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PLASMA-SPRAY̌ED DUAL DENSITYCERAMIC TURBINE SEAL SYSTEM
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FINAL REPORT
By
D.L. Clingman, B. Schechter, K.R. Cross, J.R. Cavanagh
DETROIT DIESEL ALLISON dIVISION GENERȦL MOTORS CORPORATION INDIANAPOLIS, INDIANA 46206Prepared ForNATIONAL AERONAUTICS AND SPACE ADMINISTRATION

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## SUMMARY

The object:Ive of this program was to develop a plasma-sprayed dual density ceramic abradable seal system for direct application to the HPT seal shroud of small gas turbine engines. The system concept is based on a moderately high density ceramic layer adjacent to the metal shroud to provide thermal-stress cushioning for the abradable outer layer, consisting of a specially formulated reduced-density ceramic.

The program scope consisted of three iterations on each of two different coating systems. The investigations included coating processes, abradability, erosion resistance, permeability, and microstructural characterizalion.

Results obtained with the polyester-filled system showed excellent abradability but relatively poor erosion resistance characteristics. The cenosphere-fillec system produced somewhat less-impressive abradability characteristics but was much more erosion resistant than the polyester system. Blade tip distress was not considered excessive for elther system.

Both systems require additional effort to optimize the balance between abradability and erosion resistance before commitment to engine evaluation can be made.

## IniRODUCIION

Efficiency of emall gas turbine enganes in the size class of the Army's 800 shp Advanced Technology Demonstrator Engine (ATDE) is extremely sensitive to operating clearances between compressor and turbine blade tips and the stationary seal components. From the standpoint of specific fuel consumption (SFC) the single most significant blade tip clearance location is the high pressure turbine (HPT). The plasma-sprayed ceramic seal system investigated in this program was prompted by the lack of a satisfactory available seal system adaptable to the HPT application.

Two different, yet similar, concepts were selected for development, each incorporating a dual density plasma-sprayed ceramic system to be applied directly to the HPI seal shroud. Both systems employ a moderately high density ceramic layer of approximately $12 \%$ porosity adjacent to the metal shroud substrate and metaliic bond coat to mitigate the mismatch in thermal expansion characteristics between the metallic and low density ceramic components of the system. The low density ceramic outermost layer of the system provides abradability.

The two systems selected for development differ only in the approach taken in improving the abradability of the outer layer. One system uses a sacrificial filier to produce the desired density reduction through controlled porosity brought about by thermal decomposition of the filler. The second approach employs a temperature-resistant low density filler which is distributed throughout the abradable layer and remains intact following exposure to elevated temperature.

The seal systems developed during this program have built upon the ever -increasing background of success obtained with the NASA-developed yttria-stabilized zirconin (YSZ) thermal barrier conting systems, The basic philosophy guiding the program has been to start with a proven high temperature material, preferably one with significant engine experience, and to modify the coating structure toward the end of improving the abradability of the material while retaining the desirable high temperature characteristics of the original coating system. The end resuit becomes an "abradable thermal barrier".

## Conting Configuration

Typicaliy, the NASA coating successes have been achieved with "thin" couting systems-1.e., bond coats $0.013-0.018 \mathrm{~cm}(0.005-0.007 \mathrm{In}$.$) and$ oxide layers $0.038-0.051 \mathrm{~cm}(0.015-0.020 \mathrm{In}$.) thick, as shown in Figure 1a. Further, the coatings have been "duplex" in that only two discrete layers are present, with no "graded" or mixed-composition layers.

From the structure of the dual-density coating system, shown in Figure 1b, it is readily apparent that the concept involves essentially the addition of a $0.046-0.051 \mathrm{~cm}(0.018-0.020 \mathrm{in}$.$) reduced-density abradable layer super-$ posed on top of the basic NASA thermal barrier coating. An incursion of turbine blades into a rub track, particularly in small engines such as the GMA 500/ATDE, is unlikely to exceed $0.025-0.038 \mathrm{~cm}(0.010=0.015 \mathrm{in}$.) without considerable damage being incurred by the rotor system. .The coating system geometry selected has providad for this margin in the abradable outer layer.

## Specimen Fabrication

The basic concept of an abradable thermal barrier depends on devising a method whereby the density in the blade track region of the seal is reduced below that normally obtained in the plasma-spray process. One attractive method for accomplishing the desired density reduction is to "co-spray" a sacrificial "filler" concurrently with the YSZ of the thermal barrier. This procedure interrupts the continuity of the YSZ and is followed by thermal decomposition of the flller to produce a controlled level of porosity. A major difficulty in using this technique arises from the significantly different temperature capabilities (melting points) of YS' and candidate fillers. It is this feature that prevents the constituent powders from being bound together and sprayed as a single composite material, since particle temperatures adequate for softening YSZ (required for good deposition) would surely result in premature decomposition of the filler.

A workable solution to the problem of spraying materials with such vastly different characteristics has resulted from providing different residence times in the plasma stream for each constituent powder according to its particular requirements. This is accomplished by introducing the hightemperature component (YSZ) through a powder feed port directly into the plasma-spray gun body. The low-temperature component (polyester) is fed by a separate powder feeder into the plasma stream external to the gun body at a point downstream from the nozzle. The polyester filler currently used in preparing specimens of one system for this program is subsequently
thermally decomposed by heating in air at $982^{\circ} \mathrm{C}\left(1800^{\circ} \mathrm{F}\right)$ for a period of 4 hours. This non-optimized heat treatment has proven to be adequate for removing the filler constituent, However, no attempt has been made to determine whether lower temperatures and/or lieseer times would also suffice,

## Fabrication Equipment

The plasma spray equipment used in constructing the various coating specimens was identical to that used by NASA in developing the yttriam stabllized zirconia thermal barider coating syotem. The plasmadyne Model SG-1B plasma-spray gun used exclusively ror deposition of all layers of the coatings has powder feed ports located both internal and external. to the gun body. Normally, only one of these portes is used at a time. However, because of the pecullar requirements of the filled coating layer, separate Plasmadyne Model, 1000-A powder feeders are used to supply both ports simultancously - the YSZ being introduced within the gun body and the f:lller powder infected into the plasma stream through the external downstream port. With this arrangement the optimum parameter ranges for the muitiple component system refiect a compromise of the requirenents of the individual component powders.

