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THE UNIVERSITY OF MICHIGAN

COLLEGE OF ENGINEERING
Department of Atmospheric, Oceanic and Space Sciences
Space Physics Research Laboratory

N93-18880

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Solar Extreme Ultraviolet Sensor and
Advanced Langmuir Probe

(NASA-CR-191972) SOLAR EXTREME
ULTRAVIOLET SENSOR AND ADVANCED
LANGMUIR PROBE Progress Report
(Michigan Univ.) -80 p

81P


PROGRESS REPORT
December 14, 1992

Prepared on behalf of the project by:

N. R. Voronka
B. P. Block
G. R. Carignan



Under Contract with:
National Aeronautics and Space Administration
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Grant No. NAG5-1619
Greenbelt Maryland 20771

Progress Report
December 14, 1992

Solar Extreme Ultraviolet Sensor and
Advanced Langmuir Probe

Grant No. NAG5-1619

Prepared by:

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1.0 Introduction

For more than two decades, the staff of the Space Physics Research Laboratory (SPRL) has collaborated with the Goddard Space Flight Center (GSFC) in the design and implementation of Langmuir probes (LP). This program of probe development under the direction of Larry Brace of GSFC has evolved methodically with innovations to: improve measurement precision, increase the speed of measurement, and reduce the weight, size, power consumption and data rate of the instrument. Under contract NAG5-419 these improvements were implemented and are what characterize the Advanced Langmuir Probe (ALP).

Using data from the Langmuir Probe on the Pioneer Venus Orbiter, Brace and Walter Hoegy of GSFC demonstrated a novel method of monitoring the solar extreme ultraviolet (EUV) flux. This led to the idea of developing a sensor similar to a Langmuir probe specifically designed to measure solar EUV (SEUV) that uses a similar electronics package. Under this contract, a combined instrument package of the ALP and SEUV sensor was to be designed, constructed, and laboratory tested. Finally the instrument was to be flight tested as part of a sounding rocket experiment to acquire the necessary data to validate this method for possible use in future earth and planetary aeronomy missions.

2.0 Summary of Project Activities

The primary purpose of this contract was to develop the electronics hardware and software for this instrument, since the actual sensors were supplied by GSFC. Due to budget constraints, only a flight model was constructed. These electronics were tested and calibrated in the laboratory, and then the instrument was integrated into the rocket payload at Wallops Flight Facility where it underwent environmental testing. After instrument recalibration at SPRL, the payload was reintegrated and launched from the Poker Flat Research Range near Fairbanks Alaska. The payload was successfully recovered and after refurbishment underwent further testing and development to improve its performance for future use.

2.1 Project Hardware

The SEUV/ALP hardware was designed for the sounding rocket mission but also with the intention of allowing it to be easily upgradable to a flight qualified instrument with minimal effort. The entire instrument consisted of a Flight Computer with Telemetry Interface, a Grid Voltage Generator Board and two VA Generator/Electrometer Boards. In addition, ground support equipment was designed that would allow the instrument to

operate in a laboratory setting as well as support the instrument once it was integrated into the rocket payload.

2.1.1 Flight Computer

The processor chosen for the flight computer was Intel's 80C916 12MHz microcontroller which was specifically designed to be used in embedded systems such as this one. The advantages of using this processor were that it has two timers, an eight channel A/D converter, and a serial port. The additional functionality of this processor provided for a smaller and more power efficient flight computer.

The flight computer has an address space of 64K: 8K was used for the boot ROM, 32K was used for the program EEPROM (electrically-erasable PROM), 8K was used for battery-backed RAM, and 4K was used for memory mapped I/O. A watchdog timer was also integrated into the flight computer, which would reset the flight computer should the flight program crash. The flight computer also had some signal conditioning hardware to allow the eight A/D channels to be used for housekeeping purposes.

The programming of the flight computer was done via the serial port. Once the flight program was compiled, it was uploaded to the flight computers EEPROM using the ground support computer communicating over a RS-422 link.

2.1.2 Grid Voltage Generator

The solar EUV sensor has three grids which must be biased with varying potentials ranging from approximately -50V to +50V. The Grid Voltage Generator Board has a quadruple 12-bit digital to analog converter (DAC) which produces voltages in the -10V to +10V range. Three high voltage amplifiers were used to amplify these signals to the required levels. The fourth DAC was not used for the rocket mission, but its output signal is available externally should it be required in the future. The Grid Voltage Generator Board also has a programmable timer which generates two shift clocks (one each for the SEUV and the ALP) for the optocoupled electrometers in the VA Generator/Electrometer Boards. In addition, there are buffers which were used to condition the grid voltage signals so that the rocket's telemetry system could monitor these signals during the flight.

2.1.3 VA Generator/Electrometer

The VA Generator/Electrometer Board is a result of extensive work done at SPRL to improve the accuracy and speed of the Langmuir Probe instrument. The VA Generator is constructed similarly to the Grid Voltage Generators except that a single 16-bit DAC is used to allow the VA to have a -65V to +65V ranges with 2mV resolution. The

electrometer makes its measurements while floating on the applied potential. Data signals are optically coupled from the flight computer to the electrometer gain registers and the 12-bit A/D converter. There is also a relay circuit which is used to apply +125V to the sensor to clean the sensor by electron bombardment using ionospheric electrons.

2.1.4 Ground Support Equipment

The ground support equipment for this instrument is contained in a single suitcase with the addition of a notebook sized IBM PC compatible computer. The suitcase contains a power supply and RS-422 to RS-232 interface hardware. The ground support computer is used to develop, compile, and upload object code to the flight computer. In addition, there exists software that allows one to operate the instrument in a laboratory environment where one sends commands to the instrument and receives data back from the instrument via the RS-422 link. This software has the capability of displaying the resulting I-V curves in real-time as well as saving them to disk for later analysis.

2.2 Project Software

The following paragraphs describe the real-time flight control software of the SEUV/ALP instrument. This software was designed to operate the instrument at the highest sampling rate possible without sacrificing instrument reliability, accuracy, and the portability of the flight code. The instrument can operate either in flight mode or test/laboratory mode without reprogramming the flight computer. In flight mode, the instrument steps through a sequence of pre-programmed measurement modes and telemeters the acquired data. In test/laboratory mode, the instrument requires a ground support computer to control the instrument and record measured data.

2.2.1 Overview

The majority of the software was written in a high level language, ANSI C, and was compiled with the Archimedes 80C196 cross-compiler. A high level language was used to reduce software development time. ANSI C was chosen because it is a high level language that is well suited for real-time embedded systems programming. Some assembly language programming was necessary and the Archimedes 80C196 cross-assembler was used to produce object code.

In early development phases of the software, it was decided that the use of a real-time kernel and operating system was not necessary, because it would produce overhead that would reduce the temporal resolution of the instrument. Instead, the instrument was to perform its tasks within a predefined measurement interval. In that interval, current was to

be measured, voltages were to be adjusted, telemetry was to be sent and housekeeping information gathered. This concept allowed the instrument to have temporal resolution that was dictated by the analog hardware and not by the speed of the flight computer.

The flight software was designed in modules or processes (see drawing in Appendix A). Each process or module is a collection of functionally similar tasks or routines, and these processes are described below.

2.2.2 Module Descriptions

MAIN -- This is the highest level control process of the flight software system. This process is initiated upon reset of the system -- either powerup, manual or watchdog timer reset. This process can operate in two modes: flight or bench mode.

After performing all necessary initialization, this process goes into bench mode. In this mode the process awaits for commands from the serial port continuously until a launch signal is detected. The commands are processed and executed by the COMPROC process and can be used to configure or test the instrument during pre-launch operations or to operate the instrument in a laboratory setting for measurements or testing. After the launch signal is detected, this process is in flight mode and measurement sequencing is initiated and controlled by the MODES process. To insure that measurements are made at regular time intervals in flight mode, after the necessary tasks are done, the CPU is placed into a power-conserving sleep mode and wakes up by an interrupt generated by the TIMER process.

COMPROC -- This process parses, limit checks and executes all commands received from the serial port from the SERIAL process. The commands are executed by referencing a function pointer in a lookup table allowing a very flexible and expandable command processor. Currently, there are commands for testing, calibration, hardware debugging, mode debugging, and laboratory measurement programmed in the command processor. The results from these commands are either sent via the SERIAL process to the ground support computer or via the TM process to the telemetry interface.

MODES -- The MODES process executes a pre-programmed sequence of modes. There are two tables (one for the SEUV and one for the ALP) of ordered mode names which are used to control this sequence. These tables can be either compiled in, or programmed by commands in the COMPROC process. This process controls measurement sequencing by communicating to the MODES2 process which step of which mode is to be executed. The current measurement mode and step are stored in zero-powered RAM to allow the instrument to continue operation where it left off after a power failure or a watchdog timer reset.

The mode names are stored in a table also, along with function pointers and other information, to facilitate the addition of new modes.

MODES2 -- This module is not a single process but a collection of processes that control the activities necessary to perform scientific measurements (adjusting gains, setting applied voltages, measuring currents) by executing I/O routines. Each measurement mode process is controlled by a mode step number that is received from the MODES process. The modes that are programmed in this module are specified by the *Modes of Operation* document (see Appendix B).

TM -- The process generates and transmits telemetry either over the dedicated telemetry channel or via the serial port. The SEUV/ALP instrument uses packet telemetry conforming to the Consultative Committee's on Space Data Systems (CCSDS) packet telemetry standard as specified in the CCSDS 102.0-B-2 Blue Book. This telemetry system uses packet error control as specified in the CCSDS 100.0-G-1 Green book. This process assembles data into packets and when completed, copies the assembled packets into the telemetry system interface hardware.

SERIAL -- This is an Interrupt Service Routine (ISR) module whose task is to receive data from the serial command port and transmit it to the COMPROC process, and to send data back to the ground support equipment during testing and laboratory measurement setups. To maximize the throughput and efficiency, this process was programmed in 80C916 assembly language.

TIMER -- This ISR module initializes the CPU's timers and acknowledges interrupts from the CPU. The timers are used to provide an instrument clock which ensures that current measurements are made at regular time intervals, and to provide a start time for all measurement modes which simplifies the data analysis process. This module was programmed in assembly language also.

I/O -- This module is a collection of routines that communicate directly with the instrument hardware (VA generators, A/D converters, registers, timers, etc.). The purpose of this module was to keep all device dependent programming together to reduce the effort necessary to modify the flight code for various hardware configurations. Any calibration information used in the instrument is also contained in this module.

2.3 Flight Experiment Details

The combined SEUV/ALP instrument was part of Dr. William Sharp's sounding rocket mission 27.133 UE. The instrument was piggybacked onto Dr. Sharp's payload and was launched by a Nike-Black Brant VC from Poker Flat Research Range (65°07'N 147°28'W) at 206:13:36:00 UT 1992. The payload achieved an apogee of 233.36 km,

and was successfully recovered with the SEUV/ALP instrument not sustaining any damage.

The instrument was partially successful in achieving its objectives which were twofold: to acquire SEUV data to verify the measurement model, and to perform an engineering test of the combined SEUV/ALP electronics. A satisfactory number of SEUV measurements were made, and are currently being processed. Due to a component failure, the ALP channel failed and no measurements were made. However this does not constitute a failure to meet the second objective since an identical unit which was used to measure SEUV currents did not fail.

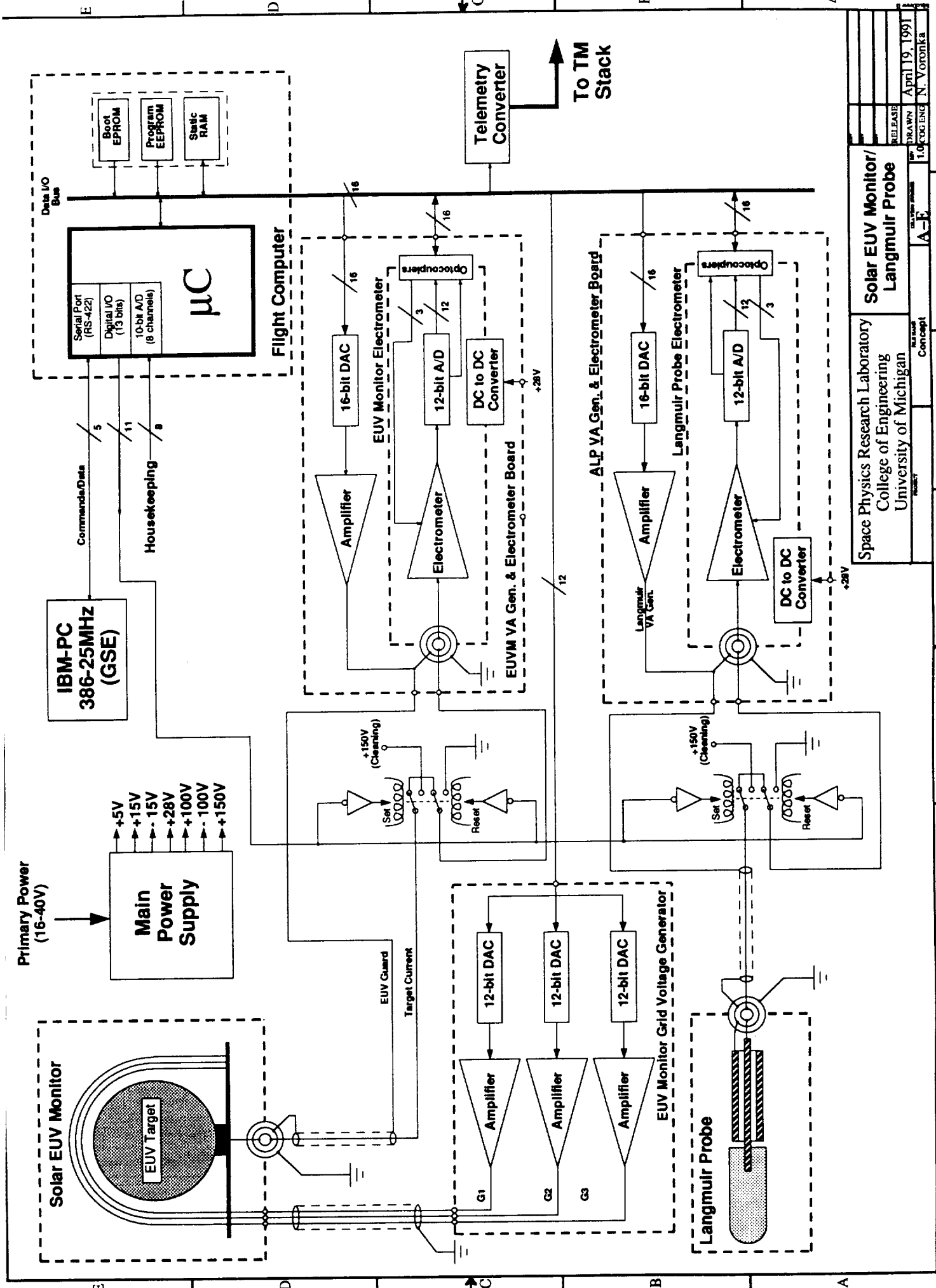
APPENDIX A

System Specifications and Block Diagrams

Langmuir Probe/Solar EUV Electronics Data Sheet



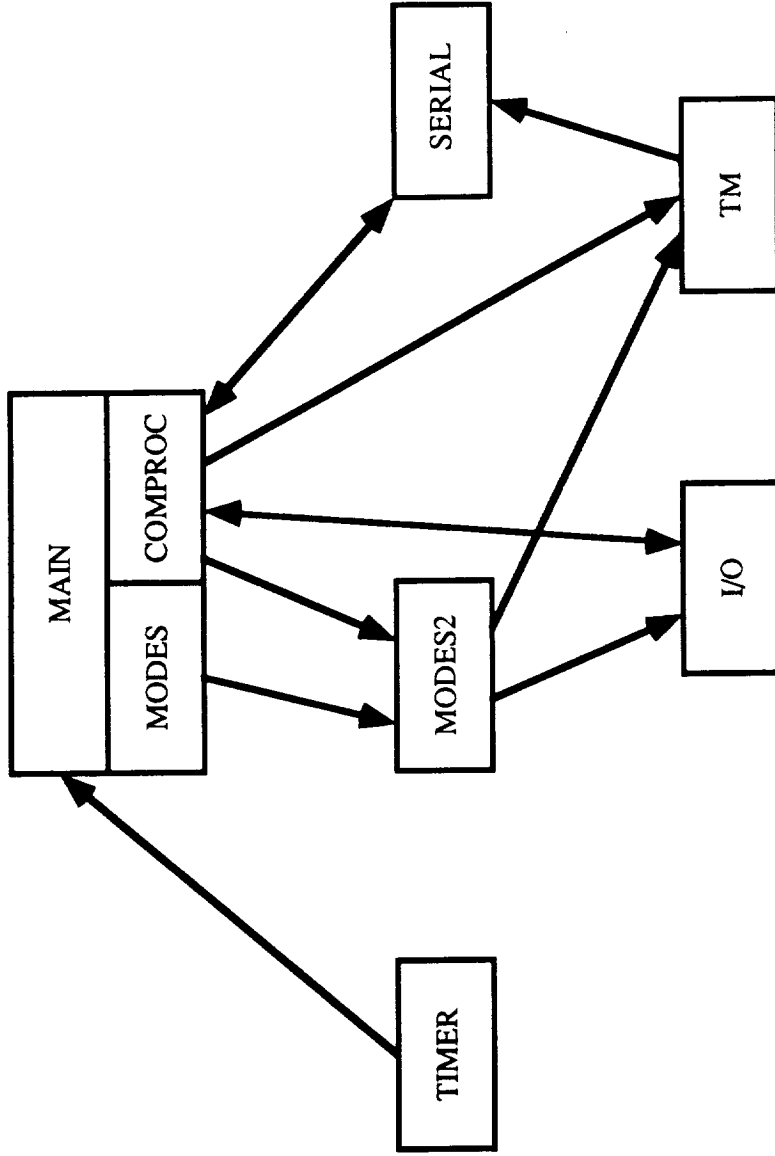
- **Applied Voltage Generators:**
 - 2 Generators with 16 bits of resolution
Range: -65.536V to 65.534V in 2mV increments
- **Grid Voltage Generators:**
 - 3 Generators with 12 bits of resolution
Range: -51.200V to 51.175V in 25mV increments
- **Electrometers:**
 - 2 Electrometers sampled with 12 bits resolution
 - Range 1: -66 μ A to +66 μ A
 - Range 2: -4 μ A to +4 μ A
 - Range 3: -200nA to +200nA
 - Range 4: -15nA to +15nA
- **Flight Computer:**
 - Custom Computer based on Intel 80C196 12MHz processor w/watchdog timer
 - 32K of EEPROM Program Memory
 - 8K of Boot/Loader ROM
 - 8K of Battery Backed RAM
- **Telemetry/Command Interface:**
 - Serial TM Interface to PCM stack at 1250 bytes/sec
(Packet TM conforming to CCSDS 102.0-B-2 standard)
 - Serial RS-422 Command/TM Interface at 9600 baud
- **Size of Electronics:**
 - 10.180" (L) x 5.930"(W) x 5.610"(H)
- **Mass of Electronics:**
 - 3.75 kg
- **Power Consumption:**
 - (2) V_a Generator/Electrometers 2.10 W
 - Grid Voltage Generators 2.94 W
 - CPU/Telemetry 2.23 W



PROJECT	CONCEPT	DATE	BY
	A-E		
Space Physics Research Laboratory College of Engineering University of Michigan		DATE	BY
Solar EUV Monitor/ Langmuir Probe		APR 19, 1991	N. VOTONKA
REVISION		DATE	BY
1.0 COG ENG			

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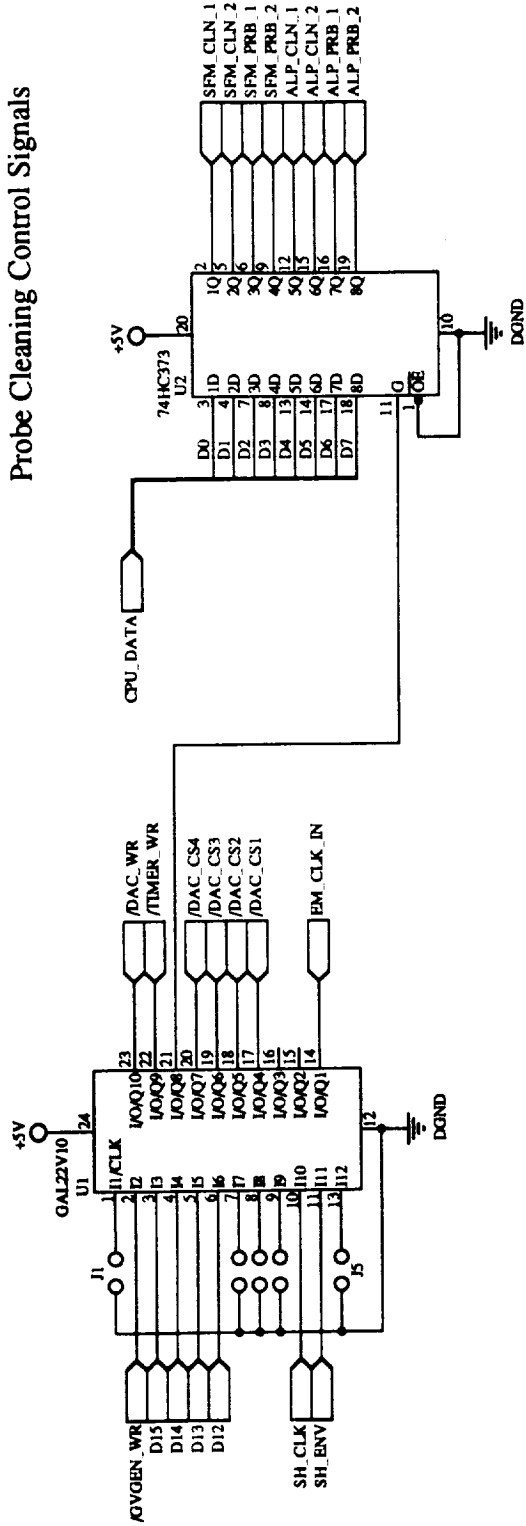


Process Name	Description
MAIN	High Level Control
COMPROC	Terminal Command Processing
MODES	Mode Sequencer
MODES2	Measurement Mode Execution
TM	Telemetry Processing
SERIAL	Serial Port ISRs
TIMER	Timer ISRs
I/O	Hardware Interface Library

APPENDIX B

SEUV/ALP Electrical Drawings

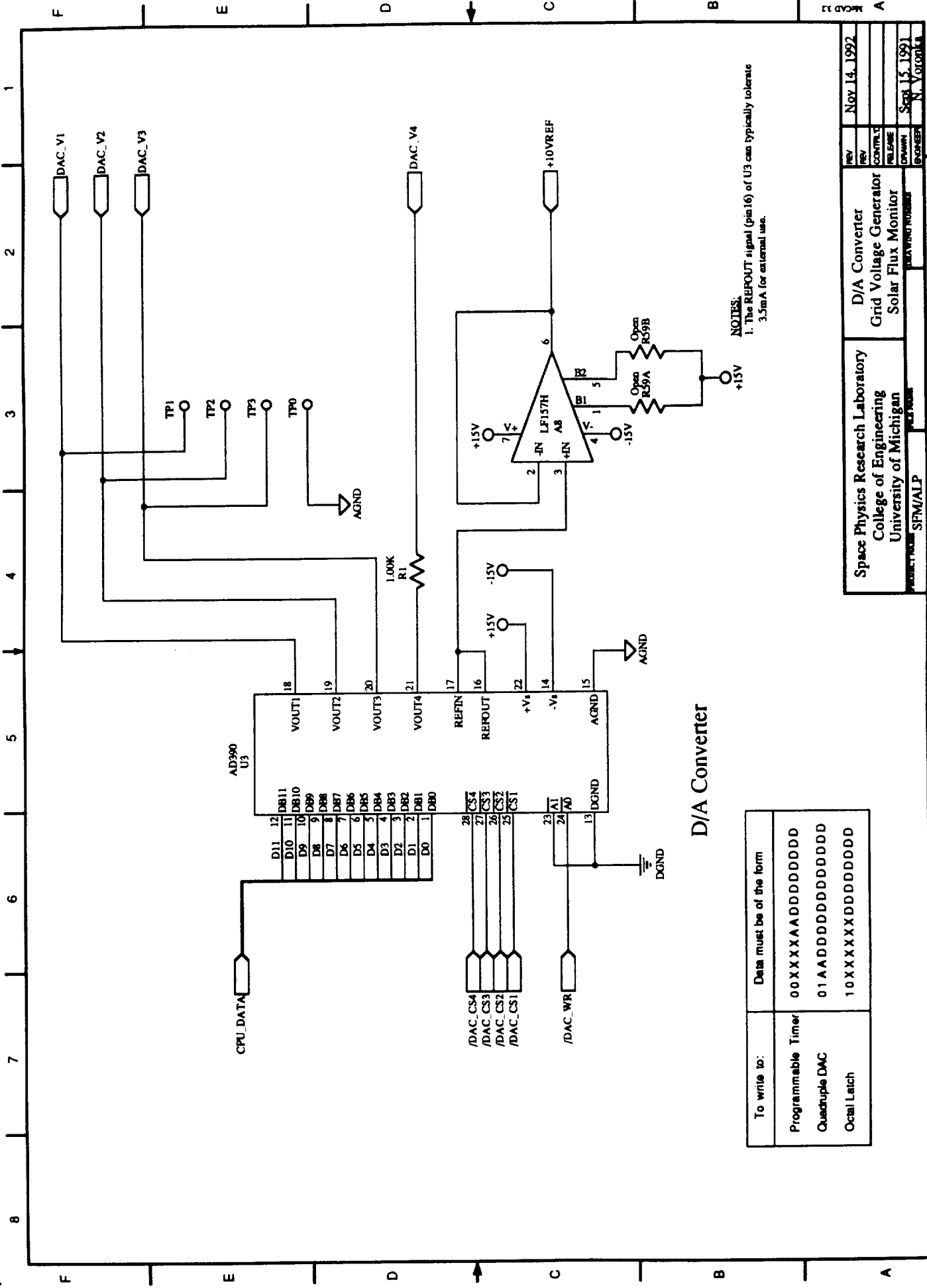
Probe Cleaning Control Signals



NOTES:
 1. Unless otherwise specified, all resistors are type RNC55 and all capacitors are type CKR05.

To write to:	Data must be of the form
Programmable Timer	00XXXXXXXXXXXXXXXX
Quadruple DAC	01AAXXXXXXXXXXXXXX
Octal Latch	10XXXXXXXXXXXXXXXX

REV	REV	CONTROL	RELEASE	DATE	BY
				Dec. 31, 1991	N. YOROKUBA
Space Physics Research Laboratory College of Engineering University of Michigan			PROJECT NUMBER: SFM/ALP		
Decoding PAL & Latch Grid Voltage Generator Solar Flux Monitor			DRAWING NUMBER: 1 I.1		



NOTES:
 1. The REPROUT signal (pin 16) of U3 can typically tolerate 3.5mA for external use.

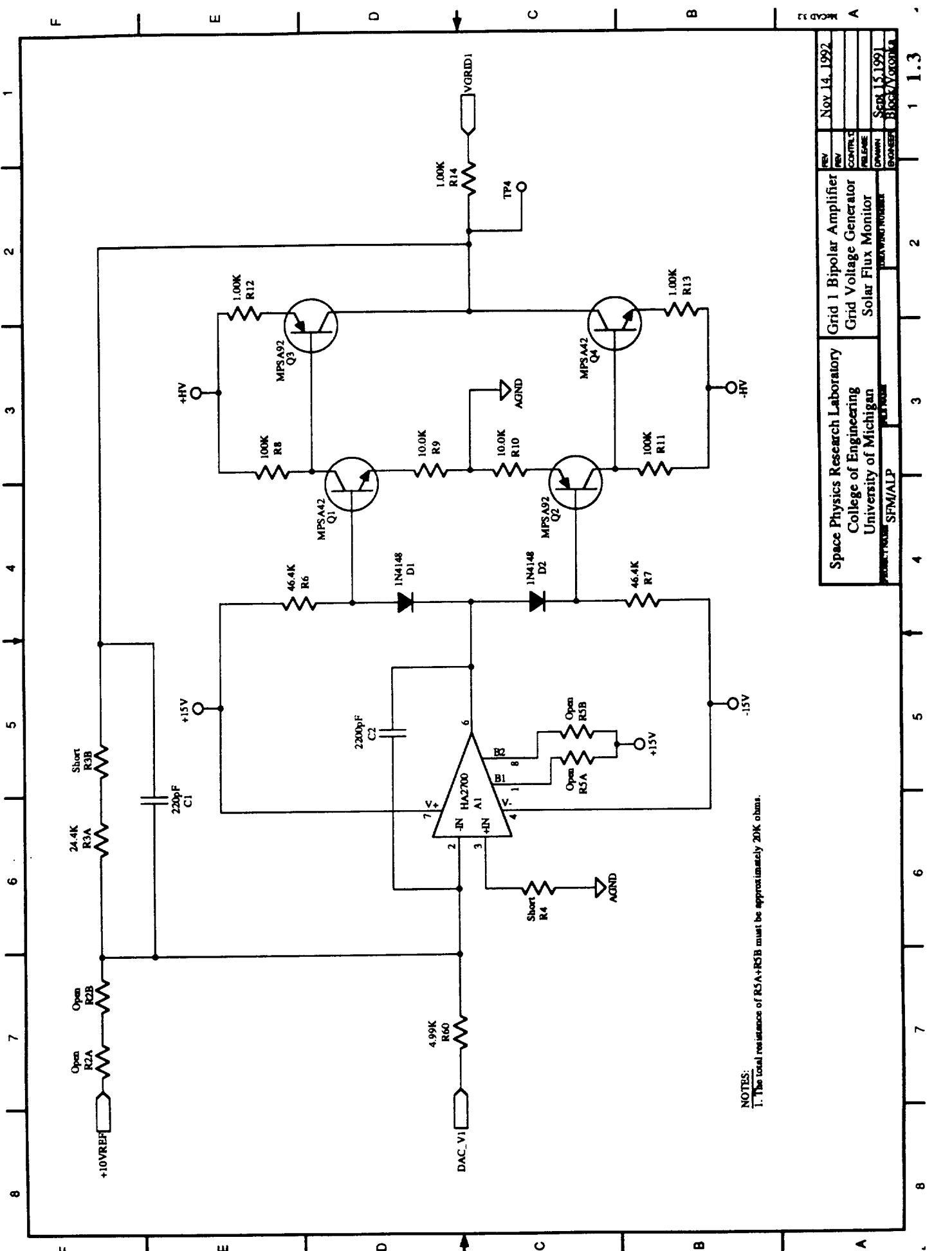
D/A Converter

To write to:	Data must be of the form
Programmable Timer	00XXXXXXXXXXXXXXXX
Quadtruple DAC	01AAXXXXXXXXXXXXXX
Octal Latch	10XXXXXXXXXXXXXXXX

REV	Nov 14, 1992
REV	
CONTROL	
RELEASE	
ISSUED	Sept 15, 1991
ENGINEER	N. Yononaka

Space Physics Research Laboratory
 College of Engineering
 University of Michigan

SFM/ALP



NOTES:
 1. The total resistance of R5A+R5B must be approximately 20K ohms.

