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NACA RESEARCH ABSTRACT

# RESEARCH MEMORANDUM

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AERODYNAMIC STUDY OF A WING-FUSELAGE COMBINATION EMPLOYING

A WING SWEPT BACK 63° - EFFECTS AT SUBSONIC SPEEDS OF A

CONSTANT-CHORD ELEVON ON A WING CAMBERED AND TWISTED

FOR A UNIFORM LOAD AT A LIFT COEFFICIENT OF 0.25

By J. Lloyd Jones and Fred A. Demele

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WASHINGTON December 5, 1949



# NATIONAL ADVISORY COMMITTEE FOR AERONAUTICS

#### RESEARCH MEMORANDUM

# AERODYNAMIC STUDY OF A WING-FUSELAGE COMBINATION EMPLOYING A WING SWEPT BACK 63°.- EFFECTS AT SUBSONIC SPEEDS OF A CONSTANT-CHORD ELEVON ON A WING CAMBERED AND TWISTED FOR A UNIFORM LOAD AT A LIFT COEFFICIENT OF 0.25

By J. Lloyd Jones and Fred A. Demele

#### SUMMARY

A cambered and twisted wing having a leading edge swept back 63° and equipped with constant-chord elevons was tested in combination with a slender fuselage to determine the longitudinal and lateral control afforded by the elevons from a Mach number of 0.20 up to a Mach number of 0.93. The tests were performed at a Reynolds number of 2.0 million. Data are presented showing lift, drag, pitching-moment, and rolling-moment characteristics of the model for various elevon deflections, and hinge-moment characteristics of the elevon. Data from the tests have been applied to the calculation of the longitudinal-stability and -control characteristics of a hypothetical airplane geometrically similar to the model.

With the elevons undeflected, the model was longitudinally unstable about the one-quarter point of the wing mean aerodynamic chord at lift coefficients above about 0.50. The elevons had sufficient pitchingmoment and rolling-moment effectiveness for all lift coefficients at which the model was longitudinally stable. At low speeds, the lift coefficient at which static longitudinal instability occurred was decreased by increasing negative elevon deflection. Increasing the Mach number increased the pitching-moment effectiveness at lift coefficients above 0.20, but reduced the rolling-moment effectiveness of the elevons.

#### INTRODUCTION

A coordinated research program has been undertaken by the Ames Aeronautical Laboratory for an aerodynamic investigation of a wingfuselage combination employing a wing having the leading edge swept back 63°. Aerodynamic characteristics of such a wing with no camber or twist have been presented in references 1, 2, 3, and 4. Reference 1 includes low-speed data on the effectiveness of a constant-chord elevon, and reference 2 reports the Mach number and Reynolds number effects on the effectiveness of the same elevon.

Camber and twist have been incorporated in the wing in an effort to improve the flow near the wing tips where, as was evident from early investigations, loss of lift occurred even at very low angles of attack. Aerodynamic characteristics of such a wing, cambered and twisted to support a uniform distribution of lift over its surface at a lift coefficient of 0.25 and a Mach number of 1.5, have been presented in references 5 and 6.

This report presents the results of tests in the Ames 12-foot pressure wind tunnel of the effectiveness and hinge moments of constantchord elevons at Mach numbers ranging up to 0.93. The elevons extended over the outer 50 percent of the span of the cambered and twisted wing, which is described in reference 6, and had the same plan form as the elevons on the model used for the tests reported in references 1 and 2.

