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Acute Effects of Whole-Body Vibration on the Postural Organization of Gait Initiation in Young Adults and Elderly: A Randomized Sham Intervention Study

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Whole-body vibration (WBV) is a training method that exposes the entire body to mechanical oscillations while standing erect or seated on a vibrating platform. This method is nowadays commonly used by clinicians to improve specific motor outcomes in various sub-populations such as elderly and young healthy adults, either sedentary or well-trained. The present study investigated the effects of acute WBV application on the balance control mechanisms during gait initiation (GI) in young healthy adults and elderly. It was hypothesized that the balance control mechanisms at play during gait initiation may compensate each other in case one or several components are perturbed following acute WBV application, so that postural stability and/or motor performance can be maintained or even improved. It is further hypothesized that this capacity of adaptation is altered with aging. Main results showed that the effects of acute WBV application on the GI postural organization depended on the age of participants. Specifically, a positive effect was observed on dynamic stability in the young adults, while no effect was observed in the elderly. An increased stance leg stiffness was also observed in the young adults only. The positive effect of WBV on dynamic stability was ascribed to an increase in the mediolateral amplitude of "anticipatory postural adjustments" following WBV application, which did overcompensate the potentially destabilizing effect of the increased stance leg stiffness. In elderly, no such anticipatory (nor corrective) postural adaptation was required since acute WBV application did not elicit any change in the stance leg stiffness. These results suggest that WBV application may be effective in improving dynamic stability but at the condition that participants are able to develop adaptive changes in balance control mechanisms, as did the young adults. Globally, these findings are thus in agreement with the hypothesis that balance control mechanisms are interdependent within the postural system, i.e., they may compensate each other in case one component (here the leg stiffness) is perturbed.

Keywords: whole-body vibration (WBV), gait initiation, elderly, young adults, anticipatory postural adjustment (APA)

INTRODUCTION

Whole-body vibration (WBV) is a training method that exposes the entire body to mechanical oscillations while standing erect or seated on a vibrating platform. This method is nowadays commonly used by clinicians to improve specific motor outcomes in various sub-populations such as elderly and young healthy adults, either sedentary or well-trained. Specifically, it has been shown that WBV application might be beneficial to numerous lower limbs motor outcomes, such as endurance, power, strength, neuromuscular activity, flexibility, and knee stability [for young healthy subjects, see for example (1–7); for elderly, see for example (8–13), for review see (14)].

Balance and locomotion might also be improved by WBV application, as quantified (i) with center of pressure (COP) measures in static upright condition [for young healthy adults, see for example (3, 15, 16); for elderly, see for example (17–20)], and (ii) with commonly-used clinical tests such as the single-leg-stance test, the Tinetti test, the Timed-Up-and-Go test, the Berg Balance Scale, and the Limits of stability. However, it is well-recognized that these classical clinical tests are subjective, show ceiling effects, and are usually not responsive enough to measure small progresses or deteriorations in a subject's ability to balance (21, 22). Mancini and Horak (22) further stressed that the greatest limitation of this clinical approach to rating balance is that it cannot specify what type of balance problem a subject suffers in order to direct a treatment. Upright balance maintenance during locomotor tasks is indeed a highly complex task since it necessitates the coordination between many complementary postural mechanisms, including dynamic postural phenomena before the swing foot clearance (23–25), the regulation of stance leg stiffness (26), the swing foot placement on the support surface (27), the braking of center of mass fall (28–30) etc. The investigation of these mechanisms [cf. description below; see also (31) for a recent review] requires an in-depth biomechanical analysis with force plate recordings. Such analysis is not provided in the classical clinical tests reported above. In fact, the classical clinical test, as Timed Up and Go test for example, could be limited to determined individual risk of falls in elderly (32). Furthermore, Topper et al. (33) show that falls happened most frequently in elderly subjects scoring poorly on clinical tests emphasizing transfer of quasi-static to dynamic situations.

Gait initiation is a functional task that is classically used in the literature as an experimental paradigm to investigate how the central nervous system (CNS) controls balance in dynamical conditions in both healthy adults [e.g., (31–35) for recent articles] and pathological patients [e.g., (36–40) for recent articles]. Gait initiation appears to be the major biomechanical model, complementary to the classical clinical test, in order to predict postural disorders in elderly fallers and non-fallers (41–44). Therefore, it seems highly appropriate for an investigation on the effects of WBV on dynamic balance. Gait initiation corresponds to the transient period between static erect posture and steady state walking (23–25). It can be divided into two successive phases: a postural phase that precedes the onset of the swing heel off (the so called "anticipatory postural adjustments",

APA) followed by an execution phase that ends at the time of swing foot contact (FC) with the ground.

During APA, the COP is shifted backward, creating the initial forward propulsive forces that are necessary to reach the intended center of mass (COM) velocity and step length (23, 25, 45). At the same time, the COP is shifted laterally toward the swing leg, which acts to propel the COM toward the stance leg (23, 26, 35, 46, 47). This anticipatory mediolateral postural dynamic acts to attenuate the COM fall toward the swing leg during the execution phase under gravity (26, 48, 49). It has therefore a stabilizing function. In case mediolateral APA are not sufficient to ensure stabilization, a strategy of lateral swing foot placement that enlarges the base of support size has been documented (27, 46, 47, 50, 51). The development of APA and the lateral swing foot placement during locomotor tasks are known to be dependent on somatosensory inputs from the lower limbs (52–55). The perturbation of these inputs by the applications of WBV might thus alter these two mechanisms and increase instability and/or reduce motor performance.

In addition to mediolateral APA and lateral swing foot placement, recent modeling study showed that increasing the stance leg stiffness along the mediolateral direction would result in a larger COM fall toward the swing leg side, thus leading to an increased mediolateral instability. The application of WBV may trigger a "tonic vibration reflex" (TVR) via the activation of muscle spindles of the lower limbs (56, 57). Although controversial (8, 58–60), this TVR might potentially be responsible for an increase in lower limbs stiffness and may thus have a negative impact on stability.

