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A Summary of V/STOL Inlet Analysis Methods

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A SUMMARY OF V/STOL INLET ANALYSIS METHODS

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Abstract

The methods used to analyze the aerodynamic performance of V/STOL inlets at the NASA Lewis Research Center is briefly described. Recent extensions and applications of the method are emphasized. They include the specification of the Kutta condition for a slotted inlet, the calculation of suction and tangential blowing for boundary layer control, and the analysis of auxiliary inlet geometries at angles of attack. A comparison is made with experiment for the slotted inlet. Finally, an optimum diffuser velocity distribution is developed.

Nomenclature

C_f	skin friction coefficient
D	fan diameter
L	inlet length (0.3048 m)
M	Mach number
\dot{m}	mass flow rate
S	surface distance
V	velocity
x	x-coordinate
$\frac{x}{L}$	nondimensional distance from the start of diffusion normalized by the total diffusion length
α	angle of attack
β	inlet yaw angle
θ	circumferential angle ($\theta = 0^\circ$ at windward plane)

Subscripts:

c	control station
de	diffuser exit
e	edge of the boundary layer
inlet	inlet
j	blowing jet
max	maximum
ref	reference
suction	suction
T	throat
∞	free stream

Introduction

In recent years, many different airframe/engine configurations have been proposed for V/STOL aircraft. Some of the proposed configurations imposed rather severe flow conditions on the propulsion system inlet. For example, the approach and takeoff flight paths of a tilt nacelle V/STOL aircraft may result in inlet angles of attack up to 120° . A major concern for the designer at these conditions is the possibility of inlet internal flow separation. Separation free flow is desired to minimize thrust loss, minimize fan blade stress, and prevent engine stall. Reliable theoretical methods of inlet flow analysis are desired to interpret and augment the results of wind tunnel testing. The methods should be able to calculate the potential and boundary layer flows in inlets of arbitrary geometry and flow conditions.

Such methods of analysis have been developed over the past several years at NASA Lewis Research Center. They consist of a series of computer programs documented in Refs. 1 to 6. Comparisons with experimental results are presented in Refs. 7 to 12. Since these reports, the programs have been extended and applied to more difficult inlet problems.

The present paper will briefly describe the basic method of analysis. The major emphasis, however, will be on presenting the recent extensions and applications. The topics covered in this paper are: the flow about a slotted inlet; the flow in an auxiliary inlet; the analysis of suction and blowing boundary layer control; and the development of an optimum diffuser velocity distribution.

Basic Method of Analysis

The basic problem to be solved is to calculate the compressible viscous flow in inlets of arbitrary geometry and operating conditions. A series of computer programs developed at NASA Lewis Research Center are used to solve this problem. A flow chart depicting the sequence for using these programs is presented in Fig. 1 with the basic programs on the left, and recent extensions on the right. All programs start with the geometry program, upper left-hand block, which creates the discrete control points for each geometric configuration. Then the incompressible potential flow program is used to calculate the basic solutions to the problem. These basic solutions are combined into a solution that satisfies the inlet operating conditions of freestream velocity, angle of attack, and inlet mass flow. Next, the incompressible flow is corrected for compressibility effects. The compressible potential flow solution is then used as an input to the boundary layer program which calculates the laminar, transition and turbulent boundary layer characteristics, and predicts flow separation.

Two iteration loops are available as shown to the left in Fig. 1. The first adds the displacement thickness to the geometry to improve the accuracy of the potential flow and boundary layer calculations. The second incorporates an automatic angle of attack sweep to find the separation boundary of an inlet in one uninterrupted computer run.

The recent extensions to these programs, which will be the major emphasis of this paper are: (a) to calculate the flow in an inlet with a leading edge slot; (b) to calculate the performance of suction and tangential blowing boundary layer control concepts, and (c) to analyze the flow in auxiliary inlet geometries at angle-of-attack. The method has also been applied to finding the optimum velocity distribution in a subsonic diffuser.

Geometry Program

A program called SCIRCL is used for 2-d and axisymmetric geometries. For an axisymmetric inlet

case, the geometry is represented by its meridional profile which is shown in Fig. 2(a). A 3-d representation of the axisymmetric inlet is shown in Fig. 2(b). Both the external and internal ducts are extended far downstream so that accurate potential flow solution can be obtained in the region of interest. SCIRCL breaks the profile into segments with a control point on each segment which are used for potential flow calculations. The program also calculates information such as curvature, wall angles, and flow area distribution which are very useful in preliminary screening of proposed inlet shapes. In addition to the surface points, SCIRCL generates off body points (like flow measuring rakes) also shown in Fig. 2(a) at axial locations where the velocity profile or the streamlines are desired.

