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DESIGN AND IMPLEMENTATION OF A PREPROCESSING SYSTEM FOR A SODIUM LIDAR

by
D. G. Voelz
C. F. Sechrist, Jr.

September 1, 1983



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ABSTRACT

A preprocessing system was designed and constructed for use with the University of Illinois sodium lidar system. The preprocessing system was developed to increase the altitude resolution and range of the lidar system and also to decrease the processing burden of the main lidar computer. This work describes the preprocessing system hardware and the software required to implement the system. Also presented are some preliminary results of an airborne sodium lidar experiment conducted with the preprocessing system installed in the sodium lidar.

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1. INTRODUCTION

1.1 University of Illinois Sodium Lidar Observations

Late in the 1930's a layer of sodium vapor was discovered in the earth's mesosphere. Observations of the layer since that time have determined that the layer is generally confined to an altitude range of 80 to 100 km with a peak density near 90 km. The upper and lower boundaries of the layer are sharply defined and seasonal and daily variations in the layer have been observed. The layer continues to be studied in order to gain a better understanding of the motions in the layer and the neutral and ion chemistry of the region.

Laser radar (lidar) has been used in the remote sensing of atmospheric constituents since the early 1960's. Initial nighttime lidar observations of the mesospheric sodium layer were conducted late in the 1960's in England [Bowman et al., 1969]. Since then, similar measurements by several sodium lidar groups in various locations have been reported. Initial lidar observations of the layer at the University of Illinois were made in 1977.

During the early experiments at the University of Illinois, emphasis was placed on observing relative structural changes in the layer [Richter and Sechrist, 1978]. In conjunction with this effort, a theory of sodium layer ion chemistry was developed [Richter and Sechrist, 1979]. To aid in the analysis of the data, signal processing techniques were developed and implemented [Rowlett and Gardner, 1979]. As the performance of the lidar system improved, theoretical and experimental studies of the response of the layer to gravity wave perturbations were conducted [Shelton and Gardner, 1981]. Recent interest has been directed toward studies of the horizontal structure of the layer and the implementation of a daytime sodium lidar system.

1.2 General and Sodium Lidar Concepts

Lidar is a remote sensing technique utilizing electromagnetic waves at optical frequencies. The detecting and locating of objects are accomplished by transmitting a laser pulse and analyzing the nature of the returned signal. Lidar systems require targets that exhibit scattering characteristics when subjected to a laser pulse such that a signal returning from the target is detectable above noise.

A basic lidar system consists of a pulsed laser, a receiving telescope, a photodetector such as a photomultiplier tube, and data collection electronics. The laser provides the transmitted pulse. Returning photons back-scattered by the target are collected by the telescope. The photodetector converts the collected photons to electrical pulses which are analyzed and recorded by the data collection electronics.

The distance or range to the target is determined by measuring the elapsed time t_r between the transmitted and received pulses. The range R is given by

$$R = 1/2 ct_r$$

where $c = 3 \times 10^8$ m/s, the speed of light. The 1/2 accounts for the two-way propagation of the pulse. Further qualities of the target may be ascertained by observing the intensity and/or the pulse shape of the returning signal.

Sodium lidar utilizes the resonant scattering mechanism of neutral sodium atoms in the mesosphere. A pulse of light at a wavelength corresponding to a sodium transition line and incident on a mesospheric sodium atom causes a fluorescence which results in an enhancement of the returning signal. A tunable dye laser operating at 589.0 nm, the D_2 transition line

of sodium, is commonly used to provide the transmit pulse.

Sodium lidar receiving systems generally operate in a photon-counting mode and use a range gate collection technique. As the transmit pulse propagates through the mesosphere, backscattered photons are counted over short time intervals Δt . The set of counts from the sequential intervals is a record of the photocounts versus range. The "range gate width" ΔR is the range resolution of this type of system and is given by

$$\Delta R = 1/2c\Delta t.$$

The interval time Δt is often referred to as the "range gate time." "Range bin" is a term applied loosely to the storage location of the counts for a particular interval. The range R_i corresponding to the i th range bin is given by

$$R_i = 1/2c(t + \Delta t/2)$$

where t is the time elapsed between the transmitting of the laser pulse and the beginning of the collection of the counts in the i th range bin. An estimate of the density of a target at a particular range (for example, sodium density at 90 km) is obtained by examining the number of counts in the corresponding range bin.

Unfortunately, in most sodium lidar systems the signal-to-noise ratio for a single laser pulse is quite poor. A common method of increasing the signal-to-noise ratio is to integrate over many laser pulses. This simply involves collecting counts for single laser pulses as described above and then adding the range bin counts to corresponding range bin counts of previous laser pulses. The completed integration process results in a set of range bin counts which are collectively termed a "profile." The term "profile integration sum," in this report, refers to the range bin counts of an incomplete profile. The integration technique does increase the signal-

to-noise ratio but the time resolution of the system is decreased.

1.3 Objectives of This Investigation

The main objectives of this investigation were to design and implement a preprocessing system for use in the receiving section of the University of Illinois sodium lidar system. The system was designed and developed to increase the altitude resolution and range of the lidar system and also to decrease the processing burden of the main lidar computer by performing the integration of the data collected from successive laser shots.

A secondary objective is to present some preliminary results of an airborne sodium lidar experiment conducted by the University of Illinois Aeronomy Laboratory (Lidar Group) in conjunction with the National Aeronautics and Space Administration (NASA). The initial testing of the preprocessing system with the complete lidar system was conducted during this experiment, and the experimental results establish a high confidence level of operation for the preprocessing system.

2. UNIVERSITY OF ILLINOIS LIDAR SYSTEM

2.1 Introduction

Observations of the mesospheric sodium layer with lidar techniques began in 1977 at the University of Illinois [Richter and Sechrist, 1978]. The lidar system at this time consisted of a flashlamp-pumped dye laser developed at the University, a 0.38 m diameter Fresnel lens receiving telescope, a liquid nitrogen cooled photomultiplier tube (PMT), and a signal pulse discriminator and counter developed in a Physics Department research project. The system was located at the Aeronomy Laboratory Field Station near Urbana, Illinois. A Digital Equipment Corporation (DEC) PDP-15 computer at the Field Station directed the collection and storage of the data.

The next few years produced several changes in the Urbana lidar system. A counter interface was built to replace the Physics Department's pulse counter [Kinter, 1977]. The interface was designed to operate with an HP 2114A microcomputer which allowed the system to be independent of the Field Station PDP-15. In 1979, a 1.22 m diameter Fresnel lens telescope superseded the 0.38 m telescope [Rowlett and Gardner, 1979]. Also in 1979, a Digital Group Z-80 microcomputer replaced the HP 2114A [Teitelbaum and Sechrist, 1979]. Early in 1981, a flashlamp-pumped dye laser, built by the Candela Corporation, was purchased for the lidar system. This laser had better reliability and provided a higher pulse repetition rate than the previous laser. Two other items were also acquired early in 1981: an electrically cooled PMT housing which replaced the liquid nitrogen cooling system; and a pulse discriminator built by Princeton Applied Research, which replaced the Physics discriminator. Later in 1981, the lidar computer system

was again upgraded with a DEC LSI-11/2 microcomputer replacing the Z-80 [Vogel, 1982].

As the reliability and performance of the system increased, sodium lidar observations became feasible at sites other than Urbana. This allowed more diverse sodium lidar observations to be made as the lidar system was integrated with specialized pieces of equipment and facilities at other sites. In June 1981, October 1981, and May 1982 sodium lidar campaigns were conducted at the National Aeronautics and Space Administration (NASA) Goddard Space Flight Center (GSFC) near Greenbelt, MD. A steerable 48-inch astronomical telescope at GSFC allowed scanning-type (off-zenith) observations of the sodium layer to be made. In March 1983, an airborne sodium lidar experiment was conducted at the NASA Wallops Flight Center, Wallops Island, VA. Chapter 5 contains some preliminary results of this experiment.

The most recent addition to the lidar system is the preprocessing system described in the following chapters of this report. The preprocessing system replaces the old counter interface while also reducing the data processing burden of the LSI-11 main computer. The following sections of this chapter describe the lidar system hardware at the present time. A block diagram of the lidar system with the preprocessing system installed is shown in Figure 3.2 of Chapter 3.

2.2 Transmitting System

The principal component of the transmitting system is a Candela LFDL-1 flashlamp-pumped tunable dye laser utilizing Rhodamine 6G Perchlorate in a methyl alcohol and water solution. The laser consists of three subsystems: (1) a laser head which contains the optical cavity, dye cell, and flashlamp; (2) a refrigeration/circulation (chiller) unit used for both cooling and dye flow systems; and (3) a control unit/high voltage power supply. The laser:

parameters are given in Table 2.1.

Laser tuning is achieved through a grating and an etalon in the laser cavity. Coarse tuning adjustments are made manually with the grating while fine adjustments are made with the etalon which is positioned by a Burleigh motor-micrometer. The wavelength of the laser beam is monitored by diverting a small fraction of the beam to a monochromator and to a hollow-cathode sodium discharge tube. The monochromator, in combination with a Reticon diode array line scanner (part numbers: RC 301, RL 256G), is used to display the intensity of the laser beam portion as a function of wavelength on an oscilloscope. The output of a sodium lamp is also displayed as a reference. Coarse tuning adjustments are monitored with this arrangement. Fine tuning adjustments are monitored by observing the laser-induced changes in the voltage between the electrodes of the gas discharge plasma in the hollow-cathode sodium tube (opto-galvanic effect). The electrode voltage is displayed on an oscilloscope.

Completing the transmitting system are the final laser beam output optics which generally include a beam expander to reduce beam divergence, and dielectric-coated mirrors to steer the laser beam.

2.3 Receiving System

The major components of the receiving system are the telescope, the photomultiplier tube (PMT) and its associated electronics, and the pre-processing and main computer systems. A 1.22 meter diameter $f/1.56$ acrylic Fresnel lens is the collecting element for the telescope utilized at the Urbana site. A detailed discussion of the telescope is provided by Rowlett and Gardner [1979]. A 48-inch Cassegrain astronomical telescope with Coude focus was employed for observations conducted at NASA Goddard Space Flight Center. The telescope is part of a versatile facility that also includes a

TABLE 2.1 CANDELA LFDL-1 LASER PARAMETERS.

Wavelength	589.0 nm
Pulsewidth (FWHM)	2 μ sec
Linewidth	1 pm
Energy per pulse	50 mj
Pulse repetition rate	10 Hz
Beam divergence	1 mrad
Flashlamp lifetime	3 x 10 ⁶ shots

computer-controlled pointing system capable of tracking stars and satellites. The airborne lidar system at NASA Wallops Flight Center utilized a 16-inch diameter primary, Newtonian configured telescope.

The telescope optics required for the 1.22 m Urbana telescope are shown in Figure 2.1. The collected photons are focussed by the Fresnel lens onto the plane of a field-stop iris. Beyond the iris, the beam is collimated by a Nikon 35 mm $f/1.4$ lens prior to its passage through an interference filter. The interference filter is used to reduce the number of photons due to background sky illumination. Two temperature controlled filters with bandwidths of 5 and 0.5 nm are currently used with the system. The filter selected for a particular experiment depends on the experimental objectives, received signal intensity at the time of the experiment, etc. A lens in the PMT housing focusses the photons passed by the filter onto the cathode of an RCA C31034A PMT. To reduce dark counts, the PMT is thermoelectrically cooled by a Products for Research Model TE-206TS-RF cooled housing.

Due to the relatively long focal lengths of the 48-inch Goddard telescope (1300 in, $f/27$) and the 16-inch Wallops telescope (approximately 400 in, $f/25$), the receiving optics arrangement following these telescopes is simplified from that shown in Figure 2.1. The long focal lengths provide a nearly collimated beam of collected light at the focus of the telescope. Therefore, the field-stop iris and the Nikon collimating lens are not required in front of the interference filter and the PMT focusing lens is positioned at the focal point of the telescope.

The output of the PMT is applied to a Princeton Applied Research Model 1121 Amplifier-Discriminator. The discriminator compares the pulses generated by the PMT to a preset threshold level. NIM standard (18 mA (-1 V), 12 nsec) and emitter-coupled logic (ECL) level pulses are produced

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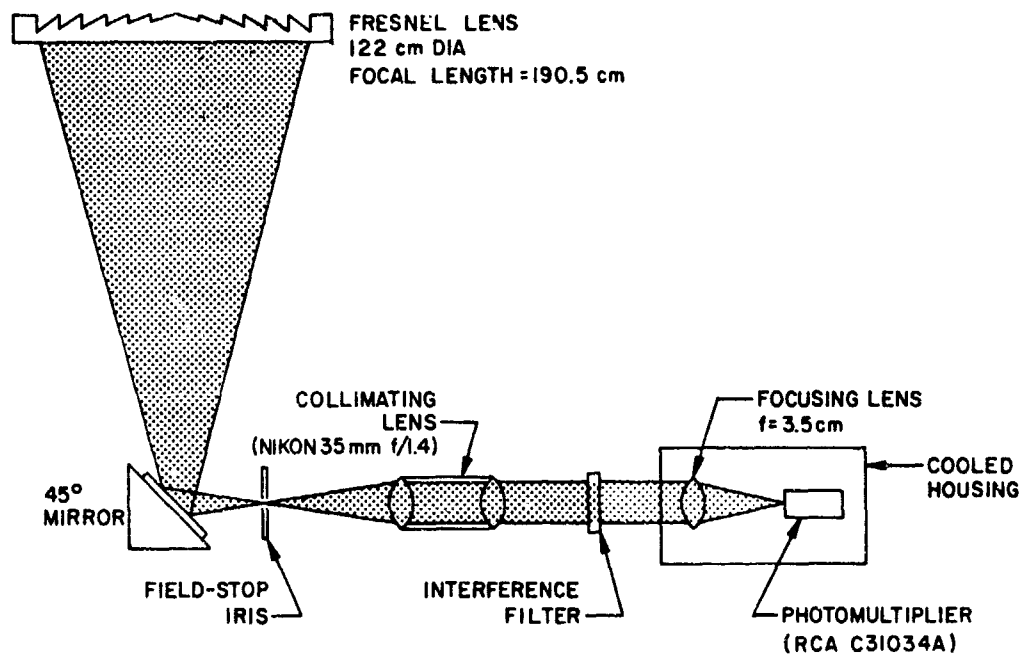


Figure 2.1 Schematic diagram of 1.22 m telescope optics [Rowlett and Gardner, 1979].

by the discriminator after receiving PMT pulses that exceed the threshold. The discriminator pulses (currently from the NIM standard output) are counted by the preprocessing system.

At very high counting rates (above 20 MHz) the PMT is subject to overloading conditions which cause significant errors in the recorded number of detected photons. Strong Rayleigh scattering of the laser beam below 30 km altitude consistently provides very high counting rates that disturb counts collected from altitudes below 30 km as well as those collected from altitudes above 30 km as the PMT is recovering. A PMT blanking controller and a timing controller were constructed to alleviate PMT overloading due to Rayleigh scattering [Shelton and Gardner, 1981].

The blanking controller achieves the blanking or gating of the PMT by reducing the voltage of the first dynode of the PMT with respect to the PMT cathode potential, effectively decreasing the overall gain of the PMT. Measurements on this system indicate the gain is reduced by approximately 3 orders of magnitude. The PMT recovery time after blanking has been observed to be on the order of 6 to 10 μ sec. Therefore, the blanking controller can be engaged to blank the PMT as scattered signal below 30 km altitude is collected, and disengaged for data collection above 30 km altitude.

The timing controller synchronizes the firing of the laser and the PMT gating. The triggering of the timing controller is initiated by a pulse received from the preprocessing system. After triggering, the timing controller engages the blanking controller and delays 5 μ sec before sending a trigger pulse to the laser. The delay ensures the blanking of the PMT is complete as the laser fires. Approximately 200 μ sec after the laser triggering (corresponding to an altitude of 30 km), the blanking controller is disengaged and data collection continues. A variable resistor in the timing

controller sets the blanking duration.

The preprocessing and LSI-11 main computer systems are discussed in the following chapters. In general, the preprocessing system initiates the laser firing, counts the discriminated pulses from the amplifier-discriminator, and integrates the counts from consecutive laser shots. The main computer directs the overall experiment and permanently stores the collected data on a floppy disk.

3. THE PREPROCESSING SYSTEM

3.1 Introduction

The sodium lidar preprocessing system is designed to direct the collection of data for one concentration vs. altitude profile of the mesospheric sodium layer. The system controls laser firing, counts the returning discriminated photon pulses, sections the counts into appropriate range bins, and integrates similar range bins over consecutive laser shots to form a profile. Completed profiles are sent to a main computer for further processing and storage. As mentioned previously, the system was devised to decrease the data processing burden of the main computer.

The system consists of two major pieces of hardware: an Apple II Plus microcomputer and the Sodium Lidar Preprocessing (SLIPP) interface unit. Other hardware items include a Direct Memory Access (DMA) circuit for the Apple-SLIPP unit communications and a RS-232 standard serial communications link between the Apple and the main computer. Software routines drive the Apple and the main computer.

The Apple computer masterminds the profile collection. All communications with both the SLIPP unit and the main computer, laser firing, and integrations are handled through the Apple's software. The range bin counts and the profile integration sum are stored in the Apple's Random Access Memory (RAM). The Apple also displays messages on its video screen to notify the lidar operator of the present status of the system.

The SLIPP unit interfaces the Apple to the transmitting and receiving sections of the lidar system. Line driver circuitry in the SLIPP unit allows the laser to be triggered by the Apple. After a laser shot the received photon pulses are counted in the SLIPP unit. The SLIPP unit has no

memory of its own so each range bin collected is immediately transferred to the Apple RAM through the DMA circuitry.

Although not strictly considered part of the preprocessing system, the lidar main computer and its software are closely associated with the preprocessing system. The main computer for the University of Illinois lidar system is a DEC LSI 11/2 computer. The LSI-11 directs the overall experiment. It is programmed with the information on time to collect a data profile and the number to collect. Through the LSI-11 terminal the lidar operator is able to access and change these experiment parameters. An RS-232 standard serial communications link allows the LSI-11 to send commands to the Apple and the Apple to send data profiles back to the LSI-11. The LSI-11 also gives the operator a summary of each of the completed profiles and stores the profiles on a floppy disk.

3.2 Data Acquisition Timing

The desired pulse repetition rate of the laser and the desired rate of collecting data profiles were two parameters of particular interest during the designing of the preprocessing system. The system had to be able to integrate data from consecutive laser shots with enough speed to let the laser operate at its maximum pulse rate (10 Hz), and the data transfer from the preprocessing system to the main computer had to be reasonably fast so as not to cause any long delays between data profiles. Figure 3.1 is a timing diagram of the data collection process timing for the completed preprocessing system.

Part (a) of Figure 3.1 shows the collection process for a single laser pulse. The laser is initially triggered by the preprocessing system. Two thousand range bins of data are then immediately collected. This requires about 2000 μ secs as the range gate time is 1 μ sec for each bin. Another

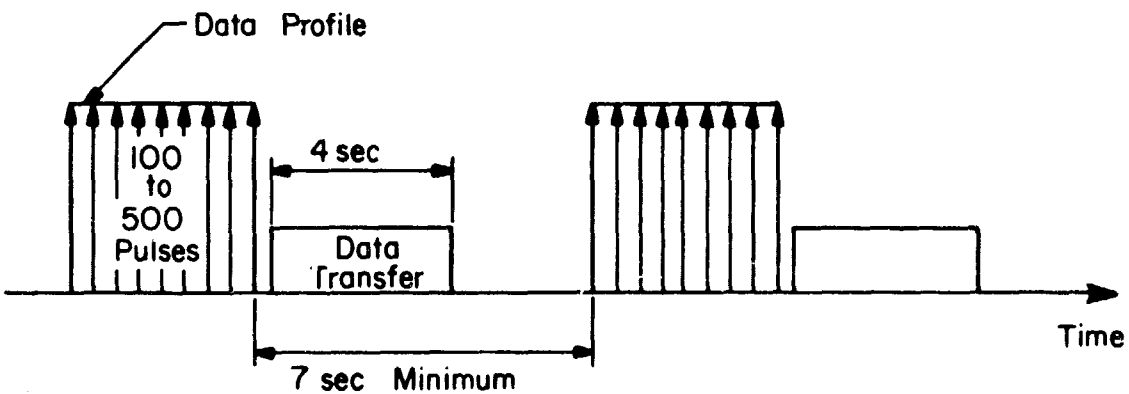
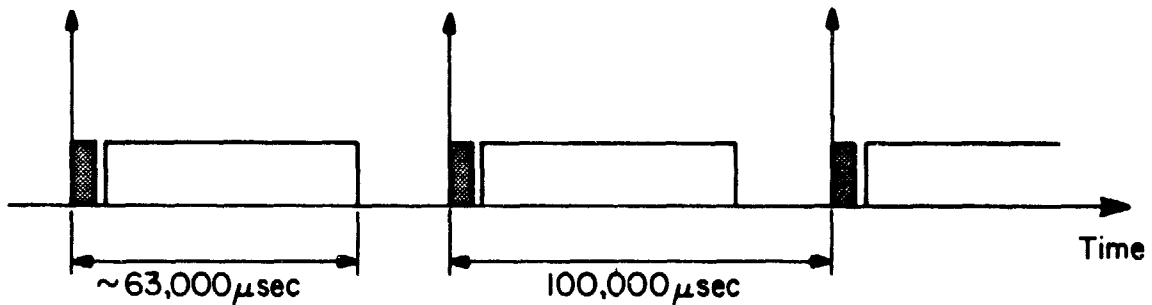
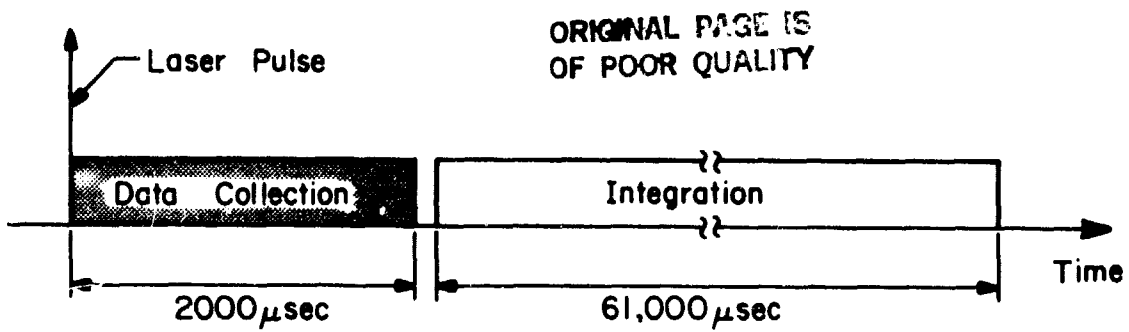


Figure 3.1 Data acquisition timing for: (a) a single laser pulse, (b) repeating laser pulses, and (c) full profiles.

61,000 μ secs are required by the Apple to integrate the data from the current laser shot into the profile integration sum. Therefore, the data preprocessing requires about 63,000 μ sec total per laser pulse.

Repeating laser pulses at 10 Hz are shown in part (b) of Figure 3.1. The data collection and integration times are denoted after each laser pulse. It is evident that the preprocessing system is able to operate with laser pulse rates exceeding 10 Hz.

Part (c) of Figure 3.1 shows the collection of completed profiles. A data profile is stored in Apple RAM as 2000 16-bit words. Therefore, roughly 4 seconds are required for the Apple to send the completed profile over the serial link to the LSI-II at 9600 baud. The LSI-11 uses another 3 seconds to store the profile on a floppy disk and give the operator a summary of the profile. The total delay of 7 seconds between the end of one profile and the beginning of the next is tolerable. More details on system timing are included in Section 3.4 on system parameters.

3.3 System Operation Description

This section describes in general terms the interactions of the preprocessing system with the rest of the lidar system during the collection of a data profile. Figure 3.2 is a block diagram of the lidar system with the preprocessing system installed. Some of the block items in the figure are explained in more detail in Chapter 2 on the lidar system hardware. The figure is a useful reference for the following discussion on the system operation.

A lidar data run begins with the operator inputting or changing experiment parameters on the LSI-11 terminal. These parameters include the number of profiles per set, the profile range bins to be saved, laser rep rate, etc. (see Section 5.2.2). Once the operator has initiated a data run,

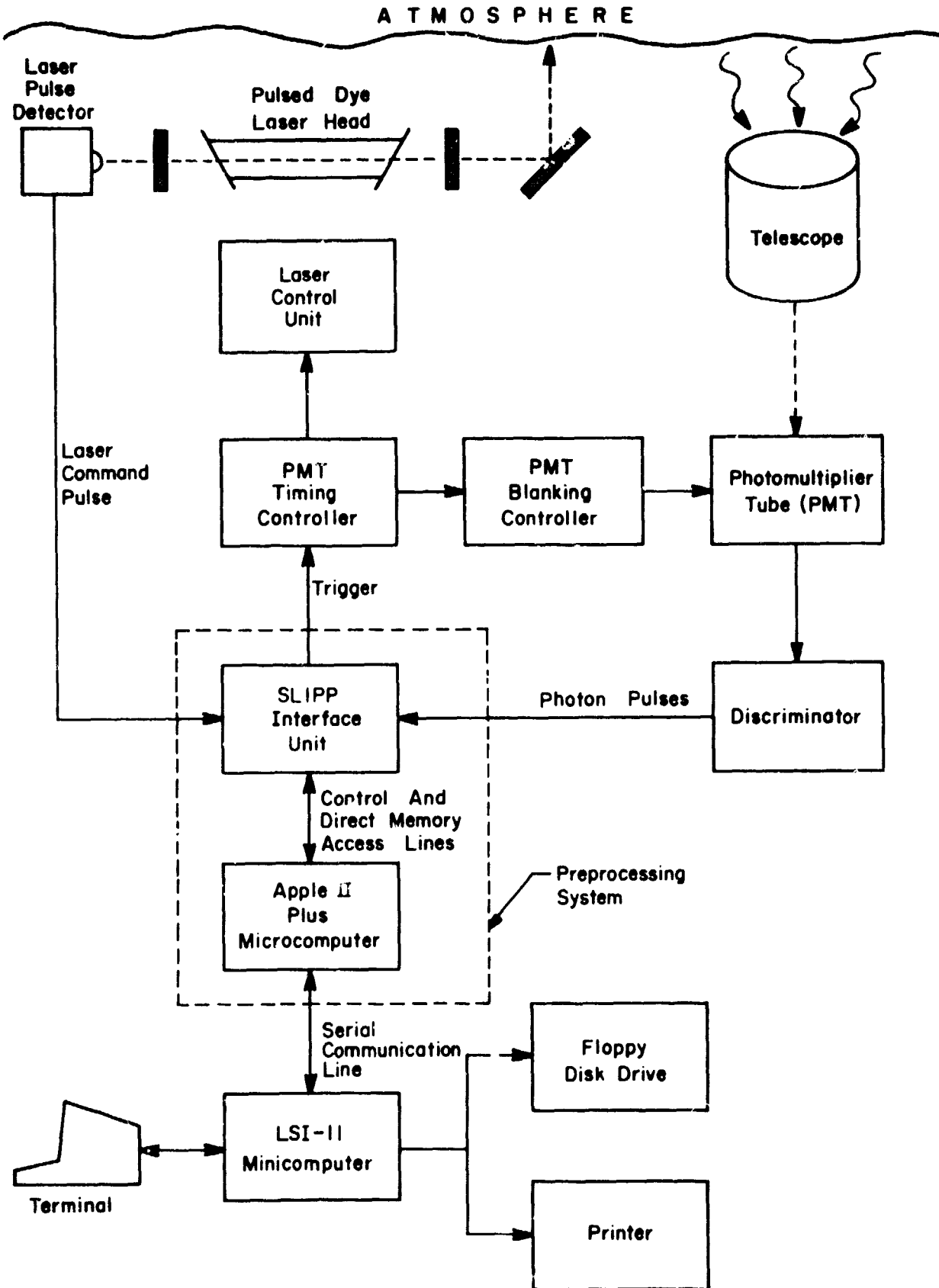


Figure 3.2 Lidar system with preprocessing system installed.

the LSI-II sends two communication frames to the Apple over the serial link. The first frame contains information on the desired laser pulse rep rate and the desired number of laser shots per profile. The second frame signals the Apple to begin collecting a profile.

The first action of the Apple upon the receipt of the "data run" frame is to initialize the DMA circuitry for data transfer from the SLIPP unit to the Apple RAM. Next, the Apple clears the block of RAM that holds the profile integration sum. Finally, the Apple sends the laser trigger pulse to the SLIPP unit. The laser pulse not only passes through the SLIPP unit to trigger the laser and the PMT timing circuitry but also enables the SLIPP unit for counting.

Once enabled, the SLIPP unit waits for the Laser Command Pulse (LCP). This is a positive logical pulse that is generated by a laser pulse detector when the laser fires. The LCP notifies the SLIPP unit that the laser has fired and the unit begins counting photon pulses in 1 μ sec intervals. At this point the DMA circuitry takes control of the Apple buses and each interval, or range bin, collected is immediately stored in the Apple RAM through DMA. The SLIPP unit actually uses two toggling counters in order that during any 1 μ sec interval, one counter is counting photon pulses while the contents of the other counter are being placed in memory. When all of the range bins are collected, normally 2000, the DMA circuitry disables the SLIPP unit and the Apple regains control of its address and data buses.

Next, the Apple checks a status bit in the DMA circuit to be sure the DMA occurred. If the bit is not set a problem occurred, such as the laser never fired, and the Apple jumps to an error routine. With the bit set, the Apple adds the new range bin counts into the profile integration sum. The collection process is now complete for one laser shot. The Apple checks to

see if the profile requires more laser shots. If so, the Apple sends the next laser trigger pulse, enables the SLIPP unit, and the collection begins again. If the profile is complete it is sent over the serial link to the LSI-11.

After receiving the profile the LSI-11 does some simple calculations and gives the operator a summary of the profile (see Section 5.2.2 for more details). The summary is given both on the terminal and a hard copy printer. The data are stored on a floppy disk and the collection of one profile is complete. If more profiles are to be collected, the LSI-11 sends the "data run" frame to the Apple again. If the set of profiles is finished the LSI-11 alerts the operator and waits for the next command.

3.4 System Parameters

This section contains descriptions and values of the important parameters of the preprocessing system. Definitions of some of the terms used in this section can be found in Section 1.2. A list of the parameter values is given in Table 3.1.

Range Gate:

The range gate time is fixed by the logic in the SLIPP interface unit at 1 μ sec. This corresponds to a range gate width of 150 meters for each range bin. This is the maximum resolution of the system.

Range Bins:

The preprocessing system currently collects 2000 range bins of data for each laser shot. With the 1 μ sec range gate time mentioned above, the total system range is 300 km. The number of range bins used for data collection may be changed with a few Apple software alterations.

Photon Pulse Count Bandwidth:

The counters and associated logic in the SLIPP interface unit are

TABLE 3.1 PREPROCESSING SYSTEM PARAMETERS.

Range gate time	1 μ sec
Number of range bins	2000
Photon pulse input (NIM)	-18 mA(\approx -1 V), 12 nsec
Photon pulse count bandwidth	50 + MHz
Inter-profile period	7 sec

capable of detecting NIM standard (-18 mA (-1 V), 12 nsec) signal pulses with rates exceeding 50 MHz. However, the discriminator used by the University of Illinois sodium lidar (P.A.R.C. Model 1121) which provides the pulses for the counters is rated at only 37 MHz for random pulses. It is also apparent that the PMT in the sodium lidar system (RCA C31034A) generally overloads at count rates approaching 20 MHz. The SLIPP unit was also designed for possible future expansion to a balanced, emitter-coupled logic (ECL) compatible, 5 nsec pulse count input. This would reduce noise created in the cable between the discriminator and the SLIPP unit. The balanced ECL and standard NIM outputs are both provided by the P.A.R.C. 1121 discriminator.

Data Acquisition Rate:

The time necessary to obtain one sodium data profile is, of course, dependent on the number of laser shots required and the laser repetition rate. A little more than 4 seconds are necessary for a profile to be transferred from the Apple to the LSI-11. Three seconds are required by the LSI-11 to display a summary of the profile on the terminal and printer, and store the profile on a floppy disk. Therefore, with a laser operating at 10 Hz, a profile requiring 100 shots can be collected in about 17 seconds.

Data Storage:

Apple Memory - The Apple Random Access Memory is used to temporarily store the incoming range bin counts and the profile integration sum. The range bin counts are recorded in 2000 8-bit bytes in an area of memory designated as "buffer memory." Two thousand integration sum bins are each 16 bits in length and stored in an area designated as "mainframe memory." For programming ease 2048 (2K) bytes are allocated as buffer memory and 4096 (4K) bytes are allocated as mainframe memory. The high order bytes and the

low order bytes of the 16-bit words in the mainframe memory are divided into two sections. This is a result of the addition routine used by the Apple to form the profile integration sum.

LSI-Memory - A profile is sent from the Apple to the LSI-11 with the low order bytes of the 16-bit words first and the high order bytes second. The bytes are assembled upon receipt by the LSI-11 into 16-bit words and stored in the array LDATA.

LSI-11 Floppy Disk - The LSI-11 computer permanently stores sets of sodium data profiles on a floppy disk with a DEC floppy disk drive (both RX01 and RX02 type drives have been used). The profile sets are stored as unformatted direct access files. The name assigned to each file is SETxxx.DAT, where xxx is the number of the set. For example, SET001.DAT is the file name for the first set collected in a data run.

4. CIRCUITS DESCRIPTION

4.1 Apple Direct Memory Access Circuit

4.1.1 Introduction. Direct Memory Access is a fast and efficient method of transferring data to or from a computer's memory. This method involves a specialized device communicating directly with the computer's memory. The data transfer can therefore be performed with minimum interaction from the microprocessor (MPU). The sodium lidar preprocessor design requires the Apple's Random Access Memory to store incoming photon counts from the SLIPP interface unit. The counts are recorded in bytes every microsecond which corresponds to a data transfer rate of 1 Mbyte/sec. This rate is much too fast for the Apple to handle in a software polling loop or an interrupt routine. Therefore, DMA is a necessity. The DMA controller selected for this project was the Motorola MC6844 Direct Memory Access Controller (DMAC) chip. The chip was designed for use with the Motorola MC6800 series microprocessors. However, strong similarities between the MOS 6502 microprocessor in the Apple and Motorola's MC6800 allow the MC6844 DMAC to work well with the Apple's circuitry.

4.1.2 Apple timing. All clock signals, memory strobe signals, and video signals in the Apple II Plus are derived from a single 14.138 MHz oscillator on the main Apple circuit board. The various signals are obtained by using a number of counters, shift registers and multiplexers. Figure 4.1 is a typical timing diagram for some of the Apple signals. 7M is an intermediate timing signal, ϕ_0 and ϕ_1 are system clocks, and Q3 is an asymmetrical general-purpose timing signal. The ϕ_0 Apple clock is comparable to the ϕ_2 clock of other microprocessor systems.

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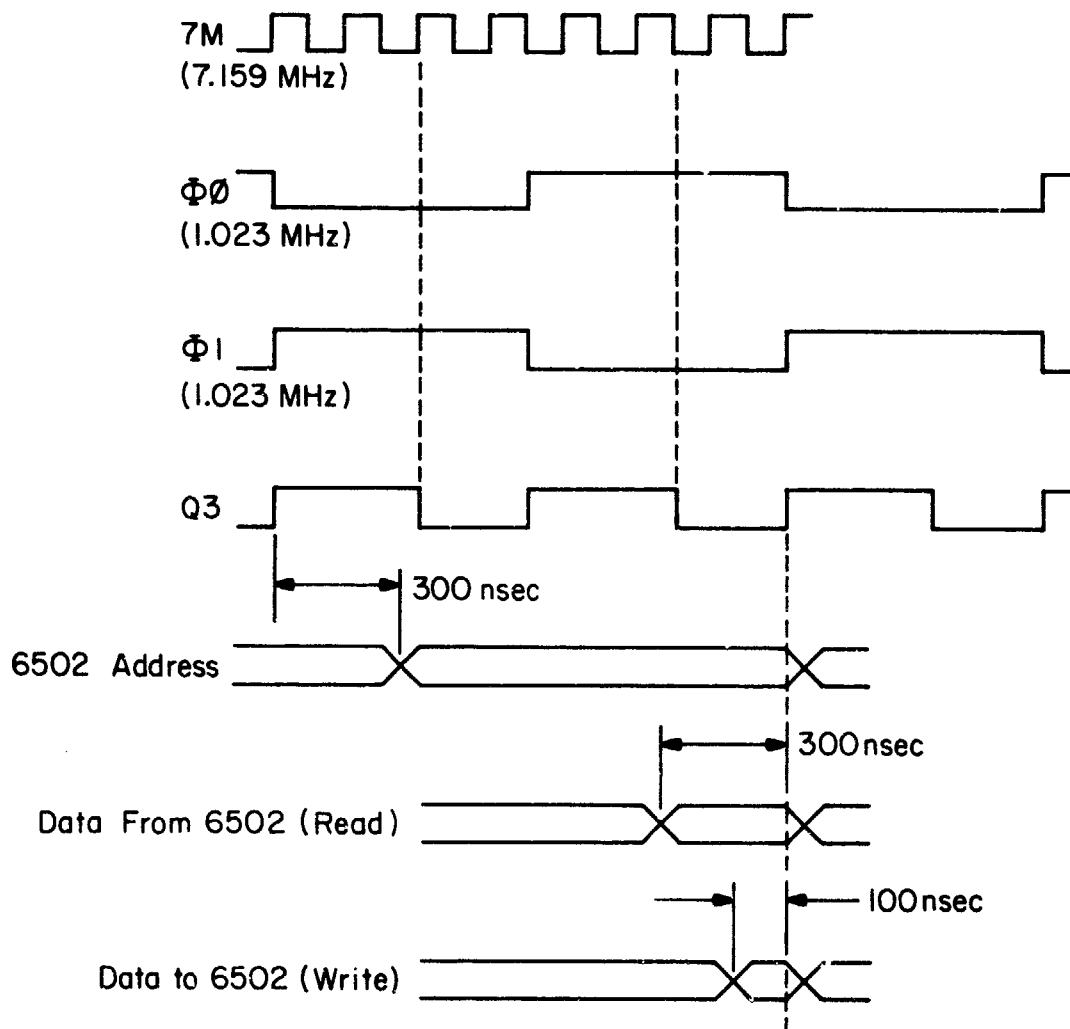


Figure 4.1 Apple timing signals.

During normal operation the Apple's RAM is used by both the 6502 and the Apple's video generating circuitry. The 6502 accesses the RAM only during the high (+5 volts) half of the $\phi 0$ clock while the video generating circuitry updates the video screen from the RAM during the low (ground) half of the $\phi 0$ clock. The action of the video circuitry also refreshes all of the Apple's RAM. Because of this feature, the easiest implementation of the DMA controller is to have it essentially replace the 6502 during DMA data transfer periods. This implementation allows the video circuitry to continue to function normally during a DMA period. Another result of this type of DMA architecture is that the data transfer rate is dictated by the microprocessor system clock rate, $\phi 0$ for the Apple, which would allow a maximum DMA transfer rate of 1.023 Mbyte/sec. The MC6844 DMAC was chosen because it is designed for the type of implementation discussed above and it is capable of operating at the Apple system clock rate.

One peculiarity of the Apple timing system is that every 65th cycle of the $\phi 0$ and $\phi 1$ clocks is lengthened by about 140 nanoseconds. This corresponds to a frequency of 0.895 MHz for the long cycle. The lengthening is an artifact of the logic used to obtain the clock signals from the 14.318 MHz oscillator. Because of this anomaly, the SLIPP interface unit was designed with its own oscillator and clock logic rather than using the Apple's. In order to place photon pulse counts in correct range bins the SLIPP unit must be able to determine accurately the time elapsed since the laser firing. This would not be possible with the Apple's inconsistent clock. This design results in the Apple and the SLIPP unit operating asynchronously. To account for the timing differences, an asynchronous First-In/First-Out buffer (FIFO) is used to interface the SLIPP unit and the Apple DMA circuit. For more details on the interfacing see Section 4.2.4.

4.1.3 Apple peripheral input/output. Along the rear edge of the Apple's main board are eight peripheral connectors. The connectors or "slots" are labeled 0 through 7 beginning from the left-hand side of the board. Slots 1 through 7 are used for most peripheral applications while slot 0 was designed specifically for memory or interface expansion. The pinout for the slots is shown in Appendix I. The preprocessor DMA card was designed to be used in any of the slots 1 through 7.

Each slot has specific memory locations assigned to it. This memory-mapped structure allows the user (or user's program) to access cards in any of the slots. Each slot is given 16 locations for general input and output purposes. The locations for the particular slots are listed in Table 4.1. Whenever the MPU calls an address within the 16-byte allocation of a particular slot, the Device Select line (pin 41) on that peripheral connector will become active (drop to ground). By listening to the Device Select line, a peripheral card can determine when a byte in the general I/O space reserved for it is being addressed.

In addition to the 16 general I/O locations, each slot is assigned 256 locations (one page) of Read Only Memory (ROM) or Programmable ROM (PROM) space. These locations are listed in Table 4.2. Although allocated as peripheral card program space, these locations function in a similar manner as the general I/O locations. Whenever an address within the one page allocation of a particular slot is called, the I/O Select line (pin 1) on that peripheral connector will become active (drop to ground). A peripheral card can determine when its program space is being addressed by listening to the I/O Select line. The Apple accesses the preprocessor DMA card through both the general I/O and the program locations. The general I/O addresses are decoded on the DMA card to provide control signals for

TABLE 4.1 APPLE PERIPHERAL CARD GENERAL PURPOSE I/O LOCATIONS.

SLOT	LOCATIONS
0	\$C080-\$C08F
1	\$C090-\$C09F
2	\$C0A0-\$C0AF
3	\$C0B0-\$C0BF
4	\$C0C0-\$C0CF
5	\$C0D0-\$C0DF
6	\$C0E0-\$C0EF
7	\$C0F0-\$C0FF

TABLE 4.2 APPLE PERIPHERAL CARD PROM LOCATIONS.

SLOT	LOCATIONS
1	\$C100-\$C1FF
2	\$C200-\$C2FF
3	\$C300-\$C3FF
4	\$C400-\$C4FF
5	\$C500-\$C5FF
6	\$C600-\$C6FF
7	\$C700-\$C7FF

firing the laser, resetting the SLIPP unit, etc. The program locations are used to access the MC6844 DMAC programmable Control Registers.

A DMA transfer with the Apple is accomplished by pulling the $\overline{\text{DMA}}$ line (pin 22) on the connector LOW. This disables the 6502's address bus and interrupts the clock to the 6502, effectively halting the microprocessor. A peripheral controller, such as the MC6844 DMAC, is able to supply the Apple RAM addresses while the $\overline{\text{DMA}}$ pin is held LOW.

Other lines present on the peripheral connector that are used by the DMA card include the clock signals $\phi 1$ and Q3 (pins 38 and 37), the Read/Write line $\overline{\text{R/W}}$ (pin 18), and the Reset line $\overline{\text{RES}}$ (pin 31).

The Apple peripheral connectors also provide pins to construct a daisy chain priority system for cards that issue interrupt or DMA requests. These pins are labeled INT IN, INT OPUT, DMA IN, and DMA OUT (pins 28, 23, 27 and 24, respectively). The system was designed for the highest priority device to be installed in the left most slot of the Apple slots 1 through 7. It was apparent that in the preprocessing system the DMA card would not have any conflicts with other devices issuing DMA requests. Therefore, rather than constructing some arbitration logic testing for DMA request conflicts, the DMA IN and DMA OUT pins on the card were simply connected together to preserve the DMA daisy chain. To preserve the interrupt daisy chain, the INT IN and INT OUT pins on the card were connected together.

4.1.4 The MC6844 DMAC. The MC6844 Direct Memory Access Controller is a TTL compatible chip that directs the DMA data transfer from the SLIPP unit to the Apple. It controls the address bus and the Read/Write line in the Apple in place of the 6502 during a DMA transfer.

The MC6844 has three modes of operation and four DMA channels. The operation modes are as follows: 1) Three State Control (TSC) Steal - in

this mode the MPU 2 clock is stretched while one byte of data is transferred; 2) Halt Steal - the MPU is halted while one byte of data is transferred; 3) Halt Burst - the MPU is halted while an entire block of data is transferred. The mode of operation selected depends on the transfer rate required with the Halt Burst mode giving the highest rate. The preprocessor DMA card was designed to use one channel of the MC6844 in the Halt Burst mode.

The MC6844 pinout is shown in Figure 4.2. Before a DMA transfer begins, the DMAC must be programmed with the data transfer location and length, transfer mode, priority of servicing, data chaining, and interrupt control. The programming is accomplished through the first five address lines (A0-A5), the data bus, and the chip select pin ($\overline{\text{CS}}$) on the DMAC. Tables 4.3 and 4.4 show the programmable registers of the MC6844. These tables are provided as a quick programming reference. More DMAC programming details are provided in the Motorola specification sheets on the MC6844.

