

# THE AXISYMETRIC ELASTICITY PROBLEM FOR A Laminated plate containing a circular hole 

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# THE AXISYMMETRIC ELASTICITY PROBLEM <br> FOR A LAMINATED PLATE CONTAINING <br> A CIRCULAR HOLE* 

by
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#### Abstract

In this paper the elasticity problem for a laminated thick plate which consists of twc bonded dissimilar layers and which contains a circular hole is considered. The problem is formulated for arbitrary axisymmetric tractions on the hole surface by using the Love strain function. Through the expansion of the boundary conditions into Fourier series the problem is reduced to an infinite system of algebraic equations which is solved by the method of reduction. Of particular interest in the problem are the stresses along the interface as they relate to the question of delamination failure of the composite plate. These stresses are calculated and are observed to become unbounded at the hole boundary. An approximate treatment of the singular behavior of the stress state is presented and the stress intensity factors are calculated.


## 1. INTRODUCTION

In this paper the elasticity problem for a thick plate which consists of two bonded dissimilar homogeneous layers is considered. It is assumed that the plate is infinite, contains a circular hole, and is subjected to axisymmetric external loads. Even though the problem as stated may have some applications, from a practical viewpoint the important problem is that of a laminated plate containing a circular hole and subjected to uniaxial membrane or bending loads away from the hole region. The latter problem has important applications in the analysis of delamination failure of perforated multilayered plate and shell structures. In such structures the interface stresses are known to have a power singularity which greatly enhances the possibility of

[^0]delamination failure [1,2,3]. In a laminated plate under general loading conditions one may always separate a homogeneous solution and reduce the problem to a perturbation problem in which the self-equilibrating tractions on the hole surface are the only external loads. By expanding these tractions into Fourier series in $\theta$ one may further separate the problem into its simpler components in the independent variables $r$ and $z$ only. Thus, the axisymmetric problem treated in this paper may also be considered as the first component of the general three-dimensional plate problem.

The three-dimensional elasticity problem for laminated plates containing a hole does not seem to have been considered before (see, for example, [4] for a recent review). The existing solutions are mostly based on numerical techniques and are generally highly approximate [5-7]. The circular hole problem for a homogeneous thick plate was considered in [8] and [9]. The technique developed in [9] will be used to solve the laminated plate problem considered in this paper. The related problem of a layered semi-infinite medium (i.e., the limiting case of the hole problem in which the hole radius is infinite) was considered in [10] where the method of singular integral equations was used to solve the problem.
2. THE HOMOGENEOUS SOLUTION

In this section we give the results of some elementary solutions for a laminated plate without a hole which is subjected to certain uniform loading conditions at infinity. First we assume that the composite plate which consists of two layers with the elastic constants $E_{1}, v_{1}$ and $E_{2}, v_{2}$, and the thicknesses $h_{1}$ and $h_{2}$ is subjected to an average radial membrane stress $\sigma_{0}$ at $r=\infty$ and is constrained to remain flat upon deformations. Thus, defining

$$
\begin{equation*}
\sigma_{r r 1}(r, \theta, z)=\sigma_{1}, \sigma_{r r 2}(r, \theta, z)=\sigma_{2}, \tag{1}
\end{equation*}
$$

we have

$$
\begin{equation*}
\sigma_{\theta \theta 1}=\sigma_{1}, \sigma_{\theta \theta 2}=\sigma_{2}, \tag{2}
\end{equation*}
$$

and all the remaining stress componerits are zero. From

$$
\begin{equation*}
\sigma_{1} h_{1}+\sigma_{2} h_{2}=\sigma_{0}\left(h_{1}+h_{2}\right), \varepsilon_{r r 1}=\varepsilon_{r r 2} \tag{3}
\end{equation*}
$$

it then follows that

$$
\begin{align*}
& \sigma_{1}=\sigma_{0} \frac{\left(1-v_{2}\right) m(1+k)}{1-v_{1}+m k\left(1-v_{2}\right)}, \\
& \sigma_{2}=\sigma_{0} \frac{\left(1-v_{1}\right)(1+k)}{1-v_{1}+m k\left(1-v_{2}\right)}, \tag{4a,b}
\end{align*}
$$

where

$$
\begin{equation*}
m=E_{1} / E_{2}, k=h_{1} / h_{2} \tag{5}
\end{equation*}
$$

Next we consider the composite plate which is uniformly loaded by an average stress $\sigma_{0}$ in $x$-direction only.
Defining now

$$
\begin{equation*}
\sigma_{x x 1}(x, y, z)=\sigma_{1}, \sigma_{x x 2}(x, y, z)=\sigma_{2}, \tag{6}
\end{equation*}
$$

and again assuming that the plate is constrained to remain flat, the nonzero stress components $\sigma_{1}, \sigma_{2}, \sigma_{y y 1}, \sigma_{y y 2}$ may be determined from

$$
\begin{align*}
& \sigma_{1} h_{1}+\sigma_{2} h_{2}=\sigma_{0}\left(h_{1}+h_{2}\right), \varepsilon_{x x 1}=\varepsilon_{x x 2}, \\
& \sigma_{y y 1} h_{1}+\sigma_{y y 2} h_{2}=0, \quad \varepsilon_{y y 1}=\varepsilon_{y y 2} \tag{7a-d}
\end{align*}
$$

Solving (7) we have

$$
\begin{align*}
& \sigma_{1}=\frac{\sigma_{0}(1+k)\left[m\left(1-v_{1} v_{2}\right)+m^{2} k\left(1-v_{2}^{2}\right)\right]}{1-v_{1}^{2}+2 m k\left(1-v_{1} v_{2}\right)+m^{2} k^{2}\left(1-v_{2}^{2}\right)}, \\
& \sigma_{2}=\sigma_{0}(1+k)-\sigma_{1} k, \\
& \sigma_{y y l}=\frac{\sigma_{1}-m \sigma_{2}}{v_{1}+m k v_{2}}, \sigma_{y y 2}=-k \sigma_{y y 1} \tag{8a-d}
\end{align*}
$$

Referring to the cylindrical coordinates the stress states in the layers 1 and 2 may be expressed as

$$
\begin{align*}
& \sigma_{r r j}=\frac{\sigma_{j}^{+\sigma} y y j}{2}+\frac{\sigma_{j}^{-\sigma} y y j}{2} \cos 2 \theta, \\
& \sigma_{\theta \theta j}=\frac{\sigma_{j}^{+\sigma} y y j}{2}-\frac{\sigma_{j}-\sigma_{y y j}}{2} \cos 2 \theta, \\
& \sigma_{r \theta j}=-\frac{\sigma_{j}-\sigma_{y y j}}{2} \sin 2 \theta, \\
& \sigma_{z z j}=\sigma_{r z j}=\sigma_{\theta z j}=0, \quad(j=1,2) . \tag{9a-f}
\end{align*}
$$

Solutions similar to that given by (4) and (8) may also be obtained for other types of uniform external loads such as bending and thermally induced loading.

## 3. SOLUTION OF THE AXISYMMETRIC PROBLEM

The problem of a laminated plate containing a circular hole with a radius a may now be solved by superimposing on the homogeneous solutions found in the previous section a perturbation solution in which the tractions $-\sigma_{r a j}(a, \theta, z),\left(\alpha=r, \theta, z ; j=1,2 ; 0 \leq \theta<2 \pi,-h_{2}<z<h_{1}\right)$ acting on the hole boundary are the only external loads, where the stress state $\sigma_{\beta \alpha j}(r, \theta, z)$, ( $\beta, \alpha=r, \theta, z ; j=1,2$ ) is given by the homogeneous solution. From, for example, (1), (4), (8), and (9) it may be seen that the simplest such perturbation problem is an axisymmetric problem corresponding to the
axisymmetrically loaded plate or to the first part of the unidirectionally loaded plate (i.e., to the $\theta$-independent part of the solution given by (9)). Thus, in this section we will consider the axisymmetric problem for the composite plate subjected to the following boundary conditions (Figure 1):

$$
\sigma_{r r j}(a, z)=\sigma_{j}(z), \sigma_{r z j}(a, z)=\tau_{j}(z),(j=1,2)(10 a, b)
$$

where $\sigma_{j}$ and $\tau_{j}$ are known tractions acting on the layers 1 and 2 , respectively. Note that the solution is independent of $\theta$ and the shear stres $\sigma_{6 \beta j}=0,(\beta=r, z ; j=1,2)$ everywhere.

