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# RESEARCH MEMORANDUM

VELOCITY DISTRIBUTIONS ON TWO-DIMENSIONAL

WING-DUCT INLETS BY CONFORMAL MAPPING

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#### SUMMARY

The conformal mapping method of the Cartesian mapping function is applied to the determination of the velocity distribution on arbitrary two-dimensional duct-inlet shapes such as are used in wing installations. An idealized form of the actual wing-duct inlet is analyzed. The effects of leading-edge stagger, inlet-velocity ratio, and section lift coefficient on the velocity distribution are included in the analysis. Numerical examples are given and, in part, compared with experimental data.

### INTRODUCTION

Inlet contours for wing-duct installations, such as those used to conduct cooling air to engines, are generally designed on a more empirical basis than airfoil sections because the geometry of a wing-duct inlet, hence the determination of its velocity distribution, is more complex than that of an airfoil section. By means of the conformal mapping method of reference 1, however, the ideal incompressible velocity distribution over two-dimensional wing-duct inlets for arbitrary lift coefficients can be calculated with about the same labor as in the corresponding calculation for an isolated airfoil.

This method is herein applied to an arbitrary two-dimensional wing-duct inlet section. The theory is illustrated by numerical examples, which are, in part, compared with experimental data.



#### ANALYSIS

### Symbols

The more important symbols used in the paper are listed here. All velocities are expressed as fractions of the free-stream velocity; that is, the free-stream velocity is taken as unity.

- c, section lift coefficient
- c chord of duct-inlet section
- d horizontal distance between leading edges of duct inlet
- h vertical distance between leading edges of duct inlet
- r stagger ratio in ζ-plane
- s stagger ratio d/h in z-plane
- v velocity on surface of duct inlet
- v<sub>Dm</sub> velocity infinitely far inside duct
- v<sub>n</sub> velocity at duct inlet
- z plane of duct inlet section (x + iy)
- $\zeta$  plane of chord lines  $(\xi + i\eta)$
- p plane of circle

#### The Conformal Transformation

The actual two-dimensional wing-duct configuration of figure 1(a) is replaced by the contour shown in figure 1(b). The two changes made in the original configuration are: (a) removal of the internal flow resistance and (b) replacement of the streamlines A'B' and C'D' by the parallel straight rigid boundaries AB and CD. Change (a) results in a flow field of constant total pressure and change (b) in a simply connected flow field. The analysis is thereby considerably simplified. Both effects associated with the replaced features, namely, variable inlet-velocity ratio and angle of attack, respectively, can be adequately represented in the flow function for the simplified configuration. For conventional wing-duct installations, the region of interest at the inlet, as regards velocity distribution,

is sufficiently far from the region in which changes (a) and (b) were made that their influence on the required velocity distributions is negligible. (See ILLUSTRATIVE EXAMPLES.)

The simplified duct-inlet contour in the z-plane is now conformally mapped onto the staggered semi-infinite parallel straight lines, QAB and PCD, in the  $\zeta$ -plane (fig. 1(b)). This mapping is accomplished by the Cartesian mapping function (CMF), defined as the vector distance  $z - \zeta$  between conformally corresponding points in the z- and  $\zeta$ -planes (reference 1); thus

$$z - \zeta = (x - \xi) + i(y - \eta)$$

$$= \Delta x + i\Delta y$$
(1)

The calculation of the CMF is carried out by considering it as a function of the central angle  $\,\phi\,$  of the p-plane circle into which the  $\zeta$ -plane contour can be conformally mapped by a known transformation. Inasmuch as z -  $\zeta$  is regular on and outside of the z- or  $\zeta$ -plane contours, by the conformal transformation from  $\,\zeta\,$  to  $\,p\,$  it is also regular on and outside of the p-plane circle. The real and imaginary parts of the CMF on the circle itself are therefore related by

$$\Delta x(\varphi) = -\frac{1}{2\pi} \int_0^{2\pi} \Delta y(\varphi^i) \cot \frac{\varphi^i - \varphi}{2} d\varphi^i \qquad (2)$$

$$\Delta y(\varphi) = \frac{1}{2\pi} \int_0^{2\pi} \Delta x(\dot{\varphi}') \cot \frac{\varphi' - \dot{\varphi}}{2} d\varphi'$$
 (3)

The conformal transformation of the  $\zeta$ -plane, staggered semi-infinite parallel lines, into the p-plane circle is carried out in two steps. In the first step a Schwarz-Christoffel transformation takes the  $\zeta$ -plane polygon into the real axis of a t-plane such that the upper-half t-plane corresponds to the  $\zeta$ -plane. With the correspondence of boundary points indicated in figure 2, this transformation is (reference 2):

$$\frac{d\xi}{dt} = C_1 \frac{(t - u_2) (t - u_4)}{t} \tag{4}$$

$$\zeta = C_1 \left[ \frac{t^2}{2} - (u_2 + u_4) t + u_2 u_4 \log_e t \right] + C_2$$
 (5)

The six constants given by  $u_2$ ,  $u_4$  (real), and  $C_1$ ,  $C_2$  (complex) are determined for the orientation and the scale indicated in figure 2 by the six conditions:

- (a) C1 real (staggered lines horizontal)
- (b) a = 1, scale factor in  $\zeta$ -plane
- (c) r equals desired stagger in  $\zeta$ -plane,  $\zeta(u_2) = r + \tau i$
- (d) u2 = -1, scale factor in t-plane
- (e) upper leading edge in  $\zeta$ -plane at point  $(\tau, 0)$  or  $\zeta(u_4) = \tau$  (two conditions)

The constant T is inserted in condition (e) in order to locate the leading edge of the upper inlet section tangent to the y axis. By use of the foregoing conditions, equation (5) reduces to

$$\zeta = \frac{1}{\pi} \left( \frac{t}{m} - 1 \right) \left\lceil \frac{m}{2} \left( \frac{t}{m} - 1 \right) + 1 \right\rceil - \frac{1}{\pi} \log_{e} \frac{t}{m} + \tau$$
 (6)

The quantity  $m \equiv u_4$  is the following function of the stagger ratio r:

$$\pi r = \log_e m + \frac{1}{2} \left( m - \frac{1}{m} \right) \tag{7}$$

Equation (7) is plotted in figure 3.

The second step of the desired transformation from  $\zeta$  to p consists in mapping the upper-half t-plane onto the region outside of the p-plane unit circle by a bilinear transformation, here taken as

$$t = i \left( \frac{p+1}{p-1} \right) . \tag{8}$$

The correspondence of points for equation (8) is indicated in figure 2. The use of other bilinear transformations will be discussed in ILLUSTRATIVE EXAMPLES.

Equations (1), (6), and (8) constitute the conformal transformation from the region around the duct-inlet section in the physical z-plane to the region outside the unit circle p-plane. These equations, with  $p=e^{i\phi}$ , give for conformally corresponding points on the boundaries

$$t = \cot \frac{\varphi}{2} \tag{9}$$

$$x = \xi + \Delta x$$

$$x = \frac{1}{\pi} \left( \frac{1}{m} \cot \frac{\varphi}{2} - 1 \right) \left[ \frac{m}{2} \left( \frac{1}{m} \cot \frac{\varphi}{2} - 1 \right) + 1 \right] - \frac{1}{\pi} \log_{e} \frac{1}{m} \left| \cot \frac{\varphi}{2} \right| + \Delta x(\varphi) + \tau$$
(10)

$$y = \eta + \Delta y$$

$$y = \Delta y(\phi) \qquad 0 < \phi < \pi \text{ upper-duct inlet section}$$

$$y = \Delta y(\phi) - 1 \qquad \pi < \phi < 2\pi \text{ lower-duct inlet section}$$
(11)

The leading-edge points of the upper-duct and lower-duct inlet sections may be defined as the upstream points of tangency of normals from the "chord" lines OA and RC with the duct-inlet contours (fig. 1(b)). These points may be found as functions of  $\phi$  by minimizing x with respect to  $\phi$  in equation (10). The resulting condition is

$$\frac{d\Delta x}{d\varphi} = \frac{\left(\cot\frac{\varphi}{2} - m\right)\left(\cot\frac{\varphi}{2} + 1\right)}{\pi \, m \, \sin\,\varphi} \tag{12}$$

## Velocity Distribution

The velocity distribution on the duct-inlet section is given by

$$v = \left| \frac{dW}{dz} \right| \tag{13}$$

in which the complex potential W is

$$W = \zeta + \frac{A}{\pi} t + \frac{B}{\pi} \log_e t$$
 (14)

The term  $\zeta$  represents a uniform flow velocity to the right, of unit magnitude in the  $\zeta$ -plane, and gives a free-stream velocity of unity in the physical plane. The term  $\frac{A}{\pi}$  t represents a uniform flow in the t-plane and corresponds to a circulatory flow around the duct inlet in the physical plane. This term gives the effect of angle of attack on the physical duct-inlet section, although the geometric angle of attack of the section analyzed must remain zero because of its semi-infinite extent. The term  $\frac{B}{\pi}\log_{e}$  t represents the flow due to a source at the origin in the t-plane and gives the desired inlet velocity into the duct in the physical plane.

