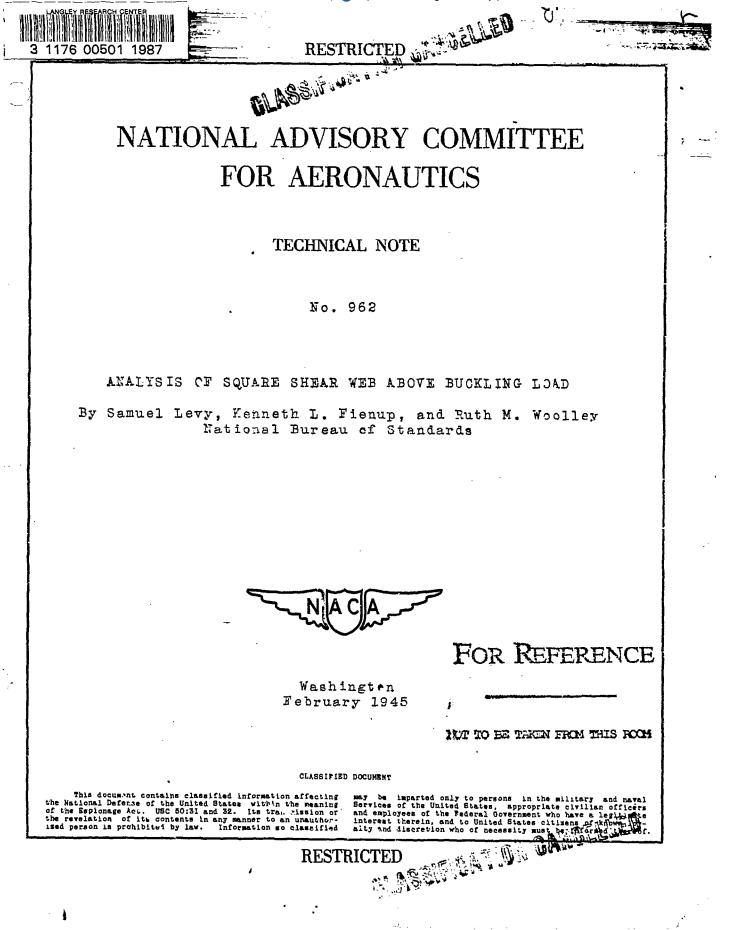
https://ntrs.nasa.gov/search.jsp?R=19930085189 2020-06-17T15:41:45+00:00Z





NATIONAL ADVISORY COMMITTEE FOR AERONAUTICS

TECHNICAL NOTE NO. 962

ANALYSIS OF SQUARE SHEAR WEB ABOVE BUCKLING LOAD

By Samuel Levy, Kenneth L. Fienup, and Ruth M. Woolley

SUMMARY

A solution of Von Karman's fundamental equations for plates with large deflections is presented for the case of a shear web divided into square panels by reinforcing struts. Numerical solutions are given for struts of infinite rigidity and for struts the weight of which is one-fourth the weight of the sheet. The results are compared with Wagner's diagonal tension theory as extended by Kuhn and by Langhaar. It is found that the diagonal tension theory as developed by Kuhn agrees best with the present paper in the practical range when r = 1/4. Kuhn's theory is in especially good agreement for the force in the strut when r = 1/4.

INTRODUCTION

The necessity for designing structures having the smallest possible weight for a given load has forced airplane designers to build wing-beams and monocoque boxes with shear webs so thin that they may be buckled in a diagonal direction under service loads. As the shear load is increased well above the buckling load, it is carried principally by diagonal tension along the buckles. The beam approaches a "diagonal-tension field" beam.

٦

The load at which such shear webs will buckle has been determined by several authors. (See, for example, pp. 357 to 363 of reference 1.) After buckling, the behavior of the web is frequently detersined from Wagner's diagonaltension-field theory (references 2 and 3) which neglects the flexural rigidity of the sheet. Experimental results .(see p. 2 of reference 4, pp. 18 and 19 of reference 5, and p. 5 of reference 6) indicate that Wagner's diagonal-tension-

RESTRICTED

field theory may be too conservative for constructions in which the diagonal tension field is only partially developed.

An analysis of the behavior of a flat plate subjected to shearing loads covering the range from the start of buckling to the development of a full diagonal tension field was, therefore, thought desirable. Such an analysis, based on Von Karman's large deflection equations, was made for the case of a shear web divided into square panels by vertical struts.

This investigation, conducted at the National Bureau of Standards, was sponsored by and conducted with the financial assistance of the National Advisory Committee for Aeronautics.

SYMBOLS

The following symbols are used (see also fig. 1): plate length and plate width а plate thickness h normal displacement of points of the middle surface w Ε Young's modulus Poisson's ratio, assumed to be $\sqrt{0.1} = 0.316$ μ x.y coordinate axes with origin at corner of one bay of the web plate $D = \frac{Eh^3}{12(1-\mu^2)} = \frac{Eh^3}{10.8}$ flexural rigidity of the plate F stress function shear load carried by beam Q. average stress in plate in x-direction $\sigma_{\mathbf{x}}$ $\overline{\sigma}_{y}$ average stress in plate in y-direction shear stress at corners of plate τ ratio of strut area to plate area r P compressive force in strut

٩.

\$

 $\epsilon_x^1, \epsilon_y^1, \gamma_x^1$ median fiber strains $\sigma_{\pm}^{1}, \sigma_{y}^{1}, \tau_{xy}^{1}$ median fiber stresses $\sigma_x^{II}, \sigma_y^{II}, \tau_{xy}^{II}$ extreme fiber bending stresses coefficients in stress function A_m, B_n lateral pressure р ^bm,n coefficient in stress function coefficient in deflection function Wm.n integral numbers used as subscripts m. n $Y = 2.632 \tau/E$ apparent shearing deformation of beam $(\overline{Y}$ is the angle through which the flanges of the beam rotate relative to the struts) displacements in x and y directions. u, v respectively. Μ bending moment in flange

FUNDAMENTAL EQUATIONS

Consider an initially flat square plate of uniform thickness. Two opposite edges are assumed to be simply supported by heavy flanges, integral with the plate, which allow rotation about the edges but prevent displacement parallel to the edges and force the edges to remain straight. The other two edges are simply supported by struts, integral with the plate, which allow rotation about the eges and displacement parallel to the edges corresponding to shortening of the strut under load but maintain the edges in a straight line.

EQUATIONS FOR THE DEFORMATIONS OF THIN PLATES

The fundamental equations governing the deformation of thin plates were developed by Von Karman. They are (see reference 1, pp. 322-323):

.

ŧ

-5

.,

٦.

$$\frac{\partial^{4}F}{\partial x^{4}} + 2 \frac{\partial^{4}F}{\partial x^{2} \partial y^{2}} + \frac{\partial^{4}F}{\partial y^{4}} = E \left[\left(\frac{\partial^{2}w}{\partial x \partial y} \right)^{2} - \frac{\partial^{2}w}{\partial x^{2}} \frac{\partial^{2}w}{\partial y^{2}} \right]$$
(1)
$$\frac{\partial^{4}w}{\partial x^{4}} + 2 \frac{\partial^{4}w}{\partial x^{2} \partial y^{2}} + \frac{\partial^{4}w}{\partial y^{4}} = \frac{p}{D} + \frac{h}{D} \left(\frac{\partial^{2}F}{\partial y^{2}} \frac{\partial^{2}w}{\partial x^{2}} + \frac{\partial^{2}F}{\partial x^{2}} \frac{\partial^{2}w}{\partial y^{2}} - 2 \frac{\partial^{2}F}{\partial x \partial y} \frac{\partial^{2}w}{\partial x \partial y} \right)$$
(2)

where the median-fiber stresses are

$$\sigma_{x}^{i} = \frac{\partial^{2} F}{\partial y^{2}}, \quad \sigma_{y}^{i} = \frac{\partial^{2} F}{\partial x^{2}}, \quad \tau_{xy}^{i} = -\frac{\partial^{2} F}{\partial x \partial y}$$
(3)

and the median-fiber strains are

$$\epsilon_{x}^{1} = \frac{1}{E} \left(\frac{\partial^{2} F}{\partial y^{2}} - \mu \frac{\partial^{2} F}{\partial x^{2}} \right)$$

$$\epsilon_{y}^{1} = \frac{1}{E} \left(\frac{\partial^{2} F}{\partial x^{2}} - \mu \frac{\partial^{2} F}{\partial y^{2}} \right)$$

$$\gamma_{x,y}^{1} = -\frac{2(1+\mu)}{E} \frac{\partial^{2} F}{\partial x \partial y}$$

$$(4)$$

The extreme-fiber bending stresses are

$$\sigma_{\mathbf{x}}^{"} = -\frac{Eh}{2(1-\mu^{2})} \left(\frac{\partial^{2} w}{\partial x^{2}} + \mu \frac{\partial^{2} w}{\partial y^{2}} \right)$$

$$\sigma_{\mathbf{y}}^{"} = -\frac{Eh}{2(1-\mu^{2})} \left(\frac{\partial^{2} w}{\partial y^{2}} + \mu \frac{\partial^{2} w}{\partial x^{2}} \right)$$

$$\tau_{\mathbf{x},\mathbf{y}}^{"} = -\frac{Eh}{2(1+\mu)} \frac{\partial^{2} w}{\partial x \partial y}$$
(5)

J

٩,

2

EQUILIBRIUM OF MEDIAN FIBER FORCES

Seydel (reference 7, p. 181) showed that the buckling load of a simply supported square plate subjected to shearing forces is given with an error of less than 1 percent if the deflection is described by

$$w = w_{1,1} \sin \frac{\pi x}{a} \sin \frac{\pi y}{a} + w_{1,3} \sin \frac{\pi x}{a} \sin \frac{3\pi y}{a} + w_{3,1} \sin \frac{3\pi x}{a} \sin \frac{\pi y}{a} + w_{2,2} \sin \frac{2\pi x}{a} \sin \frac{2\pi y}{a} + w_{3,3} \sin \frac{3\pi x}{a} \sin \frac{3\pi y}{a}$$
 (6)

where $w_{1,1}$, $w_{1,3}$, $w_{3,1}$, $w_{2,2}$, and $w_{3,3}$ are five adjustable constants. The analysis will be carried well beyond the buckling load on the assumption that expression (6) continues to give an adequate description of the buckles in the plate.

