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LATERAL AND LONGITUDINAL AERODYNAMIC STABILITY AND CONTROL PARAMETERS OF THE BASIC VORTEX FLAP RESEARCH AIRCRAFT AS DETERMINED FROM FLIGHT TEST DATA

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INTRODUCTION

Wind tunnel investigations have indicated that for swept wings a leading edge flap can improve the L/D of the wing by as much as 30 to 40 percent in the .6 to .9 Mach range. The flap causes the leading edge vortex of the swept wing to keep the flow at the leading edge attached at higher angles-of-attack, increasing the lift from the wing while not significantly increasing the drag.

The Fl06B aircraft was selected as a test bed for flight testing the leading edge vortex flap. There were three primary reasons for using this aircraft. First, the delta wing was simple, and modifying the leading edge should not be extremely difficult. Second, the speed envelope of the aircraft covered the speed range where the vortex flap should be effective. Third, the 60° leading edge sweep fell in the sweep range where the flap was effective.

So that the improvement from the vortex flap could be assessed, the basic aircraft must be documented. To do this, all available information on the aerodynamics of the F106B is being assembled. One part of this collection of aerodynamic characteristics is the flight-determined stability and control derivatives. These parameters can be correlated with the results obtained from wind tunnels and used to determine aerodynamics for areas in the flight envelope where wind tunnel tests were not run. Flight tests can also be used to estimate rotary derivatives that cannot be obtained from many tunnels. Finally, agreement between wind tunnel and flight-determined aerodynamic parameters for the basic airplane will be an important factor in determining how the flight data from the modified aircraft can be used.

An important step in the assessment of the possible effect of the flap on the handling of the basic F106B is the development of a realistic simulation of the vehicle. Flight test results will be used in conjunction with the wind tunnel data to develop a realistic simulation of the basic aircraft. This basic simulation will then be modified to reflect the expected impact on the performance and handling qualities of the aircraft of adding a leading edge flap. Flight data from the modified aircraft will then be used to refine the simulation.

The purpose of this paper is to present the aerodynamics of the basic F106B as determined at selected points in the flight envelope. In this paper, the test aircraft and the flight test procedure will be presented. Thus, the aircraft instrumentation and the data system will be discussed. This will be followed by a presentation of the parameter extraction procedure and a discussion of flight test results. These results will then be used to predict the aircraft motions for maneuvers that were not used to determine the vehicle aerodynamics. The control inputs used to maneuver the aircraft to get data for the determination of the aerodynamic parameters will be discussed in the Flight Test Procedure section. The results from the current flight tests will be compared with the results from wind tunnel tests of the basic FlO6B, where comparisons can be made, and based on these comparisons, the need for additional data was concluded.

TEST AIRCRAFT

The aircraft used in this investigation was a slightly altered Fl06B. The configuration tested had a nose boom for measuring angle-of-attack and angle-of-sideslip. Also, a light source was mounted in the left side of the aircraft to illuminate the vortices on the wing. A photograph of the test aircraft is shown as figure 1. The physical characteristics that affect the parameter identification

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procedure are given as table I. The inertias for the subject aircraft as tested are not known. The inertias used are from manufacturer's data for a similar configuration and their accuracy is not known.

FLIGHT TEST PROCEDURE

Maneuvers were made from steady conditions, either from 1 "g" flight or from a higher "g" coordinated turn. Since the aircraft could not maintain altitude in these steady turns, the maneuvers were actually perturbations from a descending spiral. In this maneuver, the greatest rate of descent was approximatly 300 ft/sec. The assumption of a constant density for each run could result in an error of up to 3 percent at the final part of a run. Elevon doublets were used to perturb the vehicle for the identification of longitudinal parameters. The amount of elevon deflection used was determined by the variation in normal acceleration.

The maneuvers used for determining the lateral parameters consisted of a rudder doublet followed by an aileron doublet. The critical parameters during the lateral maneuvers were sideslip angle due to danger of departure and roll rate due to instrument limits. In practice, roll rate usually was the variable that established the limits on the magnitude of the inputs since the range of roll rate instrument was ±1 radian per second and moderate rudder or aileron inputs could easily cause responses that would exceed these limits. In most runs, the sideslip angle did not become excessive. Also, the yaw rate tended to be small and in some early runs, was marginal for good identification of the yaw rate and yaw moment derivatives.

For runs designated as flight 13, the input design was to put in the first half of the rudder doublet at a magnitude that would result in a 60 deg/sec roll rate in hopes of getting a $10^{\circ}-15^{\circ}$ per second yaw rate. Then, on the second part of the rudder doublet, start the aileron doublet early to try to keep the roll rate from exceeding 60° per second after the rudder switch. Then the second part of the aileron doublet would be large enough to give at least a 30° per second roll rate. This design generally kept the roll rate in limits and did not result in excessive sideslip, but the yaw rate still did not exceed 10° per second and was still marginal for good identification.

INSTRUMENTATION AND DATA PROCESSING

On the F106B aircraft the instrument channels were accessed using a pulse code modulation (PCM) system that processed the data at 82 samples per second (sps). This data was then recorded on magnetic tape for processing. The data on this tape were converted to engineering units, and quantities such as true airspeed were calculated. Selected channels that are required for parameter identification were recorded at a rate of 41 sps (one-half the original data rate) and corrections for instrument location relative to the vehicle center-of-gravity and instrument alignment were made. This process resulted in a data tape that was suitable for use with the parameter identification program. The quantities recorded and their ranges are given in table II. The assumed accuracy of these measurements was 1 percent of full scale of the measuring instrument.

PARAMETER EXTRACTION PROCEDURE

Maximum Likelihood and Linear Regression Parameter Extraction Programs were used to examine the flight test data. These programs are described in references 1 and 2. For both extraction programs, a linear aerodynamic model describing a rigid airplane was assumed. The parameter values obtained using the extraction programs are given in tables that include the parameter value and the estimated sensitivity for each parameter. The estimated standard deviation and sensitivity are indicators of the identifiability of the different parameters. If the estimated standard deviation is less than 10 percent of the extracted value for the parameter, then the parameter is identified, less the 5 percent well identified. The larger the sensitivity, the more identifiable the parameter and the greater the influence of the parameter value on the vehicle motion.

RESULTS AND DISCUSSION

Maneuvers were made to independently excite the longitudinal and lateral modes of the test vehicle. The parameters determined from the longitudinal modes will be discussed first. The longitudinal parameter values for the assumed longitudinal mathematical model are given as table III. Selected longitudinal parameters are plotted versus trim angle-of-attack (Fig. 2). In addition to the runs that resulted in the parameter values shown in figure 2 and referred to as "surface" in table III, runs were made in earlier flights before the actual control surface deflections were instrumented. During these flights, stick position was measured and the corresponding control surface position calculated. The results of these maneuvers are referred to as "stick" in table III. Since the parameters plotted account for over 90 percent of the vehicle's response to pilot's inputs, the discussion will center on these parameters.

There were maneuvers performed at four different Mach numbers. At Mach numbers of .6 and .9 maneuvers were performed at several different trim angles-of-attack. Each maneuver was examined using the two parameter extraction methods mentioned in the Parameter Extraction Procedure Section. The results for the four parameters shown in figure 2 will now be discussed.

 $C_{z\alpha}$ - The values determined by both extraction methods agreed well,

indicating confidence in these results. Also, the values obtained showed trends that were similar to those of other investigators, and their magnitudes seemed reasonable. An examination of table III showed $C_{z_{\alpha}}$ to be well identified for

most runs, but in general, it was not the longitudinal parameter that was most identifiable.

 $C_{m_{\alpha}}$ - The values obtained for both extraction methods agreed well, and for Mach numbers to .6, the values were close to those predicted by other investigators. For the Mach .9 cases, the values of $C_{m_{\alpha}}$ became more negative as

expected. There were no data to check the magnitude of the increase; however, the estimated standard deviations and sensitivities implied that the parameter was generally well determined (table III) and had a significant effect on the vehicle motion. A repeat run at an angle-of-attack around 15.5 degrees gave a more negative value for the parameter. When assessing the $C_{m_{\alpha}}$ values from the two runs, the

maximum likelihood, regression and estimated standard deviations were all

considered, and for the Mach equals .9 case, a value of aproximately -.27 seemed reasonable.

 C_{m_q} - The values obtained for both extraction methods agreed for most runs. The values extracted generally were close to those predicted by other investigators for the Mach .6 case. The trends of the data were reasonable except for two points at the highest angles-of-attack. These two points both have larger magnitudes than might be expected from the other runs examined. A trend to more damping such as that seen in the regression results is reasonable, but the large jump seen in the maximum likelihood results is questionable. The values of estimated standard deviation and sensitivity shown in table III indicate that the parameter is not as well identified as the past two and does not have a great influence on the vehicle motion for many of the runs examined.

