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LIST OF ACRONYMS

AIR	Atmospheric Instrument Research (Inc.)
AIRS	Atmospheric Infrared Sounder
AMPR	Advanced Microwave Precipitation Radiometer
AMSU-A	Advanced Microwave Sounding Unit - A
CAMEX	Convection And Moisture EXperiment
CaPE	Convection and Precipitation/Electrification [experiment]
CLASS	Cross-Chain Loran Atmospheric Sounding System
COARE	Coupled Ocean Atmosphere Response Experiment
DAAC	Data Acquisition and Archive Center
DMSP	Defense Meteorological Satellite Program
EDOP	ER-2 Doppler Radar
EOS	Earth Observing System
GB-HIS	Ground Based HIS
GSFC	Goddard Space Flight Center
GMT	Greenwich Mean Time
HIS	High Resolution Interferometer Sounder
LIP	Lightning Instrument Package
MAMS	Multispectral Atmospheric Mapping Sensor
Meteosat	Meteorological Satellite
MIR	Millimeter Imaging Radiometer
MSFC	Marshall Space Flight Center
MTS	Millimeter-Wave Temperature Sounder
NASA	National Aeronautics and Space Administration
NCDC	National Climate Data Center
NOAA	National Oceanic and Atmospheric Administration
SPANDAR	S-band Radar
SSEC	Space Science Engineering Center (Univ. of Wisconsin)
SSM/I	Special Sensor Microwave/Imager
SSM/T-2	Special Sensor Microwave/Temperature Version 2
TOGA	Tropical Oceans, Global Atmospheres
USAF	United States Air Force
WFF	Wallops [Island] Flight Facility

TECHNICAL MEMORANDUM

OPERATIONS SUMMARY FOR THE CONVECTION AND MOISTURE EXPERIMENT (CAMEX)

SECTION I. INTRODUCTION

This report describes the activities during the Convection And Atmospheric Moisture Experiment (CAMEX), a NASA funded science experiment carried out at Wallops Island, VA from September 8, 1993 to October 7, 1993. CAMEX was a multidisciplinary experiment designed to measure the three-dimensional moisture fields over the Wallops Flight Facility (WFF) and to characterize the multifrequency radiometric signature of tropical convection over the Gulf Stream and southeastern Atlantic Ocean.

For ease in relating CAMEX activities that occur on the same local day but different GMT days, it seemed convenient and beneficial to define a special CAMEX day. Each CAMEX day began at 1200 GMT and continued for 24 hours. Thus, all activities that occurred (begin) on the same local day have the same CAMEX day. Table 1 shows the relationship between the CAMEX days and the GMT and local (Wallops Island, VA) dates. CAMEX day 1 began at 1200 GMT, September 7, 1993, and ended at 1159 GMT, September 8, 1993; this date was chosen to coincide with the onset of the Raman lidar studies. The ER-2 arrived at Wallops on CAMEX day 6.

CAMEX	LOCAL DAY	GMT DAY	GMT DAY
DAY	L	START	END
1	7-Sep	7-Sep	8-Sep
2	8-Sep	8-Sep	9-Sep
3	9-Sep	9-Sep	10-Sep
4	10-Sep	10-Sep	11-Sep
5	11-Sep	11-Sep	12-Sep
6	12-Sep	12-Sep	13-Sep
7	13-Sep	13-Sep	14-Sep
8	14-Sep	14-Sep	15-Sep
9	15-Sep	15-Sep	16-Sep
10	16-Sep	16-Sep	17-Sep
11	17-Sep	17-Sep	18-Sep
12	18-Sep	18-Sep	19-Sep
13	19-Sep	19-Sep	20-Sep
14	20-Sep	20-Sep	21-Sep
15	21-Sep	21-Sep	22-Sep
16	22-Sep	22-Sep	23-Sep
17	23-Sep	23-Sep	24-Sep
18	24-Sep	24-Sep	25-Sep
19	25-Sep	25-Sep	26-Sep
20	26-Sep	26-Sep	27-Sep
21	27-Sep	27-Sep	28-Sep
22	28-Sep	28-Sep	29-Sep
23	29-Sep	29-Sep	30-Sep
24	30-Sep	30-Sep	1-Oct
25	1-Oct	1-Oct	2-Oct
26	2-Oct	2-Oct	3-Oct
27	3-Oct	3-Oct	4-Oct
28	4-Oct	4-Oct	5-Oct
29	5-Oct	5-Oct	6-Oct
30	6-Oct	6-Oct	7-Oct
31	7-Oct	7-Oct	8-Oct

Table 1. Relationship between the 31 CAMEX experiment days and the GMT and local (Wallops Island, VA) dates

-

A. CAMEX Mission Resources

CAMEX resources included ER-2 data gathering missions using the instruments listed in Table 2, a Raman lidar operated at WFF, the Univ. of Wisconsin surface High Resolution Interferometer Sounder (called the GB-HIS), and a series of rawinsonde balloon launches from WFF and a Univ. of Wisconsin deployed CLASS site. In addition CAMEX was supported by the SPANDAR radar at the WFF and an ocean research vessel (the "Chessie") provided by Johns Hopkins Marine Research Center. The "Chessie" carried a tether-sonde system capable of profiling the lower atmosphere to 1 km.

Instrument	PI, Institution	Discipline	Data Parameters
High Resolution Interferometer Sounder (HIS)	Smith, U. Wis.	Dynamics, AIRS	Temperature and moisture soundings
Advanced Microwave Precipitation Radiometer (AMPR)	Spencer, MSFC Hood, MSFC	Convection, SSM/T-2	High resolution, multifrequency sampling of precipitation
Millimeter Imaging Radiometer (MIR)	Wang, GSFC Racette, GSFC	Convection, SSM/T-2	Cloud structure, water vapor, cirrus ice particle size and distribution
Microwave Temperature Sounder (MTS)	Staelin, MIT Schwartz, MIT	Convection, SSM/T-2	Precipitation, temperature profiling
ER-2 Doppler Radar (EDOP)	Heymsfield, GSFC	Convection	Vertical air motion, precipitation, structure; and mass and heat budgets
Lightning Instrument Package (LIP)	Blakeslee, MSFC	Convection	Electrical fields and air conductivity
Multispectral Atmospheric Mapping Sensor (MAMS)	Jedlovec, MSFC Guillory, MSFC	Convection, AIRS	Cloud top temperatures, water vapor and intercomparisons

Table 2. CAMEX ER-2 instruments

B. CAMEX Mission Objectives

The science objectives during CAMEX were as follows:

(1) Measurements of temperature, water vapor, clouds, precipitation, and electrical fields associated with tropical convection

(2) SSM/T-2 instrument validation and calibration

(3) Radiometric signatures of clear air and precipitation at high incidence angles

(4) High resolution vertical and horizontal measurement of the temperature and moisture field as well as top of the atmosphere radiances over WFF

(5) Indepth study of the low-level vertical temperature and moisture gradients and their relation to anomalous radar propagation.

The second and third objectives derived from a United States Air Force (USAF) request to underfly the DMSP F-11 satellite with the Millimeter Imaging Radiometer (MIR) and the Advanced Microwave Precipitation Radiometer (AMPR). The MIR and AMPR radiometric channels closely mirror those on the USAF's Special Sensor Microwave Temperature (SSM/T-2) and Special Sensor Microwave Imager (SSM/I). Underflights of the F-11 satellite were originally planned for the Tropical Oceans, Global Atmosphere-Coupled Ocean Atmosphere Response Experiment (TOGA COARE) but were rescheduled to coincide with CAMEX.

The fourth objective was designed to satisfy a requirement for very high quality "near top of the atmosphere" radiance spectra with associated temperature and water vapor profile ground truth. The data are necessary to validate and improve radiative transfer calculations over the spectral region to be observed by the EOS AIRS instrument.

The first three objectives closely mirror those of the NASA TOGA COARE program, and as such, CAMEX is an extension of NASA's TOGA COARE science efforts.

C. Facilities and Personnel

Program oversight and funding for CAMEX was provided by Ramesh Kakar, Code YS, NASA Headquarters. James Arnold, Marshall Space Flight Center (ES43), served as the field operations director and was responsible for coordination of support requirements with the WFF. The CAMEX project scientist was James Wang, Code 975, Goddard Space Flight Center, assisted by Vanessa Griffin and Robbie Hood, Marshall Space Flight Center (ES43). The ER-2 mission director was Jim Barrieaux, AMES Research Center. Judy Killmon and Joan Selby, Wallops Flight Facility, were the CAMEX focal points for support arrangements.

CAMEX was held at the NASA Wallops Island Flight Facility (WFF). WFF facilities support included hangar space for operations of the ER-2 and office space for the air crew, instrument teams, and project managers. WFF ground support included rawinsonde balloon launches at the direction of Francis Schmidlin, and SPANDAR radar support under the direction of Norris Beasley. Additional help was provided by the WFF weather, communications, radar tracking, and control facilities.

The Univ. of Wisconsin operated a CLASS mobile rawinsonde at the Chesser Farm about 3 miles west of Wallops Island. The Univ. of Wisconsin operated the GB-HIS a surface based high resolution interferometer from Wallops Island, collocated with the Raman lidar, operated by GSFC. Johns Hopkins Marine Research Center provided a small ocean-going research vessel, the "Chessie," to assist in measuring the lower atmospheric temperature and moisture profiles and the influence of temperature and moisture inversions on anomalous radar propagation. The "Chessie" was operated about 5 nm off shore east of Wallops Island, along a direct line extending from the CLASS site through the lidar site.

SECTION II. INSTRUMENT OVERVIEWS

There were seven instruments (listed in Table 2) onboard the ER-2 during CAMEX and two instruments provided ground truth. This section provides a short synopsis of each instrument's objectives and preliminary results along with samples of the data archive from each instrument. The sample data are provided for general interest only, and in most cases have not been quality controlled and should therefore not be used for scientific purposes. The actual data will be available from the instrument PI's and can be obtained by contacting them directly.

