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EXPERIMENTAL STUDIES ON THE STABILITY AND TRANSITION  
OF THREE-DIMENSIONAL BOUNDARY LAYERS

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16. Abstract <p>By means of various experimental methods, three-dimensional unstable boundary layers are examined concerning their characteristic instabilities which lead to turbulence. Using a swept cylinder, it was possible, using the hydrogen bubble method, to make standing cross flow instabilities and travelling waves visible in the boundary layer above the wall. Other experiments were conducted using the sublimation method and hot film technique on a model consisting of a swept flat plate with a pressure-inducing displacement body in the 1-meter wind tunnel. These experiments also produced both standing cross flow instabilities (<math>\lambda \approx 4.699.9x</math>) and travelling waves in a broad frequency band. The instabilities observed in the model are a close approximation of the theoretical predictions.</p>			
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## LIST OF SYMBOLS

c	0.50 m, plate depth
$C_p = \frac{P - P_\infty}{\rho/2 \cdot U_\infty^2}$	correction value for pressure, relative to the velocity component perpendicular to leading edge
d	0.20 m, cylinder diameter
E(t)	hot wire or hot film signal at output end of anemometer
E <sub>s</sub> (t)	hot wire or hot film signal after taking off a constant voltage and amplification
E <sub>c</sub> (t)	a constant voltage and amplification
f	frequency of travelling wave
$F_\delta = 2 \pi f \cdot \delta / Q_e$	normed frequencies
$F = 2\pi f \cdot \sqrt{\gamma x / U_e} / Q_e$	normed frequencies
H <sub>12</sub>	shape parameter of the velocity profile projected onto the (x <sub>t</sub> , z) plane
K	constant discretionary voltage
$k = (\alpha, \beta)$	wave vector
$k_i = (\alpha_i, \beta_i)$	excitation vector
L	standardization length
P	pressure
p	nonstationary pressure variations
Q	velocity vector
Q <sub>0</sub>	standardization velocity
q	disturbance velocity vector
Re	Reynolds number, obtained with c or d
$R = V_e \cdot \eta / \gamma$	characteristic Reynolds number for the flow in stagnation area where
	$\eta = \sqrt{\frac{\nu}{dU_e/dx _{x=0}}}$
t	time

Tu	amount of turbulence
U, V, W	velocity components of the main flow in the body coordinate system
U <sub>t</sub> , V <sub>t</sub> , W	velocity components of the main flow in the streamline coordinate system
u, v, w	nonstationary velocity components
x, y, z	body coordinate system x: wall coordinate perpendicular to leading edge y: wall coordinate parallel to leading edge z: perpendicular to wall
x <sub>t</sub> , y <sub>t</sub> , z	streamline coordinate system x <sub>t</sub> : wall coordinate tangential to local streamline at edge of boundary layer y <sub>t</sub> : wall coordinate normal to local streamline at edge of boundary layer
$\alpha = \alpha_r + \alpha_i$	complex non-dimensional wave number in direction x
$\beta = \beta_r + \beta_i$	complex non-dimensional wave number in direction y
$\gamma$	angle at circumference between stagnation line and bubble wire on the cylinder
$\delta$	99.9% boundary layer thickness
$\delta^*$	non-dimensional 99.9% boundary layer thickness
$\lambda$	wavelength measured perpendicular to propagation direction of wave
$\lambda''$	wavelength measured parallel to leading edge
$\nu$	kinematic viscosity
$\rho$	density
$\phi_0$	sweep angle, i.e. angle between the vector of undisturbed forward flow $Q_\infty$ and x, the perpendicular to the leading edge
$\phi(x)$	local sweep angle of the streamline at the boundary layer edge, i.e. angle between x and x <sub>t</sub>
$\phi_{Q1}(x)$	local sweep angle of the stationary waves to the x axis

$$\chi = V_{t \max} \cdot \Delta / \nu$$

cross flow Reynolds number where

$$\Delta = \int V_t / V_{t \max} dy$$

angle between  $x_t$  and the propagation direction of a wave

$\psi$

angle between  $x_t$  and the propagation direction of a wave

$\psi'$

angle between  $x$  and the propagation direction of a wave

$$\omega = \omega_r + \omega_i$$

complex non-dimensional frequency

EXPERIMENTAL STUDIES ON THE STABILITY AND TRANSITION  
OF THREE-DIMENSIONAL BOUNDARY LAYERS

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1. INTRODUCTION

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The occurrence of instability in a laminar boundary layer and the accompanying turbulent transition are highly significant for many technical applications. For example, the transition causes the resistance of a laminar wing to change considerably. If it is possible to keep the boundary layer on this airfoil laminar by influencing its physical properties, an aircraft's fuel consumption can be decreased as a result of diminished friction.

However, sufficient understanding of the physics of the instability which occurs is required. The present work is intended to provide new depth to this understanding.

Reynolds was the first to develop the notion that a laminar flow will become unstable when very small initial disturbances grow under certain conditions until they finally cause transition. This idea led to the mathematical concept of introducing small disturbance factors into the Navier-Stokes equation and calculating the excitation or attenuation of these disturbances.

For two-dimensional boundary layers, the Orr-Sommerfeld equation can be applied with a few simplifications. This equation was solved for the Blasius boundary layer by Tollmien in 1929 (see Schlichting [38]). He created a stability diagram which was confirmed experimentally by Schubauer and Skranstad [40]. In spite of some simplification, the theory was able to correctly describe the boundary layer's reaction to induced disturbances. The theory also provides useful criteria for the behavior of flat boundary layers with pressure gradients and for boundary layers on slightly curved surfaces as far as stability is concerned. After surpassing a certain excitation of disturbance waves all the way up to turbulence, the other processes can no longer be described by the linear theory of stability. For practical applications, various empirical criteria or, when the results of the theory /12 of stability were used, semi-empirical theories were developed, such as the so-called  $e^n$  method. These methods predicted the site of transition in two-dimensional boundary layers with satisfactory accuracy.

However, these criteria, which were found for flat boundary layers, are not valid for three-dimensional boundary layer profiles as they occur in the case of swept wings. The theoretical treatment of the three-dimensional boundary layer with

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\*Numbers in the margins indicate pagination of the foreign text.

regard to stability is much more complicated. Since velocity profiles are warped, one can no longer assume a preferred direction of the propagation of disturbing waves, as one could at the two-dimensional level.

Experimentally Gray [12] and Owen and Randall [25] observed the characteristic peculiarities of transition of three-dimensional boundary layers on arrowhead wings.

- As the angle of sweep increases, the site of transition is transferred to smaller Reynolds numbers and transition takes place, especially in the area of decreasing pressure, which is very stable in a two-dimensional model.
- In all experiments, before actual transition took place, regular stationary striations were observed in the area of decreased pressure using the sublimation method.
- As a third conspicuous phenomenon, Owen and Randall discovered that under certain experimental conditions the boundary layer even became turbulent in the region of the leading edge.

In spite of these crucial observations, there is a lack of systematic experimental studies in which the theory can be examined or which point the way to potential simplifications of the theory.

It is the goal of the present work to experimentally examine three-dimensional boundary layers in the areas of decreasing pressure. First, in Section 2, a brief summary of the experimental and theoretical results of other authors will be /13 presented. Section 3 deals with an experiment based on a suggestion by Hirschel and Dallmann [17]. They seized upon an idea of van den Berg and Elsenaar [4], who had built a model out of a swept plate with impressed pressure gradient in order to study turbulent, three-dimensional boundary layers. They suggested the construction of a similar model to study laminar turbulent transition. This model meets the requirements of the theory quite well, thereby enabling direct comparison of results. Such a model was constructed for the DFVLR 1-meter wind tunnel in Göttingen. The resulting boundary layer was examined by making the flow visible on the surface of the plate (sublimation and painting method) and using hot film measurements for stationary and travelling waves. The results were compared with computations done by Bieler [5] at the institute for theoretical flow mechanics of the DFVLR Göttingen. The actual site of the transition was compared with the prediction using a criterion developed by Coustols (1983) for the transition of three-dimensional boundary layers.

It was the aim of another experiment using an adjusted circular cylinder with a semispherical head in a model water tunnel to make the flow in the boundary layer visible. Until that time, the standing cross flow instabilities on swept wings were observed only directly on the wall in sublimation and petroleum

painting pictures. Making things visible in the boundary layer can yield other insights about the physical processes involved. The model water tunnel is particularly well-suited to stability experiments due to the low level of instability in the inflow. With the hydrogen bubble technique, a good method of making things visible is available. The design and results of this experiment are described in Section 4. Finally, Section 5 presents a summary of the results and prospects for further studies.

## 2. STABILITY AND TRANSITION OF THREE-DIMENSIONAL BOUNDARY LAYERS - KNOWLEDGE TO DATE /14

### 2.1 THEORETICAL BASIS

In three-dimensional boundary layers, the direction of velocity parallel to the wall changes with the distance from the wall. Such boundary layer profiles always develop where flow lines are bent in levels parallel to the wall and thus centrifugal force has an effect, for example, on rotating bodies, or on the flow around three-dimensional bodies. Normally, the boundary layer profile is dismantled by projecting it on one level tangential to the local streamline on the edge of the boundary layer and by projecting it on one level in a normal relationship to the former into the so-called main flow and cross flow profile (see Fig. 2.1).

Stuart (Gregory, Stuart, Walker, [14]) derived the linearized disturbance differential equations for such twisted velocity profiles with temporally excited disturbances as early as 1955. In the process, he took the curvature of surface and streamline parameters into account. The equations are quite general and they contain some of the previously derived special cases, such as the Orr-Sommerfeld equation for a flat boundary layer. With such generality, the equations could not be solved. Not until very recently did Malik and Poll's [23] results appear.

Attempts were made, however, to arrive at an equation similar to the Orr-Sommerfeld equation through simplification. Many authors (such as Reshotko [33], Mack [22], and Habiballah [15]) have already dealt with the theory and its results at length. For that reason, just a brief overview will be presented in the next section. Its thrust will center around a discussion of the simplifications, and it determines the goals of the present experiments.

In the present work, only the simplest instance of a three-dimensional boundary layer is dealt with: an incompressible flow around an infinitely long, swept, two-dimensional model. The magnitude of the flow and all the basic magnitudes of the boundary layer do not depend on the coordinates parallel to the leading edge ( $y$ ); a so-called quasi-two-dimensional boundary layer is the result. /15

Fig. 2.2 introduces two more suitable systems of coordinates: a system which is physically constant ( $x, y, z$ ) with the velocity

components of the main flow ( $U, V, W$ ), and ( $x_t, y_t, z$ ) which is oriented toward the line of flow, together with ( $U_t, V_t, W_t$ ), whose  $x_t$  axis runs tangentially to the local flow line of the external flow.  $\phi_0$  is the model's angle of sweep.  $x$  and  $x_t$  include the streamlines local sweep angle  $\phi(x)$ .

As is customary in the stability theory, disturbances  $q$  and  $p$ , which are supposed to be very small, are superimposed upon the main flow  $Q$  and  $P$ . The total resulting from main flow and disturbance flow is:

$$Q_g = Q + q \tag{1}$$

$$P_g = P + p .$$

Inserting this statement into the Navier-Stokes equation yields:

$$\begin{aligned} \frac{DQ_g}{Dt} &= \frac{\partial Q_g}{\partial t} + (Q_g, \nabla) Q_g = \\ &= \nabla P_g + \frac{1}{Re} (\nabla, \nabla) Q_g . \end{aligned} \tag{2a}$$

and the continuity equation

$$\nabla \cdot Q_g = 0 . \tag{2b}$$

In equations 2a and 2b, non-dimensional coordinates have already been introduced. Finally, the following simplifications are undertaken.

#### LINEARIZATION

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First the equations are linearized by ignoring all products of the variable quantities  $q$  and  $p$ , together with their derivations, since, according to the prediction, these are supposed to be small.

#### ASSUMING PARALLEL FLOW

In addition, the velocity component perpendicular to the wall of the main flow is assumed to be zero.

$$W = 0 .$$

The requirements for a completely formed boundary layer flow in a flat tunnel are met exactly; for other types of boundary layers, the requirement is not met entirely. This is so because the boundary layer grows with the length of the run.

## LOCAL ANALYSIS

Due to the requirements of a quasi-two-dimensional flow, not all main flow quantities depend upon coordinate  $y$ :

$$\partial/\partial y = 0.$$

Furthermore, the changes of velocity components  $U$  and  $V$  in direction  $x$  as opposed to the changes perpendicular to wall  $z$  are disregarded

$$\begin{aligned} \partial U/\partial x &<< \partial U/\partial z \\ \partial V/\partial x &<< \partial V/\partial z. \end{aligned}$$

In disregarding these things, one is limited to local analysis, since all information on the influence of the growth of the boundary layer is lost.

In addition, curvature of the surface and of the streamline is disregarded. This gives:

$$\begin{aligned} \frac{\partial u}{\partial t} + U \frac{\partial u}{\partial x} + V \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} &= - \frac{\partial p}{\partial x} + \frac{1}{Re} \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \right) \\ \frac{\partial v}{\partial t} + U \frac{\partial v}{\partial x} + V \frac{\partial v}{\partial y} + w \frac{\partial v}{\partial z} &= - \frac{\partial p}{\partial y} + \frac{1}{Re} \left( \frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} + \frac{\partial^2 v}{\partial z^2} \right) \\ \frac{\partial w}{\partial t} + U \frac{\partial w}{\partial x} + V \frac{\partial w}{\partial y} &= - \frac{\partial p}{\partial z} + \frac{1}{Re} \left( \frac{\partial^2 w}{\partial x^2} + \frac{\partial^2 w}{\partial y^2} + \frac{\partial^2 w}{\partial z^2} \right) \end{aligned} \quad (3)$$

## THE DISTURBANCE STATEMENT

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A small disturbance  $q, p$  of the boundary layer flow can be broken down with the aid of a Fourier analysis into a sum of harmonic waves. Thus, for the disturbance statement, a harmonic wave can be chosen and real disturbances simulated by superimposing partial vibrations.

By assuming parallel flows, it can be supposed that the coefficient of the system of equations depends only upon  $z$ . This makes it possible to split the disturbance statement into an amplitude which depends solely on  $z$  and a harmonic wave dependent on  $x$  and  $y$ .

$$\begin{pmatrix} p \\ u \\ v \\ w \end{pmatrix} = \begin{pmatrix} \hat{p} \\ \hat{u} \\ \hat{v} \\ \hat{w} \end{pmatrix} (z) \cdot e^{i(\alpha x + \beta y - \omega t)} \quad (4)$$

$\hat{u}(z), \hat{v}(z), \hat{w}(z), \hat{p}(z)$  are those amplitudes which have complex values;  $\alpha, \beta,$  and  $\omega$  are complex in general. Usually, however, the



computations are limited to either a temporal or spatial excitation of the disturbances.

In the case of temporal disturbances

$$\alpha = (2\pi/\lambda_x)L, \quad \beta = (2\pi/\lambda_y)L$$

are the non-dimensional components of the wave vector /18

$$\underline{k} = (\alpha, \beta),$$

which, together with the x axis, includes the angle

$$\psi' = \arctan \beta/\alpha.$$

is complex

$$\omega = \omega_r + \omega_i$$

with

$$\omega_r = 2\pi f \quad L/Q_0$$

as a non-dimensional frequency of the wave.  $\omega_i$  is an excitation or squelching factor:

$$\begin{pmatrix} u \\ v \\ w \end{pmatrix} = \begin{pmatrix} \hat{u} \\ \hat{v} \\ \hat{w} \end{pmatrix} e^{\omega_i t} e^{i(\alpha x + \beta y - \omega_r t)}.$$

Placing statement (4) in (3) and eliminating  $\hat{u}$ ,  $\hat{v}$ ,  $\hat{p}$  gives:

$$\begin{aligned} 1/i\text{Re} (\hat{w}'''' - 2(\alpha^2 + \beta^2)\hat{w}'' + (\alpha^2 + \beta^2)^2 \hat{w}) = \\ = (\alpha U + \beta V - \omega) [\hat{w}'' - (\alpha^2 + \beta^2)\hat{w}] - (\alpha U'' + \beta V'')\hat{w}. \end{aligned} \tag{5}$$

This equation is a generalization of the Orr-Sommerfeld equation for three-dimensional velocity profiles and any possible direction of propagation of the wave. In the case of  $V \equiv 0$  and  $\beta \equiv 0$ , it is transformed to the latter.

By means of a simple transformation, Squire (1933) was /19 able to prove for level boundary layer profiles ( $V \equiv 0$ ) in cases of temporally excited disturbances that every wave travelling at a slant corresponds to a wave in the streamline direction ( $\beta \equiv 0$ ) with a smaller Reynolds number. Thus, if the critical Reynolds number for a flat speed profile is to be calculated, it suffices to solve the Orr-Sommerfeld equation for  $\beta \equiv 0$ .

A similar transformation can be introduced for temporally excited waves ( $\alpha_i = \beta_i = 0$ ,  $\omega_i \neq 0$ ) in three-dimensional speed

profiles ( $V \neq 0$ ) (Stuart [14], Mack [22]). The wave vector  $\underline{k}$  is expressed by the amount and angle against the x axis.

$$\underline{k} = |k| (\cos \psi', \sin \psi').$$

It follows that

$$\alpha = |k| \cos \psi', \quad \beta = |k| \sin \psi'$$

$$\alpha^2 + \beta^2 = |k|^2.$$

Substituting the values into (5) gives:

$$1/i \operatorname{Re}(\hat{\omega}^n - 2k^2 \hat{\omega}'' + k^4 \hat{\omega}) = [|k| (U \cos \psi' + V \sin \psi') - \omega] \cdot \quad (6)$$

$$\cdot (\hat{\omega}'' - |k|^2 \hat{\omega}) - |k| (U \cos \psi' + V \sin \psi')'' \hat{\omega}.$$

Now this equation corresponds exactly to the Orr-Sommerfeld equation for a velocity profile  $U(z)$

$$U(z) = (U \cos \psi' + V \sin \psi')$$

which results from the projection of the three-dimensional profile  $Q(z) = (U(z), V(z), 0)$  onto the propagation direction of the wave.

Thus the mathematical stability problem of a three-dimensional boundary layer has been traced back to the solution of the Orr-Sommerfeld equation for projection profiles. However, 20 solutions to this equation must be found for all projection angles, and only the total of the resulting calculated flat waves for different directions allows a determination of the three-dimensional profile's stability.

Not until theoretical and experimental results have been compared can it be determined whether using equation (6) to consider projection profiles does in fact accurately describe the physical processes and whether the simplifications are therefore justified. Various authors have already discussed the effect of linearization, assumption of parallel flow, and local analysis in the course of dealing with the plane problem.

Small disturbances can be correctly calculated by linearization. Larger disturbances such as those occurring before the transition or their non-linear interaction cannot be accounted for.

By assuming parallel flow, not only is the velocity component perpendicular to the wall neglected, but the prerequisite for a simplified approach to disturbance is created. Gaster [11] and Saric and Nayfeh [35] discussed this problem and showed that the impact of this simplification is not very great as long as the disturbances are followed only over a few wavelengths. In particular, its impact is smaller for an accelerated flow, since the boundary layer does not grow as much there.

Neglecting the curve of the surface and streamlines is quite a bit more problematic, because they can play a large role in cases of practical interest, especially when cross flow instabilities are induced. Calculations for the swept cylinder by Poll and Malik [23] show that significantly different excitation results are obtained when the curve effects for several disturbance modes are considered. It is therefore extremely important, when comparing calculations which are based on the generalized Orr-Sommerfeld equation (6) and on an experiment, to approximate the condition of negligible surface and streamline curvature.

The transformation which changes equation (5) into the /21 standard Orr-Sommerfeld equation (6), thereby allowing the observation of projection profiles, is only possible for temporally excited waves. However, in a stationary boundary layer flow, temporal origin is not realistic. The disturbances are actually spatially caused, making the components of the wave vector  $\alpha$  and  $\beta$  complex while the frequency is real. For the wave, we find

$$\begin{pmatrix} u \\ v \\ w \end{pmatrix} = \begin{pmatrix} \hat{u} \\ \hat{v} \\ \hat{w} \end{pmatrix} e^{i(\alpha_r x + \beta_r y - \omega t)} e^{\alpha_i x + \beta_i y}$$

In this equation, the frequency is expressed by

$$\omega = 2\pi f L/Q_0 .$$

The real parts of  $\alpha$  and  $\beta$  correspond to the wave vector

$$\underline{k} = (\alpha_r, \beta_r)$$

and the excitation vector

$$\underline{k}_i = (\alpha_i, \beta_i)$$

can also be introduced, which need not have the same direction as  $\underline{k}$ . The direction represents an additional free parameter.

However, Mack [23] was able to show that the transformation of temporally excited solutions to spatially excited ones introduced by Gaster for two-dimensional boundary layers is also valid for three-dimensional boundary layers with low excitation rates. Therefore, temporally excited solutions also can correctly describe the stability characteristics.

## 2.2 THEORETICAL AND EXPERIMENTAL FINDINGS TO DATE

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Although equation (6) contains several simplifications, it has been possible, with the idea of considering the stability of projection profiles based on it, to explain several phenomena of transition in three-dimensional boundary layers. (Stuart [14])

- As already mentioned in the introduction, the transition for swept airfoils already occurs at much smaller Reynolds

numbers and can even begin even at the area of the pressure drop. Fig. 2.3 shows projection profiles of a typical three-dimensional boundary layer in accelerated flow dependent on the angle  $\psi$  from the tangent to the outer streamline. It is important that profiles with turning-points occur in a certain range of angles. It is known of such profiles that they become unstable even at very small critical Reynolds numbers. In addition, the excitation of instabilities is significantly more powerful there. This offers an explanation for the early transition of swept airfoils.

- In all transition experiments in three-dimensional boundary layers, the occurrence of stationary disturbances has been observed in the pressure drop area. They were found to be band structures with a direction corresponding roughly to the local frictionless streamline. In the family of profiles in Fig. 2.3 there exist profiles with a change of sign and a turning-point after a certain angle. Outstanding among these profiles is one with projection angle  $\psi_j$ , where the turning-point coincides with the zero point (often called the J-profile in the literature). It is possible, for velocity profiles in this angle range around  $\psi_j$ , to calculate excited disturbances with decreasing phase velocity

$$c_{\psi} = 0.$$

These disturbances have the form

$$\begin{pmatrix} u \\ v \\ w \end{pmatrix} = \text{Re} \left\{ \begin{pmatrix} \hat{u} \\ \hat{v} \\ \hat{w} \end{pmatrix} e^{i\omega_i t} e^{ik_{\psi} x_{\psi}} \right\}.$$

They cause stationary vortices spinning in a contrary direction, whose axes lie perpendicular to the projection plane of the velocity profile and are therefore approximately in the direction of the main flow, cf. Fig. 2.4 (cf. Arnal [2]). If this disturbance flow is overlaid on the main flow, the result for the stationary observer is a streamline configuration with half the number of vortices spinning in the same direction. The observed striated structures can be explained by these stationary vortex patterns. /23

More exact measurements in the unstable area of a quasi-two-dimensional boundary layer, which make possible a quantitative comparison of theory and experiment, were obtained by Poll [28] and [30], Arnal et al. [3], and Saric [37].

Poll conducted extensive studies of disturbances in the stagnation area and of the stability of the three-dimensional boundary layer using a swept circular cylinder whose trailing edge was constructed with a wedge attached tangentially to the cylinder. This flow is characterized by strong wall and streamline curvature and by great acceleration, see Fig. 2.5.

Poll used the petroleum painting method to determine the first appearance of cross flow instability and to measure its wavelength  $\lambda$  and its direction relative to the x axis. In addition, he found strongly negative excited travelling waves of about 1,000 Hz. With Malik, he later carried out stability calculations (Malik and Poll [23]) which took curvature terms into consideration. The findings showed a satisfactory match between wavelength and direction of the stationary modes. However, the truly significant aspect of their calculations is that not stationary but travelling waves undergo the strongest integral continuous excitation. In particular, a wave of approximately 1,000 Hz was also found for the above mentioned case. It is astounding that the stationary waves nonetheless show up so clearly in petroleum painting /24 images. The role of stationary waves in the area of turbulence remains unclear.

In addition to transition measurements, Arnal et al. conducted investigations in the boundary layer on the pressure surface of a swept ( $\phi_0 = 40^\circ$ ), set ( $\alpha = -6^\circ$ ) ONERA-D wing. Fig. 2.6 shows the velocity progression on the edge of the boundary layer. All measurements were made for  $y/c \geq 0.2$ , i.e. in a range where the profile is only slightly curved, no great acceleration exists, and, therefore, no great streamline curvature is present.

Arnal et al. utilized the sublimation method to determine the transition and to make the traces of the cross flow vortex visible on the wall. Measurements with a hot wire at a constant distance from the wall showed that the average spanwise velocity is greatly modulated (up to 15% of the external velocity) by the cross flow vortices. The measured wavelength corresponds to that measured in sublimation images; it increases with growing distance  $x/c$  from the leading edge. A widening or disappearance of single "bands" in the sublimation image corresponds to the increase of the wavelength.

In detailed measurements with reduced velocity of flow from initial direction, Arnal shows the modulation of the average velocity in an entire field with a height of  $\delta$  and a width of a wavelength  $\lambda$  (field  $(\delta, \lambda)$ ) perpendicular to the local streamline. Arnal compares the measurements to solutions of the Orr-Sommerfeld equation (6) for the local velocity profile assuming temporally negatively excited, stationary disturbances. In fact, he finds that modes of the measured wavelength are the most strongly negatively excited for all STATIONARY disturbances. Also the form of the calculated velocity modulation for this disturbance is quite a good representation of those measured.

However, he himself critically notes that the disturbances are already so great that the linear stability theory is no longer valid and that the choice of the locally most negatively excited wave is somewhat arbitrary, since it is possible that other disturbances with that travelling length could have undergone a stronger integral continuous excitation. It is therefore /25 planned and necessary to calculate the integral continuous excitation of the stationary modes.

Measurements of the nonstationary velocity in field  $(\delta, \lambda)$  show that frequencies below 200 Hz are continuously excited. Stability measurements show that, in addition to the stationary waves, travelling waves with frequencies of this order are continuously excited as well.

The continuous disturbances show very great amplitudes. They can effectively surpass a level of 15% of the external velocity. Yet the effective levels in field  $(\delta, \lambda)$  are also modulated by double the wavelength of the stationary modes. Thus there is a strong interaction between both disturbances. The travelling disturbances, whose amplitude approximates the amplitude of the stationary ones, are superimposed on the stationary mode, while the travelling wave's amplitude is closely dependent on that of the stationary one.

Saric studies a three-dimensional boundary layer on a swept plate in a closed tunnel. A pressure gradient roughly corresponding to that of an airfoil is imposed by a camber of the tunnel wall lying opposite the plate (Fig. 2.7).

In the first part of the plate, great acceleration exists, and a strong cross flow accompanied by cross flow instabilities are anticipated. With increasing run length, the acceleration decreases and Tollmien-Schlichting waves of the main flow profile may be continuously excited. Also using the sublimation method, however, Saric observed stationary disturbances whose wavelength was independent of the run length and velocity (10 and 14 m/s). Hot wire measurements at various positions  $x/c$  and at varying distances from the wall showed a span velocity modulation of half the wavelength. Reed [32] interpreted this discrepancy as follows. First, in accordance with the linear theory, stationary modes of the observed wavelength are continuously excited, which then enter into interaction with likewise stationary modes of half the wavelength, with the latter undergoing strong continuous excitation.

In summary, it can be stated that within certain bounds, it is possible to correctly calculate the stationary modes observed in the experiments and their wavelength by using the linear stability theory. The theory says, however, that stationary waves do not always undergo the greatest local or integral continuous excitation, but that travelling waves are also continuously excited. The latter are also observed in the experiments, but the observed and the calculated frequencies still have not been systematically compared. In particular, the question arises of whether the stationary modes play a more important role in the experiment than the travelling ones. It also has not been experimentally tested whether and how the two disturbance modes interact.