 $C_{m\delta e}$ - As with C_{m_q} , the values obtained for both extraction methods agreed for most of the runs. The values for $C_{m\delta e}$ determined by other investigators varied widely and the values for the Mach .6 runs generally fell between the extremes. The values showed a definite Mach effect between Mach .6 and Mach .9. Also, a trend toward greater effectiveness with angle-of-attack was seen. Both trends are reasonable, although the amount of variation seen at the largest angles-of-attack for the Mach .9 data was greater than expected. Based on the estimated standard deviation and sensitivity values, $C_{m\delta e}$ was considered to be

well identified and to have a significant influence on the vehicle motions.

A comparison of the results of longitudinal runs using actual and calculated surface positions for Mach .6 are given in figure 3. Also shown in the figure are the Mach .6 results from a run where only calculated control position was available. The results from the actual and calculated control surface position runs agree reasonably well for all parameters. The results from Mach .6 runs from the flight where only calculated surface deflection was available show the same trends and magnitudes as the runs where the actual surface positions were measured. For the longitudinal aerodynamics, these additional runs definitely add to the definition of the parameters identified.

As an additional test of the model determined using flight tests, a run at Mach .6 that was not used for determining values for the parameters was used for prediction. In this case, values for the various parameters in the mathematical model describing the vehicle were picked from figure 2 for the specific Mach number and trim angle-of-attack of the prediction run. This model was then perturbed by the actual input time history from the flight test and the resulting motions compared with the motions measured in flight. The results of this prediction are shown as figure 4a and b. The assumed model is seen to do a good job of predicting the vehicle motions.

LATERAL PARAMETERS

Next we will discuss the lateral parameters. Parameter values for the assumed lateral model are given in table IV. As was the case with table III, the designation "surface" or "stick" indicated how the control input was determined. The lateral parameters that have the greatest effect on the vehicle motion and which describe approximately 90 percent of the vehicle's response motion are shown as figure 5. The estimated standard deviations and sensitivities of the parameters

that had the most effect on the vehicle motion are given in table IV. An examination of these values indicated that $C_{\ell,\beta}$, $C_{n,\beta}$, and $C_{n,\delta,r}$ are very well identified; the parameters $C_{\ell,p}$ and $C_{\ell,\delta,a}$ are well identified; and that these five parameters describe most of the vehicle's motion. The parameters $C_{\ell,\delta,r}$, $C_{\gamma\beta}$ and $C_{n,\delta,a}$ are not as well identified and do not have much influence on the vehicle motion. The parameters shown in this figure will now be discussed individually as to their trends with angle-of-attack and actual parameter values extracted.

 $C_{\ell\beta}$ - The parameter showed consistent trends with angle-of-attack for all Mach numbers. These trends were similar to those of other investigations. The magnitudes of the extracted parameters fell within the range of the values predicted by other investigators, but in general, were less negative then expected. However, since both the Regression and Maximum Likelihood extraction programs gave similar results, the values seem reasonable.

 $C_{n\beta}$ - The parameter showed similar trends as indicated by the results from other investigators. The trend to larger $C_{n\beta}$ values with increased Mach number in the Mach .6 to Mach .9 range is also seen. The agreement between the values determined by the two extraction methods was poor, which reduced the confidence in the values determined. However, in general, the values seemed to fall in a reasonable range when compared to other results.

 $C_{y\beta}$ - The trends of the parameter values with angle-of-attack and Mach number were reasonable. The magnitude of the change appeared to be greater than anticipated. Also, the agreement between the values determined using the two extraction methods was not good for most maneuvers. The values for the parameter were also reasonable, but possibly were not negative enough in most cases.

 $C_{\ell p}$ - The magnitudes of the extracted parameters seemed reasonable, but the scatter in the parameters precluded establishing any definite trends with angle-of-attack on Mach number. At the largest angles of attack the two extraction methods agreed fairly well giving some confidence in the values obtained.

 $C_{\ell \delta_a}$ - The magnitudes determined for the parameter seemed reasonable. However, the parameter values for the Mach .9 runs seemed to show a trend with angle-of-attack which was not predicted by other investigators. There also appeared to be a trend toward more effectiveness with increasing Mach number which was greater than expected. The two extraction methods did not agree well, but the trends noted were clearly defined. The scatter in the Mach .6 results prevented any definite comments on the trend of that data.

 $C_{l\delta r}$ - There was considerable scatter in the extracted parameter values, so no trends were obvious. The parameter showed less effectiveness than was predicted by other investigators. Since the two extraction methods gave different values in most cases, the confidence in the values for this parameter was reduced.

 $C_{n\delta a}$ - The values for this parameter were generally reasonable but showed considerable scatter. The trend of the parameter values was to be less effective

than predicted by other investigators. However, the scatter in the values and the lack of agreement between the two extraction methods imply a reduced confidence in the parameter values obtained.

 $C_{n\delta r}$ - The values determined for this parameter had magnitudes and trends as expected, and the agreement with the predictions of other investigators was good. Both extraction methods gave similar results, increasing the confidence in the values extracted.

Figure 6 shows the results of comparing runs where the actual surface deflection was measured with runs where the surface deflection was calculated based on stick position or rudder pedal position. Also shown are runs where only stick position and rudder pedal position were measured. The figure shows that the trends for all the calculated deflections seen are the same as those seen in figure 5. Also, where the scatter was such that trends were not detectable, the same was true for the runs using calculated deflections. In general, with one exception, the additional runs where surface deflections were calculated were a reasonable addition to the parameter data base.

The one exception is the rudder deflection. The rudder pedal position to surface deflection calibration was done at 0 Mach. The results indicate that for a given pedal position, the deflections of the rudder decrease above Mach .5. At Mach .6 the deflections are about two-thirds of the Mach 0 deflection, and at Mach .9 the rudder deflection is about one half to Mach 0 deflection. The parameter values extracted for $C_{l\delta r}$ and $C_{n\delta r}$ reflect this reduced rudder deflection in that a greater δ_r was calculated than actually existed, so the parameter values showed less effectiveness by about two-thirds.

The predictive capability of the lateral model was also checked and the results are shown as figures 7a and b. As with the longitudinal model check, a run that was not used for extraction was used for prediction. As can be seen in figures 7a and b, two mathematical models were used for prediction. The first used values determined from extraction runs made at similar angles-of-attack and Mach number, and the second used parameter values determined by wind tunnel tests where values were available and extracted values where wind tunnel values were not available. The actual values used for the parameters are shown on the figure. The prediction using extracted values was fairly good (Fig. 7a). However, the response to input using the wind tunnel parameters had a different phase than that of the actual vehicle (Fig. 7b). Figure 8 shows the fit and parameter values obtained when the prediction data set was used with the Maximum Likelihood program to estimate parameter values.

CONCLUSIONS

Flight tests were conducted using the FlO6B that will be used for a leading edge vortex flap study. These flight tests used the basic aircraft and were run at several conditions with emphasis on Mach numbers of .6 and .9 and at angles-ofattack greater than 10°. The trends of the parameters that describe up to 90 percent of the vehicle motion were established and were reasonable. For the majority of the runs, the magnitudes of parameters were reasonable as evidenced by the fact that when these values were used in a mathematical description of the vehicle, that mathematical model had good prediction capability. Additional runs should be made to get more data points at angles-of-attack above 12° at Mach numbers of .6 and .9. Three additional points at each Mach number should be sufficient to document the basic aircraft in the high angle-of-attack region. This documentation will then serve as a basis for evaluation of the modified aircraft.