To formulate the problem the technique described in [9] will be used. Because of axisymmetry, it is sufficient to use the z-component of the Galerkin vector only which is nothing but the Love strain function $Z(r, z)[11,12]$. In addition to the surface tractions given by (10) the composite plate is subjected to the following homogeneous boundary, continuity, and regularity conditions (Figure 1):

$$
\begin{align*}
& \sigma_{r 21}\left(r, h_{1}\right)=0, \sigma_{z z 1}\left(r, h_{1}\right)=0,(a<r<\infty),  \tag{11}\\
& \sigma_{r z 2}\left(r,-h_{2}\right)=0, \sigma_{z z 2}\left(r,-h_{2}\right)=0,(a<r<\infty),  \tag{12}\\
& \sigma_{r 21}(r, 0)=\sigma_{r z 2}(r, 0), \sigma_{z z 1}(r, 0)=\sigma_{z z 2}(r, 0),(a<r<\infty)  \tag{13}\\
& u_{r 1}(r, 0)=u_{r 2}(r, 0), u_{z 1}(r, 0)=u_{z 2}(r, 0),(a<r<\infty),  \tag{14}\\
& \sigma_{r r j}(\infty, z)=0, \quad \sigma_{r z j}(\infty, z)=0,(j=1,2) . \tag{15}
\end{align*}
$$

Let $z_{1}$ and $z_{2}$ be the Love strain functions for layers 1 and 2 , respectively (Figure 1). In the absence of body forces $Z_{1}$ and $Z_{2}$ satisfy

$$
\begin{equation*}
\nabla^{2} \nabla^{2} Z_{j}(r, z)=0, \quad \nabla^{2}=\frac{\partial^{2}}{\partial r^{2}}+\frac{1}{r} \frac{\partial}{\partial r}+\frac{\partial^{2}}{\partial z^{2}} \quad, \quad(j=1,2), \tag{16}
\end{equation*}
$$

and the displacements and stresses are given by

$$
\begin{align*}
& 2 u u_{r}=-\frac{\partial^{2} z}{\partial z^{2}}, 2 \mu u_{z}=\left[2(1-v) \nabla^{2}-\frac{\partial^{2}}{\partial z^{2}}\right] z ;  \tag{17}\\
& \sigma_{r r}=\frac{\partial}{\partial z}\left(\nu \nabla^{2}-\frac{\partial^{2}}{\partial r^{2}}\right) z, \sigma_{\theta \theta}=\frac{\rho}{\partial z}\left(\nu \nabla^{2}-\frac{1}{r} \frac{\partial}{\partial r}\right) z, \\
& \sigma_{z z}=\frac{\partial}{\partial z}\left[(2-v) \nabla^{2}-\frac{\partial^{2}}{\partial z^{2}}\right] z, \sigma_{r z}=\frac{\partial}{\partial r}\left[(1-v) \nabla^{2}-\frac{\partial^{2}}{\partial z^{2}}\right] z . \tag{18}
\end{align*}
$$

Looking for a series type solution in $z$ and taking into account the regularity conditions (15), the solution of (16) may be expressed as

$$
\begin{align*}
Z_{1} & =\sum_{n=1}^{\infty}\left[A_{1 n} K_{0}\left(\alpha_{n} r\right)+A_{3 n} \alpha_{n} r K_{1}\left(\alpha_{n} r\right)+A_{5 n} z \alpha_{n} K_{0}\left(\alpha_{n} r\right)\right] \sin \alpha_{n} z \\
& +\sum_{n=1}^{\infty}\left[B_{1 n} K_{0}\left(\alpha_{n} r\right)+B_{3 n} \alpha_{n} r K_{1}\left(\alpha_{n} r\right)+B_{5 n} z \alpha_{n} K_{0}\left(\alpha_{n} r\right)\right] \cos \alpha_{n} z,  \tag{19}\\
Z_{2} & =\sum_{n=1}^{\infty}\left[C_{1 n} K_{0}\left(\alpha_{n} r\right)+C_{3 n} \alpha_{n} r K_{1}\left(\alpha_{n} r\right)+C_{5 n} z \alpha_{n} K_{0}\left(\alpha_{n} r\right)\right] \sin \alpha_{n} z \\
& +\sum_{n=1}^{\infty}\left[D_{1 n} K_{0}\left(\alpha_{n} r\right)+D_{3 n} \alpha_{n} r K_{1}\left(\alpha_{n} r\right)+D_{5 n} z \alpha_{n} K_{0}\left(\alpha_{n} r\right)\right] \cos \alpha_{n} z . \tag{20}
\end{align*}
$$

Substituting from (17)-(20) into the boundary and continuity conditions (11)-(14) and observing that these conditions must be satisfied for all values of $r$ in $a<r<\infty$, after some manipulations, it may be shown that part of the resulting algebraic system which coniains only the unknowns $A_{3 n}, B_{3 n}, C_{3 n}$, and $D_{3 n}$ is separated and is overdetermined. Hence for the conditions (11)-(14) to be satisfied it is necessary that

$$
\begin{equation*}
A_{3 n}=B_{3 n}=C_{3 n}=D_{3 n}=0 \tag{21}
\end{equation*}
$$

Considering (21) from (17)-(20) the displacements and stresses in the composite plate may now be expressed as follows:

$$
\begin{align*}
& u_{r 1}=\frac{1}{2 \mu_{1}}\left\{\sum_{n=1}^{\infty} \alpha_{n}^{2} k_{1}\left(\alpha_{n} r\right)\left[A_{1 n}+A_{5 n} 2 \alpha_{n}+B_{5 n}\right] \cos \alpha_{n} 2\right. \\
& \left.-\sum_{n=1}^{\infty} \alpha_{n}^{2} K_{1}\left(\alpha_{n} r\right)\left[B_{1 n}+B_{5 n} 2 \alpha_{n}-A_{5 n}\right] \sin a_{n} 2\right\} \text {, }  \tag{22}\\
& u_{21}=\frac{1}{2 \mu_{1}}\left\{\sum _ { n = 1 } ^ { \infty } a _ { n } ^ { 2 } \operatorname { s i n } \alpha _ { n } 2 K _ { 0 } ( \alpha _ { n } r ) \left[\left(-2+4 v_{1}\right) B_{5 n}+A_{1 n}\right.\right. \\
& \left.+A_{5 n} 2 \alpha_{n}\right]+\sum_{n=1}^{\infty} \alpha_{n}^{2} \cos \alpha_{n} 2 K_{0}\left(\alpha_{n} r\right)\left[\left(2-4 v_{p}\right) A_{5 n}\right. \\
& \left.\left.+B_{1 n}+B_{5 n} 2 \alpha_{n}\right]\right\},  \tag{23}\\
& \sigma_{r r 1}=\sum_{n=1}^{\infty} a_{n}^{3}\left[B_{1 n}\left[K_{0}\left(a_{n} r\right)+\frac{1}{a_{n} r} K_{1}\left(\alpha_{n} r\right)\right]\right. \\
& +B_{5 n} 2\left[\alpha_{n} K_{0}\left(\alpha_{n} r\right)+\frac{1}{r} K_{p}\left(\alpha_{n} r\right)\right] \\
& \left.-A_{5 n}\left[\frac{1}{\alpha_{n} r} K_{1}\left(\alpha_{n} r\right)+\left(1+2 \nu_{1}\right) K_{0}\left(\alpha_{n} r\right)\right]\right\} \sin \alpha_{n}{ }^{2} \\
& -\sum_{n=1}^{\infty} \alpha_{n}^{3}\left[A_{1 n}\left[K_{0}\left(\alpha_{n} r\right)+\frac{1}{\alpha_{n} r} K_{1}\left(\alpha_{n} r\right)\right]+A_{5 n} 2\left[\alpha_{n} K_{0}\left(\alpha_{n} r\right)\right.\right. \\
& \left.+\frac{1}{r} K_{1}\left(\alpha_{n} r\right)\right]+B_{5 n}\left[\left(1+2 v_{1}\right) K_{o}\left(\alpha_{n} r\right)\right. \\
& \left.\left.+\frac{1}{\alpha_{n} r} K_{1}\left(\alpha_{n} r\right)\right]\right\} \cos \alpha_{n} z \quad,  \tag{24}\\
& \sigma_{\theta \theta 1}=-\sum_{n=1}^{\infty} \alpha_{n}^{2} \sin \alpha_{n} z\left\{\frac{K_{1}\left(\alpha_{n} r\right)}{r}\left[B_{1 n}+B_{5 n} z \alpha_{n}-A_{5 n}\right]\right. \\
& \left.+2 v_{1} \alpha_{n} A_{5 n} K_{0}\left(\alpha_{n} r\right)\right\}+\sum_{n=1}^{\infty} \alpha_{n}^{2} \cos \alpha_{n} z\left\{\frac { K _ { 1 } ( \alpha _ { n } r ) } { r } \left[A_{1 n}\right.\right. \\
& \left.\left.+A_{5 n} 2 \alpha_{n}+B_{5 n}\right]-2 v_{1} \alpha_{n} B_{5 n} K_{0}\left(\alpha_{n} r\right)\right\},  \tag{25}\\
& \sigma_{z z 1}=-\sum_{n=1}^{\infty} a_{n}^{3} K_{0}\left(a_{n} r\right)\left[B_{1 n}+B_{5 n} 2 a_{n}+\left(1-2 v_{1}\right) A_{5 n}\right] \sin \alpha_{n} 2
\end{align*}
$$

