| (NASA-CR-197803) USER S AND TEST | N95-26694 |
| :--- | :--- |
| CASE MANUAL FOR FEMATS (MiChigan |  |
| Univ.) $65 p$ | Unclas |

# User's and Test Case Manual for FEMATS 

Arindam Chatterjee, John Volakis, Mike Nurnberger and John Natzke

National Aeronautics
\& Space Administration Moffett Field, CA 94035


April 26, 1995
(2nd Revision)

Naval Weapons Center
China Lake, CA 93555-6001

# THE UNIVERSITY OF MICHIGAN 

Radiation Laboratory
Department of Electrical Engineering and Computer Science
Ann Arbor, Michigan 48109-2122
USA

## NASA Ames Grant NAG 2-866

## Grant Title:

Development and parallelization of the Finite Element Method with Mixed Termination Schemes

## Report Title*:

## Report Authors:

User's and Test Case Manual for FEMATS

Arindam Chatterjee, John Volakis, Mike

Primary NASA-Ames Collaborator:

University Address:

Nurnberger and John Natzke

John L. Volakis
volakis@um.cc.umich.edu
Telephone: (313) 764-0500

Alex Woo
woo@ra-next.arc.nasa.gov

Radiation Laboratory Department of Electrical Engineering and Computer Science The University of Michigan Ann Arbor, MI 48109-2 122

April 1995

Funds for the support of this study have been allocated in part by the NASA-Ames
Research Center, Moffett Field, California, under Grant No. NAG 2-866

# User's and Test Case Manual for FEMATS 

Arindam Chatterjee, John Volakis. Mike Nurnberger and John Natzke<br>Radiation Laboratory<br>Dept. of Electrical Engineering and Computer Science<br>University of Michigan<br>Ann Arbor, MI 48109-2122

April 26, 1995
(2nd Revision)

For FEMATS-related questions and bug reports, please call either John
Natzke at (313) 747-1794 or Mike Nurnberger at (313) 764-0502.

This work was supported in part by NASA-Ames Research Center, Moffett Field, CA, under Grant \#NAG2-866 (grant monitor Alex Woo; e-mail: woo@ra-next.arc. nasa.gov).

## Contents

1 Introduction ..... 3
2 Geometric Data Generation ..... 3
2.1 Solid modeling ..... 4
2.2 Mesh generation ..... 1
2.3 Modifying material property labels ..... 4
2.4 Type of meshing ..... 5
2.5 Grouping nodes ..... 5
2.6 Universal file ..... 5
3 Running FEMATS ..... 6
3.1 Preprocessing ..... 7
3.2 Input parameters ..... 10
3.3 Completing the FEMATS Run on a Supercomputer ..... 12
A Stipulations for Mesh Generation ..... 14
B Code Theory of Operation ..... 15
C Example FEMATS Run ..... 22
D I-DEAS Universal File Information ..... 28
E Benchmark Test Case Manual ..... 36
F Installation ..... 49
G Directory Listing of Full Distribution ..... 52
H References ..... 63

## 1 Introduction

The FEMATS program incorporates first order edge-based finite elements: and vector absorbing boundary conditions into the scattered field formulation for computation of the scattering from three-dimensional geometries. The code has been validated extensively for a large class of geometries containing inhomogencities and satisfying transition conditions (see [1] for formulation). For geometries that are too large for the workstation environment. the FEMATS code has been optimized to run on various supercomputers. Currently. FEMATS has been configured to run on the HP 9000 workstation, vectorized for the Cray Y-MP, and parallelized to run on the Kendall Square Research (KSR) architecture and the Intel Paragon.

## 2 Geometric Data Generation

The computation of scattering from a specific geometry with FEMATS is a multi-stage process, as shown in Figure 1. Once the geometric parameters of the target are known, a solid model is constructed in the Solid Modeling family of SDRC I-DEAS, a commercial CAD/CAE/CAM software package. The solid model is then exported to the Finite Element Modeling and Analysis family of I-DEAS, and the nodes and elements necessary for the scattering analysis are generated. This data is written to an output file, called a Universal file, and operated on by several preprocessors, generating the necessary input files for FEMATS.

The process of object modeling and mesh generation is an art, not a science. Hence, it cannot be taught, or demonstrated-it must be learned through experience. Hence, this manual is not by any means an I-DEAS FE mesh generation manual. In fact, it assumes (and requires) a working knowledge of, and familiarity with, the I-DEAS Solid Modeling and Finite Element Analysis families of tasks.


Figure 1: Stages involved in scattering computation from arbitrary 3D geometries

### 2.1 Solid modeling

Once the geometry of the target is specified, it is constructed using the I-DEAS Solid Modeling Family of tasks. There is a tendency to downplay the importance of the solid model. and treat it only as a stepping stone towards a final product. However. the solid model is the framework for the finite element mesh. and as such. has a direct bearing on the quality of the mesh. Because of this, it is wise to keep the mesh generation problem as simple as possible. This helps to ensure a better mesh, and a more accurate answer.

In general, the object or body being meshed will contain various planes of symmetry. It is nearly always advisable to take advantage of whatever symmetry is available, as doing so will greatly reduce the amount of time necessary to generate the mesh and the amount of storage space it requires. In fact, the geometry may require such subdivision to make meshing possible. For more details about the creation of the solid model for FEMATS, please see the I-DEAS Solid Modeling User's Guide.

Note: When creating the Solid Model, FEMATS requires the dimensions to be in wavelengths.

### 2.2 Mesh generation

I-DEAS generates the finite element mesh by creating mesh areas on surfaces, and then combining these mesh areas into mesh volumes ( $2 \frac{1}{2}$ - D mesh generation). Each mesh volume is then filled with the chosen element type. When the solid model is imported into the Finite Element Modeling and Analysis Family of I-DEAS, these mesh areas and mesh volumes are automatically created. Generally, however, I-DEAS does not choose the correct element order (linear vs. parabolic), and the mesh volumes must be modified to reflect the correct element order. Even if the guidelines mentioned in Section 2.1 are followed, the mesh areas that are auto-created by I-DEAS can become quite complex. It is then prudent to break the mesh volume into smaller, more manageable mesh volumes. For more details on mesh creation, please see the I-DEAS Finite Element Modeling User's Guide.

### 2.3 Modifying material property labels

After all the mesh volumes have been created, the material property labels of each need to be modified according to the type of material each mesh volume contains. The elements in the volume between the target and the outer boundary usually have a material property label of 1 . If the target contains a dielectric-filled volume, the material property labels of the elements in that volume should be 2 . In this way, the code can accommodate up to 9 different material fillings. If the geometry requires more than 9 different materials,
the dimensions of the vectors $\epsilon$ and $\mu$ should be moditied (wherever the appear) to reflect the necessary number of materials.

Please see Appendix A for more details.

### 2.4 Type of meshing

The global element length also needs to be specified (usually $0.075-0.085$ units); finer meshing can be done in regions with rapidly changing fields or large curvatures by specifying the local element length or curvature-based size parameters. The geometry is then fref-meshed using the I-DEAS Mesh Creation Task. It is essential to use free meshing and not mapped meshing. since the latter maps the mesh volume into a rectangular box and back. thus distorting the elements. No such distortion occurs in space when an electromagnetic wave travels through it; a mapped mesh, therefore, alters the physics of the problem and leads to inaccuracies in the final result.

Please see Appendix A for more details.

### 2.5 Grouping nodes

The finite element method essentially solves a boundary value problem; thus, it is crucial to identify surfaces or surface edges on which the boundary conditions are imposed. In the current version of FEMATS, this is carried out by grouping the nodes which lie on the surfaces where the boundary conditions are imposed. If the surface nodes coincide with a perfect electric conductor, the group is labeled $C$, if the nodes lie on a resistive sheet, the group is labeled $R$, and so on. Detailed information about node grouping is given in Appendix A.

Care must be taken when grouping surfaces that intersect, since edges connecting two such nodes may not lie on the surface at all. For example, suppose three surfaces intersect at the corner of a cube. If the nodes on each of these surfaces are not grouped separately, the processing program will generate 'surface' edges which actually do not lie on the surface. Another anomaly may arise when the surfaces are separated by a single element. This is due to the fact that the processing program considers an edge to lie on the surface if two nodes in the group connect to form an edge. As a rule of thumb, it is best to group each surface separately. They may be grouped together only when the user is certain that spurious surface edges will not be created by the processing program.

### 2.6 Universal file

The mesh information obtained from I-DEAS is then written to an ASCII file called the Universal file. The Universal file has a specific format for identifying the nodes, elements, and groups which can be obtained from the I-DEAS User's guide.

It should be noted that only the FE entities and (iroups need to be included in the Liniversal file. and the specific format required by FEMATS is described in great detail in Appendix D. Also. while this discussion has dealt primarily with I-DEAS. any mesh generator that writes a l niversal file will work just fine.

## 3 Running FEMATS

As shown in Figure 1, two processing stages are necessary to obtain the final output once the universal file has been generated for the specified geometry. The preprocessing stage is performed by a number of smaller programs that operate on the Universal file to construct the necessary geometry data files in the specific format required by FEMATS. For a given geometry, this operation only needs to be done once. FEMATS also requires the input parameters, such as the material properties, desired tolerance, maximum number of iterations, and aspect parameters (type of pattern, etc.), to be specified for each subsequent run. The main processor then reads in all of the geometry data and run-time parameters and returns the backscatter or bistatic pattern in a separate file. See Appendix B for a description of the code theory of operation.

The preprocessing and main processing programs are all initiated by a single script. The only exception is if the final processing is to be done on a different machine. In most cases this would be a supercomputer, and the preprocessing would have been done on the workstation. This requires that a second script be started on the supercomputer once the geometry and run-time data files have been transferred. It is recommended that all of the preprocessing be done on the workstation, since it is much more efficient.

To run the FEMATS script, type
femats file.unv
where file.unv is the name of the universal file containing the mesh information. All of the subsequently created files containing the geometry data and input parameters are given the same prefix file as the universal file. If the preprocessing of the universal file has not yet been done, these programs are started and the user must respond to a number of prompts, as explained below in Section 3.1. Otherwise, if this preprocessing has already been accomplished, the user is asked:
Do you wish to preprocess file.unv again ( $\mathrm{y} / \mathrm{n}$ )?
which may be necessary if a correction must be made in the preprocessing or if a change has been made to file.unv. In either case, the user is next prompted for the input parameters for that particular run, which are described in detail in Section 3.2. Upon completing the input parameters, the user is asked:

Will the final processing be done on a different machine ( $y / n$ )?
If no. then the final processing will be done on the same machine. and the FEMATS script will continue by intiating the main processor program. A complete example run is shown in Appendix ( for this case using an HP workstation. Otherwise, if the final processing is to be done on a different machine, then the script will tar and compress all of the required data files. producing the single file file.tar. Z. This file should then be transferred to the other machine, and the appropriate script used to complete the processing as described in Section 3.3.

Note: For efficiency, the dimensioning of the arrays in the source files may be changed to reflect the size of the problem. For the preprocessor files. the relevant dimension statements are contained in the file

```
(path)/femats/src/preproc/parmvl
```

For the re-dimensioning to take effect, recompile the preprocessors by typing make all in the (path)/femats/src/preproc directory. Similarly, for the main processor source files, the relevant dimension statements are in the file

```
(path)/femats/src/{arch}/fem_data.h
```

For these changes to take effect, recompile the necessary files by typing make all in the (path)/femats/src/\{arch\} directory, where $\{\operatorname{arch}\}$ is the architecture (either cray, hp, ksr, or paragon). If any of the array dimensions are too small for a particular geometry, an overflow error will be given.