The 3-d geometry program, applicable to inlet geometries like that shown in Fig. 2(c) and discussed in Ref. 13, allows the user to input a relatively small number of points to define the inlet and centerbody. The routine then enriches the point number and redistributes the points for good potential flow analysis. The detailed description of this geometry package is given in Ref. 5. Some examples of the geometries generated by this program are shown in Figs. 2(b) and (c).

Incompressible Potential Flow Basic Solutions

The Douglas Newman Program^{5,14-16} is used for calculating the incompressible potential flow field. The following basic solutions are obtained by the above incompressible potential flow program:

1. Static solution ($V_\infty = 0$)
2. Uniform axial flow solution
3. 90° angle of attack solution
4. 90° angle of yaw solution (for 3-d geometry only)

In general, to obtain the basic solutions, the surface is replaced by a number of panels on which there is a surface source (or sink) distribution of unknown strength. For 2-d and axisymmetric cases, the source density can be a constant, linear or parabolic. For the 3-d case, only a constant source density can be used. The strength of source distribution varies over the surface in a manner such that at every control point the normal velocity is zero. However, the best static solution is found to result from using a vorticity distribution on the cowl surfaces.

Linear Combination and Corrections

The basic solutions obtained from the incompressible potential flow calculation are combined linearly into a solution of interest having arbitrary flow conditions of free stream velocity, mass flow rate, and angle of attack.¹⁷ In cases where a Kutta condition is required, the constants for linear combination are readjusted to satisfy the Kutta condition. The linearly combined incompressible solution is then corrected for compressibility.¹⁸ If the local velocity is supersonic, it is further corrected by the empirical supersonic correction formula.¹⁹ The final potential flow solution can now be used as an input to the boundary layer program.

Boundary Layer

The analysis of the boundary layer uses a 2-dimensional compressible boundary layer program.

The complete documentation of the boundary layer program is given in Ref. 6. The program calculates important boundary layer parameters such as displacement thickness, momentum thickness, and skin friction coefficient, C_f . It also provides the boundary layer velocity profiles at any desired station. The location of transition from laminar to turbulent flow can either be predicted by the program or can be specified by the user. Flow separation is defined to occur when the skin friction coefficient becomes zero.

Recent Extensions

The discussion thus far has described the basic method of analysis. Now the discussion will focus on describing the recent extensions which were motivated in part by the following thoughts. It is desirable to design a V/STOL inlet as short and as thin as possible in order to reduce the weight, to reduce the friction drag at cruise, and improve pilot visibility. However, when an inlet is too thin the peak velocity is so high that the subsequent adverse pressure gradient causes the flow to separate at the lip resulting in a low pressure recovery and high distortion. Several ways to help control this possible separation are by an inlet lip slot, the use of auxiliary inlets, by suction or blowing boundary layer control, or by optimizing the surface pressure distribution. The analysis techniques to analyze these possibilities are considered next starting with the slotted inlet.

Slotted Inlet

A slotted inlet is shown in Fig. 3. Two cases are considered, zero angle of attack and angle of attack.

At zero angle of attack or at zero forward velocity for an axisymmetric geometry the flow is axisymmetric and the Kutta condition (i.e., that the flow leaves the trailing edge of the slot, point 1 on Fig. 3, at a flow angle that bisects the slot trailing edge angle) is applicable around the entire circumference of the inlet. Calculations were made for static conditions, $V_0 = 0$. Experimental data are included for comparison. The agreement is quite good on the main inlet cowl surface (points 6 to 9). The agreement between the theoretical and experimental surface velocities are good on the leading edge (points 4 and 5) and the highlight (point 3). However, near the trailing edge (points 1 and 2) the theory does not agree as closely with the experiment suggesting some modification to mathematical Kutta condition may be appropriate. Figure 3 shows that the peak velocities occurs at point 2 on the slot and point 7 on the main cowl. Both peaks are considerably lower than the peak velocity of the inlet without the slot,¹⁹ also indicated on the figure. Thus the addition of the slot has unloaded the lip of the thin inlet.

The case of slotted inlet at an angle of attack is more difficult, because the Kutta condition can not correctly be imposed at all circumferential positions simultaneously.

Where the Kutta condition at an angle of attack is required, it can be applied by adjusting the mass flow rate through the slot at one circumferential location until the Kutta condition is satisfied at that circumferential location at the

trailing edge of the slat. Calculations were made using this approach and the results are shown in Fig. 4. Experimental data are included for comparison.