## 2.3 KNOWLEDGE OF LAMINAR-TURBULENT TRANSITION

The linear theory of stability cannot describe the transition to turbulence, due to its requirements. From numerous experiments (Klebanoff et al. [19]; Kachanov et al. [18]; Saric et al. [34]; Nishioka [24]; Kovaszny et al. [20]), however, the processes at work in a flat boundary layer up to transition are better understood. Herbert [16] was able to interpret these processes as an instability in the disturbed main flow against three-dimensional disturbances (secondary instability) through the use of linear disturbance differential equations. This theory can describe a few other phases of increasing instability in the case of two-dimensional boundary layers for experiments under strictly controlled conditions.

For determining the site of transition in wind tunnel experiments, the  $e^n$  method was developed. It relies on the results of the linear theory of stability on the one hand, yet on the other, while disregarding the complicated processes in the transition area, includes the surpassing of a critical threshold of excitation as an experimental criterion for transition.

There are still no more precise studies dealing with the processes which take place in three-dimensional boundary layers from becoming unstable to transition. In the first instance, [27] one can associate the observations with three different phenomena:

### A DISTURBANCES IN THE STAGNATION AREA

It is possible that disturbances along the leading edge spread and lead to turbulence in the stagnation area (Poll [28]). If relaminarization does not occur in the area immediately behind the stagnation line, an area of strong acceleration, this causes turbulence in the entire boundary layer.

A characteristic Reynolds number for this flow is

$$Re = V_e \eta / \nu$$

$V_e$ : velocity parallel to the leading edge, at the edge of the boundary layer

$$\eta = \text{the measure of length} \quad \eta = \sqrt{\frac{\nu}{\left. \frac{dU_e}{dx} \right|_{x=0}}}$$

with the velocity gradient  $dU_e/dx$  perpendicular to the leading edge given  $x = 0$ .

This number was indicated by Pfenninger [27], Cumpsty and Head [10], and Poll [28].

For  $R \leq 250$

the boundary layer remains laminar, even with the introduction of artificial disturbances (such as the boundary layer of a lateral wall or something similar) (Poll [28]).

## B TOLLMIE-SCHLICHTING WAVES

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In the case of delayed flow, the main flow profile can become unstable against Tollmien-Schlichting waves before another projection profile has reached its critical Reynolds number (Bieler [5]). In this case, according to Arnal, the flow can be viewed as two-dimensional. A wonderful method of separating this instability from the cross flow instability is provided by Coustols [9]; see also Arnal et al. [2].

## C CHARACTERISTIC INSTABILITY OF THE THREE-DIMENSIONAL BOUNDARY LAYER

The characteristic instability of the three-dimensional boundary layer appears not when the main flow profile, but rather projection profiles in other directions first become unstable. As was already mentioned, both standing cross flow vortices as well as continuous waves can be excited. Exactly which physical mechanisms lead to transition in these cases is still unknown to a large extent.

It is conceivable that the stationary cross flow vortices play a decisive role. Studies of transition on concave walls have shown that, between the Taylor-Görtler vortices, unstable velocity profiles occur which lead to a secondary instability (Bippes [6]). Similarly, the cross flow vortices could deform the velocity profile and thus lead to turbulence. On the other hand, one knows from calculations of stability that, together with stationary waves, travelling waves are excited as well. In point of fact, it is not the standing ones that exhibit the lowest critical Reynolds number. Computations by Malik and Poll [23] show that, for the infinitely long swept cylinder, travelling waves experience the greatest total excitation if one integrates over the run length. It is thus possible that travelling waves play the decisive role.

Just as was the case with a flat flow, attempts have been made to calculate the site of transition using an  $e^n$  method. However, such calculations are markedly more difficult than in the case of two-dimensional ones, because in addition to frequency and /29 wavelength of the disturbance, one also has the direction of propagation as a free parameter. In addition, it is not certain whether the generalized Orr-Sommerfeld equation provides the proper excitations. Calculations by Reed [32] show that the excitation of travelling waves in the presence of cross flow vortices can increase greatly. The effects of curvature, as calculations by Poll and Malik showed, can also have a great effect on excitation.

Coustols [9] developed an empirical criterion to determine transition. He summarized a few of the more recent transition experiments (among them, Poll [28], Boltz, Kenyon & Allen [7], and



the DERAT's experiments) and he correlated the cross flow Reynolds number  $\chi$  at the site of transition with the shape factor  $H_{12}$  of the main flow profile at the same site:

$$\chi = 300/\pi \arctan [0.106/(H_{12}-2.3)^{2.052}] .$$

Since only four different experiments were available to him, further data on the examination of the suggested criterion for transition are needed.

## 2.4 GOAL OF THE PRESENT WORK

It is the goal of the present work to conduct experimental studies in three-dimensional boundary layers which will contribute to a better understanding of the instabilities and the subsequent laminar-turbulent transition. In addition to the stationary cross flow instabilities observed in prior experiments, investigations are to be carried out to determine whether travelling waves are excited and how both of these disturbances interact with one another.

Another goal is to examine the theoretical results of the generalized Orr-Sommerfeld equation given the experimental findings. In order to make a direct comparison of theory and experiment possible, it is necessary to come as close as possible to meeting the requirements set forth in Section 2.1. The curvature of the wall in particular can have a decisive influence. For this reason a model consisting of a swept plate with an impressed pressure gradient was chosen, just as Hirschel and Dallman suggested in 1974 for stability studies. The pressure gradient is applied by means of a pressure-inducing displacement body. /30

Further advantages of this model are:

- The lack of an express stagnation area so that no disturbances coming from that area influence the boundary layer,
- Mechanical simplifications,
- The possibility of variation of pressure by means of changing the displacement body or its position with regard to the position of the plate.

Saric used a similar configuration for his studies. Whereas he selected his pressure progression in such a way that at first cross flow instabilities and then Tollmien-Schlichting waves of the main flow profile are caused in order to study their interchangeability, in this instance a negative pressure gradient was to be produced across the whole plate just to preserve cross flow instabilities.

The first partial assignment of this work is the development of such a model for the 1-meter wind tunnel of the DFVLR in

Göttingen. It is shown in Section 3.2. The dependence of the site of transition upon the Reynolds number as well as the change in the wavelength of stationary modes and the frequency of travelling waves is studied in the described model. After a description of the construction, methods of measurement, and preliminary tests, the results are described in Section 3.6.

In experiments to date on swept airfoils, only the traces of the stationary disturbances were made visible on the surface of the model (sublimation method, petroleum painting method). A second aspect of this work involves studying the origin of disturbances by rendering flows visible in the boundary layer. In this way it is possible to observe stationary and travelling waves and to gain some insight into their interaction. A circular /31 cylinder with a semispherical head was available for use as a model. The hydrogen bubble method in the model water tunnel served to make the phenomena visible. The first visible appearance of disturbances and the transition to turbulence in dependence from the Reynolds number and sweep angle were investigated. The experimental design and methods of measurement are described in Sections 4.1 and 4.2; Section 4.3 presents the results.

### 3. EXPERIMENTS ON THE SWEEPED PLATE

#### 3.1 EXPERIMENTAL FACILITIES

##### 3.1.1 THE 1-METER WIND TUNNEL

A 1-meter wind tunnel with a 1.3 m long open working section and a closed gust return (Fig. 3.1) was used for experiments on the basic model. While measuring, a 1.0-m x 0.7-m rectangular nozzle with a contraction ratio of 1:3.5 was used. The velocity can be regulated continuously from 0.7 to 45 m/s. Approximately 5 m before the end of the nozzle in the calming section there is a honeycomb and 3 screens with a 4.6 to 5 mm and 2.4- to 2.8-mm mesh of 1- and 0.5-mm thick wire. For all attained velocities, the amount of turbulence in the open working section is less than 0.1%. The development of a model consisting of a plate and a pressure-imposing displacement body is described in Section 3.2.

##### 3.1.2 THE CIRCULATING WATER TUNNEL

In order to construct a suitable displacement body, it was necessary to make the flow around the model visible. These experiments were conducted in the small circulating water tunnel, for which the hydrogen bubble technique (cf. Section 4) provided a good visualization method. Fig. 3.2 shows a sketch of the /32 tunnel. The measuring section, which was passed through horizontally, has a cross-section measuring 0.25 m x 0.33 m and a length of 1.25 m, and it is open at the top. The mechanical return is trained toward a round diffuser. At a contraction ratio of 1:3.4, the jet creates the transition from the round mechanical

return to the rectangular cross-section in the measuring section. This velocity can be controlled without any steps to a maximum of 5 m/s.

### 3.2 CONSTRUCTION OF THE MODEL

The goal is to create a three-dimensional boundary layer which becomes unstable and finally turbulent on a flat swept plate by imposing a pressure gradient. This boundary layer comes very close to the requirements of theory, as mentioned above in Section 2.4. The development of such a model encompasses two tasks:

- Choice of a "suitable" pressure gradient,
- Development of a displacement body which creates the desired pressure progression.

The intention is to create a pressure progression resembling that on a swept airfoil. The area of great acceleration on the profile is of particular importance here. That is where the boundary layer is very stable in two-dimensional cases, whereas with swept airfoils, turbulence can occur even there.

Several preliminary tests conducted in the 1-meter wind tunnel on a NACA-0010 airfoil provide an impressive example of this. A  $15^\circ$  angle of incidence  $\alpha$  was chosen to obtain a long stretched-out area with a negative pressure gradient. The transition line was made visible by the sublimation method. Fig. 3.3 shows such a sublimation image for a  $48^\circ$  sweep angle  $\phi_0$  and a Reynolds number of  $Re = 1.5 \cdot 10^6$  with the associated pressure progression. Transition, visible at the separation of the white area from the dark, occurs already at  $x/c = 0.28$ . In the laminar area in front of the transition a marked striated structure formation is 33 noticeable. In this area, the projection profile in the direction of the main flow is still stable. The striated structure formation can be explained by a continuously excited, stationary instability of a projection profile in a direction close to the normal one of the streamline at the edge of the boundary layer. It can therefore be supposed that the transition is influenced by cross flow instability. Since the main subject of this paper is the clarification of this question, a displacement body must be designed which imposes a pressure progression on the plate like it does on a  $15^\circ$  NACA-0010 set airfoil.

Since no inverse methods of calculation were available which could be used to figure a displacement body from a pressure progression, this body was developed and optimized experimentally. A 1:3 scaled-down first model was built for the small circulating water tunnel. In this tunnel, it is very easy to make the flow around the model visible by using the hydrogen bubble technique (cf. Section 4.2). By means of pulsed current on the bubble wire, so-called time lines are obtained at regular time intervals. Their spatial distances provide a measure of the velocity distribution in the direction of flow. The acceleration and the pressure gradient can be derived from them. The displacement body

was varied until it created the desired velocity progression on the plate. At the same time, while the model was being developed, care was taken that no nonstationary separation areas were created. As the observation of flow has shown, they can react on the flow and thereby on the boundary layer. Fig. 3.4 shows a cross-section of the final model. The slat prevents the formation of a large separation area close to the nose of the displacement body. The side of the displacement body facing the plate is very curved at first with a gradual transition to a flat plane. This form results in a weaker pressure gradient than the NACA-0010 wing has. A greater drop in pressure requires a considerably greater curvature of the displacement body, because the pressure gradient affecting the displacement body normally decreases toward its surface, i.e. toward the plate as well. However, the flow no longer follows such a curve; a separation bubble forms on the 34 side of the displacement body facing the plate, which should be avoided for the above named reasons. As will be shown later, however, the pressure gradient is sufficient to bring the boundary layer on the plate to transition. The final design (Fig. 3.4) was built for the 1-meter wind tunnel in a 3:1 enlargement.

Another important task was the simulation of a quasi-two-dimensional flow, i.e. a flow which is independent of the span coordinate  $y$ . Initial experiments with the plate and displacement body showed that deflectors are necessary for reaching this goal. For an exact directing of the flow by the walls, they would have to be formed under quasi-two-dimensional conditions following the three-dimensional warped plane of flow between the plate and displacement body. This plane of flow is only obtainable from a calculation of the entire velocity field. It is a simpler solution to form the lateral plates with only two dimensions following the streamline at the edge of the plate boundary layer. This streamline can be easily calculated from the measured pressure progression under the assumption that  $V = V_\infty = \text{const}$  (condition for an infinitely long swept wing):

$$y = x_0 + V_e / U_\infty \cdot \int (\sqrt{1 - c_p(x)})^{-1} dx .$$

With built-on lateral plates, the pressure progression demonstrated a slight change from the measurement without deflectors. The streamlines calculated for both pressure distributions, however, differ only very little (Fig. 3.5); their differences are, in particular, only near the leading edge of the plate. But that is precisely where the three-dimensional warp of the flow plane is especially great, since the streamline near the plate is greatly distorted by the strong pressure gradient in the stagnation zone, whereas just a little above the plate the effect of the stagnation area diminishes. Therefore, it is not a good idea to simulate the strong curvature of the streamline near the plate by means of the deflectors. As will be shown below in Section 3.5.4, measurements of velocity at the edge of the boundary layer showed that these deflectors provide a good simulation of a quasi-two-dimensional flow, and this justifies the simplified form.

## 3.3.1 GENERAL DESIGN

Fig. 3.6 shows the final design of the experiment in the 1-meter wind tunnel. The leading edge of the plate is at a  $45^\circ$  sweep angle to the displacement body fastened above it. The windward sides are attached outside the free jet, whereas the downwind sides end at the collecting cone due to the short length of the speed course. The two deflectors S are formed below the zero friction streamline at the edge of the plate boundary layer. The plate is outfitted with a series of pressure piercings P and a sweep mechanism V. The individual parts of the model are described in more detail below.

## 3.3.2 THE PLATE

The plate, made of double-glued plywood, is 2.30 m long, 0.5 m deep, and 30 mm thick. The surface was carefully primed, sprayed black, and wet sanded to produce a very smooth surface. The leading edge of the plate has the nose profile of a Clark-y airfoil. This profile was chosen to keep the suction point small and to insure that the stagnation line lies on the side of the plate being tested.

The plate has 22 pressure piercings placed on a cut at a  $40^\circ$  angle to the leading edge. A small steel pipe with an internal diameter of 0.7 mm and an external diameter of 1 mm is inserted into the plate for each pressure piercing before the final finishing of the surface. Any roughness brought about in the process is also primed and sanded.

A sweep mechanism is built into the plate (Fig. 3.7) for measurements using hot wire and hot film. It consists of two eccentric disks that can turn against each other, supported in bearings, in an outer ring that is tightly fastened to the 36 plate. The inner disk can take up two different cylinders, which are in turn supported by bearings allowing them to turn. The cylinders serve as a mounting for a hot wire or hot film. By turning the disks, any point within two concentric circles whose radius ranges from 30 mm to 66 mm (smallest possible and greatest possible distance from anemometer and center of the larger disk) can be reached. An additional disk with a sweep mechanism can be attached inside the plate. It moves the anemometer mounting on a straight line, whose angle to the leading edge can be set in  $5^\circ$  steps by the swing angle of the disk. This makes it possible to move the anemometer along parallel paths to the leading edge at distances of 27 cm and 33 cm, and to move it on paths perpendicularly or at various angles to the leading edge. A sweep mechanism such as this was chosen in order to be able to measure the stationary disturbances with a hot film. Only very small variation of the average wall shearing stress is to be expected, and since it is very difficult to calibrate hot films, measuring the stationary cross flow instabilities with several fixed hot films would not be possible.

In constructing and installing the sweep mechanism, extreme care was taken to avoid surface flaws. The outer fixed ring was placed in the plywood plate and finished so well with a fine filler that no measurable flaws were caused. The surface flaws between the rotating disks supported by bearings were smaller than 0.02 mm for all positions. Subsequent tests making the flow visible showed that these flaws had no influence on the site of transition.

### 3.3.3 THE DISPLACEMENT BODY

The development of the displacement body was described in Section 3.1 and a cross-section was shown by means of the model (Fig. 3.3). Precise data concerning the profile are presented in the appendix. During the experiments, the boundary layer was rendered turbulent by the attachment of artificial roughness to the side of the displacement body turned toward the plate in order to avoid separation at the curvature.

### 3.3.4 THE LATERAL PLATES

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The lateral plates were shaped following the calculated streamline at the edge of the plate boundary layer. They are made of 2-mm sheet aluminum, attached to streamline-shaped struts and fixed between the displacement body and the plate. The deflector, which is situated windward, was extended in front of the model, since it was necessary to guide the flow in front of the model as well. Both lateral plates, the extended windward one, as well as the one downwind, were struck tangentially by the flow.

## 3.4 METHODS OF MEASUREMENT

### 3.4.1 MEASUREMENTS OF PRESSURE

The static pressures were measured by a pressure pickup whose initial signal was averaged using a digital voltmeter for over 20 s. The data were stored on punch cards and evaluated on the IBM computer. The pre-chamber pressure of the 1-meter wind tunnel was measured using a Betz manometer to a tolerance of 0.5%.

### 3.4.2 MEASURING VELOCITY WITH A FIVE-HOLE ANEMOMETER

In order to measure the amount and direction of velocity, a five-hole anemometer with a very small head (1.5 mm in diameter) was used. Pressures were measured by means of pressure pickups, and they were fed into a data acquisition subsystem (see Fig. 3.8). The anemometer and the acquisition system were described in Landhäuser [21]. The inaccuracy of the velocity measurements is 5% at most; that in determination of the angle, 1.2°.

## SUBLIMATION METHOD

By means of the sublimation method, various shearing stresses of the walls can be made visible on the surface of the model with the aid of sublimating crystals. In the present experiments, naphthalene was dissolved in acetone and sprayed in thin layers on the plate. The acetone evaporates very quickly and leaves behind a thin layer of crystals. Between sprayings, thicker crystals are carefully removed with a soft brush. After repeating this process three times, a dense white layer of crystals covers the white lacquered model. If one exposes this plate to the flow, the naphthalene sublimates completely on those places first in which a higher shearing stress of the wall, and thus, a higher temperature prevails: near the leading edge, where, as a result of the thin boundary layer, high shearing stresses occur and in that area in which the shearing stress increases as a result of the turbulence. Depending upon the surrounding temperature, after 10-30 minutes of wind a picture emerges with a line of demarcation between the naphthalene which was left behind in the laminar area and the sublimated naphthalene in the area of turbulence. Thus, a simple method exists for determining the course of the transition line. The cross flow instabilities also show up in the sublimation picture.

## PETROLEUM PAINTING

To make the wall streamlines and the traces of the stationary cross flow vortices visible, the petroleum painting method was used. A suspension of petroleum and very fine colored pigments is sprayed on the plate, which is then exposed to the flow. After the petroleum has evaporated, the wall streamlines can be discerned in the residue of colored pigments.

## 3.4.4 HOT WIRE AND HOT FILM MEASUREMENTS

Three anemometers were used for hot wire and hot film measurements, see Fig. 3.9. With a surface hot film anemometer (3), changes in the wall shearing stress were measured. The anemometer consists of a small cylindrical quartz body, on the /39 face of which the hot film, a 0.2 mm wide and 0.75 mm long nickel layer, is steamed on. The film is covered by a 0.5 micron thick protective layer made of quartz.

The hot wire angle anemometer (1) is used to measure the nonstationary velocity in the boundary layer. The hot wire, with a diameter of 5 microns, is 1 mm long.

Both anemometers were swept parallel to the leading edge with the help of the sweep mechanism (Fig. 3.7). For each of the anemometers, a mounting cylinder was built and installed in the smaller disk of the sweep mechanism, ending flush with it.

An additional hot wire anemometer (2) was also used for measurement in the boundary layer. The hot wire was 1 mm long and 5 microns in diameter. The anemometer mounting can be attached to the plate at any desired point. The anemometer wire is 0.25 mm from the surface. To allow measuring standing waves with this hot wire anemometer, the mounting of the hot wire was fastened to the large disk of the sweep mechanism and directed along the local streamline. By turning the disk, the hot wire moves in an arc with a radius of  $r = 156$  mm. Measurements were made up to angles of  $\pm 7.5^\circ$  so that the arc only deviates from a straight line perpendicular to the local streamline by  $\pm 0.7$  mm (Fig. 3.10). The movement of the hot wire can thus be described in the streamline oriented coordinate system as movement along the  $y_t$  axis with constant  $x_t$ . In the body system,  $x$  changes by  $\pm 2$  cm. Due to the rotation of the hot wire and the variable distance from the leading edge, errors in the measurement of the average velocity occur. However, since only the wavelength was determined, these deviations are insignificant.

All three anemometers were run by a Disa constant temperature bridge. The superheating relationships were 1.7 for hot film and hot wire (2), and 1.5 for hot wire (1). Since the variation of the averaged output signals is very small when there is sweeping along the  $y$  coordinate, amplification is necessary. To accomplish this, the output signal of the bridge E and a fixed discretionary voltage K were put on a differential amplifier and amplified 20 times. The amplified signal  $E_s$  was directly observable on the oscillograph. With an integrating digital voltmeter, the mean values were registered (averaging interval 20 s). A quantitative analysis of the variations in velocity is possible using an FFT-analyzer, which carries out a frequency analysis of the time signal. Temporal disturbances containing large numbers of low frequencies were observed. For this reason, at no point while making or using measurements was a high-pass filtering undertaken, which could have distorted the signal. Fig. 3.11 shows a block diagram of the entire apparatus. /40

### 3.5 PRELIMINARY MEASUREMENTS AND CALCULATIONS

#### 3.5.1 METHODS OF CALCULATION

Along with the experiments, boundary layer and stability investigations were conducted at Bieler's theoretical institute. The velocity at the edge of the boundary layer was calculated from the measured pressure progression. Under the assumption of an infinitely long swept model, it holds that:

$$\begin{aligned}
 V_e &= V_\infty = Q_\infty \sin \phi_0 \\
 U_e &= \sqrt{1-c_p} \cdot U_\infty = \\
 &= \sqrt{1-c_p} \cdot Q \cos \phi_0.
 \end{aligned}$$

As will be shown in Section 3.5.4, these calculated velocities describe the experiment within defined boundaries quite well. To



calculate the boundary layer, a finite difference method was used. In addition to the three-dimensional velocity profiles, the /41 calculations yield several integral values. Fig. 3.12 shows the 99.9% boundary layer thickness, the shape factor of the main flow profile, and the cross flow Reynolds number. The numerical analysis of the stability problem described in Section 2 was carried out using an estimated value procedure and a spectral technique. The input was the calculated boundary layer profiles.

### 3.5.2 CALIBRATION OF THE TUNNEL

Since the model has a very large displacement, it was tested whether the calibration curve maintains validity even with the model installed. A comparison in Fig. 3.13 shows that no great deviations arise. The velocity can be determined with 2% accuracy from the pre-chamber pressure.

### 3.5.3 MEASUREMENT OF THE PRESSURE PROGRESSION

The pressure progression impressed on the plate by the displacement body was measured for a 45° sweep angle with lateral plates and is shown in Fig. 3.14A. Pressure measurements for various velocities yielded no major deviations of the pressure correction value. Fig. 3.14B shows the pressure progression achieved by the displacement body in comparison to that of the NACA-0010 airfoil at a 15° angle of incidence. On the profile, a stronger pressure gradient is found than on the plate. As mentioned above, it was not possible to simulate this strong gradient by means of a displacement body.

### 3.5.4 MEASUREMENTS RELATING TO FLOW QUALITY

Using various methods, it was tested to what extent the required quasi-two-dimensional flow was actually attained.

Making the flow visible by means of petroleum painting and naphthalene images provided a first overview. One photo each /42 at a flow velocity of  $Q_{\infty} = 30$  m/s is shown in Fig. 3.15 and 3.16. The petroleum painting image provides information concerning the direction of the wall streamlines. In a central area of the plate, the striated structures (cross flow instabilities) run very nicely parallel and they blur along a parallel line toward the leading edge (transition). A few irregularities occur near the deflectors. The circulation around the leading edge is of particular importance. Fig. 3.16 shows a clear stagnation line running parallel to the leading edge on the plate's upper surface.

In the sublimation picture, the areas of laminar and turbulent flow can be determined clearly. Here, too, it can be discerned that in a central, ca. 50 cm broad area, a transition line develops that runs parallel to the leading edge. It also becomes clear that on the sweep mechanism and as a result of the pressure piercings, no disturbances occur which have any bearing on transition. A turbulent wedge develops right on the deflectors

which are marked in the photo. Next to these there are areas in which the flow remains laminar for a longer time.

To render this qualitative overview complete, the velocity vector on the edge of the boundary layer was measured using a five-hole anemometer to determine the quantitative deviations of the assumed quasi-two-dimensional flow. The measurements were carried out at a velocity of  $Q_\infty = 25 \text{ m/s}$ . A sketch of the experimental design is presented in Fig. 3.17. The anemometer was set against the leading edge at a  $45^\circ$  angle so that the angle of flow lies within the anemometer's calibration range. For anemometer head distances from the leading edge less than  $x = 35 \text{ cm}$ , the anemometer was extended by means of a tubular mount. Fig. 3.18 shows the measurements of the velocity along parallels to the leading edge at the following distances:

- $x = 20 \text{ cm}$
- $x = 28 \text{ cm}$
- $x = 40 \text{ cm}$  .

The coordinate origins of the three parallels are swept /43 against one another in the direction of the wing span in such a way that the points of crossing of a flow line with the parallels in the picture lie across each other in a perpendicular arrangement. At  $x = 20 \text{ cm}$  and  $x = 28 \text{ cm}$ , the velocity components show a slight change with the direction of wingspan. If the margins of the field of flow, in which deviations of 4% occur, are removed, the deviations for the area ( $y = 10\text{-}40 \text{ cm}$  and at  $x = 20 \text{ cm}$ ) are under 2% and thus within the anemometer's tolerance limits. For  $x = 40 \text{ cm}$ , particularly in the right portion of the surveyed area, greater deviations occur (maximally 4% for  $y = -12 \text{ cm}$ ).

The results can be compared with computations obtained from the measured distribution of pressure and the sweep angle  $\phi_0$  assuming an infinitely swept wing ( $V = \text{const}$ ). For  $V_e/Q_\infty$  and  $U_e/Q_\infty$ , it holds that:

$$V_e/Q_\infty \cong V_\infty/Q_\infty = \sin \phi_0$$

$$U_e/Q_\infty \cong \sqrt{1 - c_p} \cdot \cos \phi_0 .$$

It became apparent that the results of the measurements agreed with those of the calculation to a great degree if one takes as sweep angle not the geometrical  $45^\circ$  sweep angle, but rather an effective sweep angle of  $\phi_0 = 46.6^\circ$ , an angle which might arise from the great displacement of the free jet in the wind tunnel because of the model. Thus, for the velocities, the results are:

$$V_{\infty}/Q_{\infty} = 0.727$$

$$U_e/Q_{\infty}(x/c = 0.40) = 0.541$$

$$U_e/Q_{\infty}(x/c = 0.56) = 0.617$$

$$U_e/Q_{\infty}(x/c = 0.80) = 0.712 .$$

These values are drawn in as straight lines in Fig. 3.18. Fig. 3.19 shows the velocity  $U_{te}$  and the angle of the velocity vector  $Q_e$  to the axis of the tunnel in comparison with the quantities computed from the pressure progression. Except for areas of the near trailing edge, deviations are under 2%. The angle of flow at  $x < 40$  cm deviates from the calculated flow by less than  $1^\circ$ . /44

To summarize, it may be concluded:

Making the flow visible and quantitative measurements show that the flow in a "central area" agrees in velocity at 2% and in the direction of the streamlines from the pressure progression at 1%. The flow can best be described assuming an effective sweep angle of  $46.6^\circ$ . In this way it is shown that the calculated values of the main flow can be related as reference quantities in comparison with the theory within the range of deviations from Figs. 3.18 and 3.19.

### 3.5.5 STABILITY AGAINST DISTURBANCES IN THE STAGNATION AREA

In studying transition due to cross flow instability, it is important that disturbances do not occur in the area of the stagnation line and become excited ("leading edge contamination").

