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Prediction of the Structure of Fuel Sprays in Gas Turbine Combustors

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Abstract

The structure of fuel sprays in a combustion cnamber is theoretically investigated using computer models of current interest. Three representative spray models are considered: (1) a locally nomogeneous flow (LHF) model, which assumes infinitely fast interphase transport rates; (2) a deterministic separated flow (DSF) model, which considers finite rates of interphase transport but ignores effects of droplet/ turbulence interactions; and (3) a stochastic separated flow (SSF) model, which considers droplet/turbulence interactions using random sampling for turbulence properties in conjunction with random-walk computations for droplet motion and transport. Two flow conditions, i.e., swirl number = 0.72 and 1.98, are studied to investigate the influence of swirl on droplet life histories and the effects of droplet/turbulence interactions on flow properties. Comparison of computed results with the experimental data show that general features of the flow structure can be predicted with reasonable accuracy using the two separated-flow models. In contrast, the LHF model overpredicts the rate of development of the flow. While the SSF model provides better agreement with measurements than the DSF model, definitive evaluation of the significance of droplet/ turbulence interaction is not achieved due to uncertainties in the spray initial conditions.

Nomenclature

B CD D f g h n fg K	mass transfer driving potential, Eq. (14) drag coefficient droplet diameter binary diffusivity mixture fraction mean square of mixture fraction fluctuations heat transfer coefficient heat of vaporization turbulence kinetic energy		
Le			
-	droplet mass		
^៣ ខ្ល កំ	mass flux at droplet surface		
n _i	number flow rate of droplets in group i		
$N_{\rm p}, N_{\rm c}$ convection correction, Eq. (15)			
P(f)	_s convection correction, Eq. (15) probability density function (PDF) of f		
	Prandtl number		
	radial distance		
ro	combustion chamber radius		
H D	droplot Downalds number		
S	swirl number Schmidt number source term droplet source term time		
Sc	Scnmidt number		
Sφ	source_term		
۶ _{P¢}	droplet source term		
t			
. T	temperature		
u	axial velocity		
v	radial velocity		

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tangential velocity

- V_j volume of computational cell j
- x' axial distance
- YF mass fraction of fuel vapor
- r exchange coefficient
- rate of dissipation of turbulence kinetic energy
- λ thermal conductivity
- μ viscosity
- p density
- generic property
- ψ scalar property

Subscripts

- p droplet property
- F fuel vapor
- s droplet surface property
- ∞ ambient property

Superscripts

- (_) time_averaged quantity
- (~) Favre-averaged quantity

Introduction

The objective of this investigation is to evaluate liquid fuel-spray combustion models for gas turbine combustors and furnaces. Numerous spray models have been proposed and some are currently being used in industry to assist gas turbine combustor gevelopment.^{1,2} Recent reviews by Crowe, ³ Law, ⁴ Faeth⁵ and Sirignano⁶ discuss important aspects of spray modeling that are currently being addressed. Recent spray models differ in details, but generally may be divided into two categories: the locally homogeneous flow (LHF) models and separated flow (SF) models.

LHF models represent the simplest treatment of a multiphase flow and have been widely used to analyze sprays.^{7,8} The key assumption of the LHF model is that interphase transport rates are fast in comparison to the rate of development of the flow as a whole. This implies that all phases have the same velocity and temperature, and phase equilibrium is maintained at each point in the flow. Clearly, LHF models are only formally correct for flows containing infinitely small droplets. The potential range of application, however, can be much larger, since LHF models can be used when particle relaxation times are small in comparison to the characteristic time scales of the continuous phase.⁵ LHF models have been extensively evaluated by Faeth and coworkers⁵,7 and by Khalil and Whitelaw.⁸ It was found that LHF models provide a reasonable description of the structure of a spray, however, they generally overestimate the rate of development of the flow.