The quantitative effect of the parameters A and B in the physical plane is determined by evaluation of the complex velocity

$$\frac{dW}{dz} = \left(1 + \frac{A}{\pi} \frac{dt}{d\zeta} + \frac{B}{\pi t} \frac{dt}{d\zeta}\right) \frac{d\zeta}{dz}$$
 (15)

where, by equation (6),

$$\frac{dt}{d\zeta} = \frac{\pi mt}{(t - m)(t + 1)} \tag{16}$$

and, because  $z - \zeta$  is regular on and outside of the p-plane circle,

$$z - \zeta = \sum_{0}^{\infty} \frac{c_n}{p^n}$$
 (17)

$$\frac{dz}{d\zeta} = 1 - \frac{dp}{d\zeta} \sum_{0}^{\infty} \frac{nc_n}{p^{n+1}}$$

$$\frac{dz}{d\zeta} = 1 + \frac{2i}{(t-i)^2} \frac{\pi mt}{(t-m)(t+1)} \sum_{0}^{\infty} \frac{nc_n}{p^{n+1}}$$
(18)

Infinitely far inside the duct in the physical plane, the correspondence of points is:  $z=\alpha$ ,  $\zeta=\alpha$  by equation (17), t=0 by equation (6), and p=-1 by equation (8). Hence, at this point,  $\frac{dz}{d\zeta}=1$  by equation (18),  $\frac{dt}{d\zeta}=0$  and  $\frac{1}{t}\frac{dt}{d\zeta}=-\pi$  by equation (16); and equation (15) gives for the velocity  $\mathbf{v}_{D\infty}$  infinitely far inside the duct

$$v_{Dec} = 1 - B \tag{19}$$

The velocity distribution on the inner wall of the duct-inlet section becomes almost constant a short distance behind the leading edge. (See ILLUSTRATIVE EXAMPLES.) The inlet velocity  $v_n$  is defined as this asymptotic value. The inlet velocity  $v_n$  will be different from  $v_{D\infty}$  if the height at the inlet is different from the height (unity) infinitely far inside the duct. Infinitely far upstream of the duct-inlet section the correspondence of points is:  $z=-\infty$ ,  $\zeta=-\infty$ ,  $t=i\infty$ , and p=1, and consequently  $\frac{dz}{d\zeta}=1$ ,  $\frac{dt}{d\zeta}=\frac{1}{t}\frac{dt}{d\zeta}=0$ . This result holds infinitely far outside the duct in any direction. Hence, the free-stream velocity is, by equation (15), unity.

The quantity A may be evaluated either as a function of the stagnation-point locations on the duct inlet or as a function of a suitably defined lift coefficient. In terms of the stagnation points, given by  $\frac{dW}{dz} = 0$  in equation (15), and with equations (16) and (9),

$$A = \frac{(m-1) \cot \frac{\varphi_{st}}{2} - \cot^2 \frac{\varphi_{st}}{2} + m (1 - B)}{m \cot \frac{\varphi_{st}}{2}}$$
(20)

$$\cot \frac{\varphi_{st}}{2} = \frac{-[1+m(A-1)] \pm \sqrt{[1+m(A-1)]^2 + 4m(1-B)}}{2}$$
 (21)

For a given A (and B) equation (21) is a quadratic equation for the two stagnation-point locations. When quantity A is alternatively regarded as a function of lift coefficient  $c_l$ , the section lift coefficient is defined in terms of circulation and chord by the well-known isolated airfoil relation

$$c_{l} = \frac{2\Gamma}{c}.$$
 (22)

The chord c is defined as the over-all length of the wing duct-inlet section in the free-stream direction (OE in fig. 1(b)), and the circulation  $\Gamma$ , as the line integral of the velocity over the circuit CFCHKMAEC around the wing-duct installation. This circulation can be evaluated as the sum of the potential difference over the lower surface  $\Phi_{\text{G}}$  -  $\Phi_{\text{C}}$ , and the potential difference over the upper surface  $\Phi_{\text{E}}$  -  $\Phi_{\text{H}}$ . The difference of potential over the paths GH and EC is neglected because the velocity is here approximately perpendicular to the path. Hence, by equation (14)

$$\Phi_{\rm E} - \Phi_{\rm H} = \xi_{\rm E} - \xi_{\rm H} + \frac{A}{\pi} (t_{\rm E} - t_{\rm H}) + \frac{B}{\pi} \log_{\rm e} \frac{t_{\rm E}}{t_{\rm H}}$$

$$\Phi_{G} - \Phi_{C} = \xi_{G} - \xi_{C} + \frac{A}{\pi} (t_{G} - t_{C}) + \frac{B}{\pi} \log_{e} \frac{t_{G}}{t_{C}}$$

and

$$\Gamma = (\Phi_{E} - \Phi_{H}) + (\Phi_{G} - \Phi_{C})$$

$$\Gamma = (\xi_{E} - \xi_{C}) - (\xi_{H} - \xi_{G}) + \frac{A}{\pi} \left[ (t_{E} - t_{C}) - (t_{H} - t_{G}) \right] + \frac{B}{\pi} \log_{e} \left( \frac{t_{E} t_{G}}{t_{H} t_{C}} \right)$$
(23)

Finally, solving for A and expressing  $\Gamma$  in terms of  $c_l$  by equation (22) with  $c = x_E$ ,

$$A = \frac{\pi \left[ \frac{c_{l}}{2} x_{E} - (\xi_{E} - \xi_{C}) + (\xi_{H} - \xi_{G}) \right] - B \log_{\theta} \left( \frac{t_{E}t_{G}}{t_{H}t_{C}} \right)}{(t_{E} - t_{C}) - (t_{H} - t_{G})}$$
(24)

The quantities x,  $\xi$ , and t at the various points indicated in equation (24) are given in terms of the corresponding central angle  $\varphi$  by equations (9) and (10). The various  $\varphi$  values are known when the conformal transformation of the duct inlet has been carried out.

For a CMF  $\Delta x(\phi)$ ,  $\Delta y(\phi)$ , stagger constant m, and the constants A and B corresponding to the lift coefficient and the inlet-velocity ratio, the velocity distribution on the duct-inlet contour is given by the absolute magnitude of dW/dz on the boundary. On the boundary,  $p = e^{i\phi}$ ,

$$\frac{dz}{d\xi} = 1 + \frac{d(z - \xi)}{d\xi}$$

$$\frac{dz}{d\xi} = 1 + \frac{d(\Delta x + i\Delta y)}{d\varphi} \frac{d\varphi}{dt} \frac{dt}{d\xi}$$
(25)
s (9), (16), and (25) into (15) yields for

Substitution of equations (9), (16), and (25) into (15) yields for the velocity distribution on the duct-inlet section

$$\mathbf{v} = \frac{\left(\cot\frac{\varphi}{2} - \mathbf{m}\right)\left(\cot\frac{\varphi}{2} + 1\right) + \mathbf{m}\mathbf{A}\cot\frac{\varphi}{2} + \mathbf{m}\mathbf{B}}{\pi \, \mathbf{m} \, \sin\, \varphi \sqrt{\left[\frac{\left(\cot\frac{\varphi}{2} - \mathbf{m}\right)\left(\cot\frac{\varphi}{2} + 1\right)}{\pi \, \mathbf{m} \, \sin\varphi} - \frac{\mathrm{d}\Delta x}{\mathrm{d}\, \varphi}\right]^{2} + \left(\frac{\mathrm{d}\Delta y}{\mathrm{d}\varphi}\right)^{2}}}$$
(26)

Procedure for Calculation of CMF

The calculation of the CMF  $\Delta x(\phi)$ ,  $\Delta y(\phi)$ , and stagger constant m for a given duct-inlet section may be carried out by a process of successive approximations similar to that of reference 1. The steps are outlined as follows:

- 1. The duct-inlet section is drawn in normal form (fig. l(b)). Point 0 is the origin and the scale is such that the normal distance between the chord lines OA and RC is unity. The stagger s = d/h of the duct inlet is, in general, different from the stagger r of the chord lines.
- 2. A set of abscissas  $x(\phi)$  are calculated for a standard set of values of  $\phi$  by equation (10). The  $\Delta x(\phi)$  and  $\tau$  may be that of a previous example or, at worst, equal to zero. The value of m may be taken from figure 3 for r=s.
- 3. The ordinates y of the duct-inlet contour corresponding to the abscissas x of step 2 are measured. The function  $\Delta y(\phi)$  is thereby determined (equation (11)).
- 4. The function  $\Delta x(\phi)$  is calculated from  $\Delta y(\phi)$  by equation (2).
- 5. The functions  $\Delta x(\phi)$  of step 4,  $\Delta y(\phi)$  of step 3, and m of step 2 constitute by equations (10) and (11) a duct-inlet section of which the difference in abscissas between the leading edges is, in general, other than that specified. The constant m is therefore adjusted to make this difference equal to the specified value. To this end equation (12) (corresponding to the values  $\phi_1$  and  $\phi_2$  for the two extremities) and the equation for the difference d in the leading-edge abscissas

$$x (m, \varphi_1) - x (m, \varphi_2) = d$$
 (27)

obtained from equation (10), can be solved simultaneously for  $\phi_1$ ,  $\phi_2$ , and m. A more convenient procedure is one of iteration. Initial values  $\phi_1$  and  $\phi_2$  for minimum x are graphically obtained by plotting equation (10) in the necessary regions. A value of m is then obtained from equation (27). With this value of m, values of  $\phi_1$  and  $\phi_2$  are again graphically found for minimum x by equation (10). The process is continued until  $\phi_1$ ,  $\phi_2$ , and m do not change appreciably in successive calculations. Finally, a constant  $\tau$  is so chosen that  $x(\phi_1) = 0$ . The derived inlet section is now in normal form.

6. The values of m and T derived in step 5 and  $\Delta x(\tau)$  and  $\Delta y(\tau)$  of steps 4 and 3 yield a shape by equations (10) and (11), which can be compared with the given one. If the agreement is not sufficiently close, steps 3 to 5 are repeated.

7. The velocity distribution is obtained by substitution of the final m and the derivatives  $\frac{d\Delta x}{d\phi}$  and  $\frac{d\Delta y}{d\phi}$  of the final CMF into equation (26). The value of B is chosen to produce the desired inlet velocity (the velocity given by equation (26) on the inside walls of the duct-inlet section). The value of A is chosen to locate the stagnation points in the desired manner (equation (21)) or for a desired nominal lift coefficient (equation (24)).

The inverse problem, namely, the calculation of the duct-inlet section to produce a prescribed velocity distribution, may be treated by the methods given in references 1 and 3.

# ILLUSTRATIVE EXAMPLES

As a first application of the theory, the symmetrical wing-duct installation (m=1.0) on which pressure distributions were measured in reference 4 (shape 9), was analyzed. The installation is shown in figure 4 and the ordinates are listed in table 1. The trailing-edge portions were actually flaps by which the inlet velocity was varied. The scale used for the calculation was such that the distance between trailing edges was unity, as assumed in the theory. An evenly spaced set of 48  $\phi$ -values was taken of which only 24 were actually used because of the symmetry. Of these 24 values, 21 were included in the front 8 percent of the chord. This portion of the duct inlet was therefore the portion effectively analyzed. The leading-edge portion is plotted in figure 5 to a scale such that the vertical distance between the leading edges, the entrance height h, is unity.

