

## N O T I C E

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USE OF OPTIMIZATION TO PREDICT THE EFFECT OF  
SELECTED PARAMETERS ON COMMUTER AIRCRAFT PERFORMANCE

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## I. Introduction

The resurgence of interest in small, propeller-driven aircraft has sparked renewed analysis of the aerodynamics, structures and propulsion systems of such planes. Along with advanced technology research, which is the bent of much of the recent concern, there remains a need for the answer to a, perhaps, more basic question—that is, for what mission should this airplane be designed? The "mission" includes not just stage length (which is determined by the actual leg distances flown by commuter airlines) but also the speed at which to climb and cruise and the field length from which the aircraft must takeoff and land.

This study, rather than seeking to prescribe a particular design or mission, discovers the relationships between field length and cruise speed and aircraft direct operating cost. To do this, a gradient optimizing computer program was developed to minimize direct operating cost (DOC) as a function of airplane geometry. In this way, one can compare the best airplane operating under one set of constraints with the best operating under another. Best, in this case, means having the minimum DOC.

To compare different airplanes, one can make use of relatively simple techniques for some parameter estimation. For example, a complete stability and control analysis for tail size determination is superfluous for preliminary design when statistical correlations of tail sizes with wing and fuselage characteristics exist for similar airplanes. Thus several such statistical correlations methods appear in the program. However, one must also use more sophisticated procedures when a high degree of accuracy is required or when the particular calculation may have a major influence on the performance index. The program, therefore, has extensive and detailed routines for drag, climb, range and other critical values.

For this study a constant 30-passenger fuselage and "rubberized" engines based on the General Electric CT-7 were used as a baseline. All aircraft had to have a 600 nautical mile maximum range and were designed to FAR part 25 structural integrity and climb gradient regulations. Direct operating cost was minimized for a typical design mission of 150 nautical miles. For purposes of  $C_{L_{max}}$  calculation, all aircraft had double-slotted flaps but with no Fowler action.

## II. Procedure

The optimizer minimizes direct operating cost as a function of wing area, aspect ratio and engine sea-level static horsepower rating through use of a variable metric algorithm which is, in fact, a quasi-Newton's method. A true Newton's method utilizes the following strategy for size and direction of step:

$$\hat{x}_{j+1} = \hat{x}_j - H_j^{-1} \hat{g}_j$$

where  $\hat{x}$  represents the vector of variables,  $H_j$  is the Hessian (matrix of second derivatives) at step  $j$ , and  $\hat{g}_j$  is the gradient vector at step  $j$ . In the absence of second derivative information, a numerical approximation of the Hessian using known values of the first derivatives provides an adequate substitute. The variable metric method follows exactly this procedure.

Of course, for such a complicated function as the one in this study (the "function" is a thirty page FORTRAN program), even first derivatives do not exist in closed form. Thus, the program must calculate a gradient estimate using a forward difference approximation. The differencing step size is constrained to be rather large (one percent of the variable value) since noise in the function evaluation leads to incorrect gradients for small steps.

The function evaluation program, which comprises the bulk of the calculations involved in the optimizing process, acts as a mathematical aircraft model. This routine determines, for prescribed wing area, aspect ratio, and engine power, the complete geometry, performance, and operating cost of the resulting airplane. It employs preliminary design methodology for estimating zero-lift equivalent parasite drag area, tail sizes,  $C_{L_{max}}$ , airplane efficiency factor, lift-curve slope, structural load factors, and component weights. (See references 1 and 6.) For simplicity, such parameters as thickness ratios and sweep angle of the aerodynamic surfaces are held constant since compressibility effects are essentially negligible at commuter aircraft speeds. Also, taper ratios and tail aspect ratios are treated as constants.

The program uses preliminary design methods (reference 1) to calculate takeoff and landing distances but uses analytically derived expressions for determining range, climb performance, descent performance and climb gradients. Some of the resulting integrals necessitate numerical routines for their solution. The program determines best climb speed and cruise altitude by conducting a grid search of five speeds and three altitudes and choosing the lowest cost combinations of the two.

The direct operating cost calculation is based on the 1967 ATA DOC method (reference 2) with corrections for inflation and commuter operation. It assumes that commuter pilot pay rates run about one third that of trunk carrier pilots. It also uses the following cost estimates:

Labor Rate	\$12/hr.
Airframe First Cost	\$200/lb. of airframe
Engine First Cost	from ref. 4; inflated 25%
Fuel Cost	\$1.50/gallon
Oil Cost	\$10/lb.

Appendix I contains a complete listing of the program.

### III. Results

The results of the optimization program show that the airplane with the lowest direct operating cost flies at 290 knots TAS with an allowed field length greater than or equal to 4,060 feet, Figure 1. For field lengths less than 3,650 feet, the 250 knots airplane fares best in terms of DOC as the large wings required for short landing distances cause excessive drag at the higher speeds. At greater than 3,650 foot field lengths, 290 knots is the best speed. The best 330 knots airplane, however, with a landing distance of 4,275 feet has only one percent worse direct operating cost than the best airplane overall. Direct operating cost as a function of field length and cruise speed is presented in Figure 1.

The optimization, aside from determining the effect of cruise speed and field length on DOC, produced the following crucial results:

## A. Critical Field Lengths

Although, generally, direct operating cost decreases with increasing field length (for a given speed), for each speed there exists a critical field length beyond which there is no further improvement in DOC; the field length constraint becomes non-active. Two factors contribute to this phenomenon. First, though the wing area can decrease with increased takeoff or landing distance, the aircraft must still maintain a span adequate to meet climb gradient standards. The resulting increase in aspect ratio increases the weight enough to counteract the beneficial effects of the lower wing area. Secondly, a smaller wing area forces the aircraft to an inefficient  $C_L$  far from that for best L/D (which indicates best specific range for propeller-driven aircraft). A drop in cruise altitude improves the  $C_L$  but increases the non-lift dependent drag so the altitude modification is not worthwhile.

## B. Active Constraints and Optimal Variable Values

A rough rule of thumb governing the selection of aircraft geometry states that the landing field length requirement determines the wing area and the other operative constraint, whichever one it is, fixes the proper combination of aspect ratio (span) and engine power. In fact, though wing area is not quite independent of cruise speed for a given field length, wing loading (takeoff weight divided by wing area) does not vary with speed. Thus the landing distance has only secondary effect on aspect ratio and horsepower required.

Table 1 presents a list of the active constraints—that is, those limiting the design—for each cruise speed and field length tested. The table includes the critical field length for each speed. At the lower speeds, the required enroute climb gradient sizes the aspect ratio and engine power. Since, previously, commuter aircraft have not been designed to meet FAR part 25 regulations, they have not encountered as much difficulty with the one-engine-out enroute climb restriction. Though enroute climb rarely presents a problem for turbofan aircraft, the turboprop airplane, because its speed for best climb is lower than the minimum allowable speed, is often restricted by this regulation if it is designed according to part 25 rules.

At the higher speed, in most cases, minimum cruise power to fly at 330 knots determines both engine power and aspect ratio. Obviously, increasing the horsepower increases the maximum cruise speed, but, though not as important a factor in the power-restricted cases, increasing the aspect ratio also increases the maximum cruise speed due to the reduced induced drag. So, whether the second active constraint is minimum enroute climb gradient or power to cruise at a given cruise velocity, several combinations of aspect ratio and engine power exist to satisfy that constraint. The optimizer chooses the best, or lowest cost, combination of the two.

At a cruise speed of 330 knots and landing distance 4,275 feet or more, enroute climb gradient rather than available cruise power becomes the second operational constraint. This occurs because the wing area has decreased enough that the cruise drag (and, therefore, cruise power required) has also decreased to the extent that power to climb is greater than the power to maintain a 330 knots cruise speed.

Figure 2 shows the variations of optimal wing area, aspect ratio, and horsepower with field length and cruise velocity. As expected, wing area decreases as the field length gets longer. The aspect ratio, however, increases in an attempt to keep the same span in order to maintain the same climb gradient or induced drag. The 250 knots airplanes have higher aspect ratios than the 290 knots planes because they must meet identical climb gradients but with lower power levels. The slower airplanes have lower power ratings but higher spans than the 290 knots aircraft. The 330 knots airplanes have aspect ratios lying between those of the other two speed aircraft since the cruise speed constraint affects choice of aspect ratio differently from the enroute climb constraint.