$$
\begin{align*}
& +\sum_{n=1}^{\infty} \alpha_{n}^{3} K_{0}\left(\alpha_{n} r\right)\left[A_{1 n}+A_{5 n} z \alpha_{n}+\left(2 v_{1}-1\right) B_{5 n}\right] \cos \alpha_{n} z \quad,  \tag{26}\\
& \sigma_{r 21}=-\sum_{n=1}^{\infty} \alpha_{n}^{3} K_{1}\left(\alpha_{n} r\right) \sin \alpha_{n} z\left[2 v_{1} B_{5 n}+A_{1 n}+A_{5 n} Z \alpha_{n}\right] \\
& -\sum_{n=1}^{\infty} \alpha_{n}^{3} K_{1}\left(\alpha_{n} r\right) \cos \alpha_{n} z\left[-2 v_{1} A_{5 n}+B_{1 n}+B_{5 n} 2 \alpha_{n}\right] \text {, }  \tag{27}\\
& u_{r 2}=\frac{1}{2 \mu_{2}}\left\{\sum_{n=1}^{\infty} a_{n}^{2} k_{1}\left(\alpha_{n} r\right)\left[c_{1 n}+c_{5 n} 2 a_{n}+D_{5 n}\right] \cos a_{n} 2\right. \\
& \left.-\sum_{n=1}^{\infty} \alpha_{n}^{2} k_{1}\left(\alpha_{n} r\right)\left[D_{1 n}+D_{5 n} z \alpha_{n}-C_{5 n}\right] \sin \alpha_{n} z\right\},  \tag{28}\\
& u_{z 2}=\frac{1}{2 \mu_{2}}\left\{\sum _ { n = 1 } ^ { \infty } \alpha _ { n } ^ { 2 } \operatorname { s i n } \alpha _ { n } z K _ { 0 } ( \alpha _ { n } r ) \left[\left(-2+4 \nu_{2}\right) D_{5 n}\right.\right. \\
& \left.+c_{1 n}+C_{5 n} 2 \alpha_{n}\right]+\sum_{n=1}^{\infty} \alpha_{n}^{2} \cos \alpha_{n} 2 K_{0}\left(\alpha_{n} r\right)\left[\left(2-4 v_{2}\right) c_{5 n}\right. \\
& \left.\left.+D_{1 n}+D_{5 n} Z \alpha_{n}\right]\right\},  \tag{29}\\
& \sigma_{r r 2}=\sum_{n=1}^{\infty} \alpha_{n}^{3}\left[D_{1 n}\left[K_{0}\left(\alpha_{n} r\right)+\frac{1}{\alpha_{n} r} K_{1}\left(\alpha_{n} r\right)\right]\right. \\
& +C_{5 n} z\left[\alpha_{n} K_{0}\left(\alpha_{n} r\right)+\frac{1}{r} K_{1}\left(\alpha_{n} r\right)\right] \\
& -C_{5 n}\left[\frac{1}{\alpha_{n} r} k_{1}\left(\alpha_{n} r\right)+\left(1+2 v_{2}\right) K_{0}\left(\alpha_{n} r\right)\right] f \sin \alpha_{n} z \\
& -\sum_{n=1}^{\infty} \alpha_{n}^{3}\left\{c_{1 n}\left[K_{0}\left(a_{n} r\right)+\frac{1}{a_{n} r} K_{1}\left(a_{n} r\right)\right]+c_{5 n} z\left[a_{n} K_{0}\left(\alpha_{n} r\right)\right.\right. \\
& \left.\left.+\frac{1}{r} K_{1}\left(\alpha_{n} r\right)\right]+D_{5 n}\left[\left(1+2 v_{2}\right) K_{0}\left(\alpha_{n} r\right)+\frac{1}{\alpha_{n} r} K_{1}\left(\alpha_{n} r\right)\right]\right\} \cos \alpha_{n} 2,  \tag{30}\\
& \sigma_{\theta \theta 2}=-\sum_{n=1}^{\infty} \alpha_{n}^{2} \sin \alpha_{n} z\left(\frac { k _ { 1 } ( a _ { n } r ) } { r } \left[D_{1 n}+D_{5 n} 2 \alpha_{n}\right.\right.
\end{align*}
$$

$$
\begin{align*}
& \left.\left.-C_{5 n}\right]+2 v_{2} \alpha_{n} c_{5 n} K_{0}\left(\alpha_{n} r\right)\right\}+\sum_{n=1}^{\infty} \alpha_{n}^{2} \cos \alpha_{n} z\{ \\
& \left.\frac{K_{1}\left(\alpha_{n} r\right)}{r}\left[C_{1 n}+C_{5 n} 2 a_{n}+D_{5 n}\right]-2 v_{2} a_{n} D_{5 n} K_{0}\left(a_{n} r\right)\right\},  \tag{31}\\
& \sigma_{222}=-\sum_{n=1}^{\infty} a_{n}^{3} K_{0}\left(\alpha_{n} r\right)\left[0_{1 n}+o_{5 n} 2 a_{n}+\left(1-2 v_{2}\right) c_{5 n}\right] \sin \alpha_{n}{ }^{2} \\
& +\sum_{n=1}^{\infty} a_{n}^{3} k_{0}\left(a_{n} r\right)\left[C_{1 n}+C_{5 n} 2 a_{n}+\left(2 v_{2}-1\right) D_{5 n}\right] \cos \alpha_{n} z,  \tag{32}\\
& z_{r z 2}=-\sum_{n=1}^{\infty} \alpha_{n}^{3} K_{1}\left(a_{n} r\right) \sin \alpha_{n} z\left[2 v_{2} D_{5 n}+C_{1 n}+C_{5 n} z \alpha_{n}\right] \\
& -\sum_{n=1}^{\infty} \alpha_{n}^{3} K_{1}\left(\alpha_{n} r\right) \cos \alpha_{n} z\left[-2 v_{2} C_{5 n}+D_{1 n}+D_{5 n} z \alpha_{n}\right] . \tag{33}
\end{align*}
$$

Substituting from (22)-(33) into the bcundary and continuity conditions (11)-(14) we obtain the following system of homogeneous algebraic equations:

$$
\begin{align*}
& -A_{1 n} \sin \alpha_{n} h_{1}+\left[2 v_{1} \cos \alpha_{n} h_{1}-\alpha_{n} h_{1} \sin \alpha_{n} h_{1}\right] A_{5 n} \\
& -B_{1 n} \cos \alpha_{n} h_{1}-\left[2 v_{1} \sin \alpha_{n} h_{1}+\alpha_{n} h_{1} \cos \alpha_{n} h_{1}\right] B_{5 n}=0,  \tag{34}\\
& A_{1 n} \cos \alpha_{n} h_{1}+\left[\left(2 v_{1}-1\right) \sin \alpha_{n} h_{1}+a_{n} h_{1} \cos \alpha_{n} h_{1}\right] A_{5 n}-B_{1 n} \sin \alpha_{n} h_{1} \\
& +\left[\left(2 v_{1}-1\right) \cos \alpha_{n} h_{1}-a_{n} h_{1} \sin \alpha_{n} h_{1}\right] B_{5 n}=0,  \tag{35}\\
& C_{1 n} \sin \alpha_{n} h_{2}+\left[2 v_{2} \cos \alpha_{n} h_{2}-a_{n} h_{2} \sin \alpha_{n} h_{2}\right] c_{5 n} \\
& -D_{1 n} \cos \alpha_{n} h_{2}+\left[2 v_{2} \sin \alpha_{n} h_{2}+\alpha_{n} h_{2} \cos \alpha_{n} h_{2}\right] D_{5 n}=0,  \tag{36}\\
& C_{i n} \cos \alpha_{n} h_{2}+0\left[\left(1-2 v_{2}\right) \sin \alpha_{n} h_{2}-\alpha_{n} h_{2} \cos \alpha_{n} h_{2}\right] C_{5 n}
\end{align*}
$$

$$
\begin{align*}
& +D_{1 n} \sin a_{n} h_{2}+\left[\left(2 v_{2}-1\right) \cos \alpha_{n} h_{2}-a_{n} h_{2} \sin \alpha_{n} h_{2}\right] D_{5 n}=0,  \tag{37}\\
& -2 v_{1} A_{5 n}+B_{1 n}+2 v_{2} C_{5 n}-D_{1 n}=0,  \tag{38}\\
& A_{1 n}+\left(2 v_{1}-1\right) B_{5 n}-C_{1 n}-\left(2 v_{2}-1\right) D_{5 n}=0,  \tag{39}\\
& B A_{1 n}+B B_{5 n}-C_{1 n}-D_{5 n}=0,  \tag{a0}\\
& B\left(2-4 v_{1}\right) A_{5 n}+B B_{1 n}-\left(2-4 v_{2}\right) C_{5 n}-D_{1 n}=0, \tag{41}
\end{align*}
$$

where

$$
\begin{equation*}
B=\mu_{2} / \mu_{1} . \tag{42}
\end{equation*}
$$

To obtain a non-trivial solution for the system of algebraic equations (34)-(42), the determinant of coefficients must vanish, giving

$$
\begin{equation*}
\Delta\left(a_{n}\right)=0 \tag{43}
\end{equation*}
$$

The characteristic equation (43) gives the eigenvalues $\alpha_{n},(n=1,2, \ldots)$ of the problem. A close examination of the roots of (43) shows that if $a_{n}$ is a root so are $-\alpha_{n}, \bar{a}_{n}$, and $-\bar{a}_{n}$. Therefore in solving the problem it is sufficient to use the roots in the first quadrant and consider the real part of the solution only. Further examination of the roots indicates that for dissimilar materials generally there is only one positive real root and the remaining roots are all complex. Furthermore, the complex roots form two distinct sequences in the first quadrant which greatly facilitates their numerical evaluation. When the elastic constants of the layers 1 and 2 become equal (i.e., for a homogeneous layer), the real root disappears and the two sequences of complex eigenvalues become the roots of the following characteristic equations:

$$
\begin{equation*}
\sin 2 \lambda_{n}+2 \lambda_{n}=0, \sin 2 \lambda_{n}-2 \lambda_{n}=0, \lambda_{n}=a_{n}\left(h_{1}+h_{2}\right) \text {. } \tag{44a,b}
\end{equation*}
$$

Equations (44) are known to correspond to the extension and bending problems for a homogeneous thick plate containing a circular hole $[8,9]$.