TxRQ0 through TxRQ3 (pins 29-31) are the transfer request lines. There is one request line for each of the four channels. A peripheral device requests a DMA transfer by driving the transfer request line on a particular channel HIGH. The preprocessor DMA card uses only channel #1 of the DMAC.

Transfer acknowledge outputs notify the device requesting a transfer that the request has been received by the MC6844. The transfer acknowledge signals are TxAKA and TxAKB. The Transfer Strobe line ($\overline{\text{TxSTB}}$) is a general acknowledge line which is also intended for use as the system Valid Memory Address (VMA) signal.

After a transfer request has been received by the DMAC, the DMAC must issue a request to the system's MPU. This is done with either of the two

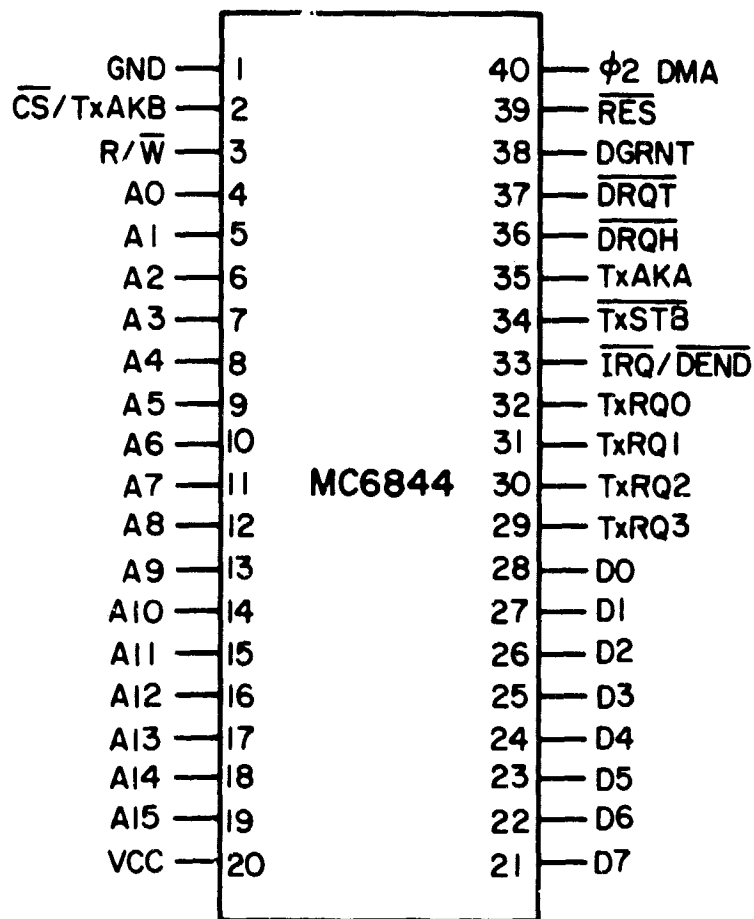


Figure 4.2 MC6844 DMAC pinout.

TABLE 4.3 MC6844 ADDRESS AND BYTE COUNT REGISTERS.

REGISTER	CHANNEL	ADDRESS (HEX)
ADDRESS HIGH	0	0
ADDRESS LOW	0	1
BYTE COUNT HIGH	0	2
BYTE COUNT LOW	0	3
ADDRESS HIGH	1	4
ADDRESS LOW	1	5
BYTE COUNT HIGH	1	6
BYTE COUNT LOW	1	7
ADDRESS HIGH	2	8
ADDRESS LOW	2	9
BYTE COUNT HIGH	2	A
BYTE COUNT LOW	2	B
ADDRESS HIGH	3	C
ADDRESS LOW	3	D
BYTE COUNT HIGH	3	E
BYTE COUNT LOW	3	F

TABLE 4.4 MC6844 CONTROL REGISTERS.

REGISTER	ADDRESS (HEX)	REGISTER CONTENTS							
		BIT 7	BIT 6	BIT 5	BIT 4	BIT 3	BIT 2	BIT 1	BIT 0
CHANNEL CONTROL	1x*	DMA FND	BUSY/READY	-	-	UP/DOWN	TSC/HALT	BURST/STEAL	READ/WRITE
PRIORITY CONTROL	14	ROTATE C'NTRL	-	-	-	R'QST ENB 3	R'QST ENB 2	R'QST ENB 1	R'QST ENB 0
INTERRUPT CONTROL	15	DEND IRQ FLAG	-	-	-	DEND IRQ ENB 3	DEND IRQ ENB 2	DEND IRQ ENB 1	DEND IRQ ENB 0
DATA CHAIN	16	-	-	-	-	2/4 CH'NL SELECT	DATA CHAIN SEL B	DATA CHAIN SEL A	DATA CHAIN ENB

*The x represents the binary equivalent of the channel desired.

outputs DMA Request TSC-Steal ($\overline{\text{DRQT}}$) or DMA Request Halt-Steal ($\overline{\text{DRQH}}$). The $\overline{\text{DRQT}}$ line is normally connected to the system clock driver and used to request a MPU clock stretch for the TSC-Steal transfer mode. The $\overline{\text{DRQH}}$ line is connected to the MPU Halt pin and requests a transfer in the halt steal or halt burst mode.

After issuing a request to the MPU, the DMAC waits for a bus available signal. This signal is generally output from the MPU or the MPU clock circuitry and is presented to the DMA Grant pin (DGRNT). The DMA transfer begins once this signal is received.

The Interrupt Request output and the DMA End signal are provided on the dual purpose line $\overline{\text{IRQ/DEND}}$. The $\overline{\text{IRQ}}$ output is used to interrupt the MPU and signal the peripheral device that a DMA transfer has ended. If the Interrupt has been enabled, the $\overline{\text{IRQ/DEND}}$ line will go LOW after the last byte of a transfer. The $\overline{\text{IRQ/DEND}}$ line also goes LOW during the last byte of a transfer to signal the DMA End. This occurs whether the Interrupt is enabled or not.

Other pins on the MC6844 include Read/Write (R/W), the clock input ($\phi 2$ DMA), and Reset ($\overline{\text{RES}}$).

One option supported by the MC6844 and used by the preprocessing system is data chaining. Data chaining allows the repetitive reading or writing of a block of data without reloading the DMAC Address and Byte Count registers for each transfer. The chaining is performed by transferring the contents of the Address and Byte Count Registers in channel #3 to the channel selected by the programming of the Data Chain Control Register. The transfer automatically occurs after the Byte Count Register of the selected channel has decremented to zero.

It should be noted that during a DMA transfer the DMAC is only supplying addresses for the system's memory at the MPU clock rate. The peripheral device requesting the transfer must write (or read) the data on the data bus at the MPU clock rate.

4.1.5 DMA circuit description. The Apple DMA circuit for the preprocessing system was designed to transfer a block of data to (or from) the Apple RAM at a rate of 1.023 Mbytes/sec. The circuit was constructed on a 2-3/4" x 7" Apple II Peripheral Board and consists of the MC6844 DMAC chip supported by ten low-power Schottky (LS) TTL chips. Connecting the Apple and the DMA card to the peripheral device requesting a DMA transfer is a 34-pin shielded ribbon cable. A connector for the cable is mounted on the DMA board. The card was designed to operate in any of the Apple peripheral slots 1 through 7 on the back of the main Apple board (see Section 4.1.3). The Apple slot pinout and the ribbon cable pinout are listed in Appendix I. The locations of the components on the DMA card are noted in Appendix II. Figure 4.3 is the wiring schematic for the DMA card. The timing for a typical DMA transfer is shown in Figure 4.4.

Both the Apple ROM I/O locations and general I/O locations are used to communicate with the DMA card (see Section 4.1.3). The ROM I/O locations access the DMAC Control Registers while the general I/O locations are decoded and used as "Control Signals." Table 4.5 lists the DMA card I/O locations. The DMAC Control Registers are programmed through the first five address lines (A0-A4), the data bus, and the chip select pin (CS) on the DMAC (see Section 4.1.4). The CS pin must be pulled LOW while programming the DMAC registers. This is accomplished by the decoding of the Apple I/O Select line and the address lines A5 through A7 with a 74LS260 5-input NOR (chip U6 in Figure 4.3). The decoding allows 32 addresses to activate the

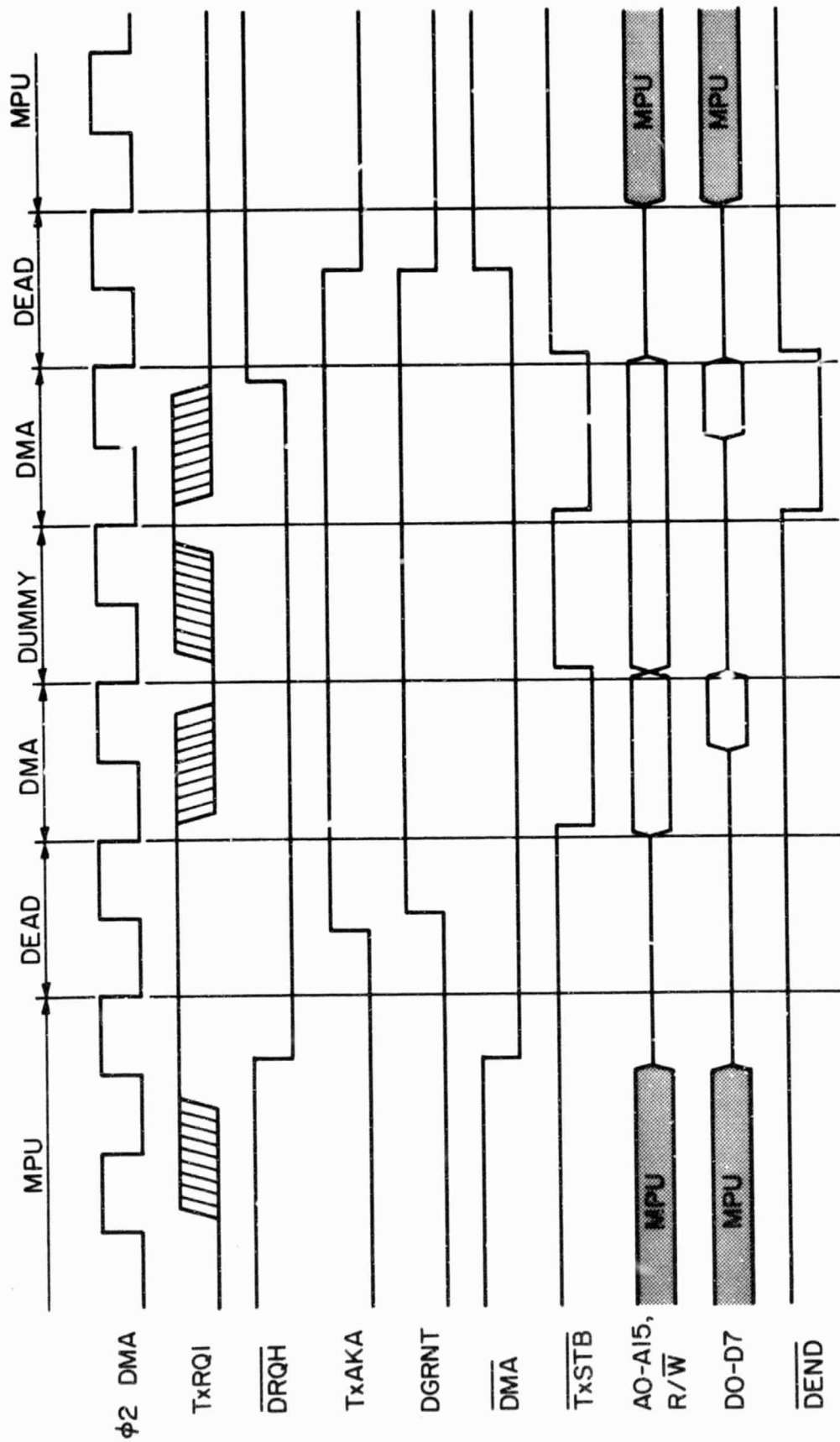


Figure 4.4 Apple DMA card transfer timing.

TABLE 4.5 APPLE DMA CARD I/O LOCATIONS.

LOCATION TITLE	ADDRESS ¹	DESCRIPTION ²
DMAC CONTROL REGISTERS ($\overline{I/O}$ \overline{SELECT})	$\$Cn00 - \$Cn0F$ ³	ADDRESS AND BYTE COUNT REGISTERS
	$\$Cn10 - \$Cn13$ ³	CHANNEL CONTROL REGISTERS
	$\$Cn14$	PRIORITY CONTROL REGISTER
	$\$Cn15$	INTERRUPT CONTROL REGISTER
	$\$Cn16$	DATA CHAIN REGISTER
CONTROL LINES (\overline{DEVICE} \overline{SELECT})	$\$C0x0$	$\overline{Y0}$ - APPLE DMA TxRQ
	$\$C0x1$	$\overline{Y1}$ - (LASER TRIGGER)
	$\$C0x2$	$\overline{Y2}$ - (AUX OUTPUT)
	$\$C0x3$	$\overline{Y3}$
	$\$C0x4$	$\overline{Y4}$ - (SLIPP UNIT RESET)

¹All hexadecimal addresses. n = Apple slot#; x = n + 8.

²The items in parentheses are the functions performed by the Control Signals in the preprocessing system.

³See Tables 4.3 and 4.4 for addresses of particular registers for each channel.

$\overline{\text{CS}}$ line. Because the DMA card only uses channel #1 of the DMAC for transfers and channel #3 for data chaining (see Section 4.1.4), only the programming of the Control Registers of those channels is pertinent. The Control Signals are generated by decoding address lines A0 through A2 with a 74LS138 3-to-8 line decoder (U7). The decoder is enabled by the address line A3 and the $\overline{\text{Device Select}}$ line from the Apple. To ensure that no spurious addresses are decoded during a DMA transfer, the 74LS138 is disabled by the DGRNT signal.

Once the Control Registers are correctly loaded, a transfer request issued to the DMAC will initiate a DMA transfer. The DMA card allows requests from peripheral devices or the Apple itself. Generally, the request is issued by a peripheral device needing attention. This is done by pulling pin 15 on the ribbon cable LOW. This causes the TxRQ1 pin on the DMAC to go HIGH which constitutes a transfer request. The Apple issues a request through the Control Signal decoding logic (see Table 4.5). Reading or writing to the transfer request address sets the output of a 74LS74 flip-flop (U2a) HIGH. This also causes the TxRQ1 pin on the DMAC to go HIGH. The flip-flop is needed to hold the transfer request HIGH throughout the DMA transfer.

The DMA card was designed to use the MC6844 in the Halt Burst mode which means an entire block of data is transferred sequentially. However, the transfer may be suspended by withdrawing the transfer request on the TxRQ1 pin of the DMAC. The timing diagram of Figure 4.4 shows this situation. For the first byte of the Halt Burst mode the DMAC tests the TxRQ1 signal on the rising edge of the $\phi 2$ DMA clock. In succeeding bytes the TxRQ1 signal is tested on the falling edge of $\phi 2$ DMA, and data are transferred during the next $\phi 2$ cycle if TxRQ1 is HIGH. After a peripheral device

issues the transfer request (ribbon cable pin 15, LOW), simply withdrawing the request will suspend the transfer. A peripheral device can also suspend the transfer when the Apple has issued the transfer request. This is also done with pin 15 on the ribbon cable. However, in this case, pulling pin 15 LOW suspends the transfer. This is a result of the exclusive-OR gate (U9) used to combine the Apple and the peripheral request lines.

After receiving a transfer request the DMAC responds with two outputs, Transfer Acknowledge A (TxAKA) and DMA Request Halt ($\overline{\text{DRQH}}$). One function of the TxAKA signal is to notify the peripheral device that a request has been received (ribbon cable pin 20). The TxAKA signal is also NOR-ed with DRQH (chips U3a, U8a and U8b) and the resulting signal is used to pull the $\overline{\text{DMA}}$ line on the Apple peripheral connector LOW, stopping the 6502 in the Apple. The TxAKA and $\overline{\text{DRQH}}$ signals are combined in order to hold the $\overline{\text{DMA}}$ line on the Apple LOW beyond the final DMA transfer cycle (see Figure 4.4).

Once the DMA halt request has been presented to the Apple, the DMAC expects a DMA Grant signal (DGRNT) to be returned. This must occur before the transfer begins. Because there is no bus available (or equivalent) connection in the Apple peripheral slot, DGRNT is synthesized from TxAKA using a 74LS74 flip-flop (U2b).

During the DMA transfer the Transfer Strobe line ($\overline{\text{TxSTB}}$, ribbon cable pin 19) acts as the Valid Memory Address (VMA) line. The completed DMA transfer is marked by the $\overline{\text{DEND}}$ signal (ribbon cable pin 18). This signal comes from the dual purpose pin $\overline{\text{IRQ/DEND}}$ on the DMAC. The $\overline{\text{IRQ/DEND}}$ and TxSTB signals are OR-ed (U3b) to produce $\overline{\text{DEND}}$. This prevents false signals arising from interrupt requests on the $\overline{\text{IRQ/DEND}}$ DMAC pin. By examining the DMA end flag, bit 7 of the Channel Control Register of channel #1 (location \$Cn11, n = Apple slot #), the Apple may determine if the block DMA transfer

has been completed. Reading of the Channel Control Register resets the DMA end bit.

Except for the data lines, all outputs to the ribbon cable are buffered through either a 74LS367 or a 74LS368 6-input buffer. Other signals not mentioned previously that are available on the ribbon cable include: the Apple clock signals $\phi 0$, $\phi 1$, and Q3, the Control Signals $\overline{Y1}$ through $\overline{Y4}$, and the Apple Reset line \overline{RES} .

As mentioned in Section 4.1.4 on the MC6844, during a DMA transfer the DMAC only supplies the Apple RAM with addresses and controls the Apple read/write line. The peripheral device sending (or receiving) the data must place the data on the data bus within the restrictions of the Apple read/write timing (see Figure 4.4).

4.2 SLIPP Interface Unit

4.2.1 Introduction. The SLIPP unit was designed to interface the Apple microcomputer to the transmitting and receiving sections of the lidar system. The unit consists of a digital circuit and its required power supplies all mounted in a 5 1/2" x 9" x 12" box. The circuit is constructed on a Vector 3682-2 6.5" long card which plugs into an edge connector inside the box. Two extra edge connectors are also available in the box. Mounted on the back panel of the box are the following connectors: 1) a 34-pin ribbon cable connector for linking the Apple DMA circuit to the SLIPP unit, 2) four isolated BNC connectors labeled LCP, NIM, TRIG and AUX OUT. LCP is the Laser Command Pulse input (+5 V pulse), NIM is the photon pulse input from the discriminator (NIM standard: - 18 mA (-1 V), 12 nsec), TRIG is the laser trigger output (+5 V, 1 μ sec pulse), and AUX OUT is an auxiliary pulse output (+5 V, 1 μ sec pulse).

Appendix I contains the pinouts for the SLIPP circuit board and the

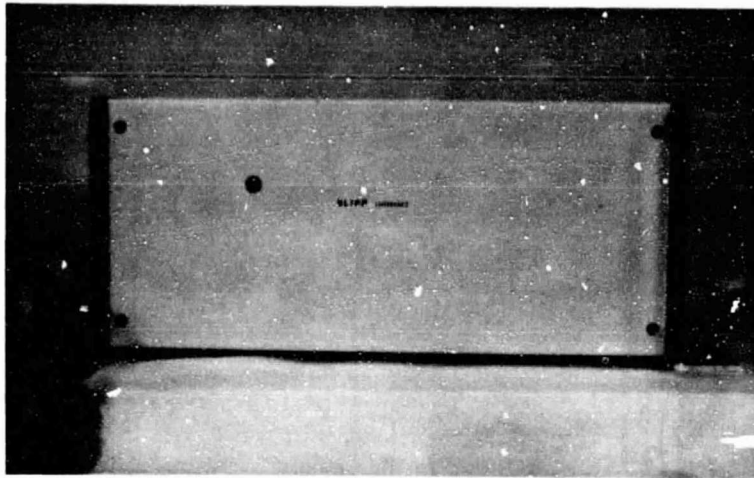
external ribbon cable. The location of the components on the circuit board is shown in Appendix II. Photographs of the SLIPP unit are shown in Figure 4.5. Figure 4.6 is the wiring schematic for the circuit.

4.2.2 Clock circuitry. The SLIPP clock circuitry is shown in the lower lefthand corner of Figure 4.6. The clock circuitry performs two functions: 1) inhibits the rest of the SLIPP photon counting circuitry until the Laser Command Pulse (LCP) is received; and 2) after receiving the LCP, provides the timing signals that drive the counting circuitry.

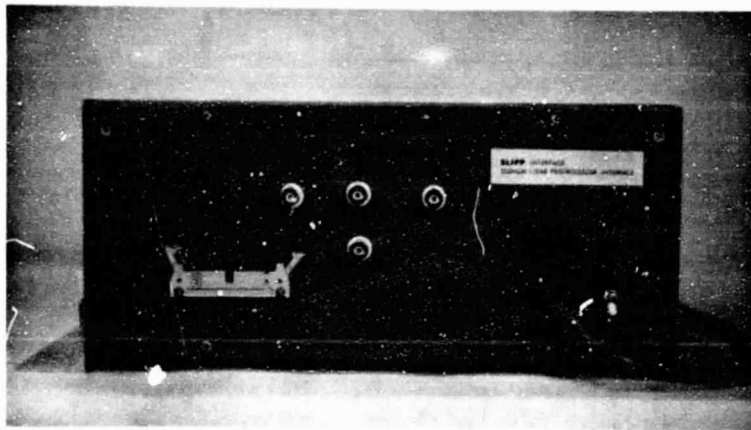
Two 74H74 positive-edge-triggered flip-flops are used to provide the enabling signals for the system. The first flip-flop (U12a) must be clocked by the user. This action enables the second flip-flop (U12b) which is then used to detect the LCP and provide the General Enable (GEN ENB) signal to the rest of the circuit. The first flip-flop is needed to ensure that the SLIPP system will not accidentally be enabled by a spurious LCP before the actual data run is to take place. Normally, the clocking of the first flip-flop is done by the pulse sent to trigger the laser (Control Signal $\overline{Y1}$ from the Apple DMA card). However, the Data Acquisition Enable Jumper, shown near the lower-center section of Figure 4.6, can be changed so that the user can clock the first flip-flop at his discretion (using Control Signal $\overline{Y3}$ from the Apple DMA card).

The master timing signal is supplied by a free-running 20 MHz oscillator. The 20 MHz signal is input into a 74162 decade counter (U23) divides the signal down to 2 MHz. However, the decade counter must be enabled by the GEN ENB signal before outputting the 2 MHz signal. In this way, no timing signals are supplied to the rest of the counting circuitry until the LCP has been received. The decade counter allows only up to 50 nsec skew time between the LCP and the beginning of the first 2 MHz clock cycle.

(a)



(b)



(c)

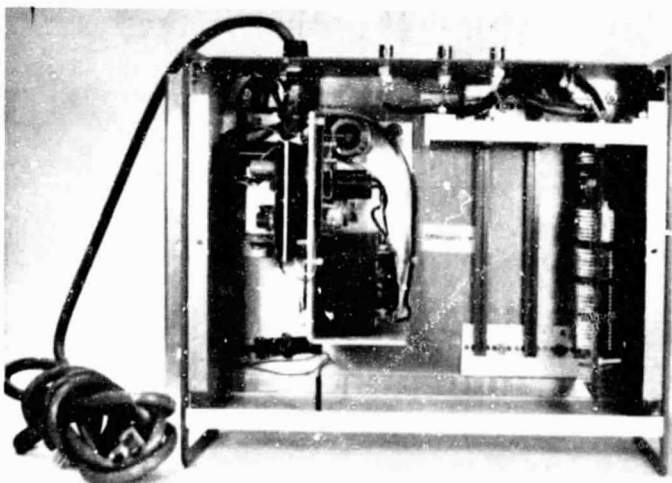


Figure 4.5 Photographs of the SLIPP unit: (a) front panel, (b) back panel, and (c) top view of the open cabinet.

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1880 CONNECTOR C2

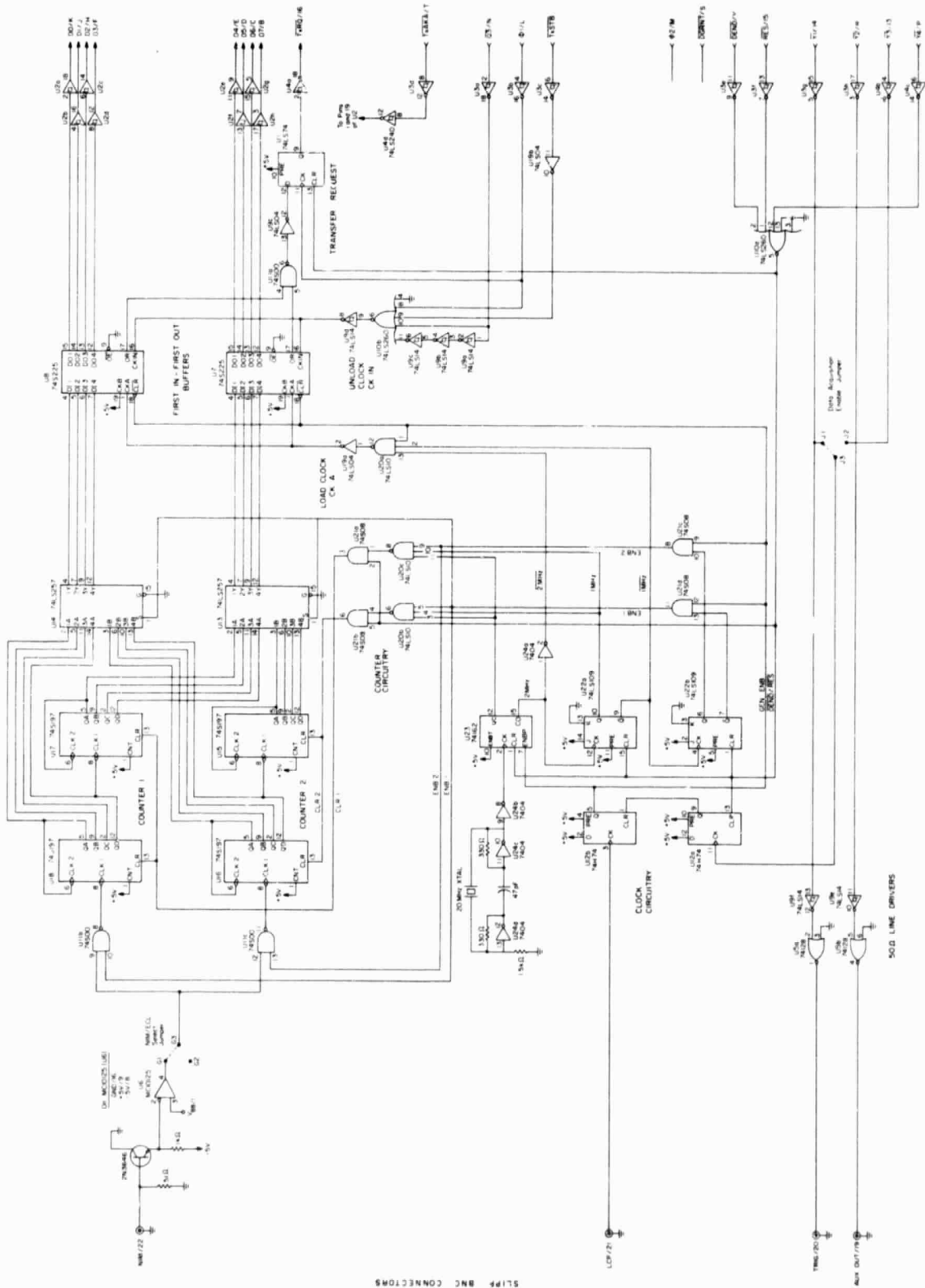


Figure 4.6 SLIPP unit circuitry.

SLIPP BNC CONNECTORS

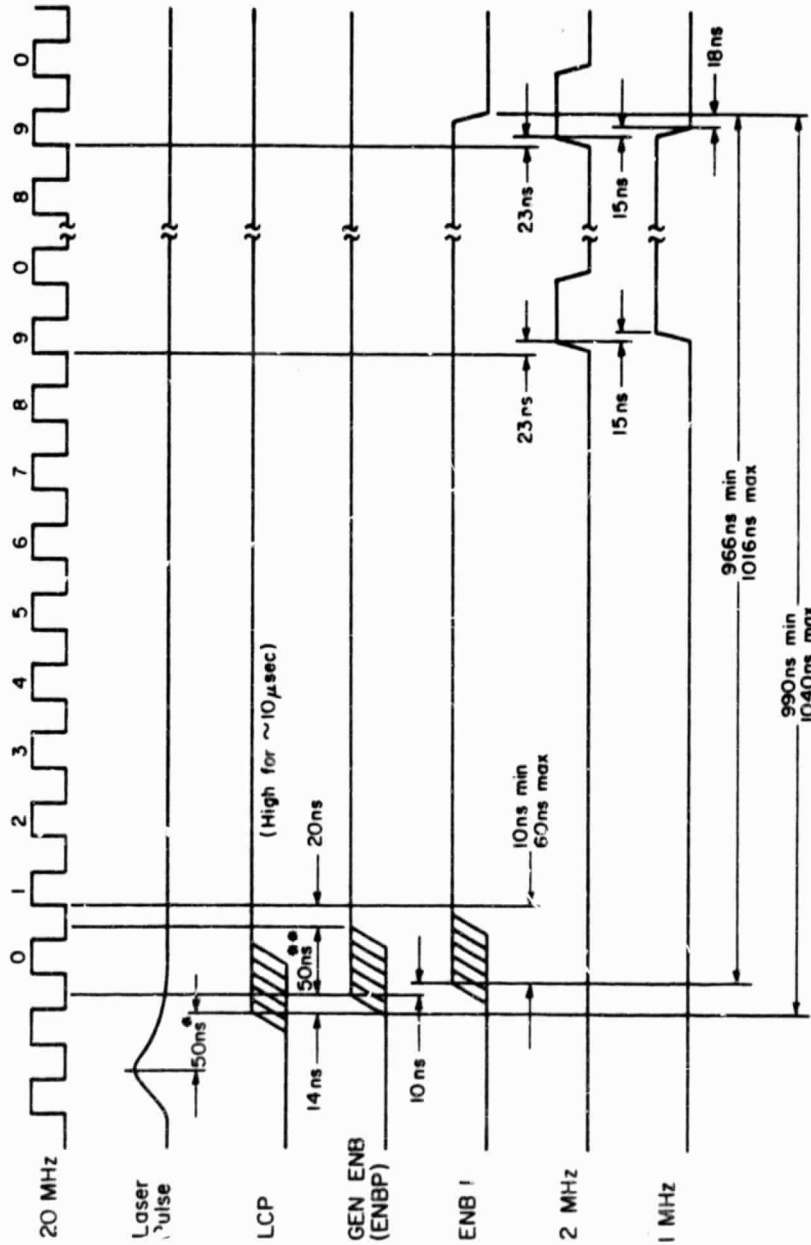
After the decade counter is enabled, two 74LS109 positive-edge-triggered flip-flops (U22a and U22b) are used to divide the 2 MHz signal down to 1 MHz and 0.5 MHz. The inverted signals $\overline{2 \text{ MHz}}$, $\overline{1 \text{ MHz}}$, and $\overline{0.5 \text{ MHz}}$ are also generated by the circuitry. The 0.5 MHz and $\overline{0.5 \text{ MHz}}$ signals are labeled ENB 1 and ENB 2, respectively. These signals are used to select the toggling photon counters discussed in Section 4.2.3. Two 74S08 NAND gates (U21c and U21d) are used to hold both ENB1 and ENB 2 LOW while the GEN ENB signal is inactive (LOW).

Figure 4.7 shows the timing relations for various clock circuitry signals immediately following a laser shot. The times noted on the diagram were calculated using typical propagation delay values for the particular chips involved.

4.2.3 Counting circuitry. The counting circuitry is shown in the upper left-hand corner of Figure 4.6. The circuitry takes the NIM standard pulses from the lidar system discriminator and counts them in consecutive 1 μsec intervals.

The counters used in the circuitry are TTL binary counters so it is necessary to shift the NIM pulses to TTL levels. This is done in two stages. First, a 2N3646 transistor configured as an emitter-follower shifts the NIM pulses to emitter-coupled logic levels (ECL: $-0.9\text{V} = "0"$, $-1.7\text{V} = "1"$). A Motorola MC10125 ECL to TTL converter chip (U6) is then used to obtain positive TTL pulses. A NIM/ECL select jumper has been provided in the circuit for possible future upgrade to ECL logic inputs.

Two 8-bit counters in a toggling configuration are used in the circuit to obtain the photon counts. At any given 1 μsec interval during a data run, one counter is counting pulses while the contents of the other counter,



*The laser pulse is actually about 2 μsec in duration. The 50 nsec time shown is an estimate of the delay in the laser pulse detector from the time the laser pulse first triggers the detector.

**50-nsec skew time.

Figure 4.7 SLIPP unit clock circuitry enable timing.

obtained during the previous interval, are being placed in Apple memory. Each counter is composed of two cascaded 74S197 4-bit binary counters (counter #1: chips U18, U17; counter #2: chips U16, U15).

The positive TTL photon pulses are input to the counters through two 74S00 NAND gates (U11b and U11c). These gates use the ENB 1 and ENB 2 signals from the clock circuitry to section the pulses into 1 μ sec intervals and select the counter to receive the pulses. The gates also invert the photon pulses for input to the 74S197 counters.

During the inactive (non-counting) cycle of a counter, two actions are performed. First, the contents of the counter are stored; and second, the counter is cleared. Two 74LS257 quad multiplexer chips (U13, U14) select the counter output to be stored. The ENB 1 signal is used to drive the select input on the chips. The multiplexers can be thought of as operating 180 degrees out of phase with the input NAND gates (U11b, U11c). The output of the multiplexers is clocked into the Apple interface circuitry described in the next section. The Qc (3rd bit) output of the decade counter in the clock circuitry (U23) is used to clear the counters. Two 3-input NAND gates (U20b, U20c) and two AND gates (U21a, U21b) determine when and which counter to clear.

The important timing signals for the counting circuitry are shown in Figure 4.8. The Data Load Clock (CK A) signal in the figure is described in the next section.

4.2.4 Apple Interfacing Logic. The logic interfacing the SLIPP unit and the Apple microcomputer allows the following functions to be performed: 1) the resetting of the SLIPP circuitry, 2) the firing of the laser and the enabling of the SLIPP counting circuitry, and 3) the DMA data transfer from the SLIPP unit to the Apple. The interfacing logic is generally shown in

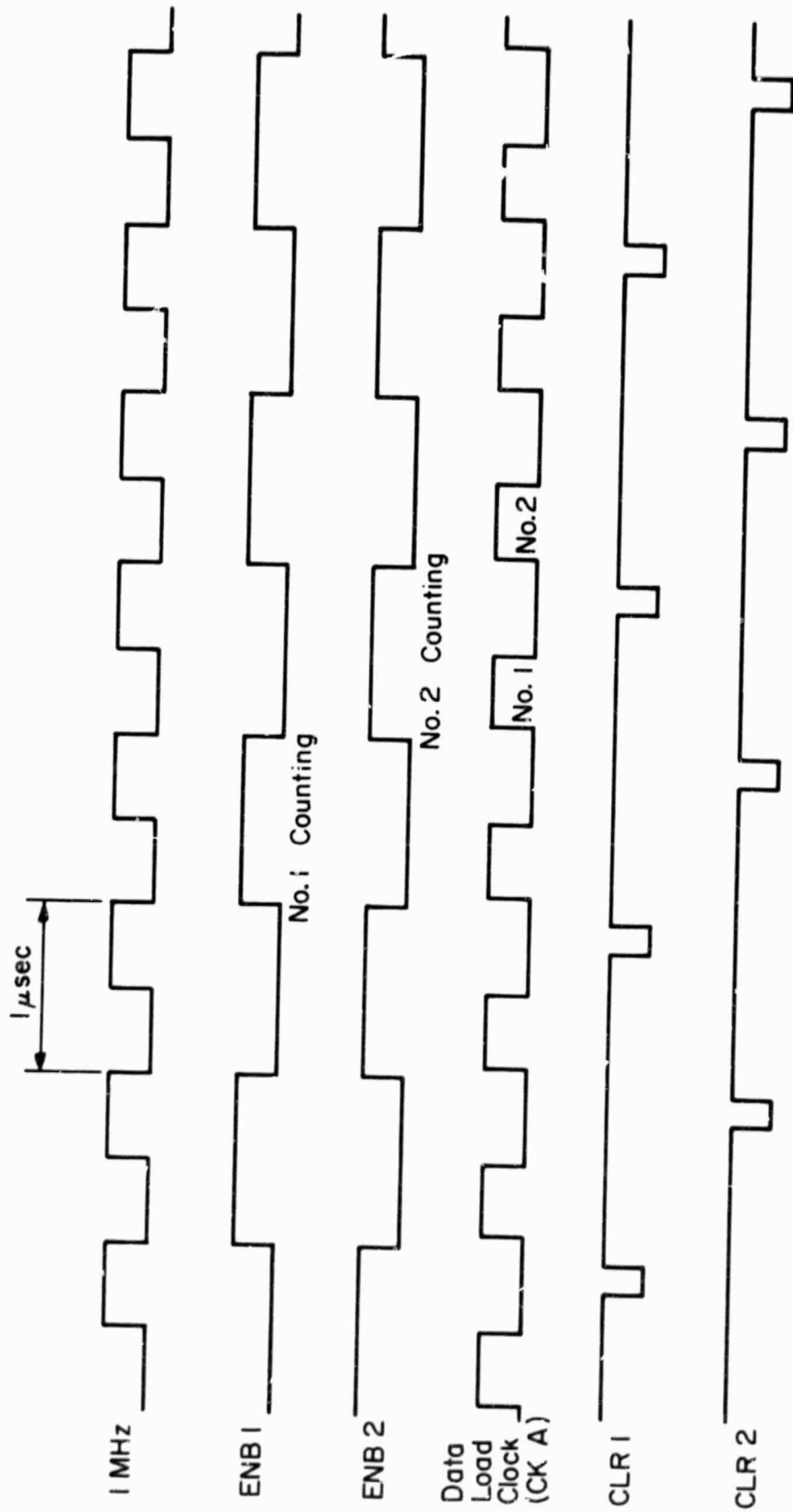


Figure 4.8 SLIPP unit counting circuitry timing.

the SLIPP unit to the Apple. The interfacing logic is generally shown in the right-hand side of Figure 4.6.

Three different signals from the Apple DMA card will reset the SLIPP circuitry. The signals are the Reset signal ($\overline{\text{RES}}$) which is connected to the Apple reset line, the $\overline{\text{Y4}}$ Control Signal, and the DMA End ($\overline{\text{DEND}}$) signal which comes at the end of a DMA transfer. The three signals are input to a 74LS260 5-input NOR gate (U10a) which is shown in the lower right-hand corner of Figure 4.6. The output of the NOR gate is used to reset the clock circuitry flip-flops discussed in Section 4.2.2, clear the counters discussed in Section 4.2.3, and reset the transfer request flip-flop which will be discussed further in this section.

The $\overline{\text{Y1}}$ Control Signal from the Apple DMA card is normally used to trigger the laser. The $\overline{\text{Y1}}$ signal on the ribbon connector (C2) is input to a 74128 50-Ohm line driver (U5a) shown in the lower left-hand corner of Figure 4.6. The line driver output is connected to the TRIG BNC connector on the back panel of the SLIPP box. Control Signal $\overline{\text{Y1}}$ is also used to enable the clock circuitry flip-flops. A second line driver (U5b) is used to drive the Auxiliary Output (AUX OUT), and Control Signal $\overline{\text{Y2}}$ is used to pulse the output. More details on the laser firing and the circuit enabling are discussed in Section 4.2.2 on the SLIPP clock circuitry.

As mentioned in Section 4.1.2 on Apple Timing, the Apple and the SLIPP unit operate asynchronously. The SLIPP unit photon counters during a data run output data at a rate of 1.0 Mbytes/sec while the Apple DMA circuitry, operating at the Apple $\Phi 0$ clock rate, accepts data at a 1.023 Mbytes/sec rate. To transfer smoothly, the data bytes from the SLIPP unit to the Apple a First-In/First-Out buffer technique was used. The buffer circuitry is shown in the upper right-hand corner of Figure 4.6 and is sectioned into the following parts: the First-In/First-Out buffers, the Load Clock (CK A), the

Unload Clock (CK IN), and the Transfer Request circuit.

Two 74S225 16 x 5 asynchronous First-In/First-Out (FIFO) buffer chips (U7 and U8) are the heart of the buffer system. Data bytes from the SLIPP unit's counting circuitry are clocked into the FIFOs with the Load Clock (CK A) circuitry. The Unload Clock (CK IN) circuitry uses the Apple Clock signals Q3 and $\phi 1$ and the Apple DMA signal $\overline{\text{TxBT}}$ to clock data out of the FIFOs to the Apple RAM.

Because the Apple DMA circuit transfers data bytes faster than the SLIPP unit can supply them, the DMA circuit must be signaled periodically to wait during a data run. This is effected through the Transfer Request circuitry. The Transfer Request circuit uses the Output Ready (OR) lines on the FIFOs. These lines are active (HIGH) whenever a valid byte is in the FIFO's output register. The OR lines from the two FIFOs are AND-ed together (U11a and U19c) and the resulting signal is input to a 74LS74 positive-edge-triggered D-type flip-flop (U1). The flip-flop essentially tests the composite OR signal on the rising edge of the Apple $\phi 0$ clock. If the OR signal is HIGH when tested, the transfer request to the Apple DMA circuit becomes (or remains) active. If the FIFOs output buffers are not ready when the OR signal is tested (OR signal LOW), the transfer request to the DMA circuit is withdrawn. This will halt the DMA process until the transfer request is restored (normally the next rising edge of $\phi 0$).

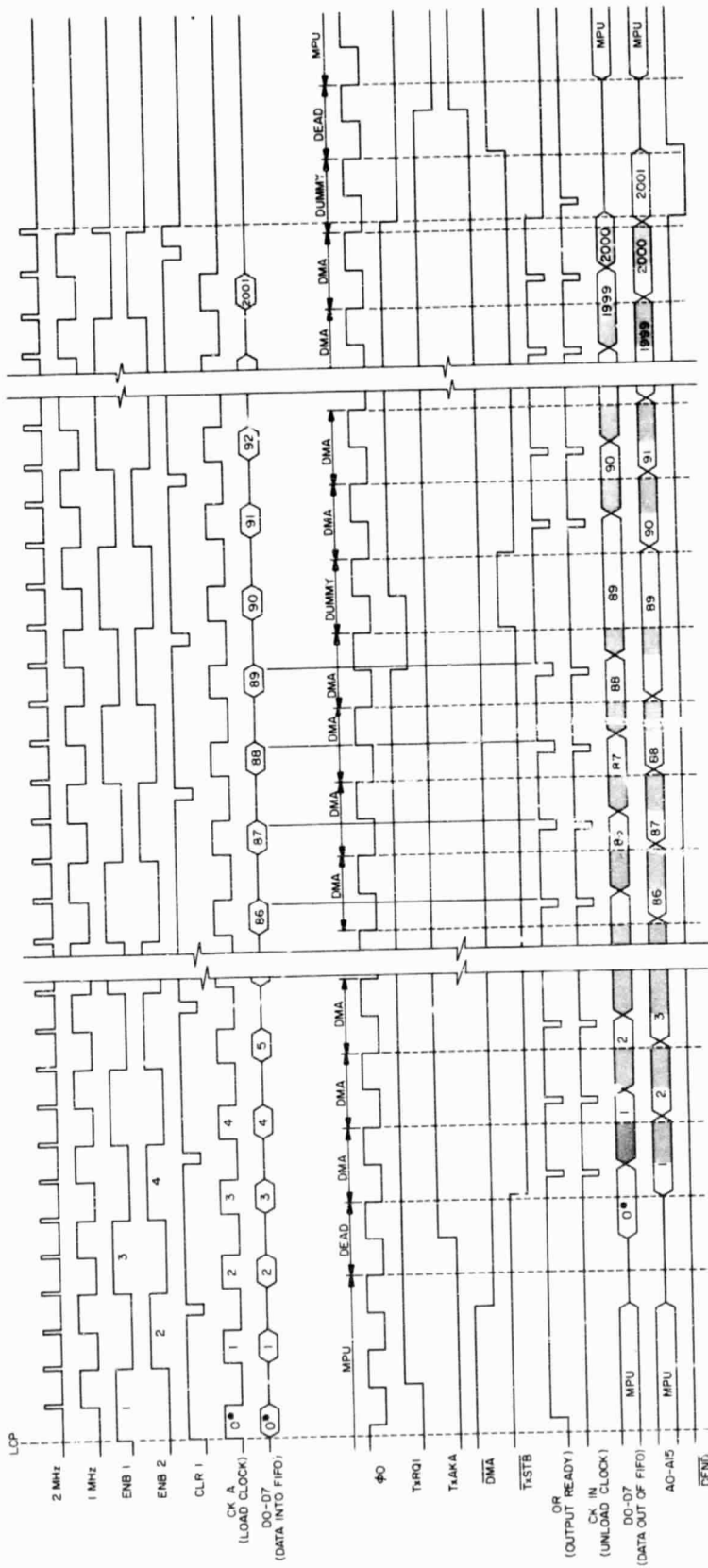
All lines connected to the 34-pin Apple-SLIPP ribbon cable are buffered with either inverting or non-inverting line drivers/receivers. The buffer chips consist of two 74LS240 octal inverting buffers (U3 and U4) and one 74LS244 octal non-inverting buffer (U2). The 74LS244 three-state buffers are used to drive the data lines D0-D7 and are activated by the DMA signal

TxAkA during a DMA transfer.