### 3.1 Preprocessing

The preprocessing stage requires a knowledge of the construction of the FE mesh contained within the universal file. The prompts given by the preprocessor programs are as follows:

Does geometry mesh need to be reflected? 1) yes 2) no
As discussed in Sections 2.1 and 2.2, it is judicious to take advantage of any inherent symmetry of the geometry when creating the FE mesh. If this has been done, then the first part of the preprocessor reflects the elements and nodes given the following information.

Enter separation dist. for nodes to be coincident:
A typical value is 0.001 . This information is required so that the nodes lying on the reflection boundaries are not reflected.

Reflect along 1) $x-y$ plane 2) $y-z$ plane or 3 ) $z-x$ plane?

The plane of reflection must be specified. Multiple reflections are done one at a time.

Point of reflection on w-axis:
where $w=x, y$, or $z$ for the $y-z, z-x$, or $x-y$ plane of reflection, respectivels. Enter the point about which the reflection is to be made.

Reflect all permanent groups ? 1) yes 2) no
By making this distinction, the preprocessor can allow for some asymmetries in the geometry. If all of the groups are not to be reflected, then a list of the defined groups is given-

| Group \# | Material Type |
| :---: | :---: |
| 1 | C |
| 2 | C |
| 3 | A |
| 4 | A |
| 5 | D |
| 6 | 0 |

In this example, there are six permanent groups which have been defined in the universal file. The material types correspond to the definitions given in Appendix A, and the numbering corresponds to their order of inclusion in the universal file.

Total no. of groups not to be reflected:
Group(s) not to be reflected:
Enter the number of groups and then the specific groups identified by their group numbers which should not be reflected.

One more reflection? 1) yes 2) no
Repeat the above process until all of the reflections are completed.
Once the reflections (if necessary) have been completed, the user is asked to input the specifications of the outer boundary, i.e. the mesh termination. The code works for spherical, cylindrical, or flat mesh termination boundaries or any combination of these. All dimension values should be entered in units of wavelengths.

```
Choose type of outer boundary used to terminate
the mesh (i.e., its shape AFTER reflecting):
    1) spherical, 2) cylindrical, 3) rectangular box,
    4) mixed boundary
```

For the first three cases, the user is prompted for the center coordinates in $(x, y, z)$ and the pertinent dimensions of the boundary shape. Fior an outer boundary having any other shape. the user should enter it to choose the mixed boundary type.

MIXED ---
Enter no. of separate surfaces in outer boundary:
The total number of distinct surfaces in the outer boundary must be entered for the mixed boundary type. For example, a cylinder with rounded ands has three separate surfaces-- the cylindrical surface and the two spherical surfaces at the top and at the bottom.

```
Enter X,Y,Z coordinates of the center and the
radius of each surface:
    For a SPHERICAL section --
        Center coordinates xc yc zc and radius
    For a CYLINDRICAL section --
        X-directed axis - 200000. yc zc radius
        Y-directed axis - xc 200000. zc radius
        Z-directed axis - xc yc 200000. radius
    For a PLANAR section --
        Parallel to YZ plane - xc 200000. 200000. 0.
        Parallel to ZX plane - 200000. yc 200000. 0.
        Parallel to XY plane - 200000. 200000. zc 0.
```

The program needs the center coordinates and the radius of each distinct surface on the mesh termination for the mixed boundary type. For a spherical section, this poses no problem. In order to have complete information about a cylindrical section, we require its axis direction as well as the center coordinates and the corresponding radius of the curved surface. For example, a cylinder whose axis is oriented along the $x$-axis and is centered along $(x, 1,-1)$ with a radius of 2 is described by the following input line:
200000. 1. -1. 2.

Similarly, a flat planar section parallel to one of the principal planes is determined uniquely by specifying the magnitude of the constant coordinate. For example, the $z=2$ plane is described by the following input line:
200000. 200000. 2. 0.

In this way, a combination of simple surfaces making up the outer termination boundary can be input to the program. FEMATS handles only these three surfaces types at present since these lead to symmetric systems of equations when incorporated into the finite element matrix. The theory can handle any doubly curved surface; they would, however, lead to an unsymmetric system of linear equations.

There remains one last set of specifications for the preprocessor-

Does input geometry contain any 2-D objects, or are they strictly $3-D(2 / 3) ?$

By definition. a 2-D object is one which is infinitesimally thin and bounded by FE mesh elements on both sides, e.g. an open PEC surface or an open or closed resistive surface. Included in this definition is the far-field integration surface when it is taken over an open surface. If there are any 2 -D objects. then more information is required as follows:

```
Any 2-D objects contained within the geometry are
associated with one or more of the following surface groups:
    1) PEC, 2) R-card, 3) Impedance sheet, or
    4) Far-field integration surface
```

How many of these 4 surface group types describe 2-D objects?
Enter surface group type(s) as numbered above:

Enter the total number of surface group types which describe 2-D objects and then the specific surface group types as identified in the list.

### 3.2 Input parameters

The input parameters are those which the user may want to alter each time FEMATS is run. For the user's convenience, the default or previous parameter values appear in the brackets '[]' with each prompt; one simply hits return to use these values.

If there are two or more material property labels defined in the universal file, then the following prompts will occur:

The geometry contains $n$ different material property labels --
For material property label 1, eps=(1.,0.), mu=(1.,0.).
For material property label $i$, enter
eps: [ (1.,0.) ]

```
mu: [ (1.,0.) ]
```

Input the complex constitutive relative parameters, $\epsilon$ and $\mu$, for each material property label $i=2, \ldots, n$. Note that material property label 1 is free-space by default. If the mesh designates material property label 1 to anything other than free-space, the program will not run.

If there is a resistive card inside the geometry (this version can handle only one), then the user must

```
Input: a) Material property label on top of card
    b) Material property label on bottom of card
    c) Normalized resistivity
```

The mesh must be constructed in such a way that the material properts labels on the top and bottom surfaces of the R-card are different. Likewise. if there is an impedance sheet within the geometry. the user will be prompted to

Input: a) Material property label on top of impedance sheet
b) Normalized impedance

The data entered until now has been related to the material properties of the geometry. The data entered from this point will be related to the iteration count, number of look angles, etc.:

Enter required tolerance: [ 0.0005 ]
The tolerance of the residual is usually kept between 0.001 and 0.0005 . This is $0.1 \%-0.05 \%$ of the solution norm.

Maximum iterations: [ 15000 ]
The maximum number of iterations is determined by trial and error. A typical value for PEC targets is $N / 100$ for $N>25000$ and $N / 120$ for $N>75000$. The code uses a diagonally preconditioned biconjugate gradient method to solve the system, so the residual error will jump to abnormal values quite frequently.

1) Bistatic or 2) Backscatter: [ 2 ]

Enter 1 for a bistatic pattern, 2 for backscatter.

```
All angle values should be integers ---
Bistatic
Angle of incidence --
Theta: [ 0 ]
Phi: [ 0 ]
Angle of observation --
Fix angle 1) phi or 2) theta? [ 1 ]
Specify value of fixed angle: [ 0 ]
For sweep angle theta, enter
    start: [ 0 ]
    end: [ 90 ]
```

    increment: [ 5 ]
    Either $o$ or $\theta$ is set to a fixed angle. Then the other angle becomes the sweep angle.

```
Backscatter
-----------
Angle of incidence --
Fix angle 1) phi or 2) theta? [ 1 ]
Specify value of fixed angle: [ 0 ]
For sweep angle theta, enter
    start: [ 0 ]
    end: [ 90 ]
    increment: [ 5 ]
```

For each increment in the sweep angle for the backscatter case, FEMATS will generate 4 additional RCS data points between $\pm 2^{\circ}$ of the increment angle using a bi- to monostatic conversion. Thus a $5^{\circ}$ increment yields a computed pattern in $1^{\circ}$ increments.

Polarization angle (alpha=0 $\Rightarrow H_{-} z=0$, alpha=90 $\Rightarrow E_{-} z=0$ ): [ 90 ]
Enter the desired polarization angle.
Do you wish to re-enter any of the input parameters ( $\mathrm{y} / \mathrm{n}$ )? [n]
The user is given the option of going through the run-time specifications over again to make any changes to the input parameters. Any parameters that had been entered become the default values for the next pass through.

### 3.3 Completing the FEMATS Run on a Supercomputer

The following instructions assume that the preprocessing has been done on a different machine, in most cases a workstation. The final processing of the job on the supercomputer is then completely non-interactive.

After the compressed tar file file.tar. $Z$ has been transferred to the supercomputer, a script is run there to initiate the main FEMATS program. To run this script, type

$$
\text { femats. }\{\operatorname{arch}\} \text { file }
$$

where $\{\operatorname{arch}\}$ is either cray, ksr, or paragon, and file is the prefix name of the original universal file. After uncompressing and untarring the given file, this script will initiate another preprocessor to convert the mesh data files
from ASC'Il to binary format. On the supercomputers. it is more efficient id read the mesh files in binary format. since the ASCll fomat is quite slow for most machines and prohibitively slow on the KSR. The script will then continue by initiating the main program. Specific runtime information is given below for each of the supported architectures.

## Cray-specific run-time information

The code was only vectorized on the Cray series of machines. Thus it always runs on a single processor with enhanced vectorization. To execute FEMATS. type
./femats.cray file
as shown above.

## KSR-specific run-time information

Before executing FEMATS, the user must inform the operating system of the required number of processors. To do this, type

```
allocate_cells -A
where \#\# is the requested number of cells. This command starts a new shell, and gives that shell control of \#\# cells. Because of this, it is important to exit the shell when FEMATS finishes, so that others may use the processor cells. After the new shell is running, the user must let the operating system know how many total threads it may run on the allocated cells by typing
```

setenv PL_NUM_THREADS \#\#

```
where \#\# is the same as in the previous command. FEMATS may now be run safely.

If any problems arise, consult the KSR manuals, and the system administrator. The above steps assume that everything works the way it is supposed to.

\section*{Intel Paragon-specific run-time information}

To execute FEMATS on the Paragon, type
```