Poll's results show that for a Reynolds number  $R$  in the stagnation line boundary layer of

$$R \leq 250$$

strong disturbances are baffled and thus cannot lead to turbulence (see Section 2.3). For a maximal flow velocity of  $Q_{\infty} = 45$  m/s and with

$$\frac{\partial U_e/U_{\infty}}{\partial x/c} \cdot \frac{U_{\infty}}{c} = 30 \cdot \frac{U_{\infty}}{c}$$

from the measured pressure progression, a maximum Reynolds number of the contact line of

$$R = 192$$

results for the present experiment so that in the vicinity of the leading edge no disturbances are excited. Hot film measurements at a distance of 5 cm from the leading edge confirm that Poll's results can be used in this case as well. /45

## 3.6 RESULTS AND DISCUSSION

### 3.6.1 TRANSITION

In defining a transition site in a three-dimensional boundary layer, two problems must be considered. For one thing, just as with two-dimensional boundary layers, the transition comprises a certain length of run length  $x$ . For another, the transition line, which is shown in sublimation images, is sharply zig-zagged (Fig. 3.16). In this case, the transition line was indicated as a middle line between those zig-zags.

For comparison, for a few of the experiments, Preston tube measurements were also carried out along the depth of the plate. The Preston tube also addresses the changes in wall shearing stress. Fig. 3.20 shows the progression of the Preston pressure across the depth of the plate. With the aid of this curve it is possible to measure the beginning and end of transition. The comparison with the sublimation pictures shows that the latter indicate a central site  $x$  between the beginning and end of transition. This site  $x$  is defined as the transition site in the following.

Between the laminar and turbulent area of the petroleum painting there are likewise characteristic differences, and these can be used in the determination of transition.

- In similar fashion to the sublimation picture, the rate of evaporation depends upon the wall shearing stress. As the image develops, a clear demarcation line is recognizable between the area which is still wet (small wall shearing stress, laminar) and the area which is already dry (great wall shearing stress, turbulent).
- In the turbulent area the drawing of the picture is /46 markedly finer.
- Small disturbances can produce turbulent wedges in a laminar surrounding; in a turbulent area they leave only narrow bands behind them (Fig. 3.21). However, disturbances can sometimes cause mere "bands" in a laminar, very stable flow. Therefore the conclusion that the surroundings are laminar should be drawn only from turbulent wedges and not the other way around from missing wedges to turbulent bands.
- In the transition area, the wall shearing stress increases markedly, and accordingly, few particles of pigment remain there. In the dried petroleum painting picture this transition area is recognizable as a narrow dark band (see Fig. 3.22).

When they are looked at carefully, the pictures obtained from the petroleum painting process provide the same site of transition as the sublimation images. Since the petroleum painting method is

easier to manage and poses less of a health hazard, it was used in addition to the naphthalene method.

The results of the measurements for various Reynolds numbers are summarized in Fig. 3.23.

Hot film measurements with anemometer 2 provide additional information about the condition of the boundary layer. The anemometer was attached at the following distances from the leading edge:

$x/c = 0.36$   
 $x/c = 0.52$   
 $x/c = 0.62$   
 $x/c = 0.75$   
 $x/c = 0.85.$

At increasing velocity, observations were made when spots occur or when the initial signal is completely turbulent. The occurrence of the first spots is labeled S in the picture; a completely turbulent signal is labeled T.

In addition to the experimentally determined line of transition, the site of transition was determined according to the Coustols criterion (see Section 2.3) /47

$$x = f(H_{12})$$

and entered into the picture. The criterion's prediction and the experiment are in very close agreement. Thus it is proven that the criterion, which was developed for various experiments on airfoils, can predict the site of transition on the plate very well.

### 3.6.2 STANDING WAVES

In petroleum painting pictures and naphthalene pictures, the traces of stationary disturbances become visible. The cross flow instability produces a variation of the average velocity in amount and direction as wide as the wingspan, and thus a variation of the wall shearing stress. In petroleum painting pictures, the modulation of amount and direction of wall shearing stress works itself out. In the laminar area before transition, a strong formation of band structures is evident, as was shown in Fig. 3.15. Following the flow downwind from the leading edge, undisturbed laminar flow is observed at first. In a few places, individual "bands" occur that change to uniform striated structures after some distance and disappear again in the turbulent area. The striated structures run more or less in the same direction as the streamline at the edge of the boundary layer. If isolated "bands" are observed very far forward in the area of pronounced curvature of the streamline, they are also greatly curved. This method of rendering the flow visible amounts to a simple and rapid aid to studying cross flow instability. Wavelength and direction of the striated structures can be

measured in the picture. The site at which isolated bands could be seen was identified as site  $x_1/c$ , the site of the first excitation.

The flow on the plate was made visible at various Reynolds numbers. To determine the wavelength, averages were taken at several places on the plate across a few bands in each case. The wavelengths determined in this way do not depend upon their 48 distance from the leading edge as far as the accuracy of their measurement is concerned. A unification of individual "bands" or the disappearance of "bands," and thus a variation of wavelength, as Arnal [3] describes it, was not observed.

The results of the wavelength measurements are compiled in Fig. 3.24. For various experiments with one Reynolds number and also within one picture, wavelength changes of up to 17% were shown. The error lines shown in the illustration cover the range of these changes.

In naphthalene pictures, a striated formation in the laminar area was shown before transition too. Just as in the case of making transition visible, the wingspan-wide change of the wall shearing stress becomes clear in the sublimation picture due to varying degrees of sublimation of the crystals. The wavelengths measured in these pictures are also registered in Fig. 3.24. They agree with the results from the petroleum painting pictures.

Measurements by Saric have shown that it is possible for other wavelengths to occur in the boundary layer besides those observed on the wall. In addition, no experiments are known which directly measure the variations of wall shearing stress. For this reason, the wavelength measurements in the sublimation and painting pictures were supplemented by measurements of the wall shearing stress using a mobile surface hot film at  $x/c = 0.66$  and by measurement in the boundary layer at  $x/c = 0.40$  and  $x/c = 0.66$  with two mobile hot wire anemometers.

The sweep mechanism for the hot film and for both hot wire anemometers was described in Sections 3.3.2 and 3.4.4.

The variation of the average velocity is shown in Fig. 3.26 a-h.

Table 3.1 summarizes the results.

Measurement Number	Anemometer	Re 10 <sup>-5</sup>	x/c	y/δ	λ"	λ
a	2	6.67	0.40	0.11	-	-
b	2	8.08	0.40	0.12	-	8.0
c	2	9.69	0.40	0.13	-	6.3
d	2	10.10	0.40	0.13	-	6.8
e	3	5.65	0.66	-	18.7	12.8
f	3	6.61	0.66	-	16	10.7
g	1	6.61	0.66	0.36	16	10.7
h	1	7.44	0.66	0.39	16	10.7

TABLE 3.1

Measurements a-d were carried out in the streamline oriented coordinate system. The measurements are corrected for temperature, for the alteration of the average velocity due to the hot wire rotation, and for the change in distance x from the leading edge. The wavelengths from measurements b to d are entered in Fig. 3.24 as circles.

The measurements of wavelength (λ") in the series of measurements e-h were carried out in a body coordinate system. Measurements were not carried out perpendicular to the stationary waves. With the local sweep angle of the striated structures, known through the painted pictures, it is possible to convert to. The values are characterized by the squares in Fig. 3.24. The wavelengths measured by means of the anemometers are in agreement with those determined in the process of making the flow visible; contrary to Saric [37], no wavelengths in the ratio 1:2 are found in the boundary layer or on the surface of the model.

In Fig. 3.25, the measured wavelengths with the calculated boundary layer thickness δ at x = x<sub>i</sub> are normed. The site x<sub>i</sub>, that is the smallest distance from the leading edge at which band formation could be observed, was determined from the petroleum painting pictures. Within the context of accuracy of measurement, the ratio is constant:

$$\lambda/\delta_i = 4.1 \quad .$$

The angle  $\phi_{q1}(x)$  of the cross flow instability to the 50 x axis was measured with an accuracy of ± 1° for three different Reynolds numbers. The results are presented in Tab. 3.2. For all measured Reynolds numbers and distances of x,  $\phi_{q1}(x)$  is about 4° less than the local sweep angle of the streamline.

Re 10 <sup>-5</sup>	x/c	$\phi_{q1}(x)$	$\phi(x)$	$\Delta\phi$
6.6	0.36	50°	54.5°	4.5°
7.8	0.55	47°	49.8°	2.8°
9.62	0.47	47.5°	51.5°	4°
9.62	0.32	51°	55.6°	4.6°

TABLE 3.2

## COMPARISON WITH THEORY

Calculations of the boundary layers' stability were carried out by Bieler [5] at the theoretical institute. He computed the Orr-Sommerfeld equation using different Reynolds numbers and different sites  $x/c$  in the flow field for several projection profiles in turn. Stationary disturbances with  $\omega_r = 0$  are possible for several projection directions  $\psi$  lying close together from  $85^\circ$  to  $87^\circ$ . The wavelengths of these modes vary with the projection angle. Their excitation differs only very little from a wavelength band having a width of about 10% of the average, most excited wave. Thus, stationary modes whose wavelengths differ from each other by about 10% undergo practically the same excitation. This corresponds to the experimental observations.

For further comparison with the experiment, the wavelengths of the stationary modes for the combinations of Reynolds numbers and site  $x_i$  of the first observation were considered. In Fig. 3.24 the wavelengths of the disturbance with the greatest excitation are paired with the experimental values. The theory is very well able to give the course of change in wavelengths with the Reynolds number; however, the calculated wavelength lies below the experimental values by about 1 mm for all Reynolds numbers. This comes as no surprise inasmuch as the experimentally observed disturbances underwent the strongest integral excitation and 51 not the strongest local excitation. For a more accurate comparison, the local excitation of the stationary disturbances would have to be integrated over the run length  $x$ .

For all Reynolds numbers, the stationary disturbance with the greatest excitation occurs at a projection angle  $\psi$  of  $85^\circ$  to  $87^\circ$ . The wave fronts (band structures) have an angle of  $(90^\circ - \psi)$ , that is,  $2^\circ$  to  $4^\circ$  from the local streamline. Within the interpretation accuracy of a painting image, this amounts to experimental angle measurements of  $4^\circ$  on the average.

## In summary:

The theory is able to explain why the wavelengths of the standing disturbances in the experiment vary by about 17%. The course of the wavelength with the Reynolds number is also described quite well. However, predictions of the wavelengths are a little too small. The directions of the excited standing waves are well described within the limits of the accuracy of measurement.

## 3.6.3 TRAVELLING WAVES

In addition to the standing waves, travelling waves were also found in the boundary layer. To investigate these waves, the hot wire anemometer (2) was fixed at six different positions  $x/c$  in the flow field:  $x/c = 0.1$ ;  $0.36$ ;  $0.52$ ;  $0.62$ ;  $0.75$ ; and  $0.85$ . The signal was observed on the oscillograph for increasing incoming



flow velocity. With the exception of  $x/c = 0.1$ , strong periodic variations in velocity were found at all positions, even in the areas in which the stationary waves were observed. Fig. 3.27 shows some examples. For systematic study, spectra of the variations of velocity were calculated using an FFT-analyzer and shown on a screen.

Hot wire signals and spectra change with the velocity in the same characteristic way at all sites  $x/c$ . Fig. 3.28 shows a typical series of velocity signals and their spectra for  $x/c = 0.52$ . First the flow is undisturbed; the spectrum has only 52 low RMS-values for frequencies below 50 Hz and has a "round shape," i.e. a slow drop in amplitude with growing frequency (Shape A in Fig. 3.28a). With increasing Reynolds number, growing amplitudes of the nearly periodic velocity variations are observed. In the respective spectrum, the effective value of the variations increases. It is striking that the spectrum has a very broad peak and not only the frequency at the peak but all lower frequencies as well are greatly excited. In contrast to the spectrum of shape A, this spectrum has a steep flank for excited disturbances, i.e. the amplitudes drop off sharply with increasing frequency (Shape B in Fig. 3.28 b-d). With further increasing Reynolds number, the amplitudes of the disturbances become greater and their frequencies shift to larger values. From a certain velocity on, the first spots appear, like the ones also observed in the transition in two-dimensional boundary layers. They contain large amounts of high frequencies. With further increases in velocity, the spots become more numerous until finally a fully turbulent flow exists, whose spectrum has the typical shallow drop (Shape T in Fig. 3.28e). A similar evolution with rising velocity has been observed at all sites  $x/c$  of the unstable area.

With increasing distance from the leading edge, a change occurs in the Reynolds number  $Re$  starting at which the strong disturbances (spectrum shape B) were observed. In Fig. 3.29, the measured spectra labeled according to their shape are entered in an  $x/c-Re$ -diagram, which also shows the experimental transition curve and the first continuous excitation of stationary waves according to the petroleum painting images. The boundary between the spectrum shapes A and B corresponds to the first occurrence of travelling waves. It can be represented very well by a curve with a constant cross flow Reynolds number

$$\chi = 115 .$$

The frequencies of the peak in the spectrum are determined 53 for different Reynolds numbers and at different sites. Since the peaks are very broad, these values are only accurate to about 10%. The peak shifts for increasing Reynolds numbers at a fixed site  $x/c$  to higher frequency (see Fig. 3.30). For growing distance at a constant Reynolds number, the frequency of the peak decreases very slightly in the example shown, as well as for other Reynolds numbers. Fig. 3.31 summarizes the results. Norming the

frequencies for  $x/c = 0.36, 0.52, \text{ and } 0.62$  with  $\delta/Q_e$ , a constant value results within the limits of measurement accuracy (see Fig. 3.32).

$$F = 2 \pi (f \delta/Q_e) = 10.6 \cdot 10^{-2} .$$

Thus, the frequencies of the most excited travelling waves are dependent only on the local velocity at the boundary layer's edge and on the thickness of the boundary layer.

#### COMPARISON WITH THEORY

Calculations by Bieler [5] show that the projection profile in the direction of the main flow ( $\psi = 0$ ) and neighboring profiles ( $\psi < 35^\circ$ ) are stable for small disturbances. In a range of angles  $90^\circ < \psi < 35^\circ$ , on the other hand, one finds excited travelling waves in an entire frequency band. The continuous excitation of the travelling waves for different projection directions  $\psi$  was calculated for a velocity profile at  $x/c = 0.52$  and a Reynolds number  $Re = 8 \cdot 10^5$ . In Fig. 3.33, this non-dimensional continuous excitation is shown superimposed in double logarithms upon the frequency. In the experiment, a mixture of travelling waves whose directions can not be differentiated by the hot wire are observed. It is therefore a good idea to consider the envelope of the curves in Fig. 3.33 when comparing theory and experiment. It has, like the measured spectra, a broad peak underneath which excited waves also appear at all frequencies. The shape of the calculated spectrum along with the location of the peak closely resembles the measured spectrum from Fig. 3.28c, which was recorded at the site  $x/c = 0.52$  with the somewhat larger Reynolds number  $Re = 8.5 \cdot 10^5$ .

For further comparison between theory and experiment, the 54 excited frequencies were computed for several sites  $x/c$  and different Reynolds numbers. In all these calculations, the most strongly excited non-dimensional frequency occurs at:

$$F = 2 \pi f \cdot \sqrt{v_x/U_e} \cdot Q_e \simeq 2.2 \cdot 10^{-2} .$$

The experimentally determined frequency  $F$  can be transformed using the non-dimensional boundary layer thickness

$$\delta^* = \delta \cdot \sqrt{U_e/v_x} .$$

For  $x/c = 0.36, 0.52, \text{ and } 0.62$ ,  $\delta^*$  is nearly constant because of the accelerated flow:

$x/c$	$\delta^*$
0.36	4.68
0.52	4.60
0.62	4.57 .

With an averaged  $\delta^* = 4.62$  one obtains

With an averaged  $\delta^* = 4.62$  one obtains

$$F = (F/\delta^*) = 2.29 \cdot 10^{-2} .$$

The calculated value of  $F = 2.2 \cdot 10^{-2}$  comes very close to this value.

With an averaged  $\delta^* = 0.45$  and an  $F_\delta$  between 0.85 and 0.95 (see Fig. 3.32), a non-dimensional frequency  $F$

$$F = 1.88 \text{ to } 2.11 \cdot 10^{-2}$$

is obtained for the sites  $x/c = 0.75$  and  $x/c = 0.85$ . This  $F$  is not as much in line with the theory. This discrepancy can be attributed to the deviation from a quasi-two-dimensional flow in the measuring area.

Thus, the observed travelling waves can be understood in /55 their entirety, using the Orr-Sommerfeld equation, as instabilities of the different projection profiles. The frequency of the most strongly excited wave is also correctly predicted by the theory.

#### 3.6.4 INTERACTION BETWEEN STANDING AND TRAVELLING WAVES

In the present experiment, standing and travelling waves were observed. The first excitation of travelling waves can be represented by the curve  $\chi = 115$ , as was mentioned. In Fig. 3.29, in addition to this curve, the first stimulation of stationary vortices as they were observed in petroleum painting pictures was entered. As described previously, the registered sites  $x_i/c$  are those where the formation of bands could be observed in isolated instances. Regular band structures could be found somewhat later. Therefore, for the present experiment, it can be concluded that stationary and travelling waves are excited by approximately the same cross flow Reynolds number. More precise statements can only be made as a result of further experiments, since both the determination of  $x_i/c$  and the determination of the boundary curve for travelling waves are still fraught with uncertainty.

With measurements of stationary waves at  $x/c = 0.66$ , the effective value of travelling waves in a Reynolds number range of  $Re = 6.65 \cdot 10^5$  to  $Re = 7.45 \cdot 10^5$  were measured simultaneously when both disturbances were excited. The variations of wall shearing stress resulting from both disturbances are of the same magnitude. That means that the difference of the averaged signals in time between the wave peaks and valleys on a stationary wave is of the same magnitude as the difference between the maximum and minimum of the time signal of a travelling wave at the same site. The same is also true of the hot wire signals from the boundary layers. In this area, both disturbances are of equal significance.

At the same time, an alternation is also evident between both disturbances. The effective value of velocity variations changes with the site  $y$  within the stationary wave. In longitudinal /56 zones of low velocity it is up to 10% greater than at sites of great velocity and great wall shearing stress. This is in keeping with the notion that in the "wave valley" of a stationary wave, due to the lower velocity and velocity gradients at the wall, a velocity profile which is on the average more unstable develops, a profile in which travelling waves are excited to a greater degree. More precise statements concerning the question whether that is a significant instability mechanism in this three-dimensional boundary layer cannot be made until more measurements are taken.

#### 4. EXPERIMENTS IN THE MODEL WATER TUNNEL

##### 4.1 DESIGN OF THE EXPERIMENT

###### 4.1.1 THE MODEL WATER TUNNEL

The model water tunnel was available for experiments involving the semispherical cylinder. Such a tunnel is particularly well-suited to stability experiments since a flow which is quite free of disturbances can be achieved. The hydrogen bubble technique offers a further advantage in that a tried-and-true method of rendering things visible is made available.

The model water tunnel is presented in Fig. 4.1. Basically, it consists of a basin which is 18 m long, whose side walls and floor are made of glass for the most part. The tunnel is attached to the floor in such a way as to be insulated against vibration. The tracks upon which the car is led are set up apart from the tunnel so that the vibrations which occur thus are not transferred to the flowing medium. The tow wagon is driven by a rope tow powered by a D.C. shunt motor. As a result of the motor's revolutions, which can be regulated without intermediate steps, any speed at all between 0 and 5 m/s can be selected. The acceleration can be regulated to such a degree that after 1 m of warm-up, the desired final velocity is reached. The wagon is /57 stopped at the end of the tunnel by two pneumatic shock absorbers at a path length of 1.0 m. Thus, 16.0 meters are available for stationary towing velocity.

###### 4.1.2 THE SEMISPHERICAL CYLINDER

An engaged (swept) circular cylinder with a semispherical head having a diameter of 0.2 m was selected as a model. It was constructed of plexiglass. The length of the model, including the semispherical head, is 900 mm. The cylinder is held at the downstream end by a short rod which is attached to a brace (Fig. 4.2). By moving the mounting on the semicircular brace the angle of incidence  $\alpha$  can be set from  $+30^\circ$  to  $-35^\circ$ . This corresponds to sweep angles of  $55^\circ$  to  $90^\circ$ . The brace is held in a steel framework which is fastened to the towing wagon (Fig. 4.3) in such a way as to be insulated from vibrations. The insulation is set up so that a transfer of vibrations to the model

above 30 Hz is avoided to a great extent. In order to make the flow visible, a 375 mm long and 25-30 microns thick wire is attached to the model. Since the wire acts as a cathode, hydrogen bubbles form on it. The wire runs parallel to the cylinder's axis, and it can be soldered to two pins at various distances from the surface of the cylinder (from 0.2 to 1.0 mm). The pins jut out from the model's surface. The total angle between the wire and the stagnation line can be varied by rotating the cylinder around its axis. Thus, in the experiment, the two flow parameters, namely sweep angle  $\phi_0$  and inflow or towing velocity  $Q_\infty$  and the parameters of making the flow visible, namely angle of roll  $\gamma$  and distance of the bubble wire from surface  $z$ , can be varied.

## 4.2 THE HYDROGEN BUBBLE METHOD

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### 4.2.1 PRODUCING HYDROGEN BUBBLES

As mentioned, the hydrogen bubble method was utilized to make the flow visible. An electrical current was laid between a wire anemometer as cathode and a long copper track on the bottom of the basin of the model water tunnel as anode. This current actuates electrolysis. Along the wire anemometer, hydrogen bubbles are formed, which are carried along by the flow and - within certain limits - follow the paths of the particles. If the bubbles are illuminated from appropriate angles, they can easily be observed and photographed.

In the experiment, the bubbles were produced by two means. To make a "skimming area" visible, a constant voltage was set up. Then a continuous layer of bubbles lifts off, composed of skimming lines, i.e. a combination of all particles which emanate from a site. In a stationary flow, this area is identical to a flow area. In nonstationary flows, skimming lines or areas can be interpreted only with difficulty.

To create so-called time lines, a pulsating voltage was laid on the wire. Making things visible in this way is especially appropriate when changes in the flow field of the velocity component perpendicular to the wire occur with the coordinate along the wire, for these changes show up clearly as distortion of the time line.

When considering and interpreting the snapshots of skimming areas and time lines it is important to realize that this method of making things visible is integrative. Once structures have formed, they move downstream and can therefore be observed in areas where they no longer exist.

### 4.2.2 ELECTRICAL POWER SUPPLY

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A mains-connected unit was available to produce hydrogen bubbles. It supplies direct-current voltage which can be set between 0 V and 1,000 V with a maximum amperage of 5 A. With this

apparatus, it is possible to obtain sufficient hydrogen bubbles to provide visibility of the flow for any velocity.

To produce time lines, the current coming from the mains-connected unit is interrupted at regular time intervals. The duration of pulse and pauses can be chosen independently of each other as multiples of the period duration of a given basic frequency. This basic frequency, in turn, can be set between 10 Hz and  $10^5$  Hz.

A detailed description of the switching is found in Bippes [6].

#### 4.2.3 ILLUMINATION

Photoflash lamps manufactured by the Heimann Company (DGQ 8760ZW1) were used for lighting. The flash duration is approximately 0.02 ms. The white light produced by the flash was filtered to prevent an unclear image due to color dispersion at the refraction of the water-glass-air surfaces. The filter used let through wavelengths above 510 nm, and the photographic layer, depending on the film, is only sensitive up to 600 or 670 nm, so that only light in a frequency band from 510 nm to a maximum of 670 nm contributes to blackening the film.

Further, it is important to carefully set an angle of  $115^\circ$  between the optical axis and the entering cone of light in order to achieve an optimal contrast and maximal blackening of the film.

#### 4.2.4 PHOTOGRAPHY

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During the experiments, both simple and stereo photographs were taken in order to be able to observe a possible three-dimensional distortion of the bubble layer in the boundary layer.

For the stereo pictures, a stereo camera made at the institute with two lenses corrected for closeness (1:8, 75 mm) was available. The distance between both the optical axes can be set between 100 and 128 mm. During the experiments, the distance was adjusted so that the stereo pictures, while providing a maximal impression of depth, were still able to be put together to a three-dimensional picture.

For the mono pictures, a Linhof camera with lenses which were likewise corrected for closeness (1:9, 150 mm) was used.

All pictures were made by using the flash with an open shutter in a darkened room. Thus, the length of exposure is determined by the flash duration of 0.02 ms so that even at the greatest velocity, the movement blur stays very small. The moment of shooting the picture is determined by the towing wagon setting off a movable flash contact. The films used were Agfa Ortho and Agfa Pan roll film or flat film with 25 or 100 ASA.

#### 4.2.5 ACCURACY OF THE METHOD

In this experiment, the photos of the visualized flow are analyzed qualitatively for the most part. No conclusions as to the local distribution of velocity are drawn from the bubble movement. Thus, it remains to be decided only whether the bubbles follow the streamlines with sufficient accuracy and whether the influence of the bubble wire on the flow can be disregarded.

In the report by Schraub et al. [39], the error potential of the hydrogen bubble method is discussed in detail. The /61 authors arrive at the conclusion that the lifting power of the hydrogen bubbles against the velocity along the streamline can be disregarded at velocities above 0.02 m/s. Schraub et al. also investigated the influence of the bubble wire itself up to Reynolds number of  $Re = 15$  (derived from the diameter of the wire) and came to the conclusion that up to 75 diameter, a velocity deficit is measurable behind the wire. However, this is significant only for quantitative measurements.

In this experiment, the wire has a diameter of 25 microns. With a towing speed of 2.5 m/s, this leads to a Reynolds number of approximately 50 derived from the diameter of the wire and the velocity component perpendicular to the wire. The velocity component perpendicular to the wire was created under consideration of the angle of incidence, the super velocity at the location of the wire, and the height of the wire in the boundary layer. At such small Reynolds numbers, according to Schlichting [38], it can be assumed that no vortex street forms in the wire's wake. In isolated experiments under extreme conditions (e.g.  $\alpha = 35^\circ$ ,  $\gamma = 90^\circ$ , height in the boundary layer at  $U/U_e = 0.7$ ), Reynolds numbers up to 70 can occur, at which shedding of vortices is possible. However, it has not yet been determined whether shedding of vortices occurs for gassing wire anemometers with this Reynolds number. However, the possibility must be reckoned with in these experiments.

If the Reynolds number surpasses about 15 to 20, narrow strips, in which no bubbles separate, can arise at regular intervals (5-10 mm). This might be caused by a characteristic vibration of the wire. Böttcher [8] studied this phenomenon more closely. As far as possible, an attempt was made to keep the velocity component perpendicular to the wire and thereby the wire Reynolds number small by choosing small angles of roll  $\gamma$  and small distances from the wall in these experiments. In experiments in which the wire Reynolds number becomes greater than 20, two questions must be settled.

Does the wire influence the formation of disturbances?

If this is not the case, how can the structures caused by regular interruptions of the separation of bubbles and those caused by the flow be kept apart?

These two questions are discussed in the appendix under consideration of the experimental results.

#### 4.3 RESULTS AND DISCUSSION

In making the flow visible, different kinds of disturbances and waves were observed in the boundary layer. As is shown by the investigations described below, it is possible first to classify two different kinds of disturbance:

- a) waves, which are brought about by disturbances in the stagnation area and
- b) waves, which are observed where the flow in the stagnation area is undisturbed, with a larger angle at circumference.

To a): Waves caused by disturbances in the stagnation area are characterized by lines of the same phase, which are at a  $70^\circ$  to  $90^\circ$  angle to the cylinder axis. Fig. 4.4 shows these waves and their change with the Reynolds number for  $\phi_0 = 70^\circ$ . The Tollmien-Schlichting waves are already observed in the vicinity of the stagnation area ( $\gamma = 30^\circ$ ) and spread into a wedge-shaped area around the streamline direction. With increasing Reynolds number, a greater diffusion along the cylinder axis is possible until, at  $Re = 4 \cdot 10^5$  ( $R = 508$ ), the disturbance becomes irregular and is so strongly excited that a laminar-turbulent turbulence takes place on the entire flank. Similar processes are also observed for the sweep angle  $\phi_0 = 65^\circ$ . By using photographs, it could be proved that these waves propagate spatially.