The CMF obtained after four approximations (which produced coincidence of the specified shape and the derived shape) is listed in table 2 and plotted in figure 6. In the first two approximations the airfoil was drawn to an abscissa scale of 25 inches for the chord and had an ordinate scale four times the abscissa scale. The last two approximations were made for the airfoil drawn to a scale such that the chord length was 100 inches; the ordinate scale was the same as the abscissa scale. The values of  $\Delta x$  were computed, for the most part, by the method of numerical evaluation of conjugate functions developed in appendix C of reference 5. Near 0° and 180°, because of the rapid variation of  $\Delta y(\phi)$  in these regions (fig. 6),  $\Delta x$  was obtained by plotting the integrand of equation (2) and graphical integration. The values of the CMF graphically obtained are indicated in table 2. The velocity distributions, also listed in table 2, were calculated for inlet-velocity ratios  $v_n$  of 0, 0.5, and 1.0 and for nominal lift coefficients of 0, 0.3, 0.6, 0.9, and are shown

in figure 7. The derivatives of the CMF used in calculating the velocity distribution were obtained by graphical measurement from the CMF.

The velocity distribution for  $c_l$  = 0 and  $v_n$  = 0.5 satisfactorily checked that experimentally obtained in reference 4 for  $c_l$  = 0 and  $v_n$  = 0.473 (fig. 7(c)). The reason for the discrepancy between theoretical and experimental inlet-velocity ratios at which the velocity distributions agreed is not clear. Possible reasons are the changes in downstream shape required by the analysis and a difference in the method of specification of inlet-velocity ratio. The theoretical inlet velocity  $v_n$  has been defined as the constant value approached by the velocity on the wall of the duct at a short distance behind the leading edge. The experimental determination of the inlet-velocity ratio in reference 4 was not made entirely clear.

The velocity distributions for the  $c_l$  values 0.3 and 0.6 were also compared with the experimental data of reference 6 obtained for the same duct-inlet section at various angles of attack with Mach numbers of 0.20. The comparison (given in figs. 7(c) and 7(d)) indicates the validity of the theoretical analysis, particularly of the derivation of the nominal section lift coefficient  $c_l$ .

The feature of the velocity distribution shown in figure 7 that should be particularly noted is the closeness to the leading edge (well within the 8-percent of the chord length that was studied) at which the greatest changes in velocity distribution occur as a result of a change in operating conditions  $\mathbf{v}_n$  or  $\mathbf{c}_l$ . This fact justifies and requires the analysis of a region very close to the inlet, that is, the concentration of the chosen set of the  $\omega$ -points close to the inlet.

In order to illustrate the use of the theory for the staggered case, m  $\neq$  1.0, the CMF  $\Delta x(\phi)$  and  $\Delta y(\phi)$  for the symmetrical inlet was used with the m-values 1.5 and 2.0. These shapes and velocities are shown in figures 8 to 11 and are given in tables 3 and 4. In the graphs of the duct inlets, the ordinates have been so adjusted that the upper and lower leading edges are 0.5 and -0.5, respectively. Although the derived shapes are different from the original unstaggered one, the effect of the stagger is to reduce the velocity peaks for positive lift coefficients.

When a more highly staggered inlet was derived for m=3.0 by the foregoing method, the upper contour of the resulting inlet was found to be excessively thick. The points in the physical plane

corresponding to  $\Delta x(\phi)$ ,  $\Delta y(\phi)$ , and m=3.0 were therefore rearanged by using the same  $\Delta x$  and  $\Delta y$ , regarded, however, as functions of  $\theta$ , with  $\theta$  related to  $\phi$  by the bilinear transformation (see appendix B of reference 5)

$$p = \frac{p' + \frac{n-1}{n+1}}{\frac{n-1}{n+1} p' + 1}$$
 (28)

where

$$p = e^{i\phi}, p' = e^{i\theta}$$
 (29)

and the two circles. The choice n=1.5 produced the shape shown in figure 12. The ordinates are listed in table 5. It should be noted that the use of an auxiliary bilinear transformation (equation (28), for example) provides a very flexible and convenient method of distributing a given number of mapping points in the optimum manner. The auxiliary bilinear transformation may also be used to smooth out a sharply peaked function of  $\phi$  to make its conjugate more easily calculable.

#### CONFORMAL MAPPING OF LEADING-EDGE REGIONS

The requirement that the velocity distribution need be accurately known only near the leading edges permitted the great simplification in the mapping consisting of replacement of the doubly connected region by a simply connected region. The modification of the 'contour shape far behind the leading edge did not appreciably alter the velocity distribution at the leading edges. Corresponding simplifications can be effected in other problems involving conformal mapping of aerodynamic shapes where only the leading-edge region is of interest.

Thus, for example, the leading-edge region of an isolated airfoil can be regarded as joining a semi-infinite shape as indicated in figure 13. The mapping of such a contour into a circle is quite simple. The leading-edge contour, z-plane, is mapped onto a semi-infinite chord line,  $\zeta$ -plane, by the CMF

$$z - \zeta = \Delta x + i\Delta y = (x - \xi) + i(y - \eta)$$
 (30)

The semi-infinite chord line is mapped onto an infinite straight line, t-plane, by

$$\zeta = t^2 \tag{31}$$

and, in turn, the t-plane contour is mapped onto a unit circle by a bilinear transformation, such as

$$t = i \left( \frac{p+1}{p-1} \right) \tag{32}$$

On the unit circle  $p=e^{i\phi}$ , equations (30) to (32) give for the coordinates x and y of the leading edge contour in the physical plane

$$x = \cot^2 \frac{\varphi}{2} + \Delta x(\varphi) \tag{33}$$

$$y = \Delta y(\varphi) \tag{34}$$

The mapping of the leading-edge contour by equations (33) and (34) involves little more than the calculation of conjugates.

The velocity distribution is obtained from the complex potential

$$W = \zeta + At \tag{35}$$

in which the term  $\zeta$  represents the uniform free-stream flow and the term At a circulatory flow around the leading edge. On the leading-edge contour the velocity distribution |dW/dz| becomes

$$v = \frac{\left(1 + \frac{A}{2} \tan \frac{\varphi}{2}\right) \cot \frac{\varphi}{2} \csc^{2} \frac{\varphi}{2}}{\sqrt{\left(\cot \frac{\varphi}{2} \csc^{2} \frac{\varphi}{2} - \frac{d\Delta x}{d\varphi}\right)^{2} + \left(\frac{d\Delta y}{d\varphi}\right)^{2}}}$$
(36)

A similar development can be made for a cascade of leading-edge regions, which bears the same relation to a cascade of airfoils as the leading-edge region just treated bears to the isolated airfoil.

# SAW-TOOTH FUNCTION AS INITIAL APPROXIMATION

In the mapping of semi-infinite contours, it may be required, or it may be simpler, to consider a contour for which the thickness at infinity is finite, as indicated in figure 13. The ordinate function  $\Delta y(\phi)$  will in this case be discontinuous at the value of  $\phi$  corresponding to the point at infinity on the physical-plane contour. The calculation of the CMF for such a contour will be simplified if the Cartesian mapping function  $\Delta x + i\Delta y$  is considered

as the sum of two component Cartesian mapping functions  $\Delta_1x + i\Delta_1y$  and  $\Delta_2x + i\Delta_2y$ , of which  $\Delta_1x + i\Delta_1y$  is analytically known and represents a contour with the same thickness at infinity.

Thus, if the thickness at infinity of the contour in the physical plane is T, the "first harmonic" saw-tooth function (fig. 14)

$$\Delta_{1}y(\varphi) = \frac{T}{\pi} \left( \frac{\pi}{2} - \frac{\varphi}{2} \right) \tag{37}$$

will yield a shape with this thickness. The function  $\Delta_{\underline{l}}x(\varphi)$  conjugate to  $\Delta_{\underline{l}}y(\varphi)$  may be simply obtained from the integral relation for the conjugate derivative (equation (C3) of reference 5)

$$\frac{d\Delta \mathbf{x}(\varphi)}{d\varphi} = -\frac{1}{4\pi} \int_{0}^{2\pi} \frac{\Delta \mathbf{y}(\varphi') - \Delta \mathbf{y}(\varphi)}{\sin^2 \frac{\varphi' - \varphi}{2}} d\varphi' \tag{38}$$

Substitution of equation (37) into (38) and integration (using integration by parts) yields

$$\frac{\mathrm{d}\Delta_1 x}{\mathrm{d}\varphi} = \frac{\mathrm{T}}{2\pi} \cot \frac{\varphi}{2} \tag{39}$$

which by integration gives for  $\Delta_1 x$ 

$$\Delta_{1}x = \frac{T}{\pi} \log_{e} \sin \frac{\varphi}{2}$$
 (40)

The ordinate function derivative is evidently

$$\frac{\mathrm{d}\Delta_{\mathbf{l}}\mathbf{y}}{\mathrm{d}\,\boldsymbol{\varphi}} = -\frac{\mathbf{T}}{2\pi} \tag{41}$$

The CMF for a "second harmonic" saw-tooth (fig. 14) corresponding to a duct-inlet section with thickness T (of each component contour) at infinity may be obtained from that of the first harmonic saw-tooth function by replacing  $\phi/2$  in equations (37), (39), and (40) by  $\phi$  and by doubling the derivatives. Thus, for the second harmonic saw-tooth function

$$\Delta_{1}y = \frac{T}{\pi} \left( \frac{\pi}{2} - \varphi \right) \qquad 0 < \varphi < \pi$$

$$\Delta_{1}y = \frac{T}{\pi} \left( \frac{3\pi}{2} - \varphi \right) \qquad \pi < \varphi < 2\pi$$

$$(42)$$

$$\frac{\mathrm{d}\Delta_{1}y}{\mathrm{d}\varphi} = -\frac{\mathrm{T}}{\pi} \tag{43}$$

$$\Delta_1 x = \frac{T}{\pi} \log_e \sin \varphi \qquad (44)$$

$$\frac{\mathrm{d}\Delta_1 x}{\mathrm{d}\varphi} = \frac{\mathrm{T}}{\pi} \cot \varphi \tag{45}$$

The duct-inlet shapes corresponding to the second harmonic saw-tooth CMF have been calculated by equations (10) and (11) with m=1.0 (no stagger) and for T=0.1, 0.2, and 0.3. The contours are shown in figure 15. For these shapes the velocity infinitely far inside the duct is, by equations (43), (45), and (26) with  $\varphi=\pi$ 

$$v_{D\infty} = \frac{1 - B}{1 - T} \tag{46}$$

which, when compared with equation (19), shows the effect of narrowing the duct at infinity.