It is found that $\alpha_{0}=0$ is also a root of (43). Therefore, a particular solution must be added to that given by (19) and (20) to account for the zero eigenvalue. Considered as sili,jle "plates" the layers are subjected to stretching, bending, and transverse shear. The particular solutions $Z_{1}^{0}$, and $Z_{2}^{0}$ must therefore exhibit the characteristics of all three modes of loading. Thus

$$
\begin{align*}
& z_{1}^{0}=N_{1} z \ell n r+M_{1} z^{2} \ell n r+P_{1} r^{2} \ell r+Q_{1}\left(z^{2}-r^{2} / 2\right), \\
& z_{2}^{0}=N_{2} z \ell n r+M_{2} z^{2} \ell n r+P_{2} r^{2} \ell n r . \tag{45a,b}
\end{align*}
$$

where the first terms in each expression correspond to stretching, and the next two terms to combined bending and transverse shear in the individual plates. * The term $Q_{1}\left(z^{2}-r^{2} / 2\right)$ corresponds to a rigid body translation in $z$-direction and is added to (45a) to insure continuity of displacements at the interface. The constants $M_{1}, N_{1}, P_{1}, M_{2}, N_{2}$, and $P_{2}$ which appear in (45) are not independent. By using expressions (17) and (18) which relate the displacements and the stresses to the Love strain function, all field quantities can be written in terms of these constants. Then, by applying the boundary and continuity conditions (11)-(14), after some lengthy algebra and after redefining the constants we obtain:

$$
\begin{align*}
& z_{1}^{0}=D_{0} z \ell n r+A_{0} z^{2} \ell n r+\frac{v_{1}}{2\left(1-v_{1}\right)} A_{0} r^{2} \ell n r+Q_{1}\left(z^{2}-r^{2} / 2\right) \\
& Z_{2}^{0}=B D_{0} z \ell n r+B A_{0} z^{2} \ell n r+B \frac{v_{2}}{2\left(1-v_{2}\right)} A_{0} r^{2} \ell n r \tag{46a,b}
\end{align*}
$$

[^1]The stress field generated by (46) can then be expressed as:

$$
\begin{align*}
& \sigma_{r r 1}^{0}=\frac{1}{r^{2}}\left(D_{0}+2 A_{0} z\right), \sigma_{\theta \theta 1}^{0}=-\frac{1}{r^{2}}\left(D_{0}+2 A_{0} z\right), \\
& \sigma_{z z 1}^{0}=0, \sigma_{r z 1}^{0}=0,  \tag{47a-d}\\
& \sigma_{r r 2}^{0}=\frac{\beta}{r^{2}}\left(D_{0}+2 A_{0} z\right), \sigma_{\theta \theta 2}^{0}=-\frac{\beta}{r^{2}}\left(D_{0}+2 A_{0} z\right), \\
& \sigma_{z z 2}^{0}=0, \sigma_{r z 2}^{0}=0 .
\end{align*}
$$

(48a-d)

In the perturbation problem the stress states in layers 1 and 2 are obtained by adding the respective stress components given by (24)-(27), (30)-(33), (47) and (48). Thus, the problem is reduced to one of determining the unknown constants $A_{0}, D_{0}, A_{1 n}, A_{5 n}, B_{1 n}, B_{5 n}, C_{1 n}, C_{5 n}, D_{1 n}$, and $D_{5 n},(n=1,2, \ldots)$. However, from (34)-(42) it is clear that the homogeneous system contains only one arbitrary constant for each eigenvalue $\alpha_{n},(n=1,2, \ldots)$. For example, one may assume that $A_{1 n},(n=1,2 \ldots)$ is the only unknown in (34)-(42) and the remaining seven unknowns $A_{5 n}, \ldots, D_{5 n}$ may be expressed in terms of $A_{1 n}$ after solving the related eigenvalue problem. The unknown constants $A_{0}, D_{0}$, and $A_{1 n},(n=1,2, \ldots)$ are then determined from the boundary conditions (10). To do this, we first substitute from the expressions (24), (47a), (30), (48a) and (27), (47d), (33), (48d) into (10a) and (10b), respectively. In the resulting equations by expanding both sides into a series of an appropriate system of orthogonal functions in $-h_{2}<z<h_{1}$ and by matching the coefficients we obtain a linear system of algebraic equations to determine the unknown coefficients $A_{0}, D_{0}$, and $A_{1 n}$. Tine algebraic system is infinite and may be solved by the method of reduction.

If we use the first $N+1$ functions of a real orthogonal system, the (real parts of) conditions (10) would give $2 N+2$ equations. On the other hand, since $A_{0}, D_{0}, A_{11}$ (corresponding to the real eigenvalue $\alpha_{1}$ ) are real and $A_{12}, A_{13}, \ldots$ are complex, truncating the series (24), (27), (30)
and (33) at the Nth term we would have $2 N+1$ real unknowns. However, it can be shown that this discrepancy disappears if one selects an orthogonal system in which the first function is a constant. Thus, if we substitute from (27), (47d), (33), and (48d) into

$$
\begin{equation*}
\int_{-h_{2}}^{h_{1}} \sigma_{r z} d z=\int_{-h_{2}}^{0} \sigma_{r z 2} d z+\int_{0}^{h_{1}} \sigma_{r z 1} d z \tag{49}
\end{equation*}
$$

corresponding to the coefficient of the first coordinate function in expanding the lefthand side of (10b), it can be shown that the expression becomes identically zero. On the other hand, the static equilibrium of the composite plate requires that

$$
\begin{equation*}
\int_{-h_{2}}^{0} \tau_{2} d z+\int_{0}^{h_{1}} \tau_{1} d z=0 \tag{50}
\end{equation*}
$$

Thus, the first equation obtained from the series expansion of (10b) becomes an identity, $0=0$, and may therefore be ignored.

Now let us assume that the tractions are

$$
\begin{equation*}
\sigma_{1}(z)=-\sigma_{1}, \quad \sigma_{2}(z)=-\sigma_{2}, \quad \tau_{1}(z)=0, \quad \tau_{2}(z)=0, \tag{51}
\end{equation*}
$$

where $\sigma_{1}$ and $\sigma_{2}$ are constant, and $\cos \left[\pi k\left(2+h_{2}\right) /\left(h_{1}+h_{2}\right)\right],(k=0,1,2, \ldots)$ is selected as the orthogonal system. By expanding (10) into cosine series and considering the first $N+1$ terms we then obtain

$$
\begin{align*}
& \operatorname{Re} \sum_{n=1}^{N} a_{n}^{3} k_{1}\left(a_{n} a\right)\left\{\left(2 v_{2} D_{5 n}+C_{1 n}\right) a_{n k}+a_{n} C_{5 n} b_{n k}\right. \\
& +\left(-2 v_{2} C_{5 n}+D_{1 n}\right) c_{n k}+a_{n} D_{5 n} d_{n k}+\left(2 v_{1} B_{5 n}+A_{1 n}\right) e_{n k} \\
& \left.+a_{n} A_{5 n} f_{n k}+\left(-2 v_{1} A_{5 n}+B_{1 n}\right) g_{n k}+a_{n} B_{5 n} h_{n k}\right\}=0, \\
& (k=1, \ldots, N), \tag{52}
\end{align*}
$$

$$
\begin{align*}
& \operatorname{Re} \sum_{n=1}^{N} a_{n}^{3} t\left(x_{n} O_{1 n}-Y_{n} c_{5 n}\right) a_{n k}+D_{5 n} a_{n} X_{n} b_{n k} \\
& -\left(X_{n} C_{1 n}+Y_{n} D_{5 n}\right) c_{n k}-a_{n} C_{5 n} X_{n} d_{n k} \\
& +\left(X_{n} B_{1 n}-Z_{n} A_{5 n}\right) e_{n k}+\alpha_{n} B_{5 n} X_{n} f_{n k} \\
& \left.-\left(x_{n} A_{1 n}+Z_{n} B_{5 n}\right) g_{n k}-a_{n} A_{5 n} x_{n} h_{n k}\right\} \\
& +\frac{D_{0}}{a^{2}}\left(m_{k}+\beta n_{k}\right)+2 \frac{A_{0}}{a^{2} \gamma_{k}^{2}}\left[(-1)^{k}-\cos \gamma_{k} h_{2}+\beta\left(\cos \gamma_{k} h_{2}-1\right)\right] \\
& =-\sigma_{1} m_{k}-\sigma_{2} n_{k}, \quad(k=1, \ldots, N),  \tag{53}\\
& \operatorname{Re} \sum_{n=1}^{N} a_{n}^{3} f\left(x_{n} D_{1 n}-Y_{n} c_{5 n}\right) a_{n 0}+D_{5 n} a_{n} X_{n} b_{n 0} \\
& -\left(x_{n} C_{1 n}+y_{n} D_{5 n}\right) c_{n o}-\alpha_{n} C_{5 n} x_{n} d_{n o} \\
& +\left(X_{n} B_{1 n}-Z_{n} A_{5 n}\right) e_{n 0}+\alpha_{n} B_{5 n} X_{n} f_{n o} \\
& \left.-\left(X_{n} A_{1 n}+Z_{n} B_{5 n}\right) g_{n 0}-a_{n} A_{5 n} X_{n} h_{n o}\right\} \\
& +\frac{D_{0}}{a^{2}}\left(h_{1}+\beta h_{2}\right)+\frac{A_{0}}{a^{2}}\left(h_{1}^{2}-\beta h_{2}^{2}\right)=-\sigma_{1} h_{1}-\sigma_{2} h_{2}, \tag{54}
\end{align*}
$$