A. AMPR

1. <u>Instrument Description</u>. The Advanced Precipitation Microwave Radiometer (AMPR) is a four-channel scanning total power radiometer which measures the passive microwave signatures of the Earth's surface at 10.7, 19.35, 37.1, and 85.5 GHz. The AMPR is designed to fly aboard NASA's ER-2 high altitude aircraft platform.

2. <u>CAMEX Objectives</u>. The AMPR collected data during the CAMEX to accomplish several scientific goals.

(A) The first was to provide data to scientists of the Phillips Laboratory for calibration and validation of the DMSP SSM/I and SSM/T-2 sensors. An underflight of the SSM/T-2 F-11 satellite by the AMPR for comparison of the 91 GHz SSM/T-2 channel and the 85.5 GHz AMPR channel was planned. The sampling of a convective rain system by the AMPR at high incidence angle was also desired to simulate the characteristics the SSM/I. Since the AMPR scans +/- 45° through nadir, this high incidence angle was to be accomplished by banking the ER-2 at a 20° angle during data collection sorties.

(B) A second scientific objective of the AMPR data collection during CAMEX was to sample oceanic precipitation. New external calibration loads had been installed in the AMPR system in September 1992. Previously, oceanic precipitation data off the west and east coasts of Florida had been collected using older calibration loads. Tropical precipitation in the Pacific Ocean using the new calibration loads had also been sampled by the AMPR during the TOGA COARE. Oceanic rain data collected over U.S. coastal waters were needed to correlate the findings of the TOGA COARE Pacific Ocean data with the previous data collected using the old calibration loads.

3. <u>Preliminary Data</u>. The AMPR performed exceptionally well during CAMEX. Data were collected of tropical precipitation systems of varying size. Figure 1, Figure 2, and Figure 3 are examples of data collected during CAMEX during different atmospheric conditions. Instrument performance was nominal, with the exception of interference in the 10 GHz data due to the EDOP instrument. Data containing the interference were collected during two CAMEX flights to assist in post-mission analysis of the interference problem.



Figure 1. AMPR imagery of Cape Hatteras, September 30, 1993.



Figure 2. AMPR imagery of light rain over ocean, September 30, 1993.



Figure 3. AMPR imagery of thunderstorm over ocean, October 5, 1993.

B. ER-2 Doppler Radar (EDOP)

1. <u>Instrument Description</u>. EDOP is an X-band fully-coherent pulsed-Doppler radar in the nose of the ER-2. It has two antennas: one nadir-pointing with pitch stabilization, and the other forward pointing. EDOP during CAMEX was configured to map time-height sections of reflectivity from the nadir and forward beams. The forward beam in addition measures linear depolarization ratio (LDR) which provides useful information on the cloud microphysical properties. The characteristics of EDOP are shown in Table 3.

Frequency	9.72 GHz
Wavelength	3.07 cm
Peak transmit power	20 kW
Pulse repetition frequency	2.2 or 4.4 kHz
Pulse widths/range resolution	0.25, 1.0 micro-sec/37.5, 150 m
Antenna beamwidths	2.9°

Table 3.	EDOP	characteristics
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The data system for EDOP consists of data acquisition from three logarithmic (forward and nadir co-polarization reflectivity and forward cross-polarization reflectivity) and four linear (forward and nadir Doppler) channels. The CAMEX configuration collected raw data from the three reflectivity channels through most of the experiment, with the exception of the ferry flight (9/12/93) during which reflectivity processing was tested.

2. <u>EDOP CAMEX Objectives</u>. CAMEX provided the first EDOP measurements of precipitation. Thus, the main objective was to perform extended engineering flights to characterize the system performance. The end-to-end system performance could best be evaluated during data flights, where actual precipitation was probed. Issues such as the stability of the calibration with thermal changes of instrument, the performance of the antennas and data system, etc., were evaluated. Also, if possible, it was desired to perform a calibration flight over the ocean, using special calibration software which would preclude normal data collection. If the flights provided scientific quality data, the second goal was to study structure of precipitation systems using joint radar/microwave data with EDOP, MIR, and AMPR. These data would also be used to examine the TRMM precipitation retrieval algorithms.

3. <u>Preliminary Results</u>. Initial EDOP flights revealed that the radar interfered with the AMPR 10.6 GHz channel. To confirm the extent of interference, EDOP was

turned on and off during two of the flights. It was decided that EDOP would not fly on the more critical flights dealing with the SSM/T underpasses. On other flights, EDOP transmission was limited to the first few hours of the flight. All flights except the 10/3/93 flight produced data, although there was virtually no precipitation in the data. A problem with a part overheating in the radar caused data quality to be more questionable before 9/25/93 (i.e., 9/1/93 and 9/12/93).

4. Data Collected During CAMEX. The data flight on 10/5/93 resulted in excellent data from stratiform precipitation and weak showers near the Florida keys. The radar operated for approximately 2 hours and 40 minutes during this flight (see example in Figure 4), after which it was shut down to avoid AMPR interference. Figure 4 shows uncalibrated reflectivity data collected during this flight over stratiform rain with embedded cells. The surface return is evident at approximately 19 km and a bright band at about 5 km above the surface. A "mirror image" return occurs below the surface. The special calibration flight was not performed during the experiment and thus the absolute calibration of the data will be less accurate than if the ocean surface backscatter was used. The post-experiment EDOP calibration has provided radar reflectivities to better than a few dBZ; additional analysis of the ocean return will provide calibration accuracy to within +/- 1 dBZ.



Figure 4. Example of EDOP uncalibrated reflectivity data collected from stratiform rain with embedded convective cells on October 5, 1993.

C. ER-2 and Ground-Based HIS

1. <u>Instrument Description</u>. The ER-2 HIS is a Michelson interferometer which measures the upwelling nadir radiance within 3.5 and 17 micron region of the spectrum with a spectral resolution of 3000. The upwelling radiance spectrum, defined by 4000 independent spectral elements, is observed every 6 sec, with a spatial resolution of 2 km (along the flight track of the ER-2). The instrument possesses an inflight calibration facility to provide absolute accuracies of better than 0.5 K and the instrument noise is about 0.25 K when viewing standard surface temperature scenes. Reduced noise level spectra are achieved by co-adding a time sequence of the 6-sec interval measurements.

The GB-HIS is a Michelson interferometer that measures downwelling zenith radiance within the 3-20 micron region of the spectrum with a spectral resolution of 1000 to 6000, depending on wavelength. The downwelling radiance spectrum is observed every few seconds but the data are co-added internally over several minutes to provide reduced noise level spectra. An automatic calibration facility enables calibrated radiance spectra to be produced in real time with a 10-min frequency and with an absolute accuracy better than 0.5 K. The noise level of the 10-min interval spectra is about 0.2 K for standard surface temperature source radiance conditions. The instrument and associated real time data processing system are designed to run in a totally unattended mode.

2. CAMEX Objectives

(A) To provide space and time coincident measurements of upwelling (at 20 km) and downwelling (with GB-HIS) spectra of infrared radiance with radiosonde and Raman lidar measurements of atmospheric temperature and moisture as needed to validate and improve spectroscopic variables and models used for radiative transfer calculations and remote sensing.

(B) To determine experimentally the temperature and water vapor profiling capability of current satellites, future satellite (as represented by prototype instruments on the NASA ER-2 aircraft), and ground-based active (Raman lidar) and passive (GB-HIS) systems.

(C) To demonstrate the ocean surface temperature and heat flux measurement advantages of high-spectral-resolution infrared sensors over the broadband sensors flown on contemporary satellites.

3. Preliminary Results

(A) Processing and Performance. All the ER-2 HIS and GB-HIS data have been processed into calibrated radiance spectra for the entire CAMEX period. The results confirm the in-field diagnosis of near perfect operation of both systems on all aircraft flight days, including the aborted missions. Figure 5 shows four atmospheric profiles calculated from GB-HIS data acquired during the CAMEX experiment. Figure 6 shows four CLASS soundings taken at the times of the GB-HIS data.

(B) Scientific Analysis. Intensive scientific investigations with the CAMEX interferometer, rawinsonde, and Raman lidar and NOAA satellite AVHRR and TOVS data are underway. Comparisons of observed aircraft and ground-based spectra with calculations from rawinsonde measurements have already been performed to reveal deficiencies of spectroscopic data files (e.g., HITRAN '91) and computational procedures. Preliminary retrievals from both aircraft and ground-based HIS data have been performed and compared to simultaneous rawinsonde data to reveal strengths and weaknesses in each observing approach and the methods used to invert the rawinsonde data into atmospheric profiles. A presentation of the first results of the CAMEX HIS observations was presented at the AIRS science team meeting held in Madison, WI on October 13, 1993.

(C) HIS Data Dissemination. Both ER-2 HIS and GB-HIS radiometric data are available for dissemination to the CAMEX HIS sponsors. Plans are to prepare a quality controlled aircraft and ground-based HIS and associated rawinsonde dataset for dissemination to the scientific community at large.



Figure 5. Ground-based HIS retrievals for Wallops Island on four CAMEX days.



Figure 6. CLASS retrievals of atmospheric temperature and moisture on four days during CAMEX.

D. Lightning Instrument Package (LIP)

1. Instrument Description

(A) Instrument Components. The Lightning Instrument Package (LIP) consists of two electric field mills, conductivity probe, and data system. One of the field mills is installed on the upper Q-bay hatch cover and the second one is mounted on the lower E-bay hatch. The conductivity probe is integrated on the right-hand superpod nose cone. The LIP data system is mounted in a 19-inch vertical rack which is located in the aft portion of the ER-2 Q-bay. The ER-2 electric field mills and the conductivity probe are compact sensors, each weighing less than 5 lbs.

