

LINEAR-FRACTIONAL PROGRAMMING: PROBLEMS OF  
OPTIMIZATION OF INHOMOGENEOUS FLOWS  
IN THE GENERALIZED NETWORKS

L.A. Pilipchuk

Belarussian State University

4, Nezalezhnosti Ave., 220050, Minsk, BELARUS

**Abstract:** Here we consider the linear-fractional non-homogeneous flow programming optimization problem with additional constraints of general kind. We obtain the increment of the objective function using network properties of the problem and principles of decomposition of a support. In the received formulas for calculation of reduced costs only the part of system of potentials is used.

**AMS Subject Classification:** 65K05, 90C08, 90C35, 05C50, 15A03, 15A06

**Key Words:** linear-fractional programming, sparse matrices, increment of the objective function, decomposition

### 1. Mathematical Model

Let  $G = (I, U)$  be a finite oriented connected multigraph (multinetwork) without multiple arcs and loops, where  $I$  is a set of nodes and  $U \subset I \times I$  is a set of multiarcs. Assume that a finite non-empty set  $K = \{1, \dots, |K|\}$  of different products (commodities) is transported through the multinetwork  $G$ . Let us denote a connected network corresponding to a certain type of flow  $k \in K$ :  $G^k = (I^k, U^k)$ ,  $I^k \subseteq I$ ,  $U^k = \{(i, j)^k : (i, j) \in \widehat{U}^k\}$ ,  $\widehat{U}^k \subseteq U$  – a set of arcs of the network  $G$  carrying the flow of type  $k \in K$ ,  $I^k = I(U^k)$ ,  $I(U^k) = \{i \in I : i \in I^k\}$  is the set of nodes used for transporting (producing/consuming/transiting) the

$k^{th}$  product. In order to distinguish the products, which can simultaneously pass through an multiarc  $(i, j) \in U$ , we introduce the set  $K(i, j) = \{k \in K : (i, j) \in U^k\}$ . Similarly,  $K(i) = \{k \in K : i \in I^k\}$  is the set of products simultaneously transported through a node  $i \in I$ . Now let us define a set  $U_0$  as an arbitrary subset of multiarcs of the multinetwork  $G$ ,  $U_0 \subseteq U$ . Each multiarc  $(i, j) \in U_0$  has an aggregate capacity constraint for a total amount of transported products from a subset  $K_0(i, j) \subseteq K(i, j), |K_0(i, j)| > 1$ . For all multiarcs  $(i, j) \in U$  we assume the amount of each product  $k \in K(i, j)$  to be non-negative. For products from a set  $K_1(i, j)$ , such that  $K_1(i, j) = K(i, j) \setminus K_0(i, j)$ , if  $(i, j) \in U_0$  and  $K_1(i, j) \subseteq K(i, j)$ , if  $(i, j) \in U \setminus U_0$ . Moreover, each multiarc  $(i, j) \in U$  can be equipped with carrying capacities for products from a set  $K_1(i, j)$ , where  $K_1(i, j) \subseteq K(i, j)$  is an arbitrary subset of products transported through the multiarc  $(i, j)$ .

On the described multinetwork  $G$  we consider the linear-fractional non-homogeneous flow programming optimization problem with additional constraints of general kind:

$$f(x) = \frac{p(x)}{q(x)} = \frac{\sum_{(i,j) \in U} \sum_{k \in K(i,j)} p_{ij}^k x_{ij}^k + \beta}{\sum_{(i,j) \in U} \sum_{k \in K(i,j)} q_{ij}^k x_{ij}^k + \gamma} \rightarrow \max, \tag{1}$$

$$\sum_{j \in I_i^+(U^k)} x_{ij}^k - \sum_{j \in I_i^-(U^k)} \mu_{ji}^k x_{ji}^k = a_i^k, i \in I^k, k \in K; \tag{2}$$

$$\sum_{(i,j) \in U} \sum_{k \in K(i,j)} \lambda_{ij}^{kp} x_{ij}^k = \alpha_p, p = \overline{1, l}; \tag{3}$$

$$\sum_{k \in K_0(i,j)} x_{ij}^k \leq d_{ij}^0, x_{ij}^k \geq 0, k \in K_0(i, j), (i, j) \in U_0; \tag{4}$$

$$0 \leq x_{ij}^k \leq d_{ij}^k, k \in K_1(i, j), (i, j) \in U; \tag{5}$$

$$x_{ij}^k \geq 0, k \in K(i, j) \setminus K_1(i, j), (i, j) \in U \setminus U_0, \tag{6}$$

where  $I_i^+(U^k) = \{j \in I^k : (i, j) \in U^k\}, I_i^-(U^k) = \{j \in I^k : (j, i) \in U^k\}; x_{ij}^k$  – amount of the  $k^{th}$  product transported through an multiarc  $(i, j); d_{ij}^k$  – carrying

