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GENERATION AND REDUCTION OF THE DATA FOR THE
ULYSSES GRAVITATIONAL WAVE EXPERIMENT

R. AGRESTI, P. BONIFAZI, L. IESS, G.B. TRAGER

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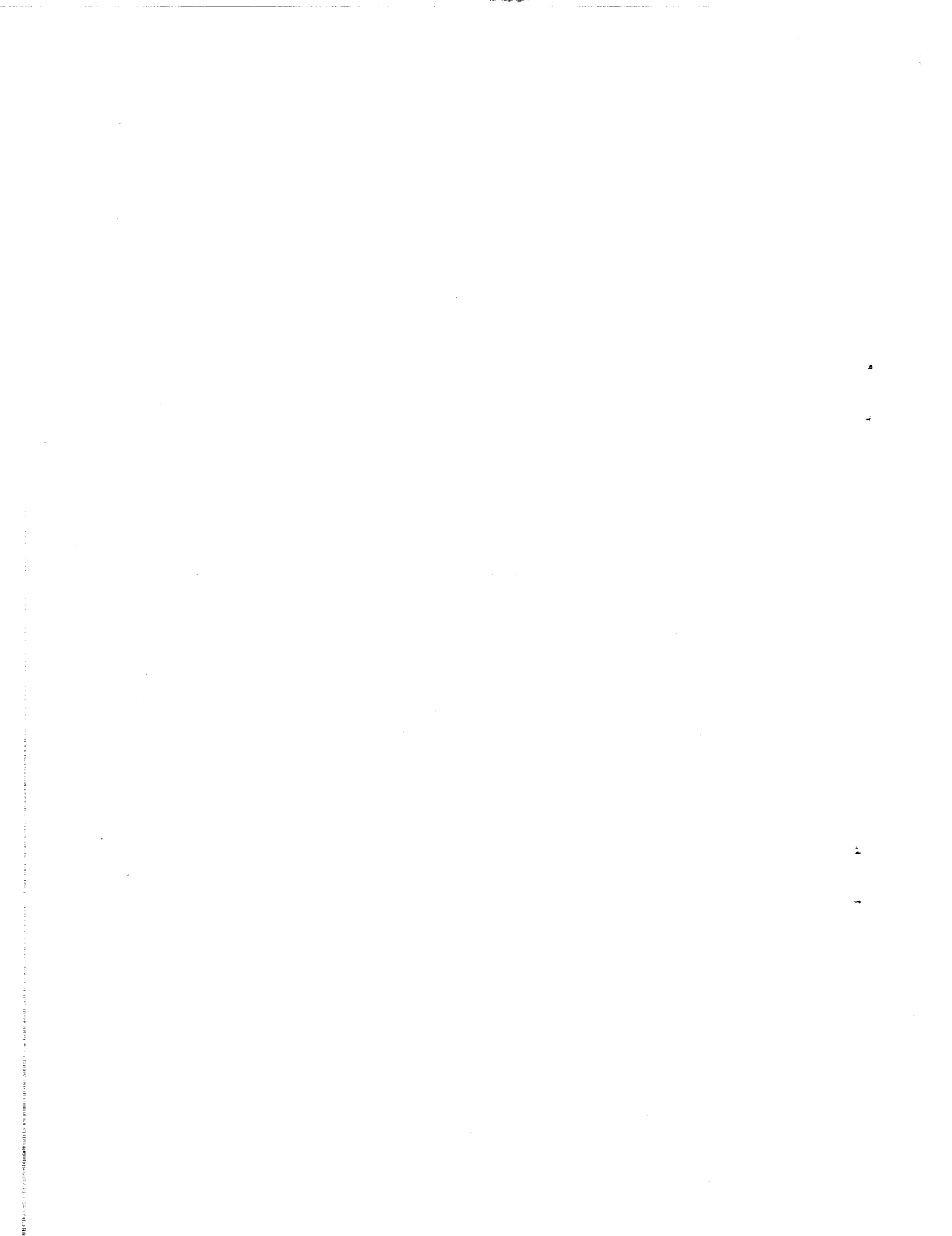
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ULYSSES GRAVITATIONAL WAVE EXPERIMENT

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SUMMARY

We describe a procedure for the generation and reduction of the radiometric data known as 'REGRES' files. These data are a current output of NASA's Orbit Determination Program. The software package was developed in view of the data analysis of the gravitational wave experiment, (GWE) planned for the European spacecraft 'Ulysses'.

INTRODUCTION

Doppler tracking of interplanetary spacecraft is routinely performed by the stations of NASA's Deep Space Network (DSN). An electromagnetic carrier of highly stable frequency is sent from a ground station to a spacecraft, which retransmits it back coherently to the Earth by means of a transponder.

The presently used radio link configurations for precision Doppler tracking are of two types: in the first one, called 'two-way' operation, the same station both transmits and receives the radio signal, in the second one, called 'three-way', the transmitting and receiving station are different. The signal is usually transmitted in S band (2.1 GHz) and received both in S and X band (8.4 GHz).

We call Doppler residual the quantity obtained by subtracting the measured frequency shift of the carrier to the predicted one. In the REGRES data, the predictions are obtained a posteriori by means of a regression method: the received radiometric data are used to improve the spacecraft ephemeris in order to minimise the least square deviation between the observables and the predictions.

In this paper we report a description of the REGRES data generation and of the software we have developed to reduce and display the data. This software has been applied to the analysis of four days (DOY 308 - DOY 313, 1980) of REGRES data relative to the Voyager I spacecraft.

The software package was implemented on an HP-1000F computer, with an RTE-6-VM operative system. The graphical unit was an HP-9872T plotter. A general purpose graphical routine, developed at IFSI-CNR, was used to plot output data.

REGRES FILE GENERATION

REGRES files are a current output of the Orbit Determination Program (ODP). The volume and the structure of REGRES files are not fixed, but depend on the way the ODP is run. Standard references on the subject are (Moyer, 1971) and (Khatib et al., 1972). ODP is actually a set of many links, which, to some extent, may be run independently. Its functions are integrated by a number of allied programs, the most important of which is DPTRAJ. The process which leads to the computation of the trajectory of the spacecraft is described in the following.

The fundamental quantities handled by the ODP are:

$\underline{X}=(\underline{r}, \dot{\underline{r}})$: spacecraft state vector, i.e. position and velocity of the spacecraft with respect to a center of integration (usually the baricenter of a celestial body).

$\underline{q}=(\underline{X}_0, \underline{a})$: parameter vector, containing the initial state of the spacecraft (\underline{X}_0) and a set (\underline{a}) of physical parameters (see below) needed for the integration of the equations of motion.

\underline{z} : vector of observable quantities (Doppler, range, angle, Δ DOR).

The main physical parameters \underline{a} are:

- the gravitational parameters $\mu_1=GM_1$ of Sun, planets and satellites of the solar system;
- the coefficients of the harmonic expansion of the

- planets' gravitational potential;
- the quantities used in modelling the probe acceleration due to small forces and manoeuvres;
- atomic station time -> UTC conversion parameter;
- coordinates of the tracking stations;
- the relativistic parameter γ .

Many other quantities may be used, depending on the particular spacecraft: there are parameters relating to atmospheric models, mass anomalies, gas leaks, solar radiation pressure, etc.

The vector \underline{a} is usually stored as a part of a file called Generalised Input File (GIN file), characterising the physical world in which the probe moves.

The ODP not only performs the integration of the equations of motion, but also allows the redeterminations of the parameters \underline{g} and, therefore, the determination of a better state vector $\underline{X}(t)$. This goal is obtained by comparing predictions and observations in a regressive analysis made up of several steps.

STEP 1 PATH-VARY (or PVDRIVE)

This link has actually a twofold purpose and may be separated for clarity into two sub-units (PATH and VARY). PATH integrates the equations of motion of the probe, starting from given injection parameters \underline{X}_0 and physical parameters \underline{a} . The probe acceleration results from the following contributions:

- Newtonian gravitational forces (leading term) from the relevant celestial bodies.
- Oblatenesses of planets.
- Mascons.
- Relativistic effects.
- Solar radiation pressure.
- Attitude control.

- Orbital manoeuvres.
- Atmospheric drag (in case of planetary encounter).

The center of integration may be any planet, or center of mass of planetary system (i.e. planet with satellites). The output of PATH is a propagation of the initial state vector \underline{X} along the trajectory as a function of time and of the parameters \underline{q} :

$$\underline{X} = \underline{X} (t, \underline{q})$$

Its output $\underline{X}(t)=(\underline{r}(t), \dot{\underline{r}}(t))$ may be stored in the Probe Ephemeris Tape (PET). It is also used as input to the program PREDIX which provides observable predictions to the tracking stations. These predictions are used to generate the pseudoresiduals contained in the Archival Tracking Data Files (ATDF).

The other subunit (VARY) integrates the variational equations

$$\frac{\partial \ddot{\underline{r}}}{\partial \underline{q}} = \frac{\partial \ddot{\underline{r}}}{\partial \underline{r}} \frac{\partial \underline{r}}{\partial \underline{q}} + \frac{\partial \ddot{\underline{r}}}{\partial \dot{\underline{r}}} \frac{\partial \dot{\underline{r}}}{\partial \underline{q}} + \left[\begin{array}{c} \frac{\partial \ddot{\underline{r}}}{\partial \underline{q}} \\ \frac{\partial \ddot{\underline{r}}}{\partial \underline{q}} \end{array} \right]_{\underline{r}, \dot{\underline{r}} = \text{const}}$$

$$\ddot{\underline{Z}} = \underline{A}\underline{Z} + \underline{B}\dot{\underline{Z}} + \underline{C} \qquad \underline{Z} = \frac{\partial \underline{r}}{\partial \underline{q}}$$

whose solution gives \underline{Z} and $\dot{\underline{Z}}$ as functions of time. These quantities are needed in the subsequent step (REGRES) to get the partial derivatives of the observable quantities with respect to the parameters. The matrices A, B and C are obtained from the equations of celestial mechanics.

STEP 2 (REGRES)

In this step, the regression partial derivatives of the observables (Doppler, range, angle) with respect to the parameters g are formed. The regression partial derivatives are needed to adjust the quantities \underline{x}_0 and \underline{a} in order to obtain a better estimate of the spacecraft trajectory (i.e. better residuals).

To this end, for each acquired value of the observable r at the reception time t_3 , the corresponding ground transmission time t_1 and spacecraft reception time t_3 are computed. The times t_1 and t_2 are obtained by solving the light time problem in the metric of the solar system baricenter. For each leg (uplink and downlink) the transmission and reception times are given by (neglecting terms of order $1/c^5$):

$$t_{\text{rec}} - t_{\text{trans}} = \frac{r_{1j}}{c} + \frac{1+\gamma}{c^3} \mu_s \ln \frac{(r_1+r_j+r_{1j})}{(r_1+r_j-r_{1j})}$$

where

$$r_1 = || \underline{r}_1 (t_{\text{trans}}) ||$$

$$r_j = || \underline{r}_j (t_{\text{rec}}) ||$$

$$r_{1j} = || \underline{r}_j (t_{\text{rec}}) - \underline{r}_1 (t_{\text{trans}}) ||$$

$\mu_s = GM_s =$ gravitational parameter of the Sun

$\gamma =$ post newtonian parameter (in general relativity $\gamma = 1$)

The vectors \underline{r} have origins in the solar system baricenter. In the last version of REGRES bending terms as

well as Jupiter and Saturn terms are included.

The solution of the light time problem must be performed for each acquired point, and requires therefore considerable computer time.

The regression derivatives $\partial \underline{r} / \partial \underline{g}$ are then formed by considering that the observable \underline{r} is a function of the state vectors of the Earth stations and the spacecraft;

$$Z = Z[\underline{X}_{st}(t_3, \underline{g}), \underline{X}_{sc}(t_2, \underline{g}), \underline{X}_{st}(t_1, \underline{g}); \underline{g}]$$

It may be seen that the partial derivatives $\partial \underline{r} / \partial \underline{g}$ are actually the sum of many terms, originating from explicit and implicit dependence of \underline{Z} on the parameter vector. We refer to (Moyer, 1982) for a detailed discussion of the subject. Here we just point out that the solution of the variational equations, which provides the quantity $\partial \underline{X}_{sc} / \partial \underline{g}$, is required for the computation of $\partial \underline{Z} / \partial \underline{g}$.

A typical REGRES output file contains:

- a) values of the parameters \underline{g} for which partials have been computed
- b) the selected observables and their residuals
- c) the selected partial derivatives $\partial \underline{r} / \partial \underline{g}$.

It must be noted that at this step the parameters \underline{g} are divided into two groups: "solve-for" parameters, for which new values are computed; "consider" parameters, which are not corrected but whose errors are taken into account in the computation of the errors for the "solve-for" parameters.

STEP 3 (ACCUME-SOLVE)

These two links use the partials obtained from the previous step to compute the parameter vector \underline{g} and

its covariance matrix. With the new q 's, a new GIN file may be created, and a new iteration, PV, REGRES, ACCUME, SOLVE (PVRAS), may be started.

The REGRES file which we analysed has not been generated by the complete sequence PVRAS, which is complicated and unnecessary for our purposes. The link REGRES was run in the so called "simulation mode", i.e. using already existing PV and GIN files and bypassing the computation of the partial derivatives $\partial z/\partial q$. The following steps have been performed to get the final REGRES file:

a) select the GIN file to be used, which contains an initial state vector $(\underline{r}_0, \underline{\dot{r}}_0)$ of the spacecraft and a set of physical parameters \underline{a} that already gave satisfactory residuals.

b) select the corresponding PV file (containing probe ephemeris)

c) select the file (ATDF or IDR) containing the observable quantities for which the residuals have to be computed (we actually used the same ATDF which was previously analysed at Frascati).

d) run the program STRIPPER which, starting from an ATDF or IDR, generates an OD file (a file which can be used as an input to REGRES)

e) run REGRES in the "simulation mode", using PV, GIN and OD files as input (together with the ephemeris of the bodies of the solar system).

The output of the step (e) is the required REGRES file.

SOFTWARE

In this section we report on the software package implemented on the HP1000F System at CNR-Frascati to handle the REGRES files.

These data, generated by an Univac 1108 System at JPL and stored on magnetic tape, have been converted using the Univac computer of the University of Rome in ASCII characters files stored on magnetic tape. The list of this Fortran program (named UNIHP) is shown in appendix B.

The main program implemented on the HP1000F (named DECODEREGRESS) decodes the REGRES data (ASCII characters) and selects the relevant items for the GWE data. The format of the output data (called STANDARD format throughout the paper) is described in (Iess and Armstrong 1985).

The software package is completed by a set of programs for the display and validation of the data and for the storage of Doppler residuals (our observable) in the HP disk memory. These programs are named: STATREGRESS, PLOTREGRESS and FFREGRESS.

STATREGRESS reads the STANDARD tapes and produces an output list for each day of data. This list contains hourly and total number of samples for each active station, band and mode.

PLOTREGRESS provides plots of the STANDARD tapes.

In order to simplify the access to the data, the STANDARD files can be copied on a disk using the FFREGRES program. Each disk file contains the data relative to a single pass.

The program listings are reported in Appendix B. In the following we report a description of the software.

DECODEREGRES

DECODEREGRESS reads the REGRES tapes in ASCII format, selects the items relevant to the GWE and generates the STANDARD tapes.

DATA STRUCTURE

INPUT

BUFFER DIMENSION: ISK(40,100)

RECORD LENGTH: 8000 characters

RECORD FORMAT: Each data record is composed of 100 cards of 80 characters each. The 80 characters of each card have the following meaning:

char. 1-5 : measurement group identifier N1, ranging from to 99999

char. 6-8 : card identifier N2, ranging from 1 to 100

char. 9-32 : data value, written in the format F24.18

char. 33-56: as above

char. 57-80: as above

DATA FORMAT: In the original tapes generated at JPL, twenty quantities were associated to each Doppler data acquisition (see tab. 1). We will refer to this set of 20 quantities as to a "measurement". Therefore each record contains 15 measurements (i. e.: $3 \times 100 / 20$), (see tab. 2). A data block is defined as a set of 40 measurements. The block identifier number N1, which appear in tab. 2, refers to the record generated at JPL with the Univac routine NTRAN.

See tab. 3 for an example of ISK (40,100) record.

OUTPUT

The output data, stored on magnetic tapes, are structured as a sequence of fixed length records with eof.

BUFFER DIMENSION: LMAT(160,15)

RECORD LENGTH: 2400 double integers number, i.e. 4800
16-bit words.
RECORD FORMAT: Each of the 160 rows contains 15 double
integer items.

DATA FORMAT: Each row contains information about one
measurement in both bands (S and X). Tab. 4 shows the data
structure of the STANDARD records.

In tab. 5 we report, the items of the REGRES
tapes generated at JPL and their corresponding items in
the STANDARD records. Tab. 6 shows an example of
STANDARD record (they e.c. refers to the same REGRES data
in tab. 3).

