Development Techniques for Generic Software

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1. INTRODUCTION

In developing the first version of a generic implementation of X.25, Levels 2 and 3, we examined three development techniques: table-driven finite state machine implementation, an integrated testing environment, and top-down design. While not designed as an experiment, we monitored the project closely and compared the product with other implementations of X.25 at Bell Laboratories to evaluate potential benefits and penalties.

2. TECHNIQUES

2.1 Finite State Machine

A finite state machine (FSM) is a powerful tool for both specifying and implementing protocols. This technique was used in the X.25 specification and has been discussed in the literature[1,2,3,4]. A table-driven implementation of the FSM was chosen to facilitate changes and simplify coding. We were interested in what effect this technique would have on program size, speed of execution, coding time, and debugging time.

2.2 Testing Environment

Contrary to common practice, we made a testing environment before coding. The complexities of a communications protocol, especially X.25, require careful attention to the problems of verifying that an

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implementation of that protocol does in fact perform correctly. In addition, we felt that the process of verification should start as early as possible in the development process. The testing environment, which runs under the UNIX^{*} operating system, let us test the FSM and its tables very early in the coding process. We were able to integrate new modules easily and test them thoroughly using this tool.

2.3 Top Down Design

In designing and implementing a solution, we followed a top-down approach. This made it possible to have a "running" version at all times, with unwritten modules replaced by dummy routines. This was not rigorously followed in coding because it was often more sensible to code all of the routines that performed one function even if that meant coding some low-level functions early. Doing this still let us always have a running version, but simplified testing.

3. MEASUREMENTS

Our main method for evaluating these techniques was comparison with existing implementations of X.25 at Bell Laboratories. We measured the size and execution speed of both our implementation and the existing ones and ran some simple complexity metrics.

* UNIX is a Trademark of Bell Laboratories

R. Hamilton Bell Labs 2 of 20 We used the testing environment to help modify and transport existing implementations of both Level 2 and Level 3 to a new environment, which gave us the opportunity to compare our versions with the existing ones in terms of the ease of making modifications. We kept a log of program bugs found and the effort it took to fix them, for all of the implementations, and tried to characterize the types of problems found.

4. CONCLUSION

A combination of a table-driven finite state machine realization, a comprehensive testing environment, and a top-down approach was used to produce an implementation of X.25, Levels 2 and 3. In comparison with other, ad hoc, X.25 implementations, we found that our solution ran as much as 20% faster, but was about 35 to 40 percent bigger. We were able to explain all but 11% of that difference in terms of added function or added flexibility. A McCabe complexity metric showed little difference between the implementations.

Comparison of time spent debugging showed that our approach was superior to the ad hoc methods, both in terms of number of errors detected and time taken to correct those errors. Even so, the testing environment was shown to be a significant aid in debugging the other implementations when compared to other testing techniques. Although not intended as a controlled experiment, the data collected during development support using these techniques in similar circumstances.

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REFERENCES

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THE VIEWGRAPH MATERIALS for the R. HAMILTON PRESENTATION FOLLOW

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DEVELOPMENT TECHNIQUES

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FOR GENERIC SOFTWARE

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X.25 DEVELOPMENT

OBJECTIVES

Portable

set of primitive functions

Maintainable

Flexible

Modifiable

Testing/ development environment Table-driven finite state

Layered approach

TOOLS

C language, minimal

DEVELOPMENT ENVIRONMENT

UNIX[™] Operating System

Make

• AWK

• SCCS

• Shell

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LEVEL 2 -- NORMAL ENVIRONMENT



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FINITE STATE MACHINE

• Table-driven

• Hierarchical

Parallel

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X.25 IMPEEMENTATION

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FINITE STATE MACHINE



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FINITE STATE MACHINE



FINITE STATE MACHINE

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	- -	
LEVEL 2	LINES OF CODE	% DIFFERENCE
• Existing	1039	
• Generic	1846	+78%
LEVEL 2	LINES OF CODE	% DIFFERENCE
• Existing	1590	
• Generic	2252	+42%

LINES OF CODE

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IEVEL 2	теут				
	TEA:	DAIA	_	- TOTAL	10 DIFFERENCE
• Existing	5088	56	Ξ	5744	
• Generic	6766	1236	=	8002	+39%
LEVEL 3	TEXT	DATA	=	TOTAL	
● Existing	6818	268		7086	
• Generic	8558	926	=	9484	+34%

Note: All programs compiled under the 8086 cross-compiler with the optimize option, without primitives, and without any debugging aids included

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LEVEL 2 SIZE DIFFERENCES

Added function

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Channel No.	200
 Timer routines 	272
Disconnect	186
Added flexibility	
 Action overhead 	248
Channel select	52
♦ Multi-table FSM	200
 Table clarity 	1 92
 Optional prims 	100
TOTAL	1450
Actual difference	2258
Bytes unaccounted for	808

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MEASUREMENTS

Size - 35 to 40% larger

Speed - 0 to 20% faster

Complexity - Equivalent

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