A suitable stress function F must now be chosen to satisfy equation (1) which expresses the condition that the median fiber forces are in equilibrium in the plane of the web. If F is taken as, ٠

٩,

k

$$F = \frac{\overline{\sigma}_{X} y^{\overline{z}}}{2} + \frac{\overline{\sigma}_{Y} x^{\overline{z}}}{2} - \tau_{XY} + \sum_{m=0}^{6} \sum_{n=0}^{6} b_{m,n} \cos \frac{m\pi x}{a} \cos \frac{m\pi y}{a}$$

$$+ \sum_{m=2,4,6} \dot{a}_{m} \cos \frac{m\pi x}{a} \left[\left(\frac{1-\mu}{1+\mu} - \frac{m\pi}{2} \operatorname{coth} \frac{m\pi}{2} \right) \operatorname{cosh} m\pi \left(\frac{y}{a} - \frac{1}{2} \right) \right]$$

$$+ m\pi \left(\frac{y}{a} - \frac{1}{2} \right) \sinh m\pi \left(\frac{y}{a} - \frac{1}{2} \right) \right]$$

$$+ \sum_{m=1,3,5} A_{m} \cos \frac{m\pi x}{a} \left[\left(\frac{1-\mu}{1+\mu} - \frac{m\pi}{2} \tanh \frac{m\pi}{2} \right) \sinh m\pi \left(\frac{y}{a} - \frac{1}{2} \right) \right]$$

$$+ \sum_{n=2,4,6} B_{n} \cos \frac{n\pi y}{a} \left[\left(\frac{1-\mu}{1+\mu} - \frac{n\pi}{2} \coth \frac{n\pi}{2} \right) \cosh m\pi \left(\frac{x}{a} - \frac{1}{2} \right) \right]$$

$$+ \sum_{n=2,4,6} B_{n} \cos \frac{n\pi y}{a} \left[\left(\frac{1-\mu}{1+\mu} - \frac{n\pi}{2} \coth \frac{n\pi}{2} \right) \cosh n\pi \left(\frac{x}{a} - \frac{1}{2} \right) \right]$$

$$+ \sum_{n=1,3,5} B_{n} \cos \frac{n\pi y}{a} \left[\left(\frac{1-\mu}{1+\mu} - \frac{n\pi}{2} \tanh \frac{n\pi}{2} \right) \sinh n\pi \left(\frac{x}{a} - \frac{1}{2} \right) \right]$$

$$+ n\pi \left(\frac{x}{a} - \frac{1}{2} \right) \sinh n\pi \left(\frac{x}{a} - \frac{1}{2} \right) \right]$$

and if equations (6) and (7) are substituted into equation (1) it is found by a method shown in reference 8 that equation (1) is identically satisfied when

(7)

1

Т

.

٠

Ý

$$b_{0,0} = 0$$

$$b_{0,8} = \frac{E}{64} (3w_{1,1}^{2} - 4w_{1,1}w_{1,8} + 18w_{3,1}^{2} - 36w_{3,1}w_{3,3})$$

$$b_{0,4} = \frac{E}{1024} (16w_{1,1}w_{1,3}^{+144w_{3,1}w_{3,3} + 32w_{2,8}^{2})$$

$$b_{0,6} = \frac{E}{5164} (16w_{3,8}^{2} + 18w_{1,3}^{2})$$

$$b_{1,1} = \frac{E}{160} (16w_{1,1}w_{3,2} + 16w_{2,2}w_{3,1})$$

$$b_{1,3} = \frac{E}{400} (16w_{1,1}w_{3,2} + 64w_{2,2}w_{3,3})$$

$$b_{2,0} = \frac{E}{64} (2w_{1,1}^{2} - 4w_{1,1}w_{3,1} - 36w_{1,3}w_{3,3} + 18w_{1,3}^{2})$$

$$b_{2,0} = \frac{E}{64} (2w_{1,1}^{2} - 4w_{1,1}w_{3,1} - 36w_{1,3}w_{3,3} + 16w_{1,3}^{2})$$

$$b_{2,0} = \frac{E}{64} (2w_{1,1}^{2} - 4w_{1,1}w_{3,1} - 36w_{1,3}w_{3,3} + 16w_{1,3}^{2})$$

$$b_{2,0} = \frac{E}{6400} (16w_{1,1}w_{3,1} + 16w_{1,1}w_{1,3} - 84w_{1,3}w_{3,1})$$

$$b_{2,4} = \frac{E}{1600} (100w_{1,3}w_{3,1} - 4w_{1,1}w_{1,3} + 36w_{1,1}w_{3,3})$$

$$b_{3,3} = 0$$

$$b_{3,5} = \frac{E}{1024} (28w_{2,3}^{2} + 16w_{1,1}w_{3,1} + 144w_{3,3}w_{1,3})$$

$$b_{4,0} = \frac{E}{1024} (28w_{2,3}^{2} + 16w_{1,1}w_{3,1} + 144w_{3,3}w_{1,3})$$

$$b_{4,4} = \frac{E}{1000} (100w_{1,3}w_{3,1} - 4w_{1,1}w_{3,1} + 144w_{3,3}w_{1,3})$$

$$b_{4,5} = \frac{E}{1000} (100w_{1,3}w_{3,1} - 4w_{1,1}w_{3,1} + 144w_{3,3}w_{1,3})$$

$$b_{4,6} = \frac{E}{102816} (-64w_{1,3}w_{3,3})$$

$$b_{5,1} = \frac{E}{2704} (64w_{2,2}w_{3,1} + 144w_{2,2}w_{3,3})$$

$$b_{5,5} = 0$$

$$b_{6,0} = \frac{E}{5184} (168w_{3,3}^{2} + 19w_{3,1}^{2})$$

$$b_{6,8} = 0$$

$$b_{m,n} = 0$$
 whenever $m + n$ is an odd number

i

٦,

BOUNDARY CONDITIONS

The condition that the edges of the plate be simply supported is automatically satisfied by equation (6) for the lateral deflection.

The condition that the edges of the plate act integrally with the supporting struts and flanges of the beam requires that the strain at the edge of the plate be equal to the strain in the supporting strut or flange. This condition will be used to determine the remaining coefficients $\overline{\sigma}_{x}$, $\overline{\sigma}_{y}$, A_{m} , and B_{n} in equation (7).

The edges y = 0, y = a (see fig. 1) are considered to be supported by flanges so heavy that they do not shorten under load. The median fiber strain in the x-direction at the edges y = 0, y = a must, therefore, be zero.

$$\begin{pmatrix} \epsilon_{x}^{t} \end{pmatrix} = 0$$
 (9)
 $y=0, y=a$

The edges x = 0 and x = a are considered to be supported by struts having a cross-sectional area of r a h. Such struts will shorten under load. If the compressive force in the strut is denoted by P, the median fiber strain in the y-direction at the edges x = 0, x = a must be

$$\left(\epsilon_{y}^{\dagger}\right)_{x=0, x=a} = -\frac{P}{rahE}$$
 (10)

Since there are an equal number of web bays and struts, the compressive force in a strut must equal the vertical tensile force in a web bay, or

 $P = \int_{0}^{a} (h\sigma_{y}^{\dagger}) dx \qquad (11)$

Substituting from equations (3) and (7) into equation (11) and performing the indicated integration gives,

$$P = ah\overline{\sigma}_{y} + \frac{4h}{(1+\mu)a} \sum_{n=2,4,6} n\pi B_{n} \sinh \frac{n\pi}{2} \cos \frac{n\pi y}{a} (12)$$

Substituting equation (12) into equation (10) gives

$$(\epsilon_{y})_{x=0,x=a} = -\frac{\overline{\sigma}_{y}}{rE} - \frac{4\pi}{(1+\mu)ra^{2}E} \sum_{\substack{n=2,4,6}} nB_{n} \sinh \frac{n\pi}{2} \cos \frac{n\pi y}{a} (13)$$

The fact that the summations in the series expansion for F equation (7) have been limited to m and n = 6 makes it impossible to satisfy identically the boundary equations (9) and (13). Except for a small variation in strain of a frequency higher than the sixth harmonic, however, it can be shown by expanding F into trigonometric series and by substituting equations (4), (7), and (8) into equations (9) and (13) that equations (9) and (13) are satisfied

*

for
$$r = \omega \left(w_{1,3} = w_{3,1} \right)$$
, when
 $\overline{\sigma}_y = \overline{\sigma}_x = \frac{\overline{B}}{\alpha^2} \left(1.804w_{1,1}^2 + 18.04w_{1,3}^2 + 16.24w_{3,3}^2 + 7.217w_{3,2}^2 \right)$
 $A_1 = B_1 = \frac{\overline{B}}{10^2} \left(-7.079w_{1,1}w_{2,2} - 12.09w_{1,3}w_{2,2} - 26.96w_{3,3}w_{2,2} \right)$
 $A_2 = B_2 = \frac{\overline{B}}{10^3} \left(-0.3838w_{1,1}^2 - 1.295w_{1,3}^2 - 0.0775w_{3,3}^2 - 0.0856w_{2,2}^2 + 3.693w_{1,1}w_{1,3} + 3.207w_{1,1}w_{3,3} + 14.04w_{1,3}w_{3,3} \right)$
 $A_3 = B_3 = \frac{\overline{B}}{10^4} \left(+0.1F9w_{1,1}w_{2,2} + 2.397w_{1,3}w_{2,2} - 1.581w_{3,3}w_{2,2} \right)$
 $A_4 = B_4 = \frac{\overline{B}}{10^5} \left(-0.0463w_{1,1}^2 - 2.414w_{1,3}^2 - 0.1666w_{3,3}^2 - 1.506w_{2,3}^2 - 0.278w_{1,1}w_{1,3} + 0.162w_{1,1}w_{3,3} - 6.10w_{1,3}w_{3,3} \right)$
 $A_6 = B_6 = \frac{\overline{B}}{10^7} \left(-0.0535w_{1,1}^2 - 1.181w_{1,3}^2 - 6.30w_{2,3}^2 - .214w_{3,3}^2 - 0.214w_{3,3}^2 + 0.417w_{1,1}w_{1,3} + 0.417w_{1,1}w_{3,3} - 2.297w_{1,3}w_{3,3} \right)$