ALGORITHM

The program reads in sequence the ISK(40,100)
records. The 20 quantities corresponding to a single
measurement are transferred in the INTEGER*4 buffer
ISK1(240). This buffer is decoded and the relevant items of
each measurement are transferred in a second INTEGER*4
buffer LMAT(160,15). It is important to note that two
subsequent measurements in input usually refers to the S
and X band respectively. In order to properly fill the
eighth column of the matrix LMAT (S-3/11X), the program
requires that S-band datum must precede the X-band datum in
the input data. In fig. 2a and 2b is reported the
flowchart of the program.

The program is structured as a main routine,
managing the input data buffer, and a subroutine, managing
the output buffer. Those two program segments are now
described in more detail, referring to fig. 2a and 2b.

MAIN PROGRAM

- 1) INFORMATION FOR INPUT/OUTPUT
 - 1a) options and parameters for the job:
sequential number of the required initial REGRES

- record, sequential number of the required final
REGRES record;
tape logical unit number;
etc.
- 1b) search for initial record to analyse
 - 2) READ A ISK (40.100) RECORD
this step is made using the system routine XTAPE
(EXEC)
check on the record length
eof causes jump to step #8
read error causes jump to next record
 - 3) TEST FOR COLUMN IDENTIFIER
if the block identifier is changed, the program
resets the decodifying buffer pointer IP. This step
is needed to eliminate the free item present at
every changing group
 - 4) DECODIFICATION AND STORAGE OF THE DATA
this step is performed by the subroutine CONTROLLO
which transfers and decodes the data
 - 5, 6, 7) REPEAT STEPS 1 TO 4 FOR ALL REQUIRED RECORDS
AND TAPES
 - 8) FINAL OPERATIONS
 - 8a) stores the last data in memory
 - 8b) writes eof on STANDARD tape and rewinds the tapes
 - 8c) prints information on the work just carried out
 - 9) STOP

STATREGRESS

This program reads the STANDARD tapes and produces an output list for each day. The list contains hourly and total number of samples for each active station, band and mode. An example of an output list is reported in tab. 7.

ALGORITHM

The input data are contained in the STANDARD files generated by DECODEREGRESS. The algorithm uses a buffer of sample counters structured as a matrix 48*24. Each row represents one of the combinations of 6 DSN, stations 4 tracking modes and 2 bands, while the 24 columns represent the hours of the day. The identification of the sample counter for a given DSN station, band, mode and hour of day combination is given by:

$$\begin{aligned} \text{ROW} &= (S - 1) * 8 + (M - 1) * 2 + B \\ \text{COL} &= \text{HOUR OF DAY} \end{aligned}$$

where B is 1 or 2 for S or X band respectively M represent the 4 different radio link modes, while S=1,2,3,4,5,6 represents the six DSS: 12, 14, 42, 43, 61 and 63 respectively. The decodification of the row number can be made as follows:

$$\begin{aligned} \text{STATION} &= \text{INT} ((\text{ROW} - 1) / 8) + 1 \\ \text{BAND} &= \text{ROW's PARITY} \\ \text{MODE} &= \text{INT} ((\text{ROW} - \text{BAND} - (\text{STATION} - 1) * 8) / 2) + 1 \end{aligned}$$

In fig. 3 is reported the flow chart of the program, whose main steps are described below.

- 1) ASK INFORMATION FOR INPUT/OUTPUT
tape logical unit number

number of records to analyse
initial and final day and year
etc.

2) READ A RECORD I4 (160,15)

3, 4) SEARCH FOR FIRST RELEVANT DATA

5, 6, 7) ANALYSE DATA AND FILL THE LIST

8) OUTPUT OPERATIONS

if the list (i.e. the output buffer) of the required
day is empty, (if there are no data, for example)
the program prints a warning, otherwise it prints
the required list.

10) START ANALYSIS OF A NEW REQUIRED DAY (if any)

11) STOP

PLOTREGRESS

This program provides plots of STANDARD data for each day and mode.

DATA STRUCTURE

The input data are the STANDARD file generated by the program DECODEREGRESS. The user selects the passes to be plotted for each desired day. DOY, mode and the DSS are required as input parameters. The data appear into three curves (S-band, X-band and S-3/11*X) as shown in fig. 4.

ALGORITHM

The program flow chart is shown in fig. 5.

- 1) ASK INFORMATION FOR INPUT/OUTPUT
 - 1a) options and parameters for the job as:
 - initial and final REGRES records
 - tape logical unit number
 - required days and modes
 - etc.
 - 1b) search for the initial record to analyse
- 2) REWIND TAPE
- 3) READ A RECORD
- 4) CHECK FOR DAY AND MODE
 - if data refers to the required day and mode, they are stored in a buffer
- 5) DO DATA REFER TO A LATER DAY?
 - in this case the selected data are plotted
- 6) LAST RECORD?
 - the search for the relevant data is repeated for

all records;
the search ends if the data of a record refer to a
later day;
if there are no data to plot, the program prints a
warning and goes to step #8.

7) PLOTTING

this step is carried out by a software package
developped at IFSI

8) OTHER PLOTS?

in this case, steps (1-7) are repeated.

9) STOP

FFREGRES

This program stores S and X band Doppler residuals and oscillator frequency from STANDARD tapes into disk files. Each file contains data referring to a given pass. Besides Doppler residuals, each file contains a header which reports spacecraft angular data, RTL T and other information. Some of these quantities are retrieved from the file DATA/FILE#1 (see Iess and Armstrong, 1985)

DATA STRUCTURE

INPUT : The input data are the STANDARD data and angular data FILE#1 (see Tab. 8)

OUTPUT: In output one obtains ASCII disk files relative to a single pass

BUFFER DIMENSION: ISTORE(3,730)

RECORD LENGTH: 2190 double integers, i.e. 4380
16-bit word

RECORD FORMAT: each of the 3 rows contains 730 double integers. The file name has the following mnemonic code:

DAT/RODTTRRDD

where:

DAT is the data subdirectory;

ROD stands for REGRES Original Doppler resid.;

TT is the code for transmitting DSS;

RR is the code for receiving DSS;

DDD are three characters indicating the DOY.

DATA FORMAT: each file (see tab. 9) is composed by a header, with general information about the pass, followed by S and X band residuals and oscillator frequency in the first, second and third row respectively. Residuals are given in mmHz while

the oscillator frequency is given in Hz. The header contains initial and final time, number of data, receiving and transmitting DSS, tracking mode, RTLT, spacecraft's right ascension and declination at the middle of the pass. An example of residual file is reported in tab. 10.

ALGORITHM

The algorithm looks for data referring to the required receiving DSS, mode and begin of tracking day. Then it selects data from FILE#1 to build the header (see fig. 6).

For the Voyager I data the sampling rate was of 1 pt/min: therefore each Doppler residual refers to a given minute of the day (MOD). The time T (in MOD) of every datum can be obtained from the following relation:

$$T = \text{module} (I - 11 - T_{in} , 1440)$$

where I is the column number of the datum in the array ISTORE, and T_{in} the MOD of the first datum of the file. Since the header must be skipped, 11 must be subtracted from I to get the right position. Finally, the remainder of the division of $I - 11 - T_{in}$ by 1440 provides the MOD of the datum (if $I - 11 - T_{in} > 1440$, the MOD refers to the next day).

ACKNOWLEDGEMENTS

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APPENDIX A

LIST OF ACRONYMS AND NAMES

ATDF	Archival Tracking Data File
DOY	Day Of the Year
DSN	Deep Space Network
DSS	Deep Space Station
EOF	End Of File
GIN	Generalised INput file
GWE	Gravitational Wave Experiment
IDR	Intermediate Data Records
MOD	Minute Of the Day
ODP	Orbit Determination Program
PET	Probe Ephemeris Tape
PV	Path-Vary
REGRES	Regression files
RTLTL	Round Trip Light Time

APPENDIX B

PROGRAM LISTINGS

We report in this appendix the fortran program listings of the computer programs used in the data analysis.

```

C      PROGRAM UNIHP
C
C *****
C *  TRASFORMAZIONE DEI NASTRI REGRESS IN FORMATO UNIVAC *
C *****
C *
C *  QUESTO PROGRAMMA OPERA SUI DATI REGRESS *
C *
C *****
C
C DICHIARAZIONI
COMMON /DATI/A(801),ADOUT(100),NROUT
DOUBLE PRECISION ARRAY(20,40),A
CHARACTER*80 ADOUT
C
C      IOUT=10
C      IOUT2=11
C      PRINT 1
1     FORMAT(2X,'N. RECORD INITIAL AND FINAL?')
      READ(S,*) NIN,NFI
      NRIN=NFI-NIN+1
      PRINT 2
2     FORMAT(2X,' DOYOU WANT PRINTOUT OF A(20,40)? <1=SI>')
      READ(S,*) ISTAM
      NR=0
      NROUT=0
      LL=0
      N1=NIN-1
      IF(N1.EQ.0) GO TO 100
200   CONTINUE
      CALL NTRAN$(IOUT,2,1600,ARRAY,L,22)
      NR=NR+1
      IF(L.LT.0) GO TO 500
      IF(NR.LT.N1) GO TO 200
100   CONTINUE
      CALL NTRAN$(IOUT,2,1600,ARRAY,L,22)
      NR=NR+1
      IF(L.LT.0) GO TO 500
      IF(L.EQ.-2) GO TO 610
      IF(ISTAM.NE.1) GO TO 150
      WRITE(8,300) NR
      WRITE(8,400)
      WRITE(8,700) (ARRAY(L,1),L=1,20)
      WRITE(8,400)
      WRITE(8,700) (ARRAY(L,40),L=1,20)
      WRITE(8,400)
150   CONTINUE
      A(801)=0.D0
      II=0
      DO 10 I=1,40
      DO 10 J=1,20
      II=II+1
      A(II)=ARRAY(J,I)

```

```

10  CONTINUE
    DO 20 L=1,801,3
      L1=L+2
      CALL FILBUF(LL,IOUT2)
      ENCODE(80,800,AOUT(LL),JJ,ERR=900) NR,LL,(A(K),K=L,L1)
      IF(ISTAM.NE.1) GO TO 20
      IF(L1.GT.9.AND.L1.LT.793) GO TO 20
      WRITE(8,850) LL,AOUT(LL)
850  FORMAT(2X,'LL=',I3,2X,A80)
20  CONTINUE
800  FORMAT(I5,I3,3D24.18)
950  FORMAT(2X,'ERROR WRITE K,LL,NR,NROUT',4I9)
C
      IF(NR.GT.NFI) GO TO 600
      GO TO 100
C
300  FORMAT(2X,'RECORD NUMBER =',I10)
400  FORMAT(//)
700  FORMAT(2X,3D24.18)
C
500  CONTINUE
      PRINT 3,NR,NROUT
3    FORMAT(2X,'HARDWARE ERROR, NR,L NROUT',2X,3I9)
      STOP
610  CONTINUE
      PRINT 6,NR,NROUT
6    FORMAT(2X,'EOF AFTER N. RECORDS =',I10,2X,' NROUT = ',I10)
600  CONTINUE
C
      CALL NTRANS(IOUT2,1,2000,AOUT,L,22)
      NROUT=NROUT+1
      PRINT 5,NROUT,NRIN
      WRITE(8,400)
      WRITE(8,5) NROUT,NRIN
5    FORMAT(2X,'NUMBER OF RECORDS WRITTEN AND READ',2X,2I10)
      CALL NTRANS(IOUT2,9,2000,AOUT,L,22)
      GO TO 1000
900  PRINT 950,K,LL,NR,NROUT
1000 CONTINUE
C
C FINE DEL MAIN
      STOP
      END
C
C *****
C QUESTA SUBROUTINE RIEMPIE IL BUFFER
      SUBROUTINE FILBUF(LL,IOUT2)
C
      COMMON /DATI/A(801),AOUT(100),NROUT
      CHARACTER*80 AOUT
      DOUBLE PRECISION A
C
      LL=LL+1

```

```
IF(LL.LT.100) RETURN
CALL NTRANS(IOUT2,1,2000,AOUT,L,22)
IF(L.LT.0) PRINT 10,NROUT
NROUT=NROUT+1
NO=(NROUT/50)*50-NROUT
IF(NO.EQ.0) PRINT 20,NROUT
10  FORMAT(2X,'HARDWARE ERROR AT RECORD =',I10)
20  FORMAT(2X,'NUMBER OF RECORDS WRITTEN =',I10)
LL=1
C
C RITORNO AL MAIN
  RETURN
C
C FINE DI FILBUF
  END
```

