

# Analysis and Correlation of Test Data From an Advanced Technology Rotor System 

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# ANALYSIS AND CORRELATION OF TEST DATA FROM AN ADVANCED TECHNOLOGY ROTOR SYSTEM 

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## SUMMARY

Comparisons have been made of the performance and blade vibratory loads characteristics for an advanced rotor system as predicted by analysis and as measured in a $1 / 5$ scale model wind tunnel test, a full scale model wind tunnel test and flight test.

The principal objective of the study was to determine the accuracy with which the various tools available at the various stages in the design/development process (analysis, model test etc.) could predict final characteristics as measured on the aircraft. A secondary objective was to evaluate the accuracy of the analyses in predicting the effects of systematic tip planform variations investigated in the full scale wind tunnel test. The principal analysis employed was the Sikorsky Y201 aeroelastic analysis which considered the effects of rotor induced and fuselage-induced flow fields. A steady twodimensional aerodynamic representation was used.

The test data from the full scale model were shown to predict forward flight performance within $+5 \%$. Hover performance measurements taken in the wind tunnel predicted cō$r$ rected hover performance data measured at the contractor's rotor whirlstand facility. Blade vibratory loads were found to be underpredicted by the full scale model and this was indicated by analysis to be mostly the result of rotor inflow distortions imparted by the flow over the fuselage.

Blade tip sweep and to a lesser extent tip planform taper were shown to be effective in reducing rotor forward flight power requirements and blade vibratory loads. When these configuration features are combined together, the resulting swept tapered tip was found to be even more effective for improving these rotor system attributes.

The $1 / 5$ scale model rotor predicted conservative full scale rotor performance as expected due to Reynolds number effects. Although blade vibratory moment trends with advance ratio were predicted by the $1 / 5$ scale model, differences in mass and edgewise stiffness distributions (due to the model fabrication early in the design stage of the full scale ATRS and, due to provisions in the model- to allow interchangeable tips) caused the absolute values of the blade vibratory moments to be underpredicted. Analytical corrections correctly accounted for most of the differences between model and full scale results.

The Contractor's Coupled Normal Modes (Y201) elastic rotor blade analysis incorporating variable inflow was able to predict most of the trends of the test data at the higher advance ratios. In addition, using rotor inflow distortions due to fuselage flow as computed by Sikorsky Aircraft's Wing and Body Aerodynamic Technique (WABAT), the Y201 program predicted increases in blade vibratory moments reasonably consistent in magnitude and phase relation with the test data. However, the analysis was unable to predict the absolute magnitude of the blade $\frac{1}{2}$ peak to peak moments at all cruise speed and rotor lift conditions. The $\frac{1}{2}$ peak to peak moments were best predicted when constant inflow was assumed. Y201 gave good performance predictions below rotor stall but optimistic rotor power predictions at high lift.

To eliminate these discrepancies, it is believed that a better representation of the aerodynamics of the blade is required. Emphasis should be placed on improving skewed, unsteady airfoil characteristics, and three-dimensional tip effects.

## INTRODUCTION

It is well known that helicopter rotors operate in a complex aerodynamic environment. This presents a challenging problem of accurately predicting the characteristics of new designs that differ significantly from past practice. To minimize the risk entailed in developing a new rotor, it would be highly desirable to surface potential problems through early analysis and/or early wind tunnel tests. Reynolds number effects, of course, exist at model scale and it is not always possible to duplicate in a model all dynamic characteristics of the full scale hardware. Such differences can exist due to scale problems and/or the fact that the model may not reflect fully the developed full scale rotor. On the other hand, wind tunnel tests of large (or even full) scale rotors usually cannot be conducted until the design/development process is well along. Nevertheless, such a test can be valuable for several reasons. It can be used to confirm the design, to reduce the risk of the flight program, to provide a solid data base on the "isolated" rotor for the purpose of validating analyses and to interpret aircraft system performance.

During the development of the advanced main rotor for a recent modern helicopter, Sikorsky conducted analyses and model and full scale wind tunnel tests of the main rotor (hereafter referred to as Advance Technology Rotor System, ATRS). See Figure 1. Not only are rotor wind tunnel data available at both full and $1 / 5$ scale (from an aerodynamically and dynamically similar model), but rotor flight test data and airfoil data appropriate to the Reynolds number both of the full and $1 / 5$ th scale model are also available. Accordingly, there became available a sufficient data base on one rotor configuration to evaluate the usefulness of models and analysis for predicting full scale rotor attributes. In addition, during the course of the full scale wind tunnel program, systematic tests of tip shapes were conducted.

The prime objective of this program was to determine the ability to use analytical, model and full scale wind tunnel test results to predict rotor flight performance and blade dynamic loading characteristics. More specifically, the objectives were to:

1. To assess the degree to which full scale wind tunnel data for an "isolated" rotor agree with flight test results.
2. To evaluate the applicability of model rotor results through comparisons with full scale wind tunnel and flight test results.
3. To assess the possibility of extending the applicability of model results through the application of analyses employing airfoil data appropriate to model scale airfoils.
4. To evaluate the accuracy of analytic predictions of rotor performance and vibratory loads, identifying important areas where improvements in the analytical methods should be developed.
5. To evaluate the accuracy of analyses in predicting the effects of systematic tip planform variations.

This study has brought these data into a comparable format and employed this data base to address the objectives cited above. It should be noted that wind tunnel data on the full scale rotor has presented an opportunity to correlate analyses with less uncertainties due to the effects of fuselage forces and rotor-fuselage aerodynamic interactive effects present in flight data.

The flight test data for the baseline ATRS comes from demonstration testing of the Sikorsky "SPIRIT ${ }^{T M}$ " helicopter. See Figure 2. The general arrangement of the helicopter is shown in Figure 3. The ATRS incorporates an advanced tip configuration that combines the features of sweep and planform taper which the study will show proved to provide significant rotor system benefits. These same full scale rotor blades were also tested in the NASA Ames 40 ft . ( 12.2 m ) by $80 \mathrm{ft}(24.4 \mathrm{~m})$ Large Subsonic Wind Tunnel. The test configuration is shown in Figure 4. Here the ATRS is mounted above the NASA's Rotor Test Apparatus (RTA) which was powered with two 1500 hp electric motors. During this series of tests, the three $5 \%$ span alternate tip configurations were demonstrated. These tips provide the opportunity to study systematically the effects of tip planform taper and tip sweep and the combination thereof with the results from a conventional rectangular planform tip at full scale Reynolds numbers. Blade spanwise twist and airfoil section were held constant. The four tips are shown in Figure 5 and are described more fully below. These tips are interchangeable with the baseline, swept tapered tip so that only one set of inboard blades were used for the test. Therefore, these tips are compared avoiding potential inboard blade differences that could occur if four sets of blades had been used. Some of the results of these tests are reported in References 1 and 3 . The $1 / 5$ scale model data were obtained in United Technology Research Center's (UTRC) 18 foot ( 5.49 m ) large subsonic Wind Tunne]. The model included a powered rotor, and a replica of the flight vehicles fuselage. The blade was an aerodynamic and dynamically scaled replica of the then defined ATRS blade; it was capable of operating at full scale Mach numbers. Figure 5 shows the model installation. The performance results of this test series are reported in Reference 2.

From these three tests, level rotor performance and blade vibratory moment data were compared where data were available. The rotor system attributes that were selected for comparison were those that are considered to be some of the more important rotor design parameters and, were available from the three tests over the cruise envelope. They are rotor power, blade root torsion (push rod load) and flatwise bending moment at the $70 \%$ span (NB-7). 0ther blade flatwise and edgewise bending moment data are also presented for selected flight conditions.

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$C_{E B-X ~ b l a d e ~ e d g e w i s e ~ b e n d i n g ~ m o m e n t ~ c o e f f i c i e n t ~ a t ~ t h e ~} 10 \times \mathrm{X} \%$ span station $=\frac{E B-X}{\pi \rho \Omega^{2} R^{5}}$
$C_{L} \quad$ airfoil lift coefficient $=\frac{L_{R}}{\frac{1}{2} \rho V^{2} S}$, or
total rotor lift coefficient $=\frac{L_{R}}{\pi \rho \Omega^{2} R^{4}}$
$C_{L_{A F}} \quad$ lift coefficient of the airframe $=\frac{L_{A F}}{\pi \rho \Omega^{2} R^{4}}$
$C_{L S S} \quad$ lateral stationary servo control force coefficient $=\frac{L_{S S}}{\pi \rho \Omega^{2} R^{4}}$
$\mathrm{C}_{\text {NB-X }}$ blade flatwise bending moment coefficient at $10 \times \mathrm{X} \%$ span station $=$

$$
\frac{N B-X}{\pi \rho \Omega^{2} R^{5}}
$$

$C_{P}$
main rotor power coefficient $=\frac{P}{\pi \rho \Omega^{3} R^{5}}$
$C_{\text {PRL }} \quad$ blade root torsional moment coefficients $=\frac{P R L}{\pi \rho \Omega^{2} R^{4} 1 n}$
$C_{Q} \quad$ main rotor torque coefficient $=\frac{Q}{\pi \rho \Omega^{2} R^{5}}$
D rotor drag, positive rearward
$\mathrm{D}_{\mathrm{AF}} \quad$ total airframe drag, positive rearward
EB-X blade edgewise moment at the $10 \times \mathrm{X} \%$ span station, positive forward f total airframe parasite drag area

| kg | kilogram, mass |
| :---: | :---: |
| kgf | kilogram, force |
| L | airfoil section or blade segment lift, positive upward |
| $L_{\text {AF }}$ | airframe lift, positive upward |
| $\mathrm{I}_{\mathrm{h}}$ | blade push rod horn length |
| $L_{R}$ | main rotor lift, positive upward |
| $\mathrm{L}_{S S}$ | lateral stationary servo control force, positive upward |
| $M_{T}$ | rotor rotation or hover tip Mach number, $\frac{\Omega R}{a}$ |
| NB-X | blade flatwise bending moment at $10 \times \mathrm{x} \%$ span station, positive upward |
| P | main rotor power |
| p-p | maximum peak minus minimum peak blade moment |
| PRL | blade push rod load, positive nose up |
| q | airstream dynamic pressure |
| Q | main rotor torque |
| R | blade radius |
| S | airfoil section or blade segment area |
| t/c | airfoil maximum thickness to chord ratio |
| Up | Vertical component of air velocity at the rotor blade, positive upward |
| $U_{R}$ | radial component of our velocity of the rotor blade, positive outward |
| $U_{T}$ | tangential component of our velocity at the other blade, positive approaching the blade |
| V | true airspeed |
| W | aircraft gross weight |
| w | main rotor downwash velocity; positive downward |

$\alpha_{E} \quad$ fuselage effective angle of attack relative to the local flow, degrees, positive nose up
main rotor shaft angle of attack relative to the airstream, degrees, positive inclined rearward
fuselage pitch attitude, degrees, positive nose up
${ }^{\theta} 1$
$\mu$
$\rho \quad$ mass density of air
$\sigma$
rotor solidity $=\frac{b c}{\pi R}$
fuselage roll, degrees, positive right wing down
rotor blade azimuth, zero over the tail cone, or fuselage yaw, degrees, positive nose right

Subscripts
$i \quad$ induced power
o profile power
p parasite drag power

## TEST ROTOR DESCRIPTIONS

## Flight Vehicle

The Advanced Technology Rotor System (ATRS), as configured for the flight test vehicle, has 4 blades with coincident flap and lag articulation provided at the blade root by elastomeric bearings. Blade pitch motion is also permitted by elastomeric bearings. The blade employs titanium spar construction with a fiberglass skin and utilizes graphite composite trailing edge strips for the control of edgewise natural frequency. The blade radius is 22 feet ( 6.706 m ) with a hinge offset of 10 inches ( 25.4 cm ) and the nominal value for chord is 15.5 inches ( 39.37 cm ). The blade has an equivalent linear twist of $-10^{\circ}$ and a $5 \%$ span swept tapered tip, whose quarter chord is swept aft 30 degrees.

Figure 1 shows a sketch of the blade with a breakdown of its airfoil characteristics. The advanced combined airfoil sections used on the blade range from SC1013R8 at the 50 inch (1.27m) radius, tapering to SC1095R8 at the 120 inch $(3.05 \mathrm{~m})$ radius, the SC1095R8 continuing out to 210 inches radius. An SC1095 airfoil is used from 220 inches to the tip with a transition region between 210 ( 5.33 m ) and 220 inches ( 5.59 m ).

The SC1095R8 has leading edge camber to increase maximum lift at low and mid Mach number, and the blade has a -3 reflexed trailing edge tab to reduce blade pitching moment. The SC1095, SC1095R8 and SC1013R8 airfoils have a ( $t / \mathrm{c}$ ) $\max =9.5 \%, 9 \%$, and $13 \%$ respectively. The position of ( $t / \mathrm{c}$ ) max is at the $27 \%$ chord for all three airfoils. The amount of camber is $.84 \%$ on the SC1095 and 2.1\% on the SC1095R8 and the SC1013R8 airfoils. The SC1095 airfoil's maximum camber is located at $30 \%$ chord; for the other two airfoils it is located at $21 \%$ chord. The airfoil surface coordinates are presented in Appendix M.

Structural and mass properties of the ATRS flight test rotor blade are identified in Appendix A. Single value items are listed as well as spanwise variations of blade parameters.

For Flight 30, the blade had a $2.27 \mathrm{lb}, 8$ to 10 inch long, tungsten counterweight starting at station 249.88 and extending inboard. This weight was not included in the aeroelastic analysis, since natural frequency calculations showed it had a small effect.

## Full Scale Model

The baseline full scale model blade is identical to the flight test rotor blade. Therefore, all items in Appendix A are applicable to both rotors. Variations were made in tip configuration to evaluate effects on performance and blade response. Figure 5 shows sketches of the various tip configurations.

The swept-tapered or production tip has a quarter chord sweep of $30^{\circ}$ and a taper ratio of $60 \%$. The trapezoidal tip has zero aerodynamic sweep and a taper ratio of $60 \%$. The rectangular tip has no sweep or taper ratio and the

Swept tip has $20^{\circ}$ of aerodynamic sweep with no taper. For the production and swept tips, the summation of tip area times the distance of the centroid of tip area from the blade feathering axis was kept essentially constant. The breakdown of the various tip section properties are tabulated in Appendix B.

The natural frequencies of the blade were calculated by the Y201 program. These natural frequencies were verified where possible during whirl testing. This was done by observing resonances during cyclic pitch shaker frequency sweeps, and also resonances due to natural harmonic forcing during rotor speed sweeps. The results of the calculations and testing are shown in Figure 7. The correlation in general is quite good, with agreement seen over a range of rotor speed. The calculated torsion mode frequency is about 200 cpm below the test data. This difference in frequency is attributed to a low estimated value for root control system stiffness.

Miscellaneous ATRS rotor head and aircraft physical properties are presented in Appendix D. Lag damper and control system geometry, as well as tail rotor and fuselage descriptions, are included.

## 1/5 Scale Model Description

Early in the design phase of the full scale ATRS, a 8.8 foot (2.68m) diameter ( $1 / 5$ th scale) model rotor was constructed for the purpose of predicting rotor performance and rotor downwash over the fuselage and empennage during powered wind tunnel tests in United Technology Research Center's 18 foot ( 5.49 m )
large subsonic wind tunnel.
The main two design requirements for this blade were to match the full scale outside contour (aerodynamic configuration) and to be able to operate at full scale tip Mach numbers. A third requirement was also established to provide an $8 \%$ span, interchangeable tip capability in order to study the effects of tip design, economically. A fourth, but lower priority requirement, was to match the then defined mass and stiffness properties as close as possible, while meeting the higher priority requirements.

The model blade was fabricated with a chord of 3.1 inches ( 7.87 cm ) and the same spanwise twist and airfoil section distribution as the full scale blade. It was made using similar composite material construction as the full scale rotor blade.

Two physical properties of the $1 / 5$ scale blade are different from the full scale blades. First, after the $1 / 5$ scale model was fabricated and tested, the full scale blade design was modified to increasing the edgewise stiffness by approximately $50 \%$. Secondly, the model's scaled mass is about $18 \%$ higher than the full scale blade. This higher weight comes from two sources, structural provisions for the interchangeable tip and from inboard mass weight growth during construction of the first model blades. Because early wind tunnel testing was desired, and because the primary purposes of the test were directed toward performance and handling qualities objectives, the mass differences were judged acceptable.

The mass and structural properties of the $1 / 5$ scale model blades as fabricated are presented in Appendix $C$.

## ROTOR FORCE TRIM ANALYSIS

To satisfy the objectives of this contract, it is necessary to define the trim state of the flight rotor. This can be accomplished in one of two ways. In the first approach, the rotor trim state can be taken as that defined by the blade pitch control angles and the rotor shaft angle measured in flight. These angles can then be used in an analysis to predict rotor forces and moments. These angles could also be used to interrogate wind tunnel data maps to determine rotor forces and moments. The principal disadvantage to this approach is of course that such angle data are not available until the aircraft flies.

The second approach, and the one employed herein, involves use of model scale fuselage characteristics measured on a sub scale model, together with an aircraft trim analysis, to define the required main rotor lift and propulsive force. Using this approach, aircraft predictions can be updated following wind tunnel tests of models. Such model tests can, of course, be conducted much earlier in the life of the aircraft program. Once rotor lift and propulsive force requirements are known, the analysis or rotor wind tunnel (or flight) data can be interrogated at these values to determine dependent quantities of interest such as power, blade stresses etc. As a final note, rotor pitch and roll moments are not considered since experience has shown that such moments are intentionally kept small by design and that on articulated rotors performance and blade loads are generally insensitive to realistic variations in these parameters. The details of the process by which trim conditions were thus computed are given below.

The main rotor lift coefficient is expressed:

where:

$$
\begin{aligned}
C_{W} & =\text { weight coefficient } \\
& =\frac{W}{\rho \pi R^{2}(\Omega R)^{2}} \\
W & =\text { aircraft weight } \\
\rho & =\text { ambient air density } \\
C_{L_{A F}} & =1 i f t \text { coefficient of the airframe }
\end{aligned}
$$

The value of $C_{L_{A F}}$ is not available from flight test measurements and must be determined either through analysis or from wind tunnel tests. For this study the value was obtained from $1 / 5$ scale configuration model tests. Appendix $F$ presents a method to determine the variation of fuselage lift, divided by the free stream dynamic pressure, with fuselage angle of attack based on the model tests. The main rotor lift coefficient is then expressed:

$$
C_{L}=C_{W}-\frac{\left(L_{A F} / q\right) q}{\rho \pi R^{2}(\Omega R)^{2}}
$$

where:

$$
\begin{aligned}
& L_{A F} / q=\text { fuselage } 1 \mathrm{ift} / \text { dynamic pressure ratio } \\
& q=\text { dynamic pressure }=\frac{2}{2} \rho V^{2}
\end{aligned}
$$

Substituting for the dynamic pressure gives:

$$
\begin{aligned}
C_{L} & =C_{W}-\frac{L_{A F} / q}{\rho \pi R^{2}(\Omega R)^{2}}\left(\frac{1}{2} \rho V^{2}\right) \\
& =C_{W}-\frac{L_{A F} / q}{2 \pi R^{2}} \mu^{2}
\end{aligned}
$$

or, dividing by the solidity ratio ( $\sigma$ ):

$$
C_{L} / \sigma=C_{W} / \sigma-\frac{L_{A F} / q}{2 b c R} \mu^{2}
$$

The $1 / 5$ scale model data of Reference 2 was also the basis for evaluating the flight test vehicle parasite drag. Appendix $F$ presents drag related data from Reference 2, along with appropriate corrections that yield the total airframe drag variation with angle of attack presented in Figure 8. These corrections consisted of additional drags due to miscellaneous protuberances, holes, instrumentation items and momentum losses that were not simulated in the wind tunnel tests. The drag coefficient after substituting for the dynamic pressure and dividing by the solidity ratio, is

$$
C_{D} / \sigma=\frac{D_{A F} / q}{2 b c R} \mu^{2}
$$

where $D_{A F}$ is the total airframe drag as evaluated in Appendix $F$.

The main rotor torque used to compare with analytic and wind tunnel results is measured directly in flight and the torque coefficient is defined:

$$
C_{Q}=\frac{Q}{\rho \pi R^{3}(\Omega R)^{2}}
$$

where:

$$
Q=\text { main rotor torque }
$$

Profile torque must be estimated and is derived from the measured main rotor torque by subtracting the calculated torques due to parasite drag and an idealized induced drag. This is best accomplished by expressing the contributions of parasite and induced drags as power coefficients, since these are numerically equal to the respective torque coefficients. The parasite drag power may be written (assuming ideal propulsive efficiency):

$$
P_{p}=\left(D_{A F} / q\right) \times q \times V=D_{A F} V
$$

or, in coefficient form:

$$
C_{P_{p}}=C_{Q_{p}}=\frac{-D_{A F} V}{\rho \pi R^{2}(\Omega R)^{3}}=-C_{D} \times \mu
$$

which is the parasite drag torque coefficient.
Induced drag power may, for small tip path plane angles, be expressed as

$$
P_{i}=L_{R}\left(\frac{w}{V}\right) V=L_{R} w
$$

where

$$
\begin{aligned}
L_{R} & =\text { main rotor lift } \\
W & =\text { main rotor downwash velocity } \\
& =\frac{C_{L}}{2 \mu} \Omega R
\end{aligned}
$$



$$
C_{P_{i}}=\frac{L_{R}}{\rho \pi R^{2}(\Omega R)^{3}} \quad\left(\frac{C_{L}}{2 \mu}\right) \Omega R=\frac{C_{L}^{2}}{2 \mu}
$$

therefore,

$$
C_{P_{i}}^{-}=C_{Q_{i}}=\frac{C_{L}^{2}}{2 \mu}
$$

the idealized induced drag torque coefficient.

The profile torque coefficient is defined:

$$
C_{Q_{0}}=\frac{Q_{0}}{\rho \pi R^{3}(\Omega R)^{2}}
$$

where:
$Q_{0}=$ profile torque
and in terms of the total main rotor torque, lift, and drag coefficients is expressed:

$$
C_{Q}=C_{Q}-\frac{C_{L}^{2}}{2 \mu}+C_{D} \times \mu
$$

Tables I and II summarize the main rotor level flight force coefficients used to compare the test and analytical data as a function of advance ratio, rotational tip Mach number and helicopter gross weight. The fuselage body attitudes measured in flight are also given for reference. Most of the advance ratio and tip Mach number conditions were selected to correspond to specific conditions tested during the full scale rotor wind tunnel tests. This rotor was tested over a range of lift and propulsive force values. Flight test data were available at two values of gross weights and also over the advance ratio range shown in the tables, but not necessarily at the specific values. The gross weight values in the tables were chosen to correspond to those values selected for the flight testing. One specific advance ratio was selected based on the flight test results. At a rotational tip Mach number ( $M_{T}$ ) equal to . 6 and a gross weight of $8200 \mathrm{lb}(3719.5 \mathrm{~kg})$, vibratory moments were measured at the most blade spanwise stations up to an advance ratio ( $\mu$ ) equal to .338 . Other flights extended the test data to higher speeds, but fewer blade loads were recorded. Therefore, $\mu=.338$ was selected as one condition to compare test data results because it was the highest speed where the most complete blade moment data were available from flight tests.

In all cases, some portion of the test data had to be interpolated to the specific conditions shown in the tables. The flight data were interpolated to a specific advance ratio holding gross weight and $M_{T}$ fixed. The full scale rotor data were usually interpolated to the specific rotor lift and propulsive forces noted in the tables holding $\mu$ and $M_{T}$ constant. The $1 / 5$ scale model data were interpolated for both rotor forces and advance ratio as required.

Late in this study, as this report was being written, an error was discovered in the evaluation of airframe lift. This error amounts to a $5 \%$ overestimation of rotor lift for trimmed level flight due to a discrepancy in calculated fuselage local angle of attack, $\alpha_{E}$. Accordingly, the full scale model test data are compared to the flight data at a $5 \%$ greater value than should be. Airframe drag was not effected because drag is essentially constant between ${ }^{\alpha} E$ $=-5^{0}$ to $+5^{0}$, the range where trim for the conditions studied occurs. The effect of this increase on the full scale model power and the blade vibratory
load was estimated and found to be equal to, or less than a $1 \%$ increase per $1 \%$ increase in rotor lift. Also, a check on the calculated fuselage interference flow on blade vibratory moments revealed only small differences in the computed values. Therefore, the effect of the high estimated rotor lift does not effect the conclusions of this report. The data results of this report have not been connected for this discrepancy and the rotor lift values for the trim conditions presented in Tables I and II are numbers that are $5 \%$ high.

Wall effect corrections were applied to all rotor data obtained in a wind tunnel. For the full scale model, this correction was based on a classical Prandtl wall correction previously derived for the $40 \times 80 \mathrm{ft}$ wind tunnel. ( $\Delta \alpha=k \times L / q$ where $k=.00197 \mathrm{deg} / \mathrm{ft}^{2}$ ). This correction becomes more accurate as test velocities are increased and is adequate at speeds 100 kts and above.

