LEO (below 3000 km)



Use and Protection of GPS Sidelobe Signals for Enhanced Navigation Performance in High Earth Orbit

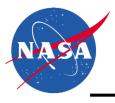
Joel J. K. Parker, Jennifer E. Valdez, Frank H. Bauer, Michael C. Moreau NASA Goddard Space Flight Center

39th Annual AAS Guidance, Navigation and Control Conference February 8, 2016

Main lobe



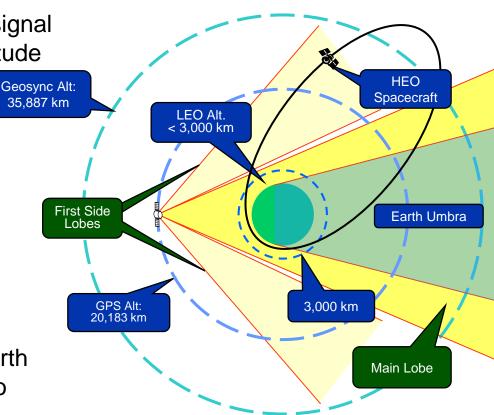
- Background
- Current GPS III SSV Requirements
- Protection of Aggregate Signal Availability
- GPS Usage in the SSV
- Analysis 1: GPS Performance Margin
- Analysis 2: GOES-R User Needs
- Proposed SSV Requirement Modification
- Conclusions



GPS Space Service Volume: Background

- GPS Space Service Volume (SSV) signal environment from 3,000–36,000 km altitude
- Current SSV specifications only capture performance provided by signals transmitted within 23.5° (L1) or 26° (L2/L5) off-nadir angle.
- Recent on-orbit data & lessons learned show **significant PNT performance improvements** when the full aggregate signal is used.
- Numerous military & civil operational missions in High & Geosynchronous Earth Orbit (HEO/GEO) utilize the full signal to enhance vehicle PNT performance





1978 1997 2005 2010 2017 1989 2020s Block IIR Block IIR-M First Block I Block IIF Block IIA Block IIIA Block IIIB launched (LM)(LM)(Boeing) (Boeing) (LM)3



| I. Availability |
|-----------------|
|-----------------|

| | HEO SSV (8,000–36,000 km alt.) | | | | |
|-------|--------------------------------|------------|---------------------|--|--|
| | 1+ Signals | 4+ Signals | Max Outage (min) | | |
| L1 | ≥ 80% | ≥ 1% | 108 | | |
| L2/L5 | ≥ 92% | ≥ 6.5% | 84 | | |

II. Received Signal Power

III. Pseudorange Accuracy

Accuracy $\leq 0.8 \text{ m} \text{ (rms)}$

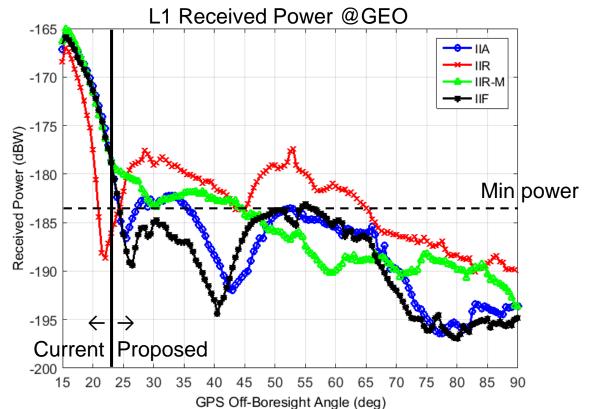
| | SSV Min. | Reference |
|----------|-------------------------|--------------------------|
| Signal | Received Power (dBW) | off-nadir angle (deg) |
| L1 C/A | -184.0 | 23.5 |
| L1 P(Y) | -187.0 | 23.5 |
| L1C | -182.5 | 23.5 |
| L1 M | -183.5 | 23.5 |
| L2C | -183.0 | 26 |
| L2 P(Y) | -186.0 | 26 |
| L2M | -182.5 | 26 |
| L5 (I/Q) | -182.0 | 26 |

Defer

COV Min

Protection of Aggregate Signal Availability

- By utilizing sidelobes, missions are benefiting from significantly enhanced on-orbit performance
 - At nearly 2x GEO altitude, MMS sees nearly 100% availability of 4 GPS signals
- Average received power at GEO shows significant variations in sidelobes between Block II designs



- Because full signal isn't specified, future GPS blocks could suppress sidelobes and severely impact future HEO/GEO mission performance.
- To address this risk, NASA is proposing a modification to the current SSV requirements to capture user-required availability