Globally, this brief literature review suggests that WBV may potentially perturb the balance control mechanisms involved in gait initiation and may therefore induce instability. This statement thus markedly contrasts with the results of the above-reported clinical tests, which rather suggest that WBV may be effective in improving relatively basic balance ability and locomotion. Thus, the purpose of this study is to clarify the effects of acute WBV application on the balance control mechanisms during gait initiation in young healthy adults and elderly. It is hypothesized that the balance control mechanisms at play during gait initiation may compensate each other in case one or several components are perturbed following acute WBV application, so that postural stability and/or motor performance can be maintained (or even improved). It is further hypothesized that this capacity of adaptation is altered with aging, with a consequent increased instability following WBV application.

METHODS

Participants

The study is a randomized investigation that includes 81 healthy adults (i.e., 41 young and 40 elderly). The non-probability convenience method is used, i.e., participants were randomly assigned to one of the four following treatment groups using the "envelope method" (see below): (1) 20 young adults (11 men and 9 women, mean age 25.3 ± 3.5 years, height 1.71 ± 0.05 m and body-mass 71.4 ± 5.3 kg) were assigned to the Young WBV training group (YWBV); (2) 21 matched young adults

were assigned to the Young Sham Group (YSG) (11 men and 10 women, mean age 26.6 ± 4.2 years, height 1.74 ± 0.04 m and body-mass 72.1 ± 4.9 kg); (3) 20 elderly (9 men and 11 women, mean age 83.5 ± 2.8 years, height 1.69 ± 0.06 m and body-mass 70.4 ± 4.3 kg) were assigned to the Elderly WBV training group (EWBV) and (4) 20 matched elderly (9 men and 11 women, mean age 84.2 ± 3.7 years, height 1.71 ± 0.07 m and body-mass 71.7 ± 3.9 kg) were assigned to the Elderly Sham Group (ESG; see **Table 1**). In the "envelope method," each participant chooses a closed envelope in which his/her treatment group is indicated in a code form. The participant does not have access to this code but the experimenters do (single blinded condition).

The two WBV groups (young adults and elderly) received a single WBV training and the two sham groups received a placebo treatment (cf. below for description). As stated above, participants were blinded to their allocation group. Participants had no recent history of trauma, known metabolic disorders, inflammatory infectious arthropathies, bone malignancies or neurological disease. In addition, participants were all naïve about WBV treatment. They all gave written consent after having been informed of the nature and purpose of the experiment which was approved by local ethics committees from the CIAMS Research Unit, Equipe d'Accueil (EA) 4532. The study complied with the standards established by the Declaration of Helsinki and was assigned the following trial registration number: 2017-002539-40.

Experimental Task and Conditions

Experiments took place in the Biomechanics laboratory of the Paris-Saclay University located within the Kremlin-Bicêtre Hospital (Paris, France). Physical conditions (room temperature and time of the day) were common to all treatment groups, and the same before/after the WBV treatment.

Participants initially stood barefoot in a natural upright posture on a force plate (0.9 × 1.80 m, AMTI, Watertown, USA) embedded at the beginning of a 6 m walkway track. The feet were shoulder-width apart, with the arms alongside the trunk and the gaze directed forward to a small target at eye level (2 cm diameter, 5 m distant). The locations of the heel and big toe of each foot in the initial posture were marked with sections of adhesive tape placed on the force plate and were used as a visual reference on which participants positioned themselves under the supervision of the experimenters. From this initial posture, participants performed two series of 10 gait initiation trials: one series just before, and a second series immediately after a specific treatment (pre- and post-treatment conditions, respectively) depending on their group (WBV or sham). In both pre- and post-treatment conditions, participants initiated gait at a spontaneous velocity and at their own initiative following an auditory signal delivered by the experimenter, and then continued walking straight until the end of the track. Participants initiated gait with their preferred leg in all trials. One blank trial was provided in the pre-manipulation condition (not recorded) to ensure that the instructions were well-understood by the participant and that the material was operational. The rest time was ~10 s between trials.

WBV and Placebo Treatment

For both the WBV group and the sham group, participants stood upright on a vibration platform (referee Power Fitness Double D®) with knees flexed ~30° and barefoot. During the treatment, knee angle was monitored on-line by both the subject him/herself and the experimenters thanks to a visual feedback provided by the signal of a monoaxial electrogoniometer (Biometrics®) fixed on the right leg. Participants were instructed to maintain the signal within a 25–35 range degrees.

For both young adults and elderly, the WBV application included four 45 s bouts of vibration, intercalated by 1 min of seated rest without vibration between bouts (61–63). Vibrations were delivered by the vibration platform at a frequency of 50 Hz [this frequency is known to enhance locomotor task and intralimb coordination (61)] with a vertical displacement of 2 mm and a 2 g acceleration.

The sham group received a treatment that followed exactly the same procedure as the WBV group except that no "real" vibrations were applied to participants. In order to maintain the most realistic placebo conditions as possible, participants were instructed by an experimenter that they could not physically feel the vibrations because they were too small to be sensed.

Mechanical Model

The same mechanical model as in a previous study was used to determine the stance leg stiffness along the mediolateral direction during the execution phase of gait initiation [for details on this model and the related equations of motion, see (26)]. In brief, the human body was modeled as a single conic inverted pendulum which rotates around a fixed point corresponding to the stance ankle. It was considered that the COM falls laterally under the influence of two forces: the gravity force $P = mg$ (where m is the mass of the whole body, and g is the gravitational acceleration) and an elastic restoring mediolateral force T (in Newtons) that reflects active muscular control of the movement (64, 65), with $T = k|yM|$ where k is the stance leg stiffness (Newtons/meter)

TABLE 1 | Anthropometric data of subjects in both WBV and sham groups (young adults and elderly).