where

$$
\begin{aligned}
& x_{n}=k_{0}\left(\alpha_{n} a\right)+\frac{1}{\alpha_{n} a} k_{1}\left(\alpha_{n} a\right), \\
& Y_{n}=\left(1+2 v_{2}\right) K_{0}\left(a_{n} a\right)+\frac{1}{a_{n}{ }^{a}} k_{1}\left(\alpha_{n} a\right), \\
& z_{n}=\left(1+2 v_{1}\right) k_{0}\left(\alpha_{n} a\right)+\frac{1}{a_{n}{ }^{a}} k_{1}\left(\alpha_{n} a\right),(n=1,2 \ldots, N), \\
& m_{k}=-\frac{\sin \gamma_{k} h_{2}}{r_{k}}, n_{k}=-m_{k}, \quad r_{k}=\frac{k \pi}{h_{1}+h_{2}}, \quad(k=1,2 \ldots, N),
\end{aligned}
$$

$$
\begin{aligned}
& a_{n k}=\frac{1}{2} \frac{\cos \gamma_{k} h_{2}}{\gamma_{k}+a_{n}}\left[\cos \left(\gamma_{k}+a_{n}\right) h_{2}-1\right] \\
& +\frac{1}{2} \frac{\sin \gamma_{k} h_{2}}{\gamma_{k}+\alpha_{n}} \sin \left(\gamma_{k}+\alpha_{n}\right) h_{2}-\frac{1}{2} \frac{\cos \gamma_{k} h_{2}}{\gamma_{k}-\alpha_{n}}\left[\cos \left(\gamma_{k}-\alpha_{n}\right) h_{2}-1\right] \\
& -\frac{1}{2} \frac{\sin \gamma_{k} h_{2}}{\gamma_{k}-a_{n}} \sin \left(\gamma_{k}-a_{n}\right) h_{2},(n=1, \ldots, N ; k=1, \ldots, N) \text {, } \\
& b_{n k}=-\frac{1}{2} \frac{\cos \gamma_{k} h_{2}}{\gamma_{k}+\alpha_{n}} h_{2} \cos \left(\gamma_{k}+\alpha_{n}\right) h_{2}+\frac{1}{2} \frac{\cos \gamma_{k} h_{2}}{\left(\gamma_{k}+\alpha_{n}\right)^{2}} \sin \left(\gamma_{k}+\alpha_{n}\right) h_{2} \\
& -\frac{1}{2} \frac{\operatorname{sin\gamma _{k}h_{2}}}{r_{k}+\alpha_{n}} h_{2} \sin \left(r_{k}+\alpha_{n}\right) h_{2} \\
& +\frac{1}{2} \frac{\sin \gamma_{k} h_{2}}{\left(\gamma_{k}+\alpha_{n}\right)^{2}}\left[1-\cos \left(\gamma_{k}+\alpha_{n}\right) h_{2}\right]+\frac{1}{2} \frac{\cos \gamma_{k} h_{2}}{\gamma_{k}-\alpha_{n}} h_{2} \cos \left(\gamma_{k}-\alpha_{n}\right) h_{2} \\
& -\frac{1}{2} \frac{\cos \gamma_{k} h_{2}}{\left(\gamma_{k}-\alpha_{n}\right)^{2}} \sin \left(\gamma_{k}-\alpha_{n}\right) h_{2}+\frac{1}{2} \frac{\sin \gamma_{k} h_{2}}{\gamma_{k}-\alpha_{n}} h_{2} \sin \left(\gamma_{k}-\alpha_{n}\right) h_{2} \\
& -\frac{1}{2} \frac{\sin \gamma_{k} h_{2}}{\left(\gamma_{k}-\alpha_{n}\right)^{2}}\left[1-\cos \left(\gamma_{k}-\alpha_{n}\right) h_{2}\right], \quad(n=1, \ldots, N ; k=1, \ldots, N) \text {, } \\
& c_{n k}=\frac{1}{2} \frac{\cos \gamma_{k} h_{2}}{r_{k}+\alpha_{n}} \sin \left(\gamma_{k}+\alpha_{n}\right) h_{2}+\frac{1}{2} \frac{\sin \gamma_{k} h_{2}}{\gamma_{k}+\alpha_{n}}\left[1-\cos \left(\gamma_{k}+\alpha_{n}\right) h_{2}\right] \\
& +\frac{1}{2} \frac{\cos \gamma_{k} h_{2}}{\gamma_{k}-\alpha_{n}} \sin \left(\gamma_{k}-\alpha_{n}\right) h_{2}+\frac{1}{2} \frac{\sin \gamma_{k} h_{2}}{\gamma_{k}-\alpha_{n}}\left[1-\cos \left(\gamma_{k}-\alpha_{n}\right) h_{2}\right] \text {, } \\
& (n=1, \ldots, N ; k=1, \ldots, N) \quad \text {, } \\
& d_{n k}=-\frac{1}{2} \frac{\cos \gamma_{k} h_{2}}{r_{k}+\alpha_{n}} h_{2} \sin \left(\gamma_{k}+\alpha_{n}\right) h_{2}+\frac{1}{2} \frac{\cos \gamma_{k} h_{2}}{\left(r_{k}+\alpha_{n} k^{k}\right.}\left[1-\cos \left(\gamma_{k}+\alpha_{n}\right) h_{2}\right] \\
& +\frac{1}{2} \frac{\sin \gamma_{k} h_{2}}{\gamma_{k}+\alpha_{n}} h_{2} \cos \left(\gamma_{k}+\alpha_{n}\right) h_{2}-\frac{1}{2} \frac{\sin \gamma_{k} h_{2}}{\left(\gamma_{k}+\alpha_{n}\right)^{2}} \sin \left(\gamma_{k}+\alpha_{n}\right) h_{2} \\
& -\frac{1}{2} \frac{\cos \gamma_{k} h_{2}}{\gamma_{k}-\alpha_{n}} h_{2} \sin \left(\gamma_{k}-\alpha_{n}\right) h_{2}+\frac{1}{2} \frac{\cos \gamma_{k} h_{2}}{\left(\gamma_{k}-\alpha_{n}{ }^{2}\right.}\left[1-\cos \left(\gamma_{k}-\alpha_{n}\right) h_{2}\right]
\end{aligned}
$$

