

Information Sciences & Technology: Human-Systems Integration Division



# Visual Stability of Objects and Environments Viewed Through Head-Mounted Displays

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# Definition of a Virtual Environment

A virtual environment is an interactive, virtual image display enhanced by special processing to convince its users that they are personally and directly physically immersed in a space other than the one they actually inhabit.

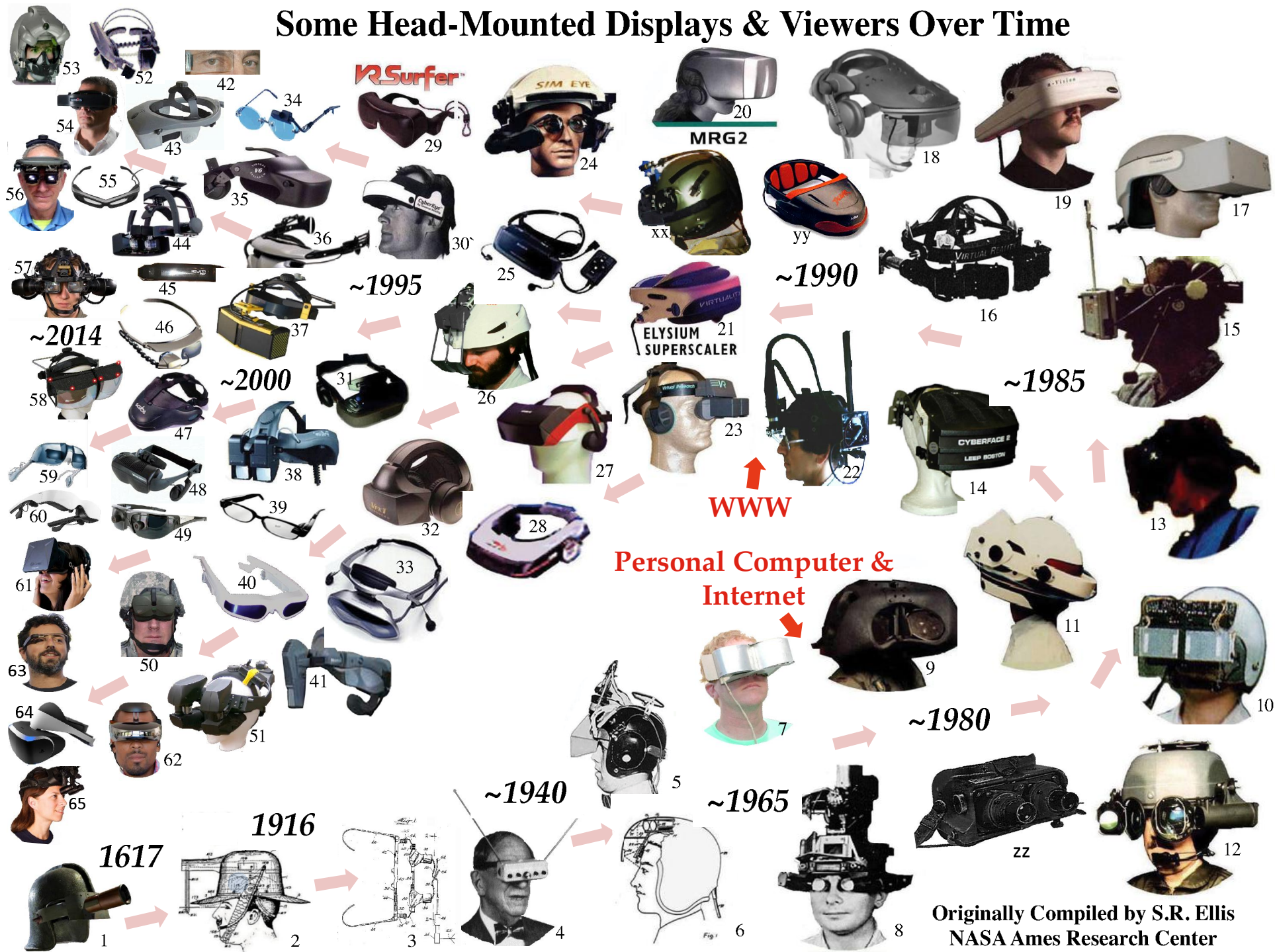


Ivan Sutherland's HMD Univ. of Utah

Ivan Sutherland's virtual environment *personal simulator*<sup>1</sup> circa 1965

<sup>1</sup>Haber, R. N. (1986). The simulation of high speed aircraft flight. *Scientific American*, 255,(July) 96-103.

