

Development and Analysis of the Automated Object Reentry Survival Analysis Tool Parametric Study Wrapper

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Introduction

The NASA Orbital Debris Program Office (ODPO) studies all aspects of spacecraft end-of-life and orbital debris measurement, modeling, and mitigation. The reentry safety group within the ODPO uses the Object Reentry Survival Analysis Tool (ORSAT) to calculate the casualty risk due to reentry of spacecraft and other types of orbital debris. ORSAT models spacecraft as a collection of fragments that break apart from the parent object at a pre-defined "breakup altitude." It then calculates the trajectory and aero-heating of these fragments to determine which fragments are completely destroyed and which survive to the ground and pose a risk to human population. Because of the historically high computational cost of these calculations, many simplifying assumptions have been made in the traditional calculation and analysis process used by the ODPO, some of which have been shown by recent research by the ODPO and others to be incorrect. Improvements to the ORSAT code and advancements in computer technology have vastly decreased the program's processing time, and have allowed the ODPO to develop a capability for large-scale parametric studies and Monte Carlo reentry simulations that can aid in both the initial spacecraft design and provide more detailed and accurate risk analysis to spacecraft operators.

Key Topics							
NASA ODPO	ORSAT	AutoORSAT	Parametric Risk Study				
Spacecraft Reentry	Monte-Carlo Risk Analysis	Design for Demise	Demisability Database				



Modeling Spacecraft Reentry \succ A reentering spacecraft is modeled as a collection of components that are released when the spacecraft breaks apart due to



Complex Nesting

Some fragments are fully

contained within larger

demises

AutoC	DRSAT Process Flow	
AutoORSAT_Wrapper_Input_File.xlsx Defines variables to be iterated, parent/child relationships, and AutoORSAT		

Automating Reentry Simulations Because the initial setup for each ORSAT calculation typically involves a large amount of manual editing of the text-based simulation definition file, performing large scale parametric studies of reentry conditions has always been a prohibitively time-consuming task and therefore limited to a small number of conditions in cases where the results of a given simulation were ambiguous. Therefore, the main purpose of the AutoORSAT wrapper was to automate the generation of individual simulation definition files.





aerodynamic forces.

> Sometimes, a component may contain other **Un-nested Fragments** components that are shielded from aero-All pieces of the spacecraft are heating until the parent component is released at the same time at the breakup altitude destroyed.

Traditionally, ORSAT has only modeled unnested fragments due to limitations of original code. AutoORSAT adds the capability of easily simulating complex nesting of components. Exact entry conditions for the spacecraft are impossible to predict, so traditionally, ORSAT is run with a single entry condition that is assumed to be representative of many possible entry conditions. Monte-Carlo analysis is often used when the starting conditions are fragments and are only exposed uncertain, and AutoORSAT adds this capability to aero-heating when the parent to the ODPO's processing toolchain.

Designing for Spacecraft End-of-Life: Design for Demise (D4D)

Most spacecraft placed in a low-Earth orbit will eventually reenter the atmosphere on a random orbit decay path, potentially posing a casualty risk to ground populations. The goal of the D4D concept is complete vaporization of the spacecraft in the upper atmosphere, leaving no surviving fragments to cause potential harm on the ground. Whether the end of mission plan for the spacecraft includes a targeted entry or a random decay reentry, the ground casualty risk can be significantly reduced by including component demisability in the initial spacecraft design.

To meet this goal of complete demise of the spacecraft, designers need access to information on component desmisability early in the design process in order to make informed component and material selections.



AutoORSAT Performance

AutoORSAT uses the Python multiprocessing module to run an arbitrary number of parallel ORSAT instances. Typically, an ORSAT run for a single fragment takes about 1 to 5 seconds of computation time depending on whether and how quickly the fragment demises. Using a single node of the ODPO computing cluster with 16 cores and 32 parallel threads, up to 126,000 ORSAT runs per hour have been achieved, with a typical run computing about 72,000 ORSAT runs per hour on average.

For a spacecraft with 150 modeled components, this computation speed enables a Monte Carlo parametric study of the full range of reentry starting conditions with 8,000 starting points to be completed in ~12 hours.

The AutoORSAT wrapper is a command-line tool written in Python that can read an easy-to-edit Excelbased input file with value ranges for each variable and output thousands of ORSAT input files to be individually processed by parallel ORSAT instances.

