

**Existence of periodically evolving convex  
curves moved by anisotropic curvature**

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# Existence of periodically evolving convex curves moved by anisotropic curvature

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## 1 Introduction.

This note reports our recent results [2] on the existence of time-periodic solution of curvature flow equations in the plane. The present paper includes a natural extension of results in [2].

Let  $\{\Gamma_t\}$  be a smooth one parameter family of closed embedded curves bounding a domain in the plane. Let  $\theta$  be the argument of the inward unit normal  $\mathbf{n}$  of  $\Gamma_t$ . The normal velocity of  $\Gamma_t$  in the direction of  $\mathbf{n}$  denotes  $V$ . We consider an equation of  $\Gamma_t$  of the form

$$V = a(\theta)k - Q(\theta, t), \quad (1)$$

where  $k$  is the inward curvature of  $\Gamma_t$  and  $a$  and  $Q$  are given functions. Since  $\theta$  is argument,  $a$  and  $Q$  are assumed to be  $2\pi$ -periodic in  $\theta$ , i.e.,  $a(\theta + 2\pi) = a(\theta)$  and  $Q(\theta + 2\pi, t) = Q(\theta, t)$ . We assume that  $a$  is strictly positive so that our problem is

parabolic.

**Existence Theorem.** Assume that  $Q$  is  $T$ -periodic in time, i.e.,  $Q(\theta, T + t) = Q(\theta, t)$  for all  $0 \leq \theta < 2\pi, t \in \mathbb{R}$ . Assume that  $a > 0$  and  $Q > 0$  is continuous with partial derivatives  $Q_{\theta\theta}, Q_t, Q_{\theta\theta t}$ . Assume that

$$Q_{\theta\theta} + Q > 0 \quad \text{for all } \theta \text{ and } t. \quad (2)$$

Then there are a constant vector  $c \in \mathbb{R}^2$  and a closed evolving curve  $\Gamma_t$  solving (1) and

$$\Gamma_{t+T} = \Gamma_t + c \quad \text{for all } t \in \mathbb{R}. \quad (3)$$

The curvature of  $\Gamma_t$  is always positive and the quantities in (1) is continuous. If  $Q$  is smooth, so is  $\Gamma_t$ .

This shows the existence of time-periodic solution of (1) when  $Q$  is time-periodic. Several examples of (1) are provided in [3] where a standard form of (1) for thermodynamics is derived. A general motion by anisotropic curvature is described as

$$V = \frac{1}{\beta(\theta)}((\sigma''(\theta) + \sigma(\theta))k - c(t)) \quad (4)$$

where  $\beta > 0$  is called a kinetic coefficient and  $\sigma > 0$  is called the surface energy density of material;  $c(t)$  is the temperature difference. Since the condition (2) is equivalent to say that the Frank diagram of  $Q(\cdot, t)$  has a positive curvature everywhere for  $Q > 0$ , our Existence Theorem yields:

**Corollary.** Assume that  $\beta > 0, \sigma > 0$  and  $c$  are continuous with the second derivative  $\sigma''$ . Assume that  $c$  is  $T$ -periodic and that the Frank diagram of  $\sigma$  and  $1/\beta$  has a positive curvature everywhere. Then there is a closed evolving curve  $\Gamma_t$  solving (4) which is  $T$ -periodic in the sense of (3). The curvature of  $\Gamma_t$  is always positive.

In our previous paper [2] these existence results are proved only for (1) with  $a \equiv 1$ . It turns out the method applies to general (1) with a small modification.

