

NASA/CR—2014–218474



Real-time Kennedy Space Center and Cape Canaveral Air Force Station High-resolution Model Implementation and Verification

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January 2015

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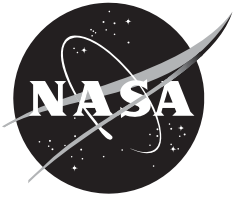
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January 2015

Acknowledgments

The authors would like to thank Mr. Kevin McGrath and Dr. Geoffrey Stano of the Short-term Prediction Research and Transition Center and Mr. Erik Magnuson of ENSCO, Inc. for lending their time and expertise with the Advanced Weather Interactive Processing System II in order to get the real-time model output available in AWIPS II. Dr. Bill Bauman and Ms. Winnie Crawford also provided valuable feedback and assistance with completing this task.

Available from:

NASA Center for AeroSpace Information
7115 Standard Drive
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Executive Summary

Customer: NASA's Launch Services Program (LSP), Ground Systems Development and Operations (GSDO), and Space Launch System (SLS) programs

NASA's LSP, GSDO, SLS and other programs at Kennedy Space Center (KSC) and Cape Canaveral Air Force Station (CCAFS) use the daily and weekly weather forecasts issued by the 45th Weather Squadron (45 WS) as decision tools for their day-to-day and launch operations on the Eastern Range (ER). For example, to determine if they need to limit activities such as vehicle transport to the launch pad, protect people, structures or exposed launch vehicles given a threat of severe weather, or reschedule other critical operations. The 45 WS uses numerical weather prediction models as a guide for these weather forecasts, particularly the Air Force Weather Agency (AFWA) 1.67 km Weather Research and Forecasting (WRF) model.

Considering the 45 WS forecasters' and Launch Weather Officers' (LWO) extensive use of the AFWA model, the 45 WS proposed a task at the September 2013 Applied Meteorology Unit (AMU) Tasking Meeting requesting the AMU verify this model. Due to the lack of archived model data available from AFWA, verification is not yet possible. Instead, the AMU proposed to implement and verify the performance of an ER version of the AMU high-resolution WRF Environmental Modeling System (EMS) model (Watson 2013) in real-time. The tasking group agreed to this proposal; therefore the AMU implemented the WRF-EMS model on the second of two NASA AMU modeling clusters.

The model was set up with a triple-nested grid configuration over KSC/CCAFS based on previous AMU work (Watson 2013). The outer domain (D01) has 12-km grid spacing, the middle domain (D02) has 4-km grid spacing, and the inner domain (D03) has 1.33-km grid spacing. The model runs a 12-hr forecast every hour, D01 and D02 domain outputs are available once an hour and D03 is every 15 minutes during the forecast period.

The AMU assessed the WRF-EMS 1.33-km domain model performance for the 2014 warm season (May–September). Verification statistics were computed using the Model Evaluation Tools, which compared the model forecasts to observations. The observational datasets included Meteorological Assimilation Data Ingest System surface observations and Stage IV gridded precipitation data from the National Centers for Environmental Prediction. The mean error values were close to 0 and the root mean square error values were less than 1.8 for mean sea-level pressure (mb), temperature (K), dewpoint temperature (K), and wind speed (ms^{-1}), all very small differences between the forecast and observations considering the normal magnitudes of the parameters. The precipitation forecast verification results showed consistent under-forecasting of the precipitation object size. This could be an artifact of calculating the statistics for each hour rather than for the entire 12-hour period. The AMU will continue to generate verification statistics for the 1.33-km WRF-EMS domain as data become available in future cool and warm seasons. More data will produce more robust statistics and reveal a more accurate assessment of model performance.

In addition to verifying the model's performance, the AMU also made the output available in the Advanced Weather Interactive Processing System II (AWIPS II). This allows the 45 WS and AMU staff to customize the model output display on the AMU and Range Weather Operations AWIPS II client computers and conduct real-time subjective analyses. In the future, the AMU will implement an updated version of the WRF-EMS model that incorporates local data assimilation. This model will also run in real-time and be made available in AWIPS II.

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1 Introduction

NASA's Launch Services Program, Ground Systems Development and Operations, Space Launch System and other programs at Kennedy Space Center (KSC) and Cape Canaveral Air Force Station (CCAFS) use the daily and weekly weather forecasts issued by the 45th Weather Squadron (45 WS) as decision tools for their day-to-day and launch operations on the Eastern Range (ER). Examples include determining if they need to limit activities such as vehicle transport to the launch pad, protect people, structures or exposed launch vehicles given a threat of severe weather, or reschedule other critical operations. The 45 WS uses numerical weather prediction models as a guide for these weather forecasts, particularly the Air Force Weather Agency (AFWA) 1.67 km Weather Research and Forecasting (WRF) model.

Considering the 45 WS forecasters' and Launch Weather Officers' (LWO) extensive use of the AFWA model, the 45 WS proposed a task at the September 2013 Applied Meteorology Unit (AMU) Tasking Meeting requesting the AMU verify this model. Due to the lack of archived model data available from AFWA, verification is not yet possible. Instead, the AMU proposed to implement and verify the performance of an ER version of the high-resolution WRF Environmental Modeling System (EMS) model configured by the AMU (Watson 2013) in real time. Implementing a real-time version of the ER WRF-EMS would generate a larger database of model output than in the previous AMU task for determining model performance, and allows the AMU more control over and access to the model output archive.

The tasking group agreed to this proposal; therefore the AMU implemented the WRF-EMS model on the second of two NASA AMU modeling clusters. The AMU also calculated verification statistics to determine model performance compared to observational data. Finally, the AMU made the model output available on the AMU Advanced Weather Interactive Processing System II (AWIPS II) servers, which allows the 45 WS and AMU staff to customize the model output display on the AMU and Range Weather Operations (RWO) AWIPS II client computers and conduct real-time subjective analyses.

2 Model Installation and Configuration

The first part of this task was to set up the model to run in real time. Once the NASA AMU modeling cluster was configured for AMU use, the AMU installed and configured WRF-EMS, and completed a few test runs. After confirming WRF-EMS was running properly, the AMU set up a triple-nested grid configuration over KSC/CCAFS based on a previous AMU task (Watson 2013). The results of that work showed the best configuration for the ER used the Advanced Research WRF core with the Lin microphysical scheme and the Yonsei University planetary boundary layer scheme. Once the model setup was configured and tested, the AMU automated WRF-EMS to run a 12-hr forecast every hour. The model is initialized every hour using the National Centers for Environmental Prediction's (NCEP) 13-km Rapid Refresh model for boundary and initial conditions, Short-term Prediction Research and Transition Center (SPoRT) Land Information System land surface data, and SPoRT sea surface temperature data.

Figure 1 shows the boundaries of the three domains included in this task. D01 is the outer domain with 12-km grid spacing, D02 is the middle domain with 4-km grid spacing, and D03 is the inner domain with 1.33-km grid spacing. D01 and D02 domain output is available once an hour and D03 is available every 15 minutes during the 12-hr forecast period. The boundaries of D01, which include much of the eastern United States, were selected should this work grow to include Wallops Flight Facility in the future. D03 is centered over the ER and is the domain for which the AMU calculated verification statistics to determine model performance.