The Mach number was calculated at the circumferential location of 270° . Agreement between theory and experiment is considered very good.

Extending the method of analysis to include the Kutta condition results in the ability to analyze a new class of inlet geometries, specifically those that employ leading-edge slats and slots.

Auxiliary Inlet

The method of analysis has also been extended to include auxiliary inlet geometries. Auxiliary inlets increase the total inlet flow area thereby reducing the amount of airflow that must be taken into the main inlet. It is another technique for preventing flow separation on cowl lips at static and low flight speed conditions. While an important application of auxiliary inlets is to supersonic inlets at low speed, the application considered here is to an auxiliary inlet on the top of a conventional subsonic inlet. The inlet and its panelling are shown in Fig. 5. A continuous N-line (in the longitudinal direction) is required for the current version of the 3-d potential flow program. When the N-line meets the auxiliary inlet opening, it is rerouted along the side wall of the auxiliary inlet and then proceeds back to the original N-line as shown in Figs. 5(a) and (b). Additional N-lines are added to completely panel the inlet. This particular example required 682 panels to describe the geometry. The 3-dimensional incompressible potential flow code was then used to calculate the basic solutions at the center of each panel (control point).

With the auxiliary inlet, the following technique was found to yield the best static solution: Two inlet-duct systems are considered, one with a straight duct and one with a flared duct as shown in Figs. 5(a) and (b). The flared duct induces more flow through the main and auxiliary inlets. The difference between the velocities for the flared inlet and nonflared duct for a free stream uniform flow then provides the static solution. This procedure was adopted because the velocities in the region of an auxiliary inlet were unrealistically large when the vorticity distribution, noted earlier, was used for the static solution.

The computer time for the basic solutions with the 682 panels is quite high, 19 minutes. However, the basic solutions are only computed once and are stored in the computer for later use in obtaining solutions of interest. Subsequent calculations using a linear combination method required only 5 seconds of computer time.

The velocity distribution along an N-line is illustrated in Fig. 6 for $V_c/V_\infty = 1.5$ and

1. $\alpha = 0^\circ$, $\beta = 0^\circ$
2. $\alpha = 30^\circ$, $\beta = 0^\circ$

The location is indicated by the letters along the N-line. At $\alpha = 0^\circ$, $\beta = 0^\circ$, the peak velocity occurs at point D (Fig. 6) which is close to the center line on the downstream side of the auxiliary inlet. Generally speaking, the downstream surface of the auxiliary inlet is the high velocity area as might be expected. As angle of attack increases to 30° , the peak velocities at D is substantially re-

duced. For this case, the highest velocity occurs at the highlight. These sample cases indicate that this program can be used to calculate the surface velocities for nacelles employing auxiliary inlets and can pinpoint the problem areas. Figure 7 shows the effect of an auxiliary inlet on the peak velocity on the windward plane of the inlet. The peak velocity ratio is reduced from 2.8 to 2.5 at the highlight when the auxiliary inlet is opened. This is the desired result.

Suction and Tangential Blowing

Another recent extension to the basic methods is the analysis of suction and tangential blowing boundary layer control systems. Suction controls the boundary layer by removing that portion of it not having sufficient momentum to negotiate the subsequent adverse pressure gradient. Blowing controls the boundary layer by reenergizing it with a thin jet of high velocity air injected tangentially into the boundary layer.

Some results from this analytical method are shown in Figs. 8 and 9 for suction and blowing, respectively. An axisymmetric inlet having a diameter of 0.508 m was analyzed at a free stream Mach number, $M_\infty = 0.12$, throat Mach number, $M_T = 0.4$, and angle of attack, $\alpha = 60^\circ$. The skin friction coefficient distribution on the internal surface of the windward cowl is shown along with boundary layer velocity profiles at several locations. Without boundary layer control, the solid line, the flow separates at $S/L = 0.81$ where the skin friction coefficient becomes zero. The boundary layer profile, just before separation, is quite weak compared to the one upstream at $S/L = 0.48$. Separation is prevented when the boundary layer is controlled by suction (Fig. 8) - the dashed line. It was necessary to bleed off only 0.12 percent of the inlet mass flow to prevent separation as indicated by the nonzero skin friction coefficients. The static-to-total pressure ratio at suction location is 0.796.

For the blowing boundary layer control (Fig. 9) a blowing velocity ratio, jet velocity to boundary layer edge velocity, $V_j/V_e = 1.75$ was selected. For this case a blow mass flow of 0.4 percent of the inlet mass flow was required to maintain attached flow. The reenergized boundary layer is clearly evident in the velocity profile just downstream of the blowing slot.

