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NATIONAL ADVISORY COMMITTEE FOR AERONAUTICS <u>RESEARCE MEMORANDUM</u>-24.8. A COMPARISON OF FLIGHT-MEASURED CARRIER-APPROACH SPEEDS P

WITH VALUES PREDICTED BY SEVERAL DIFFERENT CRITERIA

FOR 41 FIGHTER-TYPE AIRPLANE CONFIGURATIONS

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SUMMARY

Lift and drag characteristics have been determined in flight in the landing-approach configuration on 41 jet-propelled fighter-type airplane arrangements, including various wing boundary-layer-control installations. Minimum comfortable approach speeds for carrier-type landings were evaluated for these airplanes by four test pilots. The reason given most frequently for limiting (i.e., not reducing) approach speed was "inability to control altitude"; the reason given second most frequently was "stall proximity." For airplanes limited by altitude controllability, none of a number of simple criteria considered for predicting approach speed enabled predictions within ±5 knots for all the configurations. A criterion in which the approach speed was assumed to be 115 percent of the power-approach stalling speed gave as good agreement with flight values as any of the criteria considered. Departures from predicted approach speeds assumed to be 115 percent of the power-approach stalling speed were consistent with the presence of "secondary" favorable or unfavorable factors. For several of the airplanes, approach speeds were selected on $\mathbf{\Theta}$ the "back side" of the curve of thrust required against velocity, indi- c cating that this condition does not of itself impose a limitation approach speed.

INTRODUCTION

In recent years pilots have tended to increase the landing speeds of modern jet-propelled fighter airplanes in relation to the stalling speeds. The higher landing speeds have, in turn, increased the requirements for GOT'T landing gear and carrier arresting gear strength and for length of landing runway.



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Consequently, the Ames Aeronautical Laboratory of the NACA has undertaken a general program to study the problems associated with the landing approach. One of the objectives of this program is to develop means for reducing the landing speeds. To this end, studies have been made both in wind tunnels and in flight of various arrangements of boundary-layercontrol (BLC) systems. As indicated in references 1 to 6 effective BLC can reduce stalling speeds, and since the landing-approach speed is, in a general way, related to the stalling speed, it is not surprising to find that the landing-approach speed was reduced correspondingly.

Another objective of the program is to identify the factors that contribute to the selection of a particular approach speed. Other reports have listed many of the factors which pilots believe could be the principal reasons for not reducing approach speeds below selected values (see, e.g., refs. 6 to 9). There still remains unsolved, however, the problem of relating these factors to the approach speed quantitatively. A third objective of the Ames program is, then, to develop satisfactory criteria for predicting approach speeds quantitatively. Extensive flight investigations which have been conducted in connection with this broad program have yielded a considerable amount of data. Data have been accumulated on the lift-drag characteristics of 41 fighter-type configurations, including various BLC arrangements. The minimum comfortable approach speeds in carrier-type approaches were selected by several pilots, and the reasons given by the pilots for not reducing the approach speeds below the selected values were also determined. Supplementary studies are being conducted on a landing-approach simulator to aid in developing approach-speed criteria (ref. 10).

The purposes of this report are to present the available lift-drag data, to show the applicability of various simple criteria for predicting carrier-approach speeds, and to summarize the reasons why pilots limit their approach speeds.

SYMBOLS

A _x	longitudinal acceleration, units of gravity, g
A_z	vertical acceleration, units of gravity, g
CL	lift coefficient, $\frac{\text{lift}}{qS}$
$C_{L_{max}}$	maximum lift coefficient
CD	drag coefficient, $\frac{drag}{qS}$
D	drag, lb

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- F_G gross engine thrust, 1b
- hp horsepower
- L lift, lb
- S wing area, sq ft
- T thrust, lb
- V velocity, knots
- W weight of airplane, lb
- Wa mass flow of air through engine, slugs/sec
- q dynamic pressure, 1b/sq ft
- a angle of attack, deg
- δ_{f} flap deflection, deg
- ρ atmospheric density, slugs/cu ft
- γ flight-path angle, radians
- $\dot{\gamma}$ rate of change of flight-path angle, radians/sec

Subscripts

- o standard sea-level conditions
- S stall
- PA power approach
- max maximum
- min minimum
- av average

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avail available

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INSTRUMENTATION

NACA recording instruments were used to record airspeed, altitude, vertical and longitudinal acceleration, angle of attack, and tail-pipe pressure. Standard calibration techniques were used for calibrating the recording airspeed systems for all the airplanes except the F9F-6, the F9F-4, the F-94C, and the F-84F airplanes; for these latter airplanes nose-boom installations providing static pressure sources about 10 feet ahead of the airplane nose were presumed to yield static pressure with no significant error. Indicated airspeeds were calibrated against recorded airspeeds for all configurations. For most of the configurations the single tail-pipe probe, which was used as a thrust indicator in accordance with the technique described in reference 11, was calibrated by use of a ground thrust stand; an exception was the F9F-4 for which, in the absence of a calibration, the tail-pipe probe was assumed to measure the average total head across the exit.

AIRPLANES

Ten airplanes were tested in the current program, the FJ-3, F4D, F7U-3, F9F-4, F9F-6, F-84F, F-86A, F-86F, F-94C, and F-100A. Two-view sketches of these airplanes are shown in figure 1. Various wing modifications were tested on a number of these airplanes including fences, different leading-edge arrangements (slats, cambered leading edges, and suction boundary-layer control), and different trailing-edge flap arrangements (blowing boundary-layer control and suction boundary-layer control). The particular arrangement used for each test configuration is indicated in table I. References describing the modifications in more detail, where available, are indicated in table I.

TESTS

The flight program consisted of tests to determine the lift and drag as a function of angle of attack for each configuration, and tests by several pilots to determine the carrier landing-approach speed. To obtain the lift and drag curves, data were recorded during runs in steady flight in the power-approach condition at a number of different airspeeds from about 200 knots down to about 10 knots above the stalling speed. A time history was then obtained from this speed to the stall. The rate of change of airspeed during the time history portion of the record did not exceed 1 knot per second. In the interest of safety the lift-drag tests were conducted at altitudes ranging from 5,000 feet to 10,000 feet.

For the pilot's evaluation of approach speed, carrier-type landing approaches were made. In this type of approach the airspeed is relatively constant, the flight-path angle is quite low (of the order of 0° to 2°), and a high level of engine power is required to maintain steady flight. The use of this technique permitted the pilots to quote a single value for the approach speed, in contrast to conditions in low-power sinkingtype approaches where the airspeed may be changing throughout the approach. The technique employed by the pilots was to determine the stalling speed at a safe altitude, and then perform a series of approaches at progressively lower approach speeds at approach altitudes until the minimum comfortable speed had been determined. This value was determined by the pilot for a landing weight equal to the weight empty plus 1,000 pounds fuel per engine. The pilot also reported his reason for limiting the approach speed to the value designated. The tests were conducted at a field carrier-landing practice facility maintained by the Navy at Crows Landing, California.

For a few of the configurations, supplementary evaluations were made with the mirror-approach technique in which the pilot guides the airplane along a straight beam of light reflected from a mirror at an appropriate flight-path angle (about $3-1/4^{\circ}$).

Of the four NACA test pilots who participated in the evaluations, pilots A and D had no experience in landing aboard actual carriers. Pilot A is a veteran test pilot with Air Force fighter experience. Pilot D has had field training and practice for carrier landings as a Marine fighter pilot. Pilots B and C are experienced carrier pilots.