$$
\begin{aligned}
& +\frac{1}{2} \frac{\sin \gamma_{k} h_{2}}{r_{k}-\alpha_{n}} h_{2} \cos \left(\gamma_{k}-\alpha_{n}\right) h_{2}-\frac{1}{2} \frac{\sin \gamma_{k} h_{2}}{\left(\gamma_{k}-a_{n} n^{2}\right.} \sin \left(\gamma_{k}-a_{n}\right) h_{2} \text {, } \\
& (n=1, \ldots, N ; k=1, \ldots, N) \text {, } \\
& e_{n k}=-\frac{1}{2} \frac{\cos \gamma_{k} h_{2}}{\gamma_{k}+\alpha_{n}}\left[\cos \left(\gamma_{k}+\alpha_{n}\right) h_{1}-1\right]+\frac{1}{2} \frac{\sin \gamma_{k} h_{2}}{\gamma_{k}+\alpha_{n}} \sin \left(\gamma_{k}+\alpha_{n}\right) h_{1} \\
& +\frac{1}{2} \frac{\cos \gamma_{k} h_{2}}{\gamma_{k}-\alpha_{n}}\left[\cos \left(\gamma_{k}-\alpha_{n}\right) h_{1}-1\right]-\frac{1}{2} \frac{\sin \gamma_{k} h_{2}}{\gamma_{k}-a_{n}} \sin \left(\gamma_{k}-\alpha_{n}\right) h_{1} \text {, } \\
& (k=1,2, \ldots, N ; n=1, \ldots, N)] \text {, } \\
& f_{n k}=-\frac{1}{2} \frac{\cos \gamma_{k} h_{2}}{\gamma_{k}+\alpha_{n}} h_{1} \cos \left(\gamma_{k}+a_{n}\right) h_{1}+\frac{1}{2} \frac{\cos \gamma_{k} h_{2}}{\left(\gamma_{k}+\alpha_{n}\right)^{2}} \sin \left(\gamma_{k}+a_{n}\right) h_{1} \\
& +\frac{1}{2} \frac{\sin \gamma_{k} h_{2}}{\gamma_{k}+\alpha_{n}} n_{1} \sin \left(\gamma_{k}+\alpha_{n}\right) n_{1}+\frac{1}{2} \frac{\sin \gamma_{k} h_{2}}{\left(\gamma_{k}+\alpha_{n}\right)^{2}}\left[\cos \left(\gamma_{k}+\alpha_{n}\right) n_{1}-1\right] \\
& +\frac{1}{2} \frac{\cos \gamma_{k} h_{2}}{\gamma_{k}-\alpha_{n}} n_{1} \cos \left(\gamma_{k}-\alpha_{n}\right) h_{1}-\frac{1}{2} \frac{\cos \gamma_{k} h_{2}}{\left(\gamma_{k}-\alpha_{n}\right)^{2}} \sin \left(\gamma_{k}-\alpha_{n}\right) h_{1} \\
& -\frac{1}{2} \frac{\cos \gamma_{k} h_{2}}{\gamma_{k}-a_{n}} h_{1} \sin \left(\gamma_{k}-\alpha_{n}\right) h_{1}-\frac{1}{2} \frac{\sin \gamma_{k} h_{2}}{\left(\gamma_{k}-\alpha_{n}\right)^{2}}\left[\cos \left(\gamma_{k}-\alpha_{1}\right) h_{1}-1\right] \text {, } \\
& (n=1, \ldots N ; k=1, \ldots, N) \text {, } \\
& g_{n k}=\frac{1}{2} \frac{\cos \gamma_{k} h_{2}}{\gamma_{k}+\alpha_{n}} \sin \left(\gamma_{k}+\alpha_{n}\right) h_{1}+\frac{1}{2} \frac{\sin \gamma_{k} h_{2}}{r_{k} \alpha_{n}}\left[\cos \left(\gamma_{k}+\alpha_{n}\right) h_{1}-1\right] \\
& +\frac{1}{2} \frac{\cos \gamma_{k} h_{2}}{r_{k}-\alpha_{n}} \sin \left(r_{k}-\alpha_{n}\right) h_{1}+\frac{1}{2} \frac{\sin \gamma_{k} h_{2}}{r_{k}-\alpha_{n}}\left[\cos \left(r_{k}-\alpha_{n}\right) h_{1}-1\right] \text {, } \\
& (n=1, \ldots, N ; k=1, \ldots, N) \text {, } \\
& h_{n k}=\frac{1}{2} \frac{\cos \gamma_{k} h_{2}}{\gamma_{k}+\alpha_{n}} n_{1} \sin \left(\gamma_{k}+a_{n}\right) h_{1}+\frac{1}{2} \frac{\cos \gamma_{k} h_{2}}{\left(\gamma_{k}+\alpha_{n}\right)^{2}}\left[\cos \left(\gamma_{k}+\alpha_{n}\right) h_{1}-1\right] \\
& +\frac{1}{2} \frac{\sin \gamma_{k} h_{2}}{\gamma_{k}+a_{n}} h_{1} \cos \left(\gamma_{k}+a_{n}\right) h_{1}-\frac{1}{2} \frac{\sin \gamma_{k} h_{2}}{\left(\gamma_{k}+\alpha_{n}\right)^{2}} \sin \left(\gamma_{k}+a_{n}\right) h_{1}
\end{aligned}
$$

$$
\begin{align*}
& +\frac{1}{2} \frac{\cos \gamma_{k} h_{2}}{\gamma_{k}-a_{n}} h_{1} \sin \left(\gamma_{k}-a_{n}\right) h_{1}+\frac{1}{2} \frac{\cos \gamma_{k} h_{2}}{\left(\gamma_{k}-\alpha_{n}\right)^{2}}\left[\cos \left(\gamma_{k}-a_{n}\right) h_{j}-1\right] \\
& +\frac{1}{2} \frac{\sin \gamma_{k} h_{2}}{\gamma_{k}-\alpha_{n}} h_{1} \cos \left(\gamma_{k}-\alpha_{n}\right) h_{1}-\frac{1}{2} \frac{\sin \gamma_{k} h_{2}}{\left(\gamma_{k}-\alpha_{n}\right)^{2}} \sin \left(\gamma_{k}-\alpha_{n}\right) h_{1} \quad \text {, } \\
& (n=1, \ldots, N ; k=1, \ldots, N) ; \\
& a_{n o}=\frac{\cos a_{n} h_{2}-1}{a_{n}} \\
& b_{n 0}=-\frac{h_{2} \cos \alpha_{n} h_{2}}{a_{n}}+\frac{\sin \alpha_{n} h_{2}}{a_{n}^{2}}, \\
& c_{n o}=\frac{\sin \alpha_{n} h_{2}}{a_{n}} \text {, } \\
& d_{n 0}=-\frac{h_{2} \sin \alpha_{n} h_{2}}{a_{n}}+\frac{\left(1-\cos \alpha_{n} h_{2}\right)}{a_{n}^{2}}, \\
& e_{n 0}=\frac{1-\cos a_{n} h_{1}}{a_{n}}, \\
& f_{n o}=-\frac{h_{1} \cos \alpha_{n} h_{1}}{\alpha_{n}}+\frac{\sin \alpha_{n} h_{1}}{\alpha_{n}^{2}}, \\
& g_{n o}=\frac{\sin \alpha_{n} h_{1}}{a_{n}}, \\
& h_{n 0}=\frac{h_{1} \sin a_{n} h_{1}}{a_{n}}-\frac{\left(1-\cos \alpha_{n} h_{1}\right)}{a_{n}^{2}},(n=1,2 \ldots, N) . \tag{55}
\end{align*}
$$

and $\beta$ is given by (42). Even though it is difficult to investigate the regularity of the algebraic system (52)-(54), the numerical results show very good convergence with increasing $N$.
4. NUMERICAL RESULTS AND DISCUSSION

In the numerical example considered the following material properties and dimensions are used (Figure 1)

$$
\begin{align*}
& \frac{E_{1}}{E_{2}}=2, v_{1}=0.3, v_{2}=0.35 \\
& \frac{a}{h_{1}}=3, \frac{a}{h_{2}}=1.5 . \tag{56}
\end{align*}
$$

The first 60 roots of the characteristic equation (43) obtained from the algebraic system (34)-(41) are given in Table 1.

Two separate loading conditions are used to calculate the stresses. In the first it is assumed that *

$$
\begin{align*}
& \sigma_{r r 1}(a, z)=-\sigma_{1}, \sigma_{r r 2}(a, z)=-\sigma_{2} \\
& \sigma_{1} / \sigma_{2}=1.964, \sigma_{r z 1}(a, z)=\sigma_{r z 2}(a, z)=0 . \tag{57}
\end{align*}
$$

The second loading consists of a uniform pressure on the entire hole surface, namely

$$
\begin{align*}
& \sigma_{r r 1}(a, z)=\sigma_{r r 2}(a, z)=-\sigma_{2}, \\
& \sigma_{r z 1}(a, z)=\sigma_{r z 2}(a, z)=0 . \tag{58}
\end{align*}
$$

Tables 2-5 show the calculated results which are partially displayed also in Figures 2-5. Based on the calculated results one could make the following observations:
(a) Away from the hole boundary generally the convergence is quite good. It becomes slower when the hole boundary is approached. For the loading given by (57) the discontinuity in traction $\sigma_{r r}$ may be partially responsible for this. However, the main reason for the lack of convergence of the calculated results near the hole boundary appears to be

[^2]the singular nature of the stress state at the intersection of the interface and the boundary [1-3]. Thus, near the hole boundary more terms in the infinite series were needed to obtain convergence comparable to that found in computing the stresses away from the boundary.*
(b) As $r+\infty$ all stress components go to zero. However, the decay in $\sigma_{\theta \theta j}$ is much slower than that in $\sigma_{z z j}$ and $\sigma_{r z j},(j=1,2)$.
(c) From Figures 3 and 5 it may be seen that the relative magnitidues of the interface stresses $\sigma_{r z}$ and $\sigma_{z z}$ are rather small. Also, the stresses corresponding to $\sigma_{1}=\sigma_{2}$ (Figure 5) are an order of magnitude greater than those obtained for $\sigma_{1}=1.964 \sigma_{2}$ (Figure 3). A partial explanation for these results may be found if one considers the homogeneous plates separately. In a homogeneous plate axisymmetrically loaded by $\sigma_{r r l}(a, z)=-\sigma_{1}, \sigma_{r z 1}(a, z)=0,\left(0<z<h_{1}\right)$ the stress state is given by
\[

$$
\begin{equation*}
\sigma_{r r 1}=-\frac{\sigma_{1}}{(r / a)^{2}}=-\sigma_{\theta \theta 1}, \quad \sigma_{r z 1}=0, \quad \sigma_{z z 1}=0 \text {, } \tag{59}
\end{equation*}
$$

\]

from which it follows that

$$
\begin{equation*}
\varepsilon_{\theta \theta 1}=\frac{1}{2 \mu_{1}} \frac{\sigma_{1}}{(r / a)^{2}}=-\varepsilon_{r r 1}, \varepsilon_{r z 1}=0, \varepsilon_{z z 1}=0 \text {. } \tag{60}
\end{equation*}
$$

