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## SUPPLEMENT TO: A COMPUTER PROGRAM FOR THE DESIGN AND ANALYSIS OF LOW-SPEED AIRFOILS

Richard Eppler and Dan M. Somers

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# SUPPLEMENT TO: A COMPUTER PROGRAM FOR THE DESIGN AND ANALYSIS OF 

LOW-SPEED AIRFOILS

Richard Eppler* and Dan M. Somers<br>Langley Research Center


#### Abstract

SUMMARY Three new options have been incorporated into an existing computer program for the design and analysis of low-speed airfoils. These options permit the analysis of airfoils having variable chord (variable geometry), a boundary-layer displacement iteration, and the analysis of the effect of single roughness elements. All three options are described in detail and are included in the FORTRAN IV computer program which is available through COSMIC.


## INTRODUCTION

A conformal-mapping method for the design of airfoils with prescribed velocity-distribution characteristics, a panel method for the analysis of the potential flow about given airfoils, and a boundary-layer method have been combined. With this combined method, airfoils with prescribed boundary-layer characteristics can be designed and airfoils with prescribed shapes can be analyzed. All three methods and the FORTRAN IV computer program for the numerical evaluation of these methods are described in reference 1.

Three new options have been incorporated into the computer program described in reference 1. The previous version of the program (ref. 1) was capable of analyzing an airfoil with a simple flap. In the present version, an option has been added which allows the analysis of an airfoil having variable chord (variable geometry). The method of reference 1 did not contain a boundary-layer displacement iteration. An iteration procedure has been included in the present version. The third option to be added permits the analysis of the effect of single roughness elements. The input for all three options is described in detail.

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[^0]Values are given in SI units.

| $c_{f}$ | boundary-layer skin-friction coefficient |
| :---: | :---: |
| c | airfoil chord, m |
| $c_{d}$ | section profile-drag coefficient |
| $c_{1}$ | section lift coefficient |
| $c_{m}$ | section pitching-moment coefficient about quarter-chord point |
| h | height of roughness element normal to surface, m |
| 15 | lower surface |
| R | Reynolds number based on free-stream conditions and airfoil chord |
| $R_{h}$ | Reynolds number based on local conditions and height of roughness element |
| U | potential-flow velocity, m/s |
| $U_{\infty}$ | free-stream velocity, m/s |
| $u_{h}$ | $x$-component of velocity in turbulent boundary-layer at height of roughness element, m/s |
| us | upper surface |
| v | local velocity on airfoil, $\mathrm{m} / \mathrm{s}$ |
| x | airfoll abscissa, $m$; axis in streamwise direction, tangential to surface |
| $x_{R}$ | chord location of roughness element, m |
| y | airfoil ordinate, m |
| a | angle of attack relative to zero-lift line, deg |
| $\triangle$ | incremental change in quantity |
| $\delta_{1}$ | boundary-layer displacement thickness, m |
| $\delta_{2}$ | boundary-layer momentum thickness, m |
| $v$ | kinematic viscosity, $\mathrm{m}^{2} / \mathrm{s}$ |