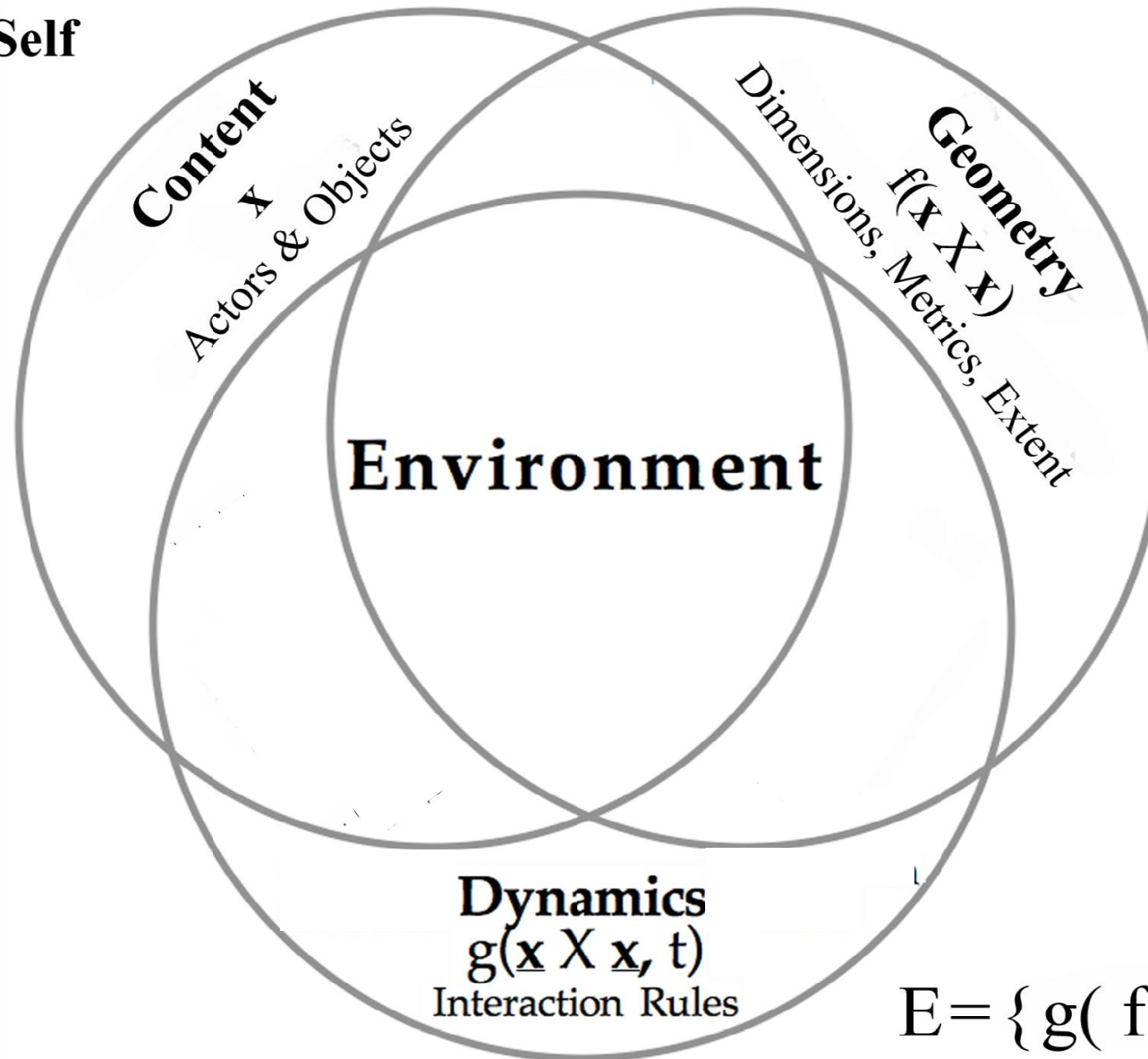
# Some Head-Mounted Displays & Viewers Over Time



Originally Compiled by S.R. Ellis  
NASA Ames Research Center

# Abstract Decomposition of an Environment

Self



$$E = \{ g( f( \mathbf{x} \times \mathbf{x} ), t ) \}$$

# Example of Path Following

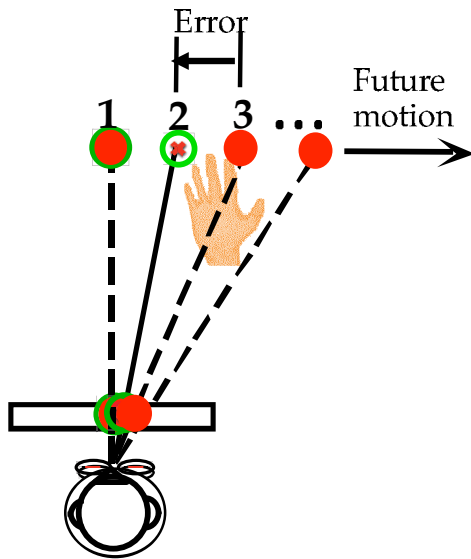
Latency ~380 ms





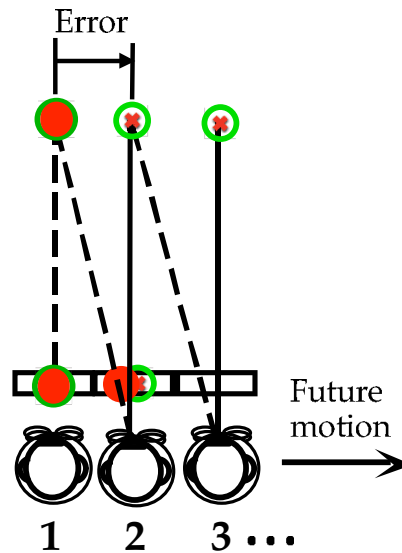
# Intersensory Performance Effects of Latency in A Virtual Environment