Figure 4.9 is a timing diagram for various SLIPP unit and Apple signals during the data collection for one laser shot. The signals in the upper half of the figure are SLIPP unit signals while Apple signals are shown in the lower half. The left-hand section of the diagram shows the beginning of the data collection. The middle section shows an instance where the Apple DMA transfer is suspended and the right-hand section shows the end of the data collection.

One consequence of the interface logic design described above is that the number of range bins collected by the SLIPP unit is set by the programming of the MC6844 DMAC Byte Count register on the Apple DMA card. If the Byte Count register is programmed for a transfer of N bytes, the SLIPP unit will collect N-1 range bins. The minus one arises from the fact that during the last byte of the DMA transfer the SLIPP unit FIFOs are being reset.

4.2.5 Power supplies. Two power supplies mounted in the SLIPP box supply +5 V and -5 V to the SLIPP circuits (Figure 4.10). A Power One C5 - 6 Amp supply provides +5 V and a Power One HA5 - 1.2 Amp supply is connected as a -5 V supply. The DC ground on the supplies is referenced to the Apple logic ground through the SLIPP-Apple ribbon cable. The AC input to the supplies is fused at 1.5 A and a switch located on the back panel of the SLIPP box turns on the supplies.



• First byte (0) is not valid data and it is not recorded.
 □ Times at which data and addresses are stable
 ■ for DMA byte transfer

Figure 4.9 SLIPP unit and Apple timing signals during data collection.

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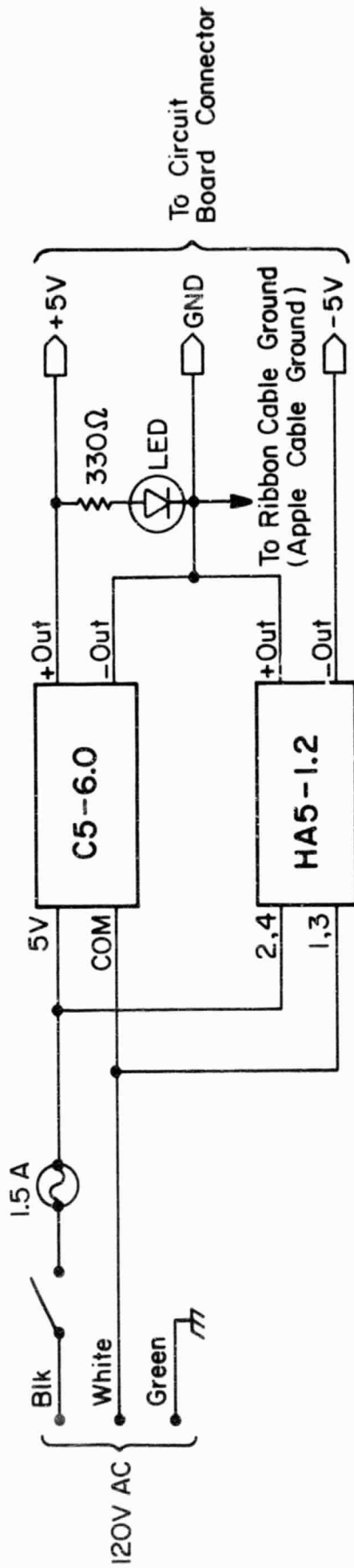


Figure 4.10 SLIPP unit power supplies.

5. SOFTWARE DESCRIPTION

5.1 Introduction

Three software routines were written for use with the preprocessing system. Two of the routines are run during data collection. They are SLPAPP.OBJ which drives the Apple in the preprocessing system and FZZ.SAV which drives the LSI-11. The third routine CONVRT.SAV is run on the LSI-11 after data collection is complete. CONVRT.SAV takes the binary data files created on a floppy disk during data collection and converts them to ASCII files. This is a necessary step before transferring the data files to the University of Illinois CYBER computer for further processing. The Apple program was written in 6502 machine language with the Apple 6502 Assembler/Editor on the Apple Tool Kit disk. The LSI-11 programs contain both Fortran and Macro-11 subroutines written under the RT-11 Version 4 operating system.

A general discussion of the data collection software is contained in Section 5.2. The routines used by the Apple and the LSI-11 for communications between each other are an integral part of the collection software. The communication routines for both computers are quite similar and are presented in Section 5.3. Section 5.4 contains notes on some of the options available in the collection software. Section 5.5 is a discussion of the data file conversion software. All the program listings are presented in Appendix III.

5.2 Data Collection Software

5.2.1 Apple routines. The file SLPAPP.OBJ, containing the Apple data collection software, is sectioned into five parts which are labeled: the Main Program Loop, the Apple Receiver, the Apple Sender, Data Run, and Printing Routines. The Apple Receiver and Sender sections handle the Apple

side of the Apple-LSI-11 communications. These routines are discussed in Section 5.3 on Apple and LSI-11 communications. The Printing Routines are a set of subroutines which display messages on the Apple monitor. Details of the Main Program Loop and the Data Run sections are discussed below.

Part (a) of Figure 5.1 shows a flowchart of the Main Program Loop section. When the file SLPAPP.OBJ is run, execution begins at this section. First, a keyboard input routine is loaded. This allows keystrokes on the keyboard to be accepted by the Apple. Next, a heading is displayed on the monitor and the program waits for a keypress before continuing. After the keypress the CCS serial card (for communication with the LSI-11) and the interrupt and byte input vectors (INTV and STATE) are initialized for use with the Apple receiving code. Finally, the interrupt disable bit is cleared, the message "IDLE" is displayed on the monitor, and the routine begins the idle wait loop. Presently, the idle loop is a simple waiting loop but in the future the loop can be replaced with a background routine such as a laser tuning algorithm.

The Data Run section of the program is actually a subroutine labeled DATRUN which is called by the Apple Receiver routine after receiving the "data run" frame. A flowchart of DATRUN is shown in part (b) of Figure 5.1. Before DATRUN is called the two variables REPNUM and MSHOTS must be loaded. REPNUM is used by DATRUN to set the laser pulse repetition rate while the desired number of laser shots per profile is contained in MSHOTS. The values to be loaded into the two variables are sent from the LSI-11 to the Apple within a "commands" communication frame.

Once called, DATRUN begins by displaying the message "TAKING DATA" on the Apple monitor. Next, the laser shot counter TSHOT is loaded with the value contained in MSHOTS and the MC6844 DMAC registers are loaded. The

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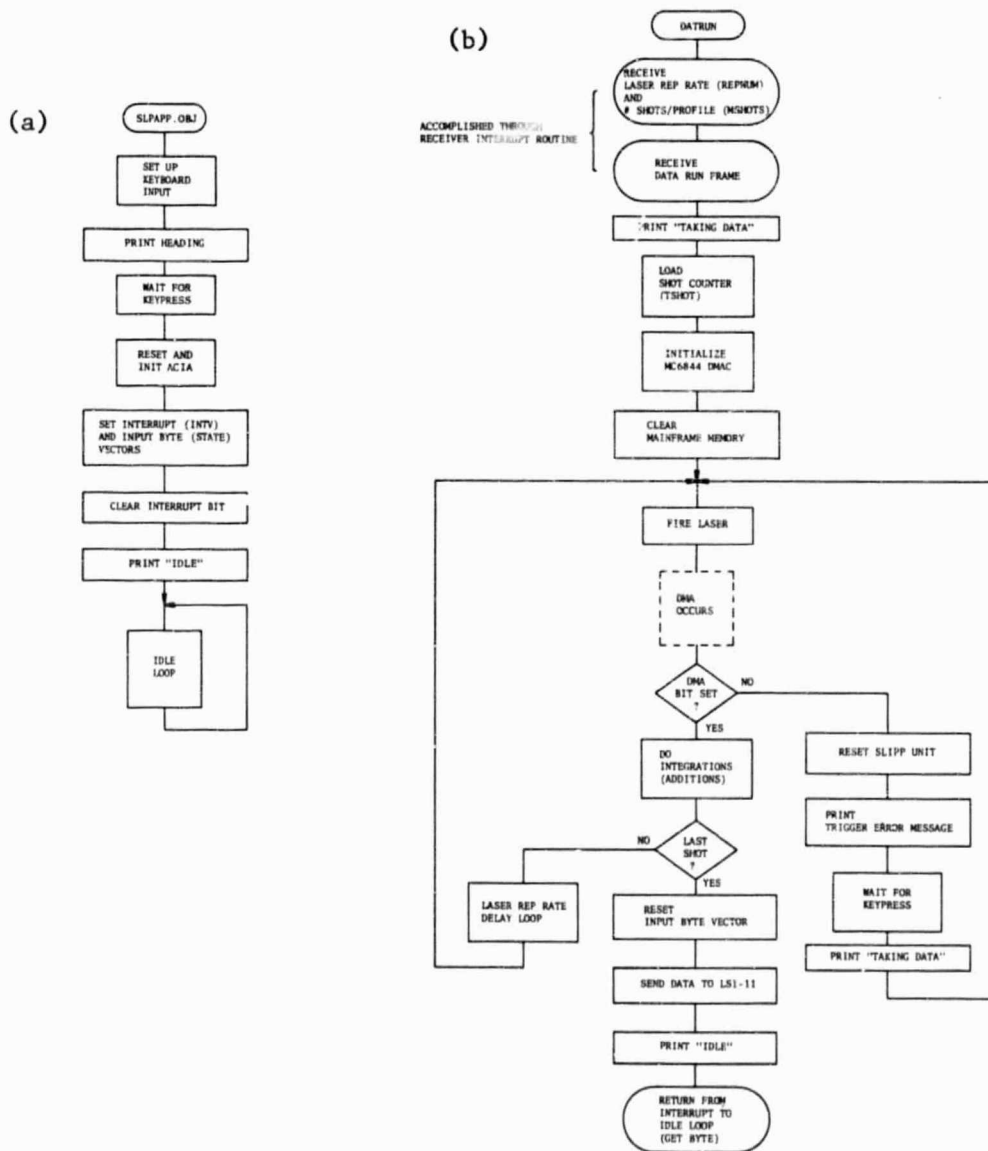


Figure 5.1 Flowchart of (a) SLPAPP Main Program Loop and (b) SLPAPP Data Run sections.

mainframe memory (the block of memory used to store the profile integration sum) is also initialized.

After the initializations the profile collection begins. The laser and the SLIPP unit are triggered by accessing the trigger address (Control Signal Y1). The routine execution is suspended during the range bin collection and DMA transfer. When the execution resumes, a status bit in the MC6844 DMAC on the Apple DMA card is tested. If the bit is not set the DMA transfer never occurred and control jumps to an error routine. With the bit set, the Apple integrates (adds) the new range bin counts into the profile integration sum in the mainframe memory. The 16-bit addition routine used causes the high order and low order bytes of the 16-bit data words to be stored in separate blocks of memory. This algorithm was selected because of its fast execution time. After the integrations, the shot counter TSHOT is decremented and tested for a zero value. If more laser shots are required for the profile, the routine executes a delay loop and then returns to fire the next laser shot.

The delay loop is required in order to regulate the laser pulse repetition rate. The value stored in the variable REPNUM is used to set the length of the delay. An equation taking into account the number of Apple machine language instructions between successive laser shots, the desired pulse repetition rate, and the structure of the delay loop code is used by the LSI-11 to solve for the value to be stored in REPNUM. REPNUM is a one-byte location so values ranging from 0 to 255 can be assigned to it. As mentioned previously, the REPNUM value is sent from the LSI-11 to the Apple within a "commands" frame.

After the data collection and integration are completed for the last laser shot of a profile, the data are sent to the LSI-11 computer within a

"data" communication frame. (Before sending the "data" frame, the input byte vector STATE must be reset to point to the beginning of the receiving code. This allows the "acknowledge" communication frame sent by the LSI-11, verifying the successful receipt of the data, to be properly interpreted.) Finally, the "IDLE" message is displayed and a return from interrupt is executed to reenter the idle wait loop in the Main Program Loop.

5.2.2 LSI-11 routines. The LSI-11 data collection software is comprised of twelve Fortran and Macro-11 files which are compiled and linked into one executable file labeled FZZ.SAV. The twelve files are: FZZ.FOR, EXPPAR.FOR, CSTTUS.FOR, LAALN.FOR, ALNRTN.FOR, DATRUN.FOR, EXMPRF.FOR, DISCAL.FOR, RCVER.MAC, SENDER.MAC, DISPLY.MAC, and HDUMP.MAC. In order to decrease file manipulation problems, all the compiled versions of the files (except for FZZ.OBJ) were placed in the library file SLPLIB.OBJ. Figure 5.2 shows a general flowchart for the collection program FZZ.SAV. Descriptions of each of the twelve files in the collection program are presented below.

FZZ is the main program file. All variables and constants for the collection software are initialized by this file. FZZ also initializes the serial port for Apple-LSI-11 communications by calling the subroutine INITR (INITR is contained in the file RCVER). The LSI-11 Job Status Word is set for "no terminal wait state." This allows the use of the Fortran input function ITTMR in the following manner: A character is transferred from the console terminal to the user's program if a character is present; but program execution continues whether a character is present or not (see Section 5.4 for the use of this option). After the initializations, FZZ displays the main collection software menu. Selection of one of the seven available options in the menu results in a call to a particular subroutine. The first six options (1-6) call the subroutines EXPPAR, CSTTUS, LAALN,

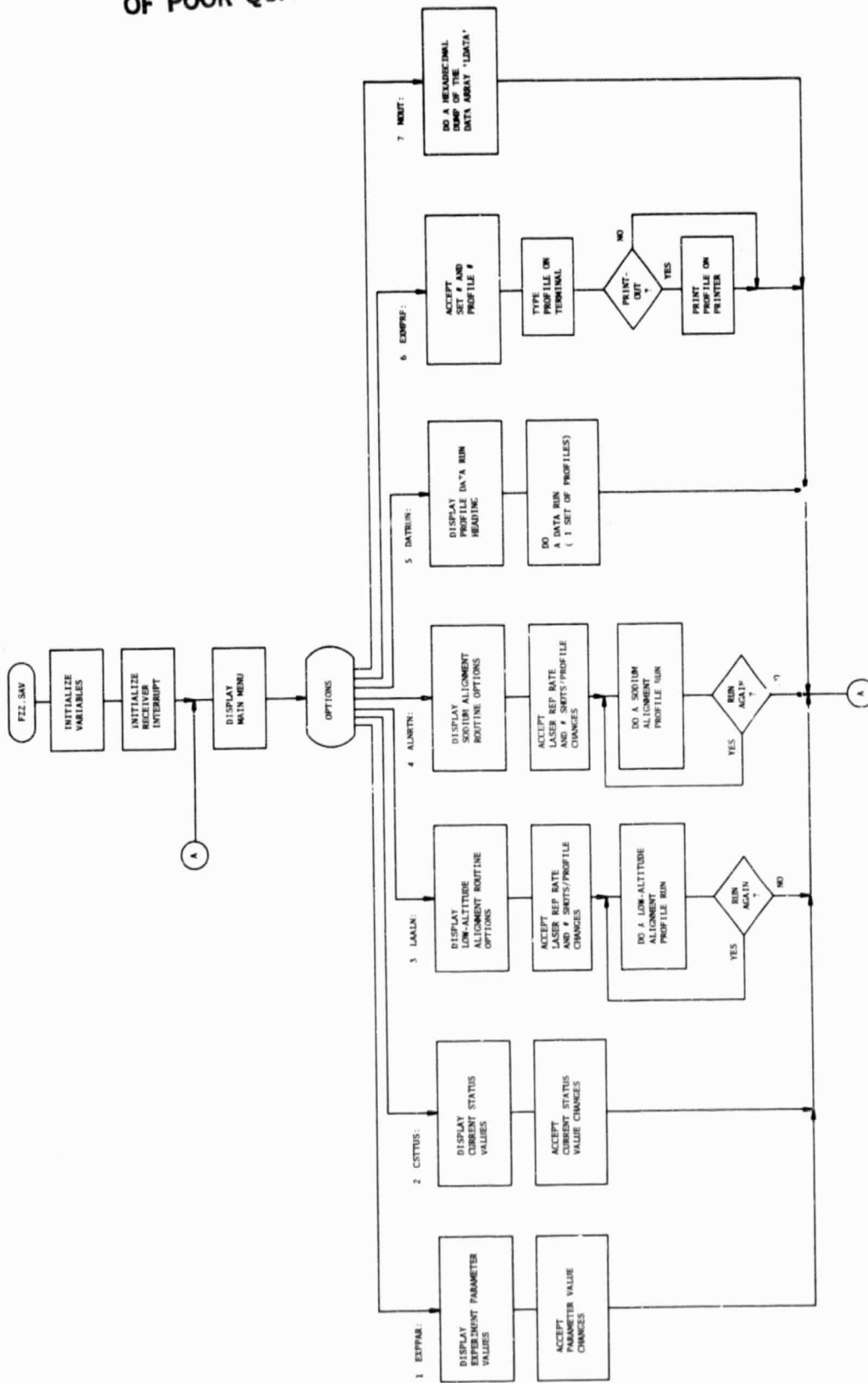


Figure 5.2 Flowchart of LSI-11 main collection program FZZ.

ALNRTN, DATRUN, and EXMPRF, respectively. Option 7 is not actually displayed in the menu but it is a viable option. Selecting option 7 results in a call to the subroutine MOUT which is contained in the file RCVER.

EXPPAR displays the experiment parameters and allows them to be changed by the operator. The parameters are used by the two routines which obtain sodium data: ALNRTN and DATRUN. A brief description of each of the parameters follows:

#Sets - number of data sets of profiles to be collected before returning to the main menu. (Presently, this is a dummy variable and is not utilized by the software.)

#Profiles Per Set - number of profiles to be placed in a data set.

#Laser Shots Per Profile - number of laser shots per profile.

Inter-Profile Delay - extra delay time desired between the collection of successive profiles (seconds).

Elevation Angle - angle between horizontal and receiving telescope line-of-sight (degrees).

Base Altitude - altitude of the lidar system in reference to the earth's surface (feet and kilometers).

Altitude Range of Data - altitude range of sodium data to be stored on a floppy disk (kilometers).

Range Bins - the set of range bins to be stored on a floppy disk.

The Elevation Angle, Base Altitude, Altitude Range of Data, and Range Bins parameters are all related through a set of range equations, and changing one of the parameters results in a recalculation of the others (see the EXPPAR listing in Appendix III.3 for details).

CSTUS displays a table of values that reflect the current status of the experiment. Included in the table are: the current profile and set

numbers (the numbers by which the next profile collected will be identified), the desired number of laser shots per profile, and the sodium values as calculated by the subroutine DISCAL for the last recorded profile. CSTTUS also allows the operator to change the current profile and set numbers.

LAALN directs a low-altitude data collection run for lidar system alignment purposes. After being called, the first action of LAALN is to allow the operator to select the laser repetition rate and the number of laser shots needed for each low-altitude profile. Next, the subroutine requests the collection of one profile and then displays the completed profile range bin counts for bins 1 through 600 (corresponding to a range of 0 to 90 km).

The steps followed by LAALN to obtain the profile are similar to those described in the paragraph on DATRUN, except it is important to note that the profile is not permanently saved on a floppy disk. After the counts are displayed the operator is prompted for a decision on whether to run the routine again or to return to the main menu. The low-altitude counts observed with the help of this routine are in general due to Rayleigh scattering. By using the routine in an iterative fashion the critical alignment of the laser beam and the receiving telescope field-of-view can be accomplished.

ALNRTN directs a sodium data collection run for lidar system alignment purposes. ALNRTN has exactly the same format as LAALN, the low-altitude alignment routine, except that each profile collected is examined for sodium returns. ALNRTN calls the subroutine DISCAL to provide a summary of the sodium counts. Also, ALNRTN uses the two experiment parameters Base Altitude and Elevation Angle as set in the subroutine EXPPAR. The two parameters are necessary for the selection of the range bins that should

contain sodium counts (see the paragraph on DISCAL). ALNRTN is helpful when making final laser tuning and laser-telescope alignment adjustments.

DATRUN directs the collection of a set of profiles with the details of the collection process set by the experiment parameters of the subroutine EXPPAR. Initially, DATRUN displays the storage space (blocks) needed on the floppy disk to save the forthcoming set of profiles. Also displayed is the record length (double words) of each profile in the set. These values are provided to help keep track of the space remaining on the data floppy disk. Along with the block length and record size values, the operator is prompted to start the data run. Once the run begins, DATRUN updates the file name to be used on the data floppy disk for identifying the forthcoming set of profiles. Also, the range parameters required by DISCAL for the sodium count summary are calculated. Values for the two variables REPNUM and MSHOTS are also determined. These variables are required by the Apple data collection software and are sent from the LSI-11 to the Apple within a "commands" communication frame. A "data run" frame sent from the LSI-11 to the Apple requests the collection of a profile. The setting of the flag DFLAG alerts the routine that the profile data has been collected and received successfully by the LSI-11. An error in the transmission of the profile data from the Apple to the LSI-11 results in the setting of the flag ERRFLG, and program control is returned to the main software collection menu. DATRUN calls the subroutine DISCAL to provide a summary of the sodium counts and the profile is saved on the data floppy disk. If more profiles are required to complete a set, the profile number is updated and collection begins again. A few details of the subroutine DATRUN are also discussed in Section 5.4 on Software Collection Options.

EXMPRF allows the operator to examine the range bin counts of profiles

that have previously been collected and stored on a floppy disk. EXMPRF prompts the operator to enter the set and profile numbers of the profile to be examined. The subroutine expects the requested data to be on a floppy disk in the disk drive designated as the data storage drive (see Section 5.4). The range bin counts are displayed on the console terminal and a printout of the counts can be obtained by responding to the prompt at the end of the terminal display.

DISCAL is called by the routines ALNRTN and DATRUN to provide the operator with a summary on the console terminal of the sodium counts in a profile. DISCAL also provides a printout of the sodium count summary for the routine DATRUN. The flag RUNFLG is used by DISCAL to determine whether ALNRTN or DATRUN is requesting its services. DISCAL expects the profile data to be recorded in the array LDATA and values for the following range parameters must be determined (by the calling routine) as they are necessary for the sodium count calculations:

B30 - 30-km bin pointer. (The number of the range bin that corresponds to an altitude of 30 km.)

B60 - 60-km bin pointer.

S20 - the number of range bins required for a collection range of 20 km.

DISCAL also uses the experiment parameters accessed through the subroutine EXPPAR. Below are descriptions of the quantities of the sodium counts displayed by DISCAL:

Detected Photons - the sum of the counts in the bins for the designated ranges (at 30 km, 60-80 km, 80-100 km, and 100-120 km).

Total Signal Photons - the detected counts in the 80-100 range minus the counts in the 60-80 km range.

Signal Photons Per Shot - the Total Signal Photons divided by the laser shots per profile.

Column Abundance Ratio - the Total Signal Photons divided by the difference of the counts in the 30-km bin and the average counts in a bin in the 60-80 km range.

RCVER and SENDER handle the LSI-11 side of the Apple-LSI-11 serial communications and are discussed in detail in Section 5.3. The RCVER file also contains the subroutines INITR and MOUT. When called, INITR initializes the program counter and status word vectors for the serial port used for the Apple-LSI-11 communications. Also initialized is the input byte vector STATE (see Section 5.3.5). The subroutine MOUT, with the use of the file HDUMP, displays on the terminal in hexadecimal form the contents of the data array LDATA.

The DISPLY file contains a set of subroutines which are called in order to enable display options available on the console terminal. The subroutines include: CLRSCN - clear screen, FORSCN - inverse or "highlighted" video, BAKSCN - normal video, and BELSCN - ring the bell. The DISPLY file listing presented in Appendix III.12 shows display subroutines designed for use with the DEC VT100 family of terminals. However, the display subroutines can be used with other types of terminals (for example, the Hazeltine 1500) by changing the terminal command codes transmitted by the subroutines to those command codes recognized by the particular terminal.

HDUMP displays a section of memory on the console terminal in hexadecimal form. HDUMP must be given the starting memory address and the byte count of the section to be dumped.

5.3 Data Collection Communication Routines

5.3.1 Introduction. During a data collection run the Apple and the

LSI-11 communicate with each other over an RS-232 standard asynchronous serial link at 9600 baud. Sequential streams of bytes, often referred to as "frames" or "packets," are used to encode the commands or data that are sent between computers. The particular Apple and LSI-11 frames are discussed in Section 5.3.3 on Protocol and Sections 5.3.4 and 5.3.5 on the sending and receiving program structures.

The frame sending sections of the Apple and LSI-11 data collection programs are essentially a set of subroutines which send the desired messages. The receiving sections of the collection programs are interrupt routines which receive and interpret the frames. Each byte received causes an interrupt which gives program control to the receiving section of code and the incoming byte is checked if it is a marker or saved if it is data. Once a complete frame is received, the receiving section of code must interpret the frame and carry out the appropriate action. This interrupt structure was developed so the computers could run background programs during "free" periods of time in the collection process. An example of a background program might be a laser tuning algorithm on the Apple which runs while the LSI-11 is busy storing and doing a printout on the current data profile.

The serial communications link was selected over other types of links (for example, a parallel link) because it was realized that during experiments the Apple and the LSI-11 might be separated by a substantial distance (20-30 feet) and it was felt that the serial link would be less susceptible to noise problems. Many of the ideas used in the design of the communications software are presented in the article "Build an Intercomputer Data Link," by Wingfield (Byte, April 1981).

5.3.2 Serial peripheral cards. Two interface cards are used for the serial communications. A California Computer Systems (CCS) model 7710A asynchronous serial interface card is used in the Apple and a DEC DLV11-J four port asynchronous interface is used in the LSI-11.

The CCS card is designed to be used in any of the Apple peripheral slots 1 through 7. The card has one channel and uses the Apple I/O addresses as shown in Table 5.1. A DB 25-pin female connector is provided on the card for serial input and output. Details on the use of the card are available in the CCS Model 7710A Owner's Manual. The preprocessing software presented in this report was written for the CCS card operating in Apple slot 2.

The DEC DLV11-J interface card mounts into the LSI-11 computer back-plane. The DLV11-J has four channels with the register and vector addresses shown in Table 5.2. Each channel has a 10(2x5) pin connector for serial I/O purposes. The DLV11-J is described in detail in the DEC Microcomputer Interfaces Handbook [1980]. In the lidar system the DLV11-J is not only used for the Apple-LSI-11 communications but also for the console terminal and the line printer input and output. The channel assignments for the lidar system are:

Channel 0 = Apple-LSI-11 communications

Channel 1 = open

Channel 2 = line printer

Channel 3 = console terminal

Figure 5.3 shows the connections for the cable between the Apple CCS card and the LSI-11 DLV11-J.

5.3.3 Communication protocol. Computer protocols are the forms that are established as appropriate and acceptable in communication between

TABLE 5.1 APPLE CCS SERIAL CARD I/O LOCATIONS

<u>ADDRESS (HEX)</u>	<u>REGISTER</u>
C0x0 (Write)	COMMAND
C0x0 (Read)	STATUS
C0x1 (Write)	TRANSMIT DATA
C0x1 (Read)	RECEIVE DATA

TABLE 5.2 LSI-11 DLV11-J SERIAL INTERFACE I/O LOCATIONS

<u>ADDRESS (OCTAL)</u>	<u>REGISTER</u>	<u>VECTOR ADDRESS</u>	<u>CHANNEL</u>
176500	RCSR		0
176502	RBUF	300	
176504	XCSR		
176506	XBUF	304	
176510	RCSR		1
176512	RBUF	310	
176514	XCSR		
176516	XBUF	314	
176520	RCSR		2
176522	RBUF	320	
176524	XCSR		
176526	XBUF	324	
177560	RCSR		3
177562	RBUF	60	(Console Device)
177564	XCSR		
177566	XBUF	64	

Apple CCS Card
(RS-232 Convention)

LSI-11 DLV11-J

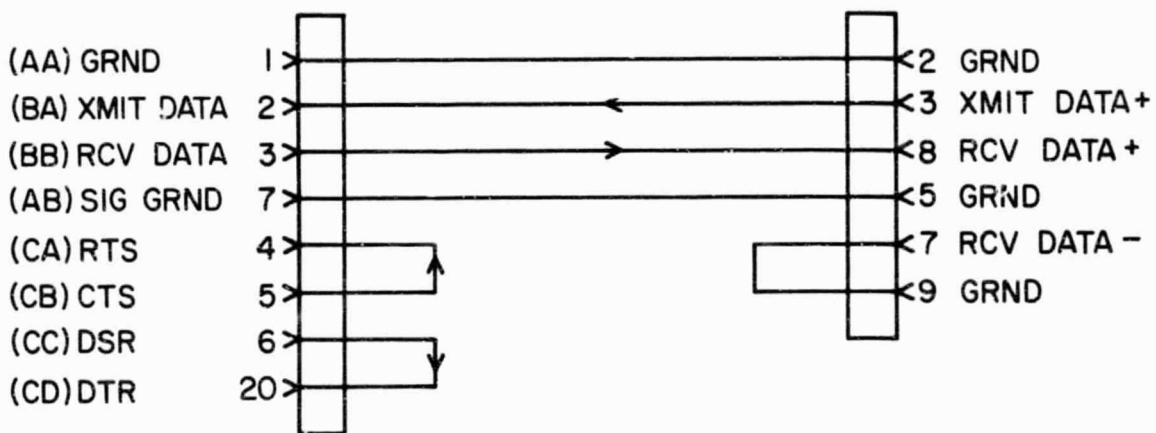


Figure 5.3 Apple CCS card and LSI-11 DLV11-J cable connections.

computers. This section describes the protocol developed for the Apple-LSI-11 serial communication link.

The commands or data sent between the Apple and the LSI-11 are encoded into sequential streams of bytes called "frames" or "packets." The frame format for this application has two parts: the header and the information section. The header part has a beginning-of-frame marker, an operation code or opcode (which determines the use of the frame), an end-of-header marker, and a checksum. The information section has a beginning-of-section marker, the data, an end-of-frame marker, and a checksum. The checksums provide more reliable communications in noisy environments. Figure 5.4 shows the general frame format.

The frame markers consist of two bytes. The first byte is the data-link escape (DLE) which alerts the receiver that the next byte should denote the start of frame (STX), the end of frame (ETX), or the start-of-frame information section (CTX). The values of the marker bytes in hexadecimal are: DLE = \$90, STX = \$83, ETX = \$82, and CTX = \$81. To avoid incorrect interpretations of DLE ETX pairs that occur as data, any DLE byte in a data frame is transmitted twice. Upon seeing the DLE DLE pair in a data frame, the receiver saves one of the DLEs and discards the other.

The opcode, following the DLE STX pair in the frame header, identifies the type of frame being transmitted. Five types of frames are used between the Apple and the LSI-11: a commands frame, a data run frame, a data frame, a profile done frame, and an acknowledge frame. The commands and data run frames are only sent from the LSI-11 to the Apple. The commands frame (opcode COM = hexadecimal 32) contains information on the desired laser repetition rate and the number of shots per profile. The data run frame (DRUN = hexadecimal 31) signals the Apple to start collecting a data pro-

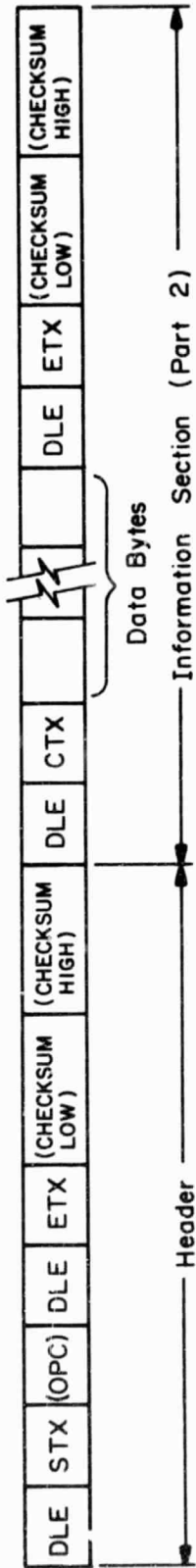


Figure 5.4 General communication frame format.

file. The data and profile done frames are sent one way from the Apple to the LSI-11. The data frames contain the profiles collected by the preprocessing system and the profile done frames (PRDONE = hexadecimal 33) signals the LSI-11 that the profile collection and transmission are completed.

The data frame is unique in that it is of variable length with its maximum length set by a constant (PAKLEN) in the Apple and LSI-11 software. The data frame opcode is also unique in that it is not a constant. This is because of the following two qualities: 1) Due to the method of storing the profile in the Apple RAM the low and high order bytes of the 16-bit profile words are sent in separate data frames; and 2) because of the long length of the high or low byte data frames (2000 bytes each), the data frame was designed to be able to transfer the data with multiple frames as opposed to one frame. The data frame encodes the two qualities given above by using the first hexadecimal digit of the opcode to differentiate the high and low byte frames and the second digit to number the frames (low byte frame = hexadecimal 50 - 5F, high byte frame = hexadecimal E0 - EF). The data frame opcode allows the LSI-11 receiving code to assemble and order the 16-bit profile words correctly upon receipt of the data frames.

After transmitting a command, data run, data, or profile done frame, the sender waits in a timeout loop for the receiver to respond with an acknowledge frame (ACK = hexadecimal 34). If an error is detected in the transmitted frame (for example, a checksum error) no acknowledge is returned, the sender timeout loop expires, and the frame is retransmitted. The sending software attempts to retransmit the frame a number of times (set by a constant, normally 2) before displaying a transmission error message on the terminal or monitor.

The five types of frames are illustrated in Figure 5.5. Only the commands frame and the data frame use the frame information section.

The checksum is the 16-bit summation of all the bytes in the frame (or frame section) except for the first DLE and the final ETX bytes. The header checksum is used to verify the frame opcode and the information checksum is used to detect transmission errors in the data. The header checksum in the commands and data frames is retained to verify that the opcode of the frame is correct before overwriting the old data values in memory with the new data values.

5.3.4 Send routine structure. The sending routines are a set of subroutines in the Apple and LSI-11 data collection software that are responsible for sending the communications frames to the receiving routine of the other computer. The Apple sending subroutines are contained in the Apple Sender program section and are labeled: SNDDAT - send data frame, SNDPRD - send profile done frame, and SNDACK - send acknowledge frame. The LSI-11 sending subroutines are contained in the Macro-11 file SENDER.MAC and are labeled: SNDCOM - send commands frame, SNDDTR - send data run frame, and SNDACK - send acknowledge frame.

Apple subroutines SNDDAT and SNDPRD along with LSI-11 subroutines SNDCOM and SNDDTR not only output the frame bytes to the communications serial port, but also wait after transmission in a timeout loop for a returning acknowledge frame. If the timeout loop is completed before the acknowledge is received, the frame is retransmitted. An error index is decremented each time a retransmission is necessary, and an error message is displayed on the sender's console after two retransmissions fail (the total number of transmission attempts is set at 3 by the constant ERRCNT, although ERRCNT can easily be changed). After a frame transmission failure

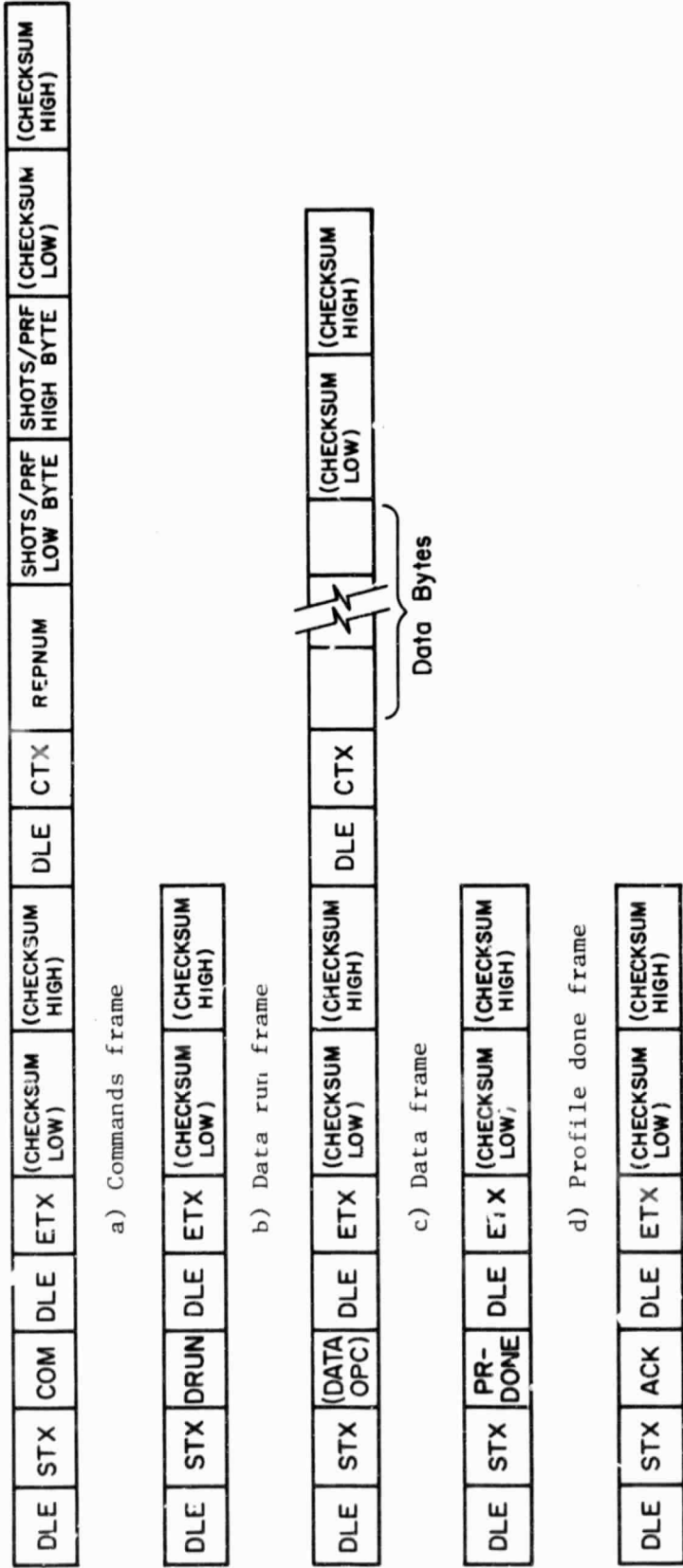


Figure 5.5 Formats for different types of communication frames.

(including the retransmission attempts), the operator has a choice of attempting the frame transmission again or exiting the sending routine. The choice is prompted by the question "Try again?" which is displayed on the sending computer console after the transmission error message.

The flowchart of the LSI-11 subroutine SNDCOM in Figure 5.6 illustrates the general structure of all the sending subroutines. First, each routine loads its respective opcode into the transmit opcode variable (OPCDE). Next, the retransmission error count (ERRORS) and the acknowledge flag (ACKFLG) are initialized. Finally, the frame bytes are sent to the communications serial port and the routine begins to execute the timeout wait loop. If an acknowledge frame is returned to the sending computer, during the wait loop, the receiving routine sets ACKFLG which drops the sending routine out of the timeout loop.

Although the general program structure of each frame sending routine is similar, there are some structure differences due to the nature of the frames. For example, the SNDACK subroutines do not incorporate the timeout loop as they have no use for it. Also, the final task of the SNDCOM subroutine is to call SNDDTR, as a commands frame will always be followed by a data run frame.

Because of the multiple low byte and high byte data frames discussed in Section 5.3.3 on Protocol, the Apple subroutine SNDDAT has some complications added to the general sending subroutine structure. A flowchart for SNDDAT is shown in Figure 5.7. SNDDAT actually uses the subroutine DATOUT to output the data frames. DATOUT is called by SNDDAT, once to send the low byte data frames and once to send the high byte data frames. Three variables must be loaded before calling DATOUT: the base data frame opcode (hexadecimal 50 or E0) is loaded into DATOPC, ADDRES holds the starting

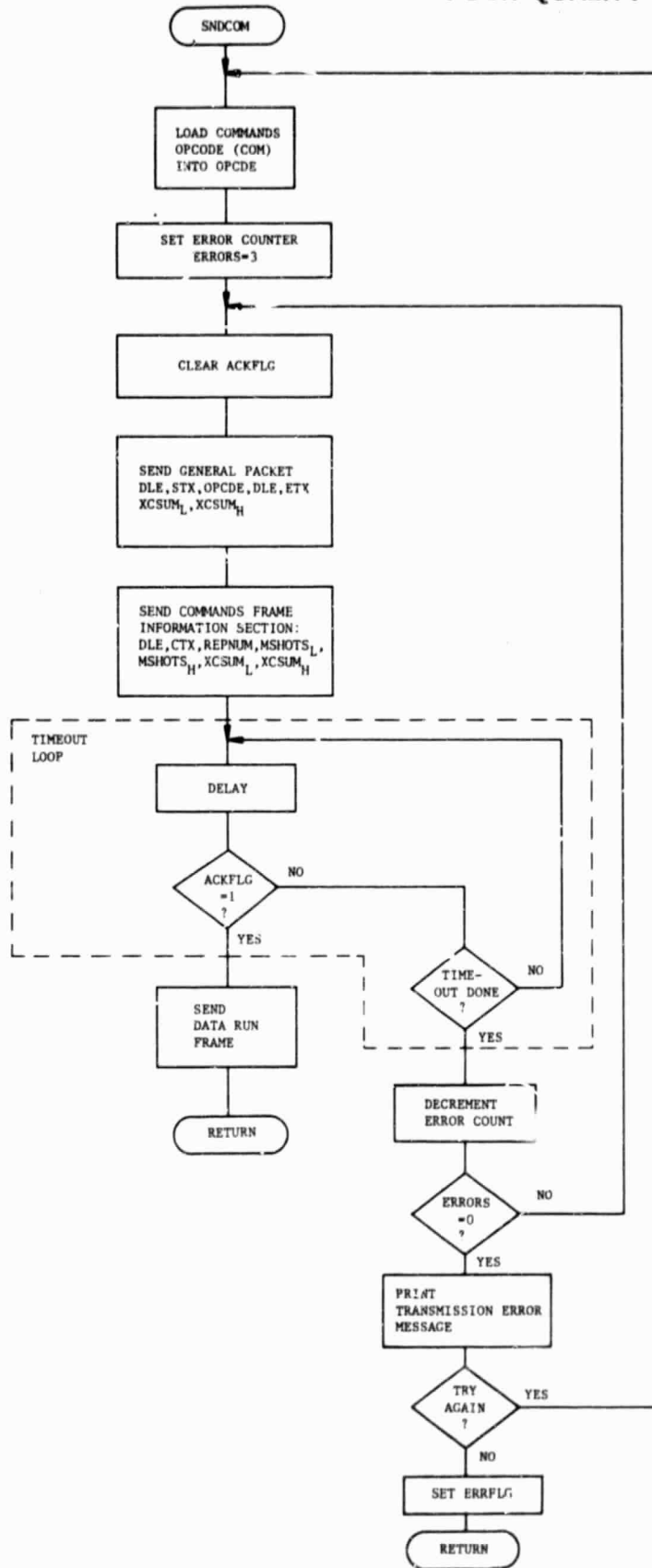


Figure 5.6 Flowchart of LSI-11 subroutine SNDCOM.

