# AN H1 -GALERKIN METHOD FOR A STEFAN PROBLEM WITH A QUASILINEAR PARABOLIC EQUATION IN NON-DIVERGENCE FORM 

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#### Abstract

Optimal error estimates in $L^{2}, H^{1}$ and $H^{2}$-norms are established for a single phase Stefan problem with quasilinear parabolic equation in non-divergence form by an $\mathrm{H}^{\mathrm{l}}$-Galerkin procedure.


EEY WORDS AND PHRASES. $H^{1}$-Galerkin procedure, finite element approximation, nonlinear Stefan problem, non-divergence form, error analysis.
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## 1. INTRODUCTION.

With the help of Galerkin finite element methods, Nitsche in his pioneering works [1]-[3] established error estimates for linear problems, proposed earlier by Magenes [4]. We extended his analysis to nonlinear problems in divergence form [5]-[6]. In the present work, a single phase Stefan problem with quasilinear parabolic equation in non-divergence form is considered and under appropriate conditions optimal error estimates for Galerkin approximation in $L^{2}, H^{1}$ as well as $H^{2}$ norms are established. We require more regularity assumptions for the present one than for the cases discussed in [5]-[6], and consequently we improve upon the estimates in $\mathrm{L}^{2}$-norm.

The organization of the paper is as follows: In section 2, the description of the problem and the transformed system with some preliminaries are presented. The weak formulation and $H^{1}$-Galerkin procedure are discussed in section 3 . Section 4 deals with an auxiliary projection and some approximation Lemmas. In section 5 optimal error estimates in $L^{2}, H^{1}$ and $H^{2}$-norms for continuous time Galerkin approximations are established, assuming existence of the approximate solution. Finally, in section 6 the question of global existence and uniqueness of the Galerkin approximation is discussed.

## 2. PROBLEA DESCRIPTION AND DOHAIN PIXING.

The nonlinear heat conduction with change of phase can be modelled as a single phase nonlinear Stefan problem in a variable domain $\Omega(\tau) \times\left(0, T_{0}\right)$, where $\Omega(\tau)=$ $\{y \cdot \varepsilon(0, S(\tau))$ and $S(\tau)$ known to be the free boundary. We state this problem as follows:

Find a pair $\{U, S\}, U=U(y, \tau), S=S(\tau)$ such that $U$ satisfies

$$
\begin{equation*}
U_{\tau}-a(U) U_{y y}=0, \text { for }(y, \tau) \in \Omega(\tau) x\left(0, T_{0}\right] \tag{2.1}
\end{equation*}
$$

with initial and boundary conditions

$$
\begin{array}{ll}
U(y, 0)=g(y), & \text { for } y \varepsilon I=(0,1) \\
U_{y}(0, . \tau)=0 & \\
\text { for } \pi>0 & \text { for } \tau>0 \\
U(S(\tau), \tau)=0, &
\end{array}
$$

and $S$, the free boundary satisfies

$$
\begin{equation*}
S_{\tau}=-U_{y}(S(\tau), \tau), \quad \text { for } \tau>0 \tag{2.4}
\end{equation*}
$$

with $S(0)=1$. The above problems is a special case of the general situation discussed in Fasano et. al. [7], where ' $a$ ' depends only on $U, q \equiv 0$ and $\phi=-\mathrm{y}, \mathrm{y}(\mathrm{S}(\tau), \tau)$ in their notations.

We use the following notiations. Let $\Omega(\tau) \quad R$ be a bounded domain for $\tau \geq 0$. Let $(u, v)=\int_{\Omega(\tau)} u v d x$ and $\|u\|^{2}=(u, u)$. For each nonnegative integer $m$, let $H^{m}(\Omega(\tau))$ be the usual Sobolev space $W^{m}, P_{(\Omega(\tau))}$, for $p=2$ with the norm

$$
\|u\|_{H^{m}(\Omega(\tau))}^{2}=\sum_{j=0}^{m}\left\|\frac{\partial^{j}}{\partial x^{j}} u(x, \tau)\right\|^{2} d x
$$

Further, $W^{m, \infty}(\Omega(\tau))$ is defined as usual with the norm

$$
\|u\|_{W^{m}, \infty(\Omega(\tau))}=\sum_{j=0}^{m} \left\lvert\, \frac{\partial^{j} u}{\partial x^{j}}\right. \|_{L^{\infty}(\Omega(\tau))}
$$

In case $I=\Omega(\tau)$, we shall omit $I$ from $H^{m}(I), L^{\infty}(I)$ and $W^{m, \infty}(I)$ and norm $\mathrm{H}^{\mathrm{m}}(\mathrm{I})$ is denoted by $\|\cdot\| \|_{\mathrm{m}}$.

If $X$ be a normed linear space with norm $\|\cdot\|_{X}$ and $\phi:(a, b) \rightarrow X$, then we denote by

$$
\|\phi\|_{W^{k}, q_{(a, b ; X)}^{q}}=\sum_{\beta=0}^{k}\left\|\frac{\partial^{\beta} \phi}{\partial t^{\beta}}\right\|_{L^{q}(a, b ; X)}^{q}, 1 \leq q<\infty
$$

and

$$
\|\phi\|_{w^{k}, q}(a, b ; x) \text { is accordingly defined. }
$$

In case $(a, b)=(0, T)$ and $X=H^{m}$ or $W^{m, \infty}$, we write simply $\|\phi\|_{W} k, q_{\left(H^{m}\right)}$
 nience, we use $\phi_{x}=\frac{\partial \phi}{\partial x}, \phi_{x x}=\frac{\partial^{2} \phi}{\partial x^{2}} ; \phi_{t}=\frac{\partial \phi}{\partial t}$ and $\phi(1)=\phi(1, t)$, if $\phi=\phi(x, t)$.

Throughout this work, $K$ will always denote a generic constant. On occasion, we will show that a constant depends on certain parameters, while independent of others.

We shall now state our main assumption on $a(),$.$g and the solution U, S$, and call them collectively 'condition B'.

## CONDITION B.

(i) For $p \in R, a(p) \geq \alpha$, where $\alpha$ is a positive constant.
(ii) For $p \in R, a(p) \varepsilon c^{3}(R)$ and there is a common bound $K_{1}>0$ such that $|a|$, $\left|a_{p}\right|,\left|a_{p p}\right|$ and $\left|a_{p p p}\right| \leq K_{1}$.
(iii) The initial function $g$ is sufficiently smooth and satisfies the compatibility condition that is $g_{y}(0)=g(1)=0$.
(iv) The problem (2.1)-(2.4) has a unique solution.