capacity of an multiarc  $(i, j)$  for the  $k^{\text{th}}$  product;  $d_{ij}^0$  – aggregate capacity of an multiarc  $(i, j) \in U_0$  for a total amount of products  $K_0(i, j)$ ;  $\lambda_{ij}^{kp}$  – weight of a unit of the  $k^{\text{th}}$  product transported through an multiarc  $(i, j)$  in the  $p^{\text{th}}$  additional constraint;  $\mu_{ij}^k$  – a flow transformation coefficient for arc  $(i, j)^k$ ,  $\mu_{ij}^k \in ]0, 1]$ ;  $\alpha_p$  – total weighted amount of products imposed by the  $p^{\text{th}}$  additional constraint;  $a_i^k$  – intensity of a node  $i$  for the  $k^{\text{th}}$  product,  $p_{ij}^k, q_{ij}^k, \beta, \gamma, a_i^k \in \mathbf{R}$ . Let's assume, that the denominator

$$q(x) = \sum_{(i,j) \in U} \sum_{k \in K(i,j)} q_{ij}^k x_{ij}^k + \gamma$$

of objective function  $f(x)$  does not change a sign for the set of multiflows  $x \in X$ . Without restriction of a generality we shall assume, that  $q(x) > 0, \forall x \in X$ .

### 2. The General Solution of the Homogeneous System

Let  $x$  be a multifold of the problem (1)–(6) i. e. components of the vector  $x$  meet the conditions (2)–(6). Along with the multifold  $x$  let us define support multifold  $\{x, U_S\}$  as a pair [1], containing of an arbitrary multifold  $x$  and a support [5]  $U_S$  of multigraph  $G = \{I, U\}$  of the problem (1) – (6),  $U_S = \{U_S^k, k \in K, U^*\}$ ,  $U_S^k \subset U^k, k \in K$ ;  $U^* \subseteq \overline{U}_0, \overline{U}_0 = \{(i, j) \in U_0 : |K_S^0(i, j)| > 1\}$ ,  $K_S(i, j) = \{k \in K(i, j) : (i, j)^k \in U_S^k\}$ ,  $(i, j) \in U$ ,  $K_S^0(i, j) = K_S(i, j) \cap K_0(i, j)$ ,  $(i, j) \in U_0$  of the problem (1)–(6). Let's consider some other multifold

$$\bar{x} = \left( \bar{x}_{ij}^k = x_{ij}^k + \Delta x_{ij}^k : (i, j) \in U, k \in K(i, j) \right)$$

Then  $\Delta x = \left( \Delta x_{ij}^k, (i, j) \in U, k \in K(i, j) \right)$  is the vector of flow increments along the multiarc  $(i, j) \in U$ . Let us denote

$$\begin{aligned} z_{ij} &= \sum_{k \in K_0(i,j)} x_{ij}^k, \\ \bar{z}_{ij} &= \sum_{k \in K_0(i,j)} \bar{x}_{ij}^k, \end{aligned} \tag{7}$$

$$\Delta z_{ij} = \bar{z}_{ij} - z_{ij} = \sum_{k \in K_0(i,j)} \Delta x_{ij}^k, \quad (i, j) \in U_0.$$

Since the multifold  $\bar{x}$  meets the conditions (2)–(6) then the following rela-

tions are true:

$$\sum_{j \in I_i^+(U^k)} \bar{x}_{ij}^k - \sum_{j \in I_i^-(U^k)} \mu_{ji}^k \bar{x}_{ji}^k = a_i^k, \quad i \in I^k, \quad k \in K, \tag{8}$$

$$\sum_{(i,j) \in U} \sum_{k \in K(i,j)} \lambda_{ij}^{kp} \bar{x}_{ij}^k = \alpha_p, \quad p = \overline{1, l}, \tag{9}$$

$$\sum_{k \in K_0(i,j)} \bar{x}_{ij}^k \leq d_{ij}^0, \quad (i, j) \in U^*. \tag{10}$$

where the part of the constraints (4) are written down only for the support multiarcs  $U^*$  [2, 5]. Subtracting from (8)–(10) the corresponding constraints (2)–(4), we obtain:

$$\sum_{j \in I_i^+(U^k)} \Delta x_{ij}^k - \sum_{j \in I_i^-(U^k)} \mu_{ji}^k \Delta x_{ji}^k = 0, \quad i \in I^k, \quad k \in K, \tag{11}$$

$$\sum_{(i,j) \in U} \sum_{k \in K(i,j)} \lambda_{ij}^k \Delta x_{ij}^k = 0, \quad p = \overline{1, l}, \tag{12}$$

$$\sum_{k \in K_0(i,j)} \Delta x_{ij}^k = \Delta z_{ij}, \quad (i, j) \in U^*, \tag{13}$$

where  $\Delta z_{ij}$  is defined by formula (7).

