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**Subject:** submission of revised manuscript "Estimation of maize canopy properties from remote sensing by inversion of 1-D and 4-D models" to Precision Agriculture.

Dear Editor,

please find here enclosed the third revision of the paper "Estimation of maize canopy properties from remote sensing by inversion of 1-D and 4-D models", by R.Casa et al. modified according to the suggestions. We have incorporated all the editing suggestions and have remove citations from the Conclusions as requested. We have also deleted from the reference list the following references:

- Bonhomme, R., Varlet-Grancher, C., & Chartier, P. (1974). The use of hemispherical photographs for determining the leaf area index of young crops. *Photosynthetica*, 8, 299-301.
- Knyazikhin, Y., Martonchik, J. V., Diner, D. J., Myneni, R. B., Verstraete, M., Pinty, B., & Gobron, N. (1998). Estimation of vegetation leaf area index and fraction of absorbed photosynthetically active radiation from atmosphere-corrected MISR data. *Journal of Geophysical Research*, 103, 32239–32256.
- Makowski, D., Hillier, J., Wallach, D., Andrieu, B., & Jeuffroy, H.M. (2006). Parameter estimation for crop models. In D. Wallach, D. Makowski & J. W. Jones (Eds.), *Working with dynamic crop models* (pp. 101-149). Amsterdam: Elsevier.
- Myneni, R. B., Hoffman, S., Knyazikhin, Y., Privette, J. L., Glassy, J., & Tian, Y. (2002). Global products of vegetation leaf area and absorbed PAR from year one of MODIS data. *Remote Sensing of Environment*, 83, 214–231.

Figures are now provided as separate files with higher resolution.

We would be grateful if you could consider this paper for potential publication in the journal Precision Agriculture.

Best regards

Prof. Raffaele Casa  
corresponding author



# Estimation of maize canopy properties from remote sensing by inversion of 1-D and 4-D models

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**Abstract** The inversion of canopy reflectance models is widely used for the retrieval of vegetation properties from remote sensing. However the accuracy of the estimates depends on a range of factors, most notably the realism with which the canopy is represented by the models and the possibility of introducing *a priori* knowledge on canopy characteristics to constrain the inversion procedure. The objective of the present work was to compare the performances and operational limitations of two contrasting types of radiative transfer models: a classical one-dimensional canopy reflectance model, PROSPECT+SAIL (PROSAIL), and a three-dimensional dynamic (4-D) maize model. The latter introduces greater realism into the description of the canopy structure and implicit *a priori* information on the crop. The assessment was carried out with multiple view angle data recorded from field experiments on maize at stages V5 to V8. The simplex numerical optimization algorithm was used to invert the two models, using spectral reflectance data for PROSAIL and gap fraction data for the 4-D maize model. Leaf area index (LAI) was estimated with a RMSE of 0.48 for PROSAIL and 0.35 for the 4-D model. Retrieval of average leaf inclination angle (ALA) was problematic with both models. The effect of the number and distribution of observation view angles was examined, and the results highlight the advantage of oblique angle measurements.

**Keywords** Multiple-look-angle · PROSPECT · SAIL · PROSAIL · Leaf area index (LAI) · Leaf inclination distribution function (LIDF) · Average leaf inclination angle (ALA)

## 1 **Introduction**

2 Remote sensing at a range of spatial scales, from close range tractor-based sensors to those on  
3 satellite platforms allows non-intrusive and cost effective monitoring of crop status and of its  
4 spatial and temporal variation. Remote sensing observations should be capable of providing  
5 reliable and quantitative estimates of canopy biophysical properties, such as leaf area index  
6 (LAI), leaf angle distribution (LAD) and chlorophyll content ( $C_{ab}$ ). Knowledge of these  
7 variables can be useful for several applications, including site-specific crop management in  
8 precision agriculture, leading to more efficient use of inputs together with reduced  
9 environmental impacts.

10 The performances of such approaches, for example for nitrogen fertilizer management (Baret  
11 et al. 2007; Houlès et al. 2007), depend on the strength of the link between the remote sensing  
12 signals and biophysical variables such as canopy structure and leaf optical properties. They  
13 depend on the type of measurements made, which is defined by the spatial, spectral and  
14 directional sampling and their measurement accuracy, and also and on the methods of  
15 interpretation used.

16 Inversion of radiative transfer models can potentially estimate biophysical variables from  
17 remote sensing efficiently (Jacquemoud et al. 2000; Weiss et al. 2000) because local  
18 calibration is not required unlike the empirically based methods that use vegetation indices.  
19 However, several difficulties in the model inversion process limit the accuracy with which  
20 canopy properties can be retrieved. For example, different combinations of model input  
21 variables may result in similar simulations of reflectance that correspond closely to actual  
22 remote sensing observations (Baret et al. 2007). This arises from the generally ill-posed  
23 nature, in mathematical terms, of the inverse problem in remote sensing (Combal et al. 2002).  
24 Radiometric information alone is usually not sufficient to identify a unique solution.  
25 Therefore, the inverse problem needs to be stabilized by exploiting additional information.  
26 Prior knowledge on the statistical distribution of input variables to the model (Weiss et al.  
27 2000) or spatial (Atzberger 2004) and temporal constraints (Baret et al. 2007) can be  
28 introduced into the algorithm for this purpose.

29 In addition, the simplification included in the canopy radiative transfer model may induce  
30 large deviations from actual observations. During the last few decades, several advances in  
31 radiative transfer and canopy modelling have been made. A large number of models have  
32 been developed. These range from turbid medium to geometrical-optical models, which  
33 describe the vegetation in terms of simple geometrical objects such as cylinders, spheres,  
34 ellipsoids, for which surface properties are known. Finally models that account explicitly for

35 the detailed 3-D canopy structure and compute radiative transfer by ray tracing (Disney et al.  
36 2000) or radiosity (Borel et al. 1991) algorithms have been developed (e.g. Chelle et al. 1998;  
37 España 1998). These initial 3-D models were essentially static, whereas dynamic models have  
38 been developed recently some of which take into account interactions with environmental  
39 factors. They result in 4-D or functional-structural plant models (Godin and Sinoquet 2005).  
40 Progress in this field is driven by the availability of increasingly fast hardware, more efficient  
41 computer graphics algorithms and the rapidly-emerging field of 3-D canopy structure  
42 measurement (Godin et al. 1999).

43 Most radiative transfer models currently used to retrieve canopy characteristics are turbid  
44 medium models, which represent canopy structure in a very simple way (Jacquemoud et al.  
45 2000; Verhoef and Bach 2007). Vegetation elements are treated as infinitely small radiation  
46 scatterers that are randomly distributed within the canopy. Such models are computationally  
47 fast and require few input variables, which make them suitable for non-linear iterative  
48 numerical inversion schemes. This approach minimizes a cost function that quantifies the  
49 difference between simulated and measured reflectance. Although these models played a key  
50 role in describing generalized behaviour and mimicking canopy reflectance reasonably well in  
51 many cases, their application is ultimately limited to the simulation of relatively  
52 homogeneous canopies. This can lead to significant errors and biases, for example when  
53 applied to row crops at the early growth stages.

54 Recent developments in the use of look-up-table (LUT) and neural network (NNT) methods  
55 reduce the computing constraint for calculating canopy reflectance because they are based on  
56 pre-computed data bases (Knyazikhin et al. 1998). This opens the way for the inversion of  
57 more detailed 3-D models (Casa and Jones 2005; Disney et al. 2000).

58 Several 3-D or 4-D models have been developed for specific plant species, such as maize  
59 (España 1998; Fournier and Andrieu 1999), sorghum (Kaitaniemi et al. 1999), barley (Buck-  
60 Sorlin et al. 2005) rice (Watanabe et al. 2005), wheat (Evers et al. 2007) and cotton (Hanan  
61 and Hearn 2003). These models implicitly include a large amount of prior information on  
62 canopy properties for the given species.