**Curvature evolution equations.** Since a solution  $\Gamma_t$  we seek is convex, we may use  $\theta$  as a coordinate to represent  $\Gamma_t$ . In  $\theta$ -coordinate evolution of curvature is described by

$$k_t = k^2(V_{\theta\theta} + V)$$

as in [3]. If  $\Gamma_t$  evolves by (1),  $k$  fulfills

$$k_t = k^2((ak)_{\theta\theta} + ak - (Q_{\theta\theta} + Q)) \quad (5)$$

Since  $\Gamma_t$  is closed,  $k$  fulfills the constraint

$$\int_0^{2\pi} \frac{e^{i\theta}}{k(\theta, t)} d\theta = 0. \quad (6)$$

Of course, since  $\theta$  is the argument of a normal,  $k$  is  $2\pi$ -periodic in  $\theta$ . As in [2] to show Existence Theorem it suffices to find a positive  $T$ -periodic solution  $k$  of (5), (6) with  $2\pi$ -periodicity in  $\theta$ . To simplify the notation we set

$$\mathbb{T} = \mathbb{R}/2\pi\mathbb{Z} \quad \text{and} \quad K = \mathbb{T} \times (\mathbb{R}/T\mathbb{Z}).$$

By  $h \in C(K)$  we mean that  $h$  is continuous in  $\mathbb{R}^2$  and that  $h(x, t)$  is  $2\pi$ -periodic in  $x$  and  $T$ -periodic in time  $t$ . As in [2], the following existence result implies the existence of  $k$  satisfying (5), (6) by setting  $Q_{\theta\theta} + Q = f$ ,  $\theta = x$ ,  $k = w$  and it yields our Existence Theorem.

**Theorem 1.** Assume that  $a \in C(\mathbb{T})$  is positive. Assume that  $f \in C(K)$  with  $f > 0$  and  $f_t \in C(K)$  satisfies

$$\int_0^{2\pi} f(x, t) e^{ix} dx = 0 \quad \text{for all } t \in \mathbb{R}. \quad (7)$$

Then there is a positive solution  $w \in C(K)$  ( with  $aw \in \bigcap_{p>1} W_p^{2,1}(K)$  )

$$w_t = w^2((aw)_{xx} + aw - f) \quad \text{in } K \quad (8)$$

satisfying

$$\int_0^{2\pi} \frac{e^{ix}}{w(x,t)} dx = 0 \quad \text{for all } t \in \mathbb{R}. \quad (9)$$

Here  $W_p^{2,1}$  denotes  $L^p$  - Sobolev space of order 2 in  $x$ , 1 in  $t$ .

If we set  $u = aw$ ,  $u$  solves

$$au_t = u^2(u_{xx} + u - f).$$

The outline of the proof of Theorem 1 is the same as that of the Main Existence Theorem in [2] where  $a$  is assumed to equal one. Instead of presenting a whole proof, we point out necessary alternations when  $a$  depends on space variable  $x$ .

The main idea is to get a priori lower and upper bounds for approximate penalized equations admitting a solution. The penalty method applies to recover constraint (9).

The biography of [2] includes many references to recent work on equations of form

$$u_t = u^\gamma(u_{xx} + g(u, x, t)), \quad \gamma \geq 1$$

where  $g$  is a given function. We do not repeat it again here.

## 2 Harnack type inequalities.

In this section, we consider the equation

$$au_t = u^\gamma\{u_{xx} + g(u, x, t)\} \quad \text{in } K, \quad (10)$$

where  $\gamma \in \mathbb{R}$  and  $a$  is a continuous positive function on  $K$  with  $a_t \in C(K)$ .

Putting  $z = u_t/u$ , we have

$$z_x = \frac{u_{xt}}{u} - \frac{u_x u_t}{u^2},$$

$$z_{xx} = \frac{u_{xxt}}{u} - \frac{2u_x z_x}{u} - \frac{u_{xx} u_t}{u^2}.$$

Differentiating  $az = u^{\gamma-1}(u_{xx} + g)$  in  $t$  yields

$$az_t = u^\gamma z_{xx} + 2u^{\gamma-1} u_x z_x + \gamma a z^2 + \{u^{\gamma-1}(g_u u - g) - a_t\}z + u^{\gamma-1} g_t.$$

