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(NASA-CR-164082) LORAN-C PLOTTING PROGRAM  
FOR PLOTTING LINES OF POSITION ON STANDARD  
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LORAN-C PLOTTING PROGRAM FOR PLOTTING LINES  
OF POSITION ON STANDARD CHARTS

The Loran-C plotting program was designed to plot Loran-C lines of position on any standard chart and is used in the data-collection system currently in use at Ohio University Avionics Engineering Center.

by

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## I. INTRODUCTION

The NASA Tri-University program at Ohio University is currently involved in the development of a low-cost Loran-C navigation receiver for use in general aviation aircraft. This paper describes a set of programs designed to be run on the IBM System/370 computer at Ohio University. These programs are used to plot Loran-C lines of position (LOP) on any common map or standard aviation sectional chart. The Loran-C plotting program JRPLLOT FORTRAN uses a standard Calcomp-compatible plotting subroutine package for the Hewlett-Packard 7203A graphic plotter.

This paper gives a general description of the features of the Loran-C plotting program. This program involves a simple add/subtract method to calculate the LOP. Refer to Figure 1. Included is a description on how to use the program and some methods of operation.

## II. FEATURES OF THE LORAN-C PLOTTING PROGRAM

The program will accommodate any scale of map desired. (Note: the larger the scale of the map the more distortion will occur.) The program was designed for standard aviation sectional charts; any larger scale than 1:500,000 is not recommended.

Plotting may be done on any size chart within the limitations of the Hewlett-Packard 7203A graphic plotter (10" high by 15" wide).

Four station pairs are calculated in the program's execution where, for the 9960 chain: (Master) control for W, X, Y, and Z is MALONE FL  $30^{\circ} 59' 38.7''$  N and  $85^{\circ} 10' 09.7''$  W.

Block address 1 is the W-pair  
Grangeville LA  $30^{\circ} 43' 33.0''$  N and  $90^{\circ} 49' 43.6''$  W

Block address 2 is the X-pair  
Raymondville TX (X)  $26^{\circ} 31' 55.0''$  N and  $97^{\circ} 50' 0.1''$  W

Block address 3 is the Y-pair  
Jupiter FL (Y)  $27^{\circ} 01' 58.5''$  N and  $80^{\circ} 06' 53.5''$  W

and block address 4 is the Z-pair  
Carolina Beach NC (Z)  $34^{\circ} 03' 46.0''$  N and  $77^{\circ} 54' 46.8''$  W

For best results only plot two LOP sets on a single chart.

The time difference for each line of position is placed to the top or side of the chart, depending on the angle of the LOP, along with the station pair identifier.

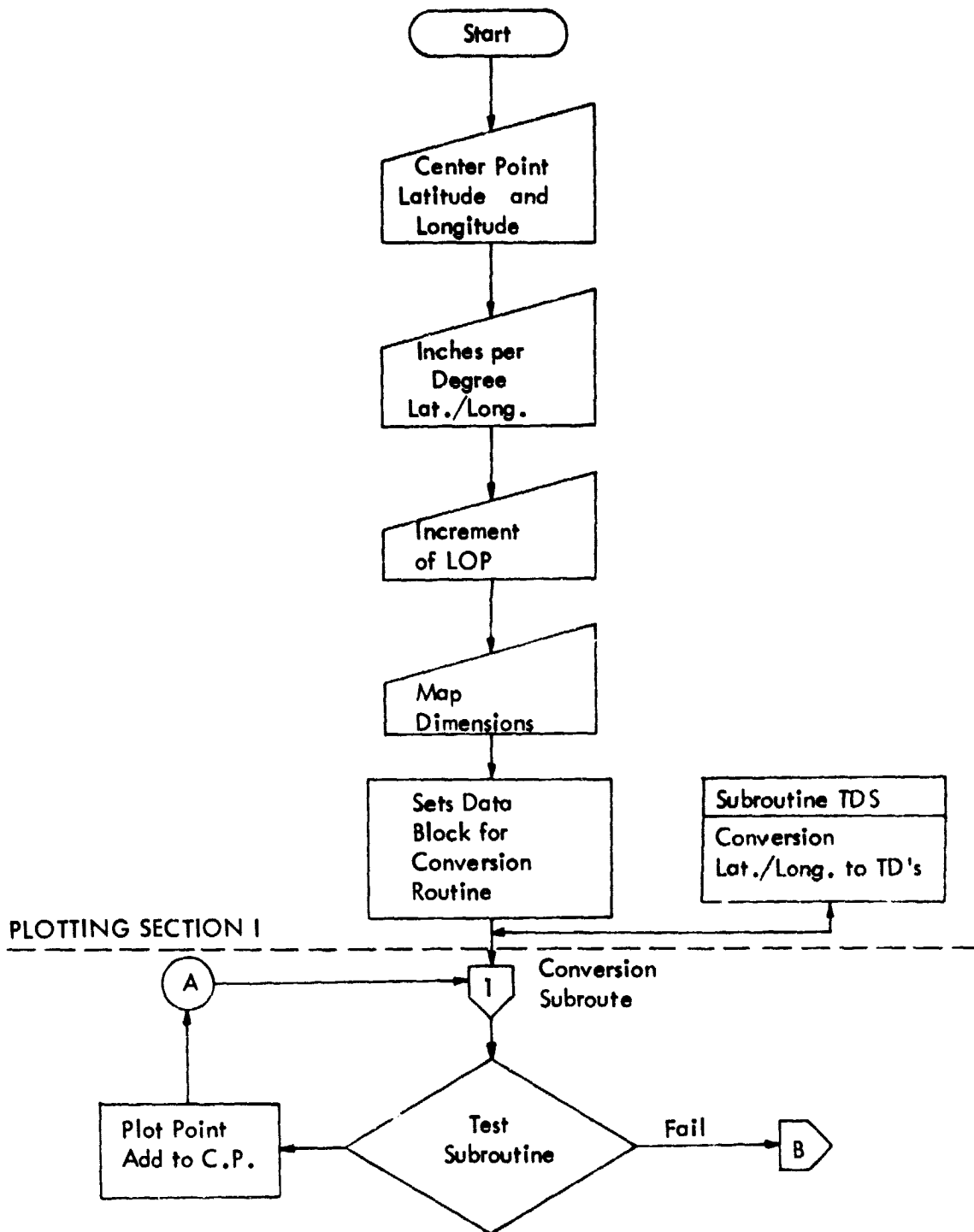


Figure 1. Flow Chart.

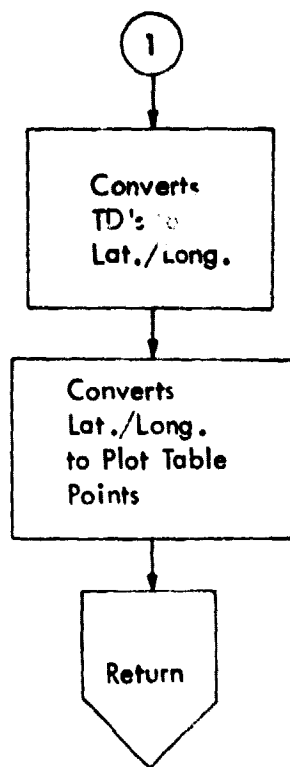


Figure 1. (Continued).