Thus, it is seen that if the second plate is axisymmetrically loaded by $\sigma_{r r 2}(a, z)=-\sigma_{2}, \sigma_{r z 2}(a, z)=0,\left(-h_{2}<z<0\right)$ and if $\sigma_{1} / \mu_{1}=\sigma_{2} / \mu_{2}$, then in the two plates the displacements would be identical along the interface and the stresses $\sigma_{z z}$ and $\sigma_{r z}$ would be zero everywhere. In the example under consideration $\mu_{1} / \mu_{2}=2.077$. Therefore, for $\sigma_{1} / \sigma_{2}=1.964$ one would expect the magnitude of the interface stresses to be rather small. Similar observations may be made with regard to the comparison of $\sigma_{\theta \theta}$ and $\sigma_{r r}$ in bonded and unbonded plates. On the other hand, for $\sigma_{1}=\sigma_{2}$

[^3]one would expect higher interface stresses because of the greater mismatch in the displacements along the interface.
(d) For the loading $\sigma_{1} / \sigma_{2}=1.964$ since the solution is close to that of a homogeneous plate, the thickness effect should not be significant. Indeed, by varying $a / h$, it is observed that the results do not change significantly. Also, in this case from Table 3 it may be seen that the variation of $\sigma_{\theta \theta}$ with $z$ is negligible, whereas for $\sigma_{1} / \sigma_{2}=1$ Table 5 shows a significant variation in $\sigma_{\theta \theta}$. Again, note that in the homogeneous plate $\sigma_{\theta \theta}$ is independent of $z$.
(e) The calculated results indicate that on the interface $2=0$ the stresses become unbounded as $r$ approaches $a$, the hole radius. Theoretically, this is indeed known to be the case [1-3]. The solution given in this paper is in terms of infinite series, meaning that for $z=0$ and $r=a$ certain series should be divergent. In problems such as this one would have to determine the eigenvalues $n_{11}$ in closed form for large values of $n$ by examining the asymptotic behavior of the characteristic equation, determine the related eigenfunctions again in closed form, and try to separate and sum the divergent part of the infinite series. Such a procedure seems to be quite impossible for the problem under consideration. However, if one has a reasonably good solution for sufficiently small values of $r-a$, one may then follow an indirect method to establish the singular behavior of the stresses in an approximate manner. To do this we note that from the plane strain solution of two bonded elastic quarter planes one may express the asymptotic behavior of the stresses for $z=0$ and for small values of $r-a$ as follows [3]
\[

$$
\begin{equation*}
\sigma_{i j} \cong \frac{A_{i j}}{(r-a)^{\alpha}}+B_{i j}(r-a)^{1-\alpha}+\ldots, \quad(i, j=r, z) \tag{61}
\end{equation*}
$$

\]

where $a$ is the root of the characteristic equation in the strip $0<\operatorname{Re}(\alpha)<1$

$$
\begin{align*}
& \left(\cos \pi \alpha+c_{11}+\alpha c_{12}+c_{13^{\alpha}}(\alpha+1) / 2\right)\left(\cos \pi \alpha+c_{21}+c_{22^{\alpha}}\right. \\
& \left.+c_{23^{\alpha}}(\alpha+1) / 2\right)-\left(d_{11+d_{12}}\right)\left(d_{21}+d_{22^{\alpha}}\right)=0 \tag{62}
\end{align*}
$$

where

$$
\begin{aligned}
& c_{11}=\frac{1}{2}-\frac{m_{1}\left(1+k_{1}\right)}{2\left(m_{1}+k_{2}\right)}-\frac{3\left(1-m_{1}\right)}{2\left(1+m_{1} k_{1}\right)}, \\
& c_{12}=\frac{6\left(1-m_{1}\right)}{1+m_{1} k_{1}}, c_{13}=-\frac{4\left(1-m_{1}\right)}{1+m_{1} k_{1}}, \\
& c_{21}=\frac{1}{2}-\frac{m_{2}\left(1+k_{2}\right)}{2\left(m_{2}+k_{1}\right)}-\frac{3\left(1-m_{2}\right)}{2\left(1+m_{2} k_{2}\right)}, \\
& c_{22}=\frac{6\left(1-m_{2}\right)}{1+m_{2} k_{2}}, c_{23}=-\frac{4\left(1-m_{2}\right)}{1+m_{2} k_{2}}, \\
& d_{11}=\frac{3\left(1+k_{2}\right)}{2\left(m_{2}+k_{1}\right)}-\frac{1+k_{1}}{2\left(1+m_{2} k_{2}\right)}, d_{12}=\frac{1+k_{1}}{1+m_{2} k_{2}}-\frac{1+k_{1}}{m_{2}+k_{1}}, \\
& d_{21}=\frac{3\left(1+k_{2}\right)}{2\left(m_{1}+k_{2}\right)}-\frac{1+k_{2}}{2\left(1+m_{1} k_{1}\right)}, d_{22}=\frac{1+k_{2}}{1+m_{1} k_{1}}-\frac{1+k_{2}}{m_{1}+k_{2}}, \\
& m_{1}=\mu_{2} / \mu_{1} \quad m_{2}=\mu_{1} / \mu_{2}, k_{i}=3-4 v_{i},(i=1,2),
\end{aligned}
$$

For real material corninations it turns out that in $0<\operatorname{Re}(\alpha)<1$ has only one root which is always real, and $\alpha=0$ is not a root (meaning that there is no need to investigate the possible existence of a logarithmic singularity). For the material constants given by (56) and used in this paper $a$ is found to be

$$
\begin{equation*}
a=0.048940 . \tag{63}
\end{equation*}
$$

Thus, the approximate asymptotic behavior of the stresses around $(2=0$, $r=a)$ may be established by assuming that $\alpha$ is known and by using the last two calculated points for $\sigma_{i j}$ in the expressions (61) to determine the corresponding constants $A_{i j}$ and $B_{i j}$. The constants $A_{i j}$ are usually referred to as the stress intensity factors. For the present problem they are found to be

| $\sigma_{1} / \sigma_{2}$ | $A_{\theta \theta 1} / \sigma_{2}{ }^{\alpha}$ | $A_{\theta \theta 2} / \sigma_{2}{ }^{\alpha}$ | $A_{22} / 10^{-2} \sigma_{2}{ }^{\alpha}$ | $A_{r 2} / 10^{-2} \sigma_{2}{ }^{\alpha}$ |
| :---: | :---: | :---: | :---: | :---: |
| 1.964 | 1.608 | 0.776 | 0.082 | -2.224 |
| 1.000 | 1.144 | 0.562 | 0.990 | -20.918 |

This is essentially a curve-fitting process to a smooth data. Consequently, for example, it was observed that the next point calculated from (61) is rather in good agreement with the stresses given by series solution.

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Table 1. The first 60 roots of the characteristic equation (43)

| n | $\operatorname{Re}\left(\alpha_{n} h_{1}\right)$ | $I_{m}\left(a_{n} n_{1}\right)$ |  |
| :---: | :---: | :---: | :---: |
| 1 | 2.576640149 | 0 |  |
| 2 | 1.293810176 |  | 0.8298514402 |
| 3 | 2.885866996 | 0.7551679918 |  |
| 4 | 4.384613298 |  | 1.587138202 |
| 5 | 4.508247667 | 0.9781794212 |  |
| 6 | 6.169990276 | 1.228997641 |  |
| 7 | 7. $¢ 82619850$ |  | 2.113409611 |
| 8 | 7.752063359 | 1.340085172 |  |
| 9 | 9.342477506 | $1.451922 \% 1$ |  |
| 10 | 10.77125258 |  | 2.453236163 |
| 11 | 10.92034586 | 1.528341711 |  |
| 12 | 12.50012425 | 1.602698086 |  |
| 13 | 13.94523374 |  | 2.705188038 |
| 14 | 14.07574872 | 1.661164351 |  |
| 15 | 15.65192294 | 1.717452823 |  |
| 16 | 17.11030656 |  | 2.905787940 |
| 17 | 17.22622651 | 1.764831059 |  |
| 18 | 18.80069246 | 1.810326620 |  |
| 19 | 20.26975009 |  | 3.072577814 |
| 20 | 20.37415766 | 1.850159284 |  |
| 21 | 21.94765603 | 1.888423334 |  |
| 22 | 23.42541951 |  | 3.215377334 |
| 23 | 23.52055621 | 1.922785421 |  |
| 24 | 25.0934437 | 1.955843539 |  |
| 25 | 26.57843058 |  | 3.340252251 |
| 26 | 26.66594450 | 1.986056608 |  |
| 27 | 28.23841688 | 2.0515177619 |  |
| 28 | 29.72949401 |  | 3.451217584 |
| 29 | 29.81062486 | 2.042135663 |  |
| 30 | 31.38280031 | 2.068169865 |  |
| 31 | 32. 87908457 |  | 3.551071015 |
| 32 | 32.95478667 | 2.092505940 |  |
| 33 | 34.52674116 | 2.116052348 |  |
| 34 | 36.02753210 |  | 3.641841058 |
| 35 | 36.09855559 | 2.138231174 |  |
| 36 | 37.67034054 | 2.159728360 |  |
| 37 | 39.17507330 |  | 3.725045967 |
| 38 | 39.24201876 | 2.180101156 |  |
| 39 | 40.81367039 | 2.199880230 |  |
| 40 | 42.3218827 |  | 3.801851958 |
| 41 | 42.38523874 | 2.218718904 |  |
| 42 | 43.95678339 | 2.237036178 |  |
| 43 | 45.46809202 |  | 3.873:744¿4 |

