NASA Contractor **Report** ¹⁷⁸³²⁸

PLATES AND SHELLS CONTAINING A SURFACE CRACK UNDER GENERAL LOADING CONDITIONS

Paul F. Joseph and Fazil Erdogan

LEHIGH UNIVERSITY Bethlehem, Pennsylvania

Grant NAG1-713 July 1987

N87-2E **1E3** $(NASA-CR-178328)$ **FIATES AND SEELLS CCNTAINING A SURFACE CRACK UNDER GENERAL** LCADING CCNDITICNS (lehigh Univ.) 391 p
Avail: NTIS BC A17/MF A01 CSCL 11D Unclas Avail: NTIS **HC** A¹⁷/BP A01 0087864 G3/24

NAS National Aeronautics and

Space Administration

Langley Research Center Hampton, Virginia 23665

CONTENTS

n.

Î

APPENDICES

 $\ddot{}$

a.

LIST OF TABLES

iv

 $\label{eq:2.1} \frac{1}{\sqrt{2}}\int_{0}^{\infty}\frac{dx}{\sqrt{2\pi}}\left(\frac{dx}{\sqrt{2\pi}}\right)^{2}dx\leq \frac{1}{2}\int_{0}^{\infty}\frac{dx}{\sqrt{2\pi}}\left(\frac{dx}{\sqrt{2\pi}}\right)^{2}dx.$

v

 $\label{eq:2.1} \frac{1}{\sqrt{2}}\left(\frac{1}{\sqrt{2}}\right)^{2} \left(\frac{1}{\sqrt{2}}\right)^{2} \left(\$

LIST OF FIGURES

vi

- Figure 3.9a,b Stresses in front of the crack tip resulting 83,84 from out-of-plane shear loading (a), and from twisting (b). $\nu = .3$
- Figures 4.1-4 Comparison of mode 1 line-spring model with and without transverse shear deformation to Newman'sand **Raju's** finite element solution. 153-156
- Figure **4.5** Geometry of the bending **contact** problem. ¹⁵⁷
- **Figure 4.6** Line-spring model approximation to the stress intensity factor at the corner of a rectangular surface crack. 158
- Figure 4.7 Line-spring model approximation to the stress 159 intensity factor at the corner of 1/4 power "semi-elliptical" surface crack.
- **Figure 4.8** Line-spring model approximation to the stress 160 intensity factor at the corner of a *through* crack subjected to bending allowing for contact stresses as compared to the **value** assuming no contact.
- Figure 4.9 The LSM approximation to the stress intensity 161 factor at the corner of a semi-elliptical surface crack.
- Figures **4.10- Normalized** stress intensity factor **profiles** 162-167 4.15 for the mode 2,3 line-spring model for rectangular and semi-elliptical surface cracks subjected to out-of-plane shear, in-plane shear and twisting.
- Figures 5.1-4 Stresses ahead of a crack in a cylinder subjected to membrane and bending loads. 205-208
- Figures 5.5,6 Out-of-plane displacement $w(0^+, y)$ as measured 209,210 from y=O in the deformed position for a cylinder with a through crack.
- Figures 6.1,2 **Comparison** of the mode 1LSM with **results** from 265,266 **Refs.** [33,40] for the normalized SIF along an axial, internal, semi-elliptical surface crack in a pressurized cylinder.
- Figures **6.3,4** Out-of-plane **displacement** w(O÷,y) as measured 267,268 from y=O in the deformed position for a cylinder with a surface crack.

Figure 6.5 The geometry of the toroidal shell. 269

Ġ,

ABSTRACT

In this study **various** through and part-through crack **problems** in plates **and** shells **are** considered. The line-spring model of Rice and Levy is generalized to the skew-symmetric case to solve surface crack problems involving mixed-mode, coplanar crack growth. **New** compliance functions **are** introduced which are **valid** for crack depth to thickness ratios **at** least up to .95. This includes expressions for tension and bending **originally** used by the model for symmetric loading as well **as** new expressions for in-plane shear, out-of-plane shear, and twisting for the skew-symmetric case. Transverse shear deformation is taken into **account** in the plate and shell theories and this effect is shown to be important in comparing stress intensity factors obtained from the plate theory with three-dimensional surface crack solutions. Stress intensity factor results for cylinders obtained by the linespring model also compare well with the three-dimensional solutions.

By using the line-spring approach, **for** a given crack length to *thickness* ratio, stress intensity factors can be obtained for the *through* crack **and** for part-through cracks of **any** crack front shape, without need for recalculating integrals that take up the bulk of the computer time. Therefore, parameter studies involving crack length, crack depth, shell *type,* and shell curvature are made in some detail. The results presented are believed to be useful in brittle fracture, and more **importantly,** in fatigue crack propagation studies.

The line-spring model is also **used** to solve the contact problem in plate bending. Investigations into stress intensity factors fo

crack growth in the length direction (as opposed to growth in the thickness direction), **are also** made by using the model. The **endpoint** behavior of the results given by the line-spring model is **considered** in detail.

In addition to part-through **crack** problems, some results **for** single **and** double through **cracks are** presented. The thin plate bending limit of Reissner's theory **and** its relationship to the **classical** theory **are** reconsidered.

All problems **considered** in this study are of the mixed boundary value type **and are** reduced to strongly singular integral **equations which** make use **of the finite-part integrals of Hadamard.** These **equations are** obtained by using displacement quantities **as** the unknowns, rather than the more **commonly** used displacement derivatives which **lead** to integral equations **with** Cauchy singularities. The equations **are** solved numerically in **a** manner that is believed to be very efficient.

CHAPTER₁

Introduction, Literature Survey **and** Overview

1.1 Introduction

Pressure vessels, pipelines, containers, ship hulls, **etc. are all** shell-like structures which **can fail** by **fracture.** The designers of these **components** must **take this** into **account as** such failures **are** often **catastrophic, endangering lives and** the **environment.** The **fracture** process typically starts **with a** small material defect or **weld** imperfection that grows **in fatigue which** is driven by mechanical or **environmental conditions.** Eventually the flaw may be **charactcrized as a** macroscopic surface **crack.** This surface or part-through **crack** then **continues** its growth **through** the thickness, leading to failure by **leaking** or to unstable fracture.

In the discipline of **fracture** mechanics one usually **assumes an** initial **flaw configuration, and** then seeks to obtain **certain** fracture \mathbf{r} parameters that are believed to govern the tendency of the **crack** to grow. In the **case** of brittle **fractures** and more importantly, **fractures** by **fatigue,** the stress **intensity factor** (SIF) **is** the most **commonly** used parameter.

The **analysis** of through **cracks** in thin structures was **first** performed **within** the theory of plates **and** shells, **which allows for a** straightforward **analytical** solution **for** practical geometries such as **cylinders,** spheres, and pipe **elbows.** The problem **is** of the mixed boundary value type and is reduced to **a** system of dual integral **equations** or **a** system of singular integral **equations** (SIE), most often

the latter. It is **usually assumed** that the **curvatures** are **constant** and the shell has constant thickness, the material is homogeneous, isotropic, or perhaps specially orthotropic, and behaves in a linear elastic manner. Three-dimensional effects due to the interaction between the free surface and the crack plane are neglected. Benthem [1] has investigated these effects for a crack in a half space. To date no research has included this surface layer behavior in a problem with **a** practical geometry.

The surface crack has **a** three-dimensional geometry which seems **accessible** only to either **analytical** or numerical techniques from the theory of elasticity. Rice in 1972 [2,3] introduced the so-called line-spring ,model (LSM) which transformed the part-through crack into a through crack problem by making use of the edge-cracked strip plane strain solution. This model has been shown to give very good results in spite of its simplicity. Therefore, within the limitations of this model, both through and part-through crack problems can be solved with the same plate or shell theory formulation.

It is important to point out that for a through crack the primary interest is in the behavior of the stress state **at and** near the crack tip. Whereas, **for** surface cracks the most important point is the deepest penetration point of the crack front. The model in its original form is limited to symmetric (mode 1) fracture, **and** cannot predict behavior **at** the endpoint where the crack front meets the free surface (again neglecting the free surface effect).

1.2 Literature Survey

The problem of determining the singular stress **field** in **an** infinitely large plate of thickness h, containing a finite crack of half-length **a,** subjected to tension was studied by Williams [4] in 1957. a 1960 paper [5] Williams also investigated the problem of plate bending by using the classical plate theory. Although in the bending problem the stress singularity was observed to be the same **as** in the plane elasticity case, (namely r-l/2), the **angular** variation of the stresses around the crack tip was found to be different. Shortly **after** this paper was published, Knowles and Wang [6] showed that this discrepancy could be removed if the 6th order Reissner plate theory [7,8], which includes transverse shear deformation, was used. This theory allows **for** the satisfaction of all three crack surface boundary conditions $(M_{xy}=0, V_x=0, N_{xy}=0)$, instead of combining these three conditions into two as did the previous theory by use of the Kirchhoff 9N condition, $(N_{xy}=0, V_x + \frac{\Delta T}{\partial y} = 0)$. The work of Knowles and Wang was **later made more** complete by **Hartranft and Sih** [9] and by **Wang** [10]. In these papers the SIF solution is given for various crack length to plate **thickness** ratios, i.e. (a/h).

In the **paper** by Knowles **and** Wang it was observed that Reissner's theory approaches classical theory in the limit **as** h/a*O, or **as** the plate gets thin. This limit is well behaved except **at** the crack tip **where** boundary layer behavior in the SIF is indicated by graphical solutions $[9,10]$. This "discontinuous" behavior was discussed by **Civelek** and Erdogan [11] with the aid of more complete and more precise numerical results, but not proven. Also it was pointed out by Hartranft [12] that this limit should not be used. For **more** discussion of this problem see Sih [13].

In all **of** the preceeding papers the solution was limited to symmetric (mode 1) loading, which includes tension and bending. Wang in 1970 [14] was the first to consider twisting, again with **Reissner's** plate theory. The **asymptotic stress field** was shown to be compatible with 2-D elasticity, therefore mode 2 and 3 SIFs had the same This problem is not approachable by the classical theory for the same reasons that apply to plate bending. The results of Wang [14] were extended by **Delale** and Erdogan [15] to include specially orthotropic **materials. elasticity**

The first analysis **of** cracks in shells was presented by Folias in **1965** for **a** cracked **sphere** [16,17] **and for an axially** cracked **cylinder** [18]. The circumferentially cracked cylinder was investigated in 1967 [19]. The results in these papers **are asymptotic** in nature for short cracks. A shallow shell *theory* was **also** used which linearlzes the governing equations. The full curvature problem is non-linear **and** has not yet been solved by analytical techniques although Sanders [20,21] has used a thin shell theory which is linear yet valid for **a** complete cylinder to obtain energy release rates (not SIFs) **for** long cracks. The validity of shallow shell analysis can be summarized **as** follows: for a given shell radius, the smaller the thickness h, the more appropriate the shell assumption; the shorter the crack length 2a, the more appropriate the shallow shell assumption.

In *the* late 1960's Erdogan and K_bler [22] and **Copley and** Sanders [23] provided a *more* complete solution to the problems studied by

Folias. employed, the numerical techniques for the solution of the singu integral equations are exact (to any reasonable specified degree of accuracy). Although the same approximate, shallow shell **equations** are

The major shortcoming of these early shell solutions, including the **work** of Sanders [20-21], **was** the neglect of transverse shear deformation **as** in the **early** plate bending problem. In shells, since **extension and** bending **are coupled,** the **elasticity concept** of the SIF **cannot** be used **with these 8th** order theories **without** redefinition. As bending becomes more of **a** factor in the geometry **and loading considered,** the results become **less accurate.** Also the **contribution from extension** is **affected.** It was Sih **and** Hagendorf **[24]** in 1974 **who** first solved **cracked** shell problems with transverse shear accounted **for;** see **also a** second paper by Sih [25]. Later papers, **which** used the shallow shell governing **equations** due to Naghdi [26], provided **more** exact and extensive results for the __xia!ly **cracked cylinder,** see Krenk [27], and for the circumferentially cracked cylinder, see Delale and Erdogan [28]. It was shown in these papers that the asymptotic stress field obtained is compatible with the solution from the theory of elastic fracture mechanics; therefore standard fracture parameters such as the SIF could be used. The skew-symmetric shell problem **was** studied by Delale [29] and it **was** shown that the mode 2 and 3 stress intensity factors also have the same elasticity definition. Therefore it appears that the simplest shell theory that may be used to stud cracks in plates and shells to obtain SIFs is one-that inclutransverse shear deformation, [7,8,26]. In 1983 Yashi and Erdogan

[30] solved the shallow shell problem for a **crack** arbitrarily oriented **with** respect to a principal line of curvature. They used the same formulation as **was** used by Delale and Erdogan [28], but the analysis involved ten unknowns instead of two [28] or three [29] because of the loss of symmetry.

In all the previous shell solutions **which** included transverse shear deformation, the **assumption** of shallowness has been applied. Barsoum, Loomis, **and** Stewart [31] were the first to publish results to the complete through crack problem in **a** cylinder by using finite elements which took into account transverse shear deformation. There is good agreement between these results and the results from the shallow shell theories [22,27], even for relatively long cracks. More recent finite element calculations by Ehlers [32] disagree with the **work** of Barsoum, **et.** al. However these calculations are limited to a/R>.5, which for a "shallow shell", is a very long crack. More work must be done to determine the error due to the shallow shell assumption **for** increasing a/R. This theory may be regarded **as** an asymptotic solution for small a/R.

The study of surface cracks in plates and shells has a more detailed history involving three-dimensional numerical techniques because it is both more important and more difficult. In addition to the finite element method [33,34], there is the alternating method [35,36], the boundary integral equation method [37], the finite element alternating method [38-40], the method of weight functions [41,42], and the body force method [43]. The standard solution for plates is that of Newman and Raju [33]. The more recent **work** of

Isida, Noyuchi, and Yoshida [43] have verified these results **and** perhaps slightly improved upon them. For reviews of the various solutions **and** methods see [44-46].

The previous studies for surface cracks deal only with mode 1 loading, which is the most important mode for crack extension. However there **are** situations that involve twisting **and** shearing that cannot be neglected. For instance, depending on the geometry, when these loadings **are** primary, a secondary mode 1 contribution can result. The body force method [47] has recently been applied to an inclined surface crack in **a** half space which involved all modes of fracture. This **problem** has **not** received much attention in the literature, because **it** is]ess **important** than mode **1,** and also more expensive to solve.

As mentioned previously the line-spring model allows for the solution **of** the 3-D surface crack problem within the 2-D theory of plates and shells. This reduces the computational effort considerably. Therefore more extensive parameter studies can be made once the model has been verified by the more **accurate** threedimensional methods.

Since the introduction of the model in 1972 [2], there have been numerous papers suggesting improvements **and** modifications. As with the through crack problem the use of **a** Reissner plate theory has improved the results [48,49], especially for realistic crack lengths on the order of a/h=l. The classical theory gives good results **for** a/h22, and in the limit as a/h⁺⁰⁰ the two theories are the same (for the LSM). The initial suggestions of Rice [3] concerning the use of

the model to study **plasticity** effects have been advanced by Parks [50] and more recently by Miyoshi, Shiratori, and Yoshida [51] who used the model with thick shell finite elements to predict crack growth. Other researchers [49,52] have devised techniques that implement a numerical plate or shell solution instead of the original singular integral equation procedure. This is **an** advantage in shell analysis, because to date, the analytical *techniques* **are** limited to the shallow shell theory which is not valid for long cracks. However the long surface crack is not a practical geometry, and if needed, can usually be approximated by a plane strain solution.

Yang in a recent paper [53] has considered crack surface loading in the form of a polynomial to solve problems of residual or thermal stress. The original LSM used only the constant **and** linear terms associated with tension **and** bending plate variables respectively. Theocaris and Wu [54,55] have suggested a way to determine the SIF at the corner of a surface crack. This method seems inappropriate since they have used the classical theory of plate bending which is unable to predict this value for the much simpler through crack case. The finite width plate has been solved by Boduroglu and Erdogan [56,57]. All previous LSM solutions were for an "infinitely large" plate. Erdogan and Aksel have considered the cavity in a plate [58] and **Wu** and Erdogan have extended the LSM to an orthotropic plate [59]. Delale and Erdogan [60] have used the model with a shallow shell formulation to predict SIFs for surface cracks in cylinders for axial, circumferential, inner and outer cracks.

1.3 Overview

The primary interests in *this* study **are** to extend the LSU to the **mixed-mode case and** to **use** the **model** to **approximate crack** growth *tendencies* **in** the **length direction as** opposed to the **depth direction for** which it **already applies.** In **Chapter 2** the **line-spring** model **for** mixed-mode **loading** conditions is **derived. Furthermore,** the mode **1 compliance relations [61-63,48] are improved** by **using** the **recent edge**cracked **strip solution of Kaya [64].** The **curves are fit** to **data for** $O((L_0/h) \leq .95$ and may be used for the entire range of values as the curves have the proper asymptotic behavior for (L_0/h) +1 [65]. Also the necessary solutions for modes 2 **and 3** are obtained.

In **Chapter** 3 some unsolved through crack problems in plates **are** considered **and** the thin **plate** limit for Reissner's theory is investigated to better understand the validity of the classical **plate** theory when **applied** to the LSM. In **Chapter** 4 the LSM, with **and** without including the transverse shear deformation, is compared to finite element surface crack solutions. SIF comparisons **are** also **made** for the corner of **a** semi-elliptical surface crack. The contact bending or crack closure problem, **a** difficult unsolved 3-D problem, is solved in a straightforward manner. Also extensive SIF results are given for both rectangular **and** semi--elliptical crack shapes under all five loading conditions, i.e. *tension,* bending, out-of-plane **shear,** in-plane shear, and twisting.

Crack problems in shells **are** considered in **Chapters 5** and **6. Comparisons** of surface crack solutions obtained with the model **are** made with 3-D solutions from the literature [34,40]. Various unsolved

through **and** part-through problems **are** considered **and** the effect of curvature is studied **for** both the symmetric and the skew-symmetric **cases.**

All integral equations **are** derived with displacement quantities **as unknowns. The resulting** equations **are,** therefore, strongly singular **and** make use of the **finite-part** integrals of Radaaard [66], see also Kaya [67]. Finite-part integrals **as** used in this study **are** defined in Appendix B. The numerical *techniques* used to solve these equations **are** presented in Appendix E.

The definition of stress intensity factors (SIFs) that are referred to throughout this dissertation is given in Appendix G.

CHAPTER 2

The Line-Spring Model

2.1 Introduction.

A surface **or** part-through **crack** in **a** pipe, pressure **vessel,** or **any** other shell-like structure is a **common and** important **flaw** geometry to analyze, see Fig. **2.1.** Because the **elasticity** problem is threedimensional, many solutions involve expensive numerical techniques such **as** the Finite Element Method [33,34], the Alternating Method [35,36], the Boundary Integral Method [37], the finite **element alternating** method [38-40], the method of **weight** functions [41,42], **and** the body force method [43]. This problem has also been formulated analytically for **a** flat plate or strip in terms of two-dimensional integral equations, but has not been solved [67].

The line-spring model, proposed by Rice and Levy [2], **and** incorporated in a plate or shell theory that allows for transverse shear deformation [7,8,26], **competes with** these methods because of its simplicity and surprising accuracy. See Figs. 4.1-4, 6.1,2, for **comparisons** with the Finite Element Method and for the effect of transverse shear for various geometries in mode 1 loading.

Briefly, the model **allows** one to use a plate or shell theory to **formulate** the problem by removing the "net **ligament** _, and replacing it by unknown, thickness averaged stress resultants **which are** treated **as crack** surface loads in **a** through **crack** problem. See Fig. **2.2** for **a** mode 1 illustration of this process. This reduces by one dimension the **complexity** of the analysis. The force resultant and displacement

variables used in both plates **and** shells are **given** below **and are** defined in Figs. 2.3a-c. Also the corresponding fracture modes a included in the figures.

$$
{F}^{T} = \left\{ F_1, F_2, F_3, F_4, F_5 \right\}, \qquad (2.1)
$$

$$
= \left\{ N_{xx}, M_{xx}, V_x, N_{xy}, M_{xy} \right\}, \qquad (2.2)
$$

$$
= \left\{ h\sigma_1, \frac{h^2}{6}\sigma_2, \frac{2h}{3}\sigma_3, h\sigma_4, \frac{h^2}{6}\sigma_5 \right\} , \qquad (2.3)
$$

$$
\{u\}^{T} = \left\{ u_{1}, u_{2}, u_{3}, u_{4}, u_{5} \right\} = \left\{ u_{x}, \beta_{x}, u_{z}, u_{y}, \beta_{y} \right\}, \qquad (2.4)
$$

$$
\delta_{\mathbf{i}} = \mathbf{u}_{\mathbf{i}}^+ - \mathbf{u}_{\mathbf{i}}^- \qquad \mathbf{i} = 1, \ldots, 5 \qquad (2.5)
$$

The two-dimensional formulation of through and part-through crack problems in plates and shells as a mixed boundary value problem makes use of the superposition illustrated in Fig. 2.4. With regard to these figures, $\frac{F_1}{1}$ are the constant applied loads at Infinity of a **from** the crack region and N and M are unknown stress resultants **which** are due to the net ligament of the part-through crack. In the case of a through crack, the crack surfaces are stress-free so N=M=O. For the solution of the mode 1 perturbation problem in a plate shown in Fig. 2.4, the **following** singular integral equations must be solved:

$$
\frac{1}{2\pi} \int_{a}^{b} \frac{u(t)}{(t-y)^2} dt = -(\stackrel{\mathcal{R}}{\mathcal{N}}_{XX} - \mathcal{N}_{XX}) , \qquad (2.6)
$$

$$
\frac{\gamma(1-\nu^2)}{2\pi}\int_{a}^{b}\frac{\beta(t)}{(t-y)^2} dt + \frac{1}{2\pi}\int_{a}^{b}\!\!\!K_{22}(y,t)\,\beta(t) dt = -(\stackrel{\mathcal{R}}{M}_{XX}-M_{XX}) \quad . \quad (2.7)
$$

For the derivation of Eqns. 2.6,7 and for the expression for $K_{22}(y,t)$,

7, and v see **Chapter 3.** Also see Appendix B for the interpretation **of** the strongly singular **integrals appearing** in these equations. The unknowns in the equations are N , M , u , and β . Since there are four unknowns and only two equations more information is needed. **In** the derivation that follows N and M are linearly related to u and β in the manner of a spring. After substitution of these relationships into Eqns. 2.6,7, u and β can be numerically determined from which all quantities of interest can be calculated.

2.2 **Derivation** of the Compliance Relationships.

The line-spring model is based on two assumptions. The first, previously stated, **and** illustrated in Fig. **2.2,** involves replacing the net ligament (in **which** the state **of** stress is two-dimensional), by resultant forces **which** are functions of y only. The second assumption **is** that the stress intensity factors along the **crack** front may be obtained from these resultant forces as though the stress state were one of plane strain. The restriction at the ends of the crack and the crack front curvature, both act against this assumption. Therefore the model is most accurate in the center of the crack and improves s s the crack gets longer for a given _A_ck depth, i.e. **as** plane strain conditions are **approached.**

In order to make use of this analogy, the plane strain stress intensity factor solution for an edge-cracked strip must be available **for** the five possible loading conditions in a shell on a given surface, see Eqns. 2.2,3 and Fig. 2.3a-c. These solutions are presented in Appendix C along **with a** curve fit in the form,

$$
g_{i}(\xi) = \frac{k_{j}}{\sigma_{i} \sqrt{L}} = \frac{K_{j}}{\sigma_{i} \sqrt{\pi L}} = \frac{1}{(1-\xi)^{\lambda}} \sum_{k=1}^{n_{i}} C_{ik} \xi^{k} , \qquad (2.8)
$$

where L is the crack depth, and the variable ξ is the ratio of th depth L to the strip thickness h, i.e. $\xi = L/h$. From Fig. 2.3a-c, when i=l or 2, **j=l, when** i=3, j=2 and **when** i=4 or **5,** j=3. The exponent k is 3/2 **when** i=1,2 (mode I), and 1/2 **when** i=3,4,5 (modes 2,3). constants n_i and C_{ik} are given in Appendix C. From this follows The

$$
K_1 = \sqrt{\pi \xi h} \left[\sigma_1 g_1 + \sigma_2 g_2 \right] , \qquad (2.9)
$$

$$
K_2 = \sqrt{\pi \xi h} \sigma_3 g_3 \tag{2.10}
$$

$$
K_3 = \sqrt{\pi \xi h} [\sigma_4 g_4 + \sigma_5 g_5] . \qquad (2.11)
$$

In these expressions $\sigma_{\bf i}^{}\!\!=\!\!\sigma_{\bf i}^{}({\bf y})$ represents the net ligament stres according to the relations given in Fig. 2.3. Note that $\xi = \xi$ ()

The derivation is based on expressing the energy available fo fracture along the crack front in two different **ways.** First we generalize Irwin's relation [68,69] for the potential energy rele rate,

$$
\frac{d}{dL}(U-V) = G = \frac{1-\nu^2}{E} \left\{ K_1^2 + K_2^2 + \frac{1}{1-\nu} K_3^2 \right\},
$$
 (2.12)

where U is the **work** done by external loads and V is the strain energy. The use of the relation,

$$
G_2 = \frac{(1 - \nu^2)K_2^2}{E}
$$
 (2.13)

involves the assumption that the crack **will** grow in its own plane. This would apply to structures that are made of composite materi

that **may have** a weak cleavage plane [70]. If the crack deviates **from** a straight path, G₂ in Eqn. 2.13 is not the energy dissipated by incremental crack growth, **and** therefore Eqn. 2.12 would not be valid.

With the **assumption** of coplanar crack growth, Eqns. 2.9-11 are substituted into **Eqn.** 2.12 to obtain,

$$
\frac{d}{dL}(U-V) = h \frac{1-\nu^2}{E} \left\{ \sigma_1^2 g_1^2 + 2\sigma_1 \sigma_2 g_1 g_2 + \sigma_2^2 g_2^2 + \sigma_3^2 g_3^2 + \frac{1}{1-\nu} \left[\sigma_4^2 g_4^2 + 2\sigma_4 \sigma_5 g_4 g_5 + \sigma_5^2 g_5^2 \right] \right\}.
$$
\n(2.14)

Next consider the **crack** to extend from L to **L+AL under** "fixed load" conditions. **Fig. 2.5 for** the **notation used),** The changes in U and V are as follows (refer to

$$
\Delta U = F_{\mathbf{i}} \Delta \delta_{\mathbf{i}} \tag{2.15}
$$

$$
\Delta V = \frac{1}{2} F_{i} (\delta_{i} + \Delta \delta_{i}) - \frac{1}{2} F_{i} \delta_{i} = \frac{1}{2} F_{i} \delta_{i} , \qquad (2.16)
$$

where F_i and δ_i are defined in Eqns. 2.1. **After** writing

$$
\Delta \delta_{\mathbf{i}} = \frac{\partial \delta_{\mathbf{i}}}{\partial L} \Delta L \quad , \tag{2.17}
$$

due to the force F_i ,

$$
\frac{\mathrm{d}}{\mathrm{d}L} \left(\mathrm{U} - \mathrm{V} \right) = \frac{1}{2} \mathrm{F}_i \frac{\partial \delta_i}{\partial L} \tag{2.18}
$$

The sum of all five loadings is,

$$
\frac{\mathrm{d}}{\mathrm{d}L}(U-V) = \frac{1}{2} \sum_{i=1}^{5} F_i \frac{\partial \delta_i}{\partial L} . \qquad (2.19)
$$

Define the following matrices,

$$
\left\{\delta^{\prime}\right\}^{T} = \left\{\delta_{1}^{\prime}, \delta_{2}^{\prime}, \delta_{3}^{\prime}, \delta_{4}^{\prime}, \delta_{5}^{\prime}\right\} = \left\{\delta_{1}, \frac{h}{6} \delta_{2}, \frac{2}{3} \delta_{3}, \delta_{4}, \frac{h}{6} \delta_{5}\right\}, \qquad (2.20)
$$

$$
\begin{bmatrix} G \end{bmatrix} = \begin{bmatrix} g_1^2 & g_1 g_2 & 0 & 0 & 0 \\ g_1 g_2 & g_2^2 & 0 & 0 & 0 \\ 0 & 0 & g_3 & 0 & 0 \\ 0 & 0 & 0 & \frac{1}{1-\nu} g_4 & \frac{1}{1-\nu} g_5 \\ 0 & 0 & 0 & \frac{1}{1-\nu} g_4 g_5 & \frac{1}{1-\nu} g_5 \end{bmatrix}
$$
(2.21)

Now equate Eqn. 2.14 to **2.19** using Eqns. 2.3,20,21 for substitution to obtain,

$$
h \frac{1-\nu^2}{E} \{\sigma\}^T[G] \{\sigma\} = \frac{1}{2} h \{\sigma\}^T \frac{\partial}{\partial L} \{\delta'\}, \qquad (2.22)
$$

or

$$
\frac{\partial}{\partial L} \left\{ \delta^{\prime} \right\} = \frac{2(1-\nu^2)}{E} \left[G \right] \left\{ \sigma \right\} \ . \tag{2.23}
$$

Integrate and observe that $\sigma \neq \sigma(L)$,

$$
\{\delta'\} = \frac{2(1-\nu^2)}{E} \left\{ \int_0^L [G] d1 \right\} \{\sigma\} + \{\delta\big\}_{L=0}^0 \qquad (2.24)
$$

Next define

$$
[B] = [a_{ij}] = \frac{1}{h} \int_0^L [G] d1 = \int_0^{\xi} [G] d\xi , \quad \xi = L/h , \qquad (2.25)
$$

where

$$
a_{ij} = \int_{0}^{\xi} g_{i} g_{j} d\xi , \quad i, j = 1, 2, 3
$$
 (2.26)

and

$$
a_{ij} = \frac{1}{1-\nu} \int_{0}^{\xi} g_{i} g_{j} d\xi , \quad i,j=4,5
$$
 (2.27)

Because of the form chosen for the functions g_i (see Eqn. 2.8), a_{ij} are determined numerically. When the matrix [B] is substituted into Eqn. 2.24 and the equation is solved for the stresses, the result is

$$
\{\sigma\} = \frac{E}{2h(1-\nu^2)} [B]^{-1} \{\delta^*\}, \qquad (2.28)
$$

where

$$
\begin{bmatrix} B \end{bmatrix}^{-1} = \begin{bmatrix} \begin{bmatrix} a_{22}/\Delta_1 & -a_{12}/\Delta_1 & 0 & 0 & 0 \\ -a_{12}/\Delta_1 & a_{11}/\Delta_1 & 0 & 0 & 0 \\ 0 & 0 & 1/a_{33} & 0 & 0 \\ 0 & 0 & 0 & a_{55}/\Delta_2 & -a_{45}/\Delta_2 \\ 0 & 0 & 0 & -a_{45}/\Delta_2 & a_{44}/\Delta_2 \end{bmatrix} \end{bmatrix}, \qquad (2.29)
$$

and

$$
\Delta_1 = a_{11}a_{22} - a_{12}^2, \qquad \Delta_2 = a_{44}a_{55} - a_{45}^2 \tag{2.30}
$$

Eqn. 2.28 has the information that is needed for substitution into integral equations of the form of Eqns. 2.6,7. First it must be non-dimensionalized. This is done according to the definitions in Appendix A. Since **all problems in** this **dissertation are either** symmetric or skew-symmetric we have $\delta_i = 2u_i$, i.e. $|u^+| = |u^-| = u_i$. The **final** non-dimensional result is:

$$
\sigma_{1} = \gamma_{11}u_{1} + \gamma_{12}u_{2} ,
$$
\n
$$
\sigma_{2} = 6[\gamma_{21}u_{1} + \gamma_{22}u_{2}],
$$
\n
$$
\sigma_{3} = \frac{5}{8(1+\nu)} \gamma_{33}u_{3} ,
$$
\n
$$
\sigma_{4} = \gamma_{44}u_{4} + \gamma_{45}u_{5} ,
$$
\n
$$
\sigma_{5} = 6[\gamma_{54}u_{4} + \gamma_{55}u_{5}],
$$
\n
$$
u_{1} = (1-\nu^{2})[\alpha_{11}\sigma_{1} + \alpha_{12}\sigma_{2}],
$$
\n
$$
u_{2} = 6(1-\nu^{2})[\alpha_{12}\sigma_{1} + \alpha_{22}\sigma_{2}],
$$
\n(2.31)

$$
u_3 = \frac{3}{2} (1 - \nu^2) a_{33} \sigma_3 ,
$$

\n
$$
u_4 = (1 - \nu^2) [a_{44} \sigma_4 + a_{45} \sigma_5],
$$

\n
$$
u_5 = 6(1 - \nu^2) [a_{45} \sigma_4 + a_{55} \sigma_5],
$$

\n(2.32)

$$
\gamma_{11} = \frac{1}{1-\nu^{2}} \frac{a_{22}}{\Delta_{1}}, \qquad \gamma_{12} = \frac{-1}{6(1-\nu^{2})} \frac{a_{12}}{\Delta_{1}},
$$

\n
$$
\gamma_{21} = \gamma_{12}, \qquad \gamma_{22} = \frac{1}{36(1-\nu^{2})} \frac{a_{11}}{\Delta_{1}},
$$

\n
$$
\gamma_{33} = \frac{16}{15(1-\nu)} \frac{1}{a_{33}},
$$

\n
$$
\gamma_{44} = \frac{1}{1-\nu^{2}} \frac{a_{55}}{\Delta_{2}}, \qquad \gamma_{45} = \frac{-1}{6(1-\nu^{2})} \frac{a_{45}}{\Delta_{2}},
$$

\n
$$
\gamma_{54} = \gamma_{45}, \qquad \gamma_{55} = \frac{1}{36(1-\nu^{2})} \frac{a_{44}}{\Delta_{2}}.
$$

\n(2.33)

If these equations are now substituted into Eqns. 2.6,7, the result is,

$$
\frac{1}{2\pi} \int_{a}^{b} \frac{u(t)}{(t-y)^{2}} dt - \gamma_{11} u - \gamma_{12} \beta = -\mathfrak{F}_{xx} = -\mathfrak{F}_{1} , \qquad (2.34)
$$
\n
$$
\frac{\gamma(1-\nu^{2})}{2\pi} \int_{a}^{b} \frac{\beta(t)}{(t-y)^{2}} dt + \frac{1}{2\pi} \int_{a}^{b} K_{22}(y,t) \beta(t) dt
$$
\n
$$
- \gamma_{21} u - \gamma_{22} \beta = -\mathfrak{F}_{xx} = -\mathfrak{F}_{2}/6 . \qquad (2.35)
$$

The compliance coefficients τ_{ij} are indirectly functions

through the variable ξ which is the non-dimensional crack depth. Note that for a through crack the γ_{ij} are zero. In this case the equations uncouple **and** respectively correspond to tension **and** bending loadings.

Since the model is most **accurate** in the central portion of the crack, it is best applied to problems where **failure** occurs when the surface crack grows through the thickness leading either to leaking or to the development of **a** through crack which then grows in length to critical size. **Because** of the **plane** strain **assumption,** the model becomes **less applicable near** the **ends** of the crack. Although the model **unexpectedly** gives **reasonable results** here **(see Figs. 4.1-4 and** 6.1,2 where curves **are** drawn up to **y/a** = **.98),** the **use of** the **solution** in this region **for** anything **other** than general trends is **not justified.** Even though the solution **at** the ends is not used, the behavior of the solution here plays a role in the convergence of the **method** over the entire range, **and** therefore should be examined.

2.3 Endpoint behavior.

In the case of the through crack it is known that the behavior of the displacement quantities are of the form (see *Appendix* D),

$$
u_{i}(t) = f_{i}(t)(1-t^{2})^{1/2}, \qquad (2.36)
$$

where the square root is referred to **as** the weight function (of the integral equation) and $f_i(t)$ is a simple function which can be represented by **a** polynomial that is easily obtained numerically. Note that the crack domain has been normalized to $(-1,1)$. If $u_i(t)$ were determined without extracting the endpoint behavior given by the weight function, convergence of $u_i(t)$ towards the ends (i.e. -1,1) would be unacceptably slow. Also in the through crack problem the stress intensity factors **are** proportional to f(-l) and f(+l), and therefore can only be **found** if the weight is extracted. **The** addition of the line-spring *terms* into the integral equation has **an** effect on *this* **asymptotic analysis** only if the **net** ligament stresses **are** unbounded, **which** is unreasonable. If **these** stresses **are assumed** to be **finite at** the ends, Eqns. 2.32 **and** 2.36 show that,

$$
u_1 = (1 - \nu^2) [\ a_{11}\sigma_1 + a_{12}\sigma_2] = f_1(t) (1 - t^2)^{1/2},
$$

\n
$$
u_2 = 6(1 - \nu^2) [\ a_{12}\sigma_1 + a_{22}\sigma_2] = f_2(t) (1 - t^2)^{1/2},
$$

\n
$$
u_3 = \frac{3}{2} (1 - \nu^2) a_{33}\sigma_3 = f_3(t) (1 - t^2)^{1/2},
$$

\n
$$
u_4 = (1 - \nu^2) [\ a_{44}\sigma_4 + a_{45}\sigma_5] = f_4(t) (1 - t^2)^{1/2},
$$

\n
$$
u_5 = 6(1 - \nu^2) [\ a_{45}\sigma_4 + a_{55}\sigma_5] = f_5(t) (1 - t^2)^{1/2}.
$$

\n(2.37)

For finite, non-zero net ligament stresses, a_{ij} in Eqns. 2.32 must carry the square root behavior as t approaches -1 and 1. Recall that a_{ij} are functions of t-through the crack shape variable ξ . If the crack depth of the surface crack is non-zero at the ends **as** in the case of a rectangular crack, $a_{\cdot,\cdot}$ will be constant at the endpoint
i The solution will then require *a.* to be **zero at** the endpoints, **a** i condition that does not seem reasonable. If the crack depth, ξ is zero at the ends, the behavior of $a_{\texttt{i} \texttt{j}}$ will depend on how ζ goes to zero. For small ξ we may write

$$
g_{i} \approx \sum_{j=0}^{N} c_{i j} \xi^{j} \tag{2.38}
$$

from which we **obtain** from Eqns. **2.26,27,**

$$
a_{11} = \frac{\pi}{2} c_{10}^2 \zeta^2 + \frac{2\pi}{3} c_{10} c_{11} \zeta^3 + 0(\zeta^4) ,
$$

\n
$$
a_{12} = a_{21} = \frac{\pi}{2} c_{10} c_{20} \zeta^2 + \frac{\pi}{3} \left[c_{20} c_{11} + c_{10} c_{21} \right] \zeta^3 + 0(\zeta^4) ,
$$

\n
$$
a_{22} = \frac{\pi}{2} c_{20}^2 \zeta^2 + \frac{2\pi}{3} c_{20} c_{21} \zeta^3 + 0(\zeta^4) ,
$$

\n
$$
a_{33} = \frac{\pi}{4} c_{31}^2 \zeta^4 + 0(\zeta^5) ,
$$

\n
$$
(1-\nu) a_{44} = \frac{\pi}{2} c_{40}^2 \zeta^2 + \frac{2\pi}{3} c_{40} c_{41} \zeta^3 + 0(\zeta^4) ,
$$

\n
$$
(1-\nu) a_{45} = (1-\nu) a_{54} = \frac{\pi}{2} c_{40} c_{50} \zeta^2 + \frac{\pi}{3} \left[c_{40} c_{51} + c_{50} c_{41} \right] \zeta^3 + 0(\zeta^4) ,
$$

\n
$$
(1-\nu) a_{55} = \frac{\pi}{2} c_{50}^2 \zeta^2 + \frac{2\pi}{3} c_{50} c_{51} \zeta^3 + 0(\zeta^4) ,
$$

\n
$$
(2.39)
$$

where from Eqn 2.8 the c_{ij} in terms of the c_{ij} are,

$$
c_{i0} = c_{i0} ,
$$

$$
c_{i1} = c_{i1} + \lambda c_{i0} .
$$
 (2.40)

ŧ

More terms in this series are given in Appendix F.

In order for Eqn. **2.37** to be true for bounded, non-zero stresses, Eqn. 2.39 (except for a_{33}) suggest that:

$$
a_{ij} \sim (1-t^2)^{1/2} \tag{2.41}
$$

or

$$
\xi^2 \sim (1-t^2)^{1/2} \quad . \tag{2.42}
$$

Therefore if the crack shape is chosen in the form

$$
\xi = \xi_0 (1 - t^2)^{1/4} \tag{2.43}
$$

convergence will be good for $|t| \leq 1$. Rice [2] made this point. Any other crack shape will impose either unbounded or zero endpoint behavior on the net ligament stresses **and** the solution will not converge **at** the endpoints in a satisfactory manner. If one considers the semi-ellipse for example, σ_i will be of the order $(1-t^2)^{-1/2}$ as Itl approaches 1.

There is one exception. In the case of a_{33} in Eqn. 2.37 the stress σ_3 will be zero. This should be expected because the assumed form of the out-of-plane shear stress is parabolic, i.e. zero at the surface of the shell. Therefore as the crack depth goes to zero so does $\sigma_{\mathbf{q}}$.

It should be pointed out that regardless of what **form** of the crack is chosen, satisfactory convergence can be obtained in the central portion where the line-spring model is most applicable. The results in this dissertation were thus obtained for the semi-ellipse. But if **a** solution is desired for (-1,1), it is necessary to have the crack shape at the ends asymptotically behave like Eqn. 2.43. A procedure to get this function utilizes a simple expansion about zero and for some typical shapes is as follows. Let

$$
\xi = \xi_0 (1-t^2)^n
$$
 (2.44)

be the desired shape. Note that a rectangle is given by n=O, **and** a semi-ellipse results **from** n=l/2. Next we write

$$
\xi = \xi_0 (1 - t^2)^n \approx \xi_0 (1 - t^2)^{1/4} g(t) , \qquad (2.45)
$$

where

$$
g(t) \approx (1-t^2)^{n-1/4} \approx \sum_{i=0}^{M} a_i t^{2i}
$$
 (2.46)

M **is** given over most of the **domain, and** the **coefficients ai, are** given **as** follows, **chosen so** that **an adequate representation of** the **crack front** is

$$
a_0 = 1
$$

\n
$$
a_1 = -(n-1/4)
$$

\n
$$
a_2 = \frac{(n-1/4) \left[(n-1/4) - 1 \right]}{2!}
$$

\n
$$
a_3 = - \frac{(n-1/4) \left[(n-1/4) - 1 \right] \left[(n-1/4) - 2 \right]}{3!}, \text{ etc.}
$$
 (2.47)

The convergence of Eqn. **2.46** is **demonstrated for n=O and** n=I/2 in tables **2.1,2,** respectively. Stress **intensity factor** results of Eqns. **2.6,7 for** the **crack** shapes in these tables **are given in** tables **2.3-6.** The stress intensity **factors in** Eqns. **2.9-11 are** normalized **with** respect to the value of K from Eqn. 2.8 for ξ in the center of the **crack** and **for** the **corresponding** loading, see section C.4 of Appendix C. This **technique** however, is of **limited** use.

Semi-elliptic **crack** shapes **are chosen for** most mode 1 **analysis** because of **their** general resemblance to surface **cracks.** Most experiments however show that **cracks grown** by **fatigue** tend to have **a** blunter shape at the **ends,** see **for** example **[55,71].** Note that the 1/4 power represents this better **than** 1/2.

One further point to make before concluding this chapter is that for small ξ the inverse of the B matrix (Eqn. 2.29) is singular and the asymptotic behavior of relations 2.32 is of the form,

$$
\gamma_{ij} = \text{(constant)} \ \xi^{-4} + 0(\xi^{-3}) \ . \tag{2.48}
$$

The constants are defined in Appendix F. It would seem that the contribution of the stress terms (Eqn. 2.31) for the case of a semiellipse where $u \sim (\tau (1-t^2))^{1/2}$ would be unbounded and to the -3/2 power rather than -1/2 as predicted by Eqn. 2.37. Rowever when the terms of Eqn. 2.31 are combined, the two leading order terms cancel and we are left with the singular nature predicted by Eqn. 2.37, see Appendix F.

Table 2.1 Crack profiles approximating a constant depth using Eqns. 2.46,47.

Rectangular Profile $(ξ = .6)$

t **.0 .I .2 .3 .4 .5 .6** .7 **.8 .9** .95 **.98** M 1 **3** 5 **I0** 20 exact **•6000 .5985** 5939 5860 5744 5584 5367 **5070 4648 .3961** .3353 .2677 6OOO 6OOO 6OOO 6OOO 5997 **5987 5958** 5882 **5689** 5170 **4536 3705** 6000 6OOO 6OOO 6OOO 6OOO 5999 5996 5980 5906 .5579 •5037 •4200 .6000 6000 **6000** 6000 **6000** 6000 6000 6000 **5993** 5900 5585 .4862 600O 6000 6000 60O0 6O00 6000 60OO 6000 6000 5992 5898 **5440** 6000 6000 6000 6000 6000 6000 6000 6000 • 6000 • 6000 • 6000 • 6000

Table **2.2 Crack** profiles **approximating a** semi**ellipse** using Eqns. **2.46,47.**

Semi-Elliptic profile, $(\xi = .6(1-t^2)^{1/2})$
Table 2.3 Normalized stress intensity factors for the crack profiles given in table 2.1 for applied tension.

Rectangular Profile $(\xi = .6)$, Tension

Table 2.4 Normalized stress intensity factors for the **crack** profiles given in table **2.1** for pure bending.

Rectangular Profile $(\xi = .6)$, Bending

Table 2.5 Normalized stress intensity **factors** for the crack profiles given in table 2.2 for applied tension.

Semi-elliptic Profile $(\xi_0 = .6)$, Tension

Table 2.6 Normalized stress intensity factors for the crack **profiles** given in *table* **2.2 for pure** bending.

Semi-elliptic Profile $(\xi_0 = .6)$, Bending

Figure 2.1 The shell geometry.

Figure 2.2 Representation of the two-dimens stress state in the net ligament with str resultants for the mode 1 proble

(a)

o

Figure 2.3a Force and Displacement quantities as defined by plate **or** shell theory that are used in the mode 1 line-spring model.

Figure 2.3b Force **and** Displacement quantities as defined by plate or shell theory that are used by the line-spring model for mode 2 loading.

Figure 2.3c Force and Displacement quantities as
defined by plate or shell theory that are used by
the line-spring model for mode 3 loading.

Figure 2.4 The superposition used to solve partthrough crack problems with the line-spring model. All solutions **are** obtained for the problem in the lower right (the perturbation problem) where the only loads **are** applied to the crack surfaces.

Figure 2.5 The corresponding plane strain problem.

CHAPTER 3

Through Cracks in **Plates**

In this **chapter** the singular integral **equations for a** cracked plate under both symmetric (mode 1) and skew-symmetric (modes 2,3) loadings will be derived. The plate theory includes transverse shear deformation. For mode 1 loading there is very little to **add** to the existing literature [6,9-13]. The thin plate limit examined in these papers **will** be reconsidered. For the skew-symmetric case stress intensity factor solutions found **in** Refs. [14,15] for **a** single crack wi!l be supplemented. **Also** some results for the double crack case will be **presented.**

3.1 Formulation

The governing equations, both dimensional (Eqns. 3.1a-16a, **18a,** 19a) and non-dimensional (Eqns. 3.1b-16b,18b,19b) are listed below. The dimensional relationships are defined in Appendix A. From equilibrium

$$
\frac{\partial N_{11}}{\partial x_1} + \frac{\partial N_{12}}{\partial x_2} = 0 \quad , \quad \frac{\partial N_{xx}}{\partial x} + \frac{\partial N_{xy}}{\partial y} = 0 \quad , \tag{3.1a,b}
$$

$$
\frac{\partial N_{12}}{\partial x_1} + \frac{\partial N_{22}}{\partial x_2} = 0 \quad , \quad \frac{\partial N_{xy}}{\partial x} + \frac{\partial N_{yy}}{\partial y} = 0 \quad , \tag{3.2a,b}
$$

$$
\frac{\partial V_1}{\partial x_1} + \frac{\partial V_2}{\partial x_2} + \overline{q}(x_1, x_2) = 0 ,
$$

$$
\frac{\partial V_x}{\partial x} + \frac{\partial V_y}{\partial y} + \frac{12(1+\nu)}{5} q(x, y) = 0 ,
$$
 (3.3a, b)

$$
\frac{\partial M_{11}}{\partial x_1} + \frac{\partial M_{12}}{\partial x_2} - V_1 = 0 ,
$$
\n
$$
\frac{\partial M_{xx}}{\partial x} + \frac{\partial M_{xy}}{\partial y} - \frac{5}{12(1+\nu)} V_x = 0 , \qquad (3.4a, b)
$$
\n
$$
\frac{\partial M_{12}}{\partial x_1} + \frac{\partial M_{22}}{\partial x_2} - V_2 = 0 , \qquad (3.4a)
$$

$$
\frac{22}{\theta x_2} - V_2 = 0 ,
$$

$$
\frac{\partial M_{xy}}{\partial x} + \frac{\partial M_{yy}}{\partial y} - \frac{5}{12(1+\nu)} V_y = 0 ,
$$
 (3.5a,b)

where $q(x,y)$ is normal loading to the plate surface. The other varinbles are standard plate quantities (see Fig. 2.3). From kinematical considerations,

$$
\epsilon_{11} = \frac{\partial u_{1D}}{\partial x_1} , \quad \epsilon_{xx} = \frac{\partial u}{\partial x} , \qquad (3.6a, b)
$$

$$
\epsilon_{22} = \frac{\partial u_{2D}}{\partial x_2} , \quad \epsilon_{yy} = \frac{\partial v}{\partial y} , \qquad (3.7a, b)
$$

$$
\epsilon_{12} = \frac{1}{2} \left[\frac{\partial u_{1D}}{\partial x_2} + \frac{\partial u_{2D}}{\partial x_1} \right] , \quad \epsilon_{xy} = \frac{1}{2} \left[\frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \right] , \quad (3.8a, b)
$$

$$
\theta_1 = \frac{\partial u_{3D}}{\partial x_1} + \beta_1 \quad , \quad \theta_x = \frac{\partial w}{\partial x} + \beta_x \quad , \tag{3.9a,b}
$$

$$
\theta_2 = \frac{\partial u_{3D}}{\partial x_2} + \beta_2 \quad , \quad \theta_y = \frac{\partial w}{\partial y} + \beta_y \quad , \tag{3.10a,b}
$$

where θ_1 and θ_2 are the total rotations of the normals. For classical plate theory they are zero showing that normals to the plate surface stay normal, i.e. there is no deformation transversely. **The** constitutive relations (Hooke's law) are,

$$
h\epsilon_{11} = \frac{1}{E} (N_{11} - \nu N_{22})
$$
, $\epsilon_{xx} = N_{xx} - \nu N_{yy}$, (3.11a,b)

$$
h\epsilon_{22} = \frac{1}{E} (N_{22} - \nu N_{11})
$$
, $\epsilon_{yy} = N_{yy} - \nu N_{xx}$, (3.12a,b)

$$
h\epsilon_{12} = \frac{1}{2\mu} N_{12}
$$
, $\epsilon_{xy} = (1+\nu)N_{xy}$, (3.13a,b)

where E is Young's modulus and *v* is Poisson's ratio. From pla bending,

$$
M_{11} = D \left[\frac{\partial \beta_1}{\partial x_1} + \nu \frac{\partial \beta_2}{\partial x_2} \right],
$$

$$
M_{xx} = \frac{1}{12(1-\nu^2)} \left[\frac{\partial \beta_x}{\partial x} + \nu \frac{\partial \beta_y}{\partial y} \right],
$$
 (3.14a,b)

$$
M_{22} = D \left[\frac{\partial \beta_2}{\partial x_2} + \nu \frac{\partial \beta_1}{\partial x_1} \right],
$$

$$
\mathbf{M}_{\mathbf{y}\mathbf{y}} = \frac{1}{12(1-\nu^2)} \left[\nu \frac{\partial \rho_{\mathbf{x}}}{\partial \mathbf{x}} + \frac{\partial \rho_{\mathbf{y}}}{\partial \mathbf{y}} \right], \qquad (3.15a, b)
$$

$$
M_{12} = \frac{D(1-\nu)}{2} \left[\frac{\partial \beta_1}{\partial x_2} + \frac{\partial \beta_2}{\partial x_1} \right],
$$

$$
M_{xy} = \frac{1}{24(1+\nu)} \left[\frac{\partial \beta_x}{\partial y} + \frac{\partial \beta_y}{\partial x} \right],
$$
 (3.16a,b)

where,

$$
D = \frac{Eh^3}{12(1-\nu^2)} \qquad (3.17)
$$

The linear transverse shear stress-strain relationships are,

$$
\theta_1 = \frac{1}{hB} V_1 , \quad \theta_x = V_x , \qquad (3.18a, b)
$$

$$
\theta_2 = \frac{1}{hB} V_2 , \quad \theta_y = V_y , \qquad (3.19a, b)
$$

where

$$
B = \frac{5E}{12(1+\nu)} \tag{3.20}
$$

From here on only the non-dimensional variables will be used. Define $\phi(x,y)$ such that

$$
N_{xx} = \frac{\partial^2 \phi}{\partial y^2} , N_{yy} = \frac{\partial^2 \phi}{\partial x^2} , N_{xy} = -\frac{\partial^2 \phi}{\partial x \partial y} ,
$$
 (3.21)

and Eqns. 3.lb,2b are satisfied. Next combine Eqns. 3.6b,7b **with** 3.11b,12b to obtain,

$$
\frac{\partial u}{\partial x} = N_{xx} - \nu N_{yy} , \quad \frac{\partial v}{\partial y} = N_{yy} - \nu N_{xx} .
$$
 (3.22)

Next use Eqns. 3.8b,13b to **write,**

$$
(1+\nu) N_{xy} = \frac{1}{2} \left[\frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \right], \qquad (3.23)
$$

or

$$
(1+\nu)\frac{\partial^2}{\partial x \partial y^N xy} = \frac{1}{2} \left[\frac{\partial^3 u}{\partial x \partial y^2} + \frac{\partial^3 v}{\partial y \partial x^2} \right] \qquad (3.24)
$$

After substituting **3.22** into 3.24 we **obtain,**

$$
(1+\nu)\frac{\partial^2}{\partial x \partial y}N_{xy} = \frac{1}{2} \left\{ \left[\frac{\partial^2 N_{xx}}{\partial y^2} - \nu \frac{\partial^2 N_{yy}}{\partial y^2} \right] + \left[\frac{\partial^2 N_{yy}}{\partial x^2} - \nu \frac{\partial^2 N_{xx}}{\partial x^2} \right] \right\}
$$
 (3.25)

Using **3.21** this becomes,

$$
\nabla^4 \phi = 0 \quad , \tag{3.26}
$$

where

$$
\nabla^2 = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \quad .
$$
 (3.27)

Next using **3.35-55** we **can write,**

$$
\frac{\partial^2 \mathbf{M}}{\partial x^2} + 2 \frac{\partial^2 \mathbf{M}}{\partial x \partial y} + \frac{\partial^2 \mathbf{M}}{\partial y^2} + q(x, y) = 0
$$
 (3.28)

Substitute Eqns. **3.14b-16b into 3.28** to **obtain,**

$$
\frac{\partial^3 \beta_x}{\partial x^3} + \frac{\partial^3 \beta_y}{\partial x^2 \partial y} + \frac{\partial^3 \beta_y}{\partial y^3} + \frac{\partial^3 \beta_x}{\partial y^2 \partial x} + 12(1-\nu)^2 q(x,y) = 0
$$
 (3.29)

Look at the following **expression** from the first two terms **of** Eqn. 3.29,

$$
\frac{\partial^3 \beta_{\mathbf{x}}}{\partial \mathbf{x}^3} + \frac{\partial^3 \beta_{\mathbf{y}}}{\partial \mathbf{x}^2 \partial \mathbf{y}} = \frac{\partial^2}{\partial \mathbf{x}^2} \left[\frac{\partial \beta_{\mathbf{x}}}{\partial \mathbf{x}} + \frac{\partial \beta_{\mathbf{y}}}{\partial \mathbf{y}} \right]
$$
 (3.30)

Substitute for β_x and β_y according to Eqns. 3.9b,10b together with 3.18b,19b,

$$
\frac{\partial^3 \beta_{\mathbf{x}}}{\partial x^3} + \frac{\partial^3 \beta_{\mathbf{y}}}{\partial x^2 \partial y} = \frac{\partial^2}{\partial x^2} \left[\frac{\partial V_{\mathbf{x}}}{\partial x} - \frac{\partial^2 \mathbf{w}}{\partial x^2} + \frac{\partial V_{\mathbf{y}}}{\partial y} - \frac{\partial^2 \mathbf{w}}{\partial y^2} \right] \quad . \tag{3.31}
$$

Next use Eqns. 3.3b and 3.27 for substitution into 3.31 to obtain,

$$
\frac{\partial^3 \beta_x}{\partial x^3} + \frac{\partial^3 \beta_y}{\partial x^2 \partial y} = \frac{\partial^2}{\partial x^2} \left[\frac{12(1+\nu)}{5} q(x,y) - \nabla^2 w \right] \quad . \tag{3.32}
$$

Similarly,

$$
\frac{\partial^3 \beta_y}{\partial y^3} + \frac{\partial^3 \beta_x}{\partial y^2 \partial x} = \frac{\partial^2}{\partial y^2} \left[\frac{12(1+\nu)}{5} q(x,y) - \nabla^2 w \right] \quad . \tag{3.33}
$$

Eqns. 3.32,33 are now substituted back into Eqn. 3.29 to **obtain,**

$$
\gamma^4_{w} = \left\{ \frac{12(1+\nu)}{5} \; \gamma^2 + 12(1-\nu^2) \right\} q(x,y) \quad . \tag{3.34}
$$

Next use Eqn. 3.4b with **substitutions** from 3.14b,3.16b and 3.18b with 3.9b to write,

$$
\beta_{x} + \frac{\partial w}{\partial x} = \frac{1}{12(1-\nu)^2} \left\{ \frac{12(1+\nu)}{5} \ \nabla^2 \beta_{x} + \frac{1+\nu}{2} \frac{\partial}{\partial y} \left[\frac{\partial \beta_{y}}{\partial x} - \frac{\partial \beta_{x}}{\partial y} \right] \right\} \ . \tag{3.35}
$$

Similar substitutions with Eqn. 3.55 leads to,

$$
\beta_{y} + \frac{\partial w}{\partial y} = \frac{1}{12(1-\nu)^2} \left\{ \frac{12(1+\nu)}{5} \ \nabla^2 \beta_{y} + \frac{1+\nu}{2} \frac{\partial}{\partial x} \left[\frac{\partial \beta_{x}}{\partial y} - \frac{\partial \beta_{y}}{\partial x} \right] \right\} \ . \quad (3.36)
$$