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        air density, kg/m
        shear stress at wall, kg/m.s}\mp@subsup{}{}{2
```

PROGRAM AVAILABILITY
The program is available at a nominal fee through the following organization:

Computer Software Management Information Center (COSMIC)
112 Barrow Hall, University of Georgia
Athens, Georgia 30602
Request the program by the designation PROF ILE LAR-12727.

VARIABLE GEOMETRY
The previous version of the computer program (ref. 1) allowed the shape of an airfoll analyzed by the panel method to be altered so as to correspond to the deflection of a simple flap. Thus, that version only permitted the rotation of a portion of the airfoil, the flap ${ }_{2}$ about a specified hinge point. Chord-increasing flaps were not allowed. the present version of the program can analyze this form of variable geometry. It should be noted that, while the airfoil shape which results from the exercise of this option does have an increased chord, it does not contain a slot and, thus, is still a singleelement as opposed to a multi-element airfoll. An application of this capability is described in reference 2.

FLAP Card
The variatle-geometry option is selected by setting NUPU $=1,2,3$, or 4 on the FLAP card.

NUPA, NUPE, and NUPI are neglected.
NUPU $=1$ - The F-words specify the points to be deleted. The five digits of $F_{i}$ are denoted aaabb. Points aaa through aaa $+b b$ are deleted. If $b b=00$, only point aaa is deleted.

It is recommended that the F-words be specified with decreasing values of aaa as the points after point aaa (higher point number) are renumbered. This means that aaa for $F$, should be greater than aaa for $F_{2}$ which should be greater than aaa for ${ }^{\prime} F_{3}$ and so on.

Only one FLAP card with NUPU $=1$ is allowed.

NUPU $=2$ - The F-words specify points to be added to the upper surface. The new points are added after the point on the upper surface having the greatest $x / c$ remalning after the deletions which resulted from the FLAP card with NUPU $=1$. Thus, if point 1 $(x / c=1)$ was not deleted, only points with $x / c>1$ can be added.
$0.01 F_{1}=x_{1} / c[F 5.4]$
$0.01 F_{2}=y_{1} / c[F 5.4]$
$\left(F_{3}, F_{4}\right)=\left(x_{2} / c, y_{2} / c\right)$ and so on
It should be noted that the new points must be in order of increasing $x / c$.
NUPU $=3$ - The F-words specify points to be added to the lower surface. The F-words are interpreted just as they are for a FLAP card with NUPU $=2$.

NUPU $=4$ - The F-words specify additional points to be splined in between the points available so far. The F-words are interpreted just as they are for an FXPR card. (See ref. 1, p. 45.)

It should be remembered that the points are renumbered during the execution of each of the preceding FLAP cards.

The panel method is called automatically after a FLAP card with NUPU $=4$ is read. Following this card, any other cards (in the proper sequence, of course) are allowed except another FLAP card. Only airfoil coordinates generated in the design mode or read in following an FXPR card can be altered by FLAP cards with NUPU $=1,2,3$, and 4. Thus, a FLAP card with NUPU $=1,2$, 3 , or 4 cannot follow another FLAP card.

Example
The following card sequence illustrates the use of the variable-geometry option.


The first FLAP card deletes points 52 through 61 as well as points 7, 5, 3 , and 2 (in the $x-y-v$ listing, $N=51$ through $60,6,4,2$, and 1). If the chord is to be increased, some of the points near the trailing edge should be deleted. In other words, a short distance between points is required near the new trailing edge, not the old one. The second FLAP card specifies two points for the extension of the upper surface: ( $x / c=1.1000, y / c=-0.0350$ ) and $(x / c=1.2000, y / c=-0.0900)$. The third FLAP card specifies four points for the extension of the lower surface: ( $x / c=0.8400, y / c=-0.0265$ ), $(x / c=0.9600, y / c=-0.0290),(x / c=1.0800, y / c=-0.0490)$, and $(x / c=1.2000, y / c=-0.0900)$. The fourth FLAP card inserts in the equiangularspacing mode (ref. 1) four points between points 52 and 53 , two points between points 51 and 52, two points between points 50 and 51 , two points between points 49 and 50 , two points between points 2 and 3 , and three points between points 1 and 2. The panel, method is called automatically after the fourth FLAP card.

This card sequence plots into one diagram (fig. 1) the velocity distributions for airfoil 664 with and without the variable-geometry flap extension. Two velocity distributions, each at $\alpha=0^{0}$ relative to the chord ine, are plotted. The following $x-y-v$ listings are also generated.



[^1]


The theoretical results for $c_{1}$ versus $c_{d}$ from the previous version of the computer program (ref. 1) agree remarkably well with experimental measurements. (For example, see ref. 3.) This good agreement, however, does not hold for $c_{1}$ versus $a$ or $c_{m}$ versus $\alpha_{\text {, particularly for aft-loaded airfoils. }}$ This is not surprising in that the boundary-layer displacement effect was only accounted for by reducing the lift-curve slope from its theoretical value to $2 \pi$. An improvement could therefore be expected from a more detailed analysis of the displacement effect.

There exists, however, a fundamental flaw in the philosophy of the application of displacement iterations. All displacement effects are of second order in boundary-layer theory (ref. 4). Accordingly, it is inconsistent to include the displacement effect while neglecting other pertinent second-order effects which arise from the pressure gradient normal to the surface within the boundary layer and other y-component terms in the NavierStokes equations. This flaw becomes more significant as the boundary-layer thickness increases.

