

1 In-situ tryptophan-like fluorometers: assessing
2 turbidity and temperature effects for freshwater
3 applications

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5 **Khamis, K.^{1,2*}, J.P.R. Sorensen³, C. Bradley¹, D.M. Hannah¹, D.J.Lapworth³, R.**
6 **Stevens²**

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9 **1. School of Geography Earth and Environmental Science, University of**
10 **Birmingham, Birmingham, B15 2TT, UK**

11 **2. RS Hydro Ltd, Leask House, Hanbury Road, Stoke Prior, Worcestershire, B60**
12 **4JZ, UK.**

13

14 **3. British Geological Survey, Maclean Building, Wallingford, Oxfordshire, OX10**
15 **8BB, UK**

16

17 *corresponding author: tel: +44 (0) 121 414 5557; e-mail: k.khamis@bham.ac.uk

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1 **Abstract**

2 Tryptophan-like fluorescence (TLF) is an indicator of human influence on water quality as
3 TLF peaks are associated with the input of labile organic carbon (e.g. sewage or farm waste)
4 and its microbial breakdown. Hence, real-time measurement of TLF could be particularly
5 useful for monitoring water quality at a higher temporal resolution than available hitherto.
6 However, current understanding of TLF quenching/interference is limited for field
7 deployable sensors. We present results from a rigorous test of two commercially available
8 submersible tryptophan fluorometers (ex ~285, em ~350). Temperature quenching and
9 turbidity interference were quantified in the laboratory and compensation algorithms
10 developed. Field trials were then undertaken involving: (i) an extended deployment (28 days)
11 in a small urban stream; and, (ii) depth profiling of an urban multi-level borehole. TLF was
12 inversely related to water temperature (regression slope range: -1.57 to -2.50). Sediment
13 particle size was identified as an important control on the turbidity specific TLF response,
14 with signal amplification apparent <150 NTU for clay particles and <650 NTU for silt
15 particles. Signal attenuation was only observed > 200 NTU for clay particles. Compensation
16 algorithms significantly improved agreement between *in-situ* and laboratory readings for
17 baseflow and storm conditions in the stream. For the groundwater trial, there was an excellent
18 agreement between laboratory and raw *in-situ* TLF; temperature compensation provided only
19 a marginal improvement, and turbidity corrections were unnecessary. These findings
20 highlight the potential utility of real time TLF monitoring for a range of environmental
21 applications (e.g. tracing polluting sources and monitoring groundwater contamination).
22 However, in situations where high/variable suspended sediment loads or rapid changes in
23 temperature are anticipated concurrent monitoring of turbidity and temperature is required
24 and site specific calibration is recommended for long term, surface water monitoring.

25 **Keywords: Fluorescence, water quality, optical sensors, in-situ monitoring, temperature**
26 **quenching, light scattering, surface water, groundwater.**

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1 Introduction

2 Due to the recent developments in field-deployable optical sensor technology, continuous
3 quantification and characterisation of dissolved organic matter (DOM) is now possible¹⁻³.
4 Tryptophan-like fluorescence (TLF), at excitation (emission) wavelengths of ~280 nm (~350
5 nm), has been identified as a useful indicator of human influence on surface water^{4,5} and
6 groundwater quality⁶⁻⁸. In urban or agricultural habitats TLF peaks are often associated with
7 the input of labile organic carbon (e.g. sewage or farm waste) and products of its microbial
8 breakdown⁵. The precise composition of the constituent compounds associated with TLF is
9 still debated (most likely a heterogeneous mixture of free amino acids and proteinaceous
10 materials)⁹. Nevertheless, strong correlations between TLF and a range of water quality
11 parameters have been reported including: Biological Oxygen Demand (BOD)^{5,10}; Chemical
12 Oxygen Demand (COD)^{10,11} and bacteria index organisms¹². Hence, real-time recording of
13 TLF could potentially be invaluable for monitoring waste water and drinking water treatment
14 processes, identifying *inter-alia* cross connected sewers and contamination events, at higher
15 temporal resolution than available hitherto^{11,13}. However, despite the potential utility of this
16 new sensor technology, particularly when compared to traditional wet chemistry methods,
17 relatively little is known about performance in the laboratory or field.

18 Compared to marine systems, where many commercially available fluorometers were
19 designed to be deployed, the environmental conditions of freshwater systems can be highly
20 dynamic in space and time^{14,15}. Hence, there are a number of challenges associated with
21 monitoring fluorescence in freshwaters that need careful consideration before sampling
22 regimes are designed or measurements interpreted^{16,17}. In particular, the optical properties of
23 fluorescent molecules or compounds (fluorophores) have been shown to display sensitivity to
24 a wide range of quenchers (dynamic/ static) and 'matrix effects'¹⁷⁻¹⁹.

25 The influence of solution or matrix temperature on fluorescence intensity has long been
26 recognised²⁰. Higher temperature increases collisional quenching and thus the chance that an
27 excited electron will return to the ground energy state via a radiationless pathway^{21,22}. A
28 recent study has indicated that diurnal temperature variations are a key driver of uncorrected
29 observation of diel CDOM (Chromophoric Dissolved Organic Matter) cycles and, in the
30 absence of correction, spurious inferences regarding biogeochemical processing may be
31 made²³. However, while temperature compensation methods have been developed and
32 corrections applied to *in-situ* fluorometer records, the degree to which variability in: (i) DOM
33 composition; and, (ii) sensor specific optical design and configuration, influences correction
34 factors requires further study^{16,23,24}.

35 Suspended particles in the water column constitute another key challenge to *in-situ*
36 monitoring of TLF and can cause both increased scattering and attenuation of excitation and
37 emission light¹. A recent study investigating the challenges to deployment of *in-situ* CDOM
38 fluorometers identified that at > 400 NTU (water turbidity was used a surrogate for
39 suspended particle concentration) the fluorescence signal can be reduced by ~80%¹⁶. Yet
40 despite the influence of particle size and shape quantifying suspended sediment (SS)
41 concentration using optical technologies²⁵, the influence of such properties on TLF remains
42 unknown. Saraceno et al.¹ highlighted the potential for in-line filtration of water samples as a
43 method to remove particle interference. Analysis is possible bankside, using thru-flow
44 fluorometers; however, the frequency of filter replacement and maintenance requirements in
45 high sediment environments may render this approach impractical in urban systems with high
46 SS loads²⁶. Hence, further work is needed to constrain algorithms for correcting unfiltered
47 optical systems¹⁶.

1 Given the need for high temporal resolution records of DOM²⁷, real-time sensor technologies
2 provide an increasingly viable and cost effective solution. However, proof of concept through
3 rigorous testing is urgently required as Tryptophan-like fluorometers are already beginning to
4 be adopted by academics and practitioners alike. Furthermore, as changes to European
5 legislation increasingly put the onus of water quality compliance on industry, a cost effective
6 and robust solution for monitoring waste water discharge and infrastructure is required²⁸.
7 Hence, it is clear that an understanding of sensor measurement repeatability/transferability
8 and interaction with environmental parameters (e.g. temperature and SS) is needed including
9 correction of quenching/ matrix interference¹⁶. To address this knowledge gap rigorous
10 laboratory tests, conducted on two commercially available, submersible tryptophan-like
11 fluorometers, were undertaken coupled with field trials involving: (i) deployment in a
12 ‘flashy’ urban river, (the Bourn Brook, Birmingham, UK) with aging waste water
13 infrastructure and known water quality problems^{21,29}; and (ii) an urban multi-level borehole
14 with low levels of sewage associated microbial contamination³⁰.

15 **Methods**

16 **Sensor characteristics**

17 Laboratory and field trials were conducted on two commercially available tryptophan-like
18 field fluorometers. The sensors: Cyclops 7TM (Turner Designs, Sunnyvale, USA) and UviLux
19 (Chelsea Technologies Group Ltd., West Molesey, UK), are herein referred to as TU and CH,
20 respectively. The key optical, mechanical and electrical specifications are summarised in
21 Table 1. Briefly, the differences between the sensors included sensor size, weight, output of
22 the light-emitting diodes (LEDs), wavelengths of the excitation and emission peaks, unit age
23 and manufacturer specified minimum detection limit and dynamic range (Table 1).
24 Furthermore, sensor CH houses a photomultiplier tube and in this study was used as a stand-
25 alone unit whereas TU was integrated with a multi-parameter Sonde (Manta 2, Eureka
26 Environmental, Austin, USA). For initial calibration experiments and borehole tests two units
27 for each manufacturer were used and are referred to as TU1, TU2, CH1 and CH2. For the
28 temperature, turbidity and Bourn Brook trials, TU2 was not available.