RESULTS

Presentation of Data

<u>Aerodynamic characteristics.</u> Plots of angle of attack, drag coefficient, and lift-drag ratio versus lift coefficient, and of drag and power required for level flight versus velocity are shown in figures 2 to 42 for each of the 41 airplane configurations. The equations used for the determination of these curves from recorded flight data are as follows:

$$C_{L} = \frac{W(A_{z} \cos \alpha + A_{x} \sin \alpha) - F_{G} \sin \alpha}{qS}$$

$$C_{D} = \frac{W(A_{z} \sin \alpha - A_{x} \cos \alpha) + F_{G} \cos \alpha - 1.69W_{a}V}{qS}$$



The curves of drag in level flight against velocity were determined from the relationships

$$D = C_D \frac{1}{2} \bar{\rho} S V^2$$

$$\nabla = \sqrt{\frac{1}{2} \rho S(C_{L} + C_{D} \tan \alpha)}$$

Based on the data shown in figures 2 to 42, a number of quantities pertinent to the estimation of approach speed have been determined and are tabulated in table II. These quantities are defined as follows:

CL_{max} values taken from figures 2 to 42

 $v_{S_{C_{L_{max}}}} \sqrt{\frac{w}{C_{L_{max}} \frac{1}{2} \rho S}}$

C_{LmaxPA}

 $C_{L_{max}} + (C_{D_{0.8}C_{L_{max}}}) (sin \alpha_{C_{L_{max}}}), maximum lift coefficient$

with first-order approximation for the effect of the thrust required for level flight

<u>Ψ</u> C_{Lmaxpa} <u>Ξ</u>ρS $v_{S_{PA}}$

V_{Spilot} average carrier-approach stalling speed reported by pilots (The stalling speeds reported by the individual pilots are listed in table III.)

Approach speeds.- In table II the approach speeds predicted by various criteria are listed for all the configurations tested, and in table IV the minimum comfortable approach speeds selected by the individual pilots are listed, together with the average values for all the pilots. The average flight approach speeds are compared with the values predicted by several methods in figure 43, and the approach speeds for the individual pilots are compared with the predicted approach speeds in figures 44 to 51. For the few configurations (4a, 4b, 16a, 16b, 16c) for which the pilots established approach speeds using the mirror-approach technique as well as the landing-signal-officer technique, there were no significant differences in the approach speeds selected; the mirror-approach values are, therefore, not presented here.



The term "minimum comfortable approach speed" as used in this report should be interpreted as the lowest trimmed approach speed which the pilot would deliberately use. It is not the absolute minimum, which is considered to be that speed below which emergency thrust application is needed or the landing approach is aborted. In fact, some speed fluctuations about the minimum comfortable approach speed would be anticipated as a result of attitude changes to adjust altitude. So long as the speed decrease was not too rapid, and the actual value of the speed reduction did not exceed about 5 knots in these maneuvers, the pilot would not feel urgently impelled to return the speed to the trim value. This value of 5 knots may vary somewhat for different configurations, depending on the rate of development of limiting factors and the severity of the limiting factors.

DISCUSSION

Methods for the Prediction of Minimum Comfortable Approach Speed

<u>Stall-speed method</u>.- A number of different methods have been advanced in the past for predicting approach speeds. The most commonly used methods have assumed the approach speed to be a certain percentage of the stalling speed, say 115 percent. A given value for this ratio of approach speed to stalling speed represents a fixed lifting acceleration available for changing flight-path angle, or alternatively a fixed margin of speed above the stall. These methods of predicting approach speed give no consideration to the speed changes that would occur if the throttle were not used in conjuction with the longitudinal control in maneuvering. Several of the criteria of this class considered here differ from each other only in the definition of the stalling speed used.

- (a) For 1.15 $V_{SC_{Imax}}$ the stalling speed is based on the aerodynamic $C_{I_{max}}$ (taken from figs. 2 to 42) with no allowance for the thrust contribution to lift.
- (b) For 1.15 V_{SPA} the stalling speed is based on the addition to the aerodynamic $C_{L_{max}}$ of a first-order estimate of the thrust contribution to the lift. This first-order lift increment is calculated on the assumption that thrust is equal to the drag at the approach speed, the approach speed, in turn, being assumed to occur at 0.8 $C_{L_{max}}$ or at about 0.75 $C_{L_{max}PA}$. The lift increment due to thrust is then computed as:

 $\Delta C_{L_{PA}} = \left(C_{D_{0.8C_{T_{max}}}} \right) \left(\sin \alpha_{C_{L_{max}}} \right)$

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(c) For 1.15 $V_{S_{\text{pilot}}}$ the stalling speed is based on the average stalling speed reported by the pilots. This value was examined as an additional criterion to cover the possibility that the pilots may regard the effective stalling speed as other than the speed corresponding to the maximum lift coefficient. This condition could result from the difficulty in defining the stall as discussed subsequently, or from possible disparities in the amount of thrust effect that should be included in the definition of maximum lift (thrust for level flight at Vg as against thrust for level flight at VPA, for example). Figure 52 shows a comparison of the average values of Vg reported by the pilots with the values of V_S corresponding to $C_{I_{maxpA}}$. The results show that, except for four configurations (6b, 8a, 8b, 12a), the average stalling speeds reported by the pilots agree with computed values within 3-1/2 knots. Considering the readability of airspeed indicators and other factors which make precise determination of stalling speeds difficult (note the dispersion in the values for the individual pilots in table III), this agreement is good verification of the validity of the method of estimating previously described. CLmaxpa

On some of the airplane designs included in this study the manifestations which usually identify a stall occurred only after the airplane had decelerated through a range of speeds wherein other characteristics were deteriorating progressively. The gradually worsening stability and control characteristics or the increase in sink rate with decreasing speed may reach such levels that the pilot considers the airplane "stalled" at a speed higher than the actual stall speed and accordingly limits his operating range to this speed rather than the true stalling speed. Of the configurations listed in table I, the following were indicated by the pilots to have this stall approach characteristic:

Airplane	Configuration	Deteriorating characteristic
F4D	4a, 4b	Sink rate, lateral-directional characteristics
F7U-3	5a, 5d	Sink rate
F-84F	8a, 8b	Sink rate, lateral-directional
E-86F (modified)	12b	Lateral-directional characteristics
F-looa	16a, 16b, 16c	Sink rate, lateral-directional and longitudinal characteristics



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velocity for zero rate of climb

It is noteworthy that the four airplanes for which sink rate was a deteriorating characteristic had curves of drag against velocity that exhibited an extended range of speeds for which the airplane could fly on a steep back side of the curve (figs. 10, 11, 12, 13, 17, 18, 30, 40, 41, and 42). This characteristic would, of course, make for an increase in sink rate with decreasing speed.

<u>Method based on $\dot{\gamma} = 0.060$ </u>. This criterion differs from those previously listed in that it stipulates a fixed capability of producing rate of change of flight-path angle rather than a fixed lifting acceleration capability. The expression for predicting the approach speed for this criterion is developed in Appendix A. It was previously indicated that a fixed ratio of $V_{\rm PA}/V_{\rm S}$ implied a given value of $\Delta A_{\rm Zavail}$. From the basic relationship $\Delta A_{\rm Z} = V\dot{\gamma}$, it is apparent that assumption of a fixed ability to change flight-path angle, $\dot{\gamma}$, will result in calculating greater ratios of approach speed to stalling speed, $V_{\rm PA}/V_{\rm S}$, for higher values of stalling speed VS.

<u>McDonnell method</u>.- A refinement of the criteria listed previously is provided by the McDonnell criterion described in reference 12 which incorporates the effects of drag characteristics. This criterion defines the approach speed as that speed at which a 50-foot climb can be performed with specified conditions of lift and speed changes and with no addition of thrust during the maneuver.