and for r = 0.25, when

$$\begin{array}{l} \vec{G}_{\rm X} = \frac{\Gamma}{4\pi} (+1.336 {\rm w}_{1,1}^2 + 1.975 {\rm w}_{1,3}^2 + 11.41 {\rm w}_{3,1}^2 + 5.354 {\rm w}_{3,2}^2 + 12.05 {\rm w}_{3,3}^2) \\ \vec{G}_{\rm y} = \frac{\Gamma}{4\pi} (+0.3313 {\rm w}_{1,1}^2 + 2.346 {\rm w}_{1,3}^2 + 0.9678 {\rm w}_{3,1}^2 + 1.325 {\rm w}_{2,2}^2 + 2.982 {\rm w}_{3,3}^2) \\ A_{\rm z} = \frac{\Gamma}{20^2} (-0.79 {\rm w}_{1,1} {\rm w}_{2,2} - 1.679 {\rm w}_{1,3} {\rm w}_{2,2} - 1.042 {\rm w}_{3,1} {\rm w}_{2,2} - 26.96 {\rm w}_{3,2} {\rm w}_{3,3}^2) \\ A_{\rm z} = \frac{\Gamma}{20^2} (-7.079 {\rm w}_{1,1} {\rm w}_{2,2} - 10.42 {\rm w}_{1,3} {\rm w}_{2,2} - 1.679 {\rm w}_{3,1} {\rm w}_{2,2} - 26.96 {\rm w}_{3,2} {\rm w}_{3,3}^2) \\ A_{\rm z} = \frac{\Gamma}{20^2} (-7.079 {\rm w}_{1,1} {\rm w}_{2,2} - 10.42 {\rm w}_{1,3} {\rm w}_{2,2} - 0.5602 {\rm w}_{3,2}^2 {\rm w}_{3,3}^2) \\ A_{\rm z} = \frac{\Gamma}{20^2} (-7.079 {\rm w}_{1,1} {\rm w}_{2,2} - 10.42 {\rm w}_{1,3} {\rm w}_{3,1} - 0.6007 {\rm w}_{3,2}^2 - 0.5622 {\rm w}_{3,3}^2) \\ A_{\rm z} = \frac{\Gamma}{20^2} (-7.079 {\rm w}_{1,1} {\rm w}_{2,3} + 21.698 {\rm w}_{1,1} {\rm w}_{3,3}^2) \\ = 2.04 {\rm w}_{1,3} {\rm w}_{3,1} + 29.87 {\rm w}_{1,3} {\rm w}_{3,5} + 0.0407 {\rm w}_{3,3}^2 + 0.5622 {\rm w}_{3,3}^2, \\ \pm 20.46 {\rm w}_{1,3} {\rm w}_{3,1} + 29.87 {\rm w}_{1,3} {\rm w}_{3,5} + 70.94 {\rm w}_{3,1} {\rm w}_{3,3} \\ \pm 20.46 {\rm w}_{1,3} {\rm w}_{3,1} + 29.97 {\rm w}_{1,3} {\rm w}_{3,5} + 70.94 {\rm w}_{3,1} {\rm w}_{3,3} \\ \pm 20.46 {\rm w}_{1,3} {\rm w}_{3,1} + 18.32 {\rm w}_{1,3} {\rm w}_{3,3} + 9.295 {\rm w}_{1,3} {\rm w}_{3,5} + 70.94 {\rm w}_{3,1} {\rm w}_{3,3} \\ \pm 20.46 {\rm w}_{1,3} {\rm w}_{3,1} + 18.32 {\rm w}_{1,3} {\rm w}_{3,3} + 2.25 {\rm w}_{3,1} {\rm w}_{3,3} + 1.578 {\rm w}_{3,2} {\rm w}_{3,3} \\ \pm 12.87 {\rm w}_{1,1} {\rm w}_{1,3} {\rm w}_{3,4} + 0.133 {\rm w}_{1,1} {\rm w}_{3,2} + 0.133 {\rm w}_{1,3} {\rm w}_{3,3} + 1.578 {\rm w}_{3,3} {\rm w}_{3,3} \\ \pm 12.42 {\rm w}_{1,3} {\rm w}_{3,1} + 10.32 {\rm w}_{1,3} {\rm w}_{3,3} + 0.135 {\rm w}_{3,1} {\rm w}_{3,3} + 0.1307 {\rm w}_{3,3}^2 \\ \pm \frac{\Gamma}{10^2} (-0.02685 {\rm w}_{1,1}^2 {\rm w}_{3,3} + 0.0667 {\rm w}_{3,1} {\rm w}_{3,3} + 0.1307 {\rm w}_{3,3}^2 \\ \pm 0.133 {\rm w}_{1,1} {\rm w}_{1,3} + 0.0262 {\rm w}_{1,1} {\rm w}_{3,3} + 0.3616 {\rm w}_{3,1} {\rm w}_{3,3} \\ \pm 0.133 {\rm w}_{1,3} {\rm w}_{1,3} + 0.0414 {\rm w}_{1,1} {\rm w}_{3,3} \\ \pm 0.4$$

11

.

ţ

:

:

:

:

ş

ł

÷

The struts and flanges are considered to be stiff enough in bending to keep straight the four edges (x = 0, x = a, y = 0, y = a) of the plate. Equations for the u and v displacement can be obtained from p. 322 of reference 1.

$$\frac{\partial u}{\partial x} = \epsilon_{x}^{i} - \frac{1}{2} \left(\frac{\partial w}{\partial x} \right)^{2}$$

$$\frac{\partial v}{\partial y} = \epsilon_{y}^{i} - \frac{1}{2} \left(\frac{\partial w}{\partial y} \right)^{2}$$

$$\frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} = \gamma_{x,y} - \frac{\partial w}{\partial x} \frac{\partial w}{\partial y}$$
(15)

Values of u and v can be obtained by substituting equations (4), (6), (7), (8), and (14) into equations (15) and integrating. This gives for the values of u and v at the edges of the plate for $r = \infty$,

$$(u)_{x=0} = 0, \qquad (u)_{x=a} = 0$$

$$(v)_{y=0} = x \frac{2.632T}{E};$$
 $(v)_{y=a} = x \frac{2.632T}{E}.$ (16a)

and for r = 0.25

$$(u)_{x=0} = 0;$$
 $(u)_{x=a} = 0$

$$(v)_{y=0} = x \frac{2.632\tau}{E};$$
 $(v)_{y=a} = x \frac{2.632\tau}{E} - \frac{4}{a} (0.3313w_{1,1}^{2})$
+ $2.346w_{1,3}^{2} + 0.9678w_{3,1}^{2} + 1.325w_{2,2}^{2} + 2.982w_{3,3}^{2}) (16b)$

١

It is seen from equations (16) that the edges of the plate corresponding to x = 0, x = a, y = 0, and y = a, satisfy the condition of remaining straight after buckling has started.

EQUILIBRIUM OF LATERAL FORCES

After the web plate buckles, the median fiber forces have components which tend to displace elements of the plate laterally from the original plane of the plate. These forces will displace the plate laterally until the bending stiffness of the plate prevents further displacement. This condition is expressed by equation (2).

The lateral deflection (equation(6)) must now be determined in such a way that equation (2) is satisfied. The fact that the series expression for w (equation (6)) has been limited to only the first five terms, makes it impossible to identically satisfy equation (2). Except for a small unequilibrated lateral pressure p of order higher than 3, however, it can be shown by expanding F into trigonometric series and by substituting equations (6), (7), (8), and (14) into equation (2), as is done in reference 8, that equation (2) is satisfied

*

.

r

١

÷

for
$$x = \omega(u_{1,3} = u_{3,1})$$
, when

$$0 = 1.973u_{1,1}^{2} + u_{1,2}^{2}(-1.657w_{1,3} - 0.1360w_{3,3}) + u_{1,1}(1.4815h^{2} + 25.69w_{1,3}^{2} + 15.16w_{3,5}^{2} + 8.09w_{2,2}^{2} - 8.86w_{1,3}w_{3,3})$$

$$- 0.5840w_{2,2}\frac{Ta^{2}}{E} - 15.147w_{1,3}^{2} - 0.00853w_{3,3}^{2} + 24.36w_{1,3}^{2}w_{3,3}$$

$$+ 1.661u_{3,3}^{2}w_{1,3} + 8.80w_{2,2}^{2}w_{1,3} + 3.602w_{2,2}^{2}w_{3,3}.$$

$$0 = 123.3w_{1,2}^{3} + u_{1,3}^{2}(-19.72w_{1,1} - 61.28w_{3,3}) + u_{1,3}(57.04h^{2} + 12.95w_{1,1}^{2} + 156.6w_{3,3}^{2} + 74.64w_{2,2}^{2} + 24.36w_{1,1}w_{3,3})$$

$$+ 1.051w_{2,2}\frac{Ta^{2}}{E} - 0.2761w_{1,1}^{3} + 0.0235w_{3,3}^{3} - 2.220w_{1,1}^{3}w_{3,3}$$

$$0 = 159.3w_{3,3}^{2} + u_{3,3}^{2}(-0.02561w_{1,1} + 0.1410w_{1,3}) + w_{3,3}(120h^{2} + 513.2w_{1,3}^{2} + 81.90w_{2,2}^{2} + 3.358w_{1,1}w_{1,3} + 15.16w_{1,1}^{2})$$

$$- 1.692w_{2,2}\frac{Ta^{2}}{E} - 0.0453w_{1,1}^{3} - 40.85w_{1,3}^{2} - 4.439w_{1,1}^{2}w_{1,3}$$

$$+ 24.36w_{1,5}^{2}w_{1,1} + 5.599w_{2,8}^{2}w_{1,1} + 149.3w_{1,3}^{2}$$

$$0 = 31.47w_{2,2}^{2} + u_{2,2}(23.704h^{2} + 8.090w_{1,1}^{2} + 149.3w_{1,3}^{2})$$

$$+ T\frac{a}{b}^{2}(-0.5840w_{1,1} + 2.102w_{1,3} - 1.892w_{3,3})$$

1

;

••

and for
$$r = 1/4$$
, when

$$0 = 1.184 w_{1,1}^{2} - w_{1,1}^{2} (0.8048\pi_{1,3}^{2} + 0.8133w_{3,1}^{2} + 0.1021\pi_{3,5}^{2}) + w_{1,2} (6.147w_{1,3}^{2})$$

$$+ 9.424 w_{2,1}^{2} + 4.946 w_{2,2}^{2} + 7.997 w_{3,3}^{2} - 4.438 w_{3,1} w_{3,5}^{2} - 4.5604 w_{1,3} w_{3,5}^{2}$$

$$+ 9.424 w_{3,1}^{2} + 4.946 w_{3,2}^{2} + 7.997 w_{3,3}^{2} - 4.438 w_{3,1} w_{3,5}^{2} - 4.5604 w_{1,3} w_{3,5}^{2}$$

$$+ 9.108 w_{1,3} w_{3,1}^{2} + 1.4815h^{2}) - 0.06137 w_{1,3}^{2} - 0.05188 w_{3,1}^{2} - 0.00543 w_{3,3}^{2}$$

$$- 6.584 w_{1,3}^{2} w_{3,1}^{2} + 1.4815h^{2}) - 0.06137 w_{1,3}^{2} - 0.05188 w_{3,1}^{2} - 0.00543 w_{3,3}^{2}$$

$$- 6.584 w_{1,3}^{2} w_{3,1}^{2} + 1.4815h^{2}) - 0.06137 w_{1,3}^{2} - 0.05188 w_{3,1}^{2} - 0.00543 w_{3,3}^{2}$$

$$- 6.584 w_{1,3}^{2} w_{3,1}^{2} + 1.4815h^{2}) - 0.06137 w_{1,3}^{2} - 0.05188 w_{3,1}^{2} - 0.00543 w_{3,3}^{2} + 2.5907 w_{1,3}^{2} w_{3,3}^{2} + 4.403 w_{1,3} w_{3,3}^{2} + 3.5307 w_{1,3}^{2} w_{3,3}^{2} + 4.403 w_{1,3}^{2} w_{3,3}^{2} + 3.5907 w_{1,3}^{2} w_{3,3}^{2} + 4.4048 w_{3,1}^{2} w_{3,3}^{2} + 3.5907 w_{1,3}^{2} w_{3,3}^{2} + 3.5907 w_{3,1}^{2} w_{3,3}^{2} + 3.5907 w_{3,1}^{2} w_{3,3}^{2} + 3.5907 w_{3,1}^{2} + 3.8007 w_{1,3}^{2} w_{3,3}^{2} + 3.6907 w_{3,1}^{2} + 1.8938 w_{3,1}^{2} w_{3,3}^{2} + 3.598 w_{1,1}^{2} + 1.0518 w_{1,3}^{2} + 1.0518 w_{3,1}^{2} - 1.8928 w_{3,8}^{2} + 3.598 w_{1,1}^{2} w_{3,1}^{2} + 3.598 w_{1,2}^{2} w_{3,1}^{2} + 3.598 w_{1,1}^{2} w_{3,1}^{2} + 3.598 w_{1,1}^{2} w_{3,1}^{2} + 3.598 w_{1,2}^{2} w_{3,1}^{2} + 3.598 w_{1,1}^{2} w_{3,1}^{2} + 3.598 w_{1,1}^{2} w_{3,1}^{2} + 3.598 w_{1,1}^{2} w_{3,1}^{2} + 3.598 w_{1,2}^{2} w_{3,1}^{2} + 3.598 w_{1,2}^{2} w_{3,1}^{2} + 3.598 w_{1,1}^{2} w_{3,1}^{2} + 3.598 w_{1,2}^{2} w_{3,1}^{2} + 3.598 w_{1,2}^{2} w_{3,1}^{2} + 3.598 w_{1,2}^{2} w_{3,1}^{2} + 3.598 w_{1,2$$

BENDING MOMENT AND SHEARING FORCE IN FLANGE

A flange of the beam (fig. 1) can itself be considered as a beam supported at the strut points and subjected to a lateral load by the median fiber tension in the shear web. Before buckling, the web carries all the shearing force in shear and therefore there is no tendency to bend the flange. After buckling, however, the web carries some of the shearing force by developing a diagonal tension field. This diagonal tension field tends to draw the two flanges together.

