

1 **Empirical ground-motion prediction equations for Northwestern**
2 **Turkey using the aftershocks of the 1999 Kocaeli earthquake**

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8 **Abstract**

9 We present ground motion models for northwestern Turkey using the aftershocks of the
10 Mw 7.4, 1999 Kocaeli earthquake. We consider 4047 velocity and acceleration records
11 for each component of motion, from 528 earthquakes recorded by stations belonging to
12 regional networks. The ground motion models obtained provide peak ground velocity,
13 peak ground acceleration, and spectral accelerations for 8 different frequencies between 1
14 and 10 Hz. The analysis of the error distribution shows that the record-to-record
15 component of variance is the largest contribution to the standard deviation of the
16 calibrated ground- motion models. Furthermore, a clear dependence of inter-event error
17 on stress drop is observed. The empirical ground-motion prediction equations, derived for
18 both the larger horizontal and vertical components, are valid in the local magnitude range
19 from 0.5 to 5.9, and for hypocentral distances up to 190 km.

20

20 **Introduction**

21 Turkey is one of the countries in the Mediterranean region that show the highest level of
22 seismic hazard. In 1999, the northwestern part of the country was struck by two
23 earthquakes, namely the Mw 7.4 Kocaeli and the Mw 7.2 Düzce earthquakes, that caused
24 much damage and many fatalities. Recent studies [e.g *Erdik et al.*, 2004; *Parsons*, 2004]
25 showed that the segments of the North Anatolian Fault in the Sea of Marmara to the
26 immediate south of Istanbul have a significant probability (40-65%) of producing a M>7
27 earthquake within the next 30 years. As a result, several international projects have been
28 promoted for mitigating the seismic risk in this region. The recordings of the Kocaeli and
29 Düzce earthquakes enriched the strong motion data sets exploited for deriving ground-
30 motion models adopted in the hazard calculations performed within these projects.
31 Examples are the empirical ground-motion prediction equations (GrMPEs) recently
32 derived for Europe [*Ambraseys et al.*, 2005], and several domestic models [e.g., *Kalkan*
33 and *Gülkan*, 2002, 2004; *Özbey et al.*, 2004]. In this study, 4047 recordings relevant to
34 528 aftershocks of the Kocaeli earthquake are used to calibrate empirical GrMPEs in the
35 local magnitude range from 0.5 to 5.9 for northwestern Turkey. The empirical GrMPEs
36 are calibrated for peak ground acceleration (PGA), peak ground velocity (PGV) and for
37 the spectral acceleration (SA) of a 5% critical damped oscillator, considering the
38 maximum between the North-South and East-West components, as well as the vertical
39 component. The inter-event and inter-station distributions of error, computed by applying
40 the random-effects approach [*Abrahamson and Youngs*, 1992] are compared for different
41 choices of the design variables.

42 **Data**

43 The attenuation models are calibrated using 4047 waveforms for each component of
44 motion relevant to 528 earthquakes recorded between August 1999 and December 1999
45 by 31 stations of the German Task Force for Earthquakes (GTF) and Sabanca-Bolu
46 (SABO) seismic networks, and by 23 accelerometers belonging to the Kandilli
47 Observatory and Earthquake Research Institute (KOERI) strong motion network. The
48 area coverage of the selected data set is shown in Figure 1 (top panel). The GTF and
49 SABO networks consist of 1-Hz geophones (Mark L-4C-3D), a 24-bit digitizer with a
50 sampling rate of 100 sps and Global Positioning System (GPS) timing. The KOERI
51 strong motion network consists of Kinometrics SSA-12 and GeoSys GSR-16 strong-
52 motion stations working with a sampling rate of 200 sps. The earthquake magnitudes and
53 locations are taken from Bindi et al. [2007] and Parolai et al. [2007]. The distribution of
54 magnitude with distance of the data is shown in Figure 1 (bottom panel). M_L ranges
55 between 0.5 and 5.9 ($1.3 \leq M_w \leq 5.6$), with only 13 earthquakes having $M_L < 1.0$, and
56 hypocentral distances up to 190 km are considered. Most of the available data lie in the
57 range 1.5-5 and 10-140 km for magnitude and distance, respectively. The depth of most
58 of the earthquakes is between 5 and 15 km. The waveforms are corrected for the
59 instrumental response and band-pass filtered with a 4th order acausal Butterworth filter
60 between 0.5-25 Hz and 0.1-25 Hz for $M_L \leq 4.5$ and $M_L > 4.5$, respectively.