TABLE I.- PHYSICAL CHARACTERISTICS OF THE F106B

Mass Range During Test: 1050 slug to 900 slug

Assumed Inertias

ĭx	19,000 slug-ft ²	19,000	
ľy	185,000 slug-ft ²	185,000	
^I z	200,000 slug-ft ²	200,000	
I _{XZ}	60,000 slug-ft ²	60,000	

Dimensional Characteristics:

Wing Area (S) 695.0	ft ²
Chord (C)	23.76	ft
Span (b)	38.13	ft

Variables	Range
(Time, Sec)	
V, ft/sec	0.0 to 1300.00
β, rad	± 0.52
α, rad	± 0.52
p, rad/sec	± 1.0
q, rad/sec	± 1.0
r, rad/sec	± 1.0
θ, rad/sec	± 0.52
φ, rad/sec	± 1.4
A _x , "G" units	± 1.0
A, "G" units y	± 1.0
A ['] , "G" units	+ 1.0 to - 7.0
δ, rad	± 0.122
δ [°] e, rad	+ 0.28 to42
δ [°] , rad	± 0.42

TABLE II.- F106B INSTRUMENTATION SYSTEM

Estimated accuracy 1 percent of full scale

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		ML; Surfa			ML; Stic	ek	Re	gression;	Surface	
		$\alpha_{\rm T} = 8$.7°		$\alpha_{\rm T} = 8$.7°	$\alpha_{\rm T} = 8.7^{\circ}$			
	M = .4				M = •4	ł		M = •4	4	
Parameter	Value	Standard Deviation	Sensitivity	Value	Standard Deviation	Sensitivity	Value	Standard Deviation	Sensitivity	
c _{xα}	•53	•093	•16E3	•65	•040	•9E3	•275	•0021		
C _{z0}	23	•0037°	. 17E6	22	.00055	•46E6	•224	.001		
$C_{z_{\alpha}}$	-2.11	•113	•31E4	-2.32	•021	•30E5	-2.15	•009		
C _{zq}	-6.61	2.25	•29E3	.69	•37	7.3	-3.27	.17		
C _{zδe}	66	•24	•21E2	34	•029	•25E3	663	•015		
$C_{m_{\alpha}}$	131	•0039	•32E5	12	•00057	•1E6	127	.0023		
с _{шq}	87	•235	•77E3	73	.018	•85E4	60	•043		
С _{щбе}	36	•021	•114E5	31	•0019	•1E6	35	•004		

TABLE III. - LONGITUDINAL PARAMETER IDENTIFICATION RESULTS

* (1) Surface denotes runs where actual control surface position was measured.

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(2) Stick denotes runs where stick position was measured and corresponding surface position calculated.

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(3) Regression denotes runs examined using the regression program of reference 2. ML denotes runs examined using the maximum likelihood program of reference 1.

		ML; Surfa			ML; Stie		Re	egression;		
		$\alpha_{\rm T} = 8$.5°		$\alpha_{\rm T} = 8$		$\alpha_{\rm T} = 8.5^{\circ}$			
		M = .4			M = .4			M = .4		
Parameter	Value	Standard Deviation	Sensitivity	Value	Standard Deviation	Sensitivity	Value	Standard Deviation	Sensitivity	
$c_{x_{\alpha}}$	•404	•087	•29E2	•426	•04	•17E3	•29	.0017		
c _{z0}	226	•0073	•17E5	217	.0015	•2E6	215	.003		
$C_{z_{\alpha}}$	-2.22	•215	•19E3	-2.49	.03	•14E7	-2.22	.013		
с _{гq}	-3.6	3.9	1.7	7.67	•95	•34E4	-3.38	•25		
C _{zδe}	30	•36	1.2	.118	•056	•55E2	-5.8	•02		
c _{mα}	14	•0062	•105E4	135	.00096	•9E6	133	•0025		
c _{mq}	-1.0	•20	•12E3	64	•034	•25E4	65	.049		
C _{mõe}	35	.02	•104E4	28	.0032	•92E6	33	.0043		
·		ML; Surfa	ace		ML; Stie		Re	egression;		
		$\alpha_{\rm T} = 1$.5°		$\alpha_{\rm T} = 1$	1.5°		$\alpha_{\rm T} = 1$	1.5°	
		M = .6	5	M = .6			M = .6			
Parameter	Value	Standard Deviation	Sensitivity	Value	Standard Deviation	Sensitivity	Value	Standard Deviation	Sensitivity	
C _{xα}	•61	•052	•3E3	•48	•036	•7E6	•2	•004		
c _{z0}	34	•0046	. 11E6	34	•0057	•13E8	34	•002		
$C_{z_{\alpha}}$	-2.46	•12	•19E4	-2.32	.13	•17E6	-2.5	.013		
C _{zq}	-13.1	3.7	•86E2	-8.8	3.9	•27E5	-6.0	.35		
C _{zðe}	56	•29	•15E2	33	•26	•68E4	6	•026		
$c_{m_{\alpha}}$	15	.0016	•23E5	147	•0024	•21E6	15	.0023		
c _{mq}	-1.31	•15	•28E3	6	•17	•79E5	96	.062		
C _{mδe}	41	•014	•62E4	32	.015	•25E5	37	•0046		

TABLE III. - LONGITUDINAL PARAMETER IDENTIFICATION RESULTS (CONTINUED)

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TABLE III. - LONGITUDINAL PARAMETER IDENTIFICATION RESULTS (CONTINUED)

		ML; Surfa	ace	[ML; Stic	 2k	Re	gression;	Surface	
		$\alpha_{\rm T} = 14$	•.3°		$\alpha_{\rm T} = 1^2$		$\alpha_{\rm T} = 14.3^{\circ}$			
•		M = .6	5		M = .6			M = .6		
Parameter	Value	Standard Deviation	Sensitivity	Value	Standard Deviation	Sensitivity	Value	Standard Deviation	Sensitivity	
C _{xa}	•85	•08	•17E5	•40	•88	•3E2	•134	•0041		
c _{z0}	46	.0023	•72E6	51	•027	•7E4	45	•003		
$C_{z_{\alpha}}$	-2.88	•041	•34E5	-3.52	•54	•6E3	-2.74	•0096		
°c _{zq}	-1.28	•87	9.0	14.2	11.4	•14E2	-7.15	•21		
C _{zδe}	51	•056	•25E3	1.5	•58	•25E2	73	•014		
$c_{m_{\alpha}}$	205	.0011	•16E6	20	.012	•28E4	193	•0034		
C _{mq}	-1.04	•03	•58E4	21	.31	4.6	-1.03	•075		
C _{m&e}	39	.0026	•92E5	31	•02	•13E4	38	•0048		
		ML; Surfa	ice		ML; Stic		Re	gression;	Surface	
		$\alpha_{\rm T} = 13$	3.7°		$\alpha_{\rm T} = 13$	3.7°		$\alpha_{\rm T} = 13$	3.7°	
		M = .3	32	M = .32			M = .32			
Parameter	Value	Standard Deviation	Sensitivity	Value	Standard Deviation	Sensitivity	Value	Standard Deviation	Sensitivity	
$c_{x_{\alpha}}$.445	•31	3.1	•47	.32	•23E2	•309	•0038		
c _{z0}	373	•0043	•44E5	375	•0044	•25E6	38	•002		
$C_{z_{\alpha}}$	-2.32	•23	•18E3	-2.42	.19	•28E5	-2.26	•016		
C _{zq}	-2.7	3.2	1.4	1.47	3.18	•71E2	-4.48	•26		
c _{zδe}	67	•22	•18E2	453	•18	•25E3	71	•018		
$c_{m_{\alpha}}$	16	•009	•84E3	149	.0085	•22E4	144	.0038		
C _{mq}	-1.01	•22	•98E2	57	•22	•64E2	744	•062		
C _{mδe}	355	.019	•12E4	29	.016	•49E5	35	•0042		

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1		ML; Surfa	ice		ML; Stic	 2k	Re	egression;	Surface		
		$\alpha_{\rm T} = 5$,7°		$\alpha_{\rm T} = 5$		$\alpha_{\rm T} = 5.7^{\circ}$				
		M = .9	· · · · · · · · · · · · · · · · · · ·		M = .9			M = .9			
Parameter	Value	Standard Deviation	Sensitivity	Value	Standard Deviation	Sensitivity	Value	Standard Deviation	Sensitivity		
$C_{\mathbf{x}_{\alpha}}$	•45	•048	•98E2	•55	•12	•26E2	.195				
c _{z0}	134	.0005	•22E6	-1.33	•0054	•18E5	135	•0008			
$C_{z_{\alpha}}$	-2.7	•027	•15E5	-2.80	•32	•19E3	-2.70	•011			
C _{zq}	-2.66	.64	•28E2	1.90	6.3	•21	-8.05	•25			
$c_{z_{\delta e}}$	65	•054	•26E3	.225	•44	•41	674	•022			
$C_{m_{\alpha}}$	254	.0008	•14E6	246	•0077	•24E4	262	•0044			
c _{mq}	-1.42	•032	. 76E4	75	•31	•25E2	-1.14	•096			
C _{mõe}	456	.0035	•58E5	34	•027	•65E3	443	•0084			
·		ML; Surfa	ice		ML; Stic	k	Re	gression;			
		$\alpha_{\rm T} = 17$	70	$\alpha_{\rm T} = 17^{\circ}$			$\alpha_{\rm T} = 17^{\circ}$				
P		M = .6		M = .6			M = .6				
Parameter	Value	Standard Deviation	Sensitivity	Value	Standard Deviation	Sensitivity	Value	Standard Deviation	Sensitivity		
$C_{x_{\alpha}}$	97	.094	•22E4	55	.076	•17E4	.052	•009			
c _{z0}	638	.012	•19E6	69	•0064	•21E6	604	.003			
$C_{z_{\alpha}}$	-2.93	.097	•29E4	-3.4	.084	•73E4	-2.84	.032			
C _{zq}	3.45	3.8	•37E2	18.7	1.98	•68E4	-9.16	•85			
$c_{z\delta e}$	501	•165	•31E2	083	.083	2•4	72	.043			
$C_{m_{\alpha}}$	194	•0037	•18E5	157	.0014	•43E8	19	.0055			
c _{mq}	-2.95	•14	•14E5	-2.59	.10	•23E5	-1.25	.145			
C _{mδe}	458	.011	•24E5	43	.007	•52E5	40	.0073			