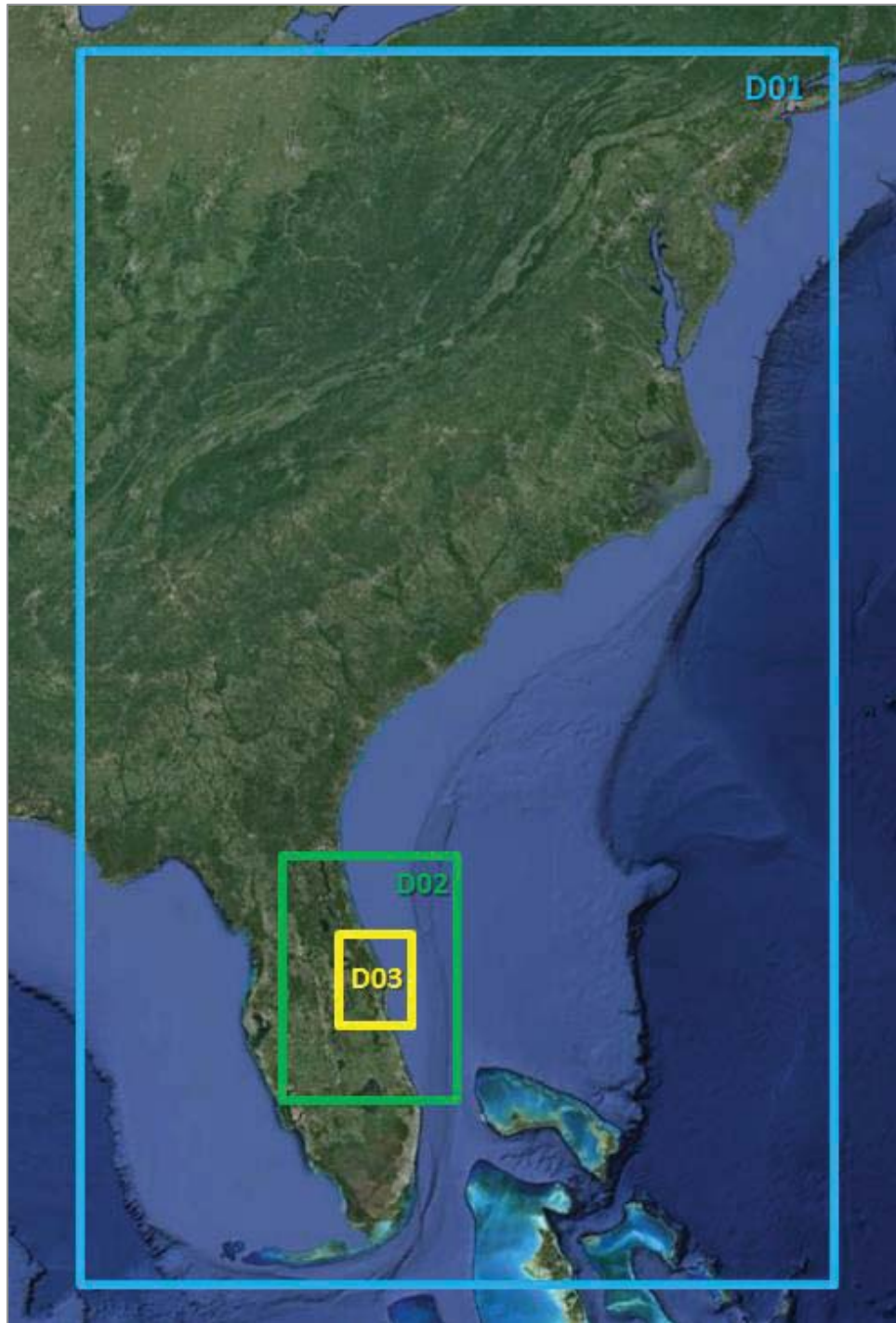


Figure 1. Map of the eastern United States showing the boundaries of each domain. The outer domain (cyan rectangle, D01) has 12-km grid spacing, the middle domain (green rectangle, D02) has 4-km grid spacing, and the inner domain (yellow rectangle, D03) has 1.33-km grid spacing. The AMU calculated verification statistics for the inner domain, D03.

3 Model Forecast Verification

The AMU assessed model performance by computing statistics that compared the model forecasts to observations. The mean error (ME) and root mean square error (RMSE) were calculated for the surface parameter forecasts, and precipitation forecasts were compared to nationally available rainfall data using a technique developed at the National Center for Atmospheric Research (NCAR).

3.1 Observational Data

In order to determine the WRF-EMS model performance, the AMU required surface weather observations of temperature (T), dewpoint temperature (T_d), wind speed and direction, and mean sea-level pressure (MSLP) as well as rainfall data. Based on the previous AMU model verification work (Watson 2013), the AMU used the NCEP Meteorological Assimilation Data Ingest System (MADIS) and Stage IV precipitation data for the observational datasets.

3.1.1 MADIS

The AMU coordinated with NCEP and set up a data connection to the NASA AMU cluster. With this connection the AMU automatically receives MADIS observational data using the local data manager software in real time. MADIS includes multiple data types including METAR and mesonet files. METAR is the international standard code format for hourly surface weather observations. Mesonet refers to a network of automated weather stations designed to observe mesoscale meteorological phenomena and report conditions in time intervals anywhere from 1 to 15 minutes. These data were used to verify hourly 2-m T (K), T_d (K), 10-m wind speed (ms^{-1}) and direction (degrees), and MSLP (mb). Figure 2 shows the locations of the METAR and mesonet weather stations (https://madis-data.noaa.gov/sfc_display/) that were used to verify the performance of the WRF-EMS inner domain.

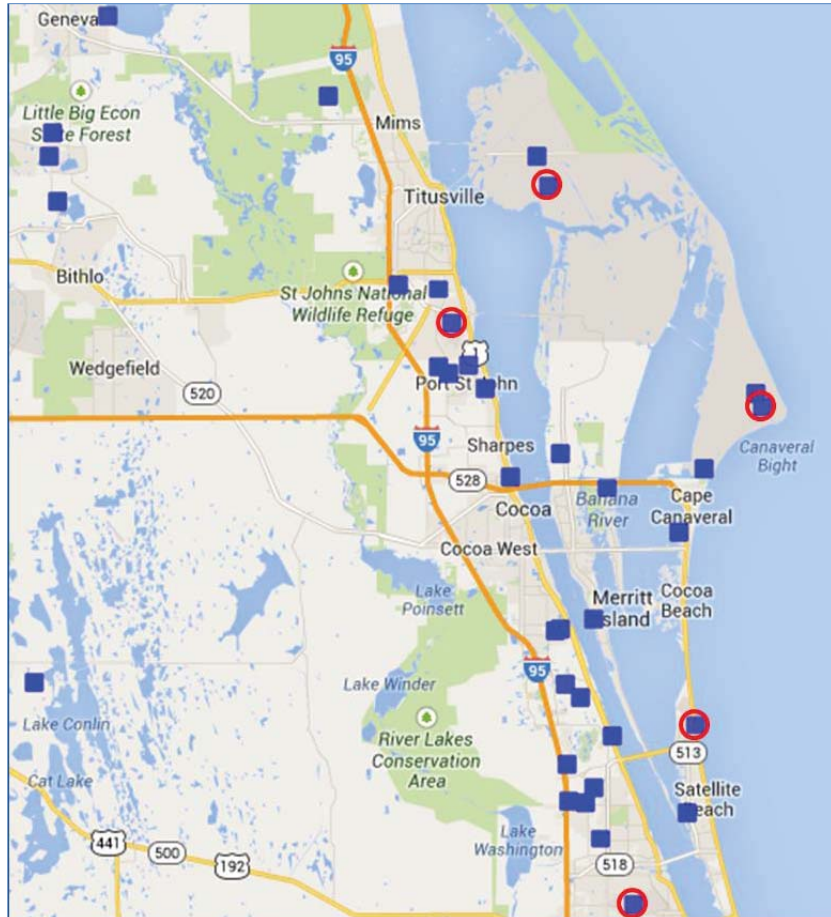


Figure 2. Map of the mesonet (blue squares) and METAR (blue squares with red circles) weather station locations from MADIS. The AMU used the data from these sites to calculate verification statistics for the inner WRF-EMS domain.

3.1.2 Stage IV

In addition to the MADIS data, the AMU used gridded NCEP Stage IV precipitation data (<http://www.emc.ncep.noaa.gov/mmb/ylin/pcpanl/stage4/>) to verify the hourly WRF-EMS precipitation forecasts. The Stage IV data combines radar data and rain gauge reports to produce hourly rainfall accumulation on a 4-km grid. It is a manually quality-controlled mosaic from the regional 1-hr precipitation analyses produced by 12 National Weather Service Forecast Centers (Lin and Mitchell 2005).

3.2 Verification Software

The AMU calculated verification statistics to determine the WRF-EMS model performance using the Model Evaluation Tools (MET) software. MET was developed by the NCAR Developmental Testbed Center through the support of AFWA and the National Oceanic and Atmospheric Administration. It was designed to be a highly configurable, state-of-the-art suite of verification tools (MET User's Guide 2013). The AMU used two of the statistical verification tools available in MET for this task: the Point-Stat tool and the Method for Object-Based Diagnostic Evaluation (MODE) tool.

3.2.1 Point-Stat Tool

The Point-Stat tool was used to compute traditional verification scores for the hourly surface forecasts including 2-m T (K), T_d (K), 10-m wind speed (ms⁻¹) and direction (degree), and MSLP (mb). It compares the WRF-EMS forecast to the corresponding MADIS point observations. This tool was run on each hourly forecast and consolidated to determine the overall model performance.