## Filler Constit.uents

## Polyester-Filled Systems

The sactificfal"fillecr" powder used to ereate the controlled porosity in the -abradable layer of the I-P. II-P, and III-P systems was Metco 600, a commerclally avallable polyaster powder suitable for plasma spray applications. Additionsl characterdzation of this powder beyond that provided by the manufacturer was Iimited by the tendency of the powder to adhere to the walls and screens of the various sleves during attempts to document particle size distributions. Thermally, the powder was found to char at a temperature oft approximately $552^{\circ} \mathrm{C}\left(1025^{\circ} \mathrm{F}\right.$ ) which is appreciably below the $982^{\circ} \mathrm{C}\left(1800^{\circ} \mathrm{F}\right)$ temperature selected for thermal decomposition.

## Cenosphere-Filled Systems

Alumino-silicate spheres ("cenospheres") comprise the "filler" used to improve the abradability of the outer layer of the I-C, II-C, and III-C systems. This material, which was supplied for the program investigations by NASA is essentially "fly-ash", a pollution by-product derived from the electric power generating industry. Low density, hollow cenospheres are reported to be selectively separated from solid spheres by a flotation process in which the heavier solid particles sink to the bottom of the container. The buoyant hollow spheres are skimmed from the surface of the ifquid and drifed prior to subsequent use.

Steve analysis of the cenospheres was inconclusive, as in the case of the polyester powder. The particles displayed a pronounced tendency to adhere to the screens and walls of the sieves, probably as a result of static electrical charging of the particles. However, under optical examination at 30 X magnification, an extremely broad particle size distribution was observed. No attempt was made to reduce the range of particle sizes since no difficulty was encountered in spraying the material in the as-received condition.

## Procegbing Procedures

A11 gubstraten materials used in this investigation wore Hastelloy $X$, This 15 the same material as that used for the shroud segmentes of the GMA $500 /$ ATDE and ensures that a fully developed coating gystem will be compatible with engine hardware.

The elapsed time between plasma spray processing steps was held to the minimum possible consistent with exercising eare and good technique, and in no case was allowed to exceed 2 hours. This condition thus required that all specimens be completed the same day that they were started.

Prior to deposition of each particular conting system, the substrates were prepared by vapor degreasing, followed by grit blasting with 60 grit aluminum oxide. Because of the number of specimens (12) prepared for each iteration: fabrication was accomplished in two batches of six specimens each.

Powder flow rates were precisely determined by collecting and weighing timed specimens of material delivered by the powder feeder. Spray distances were the same as those established by NASA for the several discrete layers of the coatings, with the same distance maintained for both the standard density layers and the filled layers, regardless of the filler employed. All spraying was done with hand-held equipment, apecimens oriented vertically, and cooling air supplied to the rear face of the specimen coupons. Deposit efficiency appeared to play a significant role in the preparation of the cenosphere-filied coatings, since littic variation in attainable composition was achieved.

## Bond Coat Powder

The bond coat employed in all instances was NiCrAlY obtained from Alloy Metals, Inc., Troy, Michigan, with the following chemical composition:

Cr 16.2\%
A1 5.5\%
Y $0.6 \%$
Ni Balance
Mesh specification was $-200+325$. The material was identical to that developed for the NASA thermal barrier coating, including the source of supply. A $13.6 \mathrm{~kg}(30 \mathrm{lb}$.$) developmental heat of the material yielded a$ net of $12.3 \mathrm{~kg}(27 \mathrm{lbs})$ of which only 2.3 Kg ( 5 lbs ) was within the -200 +325 mesh required for plasma spraying. The remaining material was nearly equally divided between +200 and -325 mesh sizes, neither of which was found to feed or spray satisfactorily.

## Oxide Layer Powder

The yttria-stabilized zirconia powder employed in this investigation marked a potentially significant departure from the NASA-developed thermal barrier materials. Because the material used in the NASA-developed coatings was quite expensive and had a history of lengthy delivery times, Nitco 202-NS was selected for the oxide layer component in the interest of controling costs
and expedting the execution of the program, The princtpal difference between the two powders is in the method of stabilization. Motco 202-NS achieves stabilization during the spray process instead of by premalloying and $1 a$ avallable off the sheff at a fraction of the cost of the prestablifzed material.

Recent, and as yet unpublished, investigations at DDA on various combinations of bond coat and yttria-stabilized airconia materials indicates that the NASA-developed material possesses superior thermal shock/fatigue resistance compared to other materinis tested. Should this factor eventualily prove troublesome with the dual-density systems under development, a minimum of: effort is expected in order to effect a material change if required.

## Standard Density Layers

parameters and techntques identical to those used by NASA were employed in depositing the standard density intermediate layer for each coating configuration. As previousiy mentioned, however, Metco 202-NS was subistituted for the premalloyed yttriamstabilized zirconin used in the NASA-developed thermal barrier coatings.

## Abradable Layers

The most signdficant parameter to evolve in the preparation of abradable layers, regardless of the "filler" employed, was the ratio of zirconia to filler material. Since the deposit efficiencies of the materials generally differ, the starting ratios were likewise different from the ratios in the deposited coating.

Some modification of the standard density layer parameters was required to optimize the deposition of the high meiting point zirconia without fncurring premature softening or melting in the filler materials. Even though the filler powders were introduced into the plasma stream through an external feed port, a significant reduction in both are current ( $-20 \%$ ) and operating voltage (up to $-10 \%$ ) were required. These parameter variations were initially established for the polyester-filled system and carried through for the cenosphere fllled-system without any further changes. The spray parameters for each of the coating systems are listed in Table I.