SF models have been proposed to consider interphase transport phenomena. Numerous separated_flow models have been proposed, Gosman

and Jonns⁹ have divided them into three groups: discrete droplet models, continuous droplet models and continuum formulation models. The discrete droplet model was first proposed by Crowe¹⁰ and later used by Gosman and Ioannides¹¹ and El Banhawy and Whitelaw.¹² In this model droplets are divided into representative groups whose trajectories are tracked by solving the Lagrangian orginary-differential equations that govern droplet transport. The gas-phase conservation equations, with source terms included to represent the effect of the droplets on the gas-phase, are solved in Eulerian coordinates. In the continuous droplet model, proposed by Williams 13 and used by Westorook, 14 the droplets are represented by a statistical distribution function in a multidimensional space of droplet size, velocity, location and time. The properties of droplets are determined by solving the conservation equation of the distribution function, similar to the analysis of molecular properties in the kinetic theory of gases. In the continuum formulation models, droplets are treated as a continuous fluid, so that the gas and droplets are represented as interpenetrating continua. This formulation requires one droplet fluid phase for each droplet size. It is very expensive in terms of computer storage and time for practical sprays, since they generally have a wide range of droplet sizes. In most recent spray models the discrete droplet formulation has been adopted, since it reduces numerical diffusion and computer storage requirements while providing a convenient framework for dealing with multiple droplet size and complex interphase transport phenomena. The present investigation emphasizes the discrete droplet model.

Many discrete droplet models neglect the effects of turbulence on interphase transport.^{1,2} This implies that droplets follow deterministic trajectories, yielding the deterministic separated flow (DSF) model. Neglecting the effects of turbulence on droplet transport is appropriate when cnaracteristic droplet relaxation times are large in comparison to characteristic times of turbulent fluctuations. Few practical sprays, however, satisfy this condition. Dukowicz,¹⁵ Gosman and Ioanniaes¹¹ and Faeth and coworkers¹⁶⁻²⁰ have adopted stochastic methods to treat the turbulence/ droplet interactions. In the stochastic separated flow (SSF) model, droplets are assumed to interact with turbulent eddies whose properties are obtained by random sampling. An appropriate number of random samples is taken for each droplet group so that statistically significant mean droplet properties can be obtained. The formulation of the SSF model was first proposed by Gosman and Ioannides 11 to study droplet dispersion. Faeth and coworkers $^{16-20}$ further developed the model to include the effects of turbulence on interphase neat and mass transport. The SSF model has been extensively evaluated by Faeth and coworkers $^{16-20}$ in a wide variety of parabolic flows and the results have been very encouraging.

The present investigation extends the SSF models of Refs. 16 to 20 to consider swirling and recirculating flows. Results from LHF and DSF models are also presented in order to highlight the effects of finite interphase transport rates and droplet/turbulence interactions.

Theoretical Methods

The LHF model is equivalent to the analysis of a variable density single-phase flow. The effects of the dispersed phase appear in the upstream boundary conditions and the representation of state relationships. The present LHF model is very similar to that reported in earlier work on evaporating and combusting sprays. ^{19,20,22}

Gas Pnase

The major assumptions of the gas-phase formulation are as follows: (1) the flow is steady, axisymmetric, and swirling, (2) exchange coefficients of all species and thermal energy are the same, (3) kinetic energy of the mean flow is negligible, (4) combustion is diffusion controlled, (5) radiative neat transfer is neglected, and (6) the sprays are dilute so that droplet collisions and the displacement of the gas by the droplets can be neglected. Favre-averaged governing equations are solved. The conserved-scalar formulism is used to obtain scalar properties. Turbulence closure is achieved by employing a $K-\varepsilon-g$ turbulence model.¹²,²¹

The governing equations of the gas-phase can be written in the general $\ensuremath{\mathsf{form}}\xspace,\ensuremath{^{12}}\xspace$

$$\frac{\partial}{\partial x} \left(\overline{\rho} \widetilde{u} \widetilde{\phi} \right) + \frac{1}{r} \frac{\partial}{\partial r} \left(r \overline{\rho} \widetilde{v} \widetilde{\phi} \right) = \frac{\partial}{\partial x} \left[r \frac{\partial \widetilde{\phi}}{\partial x} \right] + \frac{1}{r} \frac{\partial}{\partial r} \left[r r \frac{\partial \widetilde{\phi}}{\partial r} \right] + S + S_{p\phi}$$
(1)

where $\tilde{\phi} = \overline{p}\phi/\overline{p}$ is the Favre-averaged dependent variable. The expressions for the exchange coefficient r and the source term S can be found in Refs. 12 and 23. The term $S_{p\phi}$ is used for the SF models and represents the interaction between the droplets and the gas phase and is obtained from the droplet trajectory calculations, as will be described later. Because of the dilute spray assumption the influence of droplets on turbulence properties is neglected.