At the trailing edge, difficult problems arise. The potential-flow solution yields steep pressure gradients toward the trailing edge which result in a very high slope for the displacement thickness. This high slope can result in a rapid divergence for the displacement iteration, even for high Reynolds numbers. The order (quality) of the tralling-edge treatment has a significant influence on the results. The wake solution incorporated in the present panel method gives very precise results for the 11 ft coefficients of airfoils with blunt trailing edges. It, however, also predicts steep pressure gradients toward the trailing edge which, in turn, accelerate the divergence of the displacement iteration. Moreover, this solution also clearly shows that the small region which surrounds the trailing edge has a great influence on the solution for the entire airfoil.

One solution to this divergence problem is to artificially smooth the boundary-layer displacement after each iteration. But, even if convergence is obtained and, furthermore, even if smoothing were not required for convergence, the iteration process would still be questionable due to the neglect of the second-order boundary-layer terms previously mentioned. A wake solution which minimizes the pressure gradients near the trailing edge could improve the iteration process but would not eliminate the fundamental flaw in philosophy.

The question remains as to what simple procedures can be developed to obtain at least a rough estimate of the displacement effect. As previously explained, multiple iterations are not logical. Accordingly, in the present method, only one iteration is performed. The displacement thickness is smoothed once and then added to the airfoll contour. The lift and pitchingmoment coefficients are then computed for the new contour and stored. Later the linear portions of the $c_{1}-\alpha$ and $c_{m}-\alpha$ curves are adjusted by a least-squares fit to these stored values. The separation corrections are then applied as discussed in reference 1 . Thus, only a few angles of attack require this displacement iteration. The remaining angles of attack are adjusted according to the least-squares fit. The displacement effect is considered to be linear in a. A higher-order effect cannot be expected from such a simple approach.

This simple procedure does not require much computing time. The results, of course, depend on the smoothing process. In the present version of the program, the curvature of $\delta_{1}(x)\left(i . e ., \frac{d^{2} \delta_{1}}{d x^{2}}\right)$ is 1 imited. The 1 imit can be specified in the input. This 1 imit (SLM) is preset to $\frac{1}{2} \frac{d^{2} \delta_{1}}{d x^{2}}<0.5$ (三SLM).

The single iteration is initiated by one input card, which must immediately precede an input card which initiates a boundary-layer computation (i.e., an RE , FLZW, or PLW card).

DPIT Card
NUPA, NUPE, NUPI, and NUPU are neglected.
The F-words specify the angles of attack for which a displacement iteration is performed and also the plot mode mbt. The five digits of $F_{i}$ are denoted abcde. The variable abc is interpreted as an integer n and a displacement iteration is initiated for the nth angle of attack on the preceding ALFA card. A displacement iteration is performed for each Reynolds number from the immediately following RE , FLZW, or PLW card. The variable $d$ determines the plot mode. If $d>0$, a diagram containing the airfoil contour (including the displacement thickness) and the velocity distribution for the angle of attack under consideration is plotted after each displacement iteration. The plot mode mbt is set equal to $d-1$ and is described under "DIAG Card" in reference 1 ( $p .52$ ) and reviewed below.
$d=1$ - Axes are drawn, one set of data is plotted, and the diagram is terminated (i.e., closed to further plotting).
$d=2$ - Axes are drawn, one set of data is plotted, and the diagram is open to further plotting.
d=3-No axes are drawn and one set of data is plotted into the existing diagram which is then terminated.
d $=4$ - No axes are drawn and one set of data is plotted into the existing diagram which remains open to further plotting.

If $d=2$ or 3 , the RE , FLZW, or PLW card must specify only one Reynolds number.

Up to five F-words are allowed which means that displacement iterations can be performed for up to five angles of attack.
If $F_{5}<0$, the limit for $\frac{d^{2} \delta 1}{d x^{2}}$ is set to $S L M=-0$.bcde. This new
limit is used until it is reset by another DPIT card with $\mathrm{F}_{5}<0$. Obviously, only four angles of attack can be specified on DPIT cards with $\mathrm{F}_{5}<0$.

Examples
The following card sequences illustrate some of the DPIT-card options.


After the RE card is read, displacement iterations for the first, fifth, and ninth angles of attack (i.e., $\alpha=0^{\circ}, 4^{\circ}$, and 8 relative to the zero-1ift line) are performed for both $R=2 \times 10^{\circ}$ and $R=6 \times 10^{6}$. A diagram is plotted for each displacement iteration. A potential-flow diagram (no displacement iteration) is also plotted (DIAG card). Thus, one diagram containing 10 velocity distributions (DIAG card) (fig. 2) and six diagrams containing one velocity distribution each (DPIT card) (fig. 3) are plotted. The $c_{1}-a$ and $c_{p}-\alpha$ portions of the boundary-layer summary and its plot (CDCL card) are adjusted according to the computed displacement effect.

It should be noted that each displacement iteration requires a solution from the panel method. Thus, for an airfoil having 61 points, each displacement iteration requires approximately 8 seconds CPU time on a Control Data 6600 computer.


The preceding card sequence plots one diagram (fig. 4) which contains both potential-flow and displacement-iteration shapes and velocity distributions for $\alpha=3^{\circ}$ and $7^{\circ}$. Note that only one Reynolds number is considered and that displacement iterations are only performed for $\alpha=3^{0}$ and 70 . The boundarylayer summary which follows contains the adjustments due to the computed displacement effect. AC is the adjusted angle of attack (relative to the zerolift line).


