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OPDOT: A COMPUTER PROGRAM FOR THE OPTIMUM PRELIMINARY DESIGN OF A TRANSPORT AIRPLANE

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Steven M. Sliwa and P. Douglas Arbuckle

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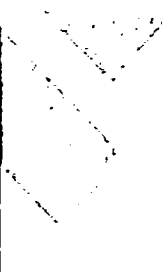
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OPDOT: A COMPUTER PROGRAM FOR THE OPTIMUM PRELIMINARY
DESIGN OF A TRANSPORT AIRPLANE

Steven M. Sliwa and P. Douglas Arbuckle

ABSTRACT

A description of a computer program, OPDOT, for the optimal preliminary design of transport aircraft is given. OPDOT utilizes constrained parameter optimization to minimize a performance index (e.g. direct operating cost per block hour) while satisfying operating constraints. The approach in OPDOT uses geometric descriptors as independent design variables. The independent design variables are systematically iterated to find the optimum design. The technical development of the program is provided and a program listing with sample input and output are utilized to illustrate its use in preliminary design. This is not meant to be a user's guide, but rather a description of a useful design tool developed for studying the application of new technologies to transport airplanes.

INTRODUCTION

When new technologies in aircraft design, fabrication and operation are evaluated, current practice requires engineering judgment in making compromises. An engineer utilizes a combination of limited analyses, experience and intuition to combine new technologies (e.g., aerodynamics, controls or structures) to maximize the benefits. This approach is imprecise because it involves extrapolating experience from previous designs and because the improvements are usually made to augment multiple, ill-defined criteria (e.g., weight, cost, or performance). To properly evaluate any changes in design concepts, the airplane configuration should be allowed to evolve to optimize a single, well-defined performance index.

This report describes OPDOT (Optimum Preliminary Design of Transports), a computer program written to perform preliminary design and evaluation of transport aircraft using nonlinear programming techniques. A set of independent design variables is iterated upon until a minimum of a performance index which satisfies a series of constraint functions has been calculated. The design variables usually consist of geometry characteristics and mission parameters, while the constraint functions include, for example, regulatory performance requirements and handling quality design criteria. A slightly modified, constrained sequential optimizer is utilized in the program.

This program, therefore, allows the evaluation of new technologies incorporated into an aircraft design in an optimal fashion. The degree of detail in the analyses when the performance function and the constraint functions are evaluated is at the preliminary design or classical aeronautics level. That is, the precision in some phases of the calculations is expected to be as

poor as 5-10 percent. Hence, whereas the predictive capabilities are expected to be marginal, the accuracy of the relative comparisons of designs is expected to be good.

This report, which includes a program listing, sample input and sample output, is a description of a useful analytical tool for analyzing the effects of new technologies on the preliminary design and sizing of transport airplanes. It describes the methods of calculation, program organization and some of the various options available, but it is not meant to be a comprehensive user's manual. The program code was written to expeditiously obtain answers for a study of the impact of active controls upon transport design. This limited the amount of effort that could be spent on developing user flexibility and on integrating into the program a high degree of self-annotation.

SYMBOLS

A	wing aspect ratio
A_t	horizontal tail aspect ratio
b	span, m
\bar{b}	ratio of tail span to wing span, b_t/b_w
B	Brequet range factor, $\frac{M L/D}{c}$
c	specific fuel consumption
\bar{c}	mean aerodynamic chord of wing
c_i	i-th constraint value
C_C	chordwise force coefficient
C_D	drag coefficient, $\text{drag}/\bar{q}S$
C_L	lift coefficient, $\text{lift}/\bar{q}S$
C_{L_A}	approach lift coefficient
C_{L_t}	tail lift coefficient
C_{L_o}	design lift coefficient for wing airfoil section

$C_{L_{so}}$	stall lift coefficient with full flaps
$C_{L_{TO}}$	lift coefficient at takeoff
C_{L_2}	lift coefficient during second segment climb
C_m	pitching moment coefficient, pitching moment/ $\bar{q}S\bar{c}$
C_N	normal force coefficient
C_T	thrust coefficient
f	unaugmented performance index
F	augmented performance index
\bar{g}_i	i th constraint function
h_t	vertical tail height, m
i	angle of incidence, deg
K	penalizing weight
K_θ	pitch feedback gain, $\partial\delta/\partial\theta$
$K_{\dot{\theta}}$	pitch rate feedback gain, $\partial\delta/\partial\dot{\theta}$
l_t	distance from wing aerodynamic center to tail aerodynamic center, m
L/D	glide ratio
m	mass (slugs)
M	Mach number
M_q	pitching moment derivative due to pitching velocity, sec^{-1}
M_w	pitching moment derivative due to unit vertical velocity, sec^{-1}
$M_{\ddot{w}}$	pitching moment derivative due to vertical acceleration, sec^{-1}
M_σ	pitching moment derivative due to control deflection, sec^{-1}

n	number of engines
n_Z/α	airplane vertical gain, g's/rad
N_i	ith constraint normalizing factor, $\frac{ S_{l_i} + S_{u_i} }{2}$
p	design parameter (constant for optimization)
\bar{q}	dynamic pressure
R	airplane range, kilometers
S_{l_i}, S_{u_i}	lower and upper boundaries of ith constraint
S_t	tail area, m^2
S_w	wing area, m^2
T	thrust at altitude, N
T_I	installed thrust at sea level, N
TOP	Take-off parameter
U_o	reference velocity, m/sec
V_{cr}	cruise velocity, m/sec
V_{l_i}, V_{u_i}	lower and upper boundaries of ith independent design variable
W	aircraft weight at altitude, N
W_{TO}	maximum aircraft weight at take-off, N
W_1	initial aircraft weight during cruise segment, N
W_2	final aircraft weight after cruise segment, N
X_i	ith independent design variable
\bar{X}_{ac}	% MAC from datum to c.g. in x-direction

Z_i	independent design variable transformed
Z_δ	dimensional vertical force derivative due to elevator deflection, sec^{-1}
\bar{z}_{ac}	% MAC from datum to c.g. in z-direction
\bar{z}_t	height of thrust vector from c.g. (% MAC)
ϵ_1	Oswald's efficiency factor for $0 \leq C_L \leq C_{L_0}$
ϵ_2	Oswald's efficiency factor for $C_L > C_{L_0}$
γ	flight path angle, rad
ω_{sp}	short period frequency, sec^{-1}
σ	Munk's interference factor
t	tail efficiency, $\frac{\bar{q}_t}{q_\infty}$

Superscript

* optimum

Subscripts

ac	aerodynamic center
cr	cruise
q	pitch rate
t	tail
u	velocity
w	wing
α	angle of attack
$\dot{\alpha}$	rate of change in angle of attack

PROGRAM DESCRIPTION

General

The overall flow of the program is depicted in figure 1. A set of starting values for the selected independent design variables and design constants is input and used to initialize the optimizer and the data base. Initially, the program was written with seven independent variables (wing area, wing aspect ratio, fuselage length, horizontal tail area, horizontal tail aspect ratio, aft-most center-of-gravity position, and installed thrust), but it has the inherent capability to handle more and has successfully converged with thirteen. Typical design constants include nonvarying geometries, mission parameters, economic constants, nonlinear aerodynamics data and some levels of technology. An extensive list of design constants that were used in one study is shown in Appendix VII.

Design constants are prime candidates for being changed to independent design variables. Both design constants and independent design variables are held constant for each call to the performance function evaluation routines. Independent design variables are typically altered each function call by the optimizer, while design constants are not allowed to vary for the entire optimization. A method for augmenting the set of independent design variables with design constants will be described in a later section.

The inputs (the current value of independent design variables and the design constants) are utilized by a sequence of subroutines that calculate a performance index which is selected by the user. Typically, minimum direct operating cost per block hour is chosen, but minimum direct operating cost per flight, maximum return-on-investment per year, minimum income required for a 15 percent return on investment, maximum L/D and minimum take-off gross weight are also available as criteria to be optimized. During the series of subroutine calls, data is exchanged with and stored in the data base for future use. The program has been constructed in a modular fashion to allow users to replace routines with preferred versions to allow significant configuration changes or to improve the level of accuracy.

Next a series of subroutines is called to calculate the constraint functions. Those that are calculated for cruising flight utilize data stored in the data base during the performance function evaluations. Many subroutines were written in such a fashion as to provide data in slow flight configurations as well as in cruising flight. These are called to yield take-off and landing performance data. As a byproduct, the longitudinal stability derivatives are generated. These nondimensional derivatives, for both approach and cruise, are converted to dimensional derivatives and are then used to determine the roots of a fourth order linear model of the longitudinal dynamics. These roots are used to calculate the damping and frequency in the short period and phugoid modes.

The program determines which constraint functions are violated and adds a penalty term for each violation to the performance index to create an augmented performance index. The optimizer then iterates upon the design variables to minimize the augmented function. If the weights on the penalty terms are sufficiently large, the violations will be driven to zero. A convergence of the optimizer results in the minimum unaugmented performance index that satisfies the constraint functions.

Optimization Code

The optimization is performed by a sequential simplex method (Ref. 1 and 2) which utilizes a continuous penalty function. This direct search algorithm has the advantage of not using gradient evaluations, and hence does not perform poorly near "ridges" in the performance index. Additionally, the penalty scheme is independent of the number of active constraints. Its chief disadvantage is slow convergence in large regions of small gradients of the augmented performance function with respect to the independent design variables.

The general problem is formulated as follows:

Let the unaugmented performance index, f , be a function of the independent design variables, x , and design parameters, p .

$$f = fcn(x,p) \quad (1)$$

and

$$\bar{g}_i \begin{cases} = 0 & \text{if } c_i \geq S_{\ell_i} \text{ and } c_i \leq S_{u_i} \\ = S_{\ell_i} - c_i & \text{if } c_i < S_{\ell_i} \\ = c_i - S_{u_i} & \text{if } c_i > S_{u_i} \end{cases}$$

then

$$F = f + \sum_{i=0}^m K(\bar{g}_i/N_i)^2 \quad (2)$$

The goal is to find the minimum of the augmented function, F , with the gains, K , large.

A variable transformation (Ref. 3) is used to automatically scale the variables and apply "side" constraints, which are inequality constraints applied

directly on the design variables. This resulted in a reduction in the number of iterations required for convergence.

The form of the transformation is as follows:

$$X_i = \frac{V_{u_i} - V_{l_i}}{2} \sin \left(\frac{\pi}{2} Z_i \right) + \frac{V_{u_i} + V_{l_i}}{2} \quad (3)$$

where V_{u_i} and V_{l_i} are the i th upper and lower independent design variable boundaries. So the simplex optimizer iterates on the transformed variable Z , which spans the set of allowable values of the independent design variables with the range in Z of 1 to -1. This allows consistency in step size selection and limits the allowed values of the independent design variables.

A version of the program is listed in Appendix I. The main program SIMPACT, the subroutines NELMIN and SETUP with the function FN are used to perform the optimization. Some key variables and a description of the pertinent labelled common blocks are shown in Appendices V and VI, respectively. Prior to the optimization, a series of inputs to initialize the optimization blocks is read in and XINPUT is used to initialize the aircraft data. NELMIN, the subroutine which returns the constrained minimum, is called several times (usually two) with increasing weights and diminishing convergence criteria and initial step sizes. This is to help in obtaining a satisfactory local minimum with no constraints violated and, ideally, with the active constraints resting against their boundaries.

NELMIN calls FN which returns the augmented performance index. FN calls SETUP which performs the variable transformations, obtains the unaugmented performance index, calls the constraint evaluation routines, determines the penalty terms and then assembles the augmented performance index. The unaugmented performance index is determined by calling DOCOST and the constraint functions are calculated from CNSTRN.

Evaluation of Unaugmented Performance Index

A flow diagram showing the general procedure for evaluating the unaugmented performance index is shown in figure 2. DOCOST (Included in Appendix I) assembles various cost components by first calling GEO to calculate and store some geometry constants and then calling CGCAL to assign the center-of-gravity positions for the various phases of flight and the landing gear position (if variable). Then WEIGHT is called which is used to estimate the airplane's operating weights, the amount of fuel burned during the mission and a variety of other parameters required from the cruise portion of the flight.

In WEIGHT, an initial estimate of take-off weight and fuel fraction is made. The individual weight components are determined using statistical relationships

from references 4 through 6. The primary source was reference 4, but the critical components for the intended uses of the program (i.e., wing, horizontal tail and fuselage) were limited to geometric ranges to maintain validity. To improve the capability of predicting the weights of these components (e.g., at high aspect ratios) an average of values calculated from references 4 through 6 was made. After the component weights are summed, FUELCAL is used to determine the weight of the fuel required to fly the passenger mission and the reserve mission. This fuel weight is used to estimate the weight of the fuel systems.

The sum of the individual estimated weight components is compared with the initial estimate of take-off weight; and, if the difference is greater than some convergence criterion (usually about .2 Newtons), a new estimate is made and the components are summed again. This continues until the weight loop convergence criterion is satisfied. The new estimate for the gross take-off weight is made through a weighting scheme based on the number of current iterations. The total and average number of iterations is displayed to the user to provide guidance in possible programming changes in the event of slow weight loop convergence. Usually WEIGHT averages between 3 and 5 iterations per function call during an optimization run.

FUELCAL assumes a flight profile schematically illustrated in Figure 3. A fixed percentage of the total fuel burnoff is attributed to the following tasks: taxi, take-off, initial climb, climb to cruise, descent and landing. The remainder of the flight (the cruise portion) is divided into ten equal segments. During the first segment the transport is flown at a C_L for maximum range factor, B^* . The initial cruise altitude is 11000 m (36000 ft), and CRUALT is called to find the desired altitude at the end of the first segment to maintain the same C_L for a new weight, while insuring the aircraft is also cruising at the desired Mach Number. The required excess thrust to generate the calculated climb gradient is then saved for future use in the constraint functions.

Segments 2 through 5 are flown in a cruise/climb mode at M_{cr} and B^* , which can be calculated from classical relationships. At segment 6, however, the climb is increased so that segments 7 through 10 can be flown at cruise Mach number, M_{cr} , and 98% L/D_{max} . The cruise is backed off L/D_{max} slightly to help provide some speed stability.

Thus, as modelled above, the independent design variables only impact the cruise portion of the flight. To simulate the complex reserve mission requirement, the transport is flown for an additional 1400 kilometers (1000 nautical miles) at 9100 meters (30,000 feet) at the speed for maximum range.

CRUFUEL calculates the amount of fuel burned during each segment as well as the time required to fly it and the altitude change to satisfy the cruise/climb assumptions. As previously described, the aircraft is flown at the speed for maximum Breguet range factor during the first five segments provided the resulting Mach number is less than or equal to the desired cruise Mach number. The solution comes from classical aeronautics, for example, reference 4.

$$L/D_{B*} = .943 L/D \quad (4)$$

from aeronautics and assuming parabolic drag polars

$$C_{L_{B*}} = .79 C_{L_{L/D_{\max}}} \quad (5)$$

CRUALT returns the required altitude to fly at the specified weight, lift coefficient and Mach number at the end of each segment. CRUFUEL then estimates a rate-of-climb slightly greater than that which would maintain the maximum range factor cruise for the given altitudes. The eventual goal is to achieve a cruise at 98% of maximum L/D for the last four segments of the cruise distance at the cruise Mach number. Holding the Mach number fixed results in increasing lift coefficients as altitude increases. This is continued until the airplane attains maximum L/D.

The assumed mission profile, although patently suboptimal, varies less than 3 percent in fuel consumption from some optimal profiles (Ref. 7). Given the level of accuracy of the program and the desire to compare designs rather than predict the performance of one design, this level of precision was deemed acceptable.

XLOD is used to estimate the aerodynamic performance of the airplane. The parasite drag is obtained from CDZL. CDZL performs a drag buildup by estimating the Reynolds number, friction coefficients, and various nonlinear constants as illustrated in references 4 and 8. Increments in drag are included for "crud" drag and flap deflections. XLOD then calls STABCOD to estimate the stability and control derivatives while in the indicated flight configuration. These nondimensional derivatives are obtained from a combination of empirical and analytical relations developed from references 8 through 10 for transport airplanes. Some aeroelastic correction factors are applied to the derivatives based on observations of data in references 10 through 12.

XLOD then utilizes the stability and control data as it calls TRIM. The desired airplane lift coefficient with the specified Mach number, parasite drag, flap configuration, center-of-gravity position and phase of flight are input to TRIM.

The following classical non-linear trim equations (Ref. 13) were used in TRIM to represent the normal and chordwise forces and to solve for the required tail or wing lift coefficients:

$$C_{N_t} = \frac{S_w \bar{c}}{S_t \ell_t} \frac{1}{\eta_t} \left(C_{N_w} \bar{X}_{ac} + C_{C_w} \bar{Z}_{ac} + C_{m_{ac}} \begin{array}{l} \text{wing} \\ \text{fuselage} \\ \text{nacelle} \end{array} + C_{C_t} \frac{S_t}{S_w} \frac{h_t}{\bar{c}} \eta_t - C_T \frac{Z_t}{\bar{c}} \right) \quad (6)$$

$$C_{C_w} = C_{D_w} \cos(\alpha_w - i_w) - C_{L_w} \sin(\alpha_w - i_w) \quad (7)$$

$$C_{N_w} = C_{L_w} \cos(\alpha_w - i_w) + C_{D_w} \sin(\alpha_w - i_w) \quad (8)$$

An iterative scheme utilizing the above equations is used whereby a new tail lift coefficient is estimated until a convergence criterion is satisfied. Direct substitution into the vertical force, horizontal force and pitching moment equation is not possible since it has been deemed inappropriate to linearize the transcendental functions. It would also require neglecting the vertical offset of the center-of-gravity from the aerodynamic center and thrust-line and neglecting the contributions due to tail drag. Typically three or four iterations are required to satisfy the trim convergence criteria ($\Delta C_{L_t} \leq .003$).

TRIM is used in one of two fashions. First, if a desired airplane lift coefficient is input, the routine iterates to find the required lift coefficients for the tail and wing. Alternatively, if a wing lift coefficient is input, the required tail lift coefficient is output along with the resulting airplane lift coefficient. The latter mode is used to determine the maximum trimmed lift coefficient for approach or take-off configurations where stalling of the wing is a concern.

The wing compressibility drag contribution is calculated in XLOD by using the empirical relationships found in reference 14, which were derived from supercritical aerodynamics wind tunnel data. The fuselage compressibility drag term is modelled from the graphs in reference 13. It should be noted that it is assumed that the fuselage is not area ruled and hence calculated drag will be pessimistic for transonic configurations ($1.0 > M_{cr} > 0.9$).

The induced drag contribution is obtained as follows:

$$C_{D_i} = \frac{C_{L_o}^2}{\pi A \epsilon_1} + \frac{C_{L_w}^2 - C_{L_o}^2}{\pi A \epsilon_2} + \frac{2\sigma C_{L_w} C_{L_t} S_{t_1}}{b \pi A S_w \epsilon_1} + \frac{S_t C_{L_t}^2}{S_w \pi A_t \epsilon_t} \quad (9)$$

The first two terms are the wing contribution including an offset for the design lift coefficient of the highly cambered wing. The third term represents the interference drag between the lift vectors of the tail and the wing. Notice how the interference term could be negative if the tail lift were downward. The fourth term is the drag contribution of the tail lift (positive for a tail load in any direction). The interference factor, σ , is a function of the gap ratio, h_t/b_w , and the span ratio, \bar{b} . This term is calculated from a least squares polynomial fit (Ref. 15) of the curves in reference 16.

The total drag, calculated in XLOD, is the sum of the induced drag, the drag due to elevator deflection ($C_{D\delta}$ estimated from Ref. 13), the compressibility drag and the parasite drag. The L/D is obviously calculated as C_L/C_D . Additionally, the lift coefficient for L/D_{\max} is estimated and stored for future use. XLOD, CDZL, STABCOD and TRIM are generalized to function for both cruise and approach conditions.

CRUFUEL then calls ENGINE to determine the thrust and specific fuel consumption as a function of altitude and Mach number. The engine performance comes from a normalized model of the baseline engine from reference 7. The engine weight and size are scaled according to reference 4 based upon the installed thrust. The specific fuel consumption obtained from ENGINE and the L/D from XLOD are substituted into the classical Brequet range relationship for each cruise segment to determine the fuel consumption.

$$\frac{W_1}{W_2} = \exp \left(\frac{c R}{V_{cr} L/D} \right) \quad (10)$$

After WEIGHT has converged upon the aircraft operating weights for the desired mission, DOCOST continues with the cost estimates. AIRCOST used the weight, some production assumptions (number of prototypes, number of production, time for development, etc.) and the statistical relationships of reference 4 to predict the purchase cost of the airplane. Some cost increases based on references 17 and 18 are arbitrarily applied to account for the inclusion of active controls.

MAINCST uses statistical relationships found in references 19 and 20 to determine the cost of airplane maintenance. A number of configuration assumptions have to be made (e.g., number of APU's, windows and IMU's) to utilize these equations (see Appendix VII). The equations for estimating the other direct operating cost terms come from references 17 and 20. Indirect operating cost is predicted using the statistical relationships from references 17 and 21. An annual rate of return on investment (ROI) is calculated and the remaining performance indices are saved in the data base for future use by the optimizer.

EVALUATION OF CONSTRAINT FUNCTIONS

The program version included herein has 52 constraint functions that can be applied to the transport design. The designer chooses an upper and lower boundary for each function as an input. The program does a test on all constraint lower boundaries; and, if -999 is input for the lower boundary of a constraint function, the constraint is not included in the penalty function even if it is a violation. The constraint functions are of two general types, design or operational constraints and handling quality constraints. The first set restricts the design to avoid infeasible geometries or to insure satisfying performance regulations and mission requirements. The second set is used in the study of tail sizing and the impact of flying qualities design criteria upon transports with relaxed static stability augmentation systems.

CNSTRN returns the values of the constraint functions to SETUP, where they are identified as violated or not violated, normalized and assembled into a penalty function. The ratio of cruise thrust available to cruise thrust required is obtained from the data base as are the cruise altitudes and the cruise wing lift coefficient. The geometry constraints include insuring that the aft center-of-gravity is far enough forward of the main landing gear to provide sufficient nose wheel steering and that there is enough floor space to seat the passengers.

The missed approach climb gradient and the second segment climb gradient are engine-out performance requirements specified by the Federal Aviation Regulations, FAR's, (Ref. 22). The required thrust to weight ratio is calculated as follows:

$$\frac{T_I}{W} = \left(\frac{N}{N-1} \right) \left(\frac{1}{L/D} + \sin \alpha \right) \left(\frac{1}{T/T_I} \right) \quad (11)$$

The flight path angle is specified by the FAR's and the L/D is obtained by calling XLOD with the proper speed and configuration specified. The second segment climb is performed at maximum gross weight and at a lift coefficient defined by

$$C_{L_2} = C_{L_{TO}} / 1.44 \quad (12)$$

The missed approach climb is performed at maximum landing weight and at a lift coefficient defined by

$$C_{L_A} = C_{L_{so}} / 1.69 \quad (13)$$

$C_{L_{TO}}$ and $C_{L_{so}}$ are determined by specifying the maximum lift coefficient that the wing can support in each flap configuration and then calling XLOD, which for this case trims the airplane maintaining the wing lift coefficient. Since the tail of conventional configurations is generally carrying a download at this point, the aircraft will usually trim at an overall lift coefficient less than the one specified for the wing alone.

The landing and take-off field length are determined using empirical relationships from reference 23. The landing field length utilizes approach speed as the independent parameter. TOP, which is defined as

$$TOP = \frac{W_{TO}/S_W}{C_{L_{TO}} T_I/W_{TO}} \quad (14)$$

is used as the independent parameter for the take-off analysis.

Several of the flying quality constraints are control power requirements. One is to maintain a lift coefficient on the tail greater than $-.8$ during approach (Ref. 24). This is to provide adequate margin from the maximum download capable of being supported by the tail (generally $C_{L_t} = -1.2$) to insure

a capability to rotate and trim the aircraft for landing.

The tail is also required to be able to rotate the airplane for take-off. The maximum available download the tail can produce during take-off roll is calculated using the relationships in reference 14 modified for ground effect using the geometric angle-of-attack method of reference 8. The required download at the tail is determined from statics, such as the development in reference 25. The constraint specifically requires the ratio of the available tail download to the required tail download to be greater than 1.

The flying quality analysis is initiated by trimming the airplane in approach configuration with an altitude of 150 meters by calling XLOD. The nondimensional stability derivatives for cruise and approach, which are stored in the data base, are converted to dimensional stability derivatives by DIMDER. The characteristic equation for the fourth order longitudinal set of equations (Ref. 26) is assembled by LONGRT. The four roots are determined by using RPOLY, a system routine for finding roots of polynomials on Langley Research Center's FORTRAN Math Library.

The preceding analysis is used to assign the following constraint functions for both cruise and approach: static stability, maneuver stability, dynamic stability, phugoid mode frequency and damping and the short period mode frequency and damping. The dimensional stability derivatives are used to estimate the following parameters which have been suggested as useful for flying

qualities analysis: time-to-double, time-to-half, flight path stability in approach, vertical gain and ω_{sp}^2/n_Z .

The tail is configured with a trimmable stabilizer, maintaining the elevator for maneuvering. If the stabilizer "hits" a control stop in either cruise or approach, the elevator is deflected to satisfy the remaining trim requirements. The amount of this trim deflection is stored as a constraint function and is usually required to be zero. Otherwise, a control deflection would indicate a loss of control authority, and in some cases, an increase in trim drag.

Since one intended use of the program is to study unaugmented flying qualities design criteria, it is desirable to insure that the airplane is capable of being practically augmented to excellent flying qualities. A pitch-attitude-hold with pitch-rate-command autopilot was chosen as a conservative estimate of an augmentation system. The airplane is arbitrarily augmented to have: $\frac{\omega_{sp}^2}{n_Z/\alpha} = 1$ and $\zeta_{sp} = .7$. An extension of reference 27 is used to calculate the feedback gains K_θ and K_θ^* . In reference 27 it is assumed that M_w , M_w^* and Z_δ are negligible and hence zero. If these assumptions are removed, the following relations are derived utilizing the short period approximation to the longitudinal dynamics:

$$K_\theta = \omega_{sp}^2 \frac{(1 - M_w U_o)}{M_\delta + M_w} + K_\theta^* \frac{(M_w M_\delta)}{M_\delta + M_w} \omega_{sp}^2 \quad (15)$$

$$K_\theta^* = 2\zeta_{sp} \omega_{sp} (M_w U_o - 1) - M_q - M_w U_o + M_w^* \omega_{sp}^2 \frac{(1 - M_w U_o)}{(M_\delta + M_\delta^*)}$$

$$+ 1 - \frac{M_w^2 M_\delta \omega_{sp}}{(M_\delta + M_w)} + 2\zeta_{sp} \omega_{sp} M_w M_\delta - M_\delta - M_w M_\delta \quad (16)$$

These gains are then substituted in equations B-31 and B-38 of reference 27 for estimating the variance of the elevator position and elevator position rate in cruise and approach. The turbulence is assumed to have a characteristic length of 760 meters (2500 feet) with an RMS gust level of .9 and 2.13 m/sec (3 and 7 ft/sec) in cruise and approach, respectively. These autopilot calculations are used to assign the following quantities in cruise and approach to available constraint functions: K_θ , K_θ^* , σ_δ and σ_δ^* . The constraint functions are used to insure that enough aerodynamic control exists to stabilize the airplane to excellent flying qualities and that enough hydraulic capability is available to prevent control surface rate saturation in heavy turbulence.

PROGRAM USE

A listing of the computer program set up to optimize seven design variables is included as Appendix I. Appendices II and III show sample input and output, respectively, for the program. Appendix IV contains a listing of a procedure file that will execute the program on the Langley Research Center computer system. As an aid in understanding the coding, a list of key program variables by routine and descriptions of their values are presented in Appendix V. Appendix VI is a compendium describing the variables in the common blocks.

The procedure file listed in Appendix IV contains a call to PPB, a program for executing a geometry preprocessor upon the output data placed on TAPE⁴ by subroutine XOUTPUT. This preprocessor puts on TAPE⁷ a data set suitable for executing ABS2290, an airplane graphics package described in reference 28. It is useful during conceptual design trade studies to see pictures of the configurations being generated. An example of this feature is shown in Figure 4.

Typically, with a case similar to the one contained in the appendices, approximately 500 function calls, or iterations, are required for a convergence of NELMIN. A function call averages about 1 second in execution time on the Langley Research Center Cyber 175.

If the user desired to add more design variables for the optimizer to iterate upon, these can be added as assignment statements beneath the transformation in SETUP (see Appendix I). Sample statements are left for adding cruise Mach number, wing sweep angle, wing thickness ratio and fuselage diameter as design variables. Usually all that is necessary to add an independent design variable is to equate it to a variable in the system of common blocks, which should contain degrees of freedom adequate for studies at the preliminary design level.

An array in the common block GEOM named PX has been included to aid in the study of certain changes representative of technological improvements. The specifics of its use are described in Appendix VI. For example, the following parameters could be studied during a design series: engine fuel efficiency, wing drag reduction, pitching moment reduction and structural efficiency.