FTN7X,S

PROGRAM DECODEREGRESS(),

(880329.1415)

```
C
C *****
C * DECODIFICA SEQUENZIALE DEI DATI REGRESS DA NASTRO *
C *****
C *
C * QUESTO PROGRAMMA OPERA SUI DATI REGRESS. *
C *
C * ESSO LEGGE DA NASTRO RECORDS DI 4000 PAROLE, LI DECODIFICA *
C * ED IMMAGAZZINA SU NASTRO D'USCITA COME INTEGER*4. *
C *
C *****
C
C DICHIARAZIONI
  DIMENSION ISK(40,100)
  COMMON ISK1(240),IP,IRM,IRC,IC3,IPRINT1,IPRINT2,ITAPE1
  COMMON IWR1,NIN,ILM1,ILM2
  INTEGER*4 LMAT(160,15)
  DIMENSION IA(4)
C
C ESEGUIBILE
C INFORMAZIONI DI INGRESSO/USCITA
111 WRITE(1,11)
  11 FORMAT(1X,21/)
  WRITE(1,*) ''
  WRITE(1,*) ' DECODIFICA SEQUENZIALE DEI DATI REGRESS'
  WRITE(1,*) ' *****'
  WRITE(1,*)
  WRITE(1,*)
  WRITE(1,*) ' QUESTO PROGRAMMA LEGGE DA NASTRO RECORDS DI '
  WRITE(1,*) ' 4000 PAROLE FORNENDO IN USCITA, A SCELTA:'
  WRITE(1,*)
  WRITE(1,*) ' 1) SEMPLICE LISTATO DEI DATI'
  WRITE(1,*) ' 2) LISTATO DEI DATI DECODIFICATI'
  WRITE(1,*) ' 3) IMMAGAZZINAMENTO DEI DATI DECODIFICATI'
  WRITE(1,12)
12 FORMAT(1X,/,80*',/)
  WRITE(1,'("RECORD REGRESS INIZIALE: ")')
  READ(1,*) NIN
  WRITE(1,'("RECORD REGRESS FINALE: ")')
  READ(1,*) NFI
  WRITE(1,'("UNITA'' NASTRO IN LETTURA: ")')
  READ(1,*) ITAPE
  REWIND ITAPE
  WRITE(1,'("VUOI IL SEMPLICE LISTATO? <1=SI>: ")')
  READ(1,*) IPRINT
  IF(IPRINT.EQ.1) THEN
    WRITE(1,'("UNITA'' STAMPANTE?: ")')
    READ(1,*) IWR
    WRITE(IWR,*)
    WRITE(1,'("DESIDERI SOLO QUESTA STAMPA? <1=SI>: ")')
    READ(1,*) IONLY
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ENDIF
IF(IONLY.NE.1) THEN
  WRITE(1,('("VUOI IMMAGAZZINARE I DATI STANDARD? <1=SI>: ")'))
  READ(1,*) IPRINT2
  IF(IPRINT2.EQ.1) THEN
    WRITE(1,('("UNITA'' NASTRO IN SCRITTURA?: ")'))
    READ(1,*) ITAPE1
    IF(ITAPE.EQ.ITAPE1) THEN
      WRITE(1,*) 'ATTENTO! HAI FORNITO LA STESSA UNITA'' NASTRO'
      WRITE(1,*) 'SIA IN SCRITTURA CHE IN LETTURA!'
      GO TO 111
    ENDIF
  ENDIF
ENDIF
WRITE(1,('("VUOI UNA STAMPA DEI DATI STANDARD? <1=SI>: ")'))
READ(1,*) IPRINT1
IF(IPRINT1.EQ.1) THEN
  WRITE(1,('("UNITA'' STAMPANTE?: ")'))
  READ(1,*) IWR1
  WRITE(IWR1,*)
ENDIF
ENDIF

C
C RICERCA DEL RECORD INIZIALE RICHIESTO
  NRC=NIN-1
  IF(NRC.NE.0) WRITE(1,*) 'RICERCA DEL RECORD INIZIALE'
  DO 1 I=1,NRC
    CALL XTAPE(1,ITAPE,ISK,4000,LEN)
    IF(LEN.NE.4000) THEN
      WRITE(1,100)I,LEN
100   FORMAT(2X,'ERRORE IN LETTURA REC# ',I5,' LUN.# ',I5)
    ENDIF
    1 CONTINUE
    WRITE(1,200) NRC
200   FORMAT('NUMERO DI RECORDS REGRESS SALTATI:',I5)
    WRITE(1,300)
300   FORMAT(1X,/,/,80'*)
C
C PER CIASCUN RECORD RICHIESTO
  DO 2 II=NIN,NFI
    IRC=IRC+1
C
C LETTURA DI UN RECORD
    CALL XTAPE(1,ITAPE,ISK,4000,LEN)
    IF (LEN.NE.4000) THEN
      IF (LEN.EQ.-1) THEN
        WRITE(1,*) 'EOF IN LETTURA'
        GO TO 10
      ENDIF
      WRITE(1,100) 'ERRORE IN LETTURA RECORD #',II,' LUN.=' ,LEN
      GO TO 2
    ENDIF
    WRITE(1,*) 'LETTO DALLA UNITA''',ITAPE,' IL RECORD #',II
  
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C

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C STAMPA IL RECORD REGRESS SE RICHIESTO
  IF(IPRINT.EQ.1) THEN
    IF(IWR.NE.1) WRITE(1,*) 'SCRITTURA SULLA UNITA''',IWR,
+ ' REC #',II
    WRITE(IWR,400) II
400  FORMAT(1X,'      RECORD # ',I5)
    WRITE(IWR,500) ((ISK(I,J),I=1,40),J=1,100)
500  FORMAT(40A?)
    WRITE(IWR,600)
600  FORMAT(/)
    IF(IONLY.EQ.1) GO TO 2
  ENDIF

C
C PER CIASCUNA COLONNA DEL RECORD
  DO 3 ICL=1,100

C
C CONTROLLO SUGLI IDENTIFICATORI
  CALL SMOVE(ISK(1,ICL),1,8,IA,1)
  DECODE(8,700,IA,ERR=20) IC1,IC3
700  FORMAT(I5,I3)
  IF(IC1.NE.IC2) THEN
    IC2=IC1
    IP=1
  ENDIF

C
C TRASFERIMENTO DI UNA COLONNA DI 'ISK' IN 'ISK1' CONTROLLANDO,
C DATO PER DATO, SE IL BUFFER E' PIENO (TEST SU IP)
  CALL SMOVE(ISK(1,ICL),9,32,ISK1(1),IP)
  CALL CONTROLLO(LMAT)
  CALL SMOVE(ISK(1,ICL),33,56,ISK1(1),IP)
  CALL CONTROLLO(LMAT)
  CALL SMOVE(ISK(1,ICL),57,80,ISK1(1),IP)
  CALL CONTROLLO(LMAT)

C
C SI RIPETE PER UN' ALTRA COLONNA
  3 CONTINUE

C
C SI RIPETE PER UN ALTRO RECORD
  2 CONTINUE

C
C OPERAZIONI FINALI
  10 REWIND ITAPE
  IF(IONLY.NE.1) THEN

C
C SI IMMAGAZZINANO I DATI RIMASTI IN MEMORIA
  IF(IPRINT2.EQ.1) THEN
    ILM2=ILM2+1
    CALL XTAPE(2,ITAPE1,LMAT,4800,LEN)
    IF(LEN.NE.4800) THEN
      WRITE(1,*) 'ERRORE IN SCRITTURA SU ',ITAPE1
      WRITE(1,*) 'LMAT #',ILM2,' LEN =',LEN
    ENDIF
    WRITE(1,*) '**SCRITTO SU',ITAPE1,' #',ILM2,'RECORDS STANDARD'
  
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ENDIF
IF(IPRINT1.EQ.1) THEN
  ILM1=ILM1+1
  WRITE(1,*) 'SCRITTURA SU',IWR1,' DEL RECORD #',ILM1
  DO 4 MM=1,160
4  WRITE(IWR1,800) MM,(LMAT(MM,NN),NN=1,15)
800  FORMAT(I3,I6,I7,I9,I7,I9,I8,I9,I6,I7,I8,5I7)
ENDIF

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C
C SCRITTURA DELL' EOF SUL NASTRO IN USCITA
IF(IPRINT2.EQ.1) THEN
  WRITE(1,('VUOI UN ALTRO NASTRO REGRESS? (1=SI): '))
  READ(1,*) NY
  IF(NY.EQ.1) GO TO 111
  ENDFILE(UNIT=ITAPE1,IOSTAT=KKK,ERR=30)
  WRITE(1,*) '**SCRITTO EOF SU',ITAPE1
  REWIND ITAPE1
ENDIF
ENDIF

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C
C FINE REGOLARE DELL' ANALISI
WRITE(1,300)
WRITE(1,*) '*****'
WRITE(1,*) '***LETTI DA',ITAPE,' ',NFI-NIN+1,' R. RECORDS'
IF(IPRINT.EQ.1) THEN
  WRITE(1,*) '*****'
  WRITE(1,*) 'SCRITTI SU',IWR,' ',IRC,' R. RECORDS'
ENDIF
IF(IPRINT2.EQ.1) THEN
  WRITE(1,*) '*****'
  WRITE(1,*) 'IMMAGAZZINATI SU',ITAPE1,' ',ILM2,' S. RECORDS'
ENDIF
IF(IPRINT1.EQ.1) THEN
  WRITE(1,*) '*****'
  WRITE(1,*) 'SCRITTI SU',IWR1,' ',ILM1,' S. RECORDS'
ENDIF
WRITE(1,*) '*****'
WRITE(6,300)
WRITE(6,*) '*****'
WRITE(6,*) '***LETTI DA',ITAPE,' ',NFI-NIN+1,' R. RECORDS'
IF(IPRINT.EQ.1) THEN
  WRITE(6,*) '*****'
  WRITE(6,*) 'SCRITTI SU',IWR,' ',IRC,' R. RECORDS'
ENDIF
IF(IPRINT2.EQ.1) THEN
  WRITE(6,*) '*****'
  WRITE(6,*) 'IMMAGAZZINATI SU',ITAPE1,' ',ILM2,' S. RECORDS'
ENDIF
IF(IPRINT1.EQ.1) THEN
  WRITE(6,*) '*****'
  WRITE(6,*) 'SCRITTI SU',IWR1,' ',ILM1,' S. RECORDS'
ENDIF
WRITE(6,*) '*****'

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WRITE(1,900)
900 FORMAT(1X,/,50'*','FINE REGOLARE DELL''ANALISI')
REWIND ITAPE
REWIND ITAPE1
STOP
C
C ERRORE DI DECODIFICA
20 WRITE(1,*) '**ERRORE DI DECODIFICA**'
STOP
C
C ERRORE IN EOF
30 WRITE(1,*) 'ERRORE SU',ITAPE1,' IN EOF #',KKK
STOP
C
C FINE DEL MAIN
END
C
C *****
C QUESTA SUBROUTINE SLITTA L'INDICE DI POSIZIONE NEL BUFFER
C E LO DECODIFICA SE QUESTO E' PIENO
SUBROUTINE CONTROLLO(LMAT)
C
C DICHIARAZIONI
COMMON ISK1(240),IP,IRM,IRC,IC3,IPRINT1,IPRINT2,ITAPE1
COMMON IWR1,NIN,ILM1,ILM2
INTEGER*4 LMAT(160,15)
INTEGER*4 LYD,LHMS,LTRM,LE,LB,LFRQ
DOUBLE PRECISION DTIM,DOBS,DFRQ,DPAS,DCOM,DRTL,DHRG,DDEC,DAZM
DOUBLE PRECISION DELV,DG1,DGM3,DGM1,DRES,DRJC,DWGH,DCRS,DMOD
CHARACTER A1,A2,A3,A4,A(10)
C
C SLITTAMENTO DELL' INDICE DI POSIZIONE NEL BUFFER
IP=IP+24
C
C CONTROLLO SUL RIEMPIMENTO DEL BUFFER
IF(IP.EQ.481) THEN
C
C IL BUFFER E' PIENO: CONTIENE TUTTI I DATI RELATIVI AD UNA MISURA
C SI EFFETTUA LA DECODIFICA
IP=1
DECODE(480,100,ISK1,ERR=900) DTIM,A1,LYD,LHMS,(A(K),K=1,10),
+IB,IT,IR,IM,A2,A3,A4,DOBS,DFRQ,DPAS,DCOM,DRTL,DHRG,DDEC,DAZM,
+DELV,DG1,DGM3,DGM1,DRES,DRJC,DWGH,DCRS,DMOD
100 FORMAT(D24.18,A2,15,I7,10A2,4I2,3A2,17D24.18)
C
C CONTROLLO SULLA BONTA' DEI DATI
IF(DRJC.NE.O.DO.DR.DWGH.NE.O.DO) THEN
ICO=IRC+NIN-1
WRITE(1,*) ' RECORD #',ICO,IC3
WRITE(1,*) ' ERRORE NEI DATI: REJCOD =',DRJC,' WEIGHT =',DWGH
WRITE(1,*) ' ----- '
ENDIF
C

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C ELABORAZIONE DEI DATI
  LHMS=LHMS/10.
  LTRM=IT*10000.+IR*100.+IM
  CALL ELEV(IT,DHRG,DDEC,EL)
  IELUP=DG1*100.
  IELDW=EL*100.
  LE=IELUP*10000.+IELDW
  LB=DRES*1000000.
  LFRQ=DFRQ

C
C TRASFERIMENTO DEI DATI NEL BUFFER DI USCITA
  IF(LMAT(IRM,1).EQ.LYN.AND.LMAT(IRM,2).EQ.LHMS.AND.LMAT(IRM,3)
    + .EQ.LFRQ.AND.LMAT(IRM,4).EQ.LTRM.AND.LMAT(IRM,5).EQ.LE) THEN
C
C MISURA CONTEMPORANEA ALLA PRECEDENTE
  IF(IB.EQ.11) THEN
C S-BAND
  LMAT(IRM,6)=LB
  LMAT(IRM,9)=DOBS
  ELSE
C X-BAND
  LMAT(IRM,7)=LB
  LMAT(IRM,10)=DOBS
  IF(IB.NE.21) THEN
    LMAT(IRM,12)=999999999
  ELSE
    TBD=LMAT(IRM,6)-3./11.*LMAT(IRM,7)
    LMAT(IRM,8)=TBD
  ENDIF
ENDIF
ELSE

C TRASFERIMENTO IN UNA NUOVA RIGA DEL BUFFER LMAT
  IRM=IRM+1
C
C CONTROLLO SUL RIEMPIMENTO DEL BUFFER DI USCITA
  IF(IRM.EQ.161) THEN
    IF(IPRINT2.EQ.1) THEN
      ILM2=ILM2+1
      CALL XTAPE(2,ITAPE1,LMAT,4800,LEN)
      IF(LEN.NE.4800) THEN
        WRITE(1,*) 'ERRORE IN SCRITTURA SU',ITAPE1
        WRITE(1,*) 'LMAT #',ILM2,' LUN =',LEN
      ENDIF
      WRITE(1,*) '**SCRITTO SU',ITAPE1,' S. RECORD #',ILM2
    ENDIF
    IF(IPRINT1.EQ.1) THEN
      ILM1=ILM1+1
      WRITE(1,*) 'SCRITTURA SU',IWR1,' S. RECORD #',ILM1
      DO 1 MM=1,160
        WRITE(IWR1,200) MM,(LMAT(MM,NN),NN=1,15)
1      FORMAT(I3,I6,I7,I9,I7,I9,I8,I9,I6,I7,I8,SI7)
200      ENDIF
      DO 2 MM=1,160

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        DO 2 NN=1,15
2       LMAT(MM,NN)=0
        IRM=1
        ENDIF
C
C MISURA NON CONTEMPORANEA ALLA PRECEDENTE
        LMAT(IRM,1)=LYD
        LMAT(IRM,2)=LHMS
        LMAT(IRM,3)=DFRQ
        LMAT(IRM,4)=LTRM
        LMAT(IRM,5)=LE
        LMAT(IRM,11)=DRJC*10.**6
        LMAT(IRM,12)=DWGH*10.**6
        IF(IBM.EQ.11) THEN
C S-BAND
                LMAT(IRM,6)=LB
                LMAT(IRM,9)=DOBS
                ELSE
C X-BAND
                LMAT(IRM,7)=LB
                LMAT(IRM,10)=DOBS
        ENDIF
        ENDIF
C
C RITORNO AL MAIN
        ENDIF
        RETURN
C
C ERRORE DI DECODIFICA DEL BUFFER
900 WRITE(1,*) '**ERRORE DI DECODIFICA DEL RECORD**'
        STOP
C
C FINE DI CONTROLLO
        END
C
C *****
C QUESTA ROUTINE CALCOLA L' ELEVAZIONE
        SUBROUTINE ELEV(IT,DHRG,DDEC,EL)
C
C DICHIARAZIONI
        DOUBLE PRECISION DHRG,DDEC
C
C RICERCA DELLA LATITUDINE DELLA STAZIONE IN QUESTIONE
        IF(IT.EQ.12) THEN
                LATD=35
                LATP=17
                ELSE
                IF(IT.EQ.14) THEN
                        LATD=35
                        LATP=25
                ELSE
                IF(IT.EQ.42) THEN
                        LATD=-35

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LATP=24
      ELSE
IF(IT.EQ.43) THEN
  LATD=-35
  LATP=24
      ELSE
IF(IT.EQ.61) THEN
  LATD=40
  LATP=25
      ELSE
IF(IT.EQ.63) THEN
  LATD=40
  LATP=25
ENDIF
ENDIF
ENDIF
ENDIF
ENDIF
ENDIF
C
C CALCOLO L' ELEVAZIONE
PIG=3.141592654
CON=PIG/180.
IF(LATD.GT.0) THEN
  ALAT=CON*(LATD+LATP/60.)
      ELSE
  ALAT=CON*(LATD-LATP/60.)
ENDIF
RHRG=DHRG*CON
RDEC=DDEC*CON
SINEL=COS(RDEC)*COS(ALAT)*COS(RHRG)+SIN(RDEC)*SIN(ALAT)
EL=ASIN(SINEL)
EL=EL/CON
C
C RITORNO AL MAIN
RETURN
C
C FINE DI ELEV
END

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FTN7X,S

```
C
      PROGRAM  .STATREGRESS(),                (880329.1415)
C
C *****
C *  LISTA RIASSUNTIVA DEI DATI STANDARD      *
C *****
C *
C *  QUESTO PROGRAMMA OPERA SUI DATI STANDARD *
C *
C *  ESSO PRODUCE IN USCITA UNA LISTA RIASSUNTIVA DEL NUMERO *
C *  DI DATI STANDARD SEPARANDOLI, PER OGNI GIORNO DI DATI *
C *  RICHIESTO, PER ORA, STAZIONE, BANDA E MODO DI COLLEGAMENTO *
C *
C *****
C
C
C DICHIARAZIONI
      INTEGER*4  LMAT(160,15),IYD,ZERO
      DIMENSION  NATR(48,24)
      CHARACTER  B
C
C INFORMAZIONI DI INGRESSO/USCITA
      WRITE(1,100)
100  FORMAT(1X,20/,80'*)
      WRITE(1,*) ' LISTA RIASSUNTIVA DEI DATI STANDARD'
      WRITE(1,*) ' *****'
      WRITE(1,*)
      WRITE(1,*) ' QUESTO PROGRAMMA PRODUCE ITERATIVAMENTE,'
      WRITE(1,*) ' PER OGNI GIORNO DI DATI STANDARD RICHIESTO,'
      WRITE(1,*) ' UNA LISTA RIASSUNTIVA DEL NUMERO DI DATI'
      WRITE(1,*) ' SEPARANDOLI PER ORA, STAZIONE, BANDA E MODO.'
      WRITE(1,101)
101  FORMAT(1X,/,80'*,/)
10  WRITE(1,('("NASTRO DI LETTURA (ENTER 8 OR 9) #: ")'))
      READ(1,*) ITAPE
      IF(ITAPE.NE.8.AND.ITAPE.NE.9) GO TO 10
      REWIND ITAPE
30  WRITE(1,('("GIORNO INIZIALE (DA 1 TO 365): ")'))
      READ(1,*) IDAYI
      IF(IDAYI.LE.0.OR.IDAYI.GE.366) GO TO 30
40  WRITE(1,('("GIORNO FINALE (DA 1 TO 365) #: ")'))
      READ(1,*) IDAYF
      IF(IDAYF.LE.0.OR.IDAYF.GE.366) GO TO 40
50  WRITE(1,('("ANNO:19 ")'))
      READ(1,*) IYEAR
      IF(IYEAR.GE.100) GO TO 50
      WRITE(1,('("STAMPANTE #: ")'))
      READ(1,*) IWR
      ZERO=0
C
C PER CIASCUN GIORNO RICHIESTO
      DO 8 ID=IDAYI, IDAYF
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        IYD=IYEAR*1000.+ID
C
C INIZIALIZZAZIONE
      NRC=0
      DO 1 II=1,24
        DO 1 JJ=1,48
          1 NATR(JJ,II)=0
          CALL EXEC(3,ITAPE+0200B)
          IPAGE=12
          WRITE(IWR,200) IPAGE
        200 FORMAT(A2)
C
C LETTURA DI UN RECORD
      2 CALL XTAPE(1,ITAPE,LMAT,4800,LEN)
      NRC=NRC+1
      IF(LEN.EQ.-1) THEN
        WRITE(1,*) 'EOF IN LETTURA'
        GO TO 60
      ENDIF
      IF(LEN.NE.4800) WRITE(1,*) '**ERRORE IN LETTURA: LUN.=' ,LEN
C
C PER CIASCUNA RIGA DEL RECORD
      DO 3 I=1,160
        IRG=I
C
C RICERCA DEL GIORNO RICHIESTO
      IGO=LMAT(I,1)-IYD
      IF(IGO.LT.0) GO TO 3
      IF(IGO.GT.0) GO TO 60
C
C ANALISI DEI DATI PER LA MTRICE
      IRM=LMAT(I,4)-LMAT(I,4)/10000*10000
      IR=IRM/100
      IM=IRM-IR*100-10
      IF(IR.EQ.12) THEN
        IRR=1
      ELSE
        IF(IR.EQ.14) THEN
          IRR=2
        ELSE
          IF(IR.EQ.42) THEN
            IRR=3
          ELSE
            IF(IR.EQ.43) THEN
              IRR=4
            ELSE
              IF(IR.EQ.61) THEN
                IRR=5
              ELSE
                IF(IR.EQ.63) IRR=6
              ENDIF
            ENDIF
          ENDIF
        ENDIF
      ENDIF
    ENDIF
  ENDIF