## Surface Machining

The surface of each specimen was prepared by machining with a single-point cuting tool of the replaceable carbide insert variety prior to any further conditioning (e.g., burn-out in the case of polyester-filled coatings).

Machining parameters were determined for the I-P coating system by trial and error using both single-point machining and wet grinding techniques. The coating was found to machine easily with either method, and as expected, the smoother surface was obtained by grinding. Specimens subjected to the grinding operation were flushed with clear water and dried in vacuum to remove any contamination from the grinding coolant. The parameters estabilshed for the I-P system were used for the machining of all subsequent coating systems, These parameters were:

- Cutting tool Carbide Insert - TPG 431-KG8
- Work Speed $118.9 \mathrm{~cm} / \mathrm{min}(390 \mathrm{ft} / \mathrm{min})$
- Cross Feed $0.015 \mathrm{~cm} / \mathrm{min}(0.006 \mathrm{In} / \mathrm{min})$
- Material removed per pass 0.025 cm ( 0.010 Inches)

Roughness measurements were made prior to thermal decomposition of the polyester filler for the I-P system. These measurements included readings for both a ground as well as a machined surface. The order of magnitude of attainable surface fitnish for the I-P system represents an upper bound when compared to high density coating systems as can be seen from Table II. This table is a compilation of the surface roughness of each of the coating systems as taken after surface machining.

Hardness of the I-P coating system was measured for the as-sprayed and machined configurations, both before and after thermal decomposition of the polyester filler. The RI5Y superficial hardness ecale ( 1.5 kg load, 1.27 cm ( $\frac{1}{2}$ Inch) diameter ball indenter) was found to be satisfactory for the softer coatings typified by the I-P system, but lacked sufficient definition for the harder coatings. Consequently, some of the harder coating systems necessitated use of the R15W scale ( 15 kg load 0.32 cm ( $1 / 8$ inch) diameter indenter) as an alternate measurement system. Measurements obtained from both systems are provided in Teble III.

## High Speed Abradability Rig

The abradability evaluations were conducted on the high speed, high temperature test rig shown in Figure 2. This rig consists of a stean turbinedriven spindle with replaceable test disks. The program test condition of $228.6 \mathrm{~m} / \mathrm{sec}(750 \mathrm{ft} / \mathrm{sec})$ requires the unit to rotate at $29,650 \mathrm{rpm}$, approximately one-half the design limit.

The heat source for this test unit is a quartz lamp furnace which is limited to $760^{\circ} \mathrm{C}\left(1400^{\circ} \mathrm{F}\right)$ due to mechanical design constraints of the disk/shaft attachment. Evaluation temperatures of $538^{\circ} \mathrm{C}\left(1000^{\circ} \mathrm{F}\right)$ were specified for this program. This temperature was achieved during rig warmup at 5000 rpm but could not be maintained at levels greater than $302^{\circ} \mathrm{C}\left(575^{\circ} \mathrm{F}\right)$ when the disk was brought to operating speed because of cooling resulting from excessive windage in the furnace cavity.

The mechanism used to provide the rub incursion motion is designed around a rigid frame system which supports the test coupon above the rotating IN 792 test disc in the quartz lamp heated cavity, The vertical incursion drive is fixed to the frame above the test coupon through a thin flexure which essentialiy isolates the normal and tangential forces produced by the rub. The rub interaction rates of $0.0025 \mathrm{~cm} / \mathrm{sec}(0.001 \mathrm{in} / \mathrm{sec})$ and $0.025 \mathrm{~cm} / \mathrm{sec}$ ( $0.010 \mathrm{in} / \mathrm{sec}$ ) are achieved by controlling the pulse rate of a stepping motor which drives a lead screw. Normal force signals are sensed ${ }^{2}$ a load cell positioned between the lead screw and the flexure leaf. The tangential force signals are transmitted by a rigid load frame through swivel. couplings to two load cells mounted outside the heated cavity. The tangential force signals are then summed electrically to provide the instantaneous tangential force signal.

## Erosion Test Rig

Erosion tests were conducted on the apparatus shown in Figure 3. The specimen is mounted at the prescribed angle to the impinging air/particuiate stream. The tests were performed at room temperature with the particulate flow rate ${ }_{3}$ set at a nominal $20 \mathrm{gms} / \mathrm{hr}(0.044 \mathrm{lb} / \mathrm{hr})$ and the air flow nominally at $11.2 \mathrm{~m}^{3} / \mathrm{hr}\left(400 \mathrm{ft} /{ }^{3} \mathrm{hr}\right.$ ) with a supply pressure of 482.3 KPag ( 70 psig ). A timer shuts the rig off at the predetermined time. The erosive medium used was AC Coarse Air Cleaner Dust (Natural Arizona Road Dust) which is primarily calcium silicate and has the following particle size distribution:

| 0.5 microns | $12 \%$ |
| :--- | ---: |
| $5-10$ microns | $12 \%$ |
| $10-20$ microns | $14 \%$ |
| $20-40$ microns | $23 \%$ |
| $40-80$ microns | $30 \%$ |
| $80-200$ microns | $9 \%$ |

Specimen and dust reservoir weights are recorded prior to and at the conclusion of each test.

The angular incidence of the specimen with xespect to the erosive air stream was selected as $15^{\circ}$ based on the tests of the standard density system shown in Figures 4 through 6. The $15^{\circ}$ setting, Figure 6, was considered to be most representative of engine air flow conditions and would not unduly penalize candidate coating systems.