REV	Nov 14, 1992
CONTR'D	
RELEASE	
DRAWN	SPD 15 1991
ENGINEER	Block/Veronica

Space Physics Research Laboratory
 College of Engineering
 University of Michigan

PROJECT NUMBER SFM/ALP
 DATE 11/14/92

Grid 1 Bipolar Amplifier
 Grid Voltage Generator
 Solar Flux Monitor

1 1.3

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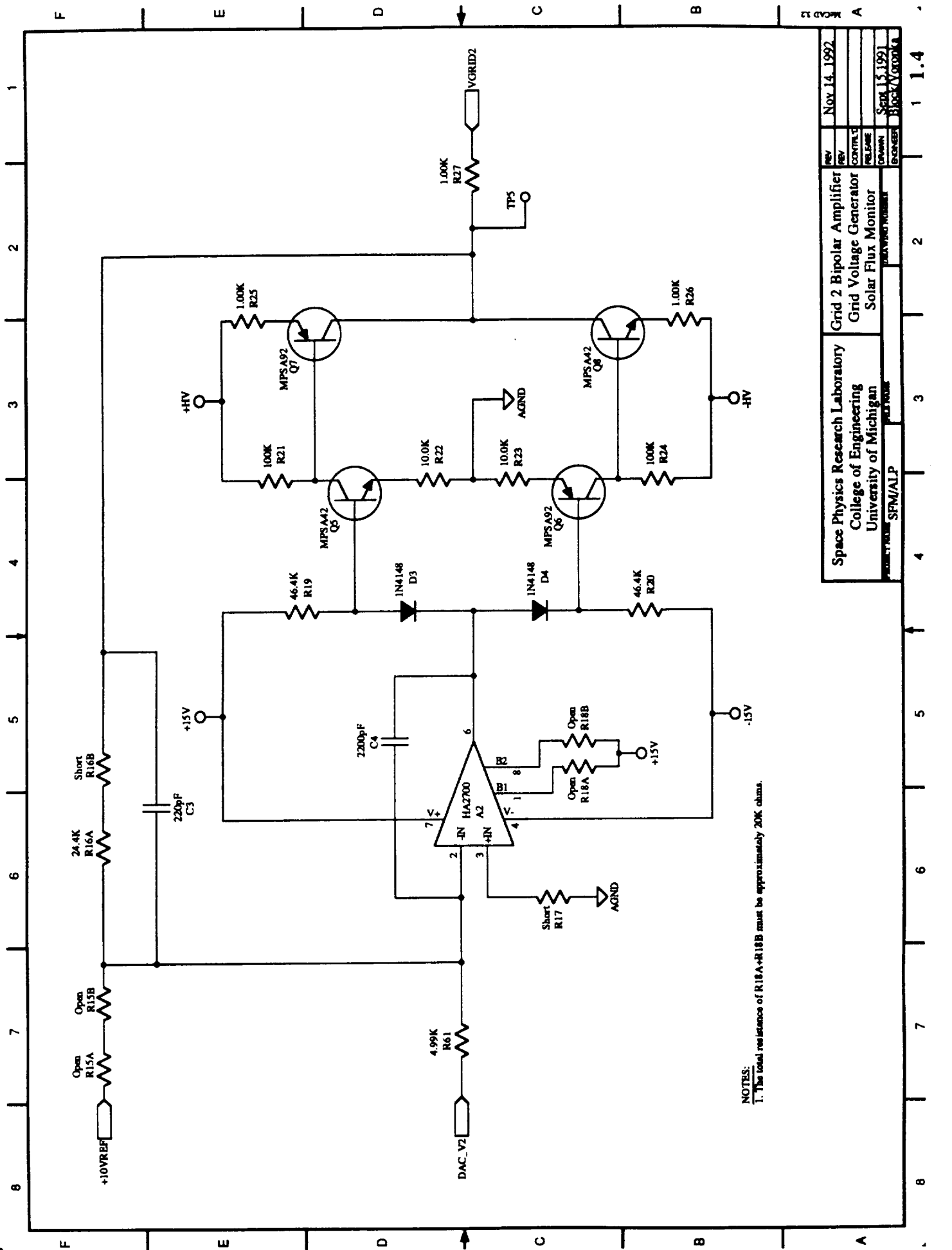
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MCAD 12

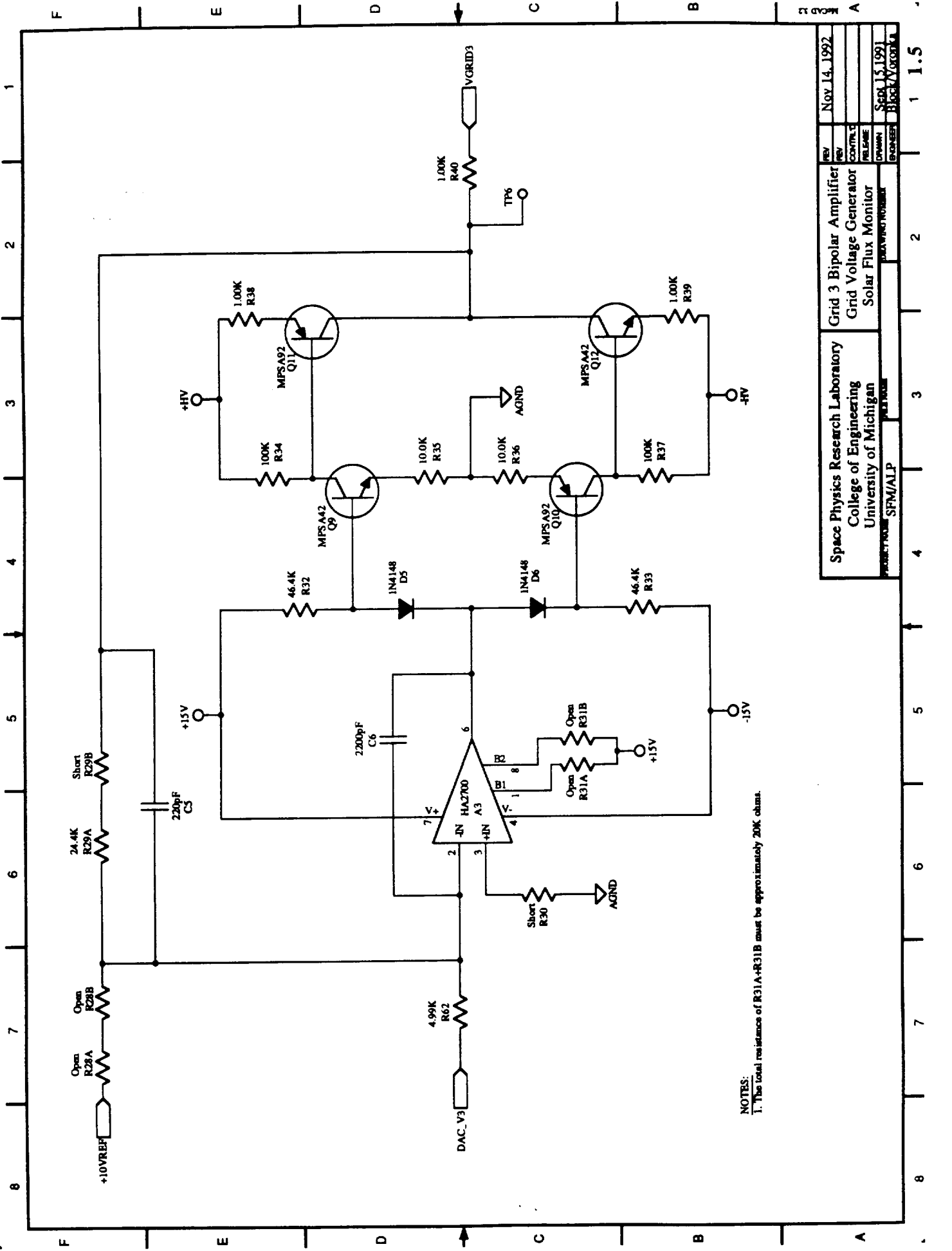


NOTES:
 1. The total resistance of R18A+R18B must be approximately 20K ohms.

REV	Nov 14, 1992
REV	
CONTROL	
RELEASE	
DATE	Nov 15, 1992
DESIGNER	Block/Corona

Space Physics Research Laboratory
 College of Engineering
 University of Michigan

PROJECT NUMBER: SPM/ALP
 TITLE: Grid 2 Bipolar Amplifier
 Grid Voltage Generator
 Solar Flux Monitor



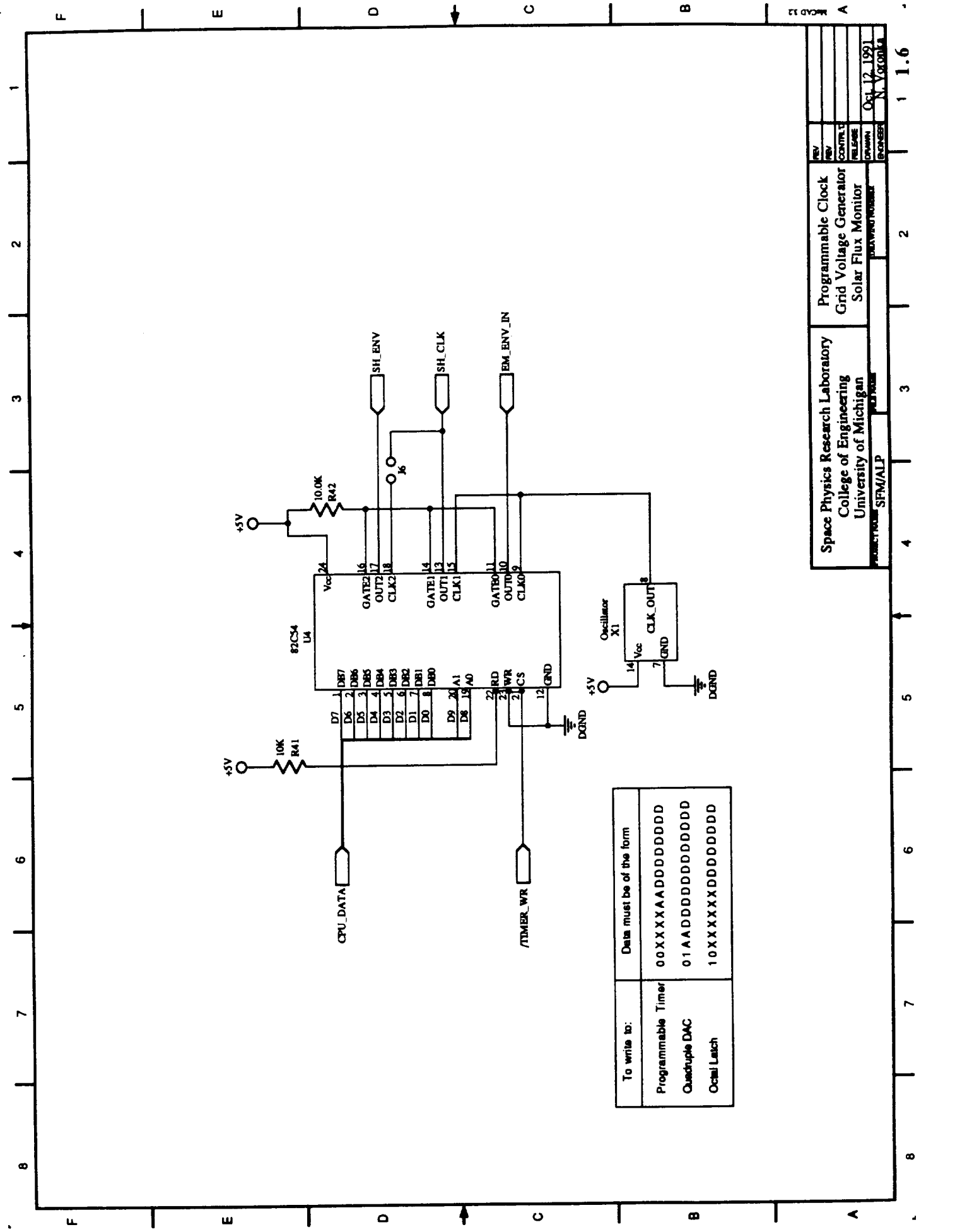
NOTES:
 1. The total resistance of R31A+R31B must be approximately 20K ohms.

REV	Nov 14, 1992
CONTROL	
RELEASE	
DRAWN	
ENGINEER	
DATE	SEP 15, 1991
PROJECT NUMBER	Block V/COO/VA

Space Physics Research Laboratory
 College of Engineering
 University of Michigan

SFM/ALP

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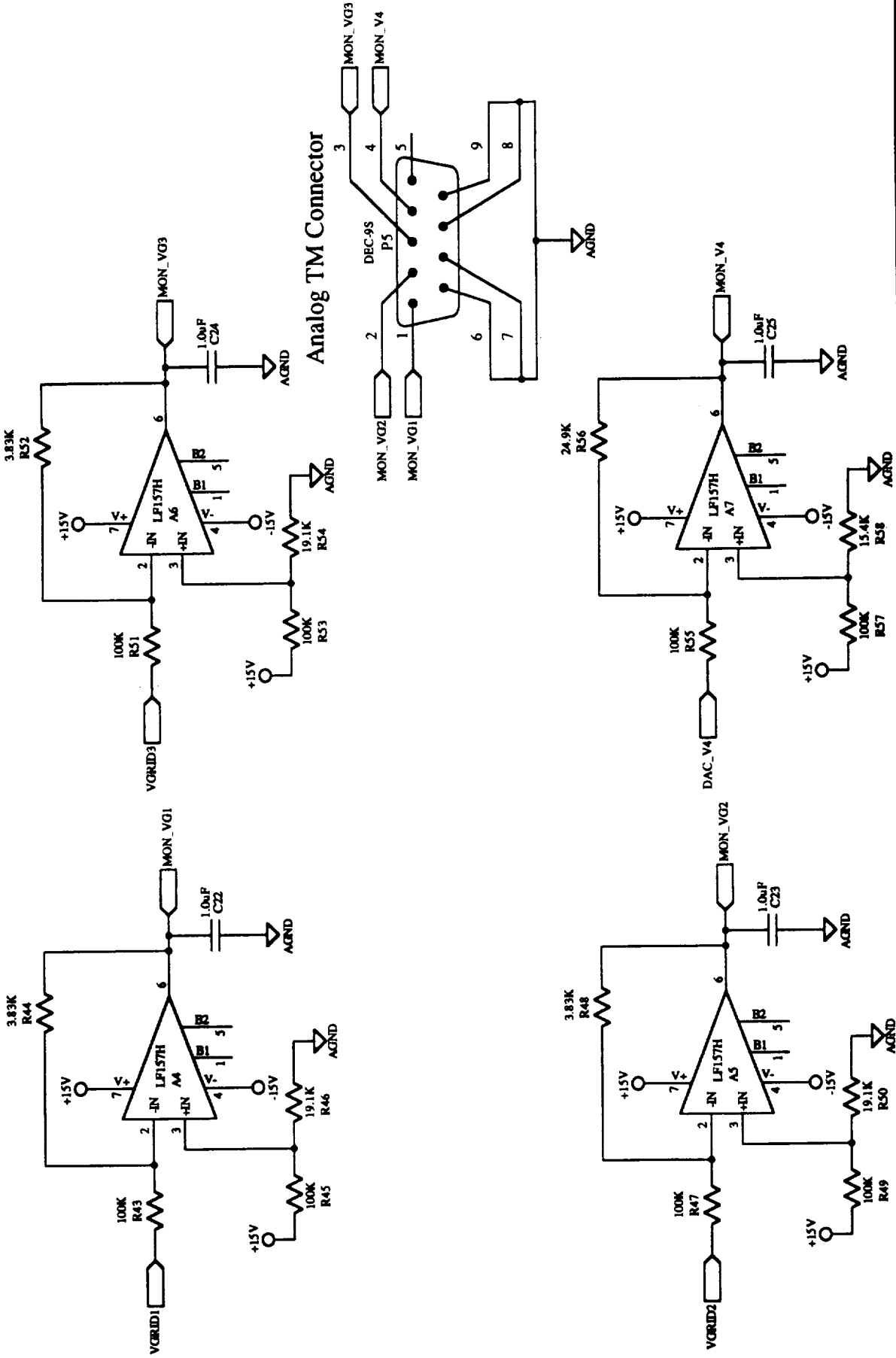
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Programmable Timer	00XXXXXXXXXXXXXXXX
Queueable DAC	01AAXXXXXXXXXXXXXX
Occal Latch	10XXXXXXXXXXXXXXXX

REV	
REV	
CONTROL	
RELEASE	
DATE	Oct 12 1991
DESIGNER	N. Y. GRIMA
PROJECT NUMBER	SFM/ALP

Space Physics Research Laboratory
 College of Engineering
 University of Michigan

Programmable Clock
 Grid Voltage Generator
 Solar Flux Monitor

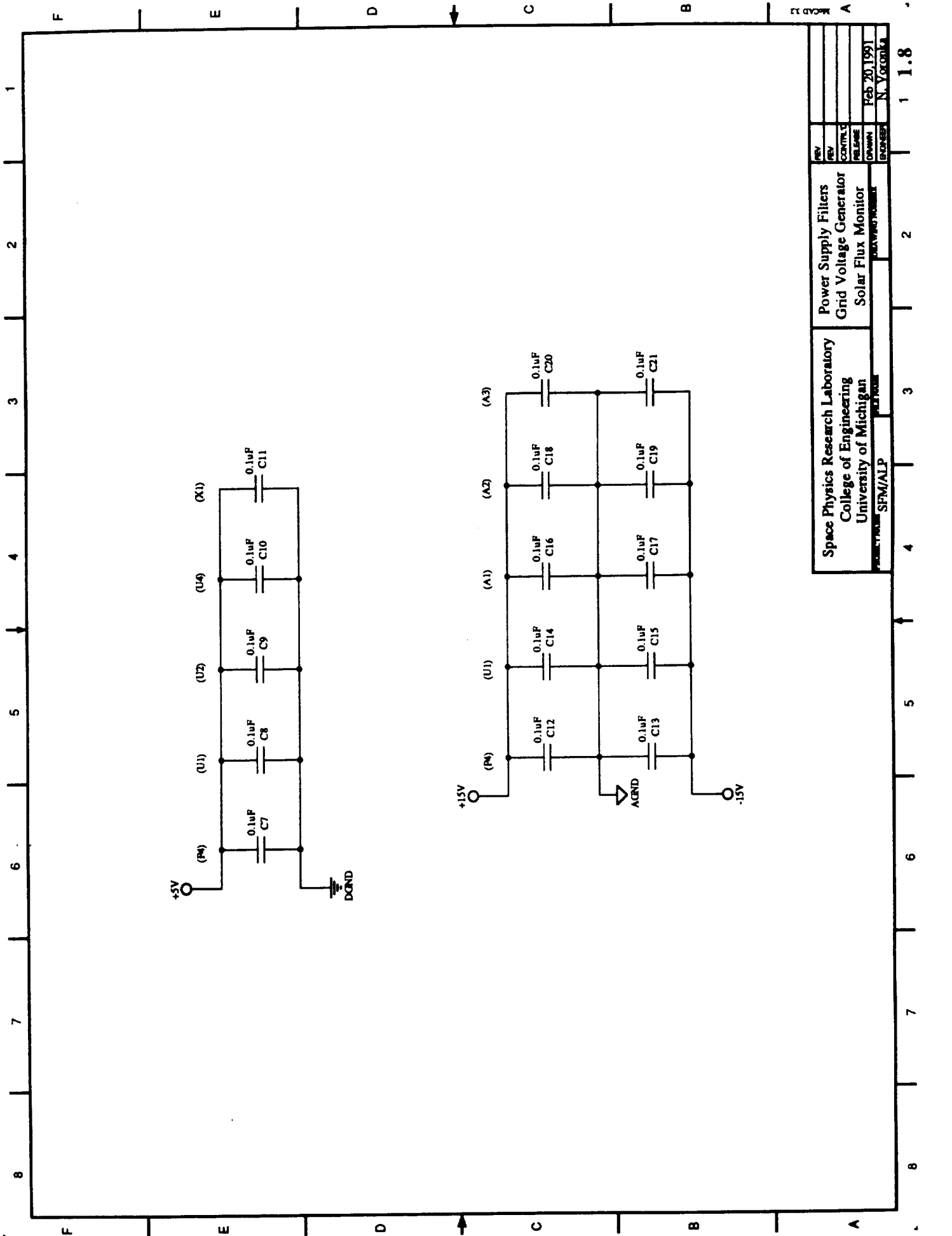
Analog TM Connector



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DESIGNER	N. VORONKA
DATE	FEB. 19, 1992
PROJECT	SPACE PHYSICS RESEARCH LABORATORY
TITLE	VOLTAGE MONITOR BUFFERS
DESCRIPTION	VOLTAGE MONITOR BUFFERS GRID VOLTAGE GENERATOR SOLAR FLUX MONITOR

SPACE PHYSICS RESEARCH LABORATORY	SRM/ALP
COLLEGE OF ENGINEERING	
UNIVERSITY OF MICHIGAN	

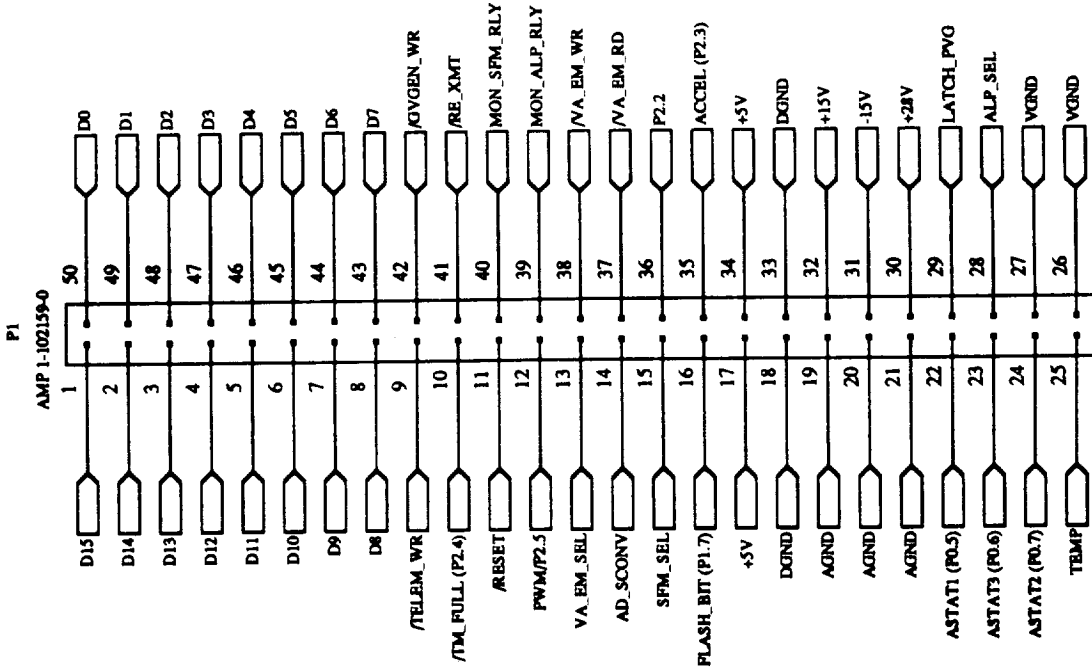
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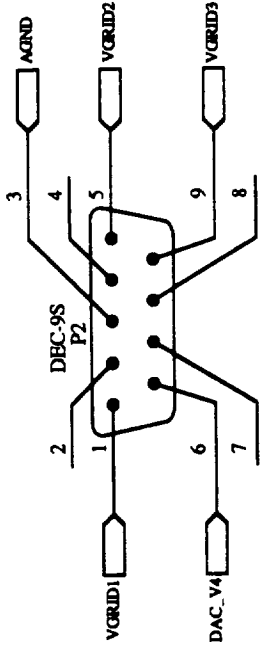
REV			
REV			
CONTROL			
RELEASE			
DATE	Feb 20 1991		
BY	N. Y. GONZA		

Space Physics Research Laboratory
 College of Engineering
 University of Michigan
 SPM/ALP
 POWER SUPPLY FILTERS
 Grid Voltage Generator
 Solar Flux Monitor
 1 1.8
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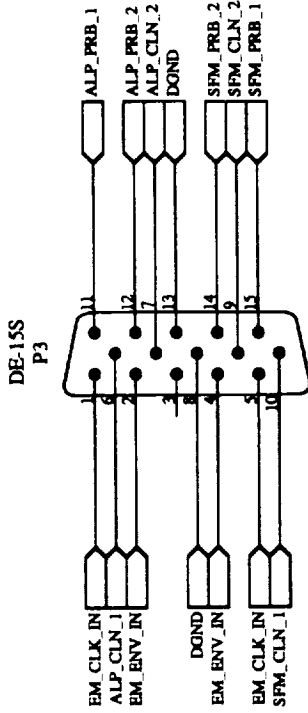
CPU Bus Connector



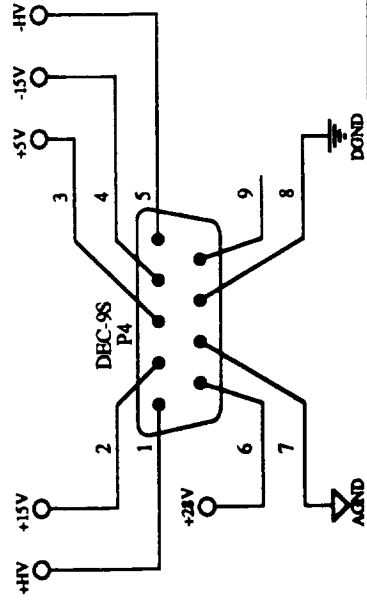
Grid Voltage Connector



Relay Control & Shift Clock Connector

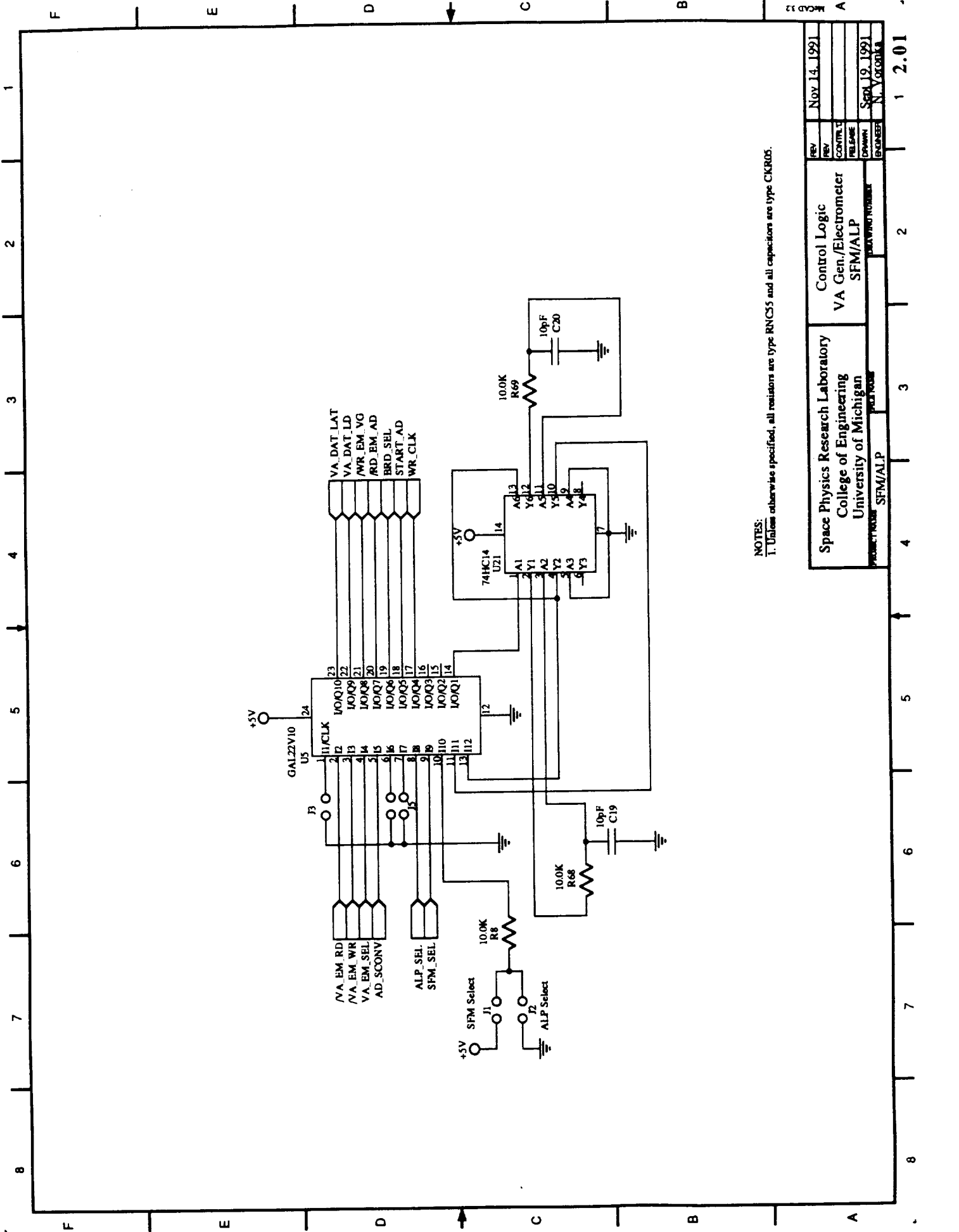


Power Supply Connector



Space Physics Research Laboratory College of Engineering University of Michigan	Connectors Grid Voltage Generator Solar Flux Monitor	Nov 14, 1992
DESIGNED: SFM/ALP	DRAWN: N. V. GONKA	REV: 1
CHECKED: SFM/ALP	APPROVED: SFM/ALP	DATE: Sept 14, 1991
		ENGINEER: N. V. GONKA

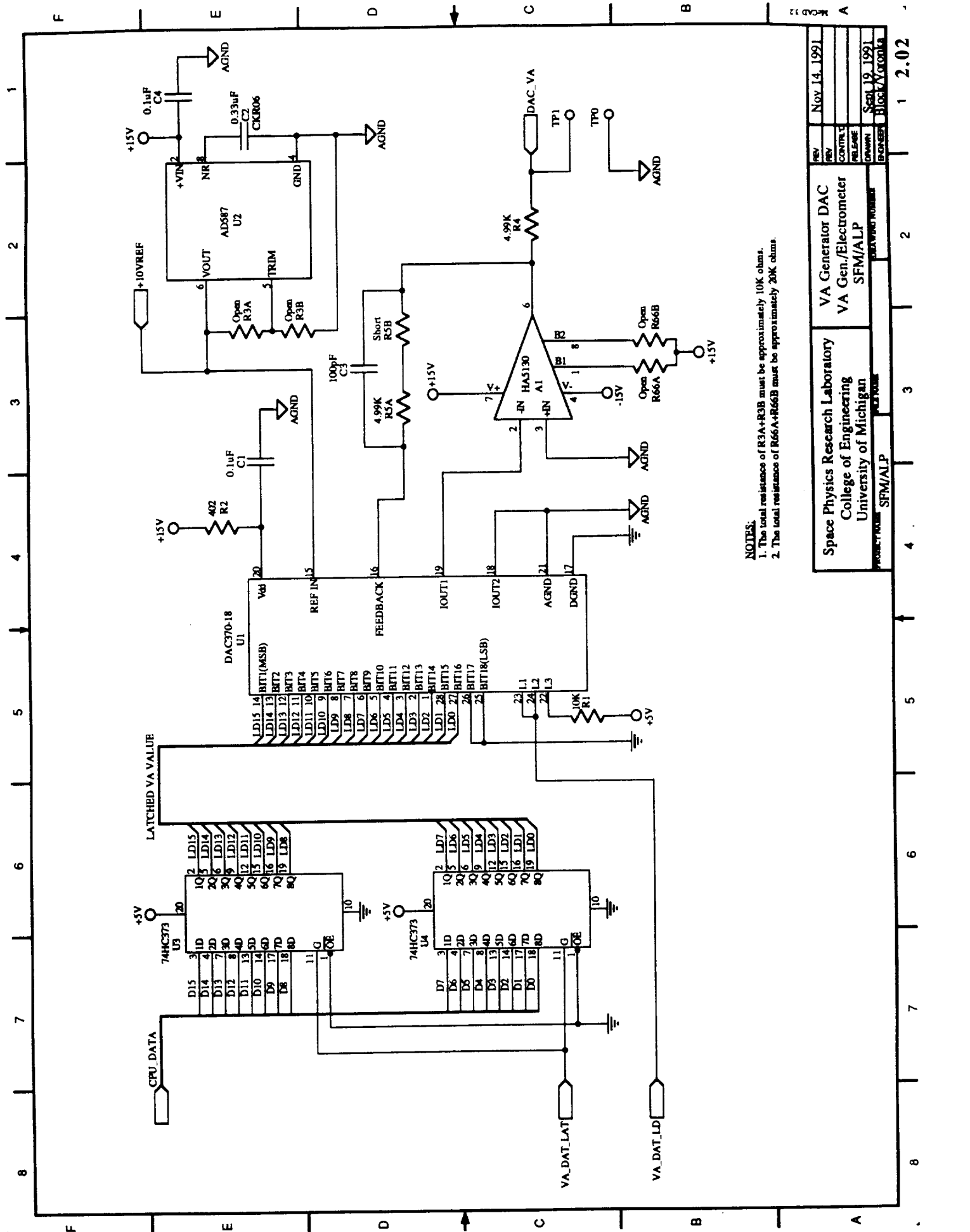
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NOTES:
 1. Unless otherwise specified, all resistors are type RNCS5 and all capacitors are type CKR05.