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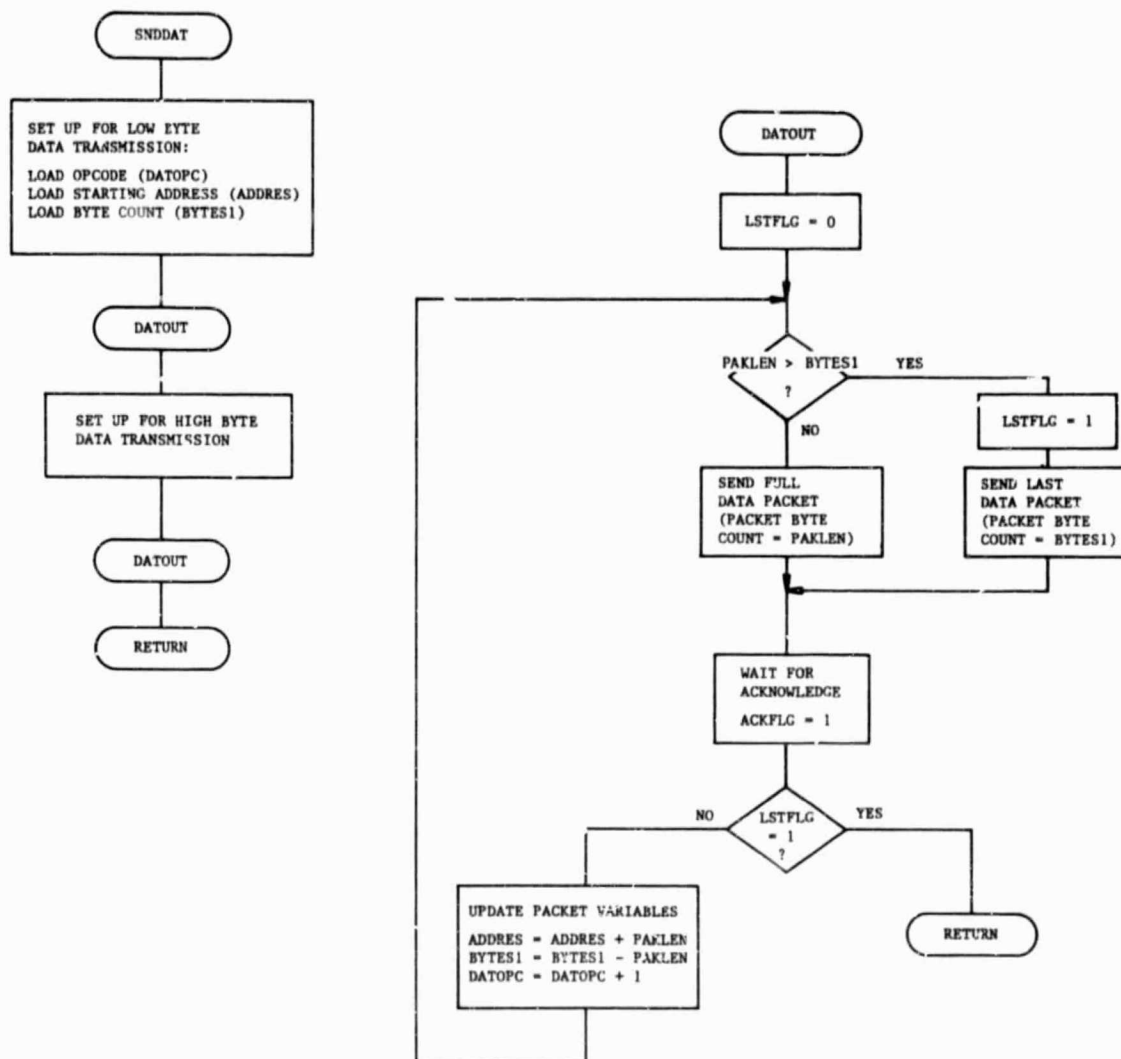


Figure 5.7 Flowchart of Apple subroutine SNDDAT.

location of the block of bytes to be transferred, and BYTES1 contains the transfer byte count. DATOUT uses the variable values to break the blocks of data into multiple data frames. The constant PAKLEN sets the maximum number of data bytes in one frame. The DATOUT routine was designed so that changing the maximum packet length is simply a matter of changing PAKLEN and recompiling the Apple program. Section 5.4 on Data Collection Software Options contains a more detailed discussion on changing the maximum data frame length.

In the data frames, data bytes that happen to have the same value as the DLE marker byte are doubled to avoid a false end-of-frame marker. Upon receipt, the LSI-11 receiving routine saves one of the DLEs as data and discards the other.

5.3.5 Receive routine structure. Figures 5.8 and 5.9 show the receiving routine flowcharts for the Apple and LSI-11, respectively. These routines receive and decode the frames sent by the sending routine of the other computer. Both Apple and LSI-11 routines are interrupt service routines with differences between the routines arising from the receiving of different types of frames. The Apple routine is contained in the Apple Receiver program section and the LSI-11 routine is contained in the Macro-11 file RCVER.MAC.

Each incoming byte on the communication serial port (of either computer) causes an interrupt which results in the program control jumping to the receiving routine. The incoming byte essentially enters the receiving routine at one of the GET BYTE blocks shown in the flowcharts. (The GET BYTE blocks actually represent the subroutine GTBYTE in the receiving code. When called, GTBYTE saves the return address in the variable STATE and executes a return from interrupt. The interrupt from the next incoming byte

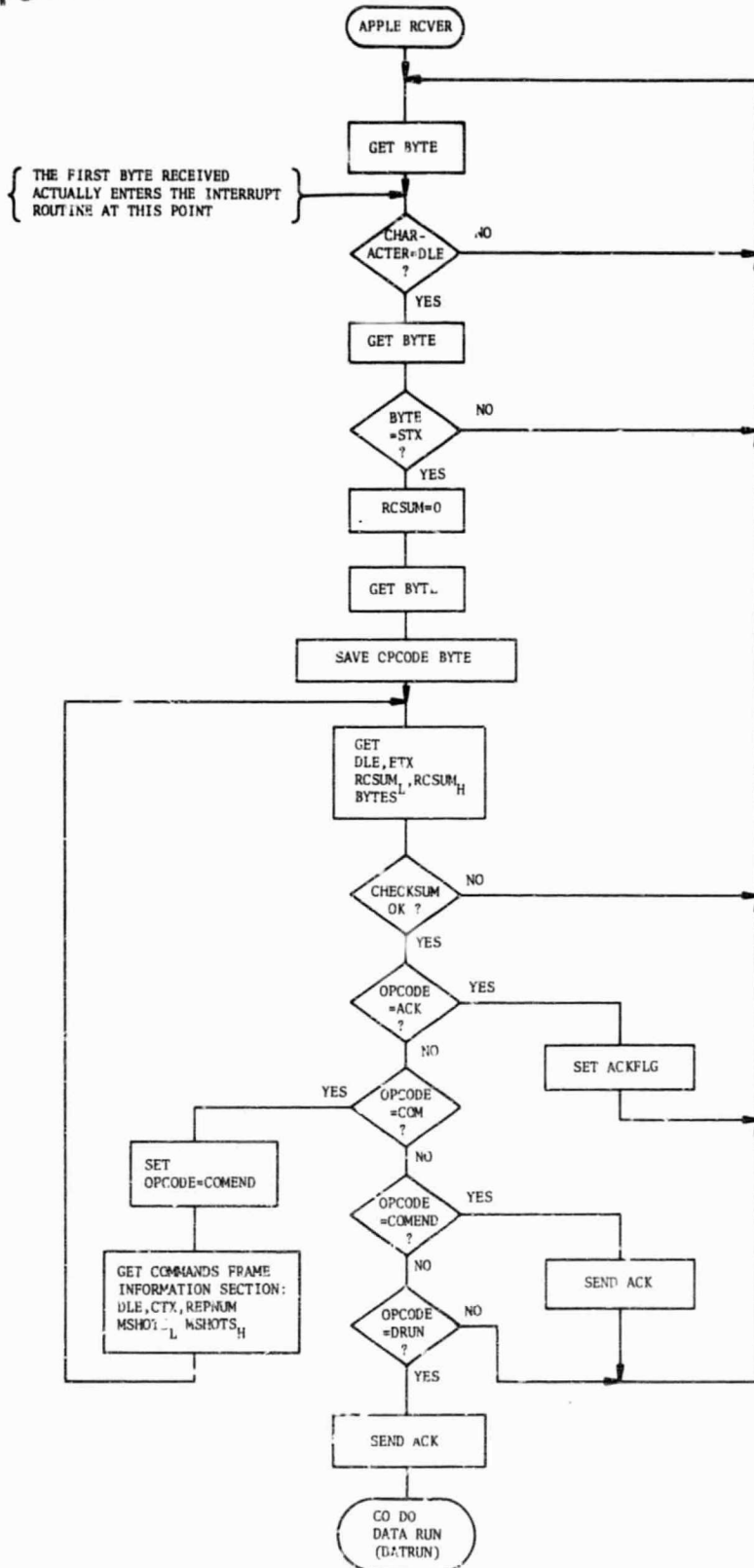


Figure 5.8 Flowchart of Apple receiving routine.

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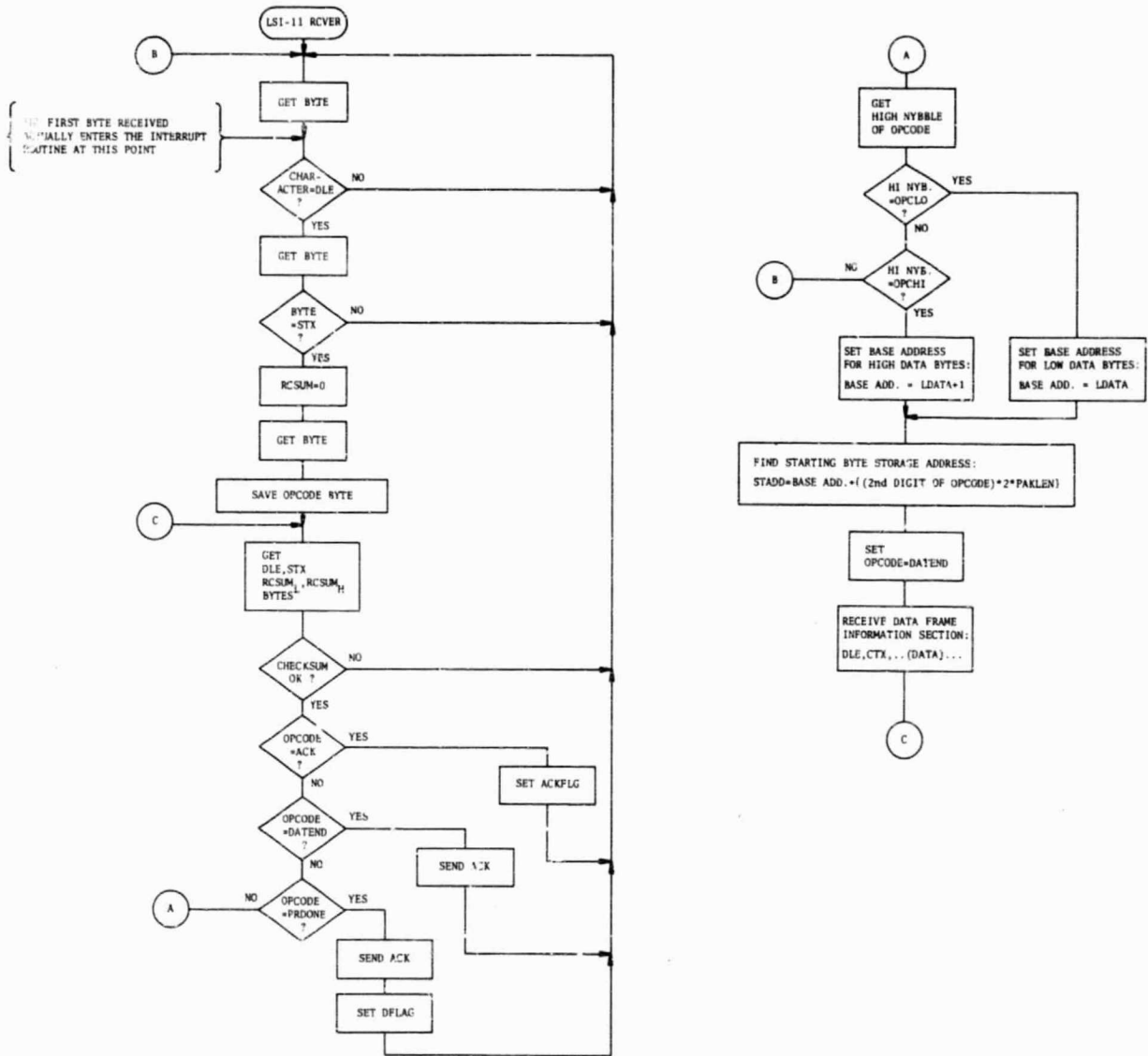


Figure 5.9 Flowchart of LSI-11 receiving routine.

results in the reentering of the receiving routine at the address stored in STATE and the incoming byte is processed by the correct portion of the receiving code. However, it is conceptually easier to think of the GET BYTE blocks as simply a wait followed by an incoming byte.)

The initial portion of the receiving code checks for the DLE STX beginning-of-frame marker. If the bytes are not DLE STX, control returns to the beginning of the receiving code.

After receiving the DLE STX pair, the next incoming byte is assumed to be the frame opcode and is saved for interpretation after the header checksum is received.

Next, the DLE ETX pair and the two bytes of the header checksum are received. If the received checksum equals the calculated checksum, the routine interprets the frame opcode. If not, control returns to the beginning of the receiving code.

In both the Apple and LSI-11 routines an ACK opcode causes the acknowledge flag (ACKFLG) to be set. In the Apple routine the COM opcode implies that the commands frame information section will be transmitted next. The DRUN opcode implies a data run is being requested.

In the LSI-11 routine the PRDONE opcode indicates a data profile has been transmitted successfully and the data flag DFLAG is set. The data frame opcode is the last to be checked for by the LSI-11 routine. The first hexadecimal digit of the data frame opcode designates the frame as high or low byte data, and the second hexadecimal digit is used to place the frame in the correct section of the array LDATA. The low order byte data are stored in the even byte address locations within LDATA and the high order byte data are stored in the odd byte address locations. This procedure results in the separately transmitted high and low bytes of the data profile

being paired as 16-bit words in the array LDATA.

The opcodes COMEND in the Apple receiving code and DATEND in the LSI-11 code are dummy opcodes which are loaded into the opcode variable while the information section of a commands frame or a data frame is being received. The dummy opcodes are essentially flags which allow the checksum testing code (before the opcode identification) to be reused for the end of the information frame section.

After a frame is successfully received and the appropriate action is taken, control returns to the beginning of the receiving code so that the next incoming frame may be interpreted correctly.

5.4 Data Collection Software Options

This section describes the real time interactive options available in the collection software that are not obvious to an inexperienced operator. Also mentioned in this section are some important program changes which allow the collection software to be adapted for use in various experiment situations.

For the most part, all of the real time interaction between the main computer/preprocessing system and the lidar operator is accomplished through the LSI-11 console terminal. Occasionally, the Apple keyboard must be accessed to allow the preprocessing system to continue after a laser triggering error. With the collection software running, the LSI-11 console terminal should initially display the main collection menu (see Section 5.2.2). Selecting one of the menu options results in a jump to a corresponding subroutine, and in general, each option subroutine halts at some point to prompt the operator for an input of some type. At this point, in menu options 1 through 5, typing a carriage return will result in a return to the main menu. Menu option 6, the profile data examine routine (EXMPRF),

initially asks for a set a. d profile number. Inputting the value zero (0) for either number will result in a return to the main menu. Menu option 7, the hexadecimal dump of the data array LDAIA, supplies no prompts and the array values are simply displayed on the terminal. After the display is completed a return to the main menu is automatically executed.

The three data collection options in the main menu (options 3, 4, and 5; routines LAALN, ALRTN, and DATRUN) all execute a waiting loop while the preprocessing system is collecting data. Normally, the loop is exited when the profile is successfully received by the LSI-11. However, the operator can force the routine to exit the waiting loop at any time by typing "s" and a carriage return. This option allows routine execution to be returned to the main collection menu when problems occur with the laser (or any other system hardware) while a data profile is being collected. This option is created through the use of the Fortran function ITTINR.

The preprocessing system requires the use of two peripheral cards in the Apple computer peripheral slots: A CCS serial communications card and the preprocessor DMA card. The Apple collection software presented in Appendix III.1 requires the CCS card to be mounted in slot 2 and the DMA card to be mounted in slot 4. However, these slot assignments can be changed by first altering the values of the constants CSR, DMAREG, and SLPIO in the program and then recompiling the program. CSR is the location of the CCS card status register, DMAREG is the beginning location for the DMA card programmable registers, and SLPIO is the beginning location for the DMA card Control Signals (see Appendix III.1).

Two floppy disk drives are required by the LSI-11 collection software to collect data in an efficient manner. One drive contains the system floppy disk and the other drive contains the data floppy disk. The system

disk is generally assigned as the drive on which the computer is booted. The data drive is assigned in the main program file FZZ.FOR in the first four locations of the array variable FNAME. Presently the data disk is assigned as DY0:.

As mentioned throughout Section 5.3 on Data Collection Communication Routines, the data frames sent from the Apple to the LSI-11 are of variable length with the maximum data byte count set by the constant PAKLEN. Changing the maximum data byte count is done by first setting the PAKLEN constant in both the Apple Sender program section and the LSI-11 RCVER section to the desired value and then recompiling the programs. Because of the error checking feature (checksum) of the frame communications technique, in a noisy environment many short data frames may provide more efficient transmission than a fewer number of long data frames. For this reason, a simple method of changing the maximum data byte count in a data frame was provided.

5.5 Data Conversion Software

During data collection, the collection software permanently stores sets of profiles on a floppy disk in unformatted direct access files. The data values in these files are represented in a binary format. After the collection is completed the data are transferred to the University of Illinois CYBER computer for further processing. However, the binary data files must be converted to files with an ASCII format before the transfer can occur. This is due to hardware restrictions in the LSI-11-CYBER link used to transfer the data. The routine CONVRT.SAV is used to accomplish the binary-to-ASCII file conversion.

CONVRT initially requests the name of the device containing the binary files and the name of the device on which the converted files will be

stored. Typical responses might be DY0: and DMI:. Next, a set number is requested and also the total number of profiles in the set must be entered. CONVRT also requests the input of four values that are not recorded in the binary data files. These values are the ground speed (kts), altitude (ft), latitude (deg.-min.), and longitude (deg.-min.) at the time the profile was collected. These are values that were recorded manually during the airborne experiment discussed in Chapter 6; and CONVRT inserts them into the ASCII data files.

The binary-to-ASCII conversion is accomplished with the use of the Fortran functions ENCODE and DECODE. The binary files designated by the name SETxxx.DAT are converted and saved in new files designated by the name SETxxx.ASC, where xxx is the set number. The listing of CONVRT in Appendix III.14 shows the format of the ASCII data files.

6. PRELIMINARY RESULTS OF AN AIRBORNE EXPERIMENT

6.1 Introduction

In March 1983, the University of Illinois Aeronomy Laboratory (Lidar Group) conducted an airborne sodium lidar experiment aboard a National Aeronautics and Space Administration (NASA) aircraft. The primary goal of the experiment was to determine the feasibility of obtaining mesospheric sodium density measurements with an airborne lidar system. In reference to this report, the initial testing of the new sodium lidar preprocessing system with the complete lidar system was conducted during this airborne experiment.

Initial sodium lidar measurements by the University of Illinois Lidar Group were made from ground-based stations [Richter and Sechrist, 1978; Shelton and Gardner, 1981]. Generally, these experiments provided information on the temporal structure of the mesospheric sodium layer as the layer drifted above the test site. In addition, the use of a steerable receiving telescope at NASA Goddard Space Flight Center provided limited observations of the horizontal structure of the layer. An airborne lidar system holds two distinct advantages over these ground-based systems. First, attenuation of the transmitted laser pulse due to low-altitude cloud cover and haze can be alleviated by flying above the obstructions. Second, the aircraft allows observations to be recorded over a long horizontal base line, an essential requirement for good horizontal structure measurements of the layer. This particular airborne experiment was designed as a forerunner to more extensive airborne sodium lidar observations.

6.2 Airborne Sodium Lidar System

The sodium lidar system was flown aboard the NASA Lockheed Electra

L-188 turboprop aircraft (Figure 6.1). The aircraft is stationed at NASA Wallops Flight Center, Wallops Island, Virginia. The University of Illinois lidar equipment was used in conjunction with the NASA Electra Lidar Facility. This Lidar Facility consists of three standard optical table tops and a 16-inch, $f/2.5$ primary, receiving telescope all mounted on a table support structure.

The telescope is mounted near the center of the support table in an upward pointing position. Two of the optical table tops are positioned on top of the support table on either side of the telescope. The third optical table top is mounted in the support structure underneath the larger upper table top. The support structure is bolted to the floor of the aircraft with the telescope positioned beneath a quartz window in the roof of the plane's cabin.

The dye laser and transmitting optics for the lidar system were fastened to the larger upper table top of the Lidar Facility. The laser beam was steered through the quartz window, located directly over the telescope, with dielectric-coated optics. The receiving components, including the preprocessing system, were fastened to the smaller upper table top of the Lidar Facility. Power supplies and laser tuning equipment were mounted on the lower table top. Figure 6.2 shows the equipment configuration on the receiving side of the Lidar Facility. Figure 6.3 is a photograph of the equipment from the transmitting side of the Facility. The laser high-voltage power supply and chiller unit in Figure 6.3 were bolted to the floor of the aircraft. Also shown in Figure 6.3 are the nitrogen gas bottle, which provided nitrogen for purging the laser dye of oxygen, and the line printer used by the LSI-11 main computer.

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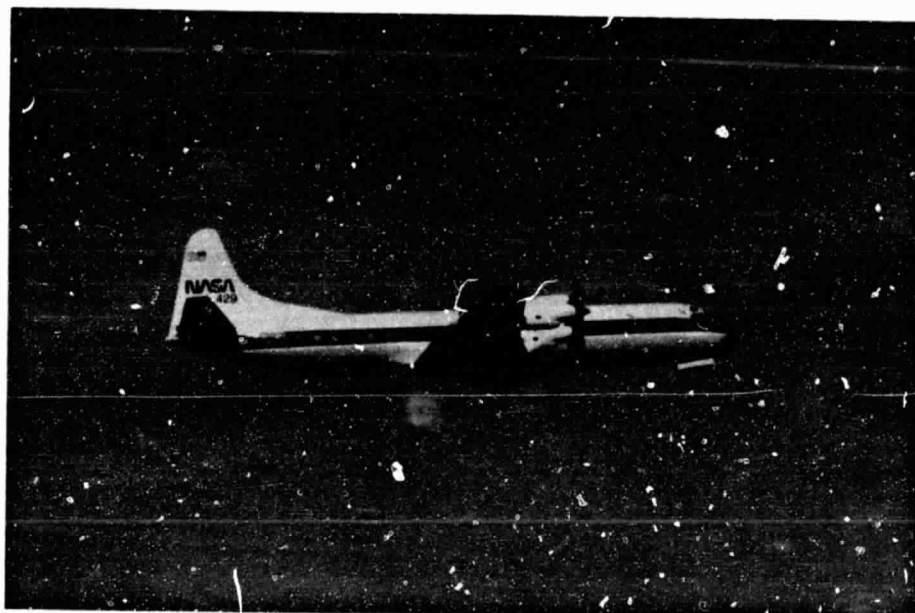


Figure 6.1 Photograph of the NASA Electra aircraft.

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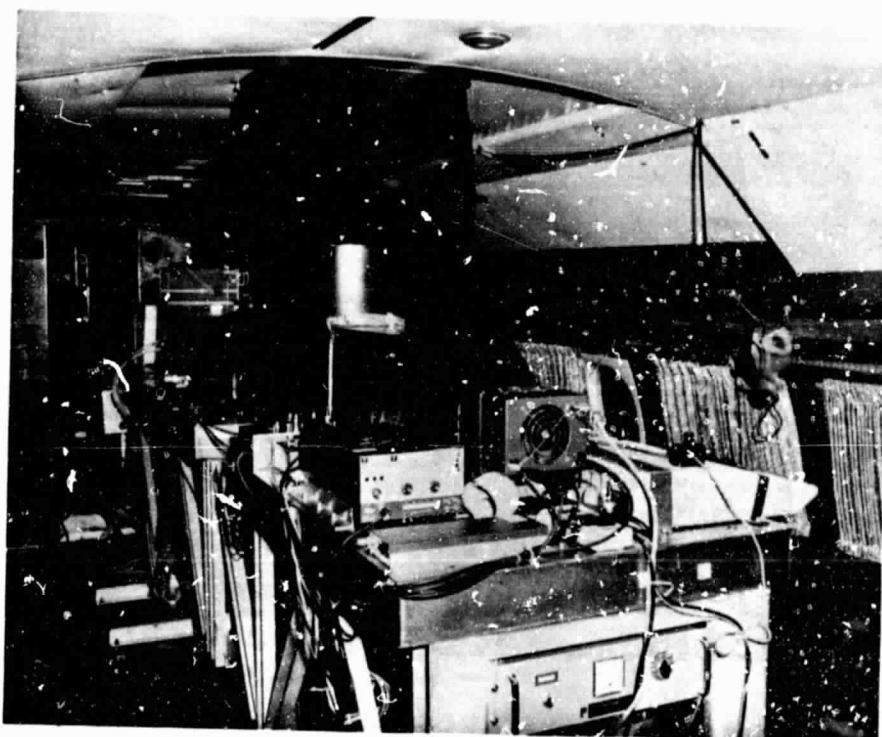


Figure 6.2 Photograph of the lidar receiving system equipment aboard the NASA Electra. On top of the table in the foreground from left to right are the amplifier-discriminator, PMT housing, and the preprocessor Apple microcomputer.

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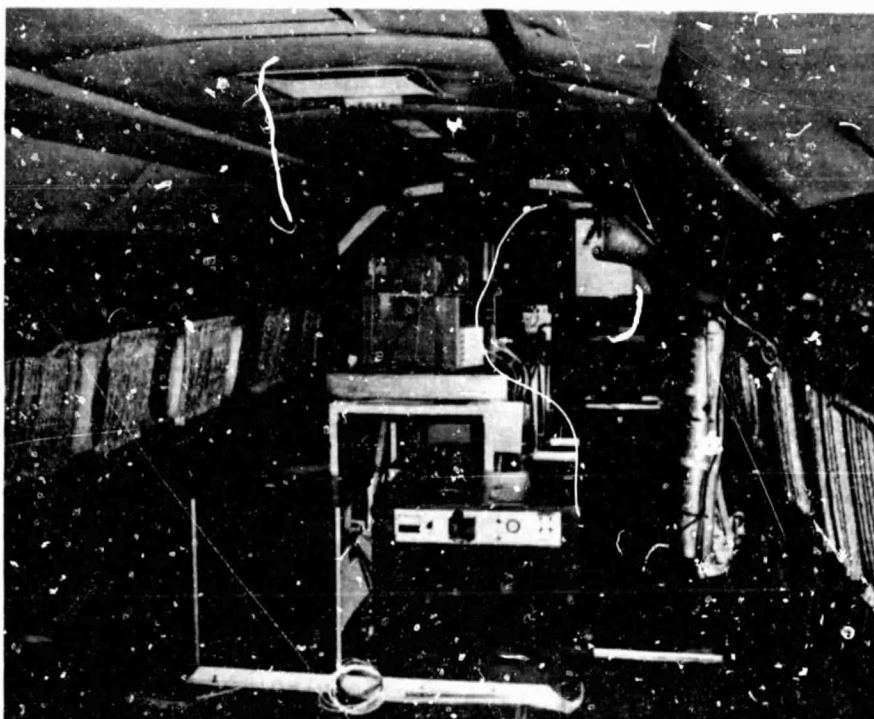


Figure 6.3 Photograph of the lidar transmitting system equipment aboard the NASA Electra. In the foreground on the floor are the laser high-voltage power supply and chiller unit. On the table are the laser tuning monitor oscilloscopes. The laser head is located on the table behind the oscilloscopes.

Figure 6.4 shows the computer rack. This rack was positioned across the aisle from the line printer. Mounted in the rack were the LSI-11 computer, disk drive, terminal, monitor, and the preprocessing system Apple monitor.

6.3 Results

The airborne lidar test was conducted on the night of March 30, 1983 beginning at approximately 2130 EST. The flight originated at Wallops Flight Center (38 °N, 74 °W), reached a turn-around point near Albany, NY (42 °N, 73 °W), and terminated at Wallops at approximately 2330 EST. Although data collection began during the ascent, scattering of the laser beam by high cirrus clouds prevented collection of good sodium data until the aircraft reached an altitude above 25,000 feet. A similar collection problem occurred during the descent. Also, occasional cirrus above 30,000 feet attenuated the received sodium signal photons at various points in the experiment.

Plots of the spatial variations in estimates of the sodium density are shown in Figure 6.5. Figure 6.5(a) shows sodium density profiles collected on the outbound leg of the flight and Figure 6.5(b) shows profiles collected on the return leg. Each profile required 2,000 laser shots. The peak sodium concentration is seen to be located above 90 km which is consistent with previous measurements obtained during the month of March with the ground-based systems. The distribution of the sodium density around the peak is also consistent with previous ground-based observations. The profiles seem to have some related structural features such as the descending local peaks beneath the principal peaks in the three profiles on the right side of Figure 6.5(b). Another interesting feature, most notable in Figure 6.5(a), is a possible secondary layer appearing above 100 km.

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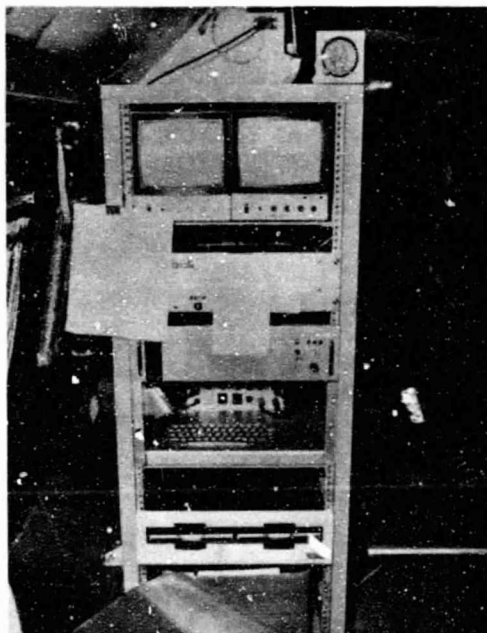


Figure 6.4 Photograph of the computer rack aboard the NASA Electra. Mounted in the rack from top to bottom are the LSI-11 and Apple monitors, the LSI-11 power supply and computer backplane, the LSI-11 keyboard, and the LSI-11 floppy disk drives.

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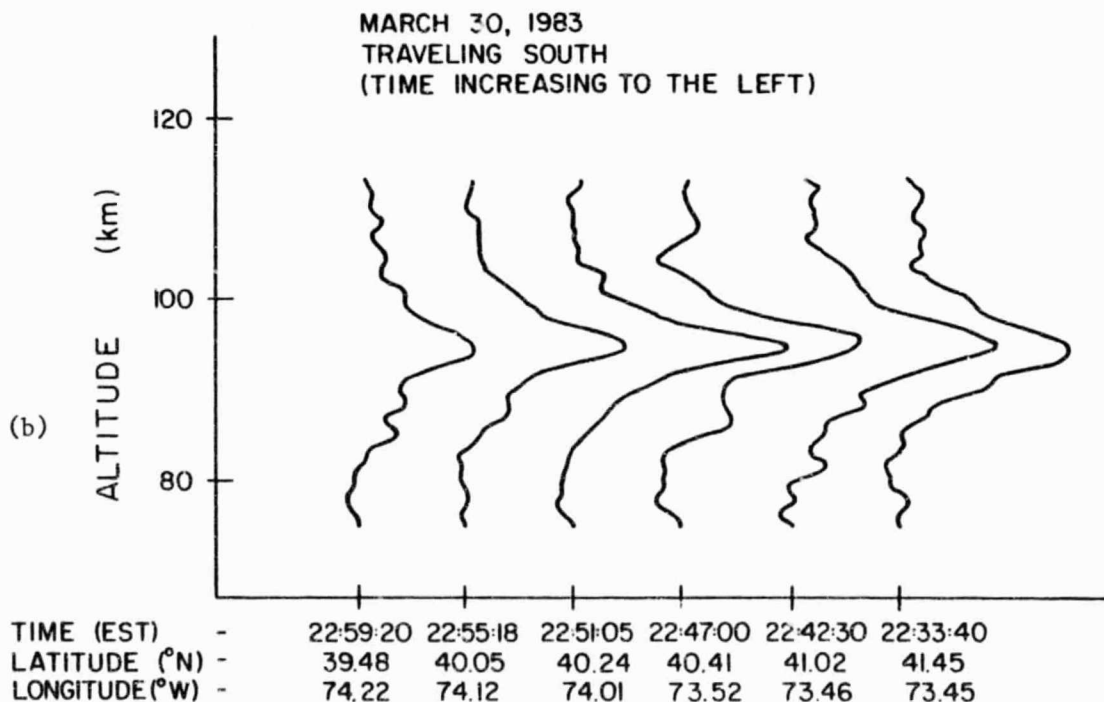
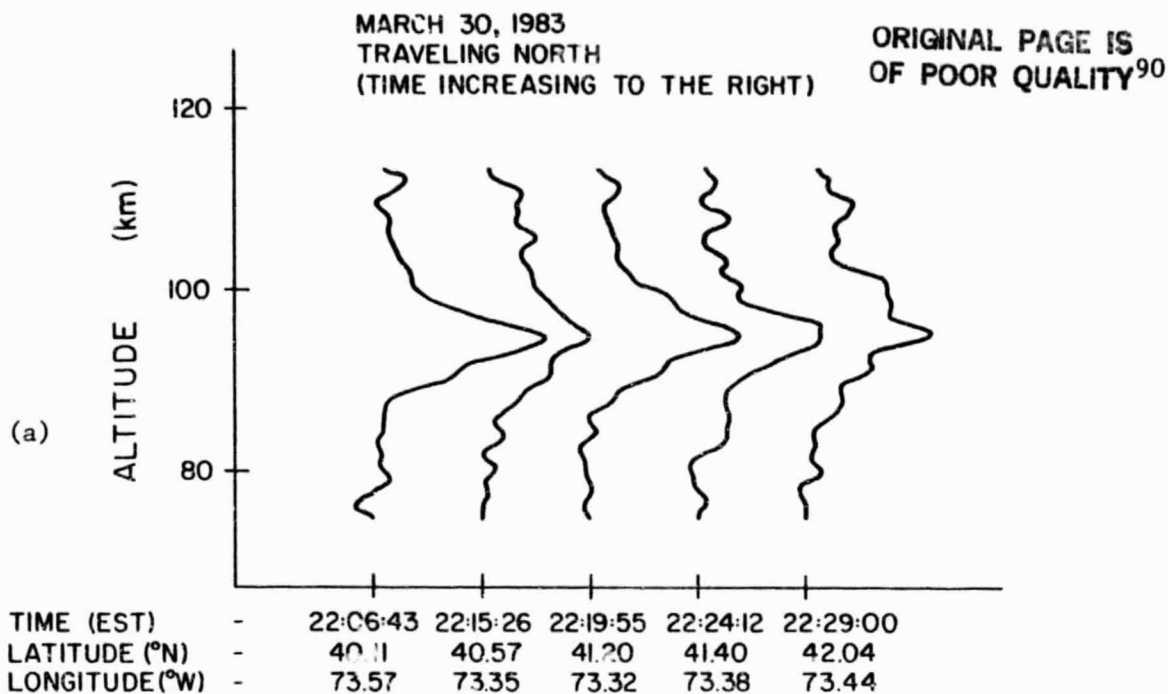


Figure 6.5 Time and location history of the estimated altitude profiles of sodium density observed on (a) the outbound leg and (b) the return leg of the airborne experiment conducted on March 30, 1983. A Hamming window lowpass filter with a cutoff of $.35 \text{ km}^{-1}$ was used to spatially filter the profiles.

7. CONCLUSIONS AND SUGGESTIONS FOR FUTURE WORK

The preliminary results of the airborne sodium lidar experiment presented in Chapter 6 indicate that the preprocessing system is functioning as designed. The sodium layer profiles collected during the experiment contain features that are similar to those typically observed by sodium lidar systems. Noise in the data resulting from cloud cover and other factors makes it difficult to evaluate the performance of the preprocessing system in an absolute manner. However, no obvious contamination of the data directly attributable to the preprocessing system was noticed.

Desirable future additions to the preprocessing and main computer systems would include the capability of further real-time processing of the data during collection. This might involve digitally filtering the data and displaying the filtered profiles on a graphics terminal. This type of immediate feedback would help in maintaining the lidar system at an optimal operation level. For example, drifting of the laser tuning would be clearly noticeable in the displayed profiles. Also, the displayed profiles would indicate the quality of the data and any interesting features of the profiles.

Because of the interrupt structure of the preprocessing system software, both the Apple and LSI-11 computers may be employed to run background routines in addition to the data collection routines. This provides the option of controlling any of the lidar system equipment with a computer. Examples would be computer-directed laser tuning and computer-controlled alignment of the transmitted and received beams.

I.1 Apple Peripheral Card Connector Pinout

<u>PIN</u>	<u>NAME</u>	<u>FUNCTION</u>
1	<u>I/O SELECT</u>	MEMORY MAPPED SELECT LINE
2	A0	} ADDRESS BUS
3	A1	
4	A2	
5	A3	
6	A4	
7	A5	
8	A6	
9	A7	
10	A8	
11	A9	
12	A10	
13	A11	
14	A12	
15	A13	
16	A14	
17	A15	
18	R/ <u>W</u>	READ/WRITE
19	<u>N.C.</u>	
20	<u>I/O STROBE</u>	MEMORY MAPPED STROBE LINE
21	<u>RDY</u>	6502 'READY' LINE
22	<u>DMA</u>	DIRECT MEMORY ACCESS CONTROL LINE
23	INT OUT	INTERRUPT DAISY CHAIN OUTPUT
24	DMA OUT	DMA DAISY CHAIN OUTPUT
25	+5V	+5 VOLTS
26	GND	LOGICAL GROUND
27	DMA IN	DMA DAISY CHAIN INPUT
28	INT IN	INTERRUPT DAISY CHAIN INPUT
29	<u>NMI</u>	NON MASKABLE INTERRUPT REQUEST
30	<u>IRQ</u>	INTERRUPT REQUEST
31	<u>RES</u>	RESET LINE
32	<u>INH</u>	ROM INHIBIT LINE
33	-12V	-12 VOLTS
34	-5V	-5 VOLTS
35	<u>N.C.</u>	
36	7M	7 MHZ CLOCK
37	Q3	2 MHZ (ASYMMETRIC) CLOCK
38	Φ 1	PHASE 1 CLOCK
39	USER1	INTERNAL I/O ADDRESS DISABLE
40	Φ 0	PHASE 0 CLOCK (ALSO Φ 2)
41	<u>DEVICE SELECT</u>	MEMORY MAPPED SELECT LINE
42	D7	} DATA BUS
43	D6	
44	D5	
45	D4	
46	D3	
47	D2	
48	D1	
49	D0	
50	+12V	+12 VOLTS

I.2 Apple DMA Card Ribbon Connector Pinout

<u>PIN</u>	<u>NAME</u>	<u>FUNCTION</u>
1	GND	} LOGIC GROUND
2		
3		
4		
5		
6		
7		
8		
9		
10		
11	GND	
12	$\overline{Y3}$	CONTROL LINE $\overline{Y3}$
13	$\overline{Y1}$	CONTROL LINE $\overline{Y1}$
14	\overline{RES}	RESET LINE
15	\overline{TxRQ}	DMA TRANSFER REQUEST
16	N.C.	
17	N.C.	
18	\overline{DEND}	DMA END SIGNAL
19	\overline{TxSTB}	DMA TRANSFER STROBE
20	\overline{TxAKA}	DMA TRANSFER ACKNOWLEDGE
21	\overline{DGRNT}	DMA BUS GRANT
22	$\overline{Y2}$	CONTROL LINE $\overline{Y2}$
23	$\overline{Y4}$	CONTROL LINE $\overline{Y4}$
24	$\overline{Q3}$	INVERTED APPLE $\overline{Q3}$ CLOCK
25	$\Phi 0$	APPLE $\Phi 0$ CLOCK
26	$\Phi 1$	APPLE $\Phi 1$ CLOCK
27	D0	} DATA LINES
28	D1	
29	D2	
30	D3	
31	D4	
32	D5	
33	D6	
34	D7	

I.3 SLIPP Unit External Ribbon Connector Pinout

<u>PIN</u>	<u>NAME</u>	<u>FUNCTION</u>
1	<u>DEND</u>	DMA END SIGNAL
2	<u>TxSTB</u>	DMA TRANSFER STROBE
3	<u>TxAKA</u>	DMA TRANSFER ACKNOWLEDGE
4	<u>DGRNT</u>	DMA BUS GRANT
5	<u>Y2</u>	CONTROL LINE <u>Y2</u>
6	<u>Y4</u>	CONTROL LINE <u>Y4</u>
7	<u>Q3</u>	INVERTED APPLE Q3 CLOCK
8	$\Phi 0$	APPLE $\Phi 0$ CLOCK
9	$\Phi 1$	APPLE $\Phi 1$ CLOCK
10	D0	} DATA LINES
11	D1	
12	D2	
13	D3	
14	D4	
15	D5	
16	D6	
17	D7	
18	GND	} LOGIC GROUND
19		
20		
21		
22		
23		
24		
25		
26		
27		
28	<u>GND</u>	
29	<u>Y3</u>	CONTROL LINE <u>Y3</u>
30	<u>Y1</u>	CONTROL LINE <u>Y1</u>
31	<u>RES</u>	RESET LINE
32	<u>TxRQ</u>	DMA TRANSFER REQUEST
33	N.C.	
34	N.C.	

I.4 SLIPP Unit Internal Card Edge Connector Pinout

<u>PIN</u>	<u>NAME</u>	<u>FUNCTION</u>
A	+5V	+5 VOLTS
B	D7	} DATA LINES
C	D6	
D	D5	
E	D4	
F	D3	
H	D2	
J	D1	
K	D0	
L	$\Phi 1$	APPLE $\Phi 1$ CLOCK
M	$\Phi 0$	APPLE $\Phi 0$ CLOCK
N	$\overline{Q3}$	INVERTED APPLE Q3 CLOCK
P	$\overline{Y4}$	CONTROL LINE $\overline{Y4}$
R	$\overline{Y2}$	CONTROL LINE $\overline{Y2}$
S	\overline{DGRNT}	DMA BUS GRANT
T	\overline{TxAKA}	DMA TRANSFER ACKNOWLEDGE
U	\overline{TxSTB}	DMA TRANSFER STROBE
V	DEND	DMA END SIGNAL
W	N.C.	
X	N.C.	
Y	N.C.	
Z	GND	LOGIC GROUND
1	-5V	-5 VOLTS
2	GND	} LOGIC GROUND
3		
4		
5		
6		
7		
8		
9		
10		
11		
12	GND	
13	$\overline{Y3}$	CONTROL LINE $\overline{Y3}$
14	$\overline{Y1}$	CONTROL LINE $\overline{Y1}$
15	\overline{RES}	RESET LINE
16	\overline{TxRQ}	DMA TRANSFER REQUEST
17	N.C.	
18	N.C.	
19	AUX OUT	AUXILIARY OUTPUT
20	TRIG	LASER TRIGGER OUTPUT
21	LCP	LASER COMMAND PULSE INPUT
22	NIM	FAST NIM DISCRIMINATOR INPUT

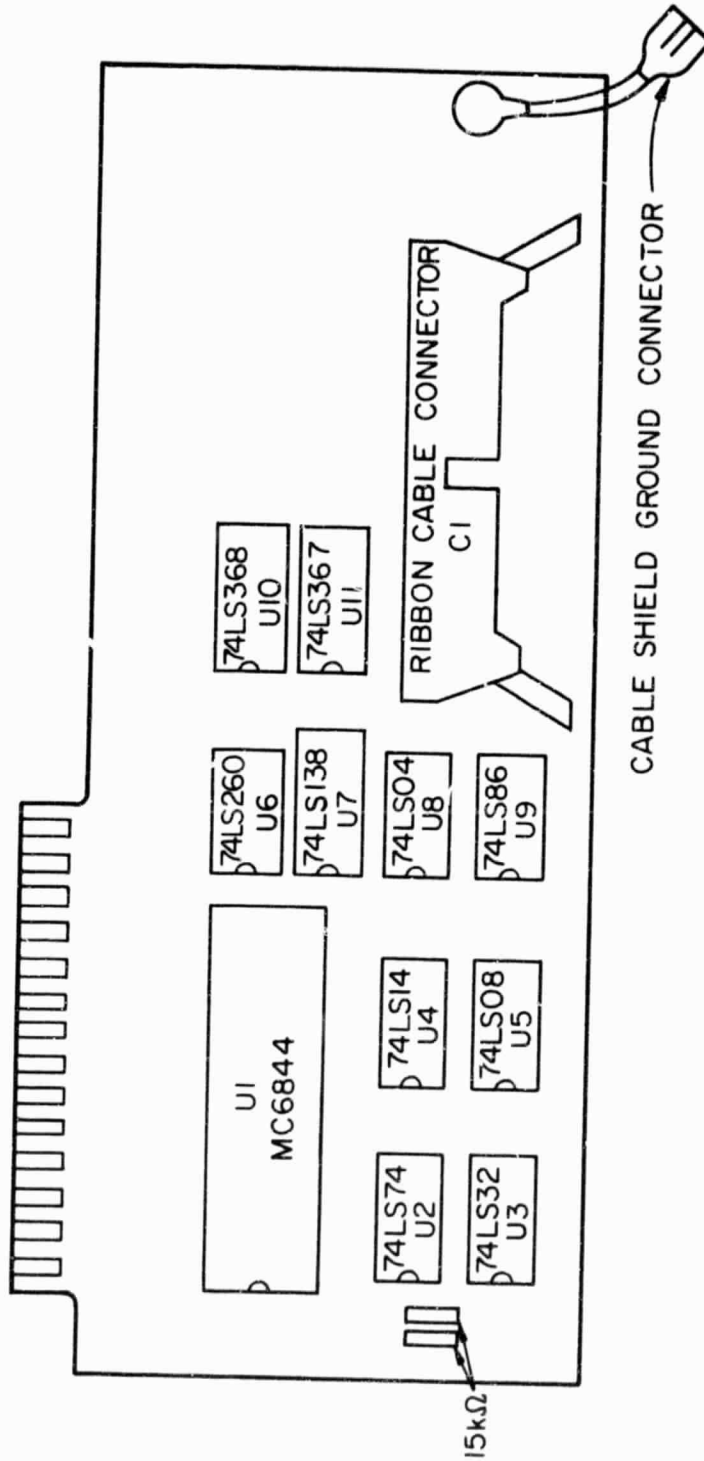


Figure II.1 Apple DMA card component diagram.

