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# Computer Program for a Four-Cylinder-Stirling-Engine Controls Simulation

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June 1982

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Prepared for  
**U.S. DEPARTMENT OF ENERGY**  
**Conservation and Renewable Energy**  
**Office of Vehicle and Engine R&D**



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Cleveland, Ohio 44135

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## Summary

A four-cylinder-Stirling-engine, transient-engine-simulation computer program is presented. The program is intended for controls analysis. The associated engine model has been simplified to shorten computer calculation time. The model includes engine mechanical drive dynamics and vehicle load effects. The computer program also includes subroutines that allow (1) acceleration of the engine by addition of hydrogen to the system and (2) braking of the engine by short circuiting of the working spaces. Subroutines to calculate degraded engine performance (e.g., due to piston ring and piston rod leakage) are provided. Input data required to run the program are described and flow charts are provided. The program is modular to allow easy modification of individual routines. Examples of steady-state and transient results are presented.

## Introduction

A Stirling engine is a mechanical device that operates on a closed regenerative cycle. Cycle expansion and compression of working fluid is done at different temperature levels. Flow is controlled by volume changes. Heat is supplied continuously and externally and extracted with a net conversion of heat to work. In its simplest form a Stirling process consists of two pistons, one operating in a hot space and one in a cold space. A working fluid between the pistons moves continuously back and forth within a working space between the hot and cold spaces, where it is continuously heated and cooled. The fluid passes through a regenerator, which is a heat storage device. The regenerator stores or gives off heat depending on the temperature of the fluid passing through it. The result of the process is the Stirling cycle. Stirling engines are used for stationary power generation, heat pumps, refrigeration systems, and artificial hearts. Another application is the automotive Stirling engine. In this application there are four pistons, all interconnected by four working spaces (fig. 1). This report presents a computer simulation of an automotive Stirling engine that can be used for controls research.

Stirling engine modeling is usually done for the purpose of predicting engine performance. The models are, of necessity, complex since Stirling engine performance (e.g., efficiency and fuel consumption) is quite sensitive to factors such as pressure drop within the engine. In general a Stirling engine performance model includes two pistons and the working space between them. The pistons are positioned as a function of time and are  $90^\circ$  out of phase. Control volumes are used to segment the working space into its components—expansion space, heater, regenerator,

cooler, and compression space. More than one control volume can be used to describe a component. Various heat transfer paths are usually included. Although many Stirling engines have more than one working space, the models used to predict performance generally do so for a single working space, and the resultant power generated is multiplied by the number of working spaces. One such model has been developed by Tew, Jeffries, and Miao and is described in reference 1. It contains 13 control volumes in the working space. The model calculates flow resistances and heat transfer coefficients as well as performance over a single engine cycle. Daniele and Lorenzo (ref. 2) have reduced the number of control volumes in the working space to seven, one each for the expansion space, heater, cooler, and compression space and three for the regenerator. Also, a metal volume has been associated with each regenerator gas volume. Average flow resistances and heat transfer coefficients are derived from the Tew model. Within each gas volume the continuity and energy equations are integrated and a simplified, first-order momentum term (flow resistance) is calculated. Upwind differencing (ref. 3) is used to calculate the interface volume temperatures for use in the energy equation. The resultant model has 17 state variables and uses a backward-difference integration scheme for problem solution. Results generated by that model compare well with experimental power and torque data over the entire speed and pressure ranges of the engine.

The aforementioned modeling approach produces acceptable steady-state (power and torque) predictions when working spaces in the engine are isolated. However, proposed control schemes for four-cylinder Stirling engines require that the working spaces not remain isolated. One such scheme is engine braking by short circuiting. In this case, all four working spaces are connected to high- and low-pressure manifolds. Flow enters or leaves a working space depending on the pressure differential and the orientation of the check valves between the pressure manifolds and the working spaces. A complete four-cylinder model is needed to analyze this controls problem.

One such four-cylinder controls model is described in reference 2. In that model, each working space model is further simplified to reduce computer run time. This simplification involves reducing the number of control volumes in a working space from seven to three—one for the expansion space and the heater, one for the regenerator, and one for the cooler and the compression space. It is also assumed (1) that the temperature within a control volume remains constant and (2) that the gas and regenerator mesh temperatures are equal. This reduces the number of state variables in a working space to three (or 12 for the whole engine). Results from this simplified model are presented in references 2 and 4 and agree well

with steady-state experimental data. The model has been used to predict the steady-state performance of the engine with short circuiting and with piston ring leakage. Reference 4 describes the use of the simulation to study supply transients with and without piston rod leakage.

This report documents the simplified four-cylinder model and its implementation. A users manual is given on how to run the simulation. Both steady-state and transient results are presented and a printout is provided for a test case. Finally flow charts are given for the subroutines and the overall simulation.

## Model Description

A schematic of the four-cylinder-Stirling-engine controls model is shown in figure 1. The four cylinders are shown interconnected by the four working spaces. Each working space contains three volumes – one for the expansion space and the heater, one for the regenerator, and one for the cooler and the compression space. Each volume is assumed to be at constant temperature. Variations in volume temperature can be scheduled as a function of engine speed. Variable names shown in figure 1 correspond to the computer coding. A complete symbols list is given in appendix A.

Besides the engine thermodynamic elements, three other system models are shown in figure 1—a drive geometry model, a working-fluid supply model, and a short-circuiting model. Torque is calculated as a function of differential forces on the pistons and summed in the drive geometry model. Losses due to auxiliaries, load effects, etc., are included. The net torque is then integrated once to give engine speed and again to give crank angle. The remaining models shown in figure 1 are associated with control schemes for accelerating and decelerating the engine. The acceleration system is indicated by alternate long- and short-dashed lines and is described in appendix B. Engine deceleration is accomplished by short circuiting the working spaces. This deceleration system is indicated by short-dashed lines. This system is also described in appendix B.

A schematic of the drive dynamics is shown in figure 2. Differential forces on the pistons are translated into torque through the vehicle drive geometry and summed to form total torque (TORQT). Torque due to engine friction is subtracted to form brake torque. This is available to drive the auxiliaries and the vehicle load. The vehicle inertia and the gear ratio are used to compute the effective load. The summation of torques is integrated to give engine speed (PSIDT) and again to give crank angle (PSI). The crank angle is used to generate piston position (by using the crank geometry). The model can be run in this manner, or piston position can be input as a function

of time with torque and cycle performance calculated at constant speed.

Relative to the performance models, the controls model is simple, yet it contains the essential elements for controls analysis. It has been shown in reference 2 that simulation predictions compare well with experimental data. However, it should be noted that heat flow dynamics are not included in the model. These effects may, in some instances, be significant and thus necessitate expansion of the model.

## Users Manual

### Simulation Flow Diagram

The overall simulation structure is shown in figure 3. Run conditions are set in the main program (MAINSE). Subroutine ICSTUP is then called to calculate initial conditions. SHORT2 and PISTN3 are called from ICSTUP to calculate the initial conditions for short circuiting and initial piston positions, respectively. ICSTUP then calls FOURW2, which is the integration subroutine. FOURW2 handles the incrementing of time, data output, and run termination. FOURW2 calls the Stirling engine simulation subroutine FWS3V2 to generate the information it needs for the Jacobian matrix associated with the backward difference integration. FWS3V2 calls LOSSES to calculate engine friction and auxiliary losses and vehicle load effects; PISTN3, to calculate piston positions from crank angle and crank geometry; PLEAK2, to calculate leakage flow if piston ring leakage effects are considered; SHORT2, to calculate short-circuiting flows if engine braking is desired; and SUPPL2, to calculate the flow into the engine and the phasing of the injected flows. SUPPL2 calls SUPLRK if rod leakage is considered. FWS3V2 then returns to FOURW2.

In figure 3, the body of FOURW2 is shown within the dashed line. The subroutines enclosed are actually subroutines to FOURW2. Although they are all called by and return to FOURW2, they are shown as calling one another to illustrate the looping that takes place within the subroutine. Once a Jacobian matrix is calculated, FOURW2 calls DMINV for a matrix inversion or BROYF1 for updates to a previously generated matrix. Subroutine BROYF1 contains the Broyden update algorithm. This algorithm is used to try to eliminate the need to calculate new Jacobian matrices as the simulation moves away from an operating point. The algorithm tries to accomplish this by continually updating the inverted Jacobian matrix. The reason for using the algorithm is to try to shorten computer calculation time since generating Jacobian matrices and taking inverses is very time consuming. The use of this algorithm is discussed in more detail in appendix C. Convergence is then checked. If the



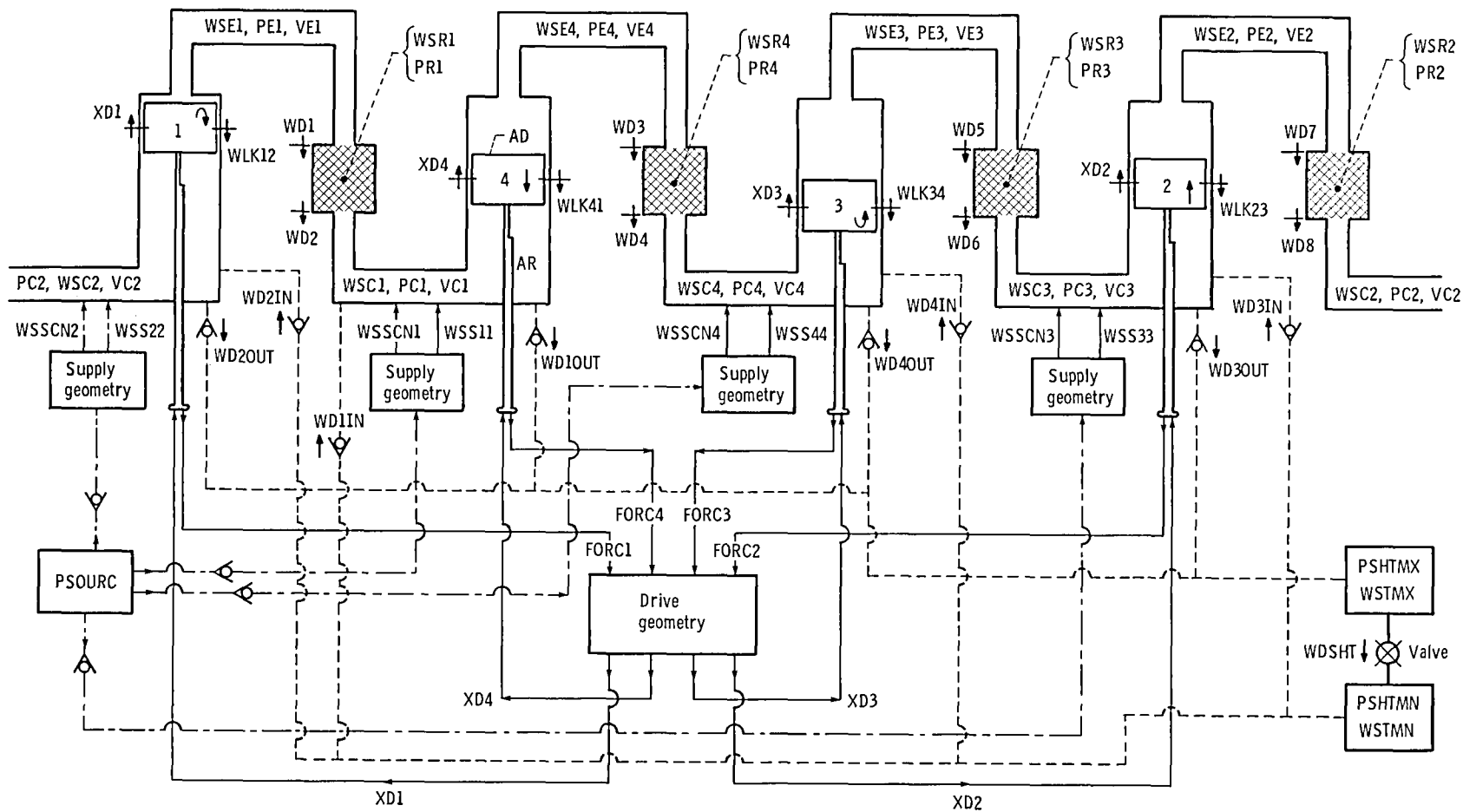


Figure 1. - Schematic of four-working-space (FWS) model.

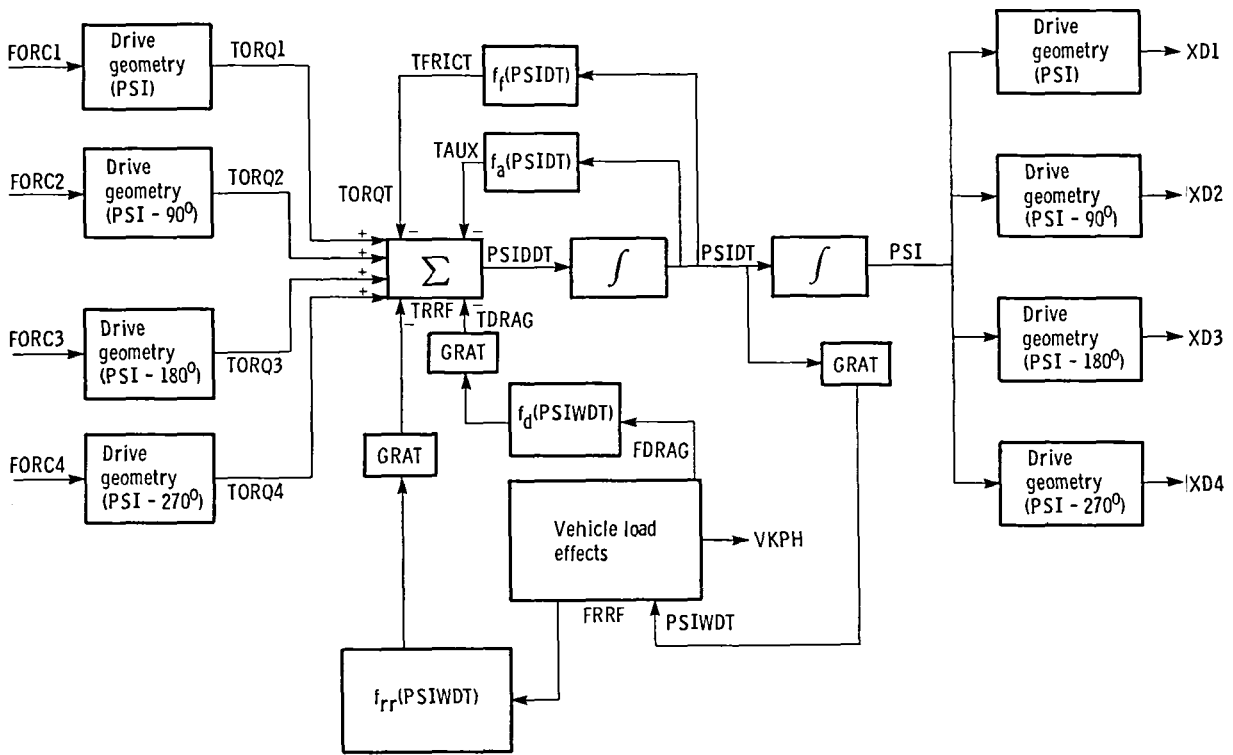


Figure 2. - Stirling engine drive dynamics.

simulation is not converged, more passes are made through FOURW2 to generate better iteration guesses or a new Jacobian matrix. If converged, FOURW2 calls TRAP to do a trapezoidal integration on the product of pressure and volume in the expansion and compression spaces. TRAP returns to FOURW2, which then calls OUTPUT if a printout is desired at the current time. OUTPUT returns to FOURW2; then GUESF2 is called to predict the next set of state variables for the next time step. This is done until the desired maximum number of time steps has been run, at which time FOURW2 terminates the run. Flow charts for all subroutines are given in appendix C.

### Program Setup

The program setup is done in the main program MAINSE: Switches are set to indicate the type of transient desired, and engine geometry and flow data are input. Tables I to X indicate the required input as well as the options available. In table I engine geometric data are specified. The expansion-space dead volume (VOE) includes the heater volume; the compression-space dead volume (VOC) includes the cooler volume. The total regenerator volume excluding the volume of the mesh is denoted by VR. Table II lists the required heater and cooler wall temperatures. Table III lists the flow resistances between the volumes. All the constants are listed in table IV. Data for the implicit integration

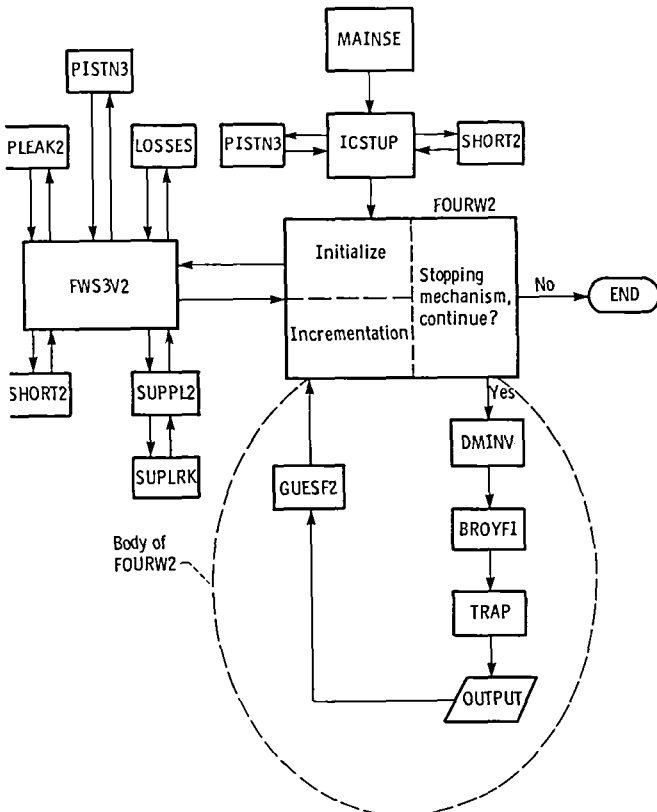


Figure 3. - Overall simulation structure.

method are listed in table V. Most of the integration settings should be kept the same. However, increasing MPAS and/or TOLPCG sometimes is helpful for difficult convergence problems (not observed in this application). The simulation will continue to run if MPAS is exceeded but will output an error message indicating it has been exceeded.

The different options available can be selected by a set of switches defined in table VI. ISS must be set equal to zero and MATRIX, equal to 1. The rest of the switches are user definable. Table VII lists all the run conditions that must be specified. Table VIII defines the load characteristics. Table IX describes the cycle data – the number of cycles to be run and the number of integrations per cycle. Table X lists the required transient data. If no supply or short-circuiting transients are desired, the cycle start-and-stop conditions for these options should be set higher than the number of cycles desired. Table XI lists all the common blocks and the subroutines that contain them. This table is provided so that the user may more easily define data transfer between subroutines.

## Output Options

The user may select from a number of output and debug options. If ICALC=1, a short printout is specified. The output, where all symbols are defined in appendix A, is given in table XII. Outputs include heater temperature (TWH), cooler temperature (TWC), cycle mean pressure (CYCLPR), engine drive mode (NONENG), number of cycles to be run (NUMBCY), piston ring leakage area scalar (ALEAK), piston rod leakage area (ARLEAK), supply pressure (PSOURC), the time step to start the supply (ISUPST), and the time step to start short circuiting (ISHTST). No output values are given in this example since this output option was used for all the test cases.

Next, results from the output data are printed out at the desired time steps. Power and torque calculations along with crank angle, mean pressure, and engine speed are output. ITRAN indicates the number of time steps taken up to the printout; and KWORK indicates the number of time steps in the calculation of the pressure-volume area. (Note that if KWORK = 101, 100 time steps were taken, since the first time step printed out is the initial condition.)

If ICALC=0, a long printout is specified. An example of a long printout is shown in table XIII. At each time point a complete listing of all engine variables is given. Note that the output is arranged in rows of four (except for the overall parameters). The first row is for the first working space; the second, for the second working space; etc. The output includes pressure, temperature and volume data, flow data, convergence data (guess variables (VS) and errors (E)), the short-circuiting

system, and finally, power and torque data. Data are given for this printout as an example; subsequent examples will make use of the short printout (ICALC=1).

There is also a debug option to aid in solving problems that may occur in the simulation. This option is specified in MAINSE by NOBUG. If NOBUG=1, the option is not used unless (1) there is a problem with convergence (the maximum number of allowable iteration passes (MPAS) is exceeded without convergence) or (2) there is a problem in generating a partial derivative for the Jacobian matrix. In both cases the debug option comes from FWS3V2. No printout of variable names is given. However, an indicator shows where and what subroutine the debug output comes from. For example, if “DEBUG PRINTOUT FROM FWS3V2 NUMBER 1” is printed, the user can go to FWS3V2 and look for the comment that indicates debug printout number 1. Using the data printed and the FORTRAN listing of the variable names, the user should be able to debug his program.

If the debug option is called (NOBUG=0), a dump of all variables as they are calculated comes from FOURW2 and FWS3V2. This option should be used judiciously because of the amount of data printed. Again, an indicator points to the source of the debug output to help the user find the source of a problem. A sample debug is shown in table XIV. The first part of the output comes from ICSTUP and gives all the initial conditions calculated. Next comes the heading “DEBUG OUTPUT FROM FOURW2 NUMBER 1.” Here the variable TIME is listed. Next “DEBUG PRINTOUT FROM FWS3V2 NUMBER 1” is printed. Here the variables are not labeled, so the user must trace through the FORTRAN for FWS3V2 to the proper area of code to begin debugging the problem. In the sample the second debug output from FWS3V2 is also given. The output “CONVERGENCE IN ERR VECTOR” is printed if NOBUG=0 and convergence occurs.

## Output – Test Cases

Two output test cases – a supply transient and a short-circuiting transient are given. Input and output data are provided for both cases.

### Supply Transient (100 Points per Cycle)

A supply transient is used as the first test case. The assumed initial conditions for the engine are a mean pressure of 5 MPa and a speed of 2000 rpm. After five cycles, hydrogen is injected to accelerate the engine for 1000 engine cycles. The supply pressure is 10 MPa and is constant. Leakage through piston rings and piston rods is not considered.

The FORTRAN input in MAINSE for this case is shown in table XV. The transient is defined by CYCLPR = 5.0, SPDRPM = 2000.0, NCYSUP = 5, NUMBCY = 1000, PSOURC = 10.0, ALEAK = 0.0, and ARLEAK = 0.0. For this case the Broyden update algorithm is not used (IBRYTH = 0); the step size is set by the desired 100 integration points per cycle (NPTPCY = 100); the desired printout is at every 100 points (IPRTOP = 100); the short printout option is desired (ICALC = 1); and no short circuiting is used. (NCYSHT is set above NUMBCY, or at 50 000.)

A sample output for the test case is shown in table XVI. Note that TIME is incremented in such a way that the specified number of integration points per cycle is obtained. Therefore the time step is variable as a function of engine speed. For the example presented, only parts of the printout are shown because of the large number of engine cycles simulated. Before a specified limit on CPU time was exceeded, 803 engine cycles (20.77 sec of engine time) were simulated. The simulation was run on an IBM 370/3033 computer and used 20 minutes of CPU time. Thus the simulation takes about 1.5 seconds of CPU time per engine cycle. Figure 4 shows a plot of the results. Note that the engine mean pressure (PAVEMP) and output power (POWER) rise quickly. Engine speed rises more slowly because of the effective inertia of the load.

#### Supply Transient (25 Points per Cycle)

The second test case is the same as the first case but has NPTPCY = 25 instead of 100. Sample output is presented

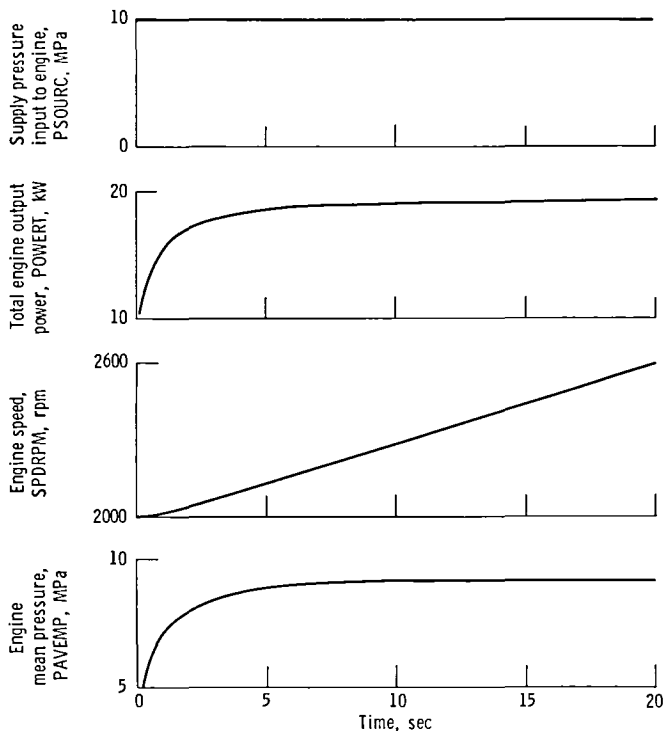


Figure 4. - Supply transient (100 integration points per cycle).

in table XVII. Note that KWORK = 26 since there are 25 points per cycle. POSDEG is somewhat off after each cycle (270.2°) since the integration is coarser than for the 100-points-per-cycle case. Also, at some time points the simulation does not converge. Since MPAS is set equal to 20 in MAINSE, the simulation prints a debug output after 21 iteration passes. The message "ITERATION FAILURE 13 21" "DEBUG OUTPUT FROM FWS3V2, FLOW CONTINUES" contains the number of converged errors, 13 (this will vary), and MPAS plus 1, 21. Note in the first debug printout that there are 13 converged errors but 14 states. Error 7 is  $-0.115E-3$ , which is greater than the specified error tolerance (TOLSS in MAINSE),  $-0.1E-3$ . This convergence failure occurs because this is a rather coarse integration (large step size). The simulation continues, however, and eventually recovers.

Since the simulation fails to converge, there may be some question about the validity of the output. Figure 5 shows a comparison of the 25- and 100-points-per-cycle cases. There is excellent agreement between the cases because the errors that do not converge are very close to the tolerance band. For the 25-points-per-cycle case, all 1000 cycles were simulated in 14 minutes of CPU time on the IBM 370/3033 computer, or about 0.81 second of CPU time per cycle. This amounts to 25.33 seconds of engine run time.

As a matter of interest, the 25-points-per-cycle case was rerun by using the Broyden update algorithm

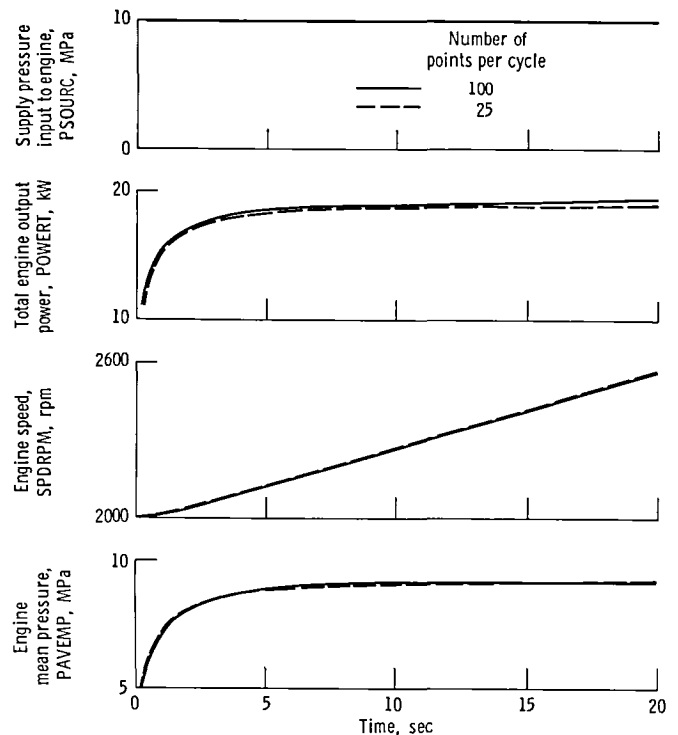


Figure 5. - Comparison of supply transients for different integration step sizes.

(IBRYTH = 1). The case took about the same amount of CPU time for 1000 cycles as it did without the algorithm, the only difference being that two more iteration failures occurred. It may be that the number of calculations required for the algorithm to update the inverted matrix approaches that required for generating a new matrix and its inverse for low-order systems. The algorithm is supplied in this simulation package to allow for expansion of the simulation to include more volumes, the energy equation dynamics, and a control system.

The increase in the time step (decrease in the number of integration points per cycle) is desirable to decrease the computer run time. However, as the integration becomes coarser, some iteration failures can occur. Good agreement may still result, depending on how close the unconverged error was to the tolerance band at the convergence failure. This is problem dependent. The same supply case was run with 50 integration points per cycle. No iteration failures occurred, and 1000 engine cycles took 18 minutes of 370/3033 CPU time, or 1.1 seconds of CPU time per cycle. Again good agreement was obtained with the 100-points-per-cycle case.

### Short-Circuit Transient

The final test case is a short-circuit transient. This is set up in MAINSE by setting the short-circuit valve area (ASHTT), the cycle at which to start the short circuiting (NCYSHT), and the cycle at which to stop the short circuiting (NCYSHS) and by setting the supply start (NCYSUP) and the supply stop (NCYSTP) cycles greater than the maximum number of cycles (NUMBCY). The plenum pressures PSHTMX and PSHTMN are set internally in the program to 1 MPa above and 1 MPa below the mean pressure, respectively. The MAINSE statements for this case are given in table XVIII. The output for this case is shown in figure 6. Maximum and minimum plenum pressures are shown at the top of the figure. Their initial values are 16 and 14 MPa, respectively. At five cycles (126 time steps) a short-circuiting sequence is begun. The valve area (ASHTT) is set equal to zero initially so that the plenums come to maximum and minimum pressures of 18.9 and 11.7 MPa, respectively. Then, 500 time steps later (internally set in the program), the short-circuiting valve is opened. The plenum pressures respond immediately, as indicated. Total engine power drops from 56 to 36 MPa when the valve opens. Speed drops off more slowly because of inertia effects. The torque, after 18 seconds of engine run time, is still slightly negative. Hence, speed continues to decrease. Mean pressure in the engine stays fairly constant.

The test cases show that the simulation is capable of producing transients that are representative of Stirling engine controls analysis. The input routine (MAINSE)

allows for user selection of the desired transient and for detailed study of all or part of the transient. Results can be obtained over many engine cycles (as in the test cases) or on an individual cycle basis (as was done in ref. 4).

### Concluding Remarks

A four-cylinder-Stirling-engine computer program is presented. The program is intended for controls analysis. The associated engine model has been derived from a more complex four-cylinder engine model. The simpler controls model results in a decrease in computer calculation times. The model includes drive dynamics and vehicle load effects. The computer program also includes subroutines that allow simulation of control strategies such as acceleration of the engine by adding to the inventory of hydrogen in the system and braking of the engine by short circuiting between the working spaces. Subroutines are provided to calculate degraded engine performance due to piston ring leakage.

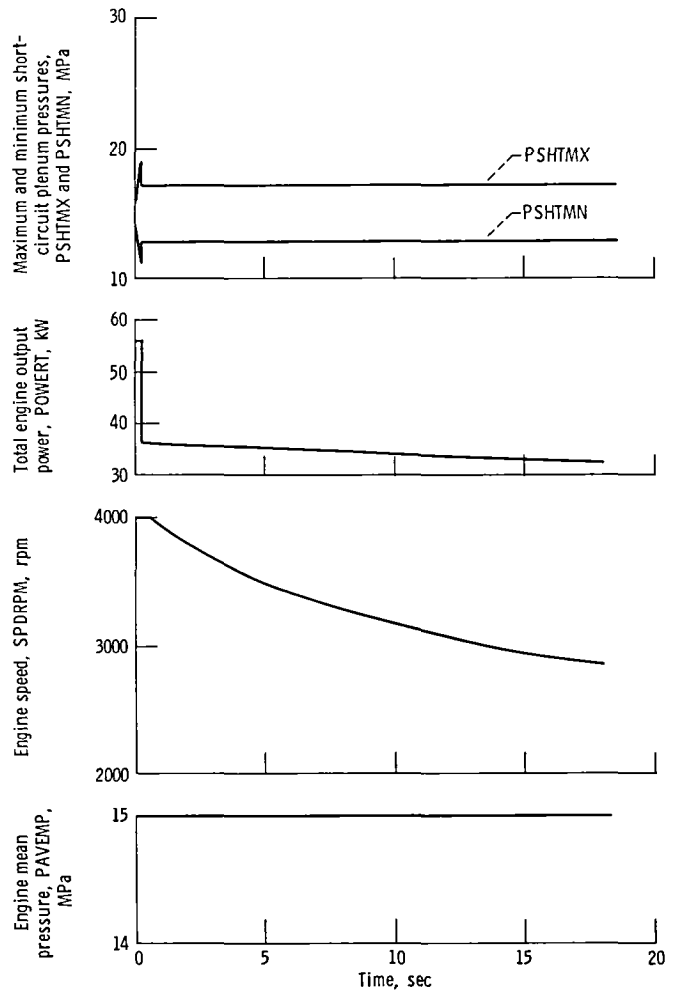


Figure 6. - Short-circuit transient. Valve area, ASHTT, 0.2 cm<sup>2</sup>.

All input data required to run the program are described, and complete FORTRAN listings of the main program and all the subroutines are provided. Flow charts of the overall simulation and the subroutines are also given. The simulation is modular to allow for easy modification of the model.

An input routine is provided in which the user specifies the transient to be run by setting switches and supplying the proper geometric and engine data. The output is also selected by the user by setting a switch in the input routine. A very detailed printout at the desired printout increment or a less detailed printout can be selected. The integration step size and the printout interval do not have to be the same.

The simulation has been run to generate both steady-state and transient results. Power and torque predictions from the simulation compare well with experimental data over a wide range of engine speeds and pressures. The simulation is capable of predicting steady-state performance with piston ring leakage and short circuiting between the working spaces. Engine acceleration and deceleration data are presented, along with associated printouts that can be used as test cases.