## Hand Translation



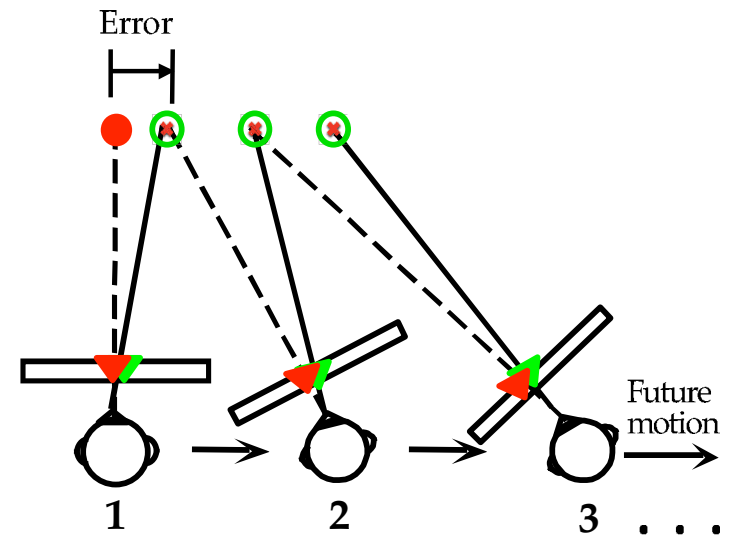
Error in the direction of motion

## Head Translation



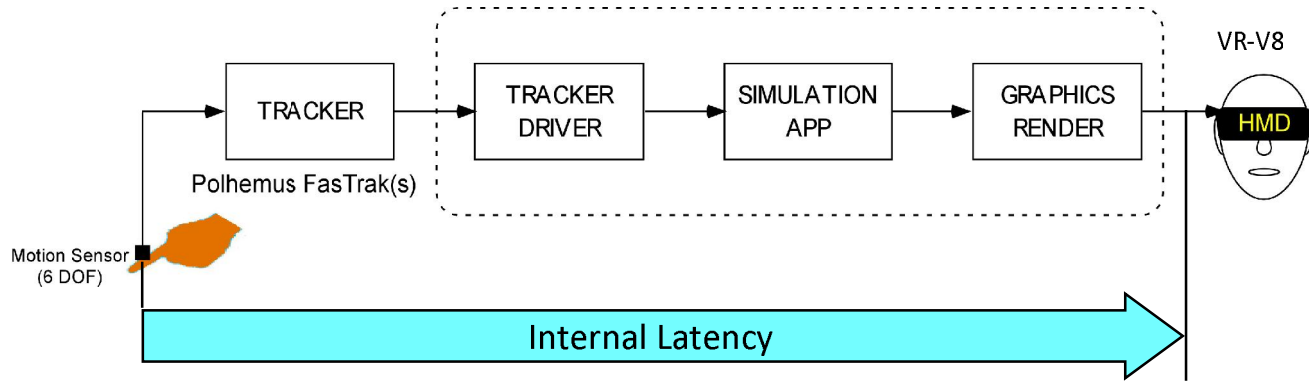
Error against the direction of motion

## Head Translation and Rotation



Superposition of errors both in and against the direction of motion for translation and rotation

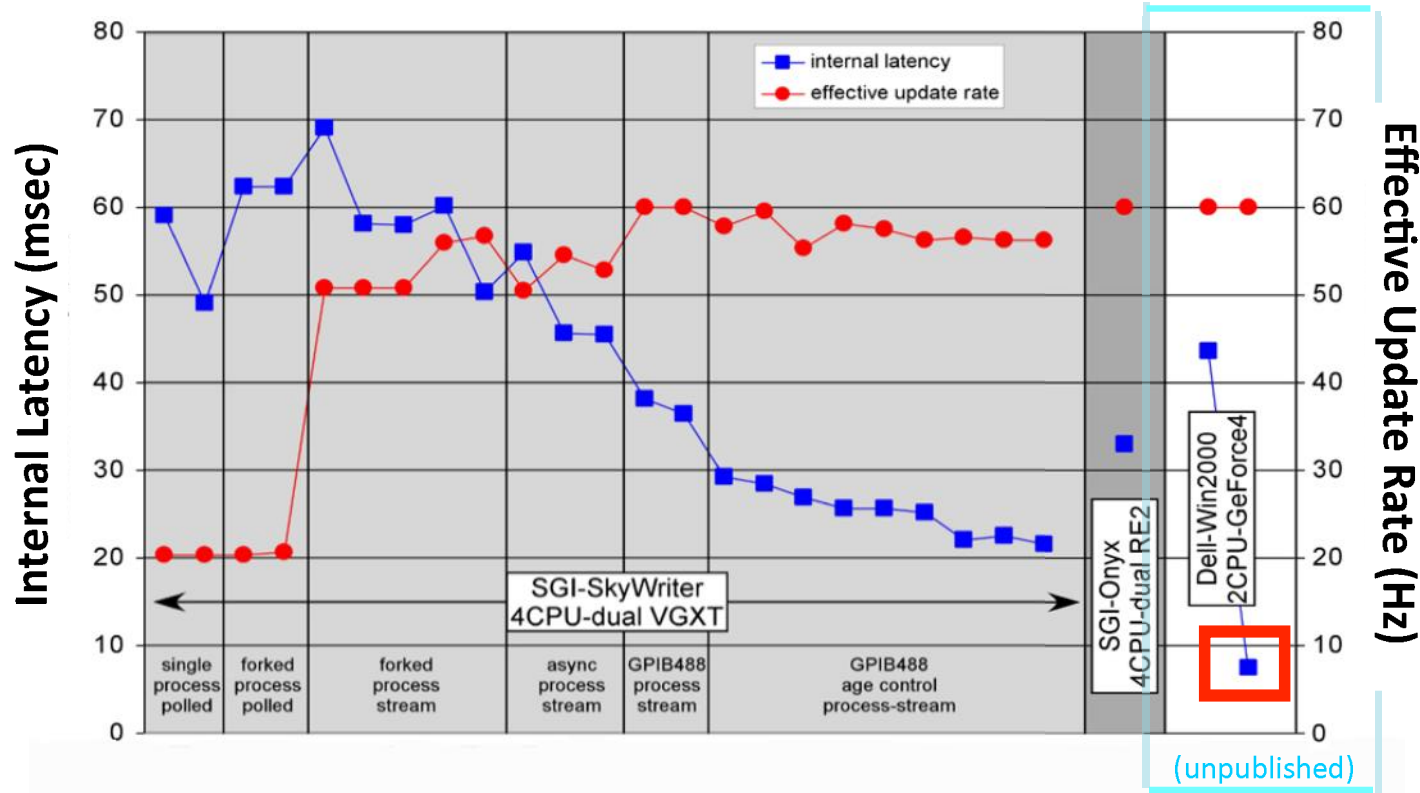
# System Latency with some Polhemus-based Systems