3.2.2 MODE Tool

The MODE tool applies an object-based verification technique in comparing a gridded forecast to a gridded analysis. MODE was used to compare the WRF-EMS precipitation accumulation forecasts to the NCEP Stage IV observations.

In order to use MODE for verification, the timing and grid spacing of the forecast must match observational data. Since the WRF-EMS produces precipitation forecasts every 15 minutes on a 1.33-km grid and the Stage IV data is available hourly on a 4-km grid, the AMU had to reformat the WRF-EMS output to match the observations. Each of the 15-minute WRF-EMS files were converted from 1.33-km to a 4-km grid and then combined to create a 1-hr 4-km WRF-EMS precipitation accumulation forecast file. The MODE tool ingested these new files and compared them to the Stage IV data for verification. This process was repeated for every forecast hour.

3.3 Warm Season Verification Results

The AMU calculated verification statistics to determine the WRF-EMS 1.33-km domain model performance for the 2014 warm season (May–September) using the tools described in section 3.2.

3.3.1 Surface Parameters

The Point-Stat tool was used to compute the ME and RMSE for the hourly 2-m MSLP, T, T_d, and 10-m wind speed and direction. The ME is the overall bias of the model parameter during the period of interest, calculated by subtracting the observation from the forecast and averaging the differences. It determines whether there is a positive, negative, or no bias in the model forecast for any parameter. ME values range from negative infinity to infinity with a perfect score equal to 0.

$$ME = \frac{1}{n} \sum_{i=1}^n (f_i - o_i)$$

where:

n = number of model output times and/or vertical levels over the forecast period,

f_i = WRF forecast of MSLP, T, T_d, wind speed, or wind direction, and

o_i = observed MSLP, T, T_d, wind speed, or wind direction.

The RMSE isolates the magnitude of the model error as ME can mask the variance in the differences between the forecast and observations. An ME close to 0 could be the result of averaging larger negative and positive differences. The RMSE equation squares the differences, calculates an average of the squared differences, then calculates the square root of the average value. As with ME, smaller RMSE values indicate better model performance. It ranges from 0 to infinity with a perfect score equal to 0.

$$RMSE = \sqrt{\frac{1}{n} \sum_{i=1}^n (f_i - o_i)^2}$$

where n , f_i , and o_i are defined as above.

Figure 3 shows the ME for MSLP, T, T_d , and wind speed versus model forecast hour for the 2014 warm season. The ME curve for T is close to 0 at all forecast hours, indicating a good forecast for this parameter. The ME values for wind speed and T_d are within ± 0.4 with wind speed showing a small positive bias and T_d showing a slightly negative, or dry, bias. The values for MSLP are all negative ranging from -1.2 to -1.4. Considering the magnitude of MSLP values on the order of 1000 mb, these biases are very small in comparison. Figure 4 is the same but for wind direction. These values increase with forecast hour from just above 25 to 35 degrees.

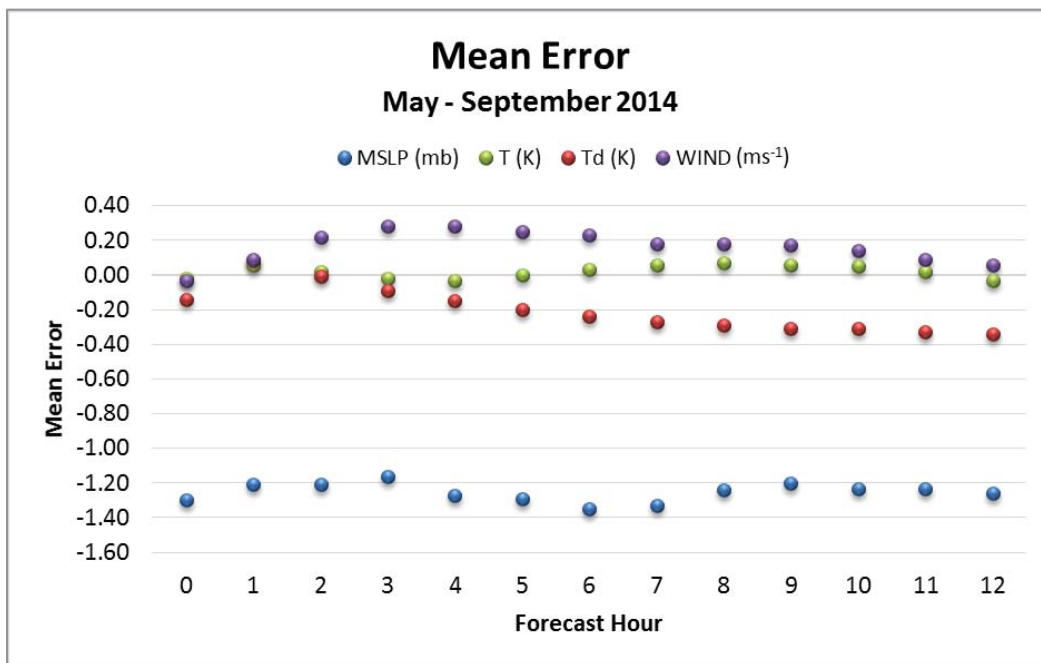


Figure 3. The ME for each parameter versus forecast hour. Surface pressure is in mb (blue dots), temperature in K (green dots), dewpoint temperature in K (red dots) and wind speed in ms⁻¹ (purple dots).

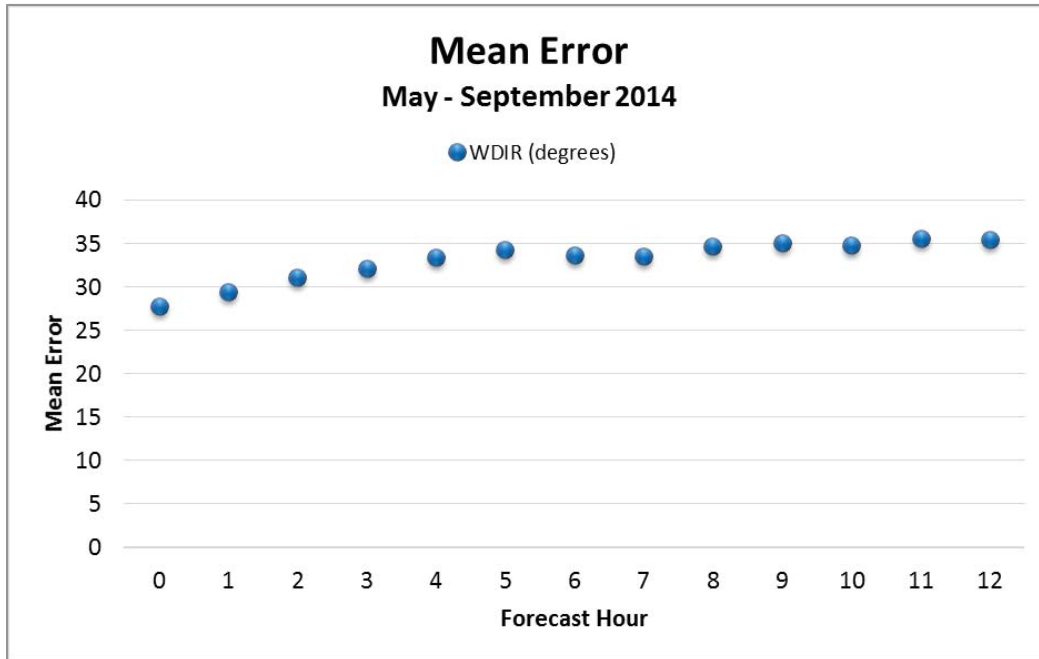


Figure 4. The ME for wind direction in degrees versus forecast hour.

Figures 5 and 6 are the same as Figures 3 and 4 respectively, but for RMSE. The RMSE values for MSLP, T, T_d and wind speed slightly increase with forecast hour but remain between 1 and 1.8 (Figure 5). These values are close to 0 which confirms the magnitude of the model error for these parameters is very small. A similar trend exists for wind direction but the RMSE values range from about 40 to 50 degrees. These values could be because of light and variable winds that are common at night over KSC/CCAFS during the warm season. When winds are light there tends to be a large variance in the wind direction that would be difficult for the model to forecast. In the future, the AMU will stratify the warm season results diurnally to determine how the time of day influences the model wind direction forecasts.