29 **Standard solutions and calibration**

30 Calibration standards were prepared using L-tryptophan, purchased from Acros Organics,
31 USA ($\geq 98\%$), and Milli-Q ultra-pure water ($18.2\text{ M}\Omega^{-1}$). A tryptophan stock solution (1000
32 ppm) was used to prepare standards that ranged from 1 – 1000 ppb. Standard solutions were
33 prepared daily, while the stock solution was stored at 4 °C for a maximum of 72 hrs. Before
34 analysis all standards were equilibrated in a temperature controlled dark room (20°C) and
35 their temperature confirmed using a HI 935005 meter (Hannah instrument, Rhode Island,
36 USA: accuracy $\pm 0.2\text{ }^{\circ}\text{C}$). All solutions had a final volume of 1 L and were stored in acid
37 washed (HCl 0.5 M), glass volumetric flasks. Measurements of standard solutions were
38 completed in a 2 L glass beaker placed within a non-reflective black bucket to avoid spurious
39 readings due to scattering and reflection. Sensors were clamped to ensure measurement
40 location within the beaker was consistent between readings. Solution temperatures were
41 periodically checked throughout the measurement runs to account for any increase in
42 temperature. For the measurement of each standard the sensor was allowed 1 min to stabilize,
43 before logging 10 readings at 10 s intervals. Between each solution measurement the sensors
44 and beaker were thoroughly rinsed in ultra-pure water and the optics wiped with a lens cloth.
45 The measurement series was repeated twice on separate days and varied by an average of ~ 3
46 %. A 10 mL sub-sample was taken from each standard solution and TLF intensity

1 determined, within 1 hr, using a bench-top scanning fluorometer (see below for analytical
2 procedure).

3 **Assessment of temperature effects**

4 To determine the effect of temperature on the TLF signal of the experimental sensors,
5 readings were logged over a warming and cooling cycle that ranged from 5-35 °C for four
6 tryptophan concentrations (10, 25, 50 and 100 ppb). Sensors and standard solutions were first
7 cooled in a dark room at constant temperature (5 °C) and then transferred to a MLR-352,
8 294L programmable incubator (Sanyo, Osaka, Japan). The sensors were interfaced with a CR-
9 1000 data logger (Campbell Scientific, Logan, USA: 1 min logging) and submerged in a 2L
10 glass beaker containing 1L of tryptophan standard. A thermistor (Campbell Scientific, 107-L:
11 ± 0.2 °C) was also submerged in each beaker and interfaced with the data logger. For each
12 concentration run (n = 4) the temperature was gradually increased to 35 °C over a period of 4
13 hrs and then cooled to 5 °C at the same rate²³.

14 **Assessment of turbidity effects**

15 Two sediment types were chosen for the experiment based on particle sizes that are
16 commonly observed during baseflow and high flow conditions in urban river systems³¹⁻³³: (i)
17 Fuller's Earth, a clay material ($D_{50} = 11.9\mu\text{m}$); and, (ii) silt collected from the outwash of a
18 retreating glacier ($D_{50} = 52.1\mu\text{m}$). Following Gray et al.³⁴, sediments were first treated with
19 30 % Hydrogen peroxide (H_2O_2) to remove any organic material. The treated sediments were
20 then rinsed in deionised water and dried in an oven at 65°C.

21 The impacts of turbidity were assessed for seven standard solutions (0, 10, 25, 50, 100, 250,
22 500 ppb) with independent runs for the two sediment types. Prior to measurement, all sensors
23 and solutions were equilibrated in a temperature controlled darkroom (20 °C). Subsequently,
24 standard solutions (1 L) were transferred to a 2 L glass beaker and constantly stirred on a
25 magnetic stir plate. Weighed sediment was added incrementally (n = 14) to each standard to
26 give a range of turbidity (0 - ~1000 NTU). For each increment, turbidity was measured on
27 five occasions using a nephelometric turbidimeter (McVan; Analite NEP 390, Scoresby,
28 Australia, ± 1%). The sensors were given 1 min to stabilize, before taking 5 readings at 10 s
29 intervals. During the experimental runs, all sensors (fluorometers and turbidimeter) were
30 suspended at a fixed location in the beaker to avoid edge effects. Temperature was measured
31 periodically during each run to account for any warming due to the sustained stirring.

32 **Development of correction factors**

33 *Temperature*

34 Two approaches were adopted to develop correction factors to compensate for thermal
35 quenching of the fluorescence signal. First, Ordinary Least Squares (OLS) Regression was
36 used to model the relationship between temperature and TLF signal for each reference
37 standard^{23,35}. The ratio of the slope:intercept (m/c) has been shown to be relatively constant
38 regardless of fluorophore concentration and thus provides a robust temperature compensation
39 coefficient²³. Following Watras et al²³ fluorophore concentration can be temperature
40 compensated using the following equation:

$$TLF_{ref} = \frac{TLF_{mes}}{1 + \rho(T_{mes} - T_{ref})} \quad (1)$$

41

1 Where TLF is tryptophan concentration (ppb), T is temperature ($^{\circ}\text{C}$) and subscripts mes and
 2 ref represent the measured and reference values respectively. As the calibration and turbidity
 3 experiments were conducted at 20°C this was chosen as the reference temperature for this
 4 study, thus $T_{ref} = 20^{\circ}\text{C}$ and TLF_{ref} represents the tryptophan concentration at 20°C . Hence, ρ
 5 is calculated as the quotient (m/c) at the reference temperature. Therefore, in this study the
 6 intercept used was calculated by solving the linear regression equation for $T = 20$.

7 Second the relationship between temperature and TLF quenching was modelled using an
 8 exponential relationship of the form:

$$TLF_{mes} = TLF_{std} e^{\alpha(T_{mes}-T_{ref})} \quad (2)$$

9

10 Where TLF_{std} is the concentration of the tryptophan standard solution and the decay constant
 11 (α) is estimated using nonlinear least squares regression. TLF_{ref} was subsequently
 12 calculated as follows:

$$TLF_{ref} = \frac{TLF_{mes}}{e^{\alpha(T_{mes}-T_{ref})}} \quad (3)$$

13

14 *Turbidity*

15 Prior to model development, the data were split on the basis of turbidity to create 14 groups
 16 of similar NTU. The 95% confidence interval overlap between sensor specific turbidity
 17 concentration runs was then tested. Here the observed tryptophan value is analogous to the
 18 response variable in a linear model and the concentration (treated as a factor) is the predictor.
 19 When an overlap was detected (i.e. no significant difference between concentration) all
 20 values greater than or equal to the specific NTU were disregarded and the remaining data
 21 used to create the correction algorithm.

22 Due to the variability in turbidity response between sensors (see also¹⁶) and sediment types a
 23 a generalized relationship could not be obtained. Hence, a statistical model fitting approach
 24 was adopted and complex polynomial regression models were developed for CH1 and TU1
 25 (the sensors used in the urban river field trials) to provide correction values for scattering and
 26 attenuation of excitation and emission light related to suspended particles. The models
 27 consisted of two predictor variables: (i) turbidity (denoted below as a) and (ii) the measured
 28 tryptophan signal (denoted below as b); and the response variable, correction factor (cf) that
 29 represented the differences between the measured and the blank signal (i.e. 0 NTU).

30 Preliminary analysis of the turbidity response suggested that a 3rd order polynomial would be
 31 sufficient to model the data. A global model was first tested including all possible terms and
 32 interactions, followed by an iterative procedure to test all possible permutations of the terms
 33 in the global model. As we were wary of over fitting the model, the best correction algorithm
 34 was considered to be that which included only significant parameters ($P < 0.05$), retained
 35 high explanatory power, and had normally distributed residuals³⁶. The final models for silt
 36 [eq. 5] and clay [eq. 6] were of the following forms:

$$Cf = a+ab+a^2+a^2b^2+b^3+a^3b^2 \quad (4)$$

37

$$Cf = a + ab + a^2 + a^2b^2 \quad (5)$$

1 Data were then corrected by subtracting the Cf (for the corresponding the turbidity and
2 observed TLF signal) from the observed TLF signal.

3 **Field trials**

4 *Urban Stream*

5 To assess the impact of: (i) field conditions on laboratory calibrated sensor readings and (ii)
6 the suitability of the laboratory derived correction algorithms, continuous records and discrete
7 samples were collected from the Bourn Brook, a tributary of the River Rea, Birmingham, UK
8 ($52^{\circ}27'N$, $1^{\circ}54'W$) between 23rd Sept. -15th Oct. 2014. Carstea et al.³⁷ provide a detailed
9 description of the basin characteristics; the catchment is 27.9 km² in area and urban/suburban
10 land use covers ~80% of the basin³⁸. There are no wastewater treatment works within the
11 catchment, but an extensive network of storm sewers and combined sewer overflows
12 discharge to the main channel. Fluorometers TU1 and CH1 were deployed alongside: (i) a
13 turbidimeter (Analite NEP 390), (ii) an integrated water temperature and electrical
14 conductivity probe (247-L, Campbell Scientific); and (iii) a vented pressure transducer
15 (CS420-L, Druck Inc., Billerica, Massachusetts). On three occasions, when high flow was
16 anticipated, discrete 500 mL samples were collected at 30-60 min intervals, using an
17 automatic pump sampler (3700, ISCO, Lincoln, USA). Samples were retained in acid washed
18 HDPE bottles and kept cool within the pump sampler using ice packs. Samples were returned
19 to the Water Sciences laboratory at the University of Birmingham for analysis within 24 hrs
20 of collection. During Event 2 (see Fig. 5) six bulk water samples (10 L) were collected at
21 roughly 1.5 hr intervals during the rising and falling limbs of the hydrograph. Bulk samples
22 were then analysed for particle size distribution using a Mastersizer 2000 (Malvern
23 Instruments, Malvern, UK) following methods outlined by Phillips & Walling³⁹.