$$E(\tau_{end-to-end}) = \sum_{i=1}^N E(\tau_i)$$

$$\sigma^2_{end-to-end} = \sum_{i=1}^N \sigma_i^2$$

Measure and Model



# Example of Path Following Low Latency ~1994



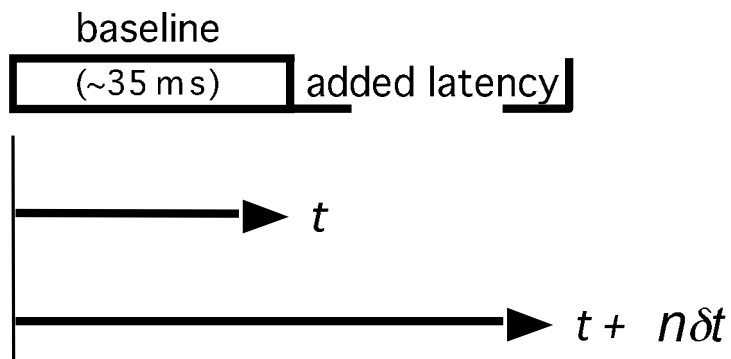


# Some Characteristics of the Head Mounted Display System Used Or Where We Were ~ 1990? (at least some of us)

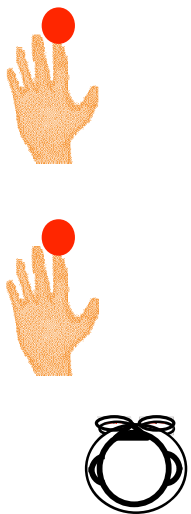
Weight	0.77 – 1.1 kg	Thank you Sony!
Visual		
Resolution	1024 X 768	→ ~700 X 525 <b>check VIEW hardware</b>
Brightness min/max		6/68 cd/m <sup>2</sup> ~ w/r see-thru background
FOV		20°-32° diameter
Contrast(Michelson)		0.6 – 0.8 ~ w/r see-thru background
Color		Monochrome
Accommodative Demand		1 diopter (adjustable)
Stereo resolution		~2-3 arcmin
Stereo overlap		100%
IPD		60 -78 mm
Tracking & Rendering		Polhemus Fastrak/vairous SGI/PCs
Accuracy		~ ±5 mm, 1-2°
Resolution		< 1 mm, < 0.24°
Position sensing:		120 Hz
Frame (Update) rate:		60 Hz
Latency		~45 ms (now 8-25 ms)
User Interface		
		None: voice to computer operator/HMD assistant

# Latency Discrimination in Virtual Environments

## Two-Alternative Forced Choice Discrimination



$t = \{35, 101, 205\}$ ,  $\Delta t = 16.7$  ms  
 $n = \{0, 1, 2, 3, 4, 5, 6\}$



- Method of constant stimuli
- Randomized blocks each base  $t$  (224 judgments)
- Sub-blocks each increment  $\Delta t$  (32 judgments)
- 3 repetitions per subject
- Metronome-paced movement 0.5 Hz