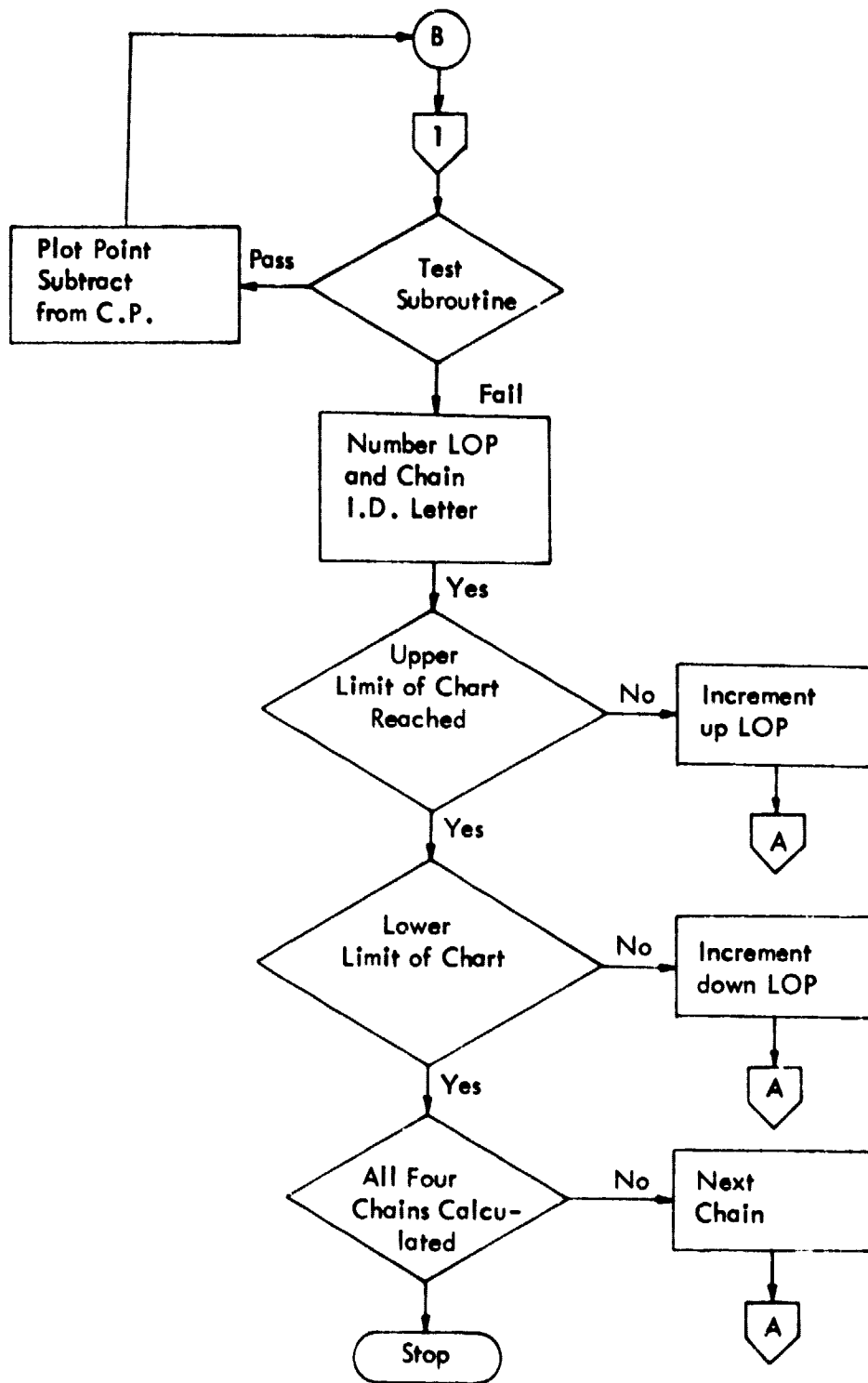


Figure 1. (Continued).

### III. ACCURACY

There are two sources of error in the system. Although the latitude/longitude conversion subprogram takes into account the curvature of the earth, the plotting routine is purely linear, therefore, the larger the scale of the chart the greater the percentage of error. The error for large scale sectionals is approximately  $\pm 10 \mu\text{sec}$ . The error for small scale geographic survey charts is  $\pm 5 \mu\text{sec}$ . The other source of error is in measurement of the parameters listed below. These errors can be reduced by methods listed in Section IV depending on the accuracy the programmer wishes to achieve.

### IV. EXECUTION

1. The center point of the chart must be measured as accurately as possible. Then, the latitude and longitude must be taken from that point. The proper form for entering into the computer is:

integer degrees                      integer minutes                      floating point seconds  
###space##space###

2. Then measure the number of inches per degree of latitude and measure the number of inches per degree of longitude. See Figure 2.

3. Then enter the increment that the lines of position should be spaced apart.

Recommended increments are:

50.0 for standard sectional charts

2.0 for geographic survey charts.

4. Enter the actual dimensions of the chart to be plotted (see Figure 2). The chart should be no larger than 11 x 15 inches and no smaller than 5 x 5 inches. These are the practical limitations of the Hewlett-Packard 7203A plotter. When the program is finished executing, the chains will be located as follows:

Block Address	Station Pair
1	W
2	X
3	Y
4	Z

It is recommended to plot all four chains on a blank sheet of paper the same size as the chart. This procedure will help the operator the actual chart.



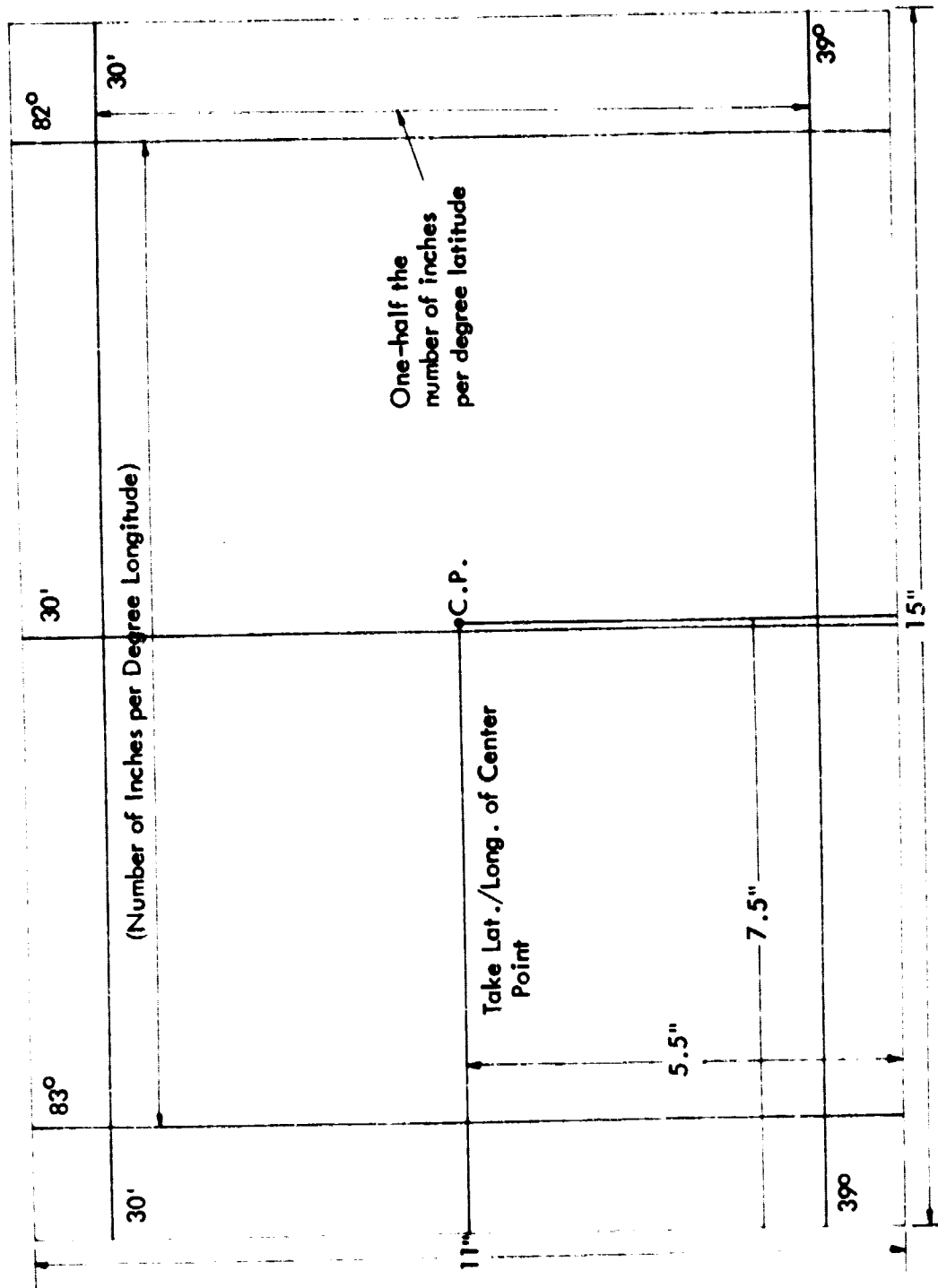


Figure 2. Sample Chart for Measurements.