Lewis Research Center  
National Aeronautics and Space Administration  
Cleveland, Ohio, February 26, 1982

## Appendix A

### Symbols

|        |                                                                             |               |                                                                                             |
|--------|-----------------------------------------------------------------------------|---------------|---------------------------------------------------------------------------------------------|
| A      | piston ring leakage area, cm <sup>2</sup>                                   | CCCHKP        | previous change in piston 3 position, cm                                                    |
| AAN    | problem order                                                               | CCCKKK        | scalar change to time increment to predict when piston 3 will again reach its initial value |
| AD     | piston area, cm <sup>2</sup>                                                |               |                                                                                             |
| ADJCMP | adjustment to compression-space temperature due to speed, K                 |               |                                                                                             |
| ADJEXP | adjustment to expansion space temperature due to speed, K                   |               |                                                                                             |
| ADM    | piston area, m <sup>2</sup>                                                 | <b>CMAT</b>   | storage matrix in BROYP1                                                                    |
| ADR    | piston rod area, cm <sup>2</sup>                                            | COS1          | } cosine of crank angle and 90° offsets                                                     |
| ADRM   | piston rod area, m <sup>2</sup>                                             | COS2          |                                                                                             |
| ADS1   | } slot area in piston rods 1 to 4 for working-fluid supply, cm <sup>2</sup> | COS3          |                                                                                             |
| ADS2   |                                                                             | COS4          |                                                                                             |
| ADS3   |                                                                             |               |                                                                                             |
| ADS4   |                                                                             |               |                                                                                             |
| AGDN1  | } adjustments to cycle pressures 2, 3, and 4, kg/(m <sup>2</sup> N)         | CYCLPM        | maximum cycle pressure, MPa                                                                 |
| AGDN2  |                                                                             | CYCLPR        | current cycle pressure, MPa                                                                 |
| AGDN3  |                                                                             | DEGR          | conversion factor, rad/deg                                                                  |
| AIE    | engine moment of inertia, N-m/sec <sup>2</sup>                              | <b>DELE</b>   | vector of changes in error vector                                                           |
| AINERT | total effective moment of inertia, N-m/sec <sup>2</sup>                     | DELPSI        | change in crank angle, rad                                                                  |
| AIVEH  | equivalent load moment of inertia, N-m/sec <sup>2</sup>                     | DELT          | change in time, sec                                                                         |
| AIWHEL | wheel moment of inertia, N-m/sec <sup>2</sup>                               | <b>DELTAV</b> | vector change in guess variables                                                            |
| AKG1   | } adjustment to cycle pressure, N-m/kg                                      | <b>DELX</b>   | vector change in guess variables (Broyden algorithm)                                        |
| AKG2   |                                                                             |               |                                                                                             |
| AKG3   |                                                                             |               |                                                                                             |
| ALEAK  | piston ring leakage area scalar                                             | <b>DELY</b>   | vector change in error variables (Broyden algorithm)                                        |
| ALPHA  | crank angle lag, deg                                                        | DENOM         | scalar change to cycle pressure, cm <sup>3</sup> /K                                         |
| AMPLIT | half of piston stroke, cm                                                   | DETERM        | matrix determinant                                                                          |
| AO     | piston ring leakage area, cm <sup>2</sup>                                   | DIAM          | orifice diameter, cm                                                                        |
| APSI   | number of crank rotations                                                   | DIR1          | } piston ring leakage flow direction                                                        |
| APTS   | number of integrations per cycle                                            | DIR2          |                                                                                             |
| AR     | piston rod area, cm <sup>2</sup>                                            | DIR3          |                                                                                             |
| AREA   | trapezoidal integration area, N-m                                           | DIR4          |                                                                                             |
| AREAO  | summed trapezoidal integration area, N-m                                    | DIV           | stored mass scalar                                                                          |
| ARLEAK | piston rod leakage area, cm <sup>2</sup>                                    | DRIVO         | initial condition for drive torque, N-m                                                     |
| AS     | square of half stroke, cm <sup>2</sup>                                      | <b>E</b>      | error vector                                                                                |
| ASHTT  | short-circuit valve area, cm <sup>2</sup>                                   | <b>EMAT</b>   | Jacobian matrix for 14th-order system                                                       |
| BIGA   | pivot element in matrix invert routine                                      | <b>ERRBSE</b> | past error vector                                                                           |
| BIGDEL | scalar for matrix predictor (biggest change)                                | FDRAG         | force due to vehicle air drag, N                                                            |
| BIGNUM | scalar for matrix predictor (biggest number)                                | FFFF1         | } torque scalar for each piston                                                             |
|        |                                                                             | FFFF2         |                                                                                             |
|        |                                                                             | FFFF3         |                                                                                             |
|        |                                                                             | FFFF4         |                                                                                             |
| CCCHK  | change of piston 3 position from initial value, cm                          | FORC1         | } force on each piston, N                                                                   |
|        |                                                                             | FORC2         |                                                                                             |
|        |                                                                             | FORC3         |                                                                                             |
|        |                                                                             | FORC4         |                                                                                             |
|        |                                                                             | FRAC          | external control for matrix convergence                                                     |
|        |                                                                             | FREQ          | engine rotational speed, rps                                                                |
|        |                                                                             | FREQQ         | engine rotational speed, rpm                                                                |
|        |                                                                             | FREQRP        | engine rotational speed, rpm                                                                |
|        |                                                                             | FRFR          | force due to rolling resistance, N                                                          |

|        |                                                                  |                                                       |                                                                       |                                                                                      |                                                                                      |                            |                                                                                           |        |
|--------|------------------------------------------------------------------|-------------------------------------------------------|-----------------------------------------------------------------------|--------------------------------------------------------------------------------------|--------------------------------------------------------------------------------------|----------------------------|-------------------------------------------------------------------------------------------|--------|
| G      | gravitational constant, kg/(MPa sec <sup>2</sup> )               | LW                                                    | scratch vector                                                        |                                                                                      |                                                                                      |                            |                                                                                           |        |
| GR     | gear ratio                                                       | M                                                     | index                                                                 |                                                                                      |                                                                                      |                            |                                                                                           |        |
| GRAT   | overall gear ratio                                               | MATRIX                                                | switch for generating a new Jacobian matrix                           |                                                                                      |                                                                                      |                            |                                                                                           |        |
| GTRAN  | transmission gear ratio                                          | MATTOT                                                | counter for number of matrices generated during a transient run       |                                                                                      |                                                                                      |                            |                                                                                           |        |
| HOLD   | variable for row and column interchange in matrix invert routine | MBUG                                                  | debug switch for iteration failure                                    |                                                                                      |                                                                                      |                            |                                                                                           |        |
| I      | integer                                                          | MPAS                                                  | maximum allowable iteration passes                                    |                                                                                      |                                                                                      |                            |                                                                                           |        |
| IBRYTH | switch for using Broyden algorithm                               | MW                                                    | scratch vector                                                        |                                                                                      |                                                                                      |                            |                                                                                           |        |
| ICALC  | switch for output options                                        | N                                                     | system order                                                          |                                                                                      |                                                                                      |                            |                                                                                           |        |
| ICON   | counter for converged errors                                     | NCYSHS                                                | cycle at which to stop short circuiting                               |                                                                                      |                                                                                      |                            |                                                                                           |        |
| IDB    | switch for internal DEBUG output                                 | NCYSHT                                                | cycle at which to start short circuiting                              |                                                                                      |                                                                                      |                            |                                                                                           |        |
| IHPCNV | switch for causing a matrix to be generated at every time point  | NCYSTP                                                | cycle at which to stop supply                                         |                                                                                      |                                                                                      |                            |                                                                                           |        |
| IICC   | counter for partial derivative generation                        | NCYSUP                                                | cycle at which to start supply                                        |                                                                                      |                                                                                      |                            |                                                                                           |        |
| IJ     | index                                                            | NITER                                                 | counter for number of iterations at a time point                      |                                                                                      |                                                                                      |                            |                                                                                           |        |
| IK     | index                                                            | NK                                                    | index                                                                 |                                                                                      |                                                                                      |                            |                                                                                           |        |
| INDICA | switch for sign change on error variable                         | NMAT                                                  | counter for number of Jacobian matrices generated at a time point     |                                                                                      |                                                                                      |                            |                                                                                           |        |
| IPRTOP | switch for number of printouts per cycle                         | NOBUG                                                 | switch for a debug printout                                           |                                                                                      |                                                                                      |                            |                                                                                           |        |
| IROT   | switch for indicating a complete crank rotation                  | NONENG                                                | switch for type of piston motion                                      |                                                                                      |                                                                                      |                            |                                                                                           |        |
| ISHSP2 | two time points after short circuiting starts                    | NPSI                                                  | reset PSI to zero after 360° rotation                                 |                                                                                      |                                                                                      |                            |                                                                                           |        |
| ISHSTP | time point for end of short circuiting                           | NPTPC                                                 | number of integration points per cycle plus 1                         |                                                                                      |                                                                                      |                            |                                                                                           |        |
| ISHSUP | one time point after short circuiting starts                     | NPTPCY                                                | number of integration points per cycle                                |                                                                                      |                                                                                      |                            |                                                                                           |        |
| ISHTST | time point for start of short circuiting                         | NSTP                                                  | switch for storing past converged scale factors for iteration guesses |                                                                                      |                                                                                      |                            |                                                                                           |        |
| ISPSTP | time point for end of supply                                     | NTMAX                                                 | maximum number of iteration variables                                 |                                                                                      |                                                                                      |                            |                                                                                           |        |
| ISS    | switch for initial conditions                                    | NUMBCY                                                | number of engine cycles to be run                                     |                                                                                      |                                                                                      |                            |                                                                                           |        |
| ISTEP  | counter                                                          | PAUX                                                  | power lost due to engine auxiliaries, kW                              |                                                                                      |                                                                                      |                            |                                                                                           |        |
| ISUPST | time point for start of supply transient                         | PAVEMP                                                | cycle mean pressure for all four cylinders after iteration, MPa       |                                                                                      |                                                                                      |                            |                                                                                           |        |
| ITRAN  | counter for time steps                                           | PCCBAR                                                | cycle mean pressure for all four cylinders during iteration, MPa      |                                                                                      |                                                                                      |                            |                                                                                           |        |
| ITRMAX | maximum number of time steps                                     | PCCMAX                                                | cycle maximum pressure for all four cylinders during iteration, MPa   |                                                                                      |                                                                                      |                            |                                                                                           |        |
| IZ     | } index                                                          | PCCMIN                                                | cycle minimum pressure for all four cylinders during iteration, MPa   |                                                                                      |                                                                                      |                            |                                                                                           |        |
| J      |                                                                  | } index for setting time increment for crank rotation | PCMAX                                                                 | cycle maximum compression-space pressure for all four cylinders after iteration, MPa |                                                                                      |                            |                                                                                           |        |
| JI     |                                                                  |                                                       | } index                                                               | PCMIN                                                                                | cycle minimum compression-space pressure for all four cylinders after iteration, MPa |                            |                                                                                           |        |
| JN     |                                                                  |                                                       |                                                                       | } index                                                                              | PCNCHG                                                                               | iteration convergence rate |                                                                                           |        |
| JP     |                                                                  |                                                       |                                                                       |                                                                                      | } index                                                                              | PCOLD1                     | } compression-space pressure from previous time step for pressure-volume integration, MPa |        |
| JQ     |                                                                  |                                                       |                                                                       |                                                                                      |                                                                                      | } index                    |                                                                                           | PCOLD2 |
| JR     |                                                                  |                                                       |                                                                       |                                                                                      |                                                                                      |                            |                                                                                           | PCOLD3 |
| JWORK  | index for setting time increment for crank rotation              | PCOLD4                                                |                                                                       |                                                                                      |                                                                                      |                            |                                                                                           |        |
| K      | index                                                            |                                                       |                                                                       |                                                                                      |                                                                                      |                            |                                                                                           |        |
| KBROY  | counter for calls to Broyden algorithm                           |                                                       |                                                                       |                                                                                      |                                                                                      |                            |                                                                                           |        |
| KI     | } index                                                          |                                                       |                                                                       |                                                                                      |                                                                                      |                            |                                                                                           |        |
| KJ     |                                                                  | } index                                               |                                                                       |                                                                                      |                                                                                      |                            |                                                                                           |        |
| KK     |                                                                  |                                                       |                                                                       |                                                                                      |                                                                                      |                            |                                                                                           |        |
| KWORK  | counter for pressure-volume integration                          |                                                       |                                                                       |                                                                                      |                                                                                      |                            |                                                                                           |        |
| KWRIT  | counter for printout                                             |                                                       |                                                                       |                                                                                      |                                                                                      |                            |                                                                                           |        |
| L      | index                                                            |                                                       |                                                                       |                                                                                      |                                                                                      |                            |                                                                                           |        |



|        |                                                                                           |                                                       |                                                                                 |
|--------|-------------------------------------------------------------------------------------------|-------------------------------------------------------|---------------------------------------------------------------------------------|
| PCVCO1 | } summation of pressure-volume integration in compression space to previous time step, kW | PIE                                                   | constant (3.14159)                                                              |
| PCVCO2 |                                                                                           | PLOAD                                                 | power loss due to load, kW                                                      |
| PCVCO3 |                                                                                           | PNET                                                  | net power, kW                                                                   |
| PCVCO4 |                                                                                           | POSDEG                                                | crank angle, deg                                                                |
| PCVCR1 | } summation of pressure-volume integration in compression space to current time step, kW  | POSDEO                                                | initial-condition crank angle, deg                                              |
| PCVCR2 |                                                                                           | POSDT                                                 | speed, rad/sec                                                                  |
| PCVCR3 |                                                                                           | POSEOO                                                | initial-condition speed, rad/sec                                                |
| PCVCR4 |                                                                                           | POWERT                                                | total engine power, kW                                                          |
| PCY    | cycle pressure, MPa                                                                       | POWER1                                                | } power from each working space, kW                                             |
| PCY1   | } cycle pressure in each working space, MPa                                               | POWER2                                                |                                                                                 |
| PCY2   |                                                                                           | POWER3                                                |                                                                                 |
| PCY3   |                                                                                           | POWRE4                                                |                                                                                 |
| PCY4   |                                                                                           | PP1                                                   | } average pressure at piston ring, MPa                                          |
| PC1    | PC2                                                                                       | PP2                                                   |                                                                                 |
| PC3    | PC4                                                                                       | PP3                                                   |                                                                                 |
| PC4    | PP4                                                                                       |                                                       |                                                                                 |
| PC1MAX | } maximum compression-space pressure in each working space, MPa                           | PRRF                                                  | power loss due to rolling resistance, kW                                        |
| PC2MAX |                                                                                           | PR1                                                   | } regenerator pressure in each working space, MPa                               |
| PC3MAX |                                                                                           | PR2                                                   |                                                                                 |
| PC4MAX |                                                                                           | PR3                                                   |                                                                                 |
| PC1MIN | PC2MIN                                                                                    | PR4                                                   |                                                                                 |
| PC2MIN | } minimum compression-space pressure in each working space, MPa                           | PSHTMN                                                | minimum-pressure manifold pressure, MPa                                         |
| PC3MIN |                                                                                           | PSHTMX                                                | maximum-pressure manifold pressure, MPa                                         |
| PC4MIN |                                                                                           | PSI                                                   | crank angle, rad                                                                |
| PDRAG  |                                                                                           | PEMAX                                                 | PSIDDT                                                                          |
| PEMAX  | cycle maximum expansion-space pressure for all four cylinders after iteration, MPa        | PSIDEG                                                | crank angle, deg                                                                |
| PEMIN  | cycle minimum expansion-space pressure for all four cylinders after iteration, MPa        | PSIDT                                                 | crank angle velocity, rad/sec                                                   |
| PENG   | engine power loss due to auxiliaries and mechanical friction, kW                          | PSIM                                                  | crank angle adjusted to remain between 0 and 2 $\pi$ radians, rad               |
| PEOLD1 | } expansion space pressure from previous time step for pressure-volume integration, M     | PSIMD                                                 | adjusted crank angle, deg                                                       |
| PEOLD2 |                                                                                           | PSIWDT                                                | wheel velocity, rad/sec                                                         |
| PEOLD3 |                                                                                           | PSI1                                                  | } piston crank position, rad                                                    |
| PEOLD4 |                                                                                           | PSI2                                                  |                                                                                 |
| PEVEO1 | PSI3                                                                                      |                                                       |                                                                                 |
| PEVEO2 | PSI4                                                                                      |                                                       |                                                                                 |
| PEVEO3 | } summation of pressure-volume integration in expansion space to previous time step, kW   | PSOURC                                                | working-fluid storage pressure, MPa                                             |
| PEVEO4 |                                                                                           | R                                                     | gas constant, (MPa cm <sup>3</sup> )/(K kg)                                     |
| PEVER1 |                                                                                           | RAT                                                   | scalar change on step size for iteration                                        |
| PEVER2 |                                                                                           | RATIO                                                 | largest step-size change                                                        |
| PEVER3 | } summation of pressure-volume integration in expansion space to current time step, kW    | RATOO                                                 | ratio of slot valve opening length to piston rod length                         |
| PEVER4 |                                                                                           | RATT                                                  | length of slot valve opening, cm                                                |
| PE1    |                                                                                           | RATTT                                                 | scalar adjustment to expansion- and compression-space temperatures due to speed |
| PE2    |                                                                                           | } expansion-space pressure in each working space, MPa | REF                                                                             |
| PE3    | } power loss due to mechanical engine friction, kW                                        |                                                       |                                                                                 |
| PE4    |                                                                                           |                                                       |                                                                                 |
| PFRICT |                                                                                           |                                                       |                                                                                 |

|              |                                                                                               |        |                                                                                |
|--------------|-----------------------------------------------------------------------------------------------|--------|--------------------------------------------------------------------------------|
| RER          | flow resistance between expansion space and regenerator, (MPa sec)/kg                         | TEST1  | } pressure drop across piston rings for each piston, MPa                       |
| <b>RMAT</b>  | Jacobian matrix for 16th-order system                                                         | TEST2  |                                                                                |
| RODL         | crank rod length, cm                                                                          | TEST3  |                                                                                |
| RODLS        | $\text{SQRT}(\text{RODL}^2 + \text{AMPLIT}^2)$ , cm                                           | TEST4  |                                                                                |
| RR           | maximum error value                                                                           | TEO1   | } initial value of expansion-space temperatures for each working space, K      |
| RRC          | flow resistance between regenerator and compression space, (MPa sec)/kg                       | TEO2   |                                                                                |
| RS           | square of crank length, $\text{cm}^2$                                                         | TEO3   |                                                                                |
| RSHT         | flow resistance between manifolds and compression spaces, (MPa sec)/kg                        | TEO4   |                                                                                |
| RSHTCT       | flow resistance between high- and low-pressure manifolds, ( $\text{cm}^2 \text{MPa sec}$ )/kg | TE1    | } expansion-space temperature for each working space, K                        |
| RSHTT        | short-circuit flow scalar, $\text{kg}/(\text{sec MPa})$                                       | TE2    |                                                                                |
| RSUP         | supply flow resistance, ( $\text{cm}^2 \text{MPa sec}$ )/kg                                   | TE3    |                                                                                |
| RWHEEL       | radius of car wheel, cm                                                                       | TE4    |                                                                                |
| SES          | summation of squares of present errors                                                        | TFRICT | torque loss due to mechanical friction, N-m                                    |
| SESP         | summation of squares of past errors                                                           | TIME   | time, sec                                                                      |
| SGN          | sign of perturbation step                                                                     | TIMPRV | time at previous time step, sec                                                |
| SIN1         | } square of sines of crank angle and offsets                                                  | TLOAD  | torque loss due to load, N-m                                                   |
| SIN2         |                                                                                               |        |                                                                                |
| SIN3         |                                                                                               |        |                                                                                |
| SIN4         |                                                                                               |        |                                                                                |
| SIN11        | } sine of crank angle and offsets                                                             | TNET   | net torque, N-m                                                                |
| SIN22        |                                                                                               |        |                                                                                |
| SIN33        |                                                                                               |        |                                                                                |
| SIN44        |                                                                                               |        |                                                                                |
| SPEEDR       | engine speed, rad                                                                             | TOLPCG | convergence rate at which a decision is made to generate a new Jacobian matrix |
| SPDMAX       | maximum engine speed, rpm                                                                     | TOLSS  | error tolerance                                                                |
| SPDRPM       | engine speed, rpm                                                                             | TOL1   | lower limit for good partial derivatives                                       |
| STROKE       | piston stroke length, cm                                                                      | TOL2   | upper limit for good partial derivatives                                       |
| TAUX         | torque loss due to auxiliaries, N-m                                                           | TORMAX | maximum torque, N-m                                                            |
| TCO1         | } initial value of compression-space temperatures for each working space, K                   | TORMIN | minimum torque, N-m                                                            |
| TCO2         |                                                                                               |        |                                                                                |
| TCO3         |                                                                                               |        |                                                                                |
| TCO4         |                                                                                               |        |                                                                                |
| TC1          | } compression-space temperature for each working space, K                                     | TORQT  | total torque, N-m                                                              |
| TC2          |                                                                                               |        |                                                                                |
| TC3          |                                                                                               |        |                                                                                |
| TC4          |                                                                                               |        |                                                                                |
| TDRAG        | torque loss due to air drag, N-m                                                              | TORQ1  | } torque generated by each piston, N-m                                         |
| TEMP         | Broyden update scalar                                                                         | TORQ2  |                                                                                |
| TEMP1        | Broyden update scalar                                                                         | TORQ3  |                                                                                |
| <b>TEMP2</b> | Broyden update vector                                                                         | TORQ4  |                                                                                |
| <b>TEMP3</b> | Broyden update vector                                                                         | TRRF   | torque loss due to rolling friction, N-m                                       |
| TENG         | total torque loss due to engine auxiliaries and mechanical friction, N-m                      | TRO1   | } initial-condition regenerator gas temperature for all four working spaces, K |
|              |                                                                                               | TRO2   |                                                                                |
|              |                                                                                               | TRO3   |                                                                                |
|              |                                                                                               | TRO4   |                                                                                |
|              |                                                                                               | TR1    | } regenerator gas temperature for all four working spaces, K                   |
|              |                                                                                               | TR2    |                                                                                |
|              |                                                                                               | TR3    |                                                                                |
|              |                                                                                               | TR4    |                                                                                |
|              |                                                                                               | TSH    | short-circuit manifold temperature, K                                          |
|              |                                                                                               | TST31H | } pressure drop from compression spaces to high-pressure plenum, MPa           |
|              |                                                                                               | TST32H |                                                                                |
|              |                                                                                               | TST33H |                                                                                |
|              |                                                                                               | TST34H |                                                                                |
|              |                                                                                               | TST31L | } pressure drop from low-pressure plenum to compression spaces, MPa            |
|              |                                                                                               | TST32L |                                                                                |
|              |                                                                                               | TST33L |                                                                                |
|              |                                                                                               | TST34L |                                                                                |

|                                              |                                                                                                   |                                              |                                                                                  |
|----------------------------------------------|---------------------------------------------------------------------------------------------------|----------------------------------------------|----------------------------------------------------------------------------------|
| TT1 }<br>TT2 }<br>TT3 }<br>TT4 }             | average temperature at piston ring for each piston, K                                             | VMAT                                         | vector of changes in state variables during iteration                            |
| TWC                                          | adjusted compression-space temperature, °C                                                        | VOC                                          | compression-space dead volume, cm <sup>3</sup>                                   |
| TWCIN                                        | cooler wall temperature, °C                                                                       | VOE                                          | expansion-space dead volume, cm <sup>3</sup>                                     |
| TWH                                          | adjusted expansion-space temperature, °C                                                          | VR                                           | regenerator volume, cm <sup>3</sup>                                              |
| TWHIN                                        | heater wall temperature, °C                                                                       | VR1 }<br>VR2 }<br>VR3 }<br>VR4 }             | regenerator volumes for the four working spaces, cm <sup>3</sup>                 |
| VCC1 }<br>VCC2 }<br>VCC3 }<br>VCC4 }         | initial-condition compression-space volume for each working space, cm <sup>3</sup>                | VS                                           | state variable guess vector                                                      |
| VCOLD1 }<br>VCOLD2 }<br>VCOLD3 }<br>VCOLD4 } | compression-space volume from previous time step for pressure-volume integration, cm <sup>3</sup> | VSAVE                                        | vector of saved, converged state variables used for generating a Jacobian matrix |
| VCONV                                        | vector of converged state variables from previous time step                                       | VSH                                          | short-circuit low- and high-pressure plenum volumes, cm                          |
| VC1 }<br>VC2 }<br>VC3 }<br>VC4 }             | compression-space volume, cm <sup>3</sup>                                                         | WDSHT                                        | short-circuit flow from high-pressure plenum to low-pressure plenum, kg/sec      |
| VDELTA                                       | initial perturbation on state variables for matrix generation                                     | WD1 }<br>WD2 }                               | mass flow rates in working space 1, kg/sec                                       |
| VDENOM                                       | vector of past converged state variables used in error vector calculation                         | WD3 }<br>WD4 }                               | mass flow rates in working space 4, kg/sec                                       |
| VDOT                                         | vector of state variable derivatives at current time                                              | WD5 }<br>WD6 }                               | mass flow rates in working space 3, kg/sec                                       |
| VDOTSV                                       | vector of state variable derivatives at previous time                                             | WD7 }<br>WD8 }                               | mass flow rates in working space 2, kg/sec                                       |
| VDOTT                                        | vector of average values of state variable derivatives from present and past time steps           | WD1IN }<br>WD2IN }<br>WD3IN }<br>WD4IN }     | short-circuit mass flows from low-pressure plenum to compression spaces, kg/sec  |
| VEE1 }<br>VEE2 }<br>VEE3 }<br>VEE4 }         | initial-condition expansion-space volume for each working space, cm <sup>3</sup>                  | WD1OUT }<br>WD2OUT }<br>WD3OUT }<br>WD4OUT } | short-circuit mass flows from compression spaces to high-pressure plenum, kg/sec |
| VEOLD1 }<br>VEOLD2 }<br>VEOLD3 }<br>VEOLD4 } | expansion-space volume from previous time step for pressure-volume integration, cm <sup>3</sup>   | WLK12 }<br>WLK23 }<br>WLK34 }<br>WLK41 }     | piston ring leakage flow from working space i to j, kg/sec                       |
| VE1 }<br>VE2 }<br>VE3 }<br>VE4 }             | expansion-space volume, cm <sup>3</sup>                                                           | WSC1DT }<br>WSC2DT }<br>WSC3DT }<br>WSC4DT } | stored mass derivative in compression volume for each working space, kg/sec      |
| VGUESS                                       | state variable guess vector                                                                       | WSE1DT }<br>WSE2DT }<br>WSE3DT }<br>WSE4DT } | stored mass derivative in expansion volume for each working space, kg/sec        |
| VKPH                                         | car velocity, km/hr                                                                               | WSMNI                                        | initial stored mass in low-pressure plenum, kg                                   |
|                                              |                                                                                                   | WSMX1                                        | initial stored mass in high-pressure plenum, kg                                  |

|        |                                                                               |                                                           |                                                                                               |
|--------|-------------------------------------------------------------------------------|-----------------------------------------------------------|-----------------------------------------------------------------------------------------------|
| WSR1DT | } stored mass derivative in regenerator volume for each working space, kg/sec | XDST                                                      | slide valve opening position, cm                                                              |
| WSR2DT |                                                                               | XD1                                                       | } piston position with zero reference at midstroke, cm                                        |
| WSR3DT |                                                                               | XD2                                                       |                                                                                               |
| WSR4DT |                                                                               | XD3                                                       |                                                                                               |
| WSSCN1 | XD4                                                                           | } piston position with zero reference at top of crank, cm |                                                                                               |
| WSSCN2 | XD1P                                                                          |                                                           |                                                                                               |
| WSSCN3 | XD2P                                                                          |                                                           |                                                                                               |
| WSSCN4 | XD3P                                                                          |                                                           |                                                                                               |
| WSS11  | } stored mass supply flow into each working space, kg/sec                     | XD4P                                                      |                                                                                               |
| WSS22  |                                                                               | XD30                                                      | initial position of piston 3, cm                                                              |
| WSS33  |                                                                               | XD3PRV                                                    | position of piston 3 at previous time step, cm                                                |
| WSS44  |                                                                               |                                                           |                                                                                               |
| WSTMN  | stored mass in low-pressure plenum, kg                                        | XXX                                                       | summation of squares of changes in errors to maximum error                                    |
| WSTMND | stored mass derivative in low-pressure plenum, kg/sec                         | Y                                                         | present abscissa value for trapezoidal integration                                            |
| WSTMX  | stored mass in high-pressure plenum, kg                                       | YOLD                                                      | past abscissa value for trapezoidal integration                                               |
| WSTMXD | stored mass derivative in high-pressure plenum, kg/sec                        | YSCALE                                                    | stored mass scalar                                                                            |
| WSTOTL | total stored mass in engine, kg                                               | YYY                                                       | scalar vector for changes in state                                                            |
| WSWANT | initial stored mass in each working space, kg                                 | YYYX                                                      | summation of squares of changes in errors to maximum error for debug output                   |
| WTCAR  | mass of car, kg                                                               |                                                           |                                                                                               |
| WTENG  | mass of engine, kg                                                            | Z                                                         | present ordinate value for trapezoidal integration                                            |
| WTOT   | total stored mass in engine during integration, kg                            | ZEROBS                                                    | position bias to change zero reference of piston position from top crank to center stroke, cm |
| WTWHEL | mass of wheels, kg                                                            | ZMAT                                                      | Jacobian matrix for 12th-order system                                                         |
| WT1    | } stored mass in each working space during integration, kg                    | ZOLD                                                      | past ordinate value for trapezoidal integration                                               |
| WT2    |                                                                               |                                                           |                                                                                               |
| WT3    |                                                                               |                                                           |                                                                                               |
| WT4    |                                                                               |                                                           |                                                                                               |

## **Appendix B**

### **Analytical Model**

The dynamic equations used to model the four-cylinder controls model were simplified from those used to represent the single-working-space model. Both sets of equations are given in reference 2. For completeness, the equations of the four-cylinder model are presented here. All equations are in FORTRAN.

#### **Dynamic Equations**

A schematic of the four-cylinder controls model is given in figure 1. The pistons are numbered in the order in which they reach top stroke as indicated by the arrows in the piston heads. The dynamic equations are

$$WSE1DT = -WD1 - WLK12$$

$$WSR1DT = WD1 - WD2$$

$$WSC1DT = WD2 + WLK41 + WSS11 + WSSCN1 + WD1IN - WD1OUT$$

$$WSE2DT = -WD7 - WLK23$$

$$WSR2DT = WD7 - WD8$$

$$WSC2DT = WD8 + WLK12 + WSS22 + WSSCN2 + WD2IN - WD2OUT$$

$$WSE3DT = -WD5 - WLK34$$

$$WSR3DT = WD5 - WD6$$

$$WSC3DT = WD6 + WLK23 + WSS33 + WSSCN3 + WD3IN - WD3OUT$$

$$WSE4DT = -WD3 - WLK41$$

$$WSR4DT = WD3 - WD4$$

$$WSC4DT = WD4 + WLK34 + WSS44 + WSSCN4 + WD4IN - WD4OUT$$

The first-order approximations to the momentum equations are

$$WD1 = (PE1 - PR1)/RER$$

$$WD2 = (PR1 - PC1)/RRC$$

$$WD3 = (PE4 - PR4)/RER$$

$$WD4 = (PR4 - PC4)/RRC$$

$$WD5 = (PE3 - PR3)/RER$$

$$WD6 = (PR3 - PC3)/RRC$$

$$WD7 = (PE2 - PR2)/RER$$

$$WD8 = (PR2 - PC2)/RRC$$

### **Pressure**

Pressures are given by the ideal-gas law:

$$PE1 = (TE1 * R * WSE1) / VE1$$

$$PR1 = (TR1 * R * WSR1) / VR1$$

$$PC1 = (TC1 * R * WSC1) / VC1$$

$$PE2 = (TE2 * R * WSE2) / VE2$$

$$PR2 = (TR2 * R * WSR2) / VR2$$

$$PC2 = (TC2 * R * WSC2) / VC2$$

$$PE3 = (TE3 * R * WSE3) / VE3$$

$$PR3 = (TR3 * R * WSR3) / VR3$$

$$PC3 = (TC3 * R * WSC3) / VC3$$

$$PE4 = (TE4 * R * WSE4) / VE4$$

$$PR4 = (TR4 * R * WSR4) / VR4$$

$$PC4 = (TC4 * R * WSC4) / VC4$$

### **Temperatures**

Temperatures are set as a weak function of speed. The temperature functions in the expansion and compression spaces are derived from steady-state data from the single-working-space model results (ref. 2). The speed ratio is

$$RATTT = (SPDMAX - FREQRP) / 1000.0$$

and the temperatures in the volumes are given by

$$TE1 = TWH + RATTT * 5.555 - 55.55$$

$$TE2 = TWH + RATT*5.555 - 55.55$$

$$TE3 = TWH + RATT*5.555 - 55.55$$

$$TE4 = TWH + RATT*5.555 - 55.55$$

$$TC1 = TWC - RATT*3.888 + 55.55$$

$$TC2 = TWC - RATT*3.888 + 55.55$$

$$TC3 = TWC - RATT*3.888 + 55.55$$

$$TC4 = TWC - RATT*3.888 + 55.55$$

$$TR1 = (TE1 + TC1)/2.0$$

$$TR2 = (TE2 + TC2)/2.0$$

$$TR3 = (TE3 + TC3)/2.0$$

$$TR4 = (TE4 + TC4)/2.0$$

### Volumes

Variable volumes are a function of piston position:

$$VE1 = VOE + (STROKE/2.0 - XD1)*AD$$

$$VC1 = VOC + (STROKE/2.0 + XD4)*(AD - AR)$$

$$VE2 = VOE + (STROKE/2.0 - XD2)*AD$$

$$VC2 = VOC + (STROKE/2.0 + XD1)*(AD - AR)$$

$$VE3 = VOE + (STROKE/2.0 - XD3)*AD$$

$$VC3 = VOC + (STROKE/2.0 + XD2)*(AD - AR)$$

$$VE4 = VOE + (STROKE/2.0 - XD4)*AD$$

$$VC4 = VOC + (STROKE/2.0 + XD3)*(AD - AR)$$

The regenerator volumes are fixed:

$$VR1 = VR$$

$$VR2 = VR$$

$$VR3 = VR$$

$$VR4 = VR$$

### **Piston Positions**

Piston positions are calculated from the drive geometry and the crank angle:

$$\begin{aligned} XD1 &= (STROKE/2.0)*COS(PSI) \\ &+ SQRT(RODL**2 - (STROKE/2.0)**2*(SIN(PSI))**2) \\ &- SQRT(RODL**2 - (STROKE/2.0)**2) - ZEROBS \end{aligned}$$

$$\begin{aligned} XD2 &= (STROKE/2.0)*COS(PSI - PIE/2.0) \\ &+ SQRT(RODL**2 - (STROKE/2.0)**2*(SIN(PSI - PIE/2.0))**2) \\ &- SQRT(RODL**2 - (STROKE/2.0)**2) - ZEROBS \end{aligned}$$

$$\begin{aligned} XD3 &= (STROKE/2.0)*COS(PSI - PIE) \\ &+ SQRT(RODL**2 - (STROKE/2.0)**2*(SIN(PSI - PIE))**2) \\ &- SQRT(RODL**2 - (STROKE/2.0)**2) - ZEROBS \end{aligned}$$

$$\begin{aligned} XD4 &= (STROKE/2.0)*COS(PSI - 3.*PIE/2.) \\ &+ SQRT(RODL**2 - (STROKE/2.0)**2*(SIN(PSI - 3.*PIE/2.))**2) \\ &- SQRT(RODL**2 - (STROKE/2.0)**2) - ZEROBS \end{aligned}$$

where ZEROBS is a small bias to center the piston stroke around zero reference rather than at the top of the crank.

### **Torque**

Torque is calculated from piston areas, cycle pressures, and drive geometry. The forces on the pistons are

$$FORC1 = PE1*AD - PC2*(AD - AR)$$

$$FORC2 = PE2*AD - PC3*(AD - AR)$$

$$FORC3 = PE3*AD - PC4*(AD - AR)$$

$$FORC4 = PE4*AD - PC1*(AD - AR)$$

The torques generated by each piston are



$$\text{TORQ1} = (\text{STROKE}/2.0) * \text{FORC1} * \text{SIN}(\text{PSI}) * (1.0 + \text{COS}(\text{PSI}))$$

$$/ \sqrt{(\text{RODL})^2 - (\text{STROKE}/2.0)^2 * (\text{SIN}(\text{PSI}))^2}$$

$$\text{TORQ2} = (\text{STROKE}/2.0) * \text{FORC2} * \text{SIN}(\text{PSI} - \text{PIE}/2.0) * (1.0 + \text{COS}(\text{PSI} - \text{PIE}/2.0))$$

$$/ \sqrt{(\text{RODL})^2 - (\text{STROKE}/2.0)^2 * (\text{SIN}(\text{PSI} - \text{PIE}/2.0))^2}$$

$$\text{TORQ3} = (\text{STROKE}/2.0) * \text{FORC3} * \text{SIN}(\text{PSI} - \text{PIE}) * (1.0 + \text{COS}(\text{PSI} - \text{PIE}))$$

$$/ \sqrt{(\text{RODL})^2 - (\text{STROKE}/2.0)^2 * (\text{SIN}(\text{PSI} - \text{PIE}))^2}$$

$$\text{TORQ4} = (\text{STROKE}/2.0) * \text{FORC4} * \text{SIN}(\text{PSI} - 3. * \text{PIE}/2.) * (1. + \text{COS}(\text{PSI} - 3. * \text{PIE}/2.))$$

$$/ \sqrt{(\text{RODL})^2 - (\text{STROKE}/2.0)^2 * (\text{SIN}(\text{PSI} - 3. * \text{PIE}/2.))^2}$$

where total torque is

$$\text{TORQT} = \text{TORQ1} + \text{TORQ2} + \text{TORQ3} + \text{TORQ4}$$

#### Losses

Vehicle load effects, engine auxiliary power loss, and mechanical friction are calculated from

$$\text{PAUX} = 1.57667\text{E} - 10 * \text{FREQR}^3 - 4.3\text{E} - 7 * \text{FREQR}^2 + 8.9331\text{E}$$

$$- 4 * \text{FREQR} - + .78002$$

$$\text{PFRICT} = 12.8/20.0 * (\text{FREQR}/\text{SPDMAX}) * (\text{PCCBAR} + 5.0)$$

where

$$\text{PCCBAR} = .462 * \text{PCCMAX} + .538 * \text{PCCMIN}$$

and PCCMAX and PCCMIN are the average maximum and minimum compression-space pressures for each of the four working spaces.