<u>Speed-stability method</u>.- This criterion is simply represented as the speed for minimum drag. The usual variations of drag in level flight with airspeed are such that if the effects of stick-free and stick-fixed longitudinal stability are disregarded, the speed for minimum drag will represent a speed for neutral speed stability, separating a stable region at higher speeds from an unstable region at lower speeds; that is, at speeds higher than that for minimum drag the airplane will return to the trim speed following a disturbance; at lower speeds the airplane will diverge in speed following a disturbance.

With regard to this criterion, reference 13 points out that the minimum drag point loses its significance as a point of neutral speed stability when all the longitudinal degrees of freedom are considered. It is noted further, however, that if the airplane motion is constrained to a constant altitude or to a rectilinear flight path, then the minimum drag point again regains its significance. This constraint condition appears to be a reasonable one to apply to the landing-approach situation, in which case the speed for minimum drag would be the appropriate speed to define neutral speed stability.

<u>Method based on speed for maximum L/D.</u> The speed for maximum L/D may be significant as a criterion in view of the fact that it is the speed corresponding to minimum glide angle, considering only aerodynamic parameters. For this reason it is included among the criteria evaluated herein.



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<u>Method based on speed for minimum power required</u>.- This speed was considered as having possible significance as an indicator of the speed for minimum rate of descent at zero thrust. A factor of 1.08 was used with this speed in order to provide the best agreement between flight approach speeds and the speeds predicted by this method from present tests.

Reasons for Limiting Approach Speed

A number of different terms are used by the pilots as reasons for limiting the approach speed. These are defined more completely in the following section:

(a) Ability to control altitude - Some difficulty has been experienced in defining this reason explicitly, apparently because a number of factors may combine in different ways to produce different airplane responses, all of which the pilot describes by this reason. If the individual factors that produce the response could be isolated, it is possible that this reason would break down into a number of different reasons, each more descriptive than the broader term. As of this time it has not been possible to isolate all the individual factors, and the following description of ability to control altitude must, therefore, be broad enough to reflect the combined effects of all the factors. The term "ability to control altitude" and such synonymous terms as "ability to arrest sink" and "longitudinal control of flight path" are used to describe the condition where there is unsatisfactory response of the airplane to attempts to gain altitude or to produce positive flight-path angle changes. The unsatisfactory altitude controllability has in an isolated instance been identified with deficient response of the airplane to longitudinal control, due to control ineffectiveness, but, in general, as already noted, the responsible factors have not been segregated. The deficient altitude controllability may be, but is not necessarily, associated with large rates of airspeed loss. The throttle may be used in conjuction with aerodynamic controls in maneuvering the airplane to define the altitude controllability, the amount of throttle depending on the relative response of the airplane to aerodynamic and thrust control, and perhaps even more on the inclination of the pilot to rely on the throttle. (This difference in pilot attitude toward reliance on the throttle is, for example, believed to be responsible for some of the disagreements between approach speeds quoted by the Ames test pilots.) However, some aerodynamic maneuvering capability is required by all pilots, and most of them seem to treat aerodynamic control as the dominant control.



In the study reported in reference 9, the predominant reason for limiting approach speed was deterioration of speed stability. Since, in many of the cases studied in the present investigation, rapid changes in airspeed were associated with development of unsatisfactory altitude controllability, it is probable that the reason given in reference 9 corresponds to the general category of reason described herein as "ability to control altitude."

- (b) Stall proximity This term is used to describe the condition where, maneuvering characteristics and all other characteristics of the airplane being satisfactory, the pilot is forced to limit speed because of either stall behavior or stall warning. A stall that was characterized by an abrupt pitching or rolling tendency with inadequate warning might define the speed above which a certain speed margin is demanded by the pilot in the approach; or the existence of stall warning in the form of buffeting, mild pitch-up, or similar controllable motions at speeds well removed from the stall might cause the pilot to select even higher approach speeds, while indicating stall proximity to be the reason for limiting approach speed.
- (c) Unsatisfactory lateral-directional (stability or control) characteristics - The development of erratic or unusual lateraldirectional stability or control characteristics may prevent the pilot from following a desired precise flight course. If these characteristics occurred at a lift coefficient considerably removed from $C_{I_{max}}$, so that they would not tend to be identified with the stalling of the wing, then the pilot might use this term as the reason for limiting approach speed.
- (d) Visibility In steady flight, pitch attitudes attained may be so high that it would be difficult for the pilot to see the landing signal officer or other ground references that the pilot is accustomed to using. In such cases "visibility from the cockpit" would be given as the reason for limiting approach speed.

<u>Reasons in combination</u>.- In some cases approach speeds are described as being limited for other reasons in combination with ability to control altitude (table IV). One possible interpretation for such a case is that either factor alone would have limited the approach speed at the selected value. Another interpretation is that the presence of a number of factors in combination results in a higher approach speed than any one of the factors alone. There is not sufficient information in hand to provide a definitive answer as to which interpretation is correct, or even to state that only one interpretation is generally correct. There is evidence from one case that the presence of a number of factors results in higher approach speeds. The F4D airplane in configurations 4a and 4b had nearly

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identical lift-drag characteristics, but the lateral-directional characteristics of configuration 4b were reported to be considerably worse than those of configuration 4a. Both configurations were described as limited in approach speed primarily by ability to control altitude although the selected approach speeds differed by about 9 knots. The accepted explanation of this paradoxical result is that the attention required of the pilot in controlling lateral-directional disturbances diverts him from the task of monitoring airspeed and flight-path changes so that an additional speed margin is desired.

Of the reasons listed for limiting approach speed, the most prevalent were ability to control altitude and stall proximity. Most of the criteria discussed herein are related to some extent to ability to control altitude. The approach speed of airplanes limited primarily for other reasons would not be expected to be as closely predicted by these criteria. In the comparisons in figures 43 to 51, different symbols are used to distinguish these latter airplanes from those limited by ability to control altitude.

Comparison of Flight and Predicted Approach Speeds

Because of a number of factors, it is considered that the values given for the individual and average flight approach speeds can be relied on only within about 2 knots at best. One source of uncertainty is the fact that pilots cannot, with assurance, report approach speed to the nearest knot; in fact, there is a definite tendency to round the value off to the nearest 5 knots. Ability to read the airspeed indicator to a given increment would be a factor in this regard, as would ability to define a comfortable speed within narrow limits. Differences in evaluation standards among individual pilots would exist even for skilled test pilots and could only be partially compensated for by averaging results. There are recognized differences in control technique among pilots which might also contribute to individual differences. The effects of all these factors are demonstrated by the inconsistency of the differences among various pilots shown by the data in table IV.

To arrive at a figure that would represent acceptable scatter in the comparison of flight and predicted approach speeds, the foregoing factors were borne in mind. An additional factor considered is the existence of secondary reasons for limiting approach speed, discussed in a previous section of this report. With all these factors in mind, it appears that an acceptable criterion would be one that predicted approach speeds within ±5 knots of the average flight value for all applicable configurations.

Inspection of the curves of figure 43 indicates that none of the criteria were successful in predicting approach speeds within ±5 knots for all configurations. For the bulk of the data the best levels of



agreement were obtained with the 1.15 $V_{\rm SPA}$ criterion and a modified form of the McDonnell criterion; the modification, not included in the plotted data, was the subtraction of 2 knots from the speed calculated by the basic criterion, this 2-knot reduction being over and above a 2-knot reduction that was already applied in accordance with the McDonnell method to approximate the effect of thrust on the value of $C_{\rm I_{max}}$. An equivalent level of agreement was also obtained with the 1.15 $V_{\rm Spilot}$ criterion. However, values of the pilots indicated stalling speed are not available for all the configurations, so that the conclusions regarding the validity of this criterion would be less general. The $\dot{\gamma}$ criterion appeared to be better than the other criteria for the airplanes that approach at higher speeds, but was somewhat less consistent for the main body of the data.