After defining the constants,

$$
\kappa = \frac{1}{5(1-\nu)} , \quad \gamma = \frac{1}{12(1-\nu^2)} , \qquad (3.37)
$$

and the new unknowns,

$$
\Omega(x,y) = \frac{\partial \beta_x}{\partial y} - \frac{\partial \beta_y}{\partial x} , \qquad (3.38)
$$

$$
\psi(x,y) = \kappa \left[\frac{\partial \beta_x}{\partial x} + \frac{\partial \beta_y}{\partial v} \right] - w \quad , \tag{3.39}
$$

Eqns. 3.26,34,35,36 become,

$$
\nabla^4 \phi = 0 \quad , \tag{3.40}
$$

$$
\nabla^4 w = 0 \quad , \tag{3.41}
$$

$$
\kappa \nabla^2 \psi - \psi - \mathbf{w} = 0 \quad , \tag{3.42}
$$

$$
\kappa \frac{1-\nu}{2} \sqrt{\gamma^2} \Omega - \Omega = 0 \quad , \tag{3.43}
$$

where q(x,y) has been assumed to be zero. To solve Eqns. 3.40-43 we introduce the Fourier transform,

$$
\bar{\phi}(x,\alpha) = \int_{-\infty}^{+\infty} \phi(x,y) e^{i\alpha y} dy
$$
 (3.44)

$$
\phi(\mathbf{x}, \mathbf{y}) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} \overline{\phi}(\mathbf{x}, a) e^{-i a y} d a \quad , \tag{3.45}
$$

with identical definitions for $w(x,y)$, $\psi(x,y)$ and $\hat{u}(x,y)$. After making **use of** the relationships,

$$
\int_{-\infty}^{+\infty} \nabla^2 f(x,y) e^{i\alpha y} dy = \frac{\partial^2 \overline{f}}{\partial x^2} - a^2 \overline{f} ,
$$

$$
\int_{-\infty}^{+\infty} \nabla^4 f(x,y) e^{i\alpha y} dy = \frac{\partial^4 \overline{f}}{\partial x^4} - 2a^2 \frac{\partial^2 \overline{f}}{\partial x^2} + a^4 \overline{f} ,
$$
 (3.46)

Eqns. 3.40-43 are reduced to the following ordinary differential equations,

$$
\frac{\partial^4 \vec{\phi}}{\partial x^4} - 2a^2 \frac{\partial^2 \vec{\phi}}{\partial x^2} + a^4 \vec{\phi} = 0 \quad , \tag{3.47}
$$

$$
\frac{\partial^4 \overline{w}}{\partial x^4} - 2a^2 \frac{\partial^2 \overline{w}}{\partial x^2} + a^4 \overline{w} = 0 \quad , \tag{3.48}
$$

$$
\kappa \left\{ \frac{\partial^2 \overline{\psi}}{\partial x^2} - \alpha^2 \overline{\psi} \right\} - \overline{\psi} - \overline{\mathbf{w}} = 0 \quad , \tag{3.49}
$$

ŧ

$$
\kappa \frac{1-\nu}{2} \left\{ \frac{\partial^2 \overline{n}}{\partial x^2} - \alpha^2 \overline{n} \right\} - \overline{n} = 0 \quad . \tag{3.50}
$$

Assuming symmetry of loading and geometry with respect to x , th transformed solution for x>O of Eqns. 3.47-50 is,

$$
\phi(\mathbf{x}, \mathbf{y}) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} \left[A_1(a) e^{-\|\alpha\|_X} + A_2(a) x e^{-\|\alpha\|_X} \right] e^{-\mathbf{i} a y} d\alpha \quad , \tag{3.51}
$$

$$
w(x,y) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} \left[A_3(a) e^{-\frac{1}{2} a |x|} + A_4(a) x e^{-\frac{1}{2} a |x|} \right] e^{-\frac{1}{2} a y} da \quad , \tag{3.52}
$$

$$
\psi(x,y) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} \left\{ \left[-A_3(a) + (2|a|\kappa - x)A_4(a) \right] e^{-|a|x|} + \right.
$$

$$
C(\alpha) \exp \left[-x \left(\frac{\kappa a^2 + 1}{\kappa}\right)^{1/2}\right] \} e^{-i \alpha y} d\alpha , \qquad (3.53)
$$

$$
\Omega(x,y) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} A_5(a) e^{-Rx} e^{-iay} da , \qquad (3.54)
$$

where

$$
R = \left[a^2 + \frac{2}{\kappa (1-\nu)} \right]^{1/2} .
$$
 (3.55)

For **either** the symmetric **or** the skew-symmetric **problem** there **are** five conditions with which to determine six constants, $A_i(a)$, i=1,...,5, and C(a). This shows that one **constant** is extra and **we** take

$$
C(a) = 0 \quad , \tag{3.56}
$$

and proceed to show that the problem **can** be uniquely solved **without** it. Now that the four unknowns, w, φ, ψ , and u are known in terms of the **five** unknown **coefficients,** the **other plate variables are expressed** in terms of them. N_{xx}, N_{yy}, and N_{xy} are already expressed in this form in Eqn. 3.21. The other important expressions are,

$$
\beta_{\mathbf{x}} = \kappa \frac{1-\nu}{2} \frac{\partial \mathbf{0}}{\partial \mathbf{y}} + \frac{\partial \psi}{\partial \mathbf{x}} \quad , \tag{3.57}
$$

$$
\beta_{y} = -\kappa \frac{1-\nu}{2} \frac{\partial \Omega}{\partial x} + \frac{\partial \psi}{\partial y} , \qquad (3.58)
$$

$$
M_{xx} = \gamma \left\{ \kappa \frac{\left(1-\nu\right)^2}{2} \frac{\partial^2 \eta}{\partial x \partial y} + \frac{\partial^2 \psi}{\partial x^2} + \nu \frac{\partial^2 \psi}{\partial y^2} \right\} , \qquad (3.59)
$$

$$
M_{yy} = \gamma \left\{ -\kappa \frac{\left(1-\nu\right)^2}{2} \frac{\partial^2 \eta}{\partial x \partial y} + \frac{\partial^2 \psi}{\partial y^2} + \nu \frac{\partial^2 \psi}{\partial x^2} \right\} , \qquad (3.60)
$$

$$
M_{xy} = \frac{1}{24(1+\nu)} \left\{ \kappa \frac{1-\nu}{2} \left[\frac{\partial^2 \Omega}{\partial y^2} - \frac{\partial^2 \Omega}{\partial x^2} \right] + 2 \frac{\partial^2 \psi}{\partial x \partial y} \right\} , \qquad (3.61)
$$

$$
V_{x} = \frac{\partial w}{\partial x} + \kappa \frac{1-\nu}{2} \frac{\partial \Omega}{\partial y} + \frac{\partial \psi}{\partial x} , \qquad (3.62)
$$

$$
V_y = \frac{\partial w}{\partial y} - \kappa \frac{1-\nu}{2} \frac{\partial \Omega}{\partial x} + \frac{\partial \psi}{\partial y} , \qquad (3.63)
$$

$$
\frac{\partial^2 u}{\partial y^2} = -(2+\nu)\frac{\partial^3 \phi}{\partial y^2 \partial x} - \frac{\partial^3 \phi}{\partial x^3} , \qquad (3.64)
$$

$$
\frac{\partial v}{\partial y} = \frac{\partial^2 \phi}{\partial x^2} - \nu \frac{\partial^2 \phi}{\partial y^2}
$$
 (3.65)

Now if Eqns. 3.51-54 are substituted into Eqns. 3.21,57-65 the result is,

$$
N_{xx} = -\frac{1}{2\pi} \int_{-\infty}^{+\infty} a^2 \Big[A_1(a) + x A_2(a) \Big] e^{-\vert a \vert x} e^{-iay} da , \qquad (3.66)
$$

$$
N_{yy} = \frac{1}{2\pi} \int_{-\infty}^{+\infty} \left[a^2 A_1(a) + A_2(a) (a^2 x - 2ia) \right] e^{-\left[a \right] x} e^{-iay} da , \qquad (3.67)
$$

$$
N_{xy} = \frac{i}{2\pi} \int_{-\infty}^{+\infty} a \left[-\left| a \right| A_1(a) + (1-x|a|) A_2(a) \right] e^{-\left| a \right| x} e^{-iay} da , \qquad (3.68)
$$

$$
\beta_{x} = \kappa \frac{1-\nu}{2} \frac{-i}{2\pi} \int_{-\infty}^{+\infty} aA_{5}(a) e^{-Rx} e^{-iay} da +
$$

$$
\frac{1}{2\pi} \int_{-\infty}^{+\infty} [|a|A_{3}(a) - (2a^{2}\kappa - x|a| + 1)A_{4}(a)] e^{-|a|x} e^{-iay} da , \qquad (3.69)
$$

$$
\beta_{y} = \kappa \frac{1-\nu}{2} \frac{1}{2\pi} \int_{-\infty}^{+\infty} R A_{5}(a) e^{-Rx} e^{-iay} da -
$$
\n
$$
\frac{1}{2\pi} \int_{-\infty}^{+\infty} a \Big[-A_{3}(a) + (2|a| \kappa - x) A_{4}(a) \Big] e^{-|a|x} e^{-iay} da , \qquad (3.70)
$$
\n
$$
M_{xx} = \frac{\gamma}{2\pi} \int_{-\infty}^{+\infty} \Big\{ (1-\nu) a^{2} \Big[(2\kappa|a| - x) A_{4}(a) - A_{3}(a) \Big] +
$$

$$
2|a| \Lambda_4(a)\Big\} e^{-|a| x} e^{-iay} da +
$$

+
$$
\frac{\gamma \kappa}{2} (1-\nu)^2 \frac{1}{2\pi} \int_{-\infty}^{+\infty} aRA_5(\alpha) e^{-Rx} e^{-i\alpha y} d\alpha
$$
, (3.71)

$$
M_{yy} = \frac{-\gamma}{2\pi} \int_{-\infty}^{+\infty} \left\{ (1-\nu) a^2 \Big[(2\kappa |a| - x) A_4(a) - A_3(a) \Big] + 2\nu |a| A_4(a) \right\} e^{-|a| x} e^{-iay} da -
$$

$$
-\frac{\gamma\kappa}{2}(1-\nu)^2\frac{1}{2\pi}\int_{-\infty}^{+\infty}aRA_5(a)e^{-Rx}e^{-iay}da\quad ,\qquad (3.72)
$$

$$
M_{xy} = -\gamma (1-\nu) \frac{i}{2\pi} \int_{-\infty}^{+\infty} \alpha \Big[(x \mid \alpha \mid -2\kappa \alpha^2 - 1) A_4(\alpha) + |\alpha| A_3(\alpha) \Big] e^{-\mid \alpha \mid x} e^{-i\alpha y} d\alpha
$$

$$
-\frac{\gamma\kappa}{4}(1-\nu)^2\frac{1}{2\pi}\int_{-\infty}^{+\infty}(a^2+\kappa^2)A_5(a)e^{-\kappa x}e^{-i\alpha y}\,da\quad,\qquad (3.73)
$$

$$
V_x = -\frac{\kappa}{\pi} \int_{-\infty}^{+\infty} a^2 A_4(a) e^{-\left|a\right| x} e^{-i\alpha y} d\alpha -
$$

$$
- \frac{\kappa}{2} (1-\nu) \frac{i}{2\pi} \int_{-\infty}^{+\infty} a A_5(a) e^{-Rx} e^{-i\alpha y} d\alpha , \qquad (3.74)
$$

$$
V_{y} = -i\frac{\kappa}{\pi} \int_{-\infty}^{+\infty} \alpha |a| A_{4}(a) e^{-|a|x} e^{-iay} da +
$$

+ $\frac{\kappa}{2} (1-\nu) \frac{1}{2\pi} \int_{-\infty}^{+\infty} R A_{5}(a) e^{-Rx} e^{-iay} da$, (3.75)

$$
\frac{\partial^2 u}{\partial y^2} = \frac{1}{2\pi} \int_{-\infty}^{+\infty} \frac{a^2}{a^2} \Big[-(1+\nu) |a| \Lambda_1(a) + \Lambda_2(a) (-1+\nu-|a| \times (1+\nu)) \Big] e^{-|a| \times} e^{-i\alpha y} d\alpha
$$
\n(3.76)

$$
\frac{\partial v}{\partial y} = \frac{1}{2\pi} \int_{-\infty}^{+\infty} \left[(1+\nu) \alpha^2 A_1(\alpha) + A_2(\alpha) (-2|\alpha| + x \alpha^2 + \nu \alpha^2 x) \right] e^{-|\alpha| x} e^{-i\alpha y} d\alpha
$$
\n(3.77)

3.2 Symmetric loading, Mode I.

The symmetry conditions are,

$$
N_{xy}(0, y) = 0 \t (3.78)
$$

$$
\mathbf{M}_{\mathbf{xy}}(0,\mathbf{y}) = 0 \quad , \tag{3.79}
$$

$$
V_{\mathbf{x}}(0,\mathbf{y}) = 0 \quad . \tag{3.80}
$$

After **using** this information in Eqns. 3.68,73,74 we **obtain**

$$
A_1(a) = \frac{1}{|a|} A_2(a) , \qquad (3.81)
$$

$$
A_3(a) = \frac{\kappa (a^2 + R^2) + 1}{|a|} A_4(a) , \qquad (3.82)
$$

$$
A_5(a) = \frac{4ai}{1-\nu} A_4(a) \qquad (3.83)
$$

This eliminates three of the five unknown constants leaving only $A_2(a)$ and $A_4(a)$. The following two mixed boundary conditions will determine them.

$$
N_{xx}(0^+, y) = -f_1(y) \quad , \quad y \text{ in } L_n \quad , \tag{3.84}
$$

$$
u(0^+, y) = 0 \quad , \quad y \text{ outside of } L_n \quad , \tag{3.85}
$$

$$
M_{xx}(0^+, y) = -f_2(y) , y in L_n , \qquad (3.86)
$$

$$
\beta_{\mathbf{x}}(0^+, \mathbf{y}) = 0 \quad , \quad \mathbf{y} \text{ outside of } \mathbf{L}_{\mathbf{n}} \quad , \tag{3.87}
$$

where

$$
L_n = (a_1, b_1), (a_2, b_2), \dots, (a_n, b_n)
$$
 (3.88)

each section (a_i, b_i) defining a crack on $x=0$. Note that since all length quantities are normalized with respect to the plate thickness h, each section is actually $(a_i/h, b_i/h)$. After using Eqns. 3.81-83 in Eqns. 3.66,76,71 and 69 we obtain the following,

$$
N_{xx}(0, y) = \lim_{x \to 0} \frac{-1}{2\pi} \int_{-\infty}^{+\infty} |\alpha| A_2(a) e^{-|\alpha| x} e^{-i\alpha y} d\alpha , \qquad (3.89)
$$

$$
\frac{\partial^2 u}{\partial y^2}\Big|_{x=0} = \frac{\lim_{x \to 0} \frac{-1}{2\pi} \int_{-\infty}^{+\infty} 2A_2(a) a^2 e^{-|a|x} e^{-iay} da , \qquad (3.90)
$$

$$
M_{xx}(0, y) = \lim_{x \to 0} \frac{\gamma \kappa (1 - \nu)}{2\pi} \int_{-\infty}^{+\infty} \left\{ \left[2a^2 |\alpha| + \frac{a (3 + \nu)}{|\alpha| \kappa (1 - \nu)} \right] e^{-|\alpha| x} - 2a^2 \text{Re}^{-\text{Rx}} \right\} A_4(a) e^{-i\alpha y} d\alpha , \qquad (3.91)
$$

$$
\beta_{x}(0,y) = \lim_{x \to 0} \frac{-1}{2\pi} \int_{-\infty}^{+\infty} A_{4}(a) \left[2\kappa a^{2} e^{-Rx} - \kappa (a^{2} + R^{2}) e^{-\alpha x} \right] e^{-i\alpha y} d\alpha \quad .
$$
\n(3.92)

Note that Eqns. 3.89,90 are uncoupled from 3.91,92 for simple f_i(y) in the **mixed** boundary **conditions 3.84,86.**

3.2.1 Tension.

The singular integral equation for tension will be derived first. Consider Eqn. 3.90.

$$
\frac{\partial^2 u}{\partial y^2}\Big|_{x=0} = \frac{1}{2\pi} \int_{-\infty}^{+\infty} -2A_2(\alpha) \alpha^2 e^{-i\alpha y} d\alpha \quad .
$$
 (3.93)

From Eqns. 3.44,45 **we** invert 3.93,

$$
-2a^2A_2(a) = \int_{-\infty}^{+\infty} \frac{\partial^2 u}{\partial t^2}\Big|_{x=0} e^{i\alpha t} dt , \qquad (3.94)
$$

and then integrate by parts twice noting that $u(t)$ is zero at infinity.

$$
-2a^{2}A_{2}(a) = -i\alpha \int_{-\infty}^{+\infty} \frac{\partial u}{\partial t}\Big|_{x=0} e^{i\alpha t} dt , \qquad (3.95)
$$

$$
= -a^2 \int_{-\infty}^{+\infty} u(t) e^{i\alpha t} dt , \qquad (3.96)
$$

 \mathbf{or}

$$
A_2(a) = \frac{1}{2} \int_{L_n} u(t) e^{iat} dt , \qquad (3.97)
$$

where use has been made of Eqn. 3.85. Now $A_2(a)$ is substituted into and the displacement u(t) becomes the only unknown in the Eqn. 3.89 problem. After defining

$$
u_1(t) = u(t) ,
$$

we have,

$$
N_{XX}(0,y) = \frac{\lim_{x \to 0} \frac{-1}{2\pi} \int_{-\infty}^{+\infty} \frac{|a|}{2} \int_{L_n} u_1(t) e^{i\alpha t} dt e^{-|a|x} e^{-i\alpha y} d\alpha \quad , \quad (3.98)
$$

or

$$
N_{xx}(0,y) = \frac{\lim_{x \to 0} \frac{-1}{2\pi} \int_{L_n} u_1(t) \int_{-\infty}^{+\infty} \frac{|a|}{2} e^{-|a|x} e^{ia(t-y)} da dt
$$
 (3.99)

Next using

$$
\lim_{x\to 0} \int_0^{+\infty} a \cos a (t-y) e^{-ax} da = \frac{-2}{(t-y)^2} , \qquad (3.100)
$$

Eqn. 3.99 becomes,

$$
N_{xx}(0, y) = \frac{1}{2\pi} \int_{L_n(t-y)} \frac{u_1(t)}{(t-y)^2} dt \quad , \quad \text{for all } y \quad , \tag{3.101}
$$

 \mathbf{or}

$$
-f_1(y) = \frac{1}{2\pi} \oint_{L_n} \frac{u_1(t)}{(t-y)^2} dt \quad , \quad \text{for } y \text{ in } L_n \quad . \tag{3.102}
$$

For a single crack in tension Eqn. 3.102 becomes,

$$
\frac{1}{2\pi} \int_{-a}^{+a} \frac{u_1(t)}{(t-y)^2} dt = f_1(y) = \hat{N}_{xx} = \frac{\hat{N}_{11}}{hE} = \frac{\hat{\sigma}_1}{E} .
$$
 (3.103)

The solution is

$$
u_1(y) = 2 \frac{\sigma}{E} (a^2 - y^2)^{1/2} \quad . \tag{3.104}
$$

If we substitute this back into Eqn. 3.101, the stress in front of the crack is,

$$
\frac{\sigma_1(y)}{E} = \frac{1}{2\pi} \int_{-a}^{+a} 2 \frac{\sigma}{E} \frac{(a^2 - y^2)^{1/2}}{(t - y)^2} dt = \frac{\sigma}{E} \left\{ \frac{|y|}{(y^2 - a^2)^{1/2}} - 1 \right\} . \quad (3.105)
$$

To determine the stress intensity factor, we use Eqn. G.lO,

$$
k_{1} = \frac{\lim_{y \to a} [2(y-a)]^{1/2} \sigma_{1}(y) , \qquad (3.106)
$$

$$
= \lim_{y \to a} \frac{\int_{0}^{x} (y - a)^{1/2}}{(y + a)^{1/2} (y - a)^{1/2}} = \int_{0}^{\infty} \sqrt{a} \quad .
$$
 (3.107)

Therefore

$$
\frac{k_1}{\sigma_1 \sqrt{a}} = 1 \quad . \tag{3.108}
$$

Now determine the stress intensity factor using Eqn. G.11.

$$
k_1 = \frac{4\mu}{K+1} \lim_{y \to a} \frac{u_1(t)}{\sqrt{2(y-a)}} = \frac{E}{2} \lim_{y \to a} 2 \frac{\frac{\sigma}{E}}{E} \frac{(a^2 - y^2)^{1/2}}{\sqrt{2(y-a)}} = \frac{\sigma}{\sigma} \sqrt{a} \quad , \tag{3.109}
$$

where the following substitutions have been made,

$$
K = \frac{3-\nu}{1+\nu} \quad , \quad \mu = \frac{E}{2(1+\nu)} \quad . \tag{3.110}
$$

Therefore using either stress or displacement the result is the same. This should not be taken for granted because the equations predicting stress and displacement are from plate theory, while the stress intensity factor is defined in terms of elasticity theory. It is important to note that the classical plate theory is identical to Reissner's theory for tension, Eqn. 3.101.

In Fig. 3.1a at the end of the chapter the stress intensity factors for two identical cracks **with** a/h=l are plotted for varying separation distance.

3.2.2 Bending.

For the bending problem from Eqn. 3.91

$$
\beta_{\mathbf{x}}(0,\mathbf{y}) = \mathbf{u}_2(\mathbf{y}) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} A_4(a) \kappa(a^2 - R^2) e^{-i\alpha y} d\alpha \quad . \tag{3.111}
$$

After inversion, making use of Eqn. 3.55, $A_{\underline{A}}(\alpha)$ in terms of the new $unknown, u₂(t)$ is,

$$
A_4(a) = \frac{1-\nu}{2} \int_{L_n} u_2(t) e^{iat} dt
$$
 (3.112)

This is substituted into Eqn. 3.91,

$$
M_{xx}(0,y) = \frac{\lim_{x \to 0} \frac{\gamma \kappa (1-\nu)^2}{2\pi} \int_{L_n} u_2(t) \int_{-\infty}^{+\infty} \left\{ \left[2a^2 |a| + \frac{a (3+\nu)}{|a| \kappa (1-\nu)} \right] e^{-|a| x} - 2a^2 Re^{-Rx} \right\} e^{i a (t-y)} da dt
$$
 (3.113)

After using Eqn. 3.100 and the following integrals,

$$
\lim_{x \to 0} \int_{0}^{+\infty} a^{3} \cos a (t-y) e^{-ax} da = \frac{6}{(t-y)^{4}}
$$
 (3.114)

$$
\lim_{x \to 0} \int_{0}^{+\infty} a^{2} \text{Re}^{-\text{Rx}} \cos a (t-y) da = \frac{1}{2\gamma \kappa (1-\nu)^{2}} \left\{ \frac{4\gamma}{\kappa} \Big[K_{2}(\beta | t-y] \Big) - \frac{4\gamma \kappa (1-\nu)}{\kappa (1-\nu)^{2}} \right\}
$$

$$
K_0(\beta|t-y|)\bigg] + \frac{12\gamma(1-\nu)}{(t-y)^2}K_2(\beta|t-y|)\bigg\}\quad ,\tag{3.115}
$$

where

$$
\beta = \left(\frac{2}{\kappa(1-\nu)}\right)^{1/2} = (10)^{1/2} \quad , \tag{3.116}
$$

we obtain

$$
M_{xx}(0,y) = \frac{1}{2\pi} \int_{L_{n}} u_2(t) \left\{ \frac{-12\gamma\kappa(1-\nu)^2}{(t-y)^4} + \frac{\gamma(1-\nu)(3+\nu)}{(t-y)^2} + \frac{4\gamma}{\kappa} \left[K_2(\beta|t-y|) - K_0(\beta|t-y|) \right] + \frac{12\gamma(1-\nu)}{(t-y)^2} K_2(\beta|t-y|) \right\} dt \quad , \tag{3.117}
$$

which is valid for all y. K_2 and K_0 are modified Bessel functions of the second kind. If y is in L_n , we use Eqn. 3.87 to write,

$$
-f_2(y) = \frac{\gamma(1-\nu^2)}{2\pi} \oint_{L_n(t-y)^2} \mathrm{d}t + \frac{1}{2\pi} \int_{L_n} u_2(t) K_{22}(y,t) \, \mathrm{d}t \quad , \quad (3.118)
$$

where

$$
K_{22}(y,t) = \frac{1}{\kappa} \ln(\beta |t-y|) + \frac{2\gamma(1-\nu)}{(t-y)^2} - \frac{12\gamma\kappa(1-\nu)^2}{(t-y)^4} + \frac{4\gamma}{\kappa} \Big[K_2(\beta |t-y|) -
$$

$$
K_0(\beta|t-y|) + \frac{12\gamma(1-\nu)}{(t-y)^2}K_2(\beta|t-y|) - \frac{\gamma}{\kappa}ln(\beta|t-y|)
$$
 (3.119)

It is convenient to write this Fredholm kernel in terms of a single variable,

$$
K_{22}(y,t) = \frac{5K(z)}{12(1+\nu)} \quad , \quad z = \beta|t-y| \quad , \tag{3.120}
$$

where

$$
K(z) = \left\{ \frac{-48}{z^4} + \frac{4}{z^2} - 4K_0(z) + 4K_2(z) + \frac{24}{z^2} K_2(z) \right\} .
$$
 (3.121)

52

To show *that* K(z) is a Fredholm kernel, the small z expansions for the Bessel functions are,

$$
K_0(z) \sim -\ln(z/2) - \gamma_e - (z/2)^2 \ln(z/2) + 0(z^2)
$$
 (3.122)
\n
$$
K_2(z) \sim 2/z^2 - 1/2 - 1/2(z/2)^2 \ln(z/2) - 1/2(z/2)^2 (\gamma_e + 5/4)
$$
\n
$$
- 1/6(z/2)^4 \ln(z/2) + 0(z^4)
$$
 (3.123)

where Euler's constant, γ_e = .5772157.... Substitution of these expansions into Eqn. 3.121 leads to the following behavior for K(z),

$$
\lim_{z\to 0} K(z) \sim \left\{ \ln(z/2) + (\gamma_e - 23/4) + (z/2)^2 \ln(z/2) + \dots \right\} \quad . \tag{3.124}
$$

For simple plate bending,

$$
f_2(y) = \frac{\mathfrak{A}}{\mathfrak{A}_{xx}} = \frac{\frac{\mathfrak{A}}{\mathfrak{A}}}{h^2 E} = \frac{\frac{\mathfrak{B}}{\mathfrak{B}}}{6E}
$$
 (3.125)

The log singularity has been separated from the Fredholm kernel, see Eqn. 3.119. In such **a** case it was found helpful to handle this part in closed form. However it is possible that the contribution of the log term is nearly equal to, but of opposite sign as the rest of the kernel. Separate treatment here could lead to convergence problems especially for geometries (a/h approaching ® for Eqn. 3.118) where the coefficient of the log term gets large. In many problems this coefficient is small **and a** closed form analysis of the log is not necessary. See Appendix I for the effect of this log behavior on the numerical convergence. It should be noted that if the unknown were the derivative of the rotation, this log term would be replaced by,

$$
(t-y)\ln(\beta|t-y|) , \qquad (3.126)
$$

which is non-singular and easier to integrate (see. Appendix I). This is the least desirable feature of the strongly singular formulation. The Fredholm kernel is essentially divided by (t-y), or alternatively, the infinite integrals which determine the Fredholm kernel decay more slowly by a factor of *a,* see Appendix J, section 4. This means more asymptotic **analysis** for equal decay between the two methods. For example the infinite integral for the tension problem, Eqn. 3.100 **would** be replaced by,

$$
\lim_{x\to 0} \int_0^{+\infty} \sin \alpha (t-y) e^{-\alpha x} d\alpha = \frac{1}{t-y}
$$
 (3.127)

In most problems the infinite integrals must be evaluated numerically so this factor of a becomes important, see Chapter 5.

For **a** single crack of half length **a,** Eqn. 3.118 may be **written** as

$$
\frac{h}{24a\pi} \int_{-1}^{+1} \frac{u_2(\frac{a}{h}r)}{(r-s)^2} dr + \frac{5a}{12h(1+\nu)} \frac{1}{2\pi} \int_{-1}^{+1} u_2(\frac{a}{h}r) K(\frac{a}{h}\beta|r-s|) dr = -\frac{8a}{M_{XX}},
$$

-1

If we define

$$
u_2(t) = \frac{24a}{h} \stackrel{\circ}{M}_{xx} g(r)
$$
, $\zeta = \frac{a}{h} \beta |r-s| = z = \beta |t-y|$, (3.129)

the equation becomes,

$$
\frac{1}{\pi} \int_{-1}^{+1} \frac{g(r)}{(r-s)^2} dr + \frac{5}{\pi (1+\nu)} (a/h)^2 \int_{-1}^{+1} g(r)K(\zeta) dt = -1 , \qquad (3.130)
$$

This equation must be solved numerically, see Appendix E for an explanation of the collocation method. From section 2 of Appendix G, *and* Eqn. 3.130 the stress intensity factor (actually the maximum value at the plate surface) **will** be given by,

$$
\frac{k_1}{\sigma_2 \sqrt{a}} = f(1) = f(-1) \quad , \tag{3.131}
$$

where

$$
g(r) = f(r) (1 - r^2)^{1/2} , -1 \leq r \leq 1 . \qquad (3.132)
$$

ï

The stress intensity factor of Eqn. 3.131 is **predicted by either** stresses (Eqn. G.IO) or **displacements** (Eqn. G.11).

The governing **equations for classical** plate **bending are** identical to **3.1-20** with the **exception** that the transverse **shear deformation,.** 0. in Eqns. **3.18,19 are** ⁱ **zero, or B (Eqn. 3.20)** is infinite. The symmetry conditions, Eqns. 3.78–80, cannot be separately satis: For classical plate bending,

$$
N_{XY}(0, y) = 0 \t (3.133)
$$

$$
\frac{\partial M}{\partial y} + V_x(0, y) = 0 \quad . \tag{3.134}
$$

The result **of** this **formulation for** the **determination of** the **rotation** is,

$$
\frac{3+\nu}{1+\nu}\frac{h}{24a} \frac{1}{\pi} \int_{-1}^{+1} \frac{u_2(\frac{a_1}{h}r)}{(r-s)^2} dr = -\frac{a_1}{x} \qquad , \quad -1 \leq s \leq 1 \qquad , \tag{3.135}
$$

or in terms of $g(r)$,

$$
\frac{3+\nu}{1+\nu}\frac{1}{\pi}\int_{-1}^{+1}\frac{g(r)}{(r-s)^2} dt = -1
$$
 (3.136)

This equation can be solved in closed **form.**

$$
\frac{\sigma_2(y)}{6E} = \frac{\sigma_2}{6E} \left\{ \frac{|y|}{[y^2 - (a/h)^2]^{1/2}} - 1 \right\} , \qquad (3.137)
$$

$$
u_2(y) = \frac{1+\nu}{3+\nu} \frac{24a}{h} \frac{\sigma_2}{6E} \sqrt{1 - \left(\frac{h}{a}y\right)^2} , \quad -a/h \langle y \langle a/h \rangle . \tag{3.138}
$$

Eqn. 3.137 predicts

$$
\frac{k_1}{\sigma_2 \sqrt{a}} = 1 \quad , \tag{3.139}
$$

while Eqn. 3.138 predicts

$$
\frac{k_1}{\sigma_2 \sqrt{a}} = \frac{1+\nu}{3+\nu} \tag{3.140}
$$

This inconsistency shows that the **classical** plate theory **is** inadequate to solve for **crack** tip SIFs for bending. It **is** also true for out-ofplane shear and for twisting.

In Fig. **3.2** the normalized stress **intensity** factor as a function of **crack** length to plate thickness ratio is plotted for Reissner's theory. Table **3.1** lists some values. Note that for large h/a the limit **is** one, the same as the **classical** prediction using the stress intensity factor defined in terms of stress, Eqn. **3.139.** The other limit, the thin plate limit, is not so **clear.** It has been reported by [6] that in the limit as h/a goes to zero, the stress intensity factor for the Reissner plate, (Eqn. 3.131) approaches the value $(1+\nu)/(3+\nu)$ as predicted by Eqn. 3.140 from the classical theory, (note that h=O is not valid for Reissner's theory). Another way of putting this is that Eqn. 3.130 becomes 3.136. The evidence provided by table 3.1 for **a/h** *=* 1000 seems to indicate that this is not the case. Numerically it is very difficult to obtain convergent results in the long crack/thin plate domain using the methods of Appendix E, and for further results some kind of asymptotic analysis with a specially suited numerical scheme seems appropriate. As an aside, for this geometry, a power series (Eqn. E.29) was not adequate using single precision (14 digits). The coefficients were as high as $1.×10^{15}$, for **example** see table **E.1. The problem** was solved **using Chebychev** polynomials. The following **analysis** is provided to support the **claim** that the curve in Fig. 3.2 does not "reach" the value $(1+\nu)/(3+\nu)$.

3.2.3 Thin **Plate** Bending.

We consider the large **a/h** limit of **Eqn. 3.130.** Only the **Fredholm** kernel need be analyzed. First define

$$
I(s, a/h) = \frac{5}{\pi (1+\nu)} (a/h)^2 \int_{-1}^{+1} g(r)K(\zeta) dr
$$

=
$$
\frac{\rho^2}{2\pi (1+\nu)} \int_{-1}^{+1} g(r)K(\zeta) dr , \qquad (3.141)
$$

where $\rho = \beta(a/h)$ is introduced for convenience. From Appendix H,

$$
\lim_{\rho \to \infty} I(s, a/h) = \frac{2}{\pi (1+\nu)} \int_{-1}^{+1} \frac{g(r)}{(r-s)^2} dr = \frac{2}{\pi (1+\nu)} \int_{-1}^{+1} \frac{g'(r)}{r-s} dr , |s| < 1,
$$
\n(3.142)

$$
= \frac{2}{\pi (1+\nu)} \int_{-1}^{+1} \frac{g(r)}{(r-s)^2} dr = \frac{2}{\pi (1+\nu)} \int_{-1}^{+1} \frac{g'(r)}{r-s} dr , |s|>1 ,
$$
\n(3.143)

 $= ?$, y "near" 1, ie. $\rho(1-y) = 0(1)$. (3.144)

If Eqn. 3.142 were valid for $|s|=h/a|y| \le 1$ then in the limit as ρ approaches infinity, Eqn. 3.130 would be identical to **Eqn.** 136 and therefore the stress intensity factor would be $(1+\nu)/(3+\nu)$. But this is not the case. Figs. 3.3a-c **compare** I(s,a/h) to the limiting

integrals above. The numerically determined function for g(r) was used to compute these integrals. See Figs. 3.4-5 for plots of $g(r)$, $f(r)$ as defined in Eqn. 3.132, and Fig. 3.6 for the ratio of $g(0)$ from *Reissner's* theory to g(O) from the classical theory. Also see table 3.2 for numerical values of this ratio. This table shows that in the limit as h+0, Reissner's theory behaves like the classical theory away from the crack tip. **With** regard to Fig. 3.3, the distinct difference between I(s,a/h) and the limiting integrals is that $I(s, a/h)$ is continuous at s=1. The "spike" created when $I(s, a/h)$ goes from 1⁻ to 1⁺ gives a contribution to the stress intensity factor that makes it different from $(1+\nu)/(3+\nu)$. This contribution is of significance because it is located at the crack tip. In order to proceed further in the analysis, the area of the spike, which would represent **a** normalized force (or couple), must be determined. Consider the following:

$$
M = \lim_{\rho \to \infty} \int_0^{+1} \left\{ \frac{\rho^2}{2\pi (1+\nu)} I(s, a/h) + \frac{2}{3+\nu} \right\} ds , \qquad (3.145)
$$

$$
= \lim_{\rho \to \infty} \frac{\rho^2}{2\pi (1+\nu)} \int_{-1}^{+1} g(r) \int_{0}^{+1} K(\zeta) ds dr + \frac{2}{3+\nu} , \qquad (3.146)
$$

$$
= \lim_{\rho \to \infty} \frac{\rho}{2\pi (1+\nu)} \int_{-1}^{+1} g(r) \left\{ \frac{-16}{u^3} + \frac{4}{u} + \frac{8}{u} K_2(u) \right\} dr + \frac{2}{3+\nu} , \quad u = \rho(1-r) .
$$
\n(3.147)

Again the behavior of this integral near r=l makes it difficult to **analyze.** Note that the order one contribution to M coming **from** the "outer solution" of g(r), Eqns. 3.129,138, drops out.

The limiting value of the stress intensity factor was not four but we can make the following conclusion. Since l(s,a/h) for {sl>l has the behavior **of** Eqn. 3.143,

$$
\lim_{\rho \to \infty} \lim_{s \to 1^+} I(s, a/h) \sim \frac{1}{1-s} , \qquad (3.148)
$$

where from Eqn. 3.143, **it** may be stated *that*

$$
\lim_{\rho \to \infty} \lim_{s \to 1^+} I(s, a/h) \sim \sqrt{\rho} \quad . \tag{3.149}
$$

This order analysis is supported by Fig. 3.3. This tells us that th **magnitude** of the integrated **Fredholm kernel,** i.e. I(s,a/h), which represents a normalized stress resultant *term,* (aCtually **a** couple), becomes **infinite according** to Eqn. 3.149. Again since we **are** dealing with a region where $p(1-s)$ is of order one, the "thickness" or support of the spike is of order $(1-s)$ or ρ^{-1} . Therefore the area under the spike, given by eqn 3.147, which represents normalized force, should go to zero as $\rho^{-1/2}$. In order to determine the stress intensity factor for h/a approaching zero the **coefficient of** this leading order term must be known. If the area were of order one, the contribution to the stress intensity factor would be of order $(1-s)^{-1/2}$, see Sih [72]. If the value of stress resultant were of order one, the area would be zero **and** there would be no contribution. But the limit is between these two cases and the contribution is finite, probably resulting in a stress intensity factor that can be drawn within the space provided by the lower plot of Fig. 3.2.

Some other results for the bending problem **are** given at the end of the chapter. In Fig. 3.7 the normalized bending stresses ahead of the crack tip are plotted for **a/h=l** and 10 (Eqn. 3.117). In table 3.3

59

some results for crack interaction are listed for four different crack length ratios, (this table may also be found in [59]). Fig. 3.1 provides a plot of the interaction of equal length cracks where a/h=l for tension, bending, out-of-plane shear and twisting to compare how strong the interaction is for the various loadings. In-plane-shear is identical to tension, (shown later in this chapter).

3.3 Skew-Symmetric loading, Modes 2 & 3

The symmetry conditions are

$$
N \quad (0, y) = 0 \quad , \tag{3.150}
$$

$$
\mathbf{M}_{\mathbf{XX}}(0,\mathbf{y}) = 0 \quad . \tag{3.151}
$$

After using this information in Eqns. 3.66,71 we obtain,

$$
A_1(a) = 0 \t{3.152}
$$

$$
A_3(a) = \left\{ 2\kappa |a| + \frac{2}{(1-\nu)|a|} \right\} A_4(a) + \frac{i\kappa}{2a} (1-\nu) R A_5(a) \quad . \tag{3.153}
$$

This eliminates two of the five unknown constants leaving only $A_2(a)$, $A_4(a)$ and $A_5(a)$. The following mixed boundary conditions will determine them.

$$
V_{x}(0^{+}, y) = -f_{3}(y) \quad , \quad y \text{ in } L_{n} \quad , \tag{3.154}
$$

$$
w(0^+, y) = 0 \quad , \quad y \text{ outside of } L_n \quad , \tag{3.155}
$$

$$
N_{xy}(0^+, y) = -f_4(y) , y in L_{n} , \qquad (3.156)
$$

$$
v(0^+, y) = 0 \quad , \quad y \text{ outside of } L_n \quad , \tag{3.157}
$$

$$
M_{xy}(0^+, y) = -f_5(y) , y in L_n , \qquad (3.158)
$$

$$
\beta_{\mathbf{y}}(0^+, \mathbf{y}) = 0 \quad , \quad \mathbf{y} \text{ outside of } \mathbf{L}_{\mathbf{n}} \quad . \tag{3.159}
$$

If Eqns. 3.152,153 are substituted into Eqns. 3.52,68,70,73,74 and 77, the quantities appearing in 3.154-159 may be expressed in terms of the unknowns as follows:

$$
W_{\mathbf{x}}(\mathbf{x}, \mathbf{y}) = \frac{-\kappa}{\pi} \int_{-\infty}^{+\infty} a^2 A_4(a) e^{-|a| \mathbf{x}} e^{-i\alpha y} da
$$

$$
- \frac{\kappa}{2} (1-\nu) \frac{i}{2\pi} \int_{-\infty}^{+\infty} a A_5(a) e^{-Rx} e^{-i\alpha y} da \qquad , \qquad (3.160)
$$

$$
w(x,y) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} \left\{ A_4(a) \left[2\kappa |a| + \frac{2}{(1-\nu)|a|} + x \right] + A_5(a) \frac{i\kappa}{2a} (1-\nu) R \right\} e^{-|a|x} e^{-i\alpha y} d\alpha \quad , \tag{3.161}
$$

$$
N_{xy}(x,y) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} a(1-x|a|) A_2(a) e^{-|a|x|} e^{-i\alpha y} d\alpha \qquad (3.162)
$$

$$
\frac{\partial \mathbf{v}}{\partial \mathbf{y}} = \frac{1}{2\pi} \int_{-\infty}^{+\infty} A_2(a) \left[a^2 x - 2|a| + \nu x a^2 \right] e^{-|a|x} e^{-i\alpha y} d\alpha \quad , \tag{3.163}
$$

$$
M_{xy}(x,y) = -\gamma(1-\nu)\frac{i}{2\pi}\int_{-\infty}^{+\infty} \left\{ A_4(\alpha) \left[xa \mid a \mid -a + \frac{2a}{1-\nu} \right] + \frac{i\kappa}{2}(1-\nu) R |a| A_5(\alpha) \right\} e^{-\left[a \mid x \right]} e^{-i\alpha y} d\alpha
$$

$$
-\frac{\gamma_{\alpha}}{4}(1-\nu)^{2}\frac{1}{2\pi}\int_{-\infty}^{+\infty}(\alpha^{2}+\beta^{2})A_{5}(\alpha)e^{-\beta x}e^{-i\alpha y}d\alpha , \qquad (3.164)
$$

$$
\beta_{y}(x,y) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} \left\{ A_{4}(a) \left[x + \frac{2}{(1+\nu)|a|} \right] + \frac{\frac{1}{2}\kappa}{2a} (1-\nu) R A_{5}(a) \right\} e^{-\frac{1}{2}\alpha x} e^{-\frac{1}{2}ay} da + \frac{\kappa}{2} (1-\nu) \frac{1}{2\pi} \int_{-\infty}^{+\infty} R A_{5}(a) e^{-Rx} e^{-iay} da
$$
\n(3.165)

Note that N_{xy} is uncoupled from M_{xy} and V_{x} . The integral equation for N can be seen to be the same as for tension, compare Eqns. 3.89, xy with 3.162,163. The result for

$$
u_{4}(t) = v(0^{+}, t) , \qquad (3.166)
$$

is

$$
N_{xy}(0, y) = \frac{1}{2\pi} \int_{L_n} \frac{u_4(t)}{(t-y)^2} dt \quad , \quad \text{for all } y \quad , \tag{3.167}
$$

or

$$
-f_4(y) = \frac{1}{2\pi} \oint_{L_n(t-y)} \frac{u_4(t)}{(t-y)^2} dt \quad , \quad \text{for } y \text{ in } L_n \quad . \tag{3.168}
$$

For in-plane-shear,

$$
f_4(y) = \mathcal{R}_{xy} = \frac{\mathcal{R}_{12}}{hE} = \frac{\mathcal{Z}}{E}
$$
 (3.169)

All through crack results **for** tension **are also valid** for in-planeshear. To solve the coupled problem of M_{xy} and V_x , first define

$$
u_3(t) = w(0^+, t)
$$
, $u_5(t) = \beta_y(0^+, t)$. (3.170)

The unknowns $A_4(a)$ and $A_5(a)$ can then be expressed as,

$$
A_4(a) = \frac{-i(1-\nu)|a|}{2a} \int_{L_n} u_5(t) e^{iat} dt , \qquad (3.171)
$$

$$
A_{5}(a) = \frac{-2i a}{\kappa R(1-\nu)} \int_{L_{n}} u_{3}(t) e^{iat} dt
$$

+
$$
\left[\frac{2a^{2}}{R} + \frac{2}{\kappa R(1-\nu)}\right] \int_{L_{n}} u_{5}(t) e^{iat} dt
$$
 (3.172)

It remains only to substitute these expressions into Eqns. 3.160 and]64 and to evaluate the infinite integra]s in a way similar to the bending problem. The equations become,

$$
V_{x}(0,y) = \frac{1}{2\pi} \int_{L_{n}} \left\{ u_{3}(t) \left[\frac{2}{(t-y)^{2}} + K_{33}(z) \right] + u_{5}(t) K_{35}(z) \right\} dt , \quad (3.173)
$$

$$
M_{xy}(0,y) = \frac{1}{2\pi} \int_{L_n} \left\{ u_5(t) \left[\frac{\gamma(1-\nu^2)}{(t-y)^2} + K_{55}(z) \right] + u_3(t) K_{53}(z) \right\} dt \tag{3.174}
$$

where

$$
K_{33}(z) = \beta^2 \Bigl\{-\ln(z) + \Bigl[K_2(z) - \frac{2}{z^2}\Bigr] + \Bigl[K_0(z) + \ln(z)\Bigr]\Bigr\} , \qquad (3.175)
$$

$$
K_{35}(z) = \beta \left\{ \frac{8}{z^3} - \left[z + \frac{4}{z} \right] K_2(z) + z K_0(z) \right\} , \qquad (3.176)
$$

$$
K_{55}(z) = \frac{5}{12(1+\nu)} \Biggl\{ \ln(z) + \Bigl[\frac{48}{z^4} - \frac{4}{z^2} + 4K_0(z) - 4K_2(z) - \frac{24}{z^2} K_2(z) \Bigr] \Biggr\}
$$

+
$$
\ln(z)
$$
 - $\left[2K_0(z) + 2\ln(z)\right]$, (3.177)

$$
K_{53}(z) = \frac{5\beta}{12(1+\nu)} \left\{ \frac{-8}{z^3} + \left[z + \frac{4}{z} \right] K_2(z) - z K_0(z) \right\} \quad . \tag{3.178}
$$

If Eqns. 3.154,158 are applied to 3.173,174 the singular integral equations become,

$$
\frac{1}{2\pi} \oint_{L_n} \frac{2u_3(t)}{(t-y)^2} dt + \frac{1}{2\pi} \int_{L_n} \left\{ u_3(t)K_{33}(z) + u_5(t)K_{35}(z) \right\} dt = -f_3(y)
$$
\n(3.179)
\n
$$
\gamma (1 - \nu^2) \frac{1}{2\pi} \oint_{L_n} \frac{u_5(t)}{(t-y)^2} dt + \frac{1}{2\pi} \int_{L_n} \left\{ u_5(t)K_{55}(z) + u_3(t)K_{53}(z) \right\} dt
$$
\n
$$
= -f_5(y) \qquad (3.180)
$$

The through crack loading for out-of-plane shear is,
$$
f_3(y) = \sqrt[8]{x} = \frac{12(1+\nu)}{5Eh} \sqrt[8]{1} = \frac{8(1+\nu)}{5E} \frac{\infty}{\sigma_3}
$$
 (3.181)

and for twisting,

$$
f_5(y) = \mathbb{N}_{xy} = \frac{\mathbb{N}_{12}}{h^2 E} = \frac{\sigma}{6E}
$$
 (3.182)

For small z,

$$
K_{33}(z) \sim \beta^2 \Bigl\{-\ln(z/2) - (1/2 + \gamma_e) - 3/2(z/2)^2 \ln(z/2) + \ldots \Bigr\} \quad , \quad (3.183)
$$

$$
K_{35}(z) \sim \beta \Big\{-z/2\ln(z/2) + (9/8-\gamma_e/2) z - 2/3(z/2)^3 \ln(z/2) + \ldots \Big\} , (3.184)
$$

$$
K_{55}(z) \sim \frac{5}{12(1+\nu)} \Big\{ \ln (z/2) + (\gamma_e + 23/4) - (z/2)^2 \ln (z/2) + \ldots \Big\} , \quad (3.185)
$$

$$
K_{53}(z) \sim \frac{5\beta}{12(1+\nu)} \Big\{ (z/2) \ln(z/2) + (\gamma_e/2 - 9/8) z + 2/3 (z/2)^3 \ln(z/2) + \dots \Big\} \quad .
$$
\n(3.186)

The effect of this behavior **on** convergence is shown in Appendix I.

The **collocation method** was **used** to solve Eqns. **3.179,180** with **f(y)** given by **3.181,182** for **a** single **crack,** (tables 3.4-6, see **also** Ref. [15]), for two identical interacting cracks, (Figs. **3.1c,d), and** for two interacting cracks **of** different size, (table **3.7a,b).** The notation for the double crack is given in Fig. 3.8a,b. For **a** single crack, the stresses **ahead** of the crack tip **are** plotted in Figs. **3.ga,b.**

Table 3•1 The effect of **Poisson's ratio v and crack length** to **plate** thickness **ratio a/h on** the normalized bending stress **intensity factor.** See also Figure $3.2.$ $\sigma = 6M/h^2$.

$$
\frac{\mathbf{k}_1(\mathbf{h}/2)}{\sigma \sqrt{\mathbf{a}}}
$$

Table **3.2 The ratio** of **crack** surface rotation for Reissner's theory to that of the classical theo at the center of a cracked-plate-subjected-to bending, ν =.3. See also Figure 3.6.

 $\ddot{}$

• 66

Table 3.3 Bending stress intensity **factors** for a

OUT-OF-PLANE SHEAR TWISTING

OUT-OF-PLANE **SHEAR** TWISTING

 a/h

Table 3.6 The effect of crack length to pla thickness ratio a/h on the normalized stre intensity factors for out-of-plane shear **and** for twisting. $\sigma_3=3V/(2h)$, $\sigma_5=6M/h^2$, $\nu=.5$

OUT-OF-PLANE SHEAR TWISTING

7O

 \bullet

Figure 3.1a-d **Normalized** stress intensity **factors** in a **plate with** two identical collinear cracks **of** half length a/h=l loaded in tension (a), bending (b), out-of-plane shear (c), and twisting (d). $\mu = 0$, $\sigma_1 - \nu_{XX}/\mu$, $\sigma_2 - \nu_{\nu_{XX}}/\mu$, $\sigma_3 - \nu_{X}/(\nu_{H})$, $\sigma_4 - \nu_{\nu_{XY}}/\mu_{XY}$

Figure 3.2 Normalized stress intensity factors in a plate for bending, $\nu = .3$, $\sigma = 6M_{xx}/h^2$.

Figure 3.3a-c Plots of the Fredholm integral term Figure 3.3a-c 1100s of the Fredholm Integral term
from Reissner's theory of plate bending (Eqns.
3.129, 140) for $a/h=10$ (a), $a/h=100$ (b), $a/h=1000$
(c), (solid lines), compared to the limit from
Appendix E, (dashed line

Figure 3.3 continued.

Figure 3.3 continued.

Figure **3.4** plots **of** the normalized rotation for plate bending for a/h=10,100,1000 from Reissner theory compared to classical theory, $\nu = .3$

$$
\beta(y/a) = (a/h) (\overset{\bullet}{\sigma}/E) g(y/a).
$$

 \overline{a}

3.5 plots of the normalized rotation Figure divided by the weight function, $[1-(y/a)^2]^{1/2}$ for plate bending for a/h=10,100,1000 from Reissner's theory compared to classical theory, $\nu = .3$ $\beta(y/a) = (a/h) (\sigma/E) f(y/a) [1-(y/a)^{2}]^{1/2}.$

Figure 3.6 The ratio of crack surface rotation for Reissner's theory to that of the classical theory
at the center of a cracked plate subjected to
bending, ν =.3. See also Table 3.2.

Figure 3.7 Bending stresses in front of the crack
tip for $a/h = .5, 10.$ $\nu = .3$

Figure 3.8a, b Geometry of the double crack for (a) unequal length and (b) equal length cracks.

 $\bar{\tau}$:

Figure 3.9a,b Stresses in front of the crack tip resulting from out-of-plane shear loading (a), and from twisting (b). $\nu = .3$

Figure 3.9a, b continued.

CHkPTBR 4

Part-Through Cracks in **Plates**

The singular integral **equations** for **part-through** crack **problems** are obtained **directly** from the corresponding through crack equations combined with the compliance relations **of** Chapter **2.** The edge crack SIFs needed for these relations are **derived** and **presented** in Appendix C. All line-spring model (LSM) solutions presented in this section are normalized with respect to the **edge** crack solution for the corresponding loading and crack **depth** at the center of the given partthrough crack, see section C.4 of **Appendix** C.

4.1 **Mode** 1.

From Eqns. 3.102,118, **2.31,** and from the superposition of Fig. 2.4, the integral equations for the symmetrically loaded part-through crack are,

$$
\frac{1}{2\pi} \oint_{L_n(t-y)} \frac{u_1(t)}{2} dt - \gamma_{11} u_1(y) - \gamma_{12} u_2(y) = -\tilde{N}_x = -\tilde{\sigma}_1 ,
$$
\n(4.1)
\n
$$
\frac{\gamma(1-\nu^2)}{2\pi} \oint_{L_n(t-y)} \frac{u_2(t)}{2} dt + \frac{5}{12(1+\nu)} \frac{1}{2\pi} \int_{L_n} u_2(t)K(z) dt - \gamma_{12} u_1(y) - \gamma_{22} u_2(y) = -\tilde{N}_x = -\tilde{\sigma}_2 / 6 ,
$$
\n(4.2)

where

$$
z = \beta |t-y| \qquad (4.3)
$$

$$
K(z) = \left\{ \frac{-48}{z^4} + \frac{4}{z^2} - 4K_0(z) + 4K_2(z) + \frac{24}{z^2} K_2(z) \right\} .
$$
 (4.4)

This problem has **already** been solved for a Reissner plate [48]. The early line-spring model stress intensity **factor** solutions utilized the classical plate bending theory which in **Chapter** 3 was shown to be inadequate **for** through crack stress intensity factor determination. Recall that the LS_ provides stress intensity **factors along** the crack **front** of **a** surface crack such that -a<y<a, while the solution to **a** through crack gives the SIF at y=_a. **For** the classical **formulation,** Eqn. *4.2* is replaced with,

$$
\frac{3+\nu}{1+\nu}\frac{\gamma(1-\nu^2)}{2\pi}\oint_{L_n}\frac{u_2(t)}{(t-y)^2} dt - \gamma_{12}u_1(y) - \gamma_{22}u_2(y) = -\frac{u_1}{x}, \qquad (4.5)
$$

while Eqn. 4.1 **slays** the same. It was also shown in Chapter 3 that for large a/h the Reissner plate bending **rotation** approaches that of the classical solution except at the endpoints, see Figs. 3.4-6 and table 3.2. Since the LSM does not use the solution at the endpoints, it is expected that for long cracks, the classical and Reissner theories become identical. This is shown in Figs. 4.1-4 where the LSM for both theories is compared to the 3-D Finite element solution of Newman and Raju, [33], see also [43]. In these figures Kit and Klb correspond to the edge-cracked strip SlF solution for tension and bending respectfully. For a/h smaller than about 2, which is the realistic geometry range for part-through cracks, the transverse shear theory **shows** significant improvement over the classical theory. For larger a/h it **seems** that the extra expense of integrating the Fredholm kernel, Eqn. 4.4, is unnecessary. Also as a/h gets larger, the numerical **solution** of 4.1,2 gets more difficult. With regard to table 3.2, it is rather surprising that the classical theory gives such good results for a/h as small as 2. Probably the reason is that tension, which is the same for both theories, dominates the behavior of the solution. Otherwise the difference would be of the order of 10% for a/h as high as 7.

In tables 4.1-10a,b the normalised SIFs along the crack front for both rectangular (a) and semi-elliptical (b) cracks are listed for tension and bending. The value of the normalized SIF at the center of a semi-elliptical crack for various crack lengths and depths is given in table 4.11 and the effect of Poisson's ratio on this quantity is shown in table 4.12. The only difference between this solution and the previous solutions **which** use Reissner plate theory [48] is the compliance functions, i.e. γ_{ij} of Eqns. 4.1,2. For $\xi \leq 0.8$ the curves used here, Eqns. C.102 with coefficients listed in table C.2, are slightly more accurate, see Bqns. C.108,109. This improved accuracy is minimized after going through the solution process because of normalization such that the results of tables 4.1-10 differ from those using Bqns. C.102 by at most .002, an insignificant amount considering the approximate nature of the model. The contribution given here is for deep cracks, i.e. $.8<\xi$ s.95. As noted in Appendix C, th compliance curves can actually be extrapolated to $\xi=1$ because the match the **asymptotic** behavior given by Benthem and Koiter [65]. Although the values in these tables for crack depths of .9 and .95 are small, the normalization factor, which is the corresponding stress intensity factor for the edge-cracked strip, is very large. Tables 4.13,14 list the stress intensity factors at the maximum penetration

point of a semi-elliptical crack normalized with respect-to-th solution **of** the edge-cracked strip **for** both the corresponding depth (4.13a,14a) and **for** comparative purposes, with respect to a depth of $.2 \quad (4.13b,14b)$. The results for tension, table 4.13, show that the driving force, (dimensional SIF), does not simply increase with crack depth like the solution for the edge crack. For bending, table 4.14, the driving force is maximum **for** shallow cracks because of the constraining effect of the ends which actually causes interference and negative SIFs for deep cracks **as** discussed in the next section.

4.1.1 Contact Bending

The boundary **conditions** of the bending through **crack** problem specify the crack surface loading, $\overset{\bullet}{\sigma}_{2}$. This can only be satisfied i tension is applied (superimposed) to open the crack to prevent interference due to bending rotation. The crack opening displacements due to tension and bending loads **are** such that contact will first occur at the ends of the crack, therefore the condition for no contact is satisfied if the combined stress intensity factor (tension plus bending component) at the corner on the compressive side of the plate is *zero.* The necessary ratio of tension to bending is

$$
\frac{\frac{\sigma}{\sigma_1}}{\frac{\sigma}{\sigma_2}} \ge \frac{k_1(h/2)}{\frac{\sigma}{\sigma_2 \sqrt{a}}},
$$
\n(4.6)

where the subscript **D** refers to dimensional.

There is a similar problem with bending of a part-through crack. As can be seen from tables 4.1-10a,b, the stress intensity factors due to bending **change** sign as the **crack** gets deeper. Since **a** negative SIF has no meaning, these solutions require a superposition of a tensile solution to make K/K_{Ob}²⁰. The contact curve for the through crack ® **case where** g I is zero in Eqn. **4.6, can** be obtained from the linespring model by finding the K/K_{Ob}=0 curve. Along this curve, imagined to be a **crack front,** the **crack** opening displacement is **cusp** shaped. This solution is obtained by an iterative process where the "crack depth" L(y)/h, is the unknown **and** the **condition**

$$
K = \sqrt{h} \left[\sigma_1 g_1(y) + \sigma_2 g_2(y) \right] = 0 \quad , \tag{4.7}
$$

is used to determine it. These **curves** for various a/h values **are** given in table 4.15. A more useful problem is to determine th reduction in the stress intensity factor at the corner for bendi **with** interference, see Fig. 4.5. The line-spring model **can** be used to approximate this quantity **as** shown in the next section.