Group	Variables	WBV group	Sham group	*P*-values
Young adults (n = 41)	Women (*n*)	9	10	NS
	Men (*n*)	11	11	NS
	Age (years)	25.30 ± 3.50	26.6 ± 4.2	NS
	Height (m)	1.71 ± 0.05	1.74 ± 0.04	NS
	Body mass (kg)	71.40 ± 5.30	72.10 ± 4.90	NS
Elderly (n = 40)	Women (*n*)	11	11	NS
	Men (*n*)	9	9	NS
	Age (years)	83.50 ± 2.80	84.20 ± 3.70	NS
	Height (m)	1.69 ± 0.06	1.71 ± 0.07	NS
	Body mass (kg)	70.40±4.30	71.70±3.90	NS

Reported values are means ± standard deviation.
NS, non-significant difference.

and |yM| is the absolute value of the mediolateral COM shift (in meters), systematically oriented toward the swing leg (positive values) during the execution phase. The initial position and velocity of the cone corresponded to the position and velocity of the participant's COM at toe off.

Raw Data

Force-plate data were low-pass filtered using a second order Butterworth filter with a 10 Hz (30) cut-off frequency. The mediolateral (yp) and anteroposterior (xp) coordinates of the COP (in meters) were computed from force-plate data as follows:

$$y_P = \frac{Mx + Fy \times dz}{Fz} \tag{1}$$

$$x_P = \frac{-My + Fx \times dz}{Fz} \tag{2}$$

where Mx and My are the moments (in Newtons.meters) around the anteroposterior and mediolateral axes (at the force-plate origin), respectively; Fx, Fy, and Fz (in Newtons) are the mediolateral, anteroposterior, and vertical ground reaction forces, respectively; and dz (in meters) is the distance between the surface of the force-plate and its origin which is located below this surface.

Instantaneous COM acceleration along the anteroposterior and mediolateral axes was determined from the ground reaction forces according to the Newton's second law. COM velocity and displacement were computed by successive numerical integrations of COM acceleration using the rectangles method (66) and integration constants equal to zero, i.e., initial velocity and displacement null (23).

Experimental Dependent Variables

The biomechanical traces and the representations of the main experimental variables obtained for one representative young subject of the WBV group initiating gait (one trial) in the pre-treatment condition and post-treatment condition are presented in the **Figure 2**. The following instants were determined from the biomechanical traces: gait initiation onset (t_0), swing heel-off, swing toe-off, swing foot-contact, and rear foot-off. These instants were determined from force-plate data (23, 67, 68). Two t_0 times were estimated, one for the mediolateral axis and one for the anteroposterior axis. The t_0 times corresponded to the instants when the mediolateral or anteroposterior COP trace deviated 2.5 standard deviations from its baseline value.

The mediolateral and anteroposterior COM position in the initial upright static posture were estimated by averaging the COP position during the 250 ms period preceding the "all set" signal. Gait initiation was divided into APA (from t_0 to heel-off), swing foot-lift (from heel-off to toe-off), and execution phase (from toe-off to foot-contact). The duration of APA along the mediolateral and anteroposterior axes were computed separately, because the t_0 times for these two axes do not necessarily occur simultaneously. The amplitude of APA was characterized by the peaks of the backward and mediolateral COP shift obtained during the APA time window. COM velocity and displacement along the mediolateral and anteroposterior axes were quantified at heel-off and foot-contact.

The spatiotemporal features of gait performance during the execution phase included: the swing phase duration, the anteroposterior COM velocity at foot-contact (progression velocity), and the step length. Step length corresponds to the difference between the most backward COP position during gait initiation and the COP position at the time of rear foot-off (69). Rear foot off time was marked with the mediolateral COP trace.

The spatiotemporal features of postural stability during the execution phase included: the step width, the ML COM position at FC, the ML COM velocity at FC and the margin of stability (MOS). An adaptation of the MOS introduced by Hof et al. (70) was used to quantify the mediolateral dynamic stability at foot-contact (thereafter referred to as "stability"). The MOS corresponds to the difference between the mediolateral boundary of the base of support (BOSymax, in meters) and the mediolateral position of the "extrapolated COM" at swing foot-contact (yCOMFC, in meters). Thus:

$$MOS = BOSymax -_y COMFC \tag{3}$$

Participants systematically landed on the force-plate with the swing heel first, then the toe. Under such foot landing strategy, it is known that BOSymax could be estimated with the mediolateral COP position at the time of rear foot-off (69, 71). Based on the study by Hof et al. (70) and the results from our previous studies (26, 27, 69, 71, 72) the mediolateral position of the extrapolated COM at foot-contact (yCOMFC) was calculated as follows:

$$_yCOMFC = yM_{FC} + \frac{y'M_{FC}}{\omega_0} \tag{4}$$

where yM_{FC} and y'M_{FC} are respectively the mediolateral COM position (in meters) and velocity at foot-contact (in meters/second), and ω_0 is the eigenfrequency of the body (Hz), modeled as an inverted pendulum and calculated as follows:

$$\omega_0 = \sqrt{\frac{g}{l}} \tag{5}$$

where g = 9.81 m/s^2 is the gravitational acceleration and l is the length of the inverted pendulum, which in this study corresponded to 57.5% of body height (73). Mediolateral dynamic stability at foot-contact is preserved on the condition that $_y$COMFC is within BOSymax, which corresponds to a positive MOS. A negative MOS indicates a mediolateral instability and implies that a corrective action is required to maintain balance. Hence, variables related to the mediolateral stability included the MOS and its components, i.e., step width, mediolateral COM velocity and position at swing foot-contact. Step width corresponds to the difference between the most lateral position of the mediolateral COP trace obtained during the first plateau of the trace and the mediolateral COP position at the time of rear foot-off (69).