REV		Nov 14, 1991
REV		
CONTROL		
RELEASE		
DRAWN		Sept 19, 1991
CHECKER		N. V. COOK
PROJECT NUMBER		SFM/ALP
DRAWING NUMBER		
PAGE NUMBER		1
PAGE COUNT		2
DATE		1 2.01

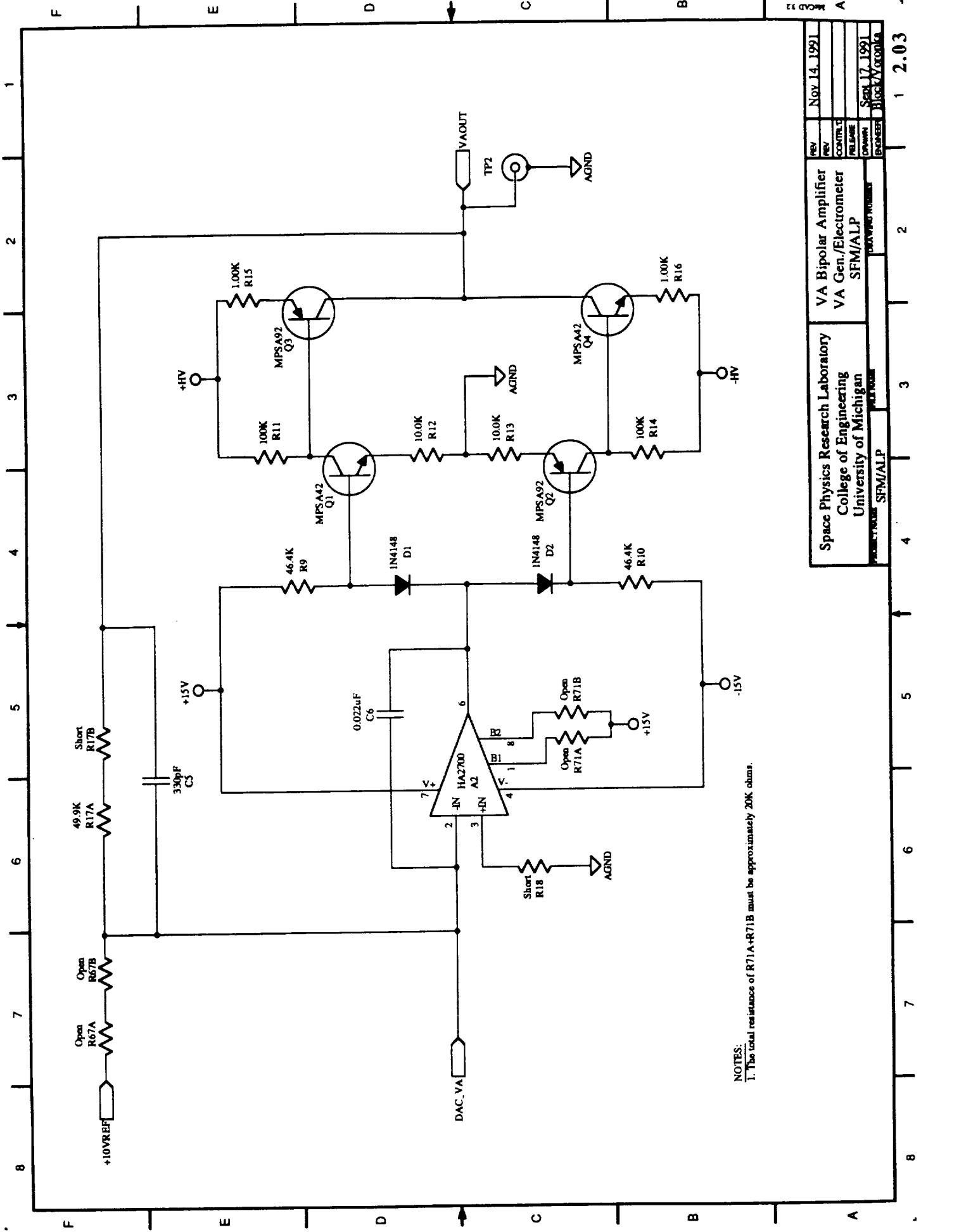
Space Physics Research Laboratory
 College of Engineering
 University of Michigan



NOTES:
 1. The total resistance of R3A+R3B must be approximately 10K ohms.
 2. The total resistance of R66A+R66B must be approximately 20K ohms.

REV	NOV 14 1991
CONTROL	
RELEASE	
OWNER	SEPT 19 1991
ENGINEER	BLOCK/ARONKA
DATA AND NOTES	
PROJECT	SFM/ALP
VA Generator DAC VA Gen./Electrometer SFM/ALP	
Space Physics Research Laboratory College of Engineering University of Michigan	

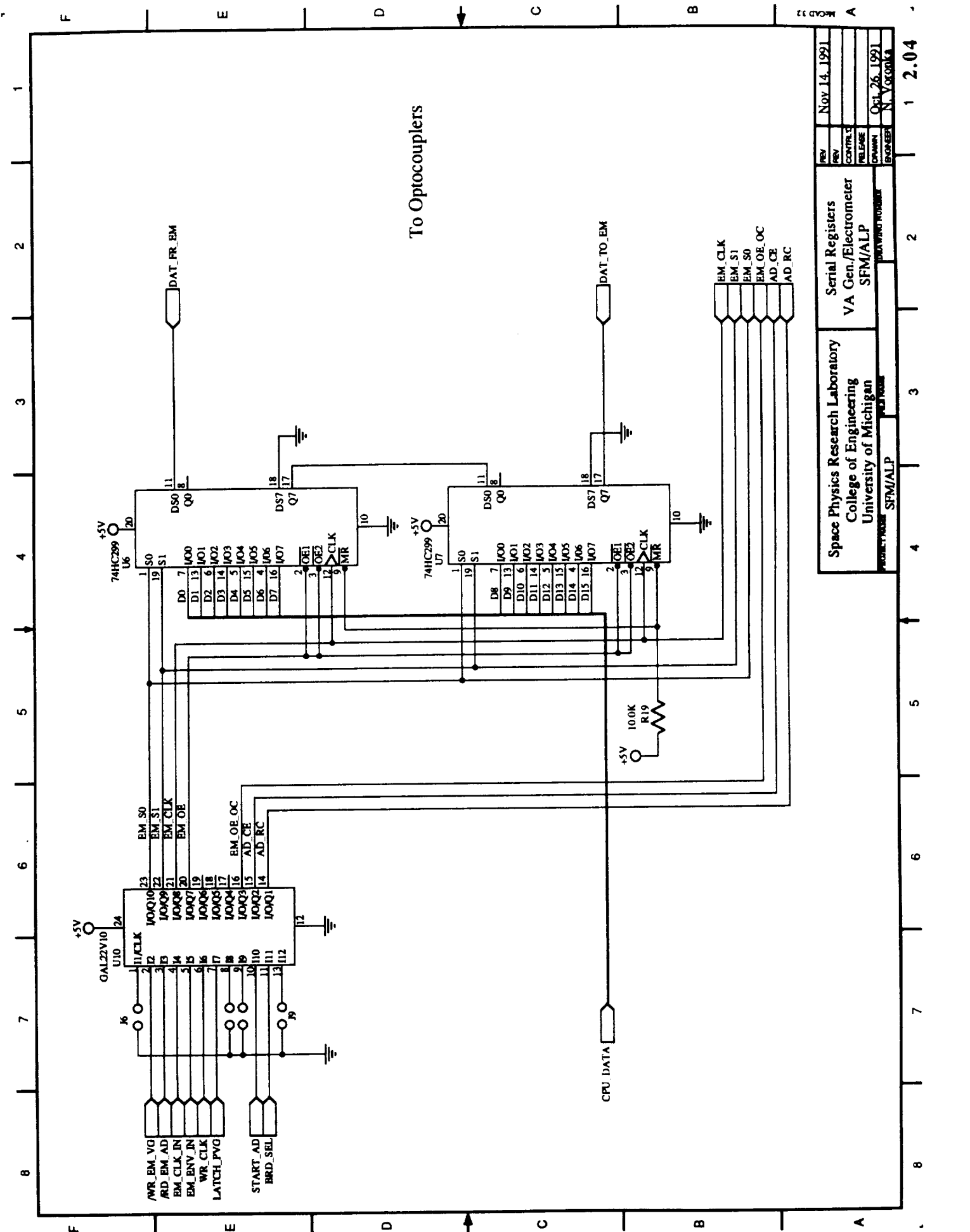
1 2.02



NOTES:
 1. The total resistance of R71A+R71B must be approximately 20K ohms.

REV	Nov 14, 1991
CONTRL	
RELEASE	
DATE	Sept 17, 1991
DESIGNER	BLOCK/KV/0001A
ENGINEER	
DRAWING NUMBER	
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PROJECT	
VA Bipolar Amplifier	
VA Gen./Electrometer	
SFM/ALP	

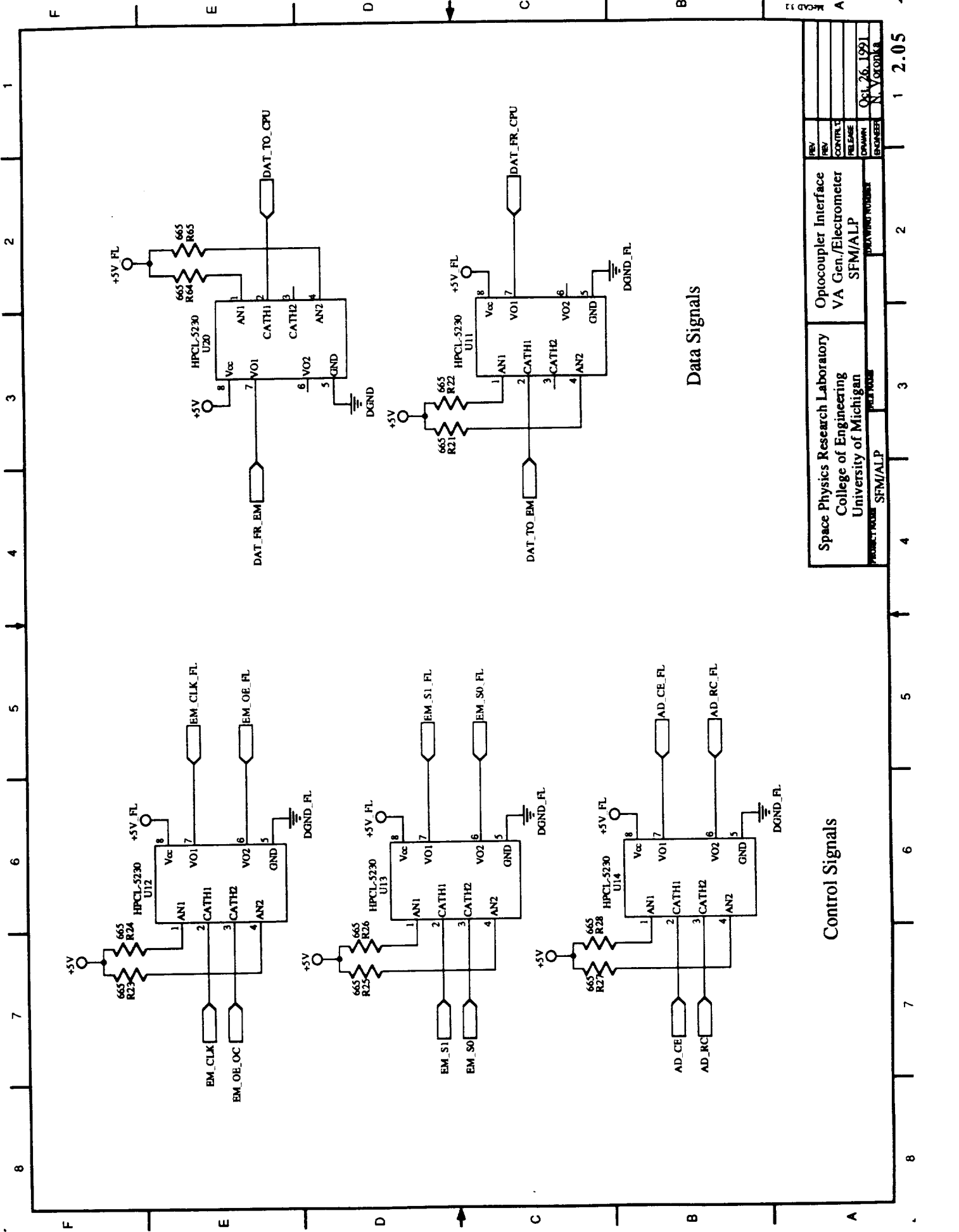
1 2.03



To Optocouplers

REV	Nov 14, 1991
CONTROL	
RELEASE	
DRAWN	Oct 26, 1991
ENGINEER	N. YOCUMKA

PROJECT NUMBER	SFM/ALP
DESIGNER	
DATE	
DESCRIPTION	Serial Registers VA Gen./Electrometer SFM/ALP

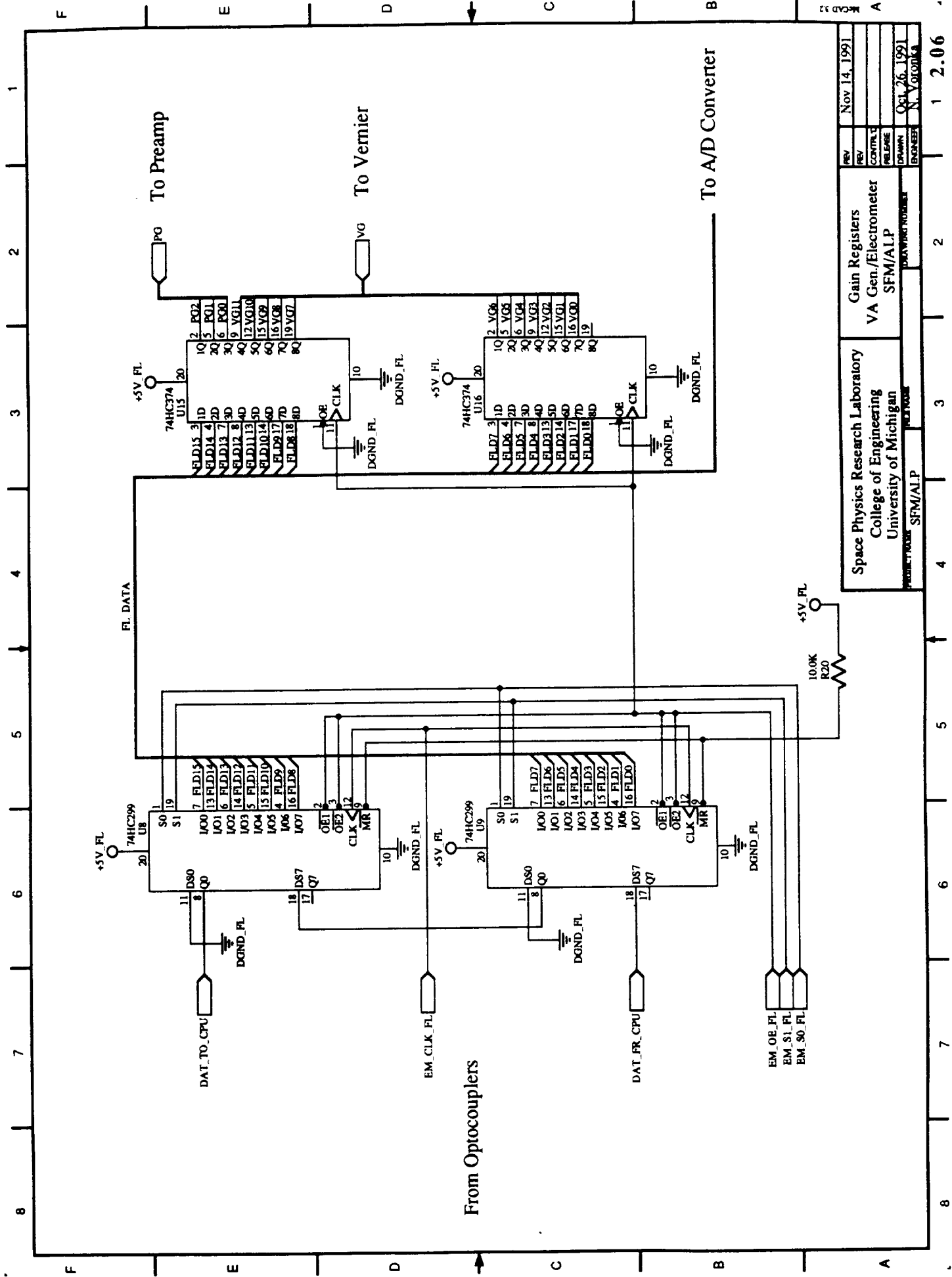


Data Signals

Control Signals

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Space Physics Research Laboratory College of Engineering University of Michigan			PROJECT NAME: SFM/ALP		
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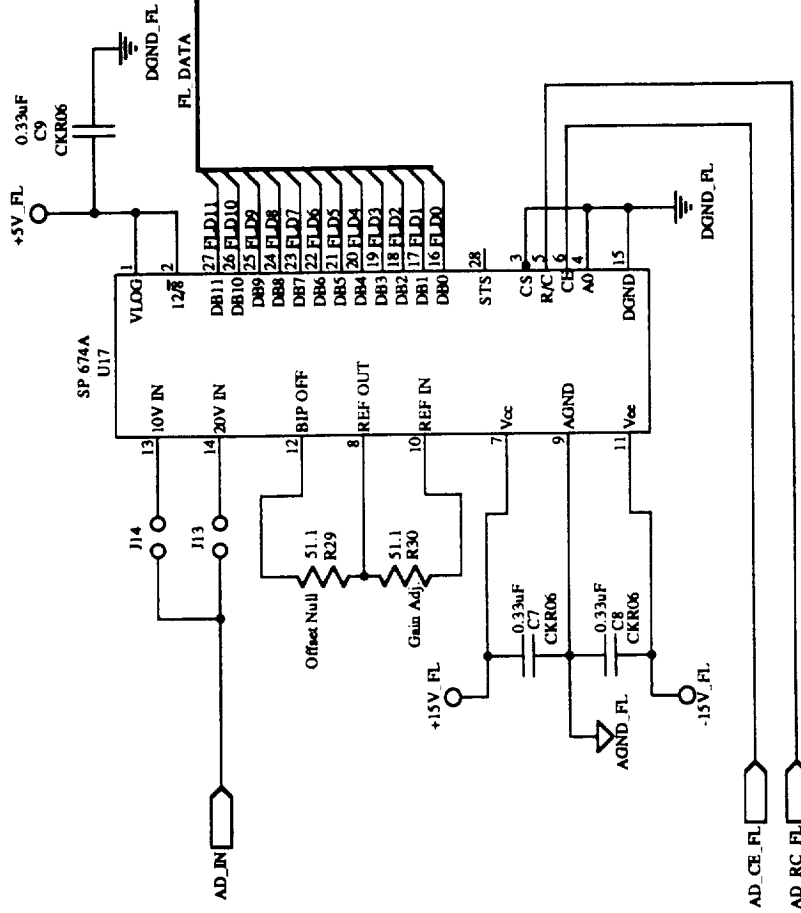


REV	Nov 14, 1991
CONTROL	
RELEASE	
DRAWN	Oct 26, 1991
EXAMINED	N. Voronka
Gain Registers	
VA Gen./Electrometer	
SFM/ALP	
PROJECT NUMBER	SFM/ALP
DRAWING NUMBER	

Space Physics Research Laboratory	1
College of Engineering	2
University of Michigan	3
SFM/ALP	4
10.0K	5
EM_OE_FL	6
EM_S1_FL	7
EM_S0_FL	8

1 2.06

To Shift Registers



A/D Converter

NOTES:
1. The values of resistors R29 and R30 must not exceed 100 ohms.

REV	Nov 14, 1991
REV	
CONTROL	
RELEASE	
DRAWN	Oct 11, 1991
ENGINEER	N. V. GONKAR
PRODUCT CODE	SFM/ALP
PROJECT NUMBER	
DESIGN NUMBER	
Electrometer A/D	
VA Gen./Electrometer	
SFM/ALP	
Space Physics Research Laboratory	
College of Engineering	
University of Michigan	

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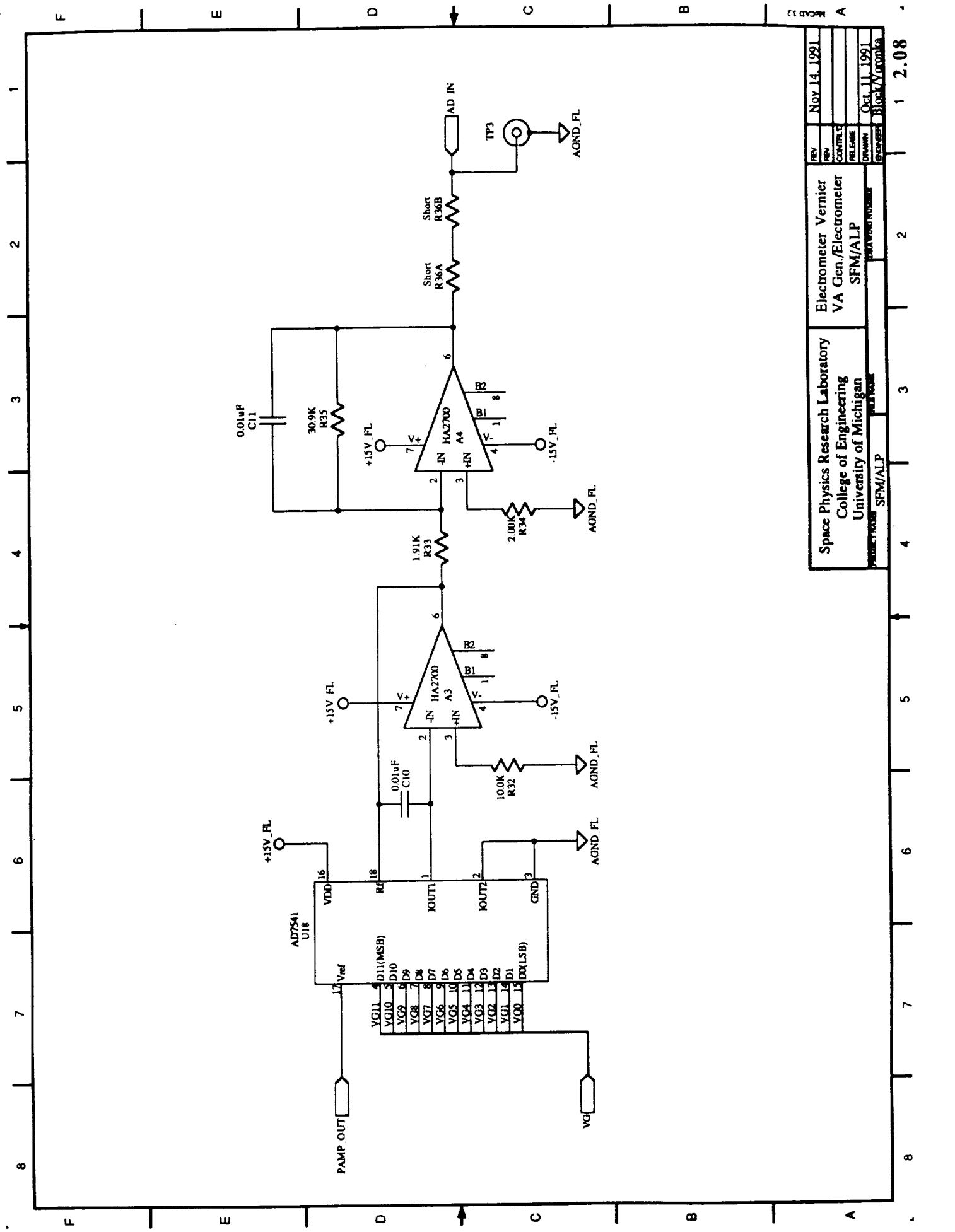
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REV	Nov 14, 1991
CONTROL	
RELEASE	
DRAWN	Oct 11, 1991
DESIGNED	BJG/AV/00016
Space Physics Research Laboratory College of Engineering University of Michigan	
Electrometer Vernier VA Gen./Electrometer SFM/ALP	
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FILE NUMBER: 81000100016	

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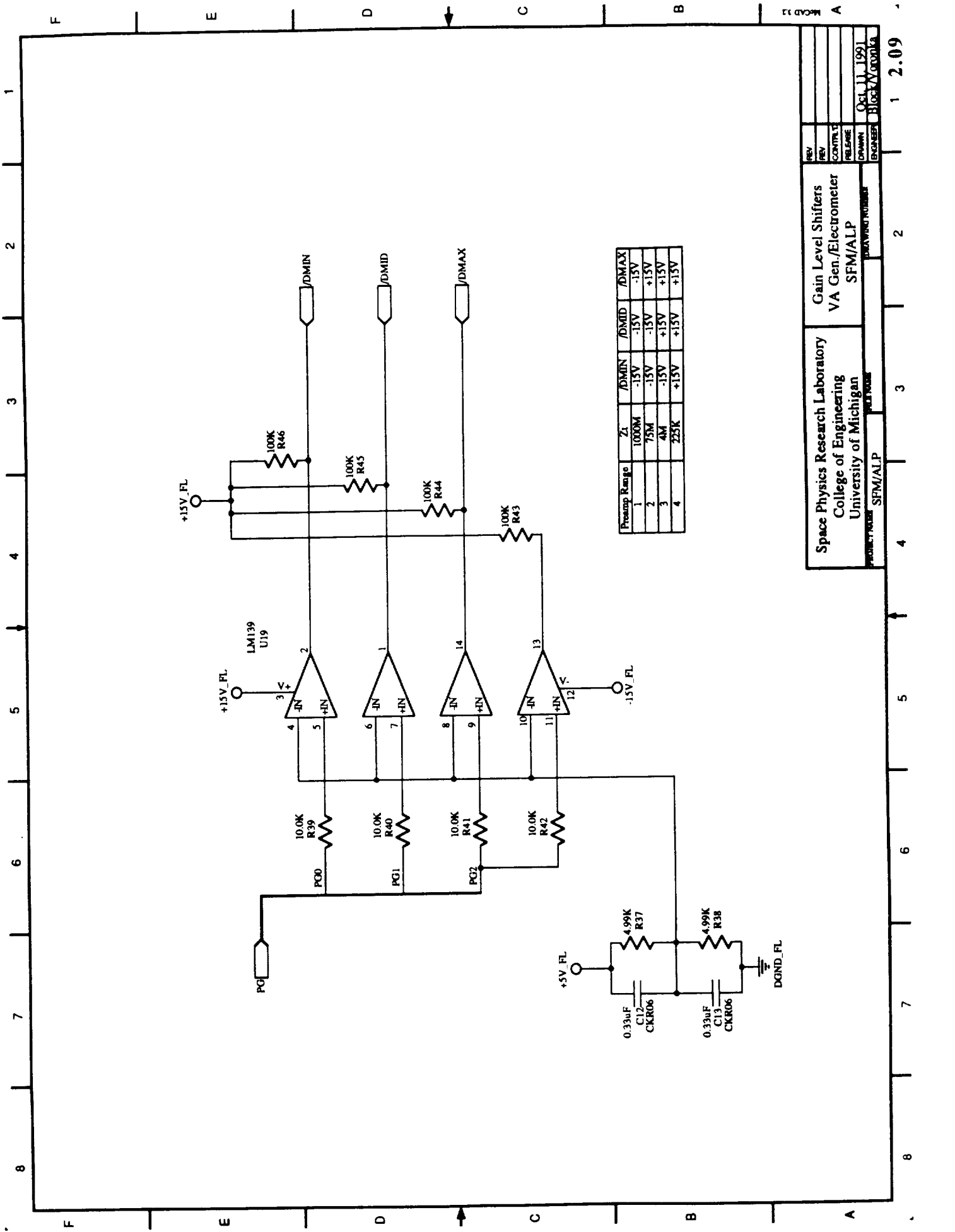
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6

7

8

F E D C B A



Preamp Range	Zi	/DMIN	/DMID	/DMAX
1	1000M	-15V	-15V	-15V
2	75M	-15V	-15V	+15V
3	4M	-15V	+15V	+15V
4	25K	+15V	+15V	+15V

REV		Gain Level Shifters
REV		VA Gen./Electrometer
CONTROL		SFM/ALP
RELEASE		
OWNER	Oct 11, 1991	
ENGINEER	BLOCH/VA Gen/VA	

Space Physics Research Laboratory
 College of Engineering
 University of Michigan