The flange bending moment will be considered as positive when it curves the lower flange concave upward or the upper flange concave downward. The shearing force in either flange will be considered positive if it tends to support an external load Q. directed as shown in figure 1.

If use is made of the fact that the flange bending mement is the same at each strut point, the shearing forces in the upper and lower flanges are, respectively,

$$\int_{\mathbf{x}}^{\mathbf{a}} h(\sigma_{\mathbf{y}}^{\mathbf{i}})_{\mathbf{y}=\mathbf{a}} d\mathbf{x} - \frac{1}{\mathbf{a}} \int_{\mathbf{0}}^{\mathbf{a}} h(\sigma_{\mathbf{y}}^{\mathbf{i}})_{\mathbf{y}=\mathbf{a}} \mathbf{x} d\mathbf{x}$$

$$\frac{1}{\mathbf{a}} \int_{\mathbf{0}}^{\mathbf{a}} h(\sigma_{\mathbf{y}}^{\mathbf{i}})_{\mathbf{y}=\mathbf{0}} \mathbf{x} d\mathbf{x} - \int_{\mathbf{x}}^{\mathbf{a}} h(\sigma_{\mathbf{y}}^{\mathbf{i}})_{\mathbf{y}=\mathbf{0}} d\mathbf{x}$$

$$(18)$$

The bending moment in the flange is determined by making the slope of the flange the same at each strut point. This gives for the bending moments in the upper and lower flanges, respectively,

$$M_{y=a} = \frac{1}{2} \int_{0}^{a} h(\sigma_{y}^{i})_{y=a} x(1-\frac{x}{a})dx + \frac{x}{a} \int_{0}^{a} h(\sigma_{y}^{i})_{y=a} xdx$$

$$- \int_{0}^{x} dx \int_{x}^{a} h(\sigma_{y}^{i})_{y=a} dx,$$

$$M_{y=0} = \frac{1}{2} \int_{0}^{a} h(\sigma_{y}^{i})_{y=0} x(1-\frac{x}{a}) dx + \frac{x}{a} \int_{0}^{a} h(\sigma_{y}^{i})_{y=0} xdx$$

$$- \int_{0}^{x} dx \int_{x}^{a} h(\sigma_{y}^{i})_{y=0} dx$$

$$(19)$$

and

NACA TH NO. 963

6

Substituting for $(\sigma_y)_{y=0}$ from equations (3) and (7) and v performing the integrations in equation (19) gives for $M_{y=0}$ $M_{y=0}$

$$= a^{2}h\overline{\sigma}_{y}\left(\frac{1}{12} - \frac{x}{2a} + \frac{x^{2}}{2a^{2}}\right) + h\left(\frac{2x}{a} - 1\right) \sum_{n=1,3}^{5} \sum_{n=0}^{6} b_{m,n}$$

$$+ h \sum_{m=1,3}^{6} \sum_{n=0}^{5} b_{m,n} \cos \frac{m\pi x}{a}$$

$$+ h \sum_{m=1,3}^{5} A_{m}\left[\left(\frac{1-\mu}{1+\mu} - \frac{m\pi}{2} \tanh \frac{m\pi}{2}\right) \sinh \frac{m\pi}{2} + \frac{m\pi}{2} \cosh \frac{m\pi}{2}\right] \left(1 - \frac{2x}{a} - \cos \frac{\pi\pi x}{c}\right)$$

$$+ h \sum_{m=a,4}^{6} A_{m}\left[\left(\frac{1-\mu}{1+\mu} - \frac{m\pi}{2} \coth \frac{n\pi}{2}\right) \cosh \frac{m\pi}{2} + \frac{\pi\pi}{2} \sinh \frac{m\pi}{2}\right] \cos \frac{m\pi x}{a}$$

$$+ h \sum_{n=1,3}^{5} B_{n}\left\{\left[\frac{1-\mu}{1+\mu} - \frac{m\pi}{2} \tanh \frac{n\pi}{2}\right]\left[\left(1 - \frac{2x}{a}\right) \sinh \frac{n\pi}{2} + \sinh n\pi\left(\frac{x}{a} - \frac{1}{2}\right)\right]\right\}$$

$$+ n\pi \left(\frac{x}{a} - \frac{1}{2}\right) \left[\cosh n\pi \left(\frac{x}{a} - \frac{1}{2}\right) - \cosh \frac{n\pi}{2}\right]\right\}$$

$$+ h \left(\sum_{n=a,4}^{6} 3_{n}\left\{\left[\frac{1-\mu}{1+\mu} - \frac{n\pi}{2} \coth \frac{n\pi}{2}\right] \cosh n\pi\left(\frac{x}{a} - \frac{1}{2}\right) + \frac{4\mu}{n\pi(1+\mu)} \sinh \frac{n\pi}{2}\right]\right\}$$

$$+ n\pi \left(\frac{x}{a} - \frac{1}{2}\right) \sinh n\pi \left(\frac{x}{a} - \frac{1}{2}\right)\right\} (19a)$$

SHEAR LOAD CARRIED BY BEAM

The beam (fig. 1) supports a shear load Q. At any vertical section through the beam this load is partially carried by shear in the web and partially by shear in the flanges. Part of the shear in the web may be considered due to the diagonal tension after buckling.

٠

The shear load carried by the flanges is obtained by adding equations (18). The shear load carried by the web is

$$-\int_{0}^{a}h \tau_{xy}^{\dagger} dy \qquad (20)$$

Adding equations (18) and (20), substituting for σ_y^{\perp} and τ_{xy}^{\perp} their values as given by equations (3), (7), (8), (14a), and (14b), and integrating gives

for
$$r = \infty (W_{1,3} = W_{3,1})$$

$$Q = -\tau_{ah+w_{2,2}} \frac{E_{h}}{a} (1.350w_{1,1} - 4.862w_{1,3} + 4.376w_{3,3})$$
(21a)

and for r = 1/4

$$Q = - \tau_{ah+w_{2}, 2ah} (1.349w_{1, 1} - 2.432w_{1, 3} - 2.430w_{3, 1} + 4.372w_{3, 3})$$
 (21b)

SHEARING DEFORMATION OF BEAM

The shearing forces acting on the end of the beam cause it to shear downward as shown in figure 1. The amount of the downward displacement is $(v)_{y=0}$ in equations (16a) and (16b). This gives

$$(v)_{y=0} = 2.632 \frac{\tau_x}{E} = \overline{\gamma}x; \quad \overline{\gamma} = 2.632 \frac{\tau}{E}$$
 (22)

where Y is the shear deformation of the beam,

EFFECTIVE WIDTH IN SHEAR

The loss in shear stiffness of the beam after buckling of the web may be considered as a loss in effective width of the sheet. The effective width ratio in shear for a given

shearing deformation \overline{Y} will be defined as the ratio of the load actually carried by the beam to the load which might have been carried had the web not buckled.

The load actually carried by the beam is given by equations (21a) and (21b). The shearing deformation of the beam is \overline{Y} (equation 22). From equations (3), (4), and (7), therefore, a load tah might have been carried with a shear deformation \overline{Y} if the web had not buckled. The effective width ratio is, therefore,

Effective width ratio =
$$Q/Tah$$
 (23)

Substituting for Q from equations (21a) and (21b) gives for $r = \infty (w_{1,3} = w_{3,1})$

Effective width ratio

$$= 1 - \frac{E}{\pi e^2} W_{2,2}(1.350W_{1,1} - 4.862W_{1,3} + 4.376W_{3,3}) \quad (24n)$$

and for r = 1/4

Effective width ratio

$$= 1 - \frac{\Xi}{\tau_{a}^{2}} w_{2,2}^{(1.349W_{1,1}-2.432W_{1,3}-2.430W_{3,1}+4.372W_{3,3})}$$
(24b)

COMPRESSIVE FORCE IN VERTICAL STRUT

After buckling of the web, the diagonal tension field tends to draw the two flanges of the beam together. This action is counteracted by the vertical struts which hold the flanges apart. The magnitude of the resulting compressive force in the strut is given by equation (12). Substituting for $\overline{\sigma}_y$, B_2 , B_4 , and B_6 the values given in equations (14a) and (14b) gives .

$$for \quad r = \infty(w_{1,3} = w_{3,1})$$

$$P = \frac{\Im h}{a} \left\{ (1.804w_{1,1}^{2} + 18.04w_{1,3}^{2} + 16.24w_{3,3}^{2} + 7.217w_{2,2}^{2}) + \cos \frac{2\pi y}{a} (-0.0846w_{1,1}^{2} - 0.2858w_{1,3}^{2} - 0.0171w_{3,3}^{2} - 0.0189w_{3,2}^{2}) + 0.815w_{1,1}w_{1,3} + 0.708w_{1,1}w_{3,3} + 3.100w_{1,3}w_{3,3}) + \cos \frac{4\pi y}{a} (-0.0047w_{1,1}^{2} - 0.2467w_{1,3}^{2} - 0.0170w_{3,3}^{2} - 0.1538w_{2,2}^{2}) + 0.0284w_{1,1}w_{1,3} + 0.0165w_{1,1}w_{3,3} - 0.623w_{1,3}w_{3,3}) + \cos \frac{6\pi y}{a} (-0.0019w_{1,1}^{2} - 0.0419w_{1,3}^{2} - 0.2235w_{3,3}^{2} - 0.0075w_{2,3}^{8}) + 0.0148w_{1,1}w_{1,3} + 0.0148w_{1,1}w_{3,3} - 0.0814w_{1,3}w_{3,3}) \right\}$$

٩.