(B) Measurement Parameters and Characteristics. The electric field mills measured components of the electric field over a dynamic range exceeding 3 orders of magnitude (i.e., there are 3 gain channels, x1, x46 and x2116). Hence fair weather electric fields as well as large thunderstorm fields (e.g., 10-20 kV/m) could be measured. The field mills also provided a measurement of the electric charge on the aircraft. Abrupt electric field changes will be used to identify lightning discharges. The conductivity probe provided a measure of the air conductivity at the aircraft altitude. Conductivity contributions due to positive and negative ions were measured simultaneously. All measurements were recorded with a PC-based data system and archived on an Exabyte 8 mm tape drive. Data were continuously recorded throughout the duration of each mission.

2. CAMEX Objectives

(A) To develop and improve algorithms employing multi-sensor data for precipitation estimation. It has been widely recognized that storm electrification is connected closely to convective precipitation development. Therefore, we anticipated that lightning data could convey a great deal of information about the precipitation structure in a thunderstorm. This objective supported the scientific goals of TOGA COARE and the TRMM which will include a lightning sensor. Table 4 gives the measurement parameters sought during CAMEX along with their scientific uses.

(B) To investigate the structure, kinematics, and evolution of thunderstorms, and relate these to lightning. Lightning rates, distribution, and characteristics are all factors that may prove useful in devising quantitative algorithms, and these factors could be studied appropriately with the ER-2.

(C) To study the electric fields, currents, and charges in the vicinity of convective storms and determine the storm's contribution to the global electric circuit. It is widely believed that thunderstorms are the generators responsible for maintaining the global electric circuit. This hypothesis has been supported by measurements of the upward directed current above thunderstorms in the United States.

Table 4. Data products produced by ER-2 LIP system during CAMEX

Product:	Electric field components and aircraft
	self-charge
Period:	Continuous record, entire flight
Resolution:	10 Hz
Comments:	Total lightning (cloud-to-ground, intracloud)
determined from electric field	eld changes in the data. Data also provided
information on the electrica	al structure in vicinity of thunderstorms.
Maxwell, displacement, and	d conduction current densities derivable using
the electric field and air con	nductivity measurements. The ER-2 dataset
was complemented by the V	U.S. ground-based lightning location network.
1 2	
Product:	Air conductivity
Period:	Continuous record, entire flight
Resolution:	10 Hz
Comments:	Simultaneous measurements provided of both
polar components of the air	conductivity (i.e., contributions from
positive and negative ions).	Storm electric conduction current densities
derivable when used with e	lectric field data.

3. <u>Preliminary Results</u>. LIP participated in 8 of the 9 ER-2 flights (not active on 9/30/93). Two of the fights (9/26/93 and 10/05/93) contained enough convective activity to produce lightning. Figure 7 shows an example of the approximate vertical field and aircraft self-charge above the storm on 9/26/93 from 1900 to 2130 GMT. The storm was located to the southeast of Cape Hatteras. Nine lightning flashes were detected during this time frame. Some of them are indicated by the letter "L." Air conductivity data were also collected during this time.



Figure 7. Vertical electric field and aircraft self-charge measurements from the LIP instrument flying above a thunderstorm on 9/26/93.

E. Multispectral Atmospheric Mapping Sensor (MAMS)

1. <u>Instrument Description</u>. In 1985, the MAMS was developed and flown to verify small-scale water vapor features observed in Visible Infrared Spin Scan Radiometer (VISSR) Atmospheric Sounder (VAS) imagery aboard the Geosynchronous Operational Environmental Satellites (GOES). MAMS is a multispectral scanner which measures reflected radiation from the Earth's surface and clouds in eight visible/near-infrared bands, and thermal emission from the surface, clouds, and atmospheric constituents (primarily water vapor) in four infrared bands. This aircraft sensor provided a unique opportunity to independently verify single-pixel variations observed in the VAS channels (Menzel et al., 1986). This verification continued for several years providing useful correlative measurements (Jedlovec et al., 1986a; Jedlovec, 1984).

2. <u>CAMEX Objectives</u>. The primary science objective with MAMS for CAMEX was the analysis of water vapor. In addition, MAMS flew in a support role during convection missions. To achieve these objectives, the ER-2 made several flights over Wallops Island, VA and the adjacent land and ocean.

3. <u>Preliminary Results</u>. Figure 8 shows MAMS imagery of Wallops Island during CAMEX. Data collected from MAMS will be used to identify: (A) mesoscale atmospheric moisture variations and (B) provide visible and infrared measurements of thunderstorms in support of the microwave and lightning investigations. The MAMS data will be used to characterize the structure of these features and to derive integrated water content (precipitable water) associated with these features. Quantitative analysis of the moisture variability associated with these features will be performed as well as intercomparisons of water vapor data sensed from the Raman lidar and rawinsondes. The MAMS 6.5 μ m channel has been used to map variations in upper tropospheric water vapor associated with a variety of atmospheric disturbances (Menzel et al., 1986; Jedlovec, 1984; Jedlovec et al., 1986b). The split-window channels at 11 and 12 μ m allow surface temperature estimations and the determination of total-integrated water content in a column of the atmosphere as discussed by Jedlovec (1990) and Guillory et al. (1993).

4. <u>References</u>:

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Menzel, W. P., G. J. Jedlovec, and G. S. Wilson, 1986: Verification of small scale features in VAS imagery using high resolution MAMS imagery. Preprints, *Second Conf. on Satellite Meteor./Remote Sensing and Applications*, AMS, Williamsburg, VA, 108-111.



F. Millimeter Imaging Radiometer (MIR)

1. Instrument Description. MIR is a six-channel, mechanically scanned, totalpower, imaging microwave radiometer that measures radiation at frequencies of 89, 150, 183.3 ± 1 , 183.3 ± 3 , 183.3 ± 7 , and 220 GHz. It has an angular resolution of about 3.5° at all frequencies. It is a cross-track scanner with an angular swath of about 100° centered at nadir. For every scan it also views heated (330 K) and cooled (250 K) external calibration targets resulting in a total frame time of about 3 sec. The radiometric signals and the measured physical temperatures from these calibration targets form the basis for the derivation of the scene brightness temperatures. The calibration accuracy is on the order of 1 K in the 250-300 K brightness temperature range. Based on the calibration data from bench testing in the laboratory environment, the measurement accuracy is estimated to be better than ± 2 K at brightness temperature below 100 K. The temperature sensitivity (Δ T) is ≤ 1 K for all channels.

2. <u>CAMEX Objectives</u>. The objectives of the MIR CAMEX mission were: (A) measurements of water vapor profiles, (B) studies of 90-220 GHz microwave signatures associated with precipitation, (C) validation of the SSM/T-2 sensor aboard the DMSP's F-12 satellite, and (D) studies of microwave signatures at high incidence angles (e.g., $\sim 60^{\circ}$ to 70°). Some of the analysis work related to these objectives will be made with data from MIR as well as other sensors (e.g., AMPR, HIS, Raman lidar, etc.) aboard the same ER-2 aircraft or on the ground. The DMSP F-12 satellite data (SSM/T-2 and SSM/I) may also be used in the analysis.

3. <u>Preliminary Results</u>. MIR performed well during CAMEX, with a single exception being loss of about 1.5 hours of data toward the end of the flight on October 3, 1993 (CAMEX Flight 7). The electrical power to the system appeared to be turned off for no explainable reason. Minor interference was observed in the 220 GHz channel data in most of the flights when the ER-2 aircraft was in the neighborhood of the Wallops Flight Facility. This can be easily screened and will not present any problem in the data analysis. Figure 9 shows multifrequency MIR data of a small oceanic thunderstorm, acquired during CAMEX.



Figure 9. Sample of MIR multispectral imagery taken during CAMEX.

G. Millimeter-Wave Temperature Sounder (MTS)

1. <u>Instrument Description</u>. The Massachusetts Institute of Technology's (MIT) Millimeter-Wave Temperature Sounder (MTS) is a dual-band microwave radiometer system for the measurement of atmospheric temperature and other phenomena affecting transmission in the microwave absorption bands of molecular oxygen. It is capable of either downward or upward viewing operation on the NASA ER-2 high-altitude aircraft, and also ground-based operation. The instrument has a scanhead installed in the aft cone of the ER-2 wing superpod, which houses the RF components and a video camera. IF amplifiers, synchronous detectors, integrators, power supplies, temperature controllers, video recorder, and microcomputer are housed in the midsection of the superpod.

One radiometer is an eight-channel scanning spectrometer with its local oscillator centered on the 118.75 GHz oxygen line. It is a double-sideband superheterodyne system. The eight channels are derived from filters in the IF section, each approximately 200 MHz wide, which together cover the IF between 350 MHz and 2000 MHz. Thus each channel has two symmetrically placed pass bands, one on each side of the line. The resulting clear air temperature weighting functions for nadir viewing from 20 km peak successively from 13 km to the surface, as one chooses frequencies farther from the line center. This spectrometer has a stationary scalar feedhorn and subreflector with 7.5° beamwidth which view a step scanning mirror. The mirror directs energy from 14 positions, extending over a 95° swath below the aircraft, and also from two calibration targets, into the spectrometer. The integration time per spot is 224 ms, yielding approximately 0.5 K rms resolution per spot, and a scan of 16 spots lasts 5.5 sec.

The second radiometer is a single-channel, nadir (or zenith) viewing, doublesideband superheterodyne system. The antenna has a 10° beamwidth. The local oscillator is tunable, under computer control, from 52 to 54 GHz. A typical mode of operation time-shares three or four local oscillator frequencies, including as many of the AMSU-A frequencies as possible.

2. <u>CAMEX Objectives</u>. MTS measured atmospheric radiances in the 52-54 GHz and 119 GHz oxygen bands during CAMEX. The primary objective of these measurements was to support general CAMEX objectives with temperature sounding capabilities and imagery of convective cells at 119 GHz. The newly reconfigured 52-54 GHz radiometer was simultaneously operated in order to validate its calibration, with particular emphasis on the AMSU-A channels within its tuning range. An additional objective, which made use of MTS in an up-looking mode, was to test and validate recently revised oxygen-band transmittance algorithms. These tests will assist algorithm development for the NOAA and EOS satellites carrying AMSU-A. 3. <u>Preliminary Results</u>. In general, the instrument performed well throughout the deployment. Assessment of the data continues at MIT. Figure 10 shows MTS data collected over a thunderstorm off the east coast of Florida. The values displayed are brightness temperature deviations from adjacent clear-air values.