Rolling resistance and air drag are considered as part of the vehicle load. For rolling resistance it is assumed that there is a 4.51-hp loss at 50 mph; thus

$$\text{PRRF} = (4.51 * .7457 / (73.333 * 30.48)) * \text{GRAT} * \text{RWHEEL} * \text{PSIDT}$$

where

$$\text{GRAT} = \text{GTRAN} * (1.0/\text{GR})$$

The force due to air drag is

$$\text{FDRAG} = .010353 * 4.448 * (\text{RWHEEL} * \text{GRAT} * \text{PSIDT})^2 / (30.48)^2$$

The power loss is

$$PDRAG = FDRAG * RWHEEL * GRAT * PSIDT / 100000.0$$

The associated torque losses are

$$TFRICT = 33000.0 * 1.356 * PFRICT / (2.0 * PIE * .7457 * FREQRP)$$

$$TAUX = 33000.0 * 1.356 * PAUX / (2.0 * PIE * .7457 * FREQRP)$$

$$TRRF = 4.51 * 550.0 * 1.356 * RWHEEL / (73.333 * 30.48) * GRAT$$

$$TDRAG = FDRAG * RWHEEL * GRAT / 100.0$$

The vehicle speed is

$$VKPH = (3600.0 * RWHEEL * GRAT * PSIDT) / 100000.0$$

The net torque is

$$TNET = TORQT - TRRF - TDRAG - TFRICT - TAUX$$

From the net torque when the drive dynamics are integrated, the equation of motion is

$$AINERT * PSIDDT = TNET$$

### Supply Flow

Supply flow into each working space is calculated as a function of differential pressure between the compression spaces and the supply. Flow is let in by a timing slot in the piston rod. When the rod is near bottom stroke, the slot allows flow into the compression space. A schematic of the system is shown in figure 7. The supply check valves function such that

$$WSS11 = \begin{cases} (PSOURC - PC1) * ADS1 / RSUP & \text{for } PC1 \leq PSOURC \\ 0.0 & \text{for } PC1 > PSOURC \end{cases}$$

$$WSS22 = \begin{cases} (PSOURC - PC2) * ADS2 / RSUP & \text{for } PC2 \leq PSOURC \\ 0.0 & \text{for } PC2 > PSOURC \end{cases}$$

$$WSS33 = \begin{cases} (PSOURC - PC3) * ADS3 / RSUP & \text{for } PC3 \leq PSOURC \\ 0.0 & \text{for } PC3 > PSOURC \end{cases}$$

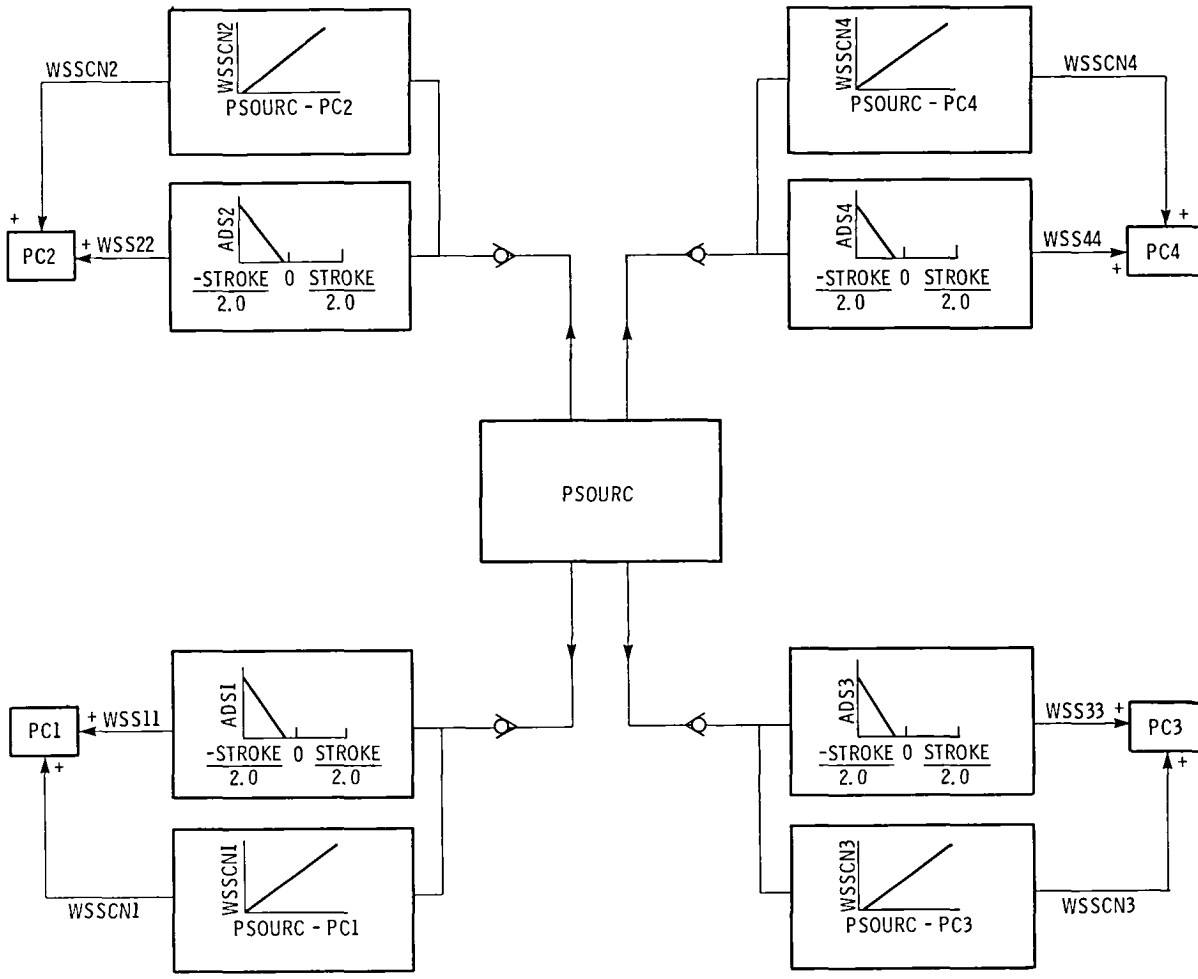


Figure 7. - Supply system.

$$WSS44 = \begin{cases} (PSOURC - PC4) * ADS4 / RSUP & \text{for } PC4 \leq PSOURC \\ 0.0 & \text{for } PC4 > PSOURC \end{cases}$$

where

$$ADS1 = \begin{cases} 1.0 - (XD4 + (STROKE/2.0)) / (RATOO * STROKE) & \text{for } XD4 \leq -STROKE * (.5 - RATOO) \\ 0.0 & \text{for } XD4 > -STROKE * (.5 - RATOO) \end{cases}$$

$$ADS2 = \begin{cases} 1.0 - (XD1 + (STROKE/2.0)) / (RATOO * STROKE) & \text{for } XD1 \leq -STROKE * (.5 - RATOO) \\ 0.0 & \text{for } XD1 > -STROKE * (.5 - RATOO) \end{cases}$$

$$\text{ADS3} = \begin{cases} 1.0 - (\text{XD2} + (\text{STROKE}/2.0))/(\text{RATOO} * \text{STROKE}) & \text{for } \text{XD2} \leq -\text{STROKE} * (.5 - \text{RATOO}) \\ 0.0 & \text{for } \text{XD2} > -\text{STROKE} * (.5 - \text{RATOO}) \end{cases}$$

$$\text{ADS4} = \begin{cases} 1.0 - (\text{XD3} + (\text{STROKE}/2.0))/(\text{RATOO} * \text{STROKE}) & \text{for } \text{XD3} \leq -\text{STROKE} * (.5 - \text{RATOO}) \\ 0.0 & \text{for } \text{XD3} > -\text{STROKE} * (.5 - \text{RATOO}) \end{cases}$$

Rod leakage flow is also modeled. A schematic of the flow is shown in figure 8.

$$\text{WSSCN1} = \begin{cases} \text{ARLEAK} * (\text{PSOURC} - \text{PC1}) / \text{RSUP} & \text{for } \text{PC1} \leq \text{PSOURC} \\ 0.0 & \text{for } \text{PC1} > \text{PSOURC} \end{cases}$$

$$\text{WSSCN2} = \begin{cases} \text{ARLEAK} * (\text{PSOURC} - \text{PC2}) / \text{RSUP} & \text{for } \text{PC2} \leq \text{PSOURC} \\ 0.0 & \text{for } \text{PC2} > \text{PSOURC} \end{cases}$$

$$\text{WSSCN3} = \begin{cases} \text{ARLEAK} * (\text{PSOURC} - \text{PC3}) / \text{RSUP} & \text{for } \text{PC3} \leq \text{PSOURC} \\ 0.0 & \text{for } \text{PC3} > \text{PSOURC} \end{cases}$$

$$\text{WSSCN4} = \begin{cases} \text{ARLEAK} * (\text{PSOURC} - \text{PC4}) / \text{RSUP} & \text{for } \text{PC4} \leq \text{PSOURC} \\ 0.0 & \text{for } \text{PC4} > \text{PSOURC} \end{cases}$$

### Piston Rod Leakage

An orifice equation is used to model piston ring leakage:

$$\text{WLK12} = .9 * \text{AO} * \text{ALEAK} * \text{SQRT}(2.0 * \text{G} * \text{PP1} / (\text{R} * \text{TT1})) * \text{SQRT}(\text{ABS}(\text{TEST1})) * \text{DIR1}$$

$$\text{WLK23} = .9 * \text{AO} * \text{ALEAK} * \text{SQRT}(2.0 * \text{G} * \text{PP2} / (\text{R} * \text{TT2})) * \text{SQRT}(\text{ABS}(\text{TEST4})) * \text{DIR4}$$

$$\text{WLK34} = .9 * \text{AO} * \text{ALEAK} * \text{SQRT}(2.0 * \text{G} * \text{PP3} / (\text{R} * \text{TT3})) * \text{SQRT}(\text{ABS}(\text{TEST3})) * \text{DIR3}$$

$$\text{WLK41} = .9 * \text{AO} * \text{ALEAK} * \text{SQRT}(2.0 * \text{G} * \text{PP4} / (\text{R} * \text{TT4})) * \text{SQRT}(\text{ABS}(\text{TEST2})) * \text{DIR2}$$

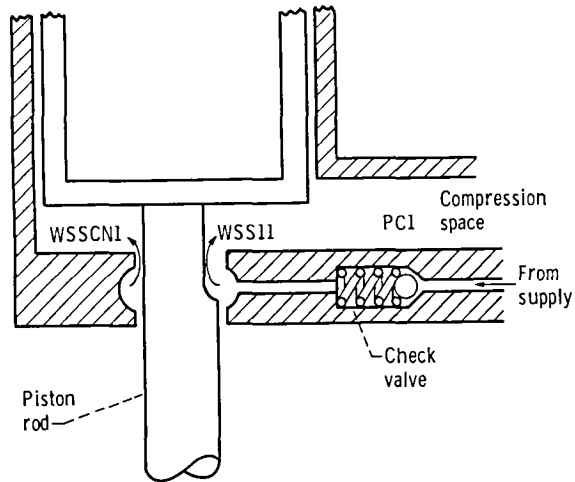


Figure 8. - Piston rod slot valve.

where

$$AO = \text{PIE}/4.0 * (\text{DIAM}^{**2} - (\text{DIAM} - .0001)^{**2})$$

and

$$\text{DIAM} = \text{SQRT}(4.0 * \text{AD} / \text{PIE})$$

Also

$$\text{TEST1} = \text{PE1} - \text{PC2}$$

$$\text{TEST2} = \text{PE4} - \text{PC1}$$

$$\text{TEST3} = \text{PE3} - \text{PC4}$$

$$\text{TEST4} = \text{PE2} - \text{PC3}$$

$$\text{PP1} = (\text{PE1} + \text{PC2}) / 2.0$$

$$\text{PP2} = (\text{PE4} + \text{PC1}) / 2.0$$

$$\text{PP3} = (\text{PE3} + \text{PC4}) / 2.0$$

$$\text{PP4} = (\text{PE2} + \text{PC3}) / 2.0$$

$$\text{TT1} = (\text{TE1} + \text{TC2}) / 2.0$$

$$\text{TT2} = (\text{TE4} + \text{TC1}) / 2.0$$

$$\text{TT3} = (\text{TE3} + \text{TC4}) / 2.0$$

$$TT4 = (TE2 + TC3)/2.0$$

DIR determines the flow direction:

$$DIR1 = \begin{cases} 1.0 & \text{for TEST1} \geq 0.0 \\ -1.0 & \text{for TEST1} < 0.0 \end{cases}$$

$$DIR2 = \begin{cases} 1.0 & \text{for TEST2} \geq 0.0 \\ -1.0 & \text{for TEST2} < 0.0 \end{cases}$$

$$DIR3 = \begin{cases} 1.0 & \text{for TEST3} \geq 0.0 \\ -1.0 & \text{for TEST3} < 0.0 \end{cases}$$

$$DIR4 = \begin{cases} 1.0 & \text{for TEST4} \geq 0.0 \\ -1.0 & \text{for TEST4} < 0.0 \end{cases}$$

### Short Circuiting

A schematic of a short-circuit system is shown in figure 9. The high- and low-pressure plenums are modeled by constant-temperature volumes. The gas temperature is assumed to be that of the compression space. For the check valves

$$TST31H = PC1 - PSHTMX$$

$$TST32H = PC2 - PSHTMX$$

$$TST33H = PC3 - PSHTMX$$

$$TST34H = PC4 - PSHTMX$$

$$TST31L = PSHTMN - PC1$$

$$TST32L = PSHTMN - PC2$$

$$TST33L = PSHTMN - PC3$$

$$TST34L = PSHTMN - PC4$$

The flows are

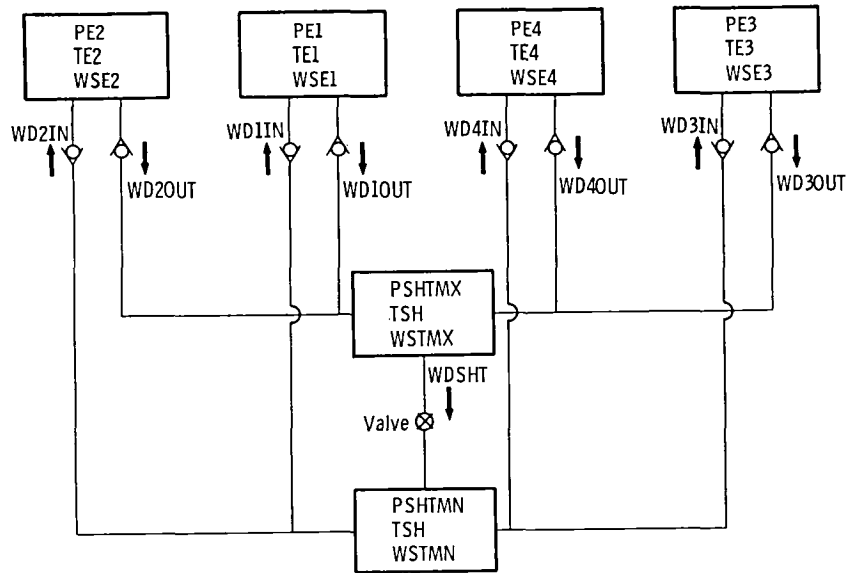


Figure 9. - Short-circuit system.

$$WD1IN = \begin{cases} TST31L/RSHT & \text{for } TST31L \geq 0.0 \\ 0.0 & \text{for } TST31L < 0.0 \end{cases}$$

$$WD2IN = \begin{cases} TST32L/RSHT & \text{for } TST32L \geq 0.0 \\ 0.0 & \text{for } TST32L < 0.0 \end{cases}$$

$$WD3IN = \begin{cases} TST33L/RSHT & \text{for } TST33L \geq 0.0 \\ 0.0 & \text{for } TST33L < 0.0 \end{cases}$$

$$WD4IN = \begin{cases} TST34L/RSHT & \text{for } TST34L \geq 0.0 \\ 0.0 & \text{for } TST34L \leq 0.0 \end{cases}$$

$$WD1OUT = \begin{cases} TST31H/RSHT & \text{for } TST31H > 0.0 \\ 0.0 & \text{for } TST31H < 0.0 \end{cases}$$

$$WD2OUT = \begin{cases} TST32H/RSHT & \text{for } TST32H \geq 0.0 \\ 0.0 & \text{for } TST32H \geq 0.0 \end{cases}$$

$$WD3OUT = \begin{cases} TST33H/RSHT & \text{for } TST33H \geq 0.0 \\ 0.0 & \text{for } TST33H < 0.0 \end{cases}$$

$$WD4OUT = \begin{cases} TST34H/RSHT & \text{for } TST34H \geq 0.0 \\ 0.0 & \text{for } TST34H < 0.0 \end{cases}$$

The short-circuit valve flow is

$$WDSHT = (PSHTMX - PSHTMN) * ASHTT / RSHTCT$$

where

$$PSHTMX = WSTMX * R * TSH / VSH$$

$$PSHTMN = WSTMN * R * TSH / VSH$$

The dynamic equations are

$$WSTMXD = WD1OUT + WD2OUT + WD3OUT + WD4OUT - WDSHT$$

$$WSTMND = -WD1IN - WD2IN - WD3IN - WD4IN + WDSHT$$



## Appendix C

### Flow Charts

This appendix contains flow charts for the main program and all the subroutines in the simulation. Most flow charts should be easy to follow, with the possible exception of that for subroutine FOURW2. FOURW2 performs both the incrementing of time and the integration of the state equations. The integration scheme is implicit. It is a backward-difference integration that uses a multivariable Newton-Raphson iteration for convergence at a time point. The reason for using this type of integration is that it is stable for both large and small step sizes. This is important when there is a large spread in eigenvalues for the system being simulated. Although only pressure-flow dynamics are being simulated, the addition of temperature dynamics may be desirable (ref. 2). This would add slow dynamics to the simulation. In that event, the implicit integration scheme will be available to handle the widespread dynamics while insuring stability.

To help in understanding how subroutine FOURW2 works, the following description is provided. Statement numbers corresponding to the FORTRAN listing are given in the flow chart.

#### Integration Scheme

The integration scheme is a backward-difference method that uses a multivariable Newton-Raphson iteration scheme for convergence. State variables are updated by using the old state vector  $\mathbf{VS}_{old}$ , the current error vector  $\mathbf{E}$ , and the inverse of a Jacobian matrix  $\mathbf{EMAT}$  (ref. 5).

$$\mathbf{VS}_{new} = -\mathbf{EMAT}^{-1} \times \mathbf{E} + \mathbf{VS}_{old} \quad (C1)$$

$\mathbf{EMAT}$  is a Jacobian matrix of partial derivatives (i.e., changes in error variables with respect to changes in state variables):

$$\mathbf{EMAT}(I,J) = (\mathbf{E}(J) - \mathbf{ERRBSE}(J)) / \mathbf{DELTA V}(I) \quad (C2)$$

Updating takes place when the errors are converged within tolerance. With this technique, both steady-state and transient solutions can be obtained by changing the error variables. In steady state, all states are at rest; thus

$$\mathbf{VDOT} = \mathbf{0.0} = \mathbf{E} \quad (C3)$$

For a transient case

$$\mathbf{VDOT} \times \mathbf{DELTA} - (\mathbf{VS}_{new} - \mathbf{VS}_{old}) = \mathbf{E} \quad (C4)$$

Equations (C3) and (C4) are converged when all the elements of  $\mathbf{E}$  are within a specified tolerance.

To use this method, a Jacobian matrix must be calculated (usually by finite differences) and then inverted. This is usually very time consuming. Therefore the logic in FOURW2 allows for calculation of a new matrix only under adverse conditions such as when the rate of convergence of the simulation is getting too slow (PCNCHG less than TOLPCG), or when the number of allowable passes (MPAS) has been exceeded.

#### Perturbation Calculation

There are several features in FOURW2 that help the implicit integration scheme converge. Of primary importance is the generation of a "good" Jacobian matrix. All the partial derivatives must be representative of the linear behavior of the system at a given operating point. Since finite differences are used, the sizes of the perturbations of the states are important. If they are too large, errors will be introduced by the system nonlinearities. If they are too small, the partials will be in error because of numerical problems (without double-precision arithmetic). Thus a tuning mechanism has been included in FOURW2 to optimize the sizes of the perturbations. First, the sum of squares of all the changes in the errors is calculated for each perturbation. Once this is done, the "goodness" of the partial is checked by calculating for each state variable

$$\mathbf{XXX} = \frac{1}{N} \sqrt{\sum_{i=1}^N [(\mathbf{E}(I) - \mathbf{ERRBSE}(I))]^2} \quad (C5)$$

and then checking if

$$\mathbf{TOL1} \leq \mathbf{XXX} \leq \mathbf{TOL2} \quad (C6)$$

If all  $\mathbf{XXX}$ 's fall within the tolerance band, the matrix is considered "good". For this simulation,  $\mathbf{TOL1} = 0.001$  and  $\mathbf{TOL2} = 0.01$ . Since all the errors are scaled, this tolerance band lies between 0.1 and 1 percent. For a more linear system the band could be larger; for a more nonlinear system, smaller.

#### Scaling of Perturbations

In general, for the initial perturbations at a point, the  $\mathbf{XXX}$ 's will not fall within the tolerance band described above. Thus, FOURW2 scales the perturbations to try to

force the XXX's within the band. This is done by calculating

$$YYY = REF/XXX \quad (C7)$$

for each state variable. REF is defined as being in the center of the tolerance band:

$$REF = (TOL1 + TOL2)/2.0 \quad (C8)$$

Once a set of YYY's has been calculated such that the XXX's fall within the band, the set of YYY's is stored. After this has been done for all N states, the scaling vector YYY is generated. When a new matrix is needed, the scaling vector YYY is applied to the current states to determine first guesses for the perturbations needed to obtain new partial derivatives. If for any state variable the new XXX falls outside the tolerance band, YYY is updated and the new result stored. This method generally reduces the number of passes required for subsequent matrix generation.

### Error Messages

In generating a partial derivative a situation may arise where XXX never gets within tolerance. When this happens, the program prints out an error message "CHECK INPUT - BAD PARTIAL DERIVATIVE," prints out a debug output to help the user diagnose the problem, and then stops the simulation. This is the only time when the simulation is stopped except for the normal exit when ITRAN has been incremented to its maximum value (ITRMAX). In general, this problem will occur when coding is added to the simulation that is not consistent throughout the simulation. One example would be calculating a piston ring leakage flow from one working space but neglecting to add it to the adjacent working space.

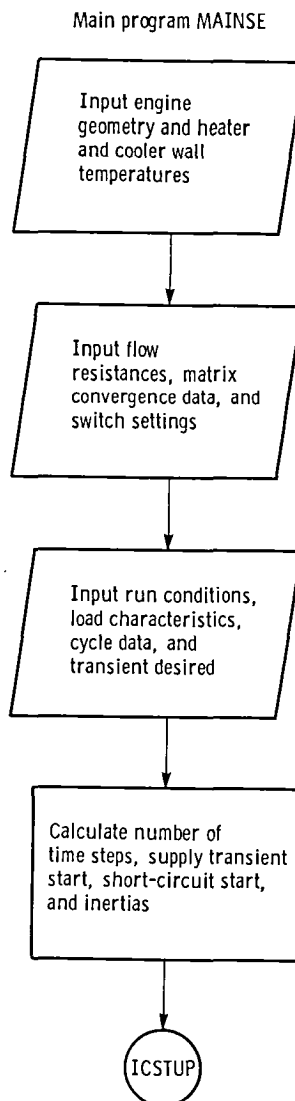
### Broyden Update Algorithm

As stated earlier, it is time consuming to calculate a Jacobian matrix and even more time consuming to invert the matrix for a large system. Usually double precision is required (as in DMINV). Lack of speed in the inverse algorithm can be prohibitive, especially in a controls model, where long transients are usually needed to evaluate controls schemes. One possible means of avoiding this problem is to generate the inverse and then to update it continually with information gained as the inverse is used. This method is the Broyden update algorithm (ref. 6) and is found in subroutine BROYF1.

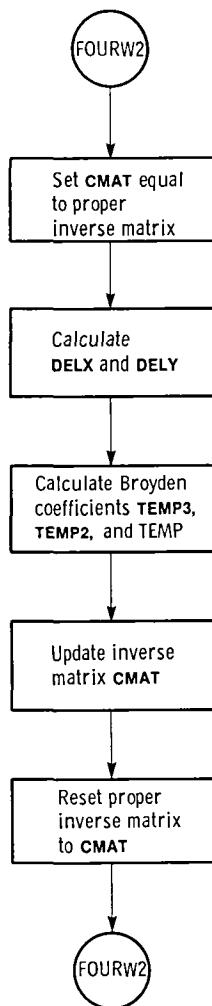
However, it should be noted that using the method is also time consuming and, for low-order systems, may not

help much in reducing the computation time for the simulation even when using large time steps. Table XIX contains the matrix update strategy for the simulation. If the Broyden algorithm is not used, a new Jacobian is generated only when the convergence rate (PCNCHG) falls below 0.5. At values of PCNCHG above 0.5 the original inverse is used. When using the Broyden algorithm a new Jacobian matrix is calculated only when TOLPCG falls below 0.0 or when the algorithm has been called more than twice the order of the system plus one ( $2*N + 1$ ) times. Since it is time consuming to use the algorithm, the inverse is updated only when PCNCHG falls below 0.7. Above PCNCHG equal to 0.7 the inverse is not updated.

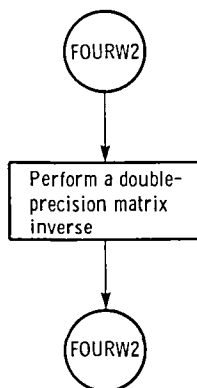
Even though the algorithm does not shorten computer time in the current simulation, it has been included in the program. If the energy equation is added to the volume dynamics or if a control system is added such that the number of states in the simulation increases significantly, the algorithm will prove much more useful.