٠

;

:

Examination of beams which have severe shear buckles indicates that the maximum membrane stresses are likely to

occur at the center of the shear bay with the line of failure running at nearly 45^c to the flanges.

The stress at the center of the plate is obtained from equations (3), (7), (3), and (14) by letting x = y = a/2. This gives

for
$$r = \omega (w_{1,3} = w_{3,1})$$

 $(\sigma \frac{1}{x} = \sigma \frac{1}{y})_{x=a/2} = \frac{E}{a^2} (3.69w_{1,1}^2 + 50.22w_{1,3}^2 + 27.35w_{3,3}^2 + 2.278w_{2,2}^2)$
 $y=a/2$
 $-15.59w_{1,1}w_{1,3} + 4.187w_{1,1}w_{3,3} - 56.24w_{1,3}w_{3,3})$
 $(\tau_{xy})_{x=a/2} = \tau + \frac{E}{a^2}w_{2,2} (2.267w_{1,1} + 25.86w_{1,3} - 5.775w_{3,3})$
 (z_{6a})

and for
$$r = 1/4$$

$$(\sigma_{\mathbf{x}}^{1})_{\mathbf{x}=a/2} = \frac{E}{a^{2}} (2.586 w_{1,1}^{a} + 14.26 w_{1,3}^{a} + 11.58 w_{3,1}^{a} + 0.4213 w_{8,2}^{a}) + 23.15 w_{3,3}^{a} - 2.673 w_{1,1} w_{1,3} - 7.823 w_{1,1} w_{3,1} + 4.326 w_{1,1} w_{3,3} + 24.59 w_{1,3} w_{3,1} - 45.57 w_{1,3} w_{3,3} - 9.942 w_{3,1} w_{3,3}) (\sigma_{\mathbf{y}}^{1})_{\mathbf{x}=a/2} = \frac{E}{a^{2}} (1.597 w_{1,1}^{2} + 13.75 w_{1,3}^{2} + 2.186 w_{3,1}^{2} - 3.612 w_{2,2}^{2} + 14.09 w_{3,3}^{a}) (\sigma_{\mathbf{y}}^{1})_{\mathbf{x}=a/2} = \frac{E}{a^{2}} (1.597 w_{1,1}^{2} + 13.75 w_{1,3}^{2} + 2.186 w_{3,1}^{2} - 3.612 w_{2,2}^{2} + 14.09 w_{3,3}^{a}) (26) -2.663 w_{1,1} w_{1,3} - 8.003 w_{1,1} w_{3,1} + 4.176 w_{1,1} w_{3,3} + 24.48 w_{1,3} w_{3,1} - 47.15 w_{1,3} w_{3,3} - 9.056 w_{3,1} w_{3,3})$$

$$(T!_{xy})_{\substack{x=a/2\\y=a/2}} = T + \frac{E}{a^2} w_{2,2} (2.268 w_{1,1} + 12.90 w_{1,3} + 12.90 w_{3,1} - 5.776 w_{3,3})$$

The maximum and minimum principal stresses at the center of the plate may be obtained from equations (26a) and (36b) by the equations on page 19 of reference 9,

$$\sigma_{\text{min}}^{i} = \frac{\sigma_{x}^{i} + \sigma_{y}^{i}}{2} \pm \sqrt{\left(\frac{\sigma_{x}^{i} - \sigma_{y}^{i}}{2}\right)^{2} + \left(\tau_{xy}^{i}\right)^{2}}$$

$$\max_{\text{max}} \qquad (27)$$

$$\tan 2\alpha = 2 \frac{\tau_{xy}^{i}}{\sigma_{x}^{i} - \sigma_{y}^{i}}$$

where α is the angle between the x-axis and the direction of a principal stress.

Stress at Corner of Shear Bay

The stress at the corner of the shear bay must be mainly a shearing stress, since the principal deformation is a change in angle between the horizontal flange and the vertical struts. The boundary conditions of zero strain parallel to the flange and of strain parallel to the strut equal to the strain in the strut were only partially satisfied (see equations (9), (13), (14a), and (14b)); so small residual stresses in the x and y directions are left. A measure of the degree to which the boundary equations are satisfied is the smallness of these residuals in the case where $r = \alpha$. These are computed later in the paper and appear in the second and third columns of tables 3a and 3b.

The stress at the corner of the plate is obtained from equations (3), (7), (8), (14a), and (14b) by letting x = 0, y = a. This gives

for
$$r = \infty (w_{1,3} = w_{3,1})$$

 $(\sigma_{x}^{1} = \sigma_{y}^{1})_{x=0} = \frac{\Xi}{a^{2}} (0.157w_{1,1}^{2} + 1.94w_{1,3}^{2} + 2.14w_{3,3}^{2} + 0.832w_{2,2}^{2})_{x=0}$

 $-1.11v_{1,1}v_{1,3}-1.18v_{1,1}v_{3,3}-0.50v_{1,3}v_{3,3}$

 $+0.732w_{1,1}w_{2,2}-0.94w_{1,3}w_{2,2}+1.96w_{3,3}w_{2,2})$

 $(\tau_{xy})_{x=0} = \overline{\tau}$

≻ (28c)

.

Ň

and for
$$r = 1/4$$

 $(\sigma_{x}^{t})_{x=0}^{t} = \frac{\pi}{a^{2}}(-0.2889w_{1,1}^{a}-12.42w_{1,3}^{2}+9.593w_{3,1}^{a}-1.029w_{2,8}^{a})$
 $-2.103w_{3,3}^{a}-0.9318w_{1,1}w_{1,5}-0.3613w_{1,1}w_{3,1}$
 $-1.360w_{1,1}w_{3,5}+0.1806w_{1,3}w_{3,1}+6.160w_{1,3}w_{3,5}$
 $-7.493w_{3,1}w_{3,5}+0.7299w_{2,8}w_{1,1}+7.324w_{1,3}w_{2,8}$
 $-8.273w_{3,1}w_{2,8}+1.945w_{2,2}w_{3,3})$
 $(\sigma_{y}^{t})_{x=0}^{t} = \frac{\pi}{a^{2}}(-1.116w_{1,1}^{a}-9.080w_{1,3}^{a}-2.108w_{3,1}^{a}-4.572w_{2,8}^{a})$
 $-10.35w_{3,3}^{a}-1.5434w_{1,1}w_{1,3}-1.290w_{1,1}w_{3,1}$
 $-2.799w_{1,1}w_{3,3}-0.1693w_{1,3}w_{3,1}-1.067w_{1,3}w_{3,3}$
 $-4.157w_{3,1}w_{3,3}+0.7298w_{1,1}w_{2,8}-0.6991w_{1,3}w_{2,8}$
 $-0.2494w_{3,1}w_{2,8}+1.945w_{2,2}w_{3,3})$
 $(\tau_{xy}^{t})_{x=0}^{t} = \frac{\pi}{t}$

Depth of Buckle

The contour of the buckle in the shear bay is given by equation (6). The depth of the buckle at the center of the bay is obtained by setting x = a/2 and y = a/2. This gives

$$w_{center} = w_{1,1} - w_{1,3} - w_{3,1} + w_{3,3}$$
 (29)

:

ł

NUMERICAL SOLUTION

Deflection Coefficients

The deflection coefficients are obtained by solution of the simultaneous equations (17a), (17b). These equations were solved by a method of successive approximation, using the following steps:

1. Divide each of equations (17a) and (17b) by h³.

2. Estimate values of $w_{1,1}/h$, $w_{1,3}/h$, $w_{3,1}/h$, $w_{3,3}/h$, $\tau a^2/Eh^2$, corresponding to a given value of $w_{2,2}/h$.

3. Expand the right-hand side of each of equations (17a) and (17b) in a Taylor series in the neighborhood of the estimated values of $w_{1,1}/h$, $w_{1,3}/h$, $w_{3,1}/h$, $w_{3,3}/h$, and $\tau a^2/Eh^2$, omitting the square and higher order terms.

4. Solve the resulting linear equations for the difference between the chosen values of $w_{1,1}/h$, $w_{1,3}/h$, $w_{3,1}/h$, $w_{3,3}/h$, $\tau a^2/Eh^2$ and the improved values. (Crout's method, reference 10, was used for this.)

5. Repeat until the estimated error is less than 0.2 percent. The convergence was rapid; so one or two trials usually were sufficient to give an accurate answer.

The results of the computation were checked by substituting the answers in the original equations (17a) and (17b). The results are given in tables 1a and 1b for values of the shear load Q up to about seven times the critical value for buckling. The value of \overline{Y} was computed from τ by using equation (22); Q was computed from τ , $w_{1,1}$, $w_{1,3}$, $w_{3,1}$, $w_{3,3}$, and $w_{2,2}$ by using equations (21a) and (21b).

Median Fiber Stresses at Center of Shear Web

The median-fiber stresses at the center of the shear web were computed from equations (26a) and (26b) and tables la and 1b. The maximum and minimum principal stresses then were computed from equation (27). These stresses are given in tables 2a and 2b and are plotted against the shear load Q in

dimensionless form in figure 2. When $r = \infty$, the direction of the maximum principal stress forms an angle of 45° with the flanges for all loads; when r = 1/4, however, the angle is 45° at the buckling load and decreases to 39° S' as the load is increased to five times the buckling load.

As might be expected, the maximum principal stress (corresponding to tension along the wrinkle) continues to rise after buckling while the minimum principal stress (corresponding to compression across the wrinkle) remains nearly constart after buckling.

The reinforcement ratio r has only a small effect on the web stresses at the center of the shear bay. (See fig. 2.) The drop in tensile stress at the center when the reinforcement ratio changes from 1/4 to ∞ is only 7 percent at a shear load of 45 Eh³/a.

Median Fiber Stresses at Corner of Shear Web

The median-fiber stresses at the corner of the shear web were computed from equations (28a) and (28b) and tables la and lb. The maximum and minimum principal stresses then were computed from equation (27). These stresses are given in tables 3a and 3b and are plotted against the shear load Q in dimensionless form in figure 3. The direction of the maximum principal stress forms an angle of 45° with the flanges for all loads when $r = \infty$; when r = 1/4, however, the angle is 45° up to the buckling load and decreases to 41° 4' as the load is increased to five times the buckling load.

Comparison of figures 2 and 3 shows that the maximum tensile stress occurs at the center of the plate while the maximum compressive stress occurs in the corner.

The reinforcement ratio r has an appreciable effect on the stress in the corner. (See fig. 3.) The increase in compressive stress at the corner when the reinforcement ratio r changes from ∞ to 1/4 is 40 percent at a load Q = 45 Eh³/a.

Effective Width of the Sheet

The effective width of the sheet (corresponding to the width of unbuckled sheet which would give the same shear deformation as the actual buckled sheet) was computed from

equations (24a) and (24b) and tables la and lb. The ratio of the effective width to the actual width is given in tables 3a and 3b and is plotted in figure 4 against the shear deformation ratio $\tilde{\gamma} \frac{a^2}{h^2}$. Changing the strut area so that the reinforcement ratio r = 1/4 instead of ∞ causes a drop in effective width ratio from 0.88 to 0.81 for a shear deformation $\tilde{\gamma} = 140 \ h^2/a^2$.