4.1.2 Using the LSM to Calculate SIFs at the Corners

In the development of the line-spring model, the net ligament of the part-through crack is replaced with "net ligament" stresses. In solving the problem these strcsses are determined. There is no difference between this problem and a through crack problem **with** these net ligament stresses **applied** as additional **crack** surface loads. Therefore in the same **way** that SIFs are calculated **for** a through crack, SIFs at the corners of a surface crack, i.e. y= $+a$, $z=h/2$ can be calculated and with no extra work. The problem **with** this idea is that close to the endpoints the net ligament stresses as provided by the

89

 $(- 2)$

model **are** not accurate and this has **a** significant effect on the crack tip stress intensity factors.

As discussed in Chapter 2, section **2.3 and** in Appendix C, the crack shape controls the endpoint behavior. For example the net ligament stresses **are** forced to zero **at** the ends of **a** rectangular crack yet have **a** square **root** singularity in the case **of** a semiellipse. In Appendix F it is shown that for the ellipse the stress intensity factor **at** the corner **as** predicted by the LSM is zero. Numerically this could not be shown but the results indicate a diminishing value as more terms are taken in solving the integral equation. The only crack profile that will make the net ligament stresses finite is the 1/4 power curve, i.e.

$$
L(y)/h = \xi = \xi_0 (1-s^2)^{1/4} \quad . \tag{4.8}
$$

The technique of section **2.3, presented again** in **Eqns.** 4.0,10, where this behavior is imposed **at** the ends of the crack profile in order to get well behaved net ligament stresses, did not work. The corner stress intensity factor was too sensitive to M, the number of terms in the series giving the crack profile:

$$
\xi = \xi_0 (1 - s^2)^n \simeq \xi_0 (1 - s^2)^{1/4} h(s) \quad , \tag{4.9}
$$

where

$$
h(s) \approx (1-s^2)^{n-1/4} \approx \sum_{i=0}^{M} a_i s^{2i}
$$
 (4.10)

Probably the best geometry for approximating the corner stress intensity factor is one for which crack depth at the end is non-zero. In this case as noted previously the net ligament stresses as predicted by the line-spring model go to zero at the endpoints. Since the net ligament stresses restrict the crack from opening, the error of the method should overestimate the correct value of the SIF. Note that the "actual" net ligament stresses (normalized with respect to the stress at "infinity") are probably between zero (for deep cracks) **and** one (for shallow **cracks), while** the normalized **applied** perturbation load is negative one.

The simplest problem that satisfies this geometry **condition** is the rectangular **crack.** The tension **and** bending **cases are** given in Fig. 4.6 as **a function** of the **crack** depth **for a/h=1.** Note that **as** the **crack** depth goes to one, the through **crack** value is approached in **a** manner similar to the **case when** two **collinear cracks approach each** other **where** behavior **at** the outer **crack** tip resembles that of one long **crack** instead of two, see Figs. **3.1a-d.** In Fig. **4.7** plots similar to those of Fig. **4.6 are presented for** the **crack** shape given in Eqn. 4.8. This **figure** is included only **for purposes** of **comparison.**

The **contact** problem of the last section also satisfies the condition of non-zero crack depths at the ends. Results for the "corrected" bending stress intensity factor are presented in Fig. 4.8. This plot shows how the interference of bending reduces the stress intensity factor from the value calculated **when** Eqn. 4.6 is assumed to be satisfied.

This method is of course very approximate. From the results of Fig. 4.6 it seems as though the tension case is **wrong** because the stress intensity factor exceeds the through crack value of one. This is due to the **contribution** from induced bending. It is conceivable that at the corner opposite the constraint, crack growth is more likely than without the constraint although total failure of the plate is less likely. In Newman's finite element results, [33], there are some geometries where this occurs but only by about 2% (k(h/2)/ σ ¹a =1.023 for $a/h=.4$, $L_0/h=.8$), not the 20% that is calculated here, although it should be noted that the semi-ellipse has a constraining effect on the corner that the rectangle does not. I believe that the trend is correct, however the result should be considered only approximate.

Perhaps a method for approximating the value of the SIF at the corner of a semi-ellipse, or for any other profile, is to use the rectangular crack that has an equal amount of net ligament as the shape being considered. This simply results in a shift along the L_0/h axis of Fig. 4.6. For the semi-ellipse this shift factor which results from **equating** the area of an **ellipse** to that of a rectangle is:

$$
(L_0/h)_{\text{rectangle}} = (\pi/4) (L_0/h)_{\text{semi-ellipse}} \tag{4.11}
$$

In Fig. 4.9 this shifted curve is presented along with some **corresponding** values from Ref. [33]. These results are quite **close** but for some other geometries the method does not predict such good agreement. One **would** think that the model would predict an upper bound because the material is redistributed away from the ends and placed in the **central** portion. This should allow the **crack** to open more therefore increasing the SIF. This is observed in most, but not all cases. Especially for shorter crack lengths, say a/h⁵¹, does this

reasoning fail. For large a/h the approximation in some cases overestimates the finite element value by as much as 50% .

Part of the problem with this method is in the interpretation of the SIF obtained. In a plate theory the stress distribution, and therefore, the stress intensity factor distribution, through the thickness is assumed, see Appendix G. The value of the SIF that is being attributed to the corner is actually the sumof the tension component (constant through the thickness) and the bending component (linear). To expect good results for a semi-ellipse is wishful thinking. In fact, the elasticity solution of Benthem [I] indicates that at a free surface, the SIF is zero for mode 1. It is interesting to note that the values obtained from this method comparerather well to the results by Mattheck et. al. [41] where the "corner" SIF is **averaged** in **order** to get **a** general idea **of** the **surface crack** to grow outwards. **Comparison** is good **for all** geometries given in this **reference.** Perhaps the interpretation of the LSM approximation should also be regarded as **an** average, especially taking into account the results from Benthem. More work needs to be done to use the model to investigate this problem.

Theocaris and Wu [53,54] have devised **a** *technique* which uses the I,SM and classical plate theory to obtain the SIF distribution over the entire range, including the corner. To obtain the value at the corner, they equate the SIF from the LSM (which is in **a** plane perpendicular to the plate surface) to the SIF from the plate with **a** through crack (which is in **a** plane parallel to the plate surface). They assume the semi-elliptical crack profile has some small, non-zero depth at the endpoint which is **measured** experimentally. The shortcoming of this method, besides **assuming** that there is **a** displacement **at** the **endpoint,** is that the classical plate theory is used which is inadequate to solve **for** through crack SIFs that involve bending **as** the part-through crack problem **always** does. This same technique cannot be **applied** to the **Reissner** plate because of convergence problems. Theocaris and Wu have solved the integral equations in closed form so *this* difficulty is overcome [53].

4.1.3 Double **Cracks**

Crack interaction introduces **more of** a three-dlmensional nature to the problem. For through cracks the plate theory should be accurate **for** crack tip separations **of** the order of the plate thickness. **The** justification for letting the cracks get closer together comes **from** asymptotic properties of the theory *that* for example are correct in *terms* of elasticity theory for small cracks, i.e. a/h approaching **zero.** The part-through crack problem is different. The **model** is inaccurate near the end, both along the crack front, and in terms of its influence on the solid at lyl>a as shown in the last section. Note *that* essentially the singular stress field causes the interaction. The contribution from the Fredholm kernel is secondary, especially at small separations where the problem is **most** interesting.

For the semi-ellipse, the most **studied** geometry in the literature, it was shown in Appendix F that a singular stress field does not exist, although numerically this is nearly impossible to show

because of convergence difficulties. This means that numerically there will be **a** singular stress **field.** Therefore *the* crack interaction problem **for** this crack shape cannot be properly solved. In table 4.16 the tension solution to two symmetrically **positioned** surface cracks is presented. The geometry of the problem is shown in Fig. 3.8b. Results **for** both the semi-ellipse and the 1/4 power curve of Eqn. 4.8 **are** included in this table. The difference in the behavior of the solution **for** two nearly similar crack shapes, **for** -.98 $\langle s \langle 0, \rangle$ shows that the line-spring model does not predict the correct trends. The semi-ellipse has **a** SIF *that* is nearly constant, whereas the other curve varies considerably. For **a** larger separation it should not be expected to be nearly **as accurate as** for **a** single crack. Perhaps the SIF in the center of the crack will-be-reasona **accurate.** bending are given in table 4.17. These results can also be found in $Ref.$ [59]. Results for **a** semi-elliptical crack under both tension **and**

4.2 Modes 2 and 3

From Eqns. 3.168,179,180, 2.31, **and** from the superposition of Fig. C.1, the integral equations **for** the skew-symmetrically loaded part-through crack **are:**

$$
\frac{1}{2\pi} \oint_{a}^{b} \frac{2u_{3}(t)}{(t-y)^{2}} dt + \frac{1}{2\pi} \int_{a}^{b} \left\{ u_{3}(t)K_{33}(z) + u_{5}(t)K_{35}(z) \right\} dt - \eta_{33} u_{3}(y) = -\tilde{V}_{x} = -8(1+\nu)/5 \tilde{\sigma}_{3} , \qquad (4.12)
$$

$$
\frac{1}{2\pi} \int_{a}^{b} \frac{u_4(t)}{(t-y)^2} dt - \gamma_{44} u_4(y) - \gamma_{45} u_5(y) = -\overset{\circ}{N}_{xy} = -\overset{\circ}{\sigma}_{4} , \qquad (4.13)
$$

$$
\gamma (1 - \nu^2) \frac{1}{2\pi} \int_{a}^{b} \frac{u_5(t)}{(t-y)^2} dt + \frac{1}{2\pi} \int_{a}^{b} \left\{ u_5(t) K_{55}(z) + u_3(t) K_{53}(z) \right\} dt - \gamma_{54} u_4(y) - \gamma_{55} u_5(y) = -\overset{\circ}{\mathcal{M}}_{xy} = -\overset{\circ}{\sigma}_{5}/6 , \qquad (4.14)
$$

where

$$
z = \beta |t - y|, \quad a \langle y \langle b \rangle, \tag{4.15}
$$

$$
K_{33}(z) = \beta^2 \Bigl\{-\ln(z) + \Bigl[K_2(z) - \frac{2}{z^2}\Bigr] + \Bigl[K_0(z) + \ln(z)\Bigr]\Bigr\} , \qquad (4.16)
$$

$$
K_{35}(z) = \beta \left\{ \frac{8}{z^3} - \left[z + \frac{4}{z} \right] K_2(z) + z K_0(z) \right\} , \qquad (4.17)
$$

$$
K_{55}(z) = \frac{5}{12(1+\nu)} \Biggl\{ \ln(z) + \left[\frac{48}{z^4} - \frac{4}{z^2} + 4K_0(z) - 4K_2(z) - \frac{24}{z^2} K_2(z) + \ln(z) \right] - \Biggl[2K_0(z) + 2\ln(z) \Biggr] \Biggr\} , \tag{4.18}
$$

$$
K_{53}(z) = \frac{5\beta}{12(1+\nu)} \left\{ \frac{-8}{z^3} + \left[z + \frac{4}{z} \right] K_2(z) - z K_0(z) \right\} \quad . \tag{4.19}
$$

Again it is noted that in crack propagation studies this solution may be used only if the crack **grows** in its own plane. Results for crack lengths of $a/h = .5, 1., 2., 4.,$ and crack depths of $L_0/h = .2, .4,$.6, .8, .9, .95 are **given** in tables 4.19-21a,b **for** rectangular (a) and semi-elliptical (b) cracks for out-of-plane shear, in-plane-shear and **for** twisting. Because there are two stress intensity **factors** (modes 2,3), normalization will be with respect to the primary value obtained **from** the edge-cracked strip at the **maximum** depth, see section C.4 of Appendix **C.** In the tables and **figures** this normalization **factor will** be denoted by K20, K3I0, and K3T0 for out-of-plane shear, in-plane shear, **and** twisting, **respectively. Profiles of** the **SIFs for a/h=l,** y=.3 are given in **Figs. 4.10-15. Note** that because **of** the symmetry **of** the **problem** the secondary **stress** intensity **factor at** the center of the crack is **zero. When** the **primary loading** is mode 3, **(twisting** or **inplane** shear), **out-of-plane crack** growth which **results** from mode **2** contributions is minimized in the **central portion of** the crack **front. The model also shows that** the **secondary value is insignificant** throughout the **range. For** the **rectangular** crack this is **expected,** but **for** the **semi-ellipse** this **should not** be the **case.** As in the mode **1 problem** for which the model works well, **it can** only be **hoped** that the inaccuracies towards the **ends** do not significantly **affect** the solution in the center. The **value** of the **SIF at** the center **of a** semi**elliptical crack** is listed **in** table **4.22 for various crack** lengths **and** depths **for all** loading **cases.** The **closer** the value in these tables is to one, the **closer** the **conditions are** to **plane** strain. For the loading **case** of out-of-plane shear, **plane** strain **conditions are** more easily met than in the mode 1 **cases** of **tension and** bending, **which are** The opposite is true for in-plane shear and **effect** of Poisson's ratio on the solution is shown in shown **in Table** twisting. table **4.23.**

The method **of approximating** the **value** of the Wcornern SIF of **a** semi-elliptical crack used in Sec. 4.1.2 for the mode 1 case i applied here. The results are given in table 4.24. As discussed in Appendix G, the **work** of Benthem [1] shows that **at a** free surface the stress singularity **for** shear (modes 2 and 3) is greater than .5. The plate theory used predicts **a zero** value **for** the mode 3 SIF **at** the

surface because of the assumed parabolic shear distribution, when in fact it should be infinite. Therefore as with the mode 1 prediction the numbers obtained from this method should be regarded as an average value that gives some idea of outward crack growth.

Table 4.1a,b Normalized stress intensity **factors** for a rectangular (a), or semi-elliptical (b) surface crack in a plate under tension or bendi loads, a/h=.5, *v=.3*

Rectangular **crack, Tension.**

Rectangular crack, Bending.

Table 4.1b Normalized stress intensity factors for **a** semi-elliptical surface crack in a plate under tension or bending loads, **a/h=.5,** v=.3

Seml-elllptical crack, **Tension.**

Seml-elllptlcal **crack, Bending.**

Table **4.2a,b Normalized** stress intensity **factors for a rectangular** (a), or semi-elliptical (b), surface crack in a plate under tension or bendi loads, $a/h=1$, $\nu=.3$

Rectangular crack, Tension.

Rectangular **crack, Bending.**

Table 4.2b Normalized stress intensity factors for a semi-elliptical surface crack in a pla under tension or bending loads, $a/h=1$, $\nu=3$.

Semi-elliptical crack, Tension.

Semi-elliptical crack, Bending.

Table 4.3a,b Normalized stress intensity **factors** for **a** rectangular (a), or semi-elliptical (b), surface crack in a plate under tension or bendi loads, **a/h=l** , *u=.O*

Rectangular **crack, Tension.**

Rectangular crack, Bending.

Table 4.3b Normalized stress intensity factors for a semi-elliptical surface crack in a plate under tension or bending loads, a/h=l , *u=-.O*

Semi-elliptical crack, Tension.

Semi-elliptical crack, Bending.

Table 4.4a,b Normalized stress intensity **factors for a rectangular** (a), or semi-elliptical (b), **surface** crack in **a** plate **under** tension or bending loads, $a/h=1$, $\nu=.5$

Rectangular **crack, Tension.**

Rectangular **crack, Bending.**

Semi-elliptical crack, Tension.

Seml-elllptlcal crack, Bending.

 $\frac{1}{2}$

Table 4.5a,b Normalized stress intensity **factors** ior a rectangular (a), or semi-elliptical (b) surface crack in a plate under tension or bendi loads, a/h=l.5 *, y=.3*

Rectangular **crack, Tension.**

 ~ 10

Rectangular crack, **Bending.**

w

Table 4.55 Normalized stress intensity factors for a semi-elliptical surface crack in a pla under tension or bending loads, $a/h=1.5$, $\nu=3.3$

Seml-elllptlcal crack, **Tension.**

Semi-elliptical crack, Bending.

Table 4.6a,b Normalized stress intensity **factors for a rectangular** (a), or semi-elliptical (b), **surface** crack in a plate under tension or bendi **loads, a/h=2 ,** *v=.3*

Rectangular crack, Tension.

Rectangular crack, Bending.

ŧ.

¢

Table 4.6b Normalized stress intensity fact **for a semi-elliptical surface crack in a pla** under tension or bending loads, a/h=2 , *u=-.3*

Seml-elliptlcal crack, Tension.

Semi-elliptical crack, Bending.

110

Table **4.?a,b** Normalized stress intensity **factors** for a **rectangular (a),** or **semi-elliptical (b),** surface crack in a plate under tension or bendi loads, **a/h=3** *,* _-.3

Rectangular **crack, Tension.**

Rectangular **crack, Bending.**

Table 4.7b Normalized stress intensity factors for **a** semi-elliptical surface crack in a plate under tension or bending loads, $a/h=3$, $\nu=.3$

.9 .95 L_0/h . 2 . 4 . 6 . 8 y/a .0411 .0144 **O.** .913 *.695* **400** .128 910 .693 399 .128 **•**0412 **•0144 .1** 901 .685 396 .128 .0415 .0143 **.2 .3** 886 .673 392 .129 .0419 .0144 **384** .130 .0424 .0145 **.4** 865 .656 .0428 .0147 **.5** 836 .633 **374** .128 **.6** 798 .603 **360 .127** .0429 .0148 749 .565 **.341 .123** .0424 .0147 **.7 .316 .117 .8 682** .515 .0410 .0143 **.281 .108** .0383 .0134 **.9** .581 .444 .495 .387 **.254 .101** .0362 .0127 **.95 .228 .095** .0348 .0123 .402 .330 **.98**

Semi-elliptical crack, Tension.

Seml-elllptlcal crack, Bending.

Table 4.8a,b Normalized stress intensity **factors for a** rectangular (a), or semi-elliptical (b), surface **crack** in **a** plate under tension or bending loads, **a/h=4** , v=-.3

Rectangular **crack,** Tension.

Rectangular **crack, Bendlng.**

113

Table 4.8b Normalized stress intensity **factors** for **a** semi-elliptical surface crack in a pla under *tension* or bending loads, a/h=4 *, u=.3*

Semi-elliptical crack, Tension.

Semi-elliptical crack, Bending.

Table 4.9a,b Normalized stress intensity **factors for a** rectangular (a), or semi-elliptical (b), surface crack in a plate under tension or bendi loads, **a/h=6** , _=-.3

Rectangular **crack, Tension.**

Rectangular **crack, Bending.**

Table 4.9b Normalized stress intensity factors for a semi-elliptical surface crack in a pla under tension or bending loads, a/h=6 , *v=-.3*

Seml-elllptlcal crack, Tension.

Semi-elliptical crack, Bending.

116

Table 4.10a,b Normalized stress intensity factors for **a** rectangular (a), or **semi-elliptical** (b), surface crack in a plate under tension or bendi loads, **a/h=lO** , *v=-.3*

Rectangular **crack,** Tension.

Rectangular **crack, Bending.**

~

Table 4.10b Normalized stress intensity factors for **a** semi-elliptical surface crack in a plate under tension or bending loads, $a/h=10$, $\nu=.3$

y/a O. .1 .2 **.3 .4** .5 .6 **.7 .8 .9** .95 **.98** Lo/h **.2 .4 .6 .8 .9** .95 **.968 .862 .624 .245 .0780 .0255 .965** .857 .621 **.245 .0784 .0256 .953 .843 .611 .244 .0796 .0261** .935 **.819 .595** .244 .0813 .0269 .907 **.786** .571 .241 **.0830** .0279 **.871 .743 .538 .235 .0839 .0288 825 .689 .497 .224 .0830 .0292** 766 .623 **.445 .207 .0793** .0285 688 .542 .381 .181 .0716 .0262 574 .436 .300 .145 .0587 .0218 481 .360 .246 .120 .0493 .0185 383 **.287** .197 **.098 .0410** .0155

Seml-e11iptlcal **crack, Tension.**

Semi-elliptical crack, Bending.

 L

Table 4.11 Normalized stress intensity factor at the center of a semi-elliptical crack subjected to tension and bending, ν =.3

Table 4.12 The effect **of** Poisson's ratio on the normalized stress intensity factor at the **center** of a semi-elliptical crack subjected to tension and bending, a/h=

Table 4.13a,b Normalized stress intensity factor at the **center** of **a semi-elliptical** surface crack subjected to tension. In 13a the normalization factor is for the corresponding depth edge crack given by L_0/h . The data in 13b is normalized with respect to a crack depth of .2 for all L_0/h , $\nu = .3$

Table 4.13b

Tab]e 4.14a,b Normalized stress intensity factor at the center of a semi-elliptical surface crack subjected to bending. In 14a the normalization factor is for the corresponding depth edge cra given by L_0/h . The data in 14b is normalized with respect to a crack depth of .2 for all L_0/h , $\nu = .3$

Table 4.14b

122

Table 4.15 Contact curve for through crack bending without addition of tensile field to prevent interference as approximated by the lin spring model, *v=.3*

Table 4.16 Normalized stress intensity factors are listed at positions along the crack front of two **collinear,** symmetric **part-through cracks** subjected to tension such that \pm b defines the inner crack tip and \pm c refers to the outer tip. Two different crack shapes are used for four different values of the separation distance, b. results **are** given **for** the crack **from** b to c. $v=3$, $(c-b)/(2h)=a/h$, $s=2/(c-b) [y-(c+b)/2]$

 $\left(\frac{\xi-\xi_0(1-s^2)^{1/4}}{s}\right)$

Table 4.17 The normalized stress intensity **factor at** the maximum penetration point of two interacting semi-elliptical surface cracks for both tension and bending loads, $\nu = .3$

t,

125

Table 4.18a,b Normalized stress intensity factors for a rectangular (a), **or** semi-elliptical (h), surface crack in a plate under out-of-plane shear, in-plane shear, or twisting loads, $a/h=.5$, $\nu=.3$

Rectangular **crack, Out-of-plane shear**

Mode 2, K2/K20

Mode **3, K3/K20** (×100)

126

Table 4.18a continued, Normalized stress intensity **factors** for **a rectangular** surface **crack** in **a** plate **under** in-plane shear loading, a/h=.5, ν =.

Rectangular **crack,** In-plane **shear**

Mode 2, K2/K3IO(×lO0)

Table 4.18a **cont.** Normalized **stress** intensity factors **for** a rectangular surface crack in a plate under twisting loads, $a/h=.5$, $\nu=.3$

Rectangular **crack, Twisting**

Mdde **3, K3/K3TO**

Mode **2, K2/K3TO**

Table 4.18b Normalized stress intensity **factors** for a semi-elliptical surface crack in a plate under out-of-plane shear, in-plane shear, or twisting loads, $a/h=0.5$, $\nu=3$.

Semi-elllptical crack, **Out-of-plane** shear

Mode 2, K2/K20

Mode **3, K3/K20(XlO0)**

f

Table **4.18b** cont. Normalized stress intensity factors for a semi-elliptical surface crack in a plate under in-plane shear loading, $a/h=.5$, $\nu=.3$

Semi-elliptical crack, In-plane shear

Mode **3, K3/K3IO**

Mode **2, K2/K3IO(XlO0)**

 $\pmb{\ell}$

Table 4.18b **cont.** Normalized stress **intensity** factors **for a** semi-elliptical surface **crack** in **a plate under** twisting **loads, a/h=.5** , *v=-.3*

Semi-elliptical crack, Twisting

Mode **3, K3/K3TO**

Mode **2, K2/K3TO**

Table 4.19a,b Normalized stress intensity factors for a rectangular (a), or semi-elliptical (b), surface crack in a plate under out-of-plane shear, in-plane shear, or twisting loads, $a/h=1$., $\nu=.3$

Rectangular **crack, Out-of-plane** shear

Mode 2, K2/K20

Mode **3, K3/K20** (XlO)

Table **4.19a** cont. Normalized stress **intensity factors for a rectangular** surface crack in **a** plate **under** in-plane **shear loading, a/h=l.** , *v=.3*

Rectangular crack, In-plane shear

Mode **3, KS/K3IO**

I[ode **2, K2/K3IO (x10)**

Table 4.19a cont. Normalized stress intensity **factors** for **a** rectangular **surface crack** in **a** plate under twisting loads, **a/h=l.** , *v=.3*

Rectangular **crack, Twisting**

Mode 3, K3/K3TO

Mode **2, K2/K3TO**

134

Table 4.19b Normalized stress intensity factors **for a** semi-elliptical surface crack in **a** plate under **out-of-plane** shear, in-plane shear, or twisting loads, $a/h=1$., $\nu=.3$

Semi-elliptical crack, Out-of-plane shear

Mode **2, K2/K20**

Mode **8, K3/K20(xlO)**

Table 4.19b cont. Normalized stress intens factors for a semi-elliptical surface crack in **a** plate under in-plane shear loading, **a/h=l.** , v=.3

Semi-elliptical crack, In-plane shear

Mode **3, K3/K3IO**

Mode 2, K2/K310 (x**10)**

Table 4.19b cont. Normalized stress intensity
factors for a semi-elliptical surface crack in a
plate under twisting loads, $a/h=1$., $\nu=.3$

Semi-elliptical crack, Twisting

Mode 3, K3/K3TO

Mode 2, K2/K3TO

Table **4•20a,b Normalized** stress intensity **factors for a rectangular (a),** or **semi-elliptical (b), surface crack** in **a plate under out-of-plane shear,** in-plane shear, or twisting loads, $a/h=2$., $\nu=.3$

Rectangular **crack,** Dut-of-plane shear

Mode 2, K2/K20

Mode 3, K31K20(xlO)

Table **4.20a cont. Normalized stress intensity factors** for a rectangular surface crack in a plater **under in-plane shear loading, a/h=2. , z_-.3**

Rectangular crack_ **In-plane shear**

Mode 3, **K3/K3IO**

Mode 2, K2/K3IO(xlO)

Table **4.20a cont. Normalized** stress intensity factors for **a** rectangular surface **crack** in **a plate** under twisting **loads, a/h=2,** j v=-.3

Rectangular **crack, Twisting**

Mode 3, **KZ/KZTO**

Mode 2, K2/K3TO

Table 4.20b Normalized stress intensity factor for a semi-elliptical surface crack in a plat **under out-of-plane shear, in-plane shear, or** twisting loads, $a/h=2$., $\nu=3$

Seml-elllptlcal crack, Out-ol-plane shear

Mode 2, K2/K20

Mode **3, K3/K20(XlO)**

Table **4.20b** cont. Normalized stress intensity **factors for a** semi-elliptical surface **crack** in **a** plate under in-plane shear loading, $a/h=2$., $\nu=.3$

Seml-e11iptlcal crack, In-plane shear

Mode 3, K3/K3IO

Mode 2, K2/K3IO (x10)

Table 4.20b cont. Normalized stress intensity **factors** for **a semi-elliptical surface crack** in **a plate under** twisting **loads, a/h=2. ,** v=-.3

Semi-elliptical crack, Twisting

Mode 8, **K3/K3TO**

Mode 2, K2/K3TO

Table **4.21a,b Normalized** stress intensity **factors** for a rectangular (a), or semi-elliptical (b), surface **crack** in a plate under out-of-plane shear, in-plane shear, or twisting loads, $a/\dot{h}=4.$, $\nu=.3$

Rectangular crack, **Out-of-plane shear**

Mode 2, K2/K20

Mode **3, K3/K20(xlO0)**

Table **4.21a** cont. Normalized stress intensity **factors** for a rectangular surface **crack** in a plate under in-plane shear loading, **a/h=4.** , **u=-.3**

Rectangular **crack, In-plane shear**

Mode 3, K3/K3IO

Mode **2, K2/K3IO (X10)**

Table 4.21a cont. Normalized stress intensity **factors for a** rectangular surface crack in a **plate** under twisting loads, $a/h=4$., $\nu=.3$

Rectangular **crack, Twisting**

Mode 3, **K3/KSTO**

Mode 2, K2/K3TO

Table 4.21b Normalized stress intensity factors for a semi-elliptical surface crack in a plate under out-of-plane shear, in-plane shear, or twisting loads, $a/h=4$., $\nu=.3$

Seml-elllptlcal crack, Out-of-plane shear

Mode 2, **K2/K20**

Mode 3, K3/K20 (x10)

Table 4.21b cont. Normalized stress intensity factors **for** a semi-elliptical surface crack in a plate under in-plane shear loading, a/h=4., ν =.3

Seml-elllptlcal crack, In-plane **shear**

Mode 3, **K3/K3IO**

Mode 2, K2/K3IO(XlO)

Table **4.21b cont.** Normalized stress intensity factors **for a** semi'elliptical surface **crack** in **a plate** under twisting **loads, a/h=4.** , v=-.3

Seml-elllptlcal crack, Twisting

Mode **3, K3/K3TO**

Mode 2, K2/K3TO

Table 4.22 Normalized stress intensity factor a the center of a semi-elliptical crack subjected to out-of-plane shear, in-plane shear, and twisting loads, $\nu=0.3$

Table 4.23 The **effect** of **Poisson's ratio** on the normalized stress intensity factor **at** the center of **a** semi-elliptical **crack** subjected to out-ofplane shear, in-plane shear, **and** twisting loads, **a/h=1.**

Table 4.24 The LSM **approximation** to the stress intensity factor **at** the corner of **a** semi**elliptical surface crack subjected to out-of-plan** shear, in-plane shear, and twisting loads, **a/h=1,** $\nu = .3.$

 $\omega = \omega_{\rm{eff}}$

Figure 4.1 Comparison of mode 1 line-spring model with and without transverse shear deformation to
Newman's and Raju's finite element solution, Ref.
[33], for $a/h=2/3$, $\nu=.3$

Figure 4.2 Comparison of mode 1 line-spring model with and without transverse shear deformation to Newman's and Raju's finite element solution, Ref.
[33], for $a/h=1.$, $\nu=.3$

Figure 4.3 Comparison of mode 1 line-spring model with and without transverse shear deformation to Newman's and Raju's finite element solution, Ref. [33], for $a/h=2.$, $\nu=.3$

Figure 4.4 Comparison of mode 1 line-spring model with and without transverse shear deformation to Newman's and Raju's finite element solution, Ref. [33], for $a/h=4.$, $\nu=.3$

Figure **4.5** Geometry of the bending **contact** Figure
problem.

ţ.

Figure 4.7 Line-spring model approximation to the stress intensity factor at the corner of 1/4 power "semi-elliptical" surface crack, $a/h=1.$, $\nu=.3$

Figure 4.8 Line-spring model approximation to the stress intensity factor at the corner of a through crack subjected to bending allowing for contact stresses as compared to the value assuming no contact, $a/h=1.$, $\nu=.3$

The LSM approximation to the stress Figure 4.9 factor at the corner of a semiintensity elliptical surface crack, $a/h=1.$, $\nu=.3.$ The finite element results are from Ref. [33].

Figure 4.10 Normalized stress intensity factor
profiles for the mode 2,3 line-spring model for a
rectangular crack subjected to out-of-plane shear,
a/h=1., $\nu=0.3$

Figure 4.11 Normalized stress intensity factor
profiles for the mode 2,3 line-spring model for a
rectangular crack subjected to in-plane shear, $a/h=1.$, $\nu=.3$

Figure **4.12 Normalized** stress **intensity factor profiles for** the **mode 2,3 line-spring model for a rectangular crack subjected** to **twisting, a/h=l.,**

Figure 4.13 Normalized stress **intensity** fsctor profiles for the mode **2,3** line-spring model for **a** semi-elliptical crack subjected to out-of-plan shear, $a/h=1.$, $\nu=.3$

Figure 4.14 Normalized stress intensity factor
profiles for the mode 2,3 line-spring model for a
semi-elliptical crack subjected to in-plane shear, $a/h=1.$, $v=.3$

Figure 4.15 Normalized stress intensity factor
profiles for the mode 2,3 line-spring model for a
semi-elliptical crack subjected to twisting,
a/h=1., $\nu=0.3$

CHAPTER 5

Through **Cracks** in Shallow Shells

In *this* chapter the singular integral **equations** for **a** series **of** collinear cracks in **a shallow shell** which **allows** for *transverse* **shear** deformations will be derived. The crack will be **assumed** to lie **along a** principal line **of** curvature which uncouples the **symmetric** (mode 1) **from** the skew-symmetric (modes 2,3) **formulation.** The **emphasis** will be on crack interaction **for some** common **geometries.** Also the equations **are** needed for the **part-through** crack problem of the next chapter.

5.1 Formulation

The governing equations, both **dimensional (Eqns. 5.1a-16a,18a, 19a) and non-dimensional** (Eqns. **5.1b-16b,18b,19b) are listed** below. **The dimensional relationships** are **defined** in Appendix A. **From** equilibrium,

$$
\frac{\partial N_{11}}{\partial x_1} + \frac{\partial N_{12}}{\partial x_2} = 0 \quad , \quad \frac{\partial N_{xx}}{\partial x} + \frac{\partial N_{xy}}{\partial y} = 0 \quad , \tag{5.1a,b}
$$

$$
\frac{\partial N_{12}}{\partial x_1} + \frac{\partial N_{22}}{\partial x_2} = 0 \quad , \quad \frac{\partial N_{xy}}{\partial x} + \frac{\partial N_{yy}}{\partial y} = 0 \quad , \tag{5.2a,b}
$$

$$
\frac{\partial v_1}{\partial x_1} + \frac{\partial v_2}{\partial x_2} + \frac{\partial}{\partial x_1} \left(\frac{\partial z}{\partial x_1} N_{11}\right) + \frac{\partial}{\partial x_1} \left(\frac{\partial z}{\partial x_2} N_{12}\right) \n+ \frac{\partial}{\partial x_2} \left(\frac{\partial z}{\partial x_1} N_{12}\right) + \frac{\partial}{\partial x_2} \left(\frac{\partial z}{\partial x_2} N_{22}\right) + \frac{\partial}{\partial (x_1, x_2)} = 0
$$
\n
$$
\frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{12(1+\nu)}{5} \left\{\frac{\partial}{\partial x} \left(\frac{\partial z}{\partial x} N_{xx}\right) + \frac{\partial}{\partial x} \left(\frac{\partial z}{\partial y} N_{xy}\right) + \frac{\partial}{\partial (x_1, x_2)} \left(\frac{\partial}{\partial x} N_{xx}\right) + \frac{\partial}{\partial x} \left(\frac{\partial z}{\partial y} N_{xy}\right) + \frac{\partial}{\partial (x_1, x_2)} \left(\frac{\partial}{\partial x} N_{xx}\right) +
$$

$$
+\frac{\partial}{\partial y}\left(\frac{\partial Z}{\partial x}N_{xy}\right) + \frac{\partial}{\partial y}\left(\frac{\partial Z}{\partial y}N_{yy}\right) + q(x,y) \} = 0 \quad , \quad (5.3a,b)
$$

$$
\frac{\partial M_{11}}{\partial x_1} + \frac{\partial M_{12}}{\partial x_2} - V_1 = 0 \quad ,
$$

$$
\frac{\partial \mathbf{M}_{XX}}{\partial x} + \frac{\partial \mathbf{M}_{XY}}{\partial y} - \frac{5}{12(1+\nu)} V_X = 0 \quad , \tag{5.4a,b}
$$

 $\frac{\partial M_{12}}{\partial x_1}$ $\frac{\partial M_{22}}{\partial x_2} - V_2 = 0$

$$
\frac{\partial W_{xy}}{\partial x} + \frac{\partial W_{yy}}{\partial y} - \frac{5}{12(1+\nu)} V_y = 0 \quad , \quad (5.5a, b)
$$

where $q(x,y)$ is normal loading to the plate surface and $Z(x,y)$ is the equation of the mid-plane of the shell. The other variables are standard shell quantities (see Figs. 2.1,2.3). From kinematical considerations,

$$
\epsilon_{11} = \frac{\partial u_{1D}}{\partial x_1} + \frac{\partial z}{\partial x_1} \frac{\partial u_{3D}}{\partial x_1} , \quad \epsilon_{xx} = \frac{\partial u}{\partial x} + \frac{\partial z}{\partial x} \frac{\partial w}{\partial x} , \qquad (5.6a, b)
$$

$$
\epsilon_{22} = \frac{\partial u_{2D}}{\partial x_2} + \frac{\partial z}{\partial x_2} \frac{\partial u_{3D}}{\partial x_2} , \quad \epsilon_{yy} = \frac{\partial v}{\partial y} + \frac{\partial z}{\partial y} \frac{\partial w}{\partial y} , \qquad (5.7a, b)
$$

$$
\epsilon_{12} = \frac{1}{2} \left[\frac{\partial u_{1D}}{\partial x_2} + \frac{\partial u_{2D}}{\partial x_1} + \frac{\partial z}{\partial x_1} \frac{\partial u_{3D}}{\partial x_2} + \frac{\partial z}{\partial x_2} \frac{\partial u_{3D}}{\partial x_1} \right],
$$

$$
\epsilon_{xy} = \frac{1}{2} \left[\frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} + \frac{\partial Z}{\partial x} \frac{\partial w}{\partial y} + \frac{\partial Z}{\partial y} \frac{\partial w}{\partial x} \right], \qquad (5.8a, b)
$$

$$
\theta_1 = \frac{\partial u_{3D}}{\partial x_1} + \beta_1 \quad , \quad \theta_x = \frac{\partial w}{\partial x} + \beta_x \quad , \tag{5.9a,b}
$$

$$
\theta_2 = \frac{\partial u_{3D}}{\partial x_2} + \beta_2 \quad , \quad \theta_y = \frac{\partial w}{\partial y} + \beta_y \quad , \tag{5.10a,b}
$$

where θ_1 and θ_2 are the total rotations of the normals. For classical theory they **are** zero showing that normals to the shell surface stay normal, i.e. *there* is no deformation *transversely.* The **constitutive** relations (Hooke's law) angel of start of the the start of the start of the start of

$$
h\epsilon_{11} = \frac{1}{E} (N_{11} - \nu N_{22})
$$
, $\epsilon_{xx} = N_{xx} - \nu N_{yy}$, (5.11a,b)

$$
h\epsilon_{22} = \frac{1}{E} (N_{22} - \nu N_{11})
$$
, $\epsilon_{yy} = N_{yy} - \nu N_{xx}$, (5.12a,b)

$$
h\epsilon_{12} = \frac{1}{2\mu} N_{12} , \quad \epsilon_{xy} = (1+\nu)N_{xy} , \qquad (5.13a,b)
$$

where E **is** Young's modulus **and** v is Poisson's ratio. From bending,

$$
M_{11} = D \left[\frac{\partial \beta_1}{\partial x_1} + \nu \frac{\partial \beta_2}{\partial x_2} \right],
$$

$$
M_{xx} = \frac{1}{12(1-\nu^2)} \left[\frac{\partial \beta_x}{\partial x} + \nu \frac{\partial \beta_y}{\partial y} \right],
$$
 (5.14a,b)

$$
M_{22} = D \left[\frac{\partial \beta_2}{\partial x_2} + \nu \frac{\partial \beta_1}{\partial x_1} \right],
$$

$$
M_{yy} = \frac{1}{12(1-\nu^2)} \left[\nu \frac{x}{\delta x} + \frac{y}{\delta y} \right], \qquad (5.15a,b)
$$

$$
M_{12} = \frac{D(1-\nu)}{2} \left[\frac{\delta \beta_1}{\delta x_2} + \frac{\delta \beta_2}{\delta x_1} \right], \qquad (5.15a,b)
$$

$$
\mathbf{M}_{\mathbf{xy}} = \frac{1}{24(1+\nu)} \left[\frac{\partial \beta_{\mathbf{x}}}{\partial \mathbf{y}} + \frac{\partial \beta_{\mathbf{y}}}{\partial \mathbf{x}} \right], \qquad (5.16a, b)
$$

 \mathbf{L}

where

$$
D = \frac{Eh^3}{12(1-\nu^2)} \qquad (5.17)
$$

The linear transverse shear stress-strain relationships **are,**

$$
\theta_1 = \frac{1}{hB} V_1 , \quad \theta_x = V_x , \qquad (5.18a, b)
$$

$$
\theta_2 = \frac{1}{hB} V_2 , \quad \theta_y = V_y , \qquad (5.19a,b)
$$

where

$$
B = \frac{5E}{12(1+\nu)} \tag{5.20}
$$

From here on only **non-dimensional variables will** be used. Define $\phi(x,y)$ such that

$$
N_{xx} = \frac{\partial^2 \phi}{\partial y^2} , N_{yy} = \frac{\partial^2 \phi}{\partial x^2} , N_{xy} = -\frac{\partial^2 \phi}{\partial x \partial y} .
$$
 (5.21)

Introduce the new unknowns $\mathbf{u}(x,y)$ and $\boldsymbol{\psi}(x,y)$ defined as follows,

$$
\Omega(x,y) = \frac{\partial \beta_x}{\partial y} - \frac{\partial \beta_y}{\partial x} , \qquad (5.22)
$$

$$
\psi(x,y) = \kappa \left[\frac{\partial \beta_x}{\partial x} + \frac{\partial \beta_y}{\partial y} \right] - w(x,y) , \qquad (5.23)
$$

where

$$
\kappa = \frac{1}{5(1-\nu)} \quad . \tag{5.24}
$$

Also it will be assumed that $Z(x,y)$ is limited to the following,

$$
\frac{\partial^2 Z}{\partial x^2} = \frac{-1}{R_1} , \quad \frac{\partial^2 Z}{\partial y^2} = \frac{-1}{R_2} , \quad \frac{\partial^2 Z}{\partial x \partial y} = \frac{-1}{R_{12}} , \tag{5.25}
$$

thus making the curvatures **constant.** For convenience the following **constants are** introduced,

$$
\lambda_1^4 = 12(1-\nu^2) (h/R_1)^2 , \quad \lambda_2^4 = 12(1-\nu^2) (h/R_2)^2 ,
$$

$$
\lambda_{12}^4 = 12(1-\nu^2) (h/R_{12})^2 , \quad \lambda^2 = 12(1-\nu^2) , \quad \gamma = \lambda^{-2} .
$$
 (5.26)

If all but λ_1 are zero, an axially cracked cylinder results; if λ_2 is
the only non-zero quantity, then the crack will be circumfere see Fig. 2.1. R_{12} is needed when the crack does not lie along a principal line of curvature. After some algebra Eqns. 5.1-19 ar reduced to the following **equations,**

$$
\nabla^4 \phi - \frac{1}{\lambda^2} \left\{ \lambda_{10y}^2 - 2\lambda_{12}^2 \frac{\partial^2}{\partial x \partial y} + \lambda_{20x}^2 \frac{\partial^2}{\partial x^2} \right\} \mathbf{w}(x, y) = 0 \quad , \tag{5.27}
$$

$$
\nabla^4 w + \lambda^2 (1 - \kappa \nabla^2) \left\{ \lambda \frac{2}{1} \frac{\partial^2}{\partial y^2} - 2 \lambda \frac{2}{12} \frac{\partial^2}{\partial x \partial y} + \lambda \frac{2}{2} \frac{\partial^2}{\partial x^2} \right\} \phi(x, y) =
$$

$$
\lambda^4 (1 - \kappa \nabla^2) q(x, y) , \qquad (5.28)
$$

$$
\kappa \nabla^2 \psi - \psi - \mathbf{w} = 0 \quad , \tag{5.29}
$$

$$
\frac{\kappa(1-\nu)}{2} \sqrt[n]{u} - 0 = 0 \quad . \tag{5.30}
$$

Now let $q(x,y) = 0$ and also confine the crack to a principal line of curvature by setting $\lambda_{12} = 0$. This reduces Eqns. 5.27,28 to

$$
\nabla^4 \phi - \frac{1}{\lambda^2} \left\{ \lambda \frac{2 \delta^2}{\delta y^2} + \lambda \frac{2 \delta^2}{\delta x^2} \right\} \mathbf{w}(x, y) = 0 \quad , \tag{5.31'}
$$

$$
\nabla^4 \mathbf{w} + \lambda^2 (1 - \kappa \nabla^2) \left\{ \lambda \frac{2 \delta^2}{1 \delta y^2} + \lambda \frac{2 \delta^2}{2 \delta x^2} \right\} \phi(\mathbf{x}, \mathbf{y}) = 0 \quad . \tag{5.32}
$$

These last four equations will be solved by using Fourier transforms. First Eqns. 5.31,32 are reduced to one equation in $\phi(x,y)$,

$$
\nabla^4 \nabla^4 \phi + (1 - \kappa \nabla^2) \nabla^2 \chi^2 \phi = 0 \quad , \tag{5.33}
$$

where

$$
\nabla_{\lambda}^{2} = \lambda_{1}^{2} \frac{\partial^{2}}{\partial y^{2}} + \lambda_{2}^{2} \frac{\partial^{2}}{\partial x^{2}} \quad .
$$
 (5.34)

The Fourier transform **is** defined for **any** function as

$$
F(x,y) = \frac{1}{2\pi} \int_{-\infty}^{\infty} \overline{F}(x,a) e^{-1ya} da ,
$$

$$
\overline{F}(x,a) = \int_{-\infty}^{+\infty} F(x,y) e^{iya} dy .
$$
 (5.35)

The transforms of the various operators of Eqn. 5.33 **are**

 r^{+00}

$$
FT[\nabla^{2}F] = \frac{d^{2}F}{d^{2}x} - a^{2}F ,
$$
\n
$$
FT[\nabla^{4}F] = \frac{d^{4}F}{d^{4}x} - 2a^{2}\frac{d^{2}F}{d^{2}x} + a^{4}F ,
$$
\n
$$
FT[\nabla^{4}\nabla^{4}F] = \frac{d^{8}F}{d^{8}x} - 4a^{2}\frac{d^{6}F}{d^{6}x} + 6a^{4}\frac{d^{4}F}{d^{4}x} - 4a^{6}\frac{d^{2}F}{d^{2}x} + a^{8}F ,
$$
\n
$$
FT[\nabla^{2}\nabla^{2}F] = \lambda \frac{4d^{4}F}{d^{4}x} - 2\lambda_{1}^{2}\lambda_{2}^{2}a^{2}\frac{d^{2}F}{d^{2}x} + \lambda_{1}^{4}a^{4}F ,
$$
\n
$$
FT[\nabla^{2}\nabla^{2}\nabla^{2}F] = \lambda \frac{4d^{6}F}{d^{6}x} - (2\lambda_{1}^{2}\lambda_{2}^{2}a^{2} + a^{2}\lambda_{2}^{4})\frac{d^{4}F}{d^{4}x} + (\lambda_{1}^{4}a^{4} + 2\lambda_{1}^{2}\lambda_{2}^{2}a^{4})\frac{d^{2}F}{d^{2}x} - a^{6}\lambda_{1}^{4}F .
$$
\n
$$
(\lambda_{1}^{4}a^{4} + 2\lambda_{1}^{2}\lambda_{2}^{2}a^{4})\frac{d^{2}F}{d^{2}x} - a^{6}\lambda_{1}^{4}F .
$$
\n(5.36)

The Fourier **transform of** Eqn. 5.33 is

$$
\frac{d^{8}\vec{\phi}}{d^{8}x} - (4a^{2} + \kappa)\frac{4}{2}\frac{d^{6}\vec{\phi}}{d^{6}x} + (6a^{4} + \lambda_{2}^{4} + 2\kappa)\frac{2}{1}\lambda_{2}^{2}a^{2} + \kappa\lambda_{2}^{4}a^{2})\frac{d^{4}\vec{\phi}}{d^{4}x}
$$

$$
- (4a^{6} + 2\lambda_{1}^{2}\lambda_{2}^{2}a^{2} + \kappa\lambda_{1}^{4}a^{4} + 2\kappa\lambda_{1}^{2}\lambda_{2}^{2}a^{4})\frac{d^{2}\vec{\phi}}{d^{2}x} + (a^{8} + \lambda_{1}^{4}a^{4} + \kappa a^{6}\lambda_{2}^{4})\vec{\phi} = 0 ,
$$

$$
(5.37)
$$

which has the solution

$$
\overline{\phi}(x,a) = \sum_{j=1}^{4} R_j(a) e^{m_j x}, \quad x > 0 \quad ,
$$

$$
\overline{\phi}(x,\alpha) = \sum_{j=5}^{8} R_j(\alpha) e^{\sum_{j=5}^{m} x} , x < 0 , \qquad (5.38)
$$

where

$$
m_{j} = -(p_{j} + a^{2})^{1/2}, j=1,2,3,4 ,
$$

\n
$$
m_{j} = +(p_{j-4} + a^{2})^{1/2}, j=5,6,7,8 .
$$
\n(5.39)

The roots pj, j=1,2,3,4 **are** obtained **following characteristic equation, from** the **solution of** the

$$
p^{4} - \kappa \lambda_{2}^{4} p^{3} + (2\kappa \lambda_{1}^{2} \lambda_{2}^{2} a^{2} - 2\kappa \lambda_{2}^{4} a^{2} + \lambda_{2}^{4} p^{2} + (2\kappa \lambda_{1}^{2} \lambda_{2}^{2} a^{2} - \kappa \lambda_{2}^{4} a^{2} + 2\lambda_{1}^{4} a^{2} + 2\lambda_{2}^{4} - 2\lambda_{1}^{2} \lambda_{2}^{2} a^{2} p + (\lambda_{2}^{2} - \lambda_{1}^{2})^{2} a^{4} = 0
$$
 (5.40)

This quartic **is** solved numerically. For large **and** small **a an asymptotic expansion** for the roots is given **in** section J.1 **of** Appendix J. Since the **crack** has been **assumed** to **lie** on **a principal line** of **curvature, only** the portion **of** the **shell** for x>Oneed be **considered.** The transformed solutions of the other unknowns **appearing** in Eqns. **5.29-32 are:**

$$
\overline{\Omega}(x,a) = A(a)e^{-TX} \quad , \quad x > 0 \quad , \tag{5.41}
$$

$$
\overline{\psi}(x,\alpha) = \frac{4}{j=1} R_j(\alpha) K_j(\alpha) e^{m_j x}, \quad x > 0 \quad , \tag{5.42}
$$

$$
\bar{w}(x,\alpha) = \frac{4}{j-1}R_j(\alpha)K_j(\alpha) (\kappa p_j-1)e^{jx}, \quad x > 0 \quad , \tag{5.43}
$$

where

$$
r = -\left[a^2 + \frac{2}{\kappa (1-\nu)} \right]^{1/2} , \qquad (5.44)
$$

$$
K_{j}(a) = \frac{p_{j}^{2} \lambda^{2}}{(\kappa p_{j} - 1) (\mathbf{m}_{j}^{2} \lambda_{2}^{2} - \lambda_{1}^{2} a^{2})}
$$
(5.45)

The next step is to express the shell quantities in terms of $A(a)$ and $R_j(\alpha)$, j=1,2,3,4, which are unknowns in the problem to be determined by boundary conditions as yet unspecified. These expressions are

$$
N_{xx} = \frac{-1}{2\pi} \int_{-\infty}^{+\infty} a^2 \sum_{j=1}^{4} R_j(a) e^{m_j x} e^{-iay} da , \qquad (5.46)
$$

$$
N_{yy} = \frac{1}{2\pi} \int_{-\infty}^{+\infty} \sum_{j=1}^{4} m_j^2 R_j(\alpha) e^{m_j x} e^{-i\alpha y} d\alpha , \qquad (5.47)
$$

$$
N_{xy} = \frac{i}{2\pi} \int_{-\infty}^{+\infty} a \sum_{j=1}^{4} m_j R_j(a) e^{jx} e^{-iay} da , \qquad (5.48)
$$

$$
\beta_{x} = \kappa \frac{1-\nu}{2} \frac{-i}{2\pi} \int_{-\infty}^{+\infty} aA(a) e^{TX} e^{-iay} da + \frac{1}{2\pi} \int_{-\infty}^{+\infty} \frac{4}{j=1} m_{j} K_{j} R_{j}(a) e^{\frac{m}{2}j^{x}} e^{-iay} da , \qquad (5.49)
$$

$$
\beta_{y} = \kappa \frac{1-\nu}{2} \frac{1}{2\pi} \int_{-\infty}^{+\infty} r A(a) e^{rx} e^{-iay} da -
$$

$$
-\frac{i}{2\pi}\int_{-\infty}^{+\infty}a\sum_{j=1}^{4}K_{j}R_{j}(a)e^{m_{j}x}e^{-i\alpha y}da , \qquad (5.50)
$$

$$
M_{XX} = \frac{1}{\lambda^4} \frac{1}{2\pi} \int_{-\infty}^{+\infty} \sum_{j=1}^{4} (\mathbf{m}_j^2 - \nu a^2) K_j R_j(a) e^{\mathbf{m}_j x} e^{-i a y} da
$$

$$
- \frac{\kappa (1-\nu)^2}{2\lambda^4} \frac{i}{2\pi} \int_{-\infty}^{+\infty} a r A(a) e^{\mathbf{r} x} e^{-i a y} da + \qquad (5.51)
$$

$$
M_{yy} = \frac{1}{\lambda^4} \frac{1}{2\pi} \int_{-\infty}^{+\infty} \sum_{j=1}^{4} (\nu m_j^2 - \alpha^2) K_j R_j(\alpha) e^{-\int_{-\infty}^{\infty} \alpha^2} e^{-i\alpha y} d\alpha + \frac{\kappa (1-\nu)^2}{2\lambda^4} \frac{1}{2\pi} \int_{-\infty}^{+\infty} \alpha r A(\alpha) e^{-rx} e^{-i\alpha y} d\alpha +
$$
 (5.52)

$$
M_{xy} = \frac{-(1-\nu)}{\lambda^4} \frac{1}{2\pi} \int_{-\infty}^{+\infty} a \sum_{j=1}^4 m_j K_j R_j(a) e^{m_j x} e^{-iay} da
$$

$$
- \frac{\kappa (1-\nu)^2}{4\lambda^4} \frac{1}{2\pi} \int_{-\infty}^{+\infty} (a^2 + r^2) A(a) e^{rx} e^{-iay} da , \qquad (5.53)
$$

$$
V_{x} = \frac{\kappa (1-\nu)}{2} \frac{-i}{2\pi} \int_{-\infty}^{+\infty} aA(a) e^{TX} e^{-iay} da +
$$

+ $\frac{\kappa}{2\pi} \int_{-\infty}^{+\infty} \frac{4}{j=1} m_j p_j K_j R_j(a) e^{m_j X} e^{-iay} da$, (5.54)

$$
V_{y} = \frac{(1-\nu)}{2\lambda^{4}} \frac{-1}{2\pi} \int_{-\infty}^{+\infty} rA(a) e^{rx} e^{-iay} da +
$$

- $\frac{1}{\lambda^{4}} \frac{i}{2\pi} \int_{-\infty}^{+\infty} a \frac{4}{j=1} p_{j} K_{j} R_{j}(a) e^{\frac{m}{2}j^{x}} e^{-iay} da , \qquad (5.55)$

$$
\frac{\partial u}{\partial y}\Big|_{x\to 0} = \frac{i}{2\pi} \int_{-\infty}^{+\infty} \frac{1}{a} \left\{ (\lambda_2^2/\lambda^2) \sum_{j=1}^4 R_j(a) \left[m_j K_j(\kappa p_j - 1) - m_j^3 \right] \right\} e^{-i\alpha y} da
$$
\n(5.56)

$$
\frac{\partial v}{\partial y}\Big|_{x\to 0} = \frac{1}{2\pi} \int_{-\infty}^{+\infty} \sum_{j=1}^{4} m_j^2 R_j(a) e^{-i\alpha y} da +
$$

+ $y(\lambda_2/\lambda)^2 \frac{-i}{2\pi} \int_{-\infty}^{+\infty} a \sum_{j=1}^{4} R_j(a) K_j(\kappa p_j-1) e^{-i\alpha y} da$, (5.57)

$$
= \frac{1}{2\pi} \int_{-\infty}^{+\infty} \sum_{j=1}^{4} m_j^2 R_j(\alpha) e^{-i\alpha y} d\alpha + y(\lambda_2/\lambda)^2 \frac{\partial w}{\partial y}\Big|_{x\to 0} . \qquad (5.58)
$$

5.2 Symmetric Loading, Mode 1

There are currently five unknowns in the problem, $A(a)$, and $R_j(a)$ for $j=1,2,3,4$. The first step is to reduce these to two unknowns by using the symmetry **conditions,**

$$
N_{xy}(0, y) = 0 \qquad (5.59)
$$

$$
\mathbf{M}_{\mathbf{xy}}(0,\mathbf{y}) = 0 \quad , \tag{5.60}
$$

$$
V_{x}(0,y) = 0 \t\t(5.61)
$$

Then replace the **remaining** two **unknowns with** the **crack** surface displacements,

$$
u_1(y) = u(x_2)/h = u(0^+, x_2)/h , \qquad (5.62)
$$

$$
u_2(y) = \beta_x(x_2) = \beta_x(0^+, x_2) \quad . \tag{5.63}
$$

The equations that relate $u_i(y)$ to the original unknowns are:

$$
A(\alpha) = \frac{2}{i\alpha(1-\nu)} \sum_{j=1}^{4} m_j p_j K_j R_j
$$
 (5.64)

$$
\frac{4}{j=1} m_j K_j R_j \left\{ \left[\kappa (1-\nu) \alpha^2 + 1 \right] p_j - \alpha^2 (1-\nu) \right\} = 0 \quad , \tag{5.65}
$$

$$
\sum_{j=1}^{4} m_{j} K_{j} R_{j} \left\{ \kappa_{p_{j}-1} \right\} = \frac{-1}{\alpha} q_{2}(\alpha) , \qquad (5.66)
$$

$$
\sum_{j=1}^{4} m_j R_j = 0 \quad , \tag{5.67}
$$

$$
\frac{4}{j=1} m_j R_j \left\{ \lambda_2^2 K_j \frac{\kappa_{p_j-1}}{\lambda^2} - m_j^2 \right\} = -a q_1(a) \quad , \tag{5.68}
$$

where

$$
q_k(a) = a \int_{-\infty}^{+\infty} u_k(t) e^{iat} dt \quad , \quad k=1,2 \quad . \tag{5.69}
$$

The solution to **Eqns.** 5.65-68 is

$$
R_{j}(a) = \sum_{k=1}^{2} \frac{\gamma_{kj} q_k}{m_j D(a)}, \quad j=1,2,3,4 \quad , \tag{5.70}
$$

where

$$
D(\alpha) = (K_1K_2 + K_3K_4)(p_1 - p_2)(p_4 - p_3) + (K_1K_3 + K_2K_4)(p_1 - p_3)(p_2 - p_4) + (K_2K_3 + K_1K_4)(p_1 - p_4)(p_3 - p_2) ,
$$
\n(5.71)

$$
\gamma_{11} = a \left[K_{2} K_{3} (p_{3} - p_{2}) + K_{2} K_{4} (p_{2} - p_{4}) + K_{3} K_{4} (p_{4} - p_{3}) \right],
$$