## V. IMPROVING ACCURACY

This procedure should be necessary only when there is a need for extreme accuracy. To make the Loran-C plotting program more accurate, three time difference positions are needed before execution of the program: the time difference of the center point, the time differences for a point left of center, and the time differences for a point right of center. Then it is a simple matter to align the grid with the known time-difference positions. By adding or subtracting from the latitude position of the center point, the grid will shift north or south respectively. By adding or subtracting from the longitude center point position, the grid will shift west or east respectively. Another method of adjusting the grid would be to add or subtract from the inches per degree parameters. Then the grid may be expanded or contracted respectively.

## VI. SUMMARY

The Loran-C plotting program is a system of plotting routines and conversion subprograms. The program is designed to accommodate a wide range of mapping needs. The program may be easily modified to meet the specific needs of the current experiment.

## VII. ACKNOWLEDGEMENTS

The subprogram TDPOS is a program written by Joseph P. Fischer of the Ohio University Avionics Engineering Center. The program was originally written for use in Loran-C data reduction. The subprogram TDS is a modification of a program also written by Mr. Fischer. This work is supported by the National Aeronautics and Space Administration.

## VIII. BIBLIOGRAPHY

Loran-C User Handbook, United States Coast Guard, May 1980.

IX. APPENDIX

A. Listing of JRPLOT Program

```

CCCCCCCCCCCCCCCC PLOTTING LORAN-C CURVES ON SECTIONAL CHARTS CCCCCC      JR000010
  DIMENSION TD(4),TH(4),ORPOS(2),POS(2)      JR000020
  DIMENSION IBCD(2),X2(2,200),Y2(2,200)      JR000030
  DIMENSION SUE(1)      JR000040
  REAL*8 PHIR,GAMB      JR000050
  COMMON PHIR,GAMB      JR000060
  COMMON/CHATND/DEL(2),A5,A5,AD(8),DM(8),CS(8)      JR000070
CCCCCCCCCCCCCCCC INPUT SECTION CCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCC JR000080
  WRITE(6,11)      JR000090
 11  FORMAT(' ',ENTER LATITUDE OF CENTER POINT FORM ##.# ##.# ')      JR000100
  READ(5,4)IDEG,MIN,SEC      JR000110
  WRITE(6,12)      JR000120
 12  FORMAT(' ',ENTER LONGITUDE OF CENTER POINT')      JR000130
  READ(5,4)IDEG1,MIN1,SEC1      JR000140
 4   FORMAT(I3,I3,I2,I3,F3.1)      JR000150
  WRITE(6,13)      JR000160
 13  FORMAT(' ',ENTER NUMBER OF INCHES PER DEGREE LATITUDE')      JR000170
  READ(5,5)R      JR000180
  WRITE(6,14)      JR000190
 14  FORMAT(' ',ENTER NUMBER OF INCHES PER DEGREE LONGITUDE')      JR000200
  READ(5,5)R      JR000210
 5   FORMAT(F7.4)      JR000220
  WRITE(6,15)      JR000230
 15  FORMAT(' ',INPUT INCREMENT BETWEEN L.O.P. ')      JR000240
  READ(5,5)XINC      JR000250
  XINC2=XINC      JR000260
  IF(XINC.GT.10.0)XINC2=10.0      JR000270
  R=R*(-1.0)      JR000280
  YIP=IDEG+(MIN+SEC/60.0)/60.0      JR000290
  YI21=IDEG1+(MIN1+SEC1/60.0)/60.0      JR000300
  CALL PLOTS(SUE,1,11)      JR000310
CCCCCCCCCCCCCCCC MAP DIMENSIONS CCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCC JR000320
  WRITE(6,1)      JR000330
 1   FORMAT(' ',ENTER HORIZONTAL DIMENSION')      JR000340
  READ(5,2)XLAT      JR000350
 2   FORMAT(F6.2)      JR000360
  WRITE(6,3)      JR000370
 3   FORMAT(' ',ENTER VERTICAL DIMENSION')      JR000380
  READ(5,2)XLONG      JR000390
  XLAT=XLAT-0.375      JR000400
  XLONG=XLONG-1.0      JR000410
  PHIR=(IDEG+(MIN+SEC/60.0)/60.0)*3.14159265/180.      JR000420
  GAMB=(IDEG1+(MIN1+SEC1/60.0)/60.0)*3.14159265/180.      JR000430
  YCP=XLAT/2.0      JR000440
  YCP1=XLONG/2.0      JR000450
CCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCC JR000460
CCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCC JR000470
  CALL TOS(TD)      JR000480
  ORPOS(1)=IDEG+(MIN+SEC/60.0)/60.0      JR000490
  ORPOS(2)=IDEG1+(MIN1+SEC1/60.0)/60.0      JR000500
  WRITE(6,10)IDEG,MIN,SEC,IDEG1,MIN1,SEC1      JR000510
 10  FORMAT(' ',LATITUDE=' ',I2,' ',I2,' ',I3,F5.2,' LONGITUDE=' ',I2      JR000520
  >,' ',I2,' ',I3,F5.2)      JR000530
  IF(A.GT.20.0)GO TO 45      JR000540
  DO 40 K=1,4,I      JR000550

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	K1=TD(K)/10	JR000560
	K1=K1+10	JR000570
	C=TD(K)-K1	JR000580
	IF(C-5.0)20,30,30	JR000590
20	TD(K)=TD(K)-C	JR000600
	GOTO 40	JR000610
30	TD(K)=TD(K)+(10.0-C)	JR000620
40	CONTINUE	JR000630
45	WRITE(6,50)(TD(K),K=1,4)	JR000640
50	FORMAT(' ', 'TD5=', 4F15.2)	JR000650
	DO 2000 I7=1,5,1	JR000660
	CC	JR000670
	CCCCCCCCCCCCCCCCCCCC DATA ALLOCATION CCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCC	JR000680
	IF(I7.GE.5)GOTO 3000	JR000690
	J7=0	JR000700
	IF(I7-2)90,100,110	JR000710
90	I=1	JR000720
	J=2	JR000730
	I2=1	JR000740
	J2=2	JR000750
	CALL DATAWX	JR000760
	GOTO 130	JR000770
100	I=2	JR000780
	J=1	JR000790
	I2=2	JR000800
	J2=1	JR000810
	CALL DATAWX	JR000820
	GOTO 130	JR000830
110	IF(I7.EQ.4)GOTO 120	JR000840
	I=3	JR000850
	J=2	JR000860
	I2=2	JR000870
	J2=1	JR000880
	CALL DATAWX	JR000890
	GOTO 130	JR000900
120	I=4	JR000910
	J=2	JR000920
	I2=2	JR000930
	J2=1	JR000940
	CALL DATAWX	JR000950
130	IF(ORPOS(2).GT.76.0)CALL NEWDATE(I7,I,I2,J,J2)	JR000960
	IC=0	JR000970
	IR=0	JR000980
	TH(I2)=TD(I)	JR000990
	TH(J2)=TD(J)	JR010000
	IRFN=3	JR010010
	CC	JR010020
	CC PLOTTING SECTION 1 CCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCC	JR010030
140	CALL CONVERTH(TH, POS, ORPOS, [FORP09, YCP, YCP1, YIP, YIP1, X, Y, R, A])	JR010040
	IC=IC+1	JR010050
	Y2(I,IC)=Y	JR010060
	X2(I,IC)=X	JR010070
	I3=0	JR010080
	CALL TEST(XLAT, YLDNC, X, Y, I3, [FORP09])	JR010090
	IF(I7.GE.1)GOTO 140	JR010100