2nd Condition

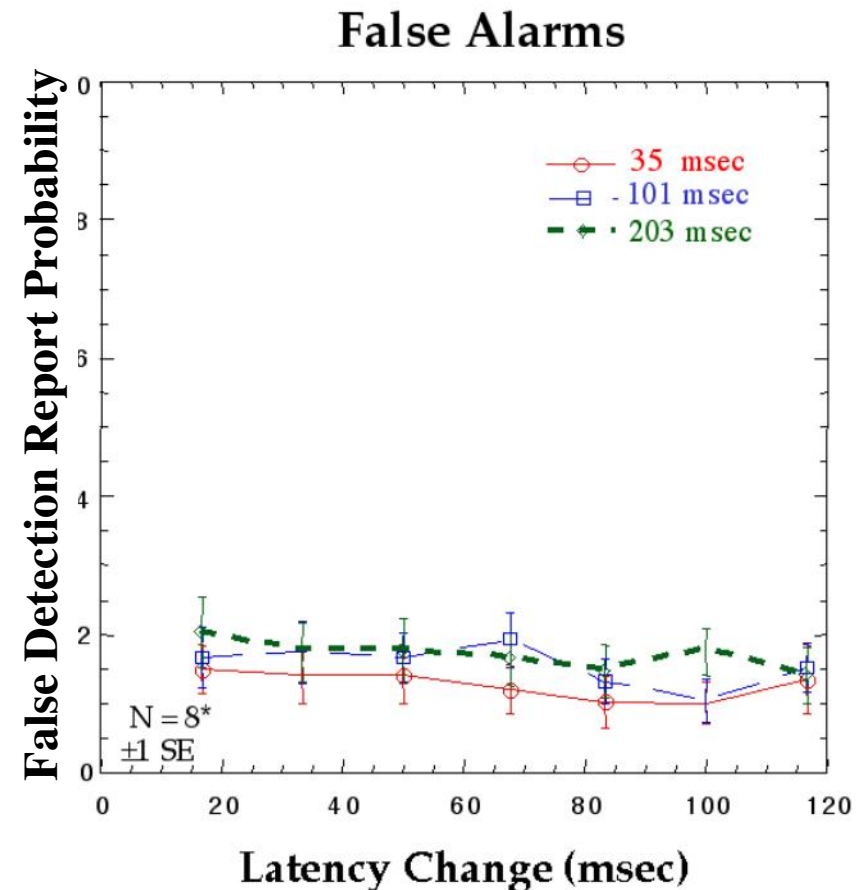
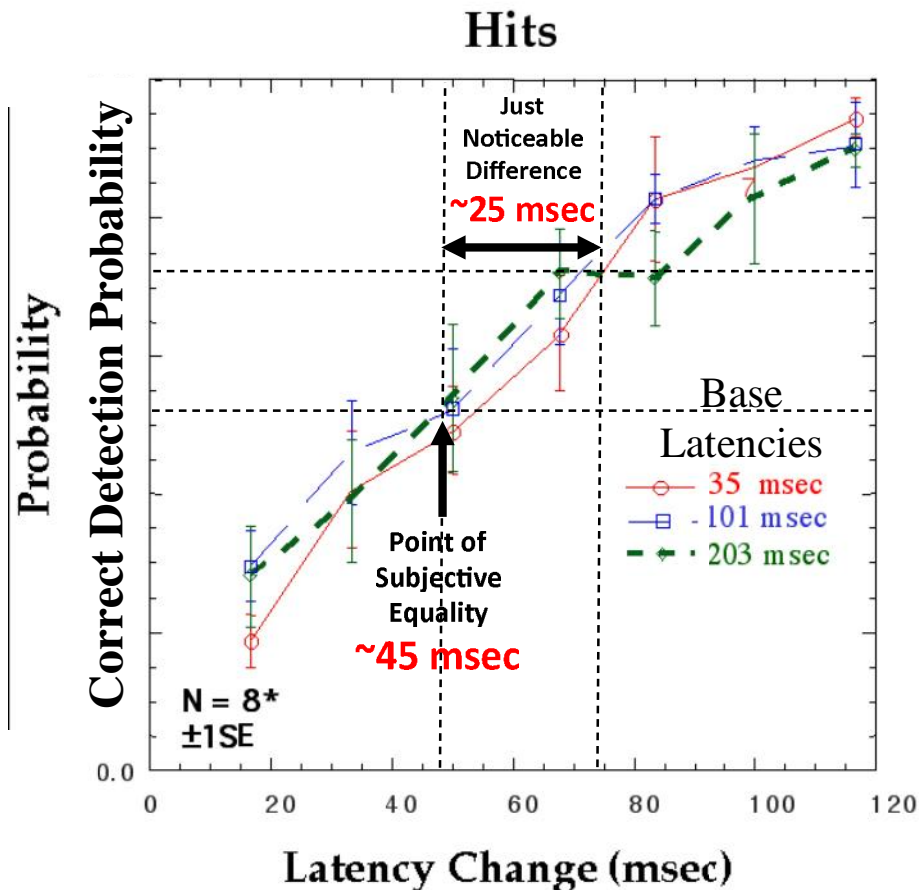
		$t$	$t+n\Delta t$
1st Condition	$t+n\Delta t$	.125	.375
	$t$	.375	.125

Catch trials

(Ellis, Young, Ehrlich, & Adelstein, 1999)

# Observer Detection of Changes of Latency during Paced Hand Movement of Virtual Objects

No Webers Law:  $\Delta t_i/t_i$  not constant!

