Earthquake Occurrence in Geometrically Complex Systems

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Earthquake Occurrence in Geometrically Complex Systems

- Focus Earthquakes and slip with non-planar faults and fault systems
- Principal result: Complex geometry introduces several new system-scale processes that do not operate with single planar faults or small arrays of planar fault segments → very strong affect on the characteristics of earthquake occurrence

Two related efforts are underway

- 1) Development of a large-scale earthquake simulation of earthquake in fault systems
 - Computationally fast, quasi-dynamic
 - 10⁵-10⁶ earthquakes M3.5-M8.0
 - Rate-state friction → clustering including foreshocks and aftershocks
 - Complex geometry
- Interactions of complex faults with embedding media
 - Off-fault stress relaxation and seismicity

Southern California Earthquake Center (SCEC) Community Fault Model



100km

Region ~ 600x 400km

Total fault length > 5000km

Fast fault system earthquake simulator

- Boundary elements Okada
- ~35,000 fault elements (single processor G5)
 - § Detailed representation of fault network geometry
 - § Simulations of M3.5-8 for southern California
- 3D stress interactions
- Strike-slip, dip-slip and mixed mode fault slip
- Repeated Simulation of 10⁵ 10⁶ events
- Basic elements of rate-state friction
 - § Healing by log time
 - § Time- and stress-dependent nucleation
 - § Full representation of normal stress history effects
- Inputs
 - § Fault slip rate (currently loading by backslip)
 - § Rate-state parameters: *A*, *B*, (*Dc* does not enter equations)
 - § Elastic modulii, shear wave speed β , stress intensity factor for rupture

Fast fault system earthquake simulator

- Computations are based on changes of fault sliding state using the method of Dieterich (1995)
 - § 0 Locked fault: aging by log time of stationary contact
 - § 1 Nucleating slip: analytic solutions with rate-state friction
 - § 2 Earthquake slip: quasi-dynamic slip speed is fixed by shear impedance

$$\dot{\delta}_{EQ} = \frac{2\beta\Delta S}{G}$$

- No simultaneous equations to solve
 - S During earthquakes slip, the initiation or termination of slip at an element requires one multiply and one divide operation to update stressing rate conditions at every element

$$\dot{S}_i = K_{ij}\dot{\delta}_j$$
, where $K_{ij} = T_{ij} - \mu N_{ij}$

- § Computation time scales by N^{~1} where N is the number of elements
- § 100,000 events with 30,000 fault elements ~ 12hrs

M8 event on fault with 10,000 fault elements

2x vertical exaggeration

QuickTime™ and a GIF decompressor are needed to see this picture.

Simulation:

- 50,000 events, 10,000 elements
- M~4.0-8.0
- Implicit shear wave speed 3km/s
- Computation time ~ 60 minutes on Mac G5 using a single 2.2 GHz CPU

M8 events:

- Duration 215s, 204s
- Rupture speed 2.2–2.4 km/s

Magnitude – Frequency

Flat fault, 1500 fault elements



Stress change and slip in a M7.1 earthquake



This event, which ruptured nearly the entire fault surface, was followed by M6.5, M5.4 and M6.3 events 64, 82 and 96 seconds, respectively following the mainshock. In a real earthquake this tight clustering might be interpreted as a single composite earthquake event.



Composite plot of earthquake clustering formed by stacking the records of seismic activity relative to mainshock times [from Dieterich, 1995]. Events in excess of the background rate, normalized by the number of mainshocks.

Clustering in synthetic catalog



Waiting-time distribution of events \geq 7.0 are quasi-periodic with cov = 0.02 for single fault system. Aperiodicity of large increases with increasing numbers of faults

200 m Compressive Stepover All events M≥6.0





- End of first M7 event 27.9 s
- 21 aftershocks in interval between first and second M7 events
- Start of second M7 event 169 s

QuickTime™ and a GIF decompressor are needed to see this picture.



Slip and shear stress change for simulated M7.1 event on a fault with fractal fault roughness. Model is for strikeslip faulting (left-lateral) with 1,500 fault elements. This event was taken from a simulation with 50,000 earthquakes M3.5-M7.2. Nucleation occurred at the black element. System-scale phenomena with complex geometries Fault slip and off-fault seismicity

Individual faults exhibit approximately self-similar roughness



San Francisco Bay Region

System-scale phenomena with complex geometries Fault slip and off-fault seismicity