Figure 2c provides an interesting insight into the effects of differing active constraints on optimum engine power. As wing areas decrease with increasing field length, the aspect ratios increase but, in general, not enough to maintain constant span. If enroute climb is critical, then, the engine power must increase for the airplane to meet the climb gradient for reduced span. At 250 knots and 290 knots this indeed happens. However, if

meeting the required cruise velocity is critical, the smaller wing area reduces the parasite drag much more than the smaller span increases induced drag. Therefore, the aircraft requires less power to overcome the cruise drag, and the curve indicating a 330 knots aircraft follows this trend.

### C. Sensitivity Studies

1. Grid Search About an Optimal Point. Although the optimizing program chooses a lowest-cost airplane for a given set of constraint parameters, it gives little information about the effects of small changes in variable values about that optimum. Figures 3a-c show cost for values of wing area, aspect ratio, and engine power above and below those calculated as the optimum for cruise speed equal to 330 knots and a field length of 4,000 feet. Constraint barriers are included in these figures to indicate areas of impossible choices. At the smallest wing area ( $345 \text{ ft}^2$ ) no airplane can meet the 4,000 foot field length constraint whereas, at a wing area of  $385 \text{ ft}^2$ , all airplanes easily fall below the field length requirement.

As these figures illustrate, the optimizer chooses the lowest cost configuration which can meet all requirements. At the optimum point, the design is bounded by both cruise power and field length, and, as a consequence, it cannot move in a direction of lower cost. (See Figure 3b.)

The "kinks" in the highest power curves of Figures 3b and 3c occur because the program allows only discrete values of cruise altitude which leads to slight discontinuities in the goal function.

2. Non-Optimal Operation. The previous discussion deals with aircraft operation under the conditions for which that aircraft is designed. Possibly, however, a commuter operator would like to have the ability to fly his airplanes at a fast speed even if he normally flies much more slowly.

Figure 4 shows the cost penalty incurred for two cases of non-optimal operation. The costs for the optimum airplanes designed for cruise at 330 knots and field lengths of 3,500 and 4,000 feet, but actually flown at



several lower cruise speeds over the 150 nautical mile typical stage length, are shown. Although the cost does decrease as the airplane slows down, it does not reach the economy level achieved for the optimized airplane at each speed. The difference in DOC between the optimized aircraft and the high-speed airplane flown at a lower speed reaches as high as 1.4% for airplanes meeting a 4,000 foot landing distance and as high as 5% for airplanes with 3,500 foot field lengths. The non-optimized airplanes cost more to operate at a given speed since their larger engines and higher wing areas contribute to higher weight and drag and, thus, to more fuel burned per mission.

#### IV. References

- [1] Shevell, Richard S., "Aerospace Systems Synthesis and Analysis", Department of Aeronautics and Astronautics, Stanford University, September 1978.
- [2] \_\_\_\_\_ . "Standard Method of Estimating Comparative Direct Operating Costs of Turbine Powered Transport Airplanes", Air Transport Association of America, December 1967.
- [3] Nash, J.C., Compact Numerical Methods for Computers, New York: John Wiley & Sons, 1979.
- [4] Lockheed-California Company, Application of Advanced Technologies to Small Short-Haul Transport Aircraft, NASA CR 152363, June 1980.
- [5] Smith, C.E., Hirschkron, R., Warren, R.E., Propulsion System Study for Small Transport Aircraft Technology (STAT), General Electric Company, NASA CR 165330, May 1981.
- [6] Ebeling, A., The Determination of Airplane Maximum Lift Coefficients, Douglas Aircraft Company, Inc., July 1964.

**Table 1. Active Constraints**

<b>Cruise Speed (kts)</b>	<b>Field Length Constraint (ft)</b>	<b>Active Constraint<sup>1</sup></b>
250	3,500	Enroute climb gradient
	3,725 <sup>2</sup>	"
290	3,500	"
	3,750	"
	4,000	"
	4,060 <sup>2</sup>	"
330	3,500	Maximum cruise power
	3,750	"
	4,000	"
	4,275 <sup>2</sup>	enroute climb gradient

1. This column contains the second active constraint. The first active constraint is landing distance at the field length listed in column 2.
2. Critical field length above which field length does not determine wing area, power or aspect ratio.