A gaseous diffusion flame structure is assumed for the combustion analysis and the droplets are treated as distributed sources of fuel vapor. The presence of envelope flames around or wake flames behind individual droplets is neglected since the majority of droplets spend most of their lifetimes in fuel rich regions. Experimental confirmation of this assumption can pe found in Refs. 5 and 24.

The Favre-averaged scalar properties (e.g., temperature and species concentrations) are calculated from the probability density function (PDF) of mixture fraction, P(f), and state relationships of scalar properties as a function of mixture fraction, $\psi(f)$,

$$\tilde{\psi} = \int_{0}^{1} \psi(f) \tilde{P}(f) df \qquad (2)$$

wnile $\bar{\rho}$ is found from

$$\vec{\rho} = \left(\int_0^1 \frac{1}{\rho(f)} \vec{P}(f) df \right)^{-1}$$
(3)

A clipped Gaussian function is assumed for $\widetilde{P}_{(T)}$ and the most probable value and variance are determined by \widetilde{T} and g. State relationships are obtained by thermodynamic equilibrium calculations using the CEC-76 computer program developed by Gordon and Mcbride.²⁵ The SSF model requires the time-averaged PDF, $\overline{P}(f)$, which can be found as follows:

$$\overline{P}(f) = \overline{\rho}/\rho(f) \ \overline{P}(f) \tag{4}$$

Jroplet Phase

The major assumptions involved in the droplet transport calculations have been discussed in detail by Law⁴ and Faeth⁵ and will not be repeated here. In the present investigation, the thin-skin approximation is used for droplet evaporation. This implies that the bulk mass of a droplet remains at its initial condition and only the surface of the droplet is heated during evaporation. This approximation is convenient for the conserved scalar approach of the gas field since energy absorbed by the liquid is neglected. The justification for this approximation is discussed in Refs. 5 and 20.

Droplet trajectories are solved in Lagrangian coordinates. The governing equations of droplet transport are given below.

<u>uroplet motion</u>. The position, axial, radial and tangential momentum equations are

$$\frac{d\tilde{u}_{p}}{dt} = U_{p}$$
 (5)

$$\frac{au_p}{dt} = \frac{3}{4} \frac{\rho C_D}{\rho_p d_p} (u - u_p) \left| \vec{u} - \vec{u}_p \right|$$
(6)

$$\frac{\mathrm{d}\mathbf{v}_{p}}{\mathrm{d}t} = \frac{3}{4} \frac{\rho C_{D}}{\rho_{p} d_{p}} \left(\mathbf{v} - \mathbf{v}_{p}\right) \left[\vec{u} - \vec{u}_{p} \right] + \frac{w_{p}^{2}}{r}$$
(7)

$$\frac{dw_p}{dt} = \frac{3}{4} \frac{\rho C_D}{\rho_p d_p} (w - w_p) \left| \vec{u} - \vec{u}_p \right| - \frac{v_p w_p}{r}$$
(8)

The standard drag coefficient is approximated as follows:

where the aroplet Reynolds number, Re, is defined

as
$$\operatorname{Re} = \rho \left| \begin{array}{c} \dot{u} - \dot{u} \\ p \end{array} \right| \left| \begin{array}{c} d_{p} / \mu \end{array} \right|$$

 $\frac{\text{Droplet evaporation.}}{\text{transport equations are as follows:}^{26}$

$$\frac{dd_p}{dt} = -\frac{2m''}{\rho_p} \tag{10}$$

$$\frac{\hbar^{''} dp}{\rho D} = 2N_{s} \ln (1 + B)$$
 (11)

$$T_{p} = T - \frac{\hbar^{"h} f_{g}}{h}$$
(12)

$$\frac{hd_{p}}{\lambda} = \frac{2 N_{p} \ln (1 + B)^{Le^{-1}}}{\left[(1 + B)^{Le^{-1}} - 1 \right]}$$
(13)

$$= \frac{(Y_{FS} - Y_{F\omega})}{(1 - Y_{FS})}$$
(14)