Let  $(x_0, t_0)$  be a minimizer of  $z$  over  $K$ . Then we have

$$\gamma a z^2 + \{u^{\gamma-1}(g_u u - g) - a_t\}z + u^{\gamma-1} g_t \leq 0 \quad \text{at } (x_0, t_0)$$

and hence

$$z \geq -u^{\gamma-1} \frac{(g_u u - g)_+}{\gamma a} - \frac{(a_t)_+}{\gamma a} - u^{\frac{\gamma-1}{2}} \frac{|g_t|^{1/2}}{(\gamma a)^{1/2}} \quad \text{at } (x_0, t_0).$$

Such differential identity is obtained for (8) with  $a = 1, f = 0$  by Gage [1]. Inequalities of Harnack type in time direction (Lemma1) and in space direction (Lemma2) follow from this estimate of  $\min_K z$  as in [2, §2].

**Lemma 1.** Assume that  $\gamma \geq 1$  and  $\alpha \geq 0$ . Suppose that there are positive constants  $c_0, c_1, c_2$  such that

$$v g_v(v, x, t) - g(v, x, t) \leq c_0, |g_t(v, x, t)|^{1/2} \leq c_1 \quad (11)$$

for all  $(v, x, t) \in (\alpha, \infty) \times K$  and  $\max_K u \geq c_2$  for each positive solution  $u$  of (10). Then there exists  $C = C(c_0, c_1, c_2, \max_K a, \min_K a, \max_K |a_t|, \gamma) > 0$  such that for each solution  $u$  of (10) with  $u > \alpha$

$$u(x, t) \leq u(x, s) \exp(-CM^{\gamma-1}(t-s)) \quad (12)$$

for all  $(x, t), (x, s) \in K$  with  $s - T \leq t \leq s$ , where  $M = \max u$ .

**Lemma 2.** Assume that  $\gamma \geq 1, \alpha \geq 0$  and (11) for  $g$ . If  $u$  is a solution of (10) with  $u > \alpha$ , then

$$u(x, t_0)^\gamma \geq M^\gamma - \frac{\gamma C_M}{2} (x - x_0)^2 \quad \text{in } K,$$

where

$$C_M = \frac{c_0}{\gamma} M^{\gamma-1} + \frac{\max(a_t)_+}{\gamma} + \frac{c_1(\max a)^{1/2}}{\gamma^{1/2}} M^{\frac{\gamma-1}{2}} + M^{\gamma-1} g_M,$$

$$g_M = \max\{(g(v, x, t))_+; \alpha < v < M, (x, t) \in K\}.$$

$$M = \max_K u = u(x_0, t_0),$$

### 3 Upper bounds.

We shall obtain an a priori upper bound for positive smooth solutions of

$$au_t = u^\gamma \{u_{xx} + \varphi(u)(u + \psi(x, u) - f(x, t))\} \quad \text{in } K, \quad (13)$$

where  $\varphi, \psi$  are smooth functions on  $(0, \infty), \mathbb{T} \times (0, \infty)$ , respectively. Here and hereafter,  $a \in C(K)$  is assumed to be time independent. This equation corresponds to the equation (3.1) in [2], in which  $\psi$  is independent of  $x$ . The dependence of  $\psi$  on  $x$  has no effect on proofs in the rest of this paper.

**Lemma 3.** Suppose that  $\psi \geq 0, f \geq 0$  and  $0 \leq \varphi \leq c_3, v - \varphi(v)v \leq c_4$  on  $(\alpha, \infty)$  with  $\alpha > 0$  for some positive constants  $c_3$  and  $c_4$ . Then for each solution  $u \in C^\infty(K)$  of (13) with  $u > \alpha$

$$\int \int_K u dx dt \leq 2\pi T(c_3 \|f\|_\infty + c_4) \equiv C_1$$

$$\int \int_K \frac{u_t^2}{u^\gamma} dx dt \leq \frac{c_3 C_1 \|f_t\|_\infty}{\min a} \equiv C_2.$$