Optimum Diffuser Velocity Distribution

Another application of the method is concerned with finding the optimum velocity distribution in a subsonic diffuser. This velocity distribution will result in the shortest no-boundary layer control inlet and the lowest loss for the required amount of diffusion.

The method of design of an optimum subsonic inlet is given in Refs. 20 and 21. Based on the design criteria given in those references, the boundary layer program was used to find the optimum diffuser velocity distribution. The generalized mathematical form of the velocity distribution is given by

$$V = V_{de} + (V_{max} - V_{de})e^{-5x^b}$$

A typical case of $V_{max} = 190$ m/s, $V_{de} = 68$ m/s is shown in Fig. 10. The overall diffusion ratio V_{max}/V_{de} is the same for the three cases shown. The upper part of the figure shows the surface velocity ratio (V/V_{de}) as a function of surface distance s/s_{ref} . Velocity distributions were calculated for three values of the exponent b .

A value of $b = 0.613$ produces the steepest initial velocity gradient (largest initial adverse pressure gradient). The initial adverse pressure gradient is so large that the flow separates on the lip at the beginning of the diffusion process. A value of $b = 1.005$ produces a relatively more severe adverse pressure gradient in the diffuser and the flow separates there. Somewhere between these two cases, there exists a velocity distribution such that at every location, the momentum of the boundary layer is just able to overcome the adverse pressure gradient so that the flow remains attached throughout the diffuser. This is called the optimum diffuser velocity distribution and is achieved when $b = 0.794$. For comparison, Stratford's optimum velocity distribution²¹ is also presented in Fig. 10. The present optimum velocity distribution is more conservative at the beginning of the diffusion process than that of Stratford. Since Stratford's distribution is derived on the basis of zero skin friction throughout the diffuser, it can be considered as a limiting case. A design velocity distribution (besides having a safety margin against separation) should have a slightly more gradual start to the pressure rise (the deceleration of velocity) than that of Stratford. The present optimum velocity distribution can be a useful design approach.

Concluding Remarks

An analysis method based on incompressible potential flow corrected for compressibility was described. Several sample calculations compared well with experimental data. The most recent applications include inlet with a leading edge slot, an auxiliary inlet, and suction or blowing boundary layer control. An optimum diffuser velocity distribution was also developed. This paper shows that the present methods can be a very powerful tool for the analysis of flow about and the design of V/STOL inlets.