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APPENDIX I - PROGRAM LISTING

```

PROGRAM SIMPACT(INPUT,OUTPUT,TAPE5=INPUT,TAPE6=OUTPUT,TAPE4)
*****
*   OPTIMIZATION COMMON BLOCKS   *
*****
COMMON /AVOID/FACT(59),GNORM(59)
COMMON /CONSTR/SU(59),SL(59),XINEQ(59)
COMMON /DEBUG/IDEBU, IDEBUG2
COMMON /FCOUNT/ICNT,JCNT,KCNT,NDAV,LCNT,IWT,NOIT
COMMON /LABELP/ARUN(8)
COMMON /PERF/UNAUG,SCF,NVAR,MINEQ
COMMON /STRAIN/ CON(59)
COMMON /VARIAB/AMP(15),AVE(15)
COMMON /VIOL/CAYY,MC,ILINE,IOUT
*****
*   DESIGN COMMON BLOCKS       *
*****
COMMON /DEVAR/DESIGN(15),ITERM(10),CST(10)
COMMON /DRAG/CDS(6),CDSAP(6)
COMMON /GEOM/W(20),HX(20),GX(35),PX(15)
COMMON /GRAVITY/CG(6)
COMMON /STAB/DERIVCR(15),DERIVAP(15),STOR(20)
COMMON /WTSVE/WTS(20)
*****
*   INPUT DATA               *
*****
REAL STEP(15),XMIN(15),XSEC(15)
REAL XBAR(15),XBARO(15)
REAL XL(15),XU(15)
READ(5,18) ARUN
18 FORMAT(8A10)
READ(5,*) NVAR,MINEQ
READ(5,*) (XBARO(I),I=1,NVAR)
IDEBU=0
IWT=0
IDEBU2=0
DO 19 J=1,NVAR
READ(5,*) JI,XL(J),XU(J)
AVE(J)=(XL(J)+XU(J))/2.0
AMP(J)=(XU(J)-XL(J))/2.0
19 CONTINUE
DO 20 I=1,MINEQ
20 READ(5,*) IJ,SL(I),SU(I)
WRITE(6,927) ARUN
927 FORMAT("1"/5X*RUN NO=*8A10/)
WRITE(6,718) NVAR,MINEQ
718 FORMAT(/10X*NO. OF VARIABLES=* I5/10X
$*NO. OF CONSTRAINTS=*I5)
WRITE(6,720) (XBARO(L),L=1,NVAR)

```

```

720 FORMAT(10X*VARIABLES=*4(T30,5F10.4/))
DO 24 J=1,NVAR
WRITE(6,22) J, XL(J),XU(J),AVE(J),AMP(J)
22 FORMAT(5X*J,XL,XU,AVE,AMP=*I5,4F15.4)
24 CONTINUE
DO 26 I=1,MINEQ
WRITE(6,928) I,SL(I),SU(I)
928 FORMAT(5X*I,SL(I),SU(I)=*I5,2F10.2)
FACT(I)=1.
XINEQ(I)=1.
IF(SL(I).EQ.-999.) FACT(I)=0.
GNORM(I)=(ABS(SU(I))+ABS(SL(I)))/2.0
26 CONTINUE
DO 27 I=1,NVAR
27 XBAR(I)=XBARO(I)
READ(5,*) NONEL
WRITE(6,39) NONEL
39 FORMAT(10X*NUMBER OF REQUESTED NELMINS=*I5)
READ(5,*) SCF,REQMIN,CAYY,STEP1,ILINE
CALL XINPUT
IOUT=0
ILINER=ILINE
ILINE=0
JCNT=0
*****
* START OPTIMIZATION *
*****
DO 1020 I=1,NONEL
DO 1000 K=1,NVAR
1000 STEP(K)=STEP1/I
CAYY=CAYY*10.
REQMIN=REQMIN/10
KCNT=0
WRITE(6,904) (XBAR(L),L=1,NVAR)
904 FORMAT(/10X*INITAIL XBAR*5(T35,5F12.4/))
XSIGN=1.
DO 915 IJ=1,NVAR
IF(ABS(XBAR(IJ)).LT.0.8) GO TO 915
XO=XBAR(IJ)
XSIGN=SIGN(XSIGN,XBAR(IJ))
DXB=ABS(XBAR(IJ))-1.
IF(DXB.GE.1..OR.DXB.EQ.0.) XBAR(IJ)=XBAR(IJ)/(ABS(XBAR(IJ))+.25)
IF(DXB.GT.0.0.AND.DXB.LT.1.0) XBAR(IJ)=XBAR(IJ)-XSIGN*DXB*2.
STEP(IJ)=SIGN(STEP(IJ),-XBAR(IJ))
WRITE(6,911) IJ,XO,XBAR(IJ),STEP(IJ),XSIGN
911 FORMAT(3X"--- RESET (VAR,XO,XBAR,STEP,XSIGN)="I5,4F12.4)
915 CONTINUE
WRITE(6,906) (STEP(L),L=1,NVAR)
906 FORMAT(10X*INITAIL STEPS*5(T35,5F12.4/))
WRITE(6,908) REQMIN,SCF,CAYY
908 FORMAT(10X*REQMIN,SCF,CAYY*T35,3E12.4)
*****
* START NELDER-MEAD SUBROUTINE *

```

```

*****
      ICOUNT=1500
      CALL NELMIN(NVAR,XBAR,XMIN,XSEC,YNEWLO,YSEC,REQMIN,STEP,
$ ICOUNT)
      WRITE(6,806)
806  FORMAT(/5X*/ // / NELMIN COMPLETE/ // /*/)
      WRITE(6,810) (XMIN(L),L=1,NVAR)
810  FORMAT(10X*XMIN=*3(T35,5F15.8/))
      WRITE(6,812) YNEWLO
812  FORMAT(10X*YNEWLO=*T35,E15.6)
      WRITE(6,814) ICOUNT,JCNT
814  FORMAT(10X*ICOUNT=*T35,I5/10X*TOT. FUNCTION CALLS=*T35,I5/)
      XIWT=IWT
      XJCNT=JCNT
      RATWT=XIWT/XJCNT
      WRITE(6,830) XIWT,RATWT
830  FORMAT(/10X,22HTOT. WEIGHT ITERATIONS,T35,F12.2/
$ 10X,28HAVE. WT. ITERATIONS PER CALL,T35,F12.3)
      DO 1010 K=1,NVAR
1010 XBAR(K)=XMIN(K)*1.0
      IOUT=1
      ILINE=0
      IOUT=0
      ILINE=ILINER
*****
*      THE FOLLOWING STATEMENTS CAN BE USED TO FIND THE GRADIENTS      *
*      AT THE OPTIMAL SOLUTION POINT:                                  *
*                                                                      *
*          DX=1.0E-5                                                  *
*          DO 610 JI=1,NVAR                                           *
*          IDX=0                                                       *
*          603 DO 605 J=1,NVAR                                         *
*          XBARO(J)=XMIN(J)                                           *
*          IF(J.EQ.JI) XBARO(J)=XMIN(J)+DX                            *
*          605 CONTINUE                                               *
*          VAL=FN(XBARO)                                               *
*          FX(JI)=(VAL-ORIG)/DX                                         *
*          IF(FX(JI).LT.1.0E4) GO TO 610                               *
*          IF(IDX.GT.0) GO TO 610                                       *
*          IDX=1                                                       *
*          DX=-DX                                                       *
*          GO TO 603                                                    *
*          610 CONTINUE                                                *
*          DO 620 JJI=1,NVAR                                           *
*          WRITE(6,607) JJI,FX(JJI)                                    *
*          607 FORMAT(10X*DERIVATIVE WITH RESPECT TO VARIABLE NO.*  *
*          $ I5,10X,E15.5)                                             *
*          620 CONTINUE                                               *
*****
1020 CONTINUE
      CALL XOUTPUT(4)
      WRITE(6,810) (XMIN(L),L=1,NVAR)
      STOP

```

```

END
SUBROUTINE NELMIN(N,START,XMIN,XSEC,YNEWLO,
1YSEC,REQMIN,STEP,ICOUNT)
  REAL START(N),STEP(N),XMIN(N),
  1XSEC(N),YNEWLO,YSEC,REQMIN,P(20,21),PSTAR(20),
  2P2STAR(20),PBAR(20),Y(20),DN,Z,YLO,RCOEFF,
  3YSTAR,ECOEFF,Y2STAR,CCOEFF,FN,DABIT,DCHK,
  4COORD1,COORD2
  DATA RCOEFF/1.0/,ECOEFF/2.0/,CCOEFF/0.5/
  DATA PSTAR,P2STAR,PBAR /60*0./
  KCOUNT=ICOUNT
  ICOUNT=0
  IF( REQMIN .LE. 0.) ICOUNT=ICOUNT-1
  IF(N .LE. 0) ICOUNT=ICOUNT-10
  IF(N .GT. 20 ) ICOUNT=ICOUNT-10
  IF(ICOUNT .LT. 0) RETURN
  DABIT=2.04607E-35
  BIGNUM=1.0E38
  KONVGE=5
  XN=FLOAT(N)
  DN=DBLE(XN)
  NN=N+1
*****
*   CONSTRUCTION OF INITIAL SIMPLEX   *
*****
  DO 1 I=1,N
  1 P(I,NN)=START(I)
  Y(NN)=FN(START)
  ICOUNT=ICOUNT+1
  DO 2 J=1,N
  DCHK=START(J)
  START(J)=DCHK+STEP(J)
  DO 3 I=1,N
  3 P(I,J)=START(I)
  Y(J)=FN(START)
  ICOUNT=ICOUNT+1
  2 START(J) =DCHK
*****
*   SIMPLEX CONSTRUCTION COMPLETE   *
*
*   FIND HIGHEST AND LOWEST Y VALUES
*
*   YNEWLO (Y(IHI)) INDICATES THE VERTEX OF THE SIMPLEX TO BE
*   REPLACED.
*****
  1000 YLO=Y(1)
  YNEWLO=YLO
  ILO=1
  IHI=1
  DO 5 I=2,NN
  IF(Y(I) .GE. YLO) GO TO 4
  YLO=Y(I)
  ILO=I

```



```

4 IF(Y(I) .LE. YNEWLO) GO TO 5
  YNEWLO=Y(I)
  IHI=I
5 CONTINUE
*****
*   PERFORM CONVERGENCE CHECKS ON FUNCTION   *
*****
  DCHK=(YNEWLO+DABIT)/(YLO+DABIT)-1.
  IF(ABS(DCHK) .LT. REQMIN) GO TO 900
  KONVGE=KONVGE-1
  IF(KONVGE .NE. 0) GO TO 2020
  KONVGE=5
*****
*   CHECK CONVERGENCE OF COORDINATES ONLY EVERY 5 SIMPLEXES   *
*****
  DO 2015 I=1,N
  COORD1=P(I,1)
  COORD2=COORD1
  DO 2010 J=2,NN
  IF(P(I,J) .GE. COORD1) GO TO 2005
  COORD1=P(I,J)
2005 IF(P(I,J) .LE. COORD2) GO TO 2010
  COORD2=P(I,J)
2010 CONTINUE
  DCHK=(COORD2+DABIT)/(COORD1+DABIT)-1.
  IF(ABS(DCHK) .GT. REQMIN) GO TO 2020
2015 CONTINUE
  GO TO 900
2020 IF(ICOUNT .GE. KCOUNT) GO TO 900
*****
*   CALCULATE PBAR, THE CENTROID OF THE SIMPLEX VERTICES EXCEPTING   *
*   THAT WITH Y VALUE YNEWLO.   *
*****
  DO 7 I=1,N
  Z=0.0
  DO 6 J=1,NN
  Z=Z+P(I,J)
  Z=Z-P(I,IHI)
  7 PBAR(I)=Z/DN
*****
*   REFLECTION THROUGH THE CENTROID   *
*****
  DO 8 I=1,N
  8 PSTAR(I)=(1.0+RCOEFF)*PBAR(I)-RCOEFF*P(I,IHI)
  YSTAR=FN(PSTAR)
  ICOUNT=ICOUNT+1
  IF(YSTAR .GE. YLO) GO TO 12
  IF(ICOUNT .GE. KCOUNT) GO TO 19
*****
*   SUCCESSFUL REFLECTION, SO EXTENSION   *
*****
  DO 9 I=1,N
  9 P2STAR(I)=ECOEFF*PSTAR(I)+(1.0-ECOEFF)*PBAR(I)

```

```

Y2STAR=FN(P2STAR)
ICOUNT=ICOUNT+1
*****
*      RETAIN EXTENSION OR CONTRACTION      *
*****
      IF(Y2STAR .GE. YSTAR) GO TO 19
10 DO 11 I=1,N
11 P(I,IHI)=P2STAR(I)
    Y(IHI)=Y2STAR
    GO TO 1000
*****
*      NO EXTENSION      *
*****
12 L=0
   DO 13 I=1,NN
   IF(Y(I) .GT. YSTAR) L=L+1
13 CONTINUE
   IF(L .GT. 1) GO TO 19
   IF(L .EQ. 0) GO TO 15
*****
*      CONTRACTION ON THE REFLECTION SIDE OF THE CENTROID      *
*****
   DO 14 I=1,N
14 P(I,IHI)=PSTAR(I)
   Y(IHI)=YSTAR
*****
*      CONTRACTION ON THE Y(IHI) SIDE OF THE CENTROID      *
*****
15 IF(ICOUNT .GE. KCOUNT) GO TO 900
   DO 16 I=1,N
16 P2STAR(I)=CCOEFF*P(I,IHI)+(1.0-CCOEFF)*PBAR(I)
   Y2STAR=FN(P2STAR)
   ICOUNT=ICOUNT+1
   IF(Y2STAR .LT. Y(IHI)) GO TO 10
*****
*      CONTRACT THE WHOLE SIMPLEX      *
*****
   DO 18 J=1,NN
   DO 17 I=1,N
   P(I,J)=(P(I,J)+P(I,ILO))*0.5
17 XMIN(I)=P(I,J)
   Y(J)=FN(XMIN)
18 CONTINUE
   ICOUNT=ICOUNT+NN
   IF(ICOUNT .LT. KCOUNT) GO TO 1000
   GO TO 900
*****
*      RETAIN REFLECTION      *
*****
19 CONTINUE
   DO 20 I=1,N
20 P(I,IHI)=PSTAR(I)
   Y(IHI)=YSTAR

```

```

      GO TO 1000
*****
*      SELECT THE TWO BEST FUNCTION VALUES (YNEWLO AND YSEC) AND THEIR *
*      COORDS. (XMIN AND XSEC) . *
*****
900 DO 23 J=1,NN
      DO 22 I=1,N
22  XMIN(I)=P(I,J)
      Y(J)=FN(XMIN)
23  CONTINUE
      YNEWLO=BIGNUM
      DO 24 J=1,NN
      IF(Y(J) .GE. YNEWLO) GO TO 24
      YNEWLO=Y(J)
      IBEST=J
24  CONTINUE
      Y(IBEST)=BIGNUM
      YSEC=BIGNUM
      DO 25 J=1,NN
      IF(Y(J) .GE. YSEC) GO TO 25
      YSEC=Y(J)
      ISEC=J
25  CONTINUE
      DO 26 I=1,N
      XMIN(I)=P(I,IBEST)
      XSEC(I)=P(I,ISEC)
26  CONTINUE
      RETURN
      END
      FUNCTION FN(XBAR)
      COMMON /VIOL/CAYY,MC,ILINE,IOUT
      COMMON /FCOUNT/ICNT,JCNT,KCNT,NDAV,LCNT,IWT,NOIT
      REAL XBAR(15)
      CALL SETUP(XBAR,IOUT,OBJ)
      FN=OBJ
      IF(ILINE.GT.0) WRITE(6,50) JCNT,FN,MC,IWT,NOIT
50  FORMAT(10X,"CALL NUMBER=",I5,5X"OBJ="E15.8,10X
      $ ,"NO. VIOLATIONS="I5,5X
      $ ,"IWT=",I5,5X,"NOIT="I5)
      RETURN
      END
      SUBROUTINE SETUP(GAINS,IPR,OBJ)
      INTEGER OUTPUT
      REAL GAINS(15),GBAR(59)
      COMMON /STRAIN/CON(59)
      COMMON /VARIAB/AMP(15),AVE(15)
      COMMON /VIOL/CAYY,MC,ILINE,IOUT
      COMMON /CONSTR/SU(59),SL(59),XINEQ(59)
      COMMON /DEVAR/DESIGN(15),ITERM(10),CST(10)
      COMMON /GEOM/W(20),HX(20),GX(35),PX(15)
      COMMON /PERF/UNAUG,SCF,NVAR,MINEQ
      COMMON /AVOID/FACT(59),GNORM(59)
      DO 22 I=1,NVAR

```

DESIGN(I)=AMP(I)*SIN(1.5707963*GAINS(I))+AVE(I)

22 CONTINUE

* TO DEFINE ADDITIONAL DESIGN VARIABLES, INSERT DEFINITION CARDS *
* HERE. SAMPLES ARE GIVEN BELOW: *

* GX(3)=DESIGN(8) ---DESIGN(8) IS MACH NUMBER *
* W(1)=DESIGN(9) ---DESIGN(9) IS WING SWEEP *
* W(4)=DESIGN(10) ---DESIGN(10) IS WING THICKNESS RATIO *
* W(3)=DESIGN(11) ---DESIGN(11) IS WING TAPER RATIO *
* GX(5)=DESIGN(12) ---DESIGN(12) IS FUSELAGE DIAMETER *

* ALSO, VARIOUS DESIGN CONSTRAINTS CAN BE ADDED. FOR EXAMPLE, *
* ADDING THE STATEMENT: *

* GX(32)=W(1) *
* RESTRICTS THE HORIZONTAL TAIL SWEEP ANGLE TO BE *
* EQUAL TO THE WING SWEEP ANGLE. *

IF(PX(5).GT.0) DESIGN(6)=GX(21)*ITERM(4)
IF(IPR.GT.0) WRITE(6,441) DESIGN
441 FORMAT(/15X*SET-UP*/20X*DESIGN=*5(T40,5F15.4/))
OUTPUT=0
CALL DOCOST(COST,0)
CALL CNSTRN(0)
UNAU= COST*SCF
IF(IPR.GT.0) WRITE(6,442) UNAU
442 FORMAT(20X*CALL TO DOC/CNSTRN COMPLETE---DOC= \$*E15.5)

* THIS SECTION CALCULATES GBAR ARRAY *
* AND THE PENALTY FOR VIOLATIONS *

MC=0
PENT=0.
DO 150 I=1,MINEQ
T=CON(I)
XINEQ(I)=0.
GBAR(I)=AMAX1(T-SU(I),SL(I)-T)
GBAR(I)=GBAR(I)*FACT(I)/GNORM(I)
IF(GBAR(I).LE.0.0) GO TO 150
XINEQ(I)=1.
MC=MC+1
PENT=PENT+CAYY*GBAR(I)*GBAR(I)

150 CONTINUE

IF(IPR.GT.0) WRITE(6,160) PENT

160 FORMAT(20X*PENALTY TERM=*E15.5)

* AUGMENTED FUNCTION IS CREATED *

OBJ=UNAU+PENT
RETURN
END
SUBROUTINE XOUTPUT(IPRNT)

```

COMMON /CONSTR/SU(59),SL(59),XINEQ(59)
COMMON /DEVAR/DESIGN(15),ITERM(10),CST(10)
COMMON /DRAG/CDS(6),CDSAP(6)
COMMON /GEOM/W(20),HX(20),GX(35),PX(15)
COMMON /GRAVITY/CG(6)
COMMON /LABELP/ARUN(8)
COMMON /STAB/DERIVCR(15),DERIVAP(15),STOR(20)
COMMON /WTSVE/WTS(20)
*****
*   PRINT OUT PARTS OF THE FUNCTION EVALUATION                               *
*                                                                                   *
*   0=NONE,1=DOC,2=CNSTRN,3=DOC & CNSTRN,4=DOC & CNSTRN & DUMP                *
*   5=DOC(2) & CNSTRN(2),6=COMMON DUMP                                          *
*****
      IDUMP=0
      IF(IPRNT.LT.1) GO TO 999
      IF(IPRNT.EQ.1) GO TO 10
      IF(IPRNT.EQ.2) GO TO 20
      IF(IPRNT.EQ.3) GO TO 30
      IF(IPRNT.EQ.4) GO TO 40
      IF(IPRNT.EQ.5) GO TO 50
      IF(IPRNT.EQ.6) GO TO 70
10  IDOC=1
    ICRN=0
    GO TO 80
20  ICRN=1
    IDOC=0
    GO TO 80
30  IDOC=1
    ICRN=1
    GO TO 80
40  IDOC=1
    ICRN=1
    IDUMP=1
    GO TO 80
50  IDOC=2
    ICRN=2
    IDUMP=0
80  CALL DOCOST(TERM, IDOC)
    CALL CNSTRN(ICRN)
    IF(IDUMP.LT.1) GO TO 999
70  WRITE(6,1010)
1010 FORMAT(*1*30X*COMMON DUMP*///)
    WRITE(6,1012) DESIGN
1012 FORMAT(/15X*DESIGN=*3(T30,5F15.5/))
    WRITE(6,1014) ITERM
1014 FORMAT(/15X*ITERM=*3(T30,5I15/))
    WRITE(6,1016) PX
1016 FORMAT(/15X"PX=",3(T30,5F15.4/))
    WRITE(6,1015) CDS
1015 FORMAT(15X*CDS=*T30,6F15.9/)
    WRITE(6,1020) CDSAP
1020 FORMAT(/15X*CDSAP=*T30,6F15.9/)

```

```

WRITE(6,1025) W
1025 FORMAT(/15X*W=*5(T30,5F15.9/))
WRITE(6,1030) HX
1030 FORMAT(/15X*HX=*5(T30,5F15.9/))
WRITE(6,1035) GX
1035 FORMAT(/15X*GX=*8(T30,5F15.9/))
WRITE(6,1040) CG
1040 FORMAT(/15X*CG=*T30,6F15.5)
WRITE(6,1045) DERIVCR
1045 FORMAT(/15X*DERIVCR=*5(T30,5F15.9/))
WRITE(6,1050) DERIVAP
1050 FORMAT(/15X*DERIVAP=*5(T30,5F15.9/))
WRITE(6,1055) STOR
1055 FORMAT(/15X*STOR=*5(T30,5F15.9/))
WRITE(6,1060) WTS
1060 FORMAT(/15X*WTS=*5(T30,5F15.3/))
WRITE(6,1070) CST
1070 FORMAT(/15X"CST="5(T30,5F15.3/))
WRITE(4,1200) ARUN
1200 FORMAT(8A10)

```

```

*****
*   WRITE AN OUTPUT TAPE FOR THE PLOTTING PREPROCESSOR   *
*****

```

```

WRITE(4,*) DESIGN
WRITE(4,*) ITERM
WRITE(4,*) W
WRITE(4,*) HX
WRITE(4,*) GX

```

```

999 RETURN
END

```

```

SUBROUTINE XINPUT
COMMON /DEVAR/DESIGN(15),ITERM(10),CST(10)
COMMON /GEOM/W(20),HX(20),GX(35),PX(15)
COMMON /GRAVITY/CG(6)
COMMON /WTSVE/WTS(20)

```

```

*****
*   INPUT DESIGN CONSTANTS   *
*****

```

```

DATA GX/35*0./
READ(5,*) WTS(1)
READ(5,*) (PX(J),J=1,8)
READ(5,*) (ITERM(I),I=1,10)
READ(5,*) WTS(16),CG(5)
READ(5,*) W(1),W(2),W(3),W(4),W(5)
READ(5,*) W(6),W(7),W(8),W(14),W(16)
READ(5,*) W(17),W(18),W(19),W(20)
READ(5,*) HX(1),HX(2),HX(3),HX(10)
READ(5,*) HX(16),HX(17),HX(18),HX(19),HX(20)
READ(5,*) GX(3),GX(4),GX(5),GX(6),GX(7)
READ(5,*) GX(8),GX(11),GX(12),GX(17),GX(18)
READ(5,*) GX(19),GX(20),GX(21),GX(22)
READ(5,*) GX(23),GX(24),GX(25),GX(26),GX(27)
READ(5,*) GX(32),GX(34),GX(16)

```

```

*****
*   WRITE OUT DATA   *
*****
    WRITE(6,100)
100 FORMAT(*1*///30X*/ / / FUNCTION INPUT/ / / *//)
    WRITE(6,110) WTS(1)
110 FORMAT(10X*WTS(1)*T40,F15.4)
    WRITE(6,120) ITERM
120 FORMAT(10X*ITERM*T40,10I6)
    WRITE(6,125) PX
125 FORMAT(10X,"PX=",3(T40,5F15.4/))
    WRITE(6,130) WTS(16)
130 FORMAT(10X*WTS(16)*T40,F15.4)
    WRITE(6,140) W(1),W(2),W(3),W(4),W(5)
140 FORMAT(10X*W...1-5=*T40,5F15.4)
    WRITE(6,150) W(6),W(7),W(8),W(14),W(16)
150 FORMAT(10X*W...6-8,14,16=*T40,5F15.4)
    WRITE(6,160) W(17),W(18),W(19),W(20)
160 FORMAT(10X*W...17-20=*T40,4F15.4)
    WRITE(6,170) HX(1),HX(2),HX(3),HX(10)
170 FORMAT(10X*HX...1-3,10=*T40,4F15.4)
    WRITE(6,175) HX(16),HX(17),HX(18),HX(19),HX(20)
175 FORMAT(10X*HX...16-20=*T40,5F15.4)
    WRITE(6,180) GX(3),GX(4),GX(5),GX(6),GX(7)
180 FORMAT(10X*GX...3-7=*T40,5F15.4)
    WRITE(6,190) GX(8),GX(11),GX(12),GX(17),GX(18)
190 FORMAT(10X*GX...8,11-12,17,18=*T40,5F15.4)
    WRITE(6,200) GX(19),GX(20),GX(21),GX(22)
200 FORMAT(10X*GX...19-22=*T40,4F15.4)
    WRITE(6,210) GX(23),GX(24),GX(25),GX(26),GX(27)
210 FORMAT(10X*GX...23-27=*T40,5F15.4)
    WRITE(6,220) GX(32),GX(34)
220 FORMAT(10X*GX...32,34=*T40,2F15.4)
    RETURN
    END
    SUBROUTINE DOCOST(UNAug,OUTPUT)
    INTEGER OUTPUT
    REAL INSUR,PER(12),XIOC(12),YIOC(12),YCOST(9)
    COMMON /DEVAR/DESIGN(15),ITERM(10),CST(10)
    COMMON /FCOUNT/ICNT,JCNT,KCNT,NDAV,LCNT,IWT,NOIT
    COMMON /GEOM/W(20),HX(20),GX(35),PX(15)
    COMMON /WTSVE/WTS(20)
*****
*   INITIALIZE GEOMETRY AND C.G.   *
*****
    CALL GEO
    CALL CGCAL
*****
*   INITIALIZE AND INCREMENT COUNTERS   *
*****
    DATA JCNT/0/
    JCNT=JCNT+1
    KCNT=KCNT+1

```

```

IF(OUTPUT.GE.1) GO TO 10
*****
*   COSTS PER BLOCK HOUR OF DESIGN FLIGHT   *
*****
  20 IOUT=OUTPUT
    IF(OUTPUT.GT.1) IOUT=0
    CALL WEIGHT(IOUT)
    CALL AIRCOST(PRICE,IOUT)
    YRMULT=1.07** (ITERM(6)-1976)
    PRICE=YRMULT*PRICE
    FL=WTS(18)
    BLKHR=WTS(19)
*****
*   DIRECT OPERATING COSTS   *
*****
    DEPRE=0.88*PRICE/(14.0*GX(26))
    SUPPORT=0.12*PRICE/(14.0*GX(26))
    SPARES=0.06*PRICE/(14.0*GX(26))
    DELAY=YRMULT*8.40
    INSUR=0.01*PRICE/(GX(26))
    FCOST=WTS(20)*WTS(16)/6.4
    FCOST=FCOST/BLKHR
    CALL MAINCST(XMCOST,IOUT)
    WTL=WTS(5)*0.453592
    FEELAND=YRMULT*1.54*WTL/1000.0
    FEELAND=FEELAND/BLKHR
    ATT=YRMULT*GX(19)*(0.691*FL+0.00175*FL*FL)
    ATT=ATT/BLKHR
    CREW=YRMULT*174*FL+43.5+(0.452*FL+.11299)*(WTS(1)*.453592/1000.)
    CREW=CREW/BLKHR
    SERVICE=YRMULT*63.0
    CONTROL=YRMULT*82.58/BLKHR
    DOC=DEPRE+SUPPORT+SPARES+DELAY+INSUR+FCOST+FEELAND+SERVICE
    $+ATT+CREW+XMCOST+CONTROL
*****
*   PERCENT OF TOTAL   *
*****
    PER(1)=DEPRE/DOC
    PER(2)=SUPPORT/DOC
    PER(3)=SPARES/DOC
    PER(4)=DELAY/DOC
    PER(5)=INSUR/DOC
    PER(6)=FCOST/DOC
    PER(7)=XMCOST/DOC
    PER(8)=FEELAND/DOC
    PER(9)=CREW/DOC
    PER(10)=ATT/DOC
    PER(11)=SERVICE/DOC
    PER(12)=CONTROL/DOC
    DO 30 J=1,12
  30 PER(J)=PER(J)*100.
    TOT=100.
*****

```


* INDIRECT OPERATING COSTS PER BLOCK HOUR OF DESIGN FLIGHT *

 DATA YIOC/10HMAIN BURDN, 9HFOOD COST, 5HMOVIE, 8HPASS INS,
 \$ 9HMISC PASS, 9HADVERTISE, 10HCOMMISSION, 5HRESER,
 \$ 9HPASS HDLG, 8HBAG HDLG, 10HCARGO HDLG, 9HSERVICING/
 XIOC(1)=XMCOST*1.05
 IFIRS=.15*GX(19)*GX(24)
 IECON=GX(19)*GX(24)-IFIRS
 XIOC(2)=(IFIRS*2.42+IECON*1.05)
 XIOC(3)=196./BLKHR
 RPM=GX(19)*GX(24)*GX(4)/1000.
 XIOC(4)=0.52*RPM/BLKHR
 XIOC(5)=GX(19)*.18/BLKHR
 REVYR=GX(25)*GX(19)*GX(24)*GX(26)*GX(4)/BLKHR
 REVHR=REVYR/GX(26)
 XIOC(6)=.023*REVHR
 XIOC(7)=2.35*RPM/BLKHR
 PASSPHR=GX(19)*GX(24)/BLKHR
 XIOC(8)=4.40*PASSPHR
 XIOC(9)=2.87*PASSPHR
 XIOC(10)=1.31*PASSPHR
 TONCAR=GX(22)/2000.
 XIOC(11)=131.08*TONCAR/BLKHR
 XIOC(12)=(0.03*9.5+0.0025)*GX(19)/BLKHR
 TOTIOC=0.
 XIOC(1)=XIOC(1)/YRMULT
 XIOC(6)=XIOC(6)/YRMULT
 DO 200 I=1,12
 XIOC(I)=XIOC(I)*YRMULT
 TOTIOC=TOTIOC+XIOC(I)

200 CONTINUE

* RETURN ON INVESTMENT CALCULATIONS *

XINVEST=0.9*PRICE
 TAXRT=0.48
 COSTHR=DOC+TOTIOC
 PROFIT=(REVHR-COSTHR)*GX(26)
 ROI=(1.-TAXRT)*PROFIT/XINVEST
 FARROI=(.26*PRICE+COSTHR*GX(26))*(BLKHR/(GX(19)*GX(24)*GX(26)
 \$ *GX(4)))

* ASSIGN PERFORMANCE INDEX *

CST(1)=DOC
 CST(2)=DOC*BLKHR
 CST(3)=ROI
 CST(4)=FARROI
 CST(7)=WTS(1)
 INCPH=COSTHR+.15*XINVEST/(GX(26)*(1.-TAXRT))
 INCPF=INCPH*BLKHR
 CST(8)=INCPF
 CST(9)=PRICE

```

UNAUG=CST(ITERM(5))
GO TO 40
*****
*   OUTPUT SECTION   *
*****
10 WRITE(6,42)
   WRITE(6,44) (DESIGN(JK),JK=1,12)
   IF(OUTPUT.GT.1) GO TO 20
   WRITE(6,705)
705 FORMAT(/5X*INPUT CONSTANTS*/)
   WRITE(6,710) (W(J),J=1,8)
710 FORMAT(10X*WING...SWEEP,INCIDENCE,TAPER RATIO:*T55,3F12.4/
$ 10X*THICKNESS,TWIST,E1,E2,DESIGN CL:*T55,5F12.4)
   WRITE(6,720) W(14),W(19),W(17),W(18),W(16),GX(17),GX(18)
720 FORMAT(10X*CM(CR,APP)*T55,2F12.4/
$ 10X*DELTA CM(10,25 DEGREES FLAP):*T55,2F12.4/
$ 10X*ANGLE OF ZERO LIFT(0,10,45 DEGREES FLAP):*T55,3F12.4)
   WRITE(6,730) W(20),GX(11),GX(5),GX(8),GX(12)
730 FORMAT(10X*DELTA CD (10-45 DEGREES FLAP):*T55,F12.4/
$ 10X*TURBULENCE LENGTH/ROOT 3,FUSE. DIA.:*T55,2F12.4/
$10X*CL-MAX(TO),CL-MAX(L):*T55,2F12.4)
   WRITE(6,740) GX(3),GX(4),GX(19),GX(22),GX(23),GX(27)
740 FORMAT(10X*MISSION...MACH NO.,RANGE,NO. PASS:*T55,3F12.4/
$ 10X*CARGO WEIGHT:*T55,F12.4/
$ 10X*DELTA CG, WTL(MAX)/WTO:*T55,3F12.4)
   WRITE(6,750) GX(6),GX(7),GX(20),GX(21)
750 FORMAT(10X*ENGINE...L,W,WT,TREF:*T55,4F12.4)
   WRITE(6,760) HX(1),HX(2),HX(3),HX(10),GX(24),GX(25),GX(26)
760 FORMAT(10X*TAIL...TAPER RATIO,THICKNESS,ELE EFF:*T55,3F12.4/
$ 10X*ELEVATOR TIME CONSTANT:*T55,F12.4/
$ 10X*ECONOMICS...LOAD FACT,$/SEAT MI,BLK HR/YR:*T55,3F12.4)
   WRITE(6,770) W(9),W(10),HX(4),HX(5),HX(6),GX(32)
770 FORMAT(/5X*SOME GEOMETRY CALCULATIONS*/
$ 10X*WING...SPAN,CMAC:*T55,2F12.4/
$ 10X*TAIL...SPAN,CMAC,VBAR,SWEEP*T55,4F12.4)
   WRITE(6,780) HX(16),HX(17),HX(18),HX(19),HX(20),GX(35)
780 FORMAT(10X*VERT. TAIL...VBAR,TAPER,AR,SWEEP,SR/SV,SV:*
$ T55,6F12.4)
   GO TO 20
40 IF(OUTPUT.LT.1) GO TO 100
   IF(OUTPUT.GT.1) GO TO 549
42 FORMAT(*1*//30X*AIRCRAFT SIZING PROGRAM*//)
44 FORMAT(5X*DESIGN VARIABLES*/10X*WING AREA (FTXX2)=*
$T40,F15.4/10X*WING ASPECT RATIO=*T40,F15.4/10X
$*FUSELAGE LENGTH (FT)=*T40,F15.4/10X
$*HOR. TAIL AREA (FTXX2)=*T40,F15.4/10X
$*HOR. TAIL ASPECT RATIO=*T40,F15.4/10X
$*TOTAL THRUST (LBS)=*T40,F15.4/10X"AFT MOST CG="T40,F15.4/
$ 10X"CRUISE MACH NO.="T40,F15.4/10X"SWEEP="T40,F15.4/10X
$ "WING T/C="T40,F15.4/10X"WING TAPER RATIO="T40,F15.4/
$ 10X,"FUSE. DIA="T40,F15.4)
   WRITE(6,52)
52 FORMAT(*1*//30X*DIRECT OPERATING COSTS--DOLLARS/FLT. HOUR*)