Statistics

Mean values and standard deviations were calculated for each variable in each condition. The normality of data was checked

using the Kolmogorov–Smirnov test and the homogeneity of variances was checked using the Bartlett test. Repeated measures (RM) ANOVAs with the treatment (pre-treatment condition vs. post-treatment condition) as within subject factor and the group (sham group vs. WBV group) as between subjects' factor were used on each experimental variable. Because this research focuses on the effect of WBV application on gait initiation in young and elderly adults, merely than on the effects of age on gait initiation, the RM ANOVAs were conducted for young and elderly adults taken separately. When necessary, a significant outcome was followed-up with the Tukey *post-hoc* test. Finally, linear correlation between variables was assessed with the Pearson coefficient *r*. The threshold of significance was set at $p < 0.05$.

RESULTS

Biomechanical Traces

The time course of the biomechanical traces was globally similar in the two groups (young adults and elderly) and in the different treatment conditions (WBV and sham). The traces obtained in a representative young adult subject, before and after the WBV treatment, are reported in the **Figure 1**.

As can be seen from this figure, swing heel off was systematically preceded by postural dynamics that corresponded to APA. During these APA, the COP displacement reached a peak value in a backward direction (see the negative variation of the xP trace) and toward the swing leg side (negative variation of the yP trace), while the COM velocity was directed forwards (positive variation of the x'M trace) and toward the stance leg side (positive variation of the y'M trace). The mediolateral COM velocity trace reached a first peak value toward the stance leg side at around heel off. This trace, then fell toward the swing leg side and a second peak value toward this side was reached a few milliseconds after foot contact. The anteroposterior COM velocity increased progressively until it reached a peak value a few milliseconds after swing foot contact. The mediolateral COM shift trace was bell-shaped and reached a peak value toward the stance leg side at the beginning of the swing phase, while the anteroposterior COM was continuously shifted forward (see **Figure 2**). Differences across the conditions are reported in the paragraphs below.

Initial Posture, Anticipatory Postural Adjustments, and Foot-Lift Phase

In both the young adults and the elderly, no baseline differences were found between the WBV and sham groups ($p > 0.05$) for all the variables (see **Table 2**).

In both the young adults and the elderly, statistical analysis showed that there was no significant effect of the group (sham group vs. WBV group) or treatment (pre-treatment condition vs. post-treatment condition) nor any significant interaction between these two factors on the initial COM position along the mediolateral or anteroposterior direction.

In the elderly, there was also no significant effect of the group or treatment nor any significant interaction between these two factors on the spatiotemporal parameters of APA along
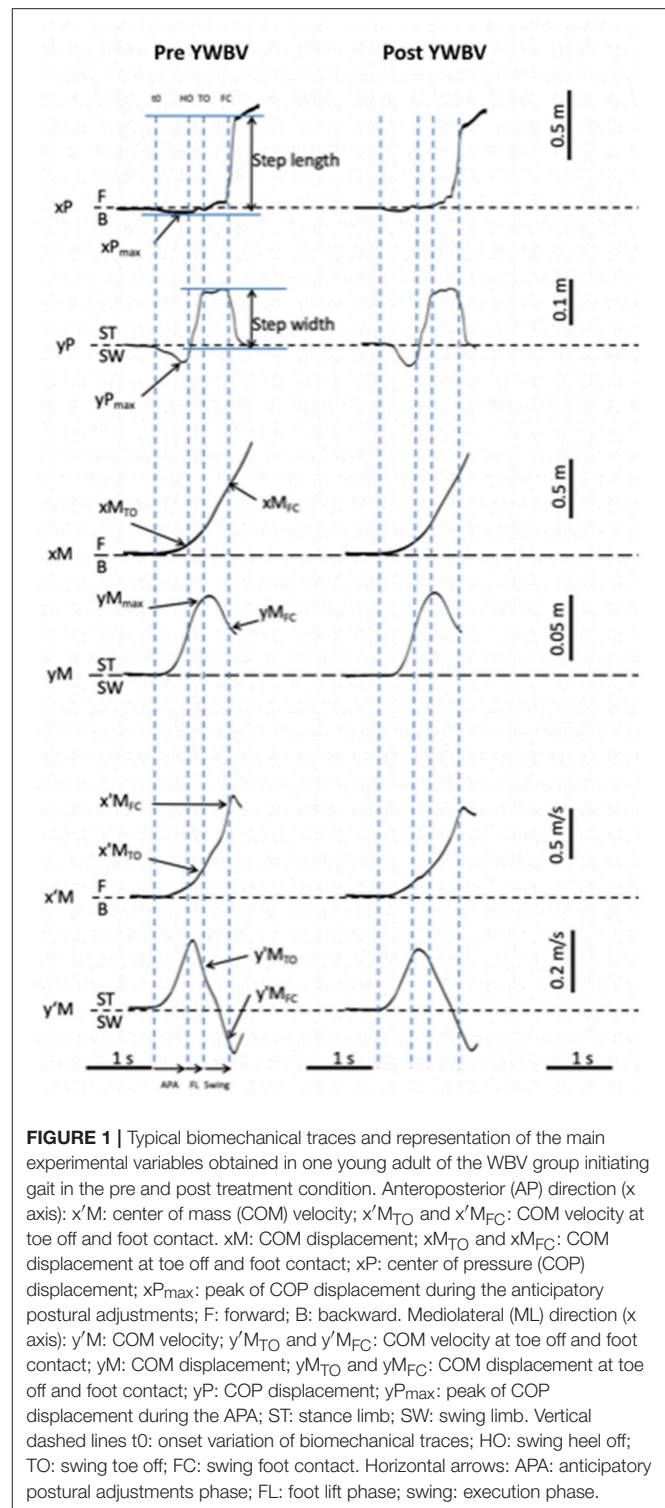