#### NOTATION

a speed of sound, feet per second

b wing span measured perpendicular to plane of symmetry, feet

c local chord measured parallel to plane of symmetry, feet

ving mean aerodynamic chord 
$$\begin{pmatrix} \int_{0}^{b/2} c^2 dy \\ \int_{0}^{b/2} c dy \end{pmatrix}$$
, feet  
CD drag coefficient  $\begin{pmatrix} \frac{drag}{qS} \\ \frac{drag}{qS} \end{pmatrix}$   
Ch hinge-moment coefficient  $\begin{pmatrix} \frac{hinge moment}{2q \times area moment of elevon} \\ about elevon hinge axis \end{pmatrix}$   
CL lift coefficient  $\begin{pmatrix} \frac{1ift}{qS} \end{pmatrix}$   
Cl rolling-moment coefficient  $\begin{pmatrix} rolling moment \end{pmatrix}$ 

- Clp damping-moment coefficient in roll; the rate of change of rolling-moment coefficient Cl with wing-tip helix angle pb/2V, per radian
- $C_{m}$  pitching-moment coefficient about the one-quarter point of the wing mean aerodynamic chord  $\left(\frac{\text{pitching moment}}{aST}\right)$

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Cm8*	$\left[\frac{(C_{\rm m})_{\delta=-4^{\rm O}} - (C_{\rm m})_{\delta=0^{\rm O}}}{-4}\right]$
H	hinge moment, foot-pounds
М	Mach number $\left(\frac{V}{a}\right)$
n	normal acceleration factor
р	angular velocity in roll, radians per second
q	dynamic pressure $\left(\frac{1}{2}\rho V^2\right)$ , pounds per square foot
R	Reynolds number $\left(\frac{\rho \nabla \overline{c}}{\mu}\right)$
S	wing area, square feet
V	free-stream velocity, feet per second
Vv	sinking speed, feet per second
VG	gliding speed, miles per hour
у	lateral ordinate, feet
α	angle of attack of root chord line, degrees
at	angle of twist with reference to root chord (positive for washin), degrees
au	angle of attack of root chord line, uncorrected for tunnel-wall interference, degrees
δ	elevon deflection measured in planes perpendicular to the elevon hinge axes (positive downward), degrees
δu	elevon deflection uncorrected for angular distortion due to load, degrees
δ <sub>Lu</sub>	left elevon deflection uncorrected for angular distortion due to load, degrees
δ <sub>Ru</sub>	right elevon deflection uncorrected for angular distortion due to load, degrees
δŢ	arithmetic sum of positive and negative elevon deflections, degrees

δ<sub>Tu</sub> arithmetic sum of positive and negative elevon deflections uncorrected for angular distortion due to load, degrees

coefficient of viscosity of air, slugs per foot-second

μρ

4

mass density of air, slugs per cubic foot

# MODEL AND APPARATUS

The model used in this investigation was the one used in the tests reported in reference 6. Photographs of the model are presented in figure 1 and dimensions are given in figures 2 and 3.

The wing had a leading-edge sweepback of  $63^{\circ}$ , a taper ratio of 0.25, and an aspect ratio of 3.5. The streamwise airfoil sections had the NACA 64A005 thickness distribution combined with a = 1 mean camber lines. The wing, as developed theoretically by the method given in reference 7, was cambered and twisted to support a uniform distribution of lift over its surface at a lift coefficient of 0.25 and a Mach number of 1.5. To provide for twisting of the wing under aerodynamic loads, the model wing was constructed with less twist than was indicated by theory, as is described in reference 6.

The elevons were of constant chord and extended over the outer 50 percent of the span. Each elevon was supported by three hinges and was restrained near the inner extremity. The ratio of elevon chord to wing chord was 1 to 4 at the wing midsemispan. The elevons had radius noses with no aerodynamic balance. The nose gaps were approximately 3/64 inch and were unsealed. These large gaps were necessary to permit the desired angular deflection since the elevons had considerable spanwise curvature. Hinge moments were measured by means of a wire-resistance strain gage mounted on the restraining member of the elevon on the left-hand wing.

The model was sting mounted, and the angle of attack was continuously controllable from a remote station during wind-tunnel operation. Forces and moments acting upon the model were measured by means of a wire-resistance strain-gage balance enclosed by the fuselage.