61 The stations of the GTF and SABO networks are free-field stations, whereas the KOERI
62 accelerometers are located in the ground floor of small buildings because they were
63 installed mainly for engineering purposes. Most of the stations of the GTF and SABO
64 networks were previously classified as rock or soil [Parolai et al., 2004], whereas NEHRP
65 site classification of the KOERI stations can be found in Durukal [2002]. We extended
66 the existing rock-soil classifications to all stations by analyzing the site responses

67 obtained by applying the generalized inversion technique (GIT) [Parolai et al., 2004,
68 2007]. Sites were classified as rock (class s_1) if they showed a maximum amplification
69 lower than a certain threshold, otherwise they were classified as soil (class s_2). The
70 geotechnical-geological classification available for some stations was exploited to select
71 the threshold. Since the GIT was carried out while setting to 1 the site response of a
72 single rock-like reference station for the GTF and SABO networks and setting to 1 the
73 average site response for the strong motion network, different thresholds were used for
74 different networks. After some trials, a level of amplification of 2.5 was used for the
75 KOERI network and of 4.5 for the GTF or SABO networks.

76 **Attenuation models**

77 The following ground-motion models are considered [Ambraseys et al., 2005]:

$$78 \log_{10} Y = a + bM + (c + dM) \log_{10} R_{\text{hypo}} + s_{1,2} \pm \sigma_{\text{tot}} \quad (1)$$

$$79 \log_{10} Y = a + bM + (c + dM) \log_{10} (R_{\text{epi}}^2 + h^2)^{0.5} + s_{1,2} \pm \sigma_{\text{tot}} \quad (2)$$

80 where Y is the variable of interest, that is the PGA, PGV, or SA, M is the magnitude, and
81 R_{epi} and R_{hypo} are the epicentral and hypocentral distances, respectively (in km); σ_{tot} is the
82 standard deviation on $\log_{10} Y$, given by $\sigma_{\text{tot}}^2 = \sigma_{\text{eve}}^2 + \sigma_{\text{sta}}^2 + \sigma_{\text{rec}}^2$, where σ_{eve}^2 ,
83 σ_{sta}^2 , and σ_{rec}^2 are the inter-event, inter-station and record-to-record components of
84 variance, respectively. The parameter h in equation (2) represents a pseudo-depth
85 parameter that accounts for the saturation of Y when R_{epi} becomes small. In equations (1)
86 and (2), the parameters a , b , c , d , h , and the site coefficients $s_{1,2}$, as well as the
87 components of variance, are determined by applying the random effects model
88 [Abrahamson and Youngs, 1992; Chen and Tsai, 2002; Bindi et al., 2006]. The velocity
89 and the acceleration are measured in [m/s] and [m/s²], respectively. The local magnitude

90 range of the considered data set is 0.5-5.9. Since there is no evidence for earthquakes
91 with $M_L < 6.0$ in Turkey to produce surface ruptures and no systematic studies exist on
92 the determination of the extent of rupture for the events in our data set, in models (1) and
93 (2) we consider the hypocentral and epicentral distances instead of distance to fault. The
94 relationships have been derived for both M_L and M_w , and considering both the maximum
95 between the North-South and East-West horizontal components (H) and the vertical
96 component (V). Finally, since the focal mechanism of the earthquakes used is dominantly
97 strike-slip [Bohnhoff et al., 2006], no factor for the earthquake mechanism is included in
98 the attenuation models (1) and (2), that have to be considered valid for the strike-slip
99 regime.