TABLE III. - LONGITUDINAL PARAMETER IDENTIFICATION RESULTS (CONTINUED)

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		ML; Surfa			ML; Stie		Re	gression;	Surface	
		$\alpha_{\rm T} = 15$			$\alpha_{\rm T} = 15$		$\alpha_{\rm T} = 15.7^{\circ}$			
h		<u>M</u> = •9) 		M = .9			M = .9		
Parameter	Value		Sensitivity	Value		Sensitivity	Value		Sensitivity	
		Deviation			Deviation			Deviation		
$C_{x_{\alpha}}$	1.38	•12	•15E5	1.6	•4	•6E6	03	•0057		
c _{z0}	578	•0045	•34E6	64	•06	•31E5	573	•003		
$C_{z_{\alpha}}$	-2.92	•049	•29E5	-2.84	•48	•13E6	-2.86	•026		
C _{zq}	-14.6	•78	•35E4	7.4	26.8	•13E4	-11.5	•66		
C _{zδe}	637	•072	•38E3	.83	1.4	•15E3	836	•042		
$c_{m_{\alpha}}$	31	.0028	. 14E6	23	•024	•13E7	287	.008		
c _{mq}	77	.056	•64E3	46	.81	•3E5	-1.22	•20		
с _{тбе}	61	.0065	•12E6	47	•081	•12E5	51	.013		
I		ML; Surfa	ace		ML; Stid	ck	Re	egression;	Surface	
		$\alpha_{\rm T} = 15$			$\alpha_{\rm T} = 13$			$\alpha_{\rm T} = 1$		
		M = .9)	M = .9			M = .9			
Parameter	Value	Standard Deviation	Sensitivity	Value	Standard Deviation	Sensitivity	Value	Standard Deviation	Sensitivity	
$C_{x_{\alpha}}$	•69	.33	•25E3	.67	•069	•52E4	.013	.0036		
c _{z0}	55	•05	•79E4	54	•00 9	•17E6	•504	•003		
$C_{z_{\alpha}}$	-2.91	•7	•41E3	-2.97	•095	•87E4	-2.8	•019		
C _{zq}	-1.41	15.3	•18	-1.31	2.4	2.7	-8.7	•44		
c _{zδe}	1.2	•88	23.6	•43	.19	68.4	69	•033		
$c_{m_{\alpha}}$	25	•016	•21E4	24	•0028	•21E5	24	•006		
c _{mq}	-2.42	•53	•35E3	-2.08	•10	•29E4	-1.27	.13		
c _{mδe}	58	.046	•27E4	55	.0093	•24E5	45	•01		

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		ML;Surfa	 ce		ML; Stic		Regression; Surface			
		$\alpha_{\rm T} = 8$			$\alpha_{\rm T} = 8$.7°	$\alpha_{\rm T} = 8.7^{\circ}$			
P		M = •4			M = •4	+		M = .4	¥	
Parameter	Value	Standard Deviation	Sensitivity	Value	Standard Deviation	Sensitivity	Value	Standard Deviation	Sensitivity	
Cyß	468	•02	•75E3	49	•01	•37E4	50	.006		
с _{ур}	0			0			.021	.023		
Cyr	0			0			•27	.105		
$c_{y\delta_a}$.19	•049	•17E2	.16	•02	•7E2	•164	•014		
$c_{y\delta r}$.064	•011	•37E2	.028	.0033	•9E2	.056	•0032		
С _{г 3}	053	.0009	•15E5	054	•0006	•14E8	054	•0006		
C _l p	124	.0061	•41E4	116	.0018	•12E8	107	•0024		
C _l r	.106	•026	•17E3	006	.009	7.3	.194	.011		
С _{гба}	086	•004	•11E5	072	•0017	•25E5	088	.0014		
Clor	.015	.0007	•92E3	.007	•0002	•11E5	.012	.0003		
С _{пв}	•08	.0015	•2E5	.082	•001	•17E6	•090	.0019		
C _{np}	027	.0097	•11E3	.068	•004	•12E5	.018	•007		
C _n r	20	•033	•33E3	•29	•014	•12E5	107	.032		
c _{nða}	057	•0065	•36E3	068	•0052	•14E5	046	•0043		
C _{nor}	054	•0005	•24E6	037	.0003	•14E6	051	.001		

TABLE IV. - LATERAL PARAMETER IDENTIFICATION RESULTS

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 \star (1) Surface denotes runs where actual control surface position was measured.

- (2) Stick denotes runs where stick position was measured and corresponding surface position calculated.
- (3) Regression denotes runs examined using the regression program of reference 2. ML denotes runs examined using the maximum likelihood program of reference 1.

		ML; Suri			ML; Stie	ck	Re	gression;		
		$\alpha_{\rm T} = 8$			$\alpha_{\rm T} = 8$		$\alpha_{\rm T} = 8.5^{\circ}$			
r		M = .4	······································		M = .4	f=		M = .4		
Parameter	Value	Standard Deviation	Sensitivity	Value	Standard Deviation	Sensitivity	Value	Standard Deviation	Sensitivity	
с _{ув}	486	•0046	. 16E5	51	.009	•6E4	51	.0032		
с _{ур}	0			0			0			
c _{yr}	0			0			.225	•055		
с _{уба}	.182	•0089	•45E3	•17	.015	.15E3	.16	•0067		
C _{yor}	•056	•0022	.77E3	.023	•0025	.95E2	•055	.0016		
ClB	054	.0003	•2E6	056	.00002	. 12E7	054	.0006		
C _{lp}	143	.0008	•25E6	135	•0006	. 7E5	12	.0021		
C _{lr}	•045	.0071	.18E3	138	•0027	•7E4	•15	.011		
С _{гба}	095	•0009	•32E5	080	.011	. 12E6	089	.0014		
c _{lor}	.014	.0002	.16E5	.006	.0018	.18E5	.012	•0003		
c _{n_β}	•080	.0005	•24E6	•080	•0008	•14E7	.093	.0016		
C _{np}	.016	.0033	•48E3	.113	•005	•26E5	•043	.0051		
C _n r	302	.013	•51E4	.36	•018	•36E5	025	•027		
$c_{n_{\delta a}}$	040	.0023	•28E4	001	.0038	•27E2	045	.0033		
c _{n { r}	059	•0004	. 13E6	042	•0004	•5E6	051	.0008		

TABLE IV. - LATERAL PARAMETER IDENTIFICATION RESULTS (CONTINUED)

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i		ML; Surf	ace		ML; Stic	k	Regression; Surface			
		$\alpha_{\rm T} = 13$	3.7°		$\alpha_{\rm T} = 13$	3.7°	$\alpha_{\rm T} = 13.7^{\circ}$			
		• M = •3			M = .3			M = .3	32	
Parameter	Value	Standard Deviation	Sensitivity	Value	Standard Deviation	Sensitivity	Value	Standard Deviation	Sensitivity	
с _у _β	51	.016	• 3E4	48	.021	•21E4	436	•009		
с _{ур}	0 -			0			.151	•018		
Cyr	0			0			1.08	•14		
с _{уба}	.19	.013	•36E3	•16	.017	.18E3	•138	•008		
C _{y5r}	.05	.003	•40E3	•26	.0031	•12E3	.039	•002		
c _£ β	067	.0015	•81E6	066	.0023	•33E6	058	.0014		
С _{2р}	111	.0013	•6E5	062	.0021	•19E5	117	•0027		
Clr	013	•02	•45E2	263	.028	•16E5	•139	•02		
Cloa	090	•0008	•17E6	095	.0011	•11E6	095	•0012		
Clor	•009	•0002	•25E5	•004	.0003	•64E4	•009	•0003		
c _{ng}	•11	.0051	•53E6	•067	•0082	•98E5	•062	•004		
C _{np}	.006	.0061	•41E2	063	•0085	•36E4	.01	•0076		
C _{nr}	•114	•072	•136E4	.109	•091	•96E3	133	.060		
c _{nôa}	09	.0016	•72E5	070	.0026	•31E5	030	.0035		
C _{nor}	03	.0013	•96E5	023	.0015	•43E5	036	•000 9		