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BASIC PROGRAMS

RECENT EXTENSIONS

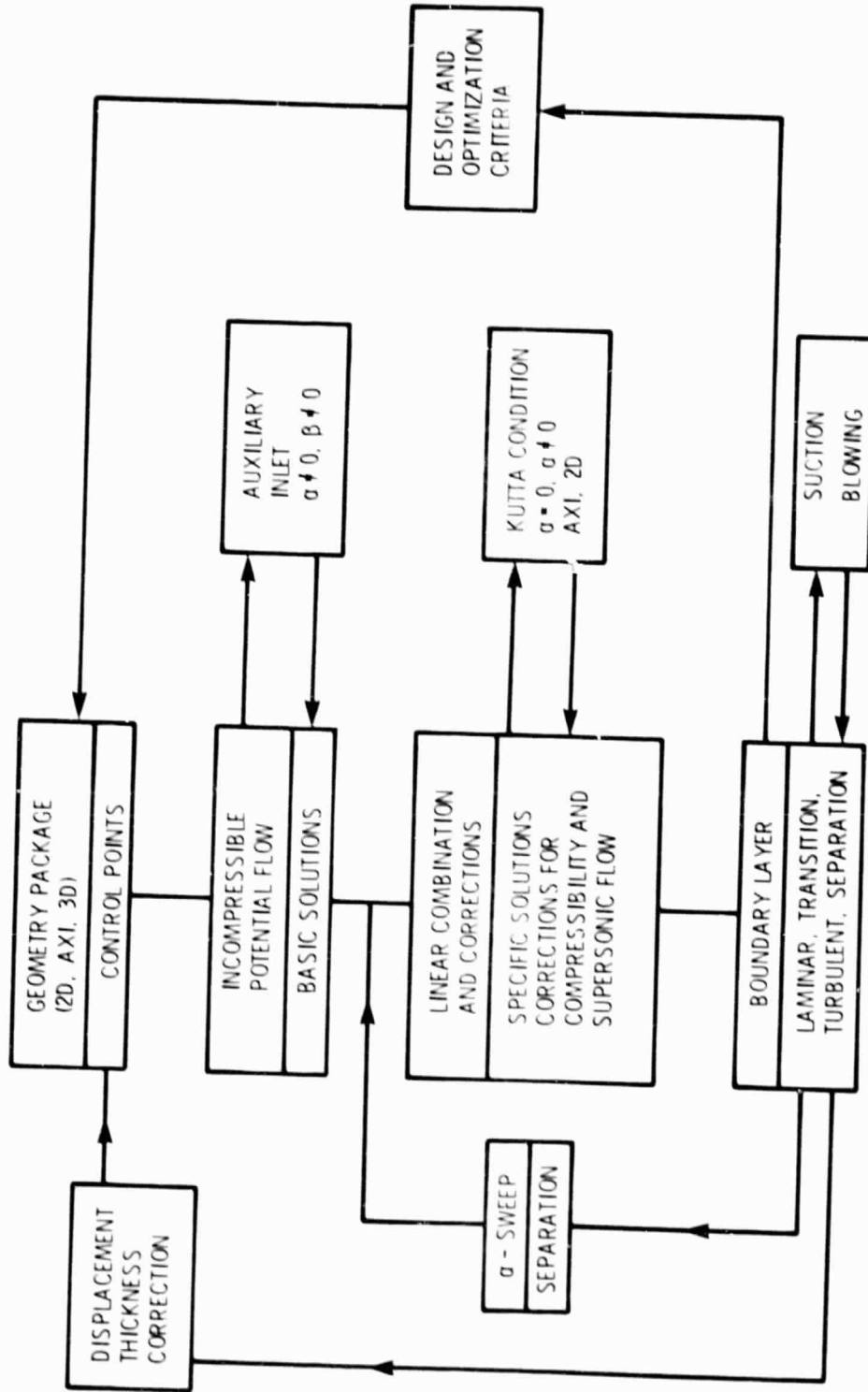
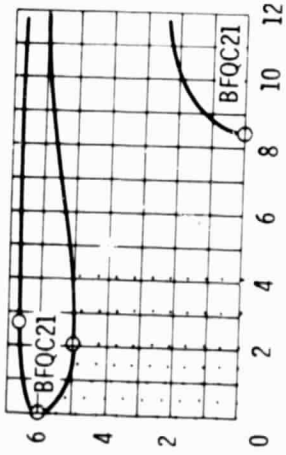
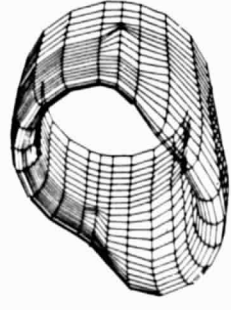


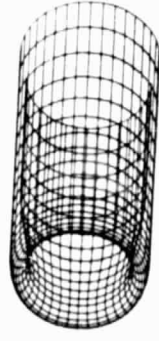
Figure 1. - Schematic diagram of computer programs.



(a) QCSEE TEST INLET, GE2.



(c) THREE-DIMENSIONAL SCOOP INLET.



(b) AXISYMMETRIC INLET.

Figure 2. - Geometries of inlets.