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Cleveland, Ohio.

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TABLE 1 - ORDINATES OF SYMMETRICAL DUCT INLET [reference 4, shape 9]

7			
i			Ordinate of inner
1		surface (measured)	surface (measured
1	chord	from center line	from center line
1	from	of channel)	of channel)
İ	leading	(percent chord)	(percent chord)
1	edge)	·	
	0	3.345	3.34
	.25	3.660	3.07
	.5	3.835	3.05
	.75	3.076	3.05
	1.25	4.228	3.07
1	2.5	4.745	3.13
į	5	5.532	3.25
	7.5	6.137	3.36
ļ	10	6.652	3.50
	15	7.467	3.78
	20	8.093	4.08
	25	8.593	
-	30	8.965	4.57
	35	9.224	
	40	9.379	4.90
	45	9.435	
	50	9.391	5.10
	55	9.240	
-	60	8.966	4.94
	65	8.510	
	70	7.804	4.27
	75	6.878	
	80	5.816	2.54
	85	4.679	
	90	3.522	1.55
	95	2.387	
	100	1.314	1.31
_			

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TABLE 2.- ORDINATES AND VELOCITY DISTRIBUTIONS FOR SYMMETRICAL DUCT INLET WITH s = 0 AND m = 1.0

 $[\tau = 0; \phi_{\rm H} = 75.00^{\circ}; \phi_{\rm G} = 285.00^{\circ}; \phi_{\rm E} = 6.882^{\circ}; \phi_{\rm C} = 353.12^{\circ}; h = 2.4860]$ 

Ψ/-		(y/h) +			Velocity, v (vn = 0; B = 1.00000)				
(deg)	ж/h	0.2011 (ordinate)	Δπ	ΔУ			0.6	0.9	
(408)		(Ordinate)			c <sub>1</sub> = 0	0.58494		1.75483	
<u> </u>					<u> </u>	0.00404	1.10000	1.70400	
			Upper duct						
0 x 7.5	∞ 20.85.40	0.2011	a-2.8592	0		1.0000	1.0000	1.0000	
1 2	12.3540 2.8117	.8662 1.2098	a-5.1796 a-1.2595	1.6534	1.0697		1.1517	1.1927	
3	1.0887	9259	5144		1.1944		1.3524	1.4427	
4	.5162	.7713	2265		1.2238		1.6075	1.7993	
5	.2490	.6695	1306	1.1644	1.2535	1.5025	1.7514	2.0003	
6	.1225	.6121	0546		1.3460		1.9982	2.3243	
7	.0524	.5708	0115		1.4799		2.3337	2.7606	
8 9	.0221	.5410 .5165	.0400 .0699	7839	1.6354	-	2.7400	3.2923 4.0902	
10	.0017	.4996	.1060	.7420	1.8827 2.0239	2.6185 2.9324	3.3544 3.8408	4.7493	
lii	.0033	4858	.1307	.7078			3.5951	4.5053	
12	.0136	.4766	.1623	. 6849			2,6161	3.3213	
13	.0259	.4713	.1879	.6716	.7651	1.2754	1.7857	2.2960	
14	.0471	.4690	.2268	.6659	.4713	.8305	1.1898	1.5490	
15	.0713	.4682	.2655	.6640	.2991	.5609	.8227	1.0845	
16 17	.1034	.4675 .4690	.3168 .3685	.6621 .6659	.1961	.3947 .2853	.5933	.7920 .5948	
18	.1842	4705	.4379	.6697	.1305	.2069	.4401	. 4491	
19	2363	4736	.5131	.6773	.0543	.1480	.2416	3353	
20	.3067	4766	.6195	.6849	.0324	.0319	.1740	.2447	
21	.3912	.4789	.7400	.6906	.0172	.0677	.1182	.1687	
22	.5227	. 4843	.9389	.7040	.0069	.0374	.0679	.0984	
23 24	.7401	.4950 .2011	al.2595	.7306	.0017	.0167	.0318	.0468	
24	_ ∞	<u></u>	a3.0449	0	10	0	10	0	
			Lower duct	inlet				· · · · · · · · · · · · · · · · · · ·	
24	00	-0.2011	a5.0449	0	0	0	0	0	
25 26	0.7401	4950 4843	al.2595	7306 7040	.0017	.0134	.0284	.0434	
27	.3912	4789	9389	6906	.0069	.0237	.0542	.0847	
28	3067	4766	6195	6849	0324	.0384	1091	1799	
29	.2363	4736	.5131	6773	.0543	.0393	1329	.2266	
30	.1842	4705	. 4379	6697	.0858	.0354	.1565	.2776	
31	.1385	4690	-3685	6659	.1305	.0243	.1791	.3339	
32	.1034	4675 - 4692	.3168	6621	.1961	.0026	.2012	.3999	
33 34	.0713	4682 4690	.2655 .2268	6640 6659	.2991	.0373	.2246 .2472	.4864	
35	.0259	4713	1879	6716	7651	.2548	.2555	7659	
36	.0136	4766	.1623		1.2056	.5004	.2048	.9100	
37	.0033	4858	.1307	7078	1.7745	.8642	.0461	9563	
38	.0017	4996	.1060			1.1155	.2070	.7014	
39	.0041	5165	.0699			1.1468	.4109	.3249	
40 41	.0221	5410 5708	.0400 0115		1.6354	1.0831	.5308	.0214	
42	.1225	6121	0546			1.0198	6937	.1982	
43	.2490	6695	1306	-1.1644	I	1.0046	.7557	.5068	
44	.5162	7713	2265	-1.4174			8402	.6484	
45	1.0887	9259	5144	-1.8018		1.0554	.9165	.7775	
46 47	2.8117	-1.2098	-1.2595 a-5.1796	-2.5076		1.0817	.9914	.9012	
L <u>*′</u>	12.3540	8662	1 -0.1180	-1.6534	T-00A	<u> </u>	.9877	.9467	

<sup>a</sup>Obtained by graphical integration.

TABLE 2. - Concluded

ORDINATES AND VELOCITY DISTRIBUTIONS FOR SYMMETRICAL DUCT INLET - Concluded

	Velocity, v									
Φ,	(v.	= 0.5:	B = -0.30		$(v_n = 1.0; B = -1.55000)$					
(deg)	$e_1 = 0$		0.6	0.9	0	0.3	0.6	0.9		
	A = 0		1.16989			0.58494		1.75483		
	·		*					20.0100		
0 x 7.5	Upper duct inlet section 0 x 7.5 1.0000 1.0000 1.0000 1.0000 1.0000 1.0000 1.0000									
ľ	1.0633	1.1043	1.1454	1.1863	1.0580		1.1400	1.1810		
2	1.1437	1.2340	1.3242	1.4144	1.1201	1.2104	1.3006	1.3909		
3	1.1288	1.2678	1.4067	1.5457	1.0739		1.3518	1.4908		
4 5	1.1018		1.4854 1.5508	1.6773 1.7997	.9998	1.1916	1.3834	1.5752		
6	1.0252	1.3513	1.6774	2.0035	.8852 .7571	1.1341	1.3830	1.6319 1.7354		
7	.9800	1.4069	1.8338	2.2607	.5622	.9891	1.4160	1.8429		
8	.8782	1.4305	1.9828	2,5351	.2454		1.3500	1.9023		
9	.7151	1.4509	2.1868	2.9226	.2607	.4751	1.2110	1.9468		
10 11	.3686 .1212	1.2770 .7891	2.1855 1.6993	3.0940 2.6096	1.0150	.1065 .7952	.8020	1.7104		
12	.4691	.2361	.9414	1.6467	1.8687	1.1635	.1151	1.0253 .2470		
13	:6167	.1064	.4039	.9142	1.7716	1.2613	7510	2407		
14	.6405	.2813	.0780	4372	1.5697	1.2105	.8512	. 4920		
15 16	.6314	.3696	.1078	.1540	.1.4090	1.1472	.8854	.6236		
17	.6148	.4601	.3053	.0250 .1505	1.2378	1.1051	.9065 .9282	.7079 .7734		
18.	.6086	.4875	.3664	2453	1.1889		9467	.8256		
19	.6008	.5071	.4135	.3198	1.1483		9610	.8673		
20	.5948	.5240	. 4532	.3825	1.1190	1.0482	.9774	.9067		
21 22	.5859 .5435	.5354	.4849	4344	1.0900	1.0395	.9890	.9385		
23	.5432	.5130 .5281	.4825 .5131	.4519 .4980	1.0034	.9729 .98 <b>3</b> 5	.9424 .9684	.9119 .9534		
24	1.3891	1.3891	1.3891	1.3891						
			Lower di	uct inle	t section	on				
24	1.3891	1.3891	1.3891	1.3891	2.5500	2,5500	2.5500	2.5500		
25	.5432	.5582	.5732	-5883	.9985	1.0135	1.0286	1.0436		
26	.5435	.5740	.6045	.6350	1.0034	1.0340	1.0645	1.0950		
27 28	.5859 .5948	.6365 .6656	.6870 .7363	.7375 .8071	1.0900	1.1407 1.1897	1.1910 1.2605	1.2416 1.3313		
29	.600B	6944	.7880	8817	1.1483	1.2419	1.3355	1.4292		
30	.6086	.7297	.8508	<b>.9</b> 719	1.1889	1.3100	1.4311	1.5523		
31	.6148	.7696	.9244	1.0792	1.2378	1.3926	1.5473	1.7021		
32 33	.6210 .6314	.8196 .8932	1.0182	1.2169 1.4168	1.3038	1.5024	1.7010	1.8997		
34	6405	.9998	1.3590	1.7183	1.5697		1.9326 2.2882	2.1944 2.6474		
35	.6167	1.1271	1.6374	2.1477	1.7717		2.7923	3.3026		
36	.4691	1.1743	1.8795	2.5848	1.8687	2.5739	3.2792	3.9844		
37 · 38	.1212	1.0314 .5399	1.9417	2.8520	1.7055		3.5261	4.4364		
39	.7151	.0208	.7567	2.3568 1.4925	2607	1.9234 .9966	2.8319 1.7325	3.7403 2.4683		
40	.8782	.3259	.2264	7786	2454	3069	.8592	1.4114		
41	.9800	.5531	.1262	.3007	.5622	.1353	.2916	.7185		
42	1.0252	.6991	.3730	.0468	.7571	. 4310	.1049	.2213		
43	1.0529	.8040 .9100	.5551 .7182	.3062 .5264	.8852 .9998	.6363 .8080	.3874	.1385		
1 45	1.1288	9898	8509	7119	1.0739	.9349	.6162 .7960	.4243 .6570		
46	1.1437	1.0535	.9632	8730	1.1201	1.0299	9396	8494		
47	1.0633	1.0223	.9813	.9403	1.0580	1.0170	.9760	9350		
	NATIONAL ADVISORY									