Let us order the components  $\Delta x$  of solution of system (11)–(13) according [5] of the following way:

$$\Delta x = (\Delta x_L, \Delta x_B, \Delta x_N),$$

where

$$\Delta x_L = (\Delta x_{ij}^k, (i, j)^k \in U_L^k, k \in K), \Delta x_B = (\Delta x_{ij}^k, (i, j)^k \in U_B^k, k \in K),$$

$$\Delta x_N = (\Delta x_{ij}^k, (i, j)^k \in U_N^k, k \in K), U_N^k = U^k \setminus (U_L^k \cup U_B^k).$$

In [5] we investigated theoretical-graphical properties of the structure of the support  $U_S = \{U_S^k, k \in K\}$  of the multigraph  $G = \{I, U\}$  for the problem (1) – (6). The aggregation of sets  $U_S = \{U_S^k, k \in K\}$  includes the support  $U_L = \{U_L^k, k \in K\}$  of multigraph  $G$  for system (2) and the set  $U_B = \{U_B^k, k \in K\}$  of bicycling arcs [2, 5].

The general solution of the homogeneous system (11) is the following [2, 5]:

$$\Delta x_{ij}^k = \sum_{(\tau, \rho)^k \in U^k \setminus U_L^k} \Delta x_{\tau\rho}^k \delta_{ij}^k(\tau, \rho), (i, j)^k \in U_L^k, k \in K, \tag{14}$$

where  $\delta^k(\tau, \rho) = (\delta_{ij}^k(\tau, \rho), (i, j)^k \in U^k)$  – characteristic vector, entailed by arc  $(\tau, \rho)^k \in U^k \setminus U_L^k$  concerning a support  $U_L^k$  for system (2),  $k \in K$  [1, 2, 5].

### 3. Formulae for Increment of Linear-Fractional Objective Function

We obtain the increment of the objective function (1) the extreme linear-fractional non-homogeneous problem (1)–(6) of flow programming with additional constraints.

$$\begin{aligned} \Delta f &= f(\bar{x}) - f(x) = \\ &= f(x + \Delta x) - f(x) = \frac{p(x + \Delta x)}{q(x + \Delta x)} - f(x) = \\ &= \frac{p(x + \Delta x) - f(x)q(x + \Delta x)}{q(x + \Delta x)} = \\ &= \left[ \left( \sum_{(i,j) \in U} \sum_{k \in K(i,j)} p_{ij}^k (x_{ij}^k + \Delta x_{ij}^k) + \beta \right) - \right. \\ &\quad \left. - f(x) \left( \sum_{(i,j) \in U} \sum_{k \in K(i,j)} q_{ij}^k (x_{ij}^k + \Delta x_{ij}^k) + \gamma \right) \right] / \\ &\quad / \left( \sum_{(i,j) \in U} \sum_{k \in K(i,j)} q_{ij}^k (x_{ij}^k + \Delta x_{ij}^k) + \gamma \right) = \left( p(x) + \right. \\ &\quad \left. + \sum_{(i,j) \in U} \sum_{k \in K(i,j)} p_{ij}^k \Delta x_{ij}^k - f(x) \left( q(x) + \sum_{(i,j) \in U} \sum_{k \in K(i,j)} q_{ij}^k \Delta x_{ij}^k \right) \right) / \\ &\quad / \left( \sum_{(i,j) \in U} \sum_{k \in K(i,j)} q_{ij}^k (x_{ij}^k + \Delta x_{ij}^k) + \gamma \right) \end{aligned}$$

or

$$\Delta f = \frac{\sum_{(i,j) \in U} \sum_{k \in K(i,j)} p_{ij}^k \Delta x_{ij}^k - f(x) \sum_{(i,j) \in U} \sum_{k \in K(i,j)} q_{ij}^k \Delta x_{ij}^k}{\sum_{(i,j) \in U} \sum_{k \in K(i,j)} q_{ij}^k (x_{ij}^k + \Delta x_{ij}^k) + \gamma} \tag{15}$$

Let's transform expressions in a numerator and a denominator for (15).