femats.paragon file -sz \#\#

```
where \#\# is the number of processors to be used.

\section*{Appendices}

\section*{A Stipulations for Mesh Generation}
- The region surrounding the scatterer should have a material property label of 1 . i.e., the least possible value.
- For a surface draped by a resistive card, it is essential to differentiate the top surface from the bottom surface of the resistive card. The only way the program can discern this from the available data is by checking the material property labels of the elements on the top and bottom surfaces. The material property label of the top surface must therefore be different from that of the bottom surface.
- When meshing a mesh-volume filled with a dielectric having a certain permeability and permittivity, the material property label of the dielectric should be different from that of the surrounding mesh.
- When grouping surface nodes, the group labels should start with a
- C for nodes that lie on a perfect electrical conductor
- \(\mathbf{R}\) for nodes that lie on a resistive card
- I for nodes that lie on an impedance sheet
- D for nodes that lie on a dielectric or on the interfaces of materials having different constitutive parameters
- A for nodes that lie on the outer boundary (i.e. on the mesh termination)
- O for nodes that lie on the far-field integration surface, usually the outer surface of the scatterer

The above order ( \(\mathrm{C}, \mathrm{R}, \mathrm{I}, \mathrm{D}, \mathrm{A}, \mathrm{O}\) ) must be maintained when grouping nodes.

\section*{B Code Theory of Operation}

\section*{proc.f}
proc.f consists of the programs u2c.f and c2p.f. It converts the mesh information stored in the Universal file into a more usable form for analysis by FEMATS. It first reads in the nodal co-ordinates. nodal comectivity and the grouped nodes from the Universal file. Since FEMATS uses edge-based shape functions, the edges and the nodes connecting them need to be identified. Because each edge is shared by more than one element, care must be taken so that the same edge is not counted more than once. A comparison of the connecting nodes must therefore be made to identify the old edges. and create the new ones. This can be a computationally intensive task if a brute force approach is taken, especially if the problem size is very large. It is necessary to use an algorithm that would scale at most linearly with the number of nodes or edges, i.e. the number of comparisons required for identifying old or new edges should be an \(O(N)\) process.

In order to realize this requirement, the ITPACK scheme [2] is utilized to store the node connectivity information. The ITPACK scheme is attractive because the number of comparisons required while augmenting the connectivity matrix depends only on the locality of the corresponding node and not on the total number of nodes or edges. In the ITPACK storage scheme, the number of rows of the connectivity matrix is equal to the number of nodes and the number of columns equals the maximum number of nodes connected to a particular node. However, this approach wastes space when the number of connecting nodes varies widely, so a modified ITPACK format is usedthe number of columns in the connectivity matrix now equals the average number of nodes connected to a particular node, and the number of rows is slightly more than the total number of nodes. The storage requirement for such a matrix is usually \(1.1 N_{n} \times 16\) integers, where \(N_{n}\) equals the number of nodes.

After generating the edges, FEMATS uses the same storage scheme for finding the surface edges and elements from the grouped nodes. These surface edges are then sorted in ascending order by element number for the various materials and boundaries on which they lie. All components of the code are extremely fast, with the slowest being the sorting routine.

The output data files from proc.f are given the following extensions:

\section*{- enode}

Contains coordinates of all the nodes in the geometry.
- eglob

Contains the edges making up each element.
- edge

Contains the nodes making up each edge.
- esize

Contains the number of nodes. elements. and edges in the geometry. as well as the number of elements with surface edges on the PEC. Rcard. impedance. dielectric. outer boundary: and far-field integration surfaces. This information is also contained in otpt with explanatory text.
- esurfed

Contains the element number, node numbers and corresponding edge numbers of the on-surface edges.
- geom

Contains the number of different material property labels and the specifications of the surface(s) making up the outer boundary.

Required storage is about \(18 N\) real Words, where \(N\) is the number of unknowns and is equal to the number of edges making up the mesh.

\section*{count.f}
count.f reads from the files eglob and esize and calculates the number of non-zero entries per row for the finite element system. The number usually varies from 9 to 31 for a typical system. The output is written to cntr, and the required storage is about \(13 N\) real Words, where \(N\) again denotes the number of unknowns.

\section*{prompt.f}

This program prompts the user for the necessary run-time parameters required by FEMATS. These parameters include any material properties that need to be specified, the desired tolerance, maximum number of iterations, and the aspect parameters (type of pattern, etc.). The run-time data file that is created has the extension in.

\section*{fr.f}

When the main processing of FEMATS is done on a supercomputer, fr.f is used to convert the mesh files from ASCII to binary format.

\section*{fem.f}

This is the main program (FEMATS) which computes backscatter or bistatic patterns after reading in the geometry data files created by proc.f and count.f and the run-time parameter file created by prompt.f. The backscatter or bistatic pattern is returned in a separate file. If the code fails to run for some reason, a list of errors is returned in the error file. The flow of control
of FEMATS is given in Figure 2 . The formulation for the me thodolege is given in [2].

Input filts: The input files containing the geometry and mesh information and parameters for running the problem are read in. When run on the supercomputer. the mesh files are read in binary format. since the ASC'Il format is quite slow for most machines and prohibitively slow on the KSk.

Proctssing data: Some preliminary processing is done to verify the radii of the outer boundary surfaces which were declared in proc.f.

FE matrix generation/assembly: The finite element matrix generation is done on an element-by-element basis. The elemental matrix is first computed. and then assembled into the global sparse matrix. The assembly is simplified since the number of non-zero entries per row of the matrix is known apriori and the order of the entries is not important. The non-zero entries of the final sparse matrix are stored in a long complex vector, the corresponding column numbers are stored in an integer vector, and the location of the first non-zero entry for each row is stored in another integer vector. This is the well-known Compressed Sparse Row (CSR) format used in public domain software packages like SLAP and SPARSPAK. The coefficient matrix is not a function of the angle of incidence.

The code also uses a simple diagonal preconditioner for speeding up the iterative process. Other complicated preconditioning strategies are also available. However, except for the block ILU preconditioner, none of them compare favourably with the point diagonal preconditioner in terms of solution time.

Excitation vector generation: The excitation vector generation is not very CPU-intensive, since the vectors are always quite sparse. It is a function of the angle of incidence.
\(B C G\) iteration: The biconjugate gradient (BCG) algorithm is used with preconditioning to solve the sparse, symmetric system of linear equations. Each iteration of the algorithm involves 1 sparse-matrix vector product, 3 vector updates and 3 inner products. The norm of the residual vector is computed after every iteration to check for convergence. Reliable results have been obtained by setting the convergence criterion to be
\[
\left\|r^{k}\right\|<0.001 *\|b\|
\]
where \(r^{k}\) is the residual vector after the \(k\) th iteration and \(b\) is the excitation vector.

Far-field evaluation: The far-field is evaluated by integrating the nearzone fields over a closed surface using the Stratton-Chu integral equation. The surface is usually taken to be very close to or on the body itself to achieve maximum accuracy.

Storage required for the code is at present 36 N complex Words, where \(N\) is the number of unknowns. The storage can be cut by \(40 \%\) if only the


Flowchart of finite element code
Figure 2: Flowchart for FEMATS
smmetric upper triangulat part of the object matrix is stored: the code. however. slows down significantly.

\section*{Subroutine functions in fem.f}

\section*{basis.f}

Calculates the two constant vectors of the bases for the finite element discretization as well as the element volume.

\section*{bd1.f}

Assigns each surface element on the mesh termination boundary its surface particulars.

\section*{bi2mono.f}

Computes the far-field pattern for a particular angle of incidence. If a monostatic pattern is desired, then monostatic values are approximated for the computed angle of incidence as well as for the four adjacent angles between \(\pm 2^{\circ}\).
bicg.f
The diagonally preconditioned biconjugate gradient solver for symmetric, linear systems of equations.
calc.f
Computes the volume integral for the finite element discretization analytically.

\section*{comput.f}

Calculates the basis functions at the mid-point of each edge.
crux.f
Computes the element matrix from the volume integral.

\section*{cruxd.f}

Imposes the boundary condition for dielectric volumes and generates the corresponding excitation vector.
diag.f
Generates the diagonal preconditioner for solving the system of equations iteratively.
f1.f
Carries out the volume integration of \(\mathbf{W}_{i} \cdot \mathbf{W}_{j}\) analytically.

\section*{fcmb.f}

Carries out the surface integration for the absorbing boundary condition
employed on the mesh termination boundary:
finc.f
Computes the volume integral for a dielectric volume to be used in the excitation vector.
hpsrt.f
A standard heapsort routine.
incc.f
Imposes the boundary condition for a perfect electric conductor. If iter is 0 , the excitation vector is computed, otherwise changes are made to the element matrix.

\section*{incd.f}

Imposes the boundary condition for a dielectric surface.

\section*{inci.f}

Imposes the boundary condition for an impedance sheet.
incr.f
Imposes the boundary condition for a resistive card.
mat.f
Performs finite element matrix generation and assembly.

\section*{mult.f}

Carries out the sparse matrix-vector multiplication for the iterative solver.
norm2d.f
Computes the element normal for a 2D geometry.
norma.f
Computes the element normal for a surface element.

\section*{ops.f}

Performs elementary vector and matrix operations.

\section*{ord.f}

Identifies the global nodes and edges in the local context.
sort.f
Sorts the edges in a element according to a specific numbering scheme.
surfint.f
Imposes the absorbing boundary condition on the mesh termination boundary.

\section*{value.f}

Computes the far-field using the Stration-Chu integral equation.
volume.f
Calculates the element volume.
xc.f

Generates the excitation vector for each angle of incidence.

\section*{C Example FEMATS Run}

A \(0.3 \times 0.3 \lambda\) perfectly conducting plate was run on an HP 9000/i1.5 workstation. The geometry was enclosed by a spherical outer boundary and the backscatter pattern was sought for \(\theta=0-10^{\circ}\) with \(\alpha=90^{\circ}\). The problem had 9712 unknowns and a diagonally preconditioned BCG solver was used. (This transcript is contained in the subdirectory femats/test/hp. along with the original universal file and output files.)
```

tull% femats small_plate.unv
femats.pre: starting femats preprocessor...
u2c: processing I-DEAS Version 6 format Universal file small_plate.unv...
u2c: perform whatever manipulations are necessary.
Name of universal file ?
small_plate.unv
There are 478 nodes in the geometry.
There are 1846 elements.
There are 3 groups containing 213 nodes.
Max. volume = 8.45531E-04, Min. volume = 2.52417E-06
Element with min. volume = 1278
REFLECTION SPECIFICATIONS
Does geometry mesh need to be reflected? 1) yes 2) no
1
Enter separation dist. for nodes to be coincident:
001
Reflect along 1) x-y plane 2) y-z plane or 3) z-x plane?
2
Point of reflection on x-axis:
0.
There are now }881\mathrm{ nodes and }3692\mathrm{ elements
Number of old groups = 3
Reflect all permanent groups ? 1) yes 2) no
1
Number of new groups = 6
One more reflection? 1) yes 2) no
1
Reflect along 1) x-y plane 2) y-z plane or 3) z-x plane?
3
Point of reflection on y-axis:
O
There are now }1625\mathrm{ nodes and }7384\mathrm{ elements
Number of old groups = 6
Reflect all permanent groups ? 1) yes 2) no

```
```

1
Number of new groups = 12
One more reflection? 1) yes 2) no
2
After reordering -
There are 12 surface groups containing }852\mathrm{ nodes.
OUTER BOUNDARY SPECIFICATIONS
Choose type of outer boundary used to terminate
the mesh (i.e., its shape AFTER reflecting):
1) spherical, 2) cylindrical, 3) rectangular box,
4) mixed boundary
1
Enter center coordinates (x,y,z) and radius:
0. 0. 0. . }4
u2c: done.
femats.pre: Does input geometry contain any 2-D objects,
or are they strictly 3-D (2/3)? 2
c2p_2d: Enter required data as necessary.
c2p_2d: please be patient...this could take a while...
Reading in data . . .
Be patient
Starting surface node generation...
Any 2-D objects contained within the geometry are
associated with one or more of the following surface groups:
1) PEC, 2) R-card, 3) Impedance sheet, or
4) Far-field integration surface
How many of these 4 surface group types describe 2-D objects?
2
Enter surface group type(s) as numbered above:
14
Finding/sorting surface edges and faces . . .
Problem size ---
There are }1625\mathrm{ nodes and 7384 elements
Edge count = 9712
180 element faces/edges on the pec
O surface elements on resistive sheet
O surface elements on impedance sheet
O surface elements on dielectric

```
```