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        ENDIF
        ENDIF
        IH=LMAT(I,2)/10000
        IMS=LMAT(I,2)-IH*10000
        IBT=IH*60+IMS/100+1
C
C RIEMPIMENTO DELLA LISTA
        I2=(IBT-1)/60.+1
        IB=1
        I1=(IRR-1)*8+(IM-1)*2+IB
        IF(LMAT(I,6).NE.ZERO) NATR(I1,I2)=NATR(I1,I2)+1
        IB=2
        I1=(IRR-1)*8+(IM-1)*2+IB
        IF(LMAT(I,7).NE.ZERO) NATR(I1,I2)=NATR(I1,I2)+1
C
C SI RIPETE PER UN'ALTRA RIGA
        3 CONTINUE
C
C SI RIPETE PER UN ALTRO RECORD
        GO TO 2
C
C FINE DELLA RICERCA DEI DATI
        60 IYEAR1=LMAT(IRG,1)/1000.
        IDAY1=LMAT(IRG,1)-IYEAR1*1000.
        WRITE(1,*) 'FINE RICERCA IL',IDAY1,' DELL' ' ANNO ',IYEAR1
C
C SCRITTURA DELLA MATRICE DI USCITA
        DO 4 JJ=1,48
            DO 4 II=1,24
                IF(NATR(JJ,II).NE.0) IPRINT1=1
4 CONTINUE
                IF(IPRINT1.EQ.1) THEN
                    IPRINT1=0
                    WRITE(IWR,300)
300 FORMAT(2X,132'.',/,/)
                    WRITE(IWR,400) IYEAR, ID
400 FORMAT(2X,'YEAR = ',I3,5X,'DAY = ',I4,9X,'HOUR = 0 1 2 3 4'
*, ' 5 : 6 7 8 9 10 11 : 12 13 14 15 16 17 : 18'
*, ' 19 20 21 22 23 NS DAY',/,/)
                    DO 7 JJ=1,48
                        DO 5 II=1,24
5 IF(NATR(JJ,II).NE.0) IPRINT=1
                        IF(IPRINT.EQ.1) THEN
                            IPRINT=0
                            IS=(JJ-1)/8.+1
                            IF(IS.EQ.1) THEN
                                ISS=12
                                    ELSE
                                IF(IS.EQ.2) THEN
                                    ISS=14
                                        ELSE
                                IF(IS.EQ.3) THEN
                                    ISS=42

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```

                ELSE
                IF(IS.EQ.4) THEN
                    ISS=43
                ELSE
                IF(IS.EQ.5) THEN
                    ISS=61
                ELSE
                IF(IS.EQ.6) ISS=63
                ENDIF
            ENDIF
        ENDIF
    ENDIF
ENDIF
IP=JJ/2.
IF(IP*2.EQ..JJ) THEN
    B='X'
    IBB=2
ELSE
    B='S'
    IBB=1
ENDIF
IMM=(JJ-IBB-(IS-1)*8)/2+1
ITOT=0
DO 6 LL=1,24
6   ITOT=ITOT+NATR(JJ,LL)
   IF(IS1.NE.IS) WRITE(IWR,*)
   IS1=IS
   WRITE(IWR,500) ISS,B,IMM,(NATR(JJ,LL),LL=1,24),ITOT
500 FORMAT(2X,'DOP' :   DSS =',I3,'      Band-Mode ',A1,I2,4X,6I3,
*,', ' : ',6I3,' : ',6I3,' : ',6I3,I8)
   ENDIF
7   CONTINUE
   WRITE(IWR,*)
   WRITE(IWR,300)
ENDIF
C
C SI RIPETE PER UN ALTRO GIORNO
   IF(LEN.EQ.-1) GO TO 70
8   CONTINUE
C
C FINE REGOLARE DELL' ANALISI
70 WRITE(IWR,200) IPAGE
   WRITE(IWR,200) IPAGE
   WRITE(1,*)
   WRITE(1,*) '**FINE REGOLARE DELL' ANALISI**'
   STOP
C
C FINE DEL MAIN
END

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FTN7X,5

C

PROGRAM PLOTREGRESS(),

(880329.1415)

C

```
C *****
C * TRACCIAMENTO SEQUENZIALE DEI DATI STANDARD *
C *****
C *
C * QUESTO PROGRAMMA OPERA SUI DATI STANDARD *
C *
C * ESSO TRACCA TUTTI I DATI RELATIVI AL GIORNO, ALLA STAZIONE ED *
C * AL MODO RICHIESTO. *
C * QUESTI VENGONO TRACCIATI SEPARATI PER BANDA IN TRE GRAFICI *
C * NEL MASSIMO FORMATO. *
C * *
C *****
```

C

C DICHIARAZIONI

```
EMA(50),BX(720),BD(720),BT(720)
INTEGER*4 LMAT(160,15),IYD
DIMENSION V(29),IST(6),IMODE(4)
CHARACTER*50 N1,N2
INTEGER YN6
CHARACTER*2 ANNO
```

C

C ESEGUIBILE

C INFORMAZIONI PER INGRESSO/USCITA

```
WRITE(1,100)
100 FORMAT(1X,20/,80'*,/)
WRITE(1,*) ' TRACCIAMENTO SEQUENZIALE DEI DATI STANDARD'
WRITE(1,*) ' *****'
WRITE(1,*)
WRITE(1,*)
WRITE(1,*) ' QUESTO PROGRAMMA TRACCA TUTTI I DATI'
WRITE(1,*) ' RELATIVI A CIASCUN GIORNO RICHIESTO'
WRITE(1,*) ' IN SUCCESSIONE PER STAZIONI E MODI'
WRITE(1,*)
WRITE(1,*) ' I GRAFICI SONO 3 PER OGNI FOGLIO'
WRITE(1,*) ' IL FORMATO E' IL MASSIMO'
WRITE(1,*)
WRITE(1,*) ' '
WRITE(1,*) ' PENNINI DEL PLOTTER:'
WRITE(1,*) ' 1: PER LE INTSTAZIONI'
WRITE(1,*) ' 2: COMPLESSO 10'
WRITE(1,*) ' 3: COMPLESSO 40'
WRITE(1,*) ' 4: COMPLESSO 60'
WRITE(1,*)
WRITE(1,101)
101 FORMAT(1X,/,80'*,/)
10 WRITE(1,('NASTRO DI LETTURA (8 0 9) #: "'))
READ(1,*) ITAPE
IF(ITAPE.NE.8.AND.ITAPE.NE.9) GO TO 10
REWIND ITAPE
```

```

30 WRITE(1,('GIORNO INIZIALE (DA 1 A 365) #: ')')
   READ(1,*) IDAYI
   IF(IDAYI.LE.0.OR.IDAYI.GE.366) GO TO 30
40 WRITE(1,('GIORNO FINALE (DA 1 A 365) #: ')')
   READ(1,*) IDAYF
   IF(IDAYF.LE.0.OR.IDAYF.GE.366) GO TO 40
50 WRITE(1,('ANNO: 19 '))
   READ(1,*) IYEAR
   IF(IYEAR.GE.100) GO TO 50
   WRITE(ANNO,102) IYEAR
102 FORMAT(I2)
   WRITE(1,('VUOI L' ECO SULLA 6? <Y=1>: ')')
   READ(1,*) YN6
   IF(YN6.EQ.1) THEN
     IPAGE=12
     WRITE(6,200) IPAGE
200 FORMAT(A2)
   ENDIF
   NR=0
   NM=0
   DO I=1,6
     NR=NR+1
     WRITE(1,*) '***** 0 PER TERMINARE'
     WRITE(1,('STAZIONE RICEVENTE? <12,14,42,43,61,63>: ')')
     READ(1,*) IST(NR)
     IF(IST(NR).EQ.0) THEN
       NR=NR-1
       GO TO 60
     ENDIF
     IF(IST(NR).NE.12.AND.IST(NR).NE.14.AND.IST(NR).NE.42.AND.
+IST(NR).NE.43.AND.IST(NR).NE.61.AND.IST(NR).NE.63) THEN
       NR=NR-1
       WRITE(1,*)
       WRITE(1,*) '*****STAZIONE NON RICONOSCIUTA!*****'
     ENDIF
   END DO
60 DO I=1,4
   NM=NM+1
   WRITE(1,*) '***** 0 PER TERMINARE'
   WRITE(1,('MODO RICHIESTO? <DA 1 A 4>: ')')
   READ(1,*) IMODE(NM)
   IF(IMODE(NM).EQ.0) THEN
     NM=NM-1
     GO TO 70
   ENDIF
   IF(IMODE(NM).LT.1.OR.IMODE(NM).GT.4) THEN
     NM=NM-1
     WRITE(1,*)
     WRITE(1,*) '*****MODO NON RICONOSCIUTO!*****'
   ENDIF
   END DO
70 CONTINUE

```

C

```

C PER CIASCUN GIORNO RICHIESTO
DO 7 ID=IDAYI, IDAYF
IYD=IYEAR*1000.+ID
C
C PER CIASCUN MODO RICHIESTO
DO 5 IMM=1, NM
IM=IMADF(IMM)
C
C PER CIASCUNA STAZIONE RICHIESTA
DO 6 K=1, NR
IS=IST(K)
C
C INIZIALIZZAZIONE
IPD=0
NRC=0
DO 1 I=1, 720
BS(I)=0.
BX(I)=0.
BD(I)=0.
BT(I)=0.
1 CONTINUE
IF(YNG.EQ.1) THEN
WRITE(6,*)
WRITE(6,*)
WRITE(6,*) 'DOY =', ID, ' ANNO =', IYEAR, ' STAZIONE RIC.=', IS,
+' MODO =', IM
WRITE(6,*)
WRITE(6,*) 'MINUTO S-BAND X-BAND NON RIPORTATE'
ENDIF
WRITE(1,*) 'DOY =', ID, ' ANNO =', IYEAR, ' STAZIONE RIC.=', IS,
+' MODO =', IM
REWIND ITAPE
C
C LEGGE UN RECORD
2 CALL XTAPE(1, ITAPE, LMAT, 4800, LEN)
NRC=NRC+1
IF(LEN.NE.4800) THEN
IF(LEN.EQ.-1) THEN
WRITE(1,*) '**EOF SU NASTRO', ITAPE
GO TO 4
ELSE
WRITE(1,*) '**ERRORE IN LETTURA: LUN=', LEN, ' SU ', ITAPE
END IF
END IF
C
C PER TUTTE LE RIGHE DEL BUFFER
DO 3 I=1, 160
IRG=I
C
C RICERCA DEL GIORNO RICHIESTO
IGD=LMAT(I, 1)-IYD
IF(IGD.LT.0) GO TO 3
IF(IGD.GT.0) GO TO 4

```

```

C
C CONTROLLO DEL MODO E DELLA STAZIONE
  IRM=LMAT(I,4)-LMAT(I,4)/10000*10000
  IR=IRM/100
  IM1=IRM-IR*100-10
C
C SE IL DATO E' QUELLO CERCATO
  IF(IM.EQ.IM1.AND.IS.EQ.IR) THEN
C
C IMMAGAZZINAMENTO DEL DATO PER LA GRAFICA
  IPO=IPO+1
  BS(IPO)=LMAT(I,6)/1000000.
  IF(BS(IPO).GT..5) BS(IPO)=.5
  IF(BS(IPO).LT.-.5) BS(IPO)=-.5
  BX(IPO)=LMAT(I,7)/1000000.
  IF(BX(IPO).LT.-2.5) BX(IPO)=-2.5
  IF(BX(IPO).GT.2.5) BX(IPO)=2.5
  BD(IPO)=LMAT(I,8)/1000.
  IF(BD(IPO).GT.20) BD(IPO)=20
  IF(BD(IPO).LT.-20) BD(IPO)=-20
  IH=LMAT(I,2)/10000
  IMS=LMAT(I,2)-IH*10000
  BT(IPO)=IH*60+IMS/100+1
  IF((BS(IPO).EQ.0.OR.BX(IPO).EQ.0).AND.YN6.EQ.1) THEN
300   WRITE(6,300) BT(IPO),LMAT(I,6),LMAT(I,7)
      FORMAT(2X,F5.0,I11,I11)
      IPO=IPO-1
      ENDIF
      ENDIF
C
C SI RIPETE PER UN' ALTERA RIGA
  3 CONTINUE
C
C SI RIPETE PER UN ALTRO RECORD
  GO TO 2
C
C FINE RICERCA DEI DATI
  4 IYEAR1=LMAT(IRG,1)/1000.
  IDAY1=LMAT(IRG,1)-IYEAR1*1000
  WRITE(1,*) 'FINE RICERCA IL:',IDAY1,' DELL'' ANNO',IYEAR1
C
C IN ASSENZA DI DATI NON SI TRACCIA IL GRAFICO
  IF(BT(1).EQ.0) THEN
    WRITE(1,*) '**NON CI SONO DATI PER QUESTO INGRESSO**'
    IF(YN6.NE.1) GO TO 6
    WRITE(6,*) '**NON CI SONO DATI DA GRAFICARE PER QUESTO INPUT**'
    GO TO 6
      ELSE
    WRITE(1,*) '**GRAFICI IN USCITA:',IPO,' PUNTI**'
    IF(YN6.EQ.1) THEN
      WRITE(6,*) '**GRAFICI IN USCITA:',IPO,' PUNTI'
    ENDIF
  ENDIF
ENDIF