FIGURE 1 | Typical biomechanical traces and representation of the main experimental variables obtained in one young adult of the WBV group initiating gait in the pre and post treatment condition. Anteroposterior (AP) direction (x axis): x'M: center of mass (COM) velocity; x'M$_{TO}$ and x'M$_{FC}$: COM velocity at toe off and foot contact. xM: COM displacement; xM$_{TO}$ and xM$_{FC}$: COM displacement at toe off and foot contact; xP: center of pressure (COP) displacement; xP$_{max}$: peak of COP displacement during the anticipatory postural adjustments; F: forward; B: backward. Mediolateral (ML) direction (x axis): y'M: COM velocity; y'M$_{TO}$ and y'M$_{FC}$: COM velocity at toe off and foot contact; yM: COM displacement; yM$_{TO}$ and yM$_{FC}$: COM displacement at toe off and foot contact; yP: COP displacement; yP$_{max}$: peak of COP displacement during the APA; ST: stance limb; SW: swing limb. Vertical dashed lines t0: onset variation of biomechanical traces; HO: swing heel off; TO: swing toe off; FC: swing foot contact. Horizontal arrows: APA: anticipatory postural adjustments phase; FL: foot lift phase; swing: execution phase.

the mediolateral or anteroposterior direction (APA duration, peak COP shift, COM shift, and velocity at heel-off), nor on the swing foot-lift phase duration. In contrast, in the young adults, there was a significant effect of the treatment [$F_{(1, 39)}$ = 17.94, $p < 0.001$] on the mediolateral peak of anticipatory

COP shift, along with a significant group X treatment interaction [$F_{(1,39)} = 8.83$, $p < 0.01$]. Similarly, there was a significant effect of the treatment [$F_{(1,39)} = 8.89$, $p < 0.01$], along with a significant group X treatment interaction [$F_{(1,39)} = 4.38$, $p = 0.04$] on the mediolateral COM velocity at heel-off. *Post-hoc* analysis further revealed that these two interactions could be ascribed to the result that none of these two APA related-parameters were significantly different between the pre and post-treatment condition for the sham group, while both were significantly larger in the post-treatment condition than in the pre-treatment condition for the WBV group ($p < 0.001$ for the mediolateral peak of anticipatory COP shift

and $p < 0.05$ for the mediolateral COM velocity at heel-off; cf. **Table 2**).

Motor Performance

In both the young adults and the elderly, no baseline differences were found between the WBV and sham groups ($p > 0.05$) for all the variables (see **Table 3**).

In both the young adults and the elderly, statistical analysis showed that there was no significant main effect of the group or treatment nor significant interaction between these two factors on the execution phase duration, step length, and progression velocity at foot contact.

Stability

In both the young adults and the elderly, no baseline differences were found between the WBV and sham groups ($p > 0.05$) for all the variables (cf. **Table 3**).

In the elderly, statistical analysis showed that there was no significant effect of the group or treatment nor any significant interaction between these two factors on the MOS and related components (i.e., step width, mediolateral COM position, and velocity at foot-contact). In contrast, in the young adults, there was a significant effect of the treatment, along with a significant group X treatment interaction on the following variables: MOS [$F_{(1,39)} = 5.14$, $p = 0.03$; $F_{(1,39)} = 5.62$, $p = 0.02$, respectively], mediolateral COM position [$F_{(1,39)} = 7.32$, $p = 0.01$, $F_{(1,39)} = 5.19$, $p = 0.03$, respectively], and mediolateral COM velocity at foot-contact [$F_{(1,39)} = 10.14$, $p < 0.01$, $F_{(1,39)} = 4.51$, $p = 0.04$; respectively]. *Post-hoc* analysis further revealed that these interactions could be ascribed to the result that none of these variables were significantly different between the pre and the post-treatment condition for
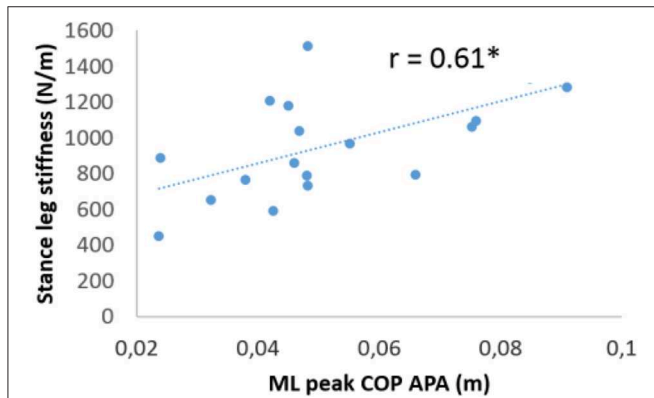

FIGURE 2 | Linear regression between normalized medio-lateral peak anticipatory center-of-pressure (COP) shift and the normalized medio-lateral stance leg stiffness in the WBV condition. Each point represents the average value of subjects in the WBV condition ($r = 0.61$, $p < 0.01$).

TABLE 2 | Comparison of APA and foot lift parameters between the pre- and post-treatment condition in the WBV and sham group (young adults and elderly).