The other criteria considered gave less satisfactory correlation with flight values. In particular, the speed stability criterion, V for minimum drag, was shown by several configurations to be inapplicable; for configurations 4a, 4b, 5a, 5b, and 16a, the selected approach speed fell on the back side of the drag-velocity curves, well removed from the speed for minimum drag. This fact is noteworthy since flight on the back side of the curve in the landing approach has long been considered impractical.

The foregoing comparisons indicate that none of the simple criteria considered here enabled predictions to be made within the acceptable limits of ± 5 knots. Until such a criterion is developed it would appear that a reasonable procedure to use in predicting approach speeds would be the use of one of the criteria that gave the best level of agreement, say 1.15 $V_{\rm SPA}$, with the understanding that certain secondary factors might increase or decrease the approach speeds. This general procedure, which is suggested by the comparative results for the F4D airplane (configurations 4a and 4b) discussed earlier, appears to be consistent with the pilots' concepts of the manner in which approach speeds are determined.

To implement this procedure it would be desirable to be able to associate certain numerical increments in approach speed with certain degrees of severity of the secondary factors. The pilots did not feel that they could segregate the effects of the various secondary factors to produce a quantitative correlation. The present data do, however, show consistent qualitative effects which are indicated here. Generally, these factors influence approach speed to the degree that they prevent the pilot from maneuvering with the minimum of attention to monitoring airspeed or altitude. Detrimental factors that would tend to cause increased approach speeds are unfavorable stability and control characteristics, poor visibility from the cockpit, insufficient engine thrust available for maneuvering, or a sharp increase in unstable slope of the drag-velocity curve. As indicated earlier, when these factors become sufficiently pronounced they may be identified as limiting the approach



speed. When they are less severe they may simply modify upward the approach speed predicted by the criterion that defines ability to control altitude.

There are, on the other hand, favorable secondary factors which tend to reduce the approach speeds. On the basis of data in figure 43 for the 1.15 $V_{\rm SPA}$ criterion, for example, it would appear that operative boundarylayer control installations which are powered by bleed air from the primary thrust source reduce approach speeds by amounts greater than would be predicted from the change in VS, the average reduction amounting to about 3 knots. Similarly, it appears that a margin of thrust available for maneuvering of the order of $\Delta T/W = 0.3$ may reduce approach speeds below the level predicted by the criterion.

Other factors may evoke a favorable comment from the pilots, such as good stick-fixed or stick-free longitudinal stability, favorable trim changes with speed or throttle movement, etc. However, at the present time the relative importance of all these factors remains to be established.

Comparison of Test Pilots' and Service Pilots' Approach Speed

The minimum approach speeds presented in this report were obtained by skilled test pilots under relatively favorable conditions of field landings. It is of interest to compare the test values with the approach speed recommended for service pilots. The following table compares the test approach speeds with values recommended in pertinent service publications for the few configurations for which such data are available. Median values of the approach speeds used by fleet pilots in actual carrier operations, as determined from unpublished statistical measurements, are also shown for the two airplanes for which such data are available. Also, since the relationship of the maximum approach speed to the median approach speed is of concern for structural design purposes, the distributions of measured approach speeds as determined from the statistical measurements, are shown for these two airplanes (fig. 53). The latter data are corrected to the landing weights used in the present investigation.

Configu- ration	Airplane	Test carrier- type approach, knots	Minimum recommended service value, knots	Fleet value, knots	Reference for recommended service value	Service type of landing
l	FJ3	112	115	121	AN-01-60JKC-1	Carrier
5a.	F7U-3	107	117	122 ^a	AN-01-45HFD-1A	Carrier
7	F9F-6	114	117		AN-O1-85FGD-1	Carrier
4a.	F4D	121	123		AN-O1-40FBA-1	Carrier
16a.	F-100A	149 to 161	Final 181 Touchdown 148		TO-1F-100A-1	Field
15a.	F-94C	131	Final 144 Touchdown 119		TO-1F-94C-1	Field
8a.	F-84F	132	Over fence 159		TO-1F-84F-1	Field

^a This value is higher than the mean service value given for the same airplane in reference 10. The difference is ascribed to the fact that the data in reference 10 were obtained from service test pilots who were intent on approaching at slow speeds.

The tabulated results and the data in figure 53 indicate that the approach speeds from the present evaluations are consistently lower than the servicerecommended values (which, in turn, are lower than the fleet values). The amounts by which the test values differ from the recommended service values range from about 2 knots to 10 knots for the Navy airplanes. For the Air Force airplanes, assuming, as suggested in reference 6, that the "overthe-fence" speed is equivalent to the carrier-approach speed, and assuming arbitrarily that the "over-the-fence" speed is about 10 knots higher than the touchdown speed, the differences are less consistent, but tend to show even greater departures from the test values. The larger differences between test and service values correspond to the existence of secondary factors of pronounced degree; in the case of the Air Force airplanes, difference in type of approach (field versus carrier) may also be a contributing factor.

CONCLUSIONS

Lift and drag characteristics have been determined in flight in the landing-approach configuration on ⁴l jet-propelled fighter-type airplane arrangements, including various wing boundary-layer-control installations. Minimum comfortable approach speeds for carrier-type landings were evaluated for these configurations by four test pilots. Flight approach speeds for the various configurations ranged from 92 to 157 knots, but the bulk of the data on which the conclusions are based were in the speed range of 95 to 115 knots. As a result of these evaluations the following conclusions were reached:





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1. The reason most frequently given by the pilots for limiting approach speeds was inability to control altitude; the reason given second most frequently was stall proximity.

2. None of a number of simple criteria examined enabled prediction of approach speeds within ± 5 knots for all configurations limited primarily by altitude controllability. A criterion in which the approach speed was assumed to be 115 percent of the power approach stalling speed (1.15 $V_{\rm SPA}$) gave as good agreement with flight values as any of the criteria considered.

3. Departures from predicted approach speeds based on taking 1.15 $V_{\rm SPA}$ were consistent with the presence of "secondary" factors. Favorable secondary factors were indicated to be large thrust margins and operative boundary-layer-control installations that are powered by bleed air from the primary thrust source. (Operation of the boundary-layer control resulted in approach-speed reductions larger than the stalling-speed reductions.) Unfavorable secondary factors included deficient flying qualities characteristics, meager thrust margin, and poor visibility from the cockpit.

4. When unfavorable factors become pronounced at higher speeds, they may become the primary reasons for limiting approach speed, in which case the approach speed would be more than 5 knots higher than would be predicted by 1.15 $V_{\rm SPA}$.

5. Recommended approach speeds from service manuals tend to be higher than the minimum comfortable approach speeds of the present evaluations. The amount of the difference seems to depend on the strength of unfavorable secondary factors.

6. The necessity to fly on the back side of the curve of thrust required against velocity does not of itself impose a limitation on the approach speed. However, the limiting conditions under which such flight is possible remain to be defined.