For the existence and uniqueness of the solution of (2.1)-(2.4), see Fasano et.al. [7].
Further it is assumed that the solution $U, S$ of (2.1)-(2.4) satisfies the following regularity condition. For an integer $r \geq 1$,
$U \varepsilon L^{\infty}\left(0, T_{0} ; H^{r+1}(\Omega(\tau)) \quad W^{1,2}\left(0, T_{0} ; H^{r+1}(\Omega(\tau))\right) \quad \cap \quad W^{1},\left(0, T_{0} ; W^{2, \infty}(\Omega(\mathrm{r}))\right)\right.$,
$S \in W^{1, \infty}\left(0, T_{0}\right)$.
Let $\tilde{K}_{2}$ be the bound for the functions in above mentioned norms.
We fix the free boundary, using Landau type transformation [8]

$$
\begin{equation*}
x=s^{-1}(\tau) y, \quad \tau \geq 0 \tag{2.5}
\end{equation*}
$$

Further, we introduce an additional transformation in time scale given by

$$
\begin{equation*}
t=t(\tau)=\int_{0}^{\tau} S^{-2}\left(\tau^{\prime}\right) d \tau^{\prime}, \tag{2.6}
\end{equation*}
$$

In order to decouple the resulting transformed system. A routine calculation shows that the function $u(x, t)=U(y, t)$ satisfies

$$
\begin{align*}
u_{t}-a(u) u_{x x} & =-u_{x}(1) x u_{x}, x \varepsilon I, t \varepsilon(0, T]  \tag{2.7}\\
u(x, 0) & =g(x), x \varepsilon I  \tag{2.8}\\
u_{x}(0, t) & =u(1, t)=0, t>0 \tag{2.9}
\end{align*}
$$

and the function $s(t)=S(\tau)$ satisfies

$$
\begin{equation*}
\frac{d s}{d t}=-u_{x}(1) s, t>0 \tag{2.10}
\end{equation*}
$$

with $s(0)=1$.
Here, $t=T$ corresponds to $\tau=T_{0}$. Note that all the regularity assumptions for $\mathrm{U}, \mathrm{S}$ are carried over to $\mathrm{u}, \mathrm{s}$ with the bound say $\mathrm{K}_{2}$ and the new regularity assumptions are collectively called $R_{1}$. Further, the integral (2.6) can be rewritten as

$$
\begin{equation*}
\frac{d \tau}{d t}=s^{2}(t), \quad \text { with } \quad \tau(0)=0 \tag{2.11}
\end{equation*}
$$

## 3. wear formulation and $\mathbf{B}^{1}$-galerkin procedure.

Consider the space:

$$
{ }^{0} H^{2}(\mathrm{I})=\left\{v \varepsilon H^{2}(\mathrm{I}): \mathrm{v}_{\mathrm{x}}(0)=\mathrm{v}(1)=0\right\}
$$

The weak formulation of (2.7)-(2.9) is given by

$$
\begin{equation*}
\left(u_{t x}, v_{x}\right)+\left(a(u) u_{x x}, v_{x x}\right)=u_{x}(1)\left(x u_{x}, v_{x x}\right), v \in \stackrel{H}{H}^{0}(I) \text { and } t>0 \tag{3.1}
\end{equation*}
$$

with $u(x, 0)=g(x)$.
$H^{1}$-Galerkin Procedure. Let $S_{h}(0<h \leq 1)$ be a finite dimensional subspace of ${ }_{H}^{0}(\mathrm{I})$ belonging to regular $\mathrm{S}_{\mathrm{h}} \mathrm{S}_{\mathrm{h}}$, family, for a definition see oden et. al. [9] and satisfying the following approximation and inverse properties:
(i) For $v \in H^{m}(I) \quad{ }^{0}{ }^{2}(I)$, there is a constant $K_{0}$ independent of $h$ such that

$$
\begin{aligned}
& \inf \left\|_{\mathrm{g}} \underset{\mathrm{~h}}{ } \mathrm{v}-\mathrm{x}\right\|_{j} \leq \mathrm{K}_{0} \mathrm{~h}^{\mathrm{m}-\mathrm{j}}\|\mathrm{v}\|_{\mathrm{m}} \text {, for } j=0,1,2 \text { and } 2 \leq \mathrm{m} \leq \mathrm{r}+1 \text {; } \\
&
\end{aligned}
$$

(ii) For $x \in \stackrel{0}{S}_{h},\|x\|_{2} \leq \mathrm{K}_{0} h^{-1}\|x\|_{1}$.

Now we call $u^{h}:(0, T]+S_{h}$ an $H^{1}$-Galerkin approximation of $u$, if it satisfies $\left(u_{t x}^{h}, x_{x}\right)+\left(a\left(u^{h}\right) u_{x x}^{h}, x_{x x}\right)=u_{x}^{h}(1)\left(x u_{x}^{h}, x_{x x}\right), x \in S_{h}^{0}$
and the initial condition

$$
\begin{equation*}
u^{h}(x, 0)=Q_{h} g(x) \tag{3.3}
\end{equation*}
$$

where $Q_{h}$ is an appropriate projection of $u$ onto $S_{h}$ at $t=0$, to be defined later. Further, the Galerkin approximations $s_{h}$ and $\tau_{h}$ of $s$ and $\tau$ respectively are given by

$$
\begin{equation*}
\frac{d s_{h}}{d t}=-u_{x}^{h}(1) s_{h}, \quad \text { with } \quad s_{h}(0)=1 \tag{3.4}
\end{equation*}
$$

and

$$
\begin{equation*}
\frac{d \tau_{h}}{d t}=s_{h}^{2}, \quad \text { with } \quad \tau_{h}(0)=0 \tag{3.5}
\end{equation*}
$$

## 4. SOME APPROXIMATION LEMMAS.

Set

$$
\begin{equation*}
A(u ; v, w)=\left(a(u) v_{x x}, w_{x x}\right)-u_{x}(1)\left(x v_{x}, w_{x x}\right) ; \text { for } u \varepsilon w^{1, \infty}, v \text { and } w \varepsilon H^{2} . \tag{4.1}
\end{equation*}
$$

The boundedness and Garding type inequality for $A$ can be established by standard arguments.