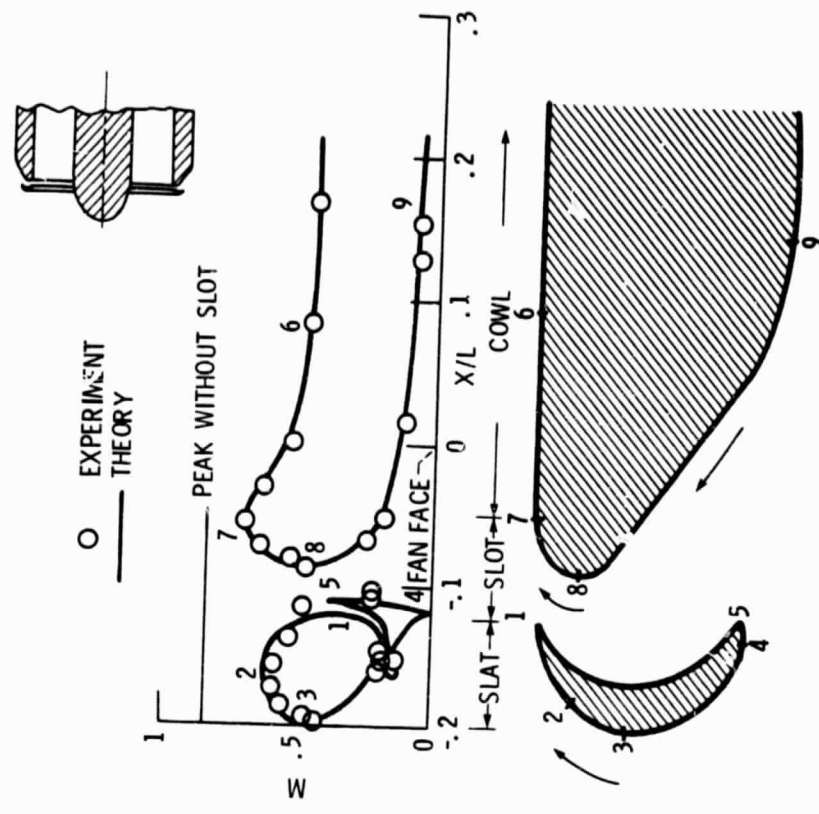


Figure 3. - Short inlet with a leading edge slot, $V_0 = 0$.

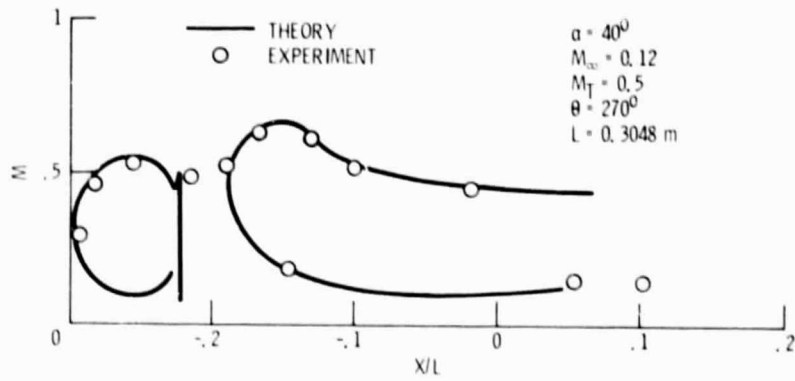


Figure 4. - Short inlet with a leading edge slot at angle of attack.

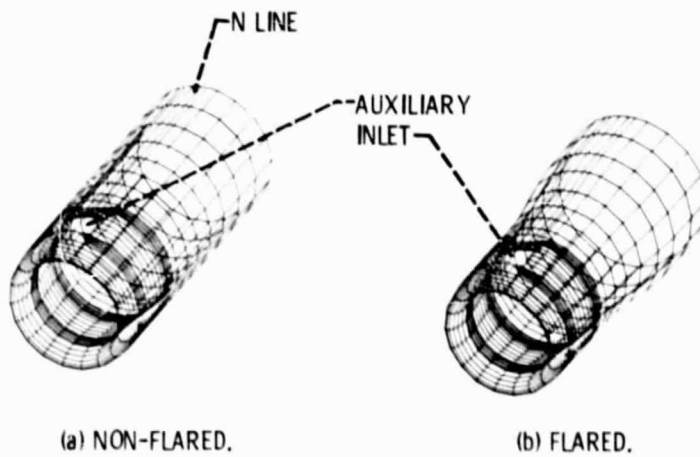


Figure 5. - Auxiliary inlets.