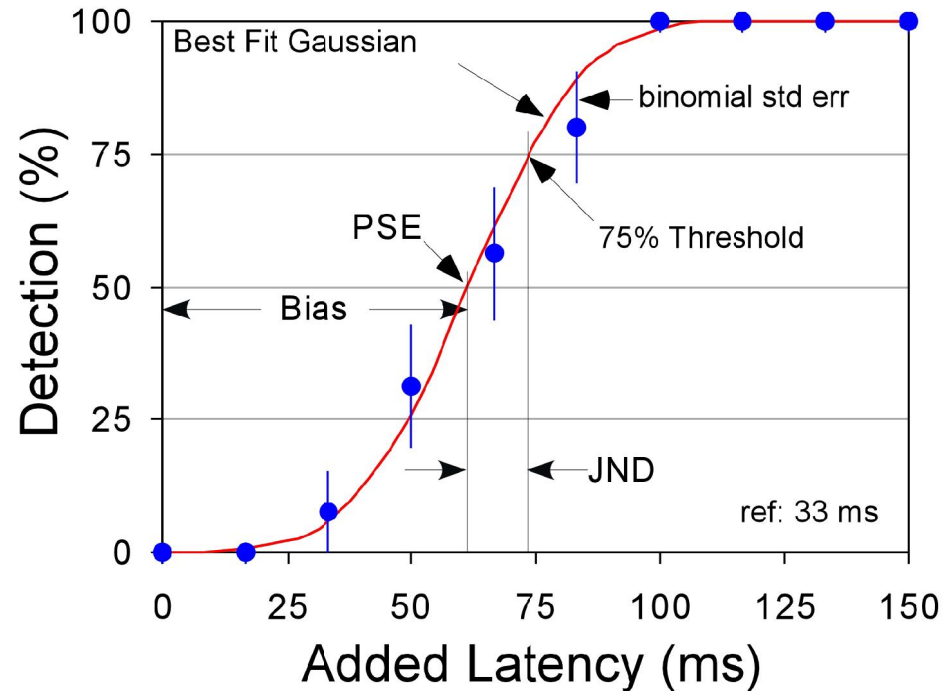


\*Practiced observers using an occluding HMD

Ellis, Stephen R. , Young, Mark J. , Ehrlich, Sheryl M., and Adelstein, Bernard D. (1999) Discrimination of changes of latency during voluntary hand movement of virtual objects. Proceedings of HFES. pp. 1182-1186.

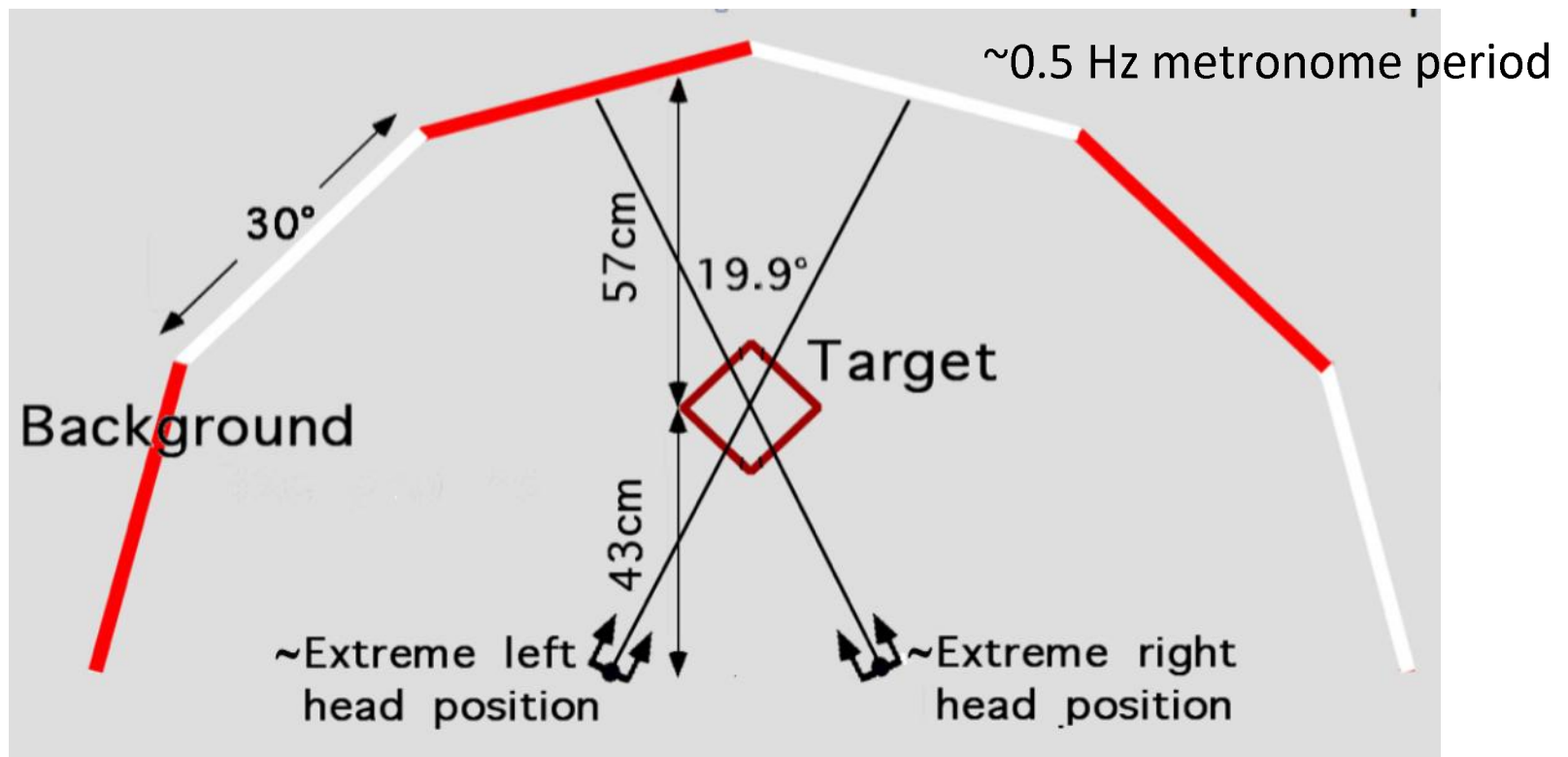
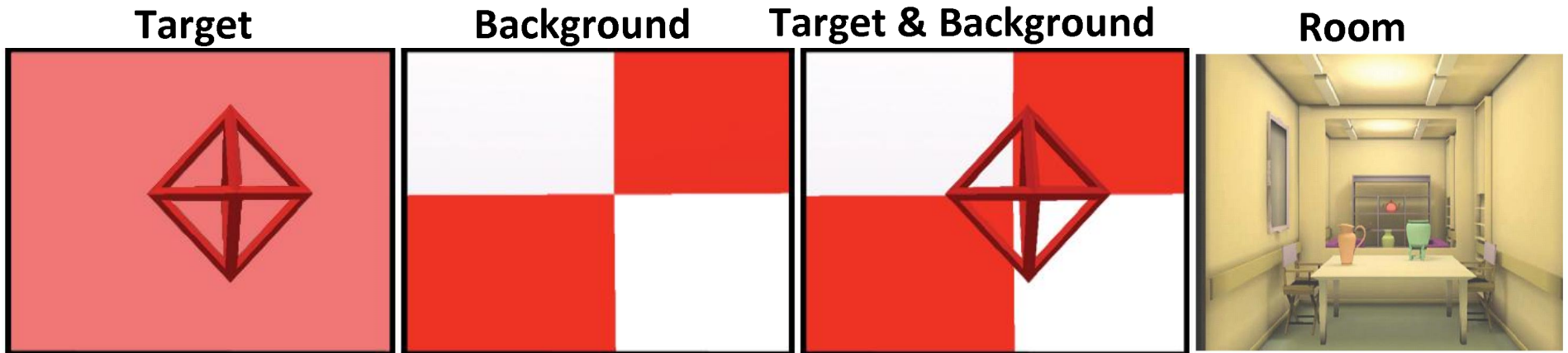
# Latency Detection One Subject Making Head Rotations