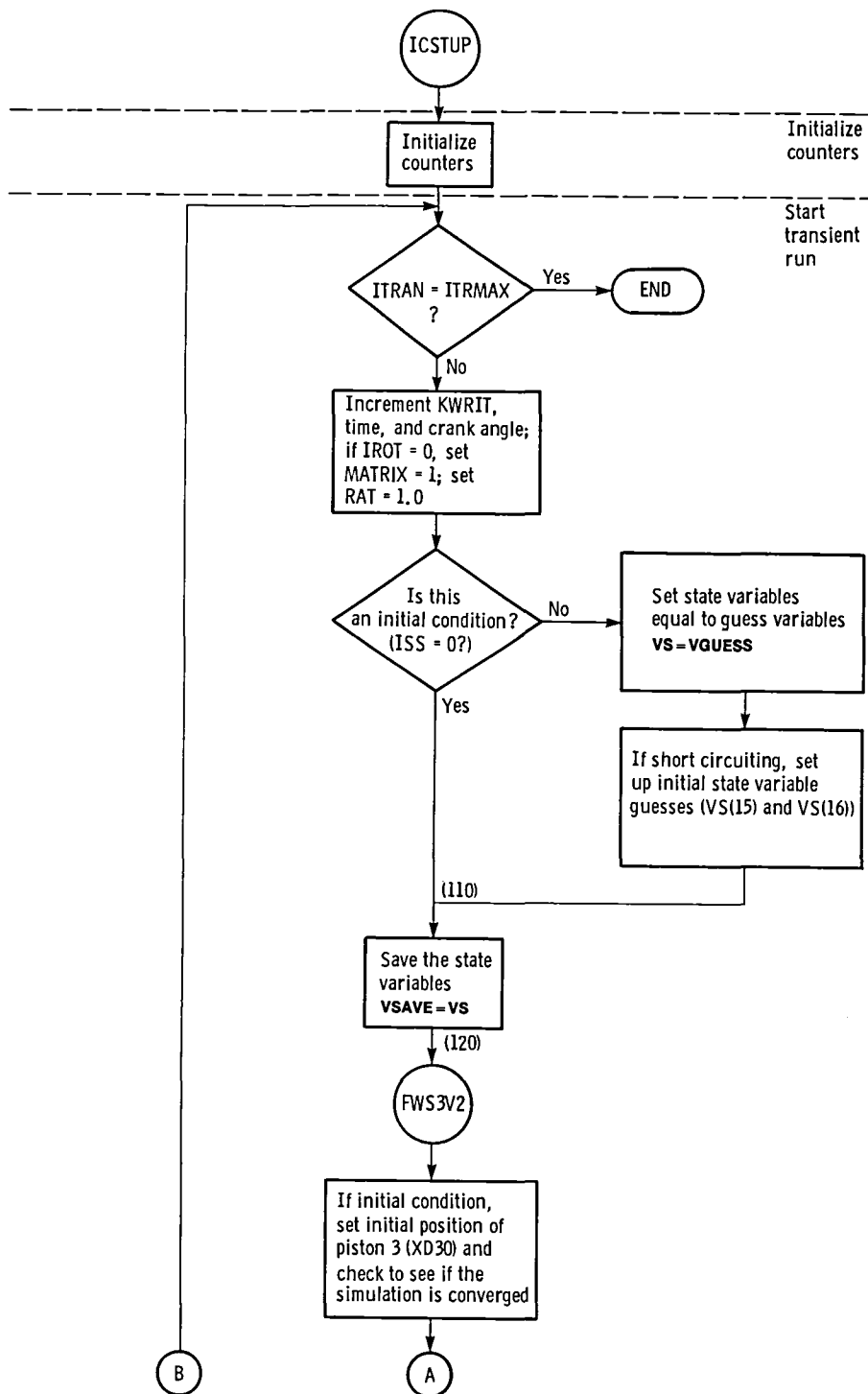
Subroutine BROYF1

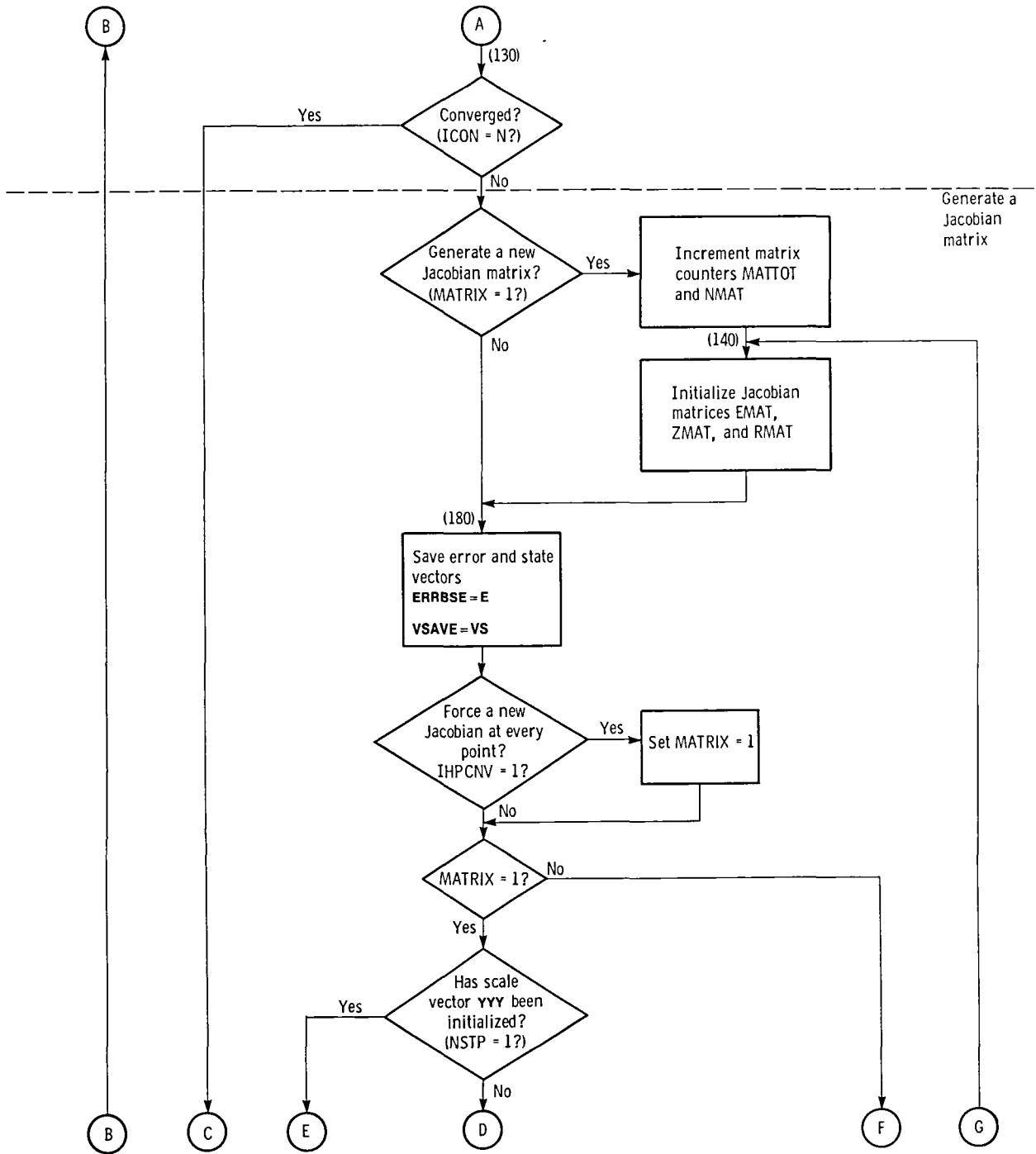


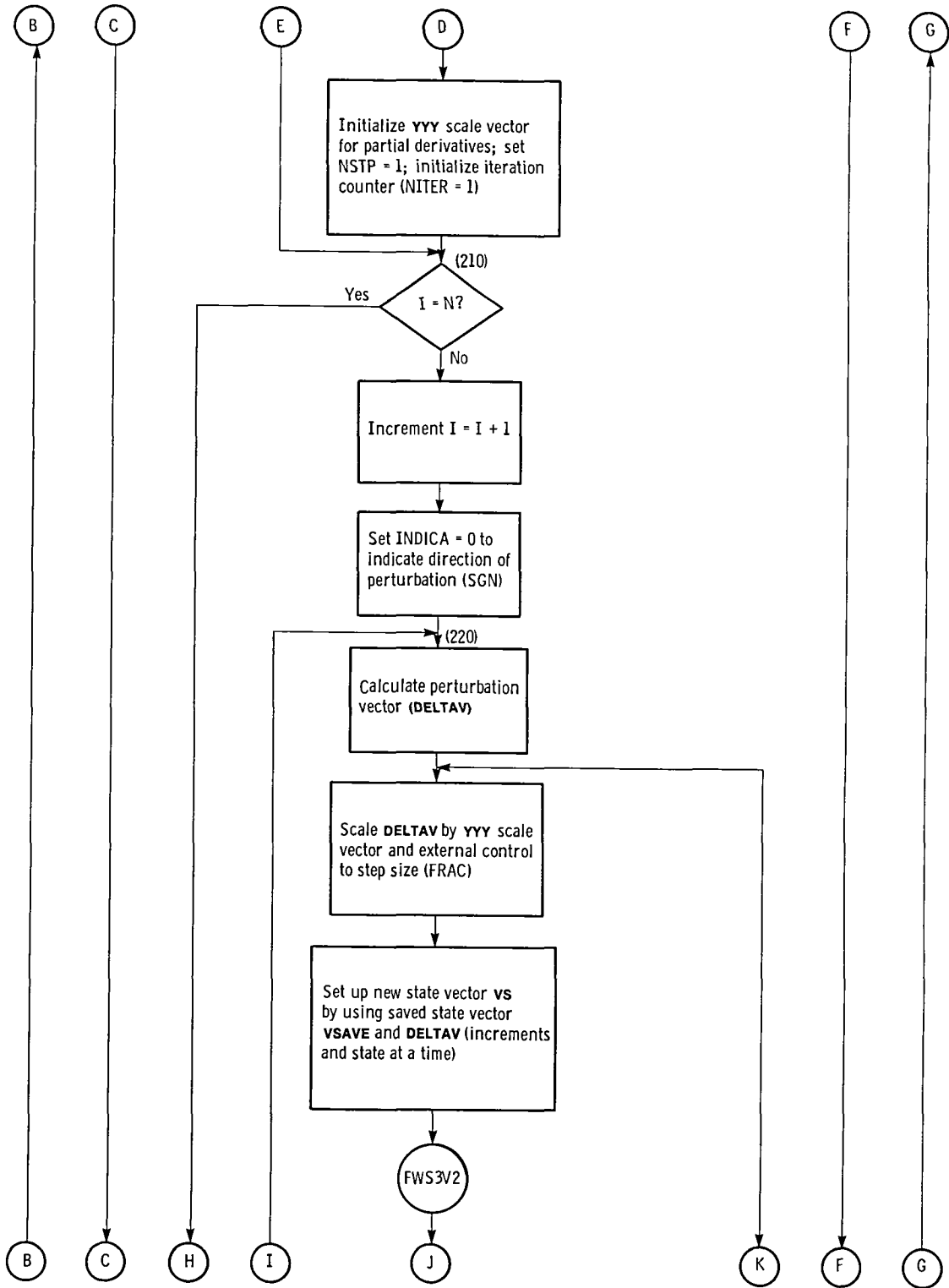
Subroutine DMINV

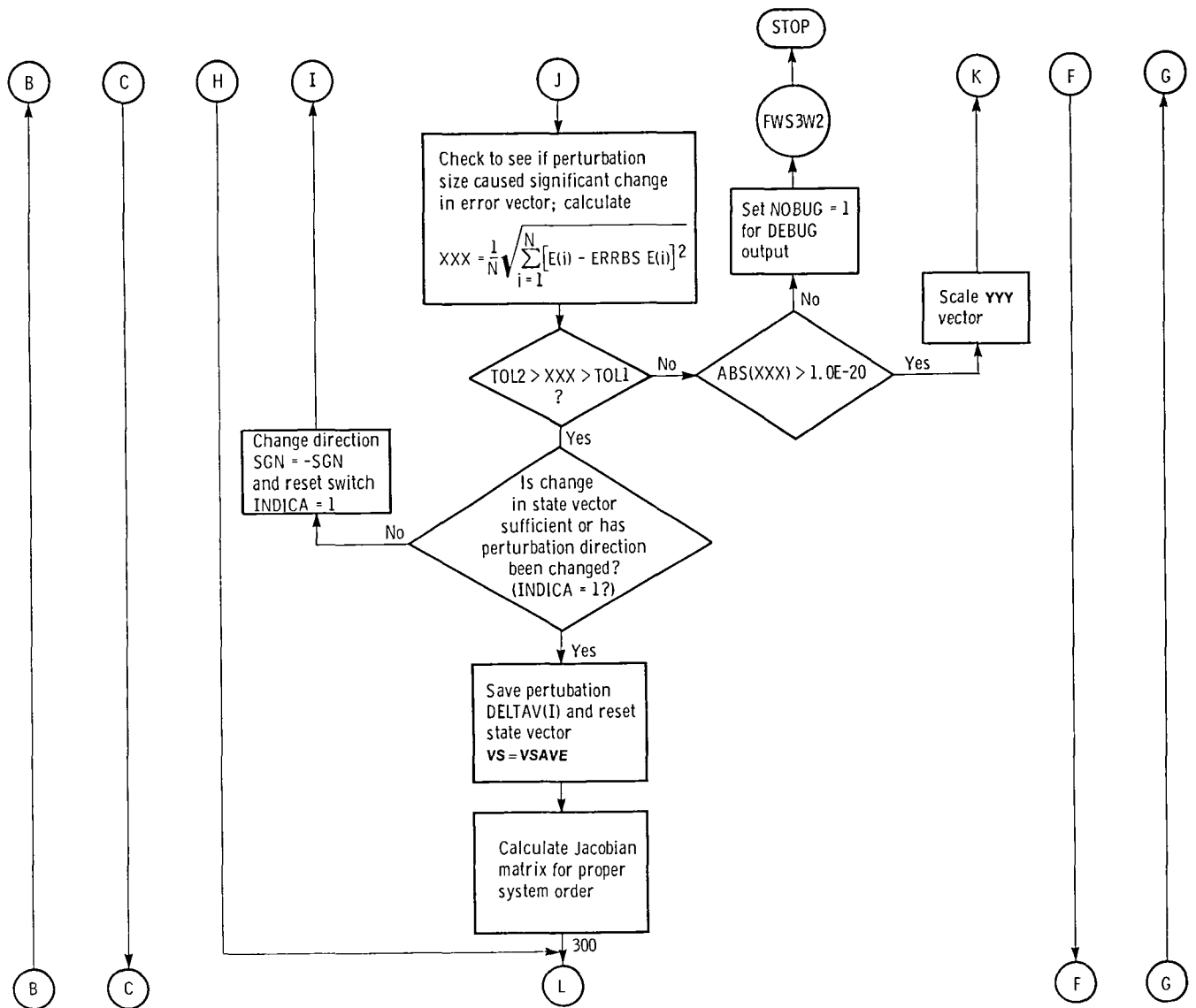


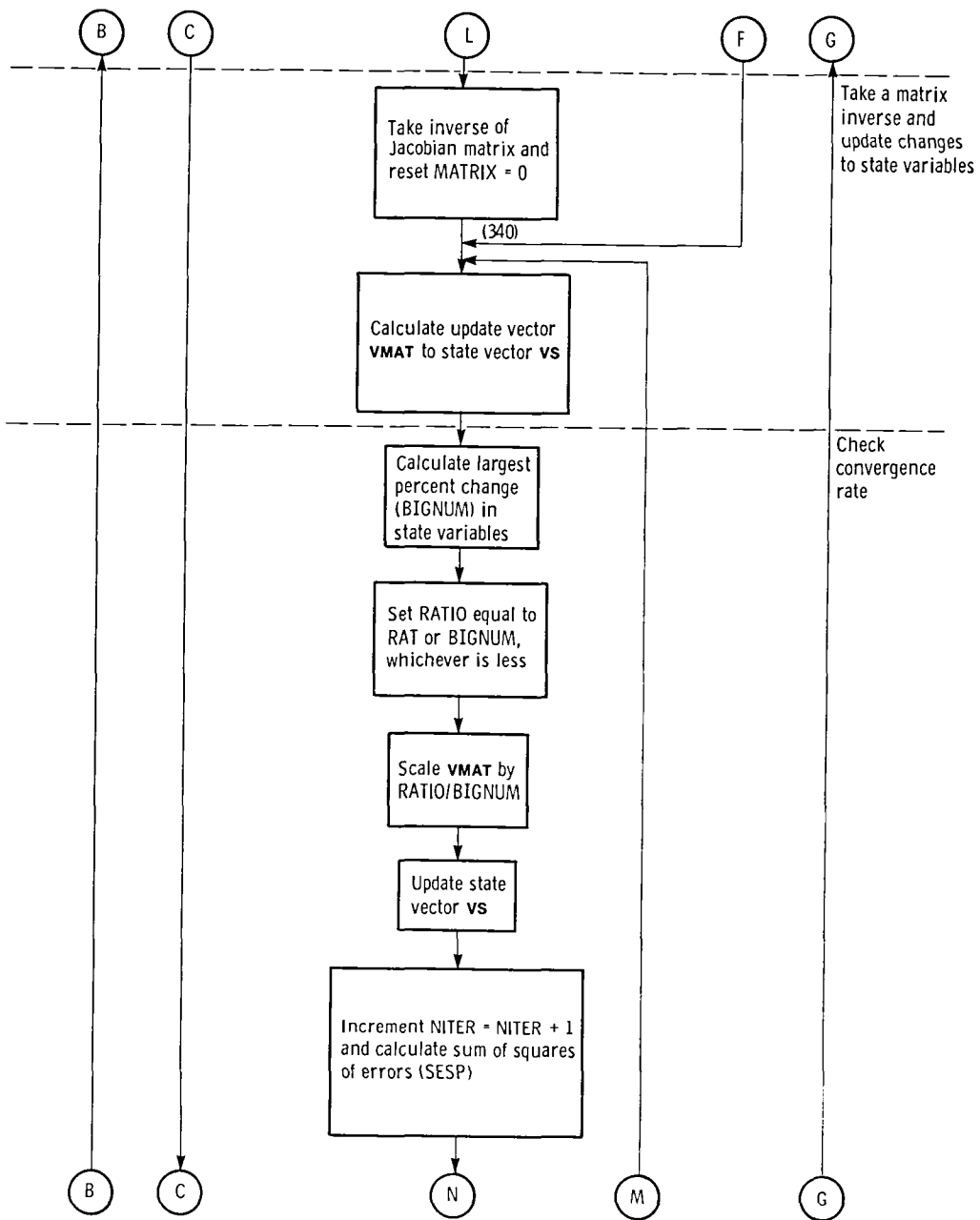
Subroutine FOURW2



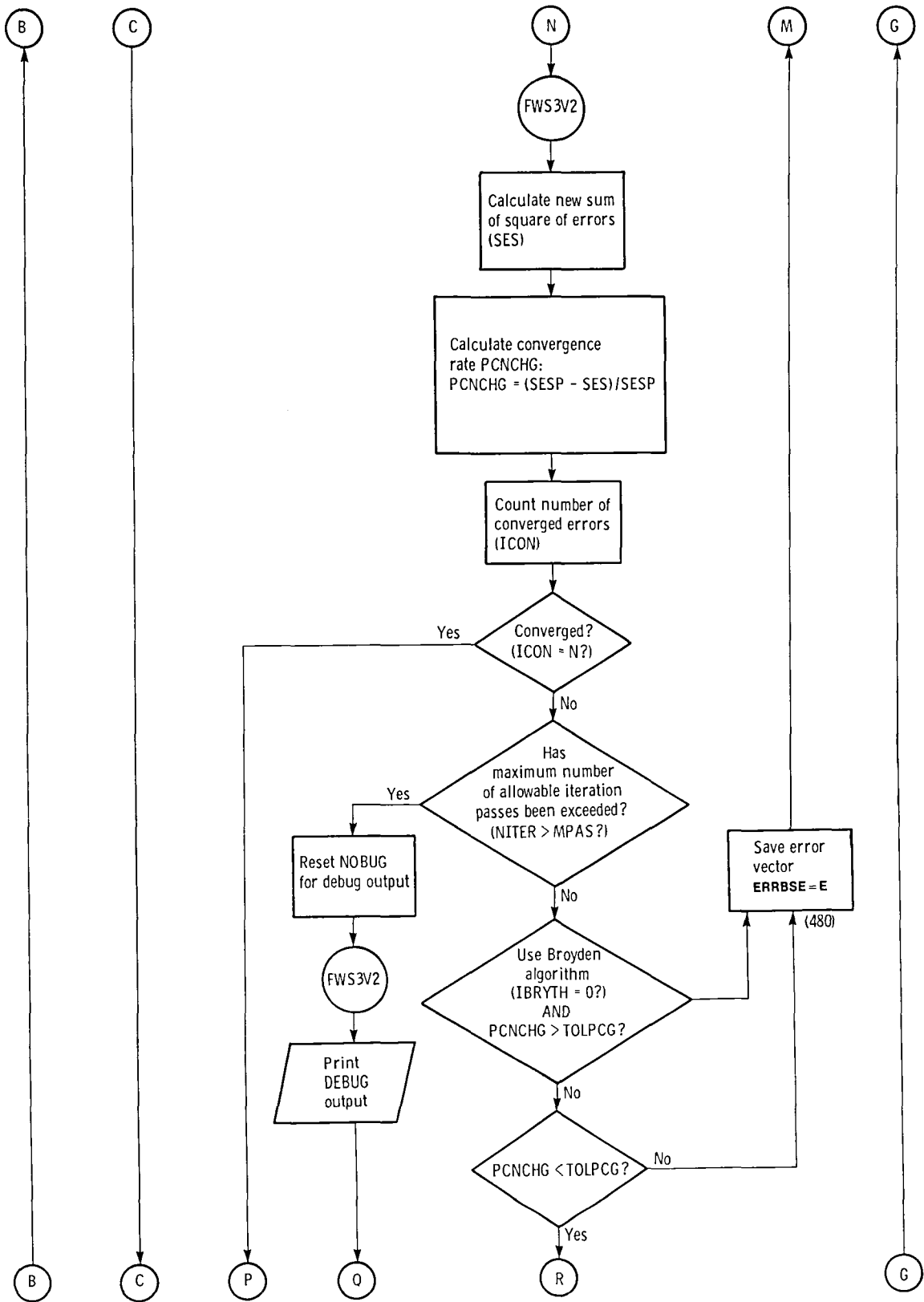


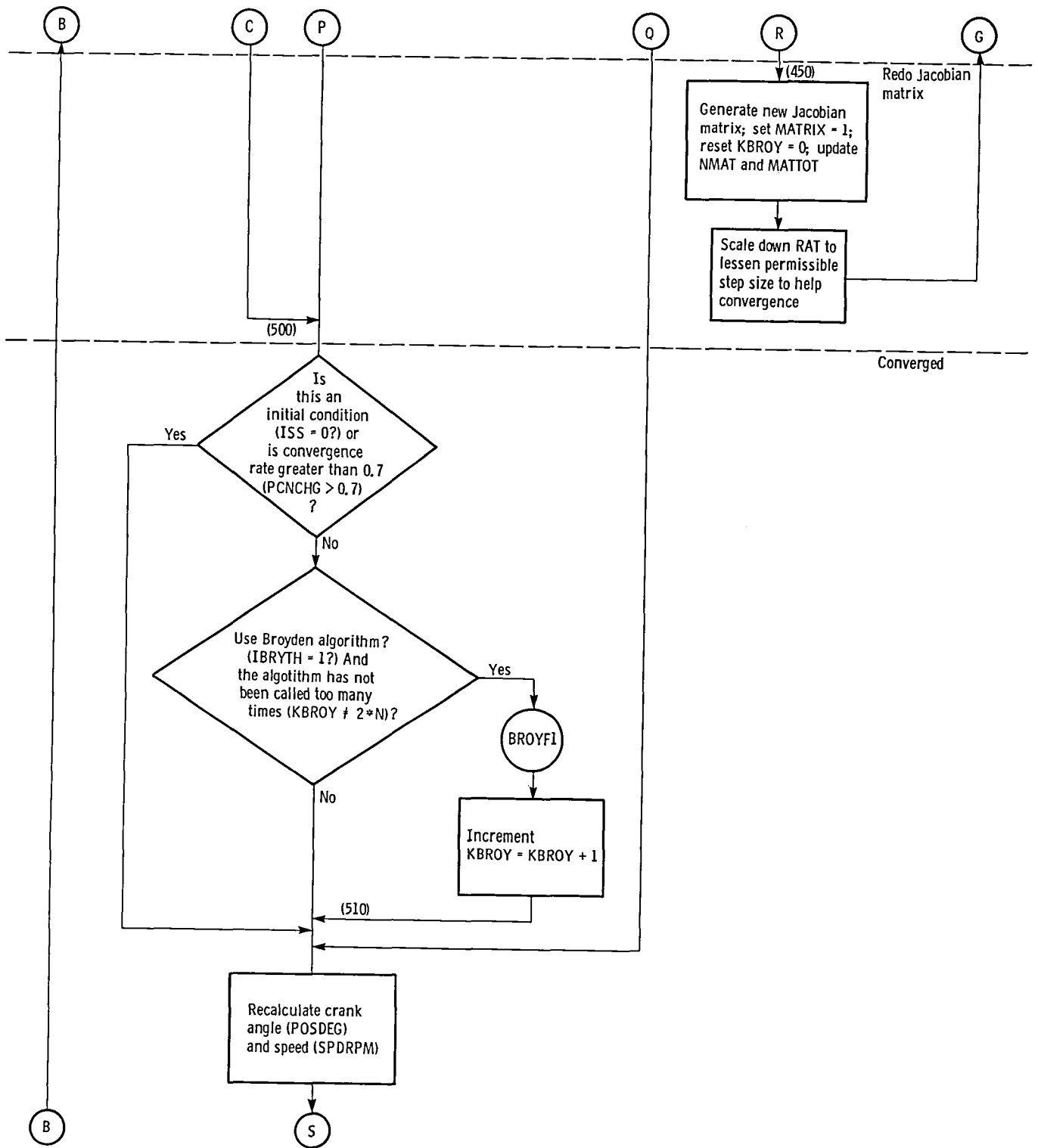


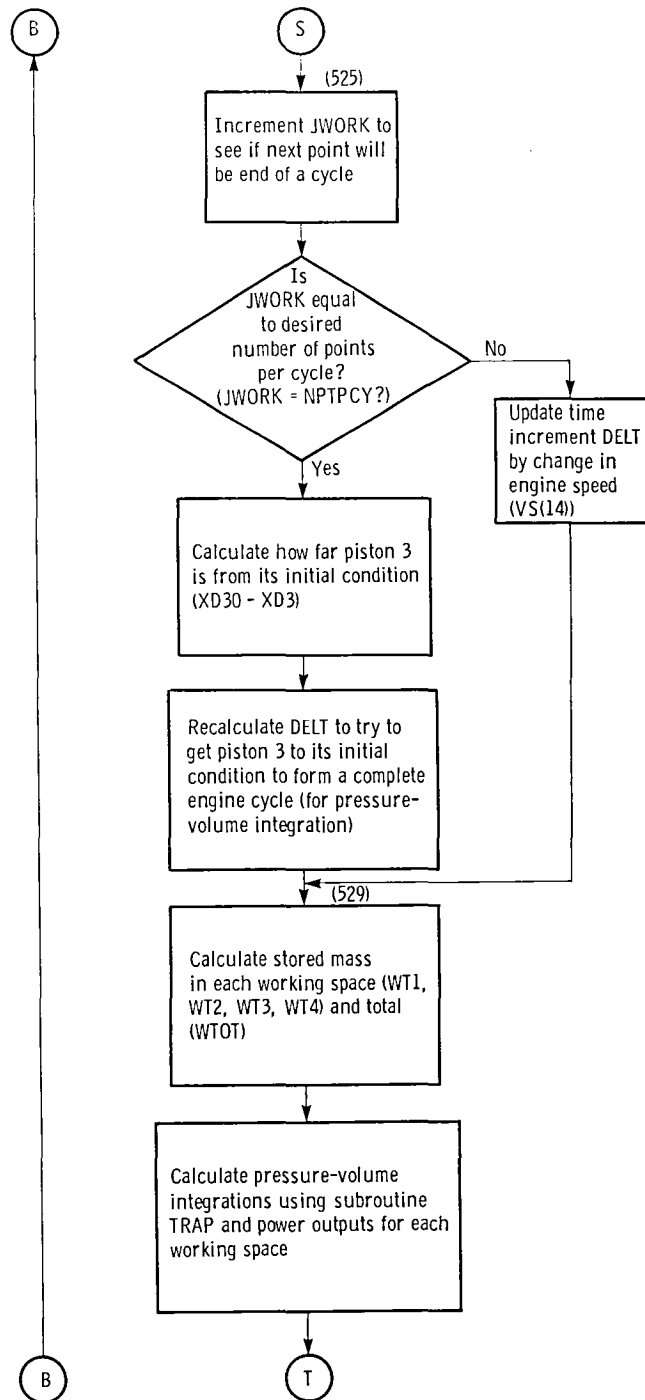


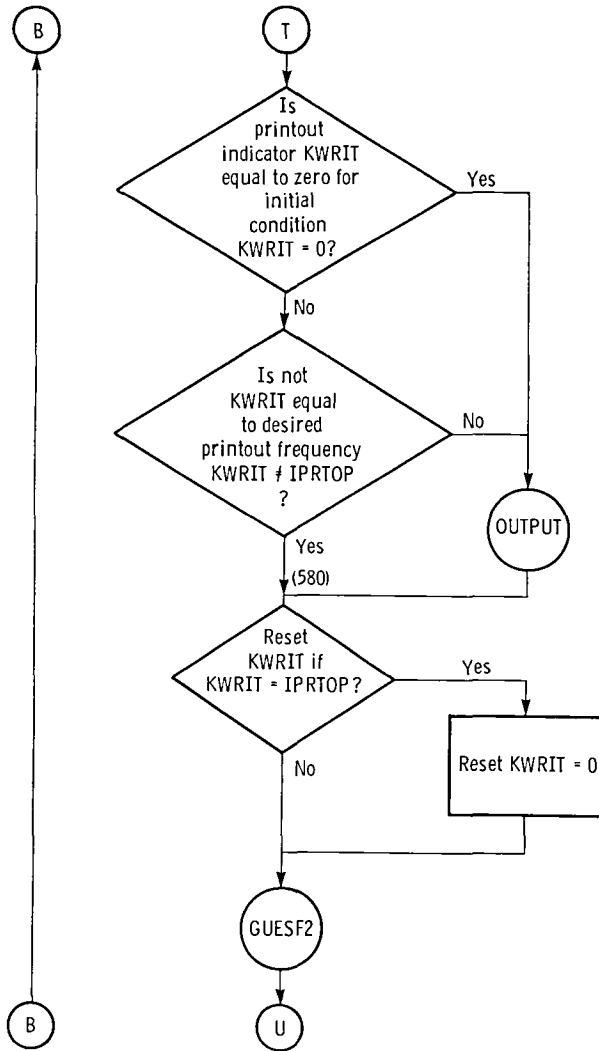


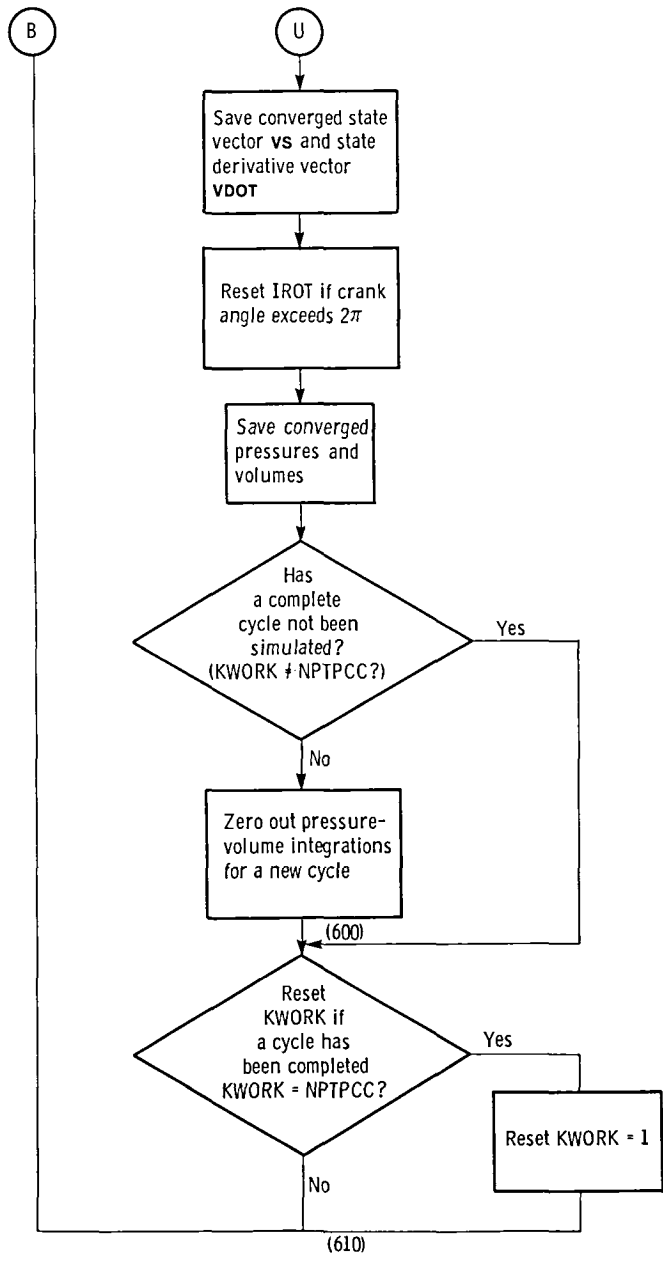




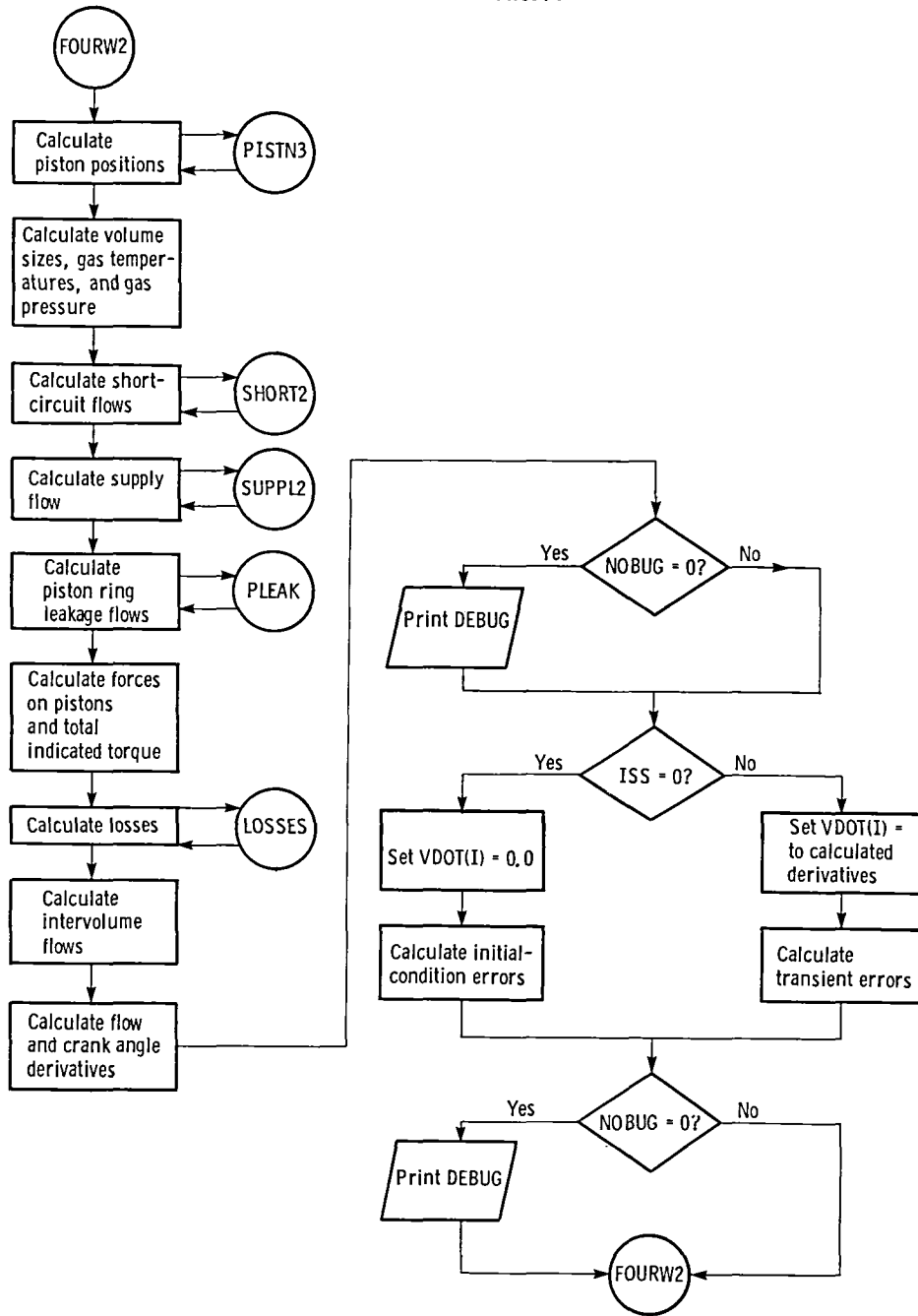




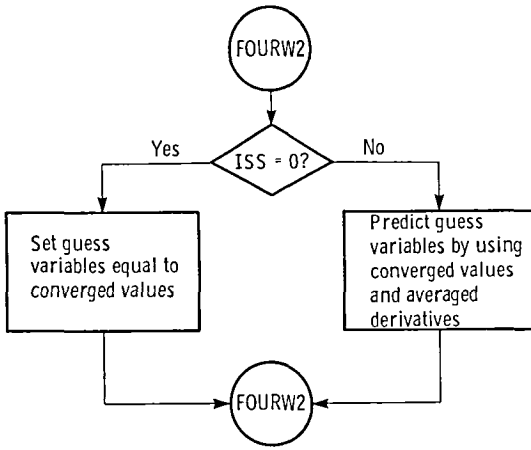




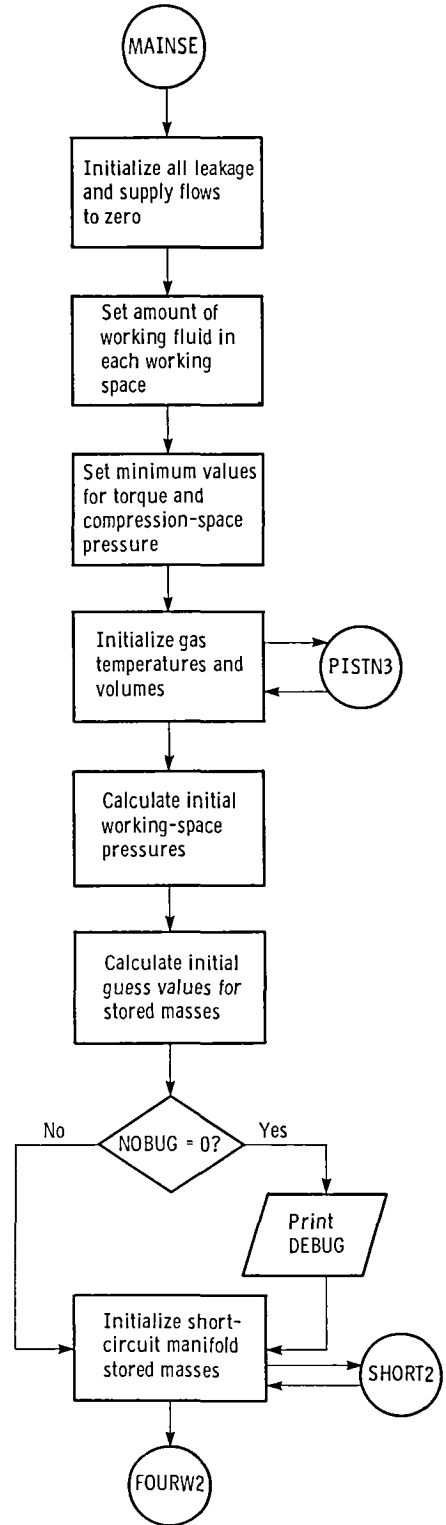
Subroutine FWS3V2



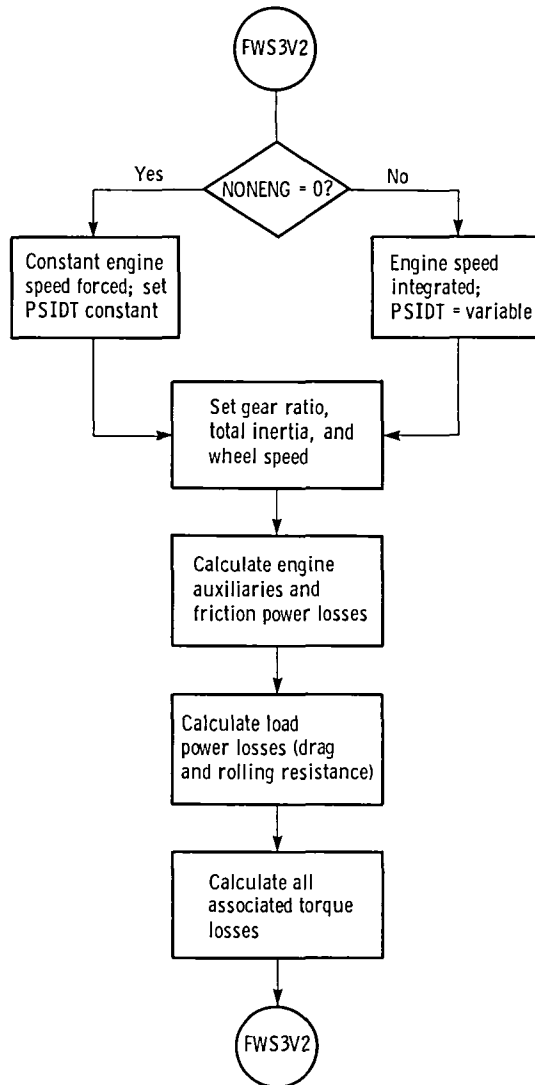
Subroutine GUESF2



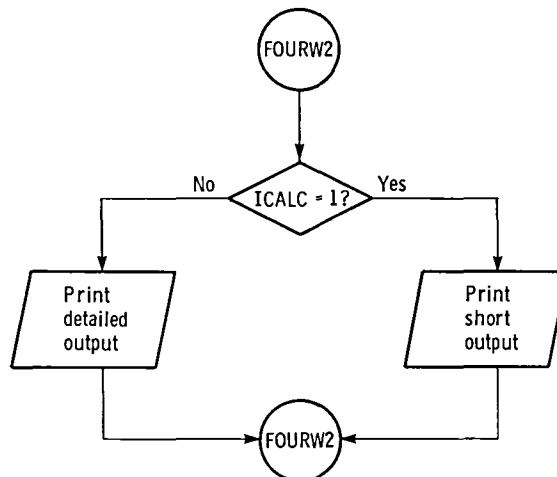
Subroutine ICSTUP



Subroutine LOSSES

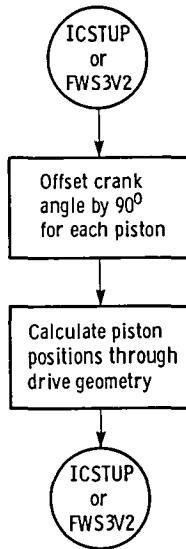


Subroutine OUTPUT

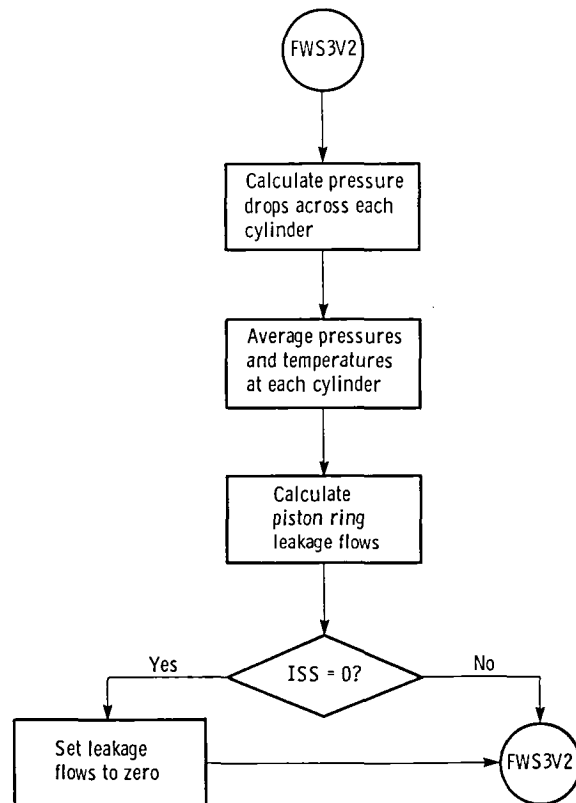




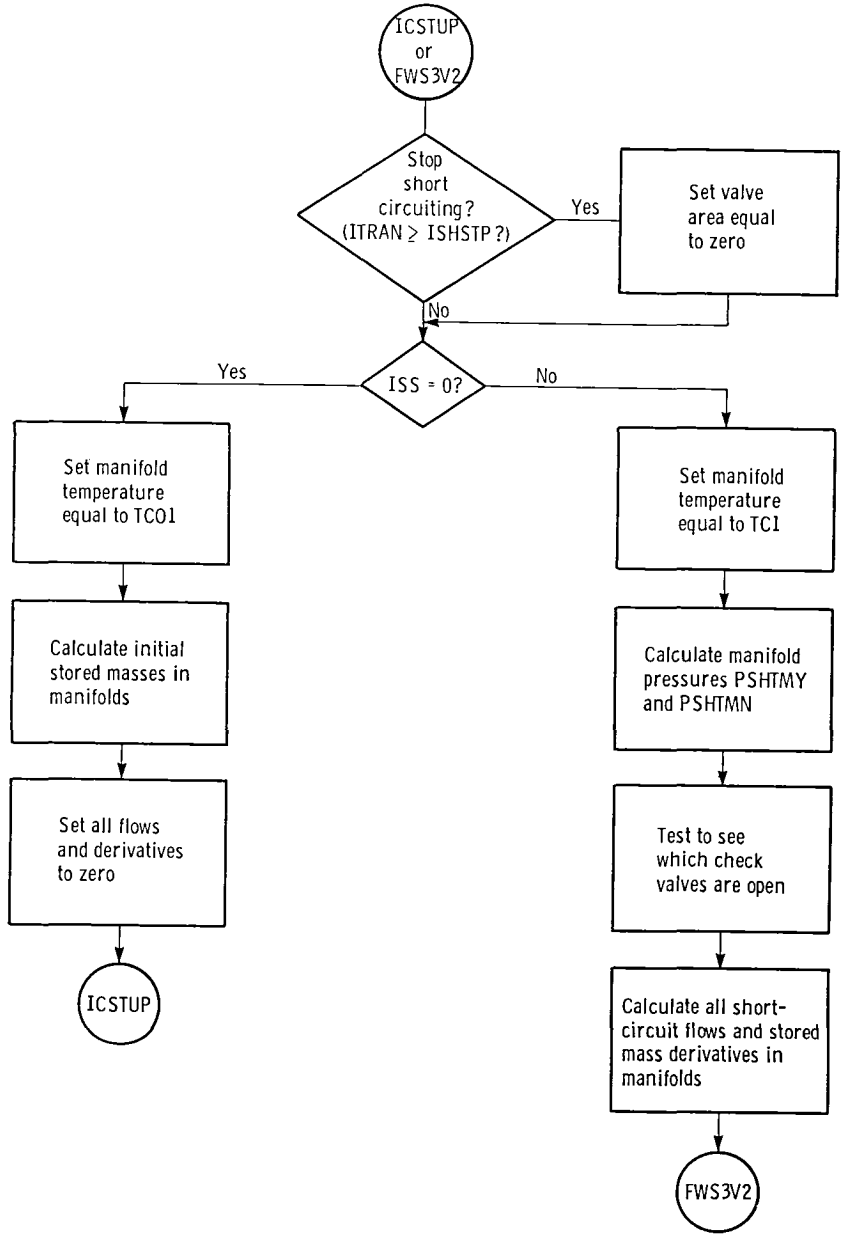
Subroutine PISTN3



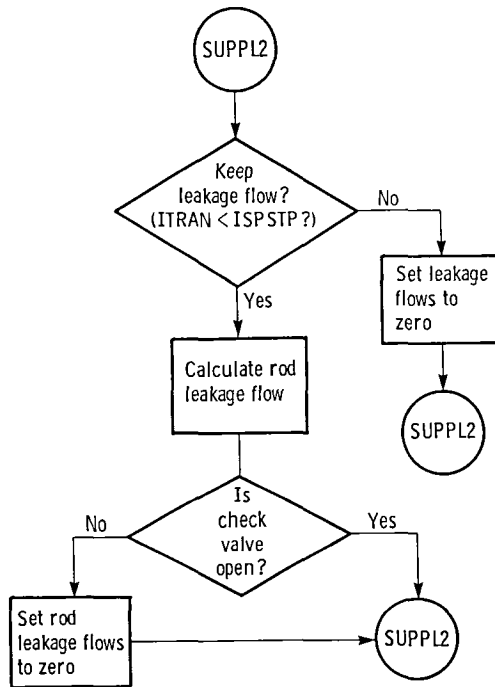
Subroutine PLEAK2



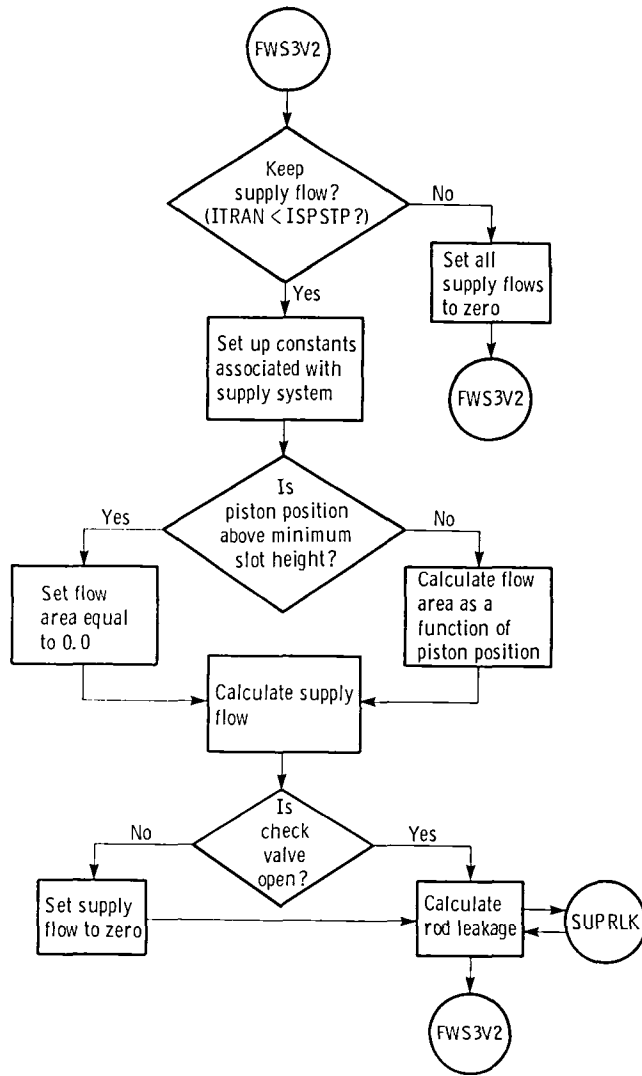
Subroutine SHORT2



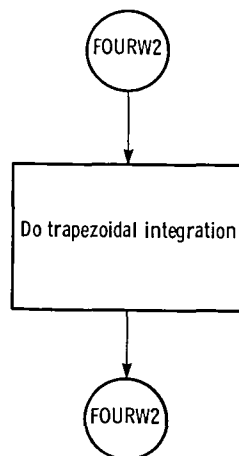
Subroutine SUPLRK



Subroutine SUPPL2



Subroutine TRAP



## Appendix D

### Steady-State Results

Steady-state results using the simulation are presented in figures 10 to 13. These results are presented here to help the user understand the mode of program operation.