63 In precision farming applications, considerable prior information is available about the crop  
64 type, the cultivar and cultural practices such as sowing time or row spacing. By exploiting this  
65 information and by improving the realism of the models used for the inversion with remotely  
66 sensed data, more accurate estimates of crop biophysical variables should be obtained in  
67 principle. However, these models should be evaluated in depth in terms of a more accurate

68 description of the corresponding radiometric signal, to assess their usefulness in the context of  
69 retrieving canopy properties from model inversion.

70 The use of inversion techniques based on look-up-tables or neural networks (Baret and Buis  
71 2007) allows very complex models to be used for estimating crop characteristics from  
72 remotely sensed observations. However, there must be a compromise between the realism of  
73 the 3-D canopy description and its parsimonious nature in terms of the number of parameters  
74 and computing time.

75 The objective of the present work was to compare the performances and operational  
76 limitations of the inversion of two contrasting type of models to retrieve leaf area index (LAI)  
77 and average leaf inclination angle (ALA). The models compared were the classical one-  
78 dimensional turbid medium canopy reflectance model PROSAIL (PROSPECT+SAIL)  
79 (Jacquemoud et al. 2009; Verhoef and Bach 2007) and a simple three-dimensional dynamic  
80 (4-D) maize model (Lopez-Lozano et al. 2007). The assessment was based on a set of  
81 multiangular field data recorded from maize canopies in Italy in 2007 and 2008 for this  
82 purpose. The data were representative of maize at the early growth stages, which we  
83 considered more interesting than a fully developed canopy for two reasons: 1) monitoring of  
84 an early stage crop seems more appropriate in the context of precision agriculture applications  
85 (e.g. fertilizer application) because management decisions based on a fully developed crop are  
86 likely to be too late to be effective, and 2) it is at early stages that row crops differ  
87 dramatically from the assumption of randomly distributed leaves present in 1-D models with  
88 an obvious clumping of foliage, whereas at later stages with full cover and more  
89 homogeneous canopy these assumptions pose fewer problems (Jacquemoud et al. 2000).

90

## 91 **Materials and methods**

### 92 **Field data**

93 Measurements were made on field grown maize crops at different growth stages in 2007 and  
94 2008. In July 2007 the measurements were made in the Sele Plain at the Improsta  
95 Experimental Farm (Naples, Italy) on the 18<sup>th</sup> July, at a maize growth stage V6 (Iowa State  
96 University, 1993). In 2008 the data were collected from the Maccarese Farm (Fiumicino,  
97 Rome, Italy) for maize growth stages V5 on the 15<sup>th</sup> of May and growth stage V8 on the 28<sup>th</sup>  
98 of May. The interrow spacing of the maize crop was 0.75 m.

99 Ground based multiple-look-angle remote sensing data were acquired from a height of 3 m (at  
100 nadir) over the canopy with a field sensor positioning system, based on an extending bipod  
101 arm with levelling head hinged on a goniometer to measure angles to the vertical (view zenith

102 angles) (Casa et al. 2009). The positioning system held 2 sensors: a spectroradiometer and a  
103 red-infrared camera. The Analytical Spectral Devices (ASD) Field Spec Fr Pro  
104 spectroradiometer measured radiance in the 350-2500 nm spectral range. Reflectance was  
105 then computed using a calibrated Spectralon panel. The field of view of the ASD  
106 spectroradiometer was 25° corresponding to a circular footprint at nadir of about 1.3 m in  
107 diameter. The red-NIR Dycam ADC camera (Dycam Inc., Chatsworth, CA, USA) was  
108 aligned with the spectroradiometer and provided images of the canopy with 496 × 365 pixels  
109 using an 8.5-mm f4.5 lens. Tests were carried out in the laboratory to assess the alignment  
110 between the spectroradiometer and the ADC camera, and a mask image was produced  
111 corresponding to the spectroradiometer footprint over the ADC image area. The mask was  
112 applied to all ADC images before further processing so that data were from exactly the same  
113 target area for both instruments.

114 In 2007 data were acquired at 9 view zenith angles (VZA) for each set of measurements,  
115 ranging from -40° to +40° with a step of 10°; this was increased to 13 VZAs (from -60° to +  
116 60°) in 2008. Most data were recorded with the sun close to the principal plane, i.e. with view  
117 zenith angles equal to sun azimuth angles irrespective of row orientation. Therefore, angles  
118 between row and view direction varied between different data sets; in a few initial sets (in  
119 2007) the measurement directions were parallel and perpendicular to row directions.  
120 Measurements were made at 4 different sites within a large field in 2007 and at 3 different  
121 sites for each date in 2008. For each site the measurements were replicated 2 to 4 times and  
122 all data from different view azimuth angles were pooled together.

123 Spectral reflectance data from sunlit soil were acquired separately at close range (nadir) for  
124 both fields at each site. Spectroradiometer data were smoothed using Savitzky-Golay filtering,  
125 with a polynomial of order 3 and frame size of 41 bands; this has been shown to remove noise  
126 without affecting spectral characteristics (Leone et al. 2007).

127 Dycam ADC images were classified (after applying the spectroradiometer footprint mask)  
128 with a supervised classification procedure using the minimum distance technique (Richards  
129 1999) to obtain the 'gap fraction', i.e. the fraction of soil visible at different view angles. This  
130 was used subsequently for inversion of the 4-D maize model. In previous tests this procedure  
131 had an overall classification accuracy of 99.4% (Casa and Jones 2005).

132 Concurrently to acquisition of the remotely sensed data, biophysical characteristics of the  
133 maize plants were measured. Four plants per site (i.e. 16 in total) were characterized fully in  
134 the field in 2007: for each leaf insertion height, length and maximum width together with  
135 inclination angle of the midrib were measured with a rule and electronic clinometer. Stem



136 diameters were also measured at each leaf insertion point. Each leaf was assumed to comprise  
137 segments of approximately constant inclination angle, and each segment length and width  
138 were measured together with the inclination angle. Leaf azimuth angles were measured with a  
139 compass. Plants were then taken to the laboratory where the area of each leaf was measured  
140 separately with a Li-Cor Li-3100 area meter.

141 Eight plants per site (a total of 48 plants for the 2 dates) were characterized similarly in 2008,  
142 except for the leaf inclination measurements which were replaced by digital photographs of  
143 plant silhouettes against a white background (Prevot et al. 1991). These images were then  
144 geometrically corrected and the coordinates of leaf midribs were obtained (Fig. 1). Relative  
145 leaf midrib coordinates were then used, together with all the other biometric data, for the 3-D  
146 reconstruction of each plant with the ADEL model (Evers et al. 2007; Fournier and Andrieu  
147 1999;) in the OpenAlea (<http://openalea.gforge.inria.fr>) environment. For this purpose relative  
148 leaf width data were calculated with the model of Prevot et al. (1991) from measurements of  
149 leaf lengths and maximum leaf widths. The 3-D reconstruction of maize plants with the  
150 ADEL model resulted in visually similar plants to those measured, although the model did not  
151 account for leaf undulation and curling (Fig. 1). A comparison of the measured area of each  
152 leaf with that reproduced by the ADEL model (each leaf was composed of 20-30 triangles)  
153 gave an RMSE of 32.4 cm<sup>2</sup>, corresponding to an absolute LAI error of 0.02 (i.e. 1% for a LAI  
154 of 2). This indicated an acceptable approximation provided by the Prevot et al. (1991) leaf  
155 width model as well as by the level of triangulation chosen. Therefore, the leaf inclination  
156 distribution from the modelled 3-D reconstructions of the plant could represent that of actual  
157 plants. The virtual plants are defined by a triangular mesh, therefore, the area and inclination  
158 of all leaf triangles were used to calculate the leaf inclination distribution function (LIDF) and  
159 average leaf angle (ALA) from the fraction of leaf area within each inclination angle class of  
160 5°. The processing of silhouette images and subsequent 3-D reconstruction of the plants (Fig.  
161 1) provides a procedure that is much less time consuming than direct measurements with  
162 clinometers or 3-D digitizers in the field.