```

C

C TRACCIAMENTO GRAFICI

```
V(1)=0
V(2)=-.5
V(3)=.5
V(4)=0
V(5)=0
V(6)=1440
V(7)=50
V(8)=30
V(9)=350
V(10)=90
V(11)=2
V(12)=3
V(13)=60.
V(14)=.02
V(15)=4
V(16)=5
V(17)=1
V(18)=0
V(19)=0
V(20)=0
V(21)=0
V(22)=1
V(23)=3
V(24)=4
IF(IS.EQ.12.OR.IS.EQ.14) V(25)=2
IF(IS.EQ.42.OR.IS.EQ.43) V(25)=3
IF(IS.EQ.61.OR.IS.EQ.63) V(25)=4
V(26)=1
V(27)=1
V(28)=0
V(29)=1
WRITE(1,*) 'TRACCIAMENTO PRIMO GRAFICO'
CALL SETPAR(V,N1,N2)
CALL EGRAPHY(BT,BS,IPO,1.,0,1)
WRITE(1,*) 'TRACCIATO PRIMO GRAFICO'
N2=' '
N1=' X-BAND [Hz]'
V(2)=-2.5
V(3)=2.5
V(8)=100
V(10)=160
V(14)=.1
WRITE(1,*) 'TRACCIAMENTO SECONDO GRAFICO'
CALL SETPAR(V,N1,N2)
CALL EGRAPHY(BT,BX,IPO,1.,0,1)
WRITE(1,*) 'TRACCIATO SECONDO GRAFICO'
N2=' '
N1='S-3/11*X [mHz]'
V(2)=-20.
V(3)=20.
V(8)=170
```



```
V(10)=230
V(14)=1
WRITE(1,*) 'TRACCIAMENTO TERZO GRAFICO'
CALL SETPAR(V,N1,N2)
CALL EGRAPHY(BT,BD,IPO,1.,0,1)
WRITE(1,*) 'TRACCIATO TERZO GRAFICO'
```

```
C
C SI RIPETE PER UN' ALTRA STAZIONE
  IF(YN6.EQ.1) WRITE(6,200) IPACE
  6 CONTINUE
```

```
C
C COMPLETAMENTO DEL GRAFICO
N2=' VOYAGER 19'//ANNO//' REGRESS FILES'
N1=' S-BAND [Hz]'
V(1)=0
V(2)=-.5
V(3)=.5
V(4)=0
V(5)=0
V(6)=1440
V(7)=50
V(8)=30
V(9)=350
V(10)=90
V(11)=2
V(12)=3
V(13)=60.
V(14)=.02
V(15)=4
V(16)=5
V(17)=1
V(18)=0
V(19)=1
V(20)=0
V(21)=1
V(22)=1
V(23)=3
V(24)=4
V(25)=0
V(26)=1
V(27)=1
V(28)=0
V(29)=1
WRITE(1,*) 'COMPLETAMENTO DEL GRAFICO'
CALL SETPAR(V,N1,N2)
CALL EGRAPHY(BT,BS,IPO,1.,0,1)
N2=' '
N1=' X-BAND [Hz]'
V(2)=-2.5
V(3)=2.5
V(8)=100
V(10)=160
V(14)=.1
```

```

CALL SETPAR(V,N1,N2)
CALL EGRAPHY(BT,BX,IPO,1.,0,1)
N2=' '
N1='S-3/11*X [mHz]'
V(2)=-20.
V(3)=20.
V(8)=170
V(10)=230
V(14)=1
CALL SETPAR(V,N1,N2)
CALL EGRAPHY(BT,BD,IPO,1.,0,1)
CALL ZDLIM(0.,370.,0.,280.,IERR)
IF(IERR.NE.0) WRITE(1,*) 'ZDLIM ERROR #',IERR
CALL ZASPK(370.,280.)
CALL ZVIEW(0.,370.,0.,280.)
CALL ZWIND(0.,370.,0.,280.)
CALL ZCOLR(1)
CALL SYMBOL(43.,25.,-2.,'00.00',0.,5)
CALL SYMBOL(93.,25.,-2.,'04.00',0.,5)
CALL SYMBOL(143.,25.,-2.,'08.00',0.,5)
CALL SYMBOL(193.,25.,-2.,'12.00',0.,5)
CALL SYMBOL(243.,25.,-2.,'16.00',0.,5)
CALL SYMBOL(293.,25.,-2.,'20.00',0.,5)
CALL SYMBOL(343.,25.,-2.,'24.00',0.,5)
CALL SYMBOL(38.,30.,-2.,'-.5',0.,3)
CALL SYMBOL(35.,100.,-2.,'-2.5',0.,4)
CALL SYMBOL(38.,170.,-2.,'-20.',0.,4)
FDAY=FLOAT(ID)
FDSS=FLOAT(IS)
FMOD=FLOAT(IM)
CALL SYMBOL(70.,260.,-3.,'DAY =',0.,5)
CALL NUMBER(95.,260.,-4.,FDAY,0.,3,'(I3)')
IF(NR.EQ.1) THEN
  CALL NUMBER(155.,260.,-4.,FDSS,0.,2,'(I2)')
  CALL SYMBOL(130.,260.,-3.,'DSS =',0.,5)
ENDIF
CALL SYMBOL(190.,260.,-3.,'MODE =',0.,6)
CALL NUMBER(220.,260.,-4.,FMOD,0.,1,'(I1)')
CALL ZNEWF

C
C SI RIPETE PER UN ALTRO MODO
  5 CONTINUE

C
C SI RIPETE PER UN ALTRO GIORNO
  7 CONTINUE

C
C DISATTIVAZIONE DEL PLOTTER
  CALL ZDEND
  CALL ZEND

C
C FINE REGOLARE DELL' ANALISI
  WRITE(1,*)
  WRITE(1,*) '**FINE REGOLARE DELL' ANALISI**'

```

REWIND ITAPE
STOP

C
C. FINE DEL MAIN
END

FTN7X,S
\$FILES(0,1)

```
C
C      PROGRAM FFREGRESS(),                (880329.1415)
C
C *****
C * CREAZIONE DI DISC FILES DEI DATI STANDARD *
C *****
C *
C * QUESTO PROGRAMMA OPERA SUI DATI STANDARD *
C *
C *
C * ESSO CREA DISC FILES A PARTIRE DAI DATI IMMAGAZZINATI SU NASTRO *
C * CIASCUN FILE CONTIENE DATI RELATIVI AD UN SINGOLO PASSAGGIO *
C * AVENDO CIOE' FISSATO LE STAZIONI ATTIVE, IL MODO ED IL GIORNO *
C * DELL'INIZIO DEL PASSAGGIO *
C * IL FILE CONTIENE TUTTI I DATI NELLE BANDE S E X E LA FREQUENZA *
C * DELL' OSCILLATORE. *
C *
C * N.B. SI E' ASSUNTO CHE FRA UN PASSAGGIO E L'ALTRO CI SIANO 8 ORE *
C *
C *****
C DICHIARAZIONI
C      INTEGER*4 LMAT(160,15), ISTORE(3,730), ANGDAT(120,6)
C      INTEGER*4 IYEAR, IYD, ZERO
C      DIMENSION IDSR(6), IDST(6), IMODE(4)
C      CHARACTER*3 NY
C      COMMON IPO, IPOS, IPOX, IAUTO, ISTORE, ANGDAT, LU
C
C ESEGUIBILE
C INFORMAZIONI DI INGRESSO/USCITA
C      WRITE(1,100)
100 FORMAT(1X,20/,80'*',/)
C      WRITE(1,*) '      CREAZIONE DI DISC FILES DEI DATI STANDARD'
C      WRITE(1,*) '      *****'
C      WRITE(1,*)
C      WRITE(1,*)
C      WRITE(1,*) '      QUESTO PROGRAMMA CREA DISC FILES A PARTIRE DAI'
C      WRITE(1,*) '      NASTRI STANDARD.'
C      WRITE(1,*) '      CIASCUN FILE CONTIENE DATI RELATIVI AD UN SINGOLO'
C      WRITE(1,*) '      PASSAGGIO NELLE DUE BANDE S E X E LA FREQUENZA'
C      WRITE(1,*) '      DELL' OSCILLATORE.'
C      WRITE(1,200)
200 FORMAT(1X,/,80'*',/)
C      10 WRITE(1,*) '***PARAMFTRI PER L'' ANALISI:'
C      WRITE(1,('NASTRO IN LETTURA (8 0 9) #: '))
C      READ(1,*) ITAPE
C      IF(ITAPE.NE.8.AND.ITAPE.NE.9) GO TO 10
C      REWIND ITAPE
C      WRITE(1,('QUANTI RECORDS? : '))
C      READ(1,*) NFI
C      WRITE(1,('VUOI L''ANALISI AUTOMATICA? <1=SI>: '))
```

```

READ(1,*) IAUTO
WRITE(1,('("STAMPANTE #: ")'))
READ(1,*) LU
IF(LU.NE.1) THEN
  WRITE(LU,300)
300 FORMAT(5X,'FILE NAMES',6X,'IN DAY   FIN DAY',6X,
+'YEAR   IN MIN   FIN MIN',6X,'MODE   TRS DSS   REC DSS',
+5X,'R ASC',7X,'DEC',6X,'RTLTL')
  WRITE(LU,*)
ENDIF
20 WRITE(1,('("GIORNO INIZIALE? <DA 1 A 365>: ")'))
READ(1,*) IDAYI
IF(IDAYI.LT.1.OR.IDAYI.GT.365) GO TO 20
30 WRITE(1,('("DELL' 'ANNO: 19 ")'))
READ(1,*) IYEAR
IF(IYEAR.GT.99.OR.IYEAR.LT.1) GO TO 30
ZERO=0
NR=0
NT=0
NM=0
DO 1 I=1,6
  NR=NR+1
  WRITE(1,*) '**** 0 PER TERMINARE'
  WRITE(1,('("STAZIONE RICEVENTE? <12,14,42,43,61,63>: ")'))
  READ(1,*) IDSR(NR)
  IF(IDSR(NR).EQ.0) THEN
    NR=NR-1
    GO TO 40
  ENDIF
  IF(IDSR(NR).NE.12.AND.IDSR(NR).NE.14.AND.IDSR(NR).NE.42.AND.
+IDSR(NR).NE.43.AND.IDSR(NR).NE.61.AND.IDSR(NR).NE.63) THEN
    NR=NR-1
    WRITE(1,*)
    WRITE(1,*) '****STAZIONE NON RICONOSCIUTA!*****'
  ENDIF
1 CONTINUE
40 DO 2 I=1,4
  NM=NM+1
  WRITE(1,*) '**** 0 PER TERMINARE'
  WRITE(1,('("MODO? <DA 1 A 4>: ")'))
  READ(1,*) IMODE(NM)
  IF(IMODE(NM).EQ.0) THEN
    NM=NM-1
    GO TO 50
  ENDIF
  IF(IMODE(NM).LT.1.OR.IMODE(NM).GT.4) THEN
    NM=NM-1
    WRITE(1,*)
    WRITE(1,*) '****MODO NON RICONOSCIUTO!*****'
  ENDIF
2 CONTINUE
50 DO I=1,6
  NT=NT+1

```

```

WRITE(1,*) '**** 0 PER TERMINARE'
WRITE(1,('STAZIONE TRASMITTENTE? <12,14,42,43,61,63>: '))
READ(1,*) IDST(NT)
IF(IDST(NT).EQ.0) THEN
  NT=NT-1
  GO TO S1
ENDIF
IF(IDST(NT).NE.12.AND.IDST(NT).NE.14.AND.IDST(NT).NE.42.AND.
+IDST(NT).NE.43.AND.IDST(NT).NE.61.AND.IDST(NT).NE.63) THEN
  NT=NT-1
  WRITE(1,*)
  WRITE(1,*) '****STAZIONE NON RICONOSCIUTA'
ENDIF
END DO

C
C LEGGE I DATI ANGOLARI
S1 WRITE(1,*)
  WRITE(1,*) 'LETTURA FILE DAT/FILE#1'
  OPEN(70,FILE='DAT/FILE#1',IOSTAT=IOSO,STATUS='OLD',ERR=60)
  READ(70,*) ANG DAT
  CLOSE(70)
  GO TO 70
60 WRITE(1,*) 'ERRORE #',IOSO,' IN OPEN IL FILE DAT/FILE#1'
  WRITE(1,(' VUOI ABORTIRE IL PROGRAMMA? <Y/N>: '))
  READ(1,400) NY
400 FORMAT(A3)
  IF(NY.EQ.'Y'.OR.NY.EQ.'YES'.OR.NY.EQ.'1')
  +STOP '***FINE IRREGOLARE DELL' ANALISI***'
  GO TO 10

C
C SI FISSANO I PARAMETRI
70 DO 5 I1=1,NR
  IDSSR=IDSR(I1)
  IDSST=IDSSR
  I3=0
  DO 5 I2=1,NM
71  IMODES=IMODE(I2)
  IF(IMODES.GT.2) THEN
    I3=I3+1
    IF(I3.GT.NT) GO TO 5
    IDSST=IDST(I3)
    IF(IDSST.EQ.IDSSR) GO TO 71
  ENDIF
  WRITE(1,*)
  WRITE(1,*) 'RICERCA: MODO =',IMODES,' DSS RICEVENTE=',IDSSR,
+ ' DSS TRASMITTENTE=',IDSST

C
C INIZIALIZZAZIONE
REWIND ITAPE
IPQ=0
IPOS=0
IPOX=0
IBTF=0

```

```

        IBTA=0
        INIT=0
        NEWDAY=0
        IDAY=IDAYI
        DO 3 II=1,3
            DO 3 JJ=1,730
                ISTORE(II,JJ)=0
    3    CONTINUE
        IYD=IYEAR*1000.+IDAY
        ITC=480
C
C LEGGE UN RECORD
        WRITE(1,*)
        WRITE(1,*) 'LEGGENDO DAL NASTRO',ITAPE
        NRC=0
    1000 CALL XTAPE(1,ITAPE,LMAT,4800,LEN)
        NRC=NRC+1
        IF(LEN.EQ.-1) GO TO 2000
        IF(LEN.NE.4800) WRITE(1,*) '**ERRORE IN LETTURA: LUN=',LEN,'**'
C
C PER CIASCUNA RIGA DEL BUFFER
    90  CONTINUE
        DO 4 I=1,160
C
C RICERCE DEL GIORNO RICHIESTO
        IGO=LMAT(I,1)-IYD
        IF(IGO.LT.0) GO TO 4
        IF(IGO.GT.0) THEN
            IDAY=IDAY+1
            IYD=IYD+1
            IF(INIT.EQ.0) GO TO 90
            NEWDAY=1
            IBTA=1440-IBTF
            ISTORE(2,9)=IBTF
            IBTF=0
        ENDIF
C
C ANALISI DEI DATI
        IST=LMAT(I,4)/10000
        IRM=LMAT(I,4)-IST*10000
        ISR=IRM/100
        IM=IRM-ISR*100-10
        IH=LMAT(I,2)/10000
        IMS=LMAT(I,2)-IH*10000
        IBT=IH*60+IMS/100
C
C FINE DEL PASSAGGIO
        IF((IBT-IBTF+IBTA).GT.ITC) THEN
            CALL CREA
            NEWDAY=0
            IBTF=IBT
            IBTA=0
        ENDIF

```

```

C
C DATO DA TRASFERIRE NEL BUFFER DI USCITA
      IF(ISR.EQ.IDSSR.AND.IM.EQ.IMODES.AND.IST.EQ.IDSST) THEN
          IPO=IPO+1
C
C PRIMO DATO PER IL BUFFER DI USCITA (RIEMPIMENTO DELLA TESTATA)
      IF(IPO.EQ.1) THEN
          IF(IAUTO.NE.1) THEN
              WRITE(1,*)
              WRITE(1,*) 'DATI PER QUESTO INPUT'
          ENDIF
          ISTORE(1,8)=IDAY
          ISTORE(1,9)=IDAY
          ISTORE(2,8)=IBT
          ISTORE(3,1)=2
          ISTORE(3,2)=IYEAR
          ISTORE(3,3)=IDSST
          ISTORE(3,4)=IDSSR
          ISTORE(3,5)=IMODES
          INIT=1
          NEWDAY=0
          ENDIF
C
C IMMAGAZZINAMENTO DEI DATI
      IBTF=IBT
      ISTORE(1,9)=IDAY
      ISTORE(2,9)=IBT
      IT=IBT-ISTORE(2,8)+11
      IF(NEWDAY.EQ.1) IT=IT+1440
      IF(IT.GT.721) THEN
          WRITE(1,('VUOI ABORTIRE IL PROGRAMMA? (Y/N): '))
          READ(1,400) NY
          IF(NY.EQ.'Y'.OR.NY.EQ.'YES'.OR.NY.EQ.'1')
+STOP '** FINE IRREGOLARE DELL''ANALISI***'
          ENDIF
          ISTORE(1,IT)=LMAT(I,6)
          ISTORE(2,IT)=LMAT(I,7)
          ISTORE(3,IT)=LMAT(I,3)
C
C AGGIORNAMENTO DEI DATI NELLA TESTATA
      IF(LMAT(I,6).NE.ZERO) THEN
          IPOS=IPOS+1
          ISTORE(1,2)=JDAY
          ISTORE(1,4)=IBT
          ISTORE(1,7)=IT
          IF(IPOS.EQ.1) THEN
              ISTORE(1,1)=IDAY
              ISTORE(1,3)=IBT
              ISTORE(1,6)=IT
          ENDIF
      ENDIF
      IF(LMAT(I,7).NE.ZERO) THEN
          IPOX=IPOX+1

```



```

        ISTORE(2,2)=IDAY
        ISTORE(2,4)=IBT
        ISTORE(2,7)=IT
        IF(IPOX.EQ.1) THEN
            ISTORE(2,1)=IDAY
            ISTORE(2,3)=IBT
            ISTORE(2,6)=IT
        ENDIF
    ENDIF
ENDIF
C
C SI RIPETE PER UN'ALTRA RIGA
    4 CONTINUE
C
C SI RIPETE PER UN ALTRO RECORD
    IF(NRC.NE.NFI) GO TO 1000
C
C FINE RICERCA DEI DATI
    2000 CALL CREA
        IYEAR1=LMAT(160,1)/1000.
        IDAY1=LMAT(160,1)-IYEAR1*1000.
        WRITE(1,*)
        WRITE(1,*) 'FINE AL GIORNO:',IDAY1,' DELL''ANNO',IYEAR1
        WRITE(1,*)
C
C SI PROCEDE CON ALTRI PARAMETRI
    IF(I3.GT.0) GO TO 71
    5 CONTINUE
C
C OPZIONE PER RIPETERE L' ANALISI CON ALTRI DATI
    IF(IAUTO.EQ.1) WRITE(1,*) ''
        WRITE(LU,*)
        REWIND ITAPE
        WRITE(1,') ("VUOI IMMAGAZZINARE ALTRI DATI? <Y/N>: ")')
        READ(1,400) NY
        IF(NY.EQ.'Y'.OR.NY.EQ.'YES'.OR.NY.EQ.'1') GO TO 10
C
C FINE REGOLARE DELL'ANALISI
    REWIND ITAPE
    WRITE(1,*)
    WRITE(1,*) '**FINE REGOLARE DELL''ANALISI**'
    STOP
C
C FINE DEL MAIN
    END
C
C *****
C QUESTA SUBROUTINE CREA I DISK FILES
    SUBROUTINE CREA
C
    INTEGER*4 ISTORE(3,730),ANGDAT(120,6)
    CHARACTER*14 NFILE
    CHARACTER*3 NY