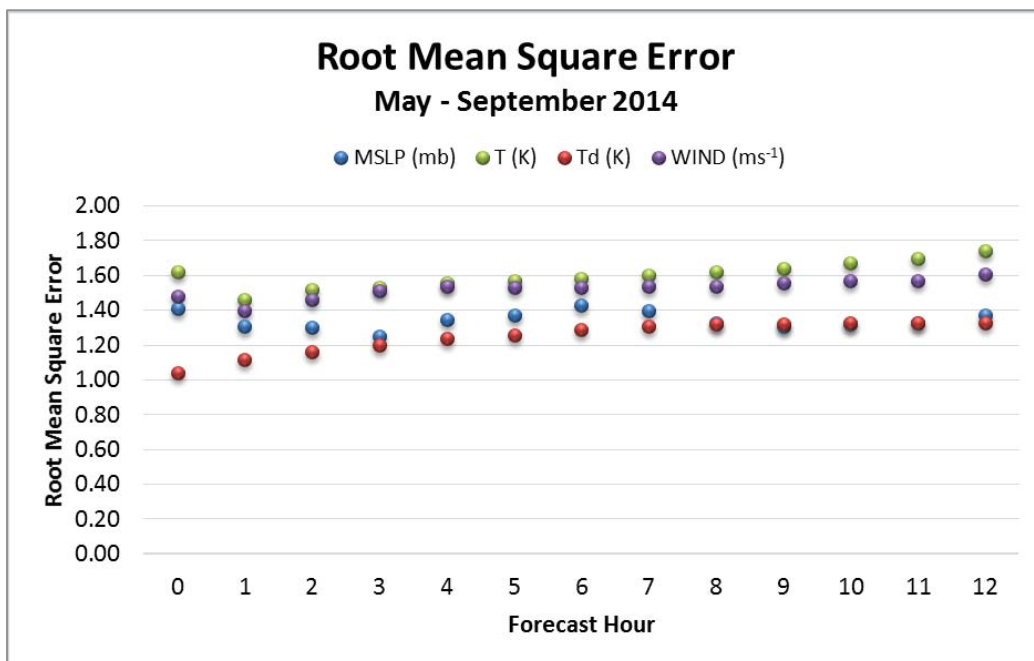


Figure 5. Same as Figure 3 but for RMSE.

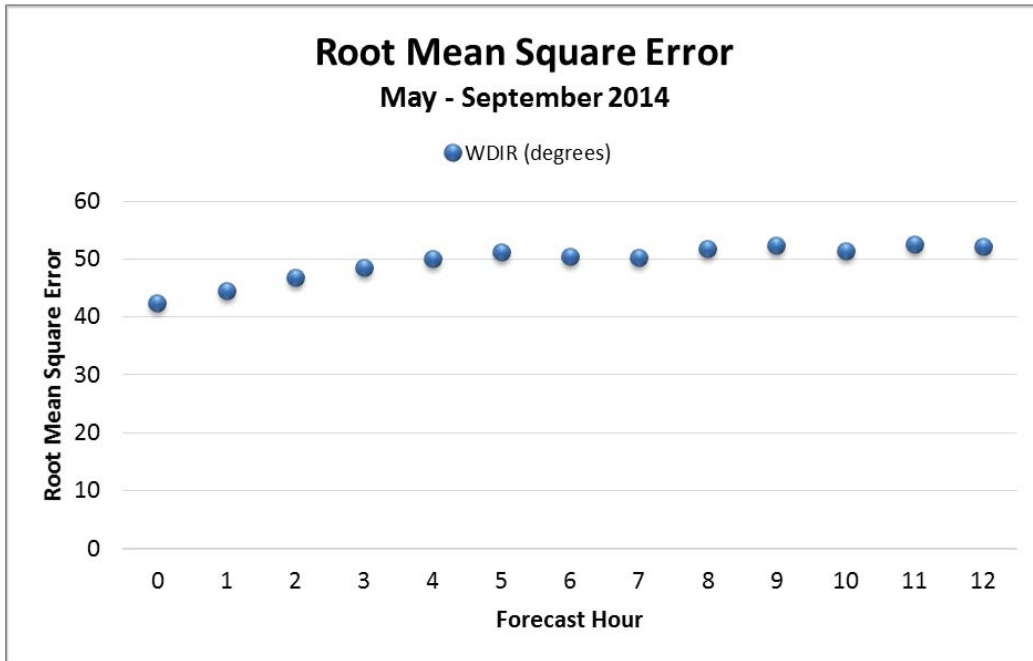


Figure 6. Same as Figure 4 but for RMSE.

3.3.2 Precipitation

The MODE tool was used to verify the model precipitation forecasts. This tool applies an object-based verification technique to compare a gridded forecast to a gridded analysis. The technique for defining objects in MODE is illustrated in Figure 7. Figure 7a is an example of raw gridded data. MODE uses two processes to convert raw gridded precipitation values into precipitation objects. The first step is to smooth the data (Figure 7b) and the second is to create a convolved field (Figure 7c). Once these steps are complete, MODE has defined final precipitation objects (Figure 7d) that are used in the verification statistics. A more detailed explanation about this process and MODE is in the MET User's Guide, chapter 8 (2013). Table 1 shows the statistics the AMU used from MODE for the model verification.

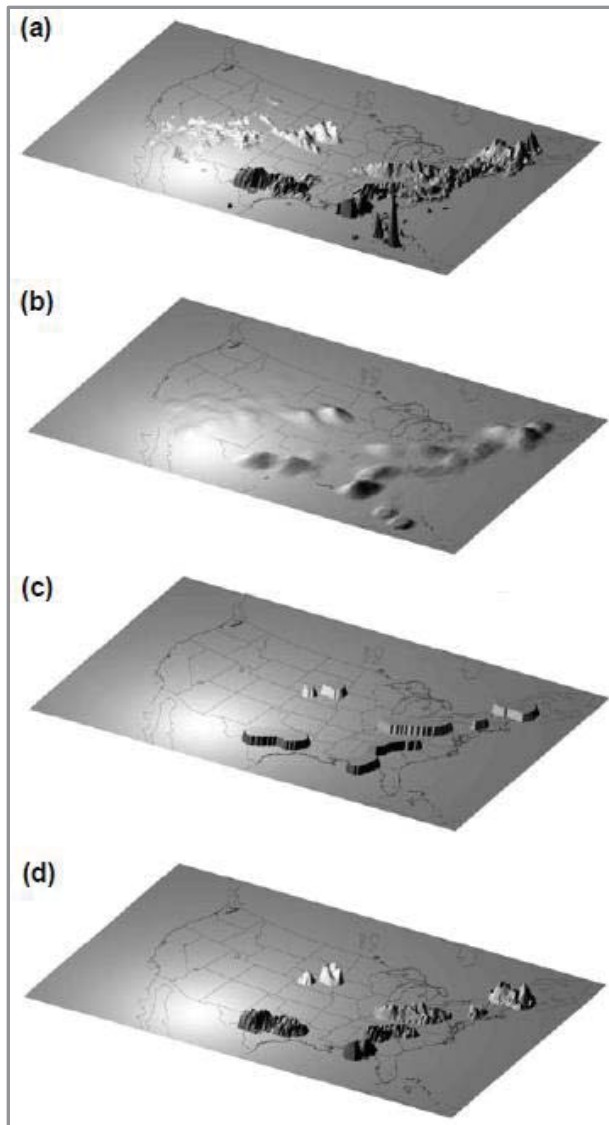


Figure 7. Illustration of the technique used in the MODE tool to define precipitation objects: a) raw gridded precipitation data, b) smoothed data, c) convolved field, d) final field of objects used in verification statistics (from the MET users guide, Figure 8-1).

Table 1. List of statistics available in the MODE tool the AMU used to verify the model.	
Statistic Name	Description
Centroid Distance	Distance between two object centroids (in grid units)
Area Ratio	Ratio of the areas of two objects defined as the lesser of the forecast area divided by the observation area or its reciprocal (unitless)
Interest	Total interest value computed for a pair of simple objects (unitless)

The centroid distance is the distance between the centers of two objects: the observed precipitation object and the corresponding forecast precipitation object. A perfect forecast would have a centroid distance equal to 0. Figure 8 shows the centroid distance versus model forecast hour for the warm season verification. As expected, there is a general increase in distance with time although it remains between 35 and 38 grid boxes. The distance in km is the centroid distance in grid boxes multiplied by the domain resolution of 1.33-km, resulting in distances between 46.55 and 50.54 km. These location differences may be present because warm season convection remains one of the most poorly forecast meteorological parameters, in part due to dynamic and thermodynamic features that occur on the mesoscale (Watson 2007). Note that MODE does not calculate statistics for the initialization time (Forecast Hour = 0) since the model takes time to spin-up the precipitation forecasts.