Permeability Rig
Through-1eakage as a result of interconnected porosity is evaluated on the rig schematically shown in Figure 7. This simple fixture consists essentially of inlet and exhaust ports which are formed in a polyurethane insert in the cover. When the cover is clamped in place over the sample, the polyurethane acts as a seal preventing leakage across the abradable surface to the exhaust port or to the atmosphere. The incoming argon is thereby forced to pass through the abradable material in order to reach the exhaust port. The feed port is connected to a pressure gage, flowneter and argon tank and the exhaust port is open to the atmosphere. Pressure is set at the argon tank by means of a regulator, and through-flow in the coating is monitored at the flowmeter. The area used for the flow calculation is the actual cross sectional area of the specimen.

## Polyester-Filled Systems

## Abradability

Abradability test results of the polyester filled systems are illustrated In Figures 8-13.

The I-P polyester-filled system is show in Figure 8 for the slow incursion rate of $0.0025 \mathrm{sm} / \mathrm{sec}$. ( $0.001 \mathrm{in} / \mathrm{sec}$.) The absence of transferred metal from the blade tip to rub track illus'rates the fine abradability characteristics of this material. The blade tip showid no evidence of distress or loss of material. A siight burnishing was present as can be seen by the faint discoloration of the tips in Figure 8. Depth of the rub was 0.013 cm ( 0.005 in .).

The II-P polyester system slow incursion rate rub is shown in Figure 9. The rub path produced by the rotating blade tips shows no evidence of metal transfer or tendency towards glazing. Depth of the rub was 0.038 cm ( 0.015 In. ). The blade tip showed no evidence of the rub. Measured tip loss was $0.00051 \mathrm{~cm}(0.0002 \mathrm{in}$.$) which is discounted as being within$ measurement tolerance.

Figure 10 shows the slow incursion rate abradability results for the III-P materials system. This was a well-defined clean rub trace with no evidence of glazing or transferred metal on the surface of the abradable material. The blade tip condition was excellent with no evidence of any distress present. No loss of blade tip material could be measured. The depth of rub was 0.038 cm ( 0.015 in.$)$.

Figure 11 was the result of the fast incursion rate rub for the I-P material system. During the course of this test, the penetration depth of the blade tip exceeded the depth of the outer abradable layer and came into contact with the more dense YSZ sub-layer. The result was a two-phase rub. Close examination of the rub track showed that the glazed area was initiated at $0.043 \mathrm{~cm}(0.017 \mathrm{in}$.$) below the surface of the coating, which is the thick-$ ness of the abradable top layer. Total rub depth was 0.053 cm ( 0.021 in .). The blade tips show definite evidence of a rub, as can be seen in Figure 11; however, no severe distress is present. The apparent damage seen in Figure 11 is more of a burnishing which produces a series of color variations on the tip of the blade rather than a physical scoring or galling of the surface. This scoring or galling of the surface is commonly present in most all-metal abradable systems. Measured blade tip loss was of the order of 0.00051 cm (0.002 in.).

The result of the fast incursion rate abradability test with the JI-P material system is shown in Figure 12. Glazing of the material occurred almost immediately upon contact, accompanied by thermal cracking at the surface of the rub path and some particle pullout. No metal debris could be seen in the rub track. The blade tip shows severe burnishing and visual indications of streaking, but there was little evidence of any physical scoring or galling taking place. The measured rub depth was 0.013 cm ( 0.005 in. ) and the maximum blade tip loss was .0015 cm (. 0006 in. ).

Figure 13 shows the condition of the rub track and the blade tips for the fast Incursion rate with the III-P materials system. The rub track was very clean and distinct except for a silght amount of metal pickup at one edge of the rub path. The blade tip shows no evidence of distress and no burnishing is present. The maximum amount of blade tip loss was $0.0025 \mathrm{~cm}(0.001 \mathrm{in}$.) and the depth of penetration in the abradable layer was $0.041 \mathrm{~cm}(0.016 \mathrm{in}$ ) .

## Erosion Resistance

Erosion tests were performed on each of the sample systems in accordance with the test description and apparatus previously described. A particularly unusual phenomenon occurred with the I-P system which can be observed in Figures 18 a through d. A layering of the coating took place during fabrication and was immediately observed after machining the samples, Figure 14a. This layering could also be observed in the erosive patterns produced, as seen in Figures $14 \mathrm{~b}, \mathrm{c}, \mathrm{d}$. This did not occur in any of the other systems and is believed to be an inconsistency in the plasma spray process, possibly resulting from spray technique employed in fabricating early specimens, It is also noted that the I-P system experfenced the most severe total erosion damage of all the systems as well as the highest rate of damage. In the first 30 minute period, the sample was virtually eroded away to the more dense YSZ sub-layer. Erosion of the II-P coating system is shown in Figures 15a through d . The layering observed in the I-P coating, Figure 14a, was not present in the II-P coating, Figure 15a. Improved erosion resistance of the II-P coating over the I-P system can be observed as early as the completion of the 30 minute test (Figures 15b compared to Figure 14b). Erosion of the III-P coating system, shown in Figures 16a through d, behaved similar to the I-P system. The specific erosion resistance plotted as a function of time is shown for all the systems in Figure 17.

## Permeability

Gas flow permeability for each polyester-fillied coating system was checked in accordance with the procedure previously described. Static input pressures up to 344.5 KPag ( 50 psig ) were applied with zero leakage noted. These results are compared with the results obtained for conventional abradable materials in Figure 18.