MTS imagery of a convective cell, 10-05-93, Florida Atlantic coast. Values displayed are brightness temperature deviations from adjacent clear-air values.


H. Scanning Raman Lidar

1. <u>Instrument Description</u>. The NASA/GSFC Scanning Raman Lidar System was stationed at the building U-70 site 3 km inland of Wallops Island during the CAMEX campaign. The lidar is based on a XeF excimer laser (351 nm) operating at 400 Hz and 18 W. A 0.76-m telescope and large scan mirror provide the ability to acquire data from horizon to horizon in a single scan plane. During CAMEX, the scan plane of the lidar was aligned at 134° (magnetic). Photomultipliers acquired the Raman scattered signals from atmospheric water vapor (402 nm), nitrogen (382 nm), oxygen (372 nm), and the direct backscatter at the laser wavelength. The prime data products were 1-min profiles of water vapor mixing ratio and aerosol backscattering ratio. Other data products, which rely on additional data from radiosondes, included relative humidity, aerosol extinction, and temperature.

The lidar was housed in two environmentally controlled trailers. The larger of the two (12.8 m x 2.4 m x 3.0 m) housed the lidar instrument itself, while the smaller (10.4 m x 2.4 m x 3.0 m) housed personnel, and computer equipment for data acquisition and analysis.

2. <u>CAMEX Objectives</u>. The objectives of the Raman lidar program were to acquire water vapor and aerosol profiles of the lower troposphere over both land and ocean. To assist in this effort the Johns Hopkins/Applied Physics Laboratory's (APL) ocean research vessel was stationed off the coast of Wallops Island and operated a tether-sonde system to provide in situ measurements of the water vapor and temperature profiles. A secondary objective of the NASA and Johns Hopkins/APL research was to study enivronmental effects on anomalous propagation of radar waves transmitted by WFF's SPANDAR radar facility.

3. <u>Preliminary Results</u>. The lidar was operational for all requested CAMEX intensive observation periods without failure acquiring both vertical data and data at various angles over the land and the ocean. In addition, the lidar operated in conjunction with the APL ship-based tethersonde system. (Note that on one occasion the tethersonde system was operated on land along side the lidar system.) Figure 11 shows the water vapor mixing ratio data, and Figure 12 the aerosol scattering ratio data acquired on the vertical and at +/- 60° (- is toward the ocean, + is toward the land) on the night of September 14, 1993. Approximately 9 hours of data are shown over the given altitude ranges. (The altitude represented for the data acquired at an angle is determined by multiplying the range by the sine of the elevation angle where the angle is measured with respect to the vertical and the range is the distance along the laser propagation path.)



Figure 11. Raman lidar water vapor imagery at three angles (-60°, 0°, and +60°) acquired on September 14, 1993.



Figure 12. Raman lidar imagery of the aerosol scattering ratio at three angles (-60°, 0°, and +60°) acquired on September 14, 1993.

Raman Lidar Sept 14 1993 WFF 0 deg

SECTION III. CAMEX ER-2 MISSION SUMMARIES

The eight ER-2 data collection flights were the primary goal of CAMEX. Table 5 gives an overview of the data flights, indicating which instruments were flown on each mission along with a very brief synopsis of the mission results. Because each ER-2 mission was characterized by different objectives, we have summarized each mission separately in Sections 3-A to 3-H. The ER-2 mission summaries, that begin on the next page, contain the ER-2 pilot's flight logs along with plots of the flight tracks. A surface analysis, along with afternoon Meteosat imagery and the 0000 GMT Wallops rawinsonde, are available for each ER-2 mission day in Section IV.

Table 5. CAMEX ER-2 flight summary

	1				T						Ť				Т			Ť									
MISSION SUMMARY	Flight aborted shortly after takeoff due to pressurization problems	with the Q-bay. Flight lasted 90 minutes.	Flight aborted 1 hour after take off due to partial failure in the	aircraft hydraulic system. Flight duration was 2.3 hours.	A short flight to test the ER-2 hydraulic system. All instruments	collected data during the flight including EDOP. There was a	failure in the MAMS recorder after 1 hour. Flight duration was 2.3 hours.	ER-2 overpasses (7) of isolated gulf-stream convection off North	Carolina. Circle maneuver was performed but no precipitation	was observed. HIS pattern flown over Wallops at end of mission.	Flight duration was 4.67 hours.	AIRS mission flown over the Wallops Flight Facility. Most	instruments worked well; however, the LIP instrument failed	during the flight. Flight duration was 4 hours (Note: Julian day	was 10/29/93.)	ER-2 flown under the DMSP F11 satellite and over coastal	rawinsonde stations. HIS pattern flown over WFF at end of the	mission. Flight duration was 6 hours.	Convection flight in the Florida region. EDOP was onboard the	ER-2 but failed on power up and was not recycled. Pilot flew	several small thunderstorms. Circle maneuver was performed but	no precipitation was observed. Flight duration was 7.5 hours.	This was the best convection flight during CAMEX with several	passes over deep convection in the South Florida area. EDOP had	good coverage of storms, and lightning was observed by LIP.	Circle maneuver flown over precipitation. Mission duration was	7.7 hours with 2.7 hours of storm observations.
PRIMARY	MIR, HIS,	AMPR	AMPR		NONE			AMPR				HIS, MIR				MIR, AMPR			AMPR				AMPR				
INSTRUMENTS	AMPR, LIP,	MAMS, MIR, MTS, HIS	AMPR, LIP,	MAMS, MIR, MTS, HTS	AMPR LIP	MAMS, MIR, MTS,	HIS, EDOP	AMPR, LIP,	MAMS, MIR, MTS,	HIS		AMPR, LIP,	MAMS, MIR, MTS,	SIH		MIR, HIS, AMPR,	MTS, MAMS		MIR, AMPR, HIS,	MTS, LIP, MAMS,	EDOP		MIR, AMPR, HIS,	MTS, LIP, MAMS,	EDOP		
OBJECTIVE	SSM/T-2		Convection		FR_7 Tect	Flight)	Convection				AIRS				SSM/T-2			Convection				Convection				
DATE	9/15/93	T 2005Z L 2135Z	9/19/93	T 2000Z	7C177 7	T 1600Z	L 1825Z	9/26/93	T 1900Z	L 2340Z		9/28/93	T 0100Z	L 0500Z		9/30/93	T 2000Z	L 0220Z	10/3/93	T 2000Z	L 0330Z		10/5/93	T 1600Z	L 2340Z		
ER-2 Sortie	93-165		93-166		02-167	101-00		93-168				93-169				93-178			94-001				94-002				
CAMEX FI JGHT	-		2		6	'n		4	-			2				9			2				8				

A. CAMEX Flight 1

1. Overview

Mission:	Underflight of DMSP F11 Satellite
ER-2 Sortie:	93-165
Date:	September 15, 1993, CAMEX day 7
Takeoff:	2005 GMT (1605 local)
Duration:	1 hour and 30 minutes
Instruments:	AMPR, HIS, LIP, MAMS, MIR, and MTS
Key Instruments:	MIR, HIS

2. <u>Mission Objective</u>. The major objective of this flight was to validate and calibrate the SSM/T-2 sensor with data from the MIR instrument. The flight track selected (Figure 13) passed underneath the F11 orbit track and covered as many rawinsonde stations as possible along the coastline from South Carolina to Massachusetts.

3. <u>Mission Summary</u>. The ER-2 launched at 2005 GMT and flew north to 39° 45' N, 74° 40' W. Upon reaching this first weight point the pilot reported a failure in the Q-bay pressurization. The mission was aborted and the ER-2 returned to WFF arriving at 2135 GMT. Very little useful science data were acquired during this mission due to the length of the mission. Figure 14 contains the pilot's log for this mission.

4. <u>Ancillary data</u>. The surface HIS collected data the entire day and Raman lidar from 0100 to 0800 GMT. CLASS rawinsondes were launched at 2200 GMT, 0100 GMT, 0400 GMT, and 0700 GMT. Additional rawinsondes were launched by the WFF at 2200 GMT (Vaisala), 0100 GMT (Vaisala and AIR), and 0400 GMT (Vaisala and AIR).

5. <u>Aircraft Performance</u>. Because of the potential detrimental effects of low pressure on the instruments, the Mission Scientist decided to abort the mission after several unsuccessful attempts to pressurize the Q-bay.

6. <u>Instrument Performance</u>. The AMPR instrument performed well as did the MIR, although noise in the MIR data was attributed to the ascent and descent. The LIP recorded good data and the problems with the conductivity probe during the ferry flight were not present. The MAMS instrument performed well except for Channel 10 (11.1 μ m). An analog-to-digital converter card was replaced after the flight. The HIS recorded clean data with an absence of the noise present in the previous flight. The MTS sensor had an in-flight failure 30 minutes after launch, and numerous attempts to recycle the MTS had no effect. No MTS data were collected after 2035 GMT.



Figure 13. Flight track for CAMEX flight 1.

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Figure 14. Pilot's flight log for CAMEX flight 1.

B. CAMEX Flight 2

1. Overview

Mission:	Convection
ER-2 Sortie:	93-166
Date:	September 19, 1993, CAMEX day 13
Takeoff:	2000 GMT (1600 local)
Duration:	2 hours and 15 minutes
Instruments:	AMPR, HIS, LIP, MAMS, MIR, and MTS
Key Instruments:	AMPR

2. <u>Mission Objective</u>. This flight was the first of a series of convection flights planned to study the multifrequency microwave signature of convective rain systems off the East Coast. Observations of Gulf Stream precipitation by the AMPR instrument are crucial for relating measurements taken during the CaPE program to observations of tropical thunderstorms in the Pacific warm pool region acquired during TOGA COARE.