PROJECT NUMBER: SFM/ALP

1 2.09

2

3

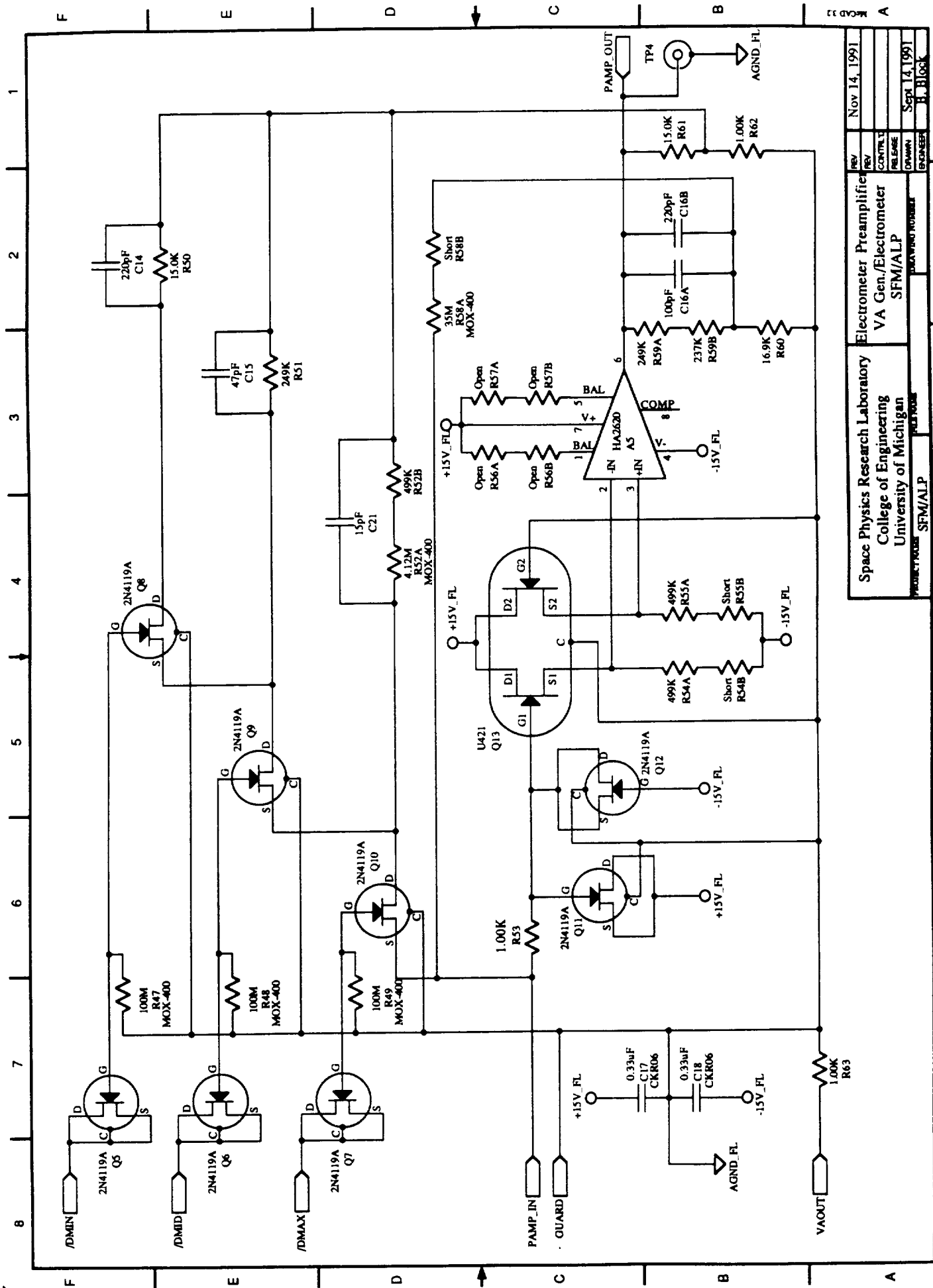
4

5

6

7

8

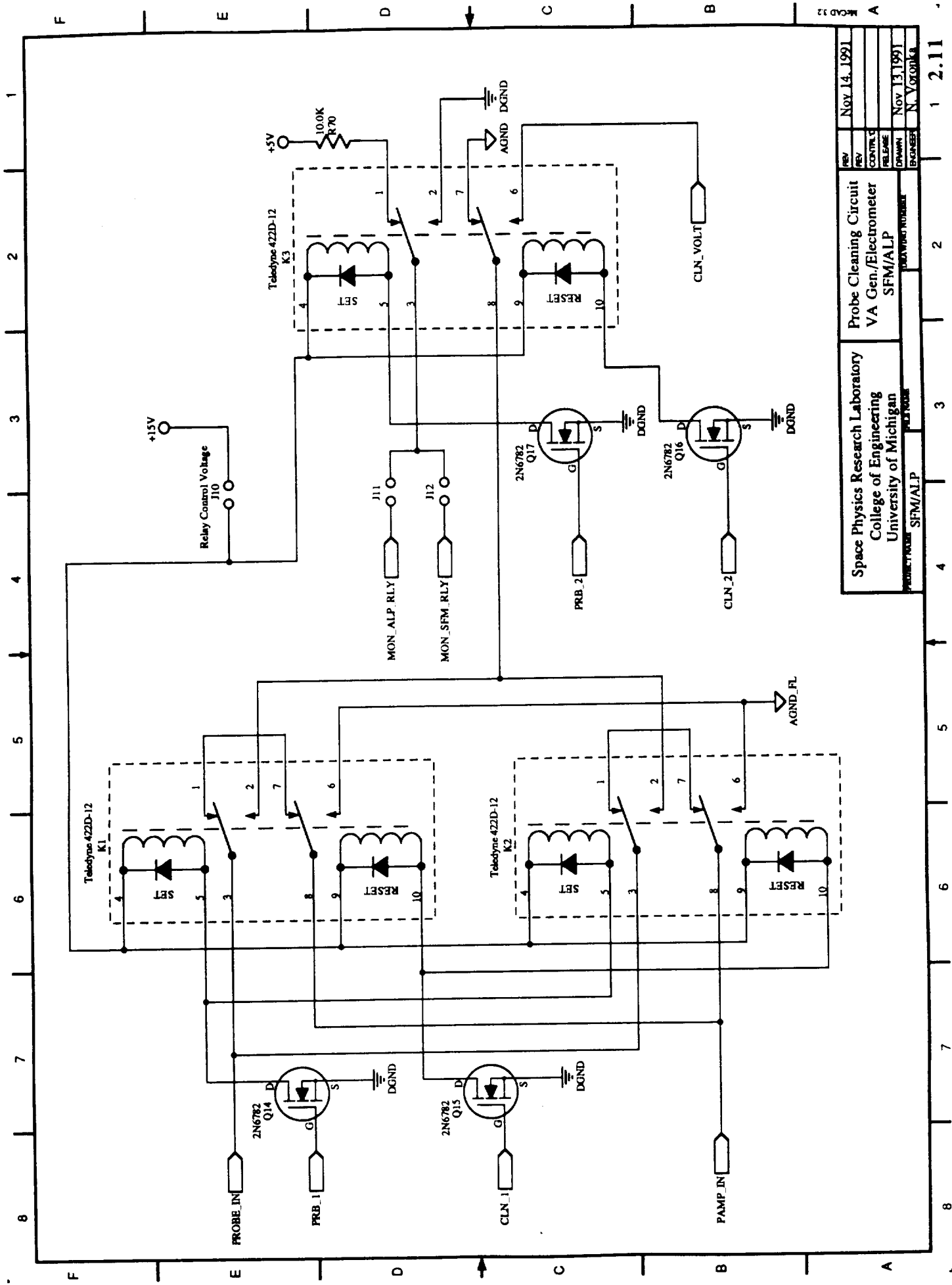


REV	Nov 14, 1991
DESIGNED BY	CONTROL
DRAWN BY	RELEASE
CHECKED BY	OPAWN
APPROVED BY	SEPT 14, 1991
PROJECT NO.	B. BLOCK

Space Physics Research Laboratory
 College of Engineering
 University of Michigan

Electrometer Preamplifier
 VA Gen./Electrometer
 SFM/ALP

PROJECT NO. SFM/ALP

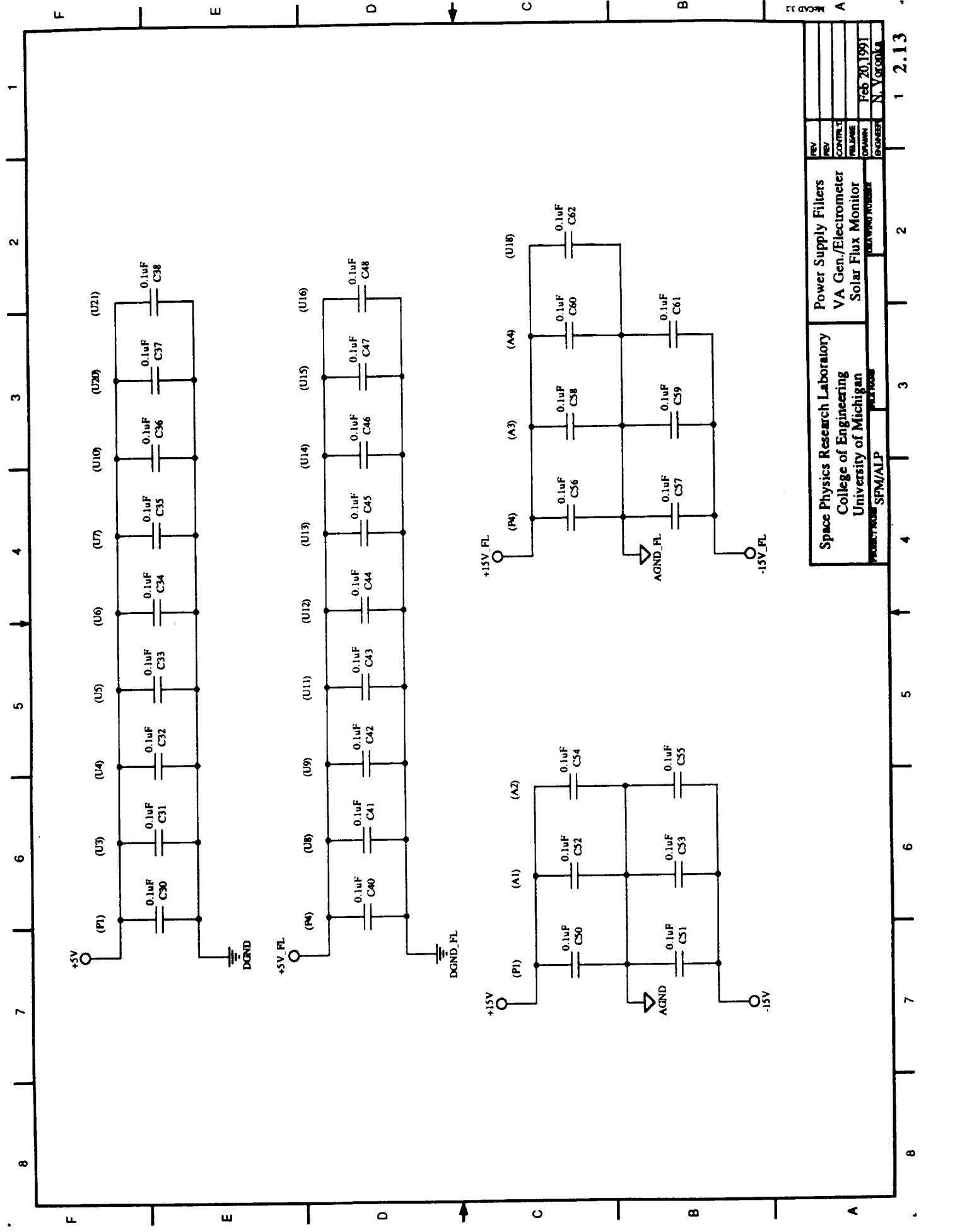


REV	NOV 14, 1991
CONTROL	
RELEASE	NOV 13, 1991
DRAWN	N. V. GONKA
ENGINEER	

Space Physics Research Laboratory
 College of Engineering
 University of Michigan

Probe Cleaning Circuit
 VA Gen./Electrometer
 SFM/ALP

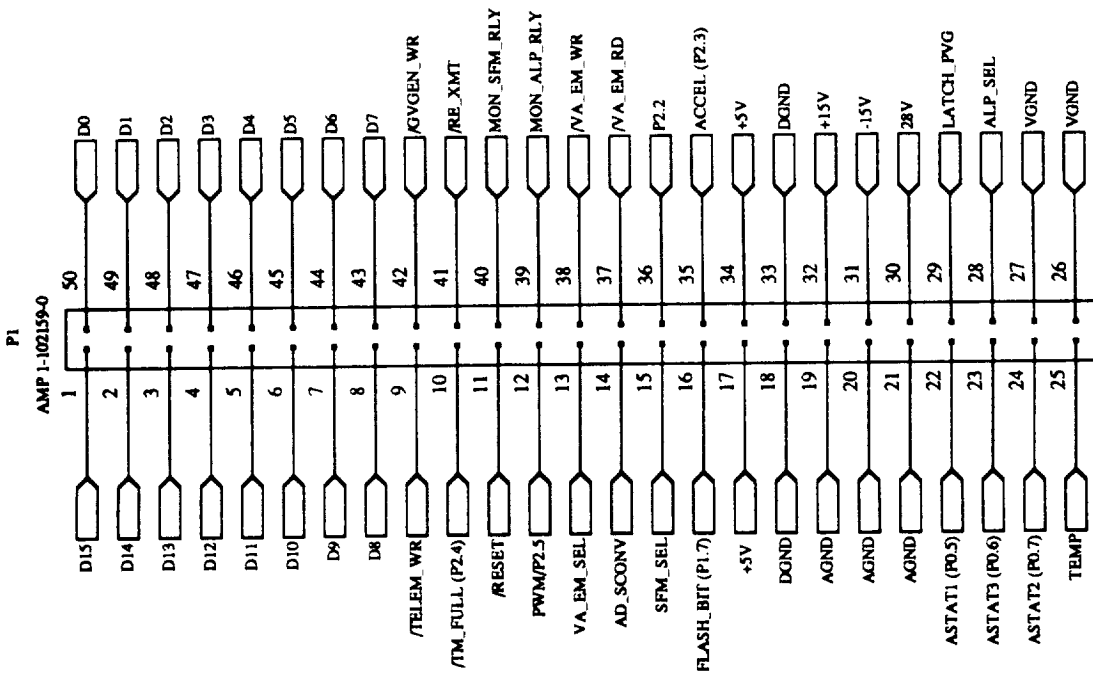
PROJECT NUMBER: SFM/ALP
 FILE NUMBER: 12.11



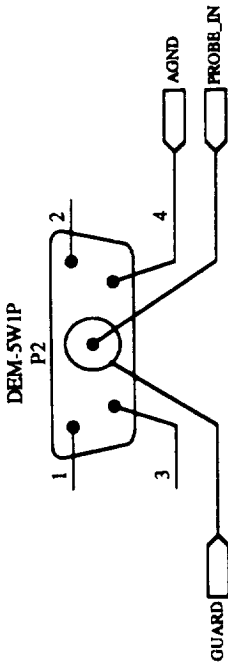
REV	REV	POWER SUPPLY FILTERS
CONTROL	CONTROL	VA GEN./ELECTROMETER
RELEASE	RELEASE	SOLAR FLUX MONITOR
DATE	DATE	
DESIGNED BY	DESIGNED BY	
CHECKED BY	CHECKED BY	
DATE	DATE	
PROJECT NUMBER	PROJECT NUMBER	
DESIGN NUMBER	DESIGN NUMBER	
ENGINEER	ENGINEER	N. YORONKA
DATE	DATE	FEB 20, 1991

Space Physics Research Laboratory
 College of Engineering
 University of Michigan

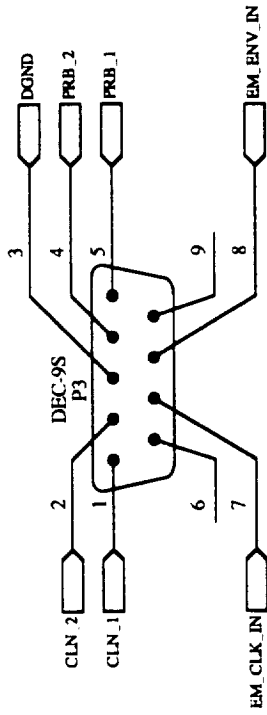
System Connector



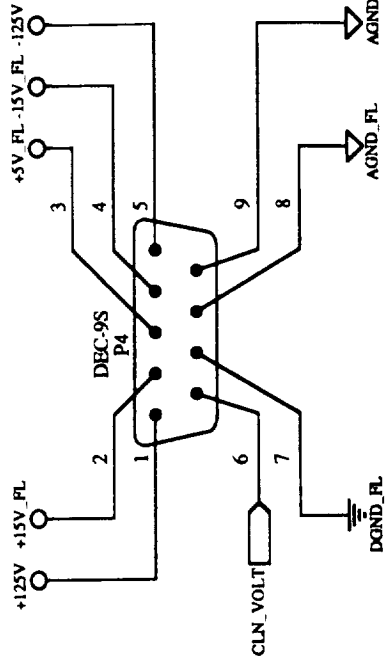
Sensor Connector



Relay Control & Shift Clock Connector

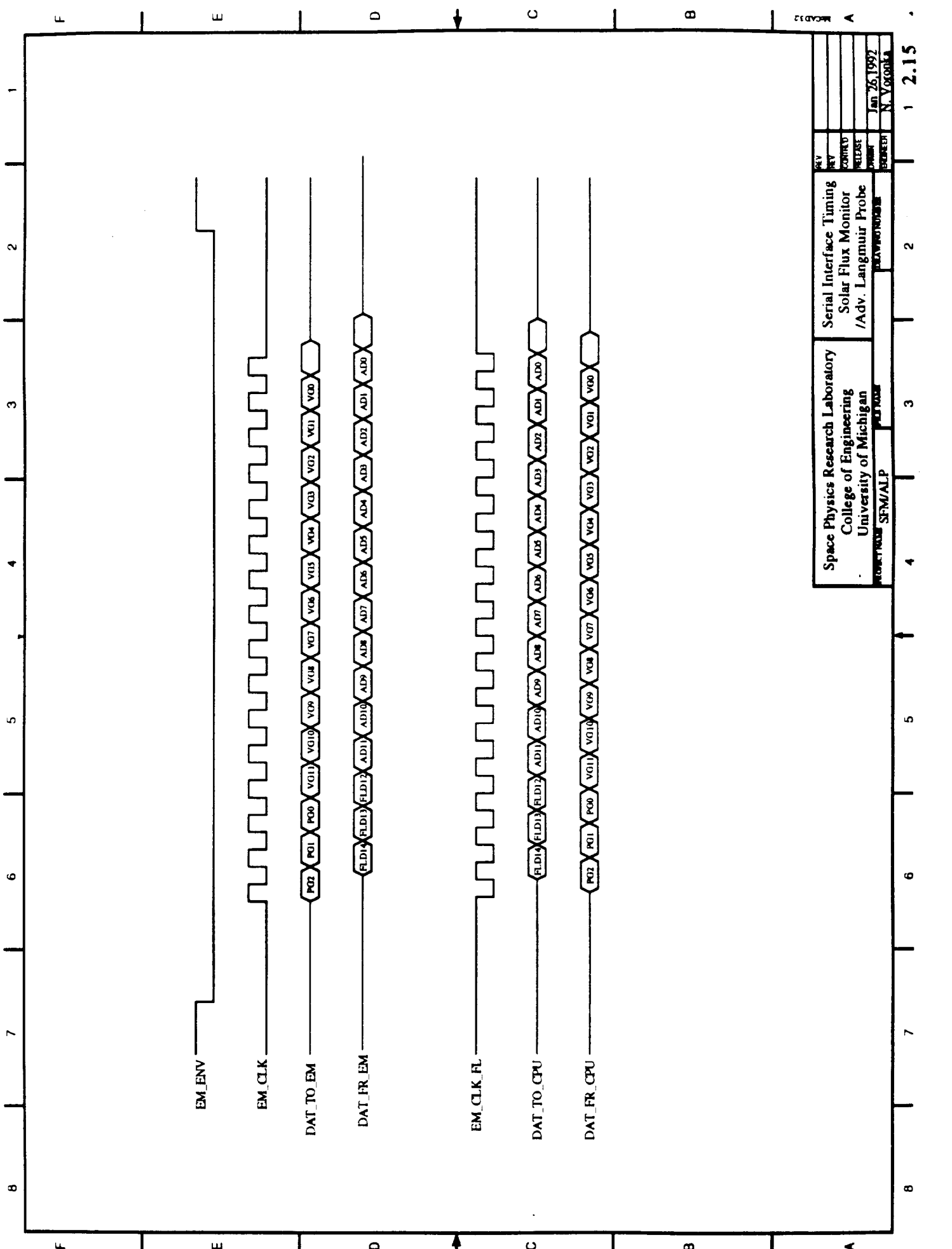


Power Supply Connector



NOTES:
1. A jumper must be installed between pin 3 of P2 (GUARD) and pin 8 of P4 (AGND_FL).

REV	
CONTROL	
RELEASE	
DATE	Sept 14, 1991
ENGINEER	N. V. GONKA
DESIGNED BY	
CHECKED BY	
APPROVED BY	
PROJECT NO.	SFM/ALP
CONTRACT NO.	
CONNECTORS	Connectors
VA GEN/Electrometer	VA Gen/Electrometer
SFM/ALP	SFM/ALP

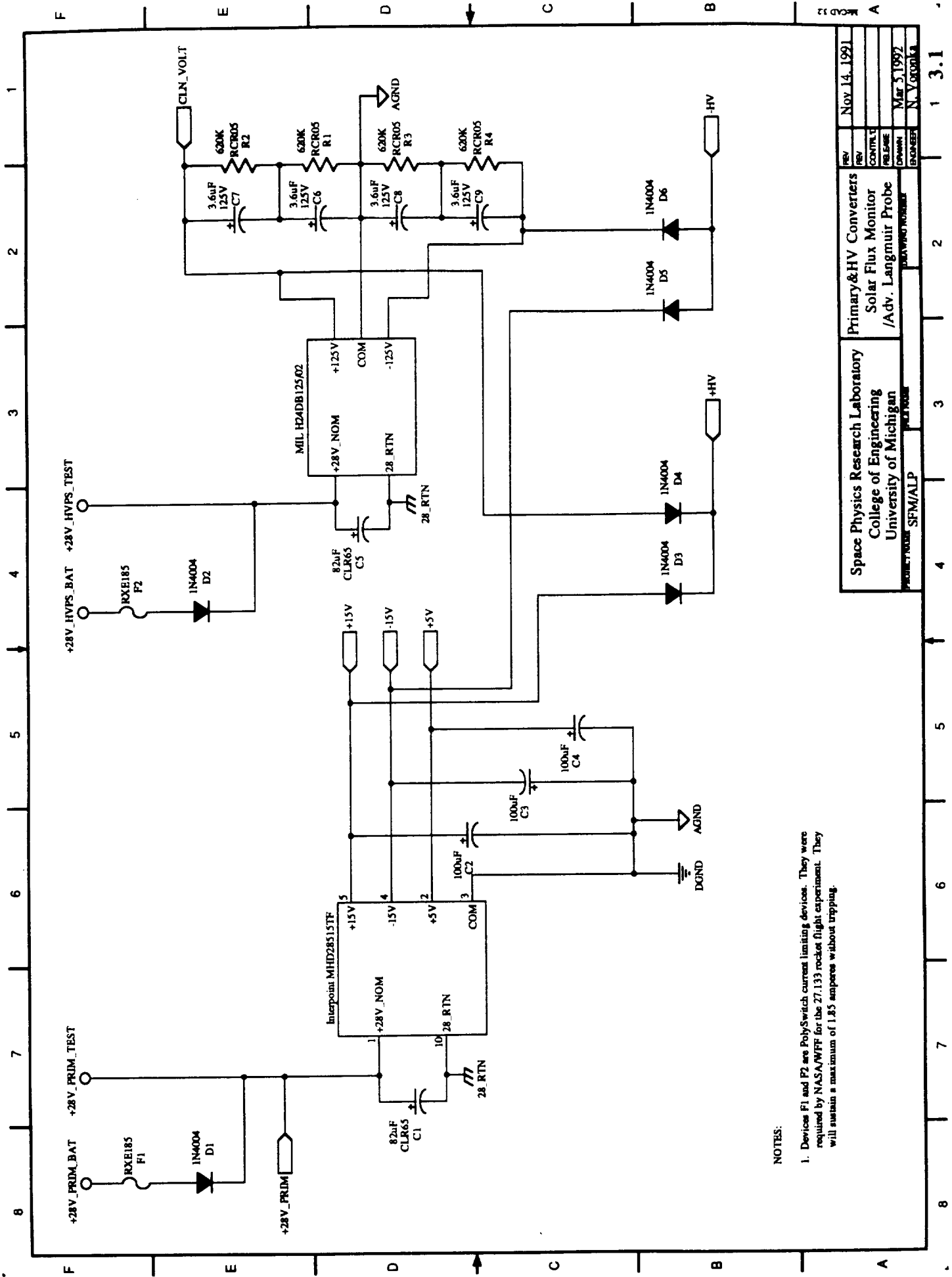


REV			
REV			
CONTRD			
RELEASE			
DATE	Jan 26, 1992		
BY	N. V. GONKA		
PROJECT NO.	SFM/ALP		
FILE NO.			
PLANNING NO.			

Space Physics Research Laboratory
 College of Engineering
 University of Michigan

Serial Interface Timing
 Solar Flux Monitor
 /Adv. Langmuir Probe

1 2.15



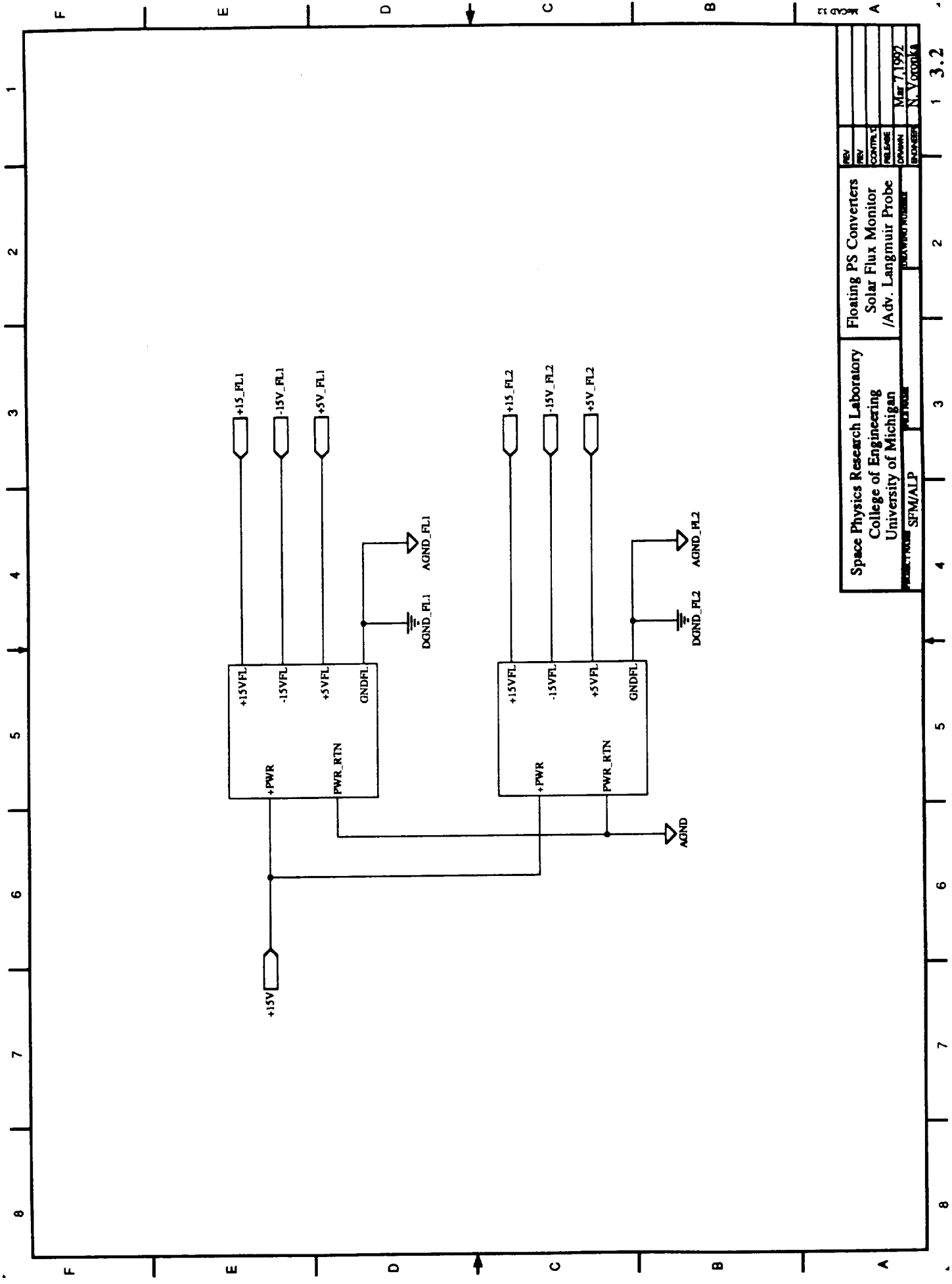
NOTES:

1. Devices F1 and F2 are PolySwitch current limiting devices. They were required by NASA/WFF for the 27.133 rocket flight experiment. They will sustain a maximum of 1.85 amperes without tripping.

PROJECT NUMBER		REV		DATE	
SFMA/ALP		Nov 14, 1991		1 3.1	
DESIGN NUMBER		CONTROL		REV	
SFMA/ALP		Solar Flux Monitor		REV	
FILE NAME		RELEASE		DRAWN	
SFMA/ALP		/Adv. Langmuir Probe		Mar 5, 1992	
FILE NAME		ENGINEER		N. Y. Gorka	

Space Physics Research Laboratory
 College of Engineering
 University of Michigan

Primary & HV Converters
 Solar Flux Monitor
 /Adv. Langmuir Probe

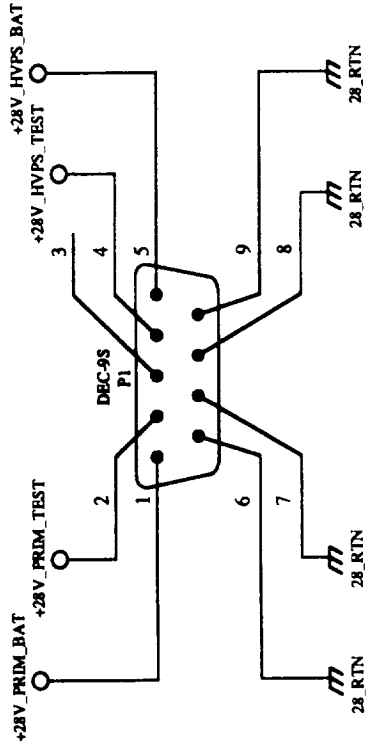


REV	REV	Floating PS Converters Solar Flux Monitor /Adv. Langmuir Probe	PROJECT LEADER SFM/ALP	SPACE PHYSICS RESEARCH LABORATORY COLLEGE OF ENGINEERING UNIVERSITY OF MICHIGAN
CONTR	CONTR			
DESIGN	DESIGN			
DATE	DATE			
DESIGNER	DESIGNER	Mar 7, 1992		
ENGINEER	ENGINEER			N. VOTONKA

1 2 3 4 5 6 7 8

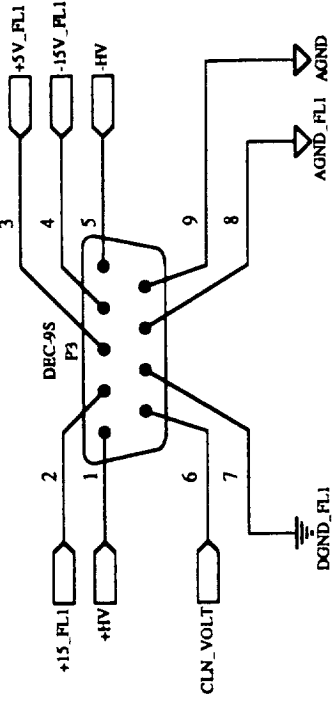
1 3.2

Primary Power Connector (to SC)