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San Francisco Bay Region

Fault systems also appear to be scale-independent



Fault in the Monterrey Formation

Random Fractal Fault Model







FAULT SEGMENTS





FAULT SEGMENTS

Backstress opposes slip and is proportional to slip. Slip saturates when the average backs stress S_{BACK} equals the stress that drives slip S_A



$$d_{\max} = c\beta^{-2}$$

$$S_{BACK} = S_A \frac{d}{\overline{d}_{MAX}}$$

$$S_{BACK} = \left(c\beta^2 S_A\right)d$$

Fault slip and stress changes



 $\Delta \sigma_{xy}$ _ 1

Yielding and Stress Relaxation

• Stresses due to heterogeneous slip cannot increase without limit - some form of steady-state yielding and stress relaxation must occur

RMS Slope $\propto \beta l^{H-1}$ Slope of 0.01 \rightarrow shear strain ≈ 0.01 , \rightarrow brittle failure

- In brittle crust, stress relaxation may occur by faulting and seismicity off of the major faults.
 - Ø Instantaneous failure and slip during earthquake
 - Ø Post-seismic aftershocks
 - Ø Interseismic background seismicity
- Yielding will couple to the failure process, by relaxing the back stresses

Steady-state yielding by earthquakes: $\beta = 0.10$ EQ rate \propto Coulomb stress rate \propto Long-term slip rate

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Average long-term earthquake rate by distance from fault with random fractal roughness

- Stressing due to fault slip at constant long-term rate
- Model assumes steady-state seismicity at the long-term stressing rate, in regions where $\dot{S} > 0$



Average long-term earthquake rate by distance from fault with random fractal roughness



Aftershocks Earthquake rates following a stress step

Earthquake rate
$$R = \frac{r}{\gamma \dot{S}_r}$$
, $d\gamma = \frac{1}{A\sigma} [dt - \gamma dS]$

Following a stress step

$$R = \frac{r}{\left[\exp\left(\frac{-\Delta S}{A\sigma}\right) - 1\right] \left[\exp\left(\frac{-t}{t_a}\right)\right] + 1}$$

Immediate aftershocks at *t*=0

$$\frac{R}{r} = \left[\exp\left(\frac{\Delta S}{A\sigma}\right) - 1 \right]$$

Dieterich, JGR (1994), Dieterich, Cayol, Okubo, Nature, (2000)

Initial Aftershock Rate / Background Rate







Rate-State Stress Relaxation

Concept for stress relaxation: Assume stresses fluctuate around a steady-state condition where the long-term growth of interaction stresses due to fault slip is balanced by off-fault yielding.

Change of stress during earthquake



Elastic response



Rate-State Stress Relaxation

Concept for stress relaxation: Assume stresses fluctuate around a steady-state condition where the long-term growth of interaction stresses due to fault slip is balanced by off-fault yielding.



Rate-State Stress Relaxation

Relaxation rate is proportional to earthquake rate, $R \propto \dot{\sigma}$ where

$$R = \frac{r}{\gamma \dot{\tau_r}} , \qquad d\gamma = \frac{1}{a\sigma} \left[dt - \gamma dS \right]$$

Relaxation rate of individual stress components

$$\dot{\sigma}_{ij}^{R} = \frac{C_{ij}}{\gamma_{ij}}, \quad d\gamma_{ij} = \frac{1}{a\sigma} \left[dt - \Lambda_{ij}^{\pm} \gamma_{ij} d\sigma_{ij} \right]$$
$$\Delta \sigma_{ij}^{R}(t) = -C \int \frac{1}{\gamma_{ij}(t)} dt$$

Factors C and Λ vary spatially.

C is set to make net long-term stressing (from tectonic loading, fault slip, and off-fault relaxation) equal to zero.

Λ is a sign function with values of ±1. $Λ_{ij}^{\pm} = +1$ if long-term slip → stress increase -1 if long-term slip → stress decrease

Off-fault stress relaxation for a full earthquake cycle t_a=11 yr, T=150 yr



Off-fault stress relaxation for a full earthquake cycle t_a=11 yr, T=150 yr



Off-fault stress relaxation for a full earthquake cycle t_a=11 yr, T=150 yr



Off-fault stress relaxation for a full earthquake cycle t_a =11 yr, T=150 yr



Stress change due to slip



















Slip due to remote tectonic loading (no stress relaxation)



Slip due to remote tectonic loading (no stress relaxation)





Slip due to remote tectonic loading (no stress relaxation)





Slip due to remote tectonic loading (no stress relaxation)







• Partitioning between far field loading and off-fault yielding is controlled by fault geometry

Asig=2 bar

- Partitioning among relaxation processes is controlled by A $\!\sigma$



Evidence for Time Dependence of Stress Heterogeneity



Modified from (Woessner, 2005)