Figure 4 shows that the effective width decreases slowly with increase in the shear deformation. In this connection it should be remembered that the present paper is limited to edge reinforcements which are rigid against bending in the plane of the web. It should not be assumed that the effective width will be as high as in figure 4 when the reinforcements allow bending in the plane of the web.

Bending Moment in Flange

The bending moments in the lower flange, due to the web stresses σ_v^1 acting normal to the flange, are given by equa-This equation does not take account of the fact tion (19a). that the web shear stress τ_{xy} contributes to the bending moment when the neutral axis of the flange does not coincide with the edge of the shear web. The bending moments along the flange y = 0 computed from equation (19a) using equations (8), (14a), (14b), and tables la and lb, are given in figure 5 for r = 1/4, $Q = 45.37 \text{Eh}^3/\text{a}$ and for $r = \infty$, $Q = 47.22 \text{Eh}^3/\text{a}$. The maximum moment occurs at the struts, x = 0, x = a. The distribution of moment is similar to that in a bean with clamped ends under a uniformly distributed load. Although the shear load Q is nearly the same in the two cases, the moments for $r = \infty$ are nearly twice the noments for r = 1/4; the decrease in cross-sectional area of the struts causes a marked decrease in flange bending moment.

Compressive Force in Strut

The compressive force in the strut is given by equation (12). The distribution of compressive force P along the strut was computed from equation (12) using equations (14a) and (14b) and tables la and lb. The results are plotted in figure 6 for r = 1/4, $Q = 45.37 \text{Eh}^3/a$ and for $r = \infty$, $Q = 47.22 \text{Eh}^3/a$. The variation in compressive force P along

the strut is 19 percent when r = 1/4 and only 8 percent when $r = \infty$. The maximum force occurs at the center of the strut, y = a/2.

The maximum force $P_{y=a/2}$ was computed for various loads. It is plotted against load in figure 7. For a given load Q on the beam, the force $P_{y=a/2}$ in the strut is about three times as great when $r = \infty$ as when r = 1/4. When r = 1/4 a considerable portion of the force holding the flanges apart seems to be carried by the sheet adjacent to the strut.

Shear Deformation of Beam

The shear deformation \overline{Y} of the beam and the shear load Q are given in dimensionless form in tables 1a and 1b. They are plotted against each other in figure 8 for r = 1/4 and $r = \infty$. The deformation when r = 1/4 is only about 9 percent greater than when $r = \infty$. The cross-sectional area of the strut apparently has only a minor effect on the stiffness of beams with buckled webs resisting shear when the strut spacing equals the beam depth and when the flanges are very stiff.

After buckling, the effective shear stiffness of the web is decreased about 8 percent for $r = \infty$ and about 12 percent for r = 1/4.

Comparison with "Tension Field" Theory

The most widely used concept in predicting the behavior of a shear web after buckling is that of the "tension field" originated by Wagner. Wagner (reference 2) postulated that the shear load carried by a thin sheet web after buckling is chiefly carried by tension in the direction of the sheet buckles. Improvements of Wagner's original theory to take account more adequately of the case of an incompletely doveloped tension field have been derived in references 11, 12, and 13.

Kuhn (references 11 and 12) has developed a semiempirical treatment for the action of shear webs in incomplete diagonal tension. Kuhn's results are plotted as curves C in figures 9, 10, and 11 for comparison with the present work. The agreement is excellent in the practical case where r = 1/4 except

ł.

for the stress in the corner of the buckle (curve B). In the extreme case where $r = \infty$, however, the agreement is not so good.

Langhaar (reference 13) takes account of roinforcements and assumes that a compressive stress equal to the critical shear stress acts perpendicular to the buckles. He neglects the effect of Poisson's ratio ($\mu = 0$). Langhaar's results are plotted as curves D in figures 9, 10, and 11 for comparison with the present work. The agreement is excellent for the stress at the center of the panel (curve A, fig. 9). It is not quite so good for the shear deformation (fig. 11). For the force in the strut (fig. 10), Langhaar's results are nearly twice as high as those of the present paper.

The preceding comparisons of Wagner's theory, as developed by Kuhn and by Langhaar, with the more complete analysis given in the present paper for the special case of a square plate, indicates that Wagner's theory as developed by Kuhn is in best agreement with the present paper in the practical case r = 1/4. Kuhn's theory is in especially good agreement for the force in the strut when r = 1/4.

National Bureau of Standards, Washington, D. C., July 1, 1944.

REFERENCES

- 1. Timoshenko, S.: Theory of Elastic Stability. McGraw-Hill Book Co., Inc., 1936.
- 2. Wagner, Herbert: Flat Sheet Metal Girders with Very Thin Metal Web.
 Part I - General Theories and Assumptions. NACA TM No. 604, 1931.
 Part II - Sheet Metal Girders with Spars Resistant to Bending - Oblique Uprights - Stiffness. NACA TM No. 605, 1935.
 Part III - Sheet Metal Girders with Spars Resistant to Bending - The Stress in Uprights - Diagonal Tension Fields. NACA TM No. 606, 1931.
- Kuhn, Paul: A Summary of Design Formulas for Beams Having Thin Webs in Diagonal Tension. NACA TN No. 469, 1933.

- 4. Schapitz, E.: The Twisting of Thin-Walled Stiffenel Circular Cylinders. NACA TM No. 878, 1938.
- 5. Moore, R. L.: An Investigation of the Effectiveness of Stiffeners of Shear-Resistent Plate-Girder Webs. NACA TN No. 862, 1942.
- Lahde, R. and Wagner, H.: Tests for the Determination of the Stress Condition in Tension Fields. NACA EM No. 809, 1936.
- 7. Seydel, E.: Über das Ausbeulen von rechteckigen isotropen öder orthogonal-anistropen Platten bei Schubbeenspruchung. Ing.-Archiv. vol. 4, 1933, pp. 169-191.
- Levy, Sanuel: Bending of Roctangular Platos with Largo Deflections. NACA Rop. No. 737, 1942. (Issued also as MACA TH No. 346, 1942.)
- 9. Timoshenko, S.: Theory of Elasticity. McGraw-Hill Book Co., Inc., 1934.
- 10. Grout, Prescott D.: A Short Mathed for Evaluating Determinants and Solving Systems of Linear Equations with Real or Corplex Coefficients. Trans. A.I.E.E., vol. 60, 1941.
- 11. Kuhn, Paul: Investigations of the Incompletely Developed Plane Diagonal-Tension Field. NACA Rep. No. 697, 1940.
- 12. Kuhn, Paul, and Chiarito, Patrick T.: The Strength of Plane Web Systems in Incomplete Diagonal Tension. EACA ARE, Aug. 1942.
- 13. Langhaar, H. L.: Theoretical and Experimental Investigations of Thin-Webbed Plate-Girder Beams. Trans. A.S.M.E., vol. 65, 1943, pp. 799-302.

Qa	- 8 a ²	<u>₩1,1</u>	<u>^w1,3</u>	₩ <u>3,1</u>	<mark>₩3•3</mark>	<u>₩2,2</u>	$\frac{\tilde{\tau}_{a^2}}{Eh^2}$
Eh3	h ²	h	h	h	h	h	
0 8.61 9.301 10.056 112.000 134.055 112.000 134.055 112.000 134.055 112.000 134.055 112.000 1142.055 112.000 1142.055 112.000 1142.000 1142.055 1142.000 1140.0000 1140.0000 1140.0000 1140.0000 1140.0000 1140.0000 1140.0000 1140.0000 1140.0000 1140.0000 1140.0000 1140.0000 1140.0000000000	0 8 8 4 15 5 5 8 9 8 8 4 12 4 15 8 9 12 12 15 8 12 15 8 12 15 8 12 15 8 12 15 8 12 15 8 12 15 8 12 15 8 12 15 8 12 15 8 12 15 15 15 15 15 15 15 15 15 15 15 15 15	0 0 +0.1587 +.2922 +.4764 .523 .6946 .814 .9166 1.2084 1.1208 1.1208 1.12084 1.5512 1.5512 1.5512 1.828	$\begin{array}{c} 0\\ 0\\ -0.0118\\0235\\04555\\04555\\053\\0695\\0857\\115\\129\\115\\129\\125\\234\\2291\\2291\\3208\\376\\376\\432\\432\\ \end{array}$	0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 0 0 0 0 0 0 0 0 0 0 0 0 0	$\begin{array}{c} 0 \\ 0 \\ -0 \\ .03902 \\ .13728 \\ .13728 \\ .13728 \\ .13728 \\ .334539 \\ .459934 \\ .459934 \\ .5704 \\ .5704 \\ .59991 \\ .13951 \\ .34539 \\ .459934 \\ .59991 \\ .13999 \\ .1309 \\ .1309 \\ .1$	0889901121211414141990605557 68331722366615503599920055557 999921011213446792663551773086 999921025557

Table 1a - Values of the deflection coefficients as a function of the apparent shearing deformation \vec{s} or of the shear load Q for r = -.

Table 1b - Values of the deflection coefficients as a function of the apparent shearing deformation \Im or of the shear load Q for r = 1/4.

<u>Qа</u> Еђ3	$-\frac{3}{h^2}$	<u>wi,1</u> h	<u>W1.3</u> . h	#3,1 h	<u>₩3,3</u> h	₩2,2 h	$\frac{{{{{\mathbb T}}a}^2}}{{{{\mathbb E}}h}^2}$
0 6 6 7 10 10 10 10 10 10 10 10 10 10	0 22345 22345 2279 3336 9412 579 3336 9412 579 698 89 989 447 567 247 567 247 567 247 567 247 567 247 568 89 447 567 247 568 80 447 568 80 447 579 568 80 447 579 568 80 447 579 568 80 579 567 20 579 568 80 579 568 80 579 568 80 579 568 80 579 568 80 579 568 80 579 567 29 568 80 579 579 568 80 579 568 80 579 568 80 579 568 80 579 568 80 579 568 80 579 578 80 569 579 578 80 579 578 80 579 578 80 579 578 578 579 578 578 579 578 578 579 578 578 579 578 579 578 578 579 579 578 579 578 579 578 579 578 579 578 579 579 579 579 579 579 579 579 579 579	$\begin{array}{c} 0\\ 0\\ + & .31922\\ + & .56647\\ + & .56647\\ + & .8962\\ + & .56647\\ + & .8962\\ + & .12327\\ + 1 & .2327\\ + 1 & .419\\ + 1 & .419\\ + 1 & .6875\\ + & .41.9754\\ + 2 & .9045\end{array}$	0 0 01178 02504 03845 0525 06709 082 097 113 128 144 175 208 240 272 303 365 365 396 458 488	0 0 01174 02472 03745 050326 076 088 101 113 125 151 169 2098 2298 267 286 324 343	$\begin{array}{c} 0 \\ + .00657 \\ + .01411 \\ + .021981 \\ + .03051 \\ + .03072 \\ + .049 \\ + .060 \\ + .071 \\ + .083 \\ + .095 \\ + .1251 \\ + .182 \\ + .214 \\ + .249 \\ + .358 \\ + .432 \\ + .472 \end{array}$	0 0479 1000 15000 2500 3500 3500 3500 4500 5000 5000 8000 8000 1.300 1.300 1.300 1.300 1.300 1.300 1.300 1.300 1.300 1.300 1.300 1.300 1.300 1.300 1.300 1.300 1.500 350 350 350 350 350 350 350 350 350 350 350 300 350 300 300 300 300 350 300 1.300 1.300 1.600	0

I.