AutoC)rsat \	Wrap	per In	put Dat	а								
Control Variabl	es and S	ummar	у										
DROP DOWN AND SINGULAR VARIABLES			RANGE VARIABLES				SUMMARY						
Variable	Value	Value 2	Value 3	Description		Variable	Max	Min	Iterations	Description		Total ORSAT Runs	2
TSTART	0	-		Click for Info		ALT	122000	122000	1	Click for Info		Nesting Levels	0
TSTOP	99999	-		Click for Info		VEL	7356.1	0	2	Click for Info		Nesting Strings	0
IPRT	100	-		Click for Info		GAMMA	-0.1	-0.1	1	Click for Info			
NFRAG	0	-		Click for Info		HAP	0	0	1	Click for Info		Apply Multip	le Range Values
DT	0.005	-		Click for Info		HP	0	0	1	Click for Info			
ISCREEN	1	-		Click for Info		INC	0.1	0.1	1	Click for Info		Apply	Clear
IPRTHD	0	-		Click for Info		LAT	0	0	1	Click for Info			
IPTRAJ	1	-		Click for Info		LON	0	0	1	Click for Info		Min Value	0
IPHEAT	1	-		Click for Info		DWNRANG	0	0	1	Click for Info			
IPTEMP	1	-		Click for Info								Max Value	0
IPAERO	1	-		Click for Info		Fragment Sheet Controls							
IPATM	0	-		Click for Info	ŭ							Iterations	1
IDHEAT	0	-		Click for Info		Reset	Update					-	
IDTEMP	0	-		Click for Info		Fragments	ts Fragments			Variable	•		
IBATCH	0	-		Click for Info									
IENG	0	-	-	Click for Info								Apply values to	selected:
ITARG	0	BLANK	BLANK	Click for Info									
IASC	1	BLANK	-	Click for Info		Delet	e Fragmen	t Ad	d Fragmen	t After			
Nesting Type	2	-		Click for Info									
GMAT Input	0	-		Click for Info									
Calculate Breakup	0	-		Click for Info						-			
Preheating	None	-		Click for Info									
Auto Parent Mass	1	-	-	Click for Info									
						So in	creen put fil	shot o e. Vai	of first riables	: page of s are def	Exce ined	el-based A by value ra	utoORSAT anges, and



Preliminary Results

Though the extent of the database is currently very limited, a general trend of fragment demisability vs starting altitude can be extracted for fragments made of copper and aluminum, shown in the plot to the right. As expected, the demisability of a fragment made of either material decreases as the release altitude decreases, with very few fragments demising when released below 70 km. However, the figures show that copper fragments demise more readily than aluminum fragments of comparable size. A possible explanation for this effect is the high density of copper. This increases the ballistic coefficient, and therefore the length of time the fragment is exposed to peak heating. These are also very large fragments (0.5 m), which may skew the results somewhat.

Demisability Database

An important goal of D4D is to make it easier for spacecraft designers to incorporate demisability into their trade studies early in the design process. Because simulating reentry demisability requires somewhat specialized knowledge, and running the number of reentry simulations to build a good model for the demisability range of a potential component can be computationally intensive, having a large database of precomputed fragment trajectories covering a broad range of possible materials, fragment shapes, release altitudes, and velocities could be invaluable to a design team. Using such a precomputed database, a designer could instantly produce a report of the demisability of a preliminary component design by searching the database for similarly shaped objects.

Using the new capabilities of AutoORSAT, the ODPO is currently building such a demisability database, which currently exists as a comma-separated value text file containing the input conditions and final state of each fragment scenario. As the number of fragment scenarios calculated increases, this method of data storage becomes increasingly cumbersome. Work is ongoing to implement the database in SQLite, which will improve searchability, data storage efficiency, and portability.

Preliminary results of database query, showing the demisability of solid copper and aluminum release VS. spheres altitude. As the release altitude decreases, the probability of survival increases, with nearly all objects released below 65 km surviving to the ground.





Monte Carlo Risk Analysis

Traditionally, ORSAT is run on a single case basis, using a set of standard inputs, to determine a value for the ground casualty risk of a given spacecraft. Some variation in input parameters can be studied either by using the limited built-in parametric study feature of ORSAT 6.0 or by manually editing the input text file each time to run multiple cases. This is a tedious process and only allows for simple one- or two-variable parametric studies for a small number of spacecraft fragments. These sorts of parametric studies therefore are used only when something in the risk model is marginal and needs more study to solidify the ORSAT analyst's confidence in the model.

Using the AutoORSAT wrapper, large parametric studies of spacecraft demisability models can be implemented and run in only a few hours. This vast increase in capability has allowed the ODPO to investigate the use of Monte Carlo analysis to obtain a clearer and more accurate picture of the real ground casualty risk of a reentering spacecraft. Rather than using a single standard entry assumption, AutoORSAT can use a realistic statistical model of the entry conditions to calculate a ground casualty risk that can automatically incorporate uncertainty and small biases. The ODPO is currently developing appropriate statistical models for inputs to the Monte Carlo analysis and ways to meaningfully interpret the output of the analysis.



Summary and Future Work The NASA Orbital Debris Program Office (ODPO) has created AutoORSAT, a python-based parametric studies on both full spacecraft models (enabling the application of Monte Carlo analysis to spacecraft reentry risk), and on individual fragments to create a database of fragment demisability for use in design for demise. Work has begun on both of these possible applications of AutoORSAT, but much remains be done. The demisability database will be re-implemented as an SQLite database to improve searchability and data storage efficiency. Monte Carlo analysis requires a good understanding of the range and probability distribution of possible input values, and work is ongoing to develop that understanding and apply it to spacecraft risk assessment.