\n
$$
\gamma_{12} = -a \left[K_{1} K_{3} (p_{3} - p_{1}) + K_{1} K_{4} (p_{1} - p_{4}) + K_{3} K_{4} (p_{4} - p_{3}) \right],
$$

\n
$$
\gamma_{13} = a \left[K_{1} K_{2} (p_{2} - p_{1}) + K_{1} K_{4} (p_{1} - p_{4}) + K_{2} K_{4} (p_{4} - p_{2}) \right],
$$

\n
$$
\gamma_{14} = -a \left[K_{1} K_{2} (p_{2} - p_{1}) + K_{1} K_{3} (p_{1} - p_{3}) + K_{2} K_{3} (p_{3} - p_{2}) \right],
$$

\n
$$
\gamma_{21} = \frac{-\gamma_{11} \lambda_{2}^{2}}{a^{2} \lambda^{2}} - \frac{K_{2}}{a} (p_{4} - p_{3}) \left\{ \left[\kappa (1 - \nu) a^{2} + 1 \right] p_{2} - a^{2} (1 - \nu) \right\} - \frac{K_{3}}{a} (p_{2} - p_{4}) \left\{ \left[\kappa (1 - \nu) a^{2} + 1 \right] p_{3} - a^{2} (1 - \nu) \right\} - \frac{K_{4}}{a} (p_{3} - p_{2}) \left\{ \left[\kappa (1 - \nu) a^{2} + 1 \right] p_{4} - a^{2} (1 - \nu) \right\} ,
$$

\n
$$
\gamma_{22} = \frac{-\gamma_{12} \lambda_{2}^{2}}{a^{2} \lambda^{2}} + \frac{K_{1}}{a} (p_{4} - p_{3}) \left\{ \left[\kappa (1 - \nu) a^{2} + 1 \right] p_{1} - a^{2} (1 - \nu) \right\} + \frac{K_{3}}{a} (p_{1} - p_{4}) \left\{ \left[\kappa (1 - \nu) a^{2} + 1 \right] p_{3} - a^{2} (1 - \nu) \right\} + \frac{K_{3}}{a} (p_{1} - p_{4}) \left\
$$

$$
+\frac{K_4}{a}(p_3 - p_1)\left\{ \left[\kappa (1-\nu)a^2 + 1 \right] p_4 - a^2 (1-\nu) \right\} ,
$$

\n
$$
\gamma_{23} = \frac{-\gamma_{13} \lambda_2^2}{a^2 \lambda^2} - \frac{K_1}{a}(p_4 - p_2)\left\{ \left[\kappa (1-\nu)a^2 + 1 \right] p_1 - a^2 (1-\nu) \right\} - \frac{K_2}{a}(p_1 - p_4)\left\{ \left[\kappa (1-\nu)a^2 + 1 \right] p_2 - a^2 (1-\nu) \right\} - \frac{K_4}{a}(p_2 - p_1)\left\{ \left[\kappa (1-\nu)a^2 + 1 \right] p_4 - a^2 (1-\nu) \right\} ,
$$

\n
$$
\gamma_{24} = \frac{-\gamma_{14} \lambda_2^2}{a^2 \lambda^2} + \frac{K_1}{a}(p_3 - p_2)\left\{ \left[\kappa (1-\nu)a^2 + 1 \right] p_1 - a^2 (1-\nu) \right\} + \frac{K_2}{a}(p_1 - p_3)\left\{ \left[\kappa (1-\nu)a^2 + 1 \right] p_2 - a^2 (1-\nu) \right\} + \frac{K_3}{a}(p_2 - p_1)\left\{ \left[\kappa (1-\nu)a^2 + 1 \right] p_3 - a^2 (1-\nu) \right\} .
$$

\n(5.72)

The following two mixed boundary **conditions will produce** two singular **integral equations** for the determination **of** the **crack opening** displacements:

$$
N_{xx}(0^+, y) = -f_1(y) , y in L_n , \qquad (5.73)
$$

$$
u_1(y) = u(0^+, x_2)/h = 0
$$
, y outside of L_n , (5.74)

$$
M_{xx}(0^+, y) = -f_2(y) , y in L_n , \qquad (5.75)
$$

$$
u_2(y) = \beta_x(0^+, x_2) = 0
$$
, y outside of L_n , (5.76)

where

$$
L_n = (a_1, b_1), (a_2, b_2), \dots, (a_n, b_n)
$$
 (5.77)

each section (a_i, b_i) , defining a crack on $x=0$. Eqns. 5.73,75 with 46,51,64 for **y** in L_n becom

$$
-f_1(y) = \frac{-1}{2\pi} \lim_{x \to 0} \int_{-\infty}^{+\infty} a^2 \sum_{j=1}^4 R_j e^{m_j x} e^{-i\alpha y} d\alpha , \qquad (5.78)
$$

$$
-\frac{\lambda^{4}}{1-\nu}f_{2}(y) = \frac{1+\nu}{2\pi} \lim_{x\to 0} \int_{-\infty}^{+\infty} \left\{ -\kappa r e^{rx} \sum_{j=1}^{4} m_{j} p_{j} K_{j} R_{j} + \frac{1}{1-\nu} \sum_{j=1}^{4} p_{j} K_{j} R_{j} e^{m_{j}x} + \alpha^{2} \sum_{j=1}^{4} K_{j} R_{j} e^{m_{j}x} \right\} e^{-i\alpha y} d\alpha
$$
 (5.79)

After **making use** of the odd/even **nature of** the infinite **integrals,** Eqns. **5.78,79** may be **written** as follows,

$$
-f_{1}(y) = -\frac{1}{\pi} \lim_{x \to 0} \int_{0}^{+\infty} a^{2} \sum_{j=1}^{4} R_{j} e^{\frac{m_{j}x}{\cos a(t-y)} d\alpha}, \qquad (5.80)
$$

$$
\frac{-\lambda^{4}}{1-\nu} f_{2}(y) = \frac{1+\nu}{\pi} \lim_{x \to 0} \int_{0}^{+\infty} \left\{ -\kappa r e^{rx} \sum_{j=1}^{4} m_{j} p_{j} K_{j} R_{j} + \frac{1}{1-\nu} \sum_{j=1}^{4} p_{j} K_{j} R_{j} e^{\frac{m_{j}x}{j}} + a^{2} \sum_{j=1}^{4} K_{j} R_{j} e^{\frac{m_{j}x}{j}} \right\} \cos \alpha (t-y) d\alpha.
$$
 (5.81)

Next Eqns. **5.69,70,74,76** are substituted into **Eqns. 5.80,81** to obtain

$$
-f_1(y) = -\frac{1}{\pi} \lim_{x \to 0} \int_{L_h} \sum_{k=1}^{2} u_k(t) \int_0^{+\infty} \frac{a^3}{D(a)} \sum_{j=1}^{4} \frac{\gamma_{kj}}{m_j} e^{\frac{m_j x}{2}} \cos \alpha (t-y) da dt +
$$
\n(5.82)

$$
\frac{-\lambda^4}{1-\nu}f_2(y) = \frac{1+\nu}{\pi} \lim_{x \to 0} \int_{L_n k=1} \sum_{k=1}^2 u_k(t) \int_0^{+\infty} \frac{a}{b(a)} \sum_{j=1}^4 \frac{\gamma_{kj}}{m_j} K_j \left\{-\kappa r m_j p_j e^{rx} + \right.
$$

$$
+\frac{1}{1-\nu} \left(m_j^2 - \nu a^2\right) e^{m_j x} \bigg\} \cos \alpha (t-y) \, da \, dt \quad . \tag{5.83}
$$

The infinite integrals **must** now be analyzed. These integrals may not **exist without** the **exponential** decay in **x.** In the limit as x **gets** small, the leading order term at a approaching infinity provides the integral that must be interpreted in the finite-part sense or perhaps in the Cauchy principal value sense, see Appendix B. Also the large α behavior must be determined so that the infinite integrals will numerically converge. The more terms that are known, the more accurate/less expensive the numerical integration. This analysis is presented in section J.2 of Appendix J. The form of the equations after using these results is,

$$
-f_{1}(y) = \frac{1}{2\pi} \int_{L_{n}} \frac{u_{1}(t)}{t-y^{2}} dt +
$$

\n
$$
+ \beta_{1}^{11} \frac{1}{\pi} \int_{L_{n}} \ln|t-y| u_{1}(t) dt + \beta_{1}^{12} \frac{1}{\pi} \int_{L_{n}} \ln|t-y| u_{2}(t) dt +
$$

\n
$$
- \frac{1}{\pi} \int_{L_{n}} u_{1}(t) \int_{0}^{A} \left\{ \frac{a^{3}}{b(a)} \sum_{j=1}^{4} \frac{1}{m_{j}} - \frac{a}{2} \right\} \cos a(t-y) da dt +
$$

\n
$$
- \frac{1}{\pi} \int_{L_{n}} u_{2}(t) \int_{0}^{A} \frac{a^{3}}{b(a)} \sum_{j=1}^{4} \frac{1}{m_{j}} \cos a(t-y) da dt +
$$

\n
$$
- \frac{1}{\pi} \int_{L_{n}} u_{1}(t) \overline{1}_{11}(t,y) dt - \frac{1}{\pi} \int_{L_{n}} u_{2}(t) \overline{1}_{12}(t,y) dt , \quad (5.84)
$$

\n
$$
\frac{-\lambda^{4}}{1-\nu^{4}} \int_{2} (y) = \frac{1+\nu}{2\pi} \int_{L_{n}} \frac{u_{2}(t)}{t-y^{2}} dt +
$$

\n
$$
- \beta_{1}^{21} \frac{1}{\pi} \int_{L_{n}} \ln|t-y| u_{1}(t) dt - \beta_{1}^{22} \frac{1}{\pi} \int_{L_{n}} \ln|t-y| u_{2}(t) dt +
$$

\n
$$
+ \frac{1}{\pi} \int_{L_{n}} u_{1}(t) \int_{0}^{A} \frac{a}{b(a)} \sum_{j=1}^{4} \frac{1}{m_{j}} K_{j} \left\{ -\kappa r m_{j} p_{j} +
$$

$$
+ \frac{1}{1-\nu} (\mathbf{m}_{j}^{2} - \nu a^{2}) \quad \cos a(t-y) \quad \text{d}a \quad \text{d}t +
$$
\n
$$
+ \frac{1}{\pi} \int_{L_{n}} u_{2}(t) \int_{0}^{A} \left[\frac{a}{D(a)} \sum_{j=1}^{4} \frac{\gamma_{2j}}{m_{j}} K_{j} \left\{ -\kappa r m_{j} p_{j} + \frac{1}{1-\nu} (\mathbf{m}_{j}^{2} - \nu a^{2}) \right\} + \frac{(1+\nu)a}{2} \right] \cos a(t-y) \quad \text{d}a \quad \text{d}t +
$$
\n
$$
+ \frac{1}{\pi} \int_{L_{n}} u_{1}(t) \overline{1}_{21}(t,y) \quad \text{d}t + \frac{1}{\pi} \int_{L_{n}} u_{2}(t) \overline{1}_{22}(t,y) \quad \text{d}t \quad . \quad (5.85)
$$

All quantities not **defined** in this chapter **are** given in Appendix J.

5.3 Symmetric Loadin_t Mode I_ **results.**

As mentioned **at** the start of **this chapter,** the primary motivation **for this analysis is** to study the **effect** of shell **curyature** on **crack interaction as** seen **through** the SIFs. **This** problem has been **considered** by Erdogan **and** Ratwani **[73],** by using the **classical** shell **theory.** As with the single **crack** solution, the **theory** used here that includes transverse shear deformations is better suited **for this** problem.

The results presented in Figs. **5.1-4,** show the **effect** of **cylinder** radius on the stresses **ahead** of **a** single **crack** (both **axial,** Figs. 5.1,2, **and circumferential,** Figs. **5.3,4)** of length **a/h=1** subjected to **crack** surface tension **and** bending loads. It is observed that **although** the primary stresses **are** not **considerably** different **from those** of the plate solution (R/h_®), the secondary values **are** now non-zero **and increase with** decreasing **radius.** These **effects would** be magnified **for** larger **a/h.** The results for **axial cracks** seem to be more sensitive to curvature in *tension than* **for** the **circumferential crack and** the **reverse** is *true* for bending.

The out-of-plane displacement w(O+,y), **or bulging of a single crack has been examined** in **[28], and has** been **used as an** interpretation for the trends **observed in** the **crack** interaction **problem [73]. In Fig. 5.5** the tension **and bending results** for an **axially cracked cylinder** with **radius** R/h=lO **are presented for various crack lengths. Fig. 5.6** gives the **results for a circumferential crack. In** these **plots** the **zero** is **fixed at y/a=O in** the **deformed** state. Again it is **observed that** the **axial crack has** more **complicated** behavior in tension, while the **circumferential orientation shows a** similar trend **in bending. For** these **loadings** the w **displacement** in the **region ahead of** the **crack** tip **has** more **of a** tendency to become **negative.**

The symmetric double crack SIF solutions are **presented in tables 5.1-8. The** geometries are **again** the **axially cracked cylinder, a/h=l** in **5.1 (tension) and** 5.2 **(bending), a/h=2 in 5.3 (tension) and** 5.4 **(bending), and** the **circuaferentially cracked cylinder** where these **four cases are repeated** in tables **5.5-8. For** both geometries the **primary stress** intensity **factor** increases **for decreasing radius** in tension, **and decreases** for **decreasing** radius **in** bending. Again the axial **crack** is more **sensitive** to **curvature** than the **circumferential crack** in tension and the **circumferential crack is** similarly more sensitive to **curvature** in bending. **The** secondary **SIFs decrease** with increasing **cylinder radius except for** the **outer crack** tip **of** the **circumferential crack, a/h=2 loaded** in tension **presented** in **Fig.** 5.7. **Also** the

secondary values have **fluctuations** for increasing **separation.** This type of **behavior was not** observed **with** the **primary** SIFs **as** it was by Erdogan **and** Ratwani [73]. **It** is **possible that** for **larger a/h** the **curvature effect** is strong **enough** that **there can** be **regions of** increase **of** the **SIFs as** the **cracks** get **farther apart.** The shortest **crack** for **which this trend** was **observed in** Ref. **[73] was a/h=2.5** for R/h=5. Because of **convergence** difficulties **and** the shallow shell **assumption, longer cracks were** not **investigated.**

5.4 Skew-Symmetric Loading, Modes 2,3

There are currently five unknowns in the problem, $A(a)$, and $R_i(a)$ for **j=1,2,3,4.** The first step is to reduce **this** to **three** unknowns by using the **symmetry conditions,**

$$
N_{xx}(0, y) = 0 \quad , \tag{5.86}
$$

$$
\mathbf{M}_{\mathbf{xx}}(0,\mathbf{y}) = 0 \quad . \tag{5.87}
$$

Then replace the **remaining** unknowns with **the crack** surface displacements,

$$
g_3(y) = u_3(y) = w(x_2)/h = w(0^+, x_2)/h , \qquad (5.88)
$$

$$
g_{4}(y) = u_{4}(y) - (\lambda_{2}/\lambda)^{2} y u_{3}(y) = v(x_{2})/h - (\lambda_{2}/\lambda)^{2} x_{2} w(x_{2})/h^{2},
$$

= v(0⁺, x₂)/h - (\lambda_{2}/\lambda)^{2} x_{2} w(0⁺, x₂)/h^{2}, (5.89)

$$
u_4(y) = v(x_2) = g_4(y) + (\lambda_2/\lambda)^2 y g_3(y) , \qquad (5.90)
$$

$$
g_5(y) = u_5(y) = \beta_y(x_2) = \beta_y(0^+, x_2) , \qquad (5.91)
$$

where $u_i(y)$ are the crack opening displacements and $g_i(y)$ are the

unknowns to be used. The in-plane displacement component, i=4, determines this, see Eqns. $5.57,58$. If u_4 were used as an unknown the resulting matrix would not be diagonally dominant **and** there may be numerical problems. The equations that relate $g_i(y)$ to the original unknowns **are:**

$$
A(\alpha) = \frac{2}{i\alpha\kappa(1-\nu)^2} \sum_{j=1}^{4} (\mathbf{m}_j^2 - \nu \alpha^2) K_j R_j
$$
 (5.92)

$$
\frac{1}{1-\nu}\sum_{j=1}^{4} p_j K_j R_j = q_5(a) , \qquad (5.93)
$$

$$
\frac{4}{j=1}R_j = 0 \t , \t (5.94)
$$

$$
\sum_{j=1}^{4} m_j^2 R_j = q_4(\alpha) , \qquad (5.95)
$$

$$
\sum_{j=1}^{4} R_j K_j (\kappa p_j - 1) = \frac{i}{\alpha} q_3(\alpha) , \qquad (5.96)
$$

where

$$
q_k(a) = -ia \int_{-\infty}^{+\infty} g_k(t) a e^{iat} dt
$$
, $k=3,4,5$. (5.97)

The solution to Eqns. **5.93-96** is

$$
R_{j}(a) = \sum_{k=3}^{5} \frac{\gamma_{kj} q_{k}}{D(a)}, \quad j=1,2,3,4 \quad ,
$$
 (5.98)

where $D(a)$ is the same as Eqn. 5.71 and γ_{kj} are as follows:

$$
\gamma_{31} = \frac{-i}{a} \Big\{ K_3 P_3 (P_4 - P_2) + K_4 P_4 (P_2 - P_3) + K_2 P_2 (P_3 - P_4) \Big\} ,
$$

$$
\gamma_{32} = \frac{i}{a} \Big\{ K_3 P_3 (P_4 - P_1) + K_4 P_4 (P_1 - P_3) + K_1 P_1 (P_3 - P_4) \Big\} ,
$$

$$
\gamma_{33} = \frac{1}{a} \Big\{ K_{2}p_{2}(p_{4}-p_{1}) + K_{4}p_{4}(p_{1}-p_{2}) + K_{1}p_{1}(p_{2}-p_{4}) \Big\},
$$
\n
$$
\gamma_{34} = \frac{1}{a} \Big\{ K_{2}p_{2}(p_{3}-p_{1}) + K_{3}p_{3}(p_{1}-p_{2}) + K_{1}p_{1}(p_{2}-p_{3}) \Big\},
$$
\n
$$
\gamma_{41} = \Big\{ K_{3}K_{4}(p_{4}-p_{3}) + K_{2}K_{4}(p_{2}-p_{4}) + K_{2}K_{3}(p_{3}-p_{2}) \Big\},
$$
\n
$$
\gamma_{42} = -\Big\{ K_{3}K_{4}(p_{4}-p_{3}) + K_{1}K_{4}(p_{1}-p_{4}) + K_{1}K_{3}(p_{3}-p_{1}) \Big\},
$$
\n
$$
\gamma_{43} = \Big\{ K_{4}K_{2}(p_{4}-p_{2}) + K_{1}K_{4}(p_{1}-p_{4}) + K_{2}K_{1}(p_{2}-p_{1}) \Big\},
$$
\n
$$
\gamma_{44} = -\Big\{ K_{3}K_{2}(p_{3}-p_{2}) + K_{1}K_{3}(p_{1}-p_{3}) + K_{2}K_{1}(p_{2}-p_{1}) \Big\},
$$
\n
$$
\gamma_{51} = -(1-\nu)\Big\{ K_{4}(kp_{4}-1)(p_{3}-p_{2}) + K_{3}(kp_{3}-1)(p_{2}-p_{4}) + K_{2}(kp_{2}-1)(p_{4}-p_{3}) \Big\},
$$
\n
$$
\gamma_{52} = (1-\nu)\Big\{ K_{4}(kp_{4}-1)(p_{3}-p_{1}) + K_{3}(kp_{3}-1)(p_{1}-p_{4}) + K_{1}(kp_{1}-1)(p_{4}-p_{3}) \Big\},
$$
\n
$$
\gamma_{53} = -(1-\nu)\Big\{ K_{4}(kp_{4}-1)(p_{2}-p_{1}) + K_{2}(kp_{2}-1)(p_{1}-p_{4}) + K_{1}(kp_{1}-1)(p_{4}-p_{2}) \Big\},
$$
\n
$$
\gamma_{54} = (1-\nu)\Big\{ K_{3}(kp_{3}-1)(p_{2}-p_{1}) + K_{2}(kp_{2}-1)(p_{1}-
$$

The following mixed boundary **conditions will** produce three singular integral **equations** for the determination of the **crack** opening **displacements** :

$$
V_x(0^+, y) = -f_3(y)
$$
, y in L_n, (5.100)

$$
g_3(y) = w(0^+, y) = 0
$$
, y outside of L_n , (5.101)

$$
N_{xx}(0^+, y) = -f_4(y) , y in L_n , \qquad (5.102)
$$

$$
g_4(y)=v(0^+,y)-(\lambda_2^2/\lambda)^2yw(0^+,y)=0 \quad , y \text{ outside of } L_n , \quad (5.103)
$$

186

 $C - 3$

$$
M_{xy}(0^+, y) = -f_5(y) , y in L_n , \qquad (5.104)
$$

$$
g_5(y) = \beta_y(0^+, y) = 0
$$
, y outside of L_n. (5.105)

See Eqn. 5.77 for the definition of **L**_n. Eqns. 5.100,102,104 with **5.48,53,54,92** become:

$$
-f_{3}(y) = \frac{1}{2\pi} \lim_{x \to 0} \int_{-\infty}^{+\infty} \left\{ \frac{-1}{r(1-\nu)} \sum_{j=1}^{4} (\mathbf{m}_{j}^{2} - \nu a^{2}) K_{j} R_{j} e^{TX} + \kappa \sum_{j=1}^{4} \mathbf{m}_{j} p_{j} K_{j} R_{j}(a) e^{M_{j}^{2}} \right\} e^{-i\alpha y} d\alpha , \qquad (5.106)
$$

$$
-f_4(y) = \frac{i}{2\pi} \lim_{x \to 0} \int_{-\infty}^{+\infty} a \sum_{j=1}^4 m_j R_j(a) e^{m_j x} e^{-i\alpha y} d\alpha , \qquad (5.107)
$$

$$
-\frac{2\lambda^{4}}{1-\nu}f_{5}(y) = \frac{1+\nu}{2\pi}\lim_{x\to 0}\int_{-\infty}^{+\infty}\left\{\sum_{j=1}^{4}K_{j}R_{j}\left[-\frac{e^{TX}(a^{2}+r^{2})}{i\alpha r(1-\nu)}(\mathfrak{m}_{j}^{2}-\nu a^{2}) - 2i\alpha\mathfrak{m}_{j}e^{m_{j}x}\right]\right\} e^{-i\alpha y} d\alpha
$$
 (5.108)

After **asymptotic analysis, see section J.3 of** Appendix J, **these three equations** may be **expressed as,**

$$
-f_{3}(y) = \frac{1}{\pi} \oint_{L_{n}(t-y)} \frac{g_{3}(t)}{2} dt + \kappa \lambda^{2} \Big[\frac{1}{8} (\lambda_{2}^{2} - \lambda_{1}^{2}) - \frac{1}{2} \lambda_{2}^{2} \Big] \frac{1}{\pi} \int_{L_{n}} \frac{g_{4}(t)}{t-y} dt + \Big[\beta_{1}^{33} + (\lambda_{2}/\lambda)^{2} \beta_{0}^{34} \Big] \frac{1}{\pi} \int_{L_{n}} \ln|t-y| g_{3}(t) dt + \frac{1}{\pi} \int_{L_{n}} g_{3}(t) \int_{0}^{A} \Big[\frac{-1}{\pi} \sum_{j=1}^{4} K_{j} \Big[i a \gamma_{3j} - (\lambda_{2}/\lambda)^{2} \gamma_{4j} \Big] x + \frac{1}{\pi} \int_{L_{n}} g_{3}(t) \int_{0}^{A} \Big[\frac{-1}{\pi} \sum_{j=1}^{4} K_{j} \Big[i a \gamma_{3j} - (\lambda_{2}/\lambda)^{2} \gamma_{4j} \Big] x + \frac{1}{\pi} \int_{L_{n}} \frac{g_{3}(t)}{f(1-y)} + \kappa m_{j} p_{j} \Big] + a \Big\} \cos \alpha(t-y) d\alpha dt +
$$

=

$$
+\frac{1}{\pi}\int_{L_{n}}g_{4}(t)\int_{0}^{A}\left\{\frac{a}{b(a)}\frac{4}{j-1}k_{j}^{2}A_{j}\right\}\left[\frac{-(m_{1}^{2}-\nu a^{2})}{r(1-\nu)}+\kappa m_{j}P_{j}\right]-\n- \kappa \lambda^{2}\left[\frac{1}{8}(\lambda_{2}^{2}-\lambda_{1}^{2})-\frac{1}{2}\lambda_{2}^{2}\right]\sin(\tau-y) d\alpha dt + \n+ \frac{1}{\pi}\int_{L_{n}}g_{5}(t)\int_{0}^{A}\frac{a}{b(a)}\frac{4}{j-1}k_{j}^{2}S_{j}\left[\frac{-(m_{1}^{2}-\nu a^{2})}{r(1-\nu)}+\kappa m_{j}P_{j}\right] \sin(\tau-y) d\alpha dt + \n+ \frac{1}{\pi}\int_{L_{n}}g_{3}(t)\overline{I}_{33}(t,y) dt + \frac{1}{\pi}\int_{L_{n}}g_{4}(t)\overline{I}_{34}(t,y) dt + \n+ \frac{1}{\pi}\int_{L_{n}}g_{5}(t)\overline{I}_{35}(t,y) dt , \n+ \frac{1}{\pi}\int_{L_{n}}g_{5}(t)\overline{I}_{35}(t,y) dt , \n+ \frac{1}{\pi}\int_{L_{n}}\frac{g_{4}(t)}{g_{2}}\frac{1}{\pi}\int_{L_{n}}\frac{g_{3}(t)}{t-y} dt + \n- \frac{1}{\pi}\int_{L_{n}}\frac{1}{t}\int_{L_{n}}\left[t-\nu\right)^{2} dt + \frac{3\lambda_{2}^{2}+\lambda_{1}^{2}}{g_{2}}\frac{1}{\pi}\int_{L_{n}}\frac{1}{t}\int_{L_{n}}\frac{1}{t-y} d\tau + \n+ \frac{1}{\pi}\int_{L_{n}}\ln|t-y|g_{4}(t) dt - \frac{1}{\pi}\int_{L_{n}}\ln|t-y|g_{5}(t) dt + \n+ \frac{1}{\pi}\int_{L_{n}}g_{5}(t)\int_{0}^{A}\left(\frac{a^{2}}{b}\frac{4}{j-1}m_{j}^{2}T_{4j} - \frac{a^{2}}{2}\right) \cos(\tau-y) d\alpha dt + \n+ \frac{1}{\pi}\int_{L_{n}}g_{5}(t)\int_{0}^{A}\left(\frac{a^{2}}{b}\frac
$$

$$
-\frac{2\lambda^{4}}{1-\nu}f_{5}(y) = \frac{1+\nu}{\pi} \int_{L_{n}(t-y)^{2}}^{E_{5}(t)} dt +
$$
\n
$$
-\beta_{1}^{54} \frac{1}{\pi} \int_{L_{n}^{n}} \ln|t-y|g_{4}(t)dt - \beta_{1}^{55} \frac{1}{\pi} \int_{L_{n}^{n}} \ln|t-y|g_{5}(t)dt +
$$
\n
$$
+\frac{1}{\pi} \int_{L_{n}^{n}} g_{3}(t) \int_{0}^{A} (\frac{1}{1-\nu^{2}} - x_{3})^{2} [i\alpha \tau_{3} - (\lambda_{2}/\lambda)^{2} \tau_{4}]^{x}
$$
\n
$$
\times \left[\frac{a^{2}+r^{2}}{a\tau(1-\nu)} \left(\frac{a^{2}}{1-\nu} - \frac{a^{2}}{1-\nu} \right) \frac{a^{2}+r^{2}}{a\tau(1-\nu)} \left(\frac{a^{2}+r^{2}}{a\tau(1-\nu)} - \frac{a^{2}}{1-\nu^{2}} \right) \frac{1}{2} \cos(\tau - y) \right] ds dt +
$$
\n
$$
+\frac{1}{\pi} \int_{L_{n}^{n}} g_{4}(t) \int_{0}^{A} \frac{a}{\nu} \frac{4}{\nu^{2}} \int_{\frac{a}{2}} \int_{\frac{a}{2}} \int_{\frac{a^{2}+r^{2}}{a\tau(1-\nu)} \left(\frac{a^{2}-\nu a^{2}}{a\tau^{2}} - 2a\omega_{3} \right) \cos(\tau - y) \right] ds dt +
$$
\n
$$
+\frac{1}{\pi} \int_{L_{n}^{n}} g_{5}(t) \int_{0}^{A} \left(\frac{a}{\nu} \frac{4}{\nu^{2}} \int_{\frac{a}{2}} \
$$

5.5 Skew-Symmetric Loading, Mode 2 and 3, results.

The results for the interaction of two **equal** length (a/h=1) **cracks in** a **cylinder** are presented in tables **5.9-11** (axial) and **5.12-** 14 (circumferential). **The** three possible loadings, **in-plane** shear, twisting, and **out-of-plane** shear are **included. The effect** of **curvature** is not as strong as for the symmetric problem of Sec. **5.3.**

Also the difference between the axial and the circumferential crack is minimal, especially for twisting, see tables 5.10,13. Both primary and secondary values of the SIFs change very little. The only trends that can be observed with respect to curvature are the mode 3 component **of** the SIF for in-plane shear loading is greater for the circumferential crack, see tables 5.9,12, and for out-of-plane shear there is **a** notable difference in the in-plane shear component of the SIF, *again* greater for the circumferential crack, 5.11,14.

Table **5.2** Mode 1 normalized stress intensity factors **for** symmetric **collinear** axial **cracks** in **a cylinder** of radius R/h subjected to bending. The inner **and** outer **crack** tips **are** located **at** y/a=*_, $-$ c respectively where $a/n = (c-v)/(2n)-1$, $v_2 = 6m_v/n$, $\nu=0.3$, $M+N_{\chi}$, $B+M_{\chi}$.

Table **5.3** Mode 1 normalized stress intensity **factors** _or symmetric **collinear** axial **cracks** in **a** cylinder of radius R/h subjected to membrane loading. The inner and outer **crack** tips are located at y/a=*b, *c respectively where a/h=(c-D)/(2n)=2, $v_1=_{\mathbf{N_Y}}$ /n, $\nu=0.3$, $m=n_x$, $D^m n_x$.

Table 5.4 Mode I normalized stress intensity factors for symmetric **collinear** axial **cracks** in **a cylinder of** radius R/h subjected to bending. The inner **and** outer **crack** tips **are** located st y/a_, \mathbb{P}^{c} respectively where $a/n = (c-b)/(2n) = 2$, $\mathcal{O}_2 = 0m_\chi/n$, $\nu = .3$, $M \rightarrow N_{\chi}$, $B \rightarrow M_{\chi}$.

Table 5.5 Mode 1 **normalized** stress intensity **factors** for symmetric collinear circumfere **cracks** in **a cylinder of radius R/h subjected** to membrane loading. The inner and outer crack tip are located at $y/a=$ b, \pm c respectively where $a/n=(c-p)/(2n)=1, v_1=n_x/n, v=.3, m=n_x, p=m_x.$

Table 5.7 Mode 1 normalized stress intensity factors for symmetric collinear circumfer cracks in a cylinder of radius R/h subjected to membrane loading. The inner and outer crack tip are located at y/a=*b, ***c** respectively **where** a/h=(c-b)/(2h)=2, Ol=Nx/h , *v=.3,* M+Nx, **B+M**x.

ALADKANL LUADING								
	b/a R/h	0.05	0.125	0.25	0.5	1	→∞	
	5 10	1.992 1.868	1.569 1.472	1.372 1.283	1.261 1.171	1.211 1.118	1.124 1.066	
$\frac{k_{\mathbf{M}}(b)}{\sigma_1 \sqrt{a}}$	20 50	1.821 1.801	1.435 1.419	1.248 1.234	1.134 1.118	1.075 1.055	1.034	
	$+00$	1.795	1.414	1.229	1.112	1.048	1.014 1.000	
$\frac{k_{\mathbf{M}}(c)}{\sigma_1\sqrt{a}}$	5 10 20 50 $+00$	1.325 1.221 1.177 1.157 1.115	1.278 1.180 1.138 1.118 1.112	1.244 1.149 1.107 1.087 1.081	1.216 1.123 1.080 1.059 1.052	1.193 1.106 1.061 1.037 1.028	1.124 1.066 1.034 1.014 1.000	
$\frac{k_B(b)}{\sigma_1\sqrt{a}}$	5 10 20 50 $+00$.212 .236 . 207 .140 .000	. 133 .163 .148 . 102 .000	.084 .117 . 110 .078 .000	.055 .081 .080 .059 .000	.061 .065 .060 .045 .000	.112 .099 .073 .043 .000	
$\frac{k_B(c)}{\sigma_1\sqrt{a}}$	5 10 20 50 $+00$.056 .082 .087 .068 .000	.058 .075 .077 .060 .000	.062 .070 .068 .053 .000	.073 .067 .060 .045 .000	.093 .072 .056 .039 .000	.112 .099 .073 .043 .000	

MBMB_NB LOADING

Table 5.9 Modes 2&3 normalized stress intensity factors for symmetric collinear axial cracks in **a** cylinder of radius R/h subjected to in-pl shear. The inner and outer crack tips are locat at y/a=*b, *c respectively where a/h=(c-b)/ $\sigma_4^{-N}xy^{n}$, ν^2-3 , μ^2N_y , μ^2m_y , σ^2N_x

Modes 2&3 normalized stress intensity Table 5.10 factors for symmetric collinear axial cracks in a cylinder of radius R/h subjected to twisting. The
inner and outer crack tips are located at $y/a=+b$,
*c respectively where $a/h=(-b)/(2h)=1$, $\sigma_5=6M_{xy}/h^2$, n.

$$
\nu=3,\quad 1^{+1}\mathrm{N}_{\mathrm{xy}},\quad 1^{+1}\mathrm{M}_{\mathrm{xy}},\quad 0^{+1}\mathrm{V}_{\mathrm{x}}.
$$

Table 5.11 Modes 2&3 normalized stress intensity factors for symmetric collinear **axial** cracks in **a** cylinder of radius R/h subjected to out-of-plan shear. The inner **and** outer crack tips **are** located **at** y/a=ib, *c respectively where **a/h=(c-b)/(2h)=l,** σ_3 ⁻³*_x/(2h), ν ^{-.}..., T_{xy} , T_{xy} , T_{xy} , T_{xy}

Table 5.12 **Modes** 2&3 normalized stress intensity factors for symmetric collinear circumferential cracks in **a** cylinder of radius **R/h** subjected to in-plane shear. The inner and outer crack tips ar located at $y/a=$ **b**, \pm c respectively where $a/h=0$ b ⁻¹/(2h)⁻¹, a_4 ⁻¹xy^{/h}, ν ⁻¹, σ , $\frac{1}{N}$ xy^{, $\frac{1}{N}$ m}xy, $0.$

Table 5.13 Modes 2&3 normalized stress intensity factors for symmetric collinear circumferential cracks in a cylinder of radius R/h subjected to
twisting. The inner and outer crack tips are located at $y/a=1$, $\pm c$ respectively where $a/h=(c-h)/(2h)-1$, $\sigma_f=8h/(2h)-2$, $I-N$, $I-N$, $I-N$, $I-N$

Table 5.14 Modes 243 normalized stress intensity factors for symmetric collinear circumferential cracks in a cylinder of radius R/h subjected to out-of-plane shear. The inner and outer crack tips are located at y/a=*b, *c respectively wher a/\ln $(c-\nu)/$ $(a\ln)$ –1, $v/3$ – v_x $\left(\ln\frac{1}{x}\right)$, $v=0$, $1/\ln\frac{1}{x}$ $\left(\ln\frac{1}{x}\right)$ $0+V_x$.

				UVI-UI-I DAND JADAR			
	b/a	0.05	0.125	0.25	0.5	$\mathbf{1}$	$\rightarrow \infty$
	R/h						
	5	2.565	1.897	1.632	1.537	1.532	1.547
$k_{30}(b)$	10	2.793	2.047	1.751	1.641	1.628	1.635
	20	2.873	2.100	1.793	1.678	1.661	1.664
$\sigma_3 \sqrt{a}$.	50	2.902	2.119	1.809	1.691	1.673	1.674
	$+00$	2.909	2.124	1.182	1.694	1.677	1.676
	5	1.561	1.526	1.514	1.518	1.532	1.547
	10	1.694	1.643	1.621	1.618	1.626	1.635
$k_{30}(c)$	20	1.742	1.684	1.659	1.653	1.658	1.664
$\sigma_3\sqrt{a}$	50	1.759	1.699	1.672	1.666	1.670	1.674
	$\rightarrow \infty$	1.763	1.702	1.675	1.669	1.673	1.676
	5	.040	.058	.076	.099	.124	.152
	10	.021	.030	.039	.050	.063	.081
$\frac{k_{2I}(b)}{\sigma_3\sqrt{a}}$	20	.010	.015	.019	.025	.031	.042
	50	.004	.006	.008	.010	.012	.017
	$\rightarrow \infty$.000	.000	.000	.000	.000	000
	5	$-.222$	$-.201$	$-.187$	$-.176$	$-.164$	- .152
	10	$-.127$	$-.114$	$-.106$	$-.099$	$-.093$	$-.081$
	20	$-.067$	$-.060$	$-.056$	$-.052$	$-.049$	- .042
$\frac{k_{2I}(c)}{\sigma_3\sqrt{a}}$	50	$-.027$	$-.025$	$-.023$	$-.022$	$-.020$	$-.017$
	$+00$.000	.000	.000	.000	.000	.000
	5	$-.067$	$-.141$	$-.230$	$-.331$	$-.400$	$-.422$
$k_{2T}(b)$	10	$-.071$	$-.151$	$-.244$	$-.350$	$-.423$	$-.452$
	20	$-.073$	$-.154$	$-.249$	$-.357$	$-.430$	$-.462$
$\sigma_3\sqrt{a}$	50	$-.074$	$-.155$	$-.251$	$-.359$	$-.433$	$-.465$
	$\rightarrow \infty$	$-.074$	$-.155$	$-.251$	$-.360$	$-.433$	$-.466$
	5	.500	.460	.437	.424	.418	.422
$k_{2T}(c)$	10	.557	.509	.480	.463	.454	.452
	20	.578	.526	.496	.477	. 467	.462
$\sigma_3\sqrt{a}$	50	.586	.533	.502	.483	.472	.465
	$+00$.588	.535	.504	. 484	.474	.466

OUT-OF-PLANE SHEAR

Figure 5.1 Stresses ahead of an axial crack $(a/h=1)$ in a cylinder subjected to membrane loading, $\nu=0.3$.

 $\overline{\bullet}$

0.

 $\overline{\mathbf{1}}$.

 $\frac{1}{1.5}$
 y/a

 \vec{z} .

Figure 5.2 Stresses ahead of an axial crack $(a/h=1)$ in a cylinder subjected to bending. The dashed line corresponds to $R/h + \infty$, $\nu = .3$.

Figure 5.3 Stresses ahead of a circumfere crack (a/h=1) in a cylinder subjected to membran loading, *v=.3.*

L

 y/a

Figure 5.4 Stresses ahead of a circumferent crack (a/h=l) in **a cylinder subjected** to **bending,** $\nu = .3$.

Figure 5.5 Out-of-plane **displacement** w(O+,y) **as measured from y=O** in the **deformed position for a cylinder** with an axial crack subjected to eith membrane loading $(\sigma_m=\mathbb{R}_x/h)$ or bending $(\sigma_b=6\mathbb{R}_x/h^2)$, *//=-.3.*

20g

Figure 5.6 Out:of-plane **displacement** w(O+,y) **as** measured **from** y=O in the deformed position **for a** cylinder **with a** circumferential crack **subjected** to either membrane loading $(\sigma_m=\stackrel{\circ}{\mathbb{R}}_x/h)$ or bending $(\sigma_{b} = 6\frac{\omega}{M}/h^{2})$, $\nu = .3$.

CHAPTER 6

Part-Through Cracks in Shells

The singular integral equations **for** part-through crack **problems** are obtained directly from the corresponding through crack equations given in •Chapter S. The compliance relations of **Chapter** 2 **and** Appendix **C are** used even *though they* correspond to the strip solution which does not *take* into account shell curvature. The **plane** strain problem for **an edge cracked cylinder** [74], **and** the axisynetric **case** of **a** circumferentially cracked cylinder [75], could be used **to** obtain these coefficients, but there **are** convergence problems for **sheli-like geometries, and also a** different **set** of constants would be required **for** each curvature. Since the **assumption** of **shallowness** has **already** been applied, neglect of this curvature effect **should not** be too significant, **see** [60]. **The** line-spring model solutions **are normalized** with respect to the edge crack solution **as** explained in section **C.4** of Appendix **C.** Perhaps if the solution is Considered to be normalized with respect to the actual "long crack" shell solution instead of the plane strain strip value, the **accuracy of** the result will **improve.** This idea is similar to what happens when **a** compliance curve that is not too **accurate** is **used.** The resulting ratio is more **accurate** than the **actual** value of the SIF.

There **are** some basic differences between plate and **shell** problems besides the mathematical complication that shell curvature introduces. In a plate, loading at **"infinity"** for **any of** the five loads of tension

 (N_{xx}) , bending (M_{xx}) , out-of-plane shear (V_x) , in-plane shear (N_{xy}) , and twisting (M_{xy}) , results in an "uncracked" solution that is constant throughout the plate. Therefore, in the perturbation problem, the solution to the various loading cases is obtained by simply **applying** the negative of these loads to the crack surfaces. The process of determining the perturbation **loads** in shells for **a** given **external** loading is not **as** e_sy. In **a** cylinder, for **example, any** loading **at** infinity can result only in membrane or in-plane shear at the crack region, (excluding minor secondary contributions). The loading cases of bending, out-of-plane shear **and** twisting become important **when an external** force **is applied near** the **crack** region. **To** make use of the various shell solutions, the solution to the shell without **a crack** must first be obtained. Thiswill in general require numerical techniques.

With the present formulation the surface **crack can** lie **along any** principal line of constant curvature of a shell. This uncouples the symmetric model loading, **from** the skew-symmetric loading that **couples** modes **2 and 3.** If the **crack were** positioned **at an arbitrary angle,** then **all** three **fracture** modes interact, see [30]. The most practical problem represented here **would** be **a** mode 1 **contribution** resulting from torsion of **a cylinder.**

The different geometries that **are considered** include the sphere, **cylinder and circular** pipe **elbow, which** is represented by **a** toroidal shell. Also the **crack** may lie on the outside or **inside** of the shell by **imposing** positive or negative **curvature,** respectively. The

emphasis in the **results** will be the effect of curvature on the **SIF at** the maximum penetration point **of a** semi-elliptical **surface** crack.

6.1 _ode **1.**

From Eqns. 5.84,85, 2.31, and from the **superposition of** Fig. **C.1,** the integral **equations for the symetrically loaded part,through crack are found** to be:

$$
\frac{1}{2\pi} \int_{a}^{b} \frac{u_{1}(t)}{(t-y)^{2}} dt + \frac{1}{\pi} \sum_{i=1}^{2} \int_{a}^{b} u_{i}(t) K_{i1}(z) dt
$$

\n
$$
- \eta_{11} u_{1}(y) - \eta_{12} u_{2}(y) = -\tilde{N}_{x} = -\tilde{\sigma}_{1} , \qquad (6.1)
$$

\n
$$
\frac{(1-y^{2})}{\lambda^{4} 2\pi} \int_{a}^{b} \frac{u_{2}(t)}{(t-y)^{2}} dt + \frac{1}{\pi} \sum_{i=1}^{2} \int_{a}^{b} u_{i}(t) K_{i2}(z) dt
$$

\n
$$
- \eta_{12} u_{1}(y) - \eta_{22} u_{2}(y) = -\tilde{N}_{x} = -\tilde{\sigma}_{2} / 6 , \qquad (6.2)
$$

where the **kernels** may be obtained **from Eqns. 5.84,85 and** Appendix **J.** The LSM for inner surface cracks in a pressurized cylinder is compare to **solutions from Raju and Newman [34]** in **Fig. 6.1, and** to **solutions from O'Donoghue et. al. [40]** in **Fig. 6.2. The only case where** agreement is poor is for the semi-circular crack with $a/h=L_0/h=.2$, **which** is **a rather severe geometry for** the **model. Outward bulging of** the **shell surface along** the **line of** the **crack** is **presented** in Fig. **6.3 for an outer circumferential crack** in **a cylinder. Fig. 6.4 shows** the **inner** crack case **where** the bulging is **inward. The** tension case **of 6.4 shows** that the **depression does not always** increase **as** the **crack** gets **deeper (i.e. increasing Lo/h)** because **of** the tendency **of** the **crack** to bulge outward **when** there is no net ligament. The net ligament **causes** a bending **component** that forces the surface inward and these two **effects** oppose **each** other. Therefore it **would** be difficult to predict **crack** depth by **a** measurement from the back surface.

To date, **as far as I** know, the LSM has only been **applied** to **cracked cylinders,** see **for example** [49,60]. In tables 6.1-5 the solution to the spherical shell is **presented** for both inner **and** outer **cracks** of varying depths **and** lengths. It is noted that the results **are** sensitive to **curvature.** Also for **a** given geometry the SIFs **are** higher for the **external crack** than for the internal **crack.** In table 6.6 the SIF distribution **along** the **contour** of **a** semi-elliptical **crack** located **at** different positions in **a** toroidal shell is **presented.** The four locations, denoted A through D, **are** shown in Fig. 6.5. Also the **crack** may be internal or **external,** making **a** total of **eight cases** that **are** given in this table, **and** in the tables that **follow.** It is noted that the functional behavior of the SIF does not vary much from position to position. This supports giving only the value of the SIF **at** the **center** of the **crack.** Therefore, the plate results may be used to get **an** idea about this distribution given the **crack** size and maximum penetration value. These results are given in Chapter 4 **for a** wide range of crack lengths and depths. The toroidal shell resul for mode **1** loading **are presented in tables 6.7-22. In these tables** the **cylinder radius** to **shell** thickness **-ratio** is held **constant** at $R/h=10$. Ri/R, **see Fig.** *6.5.* **Values** of **crack length** to **shell** thickness **(a/h),** main **parameter study is** the **elbow curvature** given by

214

w

of .5, 1., 2., 4., are used. As expected, the longer the crack, the more the influence of elbow curvature. The results given in the *tables* are for constant crack surface membrane and bending loads. It should be **noted** that in **order** to **obtain** the solution to the practical case of an internally pressurized toroidal shell, or to any other **external** loading, the **uncracked shell** solution must first be obtained. **In** general this **solution** will **not** be **constant over** the length **of** the **crack.** This is **not** a **concern** with **either** the **sphere or cylinder** because the **uncracked** solution is **constant due** to symmetry. **However,** it is most **likely** the case that the **variation** is **not considerable** and that the **results** in the tables may be **directly** applied **once** the actual **crack surface** loading **is determined.**

6.2 Modes **2** and **3**

From Eqns. 5.109-111, **2.31,** and from the superposition **of Fig. C.1,** the integral **equations** for the **skew-symmetrically loaded part**through **crack** may be **expressed** as:

$$
\frac{1}{\pi} \int_{a}^{b} \frac{g_{3}(t)}{(t-y)^{2}} dt + \kappa \lambda^{2} \Big[\frac{1}{8} (\lambda_{2}^{2} - \lambda_{1}^{2}) - \frac{1}{2} \lambda_{2}^{2} \Big] \frac{1}{\pi} \int_{L_{n}} \frac{g_{4}(t)}{t-y} dt
$$

+
$$
\frac{1}{\pi} \sum_{i=3}^{5} \int_{a}^{b} g_{i}(t) K_{i3}(z) dt - \eta_{33} u_{3}(y) = -\eta_{x} = -8(1+\nu)/5 \sigma_{3} , (6.3)
$$

$$
\frac{1}{2\pi} \int_{a}^{b} \frac{g_{4}(t)}{(t-y)^{2}} dt + \frac{1}{\pi} \sum_{i=3}^{5} \int_{a}^{b} g_{i}(t) K_{i4}(z) dt
$$

-
$$
\eta_{44} u_{4}(y) - \eta_{45} u_{5}(y) = -\eta_{xy} = -\sigma_{4} , (6.4)
$$

$$
\frac{(1-\nu^2)}{\lambda^4 2\pi} \int_{a}^{b} \frac{g_5(t)}{(t-y)^2} dt + \left[\frac{3\lambda_2^2 + \lambda_1^2}{8\lambda^2}\right] \frac{1}{\pi} \int_{L} \frac{g_3(t)}{t-y} dt
$$

+ $\frac{1}{\pi} \sum_{i=3}^{3} \int_{a}^{b} g_i(t) K_{i5}(z) dt - \gamma_{54} u_4(y) - \gamma_{55} u_5(y) = -\frac{\omega}{2} \int_{xy}^{b} = -\frac{\omega}{2} \int_{a}^{b} (6.5)$

where,

$$
g_3(y) = w(0^+, y) = u_3(y) , \qquad (6.6)
$$

$$
g_4(y)=v(0^+,y)-(\lambda_2^2/\lambda)^2 y w(0^+,y) = u_4(y)-(\lambda_2^2/\lambda)^2 y u_3(y) , \qquad (6.7)
$$

$$
u_4(y) = g_4(y) + (\lambda_2^2/\lambda)^2 y g_3(y) , \qquad (6.8)
$$

$$
g_5(y) = \beta_y(0^+, y) = u_5(y) \tag{6.9}
$$

The Fredholm kernels may be **obtained from Chapter 5 and Appendix J.**

Because of the **assumption made** in **Eqn. 2.12 (see Eqn. 6.10) concerning self-similar crack growth under mode 2 loading, solutions** to these **equations apply only** to **cases where crack growth** is **coplanar. There** are **no solutions** to **compare** with as **in** the **mode 1 problem. If** the **results** can **be verified,** then the **mixed-mode solution involving all** three **modes should give good results.** However the **solution is not expected** to be **as** accurate **as for mode 1, since** it **was observed in Chapter 4** that there **is very little difference** in the **value of the secondary SIF** between the **rectangular** *and* the *semi-elliptical* **profiles. In** the **latter case** the **secondary value** *should* **become of primary importance** as the **ends** are **approached because of changing crack front curvature. Physically** the **problem** with the **model is** that **everything is calculated in a plane perpendicular** to the **plate**

surfaces, while the SIF is defined in a plane normal to the crack front. Considering this it is remarkable that the comparisons with the finite element solutions **are** so close for mode 1, see Figs. 4.1-4, 6.1,2. Perhaps the mechanism **of** the model is such that the energy release rate, the expression for **which** is repeated below,

$$
\frac{d}{dL}(U-V) = G = \frac{1-\nu^2}{E} \left\{ K_1^2 + K_2^2 + \frac{1}{1-\nu} K_3^2 \right\},
$$
 (6.10)

is more **accurate** than **the** individual **values of** the **SIFs. If** this is true, then it may explain **why** the **secondary value of** the line-spring SIF does not behave as expected, i.e. the above combination of K₂ and K_3 is more accurate. In the mode 1 case, it doesn't matter because there **is** only one non-zero **value.** Since the **secondary value is zero** in the center of the crack due to symmetry, the primary SIF may not be too **affected** by the **rest** of the curve. **This** of course **is** the **most** dependable value calculated by the LSM.

The results in tables **6.23-34** are for **axial and** circumferential semi-elliptical cracks in a cylinder of varying radius. Crack lengths and depths are also **varied.** The value at the center of the crack is reported. In the case of twisting, as can be **seen from** the plate **results** of **Chapter 4,** the maximum is **typically at** the **ends. This** is because of the strip results from Appendix C, table C.1 (σ_{5}) , where the **SIF decreases as** the **crack** goes deeper into the **plate.** As with the mode **1 results,** the plate solutions may be **used** to get **an** idea of the character **of** the distribution. The results **for** out-of-plane **shear are** nearly **insensitive to** radius, except **for** long and deep cracks. The **in-plane shear,** the most important loading case, behaves in **a** more

reasonable way. More results for the toroidal **shell are** presented in tables **6.35-46 for a/h=l,2, and** R/h=lO. **As** with the mode 1 tables, the elbow curvature is the parameter that is of most interest. **Again** these results **are** not very sensitive to curvature. This should be expected **from** the results **of** the cylinder.

Table 6.1 Mode 1 normalized stress intensity factors at the center of a semi-elliptical surface crack in **a** spherical shell, **a/h=.5,** *v=.3.*

 \bar{t}

Table 6.2 Mode 1 normalized stress intensit factors at the center of a semi-elliptical surface crack in a spherical shell, a/h=l, *v=.3.*

Table 6.3 Mode 1 normalized stress **intensity factors at** the **center of a** semi-elliptical surface crack in a spherical shell, $a/h=2$, $\nu=.3$.

Table 6.4 Mode 1 normalized stress intensity **factors at the center of a semi-elliptical surface.** crack in a spherical shell, a/h=4, *v=.3.*

Table 6.5 Mode **i** normalized stress intensity factors at the center of a semi-elliptical surface crack in a spherical shell, $a/h=10$, $\nu=.3$.

Table 6.6 Distribution **of** the *mode* **1 normalized** stress intensity factor along a semi-elli surface crack in **a** toroidal shell located at different positions, see Fig. 6.5, a/h=1, R/h=1 **R**_i/R-3, **L**₀/R-.4, μ -.

Table 6.7 **Mode** I normalized stress intensity factors **at** the **center** of a semi-elliptical surface **crack** in **a** toroidal shell. The **crack** is located at **position** A o_ Fig. 6.5, **a/h=.5,** R/h=lO, u=.3.

k.

Table 6.8 **Mode** 1 **normalized** stress intensity **factors at** the **center** of **a** semi-elliptical surface **crack** in a toroidal shell. The crack is located at position B of Fig. 6.5, a/h=.5, R/h=lO, *v=.3.*

Table 6.9 Mode 1 **normalized** stress intensity **factors at** the center of **a** semi-elliptical surface crack in a toroidal shell. The crack is located **at** position C of Fig. **6.5, a/h=.5,** R/h=lO, **u=.3.**

Table 6.10 Mode 1 normalized stress intensity factors **at** the center of a semi-elliptical surface crack in a toroidal shell. The crack is located at position D of Fig. 6.5, a/h=.5, R/h=10, **/_=-13.**

Table 6.11 **Mode** I **normalized** stress intensity **factors at** the center of **a** semi-elliptical surface crack in **a** toroidal shell. The crack is located **at** position **A** of Fig. 6.5, **a/h=1,** R/h=lO, *v=.3.*

Table 6.12 Mode 1 normalized stress intent factors **at** the center of a semi-elliptical surface crack in a toroidal shell. The crack is located **at** position **b** of rig. 0.5 , $a/\mu-1$, $R/\mu-10$, $\nu-3$.

Table 6.13 Mode] normalized stress intensity factors **at** the center of **a** semi-elliptical surface **crack** in **a** toroida] shell. The **crack** is located **at position C** of Fig. 6.5, $a/h=1$, $R/h=10$, $\nu=.3$.

Table 6.14 Mode 1 normalized stress intens factors at the center of a semi-elliptical surfa crack in **a** toroidal shell. The crack is located at position D of Fig. 6.5 , $a/h=1$, $R/h=10$, $\nu=3.1$

Table 6.15 Mode 1 normalized stress intensity factors at the center of **a** semi-elliptical surface crack in **a** toroidal shell. The crack is located **at** position A of Fig. 6.5, $a/h=2$, $R/h=10$, $\nu=.3$.

Table 6.16 Mode 1 normalized stress intens factors at the center of a semi-elliptical surfa crack in a toroidal shell. The crack is located at position B of Fig. 6.5, a/h=2, **R/h=lO,** v=.3.

Table 6.17 Mode 1 normalized stress intens factors at the center of a semi-elliptical surfa crack in **a** toroidal shell. **The crack** is **located at position C of Fig. 6.5, a/h=2, R/h=lO,** v=.3.

0155 -.009 **.0136 -.009**

3 **.862 .552 .222**

®* **.857 .539 .210

Klb 5 .860 .547 .217

Table 6.18 Mode 1 **normalized** stress intensity **factors** at the **center** of a semi-elliptical surface **crack** in a toroidal shell. The **crack** is located **at** position D of Fig. 6.5, **a/h=2,** R/h=lO, //=-.3.

Table 6.19 Mode **1** normalized stress intensity **factors at** the center **of a** semi-elliptical surface crack in **a** toroidal **shell.** The **crack** is located **at position** A of Fig. 6.5, $a/h=4$, $R/h=10$, $\nu=0.3$.

Table 6.20 Mode **1** normalized **stress** intensity **factors** at the center of a semi-elliptical surface crack in **a** toroidal shell. The crack is **located at** position B of Fig. 6.5, **a/h=4, R/h=lO,** _=.3.

Table **6.21** Mode 1 **normalized** stress intensity factors at the center of a semi-elliptical surfa crack **in** a toroidal **shell.** The crack is located **at** position **C of** Fig. 6.5, a/h=4, R/h=lO, *u=.3.*

Table 6.22 Mode 1 **normalized** stress intensity factors **at** the center **of** a semi-elliptical surface crack in a toroidal shell• The **crack** is located **at** position D of Fig. 6.5, $a/h=4$, $R/h=10$, $\nu=.3$.

Table 6.23 Mode 3 normalized stress intens factor at the center of a semi-elliptical surfa crack in **a** cylindrical shell subjected to in-plane shear, **a/h=.5,** *u=.3.*

IN-PLANE SHEAR

Table 6.24 Mode 2 normalized stress intens factor a t the center of a semi-elliptical surfactor $\,$ crack in a cylindrical shell subjected to outpiane shear, a/h=.5, ν =.3

OUT-OF-PLANE SHEAR

Table 6.25 Mode **3 normalized** stress intensity factor **at** the **center of a** semi-elliptical **surface** crack in **a** cylindrical shell subjected to twisting, $a/h = .5$, $\nu = .3$.

TWISTING

Table 6.26 Mode 3 normalized stress intensity factor **at** the center of a semi-elliptical surface crack in a cylindrical shell subjected to in-plane shear, $a/h=1.$, $\nu=.3$.