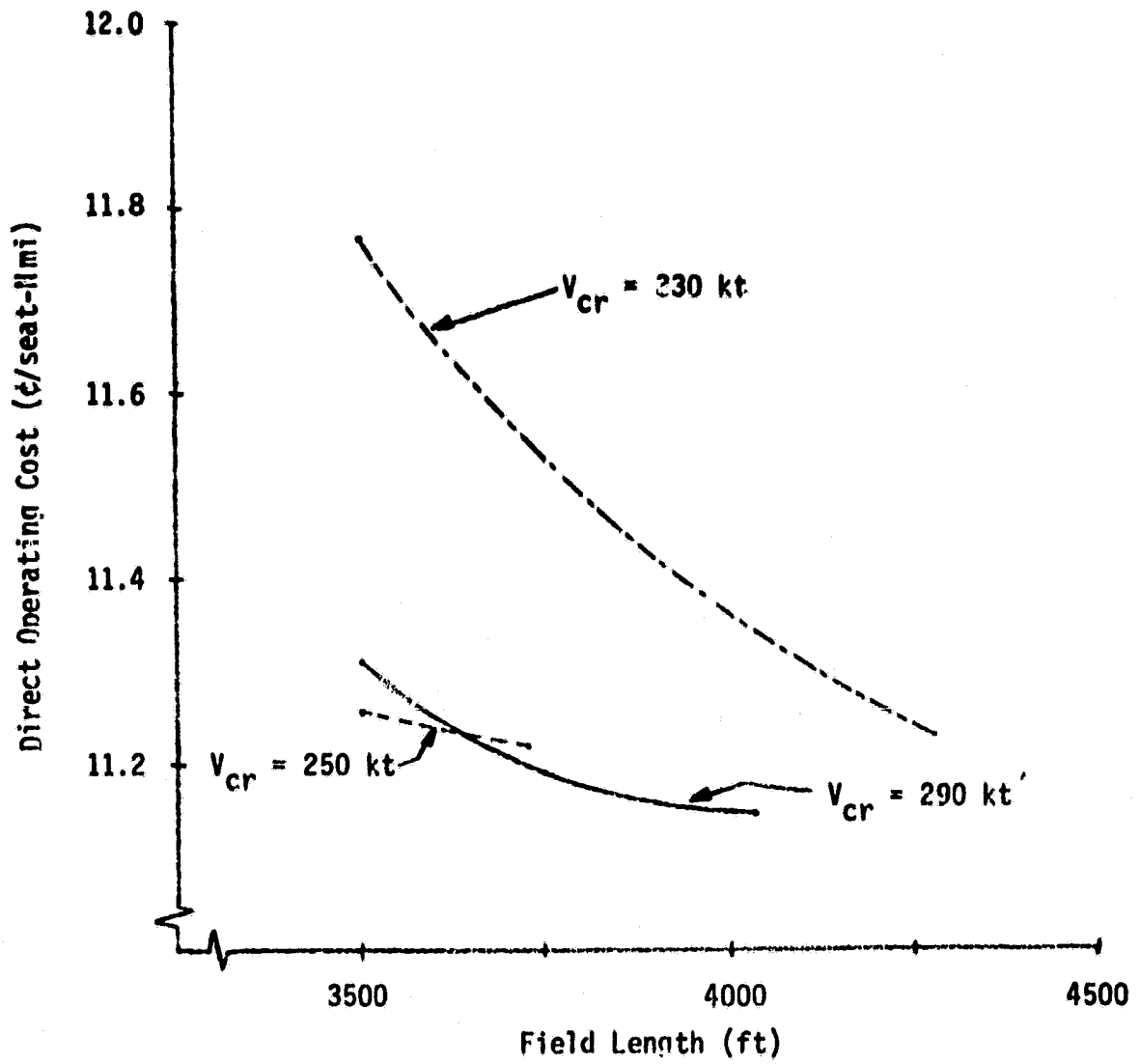


Figure 1. Direct Operating Cost vs. Field Length

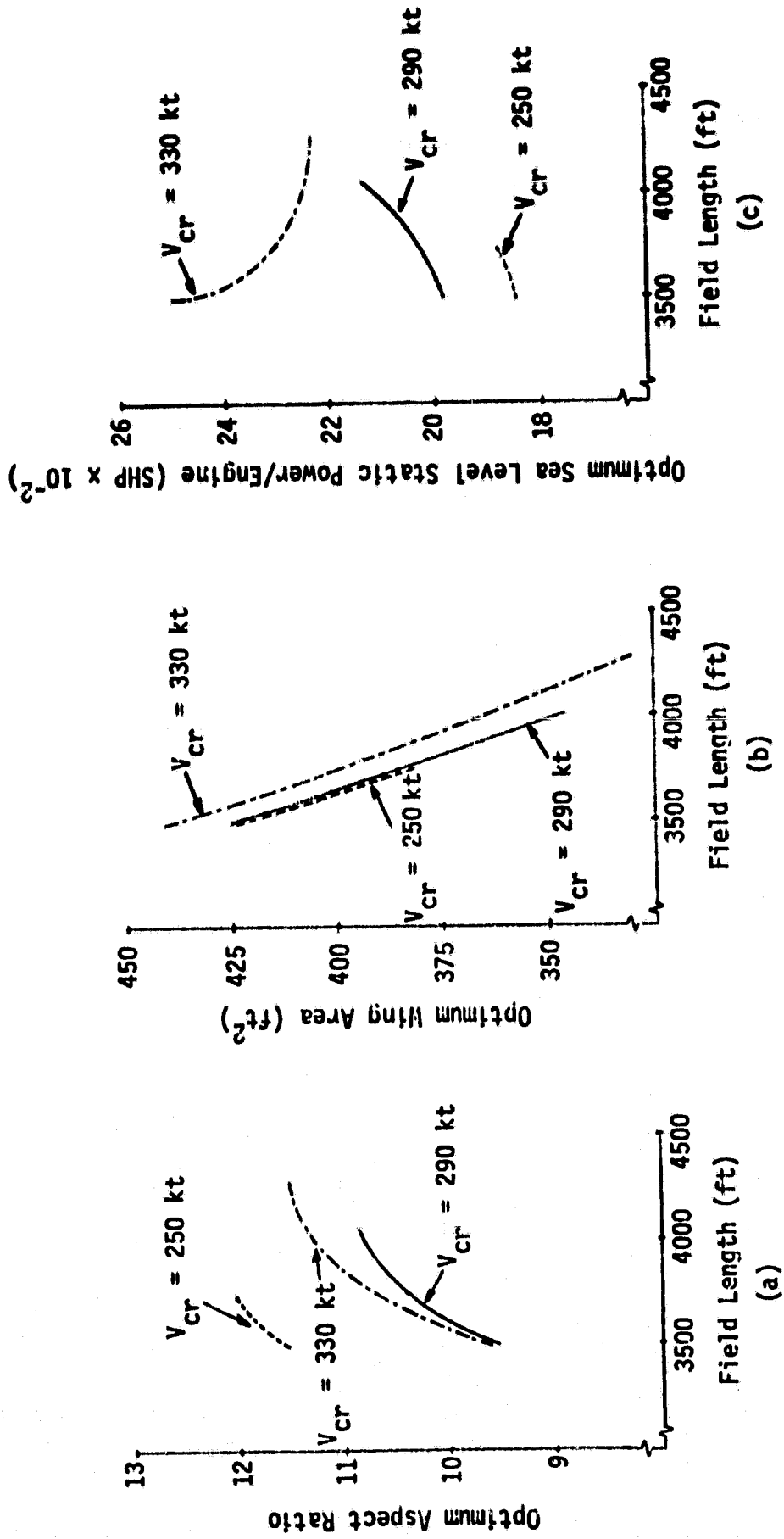


Figure 2. Optimal Variable Values vs. Field Length

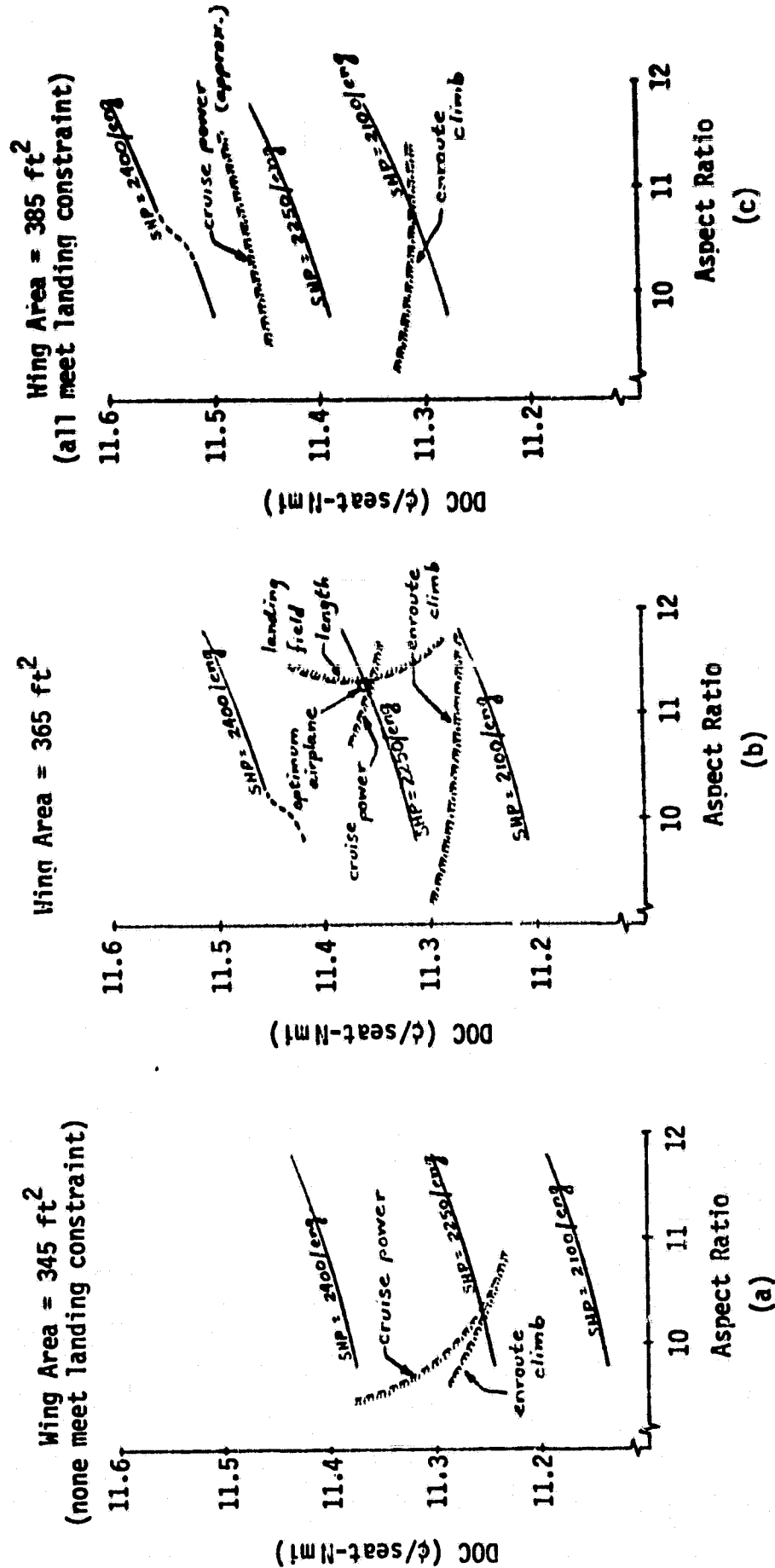


Figure 3. Optimal Point Sensitivities  
 Cruise Speed = 330 kt, Maximum Field Length = 4000 feet