## 164 Models and inversion techniques

165 The PROSAIL model was chosen as it has been widely tested and validated in the last 16  
166 years in a great number of studies both in the direct and inverse mode (Jaquemoud et al.,  
167 2009). The version used here included the treatment of the ‘hotspot’, i.e. the peak of  
168 reflectance when the sun and the viewing directions coincide. It assumed that the soil acted as  
169 a Lambertian diffuser, accepting measured soil spectra as input to the model and corresponds

170 to the version SAILH (Verhoef and Bach 2007). Inversion of the model against measured  
171 multiangular reflectance spectra was done with an optimization algorithm based on the  
172 simplex search method (Lagarias et al. 1998). The version used made it possible to constrain  
173 the estimated parameters to realistic ranges by providing bounds. Iterative optimization  
174 algorithms are known to be sensitive to the initial set of parameter values, and might also  
175 converge to local minima of the cost function instead of converging to the global minimum.  
176 For these reasons, a procedure was used in which initial parameter values were drawn  
177 randomly from within the specified bounds and the algorithm was rerun 10 times (replicates)  
178 for each estimation. The estimated parameter values retained were those that minimized the  
179 cost function within the 10 initial replicates. The parameters LAI and ALA (average leaf  
180 angle) were estimated simultaneously. The other PROSAIL parameters were fixed at their  
181 nominal values (Table 1), except for the soil spectra that were measured at each site and for  
182 sun and view angles that corresponded to the measurement configurations.

183 The inversion was carried out for wavelengths 400-1350 nm in steps of 1 nm for the  
184 Maccarese data of 2008 to avoid the absorption bands at longer wavelengths. For the 2007  
185 Sele data they were limited to the 400-900 nm range because the data were very noisy at the  
186 longer wavelengths.

187 The 4-D model chosen was the one developed by Lopez-Lozano et al. (2007). In this model,  
188 maize plants are represented by simple geometrical shapes: a quadrangular pyramid represents  
189 the stem and each leaf is represented by an isosceles triangle. Leaf number, position on the  
190 stem, area and inclination are defined on the basis of equations derived from measurements  
191 and from a previous model developed by España (1998) which is driven by thermal time (i.e.  
192 degree-days above a base temperature of 10°C). The model has few input parameters (Table  
193 1), but despite the rather crude simplifications it provides a remarkably more realistic canopy  
194 description (Fig. 2) than the homogenous opaque ‘green slab’ of a turbid medium model.

195 This model was chosen because of its simplicity, small number of parameters and fast  
196 execution time, typically 1.4 s on a laptop with an Intel Core 2 Duo Processor 1.66 GHz CPU  
197 for the generation of a 3-D scene such as that in Fig. 2. The attributes make it amenable to  
198 inversion by numerical optimization techniques.

199 The inversion of the 3-D maize model was done with the same algorithm that was used for the  
200 PROSAIL inversion, i.e. the simplex search method with bounds and 10 replicate runs for  
201 each inversion. However, in this case the cost function expressed the difference between  
202 measured and modelled gap fractions for the view configurations used in the measurements.  
203 Measured gap fractions were obtained from the Dycam ADC image classification data.

204 Modelled gap fractions were calculated using the Z-buffer technique. This involves projecting  
205 the generated 3-D scene in a given direction onto a grid. The value of each grid point is then  
206 associated with the depth of the corresponding triangle. The gap fraction is finally computed  
207 as the ratio between the number of soil grid points (maximum depth) to the total number of  
208 grid points. To avoid border effects, the scene was replicated infinitely as described by Chelle  
209 et al. (1998). The parameters to be estimated were T and  $\Delta\theta_{\text{leaf}}$  (Table 1). The LAI and ALA  
(model outputs) were calculated from model simulations using the estimated parameter  
values.

## 213 Results and discussion

214 Actual LAI values obtained from direct measurements vary between 0.58 and 2.56,  
215 representing situations ranging from incomplete canopy closure to 73% ground cover at nadir.  
216 The average leaf inclination angles obtained from the 3-D plant reconstruction for the 2008  
217 data are consistent with the clinometer data of 2007; most values are around 63° for less  
218 developed plants (stage V5 and V6) and increase somewhat to 67-68° for the more advanced  
219 stage (V8).

220 Spectral reflectance measurements show strong anisotropy, which is usually observed in  
221 multiangular measurements over plant canopies (Chopping, 2007), with a peak at view zenith  
222 angles roughly corresponding to the sun zenith angle where the minimum fraction of shades is  
223 observed (Fig. 3a). Reflectance values, especially for NIR wavelengths (700-1300 nm), are  
224 smaller for angles close to nadir because a much larger fraction of the field of view of the  
225 sensor was occupied by the soil. This is also shown by gap fraction data derived by  
226 simultaneous image acquisition from the camera (Fig. 3b).

227 The spectral reflectance data were used in the inversion of the PROSAIL model, which was  
228 generally fast, taking typically less than 30 s for one optimization on a laptop computer (see  
229 above). The chosen constraint settings for the simplex method were: a maximum of 500  
230 iterations and a maximum of 10 000 function evaluations, or a tolerance of 0.1 on the cost  
231 function or 0.01 on the parameter values. These settings applied to the 10 replicates ensured  
232 that the cost function reached a global minimum. This was evident, for example, by plotting  
233 the estimated parameter values against the starting values used to initialize the simplex  
234 procedure. To constrain the estimates to plausible values, the parameters were allowed to vary  
235 within specific ranges only: 0–5 for LAI and 0–90 for ALA.

236 Estimation of LAI from inversion of the PROSAIL model shows in general reasonable results  
237 with an overall RMSE of 0.48 and an  $R^2$  of 0.85 (Fig. 4a). The results for the 2008 data have a  
238 RMSE of 0.24 and an  $R^2$  of 0.91, whereas some points in the 2007 data are overestimated  
239 giving a RMSE of 0.74 and an  $R^2$  of 0.86.

240 Estimation of average leaf inclination angle (ALA) is rather poor by contrast (Fig. 4b) for  
241 both the 2008 data (RMSE 15.98,  $R^2$  0.56) and especially for the 2007 data (RMSE 25.04,  $R^2$   
242 0.24), some of which fall on one of the bounds that were set for this parameter. It should be  
243 noted that in 2007 the data had been recorded along or across maize rows irrespective of sun  
244 azimuth angle, whereas in 2008 most data sets were acquired as far as possible along the  
245 sun's principal plane (i.e. with view azimuth coinciding with sun azimuth). The latter  
246 approach provided a better sampling of the typical bidirectional reflectance distribution  
247 function (BRDF) features such as the 'hotspot'. In addition, observations in 2007 were  
248 acquired at 9 VZAs ( $-40^\circ$  to  $+40^\circ$ ) compared to 13 VZAs for 2008 ( $-60^\circ$  to  $+60^\circ$ ). For the  
249 inversion of the PROSAIL model, *a priori* information was not taken into account in the  
250 formulation of the cost function, but it is now advised to do so (Baret and Buis 2007).  
251 Furthermore, the turbid medium models provide an estimate of the 'effective LAI' (Chen and  
252 Black 1992) because clumping is not taken into account and it is not possible to exclude the  
253 influence of stems, whereas actual LAI measurements include only leaves.