    1408 surface elements on outer boundary
    6 4 \text { surface elements on integration surface}
    c2p_2d: done.
count: processing data files.
count: please be patient...this could take a while...
Average bandwidth 15
Peak bandwidth 31
count: done.
femats.pre: the following geometry data files have been created:
small_plate.cntr, small_plate.edgy, small_plate.eglob,
small_plate.enoddy, small_plate.esize, small_plate.esurfed,
small_plate.geom
prompt: starting prompts for run-time input data...
RUN-TIME SPECIFICATIONS
NOTE: to use default values appearing in the [],
simply hit return.
Enter required tolerance: [ 5.00000E-04 ]
Maximum iterations: [ 15000 ]
1) Bistatic or 2) Backscatter: [ 2 ]
All angle values should be integers ---
Angle of incidence --
Fix angle 1) phi or 2) theta? [ 1 ]
Specify value of fixed angle: [ 0 ]
Note: For each increment in the sweep angle, femats will
generate 4 extra RCS data points between +/- 2 deg
using a bi- to monostatic conversion. Thus a 5 deg
increment yields a computed pattern in 1 deg increments.
For sweep angle theta, enter
start: [ 0 ]

```
```

    end: [ 90 ]
    10
increment: [ 5 ]
Polarisation angle (alpha=0 => H_z=0, alpha=90 => E_z=0): [ 90 ]
Do you wish to re-enter any of the input parameters (y/n)? [n]
prompt: the run-time data file small_plate.in has been created
femats: Will the final processing be done on a different
machine ( }\textrm{y}/\textrm{n}\mathrm{ )? n
femats: continuing with processing
fr_hp: doing overflow check of dimensioned arrays
Prefix name of input file:
small_plate
fr_hp: done.
femats: starting femats main processor...
Prefix name of input data files:
small_plate
************************************************
Problem size
Number of nodes = 1625
Number of elements = 7384
Number of edges/unknowns = 9712
***************************************************
No. of surface faces on
1) PEC : }18
2) R-card : 0
3) Impedance sheet : 0
4) Dielectric interface : 0
5) Outer boundary (mesh term.) : 1408
6) Far-field integration surface : 64
***************************************************
Outer boundary shape is
Spherical
***************************************************
Backscatter pattern will be computed
Incident angle from 0 to 10
in steps of 5
Sweeping through theta; phi = 0

```
```

Polarisation angle = 90

```

```

Reading in element/edge/node data . . .
Time spent for unformatted I/O = 2.1484375 secs
Time spent for I/O = 2.2109375 seconds

```

```

Generating finite element matrix . . .
Outerloop --
.0000 .0000 90.0000
Gen_vector_soln . . .
Solver . . .
iter= 100, tol= .05493, time= 18.4297s
iter= 200, tol= .00914, time= 36.3750s
iter= 300, tol= .00536, time= 54.2734s
iter= 400, tol= .00267, time= 72.0000s
Convergence achieved in 435 iterations
Time spent in 435 iterations = 78.234375 seconds
Comput_results . . .
Monostatic angle = .0 for incidence of 0
Backscatter RCS = -5.16235124511881 dB
Monostatic angle = 1.0 for incidence of 0
Backscatter RCS = -5.16404174641413 dB
Monostatic angle = 2.0 for incidence of 0
Backscatter RCS = -5.1691052748699 dB
5.0000 .0000 90.0000
Gen_vector_soln . . .
Solver . . .
iter= 100, tol= .02634, time= 17.7031s
iter= 200, tol= .01121, time= 35.4063s
iter= 300, tol= .00413, time= 53.1172s
iter= 400, tol= .00180, time= 70.8984s
iter= 500, tol= .00205, time= 88.5938s
Convergence achieved in }517\mathrm{ iterations
Time spent in 517 iterations = 91.640625 seconds
Comput_results . . .
Monostatic angle = 3.0 for incidence of 5
Backscatter RCS = -5.18361322126989 dB
Monostatic angle = 4.0 for incidence of 5
Backscatter RCS = -5.18762443806741 dB
Monostatic angle = 5.0 for incidence of 5
Backscatter RCS = -5.1949990584817 dB

```
```

Monostatic angle = 6.0 for incidence of 5
Backscatter RCS = -5.20570715150933 dB
Monostatic angle = 7.0 for incidence of 5
Backscatter RCS = -5.21970412507492 dB
10.0000 .0000 90.0000
Gen_vector_soln . . .
Solver . . .
iter= 100, tol= .03225, time= 17.8516s
iter= 200, tol= .00699, time= 35.5859s
iter= 300, tol= .00945, time= 53.2891s
iter= 400, tol= .01602, time= 71.0000s
iter= 500, tol= .00215, time= 88.7031s
Convergence achieved in 524 iterations
Time spent in 524 iterations = 92.984375 seconds
Comput_results . . .
Monostatic angle = 8.0 for incidence of 10
Backscatter RCS = -5.2621385331921 dB
Monostatic angle = 9.0 for incidence of 10
Backscatter RCS = -5.27505870524297 dB
Monostatic angle = 10.0 for incidence of 10
Backscatter RCS = -5.29124158611137 dB
Total computational time = 266.734375 seconds
Output files --
Table of RCS data: tab.mon.p0.90
Total RCS vs. sweep angle: rcs.mon.p0.90
for a fixed angle phi = 0 with alpha = 90.

```

\section*{D I-DEAS Universal File Information}

To facilitate development of data file translators for mesh generation packages other than I-DEAS, a brief (but hopefully complete) description of the universal file format and the pertinent datasets follows. Each universal file is a sequentially-formatted text file containing records a maximum of 80 characters long, and is divided into sections called datasets. Between datasets. the universal file may contain lines (e.g., comments) which are not part of any dataset and will be ignored.

\section*{Datasets}

The first and last record of each dataset is marked by the dataset delimiter. which consists of a minus sign in column 5 and a numeric one in column 6 . The remainder of the line is blank. The second record in the dataset is the dataset type. This is an integer between 1 and 32767 , right-justified in columns 1 through 6 . The remainder of the line is blank. The rest of the records in the dataset follow the format specified for that dataset in the I-DEAS manual. The pertinent ones for FEMATS are discussed below.

\section*{Universal file processing}

Processing of the universal file begins by searching for the first dataset delimiter. Next, the dataset type line is read to determine whether the program needs to process this dataset. If the dataset is to be processed, the program reads the data per the specifications for that dataset. Otherwise, the program skips to the next dataset delimiter, which marks the end of the dataset, and begins the search process for another dataset delimiter again. This cycle continues until the end of file condition is reached.

It should be noted that the end of file condition should only occur between datasets. An end of file occuring during dataset processing indicates an incomplete dataset. Finally, datasets may occur in any order in the universal file, but with the restriction that a dataset may reference data in other datasets only if the other dataset precedes it in the file.

\section*{FEMATS-specific datasets}

As mentioned above, FEMATS only requires two sets of data-the FE Entities and the Groups. This is equivalent to three datasets in the universal file-datasets 752, 780, and 781. These are, respectively, the Permanent Groups, the Elements, and the Double Precision Nodes datasets. A description of each follows, along with an example. The format description for each line is given in terms of the FORTRAN equivalent.

\section*{Dataset 752: Permanent groups}

Record 1: FORMAT(6I10)
\begin{tabular}{ll} 
Field 1 & - group number \\
Field 2 & - active constraint set no. for group \\
Field 3 & - active restraint set no. for group \\
Field 4 & - active load set no. for group \\
Field 5 & - active dof set no. for group \\
Field 6 & - number of entities in group
\end{tabular}

Record 2: FORMAT(20A2)
Field 1 - group name
Record \(3-N\) : FORMAT(8I10)
\begin{tabular}{ll} 
Field 1 & - entity type code \\
Field 2 & - entity tag \\
Field 3 & - entity type code \\
Field 4 & - entity tag \\
Field 5 & - entity type code \\
Field 6 & - entity tag \\
Field 7 & - entity type code \\
Field 8 & - entity tag
\end{tabular}

Repeat Record 3 for all entities as defined by Record 1, Field 6. Records 1 thru \(N\) are repeated for each group in the model.

The group number (Record 1, Field 1) is strictly a numeric counter, starting at one. In FEMATS, Fields 2-5 of Record 1 are not used, and should be set to zero. Record 1, Field 6 is self-explanatory.

Record 2, Field 1 is a 40 character name, describing the group. In IDEAS this name may have any number of spaces, etc. However, FEMATS expects certain naming conventions. As mentioned in Section 2.5 and Appendix \(A\), the group names must begin with a certain letter, and occur in a certain order, as follows: C, R, I, D, A, and O (for conductor, resistive card, impedance sheet, dielectric, outer boundary, and far-field integration surface, respectively).

Records \(3-N\) describe the entity type and identifying tag number. For FEMATS, the entity type code will always be 7-a finite element node. Type codes for other entities may be found in the I-DEAS Core Utilities manual.

Example:
\(-1\)
752
0
0
0
0
\begin{tabular}{|c|c|c|c|c|c|c|c|}
\hline 7 & 1 & 7 & 2 & 7 & 3 & 7 & 4 \\
\hline 7 & 8 & 7 & 9 & 7 & 10 & 7 & 11 \\
\hline 7 & 12 & 7 & 13 & 7 & 14 & 7 & 15 \\
\hline 7 & 64 & 7 & 65 & & & & \\
\hline 2 & 0 & 0 & 0 & 0 & 146 & & \\
\hline \multicolumn{8}{|l|}{A1} \\
\hline 7 & 5 & 7 & 6 & 7 & 7 & 7 & 27 \\
\hline 7 & 28 & 7 & 29 & 7 & 30 & 7 & 31 \\
\hline 7 & 32 & 7 & 33 & 7 & 34 & 7 & 35 \\
\hline \multicolumn{8}{|l|}{etc...} \\
\hline 7 & 264 & 7 & 265 & 7 & 266 & 7 & 267 \\
\hline 7 & 268 & 7 & 269 & 7 & 270 & 7 & 271 \\
\hline 7 & 272 & 7 & 273 & & & & \\
\hline 3 & 0 & 0 & 0 & 0 & \(14^{*}\) & & \\
\hline \multicolumn{8}{|l|}{01} \\
\hline 7 & 1 & 7 & 2 & 7 & 3 & 7 & 4 \\
\hline 7 & 8 & 7 & 9 & 7 & 10 & 7 & 11 \\
\hline 7 & 12 & 7 & 13 & 7 & 14 & 7 & 15 \\
\hline 7 & 64 & 7 & 65 & & & & \\
\hline \(-1\) & & & & & & & \\
\hline
\end{tabular}

In this example, there are three groups, numbered 1 through 3 , and named \(\mathrm{C} 1, \mathrm{~A} 1\), and O 1 , respectively. Groups C 1 and O 1 have 14 entities associated with them, while group A1 has 146 entities. All the entities in all the groups are entity type 7 -nodes.

\section*{Dataset 780: Elements}

Record 1: FORMAT(8I10)
Field 1 - element label
Field 2 - fe descriptor id
Field 3 - physical property table bin number
Field \(4 \quad\) - physical property table number
Field 5 - material property table bin number
Field \(6 \quad\) - material property table number
Field 7 - color
Field 8 - number of nodes on element

Record 2: FORMAT(8I10)
Fields 1-n - node labels defining element
Records 1 and 2 are repeated for each element in the model.
The element label (Record 1, Field 1) is strictly a numeric counter, starting at one. Record 1, Field 2 defines the element type. Although many
dement 1 ypes exist. FEDASS only uses one a solid linear tetrahedron element type 111. Record 1 . Fields 3 and 4 are not used by FEMAITS. and should be set to 1. The material properties (Record 1. Fields 5) and 6). however. are used by FEMATS to distinguish between the different materials in each mesh volume. Generally, Record 1. Field 5) is set to 1. and Record 1. Field 6 indicates the material property label discussed in Section 2.3 and Appendix A of the FEMATS User's Manual. Record 1. Field 7 indicates the element color, and is not used in FEMATS. Record 1 . Field 8 is selfexplanatory.

Record 2 contains enough entries, and thus, enough lines. to list all the nodes on a particular element. For FEMATS, since only solid linear tetrahedra are used, there will only be 4 nodes, and thus only one line per element.

Example:
\begin{tabular}{|c|c|c|c|c|c|c|c|}
\hline \multicolumn{8}{|l|}{-1} \\
\hline \multicolumn{8}{|l|}{780} \\
\hline 1 & 111 & 1 & 2 & 1 & 1 & 7 & 4 \\
\hline 9 & 22 & 11 & 2 & & & & \\
\hline 2 & 111 & 1 & 2 & 1 & 1 & 7 & 4 \\
\hline 22 & 293 & 92 & 9 & & & & \\
\hline 3 & 111 & 1 & 2 & 1 & 1 & 7 & 4 \\
\hline 22 & 11 & 293 & 9 & & & & \\
\hline \multicolumn{8}{|l|}{etc....} \\
\hline 18222 & 111 & 1 & 2 & 1 & 2 & 7 & 4 \\
\hline 3294 & 3249 & 1363 & 3250 & & & & \\
\hline 18223 & 111 & 1 & 2 & 1 & 2 & 7 & 4 \\
\hline 3291 & 1341 & 3249 & 1340 & & & & \\
\hline 18224 & 111 & 1 & 2 & 1 & 2 & 7 & 4 \\
\hline 3291 & 3249 & 1341 & 3294 & & & & \\
\hline -1 & & & & & & & \\
\hline
\end{tabular}

In this example, there are 18,224 elements, all solid linear tetrahedra. They all have the same material properties, and are thus all in the same medium. As would be expected, they all have 4 nodes, and their color is 7 (green).

\section*{Dataset 781: Nodes - Double precision}

Record 1: FORMAT(4I10)
Field 1 - node label
Field 2 - definition coordinate system number
Field 3 - displacement coordinate system number
Field \(4 \quad\) - color

Record 2: FORMAT(1P3D25.16)
Fields 1-3
- 3-dimensional coordinates of node in the definition system

Records 1 and 2 are repeated for each node in the model.
The node label (Record 1, Field 1) is strictly a numeric counter, starting at one. Record 1, Field 2 indicates the coordinate system used to define the node locations. While the three standard coordinate systems are availableCartesian, cylindrical, and spherical (numbers 0,1 , and 2, respectively), FEMATS only uses Cartesian. Hence, both Record 1, Field 2 and Record 1, Field 3 should be zero. Record 1, Field 4 indicates the node color, and is not used in FEMATS.

Fields \(1-3\) of Record 2 are the 3 -dimensional coordinates of the node locations, in double precision format. In general, these three values are expressed in terms of the appropriate coordinate variables, i.e. for spherical coordinates, the coordinate variables are \((r, \theta, \phi)\), while for cylindrical coordinates, the appropriate variables are ( \(r, \theta, z\) ). Since FEMATS only uses the Cartesian system, the appropriate variables are ( \(x, y, z\) ).

\section*{Example:}
\begin{tabular}{ccccc}
1 & 0 & 0 & 11 & \\
\(-1.1250000447034835 \mathrm{E}+00\) & \(0.0000000000000000 \mathrm{E}+00\) & \(1.4375000260770320 \mathrm{E}+00\) \\
2 & 0 & 0 & 11 & \\
\(0.000000000000000 \mathrm{E}+00\) & \(-1.1250000447034835 \mathrm{E}+00\) & \(1.4375000260770320 \mathrm{E}+00\) \\
3 & 0 & 0 & 11 & \\
\(0.000000000000000 \mathrm{E}+00\) & \(0.000000000000000 \mathrm{E}+00\) & \(1.4375000260770320 \mathrm{E}+00\)
\end{tabular}
```