Poll conducted intensive studies of the boundary layer in the stagnation area and came to the conclusion (see Section 2.3) that for critical Reynolds numbers of the boundary layer in the stagnation area,

$$R > 250$$

/63

artificially introduced disturbances in the stagnation area are excited.

In these experiments, the characteristic Reynolds number for the stagnation area  $R$  falls between 250 and 440. The angle of roll of the bubble wire to the stagnation line is  $\gamma = 30^\circ$ . Thus the mounting of the bubble wire, which lies upstream, is close to the stagnation area on the cylinder and could be a possible source of disturbances. Furthermore, the front mounting pin is attached at the transition of the head of the hemisphere to the cylinder, where the boundary layer has to overcome a rise in pressure within the stagnation area, making it unstable (cf. Poll [29]).

The experiments were repeated under somewhat modified conditions. The upstream mounting pin was moved forward into the area of pressure drop on the head of the hemisphere and the angle of roll of the bubble wire to the stagnation line was enlarged. It was then found that under these conditions, with sweep



angles  $\phi_0$  in the stagnation area between  $65^\circ$  and  $55^\circ$ , no waves could be observed with phase lines from  $70^\circ$  to  $90^\circ$  to the cylinder axis. These waves can, however, be brought back by causing additional artificial roughness near the stagnation line, as Fig. 4.5 shows for  $\phi_0 = 55^\circ$ , with the mounting pin moved forward and artificial disturbance.

To b): In order to investigate the characteristic instability of the three-dimensional boundary layer, care was taken that the stagnation area is free of potential sources of disturbance. As is already known from the plate experiment and from the experiments of Arnal [3], the cross flow instability causes a strong spanwise variation of the velocity component in the direction of the main flow. The time line method is well suited to making such structures visible and was therefore used in most of the experiments.

Fig. 4.6 shows two typical time line pictures. After a certain run length, the time lines, which are straight at first, show a regular distortion of increasing strength, which <sup>/64</sup> corresponds to a spanwise variation of the velocity. Lines of the same phase (union of the "wave mounds" in the time lines) lie at the edge of the boundary layer in roughly the direction of the local streamlines. These structures are therefore attributed to the cross flow instability. When the distance of the wire is varied with all other conditions being equal, a clear and reproducible distortion of the time line could be observed only very deep within the boundary layer ( $\delta^* \sim 0.5$ ). From this it can be concluded that the intensity of the disturbance due to cross flow instability decreases greatly toward the boundary layer edge.

The boundary layer flow was made visible for various parameters  $\phi_0$  and  $Q_\infty$  and evaluated with respect to three aspects:

- The first question was, for what smallest Reynolds number with a fixed sweep angle cross flow instabilities already became visible and at which Reynolds number the boundary layer becomes turbulent.
- Secondly, in images with regular excited cross flow instability, the wavelength was measured and compared with the results of other authors.
- Third, an attempt was made to make the occurrences in the boundary layer shortly before the actual turbulence visible.

Fig. 4.7 summarizes the results of initial excitation of cross flow instabilities and transition of the boundary layer. For every parameter combination  $\phi_0$  and  $Re$  for which experiments were conducted, it is recorded whether cross flow instabilities are observed (x) and whether turbulence was attained (T). In addition to the experiments, two curves for constant characteristic Reynolds number of the stagnation line boundary layer  $R = 250$  and  $R = 570$  are shown, and for purposes of comparison with Poll's results, so is the curve from painting images for the first

occurrence of cross flow instability in the petroleum painting image ( $\chi = 200$ ) and the one for the appearance of turbulence at  $\gamma = 90^\circ$ . For  $\phi_0 = 65^\circ$  and  $60^\circ$ , the Reynolds numbers at which /65 transition takes place agree quite well with those from Poll's experiments. At  $\phi_0 = 70^\circ$ , transition begins very early. With this sweep angle, the flow is already very much influenced by the flow around the head of the hemisphere. A disturbance due to the mounting pin which has been moved forward might possibly still influence the flow field.

Surprisingly enough, the Reynolds number for the first possible observation of cross flow instabilities also comes quite close to Poll's observations for  $\phi_0 = 65^\circ$  and  $60^\circ$ . It would be reasonable to expect the instabilities to become visible in the boundary layer earlier than on the wall, since the disturbance velocities decrease toward the wall. Furthermore, the hydrogen bubble method is much more sensitive than the petroleum painting method used by Poll. A possible explanation lies in the different initial disturbances in the experiments. With the colored pigment-oil emulsion, Poll introduces an initial disturbance to his cylinder, even though a very small one, whereas in the water tunnel experiment both the surface of the model and the incoming flow are very low in disturbances. For  $\phi_0 = 55^\circ$ , cross flow instabilities were not observed until much larger Reynolds numbers. The reasons for this have not yet been discovered.

The appearance of regular structures in the time lines were observed for varying sweep angles  $\phi_0$ , velocities  $Q_\infty$ , and angles of roll of the bubble wire  $\gamma$  to the stagnation line. In one picture, the evolution of the time lines over angles at circumference of about  $10^\circ$  to  $20^\circ$  can be traced and observed. One finds that the number of waves and, thus, the wavelength does not change. Comparisons of the measured results at  $40^\circ$  and  $80^\circ$  angles of roll also reveal no deviations in the wavelengths beyond the accuracy of measurement. Thus, as in the experiments by Poll and Bippes using petroleum painting images, the wavelength of the cross flow instabilities does not change with the run length. The wavelength was measured perpendicular to lines with the same phase in the pictures and was transformed using a scale factor; the accuracy of the measurements is approximately 10%.

In Fig. 4.8,  $\lambda/d$  is plotted against the Reynolds number. /66 The results of Poll and Bippes are also entered, as well as the experiments described here. Just as was the case for the experiments on the plate, a slight decrease wavelength with the Reynolds number becomes evident.

In Fig. 4.9, the wavelength was made non-dimensional with the value

$$\eta = \sqrt{d\nu/U_\infty} = \sqrt{d^2/(Re \cdot \cos\phi_0)}$$

characteristic of the boundary layer. Within the limits of the accuracy of measurement, a constant value over the Reynolds number of

$$\lambda/n = 8.7$$

results. The 99% boundary layer thickness on the cylinder does not change much for a wide range of the angle of roll  $\gamma$  ( $30^\circ$  to  $70^\circ$ ) and takes on the approximate value

$$\delta^* \sim 2$$

when it is likewise made non-dimensional with  $\lambda$ . Thus, as in the experiment on the plate, the ratio of wavelength to boundary layer thickness is approximately four:

$$\lambda/\delta = 4.4 \quad .$$

#### MAKING THE BOUNDARY LAYER VISIBLE SHORTLY BEFORE THE LAMINAR-TURBULENT TRANSITION

It is very difficult to make the boundary layer visible just before the laminar-turbulent transition, since the boundary layer becomes very thin. In addition to the distortions of the time lines, familiar from cross flow instabilities, the pictures showed the appearance of waves with increasing Reynolds number. The lines of equal phase of these waves do not follow the local streamlines; they are at an angle of  $70^\circ$  to  $90^\circ$  to the cylinder axis. Fig. 4.10 gives some typical examples. In detail a) of 67 the figure, cross flow instabilities can be observed in the left part of the picture. The development of these cross flow instabilities can be traced over a large run length. To the right, the first thing observed is the typical distortion of the time lines due to cross flow instability; then they are disturbed by waves at a different angle. Likewise in detail b), the waves with phase lines from an angle of  $70^\circ$  to  $90^\circ$  can be seen. At a greater Reynolds number, these waves propagate over a larger section along the y axis (c).

For waves in this direction, it could be demonstrated that they propagate spatially. Also, stationary vortices are possible only in the direction of flow, since such vortices are the only ones that are free of force. The observed structures are therefore categorized as travelling waves.

Thus, just as in the experiment on the plate, standing and travelling waves are observed for the swept circular cylinder. According to these experiments, the first thing observed is a continuous excitation of the stationary vortices. It is necessary when evaluating this result to take into account that the experiments in the water tunnel were carried out with a flow which had very few disturbances, causing the initial disturbances of travelling waves to be very small. With growing Reynolds number before the transition to turbulence, travelling waves (i.e. waves

with lines of equal phase in an angle to the cylinder axis of 70° to 90°) were always observed as well.

## 5. SUMMARY AND OVERVIEW

In accordance with knowledge gained from preliminary trials, a model proposed by Hirschel and Dallmann [17] consisting of a swept plate with a displacement body impressing pressure was designed and constructed for the 1-meter wind tunnel. In the course of the experiments, this model was improved by the addition of lateral plates, so that a quite satisfactory quasi-two-dimensional flow occurred on the plate. On the plate, the pressure gradient /68 impressed by the displacement body creates a boundary layer, which becomes unstable and reaches turbulence. This unstable boundary layer was studied using methods of making the flow visible (petroleum painting and naphthalene methods) and by hot wire and hot film measurements. In detail, results of the measurements were:

- Stationary cross flow instabilities with a wavelength  $\lambda = 4\delta$  were observed in the unstable area. At the same time, a broad frequency band of travelling waves is also excited. The maximal excited frequencies are  $\omega = 2\pi f = 0.11 Q_e / \delta$ .
- Both disturbances are excited in roughly the same area. For the travelling waves, a constant cross flow Reynolds number  $\chi = 115$  describes the location of the first observable appearance quite well.
- The RMS value of the travelling waves is modulated by the standing waves. Thus, there is an interaction between both disturbances.

- The generalized Orr-Sommerfeld equation can be used to describe the wavelength and the direction of the stationary modes as well as the frequency of the travelling waves.

In a further experiment in the model water tunnel, the boundary layer on a swept circular cylinder with a semispherical head above the wall was made visible using the hydrogen bubble method. It was possible to prove the existence in the boundary layer of stationary cross flow instabilities, which had hitherto been made visible only in petroleum painting and sublimation images on the surface of swept wings. The pictures were evaluated for different Reynolds numbers, sweep angles, angles of roll of the bubble wire to the stagnation line, and heights of the wire in the boundary layer wall. The results were:

- Cross flow instabilities can only be observed very deep within the boundary layer ( $\delta \sqrt{U_\infty/\nu} \leq 0.5$ ).
- The wavelengths of the cross flow instability also amount /69 to approximately  $4\delta$

$$\lambda = 4\delta .$$

- At first, cross flow instabilities are observed on the cylinder in the water tunnel (where the oncoming flow is low in disturbances!); later, however, travelling waves with phase lines of  $70^\circ$  to  $90^\circ$  to the cylinder axis are as well.
- Before the transition to turbulence, travelling, greatly excited waves also are always observable.

For further experiments in the 1-meter wind tunnel, it would be advisable to improve several elements of the model. Should preliminary trials indicate that a smaller sweep angle also is sufficient to create an unstable boundary layer, it would be advisable to choose it in order to make better use of the free jet's potential core. By this means, it might be possible to maintain a better quasi-two-dimensional flow at the back part of the plate, too. In the course of follow-up studies of stationary instabilities, how their continuous excitation is related to initial disturbances should be investigated. This would require considering the influence of the tunnel's smoothing filters and of small initial disturbances on the plate. When looking further into the travelling waves, it would be interesting to ask whether it is possible to measure the direction of the travelling waves and to compare it to theory.

Several questions regarding the interaction of travelling and stationary waves remain unanswered. First, measurements with a calibrated hot wire could make a better quantitative comparison of the two types of disturbance possible. These measurements should be conducted with different distances from the wall. The results might shed some light on why the stationary instabilities show up so plainly in petroleum painting images in spite of such strongly excited travelling waves.

Another interesting topic would be to investigate the 70  
influence of the pressure progression and sweep angle on the two  
disturbance waves and the location of transition.

Precisely because the occurrences in the unstable three-  
dimensional boundary layer are so complex, valuable contributions  
can be made by making the flow visible. When continuing with  
these experiments, it is necessary to study thicker boundary  
layers at lower relative wind velocities, making possible better  
resolution of the occurrences and minimalization of disturbances  
caused by the wire. Also, the water tunnel is especially well-  
suited to studying the influence of artificially introduced  
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## PROFILE DATA FOR DISPLACEMENT BODY AND SLATS

The data are indicated in a Cartesian coordinate system.

## Displacement body

x points perpendicularly from the trailing edge toward the front tangentially to the flat portion of the underside.

x [mm]	Lower Side y [mm]	Upper Side y [mm]
0	0	0
20	0	20
40	0	34
60	0	47
80	0	57
100	0	65
120	0	73
140	0	79
160	0	85
180	0	91
200	0	95
220	0	99
240	0	102
260	0	103
270	1	104
280	2	104
300	4	105
320	9	105
340	14	105
360	21	103
380	29	101
400	40	98
410	46	96
420	53	94
430	59	91
440	68	85
447	77	77

The x axis points perpendicularly from the trailing edge toward the front and touches the wing there tangentially.

x [mm]	Lower Side y [mm]	Upper Side y [mm]
0	0	0
10	5	10
20	9	17
30	11	22
40	13	27
50	14	30
60	12	32
70	8	33
80	2	32
90	0	28
95	2	25
100	7	18
102	13	13

#### REMARKS CONCERNING DISTURBANCES OF THE FLOW DUE TO THE HYDROGEN BUBBLE WIRE

As was mentioned in Section 4.2.5, caution is particularly called for in wire Reynolds numbers above 15-20. One notes in many experiments that from this Reynolds number, at regular intervals no bubbles are freed from the wire. Just which procedures are responsible for this behavior is a matter which has not yet been clarified. During the experiments, attempts were made to keep the wire's Reynolds number below the 15 to 20 range by suitable selection of the parameters. For a few experiments, however, this condition could not be met. It must therefore be determined whether this effect has any influence on the flow in the boundary layer.

First, studies were carried out to determine how the structures developed as a result of the wire could be separated from those generated by the flow. /80

In experiments by Böttcher involving a wire anemometer outside a boundary layer and also in experiments involving a cylinder in which no cross flow instabilities could be found, the same behavior was always observed in the bubble layer: at regular intervals, no bubbles are freed at the wire, these "bands without bubbles" continue in a natural way along the streamline. The surrounding layer of bubbles and the time lines are not influenced

by this behavior. On the contrary, structures develop that are produced in the bubble layer with an increasing run length as a result of an already present velocity field, as Fig. 4.6 shows. In this way, both structures can be distinguished simply.

During the experiments within the range of the parameters in which structures could be observed both as a result of the bubble wire as well as due to the cross flow instabilities, special attention was paid to determine whether any influence could be noted as a result of the flow. Various experiments showed that as a result of the poor production of bubbles, structures are formed that are the result of cross flow instabilities. The wavelength of the cross flow instabilities did not agree with the characteristic distances of the interrupted bubble layer. From this it can be concluded that the cross flow instability is not influenced by the wire. For purposes of evaluation, pictures were used that show this quite plainly.

## 8. LIST OF ILLUSTRATIONS

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- Fig. 3.26: Modulation of the Averaged Velocity and Wall Shearing Stress along  $y$  and  $y_t$  by the Cross Flow Instability
- Fig. 3.27: Some Examples of the Hot-Wire Signals of Travelling Waves
- Fig. 3.28: Change in the Hot-Wire Signals of Travelling Waves and of Their Frequency Spectra as Velocity Increases
- Fig. 3.29: Appearance of Travelling and Standing Waves /85  
 Depending on the Site  $x/c$  and the Reynolds Number  $Re$ ,  
 A: Undis-turbed Flow, B: Travelling Waves, ----:  $x = 115$ ,  $\downarrow$  : First Appearance of Stationary Cross Flow Instabilities,  $\square$  : Hot-Wire Measurements

- Fig. 3.30a: Change in the Frequency Spectra of the Hot Wire Signals with a Fixed Site  $x/c = 0.52$ , 1:  $Re = 2.85 \cdot 10^5$ , 2:  $Re = 4.59 \cdot 10^5$ , 3:  $Re = 6.22 \cdot 10^5$ , 4:  $Re = 6.74 \cdot 10^5$ , 5:  $Re = 8.50 \cdot 10^5$
- Fig. 3.30b: Change in the Frequency Spectra of the Hot Wire Signals with a Fixed Reynolds Number  $Re = 6.4 \cdot 10^5$ , 1:  $x/c = 0.36$ , 2:  $x/c = 0.52$ , 3:  $x/c = 0.62$
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- Fig. 4.3: Diagram of the Model's Vibration Insulation
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- Fig. 4.5: Growth of a Turbulent Wedge and Travelling Waves Due to Disturbance of the Boundary Layer in the Stagnation Area
- Fig. 4.6: Cross Flow Instability in the Boundary Layer Made 86 Visible Time Lines
- Fig. 4.7: Appearance of Cross Flow Instabilities and Transition Depending on the Reynolds Number and the Sweep Angle
- Fig. 4.8: Wavelength of the Cross Flow Instability Depending on the Reynolds Number
- Fig. 4.9: Wavelength of the Cross Flow Instabilities Normed by  $\eta = \sqrt{d \cdot \nu / U_\infty}$
- Fig. 4.10: Visualization of Waves with Different Directions Shortly before the Laminar-Turbulent Transition

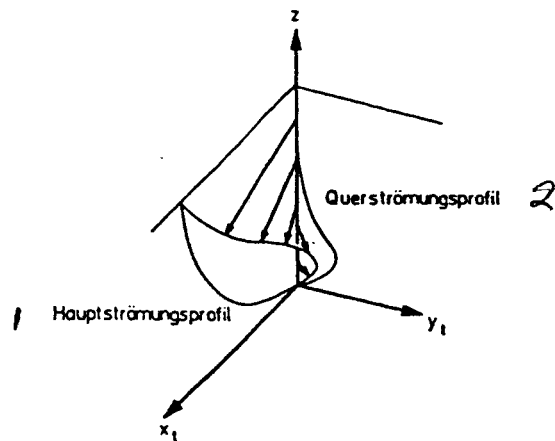


Fig. 2.1: Three-Dimensional Velocity Profile with the Profiles Projected Tangentially and Normally to the Streamline at the Edge of the Boundary Layer  
 1: Main Flow Profile  
 2: Cross Flow Profile

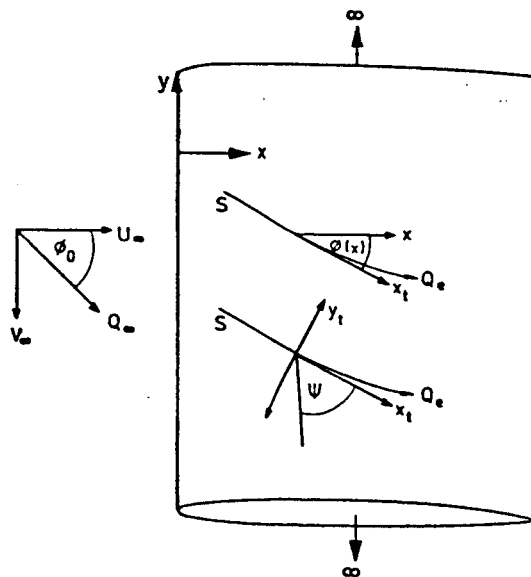


Fig. 2.2: Definition of the Coordinate System on an Infinitely Long, Swept Model

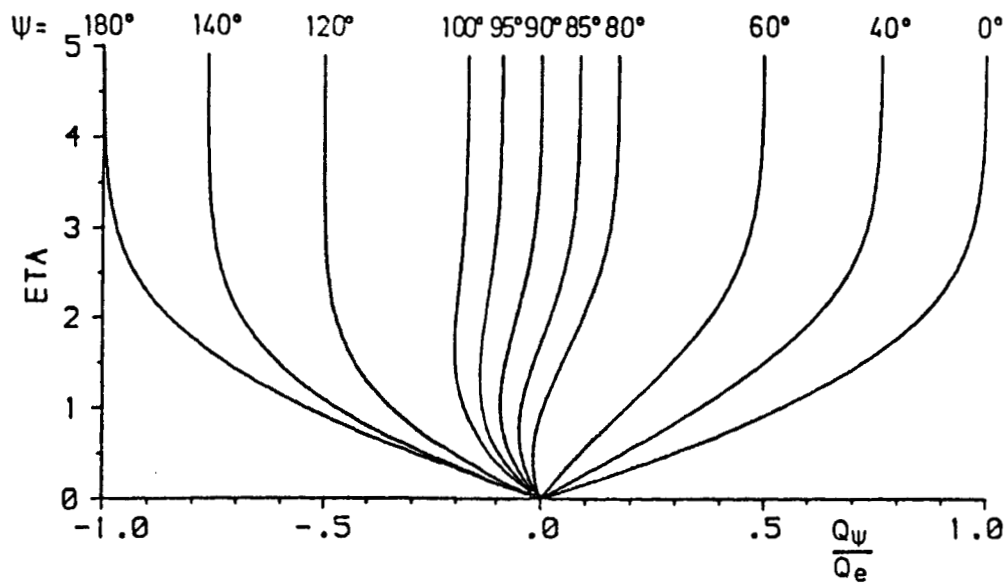


Fig. 2.3: Projection Profiles of a Three-Dimensional Velocity Profile in Accelerated Flow Independent of Angle (Bieler 1985)

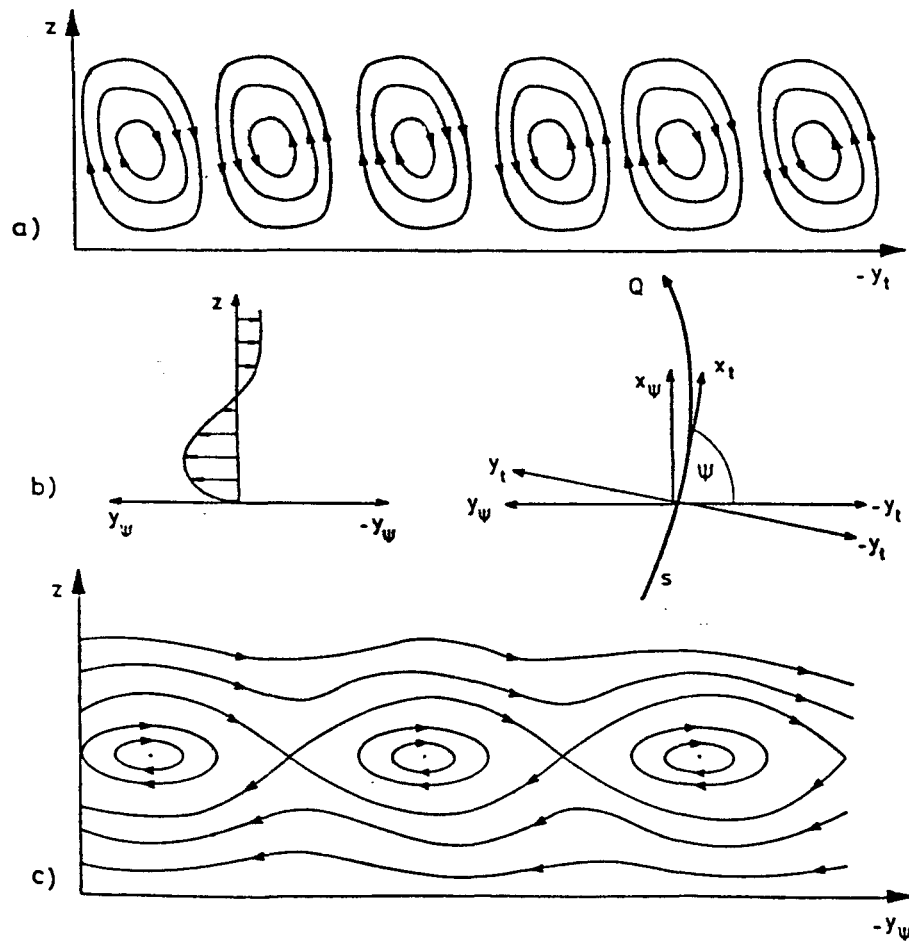


Fig. 2.4: Streamline Image of the Stationary Cross Flow Instability

- a) Streamline Image of the Disturbance
- b) Projected Profile in Direction  $y_\psi$
- c) Streamline Image of the Overlapping of Disturbance and Main Flow

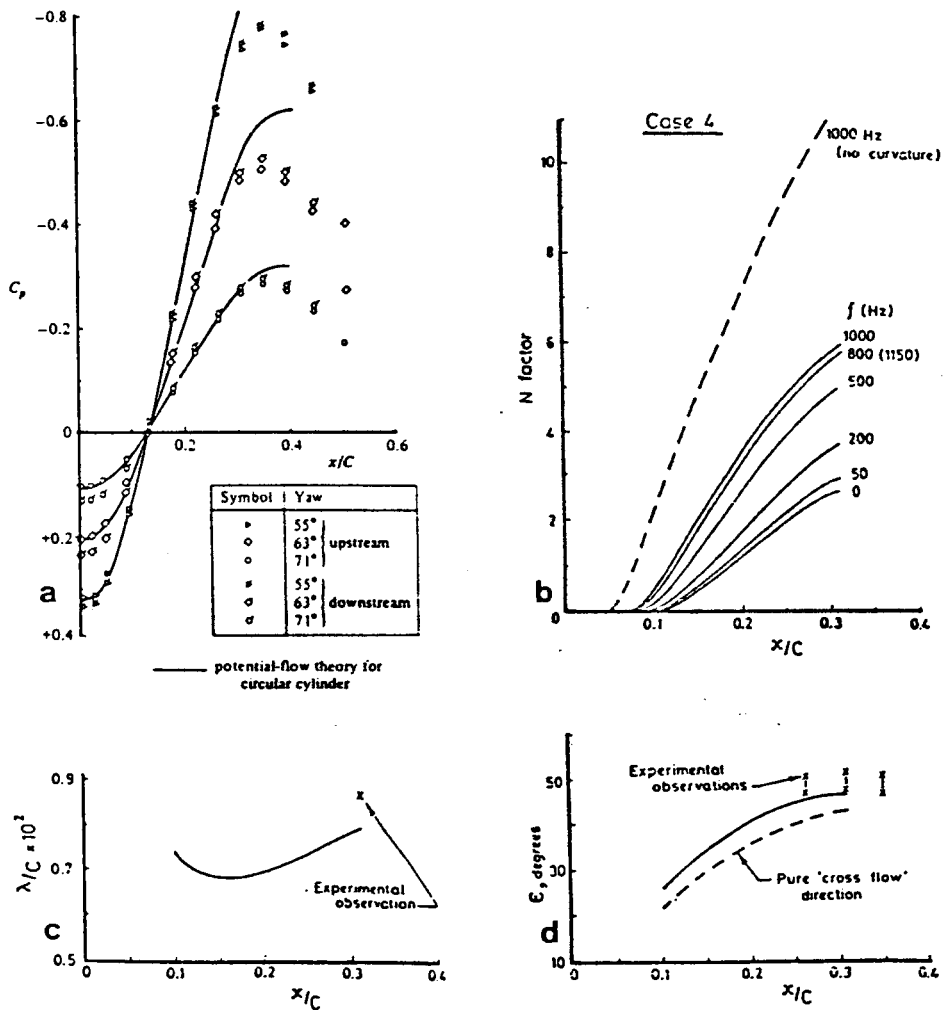


Fig. 2.5: Poll and Malik's [23] Results on a Swept Cylinder  
 a) Pressure Progression  
 b) Excitation Factor n for Various Frequencies  
 c) Wavelength of the Stationary Cross Flow Instability  
 d) Direction of the Stationary Cross Flow Instability