#### TESTS

Lift, drag, pitching-moment, rolling-moment, and elevon-hingemoment data have been obtained throughout an angle-of-attack range of -8° to +19°. This range was more limited at the larger elevon deflections and higher Mach numbers where vibration of either the model or its support or wind-tunnel power limits were critical. All tests were made at an angle of sideslip of 0°. The elevons were deflected negatively for longitudinal control and differentially for lateral control as given in the following table:

Elevon deflection angles								
Longitudina dat	al-control ta	Lateral-control data						
$\delta_{L_{u}}$ (deg)	δ <sub>Ru</sub> (deg)	$\delta_{Lu}$ (deg)	δ <sub>Ru</sub> (deg)					
0 -5 -10 -15 -20 -25	0 -5 -10 -15 -20 -25	0 10 20 30 -	0 -10 -20 -30 -					

The tests were performed at several Mach numbers ranging from 0.20 to 0.93 at a constant Reynolds number of 2.0 million.

# CORRECTIONS

The data have been corrected for the effects of tunnel-wall interference, constriction due to the tunnel walls, base pressure, and static tares due to the weight of the model. No correction has been applied to account for the change of elevon deflection under load upon the force and moment coefficients except when presented as functions of elevon angle. The angle of attack of the model was measured visually by means of a cathetometer; hence, no corrections were necessary to account for deflection of the support equipment. Precision of the force and moment measurements obtained from the strain-gage balance has been discussed in reference 6.

# Tunnel-Wall Interference

Corrections to the data to account for induced tunnel-wall interference have been determined by the method of Glauert (reference 8). Since the ratio of model span to tunnel diameter was small, the total corrections were small, and no account was taken of sweepback or of the differential flap deflections. The following corrections were added:

 $\Delta \alpha = 0.26 C_{T.}$ 

$$\Delta C_{\rm D} = 0.0046 \ {\rm CT}^2$$

No correction was applied to the pitching moment.

#### Constriction

The constriction effects of the tunnel walls have been evaluated by the method of reference 9. No modification of this method has been made to account for the effects of sweepback. The magnitude of the corrections applied to the Mach number and to the dynamic pressure is illustrated by the following table:

Corrected Mach number	Uncorrected Mach number	$\frac{q}{q}$ , corrected $\frac{1}{q}$ , uncorrected			
0.930	0.919	1.012			
.890	.884	1.007			
.800	.798	1.003			
.600	.599	1.002			
.200	.200	1.001			

#### Base Pressure

The pressure on the base of the model fuselage was measured and, in an effort to correct for support interference, the drag data were corrected to correspond to a base pressure equal to the static pressure of the free stream. The base-pressure correction to the drag was less than 5 percent for Mach numbers up to 0.75, and increased to approximately 20 percent at a Mach number of 0.93. The base-pressure correction reduced the drag.

#### Tares

There were no tares due to direct air forces on the model-support equipment, since the balance was within the model. Corrections were made for the change in static tares due to angle of attack.

#### RESULTS AND DISCUSSION

#### Longitudinal Characteristics

Elevon effectiveness and hinge moments. - Angle of attack, drag coefficient, and pitching-moment coefficient as functions of lift coefficient, and hinge-moment coefficient as a function of angle of attack are presented in figures 4 to 8, inclusive, for various elevon deflections for Mach numbers ranging from 0.20 to 0.93. The angle of attack for zero lift became more positive as the elevon was deflected upward and the minimum drag coefficient was increased considerably by negative elevon deflections greater than -5°.

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The elevon had sufficient pitching-moment effectiveness to provide longitudinal balance at all test Mach numbers for all positive lift coefficients at which the model had static longitudinal stability. The positive lift coefficient at which the loss of static longitudinal stability occurred (about 0.5) was reduced with increasing negative elevon deflection at a Mach number of 0.20, and generally increased with negative elevon deflection greater than -5° at higher Mach numbers. A slight forward movement of the aerodynamic center at zero lift was noted as the elevon was deflected negatively, and the movement became larger at the higher Mach numbers.

The change of elevon hinge moment with angle of attack was nearly uniform between angles of attack of  $-1^{\circ}$  and  $+8^{\circ}$  at a Mach number of 0.20 and between  $-1^{\circ}$  and  $+6^{\circ}$  for all other test Mach numbers. The variation of hinge-moment coefficient with angle of attack became considerably larger at angles of attack beyond these ranges. The sharply defined change of slope of the hinge-moment curves occurred coincidentally with the rearward movement of the aerodynamic center noted in the pitchingmoment data.