```

CALL PLOT(X,Y,IPFN)
TH(J2)=TH(J2)+XINC2
IPFN=2
160 IF(I2-1)160,900,900
CCCCCCCCCCCCCCCCCCCCCCCCCC PLOTTING SECTION 2 CCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCC
900 I3=0
DPPDS(1)=IDFG+(MIN+SEC/60.0)/60.0
DPPDS(2)=IDFG1+(MIN1+SEC1/60.0)/60.0
TH(J2)=TD(J)
IPFN=3
GOTO 915
910 TH(J2)=TH(J2)-XINC2
915 CALL CONVER(TH,PDS,DPPDS,IFRPP,VCP,VCP1,VIP,XIP1,X,Y,R,A)
IR=IR+1
Y2(2,IR)=Y
X2(2,IR)=X
I3=0
CALL TEST(XLAT,XINC,X,Y,I3,IFRPP)
IF(I3.GE.1)GOTO 930
CALL PLOT(X,Y,IPFN)
IPFN=2
930 IF(I3-1)910,1000,1000
CCCCCCCCCCCCCCCCCCCCCCCCCC NUMBERING SECTION CCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCC
CCCCCCCCCCCCCCCCCCCCCCCCCC
1000 HEIGHT=0.1
IF(IC.LT.20)GOTO 1005
GOTO 1006
1005 DELTAY=X2(2,(IR/2))-Y2(2,(IR/3))
DELTAY=Y2(2,(IR/2))-Y2(2,(IR/3))
IP=2
GOTO 1007
1006 DELTAY=X2(1,(IC/2))-X2(1,(IC/3))
DELTAY=Y2(1,(IC/2))-Y2(1,(IC/3))
IP=1
1007 ANGLE=ATAN2(DELTAY,DELTAY)
ANGLE=ABS((ANGLE+180.)/3.14159265)
IF(((ANGLE.LE.45.).OR.(ANGLE.GE.315.)).OR.((ANGLE.GE.135.)
>.AND.(ANGLE.LE.225.)))IPOS1=1
IF(((ANGLE.GT.45.).AND.(ANGLE.LT.135.)).OR.((ANGLE.GT.225.)
>.AND.(ANGLE.LT.315.)))IPOS1=2
1008 NPLACF=0
ANGLE=1.0
NCHAR=0
FNUM=TH(J2)
IPOS(1)=101+IP
IF(IPOS1-2)1020,1011,1011
1011 XDOWN=1.0
CALL NUMBER(X2(1,IC),(XLAT-XDOWN),HEIGHT,FNUM,ANGLE,NPLACF)
CALL SYMBOL((X2(1,IC)+0.2),(XLAT-(XDOWN-0.2)),HEIGHT,IPOS(1),ANGLE
>,NCHAR)
GOTO 1030
1020 CALL NUMBER(0,2,Y2(2,IR),HEIGHT,FNUM,ANGLE,NPLACF)
CALL SYMBOL(0,R,Y2(2,IR),HEIGHT,IPOS(1),ANGLE,NCHAR)
1030 IC=0
IR=0

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IF(J7.EQ.1)GOTO 2010
CCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCC JRP01660
CCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCC JRP01670
CCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCC INCREMENT UP CCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCC JRP01680
1010 TH(I2)=TH(I2)+XINC JRP01690
      TH(J2)=TD(J) JRP01700
      IPEN=3 JRP01710
      CALL CONVER(TH,POS,DRPOS,TERROR,YCP,XCPI,YIP,XIPI,X,Y,R,A) JRP01720
      I3=0 JRP01730
      CALL TEST(XLAT,XLONG,X,Y,I3,TERROR) JRP01740
      IF(I3-1)140,2000,2000 JRP01750
CCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCC INCREMENT DOWN CCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCC JRP01760
2000 TH(I2)=TD(I) JRP01770
      J7=1 JRP01780
      I3=0 JRP01790
2010 TH(I2)=TH(I2)-XINC JRP01800
      TH(J2)=TD(J) JRP01810
      IPEN=3 JRP01820
      CALL CONVER(TH,POS,DRPOS,TERROR,YCP,XCPI,YIP,XIPI,X,Y,R,A) JRP01830
      I3=0 JRP01840
      CALL TEST(XLAT,XLONG,X,Y,I3,TERROR) JRP01850
      IF(I3-1)140,2999,2999 JRP01860
CCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCC JRP01870
2999 CALL PLOT(0.0,0.0,-3) JRP01890
3000 CALL PLOT(0.0,0.0,999) JRP01890
      STOP JRP01900
      END JRP01910
      SUBROUTINE TDS(TD) JRP01920
CCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCC DATA FOR TIME DIFF. CONVERSION CCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCC JRP01930
      DIMENSION TD(4) JRP01940
      REAL*8 PHIM,GAMM,PHIW,GAMW,PHIX,GAMX,PHIY,GAMY,PHIZ,GAMZ JRP01950
      DATA PHIM,GAMM/0.7455002761,1.340870724/ JRP01960
      DATA PHIW,GAMW/0.8169491590,1.185559303/ JRP01970
      DATA PHIX,GAMX/0.7200063971,1.221345098/ JRP01980
      DATA PHIY,GAMY/0.5945057338,1.359840319/ JRP01990
      DATA PHIZ,GAMZ/0.6955476439,1.526928009/ JRP02000
      DATA CDRW/1.379724E4/ JRP02010
      DATA CDRX/2.696991E4/ JRP02020
      DATA CDRY/4.222161E4/ JRP02030
      DATA CDRZ/5.716205E4/ JRP02040
      TDM=ARC(PHIM,GAMM) JRP02050
      TD(1)=CDRW+ARC(PHIW,GAMW)-TDM JRP02060
      TD(2)=CDRX+ARC(PHIX,GAMX)-TDM JRP02070
      TD(3)=CDRY+ARC(PHIY,GAMY)-TDM JRP02080
      TD(4)=CDRZ+ARC(PHIZ,GAMZ)-TDM JRP02090
      RETURN JRP02100
CCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCC JRP02110
CCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCC TESTING ROUTINE CCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCC JRP02120
      END JRP02130
      SUBROUTINE TEST(XLAT,XLONG,X,Y,I3,TERROR) JRP02140
      IF(Y.GE.(XLAT-1.5))I3=1 JRP02150
      IF(Y.LE.1.375)I3=1 JRP02160
      IF(X.GE.(XLONG-1.0))I3=1 JRP02170
      IF(X.LE.1.5)I3=1 JRP02180
      IF(TERROR.EQ.-1)I3=2 JRP02190
      RETURN JRP02200

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CC JRP02210  
CCCCCCCCCCCCCCCCCCCCCCCCCCCCCC DATA FOR LAT. , LONG CONVERSION CCCCCCCCCCCC JRP02220

