# Laser Production for NASA's Global Ecosystem Dynamics Investigation (GEDI) Lidar

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#### **GEDI** Mission Overview

- NASA Earth Ventures Instrument (EVI) program
- \$90 M, cost capped, "PI-Led" mission
- Class C, 1-2 year mission
- Multi-beam waveform lidar instrument with 10 ground tracks
- Launch Vehicle: Space-X Falcon 9/Dragon or equivalent
- Platform: International Space Station,



- Orbit: 415 km average; 51.6 degrees
- Payload Allocations (TBR): 600 Kg., 887 W, 5.4 Mbps
- Science and Mission Operations Ground System, B.32 GSFC

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2015	2016	2	017	201	8	2019	2020
SRR 6-15	PDR 4-16	CDR 1-17	PER 8-17	PSR 5-18	LRD 8-18	Primary Mission: 365 Days of Science Collection	Extended Mission to Account for ISS Induced Downtime







# Characterize the effects of changing climate and land use on ecosystem structure and dynamics





GEDI provides the Earth's first comprehensive

and high-resolution data set of ecosystem structure







- Sole GEDI observable is the lidar waveform
  - Provide ground elevation, canopy height, canopy cover and various vertical profiles and metrics





# **GEDI Laser Ground Track Coverage**

- GEDI is selfcontained laser altimeter
- 3 lasers produce a total of 10 ground tracks
- Precise ranging, attitude & position sensors enable precise geo-location of each laser footprint (10-m knowledge)
- Active Pointing Control Mechanism (PCM) provides even distribution and complete coverage of ground tracks (225-m control)















ARYLN

#### **GEDI – Internal Views**













- HR = high reflective mirror
- TCL = thermal compensation lens
- TFP = thin film polarizer
- QS = Q-Switch
- 1/4 WP = 1/4 wave plate
- GRM = gradient (Gaussian) reflective mirror

- 1. HR mirror prescription change 2.5 mCC to 1.0 mCC
- 2. The TCL focal length is "adjusted" for each cavity or slab installed, to best match thermal lensing. (TCLs ordered at a range anyway)
- 3. Mini-BX added to adjust for change in divergence
- 4. Reduction in output power from 17 mJ to 10 mJ to maintain same damage margins
- 5. Reduction of power allocation from 50 W to 40 W







# HOMER Class Heritage and Philosophy



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# HOMER TRL-6 Performance Summary

Parameter	HOMER Output
Energy	20 - 15 mJ
Pulse Width	12 +/- 1 ns
Rep Rate	250 -100 Hz
LDA Current	48-80 A
LDA Derating	50%
TRL 6 Mass	6 kg
Total QS Shots HOMER Design	15+ Billion



<u>Single Mode Far Field Image</u> D<sub>x</sub>/D<sub>y</sub> = 0.99/0.96 mRad

Laser Settings:

- Diode Pulse = 65us
- I = 48 A (~55% derated)
- F = 241 Hz



Reported 01/06/2010 <u>HR mirror Near Field Image</u> W<sub>x</sub>/W<sub>y</sub> = 1.8/2.12 mm

#### Laser Output:

- E = 16 mJ
- Q-switch pulse ~11ns
- Fluence < 2.5 J/cm<sup>2</sup>







#### **GEDI** Laser Interface and Functional Overview





- Incorporating all opto-mechanical lessons learned from HOMER-2, LOLA, MLA, CALIPSO, DESDYNI, & ESA's ALADIN
- Modular design allows complete laser assembly, alignment, and substantial performance without the enclosure if necessary
- Preliminary leak rate, structural, and thermal analysis performed and will be tested





# **BDU Design Overview**





# Side Lobe Description Summary

A few rays at "top" of Y-axis travel a different path. This produces a clipping effect, or "lobe" at the slab output end.

This creates problems for science differentiating between sloped ground and tree height.

To remove this you can either:

- 1) Clip off the side lobes outside the cavity
- 2) Make the beam smaller
- 3) Make the slab bigger

All options were explored and GEDI selected option 2 by changing HR Mirror curvature.