**Proof.** The first inequality is obtained in the same way as the proof of Lemma 3.1 in [2]. Multiplying  $u_t/u^\gamma$  with (13) and integrating over  $K$  yields

$$\int \int_K a \frac{u_t^2}{u^\gamma} dx dt = - \int \int_K \varphi(u) u_t f dx dt = \int \int_K \Phi(u) f_t dx dt,$$

where

$$\Phi(s) = \int_0^s \varphi(r) dr \quad \text{for } s \in \mathbb{R}.$$

We thus have

$$\int \int_K a \frac{u_t^2}{u^\gamma} dx dt \leq c_3 C_1 \|f_t\|_\infty.$$

This implies the second inequality.  $\square$

Lemmas 2 - 3 yield the following theorem.

**Theorem 2.** Suppose that  $1 \leq \gamma < 3$  and  $\alpha > 0$ . In addition to the hypotheses in Lemma 3, assume that

$$\varphi'(v)(\psi(x, v) - f) + \varphi(v)\psi'(v) \leq 0,$$

$$0 \leq \varphi'(v)v^2 \leq c_5, \varphi(v)(\psi(x, v) - \min_K f) \leq c_6(v + 1)$$

on  $\mathbf{T} \times (\alpha, \infty)$  for some constants  $c_5, c_6 > 0$ . Then there is a positive constant  $M_0$  depending only on  $c_j (3 \leq j \leq 6), T, \|f\|_\infty, \|f_t\|_\infty, \gamma, \min_{\mathbf{T}} a$  such that  $\max_K u \leq M_0$  for each solution  $u \in C^\infty(K)$  with  $u > \alpha$ .

#### 4 Lower bounds.

We consider the equation

$$au_t = u^2 \{u_{xx} + \varphi_\epsilon(u)(u + \psi_\epsilon(x, u) - f_\epsilon)\} \quad \text{in } K \quad (14)$$

in this section. To get a positive lower bound for positive smooth solutions of (14), we investigate the stationary problem

$$U_{xx} + U = F \quad \text{in } \mathbf{T}. \quad (15)$$

The coefficient  $a$  clearly gives no effect when we treat the stationary problem.

The following lemma is a key as in [2].

**Lemma 4.** Let  $b \in \mathbf{R}$  and  $d > 0$ . Suppose that  $V \geq 0$  on  $(b, b + d)$ ,  $V \not\equiv 0$  and  $V_x$  is Lipschitz continuous on  $[b, b + d]$ . If  $V_{xx} + V \geq 0$  on  $(b, b + d)$  with  $V(b) = V_x(b) = 0$  and  $V(b + d) = 0$ , then  $d > \pi$ .

Let  $\{\mu_\varepsilon^\pm\}_{\varepsilon \geq 0}$  be a sequence of positive functions on  $\mathbb{T} \times (0, \infty)$  such that  $\mu_\varepsilon^\pm(x, \cdot)$  is nonincreasing for each  $x \in \mathbb{T}$  and  $\mu_\varepsilon^\pm \rightarrow \mu_0^\pm$  in  $\mathbb{T} \times (0, \infty)$  as  $\varepsilon \rightarrow 0$ . Suppose that  $\mu_\varepsilon^- \rightarrow \mu_0^-$  uniformly in every compact subset of  $\mathbb{T} \times (0, \infty)$  as  $\varepsilon \rightarrow 0$ . Let  $\{h_\varepsilon^-\}_{\varepsilon \geq 0}$  be a sequence in  $L^\infty(0, \infty)$  with  $0 \leq h_\varepsilon^- \leq 1$  such that  $h_\varepsilon^- \rightarrow h_0^- \equiv 1$  uniformly in every compact subset in  $\mathbb{T} \times (0, \infty)$  as  $\varepsilon \rightarrow 0$ . Put  $h_\varepsilon^+ \equiv 1$  for all  $\varepsilon \geq 0$ . For a positive function  $U$  on  $\mathbb{T}$  and  $\varepsilon \geq 0$ , we set