```

```

WRITE(6,54) DEPRE,PER(1),SUPPORT,PER(2),SPARES,PER(3),DELAY,
$ PER(4),INSUR,PER(5),FCOST,PER(6),XMCOST,PER(7),FEELAND,PER(8),
$ CREW,PER(9),ATT,PER(10),SERVICE,PER(11),CONTROL,PER(12)
54 FORMAT(/10X*DEPREC*T40,2F10.2/10X*SUPPORT*T40,2F10.2/10X*SPARES*
$T40,
$2F10.2/10X*DELAY*T40,2F10.2/10X*INSURANCE*T40,2F10.2/10X*FUEL*T40,
$2F10.2/10X*MAINTENANCE*T40,2F10.2/10X*LANDING FEE*T40,2F10.2/10X
$*CREW*T40,2F10.2/10X*ATTENDANTS*T40,2F10.2/10X*FUEL SERVICE*
$ T40,2F10.2/
$10X*CONTROL*T40,2F10.2)
WRITE(6,56) DOC,TOT
56 FORMAT(/3X*TOTAL DIRECT OPERATING COSTS*T40*$*F9.2,F10.2)
WRITE(6,150)
150 FORMAT(/30X*INDIRECT OPERATING COSTS--DOLLARS/FLT. HOUR*///)
DO 300 I=1,12
PER(I)=100.0*XIOC(I)/TOTIOC
WRITE(6,152) YIOC(I),XIOC(I),PER(I)
152 FORMAT(10X,A10,T40,2F10.2)
300 CONTINUE
WRITE(6,154) TOTIOC,TOT
154 FORMAT(/5X*TOTAL INDIRECT OPERATING COSTS*T40,2F10.2/)
549 WRITE(6,550) REVHR,COSTHR,ROI
550 FORMAT(*1*///30X*PERFORMANCE FUNCTION SUMMARY*///
$ 10X*REVENUE PER BLOCK HOUR*T50,F12.2/
$ 10X*TOTAL COST PER BLOCK HOUR*T50,F12.2/
$ 10X*RETURN ON INVESTMENT*T50,F12.4///)
DATA YCOST/6HDOC/HR,7HDOC/FLT,3HROI,4HFARE,10HSEAT-MI/GA,
$ 8HL/D(MAX),5HMTGW,4HFARE,5HPRICE/
DO 570 I=1,9
WRITE(6,560) I, YCOST(I),CST(I)
560 FORMAT(10X,I5,2X,A10,F12.3)
570 CONTINUE
100 RETURN
END
SUBROUTINE CGCAL
COMMON /DEVAR/DESIGN(15),ITRM(10),CST(10)
COMMON /GEOM/W(20),HX(20),GX(35),PX(15)
COMMON /STAB/DERIVCR(15),DERIVAP(15),STOR(20)
COMMON /GRAVITY/ CG(5)
*****
* ASSIGN CG POSITIONS *
* (1) AFT-CRUISE *
* (2) AFT-APPROACH *
* (3) FWD-CRUISE *
* (4) FWD-APPROACH *
*****
CG(1)=DESIGN(7)
CG(2)=CG(1)
CG(3)=CG(1)-GX(23)/W(10)
CG(4)=CG(2)-GX(23)/W(10)
DATA CG(6)/.18/
C
C ALLOW FREE GEAR LOCATION

```

C

```
IF (ITERM(7).GT.0.) CG(5)=CG(1)-CG(6)
RETURN
END
SUBROUTINE GEO
COMMON /DEVAR/DESIGN(15),ITERM(10),CST(10)
COMMON /GEOM/W(20),HX(20),GX(35),PX(15)
*****
* WING CONSTANTS OR COMMON VARIABLES *
*****
W(9)=(DESIGN(1)*DESIGN(2))**0.5
W(10)=4.*DESIGN(1)*(1.+W(3)+W(3)*W(3))/
$(3.*W(9)*(1.+W(3))**2.0)
W(11)=TAN(W(1)/GX(2))
W(12)=.496+0.45/DESIGN(2)
W(13)=W(12)-.9/DESIGN(2)
W(15)=COS(W(1)/GX(2))
*****
* HORIZONTAL TAIL CONSTANTS OR COMMON VARIABLES *
*****
HX(4)=(DESIGN(4)*DESIGN(5))**0.5
HX(5)=4.*DESIGN(4)*(1.+HX(1)+HX(1)*HX(1))/
$(3.*HX(4)*(1.+HX(1))**2.0)
XTXLT=0.45
IF (ITERM(4).EQ.3) XTXLT=0.43
XLT=XTXLT*DESIGN(3)
GX(33)=XLT
HX(6)=DESIGN(4)*XLT/(DESIGN(1)*W(10))
HX(7)=TAN(GX(32)/GX(2))
T=(1.-HX(1))/(4.*(1.+HX(1)))
HX(8)=HX(7)+4.*T/DESIGN(5)
HX(9)=HX(8)-2.*(1.-HX(1))/(DESIGN(5)*(1+HX(1)))
*****
* MISC. CONSTANTS OR COMMON VARIABLES *
*****
DATA GX(1),GX(2)/3.14159265,57.295779/
DATA HX(15),GX(13),GX(31)/0.,0.,0./
DATA GX(15)/32.174/
GX(35)=HX(16)*W(9)*DESIGN(1)/(XLT*0.95)
RETURN
END
SUBROUTINE WEIGHT(OUTPUT)
REAL LT,F1(2),F2(2),ANS(4),DWTA(41)
COMMON /DEBUG/IDEBU,IDEBUG2
COMMON /FCOUNT/ICNT,JCNT,KCNT,NDAV,LCNT,IWT,NOIT
COMMON /DEVAR/DESIGN(15),ITERM(10),CST(10)
COMMON /DRAG/CDS(6),CDSAP(6)
COMMON /GEOM/W(20),HX(20),GX(35),PX(15)
COMMON /WTSVE/WTS(20)
INTEGER OUTPUT
DATA WFOWTO/.26/
DO 20 I=1,41
20 DWTA(I)=0.
```

```

*****
*      FUDGE IS A FACTOR FOR WEIGHT OVERRUNS      *
*****
      FUDGE=1.05
      IF (IDEBUG.GT.0) WRITE(6,337)
      337 FORMAT(*1*/20X*WEIGHT ITERATION LOOPS*)
*****
*      SOME GEOMETRY DEFINITIONS      *
*****
      IACT=ITERM(1)
      ICGX=ITERM(2)
      AR=DESIGN(2)
      LT=DESIGN(1)*W(10)*HX(6)/DESIGN(4)
      SHT=DESIGN(4)
      TRV=HX(17)
      SVT=HX(16)*W(9)*DESIGN(1)/LT
      TENG=DESIGN(6)/ITERM(4)
      NOIT=0
      DELWTO=20.
      DIV=1.
      WTO=WTS(1)
      WTINIT=WTO
      WTFUEL=WTO*WFOWTO
      FUEL=WTFUEL/6.4
      WTENG=FUDGE*(TENG/GX(21))*GX(20)*ITERM(4)
      WTS(7)=WTS(1)/(GX(15)*0.000889*W(10)*DESIGN(1))
      WTS(9)=(WTS(1)-WTFUEL)/(GX(15)*0.002378*W(10)*DESIGN(1))
*****
*      THIS SECTION CALCULATES WTS. INDEPENDENT OF WTO AND FUEL      *
*****
      F1(1)=1.
      F1(2)=1.15
      WECTL=F1(IACT+1)*88.46*((190.+W(9))*4.0E-2)**0.294
      WTSRT=49.19*(4.0*WTENG*1.0E-3)**0.541
      PASS=GX(19)*170.
      WTFURN=39.51*GX(19)
      WTFOOD=214.5
      WTO2=300.7
      WIWIN=501.55
      WTBGH=144.72
      WTAC=3647.
      WTTR=1500.
      F2(1)=0.
      F2(2)=250.
      ACTCON=F2(IACT+1)
      DATA CREW/1700./
      BAGGAGE=GX(19)*35.0
      CARGO=GX(22)
*****
*      THIS SECTION COMPUTES WEIGHTS DEPENDENT UPON WTO      *
*      BEGIN WEIGHT ITERATION THIS SECTION      *
*****
      50 WTWING=2.0*FUDGE*0.00428*(DESIGN(1))**0.48*AR*(GX(3)-0.05)**0.43

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```

$*(WTO*1.5*(3.0-PX(8)))*0.84*W(3)**0.14/((100.0*W(4))**0.76
$(COS(W(1)/GX(2)))*1.54)
FUDHT=1.
IF(DESIGN(5).GT.5.0) FUDHT=1.+(DESIGN(5)-5.0)/10.
*****
* THIS IS A LINEAR CORRECTION FACTOR FOR TAIL ASPECT RATIOS 5; *
* INTENDED AS A PENALTY TERM TO TRY AND REFLECT THE RANGE OF *
* TAIL WEIGHT EQUATION VALIDITY *
*****
TTEMP=HX(5)*1.5*HX(2)
TEMP=(WTO*4.5)**0.813*(SHT**0.584)*(HX(4)/TTEMP)**0.033
$(W(10)/LT)**0.28
WHT1=2.0*(0.0034*TTEMP**0.915)*FUDGE
WHT2=2.0*.00563*(WTO**0.6)*(SHT**.469)*(DESIGN(5)/.75)**.539
$(1.+HX(1))/HX(2)**0.692
WHT3=1.0*(4.566*1.0E-4*(DESIGN(4)**.48)*DESIGN(5)*
$(WTO*4.5/1.))**0.84)
*****
* WHT1 -- FROM NICOLAI (REF. 4) *
* WHT2 -- FROM VDEP (REF. 6) *
* WHT3 -- ANALOGOUS TO WING WEIGHT EQUATION *
*
* THE THREE HORIZONTAL TAIL WEIGHT EQUATIONS ARE THEN AVERAGED *
*****
WHT=(WHT1+WHT2+WHT3)/3.0)*FUDHT
TEMPV=1.02*(4.5*WTO)**.363*SVT**1.089*(GX(3)*0.8)**.601
$*LT*(-.726)*(1.+HX(20))**.217*HX(18)**.337*
$(1.+TRV)**.36*(COS(HX(19)/GX(2)))**(-.484)
WTV=(0.19*TEMPV**1.014)*FUDGE
TQ=10.43*(.000364*((GX(3)+0.04)*971.15)**2.0)**0.283
WTFUSE1=((TQ*(DESIGN(3)/GX(5))**0.71)*(WTO*1.0E-3)**0.95)*FUDGE
WTFUSE2=0.0796*2.1861*(WTO**0.33)*(DESIGN(3)**0.76)
$(GX(5)+GX(5))**1.2
*****
* WTFUSE1 -- FROM NICOLAI (REF. 4) *
* WTFUSE2 -- FROM VDEP (REF. 6) *
*
* THE TWO FUSELAGE WEIGHT EQUATIONS ARE THEN AVERAGED *
*****
WTFUSE=(WTFUSE1+WTFUSE2)/2.
WTLG=2.0*(62.21*(WTO*1.0E-3)**0.84)*FUDGE
WTCTL=(56.01*(WTO*245.6*1.0E-5)**0.576)*FUDGE
WINST=2.0*(15.+0.32*WTO*1.E-3)+4.*(4.8+.006*WTO*1.0E-3)+.15*WTO*1
$.0E-3
WIMISC=(0.771*WTO*1.0E-3*1.1)*FUDGE
IF(NOIT.LT.20) GO TO 94
IF(DELWTO.LT.20.0) GO TO 96
*****
* CALCULATE FUEL WEIGHT *
*****
94 CALL FUELCAL(WTO,WTFUEL,0)
FUEL=WTFUEL/6.4
GO TO 98

```

```

96 WTFUEL=WTO*WFOWTO
   FUEL=WTFUEL/6.4
*****
*   THIS SECTION CALCULATES WTS. DEPENDENT UPON FUEL WT.   *
*****
98 WTF1=41.6*(FUEL*1.0E-2)**0.818
   WTF2=7.91*(FUEL*1.0E-2)**0.854
   WTF3=7.38*(FUEL*1.0E-2)**0.458
   WTF4=ICGX*28.38*(FUEL*1.0E-2)**0.442
   WTFSYS=WTF1+WTF2+WTF3+WTF4
   WTELEC=1162.66*((WTFSYS+931.3)*1.0E-3)**0.506
*****
*   THIS SECTION CALCULATES THE EMPTY AND FIXED WEIGHTS   *
*****
   T1=WIWING+WTHT+WTVT+WTFUSE+WTLG+WTCTL+WTINST+WIMISC+WECTL+WTSRT
   $+WTFURN+WTO2+WIWIN+WTEGH+WTAC+WTR+ACTCON
   WTEMPY=(T1+WTENG+WTELEC+WTFSYS)*FUDGE
   WTEMPY=(1.0-PX(3))*WTEMPY
   WTFIXED=WTFOOD+PASS+CREW+BAGGAGE+CARGO
*****
*   THIS SECTION COMPUTES THE TAKE-OFF WEIGHT   *
*****
   WTONEW=WTFIXED+WTFUEL+WTEMPY
   DELWTO=WTONEW-WTO
   NOIT=NOIT+1
   IWT=IWT+1
   IF(NOIT.GT.39) GO TO 58
   DIV=1.2
   IF(NOIT.LT.3) DIV=0.85
   IF(NOIT.GT.10) DIV=1.95
   IF(IDEBUG.GT.0) WRITE(6,338) NOIT,WTO,WTONEW,DELWTO
   $ ,WTFUEL,WFOWTO
338 FORMAT(5X*ITER. NO.=*I5,10X*WTO,WTONEW,DELWTO,WTFUEL,WFOWTO=*
   $ 3F12.2,F12.2,F12.5)
   WTO=WTONEW+DELWTO/DIV
   DWTA(NOIT)=DELWTO
*****
*   ITERATE WEIGHT UNTIL WITHIN 0.05 LBS   *
*****
   IF(ABS(DELWTO).GT.0.05) GO TO 50
57 IF(OUTPUT.EQ.0) GO TO 150
   GO TO 60
58 WRITE(6,59) WTO,WTONEW,DELWTO,WTINIT,WFOWTO,WTFUEL,NOIT
59 FORMAT(/* // / WEIGHT LOOP DID NOT CONVERGE/ // *
   $ /10X*WTO,WTONEW,DELWTO,WTINIT,WFOWTO,WTFUEL,NOIT=*4F12.2,
   $ F12.4,F12.2,I5/)
   WRITE(6,64) DWTA
64 FORMAT(10X*DELWTO*9(T25,5F12.3/))
   WRITE(6,80) WIWING,WTHT,WTVT,WTFUSE,WTLG,WTCTL,WTINST,WIMISC,WTELEC
   $,WTSRT,WTFURN,WTO2,WIWIN,WTEGH,WTAC,WTR,WTENG,WECTL,WTFSYS,ACTCON
   WRITE(6,82) WTEMPY
   WRITE(6,84) PASS,CREW,BAGGAGE,WTFOOD,CARGO,WTFIXED
   WRITE(6,86) WTFUEL,WTO,NOIT

```

```

WRITE(6,88) WHT1,WHT2,WHT3,WTFUSE1,WTFUSE2,WTINIT
CALL XOUTPUT(6)
WRITE(6,887) ICNT,JCNT,KCNT,NDAV,LCNT,IWT,NOIT
887 FORMAT(/5X"DUMP OF FCOUNT COMMON BLOCK"/10X
$ "ICNT,JCNT,NDAV,KCNT,LCNT,IWT,NOIT=",10X,7I5/)
WTO=WTONEW+DELWTO/2.0
WTS(1)=WTO
GO TO 57

```

```

*****
*   OUTPUT SECTION   *
*****

```

```

60 WRITE(6,80) WIWING,WHT,WTVT,WTFUSE,WTLG,WTCTL,WTINST,WTMISC,WTELEC
$,WTSRT,WTFURN,WTO2,WIWIN,WTBGH,WTAC,WTR,WTENG,WECTL,WTFSYS,ACTCON
80 FORMAT(*1*//30X,23H***WEIGHT ESTIMATION***//10X*WING*T40,F10.1
$/10X*HOR. TAIL*T40,F10.1/10X*VERT. TAIL*T40,F10.1/10X*FUSELAGE*T40
$,F10.1/10X*LANDING GEAR*T40,F10.1/10X*CONTROL SYSTEM*T40,F10.1/10X
$*INSTRUMENTS*T40,F10.1/10X*MISC INTERIOR*T40,F10.1/10X*ELECTRICAL*
$T40,F10.1/10X*STARTERS*T40,F10.1/10X*FURNISHINGS*T40,F10.1/10X
$*OXYGEN*T40,F10.1/10X*WINDOWS*T40,F10.1/10X*BAGGAGE HNDLING*T40,
$F10.1/10X*AIR CONDITIONING*T40,F10.1/10X*THRUST REVERSER*T40,F10.1
$/10X*ENGINE*T40,F10.1/10X*ENGINE CONTROLS*T40,F10.1/10X*FUEL SYS*
$T40,F10.1/10X*ACTIVE CONTROL SYSTEMS*T40,F10.1)
WRITE(6,82) WTEMPY
82 FORMAT(/5X*EMPTY WEIGHT*T40,F10.1)
WRITE(6,84) PASS,CREW,BAGGAGE,WTFOD,CARGO,WTFIXED
84 FORMAT(/10X*PASSENGERS*T40,F10.1/10X*CREW*T40,F10.1/10X
$*BAGGAGE*T40,F10.1/10X*WTFOD*T40,F10.1/10X*CARGO*T40,F10.1
$/5X*FIXED WEIGHT*T40,F10.1)
WRITE(6,86) WTFUEL,WTO,NOIT
86 FORMAT(/5X*FUEL*T40,F10.1//5X*TAKE-OFF WEIGHT*T40,F10.1//10X
$*NO. OF ITERATIONS REQUIRED*T40,I10)
WRITE(6,88) WHT1,WHT2,WHT3,WTFUSE1,WTFUSE2,WTINIT
88 FORMAT(/5X*WHT(1,2,3),WTFUSE(1,2),WTINIT=*T45,5F10.2,F12.2)
CALL FUELCAL(WTO,WTFUEL,1)
CALL XL0D(GX(9),GX(3),WTS(11),EFF,1,OUTPUT)

```

```

*****
*   ASSIGN DATA BASE VARIABLES   *
*****

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```

150 WTS(1)=WTO
WTS(2)=WTEMPY
WTS(4)=.75*WTEMPY
WTS(6)=WTFUEL
IF(NOIT.LT.40) WFWTO=WTFUEL/WTO
AENG=0.
IF(ITERM(4).EQ.3) AENG=WTENG*0.81*LT*LT/(GX(15)*3.)
WTS(13)=13.45E6
WTS(14)=13.33E6
CALL AT62(WTS(11),ANS)
WTS(7)=WTS(1)/(ANS(1)*W(10)*DESIGN(1)*GX(15))
WTS(8)=WTS(13)*GX(15)/WTS(1)
CALL AT62(500.,ANS)
WTS(9)=GX(27)*WTS(1)/(GX(15)*DESIGN(1)*ANS(1)*W(10))
WTS(10)=WTS(14)*GX(15)/(WTS(1)*GX(27))

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      IF(IDEBUG2.GT.0) WRITE(6,990) NOIT
990  FORMAT(T100*NOIT=*I10)
      RETURN
      END
      SUBROUTINE CRUALT(WT,CLCR,M,ALT)
*****
*    THIS SUBROUTINE RETURNS ALTITUDE TO SATISFY THE SPECIFIED      *
*    WEIGHT, CL, AND M. ITERATIVE TABLE LOOK UP IS USED.          *
*****
      REAL M,HOLD,HNEW,ANS(4)
      COMMON /DEVAR/DESIGN(15),ITRM(10),CST(10)
      COMMON /GEOM/W(20),HX(20),GX(35),PX(15)
      IC=0
      DATA TO,PO,ALF,R/518.14,2116.229,.00356617,53.3/
      P=2.0*WT/(1.4*DESIGN(1)*CLCR*M*M)
      HOLD=(1.0-(P/PO)**(ALF*R))*TO/ALF
50  CALL AT62(HOLD,ANS)
      DP=P-ANS(2)
      DRDH=-1.0*ANS(1)*GX(15)
      HNEW=HOLD+DP*0.9/DRDH
      IC=IC+1
      IF(IC.GT.100) GO TO 100
      DALT=HNEW-HOLD
      IF(ABS(DALT).LT.7.5) GO TO 150
      HOLD=HNEW
      GO TO 50
100 WRITE(6,102) HNEW
102  FORMAT(*1*///40X,38H***CRUISE ALTITUDE DID NOT CONVERGE***//10X
      $*LAST ALTITUDE=*F12.2)
150  ALT=HNEW
152  FORMAT(///10X,*ALTITUDE,NO. OF ITERATIONS=*F12.2,I10)
      RETURN
      END
      SUBROUTINE ENGINE(ALT,M,TCTM,TSFC)
C
C    EMPIRICAL ADJUSTMENTS HAVE BEEN MADE TO THIS SUBROUTINE TO
C    MATCH DATA.
C
      COMMON /GEOM/W(20),HX(20),GX(35),PX(15)
      REAL M,HN,ANS(4)
      CALL AT62(ALT,ANS)
      DATA TO,PO/561.2,2116.229/
      HN=ALT/40000.
C
C    TCTM FROM REF(7) -- AGGARWAL, ET. AL.
C
      TCTM=(1000./41100.)*(30.06-34.74*HN+7.25*M+12.11*HN*HN
$ -1.12*M*HN-13.96*M*M-5.46*M*HN*HN+11.82*M*M*HN
$ -.01*M*M*HN*HN)
      ALTK=((ALT-35332.)*.004/1000.)+1.
      IF(ALT.GT.35332) GO TO 40
      TCTM=(1000./41100.)*(34.71-32.22*HN-27.4*M
$ +5.8*HN*HN+36.43*HN*M+2.65*M*M-11.64*M*HN*HN

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$ +3.19*M*M*HN-5.72*M*M*HN*HN)
ALTK=1.
40 DELTA=ANS(2)/PO
    THETA=ANS(3)/TO
    TCTM=1.2*TCTM
    TN=TCTM*41100./DELTA/20000.
    FN=1000.*(2.04+3.71*TN-4.38*M+1.69*TN*TN+5.94*M*TN
$ +12.99*M*M)
FNS=FN*ALTK
F=FNS*DELTA*(THETA)**0.5
TSFC=F/(TCTM*41100.)
TSFC=(1.0-PX(2))*TSFC
RETURN
END
SUBROUTINE CDZL(ALT,CDO,M,OUTPUT)
REAL MU(2),ANS(4),U(2),K(2),DCD(2),M
INTEGER OUTPUT
COMMON /DEVAR/DESIGN(15),ITRM(10),CST(10)
COMMON /DRAG/CDS(6),CDSAP(6)
COMMON /GEOM/W(20),HX(20),GX(35),PX(15)
CALL AT62(ALT,ANS)
DATA MU/3.6878E-7,2.9652E-7/
IALT=1
IF(ALT.GT.10000.) IALT=2
SHT=DESIGN(4)
TENG=DESIGN(6)/ITRM(4)
U(1)=0.6*ANS(4)
U(2)=M*ANS(4)
SREF=DESIGN(1)
*****
*   WING DRAG CALCULATIONS   *
*****
REW=W(10)*U(IALT)*ANS(1)/MU(IALT)
CF=0.455/(ALOG10(REW))**2.58
CF=CF*(1.0-PX(4))
SWET=2.05*SREF
K(1)=1.2230
K(2)=1.456
CDO=CF*K(IALT)*SWET/SREF
*****
*   HORIZONTAL TAIL DRAG CALCULATIONS   *
*****
REH=HX(5)*U(IALT)*ANS(1)/MU(IALT)
CF=0.074/REH**0.2
K(1)=1.2560
K(2)=1.3803
SWET=SHT*2.05
CDOH=CF*K(IALT)*SWET/SREF
*****
*   VERTICAL TAIL DRAG CALCULATIONS   *
*****
TRV=HX(17)
SV=GX(35)

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BV=(SV*HX(18))**0.5
CVBAR=4.*SV*(1.+TRV+TRV*TRV)/(3.*BV*(1.+TRV)**2.0)
REV=CVBAR*U(IALT)*ANS(1)/MU(IALT)
CF=.074/REV**0.2
K(1)=1.1413
K(2)=1.3504
SWET=2.05*SV
CDOV=CF*K(IALT)*SWET/SREF
*****
*   FUSELAGE DRAG CALCULATIONS   *
*****
REF=DESIGN(3)*U(IALT)*ANS(1)/MU(IALT)
CF=0.0455/(ALOG10(REF))**2.58
DIA=GX(5)
FLOD=DESIGN(3)/DIA
RDIA=DIA/2.0
ANOSE=2.*GX(1)*RDIA*RDIA
CONEL=(DESIGN(3)-RDIA)*.25
ABOD=GX(1)*GX(5)*(DESIGN(3)-RDIA-CONEL)
SLANT=(CONEL*CONEL+RDIA*RDIA)**0.5
ACONE=GX(2)*RDIA*SLANT
SFUS=ANOSE+ABOD+ACONE
RAT=(1.+60./(FLOD*FLOD*FLOD)+.0025*FLOD)*SFUS/50.
CDDF=CF*RAT
CDBF=5.0112E-5/(CDDF)**0.5
CDOF=CDDF*50.0/SREF
*****
*   ENGINE NACELLE DRAG CALCULATIONS   *
*****
EL=GX(6)*(TENG/GX(21))**0.5
EDIA=GX(7)*(TENG/GX(21))**0.5
SWET=GX(1)*EDIA*EL
REE=EL*U(IALT)*ANS(1)/MU(IALT)
CF=0.074/REE**0.2
TT=2
IF(ITERM(4).GT.3) TT=4
CDOE=1.0033*CF*SWET*TT/SREF
*****
*   SUM UP DRAG COMPONENTS   *
*   *   *   *
*   CRUD DRAG (IALT=2)   *
*   LANDING GEAR DOWN (0.0150) + 10 DEGREES FLAPS (0.008)   *
*   (IALT=1)   *
*****
DCD(1)=0.023
DCD(2)=0.0007
CDO=(CDOW+CDOH+CDOV+CDOF+CDBF+CDOE+DCD(IALT))*1.05
IF(IALT.NE.1) GO TO 76
*****
*   DATA BASE ASSIGNMENTS   *
*****
CDSAP(1)=CDO
CDSAP(2)=CDOW

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```

CDSAP(3)=CDOH
GO TO 78
76 CDS(1)=CDO
CDS(2)=CDOW
CDS(3)=CDOH
CDS(6)=CDOF
*****
* OUTPUT SECTION *
*****
78 IF(OUTPUT.EQ.0) GO TO 100
WRITE(6,80) CDOW,CDOH,CDOV,CDOF,CDBF,CDOE,DCD(IALT),CDO
80 FORMAT(*1*//15X,19H***DRAG ANALYSIS***,//10X*WING*T35,F10.4/10X
$*HORIZONTAL TAIL*T35,F10.4/10X*VERTICAL TAIL*T35,F10.4/10X*FUSELAG
$*T35,F10.4/10X*BASE*T35,F10.4/10X*ENGINE NACELLE*T35,F10.4/10X
$*CRUD/FLAPS*T35,F10.4//5X
$*AIRCRAFT DRAG*T35,F10.4///10X*INTERFERENCE FACTOR IS 5 PERCENT*)
WRITE(6,82) REW,REH,REV,REF,REE
82 FORMAT(///15X,23H***REYNOLD'S NUMBERS***//10X*WING*T35,F12.1/10X,
$*HORIZONTAL TAIL*T35,F12.1/10X*VERTICAL TAIL*T35,F12.1/10X*FUSELAG
$*T35,F12.1/10X*ENGINE*T35,F12.1//)
IF(IALT.EQ.1) WRITE(6,84)
84 FORMAT(///30X,14H***APPROACH***/)
100 RETURN
END
SUBROUTINE STABCOD(CL,M,ICG,OUTPUT)
INTEGER OUTPUT
REAL DCDM(2),XACDM(2),ANS(4)
REAL KA,KTR,KH,M,KWB,K
REAL LF
COMMON /DEVAR/DESIGN(15),ITERM(10),CST(10)
COMMON /GEOM/W(20),HX(20),GX(35),PX(15)
COMMON /GRAVITY/CG(6)
COMMON /STAB/DERIVCR(15),DERIVAP(15),STOR(20)
COMMON /WTSVE/WTS(20)
*****
* THIS SUBROUTINE CALCULATES STABILITY AND CONTROL DERIVATIVES *
* IN EITHER APPROACH OR CRUISE CONFIGURATIONS *
* ICR=0 (APPROACH); ICR=1 (CRUISE) *
*****
XCG=(CG(1)+CG(3))/2.0
IF(ICG.LT.7) XCG=CG(ICG)
ICR=1
ELASTK=0.875
IF(M.LT.0.45) ELASTK=0.825
IF(M.LT.0.46) ICR=0
*****
* THE FOLLOWING SECTION CALCULATES CL(ALPHA) *
*****
KWB=1.0-0.25*GX(5)*GX(5)/(W(9)*W(9))+0.025*GX(5)/W(9)
BETA=(1.0-M*M)**0.5
PIAR=DESIGN(2)*GX(1)
K=1.0
XNUM=2.0*PIAR

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T1=DESIGN(2)*DESIGN(2)*BETA*BETA/(K*K)
T2=1.0+W(13)*W(13)/(BETA*BETA)
CLAW=XNUM*ELASTK/(2.0+(T1*T2+4.0)**0.5)
T1=DESIGN(2)*DESIGN(2)/(K*K)
T2=1.0+W(13)*W(13)
CLAWM0=XNUM*.725/(2.0+(T1*T2+4.0)**0.5)
KA=1./DESIGN(2)-1.0/(1.+DESIGN(2)**1.7)
KTR=(10.-3.*W(3))/7.
ZTL=GX(34)
XLT=DESIGN(1)*W(10)*HX(6)/DESIGN(4)
KH=(1.0-ZTL/W(9))/(2.0*XLT/W(9))**0.40
DEDAM0=4.44*(KA*KTR*KH*(W(15))**2.0)**1.119
DEDA=DEDAM0*(CLAW/CLAWM0)**0.444444
TM1=(1.0+HX(9)*HX(9)/(BETA*BETA))
TM2=BETA*BETA*DESIGN(5)*DESIGN(5)
CLAH=2.0*GX(1)*ELASTK*DESIGN(5)/(2.0+(TM2*TM1+4.0)**0.5)
CLAWB=KWB*CLAW
ETAH=0.90
CLA=CLAWB+CLAH*ETAH*DESIGN(4)*(1.0-DEDA)/DESIGN(1)
EWING=W(7)

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*****
* THE FOLLOWING STATEMENT CALCULATES CD(ALPHA) *
*****

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CDA=2.0*CL*CLA/(PIAR*EWING)

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*****
* THE FOLLOWING SECTION CALCULATES CM(ALPHA) *
*****

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XACW=.25-.265*M*M/(DESIGN(2))**0.5
DXACT=XLT/W(10)
AW=CLAW/GX(2)
XNRM=DESIGN(1)*W(10)*AW
TFUS=0.5836+.1690*(1.0-DEDA)
DXACF=-GX(5)*GX(5)*DESIGN(3)*TFUS/(XNRM*36.5)
DMWDF=GX(5)*W(10)/(DESIGN(1)*AW*290.)
DXACF=DXACF+DMWDF
STOR(11)=DXACF*AW
T=DESIGN(6)/ITERM(4)
WF=GX(6)*(T/GX(21))**0.5
LF=GX(7)*(T/GX(21))**0.5
TT=2.
IF(ITERM(4).GT.3) TT=4
DXACE=-TT*LF*WF*WF/(15.21*XNRM)
STOR(12)=DXACE*AW
TAL=CLAH*ETAH*DESIGN(4)*(1.0-DEDA)/(CLAWB*DESIGN(1))
XACWB=XACW+DXACF+DXACE
XAC=(XACWB+TAL*DXACT)/(1+TAL)
DCMCL=XCG-XAC
CMA=DCMCL*CLA