LEMMA 4.1. For $u \in W^{1, \infty}, v$ and $w \in H^{0}(I)$

$$
\begin{equation*}
|A(u ; v, w)| \leq M\left\|v_{x x}\right\|\left\|w_{x x}\right\| \tag{4.2}
\end{equation*}
$$

and

$$
\begin{equation*}
A(u ; v, v) \geq \tilde{\alpha}\left\|v_{x x}\right\|^{2}-\rho\left\|v_{x}\right\|^{2} \tag{4.3}
\end{equation*}
$$

where $M, \tilde{\alpha}$ and $\rho$ are constants, but $M$ and $\rho$ may depend on $\left\|u_{x}\right\|_{L^{\infty}}$.
Define

$$
A_{\rho}(u ; v, w)=A(u ; v, w)+\rho\left(v_{x}, w_{x}\right)
$$

Note that $A_{\rho}(u, \ldots)$ is coercive in $\mathrm{H}^{2}$, that is

$$
\begin{equation*}
A_{\rho}(u ; v, v) \geq \tilde{\alpha}\left\|v_{x x}\right\|^{2} \tag{4.4}
\end{equation*}
$$

Let $\tilde{u} \varepsilon \begin{array}{ll}0 \\ S_{h}\end{array}$ be an approximation of $u$ with respect to the form $A_{\rho}$ :

$$
\begin{equation*}
A_{p}(u ; u-\tilde{u}, x)=0, \quad x \in \stackrel{0}{S}_{h} \tag{4.5}
\end{equation*}
$$

Now, an application of Lax-Milgram theorem shows the existence of a unique solution $\tilde{u}$ of equation (4.5).

Consider

$$
\begin{equation*}
L^{\star}(u) \phi=\left(a(u) \phi_{x x}\right)_{x x}+u_{x}(1)\left(x \phi_{x x}\right)_{x}-\rho \phi_{x x}, u \varepsilon \hat{H}^{2} \tag{4.6}
\end{equation*}
$$

For $\Psi \in \mathrm{L}^{2}(\mathrm{I})$, define $\phi \varepsilon \mathrm{H}^{4} \quad \mathrm{H}^{0}$ by

$$
\begin{align*}
& L^{\star}(u) \phi=\Psi ; \quad x \varepsilon I  \tag{4.7}\\
& \left.\phi_{x x}\right|_{x=1}=\left.\phi_{x x x}\right|_{x=0}=0 .
\end{align*}
$$

Then, for $v \in \mathrm{H}^{2}(\mathrm{I})$ we get

$$
\begin{equation*}
\left(v, L^{*}(u) \phi\right)=A_{\rho}(u ; v, \phi) \tag{4.8}
\end{equation*}
$$

Thus, defining $D\left(L^{*}\right)$ as

$$
D\left(L^{\star}\right)=\left\{\phi \varepsilon H^{4} \quad \mathrm{H}^{2}: \phi_{\mathrm{XX}}(1)=\phi_{\mathrm{XXX}}(0)=0\right\}
$$

we have from the positivity and boundedness of $A_{\rho}$ that at least a weak solution $\phi \varepsilon D\left(L^{*}\right)$ of (4.7) for each $\Psi \varepsilon L^{2}$ exists and the regularity

$$
\begin{equation*}
\|\phi\|_{4} \leq c_{0}\|\Psi\| \tag{4.9}
\end{equation*}
$$

where $C_{0}$ depends on $u$ and its derivatives, holds.
Let $\eta=u-\widetilde{u}$. We now need to obtain some estimates of $n$ and its temporal derivatives $n_{t}$, for our future use. The following Lemma proves very convenient for our purpose.

LEMMA 4.2. Let $\geqslant \varepsilon \mathrm{H}^{2}(\mathrm{I})$ and satisfy

$$
\begin{equation*}
A_{\rho}(u ; p, x)=F(x), x \in S_{h}^{0} \tag{4.10}
\end{equation*}
$$

where $F: \mathrm{H}^{2}(I) \rightarrow R$ and linear. Let there exist constants $M_{1}$ and $M_{2}$ with $M_{1} \geq M_{2}$ such that

$$
\begin{equation*}
|F(\phi)| \leq M_{1}| | \phi_{X X} \|, \quad \phi \varepsilon H^{2} \tag{4.11}
\end{equation*}
$$

and

$$
\begin{equation*}
|F(\phi)| \leq M_{2}| | \phi \|_{4}, \quad \phi \varepsilon D\left(L^{*}\right) \tag{4.12}
\end{equation*}
$$

Then, for sufficiently small $h$

$$
\begin{gather*}
\left\|\Phi_{x x}\right\| \leq K_{3}\left[M_{I}+\inf \int_{0}\|-x\|_{2}\right]  \tag{4.13}\\
x \in S_{h}
\end{gather*}
$$

and

$$
\begin{gather*}
\|s\| \leq K_{3}\left[\left(M_{1}+\inf _{0}| | \$-x| |_{2}\right) h^{2}+M_{2}\right]  \tag{4.14}\\
x \in S_{h}
\end{gather*}
$$

where $K_{3}=K_{3}\left(\alpha, \rho, M, C_{0} ; K_{0}\right)$ is used as generic constant.
PROOF. Note that

$$
A_{\rho}(u ; \$, \$)=A_{\rho}(u ; \$, \$-\chi)-F(\$-\chi)+F(\$), \chi \in S_{h}
$$

By coercive property (4.4) for $A_{\rho}$, we get

$$
\begin{gathered}
\left\|\Phi_{x x} \mid\right\|^{2} \leq(\tilde{\alpha})^{-1}\left[\left(M| |_{x x}| |+M_{1}\right) \inf _{0}| |-x \|_{2}+M_{1}| | \Phi_{x x}| |\right] \\
x \in S_{h}
\end{gathered}
$$

For $\varepsilon 0_{H^{2}},\|\phi\|_{2} \leq \mathrm{x}\| \|_{x x} \|$. Therefore,

$$
\begin{gathered}
\left\|\left\|_{x x}\right\| \leq(\tilde{\alpha})^{-1}\left[M \inf \|-x\|_{2}+2 K M_{1}\right]\right. \\
0 \\
x \in s_{h}
\end{gathered}
$$

and the estimate (4.13) follows. In order to get an $L^{2}$-estimate, we follow here Aubin-Nitsche duality argunents. For $\psi \varepsilon L^{2}(I)$, define $\phi \in D\left(L^{*}\right)$ by (4.7). Multiply both the sides of (4.7) by to obtain for $u \varepsilon \hat{H}^{2}$,

$$
\begin{align*}
& (\phi, \Psi)=\left(\phi, L^{*}(u) \phi\right)=A(u ; D, \phi) \\
& =A(u ; b, \phi-x)+F(x-\phi)+F(\phi) \\
& \leq\left[M\| \|_{x x}\|\inf \| \phi-x\left\|_{2}+M_{1} \inf ^{0}\right\| \phi-x \|_{2}\right]+M_{2}\|\phi\|_{4} \\
& x \in S_{h} \quad x \in S_{h} \\
& \leq\left[M\| \|_{x x} \| K_{0} h^{2}+M_{1} K_{0} h^{2}+M_{2}\right]\|\phi\|_{4} . \tag{4.15}
\end{align*}
$$

From (4.9), (4.13) and (4.15), we obtain the required estimate (4.14). The next lemma contains the error estimates related to $\eta$ and $\eta_{t}$.