24 *Borehole*

25 The borehole used in this study is located in Nottingham, UK ($52^{\circ}59'N$, $1^{\circ}10'W$) and
26 penetrates through the 42 m sequence of the unconfined Sherwood Sandstone Group
27 aquifer³⁰. There are multiple mudstone beds through the sequence, with the most significant
28 positioned at 32 m below ground level (m bgl), which confines the underlying sandstones.
29 The borehole is completed as a multi-level piezometer to enable samples to be obtained from
30 eight specific intervals from 8.0-39.1 m bgl. In this locality, the aquifer is adversely impacted
31 by sewer and septic tank leakage with bacteria index organisms and viruses detected
32 throughout the sequence, but being more frequent at shallower depths³⁰.

33 Groundwater samples (~5L) were obtained from each piezometer, starting with the deepest,
34 following the purging of three equivalent interval volumes. Samples were collected in an
35 acid-washed black bucket (HDPE; previously confirmed not to leach fluorescent substances)
36 in which field fluorometers, turbidimeter, thermometer (HI 935005), and pH and electrical
37 conductivity (EC) sensors were submerged in-turn. All sensors were rinsed with the sample
38 prior to submergence. Five TLF and turbidity readings were taken at 10s intervals, having
39 allowed 30s for the sensors to stabilise. Finally, a fresh 10mL sample was collected for each
40 depth, kept in a cool box with ice, and analysed at the Birmingham Water Sciences
41 Laboratory within 24hrs of collection.

42

1

2 Analytical procedure and data processing

3 All field samples were filtered through Whatman GF/F glass fiber filter papers (pore size
4 0.7µm) that had previously been rinsed in HCl and ultra-pure water then oven dried at 105°C.
5 Calibration standards and field samples were equilibrated in a temperature controlled lab
6 (20°C) before analysis. UV – Visible absorbance spectra were collected using 10mm path
7 length quartz cuvettes on a Jenway 6800 dual beam spectrophotometer. Scans were
8 conducted between 200 – 850nm and continuously referenced to an ultra-pure water blank.
9 For river samples dissolved organic carbon (DOC) was measured using a Shimadzu TOC-V
10 CSH total organic carbon analyzer (Kyoto, Japan). Samples were acidified to pH 2,
11 combusted at high temperature (0.5% platinum catalyst) and non- dispersive IR detection
12 used to quantify DOC concentration. Replicate DOC readings (n = 3-5) indicated the
13 coefficient of variation was ≤3%. Specific UV absorbance (SUVA₂₅₄) was calculated
14 following Carstea et al³⁷.

15 Excitation-Emission Matrices (EEMs) were measured for each sample using a Varian
16 Spectrofluorometer (Cary Eclipse) set to a scan rate of 9600 nm/min and photomultiplier tube
17 voltage of 725V. A Raman blank (sealed cell) was recorded each instrument run and used to
18 calibrate fluorescence intensity⁴⁰. Standards and samples were excited between 200 nm and
19 400 nm (5 nm slit width), emission recorded 280–500 nm (2nm slit width). EEMs were blank
20 subtracted, corrected for inner-filter and instrument-specific spectral bias in Matlab (version
21 2011a) using the drEEM toolbox, following the protocol outlined by Murphy et al.⁴¹. TLF
22 intensity was then extracted for the wavelength pairs matching those of the TLF fluorometers
23 used in the study.

24

25 Statistical analysis

26 The minimum detection limit (MDL) of each sensor was calculated based on 10 replicate
27 measurements of a series of low concentration samples (0 - 5ppb) following Pellerin et al.⁴².
28 Sensor precision was calculated as one over the coefficient of variation (i.e. precision =
29 1/CV) for repeated measurements (n = 10) taken for a low concentration (5 ppb) tryptophan
30 standard¹⁴. Sensor accuracy was calculated as one over the root mean square error (see
31 Equation 3) of the calibrated relationship (i.e. accuracy = 1/RMSE). Thus, for both sensor
32 accuracy and precision a higher value represents greater accuracy/precision. Analysis of
33 Variance (ANOVA) was used to test for differences between the MDL of the sensors. The
34 students t-test was adopted to test for difference between slopes (temperature quenching
35 experiment) and temperature compensation factors for each sensor individually.

36 A suite of model efficiency statistics were employed to evaluate the performance of the
37 temperature correction models following Moriasi et al.⁴³. The Nash-Sutcliffe coefficient
38 (NS) for each model was calculated as follows:

$$NS = 1 - \frac{\sum_{i=1}^n (Y_i^{obs} - Y_i^{sim})^2}{\sum_{i=1}^n (Y_i^{obs} - Y^{mean})^2} \quad (6)$$

39

40 Percent bias (PBIAS) was estimated using:

$$PBIAS = \frac{\sum_{i=1}^n (Y_i^{obs} - Y_i^{sim})}{\sum_{i=1}^n (Y_i^{obs})} \quad (7)$$

1

2 and the RMSE error to observation SD ratio (RSR):

$$RSR = \frac{RMSE}{STDEV_{obs}} = \frac{\sqrt{\sum_{i=1}^n (Y_i^{obs} - Y_i^{sim})^2}}{\sqrt{\sum_{i=1}^n (Y_i^{obs} - Y^{mean})^2}} \quad (8)$$

3

4 Where Y^{obs} and Y^{sim} are the observed and corrected records respectively for n data records.
 5 PBIAS <10% and RSR <0.5 were considered to represent very good simulations⁴³.

6 To test the relationship between the submersible sensors during the surface water trial,
 7 Generalized Least Squares (GLS) regression was used. The regression model was of the
 8 following form:

$$C_{lab} = \alpha + \beta C_{field} + \varepsilon \quad (9)$$

9

10 Where C = tryptophan concentration (ppb), α = the intercept, β = the regression coefficient
 11 and ε = the error term. Errors were treated as first order autoregressive correlation structures
 12 based on inspection and interpretation of autocorrelation functions⁴⁴. To test the performance
 13 of the correction factors (turbidity and temperature) on the field data, RMSE and PBIAS was
 14 calculated for each event individually and all events combined. All plotting and statistical
 15 tests were carried out using R version 2.15.2⁴⁵.

16 Results and discussion

17 Response to calibration standards

18 All sensors tested displayed highly significant linear relationships ($R^2 > 0.95$, $P < 0.001$) with
 19 tryptophan concentration across the tested range (i.e. 0 -1000 ppb for TU1, TU2, CH1 and 0-
 20 800 ppb for CH2) and no signal saturation or inner filtering effects were apparent (Fig. S1).
 21 When converted to Raman Units (R.U) the upper limit of 1000 ppb equated to ~2 R.U, which
 22 is a useful linear range for tracking point source pollution in both agricultural⁴⁶ and urban
 23 environments⁴⁷.

24 For the calibration curve and relationship with the Varian, all submersible sensor displayed
 25 similar slopes (~1) and intercepts (≤ 0.15); however it is important to note that sensor TU1
 26 was an older unit with an intercept significantly greater than the other three sensors (Table 2).
 27 This raises some important questions when considering the future development of real-time
 28 sensor networks, particularly the need to quantify inter-unit variability in optical
 29 configuration and deterioration of LED/photodiode efficiency⁴⁸.

30 Minimum detection limits were significantly lower for CH sensors when compared to TU
 31 sensors (ANOVA; $F_{1,22} = 129.7$, $P < 0.001$; Table 2). Sensor precision (1/CV) was greater for
 32 CH sensors compared to TU sensors (Table 2). Measurement accuracy (1/RMSE of the
 33 calibration curve) was greater for CH sensors when compared to TU sensors (TU sensors +
 34 0.05 ppb; Table 2). Differences in the sensitivity and MDL can largely be attributed to sensor

1 CH housing a photomultiplier tube¹⁸, thus significantly increasing the intensity of emission
2 light (Table 2). However, when planning field monitoring campaigns the greater sensitivity
3 needs to be considered in combination with the increased size and weight of the unit relative
4 to sensor TU (Table 1), making CH less readily integrated into a multi-parameter sonde for
5 concurrent water temperature and turbidity measurement.

