RESEARCH MEMORANDUM

## FLIGHT MEASUREMENTS OF DIRECTIONAL STABILITY TO A MACH

NUMBER OF 1.48 FOR AN AIRPLANE TESTED WITH THREE DIFFERENT VERTICAL TAIL CONFIGURATIONS

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# NATIONAL ADVISORY COMMITTEE FOR AERONAUTICS <br> WASHINGTON 

October 7, 1955
Declassified August 14, 1958

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SUMMARY

Flight tests have been performed to measure the directional stability of a fighter-type airplane over the Mach number range from 0.72 to 1.48 . The tests were made at altitudes of 40,000 feet and 30,000 feet and employed three different vertical tails of varying aspect ratio or area, or both.

These tests showed that the directional stability for all tail configurations increased with an increase in tail aspect ratio or area, or both, over the entire Mach number range and decreased with increasing supersonic Mach number above 1.15 .

## INTRODUCTION

The decrease in directional stability with increasing supersonic Mach number during flight tests of research airplanes has been discussed previously in references 1 to 3. In general this decrease results from the fact that with increasing supersonic Mach number the lift-curve slope of the vertical tail decreases while the unstable directional moment of the fuselage remains essentially constant. If the directional stability of the airplane becomes sufficiently low, deterioration of the dynamic stability can result (refs. l to 3) and, if the directional stability becomes zero, an actual divergence can occur.

With the advent of fighter airplanes capable of appreciable supersonic Mach numbers, the problem of adequate directional stability at supersonic speed has become of immediate importance. A fighter airplane having a $45^{\circ}$ swept wing and supersonic performance capabilities is being utilized for flight research by the NACA High-Speed Flight Station at Edwards, Calif. During rate-of-roll tests this fighter airplane exhibited violent cross-coupling behavior as reported in reference 4. Low
directional stability was considered to have contributed to the violence of the behavior. An investigation was undertaken, therefore, to determine in flight the directional stability of the airplane. During the investigation two additional vertical tail configurations with increased area and aspect ratio became available and were included in the tests.

This paper gives the results of the measurements of directional stability for these three tails within the Mach number range from 0.72 to about 1.48.

## SYMBOLS

A aspect ratio
b wing span, ft
$C_{2} \quad$ rolling-moment coefficient, $\frac{\text { Rolling moment }}{q S b}$
${ }^{C} Z_{\beta} \quad$ airplane effective dihedral parameter, $\frac{\partial C_{l}}{\partial \beta}$, $\mathrm{deg}^{-1}$
$\mathrm{C}_{\mathrm{N}_{\mathrm{A}}} \quad$ airplane normal-force coefficient, $\frac{\mathrm{nW}}{\mathrm{qS}}$
$C_{n} \quad$ yawing-moment coefficient, $\frac{\text { Yawing moment }}{q S b}$
airplane directional stability parameter, $\frac{\partial C_{n}}{\partial \beta}, \operatorname{deg}^{-1}$
c chord, ft
$\bar{c} \quad$ mean aerodynamic chord, ft
$g$ acceleration due to gravity, ft/sec ${ }^{2}$
$h_{p} \quad$ altitude, ft
$I_{X} \quad$ moment of inertia about $X$-axis, slug-ft ${ }^{2}$
$I_{Y} \quad$ moment of inertia about $Y$-axis, slug-ft ${ }^{2}$
$I_{Z} \quad$ moment of inertia about $Z$-axis, slug-ft ${ }^{2}$

| $I_{X Z}$ | product of inertia, slug-ft ${ }^{2}$ |
| :---: | :---: |
| $i_{t}$ | angle of tail incidence measured from line parallel to longitudinal axis of airplane, deg |
| M | Mach number |
| n | load factor, g units |
| P | period of lateral oscillation, sec |
| p | rolling angular velocity, radians/sec |
| q | dynamic pressure, lb/sq ft |
| q | pitching angular velocity, radians/sec |
| r | yawing angular velocity, radians/sec |
| S | wing area, $\mathrm{ft}^{2}$ |
| $\mathrm{T}_{1 / 2}$ | time to damp to half amplitude of lateral oscillation, sec |
| t | time, sec |
| W | weight, lb |
| $\alpha$ | indicated angle of attack, deg |
| $\beta$ | indicated angle of sideslip, deg |
| $\delta_{a_{t}}$ | total aileron deflection, deg |
| $\delta_{r}$ | rudder deflection, deg |
| $\Lambda_{c / 4}$ | sweepback at 0.25 chord, deg |
|  | taper ratio |