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END JRP02230
SUBROUTINE DATAW JRP02240
COMMON/CHAIND/DEL(2),A5,A6,AD(8),DM(8),CS(8) JRP02250
DEL(1)=11.0E3 JRP02260
DEL(2)=25.0E3 JRP02270
A5=2.1275406E4 JRP02280
A6=2.1203281E4 JRP02290
AD(1)=42.0 JRP02300
AD(2)=76.0 JRP02310
AD(3)=46.0 JRP02320
AD(4)=67.0 JRP02330
AD(5)=42.0 JRP02340
AD(6)=76.0 JRP02350
AD(7)=41.0 JRP02360
AD(8)=69.0 JRP02370
DM(1)=42.0 JRP02380
DM(2)=49.0 JRP02390
DM(3)=49.0 JRP02400
DM(4)=55.0 JRP02410
DM(5)=42.0 JRP02420
DM(6)=49.0 JRP02430
DM(7)=15.0 JRP02440
DM(8)=59.0 JRP02450
CS(1)=50.47 JRP02460
CS(2)=34.44 JRP02470
CS(3)=27.86 JRP02480
CS(4)=39.16 JRP02490
CS(5)=50.47 JRP02500
CS(6)=34.44 JRP02510
CS(7)=11.99 JRP02520
CS(8)=40.51 JRP02530
RETURN JRP02540
END JRP02550
SUBROUTINE DATAW JRP02560
COMMON/CHAIND/DEL(2),A5,A6,AD(8),DM(8),CS(8) JRP02570
DEL(1)=25.0E3 JRP02580
DEL(2)=39.0E3 JRP02590
A5=2.128260E4 JRP02600
A6=2.121045E4 JRP02610
AD(1)=42.0 JRP02620
AD(2)=76.0 JRP02630
AD(3)=41.0 JRP02640
AD(4)=69.0 JRP02650
AD(5)=42.0 JRP02660
AD(6)=76.0 JRP02670
AD(7)=34.0 JRP02680
AD(8)=77.0 JRP02690
DM(1)=42.0 JRP02700
DM(2)=42.0 JRP02710
DM(3)=15.0 JRP02720
DM(4)=59.0 JRP02730
DM(5)=42.0 JRP02740
DM(6)=49.0 JRP02750

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DM(7)=3.0
DM(8)=54.0
CS(1)=50.47
CS(2)=34.44
CS(3)=11.98
CS(4)=40.51
CS(5)=50.47
CS(6)=33.44
CS(7)=45.61
CS(8)=47.20
RETURN
END
SUBROUTINE DATAY7
COMMON/CHAIND/DEL(2),A5,A6,AD(8),DM(8),CS(8)
DEL(1)=39.0E3
DEL(2)=54.0E3
A5=2.129260E4
A6=2.121045E4
AD(1)=42.0
AD(2)=76.0
AD(3)=34.0
AD(4)=77.0
AD(5)=42.0
AD(6)=76.0
AD(7)=39.0
AD(8)=87.0
DM(1)=42.0
DM(2)=49.0
DM(3)=03.0
DM(4)=54.0
DM(5)=42.0
DM(6)=49.0
DM(7)=51.0
DM(8)=29.0
CS(1)=50.47
CS(2)=34.44
CS(3)=45.96
CS(4)=46.76
CS(5)=50.47
CS(6)=34.44
CS(7)=07.46
CS(8)=12.14
RETURN
END
SUBROUTINE NEWDAT(I7,I,I2,I,J2)
COMMON/CHAIND/DEL(2),A5,A6,AD(8),DM(8),CS(8)
IF(I7-2)10,20,30
10 I=1
   J=2
   I2=1
   J2=2
   CALL DATAWX
   GOT040
20 I=2
   J=3

```

```

JRP02760
JRP02770
JRP02780
JRP02790
JRP02800
JRP02810
JRP02820
JRP02830
JRP02840
JRP02850
JRP02860
JRP02870
JRP02880
JRP02890
JRP02900
JRP02910
JRP02920
JRP02930
JRP02940
JRP02950
JRP02960
JRP02970
JRP02980
JRP02990
JRP03000
JRP03010
JRP03020
JRP03030
JRP03040
JRP03050
JRP03060
JRP03070
JRP03080
JRP03090
JRP03100
JRP03110
JRP03120
JRP03130
JRP03140
JRP03150
JRP03160
JRP03170
JRP03180
JRP03190
JRP03200
JRP03210
JRP03220
JRP03230
JRP03240
JRP03250
JRP03260
JRP03270
JRP03280
JRP03290
JRP03300

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    I2=1                                JR003310
    J2=2                                JR003320
    CALL DATAYV                          JR003330
    GOTO 40                              JR003340
30  IF(I7.EQ.4)GOTO 35                 JR003350
    I=3                                  JR003360
    J=4                                  JR003370
    I2=1                                 JR003380
    J2=2                                 JR003390
    CALL DATAY7                          JR003400
    GOTO 40                              JR003410
35  I=4                                  JR003420
    J=3                                  JR003430
    I2=2                                 JR003440
    J2=1                                 JR003450
    CALL DATAYZ                          JR003460
40  RETURN                               JR003470
CCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCJR003480
CCCCCCCCCCCCCCCCCCCCCONVERSION ROUTINE CCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCJR003490
    END                                   JR003500
    SUBROUTINE CONVER(TH,POS,ORPOS, IERROR,VCP,YCP1,YIP,XIP,X,Y,R,A) JR003510
    DIMENSION TH(4),POS(2),ORPOS(2)    JR003520
    CALL TORPOS(TH,POS,ORPOS, IERROR) JR003530
    DO 10 K=1,2,1                       JR003540
10  ORPOS(K)=POS(K)                     JR003550
    Y=((POS(2)-YIP)*R)+YCP1              JR003560
    Y=((POS(1)-YIP)*A)+YCP              JR003570
20  RETURN                               JR003580
CCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCJR003590
    END                                   JR003600

```

B. Listing of TDPOS Program

```

SUBROUTINE T0005(T4,POS,ORPOS,(EPP00)
DIMENSION (OSV(2),OSV(2),ANG(8),AD(8),OM(8),CS(8),OTS(2),ZTWO(2),ET0000020
:WM(2),DEL(2),IDP(2),ORO(2),OPM(2),TM(2),A(11),B(11),C(11),D(11),E(T0000030
:11),CC(11),TM(2),RLEM(2),REDEL(2),RAPP(2),RETA(2),OMG(2),TWO(2),IDT000040
:PO(2),ORPOS(2)
DATA A1/24.0305/,A2/-0.40759/,A3/3.46776E-3/,B1/0.510483/,B2/-0.01T0000070
:1402/,B3/0.001760/,RO/L.745329E-2/,OM/2.008892E-4/,OS/4.949137E-6/T0000080
:,PI/3.1415927/,A4/2.006912E2/
COMMON/CHAIND/DEL,AS,A6,AD,OM,CS
BEGIN TIME DIFFERENCE TO POSITION CONVERSION.
DO 1 I=1,2
IDP(I)=ORPOS(I)
ORO(I)=IDP(I)
1 OPM(I)=(ORPOS(I)-ORO(I))*60.0
EPP00=1
A10=(A5+A5-A6*A6)/(A5*A5)
A14=1.0-A6/A5
A50=(1.0+A14+A14*A14)
A51=(A50-1.0)
A52=(A14+A14)/2.0
A53=-A51/2.0
A54=(A14+A14)/16.0
A55=(A14+A14)/2.0
A56=A14*A14
A57=A56*1.25
A58=A56/4.0
DO 128 K=1,8
IF(AD(K))124,126,125
124 ANG(K)=PO*AD(K)-OM*OM(K)-OS*CS(K)
GO TO 128
126 ANG(K)=PO*AD(K)+OM*OM(K)+OS*CS(K)
128 CONTINUE
A12=(ANG(1)-ANG(5)+ANG(2)-ANG(6))
A12=ABS(A12)
IF(A12-0.00001)7,7,8
7 A11=-1.0
GO TO 9
8 A11=1.0
APPROXIMATE POSITIONS AND STATION COORDINATES.
9 F(1)=ANG(1)
F(2)=ANG(2)
CC(1)=ANG(3)
CC(2)=ANG(4)
F(3)=SIN(F(1))
F(4)=COS(F(1))
F(5)=F(3)/F(4)
F(8)=(F(5))*(1.0-A14)
A62=ATAN(F(8))
F(6)=SIN(A62)