Lema 4.3. For $t \in[0, T]$, the following estimates

$$
\begin{equation*}
\|n\|_{j} \leq k_{4} h^{\mathrm{m}-j}\|u\|_{\mathrm{m}} \tag{4.16}
\end{equation*}
$$

and

$$
\begin{array}{r}
\left\|n_{t}\right\|_{j} \leq k_{5} h^{m-j}\left(\|u\|_{m}+\left\|u_{t}\right\|_{m}\right), \\
j=0,1,2 \text { and } 2 \leq m \leq r+1, \tag{4.17}
\end{array}
$$

hold. Here $K_{4}$ and $K_{5}$ are positive constants depending on parameters expressed through the following expressions that is

$$
K_{4}=K_{4}\left(K_{0}, K_{3}\right) \quad \text { and } \quad K_{5}=K_{5}\left(K_{0}, K_{1}, K_{3}, K_{4},\left\|u_{t}\right\|_{w^{2}, \infty} \text { and }\|u\|_{w^{2}, \infty}\right)
$$

PROOF. Put $=n$ and $F=0$ in the previous Lemma 4.2 to get

$$
\begin{aligned}
& \left\|n_{x x}\right\| \leq x_{3} \text { inf }\|n-x\|_{2} \\
& x \in \mathrm{~S}_{\mathrm{h}}
\end{aligned}
$$

$$
\begin{aligned}
& \leq \mathrm{K}_{0} \mathrm{~K}_{3} \mathrm{~h}^{\mathrm{m}-2}\|\mathrm{u}\|_{\mathrm{m}}, 2 \leq \mathrm{m} \leq \mathrm{r}+1 .
\end{aligned}
$$

For $\eta \varepsilon \hat{H}^{0},\|\eta\| \leq\left\|n_{x}\right\|$ and $\left\|\eta_{x}\right\| \leq\left\|n_{x x}\right\|$. Hence the result (4.16) for $j=2$. Similarly, we get the estimate (4.16), for $j=0$, consequently, the estimate for $\left\|\left\|\|_{I}\right.\right.$ follows from the interpolation inequality,

$$
\|n\|_{1} \leq\|n\|^{1 / 2}\|n\|_{2}^{1 / 2}
$$

In order to estimate $\eta_{t}$, we differentiate (4.5) with respect to ' $t$ ' and obtain

$$
\begin{equation*}
A_{\rho}\left(u ; \eta_{t}, x\right)=-\left(\left[\frac{d a(u)}{d t}\right] \eta_{x x}, x_{x x}\right)+u_{t x}(1)\left(x \eta_{x}, x_{x x}\right) \tag{4.18}
\end{equation*}
$$

Identifying the right hand side of (4.18) with $F(X)$, we see that for $\phi \varepsilon H^{0}$ (I)

$$
|F(\phi)| \leq k_{6}\left\|\eta_{x x}\right\|\left\|\phi_{x x}\right\|
$$

where $K_{6}$ depends on $K_{1}$ and $\left\|u_{t}\right\|_{W} 1, \infty$
Further, for $\phi \in D\left(L^{*}\right)$ and $u \varepsilon \mathrm{H}^{2}$, we get on integration by parts

$$
\begin{aligned}
F(\phi) & =\left(\eta_{x},\left(a_{t}(u) \phi_{x x}\right)_{x}\right)-u_{t x}(1)\left(\eta,\left(x \phi_{x x}\right)_{x}\right) \\
& =-\left(\eta,\left(a_{t}(u) \phi_{x x}\right)_{x x}\right)+u_{t x}(1)\left(\eta,\left(x \phi_{x x}\right)_{x}\right)
\end{aligned}
$$

and

$$
|F(\phi)| \leq k_{7}\|n\|\|\phi\|_{4}
$$

where $k_{7}=k_{7}\left(k_{1},\left\|u_{t x x}\right\|_{L},\left\|u_{x x}\right\| \|_{L}\right.$ and $\left.\left\|u_{t}\right\|_{W^{1}, \infty}\right)$.
Thus, Lemma 4.2 is applicable with $M_{1}=K_{6}\left\|\eta_{x x}\right\|$ and $M_{2}=K_{7}\|n\|$ and we get the desired estimate (4.17) for $j=0,2$. For $j=1$, as usual we make use of the interpolation inequality. We shall also need later the following estimate for $n_{x}(1)$.

LEMMA 4.4. There is a constant $K_{8}=K_{8}\left(\alpha, K_{0}, M ; K_{4}\right)$ such that for $2 \leq m \leq r+1$.

$$
\left|n_{x}(1)\right| \leq K_{8} h^{2(m-2)}\|u\|_{m}
$$

PROOF. Define an auxiliary function $\phi \varepsilon H^{4} \quad \mathrm{H}^{2}$ as a solution of

$$
\begin{aligned}
& L^{*}(u) \phi=0, x \in I \\
& \left.\phi_{x x x}\right|_{x=0}=0 ; \\
& \left.\phi_{x x}\right|_{x=1}=1 .
\end{aligned}
$$

Multiplying by $\eta$ the first equation and integrating by parts, we obtain

$$
\begin{aligned}
& \alpha\left|n_{x}(1)\right| \leq\left|a(0) n_{x}(1)\right| \leq\left|A_{p}(u ; \eta, \phi)\right| \\
& \leq A_{p}(u ; n, \phi-x), x \in{ }^{0} S_{h} \\
& \leq M\|\eta\|_{2} \underset{\substack{\inf \\
0 \\
\mathrm{~S}_{\mathrm{h}}}}{ }\|\phi-x\|_{2} \\
& \leq \mathrm{MK}_{4} K_{0} \mathrm{~h}^{2(\mathrm{~m}-2)}\|\mathrm{u}\|_{\mathrm{m}}\|\phi\|_{\mathrm{m}}
\end{aligned}
$$

Hence, the result follows.