Because wall corrections are approximate, they are another source of error. Even a small error in the calculated angle of attack correction can result in a significant error in the corrected rotor power required. For the ATRS rotor operating at $C_{L} / \sigma=.095, M_{T}=.6$ and a $f / b C R=.107$, the approximate percentage change in power required per degree of angle correction varies as a function of advance ratio as follows:

$$
\begin{array}{cc}
\underline{\mu} & (\Delta \mathrm{Cq} / \mathrm{Cq} / \Delta \alpha) \times 100 \\
.15 & 7 \% \\
.30 & 9 \% \\
.40 & 10.4 \%
\end{array}
$$

Accordingly, if the correction to the free air conditions of the rotor performance data taken in the wind tunnel were off by 1 degree, then the rotor performance would be in error by the percentage shown in the above table. But as was noted above, as advance ratio is increased, the estimated wall corrections become more accurate and the angle of attack error becomes much less than one degree.
TABLE I

| $\begin{aligned} & \text { GW LB } \\ & (\mathrm{kg}) \end{aligned}$ | C.G. Loc. (Fus. Sta.) | $\begin{aligned} & V \\ & \text { Kts, } \\ & \text { TAS } \end{aligned}$ | $\begin{gathered} \Omega R \\ f p s \\ (\mathrm{~m} / \mathrm{sec}) \end{gathered}$ | $\begin{aligned} & { }_{\mathrm{B}}^{\mathrm{B}} \\ & \text { Deg } \end{aligned}$ | $\begin{aligned} & \phi_{\mathrm{B}} \\ & \mathrm{Deg} \end{aligned}$ | $\begin{aligned} & \psi_{\mathrm{B}} \\ & \text { Deg } \end{aligned}$ | $\begin{gathered} \begin{array}{c} \rho \\ \text { slug } \end{array} \\ \hline \mathrm{ft}^{3} \\ (\mathrm{~kg}) \\ \mathrm{m}^{3} \end{gathered}$ | $\mu$ | $M_{T}$ | $\mathrm{C}_{\mathrm{W}} / \sigma$ | $\mathrm{C}_{\mathrm{L}} / \sigma$ | $-C_{D} / \sigma$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\begin{aligned} & 8200 \\ & (3719.5) \end{aligned}$ | $\begin{aligned} & 210 \\ & 210 \end{aligned}$ | 100 | $\begin{gathered} 673 \\ (205) \end{gathered}$ | 2.87 | -1. | -2. | $\begin{gathered} .002229 \\ (1.1488) \end{gathered}$ | . 25 | . 6 | . 07140 | . 0747 | . 00336 |
| 8200 | 210 | 120 | 673 | 2.02 | -1. | -2. | . 002229 | . 3 | . 6 | . 07140 | . 0755 | . 00484 |
| 8200 | 210 | 135 | 673 | 1.40 | -. 5 | -2. | . 002229 | . 338 | . 6 | . 07140 | . 0765 | . 00615 |
| 8200 | 210 | 150 | 673 | . 8 | -1. | -2. | . 002229 | . 375 | . 6 | . 07140 | . 0781 | . 00757 |
| 8200 | 210 | 160 | 673 | . 36 | -1.3 | -2. | . 002229 | . 4 | . 6 | . 07140 | . 0797 | . 00861 |
| $\begin{aligned} & 10300 \\ & (4672) \end{aligned}$ | $\begin{aligned} & 197 \\ & 197 \end{aligned}$ | 100 | $\begin{gathered} 677 \\ (206) \end{gathered}$ | 1.5 | -1.4 | -2. | $\begin{gathered} .002275 \\ (1.1725) \end{gathered}$ | . 25 | . 6 | . 08684 | . 0898 | . 00336 |
| 10300 | 197 | 120 | 677 | 0.4 | -1. | -3. | . 002275 | . 30 | . 6 | . 08684 | . 0911 | . 00484 |
| 10300 | 197 | 140 | 677 | -1.3 | -. 9 | -1. | . 002275 | . 35 | . 6 | . 08684 | . 0931 | . 00659 |
| 10300 | 197 | 150 | 677 | -1.2 | -. 7 | -1. | . 002275 | . 375 | . 6 | . 08684 | . 0948 | . 00757 |

TABLE II


| $\begin{gathered} 8200 \\ (3719.5) \end{gathered}$ | 210 210 | 100 | $\begin{gathered} 719 \\ (219) \end{gathered}$ | 3.6 | $-2.6$ | -3. | $(1.1488)^{.002229}$ | .25 | $\begin{aligned} & .64 \\ & .65 \end{aligned}$ | .06251 | .0657 | .00336 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 8200 | 210 | 128 | 719 | 2.3 | $-.4$ | -2. | .002229 | .30 | $\begin{aligned} & .64 \\ & .65 \end{aligned}$ | .06251 | .0670 | .00484 |
| 8200 | 210 | 149 | 719 | .86 | $+.4$ | $-2$ | .002229 | .35 | $\begin{aligned} & .64 \\ & .65 \end{aligned}$ | .06251 | .0689 | .00659 |
| 8200 | 210 | 160 | 719 | 0. | $-1$. | $-1$. | .002229 | .375 | $\begin{aligned} & .64 \\ & .65 \end{aligned}$ | .06251 | .0700 | .00757 |
| 8200 | 210 | 170 | 719 | $-1.35$ | $-1.4$ | 0. | .002229 | .400 | $\begin{array}{r} .64 \\ .65 \\ \hline \end{array}$ | .06251 | .0718 | .00861 |
| 10300 | 210 | 106 | 719 | 4.7 | - | -2. | .00222 | .25 | .633 | .07904 | .0822 | .00336 |
| (4672) | 210 |  |  |  |  |  | (1.144) |  | .65 |  |  |  |
| 10300 | 210 | 128 | 719 | 3.6 | - | $-2$ | .00222 | .30 | $\begin{aligned} & .633 \\ & .65 \end{aligned}$ | .07904 | .840 | .00484 |
| 10300 | 210 | 149 | 719 | 2.25 | - | $-1$. | .00222 | .35 | $\begin{aligned} & .633 \\ & .65 \end{aligned}$ | .07904 | .0870 | .00659 |
| 10300 | 210 | 160 | 719 | 1.35 | - | $-1$. | .00272 | .375 | .65 | .07904 | .0892 | .00751 |

*First value corresponds to flight test, second to NASA/Ames test.

## DISCUSSION OF TEST RESULTS

Baseline Rotor - Flight, Full Scale and $1 / 5$ Scale Model Data Comparisons

## Performance Data

Figures 9 through 12 present the variation of trimmed level flight main rotor torque coefficient with advance ratio for two tip Mach numbers, 0.6 and 0.65 , and for two representative aircraft weights of $82001 \mathrm{~b}(3719.5 \mathrm{~kg}$ ) and 10,300 1 b ( 4622 kg ). The data presented was obtained through flight test and wind tunnel tests conducted on both full scale and $1 / 5$ scale models of the ATRS rotor as discussed in the introduction. (Note: In order to provide all flight test data on a consistent basis, the test flights for Figures 9 through 12 were initially selected as those from which the blade dynamic loads data were obtained.)

The correlation of full scale model and flight data is generally good. However, some random differences are noted in Figures 9 and 12. In Figure 9 the full scale model torques are higher than measured in flight whereas in Figure 12 they are lower. It is believed that these differences are due to small errors in the derived flight drag values. Additional flight conditions were examined to provide a greater number of data points and the results are summarized in Figure 13 where flight and full scale wind tunnel torque values are presented. The correlation is quite good as the data scatter is randomly about the $0 \%$ error line with the bulk of the data falling within $+5 \%$. In the course of making this comparison, it was noted that those data points giving the smallest errors, were those acquired during dedicated performance (as opposed to structural) testing. The range of rotor performance parameters covered by the data in Figure 13 is:

| Parameter | Value Range |  |
| :---: | :---: | :---: |
|  | Minimum | Maximum |
| ${ }^{4}$ | . 25 | . 375 |
| M | . 6 | . 635 |
| $C_{L} / \sigma$ | . 762 | . 10 |
| $C_{D} / \sigma$ | -. 0034 | -. 0076 |
| $\mathrm{C}_{\mathrm{q}} / \sigma$ | . 00325 | . 0087 |

As expected, the $1 / 5$ scale model torques are consistently higher than both the full scale model and flight test vehicle. (Figures 9 through 11) This is due to Reynolds number effects that result in higher drags at comparable lifts below stall and also to earlier stall. 1/5th scale model torques are typically $20 \%$ higher than full scale model results.

Figures 14 through 17 present the variation of level flight main rotor profile torques for the same operating conditions as for the total torques presented in Figures 9 through 12. The profile torque is estimated from the measured total torque by subtracting the torques due to idealized parasite drag and induced drag. Correlation of full scale model profile torques with flight test values is, as for the total torques, good to excellent. However, differences here may, in fact, be exaggerated because small differences in total torque will, dependent on the operating condition, result in a much larger percentage change in the profile torques derived from it since all of the difference will by definition be contained in the profile torque.

## Hover Performance Measurements

When the full scale model was installed in the NASA Ames Wind Tunnel, hover performance measurements were made with the tunnel walls open and the rotor shaft axis tilted 10 degrees forward. The shaft tilt was used to reduce rotor recirculation effects. These measurements are compared in Figure 18 with corrected data obtained on Sikorsky Aircraft's $10,000 \mathrm{hp}$ main rotor whirlstand. The whirlstand data has been reduced by three percent in order to correct for test stand interference and ground effects. The figure demonstrates good agreement between the two sets of test data and indicates that for rotors of the size of the ATRS or smaller, good quality hover data can be obtained in the subject wind tunnel.

## $\frac{1}{2}$ Peak to Peak Blade Moment Data

The vibratory moment data presented in the following sections are blade vibratory loads. They are presented in two forms, either as one half of the maximum load value minus the minimum value experienced by the blade as it moves around the aximuth, i.e. half peak to peak values ( $\frac{1}{2} p-p$ ), or the instantaneous load value as a function of blade azimuth. All moments are presented non-dimensionalized and ratioed to rotor solidity as follows:

$$
\begin{aligned}
& \frac{C_{\text {PRL }}}{\sigma}=\frac{\text { Push Rod Load }}{b c \rho \Omega^{2} R^{3}} \\
& \frac{C_{\text {NB-X }}}{\sigma}=\frac{\text { Flatwise Bending Moment at } 10 \times X \% \text { Span Station }}{b c \rho \Omega^{2} R^{4}} \\
& \frac{C_{E B-X}}{\sigma}=\frac{\text { Edgewise Bending Moment at } 10 \times X \% \text { Span Station }}{b c \rho \Omega^{2} R^{4}}
\end{aligned}
$$

Figure 19 presents the spanwise distribution $\frac{1}{2} p-p$ flatwise bending moments. These are presented at a gross weight of 8200 lb ( 3719.51 kg ) a normal blade rotational tip Mach number, $M_{T}=.6$, and an advance ratio, $\mu=.338$ or 135 knots. Flight test data (from flight 30), and full scale and $1 / 5$ scale model interpolated test data are compared along with analytic results, which will be discussed in a separate section.

The maximum measured flight test values are shown to occur at the root and at the $70 \%$ span station. They reduce to zero at the blade tip and to about half the peak values at the $30 \%$ span ( $\mathrm{NB}-3$ ) station. Data from the full scale model rotor, interpolated to the equivalent cruise speed and rotor trim lift and propulsive force conditions of the figure, accurately predict the flight test $70 \%$ span maximum and the $30 \%$ span trough values. In between the values are lower.

The corresponding vibratory edgewise loading distribution is shown in Figure 20. The maximum measured moment in flight occurs near the blade root. The interpolated full scale model test data presented over the mid span stations agrees quite closely with the flight data.

Figure 19 and 20 also present a comparison of the measured $1 / 5$ scale model spanwise $\frac{1}{2} p-p$ moments with the flight test and the full scale model interpolated data. The $1 / 5$ scale data are also interpolated to the estimated trim conditions of the flight vehicle. The two inboard flatwise gages of the $1 / 5$ scale model are in good agreement with the full scale test data while the load measured by the NB-6.5 gage is about $50 \%$ low. The $1 / 5$ scale model edgewise load is also low.

Potential reasons for the low $1 / 5$ scale model results were considered. The model data were reviewed to see if calibrations were in error; none were found. The differences in blade characteristics between model and full scale were also reviewed. As discussed in the Test Vehicle Description section, the blade flatwise and torsional spanwise stiffness distributions are very close. However, the model edgewise stiffnesses are two-thirds of the full scale blade because the model was built during the early part of the full scale blade design phase. The full scale blade final design edgewise stiffness was increased after the model blades were completed. In addition, the model blade mass distribution inboard of the $60 \%$ span station and also between the $91 \%$ to $97 \%$ span station is higher resulting in a $18 \%$ increase in total equivalent blade weight. This resulted from the practical considerations of building and testing model blades to aid in the development of a new rotor system. For example, these model blades were designed with an interchangeable tip capability to study tip changes economically. Accordingly, the model outboard weight increase results from additional structure for the joint. The inboard mass results from the desire to begin the model testing as early as possible in the full scale blade design phase, and therefore, not providing sufficient time to reduce the model blade's weight. These differences, therefore, result from very real practical considerations faced by a designer confronted with lead time constraints.

In order to estimate the effect of these two differences, the Coupled Normal Modes Elastic Rotor Analysis computer program (Y201) was run with the two sets of blade characteristics and assuming constant rotor inflow and using the same airfoil characteristics. These results are shown in Figures 21 through 24 for two advance ratios, . 338 and .375 and at 8200 lb . gross weight and $100 \%$ rotor speed. The calculations strongly suggest that these differences in blade characteristics are a significant contributor to the lower model NB-6.5 and EB-3.5 vibratory loads. Although each difference was not calculated
separately, the increased mass is believed to be the dominant factor affecting the flatwise stresses, which are significantly changed only between the $50 \%$ and $75 \%$ spanwise stations. For the edgewise loads, Y201 predicts a reduction in vibratory moments inboard of $55 \%$ span station due to the combined effects of increased mass and lower edgewise stiffness. These predicted trends are very similar to the differences observed between the full and $1 / 5$ scale model test data This is illustrated in Figures 19 and 20. The arrows connected to the $1 / 5$ scale model test points indicate the magnitude and the direction that the analytical calculations would correct the test data on a percentage basis. Some differences between $1 / 5$ scale and full scale results remain even with these corrections. These are believed to be due to Reynolds number effects on the airfoil characteristics and due to errors introduced by the need to interpolate the various loads data bases to obtain the loads at particular trim conditions.

The correlation of the three test rotors over the level flight envelope is presented in Figures 25 through 30. The blade vibratory torsional moments, in terms of the blade pushrod load, are given in Figures 25 through 27 at 8200 1b ( 3719.5 kg ) and $10,300 \mathrm{lb}(4672 \mathrm{~kg}$ ) and at two rotational tip Mach numbers, $M_{T}=.6$ and .65 . Figures 28 through 30 present the blade vibratory bending moments at the $70 \%$ span station for the same flight conditions as noted for the vibratory torsional moments. This is a station near the maximum outboard flatwise vibratory moment where data are available for all three test vehicles. As was previously noted, blade spanwise vibratory loads (Figures 19 and 20) were obtained from flight 30 up to $\mu=.338$ at $M_{T}=.6$ and gross weight $=8200$ 1b ( 3719.5 kg ). Because flight 30 did not continue to higher speeds, blade vibratory loads at higher speeds (Figure 28) were obtained from flight 2 for the noted gross weight and rotational tip Mach number. The data from the two flights overlap and can be seen to be in agreement when Figures 19 and 28 are compared.

The full scale model either predicts or slightly overpredicts the $\frac{1}{2} p-p$ torsional and outboard flatwise moments at low advance ratio ( $\mu$ ) up to .25 . As $\mu$ is increased these unsteady moments are underpredicted, but not by a large amount. For example, at $\mu=.375$, the full scale model underpredicts the flight data by about $20 \%$ on the average. As shown in Figure 30 , the full scale wind tunnel model interpolated data had some scatter at this condition. The mean of the scatter band falls below the flight data in about the same relative position as other similar data shown in Figures 28 and 29. As will be seen in the later discussion on the analytic results, the analysis suggests that flow distortions due to the aircraft flow over the fuselage is the probable cause of much of this underprediction.

The $1 / 5$ scale model data is also shown on these figures for the conditions where $M_{T}=.6$. Figures 25 and 26 show that the model underpredicts the flight blade's root torsional moments at minimum power speeds. However, at the higher advance ratios, the more critical flight test moments are well predicted. This generally good agreement is expected despite the blade design differences noted earlier, because they did not significantly influence blade torsional frequencies.

The $1 / 5$ scale model $\frac{1}{2} p-p$ flatwise bending moments (as measured) at the $65 \%$ span station are compared to the $70 \%$ span moments from flight test in Figures 28 and 29. Their magnitude is about half of the flight test value over the cruise envelope for both the high and the low gross weight values presented. The reasons for the low $1 / 5$ scale model values have been previously discussed; however, it is encouraging to note that the full scale trends with advance ratio and gross weight are well predicted by the model. This suggests that despite potential unavoidable blade differences, early sub scale model data can be used directly to examine trends.

These data and the data in Figures 19 and 20 are the extent of the available $1 / 5$ scale dynamic data. However, this is sufficient data to conclude that if model blade characteristics are scaled properly, then measured model blade dynamic characteristics will reasonably correlate with the full scale characteristics. A practical constraint faced by the model designer will be the early state of the actual blade design. Corrections for reasonable differences in model and final full scale blade designs can be developed using analytic procedures.

Although the flight and full scale model rotor are expected to be alike in many respects, one potential area of difference is that of the stationary control systems. As a result it is of interest to determine the degree to which the full scale model results could be used to predict the flight aircraft stationary control loads.

An example of the loads comparison between the full scale flight and model rotor is presented in Figures 31 and 32 for the non-rotating portions of the rotor control system. The vibratory lateral stationary servo control loads, nondimensionalized, are compared over the level flight envelope for two rotor speeds and helicopter gross weight values. At the lower gross weight, the flight data and the interpolated wind tunnel data agree very closely and there is no effect of blade tip Mach number on the stationary servo load. At the higher gross weight, the full scale model underpredicts the flight data by about $20 \%$, which is similar to what was observed for the other blade vibratory loads. As will be discussed in the analysis section, the difference is probably due in part to fuselage flow interference.

Blade Moment Time Histories
The time histories of the blade push rod load, NB-7 and EB-6 moments were harmonically analyzed for several flight conditions of interest. These data are derived from the test results of both full scale rotors. The following table summarizes the conditions, loads and the figure numbers where resultant load amplitudes and the corresponding time histories are presented.

TABLE III
TEST CONDITIONS FOR HARMONIC ANALYSIS AND TIME HISTORY PRESENTATIONS OF BASELINE ROTOR LOADS

| Test Condition |  |  | Blade Loads |  |  | Figure No. |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mu$ | $M_{T}$ | (1b) ${ }^{\text {GW }}$ (kg) | PRL | NB-7 | EB-6 | Resultant <br> Amplitude | Time History |
| . 338 | . 60 | 8200. (3719.5) | $\checkmark$ | $\checkmark$ |  | 33 | 42 |
|  |  |  |  |  |  | 34 | 46 |
|  |  |  |  |  | $\checkmark$ | 35 | 47 |
| . 4 | . 60 | 8200. | $\checkmark$ | $\checkmark$ |  | 36 | 43 |
|  |  |  |  |  |  | 37 | 48 |
| . 375 | . 60 | 10300. (4672) | $\checkmark$ | $\checkmark$ |  | 38 | 44 |
|  |  |  |  |  |  | 39 | 49 |
| . 375 | . 65 | 10300. | $\checkmark$ | $\checkmark$ |  | 40 | 45 |
|  |  |  |  |  |  | 41 | 50 |

The harmonic analysis study indicates that the first 7 harmonics of the push rod load are the most significant for both rotors. The resultant harmonics from the flight rotor are generally about the same or higher than from the full scale rotor. For the flatwise bending moment data, the first three harmonics are the most significant for both rotors. The flight test rotor generally has the higher resultant amplitudes. This is consistent with the $\frac{1}{2} \mathrm{p}-\mathrm{p}$ moment data. However, the full scale model rotor has a 10 to $60 \%$ higher first harmonic resultant moment than the flight rotor. At this time, there is no satisfactory explanation of this latter result.

The blade load time histories presented in Figures 42 through 50 were reconstructed using the first eight harmonic amplitudes of the reduced test data. A review of these figures leads to the conclusion that the resulting time histories from the wind tunnel model do tend to predict the overall amplitude and general nature of flight rotor time histories, but the higher harmonic content and associated phase are only occasionally predicted.

## Effect of Alternate Tip Configurations

## Performance Data

The main rotor power requirement as affected by the alternate tip configurations shown in Figure 5 was investigated for four flight conditions in level flight. Advance ratio and rotational tip Mach number combinations are included which cover the present day cruise envelope ( 120 to 170 kts ). Data are presented for gross weight values of $8200 \mathrm{lb}(3719.5 \mathrm{~kg}$ ) and $10,300 \mathrm{lb}$ (4672 kg ) where possible.

Figures 51 to 54 compare the ATRS with the three alternate tips to the baseline rotor in terms of rotor torque coefficient to solidity ratio. Two bars are given for each tip configuration; the left bar presents the test data at two gross weight values, the right bar presents the calculated results. (Analytic results also shown will be discussed in a later section.) In all cases, the swept tapered tip provides the lowest main rotor power. Except at $\mu=.3$ and $M_{T}=.6$, the constant chord swept tip provides the next best improvement and then the trapezoidal tip. The conventional rectangular tip requires the most power at and above $150 \mathrm{kts}(\mu=.375)$, as expected. Table IV summarizes these savings relative to the rectangular tip in terms of rotor horsepower.

TABLE IV
MAIN ROTOR BLADE TIP COMPARISON; CHANGE IN HORSEPOWER RELATIVE TO RECTANGULAR TIP

| $\mathrm{M}_{\mathrm{T}}$ | ${ }^{\mu}$ | $\underset{(\mathrm{kg})}{\mathrm{G} . \mathrm{W} .}(\mathrm{lb})$ | $\Delta H P(K W) \quad$ Relative to Rectangular Tip |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | Swept Tapered | Swept | Trapezoidal | Rectangular |
| . 6 | . 30 | 8,200 | -19.2 | 10.3 | 3. | 0. |
|  |  | (3719.5) | (-14.1) | (7.6) | (2.2) | 0. |
| . 6 | . 30 | 10,300 | -17.7 | 0. | 4.4 | 0. |
|  |  | (4672.) | (-13.0) |  | (3.2) |  |
| . 6 | . 375 | 8,200 | $(-59.1$ $(-43.4)$ | $\begin{gathered} -32.5 \\ (-23.9) \end{gathered}$ | (-26.6 $(-19.5)$ | 0. |
| . 6 | . 375 | 10,300 | (-43.4) | ( 23.9 ) | ( | 0. |
| . 65 | . 375 | 8,200 | -69.5 | -60.1 | -41.3 | 0. |
|  |  |  | (-51.1) | (-44.2) | (-30.4) |  |
| . 65 | . 375 | 10,300 | -75.1 | -18.8 | 0. | 0. |
|  |  |  | $(-55.2)$ | (-13.8) |  |  |
| . 68 | . 375 | 8,200 | $\begin{aligned} & -30 . * \\ & (-22.1) \end{aligned}$ | $\begin{aligned} & 10^{*} \\ & (7.4) \end{aligned}$ | 0.* | No data |

*Savings relative to the trapezoidal tip.

## Half Peak to Peak Blade Moment Data

The effect of blade tip configuration on blade vibratory loads was examined as a function of rotor propulsive force for four flight conditions and at two levels of rotor lift equivalent to level flight at a gross weight of 7900 lb $(3583 \mathrm{~kg})$ and $10,300 \mathrm{lb}(4672 \mathrm{~kg})$. The flight conditions that were examined are: $\mu=.3, M_{T}=.6 ; \mu=.375, M_{T}=.6, .65$ and .68. Blade push rod load and flatwise and edgewise bending moments at the 60 and $70 \%$ span stations were compared when the required data were available for each tip configuration and at each flight condition.

These differences are summarized in Figures 55 through 65 along with analytical predictions which are discussed separately. Each figure compares the four tip configurations on the basis of one blade vibratory load parameter measured in trimmed level flight at one advance ratio and tip Mach number. Two bars are given for each tip configuration; the left bar presents the test data at two gross weight values; the right bar presents the calculated results. The trim propulsive force is used in these figures without loss of generality because. the relative magnitude of the blade vibratory loads did not change significantly as rotor propulsive force was varied, i.e. $0 \leq-C_{D} / \sigma \leq .01$. In fact, for
this range, blade loads remained essentially constant or were reduced slightly as propulsive force was increased.

At an advance ratio of 0.3 ( 120 kts ), these tip configurations produced only minor differences in $\frac{1}{2} \mathrm{p}-\mathrm{p}$ blade moments. See Figures 55, 59 and 63. Increasing rotor lift within the gross weight range investigated also did not induce significant differences. At the higher advance ratio ( $\mu=0.375$ ), however, some load differences were observed at .6 and .65 blade tip rotational Mach number. These are discussed below.

Blade $\frac{1}{2} \mathrm{p}-\mathrm{p}$ root torsional moments are shown in Figures 56 and 57 to be the highest for the blade with the rectangular tip configuration at both gross weight and blade tip Mach number values. At $M_{T}=.6$, the three advanced tip configurations provide the same or small reductions in vibratory pushrod load. For the higher blade tip speed condition, blade tip sweep is shown to be very benefical. The baseline blade, which has the swept tapered tip, produced the lowest push rod loads. These were $25 \%$ lower than experienced by the rectangular tip blade.

The $\frac{1}{2} \mathrm{p}-\mathrm{p}$ flatwise bending moments at the $70 \%$ span station are compared in Figures 60 and 61. Again, the blade with the rectangular tip experienced the highest vibratory loads. For both tip Mach numbers, as taper and sweep are incorporated to reduce tip loading, the NB-7 vibratory moments are reduced with the baseline rotor having the lowest moments. At $M_{T}=.6$, its moments are reduced about $15 \%$ below the rectangular tipped blade and at least $20 \%$ at the higher tip Mach number.

For some conditions at $\mu=0.375$, there was either suspect or insufficient NB7 data to enable the swept tip blade to be interpolated to the flight trim condition and included in these figures. (Recall that NB-7 was choosen as a basis for comparison because it was one of three parameters measured on all three test vehicles.) However, insight into the relative blade bending moments among the four blade configurations can be obtained from the moments at the $60 \%$ span. A review of the NB-6 data showed that the swept tip blade moments are found to be close to the trapezoidal tip blade. Therefore, the NB-7 bending moments for the swept tip blade were assumed to be equal to those for the trapezoidal tip blade. (Figure 19 shows NB-6 and NB-7 to be quite close in magnitude so that this approach is reasonable.)

The $70 \%$ span $\frac{1}{2}$ p-p edgewise bending moments are compared in Figures 64 and 65. The test data show that the advanced tip configurations do not affect EB-7 moments by more than $10 \%$ as compared to the rectangular tip blade. At normal tip Mach number, .6, the baseline blade has slightly higher moments than the blade with the rectangular tip, while the blade with the trapezoidal tip has slightly lower moments. At $\mathrm{M}_{\mathrm{l}}=.65$, the baseline blade has slightly lower moments than the rectangular tip blade, which has the highest moments.