TABLE IV. - LATERAL PARAMETER IDENTIFICATION RESULTS (CONTINUED)

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		ML; Surf	ace		ML; Stic		Reg	gression; S	Surface	
		$\alpha_{\rm T} = 5$			$\alpha_{\rm T} = 5$		$\alpha_{\rm T} = 5.7^{\circ}$			
·		M = .9			M = •9)		M = .9		
Parameter	Value	Standard Deviation	Sensitivity	Value	Standard Deviation	Sensitivity	Value	Standard Deviation	Sensitivity	
с _{уд}	52	.0035	•4E5	51	•0069	•89E4	59	.002		
с _{ур}	0			0			.16	•008		
^C yr	0			0			.70	•047		
с _{уба}	•23	.013	•5E3	.117	•022	•4E2	.19	.0077		
c _{yor}	•067	•0024	•9E3	.036	•0025	•25E3	.046	.0017		
Cla	053	.0005	•54E6	054	•0006	•27E6	051	•0005		
C ₂ p	147	•0032	•8E5	142	.0021	•17E5	124	.0019		
C _e r	123	.019	•47E5	.10			.37	.011		
С _{¢ба}	094	.0015	•8E5	072	•0024	•3E5	108	.0018		
C _{¢ðr}	•020	•0002	•47E5	.013	.0002	•44E5	.017	•0004		
c _{nβ}	.098	.0007	•95E6	.099	.0005	•42E6	•14	.0009		
C _{np}	089	.0045	•3E5	047	•002	•27E4	.123	.0036		
C _n r	.657	.027	•41E5	40			022	.022		
C _{nδa}	092	.0026	•26E5	09			039	.0035		
C _{n & r}	061	•0004	•22E6	027	•00034	•7E5	054	.0008		

TABLE IV. - LATERAL PARAMETER IDENTIFICATION RESULTS (CONTINUED)

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	ML; Surface				ML; Sti		Regression; Surface		
	$\alpha_{\rm T} = 11.5^{\circ}$				$\alpha_{\rm T} = 1$		$\alpha_{\rm T} = 11.5^{\circ}$		
	M = .6				M = .0	•		M = .6	5
Parameter	Value	Standard Deviation	Sensitivity	Value	Standard Deviation	Sensitivity	Value	Standard Deviation	Sensitivity
с _{ув}	53	.0064	•72E6	48	.04	•4E6	5	.0024	
с _{ур}	0			0			.087	.010	
с _{уг}	0			0			1.32	.061	
c _{yδa}	•173	•016	•20E3	•35	•12	•2E4	•2	.0078	
c _{yδr}	•067	•0026	. 19E5	.055	.015	•2E4	•064	.0012	
c _{ℓβ}	064	.0011	•21E7	074	.006	•96E6	071	.0005	
с _{ер}	17	•0041	•26E6	18	.019	•19E7	145	.002	
Clr	32	.023	•98E4	089	.082	•35E5	.227	.012	
Cloa	086	•0037	•12E7	075	.017	•46E6	115	.0015	
Clor	.019	•0005	. 18E6	.013	.0017	•37E6	.015	.00023	
c _{nβ}	•069	.0021	•8E6	•064	.012	•16E5	.083	.0012	
C _{np}	007	.0063	•24E2	006	•044	•51E2	.002	.005	
c _{nr}	503	•042	•9E5	017	•22	•5	34	.030	
c _{nőa}	133	•0076	. 7E6	096	.031	•15E5	045	.0038	
C _{nôr}	056	.0009	•18E7	038	.0035	•87E5	055	•00057	

TABLE IV. - LATERAL PARAMETER IDENTIFICATION RESULTS (CONTINUED)

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	$\frac{\text{ML; Surface}}{\alpha_{T} = 14.3^{\circ}}$				$\frac{ML; Stic}{\alpha_T = 1}$	ck v 2°	$\frac{\text{Regression; Surface}}{\alpha_{T} = 14.3^{\circ}}$			
	$\frac{a_{\rm T}-14.5}{M=.6}$				$\frac{\alpha_{\rm T} = 12}{M = .6}$		M = .6			
Parameter	Value	<u></u>	Sensitivity	Value	Standard Deviation	Sensitivity	Value		Sensitivity	
с _{уβ}	•42	.31	•44E2	43	.0095	•34E4	45	.0055		
c _{yp}	0			0			024	.019		
Cyr	0			0			84	•134		
$c_{y_{\delta a}}$	1.98	•48	•61E2	•24	•014	•57E3	•24	.011		
C _{yor}	49	.10	.11E3	.061	.0031	•47E3	•066	•0026		
c _{ℓβ}	107	.0029	•22E5	108	•0015	•58E5	11	•0009		
С _{¢р}	18	.0092	•51E4	17	.0043	•8E4	176	.003		
C _{lr}	.19	•072	•15E3	41	•038	•23E4	•287	.022		
$c_{l_{\delta a}}$	118	.0042	•28E4	083	•0026	•6E4	127	.0017		
Clor	.017	.0010	•15E4	.008	.00042	•15E4	.015	•0004		
c _{ng}	.051	•0057	•19E4	.062	.0026	.19E5	.067	.0018		
c _{np}	.034	.020	.37E2	.032	.0065	•12E3	•037	•0062		
^C nr	5	.113	•79E3	.19	.057	•11E4	013	•043		
C _{nða}	035	.0079	•22E3	.0022	.0025	•1E2	035	•0034		
C _{n&r}	059	.0030	•45E4	040	•00074	•27E5	055	•0008		

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TABLE IV. — LATERA	L PARAMETER	IDENTIFICATION	RESULTS	(CONTINUED)
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		ML; Surf			ML; Stick			Regression; Surface			
	$\alpha_{\rm T} = 14.5^{\circ}$				$\alpha_{\rm T} = 14.5^{\circ}$			$\alpha_{\rm T} = 14.5^{\circ}$			
		M = .6	·····		M = .6		M = .6				
Parameter	Value	Standard Deviation	Sensitivity	Value	Standard Deviation	Sensitivity	Value	Standard Deviation	Sensitivity		
c _{y_β}	43	.014	•12E4	38	•01	•2E4	38	•0054			
c _{yp}	0			0			•12	•02			
c _{yr}	0		 -	0			1.4	.107			
$c_{y_{\delta a}}$	•21	.019	•14E3	.23	.011	•7E3	.186	.0075			
c _{yðr}	•07	.0058	.23E3	.054	•0028	•54E3	•07	.0024			
$c_{\ell_{\beta}}$	098	.001	•9E5	085	•0009	•23E6	105	.0009			
C _{lp}	16	.0048	•1E5	103	.0037	•15E5	145	.0035			
Clr	•27	.015	•46E4	.57	.013	•8E6	•29	.019			
$c_{\ell \delta a}$	11	.0011	•4E5	097	•0008	•9E6	13	.0013			
C _{lor}	.019	.0004	•31E5	.015	.0003	•25E6	.015	•0004			
c _{n_β}	.082	.0014	•25E5	.065	.0013	•46E5	•08	.0016			
c _{np}	.0057	.0075	6.8	019	•0054	•54E3	.015	•006			
c _{nr}	034	.02	•24E3	.25	.017	•36E6	•14	.032			
C _{n sa}	048	.0016	•4E4	05	.0012	. 7E6	035	.0023			
c _{nőr}	052	.00067	•24E6	033	•0004	•23E7	054	.0007			

TABLE IV. - LATERAL PARAMETER IDENTIFICATION RESULTS (CONTINUED)