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OF POOR QUALITY

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C(7)=COS(A62)
CC(3)=SIN(CC(1))
CC(4)=COS(CC(1))
CC(5)=CC(3)/CC(4)
CC(8)=(CC(5))*(1.0-A14)
A62=ATAN(CC(8))
CC(6)=SIN(A62)
CC(7)=COS(A62)
I=1
GO TO 530
15 C(9)=A35
F(10)=A66
F(11)=A67
DO 17 J=1,11
A(J)=F(J)
17 B(J)=CC(J)
F(1)=ANG(5)
F(2)=ANG(6)
CC(1)=ANG(7)
CC(2)=ANG(8)
F(3)=SIN(F(1))
F(4)=COS(F(1))
F(5)=F(3)/F(4)
F(9)=(F(5))*(1.0-A14)
A62=ATAN(F(9))
F(6)=SIN(A62)
F(7)=COS(A62)
CC(3)=SIN(CC(1))
CC(4)=COS(CC(1))
CC(5)=CC(3)/CC(4)
CC(8)=(CC(5))*(1.0-A14)
A62=ATAN(CC(8))
CC(6)=SIN(A62)
CC(7)=COS(A62)
I=2
GO TO 530
19 F(21)=A35
F(10)=A66
F(11)=A67
DO 21 J=1,11
C(J)=F(J)
21 D(J)=CC(J)
TM(1)=A(10)+A(11)
TM(2)=C(10)+C(11)
DO 45 M=1,2
RETA(M)=TM(M)
REFI(M)=RETA(M)+REFI(M)
45 BLEW(M)=RETA(M)+REFI(M)
IOSV(1)=99999
IOSV(2)=99999
ITPR=0
82 SDR=DRH(1)+DRH(1)+DRH(2)+DRH(2)
IF(SDR) 83,84,87
83 DO 30 K=1,2
IF(DRH(K)) 32,34,34

```

T0202560  
T0202570  
T0202580  
T0202590  
T0202600  
T0202610  
T0202620  
T0202630  
T0202640  
T0202650  
T0202660  
T0202670  
T0202680  
T0202690  
T0202700  
T0202710  
T0202720  
T0202730  
T0202740  
T0202750  
T0202760  
T0202770  
T0202780  
T0202790  
T0202800  
T0202810  
T0202820  
T0202830  
T0202840  
T0202850  
T0202860  
T0202870  
T0202880  
T0202890  
T0202900  
T0202910  
T0202920  
T0202930  
T0202940  
T0202950  
T0202960  
T0202970  
T0202980  
T0202990  
T0203000  
T0203010  
T0203020  
T0203030  
T0203040  
T0203050  
T0203060  
T0203070  
T0203080  
T0203090  
T0203100

```

32 RANR(K)=RNR*ORR(K)-24*TRM(K)
GO TO 30
34 RANR(K)=RNR*ORR(K)+RNR*TRM(K)
37 CONTINUE
F(1)=RANR(1)
F(2)=RANR(2)
A2R=-1.0
94 F(3)=SIN(F(1))
F(4)=COS(F(1))
F(5)=F(3)/F(4)
F(8)=(F(5))*(1.0-A14)
A62=ATAN(F(8))
F(6)=SIN(A62)
F(7)=COS(A62)
DO 96 J=1,9
96 CC(J)=C(J)
I=3
GO TO 500
90 C1=A35
C2=A44
C3=A45
C101=A47
DO 92 J=1,9
92 CC(J)=C(J)
I=4
GO TO 530
95 C4=A35
C5=A44
C6=A45
C104=A47
DO 97 J=1,9
97 CC(J)=C(J)
I=5
GO TO 530
55 C7=A35
C8=A44
C9=A45
C107=A47
IF(A11)52,99,52
53 C10=C7
C11=C8
C12=C9
C110=C107
DO 63 J=1,9
63 CC(J)=C(J)
I=6
GO TO 530
65 C7=A35
C8=A44
C9=A45
C107=A47
C13=TH(2)-C(10)-C(11)-C101+C104-C51(2)
C17=C13*A4
C18=TH(1)-A(10)-A(11)-C110+C107-C51(1)
C23=C13*A4

```

```

C23=C1-C17
C24=C4
C25=C7+C22
C26=C10
C27=(C2-C5)*(C25-C24)+(C23-C26)*(C11-C9)
C28=(C2-C5)*(C12-C9)+(C3-C6)*(C8-C11)
C30=C27/C29
C28=(C23-C24+C30*(C3-C6))/(C5-C2)
GO TO 130
52 C13=TM(2)-C(10)-C(11)-C101+C106-DE(2)
C17=C13+A4
C19=TM(1)-A(10)-A(11)-C107+C106-DEL(1)
C22=C19*A4
C23=C1-C17
C24=C4
C25=C7-C22
C27=(C2*(C25-C24)+C23*(C5-C8)+C9*(C24-C5+C25)
C28=(C2*(C4-C9)+C3*(C8-C5)+C5*(C9-C8+C6)
C30=C27/C29
C28=(C23-C24+C30*(C3-C6))/(C5-C2)
130 C31=(A5+A4*(1.0-A17))/(1.0-A10*(F(3)+F(31))+1.5
C32=(A5+A4)/(1.0-A10*(F(3)+F(31))+0.5
C33=(C32/C31)
C34=(-C28/(C32+F(4)))
F(1)=F(1)+C33
F(2)=F(2)+C34
IF(A20)132,99,134
132 A29=1.0
GO TO 84

```

Z77701640  
Z77701670  
Z77701690  
Z77701700  
Z77701710  
Z77701720  
Z77701730  
Z77701740  
Z77701750  
Z77701760  
Z77701770  
Z77701780  
Z77701790  
Z77701800  
Z77701810  
Z77701820  
Z77701830  
Z77701840  
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Z77701890  
Z77701900  
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Z77701970  
Z77701980  
Z77701990  
Z77702000  
Z77702010  
Z77702020  
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Z77702040  
Z77702050  
Z77702060  
Z77702070  
Z77702080  
Z77702090  
Z77702100  
Z77702110  
Z77702120  
Z77702130  
Z77702140  
Z77702150  
Z77702160  
Z77702170  
Z77702180  
Z77702190  
Z77702200

C -  
C - CONVERSION DONE, RETURN TO DISTANCE-READING ROUTINE.  
C -

```

000 IF(IOSV(1).NE.IWD(1))GO TO 7713
IF(IOSV(2).NE.IWD(2))GO TO 7713
IF(IAS(IOSV(1))-FWM(1)).GT.0.1)GO TO 7713
IF(IAS(IOSV(2))-FWM(2)).GT.0.1)GO TO 7713
IOP(1)=IOP(1)+1
DO 839 I=1,2
Z[IWD(I)]=IWD(I)
832 POS(I)=Z[IWD(I)]+FWM(I)/50.0
RETURN

```

C -  
C - CONTINUE ITERATIONS.  
C -

```

7713 DO 7717 M=1,2
OPD(M)=0.0
OPM(M)=0.0
OSV(M)=FWM(M)
7717 IOSV(M)=IWD(M)
ITER=ITER+1
IF(ITER.LT.100)GO TO 82
ITERDDE=-1
RETURN
134 OMC(1)=F(1)
OMC(2)=F(2)

```

```

DO 4840 M=1,2
W=OMG(M)/OD
IWD(M)=W
FWD=IWD(M)
OWD=W-FWD
FWM=OWD*60.0
CWM(M)=ABS(FWM)
IF(FWM(M)-50.0005)4840,4810,4810
4810 FWM(M)=0.0
IF(IWD(M))4820,4830,4830
4820 IWD(M)=IWD(M)-1
GO TO 4840
4830 IWD(M)=IWD(M)+1
4840 CONTINUE
GO TO 300