```

```

*****
* THE FOLLOWING SECTION CALCULATES VELOCITY DERIVATIVES *
*****

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```

CLU=(1.-M)*M*M*CL/(1.0-M*M)
DATA DCDM,XACDM/0.0202,0.1005,-3.1E-4,5.1E-4/

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Z=0.
IF(ICR.GT.0) Z=40000.
CALL AT62(Z,ANS)
AM=ANS(4)
CDU=DCDM(ICR+1)/AM+2.*CL*CLU/(PIAR*EWING*10.)
CMU=-CL*XACDM(ICR+1)
*****
*   THE FOLLOWING SECTION CALCULATES Q DERIVATIVES   *
*****
CLQH=2.0*CLAH*ETAH*HX(6)
CLQ=CLQH*1.1
CDQ=0
CMQT=-2.0*CLAH*ETAH*0.9*HX(6)*XLT/W(10)
*****
*   THE FOLLOWING SECTION CALCULATES ALPHA-DOT DERIVATIVES   *
*****
CMQ=CMQT*1.1
CLADOT=-2.0*CLAH*ETAH*HX(6)*DEDA
CDADOT=0.0
CMADOT=-2.0*CLAH*ETAH*HX(6)*XLT*DEDA/W(10)
*****
*   THE FOLLOWING SECTION CALCULATES CONTROL DERIVATIVES   *
*****
CLDEL=0.9*DESIGN(4)*CLAH*0.46/DESIGN(1)
*****
*   THIS IS PER DEGREE CONTROL DEFLECTION, OTHER PER RAD.   *
*****
CDDEL=DESIGN(4)*1.980E-3/DESIGN(1)
CMDEL=-CLAH*HX(6)*0.9*0.46
IF(ICR.LT.1) GO TO 120
XMU=215.
IF(OUTPUT.GT.-1) XMU=WTS(7)
*****
*   DATA BLOCK ASSIGNMENTS   *
*****
STOR(1)=CLAW
STOR(2)=CLAH
STOR(3)=DEDA
STOR(4)=XAC
STOR(5)=XAC-CMQ/(4.*XMU)
STOR(13)=TAI
DERIVCR(1)=CLA
DERIVCR(2)=CDA
DERIVCR(3)=CMA
DERIVCR(4)=CLU
DERIVCR(5)=CDU
DERIVCR(6)=CMU
DERIVCR(7)=CLQ
DERIVCR(8)=CDQ
DERIVCR(9)=CMQ
DERIVCR(10)=CLADOT
DERIVCR(11)=CDADOT
DERIVCR(12)=CMADOT

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```

DERIVCR(13)=CLDEL
DERIVCR(14)=CDDEL
DERIVCR(15)=CMDEL
GO TO 150
120 DERIVAP(1)=CLA
DERIVAP(2)=CDA
DERIVAP(3)=CMA
DERIVAP(4)=CLU
DERIVAP(5)=CDU
DERIVAP(6)=CMU
DERIVAP(7)=CLQ
DERIVAP(8)=CDQ
DERIVAP(9)=CMQ
DERIVAP(10)=CLADOT
DERIVAP(11)=CDADOT
DERIVAP(12)=CMADOT
DERIVAP(13)=CLDEL
DERIVAP(14)=CDDEL
DERIVAP(15)=CMDEL
XMU=70.
IF(OUTPUT.GT.-1) XMU=WTS(9)
STOR(6)=CLA
STOR(7)=CLAH
STOR(8)=DEDA
STOR(9)=XAC
STOR(10)=XAC-CMQ/(4.*XMU)
STOR(14)=TAL
150 IF(OUTPUT.LT.1) GO TO 200
*****
*   OUTPUT SECTION   *
*****
WRITE(6,162)
162 FORMAT(*1*//20X*STABILITY AND CONTROL DERIVATIVES*//)
IF(ICR.EQ.0) WRITE(6,163)
163 FORMAT(25X,14H***APPROACH***//)
WRITE(6,164) CL,M,XCG
164 FORMAT(10X*CL,M,CG. POSITION=*3F15.3//)
WRITE(6,166)
166 FORMAT(/28X*CL*14X*CD*12X*CM*/)
IF(ICR.EQ.1) GO TO 180
WRITE(6,174) DERIVAP
174 FORMAT(10X*ALPHA*4X,3F15.5/10X*VELOCITY*3F15.4/10X*Q*8X,3F15.5/
$10X*ALPHA-DOT*3F15.5/10X*ELEVATOR *3F15.5//)
GO TO 190
180 WRITE(6,174) DERIVCR
190 WRITE(6,192) XAC,DCMCL,CMA,STOR
192 FORMAT(/10X*NEUTRAL POINT*T35,F12.3/10X*STATIC STABILITY*
$T35,F12.3/10X*CM(ALPHA)*T35,F12.3/10X*STOR=*/
$2(T35,2F12.3/))
WRITE(6,196) DXACE,XACWB,XACW,AW,XNRM,TFUS,DXACF,DMWDF,
$ CLAWB,CLAH,DEDAMO,XLT,ZTL,CLAWMO,BETA,TAL,CLAW,DEDA
$,XAC,KH,KTR,TM1,TM2,KWB,XCG,KA
196 FORMAT(5(T30,5F12.4/))

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```

200 RETURN
END
SUBROUTINE TRIM(CL,M,CDO,CLWING,CLTAIL,CRIT,CRDE,EPS,IPHASE
$,ICG)
REAL LTOTOQ,LWOQ,LTLOQ,IW,M
COMMON /DEVAR/DESIGN(15),ITERM(10),CST(10)
COMMON /DRAG/CDS(6),CDSAP(6)
COMMON /GEOM/W(20),HX(20),GX(35),PX(15)
COMMON /GRAVITY/CG(6)
COMMON /STAB/DERIVCR(15),DERIVAP(15),STOR(20)
*****
*   IPHASE=1 (CR), =0 (10 DEG FLP,FWD CG), =-1 (45 DEG FLP),      *
*   =-2 (45 DEG FLAP, FWD CG), =-3 (45 DEG FLAP, FWD CG, FIND  *
*   CLMAX), =-4 (10 DEG FLAP, FWD CG, FIND CLMAX), =2 (CR, AFT CG) *
*****
N=0
*****
*   INITIALIZE VARIABLES FROM DATA BASE      *
*****
XA=.25-.265*M*M/(DESIGN(2))**.5
XAC=(CG(1)+CG(3))/2.-XA
IF(ICG.LT.7) XAC=CG(ICG)-XA
ZAC=0.08
ZTLC=-.12
ST=DESIGN(4)
CMACW=-.10-.030218*W(11)-.046875*M
CMACW=CMACW*(1.0-PX(1))
CDT=CDS(3)
AT=STOR(2)/GX(2)
AW=STOR(1)/GX(2)
DEDA=STOR(3)
AOL=W(16)
IF(IPHASE.GT.0) GO TO 10
AT=STOR(7)/GX(2)
AW=STOR(6)/GX(2)
DEDA=STOR(8)
CDT=CDSAP(3)
CMACW=CMACW+W(17)
W(19)=CMACW-W(17)
AOL=W(16)+GX(17)
IF(IPHASE.LT.-3) GO TO 10
IF(IPHASE.EQ.0) GO TO 10
CMACW=CMACW+W(18)-W(17)
AOL=W(16)+GX(18)
CDO=CDO+W(20)
10 CD=CDO+CL*CL/(DESIGN(2)*GX(1)*W(7))
CMAFUS=STOR(11)+STOR(12)
IW=W(2)
IF(IPHASE.LT.-2) GO TO 200
LTOTOQ=CL*DESIGN(1)
LTLOQ=-.1*LTOTOQ
*****
*   THIS SECTION CALCULATES CL(WING) AND CL(TAIL) GIVEN CL(TOTAL)      *

```

```
20 LWOQ=LTOTOQ-LTLOQ
   CLWING=LWOQ/DESIGN(1)
   IF (CLWING.GT.3.5) CLWING=3.5
   IF (CLWING.LT.0.1) CLWING=0.1
   CLTAIL=LTLOQ/ST
   IF (ABS (CLTAIL) .GT.2.0) CLTAIL=2.0*CLTAIL/ABS (CLTAIL)
   CDTAIL=CDT*DESIGN(1)/ST+CLTAIL*CLTAIL/(GX(1)*DESIGN(5)*0.90)
   ALFAW=CLWING/AW+AOL
   IF (ALFAW.GT.16.0) ALFAW=16.0
   CMFUS=CMAFUS*(ALFAW-IW)
   EPS=CLWING*DEDA/AW
   CRDE=0.
   ALFAT=CLTAIL/AT-CRDE
   CTLPWR=(CMACW+CLWING*XAC+CMFUS-AT*(ALFAW-EPS-IW)*HX(6)*.9)/
$ (AT*HX(6)*0.9)
   TAO=0.46
   CRIT=CTLPWR
   CRDE=0.
   IF (CRIT.LT.5.0) GO TO 40
   CRDE=(CTLPWR-5.0)/TAO
   CRIT=5.0
   GO TO 60
40 IF (CRIT.GT.-14.0) GO TO 60
   CRDE=(CTLPWR+14.0)/TAO
   CRIT=-14.0
60 CNW=CLWING*COS((ALFAW-IW)/GX(2))+CD*SIN((ALFAW-IW)/
$GX(2))
   CCW=CD*COS((ALFAW-IW)/GX(2))-CLWING*SIN((ALFAW-IW)/
$GX(2))
   CT=CD
C
C   IF TRIJET, THE UNBALANCE IS ONLY ONE ENGINE
C
   IF (ITERM(4).EQ.3) CT=CT/3.0
   CNT=(1./(0.9*HX(6)))*(CNW*XAC+CCW*ZAC+CMFUS-CT*ZTLC+CMACW)
   CLTNEW=(CNT-CDTAIL*SIN((ALFAT-CRIT)/GX(2)))/(COS((ALFAT
$-CRIT)/GX(2)))
   DTEST=CLTNEW-CLTAIL
   CLTAIL=(CLTNEW+DTEST)/(N+1)
   IF (ABS (CLTAIL) .GT.2.0) CLTAIL=2.0*CLTAIL/ABS (CLTAIL)
   LTLOQ=CLTAIL*ST
   N=N+1
   IF (ABS (DTEST) .LT.0.003) GO TO 100
   IF (N.GT.25) GO TO 80
   GO TO 20
80 WRITE(6,82) CLWING,CLTAIL,CRIT,CRDE,CNW,DTEST
   $,ALFAW,EPS,CMFUS
82 FORMAT(///20X*TRIM DID NOT CONVERGE*//3(3F15.4/)//)
100 IF (CLWING.EQ.3.5) WRITE(6,84) CLWING
   $,CLTAIL,CRIT,CRDE,CNW,DTEST
   IF (ALFAW.EQ.16.0) WRITE(6,84) CLWING
   $,CLTAIL,CRIT,CRDE,CNW,DTEST
```

```

84 FORMAT(///30X*TRIM HIT ALPHA OR CL LIMIT*//2(10X,3F12.4/))
   IF(ALFAW.EQ.16.0) CALL XOUTPUT(6)
   RETURN

```

```

*****
*   THIS SECTION CALCULATES CL(TAIL) AND CL(TOTAL) GIVEN CL(WING)   *
*****

```

```

200 CLWING=CL
    CLTAIL=-1.
    CDTAIL=CDT*DESIGN(1)/ST+CLTAIL*CLTAIL/(GX(1)*DESIGN(5)*0.90)
    ALFAW=CLWING/AW+AOL
    IF(ALFAW.GT.16.0) ALFAW=16.0
    CMFUS=CMAFUS*(ALFAW-IW)
    EPS=CLWING*DEDA/AW
    CRDE=0.
    ALFAT=CLTAIL/AT-CRDE
    CTLPWR=(CMACW+CLWING*XAC+CMFUS-AT*(ALFAW-EPS-IW)*HX(6)*.9)/
$ (AT*HX(6)*0.9)
    TAO=0.46
    CRIT=CTLPWR
    CRDE=0.
    IF(CRIT.LT.5.0) GO TO 540
    CRDE=(CTLPWR-5.0)/TAO
    CRIT=5.0
    GO TO 560
540 IF(CRIT.GT.-14.0) GO TO 560
    CRDE=(CTLPWR+14.0)/TAO
    CRIT=-14.0
560 CNW=CLWING*COS((ALFAW-IW)/GX(2))+CD*SIN((ALFAW-IW)/
$GX(2))
    CCW=CD*COS((ALFAW-IW)/GX(2))-CLWING*SIN((ALFAW-IW)/
$GX(2))
    CT=CD
    IF(ITERM(4).EQ.3) CT=CT/3.0
    CNT=(1./(0.9*HX(6)))*(CNW*XAC+CCW*ZAC+CMFUS-CT*ZTLC+CMACW)
    CLTNEW=(CNT-CDTAIL*SIN((ALFAT-CRIT)/GX(2)))/(COS((ALFAT
$-CRIT)/GX(2)))
    CLTAIL=CLTNEW
    LTLOQ=CLTAIL*ST
    LWOQ=CLWING*DESIGN(1)
    LTOTOQ=LTLOQ+LWOQ
    CL=LTOTOQ/DESIGN(1)
    RETURN
    END
    SUBROUTINE FUELCAL(WTO,WTFUEL,OUTPUT)
    COMMON /DEVAR/DESIGN(15),ITERM(10),CST(10)
    COMMON /GEOM/W(20),HX(20),GX(35),PX(15)
    COMMON /WTSVE/WTS(20)
    REAL ANS1(4)
    INTEGER OUTPUT
    IF(OUTPUT.LT.1) GO TO 30
    WRITE(6,21)
21 FORMAT(*1*///30X*// // CRUISE ANALYSIS// // *//)
    WRITE(6,23) RANGE

```

```

23 FORMAT(10X*TOTAL MISSION RANGE=*F10.2/10X
$ *CLIMB DISTANCE= 189.00*/10X
$ *DESCENT DISTANCE= 113.00*/)
WRITE(6,25)
25 FORMAT(//2X*LEG*2X*MACH NO.*3X*CL*4X*V*7X*TIME*4X*L/D*
$ 4X*TSFC*2X*T/T(IN)*1X*ALT(BEG)*2X*ALT(END)*2X*WT(BEG)*
$ 3X*WT(END)*6X*DIST*4X*TCON*4X*GAMA*5X*CLM*/)
30 WTBEQ=WTO*0.97*0.965
GX(31)=.0020
RANGE=GX(4)
GX(30)=5.
TOTTIME=0.78
ALT1=36000.
ALT11=ALT1
WT1=WTBEQ
RLOVER=RANGE-302.
R=RLOVER/10.
*****
* CALCULATE CRUISE PORTION IN 10 SEGMENTS *
*****
DO 40 I=1,10
CALL CRUFUEL(WT1,R,WT2,ALT1,ALT2,I,TIME,OUTPUT,0)
WT1=WT2
ALT1=ALT2
TOTTIME=TOTTIME+TIME
IF(I.LT.5) GO TO 40
IF(I.GT.5) GO TO 40
WTMID=WT2
WTS(15)=WTMID
WTS(11)=ALT2
40 CONTINUE
*****
* RESERVE MISSION ASSUMPTION *
*****
WIGRD=WT2
CALL CRUFUEL(WIGRD,1000.,WTRES,30000.,ALTR,11,TM,OUTPUT,1)
*****
* INSERT DATA IN DATA BASE *
*****
FL=TOTTIME
BLKHR=FL+.327
SPEED=RANGE/FL
BLKSPD=RANGE/BLKHR
WTS(5)=.97*WIGRD
WTEND=0.97*WTRES
WTFUEL=WTO-WTEND
WTS(17)=SPEED
WTS(18)=FL
WTS(19)=BLKHR
WTS(20)=WTBEQ-WTS(5)
WTS(3)=WTS(20)/BLKHR
WTS(3)=(WTBEQ-WTS(5))/TIME
FUEL=WTS(20)/6.4

```

```

XMG=RANGE/FUEL
XSMG=XMG*GX(19)
CST(5)=XSMG
*****
*   OUTPUT SECTION   *
*****
      IF(OUTPUT.EQ.0) GO TO 100
      WRITE(6,52) WTO,WTBEG,WIMID,WIGRD,WTRES,WTEND,WTFUEL
52  FORMAT(*1*//40X,26H***FUEL WEIGHT ANALYSIS***//10X*TAKE-OFF*T35,
      $F12.2/10X*START-CRUISE*T35,F12.2/10X*MID-CRUISE*T35,F12.2/
      $10X*END-CRUISE*T35,F12.2/10X*AFTER RESERVE*T35,F12.2/10X
      $*AFTER DESCENT/TAXI*T35,F12.2//5X*NET FUEL WEIGHT(LBS)*T35,F12.2)
      WRITE(6,54) ALT11,ALT2,ALTR
54  FORMAT(///5X*CRUISE ALTITUDES*/10X*LEG 1*T35,F12.2/10X*LEG 2*
      $T35,F12.2/10X*RESERVE LEG*T35,F12.2)
      WRITE(6,64) FL,SPEED,BLKHR,BLKSPD
64  FORMAT(///10X*FLIGHT LENGTH (HR)*T35,F12.2/
      $ 10X*AVERAGE SPEED (KTS)*T35,F12.2/
      $ 10X*BLOCK TIME (HR)*T35,F12.2/
      $ 10X*BLOCK SPEED (KTS)*T35,F12.2)
      WRITE(6,66) WTS(20),FUEL,XMG,XSMG
66  FORMAT(10X*BLOCK FUEL (LBS)*T35,F12.2/
      $10X*BLOCK FUEL (GALS)*T35,F12.2/10X
      $*NAUT. MI/GAL*T35,F12.2/10X*NAUT. SEAT MI./GAL.*
      $T35,F12.2)
      TENG=DESIGN(6)/ITERM(4)
      TREF=GX(21)
      SCF=TENG/TREF
      WRITE(6,68) DESIGN(6),ITERM(4),TENG,TREF,SCF
68  FORMAT(/10X*INSTALLED THRUST (LBS)*T35,F12.2/
      $ 10X*NO. OF ENGINES*T35,I12/10X
      $ *ENGINE THRUST (LBS)*T35,F12.2/10X
      $ *REFERENCE ENGINE (LBS)*T35,F12.2/10X
      $ *SCALE FACTOR*T35,F12.3)
100 RETURN
      END
      SUBROUTINE CRUFUEL(WTBEG,RANGE,WTEND,ALTCR,ALTEND,ICOUNT,TIME
      $ ,OUTPUT,IRES)
*****
*   CRUFUEL CALCULATES PERFORMANCE DURING CRUISE/CLIMB OR RESERVE   *
*   SEGMENT                                                           *
*****
      REAL ANS(4),LOD,HZ,M
      INTEGER OUTPUT
      COMMON /DEVAR/DESIGN(15),ITERM(10),CST(10)
      COMMON /DRAG/CDS(6),CDSAP(6)
      COMMON /GEOM/W(20),HX(20),GX(35),PX(15)
      COMMON /WTSVE/WTS(20)
      M=GX(3)
      GAMA=0.
      CALL CDZL(ALTCR,CDO,M,0)
      CDO=CDO+GX(31)
      XT1=W(8)*W(8)*(1.0/W(6)-1.0/W(7))/(GX(1)*DESIGN(2))

```

```

CLM=1.00*(GX(1)*DESIGN(2)*W(7)*(CDO+XT1)**0.5
IF(IRES.LT.1) GO TO 10
CLCR=0.79*CLM
*****
*   THE FOLLOWING STATEMENTS CALCULATE THE RESERVE MISSION WHICH   *
*   IS AT 30000 FT AT MAXIMUM RANGE.                               *
*****
CALL AT62(30000.,ANS)
VCR=(WTBEG*2.0/(DESIGN(1)*ANS(1)*CLCR)**0.5
M=VCR/ANS(4)
CALL XLOD(CLCR,M,30000.,LOD,1,0)
HZ=3.0
ALTEND=30000.
TIME=RANGE/(VCR*1.467*1.1507)
GO TO 88
*****
*   THE FOLLOWING STATEMENTS CALCULATE THE CRUISE/CLIMB AT MAXIMUM *
*   RANGE FACTOR.                                                 *
*****
10 CALL AT62(ALTCR,ANS)
VCR=M*ANS(4)
WTT=.98*WTBEG
Q=0.5*ANS(1)*VCR*VCR
CLCR=WTBEG/(Q*DESIGN(1))
IF(CLCR.GT.0.79*CLM) GO TO 15
CLCR=0.79*CLM
VCR=(WTBEG*2./(ANS(1)*DESIGN(1)*CLCR)**0.5
M=VCR/ANS(4)
CRCL=.79*CLM
TIME=RANGE/(VCR/(1.467*1.1507))
CALL CRUALT(WTT,CRCL,GX(3),ALTD)
ROC=(ALTD-ALTCR)/(3600.*(TIME-.02))
GAMA=ASIN(ROC/VCR)
GO TO 20
*****
*   THE FOLLOWING STATEMENTS CALCULATE THE CRUISE/CLIMB AT 90% OF *
*   CL FOR (L/D)MAX.                                             *
*****
15 IF(CLCR.LT.0.98*CLM) GO TO 18
CRCL=0.9*CLM
CALL CRUALT(WTT,CRCL,GX(3),ALTD)
TIME=RANGE/(VCR/(1.467*1.1507))
ROC=(ALTD-ALTCR)/(3600.*(TIME-.02))
GAMA=ASIN(ROC/VCR)
GO TO 20
*****
18 IF(ICOUNT.LT.6) GO TO 20
CRCL=.9*CLM
CALL CRUALT(WTT,CRCL,GX(3),ALTD)
ROC=(ALTD-ALTCR)/(3600.*(TIME+0.02))
GAMA=ASIN(ROC/VCR)
20 CALL XLOD(CLCR,M,ALTCR,LOD,1,0)
HZ=ALTCR/10000.

```

```

88 CALL ENGINE (ALTCR,M,TCTM,TSFC)
   WTEND=WTBEG/(EXP(TSFC*RANGE/(VCR*0.59239*LOD)))
   TIME=RANGE/(VCR/(1.467*1.1507))
   TOWAV=DESIGN(6)/WTBEG
   TOWRQ=(1./TCTM)*(1./LOD+SIN(GAMA))
   TCON=TOWAV/TOWRQ
   IF(TCON.LT.GX(30)) GX(30)=TCON
   IF(ICOUNT.GT.10) GO TO 92
   CALL CRUALT(WTEND,CLCR,M,ALTEND)
   ALTEND=ALTEND+SIN(GAMA)*VCR*3600.*TIME
92 IF(ICOUNT.NE.5) GO TO 99
*****
*   DATA BASE ASSIGNMENTS   *
*****
   CDS(4)=LOD
   CDS(5)=CLCR/LOD
   GX(9)=CLCR
   CALL CRUALT(WTEND,CLM,GX(3),ALTLDM)
   WTS(12)=ALTLDM
99 IF(OUTPUT.LT.1) GO TO 100
*****
*   OUTPUT SECTION   *
*****
   WRITE(6,188) ICOUNT,M,CLCR,VCR,TIME,LOD,TSFC,TCTM,
   $ ALTCR,ALTEND,WTBEG,WTEND,RANGE,TCON,GAMA,CLM
188 FORMAT(I5,F8.2,F7.3,F8.1,F8.3,F8.2,F7.3,F7.3,5F10.1,
   $ F8.3,F8.4,F8.3)
100 RETURN
   END
   SUBROUTINE XLOD(CL,XM,ALT,LOD,IPHASE,OUTPUT)
   REAL LOD,ANS(4),A1(5),A2(4),A3(5),B1(4)
   INTEGER OUTPUT
   COMMON /DEVAR/DESIGN(15),ITRM(10),CST(10)
   COMMON /DRAG/CDS(6),CDSAP(6)
   COMMON /GEOM/W(20),HX(20),GX(35),PX(15)
   COMMON /GRAVITY/CG(6)
   COMMON /STAB/DERIVCR(15),DERIVAP(15),STOR(20)
   COMMON /WTSVE/WTS(20)
*****
*   IPHASE=1 (CR), =0 (10 DEG FLP,FWD CG), =-1 (45 DEG FLP), *
*   =-2 (45 DEG FLAP, FWD CG), =-3 (45 DEG FLAP, FWD CG, FIND *
*   CLMAX), =-4 (10 DEG FLAP, FWD CG, FIND CLMAX), =2 (CR, AFT CG) , *
*****
   DATA A1/.00102,.028817,.841,5.714076,10.706253/
   DATA A2/1.00131,-.122063,.030714,-.005556/
   DATA A3/276.559019,-1306.362579,2314.351122,-1817.552645,
   $ 534.505085/
   DATA B1/-.794,-.296,.812,.111/
   IF(IPHASE.LT.1) XM=.15
   ICG=ITRM(3)
   IF(IPHASE.GT.1) ICG=1
   IF(IPHASE.GT.0) GO TO 25
   CALL AT62(ALT,ANS)

```

```

F1=GX(27)
IF(IPHASE.EQ.0.OR.IPHASE.LT.-3) F1=1.
V=(2.*F1*WTS(1)/(ANS(1)*DESIGN(1)*CL)**0.5
XM=V/ANS(4)
ICG=4
IF(IPHASE.EQ.-1.OR.IPHASE.EQ.0) ICG=2
ICG=2
IF(IPHASE.LT.-1) ICG=4
25 CALL CDZL(ALT,CDO,XM,OUTPUT)
CALL STABCOD(CL,XM,ICG,OUTPUT)
CALL TRIM(CL,XM,CDO,CLWING,CLTAIL,CRIT,CRDE,EPS,IPHASE,
$ICG)
*****
* COMPRESSIBILITY DRAG *
*****
DFME=0.
FMCR=0.
DWME=0.
WMCR=0.
IF(XM.LT.0.65) GO TO 40
CLWN=CLWING/(W(15)*W(15))
WMCRN=(W(4)-(B1(4)*CLWN+B1(3)))/(B1(2)*CLWN+B1(1))
WMCR=WMCRN/W(15)
DM=XM-WMCR
Z1=A1(1)
DO 28 I=2,5
Z1=Z1+A1(I)*DM**(I-1)
28 CONTINUE
DWME=Z1
BARL=DESIGN(3)/(GX(5)*10.)
Z1=A2(1)
DO 30 I=2,4
Z1=Z1+A2(I)*BARL**(I-1)
30 CONTINUE
FMCR=Z1
Z1=A3(1)
DM=XM-FMCR
BARM=0.89+DM
DO 32 I=2,5
Z1=Z1+A3(I)*BARM**(I-1)
32 CONTINUE
DFME=(Z1-1.)*CDS(6)
40 E1=W(6)
E2=W(7)
IF(IPHASE.LT.1) E2=0.7
*****
* WING INDUCED DRAG *
*****
CLO=W(8)
T1=CLO*CLO/(GX(1)*DESIGN(2)*E1)
T2=(CLWING*CLWING-CLO*CLO)/(GX(1)*DESIGN(2)*E2)
TT1=T1+T2
*****

```

```

*      MUNK'S INTERFERENCE TERM      *
*****
SMU=HX(4)/W(9)
G=(.25*GX(5)+GX(34))/W(9)
G2=G*G
G3=G2*G
C0=.000076+.006814*G-.088417*G2+.247037*G3
C1=1.002161+2.242040*G-34.140971*G2+73.096667*G3
C2=.000145-24.824801*G+211.181316*G2-442.515185*G3
C3=-.014537+42.231817*G-375.564896*G2+803.7551111*G3
C4=.009817-24.947988*G+220.010784*G2-472.608148*G3
SIGMA=C0+C1*SMU+C2*SMU*SMU+C3*SMU*SMU*SMU+C4*SMU*SMU*SMU*SMU
*****
*      INTERFERENCE DRAG      *
*****
T3=2.*SIGMA*CLWING*CLTAIL*DESIGN(4)/(SMU*GX(1)*DESIGN(2)
$ *DESIGN(1)*E1)
*****
*      TAIL INDUCED DRAG      *
*****
T4=DESIGN(4)*CLTAIL*CLTAIL/(DESIGN(1)*GX(1)*DESIGN(5)*.8)
*****
*      INDUCED DRAG FROM HAVING TAIL      *
*****
DELCL2=CLWING*CLWING-CL*CL
TDG=DELCL2/(GX(1)*DESIGN(2)*E2)+T3+T4
CDI=TT1+T3+T4
CDEL=(ABS(CRDE))*DERIVCR(14)
IF(IPHASE.LT.1) CDEL=(ABS(CRDE)+GX(2)*GX(13))*DERIVAP(14)
CDTOT=CDI+CDO+CDEL+DWME+DFME
XT1=CLO*CLO*(1./E1-1./E2)/(GX(1)*DESIGN(2))
CDOP=CDO+TDG
*****
*      DATA BASE ASSIGNMENTS      *
*****
GX(31)=TDG
XLDMX=.5*((GX(1)*DESIGN(2)*E2)/(CDOP+XT1))**.5
CLLDMX=(GX(1)*DESIGN(2)*W(7)*(CDOP+XT1))**.5
IF(IPHASE.LT.1) GO TO 48
HX(14)=CRDE
CST(6)=XLDMX
GX(28)=CLWING
DTAIL=CDS(3)+TDG
GO TO 50
48 CDSAP(4)=CL/CDTOT
DTAIL=CDSAP(3)+TDG
CDSAP(5)=CDTOT
HX(11)=CLTAIL
GX(29)=CLWING
HX(12)=CRIT
HX(13)=CRDE
50 LOD=CL/CDTOT
*****

```



```

*      OUTPUT SECTION      *
*****
      IF(OUTPUT.EQ.0) GO TO 100
      WRITE(6,80)
80  FORMAT(*1*//20X*ACCURATE L/D ANALYSIS*)
      IF(IPHASE.LT.0) WRITE(6,81)
81  FORMAT(//20X*APPROACH WITH 45 DEGREES FLAP*)
      IF(IPHASE.LT.-1) WRITE(6,87)
87  FORMAT(20X*FORWARD C.G.*/)
      WRITE(6,82) CL,CLWING,CLTAIL,CRDE,CRIT
82  FORMAT(//10X*CL (REQUESTED)=*T45,F15.3/10X*CL (WING)=*T45,F15.3/10X
      $*CL (TAIL)=*T45,F15.3/10X*ELEVATOR (DEGREES)=*T45,F15.2/
      $10X*STABILIZER (DEGREES) *T45,F15.2/)
      WRITE(6,83) TT1,T3,T4,TDG,DTAIL,SIGMA
83  FORMAT(/5X*INDUCED DRAG COMPONENTS*/10X*WING=*T45,F15.4/
      $10X*INTERFERENCE=*T45,F15.4/10X*TAIL=*T45,F15.4
      $ /10X*(TRIM)=*T45,F15.4/10X*(TAIL)=*T45,F15.4/10X*SIGMA*T45,
      $ F15.4/)
      WRITE(6,84) CDI,CDO,CDDEL,DWME,WMC,DFME,FMCR,CDTOT
84  FORMAT(5X*DRAG COEFFICIENTS*/10X*INDUCED=*T45,F15.4/
      $ 10X*ZERO LIFT=*
      $T45,F15.4/10X*ELEVATOR=*T45,F15.4/10X
      $ *WING (MACH) , M(CRIT)=*T45,F15.4,F15.2/10X
      $ *FUZE (MACH) , M(CRIT)=*T45,F15.4,F15.2/10X
      $ *TOTAL=*T45,F15.4/)
      WRITE(6,86) LOD
86  FORMAT(//15X*L/D=*T45,F15.3)
      WRITE(6,92) XLDMX,CLLDMX,CDOP
92  FORMAT(///15X*MAX. L/D=*T45,F15.3/15X*CL-L/D MAX=*T45,F15.3/
      $ 10X*MODIFIED CDO=*T45,F15.4/)
100 RETURN
      END
      SUBROUTINE AIRCOST(COST,OUTPUT)
      REAL CD(10),CP(10)
      REAL T1(2),T3(2),T9(2),T10(2),T32(2)
      INTEGER OUTPUT
      COMMON /DEVAR/DESIGN(15),ITRM(10),CST(10)
      COMMON /WTSVE/WTS(20)
      COMMON /GEOM/W(20),HX(20),GX(35),PX(15)
      A=WTS(4)
      DATA T1,T3,T9,T10/1.,1.15,1.,2.,1.,1.15,0.,1./
      DATA T32/1.,1.1/
*****
*      LIST OF PURCHASE PRICE ELEMENTS IN 1974 $      *
*      REF(4) --- NICOLAI                             *
*      ENGINEERING (1)                                 *
*      DEVELOPMENT SUPPORT (2)                         *
*      FLIGHT TEST (3)                                 *
*      TOOLING (4)                                     *
*      MANUFACTURING LABOR (5)                         *
*      QUALITY CONTROL (6)                             *
*      MATERIALS (7)                                   *
*      ENGINE (8)                                      *

```

```

*           AVIONICS (9)           *
*           ACTIVE CONTROL SYSTEM (10) *
*****

```

```

IACT=0
ICGX=ITERM(2)
CD(1)=T1 (IACT+1)*10964.13*A**0.791
CP(1)=T1 (IACT+1)*26567.12*A**0.791-CD(1)
CD(2)=1627.68*A**0.873
CP(2)=0.0
CD(3)=T3 (IACT+1)*T32 (ICGX+1)*19.16*A**1.160
CP(3)=T3 (IACT+1)*T32 (ICGX+1)*0.0
CD(4)=15716.31*A**0.764
CP(4)=43272.95*A**0.764-CD(4)
CD(5)=13026.56*A**0.74
CP(5)=164219.18*A**0.74-CD(5)
CD(6)=CD(5)*0.13
CP(6)=CP(5)*0.13
CD(7)=2733.64*A**0.689
CP(7)=125960.83*A**0.689-CD(7)
CD(8)=(ITERM(4)+1)*2.*1.31*169.0*(DESIGN(6)/ITERM(4))**0.8356
CP(8)=ITERM(4)*250.*1.31*169.0*(DESIGN(6)/ITERM(4))**0.8356
CD(9)=2.*300000.*T9 (IACT+1)
CP(9)=250.*300000.*T9 (IACT+1)

```

```

C
C ACTIVE CONTROLS PRICE HAS TO BE ESTIMATED
C

```

```

CD(10)=206250.*2.*ITERM(1)
CP(10)=206250.*250.*ITERM(1)
TOTD=0.
TOTP=0.