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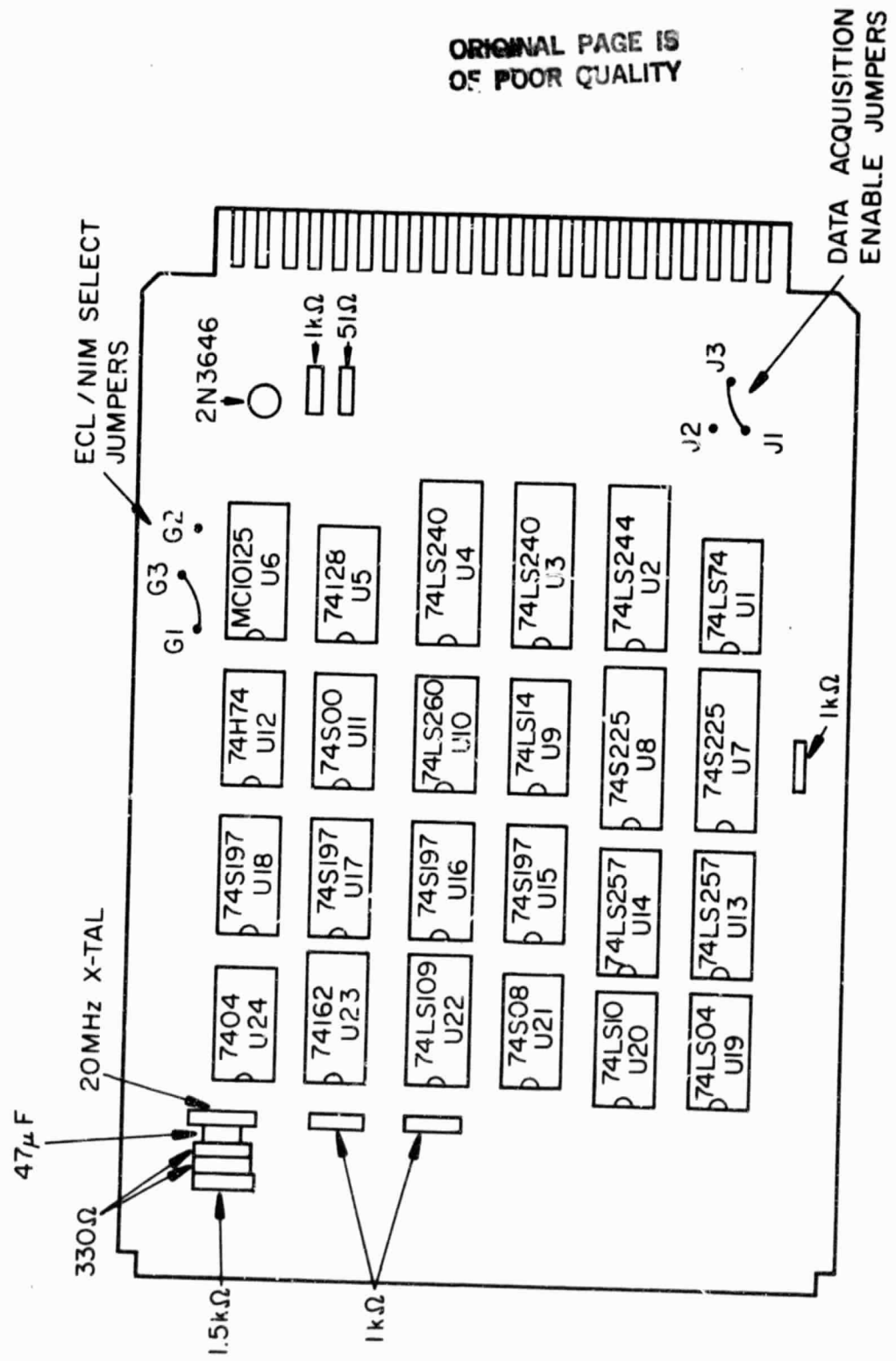


Figure II.2 SLIPP unit circuit component diagram.

APPENDIX III SOFTWARE LISTINGS

III.1 SLPAPP

SOURCE FILE: SLPAPP

---- NEXT OBJECT FILE NAME IS SLPAPP.OBJ

```

0C28:          1          ORG  %C28
0C28:          2 *****
0C28:          3 *
0C28:          4 *          APPLE
0C28:          5 *          SLIPP SOFTWARE
0C28:          6 *          D.VOELZ
0C28:          7 *          FEB. 20, 1983
0C28:          8 *
0C28:          9 *****
0C28:         10 *
0C28:         11 * I/O  LOCATIONS
0C28:         12 *
0C0A:         13 CSR    EQU  %C0A0    ;SERIAL CARD IN SLOT 2
0C0A:         14 XRDR   EQU  CSR+1
0C26:         15 *
0C40:         16 DMAREG EQU  %C400    ;DMA BOARD IN SLOT 4
0C0C:         17 SLPIO  EQU  %C0C0
0C0C:         18 TRIG   EQU  SLPIO+1
0C0C:         19 SLPRST EQU  SLPIO+4
0C28:         20 *
0C28:         21 * GENERAL PARAMETERS
0C28:         22 *
0003:         23 ERRCNT EQU  3          ;ERROR COUNT
0032:         24 DEL1   EQU  50          ;DELAY PAR. 1
0031:         25 DRUN   EQU  $31          ;OPCODES -DATA RUN
0032:         26 COM    EQU  $32          ;          -COMMANDS
0033:         27 PRDONE EQU  $33          ;          -PROFILE DONE
0034:         28 ACK    EQU  $34          ;          -ACKNOWLEDGE
0045:         29 COMEND EQU  $45          ;          -COMMANDS DONE
0081:         30 CTX    EQU  $81          ; 'CTX' CHAR
0082:         31 ETX    EQU  $82          ; 'ETX' CHAR
0083:         32 STX    EQU  $83          ; 'STX' CHAR
0090:         33 DLE    EQU  $90          ; 'DLE' CHAR
03FE:         34 INTV   EQU  $03FE        ;INTERRUPT VECTOR
FCAB:         35 WAIT   EQU  %FCAB        ;DELAY ROUTINE
FF3F:         36 IOREST EQU  %FF3F        ;RESTORE REGISTERS
FF4A:         37 IOSAVE EQU  %FF4A        ;SAVE REGISTERS
0C28:         38 *
0C28:         39 * DATA PACKET PARAMETERS
0C28:         40 *
0050:         41 OPCLO  EQU  $50          ;LO BYTE DATA OPCODE
00E0:         42 OPCHI  EQU  $E0          ;HI BYTE DATA OPCODE
6000:         43 BUFADD EQU  $6000        ;INPUT BUFFER MEMORY
9000:         44 STADDL EQU  $9000        ;LO BYTE MAINFRAME MEMORY
9800:         45 STADH  EQU  STADDL+$800 ;HI BYTE MAINFRAME MEMORY

```

```

07D0:          46 PAKLEN EQU 2000      ;PACKET LENGTH (MAX=32767)
07D0:          47 BYTCNT EQU 2000    ;BYTE COUNT
0C28:          48 *
0C28:          49 * MONITOR REFERENCES
0C28:          50 *
0024:          51 CH EQU $24        ;HORIZONTAL TAB LOCATION
0025:          52 CV EQU $25        ;VERTICAL TAB LOCATION
003B:          53 KSW EQU $3B       ;KEYBOARD SWITCH
008D:          54 CR EQU $8D       ;CARRIAGE RETURN
C010:          55 KBDSTB EQU $C010    ;KEYBOARD STROBE
FC58:          56 HOME EQU $FC58    ;CLEAR SCREEN
FC22:          57 VTAB EQU $FC22    ;VERTICAL TAB
FD0C:          58 RDKEY EQU $FD0C    ;READ KEY ROUTINE
FD1B:          59 KEYIN EQU $FD1B    ;KEY INPUT ROUTINE
FDF0:          60 COUT1 EQU $FDF0    ;OUTPUT CHARACTER
FE80:          61 SETINV EQU $FE80    ;INVERSE SCREEN
FE84:          62 SETNRM EQU $FE84    ;NORMAL SCREEN
0C28:          63 *
0C28:          64 * ZERO PAGE VARIABLES
0C28:          65 *
0000:          66          DSECT
00F9:          67          ORG $F9
00F9:          68 ADDRES DS 2          ;TRANSMIT ADDRESS VECTOR
00FB:          69 BYTES1 DS 2          ;TRANSMIT BYTE COUNTER
00FD:          70 PRTADD DS 2          ;PRINTING ADDRESS VECTOR
00FF:          71 TLBTCT DS 1          ;TEMPORARY TRANSMIT BYTE COUNTER
0C28:          72          DEND
0C28:          73 *
0C28:          74 * GENERAL VARIABLES
0C28:          75 *
0000:          76          DSECT
0C00:          77          ORG $0C00
0C00:          78 REPNUM DS 1          ;LASER REP NUMBER
0C01:          79 MSHOTS DS 2          ;SHOTS/PROFILE (MAX=32767)
0C03:          80 *
0C03:          81 ACKFLG DS 1          ;ACKNOWLEDGE FLAG
0C04:          82 DATOPC DS 1          ;TRANSMIT OPCODE STORAGE
0C05:          83 ERRORS DS 1          ;ERROR COUNTER
0C06:          84 LSTFLC DS 1          ;LAST PAGE TRANSMIT FLAG
0C07:          85 OPCODE DS 1          ;RECVD OPCODE STORAGE
0C08:          86 *
0C08:          87 COUNT1 DS 2          ;TEMP. TRANSMIT BYTE COUNTER
0C0A:          88 RCSUM DS 2          ;RECVD CHECKSUM
0C0C:          89 SAVADD DS 2          ;PLACE TO SAVE ADDRESS
0C0E:          90 SAVSUM DS 2          ;PLACE TO SAVE CHECKSUM
0C10:          91 STATE DS 2          ;INPUT BYTE VECTOR
0C12:          92 TSHOT DS 2          ;SHOT COUNTER
0C14:          93 XCSUM DS 2          ;TRANSMIT CHECKSUM
0C28:          94          DEND
0C28:          95 *
0C28:          96 *****
0C28:          97 *
0C28:          98 * MAIN PROGRAM LOOP
0C28:          99 *
0C28:          100 *****
0C28:          101 *

```

```

0C2B:          102 * INITIALIZE RECEIVER
0C2B:          103 *
0C2B:A9 1B     104          LDA #>KEYIN    ;LOAD KEYBOARD SWITCH
0C2A:85 3B     105          STA KSW
0C2C:A9 FD     106          LDA #<KEYIN
0C2E:85 39     107          STA KSW+1
0C30:          108 *
0C30:2C 10 C0  109          BIT KBDSTB    ;CLEAR KEYBOARD STROBE
0C33:          110 *
0C33:20 6C 10  111          JSR HEDPRT    ;PRINT HEADING
0C36:          112 *
0C36:A9 03     113          LDA #03        ;MASTER RESET ACIA
0C38:8D A0 C0  114          STA CSR
0C3B:A9 95     115          LDA #95        ;SET UP ACIA
0C3D:8D A0 C0  116          STA CSR
0C40:          117 *
0C40:A9 5E     118          LDA #>IOINT    ;SET INTERRUPT VECTOR
0C42:8D FE 03  119          STA INTV      ; FOR IOINT
0C45:A9 0C     120          LDA #<IOINT
0C47:8D FF 03  121          STA INTV+1
0C4A:          122 *
0C4A:A9 8C     123          LDA #>STPAK1   ;SET INPUT BYTE VECTOR
0C4C:8D 10 0C  124          STA STATE
0C4F:A9 0C     125          LDA #<STPAK1
0C51:8D 11 0C  126          STA STATE+1
0C54:          127 *
0C54:58        128          CLI                ;CLEAR INTERRUPT BIT
0C55:20 B6 10  129          JSR IDLPRT    ;PRINT 'IDLE'
0C58:          130 *
0C58:EA        131 WLOOP   NOP                ;IDLE LOOP
0C59:EA        132          NOP
0C5A:EA        133          NOP
0C5B:4C 58 0C  134          JMP WLOOP
0C5E:          135 *
0C5E:          136 *****
0C5E:          137 *
0C5E:          138 * APPLE RECEIVER
0C5E:          139 *
0C5E:          140 *****
0C5E:          141 *
0C5E:          142 * INTERRUPT ENTRY POINT
0C5E:          143 *
0C5E:78        144 IOINT   SEI                ;DISABLE INTERRUPT
0C5F:20 4A FF  145          JSR IOSAVE    ;SAVE REGISTERS
0C62:AD A0 C0  146          LDA CSR        ;CLEAR INTR BIT IN CSR
0C65:AD A1 C0  147          LDA XRDR      ;LOAD ACCUM WITH INPUT BYTE
0C68:6C 10 0C  148          JMP (STATE)   ;GO TAKE CARE OF INPUT BYTE
0C6B:          149 *
0C6B:          150 * INTERRUPT EXIT POINT
0C6B:          151 *
0C6B:18        152 GETBT   CLC                ;UPDATE RECD CHECKSUM
0C6C:6D 0A 0C  153          ADC RCSUM    ; LO BYTE
0C6F:90 03     154          BCC SKUPRC
0C71:EE 0B 0C  155          INC RCSUM+1   ; HI BYTE
0C74:8D 0A 0C  156 SKUPRC  STA RCSUM
0C77:          157 *

```

```

0C77:18      158      CLC          ;SET NEW INPUT BYTE VECTOR
0C78:68      159      PLA          ; PULL LO ADDRESS(-1)
0C79:69 01   160      ADC #1
0C7B:8D 10 0C 161      STA STATE
0C7E:6E      162      PLA          ; PULL HI ADDRESS
0C7F:69 00   163      ADC #0
0C81:8D 11 0C 164      STA STATE+1
0C84:         165 *
0C84:20 3F FF 166      JSR IOREST  ;RESTORE REGISTERS
0C87:58      167      CLI          ;ENABLE INTERRUPT
0C88:40      168      RTI
0C89:         169 *
0C89:         170 *-----
0C89:         171 * PACKET RECEIVING
0C89:         172 *-----
0C89:20 6B 0C 173 STPAK JSR GETBT
0CB0:C9 90   174 STPAK1 CMP #DLE    ;CHECK FOR 'DLE' BYTE
0C8E:D0 F9   175      BNE STPAK
0C90:         176 *
0C90:20 6B 0C 177      JSR GETBT
0C93:C9 83   178      CMP #STX    ;CHECK FOR 'STX' BYTE
0C95:D0 F2   179      BNE STPAK
0C97:A2 00   180      LDX #0      ; ZERO RECD CHECKSUM
0C99:8E 0A 0C 181      STX RCSUM
0C9C:8E 0B 0C 182      STX RCSUM+1
0C9F:         183 *
0C9F:20 6B 0C 184      JSR GETBT  ;GET OPCODE
0CA2:8D 07 0C 185      STA OPCDE  ; SAVE IT
0CA5:         186 *
0CA5:         187 * VERIFY CHECKSUM
0CA5:         188 *
0CA5:20 6B 0C 189 VERCHK JSR GETBT  ;GET 'DLE' BYTE
0CAB:20 6B 0C 190      JSR GETBT  ;GET 'ETX' BYTE
0CAB:AE 0A 0C 191 VERIFY LDX RCSUM  ;SAVE LO BYTE RECD CHECKSUM
0CAE:8E 0E 0C 192      STX SAVSUM
0CB1:AE 0B 0C 193      LDX RCSUM+1 ;SAVE HI BYTE RECD CHECKSUM
0CB4:8E 0F 0C 194      STX SAVSUM+1
0CB7:         195 *
0CB7:20 6B 0C 196      JSR GETBT  ;GET LO BYTE XMITTED CHECKSUM
0CBA:CD 0E 0C 197      CMP SAVSUM  ; CHECK IT
0CBD:D0 CA   198      BNE STPAK
0CBF:         199 *
0CBF:20 6B 0C 200      JSR GETBT  ;GET HI BYTE XMITTED CHECKSUM
0CC2:CD 0F 0C 201      CMP SAVSUM+1 ; CHECK IT
0CC5:D0 C2   202      BNE STPAK
0CC7:         203 *
0CC7:         204 * DECIPHER GPCODE
0CC7:         205 *
0CC7:AD 07 0C 206      LDA OPCDE  ;LOAD OPCODE
0CCA:C9 34   207      CMP #ACK    ; ACK ?
0CCC:F0 18   208      BEQ ACKN
0CCE:C9 32   209      CMP #COM    ; COMMANDS ?
0CD0:F0 1C   210      BEQ COMN
0CD2:C9 45   211      CMP #COMEND ; COMMAND PACKET COMPLETED ?
0CD4:D0 06   212      BNE CHKDTR ; -NO,GO ON
0CD6:20 1E 0D 213      JSR SNDACK ; -YES,SEND ACK

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```

OCD9:4C B9 0C 214          JMP  STPAK
OCD9:C9 31          215 CHKDTR CMP  #DRUN      ; DATA RUN ?
OCD9:D0 A9         216          BNE  STPAK      ; -NO,BAD OPCODE
OCE0:20 1E 0D     217          JSR  SNDACK     ; -YES,SEND ACK
OCE3:4C A6 0E     218          JMP  DATRUN     ; JUMP TO DATA RUN
OCE6:              219 *
OCE6:              220 *-----
OCE6:              221 * RECEIVED ACKNOWLEDGE
OCE6:              222 *-----
OCE6:A9 01        223 ACKN  LDA  #1          ;SET ACK FLAG
OCE8:8D 03 0C     224          STA  ACKFLG
OCE8:4C B9 0C     225          JMP  STPAK
OCEE:              226 *
OCEE:              227 *
OCEE:              228 *-----
OCEE:              229 * RECEIVE COMMANDS
OCEE:              230 *-----
OCEE:A9 45        231 CGMN  LDA  #COMEND   ;STORE 'COMMANDS COMPLETED' OPC
OCF0:8D 07 0C     232          STA  GPCDE
OCF3:20 6B 0C     233          JSR  GETBT
OCF6:C9 90        234          CMP  #DLE       ;CHECK FOR 'DLE' BYTE
OCF8:D0 8F        235          BNE  STPAK
OCFA:              236 *
OCFA:20 6B 0C     237          JSR  GETBT
OCFD:C9 B1        238          CMP  #CTX       ;CHECK FOR 'CTX' BYTE
OCFF:D0 88        239          BNE  STPAK
OD01:A2 00        240          LDX  #0         ; ZERO RECD CHECKSUM
OD03:8E 0A 0C     241          STX  RCSUM
OD06:8E 0B 0C     242          STX  RCSUM+1
OD09:              243 *
OD09:20 6B 0C     244          JSR  GETBT     ;GET LASER REP NUMBER
OD0C:8D 00 0C     245          STA  REPNUM
OD0F:20 6B 0C     246          JSR  GETBT     ;GET LO BYTE SHOTS/PROF
OD12:8D 01 0C     247          STA  MSHOTS
OD15:20 6B 0C     248          JSR  GETBT     ;GET HI BYTE SHOTS/PROF
OD18:8D 02 0C     249          STA  MSHOTS+1
OD1B:4C A5 0C     250          JMP  VERCHK
OD1E:              251 *
OD1E:              252 *****
OD1E:              253 *
OD1E:              254 * APPLE SENDER
OD1E:              255 *
OD1E:              256 *****
OD1E:              257 *
OD1E:              258 *-----
OD1E:              259 * SEND ACKNOWLEDGE
OD1E:              260 *-----
OD1E:A9 34        261 SNDACK LDA  #ACK       ;LOAD ACK OPCODE
OD20:8D 04 0C     262          STA  DATOPC
OD22:20 5C 0E     263          JSR  SNDFRM   ;SEND ACK FRAME
OD26:60          264          RTS
OD27:              265 *
OD27:              266 *-----
OD27:              267 * SEND PROFILE DONE FRAME
OD27:              268 *-----
OD27:58          269 SNDPRD CLI

```

```

0D28:A9 33      270      LDA  #PRDONE      ;LOAD 'PRDONE' OPCODE
0D2A:8D 04 0C   271      STA  DATOPC
0D2D:A9 03      272      LDA  #ERRCNT      ;LOAD ERROR COUNT REG
0D2F:8D 05 0C   273      STA  ERRORS
0D32:58         274      CLI
0D33:         275 *
0D33:A9 00      276  SNDPR1 LDA  #0          ;CLEAR ACK FLAG
0D35:8D 03 0C   277      STA  ACKFLG
0D38:20 5C 0E   278      JSR  SNDFRM      ;SEND PROFILE DONE FRAME
0D3B:         279 *
0D3B:A0 32      280      LDY  #DEL1       ;WAIT FOR ACK
0D3D:A9 10      281  ACKWT1 LDA  #16
0D3F:20 AB FC   282      JSR  WAIT        ; DELAY
0D42:AD 03 0C   283      LDA  ACKFLG      ; CHECK ACK FLAG
0D45:D0 0B      284      BNE  OKACK1
0D47:88         285      DEY
0D48:D0 F3      286      BNE  ACKWT1
0D4A:CE 05 0C   287  ERRCK1 DEC  ERRORS
0D4D:D0 E4      288      BNE  SNDPR1
0D4F:4C F7 0F   289      JMP  ERRPRT
0D52:         290 *
0D52:60         291  OKACK1 RTS
0D53:         292 *=====
0D53:         293 * SEND DATA PACKETS
0D53:         294 *=====
0D53:         295 *
0D53:         296 * SEND LO BYTE DATA
0D53:         297 *
0D53:20 EA 10   298  SNDAT JSR  TDPRT      ;PRINT 'TRANSMITTING DATA'
0D56:56         299      CLI
0D57:A9 50      300      LDA  #OPCLO      ;LOAD BASE OPCODE
0D59:8D 04 0C   301      STA  DATOPC
0D5C:         302 *
0D5C:A9 00      303      LDA  #>STADDL   ;LOAD STARTING ADDRESS
0D5E:85 F9      304      STA  ADDRES
0D60:A9 90      305      LDA  #<STADDL
0D62:85 FA      306      STA  ADDRES+1
0D64:         307 *
0D64:A9 D0      308      LDA  #>BYTCNT   ;LOAD BYTE COUNT
0D66:85 FB      309      STA  BYTES1
0D68:A9 07      310      LDA  #<BYTCNT
0D6A:85 FC      311      STA  BYTES1+1
0D6C:         312 *
0D6C:20 8B 0D   313      JSR  DATOUT      ;GO SEND LO BYTES
0D6F:         314 *
0D6F:         315 * SEND HI BYTE DATA
0D6F:         316 *
0D6F:A9 E0      317      LDA  #OPCHI      ;LOAD BASE OPCODE
0D71:8D 04 0C   318      STA  DATOPC
0D74:         319 *
0D74:A9 00      320      LDA  #>STADDH   ;LOAD STARTING ADDRESS
0D76:85 F9      321      STA  ADDRES
0D78:A9 98      322      LDA  #<STADDH
0D7A:85 FA      323      STA  ADDRES+1
0D7C:         324 *
0D7C:A9 D0      325      LDA  #>BYTCNT   ;LOAD BYTE COUNT

```

```

0D7E:85 FB      326      STA  BYTES1
0D80:A9 07      327      LDA  #<BYTCNT
0D82:85 FC      328      STA  BYTES1+1
0D84:          329 *
0D84:20 8B 0D   330      JSR  DATOUT      ;GO SEND HI BYTES
0D87:          331 *
0D87:20 27 0D   332      JSR  SNDPRD      ;GO SEND 'PROFILE DONE' FRAME
0D8A:          333 *
0D8A:60         334 IDONE  RTS
0D8B:          335 *
0D8B:          336 *-----
0D8B:          337 *  DATA PACKET SENDING ROUTINE
0D8B:          338 *-----
0D8B:          339 *
0D8B:          340 *  CHECK FOR LAST PACKET (SET LAST PACKET FLAG)
0D8B:          341 *
0D8B:A9 00      342 DATOUT  LDA  #0          ;INITIALIZE LAST PACKET FLAG
0D8D:8D 06 0C   343          STA  LSTFLG
0D90:          344 *
0D90:A9 07      345 DTOUT1  LDA  #<PAKLEN  ; CHECK HI BYTE
0D92:C5 FC      346          CMP  BYTES1+1
0D94:F0 05      347          BEQ  CHKLO
0D96:90 1B      348          BCC  FULPAK
0D9B:4C A1 0D   349          JMP  SETFLG
0D9B:A9 D0      350 CHKLO   LDA  #>PAKLEN  ; CHECK LO BYTE
0D9D:C5 FB      351          CMP  BYTES1
0D9F:90 12      352          BCC  FULPAK
0DA1:          353 *
0DA1:A9 01      354 SETFLG  LDA  #1          ;SET LAST PACKET FLAG
0DA3:8D 06 0C   355          STA  LSTFLG
0DA6:          356 *
0DA6:A5 FB      357          LDA  BYTES1      ;SET BYTE COUNT FOR LAST PACKET
0DAB:8D 08 0C   358          STA  COUNT1
0DAB:A5 FC      359          LDA  BYTES1+1
0DAD:8D 09 0C   360          STA  COUNT1+1
0DB0:4C BD 0D   361          JMP  PAKOUT
0DB3:          362 *
0DB3:A9 D0      363 FULPAK  LDA  #>PAKLEN  ;SET BYTE COUNT FOR FULL PACKET
0DB5:8D 08 0C   364          STA  COUNT1
0DBB:A9 07      365          LDA  #<PAKLEN
0DBA:8D 09 0C   366          STA  COUNT1+1
0DBD:          367 *
0DBD:          368 *  SEND ONE PACKET
0DBD:          369 *
0DBD:A9 03      370 PAKOUT  LDA  #ERRCNT     ;INITIALIZE ERROR COUNT REGISTER
0DBF:8D 05 0C   371          STA  ERRORS
0DC2:A9 00      372 PAKOT1  LDA  #0          ;INITIALIZE ACK FLAG
0DC4:8D 03 0C   373          STA  ACKFLG
0DC7:          374 *
0DC7:20 5C 0E   375          JSR  SNDFRM     ;SEND DATA FRAME PART 1
0DCA:20 0C 0E   376          JSR  SNDPK2     ;SEND DATA FRAME PART 2
0DCD:          377 *
0DCD:A0 32      378          LDY  #DEL1     ;WAIT FOR ACK FLAG
0DCF:A9 10      379 ACKWT2  LDA  #16
0DD1:20 AB FC   380          JSR  WAIT      ; DELAY
0DD4:AD 03 0C   381          LDA  ACKFLG     ; CHECK ACKFLAG