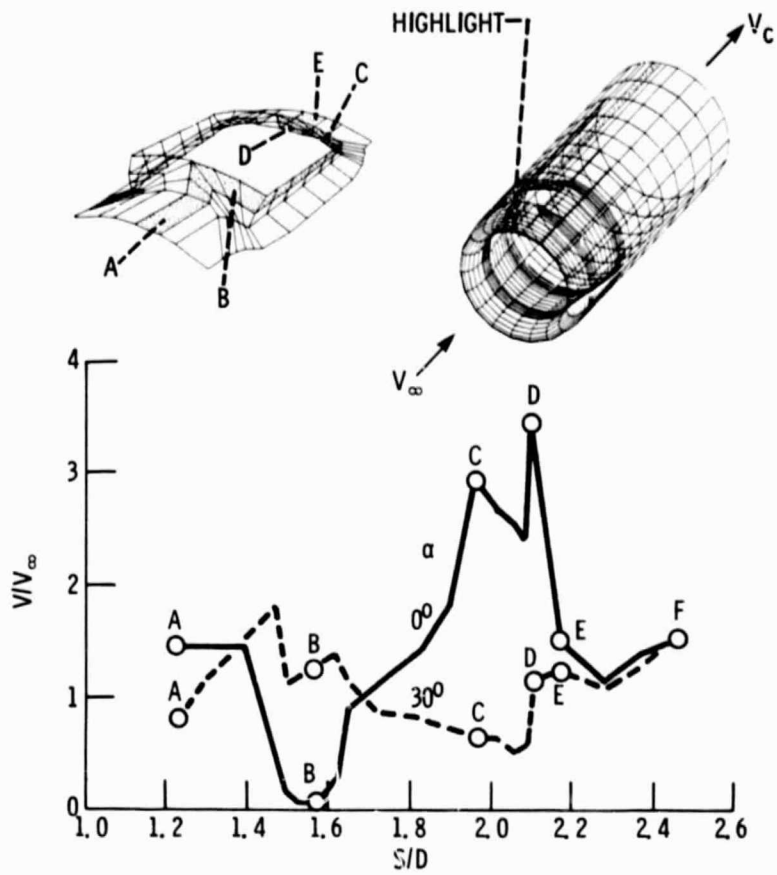


Figure 6. - The surface velocity of an auxiliary inlet.

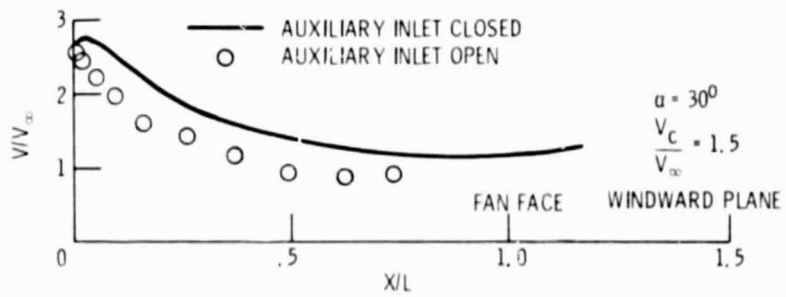
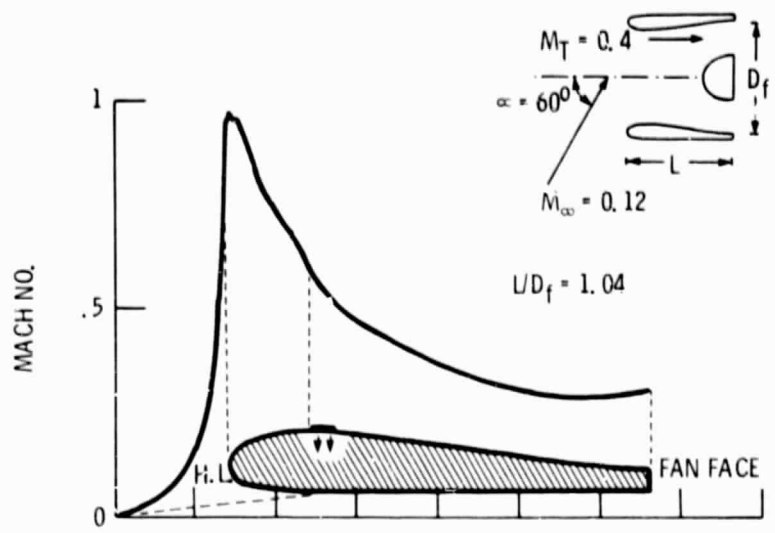


Figure 7. - The reduction of peak velocity by opening auxiliary inlet.



$\frac{\dot{m}_{\text{suction}}}{\dot{m}_{\text{inlet}}} = 0.12\%$ $\frac{P_s}{P_o} = 0.796$