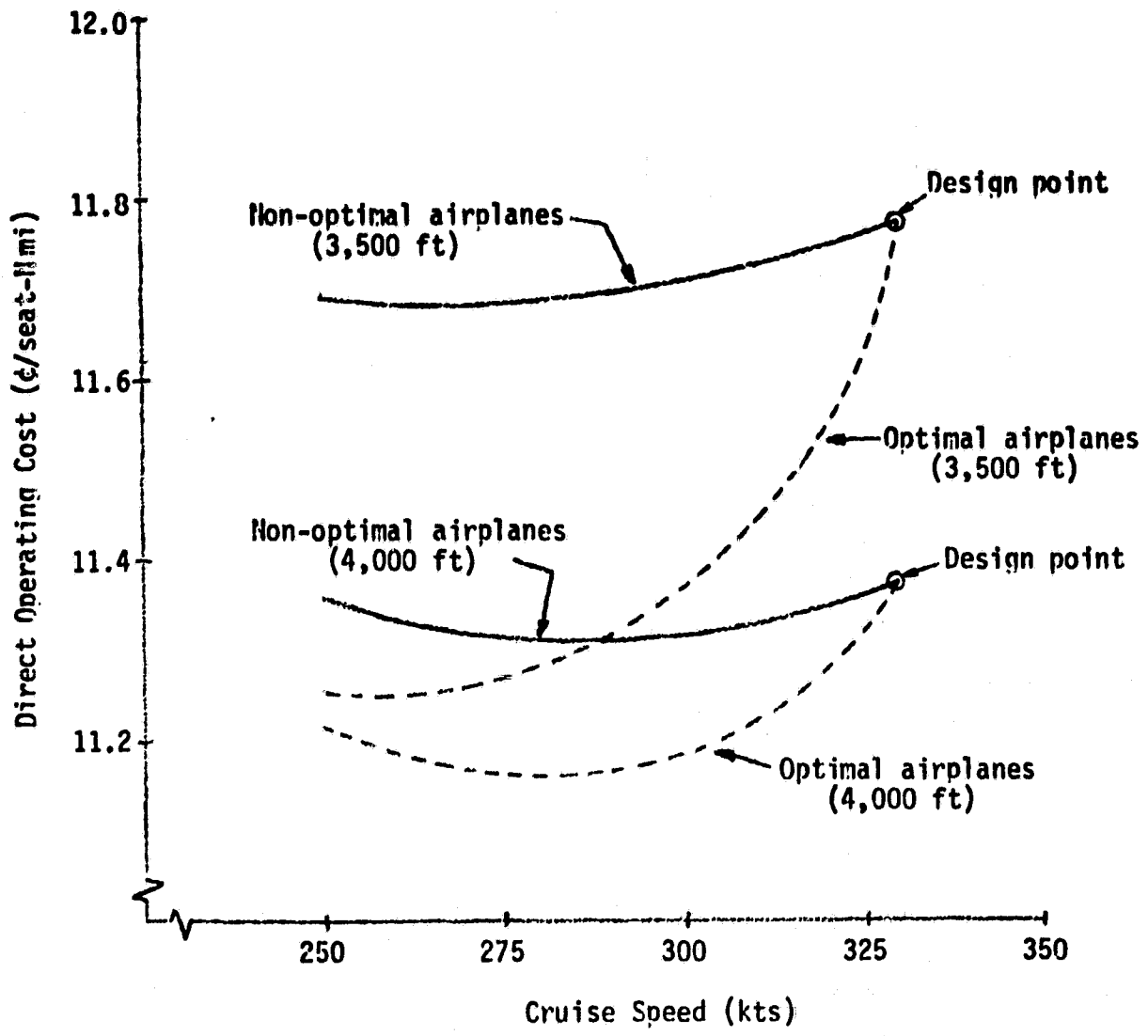


Figure 4. Cost for Non-Optimal Operation  
[330 kt designs flown at lower speeds]

**Appendix I**

**Program Listing**



COMPILER OPTIONS - NAME= MAIN,OPT=02,LINECNT=50,SIZE=0000K,  
 SOURCE,ECCDIC,NOLIST,NODECK,LOAD,MAP,NODEIT,IO,NOXREF  
 C PROGRAM TO MINIMIZE A FUNCTION OF N VARIABLES BY A VARIABLE  
 C METRIC ALGORITHM, WHICH, IN FACT, IS A SECOND ORDER GRADIENT  
 C METHOD USING AN ESTIMATED GRADIENT COMPUTATION (SUBROUTINE  
 C GRDENT).

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ISN 0002 COMMON/CONST/PI,G
ISN 0003 COMMON/BLOCK1/BLOCKT,BLOCKF,VCRUS,STAGE
ISN 0004 REAL K
ISN 0005 INTEGER COUNT
ISN 0006 DIMENSION XB(15),GR(15),C(15),X(15),T(15),B(15,15)
ISN 0007 N = 3
ISN 0008 IG = 0
ISN 0009 IFN = 0
ISN 0010 H = .2
ISN 0011 TOL = .0001

ISN 0012 PI = 3.1415927
ISN 0013 G = 32.18
ISN 0014 DO 500 LENGTH = 3500,4250,250
ISN 0015 FLEN = FLOAT(LENGTH)
ISN 0016 VCRUS = 422.25
ISN 0017 IFN = 0
ISN 0018 IG = 0

ISN 0019 DO 1 I = 1,N
ISN 0020 XB(I) = 1.
ISN 0021 CONTINUE

ISN 0022 CALL EVAL(XB,N,PO,FLEN)
ISN 0023 CALL INFO(FLEN)

ISN 0024 IFN = IFN + 1

ISN 0025 CALL GRDENT(PO,XB,N,GR,FLEN)
GR(1) = 2.*(XB1) - 1.) - 400.*XB1)*(XB2) - XB1)**2
GR(2) = 200.*(XB2) - XB1)**2

ISN 0026 IG = IG + 1

ISN 0027 DO 20 I = 1,N
ISN 0028 DO 21 J = 1,N
ISN 0029 B(I,J) = 0.

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ISN 0030      21      CONTINUE
ISN 0031      B(I,I) = 1.
ISN 0032      20      CONTINUE
C
C SET COUNTER
C
C      ILAST = IG
C
C START MAIN ITERATION LOOP.
C
4      WRITE(6,100)IG,IFN,PO
ISN 0034
ISN 0035      100     FORMAT(/,IX,'GRADS,RFUNCS,FUNC VALUE = ',215,F16.8)
ISN 0036      WRITE(6,79)(GR(I),I=1,N),(XB(I),I=1,N)
ISN 0037      79      FORMAT(IX,'GRADS = ',3F16.8,/, ' VARIABLES = ',3F16.8)
C
ISN 0038      DO 22 I = 1,N
ISN 0039      X(I) = XB(I)
ISN 0040      C(I) = GR(I)
ISN 0041      22      CONTINUE
C
C COMPUTE THE STEP VECTOR, T, AND THE DIRECTION INDICATOR, DI.
C
ISN 0042      DI = 0.
ISN 0043      DO 23 I = 1,N
ISN 0044      SS = 0.
ISN 0045      DO 24 J = 1,N
ISN 0046      SS = SS - B(I,J)*GR(J)
ISN 0047      24      CONTINUE
ISN 0048      T(I) = SS
ISN 0049      DI = DI - SS*GR(I)
ISN 0050      23      CONTINUE
C
ISN 0051      C NOW, DETERMINE WHICH DIRECTION WE ARE TRAVELLING.
C
C      IF (DI .LE. 0.) GO TO 60
C
C      IF WE ARE GOING DOWN, CONTINUE THE SEARCH.
C
C      K = 1
C      COUNT = 0
C
C FIND THE NEXT STATE VECTOR.
C
ISN 0053      DO 25 I = 1,N
ISN 0054      STEP = K*T(I)
ISN 0055      IF (ABS (STEP) .GT. .1) STEP = .1*STEP/ABS(STEP)
ISN 0056      XB(I) = X(I) + STEP
ISN 0057      IF (XB(I) .EQ. X(I)) COUNT = COUNT + 1
ISN 0058      25      CONTINUE
ISN 0059
ISN 0060      C DETERMINE CONVERGENCE
ISN 0061      IF (COUNT .GE. N) GO TO 60
ISN 0062      CALL EVAL(XB,N,P,FLEN)
ISN 0063      IFN = IFN + 1
ISN 0064      C
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110. C TRY ACCEPTANCE TEST. IF THE NEW POINT IS NOT WITHIN THE TOLERANCE
111. C REQUIRED, CONTINUE THE ITERATION. IF SO, TRY A NEW TOLERANCE.
112.
113. PACC = P0 - D1*K*TOL
114. IF (P .GE. PACC) GO TO 70
115. P0 = P
116.
117. C COMPUTE THE GRADIENT AT THE NEW POINT.
118.
119. CALL GRDENT(P0,XB,N,GR,FLEN)
120. GR(1) = 2.*(XB(1) - 1.) - 400.*XB(1)*(XB(2) - XB(1)**2)
121. GR(2) = 200.*(XB(2) - XB(1)**2)
122. IG = IG + 1
123.
124. C COMPUTE GRADIENT DIFFERENCE DIRECTION.
125.
126.
127. D1 = 0.
128. DO 26 I = 1,N
129. T(I) = K*T(I)
130. C(I) = GR(I) - C(I)
131. D1 = D1 + T(I)*C(I)
132. CONTINUE
133.
134. IF (D1 .LE. 0.) GO TO 3
135.
136. C NOW DO SOME STUFF THAT I DON'T COMPLETELY UNDERSTAND.
137. C HAS TO DO WITH COMPUTING THE RATE OF CHANGE OF THE GRADIENT.
138.
139.
140. D2 = 0.
141. DO 27 I = 1,N
142. SS = 0.
143. DO 28 J = 1,N
144. SS = SS + B(I,J)*C(J)
145. CONTINUE
146. X(I) = SS
147. D2 = D2 + SS*C(I)
148. CONTINUE
149.
150. D2 = 1. + D2/D1
151. DO 29 I = 1,N
152. DO 29 J = 1,N
153. B(I,J) = B(I,J) - (T(I)*X(J) + X(I)*T(J)) - D2*T(I)*T(J))/D1
154. CONTINUE
155. GO TO 4
156.
157. IF (LAST .NE. IG) GO TO 3
158. GO TO 18
159.
160. K = M*K
161. GO TO 8
162.
163. WRITE(6,102)(XB(I),I=1,N)
164. FORMAT(/,IX,'VARIABLES = ',3F16.8)
165. WRITE(6,100)IG,IFN,P0
166. CALL EVAL(XB,N,P0,FLEN)