## AIRPLANE AND INSTRUMENTATION

The airplane utilized in this investigation is a fighter type with a single turbojet engine and a low swept wing and tail. A three-view drawing of the airplane with the original vertical tail is shown in
figure l. Figure 2 presents a photograph of the airplane. The geometric and mass characteristics of the airplane are given in table 1.

The tests utilized three vertical tails characterized by differing areas and aspect ratios as follows:

|  | Area, sq ft | Aspect ratio |
| :---: | :---: | :---: |
| Tail A | 33.5 | 1.13 |
| Tail B | 37.3 | 1.49 |
| Tail C | 42.7 | 1.49 |

Drawings of the three tails are shown in figure 3. Figure 4 presents a photograph of two airplanes showing tails $A$ and $C$. The same rudder was used with all tails.

Complete stability and control instrumentation was installed for the flight research reported in this paper. The angle of attack, angle of sideslip, airspeed, and altitude were sensed on the nose boom. The Mach numbers presented are based on a preliminary calibration of the airspeed installation and are considered accurate to $\pm 0.02$ at subsonic speeds and to $\pm 0.01$ at supersonic speeds. The angle of attack and angle of sideslip are presented as measured.

## TESTS AND DATA REDUCTION

Rudder pulses were performed to determine the period and damping of the lateral motions. The maneuvers were performed by abruptly deflecting the rudder pedals, returning them to neutral, then holding them fixed. The stick was held fixed throughout the maneuver. Representative maneuvers are presented in time history form in figure 5. Maneuvers were performed in level flight as shown in the following tabulation, except for the maneuvers at Mach numbers greater than 1.35 which were performed in dives at altitudes above 33,000 feet.

| M | Altitude, ft | Vertical tail |
| :---: | :---: | :--- |
| 0.72 to 0.74 | 30,000 | A, B, and C |
| 0.84 to 1.34 | 40,000 | A |
| 0.78 to 1.39 | 40,000 | B |
| 0.72 to 1.48 | 40,000 | C |

It was found that the simplified method of determining the value of the directional stability parameter $C_{n_{\beta}}$ given in reference 5 was inadequate for this airplane. Therefore, the following expression was used (see appendix A for derivation):

$$
C_{n_{\beta}}=\left[\left(\frac{2 \pi}{P}\right)^{2}+\left(\frac{0.693}{I_{I / 2}}\right)^{2}\right] \frac{I_{Z}}{57 \cdot 3 q S b}-\frac{I_{X Z}}{I_{X}} c_{l_{\beta}}+\alpha \frac{I_{Z}}{I_{X}} c_{l_{\beta}}
$$

It may be noted that this expression includes the single-degree-offreedom relation of reference 5 modified to include the effects of damping, product of inertia, and an angle-of-attack term. The expression gives the value of $\mathrm{C}_{\mathrm{n}}$, as measured about the body axis. The product-of-inertia term is very small since the principal axis is estimated by the manufacturer to be inclined only about $1 / 2^{0}$ down at the nose for an average test weight. Unpublished wind-tunnel measurements of $C_{l_{\beta}}$ for Mach numbers up to 1.0 were used in the equation. Since above $M=1.0$ the angles of attack were generally less than $3^{\circ}$ and $C_{q_{\beta}}$ is quite small, the angle-of-attack term is considered small enough to be neglected at supersonic speeds.

## RESULTS AND DISCUSSION

The time histories of maneuvers at $M=0.74$ and at $M=1.38$ in figure 5 were performed with tail B but are representative of all three tails. In most cases the pedals and stick were held fixed subsequent to the pulse; however, small control surface movements did occur.