——— NO SUCTION
 - - - SUCTION

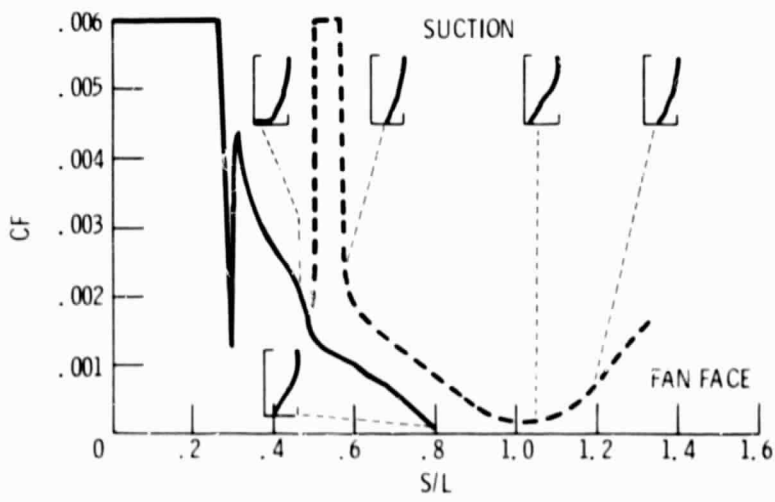
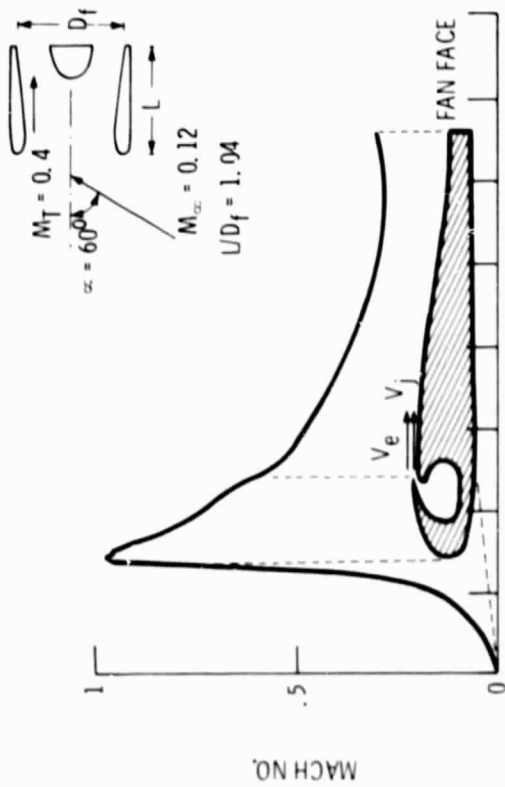


Figure 8. - Skin friction and velocity profiles with and without suction.



$$\frac{\dot{m}_{\text{blowing}}}{\dot{m}_{\text{inlet}}} = 0.4\% \quad \frac{V_j}{V_e} = 1.75$$

— NO BLOWING
 - - - BLOWING

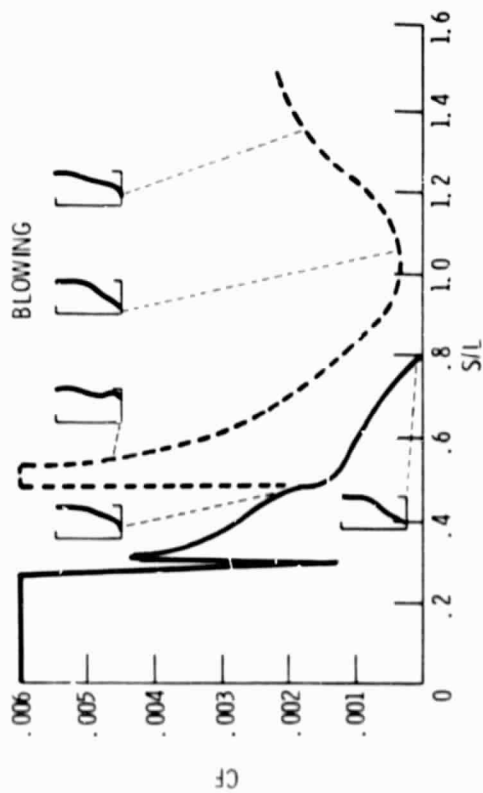


Figure 9. - Skin friction and velocity profiles with and without blowing.

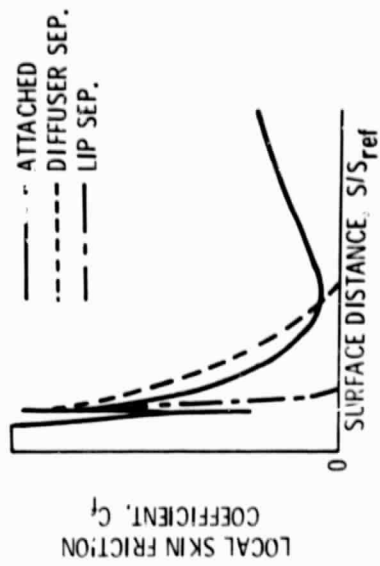
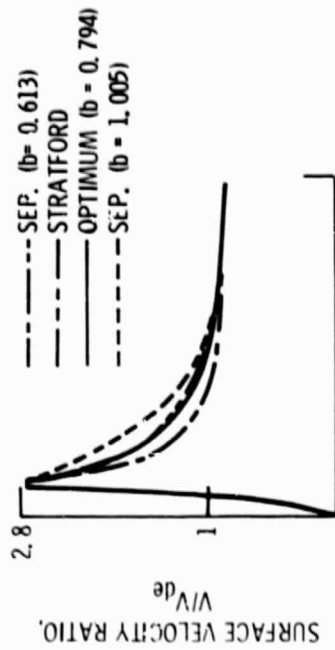


Figure 10. - Optimum velocity distribution.