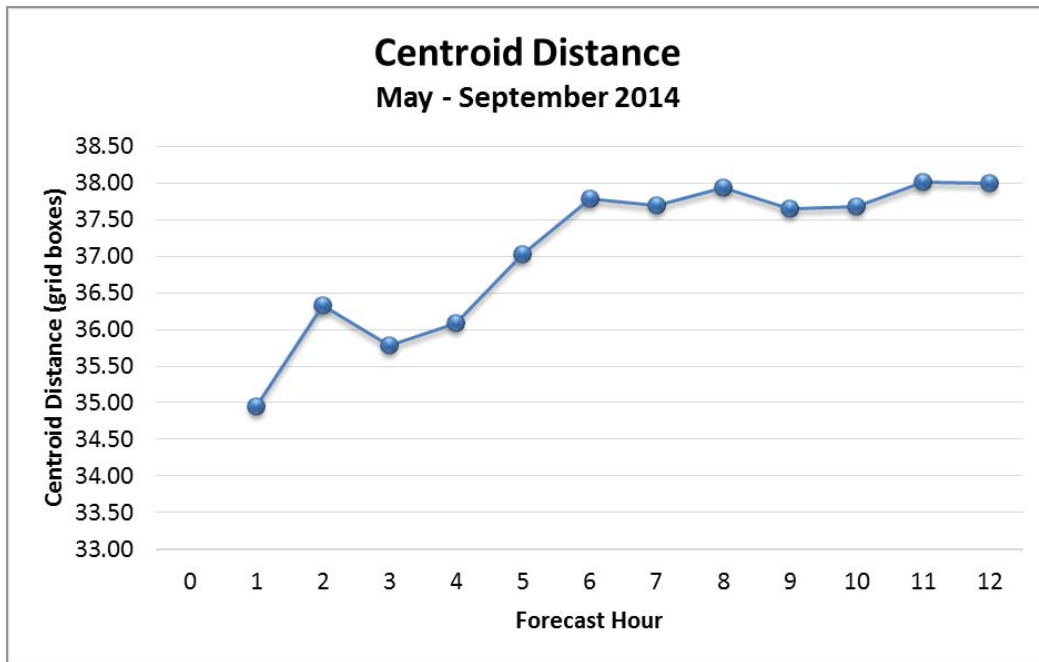


Figure 8. Centroid distance versus model forecast hour for the warm season model verification. Centroid distances are in number of grid boxes.

The area ratio compares the size of the forecast objects to the observation objects (forecast area divided by observation area). A perfect forecast would have an area ratio equal to 1. A value greater than 1 indicates the model is forecasting larger objects than observed, and a value less than one indicates the model is forecasting smaller objects than observed. Figure 9 shows the area ratio versus model forecast hour remaining steady at about 0.35. This means the model is consistently under-forecasting the size of the precipitation objects.

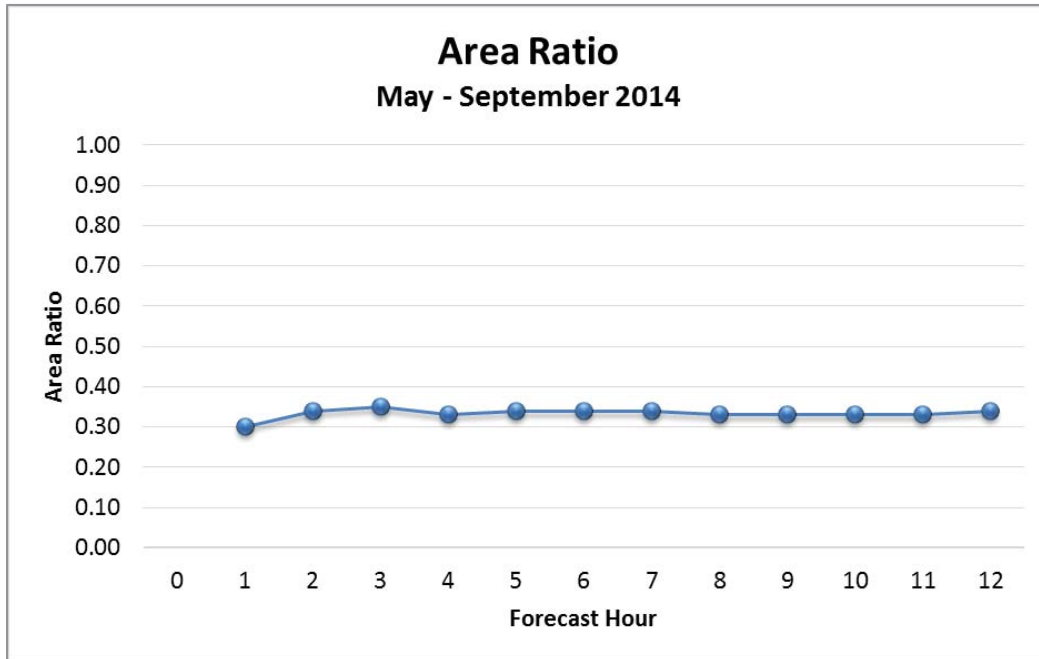


Figure 9. Area ratio versus model forecast hour for the warm season model verification.

Finally, the interest value compares the differences in attributes between the forecast and observed objects, including the centroid distance and area ratio, and gives an indication of the overall quality of the model precipitation forecasts. It ranges from 0 to 1 with a perfect score equal to 1. More detail about these statistics can be found in Brown et al. 2007. Figure 10 shows the interest versus model forecast hour. These values consistently remain just above 0.6 regardless of model forecast hour.

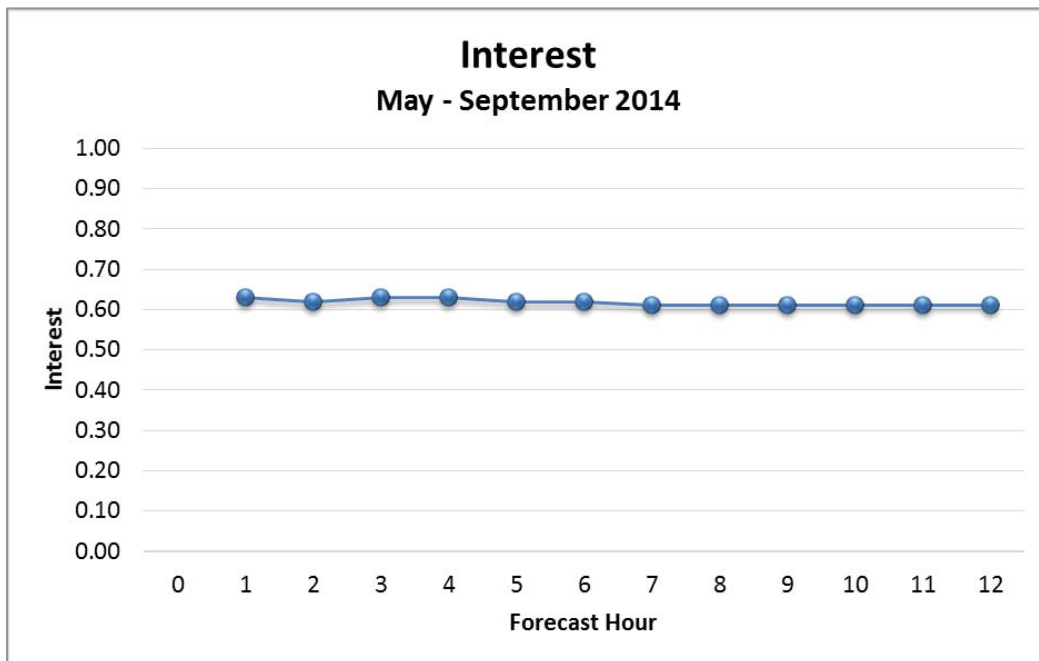


Figure 10. Interest value versus model forecast hour for the warm season model verification.