$$\sum_{(i,j) \in U} \sum_{k \in K(i,j)} p_{ij}^k \Delta x_{ij}^k = \sum_{k \in K} \sum_{(\tau,\rho)^k \in U^k \setminus U_L^k} \Delta x_{\tau\rho}^k \Delta_P^k(\tau, \rho), \tag{16}$$

where

$$\Delta_P^k(\tau, \rho) = p_{\tau\rho}^k + \sum_{(i,j)^k \in U_L^k} p_{ij}^k \delta_{ij}^k(\tau, \rho), \tag{17}$$

and

$$\sum_{(i,j) \in U} \sum_{k \in K(i,j)} q_{ij}^k \Delta x_{ij}^k = \sum_{k \in K} \sum_{(\tau,\rho)^k \in U^k \setminus U_L^k} \Delta x_{\tau\rho}^k \Delta_Q^k(\tau, \rho), \tag{18}$$

where

$$\Delta_Q^k(\tau, \rho) = q_{\tau\rho}^k + \sum_{(i,j)^k \in U_L^k} q_{ij}^k \delta_{ij}^k(\tau, \rho). \tag{19}$$

As  $\bar{x} = (\bar{x}_{ij}^k : (i, j) \in U, k \in K(i, j))$  is multiflow,  $\bar{x}_{ij}^k = x_{ij}^k + \Delta x_{ij}^k$ , that for the denominator  $g(\bar{x})$  of the objective function (1) the inequality is true:

$$g(\bar{x}) = \sum_{(i,j) \in U} \sum_{k \in K(i,j)} q_{ij}^k (x_{ij}^k + \Delta x_{ij}^k) + \gamma > 0$$

Hence the sign on an increment  $\Delta f$  of the objective function depends only on numerator.

Let's substitute (16) and (18) into numerator of the increment of the objective function (15). We have

$$\begin{aligned} N_{\Delta f} &= \sum_{(i,j) \in U} \sum_{k \in K(i,j)} p_{ij}^k \Delta x_{ij}^k - f(x) \sum_{(i,j) \in U} \sum_{k \in K(i,j)} q_{ij}^k \Delta x_{ij}^k = \\ &= \sum_{k \in K} \sum_{(\tau,\rho)^k \in U^k \setminus U_L^k} \Delta^k(\tau, \rho) \Delta x_{\tau\rho}^k, \end{aligned} \tag{20}$$

where

$$\Delta^k(\tau, \rho) = \Delta_P^k(\tau, \rho) - f(x) \Delta_Q^k(\tau, \rho), (\tau, \rho)^k \in U^k \setminus U_L^k, k \in K. \tag{21}$$

For performance of decomposition of an increment of the objective function we shall substitute (14) into (12).

$$\begin{aligned} & \sum_{k \in K} \sum_{(i,j)^k \in U^k} \lambda_{ij}^{kp} \Delta x_{ij}^k = \sum_{k \in K} \sum_{(i,j)^k \in U_L^k} \lambda_{ij}^{kp} \Delta x_{ij}^k + \sum_{k \in K} \sum_{(\tau,\rho)^k \in U^k \setminus U_L^k} \lambda_{\tau\rho}^{kp} \Delta x_{\tau\rho}^k = \\ & = \sum_{k \in K} \sum_{(i,j)^k \in U_L^k} \lambda_{ij}^{kp} \left[ \sum_{(\tau,\rho)^k \in U^k \setminus U_L^k} \Delta x_{\tau\rho}^k \delta_{ij}^k(\tau, \rho) \right] + \sum_{k \in K} \sum_{(\tau,\rho)^k \in U^k \setminus U_L^k} \lambda_{\tau\rho}^{kp} \Delta x_{\tau\rho}^k = \\ & = \sum_{k \in K} \sum_{(\tau,\rho)^k \in U^k \setminus U_L^k} \left( \lambda_{\tau\rho}^{kp} + \sum_{(i,j)^k \in U_L^k} \lambda_{ij}^{kp} \delta_{ij}^k(\tau, \rho) \right) \Delta x_{\tau\rho}^k = 0, \quad (22) \\ & \Lambda_{\tau\rho}^{kp} = \lambda_{\tau\rho}^{kp} + \sum_{(i,j)^k \in U_L^k} \lambda_{ij}^{kp} \delta_{ij}^k(\tau, \rho), (\tau, \rho)^k \in U^k \setminus U_L^k, p = \overline{1, l}. \end{aligned}$$

The equations (22) are transformed to the following kind:

$$\sum_{k \in K} \sum_{(\tau,\rho)^k \in U^k \setminus U_L^k} \Lambda_{\tau\rho}^{kp} \Delta x_{\tau\rho}^k = 0, p = \overline{1, l}. \quad (23)$$

Similarly we shall transform the equations of system (13).