## Cenosphere - Filled Systems

Abradability
Figures 19 through 21 are the results of the slow incursion rate abradability tests on the cenosphere-filled coating systems. These coatings were generally characterized by a very audible telegraphing of the rotating blade tip contacting the abradable surface. The presence of severe glazing and thermal cracking in the surface of the abradable layer during the slow incursion rate tests suggested a more rapid incursion rate could result in possible damage to the test rig and were therefore deleted from the test program. In all instances, the wear scar appeared to be glassy in nature and layered above the surface of the wear path. The layering appears to start at the entrance to the rub zone and builds in thickness as the blade path exits the material. The blade tips all exhibit heavy burnishing and some scoring and it is likely that some glazed material adherred to the blade tips, thereby preventing an accurate measure of blade tip loss. This loss as best determined,
measured $0.0025 \mathrm{~cm}(0.001 \mathrm{in}$.) on the I-C test, $0.00051 \mathrm{~cm}(0.0002 \mathrm{In}$.) on the II-C test and $0.00015 \mathrm{~cm}(0.0006 \mathrm{in}$, ) on the III-C test. Depth of rub was $0.013 \mathrm{~cm}(0.005 \mathrm{in}),. 0.031 \mathrm{~cm}(0.012 \mathrm{in}$.$) and 0.023 \mathrm{~cm}(0.009 \mathrm{in}$. for the I-C, II-C, and III-C tests respectively.

## Erosion Resistance

Erosion test results of the cenosphere-filled systems are shown in Figures 22 through 24. No evidence of layering, as was observed in the I-P system, was present in any of the cenosphere-filied coatings. Erosion resistance of the cenosphere-filled systems was significantly improved over the polyesterfilled systems. The specific erosion resistances, as plotted in Figure 17, of the three cenosphere filled systems were very similar in erosive performance, as could be expected when comparing the final composition listed in Table IV.

## Permeability

Permeability for each coating was checked to 344.5 KPag ( 50 psig ) with zero leakage noted. Both polyester- and cenosphere-filled systems displayed superior leakage characteristics in comparison with more comnon abradable materials, as shown in Figure 18.

## Microstructure Determination Polyester-Filled Systems

Porosity Level
The porosity level of the specimens I-P, II-P, and III-P were measured and tabulated in Table IV. Section views of the I-P, II-P, and III-P coatings (100X) are displayed in Figure 25a, Figure 26a, and Figure 27a. The progression of the iterations I-P, II-P and III-P leading to lower porosity levels shows that both the pore size and pore distribution decreased in subsequent iterations. It may be noted that the thickness of the porous oxide layer, as shown in Figure 25a, is inconsistent with the thickness shown in Figure 1 b . This resulted from sectioning the coating at the end of the specimen, where the outer layer spray pattern tapered silghtly toward the substrate.

## Ceramic Particles Morphology

Cross-section views at 1000X of I-P, II-P, and III-P are shown in Figure 25b, Figure 26b, and Figure 27b. The views shown display the coating fine structure resulting from plasma spray co-deposition of the polyester and YSZ powders followed by the burn-out of the polyester phase. The level of polyester powder in the plasma spray operation affects the coating structure. particles of polyester are trapped to form voids and provide a foreign material to weaken the mechanical bonding between the deposited ceramic YSZ particles. Figure 25b, showing the porous oxide layer of specimen series I-P, shows evidence of a spongy area surrounding some of the YSZ particles which likely lessens the inter-particle bond strength.

## Interconnectivity of Coating Pores

A specimen from series II-P was examined by Scanning Electron Microscopy (SEM) at 200X. Figure 28 discloses that the voids resulting from the polyester deposition and burn-out are only randomly connected and rarely
communicate between pores over a path exceeding $.013 \mathrm{~m} .020 \mathrm{~cm}(.005 \mathrm{~m} .008$ inches). The "closed pore" structure therefore explains the low permeability of the polyester/YSZ coating series compared to the leaky characteristics of abradable materials such as the sintered metal type of coating structure.

Additionally, Figure $28 a$ and $b$ displays the level of $Z r$ and $Y$ as the sensor traverses over the surface and void areas. The straight line across each view defines the line being scanned for the given element. A minimum level for $Z x$ and $Y$ is indicated as the scan progresses over the void areas.

Figure 29 displays the results of an X-ray analysis of elemental distribution on the surface of the cross section of a II-P specimen. Zone 1 is shown to be a void or surface hole. Zone 2 shows the polished YSZ surface with a major indication for zirconium and a minor indjcation for yttrium. Minor traces of calcium, silicon and sodium were also noted.

## Microstructure Determination Cenosphere-Filied Systems

Porosity Level
The porosity level of the test specimen series I-C, II-C, and III-C is achieved by the in-situ trapping of the hollow cenospheres during plasma spray co-deposition with the YSZ ceramic material. Section views of specimens from the series in I-C, II-C and III-C coatings are displayed in Figure 30a, Figure 31a, and Figure 32a. The progression of the iterations of the I-C, II-C and III-C series was to increase the cenosphere percentage with a goal of improving abratubility, The level of cenosphere entrapment was measured by a point-count technique and found to be 30,35 and 32 volume percent respectively for $I-C, I I-C$, and III-C as shown in Table IV.

Cenosphere/YSZ Particle Morphology
Cross-section views at 100 X of series I-C, II-C, and III-C are shown in Figure 39b, Figure 31b, and Figure 32b. The high magnification reveals that the yttria-stabilized zirconia coating matrix encloses both identifiable whole cenosphere particles and solidified agglomerates of the cenosphere material. The solidified agglomerates appear as fairly smooth glassy type particles with 1ittle evidence of fracture through the phase. In contrast, the zirconia matrix exhibits both irregular voids and crack or internal fracture patterns.

Figure 33 illustrates the same $I-C$ series coating at $200 X$ magnification with elemental line scans for zirconium and yttrium identifying the yttria stabilized zirconia (YSZ) zones. The dark grey cenosphere particles and solidified agglomerate zones are indicated by noting the areas where the zirconium line scan is at the minimum level.

A view of the II-C series coating at 200 X magnification is presented in Figure 34 with the accompanying elemental line scans again shown for zirconium and yttrium. The II-C SEM micrographs (Figure 31) reveal the zirconia matrix as slightly more spongy in appearance. The size distribution of the cenosphere balls and the solid cenosphere material distributed within the coatings are likely related to the distribution of cenosphere particle size supplied to the plasma spray gun.