100 **Results and Discussion**

101 Eight tables including the coefficients obtained for the empirical GrMPEs (1) and (2) are
102 provided as *Electronic Data Supplements*.

103 *Error distributions*

104 Figure 2 exemplifies the analysis of the variances for equation (1) in the case of
105 maximum horizontal SA, considering both M_L and M_w and the epicentral distance. The
106 results show that the total standard deviation σ_{tot} is mainly determined by the record-to-
107 record variability σ_{rec} . The record-to-record variability can be associated to both source
108 effects (e.g. directivity) and propagation effects. Since we analyzed small to moderate
109 size earthquakes recorded at far field distances, we think that the heterogeneities affecting
110 the propagation medium are the main source of the observed ground motion variability
111 for sites that belong to the same class. Figure 2 also shows the behavior of the standard
112 deviation of the inter-event distribution of error (σ_{eve}) with frequency. The inter-event
113 distribution of error, which weakly contributes to the total error, assumes a specific value

114 for each earthquake and it is due to the correlation between the errors for different
115 recordings of the same earthquake. Then, the value of σ_{eve} reflects the variability of the
116 ground motion between earthquakes having the same magnitude, and the analysis of σ_{eve}
117 as a function of frequency can provide some information about the variability of the
118 source characteristics. For $f < 1$ Hz, σ_{eve} increases with decreasing frequencies for both
119 Mw and M_L . For $1 \text{ Hz} \leq f \leq 5 \text{ Hz}$, σ_{eve} is almost constant and similar for both the Mw
120 and M_L regressions. For frequencies $> 5 \text{ Hz}$, σ_{eve} increases when the regression is
121 performed considering Mw, while it starts to increase only after 10 Hz when M_L is used.
122 The dependence of σ_{eve} with frequency can be explained by considering both the
123 frequency range spanned by the corner frequency f_c of the considered earthquakes [Figure
124 4 in Parolai et al., 2007] and the characteristic frequency band used for the computation
125 of M_L and Mw. In fact, considering the response of the Wood-Anderson seismometer
126 (which acts as a high pass filter for displacement with a corner frequency f_c at 1.25 Hz)
127 and the range of frequency in which most of the f_c are lying ($1 \text{ Hz} < f_c < 10 \text{ Hz}$), M_L
128 estimates reflect mainly source properties for frequencies between 1 and 10 Hz. The
129 increase of σ_{eve} when Mw is used for the regression, starts at lower frequencies because
130 Mw is estimated from the low frequency spectral level. It follows that earthquakes having
131 the same Mw can show differences in the spectral amplitudes at higher frequencies due to
132 stress-drop variations. Causes for the increase of σ_{eve} below 1 Hz are the low signal-to-
133 noise ratio of the acceleration spectra, the effect of the Wood-Anderson high-pass filter,
134 and the uncertainties affecting Mw for the largest earthquakes of the data set, due to the
135 too-narrow low-frequency plateau that is exploitable for the seismic moment estimation.

136 Another result from Figure 2 is that σ_{rec} for the Mw and M_L regressions are similar. This
137 was expected since σ_{rec} is not related to the source properties of a specific earthquake.
138 Considering that Figure 2 show that σ_{rec} provides the main contribution to σ_{tot} , it follows
139 that σ_{sta} has a negligible contribution, similar to σ_{eve} (see the Electronic Supplements).