$$\sum_{k \in K_0(i,j)} \sum_{(\tau,\rho)^k \in U^k \setminus U_L^k} \delta_{ij}(B_{\tau\rho}^k) \Delta x_{\tau\rho}^k = \Delta z_{ij}, (i, j) \in U^*, \quad (24)$$

where

$$\delta_{ij}(B_{\tau\rho}^k) = \begin{cases} \delta_{ij}^k(\tau, \rho), k \in K_0(i, j), \\ 0, k \notin K_0(i, j), \\ (i, j) \in U_0, (\tau, \rho)^k \in U^k \setminus U_L^k, k \in K. \end{cases}$$

or

$$\begin{aligned} & \sum_{k \in K_0(i,j)} \sum_{(\tau,\rho)^k \in U_B^k} \delta_{ij}(B_{\tau\rho}^k) \Delta x_{\tau\rho}^k = \\ & = \Delta z_{ij} - \sum_{k \in K_0(i,j)} \sum_{(\tau,\rho)^k \in U_N^k} \delta_{ij}(B_{\tau\rho}^k) \Delta x_{\tau\rho}^k, (i, j) \in U^*. \end{aligned} \quad (25)$$

Thus, we obtain the system of linear algebraic equations (23), (25). Let's present system (23), (25) in the matrix form:

$$D \Delta x_B = \tilde{\beta}, \tilde{\beta} = \begin{pmatrix} \tilde{\beta}_p, & p = \overline{1, l}, \\ \tilde{\beta}_{l+\xi(i,j)}, & (i, j) \in U^* \end{pmatrix}, \quad (26)$$

$$\Delta x_B = \left( \Delta x_{ij}^k, (i, j)^k \in U_B^k, k \in K \right),$$

$$\tilde{\beta}_p = - \sum_{k \in K} \sum_{(\tau, \rho)^k \in U_N^k} \Lambda_{\tau\rho}^{kp} \Delta x_{\tau\rho}^k, p = \overline{1, l},$$

$$\tilde{\beta}_{l+\xi(i, j)} = \Delta z_{ij} - \sum_{k \in K_0(i, j)} \sum_{(\tau, \rho)^k \in U_N^k} \delta_{ij}(B_{\tau\rho}^k) \Delta x_{\tau\rho}^k, (i, j) \in U^*.$$

where

$$D = \begin{pmatrix} D_1 \\ D_2 \end{pmatrix}, D_1 = (\Lambda_{\tau\rho}^{kp}, p = \overline{1, l}, t(\tau, \rho)^k = \overline{1, |U_B|}),$$

$$D_2 = (\delta_{ij}(B_{\tau\rho}^k), \xi(i, j) = \overline{1, |U^*|}, t(\tau, \rho)^k = \overline{1, |U_B|}),$$

$\xi = \xi(i, j)$  – number of the arc  $(i, j) \in U^*, \xi \in \{1, 2, \dots, |U^*|\}$ . The numbers  $\delta_{ij}(B_{\tau\rho}^k)$  are calculated as follows:

$$\delta_{ij}(B_{\tau\rho}^k) = \begin{cases} \delta_{ij}^k(\tau, \rho), k \in K_0(i, j), \\ 0, k \notin K_0(i, j), \\ (i, j) \in U_0, (\tau, \rho)^k \in U^k \setminus U_L^k, k \in K. \end{cases}$$

where  $B_{\tau\rho}^k = U_L^k \cup (\tau, \rho)^k$  – a bicycle, entailed by the arc  $(\tau, \rho)^k \in U^k \setminus U_L^k, k \in K$ . Also, for each bicycle  $B_{\tau\rho}^k$ , entailed by an arc  $(\tau, \rho)^k \in U_B^k$  we consider the determinants  $\Lambda_{\tau\rho}^{kp}$  [5, 6] of the bicycle  $B_{\tau\rho}^k$  for the equations (3) with numbers  $p = \overline{1, l}$ :

$$\Lambda_{\tau\rho}^{kp} = \sum_{(i, j)^k \in B_{\tau\rho}^k} \lambda_{ij}^{kp} \delta_{ij}^k(\tau, \rho), (\tau, \rho)^k \in U^k \setminus U_L^k,$$

or

$$\Lambda_{\tau\rho}^{kp} = \lambda_{\tau\rho}^{kp} + \sum_{(i, j)^k \in U_L^k} \lambda_{ij}^{kp} \delta_{ij}^k(\tau, \rho), (\tau, \rho)^k \in U^k \setminus U_L^k.$$

Since  $U_S = \{U_S^k, k \in K, U^*\}$  is a support of the multigraph  $G = \{I, U\}$  for the problem (1) – (6) [4, 5], then  $\det D \neq 0$ . We have

$$\Delta x_B = D^{-1} \tilde{\beta}. \tag{27}$$

Let's denote through  $D^{-1} = = (\nu_{zq} : z = \overline{1, \tilde{t}}, q = \overline{1, \tilde{t}})$  – elements of a inverse matrix,  $\tilde{t} = \sum_{k \in K} |U_B^k|$ .