etc....

```
\begin{tabular}{ccccc}
3718 & 0 & 0 & 11 & \\
\(-1.1962018850819641 \mathrm{E}-01\) & \(-7.3728312687791492 \mathrm{E}-02\) & \(9.1661646783763676 \mathrm{E}-02\) \\
3719 & 0 & 0 & 11 & \\
\(-5.5161825599575895 \mathrm{E}-02\) & \(-6.6190053659418503 \mathrm{E}-02\) & \(9.6638066869683866 \mathrm{E}-02\) \\
3720 & 0 & 0 & 11 & \\
\(-8.5961703548581673 \mathrm{E}-02\) & \(-1.1321300839107060 \mathrm{E}-01\) & \(5.2343589137973839 \mathrm{E}-02\)
\end{tabular}

In this example. there are \(3-20\) nodes. all defined in the (artesian coordinate sys tem. and their color is 11 (red).

NOTE: Although these datasets have been presented in numerical order by their number, it should be realized that dataset 781 (Nodes) must precede dataset 780 (Elements) in the universal file. as dataset 780 references information from dataset 781 . Also. since the groups depend on both the nodes and elements. dataset 752 (Groups) should appear after both dataset 780 and 781 .

Following is an example universal file generated in I-DEAS for use with FEMATS. Because I-DEAS requires other information in excess of that necessary for FEMATS, there are several datasets included in the following universal file which are not described above. As these datasets are not necessary for FEMATS, and are only necessary if the user is attempting to write a full conversion routine from some other mesh generation package to I-DEAS, or trying to import their mesh into I-DEAS, they will not be covered in this manual, and the user is referred to both the I-DEAS Core Utilities Manual and the I-DEAS PEARL Manual for more information.

Sample I-DEAS Universal File:
```