A flight pattern was selected (Figure 15) to position the ER-2 over a line of convective precipitation over the Gulf Stream, off the coast of Virginia. GOES satellite imagery from 1600 GMT depicted a strong line of thunderstorms associated with a cold frontal boundary east of Wallops Island, VA. Two end points were selected to ensure the ER-2 flew over the most significant activity, while allowing for advection of the storms. An alternate flight pattern over ocean buoys and coastal rawinsonde sites was planned in the event the thunderstorms had dissipated or moved out of the operations area before the ER-2 reached the region.

3. <u>Mission Summary</u>. After a 2000 GMT launch, the ER-2 flew east to the designated flight operations area. Upon arrival at the first way point (36° 30' N, 71° 30' W) at 2044 GMT, the pilot reported there were no thunderstorms present in the designated flight area. The Mission Scientist requested the pilot fly the alternate pattern. While making a turn to start the alternate flight plan, the pilot detected an aircraft hydraulics failure and aborted the mission. The ER-2 arrived back at WFF at 2215 GMT. Little useful science data were acquired during this mission due to the shortened length of the mission and the lack of convection, although there may be good calibration data over clear ocean from many of the instruments. Figure 16 contains the pilot's log for this flight.

4. <u>Ancillary data</u>. The surface HIS started collecting data from 1800 GMT. The Raman lidar collected data from 0100 to 0530 GMT. CLASS rawinsondes were launched at 2300 GMT, 0100 GMT, and 0400 GMT. Additional rawinsondes were launched from the Wallops Flight Facility at 2200 GMT (VIZ, Vaisala, and AIR), 0100 GMT (VIZ and Vaisala), and 0400 GMT (VIZ, Vaisala, and AIR).

5. <u>Aircraft Performance</u>. The mission was aborted 60 minutes after takeoff because of a failure in the hydraulics system.

6. <u>Instrument Performance</u>. The AMPR instrument performed satisfactorily with minor noise observed in the 10 GHz channel starting at 2132 GMT. The LIP instrument had no major problems although data from the field-mil on the top of the aircraft continued to be slightly noisy. The MAMS collected good data with only minor RF noise in the IR channels, and the HIS and MIR also performed well. The MTS operated nominally in the downward looking position, but had oscillation in the three highest channels during descent.



Figure 15. ER-2 flight track for CAMEX flight 2.

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Figure 16. Pilot's flight log for CAMEX flight 2.

C. CAMEX Flight 3

1. Overview

ER-2 Test Flight (after repair of hydraulic system)
93-167
September 25, 1993, CAMEX day 19
1610 GMT (1210 local)
2 hours and 15 minutes
AMPR, EDOP, HIS, LIP, MAMS, MIR, and MTS
None

2. <u>Mission Objective</u>. The objective of this 2-hour flight was to check out the functioning of the aircraft after the hydraulic system was repaired. The flight also provided a good opportunity to examine the performance of all instruments. The flight path covered both ocean and land (Figure 17).

3. <u>Mission Summary</u>. The aircraft launched from WFF and headed south and southeast to way point (36° N, 75° W) over the ocean, and then to another way point (37° 30' N, 77° 20' W) over land before returning to WFF. A pass over the lidar site at 20-km altitude was made before the aircraft descended and landed around 1815 GMT. It was cloudy during the entire flight. Figure 18 shows the pilot's log for this flight.

4. <u>Ancillary Data</u>. Univ. of Wisconsin GB-HIS collected data from 1400 GMT to 0000 GMT. A CLASS rawinsonde was launched at 1700 GMT near the time of the aircraft overpass.

5. <u>Aircraft Status</u>. Aircraft performance was nominal during the 2-hour mission, and the crew certified that the airplane was ready to resume normal operations.

6. <u>Instrument Status</u>. All channels from AMPR worked well; the interference from EDOP at 10 GHz channel was still present, of course. Most of the MIR data were somewhat noisy because a major portion of the flight was spent on ascending and descending, and MIR needed some time to reach stabilization. HIS acquired a good dataset, but the spectra from 1731 to 1743 GMT needed to be reprocessed because of the false mirror position indication in housekeeping data. Some segments of LIP data were noisy; there was no clear correlation with the EDOP operation. MTS had a successful upward-looking flight. MAMS collected good data; however, there was a bad spot on tape around 1707 GMT and post analysis could not recover the missing data. EDOP had a good flight. The efforts to improve the system in the past few days had paid off apparently, as the noise present in the previous flights had disappeared.



Figure 17. ER-2 flight track for CAMEX flight 3.

FLIGHT LOG & RECORD CARD

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Figure 18. Pilot's flight log for CAMEX flight 3.

D. CAMEX Flight 4

1. Overview.

Mission:	Convection Flight
ER-2 Sortie:	93-168
Date:	September 26, 1993, CAMEX day 20
Takeoff:	1900 GMT (1500 local)
Duration:	4 hours and 40 minutes
Instruments:	AMPR, HIS, LIP, MAMS, MIR, and MTS
Key Instruments:	AMPR

2. <u>Mission Objective</u>. The objective of this mission was to collect multifrequency data over Gulf Stream convection, within the acquisition range of the SPANDAR radar at Wallops, using the three passive microwave sensors onboard (AMPR, MTS, MIR). Observations of convection during CAMEX by the AMPR will help scientists relate the observations of thunderstorms during CaPE to those acquired during TOGA COARE (the calibration hardware for AMPR was rebuilt between the two experiments). A cold front that had moved off the East Coast north of Wallops was producing shallow rainfall over the Atlantic City area and there were more significant thunderstorms well to the east and southeast of Wallops Island. An alternate objective was to observe any precipitation outside SPANDAR's effective range. The flight track for the ER-2 is shown in Figure 19.

3. <u>Mission Summary</u>. The ER-2 launched at 1900 GMT and flew northward to the first way point (39° 31' N, 73° 08' W). By the time of his arrival at way point 1 (1930 GMT) the precipitation over the ocean in the region had ended, and the Mission Scientist requested the ER-2 switch to the alternate flight plan calling for flight legs over precipitation northeast and east of Cape Hatteras, NC. At 2025 GMT the ER-2 pilot reported he was over an area of thunderstorms from 32° to 34° N and 73° to 74° W. He began flying repeated passes over these storms. Although, the storms were outside the effective range of the SPANDAR radar, the storms were observable on the Cape Hatteras weather radar and the East Coast lightning detection network indicated the storms were electrified. The ER-2 made five passes over storms and the times and locations as noted by the pilot were:

2004-2009 GMT	36° 51' N, 72° 04' W to 36° 24' N, 72° 27' W
2015-2039 GMT	35° 48' N, 72° 41' W to 34° 09' N, 75° 14' W
2046-2049 GMT	34° 26' N, 74° 57' W to 34° 43 N, 74° 44' W
2050-2053 GMT	34° 50' N, 74° 42' W to 35° 09' N, 74° 36' W
2100-2115 GMT	35° 00' N, 75° 40' W to 35° 58' N, 72° 15' W

After 2115 GMT, the storms began to dissipate and the Mission Scientist requested the pilot return to WFF Before his return, the pilot executed two 360° turns at with 20° bank (one left turn and one right turn); however, there was no precipitation in the area selected by the pilot for the turns. Upon arrival over Wallops at 2214 GMT the ER-2 flew the Raman lidar ground pattern (Figure 21) one time prior to landing at 2340 GMT. The Raman lidar was not operating during this flight, but the Univ. of Wisconsin GB-HIS was collecting data. The pilot's log for this mission is shown in Figure 20.

4. <u>Ancillary Data</u>. A CLASS rawinsonde was launched at 2200 GMT near the time of the aircraft overpass. The GB-HIS was operating from 1600 GMT until 1200 GMT.

5. Aircraft Status. The ER-2 performed nominally during the mission.

6. <u>Instrument Status</u>. The AMPR performed well with some noise in the 85 GHz channel and minor RF interference in 19 GHz and 37 GHz channels. The AMPR data indicated the pilot flew over several small convective cells, all less than 20 km in diameter. A preliminary look at the data collected during the 360° maneuvers indicated no precipitation was present. MAMS collected good data; however, some RF noise was apparent, as well as a possible absolute calibration problem. The LIP instrument collected a good dataset and detected lightning in some of the cells. Data from the top field mill did not contain the noise seen in the earlier missions. The HIS and MTS collected great datasets; although there was an 80 second glitch in the MTS data shortly after ascent. The MIR also collected excellent observations of small rain cells.



Figure 19. ER-2 flight track for CAMEX flight 4.

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Figure 20. Pilot's flight log for CAMEX flight 4.

E. CAMEX Flight 5

1. Overview

Special Flight for the AIRS Project
93-169
September 29, 1993, CAMEX day 22
0100 GMT (2100 local, September 28, 1993)
4 hours
AMPR, HIS, LIP, MAMS, MIR, and MTS
HIS, MIR

2. <u>Mission Objective</u>. The objective of the "AIRS" mission is to achieve very high quality "Near Top of the Atmosphere" radiance spectra with associated temperature and water vapor profile ground truth to validate and improve radiative transfer calculations over the spectral regions to be observed by the EOS AIRS instrument. The major spectroscopic issue to be studied was the water vapor continuum and associated absorption line shape approximations. Secondary issues were CO_2 line strengths and half widths and the shortwave N_2 continuum.

The University of Wisconsin is supporting this study with ER-2 aircraft HIS spectra of upwelling radiance at aircraft altitude, downwelling radiance spectra observed at the surface with a ground-based HIS (called the GB-HIS), and CLASS rawinsondes from the Chesser farm. Other supporting data are WFF rawinsondes, Raman lidar water vapor profiles, and MAMS multispectral imagery and derived integrated water content (precipitable water).