Limited test data are also available at blade rotational Mach number equal to .68 and an advance ratio of .375 ( 170 kts ) to allow the three advance tip configurations to be compared. Blade $\frac{1}{2} \mathrm{p}-\mathrm{p}$ push rod loads are presented in Figure 58 and NB-6 moments in Figure 62. The push rod load for the swept tip
blade is not available. These data also demonstrate that the swept tapered tip produces the lowest blade loads.

## Blade Moment Time Histories

A comparison of the blade root torsion and $60 \%$ span flatwise bending moments as they vary around the rotor azimuth and as affected by the four tip configurations is presented in Figure 66 through 69. These data were originally published in Reference 3. The rotor is being flown in near trimmed level flight at a gross weight of $10,500 \mathrm{lb}$. Test data are presented at two blade rotational tip Mach numbers, 6 and .65 .

As was observed in the discussion on the $\frac{1}{2}$ p-p loads, the blade with the rectangular tip is shown generally to have the largest excursions as it traveled around the rotor azimuth for both root torsion and NB-6 moments. Modifying the tip to incorporate taper or sweep provides a modest reduction in peak loads at $M_{T}=.6$ for this moderately twisted blade, and only minor changes in blade wave form. As $M$ is increased to .65 the reduction in peak loads and changes in wave form increase. The swept and the tapered tip configuration exhibit very similar moment signatures.

The swept tapered tip induced a substantially different blade moment time history than the other tip configurations, especially for the blade push rod load time history. The blade pitch down moment at the $100^{\circ}$ to $180^{\circ}$ azimuth region was significantly reduced at both tip Mach number flight conditions (Figures 66 and 67). The swept and trapezoidal tips also showed this trend, especially at $M_{T}=.65$. As the figures show, the elimination of this peak removes one of the major peaks of the blade torsion response. Correspondingly, the $60 \%$ span, peak downward flatwise bending moment is reduced in thjs azimuth region and the peak upward bending moment is also reduced at the $240^{\circ}$ azimuth location.

Why the combination of sweep and taper produces this benefit is not precisely understood but some insights are suggested by considering some first order effects that appear to be supported by the test data. First recall that for the high tip Mach number condition, the advancing blade tip Mach number is 0.9. Reducing blade tip thickness through taper is beneficial because tip drag is reduced. Reducing tip drag on the advancing blade, when the tip region is bent downward due to negative tip lift, would cause an incremental nose up twisting moment causing the tip to be unloaded. This is supported by the advancing blade negative flatwise bending moments shown in Figures 68 and 69, and the reduced blade torsion peak at $\psi=140^{\circ}$ for the trapezoidal tip blade shown in Figures 66 and 67 . Secondly, when aft tip sweep is added to a blade, the aerodynamic center of the swept portion of the blade is moved rearward relative to the main blade's elastic axis. Accordingly, tip lift produces a stabilizing moment which also unloads the tip and redistributes this load change inboard. Correspondingly, when tip lift is downward, as on the advancing side of the rotor disc for a twisted blade, the down lift produces a nose up moment, thus again unloading the tip. Moreover, tip sweep provides local Mach number relief for an advancing blade, thus reducing tip drag. Because the blade is bent downward due to negative lift, drag reduction
produces an incremental nose up moment. These latter two tip loading effects combine to reduce a nose down blade torsional moment on the advancing blade as, in fact, the test data shows in Figures 66 and 67 for the swept tip blade. Now, when taper was combined with sweep in the baseline tip, the product of tip area and the offset of the centroid of that area from the blade quarter chord was maintained essentially the same for both this tip and the swept tip. That is, the stabilizing twisting effect of tip lift was designed to be similar for these two tips. Therefore, if sweep and taper are combined in a tip, as was done for the baseline tip, then it is certainly reasonable to expect that the above noted benefits could complement each other, producing a still larger nose down moment reduction than was realized from each component reduction.

The test data does support this hypothesis by showing that the lowest nose down torsional moment at $\psi=140^{\circ}$ does occur for the baseline blade, and that this benefit is Mach number dependent for all three advanced tip configurations. It is noted that rotor horsepower reductions given in Jable IV vary in a similar manner as the nose down moment is reduced at $\psi=140^{\circ}$. The swept taper tip produced the greatest horsepower reductions at the high advance ratio relative to the rectangular tip while the swept and trapezoidal tips produced similar magnitude lower reductions. There is, however, one area where the test data show an inconsistent trend: the lower tip Mach number condition shows the greatest reduction in blade nose down moment for the swept tapered tip which should occur at the higher tip Mach number condition. Rotor trim moment differences or data interpolation inaccuracies might account for this inconsistency.

## Assessment of Theoretical Performance Correlation

Theoretical rotor power predictions using variable inflow are compared with test values Figures 70 through 73. Each figure presents rotor $C_{0} / \sigma$ for a range of advance ratios and a constant sea level standard gross weight and rotational tip Mach number. The four presented flight conditions represent 8200 lb ( 3719.5 kg ) gross weight at . 60 hover tip Mach number, $10,300 \mathrm{lb}(4672 \mathrm{~kg}$ ) gross weight at . 60 hover tip Mach number, 8200 1b at . 65 hover tip Mach number, and $10,300 \mathrm{lb}$ at . 65 hover tip Mach number. At each gross weight and rotational tip mach number, experimental data is presented from three sources. These are full scale model, flight, and $1 / 5$ scale model tests.

Superimposed on the same plots are predicted performance with full scale and model scale airfoil data. Because the two gross weight conditions present markedly different correlation trends, the correlation will be discussed separately at $8200 \mathrm{lb}(3719.5 \mathrm{Kg})$ and $10,300 \mathrm{lb}(4672 \mathrm{Kg})$ gross weight. Also, the full scale correlation will be discussed separately from the model scale results due to different confidence levels in the applied airfoil coefficient data. Full scale analytical results will be examined relative to the full scale model results rather than the flight data. This reflects the belief that the full scale model data represents a higher degree of test condition control. At $8200 \mathrm{lb}(3719.5 \mathrm{Kg})$ gross weight, full scale predicted performance is considered good to excellent at both .60 and .65 rotational tip Mach numbers. This is illustrated by the fact that the predicted results are a better indicator of full scale flight performance than the full scale model test at the .60 rotational tip Mach number condition. At the higher rotational tip Mach number, the analytic prediction is equally accurate relative to the full scale model, but the full scale model is a better predictor of flight results.

At the higher gross weight of $10,300 \mathrm{lb}$, the analysis predicts optimistic performance irrespective of the hover tip Mach number. The only exception is the good prediction accuracy obtained at an advance ratio of 25 . In all other speed regimes, the full scale test power requirements are under predicted, with the most optimism occurring at the highest advance ratio of 0.4. It is also noted that the under estimation of required power becomes less accurate for the lower rotational tip Mach number condition.

Deterioration of the prediction accuracy at the high load condition is not unexpected and is due to approximations applied to the static airfoil data to account for skewed flow in the existing theoretical model. When the airfoil lift requirements are moderate and the static airfoil lift coefficients adequately represent the rotor load distribution, the current Y201 aerodynamic model is sufficient for power prediction. At high retreating side lift conditions, however, the approximate skewed flow lift model and the lack of unsteady aerodynamics compromise performance predictions. As retreating side angles of attack in $Y 201$ progressively enter the stall regime, the approximate skewed flow lift stall model initially causes optimistic power prediction. At
deeper stall conditions, the lack of unsteady lift enhancement predominates and rotor power is largely over predicted. Figure 74 illustrates the skewed flow model stall mechanism that causes optimistic power predictions. The skewed $C_{1}-\alpha$ curve is constructed by connecting a linear extrapolation of the zero skew lift line to a new curve formed by dividing the zero skew curve by the cosine of the sweep angle. As indicated in the figure, this procedure eliminates the nonlinear region prior to $C_{L_{M A X}}$ and substantially elevates
airfoil L/D in the shaded region. When the calculated blade side angle of attack enter the shaded region, the rise in airfoil L/D causes the optimistic performance predictions noted at $10,200 \mathrm{lb}$ ( 4672 kg ) gross weight. This behavior was confirmed by recalculating the $10,200 \mathrm{lb}, \mathrm{M}_{\mathrm{T}} .60$ performance at two advance ratios with the Generalized Rotor Performance Program (GRP), a nonelastic blade rotor analysis. This program has aerodynamics which are similar to those of Y 201 , except that a more conservative skewed flow stall model is used. In this case, the optimism in the rotor power prediction was reduced to approximately $3 \%$. The GRP calculated performance points are noted in Figure 71. It is anticipated that, had the more conservative model been used in Y201, the good correlation demonstrated at 8200 lb ( 3719.5 kg ) gross weight would have also extended to the higher gross weight.

Although not strongly indicated by the presented correlation, increasing the calculated retreating blade angles of attack beyond the shaded region in Figure 74 , will result in premature rotor stall and a sharp rise in predicted power. Both the stall onset and the accompanying power increase occur prematurely in the analysis due to the lack of unsteady aerodynamic lift extension. The beginning of this behavior can be noted in the predicted power curve slope between an advance ratio of 0.38 and 0.40 for the $10,000 \mathrm{lb}$ ( 4672 kg ), . 60 rotational tip Mach number case. (See Figure 71.)

The skewed flow stall model used in the $Y 201$ elastic blade analysis was an early attempt to approximate the effects of skew flow on steady 2-D airfoil data. At the time it was initiated, no better modeling was available. The more accurate conservative analysis was later developed for the rigid blade, performance programs to meet the requirement of predicting rotor performance. Because both an oblique and unsteady flow representation of the airfoil data is believed to be required to more accurately predict elastic blade dynamic loads, Sikorsky Aircraft and UTRC are presently developing such a representation. The updating of the Y201 program awaits the results of that analysis development.

Torque prediction for the $1 / 5 \mathrm{th}$ scale model at the $8200 \mathrm{lb}(3719.5 \mathrm{~kg}$ ) condition is as good or better than that achieved for the full scale rotor at both rotational tip Mach numbers. However, since the full scale rotor analysis consistently underpredicts the full scale model tests results for the same conditions, the predicted effect of Reynolds number on the rotor torque is generally too large. The most likely cause of this discrepancy is the accuracy of the model scale airfoil data at high lift. Due to the lack of a suitable balance apparatus, the model scale airfoil drag data was measured in the NASA Langley Research Center $6 \times 28$ inch ( $15.3 \times 68.5 \mathrm{~cm}$ ) transonic wind tunnel with a wake rake. At high lift coefficients, which induce flow
separation, and tunnel speeds above the critical Mach number, which gives rise to wave drag, the wake rake is not an accurate indicator of airfoil drag. Also, the measured maximum lift coefficient in the test were affected by severe wall interference. This tunnel operational problem was noted by NASA prior to the test. It is noted that the predicted Reynolds number effect is substantially more accurate at the lower advance ratios where the airfoil flow patterns are less severe.

At the higher $10,300 \mathrm{lb}(4672 \mathrm{~kg})$ gross weight conditions, the $1 / 5 \mathrm{th}$ scale model torque prediction is also more accurate than the full scale prediction. The error in the model torque prediction, however, is pessimistic as opposed to the optimistic trend noted for the full scale rotor cases. This behavior probably results from either the previously discussed accuracy limits on the model airfoil drag data, the lowered maximum lift coefficients of the model airfoil data, or a combination of the two. As indicated in the prior discussion of the $Y 201$ lift representation in the stall regime, the lack of unsteady aerodynamics causes a pessimistic torque trend when the skewed static maximum lift coefficient is approached. For the $1 / 5$ th scale model rotor, this lift limit will be reached at lower load and advance ratio conditions.

In summary, the Y 201 elastic blade analysis generally predicts optimistic full scale performance in the rotor $C / \sigma$ range above 0.08 . The GRP rigid blade rotor performance analysis predicts well full scale performance. The difference is principally due to the skewed flow models used in each program. The Y201 analysis using $1 / 5$ scale model airfoil data predicts pessimistic performance. This indicates that if full scale performance is derived from $1 / 5$ scale model results using corrections based on the differences in available airfoil at the appropriate Reynolds number, the resulting performance will be optimistic. This means that Reynolds number corrections derived from the available airfoil data are too large.

## Alternate Tips

Figures 51 through 54 present comparisons, of predicted performance and full scale model measured performance for 20 alternate tip test conditions. Each of the four figures presents test and analytical results for fixed gross weights, advance ratio, rotational tip Mach number, and propulsive force. Baseline rotor test and calculated performance is also included as a reference. For each figure, test and calculated torques are presented at the propulsive force required to sustain level flight on the flight vehicle. It should be noted that test results are not available for the three alternate tips at the highest gross weight presented at the . 375 advance ratio and . 6 rotational tip Mach number condition examined in Figure 52. Analytical results, however, are presented for this high $C_{L} / \sigma$ condition to highlight analytical trends.

In general, absolute performance prediction accuracy for the three alternate tips is similar to the previously discussed trends for the swept tapered tips. For most low gross weight conditions, prediction accuracy is fair to good. At the high gross weight the performance correlation also holds up quite well except for the .375 advance ratio condition at .60 rotational Mach number.

For this case, the baseline rotor torque is under predicted. Although equivalent experimenal data is not available on the alternate tips, it is anticipated that a similar underprediction of rotor torque would occur.

The ability to predict the differential torque requirement between various tip designs is as important, or more important, than accurate prediction of absolute torque. If differential torque trends can be accurately predicted, then the analysis can be used in the future to choose a specific design configuration over another with a degree of confidence. At the low advance ratio condition, no consistent trend with test data emerges in the accuracy of the predicted torque differential. The differentials are smaller for this conditions. However, for the other advance ratio and rotational tip Mach number conditions, the predicted torque differential trends among the tips compare favorably with the test data. The only exception at the high speed conditions is for $\mu=.375$ and $M_{T}=.68$. Here, the swept tip is predicted to be superior to the trapezoidal tip, while the test data indicates the opposite.

Assessment of Theoretical Blade Vibratory Moment Correlation

## Baseline Rotor

Rotor vibratory moments were computed with the $Y 201$ analysis using both constant inflow and variable inflow assumptions. The results are presented in Figures 19 and 20 as a function of blade span (at a $\mu=.338$ ) and in Figures 25 through 30 as a function of advance ratio (at selected spanwise stations). Contrary to expectations, it was found that the vibratory moments were predicted most accurately when the constant inflow assumption was employed.

In Figures 19 and 20, the important outboard peak flatwise bending moment from flight test was predicted using constant inflow to within $5 \%$ although it is predicted to occur more inboard at $58 \%$ span. Between this peak and the $30 \%$ span station, the constant inflow analysis overpredicts the test data while further inboard and outboard of the $60 \%$ span the test data is underpredicted. The predicted maximum $\frac{1}{2}$ p-p edgewise moment occurs about $20 \%$ span more outboard than the test data maximum, which is near the $10 \%$ span station. The peak test value is also underpredicted by $12.5 \%$. Further outboard on the blade, the difference between the test and predicted moments increases.

The analysis was also run in the coupled Y201/variable inflow (F389 SR) mode, assuming a skewed helical wake. See Appendix $G$ for a more detailed discussion of this analysis. The calculated $\frac{1}{2} p-p$ moments versus with blade span are very similar to those calculated assuming constant inflow. However, using this variable inflow analysis, the blade $\frac{1}{2} p-p$ moments are significantly underpredicted for the ATRS with its swept tip configuration. This underprediction was typical for the entire cruise envelope.

Figures 25 through 30 show the trends with advance ratio. Blade vibratory root moments expressed in terms of blade pushrod load and flatwise bending at the $70 \%$ span (NB-7) are presented for the two values of gross weight and blade rotational Mach number being analyzed. Typically, the analysis using constant inflow underpredicts the test data by $20-30 \%$, but generally predicts the rate
of increase in pushrod load and NB-7 moment as speed increases above the speed for minimum power.

Predictions of the blade vibratory loading using variable inflow and the classical wake are shown to be more optimistic in Figures 25 through 30 than when using constant inflow. The analysis is only predicting about $50 \%$ of the flight test blade $\frac{1}{2}$ p-p moments. Furthermore, the analysis gives a lower moment sensitivity to increasing speed than the test data unlike that which was predicted using constant inflow. Also included in this correlation study were four high speed dive conditions. The flight and rotor force trim conditions are given in the table below:

## TABLE V

ROTOR FORCE TRIM FOR HIGH SPEED DIVE CONDITIONS

| Condition <br> No. | $\mu$ | $M_{T}$ | Dive <br> Angle | Load <br> Factor | $\%$ Normal <br> Rotor RPM | $C_{L} / \sigma$ | $-C_{D} / \sigma$ |
| :--- | :---: | :--- | :---: | :---: | :---: | :---: | :---: |
| 1 | .488 | .593 | -6.9 | 1.07 | 99.6 | .0817 | .00335 |
| 2 | .468 | .647 | -10.4 | .98 | 107.6 | .0658 | .00026 |
| 3 | .463 | .603 | -5.99 | .99 | 100.2 | .0973 | .00202 |
| 4 | .449 | .638 | -7.75 | 1.04 | 106.1 | .0872 | -.00061 |

The first two conditions were flown at a gross weight of 8200 lb ( 3719.5 kg ) with true airspeed of about 194 and 210 knots, respectively. The second two conditions were flown at $10,300 \mathrm{lb}(4672 \mathrm{~kg})$ and 185 and 190 knots, respectively.

A comparison of the predicted main rotor torque and blade $\frac{1}{2}$ p-p loads using the variable inflow analysis is given in Table VI.

TABLE VI
HIGH SPEED DIVE CORRELATION RESULTS

| Flight Test Data |  |  |  | Predicted Data |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Condition | $\mathrm{C}_{\text {PRL }} / \sigma$ | $\mathrm{C}_{\text {NB-7 }} / \circ$ | $\mathrm{C}_{\mathrm{Q}} / \sigma$ | $\mathrm{C}_{\text {PRL }} / \sigma$ | $\mathrm{C}_{\text {NB-7 }} / \sigma$ | $\mathrm{C}_{\mathrm{Q}} / \sigma$ |  |
| No. | 4.37 | 2.23 | 9.09 |  | 3.2 | 1.34 |  |
| 1 | 4.64 | 2.27 | 6.24 | 7.61 |  |  |  |
| 2 | 6.75 | 2.72 | 9.04 | 4.7 | 1.82 | 6.78 |  |
| 3 | 7.77 | 2.22 | 7.66 | 4.0 | 1.68 | 8.84 |  |
| 4 | $\left(\times 10^{-3}\right)$ | $\left(\times 10^{-4}\right)$ | $\left(\times 10^{-3}\right)$ | $\left(\times 10^{-3}\right)$ | 1.52 | 4.98 |  |
|  |  |  | $\left.\times 10^{-4}\right)$ | $\left(\times 10^{-3}\right)$ |  |  |  |

At these high forward speeds the variable inflow analyses generally underpredicts the rotor performance and blade vibratory moments test data, but the degree of underprediction is less than for the lower flight speed conditions.

Part of this underprediction of the blade loads can be attributed to assuming isolated, rotor operation (i.e. no fuselage flow perturbations) which would normally be done in the design process. It will be shown below that the flight test data does include at least a $20 \%$ increase in the blade vibratory loads due to fuselage flow. However, this is only part of the reason for the difference between test and analysis.

A comparison of the calculated and the full scale model blade bending moment variations around the azimuth provides some insight to one probable reason for the low peak loading predictions. These comparisons are shown in Figures 46 through 50 and they are for flight conditions which cover the higher speed portion of today's cruise speed flight envelope. A review of these figures shows that the wave forms, especially for the lower harmonics, are reasonably in phase with the full scale model rotor data, which have a lesser influence of fuselage flow distortions. This phase agreement is also true for the edgewise moment time history shown in Figure 47. What appears to be missing from the variable inflow analysis is sufficient moment amplitude for the first three or four harmonics.

With the assumption of constant inflow, (Figures 42 and 46) the analyses causes a degradation in phase relation, but provides a larger amplitude excitation. Referring to Figure 56, the constant jnflow curve shows greater amplitude at azimuth positions of $120^{\circ}$ and $240^{\circ}$, resulting in the greater predicted $\frac{1}{2} \mathrm{p}-\mathrm{p}$ moment than was predicted by the variable inflow analysis. The phase correlation with test data, however, is not as good as with variable inflow, expecially around $270^{\circ}$ azimuth. The variable inflow results do not exhibit any increase in higher harmonic content but rather a reduction in the one and two per rev components. Figure 42 shows the same comparison for push rod load. The constant inflow curve displays a more negative amplitude around $140^{\circ}$ azimuth, resulting in the higher $\frac{1}{2} \mathrm{p}-\mathrm{p}$ value. The variable inflow does produce a $4 / r e v$ component that is present in the test data, but not reflected in the constant inflow results. Accordingly, this comparison suggests that while constant inflow improves correlation of $\frac{1}{2} p-p$ moment values, the improvement is probably fortuitous in light of the poorer phase relationship that results.

## Alternate Tips

The predicted (using variable inflow) effects of tip configuration on push rod load and flatwise bending moment are presented in Figures 55 through 65. The analysis predicts a strong beneficial effect due to the addition of sweep and taper on push rod load. The test results show a similar, though less strong, benefit at the higher Mach number - advance ratio conditions. At the lower Mach number - advance ratio condition, the test data do not show simjlar consistent benefits. The analysis correctly predicts (qualitatively) the beneficial effect of reduced gross weight.

For the $70 \%$ span flatwise vibratory bending moments, Figures 59 through 61 (NB-6 in Figure 62), the analysis again predicts benefits in these moments due to planform taper and sweep for both blade tip Mach number and gross weight values. Tip sweep was predicted to be more beneficial than tip taper, while
the test data at the high advance ratio generally confirms that tip taper and sweep reduce NB-7 moments relative to a conventional blade. For the swept tapered tip, the NB-7 moments were predicted to be the lowest and this is confirmed by the test results for all conditions presented. The analysis predicts the benefits of tip sweep and taper are additive at $M_{T}=.65$ while at $M_{T}-.6$ they are not. At the highest value of $M_{T}=.68$ (Figure 62), the analysis not only predicts the test data trends with tip configuration and gross weight, it also predicts the absolute value of NB-6. This is also true for the blade vibratory push rod loads (Figure 58) and rotor torque (Figure 54). This agreement is unique and occurs at the highest rotational tip Mach number studied. The reason for this agreement is not understood at this time.

The measured vibratory edgewise moments for all the conditions presented (Figures 63 through 65) show little effect of the various tip configurations. In contrast, the analysis predicts beneficial effects for adding sweep and taper for $M_{T}=.6$ conditions, the analysis is overpredicting the effect of increasing gross weight. These are the conditions of the highest rotor lift coefficients. As predicted by the analysis, tip sweep exhibits a strong influence for reducing vibratory edgewise moments of high rotor lift conditions.

Although the Y201 analysis tends to generally predict the trends in the test data, blade bending moments are generally underpredicted as was discussed previously for the baseline blade. However, it is interesting to note that blade pushrod loads are predicted for the tip configurations without sweep. Furthermore, there is a larger increase in the predicted blade moments with gross weight than is demonstrated by the test data for the .6 tip Mach number condition. For the high gross weight, the rotor is operating at $C_{1} / \sigma=.094$, which is considered high. Also note that this predicted jump is dtminished as tip sweep is introduced. When the blade tip is not swept, the analysis allows the tip to carry more load at local angles of attack in the neighborhood of stall. With tip sweep the analysis unloads the tip and redistributes the blade lift more inboard thus reducing the blade response. While these predicted tip effects trend correctly, the trend magnitude is not correct. The analysis assumes two-dimensional steady flow in a region that has threedimensional, unsteady flow, and for skewed flow corrections, mentioned earlier. These assumptions governing the loading in the tip region are clearly subjects for review.

## Effect of Fuselage Flow on the Baseline Blade Moments

Sikorsky Aircraft's Wing and Body Aerodynamic Technique (WABAT) computer analysis (Y179) was used to compute the local flow over the flight test vehicle's fuselage and the resulting normal interference velocities at the rotor. See Appendix $H$ for a more detailed description of the analysis. Using these interference velocities as input (listed in Appendix L), the coupled normal modes (Y201)/variable inflow (F389) Elastic Rotor Analysis was employed to calculate the effects of fuselage flow distortions on rotor blade vibratory loads. The conditions analyzed are as follows:

## TABLE VII

## FLIGHT CONDITIONS FOR CORRELATION STUDY OF FUSELAGE FLOW EFFECTS ON ROTOR BLADE VIBRATORY LOADS

| $\mu$ | $M_{T}$ | GW |
| :--- | :--- | :--- |
| .388 | .60 | $8200 \mathrm{lb}(3719.5 \mathrm{~kg})$ |
| .4 | .60 | 8200 lb |
| .375 | .60 | $10,300 \mathrm{lb}(4672 \mathrm{~kg})$ |
| .375 | .65 | $10,300 \mathrm{lb}$ |

The effect of the fuselage is summarized in Figures 75 through 82 where the calculated and the full scale test time histories of the blade root torsion and $70 \%$ span flatwise bending moments are compared. The top two time histories in each figure are the flight and full scale test data results with the steady values of the time history adjusted (to be nearly equal) so that the harmonic portion of the load variations can be compared more directly. The flight test time history includes the effect of the fuselage flow, while the full scale time history includes the lesser flow distortions from the NASA/Ames RTA. (See Figure 4) The bottom two time histories are calculated, one for the rotor alone and one including inflow distortions due to the fuselage.

In order to obtain an indication of difference in inflow velocities due to the two near bodies, the rotor inflow velocities induced by the RTA were estimated using the WABAT analysis as were the velocities induced by the flight vehicle's fuselage. These calculations are compared in Figure 83 in terms of local angle-of-attack change at the rotor blade, induced by the fuselage flow. The two near bodies are located at their respective test heights below and incidence attitudes to the rotor. As the figure shows, the RTA induces a lesser angle-of-attack distortion than the flight vehicle over entire rotor in the longitudinal plane of symmetry. Because the flight vehicle has a wider body than the RTA, the RTA's flow influence also diminishes more rapidly than the flight vehicle's at all other positions in the plane of the rotor. Therefore, the difference between the two test time histories should be an indication of the influence of the flight vehicle's fuselage flow distortion at the rotor.