    -1
    151
    temp1
temp1
SDRC I-DEAS VI.i: Monitor
04-AUG-93 10:55:54 6 0
04-AUG-93 14:00:32
SDRC I-DEAS VI.i: FE_Modeling_\&_Analysis
04-AUG-93 14:01:59
-1
-1
164
5Modified SI (mm) 2
1.00000000000000000E+03 1.00000000000000000E +03 1.00000000000000000E E+00
2.73149999999999960E+02
-1
-1
800
1
WORKING_SET1
-1
-1
7 7 0
1

```

MAIN
-1
-1
771
\(\begin{array}{lll}1 & 1 & 1\end{array}\)
FE MODEL1
-1
-1
781
\begin{tabular}{ccccc}
1 & 0 & 0 & 11 & \\
\(1.5000000712461767 \mathrm{E}-01\) & \(-2.7105054312137611 \mathrm{E}-17\) & \(0.0000000000000000 \mathrm{E}+00\) \\
2 & 0 & 0 & 11 & \\
\(0.0000000000000000 \mathrm{E}+00\) & \(0.0000000000000000 \mathrm{E}+00\) & \(0.0000000000000000 \mathrm{E}+00\) \\
3 & 0 & 0 & 11 & \\
\(2.1175823681357506 \mathrm{E}-17\) & \(1.5000000712461767 \mathrm{E}-01\) & \(0.0000000000000000 \mathrm{E}+00\)
\end{tabular}
etc....
\begin{tabular}{|c|c|c|c|c|}
\hline \(3.7500877506659887 \mathrm{E}-01\) & \multicolumn{2}{|l|}{1.4697603711765345E-01} & \multicolumn{2}{|l|}{\multirow[t]{2}{*}{8.7404428380300838E-02}} \\
\hline \(451 \quad 0\) & 011 & 11 & & \\
\hline \(3.7094838851549648 \mathrm{E}-01\) & \multicolumn{2}{|l|}{\(6.9079955860908915 \mathrm{E}-02\)} & \multicolumn{2}{|l|}{8.3694518214300438E-02} \\
\hline 4520 & \multicolumn{2}{|l|}{011} & & \\
\hline 3.9089404906600184E-01 & \multicolumn{2}{|l|}{\(9.8862596006164716 \mathrm{E}-02\)} & \multicolumn{2}{|l|}{\(4.3313292570483312 \mathrm{E}-02\)} \\
\hline -1 & & & & \\
\hline -1 & & & & \\
\hline 780 & & & & \\
\hline \(1 \quad 111\) & 12 & 1 & 1 & 7 \\
\hline 9 22 & 112 & & & \\
\hline 2111 & 12 & 1 & 1 & 7 \\
\hline \(22 \quad 293\) & \(92 \quad 9\) & & & \\
\hline 3111 & 12 & 1 & 1 & 7 \\
\hline 2211 & 293 9 & & & \\
\hline
\end{tabular}
etc...



\section*{E Benchmark Test Case Manual}

Most of the benchmark geometries specified by the Electromagnetics Code Consortium (EMC(') have been run with FEMATS. These benchmark cases demonstrate the code's validity and allow the user to verify the correct operation of the code on his/her machine. The following test cases are included here:
1. EMCC Target \#4, Rectangular PEC Plate: \(\sigma=0^{\circ}\). cr-pol
2. EMCC Target \#4. Rectangular PEC Plate: \(\varphi=90^{\circ}\). w-pol
3. EMCC Target \#4, Rectangular PEC Plate: \(\phi=90^{\circ}\). \(h \mathrm{~h}\)-pol
4. EMCC Target \#6, Foam Cylinder, Co-Linear Wires
5. EMCC Target \#6, Foam Cylinder, Wires in Echelon
6. EMCC Target \#8, Glass Plate
7. \(1.0 \lambda \times 1.0 \lambda \times 1.5 \lambda\) Rectangular Inlet, Rectangular Mesh Termination, \(v v\)-pol
8. \(1.0 \lambda \times 1.0 \lambda \times 1.5 \lambda\) Rectangular Inlet, Rectangular Mesh Termination, \(h h\)-pol
9. \(1.0 \lambda \times 1.0 \lambda \times 1.5 \lambda\) Spherical Inlet, Rectangular Mesh Termination, \(v v\) pol
10. \(1.0 \lambda \times 1.0 \lambda \times 1.5 \lambda\) Spherical Inlet, Rectangular Mesh Termination, \(h h-\) pol
11. \(1.875 \lambda\) height \(\times 1.25 \lambda\) dia Circular Inlet, Cylindrical Mesh Termination, \(v v\)-pol
12. \(1.875 \lambda\) height \(\times 1.25 \lambda\) dia Circular Inlet, Cylindrical Mesh Termination, \(h h\)-pol

Plots of each case are included in order following this introduction.
The original universal file and the preprocessor input files, along with the file containing the plot data, are included in the appropriate subdirectory in the benchmark subdirectory ( \({ }^{\text {femats/bench) of the FEMATS installation }}\) tree, given at the bottom of each plot.

\title{
Rectangular PEC Plate Benchmark Target
}

\author{
\(3.5 \lambda \times 2.0 \lambda\) Plate, \(\phi=0^{\circ}\) \\ VV-Polarization
}


\section*{Backscatter Pattern of Metal Plate}

This file (rect_plate_p0_vv.ps) and its associated input, output, and runtime data in ~femats/bench/rect_plate.

\section*{Rectangular PEC Plate Benchmark Target}

\section*{\(3.5 \lambda \times 2.0 \lambda\) Plate, \(\phi=0^{\circ}\) HH-Polarization}


This file (rect_plate_p0_hh.ps) and its associated input, output, and runtime data in ~femats/bench/rect_plate.

\title{
Rectangular PEC Plate Benchmark Target
}

\section*{\(3.5 \lambda \times 2.0 \lambda\) Plate, \(\phi=90^{\circ}\) \\ HH-Polarization}


This file (rect_plate_p90_hh.ps) and its associated input, output, and runtime data in \(\sim\) femats/bench/rect_plate.

\title{
Foam Cylinder Benchmark Target, Co-Linear Wires
}


This file (foam_cyl_colinear.ps) and its associated input, output, and runtime data in \(\sim\) femats/bench/foam_cyl.

\title{
Foam Cylinder Benchmark Target, Wires in Echelon
}


Backscatter Pattern of Foam Cylinder
Cylinder Radius \(=1.0 \lambda\), Cylinder Height \(=3.5 \lambda\). Three Wires of Length \(0.5 \lambda\), Spaced \(0.5 \lambda\) Apart.

Cylindrical Mesh Termination Placed \(0.45 \lambda\) Away.
This file (foam_cyl_echelon.ps) and its associated input, output, and runtime data in ~femats/bench/foam_cyl.

\section*{Glass Plate Benchmark Target}


This file (glass_plate.ps) and its associated input, output, and runtime data in \(\sim\) femats/bench/glass_plate.

\title{
Rectangular Inlet Benchmark Target
}

VV-Polarization
Rectangular Mesh Termination Boundary



\section*{Backscatter Pattern of Rectangular Inlet}

Inlet Dim.: \(1.0 \lambda \times 1.0 \lambda \times 1.5 \lambda\)
This file (rect_inlet_vv_r.ps) and its associated input, output, and runtime data in \(\sim\) femats/bench/rect_inlet.

\title{
Rectangular Inlet Benchmark Target
}

\section*{HH-Polarization}

Rectangular Mesh Termination Boundary


Inlet Dim.: \(1.0 \lambda \times 1.0 \lambda \times 1.5 \lambda\)

This file (rect_inlet_hh_r.ps) and its associated input, output, and runtime data in \(\sim\) femats/bench/rect_inlet.

\title{
Rectangular Inlet Benchmark Target
}

VV-Polarization
Spherical Mesh Termination Boundary


\section*{Backscatter Pattern of Rectangular Inlet}

Inlet Dim.: \(1.0 \lambda \times 1.0 \lambda \times 1.5 \lambda\)
This file (rect_inlet_vv_s.ps) and its associated input, output, and runtime data in ~femats/bench/rect_inlet.

\title{
Rectangular Inlet Benchmark Target HH-Polarization \\ Spherical Mesh Termination Boundary
}



\section*{Backscatter Pattern of Rectangular Inlet}

Inlet Dim.: \(1.0 \lambda \times 1.0 \lambda \times 1.5 \lambda\)

This file (rect_inlet_hh_s.ps) and its associated input, output, and runtime data in \(\sim\) femats/bench/rect_inlet.

\title{
Circular Inlet Benchmark Target
}

\section*{VV-Polarization}

Cylindrical Mesh Termination Boundary



\section*{Backscatter Pattern of Circular Inlet}

Inlet Dim.: \(\boldsymbol{h}=1.875 \lambda\), dia \(=1.25 \lambda\)
This file (circ_inlet_vv_c.ps) and its associated input, output, and runtime data in \(\sim\) femats/bench/circ_inlet.

\title{
Circular Inlet Benchmark Target
}

\section*{HH-Polarization}

Cylindrical Mesh Termination Boundary


This file (circ_inlet_hh_c.ps) and its associated input, output, and runtime data in \(\sim\) femats/bench/circ_inlet.

\section*{F Installation}

FEMATS is designed to run on multiple computing plat forms to best utilize various machine capabilities. The preprocessing programs can be readily run on a UNIX workstation, while the main processing might be done on a different machine, e.g. a CRAY' supercomputer, if the memory and speed requirements demand so for a given geometry. Hence. there are two sets of source code included on the tape, one for the preprocessor and one for the main processor, along with two installation procedures. Also included is the small test case used to generate the example run in Appendix C. starting with the I-DEAS universal file small_plate.unv and ending with the FEMATS output files.

\section*{Installation instructions}
1. Place the distribution tape in the tape drive. If the drive is not the default system drive, you will need to find out what device it is.
2. Retrieve the appropriate files from the tape. For example, if you wanted to install FEMATS in your home directory, you would say (assuming the tape drive being used is the system default tape drive):
```

cd
tar xv README femats.bench.tar.Z femats.doc.tar.Z
femats.{arch}.tar femats.preproc.tar

```
where \(\{\operatorname{arch}\}\) is one of the supported architectures: cray, hp, ksr, or paragon.
This places the named files in your home directory.
There are eight files on the tape:
```

README
femats.bench.tar.Z
femats.cray.tar
femats.doc.tar.Z
femats.hp.tar
femats.ksr.tar
femats.paragon.tar
femats.preproc.tar

```

README is a short description of the files on the tape.
femats .bench.tar. \(Z\) is a compressed tar file containing the benchmark runs mentioned in Appendix E of this manual.
femats.cray.tar is a tar file containing the source code and test files for the CRAY version of FEMATS.
femats.doc.tar. \(Z\) is a compressed tar file containing the documentation for all of FEMATS (ATEXand .ps formats).
femats.hp.tar is a tar file containing the source code and test files for the HP workstation version of FEMATS.
femats.ksr.tar is a tar file containing the source code and test files for the KSR version of FEMATS.
femats.paragon.tar is a tar file containing the source code and test files for the Intel Paragon version of FEMATS.
femats.preproc.tar is a tar file containing the source code and test files for the preprocessing portion of FEMATS.
3. If necessary, ftp the supercomputer portion of FEMATS to the supercomputer, putting it in the appropriate directory.
4. If femats.preproc.tar is not in the directory where you want to install FEMATS, then put it there. Note: When the files are 'untar'd, a directory named femats will be created, and the appropriate files and subdirectories placed in it. (See Appendix G for a full file listing.)
5. Uncompress femats .preproc.tar.Z: type
uncompress femats.preproc.tar. Z
6. Untar femats preproc.tar: type
tar xvf femats.preproc.tar
7. Change directories to femats/src/preproc, and type make install. This will compile the preprocessors and automatically place them in the femats/bin directory. If you wish, you may then type make clean to remove the .o files.
8. Follow the same steps for the chosen workstation or supercomputer source code files, starting with step 4 , and changing femats.preproc to femats. \(\{\operatorname{arch}\}\) in all cases.
9. For both the workstation and the supercomputer, FEMATS assumes that it will be run from the user's current working directory. To accomodate this, the femats/bin directory must be included in the search path. To do this, modify the appropriate startup file (the following assumes the C Shell, i.e. the .cshrc file):
```

set path=(\$path femats_dir/bin)

```
where femats_dir is the full path of the femats directory. For example,
```

set path=(\$path /l/usr/femats/bin)

```

Then type source eshre to ensure that the new path take effect. If any difficulties are encountered, ask your system/site administrator.
10. If any problems occur. don't hesitate to look in the scripts - they are quite simple, and there may be some machine or \(O S\) version dependencies that were missed...

\section*{G Directory Listing of Full Distribution}
```

femats:
total 9
drwxrwxrwx }7\mathrm{ mwnurnbe

| 512 | Oct | 5 | $10: 36$ | . |
| ---: | :--- | :--- | :--- | :--- |
| 512 | Oct | 5 | $15: 24$ | $\ldots$ |
| 1308 | Oct | 3 | $16: 10$ | README |
| 512 | Oct | 5 | $11: 56$ | bench |
| 512 | Oct | 5 | $11: 07$ bin |  |
| 1024 | Oct | 5 | $10: 46$ | doc |
| 512 | Oct | 5 | $10: 41$ | src |
| 512 | Oct | 5 | $09: 10$ | test |

```
femats/bench:
total 7
\(\begin{array}{lllllll}\text { drwxrwxrwx } & 7 \text { mwnurnbe } & 512 & \text { Oct } & 5 & 11: 56 & . \\ \text { drwxrwxrwx } & 7 & \text { mwnurnbe } & 512 & \text { Oct } & 5 & 10: 36\end{array}\)
drwxrwxrwx 4 mwnurnbe 512 Oct 5 11:46 circ_inlet
drwxrwxrwx 4 mwnurnbe 512 Oct 5 11:47 foam_cyl
drwxrwxrwx 2 mwnurnbe 512 Oct \(511: 51\) glass_plate
drwxrwxrwx 4 mwnurnbe 512 Oct 5 11:52 rect_inlet
drwxrwxrwx 4 mwnurnbe 512 Oct \(511: 57\) rect_plate
\begin{tabular}{|c|c|c|}
\hline drwxrwxrwx 4 mwnurnbe & 512 Oct & 5 11:46 \\
\hline drwxrwxrwx 7 mwnurnbe & 512 Oct & \(511: 56\) \\
\hline -rw-r--r-- 1 mwnurnbe & 191099 May & 5 12:37 circ_inlet_hh_c.ps \\
\hline -rw-r--r-- 1 mwnurnbe & 180165 May & 5 12:32 circ_inlet_vv_c.ps \\
\hline drwxrwxrwx 2 mwnurnbe & 512 Oct & 5 11:46 cyl_term \\
\hline drwxrwxrwx 2 mwnurnbe & 512 Oct & 5 11:46 rect_term \\
\hline \multicolumn{3}{|l|}{```
femats/bench/circ_inlet/cyl_term:
total 12285
```} \\
\hline drwxrwxrwx 2 mwnurnbe & 512 Oct & 5 11:46 \\
\hline drwxrwxrwx 4 mwnurnbe & 512 Oct & 5 11:46 \\
\hline -rw-r--r-- 1 mwnurnbe & 660392 May & 8 21:29 cntr \\
\hline -rw-r--r-- 1 mwnurnbe & 2518518 May & 8 21:29 cyl_inlt_c.unv \\
\hline -rw-r--r-- 1 mwnurnbe & 2019142 May & 8 21:29 edgy \\
\hline -rw-r--r-- 1 mwnurnbe & 15 May & 8 21:29 eg \\
\hline -rw-r--r-- 1 mwnurnbe & 5603435 May & 8 21:29 eglob \\
\hline -rw-r--r-- 1 mwnurnbe & 697562 May & 8 21:29 enoddy \\
\hline -rw-r--r-- 1 mwnurnbe & 993240 May & 8 21:29 esurfed \\
\hline -rw-r--r-- 1 mwnurnbe & 166 May & 8 21:29 ip_femats \\
\hline
\end{tabular}
```

-rw-r--r-- 1 mwnurnbe 64 May 8 21:29 ip_mesh
femats/bench/circ_inlet/rect_term:
total }1594

| drwxrwxrwx | 2 mwnurnbe | 512 Oct | 5 | $11: 46$ | . |
| :--- | :--- | ---: | :--- | :--- | :--- |
| drwxrwxrwx | 4 mwnurnbe | 512 Oct | 5 | $11: 46$ | $\ldots$ |
| -rw-r--r-- | 1 mwnurnbe | 849216 May | 8 | $21: 29$ cntr |  |
| -rw-r--r-- | 1 mwnurnbe | 3231558 May | 8 | $21: 29$ cyl_inlet_b.unv |  |
| -rw-r--r-- | 1 mwnurnbe | 2637600 May | 8 | $21: 29$ edgy |  |
| -rw-r--r-- | 1 mwnurnbe | 15 May | 8 | $21: 29$ eg |  |
| -rw-r--r-- | 1 mwnurnbe | 7372490 May | 8 | $21: 29$ eglob |  |
| -rw-r--r-- | 1 mwnurnbe | 880955 May | 8 | $21: 29$ enoddy |  |
| -rw-r--r-- | 1 mwnurnbe | 1294056 May | 8 | $21: 29$ esurfed |  |
| -rw-r--r-- | 1 mwnurnbe | 242 May | 8 | $21: 29$ ip_femats |  |
| -rw-r--r-- | 1 mwnurnbe | 65 May | 8 | $21: 29$ ip_mesh |  |

femats/bench/foam_cyl:
total 412

| drwxrwxrwx | 4 mwnurnbe | 512 | Oct | 5 | $11: 47$ | . |
| :--- | :--- | ---: | :--- | :--- | :--- | :--- |
| drwxrwxrwx | 7 mwnurnbe | 512 | Oct | 5 | $11: 56$ | $\ldots$ |
| drwxrwxrwx | 2 mwnurnbe | 512 Oct | 5 | $11: 47$ | colinear |  |
| drwxrwxrwx | 2 mwnurnbe | 512 Oct | 5 | $11: 51$ echelon |  |  |
| -rw-r--r-- | 1 mwnurnbe | 204989 May | 4 | $19: 05$ foam_cyl_colinear.ps |  |  |
| -rw-r--r-- | 1 mwnurnbe | 185065 May | 4 | $19: 00$ foam_cyl_echelon.ps |  |  |

femats/bench/foam_cyl/colinear:
total 33069