```



```

0DD7:D0 0B      382          BNE  DKACK2
0DD9:88         383          DEY
0DDA:D0 F3     384          BNE  ACKWT2
0DDC:          385 *
0DDC:CE 05 0C 386  ERRCK2  DEC  ERRORS
0DDF:D0 E1     387          BNE  PAKUT1
0DE1:4C F7 0F 388          JMP  ERRPRT
0DE4:          389 *
0DE4:          390 * CHECK LAST PACKET FLAG
0DE4:          391 *
0DE4:AD 06 0C 392  DKACK2  LDA  LSTFLG    ;LAST PACKET DONE ?
0DE7:C9 01     393          CMP  #1
0DE9:F0 20     394          BEQ  DONE      ; -YES,GOTO DONE
0DEB:          395 *
0DEB:          396 * DETERMINE NEW STARTING ADDRESS, BYTE COUNT, & OPCODE
0DEB:          397 *
0DEB:18        398  NEWADD  CLC          ;NEW ADDRESS
0DEC:A9 D0     399          LDA  #>PAKLEN ; LO BYTE
0DEE:65 F9     400          ADC  ADDRES
0DF0:85 F9     401          STA  ADDRES
0DF2:          402 *
0DF2:A9 07     403          LDA  #<PAKLEN ; HI BYTE
0DF4:65 FA     404          ADC  ADDRES+1
0DF6:85 FA     405          STA  ADDRES+1
0DF8:          406 *
0DF8:38        407          SEC          ;NEW BYTE COUNT
0DF9:A5 FB     408          LDA  BYTES1  ; LO BYTE
0DFB:E9 D0     409          SBC  #>PAKLEN
0DFD:85 FB     410          STA  BYTES1
0DFE:          411 *
0DFE:A5 FC     412          LDA  BYTES1+1 ; HI BYTE
0E01:E9 07     413          SBC  #<PAKLEN
0E03:85 FC     414          STA  BYTES1+1
0E05:          415 *
0E05:EE 04 0C 416          INC  DATOPC   ;NEW OPCODE
0E08:4C 90 0D 417          JMP  DTOUT1   ;SEND NEXT PACKET
0E0B:          418 *
0E0B:60        419  DONE    RTS          ;DATA BLOCK SENDING COMPLETE
0E0C:          420 *
0E0C:          421 *-----
0E0C:          422 * DATA PACKET PART 2
0E0C:          423 * SENDING ROUTINE
0E0C:          424 *-----
0E0C:A5 FA     425  SNDPK2  LDA  ADDRES+1 ;SAVE HI BYTE OF ADDRESS
0E0E:8D 0C 0C 426          STA  SAVADD
0E11:          427 *
0E11:A9 90     428          LDA  #DLE
0E13:20 99 0E 429          JSR  SNDBYT   ;SEND 'DLE' CHARACTER
0E16:A9 00     430          LDA  #0       ;CLEAR XMIT CHECKSUM
0E18:8D 14 0C 431          STA  XCSUM
0E1B:8D 15 0C 432          STA  XCSUM+1
0E1E:          433 *
0E1E:A9 81     434          LDA  #CTX
0E20:20 8B 0E 435          JSR  UPDTCK   ;UPDATE XMIT CHECKSUM & SEND 'CTX'
0E23:          436 *
0E23:AE 09 0C 437          LDX  COUNT1+1

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0E26:A0 00      438 SENDPG LDY #0
0E28:E0 00      439          CPX #0          ;LAST PAGE TO BE SENT ?
0E2A:F0 11      440          BEQ LASTPG          ; -YES,SEND LAST PAGE
0E2C:10 08      441          BPL FULLPG          ; -NO,SEND FULL PAGE
0E2E:AD 0C 0C   442          LDA SAVADD          ; -PACKET COMPLETED
0E31:B5 FA      443          STA ADDRESS+1      ; RESTORE INITIAL ADDRESS
0E33:4C 74 0E   444          JMP ENDER           ; SEND PACKET ENDER
0E36:          445 *
0E38:A9 00      446 FULLPG LDA #0          ;SET BYTE COUNT FOR FULL PAGE
0E3B:85 FF      447          STA TLBTCT
0E3A:4C 46 0E   448          JMP SNDIT1
0E3D:          449 *
0E3D:AD 0B 0C   450 LASTPG LDA COUNT1      ;SET BYTE COUNT FOR LAST PAGE
0E40:85 FF      451          STA TLBTCT
0E42:          452 *
0E42:C4 FF      453 SENDIT CPY TLBTCT      ;LAST BYTE OF PAGE SENT ?
0E44:F0 10      454          BEQ NEXTPG          ; -YES,SET UP FOR NEXT PAGE
0E46:B1 F9      455 SNDIT1 LDA (ADDRESS),Y ; -NO,SEND ANOTHER
0E48:20 8B 0E   456          JSR UPDTCK
0E4B:C9 90      457          CMP #DLE           ;DATA = 'DLE' BYTE ?
0E4D:D0 03      458          BNE SKDBL          ; -NO,SKIP DOUBLE 'DLE'
0E4F:20 8B 0E   459          JSR UPDTCK          ; -YES,SEND SECOND 'DLE'
0E52:C8          460 SKDBL INY
0E53:4C 42 0E   461          JMP SENDIT          ;GO TO SEND ANOTHER BYTE
0E56:          462 *
0E56:CA          463 NEXTPG DEX
0E57:E6 FA      464          INC ADDRESS+1      ;SET ADDRESS FOR NEXT PAGE
0E59:4C 26 0E   465          JMP SENDPG
0E5C:          466 *
0E5C:          467 *-----
0E5C:          468 *  HEADER PACKET SENDING ROUTINE
0E5C:          469 *-----
0E5C:A9 90      470 SNDFRM LDA #DLE
0E5E:20 99 0E   471          JSR SNDBYT          ;SEND 'DLE' CHARACTER
0E61:A9 00      472          LDA #0             ;CLEAR XMIT CHECKSUM
0E63:8D 14 0C   473          STA XCSUM
0E66:8D 15 0C   474          STA XCSUM+1
0E69:          475 *
0E69:A9 83      476          LDA #STX
0E6B:20 8B 0E   477          JSR UPDTCK          ;UPDATE XMIT CHECKSUM & SEND 'STX'
0E6E:          478 *
0E6E:AD 04 0C   479          LDA DATOPC
0E71:20 8B 0E   480          JSR UPDTCK          ;UPDATE XMIT CHECKSUM & SEND OPCODE
0E74:          481 *
0E74:A9 90      482 ENDER LDA #DLE
0E76:20 8B 0E   483          JSR UPDTCK          ;UPDATE XMIT CHECKSUM & SEND 'DLE'
0E79:          484 *
0E79:A9 82      485          LDA #ETX
0E7B:20 99 0E   486          JSR SNDBYT          ;SEND 'ETX' CHARACTER
0E7E:          487 *
0E7E:AD 14 0C   488 SNDCHK LDA XCSUM          ;SEND XMIT CHECKSUM
0E81:20 99 0E   489          JSR SNDBYT          ; LO BYTE
0E84:AD 15 0C   490          LDA XCSUM+1
0E87:20 99 0E   491          JSR SNDBYT          ; HI BYTE
0E8A:          492 *
0E8A:60          493          RTS

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0E8B:      494 *
0E8B:      495 *-----
0E8B:      496 *  UPDATE CHECKSUM & SEND BYTE
0E8B:      497 *          ROUTINES
0E8B:      498 *-----
0E8B:48    499 UPDTCK PHA          ;SAVE BYTE
0E8C:18    500          CLC
0E8D:6D 14 0C 501          ADC XCSUM  ;UPDATE CHECKSUM
0E90:90 03    502          BCC SKUPXC
0E92:EE 15 0C 503          INC XCSUM+1
0E95:8D 14 0C 504 SKUPXC STA XCSUM
0E98:68    505          PLA          ;RESTORE BYTE
0E99:      506 *
0E99:48    507 SNDBYT PHA          ;SAVE BYTE
0E9A:AD A0 C0 508 LOOP1 LDA CSR      ;CHECK ACIA STATUS
0E9D:29 02    509          AND #2
0E9F:F0 F9    510          BEQ LOOP1
0EA1:      511 *
0EA1:68    512          PLA          ;RESTORE BYTE
0EA2:8D A1 C0 513          STA XRDR  ;SEND BYTE
0EA5:60    514          RTS
0EA6:      515 *
0EA6:      516 *****
0EA6:      517 *
0EA6:      518 * DATA RUN
0EA6:      519 *
0EA6:      520 *****
0EA6:      521 *
0EA6:20 D0 10 522 DATRUN JSR TKPPRT
0EA9:AD 01 0C 523          LDA MSHOTS ;LOAD SHOT COUNTER TSHOT
0EAC:8D 12 0C 524          STA TSHOT
0EAF:4D 02 0C 525          LDA MSHOTS+1
0EB2:8D 13 0C 526          STA TSHOT+1
0EB5:      527 *
0EB5:A9 00    528          LDA #0      ;CHECK LO BYTE SHOT COUNT
0EB7:CD 12 0C 529          CMP TSHOT  ; = 0 ?
0EBA:D0 03    530          BNE IDMAC  ; -NO,GO ON
0EBC:CE 13 0C 531          DEC TSHOT+1 ; -YES,DEC HI BYTE SHOT COUNT
0EBF:      532 *-----
0EBF:      533 * INITIALIZE DMAC
0EBF:      534 *-----
0EBF:A9 60    535 IDMAC LDA #<BUFADD ;LOAD ADDRESS HI BYTE
0EC1:8D 04 C4 536          STA DMAREG+4 ; CHANNEL 1
0EC4:8D 0C C4 537          STA DMAREG+12 ; CHANNEL 3
0EC7:A9 00    538          LDA #>BUFADD ;LOAD ADDRESS LO BYTE
0EC9:8D 05 C4 539          STA DMAREG+5 ; CHANNEL 1
0ECC:8D 0D C4 540          STA DMAREG+13 ; CHANNEL 3
0ECF:A9 07    541          LDA #07      ;LOAD COUNT HI BYTE
0ED1:8D 06 C4 542          STA DMAREG+6 ; CHANNEL 1
0ED4:8D 0E C4 543          STA DMAREG+14 ; CHANNEL 3
0ED7:A9 D1    544          LDA #D1      ;LOAD COUNT LO BYTE
0ED9:8D 07 C4 545          STA DMAREG+7 ; CHANNEL 1
0EDC:8D 0F C4 546          STA DMAREG+15 ; CHANNEL 3
0EDF:A9 02    547          LDA #2      ;LOAD CHANNEL CONTROL
0EE1:8D 11 C4 548          STA DMAREG+17
0EE4:A9 0C    549          LDA #0      ;LOAD INTERRUPT CONTROL

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0EE6:8D 15 C4 550      STA  DMAREG+21
0EE9:A9 03 551      LDA  #3          ;LOAD DATA CHAIN
0EEB:8D 16 C4 552      STA  DMAREG+22
0EEE:A9 02 553      LDA  #2          ;LOAD PRIORITY CONTROL
0EF0:8D 14 C4 554      STA  DMAREG+20
0EF3:                555 *-----
0EF3:                556 *  INIT MAINFRAME MEMORY
0EF3:                557 *-----
0EF3:A9 00 558      LDA  #>STADDL  ;LOAD STARTING ADDRESS
0EF5:85 FD 559      STA  PRTADD
0EF7:A9 90 560      LDA  #<STADDL
0EF9:85 FE 561      STA  PRTADD+1
0EFB:                562 *
0EFB:A2 10 563      LDX  #16         ;LOAD X WITH 16 (PAGES)
0EFD:A9 00 564      LDA  #0         ;CLEAR A & Y
0EFF:AB 565      TAY
0F00:                566 *
0F00:91 FD 567 CLRLP  STA  (PRTADD),Y ;CLEAR MEMORY
0F02:C8 568      INY
0F03:D0 FB 569      BNE  CLRLP
0F05:E6 FE 570      INC  PRTADD+1
0F07:CA 571      DEX
0F08:D0 F6 572      BNE  CLRLP
0FOA:                573 *-----
0FOA:                574 *  FIRE LASER & CHECK FOR
0FOA:                575 *      DMA DONE
0FOA:                576 *-----
0FOA:8D C1 C0 577 TRIG1  STA  TRIG          ;FIRE LASER
0F0D:EA 578      NOP
0F0E:EA 579      NOP
0F0F:EA 580      NOP
0F10:A9 04 581      LDA  #4          ;'WAIT' DURING DMA
0F12:20 AB FC 582      JSR  WAIT
0F15:2C 11 C4 583      BIT  DMAREG+17 ;DMA BIT SET ?
0F18:30 0C 584      BHI  INTGRT    ; -YES,GOTO INTGRT
0F1A:8D C4 C0 585      STA  SLPRST    ; -NO,RESET SLIPP INTERFACE
0F1D:20 3A 10 586      JSR  TRGPRT    ; PRINT ERROR MESSAGE
0F20:20 D0 10 587      JSR  TKPPRT
0F23:4C 0A 0F 588      JMP  TRIG1
0F26:                589 *-----
0F26:                590 *  INTEGRATION
0F26:                591 *-----
0F26:A0 00 592 INTGRT  LDY  #0          ;INIT Y
0F28:18 593 ADD0    CLC          ;FIRST PAGE ADDITION
0F29:B9 00 60 594      LDA  BUFADD,Y  ; LOW BYTE ADD
0F2C:79 00 90 595      ADC  STADDL,Y
0F2F:99 00 90 596      STA  STADDL,Y
0F32:A9 00 597      LDA  #0          ; HIGH BYTE ADD
0F34:79 00 98 598      ADC  STADDH,Y
0F37:99 00 98 599      STA  STADDH,Y
0F3A:18 600 ADD1    CLC          ;SECOND PAGE ADDITIONS
0F3B:B9 00 61 601      LDA  BUFADD+#100,Y
0F3E:79 00 91 602      ADC  STADDL+#100,Y
0F41:99 00 91 603      STA  STADDL+#100,Y
0F44:A9 00 604      LDA  #0
0F46:79 00 99 605      ADC  STADDH+#100,Y

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OF49:99 00 99 606 STA STADDH+$100,Y
OF4C:18 607 ADD2 CLC ;THIRD PAGE ADDITIONS
OF4D:B9 00 62 608 LDA BUFADD+$200,Y
OF50:79 00 92 609 ADC STADDL+$200,Y
OF53:99 00 92 610 STA STADDL+$200,Y
OF56:A9 00 611 LDA #0
OF58:79 00 9A 612 ADC STADDH+$200,Y
OF5B:99 00 9A 613 STA STADDH+$200,Y
OF5E:18 614 ADD3 CLC ;FORTH PAGE ADDITIONS
OF5F:B9 00 63 615 LDA BUFADD+$300,Y
OF62:79 00 93 616 ADC STADDL+$300,Y
OF65:99 00 93 617 STA STADDL+$300,Y
OF68:A9 00 618 LDA #0
OF6A:79 00 9B 619 ADC STADDH+$300,Y
OF6D:99 00 9B 620 STA STADDH+$300,Y
OF70:18 621 ADD4 CLC ;FIFTH PAGE ADDITIONS
OF71:B9 00 64 622 LDA BUFADD+$400,Y
OF74:79 00 94 623 ADC STADDL+$400,Y
OF77:99 00 94 624 STA STADDL+$400,Y
OF7A:A9 00 625 LDA #0
OF7C:79 00 9C 626 ADC STADDH+$400,Y
OF7F:99 00 9C 627 STA STADDH+$400,Y
OF82:18 628 ADD5 CLC ;SIXTH PAGE ADDITIONS
OF83:B9 00 65 629 LDA BUFADD+$500,Y
OF86:79 00 95 630 ADC STADDL+$500,Y
OF89:99 00 95 631 STA STADDL+$500,Y
OF8C:A9 00 632 LDA #0
OF8E:79 00 9D 633 ADC STADDH+$500,Y
OF91:99 00 9D 634 STA STADDH+$500,Y
OF94:18 635 ADD6 CLC ;SEVENTH PAGE ADDITIONS
OF95:B9 00 66 636 LDA BUFADD+$600,Y
OF98:79 00 96 637 ADC STADDL+$600,Y
OF9B:99 00 96 638 STA STADDL+$600,Y
OF9E:A9 00 639 LDA #0
OFA0:79 00 9E 640 ADC STADDH+$600,Y
OFA3:99 00 9E 641 STA STADDH+$600,Y
OFA6:18 642 ADD7 CLC ;EIGHTH PAGE ADDITIONS
OFA7:B9 00 67 643 LDA BUFADD+$700,Y
OFAA:79 00 97 644 ADC STADDL+$700,Y
OFAD:99 00 97 645 STA STADDL+$700,Y
OFB0:A9 00 646 LDA #0
OFB2:79 00 9F 647 ADC STADDH+$700,Y
OFB5:99 00 9F 648 STA STADDH+$700,Y
OFB8: 649 *
OFB8:C8 650 INY
OFB9:F0 03 651 BEQ NXTSHT
OFBB:4C 28 0F 652 JMP ADD0
OFBE: 653 *
OFBE: 654 *-----
OFBE: 655 * CHECK SHOT COUNTER
OFBE: 656 * SEND PROFILE
OFBE: 657 *-----
OFBE:CE 12 0C 658 NXTSHT DEC TSHOT ;CHECK SHOT COUNTER
OFC1:D0 05 659 BNE SKUPTS
OFC3:CE 13 0C 660 DEC TSHOT+1
OFC6:30 0E 661 BMI PDONE

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OFCB:          662 *
OFCB:A0 06     663 SKUPTS  LDY #6
OFCB:AD 00 0C 664 RPLOOP  LDA REPNUM    ;LASER REP DELAY
OFCB:20 AB FC  665          JSR WAIT
OFCB:8B        666          DEY
OFCB:D0 F7     667          BNE RPLOOP
OFCB:4C 0A 0F 668          JMP TRIG1    ;GO FIRE ANOTHER SHOT
OFCB:         669 *
OFCB:A9 BC     670 PDONE   LDA #>STPAK1 ;RESET INPUT BYTE VECTOR
OFCB:8D 10 0C 671          STA STATE
OFCB:A9 0C     672          LDA #<STPAK1
OFCB:8D 11 0C 673          STA STATE+1
OFCB:         674 *
OFCB:20 53 0D 675          JSR SNDDAT    ;SEND DATA
OFCB:20 B3 10 676          JSR IDLPRT    ;PRINT 'IDLE'
OFCB:4C 89 0C 677          JMP STPAK
OFCB:         678 *
OFCB:         679 *****
OFCB:         680 *
OFCB:         681 * PRINTING ROUTINES
OFCB:         682 *
OFCB:         683 *****
OFCB:         684 *
OFCB:         685 * PRINT SUBROUTINE
OFCB:         686 *
OFCB:A0 00     687 PRINT   LDY #0
OFCB:B1 FD     688 PRINT1  LDA (PRTADD),Y
OFCB:F0 07     689          BEQ ENDP
OFCB:20 F0 FD 690          JSR COUT1
OFCB:CB        691          INY
OFCB:4C EB 0F 692          JMP PRINT1
OFCB:60        693 ENDP   RTS
OFCB:         694 *-----
OFCB:         695 * DATA TRANSMISSION ERROR MESSAGE
OFCB:         696 *-----
OFCB:20 5B FC 697 ERRPRT  JSR HOME    ;CLEAR SCREEN
OFCB:         698 *
OFCB:A9 0A     699          LDA #10    ;SET VERTICAL TAB
OFCB:85 25     700          STA CV
OFCB:20 22 FC 701          JSR VTAB
OFCB:         702 *
OFCB:A9 09     703          LDA #9    ;SET HORIZONTAL TAB
OFCB:85 24     704          STA CH
OFCB:20 B0 FE 705          JSR SETINV  ;SET INVERSE SCREEN
OFCB:A9 57     706          LDA #ERRMSG
OFCB:85 FD     707          STA PRTADD
OFCB:A9 11     708          LDA #<ERRMSG
OFCB:85 FE     709          STA PRTADD+1
OFCB:20 E9 0F 710          JSR PRINT    ;PRINT ERROR MESSAGE
OFCB:         711 *
OFCB:A9 0A     712          LDA #10    ;SET HORIZONTAL TAB
OFCB:85 24     713          STA CH
OFCB:20 84 FE 714          JSR SETNRM  ;SET NORMAL SCREEN
OFCB:A9 72     715          LDA #>TRYAGN
OFCB:85 FD     716          STA PRTADD
OFCB:A9 11     717          LDA #<TRYAGN

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1020:85 FE      718      STA  PRTADD+1
1022:20 E9 OF  719      JSR  PRINT      ;PRINT TRY AGAIN
1025:          720 *
1025:20 0C FD  721      JSR  RDKEY      ;GET RESPONSE
1028:C9 D9     722      CMP  #'Y
102A:D0 06     723      BNE  NTAGN
102C:20 58 FC  724      JSR  HOME
102F:4C 53 0D  725      JMP  SDDAT
1032:20 58 FC  726 NTAGN JSR  HOME
1035:68        727      PLA          ;GET OFF STACK
1036:68        728      PLA
1037:4C 8A 0D  729      JMP  DDONE
103A:          730 *
103A:          731 *-----
103A:          732 *  LASER TRIGGER ERROR MESSAGE
103A:          733 *-----
103A:20 58 FC  734 TRGPRT JSR  HOME
103D:A9 0A     735      LDA  #10
103F:85 25     736      STA  CV
1041:20 22 FC  737      JSR  VTAB
1044:          738 *
1044:A9 09     739      LDA  #9
1046:85 24     740      STA  CH
1048:20 80 FE  741      JSR  SETINV
1048:A9 85     742      LDA  #>TGMSG1
104D:85 FD     743      STA  PRTADD
104F:A9 11     744      LDA  #<TGMSG1
1051:85 FE     745      STA  PRTADD+1
1053:20 E9 OF  746      JSR  PRINT
1056:          747 *
1056:A9 07     748      LDA  #7
1058:85 24     749      STA  CH
105A:20 84 FE  750      JSR  SETNRM
105D:A9 9F     751      LDA  #>TGMSG2
105F:85 FD     752      STA  PRTADD
1061:A9 11     753      LDA  #<TGMSG2
1063:85 FE     754      STA  PRTADD+1
1065:20 E9 OF  755      JSR  PRINT
1068:          756 *
1068:20 0C FD  757      JSR  RDKEY
106B:60        758      RTS
106C:          759 *
106C:          760 *-----
106C:          761 *  HEADER MESSAGE
106C:          762 *-----
106C:20 58 FC  763 HEDPRT JSR  HOME
106F:A9 06     764      LDA  #6
1071:85 25     765      STA  CV
1073:20 22 FC  766      JSR  VTAB
1076:          767 *
1076:A9 0D     768      LDA  #13
1078:85 24     769      STA  CH
107A:A9 04     770      LDA  #>HDMSG1
107C:85 FD     771      STA  PRTADD
107E:A9 11     772      LDA  #<HDMSG1
1080:85 FE     773      STA  PRTADD+1

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1082:20 E9 0F 774      JSR PRINT
1085:                775 *
1085:A9 08 776      LDA #8
1087:85 24 777      STA CH
1089:A9 15 778      LDA #>HDMSG2
108B:85 FD 779      STA PRTADD
108D:A9 11 780      LDA #<HDMSG2
108F:85 FE 781      STA PRTADD+1
1091:20 E9 0F 782      JSR PRINT
1094:                783 *
1094:A9 0F 784      LDA #15
1096:85 24 785      STA CH
1098:A9 31 786      LDA #>HDMSG3
109A:85 FD 787      STA PRTADD
109C:A9 11 788      LDA #<HDMSG3
109E:85 FE 789      STA PRTADD+1
10A0:20 E9 0F 790      JSR PRINT
10A3:                791 *
10A3:A9 08 792      LDA #8
10A5:85 24 793      STA CH
10A7:A9 3E 794      LDA #>HDMSG4
10A9:85 FD 795      STA PRTADD
10AB:A9 11 796      LDA #<HDMSG4
10AD:85 FE 797      STA PRTADD+1
10AF:20 E9 0F 798      JSR PRINT
10B2:                799 *
10B2:20 0C FD 800      JSR RDKEY
10B5:60 801          RTS
10B6:                802 *-----
10B6:                803 * STATUS MESSAGES
10B6:                804 *-----
10B6:                805 *
10B6:                806 * IDLE MESSAGE
10B6:                807 *
10B6:20 58 FC 808 IDLPRT JSR HOME
10B9:A9 0A 809      LDA #10
10BB:85 25 810      STA CV
10BD:20 22 FC 811      JSR VTAB
10C0:                812 *
10C0:A9 10 813      LDA #16
10C2:85 24 814      STA CH
10C4:A9 BA 815      LDA #>IDLMSG
10C6:85 FD 816      STA PRTADD
10C8:A9 11 817      LDA #<IDLMSG
10CA:85 FE 818      STA PRTADD+1
10CC:20 E9 0F 819      JSR PRINT
10CF:60 820          RTS
10D0:                821 *
10D0:                822 * TAKING PROFILE MESSAGE
10D0:                823 *
10D0:20 58 FC 824 TKPPRT JSR HOME
10D3:A9 0A 825      LDA #10
10D5:85 25 826      STA CV
10D7:20 22 FC 827      JSR VTAB
10DA:                828 *
10DA:A9 0A 829      LDA #10

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10DC:85 24      830          STA  CH
10DE:A9 C3      831          LDA  #>TKPMSG
10E0:85 FD      832          STA  PRTADD
10E2:A9 11      833          LDA  #<TKPMSG
10E4:85 FE      834          STA  PRTADD+1
10E6:20 E9 0F   835          JSR  PRINT
10E9:60         836          RTS
10EA:          837 *
10EA:          838 * TRANSMITTING DATA MESSAGE
10EA:          839 *
10EA:20 5B FC   840 TDFRT   JSR  HOME
10ED:A9 0A      841          LDA  #10
10EF:85 25      842          STA  CV
10F1:20 22 FC   843          JSR  VTAB
10F4:          844 *
10F4:A9 0A      845          LDA  #10
10F6:85 24      846          STA  CH
10F8:A9 D6      847          LDA  #>TDMSG
10FA:85 FD      848          STA  PRTADD
10FC:A9 11      849          LDA  #<TDMSG+1
10FE:85 FE      850          STA  PRTADD+1
1100:20 E9 0F   851          JSR  PRINT
1103:60         852          RTS
1104:          853 *
1104:          854 *-----
1104:          855 * DATA
1104:          856 *-----
1104:C1 D0 D0   857 HDMSG1  ASC  'APPLE      SOFTWARE'
1107:CC C5 A0
110A:D3 CF C6
110D:D4 D7 C1
1110:D2 C5
1112:8D 8D 00   858          DFB  CR,CR,0
1115:D3 CF C4   859 HDMSG2  ASC  'SODIUM    LIDAR PREPROCESSOR'
1118:C9 D5 CD
111B:A0 CC C9
111E:C4 C1 D2
1121:A0 D0 D2
1124:C5 D0 D2
1127:CF C3 C5
112A:D3 D3 CF
112D:D2
112E:8D 8D 00   860          DFB  CR,CR,0
1131:B2 B0 AD   861 HDMSG3  ASC  '20-FEB-83'
1134:C6 C5 C2
1137:AD B8 B3
113A:8D 8D 8D   862          DFB  CR,CR,CR,0
113D:00
113E:BC A0 D0   863 HDMSG4  ASC  '<      PRESS A KEY TO BEGIN >'
1141:D2 C5 D3
1144:D3 A0 C1
1147:A0 CB C5
114A:D9 A0 D4
114D:CF A0 C2
1150:C5 C7 C9
1153:CE A0 BE

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1156:00	864	DFB	0	
1157:C4 C1 D4	865 ERRMSG	ASC	"DATA	TRANSMISSION ERROR"
115A:C1 A0 D4				
115D:D2 C1 CE				
1160:D3 CD C9				
1163:D3 D3 C9				
1166:CF CE A0				
1169:C5 D2 D2				
116C:CF D2				
116E:8D 8D 8D	866	DFB	CR,CR,CR,0	
1171:00				
1172:D4 D2 D9	867 TRYAGN	ASC	"TRY	SENDING AGAIN?"
1175:A0 D3 C5				
1178:CE C4 C9				
117B:CE C7 A0				
117E:C1 C7 C1				
1181:C9 CE BF				
1184:00	868	DFB	0	
1185:CC C1 D3	869 TGMSG1	ASC	"LASER	TRIGGER ERROR"
1188:C5 D2 A0				
118B:D4 D2 C9				
118E:C7 C7 C5				
1191:D2 A0 D3				
1194:C3 D2 C5				
1197:D7 AD D5				
119A:D0				
119B:8D 8D 8D	870	DFB	CR,CR,CR,0	
119E:00				
119F:BC D0 D2	871 TGMSG2	ASC	"<PRESS	A KEY TO TRY AGAIN>"
11A2:C5 D3 D3				
11A5:A0 C1 A0				
11A8:CB C5 D9				
11AB:A0 D4 CF				
11AE:A0 D4 D2				
11B1:D9 A0 C1				
11B4:C7 C1 C9				
11B7:CE BE				
11B9:00	872	DFB	0	
11BA:BC A0 C9	873 IDLMSG	ASC	"<	IDLE >"
11BD:C4 CC C5				
11C0:A0 BE				
11C2:00	874	DFB	0	
11C3:BC A0 D4	875 TKPMMSG	ASC	"<	TAKING PROFILE >"
11C6:C1 CB C9				
11C9:CE C7 A0				
11CC:D0 D2 CF				
11CF:C6 C9 CC				
11D2:C5 A0 BE				
11D5:00	876	DFB	0	
11D6:BC A0 D4	877 TDMSG	ASC	"<	TRANSMITTING DATA >"
11D9:D2 C1 CE				
11DC:D3 CD C9				
11DF:D4 D4 C9				
11E2:CE C7 A0				
11E5:C4 C1 D4				
11E8:C1 A0 BE				
11EB:00	878	DFB	0	

0C03 ACKFLG	0CE6 ACKN	0D3D ACKWT1	0DCF ACKWT2
34 ACK	0F28 ADD0	?0F3A ADD1	?0F4C ADD2
?0F5E ADD3	?0F70 ADD4	?0F82 ADD5	?0F94 ADD6
?0FA6 ADD7	F9 ADDRES	6000 BUFADD	07D0 BYTCNT
FB BYTES1	24 CH	0CDC CHKDTR	0D9B CHKLO
0F00 CLRLP	32 COM	45 COMEND	0CEE COMN
0C08 COUNT1	FDF0 COUT1	BD CR	00A0 CSR
B1 CTX	25 CV	0C04 DATOPC	0DDB DATOUT
0EA6 DATRUN	0DBA DOONE	32 DEL1	97 DLE
C400 DMAREG	0E0B DONE	31 DRUN	0D90 DTOUT1
0E74 ENDER	0FF6 ENDP	?0D4A ERRCK1	?0DDC ERRCK2
03 ERRCNT	1157 ERRMSG	0C05 ERRORS	0FF7 ERRPRT
B2 ETX	0C36 FULLPG	0DB3 FULPAK	0C6B SETB1
1104 HDMSG1	1115 HDMSG2	1131 HDMSG3	113E HDMSG4
106C HEDPRT	FC5B HOME	11BA IDLMSG	10B6 IDLPRT
0EBF IDMAC	0F26 INTGRT	03FE INTV	0C5E IOINT
FF3F IOREST	FF4A IOSAVE	C010 KBDSTB	FD1B KEYIN
38 KSW	0E3D LASTPG	0E9A LOOP1	0C06 LSTFLG
0C01 MSHOTS	?0DEB NEWADD	0E56 NEXTPG	1032 NTAGN
0FBE NXTSHT	0D52 OKACK1	0DE4 OKACK2	0C07 OPCDE
E0 OPCHI	50 OPCLO	07D0 PAKLEN	0DC2 FAKOT1
0DBD PAKOUT	0FD6 PDONE	33 PRDONE	0FE9 PRINT
0FEB PRINT1	FD PRTADD	0C0A RCSUM	FDOC RBKEY
0C00 REPNUM	0FCA RPLDOP	?C0C SAVADD	0C0E SAVSUM
0E42 SENDIT	0E26 SENDPG	0DA1 SETFLG	FE80 SETINV
FE84 SETNRM	0E52 SKDBL	0C74 SKUPRC	0FC8 SKUPTS
0E95 SKUPXC	C0C0 SLPID	C0C4 SLPRST	0D1E SNDACK
0E99 SNDBYT	?0E7E SNDCHK	0D53 SNDDAT	0E5C SNDFRM
0E46 SNDIT1	0E0C SNDPK2	0D33 SNDPK1	0D27 SNDFRD
9800 STADDH	?000 STADDL	0C10 STATE	0C87 STPAK
0C8C STPAK1	87 STX	11D6 TDMSG	10EA TDFRT
1185 TGMSG1	119F TGMSG2	11C3 TKPMSG	10D0 TKFPRT
FF TLBTCT	103A TRGPRT	C0C1 TRIG	0F0A TRIG1
1172 TRYAGN	0C12 TSHOT	0E82 UPDTCK	0C45 VERCHK
?0CAB VERIFY	FC22 VTAB	FCAB WAIT	0C5B WLOOP
0C14 XCSUM	00A1 XRDR		

III.2 FZZ

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```
C *****
C *
C *   SODIUM LIDAR PROGRAM
C *   11/16/82
C *   D.VOELZ
C *
C *****
C THIS PROGRAM ( ALONG WITH ITS ASSOCIATED SUBROUTINES )
C IS DESIGNED TO CONTROL THE SODIUM LIDAR EXPERIMENT
C AT THE UNIVERSITY OF ILLINOIS.
C THE PROGRAM DISPLAYS A MAIN MENU. CHOOSING ONE OF THE
C OPTIONS DISPLAYED CAUSES THE PROGRAM TO GO TO ONE OF
C THE ASSOCIATED SUBROUTINES.
C
C MAIN SUBROUTINES CALLED IN THE PROGRAM FOLLOW:
C   EXPPAR - EXPERIMENT PARAMETERS
C   CSTTUS - CURRENT STATUS
C   LAALN - LOW-ALTITUDE ALIGNMENT ROUTINE
C   ALNRTN - SODIUM ALIGNMENT ROUTINE
C   DATRUN - DATA RUN
C   EXMPRF - EXAMINE PROFILE ON DISK
C   MOUT - HEX DUMP OF THE ARRAY LDATA
C
C OTHER SUBROUTINES USED:
C   CLRSCN - CLEAR TERMINAL SCREEN
C   BAKSCN - NORMAL (BACKGROUND) SCREEN
C   FORSCN - HIGHLIGHT (FOREGROUND) SCREEN
C   DATE - GET PRESENT DATE
C   TIME - GET PRESENT TIME
C
C A DESCRIPTION OF SOME OF THE VARIABLES USED IN THIS PROGRAM
C AND ITS SUBROUTINES FOLLOWS:
C   BINS - # BINS OF INTEREST
C   BSATF - BASE ALTITUDE (FT)
C   B60 - 60 KM BIN POINTER
C   CLA - COLUMN ABUN'D RATIO
C   CSET - CURRENT SET
C   FNAME - FILE NAME ARRAY
C   HBI - HI BIN OF INTEREST
C   HRI - HI RANGE OF INTEREST
C   INTSIZ - FILE BLOCK SIZE
C   K60 - PHOTONS 60-80 KM
C   K100 - PHOTONS 100-120 KM
C   LDATA - DATA ARRAY
C   LREP - DATRUN REP RATE
C   MSHOTS - SHOTS/PROF (SENT)
C   REANG - ELEVA'N ANGLE (RAD)
C   REPNUM - REP NUMBER
C   REPR4 - ALNRTN REP RATE
C   SETS - # OF SETS
C   SHOTSP - DATRUN SHOTS/PROF
C   SHOTS4 - ALNRTN SHOTS/PROF
C   TSGP - TOTAL SIGNAL PHOTONS
C   BSAT - BASE ALTITUDE (KM)
C   B30 - 30 KM BIN POINTER
C   C - SPEED OF LIGHT
C   CPROF - CURRENT PROFILE
C   EANG - ELEVATION ANGLE (DEGREES)
C   GATTIM - RECEIVER GATE TIME
C   HDRB - # HEADER BYTES IN DATA FILE
C   IDATE - DATE ARRAY
C   ITIME - TIME ARRAY
C   K80 - PHOTONS 80-100 KM
C   LBI - LO BIN OF INTEREST
C   LRI - LO RANGE OF INTEREST
C   LSET - PREVIOUS SET #
C   PDEL - INTER-PROFILE DELAY
C   RECSIZ - FILE RECORD SIZE
C   REPR3 - LAALN REP RATE
C   RG - RANGE GATE (BIN SIZE)
C   SGP - SIGNAL PHOTONS
C   SHOTS3 - LAALN SHOTS/PROF
C   S20 - # BINS IN 20 KM
```

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```

C
C  FLAGS:
C  ERRFLG - SET WHEN A LSI11-APPLE TRANSMISSION ERROR OCCURS
C  DFLAG - SET WHEN A COMPLETED PROFILE IS RECEIVED
C  RUNFLG - DESIGNATES WHICH SUBROUTINE (LAALN,ALRTN,DATRUN) IS
C           BEING RUN
0001      INTEGER SETS,PROFS,SHOTSP,CSET,CPROF,LSET,LPROF,HBI,LBI
> ,SHOTS3,SHOTS4,INTSIZ,RECSIZ,B30,B60,S20,K30,K60,K80,K100
> ,SGP,TSGP,PDEL
0002      REAL LREP,LRI,HRI,EANG,BSAT,REPR3,REPR4,PI,C,GATTIM,RG
> ,CLA,REANG,BSATF
0003      LOGICAL*1 IDATE(9),ITIME(8)
0004      BYTE FNAME(15)
C
0005      COMMON /DATTIM/ IDATE,ITIME
0006      COMMON /SETS/ SETS,PROFS,SHOTSP
0007      COMMON /LREPS/ LREP,LRI,HRI,LBI,HBI,BSAT,BSATF,EANG
> ,REANG,PDEL
0008      COMMON /STATS/ CSET,CPROF,LSET,LPROF
0009      COMMON /CALCS/ K30,K60,K80,K100,SGP,TSGP,CLA
0010      COMMON /ALN/ REPR4,SHOTS4
0011      COMMON /LAAN/REPR3,SHOTS3
0012      COMMON /DISK/ INTSIZ,RECSIZ,FNAME
0013      COMMON/PTERS/ B30,B60,S20
0014      COMMON /CONST/ PI,C,GATTIM,RG
C
C  VARIABLE DEFAULT VALUES
C
0015      SETS = 20
0016      PROFS = 10
0017      SHOTSP = 100
0018      LREP = 10.0
0019      PDEL=0
0020      EANG = 90.
0021      LRI = 0.075
0022      HRI = 149.925
0023      BSAT = 0.
0024      BSATF = 0.
0025      LBI = 1
0026      HBI = 1000
0027      CSET = 1
0028      CPROF = 1
0029      LSET = 0
0030      LPROF = 0
0031      K30 = 0
0032      K60 = 0
0033      K80 = 0
0034      K100 = 0
0035      SGP = 0
0036      TSGP = 0
0037      CLA = 0.
0038      REPR3=10.
0039      SHOTS3=100

```

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```
0040      REPR4=10.
0041      SHOTS4=100
0042      PI=3.1415927
0043      C=3.0E5
0044      GATTIM=1.0E-6
0045      RG=(GATTIM*C)/2.
0046      REANG=PI/2.
0047      DATA FNAME/'D','Y','O',' ','S','E','T',0,0,0,' ','D','A'
           >,'T',0/
```

```
C-----
C  INITIALIZATION
```

```
C-----
C  INIT SERIAL RECEIVER INTERRUPT ROUTINE
0048      CALL INTR
C  SET JOB STATUS FOR TERMINAL CONTINUE MODE
0049      CALL IPOKE("44,"100.DR.IPEEK("44))
```

```
C-----
C  DISPLAY MAIN MENU
```

```
C-----
0050      3 CALL CLRSCN
0051      CALL BAKSCN
0052      TYPE 5
0053      CALL DATE(IDATE)
0054      CALL TIME(ITIME)
0055      TYPE 12,(IDATE(I),I=1,9),(ITIME(J),J=1,8)
0056      TYPE 10
0057      TYPE 15
0058      TYPE 20
0059      TYPE 22
0060      TYPE 25
0061      TYPE 30
0062      TYPE 32
0063      TYPE 35
0064      5 FORMAT(' 'T22'SODIUM LIDAR - UNIVERSITY OF ILLINOIS'//)
0065      10 FORMAT(' 'T35'MAIN MENU'//)
0066      12 FORMAT(' ',T35,9A1,/,T35,8A1,//)
0067      15 FORMAT('O'T14'<1> Experiment Parameters'//)
0068      20 FORMAT(' 'T14'<2> Current Status'//)
0069      22 FORMAT(' 'T14'<3> Low Altitude Alignment Run'//)
0070      25 FORMAT(' 'T14'<4> Sodium Alignment Run'//)
0071      30 FORMAT(' 'T14'<5> Data Run'//)
0072      32 FORMAT(' 'T14'<6> Examine Profile on Disk'//)
0073      35 FORMAT('O'/T5'Enter an option: '$)
```

```
C-----
C  GET AND CHECK RESPONSE
```

```
C-----
0074      READ(5,*,ERR=3) OPT
C  EXPERIMENT PARAMETERS
0075      IF(OPT.EQ.1) CALL EXPPAR
C  CURRENT STATUS
0077      IF(OPT.EQ.2) CALL CSTTUS
C  LOW-ALTITUDE ALIGNMENT RUN
0079      IF(OPT.EQ.3) CALL LAALN
C  SODIUM ALIGNMENT RUN
```

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```
0081      IF(OPT.EQ.4) CALL ALNRTN
0082      C DATA RUN
0083      IF(OPT.EQ.5) CALL DATRUN
0084      C EXAMINE PROFILE ON DISK
0085      IF(OPT.EQ.6) CALL EXMPRF
0086      C HEX DUMP OF ARRAY LDATA
0087      IF(OPT.EQ.7) CALL MOUT
0088      GOTO 3
0089      STOP
0090      STOP
0091      END
```

FORTTRAN IV Storage Map for Program Unit .MAIN.

Local Variables, .PSECT \$DATA, Size = 000020 (8. words)

Name	Type	Offset	Name	Type	Offset	Name	Type	Offset
I	I*2	000006	J	I*2	000010	OPT	R*4	000012

COMMON Block /DATTIM/, Size = 000021 (9. words)

Name	Type	Offset	Name	Type	Offset	Name	Type	Offset
IDATE	L*1	000000	ITIME	L*1	000011			

COMMON Block /SETS /, Size = 000006 (3. words)

Name	Type	Offset	Name	Type	Offset	Name	Type	Offset
SETS	I*2	000000	PROFS	I*2	000002	SHOTSP	I*2	000004

COMMON Block /LREPS /, Size = 000042 (17. words)

Name	Type	Offset	Name	Type	Offset	Name	Type	Offset
LREP	R*4	000000	LRI	R*4	000004	HRI	R*4	000010
LBI	I*2	000014	HBI	I*2	000016	BSAT	R*4	000020
BSATF	R*4	000024	EANG	R*4	000030	REANG	R*4	000034
PDEL	I*2	000040						

COMMON Block /STATS /, Size = 000010 (4. words)

Name	Type	Offset	Name	Type	Offset	Name	Type	Offset
CSET	I*2	000000	CPROF	I*2	000002	LSET	I*2	000004
LPROF	I*2	000006						

COMMON Block /CALCS /, Size = 000020 (8. words)

Name	Type	Offset	Name	Type	Offset	Name	Type	Offset
K30	I*2	000000	K60	I*2	000002	K80	I*2	000004
K100	I*2	000006	SGP	I*2	000010	TSGP	I*2	000012
CLA	R*4	000014						

COMMON Block /ALN /, Size = 000006 (3. words)

Name	Type	Offset	Name	Type	Offset	Name	Type	Offset
.EPR4	R*4	000000	SHOTS4	I*2	000004			

COMMON Block /LAAN /, Size = 000006 (3. words)

Name	Type	Offset	Name	Type	Offset	Name	Type	Offset
REPR3	R*4	000000	SHOTS3	I*2	000004			

COMMON Block /DISK /, Size = 000023 (10. words)

Name	Type	Offset	Name	Type	Offset	Name	Type	Offset
INTSIZ	I*2	000000	RECSIZ	I*2	000002	FNAME	L*1	000004

FORTRAN IV Storage Map for Program Unit .MAIN.

COMMON Block /PTERS /, Size = 000006 (3. words)

Name	Type	Offset	Name	Type	Offset	Name	Type	Offset
B00	I*2	000000	B60	I*2	000002	S20	I*2	000004

COMMON Block /CONST /, Size = 000020 (8. words)

Name	Type	Offset	Name	Type	Offset	Name	Type	Offset
P1	R*4	000000	C	R*4	000004	GATTIM	R*4	000010
RG	R*4	000014						

Local and COMMON Arrays:

Name	Type	Section	Offset	Size	Dimensions
FNAME	L*1	DISK	000004	000017 (8.)	(15)
IDATE	L*1	DATTIM	000000	000011 (5.)	(9)
ITIME	L*1	DATTIM	000011	000010 (4.)	(8)

Subroutines, Functions, Statement and Processor-Defined Functions:

Name	Type	Name	Type	Name	Type	Name	Type	Name	Type
ALNRN	R*4	BAKSCN	R*4	CLRSCN	R*4	CSTTUS	R*4	DATE	R*4
DATRUN	R*4	EXMPRF	R*4	EXPPAR	R*4	INITR	I*2	IPEEK	I*2
IPOKE	I*2	LAALN	I*2	MOUT	I*2	TIME	R*4		

III.3 EXPPAR

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```

C *****
C SUBROUTINE EXPPAR - EXPERIMENT PARAMETERS
C   D.VOELZ
C *****
C THIS SUBROUTINE DISPLAYS THE LIDAR EXPERIMENT
C PARAMETER VALUES AND ALLOWS THE VALUES TO BE
C CHANGED.
C
0001 SUBROUTINE EXPPAR
0002 INTEGER SETS,PROFS,SHOTSP,LBI,HBI,PDEL
0003 REAL LREP,LRI,HRI,EANG,C,GATTIM,RG,PI,REANG,BSAT,DENOM
0004 REAL BSATF
0005 LOGICAL*1 IDATE(9),ITIME(8)
0006 BYTE CHNG
C
0007 COMMON /DATTIM/ IDATE,ITIME
0008 COMMON /SETS/ SETS,PROFS,SHOTSP
0009 COMMON /LREPS/ LREP,LRI,HRI,LBI,HBI,BSAT,BSATF,EANG,
0010 >REANG,PDEL
0011 COMMON /CONST/ PI,C,GATTIM,RG
C
C-----
C DISPLAY PARAMETER MENU
C-----
C CLEAR SCREEN AND SET ON BACKGORUND (LO INTENSITY)
0011 5 CALL CLRSCN
0012 CALL BAKSCN
C GET DATE AND TIME
0013 CALL DATE(IDATE)
0014 CALL TIME(ITIME)
0015 TYPE 20,(IDATE(I),I=1,9),(ITIME(J),J=1,8)
C SET SCREEN ON FOREGROUND (HI INTENSITY)
0016 CALL FORSCN
0017 TYPE 30,SETS
0018 TYPE 35,PROFS
0019 TYPE 40,SHOTSP
0020 TYPE 45,LREP
0021 TYPE 46,PDEL
0022 TYPE 47,EANG
0023 TYPE 48,BSAT
0024 TYPE 49,BSATF
0025 TYPE 50,LRI,HRI
0026 TYPE 52,LBI,HBI
C SET SCREEN ON BACKGROUND (LO INTENSITY)
0027 CALL BAKSCN
0028 TYPE 70
0029 20 FORMAT(' ',T29,'EXPERIMENT PARAMETERS',/,/T35,9A1,/T35-8A1,/)
0030 30 FORMAT(' ',T14,'<S> #Sets ',21X,'=' ',I4,' ')
0031 35 FORMAT(' ',T14,'<P> #Profiles Per Set ',9X,'=' ',I4
0032 40 FORMAT(' ',T14,'<L> #Laser Shots Per Profile',3X,'=' ',I4
>,' ')

```

```

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0033      45 FORMAT(' ',T14,'<R> Laser Rep Rate',13X,'= ',F4.1,' Hz'
>,' ')
0034      46 FORMAT(' ',T14,'<D> Inter-Profile Delay',8X,'= ',I4,' Sec'
>,' ')
0035      47 FORMAT(' ',T14,'<E> Elevation Ansls',12X,'= ',F5.1,' Degrees'
>,' ')
0036      48 FORMAT(' ',T14,'<B> Base Altitude',14X,'= ',F6.2,' KM'
>,' ')
0037      49 FORMAT(' ',T14,'<F>',29X,'= ',F7.1,' Ft',' ')
0038      50 FORMAT(' ',T14,'<H> Altitude Range of Data',4X,' = ',F6.2,
+ ' To ',F7.2,' KM')
0039      52 FORMAT(' ',T14,'<N> Range Bins',16X,' = ',I4,' To ',I4
>,' ')
0040      70 FORMAT('0',///,T5,'To change any parameter value first enter th
+ e correspondina',/T5,'LETTER and then RETURN ',)$

C-----
C GET RESPONSE
C-----

0041      READ(5,80,ERR=5) CHNG
0042      80 FORMAT(A1)

C-----
C CHECK RESPONSE AND CHANGE VALUES
C-----

0043      CALL FORSCN
C CHANGE SETS
0044      81 IF(CHNG.NE.'S') GOTO 90
0046      TYPE 85
0047      85 FORMAT('0',T14,'#Sets = ',)$
0048      READ(5,*,ERR=200)SETS
0049      IF(SETS.LE.0) GOTO 200
0051      GOTO 5

C CHANGE PROFILES PER SET
0052      90 IF(CHNG.NE.'P') GOTO 100
0054      92 TYPE 93
0055      93 FORMAT('0',T14,'#Profiles Per Set = ',)$
0056      READ(5,*,ERR=200)PROFS
0057      IF(PROFS.LE.0) GOTO 200
0059      GOTO 5

C CHANGE LASER SHOTS PER PROFILE
0060      100 IF(CHNG.NE.'L') GOTO 110
0062      102 TYPE 103
0063      103 FORMAT('0',T14,'#Laser Shots Per Profile = ',)$
0064      READ(5,*,ERR=200)SHOTSP
0065      IF(SHOTSP.LE.0)GOTO 200
0067      GOTO 5

C CHANGE LASER REP RATE
0068      110 IF(CHNG.NE.'R') GOTO 115
0070      112 TYPE 113
0071      113 FORMAT('0',T14,'Laser Rep Rate = ',)$
0072      READ(5,*,ERR=200)LREP
0073      IF((LREP.LE.0.0).OR.(LREP.GT.10.0)) GOTO 200
0075      GOTO 5

C CHANGE INTER-PROFILE DELAY
0076      115 IF(CHNG.NE.'D')GOTO 120

```

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```

0078 117 TYPE 113
0079 118 FORMAT('0',T14,'Inter-Profile Delay = ',%)
0080 READ(5,*,ERR=200) PDEL
0081 IF(PDEL.LT.0)GOTO 200
0083 GOTO 5
C CHANGE ELEVATION ANGLE
0084 120 IF(CHNG.NE.'E')GOTO 130
0086 122 TYPE 123
0087 123 FORMAT('0',T14,'Elevation Ansls = ',%)
0088 READ(5,*,ERR=200)EANG
0089 IF((EANG.LE.0).OR.(EANG.GT.90)) GOTO 200
0091 REANG=(PI/180.)*EANG
0092 GOTO 300
C CHANGE BASE ALTITUDE
0093 130 IF(CHNG.NE.'B')GOTO 140
0095 132 TYPE 133
0096 133 FORMAT('0',T14,'Base Altitude (KM) = ',%)
0097 READ(5,*,ERR=200)BSAT
0098 BSATF=3281.*BSAT
0099 GOTO 300
0100 140 IF(CHNG.NE.'F')GOTO 150
0102 142 TYPE 143
0103 143 FORMAT('0',T14,'Base Altitude (Feet)= ',%)
0104 READ(5,*,ERR=200)BSATF
0105 BSAT=.0003048*BSATF
0106 GOTO 300
C CHANGE ALTITUDE RANGE OF DATA
0107 150 IF(CHNG.NE.'H') GOTO 160
0109 152 TYPE 153
0110 153 FORMAT('0',T14,'Altitude Range of Data = ',%)
0111 READ(5,*,ERR=200)LPI
0112 IF(LRI.LT.BSAT) GOTO 200
0114 TYPE 157
0115 157 FORMAT('+',T34,'To ',%)
0116 READ(5,*,ERR=200)HRI
0117 IF(HRI.LE.LRI) GOTO 200
0119 GOTO 290
C CHANGE RANGE BINS
0120 160 IF(CHNG.NE.'N') RETURN
0122 162 TYPE 163
0123 163 FORMAT('0',T14,'Range Bins = ',%)
0124 READ(5,*,ERR=200)LBI
0125 TYPE 167
0126 167 FORMAT('+',T22,'To ',%)
0127 READ(5,*,ERR=200)HBI
0128 IF(HBI.LE.LBI) GOTO 200
0130 REANG=(PI/180.)*EANG
0131 GOTO 295
C-----
C ERROR MESSAGES
C-----
0132 200 TYPE 210
0133 210 FORMAT(' ',T7,'?? PARAMETER RANGE ERROR')
0134 GOTO 81

```

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```
C-----  
C RANGE CALCULATIONS  
C-----  
0135 290 REANG=(PI/180.)*EANG  
0136 DENOM=SIN(REANG)*RG  
0137 LBI=IFIX((LRI+(RG/2.))-BSAT)/DENOM  
0138 HBI=IFIX((HRI+(1.5*RG))-BSAT)/DENOM  
0139 295 IF(HBI.GT.2000)HBI=2000  
0141 IF(LBI.LT.1)LBI=1  
0143 300 LRI=FLOAT(((LBI*RG)-(RG/2.))*SIN(REANG)+BSAT)  
0144 HRI=FLOAT(((HBI*RG)-(RG/2.))*SIN(REANG)+BSAT)  
0145 GOTO 5  
  
C  
0146 STOP  
0147 END
```

FORTRAN IV Storage Map for Program Unit EXPPAR

Local Variables, .PSECT \$DATA, Size = 000040 (16. words)

Name	Type	Offset	Name	Type	Offset	Name	Type	Offset
CHNG	L*1	000012	DENOM	R*4	000006	I	I*2	000014
J	I*2	000016						

COMMON Block /DATTIM/, Size = 000021 (9. words)

Name	Type	Offset	Name	Type	Offset	Name	Type	Offset
IDATE	L*1	000000	ITIME	L*1	000011			

COMMON Block /SETS /, Size = 000006 (3. words)

Name	Type	Offset	Name	Type	Offset	Name	Type	Offset
SETS	I*2	000000	PROFS	I*2	000002	SHOTSP	I*2	000004

COMMON Block /LREPS /, Size = 000042 (17. words)

Name	Type	Offset	Name	Type	Offset	Name	Type	Offset
LREP	R*4	000000	LRI	R*4	000004	HRI	R*4	000010
LBI	I*2	000014	HBI	I*2	000016	BSAT	R*4	000020
BSATF	R*4	000024	EANG	R*4	000030	REANG	R*4	000034
PDEL	I*2	000040						

COMMON Block /CONST /, Size = 000020 (8. words)

Name	Type	Offset	Name	Type	Offset	Name	Type	Offset
PI	R*4	000000	C	R*4	000004	GATTIM	R*4	000010
RG	R*4	000014						

Local and COMMON Arrays:

Name	Type	Section	Offset	-----Size-----	Dimensions
IDATE	L*1	DATTIM	000000	000011 (5.)	(9)
ITIME	L*1	DATTIM	000011	000010 (4.)	(8)

Subroutines, Functions, Statement and Processor-Defined Functions:

Name	Type	Name	Type	Name	Type	Name	Type	Name	Type
BAKSCN	R*4	CLRSCN	R*4	DATE	R*4	FLOAT	R*4	FORSCN	R*4
IFIX	I*2	SIN	R*4	TIME	R*4				

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III.4 CSTTUS

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```

C *****
C
C   SUBROUTINE CSTTUS - CURRENT STATUS
C   D.VOELZ
C *****
C
C   THIS SUBROUTINE DISPLAYS THE CURRENT STATUS OF THE EXPERIMENT.
C   ALSO DISPLAYED ARE THE CHARACTERISTIC DATA VALUES FOR THE LAST
C   RECORDED PROFILE. THE SUBROUTINE ALLOWS THE VALUES OF THE
C   CURRENT SCAN AND PROFILE TO BE CHANGED.
C
0001   SUBROUTINE CSTTUS
0002   INTEGER SETS,PROFS,SHOTSP,CSET,CPROF,LSET,LPROF,CHNG
      >,K30,K60,K80,K100,SGP,TSGP
0003   REAL EANG,CLA
0004   LOGICAL*1 IDATE(9),ITIME(8)
C
0005   COMMON /DATTIM/ IDATE,ITIME
0006   COMMON /SETS/ SETS,PROFS,SHOTSP
0007   COMMON /STATS/ CSET,CPROF,LSET,LPROF
0008   COMMON /CALCS/ K30,K60,K80,K100,SGP,TSGP,CLA
C
C   -----
C   DISPLAY CURRENT STATUS MENU
C   -----
0009   5 CALL CLRSCN
0010     CALL BAKSCN
0011     TYPE 30
0012     CALL DATE(IDATE)
0013     TYPE 35,(IDATE(I),I=1,9),SETS
0014     CALL TIME(ITIME)
0015     TYPE 40,(ITIME(J),J=1,8)
0016     CALL FORSCN
0017     TYPE 45,CSET
0018     CALL BAKSCN
0019     TYPE 50,PROFS
0020     CALL FORSCN
0021     TYPE 55,CPROF
0022     CALL BAKSCN
0023     TYPE 60
0024     TYPE 65,LSET,SHOTSP
0025     TYPE 70,LPROF
0026     TYPE 75,K30,K60,K80,K100
0027     TYPE 95,TSGP
0028     TYPE 100,SGP
0029     TYPE 105,CLA
0030     TYPE 110
C
0031   30 FORMAT('+',T2,'CURRENT STATUS -----
      +-----')
0032   35 FORMAT('0',T5,9A1,21X,'Desired # Sets ',11X,'=',I6)
0033   40 FORMAT(' ',T5,8A1,$)

```

```

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0034      45 FORMAT('+',T20,'<CS> Current Set ',I2X,'=',I6)
0035      50 FORMAT(' ',T35,'Profiles Per Set ',9X,'=',I6)
0036      55 FORMAT(' ',T31,'<CP> Current Profile',9X,'=',I6)
0037      60 FORMAT('0',T2,'LAST RECORDED PROFILE -----
+-----')
0038      65 FORMAT('0',T5,'Set # ',I4,I6X,'Laser Shots Per Profile ='
+,I6)
0039      70 FORMAT(' ',T5,'Profile # ',I4,I6X,'Detected Photons:')
0040      75 FORMAT(' ',T50,'at 30 Km',3X,'=',I6,/T47,'60 - 80 Km',3X,
+='',I6,/T47,'80 - 100 Km',3X,'=',I6,/T46,'100 - 120 Km',3X,
+='',I6)
0041      95 FORMAT(' ',T35,'Total Signal Photons =',I6)
0042      100 FORMAT(' ',T35,'Signal Photons Per Shot =',I6)
0043      105 FORMAT(' ',T35,'Column Abundance Ratio =',F6.2)
0044      110 FORMAT('0',T2,'To change the Current Set or Profile values first
+ enter the',/T2,'corresponding LETTERS then RETURN ',I6)

C -----
C GET RESPONSE
C -----
0045      READ(5,150,ERR=5) CHNG
0046      150 FORMAT(A2)

C -----
C CHECK RESPONSE AND CHANGE VALUES
C -----
0047      CALL FORSCN
C CHANGE CURRENT SET
0048      155 IF(CHNG.NE.'CS') GOTO 170
0050      160 TYPE 162
0051      162 FORMAT('0',T14,'Current Set = ',I6)
0052      READ(5,*,ERR=200)CSET
0053      IF(CSET.LE.0)GOTO 200
0055      GOTO 5

C CHANGE CURRENT PROFILE
0056      170 IF(CHNG.NE.'CP')RETURN
0058      172 TYPE 173
0059      173 FORMAT('0',T14,'Current Profile = ',I6)
0060      READ(5,*,ERR=200) CPROF
0061      IF(CPROF.LE.0.OR.CPROF.GT.PROFS)GOTO 200
0063      GOTO 5