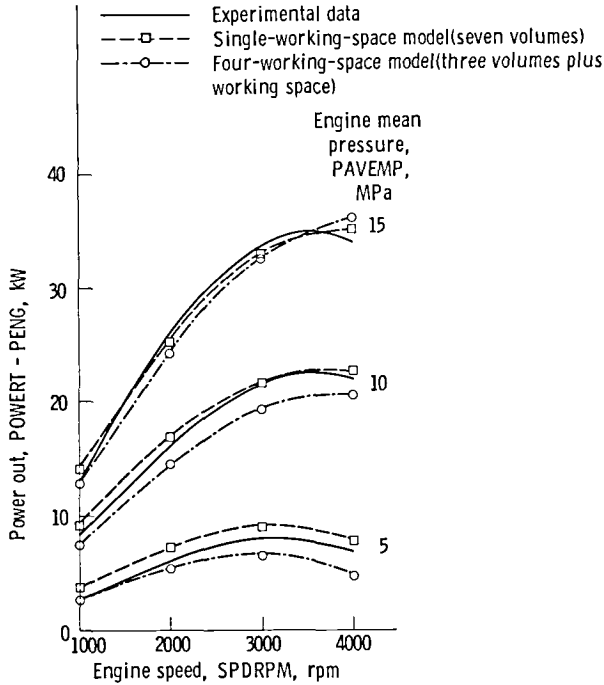


Figure 10. - Net power as a function of speed for single- and four-working-space models and engine data.

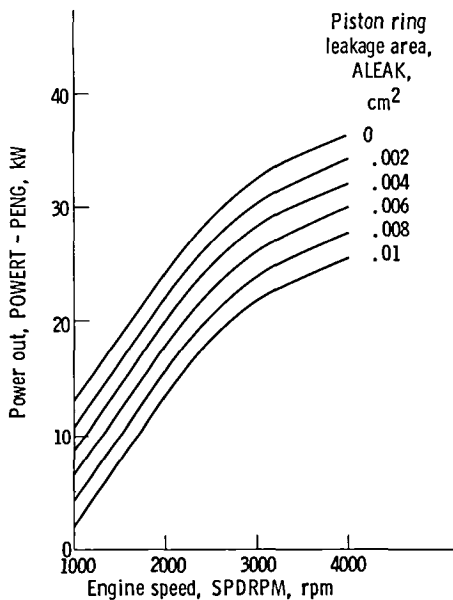


Figure 11. - Net power as a function of speed for various piston ring leakage areas. Engine mean pressure, PAVEMP, 15 MPa.

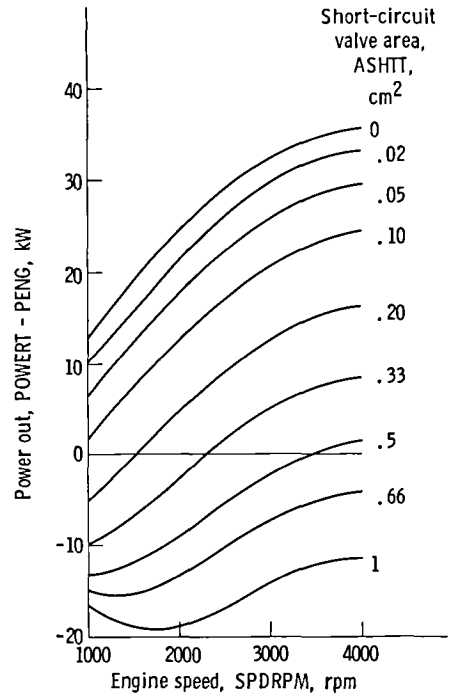


Figure 12. - Net power as a function of engine speed for various short-circuit valve areas. Engine mean pressure, PAVEMP, 15 MPa.

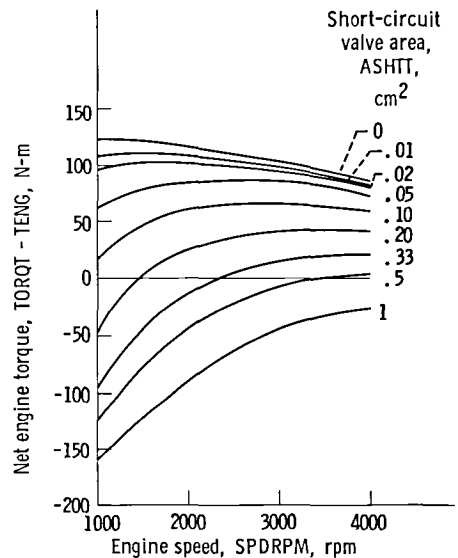


Figure 13. - Net torque as a function of engine speed for various short-circuit valve areas. Engine mean pressure, PAVEMP, 15 MPa.

The term “steady state” for a Stirling engine actually refers to a transient run in which the engine is simulated over many cycles at constant input conditions (constant heater and cooler wall temperatures and constant speed; i.e., no supply fluid). Figures 10 to 13 were also presented in reference 2. All steady-state cases were run by forcing piston position as a function of time (NONENG=0).

Figure 10 shows a comparison of results from the simplified four-cylinder Stirling engine controls model with results from the seven-volume, single-working-space model (which includes the energy equation). Also shown are experimental data run at Lewis. The simulation data were obtained by setting constant engine mean pressure (CYCLPR=5., 10., or 15. MPa) and constant engine speed (SPDRPM=1000., 2000., 3000., or 4000. rpm). After steady state was reached, cycle data were recorded. Figure 10 shows that the simplified model agrees well with the experimental data over the ranges of engine speed and mean pressure.

Steady-state power versus engine speed at different piston ring leakage areas is given in figure 11. To obtain these data, mean pressure was held constant at 15 MPa (CYCLPR=15.0), while speed and leakage area were varied (SPDRPM=1000., 2000., 3000., and 4000. and ALEAK=0.0, 0.002, 0.004, 0.006, 0.008, and 0.010, respectively). As expected, performance degrades as leakage area increases. However, power loss due to leakage seems to be independent of speed.

Net power versus speed for different short-circuit valve areas is shown in figure 12. These curves were generated by setting engine mean pressure constant (CYCLPR=15.0) and varying engine speed (SPDRPM) and short-circuit valve area (ASHTT). Note the large drop in engine power with short circuiting. The corresponding torque curve is given in figure 13. Torque reversal occurs for leakage areas above 0.1.

## Appendix E

### Transient Results

For controls analysis, transient data over a number of engine cycles are of interest. To obtain these data, the simulation calculates each cycle individually. Thus the simulation can also be used to obtain information regarding engine parameters during a single cycle. Data on an individual cycle basis were presented in reference 4. Data are presented herein to help the user understand how to obtain transient information.

A working-fluid supply transient for six cycles is shown in figure 14. Because for this case speed must change, the simulation must be run with the drive dynamics (NONENG=1). The initial engine pressure is 5 MPa (CYCLPR=5.0); the source pressure for the working fluid is 13.8 MPa (PSOURC=13.8); the supply is started at the second engine cycle (NCYSUP=2); there is no rod

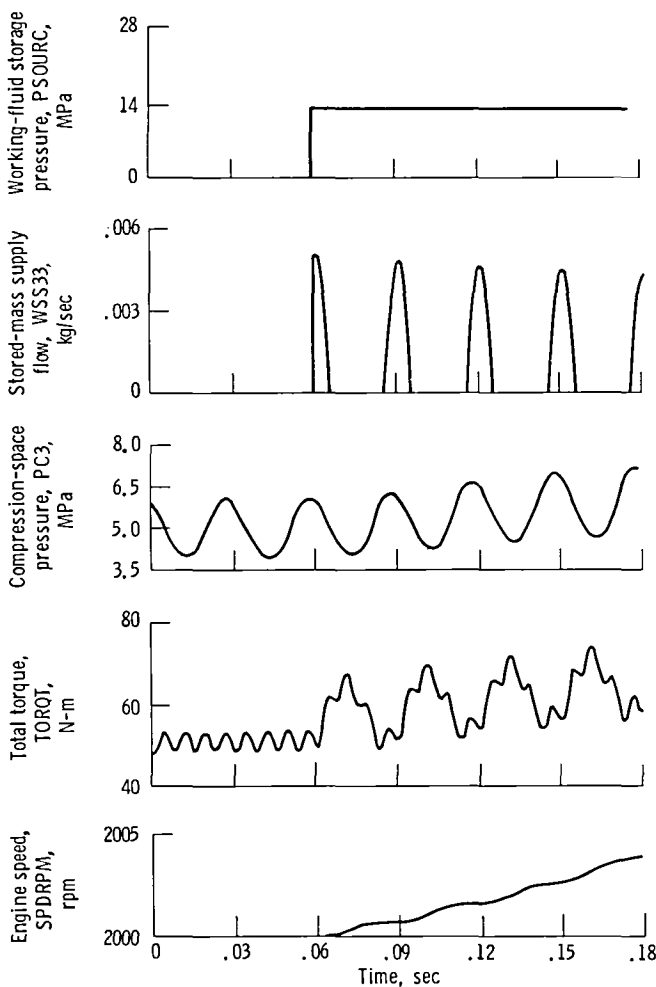


Figure 14. - Working-fluid supply transient with no piston rod leakage. Working-fluid storage pressure, PSOURC, 13.8 MPa at 0.06 sec.

leakage (ARLEAK=0.0). To get the desired printout, set IPRTOP equal to 1; this gives a printout at every point during the cycle (NPTPCY=100).

The same transient with piston rod leakage is shown in figure 15. In this case, all the input data are the same except ARLEAK=0.5. Note that the transient results for the two cases are markedly different.

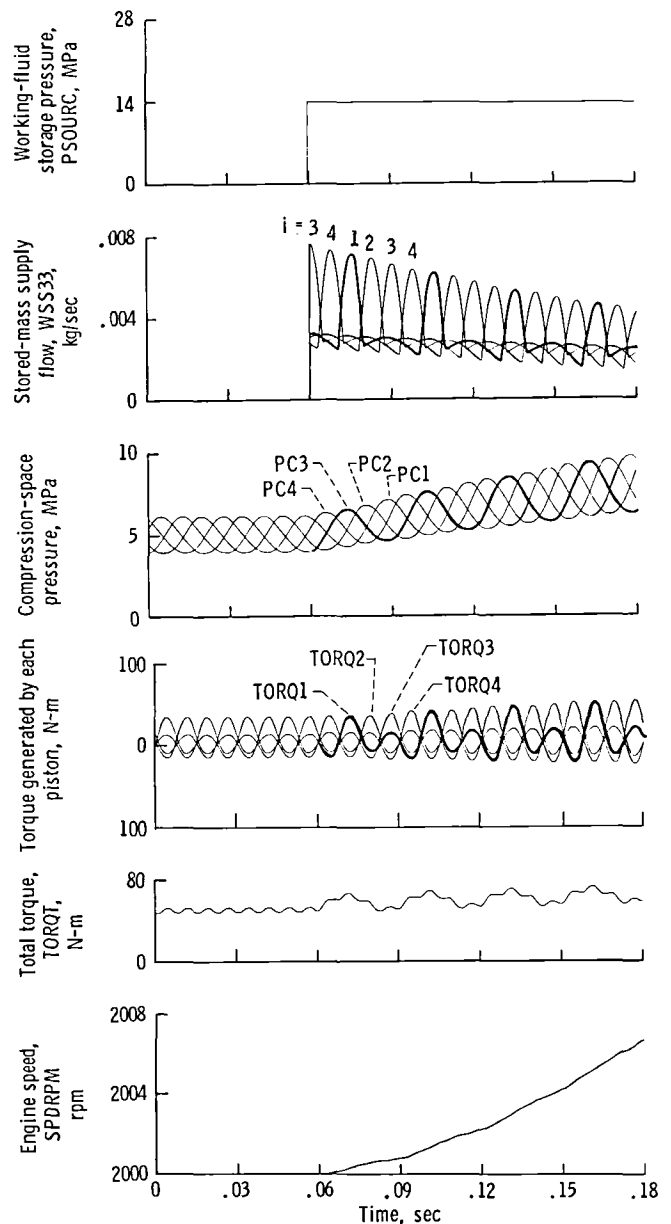


Figure 15. - Working-fluid supply transient with uniform piston rod leakage. Piston rod leakage area, ARLEAK, 0.5 cm<sup>2</sup>; working-fluid storage pressure, PSOURC, 13.8 MPa at 0.06 sec.

## References

1. Tew, R. C.; Jefferies, K.; and Miao, D.: A Stirling Engine Computer Model for Performance Calculations. DOE/NASA/1011-78/24, NASA TM-78884, 1978.
2. Daniele, Carl J.; and Lorenzo, Carl F. : Preliminary Results from a Four Working Space, Double-Acting Piston, Stirling Engine Controls Model. DOE/NASA/1040-17, NASA TM-81569, 1980.
3. Roache, Patrick J. : Computational Fluid Dynamics. Hermosa Publishers, 1972, pp. 64-67.
4. Lorenzo, Carl F.; and Daniele, Carl J.: A Four Cylinder Stirling Engine Controls Model. DOE/NASA/51040-21, NASA TM-81648, 1980.
5. Carnahan, B.; Luther, H. A.; and Wilkes, J: Applied Numerical Methods. John Wiley & Sons, Inc., 1969, pp. 319-320.
6. Broyden, C. G.: Quasi-Newton Methods and Their Applications to Function Minimization. Mathematics of Computation, vol. 21, July 1967, pp. 368-381.



TABLE I. - SIMULATION INPUT: ENGINE GEOMETRY

| Name   | Setting | Function                      |
|--------|---------|-------------------------------|
| AD     | 23.7613 | Piston area                   |
| AR     | 1.1290  | Piston rod area               |
| RODL   | 10.0    | Crank rod length              |
| VR     | 115.339 | Regenerator volume            |
| VOE    | 63.87   | Expansion-space dead volume   |
| VOC    | 61.70   | Compression-space dead volume |
| STROKE | 4.0     | Piston stroke                 |
| ALPHA  | 90.0    | Crank angle lag               |

TABLE II. - SIMULATION INPUT: HEATER  
AND COOLER WALL TEMPERATURES

| Name  | Setting | Function                |
|-------|---------|-------------------------|
| TWHIN | 705.0   | Heater wall temperature |
| TWCIN | 86.0    | Cooler wall temperature |

TABLE III. - SIMULATION INPUT:  
FLOW RESISTANCES

| Name | Setting | Function                                             |
|------|---------|------------------------------------------------------|
| RER  | 1.9     | Resistance between expansion space and regenerator   |
| RRC  | 1.9     | Resistance between regenerator and compression space |

TABLE IV. - SIMULATION INPUT: CONSTANTS

| Name | Setting | Function               |
|------|---------|------------------------|
| DEGR | 57.296  | Degrees to radians     |
| PIE  | 3.1416  | -----                  |
| R    | 4125.6  | Gas constant           |
| G    | 10017.0 | Gravitational constant |

TABLE V. - SIMULATION INPUT: MATRIX CONVERGENCE

| Name   | Setting | Function                                             |
|--------|---------|------------------------------------------------------|
| VDELTA | 0.01    | Initial perturbation of guesses, 1 percent           |
| FRAC   | 1.0     | External control of iteration step magnitude         |
| TOL1   | 0.001   | Bottom limit on error tolerance for matrix linearity |
| TOL2   | 0.01    | Top limit on error tolerance for matrix linearity    |
| TOLSS  | 0.0001  | Solution tolerance                                   |
| N      | 12      | System order when NONENG = 0                         |
|        | 14      | System order when NONENG = 1                         |
| NTMAX  | 16      | Largest system order (when short circuiting)         |
| MPAS   | 20      | Maximum allowable convergence passes                 |
| TOLPCG | 0.5     | Switch for calculating new matrix                    |

TABLE VI. - SIMULATION INPUT: SWITCHES

| Name   | Setting | Function                                |
|--------|---------|-----------------------------------------|
| ISS    | 0       | Set up initial conditions               |
|        | 1       | Transient (set internally)              |
| ICALC  | 0       | Detailed printout                       |
|        | 1       | Short printout                          |
| MATRIX | 1       | Generate a new Jacobian matrix          |
| NONENG | 0       | Force crank angle as a function of time |
|        | 1       | Runs with drive dynamics in             |
| IPRTOP | NN      | Print out data every NN points          |
| IBRYTH | 0       | Do not use Broyden algorithm            |
|        | 1       | Use Broyden algorithm                   |
| IHPCNV | 0       | Use logic to generate a new matrix      |
|        | 1       | Generate a new matrix at every point    |
| NOBUG  | 0       | No debug output <sup>a</sup>            |
|        | 1       | Desire debug output                     |

<sup>a</sup>If iteration convergence fails or matrix generation problems occur, a debug output is given.

TABLE VII. - SIMULATION INPUT: RUN CONDITIONS

| Name   | Setting  | Function                                               |
|--------|----------|--------------------------------------------------------|
| ALEAK  | 0.0      | Piston ring leakage area scalar                        |
| ARLEAK | 0.0      | Piston rod leakage area                                |
| PSOURC | 10.0     | Hydrogen bottle pressure                               |
| CYCLPM | 15.0     | Maximum engine pressure                                |
| SPDMAX | 4000.0   | Maximum engine speed                                   |
| CYCLPR | 5.0      | Initial engine pressure                                |
| POSDEO | 270.0    | Initial crank angle                                    |
| WSTOTL | 0.007786 | Total stored mass at 15 MPa                            |
| VSH    | 32.78    | Short-circuit volume                                   |
| RSHT   | 38.0     | Flow resistance between plenums and compression spaces |
| ASHTT  | 0.2      | Short-circuit valve area                               |

TABLE IX. - SIMULATION INPUT: CYCLE DATA

| Name   | Setting | Function                     |
|--------|---------|------------------------------|
| NUMBCY | 100     | Desired number of cycles     |
| NPTPCY | 100     | Integration points per cycle |

TABLE VIII. - SIMULATION INPUT:  
LOAD CHARACTERISTICS

[Vehicle information values given in this report are representative and do not correspond to any actual vehicle.]

| Name   | Setting  | Function                |
|--------|----------|-------------------------|
| GTRAN  | 1.0/2.53 | Transmission gear ratio |
| GR     | 1.5      | Gear ratio              |
| WTENG  | 0.0      | Engine mass             |
| WTWHEL | 20.48    | Mass of a wheel         |
| WTCAR  | 1420.0   | Car mass                |
| RWHEEL | 30.48    | Wheel radius            |

TABLE X. - SIMULATION INPUT: TRANSIENT DESIRED

| Name   | Setting            | Function                               |
|--------|--------------------|----------------------------------------|
| NCYSHT | 5                  | Start of short circuit at fifth cycle  |
| NCYSUP | <sup>a</sup> 15000 | Start of supply at 15 000th cycle      |
| NCYSTP | <sup>a</sup> 40000 | End of supply at 40 000th cycle        |
| NCYSHS | 500                | End of short circuiting at 500th cycle |

<sup>a</sup>Note that if no supply (or short-circuiting) is desired, set the corresponding start and end parameters very large (greater than the number of cycles desired).



TABLE XIII. - SAMPLE OUTPUT FOR DETAILED PRINTOUT OPTION (ICALC = 0)

STIRLING ENGINE FOUR CYLINDER, THREE VOLUMES PER CYLINDER, CONTROLS MODEL

| RUN CONDITIONS FOR THIS TRANSIENT |             |             |            |            |             |             |             |             |             |             |       |
|-----------------------------------|-------------|-------------|------------|------------|-------------|-------------|-------------|-------------|-------------|-------------|-------|
| TWH =                             | 978.0       | TWC =       | 359.0      | CYCLPR =   | 5.000       | NONENG =    | 1           | NUMBCY =    | 1           |             |       |
| ALEAK =                           | 0.0000      | ARLEAK =    | 0.0000     | PSOURC =   | 10.00       | ISUPST =    | 501         | ISHTST =    | 5000001     |             |       |
| TIME                              | XD1         | XD2         | XD3        | XD4        | POSDEG      | SPDRPM      | PAVEMP      | WTOT        | DELT        | ITRAN       |       |
|                                   | PE1         | PR1         | PC1        | TE1        | TR1         | TC1         | VE1         | VR1         | VC1         | WT1         |       |
|                                   | PE2         | PR2         | PC2        | TE2        | TR2         | TC2         | VE2         | VR2         | VC2         | WT2         |       |
|                                   | PE3         | PR3         | PC3        | TE3        | TR3         | TC3         | VE3         | VR3         | VC3         | WT3         |       |
|                                   | PE4         | PR4         | PC4        | TE4        | TR4         | TC4         | VE4         | VR4         | VC4         | WT4         |       |
|                                   | WD1         | WD2         | WSS11      | WSSCN1     | WD1IN       | WD1OUT      | WLK12       | WSE1DT      | WSR1DT      | WSC1DT      |       |
|                                   | WD7         | WD8         | WSS22      | WSSCN2     | WD2IN       | WD2OUT      | WLK23       | WSE2DT      | WSR2DT      | WSC2DT      |       |
|                                   | WD5         | WD6         | WSS33      | WSSCN3     | WD3IN       | WD3OUT      | WLK34       | WSE3DT      | WSR3DT      | WSC3DT      |       |
|                                   | WD3         | WD4         | WSS44      | WSSCN4     | WD4IN       | WD4OUT      | WLK41       | WSE4DT      | WSR4DT      | WSC4DT      |       |
|                                   | VS(1)       | VS(2)       | VS(3)      | VS(13)     | E(1)        | E(2)        | E(3)        | E(13)       | TORQ1       | POWER1      |       |
|                                   | VS(4)       | VS(5)       | VS(6)      | VS(14)     | E(4)        | E(5)        | E(6)        | E(14)       | TORQ2       | POWER2      |       |
|                                   | VS(7)       | VS(8)       | VS(9)      | VS(15)     | E(7)        | E(8)        | E(9)        | E(15)       | TORQ3       | POWER3      |       |
|                                   | VS(10)      | VS(11)      | VS(12)     | VS(16)     | E(10)       | E(11)       | E(12)       | E(16)       | TORQ4       | POWER4      |       |
|                                   | WSTMXD      | WSTMND      | WDSHT      | PSHTMX     | PSHTMN      | TSH         | WSMX1       | WSMN1       |             |             |       |
| POSDEG                            | POWERT      | PFRICT      | PAUX       | PRRF       | PDRAG       | PLOAD       | PENG        | PNET        | KWORK       | SPDRPM      | VKPH  |
|                                   | TORQT       | TFRICT      | TAUX       | TRRF       | TDRAG       | TLOAD       | TENG        | TNET        |             |             |       |
| 0.3000E-01                        | -0.2031     | -2.000      | -0.2008    | 2.000      | 270.0       | 2000.       | 5.003       | 0.2609E-02  | 0.3000E-03  | 101         |       |
|                                   | 4.031       | 4.015       | 4.004      | 933.6      | 670.2       | 406.8       | 116.2       | 115.3       | 152.2       | 0.6523E-03  |       |
|                                   | 4.552       | 4.539       | 4.511      | 933.6      | 670.2       | 406.8       | 158.9       | 115.3       | 102.4       | 0.6523E-03  |       |
|                                   | 5.985       | 6.007       | 6.017      | 933.6      | 670.2       | 406.8       | 116.2       | 115.3       | 61.70       | 0.6523E-03  |       |
|                                   | 5.445       | 5.453       | 5.481      | 933.6      | 670.2       | 406.8       | 63.87       | 115.3       | 102.4       | 0.6523E-03  |       |
|                                   | 0.8571E-02  | 0.5987E-02  | 0.0000     | 0.0000     | 0.0000      | 0.0000      | 0.0000      | -0.8571E-02 | 0.2584E-02  | 0.5987E-02  |       |
|                                   | 0.7222E-02  | 0.1462E-01  | 0.0000     | 0.0000     | 0.0000      | 0.0000      | 0.0000      | -0.7222E-02 | -0.7403E-02 | 0.1462E-01  |       |
|                                   | -0.1133E-01 | -0.5490E-02 | 0.0000     | 0.0000     | 0.0000      | 0.0000      | 0.0000      | 0.1133E-01  | -0.5836E-02 | -0.5490E-02 |       |
|                                   | -0.4178E-02 | -0.1491E-01 | 0.0000     | 0.0000     | 0.0000      | 0.0000      | 0.0000      | 0.4178E-02  | 0.1073E-01  | -0.1491E-01 |       |
|                                   | 0.1216E-03  | 0.1675E-03  | 0.3632E-03 | 4.712      | 0.9936E-05  | -0.1462E-05 | -0.1090E-05 | 0.9294E-07  | 12.60       | 2.671       |       |
|                                   | 0.1878E-03  | 0.1893E-03  | 0.2752E-03 | 209.4      | 0.1049E-05  | -0.6665E-05 | 0.2206E-05  | 0.4292E-07  | -0.2490E-01 | 2.664       |       |
|                                   | 0.1805E-03  | 0.2506E-03  | 0.2212E-03 | 0.1172E-03 | -0.8438E-04 | 0.2859E-04  | -0.1996E-04 | 0.0000      | 36.32       | 2.662       |       |
|                                   | 0.9029E-04  | 0.2275E-03  | 0.3345E-03 | 0.7813E-04 | 0.1733E-05  | -0.1554E-04 | 0.6429E-05  | 0.0000      | -0.5058E-01 | 2.671       |       |
|                                   | 0.0000      | 0.0000      | 0.0000     | 6.000      | 4.000       | 0.0000      | 0.1172E-03  | 0.7813E-04  |             |             |       |
| 270.0                             | 10.67       | 3.221       | 2.108      | 2.531      | 2.360       | 4.891       | 5.329       | 0.3469      |             |             |       |
|                                   | 48.84       | 15.38       | 10.07      | 12.09      | 11.27       | 23.35       | 25.45       | 0.4489E-01  | 101         | 2000.06     | 60.56 |

TABLE XIV. - SAMPLE DEBUG PRINTOUT (NOBUG = 0)

|                                     |                |                 |                 |                 |            |            |            |            |
|-------------------------------------|----------------|-----------------|-----------------|-----------------|------------|------------|------------|------------|
| -0.20196623                         | -1.9998884     | -0.20191854     | 2.0001106       |                 |            |            |            |            |
| 12.062994                           | 12.062994      | 12.062994       | 0.00000000      | 0.00000000      | 116.19153  | 152.23161  |            |            |
| 13.569489                           | 13.569489      | 13.569489       | 0.00000000      | 0.00000000      | 158.91251  | 102.39359  |            |            |
| 17.951859                           | 17.951859      | 17.951859       | 0.00000000      | 0.00000000      | 116.19040  | 61.702515  |            |            |
| 16.429947                           | 16.429947      | 16.429947       | 0.00000000      | 0.00000000      | 63.867355  | 102.39467  |            |            |
| 922.44482                           | 668.49976      | 414.55493       | 922.44482       | 668.49976       | 414.55493  |            |            |            |
| 922.44482                           | 668.49976      | 414.55493       | 922.44482       | 668.49976       | 414.55493  |            |            |            |
| 0.00000000                          | 0.00000000     | 0.00000000      | 0.00000000      | 0.00000000      | 0.00000000 |            |            |            |
| 0.00000000                          | 0.00000000     | 0.00000000      | 0.00000000      | 0.00000000      | 0.00000000 | 0.00000000 | 0.00000000 |            |
| 0.00000000                          | 0.00000000     | 0.00000000      | 0.00000000      | 0.00000000      | 0.00000000 | 0.00000000 | 0.00000000 |            |
| 16.000000                           | 14.000000      | 0.00000000      | 0.00000000      | 0.00000000      |            |            |            |            |
| DEBUG OUTPUT FROM FOURW2 NUMBER 1   |                |                 |                 |                 |            |            |            |            |
| TIME = 0.00000000                   |                |                 |                 |                 |            |            |            |            |
| DEBUG PRINTOUT FROM FWS3V2 NUMBER 1 |                |                 |                 |                 |            |            |            |            |
| -0.20196623                         | -1.9998884     | -0.20191854     | 2.0001106       |                 |            |            |            |            |
| 12.062987                           | 12.062986      | 12.062989       | 0.50193393E-06  | -0.15058013E-05 | 116.19153  | 152.23161  |            |            |
| 13.569483                           | 13.569486      | 13.569482       | 0.00000000      | 0.00000000      | 158.91251  | 102.39359  |            |            |
| 17.951843                           | 17.951843      | 17.951843       | 0.00000000      | 0.00000000      | 116.19040  | 61.702515  |            |            |
| 16.429932                           | 16.429932      | 16.429932       | -0.15058013E-05 | 0.20077350E-05  | 63.867355  | 102.39467  |            |            |
| 922.44482                           | 668.49976      | 414.55493       | 922.44482       | 668.49976       | 414.55493  |            |            |            |
| 922.44482                           | 668.49976      | 414.55493       | 922.44482       | 668.49976       | 414.55493  |            |            |            |
| 418.87988                           | 7.9077196      | 80.492523       | 150.37494       | 21.255264       | 2.6879129  |            |            |            |
| 0.00000000                          | 0.00000000     | 0.00000000      | 0.00000000      | 0.00000000      | 0.00000000 | 0.00000000 | 0.00000000 |            |
| 0.00000000                          | 0.00000000     | 0.00000000      | 0.00000000      | 0.00000000      | 0.00000000 | 0.00000000 | 0.00000000 |            |
| 16.000000                           | 14.000000      | 0.00000000      | 0.00000000      | 0.00000000      |            |            |            |            |
| DEBUG PRINTOUT FROM FWS3V2 NUMBER 2 |                |                 |                 |                 |            |            |            |            |
| 1                                   | 0.36830036E-03 | -0.81770270E-06 | 0.00000000      | 0.00000000      | 0.00000000 | 0.00000000 | 0.00000000 | 0.00000000 |
| 2                                   | 0.50447881E-03 | 0.23878920E-05  | 0.00000000      | 0.00000000      | 0.00000000 | 0.00000000 | 0.00000000 | 0.00000000 |
| 3                                   | 0.10737202E-02 | -0.84144904E-06 | 0.00000000      | 0.00000000      | 0.00000000 | 0.00000000 | 0.00000000 | 0.00000000 |
| 4                                   | 0.56662294E-03 | 0.15945006E-05  | 0.00000000      | 0.00000000      | 0.00000000 | 0.00000000 | 0.00000000 | 0.00000000 |
| 5                                   | 0.56748115E-03 | -0.37148757E-05 | 0.00000000      | 0.00000000      | 0.00000000 | 0.00000000 | 0.00000000 | 0.00000000 |
| 6                                   | 0.81239524E-03 | 0.14828265E-05  | 0.00000000      | 0.00000000      | 0.00000000 | 0.00000000 | 0.00000000 | 0.00000000 |
| 7                                   | 0.54809055E-03 | 0.00000000      | 0.00000000      | 0.00000000      | 0.00000000 | 0.00000000 | 0.00000000 | 0.00000000 |
| 8                                   | 0.75075356E-03 | 0.00000000      | 0.00000000      | 0.00000000      | 0.00000000 | 0.00000000 | 0.00000000 | 0.00000000 |
| 9                                   | 0.64765452E-03 | 0.00000000      | 0.00000000      | 0.00000000      | 0.00000000 | 0.00000000 | 0.00000000 | 0.00000000 |
| 10                                  | 0.27573225E-03 | 0.00000000      | 0.00000000      | 0.00000000      | 0.00000000 | 0.00000000 | 0.00000000 | 0.00000000 |
| 11                                  | 0.68710651E-03 | 0.00000000      | 0.00000000      | 0.00000000      | 0.00000000 | 0.00000000 | 0.00000000 | 0.00000000 |
| 12                                  | 0.98365918E-03 | 0.00000000      | 0.00000000      | 0.00000000      | 0.00000000 | 0.00000000 | 0.00000000 | 0.00000000 |
| 13                                  | 4.7123709      | 0.00000000      | 0.00000000      | 0.00000000      | 0.00000000 | 0.00000000 | 0.00000000 | 0.00000000 |
| 14                                  | 418.87988      | 0.00000000      | 0.00000000      | 0.00000000      | 0.00000000 | 0.00000000 | 0.00000000 | 0.00000000 |
| CONVERGENCE IN ERR VECTOR           |                |                 |                 |                 |            |            |            |            |