Figure 6 shows the measured period and damping for the three tail configurations. These data are presented for an altitude of 40,000 feet with the exception of the points above $M=1.35$ which, as mentioned previously, were obtained in dives between 40,000 feet and 33,000 feet. For any given tail there is very little scatter in the periods measured, indicating the small control movements did not unduly influence the period. The measured damping, however, shows considerable scatter. This condition reflects the difficulty of measuring the damping and possibly the effect of the small control motions. For the most part, the periods show a general decrease with an increase of Mach number at subsonic speeds and show an almost constant value at supersonic speeds. With each of the three tail configurations, the measured variation of damping of the airplane indicates a region of reduced stability (increased time to damp) at transonic speeds with less time required to damp to half amplitude at Mach numbers above and below this region.

The values of the directional stability parameter $C_{n_{\beta}}$ were computed from the values of $P$ and $T_{1 / 2}$ in figure 6. Figure 7 presents the Mach number variation of $C_{n_{\beta}}$ determined for each of the tail configurations. The value of $\mathrm{C}_{\mathrm{n}_{\beta}}$ increases with increasing tail size as would be expected from the increase in aspect ratio or area, or both.

The decrease in $C_{n_{\beta}}$ anticipated with increasing supersonic Mach number (ref. 2) is quite pronounced particularly above $M \approx 1.15$. With tail C, for example, the airplane lost about half its directional stability between $M=1.15$ and $M=1.48$. A measure of the improvement in $\mathrm{C}_{\mathrm{n}_{\beta}}$ (produced by increasing tail area and aspect ratio) is shown by the fact that a value of $C_{n_{\beta}}=0.001$ was reached at $M=1.22$ with tail $A$, but with tail $C$ the value of $C_{n_{\beta}}=0.001$ was not reached until about $\mathrm{M}=1.48$.

An unpublished value of $C_{n_{\beta}}=0.0019$ measured in the Langley 4 - by 4 -foot supersonic pressure tunnel at $M=1.41$ is shown in figure 7 . When this value is corrected for aeroelastic effects estimated by the manufacturer $\left(\Delta \mathrm{n}_{\beta}=-0.00052\right)$ and the effect of turning the air flow at the intake duct $\left(\Delta C_{n_{\beta}}=-0.00025\right)$, a value of $C_{n_{\beta}}$ nearly equivalent to that measured in flight is obtained.

The required value of $\mathrm{C}_{n_{\beta}}$ for reasonable handling qualities is, of course, not indicated in these tests but must be determined by the performance of other maneuvers such as the aileron rolls presented in reference 4. That $C_{n_{\beta}}$ may become very small or neutral at high Mach numbers, however, indicates that under some conditions poor dynamic stability may be encountered, as for the Douglas D-558-II airplane (refs. I to 3), or an actual static directional divergence may occur.

## CONCLUDING REMARKS

Flight tests of a fighter-type airplane with three different vertical tail configurations over the Mach number range from 0.72 to 1.48 indicate, as would be expected, that the directional stability increased with an increase in tail aspect ratio or area, or both, over the entire Mach number range and decreased with increasing supersonic Mach number for all tail configurations.

The Mach number at which a value of the directional stability parameter $C_{n_{\beta}}$ had decreased to 0.001 was increased from a Mach number of 1.22 to a Mach number of 1.48 by increasing the tail area 27 percent and increasing the tail aspect ratio 32 percent.

High-Speed Flight Station, National Advisory Committee for Aeronautics, Edwards, Calif., July 20, 1955.

## APPENDIX A

## DERIVATION OF $\mathrm{C}_{\mathrm{n}_{\beta}}$ EQUATION

The three lateral equations of motion containing terms pertinent to the derivation of $\mathrm{C}_{\mathrm{n}_{\beta}}$ are written as

$$
\begin{gathered}
\dot{\beta}=-r+\alpha p+\frac{q S}{m V} c_{Y_{\beta}} \beta \\
\dot{r}=\frac{I_{X Z}}{I_{Z}} \dot{p}+\frac{q S b^{2}}{2 V I_{Z}} c_{n_{r}} r+\frac{q S b}{I_{Z}} C_{n_{\beta}} \beta+\frac{q S b}{2 V I_{Z}} C_{n_{\beta}} \cdot \dot{\beta} \\
\dot{p}=\frac{q S b}{I_{X}} c_{Z_{\beta}} \beta
\end{gathered}
$$