## Data Analysis Procedure

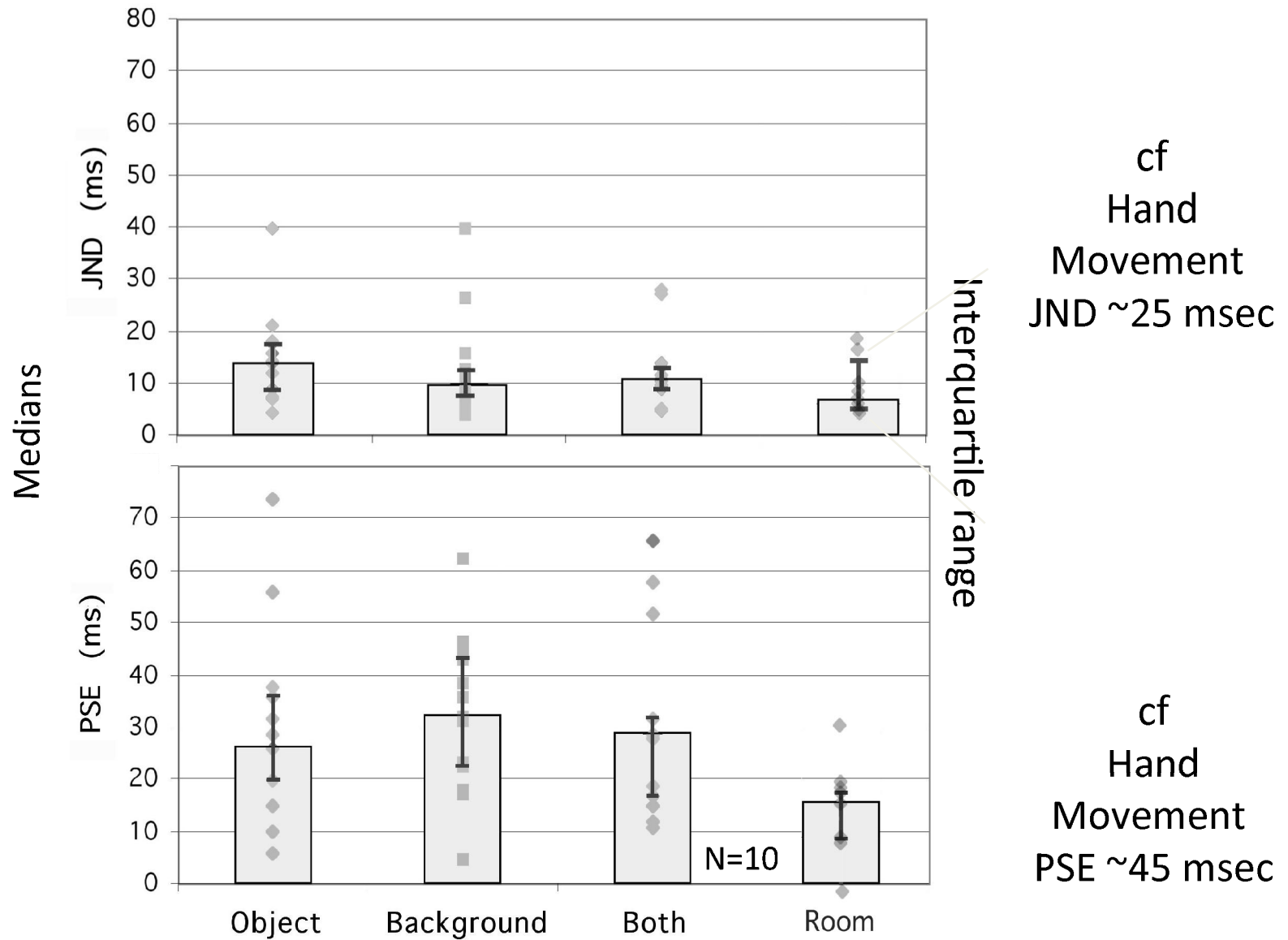


- Accumulated responses from 10 ascending 10 descending runs
- Probit Analysis → Gaussian Quartiles → PSE & JND