N_p or N_s = 1 +
$$\frac{0.276 \text{ Re}^{1/2} (\text{Pr or Sc})^{1/3}}{\lfloor 1 + 1.232 / (\text{Re}(\text{Pr or Sc})^{4/3} \rfloor^{1/2}}$$
(15)

В

The fuel vapor concentration and temperature at the liquid surface are related through the fuel vapor pressure characteristics

$$Y_{Fs} = f(T_{s}, p)$$
 (16)

Time-averaged gas properties and instantaneous eddy properties should be used for droplet trajectory calculations in the DSF and SSF models, respectively. Time-averaged scalar properties can be found directly from the conserved-scalar formulation.²⁷ However, to convert Favreaveraged velocities to time-averaged velocities requires correlations of velocity-density fluctuations. To avoid undue complications in the analysis, the Favre-averaged gas velocities are used in the calculations. Jeng and Faeth²⁸ estimated the difference between the two averaged velocities in their diffusion flame to be less than 5 percent.

Droplet/Turbulence Interaction

In the SSF model, the effects of turbulence on droplet transport are treated by a stochastic approach. The complete formulation of the stochastic method can be found in Refs. 9 and 16 to 20 and only a brief description is given here.

Lagrangian equations of droplet motion and transport are solved by dividing the droplets into n groups (defined by initial position, size and velocity) at the nozzle exit and computing their life histories in the flow field. The droplets are assumed to interact with a random distribution of eddies along their trajectories. The eddy properties are obtained by random sampling of the PDF's of velocity and mixture fraction. To simplify the analysis, velocity and mixture fraction are assumed to be statistically independent. The turbulence is assumed to be isotropic and to have a Gaussian PDF in the velocity fluctuations. Although the time-averaged PDF should strictly be used, the Favre-averaged PDF is used here for the same reason as in the DSF analysis.

The scalar eddy properties are obtained by sampling the time-averaged PDF, $\overline{P}(f)$, for an

instantaneous value of f and then obtaining the corresponding scalar properties from the state relationsnips. The droplet/eddy interaction time is assumed to be the minimum of either the eddy lifetime or the transit time for the droplet to cross the eddy. Details of the specification of these times and their calibration can be found in Refs. 15 to 20.

Droplet Source Terms

The influence of droplets on the turbulence is neglected in this study and no source terms from the droplets are included in the k, ε and g equations. The droplet mass and momentum source terms appearing in Eq. (1) are computed after the droplet transport equations are integrated.

The mass and axial momentum source terms for each computational cell j are calculated from the net change of droplet mass and axial momentum for each droplet group traversing this cell, as follows:

$$S_{pmj} = V_j^{-1} \left(\sum_{i=1}^{n} \dot{n}_i \left(m_{pi} - m_{pi}_{out} \right) \right)_j$$
(17)

$$S_{puj} = V_{j}^{-1} \left(\sum_{i=1}^{n} \tilde{n}_{i} \left((m_{pi}u_{pi})_{in} - (m_{pi}u_{pi})_{out} \right) \right)_{j}$$
(18)

The droplet radial and tangential momentum source terms, however, cannot be calculated in this manner due to the additional force terms in the respective droplet equations of motion (cf. Eqs. (7) and (8)). These source terms are obtained by directly computing the change of radial and tangential momentum due to drag, as follows:

$$S_{pvj} = V_{j}^{-1} \int_{t_{in}}^{t_{out}} \left(\sum_{i=1}^{n} \frac{3}{4} n_{i} m_{pi} \frac{-p}{\rho_{p} d_{p}} C_{p} \right) \\ \times (v_{pi} - v) \left| \vec{u}_{pi} - \vec{u} \right| dt$$
(19)

$$S_{pwj} = V_{j}^{-1} \int_{t_{in}}^{t_{out}} \left(\sum_{i=1}^{n} \frac{3}{4} \dot{n}_{i} m_{pi} \frac{p}{p_{p}d_{p}} C_{D} \right) \\ \times (w_{pi} - w) \left| \dot{u}_{pi} - \dot{u} \right| dt \qquad (20)$$

Boundary and Initial Conditions

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The elliptic nature of the gas-phase governing equations requires that boundary conditions be specified along all surfaces enclosing the computational domain. Measured values of mean axial velocity and temperature are prescribed at the inlet. Inlet radial velocity is taken as zero and the tangential velocity is specified to have a solid-body rotation profile. Second derivatives of all dependent variables are assumed to be zero at the exit. Axisymmetry is assumed and adiabatic and non-slip conditions are specified along all solid surfaces.