Taking the time derivative of the $\dot{\beta}$ equation assuming $\alpha$ is constant

$$
\ddot{\beta}=-\dot{r}+\alpha \dot{p}+\frac{q S}{m V} C_{Y_{\beta}} \dot{\beta}
$$

Substituting and collecting terms gives

$$
\begin{aligned}
& \ddot{\beta}-\left(\frac{q S}{m V} C_{Y_{\beta}}-\frac{q S b^{2}}{2 V I_{Z}} C_{n_{\beta}}+\frac{q S b^{2}}{2 V I_{Z}} C_{n_{r}}\right) \dot{\beta}+\left(\frac{q S b}{I_{Z}} c_{n_{\beta}}-\frac{\alpha q S b}{I_{X}} c_{\imath_{\beta}}+\right. \\
& \left.\frac{I_{X Z q S b}}{I_{Z} I_{X}} c_{\imath_{\beta}}\right) \beta=0
\end{aligned}
$$

It is assumed that $r=-\dot{\beta}$ and the damping factor, $\zeta$, is equal to

$$
\frac{q S}{m V} C_{Y_{\beta}}-\frac{q S b^{2}}{2 V I_{Z}} C_{n_{\dot{\beta}}}+\frac{q S b^{2}}{2 V I_{Z}} C_{n_{r}}
$$

Therefore

$$
\ddot{\beta}-\zeta \dot{\beta}+\left(\frac{q S b}{I_{Z}} c_{n_{\beta}}-\alpha \frac{q S b}{I_{X}} c_{\imath_{\beta}}+\frac{I_{X Z} q S b}{I_{Z} I_{X}} c_{\imath_{\beta}}\right) \beta=0
$$

The natural frequency of the oscillation $\omega$ is determined from the imaginary part of the roots.

$$
\frac{i \sqrt{\zeta^{2}-4\left(\frac{q S b}{I_{Z}} c_{n_{\beta}}-\frac{\alpha q S b}{I_{X}} c_{\tau_{\beta}}+\frac{I_{X Z}}{I_{Z}} \frac{q S b}{I_{X}} c_{\tau_{\beta}}\right)}}{2}=\omega
$$

Squaring and simplifying

$$
C_{n_{\beta}}=\frac{\omega^{2} I_{Z}}{q S b}+\alpha \frac{I_{Z}}{I_{X}} c_{Z_{\beta}}-\frac{I_{X Z}}{I_{X}} c_{Z_{\beta}}+\frac{\zeta^{2} I_{Z}}{4 q S b}
$$

Inasmuch as $\omega^{2}=\left(\frac{2 \pi}{P}\right)^{2}$ and $\zeta^{2}=4\left(\frac{0.693}{\mathrm{~T} 1 / 2}\right)^{2}$, substitution and rearrangement of terms gives

$$
C_{n_{\beta}}=\left[\left(\frac{2 \pi}{P}\right)^{2}+\left(\frac{0.693}{T_{I / 2}}\right)^{2}\right] \frac{I_{Z}}{q S b}+\alpha \frac{I_{z}}{I_{X}} c_{\tau_{\beta}}-\frac{I_{X Z}}{I_{X}} c_{\tau_{\beta}}
$$

where

$$
\begin{aligned}
& C_{n_{r}}=\partial C_{n} / \partial \frac{r b}{2 V} \\
& C_{n_{\dot{\beta}}}=\partial C_{n} / \partial \dot{\beta} \\
& C_{Y}=\frac{\text { Side force }}{q S} \\
& C_{Y_{\beta}}=\partial C_{Y} / \partial \beta
\end{aligned}
$$