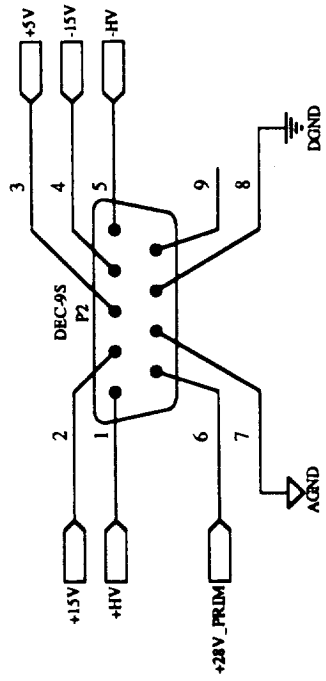
Power Supply Connector

ALP VA Gen./Electrometer



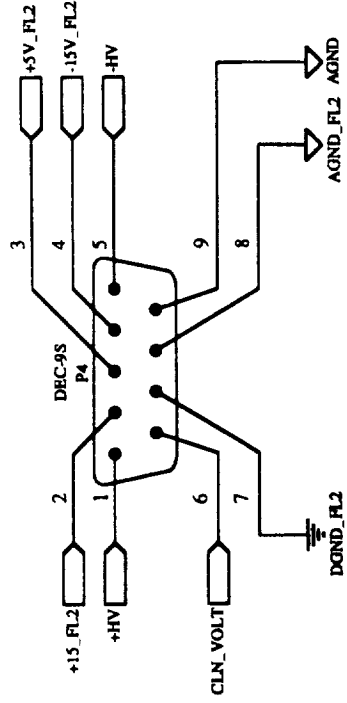
Power Supply Connector

Grid Voltage Generator



Power Supply Connector

SFM VA Gen./Electrometer

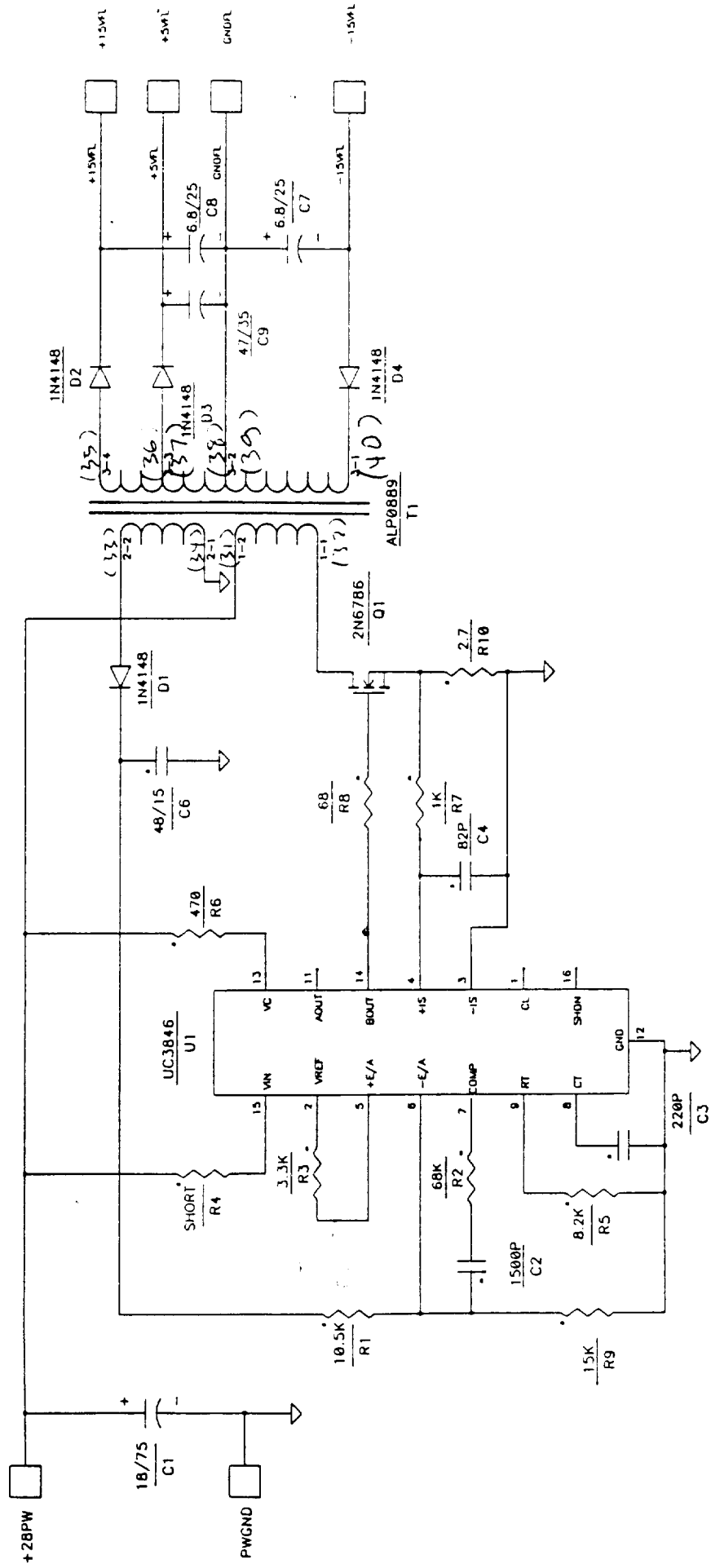


PROJECT NAME	SFM/ALP	DATE	Jan 9 1992
DESIGNER	N. Y. GONG	REVISION	
DRAWN		CONTROL	
RELEASE		DATE	
APPROVED		BY	

Space Physics Research Laboratory
 College of Engineering
 University of Michigan

Power Supply Connectors
 Solar Flux Monitor
 /Adv. Langmuir Probe

PCB PART NUMBER



ENGINEER	BLOCK	DRAFTSMAN	8/26/89
SPACE PHYSICS RESEARCH LABORATORY		+/- 15, +5 POWER SUPPLY	
COLLEGE OF ENGINEERING		CURRENT-MODE TECHNOLOGY	
UNIVERSITY OF MICHIGAN		CRAF-NGIMS/ALP	
ANN ARBOR, MICHIGAN		B-E8574	
		DATE	

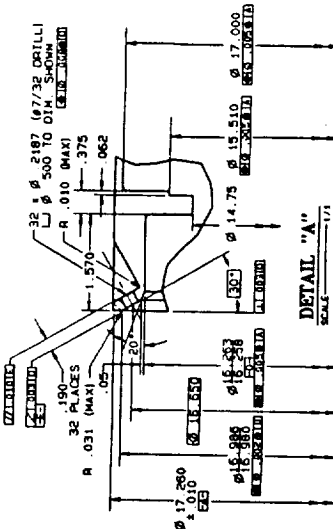
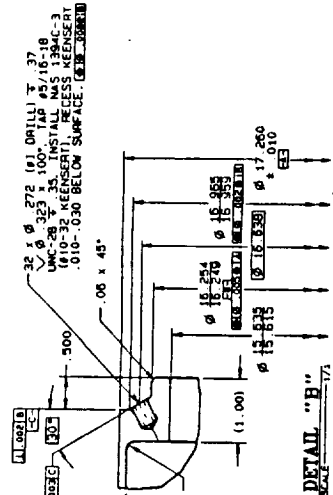
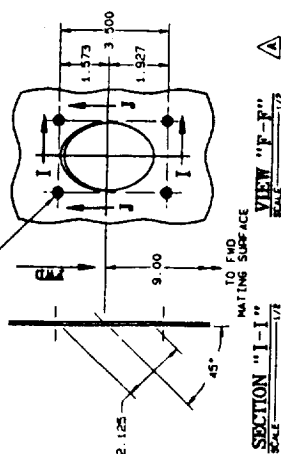
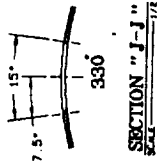
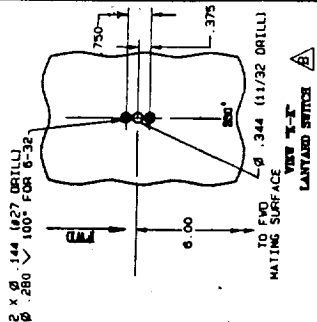
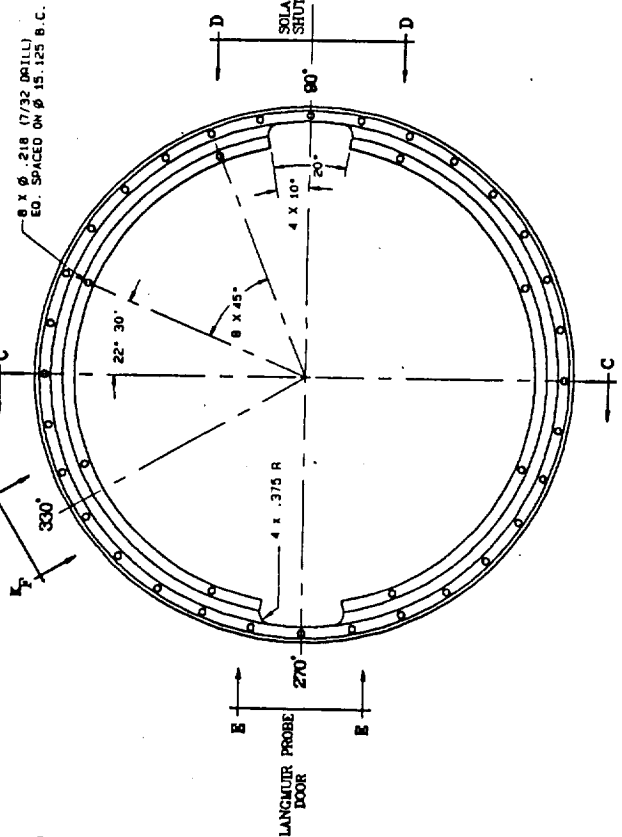
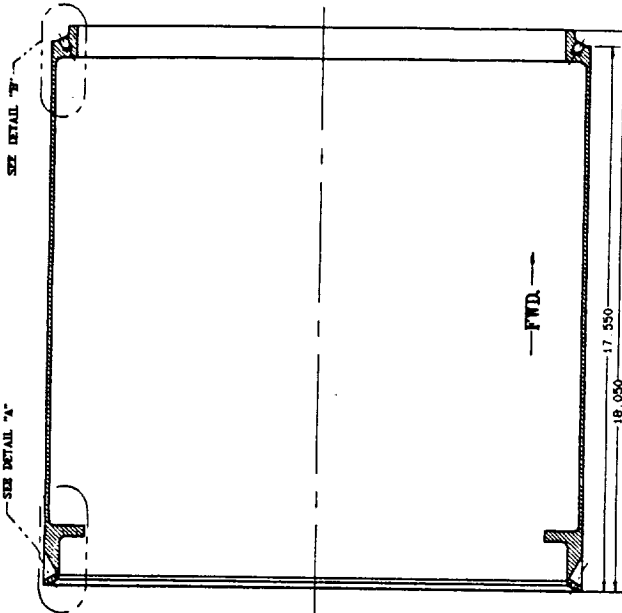
LAST USED R

APPENDIX C

SEUV/ALP Mechanical Drawings

D-27-18698

DATE	LET	REVISION
4/92	A	ADDED 61 PIN UM81
4/92	B	ADDED LANYARD SWITCH
4/92	C	ADDED OVERALL DIMENSION 18.050



ITEM	QTY	DESCRIPTION	SCALE	DATE	BY
1	1	DOOR	1/2		
2	1	FLANGE	1/2		

DATE	BY	REVISION
4/92	A	ADDED 61 PIN UM81
4/92	B	ADDED LANYARD SWITCH
4/92	C	ADDED OVERALL DIMENSION 18.050

DATE	BY	REVISION
4/92	A	ADDED 61 PIN UM81
4/92	B	ADDED LANYARD SWITCH
4/92	C	ADDED OVERALL DIMENSION 18.050

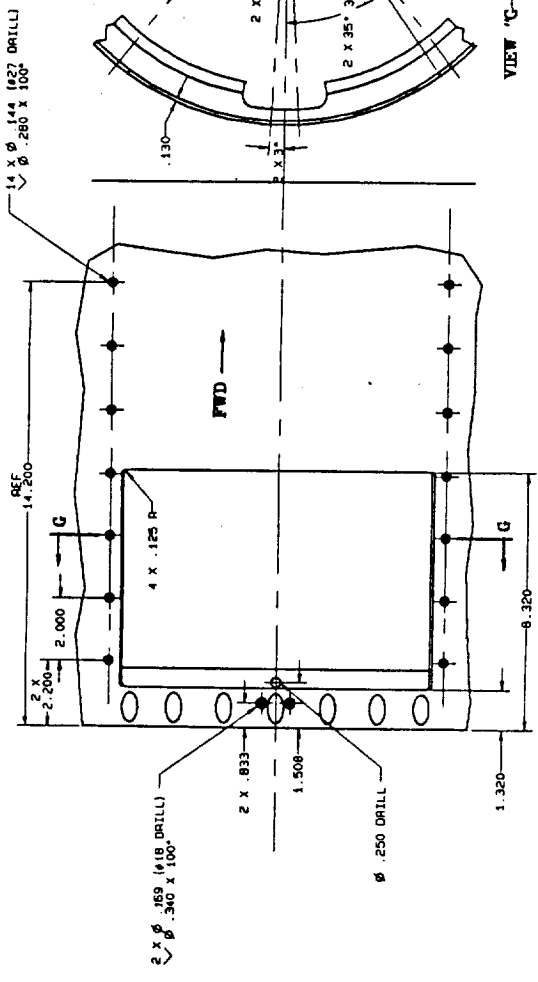
DATE	BY	REVISION
4/92	A	ADDED 61 PIN UM81
4/92	B	ADDED LANYARD SWITCH
4/92	C	ADDED OVERALL DIMENSION 18.050

DATE	BY	REVISION
4/92	A	ADDED 61 PIN UM81
4/92	B	ADDED LANYARD SWITCH
4/92	C	ADDED OVERALL DIMENSION 18.050

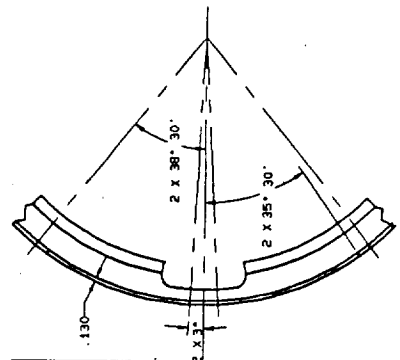
D-27-18698

DATE	BY	REVISION

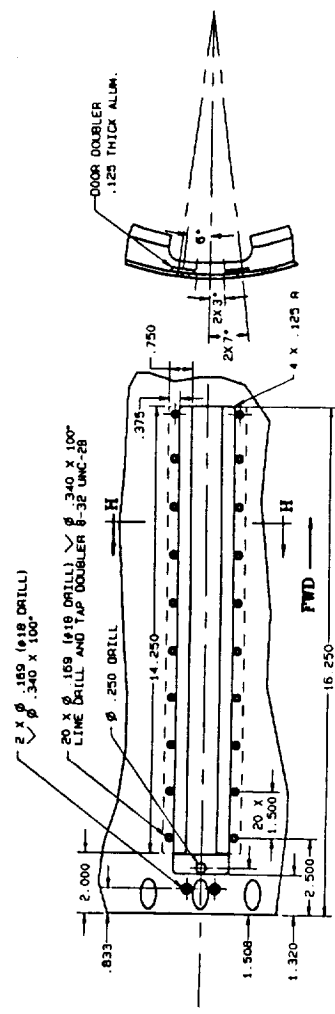
D-27-18988



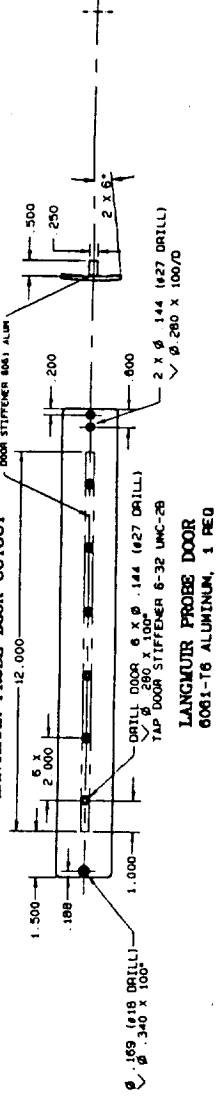
VIEW "D-D"
SOLAR FLUX MONITOR DOOR CUTOUT



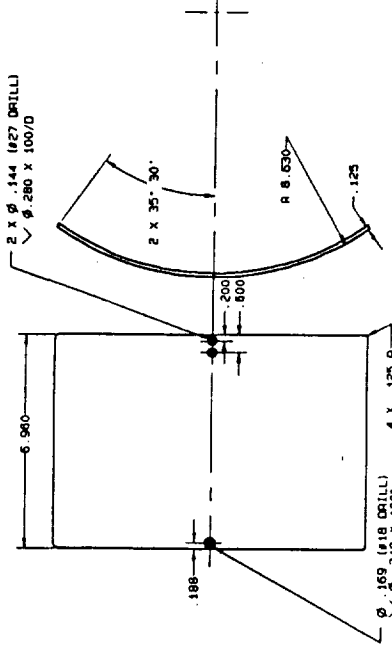
VIEW "C-C"



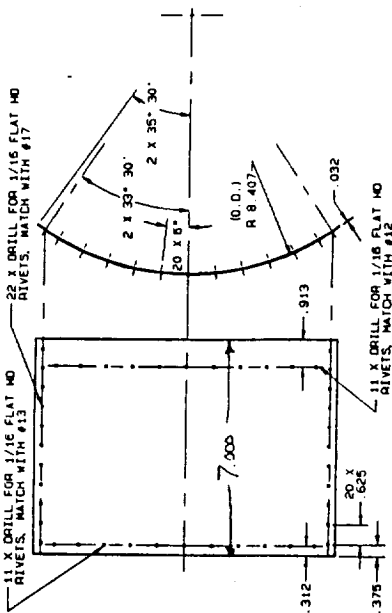
VIEW "D-D"
LANGMUIR PROBE DOOR CUTOUT



VIEW "E-E"
LANGMUIR PROBE DOOR CUTOUT



VIEW "D-D"
SOLAR FLUX MONITOR EJECTABLE DOOR

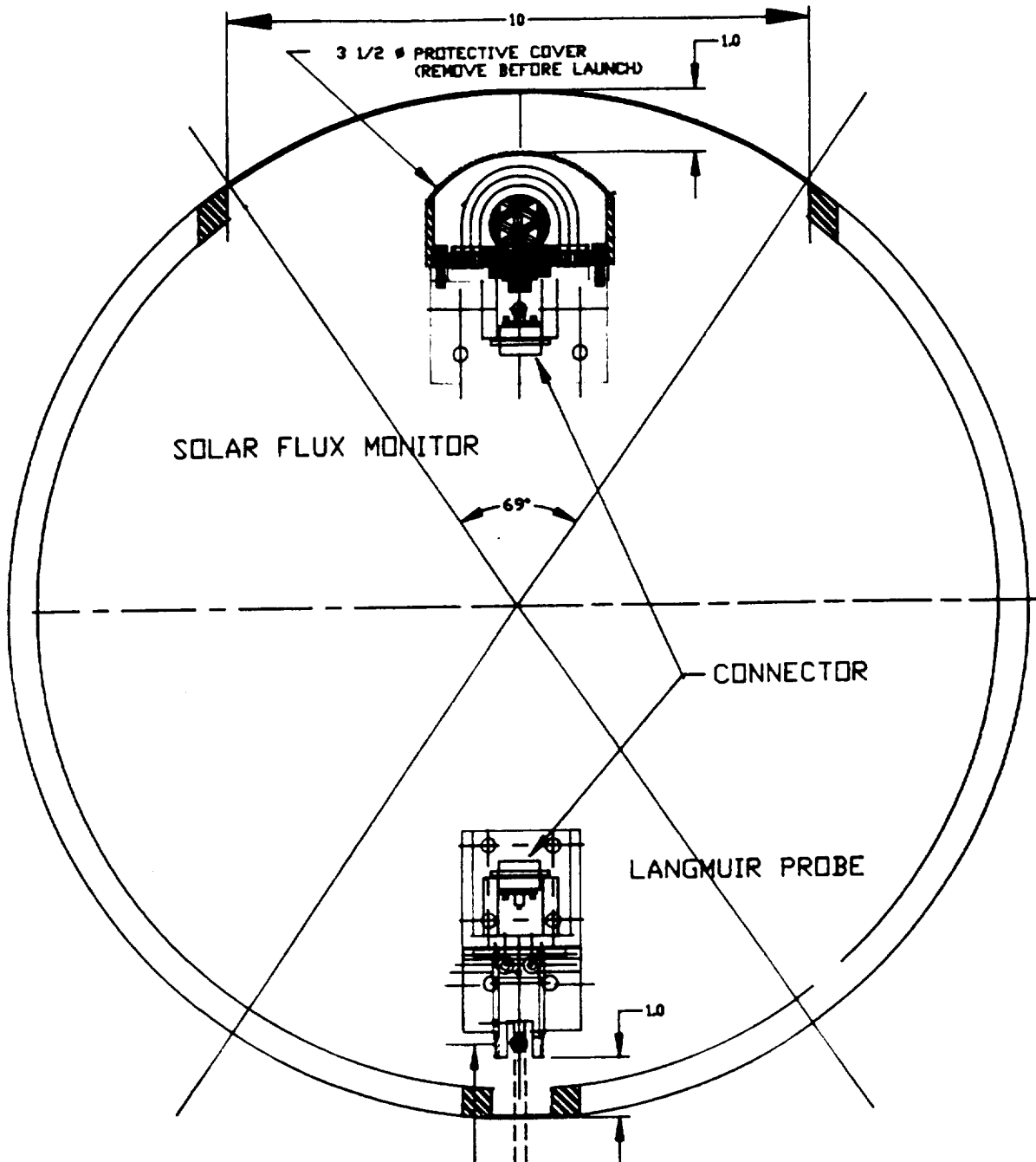


VIEW "D-D"
SOLAR FLUX MONITOR SLIDING DOOR

UNIT OR PROJECT	SCALE	MATERIAL	WELD	FINISH	OR	DATE	BY
27 133	2:1	NOTED					
DESIGNED BY	CHECKED BY	APPROVED BY	DATE	BY			

DATE	BY	REVISION

D-27-18988
REVISION 2 OF 4



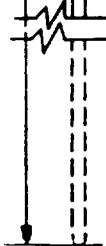
SOLAR FLUX MONITOR & ADVANCED LANGMUIR PROBE

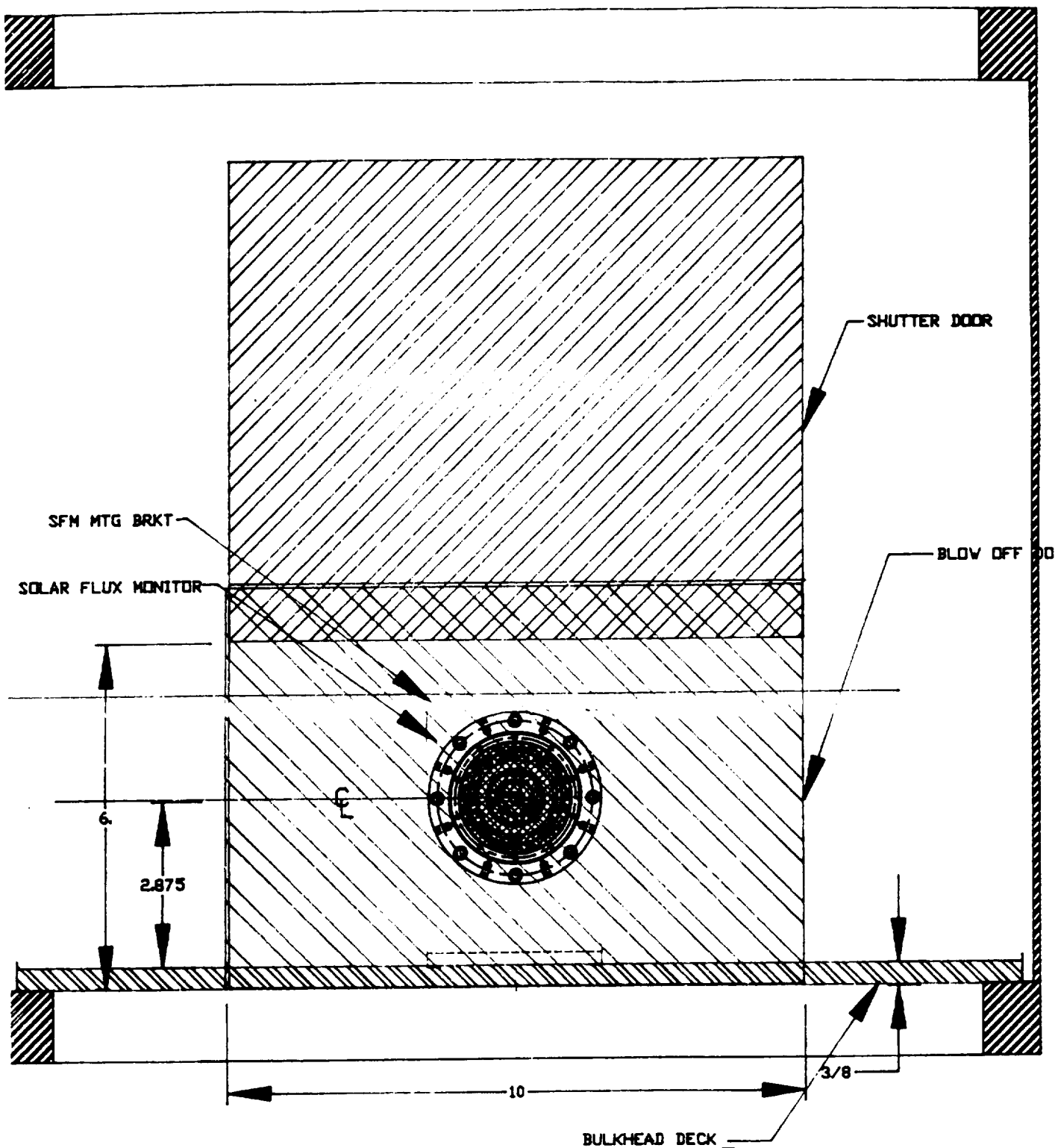
LAYOUT FOR AFT EXPERIMENT SECTION 27.133

4/2/92

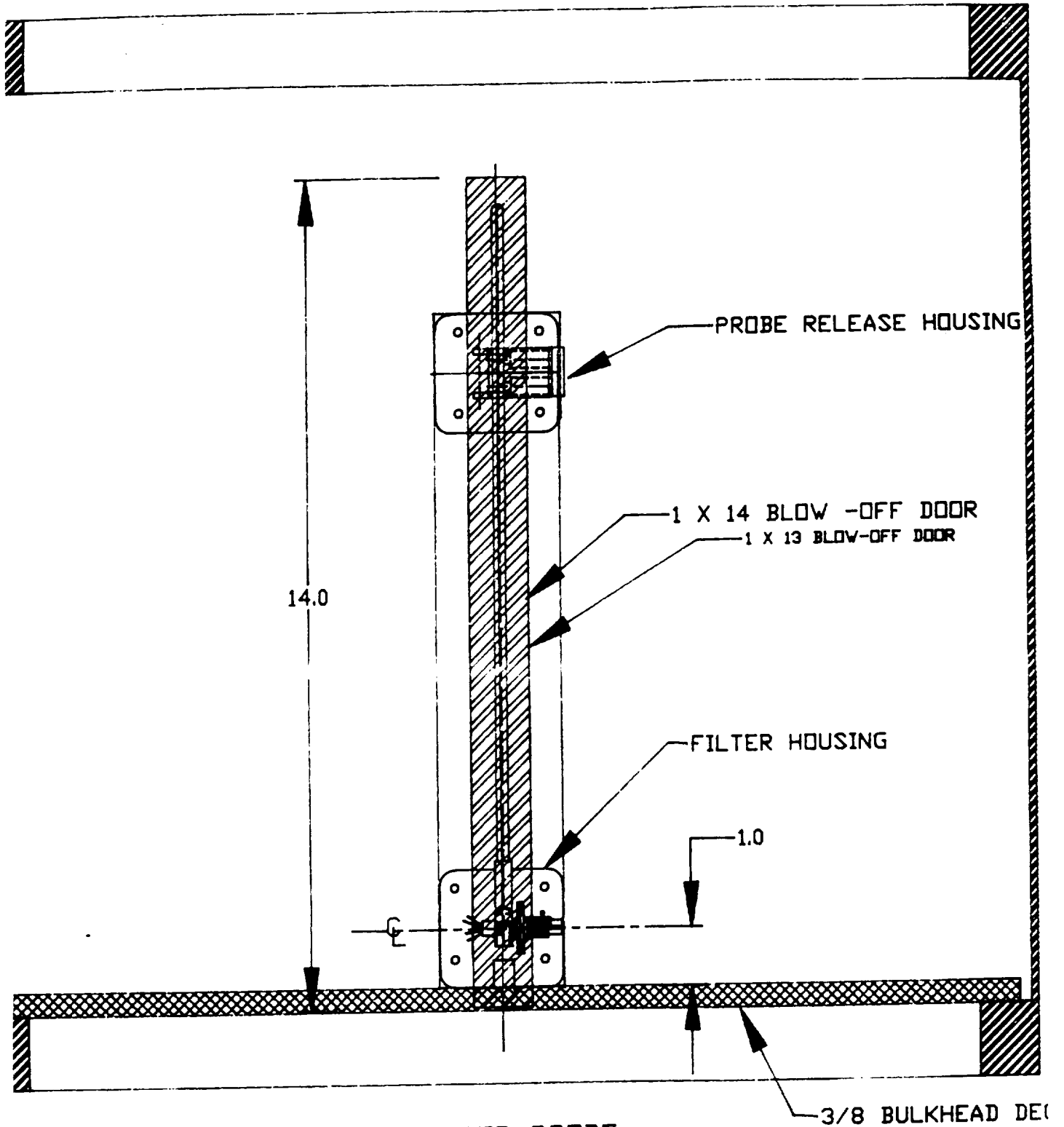
12.0

BL-BRANT





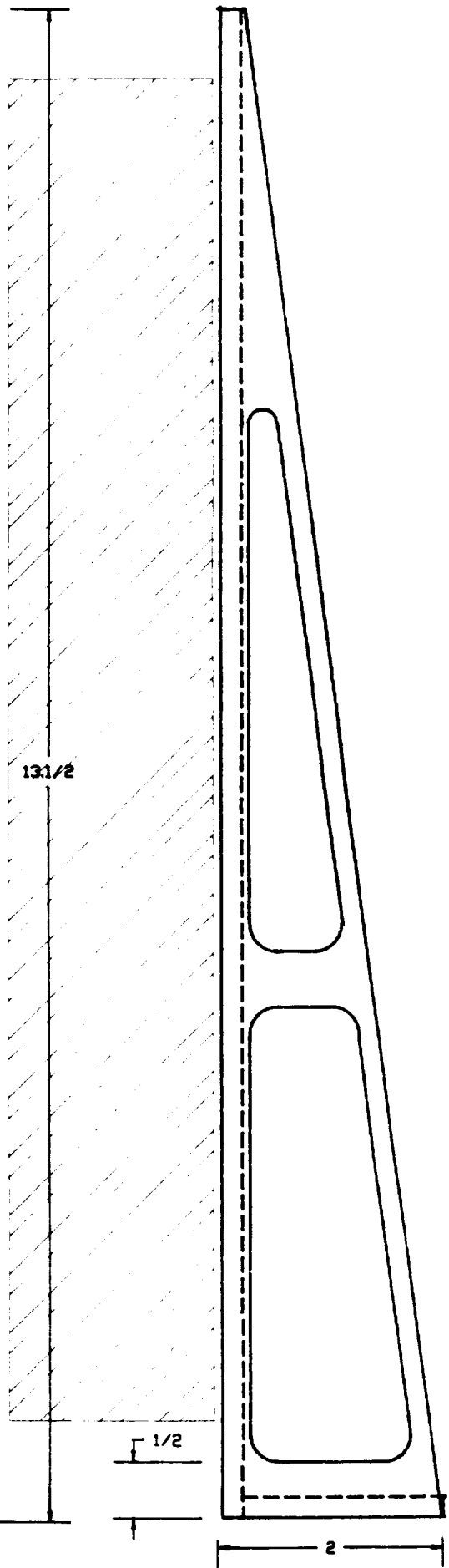
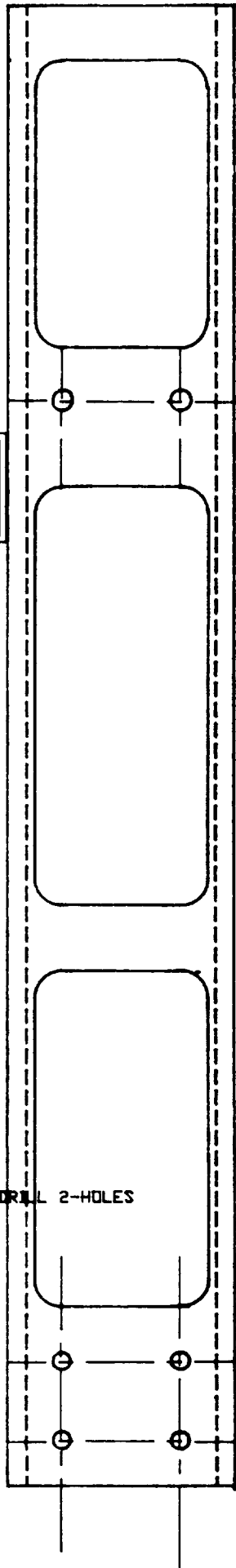
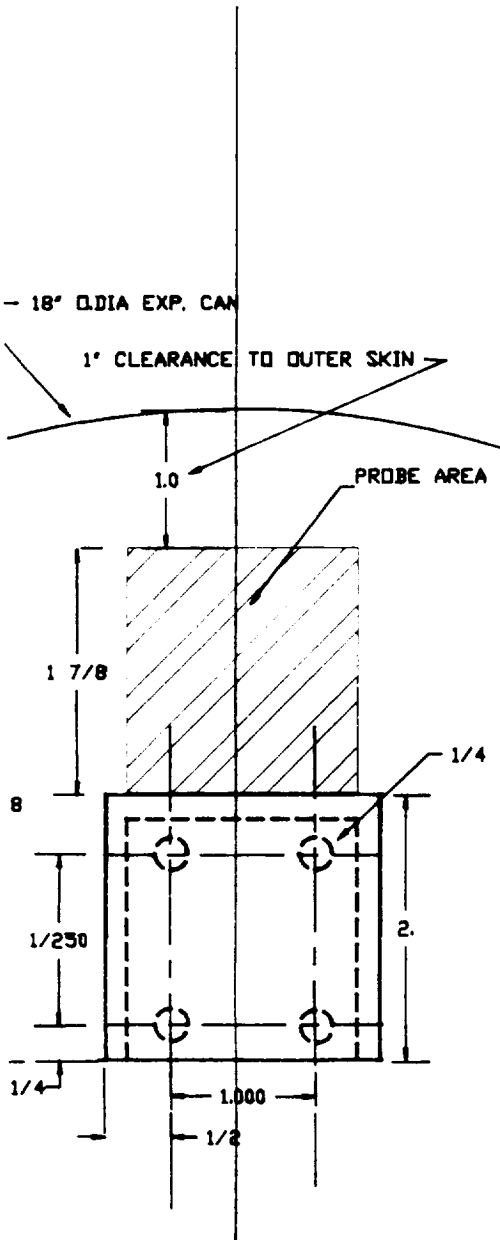
SOLAR FLUX MONITOR
 LAYOUT FOR AFT EXPERIMENT SECTION