$$A_\varepsilon^\pm(\zeta, U) = \int_0^{2\pi} \sin_\pm(x - \zeta) \mu_\varepsilon^\pm(x, U) h_\varepsilon^\pm(U) dx \quad \text{for } \zeta \in \mathbb{R},$$

where  $\sin_+ z = \max(\sin z, 0)$  and  $\sin_- z = -\min(\sin z, 0)$ .

The following lemma is the same as Lemma 4.2 in [2] except for the dependence of  $\mu_\varepsilon^\pm$  on  $x \in \mathbb{T}$ , which does not affect the proof.

**Lemma 5.** Assume that there are positive constants  $k_j$  ( $0 \leq j \leq 4$ ) such that for each positive solution  $U \in C^2(\mathbb{T})$

- i)  $0 \leq F \leq k_0$ , where  $F = U_{xx} + U$
- ii)  $k_1 \leq \max U \leq k_2$ ,
- iii)  $A_\varepsilon^-(\zeta, U) \leq k_3 A_\varepsilon^+(\zeta, U) + k_4$  for all  $\zeta \in \mathbb{R}$ .

Suppose that

$$\int_0^1 \mu_0^-(x^2) dx = \infty.$$

Then there are positive constants  $\delta_0, \varepsilon_0$  depending only on  $k_j$ 's and  $\{\mu_\varepsilon^\pm\}, \{h_\varepsilon^-\}$  such that  $\min_{\mathbb{T}} U \geq \delta_0$  for each positive solution  $U \in C^2(\mathbb{T})$  of (15) and  $0 \leq \varepsilon \leq \varepsilon_0$ .

The following is the same as Lemma 4.4 in [2].

**Lemma 6.** If  $u \in C(K)$  satisfies (12), then there are  $\lambda, \Lambda > 0$  depending only on  $C, \gamma, M, T$  such that

$$\lambda u(x, t) \leq U(x) \leq \Lambda u(x, t) \quad \text{for } (x, t) \in K,$$

where  $U(x) = \int_0^T u(x, t) dt$ .

Lemma 5.3 in [2] remains valid even if  $\psi_\varepsilon(u)$  is replaced by  $\psi_\varepsilon(x, u)$  as stated below.

**Lemma 7.** Assume that  $f_\varepsilon \in C^\infty(K)$  satisfies (7). If  $0 \leq \varphi_\varepsilon \leq 1$  and  $1 - \varphi_\varepsilon(v) \leq c_7 \varepsilon^2 v^{-1}$  for  $v > \varepsilon^2$  with some positive constant  $c_7$ , then

$$\left| \int \int_K \{ \varphi_\varepsilon(u) \psi_\varepsilon(x, u) + (1 - \varphi_\varepsilon(u)) f_\varepsilon \} \sin(x - \zeta) dx dt \right| \leq 4T c_7 \varepsilon^2 \quad (16)$$

for each solution  $u \in C^\infty(K)$  of (14) with  $u > \varepsilon^2$  and  $\zeta \in \mathbb{R}$ .

Using Lemmas 5-7, we can prove our lower bound theorem in the same way as the proof of Theorem 5.7 in [2].