	APA and Foot lift phase	WBV group		Sham group		Group X treatment interaction
	Variables	Pre-treatment	Post-treatment	Pre-treatment	Post-treatment	P-values
Young adults	AP COP shift (cm)	4.94 ± 1.51	5.29 ± 1.23	5.44 ± 1.37	5.52 ± 1.41	NS
	ML COP shift(cm)	4.61 ± 2.17	5.35 ± 2.09***	4.99 ± 1.27	5.12 ± 1.43	<0.001
	AP APA duration (s)	0.05 ± 0.11	0.47 ± 0.01	0.51 ± 0.10	0.50 ± 0.09	NS
	ML APA duration (s)	0.45 ± 0.08	0.47 ± 0.09	0.49 ± 0.01	0.45 ± 0.07	NS
	Foot lift duration (s)	0.12 ± 0.02	0.12 ± 0.03	0.14 ± 0.04	0.13 ± 0.04	NS
	AP COM velocity at HO (m/s)	0.21 ± 0.04	0.22 ± 0.05	0.23 ± 0.04	0.22 ± 0.04	NS
	ML COM velocity at HO (m/s)	0.14 ± 0.04	0.15 ± 0.04**	0.15 ± 0.02	0.15 ± 0.03	0.04
Elderly	AP COP shift (cm)	4.53 ± 1.23	5.03 ± 1.32	4.69 ± 0.64	4.95 ± 1.27	NS
	ML COP shift(cm)	4.21 ± 1.55	4.48 ± 1.63	4.85 ± 1.53	5.05 ± 1.88	NS
	AP APA duration (s)	0.40 ± 0.09	0.36 ± 0.06	0.38 ± 0.06	0.36 ± 0.05	NS
	ML APA duration (s)	0.39 ± 0.09	0.37 ± 0.05	0.36 ± 0.05	0.37 ± 0.05	NS
	Foot lift duration (s)	0.14 ± 0.02	0.14 ± 0.02	0.14 ± 0.02	0.14 ± 0.04	NS
	AP COM velocity at HO (m/s)	0.15 ± 0.05	0.16 ± 0.05	0.14 ± 0.03	0.15 ± 0.05	NS
	ML COM velocity at HO (m/s)	0.11 ± 0.04	0.11 ± 0.03	0.12 ± 0.04	0.12 ± 0.04	NS

*Reported values are means ± standard deviation. APA, anticipatory postural adjustments; COM, center of mass; COP, center of pressure; AP, anteroposterior; ML, mediolateral; HO, heel off; NS, non-significant interaction. *, **, ***Significant difference between the pre and post-treatment condition as revealed with the Tukey post-hoc test, with P < 0.05, P < 0.01, and P < 0.001, respectively.*

TABLE 3 | Comparison of motor performance, stability and stiffness parameters between the pre- and post-treatment condition in the WBV and sham group (young adults and elderly).

	Motor performance, stability and stiffness	WBV group		Sham group		Group X treatment interaction
	Variables	Before	After	Before	After	P-values
Young adults	Swing phase duration (s)	0.12 ± 0.02	0.13 ± 0.03	0.14 ± 0.04	0.14 ± 0.04	NS
	Step length (cm)	67.94 ± 6.43	67.89 ± 6.74	70.32 ± 8.61	70.68 ± 7.45	NS
	AP COM velocity at FC (m/s)	0.96 ± 0.01	0.98 ± 0.09	1.01 ± 0.12	1.02 ± 0.11	NS
	Step width (cm)	17.11 ± 4.03	17.07 ± 4.09	18.12 ± 4.57	17.52 ± 4.19	NS
	ML COM position at FC (cm)	3.56 ± 2.80	4.52 ± 2.11**	3.85 ± 2.27	3.93 ± 2.31	0.03
	ML COM velocity at FC (m/s)	−0.14 ± 0.05	−0.12 ± 0.04**	−0.15 ± 0.03	−0.14 ± 0.03	0.04
	Margin of stability (cm)	4.74 ± 3.43	5.76 ± 2.56*	5.79 ± 2.65	5.77 ± 2.48	0.02
	Stiffness	835.10 ± 355.40	975.62 ± 290.11*	973.32 ± 293.83	972.98 ± 328.87	0.04
Elderly	Swing phase duration (s)	0.14 ± 0.02	0.14 ± 0.04	0.14 ± 0.02	0.14 ± 0.04	NS
	Step length (cm)	52.74 ± 10.19	53.89 ± 8.35	52.74 ± 10.32	54.39 ± 9.20	NS
	AP COM velocity at FC (m/s)	0.74 ± 0.17	0.78 ± 0.11	0.76 ± 0.14	0.79 ± 0.11	NS
	Step width (cm)	16.84 ± 2.44	17.17 ± 2.77	17.49 ± 4.42	18.10 ± 4.96	NS
	ML COM position at FC (cm)	6.32 ± 5.19	5.98 ± 4.84	6.38 ± 6.34	6.11 ± 5.66	NS
	ML COM velocity at HC (m/s)	−0.13 ± 0.03	−0.14 ± 0.03	−0.14 ± 0.04	−0.15 ± 0.05	NS
	Margin of stability (cm)	5.98 ± 1.72	5.18 ± 2.21	6.38 ± 2.24	5.59 ± 2.58	NS
	Stiffness	1061.90 ± 145.99	1006.45 ± 221.21	1208.88 ± 389.14	1208.33 ± 508.51	NS

Reported values are means ± standard deviation. COM, center of mass; COP, center of pressure; AP, anteroposterior; ML, mediolateral; FC, foot contact; NS, non-significant interaction.
*, **, ***Significant difference between the pre and post-treatment condition as revealed with the Tukey post-hoc test, with $P < 0.05$, $P < 0.01$, and $P < 0.001$, respectively.

the sham group, while they were statistically different for the WBV group. Specifically, the mediolateral COM position ($p < 0.01$) and the mediolateral COM velocity at foot-contact ($p < 0.01$) were both significantly smaller in the post-treatment condition than in the pre-treatment condition for the WBV group, while the MOS was significantly larger ($p < 0.05$; cf. **Table 3**).