Let's present (27) as (28).

$$\Delta x_{\tau\rho}^k = \sum_{p=1}^l \nu_{t(\tau,\rho)^k,p} \tilde{\beta}_p + \sum_{(i,j) \in U^*} \nu_{t(\tau,\rho)^k,l+\xi(i,j)} \tilde{\beta}_{l+\xi(i,j)}, \tag{28}$$

$$(\tau, \rho)^k \in U_B^k, k \in K, \tilde{\beta} = \begin{pmatrix} \tilde{\beta}_p, & p = \overline{1, l}, \\ \tilde{\beta}_{l+\xi(i,j)}, & (i, j) \in U^*, \end{pmatrix},$$

$$\tilde{\beta}_p = - \sum_{k \in K} \sum_{(\tau,\rho)^k \in U_N^k} \Lambda_{\tau\rho}^{kp} \Delta x_{\tau\rho}^k, p = \overline{1, l}, \tag{29}$$

$$\tilde{\beta}_{l+\xi(i,j)} = \Delta z_{ij} - \sum_{k \in K_0(i,j)} \sum_{(\tau,\rho)^k \in U_N^k} \delta_{ij}(B_{\tau\rho}^k) \Delta x_{\tau\rho}^k, (i, j) \in U^*. \tag{30}$$

Let's substitute (28) into numerator of the increment of the objective function (20):

$$\begin{aligned} & \sum_{(i,j) \in U} \sum_{k \in K(i,j)} p_{ij}^k \Delta x_{ij}^k - f(x) \sum_{(i,j) \in U} \sum_{k \in K(i,j)} q_{ij}^k \Delta x_{ij}^k = \\ & = \sum_{k \in K} \sum_{(\tau,\rho)^k \in U^k \setminus U_L^k} \Delta^k(\tau, \rho) \Delta x_{\tau\rho}^k = \\ & = \sum_{k \in K} \sum_{(\tau,\rho)^k \in U_B^k} \Delta^k(\tau, \rho) \Delta x_{\tau\rho}^k + \sum_{k \in K} \sum_{(\tau,\rho)^k \in U_N^k} \Delta^k(\tau, \rho) \Delta x_{\tau\rho}^k = \\ & = \sum_{k \in K} \sum_{(\tau,\rho)^k \in U_B^k} \Delta^k(\tau, \rho) \times \\ & \times \left( \sum_{p=1}^l \nu_{t(\tau,\rho)^k,p} \tilde{\beta}_p + \sum_{(i,j) \in U^*} \nu_{t(\tau,\rho)^k,l+\xi(i,j)} \tilde{\beta}_{l+\xi(i,j)} \right) + \\ & + \sum_{k \in K} \sum_{(\tau,\rho)^k \in U_N^k} \Delta^k(\tau, \rho) \Delta x_{\tau\rho}^k. \tag{31} \end{aligned}$$

Let us introduce the following denotation:

$$r_p = \sum_{k \in K} \sum_{(\tau,\rho)^k \in U_B^k} \Delta^k(\tau, \rho) \nu_{t(\tau,\rho)^k,p}, p = \overline{1, l};$$

$$r_{ij} = \sum_{k \in K} \sum_{(\tau,\rho)^k \in U_B^k} \Delta^k(\tau, \rho) \nu_{t(\tau,\rho)^k,l+\xi(i,j)}, (i, j) \in U^*.$$

Let's substitute (29) and (30) into (31). In result the numerator will be transformed to a kind (32):

$$N_{\Delta f} = \sum_{k \in K} \sum_{(\tau, \rho)^k \in U_N^k} \left( \Delta^k(\tau, \rho) - \sum_{p=1}^l r_p \Lambda_{\tau\rho}^{kp} - \sum_{(i,j) \in U^*} r_{ij} \delta_{ij}(B_{\tau\rho}^k) \right) \times \\ \times \Delta x_{\tau\rho}^k + \sum_{(i,j) \in U^*} r_{ij} \Delta z_{ij} \tag{32}$$

or

$$N_{\Delta f} = \sum_{k \in K} \sum_{(\tau, \rho)^k \in U_N^k} \tilde{\Delta}^k(\tau, \rho) \Delta x_{\tau\rho}^k + \sum_{(i,j) \in U^*} r_{ij} \Delta z_{ij}, \tag{33}$$

$$\tilde{\Delta}^k(\tau, \rho) = \Delta^k(\tau, \rho) - \sum_{p=1}^l r_p \Lambda_{\tau\rho}^{kp} - \sum_{(i,j) \in U^*} r_{ij} \delta_{ij}(B_{\tau\rho}^k). \tag{34}$$