3. <u>Mission Summary</u>. The flight consisted of multiple passes along two perpendicular lines over the Raman lidar site, one parallel to the coast of the Wallops Island, and another perpendicular to it (Figure 21). The total on-station time at the aircraft altitude of 20 km was 3 hours. The entire ER-2 flight track is shown on Figure 22. The pilot's log for the AIRS mission is shown in Figure 23.

4. <u>Ancillary Data</u>. The GB-HIS (Univ. of Wisconsin) operated for a full 24 hours during CAMEX day 22, including the complete mission time. The Raman lidar collected data from 0030 to 0500 GMT. The Univ. of Wisconsin launched CLASS sondes at 2200, 0100, and 0400 GMT. The WFF launched AIR and Vaisala rawinsondes at 2200, 0100, and 0400 GMT, and an ozone sonde at 0100 GMT.

5. <u>Aircraft Status</u>. The aircraft-sensor interface box was accidentally damaged during the EDOP integration process (no fault of EDOP). Therefore, EDOP was pulled off the aircraft at the last moment, and the takeoff time was postponed for 1 hour while

the aircraft crew repaired to the electrical system. The LIP instrument had a physical hardware failure, apparently resulting from the electrical system damage.

6. <u>Instrument Status</u>. HIS acquired a very good dataset during the flight. MIR also had a good flight and the data at all channels looked great. MTS was looking upward during this flight, and a very clean dataset was collected. AMPR acquired a great dataset for the duration of the entire flight. Unfortunately, MAMS experienced a tape system failure resulting in no data being collected. LIP had a major hardware failure at the start of the flight, apparently related to the problems encountered during the EDOP integration.



Figure 21. HIS-AIRS ground track pattern.



Figure 22. ER-2 flight track for CAMEX flight 5.

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Figure 23. Pilot's flight log for CAMEX flight 5.

F. CAMEX Flight 6

1. Overview

Mission:	SSM/T-2 Under flight
ER-2 Sortie:	93-178
Date:	September 30, 1993, CAMEX day 24
Takeoff:	2000 GMT (1600 local)
Duration:	6 hours and 20 minutes
Instruments:	MIR, AMPR, MTS, HIS, and MAMS
Key Instruments:	MIR, AMPR

2. <u>Mission Objective</u>. The major objectives of this flight were (A) to validate/calibrate the SSM/T-2 channels with the MIR measurements and (B) to study the microwave signatures at high incidence angles (up to 65°) over ocean areas under clear and cloudy conditions in the frequency range of AMPR and MIR.

3. <u>Mission Summary</u>. The flight path was designed to cover as many rawinsonde stations as possible, within the region of coverage by the SSM/T-2, along the coastline of the eastern shore from the Carolinas to Massachusetts. Over the ocean areas the aircraft also flew over some buoy sites that provided measurements of sea surface temperature and near-surface humidity and air temperature. Toward the end, two perpendicular passes over the Lidar site in the Wallops Island were conducted before landing. Figure 24 shows the flight track for this mission.

The aircraft flew over rawinsonde stations located at Atlantic City, Chatham, Cape Hatteras, Charleston, Greensboro, and Wallops, and buoy sites 44005, 44008, 44004, 44014, and 44009. Two 360° turns, left and right, were flown in the neighborhood of the buoy site 44008 at 2140 GMT. The weather in the region of coverage during the flight period was mostly clear over land and (probably) partly cloudy over the oceans. The wind condition at the time of aircraft takeoff was north to northeasterly from 10 to 15 knots. At the time of landing the wind was expected to be northerly and less than 10 knots. The nighttime temperature was in the low 40's (°F). The pilot's log for this mission is shown in Figure 25.

4. <u>Ancillary Data</u>. The Univ. of Wisconsin operated the GB-HIS for 24 hours during CAMEX day 24. The Raman lidar collected data from 0030 to 0500 GMT. The Univ. of Wisconsin personnel launched CLASS sondes at 2200, 0100, and 0400 GMT. The WFF launched rawinsondes at 2200 (Vaisala and AIR), 0100 (Vaisala), and 0400 GMT (Vaisala and AIR), and also launched an ozone sonde at 0100 GMT.

5. <u>Aircraft Summary</u>. The aircraft performance was nominal during the flight; however, there was a failure in the flight navigation recorder near the end of the flight.

6. <u>Instrument Summary</u>. MIR had a very good flight and a clean dataset was acquired. AMPR also collected a great dataset during the entire flight, as did the HIS. MTS acquired a clean dataset throughout. MAMS collected good data. The HIS lost their navigation data in the last one-third of the flight, though the navigation data were available in the data stream of the other instruments. The LIP instrument was undergoing repairs caused by the electrical problems during the previous flight, and did not fly on this mission.



Figure 24. ER-2 flight track for CAMEX flight 6.

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Figure 25. Pilot's flight log for CAMEX flight 6.

G. CAMEX Flight 7

1. Overview

Mission:	Convection
ER-2 Sortie:	94-001
Date:	October 03, 1993, CAMEX day 27
Takeoff:	2000 GMT (1600 local)
Duration:	7 hours 30 minutes
Instruments:	MIR, AMPR, EDOP, LIP, MTS, HIS, and MAMS
Key Instruments:	AMPR

2. <u>Mission Objective</u>. The major objective of this flight was to continue multifrequency microwave radiometer measurements of tropical convection in the Southeastern U.S., using AMPR, MIR, and MTS. In addition, a secondary objective was EDOP measurements of precipitation over an ocean background. Due to lack of precipitation off the coast of Virginia, a flight path was selected to fly over convection in the coastal waters off the Florida Peninsula. GOES imagery from 1600 GMT indicated there were active areas of convection west of Tampa, near Ft. Meyers, and east of Daytona. Figure 26 shows the ER-2 flight track for CAMEX flight 7.

3. <u>Mission Summary</u>. After launch at 2000 GMT the pilot proceeded to the first way point (35° 07' N, 74°11' W) due east of Cape Hatteras where a large convective complex was observed on the satellite imagery. After a pass over convection in this region, the ER-2 flew to the Daytona area and the pilot requested a location of the most active convection from the air traffic control center. The ER-2 was directed to an area of convection west of Ft. Meyers, FL. Arriving in the area at 2220 GMT, the ER-2 made several short passes over convection in this region. The dates and times the ER-2 was over deep convective as recorded by the pilot were:

2224 - 2226 GMT	25°18' N, 81°26' W
2232-2234 GMT	25°33' N, 81°56' W
2246-2247 GMT	25°31' N, 81°47' W
2259-2301 GMT	25°43' N, 81°47' W
2344 GMT	25°36' N, 82°27' W
2152 GMT	26°21' N, 82°11' W
2159 GMT	26°23' N, 82°07' W

The ER-2 performed two 360° turns from 0001 to 0015 GMT (Oct. 4), but the post-flight analysis indicated the aircraft was not in an area with precipitation. Figure 27 shows the pilot's log for this flight.

4. <u>Ancillary Data</u>. The Univ. of Wisconsin operated the GB-HIS for 24 hours during CAMEX day 27. The Raman lidar collected data from 0000 GMT to 0500 GMT. CLASS sondes were launched at 2200, 0100, and 0400 GMT. WFF launched rawinsondes at 2200 (AIR, Vaisala, and VIZ), 0100 (Vaisala), and 0300 GMT (AIR, Vaisala, and VIZ), and an ozone sonde at 0100 GMT.

5. <u>Aircraft Summary</u>. The aircraft performance was nominal during the flight. The navigation recorder (which was replaced) worked well.

6. <u>Instrument Summary</u>. The AMPR collected excellent data during the flight, with the exception of some minor noise in the 19 GHz channel. The EDOP transmitter failed to start when switched on, and at the instructions of the Mission Scientist, the EDOP was not recycled. Thus, the instrument collected no data during the flight. The MAMS instrument worked well, and was able to receive the navigation data through the RS-232 channel for the first time during the experiment. The LIP instrument had a failure early in the mission, but recycled properly and collected good data. Preliminary post-flight analysis of the LIP data indicated that while there were significant electrical fields in the areas of active convection, no obvious lightning signals were present. The MTS instrument worked well, recording clean data, although there was some gain instability. The HIS sensor also worked well. MIR had a failure and did not record any data the last 90 minutes of the flight. The cause of the MIR failure could not be located.



Figure 26. ER-2 flight track for CAMEX flight 7.

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D	VRB 044 03	°05	120 117.3	204	532	:35 1:52	55					
E	RSW 253 10	00	55	238	230	:34	221.7		OULER ON TO & YW			
F	EYW 253	48	82	148	- <i>11</i> Z-	:18_			2232-34 (2243-47) 22-7-63 D 25 33 25 37 / 147 81 55 51 47 - 21 47			
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Figure 27. Pilot's flight log for CAMEX flight 7.

H. CAMEX Flight 8

1. Overview

Mission:	Convection
ER-2 Sortie:	94-002
Date:	October 05, 1993, CAMEX day 29
Takeoff:	1600 GMT (1200 local)
Duration:	7 hours and 40 minutes
Instruments:	MIR, AMPR, EDOP, LIP, MTS, HIS, and MAMS
Key Instruments:	AMPR

2. <u>Mission Objective</u>. The major objectives of this flight were to continue multifrequency microwave radiometer measurements of tropical convection in the Southeastern U.S., using AMPR, MIR, and MTS, and collect EDOP measurements of precipitation over an ocean background. A secondary objective was to study the interference in the AMPR data caused by the EDOP, comparing the interference patterns over land and ocean backgrounds. A flight path was selected to fly over convection in the coastal waters off the Florida Peninsula, and an earlier launch time was set to maximize daylight observations. Satellite imagery from 1200 GMT indicated there were active areas of convection south of Key West and east of Miami. To ensure the pilot flew over the most significant precipitation, a radio-contact schedule was established and the pilot was given hourly position fixes of convection in south Florida.