Options were reviewed externally by NESC supervised laser team from 554, 562, and expert from NGS. See GEDI-LAS-REVW-0004









# Laser Testing Performance Summary

Parameter	Value	Unit
Average Energy	10.2	mJ
Frequency	242	Hz
Pump Width	71-77	μs
Current	55	А

10 mJ example beam with no side lobes from GEDI-LAS-RPT-0029

Parametric Testing :

- Thermal lensing
- Diode distance



• End mirror tolerance





#### ETU Diode Life Test Results





Energy measurements were corrected for the LDA temperature change. Efficiency of the LDA decreases as the temperature increases.







# GEDI Laser Requirements Verification

O = Occasional C = Continuous X = One Time Measurement

ID	Requirement	Values	FT	СРТ	Life test	Technique Used
1	Laser Wavelength	1064.5 nm ± 0.2 nm in vacuum		х	0	Pickoff beam. Use built in software to calibrate measurement for vac. Take vacuum and air values
2*	Laser Output Energy	10 mJ +5% fully captured beam at the output	х	x	С	Measuring Total Output Energy using energy meter with 10ms integration time. CPT - energy meter put at the end of the snout to get full output. Used to calibrate pickoff measurement as well FT/Lifetest - calibrated pickoff
3*	Far-Field Divergence of the Central Lobe	0.6 mrad ±0.08mrad 1/e <sup>2</sup> div.	x	x	С	Spiricon camera (raw beam data) 5-10 captures Computer Analysis and post processing for side lobes FT-50 cm lens CPT - Rayleigh Range
6	Laser Output Polarization Ratio	≥ 200:1		х	0	Measure by hand using wave-plate/hi ratio polarizer configuration
9	Pulse Repetition Rate	242 ± 2 Hz	x	х	С	Confirm pulse with Tektonix 2024C and use e-drive output reading for continuous measurement
10	Pulse Width	<16ns ns Full-width and half- max	x	x	С	FT- 200 MHz Oscilloscope Average of 16 captures of laser pulses CPT -2 GHz scope. High speed Oscilloscope compiling 10,000 shots with histogram through computer analysis and post processing. LMB will be measured as well.
12	Laser Pulse Energy Concentration in Far- Field Outside of Central Lobe	≤ 0.5% of 1/e <sup>2</sup> Central Lobe per energy concentration		x	0	Spiricon camera (raw beam data) 5-10 captures Computer Analysis and post processing
13*	Number of Laser Shots for Life Testing	3.2 billion shots	x	х	С	GSE shot counter will monitor shots for every test. ETU life time shot count will be monitored continuously
24	LDA Operating Temperature	35 +/- 2 °C		х	С	.Internal 10k thermistors read by EGSE
WYLN.						



Level of Assembly	
ltem	
Supplier	
Quantity	
Hardware Type	
Modal Survey	
trength - Design Loads (11)	
ne Survey (Sine Sweep)	Stru
Sine Vibration	otur
Random Vibration	
Mechanical Shock	acha
etrology/Dim Inspection	nical
Mechanical Function	
Life Tests	
Mass Properties	
Interface Tests	E
Conducted Emissions	EMI/I
Radiated Emissions	EMC
onducted Susceptibility Y	; & M
Self Compatibility	agne
agnetic Properties (AC) agnetic Properties (DC)	etics
Leak Test	The
Pressure Test	٦rm
Thermal Vacuum [# of Cycles]	al / \
Thermal Balance	/201
ermal Cycling - Ambient	m
Bakeout	(3)

- Environmental Testing performed on ETU and Flight units
  - ETU: Vibration, TVAC, EMC, and life test
  - Flight: Vibration, TVAC, EMI/C (at instrument level)
  - CPTs before and after each test (or specific cycles)
- Interface testing: BDU, LEU, DOE







#### Laser GSE Functional Diagram









#### **Optical Setup – Laser Lifetest w/BDU**













#### Laser Assembly Flow





#### Laser Assembly Flow









#### Laser ETU Bucket and Driver Assembly









#### Laser ETU Diode and Bench Assembly









#### **BDU ETU Assembly Test Configuration**