C -----
C ERROR MESSAGES
C -----
0064      200 TYPE 210
0065      210 FORMAT(' ',T7,'?? PARAMETER RANGE ERROR')
0066      GOTO 155
0067      STOP
0068      END

```


FORTRAN IV Storage Map for Program Unit CSTTUS

Local Variables, .PSECT \$DATA, Size = 000020 (8. words)

Name	Type	Offset	Name	Type	Offset	Name	Type	Offset
CHNG	I*2	000006	EANG	R*4	000010	I	I*2	000014
J	I*2	000016						

COMMON Block /DATTIM/, Size = 000021 (9. words)

Name	Type	Offset	Name	Type	Offset	Name	Type	Offset
IDATE	L*1	000000	ITIME	L*1	000011			

COMMON Block /SETS /, Size = 000006 (3. words)

Name	Type	Offset	Name	Type	Offset	Name	Type	Offset
SETS	I*2	000000	PROFS	I*2	000002	SHOTSP	I*2	000004

COMMON Block /STATS /, Size = 000010 (4. words)

Name	Type	Offset	Name	Type	Offset	Name	Type	Offset
CSET	I*2	000000	CPROF	I*2	000002	LSET	I*2	000004
LPROF	I*2	000006						

COMMON Block /CALCS /, Size = 000020 (8. words)

Name	Type	Offset	Name	Type	Offset	Name	Type	Offset
K30	I*2	000000	K60	I*2	000002	K90	I*2	000004
K100	I*2	000006	SGP	I*2	000010	TSGP	I*2	000012
CLA	I*4	000014						

Local and COMMON Arrays:

Name	Type	Section	Offset	-----Size-----	Dimensions
IDATE	L*1	DATTIM	000000	000011 (5.)	(9)
ITIME	L*1	DATTIM	000011	000010 (4.)	(8)

Subroutines, Functions, Statement and Processor-Defined Functions:

Name	Type	Name	Type	Name	Type	Name	Type	Name	Type
BAKSCN	R*4	CLRSCN	R*4	DATE	R*4	FORSCN	R*4	TIME	R*4

III.5 LAALN

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```

C *****
C
C SUBROUTINE LAALN.FOR -- LOW ALTITUDE ALIGNMENT ROUTINE
C                               D.VOELZ
C *****
C
C THIS SUBROUTINE INITIATES A LOW ALTITUDE ALIGNMENT DATA
C RUN.
C
0001 SUBROUTINE LAALN
0002 REAL REPR3
0003 INTEGER SHOTS3,MSHOTS,REPNUM,BCNT,BNMBR,LDATA(2100)
0004 LOGICAL*1 IDATE(9),ITIME(8)
0005 BYTE RUNFLG,DFLAG,ERRFLG,MON,JCHAR,OPT
C
0006 COMMON/DATTIM/ IDATE,ITIME
0007 COMMON/LAAN/ REPR3,SHOTS3
0008 COMMON/FLAGS/ RUNFLG,DFLAG,ERRFLG
0009 COMMON/SEND/ REPNUM,MSHOTS
0010 COMMON/BUFF/ LDATA
C
C TYPE LOW ALTITUDE ALIGNMENT ROUTINE SCREEN
C
0011 5 CALL CLRSCN
0012 CALL BAKSCN
0013 CALL DATE(IDATE)
0014 CALL TIME(ITIME)
0015 TYPE 20,(IDATE(I),I=1,9),(ITIME(J),J=1,8)
0016 CALL FORSCN
0017 TYPE 22,SHOTS3
0018 TYPE 24,REPR3
0019 CALL BAKSCN
0020 TYPE 26
0021 TYPE 30
0022 20 FORMAT(' ',//,T25,'LOW ALTITUDE ALIGNMENT ROUTINE',//,T35
>,9A1,/,T35,8A1,/)
0023 22 FORMAT(' ',T10,'<L> Laser Shots Per Profile = ',I4
>,' ')
0024 24 FORMAT(' ',T10,'<R> Laser Rep Rate = ',F4.1
+,' Hz',' ')
0025 26 FORMAT(' ',//,T5,'To change any parameter value enter the corres
+ponding LETTER',/T5,'and then RETURN')
0026 30 FORMAT(' ',//,T5,'To begin the alignment routine press "Y"
+ then RETURN ',)
C =====
C GET & CHECK RESPONSE
C =====
0027 READ(5,80,ERR=5) OPT
0028 80 FORMAT(A1)
C
0029 CALL FORSCN
C CHANGE LASER SHOTS PER PROFILE
0030 81 IF(OPT.NE.'L') GOTO 90

```

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```
0032           TYPE 85
0033       85 FORMAT('0',T10,'Laser Shots Per Profile = ',%)
0034           READ(5,*,ERR=200)SHOTS3
0035           IF(SHOTS3.LE.0)GOTO 200
0037           GOTO 5
C   CHANGE LASER REP RATE
0038       90 IF(OPT.NE.'R') GOTO 100
0040           TYPE 95
0041       95 FORMAT('0',T10,'Laser Rep Rate = ',%)
0042           READ(5,*,ERR=200)REPR3
0043           IF((REPR3.LE.0.0).OR.(REPR3.GT.10.0)) GOTO 200
0045           GOTO 5
C   =====
C   LOW ALTITUDE ALIGNMENT RUN
C   =====
0046       100 IF(OPT.NE.'Y') RETURN
0048           CALL BAKSCN
C
C   PARAMETER CALCULATIONS
C
0049           MSHOTS=SHOTS3
0050           REPNUM=IFIX((SQRT((1.02046*1.E6/REPR3-57251.)*4./15.+
          >(5.4*5.4))-5.4)/2.+5)
C
C   INIT FLAGS & START PROFILE RUN
C
0051       120 DFLAG=0
0052           ERRFLG=0
0053           CALL SNDCOM
C
C   GET DATE AND TIME
C
0054           CALL TIME(ITIME)
0055           CALL DATE(IDATE)
C
C   WAIT FOR PROFILE
C
0056       130 ICHAR=ITTINR()
0057           JCHAR=ICHR
0058           IF(JCHAR.EQ.'S') GOTO 180
0060           IF(DFLAG.NE.1)GOTO 130
0062           IF(ERRFLG.EQ.1)GOTO 180
C
C   DISPLAY
C
0064           DO 160 K=1,3
0065           TYPE 135,(IDATE(I),I=1,9),K,(ITIME(I),I=1,8)
0066       135 FORMAT(' ',T5.9A1,25X,I2,/,T5.8A1)
0067           BCNT=1+200*(K-1)
0068           DO 150 J=1,20
0069           BNMBR=BCNT+10*(J-1)
0070           TYPE 140,BNMBR,(LDATE(I),I=BNMBR,BNMBR+9)
0071       140   FORMAT(' ',I5,'-',I10I6)
0072       150   CONTINUE
```

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```
0073 PAUSE
0074 160 CONTINUE
0075 163 TYPE 165
0076 165 FORMAT(' ',//,T19,'Do you want to run the Routine
      > again ? ',)
0077 READ(5,170,ERR=163)MON
0078 170 FORMAT(A1)
0079 IF(MON.EQ.'Y')GOTO 120
C
0081 180 RETURN
C
C-----
C ERROR MESSAGES
C-----
0082 200 TYPE 210
0083 210 FORMAT(' ',T7,'?? PARAMETER RANGE ERROR')
0084 GOTO 81
C
0085 STOP
0086 END
```

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FORTRAN IV Storage Map for Program Unit LAALN

Local Variables, .PSECT \$DATA, Size = 000046 (19. words)

Name	Type	Offset	Name	Type	Offset	Name	Type	Offset
BCNT	I*2	000014	BNMBR	I*2	000016	I	I*2	000024
ICHAR	I*2	000030	J	I*2	000026	JCHAR	L*1	000021
K	I*2	000032	MON	L*1	000020	OPT	L*1	000022

COMMON Block /DATTIM/, Size = 000021 (9. words)

Name	Type	Offset	Name	Type	Offset	Name	Type	Offset
IDATE	L*1	000000	ITIME	L*1	000011			

COMMON Block /LAAN /, Size = 000006 (3. words)

Name	Type	Offset	Name	Type	Offset	Name	Type	Offset
REPR3	R*4	000000	PHOTS3	I*2	000004			

COMMON Block /FLAGS /, Size = 000003 (2. words)

Name	Type	Offset	Name	Type	Offset	Name	Type	Offset
RUNFLG	L*1	000000	DFLAG	L*1	000001	ERRFLG	L*1	000002

COMMON Block /SEND /, Size = 000004 (2. words)

Name	Type	Offset	Name	Type	Offset	Name	Type	Offset
REPNUM	I*2	000000	MSHOTS	I*2	000002			

COMMON Block /BUFF /, Size = 010150 (2100. words)

Name	Type	Offset	Name	Type	Offset	Name	Type	Offset
LDATA	I*2	000000						

Local and COMMON Arrays:

Name	Type	Section	Offset	-----Size-----	Dimensions
IDATE	L*1	DATTIM	000000	000011 (5.)	(9)
ITIME	L*1	DATTIM	000011	000010 (4.)	(8)
LDATA	I*2	BUFF	000000	010150 (2100.)	(2100)

Subroutines, Functions, Statement and Processor-Defined Functions:

Name	Type	Name	Type	Name	Type	Name	Type	Name	Type
BAKSCN	R*4	CLRSCN	R*4	DATE	R*4	FORSCN	R*4	IFIX	I*2
ITTINR	I*2	SNDCOM	R*4	SQRT	R*4	TIME	R*4		

III.6 ALNRTN

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```

C *****
C SUBROUTINE ALNRTN.FOR - SODIUM ALIGNMENT ROUTINE
C                               D.VOELZ
C *****
C THIS SUBROUTINE INITIATES A SODIUM ALIGNMENT DATA
C RUN.
0001 SUBROUTINE ALNRTN
0002 REAL REPR4,LREP,LRI,HRI,BSAT,EANG,PI,C,GATTIM,RG,REANG
    >,DENOM,BSATF
0003 INTEGER REPNUM,SHOTS4,MSHOTS,LBI,HBI,INTSIZ,RECSIZ,B30
    >,B60,S20,PDEL
0004 LOGICAL*1 IDATE(9),ITIME(8)
0005 BYTE RUNFLG,DFLAG,ERRFLG,MON,JCHAR,OPT
C
0006 COMMON/PTERS/ B30,B60,S20
0007 COMMON/LREPS/ LREP,LRI,HRI,LBI,HBI,BSAT,BSATF,EANG,
    >REANG,PDEL
0008 COMMON/DATTIM/ IDATE,ITIME
0009 COMMON/ALN/ REPR4,SHOTS4
0010 COMMON/FLAGS/ RUNFLG,DFLAG,ERRFLG
0011 COMMON/SEND/ REPNUM,MSHOTS
0012 COMMON/CONST/ PI,C,GATTIM,RG
C
C TYPE SODIUM ALIGNMENT ROUTINE SCREEN
0013 5 CALL CLRSCN
0014 CALL BAKSCN
0015 CALL DATE(IDATE)
0016 CALL TIME(ITIME)
0017 TYPE 20,(IDATE(I),I=1,9),(ITIME(J),J=1,8)
0018 CALL FORSCN
0019 TYPE 22,SHOTS4
0020 TYPE 24,REPR4
0021 CALL BAKSCN
0022 TYPE 26
0023 TYPE 30
0024 20 FORMAT(' ',/,T28,'SODIUM ALIGNMENT ROUTINE',/,/T35,9A1,/T35
    >,8A1,/)
0025 22 FORMAT(' ',T10,'<L> Laser Shots Per Profile = ',I4
    >,' ')
0026 24 FORMAT(' ',T10,'<R> Laser Rep Rate = ',F4.1
    +,' Hz',')
0027 26 FORMAT(' ',//,T5,'To change any parameter value enter the corres
    +ponding LETTER',/T5,'and then RETURN')
0028 30 FORMAT(' ',//,T5,'To begin the alignment routine press "Y"
    + then RETURN ',)$)
C =====
C GET & CHECK RESPONSE
C =====
0029 READ(5,80,ERR=5) OPT

```

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```

0030      80 FORMAT(A1)
C
0031      CALL FORSCN
C CHANGE LASER SHOTS PER PROFILE
0032      81 IF(OPT.NE.'L') GOTO 90
0034      TYPE 85
0035      85 FORMAT('0',T10,'Laser Shots Per Profile = ',%)
0036      READ(5,*,ERR=200)SHOTS4
0037      IF(SHOTS4.LE.0)GOTO 200
0039      GOTO 5
C CHANGE LASER REP RATE
0040      90 IF(OPT.NE.'R') GOTO 100
0042      TYPE 95
0043      95 FORMAT('0',T10,'Laser Rep Rate = ',%)
0044      READ(5,*,ERR=200)REPR4
0045      IF((REPR4.LE.0.0).OR.(REPR4.GT.10.0)) GOTO 200
0047      GOTO 5
C =====
C SODIUM ALIGNMENT RUN
C =====
0048      100 IF(OPT.NE.'Y') RETURN
0050      CALL BAKSCN
0051      RUNFLG=3
C
C PARAMETER CALCULATIONS
C
0052      DENOM=SIN(REANG)*RG
0053      B30=IFIX((30.+(RG/2)-BSAT)/DENOM+.5)
0054      B60=IFIX((60.+(RG/2)-BSAT)/DENOM+.5)
0055      S20=IFIX((20.+(RG/2))/DENOM+.5)
0056      MSHOTS=SHOTS4
0057      REPNUM=IFIX((SQRT((1.02046*1.E6/REPR4-57251.)*4./15.+
>(5.4*5.4))-5.4)/2.+5)
C
C INIT FLAGS & START PROFILE RUN
C
0058      120 DFLAG=0
0059      ERRFLG=0
0060      CALL SNDCOM
C
C GET DATE AND TIME
C
0061      CALL TIME(ITIME)
0062      CALL DATE(IDATE)
C
C WAIT FOR PROFILE
C
0063      130 ICHAR=ITTINR()
0064      JCHAR=ICHAR
0065      IF(JCHAR.EQ.'S') GOTO 160
0067      IF(DFLAG.NE.1)GOTO 130
0069      IF(ERRFLG.EQ.1)GOTO 160
0071      CALL DISCAL
C

```

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```
0072    135 TYPE 140
0073    140 FORMAT(' ',//,T19,'Do you want to run the Routine
         > again ? ',*)
0074            READ(5,145,ERR=135)MON
0075    145 FORMAT(A1)
0076            IF(MON.EQ.'Y')GOTO 120
      C
0078    160 RETURN
      C
      C-----
      C    ERROR MESSAGES
      C-----
0079    200 TYPE 210
0080    210 FORMAT(' ',T7,'?? PARAMETER RANGE ERROR')
0081            GOTO 81
      C
0082            STOP
0083            END
```


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FORTRAN IV Storage Map for Program Unit ALNRTN

Local Variables, .PSECT \$DATA, Size = 000060 (24. words)

Name	Type	Offset	Name	Type	Offset	Name	Type	Offset
DENOM	R*4	000006	I	I*2	000022	ICHAR	I*2	000026
INTSIZ	I*2	000012	J	I*2	000024	JCHAR	L*1	000017
MON	L*1	000016	OPT	L*1	000020	RECSIZ	I*2	000014

COMMON Block /PTERS /, Size = 000006 (3. words)

Name	Type	Offset	Name	Type	Offset	Name	Type	Offset
B30	I*2	000000	B60	I*2	000002	S20	I*2	000004

COMMON Block /LREPS /, Size = 000042 (17. words)

Name	Type	Offset	Name	Type	Offset	Name	Type	Offset
LREP	R*4	000000	LRI	R*4	000004	HRI	R*4	000010
LBI	I*2	000014	HBI	I*2	000016	BSAT	R*4	000020
BSATF	R*4	000024	EANG	R*4	000030	REANG	R*4	000034
PDEL	I*2	000040						

COMMON Block /DATTIM/, Size = 000021 (9. words)

Name	Type	Offset	Name	Type	Offset	Name	Type	Offset
IDATE	L*1	000000	ITIME	L*1	000011			

COMMON Block /ALN /, Size = 000006 (3. words)

Name	Type	Offset	Name	Type	Offset	Name	Type	Offset
REPR4	R*4	000000	SHOTS4	I*2	000004			

COMMON Block /FLAGS /, Size = 000003 (2. words)

Name	Type	Offset	Name	Type	Offset	Name	Type	Offset
RUNFLG	L*1	000000	DFLAG	L*1	000001	ERRFLG	L*1	000002

COMMON Block /SEND /, Size = 000004 (2. words)

Name	Type	Offset	Name	Type	Offset	Name	Type	Offset
REPNUM	I*2	000000	MSHOTS	I*2	000002			

COMMON Block /CONST /, Size = 000020 (8. words)

Name	Type	Offset	Name	Type	Offset	Name	Type	Offset
PI	R*4	000000	C	R*4	000004	GATTIM	R*4	000010
RG	R*4	000014						

Local and COMMON Arrays:

Name	Type	Section	Offset	-----Size-----	Dimensions
IDATE	L*1	DATTIM	000000	000011 (5.)	(9)
ITIME	L*1	DATTIM	000011	000010 (4.)	(8)

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III.7 DATRUN

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```

C *****
C SUBROUTINE DATRUN - DATA RUN
C   D.VOELZ
C *****
C THIS SUBROUTINE INITIATES A DATA RUN (WHICH CONSISTS
C OF A SET OF PROFILES).
0001 SUBROUTINE DATRUN
0002 LOGICAL*1 IIDATE(9),ITIME(8)
0003 REAL LREP,LRI,HRI,BSAT,EANG,C,GATTIM,RG,PI,REANG,DENOM,BSATF
0004 INTEGER SETS,PROFS,SHOTSP,CSET,CPROF,LSET,LPROF,HBI,LBI
    >,INTSIZ,RECSIZ,B30,B60,S20,REPNUM,MSHOTS,MN,DAY,YR,HDRB
    >,BINS,LDATA(2100),PDEL
0005 INTEGER*4 TIM2,TIML,TIMH,STIM,DTIM
0006 BYTE OPT,MON,RUNFLG,FNAME(15),EXT(3),DFLAG,ERRFLG
    >,JCHAR
C
0007 COMMON /DATTIM/ IIDATE,IYIME
0008 COMMON /DISK/ INTSIZ,RECSIZ,FNAME
0009 COMMON /PTERS/ B30,B60,S20
0010 COMMON /LREPS/ LREP,LRI,HRI,LBI,HBI,BSAT,BSATF,EANG,
    >REANG,PDEL
0011 COMMON /SETS/ SETS,PROFS,SHOTSP
0012 COMMON /FLAGS/ RUNFLG,DFLAG,ERRFLG
0013 COMMON /SEND/ REPNUM,MSHOTS
0014 COMMON /STATS/ CSET,CPROF,LSET,LPROF
0015 COMMON/CONST/ PI,C,GATTIM,RG
0016 COMMON/BUFF/LDATA
C
0017 HDRB=9
0018 BINS=HBI-LBI+1
0019 RECSIZ=(BINS+HDRB+1)/2
0020 INTSIZ=IFIX(FLOAT(PROFS)*(BINS+HDRB)/256.+1.1)
C
C TYPE DATA RUN SCREEN
C
0021 5 CALL CLRSCN
0022 CALL DATE(IIDATE)
0023 CALL TIME(ITIME)
0024 TYPE 20,(IIDATE(I),I=1,9),(ITIME(J),J=1,8)
0025 TYPE 25,RECSIZ,INTSIZ
0026 TYPE 30
0027 20 FORMAT(' ',/T35,'DATA RUN',/T35,9A1,/T35,8A1,/)
0028 25 FORMAT(' ',/T5,'Disk Parameters:',/T8,'Recordsize = ',I4
    >,/T8,'Set Blocksize = ',I4,/)
0029 30 FORMAT(' ',/T5,'To begin a Data Run press "Y" then RETURN '
    >,$)
C =====
C GET & CHECK RESPONSE
C =====
0030 READ(5,80,ERR=5) OPT

```

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```

0031      80 FORMAT(A1)
0032      IF(OPT.NE.'Y') RETURN
C =====
C DATA RUN
C =====
0034      RUNFLG=1
C
C UPDATE SET FILE NAME
C
0035      ENCODE(3,100,EXT)CSET
0036      100 FORMAT(I3)
0037      DO 105 I=1,3
0038      FNAME(7+I)='0'
0039      105 IF(EXT(I).NE.' ')FNAME(7+I)=EXT(I)
C
C PARAMETER CALCULATIONS
C
0041      CALL JICVT(PDEL,DTIM)
0042      DTIM=60*DTIM
0043      DENOM=SIN(REANG)*RG
0044      B30=IFIX((30.+(RG/2.)-BSAT)/DENOM+.5)
0045      B60=IFIX((60.+(RG/2.)-BSAT)/DENOM+.5)
0046      S20=IFIX((20.+(RG/2.))/DENOM+.5)
0047      MSHOTS=SHOTSP
0048      REPNUM=IFIX((SQRT((1.02046*1.0E6/LREP-57251.)*4./15.+
>(5.4*5.4))-5.4)/2.+5)
C -----
C START DATA RUN
C -----
0049      LSET=CSET
0050      PRINT 115,CSET,(IIDATE(I),I=1,9),(ITIME(I),I=1,8)
0051      115 FORMAT(' ',T14,'SET # ',I4,11X,9A1,11X,8A1)
0052      REWIND 6
0053      OPEN(UNIT=3,TYPE='NEW',INITIALSIZE=INTSIZ,RECORDSIZE=RECSIZ
>,NAME=FNAME,ACCESS='DIRECT',FORM='UNFORMATTED')
C
C INIT FLAGS & START PROFILE RUN
C
0054      120 DFLAG=0
0055      EPRFLG=0
0056      CALL SNDCOM
C
C GET TIME AND DATE
C
0057      125 CALL GTIM(TIM2)
0058      CALL IDATE(MN,DAY,YR)
0059      CALL TIMASC(TIM2,ITIME)
0060      CALL DATE(IIDATE)
C
C WAIT FOR PROFILE
C
0061      130 ICHAR=ITTINR()
0062      JCHAR=ICHR
0063      IF(JCHAR.EQ.'S') GOTO 195

```

ORIGINAL PAGE 14
OF POOR QUALITY

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```

0065      IF(DFLAG.NE.1)GOTO 130
0067      IF(ERRFLG.EQ.1)GOTO 200
0069      CALL DISCAL
0070      WRITE(3'CPROF) BINS,LBI,CSET,CPROF,MN,DAY,YR,TIM2
          >,(LDATA(K),K=LBI,HBI)
C
C  UPDATE & CHECK COUNTERS
C
0071      LPROF=CPROF
0072      CPROF=CPROF+1
0073      IF(CPROF.GT.PROFS)GOTO 140
C
C  INTER-PROFILE DELAY
C
0075      CALL GTIM(TIML)
0076      CALL JJCUT(TIML)
0077      135 CALL GTIM(TIMH)
0078      CALL JJCUT(TIMH)
0079      CALL JSUB(TIMH,TIML,STIM)
0080      IF(STIM.LT.0)TIM2=0
0082      IF(DTIM.GT.STIM)GOTO 135
C
0084      DFLAG=0
0085      ERRFLG=0
0086      CALL SNDDTR
0087      GOTO 125
C
C  -----
C  SET COMPLETED
C  -----
0088      140 CLOSE(UNIT=3)
0089      CSET=CSET+1
0090      CPROF=1
0091      CALL FORSCN
0092      TYPE 150,LSET
0093      CALL BAKSCN
0094      PAUSE 'Press RETURN to continue'
0095      145 RETURN
0096      150 FORMAT(' ',///,' SET # ',I4,' -- COMPLETED')
C
C  =====
C  PROFILE ERROR
C  =====
C  CLEAR 'S' CHARACTER FROM KEYBOARD
0097      195 READ(5,80) OPT
C  ERROR ROUTINE
0098      200 CALL CLRSCN
0099      TYPE 210
0100      210 FORMAT(' ',/////,T11,'Do you want to close out the current
          > Data Set on disk ? ',%)
0101      READ(5,80) OPT
0102      IF(OPT.EQ.'Y') GOTO 140
0104      TYPE 220
0105      220 FORMAT(' ',///,T27,'Press RETURN to try again ',%)
0106      READ(5,80) OPT
0107      GOTO 120
0108      END

```

FORTTRAN IV Storage Map for Program Unit DATRUN

Local Variables, .PSECT \$DATA, Size = 000136 (47. words)

Name	Type	Offset	Name	Type	Offset	Name	Type	Offset
BINS	I*2	000034	DAY	I*2	000026	DENOM	R*4	000020
DTIM	I*4	000056	HDRB	I*2	000037	I	I*2	000066
ICHAR	I*2	000072	J	I*2	000070	JCHAR	L*1	000064
K	I*2	000074	MN	I*2	000024	MON	L*1	000063
OPT	L*1	000062	STIM	I*4	000052	TIMH	I*4	000046
TIML	I*4	000042	TIM2	I*4	000036	YR	I*2	000030

COMMON Block /DATTIM/, Size = 000021 (9. words)

Name	Type	Offset	Name	Type	Offset	Name	Type	Offset
IIDATE	L*1	000000	ITIME	L*1	000011			

COMMON Block /DISK /, Size = 000023 (10. words)

Name	Type	Offset	Name	Type	Offset	Name	Type	Offset
INTSIZ	I*2	000000	RECSIZ	I*2	000002	FNAME	L*1	000004

COMMON Block /PTERS /, Size = 000006 (3. words)

Name	Type	Offset	Name	Type	Offset	Name	Type	Offset
B30	I*2	000000	B60	I*2	000002	S20	I*2	000004

COMMON Block /LREPS /, Size = 000042 (17. words)

Name	Type	Offset	Name	Type	Offset	Name	Type	Offset
LREP	R*4	000000	LRI	R*4	000004	HRI	R*4	000010
LBI	I*2	000014	HBI	I*2	000016	BSAT	R*4	000020
BSATF	R*4	000024	EANG	R*4	000030	REANG	R*4	000034
PDEL	I*2	000040						

COMMON Block /SETS /, Size = 000006 (3. words)

Name	Type	Offset	Name	Type	Offset	Name	Type	Offset
SETS	I*2	000000	PROFS	I*2	000002	SHOTSP	I*2	000004

COMMON Block /FLAGS /, Size = 000003 (2. words)

Name	Type	Offset	Name	Type	Offset	Name	Type	Offset
RUNFLG	L*1	000000	DFLAG	L*1	000001	ERRFLG	L*1	000002

COMMON Block /SEND /, Size = 000004 (2. words)

Name	Type	Offset	Name	Type	Offset	Name	Type	Offset
REPNUM	I*2	000000	MSHOTS	I*2	000002			

COMMON Block /STATS /, Size = 000010 (4. words)

Name	Type	Offset	Name	Type	Offset	Name	Type	Offset
CSET	I*2	000000	CPROF	I*2	000002	LSET	I*2	000004
LPROF	I*2	000006						

FORTTRAN IV Storage Map for Program Unit DATRUN

COMMON Block /CONST /, Size = 000020 (8. words)

Name	Type	Offset	Name	Type	Offset	Name	Type	Offset
PI	R*4	000000	C	R*4	000004	GATTIM	R*4	000010
RG	R*4	000014						

COMMON Block /BUFF /, Size = 010150 (2100. words)

Name	Type	Offset	Name	Type	Offset	Name	Type	Offset
LDATA	I*2	000000						

Local and COMMON Arrays:

Name	Type	Section	Offset	Size	Dimensions
EXT	L*1	\$DATA	000000	000003 (2.)	(3)
FNAME	L*1	DISK	000004	000017 (8.)	(15)
IIDATE	L*1	DATTIM	000000	000011 (5.)	(9)
ITIME	L*1	DATTIM	000011	000010 (4.)	(8)
LDATA	I*2	BUFF	000000	010150 (2100.)	(2100)

Subroutines, Functions, Statement and Processor-Defined Functions:

Name	Type	Name	Type	Name	Type	Name	Type	Name	Type
BAKSCN	R*4	CLRSCN	R*4	DATE	R*4	DISCAL	R*4	FLOAT	R*4
FORSCN	R*4	GTIM	R*4	IDATE	I*2	IFIX	I*2	ITTINR	I*2
JICVT	I*2	JJCVT	I*2	JSUB	I*2	SIN	R*4	SNDCOM	R*4
SNDTR	R*4	SQRT	R*4	TIMASC	R*4	TIME	R*4		

III.8 EXMPRF

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```

C *****
C C
C SUBROUTINE EXMPRF - EXAMINE PROFILE
C D.VOELZ
C *****
C C
C THIS SUBROUTINE DISPLAYS A SELECTED PROFILE
C FROM THE DATA DISK ON THE TERMINAL AND PRINTER.
C
0001 SUBROUTINE EXMPRF
0002 INTEGER DSET,DPROF,BINS,LBI,CSET,CPROF,MN,DAY,YR
>,LDATA(2100),HDRB,NXTL,LSTL,ICNT,BCNT,BNMBR,INMBR
>,LNMBR,INTSIZ,RECSIZ
0003 INTEGER*4 TIM2
0004 LOGICAL*1 ITIME(8)
0005 BYTE FNAME(15),EXT(3),MON
C
0006 COMMON/BUFF/ LDATA
0007 COMMON/DISK/ INTSIZ,RECSIZ,FNAME
C
0008 HDRB=9
C=====
C RESPONSES
C=====
0009 CALL CLRSCN
0010 TYPE 15
0011 TYPE 20
0012 READ(5,*)DSET
0013 IF(DSET.EQ.0)RETURN
0015 TYPE 30
0016 READ(5,*)DPROF
0017 IF(DPROF.EQ.0)RETURN
0019 20 FORMAT(' ',T5,'SET # ',%)
0020 15 FORMAT(' ',T32,'EXAMINE PROFILE',///)
0021 30 FORMAT(' ',T5,'PROFILE # ',%)
C
C C
C SET FILE NAME
C
0022 ENCODE(3,50,EXT)DSET
0023 50 FORMAT(I3)
0024 DO 60 I=1,3
0025 FNAME(7+I)='0'
0026 60 IF(EXT(I).NE.' ')FNAME(7+I)=EXT(I)
C
C C
C DETERMINE RECORD SIZE
C
0028 OPEN(UNIT=3,TYPE='OLD',RECORDSIZE='2',NAME=FNAME,ACCESS=
>'DIRECT',FORM='UNFORMATTED',ERR=200)
0029 READ(3'1,ERR=210)BINS
0030 CLOSE(UNIT=3)
0031 RECSIZ=(BINS+HDRB+1)/2
C
C GET DATA

```


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```

C
0032 OPEN(UNIT=3,TYPE='OLD',RECORDSIZE=RECSIZ,NAME=FNAME,ACCESS=
>'DIRECT',FORM='UNFORMATTED',ERR=200)
0033 READ(3'DPROF,ERR=210)BINS,LBI,CSET,CPROF,MN,DAY,YR,TIM2
,:(LDATA(K),K=1,BINS)
0034 CLOSE(UNIT=3)
C-----
C DISPLAY
C-----
C
C CONVERT TIME
C
0035 CALL TIMASC(TIM2,ITIME)
0036 K=0
C-----
C DISPLAY ON TERMINAL
C-----
C
C SET UP PAGE
C
0037 70 TYPE 75,CSET,MN,DAY,YR,K+1
0038 75 FORMAT(' ', ' SET # ',I4,4X,I2,'-',I2,'-',I2,10X,I2)
0039 TYPE 77,CPROF,ITIME
0040 77 FORMAT(' ', ' PROFILE # ',I4,4X,BA1)
0041 NXTL=20
0042 ICNT=1+20C*K
0043 BCNT=LBI+ICNT-1
0044 IF(ICNT+199.GE.BINS)NXTL=(BINS-ICNT)/10
0046 IF(NXTL.EQ.0)GOTO 120
C
C TYPE FULL LINES
C
0048 DO 80 J=1,NXTL
0049 BNMBR=BCNT+10*(J-1)
0050 INMBR=ICNT+10*(J-1)
0051 LNMBR=ICNT+10*J-1
0052 80 TYPE 90,BNMBR,(LDATA(I),I=INMBR,LNMBR)
0053 90 FORMAT(' ',I5,'-',I6)
0054 IF(NXTL.NE.20)GOTO 120
0056 K=K+1
0057 PAUSE
0058 GOTO 70
C
C TYPE FINAL LINE
C
0059 120 TYPE 130,BNMBR+10
0060 130 FORMAT(' ',I5,'-',I6)
0061 DO 140 K=LNMBR+1,BINS
0062 140 TYPE 150,LDATA(K)
0063 150 FORMAT(I7,$)
0064 TYPE 160
0065 160 FORMAT(' ')
0066 PAUSE 'LAST PAGE'
C-----

```

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```

C PRINT OUT
C-----
0067 165 TYPE 170
0068 170 FORMAT('0',T20,'Do you want a printout ? ',)
0069 READ(5,175-ERR=165)MON
0070 175 FORMAT(A1)
0071 IF(MON.NE.'Y')GOTO 190

C
C SET UP PAGE
C
0073 PRINT 176,CSET,MN,DAY,YR
0074 176 FORMAT(' ',SET#',I4,4X,I2,'-',I2'-',I2)
0075 PRINT 77,CPROF,ITIME
0076 LSTL=IFIX(FLOAT(BINS)/10.+.99)

C
C PRINT LINES
C
0077 DO 177 J=1,LSTL
0078 BNMBR=LBI+10*(J-1)
0079 INMBR=1+10*(J-1)
0080 LNMBR=10*J
0081 PRINT 90,BNMBR,(LDATA(I),I=INMBR,LNMBR)
0082 177 CONTINUE
0083 REWIND 6

C
0084 190 RETURN

C-----
C ERROR CONDITIONS
C-----
0085 200 PAUSE '?? FILE OPENING ERROR'
0086 RETURN

C
0087 210 PAUSE '?? FILE READ ERROR'
0088 CLOSE(UNIT=3)
0089 RETURN

C
0090 END
```

FORTRAN IV Storage Map for Program Unit EXMPRF

Local Variables, .PSECT \$DATA, Size = 000130 (44. words)

Name	Type	Offset	Name	Type	Offset	Name	Type	Offset
BCNT	I*2	000060	BINS	I*2	000032	BNMBR	I*2	000062
CPROF	I*2	000040	CSET	I*2	000036	DAY	I*2	000044
DPROF	I*2	000030	DSET	I*2	000026	HDRB	I*2	000050
I	I*2	000076	ICNT	I*2	000056	INMBR	I*2	000064
J	I*2	000102	K	I*2	000100	LBI	I*2	000034
LNMBR	I*2	000066	LSTL	I*2	000054	MN	I*2	000042
MON	L*1	000074	NXTL	I*2	000052	TIM2	I*4	000070
YR	I*2	000046						

COMMON Block /BUFF /, Size = 010150 (2100. words)

Name	Type	Offset	Name	Type	Offset	Name	Type	Offset
LDATA	I*2	000000						

COMMON Block /DISK /, Size = 000023 (10. words)

Name	Type	Offset	Name	Type	Offset	Name	Type	Offset
INTSIZ	I*2	000000	RECSIZ	I*2	000002	FNAME	L*1	000004

Local and COMMON Arrays:

Name	Type	Section	Offset	Size	Dimensions
EXT	L*1	\$DATA	000010	000003 (2.)	(3)
FNAME	L*1	DISK	000004	000017 (8.)	(15)
ITIME	L*1	\$DATA	000000	000010 (4.)	(8)
LDATA	I*2	BUFF	000000	010150 (2100.)	(2100)

Subroutines, Functions, Statement and Processor-Defined Functions:

Name	Type	Name	Type	Name	Type	Name	Type	Name	Type
CLRSCN	R*4	FLOAT	R*4	IFIX	I*2	TIMASC	R*4		

III.9 DISCAL

FORTRAN IV

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```
C *****
C
C SUBROUTINE DISCAL.FOR - DATA CALCULATIONS AND DISPLAY
C                               D.VOELZ
C *****
C THIS SUBROUTINE PROCESSES INCOMING SODIUM LIDAR PROFILES.
C IT CALCULATES AND DISPLAYS PARTICULAR VALUES OF INTEREST.
C
0001 SUBROUTINE DISCAL
0002 INTEGER CSET,CPROF,LSET,LPROF,INTSIZ
    >,RECSIZ,B30,B60,S20,LDATA(2100),K30,K60,K80,K100
    >,SGP,TSGP,AK30,AK60,AK80,AK100,ASGP,ATS GP
    >,REPNUM,MSHOTS,LBI,HBI,PDEL
0003 REAL CLA,ACLA,RAYC,LREP,LRI,HRI,EANG,REANG,BSAT,BSATF
0004 LOGICAL*1 IDATE(9),ITIME(8)
0005 BYTE RUNFLG,DFLAG,ERRFLG
C
0006 COMMON /DATTIM/ IDATE,ITIME
0007 COMMON /STATS/ CSET,CPROF,LSET,LPROF
0008 COMMON /CALCS/ K30,K60,K80,K100,SGP,TSGP,CLA
0009 COMMON /FLAGS/ RUNFLG,DFLAG,ERRFLG
0010 COMMON /PTERS/ B30,B60,S20
0011 COMMON /BUFF/ LDATA
0012 COMMON /SEND/ REPNUM,MSHOTS
0013 COMMON /LREPS/ LREP,LRI,HRI,LBI,HBI,BSAT,BSATF,EANG,
    >REANG,PDEL
C
0014 CALL CLRSCN
C
C -----
C CALCULATIONS
C -----
0015 AK30=0
0016 AK60=0
0017 AK80=0
0018 AK100=0
C CALCULATE K30
0019 DO 10 I=1,5
0020 10 AK30=AK30+LDATA(B30-3+I)
0021 AK30=IFIX(FLOAT(AK30)/5+.5)
C CALCULATE K60,K80,100
0022 DO 20 I=1,S20
0023 AK60=AK60+LDATA(B60-1+I)
0024 AK80=AK80+LDATA(B60-1+I+S20)
0025 20 AK100=AK100+LDATA(B60-1+I+S20+S20)
C CALCULATE SIGNAL PHOTONS
0026 ATSGP=AK80-AK60
0027 ASGP=IFIX(FLOAT(ATSGP)/MSHOTS+.5)
C COLUMN ABUNDANCE RATIO
0028 RAYC=FLOAT(AK30)-FLOAT(AK60)/S20
0029 ACLA=0.
0030 IF(RAYC.LE.0.)GOTO 25
```

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```

0032            ACLA=FLOAT(ATSGP)/RAYC
C-----
C    CHECK RUN FLAG
C-----
0033            25 IF(RUNFLG.EQ.3)GOTO 30
C-----
C    DATA RUN DISPLAY
C-----
0035            K30=AK30
0036            K60=AK60
0037            K80=AK80
0038            K100=AK100
0039            SGP=ASGP
0040            TSGP=ATSGP
0041            CLA=ACLA
C
0042            TYPE 40
0043            TYPE 50,(IDATE(I),I=1,9),(ITIME(I),I=1,8)
0044            TYPE 60,CSET,CPROF
0045            TYPE 70,MSHOTS
0046            TYPE 72,BSAT
0047            TYPE 80,K30,K60,K80,K100
0048            TYPE 90,TSGP
0049            TYPE 100,SGP
0050            TYPE 110,CLA
C
0051            PRINT 50,(IDATE(I),I=1,9),(ITIME(I),I=1,8)
0052            PRINT 60,CSET,CPROF
0053            PRINT 70,MSHOTS
0054            PRINT 72,BSAT
0055            PRINT 80,K30,K60,K80,K100
0056            PRINT 90,TSGP
0057            PRINT 100,SGP
0058            PRINT 110,CLA
0059            PRINT 47
0060            REWIND 6
C
0061            RETURN
C-----
C    SODIUM ALIGNMENT RUN DISPLAY
C-----
0062            30 TYPE 45
0063            TYPE 50,(IDATE(I),I=1,9),(ITIME(I),I=1,8)
0064            TYPE 70,MSHOTS
0065            TYPE 72,BSAT
0066            TYPE 80,AK30,AK60,AK80,AK100
0067            TYPE 90,ATSGP
0068            TYPE 100,ASGP
0069            TYPE 110,ACLA
C
0070            RETURN
C-----
C    FORMAT STATEMENTS
C-----

```

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```

0071      40 FORMAT(' ',/T35,'DATA RUN',/)
0072      45 FORMAT(' ',/T30,'SODIUM ALIGNMENT RUN',/)
0073      47 FORMAT(' ',T23,'-----')
0074      ' ) FORMAT(' ',T35,9A1,/T35,8A1,)
0075      60 FORMAT(' ',T33,'Set # ',I4,/T33,'Profile # ',I4,/)
0076      70 FORMAT(' ',T23,'Laser Shots Per Profile =',I6)
0077      72 FORMAT(' ',T23,'Base Altitude Settings =',F6.2)
0078      80 FORMAT(' ',T23,'Detected Photons:',/T38,'at 30 Km =',I6,
>/T35,'60 - 80 Km =',I6,/T35,'80 - 100 Km =',I6,/T34,'100
> - 120 Km =',I6)
0079      90 FORMAT(' ',T23,'Total Signal Photons =',I6)
0080      100 FORMAT(' ',T23,'Signal Photons Per Shot =',I6)
0081      110 FORMAT(' ',T23,'Column Abundance Ratio =',F6.2)
0082      END

```

FORTRAN IV Storage Map for Program Unit DISCAL

Local Variables, .PSECT \$DATA, Size = 000070 (28. words)

Name	Type	Offset	Name	Type	Offset	Name	Type	Offset
ACLA	R*4	000036	AK100	I*2	000030	AK30	I*2	000022
AK60	I*2	000024	AK80	I*2	000026	ASGP	I*2	000032
ATSGP	I*2	000034	I	I*2	000046	INTSIZ	I*2	000016
RAYC	R*4	000042	RECSIZ	I*2	000020			

COMMON Block /DATTIM/, Size = 000021 (9. words)

Name	Type	Offset	Name	Type	Offset	Name	Type	Offset
IDATE	L*1	000000	ITIME	L*1	000011			

COMMON Block /STATS /, Size = 000010 (4. words)

Name	Type	Offset	Name	Type	Offset	Name	Type	Offset
CSET	I*2	000000	CPROF	I*2	000002	LSET	I*2	000004
LPROF	I*2	000006						

COMMON Block /CALCS /, Size = 000020 (8. words)

Name	Type	Offset	Name	Type	Offset	Name	Type	Offset
K30	I*2	000000	K60	I*2	000002	K80	I*2	000004
K100	I*2	000006	SGP	I*2	000010	TSGP	I*2	000012
CLA	R*4	000014						

COMMON Block /FLAGS /, Size = 000003 (2. words)

Name	Type	Offset	Name	Type	Offset	Name	Type	Offset
RUNFLG	L*1	000000	DFLAG	L*1	000001	ERRFLG	L*1	000002

COMMON Block /PTERS /, Size = 000006 (3. words)

Name	Type	Offset	Name	Type	Offset	Name	Type	Offset
B30	I*2	000000	B60	I*2	000002	S20	I*2	000004

COMMON Block /BUFF /, Size = 010150 (2100. words)

Name	Type	Offset	Name	Type	Offset	Name	Type	Offset
LDATA	I*2	000000						

COMMON Block /SEND /, Size = 000004 (2. words)

Name	Type	Offset	Name	Type	Offset	Name	Type	Offset
REPNUM	I*2	000000	MSHOTS	I*2	000002			

COMMON Block /LREPS /, Size = 000042 (17. words)

Name	Type	Offset	Name	Type	Offset	Name	Type	Offset
LREP	R*4	000000	LRI	R*4	000004	HRI	R*4	000010
LBI	I*2	000014	HBI	I*2	000016	BSAT	R*4	000020
BSATF	R*4	000024	EANG	R*4	000030	REANG	R*4	000034
PDEL	I*2	000040						

FORTRAN IV Storage Map for Program Unit DISCAL

Local and COMMON Arrays:

Name	Type	Section	Offset	-----Size-----	Dimensions
IDATE	L*1	DATTIM	000000	000011 (5.)	(9)
ITIME	L*1	DATTIM	000011	000010 (4.)	(8)
LDATA	I*2	BUFF	000000	010150 (2100.)	(2100)

Subroutines, Functions, Statement and Processor-Defined Functions:

Name	Type	Name	Type	Name	Type	Name	Type	Name	Type
CLRSCN	R*4	FLOAT	R*4	IFIX	I*2				

III.10 RCVER

RCVER.MAC MACRO V04.00 31-MAY-83 15:40:37 PAGE 1

```

1
2
3
4
5
6
7
8
9
10 000000
11
12
13
14          176500
15          176502
16          000300
17          000302
18
19
20
21          000340
22          000003
23          000063
24          000064
25          000071
26          000201
27          000202
28          000203
29          000220
30
31
32
33          000120
34          000340
35          003720
36
37
38
39
40 000000
41 000020 012737 000062' 000300
42 000026 012737 000340 000302
43 000034 012767 000144' 000000'
44 000042 000207
45
46
47
48 000044 012701 000000'
49 000050 012702 007640
50 000054 004767 000000G
51 000060 000207
52
53
54
55
56
57

```

```

*****
LSI-11 RECEIVER
D.VOELZ
*****
.TITLE RCVER.MAC
.MCALL .INTEN,.PROTECT
.GLOBL HDUMP,SNACK,INITR,MOUT
.CSECT RCVER

I/O LOCATIONS
RCSR=176500          ;DLV11-J CHN.0 LOCATIONS
RBUF=RCSR+2
PCVEC=300
STVEC=PCVEC+2

GENERAL PARAMETERS
PR7=340              ;PRIORITY LEVEL 7
ERRCNT=3             ;ERROR COUNT
PRDONE=063          ;OPCODES-PROFILE DONE
ACK=064              ;      -ACKNOWLEDGE
DATEND=071          ;      -END OF DATA
CTX=201              ;'CTX' CHAR
ETX=202              ;'ETX' CHAR
STX=203              ;'STX' CHAR
DLE=220              ;'DLE' CHAR

DATA PACKET PARAMETERS
OPCLO=120            ;LO BYTE DATA OPCODE
OPCHI=340            ;HI BYTE DATA OPCODE
PAKLEN=2000.         ;PACKET LENGTH (MAX=32767)

-----
INITIALIZE RECEIVER
-----
INITR:: .PROTECT      #PAREA:#300
        MOV    #IOINT,#PCVEC ;SET UP PC VECTOR
        MOV    #PR7,#STVEC  ;SET UP STATUS WORD VECTOR
        MOV    #STPAK1,STATE ;SET INPUT BYTE VECTOR
        RTS    PC

-----
HEX MEMORY DUMP OF ARRAY LDATA
-----
MOUT::  MOV    #LDATA,R1
        MOV    #4000.,R2
        JSR    PC,HDUMP
        RTS    PC

-----
INTERRUPT POINTS
-----
INTERRUPT ENTRY POINT