**Theorem.** *The general solution of nonhomogeneous system (2) is calculated from the formulae (35) for the fixed  $k \in K$*

$$x_{ij}^k = \sum_{(\tau, \rho)^k \in U^k \setminus U_L^k} x_{\tau\rho}^k \delta_{ij}^k(\tau, \rho) + \left( \tilde{x}_{ij}^k - \sum_{(\tau, \rho)^k \in U^k \setminus U_L^k} \tilde{x}_{\tau\rho}^k \delta_{ij}^k(\tau, \rho) \right), \tag{35}$$

$$(i, j)^k \in U_L^k; \quad x_{\tau\rho}^k \in \mathbf{R},$$

where  $\tilde{x}^k = (\tilde{x}_{ij}^k, (i, j)^k \in U^k)$  – is any partial solution of the nonhomogeneous system (2) and  $\delta^k(\tau, \rho) = (\delta_{ij}^k(\tau, \rho), (i, j)^k \in U^k)$ ,  $(\tau, \rho)^k \in U^k \setminus U_L^k, k \in K$  is the system of characteristic vectors, entailed by an arc  $(\tau, \rho)^k \in U^k \setminus U_L^k, k \in K$  for the fixed  $k \in K$ , see [5].

**Remark.** Further, we shall use the partial solution

$$\tilde{x}^k = (\tilde{x}_{ij}^k, (i, j)^k \in U^k), k \in K$$

which is constructed to the following rules: non-supporting elements  $(\tau, \rho)^k \in U^k \setminus U_L^k, k \in K$  are equal to zeros and supporting elements  $(i, j)^k \in U_L^k, k \in K$  satisfy system (2).

Let's transform a denominator of the increment of the objective function (15). For it we transform the sum  $\sum_{(i,j) \in U} \sum_{k \in K(i,j)} q_{ij}^k x_{ij}^k$ , using (35) for arcs

$$(i, j)^k \in U_L^k, k \in K :$$

$$\sum_{(i,j) \in U} \sum_{k \in K(i,j)} q_{ij}^k x_{ij}^k = \sum_{k \in K} \sum_{(i,j)^k \in U^k} q_{ij}^k x_{ij}^k = \sum_{k \in K} \sum_{(i,j)^k \in U_L^k} q_{ij}^k x_{ij}^k +$$

$$\begin{aligned}
 & + \sum_{k \in K} \sum_{(i,j) \in U^k \setminus U_L^k} q_{ij}^k x_{ij}^k = \sum_{k \in K} \sum_{(i,j) \in U_L^k} q_{ij}^k \left[ \sum_{(\tau,\rho) \in U^k \setminus U_L^k} x_{\tau\rho}^k \delta_{ij}^k(\tau, \rho) + \right. \\
 & \left. + \left( \tilde{x}_{ij}^k - \sum_{(\tau,\rho) \in U^k \setminus U_L^k} \tilde{x}_{\tau\rho}^k \delta_{ij}^k(\tau, \rho) \right) \right] + \sum_{k \in K} \sum_{(\tau,\rho) \in U^k \setminus U_L^k} q_{\tau\rho}^k x_{\tau\rho}^k =
 \end{aligned}$$

[ change the order of summation: ]

$$\begin{aligned}
 & = \sum_{k \in K} \sum_{(\tau,\rho) \in U^k \setminus U_L^k} x_{\tau\rho}^k \left( q_{\tau\rho}^k + \sum_{(i,j) \in U_L^k} q_{ij}^k \delta_{ij}^k(\tau, \rho) \right) + \\
 & + \sum_{k \in K} \sum_{(i,j) \in U_L^k} q_{ij}^k \left[ \tilde{x}_{ij}^k - \sum_{(\tau,\rho) \in U^k \setminus U_L^k} \tilde{x}_{\tau\rho}^k \delta_{ij}^k(\tau, \rho) \right] =
 \end{aligned}$$

Let's denote

$$Q = \sum_{k \in K} \sum_{(i,j) \in U_L^k} q_{ij}^k \left[ \tilde{x}_{ij}^k - \sum_{(\tau,\rho) \in U^k \setminus U_L^k} \tilde{x}_{\tau\rho}^k \delta_{ij}^k(\tau, \rho) \right].$$

We have:

$$\sum_{(i,j) \in U} \sum_{k \in K(i,j)} q_{ij}^k x_{ij}^k = \sum_{k \in K} \sum_{(\tau,\rho) \in U^k \setminus U_L^k} \Delta_Q^k(\tau, \rho) x_{\tau\rho}^k + Q, \tag{36}$$

where

$$\begin{aligned}
 \Delta_Q^k(\tau, \rho) & = q_{\tau\rho}^k + \sum_{(i,j) \in U_L^k} q_{ij}^k \delta_{ij}^k(\tau, \rho), \\
 Q & = \sum_{k \in K} \sum_{(i,j) \in U_L^k} q_{ij}^k \left( \tilde{x}_{ij}^k - \sum_{(\tau,\rho) \in U^k \setminus U_L^k} \tilde{x}_{\tau\rho}^k \delta_{ij}^k(\tau, \rho) \right) \tag{37}
 \end{aligned}$$