TABLE 3.- ORDINATES AND VELOCITY DISTRIBUTIONS FOR NONSYMMETRICAL DUCT INLET WITH s = 0.132 AND m = 1.5

 $[\tau = -0.0341; \phi_H = 109^\circ; \phi_G = 289.31^\circ; \phi_E = 6.51^\circ; \phi_C = 353.12^\circ; h = 2.6667]$ 

<del></del>				<del></del>				
		(y/h)+	Velocity, v (v <sub>n</sub> = 0.5; B = -0.38907)					
•	x/h	0.1650				<b>'</b> )		
(deg)	2/11	(ordinate)	c <sub>1</sub> = 0	0.3	0.6	0.9		
			A = 0.01518	0.38901	0.76285	1.13668		
		Upper	duct inlet se	ction				
0 x 7.5	60	0.1650	1.0000	1.0000	1.0000	1,0000		
1	6.3926	.7850	1,0751	1.1162	1.1571	1.1985		
2	1.2849	1.1053	1.2487	1.3510	1.4533	1.5556		
3	. 4257	.8407	1,2072	1.3709	1.5346	1.6983		
4	.1693	.6965	1.1023	1.3316	1.5608	1.7900		
5	.0559	.6016	.9625	1.2689	1.5753	1.8817		
6	.0159	.5481	.7539	1.1475	1.5712	1.9349		
7	0 0057	.5096	.4219	.8743	1.3267	1.7790		
8	.0057	.4818	.0418	.4934	.9451	1.3968		
	.0134	.4590	.2796	.1409	.5614	.9820		
10 11	.0295	.4433	.5018	.1377	.2264	.5905		
12	.0455	.4304	.6440	.3338	.0236	.2866		
13	.066.7 .0876	.4219	.7169	.4593	.2018	•0558		
14	.1153	.4169 .4147	.7479	.5357	.3235	.1112		
15	.1133	.4140	• <b>729</b> 5	.5609	.3922	.2235		
16	.1804	.4133	.6994 .6740	.5654	.4315	.2975		
17	.2184	.4133	.6561	•5663	• 4586	.3509		
18	.2655	.4161	.6406	.5687	.4813	.3939		
19	.3182	.4190	6252	.5700 .5693	.4995 .5134	. 4290		
20	.3875	.4219	.6128	.5697	.5267	.4576 .4837		
21	,4697	42 40	•5125 •5985	.5673	.5361	.5049		
22	.5953	. 4290	.5515	.5324	.5133	.4942		
23	.8010	.4390	.5469	.5374	5279	.5183		
24	00	.1650	1.3891	1.3891	1.3891	1.3891		
		Lower	duct inlet se	ction				
24	80	-0.2100	1.3891	1.3891	1.3891	1,3891		
25	0.8062	4840	•5398	.5495	.5592	.5689		
26	.6058	4740	•5373	.5571	.5769	.5967		
27	. 4855	<b>4</b> 690	•5775	.6105	.6436	.6766		
28	. 4088	4669	•5843	.6309	.6775	.7241		
29	.3452	4640	.5887	.6507	.7127	.7748		
30	.2985	4611	.5954	.6760	.7567	.8374		
31 32	.2576	4597	.6010	.7046	.8081	.9116		
33	.2264 .1978	4583 4590	.6073	.7406	.8740	1.0073		
34	.1764	4590 4597	.6193 .6322	.7954	.9714	1.1474		
35	.1574	4619		.8733	1.1143	1.3554		
36	.1462	4669	.615? .4874	.9536	1.2915 1.3887	1.6294		
37	.1362	4754	2085	.9380 .7658	1.3231	1.8394 1.8804		
38	.1334	- 4883	.1844	.7848	.9540	1.5232		
39	.1325	5040	.5214	.0187	4840	.9866		
40	.1435	5268	.7311	.3237	.0837	.4911		
41	.1614	5546	8833	5481	2128	.1224		
42	.2081	5931	.9699	.7018	4336	.1655		
43	.2903	6466	1.0282	.8159	.6036	.3913		
44	. 4663	7415	1.1043	.9347	.7651	.5955		
45	.8257	8857	1.1660	1.0375	.9091	.7806		
46	1.8893	-1.1503	1.2070	1.1202	1.0334	.9466		
47	7.6068	8300	1.0715	1.0330	.9945	.9560		
				······································	ATIONAL AD			

TABLE 4.- ORDINATES AND VELOCITY DISTRIBUTIONS FOR NONSYMMETRICAL DUCT INLET WITH  $\pm$  = 0.215 AND m = 2.0

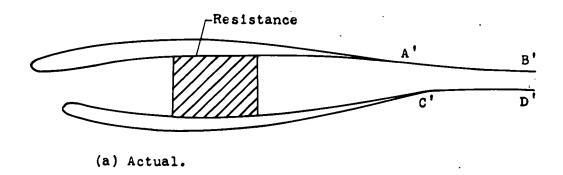
 $[\tau = 0.0374; \ \phi_{R} = 114.98^{\circ}; \ \phi_{G} = 289.12^{\circ}; \ \phi_{E} = 6.19^{\circ}; \ \phi_{C} = 353.12^{\circ}; \ h = 2.8525]$ 

	<del></del>					<del></del>		
_ [		(y/h) + (y = 0.5; R = -0.38907)						
Ψ	x/h	0.1206		$(v_n = 0.5; B = -0.38907)$				
(deg)	,	(ordinate)	c <sub>1</sub> = 0	0.3	0.6	0.9 0.85259		
<del></del>			A = 0.03038	0,30445	0,57852	0,83289		
<u> </u>		Upper	duct inlet so	ection				
0 x 7.5	<b>60</b>	0.1206	1,0000	1.0000	1.0000	1.0000		
1	3.6137	7002	1,0655	1.1068	1.1481	1.1895		
2	.6084	.9997	1.3818	1.5022	1,6226	1.7430		
3	.1545	.7522	1.2524	1.4466	1.6408	1.8350		
4	.0444	.6175	.9326	1.1822	1.4317	1.6813		
5	.0019	.5288	.6065	.9191	1.2316	1.5442		
6	.0009	.4798	.1917	.5156	8396	1.1636		
7	.0091	.4427	.1527	.1446	.4419	.7393		
8 9	.0302 .0489	.4167 .3954	.3887	.1260 .3185	.1366 .0860	.3993 .1466		
10	.0489	.3954	.5511 .6559	.4525	.0860	.0458		
l ii	.0943	3687	.7284	.4525	.3711	.1925		
12	.1194	3607	7656	.6112	4567	.3023		
13	.1435	.3560	7797	.6474	.5151	.3827		
14	.1731	3540	.7553	.6461	.5370	.4278		
15	.2037	.3534	.7217	.6324	.5430	4537		
16	.2399	.3527	.6929	.6194	.5461	.4726		
17	.2778	.3540	.6717	.6111	.5506	.4900		
18	.3240	.3554	.6531	.6036	.5541	.5046		
19	.3751	.3580	.6350	.5954	.5558	.5162		
20	.4417	.3607	.6203	.5895	.5587	.5279		
21	.5200	.3627	.6039	.5814	.5588	.5363		
22	.6390 .8325	.3674	.5550 .5485	.5412 .5416	.5273	.5134 .5277		
23 24		.3767	1.5891	1.3891	1.3891	1,3891		
103	∞		1,0001	1.0001	1.0052	1 2,0002		
		Lower	duct inlet s	ection				
24	000	-0.2300	1.3891	1.3891	1.3891	1.3891		
25	0.8399	4861	.5384	.5455	.5526	.5598		
26	.6537	4768	.5345	.5491	.5638	.5784		
27	.5423	4721	.5738	.5983	.6228	.6474		
28	.4716	4701	.5798	.6145	.6492	.6839		
29	.4130	4675	.5836	.6299	.6763	.7226		
30	.3702	4648	.5900	.6504	.7108	.7713		
31	.3328	4635 4621	.5957	.6735	.7512 .8033	.8289		
32 33	2782	4628	6165	7490	.8815	1.0140		
34	2587	4635	6328	.8140	9953	1.1765		
35	2414	4655	.6221	8744	1,1266	1.3789		
36	.2311	4701	.5057	8361	1.1665	1.4970		
37	.2215	4781	.2602	.6600	1,0597	1.4595		
38	.2182	4901	.0828	.3270	.7367	1.1464		
39	.2160	5048	.3965	.0215	.3535	.7285		
40	.2234	5261	.6176	.3004	.0168	.3339		
41	.2355	5522	.7928	.5207	.2486	.0235		
42	.2702	5882	.9072	.6814	4557	.2299		
43	.3306	6382	.9906	.8060	.6215	. 4369		
44	. 4609	7269 8617	1.0874	.9356 1.0673	.7838	.6320 .8269		
45	.7152 1.4561	-1.1091	1.2634	1.1787	1.0939	1.0091		
46 47	5.3157	8096	1.0653	1.0289	9924	.9559		
13,	10.010				NATIONAL A	1		