For each of the four conditions investigated, the significant differences between the rotor alone and the rotor plus fuselage curves, as indicated by the arrows, for both the test and calculated results, generally occur at about the same azimuth positions. This is particularly true for flatwise bending moments, high or low gross weight. For the calculated root torsion results, most significant differences occur as the blade has just passed over the nose of the aircraft where the upflow is expected to be the strongest. These excitations continue on over the retreating portion of the disc and are small on the advancing side of the disc. The test data tends to demonstrate similar differences but also indicates higher excitations over the tail cone.

The calculated and test differences for flatwise bending are very similar on the retreating side of the rotor disc. However, on the advancing side of the disc the test data shows more excitation and the higher 3 per rev resultant bending moment amplitude between flight test and the full scale model that was previously discussed.

The similarity of the azimuth location and direction of moment of the differences between the test and calculated time histories, especially on the retreating side of the rotor disc, suggests that the fuselage flow is a significant contributor. According to the test data, the effect of the fuselage flow is to increase $\frac{1}{2}$ p-p pushrod loads and blade flatwise bending moments by about $20 \%$. However, if the ATRS could have been tested completely free of nearbody flow effects and the results compared to flight test data, blade vibratory loads increases may have been found to be greater than 20\%. The predicted increases in $\frac{1}{2} \mathrm{p}-\mathrm{p}$ loads range from 14 to $44 \%$.

## Some Considerations for Analysis Improvement

The above correlation studies have revealed areas of agreement and disagreement between the test data and the Y201 variable inflow analysis, using a skewed helical wake. Improving loads correlation should be particularly emphasized. In this context, four aerodynamic areas where the mathematical modeling of the Y201 rotor blade response analysis and of industry's analysis in general require improvements have been cited above. Note that they are all items that more accurately characterize the blade and the actual environment in which it must operate. The areas are:

- Skewed flow aerodynamics
- Unsteady stall aerodynamics
- Three dimensional, swept tip aerodynamics
. Rotor inflow velocities and wake structure
A possible fifth mathematical moeling area that may require refinement and that pertains principally to Y201 is that of blade structural modeling. Y201 utilized a modal approach, with a limited number of modes and retains only first order twist coupling terms. In the past this modeling has been acceptable, but it is possible that with the recent trend to higher twist rotor blades, that improvements in this area are required.

Unfortunately, the influence that each of the above items has on blade response is highly interrelated with each of the other items so that it is difficult to identify the exact cause of each correlation difficiency. It is believed, however, that the aerodynamic aspect of the problem is more critical. Further, it is also believed that the inflow and tip aerodynamics modeling are the most critical of the aerodynamic areas for improving the loads correlation at flight conditions studied in this report.

The reasons for these beliefs are:
a) Inadequacies in the structural math modeling tend to affect the torsional response most and for the most part the torsional response is well predicted with the current program.
b) The lack of correlation exists at conditions for which significant blade stall is not present. Thus, unsteady and skewed flow effects should be relatively small. Of course, such effects would become important when stall occurs and work in this area is required from that standpoint.
c) The outboard blade loading is a powerful driver of loads - e.g. the differences between constant and variable inflow loadings tend to be concentrated near the tip.

Further discussion of these critical areas, together with some thoughts on how to approach each, follows.

## Three-Dimensional Swept Tip Aerodynamics

Owing to the high dynamic pressures at a rotor tip, the tip region is a powerful contributor to blade response. The present tip aerodynamic model in Y 201 is based on a simple two-dimensional sweep theory. The geometric tip sweep is assumed to define the aerodynamic sweep of the tip. The Y201 program thus employs this assumption together with the calculation of the local flow velocity vectors normal to and along the local swept axis of the blade. This approach is based on the classical approach to rotary wing aerodynamics. The validity of simple sweep assumption applied to the tip region of the rotor blade is an area that clearly needs further study. Simple sweep theory is most valid on high aspect ratio yawed wing. Where a wing is truncated (e.g., at the tip) three dimensional departures obviously come into play. A large body of fixed wing lifting surface calculations has confirmed these phenomena. See Reference 5 for example. Consequently, because the tip region is critical to the simulation of accurate blade responses, a dedicated study of the adequacy of two-dimensional sweep theory is justified. This should include experimental work as well as application of the three-dimensional lifting surface analyses applicable to rotating wings and fixed wings. This study might include a comparison of pressures on elastic fixed wings calculated from lifting surface and simple sweep theory. Motivation for including elasticity is that equations for the relative flow velocity vector indicate that elastic displacements can have a significant effect on the velocity component normal to the tip surface. A change in inflow angle $\phi$ of 1 to 2 degrees can be induced by flatwise deflections between unswept and swept blade regions. Simple sweep theory will magnify the inflow angle $\phi$ and pressure changes beyond the correct three dimensional values. Thus the appropriateness of the aerodynamic model becomes even more important for elastic blades than for rigid blades.

To complement the analytic work on tip aerodynamics, pressure and/or laser velocometer measurements (of circulation) to measure tip loading details should be made.

## Rotor Inflow Velocities and Wake Structure

Rotor blade loading is intimately related to the flow field induced by the rotor. The calculations made herein have employed the rotary wing equivalent to the classical fixed-wing, finite-span, lifting-line theory. Wake distortions are neglected as are lifting surface effects which are expected to be significant near the tip (as discussed in the preceeding section) and in blade-vortex encounters. While these assumptions would appear reasonable (except in the tip area) for computing lower harmonics of loading at the advance ratios considered in this report, a complete experiment to validate the inflow-airloading analysis has not been conducted.

Laser velocimeter technology is now becoming generally available. It is capable of making the desired measurements. UTRC, for example, has measured wake structure and induced velocities under a rotor using laser velocimetry techniques for the U.S. Army Research Office. This work is reported in Reference 4. It is believed that the measurements should be made using moderate scale ( 2.84 m . diameter) model rotor systems, like the one used in this study (See Figure 6). This model rotor system is sufficiently large to prevent large Reynold number effects. Moreover a model of this size permits an area over which the velocity measures would be required to be of reasonable size. The model can also be made with nonflexible blades or can be scaled to represent full scale structural properties (and, thus the elastic deflections mentioned above) and operate at full scale Mach numbers. Also, it can be internally instrumented to allow detailed blade elastic deformations to be determined. The blades used in this study or the blades built specifically to study elastic deformations for the U.S. Army Research and Technology Laboratories (Reference 6) are specific blade examples.

## CONCLUSIONS

## Full Scale Baseline Rotor Test Results

1. Rotor hover performance can be measured to within +0 to $-4 \%$ in the NASA/ Ames $40 \mathrm{ft} .(12.2 \mathrm{~m})$ by $80 \mathrm{ft} .(24.4 \mathrm{~m})$ wind tunnel using rotors of the size of ATRS or smaller.
2. Helicopter rotor forward flight performance can be predicted for substantially unstalled conditions to within $+5 \%$ of the flight test measurements up to an advance ratio of .4 using aerodynamically similar, full scale wind tunnel models.
3. The maximum outboard rotor blade $\frac{1}{2} p-p$ dynamic loads are generally predicted to about $80 \%$ of the flight test values using data from a dynamically similar, full scale wind tunnel model rotor. Closer agreement would result if the aircraft fuselage were included in the wind tunnel test.

## 1/5 Scale Baseline Rotor Test Results

1. Due to Reynolds number effects, a $1 / 5$ scale model rotor predicts poorer full scale helicopter forward flight performance throughout the flight envelope. At $\mu=.375$ and a rotational Mach number, $M_{T}=.6$, the overprediction of power amounts to nominally $20 \%$.
2. If model blade dynamic characteristics are scaled faithfully, then model blade $\frac{1}{2}$ p-p dynamic loads will reasonably predict full scale dynamic loads.
3. If model blade dynamic characteristics differ, the analysis can be used to provide corrected results that agree well with flight data.

Alternate Tip Effects From Full Scale Test Results

1. Combining tip aft sweep and tip planform taper is effective in reducing main rotor power over the cruise envelope. Applying each individually also provides for reductions in rotor power, but to a lesser extent.
2. The effect on blade $\frac{1}{2} p-p$ vibratory blade loads of three alternate tips is small at $\mu=.3$. However, as advancing blade tip Mach number ( $\mathrm{M}_{1}, 90$ ) approaches .9, blade control loads and flatwise $\frac{1}{2} p-p$ loads are significantly reduced for swept, tapered tip configurations covering spans as small as $5 \%$ of the rotor radius.
3. The time history signatures of the blade control and bending loads for the various tips at $\mu=.375$ ( 150 kts ) show that when tip sweep and planform taper are utilized alone, modest reductions in peak loads are achieved as compared to the conventional rectangular tip loads. However, when tip sweep and taper are combined, substantial reductions in the higher harmonic loads are achieved.

## Analytic Results

## Performance

1. The Y201 elastic blade analysis predicts main rotor level flight performance to within $+5 \%$ at 150 kts for blade loadings below. 08. At the higher blades loadings investigated by this study (.095) the analysis becomes optimistic. This would be improved by using a more accurate skewed flow model in the analysis.
2. Performance-oriented, rigid blade analyses, on the other hand, predict performance well for all conditions except those involving significant retreating blade stall.
3. The effect of reducing Reynolds number to $1 / 5$ scale model values is overpredicted. This is attributed to the $1 / 5$ scale model airfoil data used, which is compromised by wall effects at high lift, shock effects at high Mach number on wake rake drag measurements. (Note, unsteady effects were not used to make this comparison in either the full scale or the $1 / 5$ scale model analysis.)
4. At and above 150 kts , the Y 201 analysis predicts improvement trends in rotor performance due to tip sweep, taper and the combination thereof, which are consistent with full scale test results.

## Blade Vibratory Loads

1. A comparison of predicted blade vibratory loads with test data using Sikorsky Aircraft's rotor blade dynamic program, normal modes (Y201) shows that the analysis generally is very optimistic when using variable inflow. The use of constant inflow provides the best correlation, still underpredicting, but exhibiting very similar trends (relative to full scale flight data) in $\frac{1}{2} p-p$ vibratory loading.
2. The analysis predicts that, as compared to a conventional rectangular tip design, blade tip sweep or planform taper tends to reduce blade $\frac{1}{2} \mathrm{p}-\mathrm{p}$ vibratory loads in cruise flight. The test data generally confirm these trends. The magnitude of the predicted reductions tended to be larger than measured.
3. The calculated effect of the fuselage flow field is to increase the blade vibratory flatwise bending and torsional moments relative to those predicted for an isolated rotor. The predicted changes in loads due to fuselage flow were qualitatively similar to, but larger than those observed when full scale flight and wind tunnel model test data are compared. This was consistent with the presence of some flow distortion effects due to the wind tunnel test module.

## RECOMMENDATIONS

1. Conduct further analytic studies to understand, in more detail, the sensitivity of the results presented to the assumptions made in the analysis.
2. Conduct analytic studies to develop a better approximation for modeling the three-dimensional flow effects on blades having swept tips.
3. Conduct unsteady airfoil tests to provide aerodynamic load characteristics in the region of stall as a function of skew angle and Mach number.
4. Conduct a sub-scale and full scale model test to measure the details of the flow, air loading and blade response on a rotor blade having swept tips.

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Main rotor blade


| Main rotor parameters |  |  |  |
| :--- | :---: | :--- | :--- |
| Radius | 22 ft | Flapping hinge offset | $3.79 \%$ radius |
|  | $(6.706 \mathrm{~m})$ | Lock no. | 11.6 |
| Nominal chord | 15.5 in. | $100 \%$ rpm | 293 |
|  | $(39.37 \mathrm{~cm})$ | $100 \% \Omega R$ | 675 fps |
| Solidity ratio | .0748 |  | $(205.74 \mathrm{mps})$ |
| Number of blades | 4 |  |  |
| Airfoils | SC1095 |  |  |

Figure 1 - Geometry details of the advanced technology rotor system main rotor blade.


Figure 2 - Flight test vehicle


Figure 3 - Flight test vehicle for advanced technology rotor system.


Figure 4 - ATRS full scale model installed in NASA Ames $40 \mathrm{ft} \times 80 \mathrm{ft}$ wind tunnel.


Figure 5 - Advanced technology rotor system swept tapered and alternate tips


Figure $6-1 / 5$ Scale ATRS model installed in the 18 ft section of the UTRC wind tunnel.


Figure 7 - Sikorsky advanced geometry 44 foot rotor blade bending and torsion frequencies.


Figure 8 -Flight test vehicle. Total corrected configuration drag.

## Level flight

$$
f=12.23 \mathrm{ft}^{2}\left(3.72 \mathrm{~m}^{2}\right)
$$



Figure 9, 10 - Main rotor torque coefficient/solidity versus advance ratio.
Flight tests compared with model tests.

## Level flight

$\mathrm{f}=12.23 \mathrm{ft}^{2}\left(3.72 \mathrm{~m}^{2}\right)$


Figures 11, 12 - Main rotor torque coefficient/solidity versus advance ratio. Flight test compared with model tests.


Figure 13 - Comparsion of measured flight and full scale model measured rotor torque coefficient/solidity vlaues.


Figures 14, 15 -Main rotor profile torques compared.


Figure 16,17 - Main rotor profile torques compared.


Figure 18 - Advanced technology rotor system hover performance.


Figures 19, 20 - Main rotor blade vibratory bending moment coefficient/solidity versus blade span. Flight test compared with model tests and analysis.


Figures 21, 22 - Calculated 1/2 P-P flatwise bending moment versus blade span. Effect of mass and edgewise stiffness distribution differences between full scale and $\mathbf{1 / 5}$ scale model blades.


Figures 23, 24 - Calculated 1/2 P-P edgewise bending moment versus blade span. Effect of mass and edgewise stiffness distribution differences between full scale and $1 / 5$ scale model blades.


Figures 25, 26 - Main rotor blade vibratory push rod load coefficient/solidity versus advance ratio. Flight test compared with model tests and analysis.


Figure 27-Main rotor blade vibratory push rod load coefficient/solidity versus advance ratio. Flight test compared with model tests and analysis.


Figure 28 -Main rotor blade vibratory flatwise bending moment coefficient (NB-7)/solidity. versus advance ratio. Flight test compared with model tests and analysis.


Figures 29, 30-Main rotor blade vibratory flatwise bending moment coefficient (NB-7)/solidity. versus advance ratio. Flight test compared with model tests and analysis.


Figures 31, 32 - Flight and wind tunnel lateral stationary star control load coefficient/solidity versus advance ratio.


Figures 33, 34, 35- Resultant amplitude of main rotor blade load versus harmonic number. Flight and full scale model.

$$
\begin{aligned}
& \mathrm{GW}=8200 \mathrm{lb}(3719.5 \mathrm{~kg}) \\
& \text { Level flight } \\
& \mu=.4 \\
& M_{T}=.6 \\
& f=12.23 \mathrm{ft}^{2}\left(3.73 \mathrm{~m}^{2}\right)
\end{aligned}
$$




Figures 36, 37 - Resultant amplitude of main rotor blade load versus harmonic number. Flight and full scale model.

$$
\begin{aligned}
& \mathrm{GW}=10,300 \mathrm{lb}(4672 \mathrm{~kg}) \\
& \text { Level flight } \\
& \mu=.375 \\
& \mathrm{M}_{\mathrm{T}}=.6 \\
& \mathrm{f}=12.23 \mathrm{ft}^{2}\left(3.73 \mathrm{~m}^{2}\right)
\end{aligned}
$$




Figures 38, 39 - Resultant amplitude of main rotor blade load versus harmonic number. Flight and full scale model.

$$
\begin{aligned}
& \mathrm{GW}=10,300 \mathrm{lb}(4672 \mathrm{~kg}) \\
& \text { Level } \mathrm{flight} \\
& \mu=.375 \\
& M_{T}=.65 \\
& \mathrm{f}=12.23 \mathrm{ft}^{2}\left(3.73 \mathrm{~m}^{2}\right)
\end{aligned}
$$




Figures 40, 41 - Resultant amplitude of main rotor blade load versus harmonic number. Flight and full scale model.


Figures 42, 43 - Main rotor blade push rod load coefficient/solidity versus blade azimuth. Flight test compared with full scale model and analysis.


Figures 44, 45 - Main rotor blade push rod load coefficient/solidity versus blade azimuth. Flight test compared with full scale model and analysis.


Figures 46, 47 - Main rotor blade bending moment coefficient/solidity versus blade azimuth. Flight test compared with full scale model and analysis.


Figures 48, 49 - Main rotor blade flatwise bending moment coefficient/solidity versus blade azimuth. Flight test compared with full scale model and analysis.


Figure 50 - Main rotor blade flatwise bending moment coefficient/solidity versus blade azimuth. Flight test compared wiht full scale model and analysis.


Figures 51, 52 - Effect of tip configuration on trimmed level flight performance. Full scale model test data compared with analysis.

```
5% Span tip
\mu=.375
f=12.23 ft2 (3.72m')
```

$M_{T}=.65$



Figures 53, 54 - Effect of tip configuration on trimmed level flight performance. Full scale date compared with analysis.


Figures 55, 56 - Effect of tip configuration on blade vibratory push rod load. Full scale model test data and comparison with analysis.


Figures 57, 58 - Effect of tip configuration on blade vibratory push rod load.
Full scale model test data and comparison with analysis.


Figures 59, 60 -Effect of tip configuration on blade vibratory flatwise bending moment (NB-7). Full scale test model data and comparsion with analysis.


Figures 61, 62 -Effect of tip configuration on blade vibratory flatwise bending moment (NB-7). Full scale test model data and comparsion with analysis.

$$
\begin{aligned}
& 5 \% \text { Span tip } \\
& M_{T}=.6 \\
& f=12.23 \mathrm{ft}^{2}\left(3.73 \mathrm{~m}^{2}\right)
\end{aligned}
$$




Figures 63, 64- Effect of tip configuration on blade vibratory edgewise bending moment (EB-7). Full scale model test data and comparison with analysis.


Figure 65 - Effect of tip configuration on blade vibratory edgewise bending moment (EB - 7). Full scale model test data and comparison with analysis.

| $\mathrm{GW}=10,500 \mathrm{lb}(4680 \mathrm{~kg})$ | - | Rectangular |
| :--- | :--- | :--- |
| Level flight | $-\infty-\infty$ | Tapered |
| $\mu=.375$ | - | Swept |
| $\mathrm{f}=12.23 \mathrm{ft}^{2}\left(3.73 \mathrm{~m}^{2}\right)$ | - | Swept tapered |




Figures 66, 67 - Effect of tip configuration on blade push rod load time history.




Figures 68, 69 - Effect of tio configuration on blade flatwise bending moment (NB-6) time history

## Level flight

$\mathrm{f}=12.23 \mathrm{ft}^{\mathbf{2}}\left(3.72 \mathrm{~m}^{2}\right)$



Figures 70, 71 - Main rotor torque coefficient/solidity versus advance ratio. Model tests compared with analysis.


Figures 72, 73 - Main rotor torque coefficient/solidity versus advance ratio. Model tests compared with analysis.


Figure 74 - Y201 Skewed flow lift stall model.


Figure 75 - Effect of fuselage on blade push rod load time history. Test and calculated results.


Figure 76 - Effect of fuselage on blade flatwise bending moment time history. Test and calculated results.


Figure 77 -Effect of fuselage on blade push rod load
time history. Test and calculated results.
Figure 77 -Effect of fuselage on blade push rod load
time history. Test and calculated results.



Figure 78 - Effect of fuselage on blade flatwise bending moment time history. Test and calculated results.


Figure 79 - Effect of fuselage on blade push rod load time history. Test and calculated results.


Figure 80 - Effect of fuselage on blade flatwise bending moment. time history. Test and calculated results.


Figure 81 - Effect of fuselage on blade push rod load
time history. Test and calculated results.
Figure 81 - Effect of fuselage on blade push rod load
time history. Test and calculated results.



Figure 82 - Effect of fuselage on blade flatwise bending moment time history. Test and calculated results.

Flight vehicle, $\mathrm{a}_{\mathrm{E}}=00$
NASA/AMES RTA, $a_{E}=-5^{\circ}-\infty$ -


Figure 83 - Effect of fuselage flow on rotor blade local angle of attack in the longitudinal plane of symmetry.
APPENDIX A
ATRS Flight Test Rotor Blade Structural and Mass Properties










TABLE A. 1 Continued

| $\Delta r / R$ | $r / R$ | Flatwise Stiffness$E I_{f} \times 10^{-6}$ |  | Edgewise Stiffness$E_{e} \times 10^{-6}$ |  | Torsional Stiffness GJ $\times 10^{-6}$ |  | Chord C |  | Blade <br> Twist <br> $\theta 1$ <br> Deg |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | $L b-i n{ }^{2}$ | (kgf-cm ${ }^{2}$ ) | Lb-in ${ }^{2}$ | $\left.\mathrm{kgf}-\mathrm{cm}^{2}\right)$ | $L B-i n^{2}$ | gf-cm ${ }^{2}$ | Ft | (cm) |  |
| . 0540 | . 0649 | 11.60 | (33.95) | 11.52 | (33.71) | 15.00 | (43.90) | 0.0 | (0.0) | 0.0 |
| . 0975 | . 1406 | 21.67 | (63.42) | 152.5 | (446.3) | 16.20 | (47.41) | . 777 | (23.68) | 2.04 |
| . 1136 | . 2462 | 9.69 | (28.36) | 232.7 | (681.0) | 11.30 | (33.07) | 1.304 | (39.75) | 4.45 |
| . 0758 | . 3409 | 7.36 | (21.54) | 232.5 | (680.4) | 9.02 | (26.40) | 1.304 | (39.75) | 4.09 |
| . 0758 | . 4167 | 5.99 | (17.53) | 232.1 | (679.2) | 7.55 | (22.09) | 1.304 | (39.75) | 3.33 |
| . 0758 | . 4925 | 5.40 | (15.80) | 225.5 | (659.9) | 7.0 | (20.49) | 1.304 | (39.75) | 2.58 |
| . 0758 | . 5693 | 5.40 | (15.80) | 225.5 | (659.9) | 7.0 | (20.49) | 1.304 | (39.75) | 1.82 |
| . 0758 | . 6441 | 5.40 | (15.80) | 225.5 | (659.9) | 7.0 | (20.49) | 1.304 | (39.75) | 1.06 |
| . 0568 | . 7104 | 5.67 | (16.59) | 248.0 | (725.8) | 7.133 | (20.87) | 1.304 | (39.75) | . 40 |
| . 0568 | . 7672 | 5.72 | (16.74) | 248.0 | (725.8) | 7.160 | (20.95) | 1.304 | (39.75) | -. 17 |
| . 0379 | . 8145 | 5.52 | (16.15) | 240.0 | (702.3) | 7.018 | (20.54) | 1.298 | (39.56) | -. 64 |
| . 0568 | . 8619 | 5.31 | (15.54) | 198.5 | (580.9) | 6.876 | (20.12) | 1.292 | (39.37) | -1.12 |
| . 0610 | . 9208 | 5.27 | (15.42) | 207.4 | (606.9) | 6.810 | (19.93) | 1.292 | (39.37) | -1.71 |
| . 0246 | . 9636 | 2.99 | (8.75) | 144.8 | (423.7) | 3.100 | (9.07) | 1.205 | (36.73) | -2.13 |
| . 0246 | . 9882 | 1.09 | (3.19 | 60.40 | (176.8) | . 979 | (2.86) | . 923 | (28.13) | -2.38 |

TABLE A. 1 Concluded

| $\Delta r / R$ | $r / R$ | Distance From e.a. Fwd to $\mathrm{C} / 4$ (+ for $\mathrm{C} / 4 \mathrm{Fwd}$ ) |  | Modulus Weighted Radius of Gyration About Elastic Axis$\left[\frac{1}{E A} \int_{y^{2} E d A}\right]^{\frac{1}{2}}$ |  | Structural Area EA $\times 10^{-6}$ |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Ft | (cm) | Ft | (cm) | Lb | (kgf) |
| . 054 | . 0649 | 0.0 | (0.0) | . 0658 | (2.006) | 31.0 | (14.1) |
| . 0975 | . 1406 | -. 0042 | (-.128) | . 187 | (5.700) | 24.0 | (10.9) |
| . 1136 | . 2462 | -. 0216 | (-.658) | . 239 | (7.285) | 18.0 | (8.2) |
| . 0758 | . 3409 | -. 087 | (-.570) | . 239 | (7.285) | 18.0 | (8.2) |
| . 0758 | . 4167 | -. 0172 | (-.524) | . 239 | (7.285) | 18.0 | (8.2) |
| . 0758 | . 4925 | -. 017 | (-.518) | . 238 | (7.285) | 17.5 | (7.9) |
| . 0758 | . 5683 | -. 017 | (-.518) | . 238 | (7.285) | 17.5 | (7.9) |
| . 0758 | . 6441 | -. 017 | (-.518) | . 238 | (7.285) | 17.5 | (7.9) |
| . 0568 | . 7104 | -. 0448 | (-1.366) | . 244 | (7.437) | 19.0 | (8.6) |
| . 0568 | . 7672 | -. 0448 | (-1.366) | . 244 | (7.437) | 19.0 | (8.6) |
| . 0379 | . 8145 | -. 042 | (-1.280 | . 255 | (7.772) | 19.0 | (8.6) |
| . 0568 | . 8619 | -0.398 | (-1.218) | . 267 | (8.137) | 19.0 | (8.6) |
| . 0610 | . 9208 | -. 0398 | (-1.213) | . 267 | (8.137) | 19.0 | (8.6) |
| . 0246 | . 9636 | -. 1584 | (-4.828) | . 285 | (8.687) | 12.0 | (5.4) |
| . 0246 | . 9882 | -. 4246 | (-12.942) | . 231 | (7.041) | 8.0 | (3.6) |

Table A. 2 Miscellaneous Blade and Control System Properties
Units

Ft-Lb/Rad. (m-kgf/Rad.)
Ft-Lb/Rad. (m-kgf/Rad.)
Ft-Lb/Rad. (m-kgf/Rad.)
Deg.
$\%$
Ft $(\mathrm{m})$
Ft $(\mathrm{cm})$
Ft $(\mathrm{cm})$ Blade Mass
Blade First Moment of Inertia about Lag Hinge
Blade Second Moment of Inertia about Flap Hinge
Elastomeric Hinge Flap and Hinge Spring Constant
Effective Control System Stiffness
Elastomeric Hinge Bearing Torsional Stiffness
Collective Pitch for Zero Static Elastomeric
Hinge Torsion
Structural Damping (bending and torsion) Radius Flap and Lag Hinge Offset
Aerodynamic Root Cutout
APPENDIX B

Table B. 1 ATRS Full Scale Model Blade Swept Tapered and Alternate Tips | ITEM |  |  | QUANTITY |  |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| Tip Configuration |  | $\begin{array}{c}\text { Swept } \\ \text { Tapered }\end{array}$ | Trapezoidal |  | $\begin{array}{c}\text { Swept } \\ \text { Untapered }\end{array}$ | Rectangular |

Table B. 1 Concluded

| ITEM |  | quantity |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Tip Configuration | Swept Tapered | Trapezoidal | Swept Untapered | Rectangular |
| Total Tip Mass, slugs (kg) | $\begin{aligned} & .066 \\ & (.963) \end{aligned}$ | $\begin{aligned} & .063 \\ & (.919) \end{aligned}$ | $\begin{gathered} .075 \\ (1.095) \end{gathered}$ | $\begin{gathered} .080 \\ (1.168) \end{gathered}$ |
| Total Tip Chordwise Mass Moment, Slug-ft, + fwd (kg-m) | $\begin{gathered} -.0163 \\ (-.0725) \end{gathered}$ | $(-.0119)(-.0529)$ | $(-.0264)(-.1174)$ | $\begin{gathered} -.0167 \\ (-.0743) \end{gathered}$ |
| Total Tip Moment of Inertia, $\begin{gathered} \text { Slug-ft }{ }^{2} \\ \left(\mathrm{~kg}-\mathrm{m}^{2}\right) \end{gathered}$ | $\begin{array}{r} .00856 \\ (.0116) \end{array}$ | $\begin{gathered} .0049 \\ (.0066) \end{gathered}$ | $\begin{gathered} .0151 \\ (.0205) \end{gathered}$ | $\begin{gathered} .0086 \\ (.0117) \end{gathered}$ |
| Tip Outboard Chord/Inboard Chord | . 6 | . 6 | 1.0 | 1.0 |
| Tip Leading Edge Sweep (deg) | 35.0 | 6.9 | 20.0 | 0.0 |
| Tip Quarter Chord Sweep (deg) | 30.0 | 0.0 | 20.0 | 0.0 |
| Tip Trailing Edge Sweep (deg) | 10.0 | -19.9 | 20.0 | 0.0 |

APPENDIX C
1/5 Scale Model Blade and Mass Properties
(Converted to Full Scale Values)




.