```

```

femats/bench/foam_cyl/echelon:
total 33197
drwxrwxrwx 2 mwnurnbe 512 Oct 5 11:51.
drwxrwxrwx 4 mwnurnbe 512 Oct 5 11:47 ..
-rw-r--r-- 1 mwnurnbe 1744840 May 8 21:24 cntr
-rw-r--r-- 1 mwnurnbe 5556858 May 8 21:24 edgy

```
\begin{tabular}{|c|c|c|c|c|c|}
\hline & mwnurnbe & 15 May & & 21:24 & \\
\hline rw-r--r & mwnurnbe & 15855216 May & & 21:24 & eglob \\
\hline W-r--r & nurnbe & 1769881 May & & 21:24 & enoddy \\
\hline w-r--r & wnurnbe & 2338557 May & & 21:24 & fed \\
\hline -r-r & mwnurnbe & 6647785 May & & 21:24 & om_off \\
\hline & mwnurnbe & 163 May & & 21:24 & ip_femats \\
\hline & mwnurn & 68 May & & 21: & p_m \\
\hline
\end{tabular}
femats/bench/glass_plate:
total 11741

femats/bench/rect_inlet:
total 676
\begin{tabular}{llrllll} 
drwxrwxrwx & 4 mwnurnbe & 512 Oct & 5 & \(11: 52\) &. \\
drwxrwxrwx & 7 mwnurnbe & 512 & Oct & 5 & \(11: 56\) & \(\ldots\) \\
-rw-r--r-- & 1 mwnurnbe & 157459 May & 5 & \(11: 21\) & rect_inlet_hh_r.ps \\
-rw-r--r-- & 1 mwnurnbe & 157728 May & 5 & \(11: 18\) rect_inlet_hh_s.ps \\
-rw-r--r-- & 1 mwnurnbe & 157892 May & 5 & \(11: 20\) rect_inlet_vv_r.ps \\
-rw-r--r-- & 1 mwnurnbe & 161102 May & 5 & \(11: 15\) rect_inlet_vv_s.ps \\
drwxrwxrwx & 2 mwnurnbe & 512 Oct & 5 & \(11: 52\) rect_term \\
drwxrwxrwx & 2 mwnurnbe & 512 Oct & 5 & \(11: 52\) sphere_term
\end{tabular}
femats/bench/rect_inlet/rect_term:
total 11661
\begin{tabular}{llrlll} 
drwxrwxrwx & 2 mwnurnbe & 512 Oct & 5 & \(11: 52\) &. \\
drwxrwxrwx & 4 mwnurnbe & 512 Oct & 5 & \(11: 52\) & \(\ldots\) \\
-rw-r--r-- & 1 mwnurnbe & 625116 May & 8 & \(21: 33\) & cntr \\
-rw-r--r-- & 1 mwnurnbe & 1907209 May & 8 & \(21: 33\) edgy \\
-rw-r--r-- & 1 mwnurnbe & 15 May & 8 & \(21: 33\) eg \\
-rw-r--r-- & 1 mwnurnbe & 5269840 May & 8 & \(21: 33\) eglob \\
-rw-r--r-- & 1 mwnurnbe & 642125 May & 8 & \(21: 33\) enoddy \\
-rw-r--r-- & 1 mwnurnbe & 1038069 May & 8 & \(21: 33\) esurfed \\
-rw-r--r-- & 1 mwnurnbe & 247 May & 8 & \(21: 33\) ip_femats
\end{tabular}

\begin{tabular}{ll}
-rwxr-xr-x & 1 mwnurnbe \\
-rwxr-xr-x & 1 mwnurnbe \\
-rwxr-xr-x & 1 mwnurnbe \\
-rwxr-xr-x & 1 mwnurnbe \\
-rwxr-xr-x & 1 mwnurnbe \\
-rwxr-xr-x & 1 mwnurnbe \\
-rwxr-xr-x & 1 mwnurnbe
\end{tabular}
\begin{tabular}{rlll}
1813873 & Oct & 5 & \(11: 53\) edgy \\
15 & Oct & 5 & \(11: 53\) eg \\
4921745 & Oct & 5 & \(11: 53\) eglob \\
628853 Oct & 5 & \(11: 53\) enoddy \\
976573 Oct & 5 & \(11: 53\) esurfed \\
324 Oct & 5 & \(11: 53\) ip_femats \\
63 Dct & 5 & \(11: 53\) ip_mesh
\end{tabular}

\section*{femats/bin:}
total 27
\begin{tabular}{ll} 
drwxrwxrwx & 2 mwnurnbe \\
drwxrwxrwx & 7 mwnurnbe \\
-rwxr-xr-x & 1 mwnurnbe \\
-rwxr-xr-x & 1 mwnurnbe \\
-rwxr-xr-x & 1 mwnurnbe \\
-rwxr-xr-x & 1 mwnurnbe
\end{tabular}
\(\left.\begin{array}{rlll}512 & \text { Oct } & 5 & 11: 07 \\ 512 & \text { Oct } & 5 & 10: 36\end{array}\right]\).
```

femats/doc:
total }501
drwxrwxrwx 2 mwnurnbe
drwxrwxrwx }7\mathrm{ mwnurnbe
-rw-r--r-- 1 mwnurnbe
-rw-r--r-- 1 mwnurnbe
-rw-r--r-- 1 mwnurnbe
-rw-r--r-- 1 mwnurnbe
-rw-r--r-- 1 mwnurnbe
-rw-r--r-- }1\mathrm{ mwnurnbe
-rw-r--r-- }1\mathrm{ mwnurnbe
-rw-r--r-- 1 mwnurnbe
-rw-r--r-- }1\mathrm{ mwnurnbe
-rw-r--r-- 1 mwnurnbe
-rw-r--r-- 1 mwnurnbe
-rw-r--r-- }1\mathrm{ mwnurnbe
-rw-r--r-- }1\mathrm{ mwnurnbe
-rw-r--r-- 1 mwnurnbe
-rw-r--r-- }1\mathrm{ mwnurnbe
-rw-r--r-- 1 mwnurnbe
-rw-r--r-- 1 mwnurnbe
-rw-r--r-- 1 mwnurnbe
-rw-r--r-- }1\mathrm{ mwnurnbe
-rw-r--r-- }1\mathrm{ mwnurnbe
-rw-r--r-- }1\mathrm{ mwnurnbe
-rw-r--r-- 1 mwnurnbe
-rw-r--r-- 1 mwnurnbe
1024 Oct 5 10:46.
512 Oct 5 10:36 ..
191099 Sep 26 14:51 circ_inlet_hh_c.ps
180165 Sep 26 14:51 circ_inlet_vv_c.ps
3695 Sep 26 14:51 f.ps
7584 Sep 26 14:51 flow.ps
204989 Sep 26 14:51 foam_cyl_colinear.ps
185065 Sep 26 14:51 foam_cyl_echelon.ps
217865 Sep 26 14:51 glass_plate.ps
1129 Sep 26 14:51 macros.tex
2921 Sep 26 14:51 manual.aux
80888 Sep 26 14:51 manual.dvi
29460 Sep 26 14:51 manual.log
2508214 Sep 26 14:51 manual.ps
32231 Sep 26 14:51 manual.tex
1604 Sep 26 14:51 manual.toc
32562 Sep 26 14:51 manual1.tex
157459 Sep 26 14:51 rect_inlet_hh_r.ps
157728 Sep 26 14:51 rect_inlet_hh_s.ps
157892 Sep 26 14:51 rect_inlet_vv_r.ps
161102 Sep 26 14:51 rect_inlet_vv_s.ps
222419 Sep 26 14:51 rect_plate_p0_hh.ps
218655 Sep 26 14:51 rect_plate_p0_vv.ps
197611 Sep 26 14:51 rect_plate_p90_hh.ps
24 Sep 26 14:51 sngl_side.pro

```

\[
\begin{array}{ll}
-r w-r--r-- & 1 \text { mwnurnbe } \\
-r w-r-r-- & 1 \text { mwnurnbe } \\
-r w-r-r-- & 1 \text { mwnurnbe } \\
-r w-r-r-- & 1 \text { mwnurnbe } \\
-r w-r-r-- & 1 \text { mwnurnbe } \\
-r w-r--r-- & 1 \text { mwnurnbe } \\
-r w-r-r-- & 1 \text { mwnurnbe } \\
-r w-r--r-- & 1 \text { mwnurnbe } \\
-r w-r-r-- & 1 \text { mwnurnbe } \\
-r w-r-r-- & 1 \text { mwnurnbe } \\
-r w-r--r-- & 1 \text { mwnurnbe } \\
-r w-r-r-- & 1 \text { mwnurnbe } \\
-r w-r-r-- & 1 \text { mwnurnbe }
\end{array}
\]
```

2182 Sep 19 14:31 incci.f
2108 Sep 19 14:32 incd1.f
2247 Sep 19 14:32 inci.f
2311 Sep 19 14:32 incr.f
1547 Sep 19 14:32 norm2d.f
2458 Sep 19 14:32 norma.f
1359 Sep 19 14:32 ops.f
560 Sep 19 14:32 ord.f
6 2 5 ~ S e p ~ 1 9 ~ 1 4 : 3 2 ~ s o r t . f ~
354 Sep 19 14:32 string.f
1534 Sep 19 14:32 surfint1.f
3371 Sep 19 14:32 value.f
439 Sep 19 14:32 volume.f