140 *Stress drop dependence of σ_{eve}*

141 In order to investigate the influence of the stress drop on σ_{eve} , the inter-event error
142 distribution for the regression carried out on PGA, while considering the maximum
143 horizontal component, the epicentral distance and both M_L and Mw, is shown in Figure 3.
144 The source parameters $\Delta\sigma$ and M_0 are taken from Parolai et al. [2007]. We emphasise the
145 results obtained for PGA since this is the parameter that is most affected by stress-drop
146 variations. The errors, defined such that their absolute value must be greater than 10% of
147 the maximum absolute error, so as to make the graphical presentation clearer, are shown
148 in Figure 3 against M_L and the stress drop $\Delta\sigma$ of the circular Brune [1970] model for the
149 M_L regression, and against the seismic moment M_0 and $\Delta\sigma$ for the Mw regression. Figure
150 3 shows that, for a given M_L or Mw, the inter-event errors show the tendency to range
151 from negative (over-estimation) to positive (under-estimation) values, depending on $\Delta\sigma$.
152 Low stress drops are associated to negative errors while positive errors are observed for
153 high stress drops. The range spanned by $\Delta\sigma$ depends on magnitude and generally
154 increases with increasing magnitude.

155 *Site classification dependence of σ_{sta}*

156 The inter-station distribution is evaluated twice; first without considering the site
157 classification, and second after introducing the two site classes. The site classification
158 allows for a significant reduction of the errors, and the standard deviation of the error

159 distribution of GTF and SABO stations is reduced from 0.21 to 0.14. The inter-station
160 errors for the KOERI network are smaller than 0.1 and are less affected by the
161 classification. The coefficients for the calibrated SA models are provided in the
162 Supplement for 8 frequencies between 1 and 10 Hz.

163 *Empirical GrMPEs*

164 Figure 4 compares the predicted PGA for a rock site resulting from a $M_w=5.2$ earthquake
165 with the predictions from the Özbey et al [2004] (hereinafter Özb04) and Ambraseys et
166 al. [2005] (hereinafter Amb05) relationships. We selected $M_w=5.2$ because it is larger
167 than the minimum magnitude for Özb04 and Amb05 ($M_w>5$), but the corresponding M_L
168 (about 5.5) is still within the range of validity of our model. Özb04 was derived by
169 considering the Kocaeli and Düzce earthquakes and their strongest aftershocks (17
170 earthquakes in all), whereas Amb05 was derived considering earthquakes that occurred in
171 Europe and Middle East. Both relationships are derived for $M_w>5$ and for the closest
172 distances from the fault. Since for a magnitude 5.2 the correction for the difference
173 between the epicentral distance and the closest distance from the fault is expected to be
174 negligible [Scherbaum et al., 2004], we do not apply any statistical corrections for the
175 difference between the metrics. A comparison with empirical GrMPEs derived for other
176 regions is beyond the aim of the present article. Anyway, a comparison between regional
177 empirical GrMPEs derived for similar tectonic regime in Western United States (e.g.
178 Sadigh et al. [1997]) can be found in Özb04. More recent comparisons can be found in
179 the reports of the Next Generation Attenuation (NGA) models project developed by the
180 Pacific Earthquake Engineering Research Center (PEER), available at
181 <http://peer.berkeley.edu>. Figure 4 shows that, for an earthquake of $M_w=5.2$, the Amb05
182 relationship is in good agreement with the local relationship calibrated in the present

183 study, whereas the Özb04 relationship under-estimates the PGA, especially at distances
184 <20 km. Indeed, in the Kocaeli earthquake the recorded near field ground motion levels
185 were lower than the ones predicted by empirical GrMPEs, while the recorded level were
186 in agreement with the empirical GrMPEs for larger distances [Durukal, 2002]. Since
187 Özb04 relationship uses records from $M > 5$ events from the Kocaeli sequence, the
188 discrepancy between our model and Özb04 model was expected. The agreement between
189 Amb05 and Özb04 improves with increasing M_w , and they are almost coincident for
190 $M_w = 7.4$. An attempt to extrapolate the relationship calibrated in this study to events of
191 $M_w = 7.4$ resulted in PGA values being overestimated with respect to the Amb05 and
192 Özb04, suggesting that extrapolating empirical GrMPEs to well outside their calibration
193 magnitude range is not viable.