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CALL INFO(FLEN)

C

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ISN 0106  
ISN 0107  
ISN 0108

500 CONTINUE  
59 STOP  
END





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COMPILER OPTIONS - NAME= MAIN,OPT=02,LINECNT=58,SIZE=0000K,  
SOURCE,EBCDIC,NOLIST,NODECK,LOAD,MAP,NOEDIT,IO,NOXREF

ISN 0002	C	SUBROUTINE INFO(FL)	256.
	C		299.
	C		299.
	C		300.
	C		301.
	C		302.
	C		303.
	C		304.
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	C		306.
	C		307.
	C		309.
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	C		340.
	C		341.

ISN 0003	C	COMMON/CONSTR/DIST,DIFF,TOFL,XLFL,GAHSS,GAHER,CENT
ISN 0004	C	COMMON/BLOCK1/BLOCKT,BLOCKF,VCRUS,STAGE
ISN 0005	C	COMMON/CHARAC/CDP,E,B
ISN 0006	C	COMMON/HEIGHT/ONEPL,AFNT
ISN 0007	C	COMMON/GEOM/XMAC,SHE,SHG,BH,SVE,SVG,OV
ISN 0008	C	COMMON/VARIAB/TON,S,SLSHIP,AR,VCLIMB,HCRUS
ISN 0009	C	WRITE(6,200)VCRUS,FL
ISN 0010	200	FORMAT(1X,'CRUISE SPEED = ',F6.2,2X,'FIELD LENGTH = ',F7.1)
ISN 0011	C	WRITE(6,201)TON,S,SLSHIP,AR,VCLIMB,HCRUS
ISN 0012	201	FORMAT(//,1X,'TON,S,SLSHIP,AR = ',4F10.3,/, 'VCLIMB,HCRUS = ',2F9.2)
ISN 0013	C	WRITE(6,210)ONEPL,AFNT
ISN 0014	210	FORMAT(//,1X,'ZFW, AIRFRAME HEIGHT = ',2F10.2)
ISN 0015	C	WRITE(6,202)XMAC,SHG,SVE
ISN 0016	202	FORMAT(//,1X,'MAC = ',F5.3,/, 'GROSS HORIZONTAL AREA = ',F7.3)
ISN 0017	C	F7.3,/, 'EXPOSED VERTICAL AREA = ',F7.3)
ISN 0018	203	WRITE(6,203)CDP,E
ISN 0019	C	FORMAT(//, 'CDP,E = ',2F12.8)
ISN 0020	100	WRITE(6,100)DIST,DIFF,TOFL
	1	FORMAT(//,1X,'RANGE = ',F14.7,/,1X,'DIFF = ',F14.7,/,1X,'TOFL = ',F14.7)
ISN 0021	C	WRITE(6,101)XLFL,GAHSS,GAHER
ISN 0022	101	FORMAT(//,1X,'LFL = ',F14.7,/,1X,'2ND SEGMENT CLIMB GRADIENT = ',F14.7,/,1X,'ENROUTE CLIMB GRADIENT = ',F14.7)
ISN 0023	C	WRITE(6,204)STAGE,BLOCKT,BLOCKF
ISN 0024	204	FORMAT(//,1X,'STAGE LENGTH = ',F5.1,/, 'BLOCK TIME = ',F5.3,'HR',/, 'BLOCK FUEL = ',F8.2,'LBS')
ISN 0025	C	WRITE(6,102)CENT
ISN 0026	102	FORMAT(//,1X,'CENTS PER SEAT NAUTICAL MILE = ',F14.7,//)
ISN 0027	C	RETURN
ISN 0028	C	END

COMPILER OPTIONS - NAME= MAIN,OPT=02,LINECNT=50,SIZE=000K,  
SOURCE,EBCDIC,NOLIST,NODECK,LOAD,MAP,NODEFIT,IO,NODEREF

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391. C
392. C
393. C

SUBROUTINE RANGE(DIST,ACT,VCROSS)
  REAL MAXRNG
  COMON/VARIAB/TOM,S,SLSHIP,AR,VCLIMB,HCRUS
  COMON/HEIGHT/O:HEPL,AFHT
  COMON/CONST/PI,G
  COMON/CHARAC/CDP,E,E,D
  COMON/FLAG/KANT
  COMON/AERO/VEQM,CLALPH

  C COMPUTES THE TOM TO MEET THE MAXIMUM RANGE MISSION USING A FITTED
  C PARABOLA MINIMIZATION PROCEDURE. USES A GRID SEARCH TO FIND THE
  C BEST CLIMB SPEED AND CRUISE ALTITUDE FOR THE GIVEN AIRPLANE.
  TOM = 60000.
  TOMH = 50000.
  ICOUNT = 0

  C BEGIN SEARCH LOOP ON CLIMB SPEED.
  DO 200 I = 250,300,25
    CLMSFD = FLOAT(I)

  C BEGIN SEARCH LOOP ON CRUISE ALTITUDE.
  DO 100 J = 20000,30000,5000
    HMAX = FLOAT(J)
    WRITE(6,300)HMAX,CLMSFD
    FORRAT(//,1) HCRUS,VCLM = ',2F14.4)
    ICOUNT = ICOUNT + 1
    ITRNUM = 1
    TEMP = 518.69 - .00356*HMAX
    XPACH = VCROSS/SQRT((1.4*1718.*TEMP)
    BETA2 = 1. - ((1.07*(XMAC))**2
    CLALPH = ((2.*PI*AR)/(2.*SQRT((AR**2*BETA2**1.0628*4.))))

  C CALCULATE DESIGN EQUIVALENT STRUCTURAL SPEED AT 10000 FT.
  VEQH = 1.07*VCROSS*SQRT(.0017553/.0023769)