IN-PLANE **SHEAR**

Table 6.27 Mode 2 normalized stress intensity factor at the center of a semi-elliptical surface crack in **a** cylindrical shell subjected to out-ofplane shear, $a/h=1.$, $\nu=.3.$

OUT-OF-PLANE SHBAR

Table 6.28 Mode 3 normalized stress intens factor at the center of a semi-elliptical surfa crack in a cylindrical shell subjected to twisting, **a/h=l.,** *v=.3.*

TWISTING

Table 6.29 Mode 3 normalized stress intensit factor at the center of a semi-elliptical surfa crack in a cylindrical shell subjected to in-pl shear, $a/h=2.$, $\nu=.3.$

IN-PLANE **SRRA_**

2_17

Tab]e 6.30 **Mode** *2* normalized stress intensity **factor** at the center of a semi-elliptical surfa crack in a cylindrical shell subjected to outplane shear, a/h=2., *v=.3.*

OUT-OF-PLANE SHEAR

Table 6.31 **Mode 3** normalized stress intensity factor at the **center of** a semi-elliptical surface **crack** in a **cylindrical** shell subjected to twisting, $a/h=2.$, $\nu=.3.$

TWISTING

249

 $\ddot{}$

Table 6.32 Mode 3 normalized stress intensity factor at the center of a semi-elliptical surface crack in a cylindrical shell subjected to in-plane shear, $a/h=4.$, $\nu=.3.$

IN-PLANB SHEAR

Table 6.33 Mode 2 normalized stress intens factor at the center of a semi-elliptical surfa **crack in a cylindrical shell subjected to out-of-** \mathbf{plane} shear, $\mathbf{a}/\mathbf{h} = 4.$, $\nu = 0.$

OUT-OF-PLANB SImAR

Table 6.34 Mode 3 normalized stress intensit factor **at** the center of **a** semi-elliptical surface **crack,** in a **cylindrical** shell subjected to twisting, a/h=4., **U=.3.**

TrlSTING

Table 6.35 Mode **3** normalized stress intensity factor at the center of a semi-elliptical surfa crack in a toroidal shell subjected to in-pl **shear.** Crack is at position A of Fig. 6.5, R/h=1 */r=-.3.*

IN-PLANE SHEAR

" **253**

Table 6.36 Mode 2 normalized stress intens **factor at** the center of **a** semi-elliptical **surface** crack in **a** toroidal **shell subjected** to **out-ofplane shear. Crack** is **at position** A **of Fig.** 6.5, $R/h=10, \nu=.3$

OUT-OF-PLANE SHEAR

Table 6.37 Mode 3 **normalized stress** intensity factor at the center of a semi-elliptical surfa **crack** in a toroidal shell subjected to twist Crack is at position A of Fig. 6.5 , $R/h=10$, $\nu=.3$.

TWISTING

Table 6.38 Mode 3 normalized stress intensity factor **at** the center of **a** semi-elliptical surface crack in **a** toroidal shell subjected to in-plane shear. Crack is at **position B of** Fig. 6.5, R/h=lO, **v=.3.**

IN-PLANE **SWRAR**

Table 6.39 Mode 2 normalized stress intens **factor** at the center of a semi-elliptical surfa $crack$ in a toroidal shell subjected to out**plane** shear. **Crack** is **at** position B **of** Fig. **6.5,** R/h=10, ν =.3.

OUT-OF-PLANE SHEAR

Table 6.40 Mode 3 normalized stress like factor at the center of a semi-elliptical surface crack in **a** toroidal **shell subjected** to **twisting. Crack** is **at position B** of **Fig.** 6.5, R/h=lO, *v=.3.*

TWISTING

Table 6.41 Mode 3 normalized stress intensit **factor** at the center of **a** semi-elliptical surface **crack** in **a** toroidal shell subjected to in-plane shear. **Crack** is **at** position **C of** Fig. 6.5, R/h=lO, $\nu = .3$.

IN-PLANE SHEAR

Table 6.42 Mode 2 normalized stress intensity factor **at** the center **of a** semi-elliptical surface crack **in a** toroidal shell subjected to out-ofplane shear. Crack is **at** position C of Fig. 6.5, $R/h=10, \nu=.3.$

OUT-OF-PLANE SHEAR

Table 6.43 Mode **3 normalized** stress intensity **factor at** the **center** of **a** semi-elliptical surface **crack** in **a** toroidal shell subjected to twisting. Crack is at position C of Fig. 6.5 , $R/h=10$, $\nu=.3$.

TWISTING

Table 6.44 Mode 3 normalized stress **intensity** factor **at** the **center of** a **semi-elliptical** surface **crack in a** toroidal shell subjected to in-plane shear. **Crack is at position** D of Fig. 6.5, R/h=lO, $\nu = .3$.

IN-PLANE **SHEAR**

Table **6.45** Mode **2** normalized stress intensity **factor at** the **center** of **a** semi-elliptical surface **crack** in **a** toroidal shell subjected to out-ofplane shear. Crack is at position D of Fig. 6.5, $R/h=10$, $\nu=.3$.

OUT-OF-PLANB SHEAR

Table 6.46 Mode 3 normalized stress intensity **factor at** the **center** of **a** semi-elliptical surface **crack** in **a** toroidal shell subjected to twisting. Crack is at position D of Fig. 6.5, $R/h=10$, $\nu=.3$.

TWISTING

Figure 6.1 Comparison of the mode **1LSH** with **results from Ref. [34 for** the **normalized SIF** along an axial, internal, semi-elliptical surfa **crack** in **a pressurized cylinder. Crack surface** pressure is taken into account, $\nu = .3$.

Figure **6.2 Comparison** of the mode **1LSM with results from** Ref. [40] for **the** normalized SIF **along an axial,** internal, semi-elliptical surface **crack** in **a** pressurized **cylinder. Crack** surface pressure is not taken into account, $\nu = .3$.

Figure 6.3 Out-of-plane **displacement w(O+,y) as measured** from **y=O** in **the deformed position** for **a cylinder with a circumferential, external, semielliptical surface crack subjected to eith** membrane loading $(\sigma_m=\mathbb{R}_x/h)$ or bending $(\sigma_b=6\mathbb{R}/h^2)$, *y=-.3.*

Figure 6.4 Out-of-plane **displacement** w(O+,y) **as** measured **from** y=O in the **deformed position** for **a** cylinder with **a** circumferential, **internal, semielliptical surface crack** *subjected* to **either** membrane loading $(\sigma_m=\stackrel{\infty}{\mathbb{R}}/h)$ or bending $(\sigma_b=6\stackrel{\infty}{\mathbb{R}}/h^2)$, $\nu = .3$.

Figure 6.5 Geometry of the toroidal shell.

w

CHAPTER 7

Conclusions **and** Future **Work**

The severity of the underlying assumptions of the line-spring model are such that **verification** with three-dimensional solutions is necessary. Such comparisons, in this study **as** well **as** in others, show that the model is quite **accurate,** and therefore, its use in extensive parameter studies is justified. It was shown in **Chapter** 4 that **for** practical crack length to plate thickness ratios of about a/h=l, **a** plate theory that includes transverse shear deformation gives better results than the classical theory. The higher order plate theory does not seem to be necessary for **a/h** greater than about 2. **When** using the LSM with shallow shell theory it is more important to include transverse shear effects, because this theory is asymptotically correct for short cracks. The validity of the shallow shell theory for long cracks is not fully known, however, for surface cracks of practical dimensions it is expected to be **accurate. Comparison** of LSK solutions **obtained** in **this** study with three-dimensional solutions **for** semi-elliptical internal cracks in cylinders **are also** quite **accurate.**

It is still not understood why the model works **as** well **as** it does close to the crack ends. This is **a** rather **curious** problem. Since the stress intensity factors **are** defined by the model to be in **a** plane perpendicular to the plate surfaces, **and** not perpendicular to the crack front as *they* should be defined, the results **at** the ends of **a** semi-elliptical crack should be poor, but *they* **are** not. Several factors **apparently act** to cancel each other out. If *these* **factors are**

understood, and separately accounted for, **the extension of** the model to other **crack problems** will be better **achieved.**

This has special importance **in** the **proposed skew-sy_etric** or mixed-mode **line-spring** model investigated in this **study. Unfortunately,** there **are no** three-dlmensional **solutions for verification; only** the **success of** the **sy_etric case can give confidencethat** the **results** will be **of some use.** There **are additional assumptions involved that do not have** to be made **in** the mode **1 case. The first restricts** the **model** to **coplanar crack growth. The results may** be **considered as upper bounds for** materials **which have a weak cleavage plane.** Of **course, cracks along** these **planes would** be **of concern. The next assumption relates** to the **previously discussed problem in** mode **1** which **involves** the **crack front curvature and** the **plane** in **which** the **SIF is defined.** Although **in** the mode **1 case this problem** is **somehow overcome, this effect is** more **critical in** the **skew**syuetric **case** because **there are** two **stress intensity factors as opposed** to **one for** the sy_etric **case. To illustrate** this **problem, consider that** for **a semi-elliptical crack** in **which a primary** mode **3 loading** in the **center** will become **a primary mode** *2* **loading** towards the **ends, and vice versa. This is not observed** in the **results. There is no built in** mechanism **in** the model **that accounts for** this, **(but there** isn't for the mode 1 case either). Perhaps the combination of K_2 and **K3 in** the **following generalized energy release rate equation** is more **accurate** than the **individual K values.**

$$
\frac{d}{dL}(U-V) = G = \frac{1-\nu^2}{E} \left\{ K_1^2 + K_2^2 + \frac{1}{1-\nu} K_3^2 \right\} .
$$
 (7.1)

271

 $\ddot{}$

If the model can be **verified,** and improved, the shell with a crack at an **arbitrary** angle **with** respect to a principal line of curvature would be **an** important problem for **future** research.

Investigations into the endpoint behavior of the line-spring model **have led to** important conclusions about the **ability of** the model to predict stresses in **front** of **the** Wcrack **tip** m. **This also** has **applications** to the crack **interaction** problem, **and** to possible **uses** of the model to **study** crack propagation in the length direction, in **addition** to the depth direction. It **was found** that **only when** the **crack** profile behaves like

$$
\xi = \xi_0 (1 - t^2)^{1/4} \tag{7.2}
$$

near the endpoints, does the numerical procedure easily conver However, for **rectangular profiles,** convergence is **acceptable. For** the **semi-ellipse, it** is **not.**

An important **application** of the **LSM was** to **solve** the contact plate bending problem. **Here** the **flexibility** of the **model** to allow for **any** crack shape is exploited. **Future work** in this **area** includes predicting crack **shapes** for **mode** 1 crack growth **assuming a** constant K condition. Solution of **this** problem **would** involve the **same** iterative procedure that was used for the contact case.

It **should** be emphasized **that all** solutions **presented** in this **study** correspond to the perturbation **problem, where** constant loading along the length of the crack has been **assumed.** To make use of the results, the **solution** to the uncracked **shell** must **first** be obtained **along** the plane of the crack. Then **superposition** principles apply.

There may be cases where the **solution** to this **problem varies considerably along** the **crack** length, **and** studies into this **effect** may be necessary. **This** may be done **in a** straightforward manner.

The use of displacement quantities **as** unknowns in the **formulation** of the problem leads to **strongly** singular **integral equations, rather** than singular integral **equations which** result **from** using displ_cement derivatives. Although **it** is more **convenient** to deal directly **with** the displacement quantities, this **formulation** introduces log singularities **into** the **equations which** require more **asymptotic analysis** in order to have **acceptable** numerical **convergence. In** this study it **was** necessary to **evaluate** these **log** integrals in **closed form.** Sometimes log terms of the form $(t-y)^n$ ln|t-y| can be extracted from the Fredholm kernel **and calculated** inclosed form to slightly **improve convergence,** but in general it **is** not **worth** the **extra effort. The collocation** method of solving the integral **equations** was **found** to be better **and** more **convenient** than the quadrature technique. **It** has been my **experience** that orthogonal polynomials should be used as fitting functions when using the LSM **as** opposed to simpler **functions** such **as power** series.

273

t

 \bullet

LIST OF REFERENCES

- i . Benthem, J. **P.,** "The Quarter-Infinite **Crack** in a **Half** Space; Alternative **and** Additional Solutions", International Journal of Solids **and** Structures, Vol. 16, 1980, pp. 119-130.
- $2.$ Rice, J. R. **and** Levy, N., "The **Part-Through** Surface Crack **in an** Elastic Plate', ASME Journal of Applied Mechanics, Vol. **39,** 1972, pp. 185-194.
- 3. Rice, **J.** R., 'The **Line Spring** Model for **Surface Flaws", The** Surface Crack: **Physical Problems** and Computational Solutions, Swedlow, J. **L., ed.,** ASME **New** York, **1972,** pp. **171-186.**
- . **Williams,** M. L., 'On the Stress Distribution **at** the **Base** of **a** Stationary **Crack',** ASME Journal of Applied Mechanics, **Vol. 24,** 1957, **pp. 109-114.**
- *** Williams,** M. **L.,** 'The **Bending** Stress **Distribution at** the **Base of** a Stationary **Crack',** ASME Journal of Applied Mechanics, Vol. **28, 1961, pp. 78-82.**
- ***** Knowles, **J.** K. **and** Wang, **N.** M., 'On the **Bending of an** Elastic Plate **Containing a Crack',** Journal of Mathematics **and** Physics, **Vol. 39,** 1960, **pp. 223-236.**
- ***** Reissner, E., 'The Effect of **Transverse** Shear **Deformation** on the **Bending** of Elastic Plates", ASME Journal of Applied Mechanics, Vol. 12, 1945, **pp.** A69-A77.
- 8. Reissner, **E.,** ' On **Bending** of Elastic Plates', Quarterly of Applied Mathematics, **Vol. 5,** 1947-1948, pp. **55-68.**
- $9.$ **Hartranft,** R. J. **and** Sih, G. **C.,** "Effect of **Plate** Thickness **on** the Bending Stress Distribution Around Through **Cracks,** ' Journal of Mathematics **and** Physics, Vol. **47,** 1968, pp. **276-291.**
- 10. Wang, N. M., "Effects of Plate Thickness on the Bending of an **Elastic-** Plate- **Containing a Crack",** Journal of Mathematics **and** Physics, Voi._47, 1968, pp. **371-390.**
- 11. **Civelek,** M. **B. and** Erdogan, F., 'Elastic-Plastic Problem **for a** Plate with **a** Part-Through **Crack Under** Extension **and** Bending', International Journal of Fracture Mechanics, **Vol. 20,** 1982, pp. **33-46.**
- 12. **Hartranft,** R. J., 'Improved Approximate Theories **of** the **Bending and** Extension of Flat Plates", Plates **and** Shells With **Cracks",** Sih, G. **C., ed.,** Noordhoff International Publishing, Leyden, The Netherlands, 1977, pp. **45-83.**
- 13. Sih, G. C., "A review of the Three-Dimensional Stress Problem for
a Cracked Plate", International Journal of Fracture Mechanics, Vol. 7, 1971, pp. 39-61. a **Cracked** Plate" International Journal of Fracture **Mechanics,**
- Wang, N. M., "Twisting of an Elastic Plate Containing a Crack", 14. International Journal of Fracture Mechanics, Vol. 6, 1970, pp. 367-378.
- Delale, F. and Erdogan, F., "The Effect of Transverse Shear in a 15. **Applied Mechanics. Vol. 46, 1979. pp. 618-624**

Cracked Plate Under Skew-Symmetric Loading w, ASKE Journal of

- 16. Folias, E. S., "The Stresses in a Cracked Spherical Shell", Journal of Mathematics and Physics, Vol. 44, 1965, pp. 165-176.
- Folias, E. S., "A Finite Line Crack in a Pressurized Spherical 17. Shell^{*}, International Journal of Fracture Mechanics, Vol. 1, 1965, pp. 20-46.
- Folias, E. S., "An Axial Crack in a Pressurized Cylindrical 18. Shell", International Journal of Fracture Mechanics, Vol. 1, 1965, pp. 104-113.

Shell" **International Journal** of

- 19. Folias, E. S., "A Circumferential Crack in a Pressurized Cylindrical Shell", International Journal of Fracture Mechanics. **Fol. 3, 1967, pp. 1-11.**
- Sanders. J. L.. Mechanics, Vol. 49, 1982, pp. 103-221.
- $21.$ Sanders, J. L., Jr., "Circumferential Through-Cracks in a Cylindrical Shell Under Combined Bending and Tension", ASME Journal of Applied Mechanics, Vol. 50, 1983, pp. 221.

Cylindrical Shell **Under Combined** Bending **and** Tension w, ASME

With **Cracks** w, **International** Journal of Fracture Mechanics, Vol.

- $22.$ Erdogan, F. and Kibler, J. J., "Cylindrical and Spherical Shells With Cracks", International Journal of Fracture Mechanics, Vol.
5, 1969, pp. 229-237.
- $23.$ Copley, L. G. and Sanders, J. L. Jr., "Longitudinal Crack in a Cylindrical Shell Under Internal Pressure", International Journal
of Fracture Mechanics, Vol. 5, 1969, pp. 117-131.
- $24.$ Sih, G. C. and Hagendorf, H. C., "A New Theory of Spherical Shells With Cracks", Thin-Shell Structures: Theory, Experiment and Design, Fung, Y. C. and Sechler, E. E., eds., Prentice Hall, Shells With **Cracks** w, Thin-Shell Structures: Theory: Experiment
- $25.$ Sih, G. C. and Hagendorf, H. C., "On Cracks in Shells With Shear Noordhoff International Publishing, Leyden, The Netherlands Deformation", Plates and Shells With Cracks", Sih, **G.** C., ed.,
- 26. Naghdi, P. **M.,** "Note on the Equations of Shallow Elastic Shells", Quarterly of Applied **Mathematics,** Yol. 14, 1956, pp. 331-333.
- *27.* Krenk, S., 'Influence of Transverse Shear on **an Axial** Crack in a **Cylindrical** Shell', International Journal of Fracture **Mechanics, Vol.** 14, 1978, pp. 123-143.
- 28. Delale, F. and Erdogan, F., "Transverse Shea **Circumferentially** Cracked **Cylindrical Shell', Applied Mathematics,** Vol. 37, 1979, pp. 239-257. **Effect** in **a** Quarterly **of**
- 29. **Delale, F.** 'Cracked **Shells Under Skew-Synetric Loading', NASA Project Report, Lehigh University, NGR** 39-007-011, July 1981.
- 30. **Yahsi** , O. **S. and Erdogan, F . E.,** 'A **Cylindrical Shell** With an Arbitrarily Oriented **Crack', International** Journal of Solids **and** Structures, Vol. 19, 1983, **pp.955-972.**
- 31. **Barsoum, R. S., Loomis, R. W. and Stewart, B. D., 'Analysis** of **Through Cracks in Cylindrical Shells** by the quarter-Point **Elements",** International Journal **of Fracture** Mechanics, Vol. 15, 1979, pp. 259-280.
- 32. Ehlers, **R.,** 'Stress Intensity **Factors and Crack** Opening **Areas** For **Axial** Through **Cracks** in Hollow **Cylinders** Under Internal **Pressure** Loading', Engineering Fracture **Mechanics,** Vol. 25, 1986, **pp.** 63- 77.
- 33. **Newman,** J. **C.,** Jr. **and Raju, I. S.,** 'Analysis **of Surface Cracks** in **Finite Plates Under Tension or Bending Loads', NASA Technical Paper 1578, 1979.**
- 34. **Raju,** I. **S. and Newman,** J. **C.,** Jr., **'Stress-Intensity** Factors for **Internal and External** Surface **Cracks in Cylindrical Yessels",** Journal of Pressure **Vessel** Technology, **Vol.** 104, 1982, pp. 293- 298.
- 35. Shah, R. **C. and** Kobayashi, **A. S., 'On** the **Surface Flaw Problem'** , **The** Surface **Crack: Physical** Problems **and Computational** Solutions, Swedlow, J. L., ed., ASME New York, 1972, pp.79-124.
- 36. Smith, F. **W. and** Sorensen, **D.** R., 'The Semi-Elllptical Surface **Crack** - A Solution by the Alternating **Method',** International Journal of Fracture Mechanics, Vol. 12, 1976, pp. 47-57.
- 37. **Heliot,** J., Labbens, **R. C. and** Pellisier-Tanon, A., 'Semi **Elliptical Cracks** in **a Cylinder Subjected** to **Stress** Gradients', **Fracture** Mechanics, **ASTM,** STP 677, 1979, pp. 341-364.
- 38. **Nishioka, T. and** Atluri, S. N., 'Analysis of **Surface** Flaw in Pressure Vessels by **a New** 3-Dimensional **Alternating Method',**

Journal of Pressure Vessel Technology, Vo]. 104, 1982, **pp.** 299- **307.**

- **39.** Nishioka, T. and Atluri, S. N., "Analytical Solution for Embedded Elliptical **Cracks,** and Finite Element Alternating Method for Elliptical Surface **Cracks,** Subjected to Arbitrary Loadings', **Engineering** Fracture Mechanics, Vol. 17, 1982, pp. 247-268.
- 40. O'Donoghue, **P. E., Nishioka, T. and** Atluri, **S. N., 'Analysis** of **Interaction Behavior** of **Surface** Flaws in **Pressure Vessels",** Journal of **Pressure** Vessel Technology, Vol. **108,** 1986, pp. **24-32.**
- **41.** Mattheck, **C.,** Morawietz, **P.** and Munz, **V.,** 'Stress Intensity **Factor** at the **Surface** and at the **Deepest Point of** a **Semi-**Elliptical **Surface Crack** in Plates **Under** Stress **Gradients', International Journal** of **Fracture** Mechanics, **Vol. 23, 1983, pp. 201-212.**
- **42.** Grebner, **H. and Strathmeier, U.,** "Stress Intensity Factors for **Circumferential Semi-elliptical Surface Cracks in a Pipe Under Thermal Loading", Engineering Fracture** Mechanics, **Vol. 22, 1985, pp. 1-7.**
- **43. Isida,** M., Noguchi, **H. and Yoshida, T, "Tension and Bending** of Finite Thickness Plates With **a** Semi-Elliptical Surface Crack", International Journal of Fracture Mechanics, Vol. **26,** 1984, **pp.** 157-i88.
- **44.** Swedlow, J. **L., ed.,** The **Surface Crack: Physical Problems and Computational** Solutions, ASME New York, 1972.
- 45. **Newman,** J. **C.,** Jr., "A Review **and** Assessment **of** the Stress-Intensity Factors for Surface **Cracks",** NASA Technical Memorandum **78805, 1978.**
- **46.** Scott, **P.** M. **and Thorpe, T. W., "A Critical** Review of **Crack Tip** Stress Intensity Factors For Semi-elliptic Cracks", Fatigue of Engineering Materials **and** Structures, Vol. 4, 1981, **pp. 291-309.**
- **47.** Murakami, Y., 'Analysis of Stress Intensity **Factors** of Modes I,II and III for Inclined Surface Cracks of Arbitrary Shape", Engineering **Fracture** Mechanics, **Vol.** 22, **1985,** pp. 101-114.
- **48. Delale, F. and** Erdogan, F., "Line-Spring **Model for** Surface Cracks in **a** Reissner Plate", International Journal of Engineering Science, Vol. 19, 1981, **pp.** 1331-1340.
- 49. Nakamura, **H.,** Okamoto, A. **and** Kamichika, R., 'Analysis of Surface Cracks in Weld Pipe - An Application of Line Spring Model', Transactions of the 7th International Conference on SMIRT, Vol. G, F7/5, 1983.
- 50. Parks, D. M., "The Inelastic Line-Spring: Estimates of Elastic-Plastic Fracture Mechanics Parameters for Surface-Cracked Plates and Shells", Journal of Pressure *Vessel* Technology, Vol. 103, 1981, pp. 246-254.
- 51. Miyoshi, T., Shiratori, M. and Yoshida, Y., 'Analysis of J-Integral and Crack Growth for Surface Cracks by Line Spring Method', Journal of Pressure Vessel Technology, Yol. 108, 1986, pp. 305-311.
- **52.** Miyazaki, **N.** and **Kaneko, H.,** "On the **Combination of** the **Boundary** Element Method and the **Line-Spring** Model", International Journal of Fracture Mechanics, **Vol.** 31, 1986, pp. **R3-RIO.**
- 53. Yang, **C.** Y., "Line Spring Method of Stress Intensity **Factor** Determination **for** Surface Cracks in Plates Under Arbitrary In-Plane Stresses", Presented at ASTM 19th National Symposium on Fracture Mechanics, San Antonio, Texas, June **30-** July **2,** 1986.
- 54. Theocaris, P. S. and Wu, D. L., "A **Closed-Form** Solution to the Equivalent Through-Crack Model **for** Surface **Cracks",** Acta Mechanica, Vol. **58,** 1985, pp. 153-173.
- 55. Theocaris, **P.** S. **and** Wu, **D. L.,** "The Equivalent **Through-Crack** Model for the Surface Part-Through Crack["], Acta Mechanica, Vol. **59,** 1986, pp. 157-181.
- **56. Boduroglu,** H. **and** Erdogan, F., "Internal **and** Edge **Cracks** in **a** Plate of Finite Width Under Bending", ASME Journal of Applied Mechanics, Vol. **50,** 1983, pp. 621-629.
- 57. Erdogan, F. and Boduroglu, H., "Surface Cracks in a Plate of Finite Width **Under** Extension or Bending", Theoretical **and** Applied Fracture Mechanics, **Vol.** 2, 1984, pp. 197-216.
- 58. Erdogan, F. **and** Axsel, B., "Line-Spring Model **and** its Applications to Part-Through Crack Problems **in** Plates and Shells w, NASA Project Report, Lehigh University, **NGR 39-007-011,** June 1986.
- 59. Wu, **B.** H. **and** Erdogan, F., "The Surface Crack **Problem** in an Orthotropic Plate **Under** Bending and Tension", **NASA** Project Report, Lehigh **University,** NGR **39-007-011,** November 1986.
- 60. Delale, F. and Erdogan F., "Application of the Line-Spring Model to a Cylindrical Shell Containing **a** Circumferential or Axial Part-Through Crack", ASME Journal of Applied Mechanics, Vol. 49, 1982, pp. 97-102.
- 61. Gross, B. and Srawley, J. E., *"Stress* Intensity Factors for Single Edge Notch Specimens in Bending or Combined Bending and

Tension by **Boundary** Collocation **of** a Stress Function", NASA Technical Note D-2603, 1965.

- 62. Tada, n., **Paris,** P. C. **and** Irwin, G. R., The Stress Analysis **of Cracks** Handbook, Del Research **Corporation, Hellertown,** Pa., 1973.
- 63. Kaya, A. C. and Erdogan, F., "Stress Intensity Factors and COD in an Orthotropic **Strip", International** Journal **of** Fracture Mechanics, **Vol. 16, 1980, pp.** 171-190.
- 64. **Kaya, A. C. and** Erdogan, **F.,** 'On the Solution **of** Integral Equations with Strongly Singular Kernels,["] (to appear in the quarterly of Applied Mathematics).
- **65.** Benthem, J. **P. and Koiter,** W. **T.,** 'Asymptotic **Approximations** to **Crack Problems',** Methods **of** Analysis **and Solutions** of **Crack Problems, Sih,** C. **C., ed.,** Noordhoff **International Publishing, Leyden, The Netherlands, 1973.**
- 66. **Hadamard,** J., 'Lectures **on Cauchy's Problem** in **Linear Partial** Differential Equations", **Yale University Press, 1923.**
- **67. Kaya, A. C.,** 'Applications of Integral Equations with **Strong Singularities in Fracture** Mechanics', **Ph.D. Dissertation, Lehigh University, 1984.**
- **68. Irwin, G R.,** 'Analysis of **Stresses and Strains** Near the End of **a Crack Traversing a Plate',** ASME **Journal of** Applied Mechanics, **Vol. 24, 1957,** pp. **361-364.**
- 69. Irwin, G. R., "Fracture Mechanics', **Structural** Mechanics, Goodier, J. N. and Hoff, N. J., eds., Pergamon Press, New York, 1960, pp. **557-591.**
- 70. Erdogan, **F.,** "Stress **Intensity** Factors", ASME Journal of **Applied** Mechanics, Vol. **50,** 1983, **pp. 992-1002.**
- 71. Ezzat, **H. A.,** "Experimental **Verification** of the Simplified **Line- .S_ring** Model", International Journal of Fracture Mechanics, **Vol. 28,** 1985, pp. 139-150.
- 72. **Sih,** G. **C.,** Handbook of Stress Intensity Factors, **Institute** of Fracture **and** Solid Mechanics, Lehigh **University,** 1973, sec. **1.2.1-5,7.**
- 73. Erdogan, **F. and** Ratwani, M., 'k **Note** on the **Interference** of **Two Collinear Cracks in a Cylindrical Shell', International Journal** of **Fracture** Mechanics, Vol. **10, 1974, pp. 483-465.**
- 74. **Delale, F. and** Erdogan **F.,** "Stress **Intensity** Factors in **a** Hollow **Cylinder** Containing A Radial **Crack",** International Journal of Fracture Mechanics, Vol. **20,** 1982, **pp. 251-265.**
- 75. Nied, H. F. and Erdogan, F., "The Elasticity Problem for a Thick-Walled Cylinder Containing **a** Circumferential **Crack",** International Journal of Fracture Mechanics, Vol. 22, 1983, pp. 277-301.
- 76. Erdogan, F., "Approximate Solutions of Systems of Singular Integral Equations", Journal of Applied Mathematics, Yol. 17, 1969, pp. 1041-1059.
- 77. Erdogan, **F.,** 'Mixed **Boundary-Value Problems** in Mechanics", Mechanics Today, **Nemat-Nasser,** S., ed., **Yol.** 4, **Pergamon** Press, Oxford, **1978, pp.l-86.**
- 78. Muskhelishvili, I. N., Singular Integral Equations, Noordho International **Publishing, Leyden,** The Netherlands, 1953.
- 79. Kaya, A. **C., "On** the Solution **of** Integral Equations with **a** Generalized **Cauchy** Kernel", (to **appear** in the Quarterly of Applied Mathematics).
- **80.** Sih, O. **C.,** "Stress Distribution **Near** Internal **Crack** Tips **for** Longitudinal Shear Problems", ASME Journal of Applied Mechani **Yol.** 32, 1965, **pp.** 51-58.
- **81.** Sneddon, I. **N.,** "The Distribution of Stress in the **Neighborhood of a Crack** in **an Elastic** Solid", **Proceedings of the** Royal Society **of London, Series** A, **187, 1946, pp.** 229-260.
- **82.** Kassir, M. K. **and** Sih, G. **C.,** "Three-Dimensional Stress **Distribution** Around **an** Elliptical **Crack** Under Arbitrary Loadings", ASME Journal of Applied Mechanics, Vol. **33,** 1966, pp. 601-611.
- **83.** _artranft, R. **J. and** Sih, G. **C.,** "Stress Singularity **for a Crack With an** Arbitrarily **Curved** Front", Engineering Fracture Mechanics, Vol. 9, 1977, pp. 705-719.
- **84. Timoshenko, S. and** Woinowsky-Krieger, S., **Theory** of **Plates** and Shells, Mcgraw-Hill Boek Company, New York, 1959, pp. 165-171.
- **85. Ben,hem,** J. **P.,** "State *-of* Stress **at** the **Vertex** of **a** Quarter-Infinite **Crack** in **a** *Half-Space",* Vol. 13, 1977, pp. 479-492.
- **86.** Abramowitz, M. **and** Stegun, I. A., Handbook **of** Mathematical Functions, Dover Publications, 1965.
- **87.** Gradshteyn, I. S. and Ryzhik, I. M., Table of Integrals, Series, and Products, Academic Press, 1965.

APPENDIX A

Non-Dimensional Variables and Useful Formulae

A.1 Non-Dimensional Plate and Shell Quantities
\nx = x₁/h , y = x₂/h , z = x₃/h , (A.1)
\nu = u_x = u₁ = u₁D/h ,
$$
\beta_x = u_2 = \beta_1
$$
, w = u_z = u₃ = u₃D/h
\nv = u_y = u₄ = u₂D/h , $\beta_y = u_5 = \beta_2$, (A.2)
\n $\sigma_i = \sigma_{iD}/E$, $q = \overline{q}/E$, (A.3)
\n $N_{xx} = N_{11}/(hE)$, $N_{yy} = N_{22}/(hE)$, $N_{xy} = N_{12}/(hE)$,
\n $M_{xx} = M_{11}/(h^2E)$, $M_{xy} = M_{12}/(h^2E)$, $M_{yy} = M_{22}/(h^2E)$,
\n $V_x = 12(1+\nu)V_1/(5hE)$, $V_y = 12(1+\nu)V_2/(5hE)$, (A.4)
\n $\lambda^4 = \gamma^{-1} = 12(1-\nu^2)$, $\kappa = \frac{1}{5(1-\nu)}$,
\n $\lambda_1^4 = \lambda^4(h/R_1)^2$, $\lambda_2^4 = \lambda^4(h/R_2)^2$, $\lambda_{12}^4 = \lambda^4(h/R_{12})^2$. (A.5)

A.2 Some Useful Properties of Modified Bessel Functions

$$
K_1(z) = \frac{z}{2} \left[K_2(z) - K_0(z) \right],
$$
 (A.6)

$$
\frac{d}{dz} K_0(z) = -K_1(z) = \frac{-z}{2} \left[K_2(z) - K_0(z) \right],
$$
 (A.7)

$$
\frac{d}{dz} K_2(z) = -K_1(z) - \frac{2}{z} K_2(z) = -\frac{z}{2} \left[K_2(z) - K_0(z) \right] - \frac{2}{z} K_2(z) . \quad (A.8)
$$

If
$$
z = \beta |t-y|
$$
,
\n
$$
\frac{d}{dt} = \frac{dz}{dt} \frac{d}{dz} = \beta sign(t-y) \frac{d}{dz}.
$$
\n(A.9)

For small **z,**

$$
K_0(z) \sim -\ln(z/2) - \gamma_e - (z/2)^2 \ln(z/2) + 0(z^2)
$$
, (A.10)

$$
K_2(z) \sim 2/z^2 - 1/2 - 1/2(z/2)^2 \ln(z/2) - 1/2(z/2)^2 (\gamma_e + 5/4)
$$

- 1/6(z/2)⁴ ln(z/2) + 0(z⁴) , (A.11)

where Euler's constant, γ_e = $.57721566490153...$

A.3 **Chebychev Polynomials**

0f the first kind:
$$
T_n(x) = \cosh \theta, \theta = \cos^{-1}x
$$
, (A.12)

0f the second kind:
$$
U_n(x) = \frac{\sin(n+1)\theta}{\sin\theta}
$$
, $\theta = \cos^{-1}x$. (A.13)

Some **expressions needed** to **integrate**

$$
\int_{-1}^{+1} (r-s)^{i} U_{j}(r) \sqrt{1-r^{2}} \ln |r-s| dr , i=1,2,3 , \qquad (A.14)
$$

are,

$$
rU_{j}(r) = \frac{1}{2} \left[U_{j+1}(r) + U_{j-1}(r) \right],
$$

\n
$$
r^{2}U_{j}(r) = \frac{1}{4} \left[U_{j+2}(r) + 2U_{j}(r) + U_{j-2}(r) \right],
$$

\n
$$
r^{3}U_{j}(r) = \frac{1}{8} \left[U_{j+3}(r) + 3U_{j+1}(r) + 3U_{j-1}(r) + U_{j-3}(r) \right].
$$
 (A.15)

second kinds **when** using the **line-spring** model with **displacement** derivatives **as** the unknowns **is,** important **relation** between Chebychev Polynomials **of** the first **and**

$$
\int \frac{T_n(x) dx}{(1-x^2)^{1/2}} = \frac{1}{n} (1-x^2)^{1/2} U_{n-1}(x) + \text{constant} . \qquad (A.16)
$$

The **following** integrals **are** useful for **calculating** stresses **ahead** of the **crack** tip,

$$
\int_{-1}^{+1} \frac{U_n(t) (1-t^2)^{1/2}}{x-t} dt = -[x-(x^2-1)^{1/2}]^{n+1}, |x| > 1 , \qquad (A.17)
$$

$$
\int_{-1}^{+1} \frac{T_n(t)}{(1-t^2)^{1/2}(t-x)} dt = -\frac{\left[x-(x^2-1)^{1/2}\right]^{n}}{(x^2-1)^{1/2}} , \quad |x| > 1 , \qquad (A.18)
$$

$$
\int_{-1}^{+1} \frac{U_n(t) (1-t^2)^{1/2}}{(x-t)^2} dt = -(n+1) \Big[x - (x^2-1)^{1/2} \Big]^n \Big[1 - \frac{x}{(x^2-1)^{1/2}} \Big],
$$

 $|x| > 1$ (A.19)

A.4 Finite-Part, Cauchy Principal Value, and Log Integrals Except for the log integrals, these expressions are copied from [67].

$$
\int_{-1}^{+1} \frac{(1-t)^{\alpha}(1+t)^{\beta} P_n^{(\alpha,\beta)}(t)}{t-x} dt = \pi \cot(\alpha \pi) (1-x)^{\alpha}(1+x)^{\beta} P_n^{(\alpha,\beta)}(x) -
$$

$$
-\frac{2^{a+\beta}\Gamma(a)\Gamma(n+\beta+1)}{\Gamma(n+a+\beta+1)} F(n+1,-n-a-\beta; 1-a, \frac{1-x}{2}),
$$

(a > -1, β > -1, a \ne 0,1,2...), (A.20)

$$
\int_{-1}^{+1} \frac{P_n(t)}{t-x} dt = -2Q_n(x) , \qquad (A.21)
$$

$$
\int_{-1}^{+1} \frac{T_n(t)}{(1-t^2)^{1/2}(t-x)} dt = \pi U_{n-1}(x) , \qquad (A.22)
$$

$$
\int_{-1}^{+1} \frac{U_{n}(t) (1-t^{2})^{1/2}}{t-x} dt = -\pi T_{n+1}(x) , \qquad (A.23)
$$

$$
\int_{-1}^{+1} \frac{P_n(t)}{(t-x)^2} dt = \frac{-2(n+1)}{1-x^2} \left[x Q_n(x) - Q_{n+1}(x) \right], \qquad (A.24)
$$

283

 $c - 4$

$$
\int_{-1}^{+1} \frac{T_n(t)}{(1-t^2)^{1/2}(t-x)^2} dt = \frac{\pi}{1-x^2} \left[\frac{-n+1}{2} U_n(x) + \frac{n+1}{2} U_{n-2}(x) \right],
$$
\n(A.25)

$$
\int_{-1}^{+1} \frac{U_n(t) (1-t^2)^{1/2}}{(t-x)^2} dt = -\pi(n+1)U_n(x) \quad , \tag{A.26}
$$

where $P_n^{(u,p)}(t)$ are Jacobi Polynomials, $F(a,b;c;z)$ are Hypergeometric functions, $P_n(t)$ are Lagendre Polynomials, $Q_n(t)$ are Lagendre Polynomials of the second kind, and $\Gamma(a)$ is the gamma function.

Some **integrals that can** be **used with Eqn. B.27 are:**

$$
\int_{-1}^{+1} \frac{1}{t-x} dt = \ln \left[\frac{1-x}{1+x} \right], \qquad (A.27)
$$

$$
\int_{-1}^{+1} \frac{1}{(t-x)^2} dt = \frac{-1}{1-x} - \frac{1}{1+x} , \qquad (A.28)
$$

$$
\int_{-1}^{+1} \frac{1}{(1-t^2)^{1/2}(t-x)} dt = 0 \quad , \tag{A.29}
$$

$$
\int_{-1}^{+1} \frac{1}{(1-t^2)^{1/2}(t-x)^2} dt = 0 \quad , \tag{A.30}
$$

$$
\int_{-1}^{+1} \frac{(1-t^2)^{1/2}}{t-x} dt = -\pi x \quad , \tag{A.31}
$$

$$
\int_{-1}^{+1} \frac{(1-t^2)^{1/2}}{(t-x)^2} dt = -\pi \quad , \tag{A.32}
$$

$$
\int_{-1}^{+1} \frac{(1-t)^{1/2}}{t-x} dt = -2\sqrt{2} \left[1 - \frac{1}{2} \sqrt{\frac{1-x}{2}} \ln(B) \right], \qquad (A.33)
$$

$$
\int_{-1}^{+1} \frac{(1-t)^{1/2}}{(t-x)^{2}} dt = -\sqrt{2} \left[\frac{1}{1+x} + \frac{1}{4} \sqrt{\frac{2}{1-x}} \ln(B) \right], \qquad (A.34)
$$

$$
\int_{-1}^{+1} \frac{1}{(1-t)^{1/2}(t-x)} dt = \frac{\ln(B)}{\sqrt{1-x}} , \qquad (A.35)
$$

$$
\int_{-1}^{+1} \frac{1}{(1-t)^{1/2} (t-x)^{2}} dt = \frac{\sqrt{2}}{1-x} \left[\frac{-1}{1+x} + \frac{1}{4} \sqrt{\frac{2}{1-x}} \ln(B) \right], \qquad (A.36)
$$

 $where$

$$
B = \frac{1 + \sqrt{\frac{1 - x}{2}}}{1 - \sqrt{\frac{1 - x}{2}}}
$$
 (A.37)

There are **similar** formulas for **power** series.

$$
\frac{1}{\pi} \int_{-1}^{+1} t^{j-1} (1-t^2)^{1/2} \ln|t-y| dt = \sum_{k=1}^{j+2} a_k y^{k-1} , \qquad (A.38)
$$

$$
\frac{1}{\pi} \int_{-1}^{+1} \frac{t^{j-1} (1-t^2)^{1/2}}{t-y} dt = \sum_{k=1}^{j+1} b_k y^{k-1} , \qquad (A.39)
$$

$$
\frac{1}{\pi} \int_{-1}^{+1} \frac{t^{j-1} (1-t^2)^{1/2}}{(t-y)^2} dt = \sum_{k=1}^{j} c_k y^{k-1} , \qquad (A.40)
$$

where

$$
b_k = \frac{1}{2\sqrt{\pi}} \frac{\Gamma\left(\frac{j-k}{2}\right)}{\Gamma\left(\frac{j-k+3}{2}\right)}, \quad k = 1, 2, \ldots, j+1, \text{ for } j = 1, 2, 3, \ldots ,
$$

$$
b_k = 0 \quad , \quad j-k \text{ even} \quad , \tag{A.41}
$$

$$
c_k = kb_{k+1}
$$
, $k = 1, 2, 3, ..., j$, (A.42)

$$
a_k = \frac{-b_{k-1}}{k-1} , k = 2,3,4,...,j+2 ,
$$

$$
a_1 = 0 , j = 2,4,6,... ,
$$

$$
a_1 = \frac{(j-2)!}{2^{j-1} \left(\frac{j-3}{2}\right)! \left(\frac{j+1}{2}\right)!} \left\{ \sum_{k=1}^{j-1} \frac{(-1)^{k-1}}{k} - \frac{1}{j+1} - \ln(2) \right\} \qquad j = 3, 5, 7, ...
$$

$$
a_1 = -(1/4 + 1/2 \ln(2)) , \quad j = 1 .
$$
 (A.43)

And for the weight in the **denominator,**

$$
\int_{-1}^{+1} \frac{t^{n}}{(1-t^{2})^{1/2}(t-x)} dt = \sum_{k=0}^{n-1} d_{k}x^{k} ,
$$
\n(A.44)\n
$$
d_{k} = 0 , n-k \text{ even},
$$

$$
d_k = \sqrt{\pi} \frac{\Gamma\left(\frac{n-k}{2}\right)}{\Gamma\left(\frac{n-k+1}{2}\right)} \quad , \quad n-k \text{ odd} \quad , \tag{A.45}
$$

$$
\frac{1}{\pi} \int_{-1}^{+1} \frac{t^n}{(1-t^2)^{1/2} (t-x)^2} dt = \sum_{k=0}^{n-2} e_k x^k , \qquad (A.46)
$$

$$
e_k = 0 \quad , \quad n-k \text{ odd} \quad ,
$$

$$
e_k = \sqrt{\pi} \frac{\Gamma\left(\frac{n-k-1}{2}\right)}{\Gamma\left(\frac{n-k}{2}\right)} \quad (k+1) \quad , \quad n-k \text{ even} \quad . \tag{A.47}
$$

For integration **of** logs **with Chebychev Polynomials [76] (with corrections) of** the second **kind** that **are** typical **when using** the strongly singular formulation,

$$
\int_{-1}^{1} U_j(r) \sqrt{1-r^2} \ln|r-s| dr = V_j(s) , -1 \leq s \leq 1 , \qquad (A.48)
$$

where

$$
V_{j}(s) = \frac{-\pi}{2} \left[\frac{T_{j}(s)}{j} - \frac{T_{J+2}(s)}{j+2} \right], \quad j > 0
$$

= $\frac{-\pi}{2} \left[-s^{2} + 1/2 + \ln 2 \right], \quad j = 0$ (A.49)

286

 \iff

APPENDIX **B**

Finite-part Integrals

Singular integral **equations result naturally from** the **formulation** of **two-dimensional crack problems in mechanics when** the **crack opening displacement derivative** is **used as** the **unknown. The theory** is **well established due principally** to **the** work of Muskhelishvili **[78]. If** the **displacement** is **used as** the **unknown,** the **resulting singular** integral **equation takes on a new form and is referred** to **as strongly singular.** To illustrate the differences **consider** the two-dimensional, **half-space** crack **problem of Fig. B.1** with **boundary** conditions given by Eqns. B.1-4' **This simple** geometry **produces all of** the important mathematical **features** of the geometries **studied** in this **dissertation.**

 $\sigma_{xy}(0, y) = 0$ (B.1)

$$
\sigma_{xx}(0, y) = 0 \qquad (B.2)
$$

a.. is bounded **at** infinity. ij (B.3)

$$
v(x,y) = v(y) = 0, x \le a, x \ge b
$$

$$
\sigma_v(x,0) = -p(x), a\langle x\langle b. (B.4)
$$

The **resulting** integral **equation** is

$$
\int_{\mathbf{a}}^{\mathbf{b}} \frac{\phi(\mathbf{t})}{\mathbf{t} - \mathbf{x}} d\mathbf{t} + \int_{\mathbf{a}}^{\mathbf{b}} \phi(\mathbf{t}) K(\mathbf{x}, \mathbf{t}) d\mathbf{t} = -\frac{\pi(1+\kappa)}{2\mu} p(\mathbf{x}), \quad \mathbf{a} \langle \mathbf{x} \langle \mathbf{b} \rangle, \tag{B.5}
$$

where the **non-singular** Fredholm **kernel,**

$$
K(x,t) = \frac{-1}{t+x} + \frac{6x}{(t+x)^2} - \frac{4x^2}{(t+x)^3},
$$
 (B.6)

and $\phi(t)$ is the unknown derivative of the crack opening displacement $v(t)$, μ is the shear modulus of the material, and κ is defined in terms of Poisson's ratio y **for** both

plane stress:
$$
\kappa = \frac{3-\nu}{1+\nu}
$$
,

and for plane strain: $\kappa = 3-4\nu$. (B.7)

The **first** integral in Eqn. **B.5** is singular and is interpreted in the Cauchy **principal** value sense, specified as such by a line through the **integral sign.** One way to **define** a Cauchy **principal value integral** is as **follows,**

$$
\oint_{\mathbf{t}-\mathbf{x}}^{\mathbf{b}} \frac{\phi(\mathbf{t})}{\mathbf{t}-\mathbf{x}} d\mathbf{t} = \lim_{\epsilon \to 0} \left\{ \int_{\mathbf{t}-\mathbf{x}}^{\mathbf{b}} \frac{\phi(\mathbf{t})}{\mathbf{t}-\mathbf{x}} d\mathbf{t} + \int_{\mathbf{t}-\mathbf{x}}^{\mathbf{b}} \frac{\phi(\mathbf{t})}{\mathbf{t}-\mathbf{x}} d\mathbf{t} \right\}.
$$
\n(B.8)

By using the **standard** interpretation **of** an integral **as** the **area** under **a curve,** note that individually the **integrals** on the right hand side of Eqn. **B.8** do not **exist** in the **limit,** but **when added** together the ainfinite **areas** w **will** be of opposite signand **will cancel** giving **a finite** result. When the problem in Fig. B.1 is **formulated** by using the displacement $v(t)$ as the unknown instead of the derivative $\phi(t)$, the resulting integral **equation** is **found** to be,

$$
\frac{b}{\frac{1}{2}} \frac{v(t)}{(t-x)^2} dt + \int_{a}^{b} v(t) \left[\frac{-\frac{\partial K(t,x)}{\partial t}}{\frac{\partial K(t,x)}{\partial t}} \right] dt = - \frac{\pi(1+\kappa)}{2\mu} p(x) ,
$$
\n
$$
a \langle x \langle b, \rangle
$$
\n(B.9)

where the first integral no **longer exists** in the **Cauchy principal value sense and** requires **a special** interpretation. **Throughout** the dissertation **these integrals are** identified by **a** double dash **through** the integral **sign.**

Consider a direct integration by **parts** of the integrals in Eqn. **B.a.**

$$
\int_{a}^{b} \phi(t)K(x,t) dt = v(t)K(x,t) \Big|_{a}^{b} - \int_{a}^{b} v(t) \Big[\frac{\partial K(t,x)}{\partial t} \Big] dt , \qquad (B.10)
$$

$$
\int_{\mathbf{a}}^{\mathbf{b}} \frac{\phi(\mathbf{t})}{\mathbf{t} - \mathbf{x}} d\mathbf{t} \neq \left. \frac{\mathbf{v}(\mathbf{t})}{\mathbf{t} - \mathbf{x}} \right|_{\mathbf{a}}^{\mathbf{b}} + \int_{\mathbf{a}}^{\mathbf{b}} \frac{\mathbf{v}(\mathbf{t})}{(\mathbf{t} - \mathbf{x})^2} d\mathbf{t} .
$$
 (B.11)

Here again 'the same "strongly singular" integral appears. For Eqn. **B.11** to be an equality, this integral must be **finite just as** it **must** be in Eqn. **B.9,** so **we write,**

$$
\int_{a}^{b} \frac{\phi(t)}{t-x} dt = \frac{v(t)}{t-x} \Big|_{a}^{b} + \int_{a}^{b} \frac{v(t)}{(t-x)^{2}} dt
$$
 (B.12)

Note that Eqn. **B.9** is obtained if Bqns. **B.IO,12 are substituted into** Eqn. **B.5. The** integrated **terms cancel** for **either an** internal **crack** (O<a<b) **where**

$$
v(a) = v(b) = 0 , \t\t (B.13)
$$

or for **an edge crack CO=a,** O<b) **where**

$$
v(0) \left[\frac{1}{-x} + K(x,0) \right] = 0 , v(b)=0 . \qquad (B.14)
$$

The **fact** that **a** special interpretation **of** the strongly **singular** integral in Eqns. **B.9,12** is necessary **apparently reveals** that **a** "mistake" **has** been made in the **derivation** of **each equation. This** mistake **in** Eqn. **B.11** is **corrected** when Eqn. **B.8** is used when integrating by parts **as follows,**

$$
\int_{a}^{b} \frac{\phi(t)}{t-x} dt = \lim_{\epsilon \to 0} \left\{ \left[\frac{v(t)}{t-x} \Big|_{a}^{x-\epsilon} + \int_{a}^{x-\epsilon} \frac{v(t)}{(t-x)^2} dt \right] \right\}
$$
\n
$$
+ \left[\frac{v(t)}{t-x} \Big|_{x+\epsilon}^{b} + \int_{x+\epsilon}^{b} \frac{v(t)}{(t-x)^2} dt \right] \right\},
$$
\n
$$
= \lim_{\epsilon \to 0} \left\{ \frac{v(t)}{t-x} \Big|_{a}^{b} + \left[\frac{v(x-\epsilon)}{-\epsilon} + \int_{a}^{x-\epsilon} \frac{v(t)}{(t-x)^2} dt \right] \right\}
$$
\n
$$
+ \left[\frac{-v(x+\epsilon)}{\epsilon} + \int_{x+\epsilon}^{b} \frac{v(t)}{(t-x)^2} dt \right] \right\}.
$$
\n(B.15)

From Eqns. B.12 and B.15 we obtain **a result similar** to **gqn. B.8** but for strongly singular **integrals:**

$$
\frac{1}{f} \frac{v(t)}{(t-x)^2} dt = \lim_{\epsilon \to 0} \left\{ \left[\frac{v(x-\epsilon)}{-\epsilon} + \int_{a}^{x-\epsilon} \frac{v(t)}{(t-x)^2} dt \right] \right\}
$$

$$
+ \left[\frac{-v(x+\epsilon)}{\epsilon} + \int_{x+\epsilon}^{b} \frac{v(t)}{(t-x)^2} dt \right] \right\}. \tag{B.16}
$$

With this **definition Eqns. B.9,12 are correct. Consider for** example $v(t)=1$.

$$
\frac{1}{\epsilon} \frac{1}{(t-x)^2} dt = \lim_{\epsilon \to 0} \left\{ \left[\frac{-1}{\epsilon} + \frac{-1}{t-x} \right]_2^{x-\epsilon} \right\} + \left[\frac{-1}{\epsilon} + \frac{-1}{t-x} \right]_X + \epsilon \right\}, \qquad (B.17)
$$

$$
= \lim_{\epsilon \to 0} \left\{ \left[\frac{-1}{\epsilon} + \frac{1}{\epsilon} + \frac{1}{a-x} \right] + \left[\frac{-1}{\epsilon} - \frac{1}{b-x} + \frac{1}{\epsilon} \right] \right\}, \quad (B.18)
$$

$$
= \frac{1}{a-x} - \frac{1}{b-x} \ . \tag{B.19}
$$

Note that this would be the result obtained if Eqn. B.17 is integrated directly as though the **singularity were** not **present.**

Integrals of **this** type **were** studied by Hadmmard **in** 1923 [66] and were referred to as finite-part integrals, a name which describes Eqn. B.16 **where** the infinite part **is** subtracted out. For more information on finite-part **integrals and** their use for **problems** of the type studied in this dissertation see **Kaya [67].**

To derive **a property** that is more useful than **eqn** B.16 for **evaluating** finite-psxt integrals, differentiate **Eqn.** B.8 **with** respect to **x** as **follows.**

$$
\frac{\partial}{\partial x}\int_{\mathbf{a}}^{\mathbf{b}}\frac{v(t)}{t-x} dt = \frac{\partial}{\partial x}\lim_{\epsilon \to 0} \left\{ \int_{\mathbf{t}-x}^{x(\epsilon)} \frac{v(t)}{t-x} dt + \int_{\mathbf{t}-x}^{x(\epsilon)} \frac{v(t)}{t-x} dt \right\}.
$$
 (B.20)

Next differentiate on the **right** before the limit is **taken and before** integration,

$$
\frac{\partial}{\partial x} \int_{\xi-x}^{b} \frac{v(t)}{t-x} dt = \lim_{\epsilon \to 0} \left\{ \left[\frac{v(x-\epsilon)}{-\epsilon} + \int_{a}^{x-\epsilon} \frac{v(t)}{(t-x)^2} dt \right] \right\} + \left[\frac{-v(x+\epsilon)}{\epsilon} + \int_{x+\epsilon}^{b} \frac{v(t)}{(t-x)^2} dt \right] \right\}.
$$
\n(B.21)

From Eqn. B.16 **we** conclude,

$$
\frac{b}{f} \frac{v(t)}{(t-x)^2} dt = \frac{\partial}{\partial x} \int_{a}^{b} \frac{v(t)}{t-x} dt
$$
 (B.22)

By **expanding v(t)** near the **point** t=x, **another** method for the **evaluation** of finite-part integrals is obtained,

$$
\frac{b}{a} \frac{v(t)}{(t-x)^2} dt = \frac{b}{a} \frac{v(t) - (v(x) + (t-x)v'(x)) + (v(x) + (t-x)v'(x))}{(t-x)^2} dt
$$
\n
$$
= \int_{a}^{b} \frac{v(t) - v(x) - (t-x)v'(x)}{(t-x)^2} dt + v(x) \int_{a}^{b} \frac{1}{(t-x)^2} dt
$$
\n
$$
+ v'(x) \int_{a}^{b} \frac{1}{t-x} dt
$$
\n(B.24)

where

$$
v'(x) = \frac{dv}{dx} \tag{B.25}
$$

If

$$
\mathbf{v}(t) = \mathbf{f}(t)\mathbf{w}(t) \quad , \tag{B.26}
$$

$$
\int_{a}^{b} \frac{f(t)w(t)}{(t-x)^{2}} dt = \int_{a}^{b} \frac{f(t)-f(x)-(t-x)f'(x)}{(t-x)^{2}}w(t)dt + f(x)\int_{a}^{b} \frac{w(t)}{(t-x)^{2}} dt + f'(x)\int_{a}^{b} \frac{w(t)}{t-x} dt
$$
 (B.27)

See Appendix A **for finite-part and Cauchy principal value** integrals **with various** weight functions **and with** some **commonly used** forms **of f(t).**

APPENDII **C**

The Compliance Functions

As indicated **in chapter** two, the mixed-mode **line-spring** model **requires stress intensity** factor **solutions of** the **edge cracked strip** for **each of** the five losdings **shown in** Fig. **2.3. Three separate** two**dimensional problems** must be **solved** to **obtain** these **results. The** tension and bending **solutions come** from **symmetric (mode 1) loading, out-of,plane shear results come** from **skew-symmetric (mode 2) lolling,** and the anti-plane (mode 3) results are obtained from twisting and from **in-plane shear loading. Note** that **in-plane** for a **plate corresponds** to **out-of-plane** for **plane** strain and **vice versa.**

C.1Coverning equations for in-plane **loading.**

°

The governing **equations for** the **mode 1 and 2 cases are from plane elasticity where** all **field quantities are independent of s. Equilibrium of** the **solid requires,**

$$
\frac{\partial \sigma_{xx}}{\partial x} + \frac{\partial \tau_{xy}}{\partial y} = 0 \t{,} \t(0.1)
$$

$$
\frac{\partial \tau_{xy}}{\partial x} + \frac{\partial \sigma_{yy}}{\partial y} = 0 \tag{C.2}
$$

For **plane** strain, **Hooke's** law relates stresses to strains in terms of the material constants μ are ν which are respectively the shear modulus and Poisson's ratio,

$$
\sigma_{xx} = \frac{2\mu}{1-2\nu} \left[(1-\nu)\epsilon_x + \nu\epsilon_y \right] \tag{C.3}
$$

$$
\sigma_{yy} = \frac{2\mu}{1-2\nu} \left[(1-\nu)\epsilon_y + \nu\epsilon_x \right] \tag{C.4}
$$

$$
\tau_{xy} = \mu \gamma_{xy} \tag{C.5}
$$

The plane stress solution can be obtained by replacing ν by $\nu/(1+\nu)$. The **straln-displacement relations** for linear **elasticity are,**

$$
\epsilon_{\mathbf{x}} = \frac{\partial \mathbf{u}}{\partial \mathbf{x}} \; , \quad \epsilon_{\mathbf{y}} = \frac{\partial \mathbf{v}}{\partial \mathbf{y}} \; , \quad \gamma_{\mathbf{xy}} = \frac{\partial \mathbf{u}}{\partial \mathbf{y}} \; \frac{\partial \mathbf{v}}{\partial \mathbf{x}} \; , \tag{C.6}
$$

where u and v are the **x** and **y components of displacement respectively.**

If the **relations in Eqn. C.6 are substituted into** Eqns. **C.3-5 and** if the **resulting** expressions **are** then **substituted into Eqns. C.1,2,** Navier's **equations** for the displacements **are obtained:**

$$
\nabla^2 u + \frac{1}{1-2\nu} \frac{\partial}{\partial x} \left[\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right] = 0 \quad , \tag{C.7}
$$

$$
\nabla^2 \mathbf{v} + \frac{1}{1-2\nu} \frac{\partial}{\partial y} \left[\frac{\partial \mathbf{u}}{\partial \mathbf{x}} + \frac{\partial \mathbf{v}}{\partial y} \right] = 0 \quad . \tag{C.8}
$$

The **geometry of** the **cracked strip and** the **method** of **superposition are shown in Fig. C.1.** Any **field quantity on** the left **of** *this* **figure,** say **f(x,y), is given by,**

$$
f(x,y) = f_1(x,y) + f_2(x,y) , \qquad (0.9)
$$

where the subscripts **correspond** to the **geometries on** the **right.** Eqn. **C.9** is used **for all** relations including the boundary **conditions.** The preceeding **information** will he **used** for **mode** i **and for** mode **2.**

$C.1.1$ Mode 1.