3. <u>Mission Summary</u>. The ER-2 launched at 1600 GMT and flew south down along the east coast. During the transit flight the mission scientist studied the current satellite and radar imagery, concluding that the most significant convection was a line of thunderstorms south of the Florida Keys from 24° 25' N, 80° 37' W to 24° 52' N, 82° 04' W. The pilot was given these positions and proceeded to the area, arriving at 1832 GMT. The pilot made three passes over the convection before turning the EDOP transmit off to allow for interference-free data collection by the AMPR. After one more pass over the storms the pilot was directed to a developing line of storms north of Miami. This line of storms was aligned east-west from Lake Okeechobee to about 60 miles offshore of West Palm Beach. The ER-2 made repeated passes over these storms. The pilot completed two 360° turns from 2017 to 2030 GMT, and post-flight analysis of the AMPR data indicated that precipitation was observed during the banked turns. The times and locations for the passes over deep convection as noted by the pilot were:

1833-1840 GMT	24° 26' N, 80° 44' W to 24° 03' N, 81° 23' W
1848-1852 GMT	24° 13' N, 81° 17' W to 24° 22' N, 80° 57' W
1852-1917 GMT	24° 27' N, 80° 52' W to 27° 04' N, 79° 58' W
2014-2017 GMT	27° 32' N, 80° 00' W to 27° 12' N, 80° 01' W
2038-2041 GMT	26° 20' N, 80° 25' W to 26° 09' N, 80° 45' W
2050-2057 GMT	26° 06' N, 80° 56' W to 26° 26' N, 80° 13' W

The ER-2 made at least three other passes for which incomplete data were noted by the pilot. Figure 28 shows the ER-2 flight path during this mission. The pilot's log for this flight is shown in Figure 29.

4. <u>Ancillary Data</u>. The Raman lidar collected data from 0030 to 0500 GMT (6 Oct.); however, this was after the ER-2 had landed. The GB-HIS collected data for the entire 24 hours of CAMEX day 29. CLASS sondes were launched at 2200 GMT, 0100 GMT, and 0400 GMT. WFF launched rawinsondes at 2200 GMT (VIZ and Vaisala), 0100 GMT (Vaisala and AIR), and 0400 GMT (VIZ, Vaisala, and AIR), and an ozone sonde at 0100 GMT.

5. <u>Aircraft Performance</u>. The ER-2 performance was nominal during the mission.

6. <u>Instrument Performance</u>. This was the best convection flight during CAMEX. The thunderstorms as observed by the AMPR were the largest and most active seen. The LIP collected good data including observations of lightning during several of the passes. The EDOP performed very well, and collected excellent data on the storms south of the Florida Keys before being turned off at 1920 GMT. The EDOP measured the tops of the thunderstorms at 12 km. The MIR worked well, seeing numerous rain cells as did the MTS. The HIS also collected a great dataset.



Figure 28. ER-2 flight track for CAMEX flight 8.

PILOT	BAR Y	SCHED T	0 160	00	ALT CC	DE	804	- 324 - 10	53/167	19 130
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DATE	10/5/93	FLT TIME	7+	40						
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	CHS		8z	225		350	:55	17.04	1645 ADC	
-	551		<u>113.5</u> 35	217	/	175	: 26	35		
			107.8				1:29	28		
A	PIE 25605	52 3538	111	211		230	2:04	1003		
В	EYW 335	505B	82	150		_160_	<u>3:24</u> 5:28			2×360 'S IZONM RSW
C	MIA 0830	40	106	075	/	45_	: 22 5: 50		r.	
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									 	1840
F	<u>24°25</u> 80° 37				_			1832		24 26 24 03 PAST 80 44 B1 23 TRW
6/11	26 4 8 80 57	27 1 0 7934			/					184812 - 185112 TURN 2413 2422 TO NNE 8117 8057
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Figure 29. Pilot's flight log for CAMEX flight 8.
SECTION IV. DAILY SUMMARIES

Table 6 provides a synopsis of the CAMEX program with the significant activities listed for each day of the experiment. Table 7 shows the Wallops Island weather observation for each day (starting on September 12) during CAMEX. The remaining pages of this section document each day of the CAMEX field operations. Each daily summary (see Section I for a description of the CAMEX day) includes (if available) an experiment summary, a copy of the NOAA *Daily Weather Map*, Meteosat imagery (a sample of visible, IR, or water vapor), and a plot of the 0000 GMT Wallops Island rawinsonde. Although CAMEX operations did not occur on every day, the summary for each day is here included for continuity. As mentioned in Section II, the imagery and plots are included in this section for the purpose of providing an overview of CAMEX. The data have not been processed or quality controlled in any fashion. To acquire scientific quality data, you can contact the appropriate agencies.

CAMEX Day	Calendar Day	Significant Events
1	Tues, 7 Sept	Raman lidar operations begin
2	Wed, 8 Sept	
3	Thur, 9 Sept	Lidar
4	Fri, 10 Sept	
5	Sat, 11 Sept	ER-2 integration flight at ARC
6	Sun, 12 Sept	ER-2 ferry flight to WFF
		GB-HIS deployed
	····	First CLASS sondes launched
7	Mon, 13 Sept	Lidar and GB-HIS operated
		First WFF rawinsondes launched
8	Tues, 14 Sept	UB-HIS
9	Wed, 15 Sept	EK-2 Hight - aborted due to pressurization
		CB-HIS and Lidar
10	Thur 16 Cent	GB-HIS
10	Fri 17 Sent	GB-HIS
17	Sat 18 Sent	No activity
13	Sun 19 Sent	ER-2 flight - aborted due to hydraulic
1.5	Suit, 17 Sept	system failure
		Lidar and GB-HIS
14	Mon, 20 Sept	
15	Tues, 21 Sept	Johns Hopkins Research Vessel, "Chessie,"
	•	deployed
		Lidar and GB-HIS
16	Wed, 22 Sept	Lidar, GB-HIS, and "Chessie"
17	Thur, 23 Sept	Lidar, GB-HIS, and "Chessie"
18	Fri, 24 Sept	GB-HIS
19	Sat, 25 Sept	ER-2 maintenance test flight
↓	0 0 0	
20	Sun, 26 Sept	EK-2 CONVECTION HIGHL (5 NOUL)
	Mon 27 Sent	
21	Tues 28 Sent	FR-2 AIRS flight (4 hour)
22	1 uco, 20 ocpt	Lidar, GB-HIS, and "Chessie"
23	Wed, 29 Sent	Lidar, GB-HIS, and "Chessie"
24	Thur, 30 Sept	ER-2 SSM/T-2 flight (7 hour)
	, ••• •••••••	Lidar and GB-HIS
25	Fri, 1 Oct	GB-HIS
26	Sat, 2 Oct	GB-HIS
27	Sun, 3 Oct	ER-2 convection flight (7.5 hour)
		Lidar and GB-HIS
28	Mon, 4 Oct	Lidar and GB-HIS
29	Tues, 5 Oct	ER-2 convection flight (7 hour)
		Lidar and GB-HIS
30	Wed, 6 Oct	ER-2 instruments off-loaded
		GB-HIS and Lidar shut down
31	Thur, 7 Oct	ER-2 ferry flight back to ARC (only MTS
		onboard)

Table 6. CAMEX operations schedule

Date	Max T (F)	Td (F)	Weather	Minimum
				Ceiling
9/12/93	75			
9/13/93	81	62		
9/14/93	81	64		250
9/15/93	88	70		
9/16/93	79	70	FH	M7
9/17/93	74	69	F	M3
9/18/93	76		F R	
9/19/93	75		F	
9/20/93	70	49		M55
9/21/93	74	66	RLF	M8
9/22/93	74	59	F	M5
9/23/93	76	62	F H	140
9/24/93	73	53	F H	M21
9/25/93	73		F R	
9/26/93	86		FRH	
9/27/93	78	70	R F	M5
9/28/93	69	47		
9/29/93	70	42		
9/30/93	61	38	RW F	M40
10/1/93	65	47		
10/2/93	72			
10/3/93	69		Trace R	
10/4/93	77	44		
10/5/93	67	38		
10/6/93	67	44		250
10/7/93	73	60		250
10/8/93	69	64	R	130

 Table 7. Weather summary for Wallops Island during CAMEX

				CA	R	EX	Exp) Jerii	men	It S	chee	l T	[0]	U U	AM	EX	o	era	tior	l S D	ay	-			
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CAMEX FLIGHT DAY 1 - ACTIVITY

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CAMEX FLIGHT DAY 1 - SYNOPTIC CHARTS

TUESDAY, SEPTEMBER 7, 1993



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CAMEX FLIGHT DAY 2 - ACTIVITY

WEDNESDAY, SEPTEMBER 8, 1993



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CAMEX FLIGHT DAY 3 - ACTIVITY

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CAMEX FLIGHT DAY 3 - SYNOPTIC CHARTS

THURSDAY, SEPTEMBER 9, 1993



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CAMEX FLIGHT DAY 4 - ACTIVITY

FRIDAY, SEPTEMBER 10, 1993



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CAMEX FLIGHT DAY 5 - ACTIVITY

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CAMEX FLIGHT DAY 5 - SYNOPTIC CHARTS



SATURDAY, SEPTEMBER 11, 1993

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CAMEX FLIGHT DAY 6 - ACTIVITY

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CAMEX FLIGHT DAY 6 - SATELLITE IMAGERY



SUNDAY, SEPTEMBER 12, 1993



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CAMEX FLIGHT DAY 7 - ACTIVITY

CAMEX FLIGHT DAY 7 - SATELLITE IMAGERY



MONDAY, SEPTEMBER 13, 1993





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CAMEX FLIGHT DAY 8 - ACTIVITY

CAMEX FLIGHT DAY 8 - SATELLITE IMAGERY



CAMEX FLIGHT DAY 8 - SYNOPTIC CHARTS

TUESDAY, SEPTEMBER 14, 1993



CAMEX FLIGHT DAY 8 - WALLOPS RAWINSONDE



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CAMEX FLIGHT DAY 9 - ACTIVITY