7 **Temperature response and correction models**

8 For all sensors tested (TU1, CH1 and CH2), TLF was negatively related to temperature and
9 mean OLS slopes ranged from -1.57 ± 1.05 (TU1) to -2.50 ± 1.59 (CH1) (Fig. 1). Hysteresis
10 loops were apparent for all sensors but were particularly pronounced for C sensors suggesting
11 that the increased thermal capacity of the sensor housing (larger size; Table 1) contributed to
12 lag times between solution and internal temperature of optics/electronics. Thermistor self-
13 heating⁴⁹ and insufficient manufacturer LED temperature correction⁵⁰ could also lead to
14 errors and potentially contributed to the hysteresis observed.

15 A linear function fitted the data well for all sensors ($R^2 > 0.9$); however, for CH1 and CH2
16 there was a suggestion of non-linear behaviour at extreme high and low temperatures ($>25^\circ\text{C}$
17 and $<10^\circ\text{C}$; Fig. 1). For both correction models the mean decay constant varied between
18 sensors with the highest and lowest mean values for CH1 ($\rho = -0.052$, $\alpha = -0.051$) TU1 ($\rho = -$
19 0.039 , $\alpha = 0.036$) respectively (Table 3). For individual sensors values of α and ρ were
20 comparable (see above) as were the CVs of α (range = 0.27 - 0.34) and of ρ (range = 0.27 -
21 0.37).

22 The changes in fluorescence intensity observed in this study are higher than those reported in
23 studies exploring the thermal quenching of humic-like material in the laboratory^{22,51} and
24 where fluorimeters have been deployed in the field ($\rho = -0.009 - -0.025$)^{16,23,52}. This marked
25 difference in temperature induced intensity attenuation highlights the need to consider DOM
26 composition when developing temperature correction algorithms and correcting field
27 data^{21,24,51}. This is also supported by a recent study that identified the importance of seasonal
28 changes in temperature compensation factors⁵². The results also suggest that temperature
29 quenching is more pronounced for TLF when compared to the fluorophore CDOM
30 submersible fluorimeters target²¹. Further work is required to explore the influence of
31 different matrix waters on the thermal quenching of TLF for submersible sensors and identify
32 potential errors associated with using an idealized, pure tryptophan standard (i.e. ultra-pure
33 water and a synthetic tryptophan standard).

34 The correction models for all sensors displayed positive bias, i.e. there was a tendency for the
35 corrected data to be greater than the reference data, but this varied between sensor and
36 correction model. While both correction approaches performed well for all sensors (Table 3),
37 the linear correction model performed slightly better than the exponential correction model
38 for TU1 and CH1 (i.e. lower NSE, RMSE and Bias) and the exponential model performed
39 slightly better for CH2. These results highlight the need for current users of tryptophan-like
40 fluorimeters to consider temperature effects during calibration and field measurement, and
41 ideally instrument specific correction algorithms should be developed pre/post deployment.
42 Furthermore, instrument manufactures should begin to develop internal temperature
43 correction factors, similar to those that are routine for electrical conductivity and pH
44 sensors⁵³.

1 **Turbidity response and correction models**

2 The effects of turbidity on TLF were pronounced and appeared to be non-linear, but stable
3 (i.e. smooth response shape and repeatable between tryptophan concentrations), across the
4 range tested during this experiment (Fig. 2). Differences in the response shape and magnitude
5 were greater between sediment types (i.e. clay vs. silt) than between sensor units (i.e. CH1 vs
6 TU1), though still apparent between the different sensors.

7 For the silt runs, the TLF signal increased rapidly to a maximum between 100-300 NTU
8 (depending on the sensor), and then decreased gradually to 1000 NTU with little evidence of
9 signal attenuation, likely due to stray light leaking through the emission filter. The response
10 was markedly different for the clay sediment; readings increased rapidly to a maximum
11 between 25-100 NTU then decreased rapidly to 600 NTU and reached an asymptote. Signal
12 attenuation was apparent at > 200 NTU (Fig. 3).

13 For the silt, TU1 (250 ppb standard) displayed the lowest increase in signal (75.3%) at $12.6 \pm$
14 2.2 NTU, while CH1 displayed the greatest increase (82.9 %), at 296.2 ± 7.7 NTU (Fig. 3).
15 Interestingly, at ~1000 NTU the TLF was attenuated for TU1 but was still amplified for CH1
16 relative to the 0 NTU reference.

17 For the clay, TU1 (250 ppb standard) displayed the lowest increase 7.2% increase observed at
18 32.9 ± 0.9 NTU while the greatest increase in TLF 20.6 % was observed for CH1 at $62.5 \pm$
19 9.6 NTU. At ~1000 NTU the sensor reading was less than the 0 NTU reference for both TU1
20 (73 %) and CH1 (70 %).

21 When considering these results in the context of the generalized equations and theories
22 describing the interaction of light and matter⁵⁴ there appears to be a plausible physical basis
23 for the observed patterns. In the experimental situation presented here (and in most
24 freshwater environments) particles are larger than the wavelength of the interacting UV light,
25 thus the Mie approximation can be adopted⁵⁵. Using this set of theoretical assumptions we
26 would expect the larger silt particles to scatter light more efficiently than the smaller clay
27 particles⁵⁵, hence the differences in response between the clay and silt are likely to be due to
28 increased stray light reaching the fluorometer photodiode for silt particles. This phenomenon
29 of stray light leaking through the emission filter has been reported for Chl *a* fluorometers
30 deployed in the marine environment^{56,57}. Another plausible hypothesis is that as the
31 adsorption capacity for proteinaceous material of clay particles is greater than silt particles⁵⁸,
32 an attenuated signal is observed for clay relative to silt.

33 The increase in TLF intensity at low to moderate turbidity observed in our study does not
34 conform with the findings of Downing et al¹⁶ or Saraceno et al¹ who both reported
35 attenuation of CDOM fluorescence intensity at both low and high turbidity. In a laboratory
36 study Downing et al¹⁶ reporting that at 35 NTU (clay-loam material) 22% of the fluorescence
37 signal was lost. Similarly, Saraceno et al¹ identified an 8% reduction at 50 NTU
38 (predominately clay-loam) in a field based study. It is possible that an organic coating on
39 particles could cause increased fluorescence at low to moderate turbidity; however, as we
40 removed these using KOH prior to running the experiment this mechanism appears not to
41 apply in this case (i.e. the increase in fluorescence intensity at low to moderate turbidity).
42 Therefore we propose the most plausible explanations for differences observed between the
43 two fluorometer types are (i) the shorter excitation wavelength (285nm) used in Tryptophan-
44 like fluorometers is scattered more efficiently (i.e. increased potential for stray light reaching
45 the photodiode⁵⁷) than the longer wavelength (360nm) used in CDOM fluorometers⁵⁵, and;
46 (ii) the removal of organic material from the experimental sediments (KOH treatment) used

1 in this study increased the ratio of ‘hard’ to ‘soft’ scatterers and thus reduced absorption
2 relative to the untreated sediments used by Downing et al²⁵.

3 For the silt dataset, 95% CI (confidence interval) overlap was detected for the 700-800 NTU
4 group for TU1, the 800-900 NTU group for CH1 and not detected for CH2. Hence, for
5 comparability between sensors all turbidity correction models were created for data covering
6 the range 0 -700 NTU. For the clay dataset 95% CI overlap was detected for the 200-300
7 NTU group for all sensors, thus, models were created for records ≤ 200 NTU. For each
8 sediment type the ‘best’ model consisted of the same terms for both sensors (silt: 7 terms;
9 clay: 5 terms). All models appeared to reproduce the response observed in laboratory data
10 reasonably well ($R^2 > 0.6$); however, the silt models displayed better agreement with the
11 laboratory data than the clay model (Table 4). Whilst the model parameters were similar for
12 both sensors when considering the silt particles, for the clay particles the model regression
13 surface highlighted a marked difference in the values of the regression parameters (Fig. 3).
14 This highlights the need for both site and sensor specific turbidity compensation.