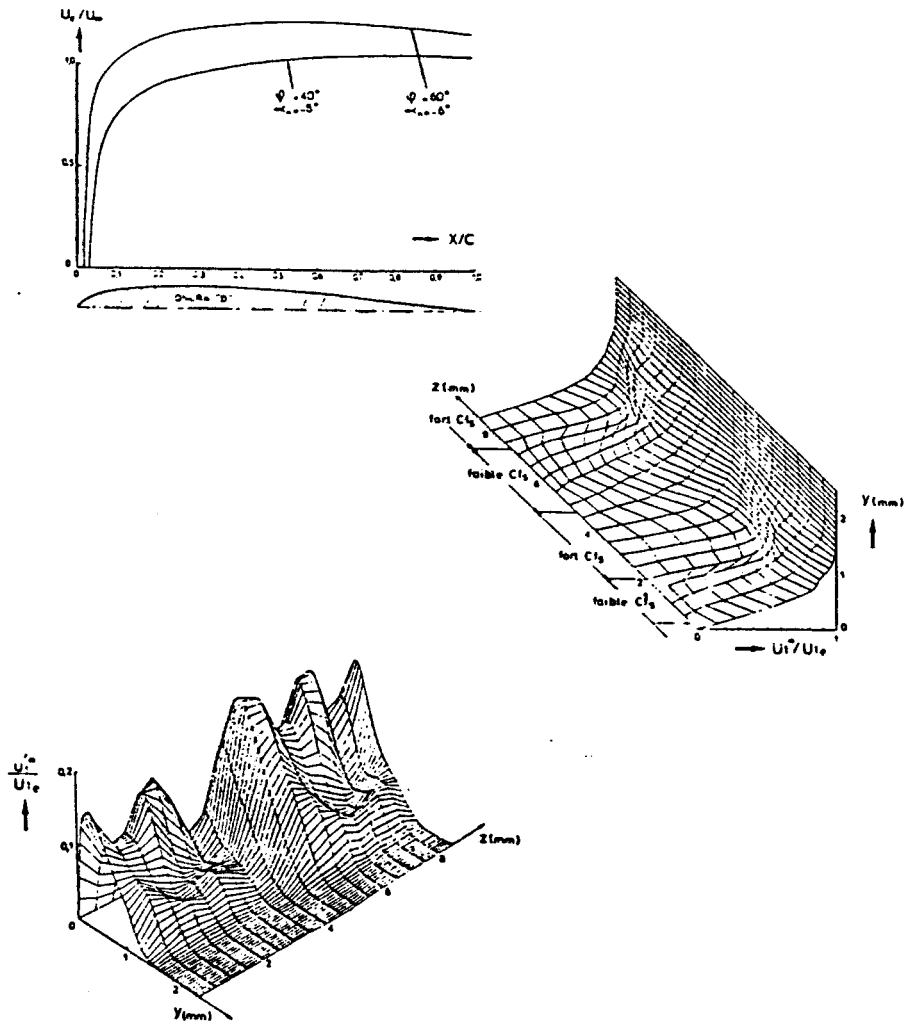


Fig. 2.6: Results achieved by Arnal et al. [3] on the ONERA "D" Airfoil

- a) Pressure Progression
- b) Modulation of the Average Velocity Due to the Cross Flow Instability
- c) Modulation of the Effective Value of the Variations in Velocity



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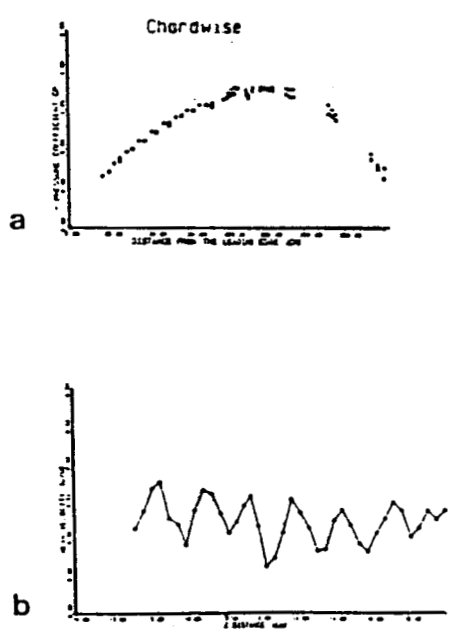


Fig. 2.7: Saric's [37] Results on a Swept Plate  
a) Pressure Progression  
b) Modulation of the Average Velocity Due to Stationary Cross Flow Instability

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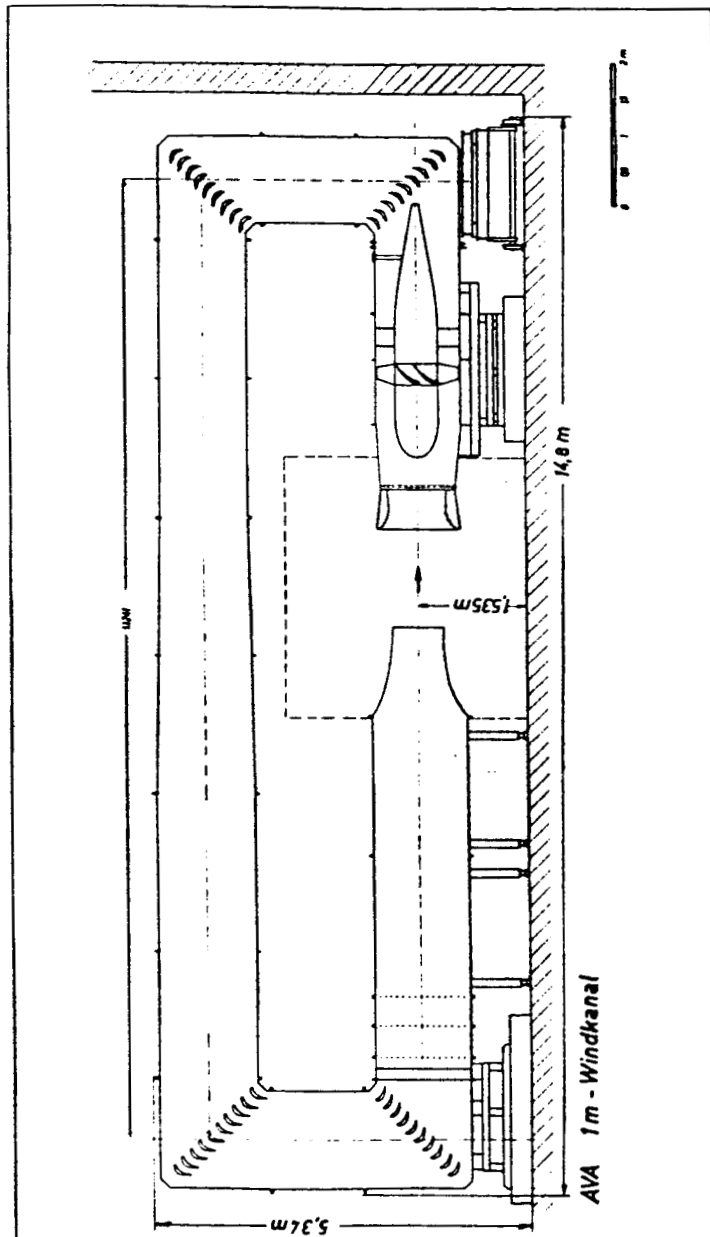


Fig. 3.1: The 1-Meter Wind Tunnel

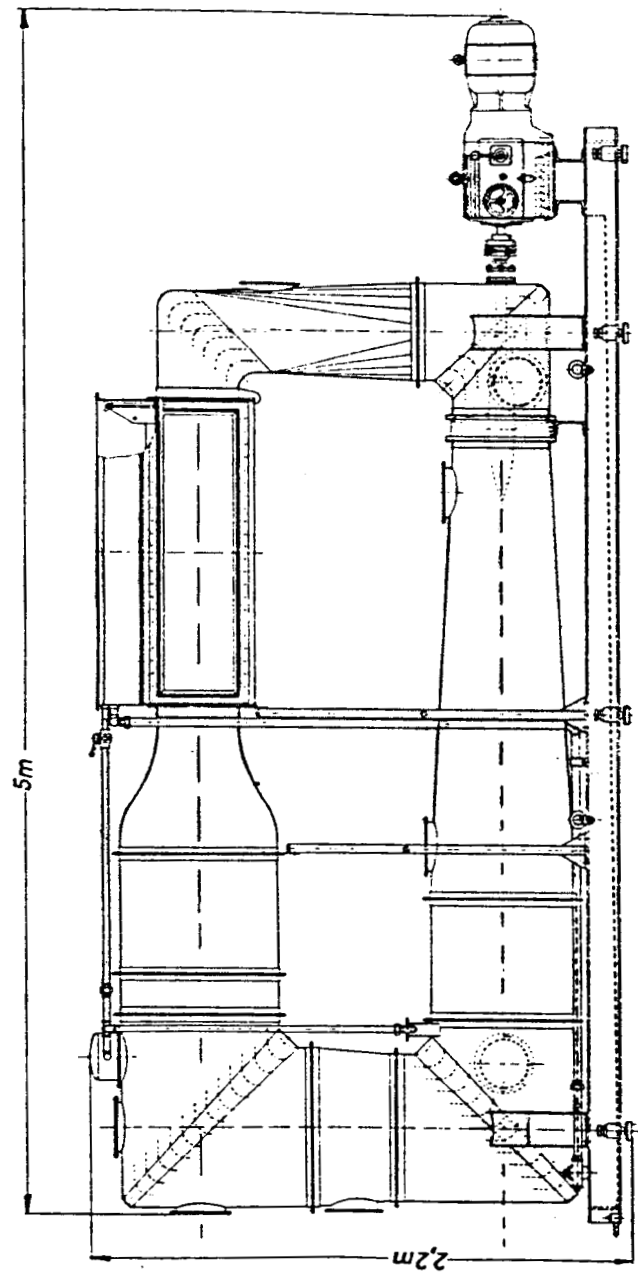


Fig. 3.2: The Circulating Water Tunnel

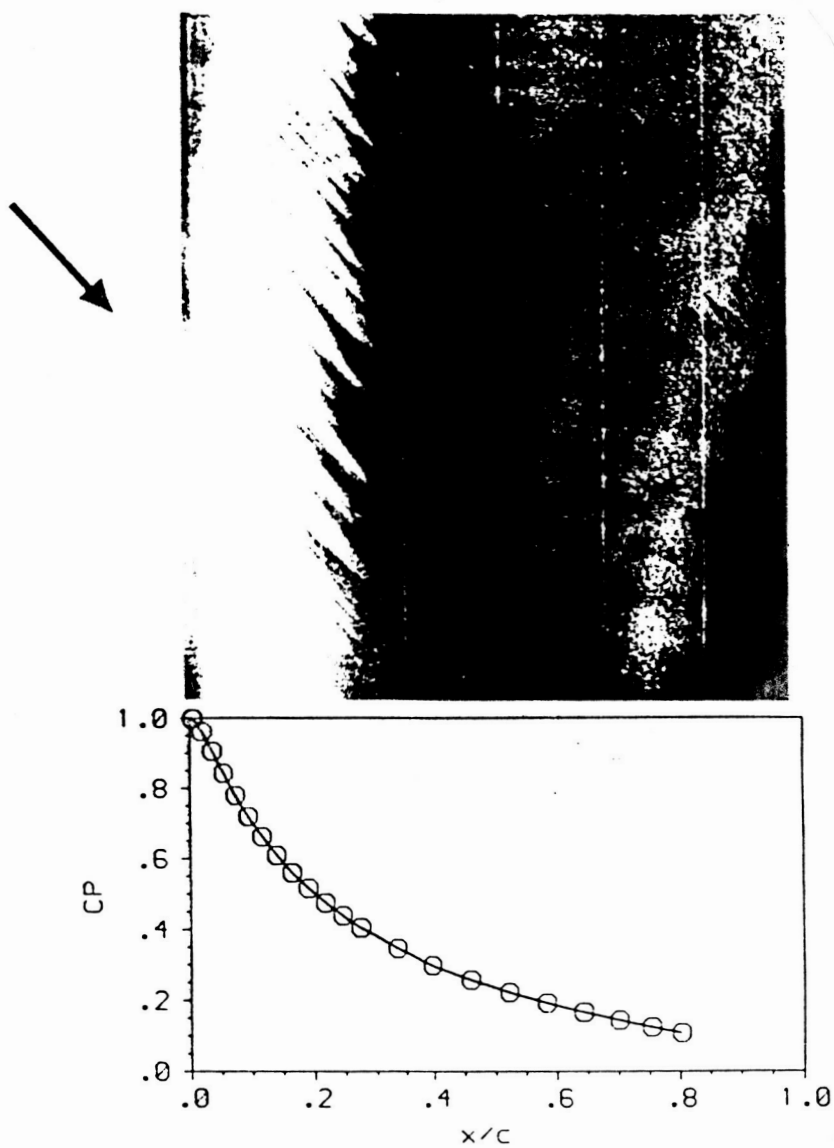


Fig. 3.3: Rendering the Transition Site and the Cross Flow Instability Visible by Means of the Sublimation Method on the Pressure Side of the NACA-0010 Wing  
 $Re = 1.5 \cdot 10^6$ ,  $\alpha = 15^\circ$ ,  $\phi_0 = 48^\circ$

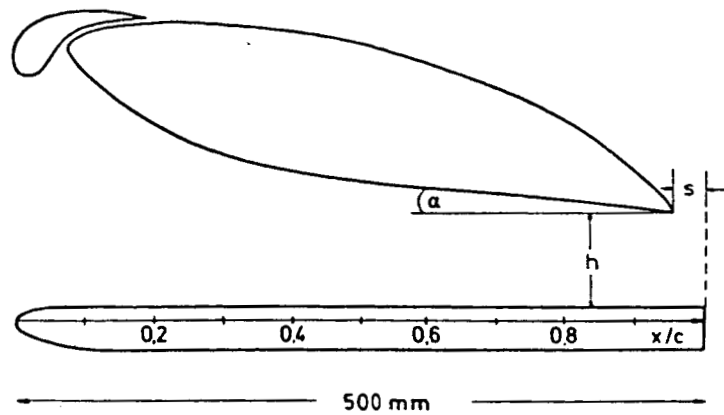


Fig. 3.4: Cross-Section of the Plate and Displacement Body

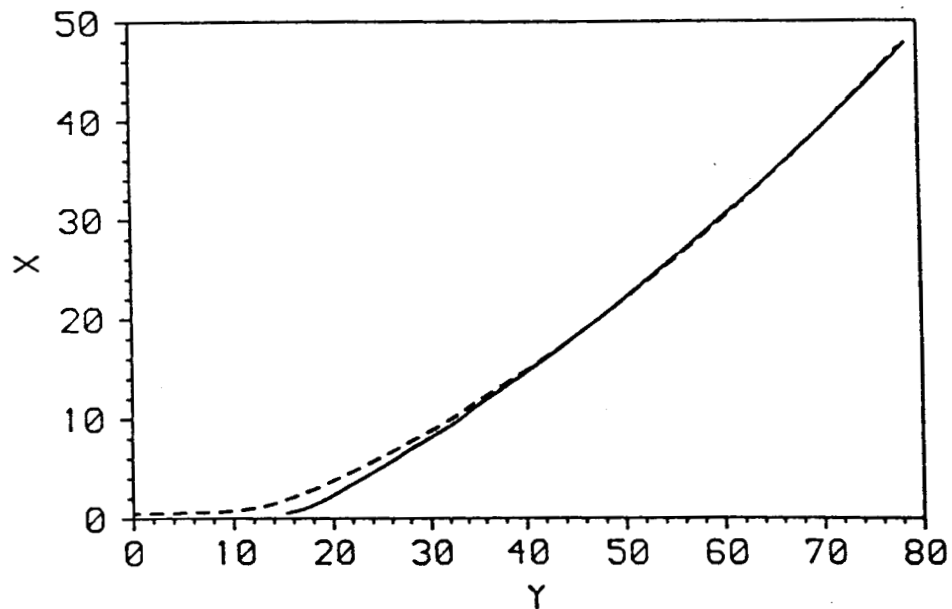


Fig. 3.5: The Streamlines Calculated from Measured Pressure Progressions  
 1: From Measurements Prior to the Installation of the Lateral Plates  
 2: From Measurements Following the Installation of the Lateral Plates

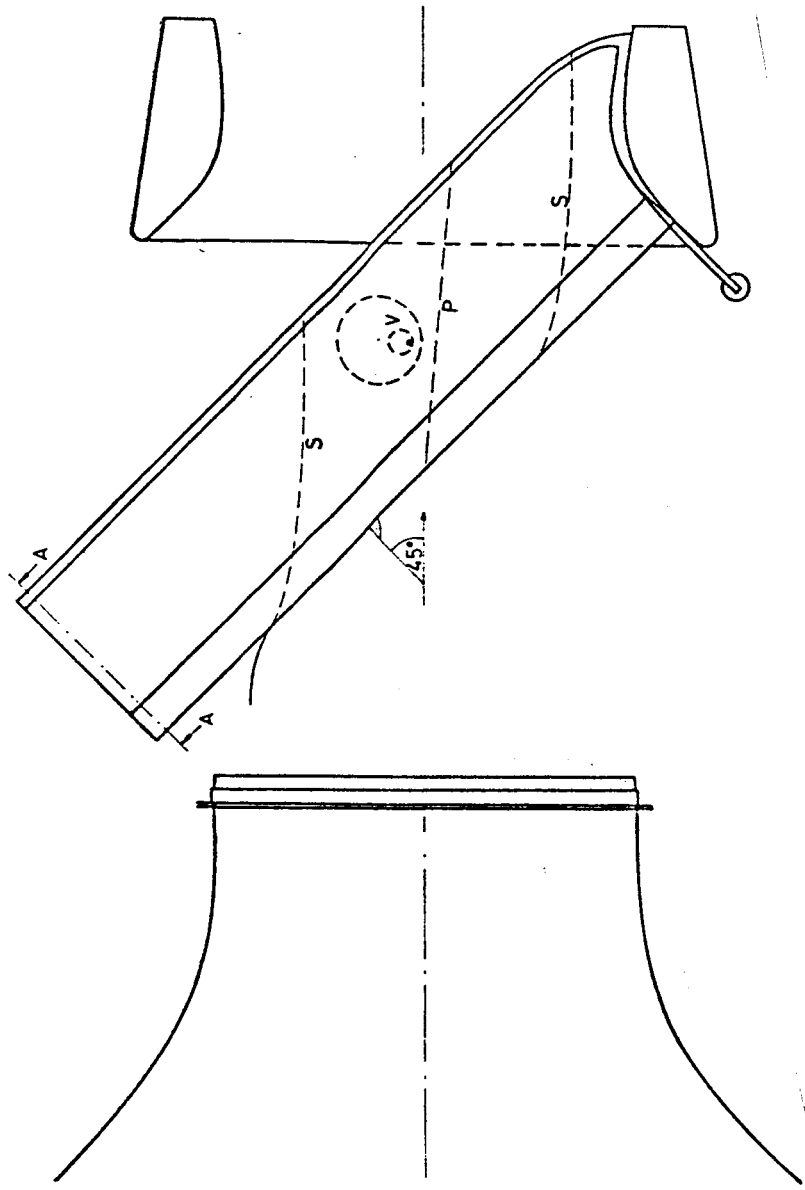


Fig. 3.6: Structural Sketch of the Test in the 1-Meter Wind Tunnel  
 S: Side Wall Shaped According to the Streamline  
 P: Pressure Piercings  
 V: Sweep Mechanism

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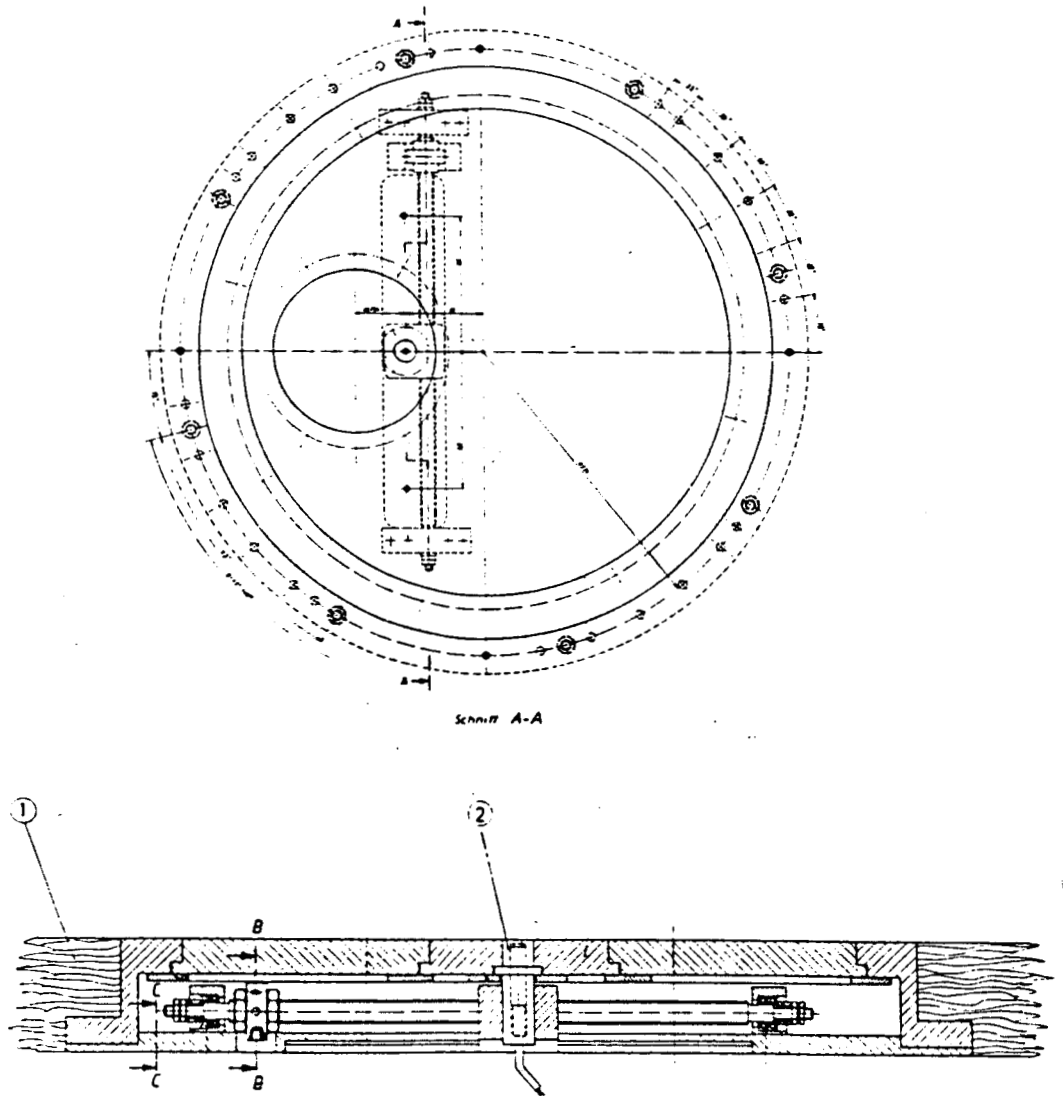


Fig. 3.7: Sweep Mechanism for Hot Wire and Hot Film Anemometer  
1: Plate, 2: Mounting Cylinder for the Anemometers  
3: Section A-A

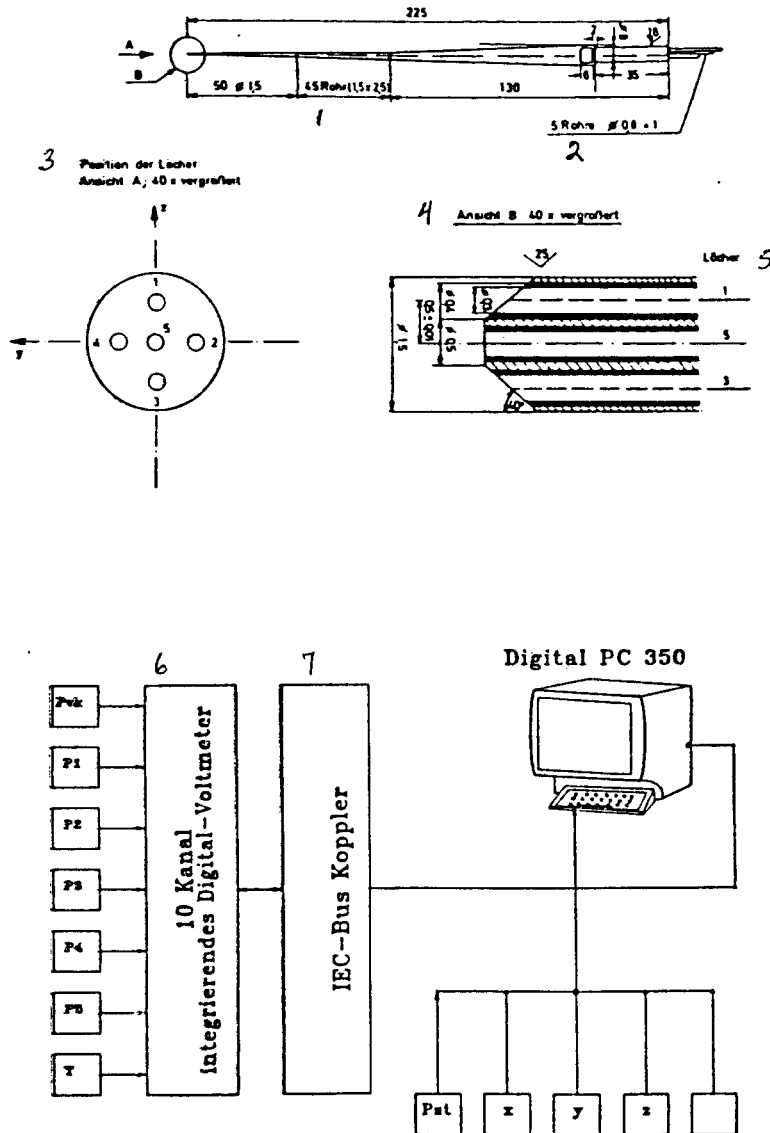


Fig. 3.8: Sketch of the Five-Hole Anemometer with a Block Diagram of the Data Acquisition System  
 1:45 Tube    2:5 Tubes    3:Position of the Holes, View A, 40 Times Enlarged    4:View B, 40 Times Enlarged  
 5:Holes    6:10-Channel Integrating Digital Voltmeter  
 7:IEC-Bus Coupler



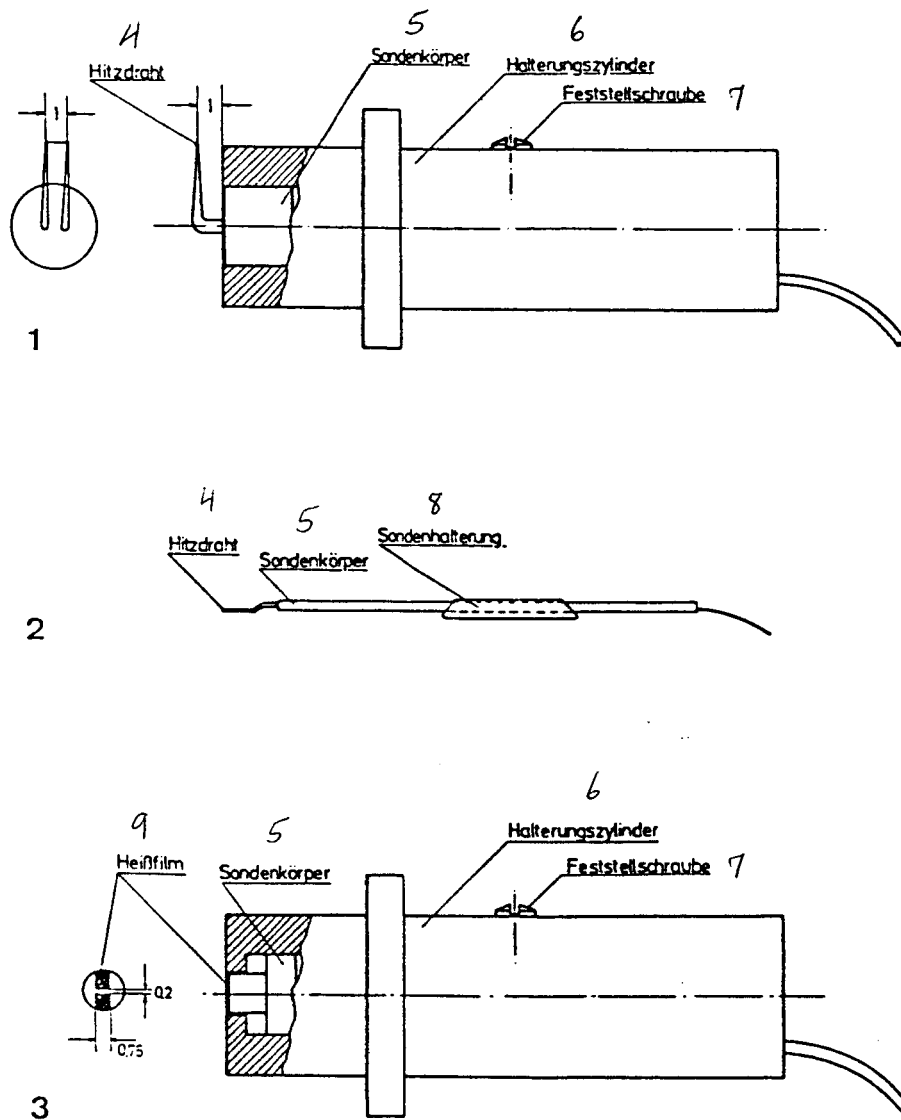


Fig. 3.9: Sketch of the Hot Wire and Hot Film Anemometers  
 4: Hot Wire 5: Anemometer Body 6: Mounting Cylinder  
 7: Screw 8: Anemometer Mounting 9: Hot Film