## 5. A PRIORI ERROR ESTIMATES FOR CONTINUOUS TIME GALERKIN APPROXIMATION.

Throughout this section, we assume that there are positive constants $K^{*}$ and $h_{0}$ such that a Galerkin approximation $u^{h} \in{\underset{S}{h}}_{0}$ in (3.2) exists and satisfies,

$$
\begin{equation*}
\left\|u^{h}\right\|_{K\left(H^{2}\right)} \leq K^{*}, \text { for } 0<h \leq h_{0} \tag{5.1}
\end{equation*}
$$

where $u^{h}(x, 0)$ is defined as $Q_{h} g$, satisfying

$$
\begin{equation*}
A_{\rho}\left(g ; g-Q_{h} g, x\right)=0, x \varepsilon{\stackrel{0}{S_{h}}}^{0} \tag{5.2}
\end{equation*}
$$

Clearly, $u^{h}(x, 0) \equiv \tilde{u}(x, 0)$.
Let $\zeta=u^{h}-\tilde{u}$ and $e=u-u^{h}=\eta-\zeta$.
THEOREM 5.1. Suppose $\eta=u-\tilde{u}$ satisfies (4.5) and $u^{h}$, the Galerkin approximation of $u$ is defined by (3.2) with $Q_{h}$ given as in (5.2). Further, assume that (5.1) holds. Then, there is a constant $K_{9}=K_{9}\left(\alpha, \rho, K^{*}, K_{1}, K_{4}, K_{5}\right.$ and $\left.K_{8}\right)$ such that for $m \geq 4$

$$
\begin{equation*}
\left\|\xi_{x}\right\|_{L^{\infty}\left(L^{2}\right)}+\beta\left\|\xi_{x x}\right\| \|_{L^{2}\left(L^{2}\right)} \leq k_{9}^{m} \quad\left(\left\|u_{t}\right\|_{L^{2}\left(H^{m}\right)}+\|u\|_{L^{2}\left(h^{m}\right)}\right) \tag{5.3}
\end{equation*}
$$

PROOF. From (4.5) and (3.1) with $v=x$, we get

$$
\left(\tilde{u}_{t x}, x_{x}\right)+A_{\rho}(u ; \tilde{u}, x)=-\left(n_{t x}, x_{x}\right)+\rho\left(u_{x}, x_{x}\right), x \varepsilon S_{h} .
$$

Subtracting this from (3.2), we obtain

$$
\begin{gather*}
\left(\zeta_{t x}, x_{x}\right)+A_{\rho}\left(u^{h} ; u^{h}, x\right)-A_{\rho}(u ; \tilde{u}, x)=\left(\eta_{t x}, x_{x}\right)-\rho\left(\eta_{x}, x_{x}\right) \\
+\rho\left(\zeta_{x}, x_{x}\right) \tag{5.4}
\end{gather*}
$$

But

$$
\begin{align*}
& A_{\rho}\left(u^{h} ; u^{h}, x\right)-A_{\rho}(u ; \tilde{u}, x)=\left(a\left(u^{h}\right) \zeta_{x x}, x_{x x}\right) \\
& \quad+\left(\left[a\left(u^{h}\right)-a(u)\right] \tilde{u}_{x x}, x_{x x}\right)-u_{x}(1)\left(x \zeta_{x}, x_{x x}\right)+\eta_{x}(1)\left(x u_{x}^{h}, x_{x x}\right) \\
&  \tag{5.5}\\
& \quad-\zeta_{x}(1)\left(x u_{x}^{h}, x_{x x}\right)+\rho\left(\zeta_{x}, x_{x}\right)
\end{align*}
$$

From (5.4)-(5.5) with $X=\zeta$, it follows on integrating by parts with respect to $x$ the two terms on the right hand side of (5.4),

$$
\begin{aligned}
\frac{1}{2} \frac{d}{d t}\left\|\zeta_{x}\right\|^{2} & +\left(a\left(u^{h}\right) \zeta_{x x}, \zeta_{x x}\right)=-\left(\eta_{t}, \zeta_{x x}\right)+\rho\left(\eta, \zeta_{x x}\right)+u_{x}(1)\left(x \zeta_{x}, \zeta_{x x}\right) \\
& +\left(\left[a(u)-a\left(u^{h}\right)\right] \tilde{u}_{x x}, \zeta_{x x}\right)-\eta_{x}(1)\left(x u_{x}^{h}, \zeta_{x x}\right)+\zeta_{x}(1)\left(x u_{x}^{h}, \zeta_{x x}\right)
\end{aligned}
$$

Using $a(.) \geq \alpha,(5.1)$ and replacing $\tilde{u}$ by $u-\eta$, we obtain

$$
\begin{align*}
& \frac{1}{2} \frac{d}{d t}\left\|\zeta_{x}\right\|^{2}+\alpha\left\|\zeta_{x x}\right\|^{2} \leq\left\{\left\|\eta_{t}\right\|+\rho\|n\|+k_{2}\left\|\zeta_{x}\right\|+K_{2}\left(\|n\|_{L}+\|\zeta\|_{L}\right)\right. \\
& \left.\|n\|_{2}+k_{1} K_{2}(\|n\|+\|\zeta\|)+K^{*}\left|\eta_{x}(1)\right|\right\}\left\|\zeta_{x x}\right\|+K^{*}\left|\zeta_{x}(1)\right|\left\|\zeta_{x x}\right\| \tag{5.6}
\end{align*}
$$

Since $\left|\zeta_{x}(1)\right| \leq\left\|\zeta_{x}\right\|^{1 / 2}\left\|_{\mathrm{xx}}\right\|^{1 / 2}$ for $\zeta \varepsilon \mathrm{H}^{2}$, applying Young's inequality for the last term and the inequality $a b \leq \frac{a^{2}}{2 \varepsilon}+\frac{\varepsilon}{2} b^{2}, a, b \geq 0 ; \varepsilon>0$ for the remaining terms in (5.6), we get using $\|\phi\|_{L}^{\infty} \leq\left\|\phi_{x}\right\|$ for $\phi \varepsilon H^{2}$

$$
\begin{aligned}
\frac{1}{2} \frac{d}{d t}\left\|\zeta_{x}\right\|^{2} & +\alpha\left\|\zeta_{x x}\right\|^{2} \leq K_{10}(\varepsilon)\left\|\zeta_{x x}\right\|^{2}+K\left(K_{1}, K_{2}, K^{\star}, \rho ; \varepsilon\right)\left(\left\|n_{t}\right\|^{2}\right. \\
& \left.+\|\eta\|^{2}+\left|n_{x}(1)\right|^{2}+\|n\|_{1}^{2}\|n\|_{2}^{2}\right) \\
& +K\left(K_{2} ; \varepsilon\right)\|\eta\|_{2}^{2}\left\|\zeta_{x}\right\|^{2}+K\left(K_{1}, K_{2} K^{\star}, \varepsilon\right)\left\|\zeta_{x}\right\|^{2} .
\end{aligned}
$$