CAMEX FLIGHT DAY 9 - SATELLITE IMAGERY



WEDNESDAY, SEPTEMBER 15, 1993





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CAMEX FLIGHT DAY 10 - ACTIVITY

CAMEX FLIGHT DAY 10 - SATELLITE IMAGERY



CAMEX FLIGHT DAY 10 - SYNOPTIC CHARTS

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THURSDAY, SEPTEMBER 16, 1993

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CAMEX FLIGHT DAY 10 - WALLOPS RAWINSONDE



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CAMEX FLIGHT DAY 11 - ACTIVITY

CAMEX FLIGHT DAY 11 - SATELLITE IMAGERY



FRIDAY, SEPTEMBER 17, 1993




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CAMEX FLIGHT DAY 12 - ACTIVITY

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CAMEX FLIGHT DAY 12 - SATELLITE IMAGERY



CAMEX FLIGHT DAY 12 - SYNOPTIC CHARTS



SATURDAY, SEPTEMBER 18, 1993

CAMEX FLIGHT DAY 12 - WALLOPS RAWINSONDE



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CAMEX FLIGHT DAY 13 - ACTIVITY

CAMEX FLIGHT DAY 13 - SATELLITE IMAGERY



CAMEX FLIGHT DAY 13 - SYNOPTIC CHARTS

SUNDAY, SEPTEMBER 19, 1993



CAMEX FLIGHT DAY 13 - WALLOPS RAWINSONDE



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CAMEX FLIGHT DAY 14 - ACTIVITY

CAMEX FLIGHT DAY 14 - SATELLITE IMAGERY



CAMEX FLIGHT DAY 14 - SYNOPTIC CHARTS

MONDAY, SEPTEMBER 20, 1993





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CAMEX FLIGHT DAY 15 - ACTIVITY

CAMEX FLIGHT DAY 15 - SATELLITE IMAGERY



CAMEX FLIGHT DAY 15 - SYNOPTIC CHARTS

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TUESDAY, SEPTEMBER 21, 1993

CAMEX FLIGHT DAY 15 - WALLOPS RAWINSONDE

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CAMEX FLIGHT DAY 16 - ACTIVITY

CAMEX FLIGHT DAY 16 - SATELLITE IMAGERY



WEDNESDAY, SEPTEMBER 22, 1993



CAMEX FLIGHT DAY 16 - WALLOPS RAWINSONDE



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CAMEX FLIGHT DAY 17 - ACTIVITY

CAMEX FLIGHT DAY 17 - SATELLITE IMAGERY





THURSDAY, SEPTEMBER 23, 1993



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CAMEX FLIGHT DAY 18 - ACTIVITY

CAMEX FLIGHT DAY 18 - SATELLITE IMAGERY



FRIDAY, SEPTEMBER 24, 1993





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CAMEX FLIGHT DAY 19 - ACTIVITY

CAMEX FLIGHT DAY 19 - SATELLITE IMAGERY



CAMEX FLIGHT DAY 19 - SYNOPTIC CHARTS



SATURDAY, SEPTEMBER 25, 1993

CAMEX FLIGHT DAY 19 - WALLOPS RAWINSONDE



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CAMEX FLIGHT DAY 20 - ACTIVITY

CAMEX FLIGHT DAY 20 - SATELLITE IMAGERY



SUNDAY, SEPTEMBER 26, 1993




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CAMEX FLIGHT DAY 21 - ACTIVITY

CAMEX FLIGHT DAY 21 - SATELLITE IMAGERY



MONDAY, SEPTEMBER 27, 1993



CAMEX FLIGHT DAY 21 - WALLOPS RAWINSONDE



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CAMEX FLIGHT DAY 22 - ACTIVITY

CAMEX FLIGHT DAY 22 - SATELLITE IMAGERY



CAMEX FLIGHT DAY 22 - SYNOPTIC CHARTS



TUESDAY, SEPTEMBER 28, 1993

CAMEX FLIGHT DAY 22 - WALLOPS RAWINSONDE



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CAMEX FLIGHT DAY 23 - ACTIVITY

CAMEX FLIGHT DAY 23 - SATELLITE IMAGERY-VISIBLE



CAMEX FLIGHT DAY 23 - SATELLITE IMAGERY-WATER VAPOR



CAMEX FLIGHT DAY 23 - SYNOPTIC CHARTS



SEPTEMBER 29, 1993



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CAMEX FLIGHT DAY 24 - ACTIVITY

CAMEX FLIGHT DAY 24 - SATELLITE IMAGERY



CAMEX FLIGHT DAY 24 - SYNOPTIC CHARTS

THURSDAY, SEPTEMBER 30, 1993





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CAMEX FLIGHT DAY 25 - ACTIVITY

CAMEX FLIGHT DAY 25 - SATELLITE IMAGERY



CAMEX FLIGHT DAY 25 - SYNOPTIC CHARTS

OCTOBER 1, 1993





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CAMEX FLIGHT DAY 26 - ACTIVITY

CAMEX FLIGHT DAY 26 - SATELLITE IMAGERY



CAMEX FLIGHT DAY 26 - SYNOPTIC CHARTS

SATURDAY, OCTOBER 2, 1993



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CAMEX FLIGHT DAY 27 - ACTIVITY

CAMEX FLIGHT DAY 27 - SATELLITE IMAGERY



CAMEX FLIGHT DAY 27 - SYNOPTIC CHARTS







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CAMEX FLIGHT DAY 28 - ACTIVITY

CAMEX FLIGHT DAY 28 - SATELLITE IMAGERY





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CAMEX FLIGHT DAY 29 - ACTIVITY

CAMEX FLIGHT DAY 29 - SATELLITE IMAGERY



CAMEX FLIGHT DAY 29 - SYNOPTIC CHARTS

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TUESDAY, OCTOBER 5, 1993

CAMEX FLIGHT DAY 29 - WALLOPS RAWINSONDE


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CAMEX FLIGHT DAY 30 - ACTIVITY

CAMEX FLIGHT DAY 30 - SATELLITE IMAGERY



WEDNESDAY, OCTOBER 6, 1993



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CAMEX FLIGHT DAY 31 - ACTIVITY

CAMEX FLIGHT DAY 31 - SYNOPTIC CHARTS

THURSDAY, OCTOBER 7, 1993



SECTION V. CAMEX DATA ACCESS

Unlike TOGA COARE, NASA has no plans for a CAMEX data archive center. CAMEX data will be available on request from the CAMEX PI's. Each PI is individually responsible for the quality control of their data, and therefore, the date the datasets will be available may differ significantly. Although Marshall will acquire much of the ancillary and ground-truth data for our own research, we do will not have a complete archive of either, so CAMEX researchers should acquire ancillary data through the normal channels (i.e., from SSEC, National Climate Data Center, or the Earth Observing System Distributed Archive and Acquisition Centers). The ground-truth data will be available from the respective instrument PI's. Table 8, shown on the next page, gives the address, telephone numbers, and E-Mail for each of the CAMEX PI's.

Instrument	PI	Address
AMPR	Ms. Robbie Hood	ES-43
		Marshall Space Flight Center
		Huntsville, AL 35812
		Ph: (205) 544-5407 Fax: (205) 544-5760
		E-Mail: RHOOD@NASAMAIL.MSFC.NASA.GOV
Applied Physics Lab	Julius Goldhirsh	JHU-Applied Physics Lab
Research Vessel.		Johns Hopkins Road
The "Chessie" -		Laurel, MD 20723-6099
Tether-Sonde		Ph: (301) 953-5042 Fax: (301) 953-5548
Tomer Bonde		E-Mail: JULIUS@NANSEN.JHUAPL.EDU
EDOP	Dr. Gerald Heymsfield	NASA/Goddard Space Flight Center
		Code 912
		Greenbelt, MD 20771
		Ph: (301)286-6369 Fax: (301)286-4661
		E Mail:heymsfie@carmen.gsfc.nasa.gov
HIS and CLASS	Dr. Willam Smith	SSEC - CIMSS
Sondes		1225 West Dayton St.
		Madison, WI 53706
		Ph: (608)264-5325 Fax: (608)262-5974
		E Mail: Bills@ssecMail.ssec.wisc.edu
LIP	Dr. Rich Blakeslee	ES-43
		Marshall Space Flight Center
		Huntsville, AL 35812
		$\mathbf{F} \mathbf{M}_{\text{odd}} = \mathbf{N}_{\text{odd}} = \mathbf{N}_{o$
		E Mail. RBLAKESLEE@NASAMAIL.MSFC.NASA.00V
MAMS	Mr. Anthony Guillory	ES-43 Marshall Space Flight Center
		Huntsville AI 35812
		Ph: (205)544-6462 Fax: (205)544-5760
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WIIK	D1. James Wang	Code 975
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MTS	Mr. Mike Schwartz	Mass. Inst. Tech 26-345
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		Ph: (617)253-2571 Fax: (617) 258-7864
		E Mail: schwartz@jansky.mit.edu
Raman lidar	Dave Whiteman	NASA/Goddard Space Flight Center
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WFF Rawinsondes	Mr. Francis Schmidlin	NASA/GSFC Wallops Flight Facility
1		Wallops Is., VA 23337
		Ph: (804)824-1681 Fax (804)824-1036
		E Mail: FJS@OSD1.WFF.NASA.GOV

Table 8. CAMEX data contacts

APPROVAL

OPERATIONS SUMMARY FOR THE CONVECTION AND MOISTURE EXPERIMENT (CAMEX)

By

V. L. Griffin, A. R. Guillory, M. Susko, and J. E. Arnold

This report has been reviewed for technical accuracy and contains no information concerning national security or nuclear energy activities or programs. The report, in its entirety, is unclassified.

Gregory S. Wilson Director, Space Sciences Laboratory

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