Table C． 1 Concluded





 $\Delta R$


 が⿴囗十

## $r / R$


Miscellaneous ATRS Rotor Head and Aircraft Physical Properties
Table D. 1 Main Rotor Properties

Ft-1b-sec (m-kgf-sec) Ft (m)
Deg
Ft (m)
Deg
Deg
Deg

ITEM

## Direction of Rotation

Number of Blades Typical Equivalent Viscous Lag Hinge Damping Radial Station of Damper Outboard End Axis
Distance of Damper Inbord End Aft of Feathering Axis Collective Pitch for Feathering and Damper Axis Coplanar with 60 Coning
Blade pushrod Horn Length
Radial Position of Blade Pushrod at Horn
Radial Position of Blade Pushrod at Swashplate Blade Pushrod Length
Blade Lag Angle for Coplanar Blade Pushrod and Rotor
Radial Position of Stationary Pushrods
Azimuth Position of FLSS Pushrod
Azimuth Position of ALSS Pushrod
Azimuth Position of LSS Pushrod
See Figure 7 for Blade Natural Frequencies

APPENDIX D CONTINUED


$$
\begin{aligned}
& \text { Gross Weight } \\
& 1 \mathrm{~b}(\mathrm{~kg}) \\
& 8200(3719.5) \\
& 10300(4672) \\
& 10300(4672)
\end{aligned}
$$

## APPENDIX D CONCLUDED

Data
 C.G. Buttline
Inches
0
0
0

Table D. 4 Flight Test Vehicle

$\begin{array}{lr}\text { C.G. Station } & \\ \text { Inches } & (\mathrm{cm}) \\ & \\ 210 & (533) \\ 210 & (533) \\ 197 & (500)\end{array}$

$$
\begin{array}{cc}
(Z \angle 9 t) & 00 \varepsilon 0 T \\
(Z \angle 9 t) & 00 \varepsilon 0 I \\
(G \cdot 6 L \angle \varepsilon) & 0028 \\
(6 y) & q L \\
746!\partial M & \text { SSOAD }
\end{array}
$$



## APPENDIX E <br> Airfoil Section Aerodynamic Characteristics

Full scale section characteristics for the SC-1095 and SC-1095R8 airfoils are presented in Tables E1 and E2 of this appendix. These data were obtained from two-dimensional steady tests conducted in the 8 ft . octagonal cross section wind tunnel at United Technology Research Center during 1975. Data was obtained using the Sikorsky Tunnel Spanning apparatus. This test technique uses a tunnel spanning airfoil that isolates a 8 -inch span metric section at the spanwise mid point. Forces and moments on this section are measured with an internal balance system. In addition, upper and lower surface pressure taps provide an independent measure of section lift and pitching moment. Also, a wake rake is used to determine section drag prior to divergence. The angle-of-attack is referenced to the airfoil section's chordline. The airfoil moments are resolved about the quarter chord position.

Model scale section coefficients for the SC-1095 and SC-1095R8 airfoils are presented in Tables E3 and E4 respectively. Supporting tests for this data was obtained in the NASA Langley 6" x 28" variable density tunnel during 1977. Use of the variable density facility permitted data to be obtained at both high Reynolds numbers representative of full scale rotor and reduced Reynolds numbers applicable to the $1 / 5$ th scale model rotor. The Langley results were analyzed to define incremental changes in section lift and drag coefficients that were applied to the baseline full scale data obtained at the United Technologies Research Center. This approach was adapted to reflect Reynolds number changes in the section characteristics without introducing bias due to a change in the test facility and procedures. It should be noted that no Reynolds number corrections were applied to the pitching moment coefficient data. This decision was based on a Reynolds number insensitivity noted in the Langley data.

Table E. 1 - Aerodynamic coefficients for full scale airfoil section SC1095


Table E. 1 - continued


Table E. 1 - concluded

| $\begin{aligned} & \text { CMOAT } \\ & \text { ※* SC1095 } \\ & \text { ALPHA } \end{aligned}$ | $5.5 \mathrm{TAB}_{\mathrm{CM}}-3$ | 3 DEF. MOMEN | T BASED ON | 1975 TSR | TESTS ** |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |
| -125.00 | . 55700 | $0-90.00$ | . 55500 | -60.00 | . 39500 | -30.00 | . 16500 |
| -30.016.0 | . 1437 | -10.0 | . 0799 | -8.0 | -. 0009 | 12.0 | . 0084 |
|  | -. 1482 | 30.0 | -. 1437 | 30.1 | -. 1437 | 34.9 | -. 222 |
| 16.0 | -. 22200 | - 45.00 | -. 29500 | 60.00 | -. 39500 | 80.00 | -. 50000 |
| 95.00 | -. 55500 | 0110.00 | -. 56000 | 125.00 | $\therefore .55700$ | 135.00 | -. 53800 |
| 145.00 | -. 43100 | - 150.00 | -. 43300 | 160.00 | -. 30000 | 174.00 | -. 35900 |
| 180.00 | -. 01300 |  |  |  |  |  |  |
| NPTS \#29. | MACH \# | \# 3000 | THICK \# | . 0950 |  |  |  |
| -180.00 | -. 01300 | - 174.00 | . 35900 | -160.00 | . 30000 | -145.00 | . 48100 |
|  | . 55700 | - -90.00 | . 55500 | -60.00 | . 39500 | -30.00 | .16500 |
| -30.0 | . 1437 | -10.0 | . 0799 | -8.0 | -. 0009 | 12.0 | . 0084 |
|  | . 1482 | 30.0 | -. 1437 | 30.1 | $-.1437$ | 34.9 | -. 222 |
| 35.0095.00 | -. 22200 | - 45.00 | -. 29500 | 60.00 | -. 39500 | 80.00 | -. 50000 |
|  | -. 55500 | $0 \quad 110.00$ | -. 56000 | 125.00 | -. 55700 | 135.00 | -. 53800 |
| 95.00 145.00 | -. 48100 | - 150.00 | -. 43800 | 160.00 | -. 30000 | 174.00 | 35900 |
| 145.00 180.00 | -. 01300 |  |  |  |  |  |  |
| NPTS \# 9 | - mach \# | \# . 4000 | тнICK \# | . 0950 |  |  |  |
| $\begin{array}{r} -30.0 \\ 10.0 \end{array}$ | . 1437 | -10.0 | . 1364 | -6.0 | -. 0009 | 6.0 | . 0052 |
|  | . 0110 | 11.2 | . 0039 | 12.4 | -. 0952 | 16.0 | -. 1329 |
|  | . 1437 |  |  |  |  |  |  |
| NPTS \# | MACH | 5000 | THICK \# | 0950 |  |  |  |
| -30.0 | . 1437 | -10.0 | . 1336 | -6.0 | -. 0019 | 9.0 | . 0038 |
|  | -. 0130 | 12.0 | -. 0860 | 14.0 | -. 1254 | 16.0 | -. 1548 |
| $\begin{aligned} & 10.0 \\ & 30 \end{aligned}$ | -. 1437 |  |  |  |  |  |  |
| NPTS \# | MACH \# | \# . 6000 | THICK \# | . 0950 |  |  |  |
| -30.07.4 | . 1437 | -10.0 | . 0975 | -5.0 | -. 0069 | . 2 | . 0073 |
|  | -. 0099 | 13.0 | -. 0079 |  | -. 1263 | 16.0 | -. 1549 |
| \% <br> -7.4 <br> 30.0 | -. 1437 |  |  |  |  |  |  |
| NPTS \# 10 | MACH | . 7000 | THICK \# | . 0950 |  |  |  |
| $\begin{array}{r} -30.0 \\ \quad 2.0 \\ \hline \end{array}$ | . 1437 | -10.0 | . 0947 | -6.0 | . 0834 | -4.0 | -. 0134 |
|  | . 0032 | 4.0 | -. 0132 | 6.0 | -. 0814 | 8.0 | -. 0954 |
| 15.0 | -. 1560 | 30.0 | -. 1437 |  |  |  |  |
| NPTS \# 10 | mach \# | \# . 7500 | THICK \# | . 0950 |  |  |  |
|  | . 1437 | -10.0 | . 1235 | -6.0 | . 1236 | -2.8 | -. 0209 |
| $\begin{array}{r} -30.0 \\ 1.4 \end{array}$ | . 0071 | 2.6 | -. 0319 | 4.0 | -. 0942 | 5.4 | -. 1135 |
| 15.0 | . 1581 | 30.0 | . 1437 |  |  |  |  |
| NPTS $\begin{array}{r}\text { \#15 } \\ -30.00\end{array}$ | МасС \# | \# . 8 | thick \# | . 095 |  |  |  |
|  | . 15000 | - -8.00 | . 07500 | -6.00 | . 06000 | -4.00 | . 03500 |
| $\begin{array}{r}-30.00 \\ -2.00 \\ \hline 20\end{array}$ | -. 01200 | 0 - | -. 02000 | 50 | -. 01500 | 1.00 | -. 01200 |
| 1.50 | -. 01700 | 02.00 | -. 02900 | 4.00 | -. 07500 | 6.00 | -. 10000 |
| NPTS ${ }^{\text {\% }}$ | -. 11500 | $0 \quad 18.00$ | -. 13000 | 30.00 | -. 15000 |  |  |
|  | maCH \# | \# - 9 | THICK \# | . 095 |  |  |  |
| NPTS -30.00 | . 14000 | 0 ... ....-8.00 | ... 12000 | -6.00 | . . 09700 | -4.00 | . 04300 |
| -2.00 | -. 01200 | 0. | -. 02000 | . 10 | -. 00100 | . 25 | . 01200 |
|  | . 01700 | - 75 | . 00900 | 1.00 | -.00700 | 1.50 | $\therefore .03000$ |
| $\begin{array}{rrrrrrr}2.00 & -.03500 & 4.00 & -.08300 & 6.00 & -.13700\end{array}$ |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |
| NPTS $\begin{array}{r}\text { \#17. } \\ -30.00\end{array}$ | mach \# |  | THICK \# | . 095 |  |  |  |
|  | . 14000 | - -8.00 | . 12000 | -6.00 | . 09700 | -4.00 | . 04300 |
| -30.00 -2.00 | -. 01200 | 0.00 | -. 02000 | . 10 | -. 00100 | . 25 | . 01200 |
|  | ... 01700 | - .... ...... 75 | $\ldots .00900$ | 1.00 | -. 00700 | 1.50 | $\bigcirc .0300$ |
|  | -. 03500 | - 4.00 | $-.08300$ | 6.00 | -. 13700 | 8.00 | -. 16000 |
| $\begin{array}{r} 2.00 \\ 30.00 \end{array}$ | -. 19000 |  |  |  |  |  |  |
| NPTS \#17. | MACH ${ }^{\text {\# }}$ | \# 2. | THICK \# | . 095 |  |  |  |
| -30.00-2.00 | . 14000 | - -8.00 | . 12000 | -6.00 | . 09700 | -4.00 | . 04300 |
|  | -. 01200 | 0.00 | -. 02000 | . 10 | -. 00100 | . 25 | . 01200 |
| . 50 | . 01700 | 0 . 75 | .00900 | 1.00 | -. 00700 | 1.50 | -. 03000 |
| $\begin{array}{r} 2.00 \\ 30.00 \end{array}$ | -. 03500 | $0 \quad 4.00$ | -. 08300 | 6.00 | -. 13700 | 8.00 | -. 16000 |
|  | -. 19000 |  |  |  |  |  |  |

Table E. 2 - Aerodynamic coefficients for full scale airfoil section SC1095-R8


Table E. 2 - continued


Table E. 2 - concluded

| CMDAT2 |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  |  |  |  |
| NPTS \#33. | MACH \# | . 0000 | THICK \# | . 0900 |  |  |  |
| -180.00 | -. 01300 | -174.00 | . 35900 | -160.00 | .30000 | -145.00 | . 48100 |
| -125.00 | . 55700 | -90.00 | . 55500 | -60.00. | . 39500 | -30.00 | . 16500 |
| -30.0 | . 1437 | -10.0 | . 1065 | -7.4 | . 0989 | -6.4 | . 0052 |
| -5.0 | . 0032 | 4.0 | . 0017 | 14.0 | . 0135 | 15.2 | -. 0932 |
| 19.0 | -. 1303 | 30.0 | -. 1437 | 30.1 | -. 1437 | 34.9 | -. 222 |
| 35.00 | -. 22200 | 45.00 | -. 29500 | 60.00 | -. 39500 | 60.00 | -. 50000 |
| 95.00 | -. 55500 | 110.00 | -. 56000 | 125.00 | -. 55700 | 135.00 | -. 53800 |
| 145.00 | -. 48100 | 150.00 | -. 43800 | 160.00 | -. 30000 | 174.00 | -. 35900 |
| $180.00-.01300$ |  |  |  |  |  |  |  |
| NPTS \#.... 33. |  |  |  |  |  |  |  |
| -180.00 | -. 01300 | -174.00 | . 35900 | -160.00 | . 30000 | -145.00 | . 48100 |
| -125.00 | . 55700 | -90.00 | . 55500 | -60.00 | . 39500 | -30.00 | . 16500 |
| -30.0 | . 1437 | -10.0 | . 1065 | -7.4 | . 0989 | -6.4 | . 0052 |
| -5.0 ..... | ... 0032 | 4.0 | . 0019 | 14.0 | . 0135 | 15.2 | -. 0932 |
| 19.0 | -. 1303 | 30.0 | -. 1437 | 30.1 | -. 1437 | 34.9 | -. 222 |
| 35.00 | -. 22200 | 45.00 | -. 29500 | 60.00 | -. 39500 | 80.00 | -. 50000 |
| 95.00 | -. 55500 | 110.00 | -. 56000 | 125.00 | -. 55700 | 135.00 | -. 53800 |
| 145.00 | -. 48100 | 150.00 | -. 43800 | 160.00 | -. 30000 | 174.00 | -. 35900 |
| $180.00-.01300$ |  |  |  |  |  |  |  |
| NPTS \# 10 | MACH \# | . 4000 | THICK \# | . 0900 |  |  |  |
| -30.0 | . 1437 | -10.0 | . 1427 | -7.0 | . 1356 | -6. 0 | . 0038 |
| -5.0 | .0019 | 8.0 | . 0124 | 11.2 | . 0115 | 12.2 | -. 1299 |
| 18.0 | -. 1341 | 30.0 | -. 1437 |  |  |  |  |
| NPTS \# 9 | MACH | . 5000 | THICK \# | . 0900 |  |  |  |
| -30.0 | . 1437 | -10.0 | . 1108 | -9.0 | . 0952 | -7.0 | . 0433 |
| -5.0 | . 0045 | 8.0 | . 0031 | 12.0 | -.. 0800 | 16.0 | -. 1293 |
| $30.0 \quad-.1437$ |  |  |  |  |  |  |  |
| NPTS \# Il | MACH \# | . 6000 | THICK \# | . 0900 |  |  |  |
| -30.0 | .1437 | -25.0 | . 1267 | -20.0 | .1047 | -15.0 | . 0878 |
| -10.0 | . 0707 | -3.0 | -. 0004 | 5.0 | . 0087 | 8.0 | -... 0490 |
| $\begin{array}{lllllll}13.0 & -.1415 & 15.0 & -.1352 & 30.0 & -.1437 & \end{array}$ |  |  |  |  |  |  |  |
| NPTS \# 15 | MACH \# | . 7000 | THICK \# | . 0900 |  |  |  |
| -30.0 | . 1437 | -25.0 | . 1416 | -20.0 | . 1397 | -25.0 | . 1327 |
| -10.0 | . 1306 | -3.0 | -. 0119 | . 0 | -. 0025 | 1.0 | -. 0064 |
| 2.0 | -. 0073 | 3.0 | -. 0241 | 4.0 | -. 0569 | 6.0 | -. 1105 |
| 8.0 | -. 1347 | 15.0 | -. 1470 | 30.0 | -. 1437 |  |  |
| $\begin{aligned} & \text { NPTS \# } 18 \\ & -30.0 . . . . . \end{aligned}$ | $\mathrm{MACH} \#$ | . 7500 | THICK \# | . 0900 |  |  |  |
|  | . 1437 | -25.0 | . 1361 | 20.0 | . 1335 | -15.0 | . 1260 |
| $-10.0$ | . 1234 | -8.0 | . 1039 | $-6.0$ | . 0544 | -4.0 | -. 0291 |
| -3.0 | -. 0335 | -2.0 | -. 0245 | . 0 | -. 0146 | 1.0 | -. 0197 |
| 2.0 | -. 0459 | 3.0 | -. 0943 | 4.0 | -. 1154 | 5.0 | -. 1177 |
| 15.0 | -. 1526 | 30.0 | $-.1437$ |  |  |  |  |
| NPTS \#15 | MACH \# | . 8 | THICK \#. 0 | 090 |  |  |  |
| -30.00 | . 25000 | -8.00 | . 07500 | -6.00 | . 06000 | $-4.00$ | . 03500 |
| $-2.00$ | -. 01200 | . 00 | -. 02000 | . 50 | -. 01500 | 1.00 | -. 01200 |
| 1.50 | -. 01700 | 2.00 | -. 02900 | 4.00 | -. 07500 | 6.00 | -. 10000 |
| 8.00 | -. 11500 | 18.00 | -. 13000 | 30.00 | -. 15000 |  |  |
| NPTS \#17. | MACH \# | . 9 | THICK \#. 0 | 090 |  |  |  |
| -30.00 | . 14000 | -8.00 | . 12000 | -6.00 | . 09700 | -4.00 | .04300 |
| .... ...... -2.00 | -. 01200 | . 00 | -. 02000 | . 10 | -. 00100 | . 25 | . 01200 |
| . 50 | . 01700 | . 75 | . 00900 | 1.00 | -. 00700 | 1.50 | -. 03000 |
| 2.00 | -. 03500 | 4.00 | -. 08300 | 6.00 | -. 13700 | 8.00 | -. 16000 |
| $30.00-.19000$ |  |  |  |  |  |  |  |
| NPTS \#17. | .... MACH \# | ..... 1. | THICK \#. 0 | 090 |  |  |  |
| -30.00 | . 14000 | -8.00 | . 12000 | -6.00 | . 09700 | -4.00 | . 04300 |
| -2.00 | -. 01200 | . 00 | -. 02000 | . 10 | -. 00100 | . 25 | . 01200 |
| . 50 | . 01700 | . 75 | . 00900 | 1.00 | -. 00700 | 1.50 | -. 0300 |
| 2.00 | ..... - -03500 | 4.00 | -. 08300 | 6.00 | ... -. 13700 | 8.00 | -. 16000 |
| $30.00-.19000$ |  |  |  |  |  |  |  |
| NPTS \#17. | MACH \# | 2. | THICK \#. 0 | 090 |  |  |  |
| $\begin{array}{r}-30.00 \\ \ldots-. . . . . . \\ \hline-2.00\end{array}$ | . 14000 | -8.00 | . 12000 | -6.00 | . 09700 | -4.00 | . 04300 |
|  | -. 01200 | . 00 | -. 02000 | ....... . 10 | ...-. 00100 | . 25 | ... 01200 |
| . 50 | . 01700 | . 75 | . 00900 | 1.00 | -. 00700 | 1.50 | -. 03000 |
| 2.00 | -. 03500 | 4.00 | -. 08300 | 6.00 | -. 13700 | 8.00 | -. 16000 |
| 30.00 | -. 19000 |  |  |  |  |  |  |

Table E. 3 - Aerodynamic coefficients for model scale airfoil section SC1095


Table E. 3 - continued
CDDAT 109502


| CK 0.095 |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| NPTS | 34. MACH | 0.0 | THICK | 0.095 |  |  |  |
| -180. | . 0222 | -179. | . 0272 | -175. | . 0672 | -172. | . 1122 |
| -150. | - . 6442 | -115. | -1.8822.. | -90. | 2.0822 | 6.5. | 1.8822 |
| -30. | . 6322 | -13. | . 0240 | -12. | . 0196 | -10. | . 0137 |
| -8. | . 0102 | -4. | . 0097 | 0. | . 0097 | 2. | . 0102 |
| 4. | . 0107 | 6. | . 0112 | 8. | . 0132 | 9. | . 0152 |
| 10. | . 019.2 | 11. | . 0222 | 12. | . 0282 | 13. | . $0922 \ldots$ |
| 14. | . 1472 | 15. | . 1872 | 30. | . 6322 | 65. | 1.8822 |
| 90. | 2.0822 | 150. | . 6422 | 172. | . 1122 | 175. | . 0672 |
| 179. | . 0272 | 180. | . 0222 |  |  |  |  |
| NPTS 34. -.. MACH..... D. 3 |  |  |  |  |  |  |  |
| -180. | . 0222 | -179. | . 0272 | -175. | . 0672 | -172. | . 1122 |
| -150. | . 6442 | -115. | 1.8822 | -90. | 2.0822 | -65. | 1.8822 |
| -30. | . 6322 | -13. | . 0240 | -12. | . 0196 | -10. | . 0137 |
| -3. | . 0104 | -4 | . 0097 | 0 | . 0097 | 2. | . $0102 \ldots$ |
| 4. | . 0107 | 6. | . 0112 | 8. | . 0132 | 9. | . 0152 |
| 10. | . 0192 | 11. | . 0222 | 12. | . 0282 | 13. | . 0922 |
| 14. | . 1472 | 15. | . 1872 | 30. | .632? | 65. | 1.8822 |
|  | $2.0822$ | .150... | ...-6422... | ..... 172. | .-1122 | -175. | . 0672 |
| 179. .0272 180. . 0222 20. 0 |  |  |  |  |  |  |  |
| NPTS | 19. MACH | 0.4 | THICK | 0.095 |  |  |  |
| -30. | . 6322 | -14. | . 1492 | -13. | . 1782 | -12. | . 0247 |
| -11. | . 0182 | -10. | . 0154 | -8. | . 0117 | -6. | . 0107 |
| -4. | . 0102 | 0. | . 0102 | 4. | . 0107 | 6. | . 0127 |
| 8. | . 0162 | 9. | . 0182 | 10. | . 0232 | 11. | . 0592 |
| 13. | . 1322 | 15. | . 1992 | 30. | . 6322 |  |  |
| NPTS _-. 20. .... MACH 0.5 . |  |  |  |  |  |  |  |
| -30. | . 6322 | -13. . 2572 -12. |  |  | .1222-10.- |  |  |
| -9. | . 0422 | -8. | . 0228 | -7. | . 0127 | -4. | . 0102 |
| -2. | . 0097 | 2. | . 0097 | 4. | . 0102 | 5. | . 0107 |
| 6. | . 0132 | 7. | . 0182 | 8. | . 0282 | 9. | .0482.6322 |
| 10. | . 0822 | 12. | . 1552 | 13. | . 1882 | 30. |  |
| NPTS | 23. MACH | 0.6 | THICK | 0.095 |  |  |  |
| -30. | . 6322 | -20. | . 3622 | -17. | . 3122 | -14. | . 2482 |
| -12. | . 1932 | -10. | .1292 | -9. | . 0972 | -8. | . 0722 |
| -7. | . 0522 | -6. | . 0282 | -4. | . 0147 | -3. | . 0117 |
| -2. | . 0107 | 2. | . 0097 | 3. | . 0107 | 4. | . 0132 |
| 5. | . 0172 | 6. | . 0312 | 9. | . 0992 | 12. | . 1822 |
| 17. | . 3122 | 20. | . 3622 | 30. $\quad .6322$ |  |  |  |
| NPTS | 19. MACH | 0.7 | THICK 0.095 |  |  |  |  |
| -30. | . 6322 | -12. | . 2452 | -10. | . 1792 | -8. | . 1152 |
| -6. | . 0622 | -4. | . 0322 | -3. | . 0192 | -2. | . 0142 |
| -1. | . 0107 |  | . 0102 | 1. | . 0107 | 2. | . 0127 |
| 3. | . 0182 | 4. | . 0382 | 8. | . 1282 | 9. | . 1472 |
| 10. | . 1642 | 12. | . 2402 | 30. | . 6322 |  |  |
| NPTS | 17. MACH | 0.75 | THICK | 0.095 |  |  |  |
| -30. | . 6322 | .-12... | ..... 26.98. | ..... -10. | . 2042 | -8..... | . 2402 |
| -6. | . 0822 | -4. | . 0472 | -3. | . 0252 | -2. | . 0157 |
| -3. | . 0112 | 0. | . 0102 | 1. | . 0122 | 2. | . 0232 |
| 4. | . 0682 | 6. | . 1072 | 8. | . 1472 | 12. | . 2632 |
| 30. | . 6322 |  |  |  |  |  |  |
| NPTS | 20. MACH | 0.80 | THICK | 0.095 |  |  |  |
| -30.0 | . 6322 | -12.0 | . 2922 | -10.0 | . 2272 | -8.0 | . 1622 |
| -6.0 | . 1022 | -4.0 | . 0672 | -3.0 | . 0442 | -2.0 | . 0302 |
| .-1.0 | - .....0232. | -..... -0.5 | -.. 0212 ... | - | . 0192 | ..0.5. | $\cdots . .0222$ |
| 1.0 | . 0272 | 2.0 | . 0422 | 4.0 | . 0922 | 6.0 | . 1302 |
| 8.0 | . 1722 | 10.0 | . 2272 | 12.0 | . 2872 | 30.0 | . 6322 |
| NPTS | 17. MACH | 0.90 | THICK | 0.095 |  |  |  |
| -30.0 | .............. 6322 | - -12.0 | . .3322 | -10.0 | . 2642 - |  |  |
| -6.0 | . 1512 | -4.0 | . 1172 | -2.0 | . 0682 | -1.0 | . 0572 |
| 0.0 | . 0522 | 1.0 | . 0622 | 2.0 | . 0822 | 4.0 | . 1222 |
| 6.0 | . 1692 | 8.0 | . 2122 | 10.0 | . 2642 | 12.0 | . 3247 |
| 30.0 |  |  |  |  |  |  |  |
| NPTS | 15. MACH | 1.00 THICK |  | 0.095 |  |  |  |
| -30.0 | . 6322 | -12.0 | . 3722 | -10.0-2.0-6.0 | . 2992 | -8.00.0 | . 2502 |
| -6. | . 2042 | -4.0 | . 1544 |  | . 1192 |  |  |
| 2. | . 1197 | 4.0 | . 1547 . |  | . 2052 | 6.0 | . 2512. |
| 10. | . 3002 | 12.0 | . 3652 | 30.0 | . 6322 |  |  |
| NPTS | 15. MACH | 2.00 | THICK | 0.095 |  |  |  |
| -30.0 | . 6322 | -12.0 | . 3642 | -10.0-2.0 | . 2992 | -8.0 | . 2502 |
| -6.a. | .......... 2042 | --4.0. | - ... 1544 ... |  | -. 2192 | -..0.0. .....-...0922. |  |
| 2.0 | . 1197 | 4.0 | . 1547 | 6.0 | . 2052 | 8.0 | . 2512 |
| 10.0 | . 3002 | 12.0 | . 3447 | 30.0 | . 6322 |  |  |