  C
  RHO = 2.3769E-3*(1. - 6.8634E-6*HMAX)**(4.2645)
  Q = .5 * RHO * VCROSS**2

  C GUESS TOM AND FIND EMPTY HEIGHT.
  X2 = 25000.
  STEP = X2/50.
  MAXRNG = 600.
  CORV = 1.
  H = HMAX
  VCL = CLMSFD

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C  NOW CALL THE FUNCTION EVALUATION ROUTINE TO FIND THE TON FOR THE
C  GIVEN RANGE.
C  MINIMIZATION ROUTINE
C  CALL DISTR(X2,F2,H,VCL,HD,Q,MAXRNG,MC,FI,VCRUS,ZFH,MTAF)
C  TEST FOR CLIMB VIOLATION.  KANT IS 1 IF CLIMB GRADIENT < 0.
    IF (KANT .EQ. 0) GO TO 10
    IF (ICOUNT .EQ. 1) GO TO 30
    IF (ICOUNT .NE. 1) GO TO 100
C 10  X3 = X2 + STEP
    X1 = X2 - STEP
    CALL DISTR(X1,F1,H,VCL,HD,Q,MAXRNG,MC,FI,VCRUS,ZFH,MTAF)
    CALL DISTR(X3,F3,H,VCL,HD,Q,MAXRNG,MC,FI,VCRUS,ZFH,MTAF)
    INTNUM = INTNUM + 1
    IF (INTNUM .GT. 50) GO TO 89
    IF (F1 .LE. F2) GO TO 1
    IF (F3 .LE. F2) GO TO 2
C  WHERE F2 IS LESS THAN F1 AND F3, FIT A PARABOLA, FIND MINIMUM AND
C  USE THAT AS THE NEXT X2
C  X2 = X2 + .5*STEP*(F1-F3)/(F3-2.*F2+F1)
    CALL DISTR(X2,F2,H,VCL,HD,Q,MAXRNG,MC,FI,VCRUS,ZFH,MTAF)
    IF (F2 .LE. CONV) GO TO 99
    STEP = STEP/3.
    GO TO 10
C  WHERE F2 IS BETWEEN OR GREATER THAN F1 AND F3, MAKE X2 THE VALUE
C  FOR A MINIMUM
C 1  IF (F3 .LT. F1) GO TO 2
    X3 = X2
    F3 = F2
    X2 = X1
    F2 = F1
    X1 = X1 - STEP
    CALL DISTR(X1,F1,H,VCL,HD,Q,MAXRNG,MC,FI,VCRUS,ZFH,MTAF)
    GO TO 3
    X1 = X2
    F1 = F2
    X2 = X3
    F2 = F3
    X3 = X3 + STEP
    CALL DISTR(X3,F3,H,VCL,HD,Q,MAXRNG,MC,FI,VCRUS,ZFH,MTAF)
    GO TO 3
C  NOT CONVERGING IF INTNUM > 50.  PRINT ERROR MESSAGE.
C 89  WRITE(6,302)
    302  FORMAT(' INTNUM = 50, CONTINUING ....')
    ISN 0073
    ISN 0074

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ISN 0075      GO TO 100
C 99          IF (X2 .GE. TOMH) GO TO 100
              CALL MAXTR(MC,VCRUS,H,DIFF)
              IF (DIFF .LT. 0. .AND. HMAX .NE. 20000.) GO TO 100
              WCH = WC
              AFMT1 = WTAF
              ONEPL1 = ZFW
              DIST1 = FI
              TOMH = X2
              HCRUS = HMAX
              CONTINUE
C 100
C 99          IF (TOMH .GE. TOM) GO TO 200
              TOM = TOMH
              VCLIMB = CLMSP0
              WCT = WCH
              AFMT = AFMT1
              ONEPL = ONEPL1
              DIST = DIST1
              CONTINUE
C 200
C 99          RETURN
C 30         CALL INFO
              STOP
C           END
ISN 0076
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LEVEL 21.3 ( JUN 74 )

05/360 FORTRAN H

DATE 02.016/13-51.50

COMPILER OPTIONS - NAME= MAIN,OPT=02,LIRECNT=53,SIZE=0000K,  
SOURCE,EBCDIC,NOLIST,NODECK,LOAD,MAP,NOEDIT,LD,NOXREF

```
C
C
C      SUBROUTINE TAKOFF(TOFL)
C      COMMON/VARIAD/TOH,S,SLSHP,AR,VCLIMB,ICRUS
C
C      COMPUTES FAR TAKEOFF DISTANCE BASED ON PROF SHEVELL'S CURVE
C      FOR TWIN ENGINE AIRCRAFT IN AA 241 NOTES. CURVE WAS FITTED
C      TO A QUADRATIC ---  $952.0 + 26.672A + .0255A^2$  -- MICRE A
C      IS THE PARAMETER  $KC2/SIGNA*CLMAX*SNTH$ . TAKEOFF POWER VS.
C      SPEED FOR SEA LEVEL AND ISA + 30.0 DEGREES F WAS FITTED TO
C      A CUBIC. POWER RATIO WAS BASED ON THE GENERAL ELECTRIC CT-7
C      ENGINE. ETA OF .65 IS ASSURED FOR TAKEOFF.
C
C      ETA = .65
C      CLMAX = 2.25
C      V = .84 * SQRT((2.*TOH)/( .002244*CLMAX*S ))
C
C      SHP = SLSHP/(.89181-4.057E-4*V+3.2768E-6*V**2-5.2103E-9*V**3)
C      TH = 550.*ETA*SHP/V
C
C      A = TOH**2/(1.9441*CLMAX*SNTH)
C      TOFL = 952.0 + 26.672*A + .0255*A**2
C
C      RETURN
C      END

ISN 0002
ISN 0003

ISN 0004
ISN 0005
ISN 0006

ISN 0007
ISN 0008

ISN 0009
ISN 0010

ISN 0011
ISN 0012
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COMPILER OPTIONS - NAME= MAIN,OPT=02,LINECNT=50,SIZE=000K,  
SOURCE,EBCDIC,NOLIST,NOECK,LOAD,FAP,NOEDIT,IG,NOXREF

ISN 0002	C	SUBROUTINE LANDING(XLFL)	531.
ISN 0003	C	COMMON/VARIAD/TOH,S,SLSH,AR,VCLIMB,HCRUS	532.
ISN 0004	C	COMPUTES LANDING DISTANCE USING LINEAR FITTED CURVE OF LANDINGS	533.
ISN 0005	C	DISTANCE VS STALL SPEED SQUARED. ASSUMES DOUBLE SLOTTED FLAPS BUT	534.
ISN 0006	C	NO SLATS. MAX LANDING HEIGHT EQUALS TOH.	535.
ISN 0007	C	VS2 = 2.*TOH/(.002244*2.67*SW1.689**2)	536.
		XLFL = .4*VS2 + 750.	537.
		RETURN	539.
		END	540.
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 ISN 0049

C EXPOSED AREA IS THE TOTAL AREA MINUS THAT AREA COVERED BY THE  
 C FUSELAGE.  
 C  
 SE =  $(18 - 8.116/2.)*(\text{CRF} + .4*\text{CR})$   
 SNET = 2.04\*SVE  
 C  
 C FIND THE EXPOSED MAC AND THE REYNOLDS NUMBER ASSOCIATED WITH THAT  
 C LENGTH AT A CRUISE SPEED OF 290 KT AT 25,000 FT.  
 C  
 XNACE =  $.6667*(\text{CRF} + .4*\text{CR} - .4*\text{CRF}*\text{NCR}/(\text{CRF} + .4*\text{CR}))$   
 RE =  $1.867E6*XNACE$   
 C  
 C FRICTION COEFFICIENT IS A FUNCTION OF THE LOG(BASE 10) OF THE  
 C REYNOLD NUMBER.  
 C  
 RELOG =  $\text{ALOG10}(\text{RE})$   
 CF =  $(78.868 - 26.463*(\text{RELOG}) + 3.1025*(\text{RELOG})**2 - .12417*(\text{RELOG})$   
 1 \*\*\*J\*\*I.E-3  
 C  
 C FIND THE FORH FACTOR USING THE FORMULA GIVEN IN THE AA241 NOTES.  
 C  
 Z =  $1.75*\text{COS}(\text{SHEEP})/\text{SQRT}(1. - .25*\text{COS}(\text{SHEEP}))**2$   
 K =  $1. + Z*\text{TCH} + 100.*\text{TCH}**4$   
 WRITE(6,\*)SNET,CF,K,TCH,Z  
 C  
 C NOW FIND THE F OF THE HING.  
 C  
 FWING =  $\text{CF}*K*\text{SNET}$   
 C  
 C DO THE SAME THING FOR THE HORIZONTAL TAIL.  
 C  
 SNET = 2.04\*SHE  
 RE =  $1.867E6*SHE/\text{BH}$   
 RELOG =  $\text{ALOG10}(\text{RE})$   
 CF =  $(78.868 - 26.463*(\text{RELOG}) + 3.1025*(\text{RELOG})**2 - .12417*(\text{RELOG})$   
 1 \*\*\*J\*\*I.E-3  
 Z =  $1.75*\text{COS}(\text{SHEEP})/\text{SQRT}(1. - .25*\text{COS}(\text{SHEEP}))**2$   
 K =  $1. + Z*\text{TCH} + 100.*\text{TCH}**4$   
 FHORIZ =  $\text{CF}*K*\text{SNET}$   
 C  
 C NOW DO THE SAME FOR THE VERTICAL TAIL.  
 C  
 SNET = 2.04\*SVE  
 RE =  $1.867E6*SVE/\text{BV}$   
 RELOG =  $\text{ALOG10}(\text{RE})$   
 CF =  $(78.868 - 26.463*(\text{RELOG}) + 3.1025*(\text{RELOG})**2 - .12417*(\text{RELOG})$   
 1 \*\*\*J\*\*I.E-3  
 Z =  $1.75*\text{COS}(\text{SHEEP})/\text{SQRT}(1. - .25*\text{COS}(\text{SHEEP}))**2$   
 K =  $1. + Z*\text{TCV} + 100.*\text{TCV}**4$   
 FVERT =  $\text{CF}*K*\text{SNET}$   
 C  
 C FIND THE GAP DRAG USING THE METHOD OF AA241.  
 C  
 FGAP =  $.0042*(\text{EH}*(\text{COS}(\text{SHEEP}))**2 + \text{DV}*(\text{COS}(\text{SHEEPV}))**2 + \text{B}/4.)$   
 C  
 C THE CONSTANT F'S HAVE BEEN DETERMINED AS:

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C      FFUSE = 3.799
      FNACPY = 1.15
C      NOW FIND THE TOTAL F USING MISCELLANEOUS DRAG TO EQUAL 6%.
C      FTOT = (FNING+FHORIZ+FVERT+FFUSE+FNACPY+FGAP)/.94
C      TO FIND THE PARASITE DRAG COEFFICIENT, DIVIDE BY THE NING AREA.
C      COP = FTOT/5
C      EFFICIENCY FACTOR IS CALCULATED USING INDUCED DRAG FACTORS
      FOUND IN SHEVELL'S NOTES.
C      SS = 1. - .0745*(8.116/B) - 1.6338*(8.116/B)**2
      U = .99867+4.33864E-4*AR-9.59822E-5*AR**2+2.02546E-6*AR**3
      E = 1./(PI*AR*(1./(PI*AR*U*SS))+.4369*COP))
C      RETURN
      END
ISN 0050
ISN 0051

ISN 0052

ISN 0053

ISN 0054
ISN 0055
ISN 0056

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ISN 0058

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ISN 0032 C VERTICAL TAIL AND RUDDER HEIGHT; VERTICAL AVG T/C = .12  
 ISN 0033 C XI3=(F2\*BV\*\*3\*(8.+44\*TCM/Z)\*IE-3)/(1.12\*.96\*.75\*SVI)  
 ISN 0034 C W3 = (.0145\*XI3 + 3.51)\*.75\*SVI  
 W4 = 1.6\*W3/3.  
 ISN 0035 C SURFACE CONTROLS HEIGHT  
 ISN 0036 C W5 = 1.7\*(SIG+SVG)  
 IF (F1 .LT. 2.5) F1 = F3  
 ISN 0037 C FUSELAGE HEIGHT  
 ISN 0038 C SLSHPH = SLSHP/2.  
 ISN 0039 C WENG = 2\*(-16.56 + 12.58\*SQRT(SLSHPH) + .0610\*SLSHPH)  
 ISN 0040 C W9 = 6520. + WENG  
 ISN 0041 C W0 = 1940. + WENG  
 ISN 0042 C T1 = .6\*F1\*(Z1-W1-W0)\*66./((PI\*8.116\*\*2)  
 ISN 0043 C T2 = T1 - T7  
 ISN 0044 C IF (T2 .LT. 0.) T2 = 0.  
 ISN 0045 C XI6 = (T7 + (T2\*\*2/(2.\*T1)))\*IE-3  
 ISN 0047 C W6 = (.102\*XI6 + 1.051)\*1472.47  
 ISN 0048 C DETERMINE ZFH. COMPARE WITH ESTIMATED ZFH. IF NOT SAME,  
 ISN 0049 C ITERATE.  
 ISN 0051 C Z2 = W1+W2+W3+W4+W5+W6+W7+.65\*W9+W6270.  
 ISN 0052 C ZFH = Z2  
 WTAZ = Z2 - 7270. - WENG  
 ISN 0053 C RETURN  
 ISN 0054 C END

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DATE 02.016/13.52.09

05/360 FORTRAN H

LEVEL 21.5 ( JUN 74 )

COMPILER OPTIONS - NAME= MAIN,OPT=02,LINECNT=50,SIZE=000K,  
SOURCE,EBCDIC,NOLIST,NODECK,LOAD,MAP,NODEIT,IO,NOXREF