TABLE XV. - INPUT ROUTINE (MAINSE) FOR SUPPLY TRANSIENT (100 POINTS/CYCLE)

```

100 C INPUT DATA FOR THE FOUR WORKING SPACE THREE VOLUME
200 C STIRLING ENGINE MODEL.
300 C
400 COMMON/PST/AD,AR,RODL,VOE,VR,RER,RRC,STROKE,ALPHA,PSIMD
500 COMMON/CARLOD/GTRAN,GR,AIE,AIWHEL,AIVEH,RWHEEL,AINERT
600 COMMON/CONST/R,G,PIE,DEGR
700 COMMON/MATXIN/VDELTA,FRAC,TOL1,TOL2,TOLSS,N,NTMAX,MPAS,
800 1 TOLPCG,REF
900 COMMON/SWITCH/ISS,ICALC,MATRIX,NONENG,IPRTOP,IBRYTH,
1000 1 IHPCNV,NOBUG
1100 COMMON /SHRTCT/ WD1IN,WD2IN,WD3IN,WD4IN,WD1OUT,WD2OUT,WD3OUT,WD4OUT
1200 1T,WDSHT,WSTMXD,WSTMND,PSHTMX,PSHTMN,WSMX1,WSMN1,VSH,RSHT,RSHTT
1300 COMMON/RUNCON/ALEAK,ARLEAK,PSOURC,CYCLPR,SPDRPM,POSDEG,
1400 1 WSTOTL,TWHIN,TWCIN,CYCLPM,SPDMAX
1500 COMMON/CYDATA/NPTPCY,ITRMAX,NUMBCY
1600 COMMON/TRANDS/ISUPST,ISHTST,TIME,KWORK,ISPSTP,ISHSTP
1700 COMMON/OUTPT/POSDEG,WTOT,ITRAN,WT1,WT2,WT3,WT4,WD1,WD2,WD3,WD4,
1800 1WD5,WD6,WD7,WD8,TORQ1,TORQ2,TORQ3,TORQ4,POWER1,POWER2,POWER3,
1900 2POWER4,POWER4,TORQT,TLOAD,TENG,PLOAD,PENG,PNET,PAVEMP,CCCHK
2000 C
2100 C
2200 C ENGINE GEOMETRY
2300 AD=23.7613
2400 AR=1.1290
2500 RODL=10.0
2600 VR=115.339
2700 VOE=63.87
2800 VOC=61.70
2900 STROKE=4.00
3000 ALPHA=90.0
3100 C
3200 C HEATER AND COOLER WALL TEMPERATURES
3300 TWHIN=705.0
3400 TWCIN=86.0
3500 C
3600 C FLOW RESISTANCES BETWEEN VOLUMES
3700 RER=1.9
3800 RRC=1.9
3900 C
4000 C CONSTANTS
4100 DEGR=57.296
4200 PIE=3.1416
4300 R=4125.6
4400 G=10017.0
4500 C
4600 C MATRIX CONVERGENCE INPUT
4700 VDELTA=.01
4800 FRAC=1.0
4900 TOL1=.001
5000 TOL2=.01
5100 TOLSS=.0001
5200 N=14
5300 NTMAX=16

5400 MPAS=20
5500 TOLPCG=.5
5600 C
5700 C SWITCHES
5800 ISS=0
5900 ICALC=1
6000 MATRIX=1
6100 NONENG=1
6200 IPRTOP=100
6300 IBRYTH=0
6400 IHPCNV=0
6500 NOBUG=1
6600 C
6700 C RUN CONDITIONS

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```

6800      ALEAK=0.0
6900      ARLEAK=0.0
7000      PSOURC=10.0
7100      CYCLPM=15.0
7200      SPDMAX=4000.0
7300      CYCLPR=5.0
7400      SPDRPM=2000.0
7500      POSDEO=270.0
7600      WSTOTL=.007786
7700      VSH=32.78
7800      RSHT=38.0
7900      ASHTT=.20
8000      C
8100      C      LOAD CHARACTERISTICS
8200      GTRAN=1.0/2.53
8300      GR=1.5
8400      WTENG=0.0
8500      WTWHEL=29.48
8600      WTCAR=1420.0
8700      RWHEEL=30.48
8800      C
8900      C      CYCLE DATA
9000      NPTPCY=100
9100      NUMBCY=1000
9200      C
9300      C      TRANSIENT DESIRED
9400      NCYSHT=50000
9500      NCYSUP=5
9600      NCYSTP=50000
9700      NCYSHS=50000
9800      C
9900      C      CALCULATED INPUT
10000     PSHTMX=CYCLPR+1.0
10100     PSHTMN=CYCLPR-1.0
10200     IF (NONENG .EQ. 0) N=12
10300     REF=(TOL1+TOL2)/2.0
10400     RWHELM=RWHEEL/100.0
10500     ITRMAX=NPTPCY*NUMBCY+1
10600     ISUPST=NCYSUP*NPTPCY+1

10700     ISHTST=NCYSHT*NPTPCY+1
10800     ISPSTP=NCYSTP*NPTPCY+1
10900     ISHSTP=NCYSHS*NPTPCY+1
11000     RSHTCT=RSHT
11100     RSHTT=ASHTT/RSHTCT
11200     AIE=0.0
11300     WTWHEL=WTWHEL*4.0
11400     AIWHEL=(WTWHEL/2.0)*(RWHELM**2+(RWHELM/2.0)**2)
11500     AIVEH=WTCAR*RWHELM**2
11600     CALL ICSTUP
11700     STOP
11800     END

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TABLE XVI. - SAMPLE OUTPUT FOR SUPPLY TRANSIENT (100 POINTS/CYCLE)

## STIRLING ENGINE FOUR CYLINDER, THREE VOLUMES PER CYLINDER, CONTROLS MODEL

| RUN CONDITIONS FOR THIS TRANSIENT |        |                 |       |                |       |          |       |             |       |                  |       |
|-----------------------------------|--------|-----------------|-------|----------------|-------|----------|-------|-------------|-------|------------------|-------|
| TWH = 978.0                       |        | TWC = 359.0     |       | CYCLPR = 5.000 |       | NONENG = |       | 1           |       | NUMBCY = 1000    |       |
| ALEAK = 0.0000                    |        | ARLEAK = 0.0000 |       | PSOURC = 10.00 |       | ISUPST = |       | 501         |       | ISHTST = 5000001 |       |
| TIME                              | POWERT | PFRICT          | PAUX  | PRRF           | PDRAG | PLOAD    | PENG  | PNET        | ITRAN | PAVEMP           |       |
| POSDEG                            | TORQT  | TFRICT          | TAUX  | TRRF           | TDRAG | TLOAD    | TENG  | TNET        | KWORK | SPDRPM           | VKPH  |
| 0.0000                            | 0.0000 | 3.201           | 2.108 | 2.531          | 2.359 | 4.890    | 5.309 | -10.20      | 1     | 4.93             |       |
| 270.0                             | 52.25  | 15.29           | 10.07 | 12.09          | 11.26 | 23.35    | 25.35 | 3.543       | 1     | 2000.00          | 60.56 |
| 0.3000E-01                        | 10.67  | 3.221           | 2.108 | 2.531          | 2.360 | 4.891    | 5.329 | 0.3469      | 101   | 5.00             |       |
| 270.0                             | 48.84  | 15.38           | 10.07 | 12.09          | 11.27 | 23.35    | 25.45 | 0.4489E-01  | 101   | 2000.06          | 60.56 |
| 0.6000E-01                        | 10.67  | 3.234           | 2.108 | 2.531          | 2.360 | 4.891    | 5.342 | 0.3330      | 201   | 5.00             |       |
| 270.0                             | 48.85  | 15.44           | 10.07 | 12.09          | 11.27 | 23.35    | 25.51 | -0.9811E-02 | 101   | 2000.12          | 60.56 |
| 0.8999E-01                        | 10.67  | 3.298           | 2.108 | 2.531          | 2.360 | 4.891    | 5.407 | 0.2684      | 301   | 5.00             |       |
| 270.0                             | 48.86  | 15.75           | 10.07 | 12.09          | 11.27 | 23.35    | 25.82 | -0.3075     | 101   | 2000.17          | 60.56 |
| 0.1200                            | 10.67  | 3.264           | 2.108 | 2.531          | 2.360 | 4.891    | 5.372 | 0.3022      | 401   | 5.00             |       |
| 270.0                             | 48.85  | 15.59           | 10.07 | 12.09          | 11.27 | 23.35    | 25.65 | -0.1534     | 101   | 2000.23          | 60.56 |
| 0.1500                            | 10.67  | 3.215           | 2.108 | 2.531          | 2.360 | 4.892    | 5.323 | 0.3522      | 501   | 5.00             |       |
| 270.0                             | 48.99  | 15.35           | 10.07 | 12.09          | 11.27 | 23.35    | 25.41 | 0.2215      | 101   | 2000.29          | 60.57 |
| 0.1800                            | 11.38  | 3.245           | 2.108 | 2.532          | 2.361 | 4.892    | 5.354 | 1.028       | 601   | 5.05             |       |
| 270.0                             | 50.14  | 15.49           | 10.07 | 12.09          | 11.27 | 23.36    | 25.56 | 1.221       | 101   | 2000.45          | 60.57 |
| 0.2100                            | 11.61  | 3.328           | 2.109 | 2.532          | 2.362 | 4.893    | 5.436 | 1.177       | 701   | 5.17             |       |
| 270.0                             | 51.30  | 15.89           | 10.07 | 12.09          | 11.27 | 23.36    | 25.95 | 1.994       | 101   | 2000.64          | 60.58 |
| 0.2399                            | 11.84  | 3.344           | 2.109 | 2.532          | 2.362 | 4.894    | 5.453 | 1.384       | 801   | 5.29             |       |
| 270.0                             | 52.41  | 15.96           | 10.07 | 12.09          | 11.27 | 23.36    | 26.03 | 3.023       | 101   | 2000.85          | 60.58 |
| 0.2699                            | 12.06  | 3.343           | 2.109 | 2.532          | 2.363 | 4.896    | 5.452 | 1.599       | 901   | 5.40             |       |
| 270.0                             | 53.45  | 15.96           | 10.07 | 12.09          | 11.28 | 23.36    | 26.02 | 4.066       | 101   | 2001.09          | 60.59 |
| 0.2999                            | 12.27  | 3.395           | 2.109 | 2.533          | 2.364 | 4.897    | 5.505 | 1.753       | 1001  | 5.51             |       |
| 270.0                             | 54.48  | 16.20           | 10.07 | 12.09          | 11.28 | 23.37    | 26.27 | 4.850       | 101   | 2001.35          | 60.60 |
| 0.3299                            | 12.47  | 3.478           | 2.110 | 2.533          | 2.365 | 4.898    | 5.588 | 1.870       | 1101  | 5.62             |       |
| 270.0                             | 55.50  | 16.59           | 10.07 | 12.09          | 11.28 | 23.37    | 26.66 | 5.468       | 101   | 2001.64          | 60.61 |
| 0.3598                            | 12.67  | 3.498           | 2.110 | 2.533          | 2.366 | 4.900    | 5.608 | 2.041       | 1201  | 5.72             |       |
| 270.0                             | 56.43  | 16.69           | 10.07 | 12.09          | 11.29 | 23.37    | 26.76 | 6.305       | 101   | 2001.94          | 60.62 |
| 0.3898                            | 12.86  | 3.478           | 2.110 | 2.534          | 2.367 | 4.901    | 5.588 | 2.246       | 1301  | 5.81             |       |
| 270.0                             | 57.36  | 16.59           | 10.07 | 12.09          | 11.29 | 23.38    | 26.65 | 7.325       | 101   | 2002.28          | 60.63 |
| 0.4198                            | 13.04  | 3.524           | 2.111 | 2.534          | 2.369 | 4.903    | 5.635 | 2.378       | 1401  | 5.91             |       |
| 270.0                             | 58.24  | 16.80           | 10.07 | 12.09          | 11.29 | 23.38    | 26.87 | 7.992       | 101   | 2002.63          | 60.64 |

|                 |                |                |                |                |                |                |                |                |             |                 |       |
|-----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|-------------|-----------------|-------|
| 0.4497<br>270.0 | 13.21<br>59.09 | 3.609<br>17.21 | 2.111<br>10.07 | 2.535<br>12.09 | 2.370<br>11.30 | 4.905<br>23.38 | 5.720<br>27.28 | 2.464<br>8.432 | 1501<br>101 | 6.00<br>2003.01 | 60.65 |
| 0.4797<br>270.0 | 13.38<br>59.91 | 3.631<br>17.31 | 2.112<br>10.07 | 2.535<br>12.09 | 2.371<br>11.30 | 4.907<br>23.39 | 5.742<br>27.37 | 2.608<br>9.151 | 1601<br>101 | 6.09<br>2003.40 | 60.66 |
| 0.5096<br>270.0 | 13.54<br>60.72 | 3.595<br>17.13 | 2.112<br>10.07 | 2.536<br>12.09 | 2.373<br>11.31 | 4.909<br>23.39 | 5.707<br>27.20 | 2.802<br>10.12 | 1701<br>101 | 6.17<br>2003.81 | 60.67 |
| 0.5396<br>270.0 | 13.70<br>61.51 | 3.647<br>17.38 | 2.113<br>10.07 | 2.536<br>12.09 | 2.374<br>11.31 | 4.911<br>23.40 | 5.759<br>27.44 | 2.903<br>10.67 | 1801<br>101 | 6.25<br>2004.24 | 60.69 |
| 0.5695<br>270.0 | 13.85<br>62.25 | 3.724<br>17.74 | 2.113<br>10.07 | 2.537<br>12.09 | 2.376<br>11.32 | 4.913<br>23.40 | 5.837<br>27.81 | 2.973<br>11.03 | 1901<br>101 | 6.33<br>2004.69 | 60.70 |
| 0.5994<br>270.0 | 14.00<br>62.94 | 3.738<br>17.81 | 2.113<br>10.07 | 2.538<br>12.09 | 2.378<br>11.32 | 4.915<br>23.41 | 5.852<br>27.87 | 3.100<br>11.66 | 2001<br>101 | 6.40<br>2005.15 | 60.71 |
| 0.6293<br>270.0 | 14.14<br>63.66 | 3.700<br>17.62 | 2.114<br>10.07 | 2.538<br>12.09 | 2.379<br>11.33 | 4.917<br>23.41 | 5.814<br>27.69 | 3.275<br>12.56 | 2101<br>101 | 6.48<br>2005.64 | 60.73 |
| 0.6592<br>270.0 | 14.28<br>64.32 | 3.748<br>17.84 | 2.115<br>10.07 | 2.539<br>12.09 | 2.381<br>11.33 | 4.920<br>23.42 | 5.862<br>27.91 | 3.359<br>12.99 | 2201<br>101 | 6.55<br>2006.13 | 60.74 |
| 0.6891<br>270.0 | 14.41<br>64.96 | 3.822<br>18.19 | 2.115<br>10.07 | 2.539<br>12.09 | 2.383<br>11.34 | 4.922<br>23.43 | 5.938<br>28.26 | 3.411<br>13.27 | 2301<br>101 | 6.61<br>2006.65 | 60.76 |
| 0.7190<br>270.0 | 14.53<br>65.57 | 3.816<br>18.16 | 2.116<br>10.07 | 2.540<br>12.09 | 2.385<br>11.35 | 4.925<br>23.43 | 5.931<br>28.22 | 3.539<br>13.92 | 2401<br>101 | 6.68<br>2007.17 | 60.77 |
| 0.7489<br>270.0 | 14.65<br>66.17 | 3.790<br>18.03 | 2.116<br>10.07 | 2.541<br>12.09 | 2.387<br>11.35 | 4.927<br>23.44 | 5.906<br>28.10 | 3.682<br>14.64 | 2501<br>101 | 6.74<br>2007.71 | 60.79 |
| 0.7788<br>270.0 | 14.77<br>66.74 | 3.833<br>18.23 | 2.117<br>10.07 | 2.541<br>12.09 | 2.389<br>11.36 | 4.930<br>23.44 | 5.950<br>28.30 | 3.751<br>15.00 | 2601<br>101 | 6.80<br>2008.27 | 60.81 |
| 0.8087<br>270.0 | 14.88<br>67.29 | 3.907<br>18.57 | 2.117<br>10.07 | 2.542<br>12.09 | 2.391<br>11.36 | 4.933<br>23.45 | 6.024<br>28.64 | 3.786<br>15.20 | 2701<br>101 | 6.86<br>2008.84 | 60.82 |
| 0.8385<br>270.0 | 14.99<br>67.83 | 3.894<br>18.51 | 2.118<br>10.07 | 2.543<br>12.09 | 2.393<br>11.37 | 4.936<br>23.46 | 6.013<br>28.58 | 3.902<br>15.79 | 2801<br>101 | 6.92<br>2009.41 | 60.84 |
| 0.8684<br>270.0 | 15.10<br>68.32 | 3.865<br>18.37 | 2.119<br>10.07 | 2.544<br>12.09 | 2.395<br>11.38 | 4.939<br>23.46 | 5.984<br>28.43 | 4.031<br>16.42 | 2901<br>101 | 6.97<br>2010.01 | 60.86 |
| 0.8982<br>270.0 | 15.20<br>68.85 | 3.909<br>18.57 | 2.119<br>10.07 | 2.544<br>12.09 | 2.397<br>11.38 | 4.942<br>23.47 | 6.029<br>28.64 | 4.084<br>16.74 | 3001<br>101 | 7.03<br>2010.61 | 60.88 |
| 0.9281<br>270.0 | 15.30<br>69.32 | 3.981<br>18.90 | 2.120<br>10.07 | 2.545<br>12.09 | 2.399<br>11.39 | 4.944<br>23.48 | 6.101<br>28.97 | 4.105<br>16.87 | 3101<br>101 | 7.08<br>2011.23 | 60.90 |
| 0.9579<br>270.0 | 15.39<br>69.78 | 3.972<br>18.85 | 2.121<br>10.07 | 2.546<br>12.09 | 2.402<br>11.40 | 4.947<br>23.48 | 6.092<br>28.92 | 4.204<br>17.37 | 3201<br>101 | 7.12<br>2011.85 | 60.92 |
| 0.9877<br>270.0 | 15.48<br>70.22 | 3.937<br>18.69 | 2.121<br>10.07 | 2.547<br>12.09 | 2.404<br>11.41 | 4.951<br>23.49 | 6.059<br>28.75 | 4.324<br>17.97 | 3301<br>101 | 7.17<br>2012.49 | 60.94 |

TABLE XVI. - Continued.

|                |                |                |                |                |                |                |                |                |             |                 |       |
|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|-------------|-----------------|-------|
| 1.017<br>270.0 | 15.57<br>70.64 | 3.977<br>18.87 | 2.122<br>10.07 | 2.548<br>12.09 | 2.406<br>11.41 | 4.954<br>23.50 | 6.099<br>28.93 | 4.367<br>18.21 | 3401<br>101 | 7.22<br>2013.14 | 60.95 |
| 1.047<br>270.0 | 15.65<br>71.05 | 4.049<br>19.20 | 2.123<br>10.07 | 2.548<br>12.09 | 2.408<br>11.42 | 4.957<br>23.51 | 6.172<br>29.27 | 4.374<br>18.28 | 3501<br>101 | 7.26<br>2013.79 | 60.97 |
| 1.077<br>270.0 | 15.73<br>71.45 | 4.036<br>19.14 | 2.123<br>10.07 | 2.549<br>12.09 | 2.411<br>11.43 | 4.960<br>23.51 | 6.160<br>29.20 | 4.463<br>18.73 | 3601<br>101 | 7.30<br>2014.45 | 60.99 |
| 1.107<br>270.0 | 15.81<br>71.81 | 3.995<br>18.93 | 2.124<br>10.07 | 2.550<br>12.09 | 2.413<br>11.44 | 4.963<br>23.52 | 6.119<br>29.00 | 4.578<br>19.28 | 3701<br>101 | 7.34<br>2015.13 | 61.02 |
| 1.136<br>270.0 | 15.89<br>72.21 | 4.035<br>19.12 | 2.125<br>10.07 | 2.551<br>12.09 | 2.416<br>11.44 | 4.967<br>23.53 | 6.160<br>29.18 | 4.608<br>19.50 | 3801<br>101 | 7.38<br>2015.81 | 61.04 |
| 1.166<br>270.0 | 15.96<br>72.56 | 4.105<br>19.44 | 2.126<br>10.07 | 2.552<br>12.09 | 2.418<br>11.45 | 4.970<br>23.54 | 6.231<br>29.51 | 4.606<br>19.51 | 3901<br>101 | 7.42<br>2016.50 | 61.06 |
| 1.196<br>270.0 | 16.03<br>72.91 | 4.115<br>19.48 | 2.126<br>10.07 | 2.553<br>12.09 | 2.421<br>11.46 | 4.973<br>23.55 | 6.242<br>29.55 | 4.660<br>19.81 | 4001<br>101 | 7.46<br>2017.19 | 61.08 |
| 1.226<br>270.0 | 16.10<br>73.23 | 4.053<br>19.18 | 2.127<br>10.07 | 2.554<br>12.09 | 2.423<br>11.47 | 4.977<br>23.55 | 6.180<br>29.25 | 4.786<br>20.43 | 4101<br>101 | 7.49<br>2017.90 | 61.10 |
| 1.255<br>270.0 | 16.16<br>73.55 | 4.089<br>19.35 | 2.128<br>10.07 | 2.555<br>12.09 | 2.426<br>11.48 | 4.980<br>23.56 | 6.217<br>29.41 | 4.810<br>20.57 | 4201<br>101 | 7.53<br>2018.61 | 61.12 |
| 1.285<br>270.0 | 16.22<br>73.85 | 4.162<br>19.68 | 2.129<br>10.07 | 2.555<br>12.09 | 2.428<br>11.48 | 4.984<br>23.57 | 6.291<br>29.75 | 4.794<br>20.53 | 4301<br>101 | 7.56<br>2019.32 | 61.14 |
| 1.315<br>270.0 | 16.28<br>74.12 | 4.165<br>19.69 | 2.130<br>10.07 | 2.556<br>12.09 | 2.431<br>11.49 | 4.987<br>23.58 | 6.294<br>29.76 | 4.846<br>20.79 | 4401<br>101 | 7.59<br>2020.04 | 61.16 |
| 1.344<br>270.0 | 16.34<br>74.43 | 4.100<br>19.38 | 2.130<br>10.07 | 2.557<br>12.09 | 2.434<br>11.50 | 4.991<br>23.59 | 6.230<br>29.45 | 4.965<br>21.40 | 4501<br>101 | 7.62<br>2020.78 | 61.19 |
| 1.374<br>270.0 | 16.40<br>74.70 | 4.133<br>19.53 | 2.131<br>10.07 | 2.558<br>12.09 | 2.436<br>11.51 | 4.995<br>23.59 | 6.264<br>29.59 | 4.983<br>21.51 | 4601<br>101 | 7.65<br>2021.52 | 61.21 |
| 1.404<br>270.0 | 16.45<br>74.95 | 4.212<br>19.89 | 2.132<br>10.07 | 2.559<br>12.09 | 2.439<br>11.52 | 4.998<br>23.60 | 6.344<br>29.96 | 4.953<br>21.39 | 4701<br>101 | 7.68<br>2022.26 | 61.23 |
| 1.433<br>270.0 | 16.50<br>75.21 | 4.213<br>19.89 | 2.133<br>10.07 | 2.560<br>12.09 | 2.442<br>11.53 | 5.002<br>23.61 | 6.346<br>29.96 | 4.999<br>21.64 | 4801<br>101 | 7.70<br>2023.00 | 61.25 |
| 1.463<br>270.0 | 16.55<br>75.45 | 4.142<br>19.55 | 2.134<br>10.07 | 2.561<br>12.09 | 2.444<br>11.53 | 5.005<br>23.62 | 6.276<br>29.62 | 5.115<br>22.21 | 4901<br>101 | 7.73<br>2023.76 | 61.28 |
| 1.492<br>270.0 | 16.60<br>75.66 | 4.161<br>19.63 | 2.134<br>10.07 | 2.562<br>12.09 | 2.447<br>11.54 | 5.009<br>23.63 | 6.295<br>29.70 | 5.139<br>22.34 | 5001<br>101 | 7.76<br>2024.52 | 61.30 |
| 1.522<br>270.0 | 16.65<br>75.92 | 4.244<br>20.01 | 2.135<br>10.07 | 2.563<br>12.09 | 2.450<br>11.55 | 5.013<br>23.64 | 6.379<br>30.08 | 5.098<br>22.20 | 5101<br>101 | 7.78<br>2025.28 | 61.32 |

|                |                |                |                |                |                |                |                |                |             |                 |       |
|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|-------------|-----------------|-------|
| 1.551<br>270.0 | 16.69<br>76.13 | 4.226<br>19.92 | 2.136<br>10.07 | 2.564<br>12.09 | 2.453<br>11.56 | 5.017<br>23.65 | 6.362<br>29.99 | 5.155<br>22.49 | 5201<br>101 | 7.80<br>2026.04 | 61.35 |
| 1.581<br>270.0 | 16.74<br>76.34 | 4.179<br>19.69 | 2.137<br>10.07 | 2.565<br>12.09 | 2.456<br>11.57 | 5.020<br>23.66 | 6.316<br>29.76 | 5.241<br>22.92 | 5301<br>101 | 7.83<br>2026.82 | 61.37 |
| 1.611<br>270.0 | 16.78<br>76.54 | 4.212<br>19.84 | 2.138<br>10.07 | 2.566<br>12.09 | 2.458<br>11.58 | 5.024<br>23.66 | 6.349<br>29.91 | 5.245<br>22.97 | 5401<br>101 | 7.85<br>2027.60 | 61.39 |
| 1.640<br>270.0 | 16.82<br>76.73 | 4.283<br>20.17 | 2.139<br>10.07 | 2.567<br>12.09 | 2.461<br>11.59 | 5.028<br>23.67 | 6.421<br>30.24 | 5.209<br>22.82 | 5501<br>101 | 7.87<br>2028.38 | 61.42 |
| 1.670<br>270.0 | 16.86<br>76.92 | 4.287<br>20.18 | 2.139<br>10.07 | 2.568<br>12.09 | 2.464<br>11.60 | 5.032<br>23.68 | 6.427<br>30.25 | 5.238<br>22.99 | 5601<br>101 | 7.89<br>2029.16 | 61.44 |
| 1.699<br>270.0 | 16.90<br>77.10 | 4.214<br>19.82 | 2.140<br>10.07 | 2.569<br>12.09 | 2.467<br>11.60 | 5.036<br>23.69 | 6.354<br>29.89 | 5.344<br>23.51 | 5701<br>101 | 7.91<br>2029.95 | 61.46 |
| 1.729<br>270.0 | 16.93<br>77.27 | 4.241<br>19.95 | 2.141<br>10.07 | 2.570<br>12.09 | 2.470<br>11.61 | 5.040<br>23.70 | 6.382<br>30.02 | 5.347<br>23.55 | 5801<br>101 | 7.93<br>2030.74 | 61.49 |
| 1.758<br>270.0 | 16.97<br>77.44 | 4.322<br>20.32 | 2.142<br>10.07 | 2.571<br>12.09 | 2.473<br>11.62 | 5.044<br>23.71 | 6.464<br>30.39 | 5.296<br>23.34 | 5901<br>101 | 7.95<br>2031.54 | 61.51 |
| 1.788<br>270.0 | 17.00<br>77.60 | 4.296<br>20.19 | 2.143<br>10.07 | 2.572<br>12.09 | 2.476<br>11.63 | 5.048<br>23.72 | 6.439<br>30.26 | 5.351<br>23.62 | 6001<br>101 | 7.96<br>2032.33 | 61.54 |
| 1.817<br>270.0 | 17.03<br>77.76 | 4.243<br>19.93 | 2.144<br>10.07 | 2.573<br>12.09 | 2.479<br>11.64 | 5.051<br>23.73 | 6.387<br>30.00 | 5.430<br>24.03 | 6101<br>101 | 7.98<br>2033.14 | 61.56 |
| 1.847<br>270.0 | 17.06<br>77.89 | 4.260<br>20.00 | 2.145<br>10.07 | 2.574<br>12.09 | 2.482<br>11.65 | 5.055<br>23.74 | 6.404<br>30.07 | 5.438<br>24.08 | 6201<br>101 | 8.00<br>2033.95 | 61.58 |
| 1.876<br>270.0 | 17.09<br>78.07 | 4.343<br>20.39 | 2.146<br>10.07 | 2.575<br>12.09 | 2.484<br>11.66 | 5.059<br>23.75 | 6.489<br>30.46 | 5.380<br>23.87 | 6301<br>101 | 8.01<br>2034.75 | 61.61 |
| 1.905<br>270.0 | 17.12<br>78.21 | 4.347<br>20.39 | 2.147<br>10.07 | 2.576<br>12.09 | 2.487<br>11.67 | 5.063<br>23.76 | 6.493<br>30.46 | 5.401<br>23.99 | 6401<br>101 | 8.03<br>2035.56 | 61.63 |
| 1.935<br>270.0 | 17.15<br>78.34 | 4.270<br>20.03 | 2.147<br>10.07 | 2.577<br>12.09 | 2.490<br>11.68 | 5.067<br>23.76 | 6.418<br>30.10 | 5.500<br>24.48 | 6501<br>101 | 8.04<br>2036.37 | 61.66 |
| 1.964<br>270.0 | 17.18<br>78.47 | 4.286<br>20.09 | 2.148<br>10.07 | 2.578<br>12.09 | 2.493<br>11.69 | 5.071<br>23.77 | 6.434<br>30.16 | 5.506<br>24.53 | 6601<br>101 | 8.06<br>2037.19 | 61.68 |
| 1.994<br>270.0 | 17.20<br>78.63 | 4.369<br>20.47 | 2.149<br>10.07 | 2.579<br>12.09 | 2.496<br>11.70 | 5.075<br>23.78 | 6.518<br>30.54 | 5.444<br>24.30 | 6701<br>101 | 8.07<br>2038.01 | 61.71 |
| 2.023<br>270.0 | 17.23<br>78.76 | 4.348<br>20.37 | 2.150<br>10.07 | 2.580<br>12.09 | 2.499<br>11.71 | 5.080<br>23.79 | 6.498<br>30.44 | 5.486<br>24.52 | 6801<br>101 | 8.08<br>2038.83 | 61.73 |
| 2.052<br>270.0 | 17.26<br>78.88 | 4.295<br>20.11 | 2.151<br>10.07 | 2.581<br>12.09 | 2.502<br>11.72 | 5.084<br>23.80 | 6.446<br>30.18 | 5.560<br>24.90 | 6901<br>101 | 8.10<br>2039.65 | 61.76 |
| 2.082<br>270.0 | 17.28<br>79.00 | 4.324<br>20.24 | 2.152<br>10.07 | 2.582<br>12.09 | 2.506<br>11.73 | 5.088<br>23.81 | 6.476<br>30.31 | 5.551<br>24.88 | 7001<br>101 | 8.11<br>2040.48 | 61.78 |

TABLE XVI. - Continued.

|                |                |                |                |                |                |                |                |                |              |                 |       |
|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|--------------|-----------------|-------|
| 4.703<br>270.0 | 18.39<br>84.70 | 4.888<br>22.02 | 2.243<br>10.11 | 2.683<br>12.09 | 2.810<br>12.66 | 5.493<br>24.74 | 7.131<br>32.13 | 5.590<br>27.83 | 16101<br>101 | 8.68<br>2119.95 | 64.19 |
| 4.731<br>270.0 | 18.40<br>84.74 | 4.779<br>21.52 | 2.245<br>10.11 | 2.684<br>12.09 | 2.813<br>12.67 | 5.497<br>24.75 | 7.023<br>31.63 | 5.698<br>28.36 | 16201<br>101 | 8.69<br>2120.83 | 64.22 |
| 4.760<br>270.0 | 18.40<br>84.77 | 4.670<br>21.02 | 2.246<br>10.11 | 2.685<br>12.09 | 2.817<br>12.68 | 5.502<br>24.76 | 6.915<br>31.13 | 5.807<br>28.88 | 16301<br>101 | 8.69<br>2121.72 | 64.24 |
| 4.788<br>270.0 | 18.41<br>84.82 | 4.700<br>21.15 | 2.247<br>10.11 | 2.686<br>12.09 | 2.820<br>12.69 | 5.507<br>24.77 | 6.947<br>31.26 | 5.779<br>28.79 | 16401<br>101 | 8.69<br>2122.62 | 64.27 |
| 4.816<br>270.0 | 18.42<br>84.86 | 4.787<br>21.53 | 2.248<br>10.11 | 2.687<br>12.09 | 2.824<br>12.70 | 5.511<br>24.79 | 7.035<br>31.64 | 5.691<br>28.44 | 16501<br>101 | 8.70<br>2123.51 | 64.30 |
| 4.844<br>270.0 | 18.42<br>84.90 | 4.781<br>21.49 | 2.249<br>10.11 | 2.688<br>12.09 | 2.828<br>12.71 | 5.516<br>24.80 | 7.030<br>31.60 | 5.697<br>28.50 | 16601<br>101 | 8.70<br>2124.39 | 64.32 |
| 4.872<br>270.0 | 18.43<br>84.94 | 4.683<br>21.05 | 2.250<br>10.11 | 2.690<br>12.09 | 2.831<br>12.72 | 5.521<br>24.81 | 6.933<br>31.16 | 5.794<br>28.98 | 16701<br>101 | 8.70<br>2125.29 | 64.35 |
| 4.901<br>270.0 | 18.43<br>84.99 | 4.710<br>21.16 | 2.251<br>10.11 | 2.691<br>12.09 | 2.835<br>12.73 | 5.525<br>24.82 | 6.961<br>31.27 | 5.767<br>28.90 | 16801<br>101 | 8.71<br>2126.18 | 64.38 |
| 4.929<br>270.0 | 18.44<br>85.03 | 4.800<br>21.55 | 2.252<br>10.11 | 2.692<br>12.09 | 2.838<br>12.74 | 5.530<br>24.83 | 7.052<br>31.67 | 5.677<br>28.53 | 16901<br>101 | 8.71<br>2127.07 | 64.40 |
| 4.957<br>270.0 | 18.44<br>85.07 | 4.795<br>21.52 | 2.253<br>10.11 | 2.693<br>12.09 | 2.842<br>12.75 | 5.535<br>24.84 | 7.048<br>31.63 | 5.683<br>28.60 | 17001<br>101 | 8.71<br>2127.95 | 64.43 |
| 4.985<br>270.0 | 18.45<br>85.11 | 4.695<br>21.06 | 2.254<br>10.11 | 2.694<br>12.09 | 2.845<br>12.76 | 5.539<br>24.85 | 6.949<br>31.18 | 5.784<br>29.08 | 17101<br>101 | 8.72<br>2128.85 | 64.46 |
| 5.013<br>270.0 | 18.46<br>85.15 | 4.722<br>21.18 | 2.255<br>10.11 | 2.695<br>12.09 | 2.849<br>12.77 | 5.544<br>24.86 | 6.978<br>31.29 | 5.756<br>29.00 | 17201<br>101 | 8.72<br>2129.74 | 64.49 |
| 5.041<br>270.0 | 18.46<br>85.19 | 4.810<br>21.56 | 2.256<br>10.11 | 2.696<br>12.09 | 2.852<br>12.78 | 5.549<br>24.87 | 7.066<br>31.67 | 5.667<br>28.65 | 17301<br>101 | 8.72<br>2130.63 | 64.51 |
| 5.069<br>270.0 | 18.47<br>85.23 | 4.806<br>21.53 | 2.257<br>10.11 | 2.697<br>12.09 | 2.856<br>12.80 | 5.553<br>24.88 | 7.063<br>31.65 | 5.671<br>28.70 | 17401<br>101 | 8.73<br>2131.51 | 64.54 |
| 5.098<br>270.0 | 18.47<br>85.27 | 4.707<br>21.08 | 2.258<br>10.12 | 2.699<br>12.09 | 2.860<br>12.81 | 5.558<br>24.89 | 6.966<br>31.20 | 5.769<br>29.18 | 17501<br>101 | 8.73<br>2132.41 | 64.57 |
| 10.00<br>270.0 | 18.98<br>91.08 | 5.188<br>21.65 | 2.462<br>10.28 | 2.896<br>12.09 | 3.535<br>14.75 | 6.432<br>26.84 | 7.650<br>31.92 | 4.703<br>32.32 | 35601<br>101 | 9.06<br>2288.65 | 69.30 |
| 10.03<br>270.0 | 18.98<br>91.09 | 5.162<br>21.53 | 2.463<br>10.28 | 2.897<br>12.09 | 3.539<br>14.76 | 6.437<br>26.85 | 7.625<br>31.81 | 4.724<br>32.44 | 35701<br>101 | 9.06<br>2289.48 | 69.32 |
| 10.05<br>270.0 | 18.98<br>91.12 | 5.173<br>21.57 | 2.465<br>10.28 | 2.898<br>12.09 | 3.543<br>14.77 | 6.441<br>26.86 | 7.637<br>31.85 | 4.710<br>32.41 | 35801<br>101 | 9.06<br>2290.30 | 69.35 |

|                |                |                |                |                |                |                |                |                |              |                 |       |
|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|--------------|-----------------|-------|
| 10.08<br>270.0 | 18.98<br>91.11 | 5.248<br>21.88 | 2.466<br>10.28 | 2.899<br>12.09 | 3.547<br>14.78 | 6.446<br>26.87 | 7.714<br>32.16 | 4.629<br>32.08 | 35901<br>101 | 9.06<br>2291.12 | 69.37 |
| 10.11<br>270.0 | 18.98<br>91.08 | 5.261<br>21.92 | 2.467<br>10.28 | 2.900<br>12.09 | 3.551<br>14.79 | 6.451<br>26.88 | 7.728<br>32.20 | 4.612<br>32.00 | 36001<br>101 | 9.06<br>2291.94 | 69.40 |
| 10.13<br>270.0 | 18.98<br>91.11 | 5.183<br>21.59 | 2.468<br>10.28 | 2.901<br>12.09 | 3.554<br>14.80 | 6.456<br>26.89 | 7.651<br>31.87 | 4.685<br>32.35 | 36101<br>101 | 9.06<br>2292.77 | 69.42 |
| 10.16<br>270.0 | 18.99<br>91.09 | 5.198<br>21.64 | 2.469<br>10.28 | 2.903<br>12.09 | 3.558<br>14.81 | 6.461<br>26.90 | 7.667<br>31.93 | 4.665<br>32.27 | 36201<br>101 | 9.07<br>2293.59 | 69.45 |
| 10.18<br>270.0 | 18.99<br>91.08 | 5.199<br>21.64 | 2.470<br>10.28 | 2.904<br>12.09 | 3.562<br>14.83 | 6.466<br>26.91 | 7.669<br>31.92 | 4.660<br>32.25 | 36301<br>101 | 9.07<br>2294.41 | 69.47 |
| 10.21<br>270.0 | 18.99<br>91.10 | 5.210<br>21.68 | 2.472<br>10.28 | 2.905<br>12.09 | 3.566<br>14.84 | 6.471<br>26.92 | 7.681<br>31.96 | 4.644<br>32.21 | 36401<br>101 | 9.07<br>2295.24 | 69.50 |
| 10.24<br>270.0 | 18.99<br>91.08 | 5.252<br>21.85 | 2.473<br>10.29 | 2.906<br>12.09 | 3.570<br>14.85 | 6.475<br>26.93 | 7.725<br>32.13 | 4.597<br>32.01 | 36501<br>101 | 9.07<br>2296.05 | 69.52 |
| 10.26<br>270.0 | 18.99<br>91.11 | 5.193<br>21.59 | 2.474<br>10.29 | 2.907<br>12.09 | 3.574<br>14.86 | 6.480<br>26.94 | 7.667<br>31.88 | 4.651<br>32.28 | 36601<br>101 | 9.07<br>2296.87 | 69.55 |
| 10.29<br>270.0 | 18.99<br>91.09 | 5.207<br>21.64 | 2.475<br>10.29 | 2.908<br>12.09 | 3.577<br>14.87 | 6.485<br>26.95 | 7.682<br>31.93 | 4.633<br>32.21 | 36701<br>101 | 9.07<br>2297.69 | 69.57 |
| 10.31<br>270.0 | 18.99<br>91.09 | 5.194<br>21.58 | 2.476<br>10.29 | 2.909<br>12.09 | 3.581<br>14.88 | 6.490<br>26.96 | 7.670<br>31.87 | 4.641<br>32.25 | 36801<br>101 | 9.07<br>2298.52 | 69.60 |
| 10.34<br>270.0 | 18.99<br>91.11 | 5.202<br>21.61 | 2.477<br>10.29 | 2.910<br>12.09 | 3.585<br>14.89 | 6.495<br>26.98 | 7.679<br>31.90 | 4.628<br>32.24 | 36901<br>101 | 9.07<br>2299.34 | 69.62 |
| 10.37<br>270.0 | 19.00<br>91.09 | 5.255<br>21.82 | 2.478<br>10.29 | 2.911<br>12.09 | 3.589<br>14.90 | 6.500<br>26.99 | 7.734<br>32.11 | 4.570<br>31.99 | 37001<br>101 | 9.07<br>2300.15 | 69.65 |
| 14.94<br>270.0 | 19.12<br>87.97 | 5.637<br>22.06 | 2.690<br>10.53 | 3.088<br>12.09 | 4.285<br>16.77 | 7.373<br>28.85 | 8.327<br>32.59 | 3.237<br>26.52 | 55101<br>101 | 9.20<br>2440.15 | 73.88 |
| 14.96<br>270.0 | 19.12<br>87.94 | 5.650<br>22.11 | 2.691<br>10.53 | 3.089<br>12.09 | 4.289<br>16.78 | 7.378<br>28.86 | 8.342<br>32.64 | 3.218<br>26.44 | 55201<br>101 | 9.20<br>2440.87 | 73.91 |
| 14.99<br>270.0 | 19.12<br>87.91 | 5.583<br>21.84 | 2.693<br>10.53 | 3.090<br>12.09 | 4.293<br>16.79 | 7.382<br>28.87 | 8.276<br>32.37 | 3.279<br>26.66 | 55301<br>101 | 9.20<br>2441.60 | 73.93 |
| 15.01<br>270.0 | 19.12<br>87.88 | 5.597<br>21.89 | 2.694<br>10.53 | 3.091<br>12.09 | 4.296<br>16.80 | 7.387<br>28.88 | 8.291<br>32.42 | 3.259<br>26.57 | 55401<br>101 | 9.20<br>2442.33 | 73.95 |
| 15.04<br>270.0 | 19.12<br>87.85 | 5.577<br>21.80 | 2.695<br>10.54 | 3.092<br>12.09 | 4.300<br>16.81 | 7.392<br>28.89 | 8.272<br>32.34 | 3.274<br>26.62 | 55501<br>101 | 9.20<br>2443.06 | 73.97 |
| 15.06<br>270.0 | 19.12<br>87.82 | 5.591<br>21.85 | 2.696<br>10.54 | 3.093<br>12.09 | 4.304<br>16.82 | 7.397<br>28.90 | 8.287<br>32.39 | 3.254<br>26.53 | 55601<br>101 | 9.20<br>2443.79 | 73.99 |
| 15.09<br>270.0 | 19.12<br>87.79 | 5.636<br>22.02 | 2.697<br>10.54 | 3.094<br>12.09 | 4.308<br>16.83 | 7.401<br>28.91 | 8.333<br>32.56 | 3.203<br>26.31 | 55701<br>101 | 9.20<br>2444.51 | 74.02 |

TABLE XVI. - Continued.

|                |                |                |                |                |                |                |                |                |              |                 |       |
|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|--------------|-----------------|-------|
| 15.11<br>270.0 | 19.12<br>87.76 | 5.595<br>21.86 | 2.698<br>10.54 | 3.094<br>12.09 | 4.311<br>16.84 | 7.406<br>28.92 | 8.294<br>32.39 | 3.239<br>26.44 | 55801<br>101 | 9.20<br>2445.14 | 74.04 |
| 15.14<br>270.0 | 19.12<br>87.73 | 5.617<br>21.93 | 2.699<br>10.54 | 3.095<br>12.09 | 4.315<br>16.85 | 7.410<br>28.93 | 8.316<br>32.47 | 3.213<br>26.32 | 55901<br>101 | 9.20<br>2445.75 | 74.05 |
| 15.16<br>270.0 | 19.12<br>87.70 | 5.589<br>21.82 | 2.700<br>10.54 | 3.096<br>12.09 | 4.318<br>16.85 | 7.414<br>28.94 | 8.289<br>32.36 | 3.236<br>26.40 | 56001<br>101 | 9.20<br>2446.36 | 74.07 |
| 15.18<br>270.0 | 19.12<br>87.67 | 5.653<br>22.06 | 2.701<br>10.54 | 3.097<br>12.09 | 4.321<br>16.86 | 7.418<br>28.95 | 8.354<br>32.61 | 3.167<br>26.11 | 56101<br>101 | 9.20<br>2446.96 | 74.09 |
| 15.21<br>270.0 | 19.12<br>87.64 | 5.666<br>22.11 | 2.702<br>10.54 | 3.097<br>12.09 | 4.324<br>16.87 | 7.422<br>28.96 | 8.369<br>32.66 | 3.149<br>26.03 | 56201<br>101 | 9.20<br>2447.57 | 74.11 |
| 15.23<br>270.0 | 19.12<br>87.62 | 5.600<br>21.85 | 2.703<br>10.55 | 3.098<br>12.09 | 4.327<br>16.88 | 7.426<br>28.97 | 8.303<br>32.39 | 3.210<br>26.26 | 56301<br>101 | 9.20<br>2448.18 | 74.13 |
| 15.26<br>270.0 | 19.12<br>87.58 | 5.614<br>21.89 | 2.704<br>10.55 | 3.099<br>12.09 | 4.331<br>16.89 | 7.430<br>28.97 | 8.318<br>32.44 | 3.192<br>26.16 | 56401<br>101 | 9.20<br>2448.80 | 74.15 |
| 15.28<br>270.0 | 19.12<br>87.55 | 5.593<br>21.81 | 2.705<br>10.55 | 3.100<br>12.09 | 4.334<br>16.90 | 7.434<br>28.98 | 8.299<br>32.36 | 3.208<br>26.21 | 56501<br>101 | 9.20<br>2449.41 | 74.16 |
| 19.81<br>269.9 | 19.13<br>82.50 | 5.890<br>21.95 | 2.900<br>10.80 | 3.244<br>12.09 | 4.966<br>18.50 | 8.210<br>30.59 | 8.790<br>32.75 | 1.958<br>19.16 | 76101<br>101 | 9.27<br>2563.11 | 77.61 |
| 19.83<br>269.9 | 19.13<br>82.49 | 5.937<br>22.12 | 2.901<br>10.81 | 3.244<br>12.09 | 4.969<br>18.51 | 8.213<br>30.60 | 8.837<br>32.92 | 1.907<br>18.97 | 76201<br>101 | 9.27<br>2563.64 | 77.62 |
| 19.86<br>269.9 | 19.13<br>82.47 | 5.895<br>21.96 | 2.902<br>10.81 | 3.245<br>12.09 | 4.972<br>18.52 | 8.217<br>30.60 | 8.797<br>32.77 | 1.943<br>19.10 | 76301<br>101 | 9.27<br>2564.17 | 77.64 |
| 19.88<br>269.9 | 19.13<br>82.45 | 5.915<br>22.03 | 2.902<br>10.81 | 3.246<br>12.09 | 4.975<br>18.52 | 8.221<br>30.61 | 8.817<br>32.83 | 1.919<br>19.01 | 76401<br>101 | 9.27<br>2564.69 | 77.66 |
| 19.90<br>269.9 | 19.13<br>82.43 | 5.887<br>21.92 | 2.903<br>10.81 | 3.246<br>12.09 | 4.978<br>18.53 | 8.224<br>30.62 | 8.790<br>32.73 | 1.942<br>19.09 | 76501<br>101 | 9.27<br>2565.22 | 77.67 |
| 19.93<br>269.9 | 19.13<br>82.42 | 5.942<br>22.12 | 2.904<br>10.81 | 3.247<br>12.09 | 4.981<br>18.54 | 8.228<br>30.63 | 8.846<br>32.93 | 1.883<br>18.86 | 76601<br>101 | 9.27<br>2565.74 | 77.69 |
| 19.95<br>269.9 | 19.13<br>82.40 | 5.961<br>22.19 | 2.905<br>10.81 | 3.248<br>12.09 | 4.984<br>18.55 | 8.232<br>30.63 | 8.867<br>33.00 | 1.859<br>18.77 | 76701<br>101 | 9.27<br>2566.26 | 77.70 |
| 19.97<br>269.9 | 19.13<br>82.39 | 5.900<br>21.95 | 2.906<br>10.81 | 3.248<br>12.09 | 4.987<br>18.55 | 8.236<br>30.64 | 8.806<br>32.77 | 1.916<br>18.98 | 76801<br>101 | 9.27<br>2566.78 | 77.72 |
| 19.99<br>269.9 | 19.13<br>82.37 | 5.914<br>22.00 | 2.907<br>10.81 | 3.249<br>12.09 | 4.990<br>18.56 | 8.239<br>30.65 | 8.821<br>32.82 | 1.897<br>18.91 | 76901<br>101 | 9.27<br>2567.31 | 77.73 |
| 20.02<br>269.9 | 19.13<br>82.35 | 5.891<br>21.91 | 2.908<br>10.82 | 3.250<br>12.09 | 4.993<br>18.57 | 8.243<br>30.66 | 8.799<br>32.73 | 1.915<br>18.97 | 77001<br>101 | 9.27<br>2567.83 | 77.75 |



|                |                |                |                |                |                |                |                |                |              |                 |       |
|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|--------------|-----------------|-------|
| 20.04<br>269.9 | 19.13<br>82.33 | 5.903<br>21.95 | 2.909<br>10.82 | 3.250<br>12.09 | 4.996<br>18.58 | 8.247<br>30.66 | 8.812<br>32.77 | 1.898<br>18.90 | 77101<br>101 | 9.27<br>2568.36 | 77.77 |
| 20.06<br>269.9 | 19.13<br>82.32 | 5.949<br>22.12 | 2.910<br>10.82 | 3.251<br>12.09 | 5.000<br>18.58 | 8.250<br>30.67 | 8.859<br>32.94 | 1.847<br>18.71 | 77201<br>101 | 9.27<br>2568.88 | 77.78 |
| 20.09<br>269.9 | 19.13<br>82.30 | 5.908<br>21.96 | 2.911<br>10.82 | 3.252<br>12.09 | 5.003<br>18.59 | 8.254<br>30.68 | 8.819<br>32.78 | 1.884<br>18.84 | 77301<br>101 | 9.27<br>2569.40 | 77.80 |
| 20.11<br>269.9 | 19.13<br>82.29 | 5.927<br>22.03 | 2.912<br>10.82 | 3.252<br>12.09 | 5.006<br>18.60 | 8.258<br>30.69 | 8.839<br>32.85 | 1.860<br>18.75 | 77401<br>101 | 9.27<br>2569.92 | 77.81 |
| 20.13<br>269.9 | 19.13<br>82.27 | 5.900<br>21.92 | 2.913<br>10.82 | 3.253<br>12.09 | 5.009<br>18.61 | 8.262<br>30.69 | 8.813<br>32.74 | 1.883<br>18.83 | 77501<br>101 | 9.27<br>2570.44 | 77.83 |
| 20.15<br>269.9 | 19.13<br>82.25 | 5.954<br>22.12 | 2.914<br>10.82 | 3.254<br>12.09 | 5.012<br>18.61 | 8.265<br>30.70 | 8.867<br>32.94 | 1.825<br>18.61 | 77601<br>101 | 9.27<br>2570.96 | 77.84 |
| 20.18<br>269.9 | 19.13<br>82.23 | 5.974<br>22.19 | 2.915<br>10.83 | 3.254<br>12.09 | 5.015<br>18.62 | 8.269<br>30.71 | 8.888<br>33.01 | 1.800<br>18.51 | 77701<br>101 | 9.27<br>2571.46 | 77.86 |
| 20.20<br>269.9 | 19.13<br>82.21 | 5.913<br>21.96 | 2.916<br>10.83 | 3.255<br>12.09 | 5.018<br>18.63 | 8.273<br>30.72 | 8.828<br>32.78 | 1.857<br>18.71 | 77801<br>101 | 9.27<br>2571.98 | 77.88 |
| 20.22<br>269.9 | 19.13<br>82.19 | 5.927<br>22.00 | 2.917<br>10.83 | 3.255<br>12.09 | 5.021<br>18.64 | 8.276<br>30.72 | 8.844<br>32.83 | 1.838<br>18.64 | 77901<br>101 | 9.27<br>2572.50 | 77.89 |
| 20.25<br>269.9 | 19.13<br>82.18 | 5.904<br>21.92 | 2.918<br>10.83 | 3.256<br>12.09 | 5.024<br>18.64 | 8.280<br>30.73 | 8.822<br>32.74 | 1.856<br>18.70 | 78001<br>101 | 9.27<br>2573.01 | 77.91 |
| 20.27<br>269.9 | 19.13<br>82.15 | 5.916<br>21.95 | 2.918<br>10.83 | 3.257<br>12.09 | 5.027<br>18.65 | 8.283<br>30.74 | 8.834<br>32.79 | 1.840<br>18.63 | 78101<br>101 | 9.27<br>2573.53 | 77.92 |
| 20.29<br>269.9 | 19.13<br>82.13 | 5.962<br>22.12 | 2.919<br>10.83 | 3.257<br>12.09 | 5.030<br>18.66 | 8.287<br>30.75 | 8.881<br>32.95 | 1.789<br>18.43 | 78201<br>101 | 9.27<br>2574.03 | 77.94 |
| 20.32<br>269.9 | 19.13<br>82.11 | 5.921<br>21.97 | 2.920<br>10.83 | 3.258<br>12.09 | 5.033<br>18.67 | 8.291<br>30.75 | 8.842<br>32.80 | 1.825<br>18.56 | 78301<br>101 | 9.27<br>2574.55 | 77.95 |
| 20.34<br>269.9 | 19.13<br>82.09 | 5.940<br>22.03 | 2.921<br>10.83 | 3.259<br>12.09 | 5.036<br>18.67 | 8.294<br>30.76 | 8.861<br>32.87 | 1.802<br>18.46 | 78401<br>101 | 9.27<br>2575.05 | 77.97 |
| 20.36<br>269.9 | 19.13<br>82.07 | 5.913<br>21.92 | 2.922<br>10.84 | 3.259<br>12.09 | 5.039<br>18.68 | 8.298<br>30.77 | 8.835<br>32.76 | 1.825<br>18.54 | 78501<br>101 | 9.27<br>2575.56 | 77.98 |
| 20.38<br>269.9 | 19.13<br>82.05 | 5.965<br>22.12 | 2.923<br>10.84 | 3.260<br>12.09 | 5.042<br>18.69 | 8.302<br>30.78 | 8.888<br>32.95 | 1.768<br>18.33 | 78601<br>101 | 9.27<br>2576.07 | 78.00 |
| 20.41<br>269.9 | 19.13<br>82.03 | 5.986<br>22.19 | 2.924<br>10.84 | 3.261<br>12.09 | 5.045<br>18.70 | 8.305<br>30.78 | 8.910<br>33.02 | 1.743<br>18.23 | 78701<br>101 | 9.27<br>2576.57 | 78.01 |
| 20.43<br>269.9 | 19.13<br>82.02 | 5.926<br>21.96 | 2.925<br>10.84 | 3.261<br>12.09 | 5.048<br>18.70 | 8.309<br>30.79 | 8.851<br>32.80 | 1.799<br>18.43 | 78801<br>101 | 9.28<br>2577.08 | 78.03 |
| 20.45<br>269.9 | 19.13<br>82.00 | 5.940<br>22.01 | 2.926<br>10.84 | 3.262<br>12.09 | 5.051<br>18.71 | 8.312<br>30.80 | 8.866<br>32.85 | 1.780<br>18.36 | 78901<br>101 | 9.28<br>2577.58 | 78.05 |

TABLE XVI. - Concluded.

|                |                |                |                |                |                |                |                |                |              |                 |       |
|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|--------------|-----------------|-------|
| 20.48<br>269.9 | 19.13<br>81.98 | 5.917<br>21.92 | 2.927<br>10.84 | 3.263<br>12.09 | 5.053<br>18.72 | 8.316<br>30.80 | 8.844<br>32.76 | 1.799<br>18.41 | 79001<br>101 | 9.28<br>2578.08 | 78.06 |
| 20.50<br>269.9 | 19.13<br>81.96 | 5.928<br>21.96 | 2.928<br>10.84 | 3.263<br>12.09 | 5.056<br>18.73 | 8.320<br>30.81 | 8.856<br>32.80 | 1.783<br>18.34 | 79101<br>101 | 9.28<br>2578.59 | 78.08 |
| 20.52<br>269.9 | 19.13<br>81.94 | 5.975<br>22.12 | 2.929<br>10.84 | 3.264<br>12.09 | 5.059<br>18.73 | 8.323<br>30.82 | 8.903<br>32.97 | 1.732<br>18.15 | 79201<br>101 | 9.28<br>2579.09 | 78.09 |
| 20.54<br>269.9 | 19.13<br>81.92 | 5.934<br>21.97 | 2.929<br>10.85 | 3.264<br>12.09 | 5.062<br>18.74 | 8.327<br>30.83 | 8.863<br>32.82 | 1.768<br>18.28 | 79301<br>101 | 9.28<br>2579.59 | 78.11 |
| 20.57<br>269.9 | 19.13<br>81.91 | 5.953<br>22.03 | 2.930<br>10.85 | 3.265<br>12.09 | 5.065<br>18.75 | 8.330<br>30.83 | 8.883<br>32.88 | 1.745<br>18.19 | 79401<br>101 | 9.28<br>2580.09 | 78.12 |
| 20.59<br>269.9 | 19.13<br>81.90 | 5.925<br>21.93 | 2.931<br>10.85 | 3.266<br>12.09 | 5.068<br>18.75 | 8.334<br>30.84 | 8.857<br>32.78 | 1.768<br>18.28 | 79501<br>101 | 9.28<br>2580.59 | 78.14 |
| 20.61<br>269.9 | 19.13<br>81.89 | 5.977<br>22.11 | 2.932<br>10.85 | 3.266<br>12.09 | 5.071<br>18.76 | 8.338<br>30.85 | 8.909<br>32.96 | 1.712<br>18.08 | 79601<br>101 | 9.28<br>2581.09 | 78.15 |
| 20.64<br>269.9 | 19.13<br>81.87 | 5.998<br>22.19 | 2.933<br>10.85 | 3.267<br>12.09 | 5.074<br>18.77 | 8.341<br>30.86 | 8.931<br>33.04 | 1.687<br>17.98 | 79701<br>101 | 9.28<br>2581.60 | 78.17 |
| 20.66<br>269.9 | 19.13<br>81.86 | 5.938<br>21.96 | 2.934<br>10.85 | 3.268<br>12.09 | 5.077<br>18.78 | 8.345<br>30.86 | 8.872<br>32.82 | 1.742<br>18.18 | 79801<br>101 | 9.28<br>2582.10 | 78.18 |
| 20.68<br>269.9 | 19.13<br>81.84 | 5.952<br>22.01 | 2.935<br>10.85 | 3.268<br>12.09 | 5.080<br>18.78 | 8.348<br>30.87 | 8.887<br>32.87 | 1.723<br>18.11 | 79901<br>101 | 9.28<br>2582.60 | 78.20 |
| 20.70<br>269.9 | 19.13<br>81.83 | 5.930<br>21.92 | 2.936<br>10.85 | 3.269<br>12.09 | 5.083<br>18.79 | 8.352<br>30.88 | 8.865<br>32.78 | 1.742<br>18.17 | 80001<br>101 | 9.28<br>2583.10 | 78.21 |
| 20.73<br>269.9 | 19.13<br>81.81 | 5.941<br>21.96 | 2.937<br>10.86 | 3.270<br>12.09 | 5.086<br>18.80 | 8.356<br>30.88 | 8.878<br>32.82 | 1.726<br>18.11 | 80101<br>101 | 9.28<br>2583.60 | 78.23 |
| 20.75<br>269.9 | 19.13<br>81.80 | 5.987<br>22.13 | 2.938<br>10.86 | 3.270<br>12.09 | 5.089<br>18.81 | 8.359<br>30.89 | 8.924<br>32.98 | 1.676<br>17.92 | 80201<br>101 | 9.28<br>2584.10 | 78.24 |
| 20.77<br>269.9 | 19.13<br>81.78 | 5.947<br>21.97 | 2.939<br>10.86 | 3.271<br>12.09 | 5.092<br>18.81 | 8.363<br>30.90 | 8.885<br>32.83 | 1.711<br>18.05 | 80301<br>101 | 9.28<br>2584.61 | 78.26 |

OVER TIME LIMIT

CPU TIME= 20.00 MINUTES.

TABLE XVII. - SAMPLE OUTPUT FOR SUPPLY TRANSIENT (25 POINTS/CYCLE)

STIRLING ENGINE FOUR CYLINDER, THREE VOLUMES PER CYLINDER CONTROLS MODEL

| RUN CONDITIONS FOR THIS TRANSIENT |        | TWC = 359.0     |       | CYCLPR = 5.000 | NONENG = 1   |       | NUMBCY = 1000 |             |       |         |       |
|-----------------------------------|--------|-----------------|-------|----------------|--------------|-------|---------------|-------------|-------|---------|-------|
| TWH = 978.0                       |        | ARLEAK = 0.0000 |       | PSOURC = 10.00 | ISUPST = 126 |       | ISHTST =      | 1250001     |       |         |       |
| TIME                              | POWERT | PFRICT          | PAUX  | PRRF           | PDRAG        | PLOAD | PENG          | PNET        | ITRAN | PAVEMP  | VKPH  |
| POSDEG                            | TORQT  | TFRICT          | TAUX  | TTRF           | TDRAG        | TLOAD | TENG          | TNET        | KWORK | SPDRPM  |       |
| 0.0000                            | 0.0000 | 3.201           | 2.108 | 2.531          | 2.359        | 4.890 | 5.309         | -10.20      | 1     | 4.93    |       |
| 270.0                             | 52.25  | 15.29           | 10.07 | 12.09          | 11.26        | 23.35 | 25.35         | 3.543       | 1     | 2000.00 | 60.56 |
| 0.1200                            | 10.55  | 3.214           | 2.108 | 2.531          | 2.360        | 4.892 | 5.322         | -0.8021E-01 | 101   | 5.00    |       |
| 270.2                             | 48.78  | 15.35           | 10.07 | 12.09          | 11.27        | 23.35 | 25.41         | 0.1758E-01  | 26    | 2000.25 | 60.56 |
| 0.2400                            | 11.71  | 3.310           | 2.109 | 2.532          | 2.362        | 4.895 | 5.419         | 0.9541      | 201   | 5.29    |       |
| 270.2                             | 52.68  | 15.80           | 10.07 | 12.09          | 11.27        | 23.36 | 25.87         | 3.450       | 26    | 2000.89 | 60.58 |
| 0.3599                            | 12.52  | 3.464           | 2.110 | 2.534          | 2.366        | 4.900 | 5.574         | 1.576       | 301   | 5.72    |       |
| 270.2                             | 56.56  | 16.52           | 10.07 | 12.09          | 11.29        | 23.37 | 26.59         | 6.593       | 26    | 2002.01 | 60.62 |
| 0.4797                            | 13.23  | 3.573           | 2.112 | 2.535          | 2.372        | 4.907 | 5.685         | 2.133       | 401   | 6.09    |       |
| 270.2                             | 59.92  | 17.03           | 10.07 | 12.09          | 11.30        | 23.39 | 27.10         | 9.436       | 26    | 2003.49 | 60.66 |
| 0.5995                            | 13.84  | 3.676           | 2.114 | 2.538          | 2.378        | 4.916 | 5.790         | 2.601       | 501   | 6.40    |       |
| 270.2                             | 62.85  | 17.51           | 10.07 | 12.09          | 11.32        | 23.41 | 27.58         | 11.86       | 26    | 2005.26 | 60.72 |
| 0.7191                            | 14.36  | 3.783           | 2.116 | 2.540          | 2.385        | 4.925 | 5.898         | 2.986       | 601   | 6.68    |       |
| 270.2                             | 65.40  | 18.00           | 10.07 | 12.09          | 11.35        | 23.43 | 28.06         | 13.90       | 26    | 2007.30 | 60.78 |
| 0.8386                            | 14.82  | 3.849           | 2.118 | 2.543          | 2.393        | 4.936 | 5.968         | 3.340       | 701   | 6.91    |       |
| 270.2                             | 67.62  | 18.29           | 10.07 | 12.09          | 11.37        | 23.46 | 28.36         | 15.80       | 26    | 2009.56 | 60.85 |
| 0.9579                            | 15.21  | 3.923           | 2.121 | 2.546          | 2.402        | 4.948 | 6.044         | 3.627       | 801   | 7.12    |       |
| 270.2                             | 69.55  | 18.62           | 10.07 | 12.09          | 11.40        | 23.49 | 28.69         | 17.37       | 26    | 2012.01 | 60.92 |
| 1.077                             | 15.54  | 3.983           | 2.124 | 2.549          | 2.411        | 4.961 | 6.106         | 3.874       | 901   | 7.30    |       |
| 270.2                             | 71.22  | 18.88           | 10.07 | 12.09          | 11.43        | 23.52 | 28.95         | 18.75       | 26    | 2014.63 | 61.00 |
| 1.196                             | 15.84  | 4.038           | 2.127 | 2.553          | 2.421        | 4.974 | 6.165         | 4.082       | 1001  | 7.45    |       |
| 270.2                             | 72.68  | 19.12           | 10.07 | 12.09          | 11.46        | 23.55 | 29.18         | 19.95       | 26    | 2017.38 | 61.08 |
| 1.315                             | 16.09  | 4.087           | 2.130 | 2.557          | 2.432        | 4.988 | 6.216         | 4.256       | 1101  | 7.58    |       |
| 270.2                             | 73.93  | 19.32           | 10.07 | 12.09          | 11.49        | 23.58 | 29.39         | 20.96       | 26    | 2020.26 | 61.17 |
| 1.434                             | 16.30  | 4.130           | 2.133 | 2.560          | 2.442        | 5.003 | 6.263         | 4.403       | 1201  | 7.70    |       |
| 270.2                             | 75.04  | 19.49           | 10.07 | 12.09          | 11.53        | 23.61 | 29.56         | 21.87       | 26    | 2023.23 | 61.26 |
| 1.552                             | 16.49  | 4.168           | 2.136 | 2.564          | 2.454        | 5.018 | 6.305         | 4.525       | 1301  | 7.80    |       |
| 270.2                             | 75.97  | 19.65           | 10.07 | 12.09          | 11.56        | 23.65 | 29.72         | 22.61       | 26    | 2026.29 | 61.35 |
| 1.670                             | 16.65  | 4.206           | 2.140 | 2.568          | 2.465        | 5.033 | 6.345         | 4.623       | 1401  | 7.88    |       |
| 270.2                             | 76.82  | 19.79           | 10.07 | 12.09          | 11.60        | 23.68 | 29.86         | 23.27       | 26    | 2029.42 | 61.45 |

TABLE XVII. - Continued.

|                |                |                |                |                |                |                |                |                |            |                 |       |
|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|------------|-----------------|-------|
| 1.789<br>270.2 | 16.79<br>77.52 | 4.257<br>20.00 | 2.143<br>10.07 | 2.572<br>12.09 | 2.477<br>11.64 | 5.049<br>23.72 | 6.400<br>30.07 | 4.685<br>23.73 | 1501<br>26 | 7.96<br>2032.61 | 61.54 |
| 1.906<br>270.2 | 16.91<br>78.10 | 4.261<br>19.99 | 2.147<br>10.07 | 2.576<br>12.09 | 2.488<br>11.67 | 5.065<br>23.76 | 6.408<br>30.06 | 4.775<br>24.28 | 1601<br>26 | 8.02<br>2035.85 | 61.64 |
| 2.024<br>270.2 | 17.02<br>78.67 | 4.286<br>20.08 | 2.150<br>10.07 | 2.580<br>12.09 | 2.501<br>11.71 | 5.081<br>23.80 | 6.437<br>30.15 | 4.832<br>24.73 | 1701<br>26 | 8.08<br>2039.13 | 61.74 |
| 2.142<br>270.2 | 17.11<br>79.20 | 4.310<br>20.15 | 2.154<br>10.07 | 2.585<br>12.09 | 2.513<br>11.75 | 5.097<br>23.83 | 6.464<br>30.23 | 4.881<br>25.14 | 1801<br>26 | 8.13<br>2042.45 | 61.84 |
| 2.259<br>270.2 | 17.20<br>79.66 | 4.374<br>20.42 | 2.158<br>10.07 | 2.589<br>12.09 | 2.525<br>11.79 | 5.114<br>23.87 | 6.532<br>30.49 | 4.879<br>25.30 | 1901<br>26 | 8.17<br>2045.80 | 61.94 |
| 2.376<br>270.2 | 17.28<br>80.14 | 4.352<br>20.28 | 2.162<br>10.07 | 2.593<br>12.09 | 2.538<br>11.83 | 5.131<br>23.91 | 6.514<br>30.36 | 4.957<br>25.87 | 2001<br>26 | 8.21<br>2049.18 | 62.05 |
| 2.493<br>270.2 | 17.36<br>80.54 | 4.376<br>20.36 | 2.165<br>10.08 | 2.598<br>12.09 | 2.550<br>11.87 | 5.148<br>23.95 | 6.541<br>30.43 | 4.983<br>26.16 | 2101<br>26 | 8.25<br>2052.59 | 62.15 |
| 2.610<br>270.2 | 17.42<br>80.94 | 4.392<br>20.40 | 2.169<br>10.08 | 2.602<br>12.09 | 2.563<br>11.90 | 5.165<br>23.99 | 6.561<br>30.48 | 5.011<br>26.47 | 2201<br>26 | 8.29<br>2056.01 | 62.25 |
| 2.727<br>270.2 | 17.49<br>81.29 | 4.409<br>20.45 | 2.173<br>10.08 | 2.606<br>12.09 | 2.576<br>11.94 | 5.182<br>24.03 | 6.582<br>30.52 | 5.032<br>26.74 | 2301<br>26 | 8.32<br>2059.47 | 62.36 |
| 2.843<br>270.2 | 17.54<br>81.63 | 4.430<br>20.51 | 2.177<br>10.08 | 2.611<br>12.09 | 2.589<br>11.98 | 5.200<br>24.07 | 6.607<br>30.59 | 5.046<br>26.97 | 2401<br>26 | 8.35<br>2062.93 | 62.46 |
| 2.959<br>270.2 | 17.60<br>81.92 | 4.443<br>20.53 | 2.181<br>10.08 | 2.615<br>12.09 | 2.602<br>12.03 | 5.217<br>24.11 | 6.624<br>30.62 | 5.063<br>27.19 | 2501<br>26 | 8.37<br>2066.41 | 62.57 |
| 3.075<br>270.2 | 17.65<br>82.21 | 4.459<br>20.58 | 2.185<br>10.08 | 2.619<br>12.09 | 2.615<br>12.07 | 5.235<br>24.15 | 6.644<br>30.66 | 5.075<br>27.40 | 2601<br>26 | 8.40<br>2069.90 | 62.67 |
| 3.191<br>270.2 | 17.70<br>82.51 | 4.476<br>20.62 | 2.189<br>10.08 | 2.624<br>12.09 | 2.629<br>12.11 | 5.253<br>24.19 | 6.665<br>30.70 | 5.082<br>27.62 | 2701<br>26 | 8.43<br>2073.41 | 62.78 |
| 3.307<br>270.2 | 17.74<br>82.83 | 4.516<br>20.77 | 2.193<br>10.08 | 2.628<br>12.09 | 2.642<br>12.15 | 5.271<br>24.23 | 6.709<br>30.85 | 5.063<br>27.74 | 2801<br>26 | 8.45<br>2076.93 | 62.89 |
| 3.422<br>270.2 | 17.79<br>83.11 | 4.527<br>20.78 | 2.197<br>10.09 | 2.633<br>12.09 | 2.656<br>12.19 | 5.288<br>24.28 | 6.724<br>30.87 | 5.072<br>27.96 | 2901<br>26 | 8.47<br>2080.45 | 62.99 |
| 3.537<br>270.2 | 17.83<br>83.37 | 4.521<br>20.72 | 2.201<br>10.09 | 2.637<br>12.09 | 2.669<br>12.23 | 5.306<br>24.32 | 6.722<br>30.81 | 5.093<br>28.24 | 3001<br>26 | 8.49<br>2083.99 | 63.10 |
| 3.652<br>270.2 | 17.87<br>83.67 | 4.558<br>20.85 | 2.205<br>10.09 | 2.642<br>12.09 | 2.683<br>12.27 | 5.325<br>24.36 | 6.764<br>30.94 | 5.069<br>28.37 | 3101<br>26 | 8.51<br>2087.53 | 63.21 |

ITERATION FAILURE 13 21  
 DEBUG OUTPUT FROM FWS3V2, FLOW CONTINUES