TABLE 5.- ORDINATES OF NONSYMMETRICAL DUCT INLET WITH s = 0.280 AND m = 3.0

ſ'n	=	1.5	τ	=	0.0310;	h	=	2.6613	ĺ
L		,			,				

[n = 1.5; $\tau$ = 0.0310; n = 2.6613]							
θ (deg)	φ (deg)	x/h	(y/h) + 0.1306 (ordinate)				
	Upper du	ct inlet sec	tion				
0 x 7.5	0	∞	0.1306				
1	5.004	6.4980	.7519				
2	10.032	1.1177	1.0729				
3	15.108	.3003	.8077				
4	29,256	.0902	.6632				
5	25.503	.0130	.5682				
6	30.874	.0011	.5145				
7	36.398	.0074	. 4759				
8	42.103	.0312	.4481				
9	48.021	.0539	. 4252				
10	54.184	.0829	.4094				
11	60.625	.1097	.3966				
12	67,380	.1407	.3880				
13	74.483	.1704	.3830				
14	81.969	.2059	.3809				
15	89.870	.2425	.3801				
16	98.213	.2851	.3794				
17	107.018	.3293	.3809				
18	116.293	. 4063	.3823				
19	126.031	.4410	.3851				
20	136.207	.5159	.3880				
21	146.773	.6037	.3901				
22	157.658	.7349	.3952				
23	168.770	.9460	.4052				
24	180.000	∞ .9400	.1306				
24		<del></del>					
24	180.000	ct inlet sec	-0.2451				
25	191.230	0.9617	5197				
26	202.342	.7664	5097				
27	213.227	.6513	5046				
28	223.793	.5799	5025				
29	233.969	.5222	4996				
30	243.707	.4817	4968				
31	252.982	.4473	4954				
32	261.787	.4232	4939 4939				
33	270.130						
34	278.031	. 4024	4946 - 4954				
35 35	285.517	•3895 3002	4954 4975				
		.3802					
36	292,620	.3799	5025				
37	299.375 305.816	<b>.382</b> 5	5111 5230				
38		.3946	5239 - 5307				
39	311.979	.4119	<b></b> 5397				
40	317.897	.4454	5626 				
41	323.602	.4926	5904				
42	329.126	.5787	6290				
43	334.497	.7176	6827				
44	339.744	.9830	<b>7777</b>				
45	344.892	1.5028	9222				
46	349.968	2.9347	-1.1874				
47	354.996	10.1469	8664				
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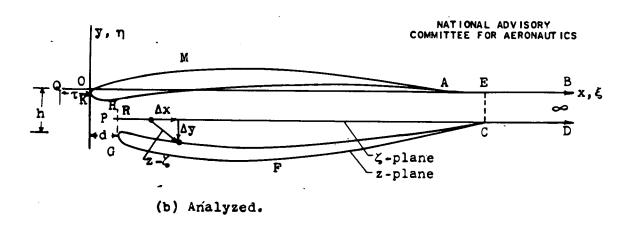
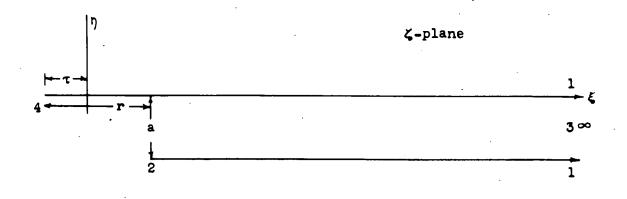
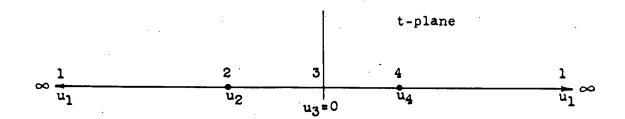


Figure 1.- Wing-duct installation.





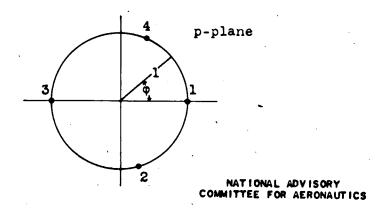


Figure 2.- Conformal relation of  $\zeta$ -, t-, and p-planes.

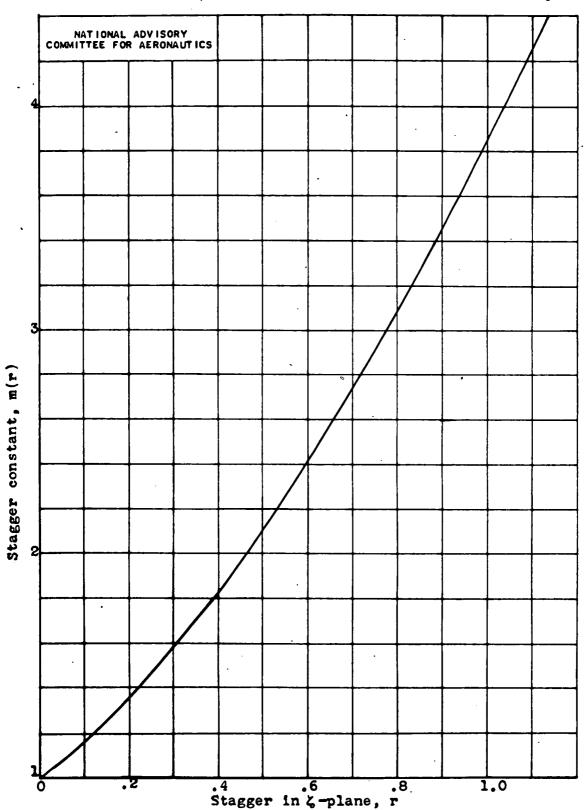
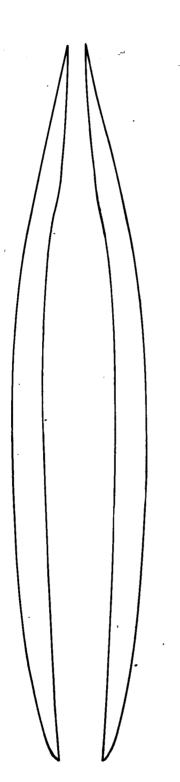


Figure 3.- Stagger constant as a function of stagger in  $\zeta$ -plane.



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= 1.0.Figure 4.- Symmetrical duct-inlet section (reference 4, shape 9). m

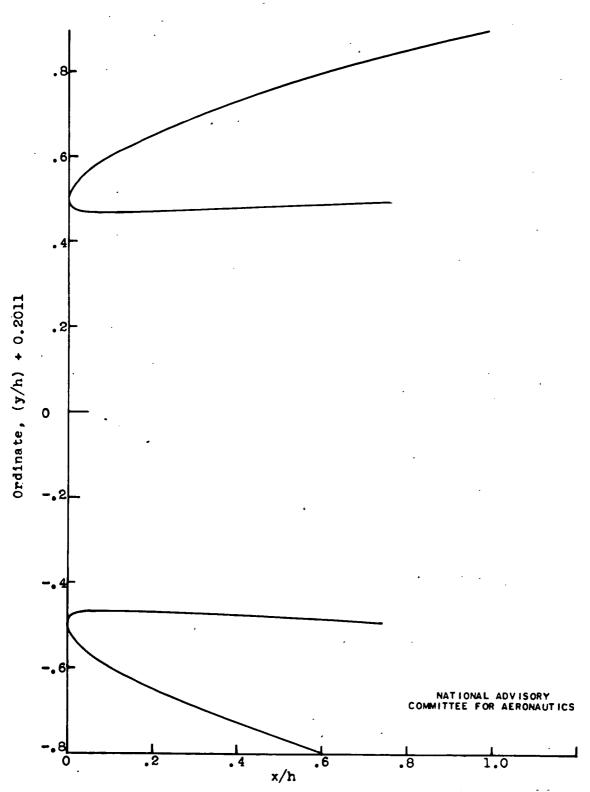


Figure 5.- Leading edge of symmetrical duct-inlet section with s = 0 and m = 1.0.

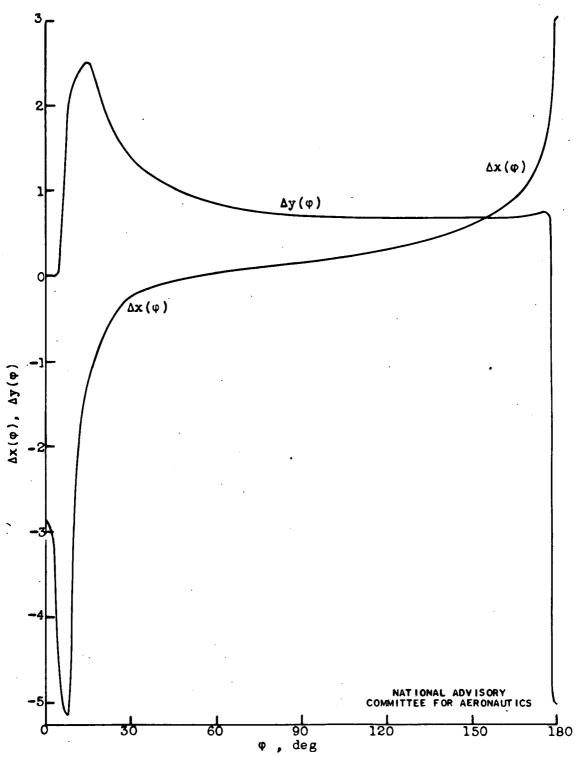
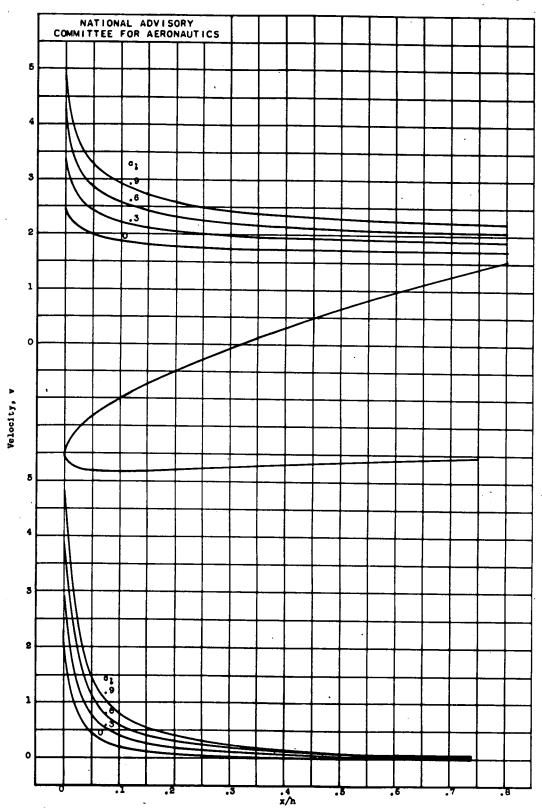
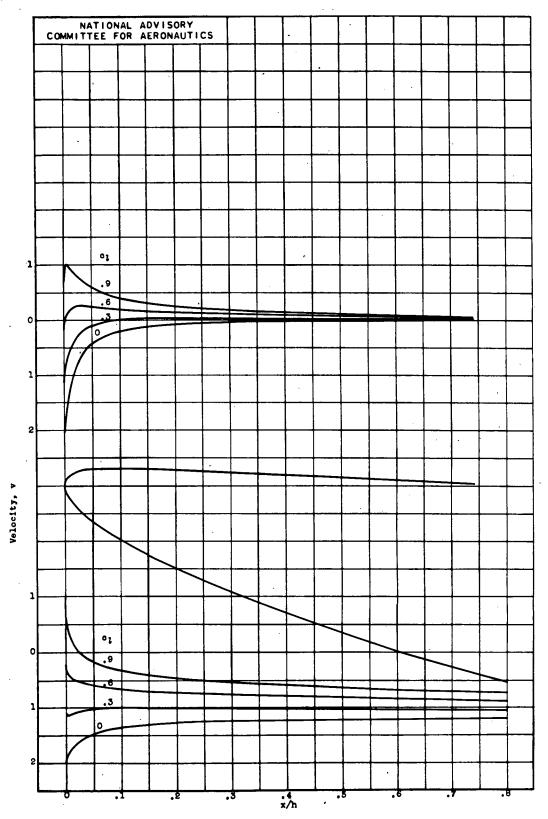


Figure 6.- Cartesian mapping function for duct-inlet sections.