```

C
C      REAL FUNCTION DRAG(H,H,V,COFO,S)
C
C      COMMON/CHARAC/COPI,E,B
C      COMMON/CONST/PI,G
C
C      COMPUTES DRAG FOR A GIVEN FLIGHT CONDITION
C
C      RHO = 2.3769E-3*(1 - 6.8634E-6*H)**4*(4.2648)
C      Q = .5*RHO*V**2
C      DRAG = CDPO*Q*S + (H**2)/(Q*PI*(B**2)*E)
C
C      RETURN
C      END

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C      RC = V*GAM*AC
C
C      CALCULATE FUEL TO CLIMB
C
      IF (H .EQ. 0.) GO TO 20
      DELTAF = (SHP*SFC)/(3600.*RC)*DH
      FC = FC + DELTAF
      W = H - DELTAF
C
C      CALCULATE DISTANCE TO CLIMB
C
      DELTAD = V*DH/RC
      DC = DC + DELTAD
C
C      CALCULATE TIME TO CLIMB
C
      DELTAT = DH/RC
      TC = TC + DELTAT
C
C      TAKE A STEP
C
20    H = H + DH
      IF (H .LE. HMAX) GO TO 10
C
60    CONTINUE
      GO TO 70
C
C      ERROR MESSAGE
C
50    WRITE(6,100)
100   FORMAT(1X,'AIRPLANE CANNOT CLIMB --- INADEQUATE FUEL OR HP.')
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70    RETURN
      END
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ISN 0025

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ISN 0044









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PAGE 002

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ISN 0031 X2 = X2 + .5*STEP*(F1-F3)/(F3-2.*F2+F1)
ISN 0032 CALL DISTN(X2,F2,HMAX,VCLIMB,MD,Q,STAGEN,MC,FI,TC,FC,VCRUS)
ISN 0033 IF (F2 .LE. CONV) GO TO 99
ISN 0034 STEP = STEP/4.
ISN 0035 GO TO 10
ISN 0036

C 1 IF (F3 .LT. F1) GO TO 2
ISN 0037 X2 = X1
ISN 0039 F2 = F1
ISN 0040 X1 = X1 - STEP
ISN 0041 CALL DISTN(X1,F1,HMAX,VCLIMB,MD,Q,STAGEN,MC,FI,TC,FC,VCRUS)
ISN 0042 GO TO 3
ISN 0043

C 2 X1 = X2
ISN 0044 F1 = F2
ISN 0045 X2 = X3
ISN 0046 F2 = F3
ISN 0047 X3 = X3 + STEP
ISN 0048 CALL DISTN(X3,F3,HMAX,VCLIMB,MD,Q,STAGEN,MC,FI,TC,FC,VCRUS)
ISN 0049 GO TO 3
ISN 0050

C 89 WRITE(6,302)
ISN 0051 FORMAT(' INTNUM = 50, CONTINUING ...')
ISN 0052

C 99 CONTINUE
ISN 0053 BLOCKF = FD + FC + (MC - MD) + .002*TON
ISN 0054 BLOCKT = TD/60. + TC/3600. + FI*6072./(VCRUS*3600.) + .25
ISN 0055

C RETURN
ISN 0056 END
ISN 0057
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COMPILER OPTIONS - NAME= MAIN,OPT=02,LINCNT=50,SIZE=0000K,  
SOURCE,EBCDIC,NOLIST,NODECK,LOAD,MAP,NOEDIT,NOXREF