## DISCUSSION OF RESULTS

The slow incursion rate abradablifty tests on the polyester-filled systems display very similar wear scar characteristics. The striking dis-similarity between the three coatings in this matrix is the variation in apparent density between I-P, II-P and III-P as seen in Figures 25, 26 and 27. The intent of the variation in coating system composition was to decrease the polyester content as the testing progressed in order to produce an abradable system which also possessed the desired erosion resistance characteristics.

The IP conting system was targeted for a volume ratio of $65 \% \mathrm{ZrO}_{2}$ and $35 \%$ polyester. The actual measured results were $72 \%$ and $28 \%$, respectively. The IIP coating was designed to nominally increase the $\mathrm{ZrO}_{2}$ density of the coating by $10 \%$ over the IP system. The measured result was $79 \%$ dense instead of the targeted $75 \%$. The resultant hardness, abradability and erosion tests results support the observed increase in density. The hardness increased from 13 to 89 on the R15Y scale. The specific erosion decreased as expected and the fast incurion rate abradability test resulted in a giazed track which occurred solely in the porous top layer. In the I-P test, the glazed track did not appear until the blade tip passed through the abradable layer and came into contact with the subsurface standard density layer. It was observed that the I-P system was so soft that the porous surface layer was eroded during the first 30 minutes of testing. Subsequentiy, the erosion was presumably taking place in the standard density layer, which naturally offered much more resistance. This accounts for the wide variation in slope between 30 and 60 minutes for the I-P test.

The III-P system which, although more dense than the II-P system exhibited some of the performance characteristics of a softer coating. The 100X micrographs indicate the density of the porous oxide layer is increasing as intended, from I-P to II-P to III-P. However, the hardness decreased substantially from II-P to III-P and the specific erosion resistance of III-P was very similar to that of I-P. The forces encountered during the slow incursion rate rubs support the oxide layer composition analysis. That is, the normal and tangential forces increase in value with increasing density for this series of runs. However, for the fast incursion rate tests, the normal forces follow the glazing trend. For example, the II-P-F run, which had a glazed rub, also had a high value for the normal load. Glazing in the I-P-F run is discounted due to the blade tip striking the standard density layer. Normal loads were not recorded for the I-P-F run due to an instrumentation failure.

The desired increase in density for the polyester-filled system was nominally achieved through variation of the polyester content during spraying. Projected increases in coating density were achieved by this method and proportionate increases in hardness and erosion resistance occurred for the II-P system, when compared to the I-P coating. However, the III-P system, although more dense than either the I-P or II-P coating systems, did not reflect the increased density in the hardness survey or in the erosion test. This paradox has not been satisfactorily explained. Abradability tests at slow incursion rates did not result in any discernable differences in the rub paths; fast incursion rates produced observable variations as noted above.

Compositional changes in the cenosphere-filled system to provide for a more abradable coating were not as pronounced as expected. The desired cenosphere percentages were never achieved and only noninal differences were
observed in the erosion test resatis. However, these coatings all resulted in significantily better erosion resistance than any of the polyster-filled systems. The normal forces registered during the rubs of the cenosphere Ellled system were appreclably lower than the glaze-producing normal forces encountered for the polyester systems. No explanation has been found for the Inability to achieve the desired porosity level. Since the coatings deposited readily, the explanation may be related to the particle size distribution of the cenospheres.

Additional studies could prove beneficial for the continued development of the cenosphere system. It was noted that the cenosphere particles had a wide variation in size. This may have resulted in poor reproducibility of the coating as well as the inability to effectively control the density of the top layer. In addition, a large proportion of the smaller particles appeared to be solid in nature which could result in an extremely closely-packed structure and contribute to the formation of the glassy phase observed in some of the cenosphere tests. Future effort should therefore include:

0 More effective particle screening. This would reduce the cenosphere particle size distribution to one more appropriate for plasma spray operations.

0 Removal of solid cenosphere particles. This would enhance the resultant abradable structure and tend to reduce the tendency towards smearing.

0 Investigation of additional fililer materials other than the cenospheres. Further work with the polyester filler is not strongly recommended.

CONCLUSION:
The application of a sacrificial filler material to provide controlled or predictable porosity in a ceramic abradable seal system offers some degree of promise. The use of a co-sprayed polyester filler material did indeed provide an impermeable, porous structure which was readily abradable. However, erosion resistance was notably lacking. Attempts to improve the erosion performance while still maintaining adequate abradability were only marginally successful in that although densities were measurably increased by $15 \%$, hardness and erosion resistance were unpredictable. Co-spraying of a cenosphere-filled system did provide acceptable erosion resistance but abradability performance did not appear to be as good as for the polyester-filled systems. A glazed wear scar appeared to be a prominent: feature of each of the cenosphere-filled iterations. Attempts to decrease the density of the abradable layer by increasing the percentage of cenospheres in the coating did not appear to be effective. Blade tip measurements made on both the polyester and cenosphere systems indicate a lower tip loss was recorded for the cenosphere-filled than for the polyester-filled system. At present, the effect of the presence of the glazed wear scar in an actual. engine configuration is unknown, particularly when successive blade tip contacts are made.

Results of the through flow leakage, or permeability tests indicate no significant leakage was present for either of the systems in any of the iterations.