**Theorem 3.** Assume that  $f_\varepsilon \in C^\infty(K)$  satisfies (7) with  $f_\varepsilon > 0$  and that  $\varphi_\varepsilon, \psi_\varepsilon$  fulfill

$$0 \leq \varphi_\varepsilon(v) \leq 1, 0 \leq \varphi_{\varepsilon v}(x, v) \leq 2, \varepsilon^2 \leq 2v(1 - \varphi_\varepsilon(v)) \leq 2\varepsilon^2 \leq 2 \quad \text{for } v > \varepsilon^2$$

$$\min_{\varepsilon > 0} \min_K (f_\varepsilon - \psi_\varepsilon(x, v)) > 0, \psi_{\varepsilon v}(x, v) \leq 0, \quad \text{for } v > \varepsilon^2, x \in \mathbb{T}.$$

Then there are positive constants  $\varepsilon_0, \delta_0$  depending only on  $T, \|f\|_\infty, \|f_t\|_\infty, \min_K f_\varepsilon, \min_{\mathbb{T}} a, \max_{\mathbb{T}} a$  such that  $\min_K u \geq \delta_0$  for each solution  $u \in C^\infty(K)$  of (14) with  $u > \varepsilon^2$  and  $0 < \varepsilon \leq \varepsilon_0$ .

## 5 Existence of periodic solutions.

We start with approximate equations

$$aw_t = (w + \varepsilon^2)^2 \left\{ w_{xx} + \frac{w^2}{(w + \varepsilon^2)^2} \left( w + \frac{\varepsilon a}{\xi_\varepsilon(x, aw + \varepsilon^2)} - f \right) \right\} \quad \text{in } K, \quad (17)$$

where  $a \in C^\infty(\mathbb{T}), f \in C^\infty(K), \xi_\varepsilon : \mathbb{T} \times (0, \infty) \rightarrow (0, \infty)$  is a smooth function such that  $\xi_\varepsilon(x, \cdot)$  is nondecreasing for every  $x \in \mathbb{T}$ ,

$$\xi_\varepsilon(x, v) = v \quad \text{for } v \geq m\varepsilon a, x \in \mathbb{T},$$

$$v \vee (m\epsilon a) \leq \xi_\epsilon(x, v) \leq l(v \vee (m\epsilon a)) \quad \text{for } v \geq 0, x \in \mathbf{T}$$

with some  $1 < l < 2$  and

$$\min_K f - \frac{1}{m} \geq \frac{1}{2} \min_K f.$$

To solve (17), we need the following fact, in which the coefficient  $a(v)$  of  $v_{xx}$  in Lemma 6.1 in [2] is replaced by  $a(v, x, t)$  and we can prove in the same way as the proof of Lemma 6.1

**Lemma 8.** Assume that  $b$  is a positive constant and that  $a$  is a continuous function on  $\mathbf{R} \times K$  such that  $a(\sigma, x, t) \geq a_0$  for all  $\sigma \in \mathbf{R}$  on  $K$  with some positive constant  $a_0$ . Then for each  $h \in C(K)$  there exists a unique solution  $v \in \bigcap_{q>1} W_q^{2,1}(K) \subset C(K)$  of

$$v_t = a(v, x, t)(v_{xx} - bv + h) \quad \text{in } K.$$

Moreover the solution operator  $h \mapsto v$  is a continuous, compact operator from  $C(K)$  into itself. There are positive constants  $\theta_0, C_0$  depending only on  $a_0, \|h\|_\infty, b, T, \sup_K a$  such that

$$\|v\|_{W_p^{2,1}} \leq C_0 \|h\|_\infty \quad \text{for } 2 \leq p \leq 2 + \theta_0, h \in C(K).$$

Take  $b > 0$  such that

$$\phi(w, x, t) = bw_+ + \frac{(w_+)^2}{(w_+ + \epsilon^2)^2} \left( w_+ + \frac{\epsilon a}{\xi_\epsilon(x, aw + \epsilon^2)} - f \right) \geq 0$$

for all  $w \in \mathbf{R}, (x, t) \in K$  and  $\phi > 0$  if  $w > 0$ . For this  $b$  let  $S$  be the solution operator of

$$av_t = (v_+ + \epsilon^2)^2 (v_{xx} - bv + h) \quad \text{in } K,$$

which is well-defined by Lemma 8. Lemma 8 also yields;

- i)  $S$  is a continuous compact operator from  $C(K)$  into itself,
- ii)  $S(h)$  is Hölder continuous on  $K$  for  $h \in C(K)$ .