ISN 0002	C	SUBROUTINE DOC(STAGE,BLOCKT,BLOCKF,CENT)	1115.
ISN 0003	C		1116.
ISN 0004	C	COMMON/VARZAS/TOM,S,SLSHP,AR,VCLIMP,HCRUS COMMON/HEIGHT/CHEPL,AFHT	1117. 1118. 1119. 1120. 1121. 1122.
	C	COMPUTES THE DIRECT OPERATING COSTS FOR A TURBOPROP FOR THE STAGE LENGTH PRESCRIBED IN THE SUBROUTINE BLOCK . USES THE 1967 ATA METHOD. CONSTANTS INCLUDE NO OF ENGINES (2), NO OF CREH (2) AND NO OF PASSENGERS (30).	1123. 1124. 1125. 1126. 1127.
	C	THE ENGINE COST IS DETERMINED BY FITTING THE LOCKHEED SHIP VS COST PER SHIP CURVE FOUND IN THEIR 1980 COMPUTER STUDY. THE COSTS ARE INFLATED BY 25% TO ACCOUNT FOR 1979 DOLLARS. AIRFRAME WEIGHT IS ASSUMED TO BE 200 DOLLARS FOR EACH POUND OF AIRFRAME.	1128. 1129. 1130. 1131. 1132. 1133.
	C	DEFINE STAGE LENGTH IN STATUTE MILES, PRICE OF FUEL	1134.
ISN 0005	C	DOLGAL = 1.5	1135.
ISN 0006	C	SLSHH = SLSHP/2.	1136.
ISN 0007	C	STAGES = 1.15 * STAGE	1137. 1138. 1139.
	C	BLOCK SPEED	1140.
ISN 0008	C	BLOCKS = STAGES/BLOCKT	1141.
ISN 0009	C	T1 = BLOCKT - .25	1142. 1143. 1144.
	C	ENGINE AND AIRFRAME ACQUISITION COSTS	1145.
ISN 0010	C	COSTEN=2.5*(61.747+1.65592E5/SLSHH- 8.38354E7/SLSHH**2)*SLSHH	1146. 1147.
ISN 0011	C	COSTAF = 200. * AFHT	1148. 1149.
	C	CREH COST	1150.
ISN 0012	C	CRWCST = (.05*(TOM/1000.)*63.)/BLOCKS	1151. 1152. 1153.
	C	FUEL AND OIL COST	1154.
ISN 0013	C	FULCST = 1.02*(BLOCKF*DOLGAL/6.7 + 2.*.135*10.*BLOCKT)/STAGES	1155. 1156. 1157.
	C	INSURANCE COST	1158.
ISN 0014	C	XINCST = .02*(COSTAF+COSTEN)/(2800.*BLOCKS)	1159. 1160. 1161.
	C	MAINTENANCE COST	1162.
	C	AIRFRAME LABOR	1163. 1164.
ISN 0015	C	XLADAF = .05*AFHT/1000. + 6. - (630./AFHT/1000.*120.)	1165.
ISN 0016	C	XLADAF = .59 * XLADAF	1166.
ISN 0017	C	AFLAB = (XLADAF**T1+XLADAF)/STAGES * 12.	1167. 1168.

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ISN 0018	C	AIRFRAME MATERIAL	1169.
	C	AFMAT = (.13*.08*COSTAF*T1)+(6.24*COSTAF)/(1E6*STAGES)	1170.
	C	ENGINE LABOR	1171.
	C	ENGINE LABOR	1172.
	C	ENGINE LABOR	1173.
	C	ENGINE LABOR	1174.
ISN 0019	C	XLABEF = (.65+(.03*SLSHH)/1000.)*2.	1175.
ISN 0020	C	XLADBEH = (.3+(.03*SLSHH)/1000.)*2.	1176.
ISN 0021	C	ENGLAB = (XLABEF*T1+XLADBEH)/STAGES * 12.	1177.
	C	ENGINE MATERIALS	1179.
	C	ENGINE MATERIALS	1179.
	C	ENGINE MATERIALS	1180.
ISN 0022	C	ENGHAT = ((2.5*COSTEN)*T1 + 2.*COSTEN)/(1E5*STAGES)	1181.
	C	ENGHAT = ((2.5*COSTEN)*T1 + 2.*COSTEN)/(1E5*STAGES)	1182.
	C	MAINTENANCE BURDEN	1183.
	C	MAINTENANCE BURDEN	1183.
	C	MAINTENANCE BURDEN	1184.
ISN 0023	C	BURDEN = 1.8 * (AFLAB + ENGLAB)	1185.
	C	BURDEN = 1.8 * (AFLAB + ENGLAB)	1186.
	C	TOTAL MAINTENANCE COST	1187.
	C	TOTAL MAINTENANCE COST	1187.
	C	TOTAL MAINTENANCE COST	1188.
ISN 0024	C	TOTHA1 = AFLAB + AFMAT + ENGLAB + ENGHAT + BURDEN	1189.
	C	TOTHA1 = AFLAB + AFMAT + ENGLAB + ENGHAT + BURDEN	1190.
	C	TOTHA1 = AFLAB + AFMAT + ENGLAB + ENGHAT + BURDEN	1191.
	C	TOTHA1 = AFLAB + AFMAT + ENGLAB + ENGHAT + BURDEN	1192.
ISN 0025	C	DEPR = ((COSTAF*COSTEN)+.1*COSTAF+.4*COSTEN)/(BLOCKS*15.*2900.)	1193.
	C	DEPR = ((COSTAF*COSTEN)+.1*COSTAF+.4*COSTEN)/(BLOCKS*15.*2900.)	1194.
	C	DEPR = ((COSTAF*COSTEN)+.1*COSTAF+.4*COSTEN)/(BLOCKS*15.*2900.)	1195.
	C	DEPR = ((COSTAF*COSTEN)+.1*COSTAF+.4*COSTEN)/(BLOCKS*15.*2900.)	1196.
	C	DEPR = ((COSTAF*COSTEN)+.1*COSTAF+.4*COSTEN)/(BLOCKS*15.*2900.)	1197.
ISN 0026	C	CENTS PER SEAT STATUTE MILE	1199.
	C	CENTS PER SEAT STATUTE MILE	1199.
	C	CENTS PER SEAT STATUTE MILE	1200.
	C	CENTS PER SEAT NAUTICAL MILE	1201.
	C	CENTS PER SEAT NAUTICAL MILE	1202.
ISN 0027	C	CENT = CENTS * 1.15	1203.
	C	CENT = CENTS * 1.15	1204.
ISN 0028	C	RETURN	
ISN 0029	C	END	



COMPILER OPTIONS - NAME= MAIN,OPT=02,LINECNT=50,SIZE=0000K,  
SOURCE,EBCDIC,NOLIST,NODECK,LOAD,HAP,NOEDIT,NOXREF

```

C
C
C
C
ISN 0002 SUBROUTINE DISTR(X,F,HMAX,EAS,LD,Q,MAXRNG,MC,F1,VCRUS,ZFH,HTAF)
ISN 0003 REAL MAXRNG
ISN 0004 COMMON/CONST/PI,G
ISN 0005 COMMON/CHARAC/CDP,E,B
ISN 0006 COMMON/VARJAB/TOH,S,SLSHP,AR,VCLIMD,ICRUS
ISN 0007 COMMON/GEOM/XRAC,SIE,SHG,BH,SVE,SVG,BV
ISN 0008 COMMON/HEIGHT/OREPL,AFHT
ISN 0009 COMMON/FLAG/KANT

C
C FUNCTION EVALUATION FOR FINDING THE TOW FOR THE REQUIRED RANGE.
C
ETA = .8
COPO = CDP
CALL POUNDS(X,S,SLSHP,ZFH,HTAF)
CALL DESENT(SLSHIP,S,HMAX,ETA,FD,TD,DD,MD,ZFH)
CALL CLIND(S,SLSHIP,X,HMAX,EAS,COPO,ETA,FC,TC,DC,CC,MC)
IF (MD .GT. MC) KANT = 1
IF (KANT .NE. 0) GO TO 10

C
C
C
C
DAV = CDP*QS + (MC**2+LD**2)/(2.*Q*PI*B**2*E)
SHIPAV = DAV*VCRUS/(550.*.85)
SHIPMAX = POKER(SLSHIP,VCRUS,HMAX)
Z = SHIPAV/SHIPMAX
SFC = .43 + 2.07E-2/Z + 2.02E-2/Z**2 - 1.04E-3/Z**3

C
C
A1 = 325.*(LD/SFC)*B*SQRT(PI*E/(CDP*MS))
A2 = Q*SQRT(CDP*PI*E*MS)
F1 = A1*(ATAN(MC/A2) - ATAN(MD/A2)) + (DD + DC)/6072.
GO TO 20

C
C IF AIRPLANE CANNOT CLIMB, LET THE RAISE BE EQUAL TO GARRAC.
C
ISN 0020 F1 = GC
ISN 0029 F = (F1 - MAXRNG)**2
C
ISN 0030 RETURN
ISN 0031 END

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