15

16 **Field trials**

17 *Urban stream*

18 *In-situ records* - For the storm events characterized, ($n = 3$; Fig. 4), the maximum river stage
19 was recorded during Event 3 (0.54 m) and maximum turbidity during Event 1 (283.4 NTU).
20 For all events the relationship between stage and turbidity was complex, with secondary
21 peaks and ‘turbidity shoulders’ apparent, suggesting heterogeneous sediment sources⁵⁹.
22 However a reduction in maximum turbidity from event 1-3 suggests sediment exhaustion
23 may have occurred²⁶. Water temperature ranged between 11.1-13.7°C and storm events
24 appeared to interrupt the diurnal cycle (Fig. 4). Raw TLF was relatively low (predominately
25 <60 ppb) during base flow with the highest TLF value recorded during Event 1 of 175.8 ppb
26 and 136.5 ppb for CH1 and TU1, respectively (Fig. 4). In Event 1 a classic ‘first flush’ type
27 response was exhibited in which a large amount of labile organic matter was mobilized for a
28 modest increase in flow (Supplementary Fig. S2). This was likely due to low antecedent
29 rainfall (7 day = 1.6mm) enabling a build-up of organic material that was then rapidly flushed
30 from Combined Sewage Overflows (CSOs) and other drainage structures close to the
31 sampling point⁶⁰. A significant relationship between TU1 and CH1 was apparent (TU1: *co-*
32 *eff.* = 1.19 ± 0.03 , *t-value* = 36.75, $P < 0.001$); however, TU1 readings were lower during
33 baseflow and high flow periods, for all events, when compared to CH1 (Supplementary Figs.
34 S2-S4). The mean suspended sediment particle size ($54.16 \pm 17.15 \mu\text{m}$) for Event 2 is similar
35 to that of coarse silt; however, at low flow mean sediment size was smaller ($36.82 \mu\text{m}$;
36 medium silt) than at peak flow ($80.81 \mu\text{m}$; very fine sand).

37 *Relationship between laboratory and in-situ fluorescence* - The general pattern displayed in
38 the laboratory samples was similar to that of the *in-situ* sensors. Low TLF was recorded
39 during base-flow with an increase of between ~ 80 ppb (Event 1) and ~ 30 ppb (Event 3) during
40 storm flow conditions. For both CH1 and TU1, systematic over-estimation of *in-situ* TLF was
41 apparent when compared to the discrete, laboratory analysed, samples (Table 5; Fig. 5). The
42 temperature correction improved the agreement; however a significant positive bias (*in-situ* $>$
43 lab) was still apparent for both sensors but more pronounced for CH1 (Table 5), most likely
44 due to the increased sensitivity to suspended particles (Fig. 2). The combined temperature
45 and turbidity correction further improved agreement but, interestingly, the best fit appeared to
46 differ for TU1 (silt + T_w) and CH1 (clay + T_w). This may have been due to fine scale

1 hydraulic variability influencing SS particle size and load⁶¹ and as the turbidity sensor was
2 mounted in the sonde (close to TU1) it was likely more representative of conditions close to
3 TU1 rather than CH1. We therefore recommend, when possible, to adopt an integrated
4 monitoring platform such as a multi-parameter sonde to improve the accuracy of
5 compensation algorithms for surface water installations.

6 The agreement between *in-situ* and laboratory readings was generally improved when events
7 were considered individually (Table 5). It is important to note that for Event 2 samples are
8 distributed across the 1:1 line for both sensors when a silt correction is applied (Fig. 5) in
9 agreement with the mean D_{50} for this event ($54.16 \pm 17.16\mu\text{m}$; Supplementary Fig. S3).
10 When examining relationships between raw/ corrected (*in-situ*) and laboratory TLF; Event 1
11 displayed the least scatter and appeared to represent a classic first flush type response
12 (Supplementary Fig. S2)²⁶. Conversely for Events 2 & 3 scatter was apparent in the raw/ Tw
13 data and this was increased by turbidity correction. For both events rainfall was prolonged
14 with episodes of varying intensity, and turbidity dynamics were also complex
15 (Supplementary Figs. S3-4), suggesting multiple/varying sediment sources during these
16 events²⁶.

17 Changes in organic matter source, concentration and composition were also likely between
18 events, as DOC concentrations and $SUVA_{254}$ varied (Supplementary Fig.s S2-4). In particular
19 the changes in the $SUVA_{254}$ from Event 1 (2.01 ± 0.14) to Event 3 (2.84 ± 0.14) suggest an
20 increase in the hydrophobic, humic contribution to bulk DOM⁶². It has been suggested that to
21 represent changes in DOM quantity using a single Excitation - Emission pair the composition
22 must be stable, thus to represent DOM dynamics completely it may be necessary to explore
23 the use of multiple wavelength pairs⁴⁶. A particularly promising approach would be the ratio
24 of TFL to CDOM (peak T/C ratio) that can conceptually be considered a DOC/BOD
25 ratio^{37,48}. Furthermore increases in DOM concentration can lead to *in-situ* signal attenuation
26 due to inner filtering. While this was not explored in this study it has been suggested that at
27 $\sim 0.2 A_{254}$ (the maximum absorbance observed in this study) $\leq 10\%$ of the signal is attenuated
28 for CDOM sensors¹⁶.

29 *Groundwater test*

30 There was a clear gradient of decreasing TLF with depth for all submersible fluorometers
31 (Fig. 6). Changes in turbidity (0.45 ± 0.33 NTU; mean \pm SD), temperature (13.14 ± 0.53 °C),
32 and pH (7.8 ± 0.07) were minimal between intervals. SEC data show a similar depth profile
33 to TLF suggesting that increases in SEC are likely to be linked to waste water, i.e. leakage
34 from the sewer network and septic tanks. Furthermore, it appears that the mudstone band at
35 32 m bgl is limiting the ingress of wastewater deeper into the aquifer.

36 There was a strong correlation between laboratory and raw *in-situ* TLF for all fluorometers (ρ
37 > 0.95), with minimal differences (Fig. 6). Temperature correction of the data modified the
38 TLF by between 12 and 22%, for TU1 and CH1, respectively. However, this only marginally
39 improved the RMSEs given the low TLF (Fig. 6). This highlights the utility of *in-situ*
40 fluorometers for groundwater applications where, generally, temperature is perennially stable
41 and turbidity is very low. Consequently, correction factors may be unnecessary in many
42 groundwater systems, with the exception of shallow (e.g. riparian alluvials) and karstic
43 aquifers.

44

1

2 **Conclusions and recommendations**

3 This study has highlighted the potential utility of field deployable, tryptophan-like
4 fluorometers for monitoring surface- and ground- water quality. Due to their high sensitivity,
5 small size (portable), relatively low cost, and maintenance requirements, this technology has
6 distinct advantages enabling high resolution data in remote locations. There is; however, a
7 need to carefully consider ambient environmental conditions as TLF intensity is sensitive to
8 matrix water properties. Using laboratory and field data we have shown that with concurrent
9 monitoring of potential TLF interferents, field data can be standardized to improve accuracy.
10 Despite the apparent ease of this procedure it is important to remember that temperature
11 quenching is sensitive to fluorophore composition²⁴. Therefore when permanent (static)
12 installation is expected, matrix waters should ideally be used for deriving compensation
13 algorithms. If this is not feasible (i.e. when a fluorometer is used as a mobile unit) a
14 standardized material, such as L-tryptophan, is recommended. Furthermore manufacturers
15 should incorporate temperature compensation algorithms into frontend processing and
16 practitioners should correct field data to 20 °C, or at a minimum report ambient temperature
17 to allow comparisons between studies.

18 Our findings also highlight the sensitivity of TLF sensors to suspended particles and we
19 recommend that when high/variable suspended sediment loads or rapid changes are
20 anticipated concurrent monitoring of turbidity is required. Hence, for certain applications
21 (e.g. surface water monitoring) compensation algorithms are essential or if high turbidity is
22 expected in-line filtration may be the most viable option. While for other applications (such
23 as groundwater monitoring) this may not be necessary. Sediment particle size specific
24 responses to turbidity increases were also identified and warrant the need for both site and
25 instrument specific calibrations when undertaking long term monitoring. Furthermore, it is
26 important to acknowledge errors associated with compensation under high turbidity and
27 report these accordingly.

28 The results also suggest circumstances when differences between field and laboratory
29 measurements may be 'real', as larger biological particles (i.e. many microbial cells) have
30 been shown to make a significant contribution to TLF⁶³ and could be removed through
31 filtration. Hence, further work is required to optimize filter pore size to the size fraction TLF
32 is anticipated to predominate, whilst still accounting for inorganic particle interference.
33 Finally, we emphasize the need to consider carefully potential interferents and the likely
34 range to be exhibited; and if frequent high sediment loads (NTU > 650) are anticipated then
35 accuracy/repeatability may be severely impaired (i.e. pre-treated sewage). Hence, for surface
36 water applications without site specific calibration TLF sensors are best employed as
37 qualitative indicators of organic enrichment and can be used to trace point source pollution.
38 However, for treated effluents, natural waters (with site specific calibration), drinking water
39 infrastructure and groundwater aquifers quantitative *in-situ* monitoring of reactive DOM
40 using TLF submersible sensors represent a sensitive, cost-effective solution.

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3

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- 14

1 Table 1. Manufacturer stated properties (mechanical, optical and electrical) of the
 2 Tryptophan-like fluorometers used in this study.