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	ML; Surface			ML; Stick			Regression; Surface			
$\alpha_{\rm T} = 15.7^{\circ}$				$\alpha_{\rm T} = 15.7^{\circ}$			$\alpha_{\rm T} = 15.7^{\circ}$			
		M = .9			M = • °	······································		M = •9)	
Parameter	Value	Standard Deviation	Sensitivity	Value	Standard Deviation	Sensitivity	Value	Standard Deviation	Sensitivity	
с _{уβ}	26	.27	3.6	46	•014	•13E4	5	•009		
с _{ур}	0			0			08	•022		
c _{yr}	0			0			•19	. 18	1	
c _{yδa}	.71	•38	•22E2	.13	•016	•9E2	•17	•012		
C _{yδr}	086	•136	7.1	•22	•0043	• 3E2	•03	•005		
С _{ев}	107	.0092	• 35E4	086	.0015	•94E5	116	•002		
с _{¢р}	18	•023	•15E5	08	.0035	•41E4	164	•005		
C _{lr}	•43	.17	•26E3	•55	•033	•62E5	•38	•04		
С _{еба}	14	.0089	•55E4	114	.0012	•15E6	146	•0025		
Clor	.024	.0027	•46E4	.012	•0005	•99E4	•017	•001		
c _{nß}	.082	•011	•11E4	.089	.0024	•73E5	•098	•0026		
c _{np}	01	.025	•10E3	004	•006	3.0	•031	•006		
C _n r	48	•22	•15E3	.19	.053	•74E4	14	•050		
с _{пба}	061	•013	•44E3	056	.0021	•3E5	035	•0032		
c _{nðr}	058	.0066	.44E5	024	•0008	•14E5	054	•0013		

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TABLE IV. - LATERAL PARAMETER IDENTIFICATION RESULTS (CONTINUED)

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	ML; Sorface				ML; Stic	k	Regression; Surface		
		$\alpha_{\rm T} = 15$			$\alpha_{\rm T} = 1$		$\alpha_{\rm T} = 15.5^{\circ}$		
r=	M = .9				M = •9	······································		M = •9	•
Parameter	Value	Standard Deviation	Sensitivity	Value	Standard Deviation	Sensitivity	Value	Standard Deviation	Sensitivity
с _{уβ}	51	.016	•13E4	57	•27	9.4	56	•0064	
с _{ур}	0			0			12	•02	
C _{yr}	0		••••••	0			.008	•11	
$c_{y_{\delta a}}$	•26	.024	•15E3	•45	•38	11.6	.19	.0093	
c _{yðr}	•068	.0071	•11E3	086	.077	13.4	.053	.0027	
c _{ℓβ}	11	•000 9	. 1E6	17	.011	•27E4	11	.002	
С _{ер}	17	•0028	•22E5	08	.032	•15E3	18	.006	
Clr	•34	.018	•15E5	.18	•21	41.0	.61	.034	
$C_{\ell_{\delta a}}$	15	.001	•84E5	13	.011	•41E4	17	.0028	
Clor	•018	.0035	•13E5	.013	.0026	•38E3	.017	.0008	
c _{nβ}	•076	.0019	•46E4	.08	•024	•3E3	.093	.0019	
c _{np}	.011	.0071	20.0	.083	.072	18.0	.0016	.0059	
c _{nr}	61	•029	•42E5	.37	•42	54.7	28	.033	
C _{nδa}	10	.002	•17E5	073	.026	•28E3	057	.0027	
C _{nor}	064	.0007	•54E5	031	•005	•38E3	060	•0008	

TABLE IV. - LATERAL PARAMETER IDENTIFICATION RESULTS (CONTINUED)

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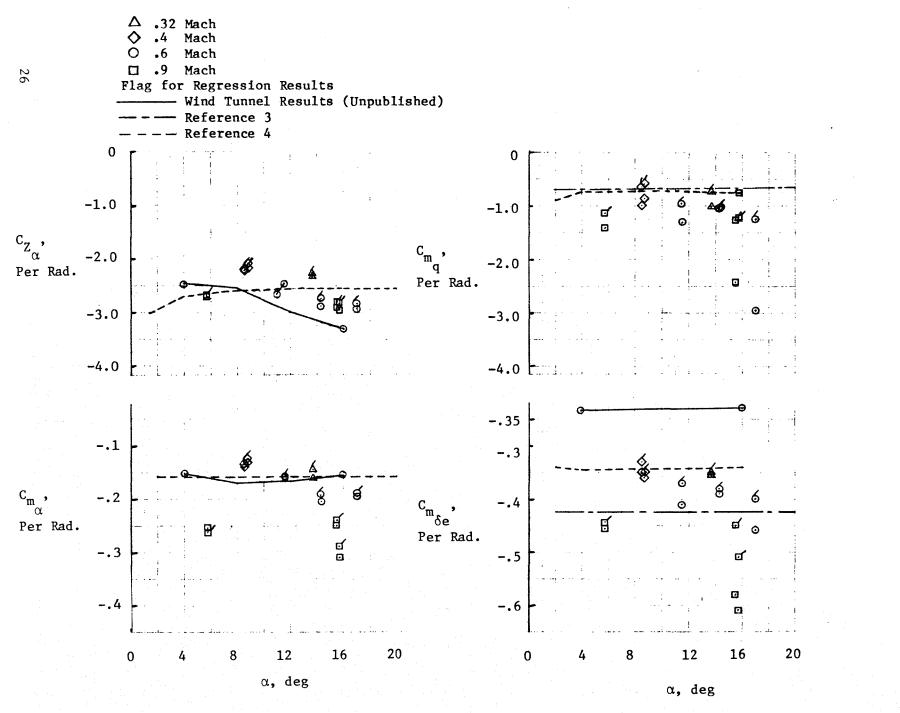
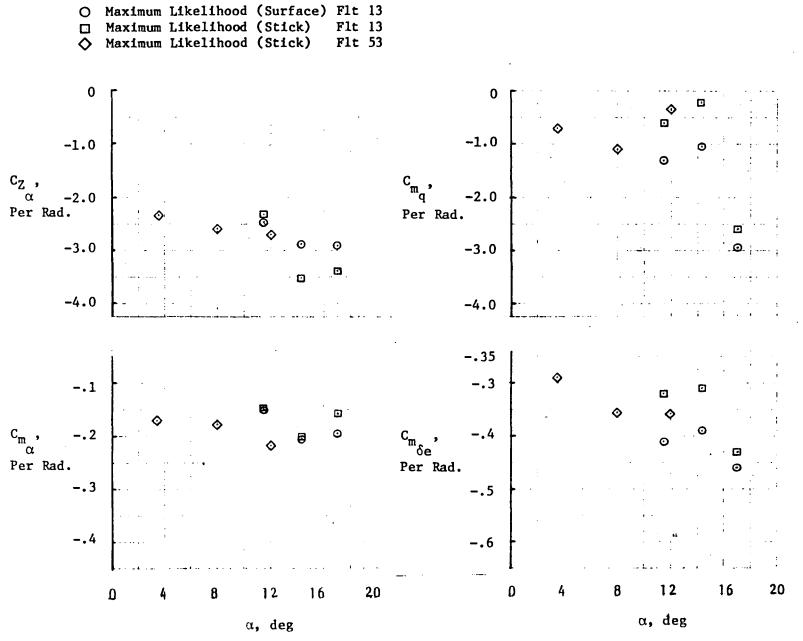
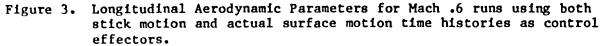
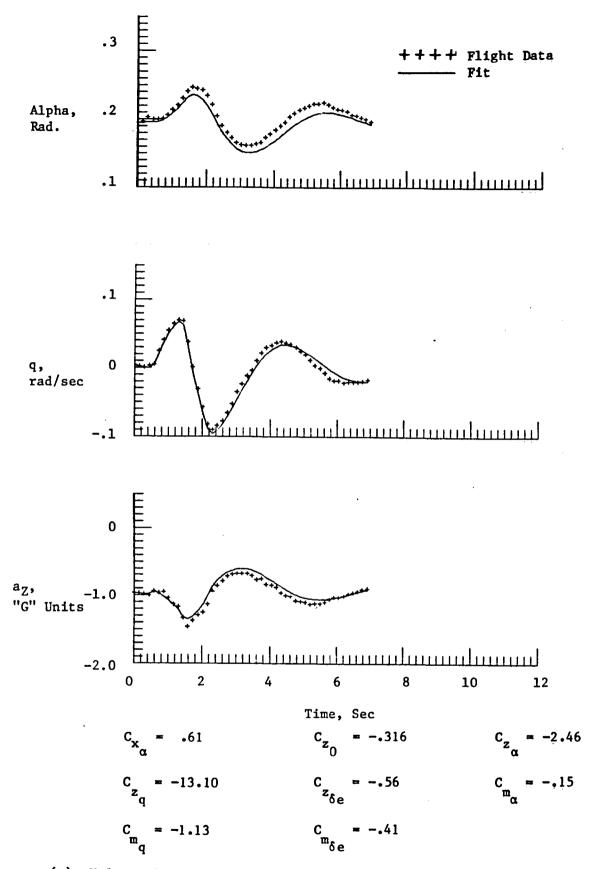


Figure 2. Longitudinal Aerodynamic Parameters plotted against trim angle-of-attack for several Mach Numbers.