3.3.3 Summary of Results

The ME values were close to 0 and the RMSE values were less than 1.8 for MSLP, T, T_d, and wind speed, all very small differences between the forecast and observations considering the normal magnitudes of the parameters. The RMSE for wind direction was between 40 and 50 degrees which could be because of the light and variable winds that are common at night over KSC/CCAFS during the warm season. In the future, the AMU will stratify the results diurnally to determine how the time of day influences the model wind direction forecasts. The precipitation forecast verification results showed consistent under-forecasting of the precipitation object size. This could be an artifact of calculating the statistics for each hour rather than for the entire 12-hour period. For example, if the timing of the model-forecast precipitation occurs within the hour before or after the observed precipitation, then the forecast will not match the observation. The model may also correctly forecast the location of the precipitation but the statistics could still show poor model performance due to timing. The AMU will continue to generate verification statistics for the 1.33-km WRF-EMS domain as data become available in future cool and warm seasons. More data will produce more robust statistics and reveal a more accurate assessment of model performance.

4 WRF-EMS Output into AWIPS II

In addition to verifying the model's performance, the AMU also made the output available in AWIPS II. This allows the 45 WS and AMU staff to customize the model output display on the AMU and RWO AWIPS II client computers and conduct real-time subjective analyses. The AMU was able to customize the WRF-EMS runs and ingest the three WRF-EMS domains separately in order to display them individually in AWIPS II via the Common AWIPS Visualization Environment (CAVE).

4.1 CAVE Examples

Example CAVE screen shots of the 12-, 4- and 1.33-km AMU WRF-EMS model frontogenesis forecast product are shown in Figures Figure 11, Figure 12 and Figure 13, respectively. The AMU wrote Perl scripts that automate the ingest process and update the model in AWIPS II every hour.

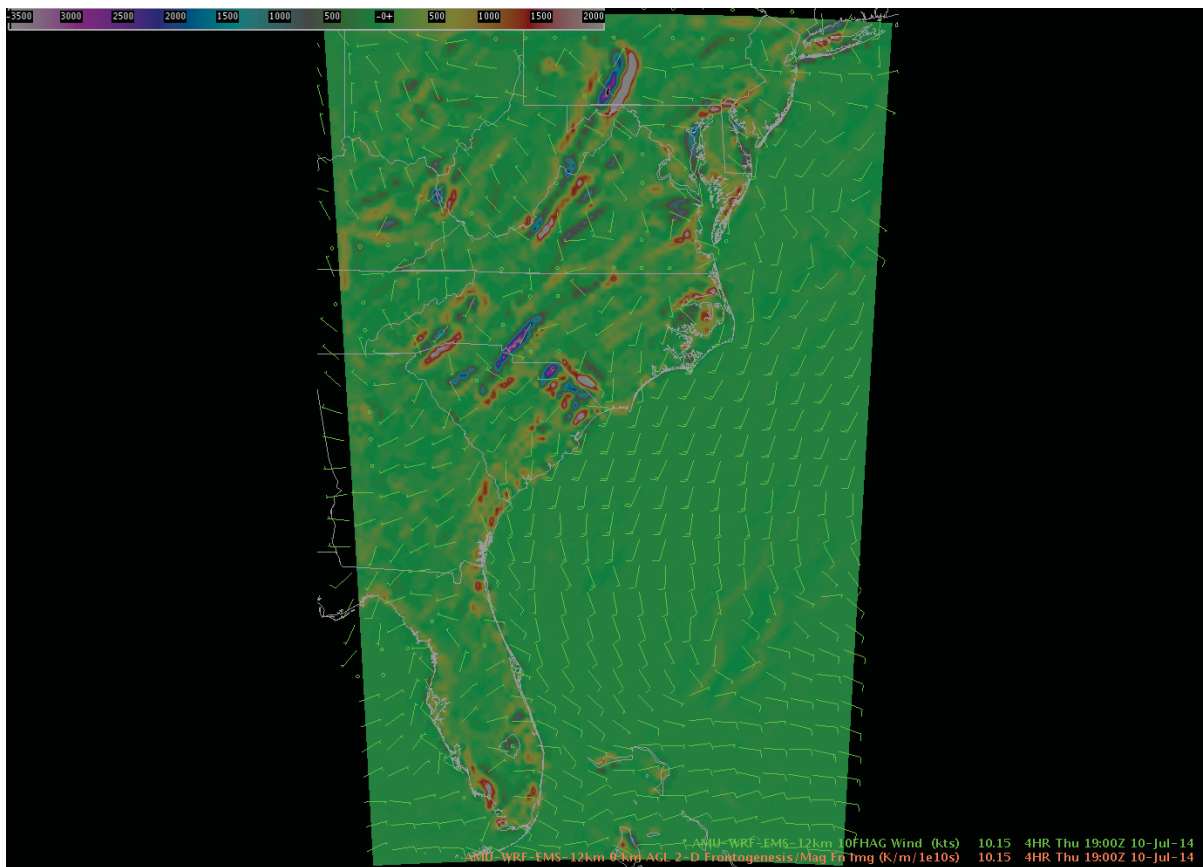


Figure 11. CAVE screen shot of the AMU WRF-EMS 12-km frontogenesis output valid at 1900 UTC on 10 July 2014. The warm colors are frontogenesis and the cool colors are frontolysis.

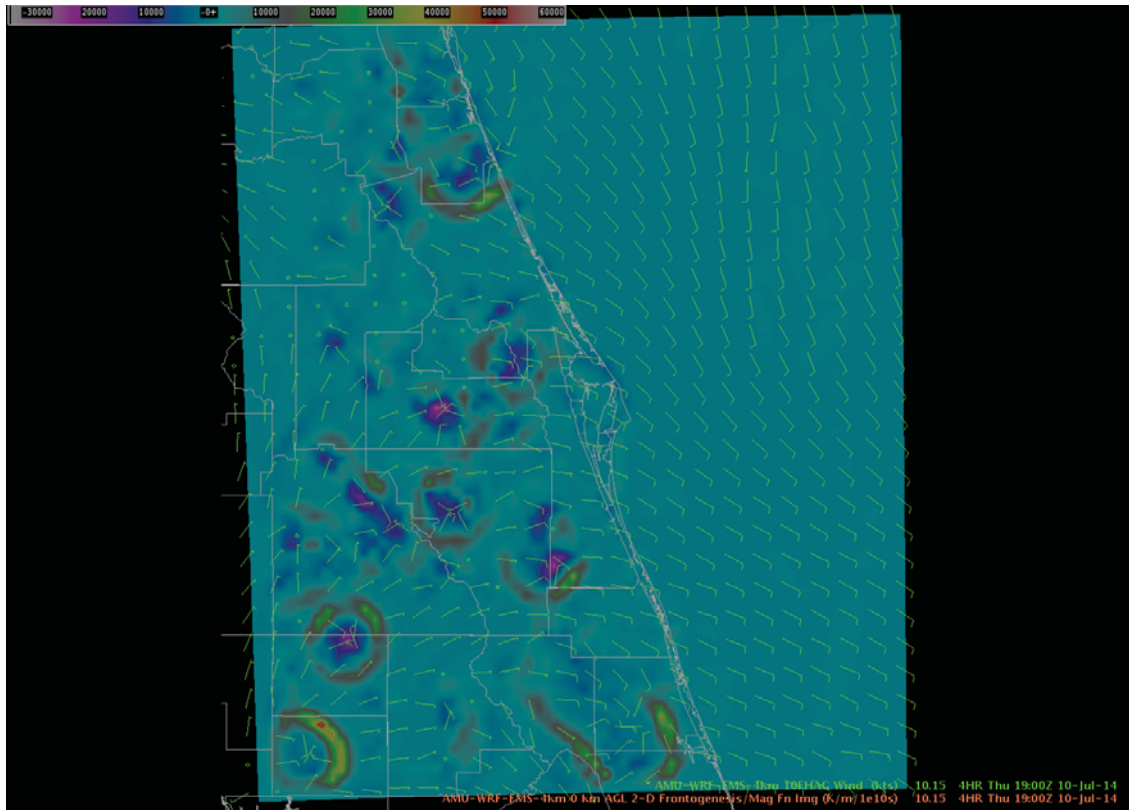


Figure 12. Same as Figure 11 but for the 4-km domain.