3

	Turner (Cyclops 7)	Chelsea (UviLux)
Dimensions	22 x 145mm	70 x 149mm
Weight (in air)	142g	800g
Depth rating	300m	>50m
Path type (detector angle)	Open (90°)	Open (90°)
Excitation (nm) ± bandpass (nm)	285 ± 10	280 ± 30
Emission (nm) ± bandpass (nm)	350 ± 55	365 ± 50
Detection limit (ppb)	3.00	0.02
Dynamic range (ppb)	0 – 20000	CH1 0 - 1000, CH2 0 – 800
Supply voltage range	3-15 Vdc	3-15 Vdc
Power consumption	<0.3Watt	<1Watt
Signal output	0-5 Vdc	0-5 Vdc
Sensor age	TU1: 2 years, TU2: 1.5 years	CH1: 2 years, CH2: 2.5 years

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3 Table 2. Calibration, precision and accuracy data for laboratory trial based on standard solution prepared with synthetic tryptophan ($\geq 98\%$) in
 4 ultra-pure water ($18.2 \text{ M}\Omega^{-1}$).

	Turner 1	Turner 2	Chelsea 1	Chelsea 2
Calibrated relationship	$y = 0.997x - 0.133$	$y = 1x + 0.0009$	$y = 1x - 0.00007$	$y = 1x + 0.00006$
Relationship with Varian (ppb)	$y = 0.99x - 0.1255$	$Y = 1x + 0.0022$	$y = 1x + 0.0076$	$y = 0.99x + 0.0129$
Relationship with Varian (R.U)	$y = 0.002x + 0.0041$	$y = 0.002x + 0.0044$	$y = 0.002x + 0.0044$	$y = 0.002x + 0.0044$
MDL \pm SD	1.99 ± 0.53	1.92 ± 0.57	0.17 ± 0.06	0.19 ± 0.15
Precision (1/CV)	0.33	0.40	2.22	4.54
Accuracy (1/RMSE)	1.59	1.61	1.75	1.72

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6

1 Table 3. The slope, regression coefficients (temperature compensation) and model performance results for the linear and exponential correction
 2 models. CV = coefficient of variation, NSE = Nash-Sutcliffe Efficiency, RSR = Ratio of RMSE to the standard deviation of the observations and
 3 Bias % is the percent bias.

4

Sensor type	Unit (fluorophore)	Linear model				Model performance			Exponential model		Model performance		
		Slope (mean \pm SD)	CV	Temperature coefficient (mean \pm SD)	CV	NSE	RSR	Bias %	Decay constant (mean \pm SD)	CV	NSE	RSR	Bias %
Tryptophan	TU1 (L-tryptophan)	-1.57 \pm 1.05	0.67	-0.039 \pm 0.0145	0.37	0.93	0.27	10.6	-0.036 \pm 0.012	0.34	0.84	0.41	10.5
	CH1 (L-tryptophan)	-2.50 \pm 1.59	0.63	-0.052 \pm 0.0146	0.28	0.94	0.25	11.8	-0.051 \pm 0.015	0.28	0.87	0.36	16.3
	CH2 (L-tryptophan)	-2.06 \pm 1.44	0.70	-0.045 \pm 0.0123	0.27	0.94	0.23	11.0	-0.044 \pm 0.012	0.27	0.98	0.15	4.3

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Table 4. Turbidity correction model results. Here Cf is the correction factor, a is the turbidity (NTU) and b is the measured tryptophan-like fluorescence.

Sensor (sediment)	Formula	<i>F</i>	<i>R</i>	<i>P</i>
TU1 (Silt)	$Cf = a + ab + a^2 + a^2b^2 + b^3 + a^3b^2$	1573 _{6,214}	0.97	<0.001
CH1 (Silt)	$Cf = a + ab + a^2 + a^2b^2 + b^3 + a^3b^2$	2488 _{6,217}	0.98	<0.001
TU1 (Clay)	$Cf = a + b + a^2 + a^2b^2 + a^3$	65.4 _{5,194}	0.63	<0.001
CH1 (Clay)	$Cf = a + b + a^2 + a^2b^2 + a^3$	917.1 _{5,194}	0.83	<0.001

1 Table 5. Summary of regression goodness of fit metrics testing agreement between *in-situ*
 2 data correction methods and laboratory measurements.

3

		RMSE (ppb)		PBIAS (%)	
		TU1	CH1	TU1	CH1
All	<i>Raw</i>	31.46	49.6	49.6	82.2
	<i>Tw</i>	16.8	21.99	21.99	32.1
	<i>Clay</i>	26.1	18.28	33.6	-0.6
	<i>Silt</i>	11.02	18.52	-1.2	-20.4
Event 1	<i>Raw</i>	45.4	34.05	62.7	74.3
	<i>Tw</i>	20.43	23.19	27.6	31.4
	<i>Clay</i>	29.85	13.19	40.2	11.9
	<i>Silt</i>	10.02	29.15	8.41	-34.5
Event 2	<i>Raw</i>	27.59	63.54	47.2	112.9
	<i>Tw</i>	19.18	27.33	25.7	43.3
	<i>Clay</i>	30.64	14.7	43.1	-11.2
	<i>Silt</i>	11.56	16.55	3.3	17.2
Event 3	<i>Raw</i>	11.86	26.21	17.2	54.1
	<i>Tw</i>	8.19	6.88	9.8	10.3
	<i>Clay</i>	12.1	13.78	7.2	-23.5
	<i>Silt</i>	10.82	23.11	-15.5	-34.1

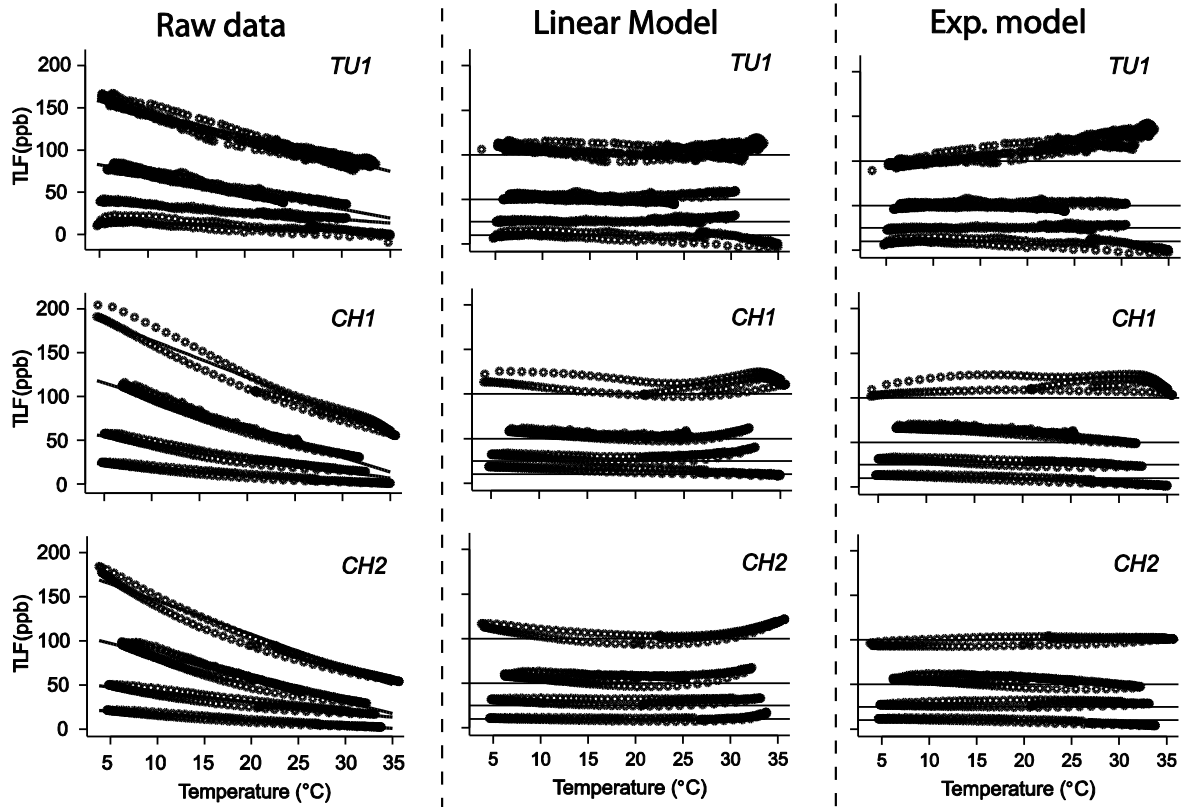
4

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2 Figure 1. Temperature effect on tryptophan-like fluorescence (TLF) at four concentrations
3 (10, 25, 50 and 100ppb) for three of the fluorimeters listed in Table 2. The experimental
4 temperature data (raw), ratio/linear temperature correction and exponential temperature
5 correction are displayed.