## Table E. 3 - concluded



Table E. 4 - Aerodynamic coefficients for model scale airfoil section SC1096-R8


Table E. 4 - continued

| CDDAT2 109582 <br> ** SC1095-R8 CD DATA ** MODEL SCALE ** |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| - ALPHA $\qquad$ . CD . $\qquad$ |  |  |  |  |  |  |  |
| -180. | . 0263 | -179. | . 0313 | -175. | . 0713 | -172. | . 1163 |
| -150. | . 6483 | -115. | 1.8863 | -65. | 1.8863 | -30. | . 6363 |
|  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |
| 4. | . 0163 | 6. | . 0168 | 8. | . 0183 | 10. | . 0203 |
| 12. | . 0223 | 13. | . 0243 | 14. | . 0288 | 15. | . 0463 |
| 16. | .... 0913 | 17. | . 1763 | 30. | . 6363 | . 65. | L. 8863 |
| 150. | . 6483 | 172. | . 1163 | 175. | . 0713 | 180. | . 0263 |
| NPTS 3 | 32. MACH | 0.30 | THICK | 0.098 |  |  |  |
| -180.--250. | . 0246 | -1836 | . 0296 | -175. | . 0696 | -172. | . 1146 |
|  | --... .6466 | --125 | . 1.8846 | ... -65... | 1.3846 | -30. | . 6346 .- |
| $\frac{-250 . .}{-8.0}$ | . 0926 | -7. | . 0656 | -6. | . 0466 | -5. | . 0266 |
| -4. | . 0176 | -3. | . 0136 | -2. | . 0126 | 2. | . 0136 |
| 4. | . 0146 | 6. | . 0151 | 8. | . 0166 | 10. | . 0186 |
|  | -..0206 | 13. | . .0226 | 14. | . 0271 | 15. | . 0446 |
|  | . 0896 | 17. | . 1746 | 30. | . 6346 | 65. | 1.8846 |
| 150. | . 6466 | 172. | . 1146 | 175. | . 0696 | 180. | . 0246 |
| NPTS 2 | 20. MACH | 0.40 | THICK | 0.098 |  |  |  |
| -30. | ...... .6342 | -10... | .....1492.- | -3.0. | . 0952 | -7... | .0692- |
| -6. | . 0482 | -5. | . 0312 | -4. | . 0172 | -3. | . 0137 |
| -2. | . 0122 | 2. | . 0122 | 4. | . 0132 | 6. | . 0147 |
| 8. | . 0167 | 9. | . 0182 | 10. | . 0227 | 11. | . 0322 |
| 12. | . 0.0542 | 13. | . 1192 | 13.5 | . 1742 | 30. | . 6342 |
| NPTS 27 | 27. MACH | 0.50 | THICK | 0.098 |  |  |  |
| -30. | . 6336 | -13. | . 2086 | -10.5 | . 1786 | -10. | . 1536 |
| -9. | . 1246 | -8. | . 1006 | -7. | . 0746 | -6. | . 0546 |
| - -5. | .-.... 0336 | $-4 . .$. | . 0241. | -3. | . 0176 | -2. | . 0136 |
|  | . 0121 | 0. | . 0116 | 2. | . 0116 | 4. | . 0126 |
| 5. | . 0136 | 6. | . 0166 | 7. | . 0246 | 6. | . 0386 |
| 9. | . 0546 | 10. | . 0746 | 11. | . 1006 | 12. | . 1316 |
| 13. | . 1716 | 13.5 | . 1936 | 30. | . 6336 |  |  |
| HPTS 29 | 29. MACH | 0.60 | THICK | 0.098 |  |  |  |
| -30. | . 6331 | -20. | . 3631 | -14. | . 2491 | -11.3 | . 1931 |
| -11. | . 2831 | -10. | . 1561 | -9. | . 1291 | -8. | . 1051 |
| -7. | -... 0811 | -6...- | . 0601 | -5. | . 0431 | -4.... | . 0311 |
|  | . 0211 | -2. | . 0131 | -1. | . 0121 | 0. | . 0111 |
| 1. | . 0106 | 2. | . 0111 | 3. | . 0131 | 4. | . 0181 |
|  | . 0281 | 6. | . 0451 | 7. | . 0651 | 8. | . 0861 |
| 5. | . 1111 | 10. | . 1351 | 11. | . 1631 | 12. | . 1921 |
| 30. . 6331 |  |  |  |  |  |  |  |
| NPTS 23 | 23. MACH | 0.70 | THICK | 0.098 |  |  |  |
| -30. | . 6326 | -12. | . 2456 | -10.6 | . 1776 | -10. | . 1646 |
| -9..... | . 1426 | - 8. | . 1196 | -7.. | . 0986 | . -6. | . 0786 . |
| -5. | . 0586 | -4. | . 0426 | -3. | . 0266 | -2. | . 0136 |
| -1. | . 0121 | 0. | . 0116 | 1. | . 0121 | 2. | . 0166 |
| 3. | . 0346 | 4. | . 0556 | 6. | . 0946 | 9. | . 1606 |
| $. . . .9 .5 .$ | ... - 1726. | 12. | ..... 2406 | ... 30. | . 6326 | - -.... |  |
|  | 19. MACH | 0.75 | THICK | 0.098 |  |  |  |
| -30. | . 6324 | -12. | . 2700 | -10. | . 2044 | -8. | . 1504 |
| -3. | . 0324 | -2.5 | . 0204 | -2. | . 0164 | -1. | . 0159 |
| $0 \ldots$ | -. .0154 | 1....- | -0264 | 2.6. | . 0514 | 3. | . 0724 |
| 4. | . 0914 | 5. | . 1084 | 6. | . 1254 | 7. | . 1424 |
|  | . 2064 | 12. | . 2634 | 30. | . 6324 |  |  |
| NPTS 20 | 20. MACH | 0.80 | THICK | 0.098 |  |  |  |
| $\begin{array}{r} -30.0 \\ -6.0 \end{array}$ | - .....6.321 | - -12.0 | ....2921 ... | -10.0 | . 2271 | -8.0.. | . 1721. |
|  | . 1241 | -4.0 | . 0771 | -3.0 | . 0441 | -2.0 | . 0301 |
| -1.0 | . 0281 | -0.5 | . 0276 | 0.0 | . 0271 | 0.5 | . 0371 |
| 1.0 | . 0441 | 2.0 | . 0721 | 4.0 | . 1101 | 6.0 | . 1501 |
| 8.0 | . 1841 | 10.0 | .2271 | 12.0 | . 2871 | -30.0 | --.6321. |
| NPTS 1 | 17. MACH | 0.90 | THICK | 0.098 |  |  |  |
| -30.0 | . 6316 | -12.0 | . 3316 | -10.0 | . 2636 | -8.0 | . 2116 |
| -6.0 | . 1646 | -4.0 | . 1166 | -2.0 | . 0676 | -1.0 | . 0646 |
| - .0.0.... | . --... 0616 | - | -.0796.. | -- - 2.0 | ....1016... | - 4.0 | -. .1396 |
| 6.0 30.0 | . 1836 | 8.0 | . 2226 | 10.0 | . 2636 | 12.0 | . 3241 |
| NPTS ${ }^{30.0}$ | . 6316 |  |  |  |  |  |  |
|  | 15. MACH | 1.00 | THICK | 0.098 |  |  |  |
| $\begin{gathered} -30.0 \\ -6 . \end{gathered}$ | ............ 6.31 | -12.0 | . 371. | .-.10.0. | . .298 | -8.0 | - 249 |
|  | . 203 | -4.0 | . 153 | -2.0 | . 118 | 0.0 | . 101 |
| 2. | . 1370 | 4.0 | . 1710 | 6.0 | . 216 | 8.0 | . 256 |
| 10. | . 299 | 12.0 | . 3640 | 30.0 | . 631 |  |  |
| NPTS - 15 | 15. - Mach | 2.00. | - THICK | 0.098 | - --. - | - -.....- |  |
| -30.0 | .630 | -12.0 | . 362 | -10.0 | . 297 | -8.0 | . 248 |
| -6.0 | . 202 | -4.0 | . 152 | -2.0 | . 117 | 0.0 | . 100 |
| 2.0 | . 1360 | 4.0 | .1700 | 6.0 | . 215 | 8.0 | . 255 |
| 10..0.. | -298. | 12.0 | . 3425 | 30.0 | .630 |  |  |

Table E. 4 - concluded
CMDAT2 107583
** SCI095-R8 1975 TSR CM DATA ** MODEL SCALE **

 NPTS $\$ 15 . \quad \mathrm{MACH}$ \# .6000 THICK \# 098


## APPENDIX F

Fuselage and Empennage Aerodynamic Force and Moment Data
SUMMARY

Fuselage and empennage aerodynamic forces for the flight test vehicle are presented in this appendix as determined from $1 / 5$ th scale unpowered model testing. Also presented is the method for calculating airframe lift and drag using the $1 / 5$ scale model data.
$C_{D_{H T}} \quad$ horizontal tail drag coefficient, $D_{H T} / q_{H T} S_{H T}$
${ }^{C_{D T}} \quad$ vertical tail drag coefficient, $D_{V T} / q_{V T} S_{V T}$
${ }^{C_{L_{H T}}}$ horizontal tail lift coefficient, $\mathrm{L}_{\mathrm{HT}} / \mathrm{q}_{\mathrm{HT}} \mathrm{S}_{\mathrm{H} T}$
${ }^{C_{L_{V T}}}$ vertical tail lift coefficient, $L_{V T} / q_{H T} S_{H T}$
$D_{A F} \quad$ total airframe drag
$D_{\text {FUS }} \quad$ fuselage drag force
$D_{H T} \quad$ horizontal tail drag force
$D_{V T}$ vertical tail drag force
$F_{Y} \quad$ fuselage side force
$\mathrm{i}_{\mathrm{HT}} \quad$ horizontal tail incidence
$L_{\text {FUS }} \quad$ fuselage lift force
$L_{H T} \quad$ horizontal tail lift force
$L_{V T} \quad$ vertical tail lift force
$L_{r} \quad$ fuselage rolling moment
$M_{F} \quad$ fuselage pitching moment
$N_{y} \quad$ fuselage yawing moment
$q \quad$ free stream dynamic pressure, $\frac{1 / 2}{2} \rho^{V^{2}}$

| ${ }^{\text {q }} \mathrm{HT}$ | effective dynamic pressure at the horizontal tail location |
| :---: | :---: |
| ${ }^{\text {q }}$ VT | effective dynamic pressure at the vertical tail location |
| $S_{H T}$ | horizontal tail reference area |
| $S_{V T}$ | vertical tail reference a |
| V | free stream velocity |
| ${ }^{\alpha}$ FUS | fuselage angle of attack |
| ${ }^{\alpha} \mathrm{HT}$ | horizontal tail angle of attack |
| $\Delta D_{\text {FUS }}$ | fuselage drag increment due to yaw |
| $\Delta L_{\text {FUS }}$ | fuselage lift increment due to yaw |
| $\triangle M_{\text {FUS }}$ | fuselage pitching moment increment due to yaw |
| $\Delta \alpha_{\text {FUS }}$ | fuselage rotor induced angle of attack |
| ${ }^{\Delta \alpha_{H T}}$ | horizontal tail rotor induced angle of attack |
| $\varepsilon$ | local flow angle at horizontal tail location, positive down |
| ${ }^{\theta} \mathrm{B}$ | fuselage pitch attitude, positive nose up |
| $\rho$ | ambient air density |
| $\sigma$ | local sideflow angle at the vertical tail location, positive from the left |
| $\phi$ | roll angle, positive right-wing down |
| $\psi$ | yaw angle, positive nose right |

The following summarizes the data presented in the figures of this appendix.
Figures $1 F, 2 F$, and $3 F$ :
$1 / 5$ scale model fuselage lift, drag, and pitching moment divided by dynamic pressure, plotted as a function of angle of attack.

Figures $4 \mathrm{~F}, 5 \mathrm{~F}, 6 \mathrm{~F}, 7 \mathrm{~F}, 8 \mathrm{~F}$, and 9 F :
$1 / 5$ scale model fuselage delta pitch moment, delta lift, delta drag, side force, roll moment, and yaw moment, divided by dynamic pressure and plotted as a function of yaw angle.

Figures 10 F and 11F:
Plots of horizontal tail lift and drag coefficients versus angle of attack.

Figures 12 F and 13 F :
Plots of vertical tail lift (side force) and drag coefficients versus angle of attack (yaw).

Figure 14 F and 15 F :
Horizontal tail downflow angle and dynamic pressure ratio variation with angle of attack.

Figure 15 F and 17F:
Vertical tail sideflow angle and dynamic pressure ratio variation with yaw angle.

Figure 18 F and 19F:
Fuselage and horizontal tail downwash delta angle of attack change versus forward speed.

Table F.1:
ATRS fuselage and tail surface geometric data.
Table F.2:
ATRS tail surface geometric description data.
Table F.3:
ATRS Aircraft gross weight and center of gravity limits data.
Table F.3:
Tail rotor data.
The data in Figures 1 F through 9 F and 14 F through 17 F have been derived from $1 / 5$ scale wind tunnel test results as labeled. The data on Figures 10F through 13F are based on established NACA two-dimensional coefficients for the respective airfoils, with finite span effect corrections theoretically derived by the DATCOM method. Figures 18 F and 19 F are derived from Sikorsky Aircraft's GENHEL simulation program.

Correction factors must be added to the sums of experimental and theoretical drag data shown in Figures $2 F, 2 \mathrm{~F}, 11 \mathrm{~F}$, and 13 F to obtain the total equivalent airframe drag area of $12.23 \mathrm{ft}^{2}$ (level flight trim value). This value was
from flight test data obtained from the instrumented flight test vehicle shown in Figure 2. These corrections consider items not included on the model, such as tail rotor and hub, interference, airflow momentum drag from cooling systems, and miscellaneous minor pertuberances. These corrections sum to 4.36 $\mathrm{ft}^{2}$ and should be added to the sum of data from Figures $2 \mathrm{~F}, 6 \mathrm{~F}, 11 \mathrm{~F}$ and 13 F to obtain the test aircraft total configuration drag. Figure 8 presents the variation of total airframe drag with local fuselage angle of attack. It is shown to be independent of rotor lift and speed because these parameters have only a minor effect on drag for realistic values of effective angle of attack in trimmed level flight.

## Calculation of Airframe Lift and Drag

Airframe lift is a function of rotor lift and must be calculated iteratively for each flight condition. The airframe lift increment was calculated as the sum of the fuselage and horizontal tail contributions accordingly, the airframe lift, $L_{A F}$, is expressed as

$$
\begin{equation*}
L_{A F}=L_{F U S}+L_{H T} \tag{1F}
\end{equation*}
$$

where $L_{\text {FUS }}$ and $L_{H T}$ are the fuselage and horizontal tail contributions, respectively.
$L_{\text {FUS }}$ is calculated as

$$
\begin{equation*}
L_{\text {FUS }}=(L / q)_{\text {FUS }} \tag{2F}
\end{equation*}
$$

where $q=\frac{1}{2} \rho^{V^{2}}$ (free stream dynamic pressure, $7 b / f t^{2}$ or $\mathrm{Kg}\left(m^{2}\right)$ and $(L / q)$ FUS is obtained from Figure IF at the appropriate effective fuselage angle of attack, $\alpha_{\text {FUS }} \cdot \alpha_{\text {FUS }}$ is expressed as

$$
\begin{equation*}
\alpha_{\text {FUS }}{ }^{2} \theta_{B}+\Delta \alpha_{\text {FUS }} \tag{3F}
\end{equation*}
$$

where $\theta_{B}$ is body pitch attitude (deg) for level flight and $\triangle \alpha_{\text {FUS }}$ is the correction angle due to main rotor downwash. Body pitch angles are obtained from either flight test data or GENHEL simulation and $\Delta a_{\text {FUS }}$ is obtained from Figure 18F.

The horizontal tail lift contribution is expressed as

$$
\begin{equation*}
L_{H T}=C_{L_{H T}}\left(Q_{H T} / q\right) q S_{H T} \tag{4F}
\end{equation*}
$$

Horizontal tail lift coefficient, $C_{L_{H T}}$, and dynamic pressure ratio ( $q_{H T} / q$ ) are obtained from Figures $10 F$ and $14 F$, respectively. The horizontal tail area,
$S_{H T}$, is $18.5 \mathrm{ft}^{2}\left(1.719 \mathrm{~m}^{2}\right)$. It should be noted that the angle of attack for determining the horizontal tail $C_{L}, \cdot \alpha_{H T}$, differs from the fuselage angle of attack due to different interference factors. In this case,

$$
\begin{equation*}
\alpha_{H T}=i_{H T}+\Delta \alpha_{H T}-\varepsilon+\theta_{B} \tag{5F}
\end{equation*}
$$

where ${ }^{i}{ }_{H T}$ is tail incidence, $\Delta \alpha_{H T}$ is the correction for main rotor wake interference obtained from Figure 19 F and $\varepsilon$ is the self-induced downwash angle at the horizontal tail presented in Figure 19 F.

The approach is further illustrated by the following worked example which also includes an evaluation of the drag.

Data:
Flight No. 12

| Gross Weight | $=10,300 \mathrm{lb}$ |
| :--- | :--- |
| Advance ratio $(\mu)$ | $=0.3$ |
| Rotational tip Mach No. $\left(M_{T}\right)$ | $=0.6$ |
| Level flight speed $(\mathrm{V})$ | $=120.8 \mathrm{knots}$-TAS |
| Body pitch attitude $\left(\theta_{\mathrm{B}}\right)$ | $=0.4^{0}$ |
| Body yaw attitude $(\psi)$ | $=2.0^{\circ}$ |
| Ambient air density $(\rho)$ | $=0.002278 \frac{\mathrm{lb} \mathrm{sec}}{\mathrm{ft}^{4}}$ |
| Horizontal tail area $\left(\mathrm{S}_{\mathrm{HT}}\right)$ | $=18.5 \mathrm{ft}^{2}$ |
| Vertical tail area $\left(\mathrm{S}_{\mathrm{VT}}\right)$ | $=19.7 \mathrm{ft}^{2}$ |

## Calculations:

From equation $3 F$ and Figure 18 F

$$
\begin{aligned}
\alpha_{\text {FUS }} & =0.4-2.20 \\
& =-1.8^{0}
\end{aligned}
$$

Corresponding to this angle of attack, the fuselage lift obtained from Figure 1 F and equation 2 F is (the effects of yaw and roll are negligible)

$$
\begin{aligned}
\Delta L_{\text {FUS }} & =-0.07 \times \frac{1}{2} \times 0.002278 \times(1.689 \times 120.8)^{2} \\
& =-3.32 \mathrm{lb}
\end{aligned}
$$

Using equation 5 F and Figures 19 and 14F the angle of attack for the horizontal tail is:

$$
\begin{aligned}
\alpha_{\mathrm{HT}} & =2 .-3.50-2.20+0.4 \\
& =-3.3^{0}
\end{aligned}
$$

From Figure 10F and equation 4 F :

$$
\begin{aligned}
\Delta L_{H T} & =0.50 \times 0.74 \times \frac{1}{2} \times 0.002278 \times(1.689 \times 120.8)^{2} \times 18.5 \\
& =-324.56 \mathrm{lb}
\end{aligned}
$$

The total configuration lift is given by equation $1 F$ :

$$
\begin{aligned}
\Delta L_{\mathrm{AF}} & =-3.32-324.56 \\
& =-327.88 \mathrm{ib}
\end{aligned}
$$

The drag is obtained using the data presented in Figures $2 \mathrm{~F}, 6 \mathrm{~F}, 11 \mathrm{~F}$ and 13 F together with the correction factor of $4.36 \mathrm{ft}^{2}$ as was discussed earlier. From Figure 2F

$$
\frac{D_{\text {FUS }}}{q}=6.6 \mathrm{ft}^{2}
$$

From Figure 6F

$$
\frac{\Delta D_{\text {FUS }}}{q}=0.5 \mathrm{ft}^{2}
$$

From Figure 11F

$$
D_{D_{H T}}=0.0028
$$

and from Figure 13F

$$
C_{D_{V T}}=0.013
$$

Converting the drag coefficients to equivalent flat plate drag areas, summing and adding the correction of 4.36 gives

$$
\begin{aligned}
\mathrm{D}_{\mathrm{AF}} / \mathrm{q} & =6.6+0.5+.028 \times 18.5+.013 \times 19.7+4.36 \\
& =12.23 \mathrm{ft}^{2}
\end{aligned}
$$



Figure 1F - ATRS fuselage lift $\mathbf{1 / 5}$ angle of attack


Figure 2F - ATRS fuselage drag vs angle of attack

$\stackrel{m}{\ddagger}$
Figure $3 F-$ ATRS fuselage pitching moment vs angle of attack


Fuselage yaw angle, $\psi$, Deg

Figure 4F - ARTS variation of fuselage pitching monent vs yaw angle


Figure 5F - ATRS variation of fuselage lift with yaw angle


Figure 6F - ATRS variation of fuselage drag with yaw angle


Figure 7F - ARTS variation of fuselage side force with yaw angle


Figure 8F-ARTS variation of fuselage rolling moment with yaw angle


Figure 9F - ATRS variation of fuselage yawing moment with yaw angle


Figure 10 F - ATRS horizontal tail lift coefficient vs angle of attack (theoretical)


Figure 11 F - ATRS horizontal tail drag coefficient vs angle of attack (theoretical)


Figure 12 F - ATRS vertical tail lift coefficient vs. angle of attack (theoretical)


Figure 13 F - ATRS vertical tail drag coefficient vs. angle of attack (theoretical)


Figure 14 F - ATRS horizontal tail dynamic pressure ratio variation with angle of attack.


Figure 15 F - ATRS horizontal tail downflow angle variation with angle of attack.


Figure 16F - ATRS vertical dynamic pressure ratio variation with yaw angle


Figure 17F - Vertical tail sideflow angle variation with yaw angle.