Ames Aeronautical Laboratory National Advisory Committee for Aeronautics Moffett Field, Calif., Dec. 11, 1957

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APPENDIX A

DEVELOPMENT OF EQUATION FOR PREDICTING APPROACE SPEED FOR CONSTANT VALUE OF $\dot{\gamma}$

At a constant speed equal to the approach speed the vertical acceleration available for maneuvering is given by

$$\Delta A_{z} = \frac{1.69 V_{PA} \dot{\gamma}}{g} = \frac{\Delta C_{L} \frac{\rho}{2} S V_{PA}^{2}}{W}$$
(A1)

where

 $\Delta C_{L} = C_{L_{max}} - C_{L_{PA}}$ (A2)

or

$$\Delta C_{\rm L} = \frac{W}{S} \left(\frac{1}{q_{\rm S}} - \frac{1}{q_{\rm PA}} \right) \tag{A3}$$

Substituting equation (A3) for
$$\Delta C_{L}$$
 in equation (A1), one obtains the following expression for $\dot{\gamma}$

$$\dot{\gamma} = \frac{V_{PA}g}{1.69} \left(\frac{1}{V_S^2} - \frac{1}{V_{PA}^2} \right)$$
(A4)

If the terms are rearranged, an equation relating $V_{\rm PA},\,V_{\rm S},\,$ and $\dot{\gamma}\,$ is found as follows:

$$v_{PA}^2 - 1.69 \frac{\dot{\gamma}}{g} v_S^2 v_{PA} - v_S^2 = 0$$
 (A5)

A value of $\dot{\gamma}$ of 0.060 was found to provide the best general level of agreement between flight approach speeds and the value of $V_{\rm PA}$ as computed from equation (A5); this value of $\dot{\gamma}$ was used in the comparison curves of this report.





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Configu- ration no.	Airplane	Landing veight, including loco 1b fuel per engine, lb	Wing area, sq ft	W/8, 1b/sq ft	Speed. brakes	Flap type	Flap setting, deg	Wing L.E. configuration and flow control devices	HLC type	Opera- tion of BLC	(4) _{avail}	Ref. report	Figur numbe for data
1	PJ-3	13,678	288	47.5	Out	Slotted	45	15° filat	Bope		0.34	1	2
28.	73-3	13,850	268	48.1	Out	Plain	77	15° Slat	Suction flep	On	.31	1	3
26	73-3	13,850	288	48.1	Out	Plain	55	15° Slat	Suction flep	orr	.31	1	+
20	PJ-3	13,850	266	48.1	In	Plain	55	· 15° Slat	Eleving flap	On	-33	1	5
3a	TJ- 3	13,990	302	46.4	In	Flain	55	Extended camber, and fence	Blowing flap .02 norrie	<u>0</u>	.32	1	6
310	FJ-3	13,990	302	46.4	In	Plain	55	Extended cumber, and fence	Blowing flap .01 nozzle	Qm.	•33	1	7
30	FJ-3	13,990	302	46.4	In	Plain	55	Extended camber, and fence	Sustion flap	On	₩3.	1	8
34	FJ-3	13,990	302	46.4	In	Plain	77	Extended camber, and fence	Blowing flay	orr	-35	1	9
44.	F4D ¹	16,870	557	30.3	In	None		10° 81at	Rone		.30		10
40	P*D ²	17,260	>57	32.0	In	Лопе		2-300 Gal. tanks 10° slat	None		.30		ш
<u>3</u> a	F70-3	21,030	535.3	39.3	Та	Kone		61at	None		.14		18
50	170-3	21,030	535-3	39.3	Out	None	Outboard 45	Slat Leading-edge	Blowing		.13		13
<u>6a</u>	P 99-4	13,100	250	52.4	In	Plain	Inboard 40 Outboard 45	flap Leading-edge	flap Bloring	012	.22	2	14
60	FSF-h	13,100	250	2.	In	Plain	Inboard 40 Outboard 30	flep	flap	001	.22	5	15
7	197-6	13,440	300	14.8		Plain	Inboard 40	Slata	Note		.24		16
- 04 - 2h	7-04	15,636	225	40.2	Ont	Flain		Plain	None				18
94	7-86A	12,192	288	42.3	In	Plain	7	15° Slat	Suction	On	.25	3,6	19
50	F-86A	12,192	288	42.3	In	Plain	55	15 ⁰ 81.st	Suntion	off	.24	3,6	20
90	7-85 A	12,192	288	42.3	In	Plain	64	15° Slat	Suction flap	On	.23	3,6	થા
94	7-86A	12,192	288	42.3	In	Flain	64	15° Elst	Suction flap	orr	.24	3,6	22
108.	3-86A	12,335	294	42.9	In	Plain	55	Camber	Suction flap	On	,23	3,6	2 3
105	766A	12,335	294	42.9	In	Pisin	55	Camber	Suction flap	orr	.23	3,6	24
مند	7-86A	12,335	294	42.9	In	Plain	55	Camber, fance	Suction	On	.23	3,6	25
118	y-86a	12,335	294	42.9	In	Flain	55	Camber, fence	Suction flap	orr	.24	3,6	26
2100	Y-86A	12,335	294	42.9	Out	Pisin	64	Camber, fence	Suction flap	On	.23	3,6	27
774	F-86A	12,335	294	42.9	Out	Plain	64	Cambar, fence	Suction flap	Off	.25	3,6	28
12=	F-86P	12,900	288	44.75	• Out	81.otted	38	Plain	Suction L.E.	o∎.	.23	6,4	29
125	7-857	12,900	288	\$4.75	Out	Slotted	38	. Plain	Suction L.E.	orr	.20	4,6	30
13=	F-86F	12,860	288	44.70	Out	Plain	<u></u>	15° ölst	Nowing flag	On	.19	3	31
13Ъ	7-867	12,860	288	44.70	Out	Plain	55	15 ⁰ Slat	Blowing flap	orr	.20	,	32
130	r-86 r	12,860	288	44.70	In	Plain	66	15° älat	flay	On	.19	5	33
13d	F-86F	12,860	258	44.70	In	Plain	66	15 ⁰ Slat	flap	Off	.20	3	34
14a	F-86F	12,860	302	42.6	ъ	Plain	55	Blatted 6-3	flap	orr	.23	5	35
240	F-86F	12,860	302	42.6	In	Plain	7 5	Blatted 6-3	Eloving flap	On	.21	5	36
140	F-86F	12,860	302	42.6	Та	flotted	38	Bletted 6-3	None		.24	5	37
150	P-94C	24,933	233	64.10	In	Split	45	Plain	lione		.ध		38
150	7-9 4C	14,933	233	64.10	Out	Split	45	Plain	lione		.19		39
16 e	P-100A	21,970	400	55.0	In	Plain	0	15 ⁰ 81at	Blowing flap	011	.14		40
160	F-100A	21,970	400	55.0	In	Plain	45	15 ⁰ Slat	Blowing	orr	.09		41

TABLE I.- CONFIGURATIONS OF TEST AIRPLANES

¹External fuel tanks off. ²External fuel tanks on.