The Lagrangian formulation of the droplet transport equations requires the specification of initial conditions for the droplets to start the integration. The initial conditions required in the present analysis include droplet velocities, location, and size distribution. This information, however, is rarely available in practical flows. As a result, approximations of initial conditions are used in the predictions. Initial aroplet locations and velocities are estimated from the limited available experimental information. The droplet size is assumed to have a Rosin-Rammler size distribution. Upon impingement on a wall, the droplets are assumed to bounce back elastically with an angle of reflection equal to the angle of incidence.

Numerical Solution Procedure

A modified version of the TEACH computer program is used to solve the gas-phase governing equations. It includes an improved finitedifference procedure, the Bounded Skew-Upwind Differencing (BSUD) method developed by Raithby. 30 The pressure field is estimated using the Pressure Implicit Split Operator (PISO) predictor-corrector technique developed by Issa.³¹ The axisymmetric flow domain is divided into relatively fine meshes, i.e., 60 by 60. For the separated-flow analysis, the ordinary differential equations governing the motion and transport of each droplet group are integrated using a fourth-order Runge-Kutta method. The numerical integration of droplet trajectories is started from the fuel nozzle exit where the initial conditions of the droplets are prescribed. Seven hundred and 2800 trajectories are computed for the DSF and SSF models, respectively, in all cases. The solution procedure follows the PSI-CELL (Particle-source in Cell) iterative method of Crowe et al. 10 The gas-phase solution is obtained with droplet source terms from the previous iteration, then the droplet trajectories and the new mass and momentum source terms in each cell are calculated. The iteration cycle is repeated until the solutions for both phases converge. Generally, convergence is achieved in 1200 interations for the separatedflow calculation and 750 iterations for the LHF calculation. The CPU time requirements are approximately 600, 1400, and 2800 sec, respectively, for the LHF, DSF, and SSF models on the CRAY-1S/2200 computer.

Results and Discussion

The theoretical models described previously were applied to the liquid-fueled furnace used by Knalil et al.²⁹ The geometry of the combustion cnamper is shown in Fig. 1. Two swirl numbers (S = 0.72 and 1.98) were considered and the fuelair equivalence ratio was fixed at 0.8.

The predicted and measured temperature profiles at different axial locations are given in Fig. 2 for S = 0.72. The results snow that both the DSF and SSF models underpredict the temperature in the near inlet region, while the LHF model overpredicts the temperature, especially at large radii $(r/r_0 > 0.8)$. The discrepancies between the predictions of the two separated-flow models and the measurements are due to the underestimation of droplet spreading and evaporation, which is probably caused by uncertainties in the spray initial conditions. The SSF model shows better agreement than the DSF model because of better predictions of droplet evaporation and spreading rates. The overestimation of temperature by the LHF model is due to the assumption of infinitely fast interphase transport.

Far downstream of the combustor inlet, all three models predicted nigher temperatures than tne measurements. This is attributed to the neglect of radiative heat transfer. However, these errors in the predicted temperatures do not significantly affect the performance of the three models and hence, the conclusions of this study. Botn tne experimental data and the separated-flow model predictions showed high temperature peaks near the combustion chamber wall at downstream locations. The peak temperatures occur in regions where droplets have traversed and evaporated. The LHF model did not predict a temperature peak near the chamber wall because this model does not consider discrete droplet motion.