Surface Roughness $\mu$-in,(RMS) (After Machining)
I-P ..... 350-400
II-P ..... 300-400
III-P ..... 270-350
I-C ..... 300-400
II-C ..... 350-400
III~C ..... 170-220
Additional Measurements: Sample I-P (Before Burnout or Machining)
Condition$\mu-\ln$. (RMS)
As Sprayed ..... 300-350
Ground ..... 80-120
Machined ..... 160-200
Table II Surface Roughness Measurements

## Hardness (Hent-Treated Condition)

| Coating System | Hardness Scale |  |
| :--- | :---: | :---: |
| I-P | $\frac{\text { R15W }}{}$ |  |
| II-P | 81. | 13 |
| III-P | 43 | 89 |
| I-C | 63 | 61 |
| II-C | 72 | 78 |
| III-C | 81 | 82 |
|  |  | 85 |

Additional Hardness Determination - I-P
(Non-lieat Treated)
Condtition ..... R1.5Y
As Sprayed ..... 73
MachIned ..... 83
Ground ..... 88
Table rit Coating System Hardness

| Coatang System Deaignation | v/0 $\mathrm{ZrO}_{2} \%$ |  | F1110r |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | $\begin{aligned} & \text { y/0 Polyegter \% } \\ & \text { Target (Measured) } \end{aligned}$ |  | v/o Cenospheres\% <br> Target (Measured) |  |
|  | Target | (Mcasured) |  |  |  |  |
| I-n | 65 | (72) | 35 | (28) | 0 | --" |
| II-P | 75 | (79) | 25 | (21) | 0 | --- |
| III-P | 80 | (83) | 20 | (17) | 0 | --- |
| I-C | 50 | (70) | 0 | --- | 50 | (30) |
| II-C | 40 | (65) | 0 | --- | 60 | (35) |
| III-C | 30 | (68) | 0 | - | 70 | (32) |
| Table IV |  | ng System | pos 1 |  |  |  |


| Senl Sybtem | $\begin{aligned} & \text { Rub Depth } \\ & \text { cm } \\ & \text { (Inch) } \end{aligned}$ | Change in Blade Length cm (Inch) | Normal Force Newtons (1bn.) | Tangential Force Newtons (1bs.) |
| :---: | :---: | :---: | :---: | :---: |
| $\mathrm{I}-\mathrm{P}-\mathrm{S}$ | $\begin{gathered} 0.013 \\ (0,005) \end{gathered}$ | 0 | -m* | $\begin{gathered} 5.12 \\ (1.15) \end{gathered}$ |
| $\mathrm{I}=\mathrm{P}-\mathrm{F}$ | $\begin{gathered} 0.053 \\ (0.021) \end{gathered}$ | $\begin{gathered} -0.005 \\ (-0.002) \end{gathered}$ | --- | $\begin{gathered} 20.82 / 47.95 \\ (4.68) /(10.78) \end{gathered}$ |
| II-P-S | $\begin{gathered} 0.038 \\ (0.015) \end{gathered}$ | $\begin{gathered} -0,0005 \\ (-0,0002) \end{gathered}$ | $\begin{aligned} & 11.61 \\ & (2.61) \end{aligned}$ | $\begin{gathered} 6.98 \\ (1.57) \end{gathered}$ |
| $\mathrm{II}-\mathrm{P}-\mathrm{F}$ | $\begin{gathered} 0.013 \\ (0.005) \end{gathered}$ | $\begin{gathered} -0.0015 \\ (-0.0006) \end{gathered}$ | $\begin{gathered} 52.22 \\ (1.1 .74) \end{gathered}$ | $\begin{aligned} & 28.24 \\ & (6.35) \end{aligned}$ |
| III-P-S | $\begin{gathered} 0.038 \\ (0.015) \end{gathered}$ | 0 | $\begin{aligned} & 25.93 \\ & (5.83) \end{aligned}$ | $\begin{aligned} & 11,30 \\ & (2,54) \end{aligned}$ |
| III-P-F | $\begin{gathered} 0.041 \\ (0.016) \end{gathered}$ | $\begin{gathered} -0.003 \\ (-0.001) \end{gathered}$ | $\begin{aligned} & 35.58 \\ & (8.0) \end{aligned}$ | $\begin{aligned} & 28.60 \\ & (6.43) \end{aligned}$ |
| $\mathrm{I}-\mathrm{C}-\mathrm{S}$ | $\begin{gathered} 0.013 \\ (0.005) \end{gathered}$ | $\begin{gathered} -0.003 \\ (-0.001) \end{gathered}$ | $\begin{aligned} & 11.25 \\ & (2.53) \end{aligned}$ | $\begin{gathered} 7.34 \\ (1.65) \end{gathered}$ |
| $\mathrm{I}-\mathrm{C}-\mathrm{F}$ | *-m | -m" | -"- | -- |
| II-C-S | $\begin{gathered} 0 . \overline{0}, \bar{y} 0 \\ (0.012) \end{gathered}$ | $\begin{gathered} -0.0005 \\ (-0.0002) \end{gathered}$ | $\begin{aligned} & 28.2 \\ & (6.3) \end{aligned}$ | $\begin{aligned} & 31.14 \\ & (7.0) \end{aligned}$ |
| II-C-F | --- | "-- | --- | --- |
| III-C-S | $\begin{gathered} 0.023 \\ (0.009) \end{gathered}$ | $\begin{gathered} -0.0015 \\ (-0.0006) \end{gathered}$ | $\begin{aligned} & 20.1 .5 \\ & (4.53) \end{aligned}$ | $\begin{aligned} & 29.80 \\ & (6.7) \end{aligned}$ |
| III-C-F | --- | -- | - | --- |
| Table V | Summary | F Abradability | Tests |  |

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Figure 2
High-speed/high-temperature abradable seal
materials test rig

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$$
\begin{gathered}
\text { c. } \quad 120 \mathrm{~min} . \text { exposure } \\
(38.1 \mathrm{gm} \text { abrasive) }
\end{gathered}
$$


a. 30 min. exposure
$(5.4 \mathrm{gm}$ abrasive $)$
b. $\quad 60 \mathrm{~min}$. exposure (45 impingement angle) Magn: 3X
(ənṭsexqe ws $L^{\circ} \dagger \mathrm{T}$ )


a. | 30 min . exposure |
| :--- |
| $(5.4 \mathrm{gm}$ abrasive) |

Figure 5 Development of accelerated er

| $\left(45^{\circ}\right.$ impingement angle) Magn: |
| :--- |

Figure 5 Development of accelerated erosion wear scar with time for standard densicy yttria-stabilized zirconia