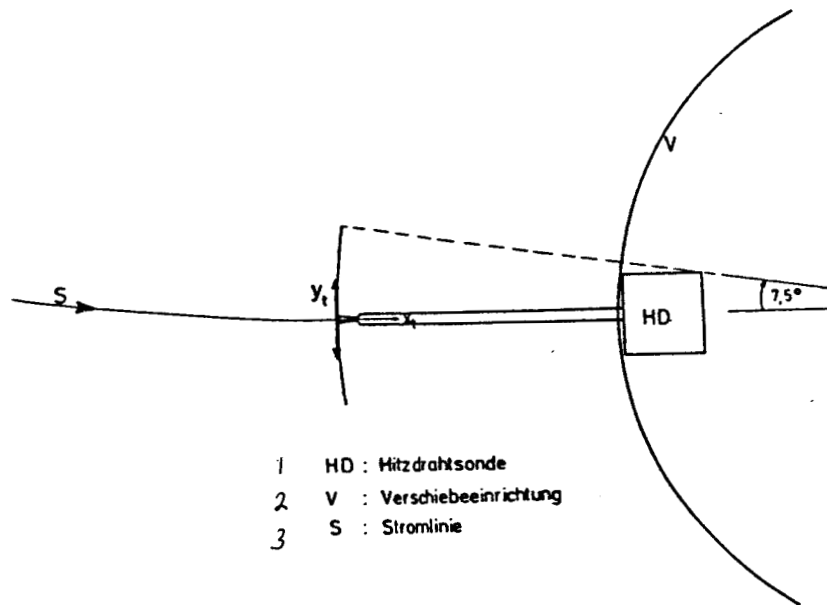


Fig. 3.10: Sketch of the Sweep of Hot Wire Anemometer 2 in the Streamline-Oriented Coordinate System. 1: Hot Wire Anemometer 2: Sweep Mechanism 3: Streamline

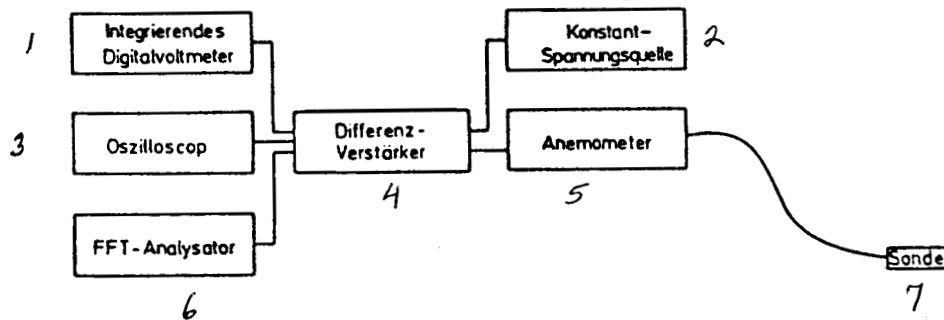


Fig. 3.11: Switching for Measurements Using the Hot Wire and Hot Film Anemometers  
1: Integrating Digital Voltmeter 2: Constant Voltage Source 3: Oscilloscope 4: Difference Amplifier  
5: Anemometer 6: FFT-Analyzer 7: Probe

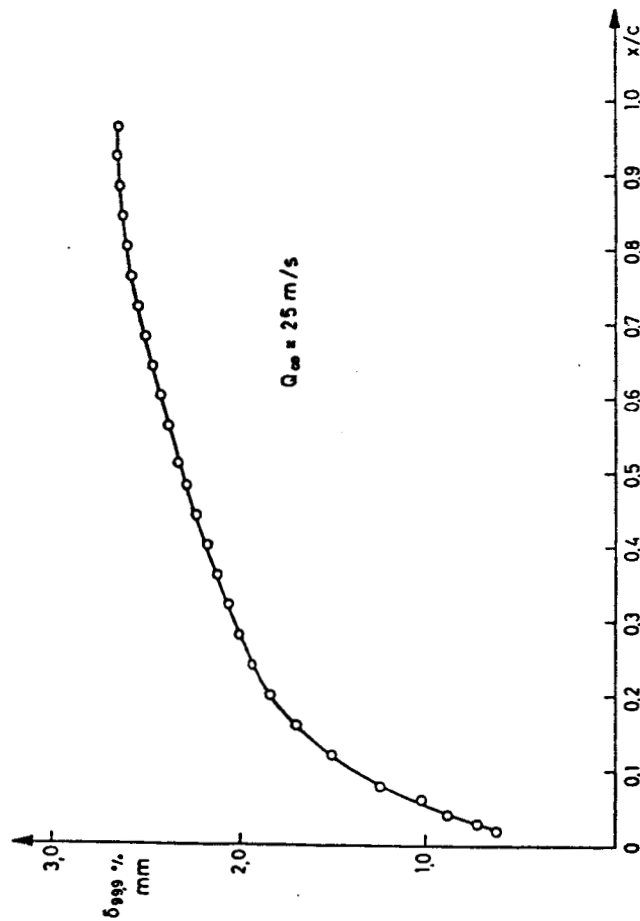


Fig. 3.12a: Course of the Calculated 99.9% Boundary Layer Thickness  $\delta$  above  $x/c$

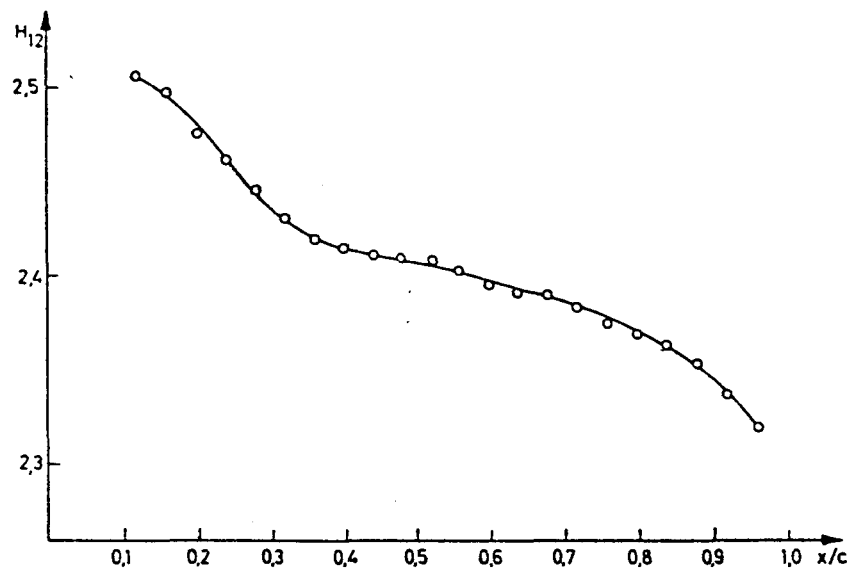


Fig. 3.12b: Course of the Shape Factor  $H_{12}$  of the Projected Velocity Profile above  $x/c$  in the Direction of the Main Flow ( $x_t$ )

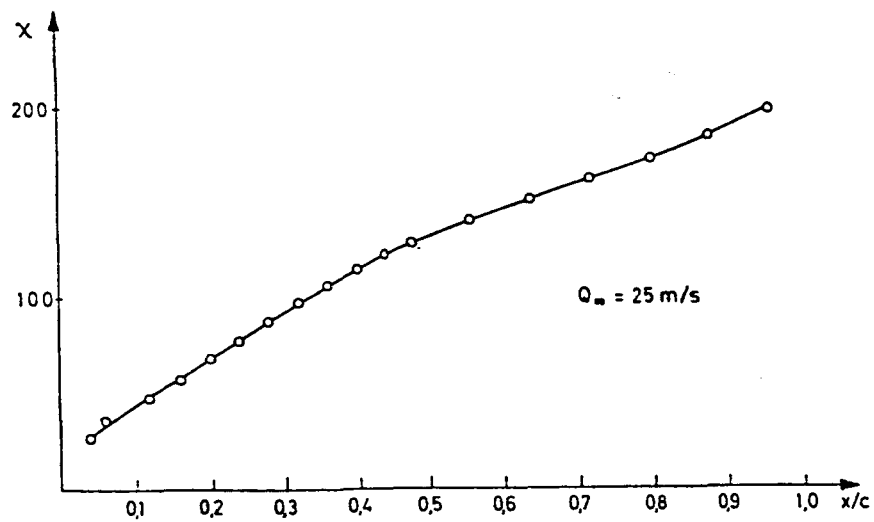


Fig. 3.12c: Course of the Cross Flow Reynolds Number  $\lambda$  above  $x/c$

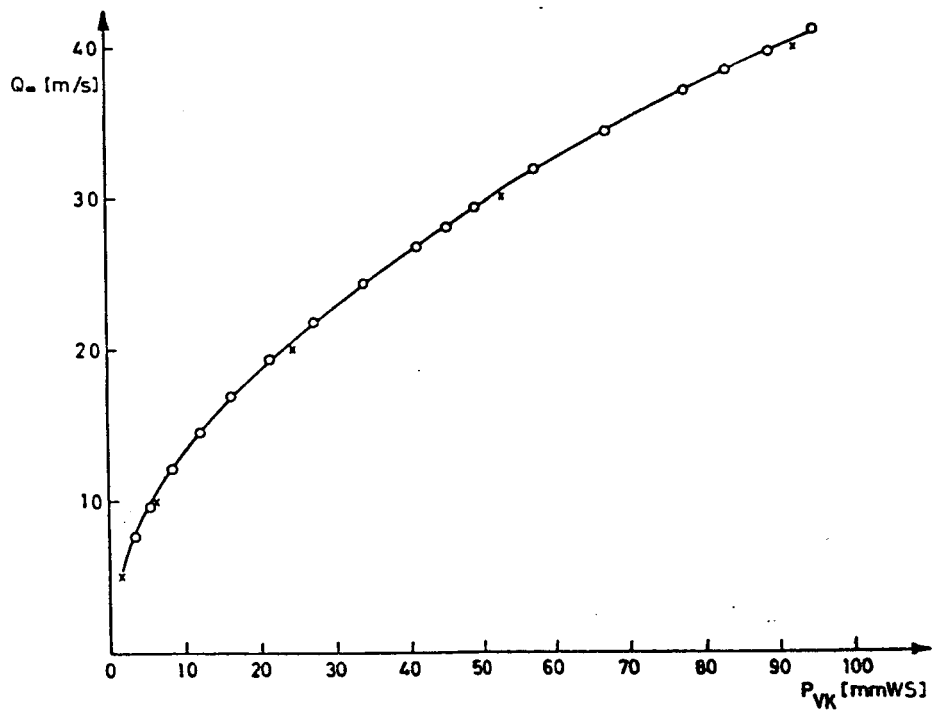


Fig. 3.13: Calibration Curve of the 1-Meter Wind Tunnel  
o: With Model  
x: Without Model

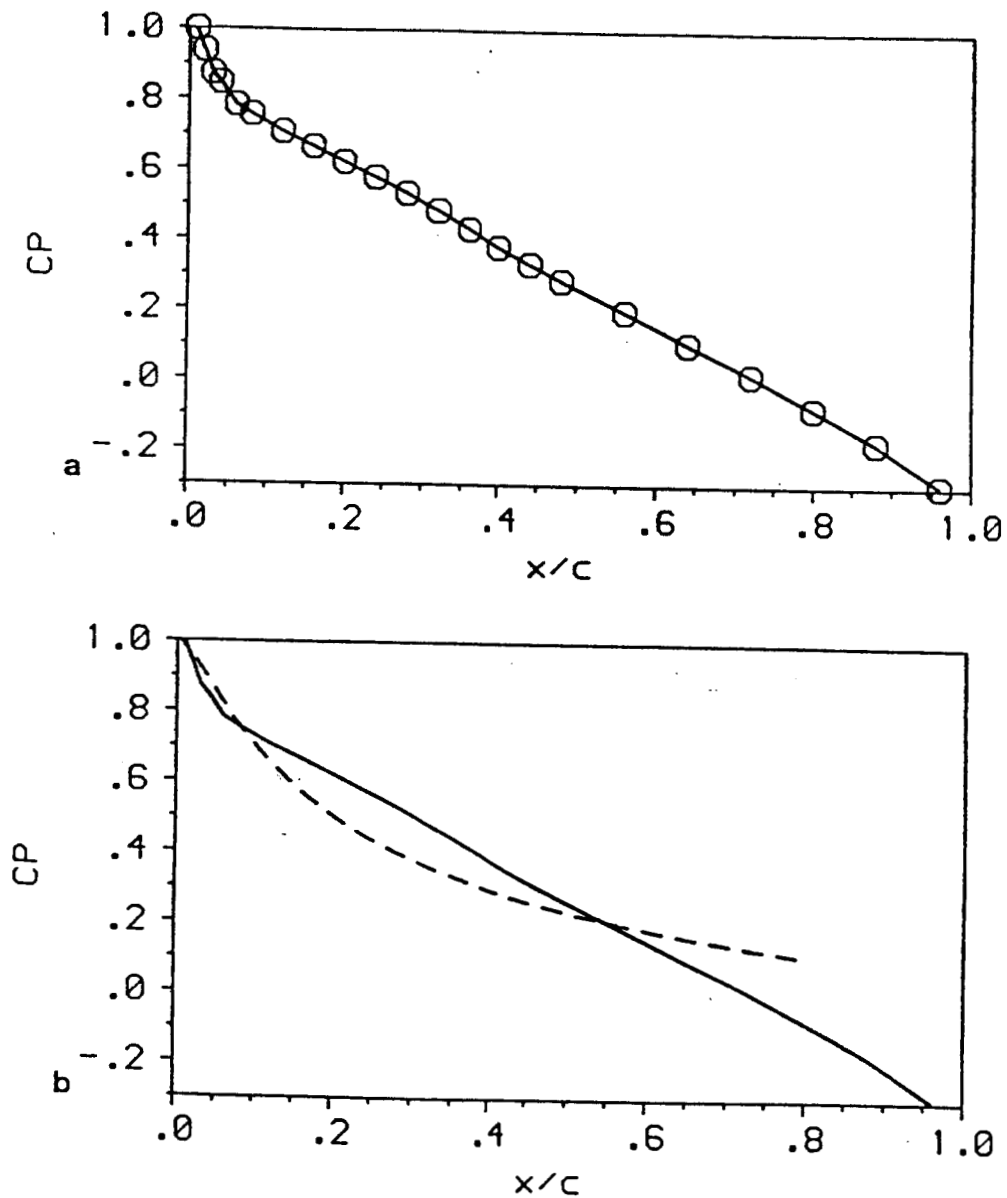


Fig. 3.14: Measured Pressure Progression on the Plate (a)  
Compared with the Pressure Progression on NACA 0010 at  
 $\alpha = 15^\circ$  (b)

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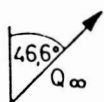


Fig. 3.15: Rendering the Wall Streamlines Visible on the Plate by Means of the Petroleum Painting Method,  $Re = 9.7 \cdot 10^5$   
l:laminar    i:cross flow instability    t:turbulent

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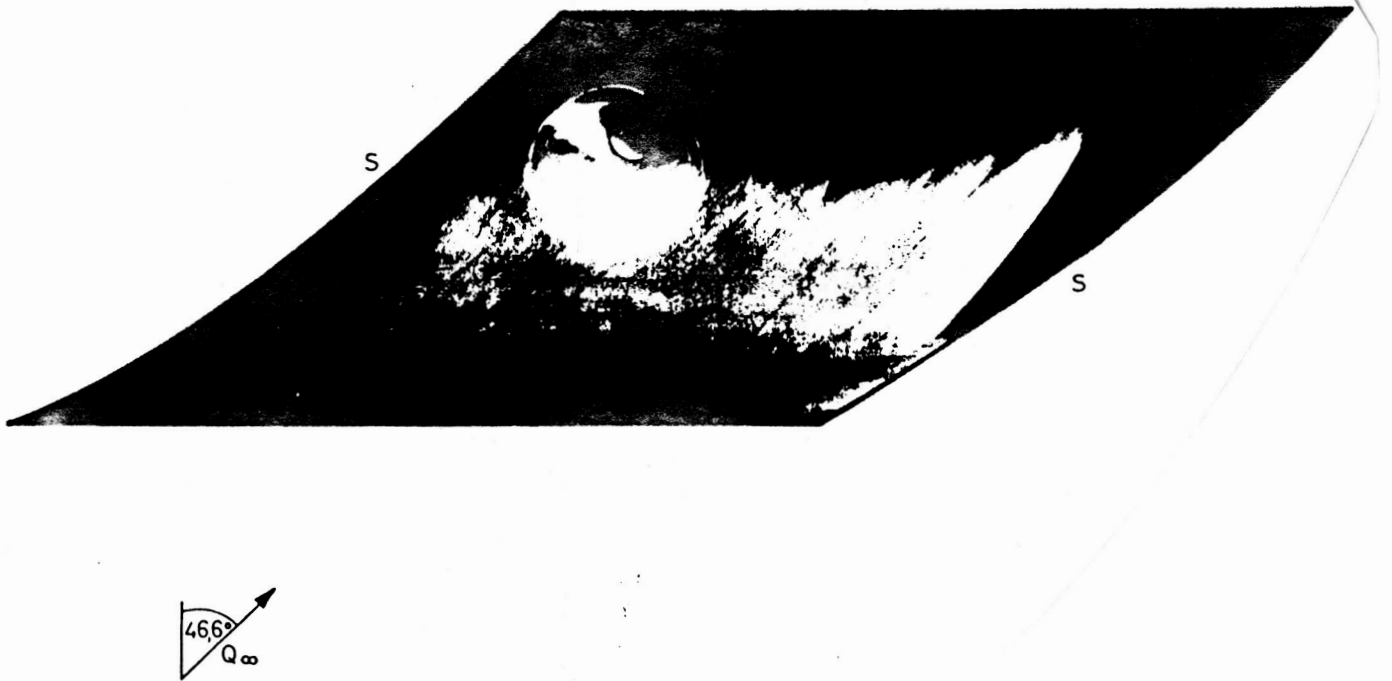


Fig. 3.16: Rendering the Site of Transition to Turbulence and the Stationary Cross Flow Instabilities on the Plate Visible by Means of the Sublimation Method,  $Re = 9.7 \cdot 10^5$



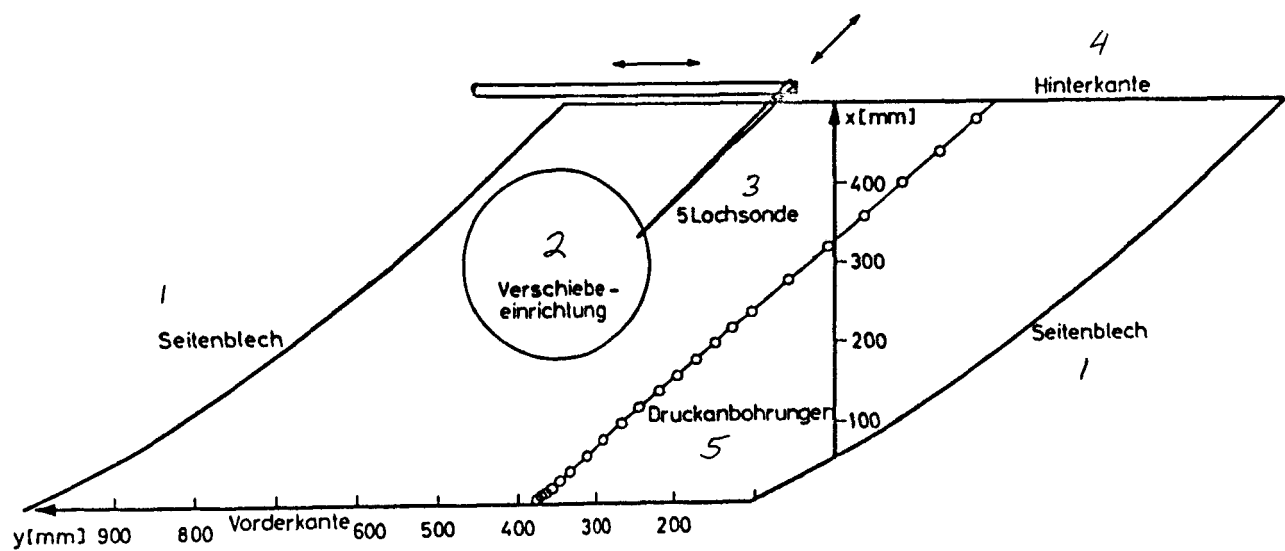


Fig. 3.17: Sketch of the Plate with the Arrangement of the Five-Hole Anemometer in the Measurement of the Velocity Vector at the Edge of the Boundary Layer  
 1: Lateral Plate    2: Sweep Mechanism    3: 5-Hole Probe  
 4: Trailing Edge    5: Pressure Piercings

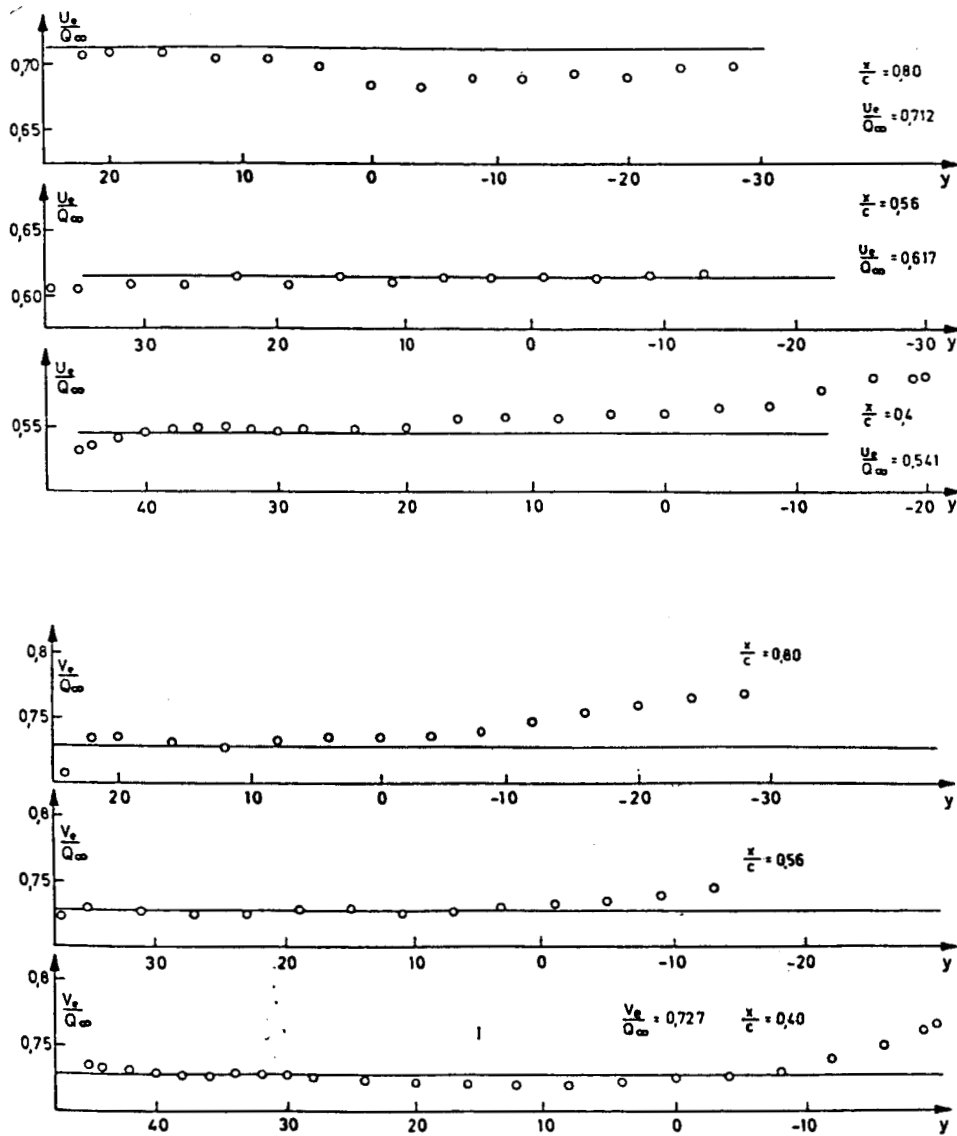


Fig. 3.18: Velocity Components  $U_e$  and  $V_e$  along Lines  $x/c = \text{const.}$ .  
When Compared with the Value Computed from the  
Pressure Progression

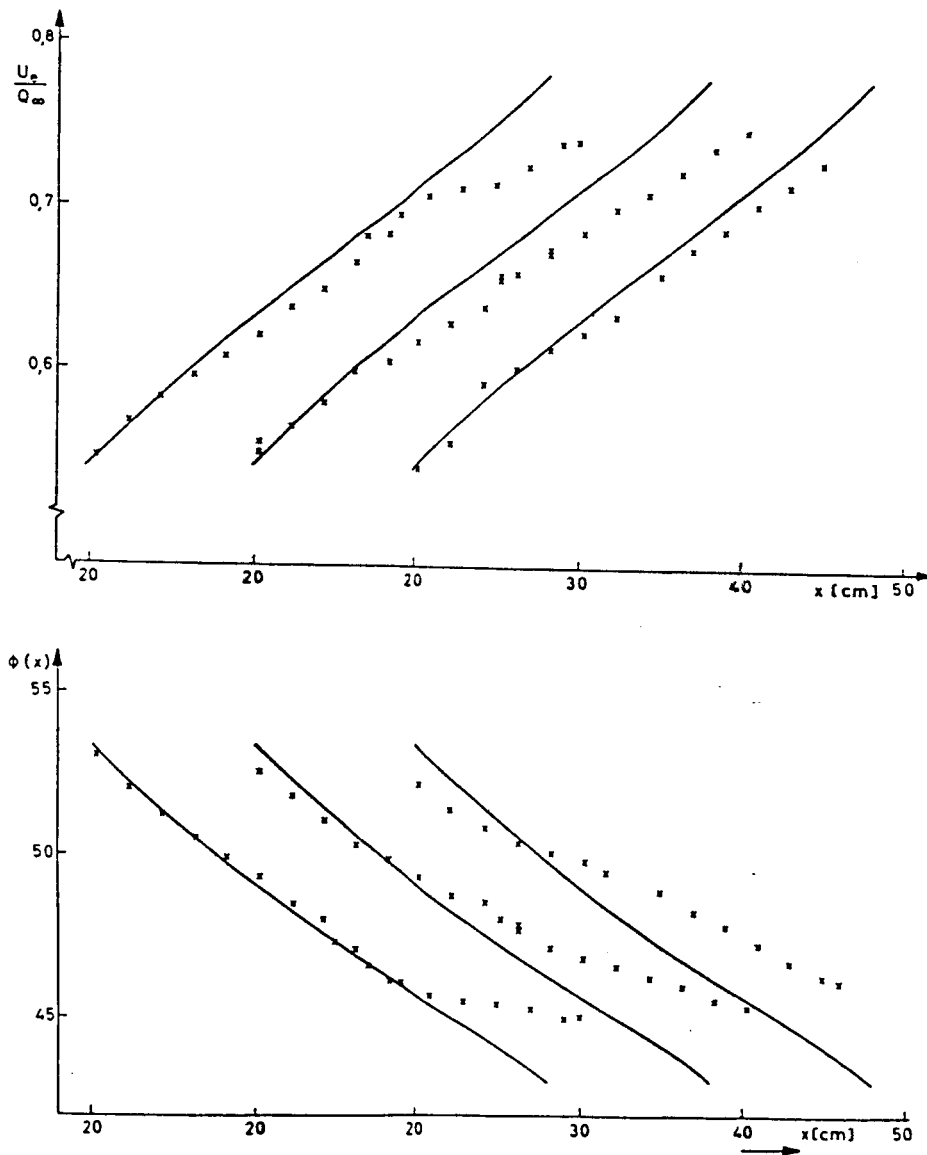


Fig. 3.19: Velocity Components  $U_e$  and Local Sweep Angle  $\phi(x)$  of the Streamline on the Edge of the Boundary Layer along Three Straight Lines with a  $45^\circ$  Angle to the Leading Edge