The variations of lift coefficient, pitching-moment coefficient, and hinge-moment coefficient with elevon deflection are presented in figure 9 for constant angles of attack at several Mach numbers. The pitching-moment effectiveness of the elevons was generally maintained throughout the entire range of elevon deflection.

The effect of Mach number on the pitching-moment effectiveness of the elevons and on the lift coefficient for longitudinal balance is shown in figure 10. The pitching-moment effectiveness was nearly independent of Mach number at lift coefficients below 0.20 over the test range of Mach numbers. The effectiveness  $-C_{m\delta}^*$  increased with increasing Mach number at lift coefficients greater than 0.20. The lift coefficient for longitudinal balance was essentially unaffected by compressibility up to a Mach number of 0.80 for negative elevon deflection of 10° or less, and it is indicated that for negative deflections of 5° or less the lift coefficient for longitudinal balance was little affected by compressibility throughout the entire test range of Mach numbers.

Lift-drag ratio. - Figure 11 presents the variation of lift-drag ratio with lift coefficient for various elevon deflections at several Mach numbers. The highest maximum lift-drag ratio occurred with an elevon deflection of -5°, which suggests that increasing the wing twist would result in a higher maximum lift-drag ratio for the wing with the elevons undeflected.

#### Lateral Control

Elevon effectiveness and hinge moments. - Rolling-moment coefficients due to elevon deflection are presented in figure 12 as a function

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cf angle of attack for differential elevon deflections of  $\pm 10^{\circ}$ ,  $\pm 20^{\circ}$ , and ± 30° at Mach numbers ranging from 0.20 to 0.93. Also presented in figure 12 are elevon-hinge-moment coefficients for the left elevon only (the deflection of which was positive) over the same range of elevon deflections and Mach numbers. These data indicate that the effectiveness of the elevons in producing rolling moment was maintained throughout the test range of angle of attack and Mach number. The effectiveness was nearly constant at angles of attack between  $-1^{\circ}$  and  $+8^{\circ}$  for a Mach number of 0.20, and between -1° and +6° for the higher Mach numbers. The angles of attack at which the rolling-moment effectiveness of the elevons began to decrease rapidly coincide with those at which the rearward movement of the aerodynamic center is noted in the pitching-moment data. The variation of elevon-hinge-moment coefficient with angle of attack remained fairly uniform over the same angle-of-attack range for which the maximum rolling-moment effectiveness was maintained. At angles of attack just beyond these ranges the variation of hinge-moment coefficient with angle of attack became considerably greater, and at the larger positive angles of attack became erratic.

The variation of rolling-moment coefficient with total elevon deflection (the arithmetic sum of the positive and negative deflections) was smooth to the largest deflection, as may be seen in figure 13. Increasing the Mach number from 0.20 to 0.93 reduced the effectiveness by roughly 10 percent for an angle of attack of 6° and by about 25 percent for an angle of attack of 10° at the largest elevon deflection  $\delta_u = \pm 30^\circ$ . The effect of Mach number on the rolling-moment effectiveness of the elevons is summarized in figure 14 for angles of attack of 0° and 4°. The rolling moment produced by a given elevon deflection was generally reduced slightly with increasing Mach number, the effect becoming greater with increasing deflections.

Helix angle.- On the basis of the methods presented in reference 10, helix angles generated by the wing tip in a steady roll have been calculated utilizing the data of figure 12. For the purposes of the calculations no torsional deflection and 0° of sideslip were assumed. Values of the damping-moment coefficient  $C_{lp}$ , calculated by the method of reference 11, varied from -0.226 at a Mach number of 0.20 to -0.231 at a Mach number of 0.93.