Now with appropriate choice of $\varepsilon, K_{10}(\varepsilon)$ can be made less than or equal to $\alpha / 2$. With this choice of $\varepsilon$, we get by integrating with respect to ' $t$ ' and using Gronwall's inequality the following

$$
\begin{aligned}
&\left\|\zeta_{x}\right\|^{2}(t)+\alpha \int_{0}^{t}\left\|s_{x x}\right\|^{2} d t^{\prime} \leq K\left(K_{1}, k_{2}, K^{\star} ; \rho\right) \int_{0}^{t}\left(\left\|\eta_{t}\right\|^{2}+\|n\|^{2}\right. \\
&\left.+\left|\eta_{x}(1)\right|^{2}+\|n\|_{1}^{2}\|n\|_{2}^{2}\right) d t^{\prime}
\end{aligned}
$$

From (4.16)-(4.17) and (4.19) with $2(m-2) \geq m$ and $2 m-3 \geq m$ that is $m \geq 4$, we get the desired estimate (5.3).

COROLLARY 5.2. Let all the assumtions of the previous theorem hold and the finite dimensional subspace $S_{h}$ satisfy the inverse property. Then there is a constant $K_{11}$ depending on $K_{9}$ and $K_{0}$ such that for $r+1 \geq m \geq 4$,

$$
\begin{align*}
& \|r\|_{L^{\infty}\left(L^{2}\right)}+\|r\|_{L^{\infty}\left(H^{1}\right)}+h\|r\|_{L^{\infty}\left(H^{2}\right)} \\
& \quad \leq K_{11} h^{m}\left(\|u\|_{L^{2}\left(H^{m}\right)}+\left\|u_{t}\right\|_{L^{2}\left(H^{m}\right)}\right) \tag{5.7}
\end{align*}
$$

PROOF. From the estimate (5.3) and $\|\zeta\| \leq\left\|\zeta_{x}\right\|$ for $\zeta \varepsilon \mathrm{S}_{\mathrm{h}}$, we get

$$
\|\zeta\|_{L\left(L^{2}\right)}+\|\zeta\|_{L\left(H^{\infty}\right)} \leq K_{11} h^{m}\left(\|u\|_{L^{2}\left(H^{m}\right)}+\left\|u_{t}\right\|_{L^{2}\left(H^{m}\right)}\right)
$$

By inverse property for $\mathrm{S}_{\mathrm{h}}$, we have

$$
\|\zeta\|_{L\left(H^{2}\right)} \leq K_{0} h^{-1}\|\zeta\|_{L\left(H^{1}\right)}, \quad \zeta \varepsilon S_{h} .
$$

Hence the result (5.7). From Theorem 5.1, Corollary 5.2, Lemma 4.3 and triangle inequality we get the following theorem.

THEOREM 5.3. Let the solution $u$ of (2.7)-(2.9) satisfy the regularity condition $R_{1}$. Further, suppose that there are positive constants $h_{0}$ and $K^{*}$ ( $K^{*} \geq 2 K_{2}$ ) such that an approximate solution $u^{h} \varepsilon S_{h}^{0}$ of (3.2) satisfying (5.1) exists in $\mathrm{I} \times(0, \mathrm{~T}]$ for $0<\mathrm{h} \leq \mathrm{h}_{0}$. Then, the following estimates hold for $\mathrm{r} \geq 3$,

$$
\begin{equation*}
\|e\|_{L\left(H^{j}\right)} \leq K_{1} h^{r+1-j}, \quad j=0,1,2 \tag{5.8}
\end{equation*}
$$

where $K_{12}=K_{12}\left(K_{4}, K_{11}\right.$ and $\left.K_{2}\right)$. Besides, for sufficiently small $h$ and $r \geq 3$,

$$
\begin{equation*}
\left\|u^{\mathrm{h}}\right\|_{\mathrm{L}^{\infty}\left(\mathrm{H}^{2}\right)} \leq 2 \mathrm{~K}_{2} \leq \mathrm{K}^{*} \tag{5,9}
\end{equation*}
$$

and consequently, $K_{12}$ can be choosen independent of $K$.
PROOF. The estimates (5.8) for $j=0,1,2$ are immediate from the Theorem 5.1, Corollary 5.2 and Lemma 4.3 by triangle inequality. To prove (5.9), we note

$$
\begin{aligned}
\left\|u^{h}\right\|_{L\left(H^{2}\right)}^{\infty} & \leq\|u\|_{L\left(H^{2}\right)}+\|e\|_{L^{\infty}\left(H^{2}\right)} \\
& \leq K_{2}+K_{12} h^{r-1} \\
& \leq 2 K_{2}, \text { for sufficiently small } h \text { and } r \geq 3 .
\end{aligned}
$$

We are now looking for approximations of $U$ and $S$, where the pair $\{U, S\}$ is the solution of (2.1)-(2.4). The Galerkin approximations $U^{h}$ and $S_{h}$ are given by

$$
\begin{align*}
u^{h}(y, \tau) & =u^{h}(x, t)  \tag{5.10}\\
S^{h}(\tau) & =s_{h}(t) \tag{5.11}
\end{align*}
$$

where,

$$
\begin{align*}
& y=s_{h}(t) x,  \tag{5.12}\\
& \tau=\tau_{h}
\end{align*}
$$

and $s_{h}, \tau_{h}$ are defined by (3.4), (3.5) respectively.
THEOREM 5.4. Suppose that the condition $B$ and the regularity condition $\tilde{R}_{1}$ are satisfied. Then the following estimates hold for $r \geq 3$,

$$
\begin{align*}
& \left\|s-s_{h}\right\|_{L}^{\infty}\left(0, T_{0}\right)  \tag{5.13}\\
& =0\left(h^{r+1}\right)  \tag{5.14}\\
& \left\|\tau-\tau_{h}\right\|_{L\left(0, T_{0}\right)}=0\left(h^{r+1}\right)
\end{align*}
$$