```
Summaer AIRFRIL 315 anGLE OF ATTACK RELATIVE TO THE ZERO-LIFT LINE ALPHAO - 2.qS DEUREES
* INOICATFS VELOCITY REDUCTION WITHIN BUBBLE BELON .94
    R.6000000 MU = 3
ALPHA E 6.00 DEGREES
    UPPE: \S TUEA S SEP CD
    MOME: .7525 0.0000 .0051
LOWER CL'4007 0.0000 .080 CN:.0013
CM=..0782AC:5.7A
ALPHA = 7.00 DEGPEES
    UPPER 1 STURB S SEP CD CO
    LOHER .3992 0.0000 .0053
TOTAL CL .789 CD..OC75
    CN=-.0801 AC=6.71
ALPHA 8.0S DEGREES
    US 1 S THPG S SEP CD
    UODEQ .9073 .003A .0074
    LOWER . 3978 0.0000 .0012
TOTAL CL = .076CO..0C86
    CN= -.0813 AC:7.64
ALPHA 9.OO DEGREES
    1 S TURB S SEP CD
    UPPER 1 STURS S SEP NOD
    LOWER . 3962 0.0000 .0011
TOTAL CL . .982CO..0096
CM=-.0823 AC = ..38
```


## SINGLE ROUGHNESS ELEMENTS

Recent flight and wind-tunnel experiments indicate that single roughness elements such as flap and aileron hinges and poorly faired spoilers significantly degrade the overall performance of an airplane (ref. 5). With the previous version of the program (ref. 1), only the effect of roughness on boundary-layer transition could be considered. Fixed transition points could be specified using transition mode 1 or 2, whereas premature transition due to distributed roughness or free-stream turbulence could be analyzed using transition modes greater than 3. (See "RE Card," ref. 1, p. 56.)

In the present version of the program, an option has been added which allows the analysis of the effect of single roughness elements on a turbulent as well as a laminar boundary layer. The method is described in detail in reference 5 and reviewed below.

The increase $\Delta \delta_{2}$ of the boundary-layer momentum thickness $\delta_{2}$ due to a single roughness element of height $h$ is assumed to depend only on the local roughness Reynolds number $R_{h}=\frac{u_{h} h}{v}$ where $u_{h}$ is the $x$-component of the velocity in the turbulent boundary layer at a distance $h$ from the surface. For a turbulent boundary layer, the increase of $\delta_{2}$ due to the roughness element is assumed to be

$$
\frac{\Delta \delta_{2}}{c}=0.15 \frac{u_{h}}{U_{\infty}} \frac{h}{c}
$$

where $c$ is the airfoil chord and $U_{\infty}$ is the free-stream velocity. An expression for the velocity $u_{h}$ is taken from reference 6 and transformed to the variables available in the boundary-layer method. This yields

$$
\frac{u_{h}}{U}=\sqrt{C_{f}}\left[2.17 \ln \left(\sqrt{C_{f}} \frac{U}{U_{\infty}} R \frac{h}{c}\right)+6.5\right]
$$

where $U$ is the local potential flow velocity, $C_{f}\left(=\frac{\tau_{0}}{\rho U^{2}}\right)$ is the local skinfriction coefficient, and $R\left(=\frac{U_{\infty} c}{v}\right)$ is the Reynolds number based on freestream conditions and airfoil chord. In the skin-friction coefficient, ${ }^{\top} 0$ is the shear stress at the wall and $\rho$ is the air density.

If the boundary layer is laminar at the position of the roughness element, transition is assumed to occur at that position. This is specified as $h=0$ which acts as a "latest" transition point. Upstream of that position, any transition mode except 1 or 2 (fixed transition) is allowed. This approach is more logical for many analyses than fixed transition, in front of which no other transition criterion is applied except transition following laminar separation. Fixed transition (mode 1 or 2) alone could result in delayed transition at some (high) angles of attack - an effect which is obviously not intended.