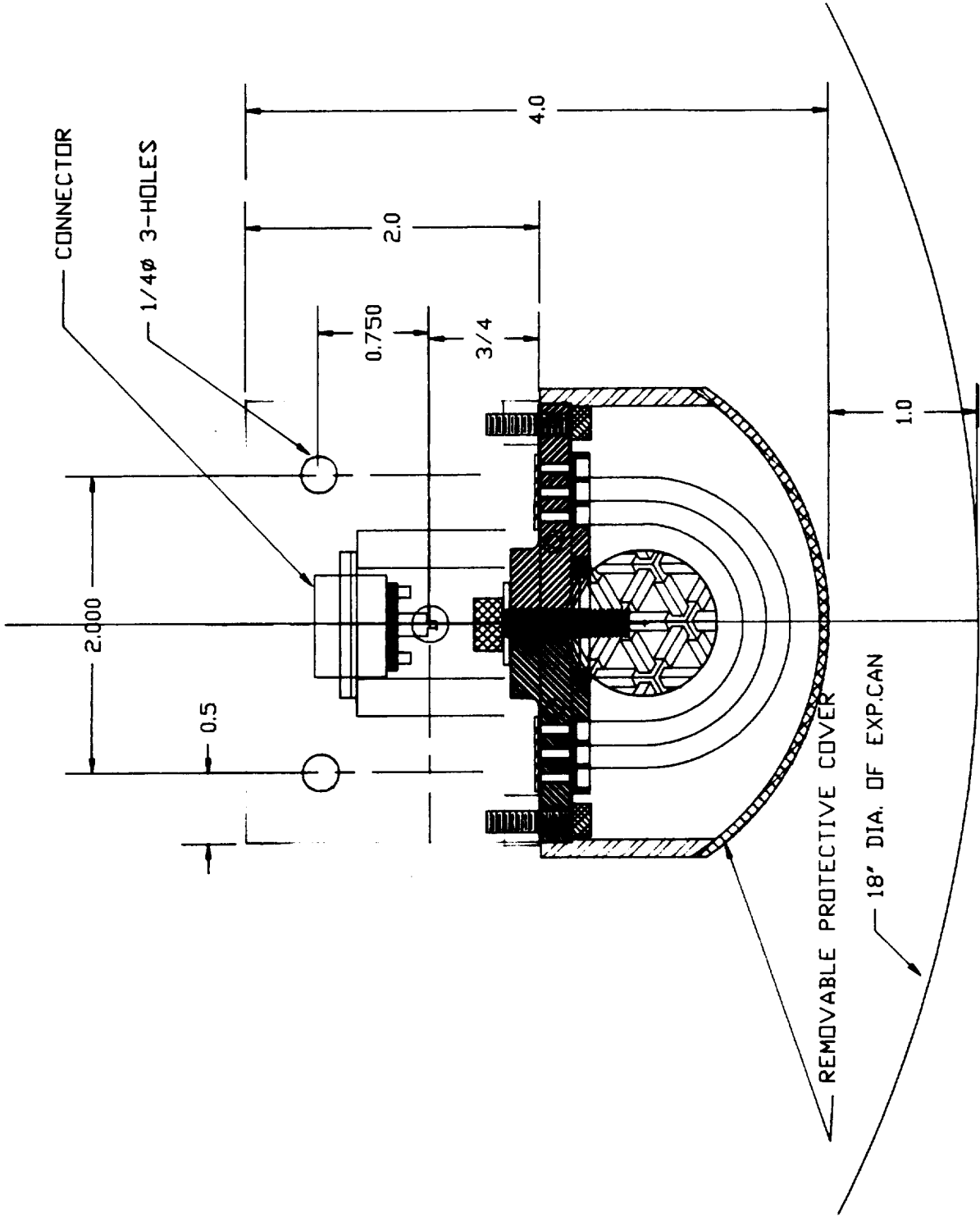


LANGMUIR PROBE

LAYOUT FOR AFT EXPERIMENT SECTION

**PROBE SUPPORT
 INSTALLATION DRAWING**
 GC-1527755





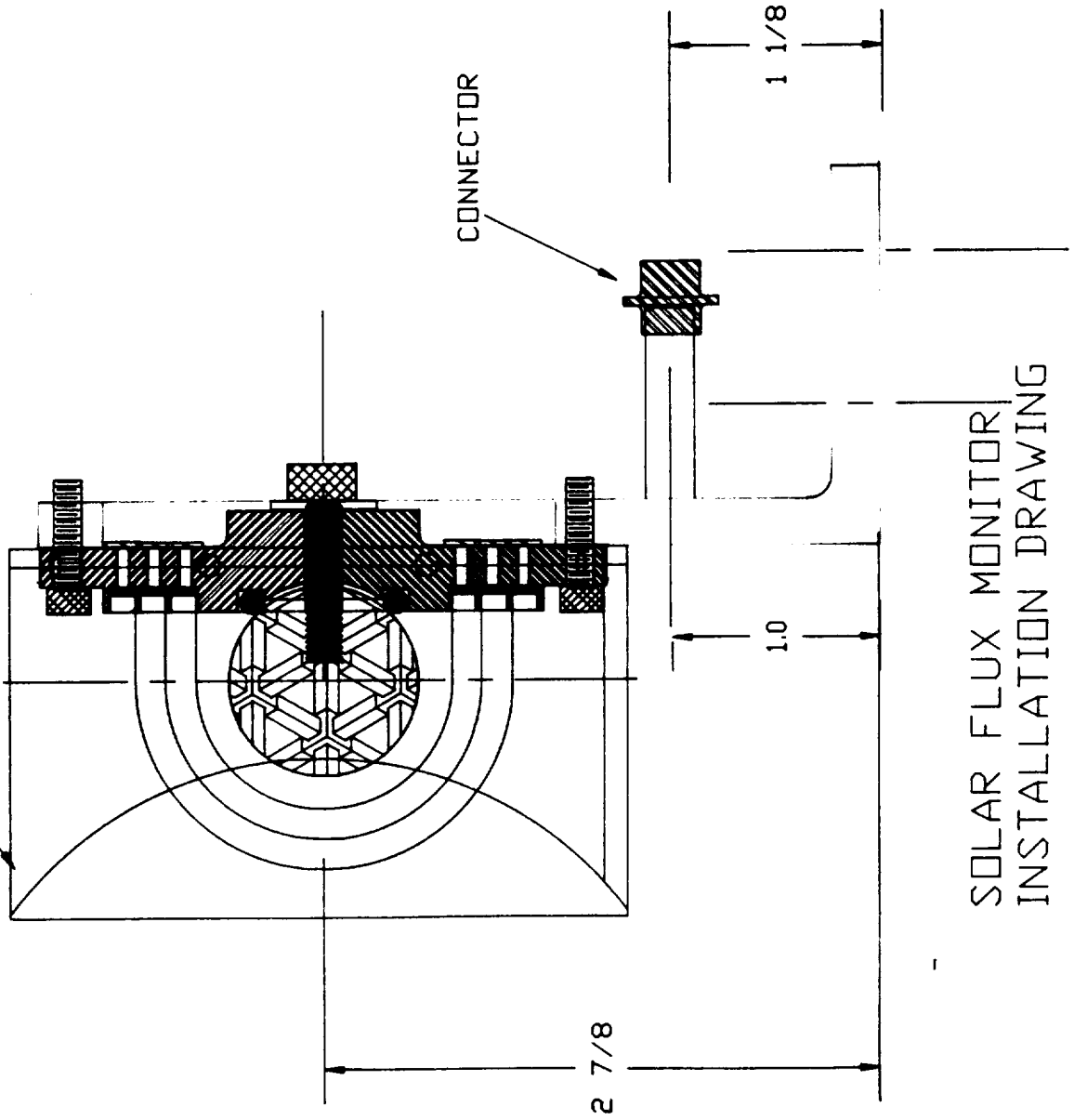
SOLAR FLUX MONITOR
 INSTALLATION DRAWING

TOP VIEW

3/26/92

EUU-7701

REMOVABLE PROTECTIVE COVER

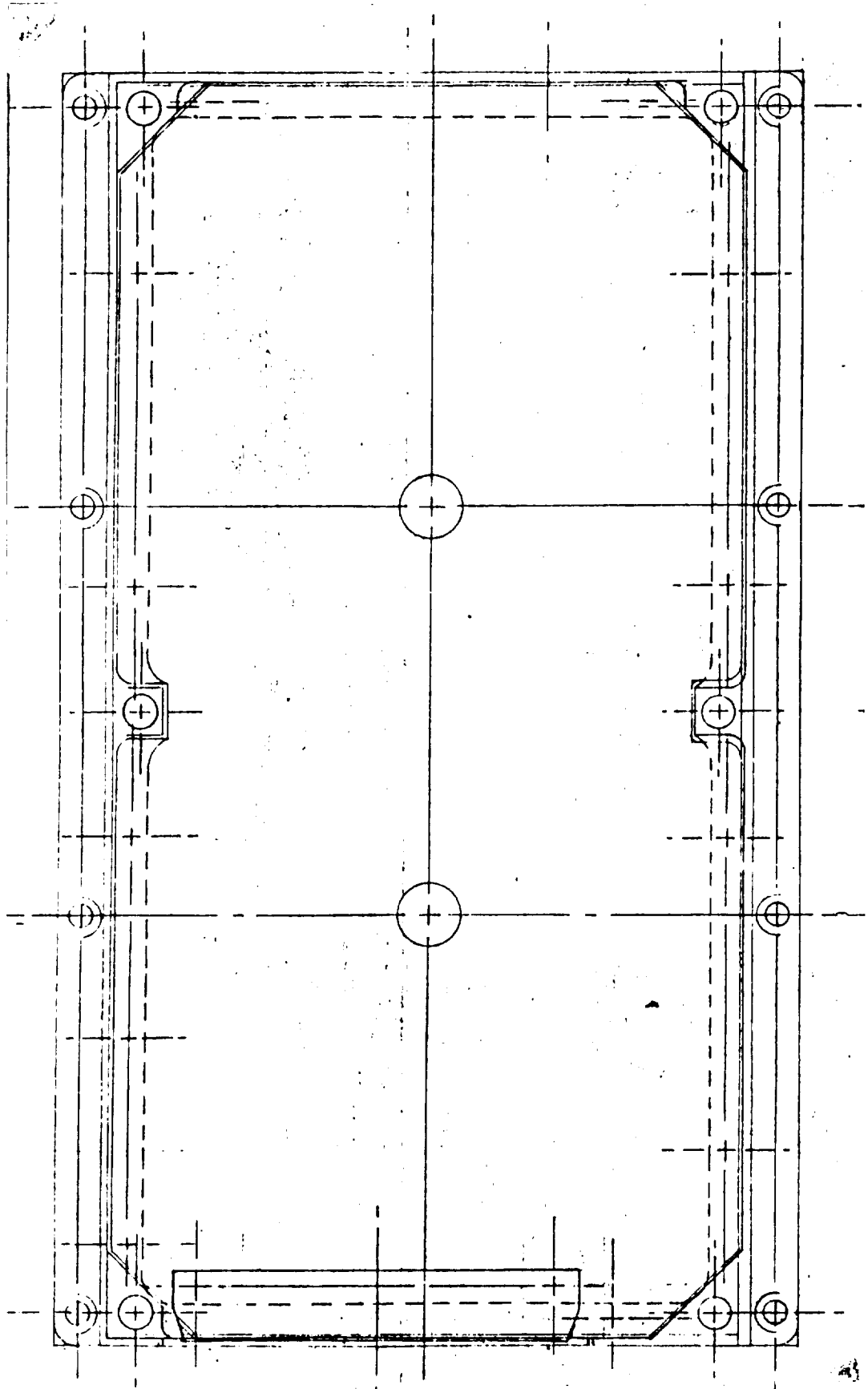


SOLAR FLUX MONITOR
INSTALLATION DRAWING

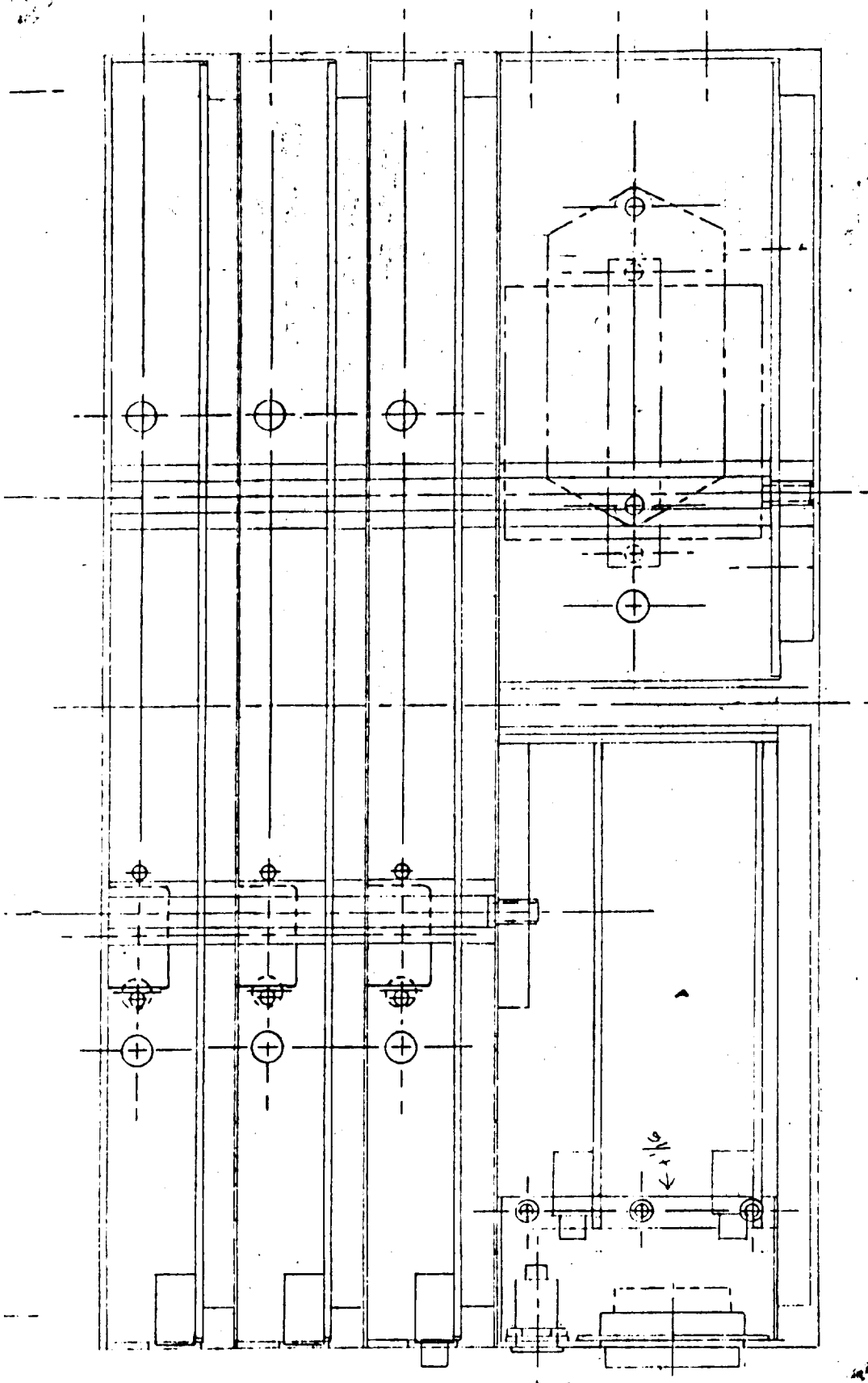
3/26/92

SIDE VIEW

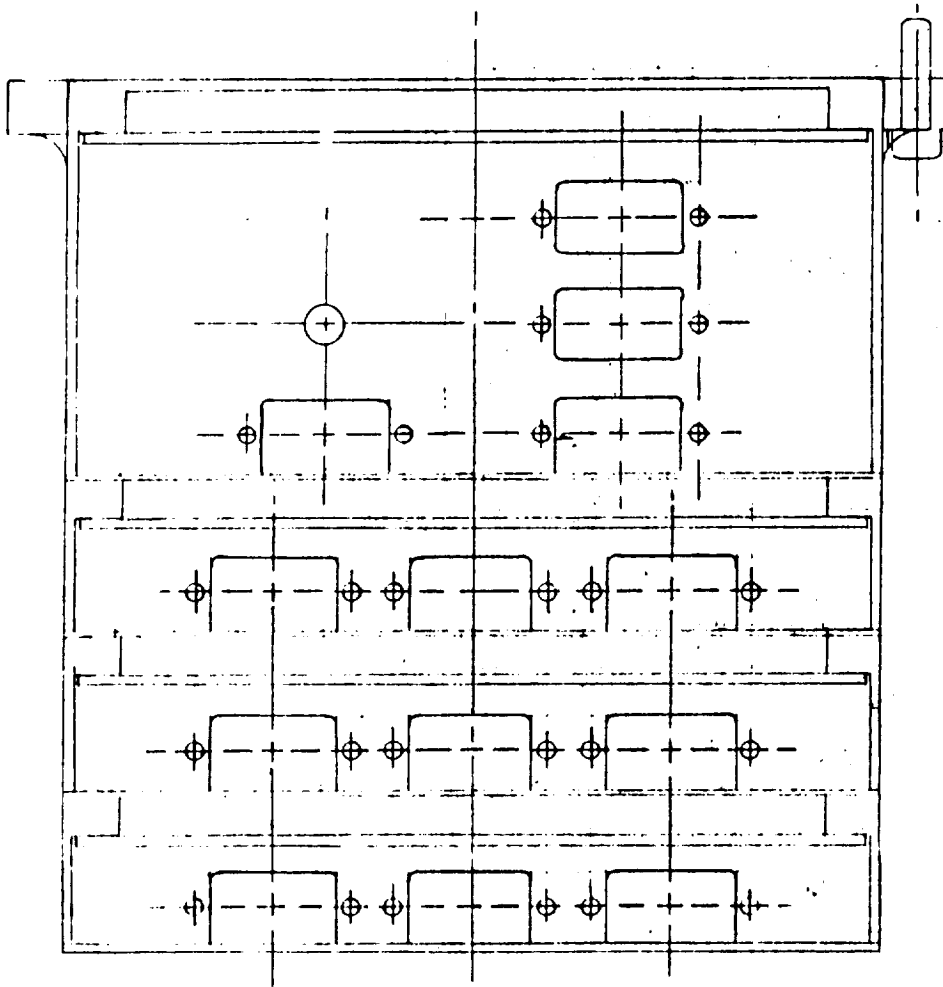
EUUV-7701



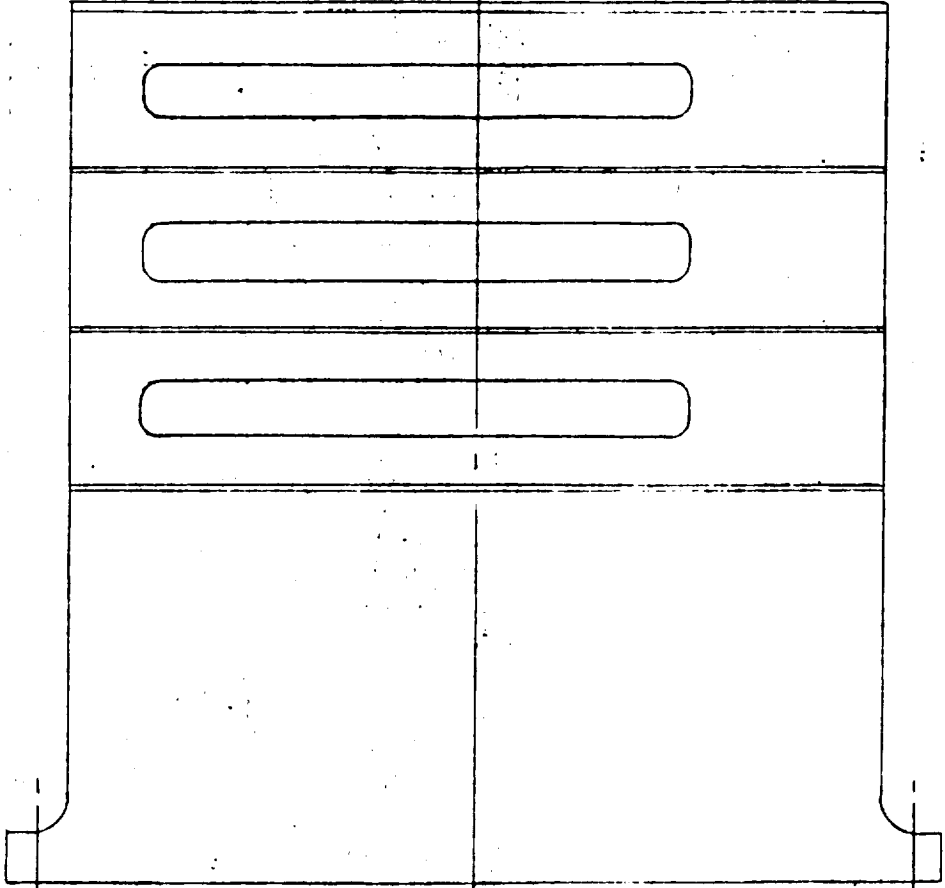
D-048-001 PLAN



D-048-001 FRONT



D-048-001 R.SIDE



D-048-001 L. SIDE

-1
-2
-3

.047 WIDE x .047 DP. SLOT.

.500

$\pm .001$
.250 DIA.

B

.375

.625

#10-32 NF-2 THD.
2 PLACES.

$\pm .002$
.020 x 45° CHAMFER
EACH END.

UNDERCUT TO DEPTH OF THD.
MAX. (.020 $\pm .005$ REF.) EACH END.

DASH NO.	NAME	A DIM.	B DIM.	# REQ'D.
-1	DECK POST	.500	3.950	6
-2	P.C. POST-LONG	.312	5.929	1
-3	P.C. POST-SHORT	.312	3.762	1

REVISION

ZONE	LTR	DESCRIPTION	DFTMIN	DATE	APPROVED

L. H. NO.	R. H. NO.	PART NO.	NAME	SIZE	DESCRIPTION
1	-3		P.C. POST-SHORT	.250 DIA x 3.762	304 ST'N ST.
1	-2		P.C. POST-LONG	.250 DIA x 5.929	304 ST'N ST.
6	-1		DECK POST	.250 DIA x 3.950	304 ST'N ST.

DESIGNED BY B.J.C.
APPROVED BY
DRAWN BY D.D.J.
SCALE FULL SIZE
CHECKED BY
DATE 5-12-92
THREADED DECK ROD
ELECTRONIC HOUSING ASS'Y.
SMI/ALP

SPACE PHYSICS RESEARCH LABORATORY
COLLEGE OF ENGINEERING
THE UNIVERSITY OF MICHIGAN
ANN ARBOR, MICHIGAN

PROJECT NO. B-048-002
UNLESS OTHERWISE SPECIFIED TOLERANCES ARE:
DIM. ENDING .000 \pm .030 ANGULAR DIM. \pm 30 MIN.

REVISION		DESCRIPTION	DATE	APPROVED
ZONE	LTR			

3/8-24 NF-2 TAP THRU

3/8-24 NF-2 THD

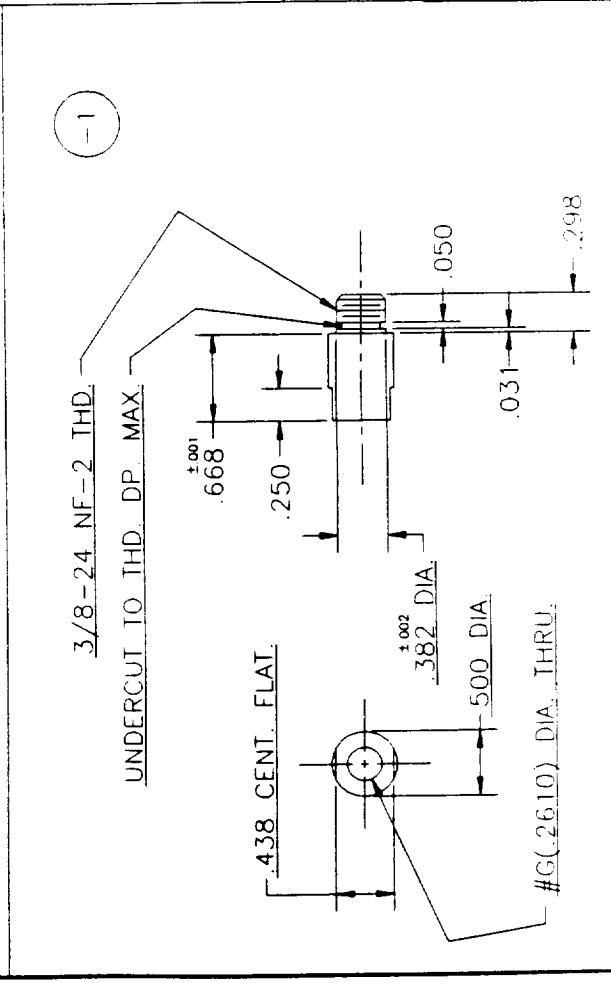
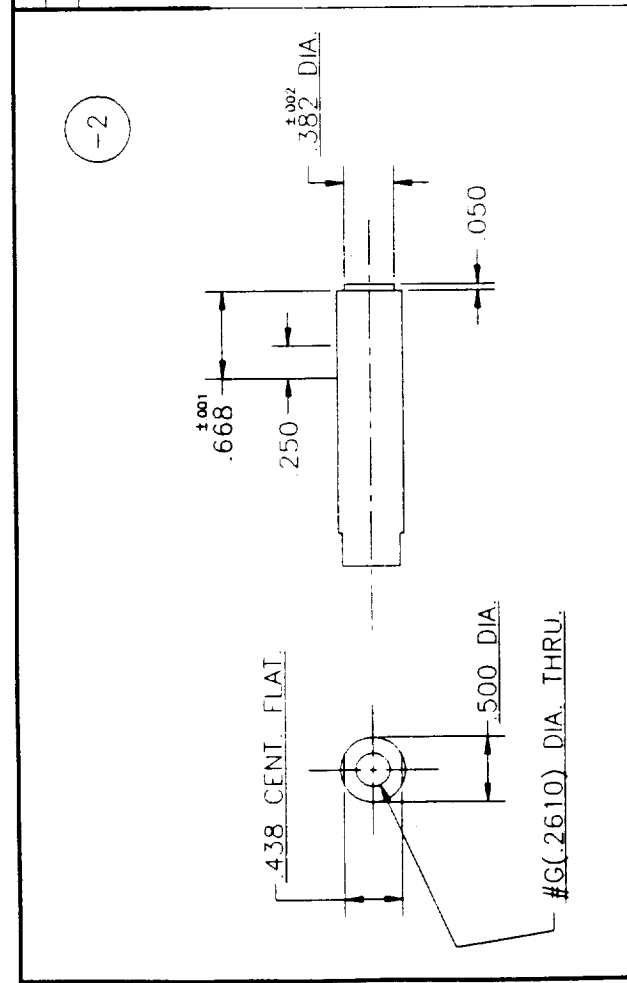
L. H. NO.	R. H. NO.	PART NO.	NAME	DESCRIPTION
6	-3		NUT	500 DIA x .250 6061-T651 AL
1	-2		LONG SPACER	500 DIA x 2.155 6061-T651 AL
6	-1		SHORT SPACER	500 DIA x .966 6061-T651 AL

DESIGNED BY	APPROVED BY
BJC	
DRAWN BY	SCALE
DDJ	FULL SIZE
CHECKED BY	DATE
	5-13-92

SPACE PHYSICS RESEARCH LABORATORY
COLLEGE OF ENGINEERING
THE UNIVERSITY OF MICHIGAN
ANN ARBOR, MICHIGAN

DECK SPACERS-POSTS & NUTS
ELECTRONIC HOUSING ASS'Y
FLIGHT SMF/ALP

DWG. NO. B-048-003

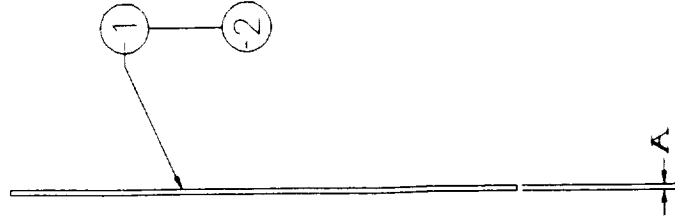
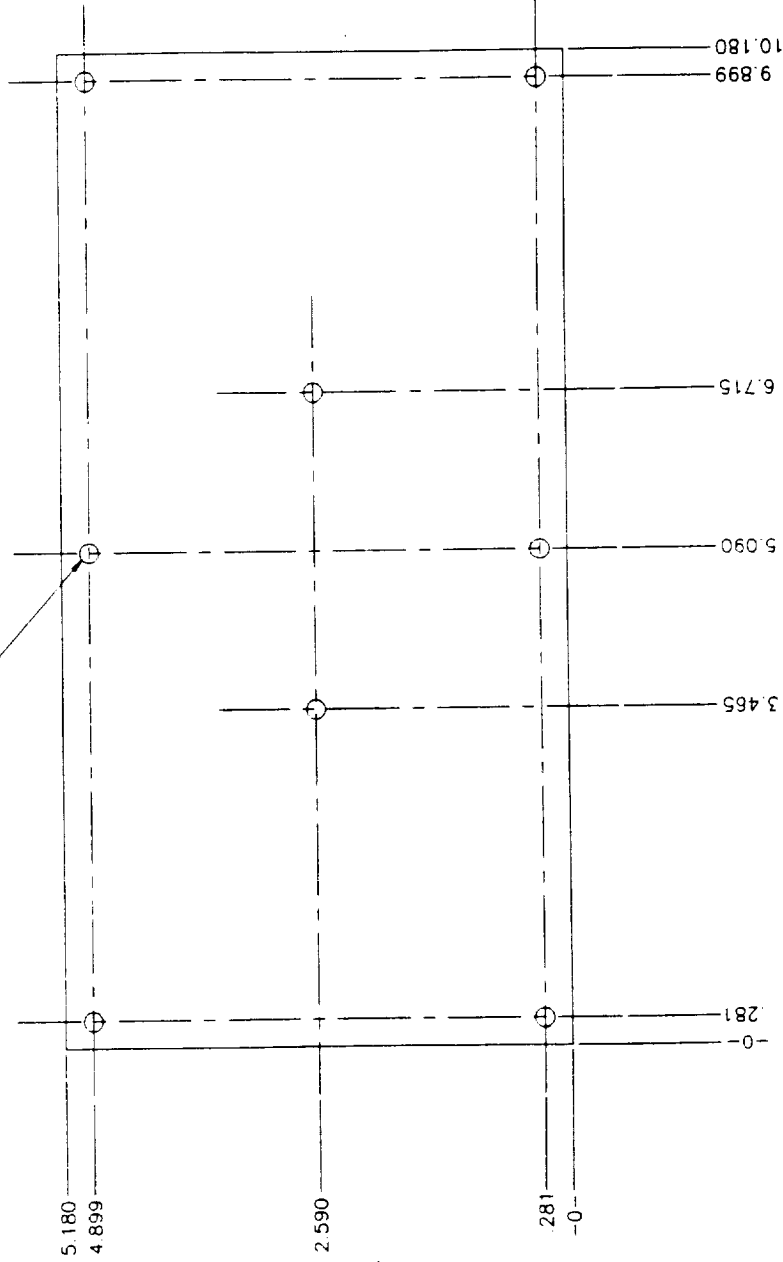