The variation of the predicted wing-tip helix angle with total elevon deflection  $\delta_{\rm T}$  is presented in figure 15 for various Mach numbers at a lift coefficient of 0.20. As anticipated from the decrease in rolling effectiveness above an angle of attack of 8°, calculations of pb/2V at a lift coefficient of 0.40 indicated a considerable decrease from its value at a lift coefficient of 0.20. No such calculations are presented herein, however, since above a Mach number of 0.20 the test angle-of-attack range was insufficient to evaluate corrections to the rolling-moment coefficient in roll. The variation of pb/2V with  $\delta_{\rm T}$ was fairly linear throughout the range of elevon deflections considered.

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Increasing Mach number generally reduced the helix angle. While the predicted wing-tip helix angle is large enough to insure high rolling velocities, it must be emphasized that the present calculations are for a rigid wing and that deflection of the wing could cause serious reductions in the magnitude of the rolling velocity.

#### Longitudinal Control of a Hypothetical Airplane

Data from the tests have been used in the calculation of the stability, maneuverability, elevon hinge moments, and power-off sinking speed of a hypothetical tailless airplane, geometrically similar to the model tested. Dimensions of the airplane were assumed to be as follows:

The center of gravity was assumed to be at 25 percent of the mean aerodynamic chord, and a wing loading of 40 pounds per square foot was assumed.

Figure 16 presents elevon hinge moment, elevon deflection, and lift coefficient as functions of Mach number calculated for the airplane in level flight and as affected by normal acceleration at an altitude of 25,000 feet. The variation of elevon deflection with Mach number and with normal acceleration factor was smooth and uniform. A very large variation of hinge moment with Mach number is noted for normal acceleration factors greater than 1.0. For unaccelerated flight (n = 1.0) increasing Mach number would require a gradually increasing push force up to a Mach number of 0.90. For a normal acceleration factor of 2.0, increasing Mach number is accompanied by a gradually decreasing push force. For constant-speed maneuvers with varying normal acceleration there are large and erratic changes in the hinge moment.

Power-off sinking speed, elevon deflection for balance, elevon hinge moment, and angle of attack are presented in figure 17 as functions of power-off gliding speed for sea-level operation.(Data at a Mach number of 0.20 were used in calculating the performance parameters shown in this figure.) The minimum power-off sinking speed is 22 feet per second and it occurs at a forward speed of approximately 215 miles per hour. The variation of elevon deflection required for longitudinal balance with gliding speed was stable for gliding speeds greater than 180 miles per hour. No computations are shown for gliding speeds less than 180 miles per hour, since the data indicated that the airplane would be longitudinally unstable at the required lift coefficients.

#### SUMMARY OF RESULTS

Tests have been made of a cambered and twisted wing with the leading edge swept back 63<sup>°</sup> in combination with a slender fuselage. The wing was equipped with constant-chord elevons extending over the outer 50 percent of the span. The tests were conducted at a Reynolds number of 2.0 million and at Mach numbers ranging from 0.20 to 0.93. The following results were obtained:

1. At low speed (M = 0.20) negative elevon deflections reduced the lift coefficient at which the loss of static longitudinal stability occurred, while at higher Mach numbers this lift coefficient generally increased with negative elevon deflections greater than  $-5^{\circ}$ . (With the elevons undeflected the loss of static longitudinal stability generally occurred at a lift coefficient of about 0.5.)

2. There was little effect of compressibility on the pitchingmoment effectiveness of the elevons at lift coefficients of 0.20 or less. At higher lift coefficients the effectiveness increased with increasing Mach number.

3. The effectiveness of the elevons in producing rolling moment was reduced slightly with increasing Mach number. The effectiveness was nearly constant at angles of attack between  $-1^{\circ}$  and  $+8^{\circ}$  for a Mach number of 0.20 and between  $-1^{\circ}$  and  $+6^{\circ}$  for the higher Mach numbers.

Ames Aeronautical Laboratory, National Advisory Committee for Aeronautics, Moffett Field, California.