```

```

C
C CONVERT FROM 1974 $ TO 1976 $
C

```

```

DO 50 J=1,10
CD(J)=CD(J)*1.23077
CP(J)=CP(J)*1.23077
TOTD=TOTD+CD(J)
TOTP=TOTP+CP(J)

```

```
50 CONTINUE
```

```

C
C INCLUDING 10% PERCENT PROFIT
C

```

```

TOTCOST=TOTD*1.1+TOTP*1.1
COST=TOTCOST/250.0
COST=COST*(1.0+PX(7)*0.05)

```

```
*****
```

```
* OUTPUT SECTION *
```

```
*****
```

```

IF(OUTPUT.EQ.0) GO TO 100
WRITE(6,70)
70 FORMAT(*1*//20X*AIRCRAFT COST ESTIMATES*//43X*DEVELOPMENT*
$9X*PRODUCTION*/)
WRITE(6,72) CD(1),CP(1)

```

```

72 FORMAT(10X*ENGINEERING*T40,F15.2,T60,F15.2)
WRITE(6,74) CD(2),CP(2)
74 FORMAT(10X*DEVELOPMENT SUPPORT*T40,F15.2,T60,F15.2)
WRITE(6,80) CD(3),CP(3)
80 FORMAT(10X*FLIGHT TEST*T40,F15.2,T60,F15.2)
WRITE(6,82) CD(4),CP(4)
82 FORMAT(10X*TOOLING*T40,F15.2,T60,F15.2)
WRITE(6,84) CD(5),CP(5)
84 FORMAT(10X*MANUFAC. LABOR*T40,F15.2,T60,F15.2)
WRITE(6,86) CD(6),CP(6)
86 FORMAT(10X*QUALITY CONTROL*T40,F15.2,T60,F15.2)
WRITE(6,88) CD(7),CP(7)
88 FORMAT(10X*MATERIALS*T40,F15.2,T60,F15.2)
WRITE(6,90) CD(8),CP(8)
90 FORMAT(10X*ENGINE*T40,F15.2,T60,F15.2)
WRITE(6,92) CD(9),CP(9)
92 FORMAT(10X*AVIONICS*T40,F15.2,T60,F15.2)
WRITE(6,94) CD(10),CP(10)
94 FORMAT(10X*ACTIVE CONTROLS SYSTEM*T40,F15.2,T60,F15.2)
WRITE(6,96) TOTD,TOTF
96 FORMAT(/10X*TOTAL*T40,F15.2,T60,F15.2)
WRITE(6,78) COST
78 FORMAT(/5X*TOTAL COST PER AIRCRAFT= $*F12.2)
100 RETURN

```

```

END
SUBROUTINE MAINCST(COST,OUTPUT)
INTEGER OUTPUT
REAL MCOST(27),LCOST(27),T9(2),XNM(27)
REAL T1(2),T3(2),T8(2),T12(2),T15(2)
REAL LCST(27),MCST(27)
COMMON /DEVAR/DESIGN(15),ITRM(10),CST(10)
COMMON /WTSVE/WTS(20)
COMMON /GEOM/W(20),HX(20),GX(35),PX(15)
DATA T1,T3,T8/1.,1.15,1.,1.2,1.,1.2/
DATA T9,T12,T15/1.,1.3,1.,1.15,1.,1.15/
IACT=ITRM(1)
ICGX=ITRM(2)
NENG=ITRM(4)
NPASS=GX(19)
WTO=WTS(1)*0.453592
WTE=WTS(2)*0.453592
WTF=WTS(6)*0.456592
DATA XNM/4HINSP,8HAIR COND,10HAUTO PILOT,6HCOMMUN,
$4HELEC,4HFURN,9HFIRE PROT,9HFLT CONTL,4HFUEL,
$9HHYD POWER,3HICE,5HINSTR,9HLAND GEAR,
$8HLIGHTING,5HNAVIG,6HOXYGEN,7HFNUEMAT,
$9HWAT/WASTE,7HAIR APU,9HSTRUCTURE,5HDOORS,
$8HFUSELAGE,8HNACELLES,5HWINGS,4HSTAB,
$7HWINDOWS,6HENGINE/

```

```

*****
*   MAINTENANCE COSTS—1976 DOLLARS/HOUR   *
*   REF(20) -- AMERICAN AIRLINES         *
*   (1)  INSPECTION AND MISC.             *

```

- * (2) AIR CONDITIONING *
- * (3) AUTO PILOT *
- * (4) COMMUNICATIONS *
- * (5) ELECTRICAL *
- * (6) EQUIPMENT AND FURNISHINGS *
- * (7) FIRE PROTECTION *
- * (8) FLIGHT CONTROLS *
- * (9) FUEL *
- * (10) HYDRAULIC POWER *
- * (11) ICE AND RAIN *
- * (12) INSTRUMENTS *
- * (13) LANDING GEAR *
- * (14) LIGHTING *
- * (15) NAVIGATION *
- * (16) OXYGEN *
- * (17) PNEUMATICS *
- * (18) WATER/WASTE *
- * (19) AIRBORNE APU *
- * (20) STRUCTURE *
- * (21) DOORS *
- * (22) FUSELAGE *
- * (23) NACELLES/PYLONS *
- * (24) WINGS *
- * (25) STABILIZERS *
- * (26) WINDOWS *

$LCOST(1)=T1(IAC+1)*7.66+0.377*WTE/1000.0$
 $MCOST(1)=T1(IAC+1)*1.21+0.062*WTE/1000.0$
 DATA $LCOST(2),MCOST(2)/5.1026,4.52/$
 $LCOST(3)=T3(IAC+1)*11.19$
 $MCOST(3)=T3(IAC+1)*2.621$
 $LCOST(4)=.0276*NPASS$
 $MCOST(4)=0.0118*NPASS$
 DATA $LCOST(5),MCOST(5)/4.306,5.748/$
 $LCOST(6)=9.11+0.08496*NPASS$
 $MCOST(6)=2.38+0.05776*NPASS$
 $LCOST(7)=.213+2.29*(2.+NENG)$
 $MCOST(7)=0.365*(2.+NENG)$
 $LCOST(8)=T8(IAC+1)*6.84+0.0035*WTO/1000.$
 $MCOST(8)=T8(IAC+1)*3.876+0.00655*WTO/1000.$
 $LCOST(9)=1.114+0.0262*WTF*T9(ICGX+1)/1000.0$
 $MCOST(9)=0.595+0.0123*WTF*T9(ICGX+1)/1000.0$
 DATA $LCOST(10),MCOST(10)/3.33,3.95/$
 $LCOST(11)=.5089+0.0013*WTO/1000.0$
 $MCOST(11)=.0847+.0037*WTO/1000.0$
 $LCOST(12)=T12(IAC+1)*0.509+.009*WTE/1000.0$
 $MCOST(12)=T12(IAC+1)*0.235+.0031*WTE/1000.0$
 $LCOST(13)=4.58+.071*WTO/1000.0$
 $MCOST(13)=4.961+.181*WTO/1000.0$
 $LCOST(14)=1.51+0.01152*NPASS$
 $MCOST(14)=0.047+0.01392*NPASS$
 $LCOST(15)=T15(IAC+1)*10.077$
 $MCOST(15)=T15(IAC+1)*7.166$

```

LCOST(16)=.515+0.00265*NPASS
MCOST(16)=0.00752*NPASS
DATA AC/200./
T=DESIGN(6)*4.448/NENG
LCOST(17)=0.181+.0003*AC*T/10000.
MCOST(17)=0.0019*AC*T/10000.
LCOST(18)=.339+0.00368*NPASS
MCOST(18)=0.00768*NPASS
DATA LCOST(19),MCOST(19)/.315,.462/
LCOST(20)=3.+0.0099*WTE/1000.
DATA MCOST(20)/0./
LCOST(21)=1.147+0.006*NPASS
MCOST(21)=.387+0.00785*NPASS
LCOST(22)=1.5+0.046*WTE/1000.
DATA MCOST(22)/0.5833/
NAC=4
IF(NENG.LT.4) NAC=2
LCOST(23)=.3366*NAC
MCOST(23)=.1391*NAC
SW=DESIGN(1)/(3.281*3.281)
DATA LCOST(24)/2.9475/
MCOST(24)=0.126+0.00506*SW
DATA LCOST(25),MCOST(25)/0.8321,0.3737/
LCOST(26)=0.763+0.00043*NPASS
MCOST(26)=0.0362*NPASS
DO 50 K=1,26
LCST(K)=LCOST(K)/2.5
MCST(K)=MCOST(K)/2.5
50 CONTINUE
TLCOST=0.
TMCOST=0.
DO 75 K=1,26
TLCOST=LCST(K)+TLCOST
TMCOST=MCST(K)+TMCOST
75 CONTINUE
TENG=DESIGN(6)/ITERM(4)
*****
*   MAIN ENGINE COST   *
*****
LCOST(27)=(ITERM(4)/(4.0*2.5))*88.5*(TENG/20000.)**0.5 *
MCOST(27)=(ITERM(4)/(4.0*2.5))*109.0*(TENG/20000.)**0.5 *
COST=TLCOST+TMCOST+LCOST(27)+MCOST(27) *
COST=COST*(1.0+PX(6)*0.05) *
*****
IF(OUTPUT.EQ.0) GO TO 100
WRITE(6,86)
86 FORMAT(*1*//30X*MAINTENANCE OPERATING COSTS*//7X*NO. SYSTEM*7X
$10X*LABOR*7X*MATERIAL*)
DO 90 K=1,26
WRITE(6,88) K,XNM(K),LCOST(K),MCOST(K)
88 FORMAT(I10,2X,A10,3X,2F15.2)
90 CONTINUE
WRITE(6,92)TLCOST, TMCOST, LCOST(27), MCOST(27), COST

```

```

92 FORMAT(//5X*LABOR COST*T35,F15.2/5X*MATERIAL COST*T35,F15.2//5X
*$*ENGINE LABOR COST*T35,F15.2/5X*ENGINE MATERIAL COST*T35,F15.2
$///30X*MAINTNENACE DOC IN 1976 DOLLARS PER HOUR*F15.2)

```

```

100 RETURN

```

```

END

```

```

SUBROUTINE CNSTRN(OUTPUT)

```

```

REAL LODMA,LOD2,ANS(4),LFL,NZOACR,NZOAA

```

```

REAL PRAMCR(4),PRAMAP(4),ACR(5),AAP(5)

```

```

REAL TCCR(4),TCAP(4)

```

```

COMPLEX ROOTCR(4),ROOTAP(4)

```

```

COMMON /STRAIN/CON(59)

```

```

INTEGER OUTPUT

```

```

REAL KT1,KT2,KTDOT1,KTDOT2,DERCR(15),DERAP(15)

```

```

COMMON /CONSTR/SU(59),SL(59),XINEQ(59)

```

```

COMMON /DEVAR/DESIGN(15),ITERM(10),CST(10)

```

```

COMMON /DRAG/CDS(6),CDSAP(6)

```

```

COMMON /GEOM/W(20),HX(20),GX(35),PX(15)

```

```

COMMON /GRAVITY/CG(6)

```

```

COMMON /STAB/DERIVCR(15),DERIVAP(15),STOR(20)

```

```

COMMON /WTSVE/WTS(20)

```

```

*****

```

```

* CONSTRAINT IDENTIFICATION

```

```

*

```

```

* NO. DESCRIPTION

```

```

* *****

```

```

* 1 .....CRUISE THRUST REQUIREMENT

```

```

* 2 .....SECOND SEGMENT CLIMB GRADIENT - THRUST REQUIREMENT

```

```

* 3 .....MISSED APPROACH CLIMB GRADIENT - THRUST REQUIREMENT

```

```

* 4 .....LANDING FIELD LENGTH - WING LOADING REQUIREMENT

```

```

* 5 .....TAKE-OFF FIELD LENGTH - WING LOADING REQUIREMENT

```

```

* 6 .....LANDING GEAR - AFT CG LIMIT

```

```

* 7,8 .....STATIC STABILITY - CRUISE, APPROACH

```

```

* 9,10.....MANUEVER MARGIN - CRUISE, APPROACH

```

```

* 11 .....TAIL LIFT - APPROACH

```

```

* 12 .....NOSE GEAR UNSTICK

```

```

* 13,14.....DYNAMIC STABILITY - CRUISE, APPROACH

```

```

* 15,16.....PHUGOID FREQUENCY - CRUISE, APPROACH

```

```

* 17,18.....PHUGOID DAMPING - CRUISE, APPROACH

```

```

* 19,20.....SHORT PERIOD FREQUENCY - CRUISE, APPROACH

```

```

* 21,22.....SHORT PERIOD DAMPING - CRUISE, APPROACH

```

```

* 23,24.....TIME-TO-DOUBLE (CRUISE, APPROACH)

```

```

* 25,26.....TIME-TO-HALF (CRUISE, APPROACH)

```

```

* 27 .....FLIGHT PATH STABILITY - APPROACH

```

```

* 28,29.....VERTICAL GAIN - CRUISE, APPROACH

```

```

* 30,31.....TIME SUB THETA 2 - CRUISE, APPROACH

```

```

* 32,33.....FREQUENCY**2/VERTICAL GAIN - CRUISE, APPROACH

```

```

* 34 .....T(1) PARAMETER - APPROACH

```

```

* 35,36.....RATIO OF MODE FREQUENCIES - CRUISE, APPROACH

```

```

* 37-39.....ELEVATOR VARIANCE - CRUISE

```

```

* 40-42.....ELEVATOR VARIANCE - APPROACH

```

```

* 43,44.....VARIANCE OF ELEVATOR RATE - CRUISE, APPROACH

```

```

* 45 .....PASSENGER VOLUME LIMIT

```

```

* 46,47.....ELEVATOR DEFLECTIONS - TRIMMED (CRUISE, APPROACH)

```

```

*      48 .....CRUISE ALTITUDE *
*      49 .....CRUISE ALTITUDE ((L/D)MAX) *
*      50,51.....WING CL - CRUISE, APPROACH **
*      52 .....TAIL ASPECT RATIO LIMIT - AR(TAIL/AR(WING)) *
*****
      IOUT=OUTPUT
      IF(OUTPUT.GT.1) IOUT=0
      CON(1)=GX(30)
*****
*      FIND TAKE-OFF CL-MAX AND SECOND SEGMENT CLIMB GRADIENTS *
*****
      CLWTO=GX(8)
      CALL XLOD(CLWTO,.1,0.,EFF,-4,0)
      NENG=ITERM(4)
      CALL AT62(0.,ANS)
      TOWAV=DESIGN(6)/WTS(1)
      CL2=CLWTO/1.44
      V=(2.*WTS(1)/(DESIGN(1)*ANS(1)*CL2))**.5
      XM=V/ANS(4)
      CALL ENGINE(0.,XM,TCTM,TSFC)
      GRAD=0.030
      CALL XLOD(CL2,.1,0.,LOD2,0,0)
      IF(ITERM(4).EQ.3) GRAD=0.027
      IF(ITERM(4).EQ.2) GRAD=0.024
      TOWRQ2=(NENG/(NENG-1.))* (1./LOD2+SIN(GRAD))* (1./TCTM)
      CON(2)=TOWAV/TOWRQ2
*****
*      NOSE GEAR UNSTICK *
*****
      ZACT=4.0/W(10)
      XMUF=0.025
      ZACLG=2.*ZACT
      XLT=HX(6)*DESIGN(1)*W(10)/DESIGN(4)
      CALL AT62(0.,ANS)
      VSTALL=(WTS(1)*2.0/(DESIGN(1)*ANS(1)*GX(8))**.5
      VLO=VSTALL*0.9
      CLW=(STOR(6)*(W(2)-GX(17)-3.0))/GX(2)
      Q=0.5*ANS(1)*VLO*VLO
      XLW=Q*DESIGN(1)*CLW*1.2
      XMW=1.05*Q*DESIGN(1)*(W(19)+W(17))*W(10)
      C1=XLT+(0.25-CG(5)-XMUF*ZACLG)*W(10)
      UNTHRU=DESIGN(6)
      IF(ITERM(4).EQ.3) UNTHRU=DESIGN(6)/3.0
      XCG=CG(3)
      COIT=HX(12)
C
C      TAIL INCIDENCE SET TO WORSE CASE FOR TAKE-OFF (BOEING)
C
      IF(GX(16).NE.-99.0) COIT=GX(16)
      XLTRQ=(XMW+ZACT*W(10)*.9*UNTHRU+W(10)*(XCG-.25)*XLW
$ -W(10)*(CG(5)-CG(3)+ZACLG*XMUF)*(WTS(1)-XLW))/C1
      DEMAX=20.
      XLTAV=STOR(7)*HX(6)*.9*((1.-STOR(3))*(W(2)-GX(17)-3.0)

```

\$-W(2)+COIT-HX(3)*DEMAX)*Q*DESIGN(4)/GX(2)

C
C
C

GROUND EFFECTS—DATCOM FUNCTION OF GEOMETRIC ALPHA

TLGE=.355*Q*DESIGN(4)

XLTAV2=XLTAV+TLGE

CLTAV=XLTAV2/(Q*DESIGN(4))

IF (CLTAV.GT.1.5) XLTAV2=-1.5*Q*DESIGN(4)

CON(12)=XLTAV2/XLTRQ

IF (OUTPUT.EQ.1) WRITE(6,548) ZACT,XMUF,ZACLG,ANS,VSTALL,CLW

\$,Q,XLW,XMW,C1,UNTHRU,XCG,XLTRQ,CL2,COIT,XLT

\$,XLTAV,CON(12),STOR(7),STOR(8),W(2),GX(17),HX(6),W(10)

\$,XLTAV2,TLGE,CLTAV

548 FORMAT(*1*//20X*DEBUG OF NOSE GEAR UNSTICK*///

\$10X"ZACT,XMUF,ZACLG="3F15.4/

\$ 10X"ANS(1,2,3,4)=" 4F15.6/

\$ 10X"VSTALL,CLW,Q,XLW,XMW="5F15.4/

\$ 10X"C1,UNTHRU,XCG,XLTRQ,CL2,COIT,XLT="7F12.4/

\$ 10X"XLTAV,CON(12),STOR(7),STOR(8),W(2)="5F15.4/

\$ 10X"GX(17),HX(6),W(10),XLTAV2,TLGE,CLTAV="6F15.4/)

* FIND APPROACH CL-MAX AND MISSED APPROACH CLIMB GRADIENTS *
* SET UP APPROACH WITH FORWARD CG AND 45 DEG FLAPS *

CLWMAX=GX(12)

CALL XLOD(CLWMAX,.1,0.,EFF,-3,0)

CLS=CLWMAX

GRAD=GRAD-.003

CLA=CLS/1.69

V=(2.*WTS(1)*GX(27)/(DESIGN(1)*ANS(1)*CLA)**0.5

XM=V/ANS(4)

CALL ENGINE(0.,XM,TCTM,TSFC)

GX(10)=CLA

CALL XLOD(CLA,.1,0.,LODMA,-2,0)

TOWRQ3=(NENG/(NENG-1.))* (1./LODMA+SIN(GRAD))* (1./TCTM)

TOWAV3=DESIGN(6)/(WTS(1)*GX(27))

CON(3)=TOWAV3/TOWRQ3

VA2=GX(27)*WTS(1)*498.23/(DESIGN(1)*CLA)

VA=VA2**0.5

GX(14)=VA*1.6881

LFL=0.29875*VA2+25.

CON(4)=LFL

TOWAV=DESIGN(6)/WTS(1)

TOP=(WTS(1)/DESIGN(1))/(CLWTO*TOWAV)

TOFL=(31.7*TOP)+910.0

CON(5)=TOFL

CON(6)=CG(5)-CG(6)-DESIGN(7)

VOLPAS=GX(19)*52.

PASSL=DESIGN(3)-1.2*GX(15)-.5*GX(33)

VOLAV=GX(1)*GX(5)*GX(5)*PASSL/8.

CON(45)=VOLAV/VOLPAS

CLTAIL=HX(11)

```

*      DATA BASE ASSIGNMENTS      *
*****
CON(11)=CLTAIL
CON(46)=HX(14)
CON(47)=HX(13)
CON(48)=WTS(11)
CON(49)=WTS(12)
CON(50)=GX(28)
CON(51)=GX(29)
CON(52)=DESIGN(5)/DESIGN(2)
*****
*      THIS ENDS DESIGN CONSTRAINT SECTION, AND BEGINS HANDLING QUALITY      *
*      CONSTRAINT SECTION                                                    *
*****
CALL XLOD(CLA, .1, 500., EFF, -1, IOUT)
CALL XLOD(GX(9), GX(3), WTS(11), EFF, 2, 0)
CON(7)=CG(1)-STOR(4)
CON(8)=CG(2)-STOR(9)
CON(9)=CG(1)-STOR(5)
CON(10)=CG(2)-STOR(10)
*****
*      CALCULATE DIMENSIONAL DERIVATIVES      *
*****
CALL AT62(WTS(11), ANS)
UOCR=GX(3)*ANS(4)
CALL DIMDER(UOCR, 1, DERCR)
CALL DIMDER(GX(14), 0, DERAP)
IF(OUTPUT.EQ.1) WRITE(6, 28) DERCR, DERAP
28 FORMAT(*1*//30X*// / / DIMENSIONAL STABILITY DERIVATIVES/ / / *
$ //10X*DERCR=*//5(T30, 3F12.4//10X*DERAP=*//5(T30, 3F12.4//)
CON(13)=DERCR(4)*DERCR(3)-DERCR(1)*DERCR(6)
CON(14)=DERAP(4)*DERAP(3)-DERAP(1)*DERAP(6)
IFULL=1
IF(IFULL.GT.0) GO TO 30
*****
*      THIS NEXT SECTION APPROXIMATES AIRCRAFT DYNAMIC PROPERTIES      *
*****
TPHUGCR=DERCR(1)*DERCR(9)-UOCR*DERCR(3)
OMPH2=GX(15)*(DERCR(3)*DERCR(4)-DERCR(6)*DERCR(1))/TPHUGCR
OMPH=(ABS(OMPH2))**.5
CON(15)=OMPH
TPHUGAP=DERAP(1)*DERAP(9)-GX(14)*DERAP(3)
OMPHA2=GX(15)*(DERAP(3)*DERAP(4)-DERAP(6)*DERAP(1))/TPHUGAP
OMPHA=(ABS(OMPHA2))**.5
CON(16)=OMPHA
TTT=-DERCR(5)-(DERCR(6)*(DERCR(2)*UOCR-GX(15)))/TPHUGCR
ZETAPH=TTT/(2.0*OMPH)
CON(17)=ZETAPH
TTTA=-DERAP(5)-(DERAP(6)*(DERAP(2)*GX(14)-GX(15)))/TPHUGAP
ZETAPHA=TTTA/(2.0*OMPHA)
CON(18)=ZETAPHA
OMSP2=DERCR(9)*DERCR(1)-DERCR(3)*UOCR
OMSP=(ABS(OMSP2))**.5

```

```

CON(19)=OMSP
OMSPA2=DERAP(9)*DERAP(1)-DERAP(3)*GX(14)
OMSPA=(ABS(OMSPA2))*0.5
CON(20)=OMSPA
TXT=-(DERCR(1)+DERCR(9)+UOCR*DERCR(12))
ZETASP=TXT/(2.0*OMSP)
CON(21)=ZETASP
TXTA=-(DERAP(1)+DERAP(9)+GX(14)*DERAP(12))
ZETASPA=TXTA/(2.0*OMSPA)
CON(22)=ZETASPA
*****
*      CALCULATE EXACT DYNAMICS FROM FOURTH ORDER MODEL      *
*****
30 CALL LONGRT(DERCR,UOCR,ROOTCR,PRAMCR,ACR,NOCR,TCCR)
   CALL LONGRT(DERAP,VA,ROOTAP,PRAMAP,AAP,NOAP,TCAP)
   IF(IFULL.LT.1) GO TO 45
   OMPH=PRAMCR(1)
   ZETAPH=PRAMCR(2)
   OMSP=PRAMCR(3)
   ZETASP=PRAMCR(4)
   OMPHA=PRAMAP(1)
   ZETAPHA=PRAMAP(2)
   OMSPA=PRAMAP(3)
   ZETASPA=PRAMAP(4)
45 IF(OUTPUT.LT.1) GO TO 50
   IF(OUTPUT.GT.1) GO TO 50
   WRITE(6,31)
31 FORMAT(*1*///30X*LONGITUDINAL DYNAMICS*//20X*// CRUISE// *)
   WRITE(6,32) ACR
32 FORMAT(/10X*COEFFICIENTS=*5F15.6)
   WRITE(6,33) ROOTCR
33 FORMAT(/10X*ROOTS (REAL,IMAGINARY)*//4(2F15.4/))
   WRITE(6,35) PRAMCR
35 FORMAT(/10X*PHUGOID FREQUENCY*T35,F15.4/10X
$*PHUGOID DAMPING*T35,F15.4/10X*SHORT PER. FREQ.*
$T35,F15.4/10X*SHORT PER. DAMPING*T35,F15.4)
   WRITE(6,36) NOCR,TCCR
36 FORMAT(/10X*NO. OF NON-OSCILLATORY ROOTS=*I11
$ /10X*TIME CONSTANTS=*T35,4F15.4)
   WRITE(6,37)
37 FORMAT(/20X*// APPROACH// *)
   WRITE(6,32) AAP
   WRITE(6,33) ROOTAP
   WRITE(6,35) PRAMAP
   WRITE(6,36) NOAP,TCAP
   WRITE(6,48) GX(8),CLWTO,CL2,GX(12),CLWMAX,CLA
48 FORMAT(/10X*CL-MAX TO (W),CL-MAX TO (AC),CL2*T60,3F10.3/
$ 10X*CL-MAX (W), CL-MAX (AC), CLA=*T60,3F10.3)
50 IF(IFULL.LT.1) GO TO 100
   CON(15)=OMPH
   CON(16)=OMPHA
   CON(17)=ZETAPH
   CON(18)=ZETAPHA

```

```

CON(19)=OMSP
CON(20)=OMSPA
CON(21)=ZETASP
CON(22)=ZETASPA
OMSP2=OMSP*OMSP
OMSPA2=OMSPA*OMSPA
IF(OMSP.EQ.0.) OMSP=1.0E-20
IF(OMSPA.EQ.0.) OMSPA=1.0E-20
IF(OMPH.EQ.0.) OMPH=1.0E-20
IF(OMPHA.EQ.0.) OMPHA=1.0E-20
GREAT=-999.
100 IF(NOCR.LT.1) GO TO 210
DO 209 K=1,NOCR
IF(TCCR(K).LT.0.0) GO TO 209
IF(TCCR(K).GT.GREAT) GREAT=TCCR(K)
209 CONTINUE
210 TDOUBCR=-0.693/(OMPH*ZETAPH)
T1=-0.693/(OMSP*ZETASP)
T2=0.693/GREAT
IF(TDOUBCR.GT.T1.AND.T1.GT.0.0) TDOUBCR=T1
IF(T2.LT.0.0) GO TO 219
IF(TDOUBCR.LT.0.0.OR.TDOUBCR.GT.T2) TDOUBCR=T2
219 IF(TDOUBCR.LT.0.0) TDOUBCR=99.
CON(23)=TDOUBCR
GREAT=-999.
IF(NOAP.LT.1) GO TO 230
DO 231 K=1,NOAP
IF(TCAP(K).LT.0.0) GO TO 231
IF(TCAP(K).GT.GREAT) GREAT=TCAP(K)
231 CONTINUE
230 TDOUBAP=-0.693/(OMPHA*ZETAPHA)
T1=-0.693/(OMSPA*ZETASPA)
T2=0.693/GREAT
IF(TDOUBAP.GT.T1.AND.T1.GT.0.0) TDOUBAP=T1
IF(T2.LT.0.0) GO TO 239
IF(TDOUBAP.LT.0.0.OR.TDOUBAP.GT.T2) TDOUBAP=T2
239 IF(TDOUBAP.LE.0.) TDOUBAP=99.
CON(24)=TDOUBAP
THALF=-99.
THALFA=-99.
IF(OMSP.EQ.1.0E-20) OMSP=-1.0E-20
IF(OMSPA.EQ.1.0E-20) OMSPA=-1.0E-20
IF(OMPH.EQ.1.0E-20) OMPH=-1.0E-20
IF(OMPHA.EQ.1.0E-20) OMPHA=-1.0E-20
GREAT=-999.
IF(NOCR.LT.1) GO TO 245
IF(TDOUBCR.NE.99.) GO TO 250
DO 242 K=1,NOCR
IF(TCCR(K).GT.0.0) GO TO 242
IF(TCCR(K).GT.GREAT) GREAT=TCCR(K)
242 CONTINUE
245 THALF=0.693/(OMPH*ZETAPH)
T1=0.693/(OMSP*ZETASP)