```

RCVER.MAC MACRO V04.00 31-MAY-81 15:40:37 PAGE 1-1

```

58
59 00006z
60 000070 010046
61 000072 010146
62 000074 010246
63 000076 010346
64
65 000100 016701 000000'
66
67 000104 113700 176502
68 000110 000111
69
70
71
72 000112 042700 177400
73 000116 060067 000002'
74
75 000122 012667 000000'
76
77 000126 012603
78 000130 012602
79 000132 012601
80 000134 012600
81 000136 000207
82
83
84
85
86 000140 004767 177746
87 000144 120027 000220
88 000150 001373
89
90 000152 004767 177734
91 000156 120027 000203
92 000162 001366
93 000164 005067 000002'
94
95 000170 004767 177716
96 000174 110067 000016'
97
98
99
100 000200 004767 177706
101 000204 004767 177702
102 000210 016767 000002' 000004'
103
104 000216 004767 177670
105 000222 120067 000004'
106 000226 001344
107 000230 004767 177656
108 000234 000367 000004'
109 000240 120067 000004'
110 000244 001335
111
112
113
114 000246 116701 000016'

```

```

;
;IOINT: .INTEN 7 ;ALERT RT-11 OF INTERRUPT
;MOV R0,-(SP) ;SAVE REGISTERS
;MOV R1,-(SP)
;MOV R2,-(SP)
;MOV R3,-(SP)
;
; MOV STATE,R1 ;MOVE INPUT BYTE VECTOR TO R1
;
; MOVB @RBUF,R0 ;LOAD R0 WITH INPUT BYTE
; JMP (R1) ;GO TAKE CARE OF INPUT BYTE
;
;
; INTERRUPT EXIT POINT
;
GETBT: BIC #177400,R0 ;CLEAR HI BYTE OF R0
; ADD R0,RCSUM ;UPDATE RECD CHECKSUM
;
; MOV (SP)+,STATE ;SET NEW INPUT BYTE VECTOR
;
; MOV (SP)+,R3 ;RESTORE REGISTERS
; MOV (SP)+,R2
; MOV (SP)+,R1
; MOV (SP)+,R0
; RTS PC
;
;-----
; PACKET RECEIVING
;-----
STPAK: JSR PC,GETST
STPAK1: CMPB R0,#DLE ;CHECK FOR 'DLE' BYTE
; BNE STPAK
;
; JSR PC,GETBT
; CMPB R0,#STX ;CHECK FOR 'STX' BYTE
; BNE STPAK
;
OPPAK: CLR RCSUM ;CLEAR RECD CHECKSUM ACCUMULATOR
;
; JSR PC,GETBT ;GET OP CODE
; MOVB R0,OPCDE ; SAVE IT
;
;
; VERIFY CHECKSUM
;
VERCHK: JSR PC,GETBT ;GET 'DLE' BYTE
; JSR PC,GETBT ;GET 'STX' BYTE
; VERIFY: MOV RCSUM,SAVSUM ;SAVE RECD CHECKSUM
;
;
; JSR PC,GETBT ;GET LO BYTE XMITTED CHECKSUM
; CMPB R0,SAVSUM ; CHECK IT
; BNE STPAK
;
; JSR PC,GETBT ;GET HI BYTE XMITTED CHECKSUM
; SWAB SAVSUM
; CMPB R0,SAVSUM ; CHECK IT
; BNE STPAK
;
;
; DECIPHER OP CODE
;
; MOVB OPCDE,R1 ;MOVE OP CODE TO R1

```

RCVER.MAC MACRO V04.00 31-MAY-83 15:40:37 PAGE 1-2

```

115
116 000252 122701 000064      ;      CMPB   #ACK,R1      ; ACK ?
117 000256 001433              ;      DEB    ACKN
118 000260 122701 000071      ;      CMPB   #DATEND,R1  ; DAT.. PACKET COMPLETED ?
119 000264 001003              ;      BNE    PRFCHK      ; -NO,GO ON
120 000266 004767 000000G     ;      JSR    PC,SENDACK  ; -YES,SEND ACK
121 000272 000722              ;      BR     STPAK
122 000274 122701 000063      ;      PRFCHK: CMPB   #PRDONE,R1  ; PROFILE COMPLETED ?
123 000300 001011              ;      BNE    DATCHK      ; -NO,GO ON
124 000302 004767 000000G     ;      JSR    PC,SENDACK  ; -YES,SEND ACK
125 000306 112767 000001 000001' ;      MOVB  #1,DFLAG      ; SET DATA RUN FLAG
126 000314 042737 000100 171500 ;      BIC  #100,@#RCSR    ; DISABLE DLV11-J INTERRUPT
127 000322 000706              ;      BR     STPAK
128 000324 042701 000017      ;      DATCHK: BIC  #17,R1  ; CLEAR LOWER 4 BITS OF OPCODE
129 000330 122701 000120      ;      CMPB  #OPCLO,R1    ; LOW BYTE DATA ?
130 000334 001410              ;      SEB   LBYTES
131 000336 122701 000340      ;      CMPB  #OPCHI,R1    ; HI BYTE DATA ?
132 000342 001410              ;      BEB   HBYTES
133 000344 000675              ;      BR     STPAK      ;BAD OPCODE
134
135
136      -----
137      RECEIVED ACKNOWLEDGE
138      -----
138 000346 112767 000001 000000' ;      ACKN: MOVB  #1,ACKFLG  ;SET ACK FLAG
139 000354 000671              ;      BR     STPAK
140
141      -----
142      RECEIVE DATA FRAME
143      -----
144
145      -----
146      DETERMINE BASE ADDRESS FOR DATA FRAME
146 000356 012704 000000'     ;      LBYTES: MOV  #LDATA,R4  ;SET BASE ADDRESS FOR LO BYTES
147 000362 000402              ;      BR     DATFRM
148 000364 012704 000001'     ;      HBYTES: MOV  #<LDATA+1>,R4 ;SET BASE ADDRESS FOR HI BYTES
149
150 000370 012703 007640      ;      DATFRM: MOV  #<2*PACKLEN>,R3 ;MOVE DOUBLE PACKET LENGTH INTO R3
151 000374 116701 000016'     ;      MOVB  OPCDE,R1      ;MOVE OPCODE INTO R1
152 000400 112767 000071 000016' ;      MOVB  #DATEND,OPCDE ;LOAD 'DATEND' OPCODE
153
154 000406 042701 177760      ;      BIC  #177760,R1    ;CLEAR HI 12 BITS OF OPCODE
155 000412 070301              ;      MUL  R1,R3          ;MULT. ADJSTD. OPCODE & DBL. PACKET LENGTH
156 000414 060304              ;      ADD  R3,R4          ;ADD ADDRESS BASE & ADDRESS OFFSET
157 000416 010467 000006'     ;      MOV  R4,STADD      ;SAVE DATA PACKET STARTING ADDRESS
158
159      -----
160      RECEIVE DATA BYTES
161 000422 004767 177464      ;      JSR    PC,GETBT
162 000426 120027 000220      ;      CMPB  R0,#DLE      ;CHECK FOR 'DLE' CHARACTER
163 000432 001242              ;      BNE    STPAK
164
165 000434 004767 177452      ;      JSR    PC,GETBT
166 000440 120027 000201      ;      CMPB  R0,#CTX      ;CHECK FOR 'CTX' CHARACTER
167 000444 001235              ;      BNE    STPAK
168 000446 005067 000002'     ;      CLR  RCSUM        ;CLEAR RECD CHECKSUM ACCUMULATOR
169
170 000452 004767 177434      ;      DATA: JSR    PC,GETBT  ;GET DATA BYTE
171 000456 120027 000220      ;      CMPB  R0,#DLE      ; CHECK FOR 'DLE' CHARACTER

```


RCVER.MAC MACRO V04.00 31-MAY-83 15:40:37 PAGE 1-4
SYMBOL TABLE

ACK = 000064	DLE = 000220	BYTES 000356R	002 PCVEC = 000300	STADD 000006R	003
ACKFLG 000000R	004 ENDIT 000514R	002 LDATA 000000R	005 PRDNE = 000063	STATE 000000R	003
ACKN 000346R	002 ERRCNT = 000003	ROUT 000044RG	002 PRFCHK 000274R	002 STPAK 000140R	002
CHKDBL 000502R	002 ERRFLG 000002R	006 OKDBL 000464R	002 PR7 = 000340	STPAK1 000144R	002
CTX = 000201	ETX = 000202	OPCDE 000016R	003 RBUF = 176502	STVEC = 000302	
DATA 000452R	002 GETBT 000112R	002 OPCHI = 000340	RCSR = 176500	STX = 000203	
DATCHK 000324R	002 HBYTES 000364R	002 OPCLO = 000120	RCSUM 000002R	003 VERCHK 000200R	002
DATEND = 000071	HDUMP = ***** G	OPPAK 000164R	002 RUNFLG 000000R	006 VERIFY 000210R	002
DATFRM 000370R	002 INITR 000000RG	002 PAKLEN = 003720	SAVSUM 000004R	003 ...V1 = 000003	
DFLAG 000001R	006 IDINT 000062R	002 PAREA 000016R	003 SNDACK = ***** G		

. ABS. 000000 000
000000 001
RCVER 000526 002
RCV 000017 003
ACKFLG 000001 004
BUFF 010150 005
FLAGS 000003 006
ERRORS DETECTED: 0

VIRTUAL MEMORY USED: 9216 WORDS (36 PAGES)
DYNAMIC MEMORY AVAILABLE FOR 54 PAGES
RCVER.LP:=RCVER.MAC

III.1J SENDER

SENDER.MAC MACRO V04.00 31-MAY-83 15:45:58 PAGE 1

ORIGINAL PAGE IS
OF POOR QUALITY

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1
2
3
4
5
6
7
8
9
10 000000
11
12
13
14          176500
15          176502
16          176504
17          176506
18
19
20
21          000003
22          000061
23          000062
24          000064
25          000201
26          000202
27          000203
28          000220
29
30
31
32
33
34
35
36
37
38
39
40
41
42
43
44
45
46
47
48
49
50
51 000000 112767 000064 000002'
52 000006 004767 000162
53 000012 000207
54
55
56
57

```

```

*****
LSI-11 SENDER
D.VOELZ
*****
.TITLE SENDER.MAC
.MCALL .TTYOUT,.PRINT,.TTYIN
.SLOBL SNDACK,SNDPTR,SPDCOM,CLRSCN
.CSECT SENDER
;
; I/O LOCATIONS
RCSR=176500 ;DLV11-J CHN.C LOCATIONS
RBUF=RCSR+2
XCSR=RCSR+4
XBUF=RCSR+6
;
; GENERAL PARAMETERS
ERRCNT=3 ;ERROR COUNT
DRUN=061 ;OPCODES-DATA RUN
COM=062 ; -COMMANDS
ACK=064 ; -ACKNOWLEDGE
CTX=201 ;'CTX' CHAR
ETX=202 ;'ETX' CHAR
STX=203 ;'STX' CHAR
DLE=220 ;'DLE' CHAR
;
; MACRO DIRECTIVE - AKWAIT
; THIS MACRO DIRECTIVE IS THE TIME-OUT LOOP FOR AN
; ACKNOWLEDGE. IF THE ACKNOWLEDGE FLAG (ACKFLG) IS
; NOT SET WHILE THE ROUTINE IS IN ITS LOOP, PROGRAM
; CONTROL JUMPS TO THE ERROR ROUTINE 'ERROUT'.
;
; .MACRO AKWAIT JMPADD,?A,?B,?C
; MOV 2000,R0
A: CMPB ACKFLG,#1
; BEB C
; DEC R0
; BNE A
B: DEC R3
; BNE JMPADD
; JMP ERROUT
C: NOP
; .ENDM AKWAIT
;
;-----
; SEND ACKNOWLEDGE
;-----
SNDACK: MOVB #ACK,OPCODE ;LOAD 'ACK' OPCODE
; JSR PC,SNDFRM ;SEND ACK FRAME
; RTS PC
;
;-----
; SEND DATA RUN FRAME
;-----

```

SENDER.MAC MFJRO V04.00 31-MAY-83 15:45:58 PAGE 1-1

```

58 000014 052737 000100 176500 SNDDTR: BIS #100, @#RCSR
59 000022 112767 000061 000002' MOV #DRUN, OPCDE ;LOAD 'DRUN' OPCODE
60 000030 012703 000003 MOV #ERRCNT, R3 ;SET ERROR COUNT
61 000034 105067 000000' SNDR1: CLR ACKFLG ;CLEAR ACK FLAG
62 000040 004767 000130 JSR PC, SNDFRM ;SEND DATA RUN FRAME
63 000044 AKWAIT SNDR1 ;WAIT FOR ACK
64 000076 000207 RTS PC
65
66 -----
67 SEND COMMANDS FRAME
68 -----
69 000100 052737 000100 176500 SNDCOM: BIS #100, @#RCSR
70 000106 112767 000062 000002' MOV #COM, OPCDE ;LOAD 'COMMANDS' OPCODE
71 000114 012703 000003 MOV #ERRCNT, R3 ;SET ERROR COUNT
72 000120 105067 000000' SNCOM1: CLR ACKFLG ;CLEAR ACK FLAG
73 000124 004767 000044 JSR PC, SNDFRM ;SEND COMMANDS FRAME PART 1
74 000130 004767 000132 JSR PC, SNDCM2 ;SEND COMMANDS FRAME PART 2
75 000134 AKWAIT SNCOM1
76 000166 004767 177622 JSR PC, SNDDTR ;SEND DATA RUN FRAME
77 000172 000207 RTS PC
78
79 -----
80 GENERAL PACKET SENDING ROUTINE
81 -----
82 000174 112700 000220 SNDFRM: MOV #DLE, R0
83 000200 004767 000146 JSR PC, SNDBYT ;SEND 'DLE' CHARACTER
84 000204 005001 CLR R1 ;CLEAR XMIT CHECKSUM
85
86 MOV #STX, R0
87 000212 004767 000126 JSR PC, UPDTCK ;UPDATE XMIT CHECKSUM & SEND 'STX'
88
89 MOV OPCDE, R0
90 000222 004767 000116 JSR PC, UPDTCK ;UPDATE XMIT CHECKSUM & SEND OPCODE
91
92 ENDER: MOV #DLE, R0
93 000232 004767 000106 JSR PC, UPDTCK ;UPDATE XMIT CHECKSUM & SEND 'DLE'
94
95 MOV #ETX, R0
96 000242 004767 000104 JSR PC, SNDBYT ;SEND 'ETX' CHARACTER
97
98 SNDCM1: MOV R1, R0 ;SEND XMIT CHECKSUM
99 000250 004767 000076 JSR PC, SNDBYT ; LO BYTE
100 000254 000301 SWAB R1
101 000256 110100 MOV R1, R0
102 000260 004767 000066 JSR PC, SNDBYT ; HI BYTE
103 000264 000297 RTS PC
104
105 -----
106 SEND COMMANDS FRAME PART 2
107 -----
108 000266 112700 000220 SNDCM2: MOV #DLE, R0
109 000272 004767 000J54 JSR PC, SNDBYT ;SEND 'DLE' CHARACTER
110 000276 005001 CLR R1 ;CLEAR XMIT CHECKSUM
111
112 MOV #CTX, R0
113 000300 112700 000201 JSR PC, UPDTCK ;UPDATE XMIT CHECKSUM & SEND 'CTX'
114 000304 004767 000034

```

SENDER.MAC MACRO V04.00 31-MAY-83 15:45:58 PAGE 1-2

```

115 000310 116700 000000'      MOVB  REPNUM,RO
116 000314 004767 000024      JSR   PC,UPDTCK      ;SEND REP NUMBER
117                               ;
118 000320 116700 000002'      MOVB  MSHOTS,RO      ;SEND MSHOTS
119 000324 004767 000014      JSR   PC,UPDTCK      ; LO BYTE
120 000330 016700 000002'      MOV   MSHOTS,RO
121 000334 000300              SWAB  RO
122 000336 004767 000002      JSR   PC,UPDTCK      ; HI BYTE
123                               ;
124 000342 000731              BR    ENDER          ;SEND PACKET ENDER
125                               ;
126                               ;
127                               ;
128                               ;-----
129                               ; UPDATE CHECKSUM & SEND BYTE
130                               ; ROUTINES
131                               ;-----
131 000344 042700 177400      UPDTCK: BIC  #177400,RO ;CLEAR HI BYTE OF RO
132 000350 060001              ADD   RO,R1          ;UPDATE CHECKSUM
133                               ;
134 000352 032737 000200 176504 SNDBYT: BIT  #200,@#XCSR ;CHECK STATUS REG
135 000360 001774              BEQ  SNDBYT
136 000362 110037 176506      MOVB  RO,@#XBUF     ;OUTPUT RO
137 000366 000207              RTS   PC
138                               ;
139                               ;
140                               ;-----
141                               ; ERROR MESSAGE
142                               ;-----
142 000370 004767 000000G      ERROUT: JSR  PC,CLRSCN
143 000374              .PRINT #ERRMSG
144 000402              .TTYIN
145 000406 110001              MOVB  RO,R1          ;GET RESPONSE
146 000410              .TTYIN
147 000414              .TTYIN
148 000420 120127 000131      CMPB  R1,#'Y        ;STORE IT
149 000424 001002              BNE  EDONE          ;PICK UP LF
150 000428 000167 177446      JMP  SNDCCM        ;PICK UP CR
151 000432 112767 000001 000001' EDONE: MOVB  #1,DFLAG     ;CHECK RESPONSE
152 000440 112767 000001 000002'      MOVB  #1,ERRFLG    ;SET DONE FLAG
153 000446 042737 000100 176500      BIC  #100,@#RCSR   ;SET ERROR FLAG
154 000454 000207              RTS   PC          ;DISABLE DLV:1-J INTERRUPT
155                               ;
156 000000              .PSECT MSGR,RW,D,LCL,REL,COM
157 000000 015 012 012 012      ERRMSG: .BYTE 15,12,12,12,12,12,12,12
158 000003 012 012 012
159 000006 012 012 012
160 000011 040 040 040          .ASCII /
161 000014 040 040 040          COMMAND TRANSMISSION ERROR/
162 000017 040 040 040
163 000022 040 040 040
164 000025 040 040 040
165 000030 040 040 040
166 000033 040 040 040
167 000036 040 040 040
168 000041 040 040 040
169 000044 103 117 115
170 000047 115 101 116
171 000052 104 040 124

```


ORIGINAL PAGE IS
OF POOR QUALITY

SENDER.MAC MACRO V04.00 31-MAY-83 15:45:58 PAGE 1-3

000055	122	101	116		
000060	123	115	111		
000063	123	123	111		
000066	117	116	040		
000071	105	122	122		
000074	117	122			
159 000076	015	012	012	.BYTE	15,12,12
160 000101	040	040	040	.ASCII	/
000104	040	040	040		
000107	040	040	040		
000112	040	040	040		
000115	040	040	040		
000120	040	040	040		
000123	040	040			
161 000125	040	040	040	.ASCII	/
000130	040	040	040		TRY AGAIN ? /<200>
000133	040	040	040		
000136	040	040	040		
000141	040	040	124		
000144	122	131	040		
000147	101	107	101		
000152	111	116	040		
000155	077	040	200		
000160	000				
162					
163 000000				.PSECT	CCM,RW,D,LCL,REL,CON
164 000000				XCSUM:	.BLKW 1
165 000002				OPCDE:	.BLKB 1
166					
167 000000				.PSECT	ACKFLG,RW,D,GBL,REL,DVR
168 000000				ACKFLG:	.BLKB 1
169					
170 000000				.PSECT	FLAGS,RW,D,GBL,REL,DVR
171 000000				RUNFLG:	.BLKB 1
172 000001				DFLAG:	.BLKB 1
173 000002				ERRFLG:	.BLKB 1
174					
175 000000				.PSECT	SEND,RW,D,GBL,REL,DVR
176 000000				REPNUM:	.BLKW 1
177 000002				MSHOTS:	.BLKW 1
178					
179	000001				.END

ORIGINAL PAGE IS
OF POOR QUALITY

SENDER.MAC MACRO V04.00 31-MAY-83 15:45:58 PAGE 1-4
SYMBOL TABLE

ACK = 000064	DRUN = 000061	ETX = 000202	SNCOM1 000120R	002 SNDFRM	000174R	002
ACKFLG 000000R	005 EDONE 000432R	002 MSHCTS 000002R	007 SNDAK 000000RG	002 SNDTR1	000034R	002
CLRSCN= ***** G	ENDER 000226R	002 OPCDE 000002R	004 SNDBYT 000352P	002 STX =	000203	
COM = 000062	ERRCNT= 000003	RBUF = 176502	SNDCHK 000246R	002 UPDTCK	000344R	002
CTX = 000201	ERRFLG 000002R	006 RCSR = 176500	SNDCH2 000266R	002 XBUF =	176506	
DFLAG 000001R	006 ERMSG 000000R	003 REPNUM 000000R	007 SNDCOM 000100RG	002 XCSR =	176504	
DLE = 000220	ERRQUT 000370R	002 RUNFLG 000000R	006 SNDDTR 000014RG	002 XCSUM	000000R	004

. ABS. 000000 000
000000 001
SENDER 000456 002
MSGR 000161 003
CCM 000003 004
ACKFLG 000001 005
FLAGS 000003 006
SEND 000004 007
ERRORS DETECTED: 0

VIRTUAL MEMORY USED: 8704 WORDS (34 PAGES)
DYNAMIC MEMORY AVAILABLE FOR 54 PAGES
SENDER.LP:=SENDER.MAC

III.12 DISPLY

DISPLY.MAC MACRO V04.00 31-MAY-83 16:02:57 PAGE 1

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9
10
11
12
13
14
15
16
17 000000
18
19      000033
20      000155
21
22
23
24
25 000000 012701 000054'
26 000004 000413
27 000006 012701 000064'
28 000012 000410
29 000014 012701 000071'
30 000020 000405
31 000022
32 000032 000207
33
34
35
36 000034 111100
37 000036
38 000042 005201
39 000044 121127 000000
40 000050 001371
41 000052 000207
42
43
44
45 000054      033      133      062 CLRSTR: .BYTE ESC,'L','2','J',ESC,'L','H',0
   000057      112      033      133
   000062      110      000
46 000064      033      133      067 FORSTR: .BYTE ESC,'L','7',LCM,0
   000067      155      000
47 000071      033      133      060 BAKSTR: .BYTE ESC,'L','0',LCM,0
   000074      155      000
48 000076      007
49
50      000001

```

```

*****
DISPLY.MAC - VT100 TERMINAL DISPLAY ROUTINES
D.VOELZ
*****

THIS SUBPROGRAM SETS UP THE DISPLAY OF THE VT100
FAMILY OF TERMINALS. THE SUBROUTINES ARE AS FOLLOWS:
CLRSCN - CLEAR SCREEN, CURSOR TO HOME
FORSCN - INVERSE VIDEO
BAKSCN - NORMAL VIDEO
BELSCN - RING THE BELL

.TITLE DISPLY.MAC
.MCALL .TTYOUT
.CSECT DISPLY

;
ESC=033
LCM=155
;
-----
VT100 DISPLAY SUBROUTINES
-----
CLRSCN::MCJ #CLRSTR,R1
        BR   OUT
FORSCN::MOV #FORSTR,R1
        BR   OUT
BAKSCN::MOV #BAKSTR,R1
        BR   OUT
BELSCN::TTYOUT BELL
        RTS  PC
;
-----
ASCII STRING OUTPUT SECTION
-----
OUT:   MOVB (R1),R0
        .TTYOUT
        INC  R1
        CMPB (R1),#0
        BNE  OUT
        RTS  PC
;
-----
ASCII STRINGS
-----

```

DISPLY.MAC MACRO V04.00 31-MAY-83 16:02:57 PAGE 1-1
 SYMBOL TABLE

BAKSCN	000014RG	002	BELSCN	000022RG	002	CLRSTR	000054R	002	FORSCN	000006RG	002	LCH	=	000155	
BAKSTR	000071R	002	CLRSCN	000000RG	002	ESC	=	000033	FORSTR	000064R	002	OUT		000034R	002
BELL	000076R	002													
. ABS.	000000	000													
	000000	001													
DISPLY	000077	002													
ERRORS DETECTED:	0														

VIRTUAL MEMORY USED: 8192 WORDS (32 PAGES)
 DYNAMIC MEMORY AVAILABLE FOR 54 PAGES
 DISPLY.LP:=DISPLY

III.13 HDUMP

HDUMP.MAC MACRO V04.00 31-MAY-83 16:04:36 PAGE 1

```

1
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11
12
13
14
15
16
17 000000 111103
18 000002 004767 000020
19 000006
20 000016 005201
21 000020 005302
22 000022 001366
23 000024 000207
24
25 000026 110346
26 000030 072327 177774
27 000034 004767 000010
28 000040 112603
29 000042 004767 000002
30 000046 000207
31
32 000050 142703 000360
33 000054 120327 000012
34 000060 100403
35 000062 062703 000067
36 000066 000402
37 000070 062703 000060
38 000074 110300
39 000076
40 000102 000207
41
42 000104 040
43
44 000001

```

```

*****
HEX MEMORY DUMP PROGRAM
D.VOELZ
*****

THIS SUBPROGRAM DUMPS A SECTION OF THE LSI-11
MEMORY IN HEXADECIMAL FORM.
--- LOAD R1 WITH STARTING MEMORY ADDRESS
--- LOAD R2 WITH BYTE COUNT

.TITLE HDUMP.MAC
.MCALL .TTYOUT
;
;
HDUMP:: MOVB (R1),R3 ;LOAD R3 WITH DATA BYTE
        JSR PC,HEXDUT ;OUTPUT BYTE IN HEX
        .TTYOUT SPACE ;OUTPUT SPACE
        INC R1
        DEC R2
        BNE HDUMP ;LAST BYTE ?
        RTS PC
;
HEXDUT: MOVB R3,-(SP) ;SAVE BYTE
        ASH #4,R3 ;SELECT HI 4 BITS
        JSR PC,SEND ;SEND IT
        MOVB (SP)+,R3 ;RETRIEVE BYTE
        JSR PC,SEND ;SEND LO 4 BITS
        RTS PC
;
SEND: BICB #360,R3 ;CLEAR HI 4 BITS (OF BYTE)
      CMPB R3,#10. ;VALUE LESS THAN 10 ?
      BMI LT10 ; -YES,GOTO LT10
      ADD #'A-10.,R3 ;ADD BASE ALPHANUMERIC OFFSET
      BR OUT
LT10: ADD #'0,R3 ;ADD BASE NUMBER OFFSET
OUT: MOVB R3,R0
     .TTYOUT ;OUTPUT CHARACTER
     RTS PC
;
SPACE: .ASCII / / ;ASCII SPACE
;
.END

```

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HDUMP.MAC MACRO V04.00 31-MAY-83 16:04:36 PAGE 1-1
SYMBOL TABLE

HDUMP	000000RG	LT10	000070R	DLT	000074R	SEND	000050R	SPACE	000104R
HEXOUT	000026R								

. ABS. 000000 000
 000105 001

ERRORS DETECTED: 0

VIRTUAL MEMORY USED: 8192 WORDS (32 PAGES)
DYNAMIC MEMORY AVAILABLE FOR 54 PAGES
HDUMP,LP:=HDUMP

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III.14 CONVRT

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```

C *****
C PROGRAM CONVRT FOR - DATA CONVERSION
C      6-APR-83
C      D.VOELZ
C *****
C THIS PROGRAM CONVERTS BINARY FILES OF LIDAR
C DATA TO ASCII FILES. THIS IS NECESSARY FOR
C THE TRANSFER OF DATA TO THE CYBER.
C THE PROGRAM ALSO ALLOWS THE GROUND SPEED (KTS),
C ALTITUDE (FT), LATITUDE (DEG.-MIN), AND
C LONGITUDE (DEG.-MIN) TO BE ADDED TO THE ASCII
C FILE.
C
C THE ASCII FILE FORMAT IS AS FOLLOWS:
C
C WRITE(4,120)BINS,LBI,CSET,CPROF,MN,DAY,YR,HRS,MINS,SECS
C 120 FORMAT(4I5,6I3)
C
C WRITE(4,125)GSPD,ALT,LAT,LONG
C 125 FORMAT(I5,F7.3,2F7.1)
C
C WRITE(4,128)(LDATA(I),I=1,BINS)
C 128 FORMAT(12(I5))
C
C *** NOTE *** IN THE PROGRAM ALL THE FORMAT STATEMENTS ABOVE
C BEGIN WITH A '1X'. THIS IS SIMPLY THE CONTROL
C CHARACTER.
C
0001 PROGRAM CONVRT
0002 INTEGER DSET,NPROF,GSPD(99),MN,DAY,YR,LDATA(2100)
0003 INTEGER HDRB,BINS,INTSIZ,LBI,RECSIZ,CSET,CPROF
0004 INTEGER HRS,MINS,SECS
0005 REAL ALT(99),LAT(99),LONG(99)
0006 LOGICAL*1 DEVF(4),DEVT(4),EXT(3),NAMEF(15),NAMET(15)
0007 LOGICAL*1 ITIME(8)
0008 INTEGER*4 JTIM
C =====
C INPUTS
C =====
C
C INITIAL VALUES
C
0009 HDRB=9
0010 DATA NAMEF/0,0,0,0,'S','E','T',0,0,0,' ','D','A','T',0/
0011 DATA NAMET/0,0,0,0,'S','E','T',0,0,0,' ','A','S','C',0/
C
C GET INITIAL RESPONSES (DEVICE,SET #,# OF PROFILES)
C
0012 TYPE 10
0013 READ(5,15) (DEVF(I),I=1,4)
0014 TYPE 20

```

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```

0015 READ(5,15) (DEVT(I),I=1,4)
0016 27 TYPE 30
0017 READ(5,*) DSET
0018 TYPE 40
0019 READ(5,*) NPROF
C
0020 10 FORMAT(' ',T32,'DATA CONVERSION',///T5,'DEVICE:',/T5
>,' From ? ',%)
0021 15 FORMAT(4A1)
0022 20 FORMAT(' ',T5,' To ? ',%)
0023 30 FORMAT('0',/T5,'SET # ? ',%)
0024 40 FORMAT(' ',T5,'TOTAL # OF PROFILES IN SET ? ',%)
C
C INPUT GROUND SPEED,ALTITUDE,LATITUDE,LONGITUDE
C
0025 DO 90 K=1,NPROF
0026 TYPE 50,DSET,K
0027 TYPE 52
0028 READ(5,*) GSPD(K)
0029 TYPE 56
0030 READ(5,*) ALT(K)
0031 TYPE 60
0032 READ(5,*) LAT(K)
0033 TYPE 64
0034 READ(5,*) LONG(K)
0035 90 CONTINUE
C
0036 50 FORMAT('0',/T5,'SET # ',I3,/T5,'PROFILE # ',I3)
0037 52 FORMAT(' ',T5,'Ground Speed (KTS) ? ',%)
0038 56 FORMAT(' ',T5,'Altitude (FT) ? ',%)
0039 60 FORMAT(' ',T5,'Latitude (DEG.-MIN.) ? ',%)
0040 64 FORMAT(' ',T5,'Longitude (DEG.-MIN.) ? ',%)
C
C =====
C CONVERT FILES
C =====
C
C GET UP FILE NAMES (SETXXX.DAT --> SETXXX.ASC)
C
0041 DO 70 I=1,4
0042 NAMEF(I)=DEVF(I)
0043 NAMET(I)=DEVT(I)
0044 70 CONTINUE
C
0045 ENCODE(3,80,EXT)DSET
0046 80 FORMAT(I3)
0047 DO 85 I=1,3
0048 NAMEF(7+I)='0'
0049 NAMET(7+I)='0'
0050 IF(EXT(I).EQ.' ') GOTO 85
0052 NAMEF(7+I)=EXT(I)
0053 NAMET(7+I)=EXT(I)
0054 85 CONTINUE
C
C CALCULATE RECORDSIZE FOR OLD FILE AND INITIAL BLOCK SIZE

```


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```

C   FOR NEW FILE
C
0055   OPEN(UNIT=3,TYPE='OLD',RECORDSIZE='2',NAME=NAMEF,ACCESS=
      >'DIRECT',FORM='UNFORMATTED')
0056   READ(3,1)BINS
0057   CLOSE(UNIT=3)
0058   RECSIZ=(BINS+HDRB+1)/2
0059   INTSIZ=IFIX((FLOAT(NPROF)*(BINS+15)/256.+1.1)*6.)
C
C   OPEN OLD & NEW FILES
C
0060   OPEN(UNIT=3,TYPE='OLD',RECORDSIZE=RECSIZ,NAME=NAMEF,ACCESS=
      >'DIRECT',FORM='UNFORMATTED')
0061   OPEN(UNIT=4,TYPE='NEW',INITIALSIZE=INTSIZ,NAME=NAMEF)
C -----
C   CONVERT DATA BY PROFILES (K=PROFILE #)
C -----
0062   DO 100 K=1,NPROF
0063   READ(3,K)BINS,LBI,CSET,CPROF,MN,DAY,YR,JTIM,
      >(LDATA(I),I=1,BINS)
C
C   CONVERT ALTITUDE FROM FEET TO KILOMETERS
C
0064   ALT(K)=ALT(K)*.0003048
C
C   CONVERT TIME
C
0065   CALL TIMASC(JTIM,ITIME)
0066   ITIME(3)=ITIME(4)
0067   ITIME(4)=ITIME(5)
0068   ITIME(5)=ITIME(7)
0069   ITIME(6)=ITIME(8)
0070   DECODE(6,115,ITIME)HRS,MINS,SECS
0071   115 FORMAT(3I2)
C
C   WRITE ASCII FILE
C
0072   WRITE(4,120)BINS,LBI,CSET,CPROF,MN,DAY,YR,HRS,MINS,SECS
0073   120 FORMAT(1X,4I5,6I3)
0074   WRITE(4,125)GSPD(K),ALT(K),LAT(K),LONG(K)
0075   125 FORMAT(1X,I5,F7.3,2F7.1)
0076   WRITE(4,128)(LDATA(I),I=1,BINS)
0077   128 FORMAT(1X,12(15))
C
0078   100 CONTINUE
C -----
C   CLOSE OUT FILES
C -----
0079   CLOSE(UNIT=3)
0080   CLOSE(UNIT=4)
0081   TYPE 130,CSET
0082   130 FORMAT('0',T5,'SET # ',I3,' CONVERTED')
C
C   RETURN FOR NEXT SET
C
0083   GOTO 27
C
0084   END

```

FORTRAN IV Storage Map for Program Unit CONVRT

Local Variables, .PSECT \$DATA, Size = 013112 (2853. words)

Name	Type	Offset	Name	Type	Offset	Name	Type	Offset
BINS	I*2	013052	CPROF	I*2	013064	CSET	I*2	013062
DAY	I*2	013044	DSET	I*2	013036	HDRB	I*2	013050
HRS	I*2	013066	I	I*2	013100	INTSIZ	I*2	013054
JTIM	I*4	013074	R	I*2	013102	LBI	I*2	013056
MINS	I*2	013070	MN	I*2	013042	NPROF	I*2	013040
RECSIZ	I*2	013060	SECS	I*2	013072	YR	I*2	013046

Local and COMMON Arrays:

Name	Type	Section	Offset	Size	Dimensions
ALT	R*4	\$DATA	010456	000614 (198.)	(99)
DEVF	L*1	\$DATA	012722	000004 (2.)	(4)
DEVT	L*1	\$DATA	012726	000004 (2.)	(4)
EXT	L*1	\$DATA	012732	000003 (2.)	(3)
GSPD	I*2	\$DATA	000000	000306 (99.)	(99)
ITIME	L*1	\$DATA	012773	000010 (4.)	(8)
LAT	R*4	\$DATA	011272	000614 (198.)	(99)
LDATA	I*2	\$DATA	000306	010150 (2100.)	(2100)
LONG	R*4	\$DATA	012106	000614 (198.)	(99)
NAMEF	L*1	\$DATA	012735	000017 (8.)	(15)
NAMET	L*1	\$DATA	012754	000017 (8.)	(15)

Subroutines, Functions, Statement and Processor-Defined Functions:

Name	Type	Name	Type	Name	Type	Name	Type	Name	Type
FLOAT	R*4	IFIX	I*2	TIMASC	R*4				

APPENDIX IV PREPROCESSING SYSTEM OPERATION PROCEDURE

IV.1 Data Collection

The following is the procedure for assembling and operating the lidar preprocessing system for sodium profile data collection.

1. Connect the components of the receiving system as shown in Figure IV.1.

Note the following items:

- (a) Three cards are required in the Apple peripheral slots: the CCS serial card in slot 2, the DMA card in slot 4, and the disk controller card in slot 6.
 - (b) Be sure to use the cable designated "Apple-LSI-11" between the Apple CCS card and the LSI-11 DLV11-J card channel 0.
 - (c) Use the shielded ribbon cable between the Apple and the SI IPP unit.
2. Connect the monitor output of the Discriminator High Voltage Supply to a digital voltmeter.
 3. Check the settings of the following components:
 - Laser Control Unit - Trigger mode external
 - Discriminator - single mode, $V = 1$, $\Delta V = \text{don't care}$, threshold multiplier = X10
 - PMT Timing Controller - blanking on, μP gate don't care, triggering external, internal rate don't care.
 4. Check the setting of the Discriminator High Voltage Supply by first disconnecting the HV cable on the HV Output and then turning on the supply. The voltage should be adjusted until the monitor voltmeter reads about 2 volts (2000 volts HVS output). Shut off the supply and reconnect the HV cable.

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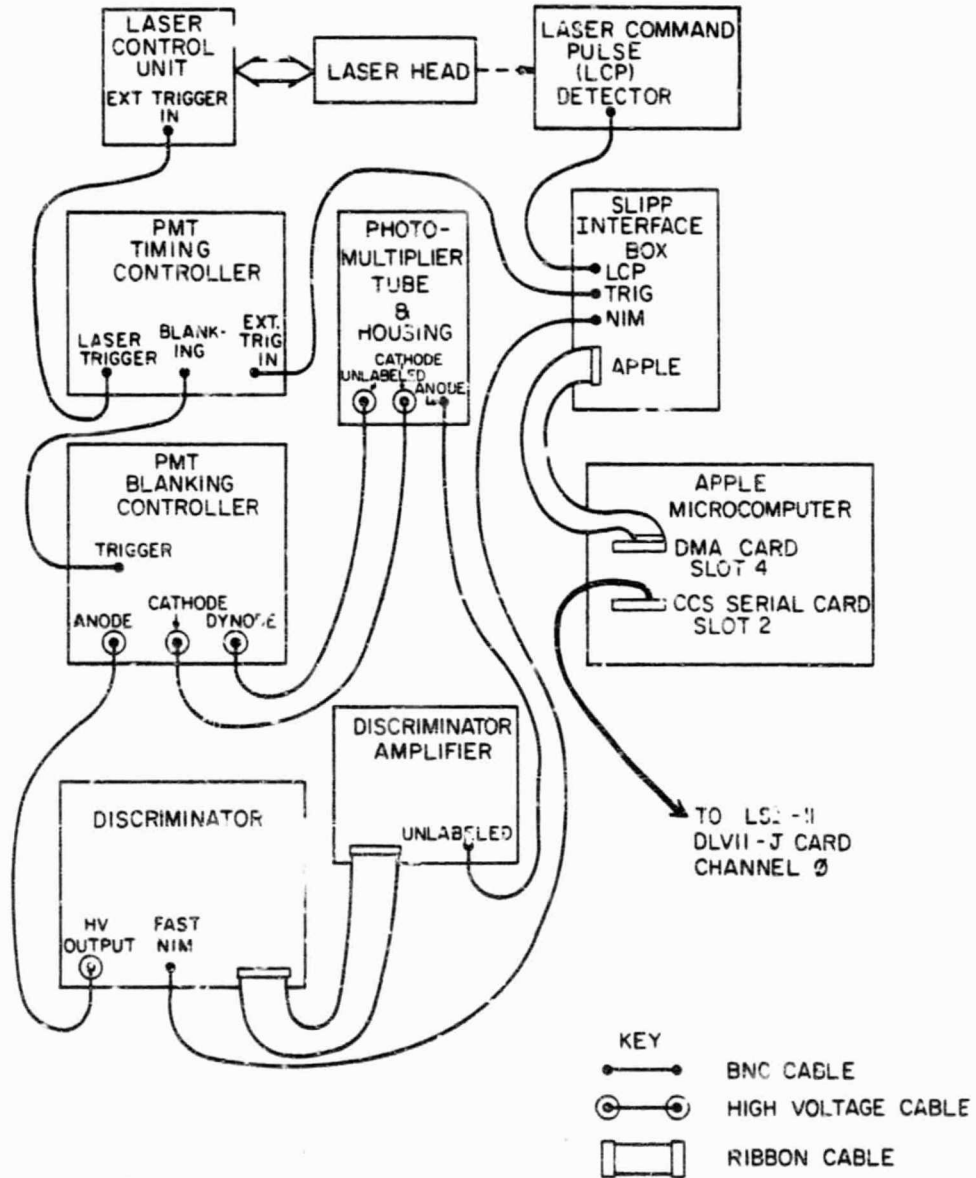


Figure IV.1 Lidar receiver connection map.

5. Power up all of the components except the Apple and LSI-11 computers. The order in which the components are switched on is not critical.
6. Load one of the Apple lidar software floppy disks into the Apple drive and switch on the Apple. Wait for the computer to boot up. Run the collection program SLPAPP.OBJ (BRUN SLPAPP.OBJ).
7. Load one of the LSI-11 lidar software floppy disks into the LSI-11 system drive and switch on the LSI-11. Wait for the computer to boot up. Load a LSI-11 data floppy disk into the storage drive. (Normally the DX1: or DY1: drive is used as the system drive and DX0: or DY0: is used as the storage drive. For more details see Section 5.4 on Data Collection Software Options.) Run the collection program FZZ.SAV (RUN FZZ).
8. The preprocessing system should now be operational. The laser-telescope alignment and data collection routines can be run by following the prompts on the Apple and LSI-11 monitors.

Notes:

- (a) Remember to power up the PMT cooling housing unit a few hours before the data collection to allow the PMT to cool sufficiently.
- (b) In order for the preprocessing system to trigger the laser the trigger mode selector switch must be set to "external." However, the trigger mode switch can be set to "internal" for laser tuning or alignment of optics.
- (c) Two pulse delay circuits are provided on the laser control unit. The circuits provide a delay between an input trigger pulse and an output pulse with the duration of the delay set by an adjustment knob on the control unit. Normally, delay circuit #2 is incorporated between the input laser trigger pulse and the final

trigger pulse sent to the laser head. Thus, there is a delay between the preprocessing system laser trigger pulse and the actual laser firing. If the delay is too long, it is possible for the Apple in the preprocessing system to send the laser trigger pulse and then test to see if the collection is complete before the laser ever fires. This results in a laser trigger error message. If the laser is firing at approximately the same time as the Apple is testing for collection completion, some peculiar behaviors can result (such as the Apple "hanging"). These problems can be alleviated by reducing the delay with the adjustment knob (normally, #2 ADJ).

IV.2 Testing

The following is a procedure for assembling and testing the preprocessing system without the rest of the lidar system components.

1. Connect the preprocessing system components (Apple, LSI-11, and SLIPP unit) as shown in Figure IV.1. However, do not connect the three SLIPP unit lines LCP, TRIG, and NIM to the receiving components. (Also, note the appropriate items in Section IV.1.)
2. Connect the TRIG BNC output on the SLIPP unit to the LCP BNC input. This loop simulates the laser in the system.
3. Connect a source of simulated photon pulses to the NIM BNC on the SLIPP unit. The pulses can be supplied by a couple of methods:
 - (a) Use the PMT and the Discriminator-Amplifier as shown in Figure IV.1 and simply leak a small amount of light into the PMT.
 - (b) Use a pulse generator with output pulses of about -1 V and 1-20 MHz.

4. Follow the steps outlined in Section IV.1 (steps 6-8) for loading the Apple and LSI-11 disks and running the collection programs. However, a slightly altered version of the Apple collection program must be used because of some timing difficulties due to the TRIG-LCP loop. This program is labeled SLPTST.OBJ and should also be provided on the Apple lidar software disks.

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