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c <sub>o</sub>					C <sub>1</sub>				
Lower	surface	Upper s	surface		Lower surface		Upper surface		
Station	Ordinate	Station	Ordinate		Station	Ordinate	Station	Ordina	
0 .75 1.25 2.50 5.00 10.0 20.0 30.0	0 404 488 616 847 -1.166 -1.599 -2.131 -2.413	0 .5 .75 1.25 2.50 5.00 10.0 20.0 30.0	0 .404 .488 .616 .847 1.166 1.599 2.131 2.413		0 .526 .778 1.283 2.535 5.039 10.041 20.036 30.026	0 366 433 536 706 927 -1.211 -1.530 -1.685	0 .474 .726 1.221 2.463 4.956 9.959 19.964 29.974	0 .438 .536 .690 .984 1.401 1.984 2.725 3.138	
40.0 50.0 60.0 70.0 80.0 90.0 100.0	-2.499 -2.354 -2.032 -1.589 -1.071 541 011	40.0 50.0 60.0 70.0 80.0 90.0 100.0	2.499 2.354 2.032 1.589 1.071 .541 .011		40.010 50.00 59.990 69.985 79.985 89.985 100.000	-1.700 -1.530 -1.231 860 479 155 	39.990 50.000 60.010 70.015 80.015 90.015 100.000	3.297 3.179 2.828 2.313 1.669 .927	

# TABLE I.- AIRFOIL-SECTION COORDINATES [All values given in percent chord]

Lower	surface	Upper surface				
Station	Ordinate	Station	Ordinate			
0 .532 .788 1.295 2.547 5.056 10.056 20.044 30.031 40.013 50.000 59.987 69.981 79.975 89.981 100.000	0 357 419 507 663 851 -1.089 -1.345 -1.458 -1.446 -1.270 982 632 288 031 931 931	0 .469 .713 1.208 2.447 4.944 9.944 19.956 29.969 39.987 50.000 60.013 70.019 80.025 90.019 100.000	0 .457 .557 .720 1.026 1.477 2.103 2.912 3.373 3.548 3.436 3.085 2.547 1.852 1.045 			

°2

°3				°4				° <sub>5</sub>			
Lower surface Upper surfac		urface	Lower a	urface	Upper surface		Lower surface		Upper surface		
Station	Ordinate	Station	Ordinate	Station	Ordinate	Station	Ordinate	Station	Ordinate	Station	Ordinate
0.533 .788 1.298 2.556 5.056 10.056 20.048 30.032 40.016 59.984 69.976 79.976 89.984	$\begin{array}{c} -0.350\\414\\502\\645\\828\\ +1.051\\ -1.290\\ -1.377\\ -1.361\\ -1.186\\892\\557\\223\\ .008\end{array}$	0.470 .709 1.202 2.444 4.944 9.944 19.952 29.968 39.984 50.000 60.016 70.024 80.024 90.016	$\begin{array}{c} 0.462 \\ .557 \\ .725 \\ 1.043 \\ 1.497 \\ 2.150 \\ 2.978 \\ 3.447 \\ 3.639 \\ 3.527 \\ 3.527 \\ 3.169 \\ 2.627 \\ 1.911 \\ 1.091 \end{array}$	0.536 .799 1.291 2.549 5.055 10.055 20.044 30.033 40.022 50.000 59.989 69.978 79.978 89.978	-0.350 405 503 646 832 -1.050 -1.291 -1.389 -1.368 -1.193 908 569 230 .011	0.470 .711 1.204 2.440 4.945 9.945 19.956 29.967 39.978 50.000 60.011 70.022 80.022 90.022	0.460 .558 .722 1.039 1.489 2.144 2.976 3.425 3.621 3.512 3.162 2.604 1.915 1.083	0.543 .788 1.278 2.557 5.061 10.070 20.053 30.035 40.018 50.000 59.982 69.982 79.982 89.982	$\begin{array}{c} -0.350 \\420 \\508 \\648 \\823 \\ -1.068 \\ -1.313 \\ -1.419 \\ -1.401 \\ -1.208 \\595 \\245 \\018 \end{array}$	0.473 .718 1.208 2.452 4.956 9.965 19.947 29.965 39.982 50.000 60.018 70.018 80.018 90.018	0.455 .560 .718 1.033 1.494 2.119 2.960 3.415 2.608 3.485 3.135 2.592 1.891 1.068

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Note: Spanwise positions of airfoil sections  $c_0$  to  $c_5$  are shown in figure 3. For all sections: Leading-edge radius = 0.175. Trailing-edge radius = 0.014.