ZONE	LT#	DESCRIPTION	DTM#	DATE	APPROVED

DASH NO.	NAME	A. DIM.	REQ'D
-1	SHIELD	.020	3
-2	TOP PLATE	.050	1

LETTER C (2610) DIA THRU
8 HOLES FOR -1 SHIELDS

#7 (2010) DIA THRU
8 HOLES FOR -2 TOP PLATE

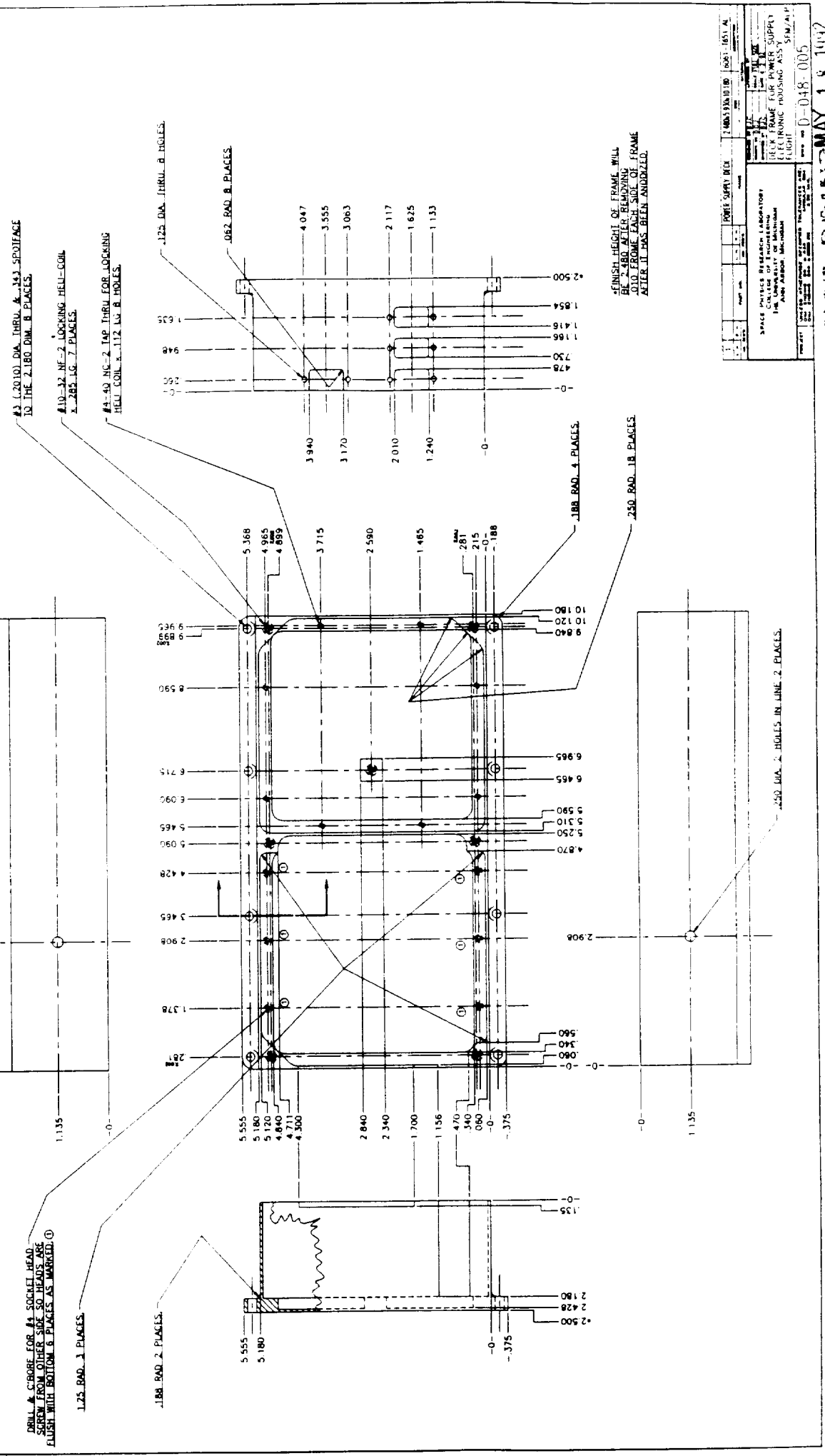


- NOTE:
- ALL HOLE DIM. 002
 - FINISH CHROMATE CONVERSION
 - 1 SHIELDS
 - BLACK ANODIZE -2 TOP PLATE

A		PART NO.		SHIELD/TOP PLATE		A.5.180x10.180 6061-1651 AL	
L. N. NO.	R. N. NO.	L. N. NO.	R. N. NO.	NAME	DESCRIPTION	DATE	BY
SPACE PHYSICS RESEARCH LABORATORY COLLEGE OF ENGINEERING THE UNIVERSITY OF MICHIGAN ANN ARBOR, MICHIGAN				DESIGNED BY D.D.J.	DATE JULY 57		
PROJECT UNLESS OTHERWISE SPECIFIED TOLERANCES DIM. ENGRG. 000 005 ±.30 MIN.				DECK SHIELD & TOP PLATE ELECTRONIC HOUSING ASSY FLIGHT		DWO. NO. C-048-004	

MAY 18 1957

REV	DATE	BY	CHKD	APP'D

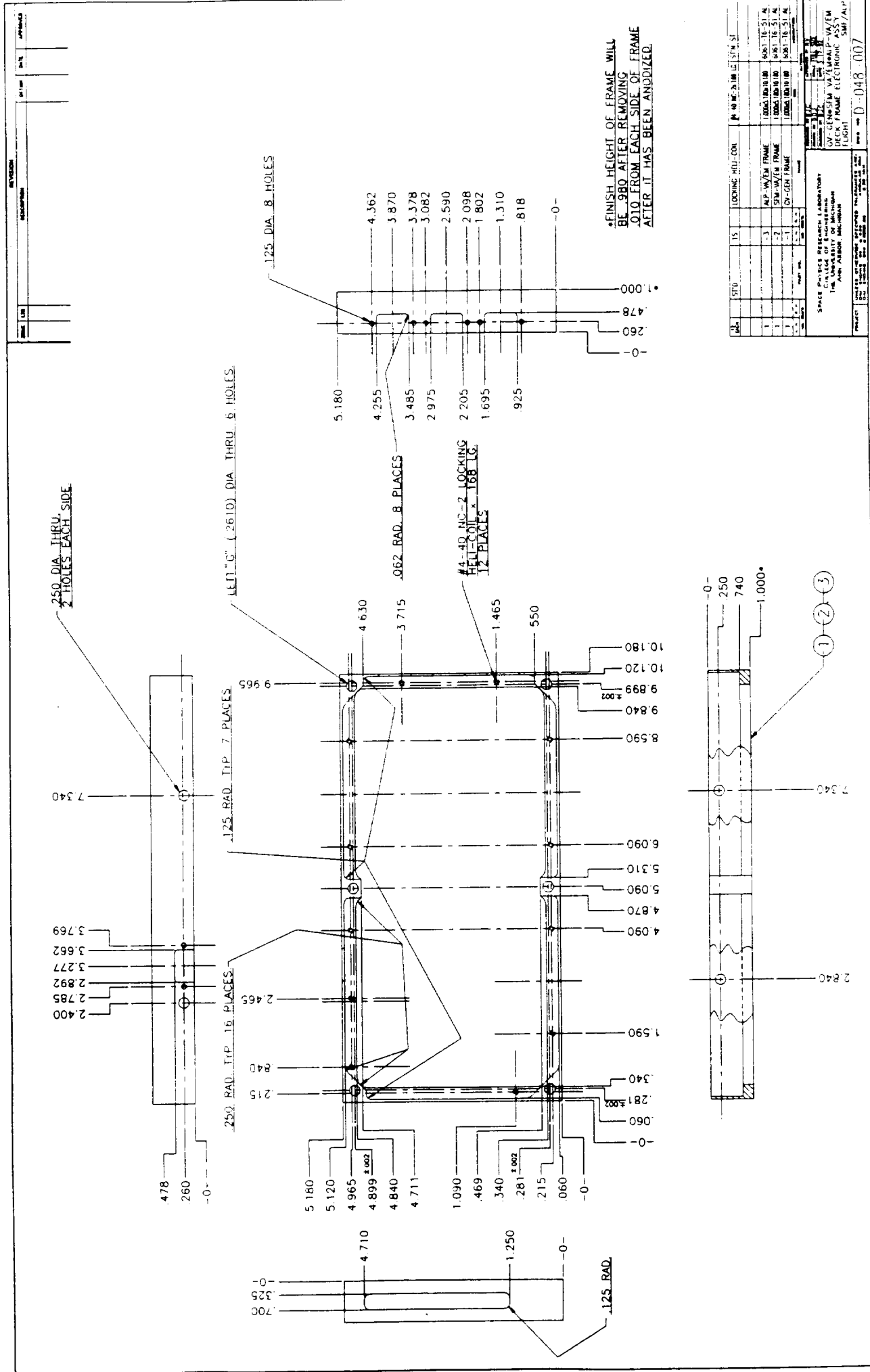


FINISH HEIGHT OF FRAME WILL BE .480 AFTER BLENDING AND FROM FACE SURFACES AFTER IT HAS BEEN ANODIZED.

REV	DATE	BY	CHKD	APP'D

SPACE PHYSICS RESEARCH LABORATORY
 FOR UNIVERSITY OF MICHIGAN
 ANN ARBOR, MICHIGAN

MAY 18 1992



REV	DATE	BY	CHK	DESCRIPTION
1				REVISED
2				REVISED
3				REVISED
4				REVISED
5				REVISED
6				REVISED
7				REVISED
8				REVISED
9				REVISED
10				REVISED
11				REVISED
12				REVISED
13				REVISED
14				REVISED
15				REVISED

REV	DATE	BY	CHK	DESCRIPTION
1				REVISED
2				REVISED
3				REVISED
4				REVISED
5				REVISED
6				REVISED
7				REVISED
8				REVISED
9				REVISED
10				REVISED
11				REVISED
12				REVISED
13				REVISED
14				REVISED
15				REVISED

REV	DATE	BY	CHK	DESCRIPTION
1				REVISED
2				REVISED
3				REVISED
4				REVISED
5				REVISED
6				REVISED
7				REVISED
8				REVISED
9				REVISED
10				REVISED
11				REVISED
12				REVISED
13				REVISED
14				REVISED
15				REVISED

REV	DATE	BY	CHK	DESCRIPTION
1				REVISED
2				REVISED
3				REVISED
4				REVISED
5				REVISED
6				REVISED
7				REVISED
8				REVISED
9				REVISED
10				REVISED
11				REVISED
12				REVISED
13				REVISED
14				REVISED
15				REVISED

REV	DATE	BY	CHK	DESCRIPTION
1				REVISED
2				REVISED
3				REVISED
4				REVISED
5				REVISED
6				REVISED
7				REVISED
8				REVISED
9				REVISED
10				REVISED
11				REVISED
12				REVISED
13				REVISED
14				REVISED
15				REVISED

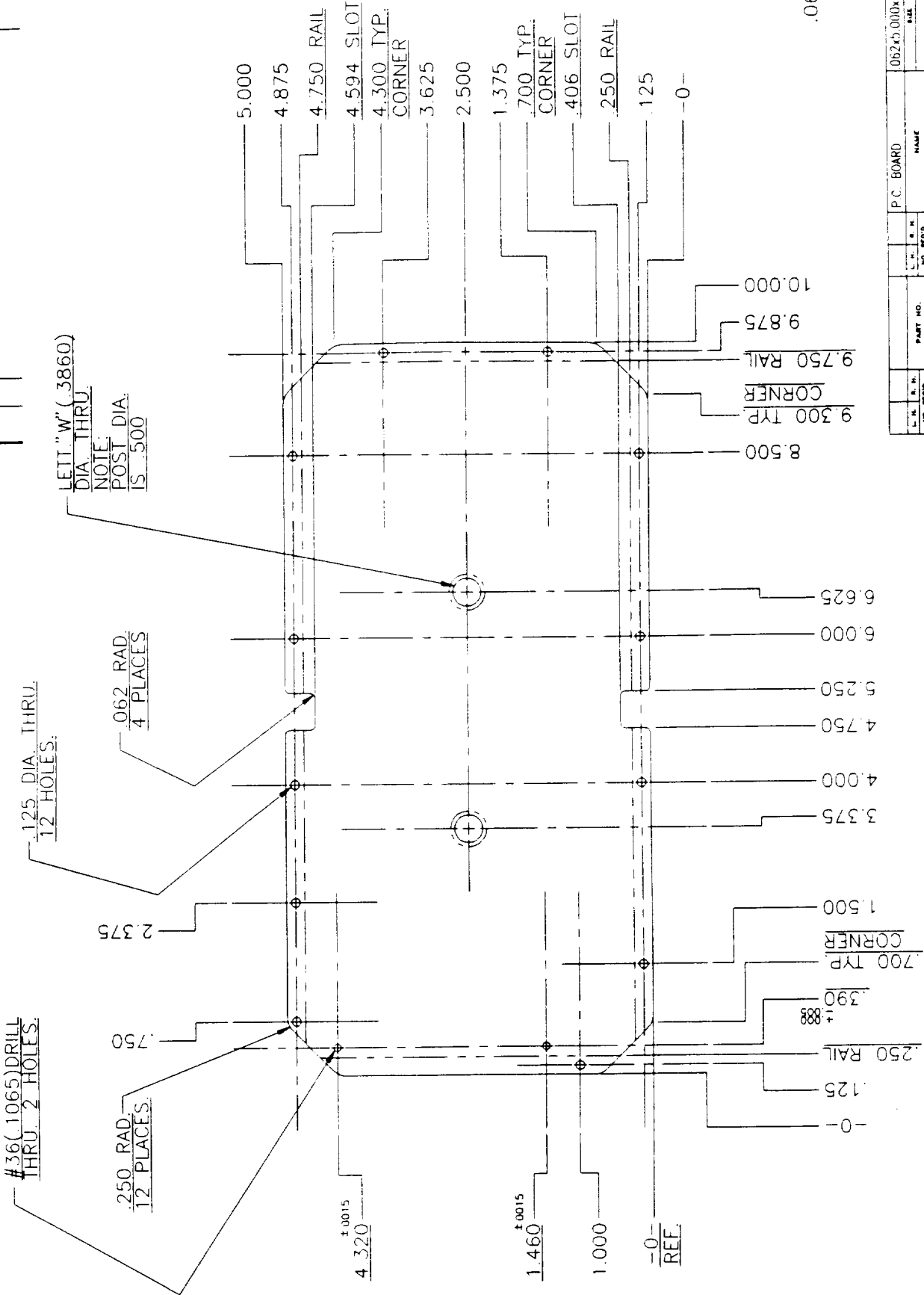
REV	DATE	BY	CHK	DESCRIPTION
1				REVISED
2				REVISED
3				REVISED
4				REVISED
5				REVISED
6				REVISED
7				REVISED
8				REVISED
9				REVISED
10				REVISED
11				REVISED
12				REVISED
13				REVISED
14				REVISED
15				REVISED

REV	DATE	BY	CHK	DESCRIPTION
1				REVISED
2				REVISED
3				REVISED
4				REVISED
5				REVISED
6				REVISED
7				REVISED
8				REVISED
9				REVISED
10				REVISED
11				REVISED
12				REVISED
13				REVISED
14				REVISED
15				REVISED

REV	DATE	BY	CHK	DESCRIPTION
1				REVISED
2				REVISED
3				REVISED
4				REVISED
5				REVISED
6				REVISED
7				REVISED
8				REVISED
9				REVISED
10				REVISED
11				REVISED
12				REVISED
13				REVISED
14				REVISED
15				REVISED

18

ZONE	DESCRIPTION	DTM	DATE	APPROVED



NOTE:
1. ALL P.C. LAYOUT WORK TO BE .050 FROM RAIL S. BOARD EDGE (WHERE THERE IS NO RAIL) & POSTS.

DESIGNED BY B.T.C.	SCALE FULL SIZE	DATE 7-5-92
DRAWN BY B.T.C.	SCALE FULL SIZE	DATE 7-5-92
P.C. BOARD MECH LAYOUT FOR GV-GEN-SFM-VA/EM & ALP-VA/EM SMF/ALP		

PROJECT	UNIVERSITY RESEARCH LABORATORY
COLLEGE OF ENGINEERING	THE UNIVERSITY OF MICHIGAN
ANN ARBOR, MICHIGAN	

UNIT	INCHES	SCALE	1:1
UNIT	MILLIMETERS	SCALE	1:1

NO.	REV.	DESCRIPTION

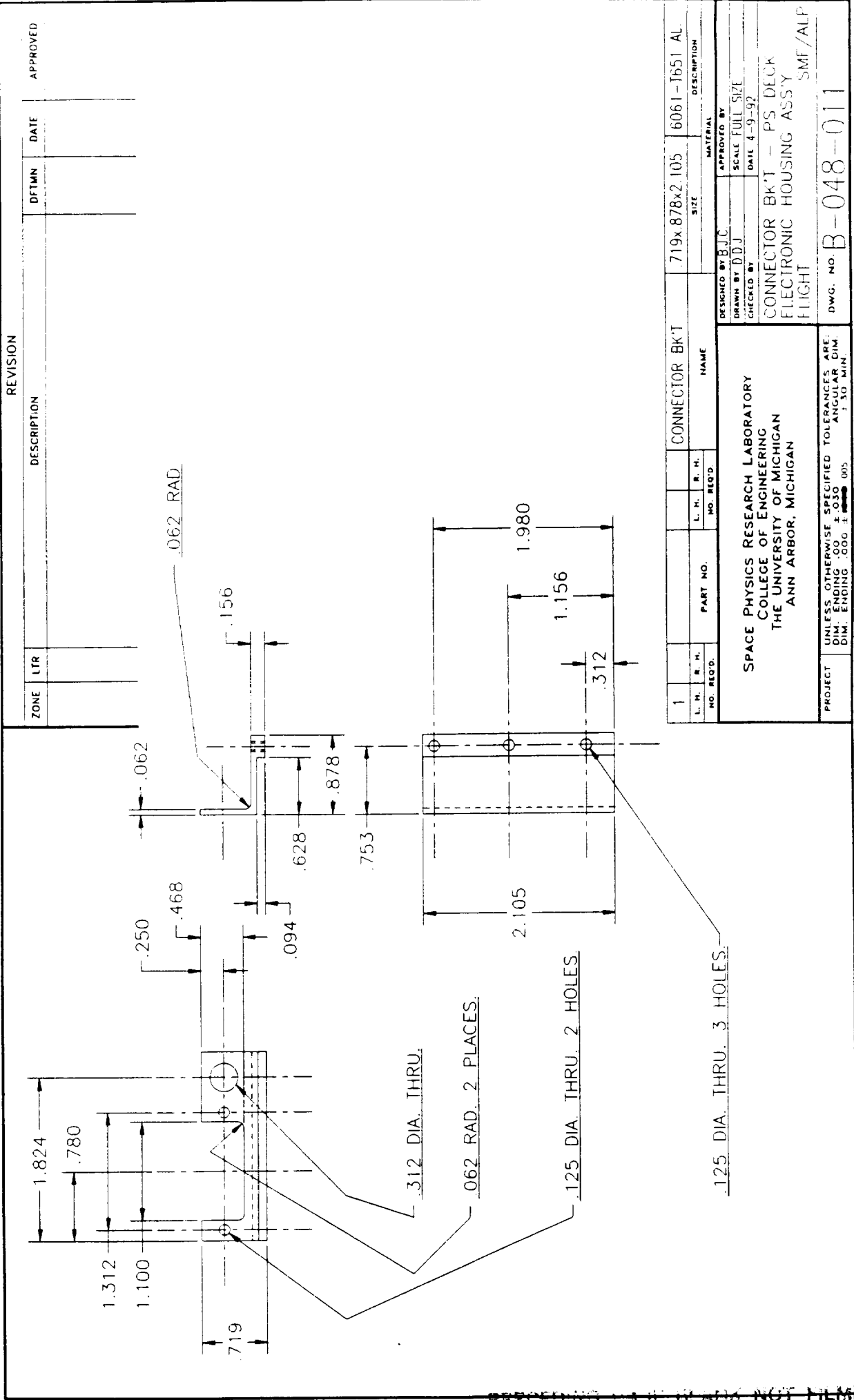
DATE	BY	DESCRIPTION

P.C. BOARD NAME

062x1000x10.000

DWG NO C-048-003

MAY 18 1992



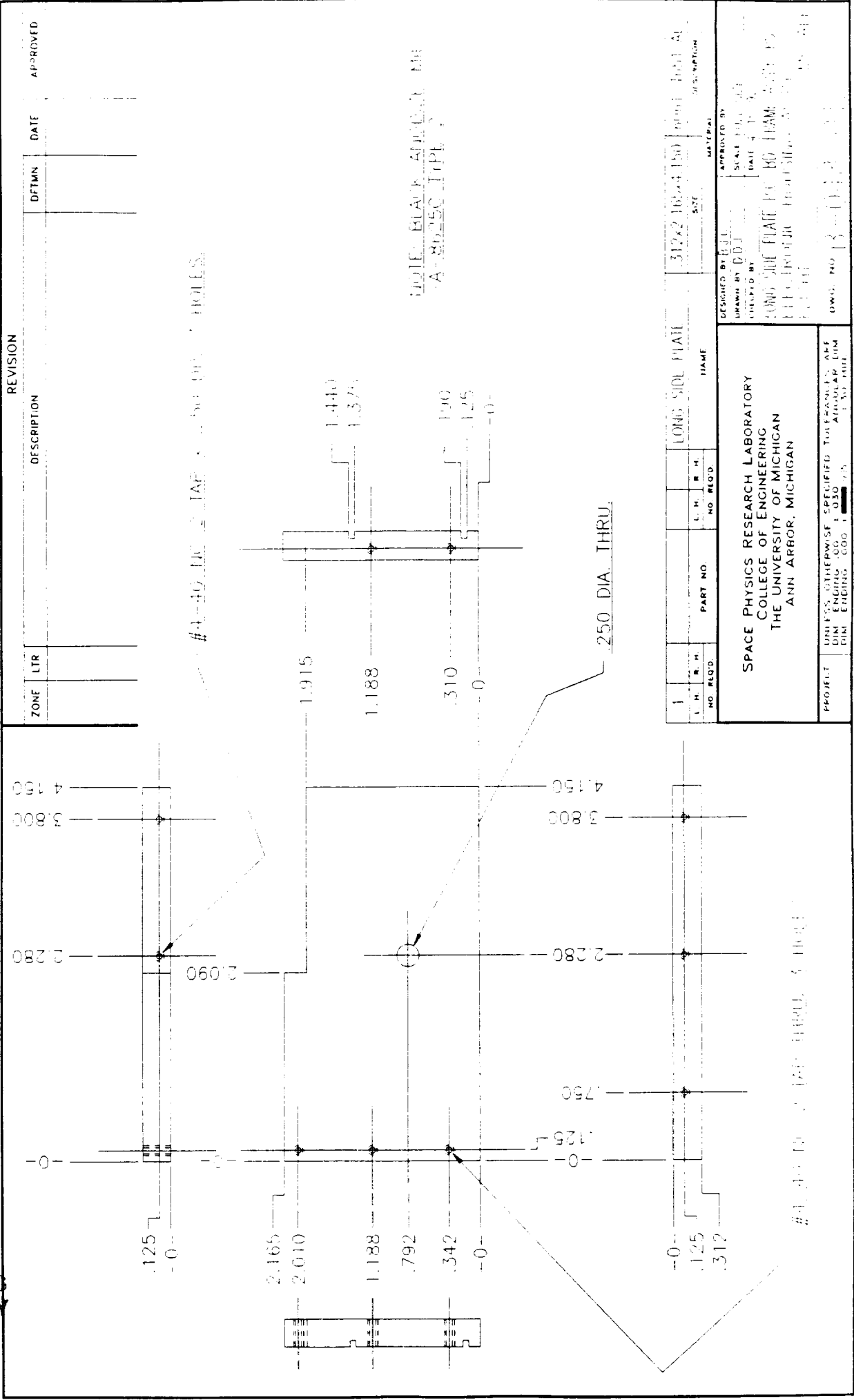
REVISION		DESCRIPTION	DFTMN	DATE	APPROVED
ZONE	LTR				

1	L. H. R. H. NO. REQ'D.	PART NO.	CONNECTOR BK'T	NAME	719x 878x2 105	MATERIAL	6061-T651 AL
	L. H. R. H. NO. REQ'D.					DESIGNED BY BJC	
						DRAWN BY D.D.J	SCALE FULL SIZE
						CHECKED BY	DATE 4-9-92
SPACE PHYSICS RESEARCH LABORATORY COLLEGE OF ENGINEERING THE UNIVERSITY OF MICHIGAN ANN ARBOR, MICHIGAN				CONNECTOR BK'T - PS DECK ELECTRONIC HOUSING ASSY FLIGHT SMF/ALP			
PROJECT	UNLESS OTHERWISE SPECIFIED TOLERANCES ARE: DIM. ENDING .00 ± .030 ANGULAR DIM ± .30 MIN. DIM. ENDING .000 ± .005		DWG. NO. B-048-011				

PRECEDING PAGE BLANK NOT FILMED

MAY 18 1992

ORIGINAL DRAWING IS OF POOR QUALITY



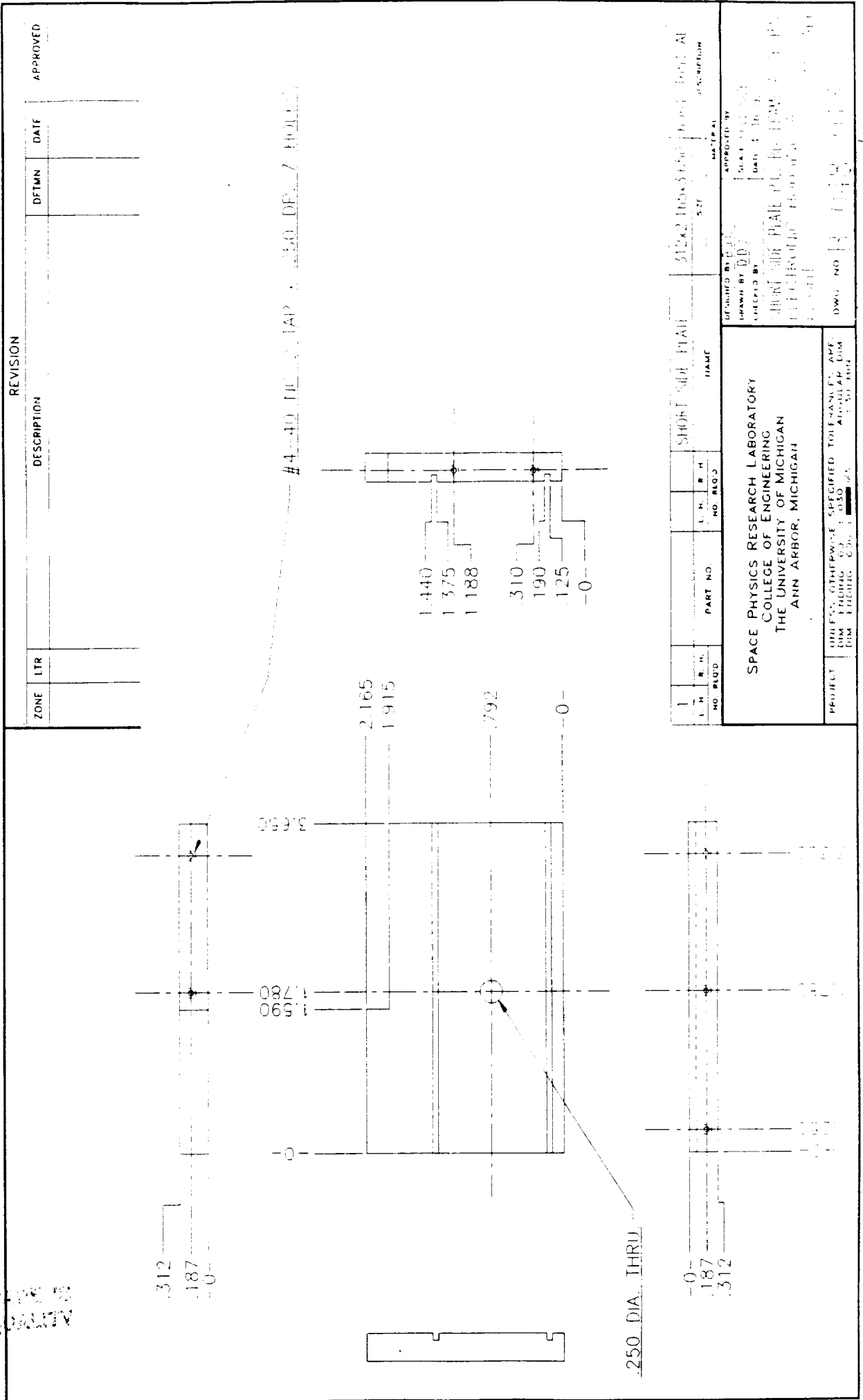
SPACE PHYSICS RESEARCH LABORATORY
 COLLEGE OF ENGINEERING
 THE UNIVERSITY OF MICHIGAN
 ANN ARBOR, MICHIGAN