6



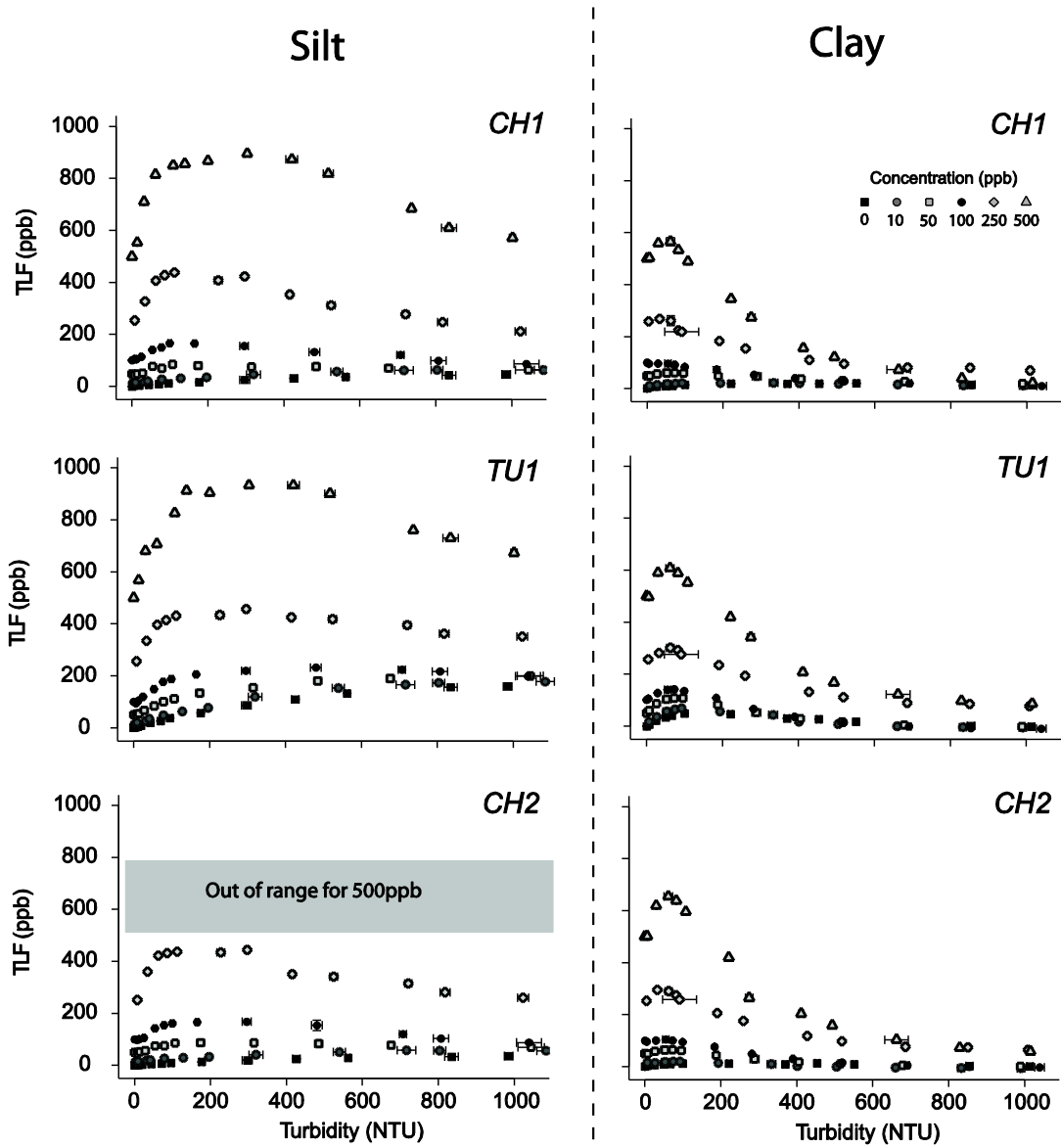
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2 Figure 2. Sensor response to turbidity for a range of tryptophan concentrations (0, 10, 50,
3 100, 250, 500ppb). Each panel represents an individual sensor and sediment combination.
4 Error bars displayed, horizontal and vertical, represent $\pm 1SD$.

5

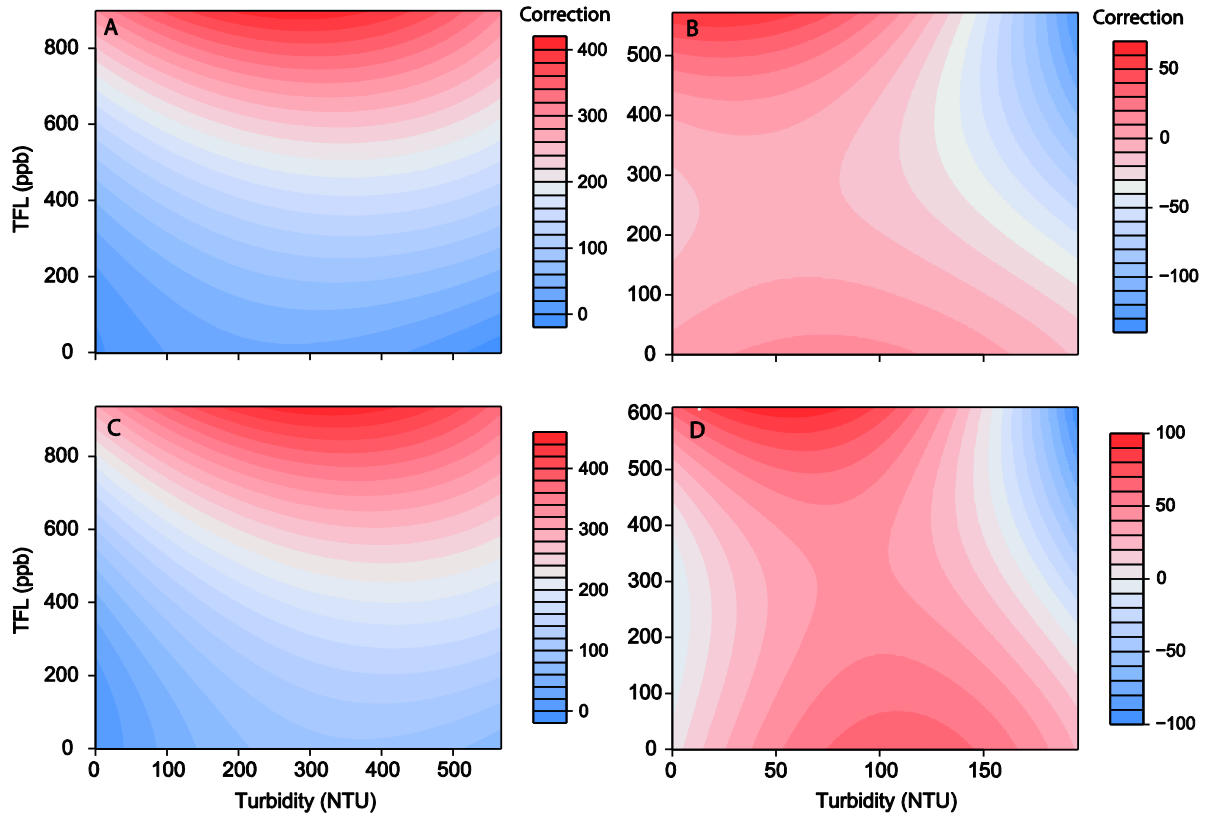


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2 Figure 3. Representation of the regression surface as a function of the two predictor variables:
3 (i) Turbidity and (ii) observed tryptophan concentration. Filled contours represent the
4 regression model output, i.e. the correction factor to be applied. Panels A and C represent the
5 silt models for sensors TU1 and CH1 respectively. Panels B and D represent the clay models
6 for sensors TU1 and CH1 respectively.