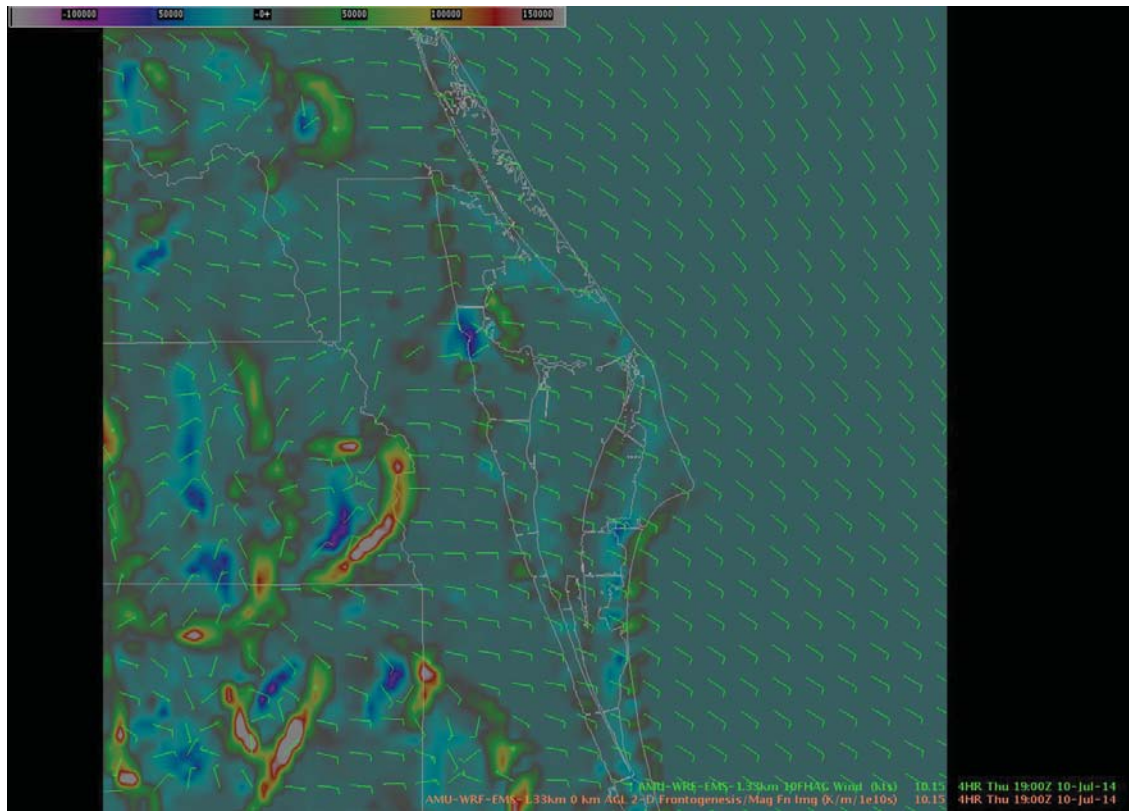


Figure 13. Same as Figure 11 but for the 1.33-km domain.

4.2 Procedures to Display WRF-EMS Output

Like all other model data available in AWIPS II, the AMU WRF-EMS is accessed via the CAVE Volume Browser. To open the Volume Browser, the user must select Volume and then Browser in the CAVE window (Figure 14). This will open the Volume Browser window. To access the AMU WRF-EMS forecasts, click the Volume drop-down list under *Sources* as indicated in Figure 15. A partial list of the model forecasts available via the Volume drop-down menu is shown in Figure 16. The three AMU WRF-EMS domains are at the top of the list. The user must then select the desired *Field* and *Plane*, for example Wind and Surface respectively, which will list the available products under *Product Selection List* (Figure 17). The product is loaded by either double clicking the item in the *Product Selection List*, or clicking the *Load* button.

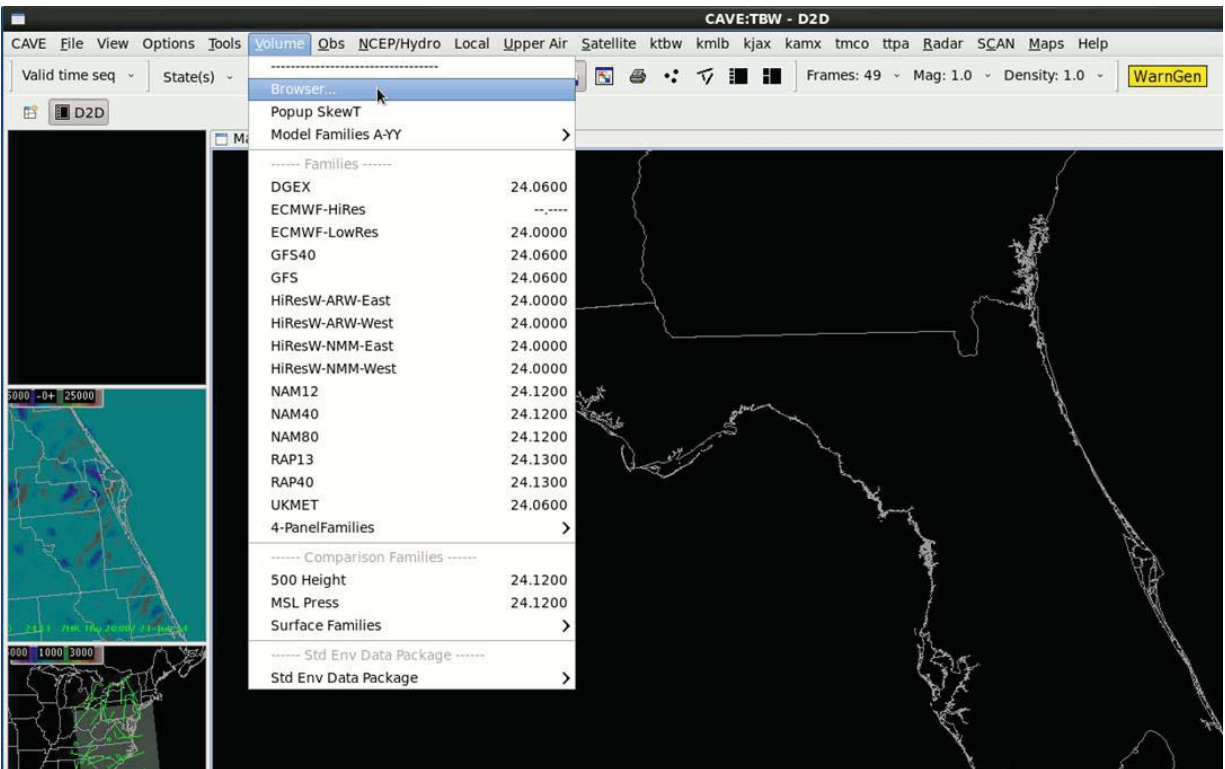


Figure 14. CAVE window highlighting how the user selects the Volume Browser to display model data.



Figure 15. Volume Browser window in CAVE. The AMU WRF-EMS is selected by clicking the Volume drop-down menu under Sources.

- AMU-WRF-EMS-12km
- AMU-WRF-EMS-4km
- AMU-WRF-EMS-1.33km
- DGEX
- AK-GFS
- AK-NAM12
- AK-NAM40
- AK-SREF
- Aviation
- DGEX
- ECMWF-HiRes
- ECMWF-LowRes
- GFS190
- GFS360
- GFS40
- GFS75
- GFS90
- GFSensemble
- GFSGbl
- HiResW-ARW-AK
- HiResW-ARW-East
- HiResW-ARW-PR
- HiResW-ARW-SJU
- HiResW-ARW-West
- HiResW-NMM-AK
- HiResW-NMM-East

Figure 16. A partial list of available models from the Volume drop-down showing the three AMU WRF-EMS domains at the top of the list.