254 Inversion of the 3-D maize model was much slower than for PROSAIL, typically it took  
255 about 20 minutes for each optimization to run (i.e. 10 replicates) on a laptop (see above). The  
256 same simplex stopping criteria were used as for PROSAIL inversion. The parameters T and  
257  $\theta_{\max}$  were constrained by the bounds 50–2500 degree-days and 0–90 degrees, respectively.  
258 Other measured parameter values (Table 1) were obtained from previous field trials in Spain  
259 (Lopez-Lozano 2007). Overall, accuracy of LAI estimation with the 3-D maize model (Fig.  
260 5a) appears to be similar to that obtained with PROSAIL, with a RMSE of 0.25 and an  $R^2$  of  
261 0.83 for the 2008 data, and a slight underestimation for the 2007 data with RMSE 0.48 and  
262 and  $R^2$  of 0.78. Estimation of the average leaf angle (Fig. 5b) shows a distinct group of points,  
263 including all 2007 data plus two 2008 data points, for which ALA is markedly  
264 underestimated. The overall RMSE is larger than that obtained from PROSAIL ALA  
265 estimation. The RMSE and  $R^2$  were 26.48 and 0.02, respectively, for the 2008 data and 49.9  
266 and 0.25, respectively, for 2007 data.

267 The results obtained from the inversion of the 4-D model on gap fraction data are similar to  
268 those obtained with the turbid medium models although this model should provide a more

269 realistic description of a maize canopy. It should be noted that the 4-D model was developed  
1 270 on relationships describing maize leaf arrangement and size, which had been derived  
2 271 specifically from maize experimental data (España 1998). This means that much of the *a*  
3 272 *priori* information was included implicitly in the inversion process.  
4 273

5 274 In the comparison between the two models it should be noted that exactly the same inversion  
6 275 technique was used for both, therefore differences in the estimation results could be attributed  
7 276 to two possible causes: 1) the use of different types of measurements, i.e. gap fraction or  
8 277 reflectance data, because gap fraction depends only on plant architecture whereas canopy  
9 278 reflectance data integrate soil and leaf biochemical information; 2) the different descriptions  
10 279 of the canopy included in the models, for example the implicit assumption of leaf clumping in  
11 280 the 4-D maize model which is absent in the turbid medium formalism.  
12 281

13 282 To clarify the relative importance of each of these two effects additional tests were carried out  
14 283 by inverting a simple Poisson model (Nilson 1971), on which the turbid medium approach is  
15 284 based, using the measured gap fraction data. The model was  
16 285

$$Po(\theta_v) = \exp^{-k LAI} , \quad (1)$$

17 286 where  $Po$  is the gap fraction at view zenith angle  $\theta_v$  and  $k$  is the extinction coefficient, i.e. the  
18 287 average projection of leaves on to a horizontal surface, which was calculated as a function of  
19 288 the view zenith angle  $\theta_v$  and the leaf angle distribution parameter  $\chi$  of Campbell's ellipsoidal  
20 289 leaf angle distribution (Campbell 1986). The model was inverted using the simplex method  
21 290 with the same settings as those used for the PROSAIL and 4-D maize models, and the  
22 291 parameters  $LAI$  and  $\chi$  were retrieved simultaneously, with bounds of 0.1–10 for  $\chi$  and 0–10  
23 292 for  $LAI$ . The average leaf angle (ALA) was then calculated from  $\chi$  with Campbell's (1990)  
24 293 equation.  
25 294

26 295 Although the Poisson model treated canopy structure in a similar way to PROSAIL, there are  
27 296 some small differences in the estimates of LAI (Fig. 6a). Estimates of the 2007 data are  
28 297 slightly better (RMSE 0.57,  $R^2$  0.50) and those of the 2008 data are marginally worse (RMSE  
29 298 0.30,  $R^2$  0.86). The ALA is estimated considerably better than it was by both PROSAIL and  
30 299 the 4-D model; the RMSE is about  $6.51^\circ$  and  $R^2$  is 0.05 for the 2008 data and 9.62 and 0.14  
31 300 for the 2007 data (Fig. 6b).  
32 301

33 302 However, none of the models seems to perform satisfactorily in the estimation of ALA. It  
34 303 should be noted that accurate direct measurement of leaf angle distribution is very difficult  
35 304 and time consuming, and so assessments of retrieval accuracy from radiometric observations  
36 305 are very in literature (e.g. Shibayama 2006). In maize the typical undulation and curling of  
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302 leaf blades make it almost impossible to measure correctly the fraction of leaf area that is  
1 303 actually oriented in each direction. Thus many workers have resorted to measuring inclination  
2 304 angles of leaf midribs (e.g. Ford et al. 2008; Prevo<sup>t</sup> et al. 1991). In such an approach it is  
3 305 assumed that leaf blades are flat, which introduces an error in the LIDF that is difficult to  
4 306 estimate, but that seems to have little effect on the gap fraction (Espa<sup>ña</sup> 1998).

8 307 From the estimates of LAI, the sampling of view zenith angles along the sun's principal plane  
9 308 seems to be particularly important because it exploits the maximum angular variation of  
10 309 canopy reflectance as shown by the results obtained with PROSAIL in 2007 and 2008 (Fig.  
11 310 4). These results were obtained using data with fairly wide directional sampling. In practice,  
12 311 measurements with such directional coverage would be unlikely and one would be limited to  
13 312 data at far fewer view zenith angles. The difference between the gap fraction calculated by  
14 313 turbid medium models and models that account implicitly for leaf clumping, such as the 4-D  
15 314 model, depends largely on the viewing direction chosen (e.g. Lopez-Lozano et al. 2007); the  
16 315 larger discrepancies are for angles close to nadir.

17 316 The impact of the number and configuration of the view zenith angles chosen, therefore, was  
18 317 investigated by inverting different models using the same procedure as described above, but  
19 318 excluding progressively more view zenith angles from the data. The assessment was done for  
20 319 LAI only and only for the 2008 data because the 2007 data were not fully consistent with  
21 320 these, i.e. they had a different sun-view geometry and fewer VZAs. Two different strategies  
22 321 were used: in the first, data were gradually removed starting from the most extreme VZAs  
23 322 (more oblique) until only three VZAs close to nadir remained ( $0^\circ$  and  $\pm 10^\circ$ ); in the second,  
24 323 the angles close to nadir were deleted until only the two most extreme angles remained  
25 324 ( $\pm 60^\circ$ ).

26 325 The RMSEs from the LAI estimates of the three models show a difference between the two  
27 326 strategies (Fig. 7). The progressive elimination of the larger VZAs in the direction of nadir  
28 327 results in a gradual decrease in the accuracy of estimation, especially for the turbid medium  
29 328 models. When only the nadir and  $\pm 10^\circ$  VZA were left, the PROSAIL model performs  
30 329 marginally better than the others. The results for the second strategy show a relative  
31 330 insensitivity to the number of VZAs in the accuracy of LAI estimates, which indicates that  
32 331 data obtained at just a few oblique view angles provide reasonable estimates of LAI. It should  
33 332 be noted that when only the most extreme VZAs remain ( $\pm 60^\circ$ ), LAI estimation could be  
34 333 more robust because of the well known insensitivity of the leaf area projection function to leaf  
35 334 inclination distribution at  $57.5^\circ$  (Warren-Wilson 1963). Information embodied in the

335 reflectance of a turbid medium target viewed from the nadir only is poor compared to that  
336 measured at an oblique angle (Jacquemoud et al. 2009); this is confirmed by the results of the  
337 tests shown in Fig. 7. Therefore, this consideration could also be extended to gap fraction  
338 data. Oblique view angle measurements, even if limited to few extreme angles, provide more  
339 accurate estimates of LAI.

## 341 **Conclusion**

342 This work shows the feasibility of inverting a simple 4-D canopy model by using the same  
343 numerical optimization technique as generally used for 1-D models. The results of the  
344 estimation of LAI from inversion of the 4-D model are only marginally better than those  
345 obtained with the 1-D model, whereas average leaf inclination angle (ALA) is not estimated  
346 satisfactorily by any of the models. The use of gap fraction data, instead of spectral  
347 reflectance, is shown to be adequate for the situation in which observations from several view  
348 angles are available. A reduction in the number of view angles severely degrades the accuracy  
349 of estimation, especially when there are only near nadir observations. Conversely oblique  
350 view angle measurements are shown to allow more accurate LAI estimation.