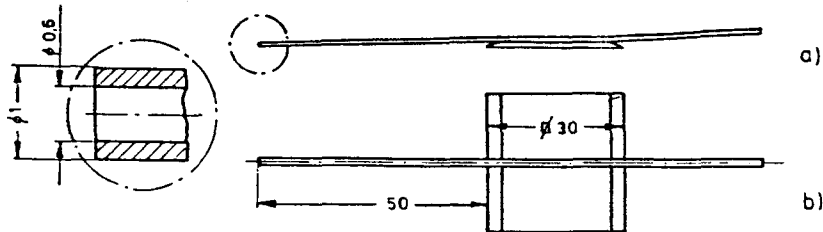


Fig. 3.20a: Diagram of the Preston Tube  
 a) Side View  
 b) Top View

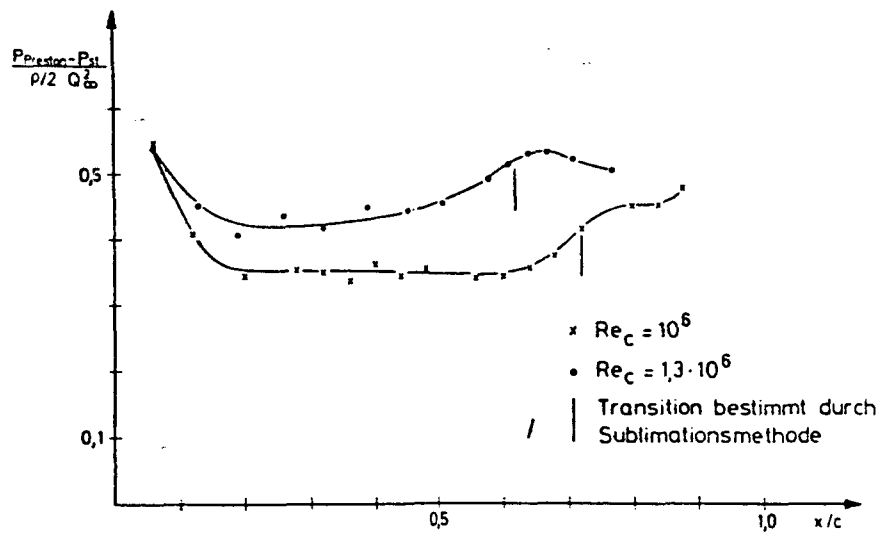
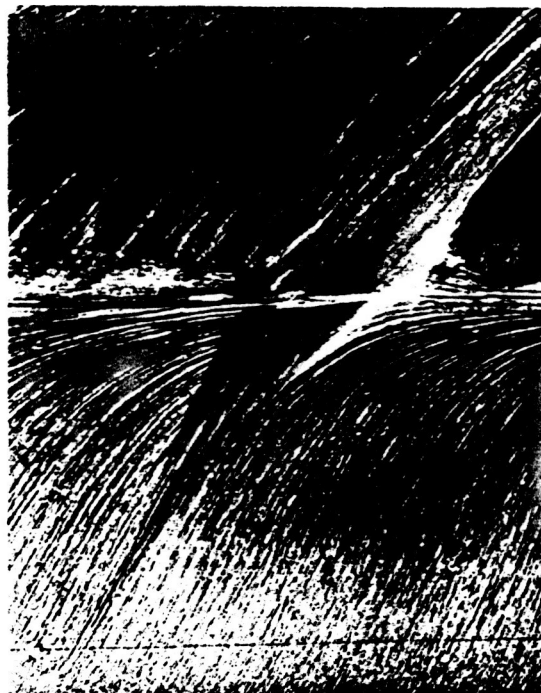


Fig. 3.20b: Measurement of the Preston Pressure along the Plate Depth to Determine Transition  
 l: Transition determined by Sublimation Method

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1: turbulent 1  
2: laminare Ablösung 2  
3: laminar mit einem  
turbulenten Keil 3  
durch eine Störung

Fig. 3.21: A Turbulent Wedge in a Laminar Boundary Layer Made Visible by the Petroleum Painting Method. The separation of the three-dimensional boundary layer is laminar; its touching down again is turbulent. The turbulent wedge causes a break through the separation bubble.  
1: Turbulent 2: Laminar Separation  
3: Laminar with a Turbulent Wedge Due to a Disturbance

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1: turbulent

2: Umschlag

3: laminar

Fig. 3.22: The Laminar-Turbulent Transition Made Visible by the Petroleum Painting Method. Fewer pigment particles are left at the site of transition due to the rapid rise in wall shearing stress. The texture of the petroleum painting picture is finer in the turbulent area than in the laminar area.

1:Turbulent 2:Transition 3:Laminar

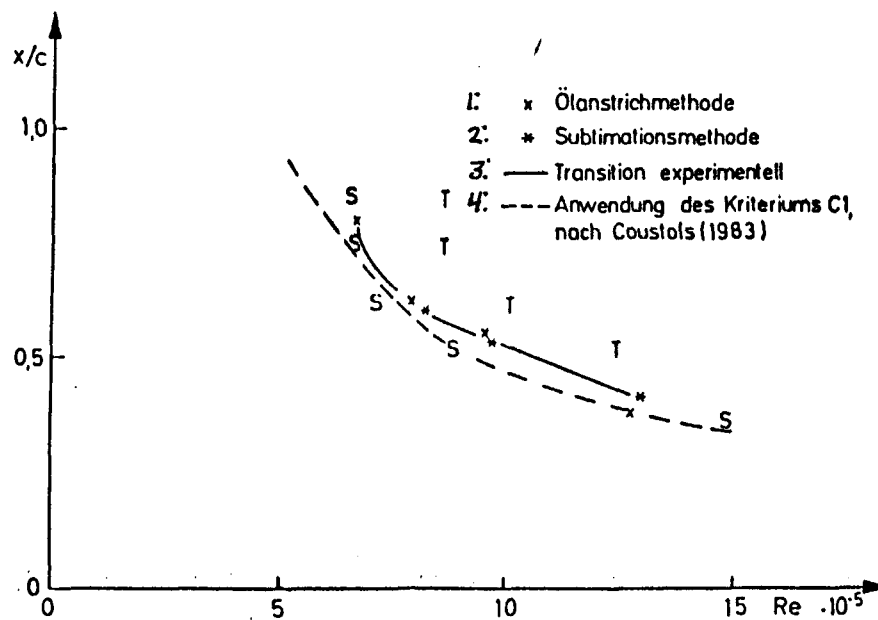


Fig. 3.23: Experimentally Determined Site of Transition to Turbulence Depending on the Reynolds Number Compared to an Empirical Criterion by Coustols (1983)

S: Turbulent Spots in the Hot-Wire Signal

T: Turbulent Hot-Wire Signal

1: Petroleum Painting Method    2: Sublimation Method

3: Experimentally Determined Transition

4: Application of the C1 Criterion by Coustols (1983)

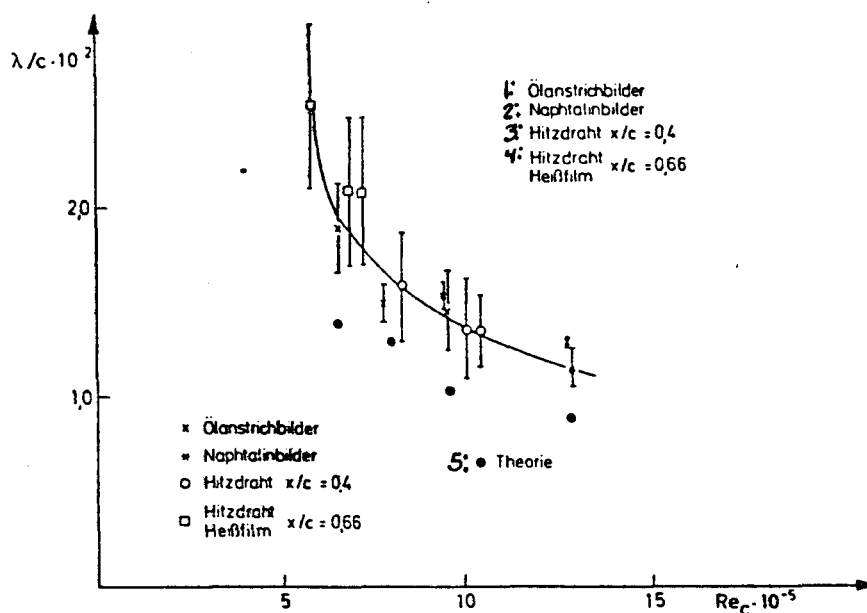


Fig. 3.24: Wavelengths of the Stationary Cross Flow Instability Depending on the Reynolds Number  
 1: Petroleum Painting Pictures    2: Naphthalene Pictures  
 3: Hot Wire  $x/c = 0.4$     4: Hot Wire Hot Film  $x/c = 0.66$   
 5: Theory

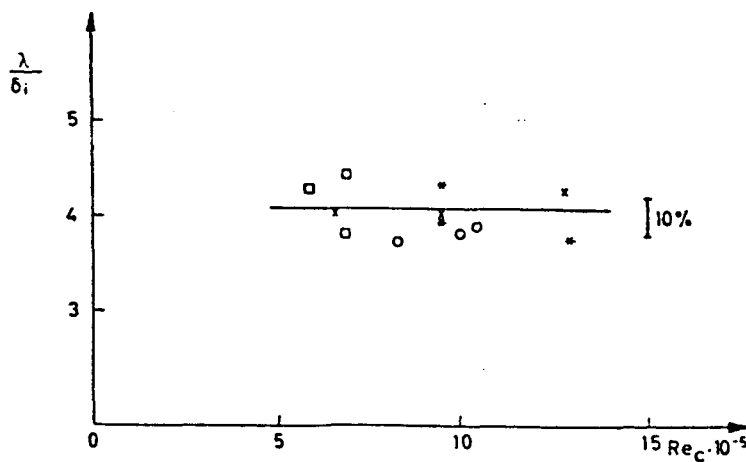


Fig. 3.25: Wavelength of the Stationary Cross Flow Instabilities Normed by the Boundary Layer Thickness at the Site of the Initial Observation



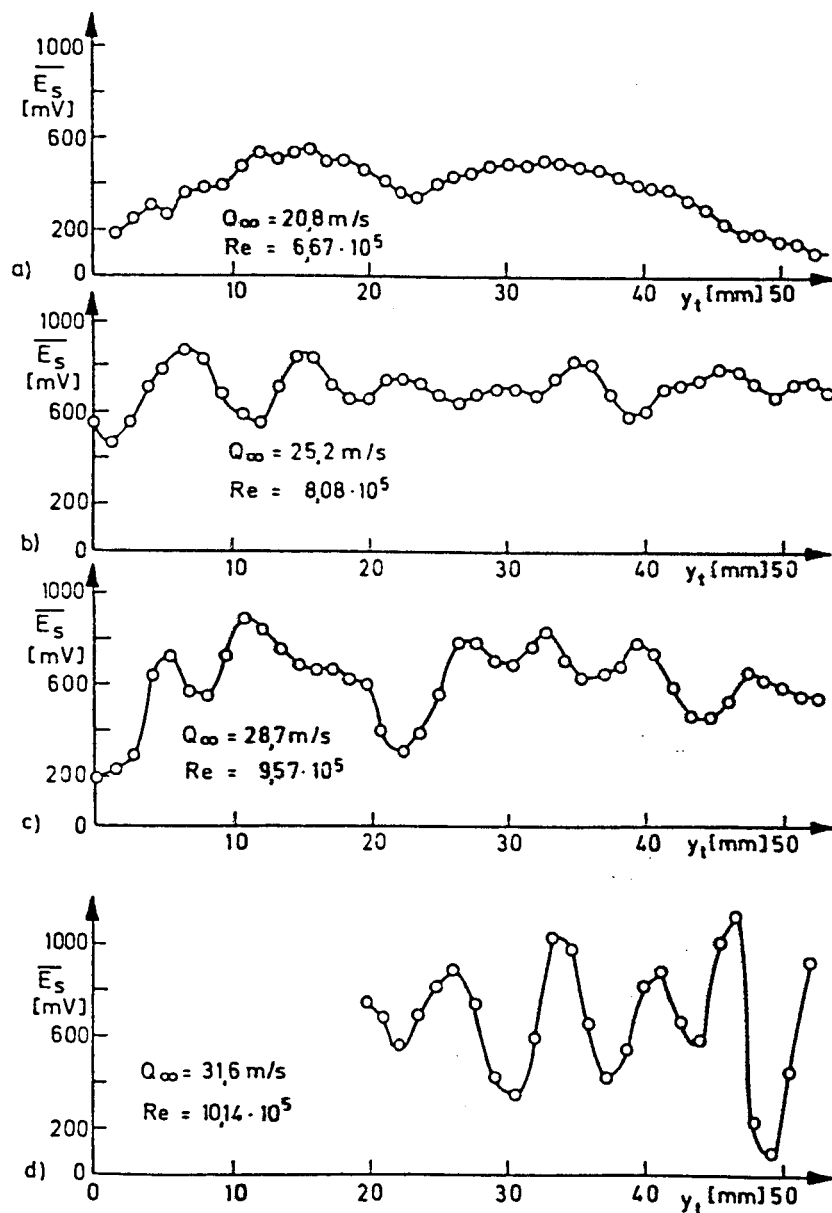


Fig. 3.26: Modulation of the Averaged Velocity and Wall Shearing-stress along  $y$  and  $y_t$  by the Cross Flow Instability, Measured by Hot Wire Anemometer 2

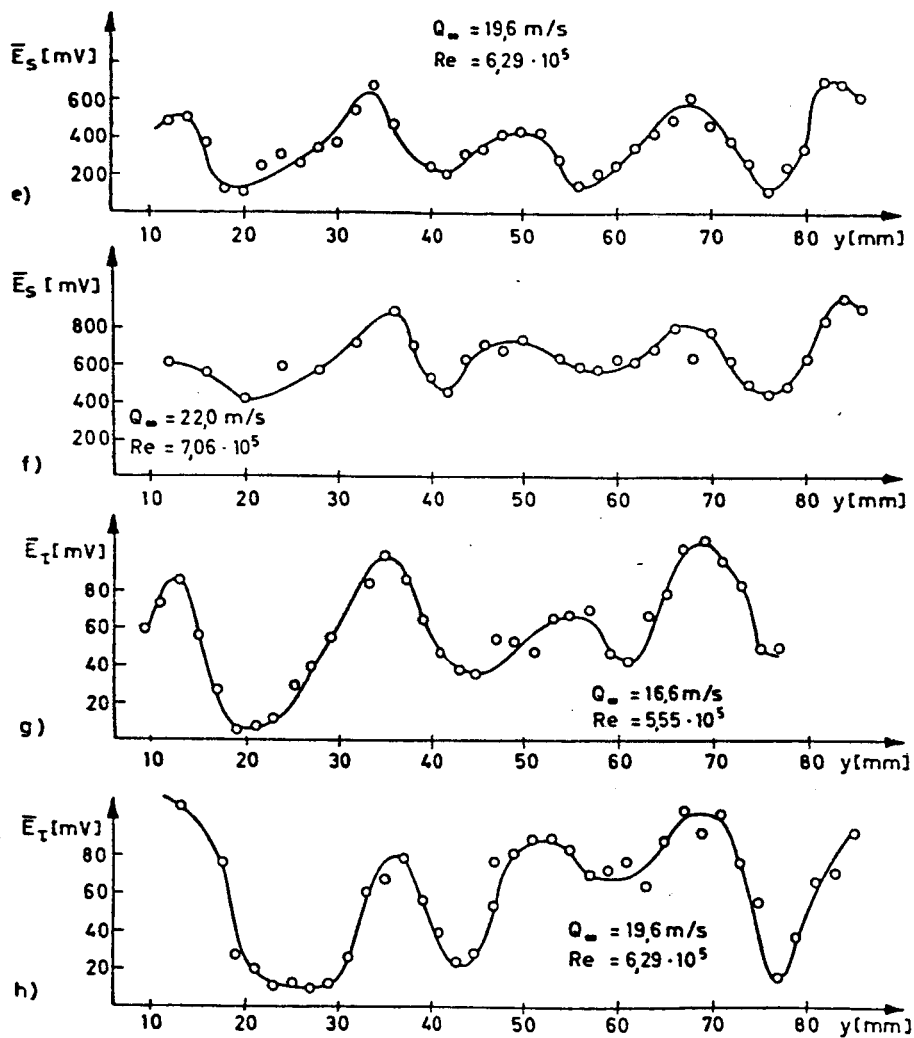


Fig. 3.26: Modulation of the Averaged Velocity ( $\bar{E}_S$ ) and Wall Shearing Stress ( $\bar{E}_T$ ) along  $y$  and  $y_t$  by the Cross Flow Instability, Measured by Hot Wire Anemometer 1 and Hot Film Anemometer 3

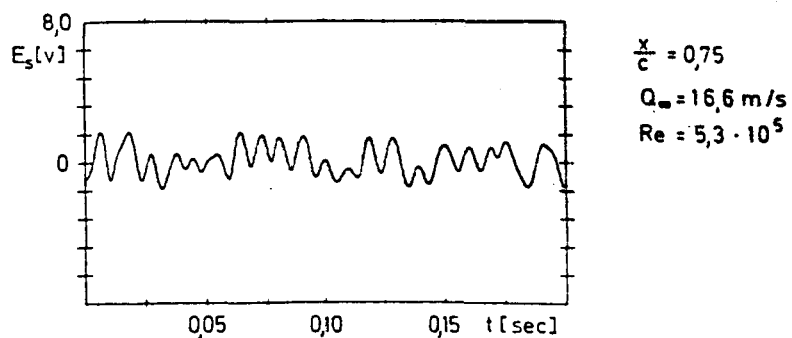
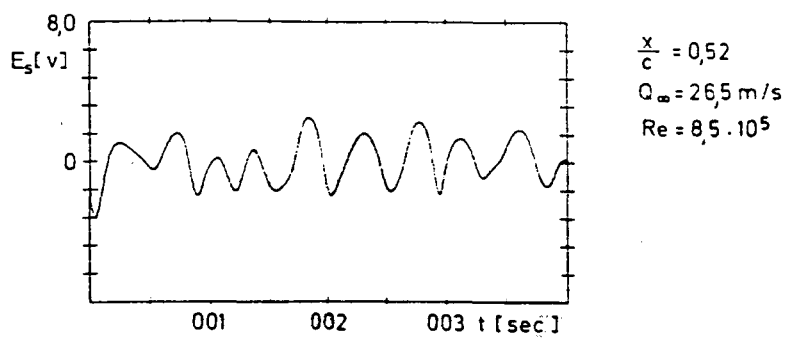
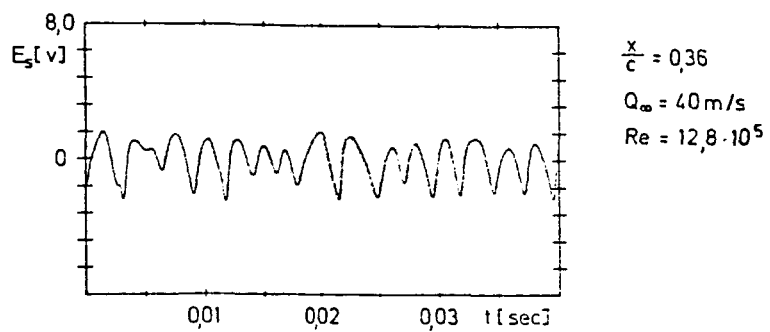


Fig. 3.27: Some Examples of the Hot-Wire Signals of Travelling Waves

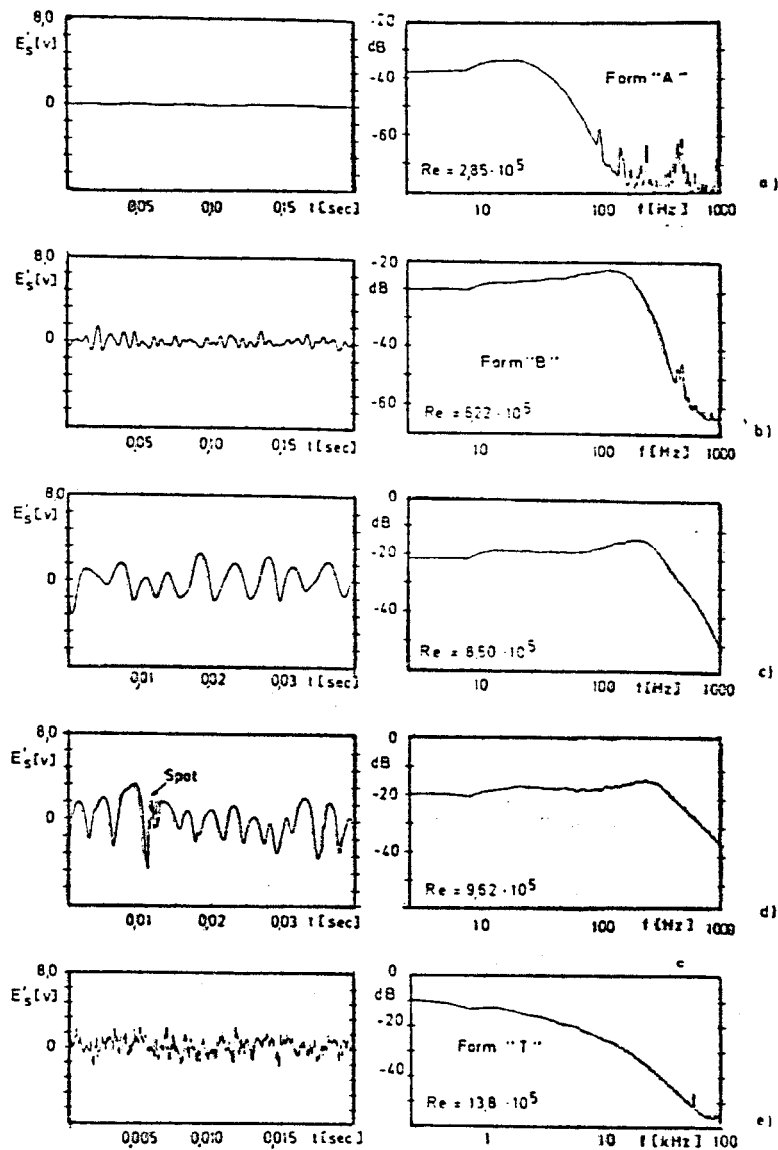


Fig. 3.28: Change in the Hot-Wire Signals of Travelling Waves and of Their Frequency Spectra as Velocity Increases - Ordinates of the Spectra:  $20 \log(E_{RMS}/E_0)$

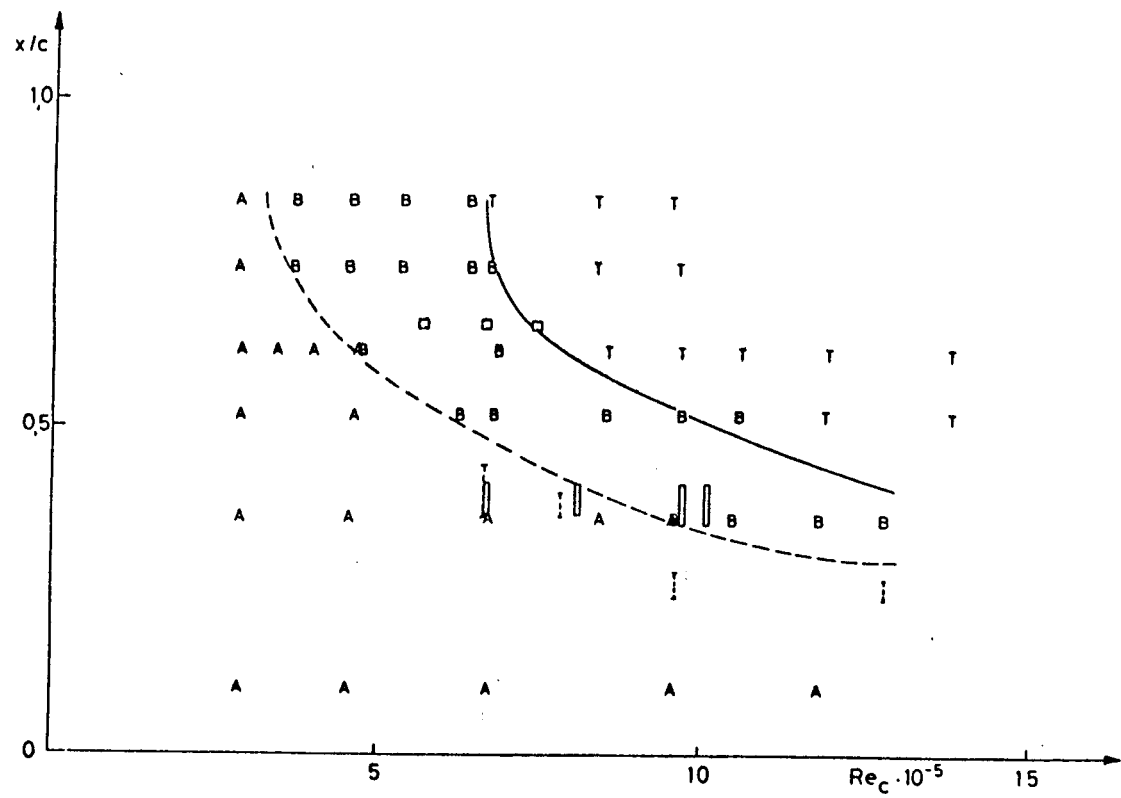


Fig. 3.29: Appearance of Travelling and Standing Waves Depending on the Site  $x/c$  and the Reynolds Number  $Re$ , A: Undisturbed Flow, B: Travelling Waves, ----:  $\chi = 115$ , - - - -: First Appearance of Stationary Cross Flow Instabilities,  $\square$ : Hot-Wire Measurements

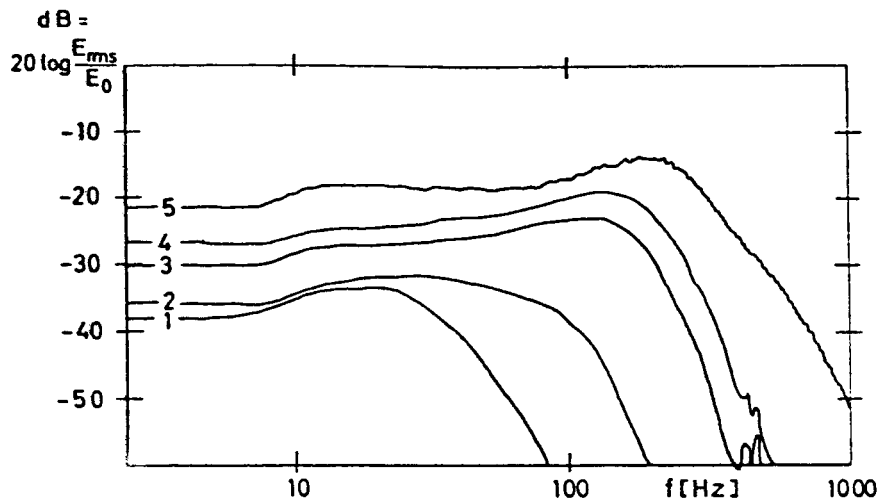


Fig. 3.30a: Change in the Frequency Spectra of the Hot Wire Signals with a Fixed Site  $x/c = 0.52$ , 1:  $Re = 2.85 \cdot 10^5$ , 2:  $Re = 4.59 \cdot 10^5$ , 3:  $Re = 6.22 \cdot 10^5$ , 4:  $Re = 6.74 \cdot 10^5$ , 5:  $Re = 8.50 \cdot 10^5$