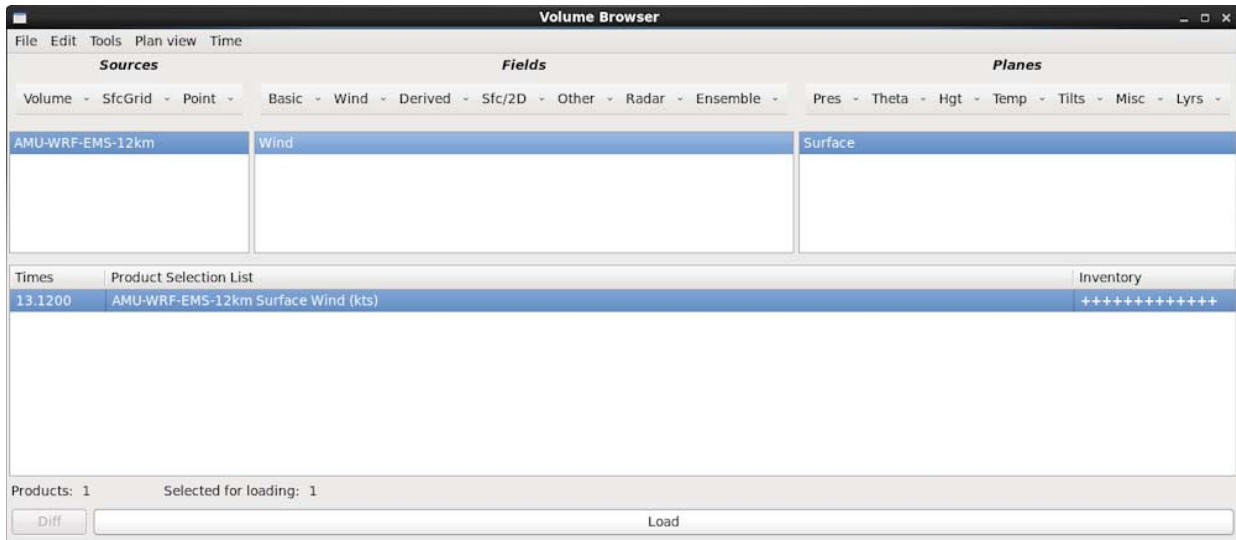


Figure 17. Volume Browser showing the selection of AMU WRF-EMS parameters and associated available products.

Figure 18 shows the products in the main CAVE window based on the selections highlighted in Figure 17. The surface wind barbs within the 12-km, outer-domain are shown in green. The bottom right corner of the window shows the loaded product details. Figure 19 is a zoomed in image of the details. The red box outlines the product name, in this example it is the AMU WRF-EMS 12-km surface winds. Next, the blue box shows the date and time (Z) the model was run. The third box (purple) is the forecast hour (0–12 hours). Finally, the green box shows the product's valid date and time.

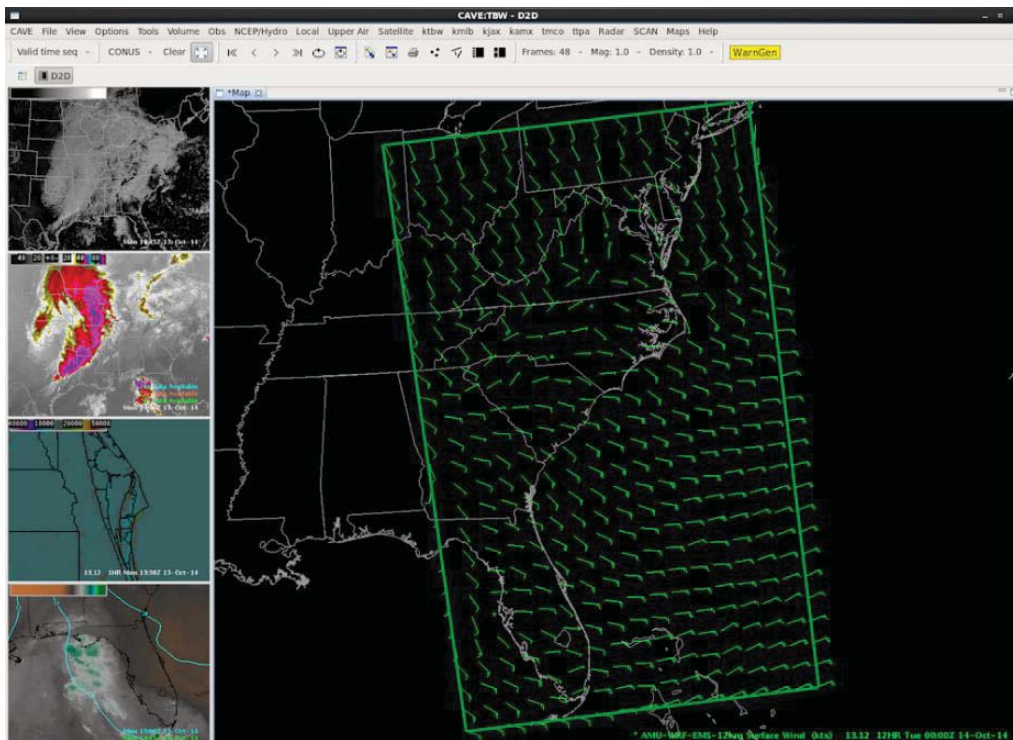


Figure 18. AMU WRF-EMS 12-km forecast surface wind barbs (green).



Figure 19. Zoomed in image of the product details shown in Figure 18. The red box outlines the product name, the blue box is the date and model run time (Z), the purple box is the forecast hour and the green box is the valid date and time.

5 Summary and Future Work

Given the extensive use of the AFWA 1.67 WRF model in operations, the 45 WS proposed a task at the September 2013 AMU Tasking Meeting requesting the AMU verify this model. Since there is a lack of archived model data available from AFWA, verification is not yet possible. Therefore, the AMU proposed to implement and verify the performance of an ER version of the AMU high-resolution WRF-EMS model in real-time. The tasking group agreed to this proposal and therefore the AMU implemented the WRF-EMS model on the second of two NASA AMU modeling clusters to begin producing model output for the verification. The model was set up with a triple-nested grid configuration over KSC/CCAFS based on a previous AMU task (Watson 2013).

The AMU assessed the WRF-EMS 1.33-km model performance for the 2014 warm season. Verification statistics were computed using the MET software, which compared the model forecasts to observations. The observational datasets included MADIS surface observations and Stage IV gridded precipitation data from NCEP. The ME values were close to 0 and the RMSE values were less than 1.8 for MSLP, T, T_d, and wind speed, all very small differences between the forecast and observations considering the normal magnitudes of the parameters. The RMSE for wind direction was between 40 and 50 degrees which could be because of the light and variable winds that are common at night over KSC/CCAFS during the warm season. In the future, the AMU will stratify the results diurnally to determine how the time of day influences the model wind direction forecasts. The precipitation forecast verification results showed consistent under-forecasting of the precipitation object size. This could be an artifact of calculating the statistics for each hour rather than for the entire 12-hour period. The AMU will continue to generate verification statistics for the 1.33-km WRF-EMS domain as data become available in future cool and warm seasons. As a potential future task, the AMU could conduct a more in-depth literature review and recalculate verification statistics once a larger database has been acquired. More data will produce more robust statistics and reveal a more accurate assessment of model performance.

In addition to the verification, the AMU also made the output available in AWIPS II. This allows the 45 WS and AMU staff to customize the model output display on the AMU and RWO AWIPS II client computers and conduct real-time subjective analyses. The LWOs and Range Weather Forecasters have found the AMU-WRF model's performance quite useful over the entire summer months during 2014. It has frequently been the preferred model to help accurately identify complex, very small scale boundary interactions. Of particular note, its rapid hourly update capability allows for constant correction and fine-tuning which further aids the LWOs during sensitive ground and launch operations that require specific timing accuracy. In the future, the AMU will implement an updated version of the WRF-EMS model that incorporates local data assimilation based on a recently completed AMU task (Watson 2014). This model will also run in real-time and be made available in AWIPS II.

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List of Acronyms

45 WS	45th Weather Squadron
AFWA	Air Force Weather Agency
AMU	Applied Meteorology Unit
AWIPS	Advanced Weather Interactive Processing System
CAVE	Common AWIPS Visualization Environment
CCAFS	Cape Canaveral Air Force Station
EMS	Environmental Modeling System
ER	Eastern Range
GSDO	Ground Systems Development and Operations
KSC	Kennedy Space Center
LSP	Launch Services Program
LWO	Launch Weather Officer
MADIS	Meteorological Assimilation Data Ingest System
ME	Mean Error
MET	Model Evaluation Tools
MODE	Method for Object-Based Diagnostic Evaluation
MSLP	Mean Sea Level Pressure
NCAR	National Center for Atmospheric Research
NCEP	National Centers for Environmental Prediction
RAP	Rapid Refresh
RH	Relative Humidity
RMSE	Root Mean Square Error
RWO	Range Weather Operations
SLS	Space Launch System
SPoRT	Short-term Prediction Research and Transition Center
T	Temperature
T _d	Dewpoint Temperature
WDIR	Wind Direction
WRF	Weather Research and Forecasting

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