¢

Ť

١.

<u>Qa</u> En ³	$\frac{\sigma'_{x} a^{2}}{Eh^{2}}$	$\frac{\sigma_{y}^{\prime} a^{2}}{Eh^{2}}$	$\frac{z_{xy}^{2}}{Eh^{2}}$	<u> </u>	σ _{max} a ² Eh ²	æ
8.8.90.0161002555670440622229 10011234556670440622229	0 .1287 .45553 1.349 1.3701 2.523 3.476 3.476 3.476 4.2536 6.7124 10.4233 18.0157 2.428 7.0.428 32.361 38.428 32.361 38.44 4.4292 32.361 38.441 .338 444 .338 .4129 58.811	0 .1287 .4555 .9363 1.3491 2.5276 3.44763 3.44763 3.44763 5.44763 5.44763 5.44763 5.44764 2.2924 1.4.20127 2.4433 1.28924 3.22.3618 3.22.924 3.22.3618 3.22.924 3.22.3618 3.22.924 3.22.3618 3.22.924 3.22.9263 3.2.924 3.2.925 3.2.924 3.2.925 3.2.925 3.2.924 3.2.925 3.5.925 3.5.955 3.5.9555 3.5.95555 3.5.95555555555	- 88.350 88.350 90.1686 - 10.112342221 - 11234257 - 10.11234257 - 1167037059 - 335949 - 335949 - 33594 - 552 	- 88.946 88.89.99900599333667002 - 999900599333667002 - 1000099333667002	8.61 8.96 9.81 11.04 12.036 14.708 14.708 14.708 14.708 14.708 14.708 14.708 14.708 14.708 14.708 14.708 14.708 14.708 15.77 53.100 72.08 394.46 82.746 107.26 120.84	45° "" "" "" "" "" "" "" "" "" "" "" "" ""

Table 2a - Median-Fiber Stress at Center, r ≈∞ Maximum and Minimum Principal Stresses Direction of Principal Stresses

Table 2b - Median-Fiber Stress at Center, r = 1/4 Maximum and Minimum Principal Stresses Direction of Principal Stresses

Qa Eh ³	Eh ²	σ <u>v</u> a ² Eh ²	$\frac{\tau'_{xv}a^2}{Eh^2}$	<u> </u>	$\frac{\sigma_{\max}^{\prime}a^{2}}{Eh^{2}}$	~
8.6730 9.0.28657 9.0.28657 10.28557 10.28557 10.28557 10.28557 10.28557 10.28557 10.28557 10.28557 10.28557 10.28557 10.28557 10.28557 10.28557 10.285577 10.285577 10.285577 10.275777 10.275777 10.275777 10.275777 10.275777 10.275777 10.275777 10.27577777777777777777777777777777777777	0.142962267590896353454 ++++22234568147093454 ++++22234568147093454 +++22234568147093454	0 + + + + + + + + + + + + + + + + + + +	$\begin{array}{c} - & 8.61 \\ - & 8.75 \\ - & 9.73 \\ - & 10.300 \\ - & 11.300 \\ - & 11.855 \\ - & 12.639 \\ - & 13.399 \\ - & 14.100 \\ - & 14.509 \\ - & 16.693 \\ - & 222.58 \\ - & 224.34 \\ - & 292.655 \\ - & 232.655 \\ - & 38.82 \\ - & 232.655 \\ - & 28.855 \\ - $		$\begin{array}{c} + 8.61 \\ + 8.831 \\ + 9.0.617 \\ + 112.873 \\ + 112.873 \\ + 115.617 \\ + 124.45.617 \\ + 125.617 \\ + 128.026 \\ + 244.026 \\ + 224.026 \\ + 237.22 \\ + 332.120 \\ + 237.22 \\ + 337.22 \\ + 402 \\ + 541.6 \\ + 766 \\ + 766 \\ + 784 \\ + 766 \\ + 784 \\ + 784 \\ + 766 \\ + 784 $	450000 54628 54628 54628 54628 515 54528 515 515 515 515 515 515 515 515 515 51

~

÷

Æ

5

ça Eh3	^r ía ² Eh ²	$\frac{{\sigma'_{\rm v}}^{\rm a^2}}{{ m Eh}^2}$	$\frac{\tau'_{xy}a^2}{Eh^2}$	$\frac{\sigma_{\max}^{\prime}a^{2}}{Eh^{2}}$	<u>$\sigma_{min}^{a^2}$</u> Eh ²	×	Effective width Ratio
8.61 8.830 10.551 10.551 112.00 111.2.2556 111.2.2556 111.2.2556 111.2.2556 111.2.2556 111.2.2556 111.2.2556 111.2.2556 111.2.2556 112.255	$\begin{array}{c} 0\\ .0004\\ .0009\\ .000\\ .001\\008\\017\\025\\037\\0502\\0599\\1411\\207\\270\\341\\425\\512\\512\\512\\512\\512\\512\\839\end{array}$	0 .00 .00 .00 .00 .00 .00 .00 .00 .00	- 8.9.9.2 - 8.9.9.2 - 10.1.2.368.3 - 10.1.2.366.6 - 12.3.6 - 12.3.6 - 12.3.6 - 12.3.6 - 12.3.6 - 12.3.6 - 12.3.6 - 12.3.5 - 12.6 - 12.3.5 - 12.6 - 12.3.5 - 12.6 - 12.5 - 12	8.61 8.83 9.35 10.12 10.73 11.23 13.66 14.61 17.50 226.45 30.78 35.476 46.77 53.14 60.182 75.86	$\begin{array}{c} - & 8.61 \\ - & 8.83 \\ - & 9.35 \\ -10.12 \\ -10.73 \\ -11.23 \\ -12.35 \\ -13.70 \\ -14.60 \\ -17.61 \\ -19.12 \\ -26.73 \\ -35.20 \\ -35.99 \\ -447.63 \\ -54.16 \\ -69.28 \\ -77.54 \end{array}$	45° 11 11 11 11 11 11 11 11 11 11 11 11 11	1 •998 •994 •988 •984 •980 •972 •964 •972 •964 •979 •949 •949 •949 •942 •936 •913 •926 •913 •904 •890 •883 •890 •8853 •876 •872 •8872 •869 •869

Table 3a - Median Fiber Stresses at Corner of Shear Web, $r = \infty$

Table 3b - Median Fiber Stresses at Corner of Shear Web, r = 1/4

.

Qa Eh3	Eh ²	σya² Eh ²	$\frac{\tau'_{xy}a^2}{Eh^2}$	<u> </u>	<u>o^rmax^{a'2}</u> Eh ²	б	Sffective width Ratio
8.6130 9.9.216 9.9.2021 10.522 0.2520 0.252 0.252 0.2520 0.2520 0.2520 0.2520 0.2520 0.2520 0.25200 000 0.2520000000000	0 	0 18 18 371 4.591 1.1.9349 1.1.937 1.1.937 1.1.937 1.1.937 1.1.8888 192 18888 192	- 8.61 - 8.74 - 9.75 -10.40 -12.91 -12.91 -13.88 -15.86 -18.605 -26.33 -29.73 -37.57 -51.07 -56.32	- 8.61 - 8.77 - 9.28 - 10.80 - 10.86 - 11.83 - 12.38 - 13.97 - 15.20 - 16.247 - 17.82 - 20.77 - 24.07 - 27.74 - 31.81 - 36.30 - 462.528 - 528 - 529 - 528 -	+ 87.4 + 90.5.20 + 105.20 + 1115.20 + 1115.2	45°°°°°°°°°°°°°°°°°°°°°°°°°°°°°°°°°°°°	9987899901112599521124 9987899901112599521124

í

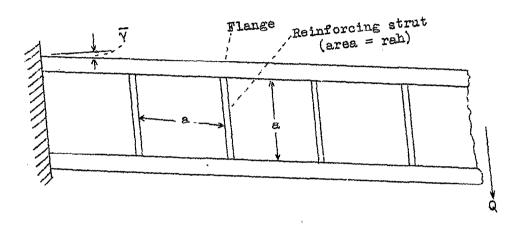
4

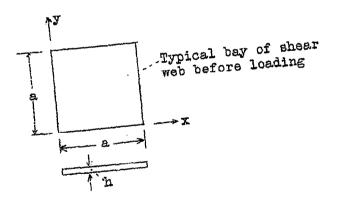
3

ţ

.

NACA TN No. 962





<u>،</u> -

7

Figure 1.- Beam under shearing force Q and typical bay of shear web.