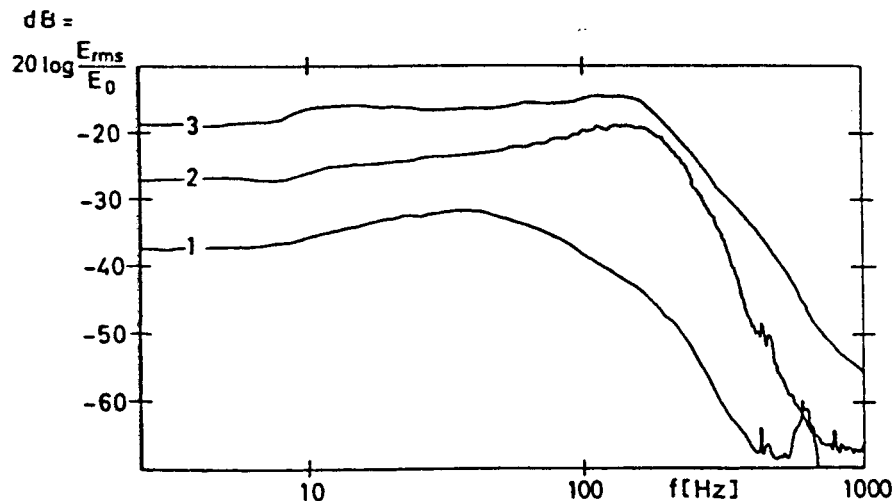


Fig. 3.30b: Change in the Frequency Spectra of the Hot Wire Signals with a Fixed Reynolds Number  $Re = 6.4 \cdot 10^5$ , 1:  $x/c = 0.36$ , 2:  $x/c = 0.52$ , 3:  $x/c = 0.62$

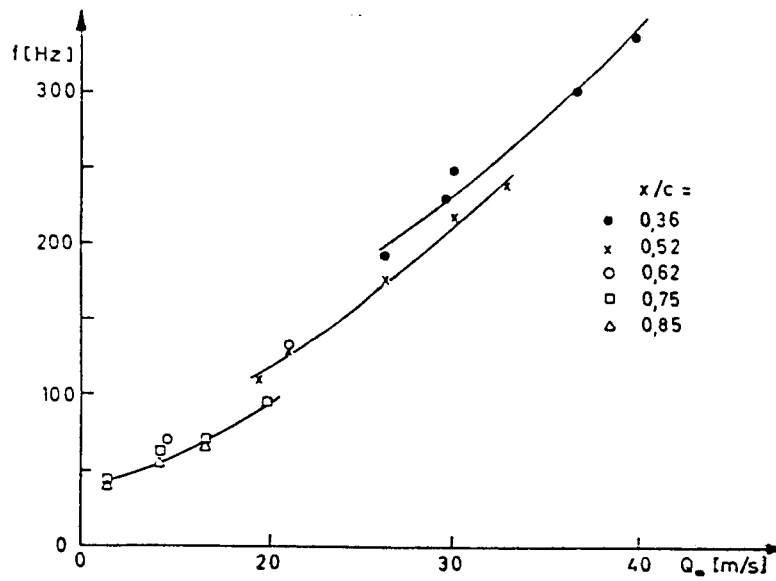


Fig. 3.31: Change in the Frequency of the Maximally Excited Waves with the Site  $x/c$  and the Reynolds Number

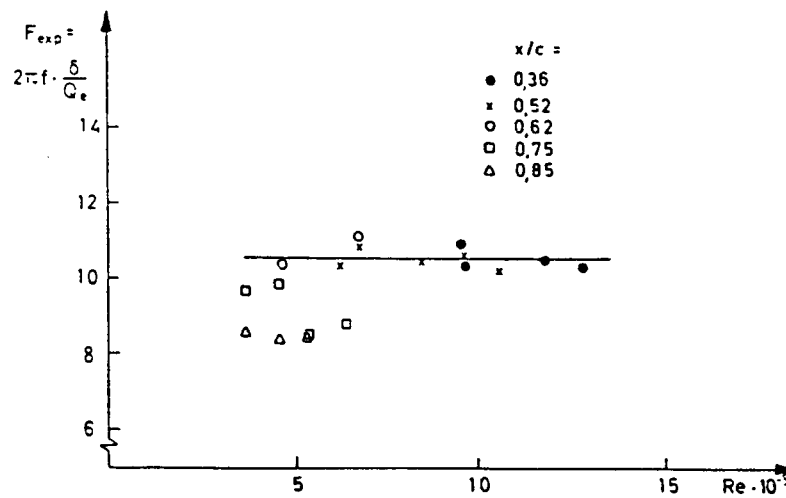


Fig. 3.32: Change in the Frequency of the Maximally Excited Waves Normed by  $\delta/Q_e$

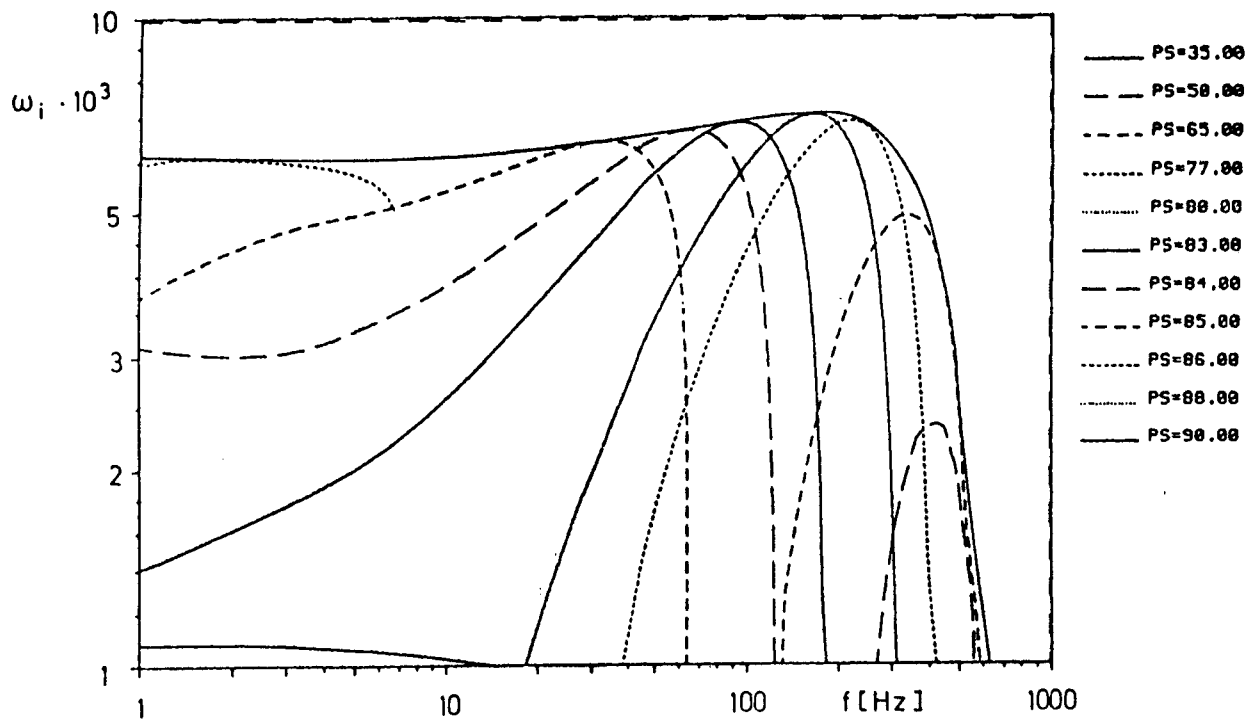


Fig. 3.33: Calculated Non-Dimensional Continuous Excitation of Travelling Waves for Various Propagation Directions  $\psi(\text{PS})$   $x/c = 0.52$ ,  $\text{Re} = 8 \cdot 10^5$



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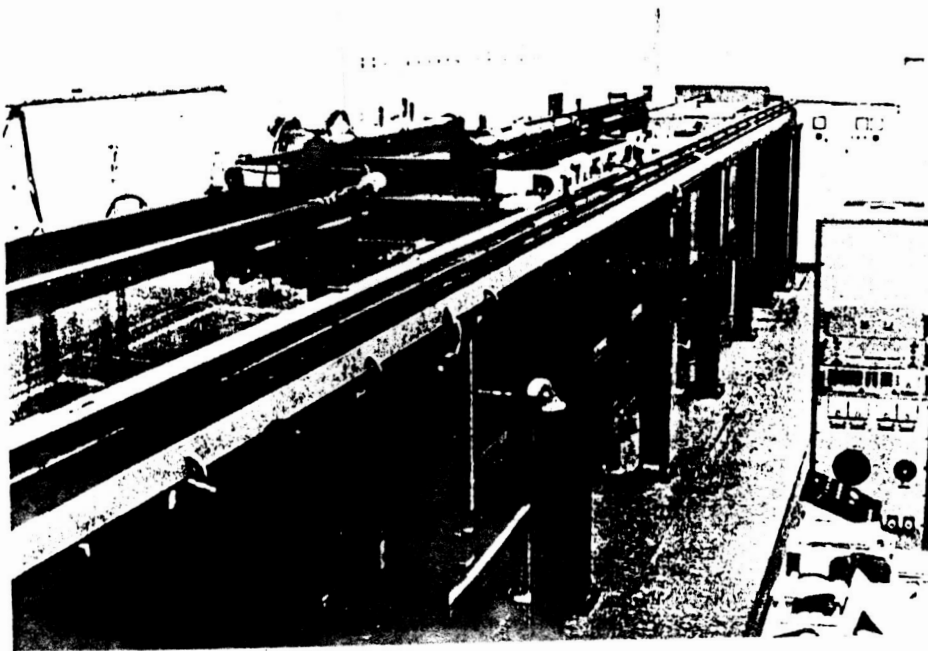


Fig. 4.1: The Model Water Tunnel

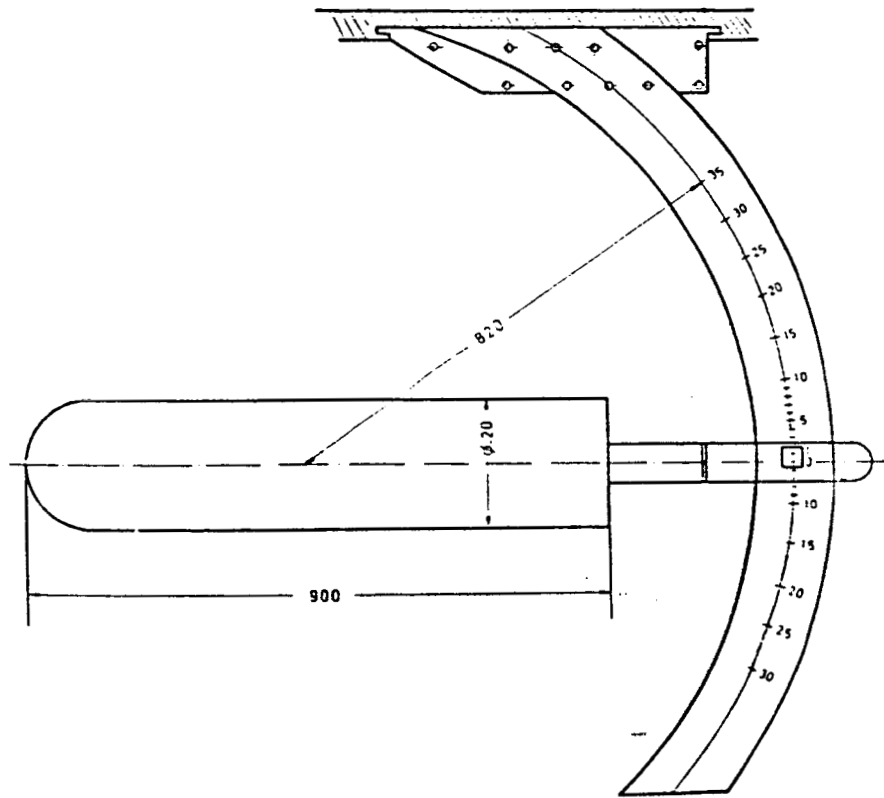


Fig. 4.2: Diagram of the Circular Cylinder with the Mounting

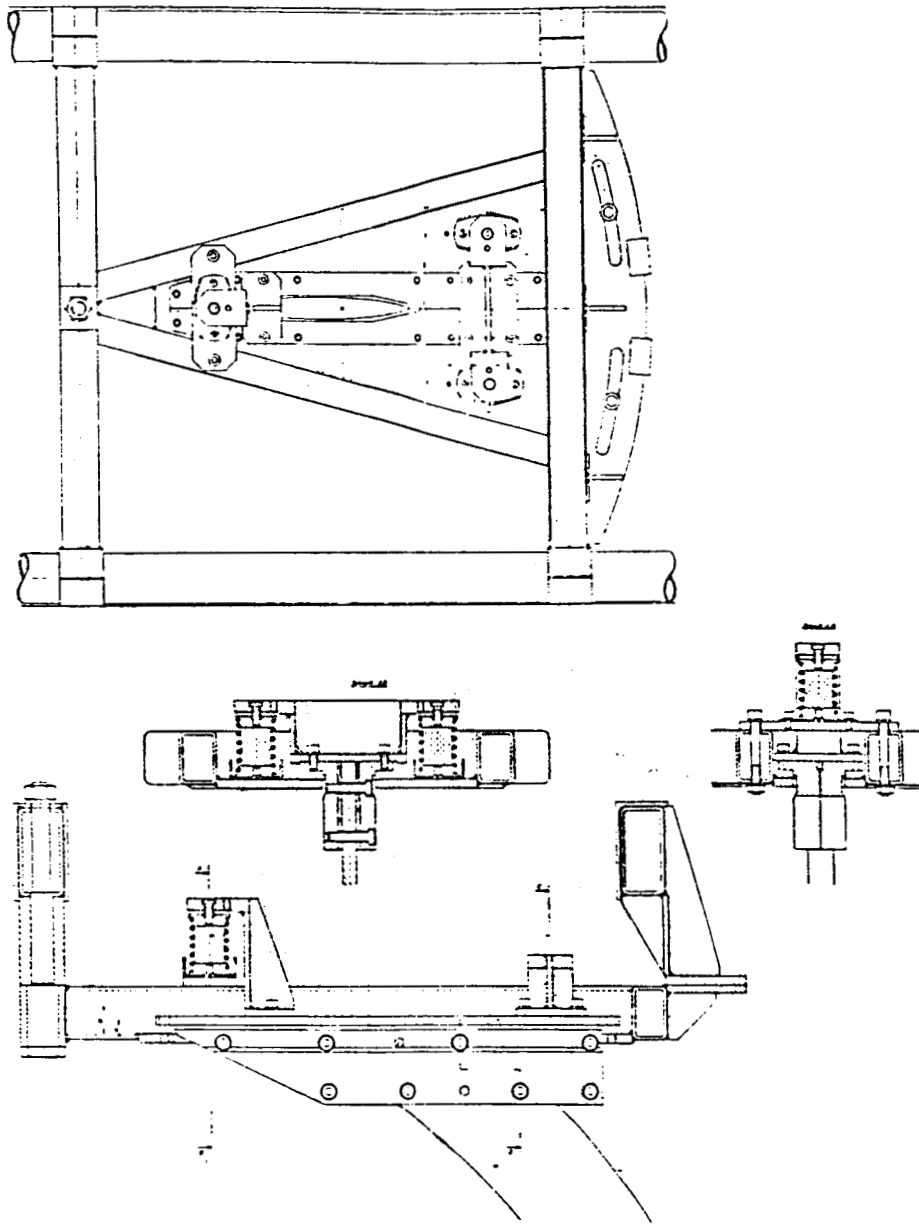


Fig. 4.3: Diagram of the Model's Vibration Insulation



$Re = 2.0 \cdot 10^5$

$Re = 3.0 \cdot 10^5$

$Re = 4.0 \cdot 10^5$

Fig. 4.4: Propagation of Travelling Waves Which Are Caused by a Disturbance of the Boundary Layer (Here: Mounting Pin) in the Stagnation Area, with Growing Reynolds Number and  $\phi_0 = 70^\circ$  B: Bubble Wire H: Bubble Wire's Mounting Pins K: Cable Inside Model

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Fig. 4.5: Growth of a Turbulent Wedge and Travelling Waves Due to Disturbance S of the Boundary Layer in the Stagnation Area  $Re = 3 \cdot 10^5$ ,  $\phi_0 = 55^\circ$

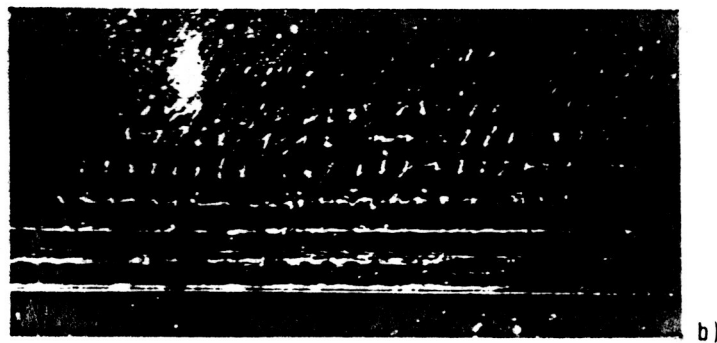
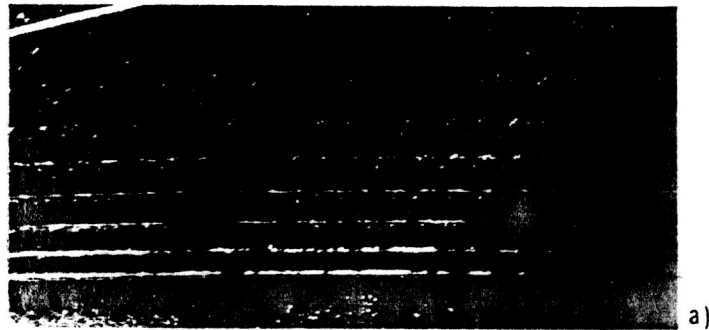
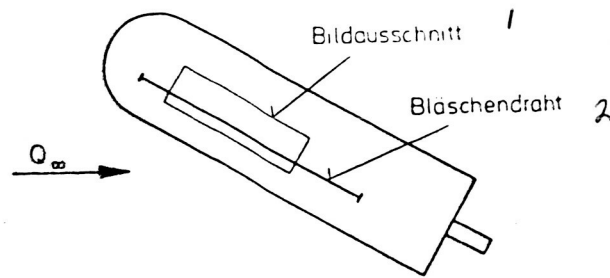


Fig. 4.6: Cross Flow Instability in the Boundary Layer Made Visible by Time Lines  
a)  $Re = 3.0 \cdot 10^5$ ,  $\phi_0 = 60^\circ$ ,  $Y = 40^\circ$   
b)  $Re = 3.5 \cdot 10^5$ ,  $\phi_0 = 65^\circ$ ,  $Y = 60^\circ$   
1:Detail 2:Bubble Wire

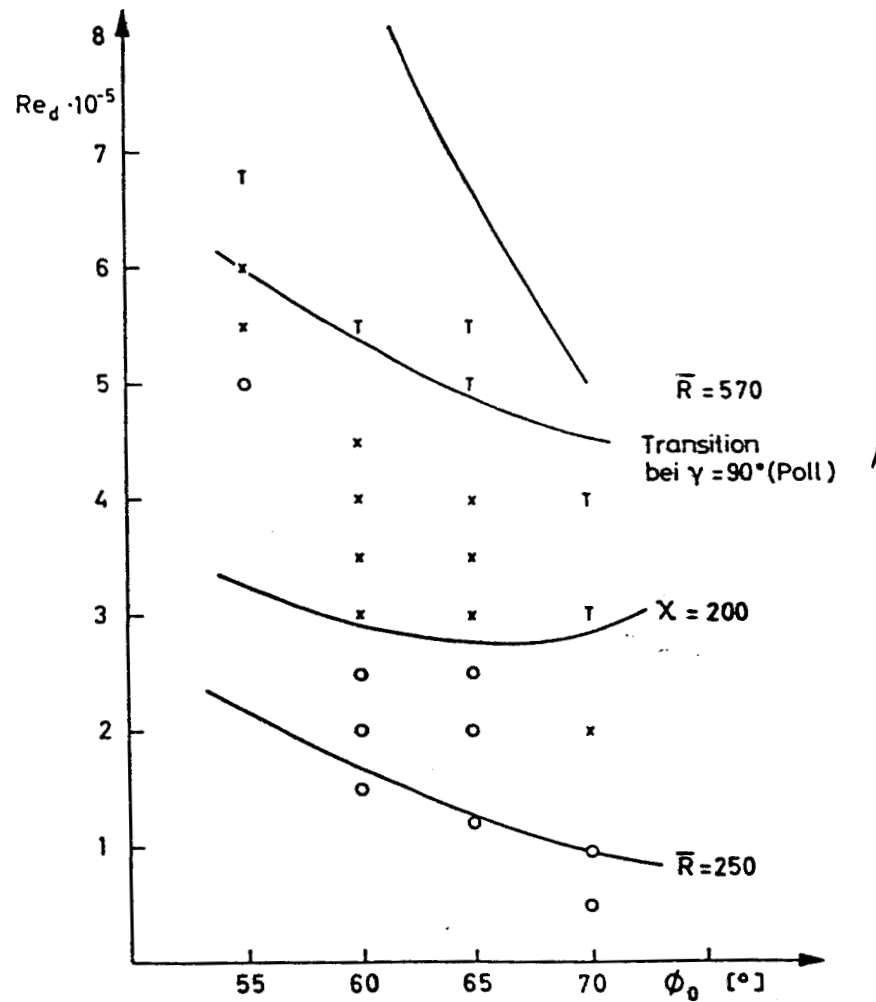


Fig. 4.7: Appearance of Cross Flow Instabilities and Transition Depending on the Reynolds Number and the Sweep Angle  
 1: Transition with  $\gamma = 90^\circ$  (Poll)

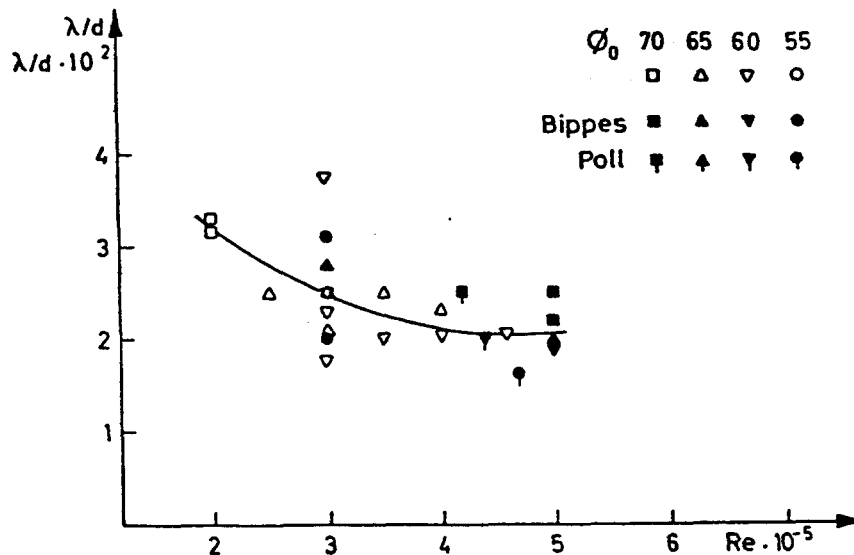


Fig. 4.8: Wavelength of the Cross Flow Instability Depending on the Reynolds Number

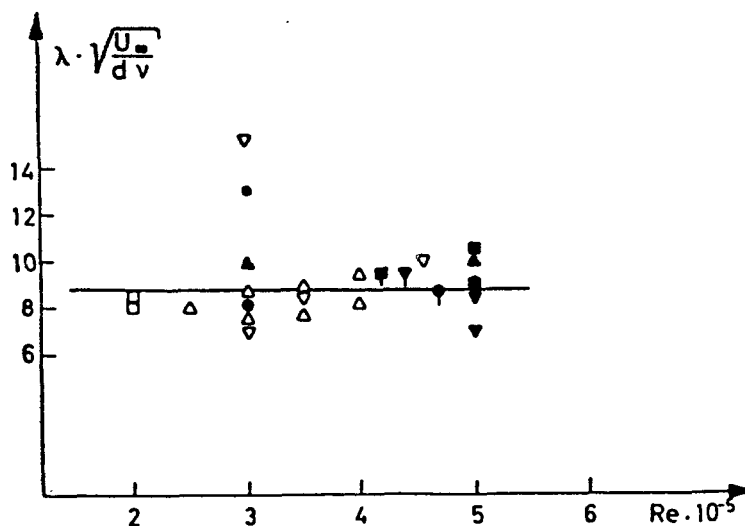
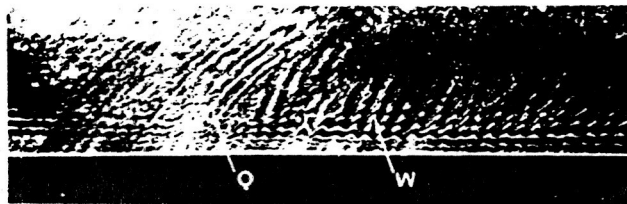
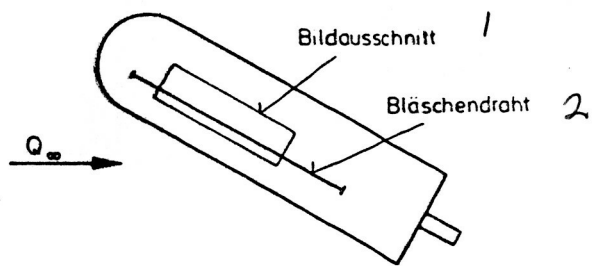
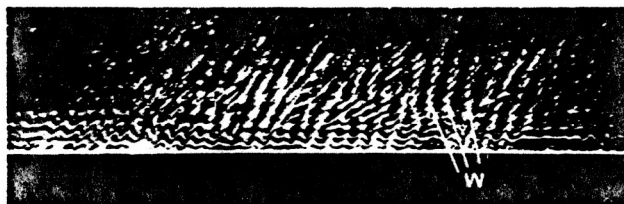


Fig. 4.9: Wavelength of the Cross Flow Instabilities Normed by Depending on the Reynolds Number  $\eta = \sqrt{d \nu / U_m}$

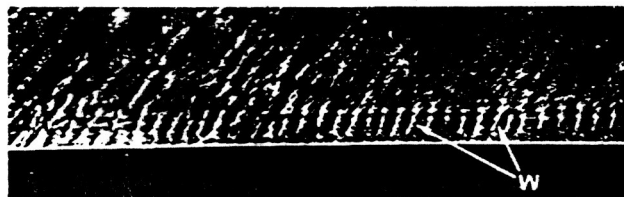




Re =  $4,5 \cdot 10^5$   
a)  $\gamma = 90^\circ$



Re =  $5,0 \cdot 10^5$   
b)  $\gamma = 80^\circ$



Re =  $5,5 \cdot 10^5$   
c)  $\gamma = 60^\circ$

Fig. 4.10: Visualization of Cross Flow Instabilities Q and Travelling Waves W in the Boundary Layer Shortly before the Laminar-Turbulent Transition  
1:Detail 2:Bubble Wire

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