Table 1 (Cont.)

| $n$ | $\operatorname{Re}\left(a_{n} h_{1}\right)$ | $I_{m}\left(a_{n} h_{1}\right)$ |  |
| :---: | :---: | :---: | :---: |
| 44 | 45.52826175 | 2.254555535 |  |
| 45 | 47.09971910 | 2.271613599 |  |
| 46 | 48.61380260 |  | 3.939745157 |
| 47 | 48.67112277 | 2.287986286 |  |
| 48 | 50.24250782 | 2.303948118 |  |
| 49 | 51.7590938 |  | 4.002158438 |
| 50 | 51.81384877 | 2.319314977 |  |
| 51 | 5378517321 | 2.334313681 |  |
| 52 | 54.90402880 |  | 4.060903¢96 |
| 53 | 54.95646096 | 2.348791111 |  |
| 54 | 56.52773403 | 2.362936830 |  |
| 55 | 58.04865835 |  | 4.116387922 |
| 56 | 58.09897623 | 2.376622132 |  |
| 57 | 59.67020534 | 2.390007063 |  |
| 58 | 61.19302391 |  | 4.16895489 |
| 59 | 61.24140822 | 2.402982400 |  |
| 60 | 62.81259940 | 2.415684503 |  |

Table 2. Variation of the stresses at the interface $2=0$, with $r / a$ for $\sigma / \sigma_{2}=1.964$

| $r / a$ | $\sigma_{\theta \theta 1} / 2 \sigma_{2}$ | $\sigma_{\theta \theta 2} / 2 \sigma_{2}$ | $\sigma_{z z} /\left(2 \sigma_{2} \times 10^{-3}\right)$ | $\sigma_{r z} /\left(2 \sigma_{2} \times 10^{-3}\right)$ |
| :--- | :---: | :---: | :---: | :---: |
| 1.025 | 0.955 | 0.460 | - | -11.0 |
| 1.037 | 0.933 | 0.449 | -1.0 | -9.7 |
| 1.050 | 0.910 | 0.438 | -1.5 | -8.9 |
| 1.075 | 0.868 | 0.417 | -1.8 | -7.7 |
| 1.100 | 0.899 | 0.399 | -1.8 | -6.7 |
| 1.150 | 0.758 | 0.365 | -1.5 | -3.1 |
| 1.200 | 0.697 | 0.335 | -1.1 | -3.9 |
| 1.300 | 0.594 | 0.286 | -0.3 | -2.3 |
| 1.500 | 0.446 | 0.215 | 0.3 | -0.8 |
| 1.750 | 0.328 | 0.158 | 0.3 | -0.2 |
| 2.0 | 0.251 | 0.121 | 0.1 | -0.05 |
| 3.0 | 0.111 | 0.054 | 0. | 0. |
| 4.0 | 0.063 | 0.030 | 0. | 0. |
| 5.0 | 0.040 | 0.019 | 0. | 0. |

Table 3. Distribution of stresses in $z$ - direction for $r / a=1.2$ and $\sigma_{1} / \sigma_{2}=1.964$

|  | $2 / h_{i}$ | $\sigma_{z z i} /\left(2 \sigma_{2} \times 10^{-3}\right)$ | $\sigma_{r z i} /\left(2 \sigma_{2} \times 10^{-2}\right.$ | $\sigma_{\theta \text { فf }} / 2 \sigma_{2}$ |
| :---: | :---: | :---: | :---: | :---: |
| $\mathrm{i}=1$ | 0. | -1.1 | -3.9 | 0.697 |
|  | 0.25 | -2.1 | -2.1 | 0.692 |
|  | 0.50 | -1.5 | 0.4 | 0.687 |
|  | 0.75 | -0.5 | 1.2 | 0.682 |
|  | 0.90 | -0.1 | 0.7 | 0.679 |
|  | 1.0 | 0. | 0. | 0.677 |
| $\mathrm{i}=2$ | 0. | -1.1 | -3.9 | 0.335 |
|  | -0.25 | 0.1 | -0.5 | 0.339 |
|  | -0.50 | -0.4 | 1.7 | 0.344 |
|  | -0.75 | -0.3 | 1.6 | 0.349 |
|  | -0.90 | -0.08 | 0.9 | 0.353 |
|  | -1.0 | 0. | 0. | 0.355 |

Table 4. Variation of the stresses at the interface $2=0$, with $r / a$ for $\sigma_{1} / \sigma_{2}=1.0$

| $r / a$ | $\sigma_{\theta \theta 1} / 2 \sigma_{2}$ | $\sigma_{\theta \theta 2} / 2 \sigma_{2}$ | $\sigma_{2 z} /\left(2 \sigma_{2} \times 10^{-2}\right)$ | $\sigma_{r 2} /\left(2 \sigma_{2} \times 10^{-2}\right)$ |
| :--- | :---: | :---: | :---: | :---: |
| 1.025 | 0.672 | 0.324 | - | -10.4 |
| 1.037 | 0.653 | 0.312 | -0.9 | -9.2 |
| 1.050 | 0.635 | 0.301 | -1.4 | -8.5 |
| 1.075 | 0.605 | 0.286 | -1.7 | -7.3 |
| 1.100 | 0.578 | 0.273 | -1.7 | -6.4 |
| 1.150 | 0.529 | 0.250 | -1.4 | -4.9 |
| 1.200 | 0.487 | 0.231 | -1.0 | -3.7 |
| 1.300 | 0.415 | 0.199 | -0.3 | -2.2 |
| 1.500 | 0.313 | 0.151 | 0.3 | -0.8 |
| 1.750 | 0.230 | 0.111 | 0.3 | -0.2 |
| 2.0 | 0.176 | 0.085 | 0.1 | -0.05 |
| 3.0 | 0.078 | 0.038 | 0. | 0. |
| 4.0 | 0.044 | 0.021 | 0. | 0. |
| 5.0 | 0.028 | 0.014 | 0. | 0. |

Table 5. Distribution of stresses in $z$ - direction for $r / a=1.2$ and $\sigma_{1} / \sigma_{2}=1.0$

|  | $z / h_{i}$ | $\sigma_{2 z i} /\left(2 \sigma_{2} \times 10^{-2}\right)$ | $\sigma_{r z i}\left(2 \sigma_{2} \times 10^{-2}\right)$ | $\sigma_{\theta \theta i} / 2 \sigma_{2}$ |
| :---: | :---: | :---: | :---: | :---: |
| $\mathrm{i}=1$ | 0. | -1.0 | -3.7 | 0.487 |
|  | 0.25 | -2.0 | -2.0 | 0.444 |
|  | 0.50 | -1.4 | 0.4 | 0.399 |
|  | 0.75 | -0.5 | 1.1 | 0.350 |
|  | 0.90 | -0.1 | 0.7 | 0.321 |
|  | 1.0 | 0. | 0. | 0.302 |
| $\mathrm{i}=2$ | 0. | -1.0 | -3.7 | 0.231 |
|  | -0.25 | 0.1 | -0.5 | 0.270 |
|  | -0.50 | -0.4 | 1.6 | 0.318 |
|  | -0.75 | -0.3 | 1.6 | 0.369 |
|  | -0.90 | -0.07 | 0.8 | 0.400 |
|  | -1.0 | 0. | 0. | 0.423 |



Figure 1. Geometry of the composite plate


Figure 2. Variation of the hoop stresses $\sigma_{\theta \theta 1}(r, 0)$ and $\sigma_{e \theta 2}(r, 0)$ with $r / a$ for $\sigma_{1} / \sigma_{2}=1.964$ and $z=0$


Figure 3. Variation of the interface stresses $\sigma_{z z}(r, 0)$ and $\sigma_{r z}(r, 0)$ with $r / a$ for $\sigma_{l} / \sigma_{2}=1.964$


Figure 1. Variation of the hoop stresses $\sigma_{\theta \theta 1}(r, 0)$ and $\sigma_{\theta \theta 2}(r, 0)$ with
$r / a$ for $\sigma_{1} / \sigma_{2}=1$


Figure 5. Variation of the interface stresses $\sigma_{z z}(r, 0)$ and $\sigma_{r z}(r, 0)$ with $r / a$ for $\sigma_{1} / \sigma_{2}=1$


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[^1]:    *Note that $Z_{1}^{0}$ and $Z_{2}^{0}$ are of the form: $\left.f(r)+g(r) h(z)+m i z\right)$ suggested in [9].

[^2]:    *The stress ratio 1.964 corresponds to (8a) and (8b) for the material pair under consideration.

[^3]:    *The numerical results given in the tables are obtained by using 20 to 30 terms in the series for locations away from the hole and up to 60 terms near the hold boundary.