Figure 18F - Effect of rotor on body angle of attack


Figure 19F - Effect of rotor on tail angle of attack

## TABLE F. 1 ATRS FUSELAGE AND TAIL SURFACE GEOMETRIC DATA

| Item | Fuselage <br> Station | Water <br> Line | Butt <br> Line |
| :--- | :---: | :---: | :---: |
| Main Rotor Center ( $5^{\circ}$ forward shaft tile) | 200 | 157 | 0 |
| Tail Rotor Center ( $0^{\circ}$ yaw and cant angle) | 518 | 163 | 19 |
| Horizontal Stabilizer Aerodynamic Center <br> of Pressure | 474 | 101 | 0 |
| Vertical Stabilizer Aerodynamic Center of <br> Pressure | 490 | 141 | 0 |
| Reference Point for Figures 1F-17F Data | 200 | 90 | 0 |

TABLE F. 2 ATRS TAIL SURFACE GEOMETRIC DESCRIPTION DATA

| Item | Units | Horizontal <br> Stabilizer | Vertical <br> Stabilizer |
| :--- | :---: | :---: | :---: |
| Area | $\mathrm{ft}^{2}\left(\mathrm{~m}^{2}\right)$ | $18.5(1.72)$ | $19.7(1.35)$ |
| Span | in. (cm) | $116.0(294.6)$ | $70.0(177.8)$ |
| Root Chord | in. (cm) | $32.0(81.3)$ | $52.0(15.8)$ |
| Tip Chord | in. (cm) | $13.8(3.51)$ | $29.0(73.7)$ |
| Aspect Ratio | - | 5.0 | 1.7 |
| Taper Ratio | - | .43 | .56 |
| Sweep (1/4 Chord) | deg. | 3.5 | 36.5 |
| Airfoil Section | - | $4412($ INVERTED) | $63_{4}-421$ |
| Incidence (Geometric) | deg. | +2.0 | 0 |

## TABLE F. 3 ATRS AIRCRAFT CG LIMIT DATA



APPENDIX G<br>Description of Coupled Normal Modes (Y201)/Variable Inflow (F389)<br>Elastic Rotor Analysis

The analysis employed in this study is identified as Y201, which was funded by the Eustis and Ames directorates of USAAMRDL, as well as the United Technologies Research Center and Hamilton Standard Division of United Technologies Corporation. The basic blade equations of motion were developed under army contract No. DA-44-177-AMC-322(T), as reported in Reference 7. A current version of the program was developed under Contract DAAJ02-71-C-0024, Reference 8.

The $Y 201$ aeroelastic rotor program contains state-of-the-art representations for all primary factors influencing rotor airloads prediction. The approach includes both dynamic and aerodynamic considerations required to determine rotor blade motions and resultant airload distributions. These analytic models are integrated into a single analysis and can be selectively employed to vary the sophistication of the airloads prediction technique. The basic mathematical model in the Y201 airloads analysis represents each blade as a segmented dynamic and aerodynamic body. Mass, stiffness and damping properties are defined for each segment which, when combined with the appropriate end constraints at the rotor head, permit calculation of the blade response to imparted airloads. Since the airloads themselves are also functions of the blade dynamic response, an iterative technique is used to converge the airload and dynamic behavior. The rotor inflow logic can be exercised on several levels of complexity. As such, only the simplest constant inflow representation is addressed directly within the Y201 analysis. The more complicated wake inflow representations are accessed through a separate analysis, F389SR, which is linked with Y201.

Rotor blade flatwise, edgewise, and torsional bending modes and frequencies are calculated internal to the program. The blade model was run with three flatwise elastic modes, two edgewise modes, and one torsion mode. These are in addition to the articulated flapping and lag modes.

The rotor model uses the normal modes of vibration of the blade to form a set of approximately uncoupled differential equations which are integrated with respect to time to calculate the response of the blade. Up to second order products of small terms in the flatwise and edgewise equations, and third order products in the torsion equation have been retained.

The analysis yields rotor performance, vibratory blade moments, stresses, push rod loads and non-linear aeroelastic stability. These results are used to evaluate or design the rotor system. Variables can include blade c.g. offset distributions, aerodynamic center offset distributions resulting from airfoil characteristics or blade planform variations, blade stiffness distributions, and control system stiffness.

A simple viscous lag damper is used on the blade. The aerodynamic model uses a blade-element yawed flow analysis. The yawed flow capability was developed for the Army ATL in 1977 and is a steady flow analysis. Table look-up of experimental data is used to obtain coefficients of appropriate airfoil lift, drag, and pitching moment. A multiple airfoil capability is also available up to two different airfoil sections along the blade span. Tip sweep back may be included with steady flow models. Presently, the aerodynamic sweep is assumed to be the geometric sweep of the blade tip quarter chord, uncorrected for three-dimensional flow effects.

Rotor trim is primarily accomplished through internal iteration on the governing rotor control inputs. An exception is rotor shaft angle setting which requires an external iteration. Rotor collective pitch and the rotor lateral and longitudinal cyclic pitch settings are internally controlled to obtain a specified lift and predetermined roll and pitch moment values.

As mentioned previously, the Y201 analysis accesses either an internally calculated uniform downwash or a radial and azimuthally variable downwash generated with the linked F389SR analysis. In either case, the downwash plays an important role in the airload determination since the effective blade section lift angles are the sum of the local airfoil section geometric angle and the flow angle induced by the local downwash.

This program is known as the UTRC Rotorcraft Prescribed Wake Induced Velocity Analysis. Descriptions of the analysis, applications, and comparisons with test data are presented in Reference 9, 10 and 11.

The F389R prescribed rotor wake inflow program computes rotor inflow distributions for interface with the Y201 airloads analysis. Since the inflow velocities are based on the evaluation of velocities induced by a representation of the wake structure, the method can describe radial and azimuthal inflow variations in great detail. The use of representative wake induced downwash distributions has a strong effect on predicted airloads. This is particularly true in regard to the higher harmonic airload excitations. The non-uniform downwash distributions were calculated with an assumed classical, skewed helical wake.

Stated briefly, the mathematical model in the rotor inflow program consists of the representation of each blade by a segmented lifting line, and the helical wake of the rotor by discrete, segmented vortex filaments. The vorticity of the trailing wake results from the spanwise variation of bound circulation. The blades are divided into a finite number of radial segments, and the induced velocity at the center of each selected blade segment is computed by summing the contributions of each bound and trailing wake segment. The contribution of each vortex segment is obtained through use of the Biot-Savart equation.

In the generation of the analytical results for this study, two complete cycles of the coupled Y201/F389SR analysis were performed. This involved one execution of Y201 with constant inflow to initiate the F389SR program and two subsequent F389SR/Y201 passes.

## APPENDIX H <br> Description of Wing and Body Aerodynamic Technique (WABAT)

The Sikorsky developed Wing And Body Aerodynamic Techniques (WABAT) program is a versatile three-dimensional potential flow method. Its primary function is the calculation of body surface pressures, surface flow velocities, and offbody velocity distributions for both non-lifting and lifting bodies. The basic potential flow solution is based on the distributed source method developed by Hess and Smith in Reference 12 while the lifting elements are represented with a modified Multhopp lifting surface procedure developed from Reference 13. The program is capable of calculating both the body pressure distribution, required for evaluating rotor flow effects on body surface excitation, and off-body potential flow velocities, needed for assessing rotor load interference.

The WABAT analysis is comprised of separate body paneling and panel source solution programs. The body paneling definition program was developed to simplify the generation of a suitable model for arbitrary body shapes. Program inputs generally describe cross sections of the body by combinations of curved and straight line segments. Figure H1 illustrates a typical airframe panel model generated with the geometry model.

For prediction of rotor load variations induced by the airframe, the ability to predict off-body velocities in the rotor plane is important. WABAT has this capability which is demonstrated as follows for a selected rotor/fuselage configuration. The predicted nondimensionalized interference velocities at the rotor plane are depicted in Figure H2. As illustrated, the interference is highest in the nose region where the rotor inflow is decreased by the nose structures and the forward pylon geometry. These effects are shown in detail in Figure H3 which shows the effect on section angle of attack when the blade passes the nose region. The net effect of the entire fuselage flow field on the rotor loads was obtained by combining the fuselage and rotor induced flows and comparing the resulting blade load pattern with that obtained without the airframe effects. The resulting angle of attack comparison for the . 30 blade radial station is shown in Figure H4. Although the interference effects are most pronounced at $180^{\circ}$, significant load distortions appear around the entire azimuth. These results were obtained by coupling the WABAT analysis with the UTRC Rotorcraft Wake Analysis (F389 SR), and then using the total inflow in a normal modes aeroelastic rotor analysis.


Figure H1 - Typical airframe panel model.


Figure $\mathbf{H 2}$ - Predicted body induced velocities at rotor plane.


Figure H3 - Nose region upwash alters local angle of attack.


Figure H4 - Blade angle of attack change due to body interference.

## APPENDIX I <br> Description of Full Scale Model Wind Tunnel Test Facility

The large scale wind tunnel at the NASA/Ames Research Center, Mountain View, California is located on the Moffett Field Naval Air Station. The tunnel is a closed throat, closed return type with a test section 40 feet ( 12.2 m ) high and 80 feet ( 24.4 m ) wide. The wind tunnel has a nominal maximum speed capability of 200 knots and is powered by six 6000 horsepower ( 4406 Kw ) electric motors. Rotor forces and moments are measured by a six-component mechanical balance.

The rotor hub was mounted at the center of the wind tunnel test section as shown in Reference 1. Figure 4 shows the entire test model installed in the NASA/Ames wind tunnel.

## APPENDIX J <br> Description of $1 / 5$ th Scale Model Test Facility

The United Technology Research Center Large Subsonic Wind Tunnel is a single return, closed throat facility with interchangeable 18 foot (5.5m) and 8 foot ( 2.4 m ) test sections. The $1 / 5$ th scale model test was conducted in the 18 foot ( 5.5 m ) octagonally shaped test section. Maximum tunnel velocity in the 18 foot ( 5.5 m ) test section is approximately 175 knots. Stagnation temperature of the airstream can be held constant by means of air exchanger values. Stagnation pressure is equal to atmospheric pressure. Electric power was supplied to the model by one of two motor generator sets capable of developing a maximum of $325 \mathrm{HP}(239 \mathrm{Kw})$ each at a variable frequency of $0-400 \mathrm{~Hz}$. A 25 channel static data acquisition system (STADAS) was used to record and process tunnel test conditions and model static data. The STADAS system is directly linked to a PDP-6 computer.

The rotor hub was mounted at the center of the wind tunnel test section at zero fuselage pitch. Because the model pitches about a point 10.6 feet ( 3.2 m ) below the rotor hub, the hub drops below the centerline of the test section by the amount:

$$
z=10.6\left(1-\cos \alpha_{f}\right) \text { in feet }
$$

or

$$
z=3.2\left(1-\cos \alpha_{f}\right) \text { in meters }
$$

The $1 / 5$ scale model is shown installed in the UTRC wind tunnel in Figure 6.

## APPENDIX K <br> NASA/Ames Rotor Test Apparatus Outside Contour Geometric Description

The NASA/Ames Rotor Test Apparatus (RTA) was used to test the Advanced Rotor System in the NASA/Ames $40^{\prime} \times 80^{\prime}$ tunnel (Figure 3). In order to analytically assess the impact of the velocities induced at the rotor due to the RTA module a geometric description of the module was developed, which is compatible with Sikorsky Aircraft's three-dimensional aerodynamic analysis. The aerodynamic analysis used was developed by Sikorsky and is designated, the Wing and Body Aerodynamic Technique (WABAT). This analysis is a potential flow analysis and calculates local velocities and pressures at points on the surface as well as off the surface. See Appendix $H$.

A half-body geometric description for symmetrical bodies is used in the analysis. The body is modeled by representing the surface of a number of approximately flat panels. Table K1 presents the coordinates of the panel nodal points. Each panel is described independently and, consequently, nodal points are duplicated if shared by more than one panel. All panels are described by four nodal points even if the panel is triangular rather than a quadrilateral.

In Table K1, the four node points are described by its Cartesian coordinate points. In the coordinate system used the $X, Y, Z$ points correspond to:

$$
\begin{aligned}
X & - \text { Buttline } \\
Y & - \text { Waterline } \\
Z & - \text { Body Station } \\
\text { Units } & - \text { Inches }
\end{aligned}
$$

As indicated by the table, the RTA module half body is described by 300 panels.
It should be noted that the actual module has small fairing approximately midlength of the body located near the bottom of the module (Figure 3). The fairings cover the attachment fittings for the balance support struts. These fairings have not been modeled since their size and distance from the rotor is sufficient to assume that their aerodynamic influence on the rotor is significant.
Table K. 1 - Rotor test apparatus outside contour coordinates


| 104 | 11.494 | 174.183 | 121.665 | 12.633 | 171.62 | 132.833 | 6.458 | 169 | 132.833 | 5.876 | 172.358 | 121.665 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| +09 | 50.76 | 174.35 | 124 |  | 161 | 132 |  |  | 132783 |  | 171.7 | 121.665 |
| 106 | -000 | 231.060 | 132.133 | . 000 | 233.860 | 144.000 | 7.040 | 233.120 | 144.000 | 6.458 | 230.381 | 132.833 |
| 107 | 6.458 | 230.341 | 132,133 | 1.040 | 233.120 | 144.000 | 13.172 | 230.933 | 144.000 | 12.633 | 22A.375 | 132.433 |
| 100 | 12.633 | 228.375 | 132.633 | 13.772 | 250.935 | 144.000 | 19.902 | 227.393 | 144.000 | 18.257 | 225.128 | 132.833 |
| 109 | 18.257 | 225.128 | 132.833 | 19.902 | 227.393 | 144.000 | 25.163 | 222.657 | 144.000 | 23.082 | 220.783 | 132.833 |
| 110 | 23.082 | 220.783 | 132.833 | 25.163 | 222.657 | 144.000 | 29.324 | 216.930 | 144.000 | 26.899 | 215.530 | 132.833 |
| 111 | 26.699 | 215.530 | 132,633 | 29,324 | -216.930 | +44.000- | 32.203 | 210.403. | 144.000 | 29.540 | 209.598 | 132.833 |
| 112 | 29.540 | 209.598 | 132.133 | 32.203 | 210.463 | 144.000 | 33.674 | 203.539 | 144.000 | 30.890 | 203.247 | 132.833 |
| 113 | 30.890 | 203.247 | 132.133 | 33.674 | 203.539 | 144.000 | 33.674 | 186.463 | 144.000 | 30.890 | 196.753 | 132.833 |
| 114 | 30.090 | 196:753 | -132.033 | 33.674 | 196. 461 | 144.000 | 32.203 | 189.535 | 14*000 | 29.540 | 190.402 | 132.833 |
| 115 | 29.540 | 190.402 | 132.833 | 32.203 | 189.537 | 144.000 | 29.324 | 183.070 | 144.000 | 26.899 | 184.470 | 132.833 |
| 116 | 26.899 | 184.470 | 132.833 | 29.324 | 183.070 | 144.000 | 25.163 | 177.343 | 144.000 | 23.082 | 179.217 | 132.833 |
| 117 | 23.082 | 179.217 | $132 \cdot 633$ | 25.163 | 177.343 ${ }^{3}$ | 144:000 | 19.902 | 172.607 | 144.000 | 16.257 | 174.872 | 132.833 |
| 118 | 14.257 | 174.872 | 132.833 | 19.902 | 172.607 | 144.000 | 13.772 | 169.067 | 144.000 | 12.633 | 171.625 | 132.833 |
| 119 | 12.633 | 171.625 | 132.833 | 13.712 | 169.067 | 144.000 | 7.040 | 166.880 | 144.000 | 6.458 | 169.619 | 132.833 |
| 120 | -6.458 | 169.619 | 132.033 | 7.040 | 166.850 | 144.000 | . 000 | 165.140 | 114.000 | :000 | 158.940 | 132.833 |
| 121 | . 000 | 233.860 | 144.000 | . 000 | 235.120 | 158.960 | 7.302 | 234.353 | 158.960 | 7.040 | 233.120 | 144.000 |
| 122 | 7.040 | 233.120 | 144.000 | 7.302 | 234.353 | 158.960 | 14.285 | 232.084 | 158.960 | 13.77 | 230.933 | 144.000 |
| 123 | 13.772 | 230.933 | 144.000 | 14.285 | 232.084 | 158.960 | 20.643 | 228.413 | 158.960 | 19.902 | 227.393 | 144.000 |
| 124 | 19.902 | 227.393 | 144.000 | 20.643 | 228.413 | 158.960 | 26.099 | 223.500 | 158.960 | 25.163 | 222.65 | 144.000 |
| 125 | 25.163 | 222.657 | 144.000 | 26.099 | 223.500 | 158.960 | 30.415 | 217.560 | 158.960 | 29.324 | 216.930 | 144.000 |
| 126 | 29:324 | 216:930 | 144:000 | 30.415 | 217:360 | 158.980 | 35.401 | 210.853 | 158.960 | 32.203 | 210.46 | 144.000 |
| 127 | 32.203 | 210.463 | 144.000 | 33.401 | 210.853 | 158.960 | 34.928 | 203.671 | 158.960 | 33.674 | 203.539 | 144.000 |
| 128 | 33.674 | 203.539 | 144.000 | 34.928 | 203.671 | 158.960 | 34.928 | 196.329 | 158.960 | 33.674 | 196.461 | 144.000 |
| 129 | 33.674 | 196.461 | 144.000 | 34.928 | 196.329 | 158.960 | 33.401 | 189.247 | 158,960 | 32.238 | 189.537 | 144.000 |
| 130 | 32.203 | 189.537 | 144.000 | 33.401 | 189.147 | 158.960 | 30.415 | 182.440 | 158.960 | 29.324 | 183.070 | 144.000 |
| 131 | 29.324 | 183.070 | 144.000 | 30.415 | 182.440 | 158.960 | 26.099 | 176.500 | 158.960 | 25.163 | 177.343 | 144.000 |
| 132 | 25.163 | 177.343 | 144.000 | 26.099 | 176.500 | 158.960 | 20.843 | 171.587 | 158.960 | 19.902 | 172.607 | 144.000 |
| 133 | 19.902 | 172.607 | 144.000 | 2 C .643 | 171.587 | 158.960 | 14.285 | 167.916 | 158.960 | 13.772 | 169.067 | 144.000 |
| 134 | 13.772 | 169.067 | 144.000 | 14.285 | 167.916 | 258.960 | 7.302 | 165.647 | 258.960 | 7.040 | 166.880 | 144.000 |
| 135 | 7.040 | 166.880 | 144.000 | 7.302 | 165.647 | 158.960 | 000 | 164.880 | 158.960 | . 000 | 166.140 | 144.000 |
| 136 | . 000 | 235.120 | 158.960 | . 000 | 235.080 | 181.385 | 7.294 | 234.313 | 181.385 | 7.302 | 234.353 | 158.960 |
| 137 | 7.302 | 234.353 | 158.960 | 7.294 | 234.313 | 181.385 | 14.268 | 232.047 | 181.385 | 14.285 | 232.084 | 158.960 |
| 138 | 14.285 | 2320684 | 158.960 | 14.268 | 232.047 | 181.385 | 20.619 | 228.380 | 181.385 | 20.643 | 228.413 | 158.960 |
| 139 | 20.643 | 228.413 | 158.960 | 20.619 | 228.380 | 181.385 | 26.069 | 223.473 | 181.385 | 26.099 | 223.500 | 158.960 |
| 140 | 26.099 | 223.500 | 158.960 | 26.069 | 223.473 | 181.385 | 30.380 | 217.540 | 181.385 | 30.415 | 217.560 | 158.960 |
| 141 | 30.415 | 217.560 | 158.960 | 35.380 | 237.540 | 181.385 | 33.363 | 210.840 | 181. 385 | 33.401 | 210.853 | 158.960 |
| 142 | 33.401 | 210.853 | 158.960 | 33.363 | 210.840 | 181.385 | 34.888 | 203.667 | 181.385 | 34.928 | 203.671 | 158.960 |
| 143 | 34.928 | 203.671 | 158.960 | 34.888 | 203.667 | 181.385 | 34.888 | 196.333 | 181.385 | 34.928 | 196.329 | 158.960 |
| 144 | 34.928 | 196.329 | 158.960 | 34.888 | 196.333 | 181.385 | 33.363 | 189.160 | 181.385 | 33.401 | 189.147 | 158.960 |
| 145 | 33.402 | 189.147 | 158.960 | 33.363 | 189.160 | 181.385 | 30.380 | 182.460 | 181.385 | 30.415 | 182.440 | 158.960 |
| 146 | 30.415 | 182.440 | 158.960 | 3 c .380 | 182.460 | 181.385 | 26.069 | 176.527 | 181.385 | 26.099 | 176.500 | 158.960 |
| 147 | 26.099 | 176.500 | 158.960 | 26.069 | 176.527 | 181.385 | 20.619 | 171.620 | 181.385 | 20.643 | 171.587 | 158.960 |
| 148 | 20.643 | 171.587 | 158.960 | 20.619 | 171.620 | 181.385 | 14.268 | 167.953 | 181.385 | 14.285 | 167.916 | 158.960 |
| 149 | 14.285 | 167.916 | 258.960 | 14.268 | 167.953 | 181.385 | 7.294 | 165.687 | 181.385 | 7.302 | 165.647 | 158.960 |
| 150 | 7.302 | 165.647 | 158.960 | 7.294 | 165.607 | 181.385 | . 000 | 164.920 | 181.385 | .000 | 164.880 | 158.960 |
| 151 | . 000 | 235.080 | 181.385 | . 000 | 235.040 | 203.810 | 7.285 | 234.274 | 203.810 | 7.294 | 234.313 | 181.385 |
| 152 | 7.294 | 234.313 | 181.385 | 7.285 | 234.274 | 203.810 | 14.252 | 232.011 | 203.810 | 14.268 | 232.047 | 181.385 |
| 153 | 14.268 | 232.047 | 181.385 | 14.252 | 232.011 | 203.810 | 20.596 | 228.348 | 203.810 | 20.619 | 228.380 | 181.385 |
| 154 | 20.619 | 228.380 | 181.385 | 20.596 | 228.348 | 203.810 | 26.040 | 223.446 | 203.810 | 26.069 | 223.473 | 181.385 |
| 155 | 26.069 | 223.473 | 181.385 | 26.040 | 223.446 | 203.810 | 30.345 | 217.520 | 203.810 | 30.380 | 217.540 | 181.385 |
| 156 | 36. 380 | 217.540 | 181.385 | 30.345 | 237.520 | 203.810 | 53.325 | 210.828 | 203.810 | 33.363 | 210.840 | 181.385 |
| 157 | 33.363 | 210.840 | 181.385 | 33.325 | 210.828 | 203.810 | 34.848 | 203.663 | 203.810 | 34.888 | 203.687 | 181.385 |
| 158 | 34.888 | 203.667 | 181.385 | 34.848 | 203.663 | 203.810 | 34.848 | 196.337 | 203.810 | 34.888 | 196.333 | 181.385 |
| 159 | 34.888 | 196.333 | 181.385 | 34.848 | 196.337 | 203.810 | 33.325 | 109.172 | 203.810 | 33.363 | 189.160 | 181.385 |
| 160 | 33.363 | 189.160 | 181.385 | 33.325 | 189.172 | 203.810 | 30.345 | 182.480 | 203.810 | 30.380 | 182.460 | 181.385 |
| 161 | 30.380 | 182.460 | 181.385 | 30.345 | 182.480 | 203.810 | 26.040 | 176.554 | 203.810 | 26.069 | 176.527 | 181.385 |
| 162 | 26.069 | 176.527 | 181.385 | 28.040 | 176.534 | 203.810 | 20.596 | 171.652 | 203.810 | 20.619 | 171.620 | 181.385 |
| 163 | 20.619 | 171.620 | 181.385 | 25.596 | 171.652 | 203.810 | 14.252 | 167.989 | 203.810 | 14.268 | 167.953 | 181.385 |

Table K. 1 - continued

Table K. 1 - continued

Table K. 1 - concluded

| 284 | 8.232 | 181.510 | 419.990 | 6.182 | 186.114 | 445.600 | 3.160 | 185.132 | 445.600 | 4.208 | 180.202 | 419.990 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 205 | 4.200 | 180.0202 | 419.990 | 3.100 | 185.132 | 445.600 | . 000 | 184.800 | 445.600 | . 000 | 179.760 | 419.995 |
| 286 | . 000 | 215.200 | 445.600 | . 000 | 210.400 | 470.000 | 2.162 | 210.173 | 470.000 | 3.160 | 214.868 | 445.600 |
| 287 | 3.160 | 214.868 | 445.600 | 2.162 | 210.173 | 470.000 | 4.230 | 209.501 | 470.000 | 6.182 | 213.886 | 445.600 |
| 288 | 6.182 | 213.886 | 445.600 | 4.230 | 209.501 | 470.000 | 6.113 | 208.414 | 470.000 | 8.934 | 212.297 | 445.600 |
| 289 | 8.934 | 212.297 | 445.600 | 6.113 | 208.414 | 470.000 | 7.729 | 206.959 | 470.000 | 11.296 | 210.171 | 445.600 |
| 290 | 11.296 | 210.171 | 445.600 | 7.729 | 206.959 | 470.000 | 9.007 | 205.200 | 470.000 | 13.164 | 207.600 | 445.600 |
| 291 | 13.164 | 207.600 | 445.600 | 9.007 | 205.200 | $\cdots 70.000$ | 9.891 | 203.214 | 470.000 | 14.456 | 204.697 | 445.600 |
| 292 | 14.456 | 204.697 | 445.600 | 9.891 | 203.214 | 470.000 | 10.343 | 201.087 | 470.000 | 15.117 | 201.589 | 445.600 |
| 293 | 15.117 | 201.589 | 445.600 | 10.343 | 202.087 | . 70.000 | 10.343 | 198.913 | 470.000 | 15.117 | 198.911 | 445.600 |
| 294 | 15.117 | 198.411 | 445.600 | 12.343 | 198.913 | 470.000 | 9.891 | 196.786 | 470.000 | 14.456 | 195.303 | 445.650 |
| 295 | 14.456 | 195.303 | 445.600 | 9.891 | 196.786 | 470.000 | 9.007 | 194.800 | 470.000 | 13.164 | 192.400 | 445.600 |
| 256 | 13.164 | 192.400 | 445.600 | 9.007 | 194.800 | 470.000 | 7.729 | 193.041 | 470.000 | 11.296 | 189.829 | 445.600 |
| 297 | 11.296 | 189.829 | 445.000 | 7.729 | 193.041 | 470.000 | 6.113 | 191.586 | 470.000 | 8.934 | 187.703 | 445.600 |
| 298 | 8.934 | 187.703 | +45.600 | 6.113 | 191.586 | 470.000 | 4.230 | 190.499 | 470.000 | 6.182 | 186.114 | 445.600 |
| 299 | 6.182 | 186.114 | 445.600 | 4.230 | 190.499 | 470.000 | 2.162 | 189.827 | 470.000 | 3.160 | 185.132 | 445.600 |
| 300 | 3.160 | 185.132 | 445.600 | 2.162 | 189.827 | 470.000 | .000 | 189.600 | 470.000 | . 000 | 184.800 | 445.600 |