```

DEBUG PRINTOUT FROM FWS3V2 NUMBER 1
-1.8488522 0.67807871 1.7777653 -1.0093956
8.4473810 8.4344292 8.3919554 0.68167634E-02 0.22354629E-01 155.32368 84.119629
10.520517 10.571616 10.618118 0.16364049E-01 0.17652512E-01 95.280518 65.120804
8.3913279 8.3846169 8.4137440 0.35321091E-02-0.15330065E-01 69.150574 122.31100
6.7948027 6.7637110 6.7301712 -0.26894122E-01-0.24474800E-01 135.37712 147.19943
933.05029 670.09106 407.13184 933.05029 670.09106 407.13184
933.05029 670.09106 407.13184 933.05029 670.09106 407.13184
218.94711 3.6300240 24.396973 90.201843 34.976685 9.6353846
0.00000000 0.00000000 0.00000000 0.00000000 0.00000000 0.00000000 0.00000000 0.00000000
0.00000000 0.00000000 0.00000000 0.00000000 0.00000000 0.00000000 0.00000000 0.00000000
6.00000000 4.00000000 0.00000000 0.00000000 0.00000000 0.00000000 0.00000000 0.00000000

DEBUG PRINTOUT FROM FWS3V2 NUMBER 2
1 0.34085358E-03-0.15308842E-05 0.18807023E-05-0.68167634E-02 0.34576468E-03-0.17407069E-02-0.42787343E-02
2 0.35189348E-03 0.19668678E-05 0.15282376E-05-0.15537865E-01 0.36992598E-03-0.15878677E-01-0.15708271E-01
3 0.42028003E-03-0.36629757E-07 0.38049284E-05 0.22354629E-01 0.39727031E-03 0.17734930E-01 0.20044778E-01
4 0.26040501E-03 0.90656331E-05 0.10422764E-05 0.26894122E-01 0.22953982E-03 0.26885588E-01 0.26889853E-01
5 0.44105924E-03-0.21163014E-05 0.17917191E-05-0.24193227E-02 0.44039311E-03 0.35782866E-02 0.57948194E-03
6 0.41166646E-03-0.36774009E-05 0.47990270E-05-0.24474800E-01 0.44319732E-03-0.30463874E-01-0.27469337E-01
7 0.15074215E-03-0.11467416E-03 0.81206042E-06-0.35321091E-02 0.15737723E-03-0.80595501E-02-0.57958290E-02
8 0.34981524E-03 0.52733361E-04 0.11413758E-05 0.18862173E-01 0.32948749E-03 0.16584896E-01 0.17723534E-01
9 0.61267894E-03-0.80659611E-05 0.63257085E-05-0.15330065E-01 0.62636589E-03-0.85253455E-02-0.11927705E-01
10 0.23896278E-03-0.59822432E-05 0.99459339E-06-0.16364049E-01 0.25784690E-03-0.16540229E-01-0.16452137E-01
11 0.28218934E-03 0.13787368E-04 0.88281422E-06-0.12884624E-02 0.28549996E-03-0.44727325E-02-0.28805975E-02
12 0.58980775E-03-0.39224651E-05 0.54192342E-05 0.17652512E-01 0.56761317E-03 0.21012962E-01 0.19332737E-01
13 2.7060757 0.36422080E-06 0.82929730E-02 218.94711 2.4547462 218.94292 218.94495
14 218.94711 0.56013025E-07 15.669580 3.6300240 218.94292 3.7022800 3.6661520
3.767 17.90 4.549 2.209 2.646 2.697 5.343 6.758 5.091 3201 8.53
270.2 83.94 20.78 10.09 12.09 12.31 24.40 30.87 28.67 26 2091.08 63.31

```

```

ITERATION FAILURE 13 21
DEBUG OUTPUT FROM FWS3V2, FLOW CONTINUES
DEBUG PRINTOUT FROM FWS3V2 NUMBER 1
-1.8488550 0.67807108 1.7777700 -1.0093880
8.4564724 8.4434786 8.4009447 0.68388470E-02 0.22386253E-01 155.32376 84.119797
10.532256 10.583419 10.630010 0.16398180E-01 0.17685641E-01 95.280701 65.120743
8.4006414 8.3939114 8.4231005 0.35421478E-02-0.15362691E-01 69.150452 122.31084
6.8018503 6.7706938 6.7370911 -0.26927751E-01-0.24521481E-01 135.37694 147.19954
933.04053 670.08960 407.13867 933.04053 670.08960 407.13867
933.04053 670.08960 407.13867 933.04053 670.08960 407.13867
219.13310 3.6251764 24.417908 90.293518 34.929977 9.6353846
0.00000000 0.00000000 0.00000000 0.00000000 0.00000000 0.00000000 0.00000000 0.00000000
0.00000000 0.00000000 0.00000000 0.00000000 0.00000000 0.00000000 0.00000000 0.00000000
6.00000000 4.00000000 0.00000000 0.00000000 0.00000000 0.00000000 0.00000000 0.00000000

DEBUG PRINTOUT FROM FWS3V2 NUMBER 2
1 0.34122425E-03-0.30216620E-06 0.18827641E-05-0.68388470E-02 0.34614024E-03-0.17336798E-02-0.42862631E-02
2 0.35227183E-03 0.13753242E-05 0.15298938E-05-0.15547406E-01 0.37032505E-03-0.15932381E-01-0.15739892E-01
3 0.42072404E-03-0.25613804E-06 0.38089847E-05 0.22386253E-01 0.39768941E-03 0.17780669E-01 0.20083461E-01
4 0.26069884E-03 0.10765216E-05 0.10434396E-05 0.26927751E-01 0.22979786E-03 0.26956864E-01 0.26942305E-01
5 0.44155261E-03-0.22081795E-05 0.17937127E-05-0.24062693E-02 0.44088671E-03 0.35657398E-02 0.57973526E-03
6 0.41212025E-03 0.75434764E-06 0.48043148E-05-0.24521481E-01 0.44368673E-03-0.30522604E-01-0.27522042E-01
7 0.15091080E-03-0.10253876E-03 0.81312339E-06-0.35421478E-02 0.15755363E-03-0.80695897E-02-0.58058687E-02
8 0.35020383E-03 0.44601446E-04 0.11427246E-05 0.18904839E-01 0.32985443E-03 0.16605478E-01 0.17755158E-01
9 0.61334926E-03-0.59714303E-05 0.63330199E-05-0.15362691E-01 0.62705064E-03-0.85358880E-02-0.11949290E-01
10 0.23921287E-03-0.90203696E-06 0.99563658E-06-0.16398180E-01 0.25811652E-03-0.16565826E-01-0.16482003E-01
11 0.28248131E-03 0.13715817E-05 0.88372758E-06-0.12874603E-02 0.28579566E-03-0.44913068E-02-0.28893836E-02
12 0.59040473E-03-0.51222283E-07 0.54247266E-05 0.17685641E-01 0.56818686E-03 0.21057133E-01 0.19371387E-01
13 2.7060795 0.33993888E-06 0.79968683E-02 219.13310 2.4547501 219.12891 219.13098
14 219.13310 0.75821980E-08 15.682890 3.6251764 219.12891 3.6948719 3.6600237

```