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Permeability Test Device
Figure 7


Blade track wear scar



Incursion rate:
$.0025 \mathrm{~cm} / \mathrm{sec}$
(.001 in/sec)

Blade tip speed:
$229 \mathrm{~m} / \mathrm{sec}$
(750 ft/sec)

Blade tip condition
Figure 8 Slow incursion rate abradability test results for specimen configuration I-P Magn: 5X


Figure 9


Blade track wear scar


Incursion rate:
$.0025 \mathrm{~cm} / \mathrm{sec}$
(. $001 \mathrm{in} / \mathrm{sec}$ )

Blade tip speed:
$229 \mathrm{~m} / \mathrm{sec}$
(750 ft/sec)

Figure 10 Slow incursion rate abradability test results for
specimen configuration LII-P Magn: 5X


Rub
Direction


Blade track wear scar


Incursion rate:
$.025 \mathrm{~cm} / \mathrm{sec}$
(. $010 \mathrm{in} / \mathrm{sec}$ )

Blade tip speed:
$229 \mathrm{~m} / \mathrm{sec}$
(750 $\mathrm{ft} / \mathrm{sec}$ )

Blade tip condition
Figure 11 Fast incursion rate abradability test results for specimen configuration I-P Magn: 5X


Figure 12 Fast incursion rate abradability test results for specimen configuration II-P Magn: 5X


Figure 13
Fast incursion rate abradability test results for
specimen configuration III-P Magn: 5 X

b. $\quad 30 \mathrm{~min}$. exposure ( 12.5 gm abrasive)


d. 120 min . exposure ( 41.7 gm abrasive)

As machined plus thermal decomposition
of filler
erosion wear scar with time for coating system

120 min. exposure ( 37.8 gm abrasive)

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$$
0 \mathrm{~min} \text {. exposure ( } 7.4 \mathrm{gm} \text { abrasive) }
$$


120 min. exposure $(45.8 \mathrm{gm}$ abrasive)
 erosion wear scar





| $\Delta$ | Manuf A1 * |
| :--- | :--- |
| $\Delta$ | Manuf A2 |
| 0 | Manuf A3 |
| $\mathbf{0}$ | Manuf A4 |
| a | Manuf B1 |
| Manuf B2 |  |
| $\boldsymbol{D}$ | Manuf B3 |
| 0 | Manuf B4 |
| 0 | Manuf B5 |
| 0 | Manuf C1 |
| 0 | DDA Dual-Density Cer |
| Manuf D1 |  | Indained from NASA Project Manager


Argon Pressure Supply
Figure 18 Abradable Seal Material Permeability



Figure 19 Slow incursion rate abradability test results for specimen configuration I-C Magn: 5X

Blade track wear scar

Incursion rate:
$.0025 \mathrm{~cm} / \mathrm{sec}$
(. $001 \mathrm{in} / \mathrm{sec}$ )
Blade tip speed:
$229 \mathrm{~m} / \mathrm{sec}$
(750 ft/sec)

$$
\begin{aligned}
& \text { Slow incursion rate abradability test results for specimen } \\
& \text { configuration II-C Magn: } 5 X
\end{aligned}
$$

Figure 20


Incursion rate:
$.0025 \mathrm{~cm} / \mathrm{sec}$
(. $001 \mathrm{in} / \mathrm{sec}$ )

Blade tip speed:
$229 \mathrm{~m} / \mathrm{sec}$
(750 ft/sec)

Figure 21
Slow incursion rate abradability test results for specimen configuration III-C Magn: 5X

b. 30 min . expsosure ( 9.3 gm abrasive)


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(22.8 gm abrasive)

## $-$


a. As machined




60 min . exposure ( 33.3 gm abrasive)


Figure $25 \begin{aligned} & \text { Porosity characteristics and ceramic particle morphology of coating } \\ & \text { system I-P. }\end{aligned}$

Standard
Density Layer


Magn : 100X
a. Porosity characteristics


Magn: 1000X
b. Ceramic particle morphology (outer layer)

Figure 26 Porosity characteristics and ceramic particle morphology of coating system II-P

Standard Density Layer

a. Porosity characteristics


Magn : 1000X

Porosity characteristics and ceramic particle morphology of coating system III-P.
b. Ceramic particle morphology (outer layer)

a. Elemental zirconium analysis


Y scan line
b. Elemental yttrium analysis

Figure 28 Elemental line scan analysis of coating system II-P Magn: 200X


Mapped Zone Designation

Zone 1
Void area

Zone 2
Major: Zr
Minor: Y , Hf
Trace: $\mathrm{Ca}, \mathrm{Na}, \mathrm{Si}$

Figure 29 Mapped zones analyzed by X-ray energy dispersive analysis to identify elemental distribution in coating system IIP. Magn: 200X

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Magn: 100X


Magn: 1000X

Figure 30 Porosity characteristics and ceramic particle morphology of coating system I-C

Filled Oxide Layer


Magn: 100X
a. Porosity characteristics


Magn: 1000X

## Figure 31

Porosity characteristics and ceramic particle morphology of coating system II-C

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Filled Oxide Lyaer


Magn: 100X
a. Porosity characteristics


Magn: 1000X

Figure 32 Porosity characteristics and ceramic particle morphology of coating system III-C

a. Elemental zirconium analysis

b. Elemental yttrium analysis

Figure 33 Elemental line scan analysis of coating system I-C

Y scan line

Magn: 200X


7r scan line
a. Elemental zirconfum analysis


Figure 34 Elemental line scan analysis of coating system 1I-C Magn: 200X