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(a) Rear view.



(b) Plan view.

Figure 1.- Model of the cambered and twisted wing with the leading edge swept back 63° in combination with a fuselage.

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Figure 3. - Plan form of right half of wing showing spanwise variation of camber and twist and location of sections for which coordinates have been calculated.

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Figure 4.- The effect of elevon deflection on the aerodynamic characteristics of the wing-fuselage combination and on the elevon hinge-moment coefficients at a Mach number of 0.20.

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(b) CL vs CD, Ch vs a.

Figure 4. - Concluded.

 $\delta_u, deg$ .6 0 0 -5 -10 ٥ .4 -20 V Lift coefficient, C<sub>L</sub> -25 Þ .2 0 -.2 -.4 NACA -.6 -8 -4 0 8 16 for  $\delta_u = 0^\circ$ 4 12 Angle of attack, a, deg .16 .12 .08 .04 0 -04 Pitching-moment coefficient, Cm (a) CL VS a, CL VS Cm.

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Figure 5.- The effect of elevon deflection on the aerodynamic characteristics of the wing-fuselage combination and on the elevon hinge-moment coefficients at a Mach number of 0.60.

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Figure 6.- The effect of elevon deflection on the aerodynamic characteristics of the wing-fuselage combination and on the elevon hinge-moment coefficients at a Mach number of 0.80.

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.8  $\delta_{u}, deg$ .6 0 0 -5 -10 .4 0 -15 Δ -20 V .2 Lift coefficient, CL -25 Þ 0 -.2 -.4 NACA -.6 -8 0 -4 4 for  $\delta_u = 0^\circ$ 8 12 16 Angle of attack, a, deg .16 .12 .08 .04 0 -.04 -.08 Pitching-moment coefficient, Cm

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(a) CL VS a, CL VS Cm.

Figure 7.- The effect of elevon deflection on the aerodynamic characteristics of the wing-fuselage combination and on the elevon hinge-moment coefficients at a Mach number of 0.89.

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(b) CL vs CD, Ch vs a.

Figure 7. - Concluded.



Figure 8. - The effect of elevon deflection on the aerodynamic characteristics of the wing-fuselage combination and on the elevon hinge-moment coefficients at a Mach number of 0.93.

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(b) CL vs CD, Ch vs a.

Figure 8. - Concluded.



(a) M, 0.20.





(b) M, 0.60.

Figure 9.- Continued.



(c) M, O.80.

Figure 9.- Continued.



(d) M, 0.89.

Figure 9. - Continued.



(e) M, O.93.

Figure 9. - Concluded.



Figure 10. – The effect of Mach number on  $C_{m_{g}}^{*}$  and on the lift coefficient for longitudinal balance.



(b) M, 0.60.

Figure 11. - The variation of lift-drag ratio with lift coefficient for various elevon deflections at several Mach numbers.

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(e) M, 0.93.

Figure II. - Concluded.



# (a) M, 0.20.

Figure 12.- The variation of rolling-moment and hinge-moment coefficients with angle of attack for various elevon deflections at several Mach numbers.

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Angle of attack, au, deg

(b) M, 0.60.

Figure 12.- Continued.

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Figure 12.- Continued.

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(c) M, 0.80.



(d) M, 0.89.

Figure 12.- Continued.









Figure 13.- The variation of rolling-moment coefficient with total elevon deflection at various angles of attack for several Mach numbers.

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Figure 14.- The effect of Mach number on the rolling-moment effectiveness of the elevons.

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Figure 15.- The variation of the wing-tip helix angle with total elevon deflection for several Mach numbers at a lift coefficient of 0.20.







