	1.10 1.25	Repair Cost Facto Average Major Equip. Hi-val Comp. Equip.	r .40 .20 .50		
Other Engineering	N/A	-	N/A	-	Plant Rate W/Fee & OH	\$43.80
Construction Mgr.			Factor on total	.08	Factor on total	.08
A&E			Factor on total	.08	Factor on total	.08

# TABLE A 12FACTORS APPLIED TO BASE COST

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