Figure 3 presents the experimental data and predictions for S = 1.98. The temperature profiles are more uniform for S = 1.98 than for S = 0.72 (Figs. 2 and 3). This is due to the increased mixing obtained with increased swirl. The nigner swirl also produces a stronger recirculating flow (i.e., more fuel vapor is transported upstream) and hence higher temperatures are obtained in the upstream region (x < 0.24 m) for S = 1.98. The agreement between the predictions and the measurements is similar to the lower swirl number case, except close to the inlet at large radii, where both the DSF and SSF models significantly underestimate the temperature. Very few fuel droplet groups are predicted to arrive in these regions (i.e., close to the inlet at large radii). This is probably caused by inaccurate initial droplet conditions. The fuel vapor concentration in these regions is therefore underpredicted which results in much lower temperatures than the experimental data. For both swirl number cases in regions far downstream, the DSF model predicts much higher temperature peaks, less uniform temperature distributions, and larger discrepancies with measurements than the SSF model (Figs. 2 and 3). This is because the DSF model neglects turbulent dispersion and hence, underestimates droplet spreading.

Radial profiles of gas-phase axial velocity are presented in Figs. 4 and 5 for S = 0.72 and 1.98, respectively. The boundaries of the central recirculation zones for S = 1.98, 1.25 and 0.94 are shown in Fig. 6. For clarity in presentation, the results of only the SSF model are given. It can be seen that both the magnitude of the reverse velocities and the size of the recirculation zones are underpredicted, the errors increase with increasing swirl number. The implication of the underestimation of the recirculation can be seen in the temperature distributions in Fig. 3. The experimental data shows more uniform distributions pecause of greater mixing caused by larger reverse velocities. The poor performance of the model in predicting the size of the central recirculation zone and the reverse velocity may be partly attributed to the $k - \varepsilon$ model used in the present analysis. It is well known that $k - \varepsilon$ models nave not been very successful in predicting highly swirling flows.³² Beyond the central recirculation zone, the predicted axial velocities are higher than the measured values due to the higher predicted temperatures.

The predicted and measured radial profiles of gas-phase tangential velocities for the higher swirl number case are illustrated in Fig. 7. The calculated tangential velocities are smaller than the measured values at almost all locations. This discrepancy is attributed to uncertainties in the inlet swirl velocities. It should also be noted that the swirl numbers quoted by Knalil et al.²⁹ for the experimental data were estimated from the swirler vane angle rather than direct measurements and may introduce some error. The underestimation of the tangential velocities is partially responsible for the errors in the predictions of flow reversal.

The predicted axial profiles of liquid mass flow rate are shown in Fig. 8 for S = 0.72 and 1.98. As expected, the LHF model produces unre-alistically high evaporation rates.¹⁹ This nigh rate of evaporation is due to the method used to obtain the inlet boundary conditions and the assumption of infinitely fast interphase tran-sport rates. The results of the two separatedflow models appear reasonable, but lack of experimental data prevents quantitative comparisons. The SSF model predicts higher evaporation rates than the DSF model because it considers the effects of turbulence on interphase transport, which enhances the rate of evaporation.^{19,20} The influence of swirl strength on the overall evaporation rate is clearly indicated in Fig. 8, which shows faster evaporation for higher inlet swirl. This can be explained by the interaction between the central recirculation zone and the droplet trajectories. In the high swirl case a large reverse flow is generated and most small droplets are trapped in the recirculation zone and evaporate there, resulting in intensive burning and high temperatures in this region. Large droplets which penetrate the central recirculation zone burn further downstream or near the combustor wall. In the low swirl case, most droplets survive the central recirculation zone and continue to evaporate in the far downstream region. Since the mixing is weak outside the reverse flow region, high fuel vapor concentration along the droplet trajectories produce local high tempera-ture peaks (see Fig. 2). In addition to the influence on droplet trajectories, the larger reverse flow zone recirculates more hot combustion products from downstream regions and increases the temperature at near inlet locations. This in turn contributes to a higher evaporation rate for the high swirl case.