```

```

T2=-0.693/GREAT
IF (THALF.LT.T1.AND.T1.GT.0.0) THALF=T1
IF (THALF.LT.T2.AND.T1.GT.0.0) THALF=T2
IF (THALF.LE.0.) THALF=-99.
250 CON(25)=THALF
GREAT=-999.
IF(NOAP.LT.1) GO TO 255
IF(TDOUBAP.NE.99.) GO TO 260
DO 252 K=1,NOAP
IF(TCAP(K).GT.0.0) GO TO 252
IF(TCAP(K).GT.GREAT) GREAT=TCAP(K)
252 CONTINUE
255 THALFA=0.693/(OMPHA*ZETAPHA)
T1=0.693/(OMSPA*ZETASPA)
T2=-0.693/GREAT
IF (THALFA.LT.T1.AND.T1.GT.0) THALFA=T1
IF (THALFA.LT.T2.AND.T2.GT.0) THALFA=T2
IF (THALFA.LE.0.) THALFA=-99.
260 CON(26)=THALFA
TDEL=DERAP(13)/DERAP(15)
TZT=(DERAP(6)*DERAP(4)-DERAP(6)*DERAP(1))/
$ (-DERAP(1)+DERAP(3)*TDEL)
TYT=(DERAP(4)-TDEL*DERAP(6))/(DERAP(1)-DERAP(3)*TDEL)
DGDU=(DERAP(5)-(DERAP(2)-GX(15)/GX(14))*TYT-DERAP(14)*TZT
$/DERAP(15))/GX(15)
CON(27)=DGDU
ZZT=UOCR*(DERCR(13)*DERCR(3)-DERCR(15)*DERCR(1))
NZOACR=ZZT/((DERCR(15)-DERCR(13)*DERCR(9)/UOCR)*GX(15))
CON(28)=NZOACR
ZZTA=GX(14)*(DERAP(13)*DERAP(3)-DERAP(15)*DERAP(1))
NZOAA=ZZTA/((DERAP(15)-DERAP(13)*DERAP(9)/GX(14))*GX(15))
CON(29)=NZOAA
TTH2=ZZT/(UOCR*(DERCR(15)+DERCR(13)*DERCR(12)))
CON(30)=TTH2
TTHA2=ZZTA/(GX(14)*(DERAP(15)+DERAP(13)*DERAP(9)))
CON(31)=TTHA2
CON(32)=OMSP2/NZOACR
CON(33)=OMSPA2/NZOAA
PIARE=1./(GX(1)*DESIGN(2)*W(7))
TAL=GX(14)/(2.0*GX(15)*(1./CDSAP(4)-2.*PIARE*GX(10)))
CON(34)=TAL
IF(OMPH*OMPH.GT.0.) GO TO 80
CON(35)=99.
GO TO 82
80 CON(35)=OMSP/OMPH
82 IF(OMPHA*OMPHA.GT.0.) GO TO 84
CON(36)=99.
GO TO 86
84 CON(36)=OMSPA/OMPHA
*****
* THE FOLLOWING SECTION CALCULATES THE RESPONSE OF A PITCH *
* ATTITUDE HOLD/RATE COMMAND AUTOPILOT IN TURBULENCE. *
*****

```

```

86 WCR2=NZOACR
WCR=WCR2**0.5
DZETA=.7
DM=DERCR(15)+DERCR(3)
DM1=1.-DERCR(12)*DERCR(12)*DERCR(15)*WCR2/DM
DM2=2.*DZETA*WCR*DERCR(12)*DERCR(15)-DERCR(15)-DERCR(3)*DERCR(15)
KTDOT1=2.*DZETA*WCR*(DERCR(12)*UOCR-1.)-DERCR(9)-DERCR(3)*UOCR
$ +DERCR(12)*WCR2*(1.-DERCR(12)*UOCR)/DM
KTDOT1=KTDOT1/(DM1*DM2)
KT1=WCR2*(1.-DERCR(12)*UOCR)+KTDOT1*WCR2*DERCR(12)*DERCR(15)
KT1=KT1/DM
XNUM=((DERCR(9)/UOCR)**2.0)*(KT1*KT1-KTDOT1*KTDOT1*(2.0*DZETA
$*WCR+WCR*WCR*GX(11)/(UOCR)))
TSTO=WCR2*GX(11)/UOCR
DENOM=TSTO-(1.+2.*DZETA*TSTO/WCR)*(2.*DZETA*WCR+TSTO)
SIG=(ABS(XNUM/DENOM))**0.5
CON(37)=3.0*SIG
HX(15)=3.0*SIG

```

C
C
C

ASSUME THAT CRUISE RMS IS 3 FT/SEC

```

CON(38)=KTDOT1
CON(39)=KT1
WA2=NZOAA.
WA=WA2**0.5
DM=DERAP(15)+DERAP(3)
DM1=1.-DERAP(12)*DERAP(12)*DERAP(15)*WA2/DM
DM2=2.*DZETA*WA*DERAP(12)*DERAP(15)-DERAP(15)-DERAP(3)*DERAP(15)
KTDOT2=2.*DZETA*WA*(DERAP(12)*GX(14)-1.)-DERAP(9)-DERAP(3)*GX(14)
$ +DERAP(12)*WA2*(1.-DERAP(12)*GX(14))/DM
KTDOT2=KTDOT1/(DM1*DM2)
KT2=WA2*(1.-DERAP(12)*GX(14))+KTDOT1*WA2*DERAP(12)*DERAP(15)
KT2=KT1/DM
XNUM=((DERAP(9)/GX(14))**2.0)*(KT2*KT2-KTDOT2*KTDOT2*(2.*WA*DZETA
$+WA2*GX(11)/(GX(14))))
TSTO=WA2*GX(11)/GX(14)
DENOM=TSTO-(1.+2.*DZETA*TSTO/WA)*(2.0*DZETA*WA+TSTO)
SIGA=(ABS(XNUM/DENOM))**0.5
CON(40)=7.0*SIGA
GX(13)=7.0*SIGA

```

C
C
C

ASSUME THAT APPROACH RMS IS 7 FT/SEC

```

CON(41)=KTDOT2
CON(42)=KT2
TA=HX(10)
TUR=GX(11)/UOCR
AO=TUR*TA
A2=TA*(2.*DZETA*WCR+WCR2*TUR)+1.+2.*DZETA*WCR*TUR
A1=TA*(1.+2.*DZETA*WCR*TUR+TUR)
A3=WCR2*(TA+TUR)+2.*DZETA*WCR
A4=WCR
VV1=-A1*A4+A2*A3

```

```

XNUM=(1./TA)*(DERCR(9)/UOCR)*KTDOT1*KTDOT1*VV1
XNUM=XNUM-A3*TUR*(DERCR(9)/UOCR)**2.0*KT1*KT1
DEN=AO*A3*A3+A1*(A1*A4-A2*A3)
SIGDOT=(ABS(XNUM/DEN))**0.5
CON(43)=3.0*SIGDOT
TUR=GX(11)/GX(14)
AO=TUR*TA
A2=TA*(2.*DZETA*WA+WA2*TUR)+1.+2.*DZETA*TUR*WA
A1=TA*(1.+2.*DZETA*WA*TUR+TUR)
A3=WA2*(TA+TUR)+2.*DZETA*WA
A4=WA2
VV1=-A1*A4+A2*A3
XNUM=XNUM-A3*TUR*(DERAP(9)/UOCR)**2.0*KT2*KT2
DEN=AO*A3*A3+A1*(A1*A4-A2*A3)
SIGDOTA=(ABS(XNUM/DEN))**0.5
CON(44)=7.0*SIGDOTA
*****
*      OUTPUT SECTION      *
*****
      IF(OUTPUT.EQ.0) GO TO 999
      WRITE(6,102)
102 FORMAT(*1*///20X*AIRCRAFT OPTIMIZATION CONSTRAINTS*//5X
$*DESIGN CONSTRAINTS*/14X*ID*5X*CONSTRAINT*T49*VALUE*
$9X*SL*10X*SU*9X*VIOLATION?*)
      WRITE(6,112) (I,CON(I),SL(I),SU(I),XINEQ(I),I=1,6)
112 FORMAT(/10X,I5,* CRUISE THRUST*T45,4F12.4/10X,I5,* 2ND SEGMENT C
$LIMB*T45,4F12.4/10X,I5,* MISSED APPROACH CLIMB*T45,4F12.4/10X,I5
$* LANDING*T45,4F12.4/10X,I5* TAKE-OFF*T45,4F12.4/10X,I5
$* LANDING GEAR LIMIT*T45,4F12.4)
      WRITE(6,116) CON(45),SL(45),SU(45),XINEQ(45)
116 FORMAT(13X*45 PASSENGER VOLUME*T45,4F12.4)
      WRITE(6,117) CON(48),SL(48),SU(48),XINEQ(48)
117 FORMAT(13X*48 CRUISE ALTITUDE*T45,4F12.4)
      WRITE(6,118) CON(49),SL(49),SU(49),XINEQ(49)
118 FORMAT(13X*49 CRUISE ALTITUDE(L/D(MAX))*T45,4F12.4)
      WRITE(6,119) CON(50),SL(50),SU(50),XINEQ(50),
$ CON(51),SL(51),SU(51),XINEQ(51)
119 FORMAT(13X*50 CRUISE WING CL*T45,4F12.4/
$ 13X*51 APPROACH WING CL*T45,4F12.4)
      WRITE(6,120) CON(52),SL(52),SU(52),XINEQ(52)
120 FORMAT(13X*52 AR(TAIL)/AR(WING)*T45,4F12.4)
      WRITE(6,122)
122 FORMAT(/5X*HANDLING QUALITY CONSTRAINTS*)
      WRITE(6,128) (I,CON(I),SL(I),SU(I),XINEQ(I),I=7,10)
128 FORMAT(/10X,I5* STATIC STAB. (CR)*T45,4F12.4/10X,I5
$* STATIC STAB. (AP)*
$T45,4F12.4/10X,I5* MANEUVER MARGIN (CR)*T45,4F12.4/10X,I5
$* MANEUVER MARGIN (AP)*T45,4F12.4)
      WRITE(6,132) (I,CON(I),SL(I),SU(I),XINEQ(I),I=11,15)
132 FORMAT(10X,I5* TAIL LIFT (AP)*T45,4F12.4/10X,I5* NOSE GEAR UNSTI
$CK*T45,4F12.4/10X,I5* DYN. STAB. (CR)*T45,4F12.4/10X,I5
$* DYN. STAB. (AP)*T45,4F12.4/10X,I5* PHUGOID FREQ (CR)*T45,
$4F12.4)

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```

WRITE(6,136) (I,CON(I),SL(I),SU(I),XINEQ(I),I=16,20)
136 FORMAT(10X,I5* PHUGOID FREQ (AP)*T45,4F12.4/10X,I5
$* PHUGOID DAMPING (CR)*T45,4F12.4/10X,I5* PHUGOID DAMPING (AP)*
$T45,4F12.4/10X,I5* SHORT PER. FREQ. (CR)*T45,4F12.4/10X,I5
$* SHORT PER. FREQ. (AP)*T45,4F12.4)
WRITE(6,141) (I,CON(I),SL(I),SU(I),XINEQ(I),I=21,25)
141 FORMAT(10X,I5* SHORT PER. DAMP (CR)*T45,4F12.4/10X,I5
$* SHORT PER. DAMP (AP)*T45,4F12.4/10X,I5* TIME-TO-DOUBLE (CR)*
$T45,4F12.4/10X,I5* TIME-TO-DOUBLE (AP)*T45,4F12.4/10X,I5
$* TIME-TO-HALF (CR)*T45,4F12.4)
WRITE(6,146) (I,CON(I),SL(I),SU(I),XINEQ(I),I=26,30)
146 FORMAT(10X,I5* TIME-TO-HALF (AP)*T45,4F12.4/10X,I5
$* FLIGHT PATH STAB. (AP)*T45,4F12.4/10X,I5* VERT. GAIN (CR)*
$T45,4F12.4/10X,I5* VERT. GAIN (AP)*T45,4F12.4/10X,I5
$* T(THETA(2)) (CR)*T45,4F12.4)
WRITE(6,147) (I,CON(I),SL(I),SU(I),XINEQ(I),I=31,40)
147 FORMAT(10X,I5* T(THETA(2)) (AP)*T45,4F12.4/10X,I5* WW/NZA (CR)*
$T45,4F12.4/10X,I5* WW/NZA (AP)*T45,4F12.4/10X,I5* T(1) (AP)*
$T45,4F12.4/10X,I5* MODE RATIO (CR)*T45,4F12.4/10X,I5
$* MODE RATIO (AP)*T45,4F12.4/10X,I5* ELE. VAR. (CR)*T45,4F12.4
$/10X,I5* THETA-DOT GAIN (CR)*T45,4F12.4/10X,I5* THETA GAIN*
$T45,4F12.4/10X,I5* ELE. VAR. (AP)*T45,4F12.4)
WRITE(6,152) (I,CON(I),SL(I),SU(I),XINEQ(I),I=41,44)
152 FORMAT(10X,I5* THETA-DOT GAIN (AP)*T45,4F12.4/10X,I5
$* THETA GAIN (AP)*T45,4F12.4/10X,I5* ELE-DOT VAR. (CR)*T45,
$4F12.4/10X,I5* ELE-DOT VAR. (AP)*T45,4F12.4)
WRITE(6,157) (I,CON(I),SL(I),SU(I),XINEQ(I),I=46,47)
157 FORMAT(10X,I5* TRIM ELEVATOR (CR)*T45,4F12.4/
$10X,I5* TRIM ELEVATOR (AP)*T45,4F12.4)
WRITE(6,167)
167 FORMAT(1H1/)
999 RETURN
END
SUBROUTINE DIMDER(U,ICR,C)
REAL C(15),A(15),ANS(4)
COMMON /DEVAR/DESIGN(15),ITRM(10),CST(10)
COMMON /DRAG/CDS(6),CDSAP(6)
COMMON /GEOM/W(20),HX(20),GX(35),PX(15)
COMMON /STAB/DERIVCR(15),DERIVAP(15),STOR(20)
COMMON /WTSVE/WTS(20)
*****
* DIMDER CONVERTS FROM NON-DIMENSIONAL TO DIMENSIONAL STABILITY *
* DERIVATIVES. *
*****
IF(ICR.EQ.0) GO TO 20
DO 15 I=1,15
15 A(I)=DERIVCR(I)
XMU=WTS(7)
CALL AT62(WTS(11),ANS)
DRAG=CDS(5)
XIY=WTS(13)
CL=GX(9)
WT=WTS(15)

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GO TO 30
20 DO 25 I=1,15
25 A(I)=DERIVAP(I)
   XMU=WTS(9)
   CALL AT62(500.,ANS)
   DRAG=CDSAP(5)
   XIY=WTS(14)
   CL=GX(10)
   WT=WTS(1)*GX(27)
30 T1=ANS(1)*DESIGN(1)*U*32.174/WT
   C(1)=T1*(-A(1)-DRAG)/2.0
   C(2)=T1*(CL-A(2))/2.0
   T2=ANS(1)*DESIGN(1)*U/(2.0*XIY)
   C(3)=A(3)*W(10)*T2
   C(4)=T1*(-CL-A(4))
   C(5)=T1*(-DRAG-A(5))
   C(6)=W(10)*A(6)*2.0*T2
   C(7)=-W(10)*A(7)*2.0*T2
   C(8)=0.
   C(9)=W(10)*W(10)*A(9)*T2/2.0
   C(10)=-A(10)/(4.0*XMU)
   C(11)=0.
   C(12)=ANS(1)*DESIGN(1)*W(10)*W(10)*A(12)/(4.0*XIY)
   C(13)=-T1*U*A(13)/2.
   C(14)=-T1*U*A(14)/2.
   C(15)=T2*U*W(10)*A(15)
   RETURN
   END
   SUBROUTINE LONGRT(DIM,U,ROOT,PARAM,A,NO,TCNST)
   REAL DIM(15),PARAM(4),A(5),OM(2),ZET(2)
   REAL TCNST(4)
   COMPLEX ROOT(4),COM(4)
*****
*   LONGRT FINDS ROOTS OF FOURTH ORDER DYNAMICS MODEL   *
*****
   A(1)=1.
   A(2)=-DIM(9)-U*DIM(12)-DIM(1)-DIM(5)
   A(3)=DIM(1)*DIM(9)-DIM(3)*U-DIM(2)*DIM(4)+DIM(5)*(DIM(9)+U*DIM(12)
$+DIM(1))
   A(4)=-DIM(5)*(DIM(1)*DIM(9)-U*DIM(3))+DIM(4)*(DIM(2)*DIM(9)
$+32.174*DIM(12))-DIM(6)*(U*DIM(2)-32.174)
   A(5)=32.174*(DIM(4)*DIM(3)-DIM(6)*DIM(1))
   IDEGRE=4
   CALL RPOLY(IDEGRE,A,ROOT,IERR)
   IF(IERR.LT.0) WRITE(6,22) IDEGRE
22 FORMAT(*1*///*ROOT SOLVER BROKE DOWN—ONLY*15* TERMS FOUND*//)
   OM(1)=0.
   OM(2)=0.
   ZET(1)=1.
   ZET(2)=1.
   DO 25 I=1,4
   TCNST(I)=0.
   PARAM(I)=0.

```



```

25 CONTINUE
   ICOM=0
   ICON=0
C
C   ASSUME THE ROOTS ARE GIVEN IN PAIRS
C
   DO 35 IROOT=1,4
   D=AIMAG(ROOT(IROOT))
   IF(D.EQ.0.0) GO TO 30
   ICOM=ICOM+1
   COM(ICOM)=ROOT(IROOT)
   GO TO 35
30 ICON=ICON+1
   TCONST(ICON)=ROOT(IROOT)
35 CONTINUE
   JCOM=0
   IF(ICOM.LT.1) GO TO 200
   DO 40 I=1,ICOM,2
   D=AIMAG(COM(I))
   E=COM(I)
   JCOM=JCOM+1
   OM(JCOM)=(D*D+E*E)**0.5
   ZET(JCOM)=-E/OM(JCOM)
40 CONTINUE
200 NO=ICON
*****
*   PHUGOID(1,2); SHORT PERIOD(3,4)   *
*****
   IF(OM(1).GT.OM(2)) GO TO 250
210 PARAM(3)=OM(2)
   PARAM(4)=ZET(2)
   PARAM(1)=OM(1)
   PARAM(2)=ZET(1)
   GO TO 275
250 IF(OM(1).LT.0.8) GO TO 210
   PARAM(3)=OM(1)
   PARAM(4)=ZET(1)
   PARAM(1)=OM(2)
   PARAM(2)=ZET(2)
275 IF(NO.LT.1) GO TO 999
   SMALL=100.
   SMALL2=100.
   DO 300 I=1,NO
   IF(TCONST(I).LT.SMALL) SMALL=TCONST(I)
300 CONTINUE
   DO 310 I=1,NO
   IF(TCONST(I).LT.SMALL2.AND.TCONST(I).NE.SMALL)
   $ SMALL2=TCONST(I)
310 CONTINUE
   R12=ABS(SMALL*SMALL2)
   ZT=- (SMALL+SMALL2)/(2.0*R12**0.5)
   IF(R12.EQ.0.0) ZT=0.
   IF(PARAM(3).EQ.0.) PARAM(3)=R12**0.5

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```
IF(PARAM(4).EQ.1.0) PARAM(4)=ZT
999 RETURN
END
```

APPENDIX II - SAMPLE INPUT DECK

MIL 8785B LEVEL III (SIMPACT)	(Title)
7 52	(Number of design variables, Number of constraints)
-.2170 .3383 -.1576 -.1123 -.3620 .0358 .1895	(Initial XBAR)
1 1000. 4000.	(Design variable number, lower bound, upper bound)
2 3. 15.	
3 120. 260.	
4 100. 1600.	
5 2. 15.	
6 10000. 120000.	
7 -0.5 1.	
1 1. 2.	(Constraint number, lower bound, upper bound)
2 1. 5.	
3 1. 5.	
4 1000. 8000.	
5 2000. 10000.	
6 0. 1.0	
7 -999. 999.	
8 -1.0 -0.10	
9 -999. 999.	
10 -999. 999.	
11 -.8 .8	
12 1. 3.00	
13 -999. 999.	
14 -999. 999.	
15 -999. 999.	
16 -999. 999.	
17 -999. 999.	
18 -999.0 999.0	
19 -999. 999.	
20 -999. 999.	
21 -999.0 999.0	
22 -999.0 999.0	
23 -999. 999.	
24 -999. 999.	
25 -999. 999.	
26 -999. 999.	
27 -3. .24	
28 -999. 999.	
29 -999. 999.	
30 -999. 999.	
31 -999. 999.	
32 -999.0 999.0	
33 -999.0 999.0	
34 -999. 999.	
35 -999. 999.	
36 -999. 999.	
37 -999. 999.	
38 -999. 999.	

39 -999. 999.
 40 -999. 999.
 41 -999. 999.
 42 -999. 999.
 43 -999. 999.
 44 -999. 999.
 45 1. 2.5
 46 -1. 1.
 47 -1. 1.0
 48 30000. 46000.
 49 30000. 52000.
 50 .1 .75
 51 1. 2.7
 52 0. 1.

2
 1. 1.0E-6 1.0E10 .2 0
 190000.
 0. 0. 0. 0. 0. 0. 0. 0.
 1 0 7 2 1 1979 0 0 0 0
 .75 .65
 21.2 2.0 .38 .14 5.
 .98 .850 0.3 -.15 -1.
 -.15 -.25 -.12 .025
 .4 .1 .46 .2
 .08 .36 1.8 35. .3
 .8 3000. 16.667 22.58 8.33
 2.2 1443.38 3.15 -5.25 -12.725
 200. 8370. 41100. 7500.
 4.0 .55 .09 3200. .70
 30. 0. -99.

(Number of calls to NELMIN)
 (SCF, REQMIN, CAYY, STEP, ILINE)
 (WTS(1))
 (PX(1-- 8))
 (ITERM(1-- 10))
 (WTS(16), CG(5))
 (W(1-- 5))
 (W(6-- 8, 14, 16))
 (W(17-- 20))
 (HX(1-- 3, 10))
 (HX(16-- 20))
 (GX(3-- 7))
 (GX(8, 11, 12, 17, 18))
 (GX(19-- 22))
 (GX(23-- 27))
 (GX(32, 34, 16))

APPENDIX III - SAMPLE OUTPUT CORRESPONDING TO SAMPLE INPUT

RUN NO- MIL 8705B LEVEL III (SIMPACT)

NO. OF VARIABLES=		7				
NO. OF CONSTRAINTS=		52				
VARIABLES=		-.2170	.3383	-.1576	-.1123	-.3620
J, XL, XU, AVE, AMP=	1	1000.0000	4000.0000		2500.0000	1500.0000
J, XL, XU, AVE, AMP=	2	3.0000	15.0000		9.0000	6.0000
J, XL, XU, AVE, AMP=	3	120.0000	260.0000		190.0000	70.0000
J, XL, XU, AVE, AMP=	4	100.0000	1600.0000		250.0000	750.0000
J, XL, XU, AVE, AMP=	5	2.0000	15.0000		8.5000	6.5000
J, XL, XU, AVE, AMP=	6	10000.0000	120000.0000		65000.0000	55000.0000
J, XL, XU, AVE, AMP=	7	-.5000	1.0000		.2500	.7500
I, SL(I), SU(I)=	1	1.00	2.00			
I, SL(I), SU(I)=	2	1.00	5.00			
I, SL(I), SU(I)=	3	1.00	5.00			
I, SL(I), SU(I)=	4	1000.00	8000.00			
I, SL(I), SU(I)=	5	2000.00	10000.00			
I, SL(I), SU(I)=	6	0.00	1.00			
I, SL(I), SU(I)=	7	-999.00	999.00			
I, SL(I), SU(I)=	8	-1.00	-.10			
I, SL(I), SU(I)=	9	-999.00	999.00			
I, SL(I), SU(I)=	10	-999.00	999.00			
I, SL(I), SU(I)=	11	-.80	.00			
I, SL(I), SU(I)=	12	1.00	3.00			
I, SL(I), SU(I)=	13	-999.00	999.00			
I, SL(I), SU(I)=	14	-999.00	999.00			
I, SL(I), SU(I)=	15	-999.00	999.00			
I, SL(I), SU(I)=	16	-999.00	999.00			
I, SL(I), SU(I)=	17	-999.00	999.00			
I, SL(I), SU(I)=	18	-999.00	999.00			
I, SL(I), SU(I)=	19	-999.00	999.00			
I, SL(I), SU(I)=	20	-999.00	999.00			
I, SL(I), SU(I)=	21	-999.00	999.00			
I, SL(I), SU(I)=	22	-999.00	999.00			
I, SL(I), SU(I)=	23	-999.00	999.00			
I, SL(I), SU(I)=	24	-999.00	999.00			
I, SL(I), SU(I)=	25	-999.00	999.00			
I, SL(I), SU(I)=	26	-999.00	999.00			
I, SL(I), SU(I)=	27	-3.00	.24			
I, SL(I), SU(I)=	28	-999.00	999.00			
I, SL(I), SU(I)=	29	-999.00	999.00			
I, SL(I), SU(I)=	30	-999.00	999.00			
I, SL(I), SU(I)=	31	-999.00	999.00			
I, SL(I), SU(I)=	32	-999.00	999.00			
I, SL(I), SU(I)=	33	-999.00	999.00			
I, SL(I), SU(I)=	34	-999.00	999.00			
I, SL(I), SU(I)=	35	-999.00	999.00			
I, SL(I), SU(I)=	36	-999.00	999.00			
I, SL(I), SU(I)=	37	-999.00	999.00			
I, SL(I), SU(I)=	38	-999.00	999.00			
I, SL(I), SU(I)=	39	-999.00	999.00			
I, SL(I), SU(I)=	40	-999.00	999.00			
I, SL(I), SU(I)=	41	-999.00	999.00			
I, SL(I), SU(I)=	42	-999.00	999.00			
I, SL(I), SU(I)=	43	-999.00	999.00			
I, SL(I), SU(I)=	44	-999.00	999.00			
I, SL(I), SU(I)=	45	1.00	2.50			
I, SL(I), SU(I)=	46	-1.00	1.00			
I, SL(I), SU(I)=	47	-1.00	1.00			
I, SL(I), SU(I)=	48	30000.00	46000.00			
I, SL(I), SU(I)=	49	30000.00	52000.00			
I, SL(I), SU(I)=	50	.10	.75			
I, SL(I), SU(I)=	51	1.00	2.70			
I, SL(I), SU(I)=	52	0.00	1.00			
NUMBER OF REQUESTED HELMINS=		2				

////FUNCTION INPUT////

WTS(1)	190000.0000						
ITEPH	1 0 7	2 1 1979	0 0	0 0	0 0		
PX=	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000
	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000
	I	I	I	I	I	I	I
WTS(16)	.7500						
W...1-5=	21.2000	2.0000		.3800	.1400	5.0000	
W...6-8,14,16=	.9800	.8500		.3000	-.1500	-1.0000	
W...17-20=	-.1500	-.2500		-.1200	.0250		
HX...1-3,10=	.4000	.1000		.4600	.2000		
HX...16-20=	.0800	.3600		1.8000	35.0000	.3000	
GX...3-7=	.8000	3000.0000		16.6670	22.5800	8.3300	
GX...8,11-12,17,18=	2.2000	1443.3800		3.1500	-5.2500	-12.7250	
GX...19-22=	200.0000	8870.0000		41100.0000	7500.0000		
GX...23-27=	4.0000	.5500		.0900	3200.0000	.7000	
GX...32,34=	30.0000	0.0000					
INITAIL XBAR	-.2170	.3383	-.1576	-.1123	-.3620		
	.0358	.1895					
INITAIL STEPS	.2000	.2000	.2000	.2000	.2000		
	.2000	.2000					
REQMIN,SCF,CAY	.1000E-06	.1000E+01	.1000E+12				

////NELMIN COMPLETE////

XMIN=	-.15129477	.18686605	-.15769764	.05231575	-.48770473
	.20364349	.16912692			
YNEWLO=	.200533E+04				
ICOUNT=	817				
TOT. FUNCTION CALLS=	825				
TOT. WEIGHT ITERATIONS	2973.00				
AVE. WT. ITERATIONS PER	3.604				
INITAIL XBAR	-.1513	.1869	-.1577	.0523	-.4877
	.2036	.1691			
INITAIL STEPS	.1000	.1000	.1000	.1000	.1000
	.1000	.1000			
REQMIN,SCF,CAY	.1000E-07	.1000E+01	.1000E+13		

////NELMIN COMPLETE////

XMIN=	-.15147188	.18662137	-.15771096	.05225537	-.48798586
	.20313425	.16913646			
YNEWLO=	.200507E+04				
ICOUNT=	484				
TOT. FUNCTION CALLS=	1317				
TOT. WEIGHT ITERATIONS	4421.00				
AVE. WT. ITERATIONS PER	3.357				

AIRCRAFT SIZING PROGRAM

DESIGN VARIABLES

WING AREA (FTXX2)= 2146.4606
 WING ASPECT RATIO= 10.7338
 FUSELAGE LENGTH (FT)= 172.8356
 HOR. TAIL AREA (FTXX2)= 911.4927
 HOR. TAIL ASPECT RATIO= 3.9514
 TOTAL THRUST (LBS)= 82253.2621
 AFT MOST CG= .4469
 CRUISE MACH NO.= I
 SWEEP= I
 WING T/C= I
 WING TAPER RATIO= I
 FUSE. DIA= I

INPUT CONSTANTS

WING...SWEEP,INCIDENCE,TAPER RATIO: 21.2000 2.0000 .3800
 THICKNESS,TWIST,E1,E2,DESIGN CL: .1400 3.0000 .9800 .8500 .3000
 CHICR,APP) -.1500 -.1207
 DELTA CM(10,25 DEGREES FLAP): -.1500 -.2500
 ANGLE OF ZERO LIFT(0,10,45 DEGREES FLAP): -1.0000 -5.2500 -12.7250
 DELTA CD (10-45 DEGREE FLAP): .0250
 TURBULENCE LENGTH/ROOT 3,FUSE. DIA.: 1443.3800 16.6670
 CL-MAX(TD),CL-MAX(L): 2.2000 3.1500
 MIXISON...MACH NO.,RANGE,NO. PASS: .8000 3000.0000 200.0000
 CARGO WEIGHT: 7500.0000
 DELTA CG, WTL(MAX)/WTO: 4.0000 .7000
 ENGINE...L,W,WT,TREF: 22.5800 8.3300 8870.0000 41100.0000
 TAIL...TAPER RATIO,THICKNESS,ELE EFF: .4600 .1000 .4600
 ELEVATOR TIME CONSTANT: .2000
 ECONOMICS...LOAD FACT,S/SEAT PI,BLK HR/YR: .5500 .0900 3200.0000

SOME GEOMETRY CALCULATIONS

WING...SPAN,CHAC: 151.7881 15.0926
 TAIL...SPAN,CHAC,VBAR,SWEEP 60.3166 16.0370 2.1883 30.0000
 VERT. TAIL...VBAR,TAPER,AR,SWEEP,SR/SV,SV: .0800 .3600 1.8000 35.0000 .3000 352.7617

WEIGHT ESTIMATION

WING 37077.8
 HOR. TAIL 7028.3
 VERT. TAIL 1068.5
 FUSELAGE 47372.1
 LANDING GEAR 14912.5
 CONTROL SYSTEM 2541.3
 INSTRUMENTS 116.2
 MISC INTERIOR 250.6
 ELECTRICAL 2192.3
 STARTERS 506.9
 FURNISHINGS 7902.0
 OXYGEN 300.7
 WINDOWS 501.6
 BAGGAGE HANDLING 144.7
 AIR CONDITIONING 3547.0
 THRUST REVERSER 1500.0
 ENGINE 18639.1
 ENGINE CONTROLS 219.5
 FUEL SYS 2571.1
 ACTIVE CONTROL SYSTEMS 250.0

EMPTY WEIGHT 156200.2

PASSENGERS 34000.0
 CREW 1700.0
 BAGGAGE 7000.0
 WTFDOOD 214.5
 CARGO 7500.0

FIXED WEIGHT 50414.5

FUEL 74815.1

TAKE-OFF WEIGHT 281429.7

NO. OF ITERATIONS REQUIRED 1

WHT(1,2,3),WTFUSE(1,2),WTINIT= 6835.45 7829.81 6419.59 57851.38 36892.78 281429.74

///CRUISE ANALYSIS///

TOTAL MISSION RANGE= 3000.00
 CLIMB DISTANCE= 189.00
 DESCENT DISTANCE= 113.00

LEG	MACH NO.	CL	V	TIME	L/D	TSFC	T/T(IN)	ALT(BEG)	ALT(END)	WT(BEG)	WT(END)	DIST	TCON	GAMA	CLM
1	.79	.593	763.4	.597	18.78	.471	.233	36000.0	37398.1	263432.3	259519.3	269.8	1.348	.0007	.751
2	.80	.606	774.5	.588	18.58	.478	.217	37398.1	37714.4	259519.3	255617.9	269.8	1.279	0.0000	.733
3	.80	.606	774.5	.588	18.55	.479	.214	37714.4	38031.6	259617.9	251765.1	269.8	1.279	0.0000	.734
4	.80	.606	774.5	.588	18.53	.480	.211	38031.6	38349.6	251765.1	247960.6	269.8	1.278	0.0000	.735
5	.80	.606	774.5	.588	18.50	.480	.208	38349.6	38668.4	247960.6	244203.8	269.8	1.276	0.0000	.735
6	.80	.606	774.5	.588	18.48	.481	.205	38668.4	41197.6	244203.8	240494.3	269.8	1.244	.0013	.736
7	.80	.674	774.5	.588	18.31	.486	.182	41197.6	41785.7	240494.3	236771.9	269.8	1.134	.0092	.743
8	.80	.682	774.5	.588	18.26	.487	.176	41785.7	42272.8	236771.9	233087.9	269.8	1.117	.0001	.749
9	.80	.687	774.5	.588	18.21	.488	.172	42272.8	42657.4	233087.9	229445.8	269.8	1.106	.0000	.751
10	.80	.689	774.5	.588	18.18	.488	.169	42657.4	43026.6	229445.8	225849.4	269.8	1.101	.0000	.752
11	.65	.569	644.4	2.620	19.00	.425	.300	30000.0	30000.0	225849.4	213004.8	1000.0	2.078	0.0000	.720