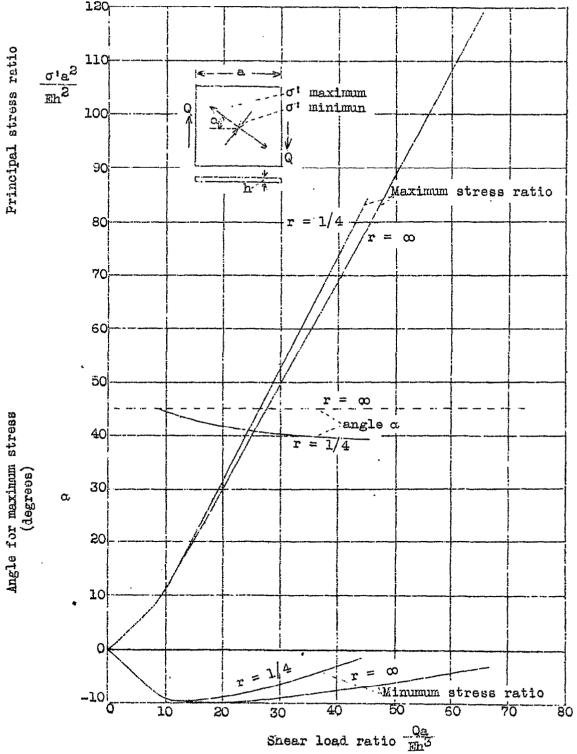
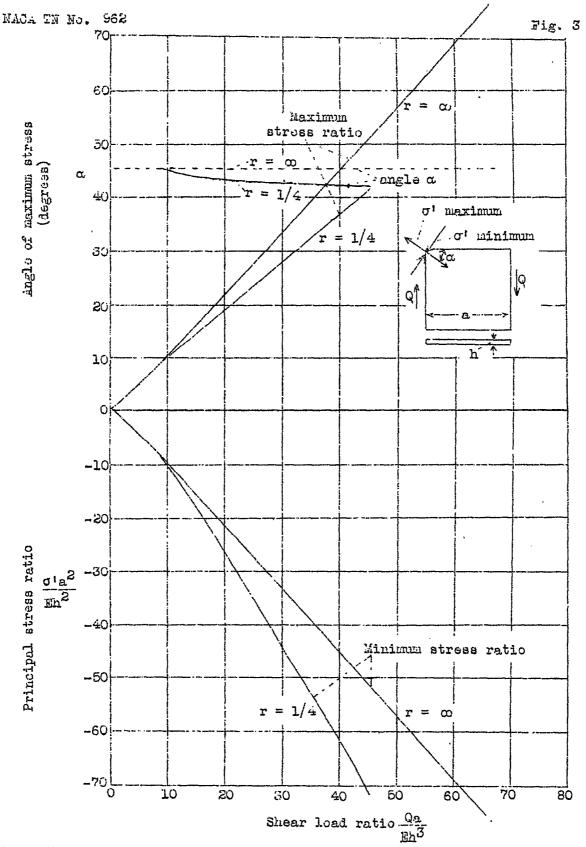
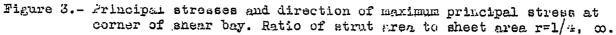
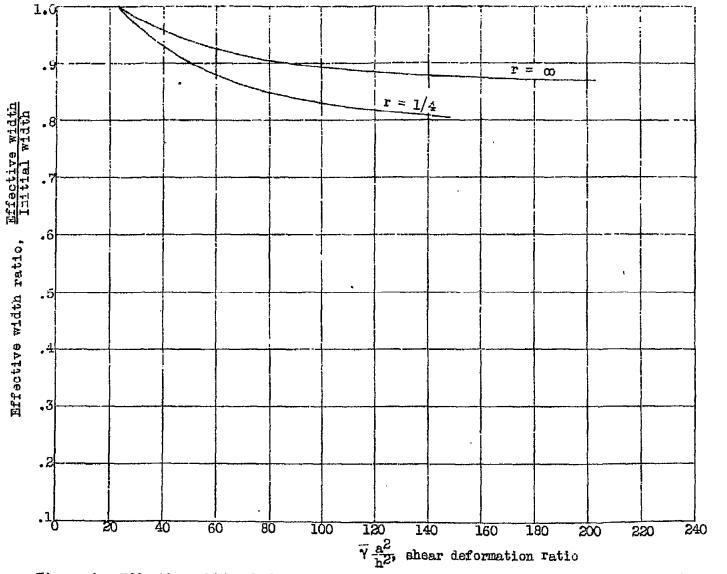
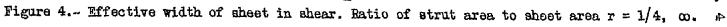


Figure 2.- Principal median fiber stresses and direction of maximum principal stress at center of shear bay. Ratio of strut area to sheat area r = 1/4, ∞ ,









Ъ18.

Fig. 5

ŧ.

ı.

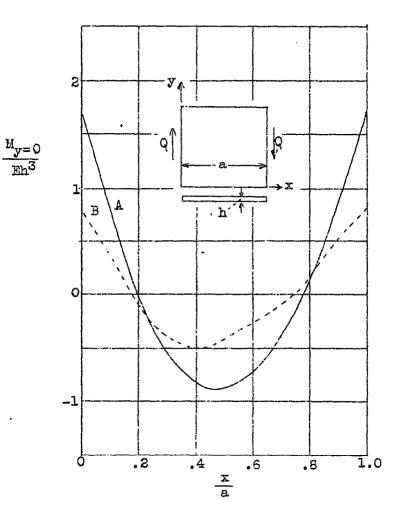


Figure 5.- Moment distribution in bottom flange (y = 0). Curve A, $r = \infty$, Q = 47.22 Eh³/a, Curve B, r = 1/4, Q = 45.37 Eh³/a.

s.

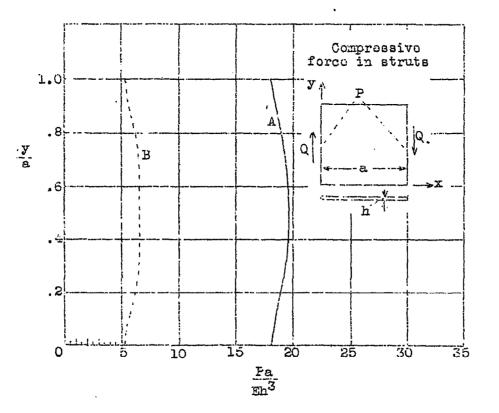


Figure 5.- Force distribution in struts at x = 0, a. Curve A, $r = \infty$, $Q = 47.22 \text{ Hh}^3/\text{e}$, Curve B, r = 1/4, Q = 45.37MH³/a, r = ratio of strut cross-sectional area to sheet crosssectional area.

-10 Py=a, compressive force in strut at y=a/2 y, 30 aPy=a QŢ ĮQ. Eh³ ⇒x 20 h $\mathbf{r} = \infty$ 10 ~ r = 1/-10 40 20 30 70 0 50 60 Qa Eh³

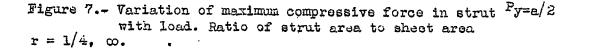


Fig. 7

\$

Fig. 8

i

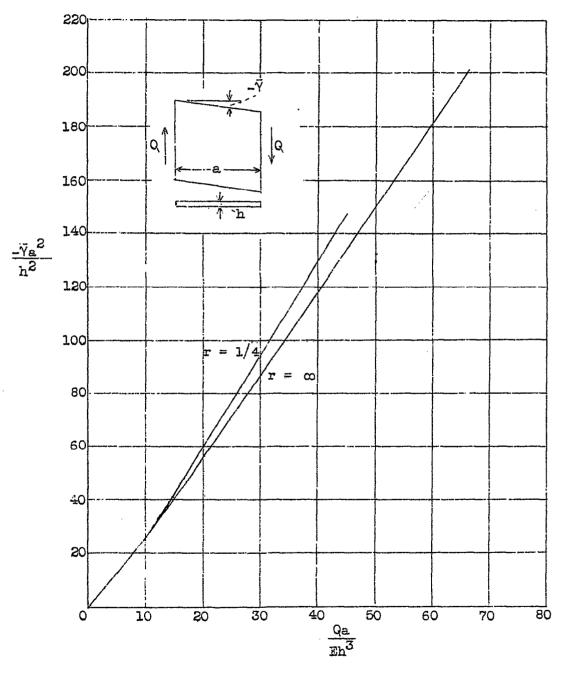


Figure 8.- Shear deformation of beam for ratio of strut area to web area r = 1/4, ∞ .

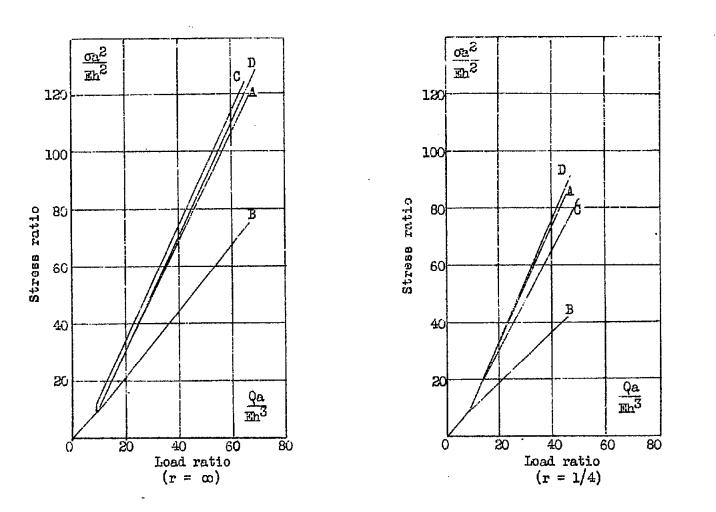


Figure 9.- Comparison of maximum median fiber stresses. σ , r = ratio of strut cross-sectional areato sheet cross-sectional area; curve A, conter of plate, present paper; curve B, cornerof plate, present paper; curve C, all points in plate, references 11 and 12; curve D, all points inplate, reference 13.

BTE 9

NACA TH No. 962

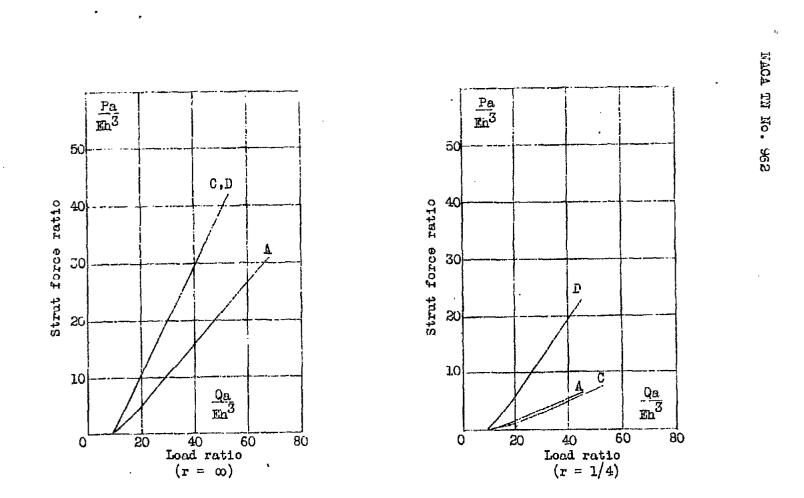


Figure 10.- Comparison of compressive force P in strut, r = ratio of strut cross-sectional area to sheet cross-sectional area; curve A, midpoint of strut, present paper; curve C, anywhere in strut, references 11 and 12; curve C, anywhere in strut, reference 13.

Ūī •Bī£

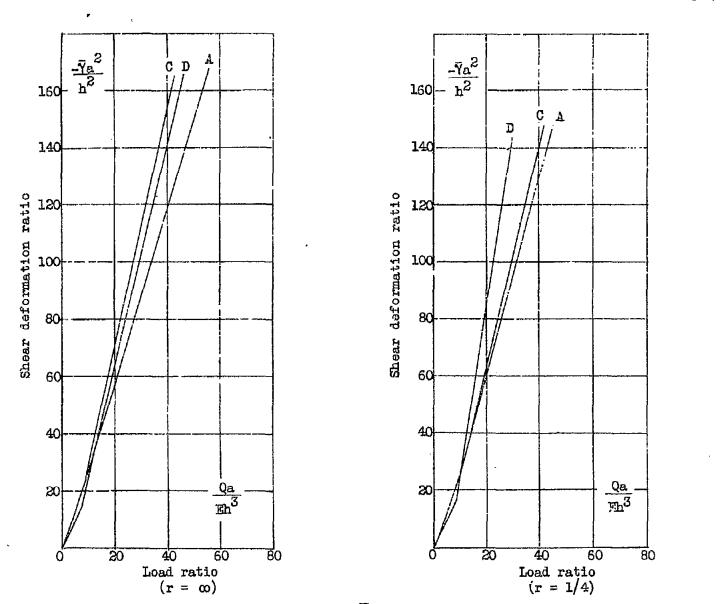


Figure 11.- Comparison of shear deformation $-\overline{Y}$, r = ratio of strut cross-sectional area to sheet cross-sectional area; curve A, present paper; curve C, references 11 and 12; curve D, reference 13.

F12. 11

MACA IN No. 963

یں۔ 1915ء ا