```

```

COMMON IPO,IPOS,IPOX,IAUTO,ISTORE,ANGDAT,LU
C
C SE CI SONO DATI
  IF(IPO.NE.0) THEN
    IF(IAUTO.NE.1) WRITE(1,*) 'CI SONO',IPO,' DATI'
C
C RICERCA DEI DATI ANGOLARI
  CALL SFARCH
C
C CREAZIONE DEL FILENAME
  WRITE(NFILE,100)ISTORE(3,3),ISTORE(3,4),ISTORE(1,8)
  100  FORMAT('DAT/ROD',I2,I2,I3)
C
C SALTO DELLE RICHIESTE DA INPUT SE IL LAVORO E' AUTOMATICO
  IF(IAUTO.EQ.1) THEN
    NY='YES'
    GO TO 10
  ENDIF
C
C SCRIVE IL DISC FILE RICHIESTO
  WRITE(1,*)
  WRITE(1,*) 'IL FILE ',NFILE,' CONTIENE I SEGUENTI DATI:'
  IF(ISTORE(3,1).EQ.2) WRITE(1,*) '***VALORI REGRESS'
  WRITE(1,*) '***BANDE: S, X E FREQUENZA'
  WRITE(1,*) '***GIORNO INIZIALE:',ISTORE(1,8)
  WRITE(1,*) '***GIORNO FINALE:',ISTORE(1,9)
  WRITE(1,*) '***ANNO:',ISTORE(3,2)
  WRITE(1,*) '***MINUTO INIZIALE:',ISTORE(2,8)
  WRITE(1,*) '***MINUTO FINALE:',ISTORE(2,9)
  WRITE(1,*) '***MODD:',ISTORE(3,5)
  WRITE(1,*) '***DSS TRASMITTENTE:',ISTORE(3,3)
  WRITE(1,*) '***DSS RICEVENTE:',ISTORE(3,4)
  WRITE(1,*) '***ASCENSIONE RETTA:',ISTORE(3,7)
  WRITE(1,*) '***DECLINAZIONE:',ISTORE(3,8)
  WRITE(1,*) '***RTLTL:',ISTORE(3,6)
  WRITE(1,*)
  WRITE(1,')(" OK AD IMMAGAZZINARE? <Y/N>: ")')
  READ(1,200) NY
  200  FORMAT(A3)
  IF(NY.EQ.'A') STOP '***FINE IRREGOLARE DELL'ANALISI***'
C
C SCRITTURA DEL FILE SE RICHIESTO
  10  IF(NY.EQ.'Y'.OR.NY.EQ.'YES'.OR.NY.EQ.'1') THEN
    IF(LU.NE.1) WRITE(LU,300) NFILE,ISTORE(1,8),ISTORE(1,9),
    +ISTORE(3,2),ISTORE(2,8),ISTORE(2,9),ISTORE(3,5),ISTORE(3,3),
    +ISTORE(3,4),ISTORE(3,7),ISTORE(3,8),ISTORE(3,6)
  300  FORMAT(1X,A16,11(I10))
    WRITE(1,*)
    WRITE(1,*) 'SCRITTURA DEL FILE ',NFILE
    ISTORE(1,5)=IPOS
    ISTORE(2,5)=IPOX
    ISTORE(3,9)=IPO
    OPEN(70,FILE=NFILE,IOSTAT=IOSD,ERR=20)

```

```

WRITE(70,*) ISTORE
CLOSE(70,IOSTAT=IOSC,ERR=30)
ELSE
WRITE(1,*) 'FILE ',NFILE,' NON CREATO'
ENDIF
C
C REINIZIALIZZAZIONE DEI BUFFERS
IPQ=0
IPOS=0
IPOX=0
DO 1 II=1,3
DO 1 JJ=1,730
ISTORF(II, JJ)=0
1 CONTINUE
ENDIF
C
C RITORNO AL MAIN
RETURN
C
C ERRORR IN OPEN FILE 70
20 WRITE(1,*) '**ERRORE IN OPEN FILE ',NFILE,' #',IOSO,'**'
STOP
C
C ERRORE IN CLOSE FILE 70
30 WRITE(1,*) '**ERRORE IN CLOSE FILE ',NFILE,' #',IOSC,'**'
STOP
C
C FINE DI CREA
END
C
C *****
C QUESTA SUBROUTINE CERCA I DATI ANGOLARI
SUBROUTINE SEARCH
C
INTEGER*4 ISTORE(3,730),ANGDAT(120,6)
INTEGER*4 SUMMIN,MINMED,IDHM,FDHM
CHARACTER*3 NY
COMMON IPO,IPOS,IPOX,IAUTO,ISTORE,ANGDAT,LU
C
C RICERCA DEI DATI ANGOLARI
SUMMIN=ISTORE(2,8)+ISTORE(2,9)+1.
IF(ISTORE(1,8).NE.ISTORE(1,9)) SUMMIN=SUMMIN+1440.
MINMED=SUMMIN/2
IF(MINMED.GT.1440) MINMED=MINMED-1440
D4=10000
I60=60
IDHM=ISTORE(1,8)*D4+MINMED/I60*100+MOD(MINMED,I60)
KK=0
DO 1 K=1,120
IF(ISTORE(3,2).LT.ANGDAT(K,1)/1000) GO TO 10
FDHM=(ANGDAT(K,1)-ISTORE(3,2)*1000)*D4+ANGDAT(K,2)/100
IF(FDHM.LT.IDHM) GO TO 1
KK=K

```

```

        GO TO 10
    1 CONTINUE
C
C DATI NON TROVATI
    10 IF(KK.EQ.0) THEN
        WRITE(1,*) '**DATI ANGOLARI NON TROVATI!**'
        IF(LU.NE.1) WRITE(LU,*) 'DATI ANGOLARI NON TROVATI'
        IF(IAUTO.NE.1) THEN
            WRITE(1,('VUOI ABORTIRE IL PROGRAMMA? <Y/N>: '))
            READ(1,200) NY
    200  FORMAT(A3)
            IF(NY.EQ.'Y'.OR.NY.EQ.'YES'.OR.NY.EQ.'1')
+STOP '**IRREGOLARE FINE DEL PROGRAMMA**'
            ENDIF
            ISTORE(3,7)=ANGDAT(120,5)
            ISTORE(3,8)=ANGDAT(120,4)
            ISTORE(3,9)=ANGDAT(120,3)
            RETURN
        ENDIF
        KKK=KK-1
        IF(KKK.EQ.0) THEN
            ISTORE(3,7)=ANGDAT(1,5)
            ISTORE(3,8)=ANGDAT(1,4)
            ISTORE(3,9)=ANGDAT(1,3)
            RETURN
        ENDIF
C
C SI RIEMPIE IL BUFFER
    FS1=ANGDAT(KKK,2)-(ANGDAT(KKK,2)/100)*100
    FH1=ANGDAT(KKK,2)/D4
    FM1=(ANGDAT(KKK,2)-FH1*D4)/100
    FS2=ANGDAT(KK,2)-(ANGDAT(KK,2)/100)*100
    FH2=ANGDAT(KK,2)/D4
    FM2=(ANGDAT(KK,2)-FH2*D4)/100
    ITS=30
    ITD=IDHM/D4
    ITH=(IDHM-ITD*D4)/100
    ITM=(IDHM-ITD*D4-ITH*100)
    IF(FH2-FH1.LT.0) THEN
        FH2=FH2+24
        IF(IDHM-FDHM.LT.0) ITH=ITH+24
    ENDIF
    T2=FS2/60.+FM2+FH2*60.
    T1=FS1/60.+FM1+FH1*60.
    T=ITS/60.+ITM+ITH*60.
    DT=T2-T1
    IF(DT.EQ.0) THEN
        WRITE(1,*) '**RIPETIZIONE NEI DATI ANGOLARI**'
        IF(LU.NE.1) WRITE(LU,*) 'RIPETIZIONE NEI DATI ANGOLARI'
        IF(IAUTO.NE.1) THEN
            WRITE(1,('VUOI ABORTIRE IL PROGRAMMA? <Y/N>: '))
            READ(1,200) NY
            IF(NY.EQ.'Y'.OR.NY.EQ.'YES'.OR.NY.EQ.'1')

```

```
+STOP '**FINE IRREGOLARE DELL' ANALISI**'
```

```
ENDIF
```

```
ISTORE(3,7)=ANGDAT(KK,5)
```

```
ISTORE(3,8)=ANGDAT(KK,4)
```

```
ISTORE(3,9)=ANGDAT(KK,3)
```

```
ENDIF
```

```
ST=ANGDAT(KK,5)-ANGDAT(KKK,5)
```

```
ISTORE(3,7)=ST/DT*(T-T1)+ANGDAT(KKK,5)
```

```
ST=ANGDAT(KK,4)-ANGDAT(KKK,4)
```

```
ISTORE(3,8)=ST/DT*(T-T1)+ANGDAT(KKK,4)
```

```
ST=ANGDAT(KK,3)-ANGDAT(KKK,3)
```

```
ISTORE(3,6)=(ST/DT*(T-T1)+ANGDAT(KKK,3))/10
```

```
C
```

```
C RITORNO ALLA CHIAMATA
```

```
RETURN
```

```
C
```

```
C FINE DI SEARCH
```

```
END
```

TAB. 1

REGRESS MEASUREMENT STRUCTURE

- 1 TIME 1: UTC (seconds 1950)
- 2 TIME 2: composite word containing UTC coded as year, day of year, hour, minute, second and fractions of second; these information are contained in the decimal part of time 2 as:

YYDDDDHHMMSSfffff

- 3 IDENTIFICATION WORD: composite word containing sampling rate in hundredths of seconds in the first seven decimal figures; the 8th figure represents the downlink band (1=S, 2=X), the 9th one the tracking network (DSN=1), the 10th and 11th the transmitting station, the 12th and 13th the receiving station, the 14th the data type (1=Doppler), the 15th the tracking link mode (2=two way, 3=three way), the last figures are not used; the scheme is:

1.5SSSSSSSBNTTRRKW

- 4 OBSERVABLE: observed frequency shift in Hertz, (same quantity as in the ATDF tapes).
- 5 FREQUENCY: oscillator frequency in Hz. The transmitted frequency is obtained multiplying FREQUENCY by 96.
- 6 PASS IDENTIFIER: composite word containing spacecraft identification code.
- 7 COMPUTED: frequency shift predicted by ODF
- 8 RTLT: round trip light time in seconds
- 9 HOUR ANGLE: composite word containing the spacecraft hour angle in degrees, minutes, seconds and fractions of seconds in the first figures; the code is:

1.DDMMSSfffff

- 10 DECLINATION: composite word containing spacecraft declination in degrees, minutes, seconds and fractions of seconds; the code is the same as in item 9.
- 11 AZIMUTH: composite word containing spacecraft azimuth in degrees, minutes, seconds and fractions of seconds; code as in item 9.

- 12 ELEVATION AT RECEIVING TIME: composite word containing spacecraft elevation at the receiving time in degrees, minutes, seconds and fractions of seconds; code as in item 9;
- 13 ELEVATION AT TRANSMITTING TIME: composite word containing spacecraft elevation at the transmitting time; code as in item 9.
- 14 DERIVATIVE OF THE ELEVATION AT RECEIVING TIME: in deg./s
- 15 DERIVATIVE OF THE ELEVATION AT TRANSMITTING TIME: in deg./s
- 16 RESIDUAL: Doppler residual in Hz, computed from OBSERVABLE minus COMPUTED (item 4 minus item 7).
- 17 REJECTION CODE: if this code is 0 the data are ok.
- 18 WEIGHT: data quality indicator (used by ODP).
- 19 CALIBRATION: media calibration to Doppler residuals (in Hz).
- 20 CALIBRATED RESIDUAL: calibrated residual in Hz. It is computed by subtracting: RESIDUAL minus CALIBRATION (items 16 and 19).

TAB. 2

STRUCTURE OF REGRESS RECORDS

rows ---->	1	6	9	33	57
columns 1	N1	N2	TIME TAG 1	TIME TAG 2	ID. WORD
2	N1	N2	OBSERVABLE	FREQUENCY	PASS ID.
3	N1	N2	COMPUTED	RTLT	HOUR ANGLE
4	N1	N2	DECLINATION	AZIMUTH	ELEV. T3
5	N1	N2	ELEV. T1	ELEV. DER. T1	ELEV. DER. T3
6	N1	N2	RESIDUAL	REJECTION	WEIGHT
7	N1	N2	CALIB. COMP.	MODELS	TIME TAG 1
8
.	.	.	omissis	.	.
100

TAB. 3

EXAMPLE OF REGRESS RECORD

The data start from time 20h 00' 29" of the DOY 308 year 1980

1	1	.973281629999999999+009	.803082000299999998+016	.100060001114121300+017
1	2-	.269094662833319999+005	.220277400000000000+008	.103080310204800000+017
1	3-	.269090225907072255+005	.101894300547065213+005	.410241037489606019+002
1	4-	.610047258413681025-001	.236355807440611173+003	.0000000000000000
1	5	.544776425522538426+002-	.283824054044811239-002	.164946371770699485-003
1	6-	.443692624774428168+000	.0000000000000000	.0000000000000000
1	7	.0000000000000000	.0000000000000000	.973281629999999999+009
1	8	.803082000299999998+016	.100060002114121300+017-	.986680276999990000+005
1	9	.220277400000000000+008	.103080310204800000+017-	.986664161639321474+005
1	10	.101894300547065213+005	.410241037489606019+002-	.610047258413681014-001
1	11	.236355807440611173+003	.0000000000000000	.544776425522538426+002
1	12-	.283824054044811239-002	.164946371770699485-003-	.161153606685252271+001
1	13	.0000000000000000	.0000000000000000	.0000000000000000
1	14	.0000000000000000	.973281629999999999+009	.803082000299999998+016
1	15	.100060001114141200+017-	.269156408999980000+005	.220277400000000000+008

. . . omissis

1	94	.0000000000000000	.973281749999999999+009	.803082002299999998+016
1	95	.100060001114121300+017-	.268720277666650000+005	.220277400000000000+008
1	96	.103080310204800000+017-	.268715821903272889+005	.101894286495735869+005
1	97	.415250900514604227+002-	.609566732206611566-001	.236819925387191006+003
1	98	.0000000000000000	.544943592287294470+002-	.285344413867476923-002
1	99	.113775830962588772-003-	.445576337711003134+000	.0000000000000000
1	100	.0000000000000000	.0000000000000000	.0000000000000000

TAB. 4

STRUCTURE OF STANDARD RECORDS

1	YYDDD	year and day
2	HHMMSS	hour, minute and second
3	FREQCY	oscillator frequency in Hz
4	TTRRNM	trans. and rec. stations, network and mode
5	ELupELdw	elevation in up and down link in degrees
6	S-RES	S-band residual in mmHz
7	X-RES	X-band residual in mmHz
8	S-3/11*X	quantity used in plasma calibration
9	S-OBS	S-band observable (in Hz)
10	X-OBS	X-band observable (in Hz)
11	REJCOD	rejection code
12	WEIGHT	datum weight
13		not used
14		not used
15		not used

TAB. 5

DATA TRANSFER FROM REGRESS FILE TO STANDARD FILE

INPUT DATA	OUTPUT DATA
1 TIME 1	not transferred
2 TIME 2	{ 1) YYDDD 2) HHMMSS
3 ID. WORD	{ band indicator 4) TTRMM
4 OBSERVABLE	9) S-OBS or 10) X-OBS
5 FREQUENCY	3) FREQCY
6 PASS ID.	not transferred
7 COMPUTED	not transferred
8 RTLT	not transferred
9 HOUR ANGLE	not transferred
10 DECLINATION	not transferred
11 AZIMUTH	not transferred
12 } ELEVATIONS	5) ELupELdw
13 }	
14 } EL. DERIVATIVES	not transferred
15 }	
16 RESIDUAL	6) S-RES or 7) X-RES
17 REJECTION CODE	11) REJCOD
18 WEIGHT	12) WEIGHT
19 CALIBRATION	not transferred,
20 CAL. RESIDUAL	not transferred.