The boundary **conditions for** the symmetric **problem are:**

$$
\tau_{xy}(x,0) = 0 , \qquad (0.10)
$$

$$
\tau_{xy}(0,y) = 0 ,
$$

$$
\tau_{xy}(h, y) = 0,
$$

\n
$$
\sigma_{xx}(0, y) = 0,
$$

\n
$$
\sigma_{xx}(h, y) = 0,
$$

\n
$$
\tau(x, 0) = 0, x \langle a, b \rangle x,
$$

\n
$$
\sigma_{yy} = -p(x), a \langle x \langle b \rangle.
$$

\n(C.12)

To solve **problem** 1 of Fig. C.1 **we** introduce the **exponential** Fourier transform **defined as** follows, f

$$
f(x,y) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} \overline{f}(\beta,y) e^{-i\beta x} d\beta
$$
 (C.13)

$$
\overline{f}(\beta, y) = \int_{-\infty}^{+\infty} f(x, y) e^{i \beta x} dx
$$
 (C.14)

When the Fourier transforms of Eqns. C.7,8 are taken, the following **ordinary** differential **equations** result,

$$
\frac{\partial^2 \overline{u}}{\partial y^2} - \beta^2 \overline{u} + \frac{1}{1-2\nu} \left[-\beta^2 \overline{u} + i \beta \frac{\partial \overline{v}}{\partial y} \right], \qquad (C.15)
$$

$$
\frac{\partial^2 \overline{\mathbf{v}}}{\partial \mathbf{y}^2} - \beta^2 \overline{\mathbf{v}} + \frac{1}{1-2\nu} \left[i \beta \frac{\partial \overline{\mathbf{u}}}{\partial \mathbf{y}} + \frac{\partial^2 \overline{\mathbf{v}}}{\partial \mathbf{y}^2} \right] \qquad (C.16)
$$

These equations are solved **for u and v,** inverted **according** to **C.13 and** then substituted into **Eqns. C.3-5** to **obtain,**

$$
u_1(x,y) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} \left\{ \left[A_1(\beta) + yA_2(\beta) \right] e^{-i\beta y} + \left[A_3(\beta) + yA_4(\beta) \right] e^{i\beta y} \right\} e^{-i\beta x} d\beta,
$$
\n
$$
v_1(x,y) = \frac{i}{2\pi} \int_{-\infty}^{+\infty} \frac{\beta}{|\beta|} \left\{ \left[-A_1(\beta) - \left(\frac{\kappa}{|\beta|} + y \right) A_2(\beta) \right] e^{-i\beta y} + \left[\frac{\beta}{|\beta|} + y \right] e^{-i\beta y} \right\} d\beta.
$$
\n(6.17)

$$
\left[A_3(\beta) - \left(\frac{\kappa}{|\beta|} - y\right) A_4(\beta)\right] e^{i\beta|y} e^{-i\beta x} d\beta , \qquad (C.18)
$$

$$
\sigma_{1xx}(x,y) = \frac{i\mu}{2\pi} \int_{-\infty}^{+\infty} \beta \Biggl\{ \Biggl[-2A_1(\beta) + A_2(\beta) \Bigl(\frac{3-\kappa}{|\beta|} - 2y \Bigr) \Biggr] e^{-|\beta|y} +
$$

$$
\Biggl[-2A_3(\beta) - A_4(\beta) \Bigl(\frac{3-\kappa}{|\beta|} + 2y \Bigr) e^{i|\beta|y} e^{-i\beta x} d\beta , \qquad (C.19)
$$

$$
\sigma_{1yy}(x,y) = \frac{i\mu}{2\pi} \int_{-\infty}^{+\infty} \beta \Biggl\{ \Biggl[2A_1(\beta) + A_2(\beta) \left(\frac{1+\kappa}{|\beta|} + 2y \right) \Biggr] e^{-i\beta|y|} +
$$

$$
\Biggl[2A_3(\beta) + A_4(\beta) \left(-\frac{1+\kappa}{|\beta|} + 2y \right) e^{-i\beta x} d\beta , \qquad (C.20)
$$

$$
\tau_{1xy}(x,y) = \frac{\mu}{2\pi} \int_{-\infty}^{+\infty} \left\{ \left[-2|\beta| \Lambda_1(\beta) + \Lambda_2(\beta) (1-\kappa - 2|\beta|y) \right] e^{-|\beta|y} + \left[2|\beta| \Lambda_3(\beta) + \Lambda_4(\beta) (1-\kappa + 2|\beta|y|) \right] e^{+|\beta|y} \right\} e^{-i\beta x} d\beta , \qquad (C.21)
$$

where $\kappa = 3-4\nu$.

For bounded behavior at infinity

$$
\Lambda_3(\beta) = \Lambda_4(\beta) = 0 \quad . \tag{C.22}
$$

For problem 2 of **Fig.** 0.1 there is **symmetry which** allows the **following Fourier** sine **and cosine transforms** to be **used,**

¢

$$
\overline{u}_2(x,a) = \int_0^{\infty} u_2(x,y) \cos \alpha y \, dy \qquad (C.23)
$$

$$
u_2(x,y) = \frac{2}{\pi} \int_0^{\infty} u_2(x,a) \cos ay \, da
$$
 (C.24)

$$
\overline{v}_2(x,a) = \int_0^{\infty} v_2(x,y) \sin \alpha y \, dy \qquad (C.25)
$$

$$
\mathbf{v}_2(\mathbf{x}, \mathbf{y}) = \frac{2}{\pi} \int_0^{\infty} \mathbf{v}_2(\mathbf{x}, a) \sin \alpha \mathbf{a} \quad . \tag{C.26}
$$

After **performing an identical analysis as was done** with **problem** I, **we obtain,**

$$
u_2(x,y) = \frac{2}{\pi} \int_0^{\infty} \left\{ \left[B_1(a) + B_2(a) \left(\frac{\kappa}{a} + x \right) \right] e^{-ax} - \left[B_3(a) - B_4(a) \left(\frac{\kappa}{a} - x \right) \right] e^{ax} \right\} \cos ay \, da \qquad (C.27)
$$

$$
v_2(x,y) = \frac{2}{\pi} \int_0^x \{ [B_1(a) + xB_2(a)]e^{-ax} +
$$

$$
[B_3(a) + xB_4(a)]e^{ax} \} \sin ay \, da
$$
 (C.28)

$$
\sigma_{2xx}(x,y) = -\frac{2\mu}{\pi} \int_0^{\infty} a \left\{ \left[2B_1(a) + B_2(a) \left(\frac{1+\kappa}{a} + 2x \right) \right] e^{-ax} + \left[2B_3(a) + B_4(a) \left(\frac{1+\kappa}{-a} + 2x \right) \right] e^{ax} \right\} \cos ay \, da \quad , \tag{C.29}
$$

$$
\sigma_{2yy}(x,y) = -\frac{2\mu}{\pi} \int_0^{\infty} a \left\{ \left[-2B_1(a) + B_2(a) \left(\frac{3-\kappa}{a} - 2x \right) \right] e^{-ax} + \left[-2B_3(a) - B_4(a) \left(\frac{3-\kappa}{a} + 2x \right) \right] e^{ax} \right\} \cos ay \, da \qquad (C.30)
$$

$$
\tau_{2xy}(x,y) = \frac{2\mu}{\pi} \int_0^{\infty} \left\{ \left[-2aB_1(a) + B_2(a)(1-\kappa-2ax) \right] e^{-ax} + \left[2aB_3(a) + B_4(a)(1-\kappa+2ax) \right] e^{ax} \right\} \sin ay \, da \qquad (C.31)
$$

Now the boundary **conditions,** Eqns. 0.10-12 **are** applied making use of Eqn. C.9. First Eqn. C.10 relates $A_1(\rho)$ to $A_2(\rho)$ as follows

$$
A_1(\beta) = \frac{1-\kappa}{2|\beta|} A_2(\beta) . \tag{C.32}
$$

Now introduce **a** new unknown,

$$
v(x) = v(x,0) ,
$$

and express $A_2(\beta)$ in terms of it.

$$
A_2(\beta) = \frac{2i\beta}{1+\kappa} \int_{-\infty}^{+\infty} v(t) e^{i\beta t} dt = \frac{2i\beta}{1+\kappa} \int_{a}^{b} v(t) e^{i\beta t} dt
$$
 (C.33)

The unknowns in the problem are $v(x)$ and $B(x_1(a), i=1,\ldots,4$. Eqns. C.11 produce a linear system **of four equations that** determine **Bi(a**) **as follows,**

$$
B_{\underline{i}}(a) = \sum_{j=1}^{4} \frac{I_j \gamma_{\underline{i}j}}{\Delta} , \qquad (C.34)
$$

where

$$
\Delta = e^{2ah} - (4a^{2}h^{2} + 2) + e^{-2ah}, \qquad (C.35)
$$
\n
$$
\gamma_{11} = -(\kappa-1)e^{2ah} + [-4a^{2}h^{2} - 2ah(\kappa-1) + (\kappa-1)] ,
$$
\n
$$
\gamma_{12} = e^{ah} [2ah\kappa + \kappa - 1] + e^{-ah} [-2ah - \kappa + 1] ,
$$
\n
$$
\gamma_{13} = -(\kappa+1)e^{2ah} + [4a^{2}h^{2} + 2ah(\kappa+1) + (\kappa+1)] ,
$$
\n
$$
\gamma_{14} = e^{ah} [-2ah\kappa + \kappa + 1] + e^{-ah} [-2ah - \kappa - 1] ,
$$
\n
$$
\gamma_{21} = 2ae^{2ah} + (4a^{2}h - 2a) ,
$$
\n
$$
\gamma_{22} = e^{ah} [-4a^{2}h - 2a] + 2ae^{-ah} ,
$$
\n
$$
\gamma_{23} = 2ae^{2ah} - (4a^{2}h + 2a) ,
$$
\n
$$
\gamma_{24} = e^{ah} [4a^{2}h - 2a] + 2ae^{-ah} ,
$$
\n
$$
\gamma_{31} = [-4a^{2}h^{2} + 2ah(\kappa-1) + (\kappa-1)] - e^{-2ah}(\kappa-1) ,
$$
\n
$$
\gamma_{32} = e^{ah} [2ah - (\kappa-1)] + e^{-ah} [-2ah\kappa + (\kappa-1)] ,
$$
\n
$$
\gamma_{33} = [-4a^{2}h^{2} + 2ah(\kappa+1) - (\kappa+1)] + (\kappa+1)e^{-2ah} ,
$$

$$
\gamma_{34} = e^{a h} [-2a h + (\kappa + 1)] - e^{-a h} [2a h \kappa + (\kappa + 1)] ,
$$

\n
$$
\gamma_{41} = [4a^2 h + 2a] - 2ae^{-2a h} ,
$$

\n
$$
\gamma_{42} = -2ae^{a h} + [-4a^2 h + 2a] e^{-a h} ,
$$

\n
$$
\gamma_{43} = [4a^2 h - 2a] + 2ae^{-2a h} ,
$$

\n
$$
\gamma_{44} = 2ae^{a h} + [-4a^2 h - 2a] e^{-a h} ,
$$
\n(C.36)

and

$$
I_{1} = \frac{-1}{2(1+\kappa)} \int_{a}^{b} (1-at)e^{-at}v(t) dt ,
$$

\n
$$
I_{2} = \frac{-1}{2(1+\kappa)} \int_{a}^{b} [1-a(h-t)]e^{-a(h-t)}v(t) dt ,
$$

\n
$$
I_{3} = \frac{-1}{2(1+\kappa)} \int_{a}^{b} (2-at)e^{-at}v(t) dt ,
$$

\n
$$
I_{4} = \frac{1}{2(1+\kappa)} \int_{a}^{b} [2-a(h-t)]e^{-a(h-t)}v(t) dt .
$$
\n(0.37)

The mixed boundary **condition** gives **a singular** integral equation **for v** (x), **a<x<b.**

$$
\int_{a}^{b} v(t) \left\{ \frac{1}{(t-x)^2} + K_0(x,t) \right\} dt + \int_{a}^{b} K_{11}(x,t) v(t) dt = \frac{-\pi (1+\kappa)}{4\mu} p(x) \atop (C.38)
$$

where

$$
K_C = -\frac{1}{(t+x)^2} + \frac{12xt}{(t+x)^4} - \frac{1}{(2h-x-t)^2} + \frac{12(h-x)(h-t)}{(2h-x-t)^4} , \qquad (C.39)
$$

and

$$
K_{I1}(x,t) = \int_0^{\infty} \left[S_1(x,t,a) + S_1(h-x,h-t,a) + S_2(x,t,a) + S_2(h-x,h-t,a) \right] da , \qquad (C.40)
$$

$$
S_1(x,t,a) = \frac{e^{-(x+t)a}}{\Delta} \left\{ e^{-2ah} \left[-2a^3x t + a^2(3x+3t) - 5a \right] + 8a^5h^2 x t -12a^4h^2(x+t) + a^3 \left[2hx + 18h^2 + 2xt + 2ht \right] + a^2 \left[-3x - 3t - 6h \right] + 5a \right\} , \quad (C.41)
$$

$$
S_2(x,t,a) = \frac{ae^{(x-t)a}}{\Delta} \left\{ e^{-2ah} \left[-a(x-t) - 3 \right] + a^3 \left[-4h^2t + 4hxt \right] + a^2 \left[6h^2 - 6hx + 6ht \right] + a \left[x - t - 10h \right] + 3 \right\} \qquad (C.42)
$$

$$
\Delta = e^{2\alpha h} - (4a^2h^2 + 2) + e^{-2\alpha h} .
$$
 (C.43)

For an **edge crack** a_O. **The** loading for tension **is,**

$$
p(x) = \sigma_1 \tag{C.44}
$$

and for bending,

$$
p(x) = \frac{2\sigma_2}{h} \left[\frac{h}{2} - x \right]. \tag{C.45}
$$

C.I.2 Mode 2.

The boundary conditions **for** the skew-symmetric case **are,**

$$
\sigma_{yy}(x,0) = 0,
$$
\n
$$
\tau_{xy}(0,y) = 0,
$$
\n
$$
\sigma_{xx}(0,y) = 0,
$$
\n
$$
\sigma_{xx}(0,y) = 0,
$$
\n
$$
\sigma_{xx}(h,y) = 0,
$$
\n(C.47)

$$
u(x,0) = 0, x \langle a, b \rangle x,
$$

\n
$$
\tau_{xy} = -p(x), a \langle x \langle b \rangle.
$$
 (C.48)

The symmetry of problem 2 in Fig. C.1 for the above bounda conditions **suggests** the following Fourier transforms **of** the displacements,

$$
\bar{u}_2(x,a) = \int_0^{\infty} u_2(x,y) \sin \alpha y \, dy \qquad (C.49)
$$

$$
u_2(x,y) = \frac{2}{\pi} \int_0^{\infty} u_2(x,a) \sin \alpha y \, da
$$
 (C.50)

$$
\overline{\mathbf{v}}_2(\mathbf{x}, a) = \int_0^\infty \mathbf{v}_2(\mathbf{x}, \mathbf{y}) \cos \alpha \mathbf{y} \, d\mathbf{y} \quad , \tag{C.51}
$$

$$
\mathbf{v}_2(\mathbf{x}, \mathbf{y}) = \frac{2}{\pi} \int_0^{\infty} \mathbf{v}_2(\mathbf{x}, a) \cos a \mathbf{y} \, da \quad . \tag{C.52}
$$

When these expressions axe **used** to **solve C.7,8 the result is,**

$$
u_2(x,y) = \frac{2}{\pi} \int_0^{\infty} \left\{ -\left[C_1(a) + C_2(a) \left(\frac{\pi}{a} + x \right) \right] e^{-ax} + \left[C_3(a) - C_4(a) \left(\frac{\pi}{a} - x \right) \right] e^{ax} \right\} \sin \alpha y \, d\alpha , \qquad (C.53)
$$

$$
v_2(x,y) = \frac{2}{\pi} \int_0^{\infty} \left\{ \left[C_1(a) + x C_2(a) \right] e^{-ax} + \left[C_3(a) + x C_4(a) \right] e^{ax} \right\} \cos \alpha y \, d\alpha , \qquad (C.54)
$$

$$
\sigma_{2xx}(x,y) = \frac{2\mu}{\pi} \int_0^{\infty} a \left\{ \left[2C_1(a) + C_2(a) \left(\frac{1+\kappa}{a} + 2x \right) \right] e^{-ax} + \left[2C_3(a) + C_4(a) \left(\frac{1+\kappa}{a} + 2x \right) \right] e^{ax} \right\} \sin \alpha y \, d\alpha , \qquad (C.55)
$$

$$
\sigma_{2yy}(x,y) = \frac{2\mu}{\pi} \int_0^{\infty} a \left\{ \left[-2C_1(a) + C_2(a) \left(\frac{3-\kappa}{a} - 2x \right) \right] e^{-ax} + \left[-2C_3(a) - C_4(a) \left(\frac{3-\kappa}{a} + 2x \right) \right] e^{ax} \right\} \sin ay \, da \quad , \tag{C.56}
$$
\n
$$
\tau_{2xy}(x,y) = \frac{2\mu}{\pi} \int_0^{\infty} \left\{ \left[-2aC_1(a) + C_2(a) \left(1 - \kappa - 2ax \right) \right] e^{-ax} + \left[-2a \left(1 - \frac{3-\kappa}{a} \right) \right] e^{-ax} + \left[-2a \left(1 - \frac{3-\kappa}{a} \right) \right] e^{-ax} + \left[-2a \left(1 - \frac{3-\kappa}{a} \right) \right] e^{-ax} + \left[-2a \left(1 - \frac{3-\kappa}{a} \right) \right] e^{-ax} + \left[-2a \left(1 - \frac{3-\kappa}{a} \right) \right] e^{-ax} + \left[-2a \left(1 - \frac{3-\kappa}{a} \right) \right] e^{-ax} + \left[-2a \left(1 - \frac{3-\kappa}{a} \right) \right] e^{-ax} + \left[-2a \left(1 - \frac{3-\kappa}{a} \right) \right] e^{-ax} + \left[-2a \left(1 - \frac{3-\kappa}{a} \right) \right] e^{-ax} + \left[-2a \left(1 - \frac{3-\kappa}{a} \right) \right] e^{-ax} + \left[-2a \left(1 - \frac{3-\kappa}{a} \right) \right] e^{-ax} + \left[-2a \left(1 - \frac{3-\kappa}{a} \right) \right] e^{-ax} + \left[-2a \left(1 - \frac{3-\kappa}{a} \right) \right] e^{-ax} + \left[-2a \left(1 - \frac{3-\kappa}{a} \right) \right] e^{-ax} + \left[-2a \left(1 - \frac{3-\kappa}{a} \right) \right] e^{-ax} + \left[-2a \left(1 - \frac{3-\kappa}{a} \right) \right] e^{-ax} + \left[-2a \left
$$

$$
\left[2aC_3(a) + C_4(a)(1-\kappa+2ax)\right] e^{ax}\cos ay da . \qquad (C.57)
$$

The solution to problem 1 in the **superposltion** of Fig. **C** 1 is the same as for **mode** 1 **(Eqns. C.17-21). Eqn. C.46** gives,

$$
A_1(\beta) = \frac{-(1+\kappa)}{2|\beta|} A_2(\beta) . \qquad (C.58)
$$

After **defining**

$$
u(x) = u(x,0) \tag{C.59}
$$

as a new unknown we can express,

$$
A_2(\beta) = \frac{-2|\beta|}{(\kappa+1)} \int_{-\infty}^{+\infty} u(x) e^{i\beta x} dx = \frac{-2|\beta|}{(\kappa+1)} \int_{a}^{b} u(x) e^{i\beta x} dx
$$
 (C.60)

The Ci(a) are determined from Eqns. C.47 to be,

$$
C_{\mathbf{i}}(a) = \sum_{j=1}^{4} \frac{I_j \gamma_{ij}}{\Delta} , \qquad (C.61)
$$

where γ_{ij} and Δ are the same as for mode 1 (Eqns. $C.35,36$) and the I.'s **are found** *to* be, 3

$$
I_{1} = \frac{-1}{2(1+\kappa)} \int_{a}^{b} ate^{-at} u(t) dt
$$

$$
I_{2} = \frac{1}{2(1+\kappa)} \int_{a}^{b} a(h-t) e^{-a(h-t)} u(t) dt
$$

$$
I_3 = \frac{1}{2(1+\kappa)} \int_{a}^{b} (1-\alpha t) e^{-\alpha t} u(t) dt
$$

$$
I_4 = \frac{1}{2(1+\kappa)} \int_{a}^{b} [1-\alpha (h-t)] e^{-\alpha (h-t)} u(t) dt .
$$
 (C.62)

The mixed **boundary condition,** Eqn. **0.48,** gives **a singular** integral **equation** for **u(x), a<x<b.**

$$
\int_{a}^{b} u(t) \left\{ \frac{1}{(t-x)^2} + K_0(x,t) \right\} dt + \int_{a}^{b} K_{12}(x,t) u(t) dt = \frac{-\pi (1+\kappa)}{4\mu} p(x) \tag{C.63}
$$

where

$$
K_C = -\frac{1}{(t+x)^2} + \frac{12xt}{(t+x)^4} - \frac{1}{(2h-x-t)^2} + \frac{12(h-x)(h-t)}{(2h-x-t)^4} , \qquad (C.64)
$$

and

$$
K_{I2}(x,t) = \int_0^{\infty} \left[S_3(x,t,a) + S_3(h-x,h+t,a) + S_4(x,t,a) + S_4(h-x,h-t,a) \right] da ,
$$
 (C.65)

$$
S_{3}(x, t, a) = \frac{e^{-(x+t)a}}{\Delta} \left\{ e^{-2ah} \left[-2a^{3}x t + a^{2}(x+t) - a \right] + 8a^{5}h^{2}xt \right\}
$$

$$
-4a^{4}h^{2}(x+t) + a^{3} \left[2hx + 2h^{2} + 2xt + 2ht \right] - a^{2} \left[x + t + 2h \right] + a \right\} , \qquad (C.66)
$$

$$
S_4(x, t, a) = \frac{ae^{(t-x)a}}{\Delta} \left\{ e^{-2ah} [a(t-x)+1] + a^3 [4h^2x - 4hxt] \right\}
$$

+
$$
a^2 [-2h^2 - 2hx + 2ht] + a [-t+x+2h] - 1 \}
$$
 (C.67)

$$
\Delta = e^{2ah} - (4a^2h^2 + 2) + e^{-2ah} .
$$
 (C.68)

For an edge **crack** a=O. **To obtain** the **mode 2 stress intensity factor for parabollc** shear loading **we** let

$$
p(x) = \sigma_3 (2/h)^2 x (h-x) . \qquad (C.69)
$$

C.2 Anti-plane shear.

The governing **equation** for **anti-plane** shear **is,**

$$
\nabla^2 \mathbf{w} = \mathbf{0} \quad , \tag{C.70}
$$

where w **is the z-component** of displacement. The stresses **and** strains can be **written in** terms of **w,**

$$
\tau_{xz} = \mu_{\partial x}^{\partial w} , \qquad \tau_{yz} = \mu_{\partial y}^{\partial w} , \qquad (C.71)
$$

$$
\gamma_{\mathbf{x}\mathbf{z}} = \frac{\partial \mathbf{w}}{\partial \mathbf{x}} \; , \qquad \gamma_{\mathbf{y}\mathbf{z}} = \frac{\partial \mathbf{w}}{\partial \mathbf{y}} \; . \tag{C.72}
$$

All other **components are** zero. Again the superposition of Fig. C.1 together with Eqn. C.9 **are** used. The **general solution** for w(x,y) in terms of the Fourier transforms of Eqns. C.13,14 **and** C.25,26 is,

$$
w(x,y) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} A_1(\beta) e^{-i\beta y} e^{-i\beta x} d\beta +
$$

$$
\frac{2}{\pi} \int_{0}^{\infty} [B_1(\alpha) e^{-\alpha x} + B_2(\alpha) e^{\alpha x}] \sin \alpha y d\alpha
$$
 (C.73)

There **are** three unknowns **in** the above **equation** and the **following** conditions will **determine** them,

$$
\tau_{\mathbf{x}\mathbf{z}}(0,\mathbf{y}) = 0 \tag{C.74}
$$

$$
\tau_{xz}(h, y) = 0 \tag{C.75}
$$

$$
\tau_{yz}(x,0) = -p(x), \quad a < x < b,
$$
\n
$$
w(x,0) = 0, \quad x < a, \quad x > b.
$$
\n(C.76)

After defining

$$
\phi(x) = \frac{\partial w}{\partial x}\Big|_{y=0} \quad , \tag{C.77}
$$

Eqn. **C.73** becomes,

$$
\phi(\mathbf{x}) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} -i\beta A_1(\beta) e^{-i\beta x} d\beta
$$
 (C.78)

Inversion **(Eqns. C.13,14) and** Eqn. **C.76 give,**

$$
-i\beta A_1(\beta) = \int_{-\infty}^{+\infty} \phi(t) e^{i\beta t} dt = \int_{a}^{b} \phi(t) e^{i\beta t} dt
$$
 (C.79)

In **order** to **apply boundary conditions C.74.75, Eqns. C.71,73 and** 79 **are used** to **express,**

$$
\tau_{xz}(x,y) = \frac{\mu}{2\pi} \int_{a}^{b} \frac{2\phi(t)}{y^2 + (t-x)^2} dt
$$

+
$$
\frac{2\mu}{\pi} \int_{0}^{\infty} \left[-aB_1(a)e^{-\alpha x} + aB_2(a)e^{\alpha x} \right] \sin \alpha y d\alpha
$$
 (C.80)

Eqns. **C.74,75 give** the **following** two inverted **equations,**

$$
B_1(a)e^{-ah} - B_2(a)e^{ah} = \frac{1}{2a}\int_a^b \phi(t) e^{-a(h-t)}dt = I_1,
$$
 (C.81)

$$
B_1(a) - B_2(a) = \frac{1}{2a} \int_a^b \phi(t) e^{-at} dt = I_2,
$$
 (C.82)

where the **following integral** has been **used,**

$$
\int_{0}^{\infty} \frac{y \sin \alpha y}{y^{2} + (h-t)^{2}} dy = \frac{\pi}{2} e^{-\alpha (h-t)}.
$$
 (C.83)

The solution is,

$$
B_1(a) = \frac{-I_1 e^{-ay} + I_2}{-e^{-2ah} + 1}, \qquad (C.84)
$$

$$
B_2(a) = \frac{-I_1 e^{-ay} + I_2 e^{-2ah}}{-e^{-2ah} + 1},
$$
 (C.85)

where I**1** and **12 axe defined** in Eqns. **C.81,82.** Next we **apply** the mixed boundary **condition** C.76. Eqns. **C.71 and C.73** must be used to **express**

$$
\tau_{yz}(x,0) = -p(x) = \lim_{y \to 0} \frac{\mu}{2\pi} \int_{a}^{b} \phi(t) \int_{-\infty}^{+\infty} -i \frac{|\beta|}{\beta} e^{-|\beta|} y e^{i \beta (t-x)} d\beta dt +
$$

$$
\lim_{y\to 0} \frac{\mu}{\pi} \int_{\frac{a}{2}}^{b} (t) \int_{0}^{\infty} \frac{1}{b} \left\{ -e^{-a(x+2h-t)} + e^{-a(x+t)} - e^{-a(-x+2h-t)} + e^{-a(-x+2h+t)} \right\} \, \mathrm{d}a \,, \tag{C.86}
$$

where

$$
D = 1 - e^{-2a h} \tag{C.87}
$$

After using the following **integrals,**

$$
\int_{-\infty}^{+\infty} -i\frac{|\beta|}{\beta} e^{-|\beta| y} e^{i\beta(t-x)} d\beta = \frac{2(t-x)}{y^2 + (t-x)^2} , \qquad (C.88)
$$

$$
\int_{0}^{\infty} \frac{1}{b} \left\{ e^{-a(x+t)} - e^{-a(-x+2h-t)} \right\} d\alpha = \frac{\pi}{2h} \cot \frac{(x+t)\pi}{2h} , \qquad (C.89)
$$

Eqn. C.87 becomes,

$$
\frac{1}{\pi}\int_{a}^{b}\phi(t)\left\{\frac{\pi}{2h}\left[\cot\frac{(x+t)\pi}{2h}-\cot\frac{(x-t)\pi}{2h}\right]\right\}dt=\frac{-1}{\mu}p(x) . \qquad (C.90)
$$

This kernel is equivalent to the following,

$$
\frac{\pi}{2h} \left[\cot \frac{(x+t)\pi}{2h} - \cot \frac{(x-t)\pi}{2h} \right] = \frac{1}{t-x}
$$
 (Cauchy kernel)
+ $\frac{\pi}{2h} \cot \frac{(x+t)\pi}{2h}$ (generalized Cauchy kernel)
+ $\frac{1}{x-t} - \frac{\pi}{2h} \cot \frac{(x-t)\pi}{2h}$ (Fredholm kernel) . (C.91)

h

This same problem formulated in a different way has been solved **in closed** form (see [77]). The solution for an edge **crack** is,

$$
\tau_{yz}(x,y) = \frac{\mu}{2h} \frac{\sin(\frac{\pi a}{2h})}{\sin^2(\frac{\pi x}{2h}) - \sin^2(\frac{\pi a}{2h})} \int_{-a}^{+a} \frac{g(\tau)}{\sin(\frac{\pi}{2h})} \frac{1 - k^2 \sin^2(\frac{\pi \tau}{2h})}{\sin(\frac{\pi}{2h})} d\tau ,
$$
\n(0.92)

where

$$
g(x) = g(-x) , \qquad (C.93)
$$

and

$$
k = (\sin \frac{\pi a}{2h})^{-1} \tag{C.94}
$$

The stress intensity factor **is** defined **as,**

$$
k_{3} = \frac{\lim_{x \to a} \sqrt{2(x-a)} \tau_{yz}(x,0) , \qquad (C.95)
$$

so

$$
k_3 = \frac{\mu_2}{h} \sqrt{\frac{h}{2\pi} \tan \frac{\pi_2}{2h}} \int_{-1}^{+1} \frac{g(at) \sqrt{1 - k^2 \sin^2(\frac{\pi_2}{2h}t)}}{\sin \frac{\pi}{2h}(t-1)} dt , \qquad (0.96)
$$

For in-plane **shear,**

$$
g(x) = \sigma_{\underline{4}} \t\t(0.97)
$$

so

$$
\frac{k_3}{\sigma_4 \sqrt{a}} = \sqrt{\frac{2}{\pi \xi} \tan(\frac{\pi}{2} \xi)}, \quad \xi = a/h
$$
 (C.98)

Because of this **simple expression a44 (Bqn. 2.27)** can be **determined in closed** form,

$$
\alpha_{44} = \frac{-4}{\pi(1-\nu)} \ln[\cos(\frac{\pi}{2}\xi)] \quad . \tag{C.99}
$$

For twisting,

$$
g(x) = \frac{2\sigma_5}{h} \left[\frac{b}{2} - |x| \right], \qquad (C.100)
$$

$$
\frac{k_3}{\sigma_4 \sqrt{a}} = \sqrt{\frac{2}{\pi \xi} \tan(\frac{\pi}{2} \xi)} \left\{ 1 - \frac{8}{\pi^2} \int_0^1 \frac{\sin^{-1} t}{\sqrt{1 - t^2}} dt \right\}.
$$
 (C.101)

C.3 Edge Crack SIF Curve Fittin_

The five solutions are listed in table C.1. In addition to the **solutions required by** the line-spring **model,** constant out-of-plane shear (σ_{β}) is also included.

The **line-spring** model **requires stress intensity factors at any value** of _ = **a/h, so a** curve is fit **to each solution appearing in** table **C.1. For mode 1** the **asymptotic analysis of Benthem and Kolter, [65]** to infinity with a power of $3/2$. Therefore for $g_1(\xi)$ and $g_2(\xi)$ we us **suggests** that **as** _ **approaches 1** the **stress intensity factor** goes

$$
g_{i}(\xi) = \frac{1}{(1-\xi)^{3/2}} \sum_{k=0}^{12} C_{ik} \xi^{k} , \quad i = 1, 2 .
$$
 (C.102)

For all other cases a 1/2 power is **used,**

$$
g_{i}(\xi) = \frac{1}{(1-\xi)^{1/2}} \sum_{k=0}^{8} C_{ik} \xi^{k} , \quad i = 3, 4, 5, 6.
$$
 (C.103)

Although the singular behavior **for mode 2** seems to be the same **as** for **mode 1, (see** Eqns. **C.38,39 vs. 63,64),** the **form** given in **Eqn. C.103 produced a** better **fit** than **did 102. For** twisting **and** in-plane-shear the form of 103 is correct as can be seen by Eqns. $C.98,101$. The $C_{\frac{1}{2}}$ **are** given in tables **C.2,3. These curves reproduce** the **numbers in** table **C.1. The most difficult** curves to obtain and to **fit are** the mode **1** curves. **The limiting values for** _ **approaching 1 are** given in

SO

[65] to be **1.122** and .374 **for** tension **and for** bending **respectively.** The **curve given by** Eqn. **C.102 produces 1.1229 and .3735** which shows both good **data and a** good **curve fit.**

For reference the **compliance curves** that **have been used in** the **literature** to **date are listed below. They are for** tension **and bending** only.

1. Cross and Srawley, 1965, [61], **used** in **Refs. [2,3].**

$$
\frac{k_1}{\sigma_1 \sqrt{a}} = \frac{1}{\sqrt{\pi}} \Biggl\{ 1.99 - .41 \xi + 18.7 \xi^2 - 38.48 \xi^3 + 53.85 \xi^4 \Biggr\} , \qquad (C.104)
$$

$$
\frac{k_1}{\sigma_2 \sqrt{a}} = \frac{1}{\sqrt{\pi}} \Biggl\{ 1.99 - 2.47 \xi + 12.97 \xi^2 - 23.17 \xi^3 + 24.8 \xi^4 \Biggr\} \quad . \tag{C.105}
$$

2. Tada, Paris, Irwin, **1973, [62], used in Refs. [50,51,53,55].**

$$
\frac{k_1}{\sigma_1 \sqrt{a}} = \left\{ \frac{2}{\pi \xi} \tan \frac{\pi \xi}{2} \right\}^{1/2} \left\{ \frac{.752 + 2.02 \xi + .37 \left[1 - \sin \left(\pi \xi / 2 \right) \right]^3}{\cos \left(\pi \xi / 2 \right)} \right\} , \quad (C.106)
$$

$$
\frac{k_1}{\sigma_2 \sqrt{a}} = \left\{ \frac{2}{\pi \xi} \tan \frac{\pi \xi}{2} \right\}^{1/2} \left\{ \frac{.923 \cdot .199 \left[1 - \sin \left(\frac{\pi \xi}{2} \right) \right]^4}{\cos \left(\frac{\pi \xi}{2} \right)} \right\} \quad . \tag{C.107}
$$

3. Kaya and Erdogan, 1980, **[63],** used **in** Refs. **[54,56-60].**

$$
\frac{k_1}{\sigma_1 \sqrt{a}} = 1.1216 + 6.5200 \xi^2 - 12.3877 \xi^4 + 89.0554 \xi^6
$$

-188.6080 \xi^8 + 207.3870 \xi^{10} - 32.0524 \xi^{12} , (C.108)

$$
\frac{k_1}{\sigma_1 \sqrt{a}} = 1.1202 - 1.8872 \xi + 18.0143 \xi^2 - 87.3851 \xi^3
$$

+241.9124 \xi^4 - 319.9402 \xi^5 + 168.0105 \xi^6 . (C.109)

C.4 Line-Spring Kodel **SIF** Normalization

The stress intensity factor solutions **for** *the* **line-spring** model **are normalized** with **respect** to the corresponding **plane strain value at** the **center of** the **crack. This** shows how the **constraining effect of** the **ends affects the crack driving force. The dimensional SIFs provided by** the **LSM are**

$$
K_1 = \sqrt{\pi \xi h} \left[\sigma_1 g_1 + \sigma_2 g_2 \right] , \qquad (C.110)
$$

$$
K_2 = \sqrt{\pi \xi h} \sigma_3 g_3 \tag{C.111}
$$

$$
K_3 = \sqrt{\pi \xi h} [\sigma_4 g_4 + \sigma_5 g_5] .
$$
 (C.112)

These are normalized with **respect** to

$$
K_{j0} = \sqrt{\pi \xi_0 h} \, \frac{\omega}{\sigma} k g_k(\xi_0) \quad , \tag{C.113}
$$

where k corresponds to the **loading and j=l when k=l,2, j=2 when k=3,** and $j=3$ when $k=4,5$. Note that the primary SIF is used for all modes given **in Eqns. C.110-112.**

Table **C.1** Stress intensity **factors for an** edge cracked .strip for tension, bending, constant inplane-shear, parabolic **out-of-plane** shear , **twisting, and constant out-of-plane shear**

STRESS INTENSITY FACTORS

Table C.2 The compliance coefficients for $g_1(\xi)$ and $g_2(\xi)$ for tension and bending respectively.

COMPLIANCE COEFFICIENTS

Mode 1

Table **C.3** The compliance coefficients for $g_i(\xi)$, i=3,4,5,6, for parabolic in-plane-shear, constant out-of-plane **shear, twisting and constant in-plane-shear respectively.**

COMPLIANCE COEFFICIENTS

Modes **2 and 3**

Figure C.1 The geometry and superposition for the **cracked strip.**

APPEN1)II **I)**

Determination of the Weight Function

the $v(x)$ for $a\langle x\langle b.$ The **solution of** a **singular integral equation such** as Eqn. B.5 or **strongly** singular version, Eqn. B.9 involves obtaining $\phi(x)$ or Before attempting the numerical solution, the Behavior **or** weight **of** the **unknown** at the **endpoints,** a and **h, should** he **determined** that will force the singular **or dominant** integral to he **of** the same **order** as the **other** terms in the **equation.** Without this asymptotic behavior an accurate solution **near** the **ends** is **difficult** to **obtain, although in** the **central portion** convergence is acceptable (at least for the integral **equations studied** in this **dissertation).** We then seek to obtain α and β defined as,

$$
\phi(t) = f(t) w_1(t) = f(t) (b-t)^{\alpha-1} (t-a)^{\beta-1}, \qquad (D.1)
$$

$$
v(t) = g(t)w_2(t) = g(t)(b-t)^a(t-a)^b,
$$
 (D.2)

for **finite**

$$
g(a), g(b), f(a), f(b) \neq 0
$$
, (D.3)

where $w_i(x)$ are known as weight functions for the integral equation

The typical integral equation studied in fracture mechanics **has a** right-hand side (p(x) in Eqns. B.5,9) that is **of order** one. Here the weight function must he such that the singular term in these equations is **finite.** All through crack **problems are in** this category. However for the part-through crack case, only when the crack shape, $\xi(x)$ is of the form,

$$
\xi(x) = \xi_0 (1 - x^2)^{\gamma}, \quad \gamma \leq 1/4 \quad , \tag{D.4}
$$

is this condition met. If $\gamma > 1/4$ the line-spring terms will be unbounded and for γ < 1/4 they will be zero (see Chapter 2). If γ > 1/4, such as for a semi-ellipse $(\gamma = 1/2)$, a solution for a $\langle x \langle b \rangle$ can **only** be **obtained** if **a** weight **is chosen** that will duplicate *this* unbounded behavior. For the special case where $K(x,t)$ is zero (see Eqn. **B.5,9)** and γ < 1/4, the weight function should be chosen such that the singular integral matches the 7 **dependent** *zero* behavior **of** the line-sprlng **contribution.** In both **of** these **cases** the weight **function** will **be** such that the **displacement profile** will be **physically unacceptable.** If this matching **is ignored and** the through crack weight is used for all γ , a convergent solution to the part-through crack **problem** can **still** be obtained **for about** 98_ of the domain, **a<x<b** without too much **extra** computer time. Of **course this** is well beyond the **expected range of validity of** the **line-spring** model, **and** therefore **all** crack **shapes** will be treated **as though** the **resulting line-spring** terms **are** of order **one.** One way to **deal** with **this problem, shown in** Chapter 2, is to force $\gamma = 1/4$ behavior at the endpoints.

- **First consider** the internal crack **case** of **an equation of** the **form o_ B.5. From** the basic **theory of** Kuskhelishvili **[78], and** from **Eqn. B.22** to **extend** this **theory** to **finite-part** integrals **(see** Kaya **[67]), we have,**

$$
\lim_{x \to a} \frac{1}{\pi} \int_{a}^{b} \frac{v(t)}{(t-x)^{2}} dt \approx -\beta \cot(\pi) \lim_{x \to a} \frac{v(x)}{x-a} + 0(1) , \qquad (D.5)
$$
$$
\lim_{x \to b} \frac{1}{\pi} \int_{a}^{b} \frac{v(t)}{(t-x)^{2}} dt \approx -acot\pi a \lim_{x \to b} \frac{v(x)}{b-x} + 0(1) , \qquad (D.6)
$$

where

$$
v(t) = g(t)(b-t)^{\alpha}(t-a)^{\beta}, \quad g(a), g(b) \neq 0
$$
 (D.7)

For Eqns. D.5,6 to be of order one,

$$
\cot \pi \beta = \cot \pi a = 0 \tag{D.8}
$$

This gives,

$$
\beta = \alpha = 1/2, 3/2, \ldots \tag{D.9}
$$

As a rule **for** deciding **what** form to take for finite-part **integrals, Kaya** [79] states that **all** roots should be used such that g(x) and **its** derivatives remain bounded at x approaching a and b. Therefore we take,

$$
\alpha = \beta = 1/2 \quad , \tag{D.10}
$$

and

$$
v(t) = g(t) (b-t)^{1/2} (t-a)^{1/2} . \qquad (D.11)
$$

In order to obtain the **compliance** functions used in the linespring model, the edge **cracked** strip (Appendix **C)** must be solved. The **crack** opening displacement, v(x) will have a different weight function **-** than Eqn. D.11. From Eqn. C.39 note that there are integrals **which** become -singular **when** both t and x go to zero simultaneously, so these terms must be included in the limit as x+O.

$$
\frac{1}{\pi} \int_{0}^{b} \frac{v(t)}{(t-x)^2} dt + \frac{1}{\pi} \int_{0}^{b} \frac{-v(t)}{(t+x)^2} dt + \frac{1}{\pi} \int_{0}^{b} \frac{12xt}{(t+x)^4} v(t) dt \sim 0(1), \tag{D.12}
$$

for

$$
v(t) = g(t) (b-t)^{\alpha} t^{\beta} , \t g(0), g(b) \neq 0 . \t (D.13)
$$

The analysis for x at b is the same as for the internal crack. From $Ref.$ [67] we have,

$$
\lim_{x\to 0} \frac{1}{\pi} \int_0^b \frac{v(t)}{(t-x)^2} dt = -\beta \cot(\pi \beta) \frac{\sin(\pi x)}{x+0} + 0(1), \qquad (D.14)
$$

$$
\lim_{x \to 0} \frac{1}{\pi} \int_0^b \frac{v(t)}{(t+x)^2} dt = \frac{\beta}{\sin \pi \beta} \lim_{x \to 0} \frac{v(x)}{x} + 0(1) , \qquad (D.15)
$$

$$
\frac{1}{\pi}\int_{0}^{b} \frac{12xt}{(t+x)^{4}} v(t) dt = \frac{12(\beta+1)\beta(\beta-1)}{3!\sin(\beta+1)} \lim_{x \to 0} \frac{v(x)}{x} + 0(1) .
$$
 (D.16)

Therefore the characteristic equation for β is,

$$
-\beta \cot \pi \beta - \frac{\beta}{\sin \pi \beta} + \frac{2(\beta+1)\beta(\beta-1)}{\sin \pi(\beta+1)} = 0 \quad , \tag{D.17}
$$

which reduces to,

$$
\frac{-\beta}{\sin \pi \beta} \left[\cos \pi \beta - 1 + 2\beta^2 \right] = 0 \quad , \tag{D.18}
$$

which has the root $\beta = 0$. Therefore for an edge crack,

$$
v(t) = g(t) (b-t)^{1/2} . \t\t (D.19)
$$

APPBNDIX E

Numerical Methods for the Solution **of** Singular Integral Equations

In this section the two most **common** numerical methods for solving singular integral **equations** of the following **form** will be **considered:**

$$
\int_{a}^{b} \phi(t) dt + \int_{a}^{b} \phi(t) K(x, t) dt = p(x), \quad a \langle x \langle b \rangle,
$$
 (E.1)

$$
\oint_{a}^{b} \frac{v(t)}{(t-x)^{2}} dt - \int_{a}^{b} v(t) \frac{\partial K}{\partial t} dt = p(x) , \quad a \langle x \langle b . \rangle
$$
 (E.2)

These two equations **are** equivalent for

$$
\mathbf{v}(t) = \mathbf{v}^+(t) - \mathbf{v}^-(t) , \quad \phi(t) = \frac{\partial \mathbf{v}}{\partial t} , \qquad (E.3)
$$

with the condition

$$
\mathbf{v}(\mathbf{a}) = \mathbf{v}(\mathbf{b}) = 0 \tag{E.4}
$$

which **for** Eqn. E.1 is expressed **as,**

$$
\int_{a}^{b} \phi(t) dt = 0 . \qquad (E.5)
$$

Both solution methods can easily be generalized to include multi unknowns **and multiple cracks,** so for simplicity **will** be left **out.**

E.1 Quadrature.

Here we **consider** the solution of Eqn. E.1 for the **case** of **an** internal **crack.** The first step is to express the unknown in terms of its **weight function** given in Eqn. D.11. We have,

$$
\phi(t) = \frac{f(t)}{(t-a)^{1/2} (b-t)^{1/2}} \quad . \tag{E.6}
$$

This is substituted into Eqn. E.1 using the following definitions:

$$
t = \frac{b-a}{2}r + \frac{b+a}{2} \quad , \tag{E.7}
$$

$$
x = \frac{b-a}{2}s + \frac{b+a}{2} \quad , \tag{E.8}
$$

$$
p(x) = \overline{p}(s) \quad , \tag{E.9}
$$

$$
\phi(t) = \frac{\overline{f}(r)}{(1-t^2)^{1/2}}, \quad f(t) = \frac{b-a}{2} \overline{f}(r) , \qquad (E.10)
$$

$$
L(r,s) = \frac{b-a}{2} K(x,t) , \qquad (E.11)
$$

to obtain,

$$
\int_{-1}^{+1} \frac{\overline{f}(r) dr}{(1-r^2)^{1/2} (r-s)} + \int_{-1}^{+1} \frac{\overline{f}(r)}{(1-r^2)^{1/2}} L(r,s) dr = \overline{p}(s) , -1\langle s\langle 1 .
$$
\n(E.12)

We now **make** use of the **quadrature** formula

$$
\int_{-1}^{+1} \frac{h(r)}{(1-r^2)^{1/2}} dr = \sum_{j=1}^{N} w_j h(r_j) , \qquad (E.13)
$$

where

$$
r_j = \cos \frac{j-1}{N-1} \pi , \quad j = 1, ..., N , \qquad (E.14)
$$

which are roots of the Chebychev polynomial $T_N(r)$, and

$$
w_{j} = \frac{\pi}{N-1} , \quad j = 2, ..., N-1 ,
$$

$$
w_{1} = w_{N} = \frac{\pi}{2(N-1)} .
$$
 (E.15)

This **quadrature** is **exact** when the **function h(t)** is **a polynomial of degree (2N-I) or less** and therefore **has** good **convergence when** integrating the **well** behaved Fredholm kernel **L(r,s)** in Eqn. E.12 **as N** is increased. **However** the integration of the singular **term** in **this**

values of sare chosen to make U_N zero, the error is reduced and th integration is exact **for** polynomials of degree 2N or less. The s **values are,** equation introduces a **relatively** large error which has been **found** to be proportional to the Chebychev polynomial $U_N(r)$. Therefore when

$$
s_{i} = \cos \frac{2i-1}{N-1} \frac{\pi}{2} , i = 1,..., N-1 . \qquad (E.16)
$$

It is this **information that** makes the method work. **Applying** the quadrature formula to **Eqn. B.11,** we **obtain,**

$$
\sum_{j=1}^{N} w_j f(r_j) \left[\frac{1}{r_j - s_i} + L(r_j, s_i) \right] = p(s_i) , i = 1,..., N-1 , (E.17)
$$

which is a system of N **unknowns** $(g(r_j), j=1,...,N)$ and $N-1$ equations. **Recalling** Bqn. E.5 we **supplement** Eqn. E.17 with

$$
\sum_{j=1}^{N} w_j f(r_j) = 0 \t\t(E.18)
$$

which can then be **solved as a** system of **linear algebraic equations.** Convergence is obtained **as** N is **increased.**

In the case **of** an edge crack where **a** *=* **O,** the weight function changes (see Eqn. D.19) and $\phi(t)$ becomes,

$$
\phi(t) = \frac{f(t)}{(b-t)^{1/2}} \tag{E.19}
$$

After substitution using Eqns. E.7-11 **with a=O,** the singular integral equation, E.1 becomes,

$$
\int_{-1}^{+1} \frac{\overline{f}(r) dr}{(1-r)^{1/2} (r-s)} + \int_{-1}^{+1} \frac{\overline{f}(r)}{(1-r)^{1/2}} L(r,s) dr = \overline{p}(s) , -1 \leq 1 .
$$
\n(E.20)

The necessary quadrature for this weight function is,

$$
\int_{-1}^{+1} \frac{h(r)}{\sqrt{1-r}} dr = \sum_{j=1}^{N} w_j h(r_j) , \qquad (E.21)
$$

where **now** the values **of** w. **and r.** must be **obtained** numerically **as** J **roots of** the **following** Jacobi **polynomials:**

$$
P_N^{(-1/2,-1)}(t_j) = 0 \quad , \quad j = 1,...,N \quad .
$$
 (E.22)

$$
P_{N-1}^{(1/2,1)}(s_i) = 0 \quad , \quad i = 1, ..., N-1 \quad .
$$
 (E.23)

It is **easier** to use Eqns. E.12-16 **and include (l+t) I/2** in the **function** f(r). For the edge **crack** however, Eqn. E.18 is replaced **with**

$$
h(-1) = h(t_N) = 0 \quad . \tag{E.24}
$$

The quadrature method is not a good choice for the solution of strongly singular integral equations such as Eqn. E.2 because the **existing** quadrature **formulas for finite-part** integrals involve **operations** that make solving the integral **equations far** more **complicated** than solving the **equivalent equation** with **a** Cauchy singularity, **(see** [67]). **Perhaps** in time **a** more convenient quadrature **will** be developed. A better and simpler approach to solving Eqn. E.2 is the expansion method, or more specifically, the collocation method.

E.2 **Collocation.**

as First **consider** the internal **crack where** the unknown is **expressed**

$$
v(t) = g(t) (t-a)^{1/2} (b-t)^{1/2} . \qquad (E.25)
$$

Note that Eqn. B.4 is satisfied which shows an **advantage of** using the displacement **as** the **unknown** which leads to **a** strongly singular integral equation. Again use Eqns. E.7-9 with

$$
v(t) = \frac{b-a}{2} \bar{v}(r) (1 - r^2)^{1/2}, \qquad (E.26)
$$

$$
L(r,s) = \left(\frac{b-a}{2}\right)^2 \frac{\partial K}{\partial t} \tag{E.27}
$$

Substituting into Eqn. E.2 **we obtain,**

$$
\int_{-1}^{+1} \frac{\bar{v}(r)\sqrt{1-r^2}}{(r-s)^2} dr + \int_{-1}^{+1} \bar{v}(r) (1-r^2)^{1/2} L(r,s) dr = \bar{p}(s) ,
$$

-1<5<1. (E.28)

Next we choose

$$
\bar{v}(r) = \sum_{j=1}^{N} a_j f_{j-1}(r) , \qquad (E.29)
$$

where fj(r) **are linearly independent functions chosen** to "fit the curve" and the a. are coefficients to be determined. I believe that J it is best to choose orthoganol **polynomials** so that the coefficients show convergence **as N** is increased. The proper choice **for** the **weight** of Eqn. E.28, is the Chebychev polynomial of the second kind, $U_{j-1}(r)$. With other functions such as a simple power series r^{j-1} , convergence can only be seen by calculating the sum (Eqn. E.29) **as** the coefficients themselves do not converge. **Also as** N gets large the coefficients of r **j-1** can get large enough to cause round off error **as** was experienced with the thin plate limit in Chapter 3. This problem is **avoided** when **using** orthoganol polynomials. These convergence characteristics **are** shown in table **E.1** where the coefficients, **a. are** J

listed for N = 10 and 20, using both $U_{(2j-2)}(r)$ and $r^{(2j-2)}$ for the fitting function, $f_{(2j-2)}(r)$ (see Eqn. 29). The problem is symmetric in r so only even functions have non-zero coefficients. This shows slow convergence typical of paxt-through crack problems. Although the numbers for $N = 20$ and $r^{(2j-2)}$ are large, they give the same result as the Chebychev polynomials. Mostly all problems can be solved with power series, but the orthoganol polynomials, I believe, are better.

Next substitute Eqn. E.29 into Eqn. E.28 to obtain,

$$
\sum_{j=1}^{N} a_j \left\{ f^{-1} \frac{f_j(r) (1 - r^2)^{1/2}}{(r - s)^2} dr + \int_{-1}^{+1} f_j(r) (1 - r^2)^{1/2} L(r, s) dr \right\} = \bar{p}(s)
$$

-1 < 5 < 1 . (E. 30)

With this method there is no restriction **on** the **choice** of s as long as it does not **coincide with** r in Eqn. E.30. Roots of Chebychev polynomials **which concentrate** points near -1 and +1 are a good **choice when** information **near** the endpoints is needed such as the determination **of** stress **intensity factors** for through **cracks. Table** E.2 lists the **coefficients** for N = **3 and 6 and** the resulting stress intensity **factor** to show how good **convergence** is **for this** type of integral **equation.**

A more uniform spacing of points has been found to be **a** better **choice for convergence** of the line-spring model **where** information in the **central** portion **is** more **important** (see Table E.3). In this table **equally** spaced points improve **convergence** by **about** one order of magnitude. **Another** reason to prefer this **choice of** sj is that the solution is most **accurate there** (recall that the **collocation** method gives the solution for **all** s) **and** it is more **convenient** to know the solution **at** these points than **at** the roots **of an orthoganol** polynomial.

For **a** given **value** of s there **are** two integrations to perform in Eqn. E.30. Any standard technique **can** he used, **for** example Gauss-Chebychev **quadrature** which takes **advantage** of the weight,

$$
\int_{-1}^{+1} h(r) (1 - r^2)^{1/2} dr = \sum_{k=1}^{M} w_k h(r_k) , \qquad (E.31)
$$

where

$$
w_k = \frac{\pi}{M+1} \left(\sin \frac{k\pi}{M+1} \right)^2 , \qquad (E.32)
$$

$$
r_k = \cos \frac{k \pi}{M+1} \tag{E.33}
$$

The **first** integral **can he determined** by **using Eqn. B.27 or for certain expansion functions fj(r)** such **as Uj(r),** there **are** closed **form expressions. For example,**

$$
\int_{-1}^{+1} \frac{U_j(r) (1 - r^2)^{1/2}}{(r - s)^2} dr = -\pi (j + 1) U_j(s) .
$$
 (E.34)

See **Appendix** A or Ref. **[67] for** similar **formulas for other functions** and **other weights. Therefore** if **Eqn.** E.30 is **evaluated at N different** points, the coefficients, **aj** , **j=I,...,N can** be **determined. Also a**]east squares technique can **be applied if** more than **N values of** s **are selected.**

Both numerical **methods have Been used** in this **dissertation, and** the collocation method **has** been **found** to be better. One **important** advantage of this method is that the number **of unknowns is unrelated** to the **way** in which the integrations **are performed.** This makes **for**

better efficiency. Another **advantage is** that the function **is** given **at all** points instead of **at** discrete values of s **as** in the quadrature method (Eqns. E.16,24). This makes **convergence** easier to **check** because with quadrature, **as** N is increased, the stations **at which** the **function** is given, shift. The only **common** points **from** one value of N to **another are** the **endpoint,** the most difficult to **converge, and** the midpoint which is the easiest. With **collocation either** the same values of s **can** be used **for** successive N values, or the **function can** simply be **evaluated at any** point **according** to Eqn. E.29. I have **found** the **collocation** method to be most **accurate** when N unknowns **and** N equations **are** used **as** opposed to using the before mentioned least squares method. This is similar in principle to **curve fitting.**

For the **edge crack** the technique is similar **except** the singular integral **in** Eqn. E.30 must be solved numerically because **expressions** such **as** Eqn. E.34 **are** not **available** for **a** (l-r) 1/2 **weight.** Kaya [67] has developed **a** scheme which gets **around** this. Instead of normalizing **from** -1 to +1, he normalizes **from** 0 to +1 **as follows,**

- $t = br$, (E.35)
- $x = bs$, (E.36)

$$
\mathbf{v(t)} = \mathbf{b}\mathbf{\bar{v}}(\mathbf{r}) \quad , \tag{E.37}
$$

$$
L(r,s) = b^2 \frac{\partial K}{\partial t} \tag{E.38}
$$

Then Eqn. E.2 becomes,

$$
\int_0^1 \frac{\overline{v}(r)}{(r-s)^2} dr - \int_0^1 \overline{v}(r) L(r,s) dr = \overline{p}(\sigma) , \quad 0 < s < 1 .
$$
 (E.39)

Now we can use

325

$$
\bar{v}(r) = g(r) (1 - r^2)^{1/2} . \tag{E.40}
$$

Also if

 $\pmb{\ell}$.

$$
\int_{-1}^{0} \frac{\bar{v}(r)}{(r-s)^2} dr , \qquad (E.41)
$$

is added and subtracted from Eqn. E.39 we have,

$$
\int_{-1}^{+1} \frac{g(r) (1 - \bar{r}^{2})^{1/2}}{(r-s)^{2}} dr + \int_{0}^{+1} g(r) (1 - r^{2})^{1/2} L(r,s) dr -
$$

$$
\int_{-1}^{0} \frac{g(r) (1 - \bar{r}^{2})^{1/2}}{(r-s)^{2}} dr = \bar{p}(s), \quad 0 < s < 1 . \qquad (E.42)
$$

Now the singular term can be **evaluated** in closed form.