FUEL WEIGHT ANALYSIS

TAKE-OFF 281429.74
 START-CRUISE 263432.31
 MID-CRUISE 244203.84
 END-CRUISE 225849.37
 AFTER RESERVE 213004.83
 AFTER DESCENT/TAXI 206614.68

NET FUEL WEIGHT(LBS) 74815.05

CRUISE ALTITUDES
 LEG 1 36000.00
 LEG 2 43026.59
 RESERVE LEG 30000.00

FLIGHT LENGTH (HR) 6.67
 AVERAGE SPEED (KTS) 449.82
 BLOCK TIME (HR) 7.00
 BLOCK SPEED (KTS) 428.80
 BLOCK FUEL (LBS) 44358.42
 BLOCK FUEL (GALS) 6931.00
 NAUT. MI/GAL .43
 NAUT. SEAT PI./GAL. 86.57

INSTALLED THRUST (LBS) 82253.26
 NO. OF ENGINES 2
 ENGINE THRUST (LBS) 41126.63
 REFERENCE ENGINE (LBS) 41100.00
 SCALE FACTOR 1.001

DRAG ANALYSIS

WING	.0078
HORIZONTAL TAIL	.0029
VERTICAL TAIL	.0011
FUSELAGE	.0025
BASE	.0002
ENGINE NACELLE	.0013
CRUD/FLAPS	.0007
AIRCRAFT DRAG	.0184

INTERFERENCE FACTOR IS 5 PERCENT

REYNOLD'S NUMBERS

WING	24674227.1
HORIZONTAL TAIL	26218180.1
VERTICAL TAIL	24576159.6
FUSELAGE	282560989.7
ENGINE	36926961.6

STABILITY AND CONTROL DERIVATIVES

CL, H, CG, POSITION= .606 .800 .314

	CL	CD	CM
ALPHA	6.69958	.28332	-1.51107
VELOCITY	.2155	.0010	-.0003
Q	16.85623	0.00000	-78.17792
ALPHA-DOT	-5.19019	0.00000	-26.74635
ELEVATOR	.68393	.00004	-3.52448

NEUTRAL POINT	.540		
STATIC STABILITY	-.226		
CM(ALPHA)	-1.511		
STOR=		5.718	3.890
		.339	.540
		.604	4.865
		3.051	.290
		.547	.737
		-.028	-.017
		.172	.205
		I	I
		I	I
		I	I

-.1729	-.2535	.1982	.0998	3232.9597
.6954	-.2789	.0040	5.7163	3.8903
.2724	77.7760	0.0000	1.5033	.6000
.1720	5.7179	.3387	.5400	.9902
1.2657	1.6135	3.7351	.9997	.3144

.0758

ACCURATE L/D ANALYSIS

CL(REQUESTED)=	.606	
CL(WING)=	.655	
CL(TAIL)=	-.118	
ELEVATOR(DEGREES)=	0.00	
STABILIZER(DEGREES)	-3.09	
INDUCED DRAG COMPONENTS		
WING=	.0146	
INTERFERENCE=	-.0019	
TAIL=	.0006	
(TRIM)=	.0009	
(TAIL)=	.0038	
SIGMA	.3715	
DRAG COEFFICIENTS		
INDUCED=	.0133	
ZERO LIFT=	.0184	
ELEVATOR=	0.0000	
WING(MACH), M(CRIT)=	.0011	.80
FUSE(MACH), M(CRIT)=	-.0000	.90
TOTAL=	.0328	
L/D=	18.477	
MAX. L/D=	19.466	
CL-L/D MAX=	.736	
MODIFIED COO=	.0193	

AIRCRAFT COST ESTIMATES

	DEVELOPMENT	PRODUCTION
ENGINEERING	137888052.30	196227689.86
DEVELOPMENT SUPPORT	53303827.90	0.00
FLIGHT TEST	17877799.44	0.00
TOOLING	144227140.03	252884765.95
MANUFAC. LAROP	90339216.98	1048521091.06
QUALITY CONTROL	11744098.21	136307741.84
MATERIALS	10453988.44	471245525.87
ENGINE	11723234.28	976936190.35
AVIONICS	738462.00	92307750.00
ACTIVE CONTROLS SYSTEM	507692.63	63461578.13
TOTAL	478803512.20	3237892333.06
TOTAL COST PER AIRCRAFT=	\$ 16353461.72	

MAINTENANCE OPEATING COSTS

NO.	SYSTEM	LABOR	MATERIAL
1	INST	35.52	5.78
2	AIR COND	5.10	4.52
3	AUTO PILOT	13.43	3.15
4	COMMUN	5.52	2.36
5	ELEC	4.31	5.75
6	FURN	26.10	13.93
7	FIRE PROT	9.37	1.46
8	FLY CONTL	8.65	5.49
9	FUEL	2.01	1.02
10	HYD POWER	3.33	3.95
11	ICE	.67	.56
12	INSTR	1.22	.49
13	LAND GEAR	13.64	28.07
14	LIGHTING	3.81	2.83
15	NAVIG	11.59	8.24
16	OXYGEN	1.05	1.50
17	PNEUMAT	1.28	6.95
18	WAT/WASTE	1.08	1.54
19	AIR APU	.32	.46
20	STRUCTURE	3.70	0.00
21	DOOPS	2.35	1.96
22	FUSELAGE	4.76	.58
23	NACELLES	.67	.28
24	WINGS	2.95	1.13
25	STAB	.83	.37
26	WINDOWS	.85	7.24

LABOR COST 65.64
MATERIAL COST 43.84

ENGINE LABOR COST 25.38
ENGINE MATERIAL COST 31.26

MAINTENACE DOC IN 1976 DOLLARS PER HOUR 166.13

DIRECT OPERATING COSTS--DOLLARS/FLT. HOUR

DEPREC	393.52	19.63
SUPPORT	53.66	2.68
SPARES	26.83	1.34
DELAY	10.29	.51
INSURANCE	62.61	3.12
FUEL	743.00	37.06
MAINTENANCE	166.13	8.29
LANDING FEE	26.80	1.34
CREW	266.48	13.29
ATTENDANTS	164.11	8.18
FUEL SERVICE	77.18	3.85
CONTROL	14.46	.72
TOTAL DIRECT OPERATING COSTS	\$ 2005.07	100.00

INDIRECT OPERATING COSTS--DOLLARS/FLT. HOUR

MAIN BURON	174.44	19.21
FOOD COST	168.35	18.53
MOVIE	34.32	3.78
PASS INS	30.05	3.31
MISC PASS	6.30	.69
ADVERTISE	97.64	10.75
COMMISSION	135.79	14.95
RESER	84.75	9.33
PASS HDLG	55.28	6.09
BAG HDLG	25.23	2.78
CARGO HDLG	86.07	9.48
SERVICING	10.07	1.11
TOTAL INDIRECT OPERATING COSTS	908.28	100.00

PERFORMANCE FUNCTION SUMMARY

REVENUE PER BLOCK HOUR 4245.12
 TOTAL COST PER BLOCK HOUR 2913.34
 RETURN ON INVESTMENT .1229

1 DOC/HR 2005.065
 2 DOC/FLT 14027.968
 3 ROI .123
 4 FARE .096
 5 SEAT-MI/GA 86.568
 6 L/D(MAX) 19.466
 7 MTOGV 281429.737
 8 FARE 31749.600
 9 PRICE 4538.000

DEBUG OF NOSE GEAR UNSTICK

ZACT,XHUF,ZACLG= .2650 .0250 .5301
 ANS(1,2,3,4)= .002377 2116.238417 288.150000 1116.449901
 VSTALL,CLW,O,XLW,XHW= 223.9352 .3642 48.2736 45279.0297 -449306.5408
 C1,UNTHRU,XCG,XLTRO,CL2,CDIT,XLT= 71.5390 82253.2621 .1819 -26773.6962 1.3723 -12.3103 77.7760
 XLTAV,CON(12),STOR(7),STOR(8),W(2)= -95242.4919 2.9739 3.0719 .2915 2.0000
 GX(17),HX(6),W(10),XLTAV2,TLGE,CLTAV= -5.2500 2.1883 15.0926 -79622.1355 15620.3564 -1.8096

DRAG ANALYSIS

WING	.0057
HORIZONTAL TAIL	.0022
VERTICAL TAIL	.0008
FUSELAGE	.0022
BASE	.0002
ENGINE NACELLE	.0010
CRUD/FLAPS	.0230
AIRCRAFT DRAG	.0376

INTERFERENCE FACTOR IS 5 PERCENT

REYNOLD'S NUMBERS

WING	64103940.0
HORIZONTAL TAIL	60115140.6
VERTICAL TAIL	63049159.4
FUSELAGE	734090064.3
ENGINE	95926692.3

APPROACH

STABILITY AND CONTROL DERIVATIVES

APPROACH

CL, M, CG, POSITION	1.713	.192	.447
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	CL	CD	CM
ALPHA	4.86481	.50147	-.40650
VELOCITY	.0529	.0007	.0005
Q	13.21915	0.00000	-61.30943
ALPHA-DOT	-3.48736	0.00000	-17.97125
ELEVATOR	.53626	.00004	-2.76400

NEUTRAL POINT
 STATIC STABILITY
 CM(ALPHA)
 STOR

	.547			
	-.100			
	-.407			
	5.716	3.090		
	.339	.540		
	.604	4.865		
	3.051	.290		
	.547	.737		
	-.028	-.017		
	.172	.205		
	I	I		
	I	I		
	I	I		
	-.2448	-.3974	.2470	.0705
	.7036	-.3996	.0057	4.0372
	.2724	77.7760	0.0000	3.5033
	.2050	4.0383	.2902	.5469
	1.2657	1.2293	15.3442	.9997
	.0758			2283.2770
				3.0509
				.9814
				.9902
				.4460

ACCURATE L/D ANALYSIS

APPROACH WITH 45 DEGREES FLAP

CL(REQUESTED)=	1.713	
CL(WING)=	1.761	
CL(TAIL)=	-.114	
ELEVATOR(DEGREES)=	0.00	
STABILIZER(DEGREES)	-1.35	
INDUCED DRAG COMPONENTS		
WING=	.1303	
INTERFERENCE=	-.0048	
TAIL=	.0005	
(TRIM)=	.0020	
(TAIL)=	.0050	
SIGMA	.3715	
DRAG COEFFICIENTS		
INDUCED=	.1260	
ZERO LIFT=	.0626	
ELEVATOR=	.0005	
WING(MACH), M(CRIT)=	0.0000	0.00
FUSE(MACH), M(CRIT)=	0.0000	0.00
TOTAL=	.1091	
L/D=	9.057	
MAX. L/D=	9.574	
CL-L/D MAX=	1.358	
MODIFIED CDD=	.0655	

////DIMENSIONAL STABILITY DERIVATIVES////

DFRCR=	-.4615	.0221	-.0004
	-.1126	-.0046	-.0000
	-.0197	0.0000	-.3444
	.0030	0.0000	-.0002
	-36.3072	-.0446	-1.5935
DERAP=	-.5723	.1281	-.0004
	-.3999	-.0430	.0000
	-.0208	0.0000	-.3632
	.0108	0.0000	-.0004
	-16.7513	-.0263	-.5984

LONGITUDINAL DYNAMICS

/\/\CRUISE/\/\

COEFFICIENTS= 1.000000 .926777 .443088 .003445 .001313

ROOTS (REAL, IMAGINARY)

-.0008 .0544
 -.0008 -.0544
 -.4634 .4779
 -.4634 -.4779

PHUGOID FREQUENCY .0544
 PHUGOID DAMPING .0145
 SHORT PER. FREQ. .6656
 SHORT PER. DAMPING .6961

NO. OF NON-OSCILLATORY ROOTS= 0
 TIME CONSTANTS= 0.0000 0.0000 0.0000 0.0000

/\/\APPROACH/\/\

COEFFICIENTS= 1.000000 .977315 .284314 .035203 .004930

ROOTS (REAL, IMAGINARY)

-.0321 .1277
 -.0321 -.1277
 -.4887 .2134
 -.4887 -.2134

PHUGOID FREQUENCY .1317
 PHUGOID DAMPING .2439
 SHORT PER. FREQ. .5332
 SHORT PER. DAMPING .9164

NO. OF NON-OSCILLATORY ROOTS= 0
 TIME CONSTANTS= 0.0000 0.0000 0.0000 0.0000

CL-MAX TO(W), CL-MAX TO (AC), CL2 2.200 1.976 1.372
 CL-MAX (W), CL-MAX (AC), CLA= 3.150 2.895 1.713

AIRCRAFT OPTIMIZATION CONSTRAINTS

DESIGN CONSTRAINTS

ID	CONSTRAINT	VALUE	SL	SU	VIOLATION?
1	CRUISE THRUST	1.1009	1.0000	2.0000	0.0000
2	2ND SEGMENT CLIMB	1.0000	1.0000	5.0000	0.0000
3	MISSED APPROACH CLIMB	1.3067	1.0000	5.0000	0.0000
4	LANDING	7999.9572	1000.0000	8000.0000	0.0000
5	TAKE-OFF	8106.5719	2000.0000	10000.0000	0.0000
6	LANDING GEAR LIMIT	.0231	0.0000	1.0000	0.0000
45	PASSENGER VOLUME	1.0000	1.0000	2.5000	0.0000
48	CRUISE ALTITUDE	38668.4002	30000.0000	46000.0000	0.0000
49	CRUISE ALTITUDE(L/D(MAX))	42707.2395	30000.0000	52000.0000	0.0000
50	CRUISE WING CL	.6552	.1000	.7500	0.0000
51	APPROACH WING CL	1.6799	1.0000	2.7000	0.0000
52	AR(TAIL)/AR(WING)	.3719	0.0000	1.0000	0.0000

HANDLING QUALITY CONSTRAINTS

7	STATIC STAB. (CR)	-.0930	-999.0000	999.0000	0.0000
8	STATIC STAB. (AP)	-.1000	-1.0000	-.1000	0.0000
9	MANEUVER MARGIN (CR)	-.1383	-999.0000	999.0000	0.0000
10	MANEUVER MARGIN (AP)	-.2900	-999.0000	999.0000	0.0000
11	TAIL LIFT (AP)	-.3897	-.8000	.8000	0.0000
12	NOSE GEAR UNSTICK	2.9739	1.0000	3.0000	0.0000
13	DYN. STAB. (CR)	.0000	-999.0000	999.0000	0.0000
14	DYN. STAB. (AP)	.0002	-999.0000	999.0000	0.0000
15	PHUGOID FREQ (CR)	.0544	-999.0000	999.0000	0.0000
16	PHUGOID FREQ (AP)	.1317	-999.0000	999.0000	0.0000
17	PHUGOID DAMPING (CR)	.0145	-999.0000	999.0000	0.0000
18	PHUGOID DAMPING (AP)	.2439	-999.0000	999.0000	0.0000
19	SHORT PER. FREQ. (CR)	.6656	-999.0000	999.0000	0.0000
20	SHORT PER. FREQ. (AP)	.5332	-999.0000	999.0000	0.0000
21	SHORT PER. DAMP (CR)	.4961	-999.0000	999.0000	0.0000
22	SHORT PER. DAMP (AP)	.9164	-999.0000	999.0000	0.0000
23	TIME-TO-DOUBLE (CR)	99.0000	-999.0000	999.0000	0.0000
24	TIME-TO-DOUBLE (AP)	99.0000	-999.0000	999.0000	0.0000
25	TIME-TO-HALF (CR)	879.9306	-999.0000	999.0000	0.0000
26	TIME-TO-HALF (AP)	21.5825	-999.0000	999.0000	0.0000
27	FLIGHT PATH STAB. (AP)	-.0016	-3.0000	.2400	0.0000
28	VERT. GAIN (CR)	10.7991	-999.0000	999.0000	0.0000
29	VERT. GAIN (AP)	4.6431	-999.0000	999.0000	0.0000
30	T(THETA(2)) (CR)	.4548	-999.0000	999.0000	0.0000
31	T(THETA(2)) (AP)	-.0613	-999.0000	999.0000	0.0000
32	WV/NZA (CR)	.0410	-999.0000	999.0000	0.0000
33	WV/NZA (AP)	.0612	-999.0000	999.0000	0.0000
34	T(1) (AP)	-470.5489	-999.0000	999.0000	0.0000
35	MODE RATIO (CR)	12.2270	-999.0000	999.0000	0.0000
36	MODE RATIO (AP)	4.0494	-999.0000	999.0000	0.0000
37	ELE. VAR. (CR)	.0011	-999.0000	999.0000	0.0000
38	THETA-DOT GAIN (CR)	-2.8326	-999.0000	999.0000	0.0000
39	THETA GAIN	-7.5689	-999.0000	999.0000	0.0000
40	ELE. VAP. (AP)	.0094	-999.0000	999.0000	0.0000
41	THETA-DOT GAIN (AP)	-4.7296	-999.0000	999.0000	0.0000
42	THETA GAIN (AP)	12.6395	-999.0000	999.0000	0.0000
43	ELE-DOT VAR. (CR)	.3184	-999.0000	999.0000	0.0000
44	ELE-DOT VAR. (AP)	.4264	-999.0000	999.0000	0.0000
46	TRIM ELEVATOR (CR)	0.0000	-1.0000	1.0000	0.0000
47	TRIM ELEVATOR (AP)	0.0000	-1.0000	1.0000	0.0000

COMMON DUMP

DESIGN-	2146.46060 82293.26214 I	10.73378 .44692 I	172.03561 I I	911.49267 I I	9.99136 I I	
ITERM-	1 1979	0 0	7 0	2 0	1 0	
PX-	0.0000 0.0000 I	0.0000 0.0000 I	0.0000 0.0000 I	0.0000 I I	0.0000 I I	
CDS-	.018435285	.007789039	.002919233	10.502198924	.032756961	.002502042
CDSAP-	.037644705	.005683200	.002194607	9.056559926	.189143434	I
W-	21.200000000 .980000000 .387874441 -1.000000000	2.000000000 .050000000 .537923713 -1.150000000	.380000000 .300000000 .454076207 -2.250000000	.140000000 151.788142905 -1.150000000 -1.120716547	5.000000000 15.092617897 .932323000 .025000000	
HX-	.400000000 2.188322980 .387874441 .0F0000000	.100000000 .577350275 -1.349290339 .360000000	.460000000 .604725140 0.000000000 1.800000000	60.316604382 .469975411 0.000000000 35.000000000	16.037015975 .200000000 .001070020 .300000000	
GX-	3.141592650 22.580000000 1443.320000000 -99.000000000 41100.000000000 3200.000000000 .000464779	57.265779000 0.330000000 3.150000000 -5.250000000 7500.000000000 .700000000 30.600000000	.000000000 2.200000000 .009396652 -12.725000000 4.000000000 .636912543 77.776023746	3000.000000000 .608075010 279.808973653 200.000000000 .550000000 1.761201849 0.000000000	16.667000000 1.732900661 32.174000000 0870.000000000 .090000000 1.100904500 352.761689100	
CG-	.44692	.44692	.18109	.18189	.65000	.18000
DERIVCR-	6.699575550 -.000309099	.283323942 16.856229399	-.623274330 0.000000000	.215493621 -78.177918252	.001025132 -5.190192106	
	0.000000000	-26.746354637	.683934363	.000840805	-3.924404929	
DERIVAP-	4.864806036 .000531027 0.000000000	.581471571 13.219153412 -17.971267917	-.486502225 0.000000000 .526361547	.052930270 -61.309434652 .000840805	.000650748 -3.487262363 -2.764004004	
STOR-	5.717885050 4.864806036 -.027830200 I	3.890306526 3.050093306 -.017255523 I	.336700306 .290192456 .172003128 I	.539955222 .546927754 .205004590 I	.505263796 .736070092 I I	
WTS-	281429.737 74815.053 38668.400 .750	156200.104 431.364 42707.240 449.025	75429.489 1337.650 13450000.000 6.669	117150.138 80.692 13330000.000 6.996	219073.004 2177.044 244203.035 44358.421	
CST-	2005.065 19.690	14027.968 201429.737	.123 31749.000	.096 4538.000	86.566 I	
XMIN-	-.15147188 .20313425	.18662137 .16913646	-.15771096	.05229537	-.468790286	

APPENDIX IV - Procedure File used to Execute OPDOT on the
Langley Research Center Computer System

```
OPDOT,T7770,CM70000.                RM 1174  ARBUCKLE/SLIWA
USER(820235N)
CHARGE,101264,LRC.
GET,OPDOT1.
GET,INPUT=SM10.                       (SM10 is static margin 10% case -- APPENDIX II)
FTN(I=OPDOT1,OPT=2,R=0)
ATTACH(FTNMLIB/UN=LIBRARY,NA)
LDSET(PRESET=ZERO,LIB=FTNMLIB)       (All variables set to zero since program is
LGO.                                   already operational)
REWIND(TAPE4)
REWIND(LGO)
GET,PPB.                               (PPB is the binary code for the
PPB.                                   OPDOT plotting preprocessor)
REWIND(TAPE7)
ATTACH(LRCGOSF/UN=LIBRARY)
GET,ABS2290/UN=181500N.               (Reference 28)
ABS2290,TAPE7.
PLOT.CALPOST,11
CONT.//BLANK PAPER, LEROY .3 PEN,
CONT. BLACK INK, MULTIPLE PLOT MODE//
EXIT.
```

APPENDIX V - KEY PROGRAM VARIABLES

SUBROUTINE	VARIABLE	DESCRIPTION [UNITS, IF APPLICABLE]
SIMPACT (Main Program)	AMP	Amplitude of sinusoid transformation Z to X domain
	AVE	Ave. of sinusoid transformation Z to X domain
	CAYY	Penalizing weight for constraint violation
	FACT	= 1 if constraint is to be considered, = 0 otherwise
	GNORM	Constraint normalization--ave. of boundaries
	MC	Number of constraint violations
	MINEQ	Number of constraint functions
	NONEL	Number of NELMIN optimizations
	NVAR	Number of independent design variables
	REQMIN	Convergence criteria
	SCF	Scale factor to multiply performance index
	SL	Lower constraint boundary
	STEP	Initial optimizer step size
	SU	Upper constraint boundary
	XBAR	Independent design variable in Z domain
	XBARO	Initial value for independent design
	XINEQ	= 1 if constraint is violated, = 0 otherwise
	XL	Lowest allowable value of independent design variable in X domain
	XMIN	Vector of optimum independent design variable in Z domain
	XU	Upper value of independent design variable in X domain
YNEWLO	Optimum performance index from NELMIN	
NELMIN	IHO	Vertex with highest performance index
	ILO	Vertex with lowest performance index
	P	Coordinates of simplex
	PBAR	Centroid of simplex
	START	Initial independent design variables
FN	ILINE	= 1 output; = 0 no output
SETUP	COST	Performance index
	IPR	= 1 output; = 0 no output
	OBJ	Augmented performance index
	PENT	Penalty contribution to OBJ
	UNAug	Unaugmented performance index
DOCOST	ATT	Attendant's cost [\$/hr]
	BLKHR	Block hours of design mission [hr]
	CONTROL	Cost of logistics control [\$/hr]
	COSTHR	Total cost per hour [\$/hr]
	CREW	Crew cost [\$/hr]
	DELAY	Delay cost [\$/hr]
	DEPRE	Depreciation cost [\$/hr]

APPENDEX V - cont.

SUBROUTINE	VARIABLE	DESCRIPTION [UNITS, IF APPLICABLE]
	FARROI	Fare for 15% ROI [\$/pass.-mile]
	FCOST	Fuel cost [\$/hr]
	FEELAND	Landing fees [\$]
	FL	Flight length (lift-off to touchdown)
	IECON	Number of economy seats
	IFIRS	Number of first class seats
	INSUR	Insurance cost [\$/hr]
	PASSPHR	Passengers per hour
	PER	Percent of total cost [%]
	PRICE	Purchase price of airplane [\$]
	PROFIT	Profit of operations [\$]
	REVHR	Revenue hours
	REYR	Revenue years
	ROI	Return on investment [year ⁻¹]
	RPM	Revenue passenger miles
	SERVICE	Servicing cost [\$]
	SPARES	Spares cost [\$]
	SUPPORT	Support cost [\$]
	TAXRT	Tax rate
	TONCAR	Tons of cargo [tons]
	TOT	Total operating cost [\$/hr]
	XINVEST	Investment cost [\$]
	XIOC	Indirect operating cost [\$/hr]
	YRMULT	Year inflation factor
WEIGHT	ACTCON	Weight of active control system [lbs]
	BAGGAGE	Weight of passenger's baggage [lbs]
	CARGO	Cargo weight [lbs]
	CREW	Crew weight [lbs]
	DELWTO	Difference between last gross weight and new gross weight [lbs]
	FUDGE	Weight overrun fudge factor
	FUEL	Mission fuel [gallons]
	LT	Length of tail [ft]
	NOIT	Number of weight iterations
	PASS	Passenger weight [lbs]
	SHT	Horizontal tail volume coefficient
	SVT	Vertical tail volume coefficient
	TRV	Vertical tail taper ratio
	WECTL	Weight of electrical system [lbs]
	WTAC	Air conditioning weight [lbs]
	WTENG	Weight of engine [lbs]
	WTFOD	Weight of food [lbs]
	WTFSYS	Fuel system weight [lbs]
	WTFUEL	Fuel weight [lbs]
	WTFURN	Weight of furnishings [lbs]

APPENDIX V - cont.

SUBROUTINE	VARIABLE	DESCRIPTION [UNITS, IF APPLICABLE]
	WTFUSE	Fuselage weight [lbs]
	WTHT	Horizontal tail weight [lbs]
	WTINST	Instrument weight [lbs]
	WTLG	Landing gear weight [lbs]
	WTMISC	Miscellaneous weight [lbs]
	WTOZ	Weight of oxygen system [lbs]
	WTSRT	Weight of engine starters [lbs]
	WTVT	Weight of vertical tail [lbs]
	WTWIN	Weight of windows [lbs]
	WTWING	Weight of wing [lbs]
CRUALT	ALF	Standard atmospheric property α , reference 14
	ALT	Cruise altitude [ft]
	ANS	Vector of atmosphere as a function of altitude
	CLCR	Cruise lift coefficient
	DALT	Difference between old altitude guess and new [ft]
	DP	Δ pressure [lbs/ft ²]
	DRDH	$\partial\rho/\partial H$, density gradient [slug/ft ²]
	HNEW	New altitude guess [ft]
	HOLD	Old altitude guess [ft]
	IC	Number of iterations in table look up
	M	Mach number
	P	Pressure [lbs/ft ²]
	PO	Sea level pressure [lbs/ft ²]
	R	Gas constant
	TO	Sea level temperature [°R]
	WT	Cruise weight [lbs]
ENGINE	ALT	Operating altitude [ft]
	DELTA	Pressure ratio, P/P_0
	F	Fuel flow rate [lbs/hr]
	FN	Normalized fuel flow
	HN	Normalized altitude
	TCTM	Cruise thrust over installed thrust
	THETA	Temperature ratio, T/T_0
	TN	Normalized thrust
	TSFC	Thrust specific fuel consumption
CDZL	ABOD	Surface area of fuselage body [ft ²]
	ACONE	Surface area of tail cone [ft ²]
	ANOSE	Surface area of nose cone [ft ²]
	BV	Span of vertical tail [ft]
	CDBF	Fuselage bluff body drag coefficient
	CDFE	Fuselage friction drag coefficient
	CDOE	Engine drag coefficient
	CDOF	Fuselage drag coefficient

APPENDIX V - cont.

SUBROUTINE	VARIABLE	DESCRIPTION [UNITS, IF APPLICABLE]
	CDOH	Horizontal tail drag coefficient
	CDOV	Vertical tail drag coefficient
	CDOW	Wing drag coefficient
	CF	Friction coefficient
	CONEL	Length of tail cone [ft]
	CVBAR	Vertical tail mean aerodynamic chord [ft]
	DIA	Fuselage diameter [ft]
	EDIA	Engine diameter [ft]
	EL	Engine length [ft]
	FLOD	Ratio of fuselage length to diameter
	MU	Viscosity [sec^{-2}]
	SREF	Reference area [ft^2]
STABCOD	AW	Wing lift curve slope [deg^{-1}]
	BETA	Mach number correction factor
	CLAWB	$C_{L\alpha}$ of wing body
	DCDM	$\partial C_D / \partial M$
	DCMDCL	$C_m / \partial C_L$, static stability
	DEDA	Downwash gradient, $\partial \epsilon / \partial \alpha$
	DEDAMO	Incompressible downwash gradient, $\left. \frac{\partial \epsilon}{\partial \alpha} \right _{M=0}$
	DXACE	Shift in aerodynamic center due to engines
	ELASTK	Elasticity correction factor
	ETAH	Tail efficiency, η_t
	XAC	Aerodynamic center
	XACDM	Shift in aerodynamic center due to compressibility
	XACW	Wing aerodynamic center
TRIM	ALFAT	Angle-of-attack of tail [deg]
	ALFAW	Angle-of-attack of wing [deg]
	AOL	Angle-of-zero-lift [deg]
	AT	Tail lift curve slope [deg^{-1}]
	AW	Wing lift curve slope [deg^{-1}]
	CLTAIL	Tail lift coefficient
	CLWING	Wing lift coefficient
	CMACW	Wing pitching moment coefficient
	CMFUS	Fuselage pitching moment coefficient
	CNT	Normal tail force coefficient
	CNW	Normal wing force coefficient
	CRDE	Elevator deflection [deg]
	CRIT	Stabilizer deflection [deg]
	CTLPWR	Control power coefficient
	DEDA	Downwash gradient
	EPS	Downwash angle [deg]
	LTLOQ	Tail lift normalized by dynamic pressure
	LTOTOQ	Total lift normalized by dynamic pressure
	LWOQ	Wing lift normalized by dynamic pressure

APPENDIX V - cont.

SUBROUTINE	VARIABLE	DESCRIPTION [UNITS, IF APPLICABLE]
	TAO	Elevator control effectiveness parameter
FUELCAL	BLKSPD	Block speed for mission [knots]
	RANGE	Range of mission [naut-mi]
	WTMID	Mid-point weight [lbs]
	WTRES	Weight after reserve mission [lbs]
	XMG	Miles per gallon of fuel
	XSMG	Seat miles per gallon of fuel
CRUFUEL	ALTCR	Cruise altitude [ft]
	ALTD	Desired altitude [ft]
	ALTEND	Altitude at end of leg [ft]
	ALTLDM	Altitude for maximum glide ratio [ft]
	CLCR	Cruise lift coefficient
	CLM	Lift coefficient for maximum glide ratio
	GAMA	Climb gradient
	IRES	= 1, reserve leg, = 0 otherwise
	LOD	Glide ratio
	ROC	Rate-of-climb, [ft/hr]
	TOWAV	T/W available
	TOWRQ	T/W required
XL0D	CLLDMX	Lift coefficient for maximum glide ratio
	CLO	Design lift coefficient of wing section
	CLWN	Wing lift coefficient normal to leading edge
	EPS	Wing downwash angle at tail [deg]
	SIGMA	Wing-tail interference factor
	TDG	Tail drag contribution
	WMCR	Critical Mach number of wing
	XLDMX	Maximum glide ratio
MAINCST	LCOST(I)	Labor cost of Ith component [\$/hr]
	MCOST(I)	Material cost of Ith component [\$/hr]
CNSTRN	AAP	Coefficients of longitudinal characteristic polynomial in approach
	ACR	Coefficients of longitudinal characteristic polynomial in cruise
	CLA	Approach lift coefficient
	CLS	Stall lift coefficient with full flaps
	CLTAIL	Required tail lift coefficient
	CLTAV	Available tail lift coefficient for nose gear unstick
	CL2	Second segment climb lift coefficient
	DERAP	Dimensional stability derivatives in approach
	DERCR	Dimensional stability derivatives in cruise
	DGDU	$\partial\gamma/\partial u$

APPENDIX V -- cont.