TAB. 6

EXAMPLE OF STANDARD RECORD

 Data start from time 20h 00' 29" of the DOY 308 year 1980

1	80308	200029	22027740	141213	54473792	-443692	-1611536	-4182
	-26909	-98668	0	0	0	0	0	
2	80308	200029	22027740	141412	54473792	-447566	-1624393	-4549
	-26915	-98690	0	0	0	0	0	
3	80308	200029	22027740	144213	54472920	-450149	-1638823	-3197
	-31147	-114208	0	0	0	0	0	
4	80308	200029	22027740	144313	54472920	-446804	-1639150	236
	-31147	-114208	0	0	0	0	0	
5	80308	200129	22027740	141213	54483776	-442122	-1610828	-2805
	-26890	-98599	0	0	0	0	0	
6	80308	200129	22027740	141412	54483776	-446126	-1623059	-3473
	-26896	-98621	0	0	0	0	0	
7	80308	200129	22027740	144213	54482936	-447568	-1638656	-661
	-31130	-114146	0	0	0	0	0	
8	80308	200229	22027740	141213	54493752	-445576	-1602485	-8534
	-26872	-98530	0	0	0	0	0	
9	80308	200229	22027740	141412	54493760	-447826	-1620098	-5981
	-26878	-98553	0	0	0	0	0	
10	80308	200229	22027740	144213	54492960	-446743	-1636628	-389
	-31114	-114085	0	0	0	0	0	
. . . omissis								
160	80308	204029	22027740	141412	53653088	-445258	-1612198	-5567
	-26197	-96058	0	0	0	0	0	

EXAMPLE OF REGRESS TABLE

Doppler residuals available for the DOY 309 of the year 1980

YEAR = 80	DAY = 309	HOUR =	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	NS DAY	
DOP	DSS = 12	Band-Mode S 3	0	0	0	0	0	0	0	0	0	0	0	0	55	55	60	56	60	59	60	60	18	40	27	0	550
DOP	DSS = 12	Band-Mode X 3	0	0	0	0	0	0	0	0	0	0	0	0	55	55	60	56	60	59	60	60	18	42	28	0	553
DOP	DSS = 14	Band-Mode S 2	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	57	60	60	54	46	60	19	28	0	384
DOP	DSS = 14	Band-Mode X 2	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	57	60	60	54	46	60	19	28	0	384
DOP	DSS = 14	Band-Mode S 3	0	0	0	0	0	0	0	0	0	0	10	0	60	57	59	0	0	0	0	0	0	23	1	0	210
DOP	DSS = 14	Band-Mode X 3	0	0	0	0	0	0	0	0	0	0	10	0	60	57	59	0	0	0	0	0	0	23	1	0	210
DOP	DSS = 42	Band-Mode S 3	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	39	60	60	21	29	0	209
DOP	DSS = 42	Band-Mode X 3	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	38	60	60	21	29	0	208
DOP	DSS = 43	Band-Mode S 2	60	44	60	60	48	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	24	21	60	377
DOP	DSS = 43	Band-Mode X 2	60	44	60	60	48	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	24	25	60	381
DOP	DSS = 43	Band-Mode S 3	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	42	42	58	19	28	0	189
DOP	DSS = 43	Band-Mode X 3	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	43	42	58	19	28	0	190
DOP	DSS = 61	Band-Mode S 3	0	0	0	0	21	16	60	31	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	128
DOP	DSS = 61	Band-Mode X 3	0	0	0	0	21	16	60	31	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	129
DOP	DSS = 63	Band-Mode S 2	0	0	0	0	0	0	0	19	58	58	57	51	51	49	58	0	0	0	0	0	0	0	0	0	401
DOP	DSS = 63	Band-Mode X 2	0	0	0	0	0	0	0	19	58	58	57	51	51	49	58	0	0	0	0	0	0	0	0	0	401
DOP	DSS = 63	Band-Mode S 3	0	0	0	0	29	18	60	30	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	137
DOP	DSS = 63	Band-Mode X 3	0	0	0	0	29	18	60	30	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	137

TAB.7

TAB. 8

ANGULAR DATA STRUCTURE

- 1 - TIME TAG (high part), coded as YYDD
- 2 - TIME TAG (low part), coded as HHMMSS
- 3 - $RTL \times 10$ it is given in seconds with an approximation of .1 sec; the stored value is $IFIX(RL \times 10.)$
- 4 - $RA \times 100$ the right ascension is given in degrees with an approximation of .01 degrees; the stored value is $IFIX(RA \times 100.)$
- 5 - $DEC \times 100$ the declination is given in degrees with an approximation of .01 degrees; the stored value is $IFIX(DEC \times 100.)$
- 6 - $ELO \times 100$ the elongation is given in degrees with an approximation of .01 degrees; the stored value is $IFIX(ELO \times 100.)$

TAB. 9

LOGICAL FORMAT OF DOPPLER DATA FILES (ROD)

rows ---->	1	2	3
columns : 1	S INITIAL DAY	X INITIAL DAY	DATA ID. (1=A 2=R)
2	S FINAL DAY	X FINAL DAY	YEAR
3	S INITIAL MINUTE	X INITIAL MINUTE	TRANSMITTING DSS
4	S FINAL MINUTE	X FINAL MINUTE	RECEIVING DSS
5	# of S-band DATA	# of X-band DATA	MODE
6	LOCATION OF THE FIRST S-BAND ITEM	LOCATION OF THE FIRST X-BAND ITEM	RTLT
7	LOCATION OF THE LAST S-BAND ITEM	LOCATION OF THE LAST X-BAND ITEM	RIGHT ASCENSION
8	INITIAL DAY	INITIAL MINUTE	DECLINATION
9	FINAL DAY	FINAL MINUTE	# of S or X DATA
10	0	0	0
11	:	:	:
.	S-BAND DATA :	X-BAND DATA :	OSCILLATOR FREQUENCY :
.	mmHz :	mmHz :	Hz :
730	∪	∪	∪

N.B.:

- 1) S and X stand for S-band and X-band respectively
- 2) The value of the item DATA IDENTIFIER is 1 for ATDF data and 2 for REGRESS data

TAB. 10

FILE DAT/ROD1414309

1	309	309	2
2	309	309	80
3	903	903	14
4	1347	1347	14
5	384	384	2
6	11	11	10187
7	455	455	18571
8	309	903	-22
9	309	1347	384
10	0	0	0
11	-1716015139	2147483647	22027744
12	2147483647	2147483647	22027744
13	2147483647	2147483647	22027744
14	-458095	-1670888	22027720
15	-457467	-1671856	22027720
16	-457156	-1669117	22027720
17	-453513	-1655412	22027720
.	.	.	.
730	0	0	0

FIGURE CAPTIONS

Fig. 1 The Deep Space Network stations.

Fig. 2a Flow chart of the program DECODEREGRES.

2b Zoom of block A of the previous flow chart.

Fig. 3 Flow chart of the program STATREGRES.

Fig. 4 Output of the program PLOTREGRES.

Fig. 5 Flow chart of the program PLOTREGRES.

Fig. 6 Flow chart of the program FFREGRES.