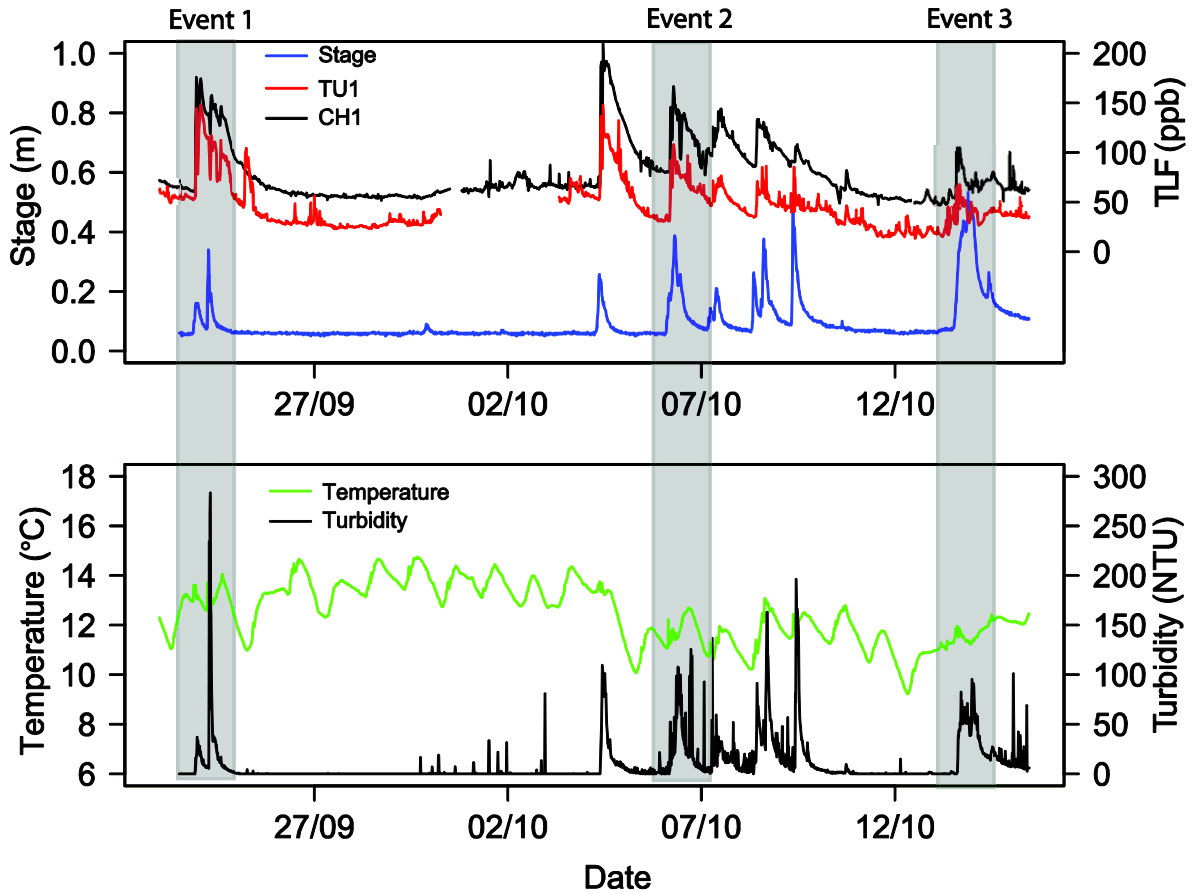


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2 Figure 4. Hydrological variables recorded at the Bourn Brook test site (23/09/2014-
3 30/09/2014). Upper panel displays river stage and raw Tryptophan-Like Fluorescence (TLF);
4 the lower panel displays water temperature and turbidity. The three events when discrete
5 sampling was undertaken to complement the *in-situ* sensor records are highlighted in grey.



6

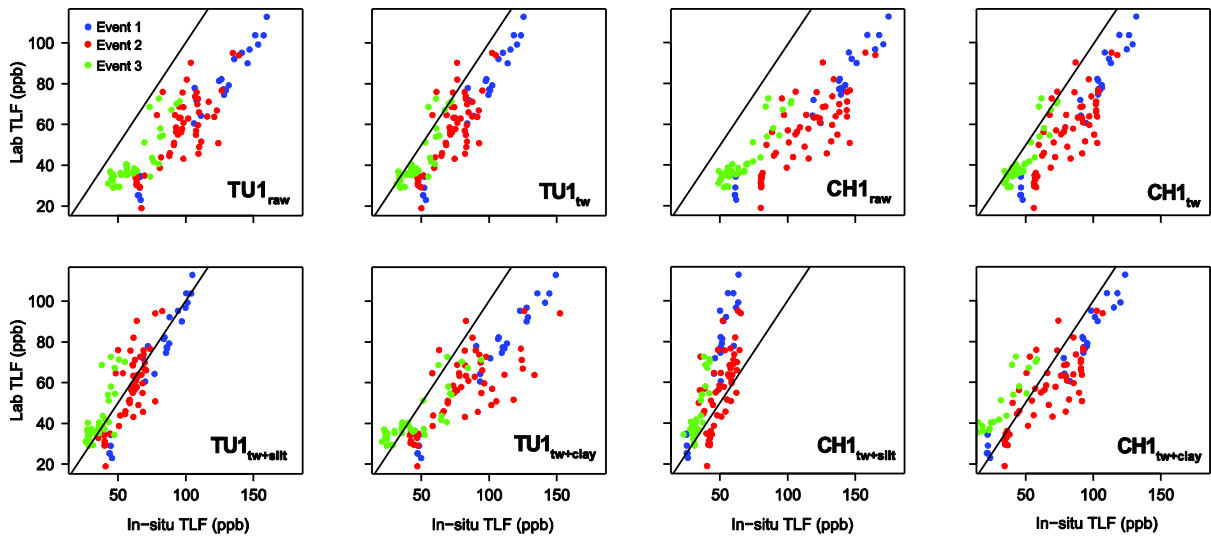
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2 Figure 5. Relationship between *in-situ* and lab TLF for the storm events characterised. Raw
3 records, temperature corrected ($T_{w_{corr}}$), clay particle size plus temperature corrected (Clay +
4 $T_{w_{corr}}$) and silt particle size plus temperature corrected (Silt + $T_{w_{corr}}$) are displayed for
5 comparison. Black line is 1:1.

6

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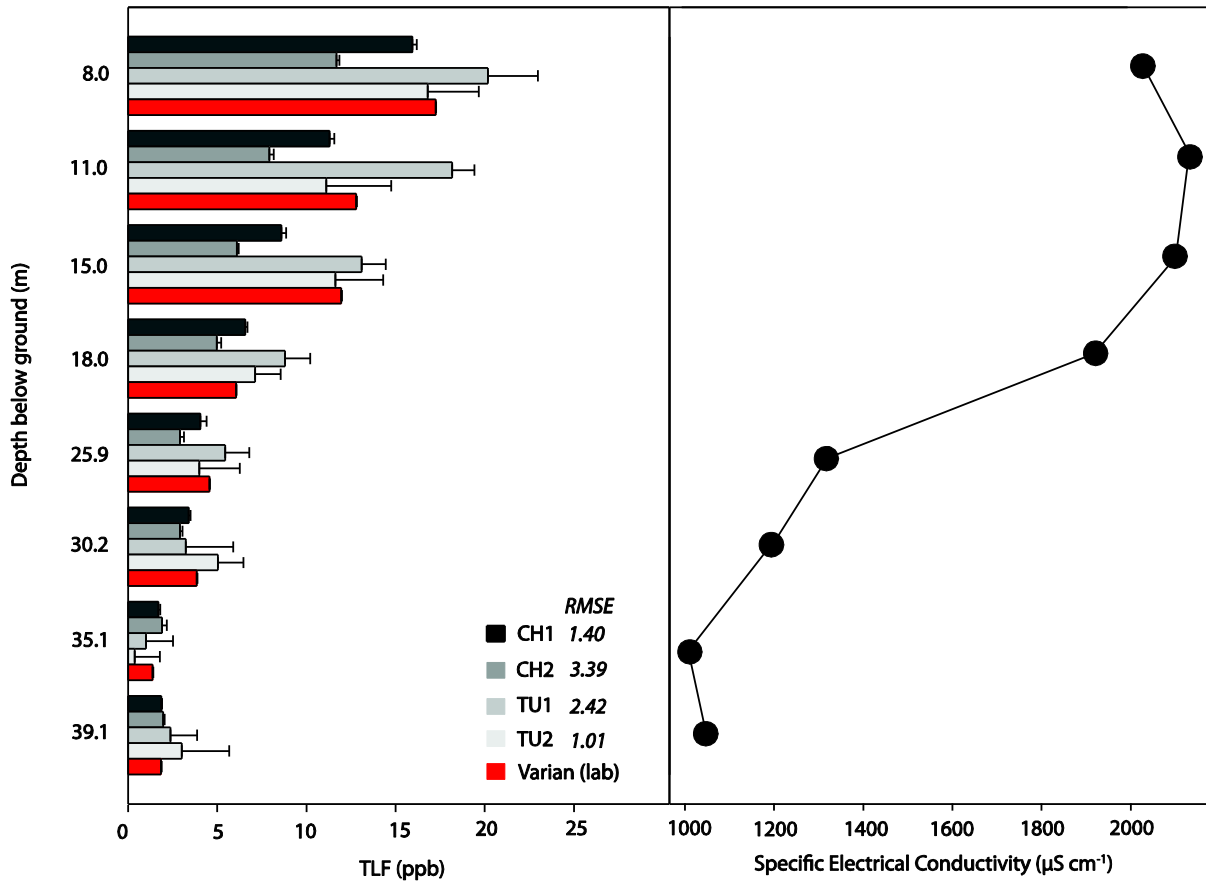
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2 Figure 6. Depth profiles for tryptophan-like fluorescence signal, grey-scale bars represent the
3 *in-situ* measurements (temperature corrected) undertaken at the Nottingham borehole site, the
4 red bar represents laboratory measurement using a Varian scanning fluorometer. RMSEs are
5 displayed in the figure legend.

6



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