```
\begin{tabular}{|c|c|}
\hline 512 Oct & 5 10:39 \\
\hline 512 Oct & \(510: 41\) \\
\hline 1748 Oct & 4 15:02 Makefile \\
\hline 512 Oct & 4 13:53 asc2bin \\
\hline 11026 Oct & \(314: 37 \mathrm{bd1.F}\) \\
\hline 8441 Oct & 3 14:37 bicg.F \\
\hline 1076 Oct & 3 14:38 diag.F \\
\hline 14590 Oct & 3 14:35 fem.F \\
\hline 98 Oct & 3 15:01 fem_data.h \\
\hline 6665 Oct & \(314: 37 \mathrm{k} 2 . \mathrm{F}\) \\
\hline 1658 Oct & \(314: 38\) mult.F \\
\hline 512 Oct & \(413: 53\) sub \\
\hline 4163 Oct & \(314: 38 \mathrm{xc} . \mathrm{F}\) \\
\hline
\end{tabular}
    512 Oct 4 13:53.
    512 Oct 5 10:39..
1563 Oct 3 15:10 fr.f
\begin{tabular}{rllll}
512 & Oct & 4 & \(13: 53\) &. \\
512 & Oct & 5 & \(10: 39\) & \(\ldots\) \\
2298 & Oct & 3 & \(14: 39\) & basis1.F \\
4572 & Oct & 3 & \(14: 41\) & bi2mono.F \\
820 & Oct & 3 & \(14: 39\) & calc \(1 . F\) \\
1507 & Oct & 3 & \(14: 39\) & comput. \(F\) \\
968 & Oct & 3 & \(14: 39\) & crux.F
\end{tabular}
```

-rw-r--r-- 1 mwnurnbe
1351 Oct 3 14:39 cruxd1.F
-rw-r--r-- 1 mwnurnbe
908 Oct 3 14:40 f11.F
-rW-r--r-- 1 mwnurnbe
13589 Oct 3 14:41 fcmb.F
-rw-r--r-- 1 mwnurnbe
-rw-r--r-- }1\mathrm{ mwnurnbe
-rw-r--r-- 1 mwnurnbe
-rw-r--r-- }1\mathrm{ mwnurnbe
-rw-r--r-- }1\mathrm{ mwnurnbe
-rw-r--r-- 1 mwnurnbe
-rw-r--r-- }1\mathrm{ mwnurnbe
-rw-r--r-- }1\mathrm{ mwnurnbe
-rw-r--r-- 1 mwnurnbe
-rw-r--r-- }1\mathrm{ mwnurnbe
-rw-r--r-- }1\mathrm{ mwnurnbe
-rw-r--r-- }1\mathrm{ mwnurnbe
-rw-r--r-- 1 mwnurnbe
-rw-r--r-- }1\mathrm{ mwnurnbe
-rw-r--r-- 1 mwnurnbe

```

```

femats/src/paragon:
total }
drwxrwxrwx 5 mwnurnbe
drwxrwxrwx 6 mwnurnbe
-rw-r--r-- }1\mathrm{ mwnurnbe
drwxrwxrwx 2 mwnurnbe
-rw-r--r-- 1 mwnurnbe
drwxrwxrwx 2 mwnurnbe
drwxrwxrwx 2 mwnurnbe

| 512 | Oct | 5 | $10: 40$ | . |
| ---: | :--- | :--- | :--- | :--- |
| 512 | Oct | 5 | $10: 41$ | $\ldots$ |
| 2106 | Oct | 5 | $10: 29$ | Makefile |
| 512 | Oct | 4 | $20: 45$ | asc2bin |
| 462 | Oct | 4 | $16: 02$ | fem_data.h |
| 512 | Oct | 4 | $16: 02$ | intel |
| 512 | Oct | 4 | $16: 02$ | intel-src |

```
```

femats/src/paragon/asc2bin:
total }
drwxrwxrwx 2 mwnurnbe 512 0ct 4 20:45.
drwxrwxrwx 5 mwnurnbe 512 Oct 5 10:40..
-rw-r----- 1 mwnurnbe 462 Sep 26 11:10 fem_data.h
-rw-r----- 1 mwnurnbe 3709 Sep 26 11:10 fr.f

```
```

femats/src/paragon/intel:
total }7
drwxrwxrwx 2 mwnurnbe
drwxrwxrwx }5\mathrm{ mwnurnbe
-rw-r--r-- 1 mwnurnbe
10796 Sep 26 11:09 bd1.f
4 2 0 2 ~ S e p ~ 2 6 ~ 1 1 : 0 9 ~ b i c g . f ~
592 Sep 26 11:09 broadcast_scalar.f
735 Sep 26 11:09 collect_vector.f
939 Sep 26 11:09 diag.f

```
\begin{tabular}{|c|c|}
\hline r--r-- 1 mwnurnbe & 4770 Sep 26 11:09 distribute_matrix.f \\
\hline \(\mathrm{w}-\mathrm{r}-\mathrm{r}-\mathrm{-} 1\) mwnurnbe & 1126 Sep 26 11:09 distribute_vector.f \\
\hline w-r--r-- 1 mwnurnbe & 15595 Sep 26 11:09 fem.f \\
\hline -rw-r--r-- 1 mwnurnbe & 1765 Sep 26 11:09 gather_data.f \\
\hline w-r--r-- 1 mwnurnbe & 6611 Sep 26 11:09 k2.f \\
\hline w-r--r-- 1 mwnurnbe & 3614 Sep 26 11:09 make_fetch_send_list. \\
\hline \(\mathrm{w}-\mathrm{r}-\mathrm{r}-\mathrm{-} 1\) mwnurnbe & 1090 Sep 26 11:10 mult.f \\
\hline rw-r--r-- 1 mwnurnbe & 4944 Sep 26 11:10 support.f \\
\hline -r--r-- 1 mwnurnbe & 107 Sep 26 11:10 user_seconds.f \\
\hline 1 mwnurnbe & 4272 Sep 26 11:10 xc.f \\
\hline
\end{tabular}

femats/src/preproc:
total 60
\begin{tabular}{lllllll} 
drwxrwxrwx & 2 mwnurnbe & 512 & Oct & 4 & \(20: 49\) &. \\
drwxrwxrwx & 6 mwnurnbe & 512 & Oct & 5 & \(10: 41\) & . \\
-rw-r--r-- & 1 & mwnurnbe & 682 & Oct & 4 & \(14: 48\) \\
-rakefile \\
-rw-r--r-- & 1 mwnurnbe & 19856 & Oct & 3 & \(13: 46\) & c2p.f \\
-rw-r--r-- & 1 mwnurnbe & 22608 & Oct & 3 & \(13: 39\) & c2p_2d.f
\end{tabular}
\(\begin{array}{ll}-r w-r--r-- & 1 \text { mwnurnbe } \\ -r w-r--r-- & 1 \text { mwnurnbe } \\ -r w-r--r-- & 1 \text { mwnurnbe }\end{array}\)
femats/test:
total 4
\(\begin{array}{ll}\text { drwxrwxrwx } & 4 \text { mwnurnbe } \\ \text { drwxrwxrwx } & 7 \text { mwnurnbe } \\ \text { drwxrwxrwx } & 2 \text { mwnurnbe } \\ \text { drwxrwxrwx } & 2 \text { mwnurnbe }\end{array}\)

\section*{femats/test/preproc:}
total 983
\(\begin{array}{ll}\text { drwxrwxrwx } & 2 \text { mwnurnbe } \\ \text { drwxrwxrwx } & 4 \text { mwnurnbe } \\ -r w-r--r-- & 1 \text { mwnurnbe } \\ -r w-r--r-- & 1 \text { mwnurnbe } \\ -r w-r--r-- & 1 \text { mwnurnbe } \\ -r w-r--r-- & 1 \text { mwnurnbe } \\ -r w-r--r-- & 1 \text { mwnurnbe } \\ -r w-r-r-- & 1 \text { mwnurnbe } \\ -r w-r--r-- & 1 \text { mwnurnbe } \\ -r w-r--r-- & 1 \text { mwnurnbe } \\ -r w-r--r- & 1 \text { mwnurnbe } \\ -r w-r--r-- & 1 \text { mwnurnbe } \\ -r w-r--r-- & 1 \text { mwnurnbe } \\ -r w-r--r-- & 1 \text { mwnurnbe }\end{array}\)
femats/test/supercomp: total 19649
\begin{tabular}{|c|c|}
\hline drwxrwxrwx & \[
2
\] \\
\hline & \\
\hline -rw-r--r-- & \\
\hline -rw-r--r-- & 1 mwnurnbe \\
\hline -rw-r----- & 1 mwnurnb \\
\hline -rw-r--r-- & 1 mwnurnbe \\
\hline W-r & 1 mwnur \\
\hline -rw-r----- & nu \\
\hline -rw-r----- & 1 mwnu \\
\hline -rw-r----- & 1 mwnur \\
\hline -rw-r----- & 1 mwnurn \\
\hline w-r----- & 1 mwnu \\
\hline rw-r & 1 mwnu \\
\hline & 1 mwn \\
\hline & \\
\hline
\end{tabular}
```

3702 Oct 3 13:39 count.f
164 May 8 21:45 parmvl
8956 Oct 4 14:43 u2c.f

```
\begin{tabular}{rllll}
512 & Oct & 5 & \(09: 10\) & \(\ldots\) \\
512 & Oct & 5 & \(10: 36\) & \(\ldots\) \\
512 & Oct & 5 & \(15: 21\) & preproc \\
1024 & Oct & 5 & \(15: 21\) & supercomp
\end{tabular}
    512 Oct 5 15:21.
    512 Oct 5 09:10..
    37756 Oct 4 19:57 small_plate.cntr
195800 Oct \(419: 57\) small_plate.cnv
            308 Oct \(419: 57\) small_plate.data
            93477 Oct \(419: 57\) small_plate.edgy
            12 Oct 4 19:57 small_plate.eg
238485 Oct 4 19:57 small_plate.eglob
    46232 Oct 4 19:57 small_plate.enoddy
    50541 Dct 4 19:57 small_plate.esurfed
        4481 Oct \(419: 57\) small_plate.grp
            251 Oct \(419: 57\) small_plate.otpt
286783 Oct \(419: 57\) small_plate.unv
        3903 Oct \(419: 57\) transcript.preproc


\section*{H References}
1. A. Chatterjee. J.M. Jin and J.L. Volakis. "Application of edge-hased finite elements and ABCs to 3-1) scattering." IEEF Trams. Ant nuas Propagat.. vol. 41. pp. 221-26. February 1993.
2. D.R. Kincaid and T.C. Oppe, "ITPACK on supercomputers." Vumerical Methods, Lecture Notes in Mathematics, vol. 1005. pp. 151 61. Springer, Berlin. \(198^{2}\).```