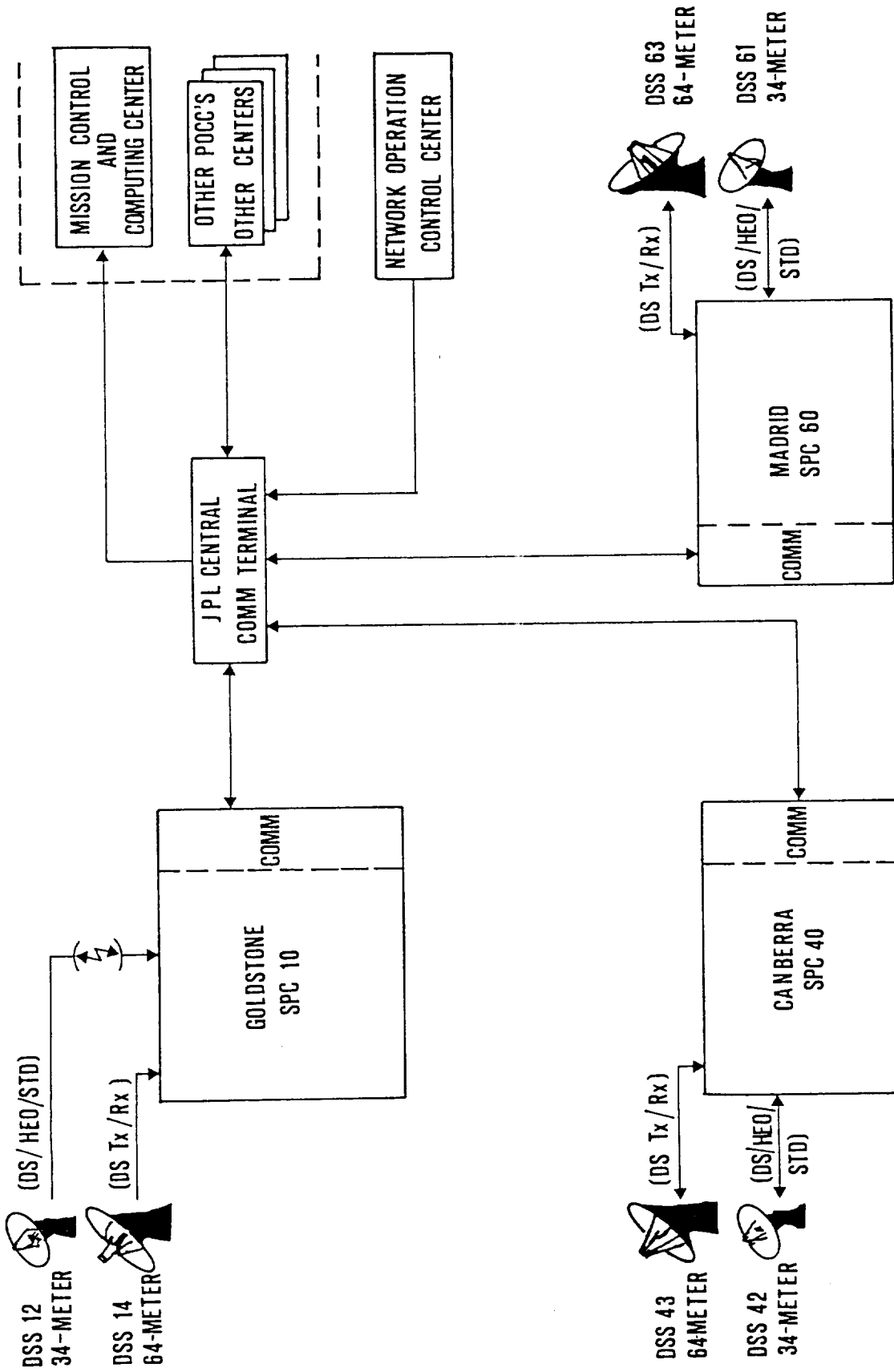


FIG. 1

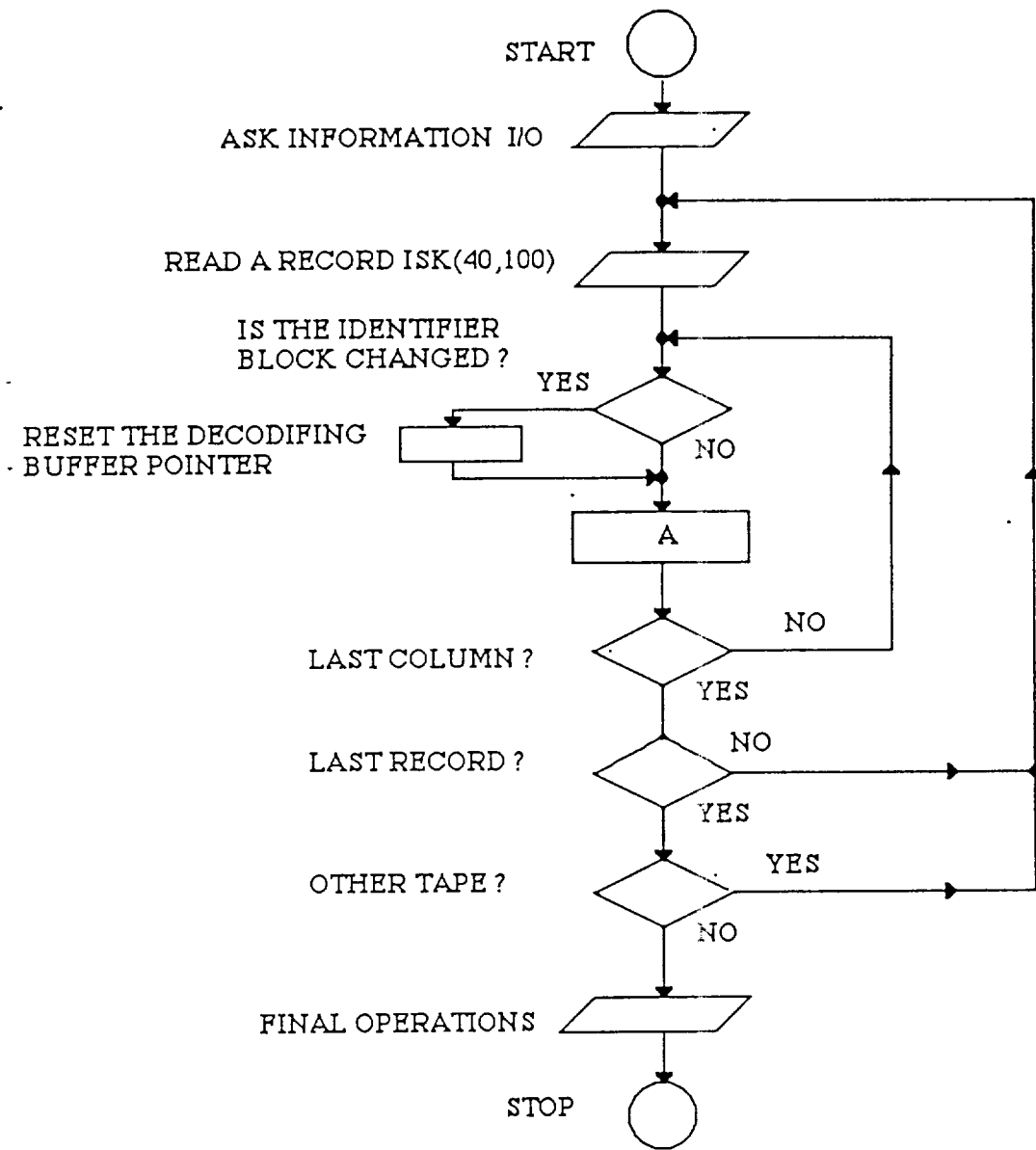


FIG. 2 a

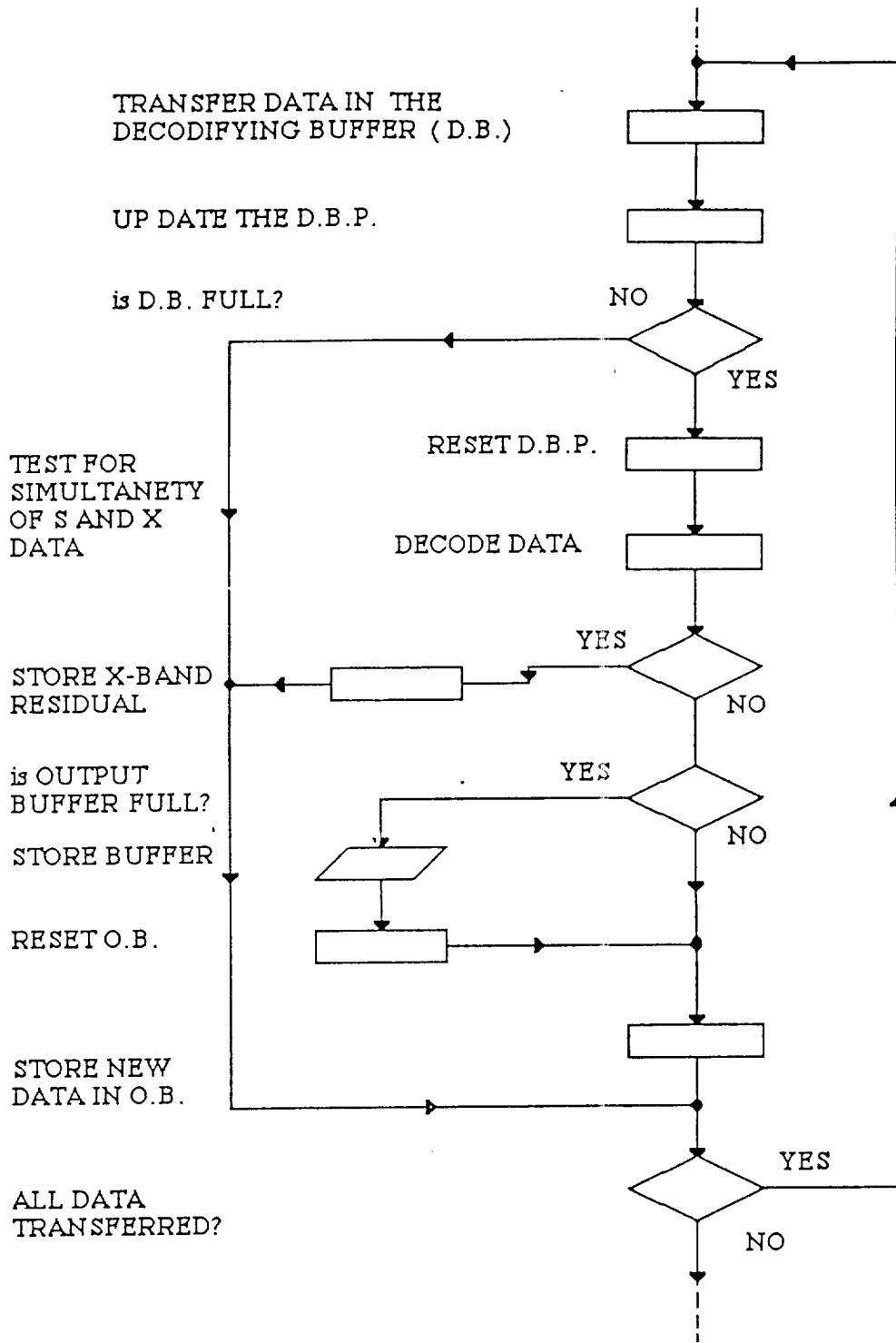


FIG. 2 b

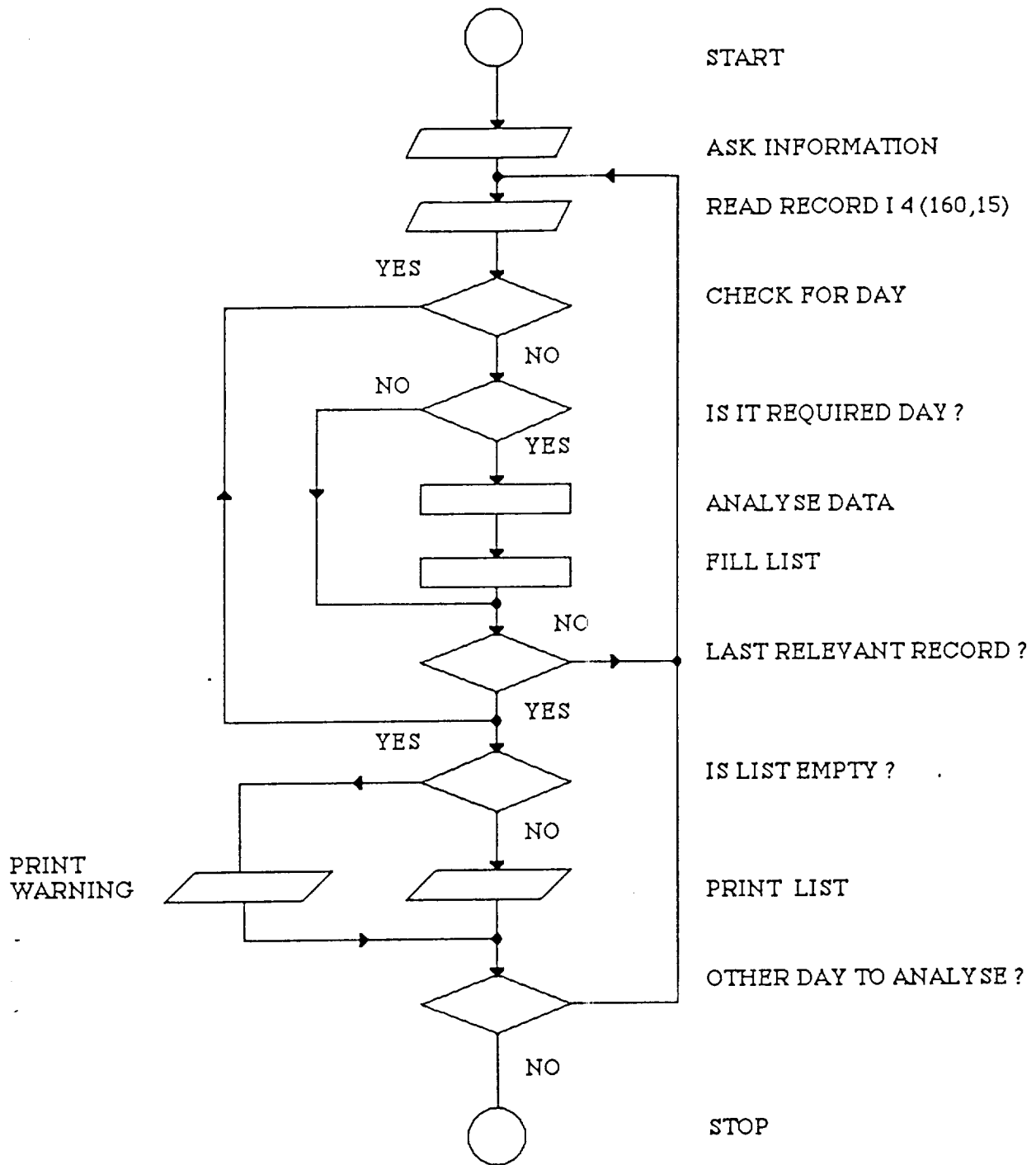
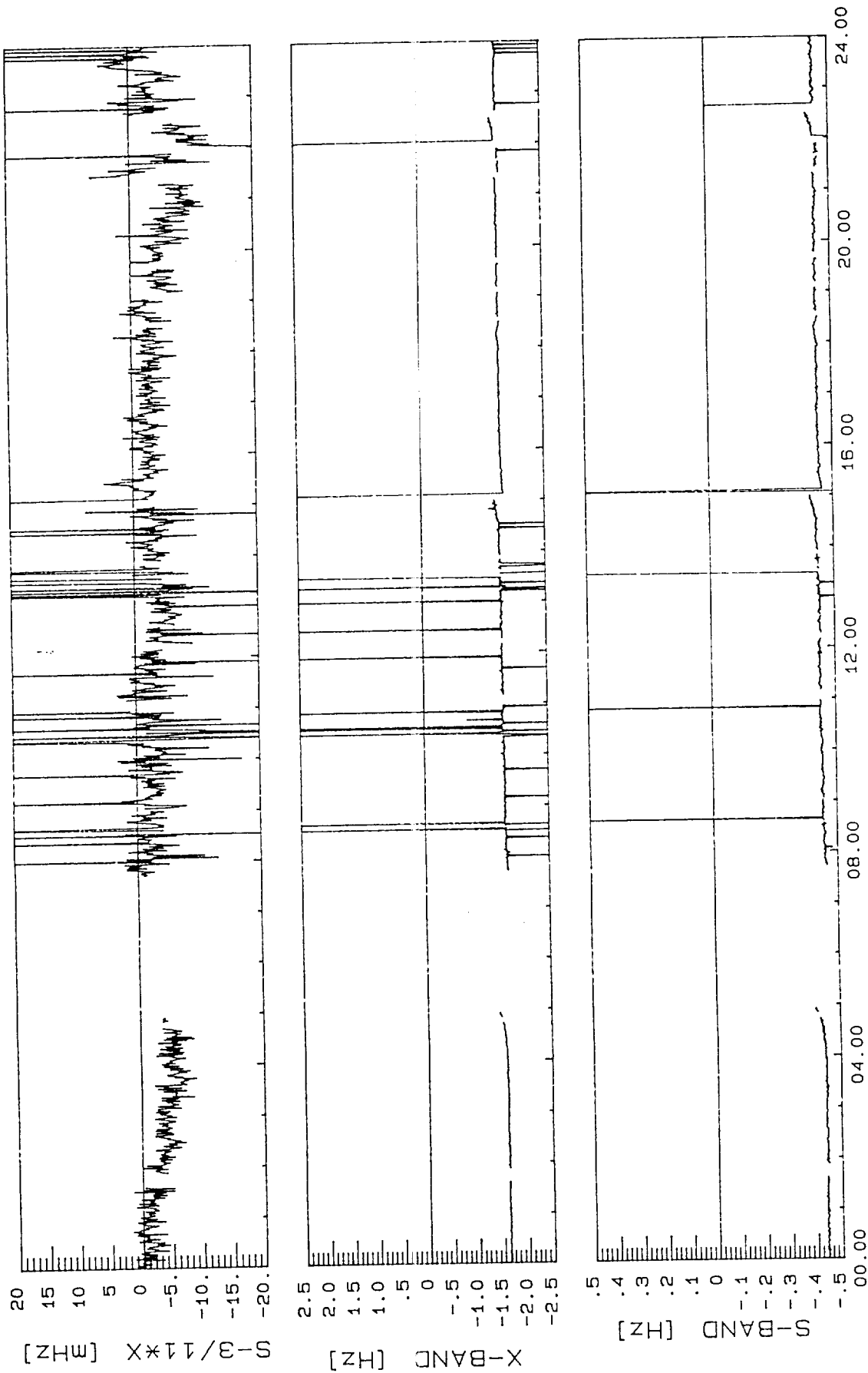


FIG. 3

DAY = 309

MODE = 2



VOYAGER 1980 REGRESS FILES

FIG. 4

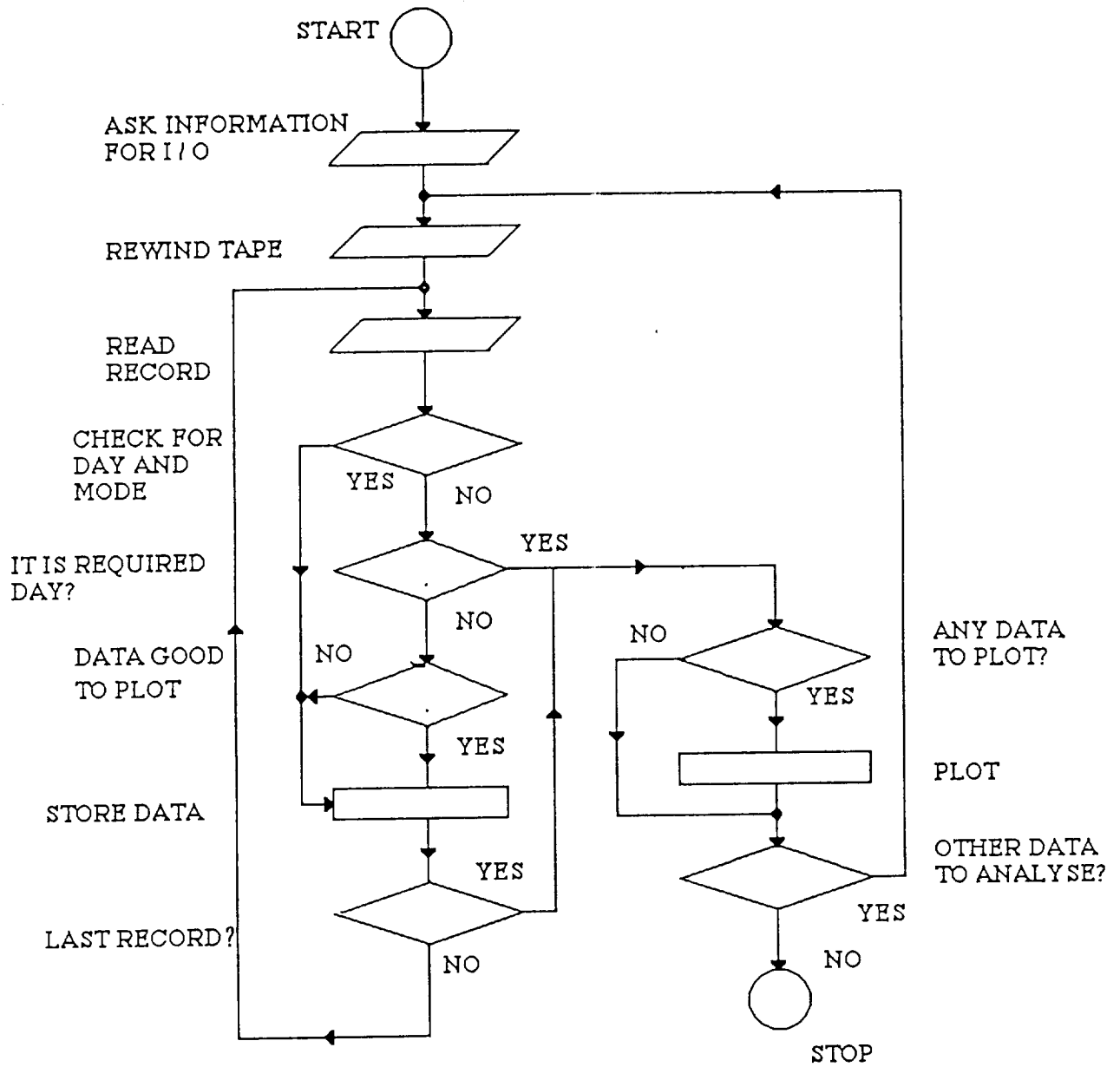


FIG. 5

1
2
3

4
5
6

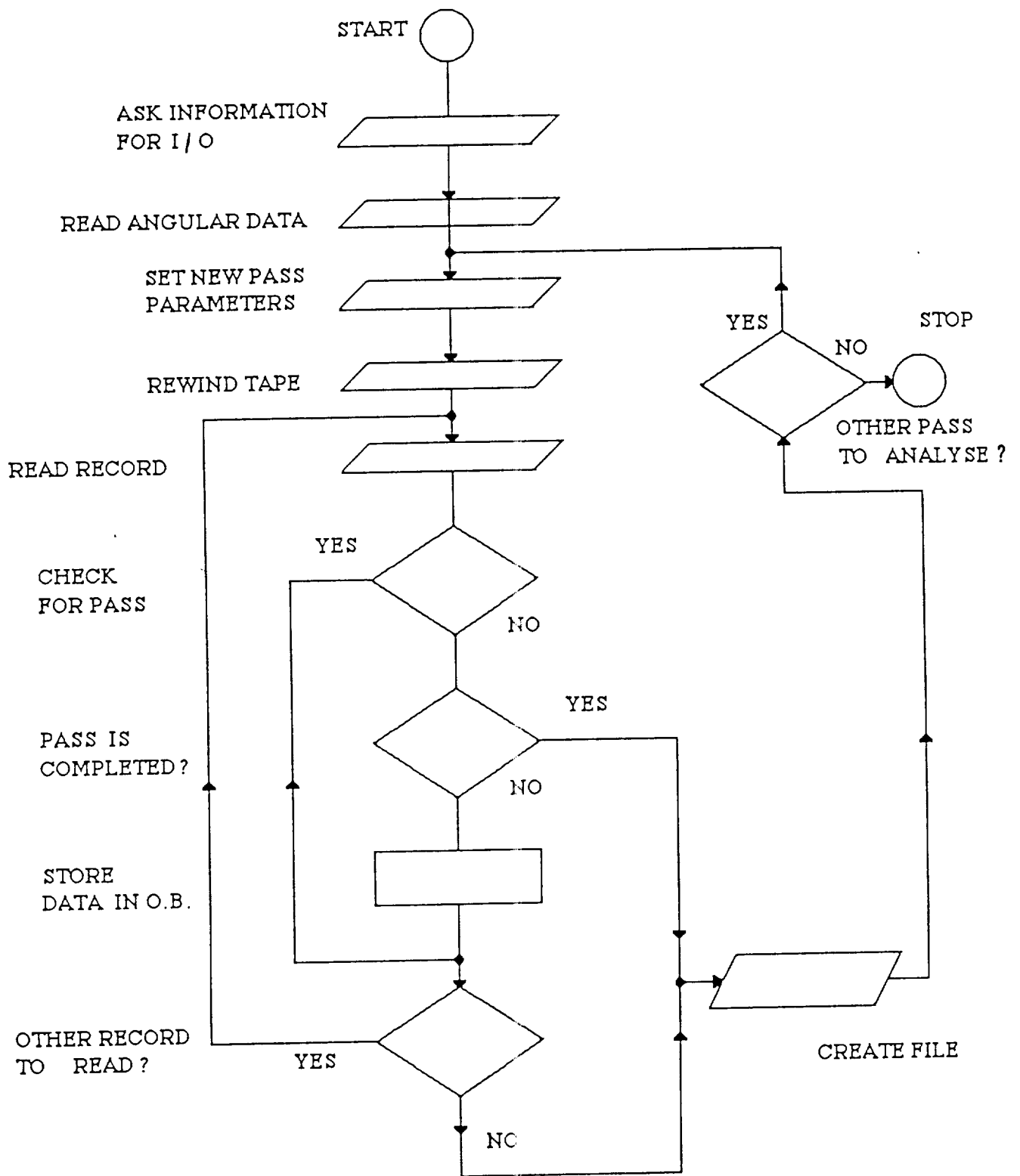


FIG. 6

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