The predicted axial profiles of droplet SMD are illustrated in Fig. 9 for S = 0.72. The values presented here were obtained by integrating over the cross-sectional area at each axial location. Following Khalil et al.,²⁹ the spray was assumed to have an initial SMD of 127 μ m. A Rosin-Rammler size distribution, with 15 size

groups and size range of 10 to 290 µm, was employed in the calculations. As the droplets move downstream, the SMD increases and then decreases. The initial increase of SMD is caused by the reduction of the number of small droplets, due to the preferential evaporation of small droplets (i.e., small droplets evaporate faster than large droplets). When most of the small droplets nave completely evaporated, the SMD begins to decrease because of the continuous evaporation of large droplets. The DSF and SSF models produce similar results, but the SSF model produces more rapid variations in the SMD than the DSF model because it predicts a higher evaporation rate.

Conclusions

Current theoretical spray models have been used to predict properties of fuel sprays in a cylindrical combustion chamber. The results showed that general features of the gas-phase flow field can be predicted reasonably well. However, the evaluation of model performance for the dispersed phase is not conclusive mainly due to inadequate knowledge of the droplet initial conditions and a lack of experimental data for downstream droplet properties. Some quantitative differences between predictions and mersurements, such as size of the recirculation zone, magnitude of the tangential velocity, temperature distribution close to the inlet, could be related to uncertainties in the gas-phase upstream boundary conditions and also to droplet initial conditions. The need for a set of benchmark experimental data on compustor fuel sprays with characterization of inlet conditions and flow measurements in both pnases has long been recognized.³,11,12 The present investigation reemphasizes this need.

The LHF method yields unrealistically high evaporation rates and overestimates the develop-ment of the flow field. Therefore, it has only limited utility in modeling practical sprays. The dispersion model gives less concentrated droplet trajectories and consequentially better temperature distributions than the deterministic method. Turbulence/droplet interaction enhances the rate of evaporation and produces higher fuel vapor concentration in the upstream portion of the combustor, where most droplets evaporate. Inclusion of these effects results in better predictions of the temperature, especially in regions near the wall and close to the inlet. Although the SSF model appears to have certain advantages over DSF model, the differences between the two predictions are not large compared to the uncertainties in the droplet initial conditions. The lack of experimental data providing important inlet conditions and detailed flow measurements in both phases prevents a decisive evaluation of the two separated-flow models.

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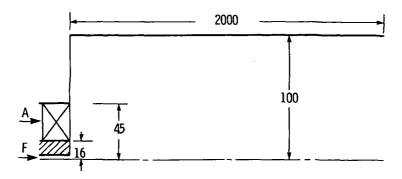
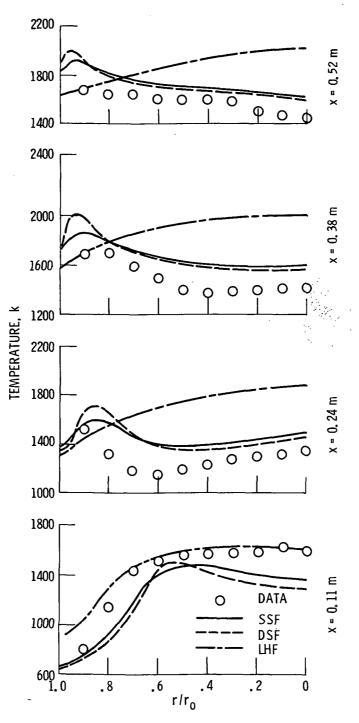
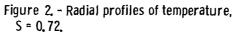
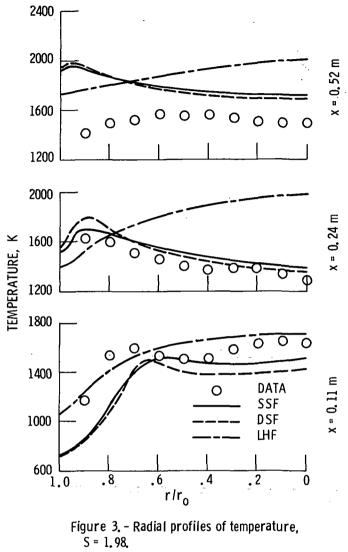


Figure 1. - Geometry of the combustion chamber. (All dimensions in mm).