(a) Values obtained from other parameter extraction runs. M=.6, α_T =11.5°.

Figure 4. Longitudinal Predictions Runs

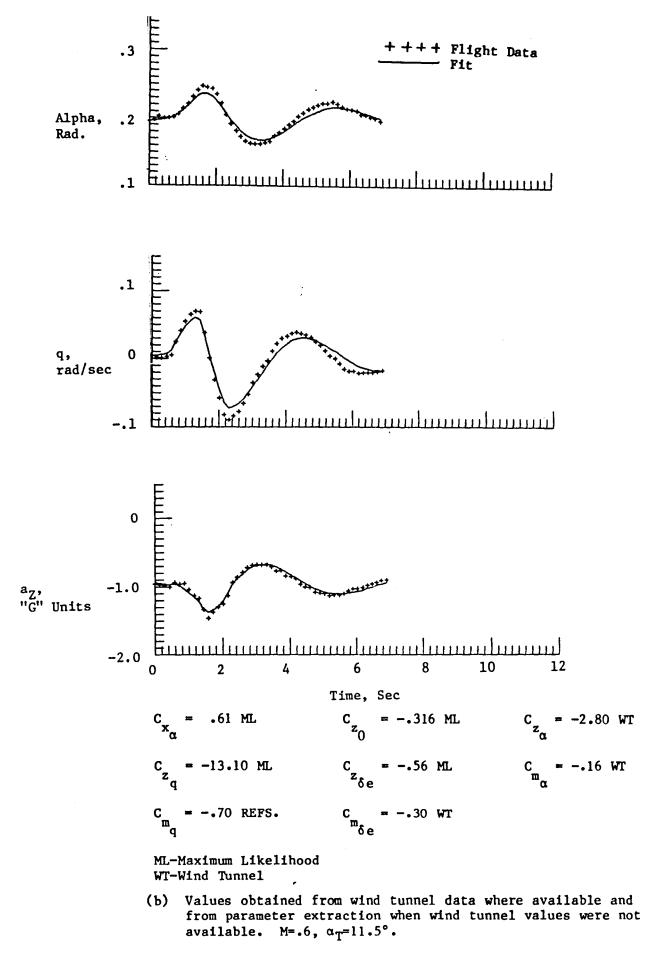
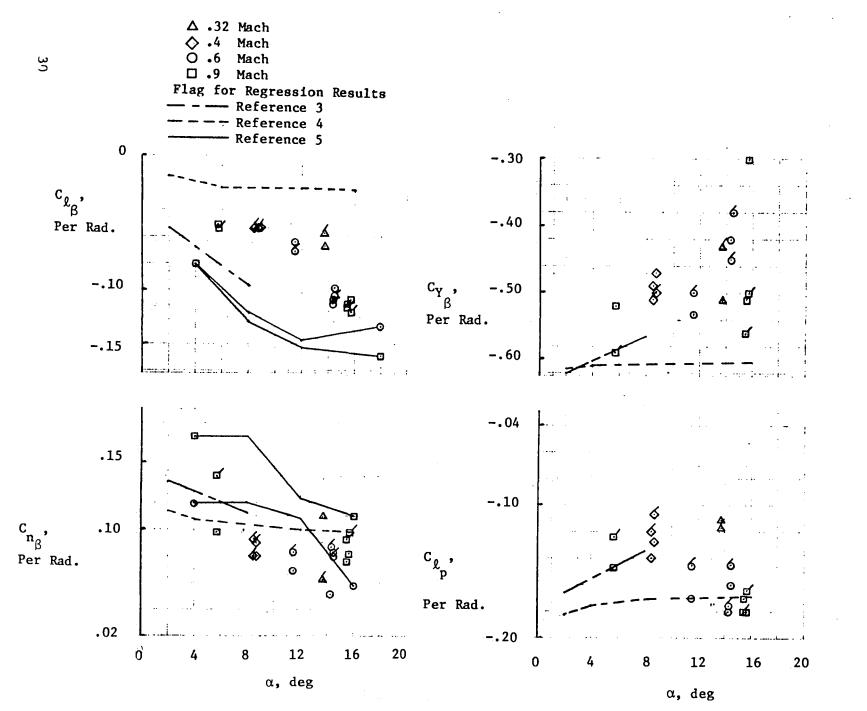
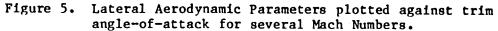


Figure 4 (Concluded)



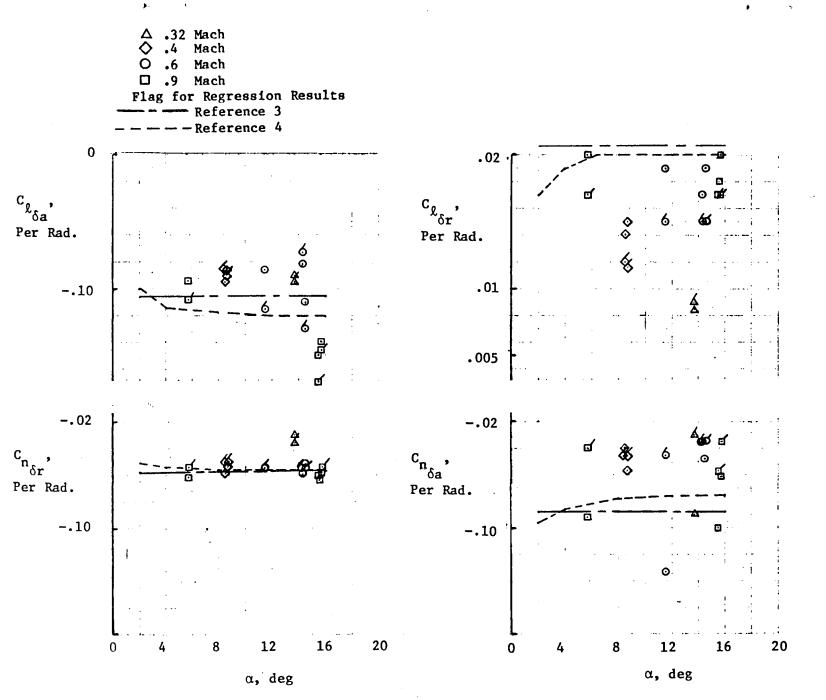
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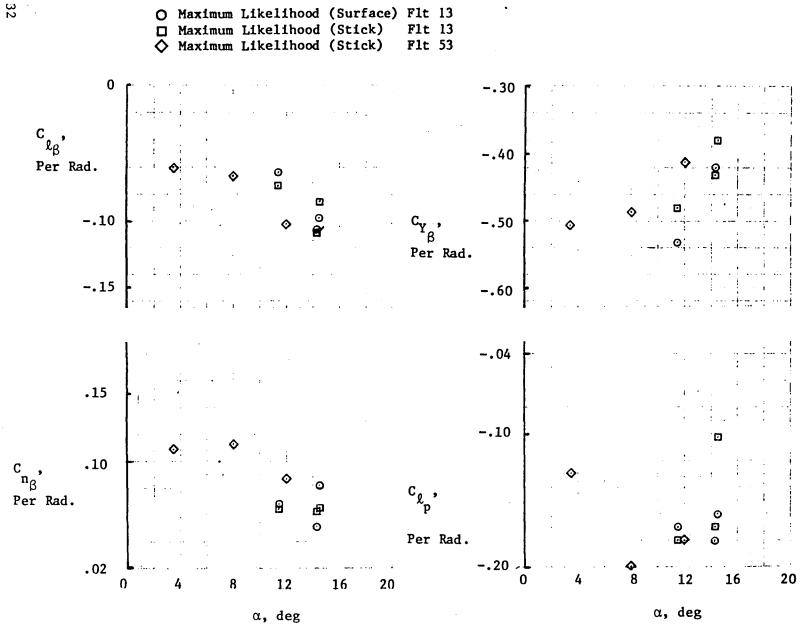
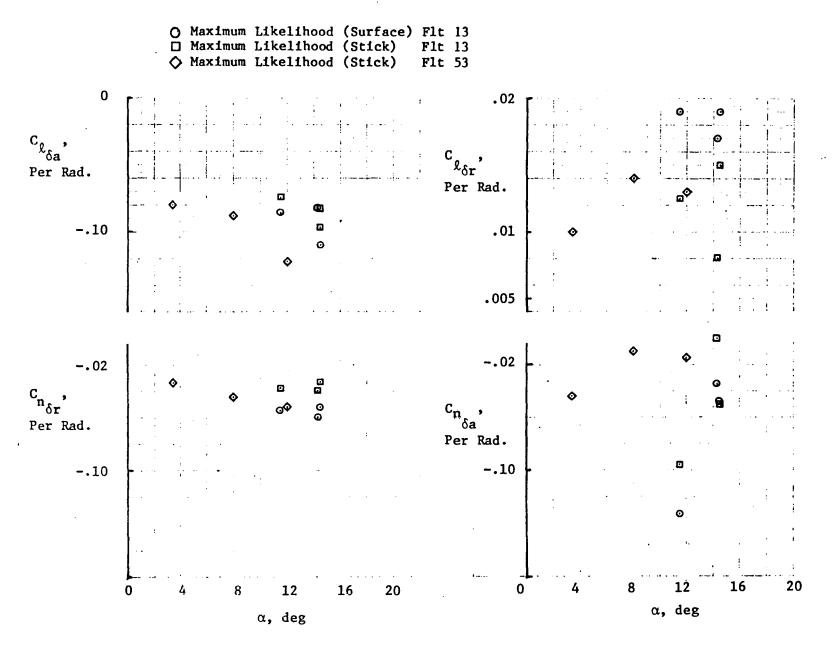
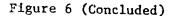