NOTE: BLACK ANGLE OF
 A-80250 TYPE

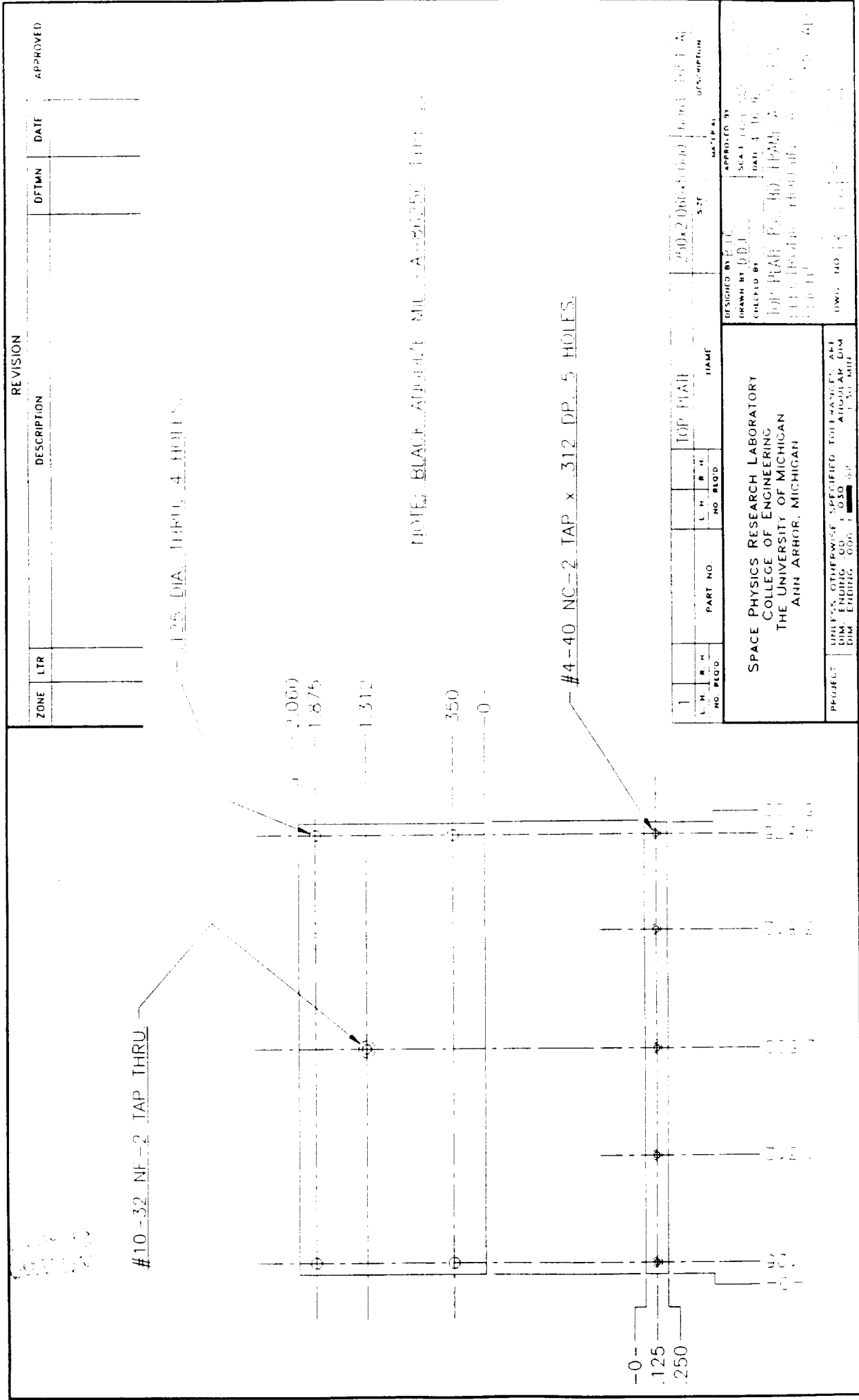
#4-40 DIA. PLATE WITH 1/8" HOLES

#4-40 DIA. PLATE WITH 1/8" HOLES

ORIGINAL DRAWING
OF POOR QUALITY



OF FLOOR



REVISION		DATE	APPROVED
ZONE	DESCRIPTION		
LTR			

#10-32 NF-2 TAP THRU

.125 DIA THRU 4 HOLES

2.060

1.875

1.312

350

0

#4-40 NC-2 TAP x .312 DP 5 HOLES

NOTE: BLACK ANGLE MIL A-20250 FOR

L. H. R. H.		PART NO.		ITEM		DESCRIPTION	
NO.	FEED	L.	R.	NO.	FEED	SCALE	DESCRIPTION
1						250x2 000x5 000	TOP PLATE

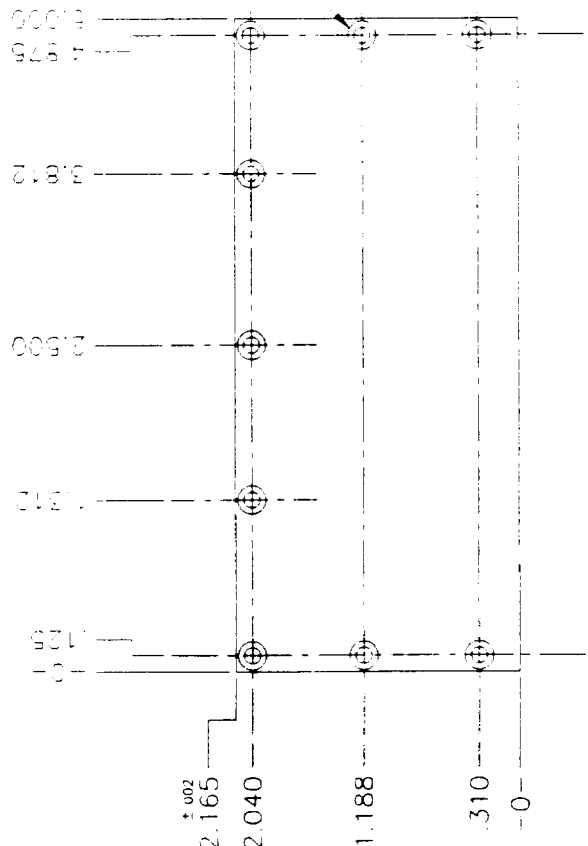
DESIGNED BY	SCALE	DATE	APPROVED BY
DRAWN BY	DATE		
CHECKED BY			

TOP PLATE FOR THE SPACE PHYSICS RESEARCH LABORATORY

SPACE PHYSICS RESEARCH LABORATORY
 COLLEGE OF ENGINEERING
 THE UNIVERSITY OF MICHIGAN
 ANN ARBOR, MICHIGAN

PROJECT	UNITS - OTHER THAN AS SPECIFIED TO BE IN METERS	APP
DIM	ENDING .000 ± .030	ANGULAR DIM
DIM	ENDING .000 ± .050	ENDING DIM

ORDER A GOOD JOB
OF POOR QUALITY



1.25 DIA. THRU & 80% DEEP TO 1/2" MAX DIA. 9 PLACES

NOTE: BLACK ANODIZE MIL. A-85, TYPE 2

REVISION			APPROVED
ZONE	DESCRIPTION	DATE	DATE

DESIGNED BY BJC				APPROVED BY			
DRAWN BY DDJ				SCALE FULL SIZE			
CHECKED BY				DATE 4-16-97			
PART NO.				NAME			
1				BACK PLATE			
L. H. R. H. NO. REQ'D				SIZE			
				062x2.165x5.000			
				MATERIAL			
				6061-T651 AL			
SPACE PHYSICS RESEARCH LABORATORY				ELECTRONIC HOUSING ASS'Y			
COLLEGE OF ENGINEERING				EIGHT			
THE UNIVERSITY OF MICHIGAN				SMI ALP			
ANN ARBOR, MICHIGAN							
UNLESS OTHERWISE SPECIFIED TOLERANCES ARE:				DWG. NO B-048-019			
DIM. FRACTIONS .005							
DIM. DECIMALS .002							
DIM. ANGLES .015							

APPENDIX D

Measurement Mode Specifications

Modes of Operation

(revised October 7, 1992)

I. Solar Flux Monitor

1) Standard EUV Measurement Mode:

G1 = - 25V

G2 = +25V

G3 = - 15V

Target = sweep from +20V to -36V in 1V steps (57 total)

Telemetry: 1 reading of Decade & Vernier settings, 57 A/D values
= 1 word + 57 words = 58 words = 116 bytes

2) High Resolution EUV Measurement Mode:

G1 = - 25V

G2 = +25V

G3 = - 15V

Target = sweep from +20V to -36V in 0.25V steps (225 total)

Telemetry: 1 reading of Decade & Vernier settings, 225 A/D values
= 1 word + 225 words = 226 words = 452 bytes

3) Grid 1 Test Mode:

G1 = - 35V, - 30V, - 25V, - 20V, - 15V

G2 = +25V

G3 = - 15V

Target = sweep from +20V to -36V in 2V steps (29 total)

Telemetry: 5 * (1 reading of Decade & Vernier settings, 29 A/D values)
= 5 * (1 word + 29 words) = 150 words = 300 bytes

4) Grid 2 Test Mode:

G1 = - 25V

G2 = +15V, +20V, +25V, +30V, +35V

G3 = - 15V

Target = sweep from +20V to -36V in 2V steps (29 total)

Telemetry: 5 * (1 reading of Decade & Vernier settings, 29 A/D values)
= 5 * (1 word + 29 words) = 150 words = 300 bytes

5) Grid 3 Test Mode:

G1 = - 25V

G2 = +25V

G3 = - 25V, - 20V, - 15V, - 10V, - 5V

Target = sweep from +20V to -36V in 2V steps (29 total)

Telemetry: 5 * (1 reading of Decade & Vernier settings, 29 A/D values)
= 5 * (1 word + 29 words) = 150 words = 300 bytes

6) EUV Ion Retarding Potential Analyzer Mode:

G1 = - 10 V

G2 = sweep from -5V to +5V in 0.2V steps (51 total)

G3 = 0V

Target = 0V

Telemetry: 1 reading of Decade & Vernier settings, 51 A/D values
= 1 word + 51 words = 52 words = 104 bytes

7) EUV Electron Retarding Potential Analyzer Mode:

G1 = +10 V

G2 = sweep from -5V to +5V in 0.2V steps (51 total)

G3 = 0V

Target = 0V

Telemetry: 1 reading of Decade & Vernier settings, 51 A/D values
= 1 word + 51 words = 52 words = 104 bytes

8) EUV Cleaning Mode 1 (5 seconds):

G1 = + 50V

G2 = + 30V

G3 = + 15V

Target = +125V

Telemetry: None.

II. Advanced Langmuir Probe

1) Fast (5-point) ALP Mode:

Probe V_a = values determined by algorithm (5 total)

Telemetry: 1 reading of Decade & Vernier settings, 1 reading of kTe,
5 A/D & D/A values
= 1 word + 1 word + 2 * 5 words = 12 words = 24 bytes

2) Standard ALP Sweep Mode:

Probe V_a = sweep from -5 V to +5 V in 0.1V steps (101 total)

Telemetry: 1 reading of Decade & Vernier settings, 101 A/D values
= 1 (16-bit) word + 101 words = 102 words = 204 bytes

3) High Resolution ALP Sweep Mode:

Probe V_a = sweep from -1.7V to +1.7V in 0.04V steps (86 total)

Telemetry: 1 reading of Decade & Vernier settings, 86 A/D values
= 1 word + 86 words = 87 words = 174 bytes

4) Medium Resolution ALP Sweep Mode:

Probe V_a = sweep from -9kTe to +1kTe in kTe/8 steps (81 total), and a
single reading at 2V above 1kTe

Telemetry: 1 reading of Decade & Vernier settings, 1 reading of kTe,
81 A/D values
= 1 word + 1 word + 81 words = 83 words
= 166 bytes

5) ALP Cleaning Mode 1 (5 seconds):

Probe V_a = +125 V

Telemetry: None.

Notes:

- 1) All data will be transmitted in packet form. The telemetry requirements above do not include packet headers & terminators (start codes, mode ID, packet length, timestamp, checksum).
- 2) To avoid unnecessary redundancy, the housekeeping information will be sent in a separate packet.

Langmuir Probe Five-Point Algorithm

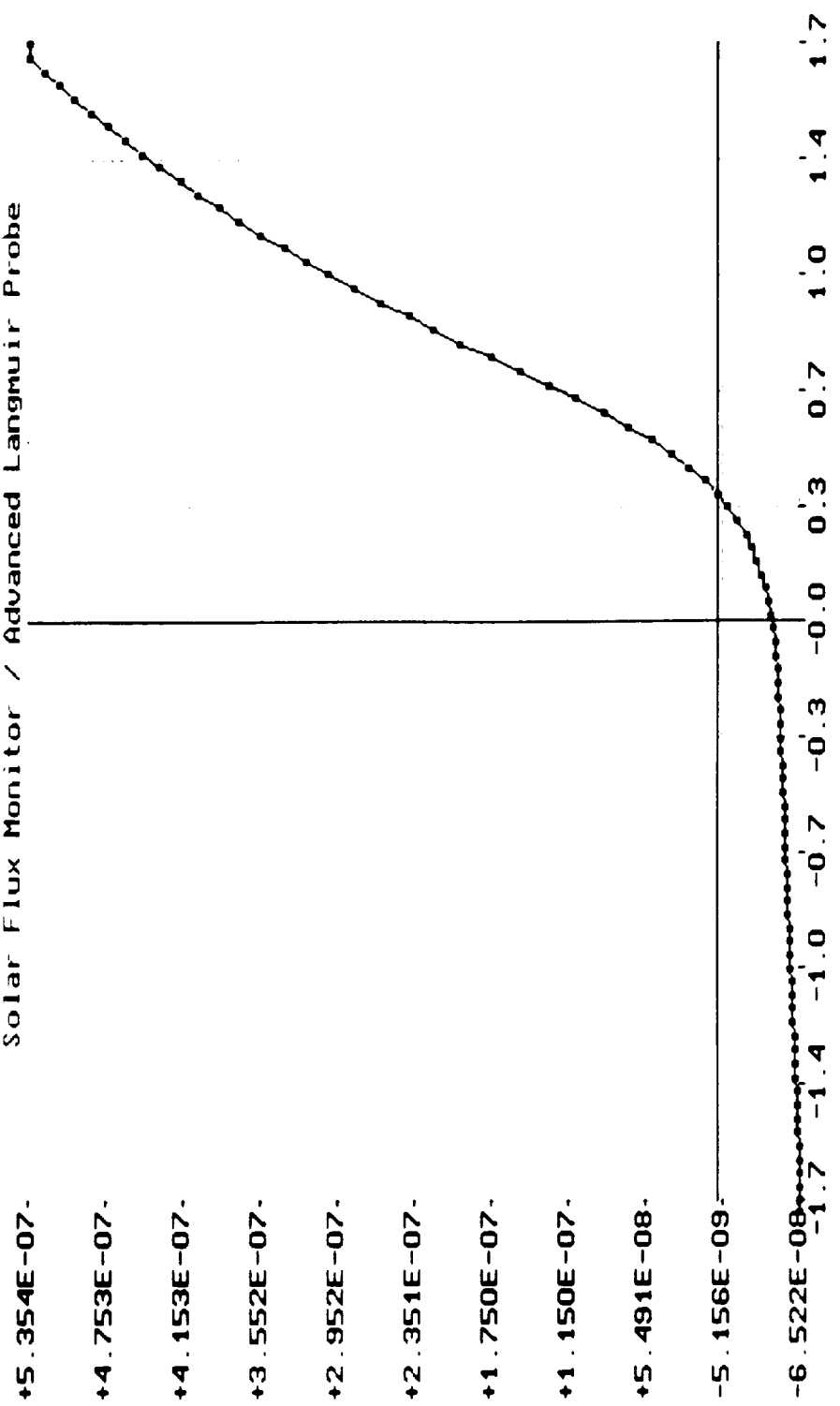
1. Set $V_a=V_1$ (initial value = -5.0 V)
2. Set preamp and vernier so that A/D measures $I_1 = -3.3V$
3. Set $V_a=V_3$ so that A/D measures $I_3 = -0.4715 * I_1$
4. Set $V_a=V_4$ so that A.D measures $I_4 = -4.0 * I_1$ (max. +5.0V)
5. Set $V_a=V_2 = V_1 + 2 * (V_4 - V_3)$ & measure I_2
6. Set $V_a=V_5 = V_4 + 7 * (V_4 - V_3)$ & measure I_5
7. Compute new $V_1 = -9 * (V_4 - V_3)$
8. Telemeter $V_1, I_1, V_2, I_2, V_3, I_3, V_4, I_4, V_5, I_5$

(For mode which sweeps from $-9kT_e$ to $+1kT_e$, $kT_e = V_4 - V_3$)

APPENDIX E

Representative Data from Sounding Rocket Flight

Solar Flux Monitor / Advanced Langmuir Probe



Process ID
 ALP_PROC
 Grid 1 (U)

Mode
 ALP_HR
 Grid 2 (U)

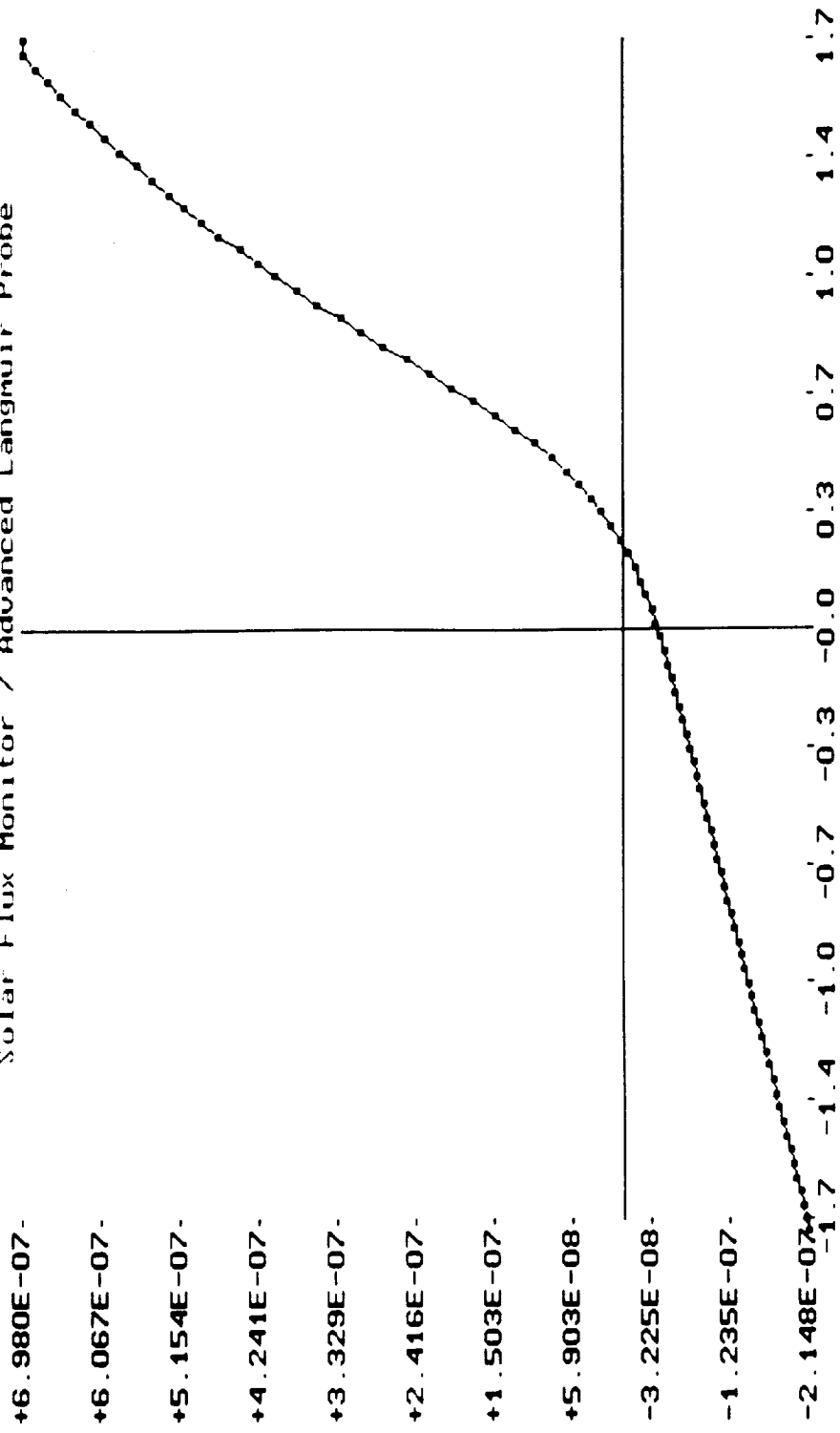
Mode Start Time
 10.305 = 2061
 Grid 3 (U)

Altitude (m)

Pre/Uern Gain
 0x1AFF
 Target (U)

Telemetry Source - GOODTM.ALP

Solar Flux Monitor / Advanced Langmuir Probe



Process ID
 ALP_PROC
 Grid 1 (V)

 Mode ALP_HR
 Grid 2 (V)

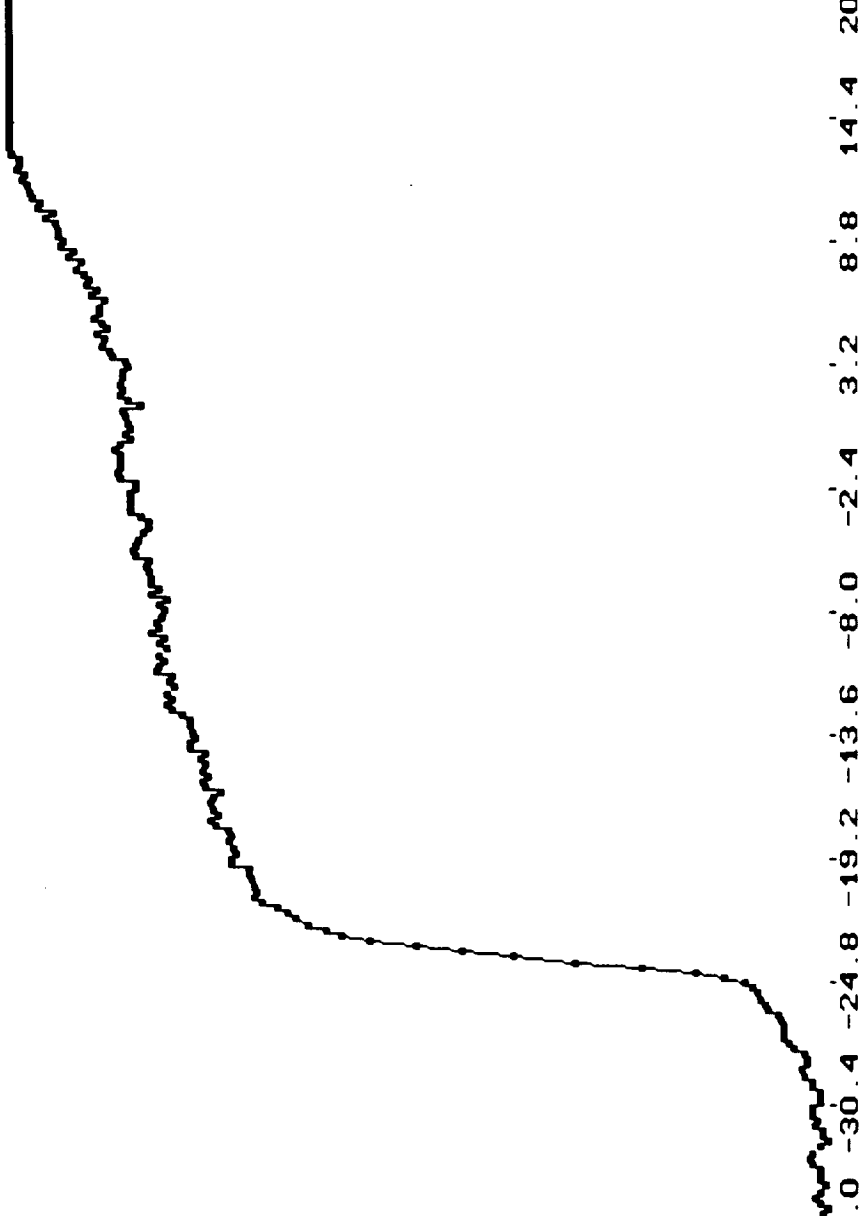
 Mode Start Time Altitude (m)
 7.730 = 1546. *****
 Grid 3 (V)

 Pre/Uern Gain
 0x1000
 Target (V)

Telemetry Source - GOODIM.ALP

Solar Flux Monitor / Advanced Langmuir Probe

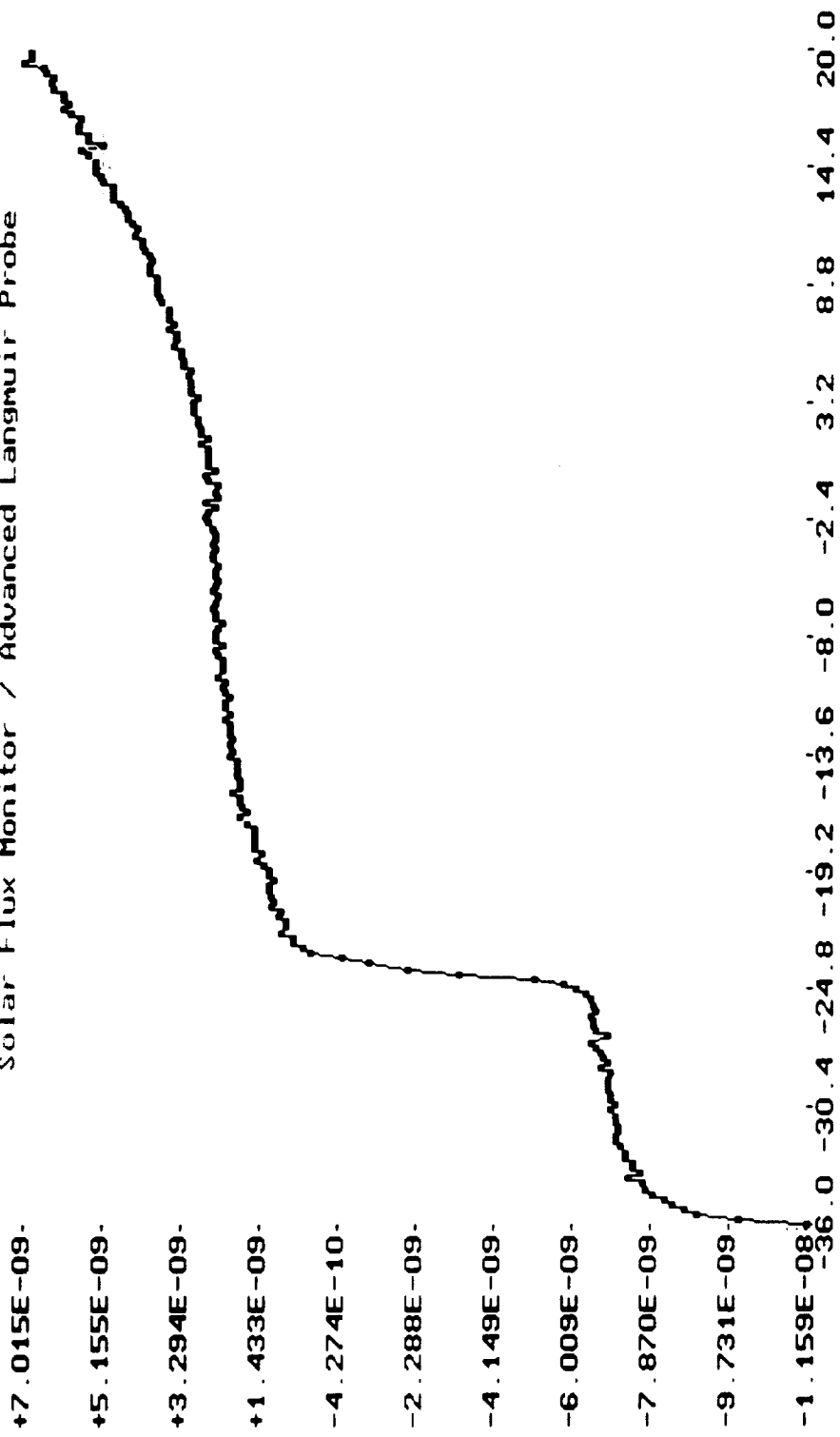
+9.565E-09-
 +7.994E-09-
 +6.423E-09-
 +4.853E-09-
 +3.282E-09-
 +1.712E-09-
 +1.412E-10-
 -1.429E-09-
 -3.000E-09-
 -4.570E-09-
 -6.141E-09-
 -36.0 -30.4 -24.8 -19.2 -13.6 -8.0 -2.4 3.2 8.8 14.4 20.0



Process ID SFM_PROC Grid 1 (U) -25.0
 Mode SFM_Grid 2 (U) +25.0
 Mode Start Time 300.355 = 60071 Grid 3 (U) -15.0
 Altitude (m) 221622
 Pre/Uern Gain 0x3000
 Target (U) SNEEP

Telemetry Source - GOODTM.SFM

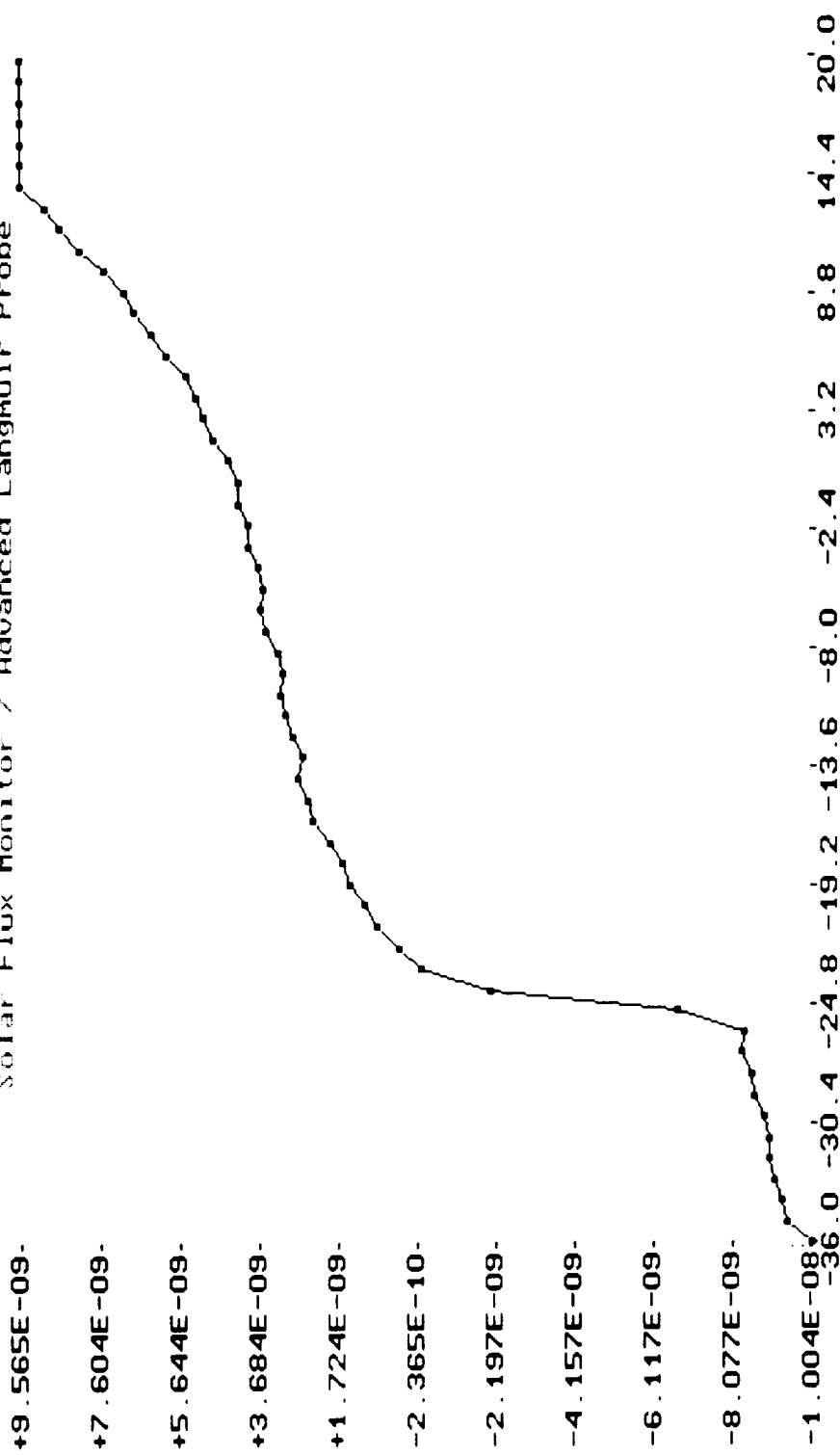
Solar Flux Monitor / Advanced Langmuir Probe



Process ID SFM_HR Mode Start Time Altitude (m) Pre/Verb Gain
 SFM_HR Grid 1 (V) 116.585 = 23317 Grid 3 (V) 0x1000
 -25.0 +25.0 -15.0 Target (V) \$SWEEP

Telemetry Source - GOODTM.SFM

Solar Flux Monitor / Advanced Langmuir Probe



Process ID SFM_PROC Grid_1 (V) -25.0 Mode SFM_STD Grid_2 (V) +25.0 Mode Start Time 304.950 = 60990 Grid_3 (V) -15.0 Altitude (m) 219322 Pre/Uern Gain 0x3000 Target (U) SNEEP

Telemetry Source - GOODTM.SFM