# Latency Discrimination During Head Movement: Graphic Models



# Latency Discrimination during Head Movement





# HIGH RESOLUTION: WHERE ARE WE?

DK1 100% overlap  
640x480 @ 110 degrees  
~6 pixels / degree

DK2  
960x1080 @ 100 degrees  
~10 pixels / degree

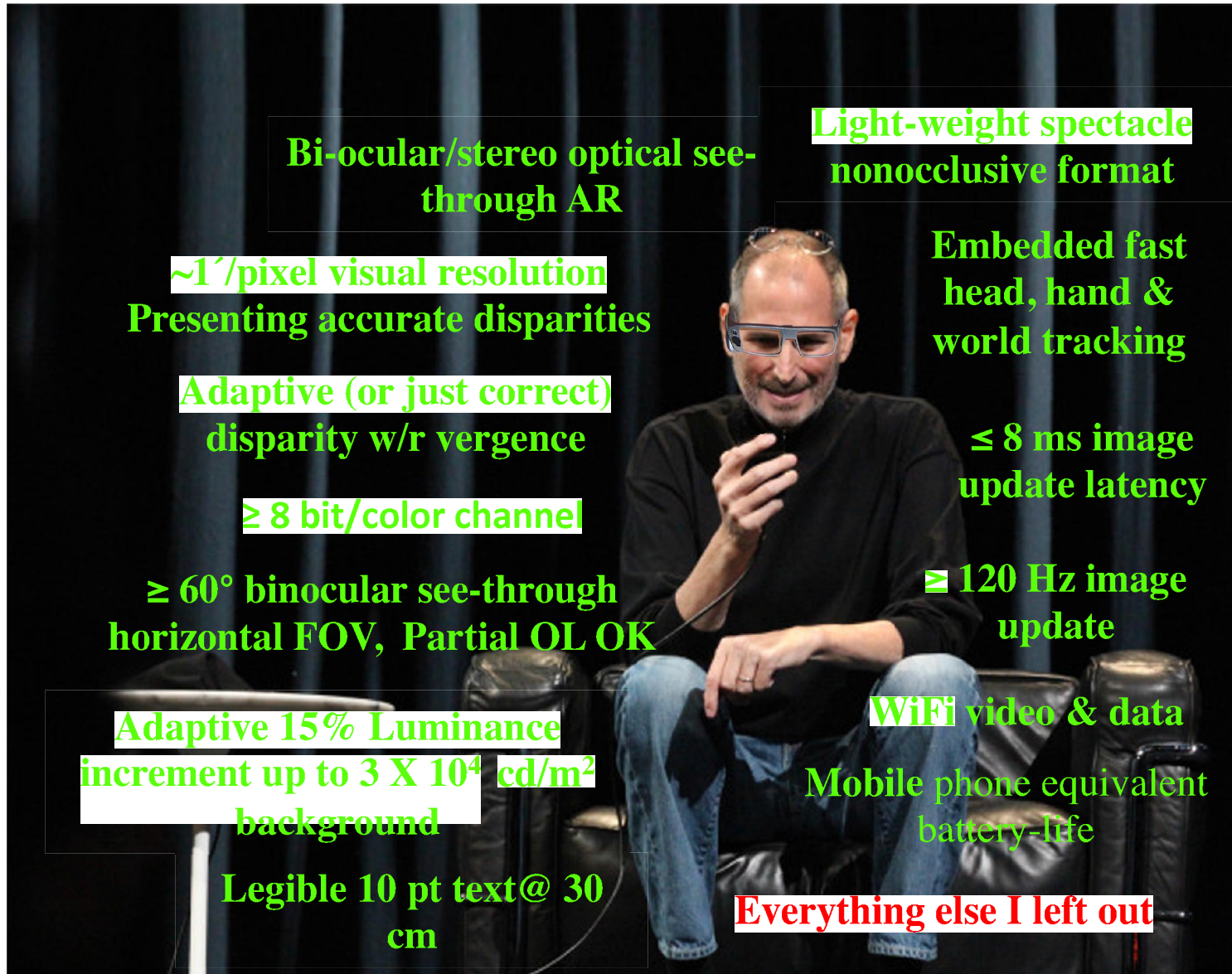
100% overlap Vive  
1080x1200 @ 105 degrees  
~10 pixels / degree

VRelia Pro G1  
1920x1080 @ 123 degrees  
~15 pixels / degree

Sony Morpheus

Courtesy and after Mark Miné, Dir. Disney, Disney Research

# Some Imagined Performance Specs for HMDs but especially for dream Augmented Reality



**Bi-ocular/stereo optical see-through AR**

**Light-weight spectacle nonocclusive format**

**~1' / pixel visual resolution**  
**Presenting accurate disparities**

**Embedded fast head, hand & world tracking**

**Adaptive (or just correct) disparity w/r vergence**

**≤ 8 ms image update latency**

**≥ 8 bit/color channel**

**≥ 60° binocular see-through horizontal FOV, Partial OL OK**

**≥ 120 Hz image update**

**Adaptive 15% Luminance increment up to  $3 \times 10^4$  cd/m<sup>2</sup> background**

**WiFi video & data**

**Mobile phone equivalent battery-life**

**Legible 10 pt text @ 30 cm**

**Everything else I left out**