Let's substitute (37) into a denominator of the increment of the objective function (15).

$$\begin{aligned}
 & \sum_{(i,j) \in U} \sum_{k \in K(i,j)} q_{ij}^k (x_{ij}^k + \Delta x_{ij}^k) + \gamma = \\
 & = \sum_{k \in K} \sum_{(\tau,\rho) \in U^k \setminus U_L^k} \Delta_Q^k(\tau, \rho) x_{\tau\rho}^k + \sum_{k \in K} \sum_{(\tau,\rho) \in U^k \setminus U_L^k} \Delta_Q^k(\tau, \rho) \Delta x_{\tau\rho}^k + Q + \gamma =
 \end{aligned}$$

$$= \sum_{k \in K} \sum_{(\tau, \rho)^k \in U^k \setminus U_L^k} \Delta_Q^k(\tau, \rho) \left( x_{\tau\rho}^k + \Delta x_{\tau\rho}^k \right) + Q + \gamma \tag{38}$$

Using (33) and (38) we have transformed the formulas of the increment of the objective function (15):

$$\Delta f = \frac{\sum_{k \in K} \sum_{(\tau, \rho)^k \in U_N^k} \tilde{\Delta}^k(\tau, \rho) \Delta x_{\tau\rho}^k + \sum_{(i, j) \in U^*} r_{ij} \Delta z_{ij}}{\sum_{k \in K} \sum_{(\tau, \rho)^k \in U^k \setminus U_L^k} \Delta_Q^k(\tau, \rho) \left( x_{\tau\rho}^k + \Delta x_{\tau\rho}^k \right) + Q + \gamma}, \tag{39}$$

$$\tilde{\Delta}^k(\tau, \rho) = \Delta^k(\tau, \rho) - \sum_{p=1}^l r_p \Lambda_{\tau\rho}^{kp} - \sum_{(i, j) \in U^*} r_{ij} \delta_{ij}^k(B_{\tau\rho}^k), \tag{40}$$

where

$$\Delta^k(\tau, \rho) = \Delta_P^k(\tau, \rho) - f(x) \Delta_Q^k(\tau, \rho),$$

$$\Delta_P^k(\tau, \rho) = p_{\tau\rho}^k + \sum_{(i, j)^k \in U_L^k} p_{ij}^k \delta_{ij}^k(\tau, \rho),$$

$$\Delta_Q^k(\tau, \rho) = q_{\tau\rho}^k + \sum_{(i, j)^k \in U_L^k} q_{ij}^k \delta_{ij}^k(\tau, \rho),$$

$$r_p = \sum_{k \in K} \sum_{(\tau, \rho)^k \in U_B^k} \Delta^k(\tau, \rho) \nu_{t(\tau, \rho)^k, p}, \quad p = \overline{1, l},$$

$$r_{ij} = \sum_{k \in K} \sum_{(\tau, \rho)^k \in U_B^k} \Delta^k(\tau, \rho) \nu_{t(\tau, \rho)^k, l + \xi(i, j)}, \quad (i, j) \in U^*.$$

### References

- [1] R. Gabasov, F.M. Kirillova, *Methods of Linear Programming. Part 3: Special Problems*, Minsk, BSU (1980), In Russian.
- [2] L.A. Pilipchuk, *Linejnyje Neodnorodnyje Zadachi Potokovogo Programirovanija*, Minsk, BSU (2009), In Russian.
- [3] L.A. Pilipchuk, A.A. Laguto, Extremalnaja setevaja zadacha drobnolineinogo programmirovaniya, *Vestnik BGU*, **1**, No. 2 (2005), 106-108, In Russian.

- [4] L.A. Pilipchuk, A.S. Pilipchuk, Y.H. Pesheva, Algorithms for construction of optimal and suboptimal solutions in network optimization problems, *IJPAM*, **54**, No. 2 (2009), 193-205.
- [5] L.A. Pilipchuk, *Razrejennyje Nedoopredelennyje Sistemi Lineinix Algebraicheskix Uravnenii*, Minsk, BSU (2012), In Russian.
- [6] L.A. Pilipchuk, I.V. Romanovski, Y.H. Pesheva, Inverse matrix updating in one inhomogeneous network flow programming problem, *Mathematica Balkanica*, **21**, No-s: 3, 4 (2007), 329-338.