$$
\mathrm{m} \quad \text { mass }
$$

$$
\dot{p}=\partial \mathrm{p} / \partial t
$$

$$
\dot{r}=\partial r / \partial t
$$

V velocity

$$
\dot{\beta}=\partial \beta / \partial t
$$

$$
\ddot{\beta}=\partial^{2} \beta / \partial t^{2}
$$

## REFERENCES

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TABLE I

## PHYSICAL CHARACTERISTICS OF AIRPLANE

Wing:
Airfoil section ..... NACA 64A007Total area (including aileron and 83.84 sq ft coveredby fuselage), sq ft376.02
Span, ft ..... 36.58
Mean aerodynamic chord, ft ..... 11.33
Root chord, ft ..... 15.86
Tip chord, ft ..... 4.76
Taper ratio ..... 0.30
Aspect ratio ..... 3.56
Sweep at 0.25 chord line, deg ..... 45
Incidence, deg ..... 0
Dihedral, deg ..... 0
Geometric twist, deg ..... 0
Aileron:
Area rearward of hinge line (each), sq ft ..... 19.32
Span at hinge line (each), ft ..... 7.81
Chord rearward of hinge line, percent wing chord ..... 25
Travel (each), deg ..... $\pm 15$
Irreversible hydraulic boost and artificial feel
Aerodynamic balance ..... None
Static balance Internal lead weights
Leading-edge slat:
Span, equivalent, ft ..... 12.71
Segments ..... 5
Spanwise location, inboard end, percent wing semispan ..... 24.6
Spanwise location, outboard end, percent wing semispan ..... 94.1
Ratio of slat chord to wing chord (parallel to fuselage reference line), percent ..... 20
Rotation, maximum, deg ..... 15
Horizontal tail:
Airfoil section NACA 65 A003. 5
Total area (including 31.65 sq ft covered by fuselage), sq ft ..... 98.86
Span, ft ..... 18.72
Mean aerodynamic chord, ft ..... 5.83
Root chord, ft ..... 8.14
Tip chord, ft ..... 2.46
Taper ratio ..... 0.30
Aspect ratio ..... 3.54
Sweep at 0.25 chord line, deg ..... 45
Dihedral, deg ..... 0
Travel, leading edge up, deg ..... 5
Travel, leading edge down, deg ..... 25Irreversible hydraulic boost and artificial feel
Vertical tail:
Airfoil section . . . . . . . . . . . . . . . . NACA
Area (excluding dorsal fin and area blanketed.
by fuselage), sq ft . . . . . . . . . . . . . . . .
Power plant:
Turbojet engine One Pratt \& Whitney J57-P7 with afterburner
Thrust (guarantee sea level), afterburner, lb ..... 15,000
Military, lb ..... 9,220
Normal, ib . ..... 8,000
Airplane weight, lb:
Basic (without fuel, oil, water, pilot) ..... 19,662 ..... 24, 800Total (full fuel, oil, water, pilot)
Center-of-gravity location, percent $\bar{c}$ :
Total weight - gear down ..... 31.80
Total weight - gear up ..... 31.80
Moments of inertia (estimated total weight): $I_{X}$, slug-ft ${ }^{2}$ ..... 11,103
$I_{Y}$, slug-ft $t^{2}$ ..... 59,248
$I_{Z}$, slug-ft $t^{2}$ ..... 67,279
$I_{X Z}$, slug-ft2 ..... 941
Inclination of principal axis (estimated total weight): ..... 0.8


Figure 1.- Three-view drawing of airplane with vertical tail A. All dimensions in inches.



Figure 3.- Sketch of vertical tails A, B, and C.


Figure 4.- Photograph of two airplanes showing tails $A$ and $C$. -89376



(a) $M \approx 0.74 ; h_{p} \approx 30,000$ feet.

Figure 5.- Time history of lateral oscillation induced by a rudder pulse for airplane with vertical tail (B).


(b) $M \approx 1.38 ; h_{p} \approx 37,000$ feet.

Figure 5.- Concluded.

(a) Vertical tail A.

Figure 6.- Mach number variation of period and time to damp to halfamplitude of lateral oscillation for altitudes near 40,000 feet.


(b) Vertical tail B.

Figure 6.- Continued.


(c) Vertical tail C .

Figure 6.- Concluded.


Figure 7.- Mach number variation of directional stability parameter $C_{n_{\beta}}$ for three vertical tail configurations at altitudes near 40,000 feet.