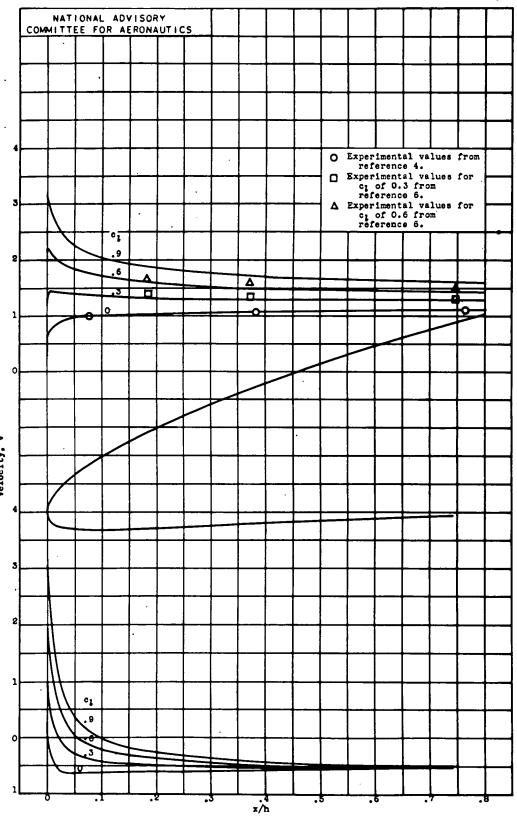


(a) Upper leading edge;  $v_n=0$ . Pigure 7.- Velocity distribution on upper and lower leading edges of symmetrical ductinlet section with s=0 and m=1.0.



(b) Lower leading edge;  $v_n = 0$ .

Figure 7. - Continued. Velocity distribution on upper and lower leading edges of symmetrical duct-inlet section with s=0 and m=1.0.



(c) Upper leading edge;  $v_n = 0.5$ .

Figure 7. - Continued. Velocity distribution on upper and lower leading edges of symmetrical duct-inlet section with s=0 and m=1.0.

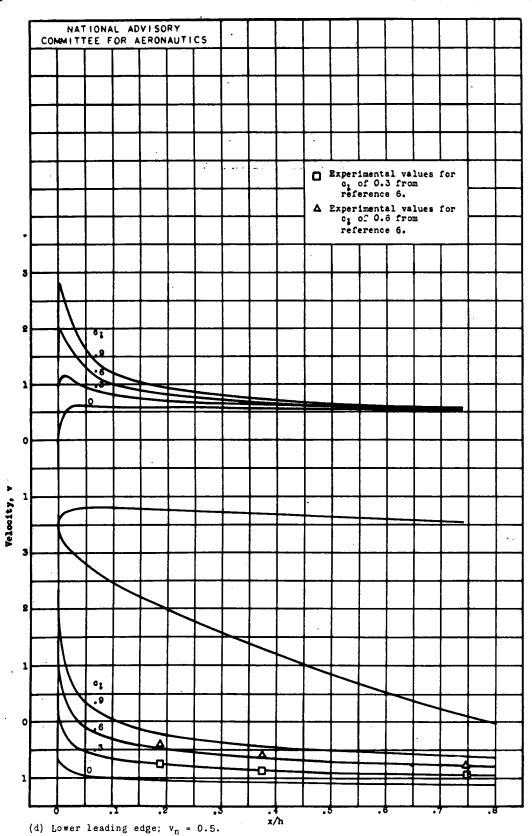


Figure 7. - Continued. Velocity distribution on upper and lower leading edges of symmetrical duct-inlet section with s=0 and m=1.0.

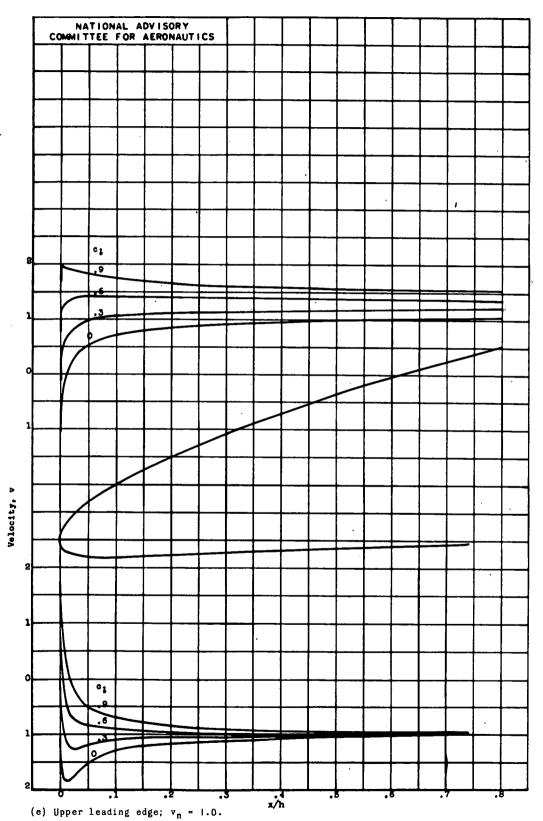
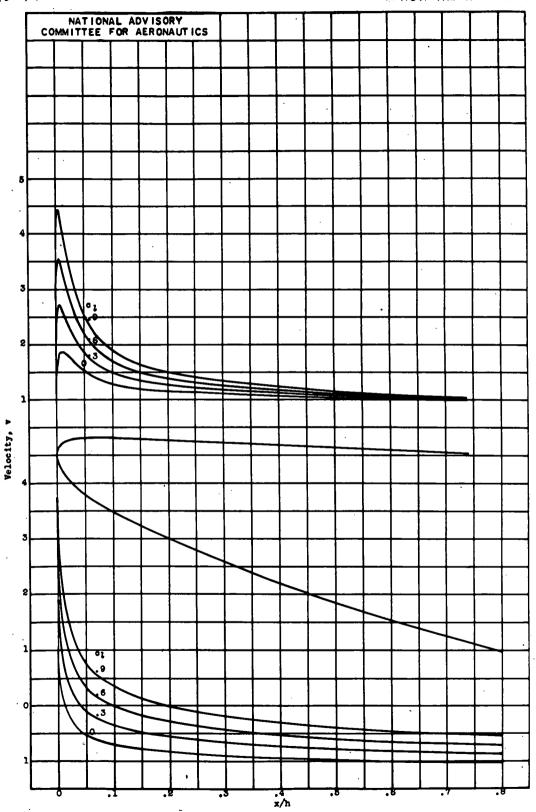


Figure 7. - Continued. Velocity distribution on upper and lower leading edges of symmetrical duct-inlet section with s = 0 and m = 1.0.



(f) Lower leading edge;  $v_n$  = 1.0. Figure 7. - Concluded. Velocity distribution on upper and lower leading edges of symmetrical duct-inlet section with s = 0 and m = 1.0.

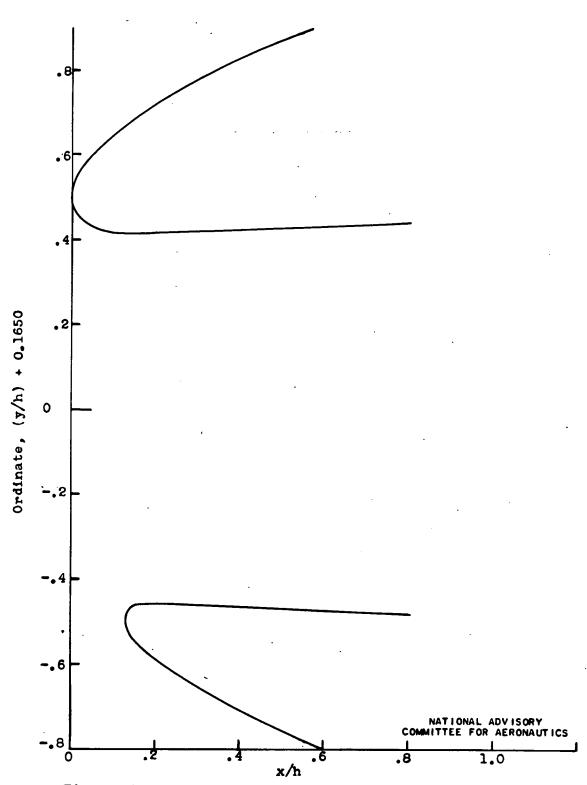
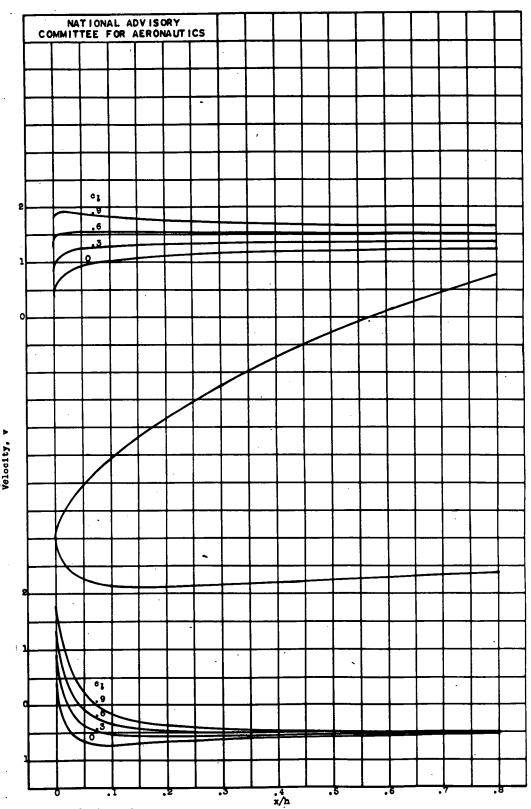
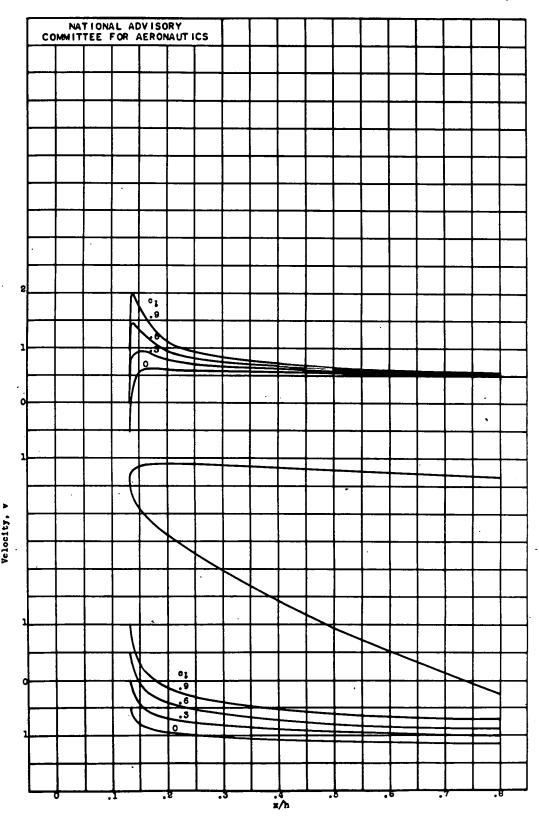