7-100A

400

55.0

21,970

16c



45

Plain

Ia

blowing flap

0a

.04

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Gantia	<u> </u>	Ve-	-	<u> </u>			Predicted	landing arrest	web meet 4	for each or	riterion	mote			Opera-
ration	Cr.mr	knote	CLANXPA	V8 _{PK} ' Imote	inots	1.15 VSCI	1.15 V8	1.15 Vepilot	McDonnell.	¥1=0.000	Vostin	(L/D)	1.05 Vhpain	Targe	tion of NLC
1	1.35	101.9	1.41	99.6	96.0	117.2	114.5	210.4	112.1	116.4	109	113.3	111.2	lione	
22.	1.44	99.0	1.72	96.9	96.7	щз.9	111.0	111.2	113.7	118.4	109	113.6	110.2	Sustian flap	04
26	1.37	101.6	1.44	99.0	97. 7	8,811	113.9	112.4	116.5	115.8	ш3.5	121.6	9.غتد	Suction flap	0ff
20	1.54	96.1	1.61	94.1	92.0	111.5	108,2	105.8	109.7	109.2	105	105.6	103.1	floring	011
34	1.58	93.0	1.65	91.2	92 . 7	106.9	104.9	106.6	107.6	105.3	108.5	106.2	101.5	flag	On
30	1.92	95.0	1.58	93.0	98.0	109-3	107-0	105.8	309.0	107.7	105.0	110.0	101.0	Blowing flap	0a
30	1.37	99.8	1.42	96.2	97.7	114.8	112.9	112.4	113.8	114.7	112.0	118.1	113.9	Suntion flap	Qu
34	1.30	106*6	1.36	100.3	98.3	118.0	115.4	113.0	115.9	117.6	118.0	121.1	115.0	flowing flap	027
44.	.80	106.0	.87	102.0		121.9	117.3		126.6	119.8	151.9	154-3	139.3	Rente	
40	.80	107.0	.87	103.0		123.1	118.9		129.8	121.2	165.0	163.2	148.5	Yone	L
	1.27	97.7	1.37	91.8	92.5	109.8	105.6	106.4	114.0	106.2	1.50+		136.0	No:24	L
	1 1 1 9	30.7	1.429	y=.0	¥.7	143.3			114.8	- 09.9	112.0	120.3	щ	Bloging	<u> </u>
6 8.	2.32	81.5	2.44	79.6	81.0	93-7	94.5	93.1	97.8	90.3	96.0	100.5	92.3	11.00	0a
	2.02	87.4	2.12	85.3	90.5	100-5	98.1	104.1	103.3	97.7	106.0	106.9	99.9	fisp	orr
	1.+3	192.0	1.7	1 93-5	712 5	10.6	128.0	103.5	124.7	106.4	129.8	121.2	116.1	Kone	
8		122.0	79	120.0	112.5	160.3	138.0	120.5	136.7	1 2 2	120.4	131-2	128 8	3038	
94	.52 1.51	\$2.0	57	89.1		104.7	102.5		104.6	102.6	105-0	105.3	99.5	Suction	0.
30	1.48	92.0	1.7	89.9		105.8	103.4		105.8	103.7	109.0	113.4	304.8	Suction	orr
9e	1.55	89.7	1.62	87.7		103.2	100.9		103.6	100.8	96.0	100.5	98.3	fiep Suction	On.
94	1.47	92.0	1.53	90.2		105.8	103.7	-	306.0	104.1	107.2	109.5	102.0	Suction	orr
204	1.69	87.5	1.17	83.6		98.3	96.I		100.4	95.3	100.0	103.5	97.6	Surtion	0œ
100	1.51	90.5	1.58	66.5		104.1	101.8		104.3	101.7	105.0	110.1	99.9	Suction	001
<u>)]</u>	1.42	93.3	1.47	91.7	91.7	107-3	105.5	105.5	106.6	105.9	101.2	104.2	105-7	Suction flag	06
шь	1.36	95.3	1.41	93.6	94.8	109.6	107.6	109.0	109.8	106.4	110.0	112.3	111.8	Suction	022
De	L\$3	93.0	1.48	91.4	_	107.0	105.1		106.1	105.5	99.0	102.4	102.6	Suction flag	Oa
114	1.33	96.4	1.37	95.0		9.مدد	109.3	—	110.3	110.3	108.4	111.2	110.7	Suction fier	orr
12.	1.79	65.9	1.89	83.5	89.0	98.8	96.0	202.4	108_1	95.4	ш. 	116.6	107-3	Suction L.S.	On
120	1.10	109.4	1.14	107.4	106.3	125.8	123.5	192.2	122.5	127.5	121.0	122.5	124.7	Stotion	ore
134	1.58	92.5	1.65	89.4	88.5	105.2	102.8	101.8	104.8	103.0	90.4	94.7	96.7	flowing flop	0=
139	1.40	97-3	1.47	9 4 -7	92.5	111.9	106.9	106.4	110.7	170-0	102.3	104.9	104.8	Blowing flag	110
13e	1.59	92.2	1.67	88.8		104.9	102.1		105.0	108.2	90.5	92.6	95.6	Noving flap	On
134	1.44	97.9	1.50	93-7		110.3	107.8		109.9	108.7	103.0	111.6	105.3	floring flag	011
144	1.42	9*.0	1.47	92.5	9 1. 7	108.0	106.4	105.5	107.7	107.1	103.8	106.4	206.4	Hoving flag	œr
145	1.59	88.8	1.65	87.1	86.0	102.1	100.2	98.9	102.5	3.00.0	93.0	96.6	97.2	floring flep	On.
IMa_	1.41	94.0	1.47	92.5	89.7	108.0	106.4	103.1	108.6	107.1	227.5	119.4	109.1	Bone	
15	1.49	112.6	1.74	110.6	110.7	129.5	127.9	327.3	125.2	131.9	123.8	126.6	124.2	Tone	
156	1.44	ш . ,	1.49	212.6	110.7	131.5	129.5	127-3	126.4	134.8	120.0	120.8	124.7	None	
168.	1.07	120.4	1.16	115.5		138.5	132.8		143.0	138.4	173.5	186.2	154-0	flag	orr
165	1.14	116.5	1.23	118.3		134.0	129.1		137-3	133-9	150.0	157-8	139.9	flep	orr
160	1.26	110.9	1.36	106.7		127.5	188.7		129.5	க	145.0	151.0	127.0	1147	0n

TABLE II.- AERODYNAMIC DATA AND CARRIER LANDING APPROACH-SPEED CRITERIA FOR EACH CONFIGURATION





	Calib	orated sta	lling	, spee	d, knots		Calibrated stalling speed, knots				
Configu- ration	Ir	dividual	pilot	s	Average	Configu- ration	Ind	lividual	pilot	8	Average of
10.	A	в	C	D	V _S pilot	що.	A	B	С	D	pilots, V _S pilot
1 2a 2b 2c 3a 3b 3c 3d	96 94 91 99 102	96 95 96 92 92 92 95 93	96 97 98 92 93 93 99 95	98 99 	96.0 96.7 97.7 92.0 92.7 92.0 97.7 98.3	10a 10b 11a 11b 11c 11d 12a 12b	90 94 92 118	92 95 86 97	89 94 90 112	96 96 88 104	91.7 94.8 89.0 106.3
44 15 15 64 610 7 84 88 94 19 05	90-95 90-95 82 90 88 114 114	95 95 77 90 93 110-114 110-114	99889844	84 92 114 114	92.5 92.5 81.0 90.5 90.0 113.5 113.5	13ª 130 1334 140 140 150 166 166	83 3 1 8 5 8 5 8 5 8 5 8 5 8 5 7 3 1 1 1	88 92 93 86-88 89 109 109 	88 92 92 92 86 91 110 110	90 93 	88.5 92.5 91.7 86.0 89.7 110.7 110.7
9a.											

TABLE III.- FLIGHT DETERMINED STALLING SPEED



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TABLE	IV	CARRIER	LANDING-A	APPROACH	SPEEDS	AND	REASONS	FOR	LIMITING
		AS 1	DETERMINEI) FROM FI	JGHT EV	VALUA	TIONS		