and

$$
\begin{equation*}
\| \mathrm{u}-\left.\mathrm{u}^{\mathrm{h}}\right|_{\mathrm{L}\left(0, \mathrm{~T}_{0} ; \mathrm{H}^{\mathrm{j}}(\tilde{\Omega}(\tau))\right)}=0\left(\mathrm{~h}^{\mathrm{r}+1-\mathrm{j}}\right), \mathrm{j}=0,1,2 \tag{5.15}
\end{equation*}
$$

where $\|$.$\| is interpreted as$

$$
\|\phi\|_{L\left(0, T_{0} ; H^{j}(\tilde{\Omega}(\tau))\right)}=\int_{0}^{T}\|\phi\|_{H^{j}(\tilde{\Omega}(\tau))} d \tau
$$

with

$$
\tilde{\Omega}(\tau)=\left(0, \min \left(S(\tau), S_{h}(\tau)\right)\right)
$$

PROOF. From (2.10) and (3.4), we have

$$
\left|s-s_{h}\right| \leq \int_{0}^{t}\left(\left|\eta_{x}(1)\right|+\left|\zeta_{x}(1)\right|\right)|s| d t^{\prime}+\int_{0}^{t}\left|u_{x}^{h}(1)\right|\left|s-s_{h}\right| d t^{\prime}
$$

An application of Gronwall's inequality and the estimates (4.19), (5.3), for $m=r+1$ gives

$$
\begin{align*}
\left\|s-s_{h}\right\|_{L(0, T)} & \leq K\left(K_{2}\right)\left\{\left\|\eta_{x}(1)\right\|_{L^{2}(0, T)}+\left\|\xi_{x}(1)\right\|_{L}^{2}(0, T)\right. \\
& \leq K\left(K_{2}, K_{8}\right)\left\{\left.\left.h^{2(r-1)}\right|_{u}\right|_{L}{ }^{2}\left(H^{r+1}\right)\right. \\
& \left.\leq\left\|\xi_{x x}\right\|_{L^{2}\left(L^{2}\right)}\right\}  \tag{5.16}\\
& \leq K_{13} h^{r+1}, \text { for } r \geq 3
\end{align*}
$$

The estimate (5.13) is immediate from (5.16), if we note that

$$
\left\|s-s_{h}\right\|_{L\left(0, T_{0}\right)}=\left\|s-s_{h}\right\|_{L(0, T)}
$$

Further, the estimate (5.14) follows from (2.11), (3.5) and (5.16). Finally since

$$
\left\|u-u^{h}\right\|_{L\left(0, T_{0} ; H^{j}(\tilde{\Omega}(\tau))\right)} \leq\left\|u-u^{h}\right\|_{L \infty\left(0, T ; H^{j}(I)\right)}
$$

we obtain the required estimate (5.15).

## 6. Global existence and uniqueness of the galerxin approximation.

Now we consider the problem of existence of the Galerkin approximation $u^{h}$ in the domain of existence of $u$. Towards this, let us recall (5.4) and note

$$
\begin{aligned}
A_{\rho}\left(u^{h} ; u^{h}, x\right)-A_{\rho}(u ; \tilde{u}, x)= & A_{\rho}(u ; \zeta, x)+\left(\left[a\left(u^{h}\right)-a(u)\right] u_{x x}^{h}, x_{x x}\right) \\
& +\eta_{x}(1)\left(x u_{x}^{h}, x_{x x}\right)-\zeta_{x}(1)\left(x u_{x}^{h}, x_{x x}\right) .
\end{aligned}
$$

From the above, we get

$$
\begin{gather*}
\left(\zeta_{t x}, x_{x}\right)+A_{\rho}(u ; \zeta, x)=\left(\eta_{t x}, x_{x}\right)-\rho\left(\eta_{x}, \zeta_{x}\right)+\rho\left(\zeta_{x}, x_{x}\right)+\left(\left[a(u)-a\left(u^{h}\right)\right]\right. \\
\left.u_{x x}^{h}, x_{x x}\right)-\eta_{x}(1)\left(x u_{x}^{h}, x_{x x}\right)+\zeta_{x}(1)\left(x u_{x}^{h}, x_{x x}\right) \tag{6.1}
\end{gather*}
$$

But,

$$
\begin{equation*}
a(u)-a\left(u^{h}\right)=\tilde{a}_{u} e=-\int_{0}^{1} \frac{\partial a}{\partial u}(u-\xi e) \text { ed } \xi \tag{6.2}
\end{equation*}
$$

Replacing $u^{h}$ by $u-e$ in (6.1) with (6.2), we have

$$
\begin{aligned}
\left(\zeta_{t x}, x_{x}\right) & +A_{\rho}(u ; \zeta, x)=-\left(\eta_{t}, x_{x x}\right)+\rho\left(\eta, x_{x x}\right)+\rho\left(\zeta_{x}, x_{x}\right) \\
& -\left(\int_{0}^{1} \frac{\partial a}{\partial u}(u-\xi e)(\eta-\zeta) d \xi\left(u_{x x}-e_{x x}\right), x_{x x}\right)-\eta_{x}(1)\left(x\left(u_{x}-e_{x}\right), x_{x x}\right) \\
& +\zeta_{x}(1)\left(x\left(u_{x}-e_{x}\right), x_{x x}\right) .
\end{aligned}
$$

Substitute $e$ by $E(x, t)$, where $E \varepsilon H^{0}$. Then we get

$$
\begin{align*}
\left(\zeta_{t x}, x_{x}\right) & +A_{\rho}(u ; \zeta, x)=-\left(\eta_{t}, x_{x x}\right)+\rho\left(\eta, x_{x x}\right)+\rho\left(\zeta_{x}, x_{x}\right) \\
& -\left(\int_{0}^{1} \frac{\partial a}{\partial u}(u-\xi E)(\eta-\zeta) d \xi\left(u_{x x}-E_{x x}\right), x_{x x}\right)-\eta_{x}(1)\left(x_{x}\left(u_{x}-E_{x}\right), x_{x x}\right) \\
& +\zeta_{x}(1)\left(x\left(u_{x}-E_{x}\right), x_{x x}\right), \tag{6,3}
\end{align*}
$$

which is a linear ordinary differential equation in $\zeta$. Therefore, for any $E=E(x, t)$ there exists a unique solution $\zeta$ of (6.3) with

$$
\begin{equation*}
\zeta(x, 0)=0 \tag{6.4}
\end{equation*}
$$

in the interval ( $0, \mathrm{~T}$ ].
The equation (6.3) defines an operator $\sigma$ such that $\zeta=\sigma$ (E), for each $E \in \mathrm{O}^{2}$. Since $e=\eta-\zeta$, therefore

$$
\begin{equation*}
e=n-\mathcal{Y}(E), \text { for each } E \in \stackrel{0}{H^{2}} \tag{6.5}
\end{equation*}
$$