Data from GPS ACE project

Current and Potential Future Missions Employing GPS in SSV HEO/GEO Segment

Rationale for GPS use in SSV:

- Significantly improves vehicle navigation performance (from: km-class to: meter-class)
- Supports quick trajectory maneuver recovery (from: 5-10 hours to: minutes)
- GPS timing reduces need for expensive on-board clocks (from: \$1M-500K to: \$50K)
- Supports **increased satellite autonomy**, lowering mission operations costs (savings from: \$0 to: \$500-750K/year)

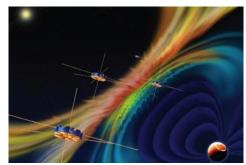
Mission Types include:



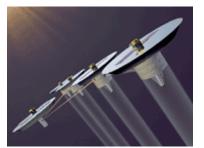
Earth Weather Prediction using Advanced Weather Satellites



Direct Injection Launch Vehicle Upper stages & Deep Space Enroute & Return



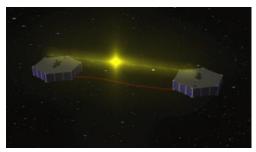
Space Weather Observations



Formation Flying & Constellation Missions



Solar Occultation Observations



Closer Spacing of Satellites in Geostationary Arc

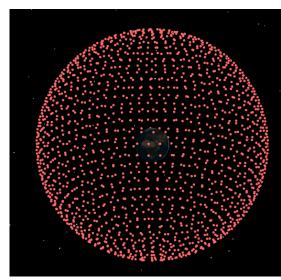


GPS Performance Margin Analysis

- Goal: Determine on-orbit minimum performance margin over current requirement, considering full signal
- Assumptions:
 - 27-satellite constellation, Block IIR-M GPS satellites
 - GPS IIR-M consistently lower-performing than IIR
 - High-fidelity data unavailable for IIA, IIF
 - Minimum GPS transmit power (derived from edge-of-Earth spec)
 - Minimum received power threshold equal to current requirement

Analysis approach:

- Global coverage analysis using STK 10
- 5° equatorial grid spacing (1652 points)
- Availability evaluated at 95% of points
- Availability analysis independent of pseudorange accuracy



STK Coverage Grid



Minimum constellation performance, 27 IIR-M SVs, full signal:

| | Signal | 1+ SV | 4+ SV | Max outage |
|------------------------------|--------|-------|-------|------------|
| | L1 | 100% | 92.6% | 0 min |
| Minimum IIR-M Performance | L2 | 99.2% | 77.4% | 9 min |
| Periormance | L5 | 99.2% | 78.6% | 8 min |
| Current Requirement | L1 | 80% | 1% | 108 min |
| | L2 | 92% | 6.5% | 84 min |
| | L5 | 92% | 6.5% | 84 min |
| Performance Margin | L1 | 20% | 91.6% | 108 min |
| | L2 | 7.2% | 70.9% | 75 min |
| | L5 | 7.2% | 72.1% | 76 min |

- Specification designed so all codes within each signal (C/A, P(Y), etc.) result in identical minimum availability
- Actual on-orbit performance of current constellation greatly exceeds minimums.
- 4+ SV availability shows greatest increase over CDD levels.

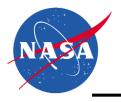


GOES-R User Needs Analysis

- Goals:
 - Updated SSV requirement must be based on user needs, not current performance
 - Derive SSV capabilities required by GOES-R, as representative HEO SSV user

• GOES-R

- NOAA/NASA Geostationary
 Operational Environmental Satellite
- GOES-R, -S, -T, -U: 4th generation operational weather satellites
- Launch: 2016, 20-year service life
- First series to use GPS for navigation
 - General Dynamics Viceroy-4 receiver
- Requirement: <120 min outage/year



GOES-R User Needs Analysis

GOES-R Requirements

- Orbit position knowledge requirement (right)
- All performance requirements are applicable during and after maneuvers.

| Parameter | Requirement (m, 1-sigma) |
|-------------|--------------------------|
| Radial | 33 |
| In-track | 25 |
| Cross-track | 25 |

- Error between 1 PPS & GPS time \leq 85 nanoseconds (1-sigma).
- Requirements unchanged for GOES-S, -T, -U

Analysis Approach

- GPS measurements to representative GOES-R orbit simulated using ODTBX
- Three types of maneuvers were simulated, placed at worst-case GPS availability times:

| Simulation Time | Maneuver Type | Direction | Duration (mins) | Thrust (N) |
|-----------------|---------------------|-------------|-----------------|------------|
| Day 1: 06:45:00 | N/S Station Keeping | Cross-Track | 45 | 0.5 |
| Day 2: 07:30:00 | Momentum Management | In-Track | 5 | 0.24 |
| Day 3: 07:00:00 | E/W Station Keeping | In-Track | 15 | 0.22 |