351 Two problems inherent to the inversion procedure can be mentioned. The first concerns the  
352 arbitrary choice of values for the model parameters that are not estimated. The values chosen  
353 can have a remarkable influence on the results. The simplex algorithm is subject to the risk of  
354 converging to local minima of the cost function if the number of parameters to be estimated is  
355 increased. However, alternative techniques, such as those based on Bayesian methods could  
356 be more robust and allow the retrieval of several parameters at the same time. This alleviates  
357 the need to provide arbitrarily fixed parameter values. The second problem stems from the  
358 fact that variation in both LAI and average leaf inclination angle (ALA) can produce similar  
359 effects on canopy reflectance and gap fraction. This is highlighted by the difficulties of  
360 retrieving accurate LAI and ALA values simultaneously.

361 In conclusion, a more thorough comparison is needed to assess the capabilities of 1-D and 4-  
362 D models to retrieve canopy properties by exploring a much wider range of canopy types and  
363 observation configurations. For example, it would be useful to investigate the sensitivity in  
364 the inversion of different kinds of models to the well known saturation effect. The latter  
365 occurs with a dense canopy cover and reflectance becomes insensitive to changes in LAI  
366 because the lower layers of foliage are not visible. Comparisons of spectral reflectance from  
367 1-D and 3-D or 4-D models could be improved if they were made under a range of situations,

368 for example by using a ray-tracing or radiosity method to calculate reflectance from 3-D  
369 descriptions of the canopy.

370

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## Tables

**Table 1.** List of the input parameters of the 1-D model PROSAIL and of the dynamic 4-D model of Lopez-Lozano et al. (2007) with the values used for their inversion.

Model	Parameter	Description	Unit	Used values*	
PROSAIL	$\theta_s$	Sun zenith angle	Radians	Measured	
	$\theta_v$	View zenith angle	Radians	Measured	
	$\varphi$	Angle between sun and view azimuth	Radians	Measured	
	Rs	Vector of soil reflectance	nm	Measured	
	Cab	Leaf chlorophyll a+b content	$\mu\text{g cm}^{-2}$	40	
	Cw	Leaf water content	$\text{g cm}^{-2}$	0.012	
	Cdm	Leaf dry matter content	$\text{g cm}^{-2}$	0.005	
	Cbp	Leaf brown pigment content	-	0	
	N	Leaf mesophyll structure index	-	1.5	
	Ang	Leaf surface roughness angle	Degrees	59	
	LAI	Leaf area index		<i>Estimated</i>	
	ALA	Average leaf angle	Degrees	<i>Estimated</i>	
	Hot	Hotspot parameter	-	0.1	
	4-D maize	$N_{\max}$	Maximum number of leaves per plant	N	18
		$S_{\max}$	Maximum leaf area per plant	$\text{m}^2$	0.5
DTc		Phyllochron	$^{\circ}\text{C d}^{-1}$	50	
DTs		Leaf lifespan	$^{\circ}\text{C d}^{-1}$	1200	
D		Plant density	$\text{plants m}^{-2}$	7	
Plasticity		Leaf azimuth adjustment parameter	-	0.2	
$d_{\text{rows}}$		Distance between rows	m	0.75	
$H_{\max}$		Maximum plant height	m	2.5	
$\theta_{\max}$		Inclination of largest leaf	Degrees	<i>Estimated</i>	
$\Delta\theta_{\text{leaf}}$		Difference in inclination between the biggest and smallest leaf	Degrees	20	
T		Temperature sum	$^{\circ}\text{C d}^{-1}$	<i>Estimated</i>	

\* values used were obtained from independent data sets obtained previously from maize plant canopies (Lopez-Lozano et al., 2007)

## Figure captions

1  
2 **Fig. 1** **a** Example of the processing of a maize plant silhouette image, **b** acquisition of leaf  
3 midrib coordinates and **c** 3-D reconstruction of the plant using the ADEL model (Fournier and  
4 Andrieu 1999).  
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9 **Fig. 2** A typical scene generated by the 4-D maize model of Lopez-Lozano et al. (2007).  
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12 **Fig. 3** **a** Multiangular spectral reflectance data recorded from the maize canopy at a sun  
13 zenith angle of  $43^\circ$  using the ASD Fieldspec spectroradiometer and **b** the corresponding gap  
14 (soil) fraction obtained from the classification of collimated bispectral images acquired  
15 concurrently to the spectra.  
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21 **Fig. 4** Results from the inversion of the PROSAIL model for the simultaneous estimation of:  
22 **a** LAI and **b** ALA on multiangular spectral reflectance data. The other model parameter  
23 values are those reported in Table 1. Filled triangles: measurements carried out at the Sele  
24 Plain in 2007; empty circles: measurements carried at Maccarese in 2008.  
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30 **Fig. 5** Estimates of: **a** LAI and **b** ALA from inversion of the 4-D maize model of Lopez-  
31 Lozano et al. (2007) on multiangular gap fraction data. The other model parameter values are  
32 those reported in Table 1. Filled triangles: measurements carried out at the Sele Plain in 2007;  
33 empty circles: measurements carried at Maccarese in 2008.  
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40 **Fig. 6** Results from the inversion of the Poisson model of Eq.1 for the simultaneous  
41 estimation of: **a** LAI and **b** ALA on multiangular gap fraction data. Filled triangles:  
42 measurements carried out at the Sele Plain in 2007; empty circles: measurements carried at  
43 Maccarese in 2008.  
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49 **Fig. 7** Sensitivity of LAI retrieval accuracy to the number of observation view zenith angles  
50 (VZA): **a** gradual reduction in the more oblique VZAs in the direction of nadir and **b** gradual  
51 reduction in the less oblique VZAs in the direction of the more oblique angles (i.e. larger  
52 VZAs).  
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Figure1  
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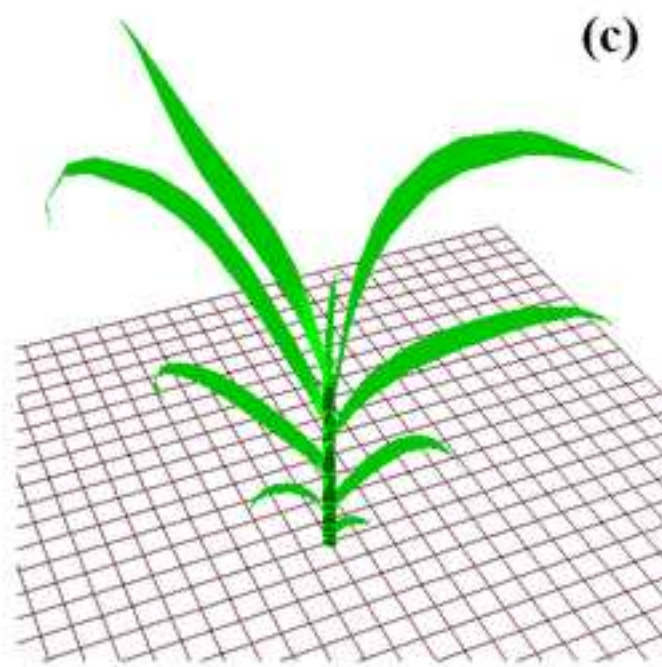
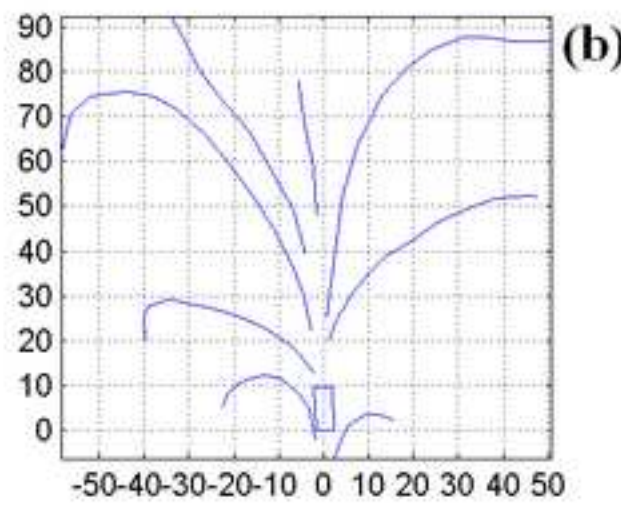