Table E.1 **Coefficients** for expansion functions, $U_{j-1}(r)$ and r^{j-1} for a part-through crack to show convergence for **coefficients** of U for increasing N and to show how power series coefficients get large.

J alj a2j alj a2j

 $\zeta = .6(1-s^2)^{1/4}$, tension.

 $U_{(2j-2)}(r)$ **r** $(2j-2)$

 $N = 10$

Table E.2 Convergence of expansion function **coefficients a. and normalized** stress **intensity** J factor $k_1/(\sigma_2\sqrt{a})$ for a through crack, $a/h=1$, $\nu=.3$

Table E.3 **The effect** of the **choice of** the **collocation points,** s. on **convergence for a** part-3 through **crack lo_ded in tension.**

 $N = 1$

329

APPENDIX F

Short **Crack** Analysis of the **Compliance** Functions

For small ξ (small crack depths) we write,

$$
g_1(\xi) = c_0 + c_{11}\xi + c_{12}\xi^2 + c_{13}\xi^3 + c_{14}\xi^4 + c_{15}\xi^5 + \dots, \quad (F.1)
$$

$$
g_2(\xi) = c_0 + c_{21}\xi + c_{22}\xi^2 + c_{23}\xi^3 + c_{24}\xi^4 + c_{25}\xi^5 + \dots, \quad (F.2)
$$

where

$$
c_{i0} = C_{i0}, C_{10} = C_{20}
$$

\n
$$
c_{i1} = 3/2C_{i0} + C_{i1},
$$

\n
$$
c_{i2} = 15/8C_{i0} + 3/2C_{i1} + C_{i2},
$$

\n
$$
c_{i3} = 35/16C_{i0} + 15/8C_{i1} + 3/2C_{i2} + C_{i3},
$$

\n
$$
c_{i4} = 315/128C_{i0} + 35/16C_{i1} + 15/8C_{i2} + 3/2C_{i3} + C_{i4},
$$

\n
$$
c_{i5} = 693/256C_{i0} + 315/128C_{i1} + 35/16C_{i2} + 15/8C_{i3} + 3/2C_{i4} + C_{i5}.
$$

where C.. axe **listed** in table **C.2.** From Eqn. **2.26,** zj

$$
a_{11} = \pi \Biggl\{ 1/2c_0^2 \xi^2 + 2/3c_0c_{11} \xi^3 + 1/4 \xi^4 [c_{11}^2 + 2c_0c_{12}] + 1/5 \xi^5 [2c_0c_{13} + 2c_{11}c_{12}] + 1/6 \xi^6 [2c_0c_{14} + c_{12}^2 + 2c_{11}c_{13}] + 1/7 \xi^7 [2c_0c_{15} + 2c_{11}c_{14} + 2c_{12}c_{13}] + 0(\xi^8) \Biggr\}, \qquad (F.4)
$$

\n
$$
a_{22} = \pi \Biggl\{ 1/2c_0^2 \xi^2 + 2/3c_0c_{21} \xi^3 + 1/4 \xi^4 [c_{21}^2 + 2c_0c_{22}] + 1/5 \xi^5 [2c_0c_{23} + 2c_{21}c_{22}] + 1/6 \xi^6 [2c_0c_{24} + c_{22}^2 + 2c_{21}c_{23}] + 1/7 \xi^7 [2c_0c_{25} + 2c_{21}c_{24} + 2c_{22}c_{23}] + 0(\xi^8) \Biggr\}, \qquad (F.5)
$$

$$
a_{12} = a_{21} = \pi \Biggl\{ 1/2c_{0}^{2}c^{2} + 1/3\xi^{3}[c_{0}c_{11} + c_{0}c_{21}] + 1/4\xi^{4}[c_{11}c_{21} + c_{0}c_{22} + c_{0}c_{12}] + 1/5\xi^{5}[c_{0}c_{23} + c_{0}c_{13} + c_{11}c_{22} + c_{21}c_{12}] + 1/6\xi^{6}[c_{0}c_{24} + c_{0}c_{14} + c_{11}c_{23} + c_{21}c_{13} + c_{12}c_{22}] + 1/7\xi^{7}[c_{0}c_{25} + c_{0}c_{15} + c_{11}c_{24} + c_{21}c_{14} + c_{12}c_{23} + c_{22}c_{13}]_{r,6}
$$

\nEqn. 2.33 relates $\tau_{i,j}$ to a_{ij} as follows
\n
$$
(1-\nu^{2})\tau_{11} = \pi \Biggl\{ \xi^{-4}1/2c_{0}^{2}\delta_{1} + \xi^{-3}[2/3c_{0}c_{21}\delta_{1} + 1/2c_{0}^{2}\delta_{2}] + \xi^{-2}[1/4(c_{21}^{2} + 2c_{0}c_{22})\delta_{1} + 2/3c_{0}c_{21}\delta_{2} + 1/2c_{0}^{2}\delta_{3}] + \xi^{-1}[2/5(c_{0}c_{23} + c_{21}c_{22})\delta_{1} + 1/4(c_{21}^{2} + 2c_{0}c_{22})\delta_{2} + 2/3c_{0}c_{21}\delta_{3} + 1/2c_{0}^{2}\delta_{4}] + 0(1) \Biggr\}, \quad (F.7)
$$

\n
$$
36(1-\nu^{2})\tau_{22} = \pi \Biggl\{ \xi^{-4}1/2c_{0}^{2}\delta_{1} + \xi^{-3}[2/3c_{0}c_{11}\delta_{1} + 1/2c_{0}^{2}\delta_{2}] + \xi^{-2}[1/4(c_{11}^{2} + 2c_{0}c_{12})\delta_{1} + 2/3c_{0}c_{11}\delta_{2} + 1/2c_{0}^{2}\delta_{3}] +
$$

$$
c_{11}c_{22} + c_{21}c_{12}\delta_1 + 1/4(c_{11}c_{21} + c_0c_{22} + c_0c_{12})\delta_2 +
$$

$$
1/3c_0(c_{11} + c_{21})\delta_3 + 1/2c_0^2\delta_4] + 0(1)
$$
, (F.9)

where

$$
\delta_1 = \frac{1}{\Delta_1},
$$
\n
$$
\delta_2 = -\frac{\Delta_2}{\Delta_1^2},
$$
\n
$$
\delta_3 = \frac{\Delta_2^2 - \Delta_1 \Delta_3}{\Delta_1^3},
$$
\n
$$
\delta_4 = \frac{\Delta_2^3 - 2\Delta_1 \Delta_2 \Delta_3 + \Delta_1^2 \Delta_4}{\Delta_1^4},
$$
\n(F.10)

and

$$
\Delta_{1} = \pi^{2} \Biggl\{ 1/8c_{0}^{2}(c_{21}^{2} + 2c_{0}c_{22} + c_{11}^{2} + 2c_{0}c_{12}) + 4/9c_{0}^{2}c_{11}c_{21} - 1/9c_{0}^{2}(c_{11}c_{21})^{2} - 1/4c_{0}^{2}(c_{11}c_{21} + c_{0}c_{22} + c_{0}c_{12}) \Biggr\},
$$
\n
$$
\Delta_{2} = \pi^{2} \Biggl\{ 1/5c_{0}^{2}(c_{0}c_{13} + c_{11}c_{12} + c_{0}c_{23} + c_{21}c_{22}) - 1/5c_{0}^{2}(c_{0}c_{23} + c_{0}c_{13} + c_{11}c_{22} + c_{21}c_{11}c_{22} + c_{21}c_{11} + 2c_{0}c_{21}c_{12}) - 1/5c_{0}^{2}(c_{0}c_{23} + c_{0}c_{13} + c_{11}c_{22} + c_{21}c_{12}) - 1/6c_{0}(c_{11} + c_{21})(c_{11}c_{21} + c_{0}c_{22} + c_{0}c_{12}) \Biggr\},
$$
\n
$$
\Delta_{3} = \pi^{2} \Biggl\{ 1/12c_{0}^{2}(2c_{0}c_{24} + c_{22}^{2} + 2c_{21}c_{23} + 2c_{0}c_{14} + c_{12}^{2} + 2c_{11}c_{13}) + 4/15c_{0}(c_{0}c_{11}c_{23} + c_{11}c_{21}c_{22} + c_{0}c_{21}c_{13} + c_{21}c_{11}c_{12}) + 1/16(c_{11}^{2} + 2c_{0}c_{12})(c_{21}^{2} + 2c_{0}c_{22}) - 1/6c_{0}^{2}(c_{0}c_{24} + c_{0}c_{14} + c_{21}c_{13} + c_{12}c_{22} + c_{12}c_{12}c_{12} + c_{12}c_{12}c_{12} + c_{12}c_{12}c_{12} + c_{12}
$$

$$
c_{11}c_{23} - 1/16(c_{11}c_{21}+c_{0}c_{22}+c_{0}c_{12})^{2} - 2/15c_{0}(c_{11}+c_{21})(c_{0}c_{23}+c_{0}c_{13}+c_{11}c_{22}+c_{21}c_{12}) ,
$$
\n
$$
\Delta_{4} = \pi^{2}\Big\{2/14c_{0}^{2}(c_{0}c_{25}+c_{21}c_{24}+c_{22}c_{23}+c_{0}c_{15}+c_{11}c_{14}+c_{12}c_{13}) + 1/9c_{0}(2c_{0}c_{11}c_{24}+c_{11}c_{22}+2c_{21}c_{11}c_{23}+2c_{0}c_{21}c_{14}+c_{21}c_{12}^{2}+2c_{11}c_{21}c_{13}) + 1/20(c_{11}^{2}+2c_{0}c_{12})(2c_{0}c_{23}+2c_{21}c_{22}) + 1/20(c_{21}^{2}+2c_{0}c_{22})(2c_{0}c_{13}+2c_{11}c_{12}) - 1/7c_{0}^{2}(c_{0}c_{25}+c_{0}c_{15}+c_{11}c_{24}+c_{21}c_{12}c_{23}+c_{22}c_{13}) - 1/9c_{0}(c_{11}+c_{21})(c_{0}c_{24}+c_{0}c_{14}+c_{11}c_{23}+c_{21}c_{13}+c_{12}c_{22}) - 1/10(c_{11}c_{21}+c_{0}c_{22}+c_{0}c_{12})(c_{0}c_{23}+c_{0}c_{13}+c_{11}c_{22}+c_{21}c_{12})\Big\}.
$$
\n(F.11)

Now **I** have

$$
\gamma_{11} = s_1 \xi^{-4} + s_2 \xi^{-3} + s_3 \xi^{-2} + s_4 \xi^{-1} + 0(1) , \qquad (F.12)
$$

$$
\gamma_{22} = q_1 \xi^{-4} + q_2 \xi^{-3} + q_3 \xi^{-2} + q_4 \xi^{-1} + 0(1) , \qquad (F.13)
$$

$$
\gamma_{12} = \gamma_{21} = t_1 \xi^{-4} + t_2 \xi^{-3} + t_3 \xi^{-2} + t_4 \xi^{-1} + 0(1) , \qquad (F.14)
$$

where s_i , t_i and q_i , i=1,2,3,4 can be obtained from Eqns. F.7-9. Now **consider** the stresses (recall Eqn. **2.31),**

$$
\sigma_1 = u(s)\gamma_{11}(\xi) + \beta(s)\gamma_{12}(\xi) , \qquad (F.15)
$$

$$
\sigma_2 = u(s)\gamma_{21}(\xi) + \beta(s)\gamma_{22}(\xi) , \qquad (F.16)
$$

where for the remaining **analysis,**

$$
\xi = \xi_0 (1 - s^2)^{1/2} \tag{F.17}
$$

I will **also assume** that the **loading** is symmetric in s, so the following expressions for $u(s)$ and $\beta(s)$ are used,

$$
u(s) = (1-s2)1/2 \sum_{j=1}^{N} a_{1j} U_{(2j-2)}(s) , \qquad (F.18)
$$

$$
\beta(s) = (1-s^2)^{1/2} \sum_{j=1}^{N} a_{2j} U_{(2j-2)}(s) .
$$
 (F.19)

For small ξ or for s near 1,

$$
u(s) = \frac{\xi}{\xi_0} \sum_{j=1}^{N} a_{1j} \Big\{ b_j + \xi^2 c_j \Big\} + 0 (\xi^4) , \qquad (F.20)
$$

$$
\beta(s) = \frac{\xi}{\xi_0} \sum_{j=1}^{N} a_{2j} \Big\{ b_j + \xi^2 c_j \Big\} + 0(\xi^4) , \qquad (F.21)
$$

where

$$
b_j = (2j-1) , \t\t (F.22)
$$

$$
c_j = \frac{-4}{\xi_0^2} \sum_{i=1}^{j-1} i^2
$$
 (F.23)

The following expressions result for Eqns. F.15,16,

$$
\sigma_{1}(\xi) = \frac{1}{\xi_{0}} \sum_{j=1}^{N} a_{1j} \left\{ \xi^{-3} b_{j} s_{1} + \xi^{-2} b_{j} s_{2} + \xi^{-1} (b_{j} s_{3} + c_{j} s_{1}) + \frac{1}{\xi_{0}} \sum_{j=1}^{N} a_{2j} \left\{ \xi^{-3} b_{j} t_{1} + \xi^{-2} b_{j} t_{2} + \xi^{-1} (b_{j} t_{3} + c_{j} t_{1}) + \frac{1}{\xi_{0}} \sum_{j=1}^{N} a_{2j} \left\{ \xi^{-3} b_{j} t_{1} + \xi^{-2} b_{j} t_{2} + \xi^{-1} (b_{j} t_{3} + c_{j} t_{1}) + 0 \left(\xi \right), \left(F. 24 \right) \right\}
$$
\n
$$
\sigma_{2}(\xi) = \frac{1}{\xi_{0}} \sum_{j=1}^{N} a_{1j} \left\{ \xi^{-3} b_{j} t_{1} + \xi^{-2} b_{j} t_{2} + \xi^{-1} (b_{j} t_{3} + c_{j} t_{1}) + \frac{1}{\xi_{0}} \sum_{j=1}^{N} a_{j} \left(\xi^{-3} b_{j} t_{1} + \xi^{-2} b_{j} t_{2} + \xi^{-1} (b_{j} t_{3} + c_{j} t_{1}) + \frac{1}{\xi_{0}} \sum_{j=1}^{N} a_{j} \left(\xi^{-3} b_{j} t_{1} + \xi^{-2} b_{j} t_{2} + \xi^{-1} (b_{j} t_{3} + c_{j} t_{1}) \right) \right\}
$$

$$
(b_jt_4 + c_jt_2) \ + \frac{1}{\xi_0} \sum_{j=1}^N a_{2j} \Big\{ \xi^{-3}b_jq_1 + \xi^{-2}b_jq_2 + \xi^{-1}(b_jq_3 + c_jq_1) + (b_jq_4 + c_jq_2) \Big\} + 0(\xi)
$$
 (F.25)

Using the prediction of **Chapter 2** that the **stresses** must have **a square** root singularity at the ends, i.e. ξ^{-1} , we must have,

$$
\frac{1}{\xi_0} \sum_{j=1}^{N} a_{1j} \left\{ \xi^{-3} b_j s_1 + \xi^{-2} b_j s_2 \right\} + \frac{1}{\xi_0} \sum_{j=1}^{N} a_{2j} \left\{ \xi^{-3} b_j t_1 + \xi^{-2} b_j t_2 \right\} = 0 , \qquad (F.26)
$$
\n
$$
\frac{1}{\xi_0} \sum_{j=1}^{N} a_{1j} \left\{ \xi^{-3} b_j t_1 + \xi^{-2} b_j t_2 \right\} + \frac{1}{\xi_0} \sum_{j=1}^{N} a_{2j} \left\{ \xi^{-3} b_j q_1 + \xi^{-2} b_j q_2 \right\} = 0 , \qquad (F.27)
$$

which is true if

$$
\sum_{j=1}^{N} a_{1j} b_j = 0 , \qquad (F.28)
$$

and

$$
\sum_{j=1}^{N} a_{2j} b_j = 0 \t\t (F.29)
$$

This is **equivalent** to saying that the through **crack** stress intensity factor is zero, because

$$
\frac{k_1}{\sigma\sqrt{a}} \alpha \sum_{j=1}^{N} a_{ij} b_j, i=1,2
$$
 (F.30)

APPENDIX ¢

Stress Intensity Factors

G.1 Elasticity Theory.

The study of the static stress distribution **near** the tip of a **crack** in a linear, **elastic** solid has been **reduced** to the determination **of constants called** stress intensity factors (see Irwin [68,69]). **To** illustrate this **consider** the two-dimensional **plane** geometry **where** Williams [4] and Sih [80] have given the asymptotic form of the stresses of in-plane and anti-plane loading, respectively. These solutions, presented below, are obtained by use of **eigenfunction expansions which** satisfy the **crack** surface boundary **conditions.** The **coordinate** system is **chosen** to duplicate the through **crack** geometry used in this dissertation **where** the **crack** lies in the yz-plane **with** z tangent to the crack front. The polar coordinates r, θ are measured from the **crack** tip and lie in the xy-plane.

$$
\sigma_{y} \approx \frac{k_{1}}{\sqrt{2r}} \cos \frac{\theta}{2} \left[1 - \sin \frac{\theta}{2} \sin \frac{3\theta}{2} \right] - \frac{k_{2}}{\sqrt{2r}} \sin \frac{\theta}{2} \left[2 + \cos \frac{\theta}{2} \cos \frac{3\theta}{2} \right] + \sum_{n=1}^{\infty} \left[b_{1n} r^{\frac{2n-1}{2}} f_{1n}(\theta) + b_{2n} r^{n} f_{2n}(\theta) \right],
$$
\n
$$
\sigma_{x} \approx \frac{k_{1}}{\sqrt{2r}} \cos \frac{\theta}{2} \left[1 + \sin \frac{\theta}{2} \sin \frac{3\theta}{2} \right] + \frac{k_{2}}{\sqrt{2r}} \sin \frac{\theta}{2} \cos \frac{\theta}{2} \cos \frac{3\theta}{2} + \sigma_{0x} + \sum_{n=1}^{\infty} \left[b_{3n} r^{\frac{2n-1}{2}} f_{3n}(\theta) + b_{4n} r^{n} f_{4n}(\theta) \right],
$$
\n(6.2)

$$
\sigma_{z} \simeq 2\nu \left[\frac{k_{1}}{\sqrt{2r}} \cos \frac{\theta}{2} - \frac{k_{2}}{\sqrt{2r}} \sin \frac{\theta}{2} \right] + \nu \sigma_{0x} + \sum_{n=1}^{\infty} \left[b_{5n} r^{\frac{2n-1}{2}} f_{5n}(\theta) + b_{6n} r^{n} f_{6n}(\theta) \right],
$$
\n(6.3)
\n
$$
\tau_{xy} \simeq \frac{k_{1}}{\sqrt{2r}} \sin \frac{\theta}{2} \cos \frac{\theta}{2} \cos \frac{3\theta}{2} + \frac{k_{2}}{\sqrt{2r}} \cos \frac{\theta}{2} [1 - \sin \frac{\theta}{2} \sin \frac{3\theta}{2}] + \sum_{n=1}^{\infty} \left[b_{7n} r^{\frac{2n-1}{2}} f_{7n}(\theta) + b_{8n} r^{n} f_{8n}(\theta) \right],
$$
\n(6.4)

$$
\tau_{yz} \simeq \frac{k_3}{\sqrt{2r}} \sin{\frac{\theta}{2}} + \sum_{n=1}^{\infty} \left[b_{9n} r^{\frac{2n-1}{2}} f_{9n}(\theta) + b_{10n} r^n f_{10n}(\theta) \right], \qquad (G.5)
$$

$$
\tau_{xz} \approx \frac{k_3}{\sqrt{2r}} \cos{\frac{\theta}{2}} + \sum_{n=1}^{\infty} \left[b_{11n} r^{\frac{2n-1}{2}} f_{11n}(\theta) + b_{12n} r^n f_{12n}(\theta) \right] \ . \tag{G.6}
$$

The stress intensity factors are kl, k 2, and k3 which **correspond** to the **opening (symmetric), sliding (skew-symmetric) and** tearing **(anti**plane) **modes of fracture shown** in **figure ft.1.** Equations similar to **G..1-6 exist** for **displacement as follows,**

$$
v(r,\theta) \approx \frac{k_1}{8\mu} \sqrt{2r} \left[(2\kappa - 1) \cos\frac{\theta}{2} - \cos\frac{3\theta}{2} \right]
$$

+
$$
\frac{k_2}{8\mu} \sqrt{2r} \left[(2\kappa + 3) \sin\frac{\theta}{2} + \sin\frac{3\theta}{2} \right],
$$
 (G.7)

$$
u(r,\theta) \approx \frac{k_1}{8\mu} \sqrt{2r} \left[(2\kappa + 1) \sin\frac{\theta}{2} - \sin\frac{3\theta}{2} \right]
$$

-
$$
\frac{k_2}{8\mu} \sqrt{2r} \left[(2\kappa - 3) \cos\frac{\theta}{2} + \cos\frac{3\theta}{2} \right],
$$
 (G.8)

337

$$
w(r,\theta) \approx \frac{k_3}{\mu} \sqrt{2r} \sin \frac{\theta}{2} \quad , \tag{G.9}
$$

where μ is the shear modulus, ν is Poisson's ratio, and $\kappa=4-3\nu$ for plane strain and $\kappa = (3-\nu)/(1+\nu)$ for plane stress. Clearly the stress intensity **factors play** the important role in the **expansion** near the **crack** tip **and** have been shown to **play an** important role in **fracture** [68] or more recently [70].

The singular terms in the stresses have **also** been shown to apply to geometries other than plane strain. Irwin [68] examined Sneddon's solution [81] of **a circular** shaped crack in an infinite solid under mode 1 loading and found that **in** a plane normal to the crack front the definition of k_1 is the same as for the straight crack front of plane **strain.** Since then Kassir **and** Sih [82] have proven this to apply **for** a plane elliptical crack under general, or mixed-mode loading **conditions.** It may be assumed that this result will hold for **any** plane crack with a smooth crack front, see Ref. [83].

From Eqns. G.1-9 **we** define the stress intensity factors in terms of stress and disp]acement below.

$$
k_1 = \frac{\lim_{y \to b} \sqrt{2(y-b)}}{\sigma_x(0, y, z)},
$$
 (G.10)

$$
= \frac{2\mu}{\kappa+1} \lim_{y \to b} \frac{1}{\sqrt{2(y-b)}} \left[u(0^+, y, z) - u(0^-, y, z) \right], \qquad (0.11)
$$

$$
k_2 = \lim_{y \to b} \sqrt{2(y-b)} \tau_{xy}(0, y, z) , \qquad (G.12)
$$

$$
= \frac{2\mu}{\kappa+1} \lim_{y \to b} \frac{1}{\sqrt{2(y-b)}} \left[v(0^+, y, z) - v(0^-, y, z) \right], \qquad (G.13)
$$

$$
k_3 = \lim_{y \to b} \sqrt{2(y-b)} \tau_{yz}(0,y,z) , \qquad (G.14)
$$

338

$$
= \frac{\mu}{2} \lim_{y \to b} \frac{1}{\sqrt{2(y-b)}} \left[\omega(0^+, y, z) - \omega(0^-, y, z) \right].
$$
 (G.15)

These **expressions are** not valid **at** the point **where** a **crack** front meets **a** free surface. Benthem [1] has found that the stress singularity **at** this point is dependent on Polsson's ratio **and** is not **equal** to .5. The values **for** the order of the singularity **are** given in table G.1. and **3** it is greater than .5. In most theoretical work a singularit of **.5** [33]. **G.I.** For mode 1 the **exponent is** less **than .5 and for** modes 2 is **assumed along** the **entire crack** front, see **for example** Ref.

G.2 Plate and Shell Theory.

The typical **expression for stress resultants** in **either plates or** shells is of the non-dimensional **form**

$$
F_{i}(0,y) = \frac{c_{i}}{\pi} \int_{a}^{b} \frac{u_{i}(t)}{(t-y)^{2}} dt + 0(1) , y \langle a, b \langle y, i=1,...,5 , (G.16)
$$

from which the singular integral **equations are** obtained

$$
-\mathbf{F}_{k}\delta_{ik} = \frac{c_{i}}{\pi} \int_{a}^{b} \frac{u_{i}(t)}{(t-y)^{2}} dt +
$$

$$
\sum_{j=1}^{5} \int_{a}^{b} u_{j}(t)K_{ij}(y,t) dt, \quad a \leq y \leq b, \quad i=1,...,5, \quad (G.17)
$$

where k **corresponds** to the loading **where 6ik** is **zero for i_k and** one **for i=k.** "a" represents the dimensional **form, and "b**I the non-dimensional. F_i , c_i , and u_i are defined in the following equations where

{ F } = { N₁₁/hE, M₁₁/h²E, V₁12(1+
$$
\nu
$$
)/5hE, N₁₂/hE, M₁₂/h²E }

$$
= \{ N_{xx}, M_{xx}, V_x, N_{xy}, M_{xy} \} , \qquad (G.18a,b)
$$

$$
\{ N_{11}, M_{11}, V_1, N_{12}, M_{12} \} =
$$

$$
\{ h\sigma_{1D}, h^2/(6)\sigma_{2D}, 2h/(3)\sigma_{3D}, h\sigma_{4D}, h^2/(6)\sigma_{5D} \}
$$

$$
\{ N_{xx}, M_{xx}, V_x, N_{xy}, M_{xy} \} =
$$

$$
\{ \sigma_1, \sigma_2/6, \sigma_3 8(1+\nu)/5, \sigma_4, \sigma_5/6 \} , \qquad (G.19a,b)
$$

$$
\sigma_{i} = \sigma_{iD}/E \quad , \tag{G.20}
$$

$$
\{ c \} = \{ 1/2, 1/24, 1, 1/2, 1/24 \}, \qquad (G.21)
$$

$$
\{ u \} = \{ u_x/h, \beta_x, u_z/h, u_y/h, \beta_y \}
$$

= $\{ u_1, u_2, u_3, u_4, u_5 \}$, (G.22a,b)

with only one exception **for** the she11,

$$
u_y(t) = hu_4(t) + (\lambda_2/\lambda)^2 tu_3(t)
$$
, (G.23)

where λ_2 and λ are shell parameters defined in Appendix A. To obtain the stress **intensity** factors (both **primary and** secondary) **from G.17** using G.10-15 we first convert G.17 to

$$
-1/P_k \delta_{ik} = \frac{1}{\pi} \int_{-1}^{+1} \frac{f_i(r) (1-t^2)^{1/2}}{(r-s)^2} dr
$$

+
$$
\sum_{j=1}^{5} \frac{1}{c_j} \int_{-1}^{+1} f_j(r) (1-r^2)^{1/2} L_{ij}(s,r) dr , -1 \leq 1, i=1,...,5 , (G.24)
$$

where

$$
t = \frac{b-a}{2} r + \frac{b+a}{2} , y = \frac{b-a}{2} s + \frac{b+a}{2} ,
$$
 (G.25)

$$
L_{ij}(s,r) = ((b-a)/2)^{2}K_{ij}(y,t) , \qquad (G.26)
$$

$$
u_{j}(t) = (b-t)^{1/2} (t-a)^{1/2} g_{j}(t)
$$

$$
= \frac{b-a}{2} \overline{g}_{j}(r) (1-r^{2})^{1/2}
$$

$$
= \frac{1}{c_{j}} \frac{a}{g_{k}} \frac{b-a}{2} f_{j}(r) (1-r^{2})^{1/2}, \qquad (6.27)
$$

$$
\sigma_k = P_k F_k \tag{G.28}
$$

$$
\{ P \} = \{ 1, 6, 5/(8(1+\nu)), 1, 6 \}.
$$
 (G.29)

To calculate stress intensity **factors** we **require** the three-dimensional stress in **dimensional** form. From Eqn. G.16 with substitutions from G.25-27,

$$
\frac{\overline{F}_{i}(0,s)}{\sigma_{k}} = \frac{1}{\pi} \int_{-1}^{+1} \frac{f_{i}(r) (1-t^{2})^{1/2}}{(r-s)^{2}} dr + 0(1) , i=1,...,5 .
$$
 (G.30)

From Eqn. G.28, **using G.25** to convert **functions of y** to **s** denoted as such by a bar, we **obtain,**

$$
\frac{\overline{\sigma}_{i}(0,s)}{\sigma_{k}} = \frac{\overline{F}_{i}(0,s)}{\sigma_{k}} P_{i} \qquad (G.31)
$$

In terms of this stress **ratio,** (dimensional and non-dimensional are **equivalent,** see Eqn. G.20), the **stress expressions needed** for Eqns. G.10,12,14 are,

$$
\sigma_{\mathbf{x}}(0, \mathbf{y}, \mathbf{z}) = \sigma_{\mathbf{k}D} h_1(\mathbf{z}) \left(\frac{\overline{\sigma}_1(0, \mathbf{s})}{\sigma_{\mathbf{k}}} \right) \text{ for tension, (mode 1),}
$$

$$
= \sigma_{\mathbf{k}D} h_2(\mathbf{z}) \left(\frac{\overline{\sigma}_2(0, \mathbf{s})}{\sigma_{\mathbf{k}}} \right) \text{ for bending, (mode 1),}
$$

$$
\tau_{yz}(0,y,z) = \frac{\omega}{\sigma_{kD}} h_3(z) \left[\frac{\bar{\sigma}_3(0,s)}{\frac{\omega}{\sigma_k}} \right] \text{ for out-of-plane shear, (mode 3),}
$$

$$
\tau_{xy}(0,y,z) = \frac{\omega}{\sigma_{k0}} h_4(z) \left[\frac{\sigma_4(0,s)}{\sigma_k} \right] \text{ for in-plane shear, } \text{(mode 2),}
$$

 $= \sigma_{kD}$ h₅(z) $\frac{1}{\sigma_{k}}$ for **twisting,** (mode **2),** (G,32)

where $h_i(z)$ are

$$
\{ h_1(z), h_2(z), h_3(z), h_4(z), h_5(z) \} =
$$

= { 1, 2z/h, [1-(2z/h)²], 1, 2z/h } (G.33)

Next **we** use the **following** result **from** the **asymptotic analysis** of singular integrals,

$$
\lim_{s \to 1} \frac{1}{\pi} \int_{-1}^{+1} \frac{f_i(r) (1-t^2)^{1/2}}{(r-s)^2} dr \sim \lim_{s \to 1} \frac{f_i(s)}{\sqrt{2(s-1)}} + 0(1), |s| > 1. \quad (G.34)
$$

From Eqns. G.I0,12,14 **we can write**

$$
k_{j} = \frac{\lim_{y \to b} \sqrt{2(y-b)} \sigma(0, y, z) .
$$
 (G.35)

which becomes after using G.25,30,31,32,34,

$$
k_{j} = \frac{\lim_{s \to 1} \left(\frac{b-a}{2}\right)^{1/2} \sqrt{2(s-1)}}{\sigma_{kD} h_{i}(z) P_{i} \frac{f_{i}(s)}{\sqrt{2(s-1)}}},
$$
 (G.36)

$$
= \left(\frac{b-a}{2}\right)^{1/2} \sigma_{kD}^{b}{}_{i}(z) P_{i} f_{i}(1) \quad , \tag{G.37}
$$

where $j=1$ for $i=1,2$, $j=2$ for $i=4,5$ and $j=3$ for $i=3$. Because the functional z dependence is known for each of the loading cases, it i sufficient to use the maximum value of h_i(z) which is one. Aft

normalizing,

$$
\frac{k_{j}}{\sigma_{kD} \left(\frac{b-a}{2}\right)^{1/2}} = P_{i} f_{i}(1) , \qquad (G.38)
$$

for the crack tip **at y=b and similarly** for **y=a**

$$
\frac{k_{j}}{\sigma_{kD} \left(\frac{b-a}{2}\right)^{1/2}} = P_{i} f_{i}(-1) \quad . \tag{G.39}
$$

In solving the integral equation, the function $f_i(r)$ is determined on the interval -1SrS1. It is therefore a simple matter to **determine** the **value** at the **endpoints** for **substitution** into **G.38,39.**

Next the **stress** intensity **factors will** be **calculated** in terms **of** the displacement. From Eqns. G.19a,b

$$
u(0,y,z) = hu_1(0,y) + (2z/h)h/2u_2(0,y),
$$

$$
v(0,y,z) = hu_4(0,y) + (2z/h)h/2u_5(0,y).
$$
 (G.40)

The expression for the **out-of-plane displacement** w, is **not known as a** function of z and will be **dealt** with later. **For modes** 1 and 2 we proceed as follows. Eqn. G.27 is substituted into the above displacement **expressions and** then Eqns. **G.II,13,15 are** used to write,

$$
k_{j} = \frac{hE}{\gamma_{j}\delta_{i}} \lim_{y \to b} \frac{1}{\sqrt{2(y-b)}} h_{i}(z) \frac{1}{c_{i}} \frac{\omega_{i}}{\delta_{k}} \frac{b-a}{2h} f_{i}(s) \sqrt{1-s^{2}}
$$

$$
= \frac{h_{i}(z)\frac{\omega_{i}}{\delta_{i}c_{i}}}{\gamma_{j}\delta_{i}c_{i}} \left(\frac{b-a}{2}\right)^{1/2} f_{i}(1) , \quad i \neq 3 , \qquad (G.41)
$$

where

$$
u_{i} = u_{i}^{+} = -u_{i}^{-}
$$
, $2\mu = \frac{E}{1+\nu}$, $\kappa = \frac{3-\nu}{1+\nu}$,

343

$$
\gamma_j = 2
$$
, j=1,2 (i.e. i=1,2,4,5), $\gamma_3 = 2(1+\nu)$,
\n $\delta_i = 1$, i=1,3,4 and $\delta_i = 2$, i=2,5. (G.42)

Therefore the **normalized** stress intensity factors calculated from displacement **are,**

$$
\frac{k_{\mathbf{j}}}{\sigma_{k}(\frac{b-a}{2})^{1/2}} = \frac{f_{\mathbf{i}}(1)}{\gamma_{\mathbf{j}}\delta_{\mathbf{i}}c_{\mathbf{i}}}
$$
 (G.43)

and

$$
\frac{k_{\mathbf{j}}}{\sigma_{k0} \left(\frac{b-a}{2}\right)^{1/2}} = \frac{f_{\mathbf{j}}(-1)}{\gamma_{\mathbf{j}} \delta_{\mathbf{i}} c_{\mathbf{j}}} \quad . \tag{G.44}
$$

From Eqns. G.38,39 **and 43,44** we **should have,**

$$
1/P_{i} = \gamma_{j} \delta_{i} c_{i} \qquad (G.45)
$$

First note that **if** the **primary stress intensity factors for** both stress and displacement **are** the same, the secondary SIFs will **also** be. **The four cases** (i=1,2,4,5), **are** shown below to be **equivalent when defined in** terms of stress **or displacement** indicating **a compatibility** between this plate theory, which includes transverse shear deformation, and **elasticity** theory for modes 1 and 2:

$$
\begin{aligned}\n\frac{\mathbf{i} = 1}{\mathbf{1} \mathbf{1}} \cdot \mathbf{1} & \mathbf{1} \mathbf{1} = 1 \\
\mathbf{1} & \mathbf{1} \cdot \mathbf{1} \mathbf{1} = (2)(1)(1/2) = 1, \\
\frac{\mathbf{i} = 2}{\mathbf{1} \mathbf{1}} \cdot \mathbf{1} & \mathbf{1} \mathbf{1} \mathbf{1} = 1/6 \\
\mathbf{1} \cdot \mathbf{1} \cdot \mathbf{1} \cdot \mathbf{1} \cdot \mathbf{1} \cdot \mathbf{1} & \mathbf{1} \cdot \mathbf{1} \cdot \mathbf{1} \cdot \mathbf{1} & \mathbf{1} \cdot \mathbf{1} \cdot \mathbf{1} \cdot \mathbf{1} \\
\frac{\mathbf{i} = 4}{\mathbf{1} \mathbf{1}} \cdot \mathbf{1} \cdot \mathbf{1} \cdot \mathbf{1} \cdot \mathbf{1} & \mathbf{1} \cdot \mathbf{1}
$$

$$
\gamma_2 \delta_4 c_4 = (2) (1) (1/2) = 1 , \qquad (G.48)
$$

i=5, $1/P_5 = 1/6$

$$
\gamma_2 \delta_5 c_5 = (2) (2) (1/24) = 1/6 . \qquad (G.49)
$$

3 loading, there is a problem. The displacement plate variable u_z, is As mentioned above, for out-of-plane shear which **represents** mode an average quantity defined **in** terms of the actual displacement w as follows, **see Timoshenko [84],**

$$
u_{z}(x,y) = \frac{3}{2h} \int_{-h/2}^{h/2} w(x,y,z) \left[1 - (2z/h)^{2}\right] dz
$$
 (G.50)

The z dependence **of uz cannot be determined** because of the **plate** assumption concerning $\epsilon_{\mathbf{z}}$, i.e. $\sigma_{\mathbf{z}} = 0$. Therefore the stress intensity factor **cannot** be **defined** in terms **of displacement.** It **can** only be shown that the stress intensity factor **obtained** from **uz is equal** to the **weighted** average using G.50.

First **assume that** the **actual** out-of-plane **displacement can** be expressed **as,**

$$
w(x,y,z) \sim \bar{w}(x,y) = hu_z(x,y) . \qquad (G.51)
$$

Then by **an analysis** similar to that used **for** i=l **and 4 above)**

$$
\frac{k_{3avg}}{\sigma_{k0} \left(\frac{b-a}{2}\right)^{1/2}} = \frac{f_3(1)}{7_3 \delta_3 c_3} = \frac{f_3(1)}{2(1+\nu)} \quad . \tag{G.52}
$$

The stress intensity **factor from** stress is given by G.37 to be,

$$
\frac{k_3(z)}{\sigma_{kD} \left(\frac{b-a}{2}\right)^{1/2}} = \frac{5f_3(1)}{8(1+\nu)} \left[1 - (2z/h)^2\right] \quad . \tag{G.53}
$$

345

When this is substituted into Eqn. G.SO, we obtain,

$$
k_{3avg} = \frac{3}{2h} \int_{-h/2}^{+h/2} k_3(z) \left[1 - (2z/h)^2 \right] dz ,
$$

$$
= \left(\frac{b-a}{2} \right)^{1/2} \frac{1}{\sigma} \int_{h/2}^{h/2} k_1 \sigma_1^2 \left(1 + \nu \right) ,
$$
 (G.54)

which is the same as predicted by Eqn. G.52.

The shell displacement **component of** Eqn. **G.23** also is **only** known **as** an average quantity because of its association with u_z . Here

$$
v(0,y,z) = hu_4(0,y) + (\lambda_2/\lambda)^2 (y/h) hu_3(0,y) + (2z/h) h/2u_5(0,y)
$$
 (G.55)

Again only in the **average** sense does this form **comply with** the theory of elasticity so stress is used for the SIF **calculation.**

It should be noted that **a** stress singularity of .5 is assumed at the free surface for all fracture modes. In mode 3 the parabolic shear assumption forces k**3 equal** to **zero at** the plate surface **When** in fact Benthem [1] predicts it to be infinite. However the surface **effects are** not believed to greatly influence the value of the SIF away from the surface **and** in most **work** a singularity of .5 is **assumed,** see for **example** Refs. [33,43].

Table G.I **Strength of** stress singularity for the intersection of a straight crack front **with** a **free** surface in a half-space, Refs. [1,85].

 \mathbb{R}^2

APPENDIX B

Thin Plate Bending Limit of Fredholm Kernel

We **consider** the behavior **of** the Fredholm **kernel of** Eqn. **3.130 for a/h approaching infinity. Define**

$$
I(y, a/h) = \frac{5}{\pi (1+\nu)} (a/h)^2 \int_{-1}^{+1} K(z)g(t) dt , \qquad (H.1)
$$

where

$$
K(z) = \frac{-48}{z^4} + \frac{4}{z^2} - 4K_0(z) + 4K_2(z) + \frac{24}{z^2}K_2(z) , \qquad (H.2)
$$

$$
z = \rho |t-y| \quad , \quad \rho = (10)^{1/2} (a/h) = \beta (a/h) \quad . \tag{H.3}
$$

First consider the limit **for** y **outside** of the **crack.** This **case** is simple because **as a/h** gets large, **z** gets large. The only **contribution** from $K(z)$ comes from the $4/z^2$ term. For $|y|>1$,

$$
\lim_{a/h \to \infty} I(y, a/h) = \frac{2}{\pi(1+\nu)} \int_{-1}^{+1} \frac{g(t)}{(t-y)^2} dt . \qquad (H.4)
$$

For y inside of the **crack** domain the **variable** z **can** be **of** order **one** at t near y so it is not **clear** that these terms are negligible even for large a/h . Rewrite $I(y, a/h)$ as follows,

$$
I(y,a/h) = \frac{5(a/h)^2}{\pi(1+\nu)} \int_{-1}^{1} K(z)g(t) dt = \frac{\rho^2}{2\pi(1+\nu)} \int_{-1}^{1} K(z)g(t) dt , (H.5)
$$

$$
= \frac{\rho^2}{2\pi(1+\nu)} \left\{ \int_{-1}^{y} K(z)g(t) dt + \int_{y}^{+1} K(z)g(t) dt \right\} , \qquad (H.6)
$$

$$
= \frac{\rho}{2\pi(1+\nu)} \left\{ \int_0^{\rho(1+y)} K(u)g(y-u/\rho) \, du + \int_0^{\rho(1-y)} K(u)g(y+u/\rho) \, du \right\}_{(H.7)}
$$

$$
-\frac{\rho}{2\pi(1+\nu)}\left\{\int_{\rho(1-y)}^{\rho(1+y)}K(u)g(y-u/\rho) du + \int_{0}^{\rho(1-y)}K(u)[g(y+u/\rho)+g(y-u/\rho)] du \right\}
$$
 (H.8)

Next write Taylor **expansions** for g(t) as follows,

$$
g(y-u/\rho) = \sum_{n=0}^{\infty} (-1)^n \frac{1}{n!} (u/\rho)^n g^n(y) , \qquad (H.9)
$$

$$
g(y+u/\rho) = \sum_{n=0}^{\infty} \frac{1}{n!} (u/\rho)^n g^n(y) , \qquad (H.10)
$$

where $g^{n}(y)$ denotes the nth derivative of $g(y)$. These expressions are substituted into the second integral **of** Eqn. **H.8.** Because **of** symmetry only y>O will be considered. After rewriting the first integral using a simple substitution, Eqn. H.8 becomes,

$$
I(y, a/h) = \frac{\rho^2}{2\pi (1+\nu)} \int_{-1}^{-1+2y} K[\rho(y-t)]g(t) dt + \frac{\rho}{\pi (1+\nu)} \sum_{n=0}^{\infty} \frac{1}{(2n)!} g^{2n}(y) \rho^{-2n} \int_{0}^{\rho (1-y)} u^{2n}K(u) du
$$
 (H.11)

Now **consider** the limit of these two terms separately. Since the first integral is not singular for $y \le 1$, as ρ gets large all terms of K(z) go to **zero** except the **4/z** 2 *term.* Therefore **we** have,

$$
\lim_{a/h \to \infty} \frac{\rho^2}{2\pi (1+\nu)} \int_{-1}^{-1+2y} K[\rho(y-t)]g(t) dt = \frac{2}{\pi (1+\nu)} \int_{-1}^{-1+2y} \frac{g(t)}{(t-y)^2} dt
$$
 (H.12)

Now for the second integral of Eqn. **H.II.** For large u

$$
K_n(u) \sim [\pi/(2u)]^{1/2} e^{-u} (1 + \alpha/u + \dots) , \qquad (H.13)
$$

where $K_n(u)$ is a Bessel function and a is a constant. The important

feature is the exponential decay. It can be shown that,

$$
\int_{u}^{\infty} \frac{u^{n}}{\sqrt{u}} e^{-u} du \sim e^{-u} . \qquad (H.14)
$$

Now divide the second **integral** in Eqn. **H.11** into two integrals,

$$
\int_0^{\rho(1-y)} u^{2n} K(u) \, du = \int_0^{\epsilon} u^{2n} K(u) \, du + \int_{\epsilon}^{\rho(1-y)} u^{2n} K(u) \, du \quad , \qquad (H.15)
$$

where ϵ is sufficiently large such that the exponentially decaying Bessel **functions** may be **neglected** when integrated **from** 6 to **infinity,** (here we assume that $\epsilon \langle \rho(1-y) \rangle$. The first term in the series, $(n=0)$ requires special treatment.

$$
\int_{0}^{\rho(1-y)} K(u) \, du = \int_{0}^{\infty} K(u) \, du - \int_{\rho(1-y)}^{\infty} K(u) \, du \qquad (H.16)
$$

where

$$
\int_{0}^{\infty} K(u) \, du = \left[\frac{-16}{u^3} + \frac{4}{u} + \frac{8}{u} K_2(u) \right]_{0}^{\infty} = 0 \quad . \tag{H.17}
$$

Now we **make** use of Eqn. **11.14** to **evaluate**

$$
\int_{\rho(1-y)}^{\infty} K(u) \, du \simeq \int_{\rho(1-y)}^{\infty} (4/u^2) \, du \simeq \frac{4}{\rho(1-y)}, \qquad (H.18)
$$

to leading order. The second integral in Eqn. H.15 for $n\geq 1$ including the coefficient of ρ^{-2n} from Eqn. H.11 becomes,

$$
\rho^{-2n} \int_{\epsilon}^{\rho(1-y)} 2n_K(u) \, \mathrm{d}u \simeq \rho^{-2n} \int_{\epsilon}^{\rho(1-y)} 2n_{(4/u^2)} \, \mathrm{d}u \simeq
$$
\n
$$
\frac{4}{2n-1} \left\{ \frac{1}{\rho} (1-y)^{2n-1} - \epsilon^{2n-1} / \rho^{2n} \right\} \simeq \frac{4}{2n-1} \frac{1}{\rho} (1-y)^{2n-1} \qquad (H.19)
$$

Now for the first integral in Eqn. H.15. For $n\geq 1$ this integral with the ρ^{-2n} coefficient from Eqn. H.11 is,
$$
\rho^{-2n} \int_0^{\epsilon} u^{2n} K(u) \, du < 0 \, (\rho^{-1}) \tag{H.20}
$$

In the limit as ρ gets large, this term will not have an order one contribution to $I(y, a/h)$ because $\epsilon \langle \langle \rho \rangle$ and therefore it is neglected.

Now we substitute Eqns. **H.12,16,18,19,20** into **H.11** and obtain,

$$
\lim_{a/h \to \infty} \mathcal{L}(y, a/h) = \frac{2}{\pi (1+\nu)} \left\{ \int_{-1}^{-1+2y} g(t) dt + \frac{-2}{1-y} g(y) + 2 \sum_{n=1}^{\infty} \frac{1}{(2n)!} g^{2n}(y) \frac{(1-y)^{2n-1}}{2n-1} \right\} . \tag{H.21}
$$

Now look at the first integral of Eqn. **H.21.**

$$
\int_{-1}^{-1+2y} \frac{g(t)}{(t-y)^2} dt = \oint_{-1}^{+1} \frac{g(t)}{(t-y)^2} dt - \oint_{1}^{-1+2y} \frac{g(t)}{(t-y)^2} dt . \qquad (H.22)
$$

Substitute the expansion,

$$
g(t) = \sum_{n=0}^{\infty} (-1)^n \frac{1}{n!} (t-y)^n g^n(y) , \qquad (H.23)
$$

into the second **integral** of H.22 **and after** some **algebra,**

$$
\int_{1}^{-1+2y} \frac{g(t)}{(t-y)^{2}} dt = \int_{1}^{-1+2y} \sum_{n=0}^{\infty} (-1)^{n} \frac{1}{n!} (t-y)^{n-2} g^{n}(y) dt =
$$

= $-2 \sum_{n=0}^{\infty} \frac{1}{(2n)!} g^{2n}(y) \frac{(1-y)^{2n-1}}{2n-1}$ (H.24)

When this is combined with Eqns. **H.21** and 22 we obtain,

$$
\frac{\text{limit}}{\text{a/h+}\infty} I(y, \text{a/h}) = \frac{2}{\pi (1+\nu)} \oint_{+1}^{-1} \frac{g(t)}{(t-y)^2} dt , \qquad (H.25)
$$

which is perhaps the expected result considering Eqn. n.4. The reasonal for **going** through this **algebra (and** there is probably **a** better **way),** is to show that this derivation fails for y sufficiently close to **one.** Eqns. H.12,18 **and** 19 are valid only for,

$$
\frac{1}{\rho(1-y)} = o(1) \quad . \tag{H.26}
$$

In the limit as ρ goes to infinity, the quantity $(1-y)$ must be such that the product $\rho(1-y)$ still goes to infinity. Otherwise Eqn. H.25 is **not valid.** For more **information,** see **Chapter 3.**

ź.

APPENDIX I

Log integrals

The **major expense** in solving **an** integral **equation** on the **computer** is in the **evaluation and** the integration **of** the **Fredholm kernels.** In the **shell problem** for **each point used** to integrate the **Fredholm kernel an** infinite integral must be **determined. The plate kernels are known** in **closed form** but involve **evaluation of Bessel functions.**

Log integrals **and** integrals **of** the form,

$$
\int_{-1}^{+1} (t-y)^n \ln|t-y| (1-t^2)^{1/2} dt , -1 \langle y \langle +1 , (1,1) \rangle
$$

which **appear** in both the **plate and** the shell **equations, (and in many other** problems) may be the **determining factor** for **convergence-of** the integration **of** the **Fredholm kernels.** Gauss-Chebychev integration **(see Eqns. E.31-33)** is **used** to **show this difficulty for small n** in *table* **1.1.** The **number of points used** to **integrate** Eqn. 1.1 is **N. The closed form expression used** may be **found** in **Appendix** A. The **value of** y **does not** have **a significant effect** on these **results. Because** of this **slow** convergence **log** *terms* were separated from the **kernels for** n_3 with the **option of** doing *them* in closed **form.** The following asymptotic analysis of the log terms for $z = \beta(t-y)$ approaching zero is given for the plate kernels where the subscripts 2,3 **and** 5 respectively correspond to bending (M_{xx}) , out-of-plane shear (V_x) , and twisting (M_{xy}) .

$$
K_{22}(z) \sim \frac{1}{\kappa} \ln(z) + c_1 + \frac{1}{\kappa} \left(\frac{z}{2}\right)^2 \ln(z) + 0(z^4 \ln(z)) , \qquad (I.2)
$$

$$
K_{33}(z) \sim -\beta^2 \ln(z) + c_2 - \frac{3}{2} \beta^2 (\frac{z}{2})^2 \ln(z) + O(z^4 \ln(z)) \quad , \quad (1.3)
$$

$$
K_{35}(z) \sim -\beta(\frac{z}{2})\ln(z) + c_3z - \frac{2}{3}\beta(\frac{z}{2})^3\ln(z) + O(z^5\ln(z))
$$
, (I.4)

$$
K_{53}(z) \sim \beta^3 \gamma (1-\nu) \left[\frac{1}{2} (\frac{z}{2}) \ln(z) + c_4 z + \frac{1}{3} (\frac{z}{2})^3 \ln(z) + O(z^5 \ln(z)) \right]_{(1.5)}
$$

$$
K_{55}(z) \sim \frac{\gamma}{\kappa} \ln(z) + c_5 + \frac{\gamma}{\kappa} \left(\frac{z}{2}\right)^2 \ln(z) + 0(z^4 \ln(z)) \quad , \tag{I.6}
$$

where the **ci's** are **constants.** In the shell problem these types of terms **come** from the large **a** behavior of the infinite integrals, see section J.4 of Appendix J.

To show how these terms affect the **convergence** of the stress intensity factors, table 1.2 lists results for the **plate** bending problem solved in three different **ways.** First both log(t-y) **and** $(t-y)^2$ log(t-y) terms of Eqn. I.2 are evaluated in closed form. The only the log term is **evaluated** in **closed** form. Finally both terms **are integrated** numerically. In the **case where** the **Iog term was integrated n1!merically, convergence was** unstable **for** increasing N . **The table** shows **improved convergence when** the **z21nz** term is **evaluated in closed** form. It should be noted however_ that **as a/h** gets **large** the **coefficient** of this **term** is proportional to (a/h)**2, and it** becomes unwise to separate it from **the** rest of the Fredholm kernel. **This** is generally the **case when** doing **part** of the Fredholm kernel in **closed form.** For certain parameters the two separate **terms** become **increasingly equal and** opposite **and consequently** big numbers are **added** to small numbers **and accuracy is lost.** This typically occurs for the most interesting/difficult geometries. **Table** 1.3 is similar to 1.2 but **for out-of-plane shear and** for twisting. **Here** there **are five** different **cases** as **can** be seen from Eqns. 1.3-6. Again it is necessary to factor out the log term. The other *terms* **are** not so important. My conclusion is that for other than the log term, a closed form **solution should only** be used when repeated calculations are necessary for an **"expensive"** problem.

Table 1.1 - *Convergence* **of log** integrals (see **Eqn.** 1.1) using Gauss-Chebychev integration **.** N=**^{** α **} corresponds** to **closed form.**

Convergence **of Log** Integrals

n=2

y=.49

n--O n=l

Table 1.3 The effect of log terms on converge **of SIF's** for a **cracked plate,** u=-.3, **a/h=l** subjected to out-of-plane shear and **twisting.**

out-of-plane **shear** twisting

APPENDIX J

Asymptotic Analysis of the Shell **Infinite** Integrals

There are two reasons why the large *a* **behavior of** the infinite integrals must **be determined.** First the **singular** behavior **of** the integral **equation comes** from the leading **order** term in the large a **expansion of** the integrand. The second **reason** is **simply** for **numerical** simplification. The **numerical** technique **used divides** the **integral** into two parts, $0 \lt a \lt A$ performed numerically, and $a > A$ which is **evaluated in closed** form. The more terms in the **expansion,** the smaller **need be** A.

The **complication** in the integrand is its **dependence on** the **roots of** the quartic **polynomial,**

$$
p^{4} - \kappa \lambda_{2}^{4} p^{3} + \left\{ \left[(\lambda_{1}^{2} - \lambda_{2}^{2}) \alpha^{2} \right] 2 \kappa \lambda_{2}^{2} + \lambda_{2}^{4} \right\} p^{2} - \\ - \left\{ \left[(\lambda_{1}^{2} - \lambda_{2}^{2}) \alpha^{2} \right] \kappa + \left[(\lambda_{1}^{2} - \lambda_{2}^{2}) \alpha^{2} \right] 2 \lambda_{2}^{2} \right\} p + \left[(\lambda_{1}^{2} - \lambda_{2}^{2}) \alpha^{2} \right]^{2} . \tag{J.1}
$$

One need only trace through Chapter 5 to see that the **kernels** in question are heavily **dependent** on *these* roots.

J.l Asymptotic Expansions for the Roots **of** the **Characteristic** Equation

A straightforward asymptotic analysis of the integrands **of** the infinite integrals of Chapter **5 would** start **with** the large **a** expansion of the roots of Eqn. J.1. They have been found to be

$$
p_1 = \frac{1}{\kappa} + \frac{1}{\alpha^4} \frac{1}{\kappa^5 (\lambda_1^2 - \lambda_2^2)^2} + \frac{1}{\alpha^6} \frac{2\lambda_2^2}{\kappa^6 (\lambda_1^2 - \lambda_2^2)^3} + \frac{1}{\alpha^8} \frac{4 \cdot 3 \kappa^2 \lambda_2^4}{\kappa^9} + \ldots , \quad (J.2)
$$

$$
p_j = a^{4/3} p_{1j} + a^{2/3} p_{2j} + p_{3j} + \dots, \quad j = 2,3,4 \quad , \tag{J.3}
$$

where

$$
p_{12} = (\kappa f)^{1/3}, \quad p_{13} = p_{12} \left[-\frac{1}{2} + i \frac{\sqrt{3}}{2} \right], \quad p_{14} = p_{12} \left[-\frac{1}{2} - i \frac{\sqrt{3}}{2} \right]
$$

\n
$$
p_{2j} = \frac{-bp_{1j}^{2}}{4p_{1j}^{3} + d}, \quad j = 2, 3, 4,
$$

\n
$$
p_{3j} = -\frac{6p_{1j}^{2}p_{2j}^{2} + ap_{1j}^{3} + 2bp_{1j}p_{2j} + f}{4p_{1j}^{3} + d}, \quad j = 2, 3, 4,
$$

\n
$$
a = -\kappa \lambda_{2}^{4}, \quad b = 2\kappa \lambda_{2}^{2}(\lambda_{1}^{2} - \lambda_{2}^{2}), \quad c = \lambda_{2}^{4}, \quad d = -\kappa (\lambda_{1}^{2} - \lambda_{2}^{2})^{2},
$$

\n(J.4)

$$
e = -2\lambda_2^2(\lambda_1^2 - \lambda_2^2) , \quad f = (\lambda_1^2 - \lambda_2^2)^2 . \tag{J.5}
$$

By using *these* **roots one can obtain all** the **quantities found** in the **various kernels, for example for** large *a*

$$
D(a) = a4 3i \sqrt{3} \lambda^{4} \kappa^{2} (\lambda_{1}^{2} - \lambda_{2}^{2})^{2} + 0(a^{2})
$$
 (J.6)

This method is good enough to determine the leading **order** term but there is **a** better **way which** is shown in section J.2. It is **also** useful to have the small $a^2(\lambda_1^2-\lambda_2^2)$ expansion of the roots of Eqn. J. They **are:**

$$
P_{1,2} = \eta_0 + z\eta_1 + z^2\eta_2 + z^3\eta_3 + 0(z^4) \quad , \tag{J.7}
$$

$$
p_{3} = \frac{z}{\lambda_{2}^{2}} + i\frac{z^{2}}{\lambda_{2}^{6}} + \frac{-4\kappa_{1}z^{3}}{2\lambda_{2}^{8}} + 0(z^{4}) ,
$$
\n
$$
p_{4} = \frac{z}{\lambda_{2}^{2}} - i\frac{z^{2}}{\lambda_{2}^{6}} + \frac{-4\kappa_{1}z^{3}}{2\lambda_{2}^{8}} + 0(z^{4}) ,
$$
\n
$$
\eta_{0} = \frac{\kappa\lambda_{2}^{4}}{2} + \frac{1}{2}(\kappa^{2}\lambda_{2}^{8} - 4\lambda_{2}^{4})^{1/2} , \quad \eta_{1} = -\frac{\overline{b}\eta_{0}^{2} - \overline{b}\eta_{0}}{4\eta_{0}^{3} + 3a\eta_{0}^{2} + 2c\eta_{0}} ,
$$
\n
$$
\eta_{2} = -\frac{6\eta_{0}^{2}\eta_{1}^{2} + 3a\eta_{0}\eta_{1}^{2} + c\eta_{1}^{2} + 2\overline{b}\eta_{0}\eta_{1} + \overline{d}\eta_{0} + \overline{e}\eta_{1} + 1}{4\eta_{0}^{3} + 3a\eta_{0}^{2} + 2c\eta_{0}} ,
$$
\n
$$
\eta_{3} = -\frac{12\eta_{0}^{2}\eta_{1}\eta_{2} + 4\eta_{0}\eta_{1}^{3} + 6a\eta_{0}\eta_{1}\eta_{2} + a\eta_{1}^{3} + b\eta_{1}^{2} + 2\overline{b}\eta_{0}\eta_{2} + 2c\eta_{1}\eta_{2} + \overline{d}\eta_{1} + \overline{e}\eta_{2}}{4\eta_{0}^{3} + 3a\eta_{0}^{2} + 2c\eta_{0}} ,
$$
\n(1.10)

$$
z = a^2(\lambda_1^2 - \lambda_2^2) \quad , \tag{J.10}
$$

$$
\overline{b} = 2\kappa\lambda_2^2, \quad \overline{d} = -\kappa, \quad \overline{e} = -2\lambda_2^2 \quad , \tag{J.11}
$$

where p_1 is obtained from using the plus sign for η_0 and p_2 **corresponds** to the minus sign.