By standard regularity theory and maximum principle, we see that each fixed point of  $S \circ \phi$  in  $C(K)$  is a positive smooth solution of (17).

We can calculate values of the Leray-Schauder degree in a large and a small ball in  $C(K)$  in the same way as in Lemmas 6.3, 6.4 in [2].

**Lemma 9.** There is  $r_0 > 0$  such that the degree of  $I - S \circ \phi$  of the value zero in  $B_r(0)$  equals one, i.e.,

$$\deg(I - S \circ \phi, B_r(0), 0) = 1$$

for  $0 < r < r_0$ .

**Lemma 10.** There is  $R_0 > 0$  such that

$$\deg(I - S \circ \phi, B_R(0), 0) = 0 \quad \text{for } R > R_0.$$

We sketch proof of Theorem 1.

**Proof of Theorem 1.** Choose an approximate sequence  $\{a_\varepsilon\} \in C^\infty(\mathbb{T})$  and  $\{f_\varepsilon\} \in C^\infty(K)$  satisfying (7) such that

$$a_\varepsilon \rightarrow a \text{ in } C(\mathbb{T}), f_\varepsilon \rightarrow f, f_{\varepsilon t} \rightarrow f_t \text{ in } C(K) \text{ as } \varepsilon \rightarrow 0.$$

From Lemmas 9, 10, for each  $\varepsilon > 0$  there exists a positive solution  $v_\varepsilon \in C^\infty(K)$  of (17) with  $a = a_\varepsilon$  and  $f = f_\varepsilon$  for each  $\varepsilon > 0$ . Putting  $u_\varepsilon = v_\varepsilon + \varepsilon^2$ ,  $u_\varepsilon$  satisfies

$$a_\varepsilon u_t = u^2 \left\{ u_{xx} + \frac{(u - \varepsilon^2)^2}{u^2} \left( u + \frac{\varepsilon a_\varepsilon}{\xi_\varepsilon(x, u + \varepsilon^2)} - f_\varepsilon - \varepsilon^2 \right) \right\} \quad \text{in } K. \quad (18)$$

Setting

$$\varphi_\varepsilon(v) = \frac{(v - \varepsilon^2)^2}{v^2}, \psi_\varepsilon(x, v) = \frac{\varepsilon a_\varepsilon}{\xi_\varepsilon(x, v + \varepsilon^2)},$$

$\varphi_\varepsilon, \psi_\varepsilon$  satisfy the assumptions of Theorems 2, 3, so there are positive constants  $M_0, \delta_0, \varepsilon_0$  such that  $\delta_0 \leq u_\varepsilon \leq M_0$  on  $K$  for  $0 < \varepsilon < \varepsilon_0$ . Then we obtain a positive solution  $u$  of

$$a u_t = u^2 (u_{xx} + u - f) \quad (19)$$

as the limit of a subsequence of  $\{v_\varepsilon\}$  in  $W_p^{2,1}(K)$  with  $p > 2$ . It remains to prove the constraint (9) for  $w = u/a$ . Multiplying  $\sin(x - \zeta)/u^2$  with (19) and integrating over  $(0, 2\pi)$  yields

$$-\frac{d}{dt} \int_0^{2\pi} \frac{a}{u(x,t)} \sin(x - \zeta) dx = - \int_0^{2\pi} f \sin(x - \zeta) dx = 0$$

for all  $t, \zeta \in \mathbf{R}$ . Letting  $\varepsilon \rightarrow 0$  in (16), it follows that

$$\int \int_K \frac{a}{u} \sin(x - \zeta) dx dt = 0 \quad \text{for all } \zeta \in \mathbf{R}.$$

These imply that  $w = u/a$  satisfies the constraint (9). Therefore  $u$  is our desired solution of (19).  $\square$

## References

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