## APPENDIX L

Normal Component of Flight Vehicle Induced Velocities At Rotor Plane

The following tables present the predicted induced velocity component normal to the plane of the rotor, for each of four flight conditions studied in the main report. The fuselage induced velocity component is normalized by the free stream velocity and is evaluated around the rotor azimuth at 15 blade radial stations, selected to be the center of each of the 15 blade segments used in the normal modes elastic blade analyses. A positive fourier series of argument $\psi$ is used to express the interference velocity. For each blade segment, the first number is the steady amplitude coefficient. The next set of 12 coefficients is the harmonic amplitudes of the $\cos (n \psi)$ terms of the series in assending order. The last set of 12 coefficients is the harmonic amplitudes of the ( $n \psi$ ) terms of the series. The data in Table L. 1 are valid for the two flight conditions studied at low gross weight (see Table VII, page 44) because, as the calculations were performed, blade coning and flapping relative to the rotor shaft are nearly the same for the two flight conditions. Table L. 2 and L. 3 cover one flight condition each.

| $G W=8200 \mathrm{lb}(3719.5 \mathrm{~kg})$ |  | , . $4 \quad M_{T}=.6$ |
| :---: | :---: | :---: |
| Table L. 1 - Harmonics of normal component of flight vehicle induced velocities at rotor plane |  |  |
| Blade segment mean station, $\mathrm{r} / \mathrm{R}$ | Fourier series amplitude coefficient |  |
| . 0649 |  | $\begin{array}{rrrr} -0.666425 E-02 & -0.743023 E-03 & -0.117297 E-02 \\ 0.504172 E-04 & 0.420667 E-04 & 0.558754 E-04 \\ 0.237309 E-05 & -0.155220 E-09 & -0.126265 E-00 \\ 0.202767 E-C E & 0.205657 E-08 & -0.737297 E-09 \end{array}$ |
| . 1406 | $0.405048 \mathrm{E}-01$  <br> $-0.778952 \mathrm{E}-01$ $0.203659 \mathrm{E}-01$ <br> $-0.169449 \mathrm{E}-02$ $-0.818522 \mathrm{E}-03$ <br> $0.346966 \mathrm{E}-03$ $0.170218 \mathrm{E}-03$ <br> $00.100693 \mathrm{E}-03$ $-0.252235 \mathrm{E}-07$ <br> $-0.100693 \mathrm{E}-03$ $0.232831 \mathrm{E}-0.3$ <br> $-0.213428 \mathrm{E}-09$ 0.0 | $-0.222066 E-01$ $-0.291731 E-02$ $-0.652741 E-02$ <br> $0.163665 E-03$ $0.385516 E-03$ $0.413871 E-03$ <br> $0.157101 E-08$ $0.776102 \mathrm{E}-10$ $-0.112535 \mathrm{E}-08$ <br> $0.120295 \mathrm{E}-08$ $-0.368051 \mathrm{E}-09$ $-0.1280 .37 \mathrm{E}-08$ |
| . 2462 | $\begin{array}{cc} 0.102059 E-01 & \\ -0.65029 E-01 & 0.171147 E-01 \\ 0.539345 E-03 & -0.130997 E-C 2 \\ -0.400213 E-03 & -C .122736 E-03 \\ \ldots .0 .85206 E-09 & -0.405 J 645-09 \\ -0.174623 E-c 8 & -0.147457 E-08 \\ -0.649986 E-09 & 0.0 \\ \hline \end{array}$ | $\begin{array}{rrr} -0.166797 E-01 & 0.405475 E-02 & -0.431335 E-02 \\ -0.204475 E-03 & -0.65 C 95 E-03 & -0.26 c 55 E E-03 \\ 0.776102 E-09 & -0.368051 E-10 & -0.737295 E-09 \\ 0.514907 E-09 & -0.659687 E-09 & -0.570128 E-09 \end{array}$ |
| . 3409 |  | $-0.196934 E-01$ $0.7116575-02$ $-0.4562215-02$ <br> $0.97445 E-03$ $0.102076 E-03$ $0.411093 E-03$ <br> $0.6203525-09$ $-0.15520 E-09$ $-0.562077 E-09$ <br> $0.353712 E-07$ $-6.757297 E-09$ $-0.892517 E-09$ |
| . 4167 | $0.431409 E-02$  <br> $-0.572084 \mathrm{E}-01$ $0.250969 \mathrm{E}-01$ <br> $0.208885 \mathrm{E}-02$ $-0.126752 \mathrm{E}-02$ <br> $0.737757 \mathrm{E}-04$ $0.6035 \% 6 \mathrm{E}-04$ <br> $0.591778 \mathrm{E}-09$ $-0.271536 \mathrm{E}-09$ <br> $-0.106265 E-08$ $-0.352961 \mathrm{E}-08$ <br> $-0.863414 \mathrm{E}-09$ 0.0 |  |
| . 4925 | $0.388297 E-02$ | $-0.165511 E-01 \quad 0.556 .996 E-02-0.518685 E-02$ $0.4088+4 \mathrm{E}-03-0.340615 \mathrm{E}-03 \quad 0.610083 \mathrm{E}-64$ <br> $0.096492 \mathrm{E}-09-\mathrm{C} .232 \mathrm{CB31E}-09-0.426856 \mathrm{E}-0 \%$ <br> 0.776102E-09-0.562077E-09 -0.601479E-09 |
| . 5683 |  | $\begin{array}{ccc} -0.12327 E E-01 & 0.451096 E-0 \varepsilon & -0.350496 E-02 \\ 0.412277 E-03 & -0.204626 E-03 & 0.100939 E-03 \\ 0.564466 E-09 & -0.776102 E-10 & -0.232831 E-09 \\ 0.504466 E-09 & -0.407454 E-09 & -0.440259 E-09 \end{array}$ |

Table L. 1 - concluded

| Blade segment mean station $r / R$ | Fourier series amplitude coefficient |
| :---: | :---: |
| . 6441 |  |
| . 7104 |  |
| . 7672 |  |
| . 8145 |  |
| . 8619 |  |
| . 9208 |  |
| . 9636 |  |
| . 9882 |  |


| $\mathrm{GW}=10,30$ | g) $\mu=.375 \quad M_{T}=.6$ |
| :---: | :---: |
| Table L. 2 - Harmonics of Normal Component of Flight Vehicle Induced Velocities at Rotor Plane |  |
| Blade segment mean station, $r / R$ | Fourier series amplitude coefficient |
| . 0649 |  |
| . 1406 | $0.395553 \mathrm{E}-01$      <br> $-0.74624 \mathrm{E}-01$ $0.171830 \mathrm{E}-01$ $-0.203224 \mathrm{E}-01$ $-0.437931 \mathrm{E}-02$ $-0.633814 \mathrm{E}-02$  <br> $-0.214048 \mathrm{E}-02$ $-0.859177 \mathrm{E}-03$ $0.956110 \mathrm{E}-04$ $0.425770 \mathrm{E}-03$ $0.449401 \mathrm{E}-03$  <br> $0.407590 \mathrm{E}-03$ $0.194430 \mathrm{E}-03$  $0.126117 \mathrm{E}-08$ $0.388051 \mathrm{E}-10$ $-0.116415 \mathrm{E}-08$ <br> $0.10865 \mathrm{E}-08$ $-0.50446 \mathrm{E}-09$ 0.126    <br> $-0.814907 \mathrm{E}-09$ $0.388051 \mathrm{E}-09$ $0.116415 \mathrm{E}-08$ $-0.329843 \mathrm{E}-09$ $-0.116415 \mathrm{E}-08$  <br> $-0.300740 \mathrm{E}-09$ 0.0     |
| . 2462 | $0.100387 E-01$ <br> -0.647734E-01 $0.142729 E-01-0.149956 E-01 \quad 0.268973 E-02-0.366623 E-02$ <br> $0.266094 \mathrm{E}-04-0.123509 \mathrm{E}-02-0.409900 \mathrm{E}-03-0.638006 \mathrm{E}-03-0.384268 \mathrm{E}-03$ <br> -0.432917E-03-0.165699E-03 <br> $0.708193 \mathrm{E}-09-0.435064 \mathrm{E}-09.0 .582077 \mathrm{E}-09 \ldots \ldots .383051 \mathrm{E}-10 \quad-0.776102 \mathrm{E}-09$ <br> $-0.151340 \mathrm{E}-08-0.135818 \mathrm{E}-08 \quad 0.853712 \mathrm{E}-09-0.659687 \mathrm{E}-09-0.100893 \mathrm{E}-08$ <br> $-0.688791 E-09 \quad 0.0$ |
| . 3409 |  |
| . 4167 | $0.287099 \mathrm{E}-02$     <br> $-0.542207 \mathrm{E}-01$ $0.109466 \mathrm{E}-01$ $-0.172202 \mathrm{E}-01$ $0.419835 \mathrm{E}-02$ $-0.444102 \mathrm{E}-02$ <br> $0.119386 \mathrm{E}-02$ $-0.865671 \mathrm{E}-03$ $0.345365 \mathrm{E}-03$ $-0.603220 \mathrm{E}-04$ $0.137318 \mathrm{E}-03$ <br> $0.823366 \mathrm{E}-04$ $0.544132 \mathrm{E}-04$    <br> $0.611100-09$ $-0.40754 \mathrm{E}-09$ $0.659687 \mathrm{E}-09$ $-0.116415 \mathrm{E}-09$ $-0.582077 \mathrm{E}-09$ <br> $-0.151340 \mathrm{E}-08$ $-0.159101 \mathrm{E}-08$ $0.659687 \mathrm{E}-09$ $-0.814907 \mathrm{E}-09$ $-0.795505 \mathrm{E}-09$ <br> $-0.863414 \mathrm{E}-09$ 0.0    |
| . 4925 | $0.260773 \mathrm{E}-02$  $0.940461 \mathrm{E}-02$ $-0.143141 \mathrm{E}-01$ $0.354054 \mathrm{E}-02$ $-0.408666 \mathrm{E}-02$ <br> $-0.42853 \mathrm{E}-01$ 0.02     <br> $0.878076 \mathrm{E}-03$ $-0.104239 \mathrm{E}-02$ $0.143435 \mathrm{E}-03$ $-0.247872 \mathrm{E}-03$ $-0.744383 \mathrm{E}-05$  <br> $-0.672270 \mathrm{E}-04$ $-0.120596 \mathrm{E}-04$  $0.50446 \mathrm{E}-09$ $0.776102 \mathrm{E}-10$ $-0.388051 \mathrm{E}-09$ <br> $0.46561 \mathrm{E}-09$ $-0.42656 \mathrm{E}-09$ 0.504466    <br> $-0.128057 \mathrm{E}-08$ $-0.116415 \mathrm{E}-08$ $0.543271 \mathrm{E}-09$ $-0.601479 \mathrm{E}-09$ $-0.601479 \mathrm{E}-09$  <br> $-0.727596 \mathrm{E}-09$ 0.0     |
| . 5683 |  |

Table L. 2 - concluded

| Blade segment Mean Station, r/R | Fourier Series Amplitude Coefficient |
| :---: | :---: |
| . 6441 |  |
| . 7104 |  |
| . 7672 |  |
| . 8145 |  |
| . 8619 |  |
| . 9208 | $-0.222282 \mathrm{E}-03$      <br> $-0.789706 \mathrm{E}-02$ $0.116226 \mathrm{E}-02$ $-0.222527 \mathrm{E}-02$ $0.301690 \mathrm{E}-03$ $-0.611822 \mathrm{E}-03$  <br> $0.431677 \mathrm{E}-04$ $-0.167938 \mathrm{E}-03$ $0.131600 \mathrm{E}-05$ $-0.444057 \mathrm{E}-04$ $-0.489090 \mathrm{E}-07$  <br> $-0.120260 \mathrm{E}-04$ $0.577294 \mathrm{E}-06$     <br> $0.873115 \mathrm{E}-10$ $-0.582077 \mathrm{E}-10$ $0.582077 \mathrm{E}-10$ $-0.970128 \mathrm{E}-11$ $-0.776102 \mathrm{E}-10$  <br> $-0.223129 \mathrm{E}-09$ $-0.261934 \mathrm{E}-09$ $0.073115 \mathrm{E}-10$ $-0.130967 \mathrm{E}-09$ $-0.116415 \mathrm{E}-09$  <br> $-0.152795 \mathrm{E}-09$ 0.0     |
| . 9636 |  |
| . 9882 |  |



Table L. 3 - concluded


## APPENDIX M

## ATRS Blade Airfoil Coordinates

The following tables present the ATRS blade airfoil surface coordinates normalized by the airfoil chord. The $X$ coordinate is parallel to the airfoil chord and is zero at the airfoils' most forward extremity. The Y coordinate is perpendiuclar to the $X$ coordinate; positive in the direction of the upper surface. The coordinates are referenced to the chord except for the SC-1095 airfoil, which is referenced to a line parallel to, but located $.17 \%$ chord above the airfoil chord.

## Table M. $1 \quad$ SC-1095 Airfoil coordinates

| er | surface |
| :---: | :---: |
| X/C | Y/ |
| 0.0 | 0. |
| 0.000 | 0 |
| 0.003 | 0 |
| 0.009 | 0.0152640 |
| 0.0183300 | 00.0219940 |
| 0.0 | 0.0287360 |
| 0 | 0 |
| 0. | 0.0401600 |
| 0.0821700 | 00.0442810 |
| 0.1049900 | 00.0473760 |
| 0.13025 | 0.0500600 |
| 0.1577 | 0.0 .0521800 |
| 0.1872900 | 00.0539200 |
| 0 | 0.0550200 |
| 0.2349500 | 0.0 .0553800 |
| 0.2516300 | 00.0555220 |
| 0.2686500 | 00.0555560 |
| 0.2859800 | 00.0554370 |
| 0.3036100 | 00.0551880 |
| 0.3215000 | 00.0548320 |
| 0.3396100 | 0.0 .0543890 |
| 0.3579300 | 00.0538760 |
| 0.3764200 | 00.0533060 |
| 0.3550500 | 00.0526880 |
| 0.4138000 | 00.0520280 |
| 0.4326200 | 00.0513280 |
| 0.4515000 | $0 \quad 0.0505870$ |
| 0.4704200 | 0.0 .0498000 |
| 0.4893400 | 0.0489610 |
| 0.5082500 | 00.0450630 |
| 0.5271400 | $0 \quad 0.0470550$ |
| 0.5459900 | 00.0460470 |
| 0.5648100 | 00.0449100 |
| 0.5835900 | 00.0436730 |
| 0.6023200 | 00.0423260 |
| 0.6209800 | 0 0..0408720 |
| 0.6395600 | 00.0393000 |
| 0.6580200 | 00.0376160 |
| 0.6763400 | 00.0358230 |
| 0.6944700 | 00.0359350 |
| 0.7123900 | 00.0319640 |
| 0.7300500 | 00.0299320 |
| 0.7474200 | 00.0278610 |
| 0.7644600 | 0.0 .0257780 |
| 0.7811300 | 00.0237120 |
| 0.7974000 | 00.0216950 |
| 0.8132300 | $0 \quad 0.0197570$ |
| 0.8286000 | $0 \quad 0.0178200$ |
| 0.8578000 | 00.0144010 |
| 0.8847500 | 0.0107400 |
| 0.9093200 | $0 \quad 0.0076470$ |
| 0.9312300 | 00.0048360 |
| 0.9503600 | 0.0 .0024750 |
| 0.9665400 | 00.0004360 |
| 0.9734900-0.0002330 <br> 0.9656000-0.0010618 <br> 1.0000000-0.0017000 |  |
|  |  |
|  |  |

## Lower surface


$0.0015000-0.0045090$
$0.0052400-0.0090190$
0.0111900-0.0136550
0.0194300-0.0183320
0.0300900-0.0228170
0.0432100-0.0268230
$0.0587600-0.0301220$
0.0766900-0.0326180
$0.0969400-0.0343760$
0.1194500-0.0356080
$0.1441000-0.0366080$
$0.1707700-0.0376320$
0.1992900-0.0387180
0.2294600-0.0393250
$0.2450900-0.0393920$
$0.2610600-0.0394470$
0.2773300-0.0394000
$0.2938700-0.0392680$
0.3106500-0.0390670
0.3276500-0.0388090
$0.3448300-0.0385060$
$0.3621700-0.0381680$
$0.3796500-0.0378020$
$0.3972300-0.0374130$
$0.4149200-0.0370030$
0.4327000-0.0365730
$0.4505900-0.0361190$
$0.4686100-0.0356380$
$0.4868000-0.0351230$
0.5051900-0.0345660
$0.5237900-0.0339530$
$0.5426200-0.0332880$
$0.5616700-0.0325470$
0.5809300-0.0317250
$0.6003700-0.0308130$
$0.6199700-0.0295040$
0.63968.00-0.0286940
$0.6594700-0.0274820$
0.6792600-0.0261730
$0.6990600-0.0247730$
$0.7187600-0.0232990$
$0.7383100-0.0217690$
$0.7576700-0.0202070$
$0.7767600-0.0180460$
0.7955200-0.0171180
$0.8135600-0.0156630$
0.8317200-0.0143170
0.8490200-0.0131170
$0.8656600-0.0120980$
$0.8815800-0.0107710$
$0.9109300-0.0033240$
$0.9365300-0.0061900$
$0.9579900-0.0044010$
$0.9750400-0.0031170$
$0.9875800-0.0023390$
1.0000000-0.0017000

Table M. 2 SC-1095R8 Airfoil coordinates

| Jpp |  |
| :---: | :---: |
| $x / C$ | Y/ |
| 0.0 | 0 |
| 0.0008200 | 0.0050470 |
| 0.0039700 | 0.0128660 |
| 0.0096600 | 0.0217500 |
| 0.0183300 | 0.0307540 |
| 0.0299900 | 0.0392540 |
| 0.0445700 | 0.0473600 |
| 0.0619900 | 0.0528920 |
| 0.0821700 | 0.0573750 |
| 0.1049500 | 0.0609810 |
| 0.1302500 | 0.0637490 |
| 0.1577500 | 0.0657359 |
| 0.1872900 | 0,0670059 |
| 0.2186600 | 0.0676209 |
| 0.2349500 | 0.0677040 |
| 0.2516300 | 0.0676469 |
| 0.2686500 | 0.0674599 |
| . 2859800 | 0.0671479 |
| 3036100 | 0.0667199 |
| . 3215000 | 0.0661829 |
| 3396100 | 0.0655450 |
| . 3579300 | 0.0648119 |
| 0.3764200 | 0.0639910 |
| 0.3950500 | 0.0630890 |
| 0.4138000 | 0.0621130 |
| 0.4326200 | 0.0610690 |
| 0.4515000 | 0.0599640 |
| 0.4704200 | 0.0558020 |
| 0.4893400 | 0.0575910 |
| 0.5032500 | 0.0563290 |
| 0.5271400 | 0.0545620 |
| 0.5459800 | 0.0535140 |
| 0.5648100 | 0.0519880 |
| 0.5835900 | 0.0503 sis 0 |
| 0.6023200 | 0.0457180 |
| 0.6209800 | 0.0469820 |
| 0.6395600 | 0.0451860 |
| 0.6580200 | 0.0433350 |
| 0.6763400 | 0.0414360 |
| 0.6944700 | 0.0394980 |
| 0.7123500 | 0.0375270 |
| 0.7300500 | 0.0355320 |
| 0.7474200 | 0.0335200 |
| 0.7644600 | 0.0315020 |
| 0.7811300 | 0.0294860 |
| 0.7974000 | 0.0274800 |
| 0.8132300 | 0.0254540 |
| 0.6206000 | 0.0235340 |
| 0.8573300 | 0.0197310 |
| 0.8547800 | 0.0161300 |
| 0.9093200 | 0.0127890 |
| 0.9312300 | 0.0097580 |
| 0.9503600 | 0.0070800 |
| 0.9665400 | 0.0047890 |
| 0.9734900 | 0.0038000 |
| 0.9896000 | 0.0014970 |
| 1.0000000 | 0.0000010 |

Lower surface

$0.0015000-0.0075230$
$0.0052400-0.0121080$
$0.0111900-0.0153640$
0.0194300-0.0177590
$0.0300900-0.0194550$
0.0432100-0.0207000
0.0587600-0.0219420 $0.0766900-0.0227870$
$0.0969400-0.0234150$
$0.1194500-0.0239310$
$0.1441000-0.0244140$
0.1707700-0.0249100
$0.1592900-0.0254340$
$0.2204600-0.0259670$
$0.2450900-0.0262250$
$0.2610600-0.0264600$
0.2773300-0.0265860
$0.2938700-0.0268300$
0.3106500-0.0270340
0.3276500-0.0271460
0.3448300-0.0272100
$0.30 ́ 21700-0.0272230$
0.3796500-0.0271820
0.3972300-0.0270890 0.4149200-0.0265440 0.4327000-0.0267530 0.4505900-0.02065230 0.4666100-0.026-2600 0.4368000-0.0259770 0.5051900-0.0256800 $0.5237900-0.0253340$ 0.5426200-0.0248040 0.5616700-0.0243450 0.5809300-0.0237210 0.6003700-0.0230200 0.6199700-0.0222470 0.6396800-0.0214110 $0.6594700-0.0205200$ $0.6792800-0.0295800$ $0.6990600-0.0186010$ 0.7187600-0.0175880 0.7383100-0.0165520 $0.7576700-0.015 \div 500$ $0.7767600-0.0144300$ $0.7955200-0.0133590$ 0.8136600-0.0122900 0.5317200-0.0112290 $0.8490200-0.0101830$ $0.5656600-0.0091580$ $0.8515000-0.0081650$ $0.9109300-0.0062670$ $0.9365300-0.0045560$ $0.9579900-0.0030710$ $0.9750400-0.0010530$ $0.9875300-0.0009340$ $1.0000000-0.0000020$

|  |  |
| :---: | :---: |
|  |  |
|  |  |
| 0.0008200 | 0.00 |
| 0.0039700 | 0.0177877 |
| 0.0096600 | 0.0300702 |
| 0.0183300 | 0.0425185 |
| . 0299900 | 0.0542701 |
| . 044570 | 0.0654769 |
| 0.0619900 | 0.0731251 |
| . 0823700 | 0.0793230 |
| 1049900 | 0.0843084 |
| 1302500 | 0.0881354 |
| 0.1577500 | 0.0908824 |
| 1872900 | 0.0926382 |
| 2186600 | 0.0934885 |
| 49500 | 0.0936033 |
| 300 | 0. |
| 2686500 | 0. |
| 2859800 | 0. |
| 036100 | 0.0 |
| 3215000 | 0.0915004 |
| 100 | 0.0906184 |
| 0.3579300 | 0. |
| 0.3764200 | 0. |
| 0.3950500 |  |
| 0.4138000 |  |
| 0.4326200 |  |
| 0.4515000 |  |
| 0.4704200 |  |
| . 4893400 |  |
| 0.5082500 | 0. |
| 0.5271400 |  |
| 0.5459900 | 0. |
| 0.5648100 | 0. |
| 0.5635900 | 0. |
| 0.6023200 | 0. |
| 0.6209800 |  |
| 0.6355600 |  |
| 0.6580200 | 0.05 |
| 0.6763400 | 0.0572368 |
| 0.6544700 | 0.05 |
| 0.7123900 | 0.0518824 |
| 0.7300500 | 0.0491243 |
| 0.7474200 | 0.0463426 |
| 0.7644600 | 0.0435526 |
| 0.7811300 | 0.0407655 |
| 0.7974000 | 0.0379921 |
| 0.8132300 | 0.0352464 |
| 0.8286000 | 0.0325366 |
| 0.8578000 | 0.0272758 |
| 0.8547800 | 0.0223003 |
| 0.9093200 | 0.0176813 |
| 0.9312300 | 0.0134908 |
| 0.9503600 | 0.0097884 |
| 0.9665400 | 0.0066210 |
| 0.9734500 | 0.0052536 |
| 0.9896000 | 0.0020697 |
| 1.000000 | 0.00000 |

## Lower surface

$0.0^{\frac{X / C}{Y / C}}$
$0.0015000-0.0104008$
$0.0052400-0.0167398$
0.0111900-0.0212413
0.0194300-0.0245525
0.0300900-0.0268973
0.0432100-0.0286185
0.0587600-0.0303356
0.0766900-0.0315039
0.0969400-0.0323721
0.1194500-0.0330855
0.1441000-0.0337533
$0.1707700-0.0344390$
0.1992900-0.0351634
$0.2294600-0.0359003$
0.2450900-0.0362570
0.2610600-0.0365930
0.2773300-0.0368571
0.2938700-0.0371626
0.3106500-0.0373755
0.3276500-0.0375304
$0.3443300-0.0376100$
0.3621700-0.0376368
$0.3796500-0.0375801$
0.3972300-0.0374515
0.4149200-0.0372511
0.4327000-0.0365870
$0.4505900-0.0306690$
$0.40686100-0.0363054$
0.4858000-0.0359142
0.5051900-0.0355146
0.5237900-0.0350252
0.5426200-0.0344031
0.5616700-0.0336579
0.5309300-0.0327852
0.6003700-0.0318260
0.6199700-0.0307573
0.6356800-0.0296015
0.6554700-0.0283697
0.6792800-0.0270701
0.6990600-0.0257166 $0.7187600-0.0243161$ 0.7383100-0.0228338 0.7576700-0.02136́02 0.7767600-0.0199500 0.7955200-0.0184693 0.8138600-0.0169914 $0.8317200-0.0155245$ $0.8490200-0.0190704$ $0.8656600-0.0126613$ 0.8815800-0.0112939 $0.9109300-0.0086644$ 0.9355300-0.0062938 0.9579900-0.0042458 0.9750400-0.0025618 0.9875800-0.0012913 1.0000000-0.0000028