J.2 Symmetric Asymptotic Analysis

 \pmb{t}

First recall Eqns. **5.39,65,66,67,68,80,81** from **Chapter** 5.

$$
m_j = -(p_j + a^2)^{1/2} , \quad j=1,2,3,4 , \qquad (J.12)
$$

$$
\sum_{j=1}^{4} m_j K_j R_j \Big\{ \left[\kappa (1-\nu) a^2 + 1 \right] p_j - a^2 (1-\nu) \Big\} = 0 \quad , \tag{J.13}
$$

$$
\sum_{j=1}^{4} m_j K_j R_j \left\{ \kappa p_j - 1 \right\} = \frac{-1}{a} q_2(a) , \qquad (J.14)
$$

$$
\sum_{j=1}^{4} m_j R_j = 0 \quad , \tag{J.15}
$$

$$
\sum_{j=1}^{4} m_{j} R_{j} \left\{ \lambda_{2}^{2} K_{j} \frac{\kappa_{p_{j}} - 1}{\lambda^{2}} - m_{j}^{2} \right\} = -\alpha q_{1}(\alpha) , \qquad (J.16)
$$

$$
-f_1(y) = -\frac{1}{\pi} \lim_{x \to 0} \int_0^{+\infty} a^2 \sum_{j=1}^{\infty} R_j e^{m_j x} \cos \alpha (t-y) d\alpha , \qquad (J.17)
$$

$$
\frac{-\lambda^{4}}{1-\nu}f_{2}(y) = \frac{1+\nu}{\pi} \lim_{x \to 0} \int_{0}^{+\infty} \left\{ -\kappa r e^{rx} \sum_{j=1}^{4} m_{j} p_{j} K_{j} R_{j} + \frac{1}{1-\nu} \sum_{j=1}^{4} p_{j} K_{j} R_{j} e^{m_{j}x} + \alpha^{2} \sum_{j=1}^{4} K_{j} R_{j} e^{m_{j}x} \right\} \cos \alpha (t-y) d\alpha
$$
 (J.18)

Instead of determining the behavior of the individual quantities of Eqns. J.17,18, Eqns. J.13-16 are used to determine the behavior of the entire sum. First Eqn. J.12 is expanded for large a.

$$
m_{j} = -(p_{j} + \alpha^{2})^{1/2} \approx -\alpha \left[1 + \frac{1}{2} \frac{p_{j}}{\alpha^{2}} - \frac{1}{8} \frac{p_{j}^{2}}{\alpha^{4}} + \cdots \right],
$$

$$
\approx -\alpha \sum_{n=0}^{\infty} a_{n} (-1)^{n+1} \left(\frac{p_{j}}{\alpha^{2}} \right)^{n}, \quad a_{n} = \begin{pmatrix} 1/2 \\ n \end{pmatrix} \text{ (binomial coef.)} . \quad (J.19)
$$

This expansion is valid because $(p_j/a^2) \sim a^{-2/3}$ which goes to zero for large a. Also the following expression will be needed,

$$
r = -\left[\alpha^{2} + \frac{2}{\kappa(1-\nu)}\right]^{1/2},
$$

$$
r \approx -\alpha \sum_{n=0}^{\infty} b_{n} (-1)^{n+1} \left(\frac{\rho}{\alpha^{2}}\right)^{n}, \rho = \frac{2}{\kappa(1-\nu)}.
$$
 (J.20)

Note that for either r or m_j , the large α and small x behavior of the exponentials may be simplified as follows,

$$
e^{rx} \sim \exp\left[-ax\left\{1 + \frac{1}{2}\frac{\rho}{a^2} - \frac{1}{8}\frac{\rho^2}{a^4} + \ldots\right\}\right] \sim e^{-ax}
$$
 (J.21)

$$
e^{m_{j}x} \sim \exp\left[-ax\left\{1+\frac{1}{2}\frac{p_{j}}{a^{2}}-\frac{1}{8}\frac{p_{j}^{2}}{a^{4}}+\ldots\right\}\right] \sim e^{-ax} \quad . \tag{J.22}
$$

The kernels of **gqns.** J.17,18 **are** defined for large *a:*

$$
I_1 = I_{11}q_1(a)/a + I_{12}q_2(a)/a = a^2 \sum_{j=1}^{4} R_j
$$
 (J.23)

$$
I_{2} = I_{12}q_{1}(a)/a + I_{22}q_{2}(a)/a = -\kappa r \sum_{j=1}^{4} m_{j}p_{j}K_{j}R_{j} + \frac{1}{1-\nu} \sum_{j=1}^{4} p_{j}K_{j}R_{j} + a^{2} \sum_{j=1}^{4} K_{j}R_{j}
$$
 (J.24)

Therefore *the* **following expressions are needed,**

$$
\sum_{j=1}^{4} R_j
$$
 (J.25)

$$
\frac{4}{j=1}K_jR_j \qquad (J.26)
$$

$$
\sum_{j=1}^{4} p_j K_j R_j \qquad (J.27)
$$

$$
\sum_{j=1}^{4} m_j p_j K_j R_j \qquad (J.28)
$$

From Eqns. J.13-16, **Eqn.** J.28 **can** be **easily determined,**

$$
\sum_{j=1}^{4} m_j p_j K_j R_j = i\alpha (1-\nu) q_2(\alpha) \quad . \tag{J.29}
$$

Also **from these equations we** can **write**

$$
\sum_{j=1}^{4} m_j K_j R_j = i a \kappa (1-\nu) q_2(a) + \frac{i}{a} q_2(a) , \qquad (J.30)
$$

$$
\frac{4}{\sum_{j=1}^{n} n_j p_j R_j} = -i \frac{\lambda_2^2}{\lambda^2} \frac{1}{a} q_2(a) + i a q_1(a)
$$
 (J.31)

Next express K_j in terms of p_j . The characteristic equation, J.1 is **first** used to write

$$
\frac{1}{\kappa p_j - 1} = \frac{\lambda_2^4}{p_j^2} + \frac{2\lambda_2^2(\lambda_2^2 - \lambda_1^2)\alpha^2}{p_j^3} + \frac{(\lambda_2^2 - \lambda_1^2)^2\alpha^4}{p_j^4} .
$$
 (J.32)

K. can then be written as J

$$
K_{j} = \frac{p_{j}^{2} \lambda^{2}}{(\pi_{j}^{2} \lambda_{2}^{2} - \lambda_{1}^{2} a^{2}) (\kappa_{P_{j}} - 1)} =
$$

$$
= \frac{\lambda^{2}}{a^{2} (\lambda_{2}^{2} - \lambda_{1}^{2})} \left\{ \lambda_{2}^{4} + \frac{2 \lambda_{2}^{2} (\lambda_{2}^{2} - \lambda_{1}^{2}) a^{2}}{p_{j}} + \frac{(\lambda_{2}^{2} - \lambda_{1}^{2})^{2} a^{4}}{p_{j}^{2}} \right\} \times
$$

$$
\times \sum_{n=0}^{\infty} (-1)^{n} \left(\frac{p_{j}}{a^{2}} \right)^{n} \delta^{n} , \quad \delta = \frac{\lambda_{2}^{2}}{\lambda_{2}^{2} - \lambda_{1}^{2}} . \quad (J.33)
$$

This expression is **used** to obtain

$$
\sum_{j=1}^{4} K_{j} R_{j} = \alpha^{2} \lambda^{2} (\lambda_{2}^{2} - \lambda_{1}^{2}) \sum_{j=1}^{4} p_{j}^{-2} R_{j} + \lambda^{2} \lambda_{2}^{2} \sum_{j=1}^{4} p_{j}^{-1} R_{j} \quad , \qquad (J.34)
$$

$$
\frac{4}{\sum_{j=1}^{j} p_j} K_{j} R_{j} = a^2 \lambda^2 (\lambda_2^2 - \lambda_1^2) \sum_{j=1}^{4} p_j^{-1} R_{j} + \lambda^2 \lambda_2^2 \sum_{j=1}^{4} R_{j}.
$$
 (J.35)

Therefore we **can** find **all** that is needed (Eqns. J.25-27), if the following three sums are known,

$$
\sum_{j=1}^{4} p_j^{-1} R_j, \quad i=0,1,2 \quad . \tag{J.36}
$$

In a similar way in which Eqns. J.34,35 were found, it may also be shown that

$$
\sum_{j=1}^{4} p_{j}^{-1} m_{j} R_{j} = \frac{i(1-\nu)}{\alpha \lambda^{2} (\lambda_{2}^{2} - \lambda_{1}^{2})} q_{2}(\alpha) ,
$$
\n
$$
\sum_{j=1}^{4} p_{j}^{-2} m_{j} R_{j} = i q_{2}(\alpha) \left\{ \frac{1}{\alpha} \frac{\kappa (1-\nu)}{\lambda^{2} (\lambda_{2}^{2} - \lambda_{1}^{2})} + \frac{1}{\alpha^{3}} \left[\frac{1}{\lambda^{2} (\lambda_{2}^{2} - \lambda_{1}^{2})} - \frac{(1-\nu) \lambda_{2}^{2}}{\lambda^{2} (\lambda_{2}^{2} - \lambda_{1}^{2})^{2}} \right] \right\} .
$$
\n(J.38)

From Eqns. **3.15,31,37,38,** the characteristic equation, J.1 can be used to determine

$$
\frac{4}{j=1}p_j^n m_j R_j \qquad (J.39)
$$

for any n because these four equations represent four consecu values of the **integer** n. **By** making use of Eqn. J.19, **Eqn.** J.39 can be converted into

$$
\frac{4}{j=1}p_j^nR_j \qquad (J.40)
$$

for any n, in particular n = 0,-1,-2, see Eqn. J.36. This involv algebra, the amount of which is determined by how many terms in th expansion are desired. The result is

$$
I_{11} \approx \frac{a}{2} + \sum_{k=1}^{5} \beta_{2k-1}^{11} a^{-(2k-1)} + 0(a^{-11}) \quad , \tag{J.41}
$$

$$
I_{12} \approx \sum_{k=1}^{5} \beta_{2k-1}^{12} a^{-(2k-1)} + 0(a^{-11}), \qquad (J.42)
$$

$$
I_{21} \approx \sum_{k=1}^{6} \beta_{2k-1}^{21} a^{-(2k-1)} + 0(a^{-13}), \qquad (J.43)
$$

\n
$$
I_{22} \approx \frac{-a}{2} (1+\nu) + \sum_{k=1}^{6} \beta_{2k-1}^{22} a^{-(2k-1)} + \frac{a}{2k-1} a^{-(2k-1)} \kappa (1-\nu) a_{k+1} (-1)^k \rho^{k+1} + 0(a^{-13}), \qquad (J.44)
$$

where,

×

$$
\rho_{1}^{11} = \left[-\kappa \gamma^{2} \frac{35}{128} + \frac{5}{8} \kappa \gamma \lambda_{2}^{2} - \frac{3}{8} \kappa \lambda_{2}^{4} \right],
$$
\n
$$
\rho_{2k-1}^{11} = \frac{2k+1}{j-1} (-1)^{k+j-1} \gamma^{2k+1-j} \mathbf{Q}_{1}(k,j) c(3k+2-j) , k = 1,...,5 ,
$$
\n
$$
\rho_{1}^{12} = \frac{1}{\lambda^{2}} \left[-\gamma \left(\frac{5}{16} (1-\nu) - \frac{3}{8} \right) + \lambda_{2}^{2} \left(\frac{3}{8} (1-\nu) - \frac{1}{2} \right) \right],
$$
\n
$$
\rho_{2k-1}^{12} = \frac{1}{\lambda^{2}} \sum_{j=1}^{2k} (-1)^{k+j+1} \gamma^{2k-j} \mathbf{Q}_{2}(k,j) d(3k+1-j) , k = 1,...,5 ,
$$
\n
$$
\rho_{1}^{21} = \lambda^{2} \left[\frac{1}{1-\nu} \left(\frac{1}{2}\lambda_{2}^{2} - \frac{3}{8}\gamma \right) + \frac{5}{16} \gamma - \frac{3}{8} \lambda_{2}^{2} \right],
$$
\n
$$
\rho_{2k+1}^{21} = \lambda^{2} \sum_{j=1}^{2k+1} (-1)^{k+j} \gamma^{2k+1-j} \mathbf{Q}_{1}(k,j) \left[\left(\frac{\gamma}{1-\nu} + \lambda_{2}^{2} \right) c(3k+3-j) - \frac{\lambda_{2}^{2}}{1-\nu} c(3k+2-j) - \gamma c(3k+4-j) \right], k = 1,...,5 ,
$$
\n
$$
\rho_{1}^{22} = \frac{1}{2\kappa (1-\nu)} ,
$$
\n
$$
\rho_{2k+1}^{22} = \left\{ \kappa (1-\nu) a_{k+2} (-1)^{k+1} \rho^{k+2} + \sum_{j=1}^{2k} (-1)^{k+j} \gamma^{2k-j} \mathbf{Q}_{2}(k,j) x + \left[\left(\frac{\gamma}{1-\nu} + \lambda_{2}^{2} \right) d(3k+2-j) - \frac{\lambda_{2}^{2}}{
$$

where

$$
\gamma = (\lambda_2^2 - \lambda_1^2) \quad , \tag{J.46}
$$

$$
c_0 = 1
$$
, $c_1 = a_1$, $c_n = a_n + \sum_{i=1}^{n-1} a_{n-i} c_i$, (J.47)

$$
d_0 = (1-\nu)
$$
, $d_n = c_n(1-\nu) - c_{n-1}$, (J.48)

$$
Q_{1}(1,1)=\kappa, Q_{1}(1,2)=2\kappa\lambda_{2}^{2}, Q_{1}(1,3)=\kappa\lambda_{2}^{4},
$$
\n
$$
Q_{1}(2,1)=\kappa^{2}, Q_{1}(2,2)=4\kappa^{2}\lambda_{2}^{2}, Q_{1}(2,3)=6\kappa^{2}\lambda_{2}^{4}-1, Q_{1}(2,4)=\lambda_{2}^{2}(4\kappa^{2}\lambda_{2}^{4}-2),
$$
\n
$$
Q_{1}(2,5)=\lambda_{2}^{4}(\kappa^{2}\lambda_{2}^{4}-1),
$$
\n
$$
Q_{1}(3,1)=\kappa^{3}, Q_{1}(3,2)=6\kappa^{3}\lambda_{2}^{2}, Q_{1}(3,3)=\kappa(15\kappa^{2}\lambda_{2}^{4}-2),
$$
\n
$$
Q_{1}(3,4)=\kappa\lambda_{2}^{2}(20\kappa^{2}\lambda_{2}^{4}-8), Q_{1}(3,5)=\kappa\lambda_{2}^{4}(15\kappa^{2}\lambda_{2}^{4}-12),
$$
\n
$$
Q_{1}(3,6)=\kappa\lambda_{2}^{6}(6\kappa^{2}\lambda_{2}^{4}-8), Q_{1}(3,7)=\kappa\lambda_{2}^{8}(\kappa^{2}\lambda_{2}^{4}-2),
$$
\n
$$
Q_{1}(4,1)=\kappa^{4}, Q_{1}(4,2)=8\kappa^{4}\lambda_{2}^{2}, Q_{1}(4,3)=\kappa^{2}(28\kappa^{2}\lambda_{2}^{4}-3),
$$
\n
$$
Q_{1}(4,4)=\kappa^{2}\lambda_{2}^{2}(56\kappa^{2}\lambda_{2}^{4}-18), Q_{1}(4,5)=(70\kappa^{4}\lambda_{2}^{8}-45\kappa^{2}\lambda_{2}^{4}+1),
$$
\n
$$
Q_{1}(4,6)=\lambda_{2}^{2}(56\kappa^{4}\lambda_{2}^{8}-60\kappa^{2}\lambda_{2}^{4}+4), Q_{1}(4,7)=\lambda_{2}^{4}(28\kappa^{4}\lambda_{2}^{8}-45\kappa^{2}\lambda_{2}^{4}+6),
$$
\n
$$
Q_{1}(4,8)=\lambda_{2}^{6}(8\kappa^{4}\lambda_{2}^{8}-18\kappa^{2}\lambda_{2}^{
$$

$$
Q_{1}(5,7)=x\lambda_{2}^{4}(210x^{4}\lambda_{2}^{8}-280x^{2}\lambda_{2}^{4}+45),
$$
\n
$$
Q_{1}(5,8)=x\lambda_{2}^{6}(120x^{4}\lambda_{2}^{8}-224x^{2}\lambda_{2}^{4}+60),
$$
\n
$$
Q_{1}(5,9)=x\lambda_{2}^{8}(45x^{4}\lambda_{2}^{8}-112x^{2}\lambda_{2}^{4}+45),
$$
\n
$$
Q_{1}(5,10)=x\lambda_{2}^{10}(10x^{4}\lambda_{2}^{8}-32x^{2}\lambda_{2}^{4}+18),
$$
\n
$$
Q_{1}(5,11)=x\lambda_{2}^{12}(x^{4}\lambda_{2}^{8}-4x^{2}\lambda_{2}^{4}+3),
$$
\n
$$
Q_{2}(1,1)=1, Q_{2}(1,2)=\lambda_{2}^{2},
$$
\n
$$
Q_{2}(2,1)=x, Q_{2}(2,2)=3x\lambda_{2}^{2}, Q_{2}(2,3)=3x\lambda_{2}^{4}, Q_{2}(2,4)=x\lambda_{2}^{6},
$$
\n
$$
Q_{2}(3,1)=x^{2}, Q_{2}(3,2)=5x^{2}\lambda_{2}^{2}, Q_{2}(3,3)=(10x^{2}\lambda_{2}^{4}-1),
$$
\n
$$
Q_{2}(3,4)=\lambda_{2}^{2}(10x^{2}\lambda_{2}^{4}-3), Q_{2}(3,5)=\lambda_{2}^{4}(5x^{2}\lambda_{2}^{4}-3),
$$
\n
$$
Q_{2}(3,6)=\lambda_{2}^{6}(x^{2}\lambda_{2}^{4}-1),
$$
\n
$$
Q_{2}(4,1)=x^{3}, Q_{2}(4,2)=7x^{3}\lambda_{2}^{2}, Q_{2}(4,3)=x(21x^{2}\lambda_{2}^{4}-2),
$$
\n
$$
Q_{2}(4,1)=x^{3}, Q_{2}(4,2)=7x^{3}\lambda_{2}^{2}, Q_{2}(4,3)=x(21x^{2}\lambda_{2}^{4}-2),
$$
\n
$$
Q_{2}(4,4)=x\lambda_{2}^{2}(35x^{2}\lambda_{2}^{4}-10), Q_{2}(4,5)=x\lambda_{2}^{4}(3
$$

 $-$

$$
Q_{2}(5,7) = \lambda_{2}^{4} (84\kappa^{4} \lambda_{2}^{8} - 105\kappa^{2} \lambda_{2}^{4} + 10),
$$

\n
$$
Q_{2}(5,8) = \lambda_{2}^{6} (36\kappa^{4} \lambda_{2}^{8} - 63\kappa^{2} \lambda_{2}^{4} + 10),
$$

\n
$$
Q_{2}(5,9) = \lambda_{2}^{8} (9\kappa^{4} \lambda_{2}^{8} - 21\kappa^{2} \lambda_{2}^{4} + 5),
$$

\n
$$
Q_{2}(5,10) = \lambda_{2}^{10} (\kappa^{4} \lambda_{2}^{8} - 3\kappa^{2} \lambda_{2}^{4} + 1).
$$
 (J.49)

As mentioned at the beginning of this appendix, the infinite integrals are divided into two parts. The portion from A to infinity is integrated in closed form. This part can be written as,

$$
\int_{A}^{\infty} I_{ij} \cos \alpha (t-y) d\alpha \quad , \quad i,j=1,2 \quad . \tag{J.50}
$$

This integral for I_{ij} of the form given by Eqns. J.41-44 is evaluated in section J.4 of this appendix. The following expressions are used in Eqns. 5.84,85.

$$
\overline{I}_{1j} = \sum_{n=2}^{5} \beta_{2n-1}^{1j} (-1)^{n} \frac{(t-y)^{2n-2}}{(2n-2)!} \ln|t-y| +
$$
\n
$$
+ \sum_{n=1}^{5} \beta_{2n-1}^{1j} (-1)^{n+1} \frac{(t-y)^{2n-2}}{(2n-2)!} F_c(1) + \sum_{n=2}^{5} \beta_{2n-1}^{1j} \overline{F}_c(2n-1), j=1,2, (J.51)
$$
\n
$$
\overline{I}_{21} = \sum_{n=2}^{6} \beta_{2n-1}^{21} (-1)^{n} \frac{(t-y)^{2n-2}}{(2n-2)!} \ln|t-y| +
$$
\n
$$
+ \sum_{n=1}^{6} \beta_{2n-1}^{21} (-1)^{n+1} \frac{(t-y)^{2n-2}}{(2n-2)!} F_c(1) + \sum_{n=2}^{6} \beta_{2n-1}^{21} \overline{F}_c(2n-1), (J.52)
$$
\n
$$
\overline{I}_{22} = \left\{ \sum_{n=2}^{6} \beta_{2n-1}^{22} + \kappa (1-\nu) \sum_{n=7}^{\infty} \rho^{n+1} (-1)^{n} a_{n+1} \right\} (-1)^{n} \frac{(t-y)^{2n-2}}{(2n-2)!} \ln|t-y| +
$$
\n
$$
+ \left\{ \sum_{n=1}^{6} \beta_{2n-1}^{22} + \kappa (1-\nu) \sum_{n=7}^{\infty} \rho^{n+1} (-1)^{n} a_{n+1} \right\} (-1)^{n+1} \frac{(t-y)^{2n-2}}{(2n-2)!} F_c(1) +
$$

+
$$
\left\{\sum_{n=2}^{6} \beta_{2n-1}^{22} + \kappa (1-\nu) \sum_{n=7}^{\infty} \rho^{n+1} (-1)^n a_{n+1} \right\} \bar{F}_c(2n-1)
$$
 (J.53)

J.3 Skew-Symmetric Asymptotic Analysis

The same procedure that was used in section J.2 is used here. The necessary equations are 5.93-96,106-108, which are repeated below,

$$
\frac{1}{1-\nu}\sum_{j=1}^{4} p_j K_j R_j = q_5(a) \qquad (J.54)
$$

$$
\sum_{j=1}^{4} R_j = 0 \quad , \tag{J.55}
$$

$$
\sum_{j=1}^{4} m_j^2 R_j = q_4(\alpha) \qquad (J.56)
$$

$$
\sum_{j=1}^{4} R_j K_j (\kappa p_j - 1) = \frac{i}{\alpha} q_3(\alpha) , \qquad (J.57)
$$

$$
-f_3(y) = \frac{1}{2\pi} \lim_{x \to 0} \int_{-\infty}^{+\infty} \left\{ \frac{-1}{r(1-\nu)} \sum_{j=1}^{4} (\mathbf{m}_j^2 - \nu \alpha^2) K_j R_j e^{TX} + \frac{4}{\nu} \right\} \frac{1}{r(1-\nu)} \frac{1}{r(1-\nu
$$

+
$$
\kappa \sum_{j=1}^{4} m_j p_j K_j R_j(a) e^{i\omega_j x} e^{-i\omega_j a}
$$
, (J.58)

$$
-f_4(y) = \frac{i}{2\pi} \lim_{x \to 0} \int_{-\infty}^{+\infty} a \sum_{j=1}^4 m_j R_j(a) e^{m_j x} e^{-iay} da , \qquad (J.59)
$$

$$
-\frac{2\lambda^{4}}{1-\nu}f_{5}(y) = \frac{1+\nu}{2\pi}\lim_{x\to 0}\int_{-\infty}^{+\infty}\left\{\sum_{j=1}^{4}K_{j}R_{j}\left[-\frac{e^{TX}(\alpha^{2}+r^{2})}{i\alpha r(1-\nu)}(\mathfrak{m}_{j}^{2}-\nu\alpha^{2}) - 2i\alpha\mathfrak{m}_{j}e^{i\alpha^{2}}\right]\right\} e^{-i\alpha y} d\alpha
$$
 (J.60)

defined as follows for large a . Eqns. J.19-22 are again used. The kernels in Eqns. J.58-60 are

$$
I_{3} = I_{33}q_{3}(a)/a + I_{34}q_{4}(a)/a + I_{35}q_{5}(a)/a =
$$
\n
$$
= \frac{-1}{r(1-\nu)} \sum_{j=1}^{4} p_{j}K_{j}R_{j} - \frac{a^{2}}{r} \sum_{j=1}^{4} K_{j}R_{j} + \kappa \sum_{j=1}^{4} n_{j}p_{j}K_{j}R_{j}(a) , \qquad (J.61)
$$
\n
$$
I_{4} = I_{43}q_{3}(a)/a + I_{44}q_{4}(a)/a + I_{45}q_{5}(a)/a =
$$
\n
$$
= ia \sum_{j=1}^{4} n_{j}R_{j}(a) , \qquad (J.62)
$$
\n
$$
I_{5} = I_{53}q_{3}(a)/a + I_{54}q_{4}(a)/a + I_{55}q_{5}(a)/a =
$$

$$
= \sum_{j=1}^{4} K_j R_j \left[\frac{-(a^2 + r^2)}{\sin^2(1-\nu)^p} \right] - \frac{a(a^2 + r^2)}{\sin^2(1-\nu)^p} - 2ia_m \right] \quad . \tag{J.63}
$$

C.

From Eqns. **J.54-57** we **find:**

$$
\sum_{j=1}^{4} p_j^{-2} R_j = q_5(a) \Big\{ \frac{\kappa(1-\nu)}{a^2 \lambda^2 (\lambda_2^2 - \lambda_1^2)} - \frac{\lambda_2^2(1-\nu)}{a^4 \lambda^2 (\lambda_2^2 - \lambda_1^2)^2} \Big\} -
$$

$$
- q_3(a) \frac{i}{a^3 \lambda^2 (\lambda_2^2 - \lambda_1^2)}
$$
 (J.64)

$$
\sum_{j=1}^{4} p_j^{-1} R_j = \frac{(1-\nu) q_5(a)}{a^2 \lambda^2 (\lambda_2^2 - \lambda_1^2)}, \qquad (J.65)
$$

$$
\sum_{j=1}^{4} R_j = 0 \quad , \tag{J.66}
$$

$$
\sum_{j=1}^{4} p_j R_j = q_4(a) \quad . \tag{J.67}
$$

Combined with Eqn. J.l the following may be determined,

$$
\sum_{j=1}^{4} p_j^{n} R_j \qquad (J.68)
$$

for **any** n **from which all** of the **expressions** in Eqns. J.fil-63 may be **obtained** to **any order of a.** The **result is:**

$$
I_{33} \simeq -i\alpha + i \sum_{k=1}^{4} \beta_{2k-1}^{33} \alpha^{-(2k-1)} - i\alpha \sum_{k=5}^{\infty} (-1)^k (\rho/\alpha^2)^k e_k + 0(\alpha^{-9})
$$
\n(3.69)

$$
I_{34} \approx \kappa \lambda^2 \Big[\frac{1}{8} (\lambda_2^2 - \lambda_1^2) - \frac{1}{2} \lambda_2^2 \Big] + \sum_{k=1}^4 \beta_{2k}^{34} a^{-(2k)} + 0 (a^{-10}) \quad , \tag{J.70}
$$

$$
I_{35} \simeq \sum_{k=1}^{4} \beta_{2k}^{35} a^{-(2k)} + \sum_{k=5}^{\infty} (-1)^k (\rho/a^2)^k [e_k - 2e_{k+1}] + 0(a^{-10}), \quad (J.71)
$$

$$
I_{43} \approx i \frac{(\lambda_2^2 - \lambda_1^2)}{8\lambda^2} + i \sum_{k=1}^3 \beta_{2k}^{34} a^{-(2k)} + 0(a^{-8}) \qquad , \qquad (J.72)
$$

$$
I_{44} \approx \frac{-a}{2} + \sum_{k=1}^{4} \beta_{2k-1}^{44} a^{-(2k-1)} + 0(a^{-9}) \quad , \tag{J.73}
$$

$$
I_{45} \approx \sum_{k=1}^{4} \beta_{2k-1}^{45} a^{-(2k-1)} + 0(a^{-9}), \qquad (J.74)
$$

$$
I_{53} \approx \frac{3}{k-1} \beta_{2k}^{53} a^{-(2k)} + a^2 \sum_{k=5}^{\infty} (-1)^k (\rho/a^2)^k [e_{k-1}^{-2e_k}] + 0(a^{-8}), \quad (J.75)
$$

$$
I_{54} \approx i \sum_{k=1}^{4} \beta_{2k-1}^{54} a^{-(2k-1)} + 0(a^{-9}) \quad , \tag{J.76}
$$

$$
I_{55} \approx -i\alpha(1+\nu) + i\sum_{k=1}^{4} \beta_{2k-1}^{55} \alpha^{-2(k-1)} - i\alpha \sum_{k=5}^{\infty} (-1)^{k+1} (\rho/\alpha^2)^k [e_{k-1} - 4e_k + 4e_{k+1}] + 0(\alpha^{-9}), \qquad (J.77)
$$

where

$$
\beta_1^{33} = \frac{1}{\kappa (1-\nu)} + \frac{\kappa}{16} (\lambda_2^4 - \lambda_1^4) ,
$$

$$
\beta_3^{33} = -\rho^2 e_{2} + \kappa \gamma \Big[-a_{3} \kappa \lambda_{2}^{6} + a_{4} 3 \kappa \lambda_{2}^{4} \gamma - a_{5} 3 \kappa \lambda_{2}^{2} \gamma^{2} + a_{6} \kappa \gamma^{3} \Big],
$$
\n
$$
\beta_5^{33} = \rho^3 e_{3} + \kappa \gamma \Big[a_{4} \lambda_{2}^{6} (\kappa^{2} \lambda_{2}^{4} - 1) - a_{5} \lambda_{2}^{4} \gamma (5 \kappa^{2} \lambda_{2}^{4} - 3) + a_{6} \lambda_{2}^{2} \gamma^{2} (10 \kappa^{2} \lambda_{2}^{4} - 3) - a_{7} \gamma^{3} (10 \kappa^{2} \lambda_{2}^{4} - 1) + a_{8} 5 \kappa^{2} \lambda_{2}^{2} \gamma^{4} - a_{9} \kappa^{2} \gamma^{5} \Big],
$$
\n
$$
\beta_7^{33} = -\rho^4 e_{4} + \kappa \gamma \Big[-a_{5} \kappa \lambda_{2}^{10} (\kappa^{2} \lambda_{2}^{4} - 2) + a_{6} \kappa \lambda_{2}^{8} \gamma (7 \kappa^{2} \lambda_{2}^{4} - 10) - a_{7} \kappa \lambda_{2}^{6} \gamma^{2} (21 \kappa^{2} \lambda_{2}^{4} - 20) + a_{8} \kappa \lambda_{2}^{4} \gamma^{3} (35 \kappa^{2} \lambda_{2}^{4} - 20) - a_{9} \kappa \lambda_{2}^{2} \gamma^{4} (35 \kappa^{2} \lambda_{2}^{4} - 10) + a_{10} \kappa \gamma^{5} (21 \kappa^{2} \lambda_{2}^{4} - 2) - a_{11} \gamma \kappa^{3} \lambda_{2}^{2} \gamma^{6} + a_{12} \kappa^{3} \gamma^{7} \Big],
$$

$$
\rho_{2}^{34} = \kappa \lambda^{2} \Big[a_{2} \kappa \lambda_{2}^{6} - a_{3} 3 \kappa \gamma \lambda_{2}^{4} + a_{4} 3 \kappa \lambda_{2}^{2} \gamma^{2} - a_{5} \kappa \gamma^{3} \Big] ,
$$
\n
$$
\rho_{4}^{34} = \kappa \lambda^{2} \Big[-a_{3} \lambda_{2}^{6} (\kappa^{2} \lambda_{2}^{4} - 1) + a_{4} \gamma \lambda_{2}^{4} (5 \kappa^{2} \lambda_{2}^{4} - 3) - a_{5} \lambda_{2}^{2} \gamma^{2} (10 \kappa^{2} \lambda_{2}^{4} - 3) +
$$
\n
$$
+ a_{6} \gamma^{3} (10 \kappa^{2} \lambda_{2}^{4} - 1) - a_{7} 5 \kappa^{2} \lambda_{2}^{2} \gamma^{4} + a_{8} \kappa^{2} \gamma^{5} \Big] ,
$$
\n
$$
\rho_{6}^{34} = \kappa \lambda^{2} \Big[a_{4} \kappa \lambda_{2}^{10} (\kappa^{2} \lambda_{2}^{4} - 2) - a_{5} \kappa \lambda_{2}^{8} \gamma (7 \kappa^{2} \lambda_{2}^{4} - 10) + a_{6} \kappa \lambda_{2}^{6} \gamma^{2} (21 \kappa^{2} \lambda_{2}^{4} - 20) -
$$
\n
$$
- a_{7} \kappa \lambda_{2}^{4} \gamma^{3} (35 \kappa^{2} \lambda_{2}^{4} - 20) + a_{8} \kappa \lambda_{2}^{2} \gamma^{4} (35 \kappa^{2} \lambda_{2}^{4} - 10) - a_{9} \kappa \gamma^{5} (21 \kappa^{2} \lambda_{2}^{4} - 2) +
$$
\n
$$
+ a_{10} 7 \kappa^{3} \lambda_{2}^{2} \gamma^{6} - a_{11} \kappa^{3} \gamma^{7} \Big] ,
$$
\n
$$
\rho_{8}^{34} = \kappa \lambda^{2} \Big[-a_{5} \lambda_{2}^{10} (\kappa^{4} \lambda_{2}^{8} - 3 \kappa^{2} \lambda_{2}^{4} + 1) + a_{6} \gamma \lambda_{2}^{8} (9 \kappa^{4} \lambda_{
$$

$$
p_2^{35} = -\rho(e_1 - 2e_2) + \kappa(1-\nu) \left[-a_2 \lambda_2^4 + a_3 2 \lambda_2^2 - a_4 7^2 \right],
$$
\n
$$
\beta_4^{35} = \rho^2 (e_2 - 2e_3) + \kappa (1-\nu) \left[a_3 \kappa \lambda_2^8 - a_4 4 \kappa \lambda_2^6 \gamma + a_5 6 \kappa \lambda_2^4 \gamma^2 - a_6 4 \kappa \lambda_2^2 \gamma^3 + a_7 \kappa \gamma^4 \right],
$$
\n
$$
\beta_6^{35} = -\rho^3 (e_3 - 2e_4) + \kappa (1-\nu) \left[-a_4 \lambda_2^8 (\kappa^2 \lambda_2^4 - 1) + a_5 \lambda_2^6 \gamma (6 \kappa^2 \lambda_2^4 - 4) - a_6 \lambda_2^4 \gamma^2 (15 \kappa^2 \lambda_2^4 - 6) + a_7 \lambda_2^2 \gamma^3 (20 \kappa^2 \lambda_2^4 - 4) - a_8 \gamma^4 (15 \kappa^2 \lambda_2^4 - 1) + a_9 6 \kappa^2 \lambda_2^2 \gamma^5 - a_{10} \kappa^2 \gamma^6 \right],
$$
\n
$$
\beta_8^{35} = \rho^4 (e_4 - 2e_5) + \kappa (1-\nu) \left[a_5 \kappa \lambda_2^{12} (\kappa^2 \lambda_2^4 - 2) - a_6 \kappa \lambda_2^{10} \gamma (8 \kappa^2 \lambda_2^4 - 12) + a_7 \kappa \lambda_2^8 \gamma^2 (28 \kappa^2 \lambda_2^4 - 30) - a_8 \kappa \lambda_2^6 \gamma^3 (56 \kappa^2 \lambda_2^4 - 40) + a_9 \kappa \lambda_2^4 \gamma^4 (70 \kappa^2 \lambda_2^4 - 30) - a_{10} \kappa \lambda_2^2 \gamma^5 (56 \kappa^2 \lambda_2^4 - 12) + a_{11} \kappa \gamma^6 (28 \kappa^2 \lambda_2^4 - 2) - a_{12} 8 \kappa^3 \lambda_2^2 \gamma^7 + a_{13} \kappa^3 \gamma^8 \right],
$$

$$
\beta_{2}^{43} = (\gamma/\lambda^{2}) \Big[-a_{3} \kappa \lambda_{2}^{4} + a_{4} 2 \kappa \lambda_{2}^{2} \gamma - a_{5} \kappa \gamma^{2} \Big] ,
$$
\n
$$
\beta_{4}^{43} = (\gamma/\lambda^{2}) \Big[a_{4} \lambda_{2}^{4} (\kappa^{2} \lambda_{2}^{4} - 1) - a_{5} 2 \lambda_{2}^{2} \gamma (2 \kappa^{2} \lambda_{2}^{4} - 1) + a_{6} \gamma^{2} (6 \kappa^{2} \lambda_{2}^{4} - 1) - a_{7} 4 \kappa^{2} \lambda_{2}^{2} \gamma^{3} + a_{8} \kappa^{2} \gamma^{4} \Big] ,
$$
\n
$$
\beta_{6}^{43} = (\gamma/\lambda^{2}) \Big[-a_{5} \kappa \lambda_{2}^{8} (\kappa^{2} \lambda_{2}^{4} - 2) + a_{6} 2 \kappa \lambda_{2}^{6} \gamma (3 \kappa^{2} \lambda_{2}^{4} - 4) - a_{7} \kappa \lambda_{2}^{4} \gamma^{2} (15 \kappa^{2} \lambda_{2}^{4} - 12) + a_{8} \kappa \lambda_{2}^{2} \gamma^{3} (20 \kappa^{2} \lambda_{2}^{4} - 8) - a_{9} \kappa \gamma^{4} (15 \kappa^{2} \lambda_{2}^{4} - 2) + a_{10} 6 \kappa^{3} \lambda_{2}^{2} \gamma^{5} - a_{11} \kappa^{3} \gamma^{6} \Big] ,
$$

$$
\rho_1^{44} = \kappa \Big[\frac{5}{128} (\lambda_2^2 - \lambda_1^2)^2 + \frac{1}{8} \lambda_1^2 \lambda_2^2 \Big],
$$

$$
\rho_3^{44} = -a_3 \lambda_2^4 (\kappa^2 \lambda_2^4 - 1) + a_4 \lambda_2^2 \gamma (4 \kappa^2 \lambda_2^4 - 2) - a_5 \gamma^2 (6 \kappa^2 \lambda_2^4 - 1) + a_6 4 \kappa^2 \lambda_2^2 \gamma^3 - a_7 \kappa^2 \gamma^4,
$$

$$
\beta_5^{44} = a_4 \kappa \lambda_2^8 (\kappa^2 \lambda_2^4 - 2) - a_5 \kappa \lambda_2^6 \gamma (6 \kappa^2 \lambda_2^4 - 8) + a_6 \kappa \lambda_2^4 \gamma^2 (15 \kappa^2 \lambda_2^4 - 12) - a_7 2 \kappa \lambda_2^2 \gamma^3 (10 \kappa^2 \lambda_2^4 - 4) + a_8 \kappa \gamma^4 (15 \kappa^2 \lambda_2^4 - 2) - a_9 6 \kappa^3 \lambda_2^2 \gamma^5 + a_{10} \kappa^3 \gamma^6
$$

\n
$$
\beta_7^{44} = -a_5 \lambda_2^8 (\kappa^4 \lambda_2^8 - 3 \kappa^2 \lambda_2^4 + 1) + a_6 \lambda_2^6 \gamma (8 \kappa^4 \lambda_2^8 - 18 \kappa^2 \lambda_2^4 + 4) - a_7 \lambda_2^4 \gamma^2 (28 \kappa^4 \lambda_2^8 - 45 \kappa^2 \lambda_2^4 + 6) + a_8 \lambda_2^2 \gamma^3 (56 \kappa^4 \lambda_2^8 - 60 \kappa^2 \lambda_2^4 + 4) - a_9 \gamma^4 (70 \kappa^4 \lambda_2^8 - 45 \kappa^2 \lambda_2^4 + 1) + a_{10} \kappa^2 \lambda_2^2 \gamma^5 (56 \kappa^2 \lambda_2^4 - 18) - a_{11} \kappa^2 \gamma^6 (28 \kappa^2 \lambda_2^4 - 3) + a_{12} 8 \kappa^4 \lambda_2^2 \gamma^7 - a_{13} \kappa^4 \gamma^8
$$

$$
\rho_{1}^{45} = -(1-\nu)\frac{\lambda_{2}^{2} + \lambda_{1}^{2}}{16\lambda^{2}},
$$
\n
$$
\rho_{3}^{45} = (1-\nu)\lambda^{2}\Big[a_{3}\kappa\lambda_{2}^{6} - a_{4}3\kappa\lambda_{2}^{4}\gamma + a_{5}3\kappa\lambda_{2}^{2}\gamma^{2} - a_{6}\kappa\gamma^{3}\Big],
$$
\n
$$
\rho_{5}^{45} = (1-\nu)\lambda^{2}\Big[-a_{4}\lambda_{2}^{6}(\kappa^{2}\lambda_{2}^{4} - 1) + a_{5}\lambda_{2}^{4}\gamma(5\kappa^{2}\lambda_{2}^{4} - 3) - a_{6}\lambda_{2}^{2}\gamma^{2}(10\kappa^{2}\lambda_{2}^{4} - 3) + a_{7}\gamma^{3}(10\kappa^{2}\lambda_{2}^{4} - 1) - a_{8}5\kappa^{2}\lambda_{2}^{2}\gamma^{4} + a_{9}\kappa^{2}\gamma^{5}\Big],
$$
\n
$$
\rho_{7}^{45} = (1-\nu)\lambda^{2}\Big[a_{5}\kappa\lambda_{2}^{10}(\kappa^{2}\lambda_{2}^{4} - 2) - a_{6}\lambda_{2}^{8}\kappa\gamma(7\kappa^{2}\lambda_{2}^{4} - 10) + a_{7}\kappa\lambda_{2}^{6}\gamma^{2}(21\kappa^{2}\lambda_{2}^{4} - 20) - a_{8}\lambda_{2}^{4}\kappa\gamma^{3}(35\kappa^{2}\lambda_{2}^{4} - 20) + a_{9}\kappa\lambda_{2}^{2}\gamma^{4}(35\kappa^{2}\lambda_{2}^{4} - 10) - a_{10}\kappa\gamma^{5}(21\kappa^{2}\lambda_{2}^{4} - 2) + a_{11}7\kappa^{3}\lambda_{2}^{2}\gamma^{6} - a_{12}\kappa^{3}\gamma^{7}\Big],
$$

$$
\begin{array}{ll}\n\beta_2^{53} & = \rho^2(\mathbf{e}_1 - 2\mathbf{e}_2) - 2\gamma \Big[\mathbf{a}_3 \lambda_2^2 - \mathbf{a}_4 \gamma \Big] \, , \\
\beta_4^{53} & = \, -\rho^3(\mathbf{e}_2 - 2\mathbf{e}_3) - 2\gamma \Big[-\mathbf{a}_4 \kappa \lambda_2^6 + \mathbf{a}_5 3\kappa \lambda_2^4 \gamma - \mathbf{a}_6 3\kappa \lambda_2^2 \gamma^2 + \mathbf{a}_7 \kappa \gamma^3 \Big] \, ,\n\end{array}
$$

$$
\rho_{6}^{53} = \rho^{4} (e_{3} - 2e_{4}) - 27 \Big[a_{5} \lambda_{2}^{6} (\kappa^{2} \lambda_{2}^{4} - 1) - a_{6} \lambda_{2}^{4} \gamma (5 \kappa^{2} \lambda_{2}^{4} - 3) + a_{7} \lambda_{2}^{2} \gamma^{2} (10 \kappa^{2} \lambda_{2}^{4} - 3) - a_{8} \gamma^{3} (10 \kappa^{2} \lambda_{2}^{4} - 1) + a_{9} 5 \kappa^{2} \lambda_{2}^{2} \gamma^{4} - a_{10} \kappa^{2} \gamma^{5} \Big] ,
$$
\n
$$
\rho_{8}^{53} = -\rho^{5} (e_{4} - 2e_{5}) - 27 \Big[-a_{6} \kappa \lambda_{2}^{10} (\kappa^{2} \lambda_{2}^{4} - 2) + a_{7} \kappa \lambda_{2}^{8} \gamma (7 \kappa^{2} \lambda_{2}^{4} - 10) - a_{8} \kappa \lambda_{2}^{6} \gamma^{2} (21 \kappa^{2} \lambda_{2}^{4} - 20) + a_{9} \kappa \lambda_{2}^{4} \gamma^{3} (35 \kappa^{2} \lambda_{2}^{4} - 20) - a_{10} \kappa \lambda_{2}^{2} \gamma^{4} (35 \kappa^{2} \lambda_{2}^{4} - 10) + a_{11} \kappa \gamma^{5} (21 \kappa^{2} \lambda_{2}^{4} - 2) - a_{12} 7 \kappa^{3} \lambda_{2}^{2} \gamma^{6} + a_{13} \kappa^{3} \gamma^{7} \Big] ,
$$

$$
\beta_{1}^{54} = -\lambda^{2} \frac{\lambda_{2}^{2} + \lambda_{1}^{2}}{8},
$$
\n
$$
\beta_{3}^{54} = 2\lambda^{2} \Big[a_{3}\kappa\lambda_{2}^{6} - a_{4}3\kappa\lambda_{2}^{4} \gamma + a_{5}3\kappa\lambda_{2}^{2} \gamma^{2} - a_{6}\kappa\gamma^{3} \Big],
$$
\n
$$
\beta_{5}^{54} = 2\lambda^{2} \Big[-a_{4}\lambda_{2}^{6}(\kappa^{2}\lambda_{2}^{4} - 1) + a_{5}\lambda_{2}^{4} \gamma(5\kappa^{2}\lambda_{2}^{4} - 3) - a_{6}\lambda_{2}^{2} \gamma^{2}(10\kappa^{2}\lambda_{2}^{4} - 3) + a_{7}\gamma^{3}(10\kappa^{2}\lambda_{2}^{4} - 1) - a_{8}5\kappa^{2}\lambda_{2}^{2} \gamma^{4} + a_{9}\kappa^{2} \gamma^{5} \Big],
$$
\n
$$
\beta_{7}^{54} = 2\lambda^{2} \Big[a_{5}\kappa\lambda_{2}^{10}(\kappa^{2}\lambda_{2}^{4} - 2) - a_{6}\kappa\lambda_{2}^{8} \gamma(7\kappa^{2}\lambda_{2}^{4} - 10) + a_{7}\kappa\lambda_{2}^{6} \gamma^{2}(21\kappa^{2}\lambda_{2}^{4} - 20) - a_{8}\kappa\lambda_{2}^{4} \gamma^{3}(35\kappa^{2}\lambda_{2}^{4} - 20) + a_{9}\kappa\lambda_{2}^{2} \gamma^{4}(35\kappa^{2}\lambda_{2}^{4} - 10) - a_{10}\kappa\gamma^{5}(21\kappa^{2}\lambda_{2}^{4} - 2) + a_{11}\gamma\kappa^{3}\lambda_{2}^{2} \gamma^{6} - a_{12}\kappa^{3}\gamma^{7} \Big],
$$

$$
\rho_1^{55} = \frac{-1}{\kappa (1-\nu)} ,
$$
\n
$$
\rho_3^{55} = \rho^2 (e_1 - 4e_2 + 4e_3) + 2(1-\nu) \left[-a_3 \lambda_2^4 + a_4 2 \lambda_2^2 7 - a_5 7^2 \right] ,
$$
\n
$$
\rho_5^{55} = -\rho^3 (e_2 - 4e_3 + 4e_4) + 2(1-\nu) \left[a_4 \kappa \lambda_2^8 - a_5 4 \kappa \lambda_2^6 7 + a_6 6 \kappa \lambda_2^4 7^2 - \frac{1}{2} \lambda_2^4 \right] ,
$$

$$
-a_{7}4\kappa\lambda_{2}^{2}\gamma^{3}+a_{8}\kappa\gamma^{4}\right],
$$
\n
$$
\beta_{7}^{55} = \rho^{4}(e_{3}-4e_{4}+4e_{5})+2(1-\nu)\left[-a_{5}\lambda_{2}^{8}(\kappa^{2}\lambda_{2}^{4}-1)+a_{6}\lambda_{2}^{6}\gamma(6\kappa^{2}\lambda_{2}^{4}-4)-a_{7}\lambda_{2}^{4}\gamma^{2}(15\kappa^{2}\lambda_{2}^{4}-6)+a_{8}\lambda_{2}^{2}\gamma^{3}(20\kappa^{2}\lambda_{2}^{4}-4)-a_{9}\gamma^{4}(15\kappa^{2}\lambda_{2}^{4}-1)+a_{10}6\kappa^{2}\lambda_{2}^{2}\gamma^{5}-a_{11}\kappa^{2}\gamma^{6}\right]
$$
\n
$$
(3.78)
$$

The **constants defined** in **section J.2** also apply to this **section.** Other constants that **are introduced are:**

$$
r^{-1} = -\left[a^2 + \frac{2}{\kappa(1-\nu)}\right]^{-1/2},
$$

$$
r^{-1} \simeq -a^{-1} \sum_{n=0}^{\infty} e_n (-1)^n \left(\frac{\rho}{a^2}\right)^n, \quad \rho = \frac{2}{\kappa(1-\nu)}.
$$
 (J.79)

As **mentioned** at the **beginning of** this **appendix,** the infinite integrals are **divided** into two **parts. The** portion **from** A to infinity is integrated in **closed form. This** part **can** be written **as,**

$$
\int_{A}^{\infty} I_{ij} \cos \alpha (t-y) d\alpha , \quad i=3, j=3; i=4,5, j=4,5 ,
$$

$$
\int_{A}^{\infty} I_{ij} \sin \alpha (t-y) d\alpha , \quad i=3, j=4,5; i=4,5, j=3 .
$$
 (J.80)

This integral for I_i of the form given by Eqns. J.61-63 is evalua in section J.4. The following expressions are used in Eqns. **5.109-** III.

$$
\overline{I}_{33} = \left\{ \sum_{n=2}^{4} \left[\beta_{2n-1}^{33} + (\lambda_2/\lambda)^2 \beta_{2n-2}^{34} \right] + \sum_{n=5}^{\infty} -e_n (-1)^n \rho^n \right\} \times \left\{ (-1)^n \frac{(t-y)^{2n-2}}{(2n-2)!} \ln|t-y| + \overline{F}_c (2n-1) \right\} +
$$

+
$$
\left\{\sum_{n=1}^{4} \left[\beta_{2n-1}^{33} + (\lambda_2/\lambda)^2 \beta_{2n-2}^{34}\right] + \sum_{n=5}^{\infty} -e_n (-1)^n \rho^n\right\}x
$$

x $(-1)^{n+1} \frac{(t-y)^{2n-2}}{(2n-2)!} F_c(1)$, (J.81)

$$
\bar{I}_{34} = \frac{4}{\sum_{n=1}^{4}} \beta_{2n}^{34} \Big\{ (-1)^{n+1} \frac{(t-y)^{2n-1}}{(2n-1)!} F_c(1) + \bar{F}_s(2n) + (-1)^{n} \frac{(t-y)^{2n-1}}{(2n-1)!} \ln|t-y| \Big\},\tag{J.82}
$$

$$
\overline{I}_{35} = \left\{ \sum_{n=1}^{4} \beta_{2n}^{35} + \sum_{n=5}^{\infty} (-1)^n \rho^n [e_n - 2e_{n+1}] \right\} \times \left\{ (-1)^n \frac{(t-y)^{2n-1}}{(2n-1)!} \ln|t-y| + \overline{F}_s(2n) + (-1)^{n+1} \frac{(t-y)^{2n-1}}{(2n-1)!} F_c(1) \right\} , \tag{J.83}
$$

$$
\overline{I}_{43} = -\left\{ \sum_{n=1}^{3} \left[\beta_{2n}^{43} \cdot (\lambda_2/\lambda)^2 \beta_{2n-1}^{44} \right] \right\} \times \left\{ (-1)^n \frac{(t-y)^{2n-1}}{(2n-1)!} \ln|t-y| + \overline{F}_s (2n) + (-1)^{n+1} \frac{(t-y)^{2n-1}}{(2n-1)!} F_c(1) \right\}
$$
\n(1.84)

$$
\overline{I}_{4j} = \sum_{n=2}^{4} \beta_{2n-1}^{4j} \{ (-1)^n \frac{(t-y)^{2n-2}}{(2n-2)!} \ln|t-y| + \overline{F}_c(2n-1) \} + \sum_{n=1}^{4} \beta_{2n-1}^{4j} (-1)^{n+1} \frac{(t-y)^{2n-2}}{(2n-2)!} F_c(1), \quad j=4,5, (J.85)
$$
\n
$$
\overline{I}_{53} = \left\{ \sum_{n=1}^{4} \left[\beta_{2n}^{53} - (\lambda_2/\lambda)^2 \beta_{2n-1}^{54} \right] + \sum_{n=5}^{\infty} (-1)^n \rho^n (e_{n-1} - 2e_n) \right\} \times \left\{ (-1)^n \frac{(t-y)^{2n-1}}{(2n-1)!} \ln|t-y| + \overline{F}_s(2n) + (-1)^{n+1} \frac{(t-y)^{2n-1}}{(2n-1)!} F_c(1) \right\}, \quad (J.86)
$$

$$
\overline{I}_{54} = \frac{4}{n-2} \beta_{2n-1}^{54} \Big\{ \overline{F}_c (2n-1) + (-1)^n \frac{(t-y)^{2n-2}}{(2n-2)!} \ln|t-y| \Big\} +
$$

$$
+\sum_{n=1}^{4} \beta_{2n-1}^{54} (-1)^{n+1} \frac{(t-y)^{2n-2}}{(2n-2)!} F_c(1) ,
$$
\n
$$
\overline{I}_{55} = \left\{ \sum_{n=2}^{4} \beta_{2n-1}^{55} + \sum_{n=5}^{\infty} (-1)^n \rho^n (e_{n-1} - 4e_n + 4e_{n+1}) \right\} \times
$$
\n
$$
\times \left\{ \overline{F}_c(2n-1) + (-1)^n \frac{(t-y)^{2n-2}}{(2n-2)!} \ln|t-y| \right\} + \left\{ \sum_{n=1}^{4} \beta_{2n-1}^{55} + \sum_{n=5}^{\infty} (-1)^n \rho^n (e_{n-1} - 4e_n + 4e_{n+1}) \right\} (-1)^{n+1} \frac{(t-y)^{2n-2}}{(2n-2)!} F_c(1) .
$$
\n(J.88)

J.4 Integrals From A to Infinity

We **need** expressions for

$$
\int_{A}^{\infty} \frac{\cos a(t-y)}{a^{2n-1}} da , \qquad (J.89)
$$

$$
\int_{A}^{\infty} \frac{\sin \alpha (t-y)}{a^{2n}} da , \quad A > 0, \quad n > 0 . \tag{J.90}
$$

These integrals **come** from the large **a expansion** of the Fredholm kernels. **Note** that for n>O the limit for x*O has been taken under the integral sign. The n=0 cases of Eqns. J.89,90, for which the limit **must** be taken after integration, **are respectively** demonstrated below,

$$
\lim_{x \to 0} \int_{0}^{\infty} a e^{-ax} \cos a (t-y) \, da = \frac{-1}{(t-y)^2} \quad , \tag{J.91}
$$

$$
\lim_{x \to 0} \int_0^{\infty} e^{-ax} \sin \alpha (t-y) \, d\alpha = \frac{1}{t-y} \quad . \tag{J.92}
$$

380

 $c - 5$

The $1/a$ case of Eqn. J.89 has a log singularity, the $1/a^2$ term of J.90 becomes (t-y)init-y[**and so** on. **This** is shown **in** the general **expressions presented** below:

$$
\int_{\Lambda}^{\infty} \frac{\cos a(t-y)}{a^{2n-1}} da = \overline{F}_c(2n-1) + (-1)^{n+1} \frac{(t-y)^{2n-2}}{(2n-2)!} F_c(1) + (-1)^n \frac{(t-y)^{2n-2}}{(2n-2)!} \ln|t-y| , \qquad (J.93)
$$

$$
\int_{\Lambda}^{\infty} \frac{\sin a(t-y)}{a^{2n}} da = \overline{F}_s(2n) + (-1)^{n+1} \frac{(t-y)^{2n-1}}{(2n-1)!} F_c(1) + (-1)^n \frac{(t-y)^{2n-1}}{(2n-1)!} \ln|t-y| , \qquad (J.94)
$$

where

$$
F_c(1) = -\gamma_e - \ln(A) - \int_0^{A|t-y|} \frac{\cos x - 1}{x} dx , \qquad (J.95)
$$

$$
\overline{F}_{c}(2n-1) = \sum_{j=1}^{n-1} (-1)^{j+1} \frac{(t-y)^{2j-2} (2n-1-2j)!}{(2n-2)! \Lambda^{2n-2j}} cos A(t-y) + \sum_{j=1}^{n-1} (-1)^{j} \frac{(t-y)^{2j-1} (2n-2-2j)!}{(2n-2)! \Lambda^{2n-2j-1}} sin A(t-y), \qquad (J.96)
$$
\n
$$
\overline{F}_{s}(2n) = \sum_{j=1}^{n} (-1)^{j+1} \frac{(t-y)^{2j-2} (2n-2j)!}{(2n-1)! \Lambda^{2n-2j+1}} sin A(t-y) + \sum_{j=1}^{n-1} (-1)^{j+1} \frac{(t-y)^{2j-1} (2n-1-2j)!}{(2n-1)! \Lambda^{2n-2j}} cos A(t-y) . \qquad (J.97)
$$

The constant in Eqn. **J.95** is Euler's constant, $\gamma_e = .57721566490153$. **This expression** is **a cosine** integral, **Ci[A[t-y[], with** the **log** term taken **out.**

Standard Bibliographic Page

 \sim \sim

For sale by the National **Technical Information** Service, Springfield, Virginia 22161

NASA Langley Form 63 (June 1985)

I