```

ITERATION FAILURE 13 21
DEBUG OUTPUT FROM FWS3V2, FLOW CONTINUES
DEBUG PRINTOUT FROM FWS3V2 NUMBER 1
-1.8487787 0.67828947 1.7776604 -1.0095730
8.4610968 8.4481249 8.4055243 0.68273023E-02 0.22421386E-01 155.32195 84.115616
10.537929 10.589179 10.635817 0.16410727E-01 0.17707225E-01 95.275513 65.122467
8.4049740 8.3982439 8.4274426 0.35421478E-02-0.15367709E-01 69.153061 122.31578
6.8053713 6.7741909 6.7405472 -0.26973929E-01-0.24546076E-01 135.38133 147.19705
933.03564 670.08887 407.14209 933.03564 670.08887 407.14209
933.03564 670.08887 407.14209 933.03564 670.08887 407.14209
219.22597 3.6283350 24.428360 90.333954 34.960403 9.6353846
0.00000000 0.00000000 0.00000000 0.00000000 0.00000000 0.00000000 0.00000000 0.00000000
0.00000000 0.00000000 0.00000000 0.00000000 0.00000000 0.00000000 0.00000000 0.00000000
6.00000000 4.00000000 0.00000000 0.00000000 0.00000000 0.00000000 0.00000000 0.00000000

```

TABLE XVII. - Continued.

## DEBUG PRINTOUT FROM FWS3V2 NUMBER

|       |                |                |                |                |                |                |                |       |      |         |       |  |  |
|-------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|-------|------|---------|-------|--|--|
| 1     | 0.34140865E-03 | 0.22348377E-05 | 0.18837527E-05 | 0.68273023E-02 | 0.34632487E-03 | 0.17477339E-02 | 0.42875148E-02 |       |      |         |       |  |  |
| 2     | 0.35246601E-03 | 0.15709418E-06 | 0.15307351E-05 | 0.15594084E-01 | 0.37052715E-03 | 0.15913814E-01 | 0.15753947E-01 |       |      |         |       |  |  |
| 3     | 0.42092893E-03 | 0.15726409E-05 | 0.38108865E-05 | 0.22421386E-01 | 0.39788615E-03 | 0.17775830E-01 | 0.20098608E-01 |       |      |         |       |  |  |
| 4     | 0.26082643E-03 | 0.50635174E-06 | 0.10439426E-05 | 0.26973929E-01 | 0.22990997E-03 | 0.26959874E-01 | 0.26966900E-01 |       |      |         |       |  |  |
| 5     | 0.44179335E-03 | 0.33051456E-05 | 0.17946668E-05 | 0.24278536E-02 | 0.44112327E-03 | 0.35993680E-02 | 0.58575720E-03 |       |      |         |       |  |  |
| 6     | 0.41235285E-03 | 0.31140107E-05 | 0.48070524E-05 | 0.24546076E-01 | 0.44393935E-03 | 0.30559242E-01 | 0.27552657E-01 |       |      |         |       |  |  |
| 7     | 0.15099508E-03 | 0.10750498E-03 | 0.81359502E-06 | 0.35421478E-02 | 0.15764408E-03 | 0.80866553E-02 | 0.58143996E-02 |       |      |         |       |  |  |
| 8     | 0.35038497E-03 | 0.43564258E-04 | 0.11433212E-05 | 0.18909857E-01 | 0.33002486E-03 | 0.16633585E-01 | 0.17771721E-01 |       |      |         |       |  |  |
| 9     | 0.61368523E-03 | 0.54550219E-05 | 0.63364050E-05 | 0.15367709E-01 | 0.62739034E-03 | 0.85469298E-02 | 0.11957318E-01 |       |      |         |       |  |  |
| 10    | 0.23934574E-03 | 0.30426918E-05 | 0.99618319E-06 | 0.16410727E-01 | 0.25825924E-03 | 0.16585402E-01 | 0.16498063E-01 |       |      |         |       |  |  |
| 11    | 0.28262753E-03 | 0.90044668E-05 | 0.88419540E-06 | 0.12964979E-02 | 0.28594467E-03 | 0.44857822E-02 | 0.28911401E-02 |       |      |         |       |  |  |
| 12    | 0.59069274E-03 | 0.27902615E-05 | 0.54273296E-05 | 0.17707225E-01 | 0.56846230E-03 | 0.21071184E-01 | 0.19389205E-01 |       |      |         |       |  |  |
| 13    | 2.7059689      | 0.33995417E-06 | 0.60149133E-02 | 219.22597      | 2.4546394      | 219.22177      | 219.22375      |       |      |         |       |  |  |
| 14    | 219.22597      | 0.18097808E-07 | 15.689538      | 3.6283350      | 219.22177      | 3.6988306      | 3.6635828      |       |      |         |       |  |  |
| 3.882 | 17.94          | 4.568          | 2.214          | 2.651          | 2.710          | 5.361          | 6.781          | 5.082 | 3301 | 8.55    |       |  |  |
| 270.2 | 84.18          | 20.83          | 10.09          | 12.09          | 12.36          | 24.44          | 30.92          | 28.82 | 26   | 2094.63 | 63.42 |  |  |

## ITERATION FAILURE

|       | 13    | 21    |       |       |       |       |       |       |      |         |       |  |  |
|-------|-------|-------|-------|-------|-------|-------|-------|-------|------|---------|-------|--|--|
| 5.130 | 18.23 | 4.702 | 2.260 | 2.700 | 2.865 | 5.566 | 6.962 | 4.974 | 4401 | 8.71    |       |  |  |
| 270.2 | 85.50 | 21.04 | 10.12 | 12.09 | 12.82 | 24.91 | 31.16 | 29.43 | 26   | 2133.85 | 64.61 |  |  |
| 5.242 | 18.25 | 4.719 | 2.265 | 2.705 | 2.880 | 5.585 | 6.983 | 4.953 | 4501 | 8.72    |       |  |  |
| 270.2 | 85.59 | 21.08 | 10.12 | 12.09 | 12.87 | 24.95 | 31.20 | 29.44 | 26   | 2137.42 | 64.72 |  |  |
| 5.354 | 18.27 | 4.725 | 2.269 | 2.709 | 2.894 | 5.604 | 6.994 | 4.942 | 4601 | 8.73    |       |  |  |
| 270.2 | 85.70 | 21.08 | 10.12 | 12.09 | 12.91 | 25.00 | 31.20 | 29.51 | 26   | 2140.97 | 64.83 |  |  |
| 5.466 | 18.28 | 4.736 | 2.273 | 2.714 | 2.909 | 5.623 | 7.010 | 4.925 | 4701 | 8.74    |       |  |  |
| 270.2 | 85.82 | 21.09 | 10.12 | 12.09 | 12.95 | 25.04 | 31.22 | 29.57 | 26   | 2144.54 | 64.93 |  |  |
| 5.578 | 18.30 | 4.753 | 2.278 | 2.718 | 2.923 | 5.642 | 7.031 | 4.901 | 4801 | 8.75    |       |  |  |
| 270.2 | 85.95 | 21.13 | 10.13 | 12.09 | 12.99 | 25.08 | 31.26 | 29.61 | 26   | 2148.09 | 65.04 |  |  |
| 5.690 | 18.32 | 4.765 | 2.282 | 2.723 | 2.938 | 5.661 | 7.047 | 4.883 | 4901 | 8.77    |       |  |  |
| 270.2 | 86.07 | 21.15 | 10.13 | 12.09 | 13.04 | 25.12 | 31.28 | 29.67 | 26   | 2151.64 | 65.15 |  |  |
| 5.801 | 18.34 | 4.815 | 2.286 | 2.727 | 2.952 | 5.680 | 7.102 | 4.825 | 5001 | 8.78    |       |  |  |
| 270.2 | 86.18 | 21.34 | 10.13 | 12.09 | 13.08 | 25.17 | 31.47 | 29.55 | 26   | 2155.19 | 65.26 |  |  |
| 5.912 | 18.35 | 4.825 | 2.291 | 2.732 | 2.967 | 5.699 | 7.116 | 4.807 | 5101 | 8.79    |       |  |  |
| 270.2 | 86.29 | 21.35 | 10.13 | 12.09 | 13.12 | 25.21 | 31.48 | 29.60 | 26   | 2158.73 | 65.36 |  |  |
| 6.023 | 18.37 | 4.798 | 2.295 | 2.736 | 2.981 | 5.718 | 7.093 | 4.825 | 5201 | 8.80    |       |  |  |
| 270.2 | 86.43 | 21.19 | 10.14 | 12.09 | 13.17 | 25.25 | 31.33 | 29.84 | 26   | 2162.27 | 65.47 |  |  |
| 6.134 | 18.38 | 4.812 | 2.300 | 2.741 | 2.996 | 5.737 | 7.111 | 4.802 | 5301 | 8.80    |       |  |  |
| 270.2 | 86.56 | 21.22 | 10.14 | 12.09 | 13.21 | 25.30 | 31.36 | 29.91 | 26   | 2165.81 | 65.58 |  |  |
| 6.245 | 18.40 | 4.820 | 2.304 | 2.745 | 3.011 | 5.756 | 7.124 | 4.783 | 5401 | 8.81    |       |  |  |
| 270.2 | 86.68 | 21.22 | 10.14 | 12.09 | 13.25 | 25.34 | 31.36 | 29.98 | 26   | 2169.33 | 65.68 |  |  |
| 6.355 | 18.41 | 4.868 | 2.308 | 2.750 | 3.025 | 5.775 | 7.176 | 4.724 | 5501 | 8.82    |       |  |  |
| 270.2 | 86.82 | 21.40 | 10.15 | 12.09 | 13.30 | 25.38 | 31.54 | 29.90 | 26   | 2172.86 | 65.79 |  |  |

|                |                |                |                |                |                |                |                |                |             |                 |       |
|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|-------------|-----------------|-------|
| 6.466<br>270.2 | 18.43<br>86.95 | 4.835<br>21.22 | 2.313<br>10.15 | 2.754<br>12.09 | 3.040<br>13.34 | 5.794<br>25.43 | 7.148<br>31.37 | 4.746<br>30.16 | 5601<br>26  | 8.83<br>2176.38 | 65.90 |
| 6.576<br>270.2 | 18.44<br>87.06 | 4.847<br>21.24 | 2.317<br>10.15 | 2.759<br>12.09 | 3.055<br>13.38 | 5.814<br>25.47 | 7.164<br>31.39 | 4.724<br>30.21 | 5701<br>26  | 8.84<br>2179.90 | 66.00 |
| 6.686<br>270.2 | 18.45<br>87.17 | 4.857<br>21.25 | 2.322<br>10.16 | 2.763<br>12.09 | 3.070<br>13.43 | 5.833<br>25.51 | 7.179<br>31.40 | 4.700<br>30.26 | 5801<br>26  | 8.85<br>2183.41 | 66.11 |
| 10.01<br>270.2 | 18.69<br>88.76 | 5.202<br>21.70 | 2.463<br>10.28 | 2.897<br>12.09 | 3.537<br>14.76 | 6.434<br>26.84 | 7.665<br>31.98 | 3.840<br>29.94 | 8901<br>26  | 9.01<br>2288.98 | 69.31 |
| 10.12<br>270.2 | 18.70<br>88.77 | 5.213<br>21.72 | 2.467<br>10.28 | 2.901<br>12.09 | 3.552<br>14.80 | 6.453<br>26.88 | 7.680<br>32.00 | 3.809<br>29.89 | 9001<br>26  | 9.01<br>2292.27 | 69.41 |
| 10.22<br>270.2 | 18.70<br>88.81 | 5.171<br>21.51 | 2.472<br>10.28 | 2.905<br>12.09 | 3.567<br>14.84 | 6.472<br>26.93 | 7.643<br>31.80 | 3.831<br>30.08 | 9101<br>26  | 9.01<br>2295.54 | 69.51 |
| 10.32<br>270.2 | 18.70<br>88.83 | 5.205<br>21.63 | 2.477<br>10.29 | 2.909<br>12.09 | 3.583<br>14.88 | 6.492<br>26.97 | 7.682<br>31.91 | 3.776<br>29.94 | 9201<br>26  | 9.02<br>2298.81 | 69.60 |
| 10.43<br>270.2 | 18.71<br>88.85 | 5.214<br>21.63 | 2.481<br>10.29 | 2.913<br>12.09 | 3.598<br>14.92 | 6.511<br>27.01 | 7.695<br>31.92 | 3.747<br>29.92 | 9301<br>26  | 9.02<br>2302.08 | 69.70 |
| 10.53<br>270.2 | 18.71<br>88.87 | 5.222<br>21.63 | 2.486<br>10.30 | 2.917<br>12.09 | 3.613<br>14.97 | 6.531<br>27.05 | 7.708<br>31.93 | 3.718<br>29.88 | 9401<br>26  | 9.02<br>2305.33 | 69.80 |
| 10.64<br>270.2 | 18.72<br>88.90 | 5.231<br>21.64 | 2.490<br>10.30 | 2.921<br>12.09 | 3.629<br>15.01 | 6.550<br>27.10 | 7.721<br>31.94 | 3.689<br>29.86 | 9501<br>26  | 9.03<br>2308.58 | 69.90 |
| 10.74<br>270.2 | 18.72<br>88.95 | 5.214<br>21.54 | 2.495<br>10.31 | 2.926<br>12.09 | 3.644<br>15.05 | 6.569<br>27.14 | 7.709<br>31.85 | 3.685<br>29.96 | 9601<br>26  | 9.03<br>2311.81 | 70.00 |
| 10.84<br>270.2 | 18.72<br>88.97 | 5.248<br>21.65 | 2.500<br>10.31 | 2.930<br>12.09 | 3.659<br>15.09 | 6.589<br>27.18 | 7.747<br>31.96 | 3.630<br>29.83 | 9701<br>26  | 9.03<br>2315.04 | 70.10 |
| 10.95<br>270.2 | 18.73<br>89.00 | 5.278<br>21.74 | 2.504<br>10.32 | 2.934<br>12.09 | 3.674<br>15.14 | 6.608<br>27.22 | 7.782<br>32.06 | 3.579<br>29.72 | 9801<br>26  | 9.04<br>2318.26 | 70.19 |
| 11.05<br>270.2 | 18.73<br>89.04 | 5.244<br>21.57 | 2.509<br>10.32 | 2.938<br>12.09 | 3.690<br>15.18 | 6.627<br>27.26 | 7.753<br>31.90 | 3.592<br>29.88 | 9901<br>26  | 9.04<br>2321.47 | 70.29 |
| 11.16<br>270.2 | 18.73<br>89.10 | 5.248<br>21.56 | 2.514<br>10.33 | 2.942<br>12.09 | 3.705<br>15.22 | 6.647<br>27.31 | 7.762<br>31.89 | 3.566<br>29.91 | 10001<br>26 | 9.04<br>2324.68 | 70.39 |
| 11.26<br>270.2 | 18.74<br>89.13 | 5.259<br>21.58 | 2.518<br>10.33 | 2.946<br>12.09 | 3.720<br>15.26 | 6.666<br>27.35 | 7.777<br>31.91 | 3.534<br>29.88 | 10101<br>26 | 9.05<br>2327.88 | 70.48 |
| 11.36<br>270.2 | 18.74<br>89.19 | 5.267<br>21.58 | 2.523<br>10.34 | 2.950<br>12.09 | 3.736<br>15.30 | 6.686<br>27.39 | 7.790<br>31.92 | 3.504<br>29.88 | 10201<br>26 | 9.05<br>2331.06 | 70.58 |
| 11.46<br>270.2 | 18.74<br>89.24 | 5.275<br>21.58 | 2.528<br>10.34 | 2.954<br>12.09 | 3.751<br>15.34 | 6.705<br>27.43 | 7.803<br>31.92 | 3.474<br>29.88 | 10301<br>26 | 9.05<br>2334.24 | 70.68 |
| 14.59<br>270.2 | 18.79<br>89.74 | 5.568<br>21.90 | 2.672<br>10.51 | 3.074<br>12.09 | 4.225<br>16.61 | 7.299<br>28.70 | 8.240<br>32.40 | 2.485<br>28.64 | 13401<br>26 | 9.12<br>2428.74 | 73.54 |

TABLE XVII. - Continued.

|                |                |                |                |                |                |                |                |                |             |                 |       |
|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|-------------|-----------------|-------|
| 14.68<br>270.2 | 18.79<br>89.72 | 5.576<br>21.90 | 2.677<br>10.51 | 3.077<br>12.09 | 4.240<br>16.65 | 7.318<br>28.74 | 8.252<br>32.41 | 2.455<br>28.57 | 13501<br>26 | 9.13<br>2431.66 | 73.63 |
| 14.78<br>270.2 | 18.79<br>89.70 | 5.583<br>21.90 | 2.681<br>10.52 | 3.081<br>12.09 | 4.256<br>16.69 | 7.337<br>28.78 | 8.264<br>32.42 | 2.424<br>28.50 | 13601<br>26 | 9.13<br>2434.57 | 73.72 |
| 14.88<br>270.2 | 18.79<br>89.71 | 5.538<br>21.70 | 2.686<br>10.52 | 3.085<br>12.09 | 4.271<br>16.73 | 7.356<br>28.82 | 8.224<br>32.22 | 2.446<br>28.67 | 13701<br>26 | 9.13<br>2437.48 | 73.80 |
| 14.98<br>270.2 | 18.79<br>89.69 | 5.546<br>21.70 | 2.691<br>10.53 | 3.088<br>12.09 | 4.286<br>16.77 | 7.374<br>28.86 | 8.237<br>32.23 | 2.416<br>28.60 | 13801<br>26 | 9.13<br>2440.37 | 73.89 |
| 15.08<br>270.2 | 18.79<br>89.69 | 5.563<br>21.74 | 2.695<br>10.54 | 3.092<br>12.09 | 4.301<br>16.81 | 7.393<br>28.90 | 8.258<br>32.28 | 2.377<br>28.51 | 13901<br>26 | 9.13<br>2443.26 | 73.98 |
| 15.18<br>270.2 | 18.79<br>89.69 | 5.560<br>21.71 | 2.700<br>10.54 | 3.095<br>12.09 | 4.316<br>16.85 | 7.412<br>28.94 | 8.260<br>32.25 | 2.356<br>28.50 | 14001<br>26 | 9.14<br>2446.08 | 74.06 |
| 15.27<br>270.2 | 18.79<br>89.67 | 5.567<br>21.71 | 2.704<br>10.55 | 3.099<br>12.09 | 4.331<br>16.89 | 7.430<br>28.97 | 8.272<br>32.26 | 2.327<br>28.43 | 14101<br>26 | 9.14<br>2448.83 | 74.15 |
| 15.37<br>270.2 | 18.79<br>89.65 | 5.574<br>21.71 | 2.709<br>10.55 | 3.102<br>12.09 | 4.345<br>16.93 | 7.448<br>29.01 | 8.283<br>32.27 | 2.299<br>28.37 | 14201<br>26 | 9.14<br>2451.56 | 74.23 |
| 15.47<br>270.2 | 18.79<br>89.63 | 5.581<br>21.72 | 2.713<br>10.56 | 3.106<br>12.09 | 4.360<br>16.96 | 7.466<br>29.05 | 8.294<br>32.28 | 2.270<br>28.30 | 14301<br>26 | 9.14<br>2454.30 | 74.31 |
| 15.57<br>270.2 | 18.79<br>89.60 | 5.588<br>21.72 | 2.718<br>10.56 | 3.109<br>12.09 | 4.375<br>17.00 | 7.484<br>29.09 | 8.305<br>32.28 | 2.241<br>28.23 | 14401<br>26 | 9.14<br>2457.03 | 74.40 |
| 15.67<br>270.2 | 18.79<br>89.57 | 5.595<br>21.72 | 2.722<br>10.57 | 3.113<br>12.09 | 4.389<br>17.04 | 7.502<br>29.13 | 8.317<br>32.29 | 2.213<br>28.15 | 14501<br>26 | 9.14<br>2459.76 | 74.48 |
| 15.76<br>270.2 | 18.79<br>89.55 | 5.601<br>21.72 | 2.727<br>10.58 | 3.116<br>12.09 | 4.404<br>17.08 | 7.520<br>29.16 | 8.328<br>32.30 | 2.184<br>28.08 | 14601<br>26 | 9.15<br>2462.49 | 74.56 |
| 15.86<br>270.2 | 18.79<br>89.51 | 5.608<br>21.73 | 2.731<br>10.58 | 3.120<br>12.09 | 4.418<br>17.12 | 7.538<br>29.20 | 8.339<br>32.31 | 2.155<br>28.00 | 14701<br>26 | 9.15<br>2465.22 | 74.64 |
| 15.96<br>270.2 | 18.79<br>89.47 | 5.615<br>21.73 | 2.736<br>10.59 | 3.123<br>12.09 | 4.433<br>17.15 | 7.556<br>29.24 | 8.351<br>32.32 | 2.127<br>27.92 | 14801<br>26 | 9.15<br>2467.95 | 74.73 |
| 18.90<br>270.1 | 18.80<br>88.60 | 5.813<br>21.78 | 2.874<br>10.77 | 3.225<br>12.09 | 4.882<br>18.29 | 8.108<br>30.38 | 8.686<br>32.55 | 1.251<br>25.67 | 17901<br>26 | 9.20<br>2548.65 | 77.17 |
| 18.99<br>270.1 | 18.80<br>88.58 | 5.819<br>21.78 | 2.878<br>10.78 | 3.228<br>12.09 | 4.897<br>18.33 | 8.125<br>30.42 | 8.697<br>32.56 | 1.223<br>25.61 | 18001<br>26 | 9.20<br>2551.16 | 77.25 |
| 19.09<br>270.1 | 18.80<br>88.55 | 5.832<br>21.81 | 2.883<br>10.78 | 3.232<br>12.09 | 4.911<br>18.37 | 8.143<br>30.45 | 8.715<br>32.59 | 1.188<br>25.51 | 18101<br>26 | 9.20<br>2553.67 | 77.32 |
| 19.18<br>270.1 | 18.80<br>88.53 | 5.838<br>21.81 | 2.887<br>10.79 | 3.235<br>12.09 | 4.926<br>18.40 | 8.161<br>30.49 | 8.725<br>32.60 | 1.160<br>25.44 | 18201<br>26 | 9.20<br>2556.18 | 77.40 |



|                |                |                |                |                |                |                |                |                  |             |                 |       |
|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|------------------|-------------|-----------------|-------|
| 19.27<br>270.1 | 18.80<br>88.50 | 5.837<br>21.79 | 2.892<br>10.79 | 3.238<br>12.09 | 4.940<br>18.44 | 8.178<br>30.52 | 8.729<br>32.58 | 1.138<br>25.40   | 18301<br>26 | 9.20<br>2558.67 | 77.47 |
| 19.37<br>270.2 | 18.80<br>88.48 | 5.844<br>21.79 | 2.896<br>10.80 | 3.241<br>12.09 | 4.955<br>18.47 | 8.196<br>30.56 | 8.740<br>32.59 | 1.109<br>25.34   | 18401<br>26 | 9.20<br>2561.15 | 77.55 |
| 19.46<br>270.2 | 18.80<br>88.47 | 5.850<br>21.79 | 2.901<br>10.81 | 3.244<br>12.09 | 4.969<br>18.51 | 8.213<br>30.59 | 8.750<br>32.60 | 1.081<br>25.28   | 18501<br>26 | 9.21<br>2563.62 | 77.62 |
| 19.55<br>270.2 | 18.80<br>88.44 | 5.856<br>21.79 | 2.905<br>10.81 | 3.247<br>12.09 | 4.983<br>18.54 | 8.231<br>30.63 | 8.761<br>32.61 | 1.053<br>25.21   | 18601<br>26 | 9.21<br>2566.09 | 77.70 |
| 19.64<br>270.2 | 18.80<br>88.42 | 5.862<br>21.80 | 2.909<br>10.82 | 3.250<br>12.09 | 4.998<br>18.58 | 8.248<br>30.67 | 8.771<br>32.61 | 1.025<br>25.14   | 18701<br>26 | 9.21<br>2568.54 | 77.77 |
| 19.74<br>270.2 | 18.80<br>88.39 | 5.868<br>21.80 | 2.914<br>10.82 | 3.254<br>12.09 | 5.012<br>18.62 | 8.265<br>30.70 | 8.782<br>32.62 | 0.9974<br>25.07  | 18801<br>26 | 9.21<br>2570.97 | 77.85 |
| 19.83<br>270.2 | 18.80<br>88.37 | 5.874<br>21.80 | 2.918<br>10.83 | 3.257<br>12.09 | 5.026<br>18.65 | 8.283<br>30.74 | 8.792<br>32.63 | 0.9692<br>25.01  | 18901<br>26 | 9.21<br>2573.41 | 77.92 |
| 19.92<br>270.2 | 18.80<br>88.36 | 5.880<br>21.80 | 2.923<br>10.84 | 3.260<br>12.09 | 5.040<br>18.69 | 8.300<br>30.77 | 8.803<br>32.64 | 0.9412<br>24.95  | 19001<br>26 | 9.21<br>2575.83 | 77.99 |
| 20.02<br>270.2 | 18.80<br>88.34 | 5.886<br>21.80 | 2.927<br>10.84 | 3.263<br>12.09 | 5.054<br>18.72 | 8.317<br>30.81 | 8.813<br>32.65 | 0.9135<br>24.88  | 19101<br>26 | 9.21<br>2578.26 | 78.07 |
| 20.11<br>270.0 | 18.80<br>88.36 | 5.899<br>21.83 | 2.931<br>10.85 | 3.266<br>12.09 | 5.069<br>18.76 | 8.335<br>30.84 | 8.831<br>32.68 | 0.8780<br>24.83  | 19201<br>26 | 9.21<br>2580.67 | 78.14 |
| 20.20<br>270.0 | 18.80<br>88.35 | 5.913<br>21.86 | 2.936<br>10.85 | 3.269<br>12.09 | 5.083<br>18.79 | 8.352<br>30.88 | 8.849<br>32.72 | 0.8431<br>24.75  | 19301<br>26 | 9.22<br>2583.06 | 78.21 |
| 24.35<br>270.1 | 18.80<br>87.42 | 6.172<br>21.93 | 3.135<br>11.14 | 3.401<br>12.09 | 5.723<br>20.34 | 9.124<br>32.42 | 9.307<br>33.08 | -0.3788<br>21.92 | 23901<br>26 | 9.28<br>2687.30 | 81.37 |
| 24.44<br>270.1 | 18.80<br>87.43 | 6.180<br>21.95 | 3.139<br>11.15 | 3.403<br>12.09 | 5.737<br>20.37 | 9.140<br>32.46 | 9.319<br>33.09 | -0.4072<br>21.88 | 24001<br>26 | 9.28<br>2689.43 | 81.43 |
| 24.53<br>270.1 | 18.80<br>87.45 | 6.185<br>21.95 | 3.144<br>11.15 | 3.406<br>12.09 | 5.751<br>20.40 | 9.157<br>32.49 | 9.329<br>33.10 | -0.4332<br>21.86 | 24101<br>26 | 9.28<br>2691.57 | 81.50 |
| 24.62<br>270.2 | 18.80<br>87.46 | 6.184<br>21.93 | 3.148<br>11.16 | 3.409<br>12.09 | 5.764<br>20.43 | 9.173<br>32.52 | 9.332<br>33.09 | -0.4534<br>21.85 | 24201<br>26 | 9.28<br>2693.70 | 81.56 |
| 24.71<br>270.2 | 18.80<br>87.48 | 6.193<br>21.94 | 3.152<br>11.17 | 3.412<br>12.09 | 5.778<br>20.47 | 9.189<br>32.55 | 9.346<br>33.11 | -0.4822<br>21.82 | 24301<br>26 | 9.28<br>2695.83 | 81.63 |
| 24.79<br>270.2 | 18.80<br>87.49 | 6.194<br>21.93 | 3.156<br>11.17 | 3.414<br>12.09 | 5.792<br>20.50 | 9.206<br>32.59 | 9.351<br>33.10 | -0.5041<br>21.81 | 24401<br>26 | 9.28<br>2697.95 | 81.69 |
| 24.88<br>270.2 | 18.80<br>87.51 | 6.217<br>21.99 | 3.161<br>11.18 | 3.417<br>12.09 | 5.805<br>20.53 | 9.222<br>32.62 | 9.378<br>33.17 | -0.5472<br>21.72 | 24501<br>26 | 9.28<br>2700.06 | 81.75 |
| 24.97<br>270.2 | 18.80<br>87.51 | 6.249<br>22.09 | 3.165<br>11.19 | 3.420<br>12.09 | 5.819<br>20.56 | 9.238<br>32.65 | 9.414<br>33.27 | -0.5995<br>21.59 | 24601<br>26 | 9.29<br>2702.17 | 81.82 |

TABLE XVII. - Concluded.

|                |                |                |                |                |                |                |                |                  |             |                 |       |
|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|------------------|-------------|-----------------|-------|
| 25.06<br>270.2 | 18.80<br>87.53 | 6.211<br>21.93 | 3.169<br>11.19 | 3.422<br>12.09 | 5.832<br>20.60 | 9.255<br>32.68 | 9.380<br>33.13 | -0.5825<br>21.73 | 24701<br>26 | 9.29<br>2704.28 | 81.88 |
| 25.15<br>270.2 | 18.80<br>87.58 | 6.218<br>21.94 | 3.174<br>11.20 | 3.425<br>12.09 | 5.846<br>20.63 | 9.271<br>32.71 | 9.392<br>33.14 | -0.6115<br>21.72 | 24801<br>26 | 9.29<br>2706.38 | 81.95 |
| 25.24<br>270.2 | 18.80<br>87.59 | 6.228<br>21.96 | 3.178<br>11.21 | 3.428<br>12.09 | 5.860<br>20.66 | 9.287<br>32.75 | 9.406<br>33.17 | -0.6420<br>21.68 | 24901<br>26 | 9.29<br>2708.49 | 82.01 |
| 25.33<br>270.2 | 18.80<br>87.62 | 6.252<br>22.03 | 3.182<br>11.21 | 3.430<br>12.09 | 5.873<br>20.69 | 9.304<br>32.78 | 9.434<br>33.24 | -0.6865<br>21.61 | 25001<br>26 | 9.29<br>2710.58 | 82.07 |

TERMINATED: STOP

CPU TIME= 13.48 MINUTES.

TABLE XVIII. - INPUT ROUTINE (MAINSE) FOR SHORT-CIRCUIT TRANSIENT

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100 C INPUT DATA FOR THE FOUR WORKING SPACE THREE VOLUME
200 C STIRLING ENGINE MODEL.
300 C
400 COMMON/PST/AD,AR,RODL,VOE,VOC,VR,RER,RRC,STROKE,ALPHA,PSIMD
500 COMMON/CARLOD/GTRAN,GR,AIE,AIWHEL,AIVEH,RWHEEL,AINERT
600 COMMON/CONST/R,G,PIE,DEGR
700 COMMON/MATXIN/VDELTA,FRAC,TOL1,TOL2,TOLSS,N,NTMAX,MPAS,
800 1 TOLPCG,REF
900 COMMON/SWITCH/ISS,ICALC,MATRIX,NONENG,IPRTOP,IBRYTH,
1000 1 IHPCNV,NOBUG
1100 COMMON /SHRTCT/ WD1IN,WD2IN,WD3IN,WD4IN,WD1OUT,WD2OUT,WD3OUT,WD4OUT
1200 1T,WDSHT,WSTMXD,WSTMND,PSHTMX,PSHTMN,WSMX1,WSMN1,VSH,RSHT,RSHTT
1300 COMMON/RUNCON/ALEAK,ARLEAK,PSOURC,CYCLPR,SPDRPM,POSDEO,
1400 1 WSTOTL,TWHIN,TWCIN,CYCLPM,SPDMAX
1500 COMMON/CYDATA/NPTPCY,ITRMAX,NUMBCY
1600 COMMON/TRANDS/ISUPST,ISHTST,TIME,KWORK,ISPSTP,ISHSTP
1700 COMMON/OUTPT/POSDEG,WTOT,ITRAN,WT1,WT2,WT3,WT4,WD1,WD2,WD3,WD4,
1800 1WD5,WD6,WD7,WD8,TORQ1,TORQ2,TORQ3,TORQ4,POWER1,POWER2,POWER3,
1900 2POWER4,POWER,TORQT,TLOAD,TENG,PLOAD,PENG,PNET,PAVEMP,CCCHK
2000 C
2100 C
2200 C ENGINE GEOMETRY
2300 AD=23.7613
2400 AR=1.1290
2500 RODL=10.0
2600 VR=115.339
2700 VOE=63.87
2800 VOC=61.70
2900 STROKE=4.00
3000 ALPHA=90.0
3100 C
3200 C HEATER AND COOLER WALL TEMPERATURES
3300 TWHIN=705.0
3400 TWCIN=86.0
3500 C
3600 C FLOW RESISTANCES BETWEEN VOLUMES
3700 RER=1.9
3800 RRC=1.9
3900 C
4000 C CONSTANTS
4100 DEGR=57.296
4200 PIE=3.1416
4300 R=4125.6
4400 G=10017.0
4500 C

```

```

4600 C   MATRIX CONVERGENCE INPUT
4700     VDELTA=.01
4800     FRAC=1.0
4900     TOL1=.001
5000     TOL2=.01
5100     TOLSS=.0001
5200     N=14
5300     NTMAX=16

5400     MPAS=20
5500     TOLPCG=.5
5600 C
5700 C   SWITCHES
5800     ISS=0
5900     ICALC=1
6000     MATRIX=1
6100     NONENG=1
6200     IPRTOP=100
6300     IBRYTH=0
6400     IHPCNV=0
6500     NOBUG=1
6600 C
6700 C   RUN CONDITIONS
6800     ALEAK=0.0
6900     ARLEAK=0.0
7000     PSOURC=10.0
7100     CYCLPM=15.0
7200     SPDMAX=4000.0
7300     CYCLPR=15.0
7400     SPDRPM=4000.0
7500     POSDEO=270.0
7600     WSTOTL=.007786
7700     VSH=32.78
7800     RSHT=38.0
7900     ASHTT=.20
8000 C
8100 C   LOAD CHARACTERISTICS
8200     GTRAN=1.0/2.53
8300     GR=2.84
8400     WTEHG=0.0
8500     WTWHEL=29.48
8600     WTCAR=1420.0
8700     RWHEEL=30.48
8800 C
8900 C   CYCLE DATA
9000     NPTPCY=25
9100     NUMBCY=1000
9200 C
9300 C   TRANSIENT DESIRED
9400     NCYSHT=5
9500     NCYSUP=50000
9600     NCYSTP=50000
9700     NCYSHS=60000
9800 C
9900 C   CALCULATED INPUT
10000    PSHTMX=CYCLPR+1.0
10100    PSHTMN=CYCLPR-1.0
10200    IF (NONENG .EQ. 0) N=12
10300    REF=(TOL1+TOL2)/2.0
10400    RWHELM=RWHEEL/100.0
10500    ITRMAX=NPTPCY*NUMBCY+1
10600    ISUPST=NCYSUP*NPTPCY+1

10700    ISHTST=NCYSHT*NPTPCY+1
10800    ISPSTP=NCYSTP*NPTPCY+1
10900    ISHSTP=NCYSHS*NPTPCY+1
11000    RSHTT=ASHTT/RSHT
11100    AIE=0.0
11200    WTWHEL=WTWHEL*4.0
11300    AIWHEL=(WTWHEL/2.0)*(RWHELM**2+(RWHELM/2.0)**2)
11400    AIVEH=WTCAR*RWHELM**2
11500    CALL ICSTUP
11600    STOP
11700    END

```

TABLE XIX. - UPDATE STRATEGIES FOR  
JACOBIAN MATRIX

| Broyden algorithm used | TOLPCG                         | Strategy                                                                    |
|------------------------|--------------------------------|-----------------------------------------------------------------------------|
| No                     | 1.0 - 0.5<br><0.5              | Use current matrix<br>Generate new matrix                                   |
| Yes                    | 1.0 - 0.7<br>0.7 - 0.0<br><0.0 | Use current inverse<br>Update inverse with algorithm<br>Generate new matrix |



|                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        |                                                      |                                                                                                  |                   |
|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|------------------------------------------------------|--------------------------------------------------------------------------------------------------|-------------------|
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| 16. Abstract<br>A four-cylinder-Stirling-engine, transient-engine-simulation computer program is presented. The program is intended for controls analysis. The associated engine model has been simplified to shorten computer calculation time. The model includes engine mechanical drive dynamics and vehicle load effects. The computer program also includes subroutines that allow (1) acceleration of the engine by addition of hydrogen to the system and (2) braking of the engine by short circuiting of the working spaces. Subroutines to calculate degraded engine performance (e.g., due to piston ring and piston rod leakage) are provided. Input data required to run the program are described and flow charts are provided. The program is modular to allow easy modification of individual routines. Examples of steady-state and transient results are presented. |                                                      |                                                                                                  |                   |
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