C -
C - CALCULATION OF INVERSE VARIABLES.
C -
500 A50=-CC(2)
A60=-F(2)
C35=A50-A60
C36=ABS(C35)
IF(C35-2)501,502,502
502 A16=2.7801-C36
GO TO 505
501 A16=C36
505 IF(A16)506,507,506
507 A16=0.0000005
506 A17=SIN(A16)
A19=COS(A16)
A20=F(6)*CC(6)
A21=F(7)*CC(7)
A22=(A17*CC(7))*2+(CC(6)*F(7)-F(6)*CC(7)+A19)*2*7.5
A23=(A20*A17)/A22
A24=1.7-A23*A23
A25=ARCSIN(A22)
A26=A25*A25
A27=1.7/A22
A28=A21/A22
A29=A24*A24
A30=(A57*A25)+A17*(A51*A22-A52*A26*A27)
A31=A24*(A53*A25+A53*A22*A21+A52*A26*A28)
A32=A19*A17*(-A52*A21*A22)
A33=A27*(A54*A25+A54*A21+A22-A52*A26*A28-A55*A27*(A21**2))
A34=A19*A24*(A52*A26*A27+A52*A22*A21*A21)
A35=(A37+A31+A32+A33+A34)*A6*A4
A36=(A51*A25+A17*(-A52*A22-A14*A14*A26*A27)
A37=A24*(-A57*A25+A58*A22*A21+A14*A14*A24*A28)
A38=(A36+A37)*823+A17
A39=SIN(A38)
A40=COS(A38)
A41=(CC(6)*F(7)-A47*F(6)*CC(7))/(A37*CC(7))
IF(A41)510,500,510
509 A41=0.0000005

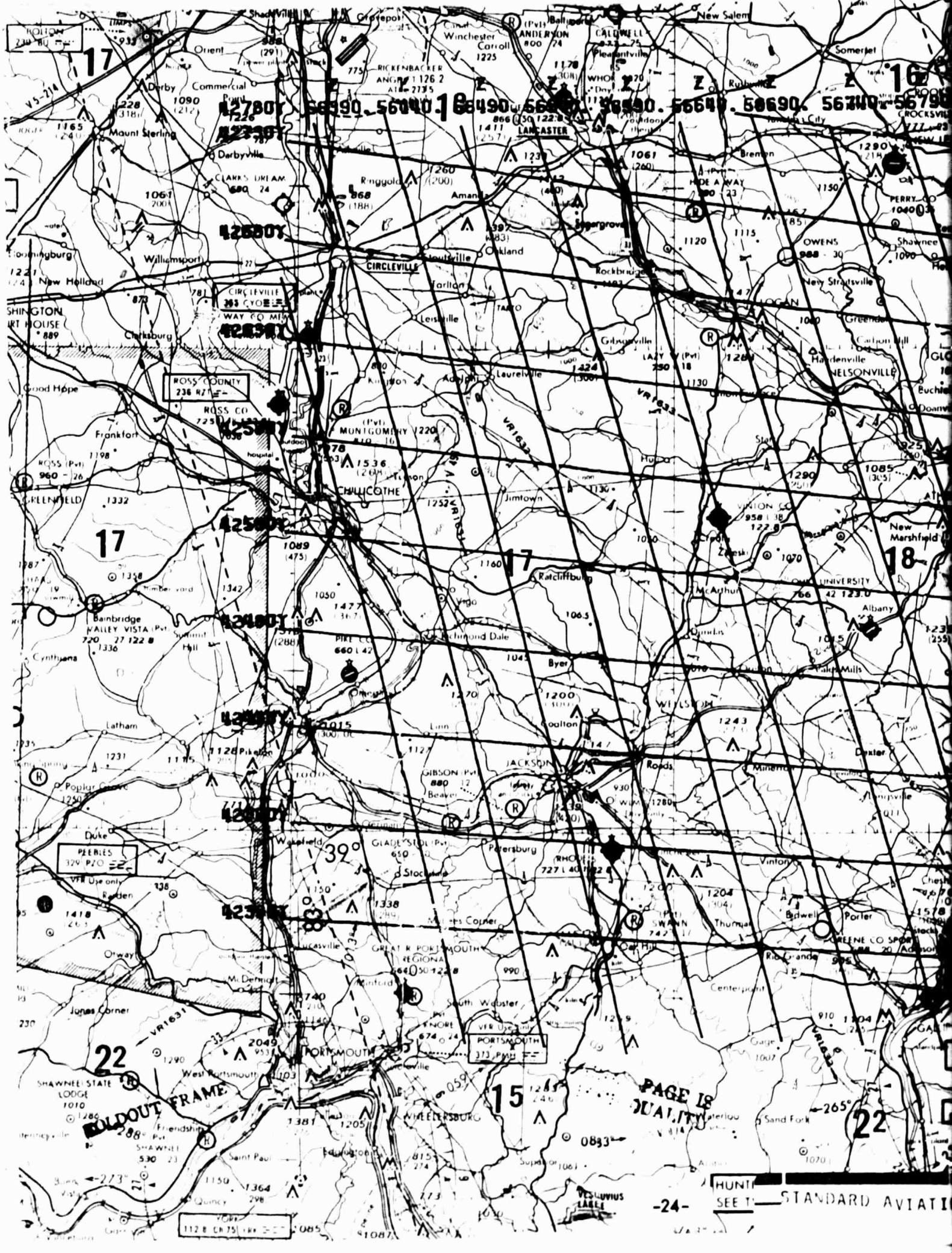
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TDD02210  
TDD02220  
TDD02230  
TDD02240  
TDD02250  
TDD02260  
TDD02270  
TDD02280  
TDD02290  
TDD02300  
TDD02310  
TDD02320  
TDD02330  
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TDD02670  
TDD02680  
TDD02690  
TDD02700  
TDD02710  
TDD02720  
TDD02730  
TDD02740  
TDD02750



510	A42=1.0/A41	Z0002740
	A43=ATAJ(A42)	Z0002770
	IF(C35)515,514,514	Z0002790
514	IF(C35-2)511,512,512	Z0002800
511	IF(A41)520,521,521	Z0002830
520	A43=01+A43	Z0002890
	GO TO 521	Z0002920
512	IF(A41)517,518,519	Z0002930
515	IF(C35+01)511,511,514	Z0002940
516	IF(A41)517,519,518	Z0002950
517	A43=01-A43	Z0002960
	GO TO 521	Z0002970
519	A43=2.0*01-A43	Z0002980
521	A43=A43+01	Z0002990
	A43=A43-2.0*01	Z0003000
	IF(A43)522,523,523	Z0003010
522	A43=A43+2.0*01	Z0003020
523	A44=514(A43)	Z0003030
	A45=C05(A43)	Z0003040
	A46=A35/1600.744	Z0003050
	IF(A46-100.0)525,526,526	Z0003060
525	A47=01/166+02+03+166	Z0003070
	GO TO 527	Z0003080
526	A47=A1/166+12+13+166	Z0003090
527	A46=A35/A4	Z0003100
	GO TO(15,17,00,05,45,45),1	Z0003110
00	RTJON	Z0003120
	END	Z0003130