## RE Card

F-words 11-14 contain the data for single roughness elements. These words previously only contained the transition points for transition modes 1 and 2 (fixed transition).
If $\mathrm{F}_{14}<0, \mathrm{~F}$-words $11-14$ specify single roughness elements and, therefore, transition modes 1 and 2 cannot be used. The five digits of F1l - F 14 are denoted abbcc. For $F_{11}$ - Fi3, a is either a blank or $0^{4}$. For $F_{14}$, a is a minus sign $(-)$. The digits bb specify the location of the roughness element $\mathrm{X}_{\mathrm{R}}$ in percent chord. The digits cc which are read as 0.cc specify the roughness height $h$ in percent chord. Thus, roughness heights can be specified over the range $0.0001 \leq h / c \leq 0.0099$. $F_{11}$ and $F_{12}$ specify roughness elements on the upper sürface whereas $F_{13}$ and $F_{14}$ are for the lower surface. If $X_{R}=0$ is specified, no roughness element is introduced for that F -word. Thus, 0,1 , or 2 roughness elements can be specified on each surface.
$F_{11}-F_{14}$ are read from each RE card which specifies at least one Reynolds number. The roughness elements remain in effect until an RE card with $F_{2} \neq 0$ is read.

Roughness elements can only be analyzed at positions which are actual airfoil coordinates. If $x_{R}$ is specified at an $x / c$ which does not correspond to any of the airfoil coordinates, the roughness-element location is shifted to the next airfoil coordinate downstream of. $x_{R}$. If there is no airfoil coordinate close enough to the desired roughness-element location, one can be inserted using a PAN or FXPR card. (See ref. 1.)

## Examples

The following RE card specifies two roughness elements on the upper surface at $x / c=0.60$ and $x / c=0.80$, each with a height $h / c=0.0010$, and one roughness element on the lower surface at $x / c=0.70$, with a height $h / c=0.0015$.


The following RE card specifies the same roughness elements on the upper surface and none on the lower surface.

| RE |
| :---: |
|  |  |

## REFERENCES

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4. Van Dyke, Milton: Perturbation Methods in Fluid Mechanics. Applied Mathematics and Mechanics, F. N. Frenkiel and G. Temple, eds., Academic Press, Inc., 1964, pp. 132-134.
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Figure 1.- Variable geometry. (Airfoil 664; $\alpha=0^{0}$ relative to chord line)


Figure 2. - Diagram without boundary-layer di splacement iteration. ( $\alpha=0^{\circ}-9^{0}$ relative to zero-lift line)


Figure 3. - Diagram with boundary-layer displacement iteration. ( $\alpha$ relative to zero-lift line)


Figure 3. - Continued.

(c) $\alpha=4^{0} ; R=2 \times 10^{6}$.

Figure 3. - Continued.


Figure 3. - Cont inued.

(e) $\alpha=8^{0} ; R=2 \times 10^{6}$.

Figure 3. - Continued.


Figure 3. - Concluded.


Figure 4. - Diagram with and without boundary-layer displacement iteration. ( a relative to zero-lift line)


[^0]:    *Professor, University of Stuttgart, Stuttgart, West Germany.

[^1]:    $\because \because \because: \therefore$ : $\because:$
    $\because 18 \because \square$