Figure 8. - Leading edge of nonsymmetrical duct-inlet section with s = 0.132 and m = 1.5.



(a) Upper leading edge. Pigure 9.- Velocity distribution on upper and lower leading edges of nonsymmetrical duct-inlet section with s = 0.132 and m = 1.5.  $v_n$  = 0.5.



(b) Lower leading edge.

Figure 9. - Concluded. Velocity distribution on upper and lower leading edges of nonsymmetrical duct-inlet's ection with s = 0.132 and m = 1.5.  $v_n$  = 0.5.

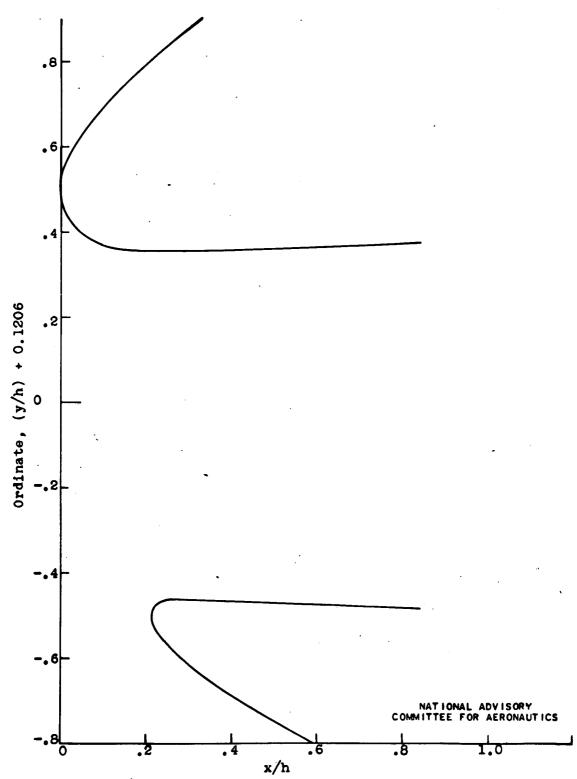
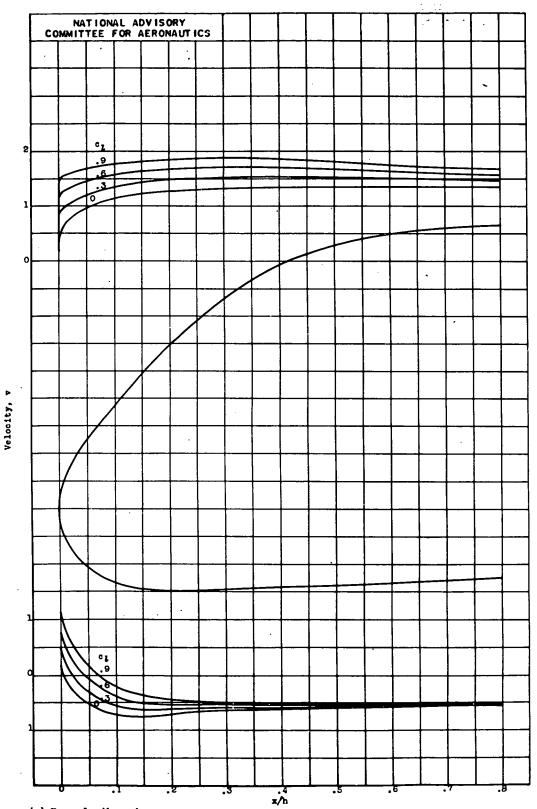


Figure 10.- Leading edge of nonsymmetrical duct-inlet section with s = 0.215 and m = 2.0.



(a) Upper leading edge. Pigure 11.- Velocity distribution on upper and lower leading edges of nonsymmetrical duct-inlet section with s = 0.215 and m = 2.0.  $v_n$  = 0.5.

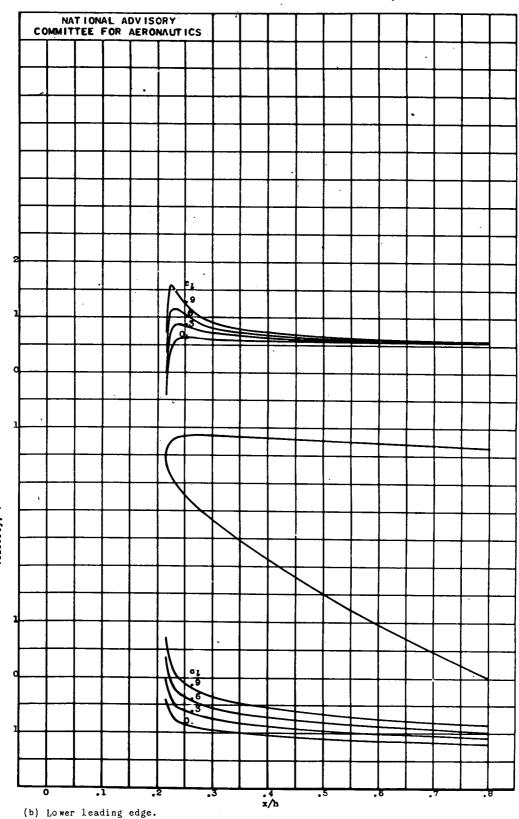


Figure 11. - Concluded. Velocity distribution on upper and lower leading edges of nonsymmetrical duct-inlet section with s=0.215 and m=2.0.  $v_n=0.5$ .

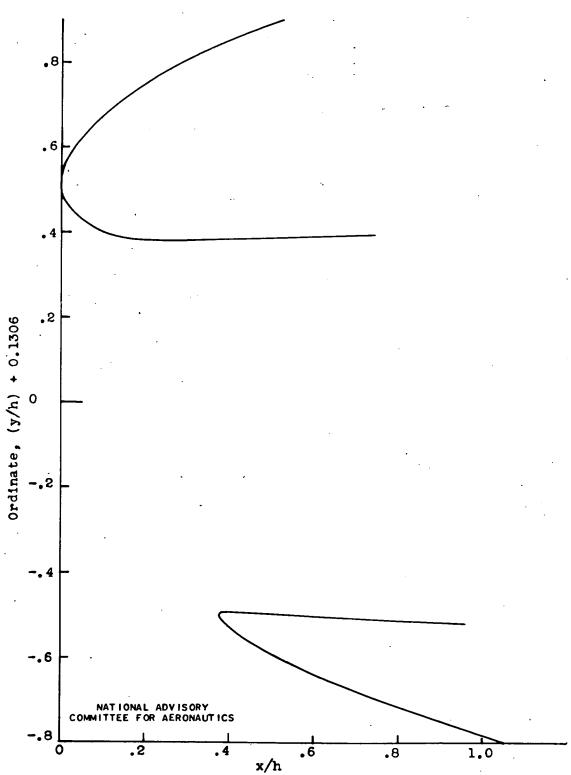


Figure 12. - Leading edge of nonsymmetrical duct-inlet section with s = 0.280 and m = 3.0. n = 1.5.

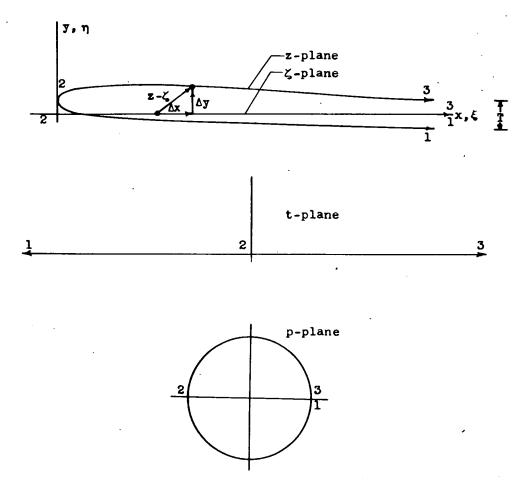


Figure 13.- Mapping of leading-edge region for isolated airfoils.

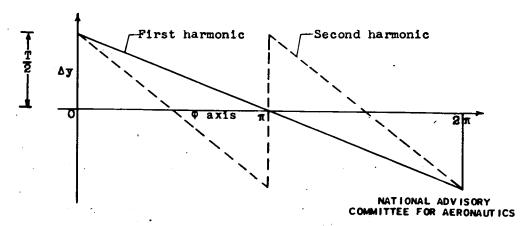


Figure 14.- Saw-tooth ordinate functions.