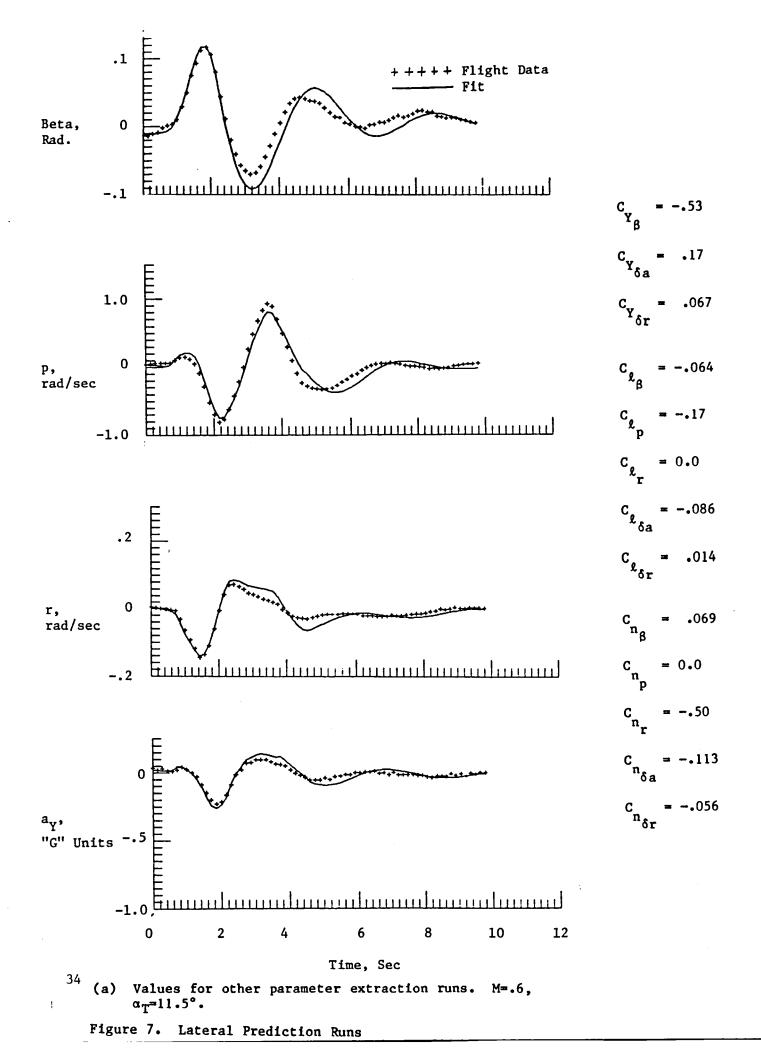
Figure 6. Lateral Aerodynamic Parameters for Mach .6 runs using both stick motion and actual surface motion time histories as control effectors.

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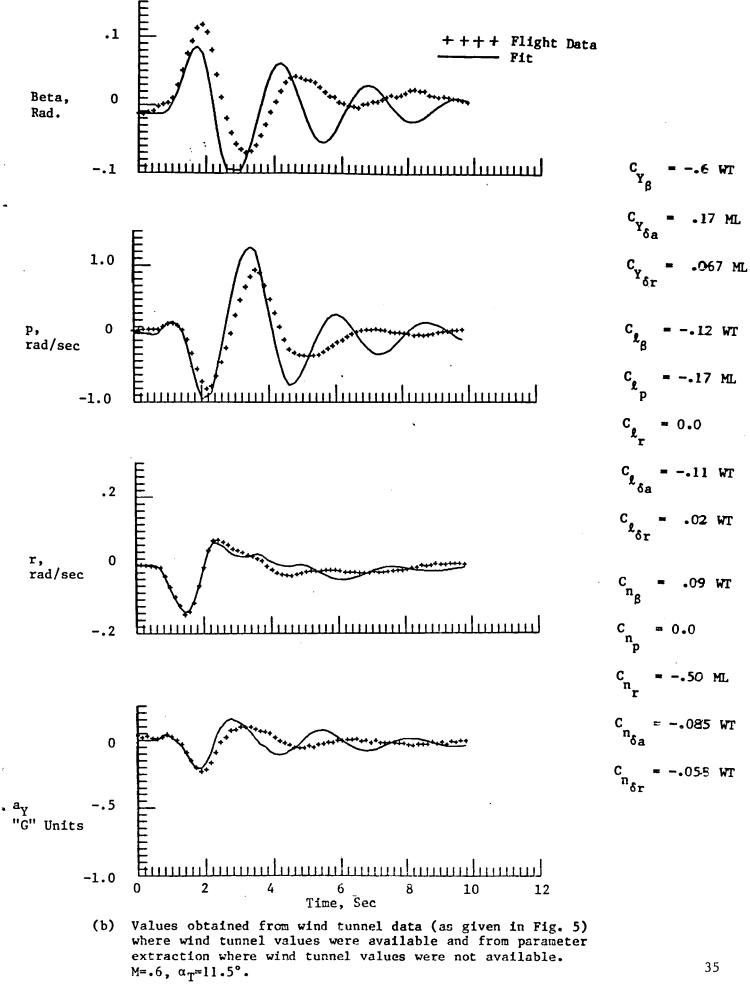
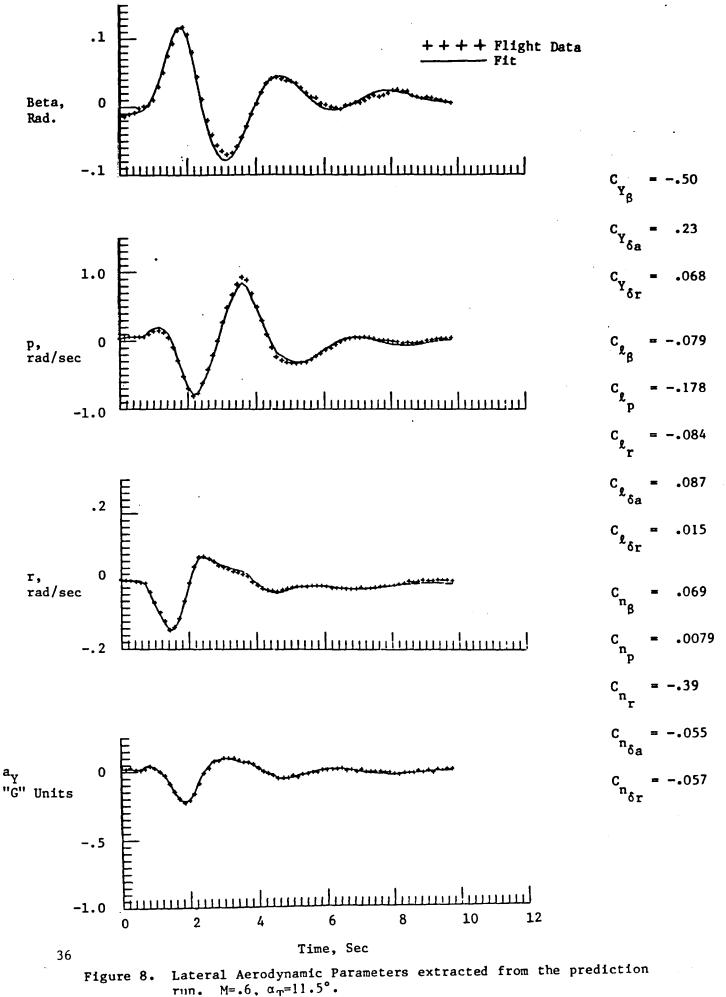


Figure 7 (Concluded)



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