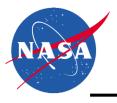
Measurements processed using GEONS EKF with varying levels of GPS signal availability (controlled via level of sidelobe contribution)



• Availability Results Summary:

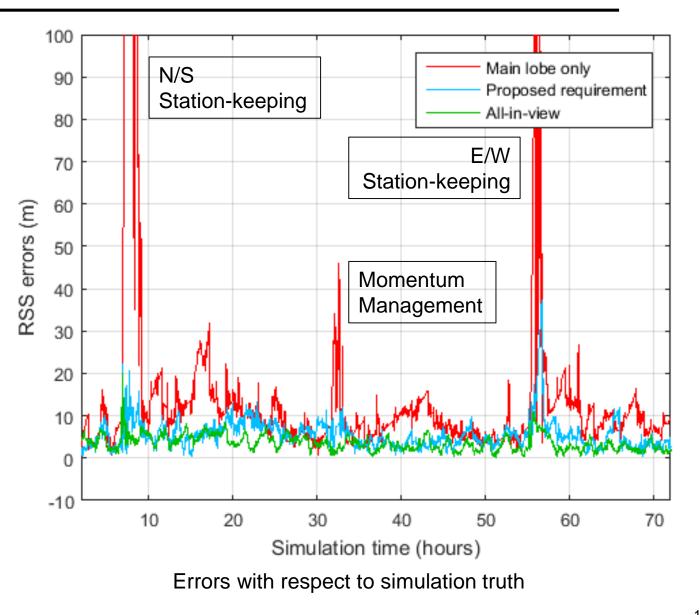
| Avail. [1+,4+] | Pass/Fail | Details |
|----------------|-----------|---|
| 80%, 2.5% | Fail | Fails positioning and stability requirements for all maneuvers, outages of up to 80 min |
| 96.75%, 20.5% | Fail | Fails positioning and stability requirements for all maneuvers |
| 98.75%, 32.3% | Pass | Passes with minimum required performance for N/S maneuver |
| 100%, 84.5% | Pass | Passes with very stable positioning during maneuvers |

- Additionally, at the 99% availability level, a pseudorange accuracy sensitivity analysis was performed
 - Pseudorange errors were increased from 2m to 5m until requirements were violated
 - Errors were applied to full signal (mainlobe and sidelobes)
 - 4m pseudorange accuracy caused nominal but acceptable requirements violations, given conservatism in analysis



GOES-R User Needs Analysis

- Only 1 SV in view necessary to recover solution
- At current required availability, post-maneuver errors exceed requirement in all cases, for up to 3 hours
- Proposed availability bounds errors within requirement





Proposed SSV Requirement Modification

- Proposed requirement adds a second availability specification, applicable at a less stringent pseudorange accuracy.
- Updated availability requirement (4m added, **0.8m unchanged**):

| | 0.8m rms accuracy | | | 4m rms accuracy | | |
|-------|-------------------|---------------|---------------------|-----------------|---------------|---------------------|
| | 1+ Signals | 4+ Signals | Max Outage (min) | 1+ Signals | 4+ Signals | Max Outage (min) |
| L1 | ≥ 80% | ≥ 1% | 108 | ≥ 99% | ≥ 33% | 10 |
| L2/L5 | ≥ 92% | ≥ 6.5% | 84 | ≥ 99% | ≥ 33% | 10 |

- MEO specification unchanged.
- Requirement captures GOES-R minimum capability with no margin.
- Applies to all signals, all codes.
- There remains significant margin in current minimum constellation performance, esp. in 4+ signal availability.
- Separate analysis indicates that 4m accuracy is realistic in sidelobes.



Conclusions & Next Steps

- Existing requirements for GPS signal availability in the SSV do not capture significant performance improvements when the full aggregate signal (mainlobe and sidelobes) is used.
- Without a specification, this **performance is at risk** of being reduced in future GPS designs, beginning in the 2030s.
- NASA has demonstrated:
 - significant existing availability margin for existing GPS Block II spacecraft, and anticipates similar performance for current Block IIIA signals
 - user requirements (GOES-R) that drive an updated SSV specification for HEO/GEO users
- NASA is working through the US Air Force Interagency Forum for Operational Requirements (IFOR) process to adopt the proposed requirement.
 - Process includes formal requirement specification, statement of user needs, and analysis of alternative solutions
 - Target for completion is **March**, **2016**
- If adopted, the proposed requirement will protect capabilities required by users today, and enable enhanced usage of GPS for navigation in HEO for the future.