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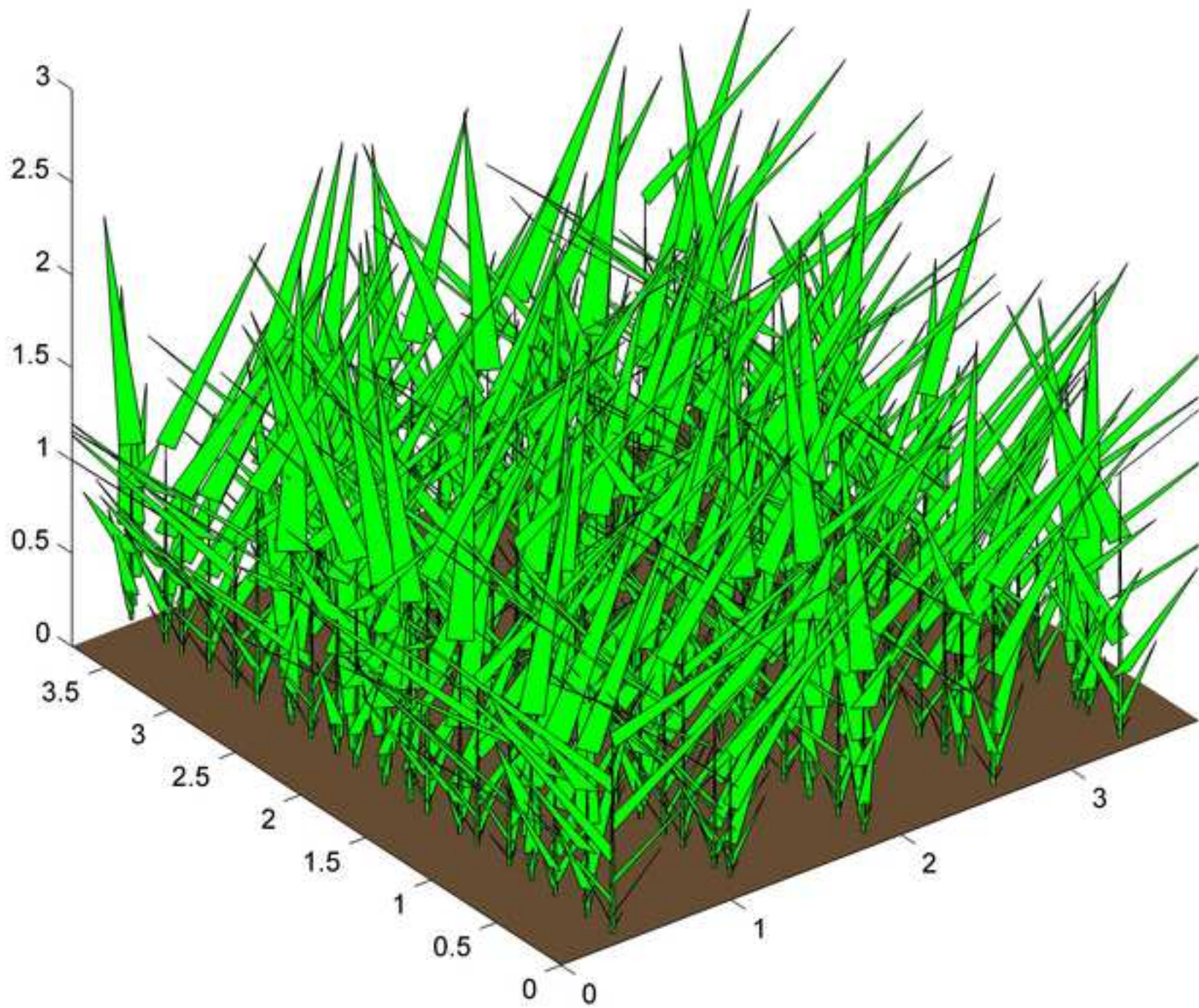


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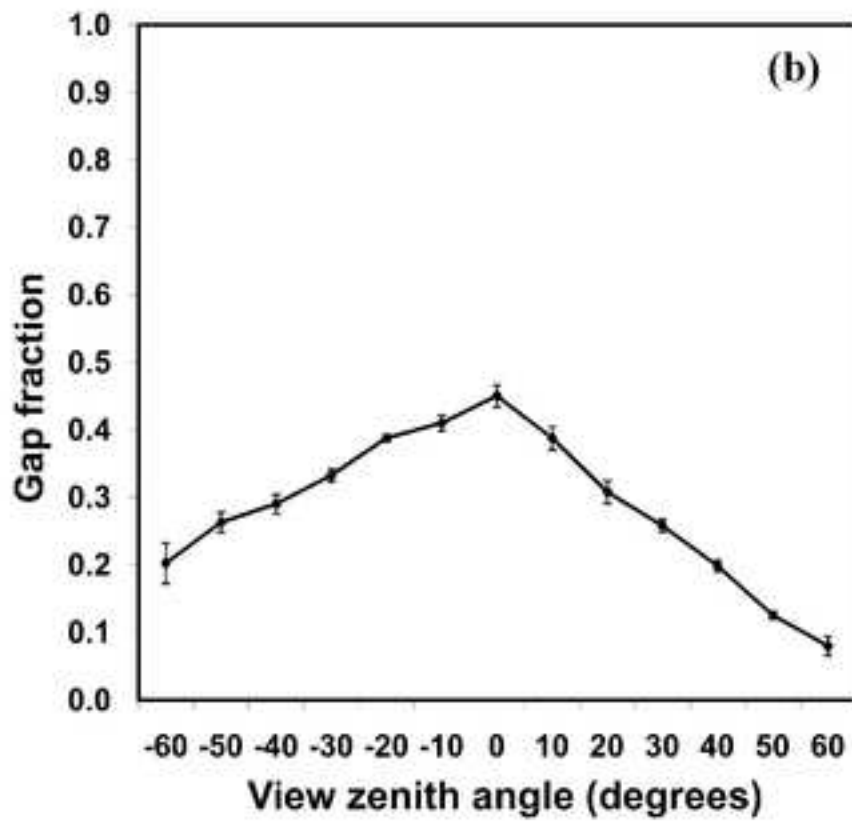
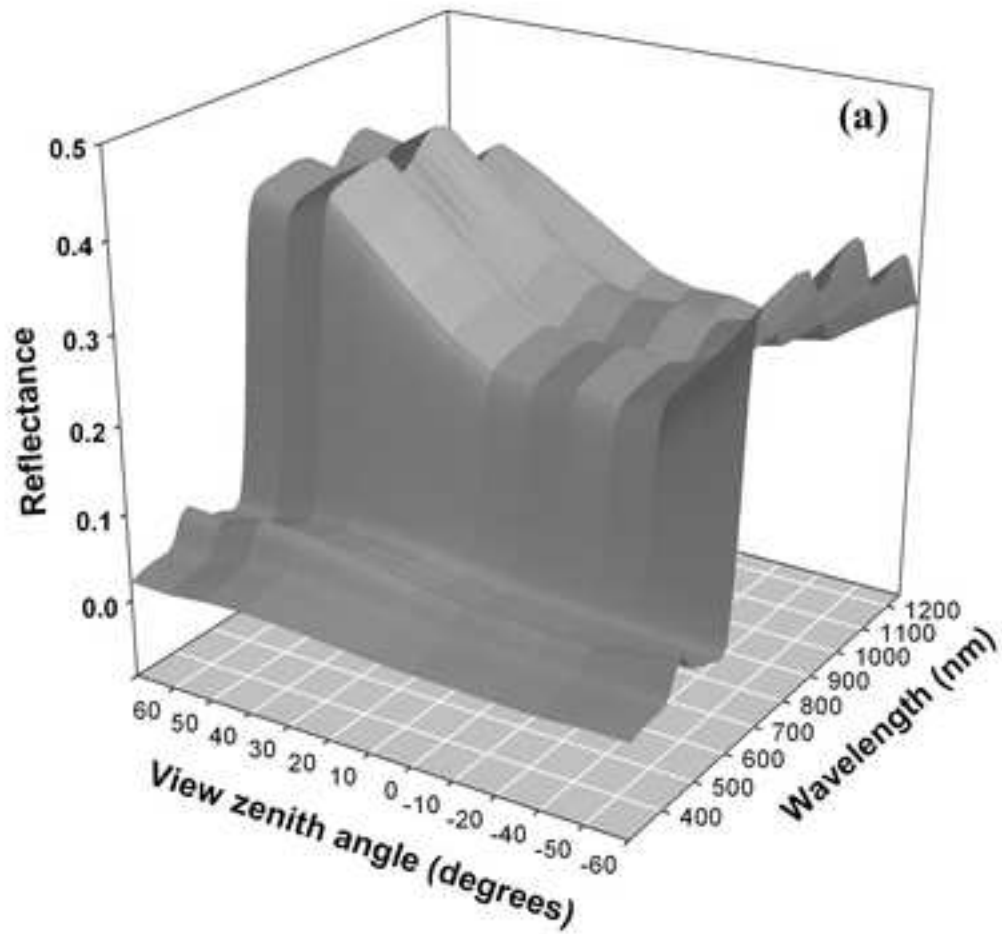