Stance Leg Stiffness

In both the young adults and the elderly, no baseline difference was found between the WBV and sham groups ($p > 0.05$; cf. **Table 3**). In the elderly, statistical analysis showed that there was no significant effect of the group or treatment nor any significant interaction between these two factors on the leg stiffness. In contrast, in the young adults, there was a significant effect of the treatment [$F_{(1, 39)} = 4.15$, $p < 0.05$) along with a significant group X treatment interaction [$F_{(1, 39)} = 4.19$, $p = 0.04$] on this variable. *Post-hoc* analysis further revealed that this interaction could be ascribed to the result that leg stiffness was not significantly different between the pre and the post-treatment condition for the sham group, while it was statistically larger for the WBV group ($p < 0.05$). In addition, results showed that, in the WBV group post-treatment condition, the stance leg stiffness in young adults was significantly correlated with the amplitude of mediolateral APA ($r = 0.61$, $p < 0.01$), i.e., the larger the leg stiffness, the larger the COP shift (**Figure 2**).

DISCUSSION

In the paragraph that follows, the coherence of biomechanical data and their implication in terms of advanced postural control knowledge in young adults and elderly are discussed.

Effect of Acute WBV Application on APA in Young Adults

In young adults, results showed that the amplitude of the mediolateral APA, expressed in terms of peak COP shift, was increased in the WBV group post-treatment. The difference between the pre- and the post-treatment condition reached up to 16.1%, which may be considered as clinically significant. The result that no difference was observed between the pre-treatment and the post-treatment condition in the sham group discards a placebo or a practice effect due to the repetition of the task. The increased mediolateral APA could neither be ascribed to an increase in the progression velocity (27) or to an increase in the duration of the execution phase of gait initiation (26, 46, 47, 72). Results indeed showed that there was no significant effect of the WBV application on these two parameters. In contrast to the mediolateral APA amplitude, the mediolateral APA duration did not change in the WBV group post-treatment. Participants were therefore able to generate larger APA within the same duration, i.e., the APA efficacy was increased post-treatment. In line with this statement, results showed that the mediolateral COM velocity at the time of swing foot-off, which is known to depend on

the spatiotemporal parameters of APA (27, 72), was larger following the WBV application. As this initial COM velocity is directed toward the stance leg, it acts to minimize the COM fall in the opposite direction (i.e., toward the swing leg) during the execution phase under the gravity effect (26, 49). The stabilizing function of APA was thus improved by acute WBV application.

The spatiotemporal parameters of APA are also known to be dependent on the somatosensory inputs arising from the lower limbs and trunk (52–55, 74–78). One can therefore wonder whether the positive effect on APA amplitude reported in this study could be ascribed to a change in the somatosensory inputs induced by the WBV application. While the current literature on healthy subjects repeatedly reported a detrimental effect of acute WBV application on the cutaneous lower limbs sensitivity (16, 79–81), it seems that acute WBV application does not influence lower limbs and trunk proprioception (17, 80–83); note that a detrimental effect on trunk proprioception was reported by Li et al. (84). Now, plantar sensitivity and limb proprioception were not investigated in the present study. However, an alteration of these inputs in the WBV group post-treatment (if any) may likely not be responsible for the changes in the mediolateral APA amplitude reported in the present study. For example, Lin and Yang (85) showed that the amplitude and the duration of mediolateral APA for gait initiation were both reduced (and not increased or unchanged, respectively, as in the present study) following plantar desensitization induced by cold water immersion. A decrease in the mediolateral APA for stepping was also reported when the ankle muscles acting in the mediolateral direction were vibrated to induce alteration of the proprioceptive afferent inflow from Ia fibers (53). In the present study, participants were exposed to WBV but, because of the standing posture with the feet on the vibrating force-plate, the ankle muscles were strongly submitted to the vibrations as in this latter study. The authors proposed that the proprioceptive information induced by vibration and afferent inflow related to body movement exaggerated sense of movement at the ankle. This biased perception led to a decrease in the APA spatiotemporal features. Similarly, a decrease in the postural response during balance recovery following cutaneous and muscular deafferentation experimentally induced by foot anesthesia and leg ischemia, respectively, was reported by Thoumie and Do (77). Finally, proprioceptive perturbation induced by experimental pain applied to the *tibialis anterior* (86) or acute fatigue of the same ankle muscles (78) were both shown to induce a decrease in the APA amplitude for gait initiation.

Globally, the above mentioned studies suggest that the increased mediolateral APA observed in the present research could probably not be ascribed to an (eventual) alteration of the somatosensory inputs induced by acute WBV application. Although not measured in these latter studies, it is possible that a major difference between these studies and the present one lays in the changes in the leg stiffness post-treatment. The stance leg stiffness was indeed increased by 16.8% during the execution phase of gait initiation following the WBV application, which may not be the case in the above mentioned

studies due to the different treatments. In the following paragraph, it is argued that this change in the mechanical feature of the stance leg might be responsible for the increased mediolateral APA.

Effect of Acute WBV Application on Stance Leg Stiffness and Relationship With APA and Stability in Young Adults

As for APA, the increased stance leg stiffness observed in the WBV group post-treatment could not be ascribed to a placebo or a practice effect since no change in this parameter could be detected in the sham group pre-treatment vs. post-treatment. This increased leg stiffness might possibly be related to a "TVR" induced by the activation of leg muscle spindles sensitive to vibrations (56, 57). The effect of WBV on limb stiffness is however controversial in the literature. In human, no effect of acute WBV on stiffness has been reported on patellar tendon (87), hamstring, quadriceps (88), and triceps surae (89) and in lower limbs during hoping (90). In contrast, WBV has been shown to increase area and stiffness of the flexor carpi ulnaris tendon in rats (91) and in the Achille tendon of older women (8). Colson and Petit (90) concluded that further studies should be undertaken to ascertain the effectiveness of WBV on lower limbs stiffness. It is possible that the effect of acute WBV application on muscle stiffness depends on the task to be done and the muscle tested (and particularly its content in spindles), but also on the mechanical features of the vibrations (amplitude, frequency, duration).