194 **Conclusions**

195 New ground-motion prediction equations have been calibrated using a large data set of
196 aftershocks following the 1999 Kocaeli earthquake. To avoid the use of corrective factors
197 for the metrics and the earthquake size when parametric seismic catalogs are used for
198 hazard assessment studies, the models have been calibrated considering both the local
199 and moment magnitudes, as well as the epicentral and hypocentral distances. The
200 equations can be applied to Northwestern Turkey for events within the local magnitude
201 range 0.5-5.9 and for hypocentral distances up to 190 km. Although the magnitude range
202 spanned in this study may appear to limit the applicability of the obtained empirical
203 GrMPEs, we recall that recent moderate earthquakes have occurred in different regions of
204 the world (e.g., the September 7, 1999 $M_s = 5.9$ Athens earthquake; the 26 May, 2006 M_L
205 $= 6.2$ Indonesia earthquake), causing severe damage and loss of life and hence have
206 shown the importance of reliable local ground-motion prediction equations for the

207 earthquake hazard assessment. The earthquake hazard in Northern Marmara is dominated
208 by the North Anatolian Fault. The probability of occurrence of a $M > 7$ earthquake within
209 the next 30 years is estimated as (40-65%) [Parsons, 2004]. This certainly does not
210 exclude the possibility that moderate size earthquakes take place near Istanbul and
211 elsewhere in Northwestern Turkey. In terms of the study area covered in this work, a
212 moderate earthquake occurring in the vicinity of Istanbul may lead to considerable
213 building damage, casualties and losses. The development of adequate empirical GrMPEs
214 for small to moderate size earthquakes is also important for Monte-Carlo-type
215 simulations involving ground motion predictions for a family of earthquake events
216 representative of regional earthquake statistics for a wide magnitude range. Such
217 considerations are particularly used in loss estimations carried out for insurance purposes.
218 Although it may be argued that the direct applicability of an empirical GrMPEs estimated
219 from aftershocks to independent events is questionable, this is certainly a research area
220 that needs further attention.

221 The analysis of the error distribution showed that the record-to-record component of
222 variance is the largest contribution to the variance of the calibrated ground- motion
223 models. Moreover, although the contribution of the inter-event component of error to the
224 total error is negligible, it is correlated to the stress-drop variability and it is higher when
225 the regressions are performed considering the moment magnitude than when local
226 magnitude is used.

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277 **Figure captions**

278 **Figure 1.** Top: Epicenter location (black dots), GTF and SABO seismological (triangles)
279 and KOERI strong motion (squares) stations. Bottom: local magnitude versus
280 hypocentral distance distribution.

281 **Figure 2.** Standard deviation σ_{tot} for the maximum horizontal SA (epicentral distance,
282 equation 2), considering M_L (gray line) and M_w (black line). The standard deviation σ_{eve}
283 (circle) of the inter-event distribution and the standard deviation σ_{rec} (square) of the
284 record-to-record distribution of error are shown for M_L (gray) and M_w (black).

285 **Figure 3.** Inter-event errors for the maximum horizontal PGA model, considering
286 epicentral distance. The amount of error is given by the color of the symbol. Top: M_w is
287 considered in the regression. The errors having absolute values >0.04 are shown as a
288 function of the stress drop $\Delta\sigma$ and the seismic moment M_0 of each earthquake. Bottom:
289 M_L is considered in the regression. The errors having absolute values >0.02 are shown as
290 a function of $\Delta\sigma$ and M_L . The source parameters are taken from Parolai et al. [2007].

291 **Figure 4.** Comparison between the mean PGA \pm one standard deviation predicted by
292 Ambraseys et al. [2005], Özbey et al [2004] and this study for a $M_w=5.2$ earthquake.