SUBROUTINE	VARIABLE	DESCRIPTION [UNITS, IF APPLICABLE]
	DZETA	Desired short period damping ratio
	ROOTAP	Longitudinal roots in approach
	ROOTCR	Longitudinal roots in cruise
	UNTHRU	Unbalanced thrust component during take-off roll

APPENDIX VI - MAP OF COMMON BLOCKS USED WITHIN
DESIGN SECTION OF PROGRAM

COMMON BLOCK	ARRAY	NO.	DESCRIPTION [UNITS, IF APPLICABLE]
DEVAR	CST	1	Direct operating cost per block hour [\$/hr]
		2	Direct operating cost per flight [\$/flight]
		3	Return on investment [year ⁻¹]
		4	Fare for a ROI of .15 [\$/seat-naut. mi]
		5	Fuel efficiency [seat-naut. mi/gal]
		6	Maximum glide ratio in cruise
		7	Maximum take-off gross wt. [lbs]
	DESIGN	1	Wing area [ft ²]
		2	Wing aspect ratio
		3	Fuselage length [ft]
		4	Horizontal tail area [ft ²]
		5	Horizontal tail aspect ratio
		6	Installed thrust [lbs]
		7	Aft most center-of-gravity in cruise [% MAC]
	ITERM	1	= 1 if active controls,=0 otherwise
		2	= 1 if center-of-gravity control,=0 otherwise
		3	Cruise C.G. Selector: = 7 if midway between FWD & AFT limits
		4	Number of engines
		5	Element of CST used in optimizer
		6	Year of evaluation
		7	= 1 if landing gear is movable,=0 otherwise
DRAG	CDS	1	Cruise Total parasite drag coefficient
		2	Cruise Wing drag coefficient
		3	Cruise Horizontal tail drag coefficient
		4	Cruise Glide ratio
		5	Cruise Total drag coefficient
		6	Cruise Fuselage drag coefficient

APPENDIX VI - cont.

COMMON BLOCK	ARRAY	NO.	DESCRIPTION [UNITS, IF APPLICABLE]
GEOM	CDSAP	1	Approach Total parasite drag coefficient with take-off flaps
		2	Approach Wing drag coefficient
		3	Approach Horizontal tail drag coefficient
		4	Approach Glide ratio with landing flaps
		5	Approach Total drag coefficient
		6	Approach Fuselage drag coefficient
	GX	1	PI (π) = 3.1415927
		2	Radian to degree conversion factor = 57.295779
		3	Cruise Mach number
		4	Design range [naut. miles]
		5	Fuselage diameter [ft]
		6	Reference engine length [ft]
		7	Reference engine diameter [ft]
		8	Maximum wing lift coefficient with flaps in take-off position
		9	Trimmed lift coefficient in cruise
		10	Trimmed lift coefficient
		11	Characteristic turbulence length divided by $\sqrt{3}$ [ft]
		12	Maximum wing lift coefficient with full flaps
		13	Variance of elevator deflection in approach [rad]
		14	Velocity in approach [ft/sec]
		15	Acceleration constant, g [ft/sec ²]
		16	Take-off stabilizer position, [deg], if -99 then use trim position for climbout
		17	Angle of zero lift in take-off [deg]
		18	Angle of zero lift with landing flaps [deg]
		19	Number of passenger seats
		20	Reference engine weight [lbs]
		21	Thrust of reference engine [lbs]
		22	Weight of cargo [lbs]
		23	Allowable C.G. range [% MAC]
		24	Passenger load factor
		25	Fare [\$/seat-mile]
		26	Airplane utilization [hrs/yr]
		27	Ratio of maximum landing weight to gross weight
28	Wing lift coefficient in cruise		
29	Wing lift coefficient in approach		
30	Minimum ratio of thrust available to thrust required in cruise		
31	Trim drag correction for estimating L/D _{max}		
32	Sweep of horizontal tail [deg]		
33	Distance between horizontal tail and wing [ft]		

APPENDIX VI - cont.

COMMON BLOCK	ARRAY	NO.	DESCRIPTION [UNITS, IF APPLICABLE]
		34	Height of horizontal tail above fuselage centerline [ft]
		35	Vertical tail area [ft ²]
	HX	1	Horizontal tail taper ratio
		2	Horizontal tail thickness ratio
		3	Elevator control effectiveness factor
		4	Horizontal tail span [ft]
		5	Horizontal tail mean aerodynamic chord [ft]
		6	Horizontal tail volume coefficient
		7	Tan (tail quarter chord sweep angle)
		8	Tan (tail leading edge sweep angle)
		9	Tan (tail half chord sweep angle)
		10	Elevator servo time constant [sec]
		11	Approach tail lift coefficient
		12	Tail incidence in approach [deg]
		13	Trimmed elevator position in approach [deg]
		14	Trimmed elevator position in cruise [deg]
		15	Variance of elevator in cruise [rad]
		16	Vertical tail volume coefficient
		17	Vertical tail taper ratio
		18	Vertical tail aspect ratio
		19	Vertical tail sweep at quarter chord [deg]
		20	Ratio of rudder area to vertical tail area
	W	1	Wing sweep at quarter chord [deg]
		2	Incidence of wing [deg]
		3	Wing taper ratio
		4	Wing thickness ratio
		5	Wing geometric twist [deg]
		6	Oswald's efficiency factor in drag bucket
		7	Oswald's efficiency factor out of drag bucket
		8	Design lift coefficient for wing section
		9	Wing span [ft]
		10	Wing mean aerodynamic chord, MAC [ft]
		11	Tan (wing quarter chord sweep angle)
		12	Tan (wing leading edge sweep angle)
		13	Tan (wing half chord sweep angle)
		14	Wing pitching moment coefficient at cruise
		15	Cos (wing quarter chord sweep angle)
		16	Wing angle-of-zero-lift with no flaps [deg]
		17	Increase in wing pitching moment coefficient at take-off
		18	Increase in wing pitching moment coefficient at landing

APPENDIX VI - cont.

COMMON BLOCK	ARRAY	NO.	DESCRIPTION [UNITS, IF APPLICABLE]
		19	Wing pitching moment coefficient at approach
		20	Increase in drag due to flap deflection
	PX	1	Pitching moment reduction coefficient
		2	TSFC reduction coefficient
		3	Weight reduction coefficient
		4	Drag reduction coefficient
		5	Disconnect rubber engine (1.0 = yes; 0.0 = no)
		6	Maintenance cost boost (% Boost = PX(6) * 5%)
		7	Purchase price boost (% Boost = PX(7) * 5%)
		8	Maneuver load alleviation (Reduction in design limit load in g's)
GRAVITY	CGS	1	Aft cruise C.G. position [% MAC]
		2	Aft approach C.G. position [% MAC]
		3	Forward cruise C.G. position [% MAC]
		4	Forward approach C.G. position [%MAC]
		5	Landing gear position [% MAC]
		6	Required distance between C.G. and landing gear [% MAC]
STAB	DERIVAP	1	Approach $C_{L\alpha}$
		2	$C_{D\alpha}$
		3	$C_{M\alpha}$
		4	C_{L_u}
		5	C_{D_u}
		6	C_{M_u}
		7	C_{L_q}
		8	C_{D_q}
		9	C_{M_q}
		10	$C_{L\dot{\alpha}}$
		11	$C_{D\dot{\alpha}}$
		12	$C_{M\dot{\alpha}}$

APPENDIX VI - cont.

COMMON BLOCK	ARRAY	NO.	DESCRIPTION [UNITS, IF APPLICABLE]
		13	$C_{L\delta}$
		14	$C_{D\delta}$
		15	$C_{M\delta}$
	DERIVCR	1	Cruise $C_{L\alpha}$
		2	$C_{D\alpha}$
		3	$C_{M\alpha}$
		4	C_{L_u}
		5	C_{D_u}
		6	C_{M_u}
		7	C_{L_q}
		8	C_{D_q}
		9	C_{M_q}
		10	$C_{L\dot{\alpha}}$
		11	$C_{D\dot{\alpha}}$
		12	$C_{M\dot{\alpha}}$
		13	$C_{L\delta}$
		14	$C_{D\delta}$
		15	$C_{M\delta}$
	STOR	1	Cruise $C_{L\alpha}$ wing
		2	$C_{L\alpha}$ horizontal tail
		3	$\partial\varepsilon/\partial\alpha$
		4	Stick fixed neutral point [% MAC]
		5	Stick fixed maneuver point [% MAC]

APPENDIX VI - cont.

COMMON BLOCK	ARRAY	NO.	DESCRIPTION [UNITS, IF APPLICABLE]
		6	Approach $C_{L\alpha}$ wing
		7	$C_{L\alpha}$ horizontal tail
		8	$\partial\epsilon/\partial\alpha$
		9	Stick fixed neutral point [% MAC]
		10	Stick fixed maneuver point [% MAC]
		11	C_{mac} fuselage
		12	C_{mac} engine
WTSVE	WTS	1	Maximum gross weight at take-off [lbs]
		2	Empty weight [lbs]
		3	Fuel flow rate [lbs/block hour]
		4	Manufacturers airframe weight [lbs]
		5	Landing weight after mission [lbs]
		6	Fuel weight including reserves [lbs]
		7	Aircraft specific density (cruise), $\frac{m}{Sc}$
		8	Radius of gyration squared (cruise), I_y/m [ft]
		9	Aircraft specific density (approach), $\frac{m}{Sc}$
		10	Radius of gyration squares (approach), I_y/m [ft]
		11	Altitude at mid cruise [ft]
		12	L/D_{max} at cruise altitude
		13	Pitch moment of inertia (cruise), [slug-ft]
		14	Pitch moment of inertia (approach), [slug-ft]
		15	Weight at mid cruise [lbs]
		16	Fuel cost [\$/gal]
		17	Cruise velocity [knots]
		18	Flight time for mission [hrs]
		19	Block time [hrs]
		20	Weight of fuel to fly economic mission [lbs]

APPENDIX VII - ASSUMPTIONS USED IN CALCULATING
TRANSPORT DESIGN FACTORS

MISSION:

Cruise Mach Number	.80
Divergence Mach Number	.84
Design Range	6500 km
Number of Seats	200
Cargo	33400 N
Maximum Lift Coefficient	3.15
Landing Field Requirement	2440 m
Take-Off Field Requirement	3050 m

GEOMETRY:

Wing Sweep Angle	26.4 deg
Wing Thickness Ratio	.12
Wing Taper Ratio	.38
Wing Incidence Angle	2 deg
Wing Geometric Twist	5 deg
Tail Thickness Ratio	.10
Tail Sweep Angle	30 deg
Tail Taper Ratio	.4
Vertical Tail Sweep	35 deg
Ratio of Rudder Area to Vertical Tail Area	.30
Ratio of Elevator Chord to Horizontal Tail Chord	.25
Ratio of Flap Span to Wing Span	.6
Maximum Flap Deflection	45 deg
Fuselage Diameter	5.08 m
Height of Aerodynamic Center Above c.g.	.08 MAC
Height of Thrust Vector Above c.g.	-.12 MAC
Height of Horizontal Tail Above c.g.	0
Number of Engines	2

ECONOMICS:

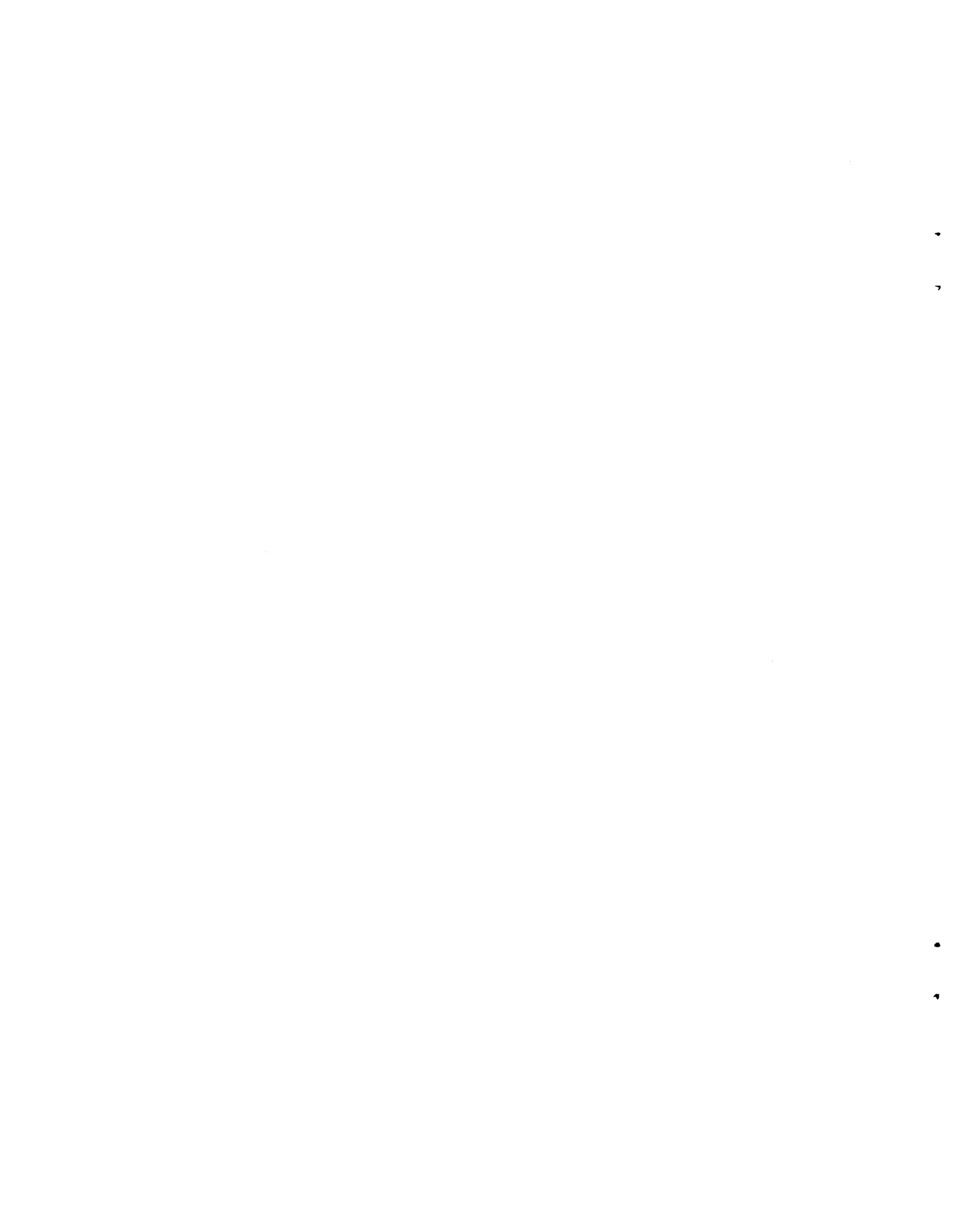
Fuel Cost	20¢/liter
Load Factor	.55
Fare	9¢/seat-naut. mi
Utilization Rate	3200 hr/yr
Depreciation Period	14 yr
Residual Value	12 percent
Tax Rate	.48
Year of Study	1979
Assumed Annual Inflation Rate	.07
Number of Prototype Aircraft	2

APPENDIX VII - cont.

Aircraft Fleet Size	250
Initial Production Rate	.5/month
Full Production Rate	5/month
Engineering Rate	19.55 '74 \$/hr
Tooling Rate	14.00 '74 \$/hr
Labor Rate	10.90 '74 \$/hr
Engines for Test Aircraft	3
Ratio of Manufacturer's Airframe Weight to Take-Off Wt.	.75

MISCELLANEOUS:

Maximum Dynamic Pressure	5.13 N/m ²
Pressurized Volume	178.2 m ³
Number of Pilots	3
Number of Attendants	8
Air Conditioning Flow Rate	200 kg/min
Autopilot Channels (w/MUX)	5
General Capacity	750 kilovolt-amperes
Maintenance Complexity Factor	1.6
Hydraulics Volume Flow Rate	300 liters/min
Number of Inertial Platform Systems	1
Ratio of APU-on Time to Engine on Time	.1
Curved Windshield	
Ratio of First Class to Economy Seating	.15
Maximum Speed	483 knots
Supercritical Airfoil Technology	
Airfoil Design Lift Coefficient	.5
Some Nonlinear Aerodynamics Terms	
Baseline Engine	CF-6
Elevator Servo Time Constant	.1 sec



OPTIMAL DESIGN METHODOLOGY

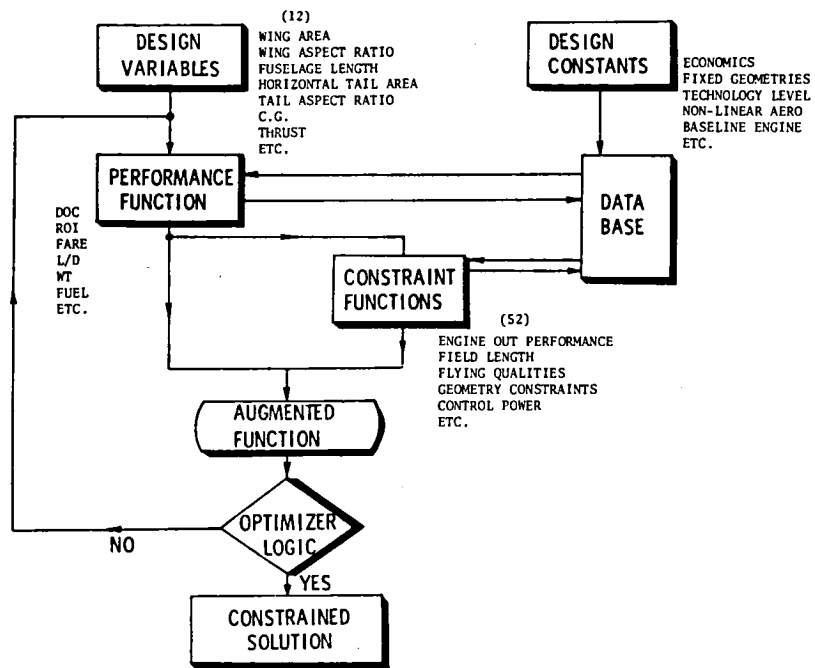


Figure 1.- Generalized flow diagram for OPDOT.

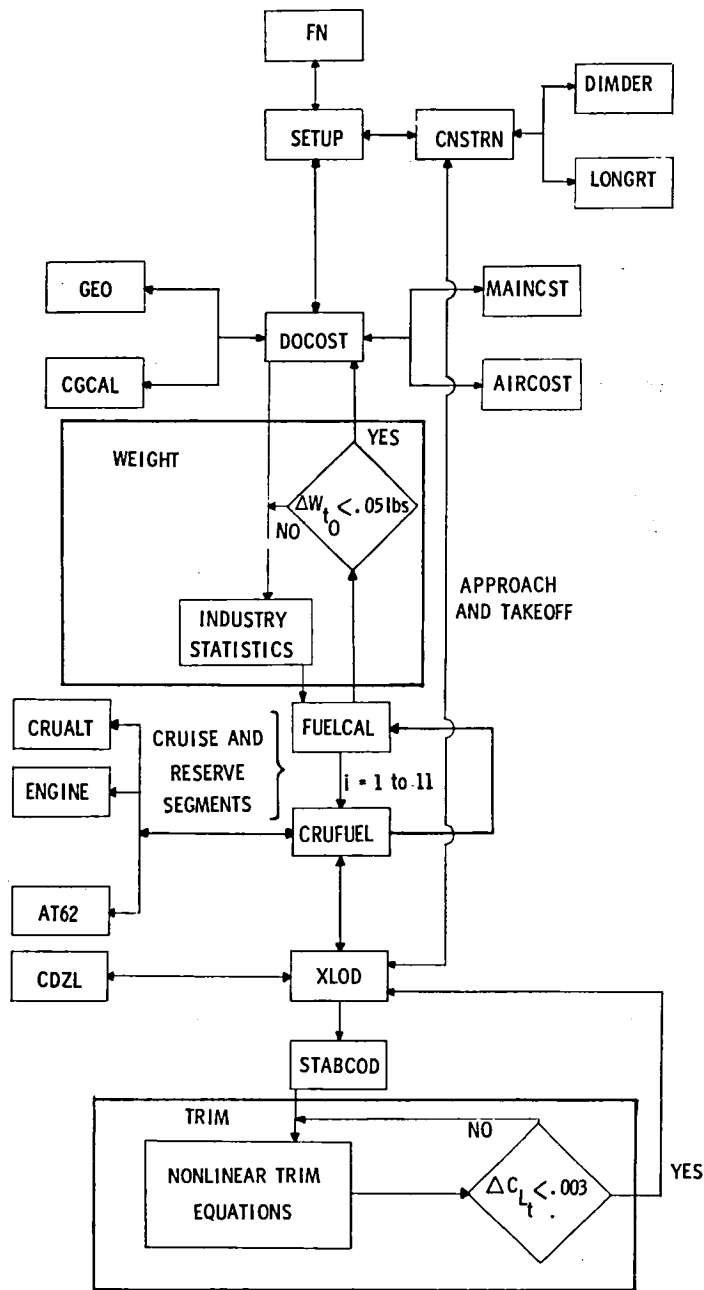


Figure 2.- Schematic showing primary calling sequence of subroutines used to evaluate the performance index and constraint functions.

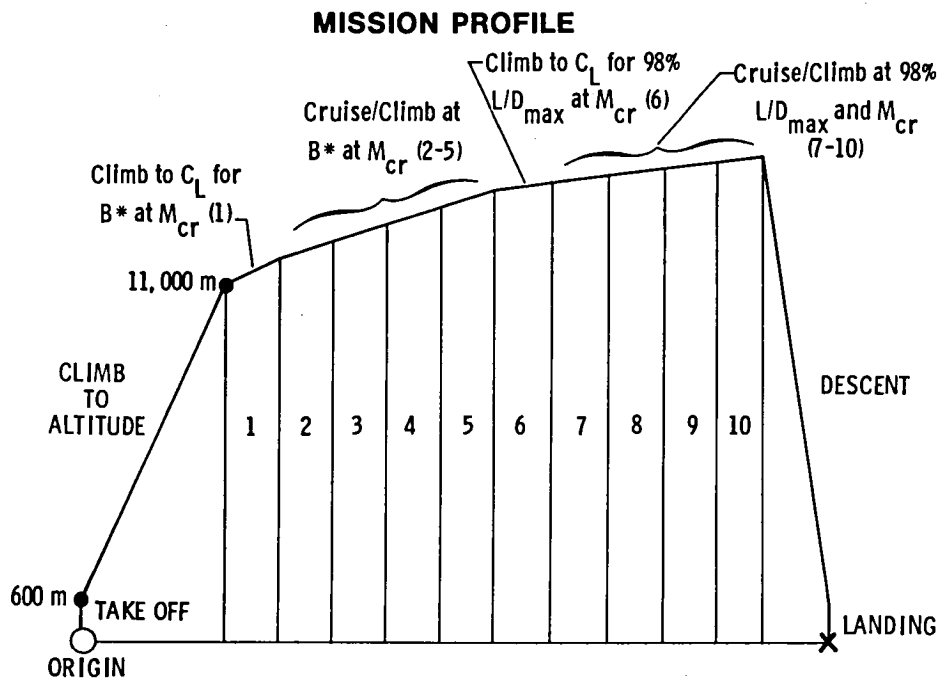


Figure 3.- Mission profile used in OPDOT.

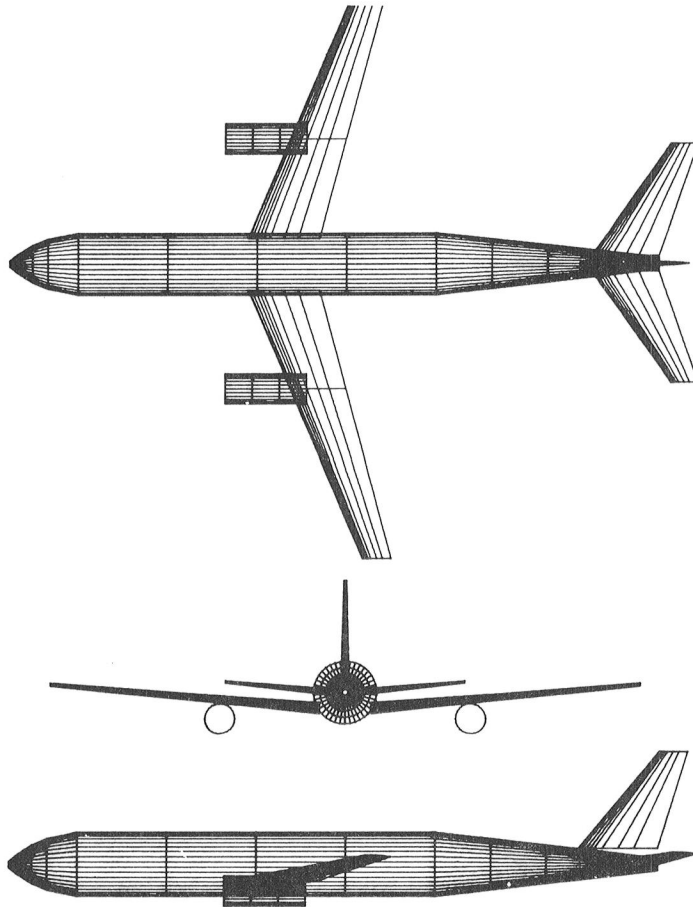
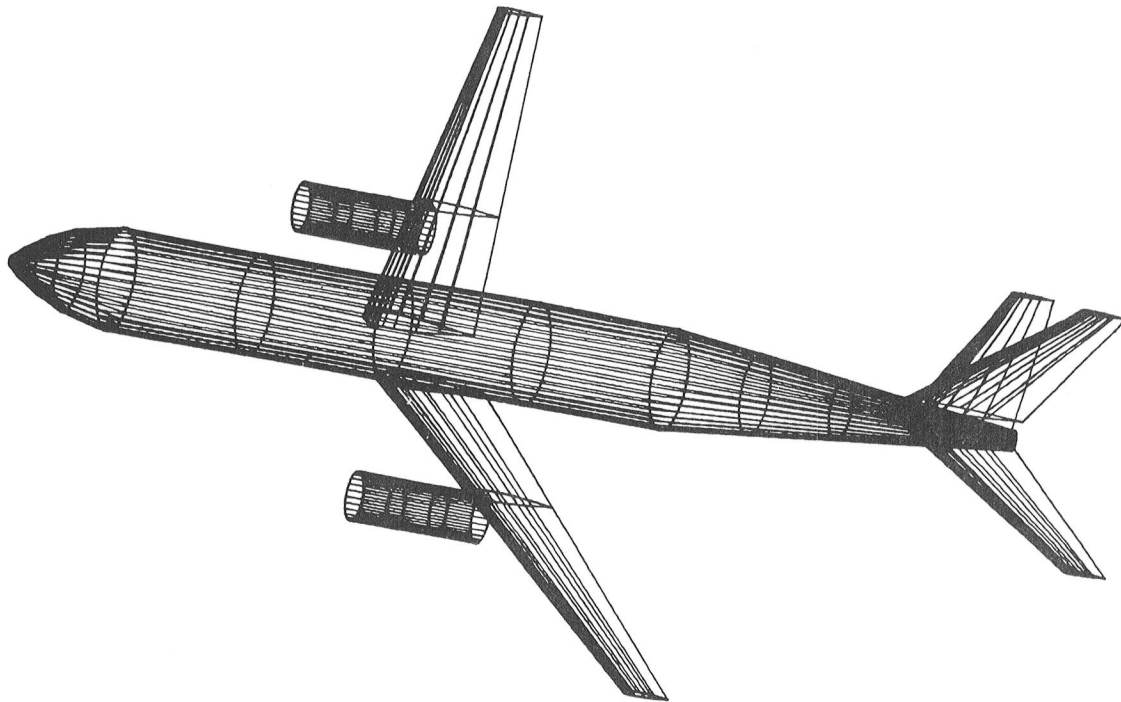


Figure 4.- Aircraft "picture" as drawn by the method of reference 28.
Aircraft pictured was optimized from data in Appendix II.

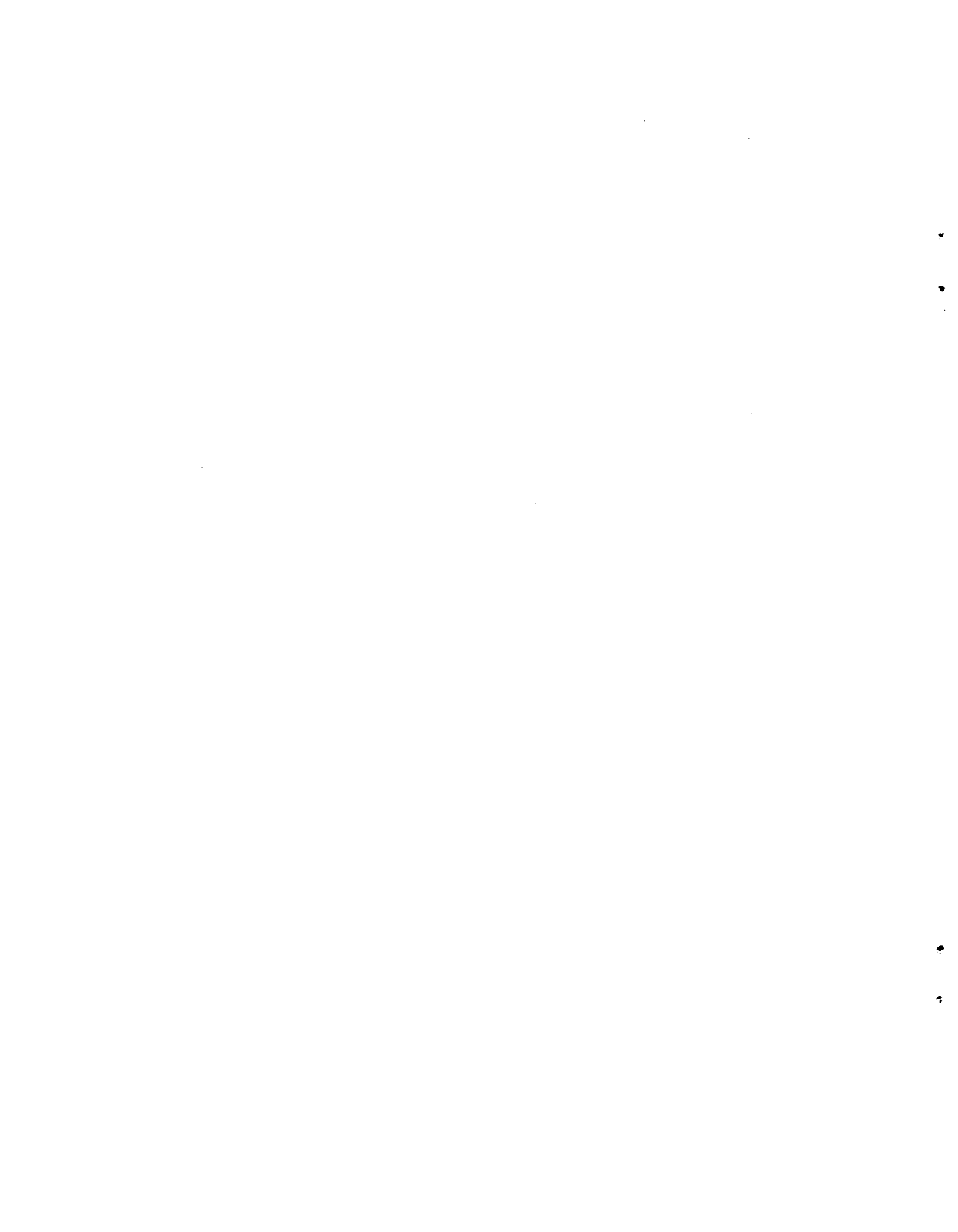


MIL 8785B LEVEL III (SIMPACT)

X Z -45.0 10.0-20.0

10.00RT

Figure 4.- Concluded.



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16. Abstract A description of a computer program, OPDOT, for the optimal preliminary design of transport aircraft is given. OPDOT utilizes constrained parameter optimization to minimize a performance index (e.g. direct operating cost per block hour) while satisfying operating constraints. The approach in OPDOT uses geometric descriptors as independent design variables. The independent design variables are systematically iterated to find the optimum design. The technical development of the program is provided and a program listing with sample input and output are utilized to illustrate its use in preliminary design. This is not meant to be a user's guide, but rather a description of a useful design tool developed for studying the application of new technologies to transport airplanes.					
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