To show the existence of a solution $u^{h}$ of (3.2), we need to show that the operator equation (6.5) has a fixed point. In other words, we are looking for an $e(E)$ such that

$$
e(E)=E
$$

THEOREM 6.1. Suppose that the finite dimensional space $S_{h}$ satisfies inverse property and $u$ is the unique solution of (2.7)-(2.9). Further, let the regularity conditions $R_{1}$ be satisfied. Then for some $\delta>0$, there exists a solution $u^{h} \varepsilon S_{h}$ of (3.2) satisfying $\left\|u-u^{h}\right\|_{L^{\infty}\left(0, T_{0} ; H^{2}(1)\right)} \leq \delta$.

PROOF. Set $x=\zeta$ in (6.3) to get

$$
\begin{aligned}
\frac{1}{2} \frac{d}{d t} & \left\|\zeta_{x}\right\|^{2}+\tilde{\alpha}\left\|\zeta_{x x}\right\|^{2} \\
& \leq\left\{\left\|n_{t}\right\|+\rho\|n\|+k_{1}\left(\|n\|_{L \infty}+\|\mid\|_{L \infty}\right)\left(\left\|u_{x x}\right\|+\left\|E_{x x}\right\|\right)\right. \\
& \left.+\left|n_{x}(1)\right|\left(\left\|u_{x}\right\|+\left\|E_{x}\right\|\right)\right\}\left\|\zeta_{x x}\right\|+\rho\left\|\zeta_{x}\right\|^{2} \\
& +\left(\left\|u_{x}\right\|+\left\|E_{x}\right\|\right)\left|\zeta_{x}(1)\right|\left\|\zeta_{x x}\right\|
\end{aligned}
$$

Using $\left|\zeta_{x}(1)\right| \leq\left\|\zeta_{x}\right\|^{1 / 2}\left\|\zeta_{x x}\right\|^{1 / 2}$, applying Young's inequality for the last term and $a b \leq \frac{a^{2}}{2 \varepsilon}+\frac{\varepsilon}{2} b^{2}, a, b \geq 0 ; \varepsilon>0$ for the remaining terms, we get

$$
\begin{aligned}
& \frac{d}{d t}\left\|\zeta_{x}\right\|^{2}+2 \tilde{\alpha}\left\|\zeta_{x x}\right\|^{2} \\
& \quad \leq K_{14}(\varepsilon)\left\|\zeta_{x x}\right\|^{2}+K\left(K_{1}, K_{2}, \rho ; \varepsilon\right)\left\{\left\|\mid n_{t}\right\|^{2}+\left(\|\mid\|_{L}^{\infty}\right.\right. \\
& \left.\quad+\left|n_{x}(1)\right|\right)\left(1+| | E\| \|_{2}^{2}\right\}+K\left(K_{1}, K_{2}, \rho ; \varepsilon\right)\left(1+\|E\|_{2}^{2}\right)\left\|\zeta_{x}\right\|^{2}
\end{aligned}
$$

Choosing $\varepsilon$ appropriately so that $2 \tilde{\alpha}=K_{14}(\varepsilon)$, integrating with respect to ' $t$ ' and there after applying Gronwall's inequality, we get

$$
\begin{aligned}
& \|\zeta\|_{1}^{2}(t) \leq K\left(K_{1}, K_{2} ; \rho\right) \exp \left[K\left(\rho, K_{1} ; K_{2}\right) t\left(1+\|E\|_{L\left(H^{2}\right)}^{2}\right)\right] \int_{0}^{t}\left\{\left\|\eta_{t}\right\|^{2}\right. \\
& \left.+\left(\|\eta\|_{1}^{2}+\left|\eta_{x}(1)\right|^{2}\right)\left(1+\|E\|_{L\left(H^{2}\right)}^{2}\right)\right\}
\end{aligned}
$$

From the estimates (4.16), (4.17) and (4.19), it follows that

$$
\begin{equation*}
\|\zeta\|_{L\left(H^{\infty}\right)} \leq K_{15}\left\{h^{r+1}+\left(h^{r}+h^{2(r-1)}\right)\left(1+\|E\|_{L\left(H^{2}\right)}^{2}\right)\right\} \tag{6.6}
\end{equation*}
$$

where $K_{15}=K_{15}\left(K_{1}, K_{2}, K_{4}, K_{8}, \rho\right.$ and $\left.\|E\|_{L\left(H^{2}\right)}\right)$. Thus we have

$$
\begin{align*}
\|e\|_{L\left(H^{2}\right)} & \leq\|\eta\|_{L\left(H^{2}\right)}+\|\zeta\|_{L\left(H^{2}\right)}^{\infty}  \tag{6.7}\\
& \leq\|\eta\|_{L\left(H^{2}\right)}+K_{0} H^{-1}\|\zeta\|_{L\left(H^{1}\right)}^{\infty}
\end{align*}
$$

For $\|E\|_{L^{\infty}\left(H^{2}\right)} \leq \delta$ and from (4.16), (6.6), (6.7), we get

$$
\|e\|_{L\left(H^{2}\right)} \leq K_{16} h^{r-1} \text {, where } K_{16}=K_{16}\left(K_{15}, K_{4} ; K_{0} ; \delta\right) \text {. }
$$

Therefore, for sufficiently small h

$$
\|e\|_{L\left(H^{2}\right)} \leq \delta .
$$

Now, an application of Schauder's fixed point theorem guarantees the existence of an $E$ such that $e=E$, which is a solution of the operator equation (6.5). The uniqueness of the approximate solution $u^{h}$ is easy to prove. So we formalize the above in the form of a Theorem.

THEORE 6.2. Let all the hypotheses of the Theorem 6.1 be satisfied and let $K>0$. Then there exists one and only one solution $u^{h} \varepsilon S_{h}^{0}$ of (3.2) in the ball $\left\{\left\|u-u^{h}\right\|_{L D_{\left(H^{2}\right)}} \leq K\right\}$, for sufficiently small $h$ and $r \geq 3$.

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