Whatever its origin, previous modeling study showed that increasing stance leg stiffness has the potential to induce instability during gait initiation (26). The current results showed that acute WBV application induced two opposite effects on postural stabilization: a *stabilizing* effect via an increase in the mediolateral APA amplitude, and a *destabilizing* effect via an increase in stance leg stiffness. Results showed that the combined action of these two opposite effects resulted in an increased stability during gait initiation, as assessed with the larger mediolateral margin of stability post-treatment. This increase reached 21.4%, which can be considered as clinically relevant. This finding suggests that the negative effect of WBV application on leg stiffness and on related-stability was (over)compensated by the larger mediolateral APA. Furthermore, results showed that these two balance control parameters were positively correlated, i.e., the larger the stance leg stiffness, the larger the mediolateral APA amplitude. Based on these findings, the authors propose that the increased stance leg stiffness induced by the WBV application was taken into account in the programming of the mediolateral APA. In this hypothesis, WBV application would induce a postural constraint in the form of an increased stance leg stiffness requiring motor adaptation to maintain stability. This interpretation is in agreement with the hypothesis that balance control mechanisms are interdependent within the postural system, i.e., they may compensate each other in case one component (here the leg stiffness) is perturbed (31, 92–94). This interdependence would be necessary to maintain an

optimal control of stability in situations where a constraint is applied to the postural system. This statement is supported by recent studies. For example, during stepping over an obstacle in reaction to sudden force-plate translation, Zettel et al. (46, 47) reported that the drastic reduction of the mediolateral APA amplitude due to the urgency to clear the swing foot from the support surface did not result in a greater instability because it was compensated by larger step width, which corresponds to another form of balance control mechanism. In the same vein, Artico et al. (94) reported that the amplitude of mediolateral APA for gait initiation with the goal to clear an obstacle depended on whether participants had to strike the ground with a "rear foot strategy" (where the swing heel strikes first, RFS) or a "forefoot strategy" (where the toe strikes first, FFS). More specifically, it was found that the amplitude of the mediolateral APA was lower in the FFS than in the RFS condition. Striking the support surface with the toe first mechanically enlarged by a few centimeters the mediolateral base of support compared to striking with the heel first, thus making the control of stability in the final posture easier. As a consequence, the need to develop large mediolateral APA was lessened in the FFS condition as compared to the RFS condition to maintain stability. Because APA has an energy cost (46, 47, 95, 96), it was proposed that the CNS would reduce them in the former condition for economical purpose. Similar statement was proposed to explain why APA for upper limb task are depressed when the postural stability is made higher by an additional thoracic support (97). The mediolateral APA would be programmed according to the swing foot strike strategy and related-stability, thus revealing an interdependence between these two mechanisms. Globally, the current results thus add to the growing evidence that dynamic stability during gait initiation may share a principle of *homeostatic*-like regulation similar to most physiological variables, where separate mechanisms need to be coordinated to ensure stabilization of vital variables, here postural stability (31).

Effects of Acute WBV on Postural Organization of Gait Initiation in the Elderly

In contrast to young adults, no significant effects of acute WBV application for any of the biomechanical variables recorded was observed in the elderly. This finding may a priori contrast with current literature that instead tends to show a beneficial effect of WBV application on postural control in static position and on various clinical locomotor tests [for review (98)]. Now, it is noteworthy that these latter studies used long-term WBV treatments and not single bout as in the present study. It is therefore not excluded that long-term WBV application would result in dynamic stability improvement in the elderly. The result that no increase in stance leg stiffness was observed in the WBV group post-treatment may possibly be ascribed to the progressive alteration with aging in the central structures (e.g., spinal motoneurons) (99, 100), somatosensory receptors of the lower limbs (e.g., spindles and mechanoreceptors of the

plantar foot sole) (101, 102), and/or sensory-motor pathways involved in the TVR reflex (103). This alteration would make elderly's stance leg stiffness less sensitive to acute WBV application than young adults. As a consequence, no motor adaptation e.g., in the form of larger APA or larger step width would be required to maintain stability since it was no further challenged by the WBV application. The current results however suggest that studies focusing on the effects of long-term WBV application in elderly should take into consideration the possibility that leg stiffness may be increased by this treatment. In case participants are not able to develop motor adaptation, instability may occur during locomotor tasks with increasing risks of falls.

CONCLUSION

The present results showed that the effects of acute WBV application on the postural organization of gait initiation depend on the age of participants. In young healthy adults, a positive effect was observed on dynamic stability, while no effect was observed in the elderly. The positive effect was ascribed to an increase in the mediolateral APA following WBV application which overcompensated the potentially destabilizing effect of the increased stance leg stiffness. WBV application may thus be efficient to improve dynamic stability but at the condition that participants are able to develop adaptive changes in balance control mechanisms. In elderly, no anticipatory (nor corrective) postural adaptation was required since acute WBV application did not elicit change in the stance leg stiffness. Globally, the present finding is therefore in agreement with the hypothesis that balance control mechanisms are interdependent within the postural system, i.e., they may compensate each other in case one component (here the leg stiffness) is perturbed.

DATA AVAILABILITY STATEMENT

The datasets generated for this study are available on request to the corresponding author.

ETHICS STATEMENT

The studies involving human participants were reviewed and approved by CIAMS Research Unit, Equipe d'Accueil (EA) 4532. The patients/participants provided their written informed consent to participate in this study. Written informed consent was obtained from the individual(s) for the publication of any potentially identifiable images or data included in this article.

AUTHOR CONTRIBUTIONS

AD, TV, MF, GL, LC, RA, FG, PF, and EY contributed with project creation, data collection, data analysis, drafted the manuscript, discussed the results, and participated in the revision of the manuscript.

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