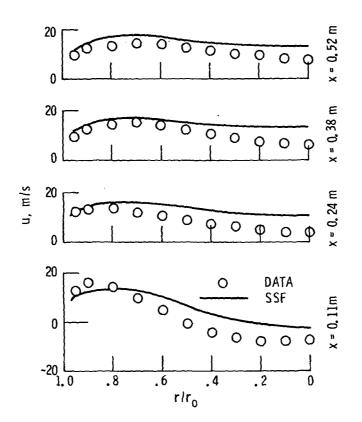
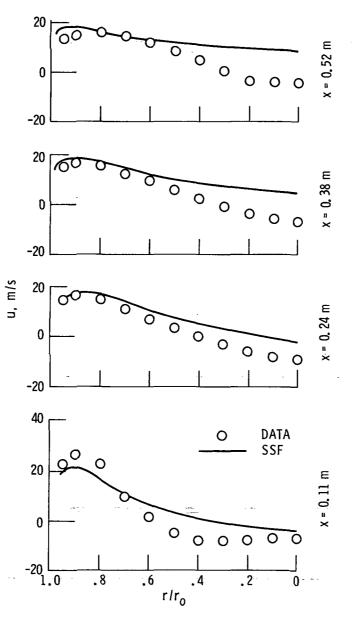
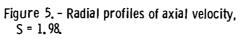
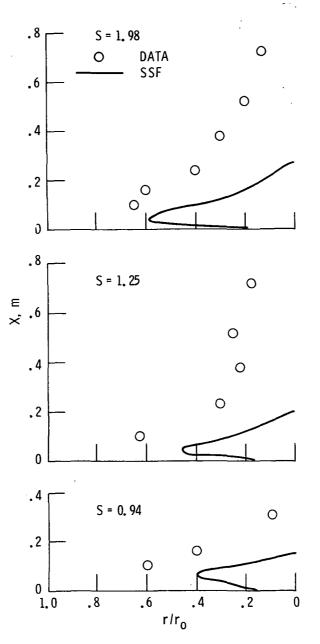


Figure 4. - Radial profiles of axial velocity, S = 0.72.

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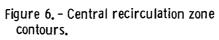


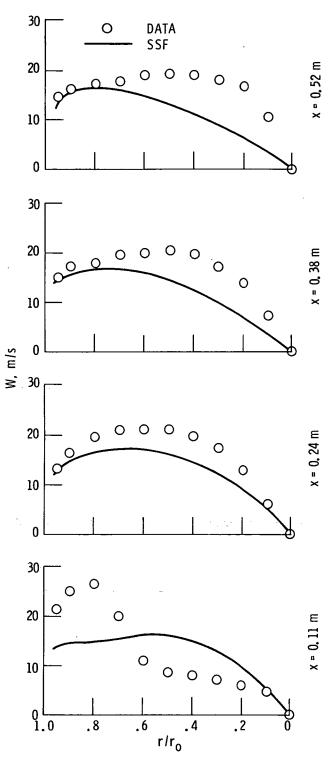


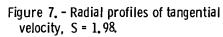


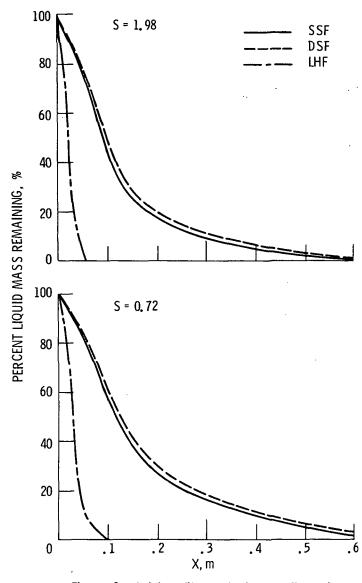
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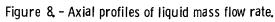
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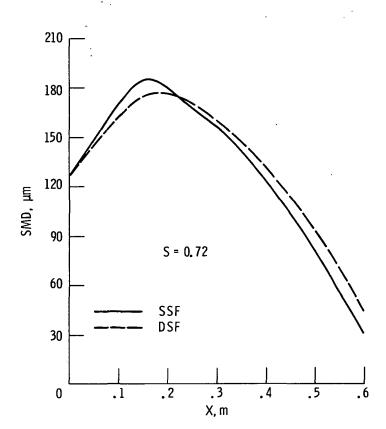


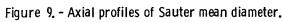












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