Figure4

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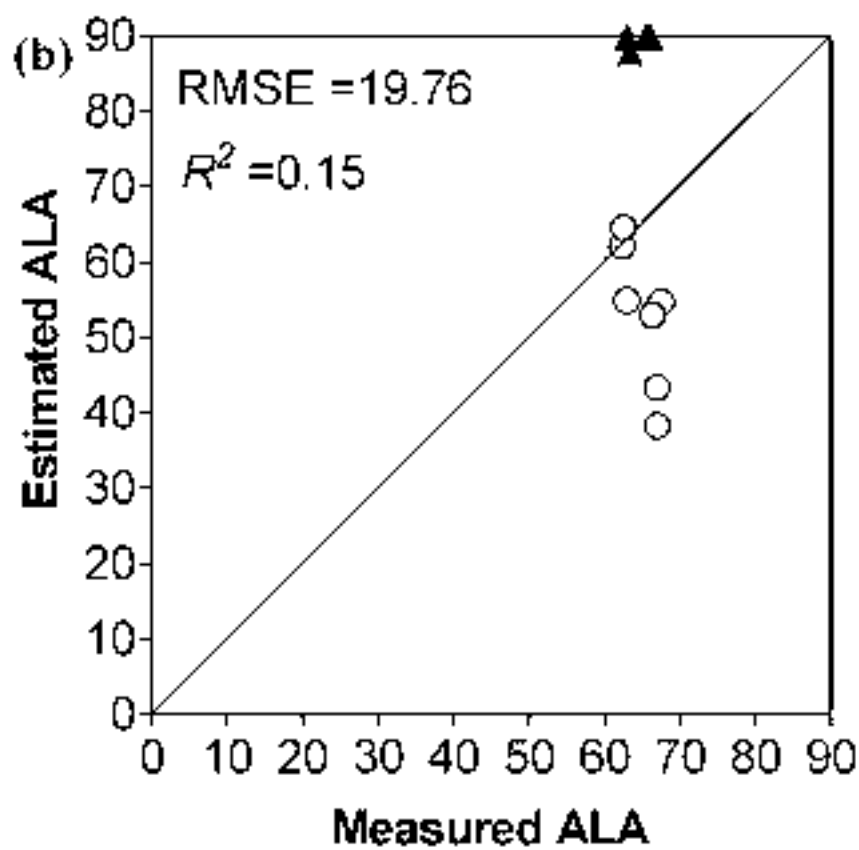
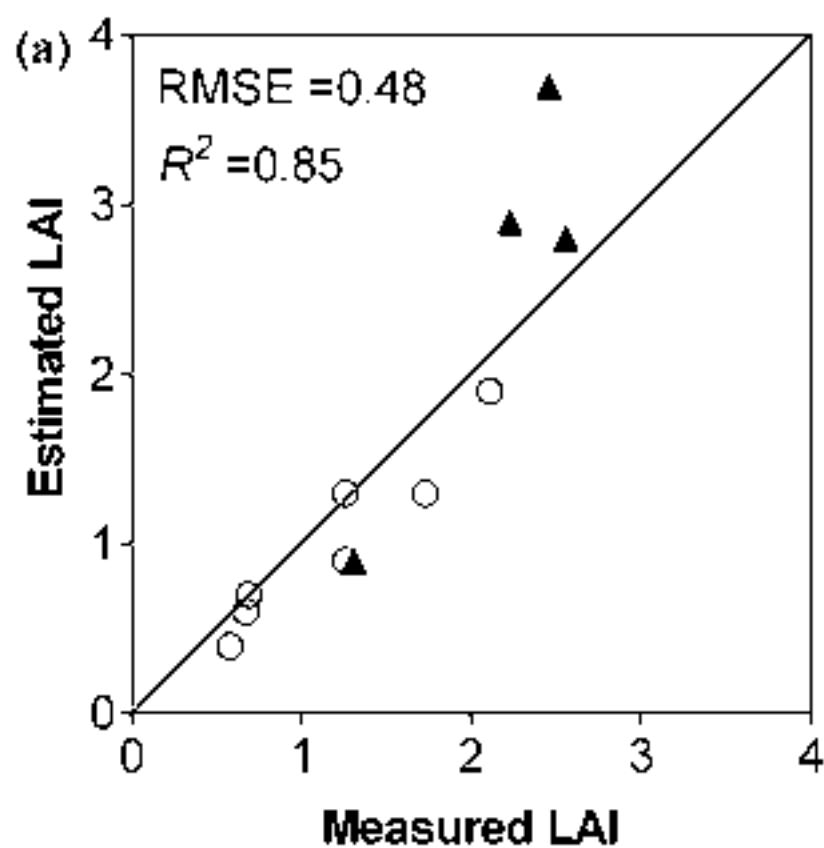