	Cali	brated	appro	ach	Average of pilots						
Configu-	mry	reason	for 1	imit-		Bees	on for				
ration	ing	appro	ach sp	eed.	approach speed.	Limitin	g approach need	Remarks			
			al pil	.01. 	imote			+			
	A	В	C	4		Primary	Secondary				
	-113	-111	-113	2006	1112			Powerful thrust mirgin contributes to improved situate controllability.			
24		-108	-106	-106	107	(2)					
25		-108	-110	-108	109	(2)	(1)				
20	-102	2	-103		103	(1)					
38	2.03	1.02	-102		102	(2)					
3b	-100	-105	-102		104	(2)					
3c	101	-109	-101		106	(2)	(1)	•			
34	-112	-109	-112		1111	(#)	(1)				
48	120	1118	¹ 124	122	121	(1)	(3)	Four lateral-directional characteristics at Low speeds affect approach speed. Powerful thrust margin.			
475	¹ 135	128	² 130	¹ 125	130	(1)	(3)	Interal-directional characteristics considered even worse with tanks on then with tanks off. Powerful thrust margin.			
54	107	107	109 ¹ 109		108	(1)		$\Delta T/V$ marginal at gross weights greater than these of present evaluation.			
<u>5</u> 0	107	-107	-109	<u> </u>	108	(1)		Same as configuration 5a.			
<u>6a</u>	-95	*87	-196	-191	92	(1)	(2,4,3)				
66	103	-100	*107	-100	103	(1)	(4)				
7	² 11*	1 11)	¹ ЛТ#		114	(1)	(a)	For intersi-directional characteristics at low speeds objectionable. Effect on approach speed uncertain.			
8a.	032	J130	¹ 136	¹ 133	132	(1)	(2,3)	Airplane yaws abruptly during flare. Elevator control force characteris- tics poor.			
80	130	730	1136	133	132	(1)	(2)	Same as configuration 8s.			
94	103	- 98	105	104	103	(1)					
<u>9</u> b	0110	-105	-112	-108	109	(1)					
<u>9</u> 0	-100	100		101	100	(1)					
94	105	-108		7105	106	(1)					
10a		- 39	-108	105	104	(1)		······			
106	110	-105	-115	-113	<u> </u>	(1)		/ ////////////////////////////////////			
11.	108	105	106	2115 8	107	(1)	(=)				
1116	2125	¹ 108	1119	² 112	113	(1)	(8)				
11c	1102	J105	¹ 107	² 102	103	(1)	(5)				
114	סור	1111	1112	°109	<u> </u>	(1)	(=)				
12a	°107	103	5112	107 ¹	107	(s)	(1)	Ability to control altitude and visibility from cockpit were of approxi- mately equal importance in defining approach speed.			
120	² 129	² 129	² 129	~ 134	130	(2)		Airplane yave abruptly during flare.			
<u>13e</u>	298	797	°99	98	98	(2)	(1)				
133	111	7777	112	-108	111	(1)					
130	*98	797	[*] 99	¹ 98	98	(2)					
134	111	7117	115	801 ¹	ш	(1)					
14a	² 103	~101	סנר		105	(2)	(1,5)				
146	295	° 96	° 97		96	(2)	(1)				
14c	105	² 106	¹ 106		106	(1)	(2,5)				
15a	¹ 137	* 132	-		131	(1)	(4.5)	Although evaluated with both brakes in and brakes out only by pilot B, pilots A and C believe that same approach speeds would apply to both			
150		4135	125				·	consigurations; mance, only one average approach speed presented for both configurations.			
168	-161	-149	160		157,	(1)	(3,5)				
160	149	138	149	*142	145	(1)	(3,4,5)	AT/W marginal			
16c	¹ 135	¹ 30	¹ 137	¹ 133	134	(1)	(B)4)	Same as configuration 16b.			

² Ability to control altitude or errest rate of sink. ² Proximity to stall or other instability. ³ Tateral-directional stability or control characteristics. ⁴ Longitudinal control. ⁶ Visibility from cockpit.



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(a) FJ-3 airplane.

Figure 1.- Two-view drawing of the test airplanes.













- (c) F7U-3 airplane.
- Figure 1.- Continued.

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- (d) F9F-4 airplane.
- Figure 1.- Continued.



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(e) F9F-6 airplane.





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- (f) F-84F airplane.
- Figure 1. Continued.







(g) F-86A and F-86F airplanes.





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(h) F-94C airplane.

Figure 1.- Continued.









Figure 1.- Concluded.





(a) Variation of lift coefficient with angle of attack, drag coefficient, and lift-drag ratio.
Figure 2.- Aerodynamic characteristics of the FJ-3 airplane; slotted flap, δ_f = 45⁰, leading-edge slats (config. 1).

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(c) Variation of horsepower required for level flight with velocity.

Figure 2.- Concluded.

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(a) Variation of lift coefficient with angle of attack, drag coefficient, and lift-drag ratio. Figure 4.- Aerodynamic characteristics of the FJ-3 airplane; plain flap, $\delta_{f} = 55^{\circ}$, leading-edge slats (config. 2b).

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(c) Variation of horsepower required for level flight with velocity.

Figure 4.- Concluded.







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Figure 5.- Concluded.







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(c) Variation of horsepower required for level flight with velocity. Figure 6.- Concluded.







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(b) Variation of airplane drag with velocity.

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(c) Variation of horsepower required for level flight with velocity.

Figure 7.- Concluded.





(a) Variation of lift coefficient with angle of attack, drag coefficient, and lift-drag ratio. Figure 8.- Aerodynamic characteristics of the FJ-3 airplane; plain flap, $\delta_{\rm f} = 55^{\circ}$, leading-edge camber, fence, suction-flap BLC (config. 3c).

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(c) Variation of horsepower required for level flight with velocity.

Figure 8. - Concluded.







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(a) Variation of lift coefficient with angle of attack, drag coefficient, and lift-drag ratio. Figure 9.- Aerodynamic characteristics of the FJ-3 airplane; plain flap, $\delta_{f} = 55^{\circ}$, leading-edge camber, fence (config. 3d).

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Figure 9.- Concluded.





(a) Variation of lift coefficient with angle of attack, drag coefficient, and lift-drag ratio. Figure 10.- Aerodynamic characteristics of the F4D airplane; leading-edge slats (config. 4a).

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(c) Variation of horsepower required for level flight with velocity.





(a) Variation of lift coefficient with angle of attack, drag coefficient, and lift-drag ratio. Figure 11.- Aerodynamic characteristics of the F4D airplane; leading-edge slats, tanks (config. 4b).

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Figure 11.- Concluded.





(a) Variation of lift coefficient with angle of attack, drag coefficient, and lift-drag ratio. Figure 12.- Aerodynamic characteristics of the F7U-3 airplane; leading-edge slats (config. 5a).

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Figure 12.- Concluded.



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(a) Variation of lift coefficient with angle of attack, drag coefficient, and lift-drag ratio. Figure 13.- Aerodynamic characteristics of the F7U-3 airplane; leading-edge slats, speed brakes (config. 5b).

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Figure 14.- Concluded.

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(a) Variation of lift coefficient with angle of attack, drag coefficient, and lift-drag ratio. Figure 16.- Aerodynamic characteristics of the F9F-6 airplane; plain flap, δ_{f} = 40°, δ_{f} outboard = 30°, leading-edge slats (config. 7).

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Figure 16. - Concluded.

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(a) Variation of lift coefficient with angle of attack, drag coefficient, and lift-drag ratio. Figure 17.- Aerodynamic characteristics of the F-84F airplane; plain flap, $\delta_f = 40^\circ$ (config. 8a).

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Figure 17.- Concluded.



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(a) Variation of lift coefficient with angle of attack, drag coefficient, and lift-drag ratio. Figure 18.- Aerodynamic characteristics of the F-84F airplane; plain flap, $\delta_f = 40^{\circ}$, speed brakes (config. 8b).

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Figure 18.- Concluded.



(a) Variation of lift coefficient with angle of attack, drag coefficient, and lift-drag ratio. Figure 19.- Aerodynamic characteristics of the F-86A airplane; plain flap, $\delta_f = 55^{\circ}$, leading-edge slats, suction-flap BLC (config. 9a).

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(c) Variation of horsepower required for level flight with velocity. Figure 19.- Concluded.





(a) Variation of lift coefficient with angle of attack, drag coefficient, and lift-drag ratio. Figure 20.- Aerodynamic characteristics of the F-86A airplane; plain flap, $\delta_f = 55^{\circ}$, leading-edge slats (config. 9b).

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(c) Variation of horsepower required for level flight with velocity.

Figure 20.- Concluded.


(a) Variation of lift coefficient with angle of attack, drag coefficient, and lift-drag ratio. Figure 21.- Aerodynamic characteristics of the F-86A airplane; plain flap, $\delta_{f} = 64^{\circ}$, leading-edge slats, suction-flap BLC (config. 9c).