C. Sample Charts with Lines of Position



127801 56190 56000 18490 56600 56600 56690 56700 56790

125801

125901

125001

124001

123001

122001

121001

120001

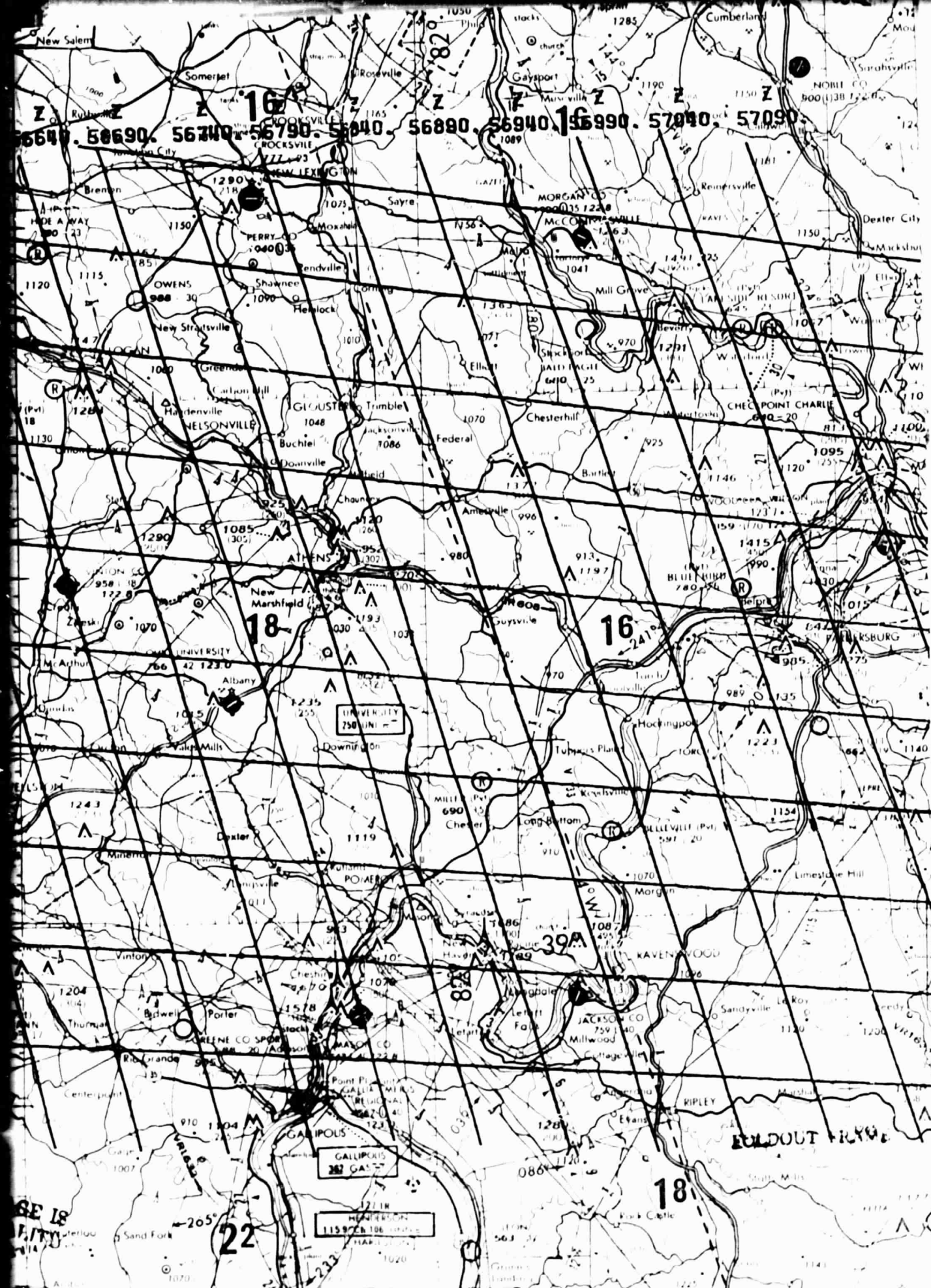
PEERIES 329 P20

PORTSMOUTH 373 PWB

BOLDOUT FRAME

PAGE IS QUALITY

HUNT SEE IT STANDARD AVIATION



SEE IS  
 24- HUNTI  
 SEE T- STANDARD AVIATION SECTIONAL

Standard Geographic Survey Chart

C.P.T.D.

42525.12 V

56696.12 Z

56689.56691.56693.56695.56697.56699.

42536.Y

42534.Y

42532.Y

42530.Y

42528.Y

42526.Y

42524.Y

42522.Y

42520.Y

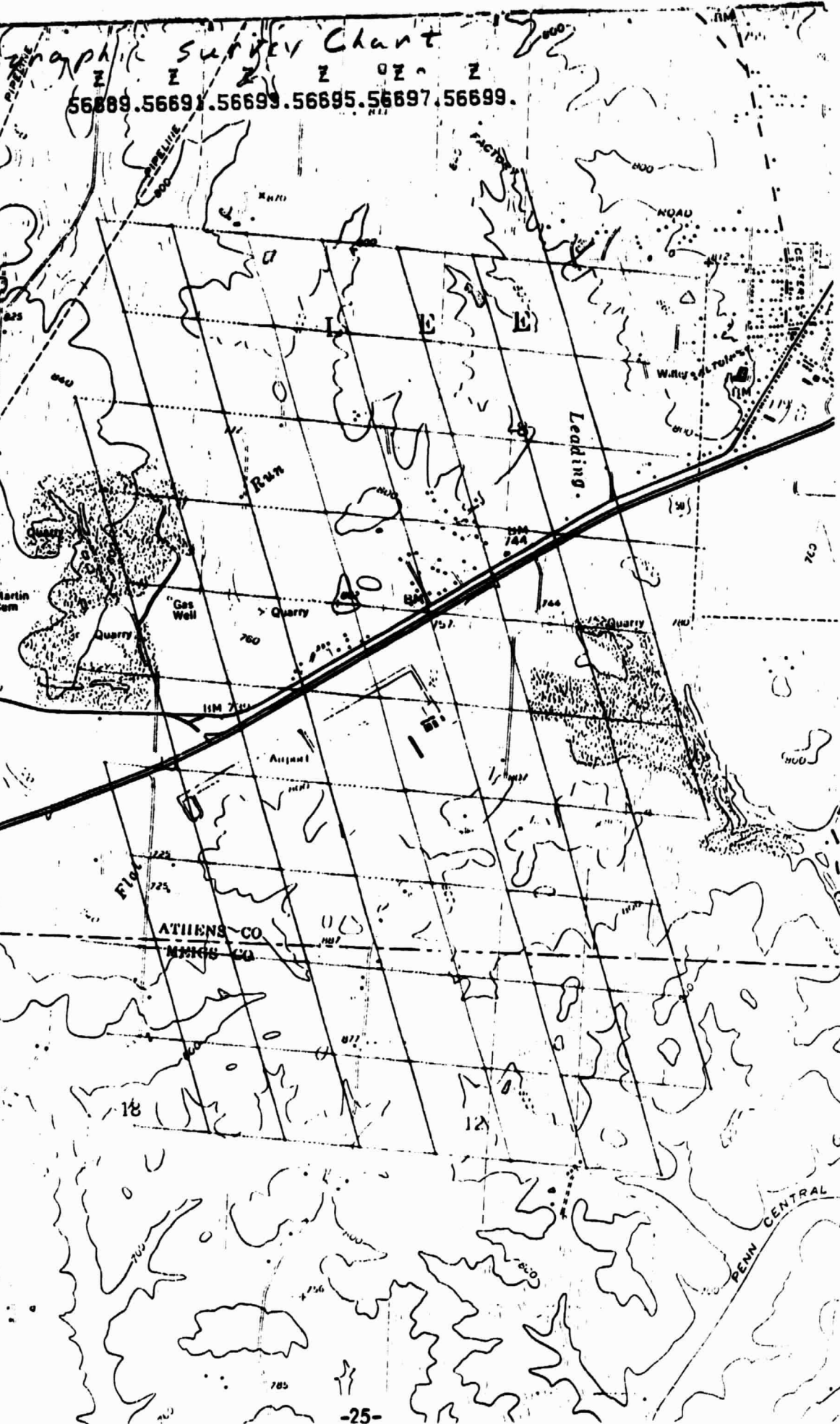
42518.Y

42516.Y

42521 CALICO THE 40 MI. 21 PRATTSVILLE 80 MI. 241

4340 T. 9 N. 110 W.

4562 1/2 NE (VALES MILLS)



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