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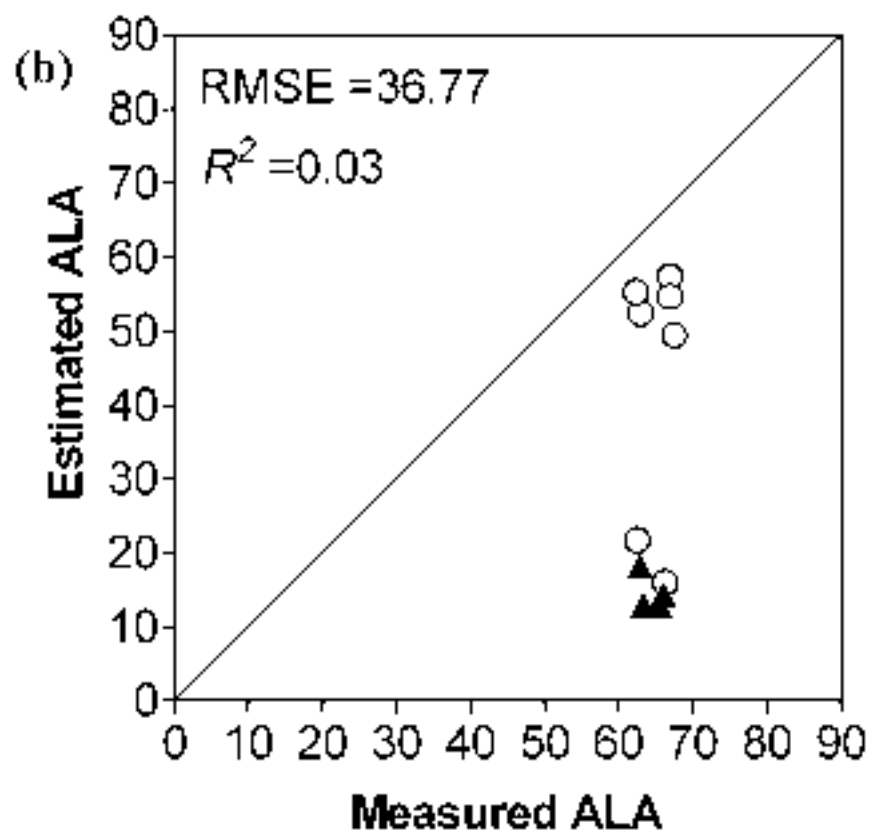
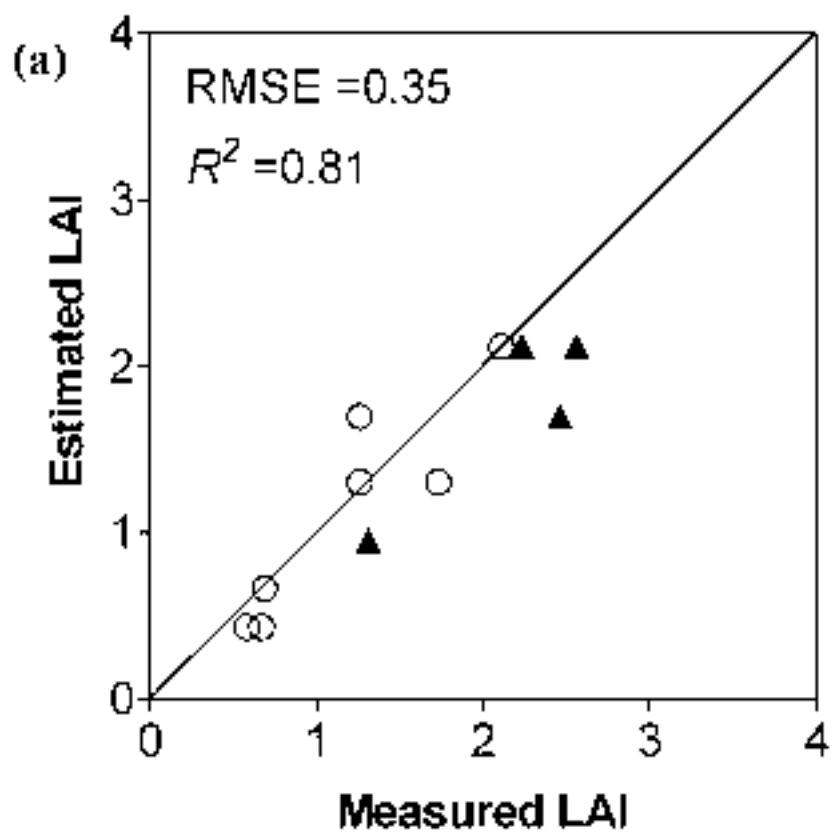


Figure6

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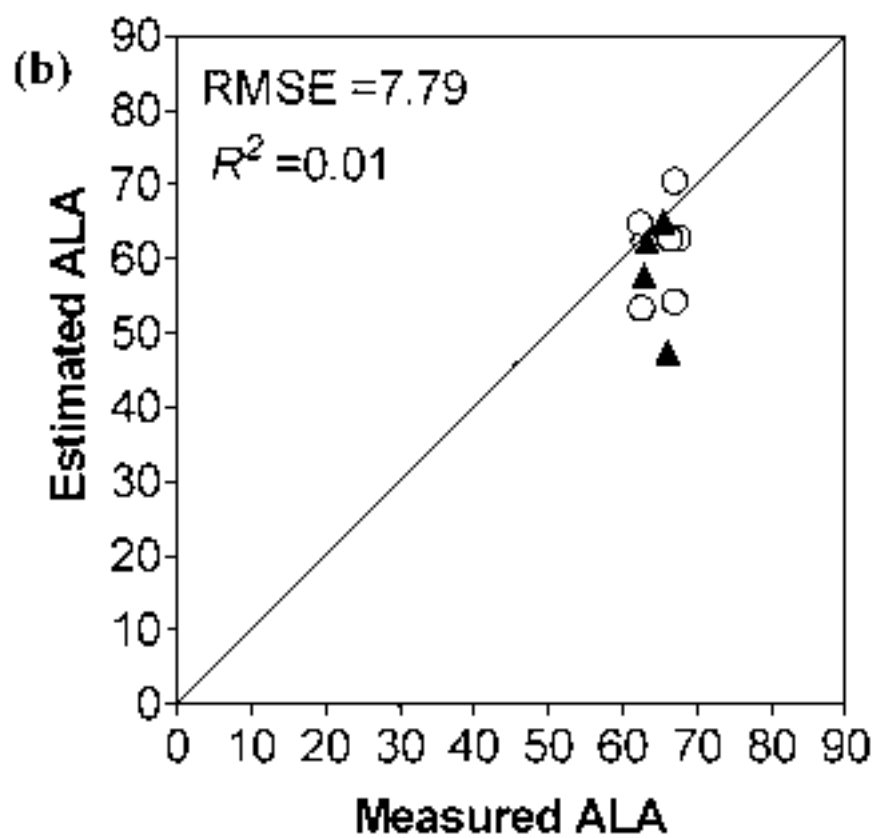
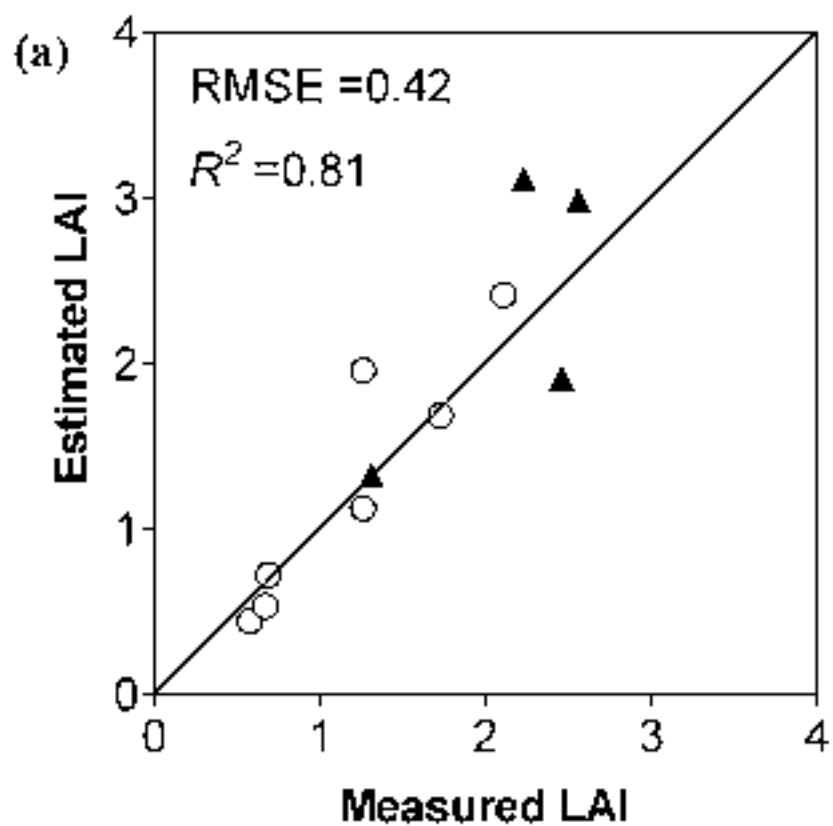


Figure7

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