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Figure 21.- Concluded.



(a) Variation of lift coefficient with angle of attack, drag coefficient, and lift-drag ratio. Figure 22.- Aerodynamic characteristics of the F-86A airplane; plain flap, $\delta_f = 64^\circ$, leading-edge slats (config. 9d).

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(c) Variation of horsepower required for level flight with velocity.

Figure 22.- Concluded.





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Figure 24.- Concluded.

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(a) Variation of lift coefficient with angle of attack, drag coefficient, and lift-drag ratio. Figure 25.- Aerodynamic characteristics of the F-86A airplane; plain flap, $\delta_f = 55^{\circ}$, leading-edge camber, fence, suction-flap BLC (config. lla).

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Figure 25.- Concluded.





(a) Variation of lift coefficient with angle of attack, drag coefficient, and lift-drag ratio. Figure 26.- Aerodynamic characteristics of the F-86A airplane; plain flap, $\delta_{f} = 55^{\circ}$, leading-edge camber, fence (config. llb).







Figure_26.- Concluded.

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(c) Variation of horsepower required for level flight with velocity.

Figure 27.- Concluded.



(a) Variation of lift coefficient with angle of attack, drag coefficient, and lift-drag ratio. Figure 28.- Aerodynamic characteristics of the F-86A airplane; plain flap, $\delta_f = 64^{\circ}$, leading-edge camber, fence (config. 11d).

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(a) Variation of lift coefficient with angle of attack, drag coefficient, and lift-drag ratio. Figure 29.- Aerodynamic characteristics of the F-86F airplane; slotted flap, $\delta_f = 38^{\circ}$, suction leading-edge BLC (config. 12a).

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Figure 29.- Concluded.



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(a) Variation of lift coefficient with angle of attack, drag coefficient, and lift-drag ratio. Figure 30.- Aerodynamic characteristics of the F-86F airplane; slotted flap, $\delta_{f} = 38^{\circ}$ (config. 12b).



(c) Variation of horsepower required for level flight with velocity.







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(c) Variation of horsepower required for level flight with velocity.

Figure 31. - Concluded.





(a) Variation of lift coefficient with angle of attack, drag coefficient, and lift-drag ratio. Figure 32.- Aerodynamic characteristics of the F-86F airplane; plain flap, $\delta_f = 55^{\circ}$, leading-edge slats (config. 13b).





(c) Variation of horsepower required for level flight with velocity. Figure 32.- Concluded.

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Figure 33.- Concluded.



(a) Variation of lift coefficient with angle of attack, drag coefficient, and lift-drag ratio. Figure 34.- Aerodynamic characteristics of the F-86F airplane; plain flap, $\delta_{f} = 66^{\circ}$, leading-edge slats (config. 13d).

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V, knots



Figure 34.- Concluded.

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(a) Variation of lift coefficient with angle of attack, drag coefficient, and lift-drag ratio. Figure 35.- Aerodynamic characteristics of the F-86F airplane; plain flap, $\delta_{f} = 55^{\circ}$, 6-3 slatted leading edge (config. 14a).

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(c) Variation of horsepower required for level flight with velocity. Figure 36.~ Concluded.







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V, knots

(c) Variation of horsepower required for level flight with velocity.

Figure 37.- Concluded.



(a) Variation of lift coefficient with angle of attack, drag coefficient, and lift-drag ratio. Figure 38.- Aerodynamic characteristics of the F-94C airplane; split flap, $\delta_{f} = 45^{\circ}$ (config. 15a).

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Figure 38.- Concluded.

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(a) Variation of lift coefficient with angle of attack, drag coefficient, and lift-drag ratio. Figure 39.- Aerodynamic characteristics of the F-94C airplane; split flap, $\delta_{f} = 45^{\circ}$, speed brakes (config. 15b).

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(a) Variation of lift coefficient with angle of attack, drag coefficient, and lift-drag ratio. Figure 40.- Aerodynamic characteristics of the F-100A airplane; leading-edge slats (config. 16a).

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V, knots

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(a) Variation of lift coefficient with angle of attack, drag coefficient, and lift-drag ratio. Figure 41.- Aerodynamic characteristics of the F-100A airplane; plain flap, $\delta_f = 45^{\circ}$, leading-edge slats (config. 16b).



(c) Variation of horsepower required for level flight with velocity.

Figure 41.- Concluded.

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Figure 42. - Concluded.

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- Ability to control altitude No BLC
- Ability to control altitude BLC operative
- Stall proximity No BLC
- Stall proximity BLC operative
- △ Factors other than ability to control altitude or stall proximity







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Reasons for limiting approach speed

- Ability to control altitude No BLC 0
- Ability to control altitude BLC operative
- Stall proximity No BLC
- Stall proximity BLC operative
- Factors other than ability to control altitude or stall proximity Δ





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150

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- Ability to control altitude No BLC
- Ability to control altitude BLC operative
- □ Stall proximity No BLC
- Stall proximity BLC operative
- △ Factors other than ability to control altitude or stall proximity





Figure 44.- Comparison of flight approach speeds for individual pilots with values predicted from 1.15 $V_{S_{C_{L_{max}}}}$ approach-speed criterion.



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Reasons for limiting approach speed

- Ability to control altitude No BLC
- Ability to control altitude BLC operative
- Stall proximity No BLC
- Stall proximity BLC operative
- △ Factors other than ability to control altitude or stall proximity







Figure 45.- Comparison of flight approach speeds for individual pilots with values predicted from 1.15 V_{SPA} approach-speed criterion.





- Ability to control altitude No BLC
- Ability to control altitude BLC operative
- □ Stall proximity No BLC
- Stall proximity BLC operative
- △ Factors other than ability to control altitude or stall proximity



Figure 46.- Comparison of flight approach speeds for individual pilots with values predicted from 1.15 V_S approach-speed criterion.



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Reasons for limiting approach speed

- O Ability to control altitude No BLC
- Ability to control altitude BLC operative
- □ Stall proximity No BLC
- Stall proximity BLC operative
- △ Factors other than ability to control altitude or stall proximity



Figure 47.- Comparison of flight approach speeds for individual pilots with values predicted from the McDonnell approach-speed criterion.

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- Ability to control altitude No BLC
 - Ability to control altitude BLC operative
- Stall proximity No BLC
- Stall proximity BLC operative
- A Factors other than ability to control altitude or stall proximity





Figure 48.- Comparison of flight approach speeds for individual pilots with values predicted from the rate of change of flight-path-angle $(V_{\dot{\gamma}=0.080})$ approach-speed criterion.



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- O Ability to control altitude No BLC
- Ability to control altitude BLC operative
- Stall proximity ~ No BLC
- Stall proximity BLC operative
- A Factors other than ability to control altitude or stall proximity



Flight approach speed, knots

Figure 49.- Comparison of flight approach speeds for individual pilots with values predicted from minimum-drag approach-speed criterion.





- Ability to control altitude No BLC
- Ability to control altitude BLC operative
- Stall proximity No BLC
- Stall proximity BLC operative
- △ Factors other than ability to control altitude or stall proximity



Figure 50.- Comparison of flight approach speeds for individual pilots with values predicted from maximum lift-drag ratio approach-speed criterion.



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- O Ability to control altitude No BLC
- Ability to control altitude BLC operative
- Stall proximity No BLC
- Stall proximity BLC operative
- △ Factors other than ability to control altitude or stall proximity



Figure 51.- Comparison of flight approach speeds for individual pilots with values predicted from minimum-horsepower approach-speed criterion.



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Figure 52.- Comparison of pilot-average stall speed with calculated powerapproach stall speed.



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